# GSX Series – The Highest Performance, Longest Life and Most Compact Linear Actuators!

GSX Series linear actuators combine the advantages of Exlar's roller screw technology and T-LAM<sup>™</sup> technology to create the next generation of linear actuators. Exlar uses a specially designed roller screw mechanism for converting electric motor power into linear motion within the actuator. Planetary rollers assembled around the actuator's extending rod follow threads which are precisely machined on the inside surface of the actuator's hollow armature. Linear motion is produced in precise synchronization with the armature rotation. Because this roller screw mechanism has an inherently larger cumulative contact surface, these actuators have a much longer working life, and can handle heavier loads at higher speeds than is possible from a similarly sized unit built around a ball screw system.

Exlar's T-LAM segmented lamination stator technology delivers higher continuous motor torque than is available in traditionally wound motors. T-LAM technology consists of stator segments, each containing individual phase wiring for maximum motor performance. The improved efficiencies of the GSX Series are a result of the limited heat generation qualities inherent in the segmented stator design as seen above. The elimination of



end turns in the stator, and use of thermally conductive potting removes the parts most susceptible to failure in a traditional stator. Other design advantages include:

- Neodymium-iron-boron magnets provide high flux density and maximum motor torque.
- Thermally conductive potting of the entire stator provides increased heat dissipation and provides protection from contamination in oil-cooled units.
- Each stator segment contains individual phase wiring. External winding of individual segments provides

maximum slot fill for maximum motor performance.

- Motors with T-LAM technology have Class 180 H insulation systems compliant with UL requirements.
- UL recognized component.
- Motors with T-LAM technology are CE compliant

The Actuator & Motor, All in one Compact Unit.

With other actuator technologies, customers are usually responsible for engineering the completed linear motion system. This usually includes purchasing the motor, gear reducer, timing belt, mounting hardware, flexible couplings, etc. separately. Then they all must be assembled to perform properly in a given application.

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GSX Series actuators eliminate all this systems engineering. These units are single, fully integrated component packages – much smaller than traditional rotary-to-linear conversion mechanisms.

#### Designed for Closed Loop Servo Systems

Their brushless servo design means GSX Series units can be used in advanced closed-loop servo systems when velocity and positioning is required. Position feedback can be delivered in a number of different forms. These include resolvers, encoders or internally mounted linear position feedback sensors.

#### Sealed for Long Life with Minimum Maintenance

GSX Series actuators have strong advantages whenever outside contami-

nants are an issue. In most rotary-tolinear devices, critical mechanisms are exposed to the environment. Thus, they must be frequently inspected, cleaned and lubricated.

In contrast, the converting components in all Exlar GSX units are mounted within the sealed motor housing. With a simple bushing and seal arrangement on the smooth extending rod, abrasive particles or other contaminants are prevented from reaching the actuator's critical mechanisms. This assures trouble-free operation even in the most harsh environments.

Lubrication requirements are minimal. GSX actuators can be lubricated with either grease or recirculated oil. Grease lubricated units will run up to 10,000 hours without re-greasing. Recirculated oil systems eliminate this type of maintenance altogether. A GSX Series actuator with a properly operating recirculating oil system will operate indefinitely without any other lubrication requirements. Available in Five Frame Sizes 2" GSX20 3" GSX30 4" GSX40 5" GSX50 7" GSX60

If you need a custom design, Exlar's Application Engineering department will work with you to engineer a solution specifically tailored to your application.

Feature	Standard	Optional
External anti-rotate mechanism	No	Yes
Pre-loaded follower	No	Yes
Electric brake	No	Yes
Internal End switches	No	Yes
Connectors	Two MS Style Connectors (3 if brake and/or Switches are Ordered)	Electroless Nickel Connectors/Male NPT with Potted Leads/ Manufacturers Connectors
Mounting Style	Extended Tie Rods, Side Tapped Mounting Holes, Trunnion, Rear Clevis, or Front Flange	Custom Mountings
Rod End	Male or Female: U.S. Standard or Metric	Specials Available To Meet OEM Requirements
Lubrication	Greased, Oil Connection Ports are Built-in for Customer Supplied Recirculated Oil Lubrication	Specials Available To Meet OEM Requirements
Primary Feedback	Standard Encoders or Resolvers to Meet Most Amplifier Requirements	Custom Feedback
Absolute Linear Feedback	No	VRVT, including signal conditioner

#### **EXLAR GSX SERIES ACTUATORS APPLICATIONS INCLUDE:**

Hydraulic cylinder replacement Ball screw replacement Pneumatic cylinder replacement Chip and wafer handling Automated flexible fixturing Dispensers Machine tool Automated assembly Parts clamping Automatic tool changers Volumetric pumps Medical equipment Conveyor diverters / gates Plastics equipment Cut-offs Die cutters Packaging machinery Entertainment Sawmill equipment Open / close doors Fillers Formers Precision grinders

Indexing stages Lifts Product sorting Material cutting Material handling Riveting / fastening / joining Molding Volumetric pumps Semiconductor Pick and place systems Robot manipulator arms Simulators Precision valve control Ventilation control systems Pressing Process control Tube bending Welding Stamping Test stands Tension control Web guidance Wire winding

Repeatable force, reliable positioning accuracy, and flexible control make GSX actuators a perfect fit for assembly presses or test stands.

> Because they cycle quickly and can be synchronized to line speeds, Exlar actuators produce dramatic improvements in web control applications.

In clean room applications like those common to semiconductor manufacturing, the compact design of our GSX Series saves critical space.

Repeatable force control plus positioning accuracy extends the life of costly tools when Exlar linear actuators are used in precision clamping applications.

### GSX Series Speed vs. Force Curves

These charts represent typical linear speed versus linear force curves for the GSX actuators using common brushless motor amplifiers. The GSX Series are compatible with many different brushless motor amplifiers, and differences in the performance ratings of these amplifiers can alter the actuator's performance. Thus, the curves below should be used for estimation only. (Further information is available by contacting Exlar Application Engineering.)





These charts represent typical linear speed versus linear force curves for GSX actuators using common brushless motor amplifiers. The GSX Series are compatible with many different brushless motor amplifiers, and differences in the performance ratings of these amplifiers can alter the actuator's performance. Thus, the curves below should be used for estimation only. (Further information is available by contacting Exlar Application Engineering.)



### GSX Series Lifetime Curves

The  $L_{10}$  expected life of a roller screw linear actuator is expressed as the linear travel distance that 90% of properly maintained roller screws manufactured are expected to meet or exceed. This is not a guarantee and these charts should be used for estimation purposes only.

The underlying formula that defines this value is:

Travel life in millions of inches, where:

- **C** = Dynamic load rating (lbf)
- $\mathbf{F} = \text{Cubic mean applied load}$  (lbf)
- **S** = Roller screws lead (inches)

$$\mathbf{L}_{10} = \left(\frac{\mathbf{C}}{\mathbf{F}}\right)^3 \times \mathbf{S} \equiv$$

100

1,000

400

350

300

50

0

600

500

400

300

200

100

0.

0

Mean Load (pounds)

0

Mean Load (pounds)

All curves represent properly lubricated and maintained actuators.

GSX20

1,000

**GSX30** 

10,000



GSX20 &	GSX30	Performance	Specifications
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Model	Frame	Stroke	Screw	Force*	Max	Continuous	Maximum	Armature	Dynamic	Weight
	Size	(nominal)*	Lead	Rating	Velocity	Motor	Static	Inertia**	Load	(approx.)
	in	in	in	Ib (N)	in/sec	Torque	Load	Ib-in-s <sup>2</sup>	Rating	Ib
	(mm)	(mm)*	(mm)	1/2/3 stack	(mm/sec)	Ib-in (N-m)	Ib (N)	(Kg-m <sup>2</sup> )	Ib (N)	(Kg)
GSX20-0301	2.25	3	0.1	367/578/NA	8.33	7.3/11.5/NA	1250	0.00101	2075	6.5
	(57)	(75)	(2.54)	(1632/2571/NA)	(211.67)	(0.82/1.30/NA)	(5560)	(0.000114)	(9230)	(2.9)
GSX20-0302	2.25	3	0.2	183/289/NA	16.77	7.3/11.5/NA	1250	0.00101	1540	6.5
	(57)	(75)	(5.08)	(814/1286/NA)	(423.33)	(0.82/1.30/NA)	(5560)	(0.000114)	(6850)	(2.9)
GSX20-0304	2.25	3	0.4	92/145/NA	33.33	7.3/11.5/NA	1250	0.00101	1230	6.5
	(57)	(75)	(10.16)	(409/645/NA)	(846.67)	(0.82/1.30/NA)	(5560)	(0.000114)	(5471)	(2.9)
GSX20-0601	2.25	6	0.1	367/578/NA	8.33	7.3/11.5/NA	1250	0.00114	2075	7.0
	(57)	(150)	(2.54)	(1632/2571/NA)	(211.67)	(0.82/1.30/NA)	(5560)	(0.000129)	(9230)	(3.2)
GSX20-0602	2.25	6	0.2	183/289/385	16.67	7.3/11.5/15.3	1250	0.00114	1540	7.0
	(57)	(150)	(5.08)	(814/1286/1713)	(423.33)	(0.82/1.30/1.73)	(5560)	(0.000129)	(6850)	(3.2)
GSX20-0604	2.25	6	0.4	92/145/192	33.33	7.3/11.5/15.3	1250	0.00114	1230	7.0
	(57)	(150)	(10.16)	(409/645/854)	(846.67)	(0.82/1.30/1.73)	(5560)	(0.000129)	(5471)	(3.2)
GSX20-1001	2.25	10	0.1	367/578/NA	8.33	7.3/11.5/NA	1250	0.00133	2075	7.5
	(57)	(250)	(2.54)	(1632/2571/NA)	(211.67)	(0.82/1.30/NA)	(5560)	(0.000150)	(9230)	(3.4)
GSX20-1002	2.25	10	0.2	183/289/385	16.67	7.3/11.5/15.3	1250	0.00133	1540	7.5
	(57)	(250)	(5.08)	(814/1286/1713)	(423.33)	(0.82/1.30/1.73)	(5560)	(0.000150)	(6850)	(3.4)
GSX20-1004	2.25	10	0.4	92/145/192	33.33	7.3/11.5/15.3	1250	0.00133	1230	7.5
	(57)	(250)	(10.16)	(409/645/854)	(846.67)	(0.82/1.30/1.73)	(5560)	(0.000150)	(5471)	(3.4)
GSX20-1201	2.25	12	0.1	367/578/NA	8.33	7.3/11.5/NA	1250	0.00143	2075	8.0
	(57)	(300)	(2.54)	(1632/2571/NA)	(211.67)	(0.82/1.30/NA)	(5560)	(0.000162)	(9230)	(3.6)
GSX20-1202	2.25	12	0.2	183/289/385	16.67	7.3/11.5/15.3	1250	0.00143	1540	8.0
	(57)	(300)	(5.08)	(814/1286/1713)	(423.33)	(0.82/1.30/1.73)	(5560)	(0.000162)	(6850)	(3.6)
GSX20-1204	2.25	12	0.4	92/145/192	33.33	7.3/11.5/15.3	1250	0.00143	1230	8.0
	(57)	(300)	(10.16)	(409/645/854)	(846.67)	(0.82/1.30/1.73)	(5560)	(0.000162)	(5471)	(3.6)
GSX30-0301	3.125	3	0.1	829/1347/NA	5	16.5/26.8/NA	2700	0.00319	5516	9.5
	(79)	(75)	(2.54)	(3688/5992/NA)	(127)	(1.86/3.03/NA)	(12010)	(0.000360)	(24536)	(4.3)
GSX30-0302	3.125	3	0.2	415/674/NA	10	16.5/26.8/NA	2700	0.00319	5800	9.5
	(79)	(75)	(5.08)	(1846/2998/NA)	(254)	(1.86/3.03/NA)	(12010)	(0.000360)	(25798)	(4.3)
GSX30-0305	3.125	3	0.5	166/269/NA	25	16.5/26.8/NA	2700	0.00319	4900	9.5
	(79)	(75)	(12.7)	(738/1197/NA)	(635)	(1.86/3.03/NA)	(12010)	(0.000360)	(21795)	(4.3)
GSX30-0601	3.125	5.9	0.1	829/1347/NA	5	16.5/26.8/NA	2700	0.00361	5516	11.5
	(79)	(150)	(2.54)	(3688/5992/NA)	(127)	(1.86/3.03/NA	(12010)	(0.000408)	(24536)	(5.2)
GSX30-0602	3.125	5.9	0.2	415/674/905	10	16.5/26.8/36	2700	0.00361	5800	11.5
	(79)	(150)	(5.08)	(1846/2998/4026)	(254)	(1.86/3.03/4.07)	(12010)	(0.000408)	(25798)	(5.2)
GSX30-0605	3.125	5.9	0.5	166/269/362	25	16.5/26.8/36	2700	0.00361	4900	11.5
	(79)	(150)	(12.7)	(738/1197/1610)	(635)	(1.86/3.03/4.07)	(12010)	(0.000408)	(21795)	(5.2)
GSX30-1001	3.125	10	0.1	829/1347/NA	5	16.5/26.8/NA	2700	0.00416	5516	19
	(79)	(250)	(2.54)	(3688/5992/NA)	(127)	(1.86/3.03/NA)	(12010)	(0.00047)	(24536)	(8.6)
GSX30-1002	3.125	10	0.2	415/674/905	10	16.5/26.8/36	2700	0.00416	5800	19
	(79)	(250)	(5.08)	(1846/2998/4026)	(254)	(1.86/3.03/4.07)	(12010)	(0.00047)	(25798)	(8.6)
GSX30-1005	3.125	10	0.5	166/269/362	25	16.5/26.8/36	2700	0.00416	4900	19
	(79)	(250)	(12.7)	(738/1197/1610)	(635)	(1.86/3.03/4.07)	(12010)	(0.00047)	(21795)	(8.6)
GSX30-1201	3.125	12	0.1	829/1347/NA	5	16.5/26.8/NA	2700	0.00443	5516	22
	(79)	(305)	(2.54)	(3688/5992/NA)	(127)	(1.86/3.03/NA)	(12010)	(0.000501)	(24536)	(10)
GSX30-1202	3.125	12	0.2	415/674/905	10	16.5/26.8/36	2700	0.00443	5800	22
	(79)	(305)	(5.08)	(1846/2998/4026)	(254)	(1.86/3.03/4.07)	(12010)	(0.000501)	(25798)	(10)
GSX30-1205	3.125	12	0.5	166/269/362	25	16.5/26.8/36	2700	0.00443	4900	22
	(79)	(305)	(12.7)	(738/1197/1610)	(635)	(1.86/3.03/4.07)	(12010)	(0.000501)	(21795)	(10)
GSX30-1402	3.125	14	0.2	415/674/905	10	16.5/26.8/36	2700	0.00473	5800	22
	(79)	(355)	(5.08)	(1846/2998/4026)	(254)	(1.86/3.03/4.07)	(12010)	(0.000534)	(25798)	(10)
GSX30-1405	3.125	14	0.5	166/269/362	25	16.5/26.8/36	2700	0.00473	4900	22
	(79)	(355)	(12.7)	(738/1197/1610)	(635)	(1.86/3.03/4.07)	(12010)	(0.000534)	(21795)	(10)
GSX30-1802	3.125	18	0.2	415/674/905	10	16.5/26.8/36	2700	0.00533	5800	25
	(79)	(455)	(5.08)	(1846/2998/4026)	(254)	(1.86/3.03/4.07)	(12010)	(0.000602)	(25798)	(11.3)
GSX30-1805	3.125	18	0.5	166/269/362	25	16.5/26.8/36	2700	0.00533	4900	25
	(79)	(455)	(12.7)	(738/1197/1610)	(635)	(1.86/3.03/4.07)	(12010)	(0.000602)	(21795)	(11.3)

