

GigaDevice Semiconductor Inc.

GD32E230

ARM[®] Cortex[™]-M23 32-bit MCU

**Firmware Library
User Guide**

Revision 1.0

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1. Introduction

This manual introduces firmware library of GD32E230 devices which are 32-bit microcontrollers based on the ARM processor.

The firmware library is a firmware function package, including program, data structure and macro definitions, all the performance features of peripherals of GD32E230 devices are involved in the package. The peripheral driving code and firmware examples on evaluation board are also included in firmware library. Users need not learn each peripherals in details and it's easy to apply a peripheral by using the firmware library. Using firmware library can greatly reduce programming time, thereby reducing development costs.

The driving code of each peripheral is concluded by a group of functions, which describes all the performance features of the peripheral. Users can drive a peripheral by a group of APIs (application programming interface), all the APIs are standardized about the code structure, function name and parameter names.

All the driving source code accord with MISRA-C:2004 standard (example files accord with extended ANSI-C standard), and will not be influenced by differences of IDEs, except the startup files which are written differently according to the IDEs.

The commonly used firmware library includes all the functions of all the peripherals, so the code size and the execution speed may not be the optimal. For most applications, users can use the library functions directly, while for the applications which are strict with the code size and execution speed, the firmware library can be used as the reference resource of how to configure a peripheral, and users adjust the code according to actual needs.

The overall structure of the firmware library user manual is shown as below:

- Rules of user manual and firmware library;
- Firmware library overview;
- Functions and registers descriptions of firmware library.

1.1. Rules of User Manual and Firmware Library

1.1.1. Peripherals

Table 1-1. Peripherals

Peripherals	Descriptions
ADC	Analog-to-digital converter
CMP	Comparator
CRC	CRC calculation unit
DBG	Debug
DMA	Direct memory access controller

Peripherals	Descriptions
EXTI	Interrupt/event controller
FMC	Flash memory controller
FWDGT	Free watchdog timer
GPIO/AFIO	General-purpose and alternate-function I/Os
I2C	Inter-integrated circuit interface
MISC	Nested Vectored Interrupt Controller
PMU	Power management unit
RCU	Reset and clock unit
RTC	Real-time Clock
SPI/I2S	Serial peripheral interface/Inter-IC sound
SYSCFG	System configuration
TIMER	TIMER
USART	Universal synchronous/asynchronous receiver /transmitter
WWDGT	Window watchdog timer

1.1.2. Naming rules

The firmware library naming rules are shown as below:

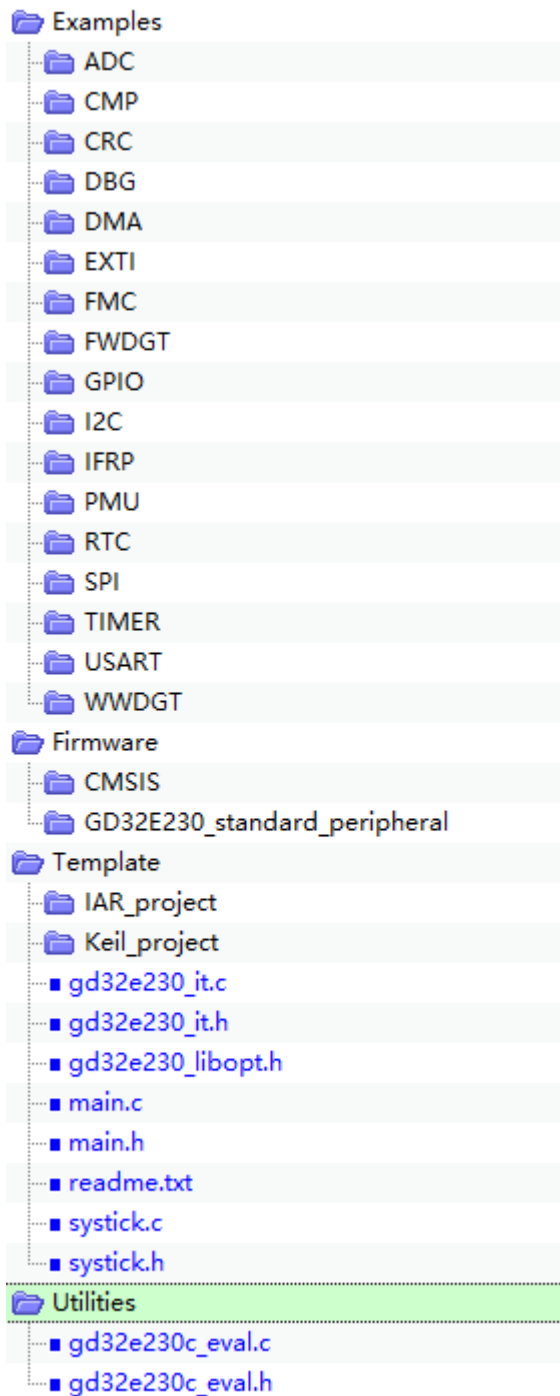
- The peripherals are shortened in XXX format, such as: ADC. More shorten information of peripherals refer to [Peripherals](#);
- The name of sourcefile and header file are started with “GD32e230_”, such as: GD32e230_adc.h;
- The constants used only in one file should be defined in the used file; the constants used in many files should be defined in corresponding header file. All the constants are written in uppercase of English letters;
- Registers are handled as constants. The naming of them are written in uppercase of English letters. In most cases, register names are shortened accord with the user manual;
- Variables are written in lowercase, when concluded by several words, underlines should be adapted among words;
- The naming of peripheral functions are started with the peripheral abbreviation added with an underline, when the function name is concluded by several words, underlines should be adapted among words, and all the peripheral functions are written in lowercase.

2. Firmware Library Overview

2.1. File Structure of Firmware Library

GD32E230_Firmware_Library, the file structure is shown as below:

Figure 2-1. File structure of firmware library of GD32E230



2.1.1. Examples Folder

Examples folder, each of GD32 peripheral has a subfolder. Each subfolder contains one or more examples of the peripheral, to show how to use the peripheral correctly. Each of the example subfolder includes the files shown as below:

- `readme.txt`: the description and using guide of the example;
- `GD32e230_libopt.h`: the header file configures all the peripherals used in the example, included by different “DEFINE” sentences (all the peripherals are enabled by default);
- `GD32e230_it.c`: the source file include all the interrupt service routines (if no interrupt is used, then all the function bodies are empty);
- `GD32e230.it.h`: the header file include all the prototypes of the interrupt service routines;
- `systick.c`: the source file include the precise time delay functions by using `systick`;
- `systick.h`: the header file include the prototype of the precise time delay functions by using `systick`;
- `main.c`: example code. Note: all the examples are not influenced by software IDEs.

2.1.2. Firmware Folder

Firmware folder includes all the subfolder and files which are the core part of the firmware:

- CMSIS subfolder includes the Cortex M23 kernel support files, the startup file based on the Cortex M23 kernel processor, the global header file of GD32E230 and system configuration file;
- GD32E230_standard_peripheral subfolder:
 - Include subfolder includes all the header files of firmware library, users need not modify this folder;
 - Source subfolder includes all the source files of firmware library, users need not modify this folder;

Note: All the codes accord with MISRA-C:2004 standard, and will not be influenced by different software IDEs.

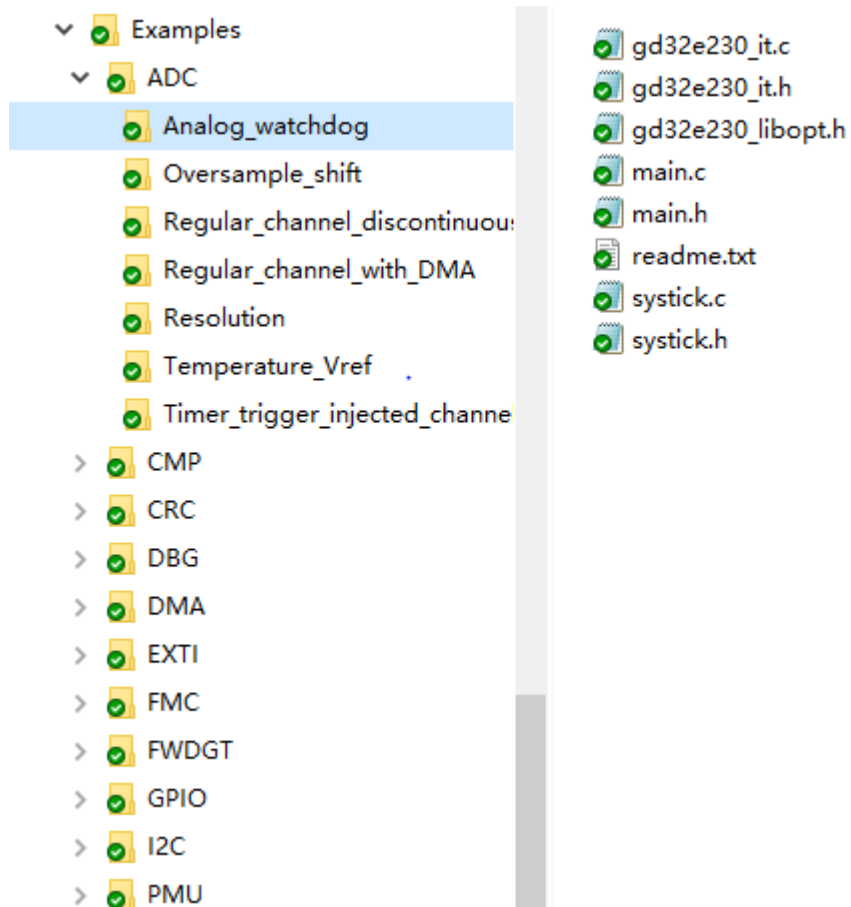
2.1.3. Template Folder

Template folder includes a simple demo of how to use LED, how to print by USART and use key to control, (IAR_project is run in IAR, and Keil_project is run in Keil5). User can use the project template to compile the formware examples, the steps are shown as below:

Select files

Open “Examples” folder, select the module to be tested, such as SPI, open “SPI” folder, select an example of SPI, such as “SPI_master_transmit_slave_receive_interrupt”, shown as below:

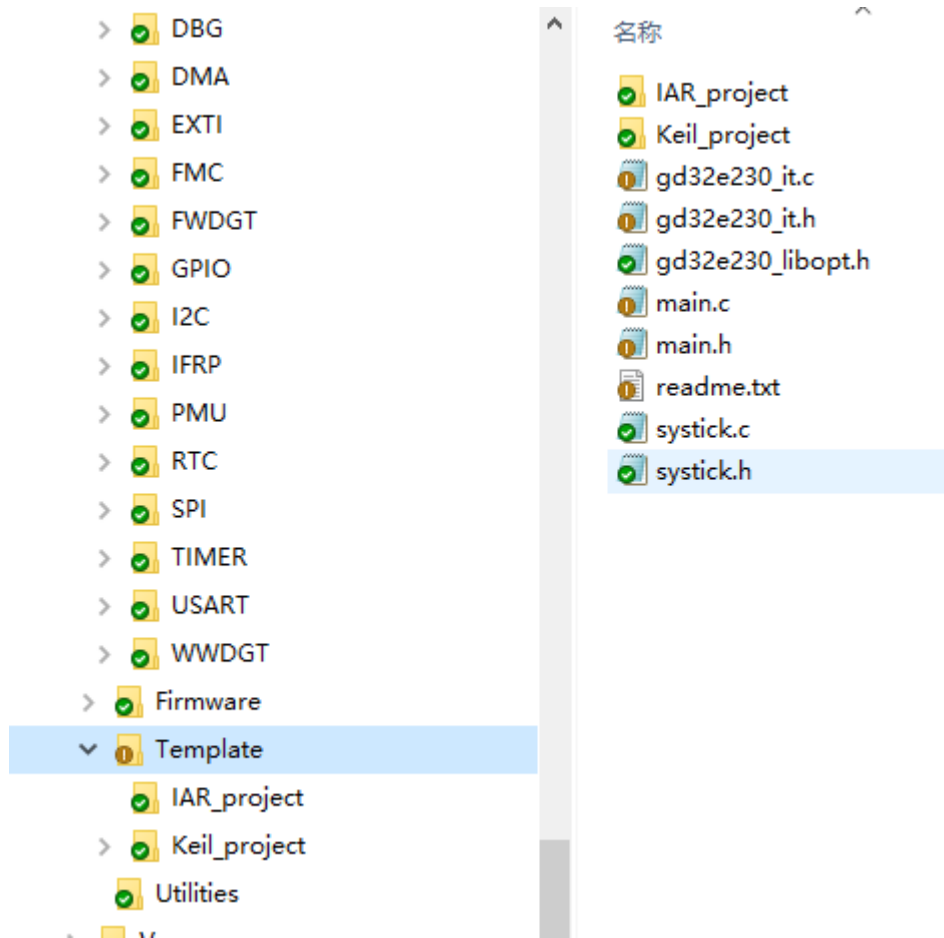
Figure 2-2. Select peripheral example files



Copy files

Open "Template" folder, keep the folders of " IAR_project" and " Keil_project", and delete the other files, then copy all the files in "SPI_master_transmit_slave_receive_interrupt" folder to the "Template" subfolder, shown as below:

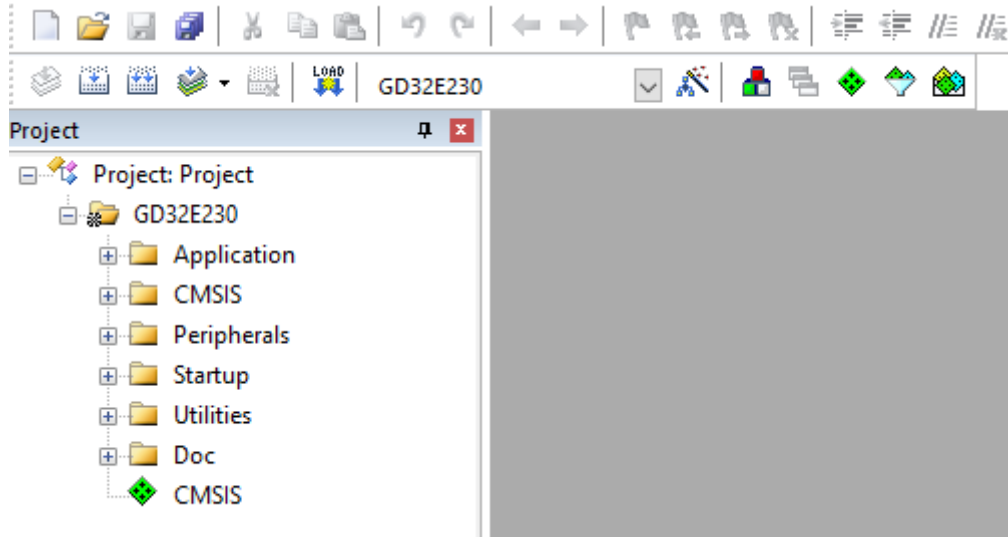
Figure 2-3. Copy the peripheral example files



Open a project

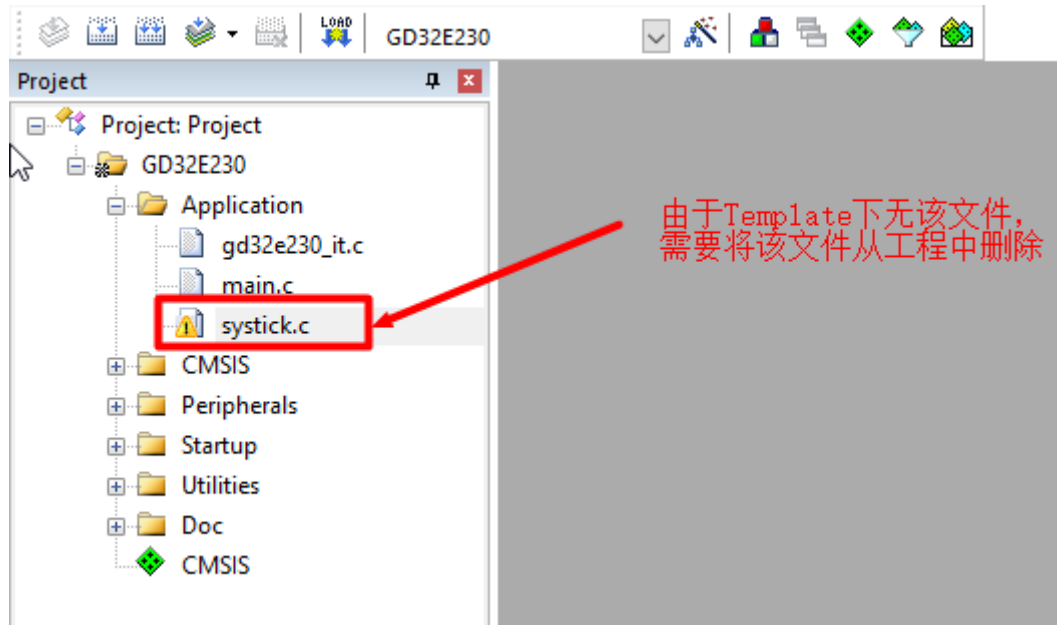
GD provides project in Keil and IAR, users can open project in different IDEs according to their need, such as "Keil_project", open \Template\Keil_project\Project.uvproj, shown as below:

Figure 2-4. Open the project file



Because different module and different functions adopt different files, users should add or delete the files in project according to the copied files, shown as below:

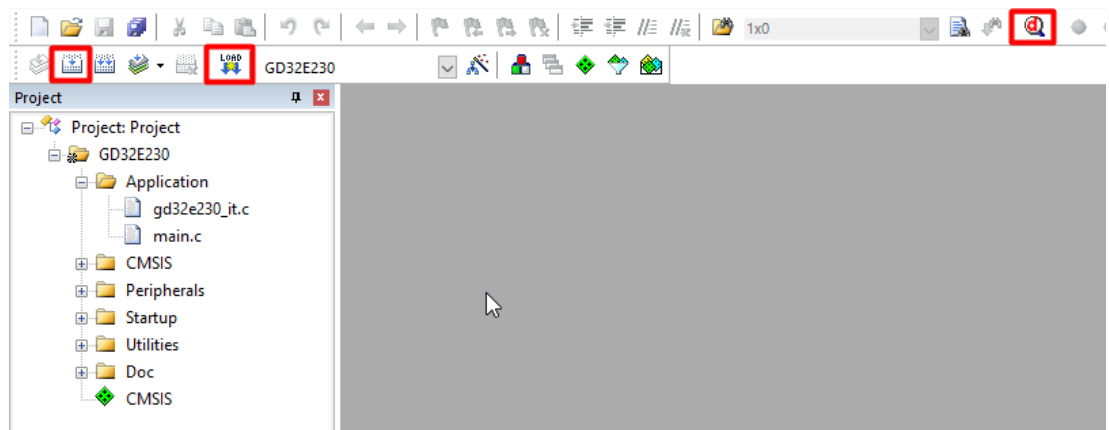
Figure 2-5. Configure project files



Compile-Debug-Download

First compile the project, if there is no error, then select the right jumper cap according to the description of readme, download the project to the target board, and there will be the phenomenon showed accord with the description of readme. The usage of IDE can refer to corresponding software user guide. If users are using Keil, the figure is shown as below:

Figure 2-6. Compile-debug-download



2.1.4. Utilities Folder

Utilities folder includes files about the firmware examples on evaluation board:

- Binary, LCD_Common and Third_Party subfolders;
- GD32e230_eval.h and GD32e230_lcd_eval.h are related header files of the evaluation board about running the firmware examples;
- GD32e230_eval.c and GD32e230_lcd_eval.c are related source files of the evaluation board about running the firmware examples.

Note: All the codes accord with MISRA-C:2004 standard, and will not be influenced by different software IDEs.

2.2. File descriptions of Firmware Library

The major files about the firmware library are listed and described in the table below.

Table 2-1. Function descriptions of Firmware Library

Files	Descriptions
GD32e230_libopt.h	The header file about all the header files of peripherals. It is the only one file which is necessary to be included in the user's application, to connect the firmware library and the application.
main.c	Example of main function.
GD32e230_it.h	Header file, including all the prototypes of interrupt service routines.
GD32e230_it.c	Source files about interrupt service routines of peripherals. User can write his own interrupt functions in this file. For the different interrupt service requests to the same interrupt vector, users can confirm the interrupt source by functions of judging interrupt flags of peripherals. The functions are included in the firmware library.
GD32e230_xxx.h	The header file of peripheral PPP, including functions about peripheral PPP, and the variables used for functions.
GD32e230_xxx.c	The C source file for driving peripheral PPP.
systick.h	The header file of systick.c, including prototypes of systick configuration function and delay function.
systick.c	The source file about systick configuration function and delay function.
readme.txt	Description document about how to configure and how to use the firmware example.

3. Firmware Library of Standard Peripherals

3.1. Overview of Firmware Library of Standard Peripherals

The description format of firmware functions are shown as below:

Table 3-1. Peripheral function format of Firmware Library

Function name	Name of peripheral function
Function prototype	Declaration prototype
Function descriptions	Explain the function how to work
Precondition	Requirements should meet before calling this function
The called functions	Other firmware functions called in this functin
Input parameter{in}	
Input parameter name	Description
xxxx	Description of input parameters
Output parameter{out}	
Output parameter name	Description
xxxx	Description of output parameters
Return value	
Return value type	The range of return value

3.2. ADC

The 12-bit ADC is an analog-to-digital converter using the successive approximation method. The ADC registers are listed in chapter [3.2.1](#), the ADC firmware functions are introduced in chapter [3.2.2](#).

3.2.1. Descriptions of Peripheral registers

ADC registers are listed in the table shown as below:

Table 3-2. ADC Registers

Registers	Descriptions
ADC_STAT	Status register
ADC_CTL0	Control register 0
ADC_CTL1	Control register 1
ADC_SAMPT0	Sample time register 0
ADC_SAMPT1	Sample time register 1
ADC_IOFFx	Inserted channel data offset register x(x=0..3)
ADC_WDHT	Watchdog high threshold register
ADC_WDLT	Watchdog low threshold register
ADC_RSQ0	Regular sequence register 0
ADC_RSQ1	Regular sequence register 1
ADC_RSQ2	Regular sequence register 2
ADC_ISQ	Inserted sequence register
ADC_IDATAx	Inserted data register x(x=0..3)
ADC_RDATA	Regular data register
ADC_OVSAMPCTL	Oversample control register

3.2.2. Descriptions of Peripheral functions

ADC firmware functions are listed in the table shown as below:

Table 3-3. ADC firmware function

Function name	Function description
adc_deinit	reset ADCx peripheral
adc_enable	enable ADC interface
adc_disable	disable ADC interface
adc_calibration_enable	ADC calibration and reset calibration
adc_dma_mode_enable	enable DMA request
adc_dma_mode_disable	disable DMA request
adc_tempsensor_vrefint_enable	enable the temperature sensor and Vrefint channel

Function name	Function description
adc_tempsensor_vrefint_disable	disable the temperature sensor and Vrefint channel
adc_resolution_config	configure ADC resolution
adc_discontinuous_mode_config	configure ADC discontinuous mode
adc_special_function_config	enable or disable ADC special function
adc_data_alignment_config	configure ADC data alignment
adc_channel_length_config	configure the length of regular channel group or inserted channel group
adc_regular_channel_config	configure ADC regular channel
adc_inserted_channel_config	configure ADC inserted channel
adc_inserted_channel_offset_config	configure ADC inserted channel offset
adc_external_trigger_config	enable ADC external trigger
adc_external_trigger_source_config	configure ADC external trigger source
adc_software_trigger_enable	enable ADC software trigger
adc_regular_data_read	read ADC regular group data register
adc_inserted_data_read	read ADC inserted group data register
adc_flag_get	get the ADC flag bits
adc_flag_clear	clear the ADC flag bits
adc_interrupt_flag_get	get the ADC interrupt bits
adc_interrupt_flag_clear	clear the ADC flag
adc_interrupt_enable	enable ADC interrupt
adc_interrupt_disable	disable ADC interrupt
adc_watchdog_single_channel_enable	configure ADC analog watchdog single channel
adc_watchdog_group_channel_enable	configure ADC analog watchdog group channel
adc_watchdog_disable	disable ADC analog watchdog
adc_watchdog_threshold_config	configure ADC analog watchdog threshold
adc_resolution_config	

Function name	Function description
adc_oversample_mode_config	configure ADC oversample mode
adc_oversample_mode_enable	enable ADC oversample mode
adc_oversample_mode_disable	disable ADC oversample mode

adc_deinit

The description of adc_deinit is shown as below:

Table 3-4. Function adc_deinit

Function name	adc_deinit
Function prototype	void adc_deinit(void);
Function descriptions	reset ADC peripheral
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset ADC */
adc_deinit();
```

adc_enable

The description of adc_enable is shown as below:

Table 3-5. Function adc_enable

Function name	adc_enable
Function prototype	void adc_enable(void);
Function descriptions	enable ADC interface
Precondition	-
The called functions	-
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* enable ADC */
adc_enable();
```

adc_disable

The description of `adc_disable` is shown as below:

Table 3-6. Function `adc_disable`

Function name	adc_disable
Function prototype	void adc_disable(void);
Function descriptions	disable ADC interface
Precondition	-
The called functions	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable ADC */
adc_disable();
```

adc_calibration_enable

The description of `adc_calibration_enable` is shown as below:

Table 3-7. Function `adc_calibration_enable`

Function name	adc_calibration_enable
Function prototype	void adc_calibration_enable(void);
Function descriptions	ADC calibration and reset calibration
Precondition	-

The called functions	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* ADC calibration and reset calibration */
```

```
adc_calibration_enable();
```

adc_dma_mode_enable

The description of `adc_dma_mode_enable` is shown as below:

Table 3-8. Function `adc_dma_mode_enable`

Function name	<code>adc_dma_mode_enable</code>
Function prototype	<code>void adc_dma_mode_enable(void);</code>
Function descriptions	enable ADC DMA request
Precondition	-
The called functions	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable ADC DMA request */
```

```
adc_dma_mode_enable();
```

adc_dma_mode_disable

The description of `adc_dma_mode_disable` is shown as below:

Table 3-9. Function `adc_dma_mode_disable`

Function name	<code>adc_dma_mode_disable</code>
Function prototype	<code>void adc_dma_mode_disable(void);</code>

Function descriptions	disable ADC DMA request
Precondition	-
The called functions	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable ADC DMA request */
adc_dma_mode_disable();
```

adc_tempsensor_vrefint_enable

The description of adc_tempsensor_vrefint_enable is shown as below:

Table 3-10. Function adc_tempsensor_vrefint_enable

Function name	adc_tempsensor_vrefint_enable
Function prototype	void adc_tempsensor_vrefint_enable(void);
Function descriptions	enable the temperature sensor and Vrefint channel
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the temperature sensor and Vrefint channel */
adc_tempsensor_vrefint_enable();
```

adc_tempsensor_vrefint_disable

The description of `adc_tempsensor_vrefint_disable` is shown as below:

Table 3-11. Function `adc_tempsensor_vrefint_disable`

Function name	<code>adc_tempsensor_vrefint_disable</code>
Function prototype	<code>void adc_tempsensor_vrefint_disable(void);</code>
Function descriptions	disable the temperature sensor and Vrefint channel
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* disable the temperature sensor and Vrefint channel */
adc_tempsensor_vrefint_disable();

```

adc_discontinuous_mode_config

The description of `adc_discontinuous_mode_config` is shown as below:

Table 3-12. Function `adc_discontinuous_mode_config`

Function name	<code>adc_discontinuous_mode_config</code>
Function prototype	<code>void adc_discontinuous_mode_config(uint8_t channel_group, uint8_t length);</code>
Function descriptions	configure ADC discontinuous mode
Precondition	-
The called functions	-
Input parameter{in}	
adc_channel_group	select the channel group
<code>ADC_REGULAR_CHA</code>	regular channel group

<i>NNEL</i>	
<i>ADC_INSERTED_CHANNEL</i> <i>NNEL</i>	inserted channel group
<i>ADC_CHANNEL_DISCONTINUOUS_DISABLE</i>	disable discontinuous mode of regular and inserted channel
Input parameter{in}	
length	number of conversions in discontinuous mode, the number can be 1..8 for regular channel, the number has no effect for inserted channel
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC regular channel group discontinuous mode */
```

```
adc_discontinuous_mode_config(ADC_REGULAR_CHANNEL, 6);
```

adc_special_function_config

The description of `adc_special_function_config` is shown as below:

Table 3-13. Function `adc_special_function_config`

Function name	<code>adc_special_function_config</code>
Function prototype	<code>void adc_special_function_config(uint32_t function, ControlStatus newvalue);</code>
Function descriptions	enable or disable ADC special function
Precondition	-
The called functions	-
Input parameter{in}	
function	the function to config
<i>ADC_SCAN_MODE</i>	scan mode select
<i>ADC_INSERTED_CHANNEL_AUTO</i>	inserted channel group convert automatically
<i>ADC_CONTINUOUS_</i>	continuous mode select

<i>MODE</i>	
Input parameter{in}	
newvalue	control value
<i>ENABLE</i>	enable function
<i>DISABLE</i>	disable function
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable ADC scan mode */
```

```
adc_special_function_config(ADC_SCAN_MODE, ENABLE);
```

adc_data_alignment_config

The description of `adc_data_alignment_config` is shown as below:

Table 3-14. Function `adc_data_alignment_config`

Function name	<code>adc_data_alignment_config</code>
Function prototype	<code>void adc_data_alignment_config(uint32_t data_alignment);</code>
Function descriptions	configure ADCx data alignment
Precondition	-
The called functions	-
Input parameter{in}	
data_alignment	data alignment select
<i>ADC_DATAALIGN_RIGHT</i>	LSB alignment
<i>ADC_DATAALIGN_LEFT</i>	MSB alignment
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* configure ADC data alignment */
```

```
adc_data_alignment_config(ADC_DATAALIGN_RIGHT);
```

adc_channel_length_config

The description of `adc_channel_length_config` is shown as below:

Table 3-15. Function `adc_channel_length_config`

Function name	adc_channel_length_config
Function prototype	void adc_channel_length_config(uint8_t channel_group, uint32_t length);
Function descriptions	configure the length of regular channel group or inserted channel group
Precondition	-
The called functions	-
Input parameter{in}	
channel_group	select the channel group
ADC_REGULAR_CHANNEL	regular channel group
ADC_INSERTED_CHANNEL	inserted channel group
Input parameter{in}	
length	the length of the channel, regular channel 1-16, inserted channel 1-4
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the length of ADC regular channel */
```

```
adc_channel_length_config(ADC_REGULAR_CHANNEL, 4);
```

adc_regular_channel_config

The description of `adc_regular_channel_config` is shown as below:

Table 3-16. Function `adc_regular_channel_config`

Function name	<code>adc_regular_channel_config</code>
Function prototype	<code>void adc_regular_channel_config(uint8_t rank, uint8_t channel, uint32_t sample_time);</code>
Function descriptions	configure ADC regular channel
Precondition	-
The called functions	-
Input parameter{in}	
rank	the regular group sequence rank, this parameter must be between 0 to 15
Input parameter{in}	
channel	the selected ADC channel
<code>ADC_CHANNEL_x</code>	ADC Channelx (x=0..9,16,17)
Input parameter{in}	
sample_time	the sample time value
<code>ADC_SAMPLETIME_1 POINT5</code>	1.5 cycles
<code>ADC_SAMPLETIME_7 POINT5</code>	7.5 cycles
<code>ADC_SAMPLETIME_1 3POINT5</code>	13.5 cycles
<code>ADC_SAMPLETIME_2 8POINT5</code>	28.5 cycles
<code>ADC_SAMPLETIME_4 1POINT5</code>	41.5 cycles
<code>ADC_SAMPLETIME_5 5POINT5</code>	55.5 cycles
<code>ADC_SAMPLETIME_7 1POINT5</code>	71.5 cycles
<code>ADC_SAMPLETIME_2 39POINT5</code>	239.5 cycles
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* configure ADC regular channel */
```

```
adc_regular_channel_config(1, ADC_CHANNEL_0, ADC_SAMPLETIME_7POINT5);
```

adc_inserted_channel_config

The description of `adc_inserted_channel_config` is shown as below:

Table 3-17. Function `adc_inserted_channel_config`

Function name	<code>adc_inserted_channel_config</code>
Function prototype	<code>void adc_inserted_channel_config(uint8_t rank, uint8_t channel, uint32_t sample_time);</code>
Function descriptions	configure ADC inserted channel
Precondition	-
The called functions	-
Input parameter{in}	
rank	the inserted group sequencer rank, this parameter must be between 0 to 3
Input parameter{in}	
channel	the selected ADC channel
<code>ADC_CHANNEL_x</code>	ADC Channelx (x=0..9,16,17)
Input parameter{in}	
sample_time	the sample time value
<code>ADC_SAMPLETIME_1POINT5</code>	1.5 cycles
<code>ADC_SAMPLETIME_7POINT5</code>	7.5 cycles
<code>ADC_SAMPLETIME_13POINT5</code>	13.5 cycles
<code>ADC_SAMPLETIME_28POINT5</code>	28.5 cycles
<code>ADC_SAMPLETIME_41POINT5</code>	41.5 cycles

1POINT5	
ADC_SAMPLETIME_5 5POINT5	55.5 cycles
ADC_SAMPLETIME_7 1POINT5	71.5 cycles
ADC_SAMPLETIME_2 39POINT5	239.5 cycles
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC0 inserted channel */
```

```
adc_inserted_channel_config(ADC0, 1, ADC_CHANNEL_0, ADC_SAMPLETIME_7POINT5);
```

adc_inserted_channel_offset_config

The description of `adc_inserted_channel_offset_config` is shown as below:

Table 3-18. Function `adc_inserted_channel_offset_config`

Function name	<code>adc_inserted_channel_offset_config</code>
Function prototype	<code>void adc_inserted_channel_offset_config(uint8_t inserted_channel, uint16_t offset);</code>
Function descriptions	configure ADC inserted channel offset
Precondition	-
The called functions	-
Input parameter{in}	
inserted_channel	insert channel select
<code>ADC_INSERTED_CHANNEL_x</code>	inserted channel, x=0,1,2,3
Input parameter{in}	
offset	the offset data, this parameter must be between 0 to 4095
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* configure ADC inserted channel offset */
```

```
adc_inserted_channel_offset_config(ADC_INSERTED_CHANNEL_0, 100);
```

adc_external_trigger_config

The description of `adc_external_trigger_config` is shown as below:

Table 3-19. Function `adc_external_trigger_config`

Function name	adc_external_trigger_config
Function prototype	void adc_external_trigger_config(uint8_t channel_group, ControlStatus newvalue);
Function descriptions	configure ADC external trigger
Precondition	-
The called functions	-
Input parameter{in}	
channel_group	select the channel group
ADC_REGULAR_CHANNEL	regular channel group
ADC_INSERTED_CHANNEL	inserted channel group
Input parameter{in}	
newvalue	control value
ENABLE	enable function
DISABLE	disable function
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable ADC inserted channel group external trigger */
```

```
adc_external_trigger_config(ADC_INSERTED_CHANNEL_0, ENABLE);
```

adc_external_trigger_source_config

The description of `adc_external_trigger_source_config` is shown as below:

Table 3-20. Function `adc_external_trigger_source_config`

Function name	<code>adc_external_trigger_source_config</code>
Function prototype	<code>void adc_external_trigger_source_config(uint8_t channel_group, uint32_t external_trigger_source);</code>
Function descriptions	configure ADC external trigger source
Precondition	-
The called functions	-
Input parameter{in}	
channel_group	select the channel group
<code>ADC_REGULAR_CHANNEL</code>	regular channel group
<code>ADC_INSERTED_CHANNEL</code>	inserted channel group
Input parameter{in}	
external_trigger_source	regular or inserted group trigger source
<code>ADC_EXTTRIG_REGULAR_T0_CH0</code>	TIMER0 CH0 event select for regular channel
<code>ADC_EXTTRIG_REGULAR_T0_CH1</code>	TIMER0 CH1 event select for regular channel
<code>ADC1_EXTTRIG_REGULAR_T0_CH2</code>	TIMER0 CH2 event select for regular channel
<code>ADC_EXTTRIG_REGULAR_T2_TRGO</code>	TIMER2 TRGO event select for regular channel
<code>ADC_EXTTRIG_REGULAR_T14_CH0</code>	TIMER14 CH0 event select for regular channel

<i>ADC_EXTTRIG_REGULAR_EXTI_11</i>	external interrupt line 11 for regular channel
<i>ADC_EXTTRIG_REGULAR_NONE</i>	software trigger for regular channel
<i>ADC_EXTTRIG_INSERTED_TED_T0_TRGO</i>	TIMER0 TRGO event select for inserted channel
<i>ADC_EXTTRIG_INSERTED_TED_T0_CH3</i>	TIMER0 CH3 event select for inserted channel
<i>ADC_EXTTRIG_INSERTED_TED_T2_CH3</i>	TIMER2 CH3 event select for inserted channel
<i>ADC_EXTTRIG_INSERTED_TED_T14_TRGO</i>	TIMER14 TRGO event select for inserted channel
<i>ADC_EXTTRIG_INSERTED_TED_EXTI_15</i>	external interrupt line 15 for inserted channel
<i>ADC_EXTTRIG_INSERTED_TED_NONE</i>	software trigger for inserted channel
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC regular channel external trigger source */
```

```
adc_external_trigger_source_config(ADC_REGULAR_CHANNEL,  
ADC_EXTTRIG_REGULAR_T0_CH0);
```

adc_software_trigger_enable

The description of `adc_software_trigger_enable` is shown as below:

Table 3-21. Function `adc_software_trigger_enable`

Function name	<code>adc_software_trigger_enable</code>
Function prototype	<code>void adc_software_trigger_enable(uint8_t channel_group);</code>
Function descriptions	enable ADC software trigger
Precondition	-

The called functions	-
Input parameter{in}	
channel_group	select the channel group
<i>ADC_REGULAR_CHANNEL</i>	regular channel group
<i>ADC_INSERTED_CHANNEL</i>	inserted channel group
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable ADC regular channel group software trigger */
adc_software_trigger_enable( ADC_REGULAR_CHANNEL);
```

adc_regular_data_read

The description of `adc_regular_data_read` is shown as below:

Table 3-22. Function `adc_regular_data_read`

Function name	<code>adc_regular_data_read</code>
Function prototype	<code>uint16_t adc_regular_data_read(void);</code>
Function descriptions	read ADC regular group data register
Precondition	-
The called functions	-
Output parameter{out}	
-	-
Return value	
uint16_t	ADC conversion value (0-0xFFFF)

Example:

```
/* read ADC regular group data register */
uint16_t adc_value = 0;
```



```
adc_value = adc_regular_data_read();
```

adc_inserted_data_read

The description of `adc_inserted_data_read` is shown as below:

Table 3-23. Function `adc_inserted_data_read`

Function name	<code>adc_inserted_data_read</code>
Function prototype	<code>uint16_t adc_inserted_data_read(uint8_t inserted_channel);</code>
Function descriptions	read ADC inserted group data register
Precondition	-
The called functions	-
Input parameter{in}	
inserted_channel	insert channel select
<code>ADC_INSERTED_CHANNEL_x</code>	inserted Channelx, x=0,1,2,3
Output parameter{out}	
-	-
Return value	
uint16_t	ADC conversion value (0-0xFFFF)

Example:

```
/* read ADC inserted group data register */
uint16_t adc_value = 0;
adc_value = adc_inserted_data_read (ADC_INSERTED_CHANNEL_0);
```

adc_flag_get

The description of `adc_flag_get` is shown as below:

Table 3-24. Function `adc_flag_get`

Function name	<code>adc_flag_get</code>
Function prototype	<code>FlagStatus adc_flag_get(uint32_t flag);</code>
Function descriptions	get the ADC flag bits
Precondition	-

The called functions	-
Input parameter{in}	
flag	the adc flag bits
<i>ADC_FLAG_WDE</i>	analog watchdog event flag
<i>ADC_FLAG_EOC</i>	end of group conversion flag
<i>ADC_FLAG_EOIC</i>	end of inserted group conversion flag
<i>ADC_FLAG_STIC</i>	start flag of inserted channel group
<i>ADC_FLAG_STRC</i>	start flag of regular channel group
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get the ADC analog watchdog flag bits*/
```

```
FlagStatus flag_value;
```

```
flag_value = adc_flag_get(ADC_FLAG_WDE);
```

adc_flag_clear

The description of `adc_flag_clear` is shown as below:

Table 3-25. Function `adc_flag_clear`

Function name	<code>adc_flag_clear</code>
Function prototype	<code>void adc_flag_clear(uint32_t flag);</code>
Function descriptions	clear the ADC flag bits
Precondition	-
The called functions	-
Input parameter{in}	
flag	the adc flag bits
<i>ADC_FLAG_WDE</i>	analog watchdog event flag
<i>ADC_FLAG_EOC</i>	end of group conversion flag

<i>ADC_FLAG_EOIC</i>	end of inserted group conversion flag
<i>ADC_FLAG_STIC</i>	start flag of inserted channel group
<i>ADC_FLAG_STRC</i>	start flag of regular channel group
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear the ADC analog watchdog flag bits*/
```

```
adc_flag_clear(ADC_FLAG_WDE);
```

adc_interrupt_flag_get

The description of `adc_interrupt_flag_get` is shown as below:

Table 3-26. Function `adc_interrupt_flag_get`

Function name	<code>adc_interrupt_flag_get</code>
Function prototype	<code>FlagStatus adc_interrupt_flag_get(uint32_t flag);</code>
Function descriptions	get the ADC interrupt bits
Precondition	-
The called functions	-
Input parameter{in}	
flag	the adc interrupt bits
<i>ADC_INT_FLAG_WDE</i>	analog watchdog interrupt
<i>ADC_INT_FLAG_EOC</i>	end of group conversion interrupt
<i>ADC_INT_FLAG_EOIC</i>	end of inserted group conversion interrupt
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get the ADC analog watchdog interrupt bits*/
```

```
FlagStatus flag_value;
```

```
flag_value = adc_interrupt_flag_get(ADC_INT_FLAG_WDE);
```

adc_interrupt_flag_clear

The description of `adc_interrupt_flag_clear` is shown as below:

Table 3-27. Function `adc_interrupt_flag_clear`

Function name	<code>adc_interrupt_flag_clear</code>
Function prototype	<code>void adc_interrupt_flag_clear(uint32_t flag);</code>
Function descriptions	clear the ADC interrupt bits
Precondition	-
The called functions	-
Input parameter{in}	
flag	the adc interrupt bits
<code>ADC_INT_FLAG_WDE</code>	analog watchdog interrupt
<code>ADC_INT_FLAG_EOC</code>	end of group conversion interrupt
<code>ADC_INT_FLAG_EOIC</code>	end of inserted group conversion interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear the ADC analog watchdog interrupt bits*/
```

```
adc_interrupt_flag_clear( ADC_INT_FLAG_WDE);
```

adc_interrupt_enable

The description of `adc_interrupt_enable` is shown as below:

Table 3-28. Function `adc_interrupt_enable`

Function name	<code>adc_interrupt_enable</code>
Function prototype	<code>void adc_interrupt_enable(uint32_t interrupt);</code>

Function descriptions	enable ADC interrupt
Precondition	-
The called functions	-
Input parameter{in}	
interrupt	the adc interrupt
<i>ADC_INT_WDE</i>	analog watchdog interrupt
<i>ADC_INT_EOC</i>	end of group conversion interrupt
<i>ADC_INT_EOIC</i>	end of inserted group conversion interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable ADC analog watchdog interrupt */
adc_interrupt_enable(ADC_INT_WDE);
```

adc_interrupt_disable

The description of `adc_interrupt_disable` is shown as below:

Table 3-29. Function `adc_interrupt_disable`

Function name	<code>adc_interrupt_disable</code>
Function prototype	<code>void adc_interrupt_disable(uint32_t interrupt);</code>
Function descriptions	Disable ADC interrupt
Precondition	-
The called functions	-
Input parameter{in}	
interrupt	the adc interrupt
<i>ADC_INT_WDE</i>	analog watchdog interrupt
<i>ADC_INT_EOC</i>	end of group conversion interrupt
<i>ADC_INT_EOIC</i>	end of inserted group conversion interrupt

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable ADC interrupt */
adc_interrupt_disable( ADC_INT_WDE);
```

adc_watchdog_single_channel_enable

The description of `adc_watchdog_single_channel_enable` is shown as below:

Table 3-30. Function `adc_watchdog_single_channel_enable`

Function name	<code>adc_watchdog_single_channel_enable</code>
Function prototype	<code>void adc_watchdog_single_channel_enable(uint8_t channel);</code>
Function descriptions	configure ADC analog watchdog single channel
Precondition	-
The called functions	-
Input parameter{in}	
channel	the selected ADC channel
<code>ADC_CHANNEL_x</code>	ADC Channel(x=0..9,16,17)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC analog watchdog single channel */
adc_watchdog_single_channel_enable(ADC_CHANNEL_1);
```

adc_watchdog_group_channel_enable

The description of `adc_watchdog_group_channel_enable` is shown as below:

Table 3-31. Function `adc_watchdog_group_channel_enable`

Function name	<code>adc_watchdog_group_channel_enable</code>
Function prototype	<code>void adc_watchdog_group_channel_enable(uint8_t channel_group);</code>
Function descriptions	configure ADC analog watchdog group channel
Precondition	-
The called functions	-
Input parameter{in}	
channel_group	the channel group use analog watchdog
<code>ADC_REGULAR_CHANNEL</code>	regular channel group
<code>ADC_INSERTED_CHANNEL</code>	inserted channel group
<code>ADC_REGULAR_INSERTED_CHANNEL</code>	both regular and inserted group
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC analog watchdog group channel */
adc_watchdog_group_channel_enable( ADC_REGULAR_CHANNEL);
```

adc_watchdog_disable

The description of `adc_watchdog_disable` is shown as below:

Table 3-32. Function `adc_watchdog_disable`

Function name	<code>adc_watchdog_disable</code>
Function prototype	<code>void adc_watchdog_disable(void);</code>
Function descriptions	disable ADC analog watchdog
Precondition	-
The called functions	-

Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable ADC0 analog watchdog */
```

```
adc_watchdog_disable(ADC0);
```

adc_watchdog_threshold_config

The description of adc_watchdog_threshold_config is shown as below:

Table 3-33. Function adc_watchdog_threshold_config

Function name	adc_watchdog_threshold_config
Function prototype	void adc_watchdog_threshold_config(uint16_t low_threshold, uint16_t high_threshold);
Function descriptions	configure ADC analog watchdog threshold
Precondition	-
The called functions	-
Input parameter{in}	
low_threshold	analog watchdog low threshold, 0..4095
Input parameter{in}	
high_threshold	analog watchdog high threshold, 0..4095
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC analog watchdog threshold */
```

```
adc_watchdog_threshold_config(0x0400, 0x0A00);
```


adc_resolution_config

The description of `adc_resolution_config` is shown as below:

Table 3-34. Function `adc_resolution_config`

Function name	<code>adc_resolution_config</code>
Function prototype	<code>void adc_resolution_config(uint32_t resolution);</code>
Function descriptions	configure ADC resolution
Precondition	-
The called functions	-
Input parameter{in}	
resolution	ADC resolution
<code>ADC_RESOLUTION_12B</code>	12-bit ADC resolution
<code>ADC_RESOLUTION_10B</code>	10-bit ADC resolution
<code>ADC_RESOLUTION_8B</code>	8-bit ADC resolution
<code>ADC_RESOLUTION_6B</code>	6-bit ADC resolution
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC resolution */
adc_resolution_config (ADC_RESOLUTION_12B);
```

adc_oversample_mode_config

The description of `adc_oversample_mode_config` is shown as below:

Table 3-35. Function `adc_oversample_mode_config`

Function name	<code>adc_oversample_mode_config</code>
Function prototype	<code>void adc_oversample_mode_config(uint32_t mode, uint16_t shift, uint8_t</code>

	ratio);
Function descriptions	configure ADC oversample mode
Precondition	-
The called functions	-
Input parameter{in}	
mode	ADC oversampling mode
<i>ADC_OVERSAMPLING _ALL_CONVERT</i>	all oversampled conversions for a channel are done consecutively after a trigger
<i>ADC_OVERSAMPLING _ONE_CONVERT</i>	each oversampled conversion for a channel needs a trigger
Input parameter{in}	
shift	ADC oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_NONE</i>	no oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_1B</i>	1-bit oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_2B</i>	2-bit oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_3B</i>	3-bit oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_4B</i>	4-bit oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_5B</i>	5-bit oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_6B</i>	6-bit oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_7B</i>	7-bit oversampling shift
<i>ADC_OVERSAMPLING _SHIFT_8B</i>	8-bit oversampling shift
Input parameter{in}	
ratio	ADC oversampling ratio

ADC_OVERSAMPLING_RATIO_MUL2	oversampling ratio multiple 2
ADC_OVERSAMPLING_RATIO_MUL4	oversampling ratio multiple 4
ADC_OVERSAMPLING_RATIO_MUL8	oversampling ratio multiple 8
ADC_OVERSAMPLING_RATIO_MUL16	oversampling ratio multiple 16
ADC_OVERSAMPLING_RATIO_MUL32	oversampling ratio multiple 32
ADC_OVERSAMPLING_RATIO_MUL64	oversampling ratio multiple 64
ADC_OVERSAMPLING_RATIO_MUL128	oversampling ratio multiple 128
ADC_OVERSAMPLING_RATIO_MUL256	oversampling ratio multiple 256
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure ADC oversample mode: 16 times sample, 4 bits shift */
```

```
adc_oversample_mode_config(ADC_OVERSAMPLING_ALL_CONVERT,  
ADC_OVERSAMPLING_SHIFT_4B, ADC_OVERSAMPLING_RATIO_MUL16);
```

adc_oversample_mode_enable

The description of `adc_oversample_mode_enable` is shown as below:

Table 3-36. Function `adc_oversample_mode_enable`

Function name	<code>adc_oversample_mode_enable</code>
Function prototype	<code>void adc_oversample_mode_enable(void);</code>
Function descriptions	enable ADC oversample mode
Precondition	-

The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable ADC oversample mode */
adc_oversample_mode_enable ();
```

adc_oversample_mode_disable

The description of `adc_oversample_mode_disable` is shown as below:

Table 3-37. Function `adc_oversample_mode_disable`

Function name	<code>adc_oversample_mode_disable</code>
Function prototype	<code>void adc_oversample_mode_disable(void);</code>
Function descriptions	disable ADC oversample mode
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable ADC oversample mode */
adc_oversample_mode_disable ();
```

3.3. CMP

The general purpose comparator can work either standalone(all terminal are available on I/Os) or together with the timers. It could be used to wake up the MCU from low-power mode by an analog signal, provide a trigger source when an analog signal is in a certain condition, achieves some current control by working together with a PWM output of a timer.The CMP registers are listed in chapter [3.3.1](#), the CMP firmware functions are introduced in chapter [3.3.2](#).

3.3.1. Descriptions of Peripheral registers

CMP registers are listed in the table shown as below:

Table 3-38. CMP Registers

Registers	Descriptions
CMP_CS	Control/Status register

3.3.2. Descriptions of Peripheral functions

CMP firmware functions are listed in the table shown as below:

Table 3-39. CMP firmware function

Function name	Function description
cmp_deinit	deinitialize comparator
cmp_mode_init	initialize comparator mode
cmp_output_init	initialize comparator output
cmp_enable	enable comparator
cmp_disable	disable comparator
cmp_switch_enable	enable comparator switch
cmp_switch_disable	disable comparator switch
cmp_output_level_get	get output level
cmp_lock_enable	lock the comparator

cmp_deinit

The description of cmp_deinit is shown as below:

Table 3-40. Function cmp_deinit

Function name	cmp_deinit
Function prototype	void cmp_deinit(void);
Function descriptions	deinitialize CMP
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* CMP deinitialize*/
cmp_deinit ();
```

cmp_mode_init

The description of cmp_mode_init is shown as below:

Table 3-41. Function cmp_mode_init

Function name	cmp_mode_init
Function prototype	void cmp_mode_init(operating_mode_enum operating_mode, inverting_input_enum inverting_input, cmp_hysteresis_enum output_hysteresis)
Function descriptions	initialize comparator mode
Precondition	-
The called functions	-
Input parameter{in}	
operating_mode	operating_mode
<i>CMP_HIGHSPEED</i>	high speed mode
<i>CMP_MIDDLESPEED</i>	medium speed mode

<i>CMP_LOWSPEED</i>	low speed mode
<i>CMP_VERYLOWSPEED</i>	very-low speed mode
Input parameter{in}	
inverting_input	inverting_input
<i>CMP_1_4VREFINT</i>	VREFINT *1/4 input
<i>CMP_1_2VREFINT</i>	VREFINT *1/2 input
<i>CMP_3_4VREFINT</i>	VREFINT *3/4 input
<i>CMP_VREFINT</i>	VREFINT input
<i>CMP_PA4</i>	PA4 input
<i>CMP_PA5</i>	PA5 input
<i>CMP_PA0</i>	PA0 input
<i>CMP_PA2</i>	PA2 input
Input parameter{in}	
output_hysteresis	hysteresis
<i>CMP_HYSTERESIS_NO</i>	output no hysteresis
<i>CMP_HYSTERESIS_LOW</i>	output low hysteresis
<i>CMP_HYSTERESIS_MIDDLE</i>	output middle hysteresis
<i>CMP_HYSTERESIS_HIGH</i>	output high hysteresis
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* CMP mode initialize*/
```

```
cmp_mode_init(CMP_HIGHSPEED,CMP_1_4VREFINT, CMP_HYSTERESIS_NO);
```

cmp_output_init

The description of cmp_output_init is shown as below:

Table 3-42. Function cmp_output_init

Function name	cmp_output_init
Function prototype	void cmp_output_init(cmp_output_enum output_slection, uint32_t output_polarity);
Function descriptions	initialize comparator output
Precondition	-
The called functions	-
Input parameter{in}	
output_slection	output_slection
<i>CMP_OUTPUT_NONE</i>	output no selection
<i>CMP_OUTPUT_TIMER0BKIN</i>	TIMER 0 break input
<i>CMP_OUTPUT_TIMER0IC0</i>	TIMER 0 channel0 input capture
<i>CMP_OUTPUT_TIMER0OCPRECLR</i>	TIMER 0 OCPRE_CLR input
<i>CMP_OUTPUT_TIMER2IC0</i>	TIMER 2 channel0 input capture
<i>CMP_OUTPUT_TIMER2OCPRECLR</i>	TIMER 2 OCPRE_CLR input
Input parameter{in}	
output_polarity	output_polarity
<i>CMP_OUTPUT_POLARITY_INVERTED</i>	output is inverted
<i>CMP_OUTPUT_POLARITY_NOINVERTED</i>	output is not inverted
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* CMP output initialize*/

cmp_output_init(CMP_OUTPUT_TIMER0BKIN,
CMP_OUTPUT_POLARITY_NOINVERTED);
```

cmp_enable

The description of cmp_enable is shown as below:

Table 3-43. Function can_fd_init

Function name	cmp_enable
Function prototype	void cmp_enable(void);
Function descriptions	enable comparator
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable CMP*/

cmp_enable();
```

cmp_disable

The description of cmp_disable is shown as below:

Table 3-44. Function cmp_disable

Function name	cmp_disable
Function prototype	void cmp_disable(void);
Function descriptions	disable comparator

Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable CMP */
```

```
cmp_disable();
```

cmp_switch_enable

The description of cmp_switch_enable is shown as below:

Table 3-45. Function cmp_switch_enable

Function name	cmp_switch_enable
Function prototype	void cmp_switch_enable(void);
Function descriptions	enable comparator switch
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable CMP switch */
```

```
cmp_switch_enable();
```

cmp_switch_disable

The description of cmp_switch_disable is shown as below:

Table 3-46. Function cmp_switch_disable

Function name	cmp_switch_disable
Function prototype	void cmp_switch_disable(void);
Function descriptions	disable comparator switch
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable CMP switch */
cmp_switch_disable();
```

cmp_output_level_get

The description of cmp_output_level_get is shown as below:

Table 3-47. Function cmp_output_level_get

Function name	cmp_output_level_get
Function prototype	uint32_t cmp_output_level_get(void);
Function descriptions	get output level
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	

-	-
Return value	
uint32_t	CMP_OUTPUTLEVEL_HIGH / CMP_OUTPUTLEVEL_LOW

Example:

```
/* get CMP output level */
cmp_output_level_get ();
```

cmp_lock_enable

The description of cmp_lock_enable is shown as below:

Table 3-48. Function cmp_lock_enable

Function name	cmp_lock_enable
Function prototype	void cmp_lock_enable(void);
Function descriptions	lock the comparator
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* lock CMP register */
cmp_lock_enable();
```

3.4. CRC

A cyclic redundancy check (CRC) is an error-detecting code commonly used in digital networks and storage devices to detect accidental changes to raw data. The CRC registers are listed in chapter [3.4.1](#), the CRC firmware functions are introduced in chapter [3.4.2](#).

