## INSTRUCTIONS

## Switchgear

## AIR CIRCUIT BREAKERS

Type AK-1-50
Electrically Operated


LOW VOLTAGE SWITCHGEAR DEPARTMENT GENERAL (8) ELECTRIC Philadelphia, pa.

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# AIR CIRCUIT BREAKERS TYPE AK-1-50-1, AND AK-1-50-2 ELECTRICALLY OPERATED 

## INTRODUCTION


#### Abstract

Before unpacking, installing, or attempting to operate the Type AK-1-50 Ar Circult Breaiker described hereln, these instructions should be thoroughly and carefully read.


The ratings for the AK-1-50 is as follows:

| Continuous Current Rating | Interrupting Rating | $\begin{aligned} & \text { Voltage } \\ & \text { A.C. }{ }^{\text {D.C. }} \end{aligned}$ |  |
| :---: | :---: | :---: | :---: |
| RMS Amperes | RuS Amperes |  |  |
| 15*10 1600 | 50,000 | 600 | 250 |

- The interrupting ralling is Inilfed on the lower rated colls.


## RECEIVING, HANDLING AND STORAGE

Immediat ely upon recelpl of the circult breaker, an examination 8 hould be made for any damage or loss bustained in transit. If injury or rough handilng is evident, a damage clalm should be Illed at once with the transportation company and the nearest General Electric Sales Office should be promptIs notifled.

The circult breaker should be umpacked as soon as possible after being recelved as difficulty may be experlenced in making claim for damage, not evident upon recelpt. Care should be used in unpacking to avold damaging any of the breaker parts. Be sure that no loose parts are

These circult breakers are generally used for protection and control of feeder and branch circults, inciuding equipment in buildings ino dustries, power stations and for marlae applicatlons withln the ratings designated.

The AK-1-50 breaker for D.C. application dilfers irom the breaker used for A. C. applicar tlons. The difference in the D.C. Breaker is in extra arcing contact per pole with corresponding difference tin the upper atud and interrupter.

These instructions apply to breakers used for both D.C. and A.C. applications.

## INSTALLATION

## LOCATION

The Atr Circult Breaker should be installed In a clean dry place where it is readily accessible for operation, inspection and proper maintenance. Spectal enclosures are avallable for the installation of circult breakers which may be subjected to dust and molsture or dher unfavorable locations.

## MOUNTINE

Dead front elrcult breakers are designed for mounting in a switchboard or an enclosing case. The mounting of dead Iront breakers consists of placing the breakers within the enclosed structure and connecting the power buses or cables and making the necessary control connections. The standard mounting depth from the back suriace of the breaker base to the back slde of the front panel is $16^{\prime \prime}$. The front cover of dead front breakers consists elther of a hinged door whit cut-out or
missing or left in the packing material. Blow orit any dirt or particles of packing material that may have accumulated on the breaker parts.

If the circuit breaker is not installed at nence, It should be stored in a clean dry place and prefer ably placed in a vertical position. It should be supported to prevent bending of studs or damage to the breaker parts. It is advisable not to cover the breaker with any packing or other material that absorbs molsture which may cause corrosion of breaker parts. A covering of paper will prevent dust irom setting on the breaker parts.

[^0]

CUSTOMER WIRING ------------.

FACTORY WIRING


LIST OF AgBREVIATIONS
A-TERMMAL BOARD LOCATED LEFT SIDE terminal board located left side FRONT VIEW
Fat OFF switehes
K-CLOSHE RELE TYPE MBA.(X)
L- angllary sw di abo contacts

- TPPE SE-12 (Mussw)

M-SMNT TRIP (TCA
P-PUSM BUTTON CLOSING SW OH ERKR.(PEJ
R-CLOSING SPRLNE CHARGINE MOTOR (M) T-auxillagy power transformer ftrans)

Fig. I Coanectica Olagre
exceeding the specilted temperature rise. Connecting cables or bus bars should be supported 80 that the breaker studs Will not bo subjected to unnecessary strains.

## WIRING DIAGRAM

Fig. 1 shows the typlcal elementary and connection diagrams for the control system of electrically operated breakers. If shows the control circult when the closing springs are discharged and the breaker is open. When rated voltage is applled to the control circult, the motor will be energized through contacts $\mathrm{I}(8-4)$, $G(1-2)$, $G(3-4), K(3-7)$ to motor $\frac{52}{\mathrm{M}}$. The motor $\mathrm{m}_{1}$ ill charge the closing oprings uniti the motor circuit is opened by cut-ofi switch contacts $G(1-2)$ and $G$ (3-4). When the $G$ cut-off switches open the $F$ cut-off switches close. Operation of the breaker
closing switch $W 111$ energize the relay coll $\frac{52}{\mathrm{x}}$ which in turn opens contacts $K(8-1)$ and $\mathrm{K}(3-7)$ and closes contacts $\mathrm{K}(8-2)$ and $\mathrm{X}(1-7)$. The circutt thru contacts $K(B-2)$ and $F(A-3)$ seals in the coll 52 . The motor circuit is now energised through contacts $K(8-2), F(1-2)$, and $K(1-7)$. The motor will then cause the charging crank (10) Fig. 7 to travel beyond the position of right angles to the paddle (1i) Fig. 7. Beyond this position the springs will discharge independently of the charging motor and the breaker will close. When the breaker cioses the control clrcult reverts to its original position and the above eycie can be repeated.

Operating the breaker control switch to the Irip position will cause the shant tripping device toopen the breaker. An auriliary swilch "hir coutact will interrupt the fiow of current through the ahunt trip coll.

## OPERATION

## manual maintenance CLOSING

To observe the operation of the breaker without power, with breaker open and apriogs discharged proceed as follows:

1. Charge the closing spring with the maintenance handle (1), Fig. 8, witil the indicator reads "charged'.
2. Continue tooperate the malntenance handle unitl the brepiker closes.
3. Open the breaker by pushing the trip button (5), Fig. 2.

## ELECTRICAL

With the breaker in the open position and the closing springs discharged, as shown by thelr respective indicators, (3) and (8) Fig. 2, the cycle of operation ts as follows:

1. The motor mechanism charges the closing
springs, In the front frame, through a linkage. This pre-charging operatlon occurs gutomatically If the control circult ts energized.
2. When the closing circuit is energized, either thru a closing switch on the breaker or a remote gwitch, the motor mechanism drives the apring charging lever over center. This discharges the closing aprings and closes the breaker. After the breaker closes, the springs will automatically be pre-charged provided the contral clrcuit has not been opened.

NOTE: The operating mechanism may reset when the closing bprings are in the pre-charged position or during the over-rmaing section of the closing operation.
3. After the breaker is tripped, the above cycle can be repeated.

## maintenance

BEFORE INSPECTION OR ANY MADNENANCE WORE IS DONE BE BURE THAT THE BREAKER IS IN THE OPEN POSITION. ALL ELECTRICAL POWER, BOTH PRIMARY AND CONTROL SOURCES, 8HOULD ALSO BE DSCONNECTED.

CAUTION: Care must be taken when the circult breaker is being installed and when any inspection or maintenance work is being done so that the breaker is in the open position and the closing aprings are belng restralned by the saiety pin. The procedure for insertling the safety pin is given below.

The elosing spring should be charged with the
maintenance handle (1), so that the salety pin (3) can be placed in the lower hold of the push rod ( 2 ), refer to Fig. 3. (The upper hole is used th the initial assembly of the springs). Continue to operate the maintenance handle, ciosing the breaker. This Is done so that the safety pin takes the spring force.

Following the inspection period, the closing aprings must be recharged, the safety pin removed from the push rod and the pin placed in the retaining spring ollp adjacent to the push rod. $\therefore$

## INEPECTION

Periodic inspection of the circult breaker

Air Circuit Breaker Type AK-1-50



Fig. 2 Front View Of Breaker
is recommended at least once a year. More irequent inspections are recommended, if severe load conditions, dust, moisture or other unfavorable conditions exist. A complete inspection of the breaker including contacts and arc quenchers, should always be made after the breaker has interrupted a short circuit current.

After the breaker has been installed, as well as at the regular inspection periods, slowly operate it manually several times as described above and observe whether the contacts line up properly and make sure that all parts move freely without binding or excessive friction.

If the breaker remains open or closed for a period of six months or more it is recommended that arrangements be made to open and close it several times in succession, preferably under load.

If overheating, not caused by overcurrent, is observed, a complete inspection of the breaker should be made including connections, contacts and flexible connectors.

At all times it is important not to permit pencll lines, paint, oil or other foreign materials to remain on the insulating surfaces of the breaker as they may cause low resistance between points of different potential and result in eventual electrical breakdown.

The breaker should be operated several times
at rated voltage to ascertain whether the control circuits are properly connected and that all electrical attachments are functioning properly.

The contacts should be inspected at the regtlar inspection perlods and always after a knowa short circult current has been interrupted, to ascertain whether the contacts are worn or pitted, In which case they should be dressed or replaced. Fis necessary to remove the arc quenchers in order to properiy inspect the contacts.

## LUBRICATION

In general, the circuit breaker requires moderate lubrication. Bearing points and sliding surfaces should be lubricated at the regularinspection periods with a thin film of G.E. Lubricant D50H15. Hardened grease and dirt should be removed from latch and bearing surfaces by using kerosene. ALL EXCESS LUBRICANT SHOULD BEREMOVED WITHA CLEAN CLOTH IN ORDER TO AVOIDANY ACCUMULATION OF DIRT OR DUST.

The use of cotion waste to wipe bearing sur faces should be avoided, as the cotton ravelings might become entangled under the bearing surfaces and destroy the surface of the bearing.

## REPAIR AND REPLACEMENT

In order to repair or replace contacts, oper ating mechanism or the overcurrent devices, the


Fig. 3 View Showing Operation of Breaker with Manual Maintenance Kandle And Installation of Safety Pin

Iront frame must be separated from the back Irame. To separate the two Irames proceed as follows:

1. The breaker contacts must be open with the afetypla in place. (See "Matntenance'".
2. Remove the two opening springs (on lower part of breaker) from the out-alde pole units.
3. Remove the clevis pin (14) Fig. 5 from the center pole unit.
4. Remove the six nuts trom the back trame using a socket wrench with on extension. These include the two nuts at the top of the - frame.
5. Remove the operating rod (5) Fig, 10. The two frames can now be separated. - :
NOTE: It is recommended that the breaker be fastened to a sultable mounting base and a sling or hook hold the front frame as the bolts are being removed.

TROUBLE 8HOOTING

| TROUBLE | Cause | REMEDY |
| :---: | :---: | :---: |
| Overheating | Contacts not aligned. <br> Contacts dirty, greasy or coated with dark illm. <br> Contacts badiy busned or pltted. <br> Current carrying ourfaces dirty. <br> Bolts and nuts at terminal connectlons not tight. <br> Current in excess of breaker rating. <br> Excessive amblent temperature. | Adjust contacts. <br> Clean contacts. <br> Replace contacts. <br> Clean surfaces of current carryling parts. <br> Tighten, but do not exceed elastic limit of bolts or fittings. <br> Decrease load, rearrange clrcult or Install larger breaker. <br> Provide adequate ventilation. |
| Fallure to Trip | Travel of tripplng device does not provide positive release of tripping latch. <br> Worn or damaged trip unit parts. | Re-adjust or replace trlpping device. <br> Replace trip unit. |
| False Tripping | Binds in overload device. | Replace overload device. |
| Fallure to Close and Latch | Binding in attachments preventing reselting of latch. <br> Chipped or worn latch. <br> Latch out af adjustment. <br> Latch return apring too weak or braken. <br> Hardened or gummy Iubricant. <br> Safety plo left in push rod. <br> Motor burned out. <br> Control devices burned out. | Re-allgn and adjust attachments. <br> Replace latch. <br> Adust latch. <br> Replace spring. <br> Clean bearing and latch suriaces. <br> Remove asfety pin. <br> Replace motor. <br> Replace device. |

## BASIC BREAKER COMPONENTS ..... . .

## ARC QUENCHER

The arc quenchers should be inspected at the regular inspection period and if the barriers are cracked or eroded, they should be replaced.

## REPLACEMENT

1. Remove the channel shaped retaining bar by removing two screws
2. Lift the quencher clear of the movable arcing contacts.
3. During replacement be careful not to overtighten the screws which secure the channel shaped retaining bar. Overtightening the screws will bow the bar and leave the center arc quencher loose.


## INSPECTING INNER, SLIDE, AND POCKET BARRIERS, FIG. 4

1. Remove arc quenchers (see above).
2. Remove screws holding spacer block (9)
3. Remove spacer block, steel backplate (8) and compound support (7).
4. Slide muffler (6) from slot and remove. The inner barrlers (5) can now be removed for inspection.
5. Remove nut and withdraw stud (1) from cap (2).
Remove cap (2). The side (3) and pocket
6. Remove cap (4) barrlers can now be removed.
7. Re-assemble and replace the arc quenchers in the reverse order. Tighten all fastenings after replacement.

8. Stud
9. Pocket Barrier
10. Compound Support
11. Cep
12. Inner Barrier
13. Steel Back Plate
14. Side Barrier
15. Muffler
16. Spacer Block

Fig. 4 Dis-Assenbly of Arc Quenchers To Inspect Imer, Side, And Pocket Barriers

## POLE UNIT ASSEMBLY

Each pole unit assembly consists of a set of arcing contacts, 2 set of main contacts, the operating linkage and the mounting base. See Fig. 5.

The stationary arcing contact consists of a set of parallel contact fingers (2), pin (3), and compression springs (22) which provide continionus contact pressure for the full travel of the conta 8.

Flexible brald leads shunt the pivot pin to prevent possible pitting at the pivot point when interrupting high cursents.

The movable arcing contact assembly consists of parallel contact arms (4) carried on two movable pivot pins (8) and (19). The arcing contacts interleaf the main contacts and plvot with them about pin (19). This relative motion is obtained by linkages from the upper pin (7) to the breaker mechanlsm.


1. Scree
2. Sta. Arcine Oontact
3. Pin (Sta. Areine Oent.)
4. Movable Areing Cooteet
5. Braid
6. Worable Eain Cont.
7. Shouldered Pin
8. Pin (Arcios Cont. Lint)
9. Iancleting Lins
10. Pin (Insul oting Link)
11. Pin (Eide Lint)
12. Lint

- 

13. Clevie
14. Clevie Pin
15. Lover Stud
16. Pole Dait Base
17. Epring (Main Yovible Cont.)
18. Pis (Hovble Matn Opat.)

- 19. Pin (Yovible Arcing Cont.) ,

20. Slde Lints
21. Epring (Ste. Main Cont:)
22. Spring (Sta. Arcine Coat.)
23. Upper Stud
24. Pin (Ste. Maln Oont.)
25. Statiouary Maia Obntmet
26. Serev
27. Serov

Fig. 5 Pole Enit lasmaty



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Movable Intermediate Contacts (8), Fig. 6

1. Remove the movable arcing contacts as described above.
2. Loosen spring (i7). See Fig. 5.
3. Slide link (12) to the side and off of pin (7).
4. Slidepins (18) and (7) far enough to the side to allow the movable intermediate contact to be replaced.
5. Re-assemble parts in reverse order.

Always check the contact wipe and pressure following contact replacement.

## OPERATING MECHANISM

The electrically operated mechanism Includes a motor and a gear reduction unit, which charges the closing springs (16) Fig. 7, through a crank shaft (14) Fig. 7. The crank shaft has an arm with a roller (12) Fig. 7, which rides on the closing cam (2) Fig. 8. The position of this closing cam roller is shown in Figs. 8A, 8B, and 8C. The closing cam is connected to the center pole unit thru a clevis, and through a cross bar controls the opening and closing of the contacts on all pole units.

With the breaker open and the closing springs discharged, the sequence of operation is as follows:

## CHARGING THE CLOSING SPRINGS, FIG. 7

1. The mechanism in position shown in Fig. 8A.
2. The motor turns the crank (10) Fig. 7, which is mounted on the output shaft of the gear reduction unlt. The charging roller, which is on the face of the crank, has paddle arm (11) bearing on it.
3. As the crank turns, the roller pushes the paddle arm upward, thereby charging the closing springs through the spring charging arm (15) of the crank shaft.
4. As the charging roller approaches dead center a cut-olf switch opens, de-energlzing the motor circult.
5. The breaker is now ready to close.

## CLOSING THE BREAKER

1. Mechanismin reset position, closing springs charged.
2. When the closing circuit is energized, the motor rotates causing crank (10) and roller (7) to move past dead center.
3. The crank (10) is free to rotate counterclockwise. This permits release of the
charging springs, rotating the crank shaft (14).
4. Referring to Fig. 8B and Fig. 8C, rotation of the crank shaft causes the closing roller (15) to push the closing cam (2) into the position shown in Fig. 8C.
5. With the closing cam in this position, the breakercontacts are closed through a clevis and linkage.

6. Stationary Arcing Contact
7. Movable Main Contact
. Movable Arcing Contact
8. Stationary Main Cont act
9. $\mathrm{Cl} \operatorname{mop}$
10. Crose Bar
11. Seriea Overcurrent Dealce
12. Movable Interaediate Contact
13. Stationary Intermediste Oontect

Fig. 6 Front View of Back Frane Assembly
6. The prop (16) engages the closing cam ( ) , locking it in this position until the breatier is opened.
7. The motor will continue to operate untll it has recharged the closing springs (16) Fig. 7, in preparation for the next opening and closing operation.

## OPENING THE BREAKER, FIG. 8

1. The rotation of the trip shaft (11) by any of the trip devices allows trip latch (10) 20 release the prop (5) and the forces from the contact and opening springs reposition the linkage of the operating mechanism finto position shown in Fig. 8A.
2. The operating cycle can now be repeated.

## ADJUSTMENTS

All adjustments should be made with the operating mechanism in the reset position as shown in Fig. 8B. (The mechanism should be resed by manual operation).

1. The gap between the trip latch (10) and the roller of the reset latch (9) should be between $1 / 64$ to $1 / 32$ inches. This adjustmeat can be obtalned by turning screw (6).
2. The center line of the trip latch (10) shoudd pass through the center of the roller ( E$)$. Form the stop (14) to m:'re this adjustment.

3. Pin
4. Crerk
5. Aushing
6. Paddle
7. Bracket
8. Closing Cat Roller
-4. Indicator
9. Closing Cen Are
S. Bracket
10. Crank Sinft
11. Frume
12. Spring Cherping Are
13. Crank Roller
14. Cear Reduction Unit
15. Motor
16. Closlne Epring
17. Puah pod
18. Clip

Fig. 7 Closing Spring And Cherging Mechonim
3. The distance between the roller on link (3) and prop (5) should be 1/B4 to $1 / 32$ of an inch. To obtain this gap advance or retard the nuts on the bottom of the rod thru resct spring (1).