\*Please note that stroke mm are nominal dimensions. \*\*Inertia +/- 5%

# GSX40 Performance Specifications

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Model	Frame	Stroke	Screw	Force*	Max	Continuous	Maximum	Armature	Dynamic	Weight
	Size	(nominal)*	Lead	Rating	Velocity	Motor	Static	Inertia**	Load	(approx.)
	in	in	in	Ib (N)	in/sec	Torque	Load	Ib-in-s <sup>2</sup>	Rating	Ib
	(mm)	(mm)*	(mm)	1/2/3 stack	(mm/sec)	Ib-in (N-m)	Ib (N)	(Kg-m <sup>2</sup> )	Ib (N)	(Kg)
GSX40-0601	3.9	6	0.1	2393/3966/NA	5	47.6/78.9/NA	5400	0.0152	7900	20
	(99)	(150)	(2.54)	(10645/17642/NA)	(127)	(5.38/8.91/NA)	(24020)	(0.001717)	(35141)	(9.1)
GSX40-0602	3.9	6	0.2	1196/1983/NA	10	47.6/78.9/NA	5400	0.0152	8300	20
	(99)	(150)	(5.08)	(5320/8821/NA)	(254)	(5.38/8.91/NA)	(24020)	( 0.001717)	(36920)	(9.1)
GSX40-0605	3.9	6	0.5	479/793/NA	25	47.6/78.9/NA	5400	0.0152	7030	20
	(99)	(150)	(12.7)	(2131/3527/NA)	(635)	(5.38/8.91/NA)	(24020)	( 0.001717)	(31271)	(9.1)
GSX40-0608	3.9	6	0.75	319/529/NA	37.5	47.6/78.9/107.1	5400	0.0152	6335	20
	(99)	(150)	(19.05)	(1419/2353/NA)	(953)	(5.38/8.91/12.1)	(24020)	( 0.001717)	(28179)	(9.1)
GSX40-0801	3.9	8	0.1	2393/3966/NA	5	47.6/78.9/107.1	5400	0.0163	7900	24
	(99)	(200)	(2.54)	(10645/17642/NA)	(127)	(5.38/8.91/12.1)	(24020)	(0.001842)	(35141)	(10.9)
GSX40-0802	3.9	8	0.2	1196/1983/2692	10	47.6/78.9/107.1	5400	0.0163	8300	24
	(99)	(200)	(5.08)	(5320/8821/11975)	(254)	(5.38/8.91/12.1)	(24020)	( 0.001842)	(36920)	(10.9)
GSX40-0805	3.9	8	0.5	479/793/1077	25	47.6/78.9/107.1	5400	0.0163	7030	24
	(99)	(200)	(12.7)	(2131/3527/4791)	(635)	(5.38/8.91/12.1)	(24020)	( 0.001842)	(31271)	(10.9)
GSX40-0808	3.9	8	0.75	319/529/718	37.5	47.6/78.9/107.1	5400	0.0163	6335	24
	(99)	(200)	(19.05)	(1419/2353/3194)	(953)	(5.38/8.91/12.1)	(24020)	( 0.001842)	(28179)	(10.9)
GSX40-1001	3.9	10	0.1	2393/3966/NA	5	47.6/78.9/107.1	5400	0.0175	7900	28
	(99)	(250)	(2.54)	(10645/17642/NA)	(127)	(5.38/8.91/12.1)	(24020)	(0.001977)	(35141)	(12.7)
GSX40-1002	3.9	10	0.2	1196/1983/2692	10	47.6/78.9/107.1	5400	0.0175	8300	28
	(99)	(250)	(5.08)	(5320/8821/11975)	(254)	(5.38/8.91/12.1)	(24020)	(0.001977)	(36920)	(12.7)
GSX40-1005	3.9	10	0.5	479/793/1077	25	47.6/78.9/107.1	5400	0.0175	7030	28
	(99)	(250)	(12.7)	(2131/3527/4791)	(635)	(5.38/8.91/12.1)	(24020)	(0.001977)	(31271)	(12.7)
GSX40-1008	3.9	10	0.75	319/529/718	37.5	47.6/78.9/107.1	5400	0.0175	6335	28
	(99)	(250)	(19.05)	(1419/2353/3194)	(953)	(5.38/8.91/12.1)	(24020)	(0.001977)	(28179)	(12.7)
GSX40-1201	3.9	12	0.1	2393/3966/NA	5	47.6/78.9/107.1	5400	0.0186	7900	32
	(99)	(305)	(2.54)	(10645/17642/NA)	(127)	(5.38/8.91/12.1)	(24020)	(0.002102)	(35141)	(14.5)
GSX40-1202	3.9	12	0.2	1196/1983/2692	10	47.6/8.9/107.1	5400	0.0186	8300	32
	(99)	(305)	(5.08)	(5320/8821/11975)	(254)	(5.38/8.91/12.1)	(24020)	( 0.002102)	(36920)	(14.5)
GSX40-1205	3.9	12	0.5	479/793/1077	25	47.6/8.9/107.1	5400	0.0186	7030	32
	(99)	(305)	(12.7)	(2131/3527/4791)	(635)	(5.38/8.91/12.1)	(24020)	( 0.002102)	(31271)	(14.5)
GSX40-1208	3.9	12	0.75	319/529/718	37.5	47.6/78.9/107.1	5400	0.0186	6335	32
	(99)	(305)	(19.05)	(1419/2353/3194)	(953)	(5.38/8.91/12.1)	(24020)	( 0.002102)	(28179)	(14.5)
GSX40-1802	3.9	18	0.2	1196/1983/2692	10	47.6/78.9/107.1	5400	0.0220	8300	44
	(99)	(455)	(5.08)	(5320/8821/11975)	(254)	(5.38/8.91/12.1)	(24020)	(0.002486)	(36920)	(20)
GSX40-1805	3.9	18	0.5	479/793/1077	25	47.6/78.9/107.1	5400	0.0220	7030	44
	(99)	(455)	(12.7)	(2131/3527/4791)	(635)	(5.38/8.91/12.1)	(24020)	(0.002486)	(31271)	(20)

\*Please note that stroke mm are nominal dimensions. \*\*Inertia +/- 5%

Model	Frame	Stroke	Screw	Continuous	Max	<b>Continuous</b>	Maximum	Armature	Dynamic	Weight
	Size	(nominal)*	Lead	Force* Rating	Velocity	Motor	Static	Inertia**	Load	(approx.)
	in	in	in	Ib	in/sec	Torque	Load	Ib-in-s <sup>2</sup>	Rating	Ib
	(mm)	(mm)*	(mm)	1/2/3 stack	(mm/sec)	Ib-in (N-m)	Ib (N)	(Kg-m <sup>2</sup> )	Ib (N)	(Kg)
GSX50-0601	5.0	6	0.1	5127/8544/NA	4	102/170/NA	13200	0.03241	15693	54
	(127)	(150)	(2.54)	(22806/38006/NA)	(101.6)	(11.5/19.2/NA)	(58717)	(0.003662)	(69806)	(24)
GSX50-0602	5.0	6	0.2	2564/4272/NA	8	102/170/NA	13200	0.03241	13197	54
	(127)	(150)	(5.08)	(11405/19003/NA)	(203)	(11.5/19.2/NA)	(58717)	(0.003662)	(58703)	(24)
GSX50-0605	5.0	6	0.5	1026/1709/NA	20	102/170/NA	13200	0.03241	11656	54
	(127)	(150)	(12.7)	(4564/7602/NA)	(508)	(11.5/19.2/NA)	(58717)	(0.003662)	(51848)	(24)
GSX50-0610	5.0	6	1.0	513/855/NA	40	102/170/NA	13200	0.03241	6363	54
	(127)	(150)	(25.4)	(2282/3803/NA)	(1016)	(11.5/19.2/NA	(58717)	(0.003662)	(28304)	(24)
GSX50-1001	5.0	10	0.1	5127/8544/NA	4	102/170/NA	13200	0.03725	15693	62
	(127)	(250)	(2.54)	(22806/38006/NA)	(101.6)	(11.5/19.2/NA)	(58717)	(0.004209)	(69806)	(28)
GSX50-1002	5.0	10	0.2	2564/4272/NA	8	102/170/NA	13200	0.03725	13197	62
	(127)	(250)	(5.08)	(11405/19003/NA)	(203)	(11.5/19.2/NA)	(58717)	(0.004209)	(58703)	(28)
GSX50-1005	5.0	10	0.5	1026/1709/2261	20	102/170/226	13200	0.03725	11656	62
	(127)	(250)	(12.7)	(4564/7602/10057)	(508)	(11.5/19.2/25.5)	(58717)	(0.004209)	(51848)	(28)
GSX50-1010	5.0	10	1.0	513/855/1131	40	102/170/226	13200	0.03725	6363	62
	(127)	(250)	(25.4)	(2349/3803/5031)	(1016)	(11.5/19.2/25.5)	(58717)	(0.004209)	(28304)	(28)
GSX50-1402	5.0	14	0.2	2564/4272/5655	8	102/170/226	13200	0.04208	13197	70
	(127)	(355)	(5.08)	(11405/19003/25155	(203)	(11.5/19.2/25.5)	(58717)	(0.004756)	(58703)	(32)
GSX50-1405	5.0	14	0.5	1026/1709/2261	20	102/170/226	13200	0.04208	11656	70
	(127)	(355)	(12.7)	(4564/7602/10057)	(508)	(11.5/19.2/25.5)	(58717)	(0.004756)	(51848)	(32)
GSX60-0603	7.0	6	0.25	5098/NA/NA	10	241/NA/NA	25000	0.1736	25300	69
	(178)	(150)	(6.35)	(22677/NA/NA)	(254)	(27/NA/NA)	(111200)	(0.019614)	(112540)	(31)
GSX60-0605	7.0	6	0.5	2549/NA/NA	20	241/NA/NA	25000	0.1736	22800	69
	(178)	(150)	(12.7)	(11339/NA/NA)	(508)	(27/NA/NA)	(111200)	(0.019614)	(101420)	(31)
GSX60-0610	7.0	6	1.0	1275/NA/NA	40	241/NA/NA	25000	0.1736	21200	69
	(178)	(150)	(25.4)	(5671/NA/NA)	(1018)	(27/NA/NA)	(111200)	(0.019614)	(94302)	(31)
GSX60-1003	7.0	10	0.25	5098/8656/12389	10	241/409/585	25000	0.1943	25300	101
	(178)	(250)	(6.35)	(22677/38504/55109	(254)	(27/46/66)	(111200)	(0.021953)	(112540)	(46)
GSX60-1005	7.0	10	0.5	2549/4328/6195	20	241/409/585	25000	0.1943	22800	101
	(178)	(250)	(12.7)	(11339/19252/27557	(508)	(27/46/66)	(111200)	(0.021953)	(101420)	(46)
GSX60-1010	7.0	10	1.0	1275/2164/3097	40	241/409/585	25000	0.1943	21200	101
	(178)	(250)	(25.4)	(5671/9626/13776)	(1018)	(27/46/66)	(111200)	(0.021953)	(94302)	(46)

Force Rating: The linear force produced by the actuator at continuous motor torque. Max Velocity: The linear velocity that the actuator will achieve at rated motor rpm. Continuous Motor Torque: Torque produced by the motor at rated continuous current. Maximum Static Load: The mechanical load limit of the actuator if re-circulated oil or other cooling method is used to allow higher than rated torque from the motor.

**Armature Inertia**: The rotary inertia of the armature of the GSX Series actuators. For calculation purposes, this value includes the screw inertia in a GSX actuator. **Dynamic Load Rating:** A design constant used in calculating the estimated travel life of the roller screw. The cubic mean load is the load at which the device will perform one million revolutions.

\* GSX offers 1, 2, or 3 stack stators providing 3 torque force levels.