3.4.1. Descriptions of Peripheral registers

CRC registers are listed in the table shown as below:

Table 3-49. CRC Registers

Registers	Descriptions
CRC_DATA	CRC data register
CRC_FDATA	CRC free data register
CRC_CTL	CRC control register
CRC_IDATA	CRC initialization data register
CRC_POLY	CRC polynomial register

3.4.2. Descriptions of Peripheral functions

CRC firmware functions are listed in the table shown as below:

Table 3-50. CRC firmware function

Function name	Function description
crc_deinit	deinit CRC calculation unit
crc_reverse_output_data_enable	enable the reverse operation of output data
crc_reverse_output_data_disable	disable the reverse operation of output data
crc_data_register_reset	reset data register to the value of initialization data register
crc_data_register_read	read the data register
crc_free_data_register_read	read the free data register
crc_free_data_register_write	write the free data register
crc_init_data_register_write	write the initial value register
crc_input_data_reverse_config	configure the CRC input data function
crc_polynomial_size_set	configure the CRC size of polynomial function
crc_polynomial_set	configure the CRC polynomial value function
crc_single_data_calculate	CRC calculate a 32-bit data
crc_block_data_calculate	CRC calculate a 32-bit data array

crc_deinit

The description of `crc_deinit` is shown as below:

Table 3-51. Function `crc_deinit`

Function name	crc_deinit
Function prototype	void crc_deinit(void);
Function descriptions	deinit CRC calculation unit
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset crc */
crc_deinit();
```

crc_reverse_output_data_enable

The description of `crc_reverse_output_data_enable` is shown as below:

Table 3-52. Function `crc_reverse_output_data_enable`

Function name	crc_reverse_output_data_enable
Function prototype	void crc_reverse_output_data_enable (void);
Function descriptions	enable the reverse operation of output data
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* enable CRC reverse operation of output data */
```

```
crc_reverse_output_data_enable ();
```

crc_reverse_output_data_disable

The description of `crc_reverse_output_data_disable` is shown as below:

Table 3-53. Function `crc_reverse_output_data_disable`

Function name	crc_reverse_output_data_disable
Function prototype	void crc_reverse_output_data_disable (void);
Function descriptions	disable the reverse operation of output data
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable crc reverse operation of output data */
```

```
crc_reverse_output_data_disable ();
```

crc_data_register_reset

The description of `crc_data_register_reset` is shown as below:

Table 3-54. Function `crc_data_register_reset`

Function name	crc_data_register_reset
Function prototype	void crc_data_register_reset(void);

Function descriptions	reset data register to the value of initializaiton data register
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset crc data register */
crc_data_register_reset ();
```

crc_data_register_read

The description of `crc_data_register_read` is shown as below:

Table 3-55. Function `crc_data_register_read`

Function name	<code>crc_data_register_read</code>
Function prototype	<code>uint32_t crc_data_register_read(void);</code>
Function descriptions	read the data register
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint32_t	32-bit value of the data register (0-0xFFFFFFFF)

Example:

```
/* read crc data register */
```



```
uint32_t crc_value = 0;

crc_value = crc_data_register_read();
```

crc_free_data_register_read

The description of `crc_free_data_register_read` is shown as below:

Table 3-56. Function `crc_free_data_register_read`

Function name	<code>crc_free_data_register_read</code>
Function prototype	<code>uint8_t crc_free_data_register_read(void);</code>
Function descriptions	read the free data register
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
<code>uint8_t</code>	8-bit value of the free data register (0-0xFF)

Example:

```
/* read crc free data register */

uint8_t crc_value = 0;

crc_value = crc_free_data_register_read();
```

crc_free_data_register_write

The description of `crc_free_data_register_write` is shown as below:

Table 3-57. Function `crc_free_data_register_write`

Function name	<code>crc_free_data_register_write</code>
Function prototype	<code>void crc_free_data_register_write(uint8_t free_data);</code>
Function descriptions	write the free data register
Precondition	-
The called functions	-

Input parameter{in}	
free_data	specify 8-bit data
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* write the free data register */
crc_free_data_register_write(0x11);
```

crc_init_data_register_write

The description of `crc_init_data_register_write` is shown as below:

Table 3-58. Function `crc_init_data_register_write`

Function name	<code>crc_init_data_register_write</code>
Function prototype	<code>void crc_init_data_register_write(uint32_t init_data)</code>
Function descriptions	write the initializaiton data register
Precondition	-
The called functions	-
Input parameter{in}	
init_data	specify 32-bit data
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* write crc initializaiton data register */
crc_init_data_register_write (0x11223344);
```

crc_input_data_reverse_config

The description of `crc_input_data_reverse_config` is shown as below:

Table 3-59. Function `crc_input_data_reverse_config`

Function name	<code>crc_input_data_reverse_config</code>
Function prototype	<code>void crc_input_data_reverse_config(uint32_t data_reverse)</code>
Function descriptions	configure the crc input data function
Precondition	-
The called functions	-
Input parameter{in}	
data_reverse	specify input data reverse function
<code>CRC_INPUT_DATA_NOT</code>	input data is not reversed
<code>CRC_INPUT_DATA_BYTE</code>	input data is reversed on 8 bits
<code>CRC_INPUT_DATA_HALFWORD</code>	input data is reversed on 16 bits
<code>CRC_INPUT_DATA_WORD</code>	input data is reversed on 32 bits
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the crc input data */
crc_input_data_reverse_config (CRC_INPUT_DATA_WORD);
```

`crc_polynomial_size_set`

The description of `crc_polynomial_size_set` is shown as below:

Table 3-60. Function `crc_polynomial_size_set`

Function name	<code>crc_polynomial_size_set</code>
Function prototype	<code>void crc_polynomial_size_set(uint32_t poly_size)</code>
Function descriptions	configure the CRC size of polynomial function
Precondition	-

The called functions	-
<i>Input parameter{in}</i>	
poly_size	size of polynomial
<i>CRC_CTL_PS_32</i>	32-bit polynomial for CRC calculation
<i>CRC_CTL_PS_16</i>	16-bit polynomial for CRC calculation
<i>CRC_CTL_PS_8</i>	8-bit polynomial for CRC calculation
<i>CRC_CTL_PS_7</i>	7-bit polynomial for CRC calculation
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the CRC polynomial size*/
crc_polynomial_size_set (CRC_CTL_PS_7);
```

crc_polynomial_set

The description of `crc_polynomial_set` is shown as below:

Table 3-61. Function `crc_polynomial_set`

Function name	<code>crc_polynomial_set</code>
Function prototype	<code>void crc_polynomial_set(uint32_t poly)</code>
Function descriptions	configure the CRC polynomial value function
Precondition	-
The called functions	-
Input parameter{in}	
poly	configurable polynomial value
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the CRC polynomial value */
crc_polynomial_set (0x11223344);
```

crc_single_data_calculate

The description of `crc_single_data_calculate` is shown as below:

Table 3-62. Function `crc_single_data_calculate`

Function name	<code>crc_single_data_calculate</code>
Function prototype	<code>uint32_t crc_single_data_calculate(uint32_t sdata);</code>
Function descriptions	CRC calculate a 32-bit data
Precondition	-
The called functions	-
Input parameter{in}	
sdata	specify 32-bit data
Output parameter{out}	
-	-
Return value	
uint32_t	32-bit CRC calculate value (0-0xFFFFFFFF)

Example:

```
/* CRC calculate a 32-bit data */
uint32_t val = 0, valcrc = 0;
val = (uint32_t)0xabcd1234;
rcu_periph_clock_enable(RCU_CRC);
valcrc = crc_single_data_calculate(val);
```

crc_block_data_calculate

The description of `crc_block_data_calculate` is shown as below:

Table 3-63. Function `crc_block_data_calculate`

Function name	<code>crc_block_data_calculate</code>
Function prototype	<code>uint32_t crc_block_data_calculate(uint32_t array[], uint32_t size);</code>

Function descriptions	calculate the CRC value of an array of 32-bit values
Precondition	-
The called functions	-
Input parameter{in}	
array	pointer to an array of 32 bit data words
Input parameter{in}	
size	size of the array
Output parameter{out}	
-	-
Return value	
uint32_t	32-bit CRC calculate value (0-0xFFFFFFFF)

Example:

```

/* CRC calculate a 32-bit data array */
#define BUFFER_SIZE    6

uint32_t valcrc = 0;

static const uint32_t data_buffer[BUFFER_SIZE] = {
0x00001111, 0x00002222, 0x00003333, 0x00004444, 0x00005555, 0x00006666};

rcu_periph_clock_enable(RCU_CRC);

valcrc = crc_block_data_calculate((uint32_t *) data_buffer, BUFFER_SIZE);

```

3.5. DBG

The DBG hold unit helps debugger to debug power saving mode. The DBG registers are listed in chapter [3.5.1](#). the DBG firmware functions are introduced in chapter [3.5.2](#).

3.5.1. Descriptions of Peripheral registers

DBG registers are listed in the table shown as below:

Table 3-64. DBG Registers

Registers	Descriptions
DBG_ID	DBG ID code register

Registers	Descriptions
DBG_CTL0	DBG control register0
DBG_CTL1	DBG control register1

3.5.2. Descriptions of Peripheral functions

DBG firmware functions are listed in the table shown as below:

Table 3-65. DBG firmware function

Function name	Function description
dbg_deinit	reset DBG register
dbg_id_get	read DBG_ID code register
dbg_low_power_enable	enable low power behavior when the MCU is in debug mode
dbg_low_power_disable	disable low power behavior when the MCU is in debug mode
dbg_periph_enable	enable peripheral behavior when the MCU is in debug mode
dbg_periph_disable	disable peripheral behavior when the MCU is in debug mode

Enum dbg_periph_enum

Table 3-66. Enum dbg_periph_enum

Member name	Function description
DBG_FWDGT_HOLD	debug FWDGT kept when core is halted
DBG_WWDGT_HOLD	debug WWDGT kept when core is halted
DBG_TIMER0_HOLD	hold TIMER0 counter when core is halted
DBG_TIMER2_HOLD	hold TIMER2 counter when core is halted
DBG_TIMER5_HOLD	hold TIMER5 counter when core is halted
DBG_TIMER13_HOLD	hold TIMER13 counter when core is halted
DBG_TIMER14_HOLD	hold TIMER14 counter when core is halted
DBG_TIMER15_HOLD	hold TIMER15 counter when core is halted
DBG_TIMER16_HOLD	hold TIMER16 counter when core is halted
DBG_I2C0_HOLD	hold I2C0 smbus when core is halted
DBG_I2C1_HOLD	hold I2C1 smbus when core is halted

DBG_RTC_HOLD	hold RTC counter when core is halted
--------------	--------------------------------------

dbg_deinit

The description of dbg_deinit is shown as below:

Table 3-67. Function dbg_deinit

Function name	dbg_deinit
Function prototype	void dbg_deinit (void);
Function descriptions	deinitialize the DBG
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* deinitialize the DBG*/
dbg_deinit();
```

dbg_id_get

The description of dbg_id_get is shown as below:

Table 3-68. Function dbg_id_get

Function name	dbg_id_get
Function prototype	uint32_t dbg_id_get(void);
Function descriptions	Read DBG_ID code register
Precondition	-
The called functions	-
Input parameter{in}	
-	-

Output parameter{out}	
-	-
Return value	
uint32_t	DBG_ID code (0-0xFFFFFFFF)

Example:

```
/* read DBG_ID code register */
```

```
uint32_t id_value = 0;
```

```
id_value = dbg_id_get();
```

dbg_low_power_enable

The description of dbg_low_power_enable is shown as below:

Table 3-69. Function dbg_low_power_enable

Function name	dbg_low_power_enable
Function prototype	void dbg_low_power_enable(uint32_t dbg_low_power);
Function descriptions	Enable low power behavior when the mcu is in debug mode
Precondition	-
The called functions	-
Input parameter{in}	
dbg_low_power	low power mode
<i>DBG_LOW_POWER_SLEEP</i>	keep debugger connection during sleep mode
<i>DBG_LOW_POWER_DEEPSLEEP</i>	keep debugger connection during deepsleep mode
<i>DBG_LOW_POWER_STANDBY</i>	keep debugger connection during standby mode
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable low power behavior when the mcu is in debug mode */
```

```
dbg_low_power_enable(DBG_LOW_POWER_SLEEP);
```

dbg_low_power_disable

The description of dbg_low_power_disable is shown as below:

Table 3-70. Function dbg_low_power_disable

Function name	dbg_low_power_disable
Function prototype	void dbg_low_power_disable(uint32_t dbg_low_power);
Function descriptions	Disable low power behavior when the mcu is in debug mode
Precondition	-
The called functions	-
Input parameter{in}	
dbg_low_power	low power mode
<i>DBG_LOW_POWER_SLEEP</i>	keep debugger connection during sleep mode
<i>DBG_LOW_POWER_DEEPSLEEP</i>	keep debugger connection during deepsleep mode
<i>DBG_LOW_POWER_STANDBY</i>	keep debugger connection during standby mode
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable low power behavior when the mcu is in debug mode */
```

```
dbg_low_power_disable(DBG_LOW_POWER_SLEEP);
```

dbg_periph_enable

The description of dbg_periph_enable is shown as below:

Table 3-71. Function dbg_periph_enable

Function name	dbg_periph_enable
----------------------	-------------------

Function prototype	void dbg_periph_enable(dbg_periph_enum dbg_periph);
Function descriptions	Enable peripheral behavior when the mcu is in debug mode
Precondition	-
The called functions	-
Input parameter{in}	
dbg_periph	Peripheral refer to Table 3-66. Enum dbg_periph_enum
<i>DBG_FWDGT_HOLD</i>	debug FWDGT kept when core is halted
<i>DBG_WWDGT_HOLD</i>	debug WWDGT kept when core is halted
<i>DBG_TIMERx_HOLD</i>	x=0,2,5,13,14,15,16, hold TIMERx counter when core is halted
<i>DBG_I2Cx_HOLD</i>	x=0,1, hold I2Cx smbus when core is halted
<i>DBG_RTC_HOLD</i>	hold RTC counter when core is halted
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable peripheral behavior when the mcu is in debug mode */
```

```
dbg_periph_enable(DBG_TIMER0_HOLD);
```

dbg_periph_disable

The description of dbg_periph_disable is shown as below:

Table 3-72. Function dbg_periph_disable

Function name	dbg_periph_disable
Function prototype	void dbg_periph_disable(dbg_periph_enum dbg_periph);
Function descriptions	Disable peripheral behavior when the mcu is in debug mode
Precondition	-
The called functions	-
Input parameter{in}	
dbg_periph	peripheral refer to Table 3-66. Enum dbg_periph_enum

<i>DBG_FWDGT_HOLD</i>	debug FWDGT kept when core is halted
<i>DBG_WWDGT_HOLD</i>	debug WWDGT kept when core is halted
<i>DBG_TIMERx_HOLD</i>	x=0,2,5,13,14,15,16, hold TIMERx counter when core is halted
<i>DBG_I2Cx_HOLD</i>	x=0,1, hold I2Cx smbus when core is halted
<i>DBG_RTC_HOLD</i>	hold RTC counter when core is halted
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable peripheral behavior when the mcu is in debug mode */
```

```
dbg_periph_disable(DBG_TIMER0_HOLD);
```

3.6. DMA

The direct memory access (DMA) controller provides a hardware method of transferring data between peripherals and/or memory without intervention from the CPU, thereby freeing up bandwidth for other system functions. The DMA registers are listed in chapter [3.6.1](#), the DMA firmware functions are introduced in chapter [3.6.2](#).

3.6.1. Descriptions of Peripheral registers

DMA registers are listed in the table shown as below:

Table 3-73. DMA Registers

Registers	Descriptions
DMA_INTF	Interrupt flag register
DMA_INTC	Interrupt flag clear register
DMA_CHxCTL (x=0..4)	Channel x control register
DMA_CHxCNT (x=0..4)	Channel x counter register
DMA_CHxPADDR (x=0..4)	Channel x peripheral base address register

Registers	Descriptions
DMA_CHxMADDR (x=0..4)	Channel x memory base address register

3.6.2. Descriptions of Peripheral functions

DMA firmware functions are listed in the table shown as below:

Table 3-74. DMA firmware function

Function name	Function description
dma_deinit	deinitialize DMA a channel registers
dma_struct_para_init	initialize the parameters of DMA struct with the default values
dma_init	initialize DMA channel
dma_circulation_enable	enable DMA circulation mode
dma_circulation_disable	disable DMA circulation mode
dma_memory_to_memory_enable	enable memory to memory mode
dma_memory_to_memory_disable	disable memory to memory mode
dma_channel_enable	enable DMA channel
dma_channel_disable	disable DMA channel
dma_periph_address_config	set DMA peripheral base address
dma_memory_address_config	set DMA memory base address
dma_transfer_number_config	set the number of remaining data to be transferred by the DMA
dma_transfer_number_get	get the number of remaining data to be transferred by the DMA
dma_priority_config	configure priority level of DMA channel
dma_memory_width_config	configure transfer data size of memory
dma_periph_width_config	configure transfer data size of peripheral
dma_memory_increase_enable	enable next address increasement algorithm of memory
dma_memory_increase_disable	disable next address increasement algorithm of memory
dma_periph_increase_enable	enable next address increasement algorithm of peripheral
dma_periph_increase_disable	disable next address increasement algorithm of peripheral

Function name	Function description
<code>dma_transfer_direction_config</code>	configure the direction of data transfer on the channel
<code>dma_flag_get</code>	check DMA flag is set or not
<code>dma_flag_clear</code>	clear DMA a channel flag
<code>dma_interrupt_flag_get</code>	check DMA flag and interrupt enable bit is set or not
<code>dma_interrupt_flag_clear</code>	clear DMA a channel flag
<code>dma_interrupt_enable</code>	enable DMA interrupt
<code>dma_interrupt_disable</code>	disable DMA interrupt

Structure `dma_parameter_struct`

Table 3-75. Structure `dma_parameter_struct`

Member name	Function description
<code>periph_addr</code>	peripheral base address
<code>periph_width</code>	transfer data size of peripheral
<code>memory_addr</code>	memory base address
<code>memory_width</code>	transfer data size of memory
<code>number</code>	channel transfer number
<code>priority</code>	channel priority level
<code>periph_inc</code>	peripheral increasing mode
<code>memory_inc</code>	memory increasing mode
<code>direction</code>	channel data transfer direction

`dma_deinit`

The description of `dma_deinit` is shown as below:

Table 3-76. Function `dma_deinit`

Function name	<code>dma_deinit</code>
Function prototype	<code>void dma_deinit(dma_channel_enum channelx);</code>
Function descriptions	deinitialize DMA a channel registers
Precondition	-
The called functions	-

Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* DMA channel0 initialize */
dma_deinit(DMA_CH0);
```

dma_struct_para_init

The description of dma_struct_para_init is shown as below:

Table 3-77. Function dma_para_init

Function name	dma_struct_para_init
Function prototype	void dma_struct_para_init(dma_parameter_struct* init_struct);
Function descriptions	initialize the parameters of DMA struct with the default values
Precondition	-
The called functions	-
Input parameter{in}	
init_struct	the initialization data needed to initialize DMA channel
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* initialize the parameters of DMA */
dma_parameter_struct dma_init_struct;
dma_struct_para_init(&dma_init_struct);
```

dma_init

The description of dma_init is shown as below:

Table 3-78. Function dma_init

Function name	dma_init
Function prototype	void dma_init(dma_channel_enum channelx, dma_parameter_struct init_struct);
Function descriptions	initialize DMA channel
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Input parameter{in}	
init_struct	Structure for initialization, the structure members can refer to Table 3-75. Structure dma_parameter_struct
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* DMA channel0 initialize */
dma_parameter_struct dma_init_struct;

dma_init_struct.direction = DMA_PERIPHERAL_TO_MEMORY;
dma_init_struct.memory_addr = (uint32_t)g_destbuf;
dma_init_struct.memory_inc = DMA_MEMORY_INCREASE_ENABLE;
dma_init_struct.memory_width = DMA_MEMORY_WIDTH_8BIT;
dma_init_struct.number = TRANSFER_NUM;
dma_init_struct.periph_addr = (uint32_t)BANK0_WRITE_START_ADDR;
dma_init_struct.periph_inc = DMA_PERIPH_INCREASE_ENABLE;
dma_init_struct.periph_width = DMA_PERIPHERAL_WIDTH_8BIT;
dma_init_struct.priority = DMA_PRIORITY_ULTRA_HIGH;
dma_init(DMA_CH0, dma_init_struct);

```


dma_circulation_enable

The description of dma_circulation_enable is shown as below:

Table 3-79. Function dma_circulation_enable

Function name	dma_circulation_enable
Function prototype	void dma_circulation_enable(dma_channel_enum channelx);
Function descriptions	enable DMA circulation mode
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DMA channel0 circulation mode */
dma_circulation_enable(DMA_CH0);
```

dma_circulation_disable

The description of dma_circulation_disable is shown as below:

Table 3-80. Function dma_circulation_disable

Function name	dma_circulation_disable
Function prototype	void dma_circulation_disable(dma_channel_enum channelx);
Function descriptions	disable DMA circulation mode
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DMA channel0 circulation mode */
dma_circulation_disable(DMA_CH0);
```

dma_memory_to_memory_enable

The description of dma_memory_to_memory_enable is shown as below:

Table 3-81. Function dma_memory_to_memory_enable

Function name	dma_memory_to_memory_enable
Function prototype	void dma_memory_to_memory_enable(dma_channel_enum channelx);
Function descriptions	enable memory to memory mode
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DMA channel0 memory to memory mode */
dma_memory_to_memory_enable(DMA_CH0);
```

dma_memory_to_memory_disable

The description of dma_memory_to_memory_disable is shown as below:

Table 3-82. Function dma_memory_to_memory_disable

Function name	dma_memory_to_memory_disable
Function prototype	void dma_memory_to_memory_disable(dma_channel_enum channelx);
Function descriptions	disable memory to memory mode
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/*disable DMA channel0 memory to memory mode */
dma_memory_to_memory_disable(DMA_CH0);
```

dma_channel_enable

The description of dma_channel_enable is shown as below:

Table 3-83. Function dma_channel_enable

Function name	dma_channel_enable
Function prototype	void dma_channel_enable(dma_channel_enum channelx);
Function descriptions	enable DMA channel
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* enable DMA channel0 */
dma_channel_enable(DMA_CH0);
```

dma_channel_disable

The description of dma_channel_disable is shown as below:

Table 3-84. Function dma_channel_disable

Function name	dma_channel_disable
Function prototype	void dma_channel_disable(dma_channel_enum channelx);
Function descriptions	disable DMA channel
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DMA channel0 */
dma_channel_disable(DMA_CH0);
```

dma_periph_address_config

The description of dma_periph_address_config is shown as below:

Table 3-85. Function dma_periph_address_config

Function name	dma_periph_address_config
Function prototype	void dma_periph_address_config(dma_channel_enum channelx, uint32_t address);

Function descriptions	set DMA peripheral base address
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Input parameter{in}	
address	peripheral base address
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* configure DMA channel0 periph address */
#define BANK0_WRITE_START_ADDR      ((uint32_t)0x08004000)
dma_periph_address_config(DMA_CH0, BANK0_WRITE_START_ADDR);

```

dma_memory_address_config

The description of dma_memory_address_config is shown as below:

Table 3-86. Function dma_memory_address_config

Function name	dma_memory_address_config
Function prototype	void dma_memory_address_config(dma_channel_enum channelx, uint32_t address);
Function descriptions	set DMA memory base address
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection

Input parameter{in}	
address	memory base address
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure DMA channel0 memory address */
```

```
uint8_t g_destbuf[TRANSFER_NUM];
```

```
dma_memory_address_config(DMA_CH0, (uint32_t) g_destbuf);
```

dma_transfer_number_config

The description of dma_transfer_number_config is shown as below:

Table 3-87. Function dma_transfer_number_config

Function name	dma_transfer_number_config
Function prototype	void dma_transfer_number_config(dma_channel_enum channelx, uint32_t number);
Function descriptions	set the number of remaining data to be transferred by the DMA
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Input parameter{in}	
number	data transfer number(0x0-0xFFFF)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure DMA channel0 transfer number */
#define TRANSFER_NUM                0x400

dma_transfer_number_config(DMA_CH0, TRANSFER_NUM);
```

dma_transfer_number_get

The description of dma_transfer_number_get is shown as below:

Table 3-88. Function dma_transfer_number_get

Function name	dma_transfer_number_get
Function prototype	uint32_t dma_transfer_number_get(dma_channel_enum channelx);
Function descriptions	get the number of remaining data to be transferred by the DMA
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
uint32_t	DMA data transmission remaining quantity (0x0-0xFFFF)

Example:

```
/* get DMA channel0 transfer number */
uint32_t number = 0;
number = dma_transfer_number_get(DMA0, DMA_CH0);
```

dma_priority_config

The description of dma_priority_config is shown as below:

Table 3-89. Function dma_priority_config

Function name	dma_priority_config
Function prototype	void dma_priority_config(dma_channel_enum channelx, uint32_t priority);

Function descriptions	configure priority level of DMA channel
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Input parameter{in}	
priority	priority Level of this channel
<i>DMA_PRIORITY_LOW</i>	low priority
<i>DMA_PRIORITY_MEDIUM</i>	medium priority
<i>DMA_PRIORITY_HIGH</i>	high priority
<i>DMA_PRIORITY_ULTRA_HIGH</i>	ultra high priority
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure DMA channel0 priority */
dma_priority_config(DMA_CH0, DMA_PRIORITY_ULTRA_HIGH);
```

dma_memory_width_config

The description of dma_memory_width_config is shown as below:

Table 3-90. Function dma_memory_width_config

Function name	dma_memory_width_config
Function prototype	void dma_memory_width_config(dma_channel_enum channelx, uint32_t mwidth);
Function descriptions	configure transfer data size of memory
Precondition	-

The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Input parameter{in}	
mwidth	transfer data width of memory
<i>DMA_MEMORY_WIDT H_8BIT</i>	transfer data width of memory is 8-bit
<i>DMA_MEMORY_WIDT H_16BIT</i>	transfer data width of memory is 16-bit
<i>DMA_MEMORY_WIDT H_32BIT</i>	transfer data width of memory is 32-bit
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure DMA channel0 memory width */
```

```
dma_memory_width_config(DMA_CH0, DMA_MEMORY_WIDTH_8BIT);
```

dma_periph_width_config

The description of `dma_periph_width_config` is shown as below:

Table 3-91. Function `dma_periph_width_config`

Function name	<code>dma_periph_width_config</code>
Function prototype	<code>void dma_periph_width_config(dma_channel_enum channelx, uint32_t pwidth);</code>
Function descriptions	configure transfer data width of peripheral
Precondition	-
The called functions	-
Input parameter{in}	

channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Input parameter{in}	
pwidth	transfer data width of peripheral
<i>DMA_PERIPHERAL_WIDTH_8BIT</i>	transfer data width of peripheral is 8-bit
<i>DMA_PERIPHERAL_WIDTH_16BIT</i>	transfer data width of peripheral is 16-bit
<i>DMA_PERIPHERAL_WIDTH_32BIT</i>	transfer data width of peripheral is 32-bit
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure DMA channel0 periph width */
```

```
dma_periph_width_config(DMA_CH0, DMA_PERIPHERAL_WIDTH_8BIT);
```

dma_memory_increase_enable

The description of `dma_memory_increase_enable` is shown as below:

Table 3-92. Function `dma_memory_increase_enable`

Function name	<code>dma_memory_increase_enable</code>
Function prototype	<code>void dma_memory_increase_enable(dma_channel_enum channelx);</code>
Function descriptions	enable next address increasement algorithm of memory
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* enable DMA channel0 memory increase */
dma_memory_increase_enable(DMA_CH0);
```

dma_memory_increase_disable

The description of dma_memory_increase_disable is shown as below:

Table 3-93. Function dma_memory_increase_disable

Function name	dma_memory_increase_disable
Function prototype	void dma_memory_increase_disable(dma_channel_enum channelx);
Function descriptions	disable next address increasement algorithm of memory
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DMA channel0 memory increase */
dma_memory_increase_disable(DMA_CH0);
```

dma_periph_increase_enable

The description of dma_periph_increase_enable is shown as below:

Table 3-94. Function dma_periph_increase_enable

Function name	dma_periph_increase_enable
----------------------	----------------------------

Function prototype	void dma_periph_increase_enable(dma_channel_enum channelx);
Function descriptions	enable next address increasement algorithm of peripheral
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DMA channel0 periph increase */
dma_periph_increase_enable(DMA_CH0);
```

dma_periph_increase_disable

The description of dma_periph_increase_disable is shown as below:

Table 3-95. Function dma_periph_increase_disable

Function name	dma_periph_increase_disable
Function prototype	void dma_periph_increase_disable(dma_channel_enum channelx);
Function descriptions	disable next address increasement algorithm of peripheral
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* disable DMA channel0 periph increase */
```

```
dma_periph_increase_disable(DMA_CH0);
```

dma_transfer_direction_config

The description of dma_transfer_direction_config is shown as below:

Table 3-96. Function dma_transfer_direction_config

Function name	dma_transfer_direction_config
Function prototype	void dma_transfer_direction_config(dma_channel_enum channelx, uint32_t direction);
Function descriptions	configure the direction of data transfer on the channel
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Input parameter{in}	
direction	specify the direction of data transfer
<i>DMA_PERIPHERAL_TO_MEMORY</i>	read from peripheral and write to memory
<i>DMA_MEMORY_TO_PERIPHERAL</i>	read from memory and write to peripheral
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure DMA channel0 transfer direction */
```

```
dma_transfer_direction_config(DMA_CH0, DMA_PERIPHERAL_TO_MEMORY);
```

dma_flag_get

The description of dma_flag_get is shown as below:

Table 3-97. Function dma_flag_get

Function name	dma_flag_get
Function prototype	FlagStatus dma_flag_get(dma_channel_enum channelx, uint32_t flag);
Function descriptions	check DMA flag is set or not
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Input parameter{in}	
flag	specify get which flag
<i>DMA_FLAG_G</i>	global interrupt flag of channel
<i>DMA_FLAG_FTF</i>	full transfer finish flag of channel
<i>DMA_FLAG_HTF</i>	half transfer finish flag of channel
<i>DMA_FLAG_ERR</i>	error flag of channel
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get DMA channel0 flag */
```

```
FlagStatus flag = RESET;
```

```
flag = dma_flag_get(DMA_CH0, DMA_FLAG_FTF);
```

dma_flag_clear

The description of dma_flag_clear is shown as below:

Table 3-98. Function dma_flag_clear

Function name	dma_flag_clear
Function prototype	void dma_flag_clear(dma_channel_enum channelx, uint32_t flag);
Function descriptions	clear DMA a channel flag
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Input parameter{in}	
flag	specify get which flag
<i>DMA_FLAG_G</i>	global interrupt flag of channel
<i>DMA_FLAG_FTF</i>	full transfer finish flag of channel
<i>DMA_FLAG_HTF</i>	half transfer finish flag of channel
<i>DMA_FLAG_ERR</i>	error flag of channel
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear DMA channel0 flag */
dma_flag_clear(DMA_CH0, DMA_FLAG_FTF);
```

dma_interrupt_flag_get

The description of dma_interrupt_flag_get is shown as below:

Table 3-99. Function dma_interrupt_flag_get

Function name	dma_interrupt_flag_get
Function prototype	FlagStatus dma_interrupt_flag_get(dma_channel_enum channelx, uint32_t flag);
Function descriptions	check DMA flag and interrupt enable bit is set or not

Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Input parameter{in}	
flag	specify get which flag
<i>DMA_INT_FLAG_FTF</i>	full transfer finish interrupt flag of channel
<i>DMA_INT_FLAG_HTF</i>	half transfer finish interrupt flag of channel
<i>DMA_INT_FLAG_ERR</i>	error interrupt flag of channel
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```

/* get DMA interrupt_flag */
if(dma_interrupt_flag_get(DMA_CH3, DMA_INT_FLAG_FTF)){
    dma_interrupt_flag_clear(DMA_CH3, DMA_INT_FLAG_G);
}

```

dma_interrupt_flag_clear

The description of dma_interrupt_flag_clear is shown as below:

Table 3-100. Function dma_interrupt_flag_clear

Function name	dma_interrupt_flag_clear
Function prototype	void dma_interrupt_flag_clear(dma_channel_enum channelx, uint32_t flag);
Function descriptions	clear DMA a channel flag
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel

<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Input parameter{in}	
flag	specify get which flag
<i>DMA_INT_FLAG_G</i>	global interrupt flag of channel
<i>DMA_INT_FLAG_FTF</i>	full transfer finish interrupt flag of channel
<i>DMA_INT_FLAG_HTF</i>	half transfer finish interrupt flag of channel
<i>DMA_INT_FLAG_ERR</i>	error interrupt flag of channel
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* get DMA interrupt_flag */

if(dma_interrupt_flag_get(DMA_CH3, DMA_INT_FLAG_FTF)){
    dma_interrupt_flag_clear(DMA_CH3, DMA_INT_FLAG_G);
}

```

dma_interrupt_enable

The description of dma_interrupt_enable is shown as below:

Table 3-101. Function dma_interrupt_enable

Function name	dma_interrupt_enable
Function prototype	void dma_interrupt_enable(dma_channel_enum channelx, uint32_t source);
Function descriptions	enable DMA interrupt
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Input parameter{in}	
source	DMA interrupt source

<i>DMA_INT_FTF</i>	full transfer finish interrupt of channel
<i>DMA_INT_HTF</i>	half transfer finish interrupt of channel
<i>DMA_INT_ERR</i>	error interrupt of channel
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DMA channel0 interrupt */
```

```
dma_interrupt_enable(DMA_CH0, DMA_INT_FTF);
```

dma_interrupt_disable

The description of `dma_interrupt_disable` is shown as below:

Table 3-102. Function `dma_interrupt_disable`

Function name	<code>dma_interrupt_disable</code>
Function prototype	<code>void dma_interrupt_disable(dma_channel_enum channelx, uint32_t source);</code>
Function descriptions	disable DMA interrupt
Precondition	-
The called functions	-
Input parameter{in}	
channelx	DMA channel
<i>DMA_CHx(x=0..4)</i>	DMA channel selection
Input parameter{in}	
source	DMA interrupt source
<i>DMA_INT_FTF</i>	full transfer finish interrupt of channel
<i>DMA_INT_HTF</i>	half transfer finish interrupt of channel
<i>DMA_INT_ERR</i>	error interrupt of channel
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* disable DMA channel0 interrupt */
```

```
dma_interrupt_disable(DMA_CH0, DMA_INT_FTF);
```

3.7. EXTI

EXTI is the interrupt/event controller in the MCU. It contains up to 21 independent edge detectors and generates interrupt requests or events to the processor. The EXTI registers are listed in chapter [3.7.1](#), the EXTI firmware functions are introduced in chapter [3.7.2](#).

3.7.1. Descriptions of Peripheral registers

EXTI registers are listed in the table shown as below:

Table 3-103. EXTI Registers

Registers	Descriptions
EXTI_INTEN	Interrupt enable register
EXTI_EVEN	Event enable register
EXTI_RTEN	Rising edge trigger enable register
EXTI_FTEN	Falling edge trigger enable register
EXTI_SWIEV	Software interrupt event register
EXTI_PD	Pending register

3.7.2. Descriptions of Peripheral functions

EXTI firmware functions are listed in the table shown as below:

Table 3-104. EXTI firmware function

Function name	Function description
exti_deinit	reset EXTI
exti_init	initialize EXTI line x
exti_interrupt_enable	enable EXTI line x interrupt
exti_event_enable	enable EXTI line x event

Function name	Function description
exti_interrupt_disable	disable EXTI line x interrupt
exti_event_disable	disable EXTI line x event
exti_flag_get	get EXTI line x flag
exti_flag_clear	clear EXTI line x flag
exti_interrupt_flag_get	get EXTI line x interrupt flag
exti_interrupt_flag_clear	clear EXTI line x interrupt flag
exti_software_interrupt_enable	enable EXTI line x software interrupt
exti_software_interrupt_disable	disable EXTI line x software interrupt

exti_deinit

The description of exti_deinit is shown as below:

Table 3-105. Function exti_deinit

Function name	exti_deinit
Function prototype	void exti_deinit(void);
Function descriptions	reset EXTI. reset the value of all EXTI registers into initial values
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* deinitialize the EXTI */
exti_deinit();
```

exti_init

The description of exti_init is shown as below:

Table 3-106. Function exti_init

Function name	exti_init
Function prototype	void exti_init(exti_line_enum linex, exti_mode_enum mode, exti_trig_type_enum trig_type);
Function descriptions	initialize EXTI line x
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x
<i>EXTI_x</i>	x=0..17,19,21
Input parameter{in}	
mode	EXTI mode
<i>EXTI_INTERRUPT</i>	interrupt mode
<i>EXTI_EVENT</i>	event mode
Input parameter{in}	
trig_type	trigger type
<i>EXTI_TRIG_RISING</i>	rising edge trigger
<i>EXTI_TRIG_FALLING</i>	falling edge trigger
<i>EXTI_TRIG_BOTH</i>	rising edge and falling edge trigger
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure EXTI_0 */
exti_init(EXTI_0, EXTI_INTERRUPT, EXTI_TRIG_BOTH);
```

exti_interrupt_enable

The description of exti_interrupt_enable is shown as below:

Table 3-107. Function exti_interrupt_enable

Function name	exti_interrupt_enable
Function prototype	void exti_interrupt_enable(exti_line_enum linex);
Function descriptions	enable EXTI line x interrupt
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x
<i>EXTI_x</i>	x=0,1,2..27
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the interrupts from EXTI line 0 */
exti_interrupt_enable(EXTI_0);
```

exti_event_enable

The description of exti_event_enable is shown as below:

Table 3-108. Function exti_event_enable

Function name	exti_event_enable
Function prototype	void exti_event_enable(exti_line_enum linex);
Function descriptions	enable EXTI line x event
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x
<i>EXTI_x</i>	x=0,1,2..27
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* enable the events from EXTI line 0 */
exti_event_enable(EXTI_0);
```

exti_interrupt_disable

The description of exti_interrupt_disable is shown as below:

Table 3-109. Function exti_interrupt_disable

Function name	exti_interrupt_disable
Function prototype	void exti_interrupt_disable(exti_line_enum linex);
Function descriptions	disable EXTI line x interrupt
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x
<i>EXTI_x</i>	x=0,1,2..27
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the interrupts from EXTI line 0 */
exti_interrupt_disable(EXTI_0);
```

exti_event_disable

The description of exti_event_disable is shown as below:

Table 3-110. Function exti_event_disable

Function name	exti_event_disable
----------------------	--------------------

Function prototype	void exti_event_disable(exti_line_enum linex);
Function descriptions	disable EXTI line x event
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x
<i>EXTI_x</i>	x=0,1,2..27
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the events from EXTI line 0 */
```

```
exti_event_disable(EXTI_0);
```

exti_flag_get

The description of exti_flag_get is shown as below:

Table 3-111. Function exti_flag_get

Function name	exti_flag_get
Function prototype	FlagStatus exti_flag_get(exti_line_enum linex);
Function descriptions	get EXTI line x flag
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x
<i>EXTI_x</i>	x=0,1,2..17, 19, 21
Output parameter{out}	
-	-
Return value	

FlagStatus	SET or RESET
-------------------	--------------

Example:

```
/* get EXTI line 0 flag status */
```

```
FlagStatus state = exti_flag_get(EXTI_0);
```

exti_flag_clear

The description of exti_flag_clear is shown as below:

Table 3-112. Function exti_flag_clear

Function name	exti_flag_clear
Function prototype	void exti_flag_clear(exti_line_enum linex);
Function descriptions	clear EXTI line x flag
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x
<i>EXTI_x</i>	x=0,1,2..17, 19, 21
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear EXTI line 0 flag status */
```

```
exti_flag_clear(EXTI_0);
```

exti_interrupt_flag_get

The description of exti_interrupt_flag_get is shown as below:

Table 3-113. Function exti_interrupt_flag_get

Function name	exti_interrupt_flag_get
Function prototype	FlagStatus exti_interrupt_flag_get(exti_line_enum linex);
Function descriptions	get EXTI line x interrupt flag

Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x
<i>EXTI_x</i>	x=0,1,2..17, 19, 21
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get EXTI line 0 interrupt flag status */
```

```
FlagStatus state = exti_interrupt_flag_get(EXTI_0);
```

exti_interrupt_flag_clear

The description of exti_interrupt_flag_clear is shown as below:

Table 3-114. Function exti_interrupt_flag_clear

Function name	exti_interrupt_flag_clear
Function prototype	void exti_interrupt_flag_clear(exti_line_enum linex);
Function descriptions	clear EXTI line x interrupt flag
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x
<i>EXTI_x</i>	x=0,1,2..17, 19, 21
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear EXTI line 0 interrupt flag status */
```

```
exti_interrupt_flag_clear(EXTI_0);
```

exti_software_interrupt_enable

The description of `exti_software_interrupt_enable` is shown as below:

Table 3-115. Function `exti_software_interrupt_enable`

Function name	<code>exti_software_interrupt_enable</code>
Function prototype	<code>void exti_software_interrupt_enable(exti_line_enum linex);</code>
Function descriptions	enable EXTI line x software interrupt
Precondition	-
The called functions	-
Input parameter{in}	
linex	EXTI line x
<i>EXTI_x</i>	x=0,1,2..17, 19, 21
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable EXTI line 0 software interrupt */
```

```
exti_software_interrupt_enable(EXTI_0);
```

exti_software_interrupt_disable

The description of `exti_software_interrupt_disable` is shown as below:

Table 3-116. Function `exti_software_interrupt_disable`

Function name	<code>exti_software_interrupt_disable</code>
Function prototype	<code>void exti_software_interrupt_disable(exti_line_enum linex);</code>
Function descriptions	disable EXTI line x software interrupt
Precondition	-
The called functions	-

Input parameter{in}	
linex	EXTI line x
EXTI_x	x=0,1,2..17, 19, 21
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable EXTI line 0 software interrupt */
exti_software_interrupt_disable(EXTI_0);
```

3.8. FMC

There is flash controller and option byte for GD32E230 series. The FMC registers are listed in chapter [3.8.1](#) the FMC firmware functions are introduced in chapter [3.8.2](#).

3.8.1. Descriptions of Peripheral registers

FMC registers are listed in the table shown as below:

Table 3-117. FMC Registers

Registers	Descriptions
FMC_WS	FMC wait state register
FMC_KEY	FMC unlock key register
FMC_OBKEY	FMC option bytes unlock key register
FMC_STAT	FMC status register
FMC_CTL	FMC control register
FMC_ADDR	FMC address register
FMC_OBSTAT	FMC option bytes status register
FMC_WP	FMC write protection register
FMC_PID	FMC product ID register

3.8.2. Descriptions of Peripheral functions

FMC firmware functions are listed in the table shown as below:

Table 3-118. FMC firmware function

Function name	Function description
fmc_unlock	unlock the main FMC operation
fmc_lock	lock the main FMC operation
fmc_wscnt_set	set the wait state counter value
fmc_prefetch_enable	enable pre-fetch
fmc_prefetch_disable	disable pre-fetch
fmc_page_erase	erase FMC page
fmc_mass_erase	erase FMC whole chip
fmc_doubleword_program	FMC program a double word at the corresponding address
fmc_word_program	FMC program a word at the corresponding address
ob_unlock	unlock the option byte operation
ob_lock	lock the option byte operation
ob_reset	reload the option byte and generate a system reset
option_byte_value_get	get option byte value
ob_erase	erase the option byte
ob_write_protection_enable	enable option byte write protection (OB_WP)
ob_security_protection_config	configure read out protect
ob_user_write	write the FMC option byte user
ob_data_program	write the FMC option byte data
ob_user_get	get the FMC option byte OB_USER
ob_data_get	get the FMC option byte OB_DATA
ob_write_protection_get	get the FMC option byte write protection
ob_obstat_plevel_get	get the value of FMC option byte security protection level (PLEVEL) in FMC_OBSTAT register
fmc_interrupt_enable	enable FMC interrupt
fmc_interrupt_disable	disable FMC interrupt

Function name	Function description
fmc_flag_get	get flag set or reset
fmc_flag_clear	clear the FMC pending flag
fmc_interrupt_flag_get	get interrupt flag set or reset
fmc_interrupt_flag_clear	clear the FMC interrupt pending flag by writing 1
fmc_state_get	return the FMC state
fmc_ready_wait	check FMC ready or not

fmc_state_enum

Table 3-119. fmc_state_enum

enum name	enum description
FMC_READY	the operation has been completed
FMC_BUSY	the operation is in progress
FMC_PGERR	program error
FMC_PGAERR	program alignment error
FMC_WPERR	erase/program protection error
FMC_TOERR	timeout error
FMC_OB_HSPC	option byte security protection code high

fmc_unlock

The description of fmc_unlock is shown as below:

Table 3-120. Function fmc_unlock

Function name	fmc_unlock
Function prototype	void fmc_unlock (void);
Function descriptions	unlock the main FMC operation
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* unlock the main FMC operation */
```

```
fmc_unlock ( );
```

fmc_lock

The description of fmc_lock is shown as below:

Table 3-121. Function fmc_lock

Function name	fmc_lock
Function prototype	void fmc_lock(void);
Function descriptions	lock the main FMC operation
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* lock the main FMC operation */
```

```
fmc_lock( );
```

fmc_wscnt_set

The description of fmc_wscnt_set is shown as below:

Table 3-122. Function fmc_wscnt_set

Function name	fmc_wscnt_set
Function prototype	void fmc_wscnt_set(uint32_t wscnt);

Function descriptions	set the wait state counter value
Precondition	-
The called functions	-
Input parameter{in}	
wscnt	wait state counter value
<i>WS_WSCNT_0</i>	FMC 0 wait
<i>WS_WSCNT_1</i>	FMC 1 wait
<i>WS_WSCNT_2</i>	FMC 2 wait
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set the wait state counter value */
```

```
fmc_wscnt_set (WS_WSCNT_1);
```

fmc_prefetch_enable

The description of fmc_prefetch_enable is shown as below:

Table 3-123. Function fmc_prefetch_enable

Function name	fmc_prefetch_enable
Function prototype	void fmc_prefetch_enable(void);
Function descriptions	enable pre-fetch
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* enable pre-fetch */
```

```
fmc_prefetch_enable( );
```

fmc_prefetch_disable

The description of fmc_prefetch_disable is shown as below:

Table 3-124. Function fmc_prefetch_disable

Function name	fmc_prefetch_disable
Function prototype	void fmc_prefetch_disable (void);
Function descriptions	disable pre-fetch
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable pre-fetch */
```

```
fmc_prefetch_disable( );
```

fmc_page_erase

The description of fmc_page_erase is shown as below:

Table 3-125. Function fmc_page_erase

Function name	fmc_page_erase
Function prototype	fmc_state_enum fmc_page_erase(uint32_t page_address);
Function descriptions	erase page
Precondition	fmc_unlock

The called functions	fmc_ready_wait
Input parameter{in}	
page_address	the page address to be erased
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC,the enum members can refer to members of the enum Table 3-119. fmc_state_enum

Example:

```
/* erase page */
```

```
fmc_state_enum state = fmc_page_erase ( 0x08004000);
```

fmc_mass_erase

The description of fmc_mass_erase is shown as below:

Table 3-126. Function fmc_mass_erase

Function name	fmc_mass_erase
Function prototype	fmc_state_enum fmc_mass_erase(void);
Function descriptions	erase whole chip
Precondition	fmc_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC,the enum members can refer to members of the enum Table 3-119. fmc_state_enum

Example:

```
/* erase whole chip */
```

```
fmc_state_enum state = fmc_mass_erase ( );
```

fmc_doubleword_program

The description of fmc_doubleword_program is shown as below:

Table 3-127. Function fmc_doubleword_program

Function name	fmc_doubleword_program
Function prototype	fmc_state_enum fmc_doubleword_program(uint32_t address, uint64_t data);
Function descriptions	program a double word at the corresponding address
Precondition	fmc_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
address	the address to program
Input parameter{in}	
data	the data to program
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC, the enum members can refer to members of the enum Table 3-119. fmc_state_enum

Example:

```
/* program a double word at the corresponding address */
```

```
fmc_state_enum fmc_state = fmc_doubleword_program( 0x08004000, 0xaabbccddeeffgghh);
```

fmc_word_program

The description of fmc_word_program is shown as below:

Table 3-128. Function fmc_word_program

Function name	fmc_word_program
Function prototype	fmc_state_enum fmc_word_program(uint32_t address, uint32_t data);
Function descriptions	program a word at the corresponding address
Precondition	fmc_unlock
The called functions	fmc_ready_wait

Input parameter{in}	
address	the address to program
data	the data to program
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC,the enum members can refer to members of the enum Table 3-119. fmc_state_enum

Example:

```
/* program a word at the corresponding address */
```

```
fmc_state_enum fmc_state = fmc_word_program ( 0x08004000,0xaabbccdd);
```

ob_unlock

The description of ob_unlock is shown as below:

Table 3-129. Function ob_unlock

Function name	ob_unlock
Function prototype	void ob_unlock(void);
Function descriptions	unlock the option byte operation
Precondition	fmc_unlock
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* unlock the option byte operation */
```

```
ob_unlock( );
```

ob_lock

The description of ob_lock is shown as below:

Table 3-130. Function ob_lock

Function name	ob_lock
Function prototype	void ob_lock(void);
Function descriptions	lock the option byte operation
Precondition	fmc_lock
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* lock the option byte operation */
ob_lock( );
```

ob_reset

The description of ob_reset is shown as below:

Table 3-131. Function ob_reset

Function name	ob_reset
Function prototype	void ob_reset (void);
Function descriptions	reload the option byte and generate a system reset
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* reload the option byte and generate a system reset */
```

```
ob_reset ( );
```

option_byte_value_get

The description of option_byte_value_get is shown as below:

Table 3-132. Function option_byte_value_get

Function name	option_byte_value_get
Function prototype	uint32_t option_byte_value_get(uint32_t addr);
Function descriptions	get option byte value
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint32_t	option byte value

Example:

```
/* get option byte value*/
```

```
uint32_t temp;
```

```
temp = option_byte_value_get(0x1fff f800);
```

ob_erase

The description of ob_erase is shown as below:

Table 3-133. Function ob_erase

Function name	ob_erase
----------------------	----------

Function prototype	void ob_erase(void);
Function descriptions	erase the option byte
Precondition	ob_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC,the enum members can refer to members of the enum Table 3-119. fmc_state_enum

Example:

```
/* erase the option byte */
```

```
fmc_state_enum fmc_state = ob_erase ( );
```

ob_write_protection_enable

The description of ob_write_protection_enable is shown as below:

Table 3-134. Function ob_write_protection_enable

Function name	ob_write_protection_enable
Function prototype	fmc_state_enum ob_write_protection_enable(uint16_t ob_wp);
Function descriptions	enable option byte write protection (OB_WP)
Precondition	ob_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
ob_wp	write protection configuration data
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC,the enum members can refer to members of the enum Table 3-119. fmc_state_enum

Example:

```
/* enable write protection */
```

```
fmc_state_enum fmc_state = ob_write_protection_enable (0x01);
```

ob_security_protection_config

The description of ob_security_protection_config is shown as below:

Table 3-135. Function ob_security_protection_config

Function name	ob_security_protection_config
Function prototype	fmc_state_enum ob_security_protection_config (uint16_t ob_spc);
Function descriptions	configure security protection
Precondition	ob_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
ob_spc	specify security protection
<i>FMC_NSPC</i>	no security protection
<i>FMC_LSPC</i>	low security protection
<i>FMC_HSPC</i>	high security protection
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC, the enum members can refer to members of the enum Table 3-119. fmc_state_enum

Example:

```
/* enable security protection */
```

```
fmc_state_enum fmc_state;
```

```
fmc_state = ob_security_protection_config (FMC_USPC);
```

ob_user_write

The description of ob_user_write is shown as below:

Table 3-136. Function ob_user_write

Function name	ob_user_write
Function prototype	fmc_state_enum ob_user_write(uint8_t ob_user);
Function descriptions	program the FMC user option byte
Precondition	ob_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
ob_user	user option byte
<i>OB_FWDGT_HW</i>	hardware free watchdog timer
<i>OB_DEEPSLEEP_RST</i>	no reset when entering deepsleep mode
<i>OB_STDBY_RST</i>	no reset when entering deepsleep mode
<i>OB_BOOT1_SET_1</i>	BOOT1 bit is 1
<i>OB_VDDA_DISABLE</i>	disable VDDA monitor
<i>OB_SRAM_PARITY_ENABLE</i>	enable SRAM parity check
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC,the enum members can refer to members of the enum Table 3-119. fmc_state_enum

Example:

```
/* program the FMC user option byte */
fmc_state_enum fmc_state = ob_user_write(OB_FWDGT_HW);
```

ob_data_program

The description of ob_data_program is shown as below:

Table 3-137. Function ob_data_program

Function name	ob_data_program
Function prototype	fmc_state_enum ob_data_program(uint16_t data);
Function descriptions	program the FMC data option byte

Precondition	ob_unlock
The called functions	fmc_ready_wait
Input parameter{in}	
data	the data to be programmed, OB_DATA[0:15]
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC,the enum members can refer to members of the enum Table 3-119. fmc_state_enum

Example:

```
/* program option bytes data */
```

```
fmc_state_enum fmc_state = ob_data_program (0x56);
```

ob_user_get

The description of ob_user_get is shown as below:

Table 3-138. Function ob_user_get

Function name	ob_user_get
Function prototype	uint8_t ob_user_get(void);
Function descriptions	get OB_USER in register FMC_OBSTAT
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint8_t	the FMC user option byte values(0x00 – 0xFF)

Example:

```
/* get the FMC user option byte */
```

```
uint8_t user = ob_user_get ( );
```

ob_data_get

The description of ob_data_get is shown as below:

Table 3-139. Function ob_data_get

Function name	ob_data_get
Function prototype	uint16_t ob_data_get(void);
Function descriptions	get OB_DATA in register FMC_OBSTAT
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint16_t	the FMC data option byte values(0x0 – 0xFFFF)

Example:

```
/* get the FMC data option byte */
uint16_t data = ob_data_get ( );
```

ob_write_protection_get

The description of ob_write_protection_get is shown as below:

Table 3-140. Function ob_write_protection_get

Function name	ob_write_protection_get
Function prototype	uint16_t ob_write_protection_get(void);
Function descriptions	get the FMC option byte write protection (OB_WP) in register FMC_WP
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	

-	-
Return value	
uint16_t	the FMC write protection option byte value(0x0 – 0XFFFF)

Example:

```
/* get the FMC option byte write protection */
uint16_t wp = ob_write_protection_get ( );
```

ob_obstat_plevel_get

The description of ob_obstat_plevel_get is shown as below:

Table 3-141. Function ob_obstat_plevel_get

Function name	ob_obstat_plevel_get
Function prototype	uint32_t ob_obstat_plevel_get(void);
Function descriptions	get the value of FMC option byte security protection level (PLEVEL) in FMC_OBSTAT register
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint8_t	the value of PLEVEL(0x0,0x01,0x03)

Example:

```
/* get the FMC option byte security protection level */
uint32_t obstat_plevel = ob_obstat_plevel_get ( );
```

fmc_interrupt_enable

The description of fmc_interrupt_enable is shown as below:

Table 3-142. Function fmc_interrupt_enable

Function name	fmc_interrupt_enable
----------------------	----------------------

Function prototype	void fmc_interrupt_enable(uint32_t interrupt);
Function descriptions	enable FMC interrupt
Precondition	-
The called functions	-
Input parameter{in}	
interrupt	the FMC interrupt source
<i>FMC_INT_END</i>	FMC end of program interrupt
<i>FMC_INT_ERR</i>	FMC error interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable FMC interrupt */
fmc_interrupt_enable(FMC_INT_END);
```

fmc_interrupt_disable

The description of fmc_interrupt_disable is shown as below:

Table 3-143. Function fmc_interrupt_disable

Function name	fmc_interrupt_disable
Function prototype	void fmc_interrupt_disable(uint32_t interrupt);
Function descriptions	disable FMC interrupt
Precondition	-
The called functions	-
Input parameter{in}	
interrupt	the FMC interrupt source
<i>FMC_INT_END</i>	FMC end of program interrupt
<i>FMC_INT_ERR</i>	FMC error interrupt
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* disable FMC interrupt */
```

```
fmc_interrupt_disable(FMC_INT_END);
```

fmc_flag_get

The description of fmc_flag_get is shown as below:

Table 3-144. Function fmc_flag_get

Function name	fmc_flag_get
Function prototype	FlagStatus fmc_flag_get(uint32_t flag);
Function descriptions	check FMC flag
Precondition	-
The called functions	-
Input parameter{in}	
flag	check FMC flag
<i>FMC_FLAG_BUSY</i>	FMC busy flag bit
<i>FMC_FLAG_PGERR</i>	FMC programming error flag
<i>FMC_FLAG_PGAERR</i>	FMC program alignment error flag bit
<i>FMC_FLAG_WPERR</i>	FMC write protection error flag
<i>FMC_FLAG_END</i>	FMC end of programming flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get FMC flag */
```

```
FlagStatus flag = fmc_flag_get(FMC_FLAG_END);
```

fmc_flag_clear

The description of fmc_flag_clear is shown as below:

Table 3-145. Function fmc_flag_clear

Function name	fmc_flag_clear
Function prototype	void fmc_flag_clear(uint32_t flag);
Function descriptions	clear the FMC flag by writing 1
Precondition	-
The called functions	-
Input parameter{in}	
flag	clear FMC flag
<i>FMC_FLAG_PGERR</i>	FMC operation error flag
<i>FMC_FLAG_PGAERR</i>	FMC program alignment error flag
<i>FMC_FLAG_WPERR</i>	FMC erase/program protection error flag
<i>FMC_FLAG_END</i>	FMC end of operation flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* get FMC flag */
fmc_flag_clear(FMC_FLAG_END);
```

fmc_interrupt_flag_get

The description of fmc_interrupt_flag_get is shown as below:

Table 3-146. Function fmc_interrupt_flag_get

Function name	fmc_interrupt_flag_get
Function prototype	FlagStatus fmc_interrupt_flag_get(uint32_t int_flag);
Function descriptions	get interrupt flag set or reset
Precondition	-

The called functions	-
Input parameter{in}	
flag	FMC flag
<i>FMC_INT_FLAG_PGE</i> <i>RR</i>	FMC operation error flag
<i>FMC_INT_FLAG_PGA</i> <i>ERR</i>	FMC program alignment error flag
<i>FMC_INT_FLAG_WPE</i> <i>RR</i>	FMC erase/program protection error flag
<i>FMC_INT_FLAG_END</i>	FMC end of operation flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get FMC flag */
```

```
FlagStatus flag = fmc_interrupt_flag_get (FMC_INT_FLAG_PGERR);
```

fmc_interrupt_flag_clear

The description of fmc_interrupt_flag_get is shown as below:

Table 3-147. Function fmc_interrupt_flag_clear

Function name	fmc_interrupt_flag_clear
Function prototype	void fmc_interrupt_flag_clear(uint32_t int_flag);
Function descriptions	clear the FMC interrupt pending flag by writing 1
Precondition	-
The called functions	-
Input parameter{in}	
flag	clear FMC flag
<i>FMC_INT_FLAG_PGE</i> <i>RR</i>	FMC operation error flag

<i>FMC_INT_FLAG_PGA ERR</i>	FMC program alignment error flag
<i>FMC_INT_FLAG_WPE RR</i>	FMC erase/program protection error flag
<i>FMC_INT_FLAG_END</i>	FMC end of operation flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear FMC flag */
```

```
fmc_interrupt_flag_get (FMC_INT_FLAG_PGERR);
```

fmc_state_get

The description of `fmc_state_get` is shown as below:

Table 3-148. Function `fmc_state_get`

Function name	<code>fmc_state_get</code>
Function prototype	<code>fmc_state_enum fmc_state_get(void);</code>
Function descriptions	get the FMC state
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC,the enum members can refer to members of the enum Table 3-119. fmc_state_enum

Example:

```
/* get the FMC state */
```

```
fmc_state_enum state = fmc_state_get();
```

fmc_ready_wait

The description of fmc_ready_wait is shown as below:

Table 3-149. Function fmc_ready_wait

Function name	fmc_ready_wait
Function prototype	fmc_state_enum fmc_ready_wait(uint32_t timeout);
Function descriptions	check whether FMC is ready or not
Precondition	-
The called functions	fmc_state_get()
Input parameter{in}	
timeout	timeout count
Output parameter{out}	
-	-
Return value	
fmc_state_enum	state of FMC, the enum members can refer to members of the enum Table 3-119. fmc_state_enum

Example:

```
/* check whether FMC is ready or not */
fmc_state_enum state = fmc_ready_wait (0x00001000 );
```

3.9. FWDGT

The free watchdog timer (FWDGT) is a hardware timing circuitry that can be used to detect system failures due to software malfunctions. It's suitable for the situation that requires an independent environment and lower timing accuracy. The FWDGT registers are listed in chapter [3.9.1](#) the FWDGT firmware functions are introduced in chapter [3.9.2](#).

3.9.1. Descriptions of Peripheral registers

FWDGT registers are listed in the table shown as below:

Table 3-150. FWDGT Registers

Registers	Descriptions
FWDGT_CTL	Control register
FWDGT_PSC	Prescaler register
FWDGT_RLD	Reload register
FWDGT_STAT	Status register
FWDGT_WND	window register

3.9.2. Descriptions of Peripheral functions

FWDGT firmware functions are listed in the table shown as below:

Table 3-151. FWDGT firmware function

Function name	Function description
fwdgt_write_enable	enable write access to FWDGT_PSC and FWDGT_RLD
fwdgt_write_disable	disable write access to FWDGT_PSC and FWDGT_RLD
fwdgt_enable	start the FWDGT counter
fwdgt_prescaler_value_config	configure the FWDGT counter clock prescaler value
fwdgt_reload_value_config	configure the FWDGT counter reload value
fwdgt_window_value_config	configure the FWDGT counter window value
fwdgt_counter_reload	reload the counter of FWDGT
fwdgt_config	configure counter reload value, and prescaler divider value
fwdgt_flag_get	get flag state of FWDGT

fwdgt_write_enable

The description of fwdgt_write_enable is shown as below:

Table 3-152. Function fwdgt_write_enable

Function name	fwdgt_write_enable
Function prototype	void fwdgt_write_enable(void);
Function descriptions	enable write access to FWDGT_PSC and FWDGT_RLD
Precondition	-
The called functions	-

Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable write access to FWDGT_PSC and FWDGT_RLD */
```

```
fwdgt_write_enable ( );
```

fwdgt_write_disable

The description of fwdgt_write_disable is shown as below:

Table 3-153. Function fwdgt_write_disable

Function name	fwdgt_write_disable
Function prototype	void fwdgt_write_disable(void);
Function descriptions	disable write access to FWDGT_PSC and FWDGT_RLD
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable write access to FWDGT_PSC and FWDGT_RLD */
```

```
fwdgt_write_disable ( );
```

fwdgt_enable

The description of fwdgt_enable is shown as below:

Table 3-154. Function fwdgt_enable

Function name	fwdgt_enable
Function prototype	void fwdgt_enable(void);
Function descriptions	start the FWDGT counter
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* start the free watchdog timer counter */
```

```
fwdgt_enable ( );
```

fwdgt_prescaler_value_config

The description of fwdgt_prescaler_value_config is shown as below:

Table 3-155. Function fwdgt_prescaler_value_config

Function name	fwdgt_prescaler_value_config
Function prototype	ErrStatus fwdgt_prescaler_value_config(uint16_t prescaler_value);
Function descriptions	configure the FWDGT counter clock prescaler value
Precondition	-
The called functions	-
Input parameter{in}	
prescaler_value	specify prescaler value
<i>FWDGT_PSC_DIVx</i>	FWDGT prescaler set to x(x=4,8,16,32,64,128,256)
Output parameter{out}	
-	-

Return value	
ErrStatus	ERROR / SUCCESS

Example:

```
/* set FWDGT prescaler to 4 */
```

```
ErrStatus flag;
```

```
flag = fwdgt_prescaler_value_config (FWDGT_PSC_DIV4);
```

fwdgt_reload_value_config

The description of fwdgt_reload_value_config is shown as below:

Table 3-156. Function fwdgt_reload_value_config

Function name	fwdgt_reload_value_config
Function prototype	ErrStatus fwdgt_reload_value_config(uint16_t reload_value);
Function descriptions	configure the FWDGT counter reload value
Precondition	-
The called functions	-
Input parameter{in}	
reload_value	reload_value: specify reload value(0x0000 - 0x0FFF)
Output parameter{out}	
-	-
Return value	
ErrStatus	ERROR / SUCCESS

Example:

```
/* set FWDGT reload value to 0xFFFF */
```

```
ErrStatus flag;
```

```
flag = fwdgt_reloadr_value_config (0xFFFF);
```

fwdgt_window_value_config

The description of fwdgt_window_value_config is shown as below:

Table 3-157. Function fwdgt_window_value_config

Function name	fwdgt_window_value_config
----------------------	---------------------------

Function prototype	ErrStatus fwdgt_window_value_config(uint16_t window_value);
Function descriptions	configure the FWDGT counter window value
Precondition	-
The called functions	-
Input parameter{in}	
window_value	window_value: specify window value(0x0000 - 0x0FFF)
Output parameter{out}	
-	-
Return value	
ErrStatus	ERROR / SUCCESS

Example:

```
/* set FWDGT window value to 0xFFFF */
```

ErrStatus flag;

```
flag = fwdgt_window_value_config (0xFFFF);
```

fwdgt_counter_reload

The description of fwdgt_counter_reload is shown as below:

Table 3-158. Function fwdgt_counter_reload

Function name	fwdgt_counter_reload
Function prototype	void fwdgt_counter_reload(void);
Function descriptions	reload the counter of FWDGT
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reload FWDGT counter */
```

```
fwdgt_counter_reload ( );
```

fwdgt_config

The description of fwdgt_config is shown as below:

Table 3-159. Function fwdgt_config

Function name	fwdgt_config
Function prototype	ErrStatus fwdgt_config(uint16_t reload_value, uint8_t prescaler_div);
Function descriptions	configure counter reload value, and prescaler divider value
Precondition	-
The called functions	-
Input parameter{in}	
reload_value	specify reload value(0x0000 - 0x0FFF)-
Input parameter{in}	
prescaler_div	FWDGT prescaler value-
<i>FWDGT_PSC_DIV4</i>	FWDGT prescaler set to 4
<i>FWDGT_PSC_DIV8</i>	FWDGT prescaler set to 8
<i>FWDGT_PSC_DIV16</i>	FWDGT prescaler set to 16
<i>FWDGT_PSC_DIV32</i>	FWDGT prescaler set to 32
<i>FWDGT_PSC_DIV64</i>	FWDGT prescaler set to 64
<i>FWDGT_PSC_DIV128</i>	FWDGT prescaler set to 128
<i>FWDGT_PSC_DIV256</i>	FWDGT prescaler set to 256
Output parameter{out}	
-	-
Return value	
ErrStatus	ERROR or SUCCESS

Example:

```
/* confiure FWDGT counter clock: 40KHz(IRC40K) / 64 = 0.625 KHz */
```

```
fwdgt_config(2*500, FWDGT_PSC_DIV64);
```


fwdgt_flag_get

The description of fwdgt_flag_get is shown as below:

Table 3-160. Function fwdgt_flag_get

Function name	fwdgt_flag_get
Function prototype	FlagStatus fwdgt_flag_get(uint16_t flag);
Function descriptions	get flag state of FWDGT
Precondition	-
The called functions	-
Input parameter{in}	
flag	flag to get
<i>FWDGT_FLAG_PUD</i>	a write operation to FWDGT_PSC register is on going
<i>FWDGT_FLAG_RUD</i>	a write operation to FWDGT_RLD register is on going
<i>FWDGT_FLAG_WUD</i>	a write operation to FWDGT_WND register is on going
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```

/* test if a prescaler value update is on going */
FlagStatus status;

status = fwdgt_flag_get (FWDGT_FLAG_PUD);

if(status == RESET)
{
...
}else
{
...
}

```

3.10. GPIO

GPIO is used to implement logic input/output functions for the devices. The GPIO registers are listed in chapter [3.10.1](#), the GPIO firmware functions are introduced in chapter [3.10.2](#).

3.10.1. Descriptions of Peripheral registers

GPIO registers are listed in the table shown as below:

Table 3-161. GPIO Registers

Registers	Descriptions
GPIOx_CTL	GPIO port control register
GPIOx_OMODE	GPIO port output mode register
GPIOx_OSPD0	GPIO port output speed register 0
GPIOx_PUD	GPIO port pull-up/pull-down register
GPIOx_ISTAT	GPIO port input status register
GPIOx_OCTL	GPIO port output control register
GPIOx_BOP	GPIO port bit operation register
GPIOx_LOCK	GPIO port configuration lock register
AFIO_AFSEL0	GPIO alternate function selected register 0
AFIO_AFSEL1	GPIO alternate function selected register 1
AFIO_BC	GPIO bit clear register
AFIO_TG	GPIO port bit toggle register

3.10.2. Descriptions of Peripheral functions

GPIO firmware functions are listed in the table shown as below:

Table 3-162. GPIO firmware function

Function name	Function description
gpio_deinit	reset GPIO port
gpio_mode_set	set GPIO mode
gpio_output_options_set	set GPIO output type and speed
gpio_bit_set	set GPIO pin bit

Function name	Function description
gpio_bit_reset	reset GPIO pin bit
gpio_bit_write	write data to the specified GPIO pin
gpio_port_write	write data to the specified GPIO port
gpio_input_bit_get	get GPIO pin input status
gpio_input_port_get	get GPIO port input status
gpio_output_bit_get	get GPIO pin output status
gpio_output_port_get	get GPIO port output status
gpio_af_set	set GPIO alternate function
gpio_pin_lock	lock GPIO pin
gpio_bit_toggle	toggle GPIO pin status
gpio_port_toggle	toggle GPIO port status

gpio_deinit

The description of gpio_deinit is shown as below:

Table 3-163. Function gpio_deinit

Function name	gpio_deinit
Function prototype	void gpio_deinit(uint32_t gpio_periph);
Function descriptions	reset GPIO port
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C, F)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset GPIOA */
```

```
gpio_deinit (GPIOA);
```

gpio_mode_set

The description of gpio_mode_set is shown as below:

Table 3-164. Function gpio_mode_set

Function name	gpio_mode_set
Function prototype	void gpio_mode_set(uint32_t gpio_periph, uint32_t mode, uint32_t pull_up_down, uint32_t pin);
Function descriptions	set GPIO mode
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,F)
Input parameter{in}	
mode	gpio pin mode
<i>GPIO_MODE_INPUT</i>	input mode
<i>GPIO_MODE_OUTPUT</i>	output mode
<i>GPIO_MODE_AF</i>	alternate function mode
<i>GPIO_MODE_ANALOG</i>	analog mode
Input parameter{in}	
pull_up_down	gpio pin with pull-up or pull-down resistor
<i>GPIO_PUPD_NONE</i>	floating mode, no pull-up and pull-down resistors
<i>GPIO_PUPD_PULLUP</i>	with pull-up resistor
<i>GPIO_PUPD_PULLDOWN</i>	with pull-down resistor
Input parameter{in}	
pin	GPIO pin

<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* config PA0 as input mode with pullup*/
```

```
gpio_mode_set (GPIOA, GPIO_MODE_INPUT, GPIO_PUPD_PULLUP, GPIO_PIN_0);
```

gpio_output_options_set

The description of gpio_output_options_set is shown as below:

Table 3-165. Function gpio_output_options_set

Function name	gpio_output_options_set
Function prototype	void gpio_output_options_set(uint32_t gpio_periph, uint8_t otype, uint32_t speed, uint32_t pin);
Function descriptions	set GPIO output type and speed
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,F)
Input parameter{in}	
otype	gpio pin output mode
<i>GPIO_OTYPE_PP</i>	push pull mode
<i>GPIO_OTYPE_OD</i>	open drain mode
Input parameter{in}	
speed	gpio pin output max speed
<i>GPIO_OSPEED_2MHZ</i>	output max speed 2MHz

<i>GPIO_OSPEED_10MH</i> Z	output max speed 10MHz
<i>GPIO_OSPEED_50MH</i> Z	output max speed 50MHz
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* config PA0 as push pull mode */
```

```
gpio_output_options_set (GPIOA, GPIO_OTYPE_PP, GPIO_OSPEED_2MHZ, GPIO_PIN_0);
```

gpio_bit_set

The description of gpio_bit_set is shown as below:

Table 3-166. Function gpio_bit_set

Function name	gpio_bit_set
Function prototype	void gpio_bit_set(uint32_t gpio_periph,uint32_t pin);
Function descriptions	set GPIO pin bit
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C, F)
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)

<i>GPIO_PIN_ALL</i>	All pins
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set PA0*/
```

```
gpio_bit_set (GPIOA, GPIO_PIN_0);
```

gpio_bit_reset

The description of `gpio_bit_reset` is shown as below:

Table 3-167. Function `gpio_bit_reset`

Function name	<code>gpio_bit_reset</code>
Function prototype	<code>void gpio_bit_reset(uint32_t gpio_periph,uint32_t pin);</code>
Function descriptions	reset GPIO pin
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,F)
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset PA0*/
```

```
gpio_bit_set (GPIOA, GPIO_PIN_0);
```

gpio_bit_write

The description of gpio_bit_write is shown as below:

Table 3-168. Function gpio_bit_write

Function name	gpio_bit_write
Function prototype	void gpio_bit_write(uint32_t gpio_periph,uint32_t pin,bit_status bit_value);
Function descriptions	write data to the specified GPIO pin
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,F)
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Input parameter{in}	
bit_value	SET or RESET
<i>RESET</i>	clear the port pin
<i>SET</i>	set the port pin
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* write 1 to PA0 */
```

```
gpio_bit_write (GPIOA, GPIO_PIN_0, SET);
```


gpio_port_write

The description of gpio_port_write is shown as below:

Table 3-169. Function gpio_port_write

Function name	gpio_port_write
Function prototype	void gpio_port_write(uint32_t gpio_periph, uint16_t data);
Function descriptions	write data to the specified GPIO port
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,F)
Input parameter{in}	
data	specify the value to be written to the port output data register
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/*write 1010 0101 1010 0101 to Port A */
gpio_port_write (GPIOA, 0xA5A5);
```

gpio_input_bit_get

The description of gpio_input_bit_get is shown as below:

Table 3-170. Function gpio_input_bit_get

Function name	gpio_input_bit_get
Function prototype	FlagStatus gpio_input_bit_get(uint32_t gpio_periph, uint32_t pin);
Function descriptions	get GPIO pin input status
Precondition	-
The called functions	-

Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,F)
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Output parameter{out}	
-	-
Return value	
FlagStatus	SET / RESET

Example:

```
/* get status of PA0 */
```

```
FlagStatus bit_state = gpio_input_bit_get (GPIOA, GPIO_PIN_0);
```

gpio_input_port_get

The description of gpio_input_port_get is shown as below:

Table 3-171. Function gpio_input_port_get

Function name	gpio_input_port_get
Function prototype	uint16_t gpio_input_port_get(uint32_t gpio_periph);
Function descriptions	get GPIO all pins input status
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,F)
Output parameter{out}	
-	-
Return value	

uint16_t	0x0000-0xFFFF
-----------------	---------------

Example:

```
/* get input value of Port A */
uint16_t port_state;
port_state = gpio_input_bit_get (GPIOA);
```

gpio_output_bit_get

The description of `gpio_output_bit_get` is shown as below:

Table 3-172. Function `gpio_output_bit_get`

Function name	gpio_output_bit_get
Function prototype	FlagStatus gpio_output_bit_get(uint32_t gpio_periph,uint32_t pin);
Function descriptions	get GPIO pin output status
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,F)
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Output parameter{out}	
-	-
Return value	
FlagStatus	SET / RESET

Example:

```
/* get output status of PA0 */
FlagStatus bit_state;
bit_state = gpio_output_bit_get (GPIOA, GPIO_PIN_0);
```

gpio_output_port_get

The description of gpio_output_port_get is shown as below:

Table 3-173. Function gpio_output_port_get

Function name	gpio_output_port_get
Function prototype	uint16_t gpio_output_port_get(uint32_t gpio_periph);
Function descriptions	get GPIO all pins output status
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,F)
Output parameter{out}	
-	-
Return value	
Uin16_t	0x0000-0xFFFF

Example:

```

/* get output value of Port A */
uint16_t port_state;
port_state = gpio_output_port_get (GPIOA);

```

gpio_af_set

The description of gpio_af_set is shown as below:

Table 3-174. Function gpio_af_set

Function name	gpio_af_set
Function prototype	void gpio_af_set(uint32_t gpio_periph, uint32_t alt_func_num, uint32_t pin);
Function descriptions	set GPIO alternate function
Precondition	-
The called functions	-
Input parameter{in}	

gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C)
Input parameter{in}	
alt_func_num	GPIO pin af function, please refer to specific device datasheet
<i>GPIO_AF_0</i>	<i>TIMER13, TIMER14, TIMER16, SPI0, SPI1, I2S0, CK_OUT, USART0, I2C0, I2C1, SWDIO, SWCLK</i>
<i>GPIO_AF_1</i>	<i>USART0, USART1, TIMER14, I2C0, I2C1</i>
<i>GPIO_AF_2</i>	<i>TIMER0, TIMER1, TIMER15, TIMER16, I2S0</i>
<i>GPIO_AF_3</i>	<i>I2C0, TIMER14</i>
<i>GPIO_AF_4 (port A,B only)</i>	<i>USART1, I2C0, I2C1, TIMER13</i>
<i>GPIO_AF_5 (port A,B only)</i>	<i>TIMER15, TIMER16, I2S0</i>
<i>GPIO_AF_6 (port A,B only)</i>	<i>SPI1</i>
<i>GPIO_AF_7 (port A,B only)</i>	<i>CMP</i>
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/*set PA0 alternate function 0*/
```

```
gpio_af_set(GPIOA, GPIO_AF_0, GPIO_PIN_0);
```

gpio_pin_lock

The description of `gpio_pin_lock` is shown as below:

Table 3-175. Function gpio_pin_lock

Function name	gpio_pin_lock
Function prototype	void gpio_pin_lock(uint32_t gpio_periph, uint32_t pin);
Function descriptions	lock GPIO pin bit
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B)
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
<i>GPIO_PIN_ALL</i>	All pins
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* lock PA0*/
```

```
gpio_pin_lock (GPIOA, GPIO_PIN_ 0);
```

gpio_bit_toggle

The description of gpio_bit_toggle is shown as below:

Table 3-176. Function gpio_bit_toggle

Function name	gpio_bit_toggle
Function prototype	void gpio_bit_toggle(uint32_t gpio_periph, uint32_t pin);
Function descriptions	toggle GPIO pin status
Precondition	-
The called functions	-

Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,F)
Input parameter{in}	
pin	GPIO pin
<i>GPIO_PIN_x</i>	GPIO_PIN_x(x=0..15)
GPIO_PIN_ALL	GPIO_PIN_ALL
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* toggle PA0 */
gpio_bit_toggle (GPIOA, GPIO_PIN_0);
```

gpio_port_toggle

The description of gpio_port_toggle is shown as below:

Table 3-177. Function gpio_port_toggle

Function name	gpio_port_toggle
Function prototype	void gpio_port_toggle(uint32_t gpio_periph);
Function descriptions	toggle GPIO port status
Precondition	-
The called functions	-
Input parameter{in}	
gpio_periph	GPIO port
<i>GPIOx</i>	GPIOx(x = A,B,C,F)
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* toggle GPIOA*/
gpio_port_toggle (GPIOA);
```

3.11. I2C

The I2C (inter-integrated circuit) module provides an I2C interface which is an industry standard two-line serial interface for MCU to communicate with external I2C interface. The I2C registers are listed in chapter [3.11.1](#), the I2C firmware functions are introduced in chapter [3.11.2](#).

3.11.1. Descriptions of Peripheral registers

I2C registers are listed in the table shown as below:

Table 3-178. I2C Registers

Registers	Descriptions
I2C_CTL0	Control register 0
I2C_CTL1	Control register 1
I2C_SADDR0	Slave address register 0
I2C_SADDR1	Slave address register 1
I2C_DATA	Transfer buffer register
I2C_STAT0	Transfer status register 0
I2C_STAT1	Transfer status register 1
I2C_CKCFG	Clock configure register
I2C_RT	Rise time register
I2C_SAMCS	SAM control and status register
I2C_FMPCFG	Fast mode plus configure register

3.11.2. Descriptions of Peripheral functions

I2C firmware functions are listed in the table shown as below:

Table 3-179. I2C firmware function

Function name	Function description
i2c_deinit	reset I2C
i2c_clock_config	configure I2C clock
i2c_mode_addr_config	configure I2C address
i2c_smbus_type_config	SMBus type selection
i2c_ack_config	whether or not to send an ACK
i2c_ackpos_config	configure I2C ACK position
i2c_master_addressing	master send slave address
i2c_dualaddr_enable	enable dual-address mode
i2c_dualaddr_disable	disable dual-address mode
i2c_enable	enable I2C
i2c_disable	disable I2C
i2c_start_on_bus	generate a START condition on I2C bus
i2c_stop_on_bus	generate a STOP condition on I2C bus
i2c_data_transmit	I2C transmit data function
i2c_data_receive	I2C receive data function
i2c_dma_enable	I2C DMA mode enable
i2c_dma_last_transfer_config	configure whether next DMA EOT is DMA last transfer or not
i2c_stretch_scl_low_config	whether to stretch SCL low when data is not ready in slave mode
i2c_slave_response_to_gcall_config	whether or not to response to a general call
i2c_software_reset_config	software reset I2C
i2c_pec_enable	whether I2C PEC calculation is enabled
i2c_pec_transfer_enable	I2C whether to transfer PEC value
i2c_pec_value_get	packet error checking value
i2c_smbus_issue_alert	I2C issue alert through SMBA pin
i2c_smbus_arp_enable	whether ARP is enabled under SMBus
i2c_sam_enable	enable SAM_V interface

Function name	Function description
i2c_sam_disable	disable SAM_V interface
i2c_sam_timeout_enable	enable SAM_V interface timeout detect
i2c_sam_timeout_disable	disable SAM_V interface timeout detect
i2c_flag_get	check I2C flag is set or not
i2c_flag_clear	clear I2C flag
i2c_interrupt_enable	enable I2C interrupt
i2c_interrupt_disable	disable I2C interrupt
i2c_interrupt_flag_get	check I2C interrupt flag
i2c_interrupt_flag_clear	clear I2C interrupt flag

i2c_deinit

The description of i2c_deinit is shown as below:

Table 3-180. Function i2c_deinit

Function name	i2c_deinit
Function prototype	void i2c_deinit(uint32_t i2c_periph);
Function descriptions	reset I2C
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset I2C0 */
```

```
i2c_deinit (I2C0);
```

i2c_clock_config

The description of i2c_clock_config is shown as below:

Table 3-181. Function i2c_clock_config

Function name	i2c_clock_config
Function prototype	void i2c_clock_config(uint32_t i2c_periph, uint32_t clkspeed, uint32_t dutycyc);
Function descriptions	I2C clock configure
Precondition	-
The called functions	rcu_clock_freq_get
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
clkspeed	i2c clock speed
Input parameter{in}	
dutycyc	duty cycle in fast mode
<i>I2C_DTCY_2</i>	T_low/T_high=2
<i>I2C_DTCY_16_9</i>	T_low/T_high=16/9
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure I2C0 clock speed as 100KHz*/
i2c_clock_config(I2C0, 100000, I2C_DTCY_2);
```

i2c_mode_addr_config

The description of i2c_mode_addr_config is shown as below:

Table 3-182. Function i2c_mode_addr_config

Function name	i2c_mode_addr_config
----------------------	----------------------

Function prototype	void i2c_mode_addr_config(uint32_t i2c_periph, uint32_t mode, uint32_t addformat, uint32_t addr);
Function descriptions	configure I2C address
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
mode	I2C mode select
<i>I2C_I2CMODE_ENABLE</i>	I2C mode
<i>I2C_SMBUSMODE_ENABLE</i>	SMBus mode
Input parameter{in}	
addformat	7bits or 10bits
<i>I2C_ADDFORMAT_7BITS</i>	7bits
<i>I2C_ADDFORMAT_10BITS</i>	10bits
Input parameter{in}	
addr	I2C address
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure I2C0 address as 0x82, using 7 bits */
```

```
i2c_mode_addr_config(I2C0, I2C_I2CMODE_ENABLE, I2C_ADDFORMAT_7BITS, 0x82);
```

i2c_smbus_type_config

The description of i2c_smbus_type_config is shown as below:

Table 3-183. Function i2c_smbus_type_config

Function name	i2c_smbus_type_config
Function prototype	void i2c_smbus_type_config(uint32_t i2c_periph, uint32_t type);
Function descriptions	SMBus type selection
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
type	Device or host
<i>I2C_SMBUS_DEVICE</i>	device
<i>I2C_SMBUS_HOST</i>	host
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* config I2C0 as SMBUS host type*/
i2c_smbus_type_config (I2C0, I2C_SMBUS_HOST);
```

i2c_ack_config

The description of i2c_ack_config is shown as below:

Table 3-184. Function i2c_ack_config

Function name	i2c_ack_config
Function prototype	void i2c_ack_config(uint32_t i2c_periph, uint32_t ack);
Function descriptions	whether or not to send an ACK

Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
ack	whether or not to send an ACK
<i>I2C_ACK_ENABLE</i>	ACK will be sent
<i>I2C_ACK_DISABLE</i>	ACK will not be sent
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* I2C0 will send ACK */
```

```
i2c_ack_config (I2C0, I2C_ACK_ENABLE);
```

i2c_ackpos_config

The description of `i2c_ackpos_config` is shown as below:

Table 3-185. Function `i2c_ackpos_config`

Function name	<code>i2c_ackpos_config</code>
Function prototype	<code>void i2c_ackpos_config(uint32_t i2c_periph, uint32_t pos);</code>
Function descriptions	I2C POAP position configure
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	

pos	ACK position
<i>I2C_ACKPOS_CURRENT</i>	whether to send ACK or not for the current
<i>I2C_ACKPOS_NEXT</i>	whether to send ACK or not for the next byte
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* The ACK of I2C0 is send for the current frame*/
```

```
i2c_ackpos_config (I2C0, I2C_ACKPOS_CURRENT);
```

i2c_master_addressing

The description of i2c_master_addressing is shown as below:

Table 3-186. Function i2c_master_addressing

Function name	i2c_master_addressing
Function prototype	void i2c_master_addressing(uint32_t i2c_periph, uint32_t addr, uint32_t trandirection);
Function descriptions	master sends slave address
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
addr	slave address
Input parameter{in}	
trandirection	transmitter or receiver
<i>I2C_TRANSMITTER</i>	transmitter
<i>I2C_RECEIVER</i>	receiver

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* send slave address to I2C bus and I2C0 act as receiver */
```

```
i2c_master_addressing(I2C0, 0x82, I2C_RECEIVER);
```

i2c_dualaddr_enable

The description of i2c_dualaddr_enable is shown as below:

Table 3-187. Function i2c_dualaddr_enable

Function name	i2c_dualaddr_enable
Function prototype	void i2c_dualaddr_enable(uint32_t i2c_periph, uint32_t addr)
Function descriptions	dual-address mode enable
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
addr	second address in dual-address mode
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable I2C0 dual-address*/
```

```
i2c_dualaddr_enable (I2C0, 0x80);
```


i2c_dualaddr_disable

The description of i2c_dualaddr_disable is shown as below:

Table 3-188. Function i2c_dualaddr_enable

Function name	i2c_dualaddr_disable
Function prototype	void i2c_dualaddr_disable(uint32_t i2c_periph)
Function descriptions	dual-address mode disable
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable I2C0 dual-address*/
i2c_dualaddr_disable (I2C0);
```

i2c_enable

The description of i2c_enable is shown as below:

Table 3-189. Function i2c_enable

Function name	i2c_enable
Function prototype	void i2c_enable(uint32_t i2c_periph);
Function descriptions	enable I2C
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral

<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable I2C0 */
```

```
i2c_enable (I2C0);
```

i2c_disable

The description of i2c_disable is shown as below:

Table 3-190. Function i2c_disable

Function name	i2c_disable
Function prototype	void i2c_disable(uint32_t i2c_periph);
Function descriptions	disable I2C
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable I2C0 */
```

```
i2c_disable (I2C0);
```

i2c_start_on_bus

The description of i2c_start_on_bus is shown as below:

Table 3-191. Function i2c_start_on_bus

Function name	i2c_start_on_bus
Function prototype	void i2c_start_on_bus(uint32_t i2c_periph);
Function descriptions	generate a START condition on I2C bus
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* I2C0 send a start condition to I2C bus */
```

```
i2c_start_on_bus (I2C0);
```

i2c_stop_on_bus

The description of i2c_stop_on_bus is shown as below:

Table 3-192. Function i2c_stop_on_bus

Function name	i2c_stop_on_bus
Function prototype	void i2c_stop_on_bus(uint32_t i2c_periph);
Function descriptions	generate a STOP condition on I2C bus
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* I2C0 generate a STOP condition to I2C bus */
```

```
i2c_stop_on_bus (I2C0);
```

i2c_data_transmit

The description of i2c_data_transmit is shown as below:

Table 3-193. Function i2c_data_transmit

Function name	i2c_data_transmit
Function prototype	void i2c_data_transmit(uint32_t i2c_periph, uint8_t data);
Function descriptions	I2C transmit data function
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
data	transmit data
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* I2C0 transmit data */
```

```
i2c_data_transmit (I2C0, 0x80);
```

i2c_data_receive

The description of i2c_data_receive is shown as below:

Table 3-194. Function i2c_data_receive

Function name	i2c_data_receive
Function prototype	uint8_t i2c_data_receive(uint32_t i2c_periph);
Function descriptions	I2C receive data function
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
uint8_t	0x00..0xFF

Example:

```

/* I2C0 receive data */
uint8_t i2c_receiver;

i2c_receiver = i2c_data_receive(I2C0);
  
```

i2c_dma_enable

The description of i2c_dma_enable is shown as below:

Table 3-195. Function i2c_dma_enable

Function name	i2c_dma_enable
Function prototype	void i2c_dma_enable(uint32_t i2c_periph, uint32_t dmastate);
Function descriptions	enable I2C DMA mode
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)

Input parameter{in}	
dmastate	on or off
<i>I2C_DMA_ON</i>	DMA mode enable
<i>I2C_DMA_OFF</i>	DMA mode disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* I2C0 DMA mode enable */
```

```
i2c_dma_enable(I2C0, I2C_DMA_ON);
```

i2c_dma_last_transfer_config

The description of `i2c_dma_last_transfer_config` is shown as below:

Table 3-196. Function `i2c_dma_last_transfer_config`

Function name	<code>i2c_dma_last_transfer_config</code>
Function prototype	<code>void i2c_dma_last_transfer_config(uint32_t i2c_periph, uint32_t dmalast);</code>
Function descriptions	flag indicating DMA last transfer
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
dmalast	next DMA EOT is the last transfer or not
<i>I2C_DMALST_ON</i>	next DMA EOT is the last transfer
<i>I2C_DMALST_OFF</i>	next DMA EOT is not the last transfer
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* next DMA EOT is the last transfer */
```

```
i2c_dma_last_transfer_config (I2C0, I2C_DMALST_ON);
```

i2c_stretch_scl_low_config

The description of `i2c_stretch_scl_low_config` is shown as below:

Table 3-197. Function `i2c_stretch_scl_low_config`

Function name	<code>i2c_stretch_scl_low_config</code>
Function prototype	<code>void i2c_stretch_scl_low_config(uint32_t i2c_periph, uint32_t stretchpara);</code>
Function descriptions	whether to stretch SCL low when data is not ready in slave mode
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
stretchpara	SCL stretching enable or disable
<i>I2C_SCLSTRETCH_ENABLE</i>	SCL stretching is enabled
<i>I2C_SCLSTRETCH_DISABLE</i>	SCL stretching is disabled
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* stretch SCL low when data is not ready in slave mode */
```

```
i2c_stretch_scl_low_config (I2C0, I2C_SCLSTRETCH_ENABLE);
```

i2c_slave_response_to_gcall_config

The description of i2c_slave_response_to_gcall_config is shown as below:

Table 3-198. Function i2c_slave_response_to_gcall_config

Function name	i2c_slave_response_to_gcall_config
Function prototype	void i2c_slave_response_to_gcall_config(uint32_t i2c_periph, uint32_t gcallpara);
Function descriptions	whether or not to response to a general call
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
gcallpara	response to a general call or not
<i>I2C_GCEN_ENABLE</i>	slave will response to a general call
<i>I2C_GCEN_DISABLE</i>	slave will not response to a general call
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* I2C0 will response to a general call */
```

```
i2c_slave_response_to_gcall_config (I2C0, I2C_GCEN_ENABLE);
```

i2c_software_reset_config

The description of i2c_software_reset_config is shown as below:

Table 3-199. Function i2c_software_reset_config

Function name	i2c_software_reset_config
Function prototype	void i2c_software_reset_config(uint32_t i2c_periph, uint32_t sreset);
Function descriptions	software reset I2C

Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
sreset	reset or not
<i>I2C_SRESET_SET</i>	I2C is under reset
<i>I2C_SRESET_RESET</i>	I2C is not under reset
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* software reset I2C0 */
```

```
i2c_software_reset_config (I2C0, I2C_SRESET_SET);
```

i2c_pec_enable

The description of `i2c_pec_enable` is shown as below:

Table 3-200. Function `i2c_pec_enable`

Function name	<code>i2c_pec_enable</code>
Function prototype	<code>void i2c_pec_enable(uint32_t i2c_periph, uint32_t pecstate);</code>
Function descriptions	I2C PEC calculation on or off
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	

pecstate	on or off
<i>I2C_PEC_ENABLE</i>	PEC calculation on
<i>I2C_PEC_DISABLE</i>	PEC calculation off
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* Enable I2C PEC calculation */
```

```
i2c_pec_enable (I2C0, I2C_PEC_ENABLE);
```

i2c_pec_transfer_enable

The description of `i2c_pec_transfer_enable` is shown as below:

Table 3-201. Function `i2c_pec_transfer_enable`

Function name	<code>i2c_pec_transfer_enable</code>
Function prototype	<code>void i2c_pec_transfer_enable(uint32_t i2c_periph, uint32_t pecpara);</code>
Function descriptions	I2C whether to transfer PEC value
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
pecpara	Transfer PEC or not
<i>I2C_PECTRANS_ENABLE</i>	transfer PEC
<i>I2C_PECTRANS_DISABLE</i>	not transfer PEC
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* I2C0 transfer PEC */
```

```
i2c_pec_transfer_enable (I2C0, I2C_PECTRANS_ENABLE);
```

i2c_pec_value_get

The description of `i2c_pec_value_get` is shown as below:

Table 3-202. Function `i2c_pec_value_get`

Function name	<code>i2c_pec_value_get</code>
Function prototype	<code>uint8_t i2c_pec_value_get(uint32_t i2c_periph);</code>
Function descriptions	get packet error checking value
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
uint8_t	PEC value

Example:

```
/* I2C0 get packet error checking value */
```

```
uint8_t pec_value;
```

```
pec_value = i2c_pec_value_get (I2C0);
```

i2c_smbus_issue_alert

The description of `i2c_smbus_issue_alert` is shown as below:

Table 3-203. Function `i2c_smbus_issue_alert`

Function name	<code>i2c_smbus_issue_alert</code>
----------------------	------------------------------------

Function prototype	void i2c_smbus_issue_alert(uint32_t i2c_periph, uint32_t smbuspara);
Function descriptions	I2C issue alert through SMBA pin
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
smbuspara	issue alert through SMBA pin or not
<i>I2C_SALTSEND_ENABLE</i>	issue alert through SMBA pin
<i>I2C_SALTSEND_DISABLE</i>	not issue alert through SMBA pin
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* I2C0 issue alert through SMBA pin enable*/
```

```
i2c_smbus_issue_alert (I2C0, I2C_SALTSEND_ENABLE);
```

i2c_smbus_arp_enable

The description of i2c_smbus_arp_enable is shown as below:

Table 3-204. Function i2c_smbus_arp_enable

Function name	i2c_smbus_arp_enable
Function prototype	void i2c_smbus_arp_enable(uint32_t i2c_periph, uint32_t arpstate);
Function descriptions	enable or disable I2C ARP protocol in SMBus switch
Precondition	-
The called functions	-
Input parameter{in}	

i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
arpstate	ARP protocol in SMBus switch
<i>I2C_ARP_ENABLE</i>	enable ARP
<i>I2C_ARP_DISABLE</i>	disable ARP
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable I2C0 ARP protocol in SMBus switch */
```

```
i2c_smbus_arp_enable (I2C0, I2C_ARP_ENABLE);
```

i2c_sam_enable

The description of `i2c_sam_enable` is shown as below:

Table 3-205. Function `i2c_sam_enable`

Function name	<code>i2c_sam_enable</code>
Function prototype	<code>void i2c_sam_enable (uint32_t i2c_periph);</code>
Function descriptions	enable SAM_V interface
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable I2C0 SAM_V interface */
```

```
i2c_sam_enable (I2C0);
```

i2c_sam_disable

The description of i2c_sam_disable is shown as below:

Table 3-206. Function i2c_sam_disable

Function name	i2c_sam_disable
Function prototype	void i2c_sam_disable (uint32_t i2c_periph);
Function descriptions	disable SAM_V interface
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable I2C0 SAM_V interface*/
```

```
i2c_sam_disable (I2C0);
```

i2c_sam_timeout_enable

The description of i2c_sam_timeout_enable is shown as below:

Table 3-207. Function i2c_sam_timeout_enable

Function name	i2c_sam_timeout_enable
Function prototype	void i2c_sam_timeout_enable (uint32_t i2c_periph);
Function descriptions	enable SAM_V interface timeout detect
Precondition	-

The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable I2C0 SAM_V interface timeout detect */
```

```
i2c_sam_timeout_enable (I2C0);
```

i2c_sam_timeout_disable

The description of i2c_sam_timeout_disable is shown as below:

Table 3-208. Function i2c_sam_timeout_disable

Function name	i2c_sam_timeout_disable
Function prototype	void i2c_sam_timeout_disable (uint32_t i2c_periph);
Function descriptions	disable SAM_V interface timeout detect
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable I2C0 SAM_V interface timeout detect */
```

i2c_sam_timeout_disable (I2C0);

i2c_flag_get

The description of i2c_flag_get is shown as below:

Table 3-209. Function i2c_flag_get

Function name	i2c_flag_get
Function prototype	FlagStatus i2c_flag_get(uint32_t i2c_periph, i2c_flag_enum flag)
Function descriptions	check I2C flag is set or not
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
flag	specify get which flag
<i>I2C_FLAG_SBSEND</i>	start condition send out
<i>I2C_FLAG_ADDSEND</i>	address is sent in master mode or received and matches in slave mode
<i>I2C_FLAG_BTC</i>	byte transmission finishes
<i>I2C_FLAG_ADD10SEND</i>	header of 10-bit address is sent in master mode
<i>I2C_FLAG_STPDET</i>	stop condition detected in slave mode
<i>I2C_FLAG_RBNE</i>	I2C_DATA is not Empty during receiving
<i>I2C_FLAG_TBE</i>	I2C_DATA is empty during transmitting
<i>I2C_FLAG_BERR</i>	a bus error occurs indication a unexpected start or stop condition on I2C bus
<i>I2C_FLAG_LOSTARB</i>	arbitration lost in master mode
<i>I2C_FLAG_AERR</i>	acknowledge error
<i>I2C_FLAG_OUERR</i>	overflow or underflow situation occurs in slave mode
<i>I2C_FLAG_PECERR</i>	PEC error when receiving data
<i>I2C_FLAG_SMBTO</i>	timeout signal in SMBus mode

<i>I2C_FLAG_SMBALT</i>	SMBus alert status
<i>I2C_FLAG_MASTER</i>	a flag indicating whether I2C block is in master or slave mode
<i>I2C_FLAG_I2CBSY</i>	busy flag
<i>I2C_FLAG_TR</i>	whether the I2C is a transmitter or a receiver
<i>I2C_FLAG_RXGC</i>	general call address (00h) received
<i>I2C_FLAG_DEFSMB</i>	default address of SMBus device
<i>I2C_FLAG_HSTSMB</i>	SMBus host header detected in slave mode
<i>I2C_FLAG_DUMOD</i>	dual flag in slave mode indicating which address is matched in dual-address mode
<i>I2C_FLAG_TFF</i>	txframe fall flag
<i>I2C_FLAG_TFR</i>	txframe rise flag
<i>I2C_FLAG_RFF</i>	rxframe fall flag
<i>I2C_FLAG_RFR</i>	rxframe rise flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET / RESET

Example:

```
/* check whether start condition send out */
```

```
FlagStatus flag_state = RESET;
```

```
flag_state = i2c_flag_get (I2C0, I2C_FLAG_SBSEND);
```

i2c_flag_clear

The description of i2c_flag_clear is shown as below:

Table 3-210. Function i2c_flag_clear

Function name	i2c_flag_clear
Function prototype	void i2c_flag_clear(uint32_t i2c_periph, i2c_flag_enum flag)
Function descriptions	clear I2C flag
Precondition	-

The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
flag	flag type
<i>I2C_FLAG_SMBALT</i>	SMBus Alert status
<i>I2C_FLAG_SMBTO</i>	timeout signal in SMBus mode
<i>I2C_FLAG_PECERR</i>	PEC error when receiving data
<i>I2C_FLAG_OUERR</i>	over-run or under-run situation occurs in slave mode
<i>I2C_FLAG_AERR</i>	acknowledge error
<i>I2C_FLAG_LOSTARB</i>	arbitration lost in master mode
<i>I2C_FLAG_BERR</i>	a bus error
<i>I2C_FLAG_ADDSEND</i>	cleared by reading I2C_STAT0 and reading I2C_STAT1
<i>I2C_FLAG_TFF</i>	txframe fall flag
<i>I2C_FLAG_TFR</i>	txframe rise flag
<i>I2C_FLAG_RFF</i>	rxframe fall flag
<i>I2C_FLAG_RFR</i>	rxframe rise flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear a bus error flag*/
```

```
i2c_flag_clear (I2C0, I2C_FLAG_BERR);
```

i2c_interrupt_enable

The description of i2c_interrupt_enable is shown as below:

Table 3-211. Function `i2c_interrupt_enable`

Function name	<code>i2c_interrupt_enable</code>
Function prototype	<code>void i2c_interrupt_enable(uint32_t i2c_periph, i2c_interrupt_enum interrupt);</code>
Function descriptions	enable I2C interrupt
Precondition	-
The called functions	-
Input parameter{in}	
<code>i2c_periph</code>	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
<code>inttype</code>	interrupt type
<i>I2C_INT_ERR</i>	error interrupt enable
<i>I2C_INT_EV</i>	event interrupt enable
<i>I2C_INT_BUF</i>	<i>buffer interrupt enable</i>
<i>I2C_INT_TFF</i>	<i>txframe fall interrupt enable</i>
<i>I2C_INT_TFR</i>	<i>txframe rise interrupt enable</i>
<i>I2C_INT_RFF</i>	<i>rxframe fall interrupt enable</i>
<i>I2C_INT_RFR</i>	<i>rxframe rise interrupt enable</i>
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable I2C0 event interrupt */
i2c_interrupt_enable (I2C0, I2C_INT_EV);
```

`i2c_interrupt_disable`

The description of `i2c_interrupt_disable` is shown as below:

Table 3-212. Function `i2c_interrupt_disable`

Function name	<code>i2c_interrupt_disable</code>
Function prototype	<code>void i2c_interrupt_disable(uint32_t i2c_periph, i2c_interrupt_enum interrupt);</code>
Function descriptions	disable I2C interrupt
Precondition	-
The called functions	-
Input parameter{in}	
<code>i2c_periph</code>	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
<code>inttype</code>	interrupt type
<i>I2C_INT_ERR</i>	error interrupt disable
<i>I2C_INT_EV</i>	event interrupt disable
<i>I2C_INT_BUF</i>	buffer interrupt disable
<i>I2C_INT_TFF</i>	<i>txframe fall interrupt enable</i>
<i>I2C_INT_TFR</i>	<i>txframe rise interrupt enable</i>
<i>I2C_INT_RFF</i>	<i>rxframe fall interrupt enable</i>
<i>I2C_INT_RFR</i>	<i>rxframe rise interrupt enable</i>
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable I2C0 event interrupt */
i2c_interrupt_disable (I2C0, I2C_INT_EV);
```

`i2c_interrupt_flag_get`

The description of `i2c_interrupt_flag_get` is shown as below:

Table 3-213. Function `i2c_interrupt_flag_get`

Function name	<code>i2c_interrupt_flag_get</code>
Function prototype	<code>FlagStatus i2c_interrupt_flag_get(uint32_t i2c_periph, i2c_interrupt_flag_enum int_flag)</code>
Function descriptions	check I2C interrupt flag
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	
int_flag	interrupt flag
<i>I2C_INT_FLAG_SBSE ND</i>	start condition sent out in master mode interrupt flag
<i>I2C_INT_FLAG_ADDS END</i>	address is sent in master mode or received and matches in slave mode interrupt flag
<i>I2C_INT_FLAG_BTC</i>	byte transmission finishes
<i>I2C_INT_FLAG_ADD10 SEND</i>	header of 10-bit address is sent in master mode interrupt flag
<i>I2C_INT_FLAG_STPD ET</i>	stop condition detected in slave mode interrupt flag
<i>I2C_INT_FLAG_RBNE</i>	I2C_DATA is not Empty during receiving interrupt flag
<i>I2C_INT_FLAG_TBE</i>	I2C_DATA is empty during transmitting interrupt flag
<i>I2C_INT_FLAG_BERR</i>	a bus error occurs indication a unexpected start or stop condition on I2C bus interrupt flag
<i>I2C_INT_FLAG_LOSTA RB</i>	arbitration lost in master mode interrupt flag
<i>I2C_INT_FLAG_AERR</i>	acknowledge error interrupt flag
<i>I2C_INT_FLAG_OUER R</i>	over-run or under-run situation occurs in slave mode interrupt flag
<i>I2C_INT_FLAG_PECE RR</i>	PEC error when receiving data interrupt flag

<i>I2C_INT_FLAG_SMBT</i> O	timeout signal in SMBus mode interrupt flag
<i>I2C_INT_FLAG_SMBA</i> LT	SMBus Alert status interrupt flag
<i>I2C_INT_FLAG_TFF</i>	txframe fall interrupt flag
<i>I2C_INT_FLAG_TFR</i>	txframe rise interrupt flag
<i>I2C_INT_FLAG_RFF</i>	rxframe fall interrupt flag
<i>I2C_INT_FLAG_RFR</i>	rxframe rise interrupt flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET / RESET

Example:

```
/* check the byte transmission finishes interrupt flag is set or not*/
```

```
FlagStatus flag_state = RESET;
```

```
flag_state = i2c_interrupt_flag_get (I2C0, I2C_INT_FLAG_BTC);
```

i2c_interrupt_flag_clear

The description of `i2c_interrupt_flag_clear` is shown as below:

Table 3-214. Function `i2c_interrupt_flag_clear`

Function name	<code>i2c_interrupt_flag_clear</code>
Function prototype	<code>void i2c_interrupt_flag_clear(uint32_t i2c_periph, i2c_interrupt_flag_enum int_flag);</code>
Function descriptions	clear I2C interrupt flag
Precondition	-
The called functions	-
Input parameter{in}	
i2c_periph	I2C peripheral
<i>I2Cx</i>	(x=0,1)
Input parameter{in}	

intflag	interrupt flag
<i>I2C_INT_FLAG_ADDS END</i>	address is sent in master mode or received and matches in slave mode interrupt flag
<i>I2C_INT_FLAG_BERR</i>	a bus error occurs indication a unexpected start or stop condition on I2C bus interrupt flag
<i>I2C_INT_FLAG_LOSTA RB</i>	arbitration lost in master mode interrupt flag
<i>I2C_INT_FLAG_AERR</i>	acknowledge error interrupt flag
<i>I2C_INT_FLAG_OUER R</i>	over-run or under-run situation occurs in slave mode interrupt flag
<i>I2C_INT_FLAG_PECE RR</i>	PEC error when receiving data interrupt flag
<i>I2C_INT_FLAG_SMBT O</i>	timeout signal in SMBus mode interrupt flag
<i>I2C_INT_FLAG_SMBA LT</i>	SMBus Alert status interrupt flag
<i>I2C_INT_FLAG_TFF</i>	txframe fall interrupt flag
<i>I2C_INT_FLAG_TFR</i>	txframe rise interrupt flag
<i>I2C_INT_FLAG_RFF</i>	rxframe fall interrupt flag
<i>I2C_INT_FLAG_RFR</i>	rxframe rise interrupt flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear the acknowledge error interrupt flag */
i2c_interrupt_flag_clear (I2C0, I2C_INT_FLAG_AERR);
```

3.12. MISC

MISC is a software package that provide the interfaces for NVIC and SysTick. The NVIC and SysTick registers are listed in chapter [3.12.1](#), the MISC firmware functions are introduced in chapter [3.12.2](#).