## REPLACEMENT

1. Remove the front frame (see "Repair and Replacement ${ }^{\prime \prime}$ under "Maintenance').
2. Remove pins holding spring charging arms (15) Fig. 7 to closing springs.
3. Remove two bolts underneaih frame and two bolts from the front of the frame.
4. Remove any wiring-Which is atlached to the mechanism frame.
5. Note the position of the trip paddies on the irip shaft. Remove the two cotter pins which hold the sections of the trip slaft together. The mechanlsm is mow iree to be removed.
6. Re-assemble parts in reverse order. Be sure to replace the trip shaft with the trip paddies in the right position.

## MOTOR AND GEAR REDUCTION UNIT

The motor is mounted on the side of the gear reduction unit and througha worm gear and a planetary gear train drives the crank (10) Fig. 7 with a reducilon of 1000:1.

## REPLACEMENT, FIG. 7

1. Remove front frame (see "Repalr and Re" placement" under "Malntenance").
2. Remove pins from closing spring charging $\operatorname{arm}$ (15).
3. Remove the plate from right end of crank ghaft (14).
4. Slide crank shaft to right untill left ead of shaft clears gear unit housing.
5. Remove the buffer stop which is mounted to the gide of the frame and directly over the motor.
6. Open wire connections on motor and remove wires attached to gear unit housing.
7. Remove four bolts on boltom of front irame and the bolt at the top of the gear reduction unit. The motor and gear reduction anit can now be removed.

The gear reduction unlt contains 4 to 6 ounces of oll similar to Atlantic Refining Company's Grade HFSI3. It should not be necessary to add or change oll except when the gear reduction milt and motor are dis-assembled.

## - AUXILIARY SWITCH

The auxiliary switch is used to make and break various control circuits as the circult breaker is opened and closed.

The auxlliaryswitch refer to Fig. 10 is mounted on the left side of the front irame. As the mounted on the leves, with the contacts, to the opera.


FIG-8A
MECHANISM N MOTION BEFORE RESETTING AS SHOWN IN FIG.-BB


FIG.-8B
MECHANSM N RESET POSTICN
(CLOSING SPRING CHARGED)


1. Spring
2. Com
3. Elink
4. Reset Eprins
5. Prop
6. Adj. Seree
7. Adj. Serev Stop Pin
8. Prop Retura Eprime
9. Doller
10. Letch
11. Trip Shaft
12. Clevie Pin
13. Clevis
14. Latch Etop
15. Roller
16. Prop

Fis. operating Mechmin


Fig. 8 Back View of front frase Assembly


1. Mounting Bolt
2. Tie Bolt
3. Suit
4. Serew
5. Botton Cover
6. End Plate
7. Top Cover
8. 'n' Ontects

9. Frame
10. Open at Closed Indicator
11. Front Escutcheon
12. Croes Ber
13. Operating Pod
14. Trimarular Lirts
15. Link
16. Dperating Shaft
17. Ariliary Shaft.

Fig. 10 Open And Closed Indicator Liakage


Fig. Il motery Ampillary Sultch
9. Ontact Epring
10. Bocker Arm
11. Pln
12. $\mathrm{C}=$
13. 'b' Onntacte
14. "b" Terninal.
15. "a' Terninals
16. Berriter
or closed position it operates a triangular link (6) through an operating rod (5). The triangular link rotates the operating shaft (8) of the auxiliary switch, which through cams located on this shatt opens and closes the auxiliary switch contacts. The top terminals of the switch are " 2 " contacts (open when the breaker is open) and the bottom terminals are " $\psi$ ' contacts (closed when the breaker is open).

## REPLACEMENT, FIG. 10

1. Disconnect all leads to auxillary awitch.
2. Remove two mounting bolts.
3. Disengage auxillary switch shaft (B) from the trlangular link (6).
4. Set arrow on new auxiliary ewitch shaft as shown in Fig. 10.
5. Push auxillary switch shati (8) into Bquare hole in link (breaker open).
6. Replace mounting hardware and wiring.

## ELECTRICAL CLOSING DEVICES AND CONTROLS

A closing switch and motor mechanism are provided for closing the breaker electrically.

## CLOSING SWITCH

The closing button is mounted on the right side of the front escuicheon. When the closing button is pressed inward it engages a rod which in turn operates a switch, which is mounted on the front frame to the right of the operating mechanism.

To replace the closing switch, disconnect the wiring and remove the nuts which hold the switch to its mounting bracket.

## CUT-OFFSWITCHES

The motor cut-off switches are mounted on the side of the front frame as shown in FIg. 12. At the end of the charging stroke, the cut-oif switch (1) opens de-energizing the motor circuil. The cutoff 5 witch (3) closes. When the closing control circuit is energized, the motor operates to discharge the closing springs and close the breaker. After this is completed, the cut-off switch (3) opens, de-energizing the motor circult. The cut off Ewitch (1) closes, and the above cycle can be repeated.

## REPLACEMENT

If the switches do not function properly, they


| 1. g" switch | 5. Rotainlag Ring |
| :--- | :--- |
| 2. Insulation | 6. Lever Bracket |
| 3. F" Suitch | 7. Wtg Brackot |
| 4. Rod | 8. Cover |

Fig. 12 Notor Cut-0ff switch
should be replaced by disconnecting the wiring and removing them from their mounting bracket.

## CONTROL RELAY

The control relay is mounted on the left side of the front frame. It is used to open and close tive motor circuit. To replace remove wiring and holding serews.

## PROTECTIVE• DEVICES

## TIME DELAY UNDERVOLTAGE TRIPPING DEVICE

This device is mounted to a bracket on the left side of the operating mechanism (looking from the front). The purpose of this device is to trip the breaker for undervolt'ge. For rated voltage,
the armature (3) is attracted by the magnet (14). If the voltage falls below the predetermined vate the magnet (14) releases the armature (3). Sprat (4) then pulls armature (3) upward agalnst the $5^{\circ}$ straining force of the oll in cylinder (10); tis action caused a time delay. When the spring over comes the restraining force of the oll, the arme
ture engages screw (20) thus rotating the trip shaft and opening the breaker. (For parts reference refer to Fig. 13).

## ADJUSTMENTS, FIG. 13

An adjusting screw (20) in the trip lever is used to allow from $1 / 32$ to $1 / 16$ inch overtravel after tripping the breaker.

Adjusting screw (2) is used to adjust the armature sothat it will pick up at $80 \%$ of normal voltage and drop out between $30 \%$ and $60 \%$ of normal voltage.

Adjusting nut (8) on connecting rod (i1) is in ${ }^{-}$ tended for a minimum amount of adjustment of the time delay setting.

From $1 / 4$ to $3 / 8$ inch of oll should be maintained in the cyllnder at all limes. In order to make an inspection of the oll, the cylinder may be unscrewed irom the cap. G. E. gilicone on 9981LT4ONV or similar grade should be used in the cylinder.

## REPLACEMENTS

Time Deiay Undervoltage Device, Fig. 13

1. Disconnect coll leads.
2. Remove two screws from bracket (1). (Bracket Is omitted when instantaneous undervoltage device is used). (21) and re-
3. Remove four mounting scre move device. in in reverse order.
4. Install new device in reverse order.

## Coll 15

1. Disconnect leads to coll.
2. Remove two screvs (16).
3. Remove magnet and coll assembly.
4. Straighten Iamingtions around shading
ring (5).
Remove shading ring and striighten lower
5. Remove shading ring end of coll clamp (13).
6. Remove coll. Install new coll in reverse

## order.

## INSTANTANEOUS NNDERyOLTAGE TRIPPING DEVICE <br> The undervoltage tripping device is construct-

 edsimilarly to the time delay undervoltage fripping device with the exception that the cylinder (10), plunger (12), connecting rod (11), cievis (7), brack are omitted.The adjustments and replacements for this device are also the same as those for the time delay undervoltage tripping device.


negit vite gunam montius manist

1. Series Coll
2. Megnet
3. Pallet
4. Pinion
5. Eocape theel
6. Driving Seppent
7. S.T.D. Acmature
8. S.T.D. Callbrafion Eprime
9. Trip Are
10. L. T.D. Areature
11. L.T.D. Calibration Spring
12. Instent meous Trip Epriay
13. Sprint Holder
14. Callbration Clap Iut
15. Plunger
16. Cylinder
17. Calibration Plete
18. Trip Padile
19. Trip Padile Mdjuntine Eere
20. Cluplore Bracket

Fig. If Seriat overearrent Trlopiag Burice

## SERIES OVERCURRENT TRIPPING DEVICE

Each series overcurrent tripping device is enclosed in a molded case and mounted by three screws and a bracket to the lower part of the pole unit base.

The device can be provided with the following tripping combinations:

1. Long time delay, short time delay and instantaneous tripping.
2. Long time and short time delay tripping only.
3. Long time delay and instantaneous tripping.
4. Short time delay and instantaneous tripping.
5. Short time delay tripping only.
6. Instantaneous tripping.
(a) Adjustable
(b) Non-adjustable

8HORT TIME DELAY TRIPPING, FIG. 14
The armature (7) is retained by callbrating spring (8). After the magnetic force, produced by - an overcurrent condition, overcomes this re-- straining force, the armature movement is further retarded by an escapement mechanism which produces an inverse time delay characteristic. The mechanism is shown on Fig. 14a.

## LONG TIME DELAY TRIPPING, FIG. 14

The armature (10) is retained by the callbration spring (11). After the magnetic force, produced by an overcurrent condition, overcomes this restraining force, the armature movement is further retarded by the flow of sllicone oll in a dashpot, which produces an inverse time delay characteristic. The mechanism is shown on Fig. 14b.

## INSTANTANEOUS TRIPPING, FIG. 14

(a) Adjustable instantaneous tripping takes place after the magnetic force produced by an overcurrent condition, overcomes the restraining force of the callbration spring which can be adjusted by the calibration clamp nut (14).
(b) Non-adjustable instant aneous tripping takes place after the magnetic force produced by an overcurrent condition overcomes the restraining force of a nonadjustable spring.
Selectivetripping is oblained when the breakers in the electrical distribution system are arranged on the basis of a progressive series of time and current pickup. This will allow the breaker having the shorter time setting and the lower pickup to trip before the breaker having the longer time setting and the higher current pickup, provided the fault is on the part of the line protected by the breaker having the lower setting. Hence, if a fault occurs in any part of the electrical system, only the breaker nearest the fault will trip.

In order to reduce the possibility of damaging the equipment and to provide maximum safety to the operator, the overload caused by a fault is removed in a minimum amount of time by selective tripping. Overioads producing current up to 5 or 10 times the breaker rating are removedina matter of a few seconds while currents in excess of this value are removed in a fraction of a second.

For the exact characteristics and setting of each breaker in a selective system, reference should be made to the coordination chart furnished for the particular system.

## ADJUSTMENTS, FIG. 14

Callbration clamping nuts (14) are used to ad the desired plckup for the adjustable elements.

To adjust for approximately 1/3\%' overtravel of trip arm (9) after tripping:

1. Check trip latch engagement. 8ee "Adjustments - Operating Mechanism".
2. Loosen the locknut and turn the adjusting screw (19) on the trip arm (9). The screw should not touch the trip paddle when the breaker is "open" and the latch is resef, but should have a clearance not exceeding 1/32'.
3. Tighten the adjusting screw locknut on the trip arm.

## REPLACEMENT

1. Remove front frame (See "Repair and Replacement').
2. Remove the bolts holding the coil to the lower stud.
3. Remove bracket and mounting screvs.


Fig. 15 Chocking Travel Distance of gerles overcarrent Tripping Device
4. Before installing a new device, check the travel of the trip arm with a rod or wire and push the armature solldiy ggainst the magnet (see Fig. 15). The trip arm should move at least $5 / 32^{\circ}$. If there appears to be insufficient movement of the trip arm, or If the armature appears to be binding, the device should not be used.
5. Replace new device in reverse order.
6. Adjust device as described above.

NOTE: No component parts of the overcurrent tripping devices are replaced. If will be necessary $t 0$ Install anew device whem parts are worn or damaged.

```
REVERSE CURRENT
TRIPPING DEVICE
```

The device is enclosed in a molded case and is mounted on the right pole base similiarly to the series overcurrent tripplag device.


The reverse current iripping device (sot Fug. 17) consists of a geries coll (2) with an irce eore mountad between two pole pleces ( 0 ), also : tential coil (7) connected acroses a constant wiret of voltage and mounted around a rotary-type spme ture (10). Calibration apring (B) determines the armature pick-up when acerend of curronl oceurs.

As long as the flow of eurrent throwh the breaker is in the normal direction, the mpetic tux of the series coll and the magnetic five the potential coll produce a torque which tends terrelate the armature counter clocisise. The calfinitor spring also tends to rotate the armature in fic same direction. This torque causes the ar fort to rest agalnst the stop ecrew (12) stacbel to : bearing plate on the right alde of the devico.

If the current through the ceries coll $p$ ) Is reversed, the armalure (10) tends to move fo thr clockisho direction agalnat the restrain dith

fig. If Tyical Tine-surrent Charsetoriatle
备


| 1. Trip Padale | 6. Spring | 11. Oounter Buight |
| :---: | :---: | :---: |
| 2. Serles Ooll | 7. Potentin a |  |
| 3. Trip mod | 8. Calibration iut | 13. Sere |
| 4. Trip Crank | 20. Prometure | 14. Eerem |

Fig. 17 Aevarse carrent Trlpplag Devict
calibration spring (6). When the current reversal exceeds the callbration setting, the armature revolves clockwise causing the frip rod (3) to move upward engaging the trip paddle (i), thereby trippling the breaker.

## ADIUSTMENTS, FIG. 17

No adjustments should be made in the field with the exception of checking for overtravel of the trip rod. Proper overtravel of the trlp rod la provided, if the trip rod advances the trlp paddle between $1 / 32^{\prime \prime}$ to $3 / 64^{\prime \prime}$ beyond the polnt where the breaker trips. To adjust for this amount of overtravel, lift the trip rod as high as possible after backing off the adjusting nut on the trip rod (3) 80 that it will not touch the trip paddle (1). Advance
adjusting nut on the trip rod until you can just iry the breater by lufting the trip rod (3) as iar as. will go. Then advance thls same adjusting aut a additional $1-1 / 2$ turns, thereby assuring positity tripping. Lock adjusting arz.

Be extremely cautious not to have hands mea moving parts of the breaker when making this ad justment.

## REPLACEMENT

Alter removing the wiring for the poterth: coll the reverse current device can be remore and replaced by following the procedure outline for replacing the serles overcurrent device. Fr wiring, 860 Fig. 17.

## MISCELLANEOUS

## SRUNT TRIPPING DEVICE

The shunt tripping device (refer to Fip. 18) is mounted on a bracket attached to the left alde of the operating mechanism (looking from the fromt).

A remole switch or relay contacts are used to close the circult of the device causing the armature (9) to engage the irip paddle (i1), thereby tripping the breaker. The spring (2) is used to return the armature to the neutral poaition after the breaker trips.

To prevent overheating, the coil (7) is cut off by contacts of the auxillary switch which are open when the breaker is open.

## ADIUSTMENTS

From 1/32" to $1 / 16^{\prime \prime}$ covertravel of the armatior is required when the breaker is tripped. II an adjustment is necessary to provide thls amovit a overtravel, the trip lever is bent in or out ac cordingly.

## REPLACEMENT - COL (7), FIG. 18

1. Discomnect leads to coll.
2. Remove magnet (6) and coll from frame (3
3. Bend lower end of clamp (8) atraigh an remove.
4. Remove coll and install new coll in re verse order.

## bell alarm and LOCKOUT DEVICE

Refer to Fis. 19. When the breaker is tripped by an overload device, auxiliary shan (9) rotates counter clockwise causing latch (B) to move off of latch arm (5). The breaker opens causing prop (3) to rotate clockwise aliowing switch (2) to close. The switch then rotates latch arm (5), which, in turn allows catch (11) to move downward thereby locking latch arm ( 6 ) in the rotated position. When In the rotated position the latch arm keeps the trip shaft and prop (3) in the trip-lree poslition, thus keeping the breater irom being closed unth the lockout mechanism is reset by means of reset button (1). When tive switch is closed it sounds in alarm. If the breaker is tripped by any device other than an overload derice, latch (8) keeps latch arm (5)
from rotating and therefore stops the bell alarit and lockout device mechanism from operating.

## AnTESTELETS

1. With the breaker mechanism and lockut mechanism in the reset poaltion adjustins screw (13) should be set so that auxiliars shalt (9) clears ithe overload paddles e the trip shaft by $1 / \mathrm{K}^{\prime \prime}$ to $3 / A K^{\prime \prime}$.
2. With the iront Irame assembied to the back irame the adjusting serews in the serien overcurrent trippligg devices should be ad justed so that there is approximately $1 / \mathrm{c}^{2}$ overtravel after the overiond device trips the breaker. gee fiem 4 under 'series the breaker. see ${ }^{\text {nem }}$ Orercurrent Device, "Replacements."


Fig. 19 Boll Alarm Ind Lockot't gevice

## DISCONNECTS

The disconnects are attached to the circult breaker studs at the rear of the breaker.

Each disconnect consists of elght contact fingers (5), 10 ur retainers (V), two spacers (4), twoscrews (1), one retaining ring (6), four washers (2) and four springs (3). The parts are assembled as shown in Fig. 20.

## ADIESTMENTS, FIG. 20

Tighten the nuts on screw (1) compressing eprings (3) so that the spring length from retalner to washer does not exceed 1-1/32 inches.

## LUBRICATION

Grease contact fingers (5) with General Electric Company grease speclifcatloa D50H28.


Fis. 2 secendary Ilscennect

## RENEWAL PARTS

When ordering renewal parts, address the nearest Sales Oifice of the General Electric Company speclifing the quantlty required. The parts should be described and the complete nameplate data of the breaker should be given.