\*Please note that stroke mm are nominal dimensions. \*\*Inertia +/- 5%

GSX50 & GSX60 Performance Specifications

### **GSX20** Mechanical and Electrical Specifications

							GS	X20	-				
Nominal Backlash	in (mm)						0.00	A ( 10)					
Maximum Backlach (pro-loaded)	in (mm)						0.00	<u>+ (.10)</u>					
Lead Accuracy in/ft (r	m/200 mm)						0.00	J.U L ( 025)					
Maximum Padial Load	IIII/300 IIIII) Ib /N)						0.00	(00)					
Maximum Raulai Luau	Ontional						20	(90)					
Elivirollillelital Ratiliy. Stalluaru /	Ορτιοπαί	110	120	150	160	210	220	00/07 050	260	210*	220*	250*	260*
MULUF STATUF BMS Sinusoidal Commutatio	<b>n</b>	110	130	100	100	210	230	200	200	310	330	300	300
Continuous Motor Torque	lhf_in	7.6	7 2	7.0	7.0	11.0	11.5	11.0	11.2	15.2	15.2	1/1.0	15.0
	(Nm)	(0.86)	(0.83)	(0.70)	(0.70)	(1.35)	(1.30)	(1.27)	(1.28)	(1.73)	(1.73)	(1.67)	(1.60)
Torque Constant (Kt)	lbf_in/A	2.5	5.2	(0.73) 83	0.73)	25	5.2	80	10.2	23	53	8.8	10.2
(+/_ 10% @ 25°°)	(Nm/A)	(0.28)	(0.50)	(0.0/1)	(1.07)	(0.28)	(0.50)	(1.00)	(1 15)	(0.26)	(0.60)	(0.00)	(1.15)
Continuous Current Pating: Cro		(0.20)	1.6	(0.34)	(1.07)	(0.20)	0.00)	(1.00)	(1.13)	(0.20)	(0.00)	1.0	(1.15)
Continuous current hating. Gre	Dilad (IL) A	0.4	1.0	1.0	0.0	10.0	2.0	1.4	1.2	1.0	0.Z	1.9	1.0
Deck Current Dating	Jileu (IL) A	0.9	0.1	1.9	1.0	10.0	4.9	2.0	2.0	14.0	0.0	3.0 0.0	ა.ა იი
Transpecidel Commutation	Amps	0.9	J.I	1.9	1.0	10.0	4.9	2.0	2.0	14.0	0.0	3.0	3.3
	11.1 1	7.0	7.0	07	67	44.4	11.0	10.7	10.0	147	14.0	144	14.0
Continuous wotor lorque	IDT-IN	1.3	/.U	0.7	0./	(1.00)	11.0	10.7	1U.ð	14./	14.0	14.1	14.3
T 0	(Nm)	(0.82)	(0.79)	(0.76)	(0./6)	(1.29)	(1.24)	(1.21)	(1.22)	(1.66)	(1.65)	(1.60)	(1.61)
lorque Constant (Kt)	Ibt-in/A	1.9	4.1	/.4	1.4	1.9	4.1	6.9	7.9	1.8	4.1	6.9	7.9
(+/- 10% @ 25°C)	(Nm/A)	(0.22)	(0.46)	(0.73)	(0.84)	(0.22)	(0.46)	(0.78)	(0.89)	(0.21)	(0.46)	(0.77)	(0.89)
Continuous Current Rating: Gre	ased (IG) A	4.2	1.9	1.1	1.0	6.6	3.0	1.7	1.5	9.0	4.0	2.3	2.0
	Diled (IL) A	8.4	3.9	2.3	2.0	13.2	6.0	3.5	3.0	17.9	8.0	4.6	4.0
Peak Current Rating	Amps	8.4	3.9	2.3	2.0	13.2	6.0	3.5	3.0	17.9	8.0	4.6	4.0
Motor Stator Data													
Voltage Constant (Ke)	Vrms/krpm	16.9	35.6	56.9	64.9	16.9	35.6	60.5	69.4	16.0	36.0	60.0	69.4
(+/- 10% @ 25°C)	Vpk/kprm	23.9	50.3	80.9	91.8	23.9	50.3	85.5	98.1	22.6	50.9	84.9	98.1
Pole Configuration	8	8	8	8	8	8	8	8	8	8	8	8	
Resistance (L-L) (+/– 5% @ 25°C)	Ohms	2.6	12.5	35.2	45.8	1.1	5.3	16.0	20.7	0.62	3.1	9.4	12.2
Inductance (L-L)(+/- 15%)	mH	5.1	22.8	58.3	75.8	2.5	11.0	31.7	41.7	1.5	7.4	20.5	27.4
Brake Inertia	lbf-in-sec <sup>2</sup>	.000025	.000025	.000025	.000025	.000025	.000025	.000025	.000025	.000025	.000025	.000025	.000025
	(Kg-cm <sup>2</sup> )	(0.028)	(0.028)	(0.028)	(0.028)	(0.028)	(0.028)	(0.028)	(0.028)	(0.028)	(0.028)	(0.028)	(0.028)
Brake Current @ 24 Vdc	A	.21	.21	.21	.21	.21	.21	.21	.21	.21	.21	.21	.21
Brake Holding Torque - Dry	lbf-in (Nm)	24 (2.71)	24 (2.71)	24 (2.71)	24 (2.71)	24 (2.71)	24 (2.71)	24 (2.71)	24 (2.71)	24 (2.71)	24 (2.71)	24 (2.71)	24 (2.71)
Brake Holding Torque - Oil Lubricate	d Ibf-in (Nm)	8 (0.90)	8 (0.90)	8 (0.90)	8 (0.90)	8 (0.90)	8 (0.90)	8 (0.90)	8 (0.90)	8 (0.90)	8 (0.90)	8 (0.90)	8 (0.90)
Brake Engage/Disengage Time	ms	250/50	250/50	250/50	250/50	250/50	250/50	250/50	250/50	250/50	250/50	250/50	250/50
Mechanical Time Constant (tm),m	s min	6.0	6.5	7.1	7.1	2.5	2.7	2.9	2.8	1.6	1.6	1.7	1.7
	max	8.5	9.2	10.1	10.1	3.6	3.9	4.0	4.0	2.2	2.2	2.4	2.4
Electrical Time Constant (te)	ms	2.0	1.8	1.7	1.7	2.2	2.1	2.0	2.0	2.4	2.4	2.2	2.2
Damping Constant	lbf-in/krpm	0.55	0.55	0.55	0.55	0.55	0.55	0.55	0.55	0.55	0.55	0.55	0.55
	(Nm/krpm)	(0.06)	(0.06)	(0.06)	(0.06)	(0.06)	(0.06)	(0.06)	(0.06)	(0.06)	(0.06)	(0.06)	(0.06)
Friction Torque	lbf-in	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
	(Nm)	(0.11)	(0.11)	(0.11)	(0.11)	(0.11)	(0.11)	(0.11)	(0.11)	(0.11)	(0.11)	(0.11)	(0.11)
Bus Voltage	Vrms	115	230	400	460	115	230	400	460	115	230	400	460
Speed @ Bus Voltage	rpm	5000	5000	5000	5000	5000	5000	5000	5000	5000	5000	5000	5000
Motor Wire Insulation	- F						Class	180 H					
Motor Stator Rating							Class	180 H					
Thermal Switch Case Temperature	J°						1	00					
Standard Connectors (0-ontion)	Motor						MS-311	2-E16-8P					
	Feedback						MS-3112	-F14-18P					
Rr	ke/l imit Sw						MS-311	2-F12-8P					
Dia	ato/ Linnt OW.												

All ratings at 25 degrees Celsius For amplifiers with peak sinusoidal commutation Kt = Ktrms(0.707), lc = lcrms/(0.707), lpk = lpkrms/(0.707) \*The 3 stack motor is not available with the .1 inch lead GSX20. The 3 stack lamination fits only the 6 inch and longer GSX20. The GSX20-03 can only accommodate the 1 or 2 stack.

						GS	X30					
Nominal Backlash in (mn	)					0.004	(.10)					
Maximum Backlash (pre-loaded) in (mn	)					0	.0					
Lead Accuracy in/ft (mm/300 mn	)					0.001	(.025)					
Maximum Radial Load Ib (1	)					30 (	134)					
Environmental Rating: Standard / Optional	,					IP6	5/67					
Motor Stator	118	138	158	168	218	238	258	268	318*	338*	358**	368*
RMS Sinusoidal Commutation												
Continuous Motor Torque Ibf-	n 16.6	16.5	15.7	15.7	26.8	26.8	26.7	26.7	38.7	38.3	36.3	36.3
(Nn	) (1.88)	(1.87)	(1.77)	(1.78)	(3.03)	(3.03)	(3.02)	(3.01)	(4.38)	(4.33)	(4.10)	(4.10)
Torque Constant (Kt) Ibf-in/	A 4.4	8.7	15.5	17.5	4.4	8.7	15.5	17.5	4.4	8.7	15.7	17.6
(+/- 10% @ 25°C) (Nm//	) (0.49)	(0.99)	(1.75)	(1.98)	(0.49)	(0.99)	(1.75)	(1.98)	(0.50)	(0.98)	(1.77)	(1.98)
Continuous Current Rating: Greased (IG)	A 4.2	2.1	1.1	1.0	6.9	3.4	1.9	1.7	9.7	4.9	2.6	2.3
Oiled (IL)	A 8.5	4.2	2.3	2.0	13.7	6.8	3.8	3.4	19.5	9.9	5.2	4.6
Peak Current Rating Amp	s 8.5	4.2	2.3	2.0	13.7	6.8	3.8	3.4	19.5	9.9	5.2	4.6
Trapezoidal Commutation												
Continuous Motor Torque Ibf-	n 15.9	15.8	14.9	15.0	25.6	25.6	25.5	25.5	37.0	36.6	34.8	34.7
(Nn	) (1.79)	(1.78)	(1.69)	(1.70)	(2.89)	(2.89)	(2.88)	(2.88)	(4.18)	(4.13)	(3.91)	(3.92)
Torque Constant (Kt) Ibf-in/	A 3.4	6.8	12.1	13.6	3.4	6.8	12.1	13.6	3.5	6.8	12.2	13.7
(+/- 10% @ 25°C) (Nm//	) (0.39)	(0.77)	(1.37)	(1.54)	(0.39)	(0.77)	(1.37)	(1.54)	(0.39)	(0.76)	1.38	(1.55)
Continuous Current Rating: Greased (IG)	A 5.2	2.6	1.4	1.2	8.4	4.2	2.4	2.1	11.9	6.0	3.2	2.8
Oiled (IL)	A 10.4	5.2	2.8	2.5	16.8	8.4	4.7	4.2	23.9	12.1	6.3	5.7
Peak Current Rating Amp	s 10.4	5.2	2.8	2.5	16.8	8.4	4.7	4.2	23.9	12.1	6.3	5.7
Motor Stator Data												
Voltage Constant (Ke) Vrms/krp	n 29.9	59.7	106.0	119.5	29.9	59.7	106.7	119.5	30.3	59.2	106.9	119.9
(+/- 10% @ 25°C) Vpk/kpr	n 42.2	84.5	149.9	169.0	42.2	84.5	149.9	168.9	42.9	83.8	151.2	169.6
Pole Configuration	8 8	8	8	8	8	8	8	8	8	8	8	
Resistance (L-L)(+/- 5% @ 25°C) Ohm	s 2.8	11.2	39.5	49.6	1.1	4.5	14.1	18.0	0.65	2.6	9.3	11.6
Inductance (L-L)(+/- 15%) m	1 7.7	30.7	96.8	123.0	3.7	14.7	46.2	58.7	2.5	9.5	30.9	38.8
Brake Inertia Ibf-in-se	.00012	.00012	.00012	.00012	.00012	.00012	.00012	.00012	.00012	.00012	.00012	.00012
(Kg-cm	) (0.136)	( 0.136)	( 0.136)	( 0.136)	( 0.136)	( 0.136)	( 0.136)	( 0.136)	( 0.136)	( 0.136)	( 0.136)	( 0.136)
Brake Current @ 24 Vdc	A .72	.72	.72	.72	.72	.72	.72	.72	.72	.72	.72	.72
Brake Holding Torque - Dry Ibf-in (Nn	) 78 (8.81)	78 (8.81)	78 (8.81)	78 (8.81)	78 (8.81)	78 (8.81)	78 (8.81)	78 (8.81)	78 (8.81)	78 (8.81)	78 (8.81)	78 (8.81)
Brake Holding Torque - Oil Lubricated Ibf-in (Nn	) 26 (2.94)	26 (2.94)	26 (2.94)	26 (2.94)	26 (2.94)	26 (2.94)	26 (2.94)	26 (2.94)	26 (2.94)	26 (2.94)	26 (2.94)	26 (2.94)
Brake Engage/Disengage Time m	s 250/50	250/50	250/50	250/50	250/50	250/50	250/50	250/50	250/50	250/50	250/50	250/50
Mechanical Time Constant (tm),ms m	n 6.5	6.5	7.3	7.2	2.6	2.6	2.6	2.6	1.5	1.5	1.7	1.7
ma	x 10.8	10.9	12.2	12.0	4.3	4.3	4.4	4.4	2.5	2.5	2.8	2.8
Electrical Time Constant (te) m	s 2.8	2.7	2.5	2.5	3.3	3.3	3.3	3.3	3.8	3.7	3.3	3.3
Damping Constant Ibf-in/krp	n 1.23	1.23	1.23	1.23	1.23	1.23	1.23	1.23	1.23	1.23	1.23	1.23
(Nm/krpn	) (.14)	(.14)	(.14)	(.14)	(.14)	(.14)	(.14)	(.14)	(.14)	(.14)	(.14)	(.14)
Friction Torque Ibf-	n 2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00
(Nn	) (0.23)	(0.23)	(0.23)	(0.23)	(0.23)	(0.23)	(0.23)	(0.23)	(0.23)	(0.23)	(0.23)	(0.23)
Bus Voltage Vrm	s 115	230	400	460	115	230	400	460	115	230	400	460
Speed @ Bus Voltage rp	n 3000	3000	3000	3000	3000	3000	3000	3000	3000	3000	3000	3000
Motor Wire Insulation						Class	180 H					
Motor Stator Rating						Class	180 H					
Thermal Switch Case Temperature						1	00					
Standard Connectors (O-option) Mote	r					MS-311	2-E16-8P					
Feedbac	k					MS-3112	-E14-18P					
Brake/Limit Sv	I.					MS-311	2-E12-8P					

All ratings at 25 degrees Celsius For amplifiers with peak sinusoidal commutation Kt = Ktrms(0.707), Ic = Icrms/(0.707), Ipk = Ipkrms/(0.707) \*The 3 stack lamination fits only the 6 inch and longer GSX30. The GSX30-03 can only accommodate the 1 or 2 stack. \*\*The 3X8 option is not available in the 3" stroke GSX30 actuator.

