

Application Note

Helmholtz Coil

Model MH-6

Magnetic Field Standard



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CERTIFICATION

Lake Shore certifies that this product has been inspected and tested in accordance with its published specifications and that this product met its published specifications at the time of shipment. The accuracy and calibration of this product at the time of shipment are traceable to the United States National Institute of Standards and Technology (NIST); formerly known as the National Bureau of Standards (NBS).

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1.0 GENERAL

The Lake Shore Model MH-6 Helmholtz coil provides a simple method of producing small volume, relatively low-value magnetic fields. The field produced is approximately 25 G/A. A calibration constant is provided which allows the user to generate accurate field values with a known current input. The field homogeneity is specified to exist in a volume centered in the coil interior.

2.0 SPECIFICATIONS

2.1 PHYSICAL SPECIFICATIONS

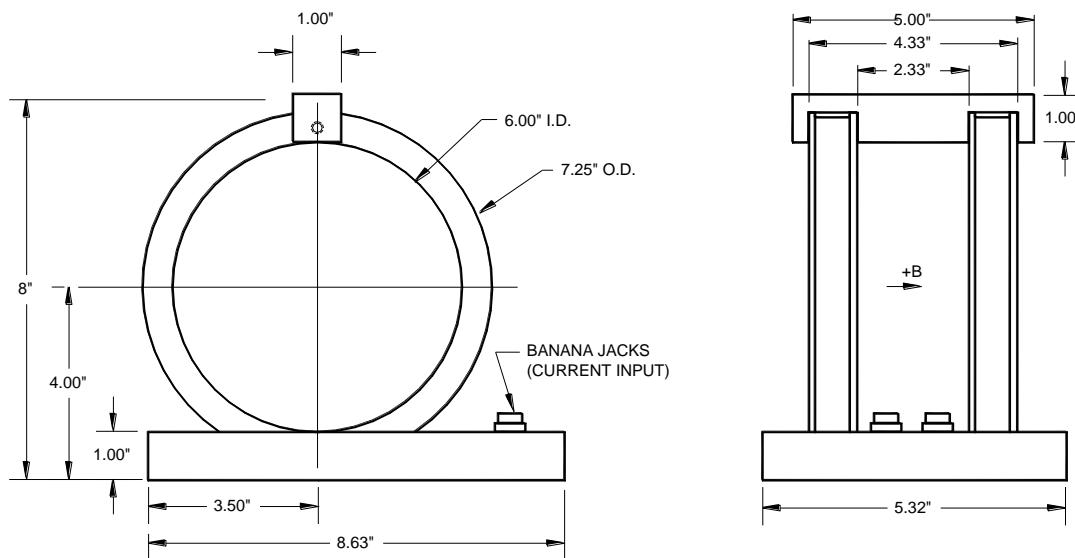


Figure 1. MH-6 Physical Dimensions, Front and Side Views

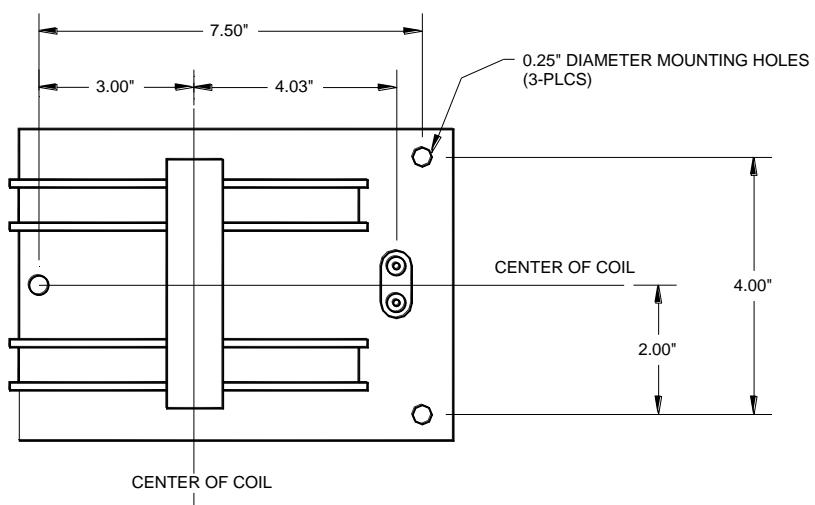


Figure 2. MH-6 Physical Dimensions, Mounting Holes

2.2 ELECTRICAL SPECIFICATIONS

Table 1. MH-6 Electrical and Magnetic Specifications

<i>Parameter</i>	<i>Model MH-6</i>
Description	Helmholtz coil, 6 in inside diameter, $\pm 0.5\%$ center field accuracy
Field strength	25 G at 1 A (approximate—an exact value is supplied)
Maximum continuous current	2 A DC (or RMS)
Field uniformity	$\pm 0.5\%$ of center value, within a cylindrical volume 1.6 in long, 1.6 in diameter, centered in the coil interior
DC coil resistance/inductance	10 Ω / 36 mH
Operating ambient temperature range	-20 $^{\circ}\text{C}$ to +40 $^{\circ}\text{C}$

3.0 INSTALLATION

3.1 GENERAL

Utilization of a Helmholtz coil is relatively straightforward. A current is supplied to the coil, the current magnitude is measured, and the magnetic field value is calculated. A DC or AC current can be used. **However, please read the paragraph on AC Operation to be aware of limitations and possible safety hazards when using AC currents.**

3.2 INSTRUMENTATION SETUP

