

## 5.18 jal, jr: Subroutine instructions

### A brief note from your instructor:

Sections 5.18-5.21 provide a good conceptual description of how MIPS subroutines work, using temporary registers (\$t) and parameters. However, practically speaking their translation is not accurate because temporary registers by definition are saved across procedure calls, and MIPS provides \$a registers for parameters.

Therefore I recommend skimming this section but will not require completing the activities. I will be demonstrating in class a way of translating subroutines to MIPS, using these concepts.

### Subroutines

A program often needs to perform the same operation for different data values. Ex: Determining the maximum of two values, temperature from Fahrenheit to Celsius, etc. Instead of duplicating the instruction sequence for an operation multiple times, a program can use a subroutine. A **subroutine** is a sequence of instructions that performs a specific operation that can be called from a program. A subroutine call causes the subroutine's statements to execute.

#### PARTICIPATION ACTIVITY

5.18.1: Subroutine for computing maximum of two values.

Start ☐ 2x speed

```
# Compute max of DM[5000] & DM[5004]
addi $t6, $zero, 5000
lw $t0, 0($t6)
addi $t6, $zero, 5004
lw $t1, 0($t6)
```

```
# Compute max of DM[5000] & DM[5004]
addi $t6, $zero, 5000
lw $t0, 0($t6)
addi $t6, $zero, 5004
lw $t1, 0($t6)
```

```

slt $t3, $t0, $t1
bne $t3, $zero, Max1IsT1
add $t2, $zero, $t0
j Max1End
Max1IsT1: add $t2, $zero, $t1
Max1End: addi $t6, $zero, 5008
sw $t2, 0($t6)

# Compute max of DM[5012] & DM[5016]
addi $t6, $zero, 5012
lw $t0, 0($t6)
addi $t6, $zero, 5016
lw $t1, 0($t6)
slt $t3, $t0, $t1
bne $t3, $zero, Max2IsT1
add $t2, $zero, $t0
j Max2End
Max2IsT1: add $t2, $zero, $t1
Max2End: addi $t6, $zero, 5020
sw $t2, 0($t6)

```

No subroutine with redundant code

Call CompMax subroutine (not shown)

```

addi $t6, $zero, 5008
sw $t2, 0($t6)

```

```

# Compute max of DM[5012] & DM[5016]
addi $t6, $zero, 5012
lw $t0, 0($t6)
addi $t6, $zero, 5016
lw $t1, 0($t6)

```

Call CompMax subroutine (not shown)

```

addi $t6, $zero, 5020
sw $t2, 0($t6)

```

CompMax:

```

slt $t3, $t0, $t1
bne $t3, $zero, MaxIsT1
add $t2, $zero, $t0
j MaxEnd
MaxIsT1: add $t2, $zero, $t1
MaxEnd: Return from subroutine

```

CompMax subroutine computes max of \$t0 and \$t1, writing max to \$t2.

#### PARTICIPATION ACTIVITY

#### 5.18.2: Subroutines.

Refer to the animation above.

- 1) What label indicates the first instruction of the subroutine for computing the maximum value?

- ☐ CompMax  
☐ MaxEnd

- 2) How many redundant instructions in the original code were moved to the subroutine.
- ☐ 5
- ☐ 10
- 3) A subroutine's instructions must be duplicated each time the subroutine is called.
- ☐ True
- ☐ False
- 4) A subroutine may have up to 1024 instructions.
- ☐ True
- ☐ False

## Jump and link and jump register instructions

The **jump and link (jal)** instruction stores the address of the next instruction in register \$ra, and then jumps to the instruction specified location. Ex: `jal CalcCube` stores the address of the instruction after the jal instruction in \$ra, and continues execution at the instruction at CalcCube; CalcCube is the label for the first instruction of the subroutine. The **\$ra** register (or **return address**) holds the instruction address to which a subroutine returns after executing. The **jump register (jr)** instruction jumps to the instruction address held in a register. Ex: `jr $ra` jumps to the instruction at the address held in register \$ra. A programmer uses jal to call a subroutine, and jr to return from a subroutine.

### PARTICIPATION ACTIVITY

5.18.3: Subroutine call using jal and jr instructions.

Start

☐ 2x speed

```

# Compute cube of 3
12 addi $t0, $zero, 3
16 jal CalcCube # Call CalcCube
20 sw $t1, 0($t6)

```

...

```

# CalcCube subroutine
CalcCube:
60 mul $t1, $t0, $t0
64 mul $t1, $t1, $t0
68 jr $ra

```

Register file	
\$zero	0
\$t0	3
\$t1	9 27
...	
\$t6	5000
\$ra	20

Data memory DM	
5000	27
5004	

#### PARTICIPATION ACTIVITY

#### 5.18.4: jal and jr instructions.

- 1) Write a jump and link instruction to call a subroutine named CalcTip.