### GSX40 Mechanical and Electrical Specifications

						GS	X40				
Nominal Backlash	in (mm)					0.004	(.10)				
Maximum Backlash (pre-loaded)	in (mm)					0	.0				
Lead Accuracy in/ft (r	nm/300 mm)					0.001	(.025)				
Maximum Radial Load	lb (N)					40 (	179)				
Environmental Rating: Standard /	Optional					IP6	5/67				
Motor Stator		118	138	158	168	238	258	268	338*	358*	368*
RMS Sinusoidal Commutatio	on										
Continuous Motor Torque	lbf-in	47.6	47.6	44.7	45.5	78.9	78.8	79.7	107.1	105.5	107.1
· · · · · · · · · · · · · · · · · · ·	(Nm)	(5.38)	(5.37)	(5.05)	(5.14)	(8.91)	(8.91)	(9.00)	(12.10)	(11.92)	(12.10)
Torque Constant (Kt)	lbf-in/A	4.1	8.2	14.6	16.8	8.2	14.6	16.8	8.4	14.8	16.8
(+/- 10% @ 25°C)	(Nm/A)	(0.46)	(0.93)	1.65	(1.90)	(0.93)	(1.65)	(1.90)	(0.95)	(1.65)	(1.90)
Continuous Current Rating: Gre	ased (IG) A	12.9	6.5	3.4	3.0	10.7	6.0	5.3	14.2	8.1	7.1
	Oiled (IL) A	25.9	12.9	6.9	6.0	21.4	12.1	10.6	28.5	16.2	14.2
Peak Current Rating	Amps	25.9	12.9	6.9	6.0	21.4	12.1	10.6	28.5	16.2	14.2
Trapezoidal Commutation											
Continuous Motor Torque	lbf-in	45.5	45.4	42.7	43.5	75.3	75.3	76.1	102.3	100.7	102.3
	(Nm)	(5.14)	(5.13)	(4.83)	(4.91)	(8.51)	(8.50)	(8.60)	(11.56)	(11.38)	(11.56)
Torque Constant (Kt)	lbf-in/A	3.2	6.4	11.4	13.1	6.4	11.4	13.1	6.6	11.4	13.1
(+/- 10% @ 25°C)	(Nm/A)	(0.36)	(0.72)	(1.28)	(1.48)	(0.72)	(1.28)	(1.48)	(0.74)	(1.28)	(1.48)
Continuous Current Rating: Gre	ased (IG) A	15.9	7.9	4.2	3.7	13.1	7.4	6.5	17.4	9.9	8.7
	Oiled (IL) A	31.7	15.8	8.4	7.4	26.3	14.8	13.0	34.9	19.8	17.4
Peak Current Rating	Amps	31.7	15.8	8.4	7.4	26.3	14.8	13.0	34.9	19.8	17.4
Motor Stator Data		-									
Voltage Constant (Ke)	Vrms/krpm	28.1	56.1	96.5	114.8	56.1	99.5	114.8	57.4	99.5	114.8
(+/- 10% @ 25°C)	Vpk/kprm	39.7	79.4	140.7	162.4	79.4	140.7	162.4	81.2	140.7	162.4
Pole Configuration	8	8	8	8	8	8	8	8	8	8	
Resistance (L-L) (+/- 5% @ 25°C)	Ohms	0.4	1.7	6.0	7.8	0.7	2.26	3.0	0.5	1.52	1.9
Inductance (L-L) (+/- 15%)	mH	3.0	11.9	37.5	49.9	5.8	18.2	24.2	4.0	12.0	16.0
Brake Inertia	lbf-in-sec <sup>2</sup>	.00186	.00186	.00186	.00186	.00186	.00186	.00186	.00186	.00186	.00186
	(Ka-cm <sup>2</sup> )	(2.102)	(2.102)	(2.102)	(2.102)	(2.102)	(2.102)	(2.102)	(2.102)	(2.102)	(2.102)
Brake Current @ 24 Vdc	A	.88	.88	.88	.88	.88	.88	.88	.88	.88	.88
Brake Holding Torque - Drv	lbf-in (Nm)	120 (13.56)	120 (13.56)	120 (13.56)	120 (13.56)	120 (13.56)	120 (13.56)	120 (13.56)	120 (13.56)	120 (13.56)	120 (13.56)
Brake Holding Torque - Oil Lubricated	d lbf-in (Nm)	40 (4.52)	40 (4.52)	40 (4.52)	40 (4.52)	40 (4.52)	40 (4.52)	40 (4.52)	40 (4.52)	40 (4.52)	40 (4.52)
Brake Engage/Disengage Time	ms	250/50	250/50	250/50	250/50	250/50	250/50	250/50	250/50	250/50	250/50
Mechanical Time Constant (tm).ms	s min	5.3	5.3	6.0	5.8	2.3	2.3	2.2	1.5	1.5	1.5
	max	7.7	7.7	8.7	8.4	3.3	3.3	3.2	2.1	2.2	2.1
Electrical Time Constant (te)	ms	7.0	7.0	8.2	6.4	8.0	8.0	8.2	8.2	7.9	8.2
Damping Constant	lbf-in/krpm	3.25	3.25	3.25	3.25	3.25	3.25	3.25	3.25	3.25	3.25
	(Nm/krpm)	(0.37)	(0.37)	(0.37)	(0.37)	(0.37)	(0.37)	(0.37)	(0.37)	(0.37)	(0.37)
Friction Torque	lbf-in	4.50	4.50	4.50	4.50	4.50	4.50	4.50	4.50	4.50	4.50
	(Nm)	(0.51)	(0.51)	(0.51)	(0.51)	(0.51)	(0.51)	(0.51)	(0.51)	(0.51)	(0.51)
Bus Voltage	Vrms	115	230	400	460	230	400	460	230	400	460
Speed @ Bus Voltage	rom	3000	3000	3000	3000	3000	3000	3000	3000	3000	3000
Motor Wire Insulation						Class 1	180 H				
Motor Stator Rating						Class 1	180 H				
Thermal Switch Case Temperature	С°					10	0				
Standard Connectors (O-option)	Motor					MS-3102-	E20-15P				
	Feedback					MS-3112-	E14-18P				
Br	ake/Limit Sw.					MS-3112	-E12-8P				
		1									

All ratings at 25 degrees Celsius For amplifiers with peak sinusoidal commutation Kt = Ktrms(0.707), Ic = Icrms/(0.707), Ipk = Ipkrms/(0.707) \*The 3 stack lamination fits only the 8 inch and longer GSX40.

The shortest length of each actuator can only accommodate the 1 or 2 stack.

# GSX50 Mechanical and Electrical Specifications

		GSX50										
Nominal Backlash in (mm)				0.004	4 (.10)							
Maximum Backlash (preloaded) in mm	0.0											
Lead Accuracy in/ft (m/300 mm)				0.001	(.025)							
Maximum Radial Load Ib (N)				100	(445)							
Environmental Rating: Standard				IP	965							
Motor Stator	138	158	168	238	258	268	358*	368*				
RMS Sinusoidal Commutation												
Continuous Motor Torque Ibf-in	106.9	104.4	106.2	179.2	178.2	177.2	236.4	237.5				
(Nm)	(12.07)	(11.80)	(12.00)	(20.25)	(20.13)	(20.02)	(26.71)	(26.83)				
Torque Constant (Kt) Ibf-in/A	11.8	20.1	23.5	11.8	20.1	23.5	20.1	23.9				
(+/- 10% @ 25°C) (Nm/A)	(1.33)	(2.28)	(2.66)	(1.33)	(2.28)	(2.66)	(2.28)	(2.70)				
Continuous Current Rating: Greased (IG) A	10.2	5.8	5.0	17.0	9.9	8.4	13.1	11.1				
Oiled (IL) A	20.3	11.6	10.1	34.1	19.8	16.8	26.2	22.2				
Peak Current Rating Amps	20.3	11.6	10.1	34.1	19.8	16.8	26.2	22.2				
Trapeziodal Commutation												
Continuous Motor Torque Ibf-in	102.0	99.7	101.5	171.1	170.1	169.2	225.8	226.8				
(Nm)	(11.53)	(11.26)	(11.46)	(19.34)	(19.22)	(19.12)	(25.51)	(25.62)				
Torque Constant (Kt) Ibf-in/A	9.2	15.7	18.3	9.2	15.7	18.3	15.7	18.7				
(+/- 10% @ 25°C) (Nm/A)	(1.04)	(1.77)	(2.07)	(1.04)	(1.77)	(2.07)	(1.77)	(2.11)				
Continuous Current Rating: Greased (IG) A	12.4	7.1	6.2	20.9	12.1	10.3	16.1	13.6				
Oiled (IL) A	24.9	14.2	12.4	41.7	24.2	20.6	32.1	27.2				
Peak Current Rating Amps	24.9	14.2	12.4	41.7	24.2	20.6	32.1	27.2				
Motor Stator Data												
Voltage Constant (Ke) Vrms/krpm	80.3	137.6	160.6	80.3	137.6	160.6	137.6	163.4				
(+/- 10% @ 25°C) Vpk/krpm	113.5	194.6	227.1	113.5	194.6	227.1	194.6	231.1				
Pole Configuration 8	8	8	8	8	8	8	8					
Resistance (L-L) (+/- 5% @ 25°C) Ohm	1.00	3.09	4.06	0.37	1.11	1.52	0.66	0.92				
Inductance (L-L) (+/- 15%) mH	23.7	69.6	94.8	10.7	31.6	43.0	20.3	28.7				
Brake Inertia Ibf-in-sec <sup>2</sup>	.008408	.008408	.008408	.008408	.008408	.008408	.008408	.008408				
(Kg-cm²)	(9.5)	(9.5)	(9.5)	(9.5)	(9.5)	(9.5)	(9.5)	(9.5)				
Brake Current at 24 VDC A	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0				
Brake Holding Torque - Dry Ibf-in	354	354	354	354	354	354	354	354				
(Nm)	(39.99)	(39.99)	(39.99)	(39.99)	(39.99)	(39.99)	(39.99)	(39.99)				
Brake Engage/Disengage Time ms	7.3	7.3	7.3	7.3	7.3	7.3	7.3	7.3				
Mechanical Time Constant (tm) ms min	3.3	3.4	3.3	1.2	1.2	1.2	0.7	0.7				
Max	4.7	5.0	4.8	1.8	1.8	1.8	1.1	1.0				
Electrical Time Constant (te) ms	23.6	22.6	23.4	28.9	28.5	28.2	31.0	31.2				
Damping Constant Ibf-in/krpm	7.00	7.00	7.00	7.00	7.00	7.00	7.00	7.00				
(Nm/krpm)	(0.79)	(0.79)	(0.79)	(0.79)	(0.79)	(0.79)	(0.79)	(0.79)				
Friction Torque Ibf-in	8.00	8.00	8.00	8.00	8.00	8.00	8.00	8.00				
(Nm)	(0.90)	(0.90)	(0.90)	(0.90)	(0.90)	(0.90)	(0.90)	(0.90)				
Bus Voltage Vrms	230	400	460	230	400	460	400	460				
Speed @ Bus Voltage rpm	2400	2400	2400	2400	2400	2400	2400	2400				
Motor Wire Insulation				Class	180 H							
Motor Stator Rating				Class	180 H							
Thermal Switch Case Temperature °C				1	00							
Standard Connectors (O-option) Motor				MS-310	2-E20-8P							
Feedback				MS-3112	_E14-18P							
Brake/Limit Sw				MS-311	2-E12-8P							

For amplifiers with peak sinusoidal commutation Kt = Ktrms(0.707), Ic = Icrms/(0.707), Ipk = Ipkrms/(0.707)