Renewal parts, which are furnished, may not be identical whithe original parts Bince improvements are made from time to time. Parts which are furnished will be interchangeable.

| G.E. - VOLUME 1 - TYPE 'A K L.V. BREAKERS |  |  |  |
| :---: | :---: | :---: | :---: |
| TAB | CATALOG SECTION | DESCRIITION | CONTENTS |
| 1 |  | AK Breakers with Stored Energy |  |
| 2 | $\frac{\text { GEK-7302B }}{\text { GEK-7302 }}$ | Instuctions/Installation/ Operation Manual | $A K-2 / 3 / 2 A / 3 A-15$ $A K-2 / 2 / 2 A / 3 A-25$ $A K-2 / 3 / / 5 / 2 A / 3 A / A / / 5 A-50 / 50 S$ $A K-2 / 3 / 2 A / 3 A-75 / 75 S$ $A K-2 / 3 / 2 A / 3 A-100 / 100 S$ $A K T-2 / 3 / 50 / 50 S$ $A K L-2 / 3 / 2 A / 3 A-25$ $A K L-2 / 3 / 4 / 5 / 2 A / 3 A / 4 A / 5 A-50 / 50 S$ $A K F-2 / 2 A-25$ $A K F-2 C 12 D / 2 E$ |
| 3 | GEH-2021D <br> GEH-20210 <br> GEH-2021 | Instuctions/Installation / Operation Manual | AK-1-15/25/50/75/100 <br> AK $-2-15 / 25 / 50 / 75 / 100$ <br> AK-1k-25 <br> AK-2A-15/25/50/75/100 <br> AK-2-508/758/4008 <br> AK-2 $4-508 / 758 / 100 \mathrm{~S}$ <br> A.KF-1A-25 <br> AKFF-1E/C/2C/1D/2D <br> AKU-2-25/50/508 <br> AKU-2 $\mathrm{A}-25 / 50$ |
| 4 | $\begin{aligned} & \text { GEF-74603 } \\ & \text { GEL-74602 } \\ & \text { GEI-23989 } \end{aligned}$ | Instuctions/Maintenance Manual | $\begin{aligned} & \text { AK }-1-15 \\ & \text { AK-1-25 } \end{aligned}$ |
| 5 | GEI-74624 | Instructions/Maintenance Manual | AKF-18-3 to 10 |
| 6 | GEF-3506E | Renewal Parts | $\begin{gathered} A K-1-15 \text { and AK-1-25 } \\ \text { AKF-18 } \end{gathered}$ |


| 7 | GEI-50299E | Maintenance/nistuctions Manual | AK-2/2A-15 |
| :---: | :---: | :---: | :---: |
|  | GEI-50299D |  | AK-23/2A/3A-25 |
|  | GEI-50299A |  | $A K U-2 / 3 / 2 A / 3 A-25$ |
| 8 | GE1-93863A | Instructions Manual | AKF-2/2A-25 |
| 9 | GEF-4149G | Renewal Parts Data | AK-2/2s-15 |
|  | GEF-4149E |  | AK-2/3/2A/3A-25 |
|  |  |  | AKL-2/3/2A/3A-25 $A K F-2 / 2 A-25$ |

## Stored energy provides positive, high-speed. closing of General Electric Type <br> AK low vollage breakers

All frame sizes of General Electric low voltage power circuit breakers employ spring-operated, stored-energy mechanisms for manual or electrical operation. The stored-energy principle provides a quick-make, quick-break operating mechanism that assures positive high-speed closing of breaker, independent of the operating force. Positive, controlled closing prevents unnecessary arcing between movable and stationary contacts. This results in longer contact and breaker life.

Type AK-2A and AK-3A breakers are rugged switching and overioad and short-circuit protective devices for main, tie or feeder circuits. They provice a muans for switching circuits and equipment, disconnecting circuits for maintenance and construction and provide short-circuit protection. They also perform a wide variety of control functions such as motor starting and automatic throw-over.

## ELECTRICAHY OPER STED STORED ENER

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amotor oreotengid. in th
frame size $(225-600 \mathrm{amp})$
conseve space In the large frane give. 18.0040 . 40
amp arazeldecmotoris used ro kete cot Ho bion
requirements low (4 ampat 230 rolfs)
When the solenoid is energized
cosing spings and drives the medianis. 1 thes the
in one continuous motion, Moto she then

cosing spingeto a precetcminow fro at the


dosing stroty fie spring sump by hatuacosing

bargas shatis to cose theico
craw conditont

 adctachabe hatiles?

## WAUUAFQ QRERAUD STOREDENERC?

Wainh storedenergy breakers at sinuged and Cosed by the operation or an wing it harall in die Ak 2 A 3 thand 25 breaker, diateng of ficdo









(1)


Type AK-2A-50 manually-oporated power circuil breaker.


## $\underbrace{i x t w n t y y}$

## AK LOW VOLTAGE POWER CIRCUIT BREAKERS

## Installation and Operation

Types

AK-2/3/2A/3A-15
AK-2/3/2A/3A-25
$\mathrm{AK}-2 / 3 / 4 / 5 / 2 \mathrm{~A} / 3 \mathrm{~A} / 4 \mathrm{~A} / 5 \mathrm{~A}-50 / 50 \mathrm{~S}$
AK-2/3/2A/3A-75/75S
AK-2/3/2A/3A-100/100S

AKT-2/3/50/50S
AKU-2/3/2A/3A-25
AKU-2/3/4/5/2A/3A/4A/5A-50/50S
AKF-2/2A-25
$\mathrm{AKF}-2 \mathrm{C} / 2 \mathrm{D} / 2 \mathrm{E}$

## SWITCHGEAR PRODUCTE DEPARTMENT



## AUXILIARY DEVICES SPECIFICATIONS

| $\begin{gathered} \text { TYPE LOAD } \\ \text { OR P.F. } \end{gathered}$ | VOLTAGE |  | INTERRUPTING RATING (AMPS) |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Nominal | Range | $\begin{aligned} & \text { Auxiliary } \\ & \text { Switch } \end{aligned}$ | Bell Alarm Switch | $\begin{gathered} \text { EC-1 } \\ \text { Switchette } \end{gathered}$ |
| Resistance | 48 DC | 41-56 | 25.00 | - | - |
|  | 125 DC | 106-140 | 11.00 | 2.5 | 0.30 |
|  | 250 DC | 210-280 | 2.00 | 0.9 | 0.15 |
|  | 600 DC | 508-672 | 0.45 | 0.3 | - |
| ElectroMagnet | 48 DC | 41-56 | 15.00 | - | - |
|  | 125 DC | 106-140 | 6.25 | 2.5 | 0.30 |
|  | 250 DC | 210-280 | 1.75 | 0.9 | 0.15 |
|  | 600 DC | 508-672 | 0.35 | 0.3 | - |
| $\begin{aligned} & 75-85 \% \\ & \text { Lagging } \end{aligned}$ | 120 AC | 104-127 | 75.0 | 30.0 | - |
|  | 240 AC | 208-254 | 50.0 | 15.0 | 10.0 |
|  | 480 AC | 416-508 | 25.0 | 7.0 | 10.0 |
|  | 600 AC | 520-635 | 12.0 | 5.0 | - |
| $\begin{aligned} & 30-35 \% \\ & \text { Lagging } \end{aligned}$ | 120 AC | 104-127 | 50.0 | 30.0 | - |
|  | 240 AC | 208-254 | 25.0 | 15.0 | 10.0 |
|  | 480 AC | 416-508 | 12.0 | 7.0 | 10.0 |
|  | 600 AC | 520-635 | 8.0 | 5.0 | - |
|  |  |  |  |  |  |
| Continuous Rating (Amps) |  |  | *20.0 | *10.0 | *10.0 |
| Closing Rating (Amps) ${ }_{\text {Or }}^{30-35 \% ~} \mathrm{Pesistive}$ |  |  | 50.0 | 30.0 | ** |

* Limited to 5.0A continuous rating of \#16GA. wire on Drawout Breakers.
** Adequate for use with AK Breaker Shunt Trip Coils of the voltage ratings listed in above table. (Maximum current of 12.3 A for the 120 V . AC coil)


## RECEIVING, HANDLING AND STORAGE

Before installing, or operating these circuit breakers, make a careful reading of the sections of these instructions which are pertinent to the anticipated work.

Upon receipt of a circuit breaker, immedtately make an examination for any damage or loss sustained in shipment. If injury, loss or rough handiing is evident, file a damage claim at once with the trans-

## LOCATION

In choosing a location for the installation of an AK Circuit Breaker, there are two factors to be considered. The first of these is the effect of the location on the breaker itself. Much better performance and longer life may be expected if the area is clean, dry, dust-free, and well ventilated, than if the opposites to these conditions exist. The second consideration is convenience for operation and matntenance. The breaker should be easily accessible to the operator, and there should be sufficient space allowed for maintenance work to be done if this becomes necessary.

## MOUNTING

AK Circuit Breakers are designed to be mounted in any one of three ways. These are dead front mounting, Individual mountiug with the enclosure being provided, and drawout mounting in which the breaker is designed for insertion into a cubicle in drawout equipment such as a substation or control board.

## DEAD FRONT BREAKERS

These breakers are designed for mountIng in a switchboard or enclosing case of the customer's design and construction. Mounting in this instance consists of bolting the breaker frame to a supporting structure within the switchboard or enclosure, connecting the power buses or. cables, and making any necessary control cónnections. The front cover of the breaker enclosure The front cover of the breaker enclosure
may be a hinged door or a plate bolted to the panel. In either case, it should have a section cut out, through which the front escutcheon of the breaker may protrude. Outline drawing numbers giving the dimensions needed for preparing a suitable enclosure or cubicle for the various types of AK breakers are given below. These are for standard 2 or 3 pole breakers.
portation company and notify the nearest General Electric Sales Office.

Unpack the circuit breaker as soon as possible after it has been received. Exercise care in the unpacking to avoid damage to the breaker parts. Be sure that no loose parts are missing or left in the packaging material. Blow out any dirt or loose particles of packaging material remainingon/or In the breaker.

## INSTALLATION

\[

\]

Typlcal Outline
Drawing No.

The surface on which the breaker is mounted must be flat throughout in order not to impose any internal distortion on the breaker unit. The supporting structure must be rigid enough to avoid any possibility of the breaker studs supporting the weight of the breaker. Minimum cutout dimensions, as given by the appropriate outline drawing, must be maintained to provide adequate electrical clearance.

## INDIVIDUALLY ENCLOSED BREAKERS

Individually enclosed breakers are supplied with several types of enclosures, most common is the general puxpose type or the weather resistant type. The former is used for fayorable indoor locations and used for favorable inder for outdoor locations or indoor locations that may be subject to unfavorable conditions. All of the enclosures are pro-' vided with suitable means for mounting on walls or supporting framework. Removable cover plates are supplied with the enclosures which may be drilled or machined to accommodate the entrance of bus ducts,

If the circuit breaker is not to beplaced in service at once, store it in a clean, dry location in an upright position. Support it to prevent bending of the studs or damage to any of the breaker parts. Do not cover the breaker with any packing or other material which absorbs molsture, that may cause corrosion of breaker parts. A covering of kraft or other non-absorbent paper will prevent dust from settling on the breaker.
conduits or cables. Steps in the procedure for installing enclosed breakers follow:

1. If the breaker is an AK-15, AK-25 or an AK-50, remove it from the enclosure. With AK-50 breakers, a handle and cam arrangement is used for that part of the breaker movement that involves the disengagement or engagement of the primary disconnect. AK-75 and AK-100 breakers are bolted solidly to the enclosure frame and need not be removed from the enclosure.
2. Remove cover plates of enclosure and prepare them to accommodate whatever power entrance means is used.
3. Mount enclosing case to supporting structure.
4. Replace cover plate and make power connections to stationary terminals in enclosure.
5. If the breaker is a type AK-15, $A K-25$ or AK-50 and has been removed from the enclosure, it may now be replaced. Control power comnections to the terminal board should be made as required. (See CONNECTIONS).
6. Before energizing the power circuit, operate the breaker several times to be sure that it is functioning properly. (See OPERATION).

AK-4/5-50 breakers which are individually enclosed will have enclosures of the AKD5 drawout type. These breakers will be stralght drawout breakers, types AK-4A50 and AK-5A-50. (See instructions in this book under the heading, "Drawout Breakers AKD5 Equipment")

## DRAWOUT BREAKERS AKD EQUIPMENT

Mounting drawout breakers consists of simply placing the breaker in the proper position with respect to its enclosure, sliding or rolling it to a stop position, and, by means of a racking handle and mechanism, racking it through the last part of its movement during which the stationary and movable halves of the disconnects engage.

These instruetions do not purport to cover oll detoils of variations in equipment nor to provide for every possible contingency to be met in connection with installation, operotion or mainfenance. Should further information be desired or should particular probloms orise which are not covered sufficiently for the purchaser's purposes, the matter should be referred to the General Electric Company.

Large drawout breakers are fastened to a telescoping tray which extends out from the enclosure to receive the breaker. Small breakers have guldes on their side plates which slide in channels in the enclosures. Both large and small breakers have a test position in which the secondary disconnects are engaged, but the primary disconnects are not. In this position, the breaker may be operated electrically without energizing the load cable or bus.

Use D50H47 lubricant on the disconnect terminals to reduce the force required to insert the breaker.

## Inserting Breaker AK-15 and 25

## 1. Trip the breaker,

2. Raise the breaker unttl the guides on the sides of the breaker are level with their mating supporting channels in the enclosure, and slide the breaker part way into its enclosure. (Note - The breaker will be obstructed by a position stop at the bottom of the enclosure after the breaker has traveled only a short distance into the cubicle. Lift the position stop handle, located at the bottom right of the enclosure, which will release the position stop and allow the breaker to travel further into the cubicle).
3. Raise the rackout handle forward and up as far as its travel will permit and push the breaker into the enclosure until the rackout pins on the handle assembly bear against the housing rackout cams on the side of the enclosing case.
4. Push downward on the rackout handie forcing the pins on the handle up into the slot in the stationary cam plate. This action forces the breaker through a final short portion of its movement into the enclosure and allows the operator to provide the force necessary to make the primary disconnects engage the stationary studs in the enclosure. Inperforming this operation, make sure that the handle is rotated downwards as far as its free travel will permit and then pull the racking handle down to be sure the trip interlock is released. (Note - When the racking handle is in any position other than completely down, the breaker cannot be operated and is held trip-free by the trip interlock. This applies to the "fully in" and "test" positions.)

## Withdrawing Breaker AK-15 and 25

1. Trip the breaker open. If the breaker is not open, the interlock lever of the drawout mechanism will not permit operation of the rackout handle.
2. Pull the racking handle up and forward as far as it will travel, disengaging the primary disconnects.
3. Slide the breaker out untll the position stop engages in the front slot in the bottom of the breaker carriage. The breaker is now in the "test" position, where its primary disconnects are safely disconnected from the line and load terminals of the enclosure. (Note - Refer to section describing "Test Position" In these instructions.)
4. To remove the breaker from its enclosure, lift the position stop handle and slide the breaker forward until the position stop engages the rear slot in the bottom of
the breaker carriage. This is the safety position stop where both the primary and secondary contacte are disengaged. Again IIt the position stop handle. Silde the breaker glightly forward to remove it from the enclosure.

Inserting Breaker AK-50, 75 and 100

1. Lift the breaker to a position approximately six inches above the height of the compartment tray.
2. Pull the drawout tray out under the breaker as far as the tray will travel. NOTE - When installing an individual skeleton housing for a drawout AK-50 or 75, locate a bolt head over the two front bottom mounting holes of the housing to provide a limit stop for the drawout tray.
3. Lower the breaker about $1 / 2$ "above the dowel pins on the tray and push the breaker back into its compartment so that the rear bottom angle of the breaker is against the guides on the tray directly back of the dowel pins.
4. Slowly lower the breaker onto the tray and at the same time gulde it so that the holes in the rear angle of the breaker fit over the two dowel pins on the tray. If the breaker is correctly positioned on the dowels, its rear and side bottom frame angles will all sit firmly on the tray:
5. Insert two $3 / 8$ Inch hex. head screws through the holes in the front of the side angles on the breaker and thread them part way into the tapped holes in the tray. Do not tighten screws firmly. This provides better alignment of the primary stationary studs and the primary disconnects for the subsequent racking operation.
6. Push the breaker into the compartment untll the "test" position stop engages to prevent further travel. (Note - Refer to section describing "Test Position" in these instructions.)
7. Release the test posittion stop by depressing its lever and push the breaker back into the compartment until the racking pins on the housing butt against the outer surface of the racking cam. In this posithon, the racking pin has lifted the locking arm on the cam which allows the racking handle to be lifted enough to allow the pawl to engage the first notch on the cam.
8. When the pawl engages the first notch on the cam, push the handle down again to its normal position. This causes the cam to rotate about the racking pin. Repeat this operation five times to rack the breaker into its final operating position. Interlocks hold the breaker trip free until it is racked into the fully contacted position. The fifth stroke of the handle is only a partial stroke and does not result in any further movement of the breaker. It does serve three useful purposes: it posittons the cam so that it cannot rotate and allow the breaker to back out under short circult stresses; the partial stroke signals that the racking operation is complete, and it releases the trip interlock which was engaged by the racking pin during the previous four pumps of the racking arm. NOTE: Once a racking operation has been started, it must be completed, as the breaker cannot be reversed until the racking operation is completed.
9. After completing the fifth racking stroke, lift the handle as high as it will go and allow it to drop to its normal position. NOTE: Any strokes beyond this polnt will
cause the breaker to be trip dree. Tighten the $3 / 8$ inch hex head screws Inserted in the front holes of the drawout tray during step 5 of this operation. The breaker is now in the operating position.
Withdrawing Breaker AK-50, 75 and 100
10. Trip the breaker to release the positive racking interlock.
11. Lift the racking handle as far as it will go.

This operation will re-engage the trip interlock to hold the breaker trip-iree for the remainder of the racking operation. Note that here the cam is rotated by luting the handle, whereas in racking the breaker in, the operation is performer as a result of pushing the handle down.
3. Reset the handle to its lowered position and lut it again. Thls operation must be performed 5 times to completely disengage the cams from their racking pins. After the fifth lifting stroke let the handle drop to its normal position.
4. Pull the breaker out of its compartment until the test position stop engages to hold the breaker in the "test" position.
5. Depress the test position stop handle and pull the breaker out of its compartment as far as the drawout tray will travel.
6. Remove the two $3 / 8$ hex. head screws which hold the breaker on the tray.
7. Attach a lifting device to the top frame of the breaker.
8. Lift the breaker approximately $1 / 2$ inch off the dowel pins on the tray and then pull the breaker forward until its primary contacts clear the compariment.
9. Push the tray all the way back into its compartment. The breaker is now free from its compartment.

## TEST POSITION

The "Test Position", as referred to in the previous instructions, is that breaker position where the primary power disconnect contacts are safely disengaged but the secondary control disconnects are engaged. In this position, the breaker may be tested or operated, manually or electrically without energizing the primary power circuit, provided the racking handle has been moved to the completely down position, thus releasing the trip interlock.

For a more complete description of drawout mechanisms and enciosures see AKD DRAWOUT EQUIPMENT INSTRUC. TIONS, GEH-1830 and AKD5 Drawout Equipment Instructions GEI-90890.

DRAWOUT BREAKERS AKDS EQUIPMENT
NOTE: AKD5 breakers are identified by letter "A" appearingafter breaker number example, "AK-2A-15".