See Figure 3. It is recommended that the power supply providing the current be a true **constant current** supply. This is suggested to prevent current change, and thus magnetic field change, due to coil heating. The ammeter should be capable of easily handling the maximum current planned during operation.

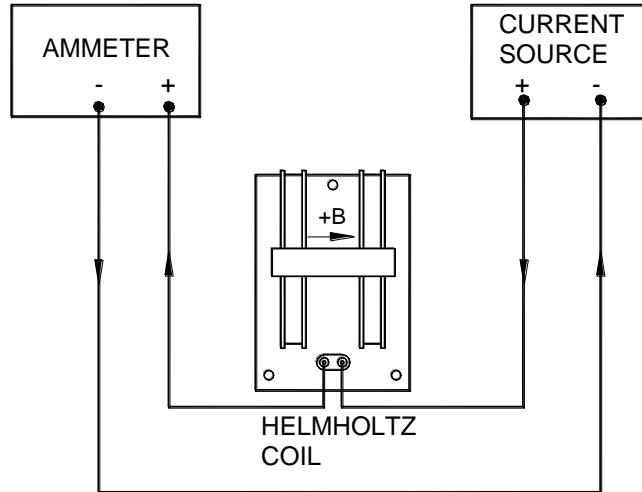


Figure 3. Basic Block Diagram

3.3 LEAD SIZE

Assure that the lead size (gauge) is ample to carry the operating current. Refer to Table 2 for some common wire sizes versus current for safe operation.

Table 2. Minimum Wire Size Versus Current

<i>DC or RMS current value (A)</i>	<i>Wire size (AWG)</i>
2	20
1.5	20
1.0	22
0.5	26

3.4 POLARITY

The hook-up polarities shown in Figure 3 provide a field vector direction as shown (also see Figure 1) when a positive current is measured on the ammeter. When the current direction is reversed, the field direction will likewise change by 180°.

3.5 MOUNTING CONSIDERATIONS

Place the MH-6 on a solid, **non-magnetic** surface such as a wood or plastic table. The presence of nearby ferrous metal will harm the accuracy of the field constant. Shielding must be used very cautiously, and its effect proven to be negligible versus the open field configuration.

If the position of the coil must be fixed, mounting holes are provided (see Figure 2). The use of ferrous fasteners is discouraged. Brass or plastic is acceptable.

4.0 OPERATION

4.1 GENERAL

A Helmholtz coil makes a very convenient low field standard. The magnetic field produced per current input can be accurately calibrated using a Hall-effect gaussmeter. The magnetic field waveform matches that of the current. Thus, complex AC as well as DC fields can be generated.

4.2 DETERMINING THE MAGNETIC FIELD VALUE

The coil has a label indicating its magnetic field flux density per current. This constant is given as "G/A."

Therefore, all the user has to do is multiply the known current in amperes times the above constant. For example, if the constant is 26.75 G/A and the current is measured at 0.45 A, then the field value (in the center of the coil) is:

$$0.45 \times 26.75 = 12.04 \text{ G.}$$

If the current is DC, the field is DC.

If the current is AC rms, the field is AC rms.

The field waveform matches that of the current.