\*The 3 stack lamination fits only the 10 inch or longer GSX50

### GSX60 Mechanical and Electrical Specifications

USABU           Marinal Backlish         in (mm)         0.0           Second (10)           Marinan Backlish (pre-back)         in (mm)         0.0           Second (20)           Marinan Backlish (pre-back)         b (0)         Second (20)           Second (20)           Second (20)           Environmental Rating: Sandard (20)         Second (20)           Second (20)         Second (20)           Colspan="4">Second (20)         Second (20)           Colspan="4">Second (20)         Second (20)           Colspan=(40)         Second (20)           Colspan=(40)         Second (20)         Second (20)           Colspan=(40)         Second (20)         Colspan=(40)         Second (20)           Continuos Control Faing (20)         Colspan=(40)         Second (20)         Colspan=(40)         Second (20)           Control Colspan=(40)         Colspan=(40)         Colspan=(40)         Colspan=(40)          Colspan=(40)						007	<u>co</u>						
						658	<u>60</u>						
Maximum backedsing (pre-based) min (mm2)         UPUTURE VETURE VETUR	Nominal Backlash	in (mm)				0.004 (	.10)						
Lask Acturnly         unit (mink 300 min)         Unit (Simple Simple Si	Maximum Backlash (pre-loaded)	in (mm)				0.0							
Maxmen Radial Laad         D (N)           Environmental Rating: Standar ( Optional Environmental Environmental Environmental Environmental Environmental Environmental Environmental Environmental Environmental Environmental Environmental Environmental Environmental Environmental Environmental Environmentation         118         118         118         224         755         134         30.0         63.1         54.6           Continuous Duront Rating         Ange         22.2         12.8         12.2         17.5         134         30.0         63.1         54.6           Targezoital Constant (M)         IbHin         24.12         23.86         24.12         40.65.7         44.4         30.0         63.1         54.6           Torque Constant (M)         IbHin         24.12         23.86         24.12         40.65.7         40.4.0         40.8.3         67.7.3         66.3           Torque Constant (M)         IbHin	Lead Accuracy in/ft (i	nm/300 mm)				0.001 (	.025)						
Environmal Rang: Standard / Optional         IFS6         288         288         288         288         288         388           MMor Stansolidal Commutation         I	Maximum Radial Load	lb (N)				75 (3	37)						
More Stator         138         159         159         228         259         258         358         368         368           IMS Sinuscial Commutation         IV         IV<	Environmental Rating: Standard / Op	tional				IP6	5						
HMS Sinusoidal Commutation         Image Continuous Mater Torque         IbFn         S22.6         24.9         42.83         42.84         43.80         66.31         56.82           Continuous Moter Torque         Ibfin         44.9         25.65         22.44         75.5         43.4         38.0         66.31         56.73           Continuous Moter Torque         Ibfin         (21.22)         22.65         43.33         46.83         16.7         13.8         13.4         22.5         22.	Motor Stator		138	158	168	238	258	268	358	368			
Confinuois Motor Torque         Ibi-n         225.6         228.9         222.8         422.8         473.0         427.5         604.2         615.0           Torque Constant (R)         Ibi-n/A         126.5         (26.53)         (47.99)         (47.97)         (48.30)         66.31         54.6           Confinuois Contratition         (10.1)         (49.9)         25.6         22.4         7.55         43.4         38.0         66.31         54.6           Tapezidal Commutation         (10.1)         (11.92)         (22.2)         (11.11)         (19.6)         27.5         58.6         64.10         405.3         57.70         58.7.3           Torque Constant (N)         (11.4)         61.92         (22.2)         (11.11)         (19.2)         (22.2)         (11.11)         (19.2)         <	RMS Sinusoidal Commutation												
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Continuous Motor Torque	lbf-in	252.6	249.9	252.6	424.8	423.0	427.5	604.2	615.0			
Torque Constant (K)         Ibilink         12.6         21.8         22.2         12.6         21.8         22.2         21.4         25.2           Continuous Current Rating: Grassed         (K)A         22.4         12.8         11.2         37.7         21.7         19.0         31.8         27.3           Deak Current Rating         Grassed         (K)A         44.9         25.6         22.4         75.5         43.4         38.0         63.1         54.6           Tapezoldal Commutation         Cartinuous Motor Torque         1b <sup>4</sup> 44.9         25.6         22.4         75.5         43.4         38.0         63.1         54.6           Continuous Motor Torque         1b <sup>4</sup> 44.9         25.6         22.4         75.5         43.4         38.0         63.1         54.6           Continuous Motor Torque         1b <sup>4</sup> 44.9         25.6         22.4         405.7         44.0.0         406.3         577.0         68.7           Continuous Current Rating Grassed         (K)A         8.8         17         19.6         98.3         17.0         19.6         16.7         13.4           Continuous Current Rating Grassed         (K)A         75.5         92.4         53.0		(Nm)	(28.53)	(28.23)	(28.53)	(47.99)	(47.79)	(48.30)	(68.26)	(69.49)			
(+7-10% s0 25 C)       (MmA)       (1.42)       (2.44)       (2.45)       (2.47)       (1.42)       (2.44)       (2.44)       (2.45)       (2.44)       (2.45)       (2.44)       (2.45)       (2.44)       (2.45)       (2.45)       (4.50)       (4.50)       (4.50)       (4.50)       (4.51)       (4.	Torque Constant (Kt)	lbf-in/A	12.6	21.8	25.2	12.6	21.8	25.2	21.4	25.2			
Continuous Gurrent Rating Greased (IIG) A         22.4         11.2         37.7         21.7         19.0         31.6         27.3           Olied (II) A         44.9         25.6         22.4         75.5         43.4         38.0         63.1         54.6           Peak Current Rating         Amps         44.9         25.6         22.4         75.5         43.4         38.0         63.1         54.6           Continuous Motor Torque         III-In         22.6         22.6         72.5         43.4         38.0         63.1         54.6           Continuous Motor Torque         III-In         22.6         (22.25)         (45.89)         (46.13)         (65.19)         (66.35)           Torque Constant (Kt)         ID+in/A         9.8         17         13.6         9.8         17.3         66.9           Continuous Current Rating Greased         (16) A         27.5         15.7         13.7         46.2         26.5         73.3         66.9           Peak Current Rating Greased         (16) A         27.5         92.4         53.0         46.5         77.3         66.9           Peak Urrent Rating Greased         Motor Stator	(+/- 10% @ 25°C)	(Nm/A)	(1.42)	(2.46)	(2.84)	(1.42)	(2.46)	(2.84)	(2.42)	(2.84)			
Oiled         (I)         A 44.9         25.6         22.4         75.5         43.4         38.0         63.1         54.6           Peak Current Rating         Amys         44.9         25.6         22.4         75.5         43.4         38.0         63.1         54.6           Continuous Motor Torque         Ibrin         241.2         28.6         22.12         400.7         404.0         406.3         577.0         557.3           Continuous Motor Torque         Ibrin         241.2         28.6         22.12         405.7         404.0         406.3         67.7         19.6           Torque Constant (KI)         Ibrin/M         Q.11         (1.92)         (2.22)         (1.11)         (1.92)         22.2         23.3         33.7         33.4           Continuous Current Rating-Gressed         (II)         Q.19         Q.22         Q.24         S5.0         44.5         77.3         66.9           Motor Stator         Mass         8.4         8	Continuous Current Rating: Greased	(IG) A	22.4	12.8	11.2	37.7	21.7	19.0	31.6	27.3			
Peak Current Rating         Angs         44.9         25.6         22.4         75.5         43.4         38.0         63.1         54.6           Trapezoida Commutation         Image Construction         I	Oiled	(IL) A	44.9	25.6	22.4	75.5	43.4	38.0	63.1	54.6			
Trapezoidal Commutation         C41.2         238.6         241.2         40.5         577.0         587.3           Continuous Motor Torque         Ibin         241.2         238.6         241.2         40.5         404.0         408.3         577.0         587.3           Torque Constant (Ki)         Ibin/M         9.8         17         19.6         9.8         17.0         19.6         16.7         19.6         19.7         404.0         40.63.9         22.2         (1.11)         (1.92)         (2.22)         (1.8)         19.6         16.7         19.6         22.3         38.7         38.4           Continuous Current Rating Greased         (16).A         27.5         17.7         46.2         26.5         23.3         38.7         38.4           Motor Stor	Peak Current Rating	Amps	44.9	25.6	22.4	75.5	43.4	38.0	63.1	54.6			
Continuous Motor Torque         IbFin         241.2         238.6         241.2         405.7         40.40         408.3         577.0         587.3           Torque Constant (K1)         IbFin/M         8.8         17         136         9.8         170         19.6         16.7         19.6         16.7         19.6         16.7         19.6         16.7         19.6         16.7         19.6         16.7         19.6         16.7         19.6         16.7         19.6         12.7         13.7         46.2         26.5         23.3         38.4         22.2         (1.8)         12.2         13.4         27.5         92.4         53.0         46.5         77.3         66.9           Peak Current Rating         Amps         54.9         31.4         27.5         92.4         53.0         46.5         77.3         66.9           Voltage Constant (Ke)         Vms/kymm         85.9         148.9         171.8         85.9         149.9         171.8         146.1         171.8           (v1-r 10% @ 25°C)         Vpk/kym         121.5         210.6         243.0         13.0         13.3         0.13         0.14         0.53         0.30         13.0         13.3         0.13	Trapezoidal Commutation												
(Im)         (22.5)         (26.69)         (27.25)         (46.58)         (46.59)         (66.57)         (66.38)           Torque Constant (Ki)         Ibirin/A         9.8         17.0         19.6         16.7         19.6           (4+-10% @ 25 C)         (Nm/M)         (1.11)         (1.92)         (222)         (1.11)         (1.82)         (222)         (1.11)         (1.82)         (222)         (1.11)         (1.82)         (222)         (1.11)         (1.82)         (222)         (1.88)         (222)         (1.88)         (222)         (1.88)         (222)         (1.88)         (222)         (1.88)         (222)         (1.88)         (222)         (1.88)         (222)         (1.88)         (222)         (1.88)         (222)         (1.88)         (222)         (1.88)         (3.8         3.8         3.3         3.3         (3.4         27.5         92.4         53.0         46.5         77.3         66.9           Motor Stator         T <tht< t<="" td=""><td>Continuous Motor Torque</td><td>lbf-in</td><td>241.2</td><td>238.6</td><td>241.2</td><td>405.7</td><td>404.0</td><td>408.3</td><td>577.0</td><td>587.3</td></tht<>	Continuous Motor Torque	lbf-in	241.2	238.6	241.2	405.7	404.0	408.3	577.0	587.3			
Torque Constant (K)         Ib-In/A         9.8         17.0         19.6         17.0         19.6         17.7         19.6         17.7         19.6         17.7         19.6         17.7         19.6         17.7         19.6         17.7         19.6         17.7         19.6         17.7         19.6         17.7         19.6         17.7         19.6         17.7         19.6         17.7         19.6         12.7         12.7         14.6         22.7         13.4         22.7         17.1         14.6         17.3         66.9           Peak Current Rating         Amps         54.9         31.4         27.5         92.4         53.0         46.5         77.3         66.9           Motor Stator           Not         71.8         148.9         171.8         85.9         149.9         171.8         146.1         171.8           Voltage Constant (Ke)         Vmms/kprm         85.9         148.9         171.8         85.9         149.9         171.8         146.1         171.8         146.1         171.8         146.1         171.8         146.1         171.8         166.1         161.5         161.5         161.5         161.5         161.5         161.5		(Nm)	(27.25)	(26.96)	(27.25)	(45.83)	(45.69)	(46.13)	(65.19)	(66.35)			
(+-10% @ 25°)       (Nm/A)       (1.11)       (1.92)       (2.22)       (1.11)       (1.92)       (2.22)       (1.83)       (2.22)         Continuous Current Rating-Greased       (16) A       2.5<	Torque Constant (Kt)	lbf-in/A	9. 8	17	19.6	9.8	17.0	19.6	16.7	19.6			
Continuous Current Rating Greased         (16) A         27.5         15.7         13.7         46.2         26.5         23.3         38.7         33.4           Dield         (L) A         54.9         31.4         27.5         92.4         53.0         46.5         77.3         66.9           Mator Stator          29.24         53.0         46.5         77.3         66.9           Mator Stator          5.9         148.9         171.8         85.9         149.9         171.8         146.1         171.8           (+/- 10% @ 25C)         Vpk/krpm         85.9         148.9         171.8         85.9         149.9         171.8         243.0         208.6         243.0         208.6         243.0         208.6         243.0         208.6         243.0         208.6         243.0         208.6         243.0         208.6         243.0         208.6         243.0         208.6         243.0         208.6         243.0         208.6         243.0         208.6         243.0         208.6         243.0         208.6         243.0         208.6         243.0         208.6         243.0         208.6         208.0         268.0         268.0         268.0         268.0	(+/- 10% @ 25°C)	(Nm/A)	(1.11)	(1.92)	(2.22)	(1.11)	(1.92)	(2.22)	(1.88)	(2.22)			
Oiled         (IL)         54.9         31.4         27.5         92.4         53.0         46.5         77.3         66.9           Peak Current Rating         Amps         54.9         31.4         27.5         92.4         53.0         46.5         77.3         66.9           Motor Stator              53.0         149.9         171.8         146.1         171.8           (/* 10% @ 25°C)         Vpk/krpm         85.9         148.9         171.8         85.9         149.9         171.8         146.1         171.8           (/* 10% @ 25°C)         Vpk/krpm         83.3         1.0         1.3         0.13         0.141         0.53         0.23         0.30           Inductance (L-1) (+/~ 15% @ 25°C)         mi         8.3         24.8         33.0         3.9         11.8         15.8         7.5         10.3           Brake Inertia         Ibf-m-sec*         0.167         0.167         0.167         0.167         0.167         0.167         0.167         0.167         0.167           Brake Current at 24 VDC         Amps         1.13         1.13         1.13         1.13         1.13         1.13         1.13         <	Continuous Current Rating:Greased	(IG) A	27.5	15.7	13.7	46.2	26.5	23.3	38.7	33.4			
Peak Current Rating         Amps         54.9         31.4         27.5         92.4         53.0         46.5         77.3         66.9           Motor Stator         C         C         C         C         C         C         C           Voltage Constant (ke)         Vms/krym         85.9         148.9         171.8         85.9         149.9         171.8         20.6         243.0         20.6         20.7         20.6         20.7         20.6         20.7         20.7         20.6         20.7         20.6         20.7         20.6         20.7         20.6         20.7         20.6 <th< td=""><td>Oiled</td><td>(IL) A</td><td>54.9</td><td>31.4</td><td>27.5</td><td>92.4</td><td>53.0</td><td>46.5</td><td>77.3</td><td>66.9</td></th<>	Oiled	(IL) A	54.9	31.4	27.5	92.4	53.0	46.5	77.3	66.9			
Motor Stator         Image	Peak Current Rating	Amps	54.9	31.4	27.5	92.4	53.0	46.5	77.3	66.9			
Voltage Constant (ke)         Vmms/kprm         85.9         148.9         171.8         85.9         149.9         171.8         146.1         171.8           (+/- 10% @ 25°C)         Vpk/kmp         121.5         210.6         243.0         206.6         243.0           Pole Configuration         8         101         101         101         101         101         101         101         101         101         101         101         101         101         101         101         101         101         101         101	Motor Stator												
(+/- 10% @ 25°C)       Vpk/krpm       121.5       210.6       243.0       121.5       210.6       243.0       206.6       243.0         Pole Configuration       8 <td>Voltage Constant (Ke)</td> <td>Vrms/kprm</td> <td>85.9</td> <td>148.9</td> <td>171.8</td> <td>85.9</td> <td>149.9</td> <td>171.8</td> <td>146.1</td> <td>171.8</td>	Voltage Constant (Ke)	Vrms/kprm	85.9	148.9	171.8	85.9	149.9	171.8	146.1	171.8			
Pole Configuration         8         8         8         8         8         8         8         8         8         8         8         8           Resistance (L-L) (+/- 5% @ 25°C)         0hms         0.33         1.0         1.3         0.13         0.41         0.53         0.23         0.30           Inductance (L-L) (+/- 15%)         mH         8.3         24.8         33.0         3.9         11.8         15.8         7.5         10.3           Brake Inerita         Ibf-in-sec <sup>2</sup> 0.0167         0.0167         0.0167         0.0167         0.0167         0.0167         0.0167         0.0167         0.0167         0.0167         0.0167         0.0167         0.0167         0.0167         0.0167         0.0167         0.0167         0.0167         0.00 (67.8)         600 (67.8)	(+/- 10% @ 25°C)	Vpk/krpm	121.5	210.6	243.0	121.5	210.6	243.0	206.6	243.0			
Resistance (L-L) (+/- 5% @ 25°C)         Ohms         0.33         1.0         1.3         0.13         0.41         0.53         0.23         0.30           Inductance (L-L) (+/- 15%)         mH         8.3         24.8         33.0         3.9         11.8         15.8         7.5         10.3           Brake Inertia         lbf-in-sec <sup>2</sup> .0167         .0167	Pole Configuration		8	8	8	8	8	8	8	8			
Inductance (L-L) (+-15%)         mH         8.3         24.8         33.0         3.9         11.8         15.8         7.5         10.3           Brake Inertia         Ibf-in-sec'         0.167<	Resistance (L-L) (+/- 5% @ 25°C)	Ohms	0.33	1.0	1.3	0.13	0.41	0.53	0.23	0.30			
Brake Inertia         Ibf-in-sec <sup>2</sup> .0167         .0167<	Inductance (L-L) (+/– 15%)	mH	8.3	24.8	33.0	3.9	11.8	15.8	7.5	10.3			
(Kg-cm <sup>2</sup> )         (18.86)         (00 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (67.8)         600 (57.8)         600 (57.8)         600 (57.8)         600 (57.8)         600 (57.8)         600 (57.8)	Brake Inertia	lbf-in-sec <sup>2</sup>	.0167	.0167	.0167	.0167	.0167	.0167	.0167	.0167			
Brake Current at 24 VDC         Amps         1.13         1.		(Kg-cm <sup>2</sup> )	(18.86)	(18.86)	(18.86)	(18.86)	(18.86)	(18.86)	(18.86)	(18.86)			
Brake Holding Torque - Dry         Ibf-in (Nm)         600 (67.8)         375 (42.38)         375	Brake Current at 24 VDC	Amps	1.13	1.13	1.13	1.13	1.13	1.13	1.13	1.13			
Brake Holding Torque - Oil Lubricated         Ibf-in (Nm)         375 (42.38)	Brake Holding Torque - Dry	lbf-in (Nm)	600 (67.8)	600 (67.8)	600 (67.8)	600 (67.8)	600 (67.8)	600 (67.8)	600 (67.8)	600 (67.8)			
Brake Engage/Disengage Time         ms         250/50         12         1.2         1.2         1.2         1.2         1.2           Max         5.6         5.7         5.6         2.3         2.3         2.3         1.3         1.3         1.3           Electrical Time Constant (te),         ms         25.4         24.6         25.1         29.4         29.1         29.8         33.0         34.2           Damping Constant         Ibf-in/krpm         28.0         28.0         28.0         28.0         28.0         28.0         28.0         28.0         28.0         28.0         28.0         28.0         28.0         28.0         28.0	Brake Holding Torque - Oil Lubricated	lbf-in (Nm)	375 (42.38)	375 (42.38)	375 (42.38)	375 (42.38)	375 (42.38)	375 (42.38)	375 (42.38)	375 (42.38)			
Mechanical Time Constant (tm), ms         min         5.0         5.1         5.0         2.0         2.1         2.0         1.2         1.2           max         5.6         5.7         5.6         2.3         2.3         2.3         1.3         1.3           Electrical Time Constant (te),         ms         25.4         24.6         25.1         29.4         29.1         29.8         33.0         34.2           Damping Constant         Ibf-in/krpm         28.0         40.0         40.0         40.0         40.0         40.0         40.0         40.0         40.0         46.0         28.0         2400         2400         2400 <t< td=""><td>Brake Engage/Disengage Time</td><td>ms</td><td>250/50</td><td>250/50</td><td>250/50</td><td>250/50</td><td>250/50</td><td>250/50</td><td>250/50</td><td>250/50</td></t<>	Brake Engage/Disengage Time	ms	250/50	250/50	250/50	250/50	250/50	250/50	250/50	250/50			
max         5.6         5.7         5.6         2.3         2.3         2.3         1.3         1.3           Electrical Time Constant (te),         ms         25.4         24.6         25.1         29.4         29.1         29.8         33.0         34.2           Damping Constant         lbf-in/krpm         28.0         40.0         40.0         40.0         40.0         40.0         40.0         40.0         40.0         460         29.0         2400         2400         2400         2400         2400	Mechanical Time Constant (tm), ms	min	5.0	5.1	5.0	2.0	2.1	2.0	1.2	1.2			
Electrical Time Constant (te),         ms         25.4         24.6         25.1         29.4         29.1         29.8         33.0         34.2           Damping Constant         lbf-in/krpm         28.0         40.0         40.0         40.0         40.0         40.0         40.0         40.0         40.0         40.0         46.0         28.0         24.00         24.00         24.00         24.00         24.00         24.00         24.00         24.00         24.00         24.00		max	5.6	5.7	5.6	2.3	2.3	2.3	1.3	1.3			
Damping Constant         Ibf-in/krpm         28.0         40.0         24.00         24.00         24.00         24.00 <t< td=""><td>Electrical Time Constant (te),</td><td>ms</td><td>25.4</td><td>24.6</td><td>25.1</td><td>29.4</td><td>29.1</td><td>29.8</td><td>33.0</td><td>34.2</td></t<>	Electrical Time Constant (te),	ms	25.4	24.6	25.1	29.4	29.1	29.8	33.0	34.2			
(Nm/krpm)         (3.16)         (4.0)         40.0	Damping Constant	lbf-in/krpm	28.0	28.0	28.0	28.0	28.0	28.0	28.0	28.0			
Friction Torque         Ibf-in/krpm         40.0         40.		(Nm/krpm)	(3.16)	(3.16)	(3.16)	(3.16)	(3.16)	(3.16)	(3.16)	(3.16)			
(Nm/krpm)         (4.52)         (4.5	Friction Torque	lbf-in/krpm	40.0	40.0	40.0	40.0	40.0	40.0	40.0	40.0			
Bus Voltage         Vrms         230         400         460         230         400         460         460           Speed @ Bus Voltage         rpm         2400		(Nm/krpm)	(4.52)	(4.52)	(4.52)	(4.52)	(4.52)	(4.52)	(4.52)	(4.52)			
Speed @ Bus Voltage         rpm         2400 <td>Bus Voltage</td> <td>Vrms</td> <td>230</td> <td>400</td> <td>460</td> <td>230</td> <td>400</td> <td>460</td> <td>400</td> <td>460</td>	Bus Voltage	Vrms	230	400	460	230	400	460	400	460			
Motor Wire Insulation     Class 180 H       Motor Stator Rating     Class 180 H       Thermal Switch Case Temperature °C     100       Standard Connectors (0-option)     Motor       Feedback     MS-3102-E24-10P       Brake/Limit Sw     MS-3112_E14-18P	Speed @ Bus Voltage	rpm	2400	2400	2400	2400	2400	2400	2400	2400			
Motor Stator Rating     Class 180 H       Thermal Switch Case Temperature     °C       Standard Connectors (0-option)     Motor       Feedback     MS-3102-E24-10P       Feedback     MS-3112_E14-18P       Brake/Limit Sw     MS-3112-E12-8P	Motor Wire Insulation			Class 180 H									
Thermal Switch Case Temperature     °C     100       Standard Connectors (0-option)     Motor     MS-3102-E24-10P       Feedback     MS-3112_E14-18P       Brake/Limit Sw     MS-3112-E12-8P	Motor Stator Rating					Class	180 H						
Standard Connectors (0-option)         Motor         MS-3102-E24-10P           Feedback         MS-3112_E14-18P           Brake/Limit Sw         MS-3112-E12-8P	Thermal Switch Case Temperature	C°				10	0						
Feedback         MS-3112_E14-18P           Brake/Limit Sw         MS-3112-E12-8P	Standard Connectors (O-option)	Motor				MS-3102-	E24-10P						
Brake/Limit Sw MS-3112-E12-8P		Feedback				MS-3112_	_E14-18P						
	Bi	ake/Limit Sw				MS-3112	-E12-8P						