Drawout Mechanism Operation - There are four positions of the drawout mechanism:

1. The Connected Position - the breaker in the operating position, both primary and secondary contacts made and the door may be closed.
2. The Test Position - theprimary (power) contacts not made but the secondary (control) contacts are made. Any breaker test not involving power may be made in this position. The door may be closed in this position.
3. Disconnect Position - nether the primary nor the secondary contacts made. The door may be closed.
4. Pully Withdrawn Position - the breaker completely out of its compartment ready for removal from the inner housing. The door must be open in this position.

Breaker Insertion AK-2A/3A - With the inner housing in the connected position proceed as follows:

1. Insert handle on jackscrew shatt located on left hand side of compartment right above indicator.
2. Rotate handle counter clockwise until jackscrew is stopped. (Indicator should read DISC).
3. Remove handle and open compartment door.
4. Rotate the two track lock links and pull the right track to the limit of , its travel.
5. Using a listing device, raise the breaker unth the breakers mounting pins are approximately one inch above the tracks.
6. Pull the remaining track out to the limit of its travel and lower breaker so the breaker mounting pins drop into the slots in the track. Remove the lifting device.


Fig. 1 (Front View)
7. Push the breaker in against the track stops. Rotate the two track lock links to lock the breaker in place. Close the compartment door.
NOTE: When moving a breaker from one position to another, be sure breaker is tripped open.
8. Insert handle on jackscrew shaft and rotate clockwise to move breaker into the compartment. Breaker is in connected position when jackscrew can no
longer be rotated. (Indicator should read CONN).

Breaker Insertion AK-4A/5A - With the inner housing in the connected position, proceed as follows:

1. Open door and remove wooden wedge in the lower guide slot of the inner housing.
2. Pull inner housing forward as far as possible.

3. Rotate the two track lock liniss, and pull the right track all the way forward.
4. Using a lifting device and the spreader provided for these breakers, ralse the breaker and position it 80 that the mounting pins on the side of the breaker line up with the slots in the track and are about 2 inches above the track.
5. Pull the left track out and lower the breaker so that the mounting pins engage the slots in the tracks.
6. Engage the racking handle. This is done by pushing the trip button in the breaker escutcheon, sliding the cover below it to the right, and inserting the handle on the jackshaft.
7. Turn the handle counterclockwise as far as it will go, (if it will move in that direction) and remove the hancle.
8. Push the breaker in against the track stops, and lock the track links.
9. Close the compartment door. Again engage the handie as in step 6, and rotate the handle clockwise as far as it will go. Towards the end, a high force requirement will be felt as the disconnect fingers on the breaker engage the stationary studs. A couple of .turns later, and the stop will be encountered. The position indicator will now show "CONN."

## Breaker Removal AK-2A/3A

1. Trip the breaker.
2. Move the breaker and inner housing to the fully withdrawn position. (See

- Breaker Insertion, Steps 1, 2 and 3).

3. Rotate the two track lock links and pull the breaker out to the limit of the track travel. Attach lifting device and lift breaker up and away from compartment untll primary disconnects clear the compartment.
4. Move the inner housing to the connected position by pushing the tracks back agalnst the track stops and then follow Steps 7 and 8 under Breaker Insertion. The inner housing is now in the connected position and the breaker is iree from its compartment.

## Breaker Removal AK-4A/5A

1. Trip the breaker.
2. Engage the handle and rotate it counterclockwise. If the breaker closing spring is fully charged, it will be discharged automatically a couple of turns before the end of the action.
3. Open the door, unlock the track locks, and pull the breaker all the way forward. The breaker may now be lifted from the tracks.

NOTE: The installation of AK-2/3-50S/75S/ 100S/AKF2C/2D and breakers equipped with the quick-closing mechanism is the same as the other breakers described in this book. The only difference occurs with drawout breakers. The compartments that house the quick-close breakers will be equipped with an interlock that prevents the manual discharging of the closing springs while the
breaker is in the racked in (connected position). This interlock, when requested, will be provided with both AKD and AKD5 equipment that require quick close breakers

## CONNECTIONS

All electrical connections should be made to assure good conductivity. Mating surfaces should be parallel and firmly bolted or clamped together. Contact surfaces should be clean and have a smooth finish. The bus or cable connecting to the breaker should have adequate currentcarrying capacity to prevent excessive heating. Control circuit connections should be made according to the wiring diagram which applies to each breaker specificaliy. Depending on the breaker type, those connections are made elther to a terminal board on the breaker or to the stationary parts of the secondary disconnects.

## INDIVIDUALLY ENCLOSED AND STATIONARY BREAKERS

The customers external connections for operation of breaker control components and accessortes are shown in Fig. 1.

## DRAWOUT BREAKERS

The customers external control connections to these breakers are made to the stationary secondary disconnected located in the breaker compartment as shown In Figs. 2 and 3, AKD Equipment and Figs. 4 and 5 AKD5 Equipment. (Note - If the breaker is used th a General Electric Company, Drawout Switchgear Equipment, all external connections must be made to terminal blocka located in the rear vertical wiring trough of the equipment.)


## OPERATION

## MANUAL CLOSING

AK-15/25 manually operated breakers are closed by turning the handle 90 degrees counterclockwise and then clockwise 90 degrees back to the original position. The indtial ccunterclockwise movement resets the closing mechanism. The clockwise movement closes the breaker.

The closing mechanism of the AK-2/3 50/75/100 manual breakers is a spring charged mechanism similar to the one used on AK-2/3-50/75/100 electrically operated breakers. AK-2/3-50/75/100 manual breakers are closed by rotating the closing handle counterclockwise through approximately 120 degrees, and then clockwise back through 120 degrees to the normal handle position. Four such complete movements of the handle are required to close the breaker. During the four counterclockwise movements and the first three clockwise movements of the handle, the springs are charged. After approximately 70 degrees travel of the fourth clockwise handle movement, the spring charged mechanism is driven over-center and the breaker closes. A charge-indicator, numbered 1 to 4, viewed through the breaker front escutcheon, moves with each complete handie movement and indicates the number of complete handle movements that have been performed.

AK-4/5-50 manual breakers are also closed by means of energy released through the discharge of a closing spring. The charging of the spring is done by a single stroke of the breaker handle. This involves raising the handle counterclockwise from the vertical position until a stop is encountered after about 140 degrees of rotatlon. The spring is then extended to its fully charged position as the handle is returned to its normal vertical position. Release of the spring, and resultant closing of the breaker, occurs when the "close" button in the escutcheon is pushed. (The breaker will close only if the racking mechanism is in the "CONN" or "TEST" position.)

ELECTRICAL CLOSING
(Figures 6 and 7)
STANDARD BREAKERS
AK-15 and AK-25 electrically operated

breakers are closed by a solenold coll. The armature of the solenold ts linked to the breaker mechanism and lts movement, operating through the mechanism, closes the breaker. The closing solenold circuit may be operated by a push button closing switch on the breaker or by a remote switch or relay, depending on the individual arrangements desired. When a closing signal is glven, the $X$ relay coll is energlzed and it in turn closes its contacts. One of these seals th the $X$ coll circult; the other three, which are arranged in series, energize the solenotd closing coll. As the breaker closes, a mechanically operated switch opens one pair of lts contacts (bb) and closes another (aa). The contacts which open cut out the $X$ relay coll. The contacts which close energize the $Y$ relay coll, whose contacts now seal in the $Y$ coll and hold open the $X$ relay coll circuit. This prevents another closing operation if one of the protective devices operates to trip the breaker before contact at the closing switch is released.

Large AK breakers (AK-50/75/100) are closed by the discharge of a closing spring. This rotates a crankshaft which, by means of an attached roller, operates a closing cam, forcing the movable breaker contacts against the stationary contacts. The closing spring is charged through the operation of a motor and gear reduction unt.

The electrical control system is comprised of an $X$ relay, two double contact mechanically operated switches ( $F$ and $G$ ), a push button closing switch and any means for remote closing which the user may incorporate into the system. When voltage is first applled to the breaker, (before any closing signal is given) the motor is energlzed through two of the $X$ relay contacts and the two $G$ switch contacts. The motor then compresses the closing springs to the "pre-charged" position at which point the mechanically operated $F$ and $G$ switches are operated. This opens the $G$ contacts, stopping the motor, and closes the F contacts, which readles the system for the actual closing of the breaker. When the push button or remote switch signals for a closing operation, the X relay coil is
 Internei Wi:1ng AK-15 and 35


LEGENO
(4) - closing coron

X - relay coil

- relar contact

Fac - mechamically operated switches
4. MCRUALLY OPEN syitce contacts - MORMALLY Closed smitch cowtacts

L - AUXILIARY SWITCH CONTACT
S:mp:stra Firgertary Dinarm
F: Stminal aintim AK-50, 75 and 190


Fig. 8
energized, operating the $X$ contacts. Thls seals in the $X$ relay and energizes the motor once again and the closing operation takes place.

## QUICK CLOSE BREAKERS (Figure 8)

Functionally, the quick close mechanism differs from the standard electrical mechanism in that the pre-charge operation is extended to completely charge the closing springs. At the end of the charging operation, which takes approximately 5 seconds, (2 seconds for AK-4/5-50 breakers) a latch olate engages the prop roller to prevent the closing springs from discharging.

With the closing springs fully charged the breaker is ready for a closing operation upon release of the prop roller. This may je accomplished either manually, by depressing the closing lever on the breaker, or electrically by closing the remote closing switch. Upon the release of the prop roller the closing springs discharge and close the breaker in the same manner as on the standard electrical breaker. AK-4/550 breakers are closed through a remote switch or the close button in the escutcheon, (if the breaker is equipped with a push button closing switch).

With control voltage applied, the motor is energized through the $G$ switch contacts, and charges the closing springs. When the springs reach the fully charged position, the mechanically operated switches operate, reversing their contacts. Upon operation of these switches the motor is stopped by the opening of the $G$ switch. The closing of the $F$ switch prepares the breaker for a closing operation.

A closing signal now given energizes the control relay $X$ whose contacts close and complete the circuit through the closing relay coil. With the closing relay coll energized the breaker closes as described above. At the same time the closing relay contact closes to energize the anti-pump relay causing its contacts to reverse providing the anti-pump feature.

When the breaker closes, the mechanical operated $G$ switches close to energize the motor again and the $F$ switches open and de-energize the control relay. The awxiliary switch contact opens preventing the control relay from betng energlzeduntil the breaker is tripped open. With the $G$ switches closed, the motor charges the closing springs ready for the next closing operation.

## MANUAL OR MAINTENANCE CLOSDNG OF ELECTRICAL BREAKERS

All electrical breakers may be closed manually by means of the maintenance handle furnished with the breaker or switchgear.

## To close AK-15/25 breakers:

-1. Place the two small hooks of the handle into the two slots located in the lower portion of the front escutcheon.
2. Rotation of the long end of the handle downwards forces the shorter end of the handle upwards against the bottom of the solenoid armature, and closes the breaker's contacts.

To close AK-2/3-50/75/100 breakers:

1. Place the ratchet type maintenance handle on the shaft that protrudes from the gear reduction unit.
2. Operate handle until the spring charge indicator reads charged.
3. Contimue to operate handle until the closing springs discharge and close the contacts.

To close AK-50S/75S/100S, AKF2C, 2D breakers and breakers equipped with the quick closing mechanism:

NOTE: All AKD, or AKD-5 drawout type breakers equipped with the quick closing mechanism cannot normally be closed manually when in the racked in (connected
position), due to mechanical designed interference between the enclosure and the spring discharge lever ${ }^{*}$ on the breaker. If manual closing is desired with the breaker racked in, the interference feature must be removed, otherwise the breaker can be manually closed in the test position or fully racked out position only.

1. With the ratchet type maintenance handle applied to the gear box shaft, operate the handle until the springs are fully charged. The fully charged position is indicated by the spring charge indicator and by solid resistance to any further handle operation.
2. Push down on the push to close lever to release the energy stored in the closing springs which closes the breaker's contacts.
To close AK-4/5-50 breakers:
NOTE: AK-4A and AK-5A drawout breakers will be "trip-free" if the racking mechanism is in any position other than the "TEST" or "CONN" position. If the breaker is on a workbench or on the extended rails, and it is to be closed with the maintenance handle, operate the drawout mechanism as far as it will go in a clockwise direction. This will put the mechanism in the "connected" position, and the breaker may be closed. If this is done, the mechanism will have to be reset to the "disconnected" position before it can be reinserted into the breaker compartment in the enclosure.
3. Place the maintenance handle on the end of the camshaft below the motor.
4. Operate the handle until the closing spring goes over center and the breaker closes. If the breaker is a "quick-close" breaker, type AK-4/5-50S, the spring will not release upon going over center, but will be held off by a blocking link. This can be released by pulling forward on the closing solenoid armature located beneath the mechanism. This can be done safely, since no moving parts are located in this space.

## TRIPPING

The breaker is tripped open by the displacement of a mechanism latch, which allows a toggle linkage supporting the movable contacts in the closed position to collapse. This trip latch is fastened rigidly to a trip shaft which runs horizontally from. leit to right through the
breaker. All of the means provided for tripping the breaker operate through striker arms which displace the mechanism trip latch by moving against trip paddles fastened on the trip shaft. Looking at the breaker from the right, counterclockwise rotation of the trip shaft causes the breaker to trip; clockwise movement resets the mechanism latch. The manual trip button, overload devices, shunt trip, undervoltage tripping device, and reverse current trip all operate in this fashion to trip the breaker. The movement of the striker arms of all of these, when activated, should move from $1 / 32$ to $1 / 16$ inch beyond the point at which tripping occurs. This is what is meant by the expression, "positive tripping".
NOTE: BEFORE MAKING ANY ADJUSTMENTS TO TRIP DEVICE SETTINGS, THE BREAKER SHOULD BE IN THE OPEN POSITION AND CONTROL POWER REMOVED.

Most AK-2 and AK-4 air circuit breakers are equipped with series overcurrent trip devices elther of the dual magnetic type (instantaneous and time delay tripping) or instantaneous alone. Breakers are designed to carry up to $100 \%$ of the continuous current rating of their trip devices. Any attempt to carry higher currents for a prolonged period will cause overheating and possible damage.

All AK-3 and AK-5 type air circuit breakers will be equipped with Power Sensor* overcurrent trip devices. The time current band as well as the pickap settings of this device are adjustable. A single captive thumb screw adjusts all three phases for any particular characteristic or setting. Should a thumb screw be inadvertently left loose the Power Sensor* will revert to the "minimum" pickup settings or "maximum" time delay bands accordingly. If after installation, nuisance tripping occurs, check the Power Sensor* for proper settings as required for the specific application and tighten all the thumb screws on the Power Sensor*.

For a more detailed discussion of the construction, operation, and application of overcurrent trip devices refer to the following publications:

1. Maintenance mamual for specific breaker involved (see "Maintenance").
2. "Selection and Application of Power Circuit Breakers" GET-1113.

## TYPE AKU AND BREAKERS WITH FUSE-BREAKER COMBINATIONS.

## Open Fuse Lockout Device

This device may be furnished with any of the above type breakers. The open fuse lockout device consists of 3 separately operated devices (one per breaker pole) each wired in parallel to corresponding breaker fuses. These devices are mounted on the
left hand side of the breaker (looking from iront). The purpose of this device is to trip the breaker upon the blowing of any one of the breaker fuses. This energizes the coil of the device causing the armature to engage the trip paddle, thereby tripping the breaker. Once operated, the armature is
latched in the closed air gap position allowing the reset button to extend forward indicating which fuse has blown, and simultancously holding the breaker in the tripfree position until the latch closed armature is released by the operating of the manual reset button.

## MAINTENANCE INSTRUCTIONS

## INSPECTION

BEFORE INSPECTION OR ANY MAIN. TENANCE WORK IS DONE, BE SURE THAT THE BREAKER IS IN THE OPEN POSITJON. ALL ELECTRICAL POWER, BOTH PRIMARY AND CONTROL SOURCES SHOULD ALSO BE DISCONNECTED.

Periodic inspection of the circuit breaker is recommended at least once a year. More frequent inspections are recommended, if severe load conditions, dust, molsture, or other unfavorable conditions exist.

Always inspect the breaker after a short circuit current has been interrupted.

At the time of inspection, the following checks should be made after the breaker has been de-energized.

1. Manually operate the breaker several times, checling for obstructions or excessive friction.
2. Electrically operate the breaker several times (if breaker has electrical control) to ascertain whether the electrical attachments are functioning properly.
3. Remove the arc quenchers by removing the channel shaped retaining bar.
4. Inspect arc quenchers and contacts for breakage or excessive burning.
Should arc quencher barriers or contacts be eroded to half their original thickness they should be replaced.

## LUBRICATION

In general, the circuit breaker requires moderate lumbrication. Bearings points and sliding surfaces should be lubricated at the regular inspection periods with a thin film of GE Lubricant D50H15. Before lubricating remove any hardened grease and dirt from latch and bearing surfaces with kerosene. ALL EXCESS LUBRICANT WHOULDBE REMOVEDWITH A CLEAN CLOTH TO AVOD ANY ACCUMULATION OF DORT OR DUST.

On drawout breakers, the contact surface of the disconnect studs should be cleaned and greased with GE Grease Specification D50H47.

These instructions have as thelr purpose the imparting of information of a general nature concerning the installation and operation of Type AK power circult breakers. If more complete and specific information is required, such as might be needed for overhauling the breaker, trouble
shorting, or replacing parts of the breaker, refer to the complete instruction for the particular breaker type involved. These are:

| Maintenance <br> Manual | Breaker Type |
| :--- | :--- |
| GEI-50298 | AK-2/2A/3/3A-15125, AK |
| GEI-93863 | U-2/2A/3/3A-25 |
| GEK-7303 | AKF-2/2A-25 |
|  | AK-2/2A/3/3A-50/75/100, |
|  | AKU-2/2A/3/3A-50 |
|  | AK-2/2A/3/3A-50S/75S/ |
| GEK-7301 | 100S, AKF-2C/2D/2E |
|  | Power Sensor Solid State |
| Test Instructions |  |
| GEK-7310 | AK/AKU-4/5-50/50S |
| GEK-7309 | Test Instructions for In- |
|  | Stallation or service of |
|  | Power Sensor Equipped |
|  | AK breakers |

Renewal parts bulletins for the various types of breakers are:

Bulletin
GEF-4149
GEF-4150
GEF-4151
GEF-4527

Breaker Type
AK-2-15/25
AK-2-50
AK-2-75/100
AK-4/5-50



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- Knoxville 39914
- Me.....iphie 2821 Governor Jahn gevier Hwy. TEXAS
- Beaumant 77705 . . . . . 1490 W . Cardiral Dr.
- Corpue Chriut $78101 . . .{ }^{2} .115$ Waco 5 .
- Dallas 78333 . . . . . 353 . ' 1302 Manor Way
- Houston $77036 \ldots . .3531$ Harvoy Wilean Dr.
- MIdiand 79701 . . . . . . . . . iot 8. Jetunton 8 .

UTAH

- Sall Lake City 81110 . . . 301 S. Tit Wect fl.