Check

Show answer

- 2) If the jal instruction below is located in instruction memory at address 200, what value is written to register \$ra?

```
jal DetSpeed
```

Check

Show answer

- 3) Using the \$ra register, write an instruction to return from a subroutine named CalcTip.

Check

Show answer

- 4) Assume \$ra holds 116. If the jr instruction below is located in instruction memory at address 200, what is the address of the instruction executed after `jr $ra`?

Check

Show answer

## Arguments and return values

An **argument** is a value passed to a subroutine, that influences the subroutine's operations. A **return value** is a value returned by a subroutine. A simple subroutine may use specific registers for the argument and return value. Ex: The CalcCube subroutine uses \$t0 for the subroutine's argument and \$t1 for the return value.

The assembly program below passes arguments to the CalcCube subroutine using \$t0. The CalcCube subroutine returns the result in \$t1. The program first passes 3 to the subroutine by writing 3 to register \$t0. After executing the subroutine, \$t1 holds the result, which is stored in data memory at address 5000. The program then passes 17 to the subroutine by writing 17 to \$t0. The result of 4 is stored to data memory at address 5004.

Figure 5.18.1: Passing arguments to multiple CalcCube subroutine calls.

```

# Initialize registers for DM addresses
addi $t5, $zero, 5000
addi $t6, $zero, 5004

# Compute cube of 3
addi $t0, $zero, 3 # Pass argument of 3
jal CalcCube      # Call CalcCube
sw $t1, 0($t5)    # Store result to DM[5000]

# Compute cube of 17
addi $t0, $zero, 17 # Pass argument of 17
jal CalcCube      # Call CalcCube
sw $t1, 0($t6)    # Store result to DM[5004]
j Done

# CalcCube subroutine.
#   $t0 is subroutine argument
#   $t1 is subroutine return value
CalcCube:
    mul $t1, $t0, $t0
    mul $t1, $t1, $t0
    jr $ra      # Return from subroutine

Done:

```

**PARTICIPATION  
ACTIVITY**
**5.18.5: Subroutine arguments and return values.**

The CalcEq subroutine below evaluates the equation:  $x * (y - z)$ . Values for x, y, and z are passed to the subroutine as arguments.

CalcEq:

```

sub $t5, $t1, $t2
mul $t3, $t5, $t0
jr $ra

```

1) Which register is used for x?

- ☐ \$t0
- ☐ \$t1
- ☐ \$t2

2) Which register is used for the argument y?

- ☐ \$t0
- ☐ \$t1
- ☐ \$t2

3) Which register is used for the argument z?

- ☐ \$t2
- ☐ \$t3

4) Which register is used for the return value?

- ☐ \$ra
- ☐ \$t3

**PARTICIPATION  
ACTIVITY**

5.18.6: Create a subroutine.

Using the CompMax subroutine, complete the assembly program to compute the maximum of the three values in DM[5000], DM[5004], and DM[5008], storing the result in DM[5020].

1. Load \$t0 and \$t1 with DM[5000] and DM[5004], and call the CompMax subroutine.
2. Copy the result, which is held in \$t2, into \$t0. Load \$t1 with DM[5008]. Call the CompMax subroutine.
3. Store the result, which is held in \$t2, to DM[5020]

Assembly

Line 1 # FIXME: Compute maximum of DM[5000],

Line 2 # DM[5004], and DM[5008]

Line 3 j Done

Line 4

Line 5 CompMax:

Line 6 slt \$t3, \$t0, \$t1

Line 7 bne \$t3, \$zero, MaxIsT1

Line 8 add \$t2, \$zero, \$t0

Line 9 j MaxEnd

Line 10 MaxIsT1: add \$t2, \$zero, \$t1

Line 11 MaxEnd: jr \$ra

Line 12

Line 13 Done:

Registers

\$zero

\$t0

\$t1

\$t2

\$t3

\$t4

\$t5

\$t6

0

0

0

0

0

0

0

0

5000

5004

5008

5020

+

D:

ENTER SIMULATION

STEP

RUN

More options

▼

Table 5.18.1: Instruction summary: jal, jr.

Instruction	Format	Description	Example
jal	jal JLabel	Jump and link: Stores the address of the next instruction in register \$ra, and continues execution with the instruction at JLabel.	jal CalcTip
jr	jr \$a	Jump register: Causes execution to continue with the instruction at address \$a.	jr \$t3



ACTIVITY

5.18.1: Call and create subroutines.

Start

Pass DM[\$t3] to the YearlySalary subroutine, and store the return value to DM[\$t4].  
\$t1 is the subroutine argument.  
\$t2 is the subroutine return value.

```
lw $t1, 0($t1)
lw $t1, 0($t1)
lw $t1, 0($t1)
lw $t1, 0($t1)
```

```
YearlySalary: addi $t2, $zero, 2000
              mul  $t2, $t1, $t2
              jr   $ra
```

Registers	
\$t1	0
\$t2	0
\$t3	5000
\$t4	5004

Done :

1

2

Check

Next

 Provide feedback on this section