For amplifiers with peak sinusoidal commutation Kt = Ktrms(0.707), Ic = Icrms/(0.707), Ipk = Ipkrms/(0.707)

# GSX Series – System Configuration

GSX Series actuators include an integrated brushless servo motor. Exlar's unique design gives users a variety of the feedback configuration options so GSX units can be powered by almost any brushless motor amplifier on the market.

This flexibility means GSX actuators can be incorporated into today's highest performance single and multi-axis motion control systems. In anything from food and beverage packaging, to multi-axis turning centers, to aircraft assembly, GSX Series units show incredible performance and durability.

The schematic below shows the typical connections for a single axis system with actuator and servo amplifier.



Drawings subject to change. Consult Exlar for certified drawings.

# GSX Series Cable and Connector Selection

This section provides you with cable part numbers for operation of your GSX Series actuators with both Exlar's and other manufacturers' servo drives.

The "O" connector option on the GSX Series of actuators provides for an actuator with Exlar's standard MS style connectors, compatible with Exlar's standard cables.

The "M" connector option on the GSX series of actuators provides for an actuator configured with connectors that allow the end user to purchase the feedback cable or power and feedback cables from the manufacturer of their servo amplifier, thus eliminating the headaches and confusion that can arise from power and feedback wiring.

Depending on actuator size, voltage, and cable availability from the amplifier manufacturer, some cables must be obtained from Exlar.

For amplifier manufacturers who use standard style military connectors, with molded and shielded cables, the feedback cable can be purchased from the amplifier manufacturer, and the power cable purchased from Exlar. The Exlar power cables with the PCx-MC-xxx model numbers are molded and shielded and provide a good match with the cables provided by the amplifier manufacturer.

For some amplifier manufacturers who utilize a different style of connector, when the "M" option is available from Exlar, both the connectors will be configured to allow the feedback and power cables to be purchased from the amplifier manufacturer. Consult Exlar for details on all connector configurations.

Cables	For Actu	ators With Exlar Standard "O" Connections	
Power	Connector-		Standard Exlar
Cables	ization	Description	Power Cable
GSX20	0	Standard Power, Molded, Shielded	PC6-MC-xxx
GSX30	0	Standard Power, Anodized	PC1-AC-xxx
	E	Standard Power, Electroless Nickel, Environmentally Sealed, EMI/RFI Shielded	PC1-EC-xxx
GSX40	0	Standard Power, Molded, Shielded	PC7-MC-xxx
GSX50	0	Standard Power, Anodized	PC7-AC-xxx
	E	Standard Power, Electroless Nickel, Environmentally Sealed, EMI/RFI Shielded	PC7-EC-xxx
GSX60	0	Standard Power, Anodized	PC3-AC-xxx
	E	Standard Power, Electroless Nickel, Environmentally Sealed, EMI/RFI Shielded	PC3-EC-xxx
Feedback			Standard Exlar
Cables			Feedback Cable
GSX20	0	Standard Resolver Feedback, Anodized	RC1-AC-xxx
GSX30	0	Standard Encoder Feedback, Anodized	EC1-AC-xxx
	E	Standard Resolver Feedback, Electroless Nickel, Environmentally Sealed, EMI/RFI Shielded	RC1-EC-xxx
	E	Standard Encoder Feedback, Electroless Nickel, Environmentally Sealed, EMI/RFI Shielded	EC1-EC-xxx
GSX40	0	Standard Resolver Feedback, Anodized	RC1-AC-xxx
GSX50	0	Standard Encoder Feedback, Anodized	EC1-AC-xxx
	E	Standard Resolver Feedback, Electroless Nickel, Environmentally Sealed, EMI/RFI Shielded	RC1-EC-xxx
	E	Standard Encoder Feedback, Electroless Nickel, Environmentally Sealed, EMI/RFI Shielded	EC1-EC-xxx
GSX60	0	Standard Resolver Feedback, Anodized	RC1-AC-xxx
	0	Standard Encoder Feedback, Anodized	EC1-AC-xxx
	E	Standard Resolver Feedback, Electroless Nickel, Environmentally Sealed, EMI/RFI Shielded	RC1-EC-xxx
	E	Standard Encoder Feedback, Electroless Nickel, Environmentally Sealed, EMI/RFI Shielded	EC1-EC-xxx
Brake			Standard Exlar
Cables			Brake Cable
GSX20	0	Standard Brake Cable, Anodized	BC1-AC-xxx
GSX30	E	Standard Brake Cable, Electroless Nickel, Environmentally Sealed, EMI/RFI Shielded	BC1-EC-xxx
GSX40	0	Standard Brake Cable, Anodized	BC1-AC-xxx
GSX50	E	Standard Brake Cable, Electroless Nickel, Environmentally Sealed, EMI/RFI Shielded	BC1-EC-xxx
GSX60	0	Standard Brake Cable, Anodized	BC1-AC-xxx
	E	Standard Brake Cable, Electroless Nickel, Environmentally Sealed, EMI/RFI Shielded	BC1-EC-xxx

Cabl	es For Actuators Wit	h "M" C	onnectors (	standard lengths of	15´, 25´ an	ıd 50´)
Exlar Actuator	Amplifier Manufacturer and Type	Exlar Feedback Callout	Power Cable Manufacturer	Power Cable Part Number	Feedback Cable Manufacturer	Feedback Cable Part Number
GSX20 GSX30	Allen Bradley Ultra 100/200	AB1	Exlar	PC6-MC-xxx	Allen Bradley	9101-1366-xxx
	Allen Bradley Ultra 3000/5000	AB7*	Allen Bradley	2090-UXNPAMP-14Sxx	Allen Bradley	2090-UXNFBMP-Sxx
	Allen Bradley Ultra 3000/5000	AB4/AB5*	Allen Bradley	2090-UXNPAMP-14Sxx	Allen Bradley	2090-UXNFBMP-Sxx**
	Control Techniques En, Epsilon and MDS Series	EM2	Control Techniques	CMDS-xxx	Control Techniques	CFCS-xxx
	Kollmorgen Servo Star & Servo Star CD	KM1	Kollmorgen	CSSSRHA1H-xxx (set includes feedback cable)	Kollmorgen	CSSSRHA1H-xxx (set includes power cable)
	Kollmorgen Servo Star 600	KM5/KM2	Kollmorgen	CSSSRHG1H-xxx (set includes feedback cable)	Kollmorgen	CSSSRHG1H-xxx (set includes power cable)
	Kollmorgen Servo Star 600	KM3/KM4	Kollmorgen	CSSSS3HG2H-xxx set includes feedback cable)	Kollmorgen	CSSSS3HG2H-xxx (set includes power cable)
	Bosch/Rexroth Indramat DKC Series, ECO Drive	IN1	Bosch/Rexroth Indramat	IKG4077, IKG4017, IKG4009, IKG4008 depending on Indramat amplifier	Bosch/Rexroth Indramat	IKS4001
	Bosch/Rexroth Indramat	IN2	Bosch/Rexroth	IKG4077, IKG4017, IKG4009, IKG4008 depending on Indramat amplifier	Bosch/Rexroth	IKS4001
	Bosch/Rexroth Indramat	IN4/IN3	Bosch/Rexroth	IKG4009	Bosch/Rexroth	IKS4374
	Bosch/Rexroth Indramat	IN1	Bosch/Rexroth	IKG4077	Bosch/Rexroth	IKS4001
	Bosch/Rexroth Indramat	IN2	Bosch/Rexroth	IKG4077	Bosch/Rexroth	IKS4001
	Bosch/Rexroth Indramat	IN3	Bosch/Rexroth	IKG4077	Bosch/Rexroth	IKS4374
	Parker Compumotor	PC3	Exlar	PC6-MC-xxx	Parker	71-018308-XX
	Yaskawa Sigma II Series	YS3	Yaskawa	B1E-xxA	Yaskawa	JZSP-CMP02-XX(B)
	(3 Inch and smaller motors 100/200VAC) Yaskawa Sigma II Series	YS3	Yaskawa	BAE-xxA	Yaskawa	JZSP-CMP02-XX(B)
	(3 Inch and smaller motors 400VAC) Yaskawa Sigma II Series	YS2	Yaskawa	B1E-xxA	Yaskawa	JZSP-CMP02-XX(B)
	(4 inch and larger motors 100/200VAC) Yaskawa Sigma II Series	YS2	Yaskawa	BAE-xxA	Yaskawa	JZSP-CMP02-XX(B)
GSX40	(4 inch and larger motors 400VAC) Allen Bradley	AB1	Exlar	2090-UXNPAMP-14Sxx – GSX40 only	Allen Bradley	9101-1366-xxx
GSX50	Oltra 100/200 Allen Bradley	AB7*	Allen Bradley	2090-UXNPAMP-10Sxx – GSX50 only 2090-UXNPAMP-14Sxx – GSX40 only	Allen Bradley	2090-UXNFBMP-Sxx
	Allen Bradley	AB4/AB5*	Allen Bradley	2090-UXNPAMP-10Sxx – GSX50 only 2090-UXNPAMP-14Sxx	Allen Bradley	2090-UXNFBMP-Sxx**
	Ultra 3000/5000 Control Techniques En,	EM2	Control Techniques	CMMS-xxx	Control	CFCS-XXX
	Epsilon and MDS Series Kollmorgen Servo Star	KM1	Kollmorgen	CSSSRHA2H-xxx	Techniques Kollmorgen	CSSSRHA2H-xxx
	& Servo Star CD Kollmorgen	KM5/KM2	Kollmorgen	(set includes feedback cable) CSSSRHG2H-xxx	Kollmorgen	(set includes power cable) CSSSRHG2H-xxx
	Servo Star 600 Kollmorgen	KM4/KM3	Kollmorgen	(set includes feedback cable) CSSSS3HG2H-xxx	Kollmorgen	(set includes power cable) CSSSS3HG2H-xxx
	Servo Star 600 Bosch/Rexroth	IN1	Bosch/Rexroth	(set includes feedback cable) IKG4009	Bosch/Rexroth	(set includes power cable) IKS4001
	Indramat DKC Series, ECO Drive Bosch/Rexroth	IN2	Indramat Bosch/Rexroth	IKG4009	Indramat Bosch/Rexroth	IKS4001
	Indramat DKC Series, ECO Drive	IN3/IN4	Indramat Bosch/Bexroth	IKG4009	Indramat Bosch/Bexroth	IKS4374
	Indramat DKC Series, ECO Drive	IN1	Indramat Bosch/Beyroth	IKG4077	Indramat Bosch/Beyroth	IKS4001
	Indramat DIAX Series	IN2	Indramat Bosch/Beyroth	IKG4077	Indramat Bosch/Revroth	IK\$4001
	Indramat DIAX Series	1112	Indramat Bosch/Revroth	IKG4077	Indramat Bosch/Revroth	IK\$4374
	Indramat DIAX Series		Indramat		Indramat	71 019209 XX
	Gemini Series	F03	Exidi		Compumotor	/ 1-010300-XX
	(3 inch and smaller motors 100/200VAC)	100	Yaskawa		Yaskawa	
	(3 inch and smaller motors 400VAC)	100	TaskaWa		raskawa	
	(4 inch and larger motors 100/200VAC)	152	Yaskawa	BIE-XXA	Yaskawa	JZSP-UMPU2-XX(B)
	Yaskawa Sigma II Series (4 inch and larger motors 400VAC)	152	Yaskawa	вае-хха	Yaskawa	JZSP-UMPU2-XX(B)
GSX60	As in tables above for	As in tables above for	Exlar	PC3-AC-xxx	As in tables above for	As in tables above for
	GSX40/GSX50 Allen Bradley	GSX40/GSX50 AB4/AB5/AB7*	Allen Bradley	2090-UXNPAMP-10Sxx	GSX40/GSX50 Allen Bradley	GSX40/GSX50 2090-UXNFBMP-Sxx
* Brake C	Ultra 3000/5000 able AB4/AB5 and AB7, 2090-UXNPAMP-18S>	x				

### High Power/Minimal Maintenance Operation Guidelines

Exlar GSX series actuators can be lubricated with either grease or oil. All are shipped from the factory fully greased and are capable of functioning for many thousands of hours between re-greasings. Typically, greased lubrication is preferred for lower speed or intermittent duty applications. In these situations, you simply mount the actuator, connect the servo amplifier, and run.