VRONIA

- Bichmond 23284 . . . . . . . 1409 trgram Ave.
- Rosinkt 24013 . ..... . . i004 River Ave., gE

WASKDGETON


- Spolate 88211 . . . . . . . . . 438 nis Miecion Et.

WEST VRGGNLA

- Charlacton 28388 . 308 MacCorkle Ave. . 8 E
wIsconsin
- Appletonl Mencera 54910 . 1728 Racine $5 t$.


# AR LOW VOLTAGE POWER CHRCUT BREAHERS INSTALLATION AND OPRRATION 

Types

$$
\begin{gathered}
\mathrm{AK}-2 / 3 / 2 \mathrm{~A} / 3 \mathrm{~A}-15 \\
\mathrm{AK}-2 / 3 / 2 \mathrm{~A} / 3 \mathrm{~A}-25 \\
\mathrm{AK}-2 / 3 / 2 \mathrm{~A} / 3 \mathrm{~A}-50 / 50 \mathrm{~S} \\
\mathrm{AK}-2 / 3 / 2 \mathrm{~A} / 3 \mathrm{~A}-75 / 75 \mathrm{~S} \\
\mathrm{AK}-2 / 3 / 2 \mathrm{~A} / 3 \mathrm{~A}-100 / 100 \mathrm{~S} \\
\mathrm{AKT}-2 / 3 / 50 / 50 \mathrm{~S} \\
\mathrm{AKU}-2 / 3 / 2 \mathrm{~A} / 3 \mathrm{~A}-25 \\
\mathrm{AKU}-2 / 3 / 2 \mathrm{~A} / 3 \mathrm{~A}-50 / 50 \mathrm{~S} \\
\mathrm{AKF}-2 / 2 \mathrm{~A}-25 \\
\mathrm{AKF}-2 \mathrm{C} / 2 \mathrm{D} / 2 \mathrm{E}
\end{gathered}
$$

# RECEIVING, HANDLING AND STORAGE 

Before ingtalling, or operaling these circult breakers, make a careful reading of the sections of these instructions which are pertinent to the anticlpated work.

Upon receipt of a circuit breaker, Immedlately make an examination for any damage or loss sustained in shipment. If Injury, loss or rough handling is evident, Hie a damage claim at once with the trans:

## LOCATION

In choosing a location for the installation of an AK Circult Breaker, there are two factors to be considered. The first of these is the effect of the location on the breaker lisell. Much better performance and longer lue may be expected 4 the area is clean, dry, dust-free, and well ventliated, than if the opposites to these condittons exist. The second consideration is conventence for operation and malntenance. The breaker should be easily accessible to the operator, and there ahould be sufficient space allowed for malntenance work to be done if this hecomes necessary.

## HOUNTUNG

AK Circuit Breakers are deslgned to be mounted in any one of three ways. These are dead front mounting, Individual mounting with the enclosure being provided, and drawout mounting in which the breaker ls deslgned for insertion into a cublcle in drawout equipment such as a substation or control board.

## DEAD FRONT BREAKERS

These breakersare designed for mounting In a switchboard or enclosing case of the customer's design and construction. Mounting In this instance consists of bolting the breaker frame to a supporting structure within the switchboard or enclosure, connecting the power buses or cables, and making any necessary control cónnections. The front cover of the breaker enclosure may be a hinged door or a plate bolted to the panel. In elther case, it should have a bection cut out, through which the front escutcheon of the breaker may protrude. Outilne drawing numbers giving the dimenalons needed for preparing a suitable enclogure or cublele for the varlous types of AK breakers are given below. These are for standard 2 or 3 pole breakers.
portation company and notily the nearest General Electric Sales Office.

Unpack the circuit breaker as soon as possible alter it has been recelved. Exercise care in the unpacking to avoid damage to the breaker parts. Be sure that no loose parts are missing or left in the packaglag material. Blow out any dirt or loose particles of packaging material remaining on/or in the breaker.

## INSTALEATION

## Breaker

AK-2-15 and 25
AK-3-15 and 25
AK-2-50 Man. Oper: AK-2-50 Elec. Oper. AK-3-50 Man. Oper.
AK-3-50 Elec. Oper.
AKT-2-50 Man. Oper.
AKT-2-50 Elec. Oper.
AKT-3-50 Man. Oper. AKT-3-50 Elec. Oper. AK-2-75 Man. Oper. AK-2-75 Elec. Oper AK-3-75 Man. Oper AK-3-75 Elec. Oper. AK-2-100 Man. Oper. AK-2-100 Elec. Oper. AK-3-100 Man. Oper. AK-3-100 Elec. Oper.

Typical Outline Drawing No.

695 C 116
$121 \mathrm{C7570}$
845 C 281
238 C 123
$121 C 7553$
121 C7555
102C3650
102C3651
121 C7589
121 C 7590
845C284
269 C 225
121 C 7583
121C7557
845 C 290
269C227
121 C7585
The surface on which the breaker is mounted must be nat throughout in order not to impose any internal distortion on the breaker unit. The supporting structure must be rigid enough to avoid any possibllity of the breaker studs supporting the weight of the breaker. Minimum cutout dimensions, as given by the appropriate outline drawing, must be maintained to provide adequate electrical clearance.

## INDIVIDUALLY ENCLOSED BREAKERS

Individually enclosed breakers are supplied with several types of enclosures, most common is the general purpose type or the weather resistant type. The forner is used for favorable indoor locations and the latter for outdoor locations or indoor locations that may be subject to unfavorable conditions. All of the enclosures are provided wilh suitable means for mounting on walls or supporting framework. Renovable cover plates are supplied with the enclosures which may be drilled or machined to accommodate the entrance of bus chucts, conduits or cables. Steps in the procedure for installing enclosed breakers follow:

1. If the breaker is an AK-15, AK-25 or an AK-50, remove it from the enclosure.

If the circult breaker ls not to be placed In service at once, store it in a clean, dry location in an upright position. Support it to prevent bending of the atuds or damage to any of the breaker parts. Do not cover the breaker with any packing or other material which absorbs molsture, that may cause corrosion of breaker parts. A covering of kraft or other non-absorbent paper will prevent dust from settling on the breaker.

With AK-50 breakers, a handle and cam arrangement is used for that part of the breaker movement that involves the disengagement or engagement of the primary disconnect. AK-75 and AK-100 breakers are bolted solidly to the enclosure irame and need not be remored from the enclosure.
2. Remove cover plates of enclosure and prepare them to accommodate whatever power entrance means is used.
3. Mount enclosing case to supporting structure.
4. Replace cover plate and make power connections to statlonary terminals in enclosure.
5. If the breaker is a type AK-15, AK-25 or AK-50 and has been removed from the enclosure, it may now be replaced. Control power connections to the terminal board should be madeas required. (See CONNECTIONS).
6. Before energizing the power circuit, operate the breaker several tures to be sure that it is functioning properly. (See OPERATION).

## DRAWOUT BREAKERS AKD EQUIPMENT

Mounting drawout breakers consists of simply placing the breaker in the proper position with respect to its enclosure sllding or rolling it to a stop position, and, by means of a racking handie and mechanism, racking it through the last part of its movement during which the staticnary and movable halves of the disconnects engage. Large drawout breakers are fastened to a telescoping tray which extends out from the enclosure to receive the breaker. Small breakers have guides on their side plates which slide in channels in the enclosures. Both large and small breakers havo a test position in which the secondary disconnects are ensaged, but the primary disconsects are not. In this position, the breaker may be operated electricaily without energizlog the loud cable or bus.
Theso instructions do not purport to cover all detailz or variations in equipmont nor to provido for evary possibla
confingency to be mot in consestion with instaltation, operalian or meinterance. Should further information bo dasired
of ahoukt partheular problams orizo whith ore rist coverod zufficionlty for the purchasor's purpasos, the matter etiould
be raforred to the Generol Eloctric Compary.

Use D50H47 lubricant on the disconnect terminals to reduce the force required to Insert the breaker.

The procedure for Inserting and withcrawling a drawout breaker from its enclosure ts as follows:

Insertlng Breaker AK-15 and 25

## 1. Trip the breaker.

2. Ralse the breaker untll the guldes on the sides of the breaker are level with thelr mating supporting channels in the enclosure, and slide the breaker part way Into lts enclosure. (Note - The breaker will be obstructed by a position stop at the bottom of the enclosure after the breaker has traveled only a short distance into the aublcle. Lift the position stop handle, iocated at the bottom right of the enclosure, which will release the position stop and allow the breaker to travel further Into the s:ublcle).
3. Raise the rackout handle forward and up as far as its travel will permit and push the breaker into the enclosure untll the rackout pins on the handle assembly bear against the housing rackout cams on the side of the enclosing case.
4. Push downward on the rackout handile forcing the pins on the handle up into the slot In the stationary cam plate. This action forces the breaker through a final short portion of its movement into the enclosure and allows the operator to provide force necessary to make the primary
iconnects engage the stationary studs In re enclosure. In performing this operation, make sure that the handle is rotated downwards as far as its free travel will permit and then pull the racking handle down to be sure the trip interlock is released. (Note - When the racking handle is in any position other than completely down, the breaker cannot be operated and is held trip-irce by the trip interlock. Thls applles to the "fully in" and "test" positions.)

## Withdrawing Breaker AK-15 and 25

1. Trip the breaker open. If the breaker is not open, the Interlock lever of the drawout mechanism will not permit operation of the rackout handle.
2. Pull the racking handle up and forward as far as it wil travel, disengaging the primary disconnects.
3. Slide the breaker out untll the position stop engages in the iront slot in the bottom of the breaker carriage. The breaker is now in the "test" position, where its primary disconnects are safely disconnccted from the line and load terminals of the enclosure. (Note - Refer to section describing "Test Position" in these instructions.)
4. To remove the breaker from tts enclosure, lut the position stop handle and slide the breaker forward until the positton Ap engages the rear slot in the bottom of
breaker carriage. This is the safety ittion stop where both the primary and
secondary contacts are disengaged. Again lift the position stop handle. silide the breaker slightly forward to remove it from the enclosure.

## Inserting Breaker AK-50, 75 and 100

1. Lift the breaker to a position approxlmately six inches above the helght of the compartment tray.
2. Pull the drawout tray out under the breaker as far as the tray will travel. NOTE - When installing an individual skeleton housing for a drawout AK-50 or 75, locate a bolt head over the two front bottom mounting holes of the housing to provide a IImit stop for the drawout tray.
3. Lower the breaker about $1 / 2^{\prime \prime}$ above the dowel pins on the tray and push the breaker back into its compartment so that the rear bottom angle of the breaker is against the guides on the tray directly back of the dowel plas.
4. Slowly lower the breaker onto the tray and at the same time guide it so that the holes in the rear angle of the breaker fit over the two dowel pins on the tray. If the breaker is correctly positioned on the dowels, its rear and side bottom frame angles will all sit firmly on the tray.
5. Insert two $3 / 8$ inch hex. head screws through the holes in the front of the side angles on the breaker and thread them part way tnto the tapped holes in the tray. Do not tighten screws firmly. This provides better alignment of the primary stationary studs and the primary disconnects for the subsequent racking operatlon.
6. Push the breaker into the compartment untll the "test" position stop engages to prevent further travel. (Note - Refer to section describlng "Test Position" in these instructions.)
7. Release the test position stop by depressing its lever and push the breaker back lnto the compartment until the racking pins on the housing butt against the outer surface of the racking cam. In this position, the racking pin has lifted the locking arm on the cam which allows the racking handle to be lifted enough to allow the pawl to engage the first notch on the cam.
8. When the pawl engages the first notch on the cam, push the handle down again to lts normal position. This causes the cam to rotate about the racking pin. Repeat this operation five times to rack the breaker into its final operating position. Interlocks hold the breaker trip free until it is racked into the fully contacted position. The futh stroke of the handle is only a partial stroke and does not result in any further movement of the breaker. It does serve three useful purposes: it positions the cam so that it cañot rotate and allow the breaker to back out under short circult stresses; the partial stroke signals that the racking operation is complete, and it releases the trip interlock which was engaged by the racking plin during the previous four pumps of the racking arm. NOTE: Once a racking operation has been started, it must be completed, as the breaker cannot be reversed until the racking operation is completed.
9. After completing the fifth racking stroke, 14 the handle as high as it will go and allow it to drop to its normal posittion. NOTE: Any strokes beyond thls point will
cause the breaker to be trip iree. Tighten the $3 / 8$ Inch hex head screws inserted in the front holes of the drawout tray during $s^{\circ}$ 5 of this operation. The breaker is no the operating position.

Withdrawing Breaker AK-50, 75 and 100

1. Trip the breaker to relcase the positlve racking interiock.

## 2. Lift the racking handle as far 28 it

 will go.Thls operation will re-engage the trip interlock to hold the breaker trip-lree for the remainder of the racking operation. Note that here the cam is rotated by luting the handle, whereas in racking the breaker in, the operation is performer as a resul of pushing the handie down.
3. Reset the handle to its lowered positton and lut it again. This operation must be performed 5 times to completely disengage the cams from their racking pins. After the fifth luting stroke let the handle drop to lts normal position.
4. Pull the breaker out of its compartment until the test position stop engages to hold the breaker in the "test" position.
5. Depress the test position stop handle and pull the breaker out of its compartment as far as the drawout tray will travel.
6. Remove the two $3 / 8$ hex. head screws which hold the breaker on the tray.
7. Attach a Ifting device to the trm frame of the breaker.
8. Luft the breaker approximately $1 /$ inch off the dowel pins on the tray and then pull the breaker forward untli its primary contacts clear the compartment.
9. Push the tray all the way back into its compartment. The breaker ts now free from lis compartment.

## TEST POSITION

The "Test Position", as referred to in the previous instructions, is that breaker position where the primary power disconnect contacts are safely disengaged but the secondary control disconnects are engaged. In this position, the breaker may be tested or operated, manually or electrically without energizing the primary power circult, provided the racking handle has been moved to the completely down position, thus releasing the trip interlock.

For a more complete degcription of drawout mechanisms and enclosures see AKD DRAWOUT EQUIPMENT INSTRUCTIONS, GEH-1830 and AKD5 Drawout Equlp. ment Instructions GEI-90980.

## DRAWOUT BREAKERS AKD5 EQUIPMENT

NOTE: AKD5 breakers are identifled by letter " $A^{\prime \prime}$ appearing after breaker number example, "AK-2A-15".

Drawout Mechanlsm Operation - There tour positions of the drawout mechanis

- 1. The Connected Position - the breaker In the operating position, both primary and secondary contacts made and the door may be closed.
The Test Posllton - the primary (power) contacts not made but the secondary (control) contacts are made. Any breaker test not involving power may be made in this position. The door may be closed in this position.

3. Disconnect Position - nelther the primary nor the secondary contacts made. The door may be closed.
4. Pully Withdrawn Position - the breaker completely out of its compartment ready for removal from the inner housing. The door must be open in thls position.

NOTE: The mechanism is designed to reverse automatically in the connect and fully disconnected positton. Once an operation is started lit must be completed. Completion of an operation is indicated by the red knob retracting to tis original position.

Breaker Insertion AK-2A/3A - With the inner housing in the connected position proceed as follows:

1. Insert handle on jackscrew shaft located on left hand slde of compartment right above indicator.
2. Rotate handle counter clockroise until jackscrew Ls stopped. (Indicator should read DISC).
Remove hancle and open compartment door.
Rotate the two track lock LInies and pull the right track to the limit of Its travel.

3. Using a Hiting device, ralse the breakor until the breakers mounting pins are approdmately one inch above the tracks.
4. Pull the remalning track out to the Umit of tts travel and lower breaker so the breaker mounting pins drop into the slots in the track. Remove the iffing device.
5. Push the breaker in against the track stops. Rotate the two track lock linkes
to lock the breaker in place. Close the compartment door.

NOTE: When moving a breaker from one position to another, be sure breaker is tripped open.
8. Insert handle on jackscrew shaft and rotate clockwise to move breaker into the compartment. Breaker is in cornected position when jackscrew can no longer be rotated. (Indlcator showld read CONN).


F:S. 2 Frant Vtes AK-15 and 25 Breaker Compartment
Pig. 3 Front Vieu AK-50, 75, 100 Bresiker Compartment

## Breaker Removal AK-2A/3A

1. Trip the breaker.

Move the breaker and inner housing to the fully withdrawn position. (See Breaker Insertion, Steps 1, 2 and 3).
3. Rotate the two track lock links and pull the breaker out to the limit of the track travel. Attach lifting device and lift breaker up and away from compartment until primary disconnects clear the compartment.
4. Move the inner housing to the connected position by pushing the tracks back against the track stops and then follow 8 steps 7 and 8 under Breaker Insertion. The Inner housing is now in the connetted position and the breaker is free from its compartment.

NOTE: The Installation of AK505/75S/ 100S/AKF2C/2D and breakers equipped with the quick-closing mechanism is the same as the other breakers described in this book. The only difference occurs with drawout breakers. The compartments that house the quick-close breakers will be equipped with an Interlock that prevents the manual discharging of the closing springs while the breaker is in the racked in (connetted position). This interlock will be provided with both AKD and AKD5 equipment that require quick-close breakers.

## CONNECTIONS

All electrical connections should be made to assure good conductivity. Mating surfaces should be parallel and firmly bolted or clamped together. Contact surfaces should be clean and have a smooth finish. The bus or cable connecting to the breaker should have adequate currentcarrying capacity to prevent excessive heating. Control circuit connections should be made according to the wiring diagram
which applies to each breaker specifically. Depending on the breaker type, those con nections are made ether to a termini; board on the breaker or to the atatlonar: parts of the secondary disconnects.

## INDIVIDUALLY ENCLOSED AND

 STATIONARY BREAKERSThe customers external connections for operation of breaker control components and accessories are shown in Fig. 1.

## DRAWOUT BREAKERS

The customers external control connectlons to these breakers are made to the stationary secondary disconnected located in the breaker compartment 28 shown in Figs. 2 and 3,AKD Equipment and Figs. 4 and 5 AKD5 Equipment. (Note - If the breaker ls used In a General Electric Company, Drawout Switchgear Equipment, all external connections must be made to terminal blocks located in the rear vertical wiring trough of the equipment.)

## OPERATION

MANUAL CLOSING
AK-15/25 manually operated breakers are closed by turning the handle 90 degrees
counterclockwise and then clockwise 80 degrees back to the original position. The initial counterclockwise movement resets the closing mechanism. The clockwise
movement closes the breaker.
The closing mechanism of the AK50/75/100 manual breakers is a spring


FRONT VIEW AK -1A-15, 25 3 AK -2A-15, 25 BREAKER COMPARTMENT
charged mechanism similar to the one used on AK-50/75/100 electrically operated breakers. AK-50/75/100 manual -reakers are closed by rotating the closing ndle counterclockwise through approxi-
ately 120 degrees, and then clockwise cock through 120 degrees to the normal handle position. Four such complete movements of the handle are required to close the breaker. During the four counterclockwise movements and the first three clockwise movements of the handle, the sprlngs are charged. Alter approxlmately 70 degrees travel of the fourth clockwise handle movement, the spring charged mechanism is driven over-center and the breaker closes. A charge-indicator, numbered 1 to 4, vlewed through the breaker front escutcheon, moves with each complete handle movement and indicates the number of complete handle movements that have been performed.