If the user wants to work in SI units, the G value can be converted to T by multiplying by 10^{-4} .

$$(12.04 \text{ G}) \times (10^{-4}) = 1.204 \text{ mT}$$

4.3 FLUX DENSITY (B) VERSUS MAGNETIC FIELD STRENGTH (H)

The flux density and magnetic field strength in air are related approximately by the permeability of vacuum, μ_0 . At least in air, the generated magnetic field can be converted to units field strength.

$$B = \mu_0 H$$

$$H = B / \mu_0$$

In the cgs system, calculations are somewhat simple due to the fact that μ_0 is given the value 1.0. Therefore, in our example in paragraph 4.2, the magnetic field strength is 12.04 G divided by 1 to give 12.04 Oe (the unit of H in the cgs system).

Conversions in the SI system are slightly more difficult because μ_0 is $4\pi \times 10^{-7}$. Again, going back to our example in 4.2, we calculate magnetic field strength as 1.204×10^{-3} divided by $4\pi \times 10^{-7}$ to give 958 A/m (the unit of H in the SI system).

4.4 FIELD UNIFORMITY

The magnetic field uniformity (homogeneity) is defined as being within $\pm 0.5\%$ of the center value over a cylindrical volume 1.6 in long and 1.6 in diameter (40.6 mm long and 40.6 mm diameter). Sometimes a user wants to use a larger volume, and is willing to accept a greater field difference than the 0.5%. Table 3 shows the axial (Z) and radial (R) components of the field for various positions in the coil. The values are normalized for 10 G in the center (0,0). Figure 4 defines the Z and R axes.