However, many GSX Series actuators are deployed into applications involving high speed, high force, or both. To provide the cooling required when operating at these high power levels and/or to eliminate periodic re-greasing, all GSX units have another built-in feature. They are designed with an internal circulation path and the portings necessary for customers to convert from grease by connecting a recirculation oil system. This feature makes GSX units the only all-electric actuators on the market capable of true continuous-duty performance in moderate and high power applications when heat is an issue.

The conversion to externally supplied oil is simple. Identify which port will be lowest when the actuator is mounted. That will become the oil supply side. *(For optimum cooling it is important that GSX*  actuators are mounted so the highside port is at least above the unit's centerline, preferably in the top quarter region. This assures that the stator windings receive the oil's cooling benefits.) Just connect your oil lines and you're done. Residual grease will be flushed out and filtered during initial operation.

A typical oil cooling system is shown below. Whenever application requirements are such that the RMS current requirement exceeds the continuous current rating of the GSX motor, oil cooling should be used to keep case temperatures below their 85°C maximum specification. For very high speed applications, consult Exlar for oil routing recommendations.



### Oil Cooling and Lubrication

Oil lubrication will extend the life of the actuator and improve its efficiency. More importantly, oil is required in high power applications for cooling. In applications where the RMS current exceeds  $I_G$  (see electrical specs on pages 13-17), oil lubrication is required in order to maintain the case temperature

below its maximum of 85°C<sup>1</sup>. When such oil lubrication is required, you can determine oil flow rates and case temperatures from this information:

Actuator Load (	Constants	$K_{L} = \left(\frac{C \times Gal}{Hour}\right)$	
K <sub>L GSX20</sub>	=	40	
K <sub>L GSX30</sub>	=	70	
$K_{L GSX40}$	=	95	
$K_{L GSX50}$	=	125	
$K_{L GSX60}$	=	260	



Use this relationship to determine oil flow requirements: W

$$W = K_L \frac{F_L}{\Delta T}$$
 Where  $\Delta_T = T_{CASE} - T_{OIL}$ 

### Consider The Following Examples:

### CASE 1:

A GSX30-238 requires 4 amps of RMS current to perform the required application. The incoming oil temperature is 45°C, and we desire to maintain the actuator at it's maximum case temperature of 85°C.

 $F_{L} = (4/3.4)^{2} = 1.38$  W = [(1.38 x 70)/(85 - 45)] = 2.415 GAL / HOUR

### CASE 2:

A GS45 requires 12 amps of RMS current to perform the required application. The incoming oil temperature is 45°C, and we desire to maintain the actuator at it's maximum case temperature of 85°C.

$$F_L = (12/8)^2 = 2.25$$
  $W = [(2.25*125) / (85 - 45)] = 7.0 \text{ GAL} / HOUR$ 

1. GSX Series actuators can be ordered with features that allow them to achieve case temperatures of 150°C. Inquire with Exlar's application engineers or local representative for details.

### GSX Series Linear Actuator Anti-rotation Option

The unique design of the GSX Series of linear actuators permits the extending rod to rotate. This simplifies actuator setup by allowing the user to rotate the rod and thread it in and out of the actuator for mechanical attachment or system testing.

However, this feature also requires that once setup and testing are completed, the rod be kept from rotating so proper linear motion will be maintained. In most applications the actuator's load is coupled to linear bearings, or some other support device. In these cases the load cannot rotate, and a separate anti-rotation system is not needed.

For applications in which the load is free to rotate, Exlar offers the anti-rotation systems shown below. Shorter GSX units use an anti-rotation arm on one side of the actuator. Longer strokes (defined above right) use rods on both sides.

### Anti-rotation Option GSX20, GSX30, GSX40 and GSX60





For longer strokes a second Anti-Rotate arm is used. Longer strokes are:

- GSX20, 12 inch
- GSX30, 10 inch and longer.
- GSX40, 12 inch and longer
- GSX60, 10 inch only and uses a single sided Anti-Rotate.

Dims in inches (mm)	GSX20	GSX30	GSX40	GSX60
Α	0.60 (15.2)	0.79 (20.1)	1.25 (31.8)	1.75 (44.5)
В	1.81 (46.0)	2.54 (64.5)	3.78 (96.0)	5.79 (147)
C	0.54 (13.7)	0.71 (18.0)	0.98 (24.9)	1.55 (39.4)
D	1.00 (25.4)	1.30 (33.0)	1.64 (41.7)	1.94 (49.3)
E	0.44 (11.2)	0.44 (11.2)	0.63 (16.0)	0.75 (19.1)
F	0.28 (7.11)	0.32 (8.13)	0.38 (9.65)	0.50 (12.7)
G	0.31 (7.87)	1.69 (42.9)	1.69 (42.9)	2.81 (71.4)
øН	0.37 (9.40)	0.50 (12.7)	0.50 (12.7)	1.00 (25.4)

### Anti-rotation Option GSX50



### **GSX Series Travel Options**

#### PF = Preloaded Follower

This option offers a true zero backlash follower for the GSX Series actuator. The dynamic load rating of zero backlash. preloaded screws is 63% of the dynamic load rating of the standard non-preloaded screws. The calculated travel life of a preloaded screw will be 25% of the calculated travel life of the same size and lead of a non-preloaded screw for the same application. Preloaded follower is not available with absolute internal feedback option.

#### EB = Electric Brake

This option provides an internal holding brake for the GSX20, 30, 40 & 60 actuators. The brake is spring activated and electrically released.

#### **RB** = Rear Electric Brake

This option provides an internal holding brake for the GSX50 actuator. The brake is spring activated and electrically released.

#### ES = Internal End of Travel Switches

This option allows for two internal end of travel switches to be included with the GSX Series actuator. These switches provide end of travel indication to the controller and are not adjustable. See page 31 for details.

#### AR = External Anti-rotate Assembly

This option provides a rod and bushing to restrict the actuator rod from rotating when the load is not held by another method. Shorter actuators have single sided anti-rotation attachments. Longer lengths require attachments on both sides for proper operation.

#### **XT = Special Travel Option Selections**

The XT Option can be used to specify various special travel options on the GSX Series of Linear Actuators. Because this option can be used to specify many things, it is important that an order including the -XT option spell out in detail, the exact options being selected by the including of the -XT in the model number.

It is recommended that prior to ordering an actuator including the -XT specifier that a quote be obtained through Exlar's special products application engineers for the desired options, and that quote be referenced on, or included with any order placed.

Do Pr Be	escriptions: rotective ellows	This option provides an accordion style protective bellows to protect the main actuator rod from damage due to abrasives or other contaminants in the environment in which the actuator must survive. The stan- dard material of this bellows is neoprene coated nylon. This standard bellows is rated for envi- ronmental temperatures of -54 degrees to 121 degrees Celsius. Longer strokes may require the main rod of the actuator to be extended beyond standard length. Consult Exlar appli- cations engineers for details.
Hi Pr Be	igh Temp rotective ellows	This option provides an accordion style protective bellows to protect the main actuator rod from damage due to abrasives or other contaminants in the environ- ment in which the actuator must survive. The high temperature material of this bellows is silicone coated fiberglass. This standard bellows is rated for environmen- tal temperatures of -73 degrees to 288 degrees Celsius. Longer strokes may require the main rod of the actuator to be extended beyond standard length. Consult Exlar applications engineers for details.
St M	olined ain Rod	This option provides a main rod manufactured of ball spline shafting, and the front seal and bushing assembly replaced with a ball spline nut to provide the anti-rotate function with- out using an external mechanism. Rod diameters are the closest metric equivalents to standard Exlar rod sizes. This option is NOT sealed in any way. This option is not suitable for any environment in which contaminants come in contact with the actuator, and may enter the actuator.
M Di Ha	anual rive andwheel	This option provides for a manual drive handwheel on the side of the actuator. The hand- wheel has a engagement/disengagement lever which allows for disengagement lever is not tied to the operation of the motor and requires that the user guaran- tee its disengagement before operating the motor. Not available on GSX20.
L1, L2,	L3 = Adjust	able External Travel Switches
Th ind	is option allo lication to th	by sup to 3 external switches to be included with the GSX Series Actuator. These switches provide travel e controller and are adjustable (must purchase anti-rotate for this option). See page 32 for details.
XL =No	n-Standard	Lubrication
Th	io option pro	widee for indication in the model number that the sustamer has enseified a lubrication other than the stan

This option provides for indication in the model number that the customer has specified a lubrication other than the standard provided by Exlar.

### Motor Speed Designators

All Exlar T-LAM<sup>™</sup> motors and actuators carry a standard motor speed designator as defined below. This is representative of the standard base speed of the motor, for the selected bus voltage.

Designator	Base Speed	Actuator/Motor Series
-50	5000 rpm	GSX20
-30	3000 rpm	GSX30, GSX40
-24	2400 rpm	GSX50, GSX60
01-99	Special S	peed, Consult Exlar

If the model number is created and the location for the motor speed designator is left blank, this is the base speed to which each motor will be manufactured. The model number can also be created including this standard speed designator.

Exlar also provides the flexibility to manufacture all of its T-LAM products with special base speeds to match the customer's exact application requirements. This may be a higher than standard speed motor, or lower base speed than standard which will allow the customer to get the required torque, at a speed optimized to their application, and use the minimum amount of current from their amplifier.

The call out for a special speed is configured in the model number by using a two digit code from 01-99. These numbers represent the number, in hundreds, of RPM that will be the base speed for the particular motor.

For example, an GSX-30-03-01-OSM-AD1-118-30 motor that normally has a 3000 rpm standard winding, can be changed to a 3300 rpm winding by changing the -30, to a -33. It can be changed to a 5000 rpm winding by changing the -30 to a -50.

Changing this speed designator will change the ratings of the motor, and these must be obtained from Exlar applications engineers. Also, it is not possible to produce every possible speed from -01 to -99 for each motor at each voltage so please contact Exlar applications engineers for confirmation of the speed that is desired for the application.

### Absolute Linear Feedback Options

#### LT = LVDT (VRVT) including conditioner

This option provides for an actuator containing an internally mounted LVDT (VRVT) transducer spanning the full stroke of the actuator. Inquire with Exlar engineering for details and conditioner output preference.

# Motor Options

GSX motor options are described with a 3 digit code. The first digit calls out the stack length, the second the rated bus voltage, and the third the number of poles of the motor. Refer to the mechanical/electrical specifications for motor torque and actuator rated force.

**118** = 1 stack, 115 Vrms, 8 Pole, Class 180 H **138** = 1 stack, 230 Vrms, 8 Pole, Class 180 H **158** = 1 stack, 400 Vrms, 8 Pole, Class 180 H **168** = 1 stack, 460 Vrms, 8 Pole, Class 180 H **218** = 2 stack, 115 Vrms, 8 Pole, Class 180 H **238** = 2 stack, 230 Vrms, 8 Pole, Class 180 H **258** = 2 stack, 400 Vrms, 8 Pole, Class 180 H **258** = 2 stack, 460 Vrms, 8 Pole, Class 180 H **318** = 3 stack, 460 Vrms, 8 Pole, Class 180 H **338** = 3 stack, 230 Vrms, 8 Pole, Class 180 H **338** = 3 stack, 230 Vrms, 8 Pole, Class 180 H **358** = 3 stack, 400 Vrms, 8 Pole, Class 180 H **358** = 3 stack, 400 Vrms, 8 Pole, Class 180 H **358** = 3 stack, 400 Vrms, 8 Pole, Class 180 H **368** = 3 stack, 400 Vrms, 8 Pole, Class 180 H

### **Rod End Attachments**

Rear Clevis Pin Spherical Rod Eye Rod Eye Rod Clevis

See drawings on pages 33-36. Attachments ordered separate from actuator.

### **Housing Options**

#### FG = Food Grade Epoxy

This option provides for an actuator coated with FDA approved white epoxy.

#### EN = Electroless Nickel Plating This option provides for an actus

This option provides for an actuator with electroless nickel plating.

#### SS = Stainless Steel Housing

This option provides an actuator with all stainless steel construction. Housing dimensions for this option are not equal to the standard housing. Please inquire with Exlar for dimensions.

#### XH = Special Housing Option

Any housing option that is not designated by the above codes should be listed as XH and described at time of order. All special options must be discussed with Exlar engineering.



**GSX Series** 



Drawings subject to change. Consult Exlar for certified drawings.







Drawings subject to change. Consult Exlar for certified drawings.

Note: The stroke limitation from the limit switch option IS NOT MECHANICAL. It represents the position at which the switches will activate. <u>The stroke limitation for the brake is a mechanical limitation.</u> The brake and limit switch options are mutually exclusive and thus are not available in the same unit. Drawing and specifications subject to change without notice.

### GSX20, GSX30, GSX40 & GSX60 Brake and Internal Limit Switch Extension Options



Actuator	A - Limit Switch Extension Length	Stroke Length Reduction
GSX20	1.784" (45.21 mm)	0.4" (10.1 mm)
GSX30	1.773" (44.96 mm)	0.4" (10.1 mm)
GSX40	No internal limit switch	
GSX60	3.575" (90.81 mm)	0.4" (10.1) mm
Actuator	A - Brake Extension Length	Stroke Length Reduction
GSX20	1.784" (45.21 mm)	NA
GSX30	1.773" (44.96 mm)	NA
GSX40	2.330" (59.18 mm)	NA
GSX60	3.575" (90.81 mm)	NA



The external limit switch option for the GSX Series of linear actuators provides the user with 1, 2 or 3 externally mounted adjustable switches for use as the end of travel limit switches or home position sensors.

The number of switches desired is selected by ordering the L1, L2 or L3 option, in which 1, 2 or 3 switches will be provided, respectively.

The switches are 9-30 VDC powered, PNP output, with either normally open or normally closed logic operation depending on the switch configuration ordered. Below is a diagram which logic operation will be provided for each switch, based on the option ordered.

Option	SW1 SW2		SW3
L1	Not Supplied	Normally Op	en Not Supplied
L2	Normally Closed	Not Supplie	d Normally Closed
L3	Normally Closed	Normally Op	en Normally Closed
Switch Type	Exlar Part Number		Turck Part Number
Normally Closed Switch	24631		BIM-INT-RP6X
Normally Open Switch	22303		BIM-INT-AP6X

EXLAR GSX Series Linear Actuators

### Actuator Rod End Options



Part numbers for rod attachment options indicate the through hole size or pin diameter. Before selecting a spherical rod eye for use with a GSX series actuator, please consult the information on the anti-rotation option for the GSX actuators. Spherical rod eyes will allow the rod to rotate if the load is not held.