## ELECTRICAL CLOSNNG

(Figures 6 and 7 )

## STANDARD BREAKERS

AK-15 and AK-25 electrically operated breakers are closed by a solenold coll. The armature of the solenoid is linked to the breaker mechanism and its movement, operating through the mechanlsm, closes the breaker. The closing solenold clrcuit may be operated by a push button closing switch on the breaker or by a remote owlich or relay, depending on the individual arrangements desired. When a closing bignal ls given, the $X$ relay coll ts energlaed and it in turn closes its contacts. One of these seals in the $X$ coll circult; the 2ther three, which are arranged in series, yergize the solenold closing coll. As the
azker closes, a mechanically operated -ritch opens one pair of tis contacts (bb) and cloges another (aa). The contacts Which open cut out the $X$ relay coll. The contacts which close energize the $\mathbf{Y}$ relay coil, whose contacts now seal in the $Y$ coll and hold open the $X$ relay coll circuit. Thls prevents another closing operation if one of the protective devices operates to trip the breaker before contact at the closing switch is released.

Large AK breakers (AK-50/75/100) are closed by the discharge of a closing spring. Thls rotates a crankshaft which, by means of an attached roller, operates a closing cam, forcing the movable breaker contacts agalnst the stationary contacts. The closing spring is charged through the operation of a motor and gear reduction unit.

The electrical control system is comprised of an X relay, two double contact mechanically operated switches ( $F$ and G), a push button closing switch and any means for remote closing which the user may incorporate Into the system. When voltage la first applied to the breaker, (before any closing slgnal is given) the motor is energized through two of the $X$ relay contacts and the two $G$ switch contacts. The motor then compresses the closing springs to the "pre-charged" position at which point the mechanically operated $F$ and $G$ switches are operaled. This opens the $G$ contacts, stopping the motor, and closes the $F$ confect, which readles the oystem for the lal closing of the breaker. When the h button or remote switch signals for - closing operation, the X relay coll is



> (0) elosine motco - nelar conl - kecar contact
Fea - mechantcally operateo switcors

- Nomanelt epen owrch contacts - mormhley clageo swnch comtacts
L - atutilary Switcm Contact

Fis. 6 Simpliticd Elementary Diagram Internal HIrint AK-15 and 25

Fig. 7 Simpliried Elementary Diagran Internal Miring AK-S0, 75 and 100
energized, operating the $X$ contacts. This seals in the X relay and energizes the motor once again and the closing operation takes place.

## QUCK CLOSE BREAKERS <br> (Figure 8)

Functionally, the quick close mechanism differs from the standard electrical mechanism in that the pre-charge operation is extended to completely charge the closing springs. At the end of the charging operation, which takes approximately 5 seconds, a latch plate engages the prop roller to prevent the closing aprings from discharging.

With the closing springs fully charged the breaker is ready for a closing operation upon release of the prop roller. This may be accomplished elther manually, by depressing the closing lever on the breaker, or electrically by closing the remote closlng switch. Upon the release of the prop roller the closing springs ditscharge and close the breaker in the same manner as on the standard electrical breaker.

With control voltage applled, the motor is energlzed through the $G$ switch contacts, and charges the closing springs. When the springs reach the fully charged position, the mechanically operated switiches operate, reversing thelr contacts. Upon operation of these switches the motor is stopped by the opening of the $G$ switch. The closing of the $F$ switch prepares the breaker for a closing operation.

A closing signal now given energizes the control relay $X$ whose contacts close and complete the circult through the closing relay coll. With the closing relay coll encrgized the breaker closes as described above. At the same time the closing relay contact closes to energize the anti-pump relay causing lts contacts to reverse providing the anti-pump feature.

When the breaker closes, the mechanical operated $G$ ariliches close to energize the molor agaln and the $F$ switches open
and de-energtze the control relay. The auxillary switch contact opens preventing the control relay from belng energizeduntil the breaker Ls tripped open. With the $\mathbf{G}$ switches closed, the motor charges the closing eprings ready for the next closing operation.

## MANUAL OR MAINTENANCE CLOSDNG OF ELECTRICAL BREAKERS

All electrical breakers may be closed manually by means of the maintenance handle furnished with the breaker or switchgear.


To close AK-15/25 breaicers:

1. Place the two small hooks of the handle into the two slots located in the lower portion of the front escutcheon.
Rotation of the long end of the handle downwards forces the shorter end of the handle upwards against the bottom of the solenoid armature, and closes the breaker's contacts.

## To close AK-50/75/100 breakers:

1. Place the ratchet type maintenance handie on the shaft that protrudes from the gear reduction unit.
2. Operate handle until the spring charge indicator reads charged.
3. Continue to operate handie until the closing springs discharge and close the contacts.

To close AK-50S/75S/100S, AKF2C, 20 breakers and breakers equipped with the quick closing mechanlsm:

NOTE: All AKD, or AKD-5 drawout type breakers equipped with the quick closing mechanism cannot normally be closed manually when in the racked in (connected position), tue to mechanical designedinterference between the enclosure and the spring discharge lever on the breaker. If manual closing is desired with the breaker racked in, the interference feature must be removed, otherwise the breaker can be manually closed in the test position or fully aracked out position only.

1. With the ratchet type maintenance handle applied to the gearbox shaft, operate the handle until the springs are fully charged. The fully charged positton is indicated by the spring charge indicator and by solid resistance to any further handle operation.
2. Push down on the push to close lever to release the energy stored in the closing springs which closes the breaker's contacts.

## TRIPPING

The breaker is tripped open by the displacement of a mechanism latch, which allows a toggle linkage supporting the movable contacts in the closed position to collapse. This trip latch is fastened rigidly to a trip shaft which runs horlzontally from left to right through the breaker. All of the means provided for tripping the breaker operate through striker arms which displace the mechanism trip latch by moving apainst trip paddles fastened on the trip shaft. Looking at the breaker from the right, counterclockwise rotation of the trip shaft causes the breaker to trip; clockwise movement resets the mechanisni latch. The manual trip button, overioad devices, shunt trip, undervoltage tripping device, and reverse current trip all operate in this fashion to trip the breaker. The movement of the striker arms of all of these, when activated, should move from $1 / 32$ to $1 / 16$ inch beyond the point at which tripping occurs. This is what is meant by the expression, "positive tripping".
NOTE: BEFORE MAKING ANY ADJUST-

MENTS TO TRIP DEVICE SETTINGS, THE BREAKER SHOULD BE IN THE OPEN POSITION AND CONTROL POWER REMOVED.

Most AK-2 air circuit breakers are 2 quipped with series overcurrent trip devices elther of the dual magnetic type (instantaneous and time delay tripping) or instantaneous alone. Breakers are designed to carry up to $100 \%$ of the continuous current rating of their trip devices. Any attempt to carry higher currents for a prolonged period will cause overheating and possible damage.

All AK-3 type air circuit breakers will be equipped with Power Sensor* overcurrent trip devices. The time current band as well as the pickup settings of this device are adjustable. A single captive thumb screw adjusts all three phases for any particular characteristic or setting. Should a thumi, screw be inadvertently left loose the Power Sensor* will revert to the "minimum" plekup settings or "maximum" time delay bands accordingly. It after installation, nulsance tripping occurs, check the Power Sensor* for proper settings as requiredfor the specific application and tighten all the thumb screws on the Power Sensor*.

For a more detatled discussion of the construction, operation, and application of overcurrent trip devices refer to the follow. ing publications:

1. Maintenance manual for spectific breaker involved (see "Maintenance").
2. "Selection and Application of Power Circuit Breakers" GET-1113.

## TYPE AKU AND BREAKERS WBTH FUSE-BREAKER COMBINATIONS

Enen Fuse Lockout Device
Thls device may be furnished with any the above type breakers. The open fuse Inckout device consists of 3 separately operated devices (one per breaker pole) each wired in parallel to corresponding breaker fuses. These devices are mounted on the
left hand side of the breaker (looking from tront). The purpose of this device is to trip the breaker upon the blowing of any one of the breaker fuses. This energizes the coll of the device causing the armature to engage the trip paddle, thereby tripping the breaker. Once operated, the armature is
latched in the closed alr gap positio allowing the reset button to extend forwar indicating which fuse has blown, and simultaneously holding the breaker in the tripIree position until the latch closed armature is released by the operating of the manual reset button.

## MAINTENANCE INSTRUCTIONS

## INSPECTION

BEFORE INSPECTION OR ANY MAINTENANCE WORK IS DONE, BESURE THAT THE BREAKER IS IN THE OPEN POSITION. ALL ELECTRICAL POWER, BOTH PRIMARY AND CONTROL SOURCES SHOULD ALSO EE DISCONNECTED.

Perlodic inspection of the circult breaker is recommended at least once a year, More frequent Inspections are recommended, if severe load conditions, dust, nolisture, or other unfavorable conditions exist.

Always Inspect the breaker after a short circult current has been interrupted.

At the time of inspection, the following checks should be made after the breaker has been de-energized.

1. Manually operate the breaker several times, checking for obstructions or excessive friction.
2. Electrically operate the breaker several times (If breaker has electrical gontrol) to ascertain whether the electrical iments are functioning properly.
3. Remove the are quenchers by removing the channel shaped retaining bar.
4. Inspect arc quenchers and contacts for breakage or excessive burning.
Should are quencher barriers or contacts be eroded to half their original thickness they should be replaced.

## LUBRICATION

In general, the circuit breaker requires moderate lumbrication. Bearing points and sllding surfaces should be lubrlcated at the reguiar inspection periods with a thin film of GE Lubricant D50H15. Before lubricating remove any hardened grease and dirt from latch and bearing surfaces with kerosene. ALL EXCESS LUBRICANT WHOULDBE REMOVEDWITH A CLEAN CLOTH TO AVOD ANY ACCUMULATION OF DORT OR DUST.

On drawout breakers, the contact surface of the disconnect studs should be cleaned and greased with GEGrease Specirlcation D50H47.

These instructions have as thelr purpose the imparting of information of a
general nature concerning the Installation and operation of Type AK power circult breakers. If more complete and specific information is required, such as might be needed for overhauling the breaker, trouble shorting, or replacing parts of the breaker, refer to the complete instruction for the particular breaker type involved. These are:

Maintenance
Manual
GEI-50299
GEI-93863
GEK-7303

GEK-7301

> Breaker Type
> AK-2/2A/3/3A-15125, AK U-2/2A/3/3A-25 AKF-2/2A-25
> AK-2/2A/3/3A-50/75/100, AKU-2/2A/3A-50 AK-2/2A/3/3A-50S/75S/ 100S, AKF-2C/2D/2E Power Sensor Solid State Test instructions

Renewal parts bulletins for the various types of breakers are:

| Bulletin | Breaker Type |
| :--- | :--- |
| GEF-4149 | AK-2-15/25 |
| GEF-4150 | AK-2-50 |
| GEF-4151 | AK-2-75/100 |







[^1]






[^2]

[^3]


OEET-:113J
electric


## Co-ordinated system provides best possible combination of continuous power, continuous protection

The highest degree of service reliability can be secured by the careful selection of main and feeder circuit breaker time-current characteristics with proper relation to one another. This is what is meant by circuit breaker co-ordination.
Electrical distribution systems-no matter how carefully constructed and thoroughly insulated-can have faults. With proper co-ordination, it is possible to protect the system from unnecessary downtime caused by faults. This is achieved by
matching the characteristics of protective devices from tine power source to utilization in order to achieve the highest d (-gree of service reliability. This co-ordination is provided in addition to proper mechanical design of the equipment, insu lation levels, thermal capacity and short-circuit bracing. Co ordinated, the system provides the most desirable combination of continuous power and continuous protection.

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Applicasion Informarion

## FOREWORD

The selection of power circuit breakers for the protection of low-voltage circuits is similar to the problem of selecting other types of electrical equipment. To be properly applied, a circuit breaker should he suited to the power system on which isf: is to be used; it should be able to with. stan:- the service conditions to be encountered, and should provide the necessary overcurrent protection either by itself or in co-ordination with other pro tective devices.

Most of the factors pertaining to the characteristics of the power system and the service conditions under which the breakers will operate will be obvious by inspection. One exception to this is the
value of the maximum available short circuit current which the breakers must interrupt. This must be determined either by calculation or with assistance from the local power company. The characteristics of the load to be supplied and the coordination required with other breakers in the system, dictate the type of overcurrent trip devices which should be selected for a particular breaker.

The material in this section is intended to assist in the selection of generalpurpose low-voltage power circuit brealsers and their trip devices as recommended by the NEMA Standards. A summary of breaker types and ratings is given in Table I.

## TABLE I-Summary of Breaker Types, Ratings



(Thero 8024T00)
pis. 1. AK.2.15

(Thote 802A132)
fig. 2. Ak-2.25

(Photo 8017150)
Fig. 3. AK-2-50

(Phete 80171sof)
Fig. 4. AK-2.75

(Fheto 8017150)
Fig. 5. AK-2-100

## APPLICATION FACTORS

In selecting power circuit breakers, the following factors relating to the characteristics of the power system to which the breakers are to be applied and the conditions under which they will operate should be considered.

1. Circuit voltage.
2. Circuit-load current.
3. Available short-circuit current.
4. System frequency.
5. The ambient temperature.
6. Frequency of operation.
7. Altitude.
8. Local electrical codes.
9. Unusual service conditions.
10. Special duty cycles.

These factors should be given the consideration indicated in the following paragraphs. Note, when reference to the Company is indicated, inquiry should be made to the nearest Apparatus Sales Office for referral to the Low Voltage Switchgear Marketing Section, Philadelphia.

## 1. Circuit Voltage

The voltage rating of the circuit breaker should equal or exceed the nominal voltage of the circuit to which it is to be applied.

## 2. Circuit-load Current

The continuous current rating of a circuit breaker should equal or exceed the maximum-load current which the circuit will carry as established by the overload or thermal ratings of the apparatus serviced by the circuit. In this connection attention is directed to the following quotation which is a paragraph under Section SG3-3.03 of NEMA Low-voltage Power Circuit Breaker Standards, Pub. No. SG3-1958.
"NOTE: Circuit breakers are rated upon a maximum basis. They are circuit interrupters and protective devices and, as such, may be called upon at any time successfully to remove from service other equipment or circuits. Furthermore, after such a circuit interruption, their current-carrying ability may be materially reduced. Because of these conditions which differ from those for generators, motors, transformers, and similar apparatus, it is not practical to establish etandard overload or thermal ratings."

## 3. Avallable Shor-eircuit Current

The available short-circuit current at a given point in a power system is the maximum current which the power system, when operating with maximum generating capacity and connected motor load can deliver to zero impedance short circuits simultaneously applied from all phases or polarities to ground. For a.c systems the calculated value of the shortcircuit current available must be less than the interrupting rating of the circuit breaker. For d-c systems the maximum steady-state current should be less than the interrupting rating of the circuit breaker.

For a discussion of the interrupting ratings of G-E breakers, refer to pages 3 and 4.

## 4. System Frequency

The frequency rating of the circuit breaker should agree with the nominal frequency of the power system. Standard G-E circuit breakers are rated for fre-
quencies of 60-25 cycles or d.c. Special recommendations should be requested from the Company for applications of circuit breakers to circuits of higher frequencies or circuits on which higher order harmonics are present, such as capacitors, rectifiers, or induction furnaces.

## 3. Ambient Temperatura

General Electric power circuit breakers are designed in accordance with NEMA Standards to carry rated current without exceeding allowable temperature rises when operated in an ambient temperature of 40 C . When the circuit breakers are mounted in enclosures the average ambient temperature inside the enclosure may be not more than 15 degrees higher than the standard ambient temperature of 40 C outside the enclosure. Applications requiring operation in ambient temperatures in excess of 40 C should be referred to the Company with complete information relative to temperature and ventilation conditions at the proposed site of installation.

## 6. Frequency of Operation

Power circuit breakers may be applied to most of the more commonly encountered power circuits such as generator, transformer, and feeder circuits without normally questioning the frequency of operation. Where repetitive operations are involved such as on circuits feeding industrial process motors, furnaces, etc., the application should be considered in light of the published information on page 23, Table XII.

## 7. Altilude

In the rarefied air above 3300 -ft altitude, both insulation and current-carrying capacity are affected, and for such applications the published ratings of power circuit breakers are modified by multiplying the ratings by the following factors established in ASA, AIEE, and NEMA standards:

| Atilifude la Fael | Cerreclion Pactors |  |
| :---: | :---: | :---: |
|  | Voliase | Curfant |
| - 3100 |  | 100 |
| 3300 4000 | 1.00 0.98 | 0.096 |
| 5000 | 0.95 | 0.99 |
| 10000 | 0.80 | 0.96 |

## 0. Local Eloctrical Codos

All G-E standard power circuit breakers are built to conform to applicable provisions of the ASA and NEMA standards. Requirements for breakers having special
characteristics in order to meet certain city, state, or other electrical codes should be referred to the Company.

## 9. Unusual Service Conditions

It is recommended that, wherever possible, steps should be taken at the site of installation to control unusual service conditions so that standard equipment can be installed. When such steps are not practical or standard equipments such as dust-tight, watertight, dripproof, or explosion-proof enclosures adaptable to the unusual condition are not listed, recommendations for special features necessary to adapt the equipment to the unusual conditions should be obtained from the Company in advance of placing the order. Among such unusual conditions are the following:

1. Exposure to damaging fumes or vapor.
2. Exposure to steam.
3. Exposure to salt air.
4. Exposure to oil vapors.
5. Exposure to hot and humid climate.
6. Exposure to dust, abrasive dus ${ }^{*}$ magnetic dust, or metallic dust.
7. Exposure to dripping water $u$. falling dirt.
8. Exposure to explosive mixtures of dust or gases.
9. Exposure to abnormal vibration, shock, or tilting.
10. Seasonal or infrequent use.
11. Unusual insulation requirements.
12. Exposure to extreme temperatures or sudden changes in temperature.
13. Unusual space limitations affecting use or installation.
14. Unusual configuration of enclosing rooms causing hot air pockets, rooms not having normal ventilation, or rooms containing large amounts of magnetic material.
15. Unusual operating duty, frequency of operation, or difficulty of maintenance.
16. Unusual or special operating requirements.