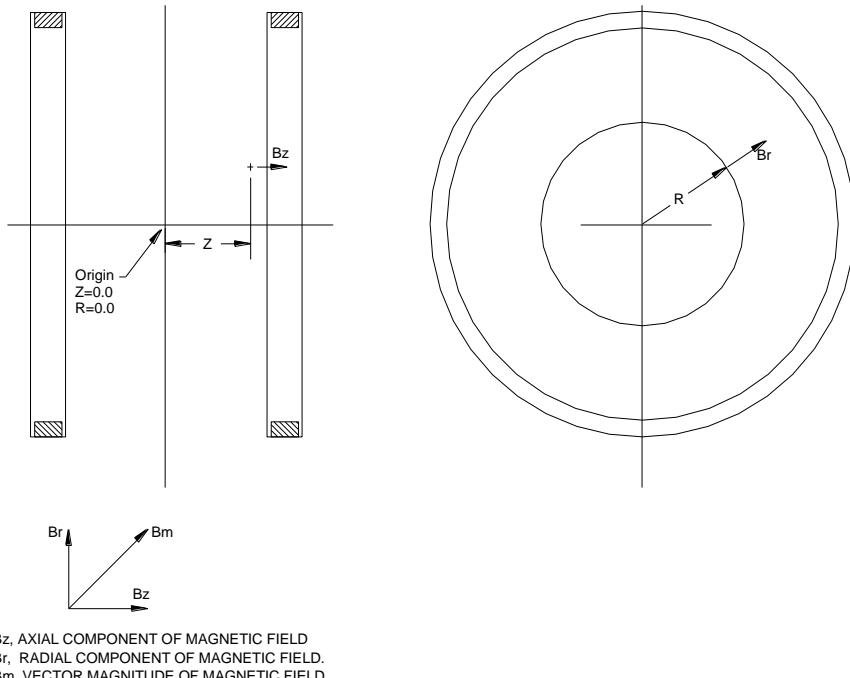


Figure 4. Definition of Terms

Table 3. Field Values at Various Positions

Z (cm)	R (cm)	B_Z (G)	B_R (G)	B_M (G)
0.00	0.00	10.000	0.00	10.000
0.00	1.00	10.000	0.00	10.000
0.00	2.00	9.992	0.00	9.992
0.00	3.00	9.939	0.00	9.939
0.00	4.00	9.769	0.00	9.769
0.00	5.00	9.351	0.00	9.351
0.00	6.00	8.488	0.00	8.488
0.00	7.00	6.976	0.00	6.976
1.00	0.00	9.995	0.00	9.995
1.00	1.00	10.002	0.004	10.002
1.00	2.00	10.015	-0.012	10.015
1.00	3.00	10.007	-0.075	10.007
1.00	4.00	9.917	-0.232	9.920
1.00	5.00	9.628	-0.552	9.644
1.00	6.00	8.924	-1.115	8.993
1.00	7.00	7.476	-1.890	7.711
2.00	0.00	9.955	0.00	9.955
2.00	1.00	9.979	0.032	9.979
2.00	2.00	10.048	0.035	10.048
2.00	3.00	10.155	-0.038	10.155
2.00	4.00	10.282	-0.264	10.286
2.00	5.00	10.377	-0.787	10.407
2.00	6.00	10.263	-1.863	10.431
2.00	7.00	9.347	-9.713	10.087
3.00	0.00	9.821	0.00	9.821
3.00	1.00	9.863	0.099	9.863
3.00	2.00	9.994	0.172	9.996
3.00	3.00	10.236	0.179	10.237
3.00	4.00	10.631	0.048	10.631
3.00	5.00	11.263	-0.381	11.270
3.00	6.00	12.262	-1.502	12.353
3.00	7.00	13.616	-4.479	14.333
4.00	0.00	9.524	0.00	9.524
4.00	1.00	9.577	0.197	9.579
4.00	2.00	9.746	0.386	9.753
4.00	3.00	10.069	0.555	10.084
4.00	4.00	10.633	0.684	10.655
4.00	5.00	11.630	0.727	11.653
4.00	6.00	13.543	0.568	13.554
4.00	7.00	17.811	-0.188	17.812

NOTE: Data presented in the above table is to demonstrate the field uniformity to be expected, and is normalized to a center field of exactly 10.000 G.

4.5 AC OPERATION

Helmholtz coils can be used to generate AC fields as well as DC fields. The field shape exactly follows the current waveform. The major application difference is that the user must consider the additional inductive reactance component in the total impedance of the coil. Therefore, it will be harder to drive current into the coil as the frequency of that current gets greater. The inductance and DC resistance specifications are given in Table 1 of this manual. The user must always use the total impedance when calculating the supply voltage required to generate the needed magnetic field.

A related factor is the possibility of generating very high voltages across the coil. As an example, about 225 V RMS are required to drive 1 A RMS at 1 kHz. If the power supply can generate these kinds of voltages, one must avoid similar operating conditions. **It is suggested that coil voltages above 48 V RMS never be used.**

4.6 OPERATION AT HIGHER CURRENTS

The maximum, continuous operating current is specified as 2 A DC or AC RMS. Though non-destructive to the MH-6 itself, the coil wire may become quite hot to the touch. **All users are cautioned not to touch the actual coil wires during high current operation.**

Brief excursions (a few seconds long) to values of current two or three times the maximum, continuous value are allowable. This must be done cautiously, and the coil structure temperature monitored for overheating. Long cool down periods between these higher current excursions are mandatory.

5.0 THEORY

Helmholtz coils are very useful when relatively accurate, low value magnetic fields are required. The assembly is in reality a pair of coils with very specific diameter and separation. The theory is that along the coil axis, the reduction in field as one moves away from coil #1 is compensated for by the increase in field as one nears coil #2. The magnetic flux density (B) or field strength (H) is directly proportional to the applied current in the coils. Thus, the field can be accurately defined as a function of the current.

Due to its split configuration the Helmholtz coil allows entry from the side or from either end. The field is relatively uniform in a cylindrical volume located on the axis, centered between the coils. A field homogeneity of $\pm 0.5\%$ is easily specified over a volume whose diameter is about 25% of the coil diameter and length is 50% of the coil spacing.

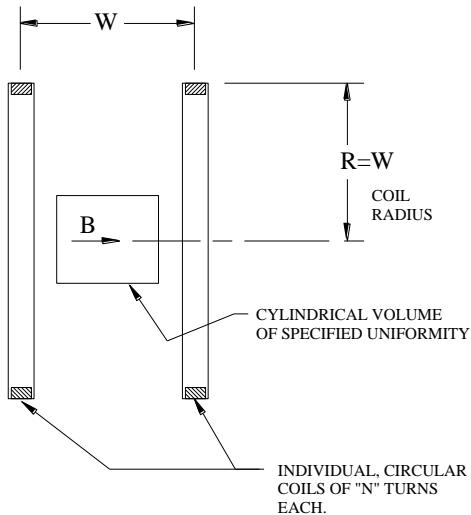


Figure 5. Typical Helmholtz Coil

Theory (Continued)

The field value for a standard Helmholtz coil can be calculated from the simple equation:

$$B = \frac{0.8991 NI}{R}$$

where:

B is magnetic flux density in G,

N is number of turns in each one of the two coils,

I is the current (A) in series (aiding) connected coils, and

R is the coil radius in cm.