3.12.1. Descriptions of Peripheral registers

Table 3-215. NVIC Registers

Registers	Descriptions
ISER ⁽¹⁾	Interrupt Set Enable Register
ICER ⁽¹⁾	Interrupt Clear Enable Register
ISPR ⁽¹⁾	Interrupt Set Pending Register
ICPR ⁽¹⁾	Interrupt Clear Pending Register
IABR ⁽¹⁾	Interrupt Active bit Register
ITNS ⁽¹⁾	Interrupt Non-Secure State Register
IPR ⁽¹⁾	Interrupt Priority Register
CPUID ⁽²⁾	CPUID Base Register
ICSR ⁽²⁾	Interrupt Control and State Register
VTOR ⁽²⁾	Vector Table Offset Register
AIRCR ⁽²⁾	Application Interrupt and Reset Control Register
SCR ⁽²⁾	System Control Register
CCR ⁽²⁾	Configuration Control Register
SHPR ⁽²⁾	System Handlers Priority Registers
SHCSR ⁽²⁾	System Handler Control and State Register

1. refer to the structure NVIC_Type, is defined in the core_cm3.h file

2. refer to the structure SCB_Type, is defined in the core_cm3.h file

Table 3-216. SysTick Registers

Registers	Descriptions
CTRL ⁽¹⁾	SysTick Control and Status Register
LOAD ⁽¹⁾	SysTick Reload Value Register
VAL ⁽¹⁾	SysTick Current Value Register
CALIB ⁽¹⁾	SysTick Calibration Register

1. refer to the structure SysTick_Type, is defined in the core_cm3.h file

3.12.2. Descriptions of Peripheral functions

Enum IRQn_Type

Table 3-217. IRQn_Type

Member name	Function description
WWDGT_IRQn	window watchDog timer interrupt
LVD_IRQn	LVD through EXTI line detect interrupt
TAMPER_IRQn	tamper through EXTI line detect
RTC_IRQn	RTC through EXTI line interrupt
FMC_IRQn	FMC interrupt
RCU_CTC_IRQn	RCU and CTC interrupt
EXTI0_IRQn	EXTI line 0 interrupts
EXTI1_IRQn	EXTI line 1 interrupts
EXTI2_IRQn	EXTI line 2 interrupts
EXTI3_IRQn	EXTI line 3 interrupts
EXTI4_IRQn	EXTI line 4 interrupts
DMA0_Channel0_IRQn	DMA0 channel0 interrupt
DMA0_Channel1_IRQn	DMA0 channel1 interrupt
DMA0_Channel2_IRQn	DMA0 channel2 interrupt
DMA0_Channel3_IRQn	DMA0 channel3 interrupt
DMA0_Channel4_IRQn	DMA0 channel4 interrupt
DMA0_Channel5_IRQn	DMA0 channel5 interrupt
DMA0_Channel6_IRQn	DMA0 channel6 interrupt
ADC0_1_IRQn	ADC0 and ADC1 interrupt
CAN0_TX_IRQn	CAN0 transmit interrupts
CAN0_RX0_IRQn	CAN0 receive0 interrupts
CAN0_RX1_IRQn	CAN0 receive1 interrupts
CAN0_EWMC_IRQn	CAN0 EWMC interrupts
EXTI5_9_IRQn	EXTI[9:5] interrupts
TIMER0_BRK_TIMER8_IRQn	TIMER0 break and TIMER8 interrupts
TIMER0_UP_TIMER9_IRQn	TIMER0 update and TIMER9 interrupts
TIMER0_TRG_CMT_TIMER10_IRQn	TIMER0 trigger and commutation and TIMER10 interrupts
TIMER0_Channel_IRQn	TIMER0 channel capture compare interrupt
TIMER1_IRQn	TIMER1 interrupt
TIMER2_IRQn	TIMER2 interrupt
TIMER3_IRQn	TIMER3 interrupt
I2C0_EV_IRQn	I2C0 event interrupt
I2C0_ER_IRQn	I2C0 error interrupt
I2C1_EV_IRQn	I2C1 event interrupt
I2C1_ER_IRQn	I2C1 error interrupt
SPI0_IRQn	SPI0 interrupt

Member name	Function description
SPI1_IRQn	SPI1 interrupt
USART0_IRQn	USART0 interrupt
USART1_IRQn	USART1 interrupt
USART2_IRQn	USART2 interrupt
EXTI10_15_IRQn	EXTI[15:10] interrupts
RTC_Alarm_IRQn	RTC alarm interrupt
USBFS_WKUP_IRQn	USBFS wakeup interrupt
TIMER7_BRK_TIMER11_IRQn	TIMER7 break and TIMER11 interrupts
TIMER7_UP_TIMER12_IRQn	TIMER7 update and TIMER12 interrupts
TIMER7_TRG_CMT_TIMER13_IRQn	TIMER7 trigger and commutation and TIMER13 interrupts
TIMER7_Channel_IRQn	TIMER7 channel capture compare interrupt
EXMC_IRQn	EXMC global interrupt
TIMER4_IRQn	TIMER4 global interrupt
SPI2_IRQn	SPI2 global interrupt
UART3_IRQn	UART3 global interrupt
UART4_IRQn	UART4 global interrupt
TIMER5_IRQn	TIMER5 global interrupt
TIMER6_IRQn	TIMER6 global interrupt
DMA1_Channel0_IRQn	DMA1 channel0 global interrupt
DMA1_Channel1_IRQn	DMA1 channel1 global interrupt
DMA1_Channel2_IRQn	DMA1 channel2 global interrupt
DMA1_Channel3_IRQn	DMA1 channel3 global interrupt
DMA1_Channel4_IRQn	DMA1 channel4 global interrupt
CAN1_TX_IRQn	CAN1 transmit interrupt
CAN1_RX0_IRQn	CAN1 receive0 interrupt
CAN1_RX1_IRQn	CAN1 receive1 interrupt
CAN1_EWMC_IRQn	CAN1 EWMC interrupt
USBFS_IRQn	USBFS global interrupt

MISC firmware functions are listed in the table shown as below:

Table 3-218. MISC firmware function

Function name	Function description
nvic_irq_enable	enable NVIC interrupt request
nvic_irq_disable	disable NVIC interrupt request
nvic_system_reset	initiates a system reset request to reset the MCU
nvic_vector_table_set	set the NVIC vector table address
system_lowpower_set	set the state of the low power mode

Function name	Function description
system_lowpower_reset	reset the state of the low power mode
systick_clksource_set	set the systick clock source

nvic_irq_enable

The description of nvic_irq_enable is shown as below:

Table 3-219. Function nvic_irq_enable

Function name	nvic_irq_enable
Function prototype	void nvic_irq_enable(uint8_t nvic_irq, uint8_t nvic_irq_pre_priority);
Function descriptions	enable NVIC request, configure the priority of interrupt
Precondition	-
The called functions	NVIC_SetPriority、NVIC_EnableIRQ
Input parameter{in}	
nvic_irq	NVIC interrupt, refer to enum Enum IRQn_Type
Input parameter{in}	
nvic_irq_pre_priority	the pre-emption priority needed to set (0~3)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable window watchDog timer interrupt , priority is 1 */
nvic_irq_enable(WWDGT_IRQn, 1);
```

nvic_irq_disable

The description of nvic_irq_disable is shown as below:

Table 3-220. Function nvic_irq_disable

Function name	nvic_irq_disable
Function prototype	void nvic_irq_disable(uint8_t nvic_irq);
Function descriptions	disable NVIC request

Precondition	-
The called functions	-
Input parameter{in}	
nvic_irq	NVIC interrupt, refer to enum Enum IRQn_Type
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable window watchDog timer interrupt */
nvic_irq_disable(WWDGT_IRQn);
```

nvic_system_reset

The description of nvic_system_reset is shown as below:

Table 3-221. Function nvic_system_reset

Function name	nvic_system_reset
Function prototype	void nvic_system_reset (void);
Function descriptions	initiates a system reset request to reset the MCU
Precondition	-
The called functions	NVIC_SystemReset
Input parameter{in}	
nvic_irq	NVIC interrupt, refer to enum Enum IRQn_Type
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset the MCU*/
nvic_system_reset();
```

nvic_vector_table_set

The description of nvic_vector_table_set is shown as below:

Table 3-222. Function nvic_vector_table_set

Function name	nvic_vector_table_set
Function prototype	void nvic_vector_table_set(uint32_t nvic_vect_tab, uint32_t offset);
Function descriptions	set the NVIC vector table address
Precondition	-
The called functions	-
Input parameter{in}	
nvic_vect_tab	the RAM or FLASH base address
<i>NVIC_VECTTAB_RAM</i>	RAM base address
<i>NVIC_VECTTAB_FLASH</i>	Flash base address
Input parameter{in}	
offset	Vector Table offset (vector table start address= base address+offset)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set vector table address = NVIC_VECTTAB_FLASH +0x200 */
nvic_vector_table_set (NVIC_VECTTAB_FLASH,0x200);
```

system_lowpower_set

The description of system_lowpower_set is shown as below:

Table 3-223. Function system_lowpower_set

Function name	system_lowpower_set
Function prototype	void system_lowpower_set(uint8_t lowpower_mode);
Function descriptions	the state of the low power mode management
Precondition	-

The called functions	-
Input parameter{in}	
lowpower_mode	the low power mode state
<i>SCB_LPM_SLEEP_EXIT_ISR</i>	if chose this para, the system always enter low power mode by exiting from ISR
<i>SCB_LPM_DEEPSLEEP_P</i>	if chose this para, the system will enter the DEEPSLEEP mode
<i>SCB_LPM_WAKE_BY_ALL_INT</i>	if chose this para, the lowpower mode can be woke up by all the enable and disable interrupts
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* the system always enter low power mode by exiting from ISR */
system_lowpower_set (SCB_LPM_SLEEP_EXIT_ISR);
```

system_lowpower_reset

The description of system_lowpower_reset is shown as below:

Table 3-224. Function system_lowpower_reset

Function name	system_lowpower_reset
Function prototype	void system_lowpower_reset(uint8_t lowpower_mode);
Function descriptions	the state of the low power mode management
Precondition	-
The called functions	-
Input parameter{in}	
lowpower_mode	the low power mode state
<i>SCB_LPM_SLEEP_EXIT_ISR</i>	if chose this para, the system will exit low power mode by exiting from ISR
<i>SCB_LPM_DEEPSLEEP_P</i>	if chose this para, the system will enter the SLEEP mode

SCB_LPM_WAKE_BY_ALL_INT	if chose this para, the lowpower mode only can be woke up by the enable interrupts
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* the system will exit low power mode by exiting from ISR */
system_lowpower_reset (SCB_LPM_SLEEP_EXIT_ISR);
```

systick_clksource_set

The description of systick_clksource_set is shown as below:

Table 3-225. Function systick_clksource_set

Function name	systick_clksource_set
Function prototype	void systick_clksource_set(uint32_t systick_clksource);
Function descriptions	set the systick clock source
Precondition	-
The called functions	-
Input parameter{in}	
systick_clksource	the systick clock source needed to choose
SYSTICK_CLKSOURCE_HCLK	systick clock source is from HCLK
SYSTICK_CLKSOURCE_HCLK_DIV8	systick clock source is from HCLK/8
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* systick clock source is HCLK/8 */
systick_clksource_set (SYSTICK_CLKSOURCE_HCLK_DIV8);
```

3.13. PMU

According to the Power management unit (PMU), provides three types of power saving modes, including Sleep, Deep-sleep and Standby mode. The PMU registers are listed in chapter [3.13.1](#), the PMU firmware functions are introduced in chapter [3.13.2](#).

3.13.1. Descriptions of Peripheral registers

PMU registers are listed in the table shown as below:

Table 3-226. PMU Registers

Registers	Descriptions
PMU_CTL	PMU control register
PMU_CS	PMU control and status register

3.13.2. Descriptions of Peripheral functions

PMU firmware functions are listed in the table shown as below:

Table 3-227. PMU firmware function

Function name	Function description
pmu_deinit	reset PMU register
pmu_lvd_select	select low voltage detector threshold
pmu_ldo_output_select	select LDO output voltage
pmu_lvd_disable	disable PMU lvd
pmu_to_sleepmode	PMU work in sleep mode
pmu_to_deepsleepmode	PMU work at deepsleep mode
pmu_to_standbymode	pmu work at standby mode
pmu_wakeup_pin_enable	enable PMU wakeup pin
pmu_wakeup_pin_disable	disable PMU wakeup pin
pmu_backup_write_enable	enable backup domain write
pmu_backup_write_disable	disable backup domain write
pmu_flag_clear	clear flag bit
pmu_flag_get	get flag state

pmu_deinit

The description of pmu_deinit is shown as below:

Table 3-228. Function pmu_deinit

Function name	pmu_deinit
Function prototype	void pmu_deinit(void);
Function descriptions	reset PMU register
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset PMU */
pmu_deinit ();
```

pmu_lvd_select

The description of pmu_lvd_select is shown as below:

Table 3-229. Function pmu_lvd_select

Function name	pmu_lvd_select
Function prototype	void pmu_lvd_select(uint32_t lvd_t_n);
Function descriptions	select low voltage detector threshold
Precondition	-
The called functions	-
Input parameter{in}	
lvd_t_n	voltage threshold value
<i>PMU_LVDT_0</i>	voltage threshold is 2.1V

<i>PMU_LVDT_1</i>	voltage threshold is 2.3V
<i>PMU_LVDT_2</i>	voltage threshold is 2.4V
<i>PMU_LVDT_3</i>	voltage threshold is 2.6V
<i>PMU_LVDT_4</i>	voltage threshold is 2.7V
<i>PMU_LVDT_5</i>	voltage threshold is 2.9V
<i>PMU_LVDT_6</i>	voltage threshold is 3.0V
<i>PMU_LVDT_7</i>	voltage threshold is 3.1V
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* select low voltage detector threshold as 3.1V */
```

```
pmu_lvd_select (PMU_LVDT_7);
```

pmu_ldo_output_select

The description of `pmu_ldo_output_select` is shown as below:

Table 3-230. Function `pmu_ldo_output_select`

Function name	<code>pmu_ldo_output_select</code>
Function prototype	<code>void pmu_ldo_output_select(uint32_t ldo_output);</code>
Function descriptions	select LDO output voltage
Precondition	-
The called functions	-
Input parameter{in}	
ldo_output	output voltage mode
<i>PMU_LDOVS_LOW</i>	LDO output voltage low mode
<i>PMU_LDOVS_HIGH</i>	LDO output voltage high mode
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* select output low voltage mode */
pmu_ldo_output_select (PMU_LDOVS_LOW);
```

pmu_lvd_disable

The description of pmu_lvd_disable is shown as below:

Table 3-231. Function pmu_lvd_disable

Function name	pmu_lvd_disable
Function prototype	void pmu_lvd_disable (void);
Function descriptions	disable PMU lvd
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable PMU lvd */
pmu_lvd_disable ();
```

pmu_to_sleepmode

The description of pmu_to_sleepmode is shown as below:

Table 3-232. Function pmu_to_sleepmode

Function name	pmu_to_sleepmode
Function prototype	void pmu_to_sleepmode(uint8_t sleepmodecmd);
Function descriptions	PMU work at sleep mode

Precondition	-
The called functions	-
Input parameter{in}	
sleepmodecmd	command to enter sleep mode
<i>WFI_CMD</i>	use WFI command
<i>WFE_CMD</i>	use WFE command
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* PMU work at sleep mode */
```

```
pmu_to_sleepmode (WFI_CMD);
```

pmu_to_deepsleepmode

The description of pmu_to_deepsleepmode is shown as below:

Table 3-233. Function pmu_to_deepsleepmode

Function name	pmu_to_deepsleepmode
Function prototype	void pmu_to_deepsleepmode(uint32_t ldo,uint8_t deepsleepmodecmd);
Function descriptions	PMU work at deepsleep mode
Precondition	-
The called functions	-
Input parameter{in}	
ldo	ldo work mode
<i>PMU_LDO_NORMAL</i>	LDO operates normally when pmu enter deepsleep mode
<i>PMU_LDO_LOWPOWER</i>	LDO work at low power mode when pmu enter deepsleep mode
Input parameter{in}	
deepsleepmodecmd	command to enter deepsleep mode

<i>WFI_CMD</i>	use WFI command
<i>WFE_CMD</i>	use WFE command
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* PMU work at deepsleep mode */
```

```
pmu_to_deepsleepmode (PMU_LDO_NORMAL, WFI_CMD);
```

pmu_to_standbymode

The description of pmu_to_standbymode is shown as below:

Table 3-234. Function pmu_to_standbymode

Function name	pmu_to_standbymode
Function prototype	void pmu_to_standbymode(uint8_t standbymodecmd);
Function descriptions	pmu work at standby mode
Precondition	-
The called functions	-
Input parameter{in}	
standbymodecmd	command to enter standby mode
<i>WFI_CMD</i>	use WFI command
<i>WFE_CMD</i>	use WFE command
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* PMU work at standby mode */
```

```
pmu_to_standby (WFI_CMD);
```

pmu_wakeup_pin_enable

The description of pmu_wakeup_pin_enable is shown as below:

Table 3-235. Function pmu_wakeup_pin_enable

Function name	pmu_wakeup_pin_enable
Function prototype	void pmu_wakeup_pin_enable(uint32_t wakeup_pin);
Function descriptions	enable wakeup pin
Precondition	-
The called functions	-
Input parameter{in}	
wakeup_pin	Wakeup pin
<i>PMU_WAKEUP_PIN0</i>	WKUP Pin 0 (PA0)
<i>PMU_WAKEUP_PIN1</i>	WKUP Pin 1 (PC13)
<i>PMU_WAKEUP_PIN5</i>	WKUP Pin 5 (PB5)
<i>PMU_WAKEUP_PIN6</i>	WKUP Pin 6 (PB15)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable wakeup pin6 */
pmu_wakeup_pin_enable (PMU_WAKEUP_PIN6);
```

pmu_wakeup_pin_disable

The description of pmu_wakeup_pin_disable is shown as below:

Table 3-236. Function pmu_wakeup_pin_disable

Function name	pmu_wakeup_pin_disable
Function prototype	void pmu_wakeup_pin_disable(uint32_t wakeup_pin);
Function descriptions	disable wakeup pin
Precondition	-

The called functions	-
Input parameter{in}	
wakeup_pin	Wakeup pin
<i>PMU_WAKEUP_PIN0</i>	WKUP Pin 0 (PA0)
<i>PMU_WAKEUP_PIN1</i>	WKUP Pin 1 (PC13)
<i>PMU_WAKEUP_PIN5</i>	WKUP Pin 5 (PB5)
<i>PMU_WAKEUP_PIN6</i>	WKUP Pin 6 (PB15)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable wakeup pin6 */
```

```
pmu_wakeup_pin_disable (PMU_WAKEUP_PIN6);
```

pmu_backup_write_enable

The description of pmu_backup_write_enable is shown as below:

Table 3-237. Function pmu_backup_write_enable

Function name	pmu_backup_write_enable
Function prototype	void pmu_backup_write_enable (void);
Function descriptions	enable backup domain write
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable backup domain write */
pmu_backup_write_enable ();
```

pmu_backup_write_disable

The description of pmu_backup_write_disable is shown as below:

Table 3-238. Function pmu_backup_write_disable

Function name	pmu_backup_write_disable
Function prototype	void pmu_backup_write_disable (void);
Function descriptions	disable backup domain write
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable backup domain write */
pmu_backup_write_disable ();
```

pmu_flag_clear

The description of pmu_flag_clear is shown as below:

Table 3-239. Function pmu_flag_clear

Function name	pmu_flag_clear
Function prototype	void pmu_flag_clear(uint32_t flag_clear);
Function descriptions	clear flag bit
Precondition	-
The called functions	-

Input parameter{in}	
flag_clear	flag
<i>PMU_FLAG_RESET_WAKEUP</i>	reset wakeup flag
<i>PMU_FLAG_RESET_STANDBY</i>	reset standby flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear flag bit */
```

```
pmu_flag_clear (PMU_FLAG_RESET_WAKEUP);
```

pmu_flag_get

The description of pmu_flag_get is shown as below:

Table 3-240. Function pmu_flag_get

Function name	pmu_flag_get
Function prototype	FlagStatus pmu_flag_get(uint32_t flag);
Function descriptions	get flag state
Precondition	-
The called functions	-
Input parameter{in}	
flag	flag
<i>PMU_FLAG_WAKEUP</i>	wakeup flag
<i>PMU_FLAG_STANDBY</i>	standby flag
<i>PMU_FLAG_LVD</i>	lvd flag
Output parameter{out}	
-	-
Return value	

FlagStatus	SET or RESET
-------------------	--------------

Example:

```
/* get flag state */
```

```
FlagStatus status;
```

```
status = pmu_flag_get (PMU_FLAG_WAKEUP);
```

3.14. RCU

RCU is the reset and clock unit. Reset Control includes the control of three kinds of reset: power reset, system reset and backup domain reset. The Clock Control unit provides a range of frequencies and clock functions. The RCU registers are listed in chapter [3.14.1](#), the RCU firmware functions are introduced in chapter [3.14.2](#).

3.14.1. Descriptions of Peripheral registers

Table 3-241. RCU Registers

Registers	Descriptions
RCU_CTL0	Control register 0
RCU_CFG0	Clock configuration register 0
RCU_INT	Clock interrupt register
RCU_APB2RST	APB2 reset register
RCU_APB1RST	APB1 reset register
RCU_AHBEN	AHB enable register
RCU_APB2EN	APB2 enable register
RCU_APB1EN	APB1 enable register
RCU_BDCTL	Backup domain control register
RCU_RSTSCK	Reset source/clock register
RCU_AHBRST	AHB reset register
RCU_CFG1	Clock configuration register 1
RCU_CFG2	Clock configuration register 2
RCU_CTL1	Control register 1
RCU_VKEY	Unlock voltage register

Registers	Descriptions
RCU_DSV	Deep-sleep mode voltage register

3.14.2. Descriptions of Peripheral functions

Table 3-242. RCU firmware function

Function name	Function description
rcu_deinit	deinitialize the RCU
rcu_periph_clock_enable	enable the peripherals clock
rcu_periph_clock_disable	disable the peripherals clock
rcu_periph_clock_sleep_enable	enable the peripherals clock when in sleep mode
rcu_periph_clock_sleep_disable	disable the peripherals clock when in sleep mode
rcu_periph_reset_enable	enable the peripherals reset
rcu_periph_reset_disable	disable the peripheral reset
rcu_bkp_reset_enable	enable the BKP domain reset
rcu_bkp_reset_disable	disable the BKP domain reset
rcu_system_clock_source_config	configure the system clock source
rcu_system_clock_source_get	get the system clock source
rcu_ahb_clock_config	configure the AHB clock prescaler selection
rcu_apb1_clock_config	configure the APB1 clock prescaler selection
rcu_apb2_clock_config	configure the APB2 clock prescaler selection
rcu_adc_clock_config	configure the ADC clock source and prescaler selection
rcu_ckout_config	configure the CK_OUT clock source and divider
rcu_pll_config	configure the main PLL clock
rcu_usart_clock_config	configure the usart clock
rcu_rtc_clock_config	configure the RTC clock source selection
rcu_hxtal_prediv_config	configure the HXTAL divider used as input of PLL
rcu_lxtal_drive_capability_config	configure the LXTAL drive capability
rcu_flag_get	get the clock stabilization and peripheral reset flags
rcu_all_reset_flag_clear	clear all the reset flag

Function name	Function description
rcu_interrupt_flag_get	get the clock stabilization interrupt and ckm flags
rcu_interrupt_flag_clear	clear the interrupt flags
rcu_interrupt_enable	enable the stabilization interrupt
rcu_interrupt_disable	disable the stabilization interrupt
rcu_osci_stab_wait	wait for oscillator stabilization flags is SET or oscillator startup is timeout
rcu_osci_on	turn on the oscillator
rcu_osci_off	turn off the oscillator
rcu_osci_bypass_mode_enable	enable the oscillator bypass mode
rcu_osci_bypass_mode_disable	disable the oscillator bypass mode
rcu_hxtal_clock_monitor_enable	enable the HXTAL clock monitor
rcu_hxtal_clock_monitor_disable	disable the HXTAL clock monitor
rcu_irc8m_adjust_value_set	set the IRC8M adjust value
rcu_irc28m_adjust_value_set	set the IRC28M adjust value
rcu_voltage_key_unlock	unlock Deep-sleep mode voltage register
rcu_deepsleep_voltage_set	set the deep-sleep mode voltage value
rcu_clock_freq_get	get the system clock, bus clock frequency

rcu_deinit

The description of rcu_deinit is shown as below:

Table 3-243. Function rcu_deinit

Function name	rcu_deinit
Function prototype	void rcu_deinit(void);
Function descriptions	deinitialize the RCU, reset the value of all RCU registers into initial values
Precondition	-
The called functions	-
Input parameter{in}	
-	-

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset RCU */
```

```
rcu_deinit();
```

rcu_periph_clock_enable

The description of rcu_periph_clock_enable is shown as below:

Table 3-244. Function rcu_periph_clock_enable

Function name	rcu_periph_clock_enable
Function prototype	void rcu_periph_clock_enable(rcu_periph_enum periph);
Function descriptions	enable the peripherals clock
Precondition	-
The called functions	-
Input parameter{in}	
periph	RCU peripherals, refer to rcu_periph_enum
<i>RCU_GPIOx</i>	GPIO ports clock (x=A,B,C,F)
<i>RCU_DMA</i>	DMA clock
<i>RCU_CRC</i>	CRC clock
<i>RCU_CFGCMP</i>	CFGCMP clock
<i>RCU_ADC</i>	ADC clock
<i>RCU_TIMERx</i>	TIMERx clock(x=0,2,5,13,14,15,16)
<i>RCU_SPIx</i>	SPIx clock (x=0,1)
<i>RCU_USARTx</i>	USARTx clock (x=0,1)
<i>RCU_WWDGT</i>	WWDGT clock
<i>RCU_I2Cx</i>	I2Cx clock (x=0,1)
<i>RCU_PMU</i>	PMU clock

<i>RCU_RTC</i>	RTC clock
<i>RCU_DBGMCU</i>	DBGMCU clock
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the USART0 clock */
```

```
rcu_periph_clock_enable(RCU_USART0);
```

rcu_periph_clock_disable

The description of `rcu_periph_clock_disable` is shown as below:

Table 3-245. Function `rcu_periph_clock_disable`

Function name	<code>rcu_periph_clock_disable</code>
Function prototype	<code>void rcu_periph_clock_disable(rcu_periph_enum periph);</code>
Function descriptions	disable the peripherals clock
Precondition	-
The called functions	-
Input parameter{in}	
periph	RCU peripherals, refer to <code>rcu_periph_enum</code>
<i>RCU_GPIOx</i>	GPIO ports clock (x=A,B,C,F)
<i>RCU_DMA</i>	DMA clock
<i>RCU_CRC</i>	CRC clock
<i>RCU_CFGCMP</i>	CFGCMP clock
<i>RCU_ADC</i>	ADC clock
<i>RCU_TIMERx</i>	TIMERx clock(x=0,2,5,13,14,15,16)
<i>RCU_SPIx</i>	SPIx clock (x=0,1)
<i>RCU_USARTx</i>	USARTx clock (x=0,1)
<i>RCU_WWDGT</i>	WWDGT clock

<i>RCU_I2Cx</i>	I2Cx clock (x=0,1)
<i>RCU_PMU</i>	PMU clock
<i>RCU_RTC</i>	RTC clock
<i>RCU_DBGMCU</i>	DBGMCU clock
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the USART0 clock */
```

```
rcu_periph_clock_disable(RCU_USART0);
```

rcu_periph_clock_sleep_enable

The description of `rcu_periph_clock_sleep_enable` is shown as below:

Table 3-246. Function `rcu_periph_clock_sleep_enable`

Function name	<code>rcu_periph_clock_sleep_enable</code>
Function prototype	<code>void rcu_periph_clock_sleep_enable(rcu_periph_sleep_enum periph);</code>
Function descriptions	enable the peripherals clock when in sleep mode
Precondition	-
The called functions	-
Input parameter{in}	
periph	RCU peripherals, refer to <code>rcu_periph_sleep_enum</code>
<i>RCU_FMC_SLP</i>	FMC clock
<i>RCU_SRAM_SLP</i>	SRAM clock
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the FMC clock when in sleep mode */
```

```
rcu_periph_clock_sleep_enable(RCU_FMC_SLP);
```

rcu_periph_clock_sleep_disable

The description of rcu_periph_clock_sleep_disable is shown as below:

Table 3-247. Function rcu_periph_clock_sleep_disable

Function name	rcu_periph_clock_sleep_disable
Function prototype	void rcu_periph_clock_sleep_disable(rcu_periph_sleep_enum periph);
Function descriptions	disable the peripherals clock when in sleep mode
Precondition	-
The called functions	-
Input parameter{in}	
periph	RCU peripherals, refer to rcu_periph_sleep_enum
<i>RCU_FMC_SLP</i>	FMC clock
<i>RCU_SRAM_SLP</i>	SRAM clock
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the FMC clock when in sleep mode */
```

```
rcu_periph_clock_sleep_disable(RCU_FMC_SLP);
```

rcu_periph_reset_enable

The description of rcu_periph_reset_enable is shown as below:

Table 3-248. Function rcu_periph_reset_enable

Function name	rcu_periph_reset_enable
Function prototype	void rcu_periph_reset_enable(rcu_periph_reset_enum periph_reset);
Function descriptions	enable the peripherals reset
Precondition	-

The called functions	-
Input parameter{in}	
periph_reset	RCU peripherals reset, refer to rcu_periph_reset_enum
<i>RCU_GPIOxRST</i>	reset GPIO ports clock (x=A,B,C,F)
<i>RCU_CFGCMRST</i>	reset CFGCMP clock
<i>RCU_ADCRST</i>	reset ADC clock
<i>RCU_TIMERxRST</i>	reset TIMERx clock (x=0,2,5,13,14,15,16)
<i>RCU_SPIxRST</i>	reset SPIx clock (x=0,1)
<i>RCU_USARTxRST</i>	reset USARTx clock (x=0,1)
<i>RCU_WWDGTRST</i>	reset WWDGT clock
<i>RCU_I2CxRST</i>	reset I2Cx clock (x=0,1)
<i>RCU_PMURST</i>	reset PMU clock
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable SPI0 reset */
```

```
rcu_periph_reset_enable(RCU_SPI0RST);
```

rcu_periph_reset_disable

The description of rcu_periph_reset_disable is shown as below:

Table 3-249. Function rcu_periph_reset_disable

Function name	rcu_periph_reset_disable
Function prototype	void rcu_periph_reset_disable(rcu_periph_reset_enum periph_reset);
Function descriptions	disable the peripheral reset
Precondition	-
The called functions	-
Input parameter{in}	

periph_reset	RCU peripherals reset, refer to rcu_periph_reset_enum
<i>RCU_GPIOxRST</i>	disable reset GPIO ports clock (x=A,B,C,F)
<i>RCU_CFGCMRST</i>	disable reset CFGCMP clock
<i>RCU_ADCRST</i>	disable reset ADC clock
<i>RCU_TIMERxRST</i>	disable reset TIMERx clock (x=0,2,5,13,14,15,16)
<i>RCU_SPIxRST</i>	disable reset SPIx clock (x=0,1)
<i>RCU_USARTxRST</i>	disable reset USARTx clock (x=0,1)
<i>RCU_WWDGTRST</i>	disable reset WWDGT clock
<i>RCU_I2CxRST</i>	disable reset I2Cx clock (x=0,1)
<i>RCU_PMURST</i>	disable reset PMU clock
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable SPI0 reset */
```

```
rcu_periph_reset_disable(RCU_SPI0RST);
```

rcu_bkp_reset_enable

The description of rcu_bkp_reset_enable is shown as below:

Table 3-250. Function rcu_bkp_reset_enable

Function name	rcu_bkp_reset_enable
Function prototype	void rcu_bkp_reset_enable(void);
Function descriptions	enable the BKP domain reset
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* reset the BKP domain */
rcu_bkp_reset_enable();
```

rcu_bkp_reset_disable

The description of rcu_bkp_reset_disable is shown as below:

Table 3-251. Function rcu_bkp_reset_disable

Function name	rcu_bkp_reset_disable
Function prototype	void rcu_bkp_reset_disable(void);
Function descriptions	disable the BKP domain reset
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the BKP domain reset */
rcu_bkp_reset_disable();
```

rcu_system_clock_source_config

The description of rcu_system_clock_source_config is shown as below:

Table 3-252. Function rcu_system_clock_source_config

Function name	rcu_system_clock_source_config
Function prototype	void rcu_system_clock_source_config(uint32_t ck_sys);

Function descriptions	configure the system clock source
Precondition	-
The called functions	-
Input parameter{in}	
ck_sys	system clock source select
<i>RCU_CKSYSSRC_IRC8M</i>	select CK_IRC8M as the CK_SYS source
<i>RCU_CKSYSSRC_HXTAL</i>	select CK_HXTAL as the CK_SYS source
<i>RCU_CKSYSSRC_PLL</i>	select CK_PLL as the CK_SYS source
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the CK_HXTAL as the CK_SYS source */
rcu_system_clock_source_config(RCU_CKSYSSRC_HXTAL);
```

rcu_system_clock_source_get

The description of `rcu_system_clock_source_get` is shown as below:

Table 3-253. Function `rcu_system_clock_source_get`

Function name	<code>rcu_system_clock_source_get</code>
Function prototype	<code>uint32_t rcu_system_clock_source_get(void);</code>
Function descriptions	get the system clock source
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-

Return value	
<code>uint32_t</code>	RCU_SCSS_IRC8M/RCU_SCSS_HXTAL/RCU_SCSS_PLL

Example:

```
uint32_t temp_cksys_status;

/* get the CK_SYS source */

temp_cksys_status = rcu_system_clock_source_get();
```

rcu_ahb_clock_config

The description of `rcu_ahb_clock_config` is shown as below:

Table 3-254. Function `rcu_ahb_clock_config`

Function name	<code>rcu_ahb_clock_config</code>
Function prototype	<code>void rcu_ahb_clock_config(uint32_t ck_ahb);</code>
Function descriptions	configure the AHB clock prescaler selection
Precondition	-
The called functions	-
Input parameter{in}	
ck_ahb	AHB clock prescaler selection
<i>RCU_AHB_CKSYS_DIVx</i>	select CK_SYS / x, (x=1, 2, 4, 8, 16, 64, 128, 256, 512)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure CK_SYS/128 */

rcu_ahb_clock_config(RCU_AHB_CKSYS_DIV128);
```

rcu_apb1_clock_config

The description of `rcu_apb1_clock_config` is shown as below:

Table 3-255. Function rcu_apb1_clock_config

Function name	rcu_apb1_clock_config
Function prototype	void rcu_apb1_clock_config(uint32_t ck_apb1);
Function descriptions	configure the APB1 clock prescaler selection
Precondition	-
The called functions	-
Input parameter{in}	
ck_apb1	APB1 clock prescaler selection
<i>RCU_APB1_CKAHB_DIVx</i>	select (CK_AHB / x) as CK_APB1 (x=1,2,4,8,16)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure CK_AHB/16 as CK_APB1 */
rcu_apb1_clock_config(RCU_APB1_CKAHB_DIV16);
```

rcu_apb2_clock_config

The description of rcu_apb2_clock_config is shown as below:

Table 3-256. Function rcu_apb2_clock_config

Function name	rcu_apb2_clock_config
Function prototype	void rcu_apb2_clock_config(uint32_t ck_apb2);
Function descriptions	configure the APB2 clock prescaler selection
Precondition	-
The called functions	-
Input parameter{in}	
ck_apb2	APB2 clock prescaler selection
<i>RCU_APB2_CKAHB_DIVx</i>	select (CK_AHB / x) as CK_APB2 clock (x=1,2,4,8,16)

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure CK_AHB/8 as CK_APB2 */
rcu_apb2_clock_config(RCU_APB2_CKAHB_DIV8);
```

rcu_adc_clock_config

The description of rcu_adc_clock_config is shown as below:

Table 3-257. Function rcu_adc_clock_config

Function name	rcu_adc_clock_config
Function prototype	void rcu_adc_clock_config(rcu_adc_clock_enum ck_adc);
Function descriptions	configure the ADC clock prescaler selection
Precondition	-
The called functions	-
Input parameter{in}	
ck_adc	ADC clock prescaler selection, refer to rcu_adc_clock_enum
<i>RCU_ADCCK_IRC28M_DIV2</i>	select CK_APB2/2 as CK_ADC
<i>RCU_ADCCK_IRC28M</i>	select CK_IRC28M as CK_ADC
<i>RCU_ADCCK_AHB_DIVx</i>	select (CK_AHB / x) as CK_ADC(x=3,5,7,9)
<i>RCU_ADCCK_APB2_DIVx</i>	select (CK_APB2 / x) as CK_ADC(x=2,4,6,8)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the ADC prescaler factor */
```

```
rcu_adc_clock_config(RCU_CKADC_CKAPB2_DIV8);
```

rcu_ckout_config

The description of rcu_ckout_config is shown as below:

Table 3-258. Function rcu_ckout_config

Function name	rcu_ckout_config
Function prototype	void rcu_ckout_config(uint32_t ckout_src, uint32_t ckout_div);
Function descriptions	configure the CK_OUT clock source and division factor
Precondition	-
The called functions	-
Input parameter{in}	
ckout_src	CK_OUT clock source selection
<i>RCU_CKOUTSRC_NONE</i>	no clock selected
<i>RCU_CKOUTSRC_IRC28M</i>	select high speed 28M internal oscillator clock
<i>RCU_CKOUTSRC_IRC40K</i>	select high speed 40K internal oscillator clock
<i>RCU_CKOUTSRC_LXTAL</i>	select LXTAL clock
<i>RCU_CKOUTSRC_CKSYS</i>	select system clock CK_SYS
<i>RCU_CKOUTSRC_IRC8M</i>	select high speed 8M internal oscillator clock
<i>RCU_CKOUTSRC_HXTAL</i>	select HXTAL clock
<i>RCU_CKOUTSRC_CKPLL_DIV1</i>	select CK_PLL clock
<i>RCU_CKOUTSRC_CKPLL_DIV2</i>	Select (CK_PLL / 2) clock
Input parameter{in}	

ckout_div	CK_OUT divider
<i>RCU_CKOUT_DIVx</i>	CK_OUT is divided by x(x=1,2,4,8,16,32,64,128)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the HXTAL as CK_OUT clock source */
```

```
rcu_ckout_config(RCU_CKOUTSRC_HXTAL);
```

rcu_pll_config

The description of `rcu_pll_config` is shown as below:

Table 3-259. Function `rcu_pll_config`

Function name	<code>rcu_pll_config</code>
Function prototype	<code>void rcu_pll_config(uint32_t pll_src, uint32_t pll_mul);</code>
Function descriptions	configure the main PLL clock
Precondition	-
The called functions	-
Input parameter{in}	
pll_src	PLL clock source selection
<i>RCU_PLLSRC_IRC8M_DIV2</i>	IRC8M/2 clock is selected as source clock of PLL
<i>RCU_PLLSRC_HXTAL</i>	HXTAL is selected as source clock of PLL
Input parameter{in}	
pll_mul	PLL clock multiplication factor
<i>RCU_PLL_MULx</i>	PLL source clock * x (x = 2..32)
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* configure the PLL */
```

```
rcu_pll_config(RCU_PLLSRC_HXTAL, RCU_PLL_MUL10);
```

rcu_usart_clock_config

The description of `rcu_usart_clock_config` is shown as below:

Table 3-260. Function `rcu_usart_clock_config`

Function name	rcu_usart_clock_config
Function prototype	void rcu_usart_clock_config(uint32_t ck_usart);
Function descriptions	configure the USART clock source selection
Precondition	-
The called functions	-
Input parameter{in}	
ck_usart	USART clock source selection
<i>RCU_USART0SRC_C KAPB2</i>	CK_USART0 select CK_APB2
<i>RCU_USART0SRC_C KSYS</i>	CK_USART0 select CK_SYS
<i>RCU_USART0SRC_LX TAL</i>	CK_USART0 select CK_LXTAL
<i>RCU_USART0SRC_IR C8M</i>	CK_USART0 select CK_IRC8M
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the LXTAL as USART0 clock */
```

```
rcu_usart_clock_config(RCU_USART0SRC_LXTAL);
```

rcu_rtc_clock_config

The description of rcu_rtc_clock_config is shown as below:

Table 3-261. Function rcu_rtc_clock_config

Function name	rcu_rtc_clock_config
Function prototype	void rcu_rtc_clock_config(uint32_t rtc_clock_source);
Function descriptions	configure the RTC clock source selection
Precondition	-
The called functions	-
Input parameter{in}	
rtc_clock_source	RTC clock source selection
<i>RCU_RTCSRC_NONE</i>	no clock selected
<i>RCU_RTCSRC_LXTAL</i>	select CK_LXTAL as RTC source clock
<i>RCU_RTCSRC_IRC40K</i>	select CK_IRC40K as RTC source clock
<i>RCU_RTCSRC_HXTAL_DIV_32</i>	select (CK_HXTAL / 32) as RTC source clock
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the RTC clock source selection */
rcu_rtc_clock_config(RCU_RTCSRC_IRC40K);
```

rcu_hxtal_prediv_config

The description of rcu_hxtal_prediv_config is shown as below:

Table 3-262. Function rcu_hxtal_prediv_config

Function name	rcu_hxtal_prediv_config
Function prototype	void rcu_hxtal_prediv_config(uint32_t hxtal_prediv)
Function descriptions	configure the HXTAL divider used as input of PLL

Precondition	-
The called functions	-
Input parameter{in}	
hxtal_prediv	HXTAL divider used as input of PLL
<i>RCU_PLL_PREDVx</i>	HXTAL divided x used as input of PLL (x=1..16)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the PLL clock source selection*/
rcu_hxtal_prediv_config(RCU_PLL_PREDV2);
```

rcu_lxtal_drive_capability_config

The description of rcu_lxtal_drive_capability_config is shown as below:

Table 3-263. Function rcu_lxtal_drive_capability_config

Function name	rcu_lxtal_drive_capability_config
Function prototype	void rcu_lxtal_drive_capability_config(uint32_t lxtal_dricap);
Function descriptions	configure the LXTAL drive capability
Precondition	-
The called functions	-
Input parameter{in}	
lxtal_dricap	drive capability of LXTAL
<i>RCU_LXTAL_LOWDRI</i>	lower driving capability
<i>RCU_LXTAL_MED_LOWDRI</i>	medium low driving capability
<i>RCU_LXTAL_MED_HI_GHDI</i>	medium high driving capability
<i>RCU_LXTAL_HIGHDRI</i>	higher driving capability
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* configure the LXTAL drive capability */
```

```
rcu_lxtal_drive_capability_config (RCU_LXTAL_LOWDRI);
```

rcu_flag_get

The description of rcu_flag_get is shown as below:

Table 3-264. Function rcu_flag_get

Function name	rcu_flag_get
Function prototype	FlagStatus rcu_flag_get(rcu_flag_enum flag);
Function descriptions	get the clock stabilization and peripheral reset flags
Precondition	-
The called functions	-
Input parameter{in}	
flag	the clock stabilization and peripheral reset flags, refer to rcu_flag_enum
<i>RCU_FLAG_IRC40KST</i> <i>B</i>	IRC40K stabilization flag
<i>RCU_FLAG_LXTALST</i> <i>B</i>	LXTAL stabilization flag
<i>RCU_FLAG_IRC8MST</i> <i>B</i>	IRC8M stabilization flag
<i>RCU_FLAG_HXTALST</i> <i>B</i>	HXTAL stabilization flag
<i>RCU_FLAG_PLLSTB</i>	PLL stabilization flag
<i>RCU_FLAG_IRC28MS</i> <i>TB</i>	IRC28M stabilization flag
<i>RCU_FLAG_V12RST</i>	V12 domain power reset flag
<i>RCU_FLAG_OBLRST</i>	option byte loader reset flag
<i>RCU_FLAG_EPRST</i>	external PIN reset flag

<i>RCU_FLAG_PORRST</i>	power reset flag
<i>RCU_FLAG_SWRST</i>	software reset flag
<i>RCU_FLAG_FWDGTR ST</i>	free watchdog timer reset flag
<i>RCU_FLAG_WWDGTR ST</i>	window watchdog timer reset flag
<i>RCU_FLAG_LPRST</i>	low-power reset flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```

/* get the clock stabilization flag */
if(RESET != rcu_flag_get(RCU_FLAG_LXTALSTB)){
}

```

rcu_all_reset_flag_clear

The description of rcu_all_reset_flag_clear is shown as below:

Table 3-265. Function rcu_all_reset_flag_clear

Function name	rcu_all_reset_flag_clear
Function prototype	void rcu_all_reset_flag_clear(void);
Function descriptions	clear all the reset flag
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear all the reset flag */
rcu_all_reset_flag_clear();
```

rcu_interrupt_flag_get

The description of rcu_interrupt_flag_get is shown as below:

Table 3-266. Function rcu_interrupt_flag_get

Function name	rcu_interrupt_flag_get
Function prototype	FlagStatus rcu_interrupt_flag_get(rcu_int_flag_enum int_flag);
Function descriptions	get the clock stabilization interrupt and ckm flags
Precondition	-
The called functions	-
Input parameter{in}	
int_flag	interrupt and ckm flags, refer to rcu_int_flag_enum
<i>RCU_INT_FLAG_IRC40KSTB</i>	IRC40K stabilization interrupt flag
<i>RCU_INT_FLAG_LXTALSTB</i>	LXTAL stabilization interrupt flag
<i>RCU_INT_FLAG_IRC8MSTB</i>	IRC8M stabilization interrupt flag
<i>RCU_INT_FLAG_HXTALALSTB</i>	HXTAL stabilization interrupt flag
<i>RCU_INT_FLAG_PLLSTB</i>	PLL stabilization interrupt flag
<i>RCU_INT_FLAG_IRC28MSTB</i>	IRC28M stabilization interrupt flag
<i>RCU_INT_FLAG_CKM</i>	HXTAL clock stuck interrupt flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```

/* get the clock stabilization interrupt flag */
if(SET == rcu_interrupt_flag_get(RCU_INT_FLAG_HXTALSTB)){
}

```

rcu_interrupt_flag_clear

The description of rcu_interrupt_flag_clear is shown as below:

Table 3-267. Function rcu_interrupt_flag_clear

Function name	rcu_interrupt_flag_clear
Function prototype	void rcu_interrupt_flag_clear(rcu_int_flag_clear_enum int_flag_clear)
Function descriptions	clear the interrupt flags
Precondition	-
The called functions	-
Input parameter{in}	
int_flag_clear	clock stabilization and stuck interrupt flags clear, refer to rcu_int_flag_clear_enum
<i>RCU_INT_FLAG_IRC40KSTB_CLR</i>	IRC40K stabilization interrupt flag clear
<i>RCU_INT_FLAG_LXTALSTB_CLR</i>	LXTAL stabilization interrupt flag clear
<i>RCU_INT_FLAG_IRC8MSTB_CLR</i>	IRC8M stabilization interrupt flag clear
<i>RCU_INT_FLAG_HXTALSTB_CLR</i>	HXTAL stabilization interrupt flag clear
<i>RCU_INT_FLAG_PLLSTB_CLR</i>	PLL stabilization interrupt flag clear
<i>RCU_INT_FLAG_IRC28MSTB_CLR</i>	IRC28M stabilization interrupt flag clear
<i>RCU_INT_FLAG_CKMSCLKR_CLR</i>	clock stuck interrupt flag clear
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* clear the interrupt HXTAL stabilization interrupt flag */
rcu_interrupt_flag_clear(RCU_INT_FLAG_HXTALSTB_CLR);
```

rcu_interrupt_enable

The description of rcu_interrupt_enable is shown as below:

Table 3-268. Function rcu_interrupt_enable

Function name	rcu_interrupt_enable
Function prototype	void rcu_interrupt_enable(rcu_int_enum stab_int);
Function descriptions	enable the stabilization interrupt
Precondition	-
The called functions	-
Input parameter{in}	
stab_int	clock stabilization interrupt, refer to rcu_int_enum
<i>RCU_INT_IRC40KSTB</i>	IRC40K stabilization interrupt enable
<i>RCU_INT_LXTALSTB</i>	LXTAL stabilization interrupt enable
<i>RCU_INT_IRC8MSTB</i>	IRC8M stabilization interrupt enable
<i>RCU_INT_HXTALSTB</i>	HXTAL stabilization interrupt enable
<i>RCU_INT_PLLSTB</i>	PLL stabilization interrupt enable
<i>RCU_INT_IRC28MSTB</i>	IRC28M stabilization interrupt enable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the HXTAL stabilization interrupt */
rcu_interrupt_enable(RCU_INT_HXTALSTB);
```

rcu_interrupt_disable

The description of rcu_interrupt_disable is shown as below:

Table 3-269. Function rcu_interrupt_disable

Function name	rcu_interrupt_disable
Function prototype	void rcu_interrupt_disable(rcu_int_enum stab_int);
Function descriptions	disable the stabilization interrupt
Precondition	-
The called functions	-
Input parameter{in}	
stab_int	clock stabilization interrupt, refer to rcu_int_enum
<i>RCU_INT_IRC40KSTB</i>	IRC40K stabilization interrupt disable
<i>RCU_INT_LXTALSTB</i>	LXTAL stabilization interrupt disable
<i>RCU_INT_IRC8MSTB</i>	IRC8M stabilization interrupt disable
<i>RCU_INT_HXTALSTB</i>	HXTAL stabilization interrupt disable
<i>RCU_INT_PLLSTB</i>	PLL stabilization interrupt disable
<i>RCU_INT_IRC28MSTB</i>	IRC28M stabilization interrupt disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the HXTAL stabilization interrupt */
rcu_interrupt_disable(RCU_INT_HXTALSTB);
```

rcu_osci_stab_wait

The description of rcu_osci_stab_wait is shown as below:

Table 3-270. Function rcu_osci_stab_wait

Function name	rcu_osci_stab_wait
Function prototype	ErrStatus rcu_osci_stab_wait(rcu_osci_type_enum osci);

Function descriptions	wait for oscillator stabilization flags is SET or oscillator startup is timeout
Precondition	-
The called functions	-
Input parameter{in}	
osci	oscillator types, refer to rcu_osci_type_enum
<i>RCU_HXTAL</i>	high speed crystal oscillator(HXTAL)
<i>RCU_LXTAL</i>	low speed crystal oscillator(LXTAL)
<i>RCU_IRC8M</i>	internal 8M RC oscillators(IRC8M)
<i>RCU_IRC28M</i>	internal 28M RC oscillators(IRC28M)
<i>RCU_IRC40K</i>	internal 40K RC oscillator(IRC40K)
<i>RCU_PLL_CK</i>	phase locked loop(PLL)
Output parameter{out}	
-	-
Return value	
ErrStatus	SUCCESS or ERROR

Example:

```

/* wait for oscillator stabilization flag */
if(SUCCESS == rcu_osci_stab_wait(RCU_HXTAL)){
}

```

rcu_osci_on

The description of rcu_osci_on is shown as below:

Table 3-271. Function rcu_osci_on

Function name	rcu_osci_on
Function prototype	void rcu_osci_on(rcu_osci_type_enum osci);
Function descriptions	turn on the oscillator
Precondition	-
The called functions	-
Input parameter{in}	

osci	oscillator types, refer to rcu_osci_type_enum
<i>RCU_HXTAL</i>	high speed crystal oscillator(HXTAL)
<i>RCU_LXTAL</i>	low speed crystal oscillator(LXTAL)
<i>RCU_IRC8M</i>	internal 8M RC oscillators(IRC8M)
<i>RCU_IRC28M</i>	internal 28M RC oscillators(IRC28M)
<i>RCU_IRC40K</i>	internal 40K RC oscillator(IRC40K)
<i>RCU_PLL_CK</i>	phase locked loop(PLL)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* turn on the high speed crystal oscillator */
```

```
rcu_osci_on(RCU_HXTAL);
```

rcu_osci_off

The description of rcu_osci_off is shown as below:

Table 3-272. Function rcu_osci_off

Function name	rcu_osci_off
Function prototype	void rcu_osci_off(rcu_osci_type_enum osci);
Function descriptions	turn off the oscillator
Precondition	-
The called functions	-
Input parameter{in}	
osci	oscillator types, refer to rcu_osci_type_enum
<i>RCU_HXTAL</i>	high speed crystal oscillator(HXTAL)
<i>RCU_LXTAL</i>	low speed crystal oscillator(LXTAL)
<i>RCU_IRC8M</i>	internal 8M RC oscillators(IRC8M)
<i>RCU_IRC28M</i>	internal 28M RC oscillators(IRC48M)