## 10. Special Duly Cycios

Breakers are used occasionally on special duty cycies, including currents above the normal rating for short periods, followed by rest periods, etc. Under these conditions it may be necessary to integrate the combined effect of the various. load currents at different parts of the dul cycle as far as heating effect is concerne It is seldom necessary to use a breaker of

# Application Informaxion 

rating corresponding to the highest current of the duty cycle. Recommendations for such applications should be requested from the Company.

## interrupting ratings

Modern design circuit interrupters such as are used on General Electric lowvoltage power circuit breakers have interrupting capabilities which are a function of voltage. This is reflected in the differences in interrupting ratings assigned to circuit breakers with instantaneous trip deviees at the three voltage levels of 600 . 480 , and 240 volts. Table I indicates these ratings, as well as the interrupting ratings without instantaneous trips, which are not a function of voltage. The latter ratings are to be used when breakers are applied without instantaneous trips, as they would be when equipped with selective trips or when direct-acting overcurrent trips are omitted-for example, when separate overcurrent relays are used.
A The rated interrupting current is the maximum current at the rated voltage which a circuit breaker is required to interrupt under the operating duty speci1 and with a normal frequency recovery دltage not less than the rated voltage.
Interrupting ratings of General Electric power circuit breakers are based on the test procedure, applicable operating duty (duty cycle), performance and conditions given in paragraphs SG3-3.08 and SG33.19 of the NEMA Standard for lowvoltage power circuit breakers. The latter paragraph reads as follows.

## determination of interrupting RATING

The test procedure and characteristics of the test circuil to be used for verifying the ability of the circuit breaker to interrupt the total rms amperes given by the interrupfing rating for the applicable operating duly shall be as follows:
A. RMS Tolal Amperes

The rms tolal amperes shall be determined by measuring the current flow as follows:

The circuit breaker shall be short circuited or omilted.
The symmetrical current shall be measured at an instant one-half cycle ofter the short circuit occurs and shall be calculated in accordance wilh the Amerienn Stondard Methods for Determining

RMS Vaiue of a Sinusoidal Current sue and a Normal-Fiequency Recovery Vollage', C37.5-1953. The degree of asymmetry for the asymmetrical tests shall be determined on the basis of a test
circuil with on $X / R$ ratio of not less than 6.6.

- Copies are available from the American Standards Association, Inc., 70 East 45th Street, New York 17, N. Y.
The circuit breaker shall be able to interrupl the rms symmetrical current rating as well as every degree of asymmetry up to an $X / R$ ratio of not less than 6.6. Verification of breaker interruption rating shall be made by:

1. A single-phase test with line-fo-line vollage across the circuil-breaker pole with the alternating-current component of current equal to or greater than 86.7 percent of the symmetrical rating, and
2. A single-phase test with maximum degree of asymmetry associated with par. 1 and with line-to-line vollage across the breaker pole, and
3. A three-phase test at rated voltage with the 3 -phase average asymmetrical current not less than 1.17 times the symmetrical rating.
The transien! characteristics of the testing circuit shall be such that the 3phase average allernating-current component of current at the end of 30 cycles (based on a 60 -cycle frequency) shall be not less than 85 percent of the average alternating-currenl component of current at the end of the first half-cycle.
4. Oparating Duty for Determining the Interrupling Rating (Duty Cycie)
The operating duty for defermining the interrupting reling of circuit breakers with instantaneous overcurrent trip devices for faull currents shall consist of an opening operation, followed after a 15 second interval by a close-open operalion.

The operating duty for determining the interrupting raling of circuil breakers with delayed overcurrent trip devices for faull currents shall consist of an opening operation, followed after a 15 -second interval by a close-open operation, the tripping being delayed by the associaled tripping devices.

## C. Performance

Al the end of any performance at or within its interrupting raling, the circuit breaker shall be in the following condilion:

1. Mechanical-The circuil breaker shall be in substantially the same mechanical condilion as at the beginning.
2. Electrical-The circuil breaker shall be cajable of withstonding rated voltage in the open position and of carrying rated continuous
current at rated vollage for a limited fime but not necessarily withoul exceeding the rated temperature rise.
After a performance at or near its interrupting rating, it is not to be inferred that the circuit breaker can again meet its interrupting rating without being inspected and, if necessary, repaired.

## D. Condilions

The conditions which are assumed in assigning an interrupling raling to a circuit breaker include the stored electrostatic and magnetic energy of the system, the re-establishment of an are under (ronsient voltage condilions, the decrement of the system and other variable conditions. These conditions are considered as not differing widely in average systems and are to be taken info account in the factor of safely employed in the rating of the circuit breaker.

## SHORT-TIME RATINGS

The short-time rating of a circuit breaker must be taken into account when the breaker is applied without directacting overcurrent trips.

The rated short-time current is the maximum current which a circuit breaker will carry without injury for specified short-time intervals. The rating recognizes the limitations imposed by both thermal and electromagnetic effects.

Short-time ratings of General Electric air circuit breakers are based on the test procedure, operating duty (duty cycle), performance, and conditions given in paragraphs SG3-3.10 and SG3-3.16 of the NEMA Standard for low-voltage power circuit breakers. This paragraph reads as follows:

## DETERMINATION OF SHORT-TIME RATING

The test procedure for determining the short-time current rating shall be as follows:

## A. RMS Tolal Amperes

Determined same as for interrupting rating.

## B. Oparating Duly (Standerd Duty Cycle)

The short-time duty cycle shall consist of maintaining rated short-time current for two periods of one-half second each, with a 15 -second interval of zero current between the one-half second periods.

## C. Performanca

At the end of any performance at or within its short-time rating, the circuit breaker shall be capabie of carrying rated continuous current without exceeding the rated temperature rise of its various parts and shall be capable of meeting its interrupting rating.

## NUMBER OF POLES AND TRIPS REQUIRED

The following data gives the correct power circuit breaker for protection of the more commonly used circuits.


Fig. 6. Singionphase, twowire, ungrounded
One 2-pole breaker with two overcurrent trips

fig. 10. singicophase, twowirn, tagrounded
One 2-pole breaker with two overcurrent trips

Fig. 14: Three-phase, thres-wire, grounded
One 3-pole breaker with three overcurrent trips
 -


Fig. 7. Singlo-phase, two. wire, grounded
Y One 1-pole breaker with overcurrent trip


Fig. 8. singlo-phase, twewift, grounded
One 2-pole breaker with two overcurrent trips


Fig. 12. SIngls-phato, three. wIrn, grounded
TOne 2-pole breaker with two overcurrent trips (one in each conductor, except neutral)


Fig. 9. Singlo-phase, two. wire, grounded
One 2-pole breaker with two overcurrent trips


Fis. 13. Thres-phase,
threo-wlro, ungrounded
One 3-pole breaker
Ohreo-wlre, ungrounded
One 3-pole breaker with three overcurrent trips


Pig. 11. Single-phase, threawirt, Engrounded
One 3-pole breaker with three overcurrent trips


Fig. 15. Threo-phase, Thret-wire, grounded
One 2-pole breaker with two overcurrent trips (one in each ungrounded conductor)


Fig. 16. Threa-phose,
four-wire, greunted
I One 3-pole breaker with three overcurrent trips


Fis. 17. Three-phaes, eaternaraler
One 3-pole breaker with three overcurrent trips. $\ddagger$ See note below.

[^4]does not interrupt the grounded conductor, other means shall be provided in the service cabinet or on the switchboard for discon. necting the grounded conductor from the interior wiring."
: Provides overcurrent and short-eircuit
protection only. Switchgear relays can be furnished to give reverse power, undervoltage, phase sequence, ground-current protection, etc. Such application should be referred to the Company.

Four basic circuits for power distribution have evolved from the many possible types and variations of substations and circuit arrangements.

The load center philosophy of power distribution that is, the use of substations located in or near the load area -is basic to all of these arrangements providing good design at minimum
cost. Power is supplied to the load center unit substations at the primary voltage level, stepped down to utilization voltage, and distributed to utilization devices on selatively short, low-voltage feeders. Selective co-ordination of protective devices is recommended where processes require continuous power. G.E load centers can be provided for any of these arrangements. Combinations of the various systems may be utilized.


SIMPLE RADIAL SYSTEM
Simple radial syslem is mast econamical loodconter distribution system, has sufficient reliobility for most power service roquiremants. There is only ene primary faeder and one transformer through which a secandory bus is served. Loss of source power means loss of the entire substation

## SECONDARY-SELECTIVE SYSTEM

Secondory selective systam is in effect two radial syslems with a secondary tie between them. Eilher source of power may be energized and power can be made availeble an both secondary buses by opening the proper substation main breaker and ciosing the lie breaker. This system colls from 251050 percent moro than the radial system.
unst the trouble has been cleared.


SPOT-NETWORK SYSTEM

Spot network system parollels the transfarmer secondarist to provide continuous service for an oulage of cne primary circuit. failure of trensformes or primary fecder results in oulomatic removal of the fauliy equipment. This syitem costs frem 20 to 50 percent more than the radial system.

PRIMARY - SELECTIVE SYSTEM
Primery selestive system provides on aliernole supply to the primary of each Iransformer. If a primery fault occurs, the ossocioted primary breoker openi ond interrupts service to half of the lead area. The de-energized transformers ... out of service . . . ore manually switched to the other feeder. Cost is 15 to 40 percent more then redial systems.

PBA97584

## TRANSFORMER SECONDARY BREAKER

A transformer secondary breaker is recommended for one or more of the following purposes:

1. To provide a fast method of removing all load from the transformer. Article $130-70$ (g) of the NEC specifies that the disconnecting means for service con.luctors may consist of not more than six riscuit breakers:
2. To provide required transformer secondary overcurrent protection in accordance with NEC Article 450-3;
3. To provide protection for faults on the main bus;
4. To provide a disconnect for maintenance purposes:
5. To provide for throwover, automatic or manual, to an alternate source in the case of failure of a primary feeder or transformer (Secondary selective circuit arrangement):
6. To back-up lower sated cascaded feeder breakers;
7. To simplify key interlocking schemes when the number of feeder breakers exceeds the practical limit.

Selection of the rating of the transformer secondary breaker should be based on the fact that forced cooling may be applied at some future time to increase the transformer rating as much as 33 percent.

## general purpose feeders

For a-c circuits, there should be one breaker pole with overcurrent trip in each ungrounded conductor. For polyphase circuits, it is essential that all phases be disconnected simultaneously; therefore multipole breakers are used.

The dual-magnetic trip (Long timeinstantaneous) with a $1 B$ long time-delay characteristic is commonly used for general purpose a-c feeders. Instantaneous trip settings should be determined on the basis of the type of load and the type of protection desired. For instance, where arcing fault protection is a consideration, as low a setting as is consistent with the inrush characteristic of the load should be used.

## A-C MOTOR STARTING AND FEEDER BREAKERS

Low-voltage power circuit breakers may be applied in motor branch circuits. They are particularly suited both economically and from good 3ystem design viewpoint for motors rated above 100 hp .
A motor branch circuit is a circuit including a single motor and a single breaker. A motor feeder circuit is a circuit
including a breaker which supplies more than one motor branch circuit. Circuit breakers may also be used for motor. running overcurrent protection and as the motor controller for starting. The elements of a motor branch circuit are shown below.


Flg. 18. Elements of a motor-branch elrculp

A circuit breaker with its accessories will provide some or all of the elements of a motor circuit shown in NEC 430-1, either in itself or in combination with a
motor controller. Because of the high inrush current associated with motor starting, only breakers with either an electrically or manually operated storedenergy mechanism should be used.

In single-motor circuits where the breaker is providing either branch circuit or motor-sunning overcurrent protection the breaker and its trip devices must have the following characteristics:

1. Continuous current-carrying capf, city at least 115 per cent of motor fullload current. (Enclosed motors may have other service factors.) See table below for the selection of the continuous current rating.
2. Interrupting capacity sufficient for available short-circuit current.
3. Sufficient time delay in the overload trip to ride over the starting current of the motor.

The breaker ratings indicated in the table below, when equipped with a 1B-3 trip characteristic, are satisfactory for starting normal motors and their loads with locked rotor currents up to 6 times motor full-load current.
4. Instantaneous tripping for protection of the motor and its circuit, set low enough to protect, and not so low that tripping occurs on transient inrush. A

TABLE $\mathrm{Il}^{\text {-Applicalion of Powar Circuif Breakers to Full-voltage Starting }}$ and Running Duty of 3-phase, 60 -cycle, 40 C Rise Induction Motors


[^5]A-C POWER SYSTEM APPLICATION

zetting of 2 times the locked rotor current is considesed adequate for most condi. tions.

## NUMBER OF OPERATIONS

In applications where the AK lowvoltage power circuit is performing the function of motor controller as well as motor branch circuit protection, the number of operations which the breaker can perform without maintenance should be considered. Based on closing currents up to $600 \%$ of the frame size rating and opening currents equal to the frame size rating, AK breakers can be expected to perform at least the number of operations without inspection and servicing, indicated in Table III.

Frequently, a particular frame size of breaker will be used to control a motor considerably smaller in size than those shown under the column headed "Maximum HP at 440 Volts." In these cases the number of operations which the breaker can suecessfully perform between inspection and possible servicing will increase appreciably.

ERENT MOTOR PROTECTION$\therefore$ THERMO-TECTOR ${ }^{(1)}$
Additional protection for the motor may be obtained through the use of separate thermal relays or Thermo-tectors built into G-E motors. Either of these protective devices can be used to trip the breaker in response to abnormal conditions.

A Thermo-tector device is a specially designed heat-sensing switch embedded in the stator windings of some G-E motors. It is responsive to rate-of-rise of temperature as well as actual temperature. It will protect for locked rotor, overload, highambient, loss of ventilation, and single phase operating conditions; in fact, any short- or long-time abnormal condition that can raise the temperature of a winding to a dangerous degree.

Each Thermo-tector (there are at least three) has a single normally closed contact (circuit opening on rising temperature) that must be connected in the coil circuit of the motor controller. When
using Type AK Power Circuit Break. efs as motor controllefs, the control will be arranged so that the Thermo-tector trips the circuit breaker by opening the undervoltage device or by dropping out an auxiliary relay to trip the breaker by means of the shunt trip device.

The branch circuit breaker for motors with inherent thermal protection should be provided with the usual instantaneous overcurrent trips set at twice locked rotor current and with long-time overcurrent trips for cable and for back-up protection and with sufficient delay to allow motor to start. Since the breaker long-time trip element is not being depended upon for motor running overcurrent, or stalled rotor protection, the long-time trips can be set somewhat higher than usual for motor circuits, usually $\mathbf{1 5 0 - 2 0 0}$ percent of motor sating depending on the cable size.

## GENERATOR CIRCUITS

The power circuit breaker for a generator should be fast closing for synchronizing and should have a continuous current rating of about 125 percent of the maximum current rating of the generator. Each pole of the breaker should be provided with overcurrent trip devices having the following characteristics:

1. Long time, set for about $\mathbf{1 2 5}$ percent of the generator continuous current rating and for maximum time, for continued moderate overcurrent protection of the generator.
2. Short time, set at about 2.5 times generator continuoilis current rating, or as required for selectivity with feeder breakers, for protection against bus faults.
3. Instantaneous, set at $\mathbf{1 0}$ to $\mathbf{1 2}$ times generator continuous current rating, for generator circuit protection on internal faults fed from other sources in system.

The generator breaker must have an interrupting rating equal to or greater than the available short-circuit current at the breaker location from all power sources on the system, including motors. The initial value of short-circuit current calculated from the generator sub-transient reactance should be used in deter-
mining the interrupting rating required. This current may be 7 to 15 times the continuous current rating of the generator.

The short-circuit current from a generator is the large value determined by the sub-transient reactance. This current decays with time until it reaches a lower sustained value that is dependent on machine synchronous reactance and excitation system characteristics. The actual sustained value may be any value between substantially zero and about three times generator continuous current rating.
The plotted values of generator output current and time under short-circuit conditions is called the decrement curve. It determines the settings and time-current characteristics required on the generator and feeder breakers in a selective system. The decrement curve of a particular generator may not be available, but the two most important points, the initial value and the sustained value of short-circuit current, can be obtained from the manufacturer.

Self-excited generators (generator field or exciter field energized from generator voltage) require special consideration because of the rapid decrement of shortcircuit current to zero. Proper tripping of the generator breaker, and selectivity between the generator and feeder breakers, can be obtained with such generators only if provision is made in the excitation system for forcing the generator to sustain short-circuit current of sufficient magnitude and duration to operate the overcurrent trip devices.
For better protection of the generator, induction type overcurrent relays with voltage restraint, type IJCV. may be used to provide tripping through a shunt trip device on the breaker. D-e tripping power, or capacitor trip, is required for reliable trip under short-circuit conditions. Suitable current and potential transformers and a lockout relay are required in addition to the IJCV relays.

When generators are operated in paraltel with other sources, a reverse power relay should be included for anti-motoring protection. A shunt trip device, which may be a-c operated, is required on the breaker.

TABLE III—AK Breakers for Molor-sfarting Applications


[^6]
## A-C POWER SYSTEM APPLICATION

## resistance welding MACHINE CIRCUITS

Certain forms of low voltage power circuit breakers are particularly adaptable to and recommended for the protection of circuits which feed welding machines for spot, seam, projection, and flash welding.

Welding-type breakers are equipped with instantaneous trips and will promptly and safely interrupt overcurrents or short circuits and permit immediate restoration of service.

Breakers with time delay overcurrent trip devices are not recommended for use in circuits feeding welding machines because the relatively high intermittent welding currents sometimes cause undue wear in trip devices, resulting in calibration changes and nuisance tripping. Where overload protection is required, thermal overload relays and current transformers give better results.

The breaker which should be selected is one whose maximum load curve is just above the greatest load (during-weld current or kva) at a duty-cycle value for the welding application. After this has been selected, the maximum available RMS Symmetrical short current must be determined to complete the breaker application.

## Examples for Selecting a Breaker

 WHEN DURING.VELD KVA is KNOWN(a) During-weld kva $=600$ $\begin{array}{ll}\text { Duty cycle } & =0.15 \\ \text { Voltage } & =440\end{array}$

Referring to Chart II (kva at 440 volts) on page 10 , the point of 600 during-weld kva and 0.15 duty cycle is below the maximum loading curve of the AK25Y1 (or AK-50Y3). This breaker is suitable for the conditions given.
When during-weld current is known
(b) During-weld current $=1360$ amp Duty cycle $=0.15$
Referring to Chart IV on page 10, we find that the point of 1360 amperes during-weld current and 0.15 duty cycle is below the maximum loading curve of the AK-25Y1 (or AK-50Y3), which is the breaker to select.

## table IV

The following tables list the maximum during-weld ampere and kva values, at various duty cycles, for which the breakers can be used. The values are obtained from the curves in the charts on page 10.