6.0 GLOSSARY OF TERMINOLOGY

accuracy. The degree of correctness with which a measured value agrees with the true value.²

ampere. The constant current that, if maintained in two straight parallel conductors of infinite length, of negligible circular cross section, and placed one meter apart in a vacuum, would produce between these conductors a force equal to 2×10^{-7} newton per meter of length.² This is one of the base units of the SI.

ampere-turn. A MKS unit of magnetomotive force equal to the magnetomotive force around a path linking one turn of a conducting loop carrying a current of one ampere; or 1.26 gilberts.

ampere/meter (A/m). The SI unit for magnetic field strength (H). 1 ampere/meter = $4\pi/1000$ oersted ≈ 0.01257 oersted.

cgs system of units. A system in which the basic units are the centimeter, gram, and second.²

coercive force (coercive field). The magnetic field strength (H) required to reduce the magnetic induction (B) in a magnetic material to zero.

coercivity. generally used to designate the magnetic field strength (H) required to reduce the magnetic induction (B) in a magnetic material to zero from saturation. The coercivity would be the upper limit to the coercive force.

compliance voltage. *See* current source.

current source. A type of power supply that supplies a constant current through a variable load resistance by automatically varying its compliance voltage. A single specification given as "compliance voltage" means the output current is within specification when the compliance voltage is between zero and the specified voltage.

deviation. The difference between the actual value of a controlled variable and the desired value corresponding to the setpoint.¹

differential permeability. The slope of a B versus H curve: $\mu_d = dB/dH$.

differential susceptibility. The slope of a M versus H curve: $\chi_d = dM/dH$.

electromagnet. A device in which a magnetic field is generated as the result of electrical current passing through a helical conducting coil. It can be configured as an iron-free solenoid in which the field is produced along the axis of the coil, or an iron-cored structure in which the field is produced in an air gap between pole faces. The coil can be water cooled copper or aluminum, or superconductive.

electron. An elementary particle containing the smallest negative electric charge. *Note:* The mass of the electron is approximately equal to 1/1837 of the mass of the hydrogen atom.²

error. Any discrepancy between a computed, observed, or measured quantity and the true, specified, or theoretically correct value or condition.²

flux (ϕ). The electric or magnetic lines of force in a region.¹

gamma. A cgs unit of low-level flux density, where 100,000 gamma equals one gauss, or 1 gamma equals 10^{-5} gauss.

gauss (G). The cgs unit for magnetic flux density (B). 1 gauss = 10^{-4} tesla = 1 Mx/cm² = line/cm². Named for Karl Fredrich Gauss (1777 – 1855) a German mathematician, astronomer, and physicist.

gaussian system (units). A system in which centimeter-gram-second units are used for electric and magnetic qualities.

gilbert (Gb). A cgs electromagnetic unit of the magnetomotive force required to produce one maxwell of magnetic flux in a magnetic circuit of unit reluctance. One gilbert is equal to $10/4\pi$ ampere-turn. Named for William Gilbert (1540 – 1603), an English physicist; hypothesized that the earth is a magnet.

gilbert per centimeter. Practical cgs unit of magnet intensity. Gilberts per cm are the same as oersteds.

Greek alphabet. The Greek alphabet is defined as follows:

Alpha	α	A	Iota	ι	I	Rho	ρ	P
Beta	β	B	Kappa	κ	K	Sigma	σ	Σ
Gamma	γ	Γ	Lambda	λ	Λ	Tau	τ	T
Delta	δ	Δ	Mu	μ	M	Upsilon	υ	Y
Epsilon	ε	E	Nu	ν	N	Phi	ϕ	Φ
Zeta	ζ	Z	Xi	ξ	Ξ	Chi	χ	X
Eta	η	H	Omicron	\circ	O	Psi	ψ	Ψ
Theta	θ	Θ	Pi	π	Π	Omega	ω	Ω

Hall effect. The generation of an electric potential perpendicular to both an electric current flowing along a thin conducting material and an external magnetic field applied at right angles to the current. Named for Edwin H. Hall (1855 – 1938), American physicist.