Roc	d Clevis Dimens	sions			
	GSX20	GSX30	GSX40	GSX50	GSX60
	RC038	RC050	RC075	RC100	RC138
A	0.787" (20 mm)	0.75" (19.1 mm)	1.125" (28.58 mm)	1.625" (41.2mm)	2.00" (50.8 mm)
В	0.787" (20 mm)	0.75" (19.1 mm)	1.25" (31.75 mm)	1.500" (38.1 mm)	2.125" (53.98 mm)
C	1.574" (40 mm)	1.50" (38.1 mm)	2.375" (60.3 mm)	3.125" (79.4 mm)	4.125" (104.78 mm)
D	.575" (14.6 mm)	0.50" (12.7 mm)	0.625" (15.88 mm)	.750" (19.1 mm)	1.00"(25.4 mm)
E	0.375" (9.5 mm)	0.765" (19.43 mm)	1.265" (32.13 mm)	1.515" (38.5 mm)	2.032" (51.6 mm)
øF	0.375" (9.5 mm)	0.50" (12.7 mm)	0.75" (19.1 mm)	1.000" (25.4 mm)	1.375" (34.93 mm)
øG	0.75" (19.1 mm)	1.00" (25.4 mm)	1.50" (38.1 mm)	2.000" (50.8 mm)	2.75" (69.85 mm)
Н	NA	1.00" (25.4 mm)	1.25" (31.75 mm)	1.500" (38.1 mm)	2.00" (50.8 mm)
øJ	NA	1.00" (25.4 mm)	1.25" (31.75 mm)	1.500" (38.1 mm)	2.00" (50.8 mm)
K	3/8-24	7/16-20	3/4-16	1-14	1-1/4 - 12

# Spherical Rod Eye Dimensions





	GSX20	GSX20 GSX30		GSX50
	SRM038	SRM044	SRM075	SRF100
Α	1.625" (41.3mm)	1.81" (46.0 mm)	2.88" (73.2 mm)	
øB	.375" (9.525mm)	0.438" (11.13 mm)	0.75" (19.1 mm)	
C	.906" (23.0mm)	1.06" (26.9 mm)	1.72" (43.7 mm)	See GSX50
D	1.0" (25.6mm)	1.13" (28.7 mm)	1.75" (44.5 mm)	Sperical Bod Eve
E	12 deg	14 deg	14 deg	drawing balaw
F	.406" (10.3mm)	0.44" (11.1 mm)	0.69" (17.5 mm)	drawing below.
G	.500" (12.7mm)	0.56" (14.2 mm)	0.88" (22.3 mm)	Requires female
Н	.688" (17.7mm)	0.75" (19.1 mm)	1.13" (28.7 mm)	rod end.
J	.562" (14.3mm)	0.63" (16.0 mm)	1.00" (25.4 mm)	
K	3/8-24	7/16-20	3/4-16	





# Rod Eye Dimensions





	GSX30	GSX40	GSX50	GSX60
	RE050	RE075	RE100	RE138
øA	0.50" (12.7 mm)	0.75" (19.1 mm)	1.00" (25.4 mm)	1.375" (34.93 mm)
В	0.75" (19.1 mm)	1.25" (31.8 mm)	1.50" (38.1 mm)	2.0" (50.8 mm)
C	1.50" (38.1 mm)	2.06" (52.3 mm)	2.81" (71.4 mm)	3.44" (87.3 mm)
D	0.75" (19.1 mm)	1.13" (28.7 mm)	1.63" (41.4 mm)	2.0" (50.8 mm)
E	0.63" (15.9 mm)	0.88" (22.3 mm)	1.19" (30.2 mm)	1.837" (46.67 mm)
F	7/16-20	3/4-16	1 - 14	1-1/4 - 12

# **Clevis Pin Dimensions**



	A	В	C	øD	øE
<b>GSX20</b>	2.28"	1.94"	0.17"	0.50"	0.095"
CP050-Rear Clevis	(57.9 mm)	(49.28 mm)	(4.32 mm)	(12.7 mm)	(2.41 mm)
<b>GSX30</b>	2.28"	1.94"	0.17"	0.50"	0.095"
CP050-Rod eye, Rod Clevis	(57.9 mm)	(49.28 mm)	(4.32 mm)	(12.7 mm)	(2.41 mm)
CP075-Rear Clevis	3.09"	2.72"	0.19"	0.75"	0.14"
	(78.5 mm)	(69.1 mm)	(4.82 mm)	(19.1 mm)	(3.56 mm)
GSX40 CP075-Rod eye, Rod Clevis Spherical Eye, Rear Clevis	3.09" (78.5 mm)	2.72" (69.1 mm)	0.19" (4.82 mm)	0.75" (19.1 mm)	0.14" (3.56 mm)
<b>GSX50</b> CP100-Rod eye, Rod Clevis Spherical Eye, Rear Clevis	3.59" (91.2 mm)	3.22" (81.8 mm)	0.19" (4.82 mm)	1.00" (25.4 mm)	0.14" (3.56 mm)
GSX60	4.66"	4.25"	0.20"	1.375"	0.173"
CP138-Rod eye, Rod Clevis	(118.3 mm)	(108 mm)	(5.08 mm)	(34.93 mm)	(4.39 mm)
CP175-Rear Clevis	5.656"	5.25"	0.203"	1.750"	0.173"
	(143.6 mm)	(133.3 mm)	(5.15 mm)	(4.44 mm)	(4.39 mm)

### **GSX** Series Ordering Information

#### AA = GSX Actuator Size

- 20 = 2 inch frame
- 30 = 3 inch frame
- 40 = 4 inch frame
- 50 = 5 inch frame
- 60 = 7 inch frame

#### **BB** = Stroke Length

- 03 = 3 inches (GSX20, GSX30)
- 06 = 5.9 inches (GSX30)
- 6 inches (GSX20, GSX40, GSX50, GSX60)
- 08 = 8 inches (GSX40)
- 10 = 10 inches (all models)
- 12 = 12 inches (GSX20, GSX30,
- GSX40)
- 14 = 14 inches (GSX30, GSX50)
- 18 = 18 inches (GSX30, GSX40)

#### CC = Lead

- 01 = 0.1 inch (GSX20, GSX30, GSX40, GSX50)9
- 02 = 0.2 inch (GSX20, GSX30, GSX40, GSX50)
- 03 = 0.25 inch (GSX60)
- 04 = 0.4 inch (GSX20 only)
- 05 = 0.5 inch (GSX30, GSX40, GSX50, GSX60)
- 08 = 0.75 inch (GSX40)<sup>10</sup>
- 10 = 1.0 inch (GSX50, GSX60)<sup>11</sup>

#### **D** = Connections

- 0 = MS style (anodized)
- E = MS style (electroless nickel)
- M = Manufacturer's Connector<sup>7</sup>
- I = Intercontec style (Exlar standard style connector)
- X = Special (please specify)

#### E = Mounting

- S = Side tapped mounting holes
- D = Double side tapped mounting
- E = Extended tie rods
- F = Front flange
- T = Trunnion
- C = Rear clevis
- X = Special (please specify)

#### F = Rod End

- M = Male, US std. Thread
- A = Male, Metric std. Thread
- F = Female, US std. Thread
- B = Female, Metric Thread
- X =Special (please specify)

- E F GGG HHH II {XX..XX} CC - D GSX AA - BB **GGG** = **Brushless Amplifier** (Please indicate the amplifier to be used to power the actuator) XX1 = Custom Feedback - purchaser must supply drawing of feedback device and desired wiring drawings 001 = Standard Feedback Mount - actuator is supplied ready for size 15 resolver or encoder, includes .375 mm shaft 002 = Same as above with 8mm shaft If the Rockwell Allen-Bradley system that you are using is the Kinetix platform or SERCOS based, additional software and data files are required from Allen-Bradley. Please contact your Rockwell Allen-Bradley representative for support. AB1 = Allen-Bradley Ultra 100/200<sup>4</sup> (std encoder, 2048 line, with commutation, 5 VDC) AB4 = Allen Bradley Ultra 3000 or 5000<sup>4</sup> with single-turn (absolute encoder) AB5 = Allen Bradley Ultra 3000 or 5000<sup>4</sup> with multi-turn (absolute encoder) AB5 = Allen Bradley 1394<sup>8</sup> (resolver, type 2)(replaces AB2) AB7 = Allen Bradley Ultra 3000 or 5000<sup>4</sup> (std encoder, 2048 line, with commutation, 5 VDC) AD1 = Advanced Digital "Simple Servo" (std encoder, 2048 line, with commutation, 5 VDC) AP1 = API resolver based (resolver, type 2) AP2 = API encoder based (std encoder, 2048 line, with commutation, 5 VDC) AM1 = Advanced Motion Controls (std encoder, 2048 line, with commutation, 5 VDC) AM2 = Advanced Motion Controls (std encoder, 1000 line, with commutation, 5 VDC) AM3 = Advanced Motion Controls (resolver, type 1) AM4 = Advanced Motion Controls BX Series default settings (std encoder, 2048 line, with commutation, 5 VDC) BD2 = Baldor Flex Series (resolver, type 1)(replaces BD1) BD3 = Baldor Flex Series (std encoder, 2048 line, with commutation, 5 VDC) BO1 = Bosch (resolver, type 2) CC1 = Cleveland Machine Controls (resolver, type 1) CM1 = Comau (resolver, type 1) CO1 = Copley Controls (std encoder, 2048 line, with commutation, 5 VDC) CS1 = Parker (Custom Servo Motors) MPA, MPSL (resolver, type 1) CS2 = Parker (Custom Servo Motors) Servo Flex (std encoder, 2048 line, with commutation. 5 VDC) EL1 = Elmo Motion Control (resolver, type 1) EL2 = Elmo CLA, SBA, FLU Series, (std encoder, 2048 line, with commutation, 5 VDC) EM2 = Emerson En, Epsilon, MDS Series and Uni-Drive<sup>4</sup> (std encoder, 2048 line, with commutation, 5 VDC) EM3 = Emerson MX Series (resolver, type 2) EM4 = Emerson UniDrive SP (resolver, type 1) EU1 = Elau (absolute encoder, multi-turn, type 2) EX4 = Exlar SV Series (resolver, type 1) (replaces EX3) GL1 = Sheffield Automation (G&L) Smart Drive (standard encoder, 2048 line, with commutation, 5 VDC) If selecting the "M" connector option with GL1, the motor power and encoder connector configuration will be equivalent to that used on the Sheffield Automation HSM Series motors. GL2 = Sheffield Automation (G&L) Smart Drive (standard encoder, 2048 line, with commutation, 5 VDC) If selecting the "M" connector option with GL2, the motor power and encoder connector configuration will be equivalent to that used on the Sheffield Automation LSM/MSM Series motors. IN1 = Bosch-Rexroth (Indramat) ECO Drive (absolute, multi-turn Heidenhain encoder, type 2) IN2 = Bosch-Rexroth (Indramat) ECO Drive (absolute, single-turn Heidenhain encoder) IN4 = Bosch-Rexroth (Indramat) ECO Drive, Standard resolver (resolver, type 1)(replaces IN3)

  - KM1 = Kollmorgen ServoStar Series<sup>4</sup> (Absolute encoder, single turn, type 1) KM3 = Kollmorgen ServoStar600 Series<sup>4</sup> (Absolute encoder, single turn, type 1) KM4 = Kollmorgen ServoStar600 Series<sup>4</sup> (Absolute encoder, multi-turn, type 2)
  - KM4 = Kollmorgen ServoStar600 Series<sup>4</sup> (Absolute encoder, findit-turn, type 2) KM5 = Kollmorgen ServoStar600 Series<sup>4</sup> and ServoStar CD (resolver, type 2)(replaces KM2) KM6 = Kollmorgen ServoStar300 Series<sup>4</sup> (std encoder, 2048 line, with commutation, 5 VDC) LZ1 = Lenze 9300 Series (Multi-turn Absolute Encoder, type 2)

  - LZ2 = Lenze 9300 Series (resolver, type 2)
  - MD1 = Modicon (resolver, type 1)
  - MX1 = Metronix ARS Series, Resolver type 1
  - OR1 = Ormec (resolver, type 2)

  - PC1 = Parker Compumotor Apex & Z Series (resolver, type 1) PC2 = Parker Compumotor TQ Series (std encoder, 2048 line, with commutation, 5 VDC)
  - PC3 = Parker Compumotor Gemini Series (std encoder, 2048 line, with commutation, 5 VDC)
  - PS2 = Pacific Scientific (std encoder, 2048 line, with commutation, 5 VDC)
  - PS3 = Pacific Scientific SC900, 700 Series (resolver, type 1)(replaces PS1)
  - SM2 = Siemens (resolver, type 1)
  - SP2 = In Motion, PAM Series (resolver, type 1)
  - WD1 = Whedco (GE-Fanuc)(resolver, type 1)
  - YS2 = Yaskawa Sigma II Series for 4 inch and larger Exlar motors (multi-turn absolute encoder, type 1)
  - YS3 = Yaskawa Sigma II Series for 3 inch and smaller Exlar actuators (multi-turn absolute encoder, type 1)

GSX Series Ordering Information
HHH = Motor Stator <sup>2</sup> - All 8 Pole 118 = 1 stack, 115 Vrms 218 = 2 stack, 115 Vrms 318 = 3 stack, 115 Vrms 138 = 1 stack, 230 Vrms 238 = 2 stack, 230 Vrms 338 = 3 stack, 230 Vrms 158 = 1 stack, 400 Vrms 258 = 2 stack, 400 Vrms 358 = 3 stack, 400 Vrms 168 = 1 stack, 460 Vrms 268 = 2 stack, 460 Vrms 368 = 3 stack, 460 Vrms
II = Motor Speed         24 = 2400 rpm, GSX50, GSX60         30 = 3000 rpm, GSX30, GSX40         50 = 5000 rpm, GSX20         01-99 = Customer specified base speed
XX XX = Options Travel Options PF = Preloaded follower <sup>1</sup> ES = Internal end of travel switches <sup>5</sup> AR = External Anti-rotate assembly EB = Electric Brake <sup>5</sup> RB = Rear Electric Brake <sup>5</sup> (GSX50) XT = Special Travel Option (see pg. 24) L1/L2/L3 = External Limit Switches
Motor Options XM = Special motor option XL = Special lubrication
Housing Options FG = Food grade paint <sup>6</sup> EN = Electroless nickel plating <sup>6</sup> SS = Stainless steel housing <sup>6</sup> XH = Special housing option
Absolute Linear Feedback LT = VRVT, including signal conditioner <sup>3</sup>
<ol> <li>The dynamic load rating of zero backlash, preloaded screws is 63% of the dynamic load rating of the standard non-preloaded screws. The calculated travel life of a preloaded screw will be 25% of the calculated travel life of the same size and lead of a non-preloaded screw. Preloaded follower is not available with absolute internal feedback option.</li> <li>Stator voltage and pole options allow for catalog rated performance at varying amplifier bus voltages and pole configuration requirements.</li> <li>Linear feedback is not available in the GSX20.</li> <li>Emerson EN and Epsilon Series, AB Ultra Series, Kollmorgen ServoStar and other amps require motor data files for operation with GSX Series actuators. These files can be downloaded from our website at www.exlar.com. Contact Exlar for details.</li> <li>The internal limit switch or brake options require a third cable. Internal limit switches and brake together are not available.</li> <li>These housing options would typically be accompanied by the choice of the electroless nickel connectors if a connectorized unit were selected. This choice may also indicate the need for special material main rods or flanges.</li> <li>Available with AB1, AB4/5, AB7, EM2, KM1, KM3, KM4, KM5, KM6, IN1, IN2, IN4, LZ1, LZ2, PC3, PS3, YS2 and YS3 feedback. This option allows the customer to use the standard cables supplied by their amplifier manufacturers.</li> <li>Use of the A-B 1394 requires assistance from Allen-Bradley to configure the axis for a custom motor.</li> <li>A lead not available above 12" stroke in GSX40.</li> </ol>