<i>RCU_IRC40K</i>	internal 40K RC oscillator(IRC40K)
<i>RCU_PLL_CK</i>	phase locked loop(PLL)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* turn off the high speed crystal oscillator */
```

```
rcu_osci_off(RCU_HXTAL);
```

rcu_osci_bypass_mode_enable

The description of `rcu_osci_bypass_mode_enable` is shown as below:

Table 3-273. Function `rcu_osci_bypass_mode_enable`

Function name	<code>rcu_osci_bypass_mode_enable</code>
Function prototype	<code>void rcu_osci_bypass_mode_enable(rcu_osci_type_enum osci);</code>
Function descriptions	enable the oscillator bypass mode
Precondition	HXTALEN or LXTALEN must be reset before it
The called functions	-
Input parameter{in}	
osci	oscillator types, refer to <code>rcu_osci_type_enum</code>
<i>RCU_HXTAL</i>	high speed crystal oscillator(HXTAL)
<i>RCU_LXTAL</i>	low speed crystal oscillator(LXTAL)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the high speed crystal oscillator bypass mode */
```

```
rcu_osci_bypass_mode_enable(RCU_HXTAL);
```

rcu_osci_bypass_mode_disable

The description of rcu_osci_bypass_mode_disable is shown as below:

Table 3-274. Function rcu_osci_bypass_mode_disable

Function name	rcu_osci_bypass_mode_disable
Function prototype	void rcu_osci_bypass_mode_disable(rcu_osci_type_enum osci);
Function descriptions	disable the oscillator bypass mode
Precondition	HXTALEN or LXTALEN must be reset before it
The called functions	-
Input parameter{in}	
osci	oscillator types, refer to rcu_osci_type_enum
<i>RCU_HXTAL</i>	high speed crystal oscillator(HXTAL)
<i>RCU_LXTAL</i>	low speed crystal oscillator(LXTAL)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the high speed crystal oscillator bypass mode */
rcu_osci_bypass_mode_disable(RCU_HXTAL);
```

rcu_hxtal_clock_monitor_enable

The description of rcu_hxtal_clock_monitor_enable is shown as below:

Table 3-275. Function rcu_hxtal_clock_monitor_enable

Function name	rcu_hxtal_clock_monitor_enable
Function prototype	void rcu_hxtal_clock_monitor_enable(void);
Function descriptions	enable the HXTAL clock monitor
Precondition	-
The called functions	-
Input parameter{in}	

-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the HXTAL clock monitor */
rcu_hxtal_clock_monitor_enable();
```

rcu_hxtal_clock_monitor_disable

The description of rcu_hxtal_clock_monitor_disable is shown as below:

Table 3-276. Function rcu_hxtal_clock_monitor_disable

Function name	rcu_hxtal_clock_monitor_disable
Function prototype	void rcu_hxtal_clock_monitor_disable(void);
Function descriptions	disable the HXTAL clock monitor
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the HXTAL clock monitor */
rcu_hxtal_clock_monitor_disable();
```

rcu_irc8m_adjust_value_set

The description of rcu_irc8m_adjust_value_set is shown as below:

Table 3-277. Function rcu_irc8m_adjust_value_set

Function name	rcu_irc8m_adjust_value_set
Function prototype	void rcu_irc8m_adjust_value_set(uint32_t irc8m_adjval);
Function descriptions	set the IRC8M adjust value
Precondition	-
The called functions	-
Input parameter{in}	
irc8m_adjval	IRC8M adjust value, must be between 0 and 0x1F
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set the IRC8M adjust value */
rcu_irc8m_adjust_value_set(0x10);
```

rcu_irc28m_adjust_value_set

The description of rcu_irc28m_adjust_value_set is shown as below:

Table 3-278. Function rcu_irc28m_adjust_value_set

Function name	rcu_irc28m_adjust_value_set
Function prototype	void rcu_irc28m_adjust_value_set(uint32_t irc28m_adjval);
Function descriptions	set the IRC28M adjust value
Precondition	-
The called functions	-
Input parameter{in}	
irc28m_adjval	IRC28M adjust value, must be between 0 and 0x1F
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* set the IRC28M adjust value */
rcu_irc28m_adjust_value_set(0x10);
```

rcu_voltage_key_unlock

The description of rcu_voltage_key_unlock is shown as below:

Table 3-279. Function rcu_voltage_key_unlock

Function name	rcu_voltage_key_unlock
Function prototype	void rcu_voltage_key_unlock (void);
Function descriptions	unlock the voltage key
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* unlock the voltage key */
rcu_voltage_key_unlock();
```

rcu_deepsleep_voltage_set

The description of rcu_deepsleep_voltage_set is shown as below:

Table 3-280. Function rcu_deepsleep_voltage_set

Function name	rcu_deepsleep_voltage_set
Function prototype	void rcu_deepsleep_voltage_set(uint32_t dsvol);
Function descriptions	set voltage in deep sleep mode
Precondition	-

The called functions	-
Input parameter{in}	
dsvol	deep sleep mode voltage
<i>RCU_DEEPSLEEP_V_1_0</i>	the core voltage is 1.0V in deep-sleep mode
<i>RCU_DEEPSLEEP_V_0_9</i>	the core voltage is 0.9V in deep-sleep mode
<i>RCU_DEEPSLEEP_V_0_8</i>	the core voltage is 0.8V in deep-sleep mode
<i>RCU_DEEPSLEEP_V_1_2</i>	the core voltage is 1.2V in deep-sleep mode
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set the deep-sleep mode voltage */
```

```
rcu_deepsleep_voltage_set(RCU_DEEPSLEEP_V_1_0);
```

rcu_clock_freq_get

The description of `rcu_clock_freq_get` is shown as below:

Table 3-281. Function `rcu_clock_freq_get`

Function name	<code>rcu_clock_freq_get</code>
Function prototype	<code>uint32_t rcu_clock_freq_get(rcu_clock_freq_enum clock);</code>
Function descriptions	get the system clock, bus clock and peripheral clock frequency
Precondition	-
The called functions	-
Input parameter{in}	
clock	the clock frequency which to get
<i>CK_SYS</i>	system clock frequency

<i>CK_AHB</i>	AHB clock frequency
<i>CK_APB1</i>	APB1 clock frequency
<i>CK_APB2</i>	APB2 clock frequency
<i>CK_ADC</i>	ADC clock frequency
<i>CK_USART</i>	USART0 clock frequency
Output parameter{out}	
-	-
Return value	
uint32_t	clock frequency of system, AHB, APB1, APB2,ADC or USART0

Example:

```
uint32_t temp_freq;

/* get the system clock frequency */

temp_freq = rcu_clock_freq_get(CK_SYS);
```

3.15. RTC

The Real-time Clock (RTC) is usually used as a clock-calendar. The ones in the Backup Domain consist of a 32-bit up-counter, an alarm, a prescaler, a divider and the RTC clock configuration register. The RTC registers are listed in chapter [3.15.1](#), the FWDGT firmware functions are introduced in chapter [3.15.2](#).

3.15.1. Descriptions of Peripheral registers

RTC registers are listed in the table shown as below:

Table 3-282. RTC Registers

Registers	Descriptions
RTC_TIME	RTC time of day register
RTC_DATE	RTC date register
RTC_CTL	RTC control register
RTC_STAT	RTC status register
RTC_PSC	RTC time prescaler register
RTC_ALRM0TD	RTC alarm 0 time and date register

Registers	Descriptions
RTC_WPK	RTC write protection key register
RTC_SS	RTC sub second register
RTC_SHIFTCTL	RTC shift function control register
RTC_TTS	RTC time of timestamp register
RTC_DTS	RTC date of timestamp register
RTC_SSTS	RTC sub second of timestamp register
RTC_HRFC	RTC high resolution frequency compensation register
RTC_TAMP	RTC tamper register
RTC_ALRM0SS	RTC alarm 0 sub second register
RTC_BKP0	RTC backup 0 register
RTC_BKP1	RTC backup 1 register
RTC_BKP2	RTC backup 2 register
RTC_BKP3	RTC backup 3 register
RTC_BKP4	RTC backup 4 register

3.15.2. Descriptions of Peripheral functions

RTC firmware functions are listed in the table shown as below:

Table 3-283.RTC firmware function

Function name	Function description
rtc_deinit	reset most of the RTC registers
rtc_init	initialize RTC registers
rtc_init_mode_enter	enter RTC init mode
rtc_init_mode_exit	exit RTC init mode
rtc_register_sync_wait	wait until RTC_TIME and RTC_DATE registers are synchronized with APB clock, and the shadow registers are updated
rtc_current_time_get	get current time and date
rtc_subsecond_get	get current subsecond value

Function name	Function description
rtc_alarm_config	configure RTC alarm
rtc_alarm_subsecond_config	configure subsecond of RTC alarm
rtc_alarm_get	get RTC alarm
rtc_alarm_subsecond_get	get RTC alarm subsecond
rtc_alarm_enable	enable RTC alarm
rtc_alarm_disable	disable RTC alarm
rtc_timestamp_enable	enable RTC time-stamp
rtc_timestamp_disable	disable RTC time-stamp
rtc_timestamp_get	get RTC timestamp time and date
rtc_timestamp_subsecond_get	get RTC time-stamp subsecond
rtc_tamper_enable	enable RTC tamper
rtc_tamper_disable	disable RTC tamper
rtc_interrupt_enable	enable specified RTC interrupt
rtc_interrupt_disable	disable specified RTC interrupt
rtc_flag_get	check specified flag
rtc_flag_clear	clear specified flag
rtc_alter_output_config	configure RTC alternate output source
rtc_calibration_config	configure RTC calibration register
rtc_hour_adjust	adjust the daylight saving time by adding or subtracting one hour from the current time
rtc_second_adjust	adjust RTC second or subsecond value of current time
rtc_bypass_shadow_enable	enable RTC bypass shadow registers function
rtc_bypass_shadow_disable	disable RTC bypass shadow registers function
rtc_refclock_detection_enable	enable RTC reference clock detection function
rtc_refclock_detection_disable	disable RTC reference clock detection function

Structure `rtc_parameter_struct`

Table 3-284. `rtc_parameter_struct`

Member name	Function description
<code>rtc_year</code>	RTC year value: 0x0 - 0x99(BCD format)
<code>rtc_month</code>	RTC month value
<code>rtc_date</code>	RTC date value: 0x1 - 0x31(BCD format)
<code>rtc_day_of_week</code>	RTC weekday value
<code>rtc_hour</code>	RTC hour value
<code>rtc_minute</code>	RTC minute value: 0x0 - 0x59(BCD format)
<code>rtc_second</code>	RTC second value: 0x0 - 0x59(BCD format)
<code>rtc_factor_asyn</code>	RTC asynchronous prescaler value: 0x0 - 0x7F
<code>rtc_factor_syn</code>	RTC synchronous prescaler value: 0x0 - 0x7FFF
<code>rtc_am_pm</code>	RTC AM/PM value
<code>rtc_display_format</code>	RTC time notation

Structure `rtc_alarm_struct`

Table 3-285. `rtc_alarm_struct`

Member name	Function description
<code>rtc_alarm_mask</code>	RTC alarm mask
<code>rtc_weekday_or_date</code>	specify RTC alarm is on date or weekday
<code>rtc_alarm_day</code>	RTC alarm date or weekday value
<code>rtc_alarm_hour</code>	RTC alarm hour value
<code>rtc_alarm_minute</code>	RTC alarm minute value: 0x0 - 0x59(BCD format)
<code>rtc_alarm_second</code>	RTC alarm second value: 0x0 - 0x59(BCD format)
<code>rtc_am_pm</code>	RTC alarm AM/PM value

Structure `rtc_timestamp_struct`

Table 3-286. `rtc_timestamp_struct`

Member name	Function description
-------------	----------------------

rtc_timestamp_month	RTC time-stamp month value
rtc_timestamp_date	RTC time-stamp date value: 0x1 - 0x31(BCD format)
rtc_timestamp_day	RTC time-stamp weekday value
rtc_timestamp_hour	RTC time-stamp hour value
rtc_timestamp_minute	RTC time-stamp minute value: 0x0 - 0x59(BCD format)
rtc_timestamp_second	RTC time-stamp second value: 0x0 - 0x59(BCD format)
rtc_am_pm	RTC time-stamp AM/PM value

Structure `rtc_tamper_struct`

Table 3-287. `rtc_tamper_struct`

Member name	Function description
rtc_tamper_source	RTC tamper source
rtc_tamper_trigger	RTC tamper trigger
rtc_tamper_filter	RTC tamper consecutive samples needed during a voltage level detection
rtc_tamper_sample_frequency	RTC tamper sampling frequency during a voltage level detection
rtc_tamper_precharge_enable	RTC tamper precharge feature during a voltage level detection
rtc_tamper_precharge_time	RTC tamper precharge duration if precharge feature is enabled
rtc_tamper_with_timestamp	RTC tamper time-stamp feature

`rtc_deinit`

The description of `rtc_deinit` is shown as below:

Table 3-288. Function `rtc_deinit`

Function name	<code>rtc_deinit</code>
Function prototype	<code>ErrStatus rtc_deinit(void);</code>
Function descriptions	reset most of the RTC registers

Precondition	-
The called functions	rcu_periph_reset_enable/ rcu_periph_reset_disable -
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
ErrStatus	ERROR or SUCCESS

Example:

```
/* reset most of the RTC registers*/
```

```
ErrStatus error_status = rtc_deinit();
```

rtc_init

The description of rtc_init is shown as below:

Table 3-289. Function rtc_init

Function name	rtc_init
Function prototype	ErrStatus rtc_init(rtc_parameter_struct* rtc_initpara_struct);
Function descriptions	initialize RTC registers
Precondition	-
The called functions	-
Input parameter{in}	
rtc_initpara_struct	pointer to a rtc_parameter_struct structure which contains parameters for initialization of the rtc peripheral, the structure members can refer to members of the structure Table 3-284. rtc_parameter_struct
Output parameter{out}	
-	-
Return value	
ErrStatus	ERROR or SUCCESS

Example:

```
/* reset most of the RTC registers*/
```



```
ErrStatus error_status = rtc_init ();
```

rtc_init_mode_enter

The description of rtc_init_mode_enter is shown as below:

Table 3-290. Function rtc_init_mode_enter

Function name	rtc_init_mode_enter
Function prototype	ErrStatus rtc_init_mode_enter(void);
Function descriptions	enter RTC init mode
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
ErrStatus	ERROR or SUCCESS

Example:

```
/*enter RTC init mode*/
```

```
ErrStatus error_status = rtc_init_mode_enter ();
```

rtc_init_mode_exit

The description of rtc_init_mode_exit is shown as below:

Table 3-291. Function rtc_init_mode_exit

Function name	rtc_init_mode_exit
Function prototype	void rtc_init_mode_exit(void);
Function descriptions	exit RTC init mode
Precondition	-
The called functions	-
Input parameter{in}	
-	-

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/*exit RTC init mode*/
```

```
rtc_init_mode_exit ();
```

rtc_register_sync_wait

The description of rtc_register_sync_wait is shown as below:

Table 3-292. Function rtc_register_sync_wait

Function name	rtc_register_sync_wait
Function prototype	ErrStatus rtc_register_sync_wait(void);
Function descriptions	wait until RTC_TIME and RTC_DATE registers are synchronized with APB clock, and the shadow registers are updated
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
ErrStatus	ERROR or SUCCESS

Example:

```
/*wait until RTC_TIME and RTC_DATE registers are synchronized with APB clock, and the shadow registers are updated*/
```

```
ErrStatus error_status = rtc_register_sync_wait ();
```

rtc_current_time_get

The description of rtc_current_time_get is shown as below:

Table 3-293. Function `rtc_current_time_get`

Function name	<code>rtc_current_time_get</code>
Function prototype	<code>void rtc_current_time_get(rtc_parameter_struct* rtc_initpara_struct);</code>
Function descriptions	get current time and date
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
rtc_initpara_struct	pointer to a <code>rtc_parameter_struct</code> structure which contains parameters for initialization of the rtc peripheral, the structure members can refer to members of the structure Table 3-284. rtc_parameter_struct
Return value	
-	-

Example:

```

/*get current time and date*/
rtc_parameter_struct rtc_initpara_struct;
rtc_current_time_get (&rtc_initpara_struct);

```

rtc_subsecond_get

The description of `rtc_subsecond_get` is shown as below:

Table 3-294. Function `rtc_subsecond_get`

Function name	<code>rtc_subsecond_get</code>
Function prototype	<code>uint32_t rtc_subsecond_get(void);</code>
Function descriptions	get current subsecond value
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	

-	-
Return value	
uint32_t	current subsecond value(0x00-0xFFFF)

Example:

```
/*get current subsecond value*/
```

```
uint32_t sub_second = rtc_subsecond_get();
```

rtc_alarm_config

The description of `rtc_alarm_config` is shown as below:

Table 3-295. Function `rtc_alarm_config`

Function name	<code>rtc_alarm_config</code>
Function prototype	<code>void rtc_alarm_config(rtc_alarm_struct* rtc_alarm_time)</code>
Function descriptions	configure RTC alarm
Precondition	-
The called functions	-
Input parameter{in}	
rtc_alarm_time	pointer to a <code>rtc_alarm_struct</code> structure which contains parameters for RTC alarm configuration, the structure members can refer to members of the structure Table 3-285. rtc_alarm_struct
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/*rtc_alarm_config*/
```

```
rtc_alarm_struct rtc_alarm_time;
```

```
rtc_alarm_config(&rtc_alarm_time);
```

rtc_alarm_subsecond_config

The description of `rtc_alarm_subsecond_config` is shown as below:

Table 3-296. Function `rtc_alarm_subsecond_config`

Function name	<code>rtc_alarm_subsecond_config</code>
Function prototype	<code>void rtc_alarm_subsecond_config(uint32_t mask_subsecond, uint32_t subsecond);</code>
Function descriptions	configure subsecond of RTC alarm
Precondition	-
The called functions	-
Input parameter{in}	
mask_subsecond	alarm subsecond mask
<i>RTC_MASKSSC_0_14</i>	mask alarm subsecond configuration
<i>RTC_MASKSSC_1_14</i>	mask <code>RTC_ALRM0SS_SSC[14:1]</code> , and <code>RTC_ALRM0SS_SSC[0]</code> is to be compared
<i>RTC_MASKSSC_2_14</i>	mask <code>RTC_ALRM0SS_SSC[14:2]</code> , and <code>RTC_ALRM0SS_SSC[1:0]</code> is to be compared
<i>RTC_MASKSSC_3_14</i>	mask <code>RTC_ALRM0SS_SSC[14:3]</code> , and <code>RTC_ALRM0SS_SSC[2:0]</code> is to be compared
<i>RTC_MASKSSC_4_14</i>	mask <code>RTC_ALRM0SS_SSC[14:4]</code> , and <code>RTC_ALRM0SS_SSC[3:0]</code> is to be compared
<i>RTC_MASKSSC_5_14</i>	mask <code>RTC_ALRM0SS_SSC[14:5]</code> , and <code>RTC_ALRM0SS_SSC[4:0]</code> is to be compared
<i>RTC_MASKSSC_6_14</i>	mask <code>RTC_ALRM0SS_SSC[14:6]</code> , and <code>RTC_ALRM0SS_SSC[5:0]</code> is to be compared
<i>RTC_MASKSSC_7_14</i>	mask <code>RTC_ALRM0SS_SSC[14:7]</code> , and <code>RTC_ALRM0SS_SSC[6:0]</code> is to be compared
<i>RTC_MASKSSC_8_14</i>	mask <code>RTC_ALRM0SS_SSC[14:8]</code> , and <code>RTC_ALRM0SS_SSC[7:0]</code> is to be compared
<i>RTC_MASKSSC_9_14</i>	mask <code>RTC_ALRM0SS_SSC[14:9]</code> , and <code>RTC_ALRM0SS_SSC[8:0]</code> is to be compared
<i>RTC_MASKSSC_10_14</i>	mask <code>RTC_ALRM0SS_SSC[14:10]</code> , and <code>RTC_ALRM0SS_SSC[9:0]</code> is to be compared
<i>RTC_MASKSSC_11_14</i>	mask <code>RTC_ALRM0SS_SSC[14:11]</code> , and <code>RTC_ALRM0SS_SSC[10:0]</code> is to be compared
<i>RTC_MASKSSC_12_14</i>	mask <code>RTC_ALRM0SS_SSC[14:12]</code> , and <code>RTC_ALRM0SS_SSC[11:0]</code> is to be compared

4	be compared
RTC_MASKSSC_13_1 4	mask RTC_ALARM0SS_SSC[14:13], and RTC_ALARM0SS_SSC[12:0] is to be compared
RTC_MASKSSC_14	mask RTC_ALARM0SS_SSC[14], and RTC_ALARM0SS_SSC[13:0] is to be compared
RTC_MASKSSC_NON E	mask none, and RTC_ALARM0SS_SSC[14:0] is to be compared
Input parameter{in}	
subsecond	alarm subsecond value(0x000 - 0x7FFF)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/*configure subsecond of RTC alarm*/
```

```
rtc_subsecond_config (RTC_MASKSSC_9_14, 0x7FFF);
```

rtc_alarm_enable

The description of rtc_alarm_enable is shown as below:

Table 3-297. Function rtc_alarm_enable

Function name	rtc_alarm_enable
Function prototype	void rtc_alarm_enable(void);
Function descriptions	enable RTC alarm
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/*enable RTC alarm*/
```

```
rtc_alarm_enable();
```

rtc_alarm_disable

The description of rtc_alarm_disable is shown as below:

Table 3-298. Function rtc_alarm_disable

Function name	rtc_alarm_disable
Function prototype	ErrStatus rtc_alarm_disable(void);
Function descriptions	disable RTC alarm
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
ErrStatus	ERROR or SUCCESS

Example:

```
/*disable RTC alarm*/
```

```
ErrStatus error_status = rtc_alarm_disable();
```

rtc_alarm_get

The description of rtc_alarm_get is shown as below:

Table 3-299. Function rtc_alarm_get

Function name	rtc_alarm_get
Function prototype	void rtc_alarm_get(rtc_alarm_struct* rtc_alarm_time);
Function descriptions	get RTC alarm
Precondition	-

The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
rtc_alarm_time	pointer to a rtc_alarm_struct structure which contains parameters for RTC alarm configuration, the structure members can refer to members of the structure Table 3-285. rtc_alarm_struct
Return value	
-	-

Example:

```
/*disable RTC alarm*/
rtc_alarm_struct rtc_alarm_time;
rtc_alarm_get (&rtc_alarm_time);
```

rtc_alarm_subsecond_get

The description of rtc_alarm_subsecond_get is shown as below:

Table 3-300. Function rtc_alarm_subsecond_get

Function name	rtc_alarm_subsecond_get
Function prototype	uint32_t rtc_alarm_subsecond_get(void);
Function descriptions	get RTC alarm subsecond
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
uint32_t	RTC alarm subsecond value(0x0-0x3FFF)

Example:

```
/*get RTC alarm subsecond*/
```



```
uint32_t subsecond = rtc_alarm_subsecond_get();
```

rtc_timestamp_enable

The description of `rtc_timestamp_enable` is shown as below:

Table 3-301. Function `rtc_timestamp_enable`

Function name	<code>rtc_timestamp_enable</code>
Function prototype	<code>void rtc_timestamp_enable(uint32_t edge);</code>
Function descriptions	enable RTC time-stamp
Precondition	-
The called functions	-
Input parameter{in}	
edge	specify which edge to detect of time-stamp
<code>RTC_TIMESTAMP_RISING_EDGE</code>	rising edge is valid event edge for timestamp event
<code>RTC_TIMESTAMP_FALLING_EDGE</code>	falling edge is valid event edge for timestamp event
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/*enable RTC time-stamp*/
rtc_timestamp_enable (RTC_TIMESTAMP_RISING_EDGE);
```

rtc_timestamp_disable

The description of `rtc_timestamp_disable` is shown as below:

Table 3-302. Function `rtc_timestamp_disable`

Function name	<code>rtc_timestamp_disable</code>
Function prototype	<code>void rtc_timestamp_disable(void);</code>
Function descriptions	disable RTC time-stamp
Precondition	-

The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/*disable RTC time-stamp*/
rtc_timestamp_disable ();
```

rtc_timestamp_get

The description of `rtc_timestamp_get` is shown as below:

Table 3-303. Function `rtc_timestamp_get`

Function name	<code>rtc_timestamp_get</code>
Function prototype	<code>void rtc_timestamp_get(rtc_timestamp_struct* rtc_timestamp);</code>
Function descriptions	get RTC timestamp time and date
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
<code>rtc_timestamp</code>	Pointer to a <code>rtc_timestamp_struct</code> structure which contains parameters for RTC time-stamp configuration, the structure members can refer to members of the structure Table 3-287. <code>rtc_tamper_struct</code>
Return value	
-	-

Example:

```
/* get RTC timestamp time and date */
rtc_timestamp_struct rtc_timestamp;
```

```
rtc_timestamp_get(& rtc_timestamp);
```

rtc_timestamp_subsecond_get

The description of `rtc_timestamp_subsecond_get` is shown as below:

Table 3-304. Function `rtc_timestamp_subsecond_get`

Function name	<code>rtc_timestamp_subsecond_get</code>
Function prototype	<code>uint32_t rtc_timestamp_subsecond_get(void);</code>
Function descriptions	get RTC time-stamp subsecond
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
<code>uint32_t</code>	RTC time-stamp subsecond value

Example:

```
/* get RTC time-stamp subsecond */
```

```
uint32_t subsecond = rtc_timestamp_subsecond_get();
```

rtc_tamper_enable

The description of `rtc_tamper_enable` is shown as below:

Table 3-305. Function `rtc_tamper_enable`

Function name	<code>rtc_tamper_enable</code>
Function prototype	<code>void rtc_tamper_enable(rtc_tamper_struct* rtc_tamper);</code>
Function descriptions	enable RTC tamper
Precondition	-
The called functions	-
Input parameter{in}	
<code>rtc_tamper</code>	pointer to a <code>rtc_tamper_struct</code> structure which contains

	parameters for RTC tamper configuration, the structure members can refer to members of the structure Table 3-287. rtc_tamper_struct
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* enable RTC tamper */
rtc_tamper_struct rtc_tamper
rtc_tamper_enable(& rtc_tamper);

```

rtc_tamper_disable

The description of rtc_tamper_disable is shown as below:

Table 3-306. Function rtc_tamper_disable

Function name	rtc_tamper_disable
Function prototype	void rtc_tamper_disable(uint32_t source);
Function descriptions	disable RTC tamper
Precondition	-
The called functions	-
Input parameter{in}	
source	specify which tamper source to be disabled
<i>RTC_TAMPER0</i>	RTC tamper0
<i>RTC_TAMPER1</i>	RTC tamper1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* disable RTC tamper */
rtc_tamper_disable(RTC_TAMPER0);

```

rtc_interrupt_enable

The description of `rtc_interrupt_enable` is shown as below:

Table 3-307. Function `rtc_interrupt_enable`

Function name	<code>rtc_interrupt_enable</code>
Function prototype	<code>void rtc_interrupt_enable(uint32_t interrupt);</code>
Function descriptions	enable specified RTC interrupt
Precondition	-
The called functions	-
Input parameter{in}	
interrupt	specify which interrupt source to be enabled
<code>RTC_INT_TIMESTAMP</code>	timestamp interrupt
<code>RTC_INT_ALARM</code>	alarm interrupt
<code>RTC_INT_TAMP</code>	tamp interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable specified RTC interrupt*/
rtc_interrupt_enable(RTC_INT_TAMP);
```

rtc_interrupt_disable

The description of `rtc_interrupt_disable` is shown as below:

Table 3-308. Function `rtc_interrupt_disable`

Function name	<code>rtc_interrupt_disable</code>
Function prototype	<code>void rtc_interrupt_disable(uint32_t interrupt);</code>
Function descriptions	disble specified RTC interrupt
Precondition	-
The called functions	-

Input parameter{in}	
interrupt	specify which RTC interrupt to disable
<i>RTC_INT_TIMESTAMP</i>	second interrupt
<i>RTC_INT_ALARM</i>	alarm interrupt
<i>RTC_INT_TAMP</i>	tamp interrupt
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable specified RTC interrupt */
rtc_interrupt_disable(RTC_INT_TAMP);
```

rtc_flag_get

The description of `rtc_flag_get` is shown as below:

Table 3-309. Function `rtc_flag_get`

Function name	<code>rtc_flag_get</code>
Function prototype	<code>FlagStatus rtc_flag_get(uint32_t flag);</code>
Function descriptions	check specified flag
Precondition	-
The called functions	-
Input parameter{in}	
flag	specify which flag to check
<i>RTC_FLAG_RECALI_B RATION</i>	recalibration pending flag
<i>RTC_FLAG_TAMP1</i>	tamper 1 event flag
<i>RTC_FLAG_TAMP0</i>	tamper 0 event flag
<i>RTC_FLAG_TIMESTA MP_OVERFLOW</i>	time-stamp overflow event flag
<i>RTC_FLAG_TIMESTA</i>	time-stamp event flag

<i>MP</i>	
<i>RTC_FLAG_ALARM0</i>	alarm event flag
<i>RTC_FLAG_INIT</i>	init mode event flag
<i>RTC_FLAG_RSYN</i>	time and date registers synchronized event flag
<i>RTC_FLAG_YCM</i>	year parameter configured event flag
<i>RTC_FLAG_SHIFT</i>	shift operation pending flag
<i>RTC_FLAG_ALARM0_WRITTEN</i>	alarm written available flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* check time-stamp event flag */
```

```
FlagStatus = rtc_flag_get(RTC_FLAG_TIMESTAMP)
```

rtc_flag_clear

The description of `rtc_flag_clear` is shown as below:

Table 3-310. Function `rtc_flag_clear`

Function name	<code>rtc_flag_clear</code>
Function prototype	<code>void rtc_flag_clear(uint32_t flag);</code>
Function descriptions	clear specified flag
Precondition	-
The called functions	-
Input parameter{in}	
flag	specify which flag to clear
<i>RTC_FLAG_TAMP1</i>	tamper 1 event flag
<i>RTC_FLAG_TAMP0</i>	tamper 0 event flag
<i>RTC_FLAG_TIMESTAMP_OVERFLOW</i>	time-stamp overflow event flag

<i>RTC_FLAG_TIMESTAMP</i>	time-stamp event flag
<i>RTC_FLAG_ALARM0</i>	alarm event flag
<i>RTC_FLAG_RSYN</i>	time and date registers synchronized event flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* cleartime-stamp event flag */
```

```
rtc_flag_clear (RTC_FLAG_TIMESTAMP);
```

rtc_alter_output_config

The description of `rtc_alter_output_config` is shown as below:

Table 3-311. Function `rtc_alter_output_config`

Function name	<code>rtc_alter_output_config</code>
Function prototype	<code>void rtc_alter_output_config(uint32_t source, uint32_t mode);</code>
Function descriptions	configure rtc alternate output source
Precondition	-
The called functions	-
Input parameter{in}	
source	specify signal to output
<i>RTC_CALIBRATION_5</i> <i>12HZ</i>	when the LSE frequency is 32768Hz and the <code>RTC_PSC</code> is the default value, output 512Hz signal
<i>RTC_CALIBRATION_1</i> <i>HZ</i>	when the LSE frequency is 32768Hz and the <code>RTC_PSC</code> is the default value, output 1Hz signal
<i>RTC_ALARM_HIGH</i>	when the alarm flag is set, the output pin is high
<i>RTC_ALARM_LOW</i>	when the Alarm flag is set, the output pin is low
Input parameter{in}	
mode	specify the output pin (PC13) mode when output alarm signal

<i>RTC_ALARM_OUTPU</i> <i>T_OD</i>	open drain mode
<i>RTC_ALARM_OUTPU</i> <i>T_PP</i>	push pull mode
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* configure rtc alternate output source */
rtc_alter_output_config(RTC_ALARM_LOW, RTC_ALARM_OUTPUT_PP);

```

rtc_calibration_config

The description of `rtc_calibration_config` is shown as below:

Table 3-312. rtc_calibration_config

Function name	<code>rtc_calibration_config</code>
Function prototype	<code>ErrStatus rtc_calibration_config(uint32_t window, uint32_t plus, uint32_t minus);</code>
Function descriptions	configure RTC calibration register
Precondition	-
The called functions	-
Input parameter{in}	
window	select calibration window
<i>RTC_CALIBRATION_WINDOW_32S</i>	2exp20 RTCCLK cycles, 32s if RTCCLK = 32768 Hz
<i>RTC_CALIBRATION_WINDOW_16S</i>	2exp19 RTCCLK cycles, 16s if RTCCLK = 32768 Hz
<i>RTC_CALIBRATION_WINDOW_8S</i>	2exp18 RTCCLK cycles, 8s if RTCCLK = 32768 Hz
Input parameter{in}	
plus	add RTC clock or not

<i>RTC_CALIBRATION_PLUS_SET</i>	add one RTC clock every 2048 rtc clock
<i>RTC_CALIBRATION_PLUS_RESET</i>	no effect
Input parameter{in}	
minus	the RTC clock to minus during the calibration window(0x0 - 0x1FF)
Output parameter{out}	
-	-
Return value	
ErrStatus	ERROR or SUCCESS

Example:

```
/* configure RTC calibration register*/
```

```
ErrStatus error_status = rtc_calibration_config(RTC_CALIBRATION_WINDOW_32S,
RTC_CALIBRATION_PLUS_SET, 0x1FF);
```

rtc_hour_adjust

The description of `rtc_hour_adjust` is shown as below:

Table 3-313. rtc_hour_adjust

Function name	<code>rtc_hour_adjust</code>
Function prototype	<code>void rtc_hour_adjust(uint32_t operation);</code>
Function descriptions	adjust the daylight saving time by adding or subtracting one hour from the current time
Precondition	-
The called functions	-
Input parameter{in}	
operation	hour adjustment operation
<i>RTC_CTL_A1H</i>	add one hour
<i>RTC_CTL_S1H</i>	subtract one hour
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* adjust the daylight saving time by adding one hour from the current time */
```

```
rtc_hour_adjust(RTC_CTL_A1H);
```

rtc_second_adjust

The description of `rtc_second_adjust` is shown as below:

Table 3-314. rtc_second_adjust

Function name	rtc_second_adjust
Function prototype	ErrStatus rtc_second_adjust(uint32_t add, uint32_t minus);
Function descriptions	adjust RTC second or subsecond value of current time
Precondition	-
The called functions	-
Input parameter{in}	
add	add 1s to current time or not
<i>RTC_SHIFT_ADD1S_R ESET</i>	no effect
<i>RTC_SHIFT_ADD1S_S ET</i>	add 1s to current time
Input parameter{in}	
minus	number of subsecond to minus from current time(0x0 - 0x7FFF)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* adjust RTC second or subsecond value of current time */
```

```
ErrStatus error_status = rtc_second_adjust(RTC_SHIFT_ADD1S_SET, 0);
```

rtc_bypass_shadow_enable

The description of `rtc_bypass_shadow_enable` is shown as below:

Table 3-315. rtc_bypass_shadow_enable

Function name	rtc_bypass_shadow_enable
Function prototype	void rtc_bypass_shadow_enable(void);
Function descriptions	enable RTC bypass shadow registers function
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable RTC bypass shadow registers function*/
rtc_bypass_shadow_enable();
```

rtc_bypass_shadow_disable

The description of `rtc_bypass_shadow_disable` is shown as below:

Table 3-316. rtc_bypass_shadow_disable

Function name	rtc_bypass_shadow_disable
Function prototype	void rtc_bypass_shadow_disable (void);
Function descriptions	disable RTC bypass shadow registers function
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* disable RTC bypass shadow registers function*/
```

```
rtc_bypass_shadow_disable ();
```

rtc_refclock_detection_enable

The description of `rtc_refclock_detection_enable` shown as below:

Table 3-317. rtc_refclock_detection_enable

Function name	rtc_refclock_detection_enable
Function prototype	ErrStatus rtc_refclock_detection_enable(void);
Function descriptions	enable RTC reference clock detection function
Precondition	-
The called functions	rtc_init_mode_enter/rtc_init_mode_exit
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
ErrStatus	ERROR or SUCCESS

Example:

```
/* enable RTC reference clock detection function*/
```

```
ErrStatus error_status = rtc_refclock_detection_enable();
```

rtc_refclock_detection_disable

The description of `rtc_refclock_detection_disable` shown as below:

Table 3-318. rtc_refclock_detection_disable

Function name	rtc_refclock_detection_disable
Function prototype	ErrStatus rtc_refclock_detection_disable(void);

Function descriptions	disable RTC reference clock detection function
Precondition	-
The called functions	rtc_init_mode_enter/rtc_init_mode_exit
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
ErrStatus	ERROR or SUCCESS

Example:

```
/* disableRTC reference clock detection function*/
```

```
ErrStatus error_status = rtc_refclock_detection_disable ();
```

3.16. SPI

The SPI/I2S module can communicate with external devices using the SPI protocol or the I2S audio protocol. The SPI/I2S registers are listed in chapter [3.16.1](#), the SPI/I2S firmware functions are introduced in chapter [3.16.2](#).

3.16.1. Descriptions of Peripheral registers

SPI/I2S registers are listed in the table shown as below:

Table 3-319. SPI/I2S registers

Registers	Descriptions
SPI_CTL0	SPI control register 0
SPI_CTL1	SPI control register 1
SPI_STAT	SPI status register
SPI_DATA	SPI data register
SPI_CRCPOLY	SPI CRC polynomial register
SPI_RCRC	SPI receive CRC register
SPI_TCRC	SPI transmit CRC register

Registers	Descriptions
SPI_I2SCTL	SPI/I2S control register
SPI_I2SPSC	SPI/I2S clock prescaler register
SPI_QCTL	SPI quad mode control register

3.16.2. Descriptions of Peripheral functions

SPI/I2S firmware functions are listed in the table shown as below:

Table 3-320. SPI/I2S firmware function

Function name	Function description
spi_i2s_deinit	reset SPI and I2S peripheral
spi_struct_para_init	initialize the parameters of SPI struct with the default values
spi_init	initialize SPI peripheral parameter
spi_enable	enable SPI
spi_disable	disable SPI
i2s_init	initialize I2S peripheral parameter
i2s_psc_config	configure I2S peripheral prescaler
i2s_enable	enable I2S
i2s_disable	disable I2S
spi_nss_output_enable	enable SPI NSS output function
spi_nss_output_disable	disable SPI NSS output function
spi_nss_internal_high	SPI NSS pin high level in software mode
spi_nss_internal_low	SPI NSS pin low level in software mode
spi_dma_enable	enable SPI DMA function
spi_dma_disable	disable SPI DMA function
spi_i2s_data_frame_format_config	configure SPI/I2S data frame format
spi_i2s_data_transmit	SPI transmit data
spi_i2s_data_receive	SPI receive data
spi_bidirectional_transfer_config	configure SPI bidirectional transfer direction
spi_crc_polynomial_set	set SPI CRC polynomial

Function name	Function description
spi_crc_polynomial_get	get SPI CRC polynomial
spi_crc_on	turn on SPI CRC function
spi_crc_off	turn off SPI CRC function
spi_crc_next	SPI next data is CRC value
spi_crc_get	get SPI CRC send value or receive value
spi_ti_mode_enable	enable SPI TI mode
spi_ti_mode_disable	disable SPI TI mode
spi_nssp_mode_enable	enable SPI NSS pulse mode
spi_nssp_mode_disable	disable SPI NSS pulse mode
qspi_enable	enable quad wire SPI
qspi_disable	disable quad wire SPI
qspi_write_enable	enable quad wire SPI write
qspi_read_enable	enable quad wire SPI read
qspi_io23_output_enable	enable quad wire SPI_IO2 and SPI_IO3 pin output
qspi_io23_output_disable	disable quad wire SPI_IO2 and SPI_IO3 pin output
spi_i2s_interrupt_enable	enable SPI and I2S interrupt
spi_i2s_interrupt_disable	disable SPI and I2S interrupt
spi_i2s_interrupt_flag_get	get SPI and I2S interrupt status
spi_i2s_flag_get	get SPI and I2S flag status
spi_crc_error_clear	clear SPI CRC error flag status
spi_fifo_access_size_config	configure SPI access size to FIFO(8-bit or 16-bit)
spi_transmit_odd_config	configure SPI total number of data transmitting by DMA is odd or not
spi_receive_odd_config	configure SPI total number of data receiving by DMA is odd or not
spi_crc_length_set	set CRC length

Structure spi_parameter_struct

Table 3-321. spi_parameter_struct

Member name	Function description
device_mode	SPI master or slave (SPI_MASTER, SPI_SLAVE)
trans_mode	SPI transtype (SPI_TRANSMODE_FULLDUPLEX, SPI_TRANSMODE_RECEIVEONLY, SPI_TRANSMODE_BDRECEIVE, SPI_TRANSMODE_BDTRANSMIT)
frame_size	SPI frame size (SPI_FRAME_SIZE_xBIT, x=4,5..16)
nss	SPI NSS control by hardware or software (SPI_NSS_SOFT, SPI_NSS_HARD)
endian	SPI big endian or little endian (SPI_ENDIAN_MSB, SPI_ENDIAN_LSB)
clock_polarity_phase	SPI clock phase and polarity (SPI_CK_PL_LOW_PH_1EDGE, SPI_CK_PL_HIGH_PH_1EDGE, SPI_CK_PL_LOW_PH_2EDGE, SPI_CK_PL_HIGH_PH_2EDGE)
prescale	SPI prescale factor (SPI_PSC_n (n=2,4,8,16,32,64,128,256))

spi_i2s_deinit

The description of spi_i2s_deinit is shown as below:

Table 3-322. Function spi_i2s_deinit

Function name	spi_i2s_deinit
Function prototype	void spi_i2s_deinit(uint32_t spi_periph);
Function descriptions	Reset SPIx and I2Sx peripheral
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Input parameter{in}	

spi_periph	SPI/I2S peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset SPI0 */
spi_i2s_deinit(SPI0);
```

spi_struct_para_init

The description of spi_struct_para_init is shown as below:

Table 3-323. Function spi_i2s_deinit

Function name	spi_struct_para_init
Function prototype	void spi_struct_para_init(spi_parameter_struct* spi_struct);
Function descriptions	Initialize the parameters of SPI struct with the default values
Precondition	-
The called functions	-
Input parameter{in}	
spi_struct	SPI init parameter struct, the structure members can refer to Table 3-321. spi_parameter_struct
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* initialize the parameters of SPI */
spi_parameter_struct spi_init_struct;
spi_struct_para_init(&spi_init_struct);
```

spi_init

The description of spi_init is shown as below:

Table 3-324. Function spi_init

Function name	spi_init		
Function prototype	ErrStatus spi_init(uint32_t spi_periph, spi_parameter_struct* spi_struct);		
Function descriptions	Initialize SPIx peripheral parameter		
Precondition	-		
The called functions	-		
Input parameter{in}			
spi_periph	SPI peripheral		
<i>SPIx</i>	x=0,1		
Input parameter{in}			
spi_struct	SPI parameter initialization struct, the structure members can refer to members of the structure parameter_struct		
	Member name	Function	description
	device_mode	SPI master or slave (SPI_MASTER, SPI_SLAVE)	
Output parameter{out}			
-	-		
Return value			
ErrStatus	ERROR or SUCCESS		

Example:

```

/* initialize SPI0 */

spi_parameter_struct spi_init_struct;

ErrStatus errstatus = ERROR;

spi_init_struct.trans_mode      = SPI_TRANSMODE_BDTRANSMIT;
spi_init_struct.device_mode     = SPI_MASTER;
spi_init_struct.frame_size      = SPI_FRAME_SIZE_8BIT;
spi_init_struct.clock_polarity_phase = SPI_CLOCK_POLARITY_HIGH_PHASE_2EDGE;

```

```

spi_init_struct.nss                = SPI_NSS_SOFT;

spi_init_struct.prescale           = SPI_PSC_8;

spi_init_struct.endian             = SPI_ENDIAN_MSB;

errstatus = spi_init(SPI0, &spi_init_struct);

```

spi_enable

The description of spi_enable is shown as below:

Table 3-325. Function spi_enable

Function name	spi_enable
Function prototype	void spi_enable(uint32_t spi_periph);
Function descriptions	Enable SPIx
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* enable SPI0 */

spi_enable(SPI0);

```

spi_disable

The description of spi_disable is shown as below:

Table 3-326. Function spi_disable

Function name	spi_disable
Function prototype	void spi_disable(uint32_t spi_periph);
Function descriptions	Disable SPIx

Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable SPI0 */
spi_disable(SPI0);
```

i2s_init

The description of i2s_init is shown as below:

Table 3-327. Function i2s_init

Function name	i2s_init
Function prototype	void i2s_init(uint32_t spi_periph, uint32_t mode, uint32_t standard, uint32_t ckpl);
Function descriptions	Initialize I2S0 peripheral parameter
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	I2S0 peripheral
<i>SPIx</i>	x=0
Input parameter{in}	
mode	I2S operation mode
<i>I2S_MODE_SLAVETX</i>	I2S slave transmit mode
<i>I2S_MODE_SLAVERX</i>	I2S slave receive mode

<i>I2S_MODE_MASTERTX</i> X	I2S master transmit mode
<i>I2S_MODE_MASTERR</i> X	I2S master receive mode
Input parameter{in}	
standard	I2S standard
<i>I2S_STD_PHILLIPS</i>	I2S phillips standard
<i>I2S_STD_MSB</i>	I2S MSB standard
<i>I2S_STD_LSB</i>	I2S LSB standard
<i>I2S_STD_PCMSHORT</i>	I2S PCM short standard
<i>I2S_STD_PCMLONG</i>	I2S PCM long standard
Input parameter{in}	
ckpl	I2S idle state clock polarity
<i>I2S_CKPL_LOW</i>	I2S clock polarity low level
<i>I2S_CKPL_HIGH</i>	I2S clock polarity high level
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* initialize I2S0 */
```

```
i2s_init(SPI0, I2S_MODE_MASTERTX, I2S_STD_PHILLIPS, I2S_CKPL_LOW);
```

i2s_psc_config

The description of `i2s_psc_config` is shown as below:

Table 3-328. Function `i2s_psc_config`

Function name	<code>i2s_psc_config</code>
Function prototype	<code>void i2s_psc_config(uint32_t spi_periph, uint32_t audiosample, uint32_t frameformat, uint32_t mckout);</code>
Function descriptions	Configure I2S0 prescaler

Precondition	-
The called functions	rcu_clock_freq_get
Input parameter{in}	
spi_periph	I2S0 peripheral
<i>SPIx</i>	x=0
Input parameter{in}	
audiosample	I2S audio sample rate
<i>I2S_AUDIOSAMPLE_8K</i>	audio sample rate is 8KHz
<i>I2S_AUDIOSAMPLE_11K</i>	audio sample rate is 11KHz
<i>I2S_AUDIOSAMPLE_16K</i>	audio sample rate is 16KHz
<i>I2S_AUDIOSAMPLE_22K</i>	audio sample rate is 22KHz
<i>I2S_AUDIOSAMPLE_32K</i>	audio sample rate is 32KHz
<i>I2S_AUDIOSAMPLE_44K</i>	audio sample rate is 44KHz
<i>I2S_AUDIOSAMPLE_48K</i>	audio sample rate is 48KHz
<i>I2S_AUDIOSAMPLE_96K</i>	audio sample rate is 96KHz
<i>I2S_AUDIOSAMPLE_192K</i>	audio sample rate is 192KHz
Input parameter{in}	
frameformat	I2S data length and channel length
<i>I2S_FRAMEFORMAT_DT16B_CH16B</i>	I2S data length is 16 bit and channel length is 16 bit
<i>I2S_FRAMEFORMAT_DT16B_CH32B</i>	I2S data length is 16 bit and channel length is 32 bit
<i>I2S_FRAMEFORMAT_DT24B_CH32B</i>	I2S data length is 24 bit and channel length is 32 bit

<i>DT24B_CH32B</i>	
<i>I2S_FRAMEFORMAT_DT32B_CH32B</i>	I2S data length is 32 bit and channel length is 32 bit
Input parameter{in}	
mckout	I2S master clock output
<i>I2S_MCKOUT_ENABLE</i>	I2S master clock output enable
<i>I2S_MCKOUT_DISABLE</i>	I2S master clock output disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure I2S0 prescaler */
```

```
i2s_psc_config(SPI0, I2S_AUDIOSAMPLE_44K, I2S_FRAMEFORMAT_DT16B_CH16B, I2S_MCKOUT_DISABLE);
```

i2s_enable

The description of `i2s_enable` is shown as below:

Table 3-329. Function `i2s_enable`

Function name	<code>i2s_enable</code>
Function prototype	<code>void i2s_enable(uint32_t spi_periph);</code>
Function descriptions	Enable I2S0
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	I2S0 peripheral
<i>SPIx</i>	x=0
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* enable I2S0*/
i2s_enable(SPI0);
```

i2s_disable

The description of i2s_disable is shown as below:

Table 3-330. Function i2s_disable

Function name	i2s_disable
Function prototype	void i2s_disable(uint32_t spi_periph);
Function descriptions	Disable I2S0
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	I2S0 peripheral
<i>SPIx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable I2S0*/
i2s_disable(SPI0);
```

spi_nss_output_enable

The description of spi_nss_output_enable is shown as below:

Table 3-331. Function spi_nss_output_enable

Function name	spi_nss_output_enable
Function prototype	void spi_nss_output_enable(uint32_t spi_periph);

Function descriptions	Enable SPIx NSS output function
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPIx peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable SPI0 NSS output */
spi_nss_output_enable(SPI0);
```

spi_nss_output_disable

The description of spi_nss_output_disable is shown as below:

Table 3-332. Function spi_nss_output_disable

Function name	spi_nss_output_disable
Function prototype	void spi_nss_output_disable(uint32_t spi_periph);
Function descriptions	Disable SPIx NSS output function
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPIx peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable SPI0 NSS output */
spi_nss_output_disable(SPI0);
```

spi_nss_internal_high

The description of spi_nss_internal_high is shown as below:

Table 3-333. Function spi_nss_internal_high

Function name	spi_nss_internal_high
Function prototype	void spi_nss_internal_high(uint32_t spi_periph);
Function descriptions	SPI NSS pin high level in software mode
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* SPI0 NSS pin is pulled high level in software mode */
spi_nss_internal_high(SPI0);
```

spi_nss_internal_low

The description of spi_nss_internal_low is shown as below:

Table 3-334. Function spi_nss_internal_low

Function name	spi_nss_internal_low
Function prototype	void spi_nss_internal_low(uint32_t spi_periph);
Function descriptions	SPI NSS pin low level in software mode
Precondition	-

The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* SPI0 NSS pin is pulled low level in software mode */
```

```
spi_nss_internal_low(SPI0);
```

spi_dma_enable

The description of spi_dma_enable is shown as below:

Table 3-335. Function spi_dma_enable

Function name	spi_dma_enable
Function prototype	void spi_dma_enable(uint32_t spi_periph, uint8_t dma);
Function descriptions	Enable SPIx DMA function
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Input parameter{in}	
dma	SPI DMA mode
<i>SPI_DMA_TRANSMIT</i>	SPI transmit data use DMA
<i>SPI_DMA_RECEIVE</i>	SPI receive data use DMA
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* enable SPI0 transmit data DMA function */
spi_dma_enable(SPI0, SPI_DMA_TRANSMIT);
```

spi_dma_disable

The description of spi_dma_disable is shown as below:

Table 3-336. Function spi_dma_disable

Function name	spi_dma_disable
Function prototype	void spi_dma_disable(uint32_t spi_periph, uint8_t dma);
Function descriptions	Disable SPIx DMA function
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Input parameter{in}	
dma	SPI DMA mode
<i>SPI_DMA_TRANSMIT</i>	SPI transmit data use DMA
<i>SPI_DMA_RECEIVE</i>	SPI receive data use DMA
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable SPI0 transmit data DMA function */
spi_dma_disable(SPI0, SPI_DMA_TRANSMIT);
```

spi_i2s_data_frame_format_config

The description of spi_i2s_data_frame_format_config is shown as below:

Table 3-337. Function spi_i2s_data_frame_format_config

Function name	spi_i2s_data_frame_format_config
Function prototype	ErrStatus spi_i2s_data_frame_format_config(uint32_t spi_periph, uint16_t frame_format);
Function descriptions	Configure SPIx/I2S0 data frame format
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Input parameter{in}	
frame_format	SPI frame size
<i>SPI_FRAME_SIZE_xBIT</i>	SPI frame size is x bits,x=4,5,6,...,15,16
Output parameter{out}	
-	-
Return value	
ErrStatus	ERROR or SUCCESS

Example:

```
/* configure SPI0/I2S0 data frame format size is 16 bits */
spi_i2s_data_frame_format_config(SPI0, SPI_FRAME_SIZE_16BIT);
```

spi_i2s_data_transmit

The description of spi_i2s_data_transmit is shown as below:

Table 3-338. Function spi_i2s_data_transmit

Function name	spi_i2s_data_transmit
Function prototype	void spi_i2s_data_transmit(uint32_t spi_periph, uint16_t data);
Function descriptions	SPI transmit data
Precondition	-

The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Input parameter{in}	
data	16-bit data
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* SPI0 transmit data */
```

```
spi_i2s_data_transmit(SPI0, spi0_send_array[send_n]);
```

spi_i2s_data_receive

The description of spi_i2s_data_receive is shown as below:

Table 3-339. Function spi_i2s_data_receive

Function name	spi_i2s_data_receive
Function prototype	uint16_t spi_i2s_data_receive(uint32_t spi_periph);
Function descriptions	SPI receive data
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
uint16_t	16-bit data

Example:

```
/* SPI0 receive data */
```

```
spi0_receive_array[receive_n] = spi_i2s_data_receive(SPI0);
```

spi_bidirectional_transfer_config

The description of spi_bidirectional_transfer_config is shown as below:

Table 3-340. Function spi_bidirectional_transfer_config

Function name	spi_bidirectional_transfer_config
Function prototype	void spi_bidirectional_transfer_config(uint32_t spi_periph, uint32_t transfer_direction);
Function descriptions	Configure SPIx bidirectional transfer direction
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Input parameter{in}	
transfer_direction	SPI transfer direction
<i>SPI_BIDIRECTIONAL_TRANSMIT</i>	SPI work in transmit-only mode
<i>SPI_BIDIRECTIONAL_RECEIVE</i>	SPI work in receive-only mode
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* SPI0 works in transmit-only mode */
```

```
spi_bidirectional_transfer_config(SPI0, SPI_BIDIRECTIONAL_TRANSMIT);
```


spi_crc_polynomial_set

The description of spi_crc_polynomial_set is shown as below:

Table 3-341. Function spi_crc_polynomial_set

Function name	spi_crc_polynomial_set
Function prototype	void spi_crc_polynomial_set(uint32_t spi_periph, uint16_t crc_poly);
Function descriptions	Set SPI CRC polynomial
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Input parameter{in}	
crc_poly	CRC polynomial value
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set SPI0 CRC polynomial */
spi_crc_polynomial_set(SPI0,CRC_VALUE);
```

spi_crc_polynomial_get

The description of spi_crc_polynomial_get is shown as below:

Table 3-342. Function spi_crc_polynomial_get

Function name	spi_crc_polynomial_get
Function prototype	uint16_t spi_crc_polynomial_get(uint32_t spi_periph);
Function descriptions	Get SPI CRC polynomial
Precondition	-
The called functions	-

Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
uint16_t	16 bit CRC polynomial value

Example:

```

/* get SPI0 CRC polynomial */
uint16_t crc_val;
crc_val = spi_crc_polynomial_get(SPI0);

```

spi_crc_on

The description of spi_crc_on is shown as below:

Table 3-343. Function spi_crc_on

Function name	spi_crc_on
Function prototype	void spi_crc_on(uint32_t spi_periph);
Function descriptions	Turn on CRC function
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* turn on SPI0 CRC function */

```

```
spi_crc_on(SPI0);
```

spi_crc_off

The description of spi_crc_off is shown as below:

Table 3-344. Function spi_crc_off

Function name	spi_crc_off
Function prototype	void spi_crc_off(uint32_t spi_periph);
Function descriptions	Turn off CRC function
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* turn off SPI0 CRC function */
```

```
spi_crc_off(SPI0);
```

spi_crc_next

The description of spi_crc_next is shown as below:

Table 3-345. Function spi_crc_next

Function name	spi_crc_next
Function prototype	void spi_crc_next(uint32_t spi_periph);
Function descriptions	SPI next data is CRC value
Precondition	-
The called functions	-
Input parameter{in}	

spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* SPI0 next data is CRC value */
```

```
spi_crc_next(SPI0);
```

spi_crc_get

The description of spi_crc_get is shown as below:

Table 3-346. Function spi_crc_get

Function name	spi_crc_get
Function prototype	uint16_t spi_crc_get(uint32_t spi_periph,uint8_t crc);
Function descriptions	Get SPI CRC send value or receive value
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Input parameter{in}	
<i>crc</i>	SPI crc value
<i>SPI_CRC_TX</i>	get transmit crc value
<i>SPI_CRC_RX</i>	get receive crc value
Output parameter{out}	
-	-
Return value	
uint16_t	16-bit CRC value

Example:

```
/* get SPI0 CRC send value */
uint16_t crc_val;

crc_val = spi_crc_get(SPI0,SPI_CRC_TX);
```

spi_ti_mode_enable

The description of spi_ti_mode_enable is shown as below:

Table 3-347. Function spi_ti_mode_enable

Function name	spi_ti_mode_enable
Function prototype	void spi_ti_mode_enable(uint32_t spi_periph);
Function descriptions	Enable SPI TI mode
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	

Example:

```
/* enable SPI0 TI mode */
spi_ti_mode_enable(SPI0);
```

spi_ti_mode_disable

The description of spi_ti_mode_disable is shown as below:

Table 3-348. Function spi_ti_mode_disable

Function name	spi_ti_mode_disable
Function prototype	void spi_ti_mode_disable(uint32_t spi_periph);
Function descriptions	Disable SPI TI mode

Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	

Example:

```
/* disable SPI0 TI mode */
spi_ti_mode_disable(SPI0);
```

spi_nssp_mode_enable

The description of spi_nssp_mode_enable is shown as below:

Table 3-349. Function spi_nssp_mode_enable

Function name	spi_ti_mode_enable
Function prototype	void spi_ti_mode_enable(uint32_t spi_periph);
Function descriptions	Enable SPI NSS pulse mode
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	

Example:

```
/* enable SPI0 NSS pulse mode */
```

```
spi_nssp_mode_enable(SPI0);
```

spi_nssp_mode_disable

The description of spi_nssp_mode_disable is shown as below:

Table 3-350. Function spi_nssp_mode_disable

Function name	spi_nssp_mode_disable
Function prototype	void spi_nssp_mode_disable(uint32_t spi_periph);
Function descriptions	Disable SPI NSS pulse mode
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	

Example:

```
/* disable SPI0 NSS pulse mode */
```

```
spi_nssp_mode_disable(SPI0);
```

qspi_enable

The description of qspi_enable is shown as below:

Table 3-351. Function qspi_enable

Function name	qspi_enable
Function prototype	void qspi_enable(uint32_t spi_periph);
Function descriptions	Enable quad wire SPI
Precondition	-
The called functions	-

Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=1
Output parameter{out}	
-	-
Return value	

Example:

```
/* enable SPI1 quad wire mode */
qspi_enable(SPI1);
```

qspi_disable

The description of qspi_disable is shown as below:

Table 3-352. Function qspi_disable

Function name	qspi_disable
Function prototype	void qspi_disable(uint32_t spi_periph);
Function descriptions	Disable quad wire SPI
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=1
Output parameter{out}	
-	-
Return value	

Example:

```
/* disable SPI1 quad wire mode */
qspi_disable(SPI1);
```


qspi_write_enable

The description of qspi_write_enable is shown as below:

Table 3-353. Function qspi_write_enable

Function name	qspi_write_enable
Function prototype	void qspi_write_enable(uint32_t spi_periph);
Function descriptions	Enable quad wire SPI write
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=1
Output parameter{out}	
-	-
Return value	

Example:

```
/* enable SPI1 quad wire write */
qspi_write_enable(SPI1);
```

qspi_read_enable

The description of qspi_read_enable is shown as below:

Table 3-354. Function qspi_read_enable

Function name	qspi_read_enable
Function prototype	void qspi_read_enable(uint32_t spi_periph);
Function descriptions	Enable quad wire SPI read
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral

<i>SPIx</i>	x=1
Output parameter{out}	
-	-
Return value	

Example:

```
/* enable SPI1 quad wire read */
qspi_read_enable(SPI1);
```

qspi_io23_output_enable

The description of qspi_io23_output_enable is shown as below:

Table 3-355. Function qspi_io23_output_enable

Function name	qspi_io23_output_enable
Function prototype	void qspi_io23_output_enable(uint32_t spi_periph);
Function descriptions	Enable SPI_IO2 and SPI_IO3 pin output
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=1
Output parameter{out}	
-	-
Return value	

Example:

```
/* enable SPI1 SPI_IO2 and SPI_IO3 pin output */
qspi_io23_output_enable(SPI1);
```

qspi_io23_output_disable

The description of qspi_io23_output_disable is shown as below:

Table 3-356. Function qspi_io23_output_disable

Function name	qspi_io23_output_disable
Function prototype	void qspi_io23_output_disable(uint32_t spi_periph);
Function descriptions	Disable SPI_IO2 and SPI_IO3 pin output
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=1
Output parameter{out}	
-	-
Return value	

Example:

```
/* disable SPI1 SPI_IO2 and SPI_IO3 pin output */
qspi_io23_output_disable(SPI1);
```

spi_i2s_interrupt_enable

The description of spi_i2s_interrupt_enable is shown as below:

Table 3-357. Function spi_i2s_interrupt_enable

Function name	spi_i2s_interrupt_enable
Function prototype	void spi_i2s_interrupt_enable(uint32_t spi_periph, uint8_t interrupt);
Function descriptions	Enable SPIx and I2S0 interrupt
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Input parameter{in}	

interrupt	SPI/I2S interrupt
<i>SPI_I2SINT_TBE</i>	transmit buffer empty interrupt
<i>SPI_I2S_INT_RBNE</i>	receive buffer not empty interrupt
<i>SPI_I2S_INT_ERR</i>	CRC error,configuration error,reception overrun error, transmission underrun error and format error interrupt
Output parameter{out}	
-	-
Return value	

Example:

```
/* enable SPI0 transmit buffer empty interrupt */
```

```
spi_i2s_interrupt_enable(SPI0,SPI_I2S_INT_TBE);
```

spi_i2s_interrupt_disable

The description of spi_i2s_interrupt_disable is shown as below:

Table 3-358. Function spi_i2s_interrupt_disable

Function name	spi_i2s_interrupt_disable
Function prototype	void spi_i2s_interrupt_disable(uint32_t spi_periph, uint8_t interrupt);
Function descriptions	Disable SPIx and I2S0 interrupt
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Input parameter{in}	
interrupt	SPI/I2S interrupt
<i>SPI_I2SINT_TBE</i>	transmit buffer empty interrupt
<i>SPI_I2S_INT_RBNE</i>	receive buffer not empty interrupt
<i>SPI_I2S_INT_ERR</i>	CRC error,configuration error,reception overrun error, transmission underrun error and format error interrupt

Output parameter{out}	
-	-
Return value	

Example:

```

/* disable SPI0 transmit buffer empty interrupt */
spi_i2s_interrupt_disable(SPI0,SPI_I2S_INT_TBE);

```

spi_i2s_interrupt_flag_get

The description of spi_i2s_interrupt_flag_get is shown as below:

Table 3-359. Function spi_i2s_interrupt_flag_get

Function name	spi_i2s_interrupt_flag_get
Function prototype	FlagStatus spi_i2s_interrupt_flag_get(uint32_t spi_periph, uint8_t interrupt);
Function descriptions	Get SPIx and I2S0 interrupt flag status
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Input parameter{in}	
interrupt	SPI/I2S interrupt
<i>SPI_I2S_INT_FLAG_TBE</i>	transmit buffer empty interrupt
<i>SPI_I2S_INT_FLAG_RBNE</i>	receive buffer not empty interrupt
<i>SPI_I2S_INT_FLAG_RXORERR</i>	overrun interrupt
<i>SPI_INT_FLAG_CONFIGERR</i>	config error interrupt
<i>SPI_INT_FLAG_CRCERR</i>	CRC error interrupt

<i>I2S_INT_FLAG_TXUR</i> <i>ERR</i>	underrun error interrupt
<i>SPI_I2S_INT_FLAG_F</i> <i>ERR</i>	format error interrupt
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```

/* get SPI0 transmit buffer empty interrupt status */
If(RESET != spi_i2s_interrupt_flag_get(SPI0.SPI_I2S_INT_FLAG_TBE)){
    while(RESET == spi_i2s_flag_get(SPI0,SPI_FLAG_TBE));
    spi_i2s_data_transmit(SPI0,spi0_send_array[send_n++]);
}

```

spi_i2s_flag_get

The description of spi_i2s_flag_get is shown as below:

Table 3-360. Function spi_i2s_flag_get

Function name	spi_i2s_flag_get
Function prototype	FlagStatus spi_i2s_flag_get(uint32_t spi_periph, uint8_t interrupt);
Function descriptions	Get SPIx and I2S0 flag status
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Input parameter{in}	
flag	SPI/I2S flag status
<i>SPI_FLAG_TBE</i>	transmit buffer empty flag
<i>SPI_FLAG_RBNE</i>	receive buffer not empty flag

<i>SPI_FLAG_TRANS</i>	transmit on-going flag
<i>SPI_FLAG_RXORERR</i>	receive overrun error flag
<i>SPI_FLAG_CONFERR</i>	mode config error flag
<i>SPI_FLAG_CRCERR</i>	CRC error flag
<i>SPI_FLAG_FERR</i>	format error interrupt flag
<i>I2S_FLAG_TBE</i>	transmit buffer empty flag
<i>I2S_FLAG_RBNE</i>	receive buffer not empty flag
<i>I2S_FLAG_TRANS</i>	transmit on-going flag
<i>I2S_FLAG_RXORERR</i>	overrun error flag
<i>I2S_FLAG_TXURERR</i>	underrun error flag
<i>I2S_FLAG_CH</i>	channel side flag
Only for SPI1	
<i>SPI_TXLVL_EMPTY</i>	SPI TXFIFO is empty
<i>SPI_TXLVL_QUARTER_FULL</i>	SPI TXFIFO is a quarter of full
<i>SPI_TXLVL_HAIF_FULL</i>	SPI TXFIFO is a half of full
<i>SPI_TXLVL_FULL</i>	SPI TXFIFO is full
<i>SPI_RXLVL_EMPTY</i>	SPI RXFIFO is empty
<i>SPI_RXLVL_QUARTER_FULL</i>	SPI RXFIFO is a quarter of full
<i>SPI_RXLVL_HAIF_FULL</i>	SPI RXFIFO is a half of full
<i>SPI_RXLVL_FULL</i>	SPI RXFIFO is full
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get SPI0 transmit buffer empty flag status */
```

```
while(RESET == spi_i2s_flag_get(SPI0,SPI_FLAG_TBE));
```

```
spi_i2s_data_transmit(SPI0,spi0_send_array[send_n++]);
```

spi_crc_error_clear

The description of spi_crc_error_clear is shown as below:

Table 3-361. Function spi_crc_error_clear

Function name	spi_crc_error_clear
Function prototype	void spi_crc_error_clear(uint32_t spi_periph);
Function descriptions	Clear SPI CRC error flag status
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=0,1
Output parameter{out}	
-	-
Return value	

Example:

```
/* clear SPI0CRC error flag status */
```

```
spi_crc_error_clear(SPI0);
```

spi_fifo_access_size_config

The description of spi_fifo_access_size_config is shown as below:

Table 3-362. Function spi_fifo_access_size_config

Function name	spi_fifo_access_size_config
Function prototype	void spi_fifo_access_size_config(uint32_t spi_periph, uint16_t fifo_access_size);
Function descriptions	Configure SPI1 access size to FIFO(8bit or 16bit)
Precondition	-

The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=1
Input parameter{in}	
fifo_access_size	byte access enable
<i>SPI_HALFWORD_ACCESS</i>	half-word access to FIFO
<i>SPI_BYTE_ACCESS</i>	byte access to FIFO
Output parameter{out}	
-	-
Return value	

Example:

```
/* configure SPI1 access size half word */
```

```
spi_fifo_access_config(SPI1, SPI_HALFWORD_ACCESS);
```

spi_transmit_odd_config

The description of spi_transmit_odd_config is shown as below:

Table 3-363. Function spi_transmit_odd_config

Function name	spi_transmit_odd_config
Function prototype	void spi_transmit_odd_config(uint32_t spi_periph, uint16_t odd);
Function descriptions	configure SPI1 total number of data to transmit by DMA is odd or not
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=1
Input parameter{in}	

odd	odd bytes in TX DMA channel
<i>SPI_TXDMA_EVEN</i>	number of byte in TX DMA channel is even
<i>SPI_TXDMA_ODD</i>	number of byte in TX DMA channel is odd
Output parameter{out}	
-	-
Return value	

Example:

```
/* configure SPI1 total number of data to transmit by DMA is odd */
spi_transmit_odd_config(SPI1, SPI_TXDMA_ODD);
```

spi_receive_odd_config

The description of spi_receive_odd_config is shown as below:

Table 3-364. Function spi_receive_odd_config

Function name	spi_receive_odd_config
Function prototype	void spi_receive_odd_config(uint32_t spi_periph, uint16_t odd);
Function descriptions	configure SPI1 total number of data to receive by DMA is odd or not
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=1
Input parameter{in}	
odd	odd bytes in TX DMA channel
<i>SPI_RXDMA_EVEN</i>	number of byte in RX DMA channel is even
<i>SPI_RXDMA_ODD</i>	number of byte in RX DMA channel is odd
Output parameter{out}	
-	-
Return value	

Example:

```
/* configure SPI1 total number of data to receive by DMA is odd */
spi_receive_odd_config(SPI1, SPI_TXDMA_ODD);
```

spi_crc_length_set

The description of spi_crc_length_set is shown as below:

Table 3-365. Function spi_crc_length_set

Function name	spi_crc_length_set
Function prototype	void spi_crc_length_set(uint32_t spi_periph, uint16_t crc_length);
Function descriptions	set CRC length
Precondition	-
The called functions	-
Input parameter{in}	
spi_periph	SPI peripheral
<i>SPIx</i>	x=1
Input parameter{in}	
crc_length	CRC length
<i>SPI_CRC_8BIT</i>	CRC length is 8 bits
<i>SPI_CRC_16BIT</i>	CRC length is 16 bits
Output parameter{out}	
-	-
Return value	

Example:

```
/* set SPI1 CRC length 16 bits */
spi_crc_length_set(SPI1, SPI_CRC_16BIT);
```

3.17. SYSCFG

The SYSCFG registers are listed in chapter [3.17.1](#), the SYSCFG firmware functions are introduced in chapter [3.17.2](#).

3.17.1. Descriptions of Peripheral registers

SYSCFG registers are listed in the table shown as below:

Table 3-366. SYSCFG Registers

Registers	Descriptions
SYSCFG_CFG0	system configuration register 0
SYSCFG_EXTISS0	EXTI sources selection register 0
SYSCFG_EXTISS1	EXTI sources selection register 1
SYSCFG_EXTISS2	EXTI sources selection register 2
SYSCFG_EXTISS3	EXTI sources selection register 3
SYSCFG_CFG2	system configuration register 2
SYSCFG_CPU_IRQ_LAT	IRQ Latency register

3.17.2. Descriptions of Peripheral functions

SYSCFG firmware functions are listed in the table shown as below:

Table 3-367. SYSCFG firmware function

Function name	Function description
syscfg_deinit	deinit syscfg module
syscfg_dma_remap_enable	enable the DMA channels remapping
syscfg_dma_remap_disable	disable the DMA channels remapping
syscfg_high_current_enable	enable PB9 high current capability
syscfg_high_current_disable	disable PB9 high current capability
syscfg_exti_line_config	configure the GPIO pin as EXTI Line
syscfg_lock_config	connect TIMER0/14/15/16 break input to the selected parameter
irq_latency_set	set the IRQ_LATENCY value

Function name	Function description
syscfg_flag_get	check if the specified flag in SYSCFG_CFG2 is set or not
syscfg_flag_clear	clear the flag in SYSCFG_CFG2 by writing 1

syscfg_deinit

The description of syscfg_deinit is shown as below:

Table 3-368. Function syscfg_deinit

Function name	syscfg_deinit
Function prototype	void syscfg_deinit(void);
Function descriptions	reset the SYSCFG registers
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset SYSCFG registers */
syscfg_deinit();
```

syscfg_dma_remap_enable

The description of syscfg_dma_remap_enable is shown as below:

Table 3-369. Function syscfg_dma_remap_enable

Function name	syscfg_dma_remap_enable
Function prototype	void syscfg_dma_remap_enable (void);
Function descriptions	enable the DMA channels remapping
Precondition	-
The called functions	-

Input parameter{in}	
syscfg_dma_remap	specify the DMA channels to remap
<i>SYSCFG_DMA_REMAP_TIMER16</i>	remap TIMER16 channel0 and UP DMA requests to channel1(default channel0)
<i>SYSCFG_DMA_REMAP_TIMER15</i>	remap TIMER15 channel2 and UP DMA requests to channel3(default channel2)
<i>SYSCFG_DMA_REMAP_USART0RX</i>	remap USART0 Rx DMA request to channel4(default channel2)
<i>SYSCFG_DMA_REMAP_USART0TX</i>	remap USART0 Tx DMA request to channel3(default channel1)
<i>SYSCFG_DMA_REMAP_ADC</i>	remap ADC DMA requests from channel0 to channel1
<i>SYSCFG_PA11_REMAP_PA12</i>	remap PA11 PA12
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DMA channel remap*/
```

```
syscfg_dma_remap_enable(SYSCFG_DMA_REMAP_TIMER16);
```

syscfg_dma_remap_disable

The description of syscfg_dma_remap_disable is shown as below:

Table 3-370. Function syscfg_dma_remap_disable

Function name	syscfg_dma_remap_disable
Function prototype	void syscfg_dma_remap_disable (void);
Function descriptions	disable the DMA channels remapping
Precondition	-
The called functions	-
Input parameter{in}	

syscfg_dma_remap	specify the DMA channels to remap
<i>SYSCFG_DMA_REMAP_TIMER16</i>	remap TIMER16 channel0 and UP DMA requests to channel1(default channel0)
<i>SYSCFG_DMA_REMAP_TIMER15</i>	remap TIMER15 channel2 and UP DMA requests to channel3(default channel2)
<i>SYSCFG_DMA_REMAP_USART0RX</i>	remap USART0 Rx DMA request to channel4(default channel2)
<i>SYSCFG_DMA_REMAP_USART0TX</i>	remap USART0 Tx DMA request to channel3(default channel1)
<i>SYSCFG_DMA_REMAP_ADC</i>	remap ADC DMA requests from channel0 to channel1
<i>SYSCFG_PA11_REMAP_PA12</i>	remap PA11 PA12
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DMA channel remap*/
```

```
syscfg_dma_remap_disable(SYSCFG_DMA_REMAP_TIMER16);
```

syscfg_high_current_enable

The description of syscfg_high_current_enable is shown as below:

Table 3-371. Function syscfg_high_current_enable

Function name	syscfg_high_current_enable
Function prototype	void syscfg_high_current_enable(void);
Function descriptions	enable PB9 high current capability
Precondition	-
The called functions	-
Input parameter{in}	
-	-

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable PB9 high current capability */
```

```
syscfg_high_current_enable();
```

syscfg_high_current_disable

The description of syscfg_high_current_disable is shown as below:

Table 3-372. Function syscfg_high_current_disable

Function name	syscfg_high_current_disable
Function prototype	void syscfg_high_current_disable(void);
Function descriptions	disable PB9 high current capability
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable PB9 high current capability */
```

```
syscfg_high_current_disable();
```

syscfg_exti_line_config

The description of syscfg_exti_line_config is shown as below:

Table 3-373. Function syscfg_exti_line_config

Function name	syscfg_exti_line_config
----------------------	-------------------------

Function prototype	void syscfg_exti_line_config(uint8_t exti_port, uint8_t exti_pin);
Function descriptions	configure the GPIO pin as EXTI Line
Precondition	-
The called functions	-
Input parameter{in}	
exti_port	specify the GPIO port used in EXTI
<i>EXTI_SOURCE_GPIOx</i>	x=A,B,C,F
exti_pin	specify the EXTI line
<i>EXTI_SOURCE_PINx</i>	x=0..15(GPIOA, GPIOB), x=13..15(GPIOC), x = 0.1.6.7 (GPIOF)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the GPIO pin as EXTI Line */
syscfg_exti_line_config(EXTI_SOURCE_GPIOA, EXTI_SOURCE_PIN0);
```

syscfg_lock_config

The description of syscfg_lock_config is shown as below:

Table 3-374. Function syscfg_lock_config

Function name	syscfg_lock_config
Function prototype	void syscfg_lock_config (uint32_t syscfg_lock);
Function descriptions	connect TIMER0/14/15/16 break input to the selected parameter
Precondition	-
The called functions	-
Input parameter{in}	
syscfg_lock	specify the parameter to be connected
<i>SYSCFG_LOCK_LOCKUP</i>	Cortex-M23 lockup output connected to the break input

<code>SYSCFG_LOCK_SRAM_PARITY_ERROR</code>	SRAM_PARITY check error connected to the break input
<code>SYSCFG_LOCK_LVD</code>	LVD interrupt connected to the break input
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* configure syscfg lock*/
syscfg_lock_config(SYSCFG_LOCK_LOCKUP);

```

irq_latency_set

The description of irq_latency_set is shown as below:

Table 3-375. Function irq_latency_set

Function name	irq_latency_set
Function prototype	void irq_latency_set(uint8_t irq_latency);
Function descriptions	set the wait state counter value
Precondition	-
The called functions	-
Input parameter{in}	
irq_latency	IRQ_LATENCY value
<i>0x00 - 0xFF</i>	IRQ_LATENCY value
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* set the wait state counter value */
irq_latency_set(0xFF);

```

syscfg_flag_get

The description of syscfg_flag_get is shown as below:

Table 3-376. Function syscfg_flag_get

Function name	syscfg_flag_get
Function prototype	FlagStatus syscfg_flag_get(uint32_t syscfg_flag);
Function descriptions	check if the specified flag in SYSCFG_CFG2 is set or not
Precondition	-
The called functions	-
Input parameter{in}	
syscfg_flag	specify the flag in SYSCFG_CFG2 to check
SYSCFG_SRAM_PCE F	SRAM parity check error flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```

/* get syscfg flag */
FlagStatus status;

status = syscfg_flag_get(SYSCFG_SRAM_PCEF);

```

syscfg_flag_clear

The description of syscfg_flag_clear is shown as below:

Table 3-377. Function syscfg_flag_clear

Function name	syscfg_flag_clear
Function prototype	void syscfg_flag_clear (uint32_t syscfg_flag);
Function descriptions	clear the flag in SYSCFG_CFG2 by writing 1
Precondition	-
The called functions	-
Input parameter{in}	

syscfg_flag	specify the flag in SYSCFG_CFG2 to check
SYSCFG_SRAM_PCE F	SRAM parity check error flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear syscfg flag */
```

```
syscfg_flag_clear(SYSCFG_SRAM_PCEF);
```

3.18. TIMER

The timers have a 16-bit counter that can be used as an unsigned counter and supports both input capture and output compare. Timers (TIMERx) are divided into five sorts: advanced timer (TIMER0), general level0 timer (TIMER2), general level2 timer (TIMER13), general level2 timer (TIMERx, x=15, 16), Basic timer (TIMER5). The specific functions of different types of timer are different. The TIMER registers are listed in chapter [3.18.1](#), the TIMER firmware functions are introduced in chapter [3.18.2](#).

3.18.1. Descriptions of Peripheral registers

TIMERx registers are listed in the table shown as below:

Table 3-378. TIMERx Registers

Registers	Descriptions
TIMER_CTL0(timerx, x=0, 2, 5, 13, 14, 15, 16)	Control register 0
TIMERx_CTL1(timerx, x=0, 2, 5, 13, 14, 15, 16)	Control register 1
TIMERx_SMCFG(timerx, x=0, 2, 14)	Slave mode configuration register
TIMERx_DMAINTEN(timerx, x=0, 2, 5, 13, 14, 15, 16)	DMA and interrupt enable register
TIMERx_INTF(timerx, x=0, 2, 5, 13, 14, 15, 16)	Interrupt flag register
TIMERx_SWEVG(timerx, x=0, 2, 5, 13, 14, 15, 16)	Software event generation register

Registers	Descriptions
16)	
TIMERx_CHCTL0(timerx, x=0, 2, 13, 14, 15, 16)	Channel control register 0
TIMERx_CHCTL1(timerx, x=0, 2)	Channel control register 1
TIMERx_CHCTL2(timerx, x=0, 2, 13, 14, 15, 16)	Channel control register 2
TIMERx_CNT(timerx, x=0, 2, 5, 13, 14, 15, 16)	Counter register
TIMERx_PSC(timerx, x=0, 2, 5, 13, 14, 15, 16)	Prescaler register
TIMERx_CAR(timerx, x=0, 2, 5, 13, 14, 15, 16)	Counter auto reload register
TIMERx_CREP(timerx, x=0, 5, 14, 15, 16)	Counter repetition register
TIMERx_CH0CV(timerx, x=0, 2, 13, 14, 15, 16)	Channel 0 capture/compare value register
TIMERx_CH1CV(timerx, x=0, 2, 14)	Channel 1 capture/compare value register
TIMERx_CH2CV(timerx, x=0, 2)	Channel 2 capture/compare value register
TIMERx_CH3CV(timerx, x=0, 2)	Channel 3 capture/compare value register
TIMERx_IRMP(timerx, x=13)	Channel complementary protection register
TIMERx_CCHP(timerx, x=0, 2, 14, 15, 16)	TIMER complementary channel protection register
TIMERx_DMCFG(timerx, x=0, 2, 14, 15, 16)	DMA configuration register
TIMERx_DMATB(timerx, x=0, 2, 14, 15, 16)	DMA transfer buffer register
TIMERx_CFG(timerx, x=0, 2, 13, 14, 15, 16)	Configuration register

3.18.2. Descriptions of Peripheral functions

The description format of firmware functions are shown as below:

Table 3-379. TIMERx firmware function

Function name	Function description
timer_deinit	deinit a timer
timer_struct_para_init	initialize the parameters of TIMER init parameter struct with the default values
timer_init	initialize TIMER counter
timer_enable	enable a timer

Function name	Function description
timer_disable	disable a timer
timer_auto_reload_shadow_enable	enable the auto reload shadow function
timer_auto_reload_shadow_disable	disable the auto reload shadow function
timer_update_event_enable	enable the update event
timer_update_event_disable	disable the update event
timer_counter_alignment	set TIMER counter alignment mode
timer_counter_up_direction	set TIMER counter up direction
timer_counter_down_direction	set TIMER counter down direction
timer_prescaler_config	configure TIMER prescaler
timer_repetition_value_config	configure TIMER repetition register value
timer_autoreload_value_config	configure TIMER autoreload register value
timer_counter_value_config	configure TIMER counter register value
timer_counter_read	read TIMER counter value
timer_prescaler_read	read TIMER prescaler value
timer_single_pulse_mode_config	configure TIMER single pulse mode
timer_update_source_config	configure TIMER update source
timer_ocpre_clear_source_config	configure TIMER OCPRE clear source selection
timer_interrupt_enable	enable the TIMER interrupt
timer_interrupt_disable	disable the TIMER interrupt
timer_interrupt_flag_get	get timer interrupt flag
timer_interrupt_flag_clear	clear TIMER interrupt flag
timer_flag_get	get TIMER flags
timer_flag_clear	clear TIMER flags
timer_dma_enable	enable the TIMER DMA
timer_dma_disable	disable the TIMER DMA
timer_channel_dma_request_source_select	channel DMA request source selection
timer_dma_transfer_config	configure the TIMER DMA transfer

Function name	Function description
timer_event_software_generate	software generate events
timer_break_struct_para_init	initialize the parameters of TIMER break parameter struct with the default values
timer_break_config	configure TIMER break function
timer_break_enable	enable TIMER break function
timer_break_disable	disable TIMER break function
timer_automatic_output_enable	enable TIMER output automatic function
timer_automatic_output_disable	disable TIMER output automatic function
timer_primary_output_config	configure TIMER primary output function
timer_channel_control_shadow_config	channel capture/compare control shadow register enable
timer_channel_control_shadow_update_config	configure TIMER channel control shadow register update control
timer_channel_output_struct_para_init	initialize the parameters of TIMER channel output parameter struct with the default values
timer_channel_output_config	configure TIMER channel output function
timer_channel_output_mode_config	configure TIMER channel output compare mode
timer_channel_output_pulse_value_config	configure TIMER channel output pulse value
timer_channel_output_shadow_config	configure TIMER channel output shadow function
timer_channel_output_fast_config	configure TIMER channel output fast function
timer_channel_output_clear_config	configure TIMER channel output clear function
timer_channel_output_polarity_config	configure TIMER channel output polarity
timer_channel_complementary_output_polarity_config	configure TIMER channel complementary output polarity
timer_channel_output_state_config	configure TIMER channel enable state
timer_channel_complementary_output_state_config	configure TIMER channel complementary output enable state

Function name	Function description
timer_channel_input_struct_para_init	initialize the parameters of TIMER channel input parameter struct with the default values
timer_input_capture_config	configure TIMER input capture parameter
timer_channel_input_capture_prescaler_config	configure TIMER channel input capture prescaler value
timer_channel_capture_value_register_read	read TIMER channel capture compare register value
timer_input_pwm_capture_config	configure TIMER input pwm capture function
timer_hall_mode_config	configure TIMER hall sensor mode
timer_input_trigger_source_select	select TIMER input trigger source
timer_master_output_trigger_source_select	select TIMER master mode output trigger source
timer_slave_mode_select	select TIMER slave mode
timer_master_slave_mode_config	configure TIMER master slave mode
timer_external_trigger_config	configure TIMER external trigger input
timer_quadrature_decoder_mode_config	configure TIMER quadrature decoder mode
timer_internal_clock_config	configure TIMER internal clock mode
timer_internal_trigger_as_external_clock_config	configure TIMER the internal trigger as external clock input
timer_external_trigger_as_external_clock_config	configure TIMER the external trigger as external clock input
timer_external_clock_mode0_config	configure TIMER the external clock mode 0
timer_external_clock_mode1_config	configure TIMER the external clock mode 1
timer_external_clock_mode1_disable	disable TIMER the external clock mode 1
timer_channel_remap_config	configure TIMER channel remap function
timer_write_chxval_register_config	configure TIMER write CHxVAL register selection
timer_output_value_selection_config	configure TIMER output value selection

Structure timer_parameter_struct

Table 3-380. Structure timer_parameter_struct

Member name	Function description
prescaler	prescaler value (0~65535)
alignedmode	aligned mode (TIMER_COUNTER_EDGE, TIMER_COUNTER_CENTER_DOWN, TIMER_COUNTER_CENTER_UP, TIMER_COUNTER_CENTER_BOTH)
counterdirection	counter direction (TIMER_COUNTER_UP, TIMER_COUNTER_DOWN)
period	period value (0~65535)
clockdivision	clock division value (TIMER_CKDIV_DIV1, TIMER_CKDIV_DIV2, TIMER_CKDIV_DIV4)
repetitioncounter	the counter repetition value (0~255)

Structure timer_break_parameter_struct

Table 3-381. Structure timer_break_parameter_struct

Member name	Function description
runoffstate	run mode off-state (TIMER_ROS_STATE_ENABLE, TIMER_ROS_STATE_DISABLE)
ideloffstate	idle mode off-state (TIMER_IOS_STATE_ENABLE, TIMER_IOS_STATE_DISABLE)
deadtime	dead time (0~255)
breakpolarity	break polarity (TIMER_BREAK_POLARITY_LOW, TIMER_BREAK_POLARITY_HIGH)
outputautostate	output automatic enable (TIMER_OUTAUTO_ENABLE, TIMER_OUTAUTO_DISABLE)
protectmode	complementary register protect control (TIMER_CCHP_PROT_OFF, TIMER_CCHP_PROT_0, TIMER_CCHP_PROT_1, TIMER_CCHP_PROT_2)
breakstate	break enable (TIMER_BREAK_ENABLE, TIMER_BREAK_DISABLE)

Structure timer_oc_parameter_struct

Table 3-382. Structure timer_oc_parameter_struct

Member name	Function description
outputstate	channel output state (TIMER_CCX_ENABLE, TIMER_CCX_DISABLE)
outputnstate	channel complementary output state (TIMER_CCXN_ENABLE,

Member name	Function description
	TIMER_CCN_DISABLE)
ocpolarity	channel output polarity (TIMER_OC_POLARITY_HIGH, TIMER_OC_POLARITY_LOW)
ocnpolarity	channel complementary output polarity (TIMER_OCN_POLARITY_HIGH, TIMER_OCN_POLARITY_LOW)
ocidlestate	idle state of channel output (TIMER_OC_IDLE_STATE_LOW, TIMER_OC_IDLE_STATE_HIGH)
ocnidlestate	idle state of channel complementary output (TIMER_OCN_IDLE_STATE_LOW, TIMER_OCN_IDLE_STATE_HIGH)

Structure timer_ic_parameter_struct

Table 3-383. Structure timer_ic_parameter_struct

Member name	Function description
icpolarity	channel input polarity (TIMER_IC_POLARITY_RISING, TIMER_IC_POLARITY_FALLING, TIMER_IC_POLARITY_BOTH_EDGE)
icselection	channel input mode selection (TIMER_IC_SELECTION_DIRECTTI, TIMER_IC_SELECTION_INDIRECTTI, TIMER_IC_SELECTION_ITS)
icprescaler	channel input capture prescaler (TIMER_IC_PSC_DIV1, TIMER_IC_PSC_DIV2, TIMER_IC_PSC_DIV4, TIMER_IC_PSC_DIV8)
icfilter	channel input capture filter control (0~15)

timer_deinit

The description of timer_deinit is shown as below:

Table 3-384. Function timer_deinit

Function name	timer_deinit
Function prototype	void timer_deinit(uint32_t timer_periph);
Function descriptions	deinit a TIMER
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Input parameter{in}	
timer_periph	TIMER peripheral

<i>TIMERx(x=0, 2, 5, 13..16)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset TIMER0 */
```

```
timer_deinit (TIMER0);
```

timer_struct_para_init

The description of timer_struct_para_init is shown as below:

Table 3-385. Function timer_struct_para_init

Function name	timer_struct_para_init
Function prototype	void timer_struct_para_init(timer_parameter_struct* initpara);
Function descriptions	initialize the parameters of TIMER init parameter struct with the default values
Precondition	-
The called functions	-
Input parameter{in}	
initpara	TIMER init parameter struct, the structure members can refer to Table 3-380. Structure timer_parameter_struct .
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* initialize TIMER init parameter struct with a default value */
```

```
timer_parameter_struct timer_initpara;
```

```
timer_struct_para_init(timer_initpara);
```

timer_init

The description of timer_init is shown as below:

Table 3-386. Function timer_init

Function name	timer_init
Function prototype	void timer_init(uint32_t timer_periph, timer_parameter_struct* initpara);
Function descriptions	initialize TIMER counter
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 5, 13..16)</i>	TIMER peripheral selection
Input parameter{in}	
initpara	TIMER init parameter struct, the structure members can refer to Table 3-380. Structure timer parameter struct .
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* initialize TIMER0 */

timer_parameter_struct timer_initpara;

timer_initpara.prescaler      = 107;

timer_initpara.alignedmode    = TIMER_COUNTER_EDGE;

timer_initpara.counterdirection = TIMER_COUNTER_UP;

timer_initpara.period         = 999;

timer_initpara.clockdivision  = TIMER_CKDIV_DIV1;

timer_initpara.repetitioncounter = 1;

timer_init(TIMER0,&timer_initpara);

```

timer_enable

The description of timer_enable is shown as below:

Table 3-387. Function timer_enable

Function name	timer_enable
Function prototype	void timer_enable(uint32_t timer_periph);
Function descriptions	enable a timer
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 5, 13..16)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable TIMER0 */
timer_enable (TIMER0);
```

timer_disable

The description of timer_disable is shown as below:

Table 3-388. Function timer_disable

Function name	timer_disable
Function prototype	void timer_disable(uint32_t timer_periph);
Function descriptions	disable a timer
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral

<i>TIMERx</i> (<i>x</i> =0, 2, 5, 13..16)	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable TIMER0 */
```

```
timer_disable (TIMER0);
```

timer_auto_reload_shadow_enable

The description of timer_auto_reload_shadow_enable is shown as below:

Table 3-389. Function timer_auto_reload_shadow_enable

Function name	timer_auto_reload_shadow_enable
Function prototype	void timer_auto_reload_shadow_enable(uint32_t timer_periph);
Function descriptions	enable the auto reload shadow function
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i> (<i>x</i> =0, 2, 5, 13..16)	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the TIMER0 auto reload shadow function */
```

```
timer_auto_reload_shadow_enable (TIMER0);
```

timer_auto_reload_shadow_disable

The description of timer_auto_reload_shadow_disable is shown as below:

Table 3-390. Function timer_auto_reload_shadow_disable

Function name	timer_auto_reload_shadow_disable
Function prototype	void timer_auto_reload_shadow_disable (uint32_t timer_periph);
Function descriptions	disable the auto reload shadow function
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 5, 13..16)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the TIMERO auto reload shadow function */
```

```
timer_auto_reload_shadow_disable (TIMER0);
```

timer_update_event_enable

The description of timer_update_event_enable is shown as below:

Table 3-391. Function timer_update_event_enable

Function name	timer_update_event_enable
Function prototype	void timer_update_event_enable(uint32_t timer_periph);
Function descriptions	enable the update event
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral

<i>TIMERx</i> (<i>x</i> =0, 2, 5, 13..16)	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable TIMER0 the update event */
```

```
timer_update_event_enable (TIMER0);
```

timer_update_event_disable

The description of timer_update_event_disable is shown as below:

Table 3-392. Function timer_update_event_disable

Function name	timer_update_event_disable
Function prototype	void timer_update_event_disable (uint32_t timer_periph);
Function descriptions	disable the update event
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i> (<i>x</i> =0, 2, 5, 13..16)	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable TIMER0 the update event */
```

```
timer_update_event_disable (TIMER0);
```


timer_counter_alignment

The description of timer_counter_alignment is shown as below:

Table 3-393. Function timer_counter_alignment

Function name	timer_counter_alignment
Function prototype	void timer_counter_alignment(uint32_t timer_periph, uint16_t aligned);
Function descriptions	set TIMER counter alignment mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMER_x(x=0, 2)</i>	TIMER peripheral selection
Input parameter{in}	
aligned	alignment mode
<i>TIMER_COUNTER_EDGE</i>	No center-aligned mode (edge-aligned mode). The direction of the counter is specified by the DIR bit.
<i>TIMER_COUNTER_COUNTER_DOWN</i>	Center-aligned and counting down assert mode. The counter counts under center aligned and channel is configured in output mode (CHxMS=00 in <i>TIMER_x_CHCTL0</i> register). Only when the counter is counting down, compare interrupt flag of channels can be set.
<i>TIMER_COUNTER_COUNTER_UP</i>	Center-aligned and counting up assert mode. The counter counts under center aligned and channel is configured in output mode (CHxMS=00 in <i>TIMER_x_CHCTL0</i> register). Only when the counter is counting up, compare interrupt flag of channels can be set.
<i>TIMER_COUNTER_COUNTER_BOTH</i>	Center-aligned and counting up/down assert mode. The counter counts under center-aligned and channel is configured in output mode (CHxMS=00 in <i>TIMER_x_CHCTL0</i> register). Both when the counter is counting up and counting down, compare interrupt flag of channels can be set.
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set TIMERO counter center-aligned and counting up assert mode */
```

```
timer_counter_alignment (TIMERO, TIMER_COUNTER_CENTER_UP);
```

timer_counter_up_direction

The description of timer_counter_up_direction is shown as below:

Table 3-394. Function timer_counter_up_direction

Function name	timer_counter_up_direction
Function prototype	void timer_counter_up_direction(uint32_t timer_periph);
Function descriptions	set TIMER counter up direction
Precondition	set TIMER counter no center-aligned mode (edge-aligned mode)
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMER_x(x=0, 2)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set TIMERO counter up direction */
```

```
timer_counter_up_direction (TIMERO);
```

timer_counter_down_direction

The description of timer_counter_down_direction is shown as below:

Table 3-395. timer_counter_down_direction

Function name	timer_counter_down_direction
Function prototype	void timer_counter_down_direction(uint32_t timer_periph);
Function descriptions	set TIMER counter down direction
Precondition	set TIMER counter no center-aligned mode (edge-aligned mode)
The called functions	-

Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set TIMERO counter down direction */
```

```
timer_counter_down_direction (TIMERO);
```

timer_prescaler_config

The description of timer_prescaler_config is shown as below:

Table 3-396. Function timer_prescaler_config

Function name	timer_prescaler_config
Function prototype	void timer_prescaler_config(uint32_t timer_periph, uint16_t prescaler, uint8_t pscreload);
Function descriptions	configure TIMER prescaler
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 5, 13..16)</i>	TIMER peripheral selection
Input parameter{in}	
prescaler	prescaler value (0~65535)
Input parameter{in}	
pscreload	prescaler reload mode
<i>TIMER_PSC_RELOAD_NOW</i>	the prescaler is loaded right now

<i>TIMER_PSC_RELOAD_UPDATE</i>	the prescaler is loaded at the next update event
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 prescaler */
```

```
timer_prescaler_config (TIMER0, 3000, TIMER_PSC_RELOAD_NOW);
```

timer_repetition_value_config

The description of timer_repetition_value_config is shown as below:

Table 3-397. Function timer_repetition_value_config

Function name	timer_repetition_value_config
Function prototype	void timer_repetition_value_config(uint32_t timer_periph, uint16_t repetition);
Function descriptions	configure TIMER repetition register value
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 15, 16)</i>	TIMER peripheral selection
Input parameter{in}	
repetition	the counter repetition value (0~255)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 repetition register value */
```

timer_repetition_value_config (TIMER0, 98);

timer_autoreload_value_config

The description of timer_autoreload_value_config is shown as below:

Table 3-398. Function timer_autoreload_value_config

Function name	timer_autoreload_value_config
Function prototype	void timer_autoreload_value_config(uint32_t timer_periph, uint16_t autoreload);
Function descriptions	configure TIMER autoreload register value
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 5, 13..16)</i>	TIMER peripheral selection
Input parameter{in}	
autoreload	the counter auto-reload value (0-65535)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER autoreload register value */
timer_autoreload_value_config (TIMER0, 3000);
```

timer_counter_value_config

The description of timer_counter_value_config is shown as below:

Table 3-399. Function timer_counter_value_config

Function name	timer_counter_value_config
Function prototype	void timer_counter_value_config(uint32_t timer_periph, uint16_t counter);
Function descriptions	configure TIMER counter register value

Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 5, 13..16)</i>	TIMER peripheral selection
Input parameter{in}	
counter	the counter value (0-65535)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 counter register value */
timer_counter_value_config (TIMER0, 3000);
```

timer_counter_read

The description of timer_counter_read is shown as below:

Table 3-400. Function timer_counter_read

Function name	timer_counter_read
Function prototype	uint32_t timer_counter_read(uint32_t timer_periph);
Function descriptions	read TIMER counter value
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 5, 13..16)</i>	TIMER peripheral selection
Output parameter{out}	
-	-

Return value	
<code>uint32_t</code>	counter value (0~65535)

Example:

```
/* read TIMER0 counter value */
uint32_t i = 0;
i = timer_counter_read (TIMER0);
```

timer_prescaler_read

The description of `timer_prescaler_read` is shown as below:

Table 3-401. Function `timer_prescaler_read`

Function name	<code>timer_prescaler_read</code>
Function prototype	<code>uint16_t timer_prescaler_read(uint32_t timer_periph);</code>
Function descriptions	read TIMER prescaler value
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 5, 13..16)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
<code>uint16_t</code>	prescaler register value (0~65535)

Example:

```
/* read TIMER0 prescaler value */
uint16_t i = 0;
i = timer_prescaler_read (TIMER0);
```

timer_single_pulse_mode_config

The description of `timer_single_pulse_mode_config` is shown as below:

Table 3-402. Function timer_single_pulse_mode_config

Function name	timer_single_pulse_mode_config
Function prototype	void timer_single_pulse_mode_config(uint32_t timer_periph, uint8_t spmode);
Function descriptions	configure TIMER single pulse mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 5, 14..16)</i>	TIMER peripheral selection
Input parameter{in}	
spmode	pulse mode
<i>TIMER_SP_MODE_SINGLE</i>	single pulse mode
<i>TIMER_SP_MODE_REPETITIVE</i>	repetitive pulse mode
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 single pulse mode */
```

```
timer_single_pulse_mode_config (TIMER0, TIMER_SP_MODE_SINGLE);
```

timer_update_source_config

The description of timer_update_source_config is shown as below:

Table 3-403. Function timer_update_source_config

Function name	timer_update_source_config
Function prototype	void timer_update_source_config(uint32_t timer_periph, uint32_t update);
Function descriptions	configure TIMER update source

Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMER_x</i> (<i>x</i> =0, 2, 5, 13..16)	TIMER peripheral selection
Input parameter{in}	
update	update source
<i>TIMER_UPDATE_SRC_GLOBAL</i>	Any of the following events generate an update interrupt or DMA request: <ul style="list-style-type: none"> - The UPG bit is set - The counter generates an overflow or underflow event - The slave mode controller generates an update event
<i>TIMER_UPDATE_SRC_REGULAR</i>	Only counter overflow/underflow generates an update interrupt or DMA request.
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER update only by counter overflow/underflow */
```

```
timer_update_source_config (TIMER0, TIMER_UPDATE_SRC_REGULAR);
```

timer_ocpre_clear_source_config

The description of timer_ocpre_clear_source_config is shown as below:

Table 3-404. Function t timer_ocpre_clear_source_config

Function name	timer_ocpre_clear_source_config
Function prototype	void timer_ocpre_clear_source_config (uint32_t timer_periph, uint8_t ocpreclear);
Function descriptions	configure TIMER OCPRE clear source selection
Precondition	-

The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMER_x(x=0, 2)</i>	TIMER peripheral selection
Input parameter{in}	
ocpreclear	clear source
<i>TIMER_OCPRE_CLEAR_SOURCE_CLR</i>	OCPRE_CLR_INT is connected to the OCPRE_CLR input
<i>TIMER_OCPRE_CLEAR_SOURCE_ETIF</i>	OCPRE_CLR_INT is connected to ETIF
Output parameter{out}	
-	-
Return value	
-	-

例如：

```
/* configure TIMER0 OCPRE_CLR_INT is connected to the OCPRE_CLR input */
timer_ocpre_clear_source_config(TIMER0, TIMER_OCPRE_CLEAR_SOURCE_CLR);
```

timer_interrupt_enable

The description of timer_interrupt_enable is shown as below:

Table 3-405. Function timer_interrupt_enable

Function name	timer_interrupt_enable
Function prototype	void timer_interrupt_enable(uint32_t timer_periph, uint32_t interrupt);
Function descriptions	enable the TIMER interrupt
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral

<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
interrupt	timer interrupt enable source
<i>TIMER_INT_UP</i>	update interrupt enable, <i>TIMERx</i> (x=0, 2, 5, 13..16)
<i>TIMER_INT_CH0</i>	channel 0 interrupt enable, <i>TIMERx</i> (x=0, 2, 13..16)
<i>TIMER_INT_CH1</i>	channel 1 interrupt enable, <i>TIMERx</i> (x=0, 2, 14)
<i>TIMER_INT_CH2</i>	channel 2 interrupt enable, <i>TIMERx</i> (x=0, 2)
<i>TIMER_INT_CH3</i>	channel 3 interrupt enable , <i>TIMERx</i> (x=0, 2)
<i>TIMER_INT_CMT</i>	commutation interrupt enable, <i>TIMERx</i> (x=0, 14..16)
<i>TIMER_INT_TRG</i>	trigger interrupt enable, <i>TIMERx</i> (x=0, 2, 14)
<i>TIMER_INT_BRK</i>	break interrupt enable, <i>TIMERx</i> (x=0, 14..16)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the TIMER0 update interrupt */
timer_interrupt_enable (TIMER0, TIMER_INT_UP);
```

timer_interrupt_disable

The description of `timer_interrupt_disable` is shown as below:

Table 3-406. Function `timer_interrupt_disable`

Function name	<code>timer_interrupt_disable</code>
Function prototype	<code>void timer_interrupt_disable (uint32_t timer_periph, uint32_t interrupt);</code>
Function descriptions	disable the TIMER interrupt
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral

<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
interrupt	timer interrupt disable source
<i>TIMER_INT_UP</i>	update interrupt disable, <i>TIMERx</i> (x=0, 2, 5, 13..16)
<i>TIMER_INT_CH0</i>	channel 0 interrupt disable, <i>TIMERx</i> (x=0, 2, 13..16)
<i>TIMER_INT_CH1</i>	channel 1 interrupt disable, <i>TIMERx</i> (x=0, 2, 14)
<i>TIMER_INT_CH2</i>	channel 2 interrupt disable, <i>TIMERx</i> (x=0, 2)
<i>TIMER_INT_CH3</i>	channel 3 interrupt disable, <i>TIMERx</i> (x=0, 2)
<i>TIMER_INT_CMT</i>	commutation interrupt disable, <i>TIMERx</i> (x=0, 14..16)
<i>TIMER_INT_TRG</i>	trigger interrupt disable, <i>TIMERx</i> (x=0, 2, 14)
<i>TIMER_INT_BRK</i>	break interrupt disable, <i>TIMERx</i> (x=0, 14..16)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the TIMERO update interrupt */
timer_interrupt_disable (TIMERO, TIMER_INT_UP);
```

timer_interrupt_flag_get

The description of `timer_interrupt_flag_get` is shown as below:

Table 3-407. Function `timer_interrupt_flag_get`

Function name	<code>timer_interrupt_flag_get</code>
Function prototype	<code>FlagStatus timer_interrupt_flag_get(uint32_t timer_periph, uint32_t interrupt);</code>
Function descriptions	get timer interrupt flag
Precondition	-
The called functions	-
Input parameter{in}	

timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
interrupt	the timer interrupt bits
<i>TIMER_INT_FLAG_UP</i>	update interrupt flag, <i>TIMERx</i> (<i>x</i> =0, 2, 5, 13..16)
<i>TIMER_INT_FLAG_CH0</i>	channel 0 interrupt flag, <i>TIMERx</i> (<i>x</i> =0, 2, 13..16)
<i>TIMER_INT_FLAG_CH1</i>	channel 1 interrupt flag, <i>TIMERx</i> (<i>x</i> =0, 2, 14)
<i>TIMER_INT_FLAG_CH2</i>	channel 2 interrupt flag, <i>TIMERx</i> <i>TIMERx</i> (<i>x</i> =0, 2)
<i>TIMER_INT_FLAG_CH3</i>	channel 3 interrupt flag, <i>TIMERx</i> <i>TIMERx</i> (<i>x</i> =0, 2)
<i>TIMER_INT_FLAG_CMT</i> <i>T</i>	channel commutation interrupt flag, <i>TIMERx</i> (<i>x</i> =0, 14..16)
<i>TIMER_INT_FLAG_TRG</i>	trigger interrupt flag, <i>TIMERx</i> (<i>x</i> =0, 2, 14)
<i>TIMER_INT_FLAG_BRK</i>	break interrupt flag, <i>TIMERx</i> (<i>x</i> =0, 14..16)
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get TIMER0 update interrupt flag */
```

```
FlagStatus Flag_interrupt = RESET;
```

```
Flag_interrupt = timer_interrupt_flag_get (TIMER0, TIMER_INT_FLAG_UP);
```

timer_interrupt_flag_clear

The description of `timer_interrupt_flag_clear` is shown as below:

Table 3-408. Function `timer_interrupt_flag_clear`

Function name	<code>timer_interrupt_flag_clear</code>
Function prototype	<code>void timer_interrupt_flag_clear(uint32_t timer_periph, uint32_t interrupt);</code>
Function descriptions	clear TIMER interrupt flag
Precondition	-

The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
interrupt	the timer interrupt bits
<i>TIMER_INT_FLAG_UP</i>	update interrupt flag, <i>TIMERx</i> (<i>x</i> =0, 2, 5, 13..16)
<i>TIMER_INT_FLAG_CH0</i>	channel 0 interrupt flag, <i>TIMERx</i> (<i>x</i> =0, 2, 13..16)
<i>TIMER_INT_FLAG_CH1</i>	channel 1 interrupt flag, <i>TIMERx</i> (<i>x</i> =0, 2, 14)
<i>TIMER_INT_FLAG_CH2</i>	channel 2 interrupt flag, <i>TIMERx</i> <i>TIMERx</i> (<i>x</i> =0, 2)
<i>TIMER_INT_FLAG_CH3</i>	channel 3 interrupt flag, <i>TIMERx</i> <i>TIMERx</i> (<i>x</i> =0, 2)
<i>TIMER_INT_FLAG_CMT</i>	channel commutation interrupt flag, <i>TIMERx</i> (<i>x</i> =0, 14..16)
<i>TIMER_INT_FLAG_TRG</i>	trigger interrupt flag, <i>TIMERx</i> (<i>x</i> =0, 2, 14)
<i>TIMER_INT_FLAG_BRK</i>	break interrupt flag, <i>TIMERx</i> (<i>x</i> =0, 14..16)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear TIMER0 update interrupt flag */
```

```
timer_interrupt_flag_clear (TIMER0, TIMER_INT_FLAG_UP);
```

timer_flag_get

The description of `timer_flag_get` is shown as below:

Table 3-409. Function `timer_flag_get`

Function name	timer_flag_get
Function prototype	FlagStatus timer_flag_get(uint32_t timer_periph, uint32_t flag);
Function descriptions	get TIMER flags

Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
flag	the timer interrupt flags
<i>TIMER_FLAG_UP</i>	update flag, <i>TIMERx</i> (<i>x</i> =0, 2, 5, 13..16)
<i>TIMER_FLAG_CH0</i>	channel 0 flag, <i>TIMERx</i> (<i>x</i> =0, 2, 13..16)
<i>TIMER_FLAG_CH1</i>	channel 1 flag, <i>TIMERx</i> (<i>x</i> =0, 2, 14)
<i>TIMER_FLAG_CH2</i>	channel 2 flag, <i>TIMERx</i> (<i>x</i> =0, 2)
<i>TIMER_FLAG_CH3</i>	channel 3 flag, <i>TIMERx</i> (<i>x</i> =0, 2)
<i>TIMER_FLAG_CMT</i>	channel commutation flag, <i>TIMERx</i> (<i>x</i> =0, 14..16)
<i>TIMER_FLAG_TRG</i>	trigger flag, <i>TIMERx</i> (<i>x</i> =0, 2, 14)
<i>TIMER_FLAG_BRK</i>	break flag, <i>TIMERx</i> (<i>x</i> =0, 14..16)
<i>TIMER_FLAG_CH00</i>	channel 0 overcapture flag, <i>TIMERx</i> (<i>x</i> =0, 2, 3..16)
<i>TIMER_FLAG_CH10</i>	channel 1 overcapture flag, <i>TIMERx</i> (<i>x</i> =0, 2, 14)
<i>TIMER_FLAG_CH20</i>	channel 2 overcapture flag, <i>TIMERx</i> (<i>x</i> =0, 2)
<i>TIMER_FLAG_CH30</i>	channel 3 overcapture flag, <i>TIMERx</i> (<i>x</i> =0, 2)
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get TIMER0 update flags */
```

```
FlagStatus Flag_status = RESET;
```

```
Flag_status = timer_flag_get (TIMER0, TIMER_FLAG_UP);
```

timer_flag_clear

The description of timer_flag_clear is shown as below:

Table 3-410. Function timer_flag_clear

Function name	timer_flag_clear
Function prototype	void timer_flag_clear(uint32_t timer_periph, uint32_t flag);
Function descriptions	clear TIMER flags
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
flag	the timer interrupt flags
<i>TIMER_FLAG_UP</i>	update flag, TIMERx(x=0, 2, 5, 13..16)
<i>TIMER_FLAG_CH0</i>	channel 0 flag, TIMERx(x=0, 2, 13..16)
<i>TIMER_FLAG_CH1</i>	channel 1 flag, TIMERx(x=0, 2, 14)
<i>TIMER_FLAG_CH2</i>	channel 2 flag, TIMERx(x=0, 2)
<i>TIMER_FLAG_CH3</i>	channel 3 flag, TIMERx(x=0, 2)
<i>TIMER_FLAG_CMT</i>	channel commutation flag, TIMERx(x=0, 14..16)
<i>TIMER_FLAG_TRG</i>	trigger flag, TIMERx(x=0, 2, 14)
<i>TIMER_FLAG_BRK</i>	break flag, TIMERx(x=0, 14..16)
<i>TIMER_FLAG_CH00</i>	channel 0 overcapture flag, TIMERx(x=0, 2, 13..16)
<i>TIMER_FLAG_CH10</i>	channel 1 overcapture flag, TIMERx(x=0, 2, 14)
<i>TIMER_FLAG_CH20</i>	channel 2 overcapture flag, TIMERx(x=0, 2)
<i>TIMER_FLAG_CH30</i>	channel 3 overcapture flag, TIMERx(x=0, 2)
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* clear TIMER0 update flags */
```

```
timer_flag_clear (TIMER0, TIMER_FLAG_UP);
```

timer_dma_enable

The description of timer_dma_enable is shown as below:

Table 3-411. Function timer_dma_enable

Function name	timer_dma_enable
Function prototype	void timer_dma_enable(uint32_t timer_periph, uint16_t dma);
Function descriptions	enable the TIMER DMA
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
dma	timer DMA source enable
<i>TIMER_DMA_UPD</i>	update DMA enable, TIMERx(x=0, 2, 5, 14..16)
<i>TIMER_DMA_CH0D</i>	channel 0 DMA enable, TIMERx(x=0, 2, 14..16)
<i>TIMER_DMA_CH1D</i>	channel 1 DMA enable, TIMERx(x=0..2, 4)
<i>TIMER_DMA_CH2D</i>	channel 2 DMA enable, TIMERx(x=0, 2)
<i>TIMER_DMA_CH3D</i>	channel 3 DMA enable, TIMERx(x=0, 2)
<i>TIMER_DMA_CMTD</i>	commutation DMA request enable, TIMERx(x=0, 14)
<i>TIMER_DMA_TRGD</i>	trigger DMA enable, TIMERx(x=0..2, 14)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable the TIMER0 update DMA */
```

```
timer_dma_enable (TIMER0, TIMER_DMA_UPD);
```

timer_dma_disable

The description of timer_dma_disable is shown as below:

Table 3-412. Function timer_dma_disable

Function name	timer_dma_disable
Function prototype	void timer_dma_disable (uint32_t timer_periph, uint16_t dma);
Function descriptions	disable the TIMER DMA
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
dma	timer DMA source disable
<i>TIMER_DMA_UPD</i>	update DMA enable, TIMERx(x=0, 2, 5, 14..16)
<i>TIMER_DMA_CH0D</i>	channel 0 DMA enable, TIMERx(x=0, 2, 14..16)
<i>TIMER_DMA_CH1D</i>	channel 1 DMA enable, TIMERx(x=0..2, 14)
<i>TIMER_DMA_CH2D</i>	channel 2 DMA enable, TIMERx(x=0, 2)
<i>TIMER_DMA_CH3D</i>	channel 3 DMA enable, TIMERx(x=0, 2)
<i>TIMER_DMA_CMTD</i>	commutation DMA request enable, TIMERx(x=0, 14)
<i>TIMER_DMA_TRGD</i>	trigger DMA enable, TIMERx(x=0..2, 14)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable the TIMERO update DMA */
```

```
timer_dma_disable (TIMER0, TIMER_DMA_UPD);
```

timer_channel_dma_request_source_select

The description of timer_channel_dma_request_source_select is shown as below:

Table 3-413. Function timer_channel_dma_request_source_select

Function name	timer_channel_dma_request_source_select
Function prototype	void timer_channel_dma_request_source_select(uint32_t timer_periph, uint32_t dma_request);
Function descriptions	channel DMA request source selection
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 14,.. 16)</i>	TIMER peripheral selection
Input parameter{in}	
dma_request	channel DMA request source selection
<i>TIMER_DMAREQUEST_CHANNELEVENT</i>	DMA request of channel n is sent when channel y event occurs
<i>TIMER_DMAREQUEST_UPDATEEVENT</i>	DMA request of channel n is sent when update event occurs
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* TIMER0 channel DMA request of channel n is sent when channel y event occurs */
```

```
timer_channel_dma_request_source_select(TIMER0,
TIMER_DMAREQUEST_CHANNELEVENT);
```

timer_dma_transfer_config

The description of timer_dma_transfer_config is shown as below:

Table 3-414. Function timer_dma_transfer_config

Function name	timer_dma_transfer_config
Function prototype	void timer_dma_transfer_config(uint32_t timer_periph, uint32_t dma_baseaddr, uint32_t dma_lenth);
Function descriptions	configure the TIMER DMA transfer
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 14,.. 16)</i>	TIMER peripheral selection
Input parameter{in}	
dma_baseaddr	DMA transfer access start address
<i>TIMER_DMACFG_DMA TA_CTL0</i>	DMA transfer address is TIMER_CTL0, TIMERx(x=0, 2, 14..16)
<i>TIMER_DMACFG_DMA TA_CTL1</i>	DMA transfer address is TIMER_CTL1, TIMERx(x=0, 2, 14..16)
<i>TIMER_DMACFG_DMA TA_SMCFG</i>	DMA transfer address is TIMER_SMCFG, TIMERx(x=0, 2, 14)
<i>TIMER_DMACFG_DMA TA_DMAINTEN</i>	DMA transfer address is TIMER_DMAINTEN, TIMERx(x=0, 2, 14..16)
<i>TIMER_DMACFG_DMA TA_INTF</i>	DMA transfer address is TIMER_INTF, TIMERx(x=0, 2, 14..16)
<i>TIMER_DMACFG_DMA TA_SWEVG</i>	DMA transfer address is TIMER_SWEVG, TIMERx(x=0, 2, 14..16)
<i>TIMER_DMACFG_DMA TA_CHCTL0</i>	DMA transfer address is TIMER_CHCTL0, TIMERx(x=0, 2, 14..16)
<i>TIMER_DMACFG_DMA TA_CHCTL1</i>	DMA transfer address is TIMER_CHCTL1, TIMERx(x=0, 2)
<i>TIMER_DMACFG_DMA TA_CHCTL2</i>	DMA transfer address is TIMER_CHCTL2, TIMERx (x=0, 2, 14..16)
<i>TIMER_DMACFG_DMA TA_CNT</i>	DMA transfer address is TIMER_CNT, TIMERx (x=0, 2, 14..16)

<i>TIMER_DMACFG_DMA TA_PSC</i>	DMA transfer address is TIMER_PSC, TIMERx (x=0, 2, 14..16)
<i>TIMER_DMACFG_DMA TA_CAR</i>	MA transfer address is TIMER_CAR, TIMERx (x=0, 2, 14..16)
<i>TIMER_DMACFG_DMA TA_CREP</i>	DMA transfer address is TIMER_CREP, TIMERx (x=0, 14..16)
<i>TIMER_DMACFG_DMA TA_CH0CV</i>	DMA transfer address is TIMER_CH0CV, TIMERx (x=0, 2, 14..16)
<i>TIMER_DMACFG_DMA TA_CH1CV</i>	DMA transfer address is TIMER_CH1CV, TIMERx(x=0, 2, 14)
<i>TIMER_DMACFG_DMA TA_CH2CV</i>	DMA transfer address is TIMER_CH2CV, TIMERx(x=0, 2)
<i>TIMER_DMACFG_DMA TA_CH3CV</i>	DMA transfer address is TIMER_CH3CV, TIMERx(x=0, 2)
<i>TIMER_DMACFG_DMA TA_CCHP</i>	DMA transfer address is TIMER_CCHP, TIMERx (x=0, 14..16)
<i>TIMER_DMACFG_DMA TA_DMACFG</i>	DMA transfer address is TIMER_DMACFG, TIMERx (x=0, 2, 14..16)
Input parameter{in}	
dma_lenth	DMA transfer count
<i>TIMER_DMACFG_DMA TC_xTRANSFER</i>	x=1..18, DMA transfer x time
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure the TIMER0 DMA transfer */
```

```
timer_dma_transfer_config(TIMER0, TIMER_DMACFG_DMATA_CTL0,  
TIMER_DMACFG_DMATC_5TRANSFER);
```

timer_event_software_generate

The description of timer_event_software_generate is shown as below:

Table 3-415. Function timer_event_software_generate

Function name	timer_event_software_generate
Function prototype	void timer_event_software_generate(uint32_t timer_periph, uint16_t event);
Function descriptions	software generate events
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
event	the timer software event generation sources
<i>TIMER_EVENT_SRC_UPDATE</i>	update event, TIMERx(x=0, 2, 5, 13..16)
<i>TIMER_EVENT_SRC_C0G</i>	channel 0 capture or compare event generation, TIMERx(x=0, 2, 13..16)
<i>TIMER_EVENT_SRC_C1G</i>	channel 1 capture or compare event generation, TIMERx(x=0, 2, 14)
<i>TIMER_EVENT_SRC_C2G</i>	channel 2 capture or compare event generation, TIMERx(x=0, 2)
<i>TIMER_EVENT_SRC_C3G</i>	channel 3 capture or compare event generation, TIMERx(x=0, 2)
<i>TIMER_EVENT_SRC_CMTG</i>	channel commutation event generation, TIMERx(x=0, 14..16)
<i>TIMER_EVENT_SRC_TRIGGER</i>	trigger event generation, TIMERx(x=0, 2, 14)
<i>TIMER_EVENT_SRC_BREAK</i>	break event generation, TIMERx(x=0, 14..16)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* software generate update event*/
```

```
timer_event_software_generate (TIMER0, TIMER_EVENT_SRC_UPG);
```

timer_break_struct_para_init

The description of timer_break_struct_para_init is shown as below:

Table 3-416. Function timer_break_struct_para_init

Function name	timer_break_struct_para_init
Function prototype	void timer_break_struct_para_init(timer_break_parameter_struct* breakpara);
Function descriptions	initialize the parameters of TIMER break parameter struct with the default values
Precondition	-
The called functions	-
Input parameter{in}	
breakpara	TIMER break parameter struct, the structure members can refer to Table 3-381. Structure timer break parameter struct.
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* initialize TIMER break parameter struct with a default value */
```

```
timer_break_parameter_struct timer_breakpara;
```

```
timer_break_struct_para_init(timer_breakpara);
```

timer_break_config

The description of timer_break_config is shown as below:

Table 3-417. Function timer_break_config

Function name	timer_break_config
Function prototype	void timer_break_config(uint32_t timer_periph,

	timer_break_parameter_struct* breakpara);
Function descriptions	configure TIMER break function
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 14..16)</i>	TIMER peripheral selection
Input parameter{in}	
breakpara	TIMER break parameter struct, the structure members can refer to Table 3-381. Structure timer_break_parameter_struct.
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* configure TIMER0 break function */
timer_break_parameter_struct timer_breakpara;

timer_breakpara.runoffstate      = TIMER_ROS_STATE_DISABLE;
timer_breakpara.ideloffstate     = TIMER_IOS_STATE_DISABLE ;
timer_breakpara.deadtime         = 255;
timer_breakpara.breakpolarity    = TIMER_BREAK_POLARITY_LOW;
timer_breakpara.outputautostate  = TIMER_OUTAUTO_ENABLE;
timer_breakpara.protectmode      = TIMER_CCHP_PROT_0;
timer_breakpara.breakstate       = TIMER_BREAK_ENABLE;

timer_break_config(TIMER0, &timer_breakpara);

```

timer_break_enable

The description of timer_break_enable is shown as below:

Table 3-418. Function timer_break_enable

Function name	timer_break_enable
----------------------	--------------------

Function prototype	void timer_break_enable(uint32_t timer_periph);
Function descriptions	enable TIMER break function
Precondition	This function can be called only when PROT [1:0] bit-filed in TIMERx_CCHP register is 00.
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 14..16)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable TIMER0 break function*/
```

```
timer_break_enable (TIMER0);
```

timer_break_disable

The description of timer_break_disable is shown as below:

Table 3-419. Function timer_break_disable

Function name	timer_break_disable
Function prototype	void timer_break_disable(uint32_t timer_periph);
Function descriptions	disable TIMER break function
Precondition	This function can be called only when PROT [1:0] bit-filed in TIMERx_CCHP register is 00.
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 14..16)</i>	TIMER peripheral selection
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* disable TIMER0 break function*/
timer_break_disable (TIMER0);
```

timer_automatic_output_enable

The description of timer_automatic_output_enable is shown as below:

Table 3-420. Function timer_automatic_output_enable

Function name	timer_automatic_output_enable
Function prototype	void timer_automatic_output_enable(uint32_t timer_periph);
Function descriptions	enable TIMER output automatic function
Precondition	This function can be called only when PROT [1:0] bit-filed in TIMERx_CCHP register is 00.
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 14..16)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable TIMER0 output automatic function */
timer_automatic_output_enable (TIMER0);
```

timer_automatic_output_disable

The description of timer_automatic_output_disable is shown as below:

Table 3-421. Function timer_automatic_output_disable

Function name	timer_automatic_output_disable
----------------------	--------------------------------

Function prototype	void timer_automatic_output_disable (uint32_t timer_periph);
Function descriptions	disable TIMER output automatic function
Precondition	This function can be called only when PROT [1:0] bit-filed in TIMERx_CCHP register is 00.
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 14..16)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable TIMER0 output automatic function */
```

```
timer_automatic_output_disable (TIMER0);
```

timer_primary_output_config

The description of timer_primary_output_config is shown as below:

Table 3-422. Function timer_primary_output_config

Function name	timer_primary_output_config
Function prototype	void timer_primary_output_config(uint32_t timer_periph, ControlStatus newvalue);
Function descriptions	configure TIMER primary output function
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 14..16)</i>	TIMER peripheral selection
Input parameter{in}	
newvalue	control value

<i>ENABLE</i>	enable function
<i>DISABLE</i>	disable function
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable TIMERO primary output function */
```

```
timer_primary_output_config (TIMER0, ENABLE);
```

timer_channel_control_shadow_config

The description of timer_channel_control_shadow_config is shown as below:

Table 3-423. Function timer_channel_control_shadow_config

Function name	timer_channel_control_shadow_config
Function prototype	void timer_channel_control_shadow_config(uint32_t timer_periph, ControlStatus newvalue);
Function descriptions	channel commutation control shadow register enable
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMER_x</i> (<i>x</i> =0, 14..16)	TIMER peripheral selection
Input parameter{in}	
newvalue	control value
<i>ENABLE</i>	enable function
<i>DISABLE</i>	disable function
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* channel capture/compare control shadow register enable */
```

```
timer_channel_control_shadow_config (TIMER0, ENABLE);
```

timer_channel_control_shadow_update_config

The description of timer_channel_control_shadow_update_config is shown as below:

Table 3-424. Function timer_channel_control_shadow_update_config

Function name	timer_channel_control_shadow_update_config
Function prototype	void timer_channel_control_shadow_update_config(uint32_t timer_periph, uint8_t ccuctl);
Function descriptions	configure commutation control shadow register update control
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMER_x(x=0, 14..16)</i>	TIMER peripheral selection
Input parameter{in}	
ccuctl	channel control shadow register update control
<i>TIMER_UPDATECTL_CCU</i>	the shadow registers update by when CMTG bit is set
<i>TIMER_UPDATECTL_CUTRI</i>	the shadow registers update by when CMTG bit is set or an rising edge of TRGI occurs
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel control shadow register update when CMTG bit is set */
```

```
timer_channel_control_shadow_update_config (TIMER0, TIMER_UPDATECTL_CCU);
```

timer_channel_output_struct_para_init

The description of timer_channel_output_struct_para_init is shown as below:

Table 3-425. Function timer_channel_output_struct_para_init

Function name	timer_channel_output_struct_para_init
Function prototype	void timer_channel_output_struct_para_init(timer_oc_parameter_struct* ocpa);
Function descriptions	initialize the parameters of TIMER channel output parameter struct with the default values
Precondition	-
The called functions	-
Input parameter{in}	
ocpara	TIMER channel output parameter struct, the structure members can refer to Table 3-382. Structure timer oc parameter struct.
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* initialize TIMER channel output parameter struct with a default value */
timer_oc_parameter_struct timer_ocinitpara;
timer_channel_output_struct_para_init(timer_ocinitpara);

```

timer_channel_output_config

The description of timer_channel_output_config is shown as below:

Table 3-426. Function timer_channel_output_config

Function name	timer_channel_output_config
Function prototype	void timer_channel_output_config(uint32_t timer_periph, uint16_t channel, timer_oc_parameter_struct* ocpa);
Function descriptions	configure TIMER channel output function
Precondition	-
The called functions	-

Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx(x=0, 2, 13..16))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx(x=0, 2, 14))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx(x=0, 2))
<i>TIMER_CH_3</i>	IMER channel 3 (TIMERx(x=0, 2))
Input parameter{in}	
ocpara	TIMER channel output parameter struct, the structure members can refer to Table 3-382. Structure timer oc parameter struct.
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* configure TIMER0 channel 0 output function */
timer_oc_parameter_struct timer_ocinitpara;
timer_ocinitpara.outputstate = TIMER_CCX_ENABLE;
timer_ocinitpara.outputnstate = TIMER_CCXN_ENABLE;
timer_ocinitpara.ocpolarity = TIMER_OC_POLARITY_HIGH;
timer_ocinitpara.ocnpolarity = TIMER_OCN_POLARITY_HIGH;
timer_ocinitpara.ocidlestate = TIMER_OC_IDLE_STATE_HIGH;
timer_ocinitpara.ocnidlestate = TIMER_OCN_IDLE_STATE_LOW;
timer_channel_output_config(TIMER0, TIMER_CH_0, &timer_ocinitpara);

```

timer_channel_output_mode_config

The description of timer_channel_output_mode_config is shown as below:

Table 3-427. Function timer_channel_output_mode_config

Function name	timer_channel_output_mode_config
Function prototype	void timer_channel_output_mode_config(uint32_t timer_periph, uint16_t channel, uint16_t ocmode);
Function descriptions	configure TIMER channel output compare mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx (x=0, 2, 13..16))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx (x=0, 2, 14))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx (x=0, 2))
<i>TIMER_CH_3</i>	IMER channel 3 (TIMERx (x=0, 2))
Input parameter{in}	
ocmode	channel output compare mode
<i>TIMER_OC_MODE_TIMING</i>	timing mode
<i>TIMER_OC_MODE_ACTIVE</i>	set the channel output
<i>TIMER_OC_MODE_INACTIVE</i>	clear the channel output
<i>TIMER_OC_MODE_TOGGLE</i>	toggle on match
<i>TIMER_OC_MODE_LOW</i>	force low mode
<i>TIMER_OC_MODE_HIGH</i>	force high mode
<i>TIMER_OC_MODE_PWM</i>	PWM mode 0

<i>M0</i>	
<i>TIMER_OC_MODE_PWM</i> <i>M1</i>	PWM mode 1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel PWM 0 mode */
```

```
timer_channel_output_mode_config(TIMER0, TIMER_CH_0, TIMER_OC_MODE_PWM0);
```

timer_channel_output_pulse_value_config

The description of timer_channel_output_pulse_value_config is shown as below:

Table 3-428. Function timer_channel_output_pulse_value_config

Function name	timer_channel_output_pulse_value_config
Function prototype	void timer_channel_output_pulse_value_config(uint32_t timer_periph, uint16_t channel, uint32_t pulse);
Function descriptions	configure TIMER channel output pulse value
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx (x=0, 2, 13..16))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx (x=0, 2, 14))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx (x=0, 2))
<i>TIMER_CH_3</i>	TIMER channel 3 (TIMERx (x=0, 2))
Input parameter{in}	

pulse	channel output pulse value (0~65535)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 output pulse value */
```

```
timer_channel_output_pulse_value_config(TIMER0, TIMER_CH_0, 399);
```

timer_channel_output_shadow_config

The description of timer_channel_output_shadow_config is shown as below:

Table 3-429. Function timer_channel_output_shadow_config

Function name	timer_channel_output_shadow_config
Function prototype	void timer_channel_output_shadow_config(uint32_t timer_periph, uint16_t channel, uint16_t ocshadow);
Function descriptions	configure TIMER channel output shadow function
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx (x=0, 2, 13..16))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx (x=0, 2, 14))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx (x=0, 2))
<i>TIMER_CH_3</i>	IMER channel 3 (TIMERx (x=0, 2))
Input parameter{in}	
ocshadow	channel output shadow state

<i>TIMER_OC_SHADOW_ENABLE</i>	channel output shadow state enable
<i>TIMER_OC_SHADOW_DISABLE</i>	channel output shadow state disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/*configure TIMER0 channel 0 output shadow function */
timer_channel_output_shadow_config (TIMER0, TIMER_CH_0,
TIMER_OC_SHADOW_ENABLE);
  
```

timer_channel_output_fast_config

The description of timer_channel_output_fast_config is shown as below:

Table 3-430. Function timer_channel_output_fast_config

Function name	timer_channel_output_fast_config
Function prototype	void timer_channel_output_fast_config(uint32_t timer_periph, uint16_t channel, uint16_t ocfast);
Function descriptions	configure TIMER channel output fast function
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx (x=0, 2, 13..16))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx (x=0, 2, 14))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx (x=0, 2))

<i>TIMER_CH_3</i>	TIMER channel 3 (TIMERx (x=0, 2))
Input parameter{in}	
ocfast	channel output fast function
<i>TIMER_OC_FAST_ENABLE</i>	channel output fast function enable
<i>TIMER_OC_FAST_DISABLE</i>	channel output fast function disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 output fast function */
```

```
timer_channel_output_fast_config (TIMER0, TIMER_CH_0, TIMER_OC_FAST_ENABLE);
```

timer_channel_output_clear_config

The description of timer_channel_output_clear_config is shown as below:

Table 3-431. Function timer_channel_output_clear_config

Function name	timer_channel_output_clear_config
Function prototype	void timer_channel_output_clear_config(uint32_t timer_periph, uint16_t channel, uint16_t occlear);
Function descriptions	configure TIMER channel output clear function
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER periphera
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx (x=0, 2))

<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx (x=0, 2))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx (x=0, 2))
<i>TIMER_CH_3</i>	TIMER channel 3 (TIMERx (x=0, 2))
Input parameter{in}	
occlear	channel output clear function
<i>TIMER_OC_CLEAR_ENABLE</i>	channel output clear function enable
<i>TIMER_OC_CLEAR_DISABLE</i>	channel output clear function disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 output clear function */
timer_channel_output_clear_config (TIMER0, TIMER_CH_0,
TIMER_OC_CLEAR_ENABLE);
```

timer_channel_output_polarity_config

The description of timer_channel_output_polarity_config is shown as below:

Table 3-432. Function timer_channel_output_polarity_config

Function name	timer_channel_output_polarity_config
Function prototype	void timer_channel_output_polarity_config(uint32_t timer_periph, uint16_t channel, uint16_t ocpolarity);
Function descriptions	configure TIMER channel output polarity
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters

Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0 (TIMERx (x=0, 2, 13..16))
<i>TIMER_CH_1</i>	TIMER channel 1 (TIMERx (x=0, 2, 14))
<i>TIMER_CH_2</i>	TIMER channel 2 (TIMERx(x=0, 2))
<i>TIMER_CH_3</i>	IMER channel 3 (TIMERx (x=0, 2))
Input parameter{in}	
ocpolarity	channel output polarity
<i>TIMER_OC_POLARITY_HIGH</i>	channel output polarity is high
<i>TIMER_OC_POLARITY_LOW</i>	channel output polarity is low
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 output polarity */
```

```
timer_channel_output_polarity_config (TIMER0, TIMER_CH_0,  
TIMER_OC_POLARITY_HIGH);
```

timer_channel_complementary_output_polarity_config

The description of timer_channel_complementary_output_polarity_config is shown as below:

Table 3-433. Function timer_channel_complementary_output_polarity_config

Function name	timer_channel_complementary_output_polarity_config
Function prototype	void timer_channel_complementary_output_polarity_config(uint32_t timer_periph, uint16_t channel, uint16_t ocnpolarity);
Function descriptions	configure TIMER channel complementary output polarity
Precondition	-
The called functions	-

Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	TIMER peripheral selection
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0(TIMERx (x=0, 2, 13..16))
<i>TIMER_CH_1</i>	TIMER channel 1(TIMERx (x=0, 2, 14))
<i>TIMER_CH_2</i>	TIMER channel 2(TIMERx (x=0, 2))
<i>TIMER_CH_3</i>	TIMER channel 3(TIMERx (x=0, 2))
Input parameter{in}	
ocpolarity	channel complementary output polarity
<i>TIMER_OCN_POLARITY_HIGH</i>	channel complementary output polarity is high
<i>TIMER_OCN_POLARITY_LOW</i>	channel complementary output polarity is low
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 complementary output polarity */
```

```
timer_channel_complementary_output_polarity_config (TIMER0, TIMER_CH_0,  
TIMER_OCN_POLARITY_HIGH);
```

timer_channel_output_state_config

The description of timer_channel_output_state_config is shown as below:

Table 3-434. Function timer_channel_output_state_config

Function name	timer_channel_output_state_config
Function prototype	void timer_channel_output_state_config(uint32_t timer_periph, uint16_t channel, uint32_t state);

Function descriptions	configure TIMER channel enable state
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0(TIMERx (x=0, 2, 13..16))
<i>TIMER_CH_1</i>	TIMER channel 1(TIMERx (x=0, 2, 14))
<i>TIMER_CH_2</i>	TIMER channel 2(TIMERx (x=0, 2))
<i>TIMER_CH_3</i>	TIMER channel 3(TIMERx (x=0, 2))
Input parameter{in}	
state	TIMER channel enable state
<i>TIMER_CCX_ENABLE</i>	channel enable
<i>TIMER_CCX_DISABLE</i>	channel disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 enable state */
```

```
timer_channel_output_state_config (TIMER0, TIMER_CH_0, TIMER_CCX_ENABLE);
```

timer_channel_complementary_output_state_config

The description of timer_channel_complementary_output_state_config is shown as below:

Table 3-435. Function timer_channel_complementary_output_state_config

Function name	timer_channel_complementary_output_state_config
Function prototype	void timer_channel_complementary_output_state_config(uint32_t

	timer_periph, uint16_t channel, uint16_t ocnstate);
Function descriptions	configure TIMER channel complementary output enable state
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 14,..16)</i>	TIMER peripheral selection
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0, <i>TIMERx (x=0, 14..16)</i>
<i>TIMER_CH_1</i>	TIMER channel 1, <i>TIMERx (x=0)</i>
<i>TIMER_CH_2</i>	TIMER channel 2, <i>TIMERx (x=0)</i>
Input parameter{in}	
state	TIMER channel complementary output enable state
<i>TIMER_CCXN_ENABLE</i>	channel complementary enable
<i>TIMER_CCXN_DISABLE</i>	channel complementary disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* configure TIMER0 channel 0 complementary output enable state */
timer_channel_complementary_output_state_config (TIMER0, TIMER_CH_0,
TIMER_CCXN_ENABLE);

```

timer_channel_input_struct_para_init

The description of timer_channel_input_struct_para_init is shown as below:

Table 3-436. Function timer_channel_input_struct_para_init

Function name	timer_channel_input_struct_para_init
----------------------	--------------------------------------

Function prototype	void timer_channel_input_struct_para_init(timer_ic_parameter_struct* icpara);
Function descriptions	initialize the parameters of TIMER channel input parameter struct with the default values
Precondition	-
The called functions	-
Input parameter{in}	
icpara	TIMER channel input parameter struct, the structure members can refer to Table 3-383. Structure timer ic parameter struct .
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* initialize TIMER channel input parameter struct with a default value */
timer_ic_parameter_struct timer_icinitpara;
timer_channel_input_struct_para_init(&timer_icinitpara);

```

timer_input_capture_config

The description of timer_input_capture_config is shown as below:

Table 3-437. Function timer_input_capture_config

Function name	timer_input_capture_config
Function prototype	void timer_input_capture_config(uint32_t timer_periph, uint16_t channel, timer_ic_parameter_struct* icpara);
Function descriptions	configure TIMER input capture parameter
Precondition	-
The called functions	timer_channel_input_capture_prescaler_config
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters

Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0(TIMERx (x=0, 2, 13..16))
<i>TIMER_CH_1</i>	TIMER channel 1(TIMERx (x=0, 2, 14))
<i>TIMER_CH_2</i>	TIMER channel 2(TIMERx (x=0, 2))
<i>TIMER_CH_3</i>	TIMER channel 3(TIMERx (x=0, 2))
Input parameter{in}	
icpara	TIMER channel input parameter struct, the structure members can refer to Table 3-383. Structure timer_ic_parameter_struct .
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* configure TIMER0 input capture parameter */
timer_ic_parameter_struct timer_icinitpara;
timer_icinitpara.icpolarity = TIMER_IC_POLARITY_RISING;
timer_icinitpara.icselection = TIMER_IC_SELECTION_DIRECTTI;
timer_icinitpara.icprescaler = TIMER_IC_PSC_DIV1;
timer_icinitpara.icfilter = 0x0;
timer_input_capture_config(TIMER0, TIMER_CH_0, &timer_icinitpara);

```

timer_channel_input_capture_prescaler_config

The description of timer_channel_input_capture_prescaler_config is shown as below:

Table 3-438. Function timer_channel_input_capture_prescaler_config

Function name	timer_channel_input_capture_prescaler_config
Function prototype	void timer_channel_input_capture_prescaler_config(uint32_t timer_periph, uint16_t channel, uint16_t prescaler);
Function descriptions	configure TIMER channel input capture prescaler value
Precondition	-

The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0(TIMERx (x=0, 2, 13..16))
<i>TIMER_CH_1</i>	TIMER channel 1(TIMERx (x=0, 2, 14))
<i>TIMER_CH_2</i>	TIMER channel 2(TIMERx (x=0, 2))
<i>TIMER_CH_3</i>	TIMER channel 3(TIMERx (x=0, 2))
Input parameter{in}	
prescaler	channel input capture prescaler value
<i>TIMER_IC_PSC_DIV1</i>	no prescaler
<i>TIMER_IC_PSC_DIV2</i>	divided by 2
<i>TIMER_IC_PSC_DIV4</i>	divided by 4
<i>TIMER_IC_PSC_DIV8</i>	divided by 8
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 channel 0 input capture prescaler value */
```

```
timer_channel_input_capture_prescaler_config (TIMER0, TIMER_CH_0,  
TIMER_IC_PSC_DIV2);
```

timer_channel_capture_value_register_read

The description of timer_channel_capture_value_register_read is shown as below:

Table 3-439. Function timer_channel_capture_value_register_read

Function name	timer_channel_capture_value_register_read
----------------------	---

Function prototype	uint32_t timer_channel_capture_value_register_read(uint32_t timer_periph, uint16_t channel);
Function descriptions	read TIMER channel capture compare register value
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx</i>	please refer to the following parameters
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0(TIMERx (x=0, 2, 13..16))
<i>TIMER_CH_1</i>	TIMER channel 1(TIMERx (x=0, 2, 14))
<i>TIMER_CH_2</i>	TIMER channel 2(TIMERx (x=0, 2))
<i>TIMER_CH_3</i>	TIMER channel 3(TIMERx (x=0, 2))
Output parameter{out}	
-	-
Return value	
uint32_t	channel capture compare register value (0~65535)

Example:

```
/* read TIMER0 channel 0 capture compare register value */
```

```
uint32_t ch0_value = 0;
```

```
ch0_value = timer_channel_capture_value_register_read (TIMER0, TIMER_CH_0);
```

timer_input_pwm_capture_config

The description of timer_input_pwm_capture_config is shown as below:

Table 3-440. Function timer_input_pwm_capture_config

Function name	timer_input_pwm_capture_config
Function prototype	void timer_input_pwm_capture_config(uint32_t timer_periph, uint16_t channel, timer_ic_parameter_struct* icpwm);
Function descriptions	configure TIMER input pwm capture function

Precondition	-
The called functions	timer_channel_input_capture_prescaler_config
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 14)</i>	TIMER peripheral selection
Input parameter{in}	
channel	channel to be configured
<i>TIMER_CH_0</i>	TIMER channel 0
<i>TIMER_CH_1</i>	TIMER channel 1
Input parameter{in}	
icpwm	TIMER channel input pwm parameter struct, the structure members can refer to Table 3-383. Structure timer_ic_parameter_struct.
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* configure TIMER0 input pwm capture parameter */
timer_ic_parameter_struct timer_icinitpara;
timer_icinitpara.icpolarity = TIMER_IC_POLARITY_RISING;
timer_icinitpara.icselection = TIMER_IC_SELECTION_DIRECTTTI;
timer_icinitpara.icprescaler = TIMER_IC_PSC_DIV1;
timer_icinitpara.icfilter = 0x0;
timer_input_pwm_capture_config (TIMER0, TIMER_CH_0, &timer_icinitpara);

```

timer_hall_mode_config

The description of timer_hall_mode_config is shown as below:

Table 3-441. Function timer_hall_mode_config

Function name	timer_hall_mode_config
Function prototype	void timer_hall_mode_config(uint32_t timer_periph, uint8_t hallmode);

Function descriptions	configure TIMER hall sensor mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2)</i>	TIMER peripheral selection
Input parameter{in}	
hallmode	TIMER hall sensor mode state
<i>TIMER_HALLINTERFACE_ENABLE</i>	TIMER hall sensor mode enable
<i>TIMER_HALLINTERFACE_DISABLE</i>	TIMER hall sensor mode disable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* configure TIMER0 hall sensor mode */
timer_hall_mode_config (TIMER0, TIMER_HALLINTERFACE_ENABLE);

```

timer_input_trigger_source_select

The description of timer_input_trigger_source_select is shown as below:

Table 3-442. Function timer_input_trigger_source_select

Function name	timer_input_trigger_source_select
Function prototype	void timer_input_trigger_source_select(uint32_t timer_periph, uint32_t intrigger);
Function descriptions	select TIMER input trigger source
Precondition	SMC[2:0] = 000
The called functions	-
Input parameter{in}	

timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 14)</i>	please refer to the following parameters
Input parameter{in}	
intrigger	trigger selection
<i>TIMER_SMCFG_TRGS EL_ITI0</i>	Internal trigger input 0(ITI0, TIMERx(x=0, 2, 14))
<i>TIMER_SMCFG_TRGS EL_ITI1</i>	Internal trigger input 0 (ITI1, TIMERx(x=0, 2, 14))
<i>TIMER_SMCFG_TRGS EL_ITI2</i>	Internal trigger input 0 (ITI2, TIMERx(ITI2, TIMERx(x=0, 2))
<i>TIMER_SMCFG_TRGS EL_ITI3</i>	Internal trigger input 0(ITI3, TIMERx(x=0, 2, 14))
<i>TIMER_SMCFG_TRGS EL_CIOF_ED</i>	CIO edge flag (CIOF_ED, TIMERx(x=0, 2, 14))
<i>TIMER_SMCFG_TRGS EL_CIOFE0</i>	channel 0 input Filtered output(CIOFE0, TIMERx(x=0, 2, 14))
<i>TIMER_SMCFG_TRGS EL_C1FE1</i>	channel 1 input Filtered output(CI1FE1, TIMERx(x=0, 2, 14))
<i>TIMER_SMCFG_TRGS EL_ETIFP</i>	External trigger input filter output(ETIFP, TIMERx(x=0, 2))
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* select TIMER0 input trigger source */
```

```
timer_input_trigger_source_select (TIMER0, TIMER_SMCFG_TRGSEL_ITI0);
```

timer_master_output_trigger_source_select

The description of timer_master_output_trigger_source_select is shown as below:

Table 3-443. Function timer_master_output_trigger_source_select

Function name	timer_master_output_trigger_source_select
----------------------	---

Function prototype	void timer_master_output_trigger_source_select(uint32_t timer_periph, uint32_t outrigger);
Function descriptions	select TIMER master mode output trigger source
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 5, 14)</i>	TIMER peripheral selection
Input parameter{in}	
outrigger	master mode control
<i>TIMER_TRI_OUT_SRC_RESET</i>	Reset. When the UPG bit in the <i>TIMERx_SWEVG</i> register is set or a reset is generated by the slave mode controller, a TRGO pulse occurs. And in the latter case, the signal on TRGO is delayed compared to the actual reset
<i>TIMER_TRI_OUT_SRC_ENABLE</i>	Enable. This mode is useful to start several timers at the same time or to control a window in which a slave timer is enabled. In this mode the master mode controller selects the counter enable signal as TRGO. The counter enable signal is set when CEN control bit is set or the trigger input in pause mode is high. There is a delay between the trigger input in pause mode and the TRGO output, except if the master-slave mode is selected.
<i>TIMER_TRI_OUT_SRC_UPDATE</i>	Update. In this mode the master mode controller selects the update event as TRGO.
<i>TIMER_TRI_OUT_SRC_CH0</i>	Capture/compare pulse. In this mode the master mode controller generates a TRGO pulse when a capture or a compare match occurred in channel 0.
<i>TIMER_TRI_OUT_SRC_O0CPRE</i>	Compare. In this mode the master mode controller selects the O0CPRE signal is used as TRGO.
<i>TIMER_TRI_OUT_SRC_O1CPRE</i>	Compare. In this mode the master mode controller selects the O1CPRE signal is used as TRGO.
<i>TIMER_TRI_OUT_SRC_O2CPRE</i>	Compare. In this mode the master mode controller selects the O2CPRE signal is used as TRGO.
<i>TIMER_TRI_OUT_SRC_O3CPRE</i>	Compare. In this mode the master mode controller selects the O3CPRE signal is used as TRGO.
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* select TIMER0 master mode output trigger source */
timer_master_output_trigger_source_select (TIMER0, TIMER_TRI_OUT_SRC_RESET);
```

timer_slave_mode_select

The description of timer_slave_mode_select is shown as below:

Table 3-444. Function timer_slave_mode_select

Function name	timer_slave_mode_select
Function prototype	void timer_slave_mode_select(uint32_t timer_periph, uint32_t slavemode);
Function descriptions	select TIMER slave mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
TIMERx(x=0, 2, 14)	TIMER peripheral selection
Input parameter{in}	
slavemode	slave mode
TIMER_SLAVE_MODE_DISABLE	slave mode disable, TIMERx(x=0, 2, 14)
TIMER_ENCODER_MODE0	encoder mode 0, TIMERx(x=0, 2)
TIMER_ENCODER_MODE1	encoder mode 1, TIMERx(x=0, 2)
TIMER_ENCODER_MODE2	encoder mode 2, TIMERx(x=0, 2)
TIMER_SLAVE_MODE_RESTART	restart mode, TIMERx(x=0, 2, 14)
TIMER_SLAVE_MODE_PAUSE	pause mode, TIMERx(x=0, 2, 14)

<i>TIMER_SLAVE_MODE_EVENT</i>	event mode, TIMERx(x=0, 2, 14)
<i>TIMER_SLAVE_MODE_EXTERNAL0</i>	external clock mode 0, TIMERx(x=0, 2, 14)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* select TIMER0 slave mode */
```

```
timer_slave_mode_select (TIMER0, TIMER_ENCODER_MODE0);
```

timer_master_slave_mode_config

The description of timer_master_slave_mode_config is shown as below:

Table 3-445. Function timer_master_slave_mode_config

Function name	timer_master_slave_mode_config
Function prototype	void timer_master_slave_mode_config(uint32_t timer_periph, uint8_t masterslave);
Function descriptions	configure TIMER master slave mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
TIMERx(x=0, 2, 14)	TIMER peripheral selection
Input parameter{in}	
masterslave	master slave mode state
<i>TIMER_MASTER_SLAVE_MODE_ENABLE</i>	master slave mode enable
<i>TIMER_MASTER_SLAVE_MODE_DISABLE</i>	master slave mode disable
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* configure TIMER0 master slave mode */
```

```
timer_master_slave_mode_config (TIMER0, TIMER_MASTER_SLAVE_MODE_ENABLE);
```

timer_external_trigger_config

The description of timer_external_trigger_config is shown as below:

Table 3-446. Function timer_external_trigger_config

Function name	timer_external_trigger_config
Function prototype	void timer_external_trigger_config(uint32_t timer_periph, uint32_t extprescaler, uint32_t expolarity, uint32_t extfilter);
Function descriptions	configure TIMER external trigger input
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2)</i>	TIMER peripheral selection
Input parameter{in}	
extprescaler	external trigger prescaler
<i>TIMER_EXT_TRI_PSC_OFF</i>	no divided
<i>TIMER_EXT_TRI_PSC_DIV2</i>	divided by 2
<i>TIMER_EXT_TRI_PSC_DIV4</i>	divided by 4
<i>TIMER_EXT_TRI_PSC_DIV8</i>	divided by 8
Input parameter{in}	
expolarity	external trigger polarity

<i>TIMER_ETP_FALLING</i>	active low or falling edge active
<i>TIMER_ETP_RISING</i>	active high or rising edge active
Input parameter{in}	
extfilter	external trigger filter control (0~15)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 external trigger input */
```

```
timer_external_trigger_config (TIMER0, TIMER_EXT_TRI_PSC_DIV2,  
TIMER_ETP_FALLING, 10);
```

timer_quadrature_decoder_mode_config

The description of timer_quadrature_decoder_mode_config is shown as below:

Table 3-447. Function timer_quadrature_decoder_mode_config

Function name	timer_quadrature_decoder_mode_config
Function prototype	void timer_quadrature_decoder_mode_config(uint32_t timer_periph, uint32_t decomode, uint16_t ic0polarity, uint16_t ic1polarity);
Function descriptions	configure TIMER quadrature decoder mode
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2)</i>	TIMER peripheral selection
Input parameter{in}	
decomode	quadrature decoder mode
<i>TIMER_ENCODER_MO DE0</i>	counter counts on CI0FE0 edge depending on CI1FE1 level
<i>TIMER_ENCODER_MO</i>	counter counts on CI1FE1 edge depending on CI0FE0 level

<i>DE1</i>	
<i>TIMER_ENCODER_MODE2</i>	counter counts on both CI0FE0 and CI1FE1 edges depending on the level of the other input
Input parameter{in}	
ic0polarity	IC0 polarity
<i>TIMER_IC_POLARITY_RISING</i>	capture rising edge
<i>TIMER_IC_POLARITY_FALLING</i>	capture falling edge
Input parameter{in}	
ic1polarity	IC1 polarity
<i>TIMER_IC_POLARITY_RISING</i>	capture rising edge
<i>TIMER_IC_POLARITY_FALLING</i>	capture falling edge
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 quadrature decoder mode */
```

```
timer_quadrature_decoder_mode_config (TIMER0, TIMER_ENCODER_MODE0,
TIMER_IC_POLARITY_RISING, TIMER_IC_POLARITY_RISING);
```

timer_internal_clock_config

The description of timer_internal_clock_config is shown as below:

Table 3-448. Function timer_internal_clock_config

Function name	timer_internal_clock_config
Function prototype	void timer_internal_clock_config(uint32_t timer_periph);
Function descriptions	configure TIMER internal clock mode
Precondition	-

The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 14)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 internal clock mode */
```

```
timer_internal_clock_config (TIMER0);
```

timer_internal_trigger_as_external_clock_config

The description of timer_internal_trigger_as_external_clock_config is shown as below:

Table 3-449. Function timer_internal_trigger_as_external_clock_config

Function name	timer_internal_trigger_as_external_clock_config
Function prototype	void timer_internal_trigger_as_external_clock_config(uint32_t timer_periph, uint32_t intrigger);
Function descriptions	configure TIMER the internal trigger as external clock input
Precondition	-
The called functions	timer_input_trigger_source_select
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 14)</i>	TIMER peripheral selection
Input parameter{in}	
intrigger	trigger selection
<i>TIMER_SMCFG_TRGS_EL_ITI0</i>	Internal trigger input 0 (ITI0), TIMERx(x=0, 2, 14)
<i>TIMER_SMCFG_TRGS_EL_ITI1</i>	Internal trigger input 0 (ITI1), TIMERx(x=0, 2, 14)

<i>TIMER_SMCFG_TRGS</i> <i>EL_ITI2</i>	Internal trigger input 0 (ITI2) , TIMERx(x=0, 2)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 the internal trigger ITI0 as external clock input */
```

```
timer_internal_trigger_as_external_clock_config (TIMER0, TIMER_SMCFG_TRGSEL_ITI0);
```

timer_external_trigger_as_external_clock_config

The description of timer_external_trigger_as_external_clock_config is shown as below:

Table 3-450. Function timer_external_trigger_as_external_clock_config

Function name	timer_external_trigger_as_external_clock_config
Function prototype	void timer_external_trigger_as_external_clock_config(uint32_t timer_periph, uint32_t extrigger, uint16_t expolarity, uint32_t extfilter);
Function descriptions	configure TIMER the external trigger as external clock input
Precondition	-
The called functions	timer_input_trigger_source_select
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 14)</i>	TIMER peripheral selection
Input parameter{in}	
extrigger	external trigger selection
<i>TIMER_SMCFG_TRGS</i> <i>EL_CIOF_ED</i>	CI0 edge flag (CIOF_ED)
<i>TIMER_SMCFG_TRGS</i> <i>EL_CIOFE0</i>	channel 0 input Filtered output (CIOFE0)
<i>TIMER_SMCFG_TRGS</i> <i>EL_C1FE1</i>	channel 1 input Filtered output (C1FE1)
Input parameter{in}	

expolarity	external trigger polarity
<i>TIMER_IC_POLARITY_RISING</i>	active high or rising edge active
<i>TIMER_IC_POLARITY_FALLING</i>	active low or falling edge active
<i>TIMER_IC_POLARITY_BOTH_EDGE</i>	falling edge or rising edge active
Input parameter{in}	
extfilter	external trigger filter control (0~15)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* configure TIMER0 the external trigger CI0FE0 as external clock input */
timer_external_trigger_as_external_clock_config (TIMER0,
TIMER_SMCFG_TRGSEL_CI0FE0, TIMER_IC_POLARITY_RISING, 0);

```

timer_external_clock_mode0_config

The description of timer_external_clock_mode0_config is shown as below:

Table 3-451. Function timer_external_clock_mode0_config

Function name	timer_external_clock_mode0_config
Function prototype	void timer_external_clock_mode0_config(uint32_t timer_periph, uint32_t extprescaler, uint32_t expolarity, uint32_t extfilter);
Function descriptions	configure TIMER the external clock mode0
Precondition	-
The called functions	timer_external_trigger_config
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2)</i>	TIMER peripheral selection
Input parameter{in}	

extprescaler	ETI external trigger prescaler
<i>TIMER_EXT_TRI_PSC_OFF</i>	no divided
<i>TIMER_EXT_TRI_PSC_DIV2</i>	divided by 2
<i>TIMER_EXT_TRI_PSC_DIV4</i>	divided by 4
<i>TIMER_EXT_TRI_PSC_DIV8</i>	divided by 8
Input parameter{in}	
expolarity	ETI external trigger polarity
<i>TIMER_ETP_FALLING</i>	active low or falling edge active
<i>TIMER_ETP_RISING</i>	active high or rising edge active
Input parameter{in}	
extfilter	ETI external trigger filter control (0~15)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 the external clock mode0 */
```

```
timer_external_clock_mode0_config (TIMER0, TIMER_EXT_TRI_PSC_DIV2,  
TIMER_ETP_FALLING, 0);
```

timer_external_clock_mode1_config

The description of timer_external_clock_mode1_config is shown as below:

Table 3-452. Function timer_external_clock_mode1_config

Function name	timer_external_clock_mode1_config
Function prototype	void timer_external_clock_mode1_config(uint32_t timer_periph, uint32_t extprescaler, uint32_t expolarity, uint32_t extfilter);
Function descriptions	configure TIMER the external clock mode1

Precondition	-
The called functions	timer_external_trigger_config
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2)</i>	TIMER peripheral selection
Input parameter{in}	
extprescaler	ETI external trigger prescaler
<i>TIMER_EXT_TRI_PSC_OFF</i>	no divided
<i>TIMER_EXT_TRI_PSC_DIV2</i>	divided by 2
<i>TIMER_EXT_TRI_PSC_DIV4</i>	divided by 4
<i>TIMER_EXT_TRI_PSC_DIV8</i>	divided by 8
Input parameter{in}	
expolarity	ETI external trigger polarity
<i>TIMER_ETP_FALLING</i>	active low or falling edge active
<i>TIMER_ETP_RISING</i>	active high or rising edge active
Input parameter{in}	
extfilter	ETI external trigger filter control (0~15)
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER0 the external clock mode1 */
```

```
timer_external_clock_mode1_config (TIMER0, TIMER_EXT_TRI_PSC_DIV2,  
TIMER_ETP_FALLING, 0);
```

timer_external_clock_mode1_disable

The description of timer_external_clock_mode1_disable is shown as below:

Table 3-453. Function timer_external_clock_mode1_disable

Function name	timer_external_clock_mode1_disable
Function prototype	void timer_external_clock_mode1_disable(uint32_t timer_periph);
Function descriptions	disable TIMER the external clock mode1
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMER_x(x=0, 2)</i>	TIMER peripheral selection
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable TIMER0 the external clock mode1 */
timer_external_clock_mode1_disable (TIMER0);
```

timer_channel_remap_config

The description of timer_channel_remap_config is shown as below:

Table 3-454. Function timer_channel_remap_config

Function name	timer_channel_remap_config
Function prototype	void timer_channel_remap_config (uint32_t timer_periph, uint32_t remap);
Function descriptions	configure TIMER channel remap function
Precondition	-
The called functions	timer_external_trigger_config
Input parameter{in}	
timer_periph	TIMER peripheral

<i>TIMERx(x=13)</i>	TIMER peripheral selection
Input parameter{in}	
remap	remap function selection
<i>TIMER13_CIO_RMP_GPIO</i>	timer13 channel 0 input is connected to GPIO(TIMER13_CH0)
<i>TIMER13_CIO_RMP_RTCCLK</i>	timer13 channel 0 input is connected to the RTCCLK
<i>TIMER13_CIO_RMP_HXTAL_DIV32</i>	timer13 channel 0 input is connected to HXTAL/32 clock
<i>TIMER13_CIO_RMP_CKOUTSEL</i>	timer13 channel 0 input is connected to CKOUTSEL
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER13 channel 0 input is connected to GPIO */
timer_channel_remap_config (TIMER13, TIMER13_CIO_RMP_GPIO);
```

timer_write_chxval_register_config

The description of timer_write_chxval_register_config is shown as below:

Table 3-455. Function timer_write_chxval_register_config

Function name	timer_write_chxval_register_config
Function prototype	void timer_write_chxval_register_config(uint32_t timer_periph, uint16_t ccsel);
Function descriptions	configure TIMER write CHxVAL register selection
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMERx(x=0, 2, 13..16)</i>	TIMER peripheral selection

Input parameter{in}	
ccsel	write CHxVAL register selection
<i>TIMER_CHVSEL_DISABLE</i>	no effect
<i>TIMER_CHVSEL_ENABLE</i>	when write the CHxVAL register, if the write value is same as the CHxVAL value, the write access is ignored
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* configure TIMER0 write CHxVAL register selection */
timer_write_chxval_register_config(TIMER0, TIMER_CHVSEL_ENABLE);

```

timer_output_value_selection_config

The description of timer_output_value_selection_config is shown as below:

Table 3-456. Function timer_output_value_selection_config

Function name	timer_output_value_selection_config
Function prototype	void timer_output_value_selection_config(uint32_t timer_periph, uint16_t outsel);
Function descriptions	configure TIMER output value selection
Precondition	-
The called functions	-
Input parameter{in}	
timer_periph	TIMER peripheral
<i>TIMER_x(x=0, 14..16)</i>	TIMER peripheral selection
Input parameter{in}	
outsel	output value selection
<i>TIMER_OUTSEL_DISABLE</i>	no effect