Helmholtz coils. A pair of flat, circular coils having equal numbers of turns and equal diameters, arranged with a common axis, and connected in series; used to obtain a magnetic field more nearly uniform than that of a single coil.¹

hysteresis. The dependence of the state of a system on its previous history, generally in the form of a lagging of a physical effect behind its cause.¹ Also *see* magnetic hysteresis.

initial permeability. The permeability determined at $H = 0$ and $B = 0$.

initial susceptibility. The susceptibility determined at $H = 0$ and $M = 0$.

international system of units (SI). A universal coherent system of units in which the following seven units are considered basic: meter, kilogram, second, ampere, kelvin, mole, and candela. The International System of Units, or Système International d'Unités (SI), was promulgated in 1960 by the Eleventh General Conference on Weights and Measures. For definition, spelling, and protocols, *see* Reference 3 for a short, convenient guide.

intrinsic coercivity. The magnetic field strength (H) required to reduce the magnetization (M) or intrinsic induction in a magnetic material to zero.

intrinsic induction. The contribution of the magnetic material (B_i) to the total magnetic induction (B).

$$B_i = B - \mu_0 H \quad (\text{SI})$$

$$B_i = B - H \quad (\text{cgs})$$

line of flux. An imaginary line in a magnetic field of force whose tangent at any point gives the direction of the field at that point; the lines are spaced so that the number through a unit area perpendicular to the field represents the intensity of the field. Also known as a Maxwell in the cgs system of units.

magnetic air gap. The air space, or non-magnetic portion, of a magnetic circuit.

magnetic field strength (H). The magnetizing force generated by currents and magnetic poles. For most applications, the magnetic field strength can be thought of as the applied field generated, for example, by a superconducting magnet. The magnetic field strength is not a property of materials. Measure in SI units of A/m or cgs units of oersted.

magnetic flux density (B). Also referred to as magnetic induction. This is the net magnetic response of a medium to an applied field, H. The relationship is given by the following equation: $B = \mu_0 (H + M)$ for SI, and $B = H + 4\pi M$ for cgs, where H = magnetic field strength, M = magnetization, and μ_0 = permeability of free space = $4\pi \times 10^{-7}$ H/m.

magnetic hysteresis. The property of a magnetic material where the magnetic induction (B) for a given magnetic field strength (H) depends upon the past history of the samples magnetization.

magnetic induction (B). *See* magnetic flux density.

magnetic moment (m). This is the fundamental magnetic property measured with dc magnetic measurements systems such as a vibrating sample magnetometer, extraction magnetometer, SQUID magnetometer, etc. The exact technical definition relates to the torque exerted on a magnetized sample when placed in a magnetic field. Note that the moment is a total attribute of a sample and alone does not necessarily supply sufficient information in understanding material properties. A small highly magnetic sample can have exactly the same moment as a larger weakly magnetic sample (*see* Magnetization). Measured in SI units as A·m² and in cgs units as emu. 1 emu = 10^{-3} A·m².

magnetic scalar potential. The work which must be done against a magnetic field to bring a magnetic pole of unit strength from a reference point (usually at infinity) to the point in question. Also known as magnetic potential.¹

magnetic units. Units used in measuring magnetic quantities. Includes ampere-turn, gauss, gilbert, line of force, maxwell, oersted, and unit magnetic pole.

magnetization (M). This is a material specific property defined as the magnetic moment (m) per unit volume (V). $M = m/V$. Measured in SI units as A/m and in cgs units as emu/cm³. 1 emu/cm³ = 10^3 A/m. Since the mass of a sample is generally much easier to determine than the volume, magnetization is often alternately expressed as a mass magnetization defined as the moment per unit mass.

magnetostatic. Pertaining to magnetic properties that do not depend upon the motion of magnetic fields.¹

Maxwell (Mx). A cgs electromagnetic unit of magnetic flux, equal to the magnetic flux which produces an electromotive force of 1 abvolt in a circuit of one turn link the flux, as the flux is reduced to zero in 1 second at a uniform rate.¹

MKSA System of Units. A system in which the basic units are the meter, kilogram, and second, and the ampere is a derived unit defined by assigning the magnitude $4\pi \times 10^{-7}$ to the rationalized magnetic constant (sometimes called the permeability of space).

oersted (Oe). The cgs unit for the magnetic field strength (H). 1 oersted = $(1000)/(4\pi)$ ampere/meter ≈ 79.58 ampere/meter.

ohm (Ω). The SI unit of resistance (and of impedance). The ohm is the resistance of a conductor such that a constant current of one ampere in it produces a voltage of one volt between its ends.²

permeability. Material parameter which is the ratio of the magnetic induction (B) to the magnetic field strength (H): $\mu = B/H$.

Also *see* Initial Permeability and Differential Permeability.

precision. Careful measurement under controlled conditions which can be repeated with similar results. *See* repeatability.

prefixes. SI prefixes used throughout this manual are as follows:

<u>Factor</u>	<u>Prefix</u>	<u>Symbol</u>	<u>Factor</u>	<u>Prefix</u>	<u>Symbol</u>
10^{24}	yotta	Y	10^{-1}	deci	d
10^{21}	zetta	Z	10^{-2}	centi	c
10^{18}	exa	E	10^{-3}	milli	m
10^{15}	peta	P	10^{-6}	micro	μ
10^{12}	tera	T	10^{-9}	nano	n
10^9	giga	G	10^{-12}	pico	p
10^6	mega	M	10^{-15}	femto	f
10^3	kilo	k	10^{-18}	atto	a
10^2	hecto	h	10^{-21}	zepto	z
10^1	deka	da	10^{-24}	yocto	y

remanence. The remaining magnetic induction in a magnetic material when the material is first saturated and then the applied field is reduced to zero. The remanence would be the upper limit to values for the remanent induction. Note that no strict convention exists for the use of remanent induction and remanence and in some contexts the two terms may be used interchangeably.

remanent induction. The remaining magnetic induction in a magnetic material after an applied field is reduced to zero.

Also *see* remanence.

repeatability. The closeness of agreement among repeated measurements of the same variable under the same conditions.²

See precision.

resolution. The degree to which nearly equal values of a quantity can be discriminated.²

measurement resolution. The ability of an instrument to resolve a measured quantity. For digital instrumentation this is often defined by the analog-to-digital converter being used. A n-bit converter can resolve one part in 2^n . The smallest signal change that can be measured is the full scale input divided by 2^n for any given range. Resolution should not be confused with accuracy.

scalar. A quantity which has magnitude only and no direction, in contrast to a vector.¹

SI. Système International d'Unités. *See* International System of Units.

stability. The ability of an instrument or sensor to maintain a constant output given a constant input.

susceptance. In electrical terms, susceptance is defined as the reciprocal of reactance and the imaginary part of the complex representation of admittance: [suscept(ibility) + (conduct)ance].

susceptibility (χ). Parameter giving an indication of the response of a material to an applied magnetic field. The susceptibility is the ratio of the magnetization (M) to the applied field (H). $\chi = M/H$. In both SI units and cgs units the volume susceptibility is a dimensionless parameter. Multiply the cgs susceptibility by 4π to yield the SI susceptibility. *See also* Initial Susceptibility and Differential Susceptibility. As in the case of magnetization, the susceptibility is often seen expressed as a mass susceptibility or a molar susceptibility depending upon how M is expressed.

tesla (T). The SI unit for magnetic flux density (B). 1 tesla = 10^4 gauss

unit magnetic pole. A pole with a strength such that when placed 1 cm away from a like pole, the force between the two is 1 dyne.

vector. A quantity that has both magnitude and direction, and whose components transform from one coordinate system to another in the same manner as the components of a displacement. Also known as a polar vector.¹

volt (V). The difference of electric potential between two points of a conductor carrying a constant current of one ampere, when the power dissipated between these points is equal to one watt.²

volt-ampere (VA). The SI unit of apparent power. The volt-ampere is the apparent power at the points of entry of a single-phase, two-wire system when the product of the RMS value in amperes of the current by the RMS value in volts of the voltage is equal to one.²

watt (W). The SI unit of power. The watt is the power required to do work at the rate of 1 joule per second.²

weber (Wb). The unit of magnetic flux in the mks system, equal to the magnetic flux which, linking a circuit of one turn, produces in it an electromotive force of 1 volt as it is reduced to zero at a uniform rate in 1 second.¹

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