<i>TIMER_OUTSEL_ENABLE</i>	if POEN and IOS is 0, the output disabled
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure TIMER output value selection */
```

```
timer_output_value_selection_config(TIMER0, TIMER_OUTSEL_ENABLE);
```

3.19. USART

The Universal Synchronous/Asynchronous Receiver/Transmitter (USART) provides a flexible serial data exchange interface. The USART registers are listed in chapter [3.19.1](#), the USART firmware functions are introduced in chapter [3.19.2](#).

3.19.1. Descriptions of Peripheral registers

USART registers are listed in the table shown as below:

Table 3-457. USART Registers

Registers	Descriptions
USART_CTL0	Control register 0
USART_CTL1	Control register 1
USART_CTL2	Control register 2
USART_BAUD	Baud rate register
USART_GP	Guard time and prescaler register
USART_RT	Receiver timeout register
USART_CMD	Command register
USART_STAT	Status register
USART_INTC	Status clear register
USART_RDATA	Receive data register
USART_TDATA	Transmit data register

Registers	Descriptions
USART_CHC	Coherence control register
USART_RFCS	Receive FIFO control and status register

3.19.2. Descriptions of Peripheral functions

USART firmware functions are listed in the table shown as below:

Table 3-458. USART firmware function

Function name	Function description
usart_deinit	reset USART
usart_baudrate_set	configure USART baud rate value
usart_parity_config	configure USART parity function
usart_word_length_set	configure USART word length
usart_stop_bit_set	configure USART stop bit length
usart_enable	enable USART
usart_disable	disable USART
usart_transmit_config	configure USART transmitter
usart_receive_config	configure USART receiver
usart_data_first_config	data is transmitted/received with the LSB/MSB first
usart_invert_config	configure USART inverted
usart_overrun_enable	enable the USART overrun function
usart_overrun_disable	disable the USART overrun function
usart_oversample_config	configure the USART oversample mode
usart_sample_bit_config	configure sample bit method
usart_receiver_timeout_enable	enable receiver timeout
usart_receiver_timeout_disable	disable receiver timeout
usart_receiver_timeout_threshold_config	configure receiver timeout threshold
usart_data_transmit	USART transmit data function
usart_data_receive	USART receive data function

Function name	Function description
usart_autobaud_detection_enable	enable auto baud rate detection
usart_autobaud_detection_disable	disable auto baud rate detection
usart_autobaud_detection_mode_config	configure auto baud rate detection mode
usart_address_config	configure the address of the USART in wake up by address match mode
usart_address_detection_mode_config	configure address detection mode
usart_mute_mode_enable	receiver in mute mode
usart_mute_mode_disable	receiver in active mode
usart_mute_mode_wakeup_config	configure wakeup method in mute mode
usart_lin_mode_enable	enable LIN mode
usart_lin_mode_disable	disable LIN mode
usart_lin_break_detection_length_config	configure LIN break frame length
usart_halfduplex_enable	enable half duplex mode
usart_halfduplex_disable	disable half duplex mode
usart_clock_enable	enable USART clock
usart_clock_disable	disable USART clock
usart_synchronous_clock_config	configure USART synchronous mode parameters
usart_guard_time_config	configure guard time value in smartcard mode
usart_smartcard_mode_enable	enable smartcard mode
usart_smartcard_mode_disable	disable smartcard mode
usart_smartcard_mode_nack_enable	enable NACK in smartcard mode
usart_smartcard_mode_nack_disable	disable NACK in smartcard mode
usart_smartcard_mode_early_nack_enable	enable early NACK in smartcard mode
usart_smartcard_mode_early_nack_disable	disable early NACK in smartcard mode

Function name	Function description
usart_smartcard_autoretry_config	configure smartcard auto-retry number
usart_block_length_config	configure block length
usart_irda_mode_enable	enable IrDA mode
usart_irda_mode_disable	disable IrDA mode
usart_prescaler_config	configure the peripheral clock prescaler in USART IrDA low-power mode
usart_irda_lowpower_config	configure IrDA low-power
usart_hardware_flow_rts_config	configure hardware flow control RTS
usart_hardware_flow_cts_config	configure hardware flow control CTS
usart_hardware_flow_coherence_config	configure hardware flow control coherence mode
usart_rs485_driver_enable	enable RS485 driver
usart_rs485_driver_disable	disable RS485 driver
usart_driver_asserttime_config	configure driver enable assertion time
usart_driver_deasserttime_config	configure driver enable de-assertion time
usart_depolarity_config	configure driver enable polarity mode
usart_dma_receive_config	configure USART DMA for reception
usart_dma_transmit_config	configure USART DMA for transmission
usart_reception_error_dma_disable	disable DMA on reception error
usart_reception_error_dma_enable	enable DMA on reception error
usart_wakeup_enable	USART be able to wake up the mcu from deep-sleep mode
usart_wakeup_disable	USART be not able to wake up the mcu from deep-sleep mode
usart_wakeup_mode_config	wakeup mode from deep-sleep mode
usart_receive_fifo_enable	enable receive FIFO
usart_receive_fifo_disable	disable receive FIFO
usart_receive_fifo_counter_number	read receive FIFO counter number
usart_flag_get	get flag in STAT/RFCR register

Function name	Function description
usart_flag_clear	clear flag in STAT register
usart_interrupt_enable	enable USART interrupt
usart_interrupt_disable	disable USART interrupt
usart_command_enable	enable USART command
usart_interrupt_flag_get	get USART interrupt and flag status
usart_interrupt_flag_clear	clear USART interrupt flag in STAT register

usart_deinit

The description of usart_deinit is shown as below:

Table 3-459. Function usart_deinit

Function name	usart_deinit
Function prototype	void usart_deinit(uint32_t usart_periph);
Function descriptions	reset USART
Precondition	-
The called functions	rcu_periph_reset_enable / rcu_periph_reset_disable
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* reset USART0 */
usart_deinit(USART0);
```

usart_baudrate_set

The description of usart_baudrate_set is shown as below:

Table 3-460. Function `usart_baudrate_set`

Function name	<code>usart_baudrate_set</code>
Function prototype	<code>void usart_baudrate_set(uint32_t usart_periph, uint32_t baudval);</code>
Function descriptions	configure USART baud rate value
Precondition	-
The called functions	<code>rcu_clock_freq_get</code>
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
baudval	baud rate value
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 baud rate value */
usart_baudrate_set(USART0, 115200);
```

usart_parity_config

The description of `usart_parity_config` is shown as below:

Table 3-461. Function `usart_parity_config`

Function name	<code>usart_parity_config</code>
Function prototype	<code>void usart_parity_config(uint32_t usart_periph, uint32_t paritycfg);</code>
Function descriptions	configure USART parity
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral

<i>USARTx</i>	x=0,1
Input parameter{in}	
paritycfg	configure USART parity
<i>USART_PM_NONE</i>	no parity
<i>USART_PM_ODD</i>	odd parity
<i>USART_PM_EVEN</i>	even parity
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 parity */
```

```
usart_parity_config(USART0, USART_PM_EVEN);
```

usart_word_length_set

The description of usart_word_length_set is shown as below:

Table 3-462. Function usart_word_length_set

Function name	usart_word_length_set
Function prototype	void usart_word_length_set(uint32_t usart_periph, uint32_t wlen);
Function descriptions	configure USART word length
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
wlen	USART word length configure
<i>USART_WL_8BIT</i>	8 bits
<i>USART_WL_9BIT</i>	9 bits

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 word length */
```

```
usart_word_length_set(USART0, USART_WL_9BIT);
```

usart_stop_bit_set

The description of usart_stop_bit_set is shown as below:

Table 3-463. Function usart_stop_bit_set

Function name	usart_stop_bit_set
Function prototype	void usart_stop_bit_set(uint32_t usart_periph, uint32_t stblen);
Function descriptions	configure USART stop bit length
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
stblen	USART stop bit configure
<i>USART_STB_1BIT</i>	1 bit
<i>USART_STB_0_5BIT</i>	0.5 bit
<i>USART_STB_2BIT</i>	2 bits
<i>USART_STB_1_5BIT</i>	1.5 bits
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 stop bit length */
usart_stop_bit_set(USART0, USART_STB_1_5BIT);
```

usart_enable

The description of usart_enable is shown as below:

Table 3-464. Function usart_enable

Function name	usart_enable
Function prototype	void usart_enable(uint32_t usart_periph);
Function descriptions	enable USART
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 */
usart_enable(USART0);
```

usart_disable

The description of usart_disable is shown as below:

Table 3-465. Function usart_disable

Function name	usart_disable
Function prototype	void usart_disable(uint32_t usart_periph);
Function descriptions	disable USART
Precondition	-

The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 */
```

```
usart_disable(USART0);
```

usart_transmit_config

The description of usart_transmit_config is shown as below:

Table 3-466. Function usart_transmit_config

Function name	usart_transmit_config
Function prototype	void usart_transmit_config(uint32_t usart_periph, uint32_t txconfig);
Function descriptions	configure USART transmitter
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
txconfig	enable or disable USART transmitter
<i>USART_TRANSMIT_ENABLE</i>	enable USART transmission
<i>USART_TRANSMIT_DISABLE</i>	disable USART transmission
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* configure USART0 transmitter */
```

```
usart_transmit_config(USART0,USART_TRANSMIT_ENABLE);
```

usart_receive_config

The description of usart_receive_config is shown as below:

Table 3-467. Function usart_receive_config

Function name	usart_receive_config
Function prototype	void usart_receive_config(uint32_t usart_periph, uint32_t rxconfig);
Function descriptions	configure USART receiver
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
rxconfig	enable or disable USART receiver
<i>USART_RECEIVE_ENABLE</i>	enable USART reception
<i>USART_RECEIVE_DISABLE</i>	disable USART reception
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* Configure USART0 receiver */
```

```
usart_receive_config(USART0, USART_RECEIVE_ENABLE);
```

usart_data_first_config

The description of usart_data_first_config is shown as below:

Table 3-468. Function usart_data_first_config

Function name	usart_data_first_config
Function prototype	void usart_data_first_config(uint32_t usart_periph, uint32_t msbf);
Function descriptions	data is transmitted/received with the LSB/MSB first
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
msbf	LSB/MSB
<i>USART_MSBF_LSB</i>	LSB first
<i>USART_MSBF_MSB</i>	MSB first
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure LSB of data first */
```

```
usart_data_first_config(USART0, USART_MSBF_LSB);
```

usart_invert_config

The description of usart_invert_config is shown as below:

Table 3-469. Function usart_invert_config

Function name	usart_invert_config
Function prototype	void usart_invert_config(uint32_t usart_periph, usart_invert_enum

	invertpara);
Function descriptions	USART inverted configure
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
invertpara	refer to usart_invert_enum
<i>USART_DINV_ENABLE</i>	data bit level inversion
<i>USART_DINV_DISABLE</i>	data bit level not inversion
<i>USART_TXPIN_ENABLE</i>	TX pin level inversion
<i>USART_TXPIN_DISABLE</i>	TX pin level not inversion
<i>USART_RXPIN_ENABLE</i>	RX pin level inversion
<i>USART_RXPIN_DISABLE</i>	RX pin level not inversion
<i>USART_SWAP_ENABLE</i>	swap TX/RX pins
<i>USART_SWAP_DISABLE</i>	not swap TX/RX pins
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 inversion */
```

```
usart_invert_config(USART0, USART_DINV_ENABLE);
```

usart_overrun_enable

The description of usart_overrun_enable is shown as below:

Table 3-470. Function usart_overrun_enable

Function name	usart_overrun_enable
Function prototype	void usart_overrun_enable(uint32_t usart_periph);
Function descriptions	enable the USART overrun function
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 overrun */
usart_overrun_enable(USART0);
```

usart_overrun_disable

The description of usart_overrun_disable is shown as below:

Table 3-471. Function usart_overrun_disable

Function name	usart_overrun_disable
Function prototype	void usart_overrun_disable(uint32_t usart_periph);
Function descriptions	disable the USART overrun function
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral

<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 overrun */
usart_overrun_disable(USART0);
```

usart_oversample_config

The description of usart_oversample_config is shown as below:

Table 3-472. Function usart_oversample_config

Function name	usart_oversample_config
Function prototype	void usart_oversample_config(uint32_t usart_periph, uint32_t oversamp);
Function descriptions	configure the USART oversample mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
oversamp	oversample value
<i>USART_OVSMOD_8</i>	oversampling by 8
<i>USART_OVSMOD_16</i>	oversampling by 16
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* config USART0 oversampling by 8 */
```

```
usart_oversample_config(USART0,USART_OVSMOD_8);
```

usart_sample_bit_config

The description of usart_sample_bit_config is shown as below:

Table 3-473. Function usart_sample_bit_config

Function name	usart_sample_bit_config
Function prototype	void usart_sample_bit_config(uint32_t usart_periph, uint32_t osb);
Function descriptions	configure the sample bit method
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
osb	sample bit
<i>USART_OSB_1BIT</i>	1 bit
<i>USART_OSB_3BIT</i>	3 bits
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* config USART0 1 bit sample mode */
```

```
usart_sample_bit_config(USART0,USART_OSB_1BIT);
```

usart_receiver_timeout_enable

The description of usart_receiver_timeout_enable is shown as below:

Table 3-474. Function usart_receiver_timeout_enable

Function name	usart_receiver_timeout_enable
----------------------	-------------------------------

Function prototype	void usart_receiver_timeout_enable(uint32_t usart_periph);
Function descriptions	enable receiver timeout
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 receiver timeout */
usart_receiver_timeout_enable(USART0);
```

usart_receiver_timeout_disable

The description of usart_receiver_timeout_disable is shown as below:

Table 3-475. Function usart_receiver_timeout_disable

Function name	usart_receiver_timeout_disable
Function prototype	void usart_receiver_timeout_disable(uint32_t usart_periph);
Function descriptions	disable receiver timeout
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* disable USART0 receiver timeout */
usart_receiver_timeout_disable(USART0);
```

usart_receiver_timeout_threshold_config

The description of usart_receiver_timeout_threshold_config is shown as below:

Table 3-476. Function usart_receiver_timeout_threshold_config

Function name	usart_receiver_timeout_threshold_config
Function prototype	void usart_receiver_timeout_threshold_config(uint32_t usart_periph, uint32_t timeout);
Function descriptions	configure receiver timeout threshold
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Input parameter{in}	
rttimeout	receiver timeout
<i>0x00000000-0x00FFFFFF</i>	receiver timeout value
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set the receiver timeout threshold of USART0*/
usart_receiver_timeout_threshold_config(USART0,115200*3);
```

usart_data_transmit

The description of usart_data_transmit is shown as below:

Table 3-477. Function usart_data_transmit

Function name	usart_data_transmit
Function prototype	void usart_data_transmit(uint32_t usart_periph, uint32_t data);
Function descriptions	USART transmit data function
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
data	data of transmission
<i>0-0x1FF</i>	data of transmission
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 transmit data */
usart_data_transmit(USART0, 0xAA);
```

usart_data_receive

The description of usart_data_receive is shown as below:

Table 3-478. Function usart_data_receive

Function name	usart_data_receive
Function prototype	void usart_data_receive(uint32_t usart_periph);
Function descriptions	USART receive data function
Precondition	-
The called functions	-
Input parameter{in}	

usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
uint32_t	data of received (0-0x1FF)

Example:

```
/* USART0 receive data */
```

```
uint16_t temp;
```

```
temp = usart_data_receive(USART0);
```

usart_autobaud_detection_enable

The description of usart_autobaud_detection_enable is shown as below:

Table 3-479. Function usart_autobaud_detection_enable

Function name	usart_autobaud_detection_enable
Function prototype	void usart_autobaud_detection_enable(uint32_t usart_periph);
Function descriptions	enable auto baud rate detection
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 auto baud rate detection */
```

```
usart_autobaud_detection_enable(USART0);
```

usart_autobaud_detection_disable

The description of usart_autobaud_detection_disable is shown as below:

Table 3-480. Function usart_autobaud_detection_disable

Function name	usart_autobaud_detection_disable
Function prototype	void usart_autobaud_detection_disable(uint32_t usart_periph);
Function descriptions	disable auto baud rate detection
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 auto baud rate detection */
usart_autobaud_detection_disable(USART0);
```

usart_autobaud_detection_mode_config

The description of usart_autobaud_detection_mode_config is shown as below:

Table 3-481. Function usart_autobaud_detection_mode_config

Function name	usart_autobaud_detection_mode_config
Function prototype	void usart_autobaud_detection_mode_config(uint32_t usart_periph, uint32_t abdm);
Function descriptions	configure auto baud rate detection mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral

<i>USARTx</i>	<i>x=0</i>
Input parameter{in}	
abdmod	auto baud rate detection mode
<i>USART_ABDM_FTOR</i>	falling edge to rising edge measurement
<i>USART_ABDM_FTOF</i>	falling edge to falling edge measurement
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 auto baud rate detection mode */
usart_autobaud_detection_mode_config(USART0, USART_ABDM_FTOR);
```

usart_address_config

The description of `usart_address_config` is shown as below:

Table 3-482. Function `usart_address_config`

Function name	<code>usart_address_config</code>
Function prototype	<code>void usart_address_config(uint32_t usart_periph, uint8_t addr);</code>
Function descriptions	configure the address of the USART terminal
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	<i>x=0,1</i>
Input parameter{in}	
addr	address of USART
<i>0-0xFF</i>	address of USART
Output parameter{out}	
-	-

Return value	
-	-

Example:

```
/* configure address of the USART0 */
usart_address_config(USART0, 0x00);
```

usart_address_detection_mode_config

The description of usart_address_detection_mode_config is shown as below:

Table 3-483. Function usart_address_detection_mode_config

Function name	usart_address_detection_mode_config
Function prototype	void usart_address_detection_mode_config(uint32_t usart_periph, uint32_t addmod);
Function descriptions	configure address detection mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
addmod	address detection mode
<i>USART_ADDDM_4BIT</i>	4 bits
<i>USART_ADDDM_FULLBIT</i>	full bits
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/*configure address detection mode */
usart_address_config(USART0, USART_ADDDM_4BIT);
```

usart_mute_mode_enable

The description of usart_mute_mode_enable is shown as below:

Table 3-484. Function usart_mute_mode_enable

Function name	usart_mute_mode_enable
Function prototype	void usart_mute_mode_enable(uint32_t usart_periph);
Function descriptions	enable mute mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 receiver in mute mode */
usart_mute_mode_enable(USART0);
```

usart_mute_mode_disable

The description of usart_mute_mode_disable is shown as below:

Table 3-485. Function usart_mute_mode_disable

Function name	usart_mute_mode_disable
Function prototype	void usart_mute_mode_disable(uint32_t usart_periph);
Function descriptions	disable mute mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral

<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 receiver in mute mode */
```

```
usart_mute_mode_disable(USART0);
```

usart_mute_mode_wakeup_config

The description of `usart_mute_mode_wakeup_config` is shown as below:

Table 3-486. Function `usart_mute_mode_wakeup_config`

Function name	<code>usart_mute_mode_wakeup_config</code>
Function prototype	<code>void usart_mute_mode_wakeup_config(uint32_t usart_periph, uint32_t wmethod);</code>
Function descriptions	configure wakeup method in mute mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
wmethod	two methods be used to enter or exit the mute mode
<i>USART_WM_IDLE</i>	idle line
<i>USART_WM_ADDR</i>	address mask
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 wakeup method in mute mode */
usart_mute_mode_wakeup_config(USART0, USART_WM_IDLE);
```

usart_lin_mode_enable

The description of usart_lin_mode_enable is shown as below:

Table 3-487. Function usart_lin_mode_enable

Function name	usart_lin_mode_enable
Function prototype	void usart_lin_mode_enable(uint32_t usart_periph);
Function descriptions	enable LIN mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 LIN mode enable */
usart_lin_mode_enable(USART0);
```

usart_lin_mode_disable

The description of usart_lin_mode_disable is shown as below:

Table 3-488. Function usart_lin_mode_disable

Function name	usart_lin_mode_disable
Function prototype	void usart_lin_mode_disable(uint32_t usart_periph);
Function descriptions	disable LIN mode
Precondition	-

The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 LIN mode disable */
```

```
usart_lin_mode_disable(USART0);
```

usart_lin_break_dection_length_config

The description of usart_lin_break_dection_length_config is shown as below:

Table 3-489. Function usart_lin_break_dection_length_config

Function name	usart_lin_break_dection_length_config
Function prototype	void usart_lin_break_dection_length_config(uint32_t usart_periph, uint32_t lblen);
Function descriptions	configure lin break frame length
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Input parameter{in}	
lblen	two methods be used to enter or exit the mute mode
<i>USART_LBLEN_10B</i>	10 bits
<i>USART_LBLEN_11B</i>	11 bits
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* configure LIN break frame length */
```

```
usart_lin_break_dection_length_config(USART0, USART_LBLEN_10B);
```

usart_halfduplex_enable

The description of usart_halfduplex_enable is shown as below:

Table 3-490. Function usart_halfduplex_enable

Function name	usart_halfduplex_enable
Function prototype	void usart_halfduplex_enable(uint32_t usart_periph);
Function descriptions	enable half-duplex mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 half duplex mode*/
```

```
usart_halfduplex_enable(USART0);
```

usart_halfduplex_disable

The description of usart_halfduplex_disable is shown as below:

Table 3-491. Function usart_halfduplex_disable

Function name	usart_halfduplex_disable
----------------------	--------------------------

Function prototype	void usart_halfduplex_disable(uint32_t usart_periph);
Function descriptions	disable half-duplex mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 half duplex mode*/
```

```
usart_halfduplex_disable(USART0);
```

usart_clock_enable

The description of usart_clock_enable is shown as below:

Table 3-492. Function usart_clock_enable

Function name	usart_clock_enable
Function prototype	void usart_clock_enable(uint32_t usart_periph);
Function descriptions	enable clock
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* enable USART0 CK pin */
usart_synchronous_clock_enable(USART0);
```

usart_clock_disable

The description of usart_clock_disable is shown as below:

Table 3-493. Function usart_clock_disable

Function name	usart_clock_disable
Function prototype	void usart_clock_disable(uint32_t usart_periph);
Function descriptions	disable clock
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 CK pin */
usart_synchronous_clock_disable(USART0);
```

usart_synchronous_clock_config

The description of usart_synchronous_clock_config is shown as below:

Table 3-494. Function usart_synchronous_clock_config

Function name	usart_synchronous_clock_config
Function prototype	void usart_synchronous_clock_config(uint32_t usart_periph, uint32_t clen, uint32_t cph, uint32_t cpl);

Function descriptions	configure USART synchronous mode parameters
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
clen	last bit clock pulse
<i>USART_CLEN_NONE</i>	clock pulse of the last data bit (MSB) is not output to the CK pin
<i>USART_CLEN_EN</i>	clock pulse of the last data bit (MSB) is output to the CK pin
Input parameter{in}	
cph	clock phase
<i>USART_CPH_1CK</i>	first clock transition is the first data capture edge
<i>USART_CPH_2CK</i>	second clock transition is the first data capture edge
Input parameter{in}	
cpl	clock polarity
<i>USART_CPL_LOW</i>	steady low value on CK pin
<i>USART_CPL_HIGH</i>	steady high value on CK pin
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 synchronous mode parameters */
```

```
usart_synchronous_clock_config(USART0,USART_CLEN_EN,USART_CPH_2CK,  
USART_CPL_HIGH);
```

usart_guard_time_config

The description of usart_guard_time_config is shown as below:

Table 3-495. Function usart_guard_time_config

Function name	usart_guard_time_config
Function prototype	void usart_guard_time_config(uint32_t usart_periph,uint32_t guat);
Function descriptions	configure guard time value in smartcard mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Input parameter{in}	
guat	guard time value
<i>0-0x000000FF</i>	guard time value
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 guard time value in smartcard mode */
usart_guard_time_config(USART0, 0x0000 0055);
```

usart_smartcard_mode_enable

The description of usart_smartcard_mode_enable is shown as below:

Table 3-496. Function usart_smartcard_mode_enable

Function name	usart_smartcard_mode_enable
Function prototype	void usart_smartcard_mode_enable(uint32_t usart_periph);
Function descriptions	enable smartcard mode
Precondition	-
The called functions	-
Input parameter{in}	

usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 smartcard mode enable */
usart_smartcard_mode_enable(USART0);
```

usart_smartcard_mode_disable

The description of usart_smartcard_mode_disable is shown as below:

Table 3-497. Function usart_smartcard_mode_disable

Function name	usart_smartcard_mode_disable
Function prototype	void usart_smartcard_mode_disable(uint32_t usart_periph);
Function descriptions	disable smartcard mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 smartcard mode disable */
usart_smartcard_mode_disable(USART0);
```

usart_smartcard_mode_nack_enable

The description of usart_smartcard_mode_nack_enable is shown as below:

Table 3-498. Function usart_smartcard_mode_nack_enable

Function name	usart_smartcard_mode_nack_enable
Function prototype	void usart_smartcard_mode_nack_enable(uint32_t usart_periph);
Function descriptions	enable NACK in smartcard mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 NACK in smartcard mode */
usart_smartcard_mode_nack_enable(USART0);
```

usart_smartcard_mode_nack_disable

The description of usart_smartcard_mode_nack_disable is shown as below:

Table 3-499. Function usart_smartcard_mode_nack_disable

Function name	usart_smartcard_mode_nack_disable
Function prototype	void usart_smartcard_mode_nack_disable(uint32_t usart_periph);
Function descriptions	disable NACK in smartcard mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral

<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 NACK in smartcard mode */
usart_smartcard_mode_nack_disable(USART0);
```

usart_smartcard_mode_early_nack_enable

The description of usart_smartcard_mode_early_nack_enable is shown as below:

Table 3-500. Function usart_smartcard_mode_early_nack_enable

Function name	usart_smartcard_mode_early_nack_enable
Function prototype	void usart_smartcard_mode_early_nack_enable(uint32_t usart_periph);
Function descriptions	enable early NACK in smartcard mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 early NACK in smartcard mode */
usart_smartcard_mode_early_nack_enable(USART0);
```

usart_smartcard_mode_early_nack_disable

The description of usart_smartcard_mode_early_nack_disable is shown as below:

Table 3-501. Function `usart_smartcard_mode_early_nack_disable`

Function name	<code>usart_smartcard_mode_early_nack_disable</code>
Function prototype	<code>void usart_smartcard_mode_early_nack_disable(uint32_t usart_periph);</code>
Function descriptions	disable early NACK in smartcard mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 early NACK in smartcard mode */
usart_smartcard_mode_early_nack_disable(USART0);
```

usart_smartcard_autoretry_config

The description of `usart_smartcard_autoretry_config` is shown as below:

Table 3-502. Function `usart_smartcard_autoretry_config`

Function name	<code>usart_smartcard_autoretry_config</code>
Function prototype	<code>void usart_smartcard_autoretry_config(uint32_t usart_periph, uint32_t scrtnum);</code>
Function descriptions	configure smartcard auto-retry number
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Input parameter{in}	

scrtnum	smartcard auto-retry number
<i>0x00000000-0x00000007</i>	smartcard auto-retry number
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure smartcard auto-retry number */
```

```
usart_smartcard_autoretry_config(USART0, 0x00000007);
```

usart_block_length_config

The description of usart_block_length_config is shown as below:

Table 3-503. Function usart_block_length_config

Function name	usart_block_length_config
Function prototype	void usart_block_length_config(uint32_t usart_periph, uint32_t bl);
Function descriptions	configure block length
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Input parameter{in}	
bl	block length
<i>0-0x000000FF</i>	block length
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure block length in Smartcard T=1 reception */
usart_block_length_config(USART0, 0x000000FF);
```

usart_irda_mode_enable

The description of usart_irda_mode_enable is shown as below:

Table 3-504. Function usart_irda_mode_enable

Function name	usart_irda_mode_enable
Function prototype	void usart_irda_mode_enable(uint32_t usart_periph);
Function descriptions	enable IrDA mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 IrDA mode */
usart_irda_mode_enable(USART0);
```

usart_irda_mode_disable

The description of usart_irda_mode_disable is shown as below:

Table 3-505. Function usart_irda_mode_disable

Function name	usart_irda_mode_disable
Function prototype	void usart_irda_mode_disable(uint32_t usart_periph);
Function descriptions	disable IrDA mode
Precondition	-

The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 IrDA mode */
usart_irda_mode_disable(USART0);
```

usart_prescaler_config

The description of usart_prescaler_config is shown as below:

Table 3-506. Function usart_prescaler_config

Function name	usart_prescaler_config
Function prototype	void usart_prescaler_config(uint32_t usart_periph, uint8_t psc);
Function descriptions	configure the peripheral clock prescaler in USART IrDA low-power mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Input parameter{in}	
psc	clock prescaler
<i>0x00-0xFF</i>	clock prescaler
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```
/* configure the USART0 peripheral clock prescaler in USART IrDA low-power mode */
usart_prescaler_config(USART0, 0x00);
```

usart_irda_lowpower_config

The description of usart_irda_lowpower_config is shown as below:

Table 3-507. Function usart_irda_lowpower_config

Function name	usart_irda_lowpower_config
Function prototype	void usart_irda_lowpower_config(uint32_t usart_periph, uint32_t irlp);
Function descriptions	configure IrDA low-power
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Input parameter{in}	
irlp	IrDA low-power or normal
<i>USART_IRLP_LOW</i>	low-power
<i>USART_IRLP_NORMA L</i>	normal
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 IrDA low-power */
usart_irda_lowpower_config(USART0, USART_IRLP_LOW);
```

usart_hardware_flow_rts_config

The description of usart_hardware_flow_rts_config is shown as below:

Table 3-508. Function usart_hardware_flow_rts_config

Function name	usart_hardware_flow_rts_config
Function prototype	void usart_hardware_flow_rts_config(uint32_t usart_periph, uint32_t rtsconfig);
Function descriptions	configure hardware flow control RTS
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
rtsconfig	enable or disable RTS
<i>USART_RTS_ENABLE</i>	enable RTS
<i>USART_RTS_DISABLE</i>	disable RTS
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 hardware flow control RTS */
usart_hardware_flow_rts_config(USART0, USART_RTS_ENABLE);
```

usart_hardware_flow_cts_config

The description of usart_hardware_flow_cts_config is shown as below:

Table 3-509. Function usart_hardware_flow_cts_config

Function name	usart_hardware_flow_cts_config
Function prototype	void usart_hardware_flow_cts_config(uint32_t usart_periph, uint32_t

	ctsconfig);
Function descriptions	configure hardware flow control RTS
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
ctsconfig	enable or disable CTS
<i>USART_CTS_ENABLE</i>	enable CTS
<i>USART_CTS_DISABLE</i>	disable CTS
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 hardware flow control CTS */
usart_hardware_flow_cts_config(USART0, USART_CTS_ENABLE);
```

usart_hardware_flow_coherence_config

The description of usart_hardware_flow_coherence_config is shown as below:

Table 3-510. Function usart_hardware_flow_coherence_config

Function name	usart_hardware_flow_coherence_config
Function prototype	void usart_hardware_flow_coherence_config(uint32_t usart_periph, uint32_t hcm);
Function descriptions	configure hardware flow control coherence mode
Precondition	-
The called functions	-
Input parameter{in}	

usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
hcm	Hardware flow control coherence mode
<i>USART_HCM_NONE</i>	nRTS signal equals to the rxne status register
<i>USART_HCM_EN</i>	nRTS signal is set when the last data bit has been sampled
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure hardware flow control coherence mode */
```

```
usart_hardware_flow_coherence_config(USART0, USART_HCM_NONE);
```

usart_rs485_driver_enable

The description of usart_rs485_driver_enable is shown as below:

Table 3-511. Function usart_rs485_driver_enable

Function name	usart_rs485_driver_enable
Function prototype	void usart_rs485_driver_enable(uint32_t usart_periph);
Function descriptions	enable USART RS485 driver
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 RS485 driver */
usart_rs485_driver_enable(USART0);
```

usart_rs485_driver_disable

The description of usart_rs485_driver_disable is shown as below:

Table 3-512. Function usart_rs485_driver_disable

Function name	usart_rs485_driver_disable
Function prototype	void usart_rs485_driver_disable(uint32_t usart_periph);
Function descriptions	disable USARTRS485 driver
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 RS485 driver */
usart_rs485_driver_disable (USART0);
```

usart_driver_assertime_config

The description of usart_driver_assertime_config is shown as below:

Table 3-513. Function usart_driver_assertime_config

Function name	usart_driver_assertime_config
Function prototype	void usart_driver_assertime_config(uint32_t usart_periph, uint32_t deatime);
Function descriptions	configure driver enable assertion time

Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
deatime	driver enable assertion time
<i>0-0x0000001F</i>	driver enable assertion time
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set USART0 driver assertime */
```

```
usart_driver_assertime_config(USART0,0x0000001F);
```

usart_driver_deassertime_config

The description of usart_driver_deassertime_config is shown as below:

Table 3-514. Function usart_driver_deassertime_config

Function name	usart_driver_deassertime_config
Function prototype	void usart_driver_deassertime_config(uint32_t usart_periph, uint32_t dedtime);
Function descriptions	configure driver enable de-assertion time
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	

deatime	driver enable de-assertion time
<i>0x00000000-0x0000001F</i>	driver enable de-assertion time
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* set USART0 driver deassertime */
```

```
usart_driver_deassertime_config(USART0,0x0000001F);
```

usart_depolarity_config

The description of usart_depolarity_config is shown as below:

Table 3-515. Function usart_depolarity_config

Function name	usart_depolarity_config
Function prototype	void usart_depolarity_config(uint32_t usart_periph, uint32_t dep);
Function descriptions	configure driver enable polarity mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
dep	DE signal
<i>USART_DEP_HIGH</i>	DE signal is active high
<i>USART_DEP_LOW</i>	DE signal is active low
Output parameter{out}	
-	-
Return value	

-	-
---	---

Example:

```

/* configure driver enable polarity mode */
usart_driver_depolarity_config(USART0, USART_DEP_HIGH);

```

usart_dma_receive_config

The description of usart_dma_receive_config is shown as below:

Table 3-516. Function usart_dma_receive_config

Function name	usart_dma_receive_config
Function prototype	void usart_dma_receive_config(uint32_t usart_periph, uint32_t dmacmd);
Function descriptions	configure USART DMA reception
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
dmacmd	enable or disable DMA for reception
<i>USART_DENR_ENABLE</i>	DMA enable for reception
<i>USART_DENR_DISABLE</i>	DMA disable for reception
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* USART0 DMA enable for reception */
usart_dma_receive_config(USART0, USART_DENR_ENABLE);

```

usart_dma_transmit_config

The description of usart_dma_transmit_config is shown as below:

Table 3-517. Function usart_dma_transmit_config

Function name	usart_dma_transmit_config
Function prototype	void usart_dma_transmit_config(uint32_t usart_periph, uint32_t dmacmd);
Function descriptions	configure USART DMA transmission
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
dmacmd	enable or disable DMA for transmission
<i>USART_DENT_ENABLE</i>	DMA enable for transmission
<i>USART_DENT_DISABLE</i>	DMA disable for transmission
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 DMA enable for transmission */
usart_dma_transmit_config(USART0, USART_DENT_ENABLE);
```

usart_reception_error_dma_disable

The description of usart_reception_error_dma_disable is shown as below:

Table 3-518. Function usart_reception_error_dma_disable

Function name	usart_reception_error_dma_disable
Function prototype	void usart_reception_error_dma_disable(uint32_t usart_periph);

Function descriptions	disable DMA on reception error
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable DMA on reception error */
usart_reception_error_dma_disable(USART0);
```

usart_reception_error_dma_enable

The description of usart_reception_error_dma_enable is shown as below:

Table 3-519. Function usart_reception_error_dma_enable

Function name	usart_reception_error_dma_enable
Function prototype	void usart_reception_error_dma_enable(uint32_t usart_periph);
Function descriptions	enable DMA on reception error
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable DMA on reception error */
usart_reception_error_dma_enable(USART0);
```

usart_wakeup_enable

The description of usart_wakeup_enable is shown as below:

Table 3-520. Function usart_wakeup_enable

Function name	usart_wakeup_enable
Function prototype	void usart_wakeup_enable(uint32_t usart_periph);
Function descriptions	USART be able to wake up the MCU from deep-sleep mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 wake up enable */
usart_wakeup_enable(USART0);
```

usart_wakeup_disable

The description of usart_wakeup_disable is shown as below:

Table 3-521. Function usart_wakeup_disable

Function name	usart_wakeup_disable
Function prototype	void usart_wakeup_disable(uint32_t usart_periph);
Function descriptions	USART not be able to wake up the MCU from deep-sleep mode
Precondition	-

The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* USART0 wake up disable */
usart_wakeup_disable(USART0);
```

usart_wakeup_mode_config

The description of usart_wakeup_mode_config is shown as below:

Table 3-522. Function usart_wakeup_mode_config

Function name	usart_wakeup_mode_config
Function prototype	void usart_wakeup_mode_config(uint32_t usart_periph, uint32_t wum);
Function descriptions	wakeup mode from deep-sleep mode
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0
Input parameter{in}	
wum	wakeup mode
<i>USART_WUM_ADDR</i>	WUF active on address match
<i>USART_WUM_START B</i>	WUF active on start bit
<i>USART_WUM_RBNE</i>	WUF active on RBNE

Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure USART0 wake up mode */
usart_wakeup_mode_config(USART0, USART_WUM_ADDR);
```

usart_receive_fifo_enable

The description of usart_receive_fifo_enable is shown as below:

Table 3-523. Function usart_receive_fifo_enable

Function name	usart_receive_fifo_enable
Function prototype	void usart_receive_fifo_enable(uint32_t usart_periph);
Function descriptions	enable receive FIFO
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable receive FIFO */
usart_receive_fifo_enable(USART0);
```

usart_receive_fifo_disable

The description of usart_receive_fifo_disable is shown as below:

Table 3-524. Function `usart_receive_fifo_disable`

Function name	<code>usart_receive_fifo_disable</code>
Function prototype	<code>void usart_receive_fifo_disable(uint32_t usart_periph);</code>
Function descriptions	disable receive FIFO
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable receive FIFO */
usart_receive_fifo_disable(USART0);
```

usart_receive_fifo_counter_number

The description of `usart_receive_fifo_counter_number` is shown as below:

Table 3-525. Function `usart_receive_fifo_counter_number`

Function name	<code>usart_receive_fifo_counter_number</code>
Function prototype	<code>uint8_t usart_receive_fifo_counter_number(uint32_t usart_periph);</code>
Function descriptions	read receive FIFO counter number
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Output parameter{out}	

-	-
Return value	
uint8_t	receive FIFO counter number

Example:

```
/* read receive FIFO counter number */
uint8_t temp;
temp = usart_receive_fifo_counter_number(USART0);
```

usart_flag_get

The description of usart_flag_get is shown as below:

Table 3-526. Function usart_flag_get

Function name	usart_flag_get
Function prototype	FlagStatus usart_flag_get(uint32_t usart_periph, usart_flag_enum flag);
Function descriptions	get flag in STAT/CHC/RFCS register
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
flag	USART flags, refer to usart_flag_enum only one among these parameters can be selected
<i>USART_FLAG_PERR</i>	parity error flag
<i>USART_FLAG_FERR</i>	frame error flag
<i>USART_FLAG_NERR</i>	noise error flag
<i>USART_FLAG_ORER</i> <i>R</i>	overrun error
<i>USART_FLAG_IDLE</i>	idle line detected flag
<i>USART_FLAG_RBNE</i>	read data buffer not empty

<i>USART_FLAG_TC</i>	transmission completed
<i>USART_FLAG_TBE</i>	transmit data register empty
<i>USART_FLAG_LBD</i>	LIN break detected flag
<i>USART_FLAG_CTSF</i>	CTS change flag
<i>USART_FLAG_CTS</i>	CTS level
<i>USART_FLAG_RT</i>	receiver timeout flag
<i>USART_FLAG_EB</i>	end of block flag
<i>USART_FLAG_ABDE</i>	auto baudrate detection error
<i>USART_FLAG_ABD</i>	auto baudrate detection flag
<i>USART_FLAG_BSY</i>	busy flag
<i>USART_FLAG_AM</i>	address match flag
<i>USART_FLAG_SB</i>	send break flag
<i>USART_FLAG_RWU</i>	receiver wakeup from mute mode
<i>USART_FLAG_WU</i>	wakeup from deep-sleep mode flag
<i>USART_FLAG_TEA</i>	transmit enable acknowledge flag
<i>USART_FLAG_REA</i>	receive enable acknowledge flag
<i>USART_FLAG_EPERR</i>	early parity error flag
<i>USART_FLAG_RFE</i>	receive FIFO empty flag
<i>USART_FLAG_RFF</i>	receive FIFO full flag
<i>USART_FLAG_RFFINT</i>	receive FIFO full interrupt flag
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get flag USART0 state */
```

```
FlagStatus status;
```

```
status = usart_flag_get(USART0,USART_FLAG_TBE);
```

usart_flag_clear

The description of usart_flag_clear is shown as below:

Table 3-527. Function usart_flag_clear

Function name	usart_flag_clear
Function prototype	void usart_flag_clear(uint32_t usart_periph, usart_flag_enum flag);
Function descriptions	clear flag in STAT register
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
flag	USART flags, refer to usart_flag_enum only one among these parameters can be selected
<i>USART_FLAG_PERR</i>	parity error flag
<i>USART_FLAG_FERR</i>	frame error flag
<i>USART_FLAG_NERR</i>	noise detected flag
<i>USART_FLAG_ORER R</i>	overrun error flag
<i>USART_FLAG_IDLE</i>	idle line detected flag
<i>USART_FLAG_TC</i>	transmission complete flag
<i>USART_FLAG_LBD</i>	LIN break detected flag
<i>USART_FLAG_CTSF</i>	CTS change flag
<i>USART_FLAG_RT</i>	receiver timeout flag
<i>USART_FLAG_EB</i>	end of block flag
<i>USART_FLAG_AM</i>	address match flag
<i>USART_FLAG_WU</i>	wakeup from deep-sleep mode flag
<i>USART_FLAG_EPERR</i>	early parity error flag
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* clear USART0 flag */
```

```
usart_flag_clear(USART0,USART_FLAG_TC);
```

usart_interrupt_enable

The description of usart_interrupt_enable is shown as below:

Table 3-528. Function usart_interrupt_enable

Function name	usart_interrupt_enable
Function prototype	void usart_interrupt_enable(uint32_t usart_periph, usart_interrupt_enum inttype);
Function descriptions	enable USART interrupt
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
inttype	interrupt type
<i>USART_INT_IDLE</i>	idle interrupt
<i>USART_INT_RBNE</i>	read data buffer not empty interrupt and overrun error interrupt enable interrupt
<i>USART_INT_TC</i>	transmission complete interrupt
<i>USART_INT_TBE</i>	transmit data register empty interrupt
<i>USART_INT_PERR</i>	parity error interrupt
<i>USART_INT_AM</i>	address match interrupt
<i>USART_INT_RT</i>	receiver timeout interrupt
<i>USART_INT_EB</i>	end of block interrupt

<i>USART_INT_LBD</i>	LIN break detection interrupt
<i>USART_INT_ERR</i>	error interrupt enable in multibuffer communication
<i>USART_INT_CTS</i>	CTS interrupt
<i>USART_INT_WU</i>	wakeup from deep-sleep mode interrupt
<i>USART_INT_RFF</i>	receive FIFO full interrupt enable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 TBE interrupt */
```

```
usart_interrupt_enable(USART0, USART_INT_TBE);
```

usart_interrupt_disable

The description of `usart_interrupt_disable` is shown as below:

Table 3-529. Function `usart_interrupt_disable`

Function name	<code>usart_interrupt_disable</code>
Function prototype	<code>void usart_interrupt_disable(uint32_t usart_periph, usart_interrupt_enum inttype);</code>
Function descriptions	disable USART interrupt
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
inttype	USART interrupt flag
<i>USART_INT_IDLE</i>	idle interrupt
<i>USART_INT_RBNE</i>	read data buffer not empty interrupt and overrun error interrupt enable interrupt

<i>USART_INT_TC</i>	transmission complete interrupt
<i>USART_INT_TBE</i>	transmit data register empty interrupt
<i>USART_INT_PERR</i>	parity error interrupt
<i>USART_INT_AM</i>	address match interrupt
<i>USART_INT_RT</i>	receiver timeout interrupt
<i>USART_INT_EB</i>	end of block interrupt
<i>USART_INT_LBD</i>	LIN break detection interrupt
<i>USART_INT_ERR</i>	error interrupt enable in multibuffer communication
<i>USART_INT_CTS</i>	CTS interrupt
<i>USART_INT_WU</i>	wakeup from deep-sleep mode interrupt
<i>USART_INT_RFF</i>	receive FIFO full interrupt enable
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* disable USART0 TBE interrupt */
```

```
usart_interrupt_disable(USART0, USART_INT_TBE);
```

usart_command_enable

The description of `usart_command_enable` is shown as below:

Table 3-530. Function `usart_command_enable`

Function name	<code>usart_command_enable</code>
Function prototype	<code>void usart_command_enable(uint32_t usart_periph, uint32_t cmdtype);</code>
Function descriptions	enable USART command
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral

<i>USARTx</i>	x=0,1
Input parameter{in}	
cmdtype	USART interrupt flag
<i>USART_CMD_ABDCM</i> <i>D</i>	auto baudrate detection command
<i>USART_CMD_SBKCM</i> <i>D</i>	send break command
<i>USART_CMD_MMCM</i> <i>D</i>	mute mode command
<i>USART_CMD_RXFCM</i> <i>D</i>	receive data flush command
<i>USART_CMD_TXFCM</i> <i>D</i>	transmit data flush request
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable USART0 command */
```

```
usart_command_enable(USART0, USART_CMD_ABDCMD);
```

usart_interrupt_flag_get

The description of `usart_interrupt_flag_get` is shown as below:

Table 3-531. Function `usart_interrupt_flag_get`

Function name	<code>usart_interrupt_flag_get</code>
Function prototype	<code>FlagStatus usart_interrupt_flag_get(uint32_t usart_periph, usart_interrupt_flag_enum int_flag);</code>
Function descriptions	get USART interrupt and flag status
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral

USARTx	x=0,1
Input parameter{in}	
int_flag	USART interrupt flag
<i>USART_INT_FLAG_EB</i>	end of block interrupt and flag
<i>USART_INT_FLAG_RT</i>	receiver timeout interrupt and flag
<i>USART_INT_FLAG_A M</i>	address match interrupt and flag
<i>USART_INT_FLAG_PE RR</i>	parity error interrupt and flag
<i>USART_INT_FLAG_TB E</i>	transmitter buffer empty interrupt and flag
<i>USART_INT_FLAG_TC</i>	transmission complete interrupt and flag
<i>USART_INT_FLAG_RB NE</i>	read data buffer not empty interrupt and flag
<i>USART_INT_FLAG_RB NE_ORERR</i>	read data buffer not empty interrupt and overrun error flag
<i>USART_INT_FLAG_ID LE</i>	IDLE line detected interrupt and flag
<i>USART_INT_FLAG_LB D</i>	LIN break detected interrupt and flag
<i>USART_INT_FLAG_W U</i>	wakeup from deep-sleep mode interrupt and flag
<i>USART_INT_FLAG_CT S</i>	CTS interrupt and flag
<i>USART_INT_FLAG_ER R_NERR</i>	error interrupt and noise error flag
<i>USART_INT_FLAG_ER R_ORERR</i>	error interrupt and overrun error
<i>USART_INT_FLAG_ER R_FERR</i>	error interrupt and frame error flag
<i>USART_INT_FLAG_RF F</i>	receive FIFO full interrupt and flag
Output parameter{out}	

-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* get the USART0 interrupt flag status */
```

```
FlagStatus status;
```

```
status = usart_interrupt_flag_get(USART0, USART_INT_FLAG_RBNE);
```

usart_interrupt_flag_clear

The description of usart_interrupt_flag_clear is shown as below:

Table 3-532. Function usart_interrupt_flag_clear

Function name	usart_interrupt_flag_clear
Function prototype	void usart_interrupt_flag_clear(uint32_t usart_periph, usart_interrupt_flag_enum flag);
Function descriptions	clear USART interrupt flag in STAT register
Precondition	-
The called functions	-
Input parameter{in}	
usart_periph	usart peripheral
<i>USARTx</i>	x=0,1
Input parameter{in}	
flag	USART interrupt flag
<i>USART_INT_FLAG_PERR</i>	parity error flag
<i>USART_INT_FLAG_ERR_FERR</i>	frame error flag
<i>USART_INT_FLAG_ERR_NERR</i>	noise detected flag
<i>USART_INT_FLAG_RBNE_ORERR</i>	read data buffer not empty interrupt and overrun error flag
<i>USART_INT_FLAG_ERR</i>	error interrupt and overrun error

<i>R_ORERR</i>	
<i>USART_INT_FLAG_IDLE</i>	idle line detected flag
<i>USART_INT_FLAG_TC</i>	transmission complete flag
<i>USART_INT_FLAG_LBD</i>	LIN break detected flag
<i>USART_INT_FLAG_CTS</i>	CTS change flag
<i>USART_INT_FLAG_RT</i>	receiver timeout flag
<i>USART_INT_FLAG_EB</i>	end of block flag
<i>USART_INT_FLAG_AM</i>	address match flag
<i>USART_INT_FLAG_WU</i>	wakeup from deep-sleep mode flag
<i>USART_INT_FLAG_RF</i>	receive FIFO full interrupt and flag
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* clear the USART0 interrupt flag */
usart_interrupt_flag_clear(USART0, USART_INT_FLAG_TC);
```

3.20. WWDGT

The window watchdog timer (WWDGT) is used to detect system failures due to software malfunctions. The WWDGT registers are listed in chapter [3.20.1](#), the FWDGT firmware functions are introduced in chapter [3.20.2](#).

3.20.1. Descriptions of Peripheral registers

WWDGT registers are listed in the table shown as below:

Table 3-533. WWDGT Registers

Registers	Descriptions
WWDGT_CTL	Control register
WWDGT_CFG	Configuration register
WWDGT_STAT	Status register

3.20.2. Descriptions of Peripheral functions

WWDGT firmware functions are listed in the table shown as below:

Table 3-534. WWDGT firmware function

Function name	Function description
wwdgt_deinit	reset the WWDGT counter configuration
wwdgt_enable	start the WWDGT counter
wwdgt_counter_update	configure the WWDGT counter value
wwdgt_config	configure counter value, window value, and prescaler divider value
wwdgt_interrupt_enable	enable early wakeup interrupt of WWDGT
wwdgt_flag_get	check early wakeup interrupt state of WWDGT
wwdgt_flag_clear	clear early wakeup interrupt state of WWDGT

wwdgt_deinit

The description of wwdgt_deinit is shown as below:

Table 3-535. Function wwdgt_deinit

Function name	wwdgt_deinit
Function prototype	void wwdgt_deinit(void);
Function descriptions	reset the WWDGT counter configuration
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	

-	-
Return value	
-	-

Example:

```
/* reset the WWDGT configuration */
```

```
wwdgt_deinit ( );
```

wwdgt_enable

The description of wwdgt_enable is shown as below:

Table 3-536. Function wwdgt_enable

Function name	wwdgt_enable
Function prototype	void wwdgt_enable (void);
Function descriptions	start the WWDGT counter
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* start the WWDGT counter */
```

```
wwdgt_enable ( );
```

wwdgt_counter_update

The description of wwdgt_counter_update is shown as below:

Table 3-537. Function wwdgt_counter_update

Function name	wwdgt_counter_update
Function prototype	void wwdgt_counter_update(uint16_t counter_value);

Function descriptions	configure the WWDGT counter value
Precondition	-
The called functions	-
Input parameter{in}	
counter_value	counter_value: 0x00000000 - 0x0000007F
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* update WWDGT counter to 0x7F */
```

```
wwdgt_counter_update(127);
```

wwdgt_config

The description of wwdgt_config is shown as below:

Table 3-538. Function wwdgt_config

Function name	wwdgt_config
Function prototype	void wwdgt_config(uint16_t counter, uint16_t window, uint32_t prescaler);
Function descriptions	configure counter value, window value, and prescaler divider value
Precondition	-
The called functions	-
Input parameter{in}	
counter	counter: 0x00000000 - 0x0000007F
Input parameter{in}	
window	window: 0x00000000 - 0x0000007F
Input parameter{in}	
prescaler	wwdgt prescaler value
<i>WWDGT_CFG_PSC_D IV1</i>	the time base of WWDGT counter = (PCLK1/4096)/1

<code>WWDGT_CFG_PSC_D IV2</code>	the time base of WWDGT counter = (PCLK1/4096)/2
<code>WWDGT_CFG_PSC_D IV4</code>	the time base of WWDGT counter = (PCLK1/4096)/4
<code>WWDGT_CFG_PSC_D IV8</code>	the time base of WWDGT counter = (PCLK1/4096)/8
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* configure WWDGT counter value to 0x7F, window value to 0x50, prescaler divider value to 8 */
```

```
wwdgt_config(127, 80, WWDGT_CFG_PSC_DIV8);
```

wwdgt_interrupt_enable

The description of `wwdgt_interrupt_enable` is shown as below:

Table 3-539. Function `wwdgt_interrupt_enable`

Function name	<code>wwdgt_interrupt_enable</code>
Function prototype	<code>void wwdgt_interrupt_enable(void);</code>
Function descriptions	enable early wakeup interrupt of WWDGT
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```
/* enable early wakeup interrupt of WWDGT */
```

`wwdgt_interrupt_enable ();`

wwdgt_flag_get

The description of `wwdgt_flag_get` is shown as below:

Table 3-540. Function `wwdgt_flag_get`

Function name	<code>wwdgt_flag_get</code>
Function prototype	<code>FlagStatus wwdgt_flag_get(void);</code>
Function descriptions	check early wakeup interrupt state of WWDGT
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
FlagStatus	SET or RESET

Example:

```
/* test if the counter value update has reached the 0x40 */
```

```
FlagStatus status;
```

```
status = wwdgt_flag_get ( );
```

```
if(status == RESET)
```

```
{
```

```
...
```

```
}else
```

```
{
```

```
...
```

```
}
```

wwdgt_flag_clear

The description of `wwdgt_flag_clear` is shown as below:

Table 3-541. Function wwdgt_flag_clear

Function name	wwdgt_flag_clear
Function prototype	void wwdgt_flag_clear(void);
Function descriptions	clear early wakeup interrupt state of WWDGT
Precondition	-
The called functions	-
Input parameter{in}	
-	-
Output parameter{out}	
-	-
Return value	
-	-

Example:

```

/* clear early wakeup interrupt state of WWDGT */
wwdgt_flag_clear( );

```

4. Revision history

Table 4-1. Revision history

Revision No.	Description	Date
1.0	Initial Release	Aug.16, 2018

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