AK-15YI and AK-25Y2 Breakers

| 0.03 | 1530 | 337 | 674 | 841 |
| :---: | :---: | :---: | :---: | :---: |
| 04 | 1925 | 292 | 584 | 729 |
| .05 | 1185 | 261 | 522 | 652 |
| 0. | 1080 | 238 | 475 | 594 |
| 06 | 1009 | 220 | 460 | 550 |
| 08 | 936 | 206 | 412 | 516 |


| $\begin{aligned} & \text { Duyy } \\ & \text { Cyelo } \end{aligned}$ | During. Anp Rns | During.wold Kra |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | 220 |  | S50 |
| AK-15Y1 and AK-25Y2 Breakers (Cont.) |  |  |  |  |
| .09 .10 | 884 990 998 | (194, | 388 378 262 | 486 <br> 461 <br> 327 <br> 28 |
| .30 .30 .50 | 201 219 375 342 | 108 9.9 98 75 | 退 315 | 288 231 2308 180 |

AK-25Y1 and AK-50Y3 Breakers

\begin{tabular}{|c|c|c|c|c|}
\hline \[
\begin{gathered}
0.03 \\
0.0 \\
\text { out } \\
\hline 00
\end{gathered}
\] \& \begin{tabular}{l}
3040 \\
3500 \\
3150 \\
\hline 100
\end{tabular} \& \begin{tabular}{l}
690 \\
\\
\hline 700 \\
680
\end{tabular} \& 1780
1540
1374
1258 \& 3225
1925
1722 \\
\hline .0\% \& 2850
2750 \& 629
980
508 \& 1238 \& \({ }_{\substack{1574 \\ 1533}}\) \\
\hline . 0 \& 2610 \& 344 \& 1056 \& 1360 \\
\hline . 10 \& \begin{tabular}{l}
3330 \\
2215 \\
\hline 1515
\end{tabular} \& \begin{tabular}{l}
513 \\
487 \\
\hline 185
\end{tabular} \& 1025 \& 1282 \\
\hline 20 \& 1566 \& 345 \& 689 \& 861 \\
\hline . 40 \& 1278 \& 281
2814
218 \& 568
487
487 \& 703

609
965 <br>
\hline ${ }_{50}$ \& 903 \& 199 \& $3{ }^{3}$ \& 497 <br>
\hline
\end{tabular}

AK-50Y2 Breaker

| $\begin{gathered} 0.03 \\ .04 \\ .05 \end{gathered}$ | $\begin{array}{r} 10680 \\ 9250 \\ 8280 \end{array}$ | 7350 3040 1820 | 4100 4080 3040 | 3970 3100 1590 |
| :---: | :---: | :---: | :---: | :---: |
| . 06 | 7530 | 1660 | 3320 | 4150 |
| . 07 | 6990 | 1540 | 3080 | 3840 |
| . 08 | 8540 | 1440 | 2480 | 3600 |
| . 09 | 8170 | 1300 | 2720 | 3390 |
| . 10 | 3860 | 1290 | 2580 | 5220 |
| .20 | 4140 | 810 | 1820 | 2280 |
| 30 | 3380 | 744 | 14 ¢f | 1860 |
| .00 |  |  | 1280 | 1610 |
| . 50 | 2620 | 576 | 1152 | 1440 |
| 40 | 2390 | 526 | 1052 | 1315 |

TABLE V-Available Resistance Welding Breakers


Dage 12

MAXIMUM LOADING CURVES FOR WELDING-TYPE BREAKERS

Chart I-For 220 Volts


Fls. 19

Chart ill-For 550 Volls


Fig. 21

Chart II-For 440 Volis


Fle. 20


Fig. 22

The duly cycte is the fraction of time that current fiows in any one minute.

## GENERAL PURPOSE FEEDERS

For a-e circuits, there should be one breaker pole with overcurrent trip in each ungrounded conductor. For poly. phase circuits, it is essential that all phases be disconnected simultaneously; therefore muitipole breakers are used.

The dual-magnetic trip (Long timeinstantaneous) with a 18 long time-delay characteristic is commonly used for general purpose a-c feeders. Instantaneous trip settings should be determined on the basis of the type of load and the type of protection desired. For instance, where arcing fault protection is a consideration, as low a setting as is consistent with the inrush characteristic of the load should be used.

## SYSTEM APPLICATION OF BREAKER

Systom Application of Breakers-A complete application study considers the breaker in relation to the equipment which it protects, as well as in its relation to other breakers in the system. Load Center Unit Substations are perhaps the principal method of using breakers in which the functioning of one breaker with respect to another must be taken into consideration.

More than just trip characteristics must be taken into account - the relationship of interrupting ratings to avail. able short-circuit current must also be carefully considered.

Basically there are two types of systems of breaker application:

1. Fully rated breakers are applied within their interrupting ratings:
a. with instantaneous trips-tripping is instantaneous for short circuits.
b. with selective trips-tripping is intentionally delayed up to. interrupting rating of breaker.
2. Cascade breakers are applied above their interrupting rating. In accordance with NEMA Standards they must be backed-up with a fully rated breaker-also must be electrically operated from a remote position.
FULIY RATED SYSTEM—The fully rated system uses main and feeder breakers which are fully rated, that is, they have interrupting ratings equal to or greater
than the available short circuit current. These breakers are equipped with gen-eral-purpose trip devices combining long time delay and instantaneous trip characteristics. No intentional time delay is introduced in the tripping characteristics at short circuit current levels to achieve selective tripping between the main and feeder breakers and/or the feeder breaker and branch circuit protective devices.

The current level of a fault on a feeder circuit depends on the location of the fault along the feeder conductors and may be as high as that available at the load terminals at the feeder breaker.

Due to the difference in current satings between the main and feeder breakers and therefore the amount of time delay for a given level of fault current, some selectivity might exist depending on the magnitude of the fault current and the settings of the instantaneous trips.

In order for selectivity to exist for all possible levels of fault current on a feeder circuit, it is necessary that the main breaker be equipped with selective trips, that is, combinations of long time and short time delay without instantaneous trips.

SELECTIVE SYSTEM-The selective system is a term used to identify a series of protective devices, i.e. relays, breakers, and fuses, the time current characteristics of which have been selectively coordinated, so that under fault conditions power is removed only. from that portion of the system on which the fault exists. The first place on a low. voltage distribution system that such coordination is usually established is within a unit substation between the main secondary and the fecder breakers. Such a substation is sometimes referred to as a "selective substation." This type of selective coordination is not to be confused with the "primary selective" or "secondary selective" load center distribution svstems.

As manufacturing processes become more critical and the need for con-
tinuity of service increases it is usually found that the "selective coordination" of protection devices or the selective system is extended beyond the load center to include motor control centers, panelboards, and the like.

In considering a load center unit substation and the low voltage distribution circuits which are fed from it, two circuit areas become apparent:

1. The ares that takes in the main breaker and any one feeder breaker. The impedance between these two protective deviees is so small, that faults at the load terminals of the feeder breaker will be for all practical purposes the same magnitude as faults at the load terminals of the main breaker. For selectivity to exist between these two breakers, at all levels of short circuit current up to the maximum available, the main breaker must be equipped with long-time and short-time delay trips.
2. The area which encompasses th feeder breaker, the feeder cable and the next protective device which is frequently a molded case breaker, part of a combination starter in a grouped motor control equipment. In this area which overlaps the first area to the extent of the feeder breaker, appreciable impedance may exist between the feeder breaker and the fautt at the load terminals of the combination starter. This means that fault current at the load terminals of the starter may be appreciably less than fault current which would exist for a fault at the load terminals of the feeder breaker. Even for short eable runs ( 50 feet) this can be true depending on the size of the cable.

The second area permits the use of the feeder breaker equipped with isng-and short-time delay trips having an additional instantaneous element with its setting equal to or greater than the available short circuit current at the motor control center bus.



ZONE SELECTIVE SYSTEM


STANDARD SELECTIVE SYSTER

Flg. 23

The instantaneous element provides short-circuit protection for the feeder cable and, where needed, backup for the molded case breakers in the starters.

Tests indicate that, for the limit of application of 100 ampere frame molded case breakers in starters of General Electric motor control centers, selcetivity is obtained with an instantancous trip setting of 12,000 ampercs on the AK feeder breaker. For faults beyond the starters, the short-circuit current will be below the instantaneous trip setting and in the region of current that would cause
the feeder breaker to trip on short-time delay. The AK breaker will therefore be selective with molded case breakers.

The requirements for zone selective feeders established in this manner differ from the requirements for the selective main breaker, AK breakers using a combination of long time delay short time delay, and instantancous trip characteristics can be applied up to the interrupting rating with instantaneous trips.

The practice of providing selective tripping for faults beyond the second
protective device and instantaneous trip. ping for faults between devices (cable circuits) gives rise to the term "zone selective system."

The requirements for applying power circuit breakers to obtain selective tripping are given in the following paragraphs. The discussion centers around Fig. 23, but the principles are basic to any application.

1. All circuit breakers, both main and feeder, must have interrupting ratings at least equal to the maximum available short-circuit current. The interrupting rating is a function of the voltage and the presence or absence of an instantaneous trip device. A suitable selection can be made from Tables I or VI.
2. Breaker $\mathbf{A}$ is a typical main breaker, without an instantaneous trip, and must be applied on the basis of ratings listed for breakers without instantaneous trips.
3. Feeder breaker $C$, which is selective with breakers D in the motor control center, should be selected on the same basis as A.
4. Feeder breaker $B$ is equipped with instantaneous trips as well as with long time and short time delay trips, following the concept of a zoneselective system. This method of application may permit the use of a smaller frame size circuit breaker, as in the example.
5. Feeder breaker E, which is not required to be selective with a downstream protective device, is equipped with an instantaneous trip and applied on that basis.
6. The overcurrent tripping devices of the main breaker A must be so coordinated with the feeder breakers, that all feeder faults are cleared by the feeder breaker involved. The main breaker will trip only in the case of bus faults or the failure of the feeder breaker to trip. A feeder fault is, therefore, always cleared without interruption of service on other feeders.
7. Proper coordinating steps should be taken in fuse and relay application on the high-voltage side of the transformer when coordination with the rest of the system is desired.

# Application Informarion <br> A-C POWER SYSTEM APPLICATION 

## EFFECT OF MOTOR CONTRIBU. TION

When short circuits occur, motors (both synchronous and induction) in operation from the same source become generators for the time being and add their contributions to the short-circuit current. Where aceurate data are not available it is customary to assume, for 240-, 480-, and 600 -volt systems, that the motor load is equal to the kva rating of the souree, and that the characteristics of the motors are such that the motor short-circuit contribution will be four times the normal current. In 208 or lower voltage systems, lighting, heating, welding, and other classes of nonregenerative load are likely to be present and hence, for such systems, it is customary to assume the motor load to be 50 percent of the total available power and the motor short-circuit contribution will be two times the normal current.
Short-circuit contributions from induction motors are very short-lived and by the time the breakers have opened they will have decreased to very low values. Synchronous motors, however, maintain their voltage for longer times and consequently they impose a heavier opening duty on the breakers. This may affect the satisfactory operation of the " $C$ " breakers in the cascade (Fig. 24). Accordingly it has been made a condition of cascading that if more than 25 percent of the motor load is synchronous the problem should be referred to the Company for recommendations. The ratings in Tables VII, VIII, IX, and $X$ are based on these considerations.

## CASCADE SYSTEMS

Low-voltage power circuit breakers may be applied on circuits where the available fault current exceeds the interrupting rating of the breaker but these conditions must be fulfilled:

1. Provided there is a fully rated breaker backing up the breaker so applied. This is illustrated in Fig. 24 where "M" is the fully rated main breaker and " $C$ " is the cascaded feeder breaker applied above its interrupting rating.
2. The feeder breaker " C " must have instantaneous trips. NEMA Standards recommend that these breakers be electrically operated.
3. The back-up breaker " $M$ " must have its instantaneous trip set in accord-
ance with NEMA Standards, so that it will trip when the fault current through the feeder breaker reaches $\mathbf{8 0 \%}$ of the feeder breaker interrupting rating. The difference in fault currents between breakers " $M$ " and " $C$ " due to motor contributions must be taken into account in calculating the maximum allowable instantancous trip setting on breaker "M."
Under the cascade system of application, a short circuit on a feeder breaker will be very likely to trip the main breaker and thus remove power from all feeder breakers. Hercin lies the advantages of the fully rated system with selective trips on the main breaker. Since the feeder breakers of a fully rated system are able to open on a short circuit without assistance from the main breaker, selective trips delay tripping of the main breaker and permit it to ride over a fault on a fecder. In case of a bus fault between the main and feeder breakers or some unusual condition which prevents the feeder from clearing, the main breaker will open and remove the short circuit.

NEMA Standards state the operation


Flg. 24
of breakers in excess of their interrupting capacity (as in cascade) is limited to one operation, after which inspection, maintenance, and repair may be required.

## EFFECT OF TWO SOURCES

Where two or more power sources are involved, as in Fig. 25, the total shortcircuit current to be considered in the determination of the interrupting rating of breakers $\mathbf{F}$ can be taken as the sum of the currents from all sources that are added together as if coming from one source.

The continuous current requirements for each breaker $M$ usually result in these breakers having adequate interrupting ratings for any faults. The M breakers must be adjusted so that all trip instantaneously before the fault current through the $\mathbf{F}$ breakers, from all sources, exceeds 80 percent of the interrupting rating of $F$. in order to conform to this rule, all
sources of power which feed current through breaker $\mathbf{F}$ must be considered.


Fig. 25
This means, for Fig. 25, for example, that the current through $F$, to a fault in the left-hand feeder, is supplied not only from the two sources through breakers $M$ but also from the motors operating in the two feeder circuits at the right of the feeder under consideration. The settings of the breakers $M$ must take the motor contributions into account and be of proportional value. This can best be illustrated by an example, as follows:
EXAMPLE: Assume that each source in Fig. 25 is a 1000 -kva, 480 -volt trans. former capable of supplying an rms symmetrical short-circuit current of $\mathbf{2 0 , 5 0 0}$ amperes, and that the motor load on each feeder will contribute an rms symmetrical short-circuit current of 4800 amperes. The total short-circuit current in the left-hand feeder through breaker $F$ then will be:
$2 \times 20,500+2 \times 4800=50,600 \mathrm{amp}$
Each of the breakers $M$ must be of 1600 -ampere continuous current rating, this inherently provides breakers of 42,000-ampere interrupting rating, which is more than ample for the 20,500. ampere requirement. At $F$ with a total short-circuit current of 50,600 amperes available, it is necessary to choose a breaker which has a minimum interrupting rating of half of this amount, or $\mathbf{2 5 , 3 0 0}$ amperes, which means an AK-1-25 breaker.
Of the 50,600 -ampere total available short-circuit current for a feeder fault, 20,500 amperes is contributed by each transformer. Since the breakers M should trip when the current passing through breaker $\mathbf{F}$ is 80 percent of its interrupting rating at 480 volts, or
$30,000 \times 80 \%=24,000 \mathrm{amp}$
the trip setting of breakers $M$ will be

$$
20,500 \times \frac{24,000}{50,600}=9800 \mathrm{amp}
$$

The application tables on the following pages list the proper low voltage power circuit breakers for load center applications. The power circuit breakers have been co-ordinated with transformer and system capacities-electrically, thermally, and mechanically.

BASIS FOR APPLICATION TABLES Application tables are based on the following:

1. A three-phase bolted fault at the low voltage terminals of the substation:
2. Transformer impedances listed in table;
3. Only source of power to the secondary is the substation transformer:
4. Total connected motor kva does not exceed 50 percent of transformer rating on 208Y/120-volt and 100 percent of transformer rating on 240-, 480-, and 600 volt systems;
5. The motor contribution is taken as $2: 0$ times the normal current of the transformer at $208 \mathrm{Y} / 120$ volts and 4.0 times normal at 240, 480, and 600 volts;

Coil sizes are listed for a circuit er applied at its maximum inter-1-n.ang rating at the specified circuit voltage. Smaller coils may be used if available short-circuit current is less;
7. Tabulated values of short circuit current are in terms of RMS symmetrical amperes per NEMA Standard SG-3.

## SUBSTATION ELECTRICAL ARRANGEMENT

Substations are available in a selective. fully rated, or cascaded arrangement. Care should be taken to specify the arrangement that provides the balance of selectivity and protection required by the power system.

## SELECTIVELY CO-ORDINATED SUBSTATIONS

A selectively coordinated substation uses fully sated breakers with long-time and short-time trip characteristics (LS) to delay the opening of the main circuit breaker until the faulted feeder has had an opportunity to clear. This provides service continuity for all but the faulted circuit.

Selectivity may be carried a step further in the substation by specifying selective feeder circuit breakers that incorporate long-time and short-time char--istics (LS) to allow downstream deo clear faults within their area.
. efinement of the selective feeder incorporates the long-time, short-time with high-set instantaneous characteristics (LSI) to provide selectivity without sacrificing instantaneous fault protection. Further, this combination of trip characteristics permits application of the breaker up to its interruptine rating with

Application Information

## A-C POWER SYSTEM APPLICATION

TABLE VI—Applicalion Range-AK Circuit Breakers

| O.E <br> Sreather Trpe | Voltoge Mallag 60 Cyetos A.C. | Palerrupilng RalingIn Amparet,IMS Symmetrieal |  | Overcurreal Trlp Device Raling-Amperas |  |  |  |  | short-1line Rallng Ampere: TMS Symmotilizal | Shert Clicusf timit for 2-step Cose cade Opara. flon Amparel DMS Symmetricel |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | Min. with <br> Inticn. toneoun Charestoristie | Min. wilh $2 C$ 5hoptfime Charasterbalte | Mln. with 18 Sharl. than Charoeferistic | Min. <br> with 2A Shert. Hinto Characferisilis | Max. <br> Breoker <br> Rating |  |  |
|  |  | With fints. Trips | Whhest Inst, Trips |  |  |  |  |  |  |  |
| AK-15 | 600 | 14.000 | 9,000 | 13 | 100 | 125 | 150 | 225 | 9.000 | 25.000 |
| AK. 25 |  | 22,000 | 22,000 | 40 | 175 | 200 | 250 | 600 | 22.000 | 42,000 |
| AK. 50 |  | 42,000 | 42,000 | 200 | 350 | 400 | 500 | 1600 | 47.000 | 85,000 |
| AK. 75 |  | 85,000 | 85,000 | 2000 | 2000 | 2000 | 2000 | 3000 | 65,000 | 85,000 |
| AK. 100 |  | 8, 0.000 | 85,000 | 2000 | 2000 | 2000 | 2000 | 4000 | 85,000 | 85,000 |
| AK. 15 | 400 | 22,000 | 9.000 | 20 | 100 | 125 | 150 | 225 | 9.000 | 42,000 |
| AK-25 |  | 30,000 | 22,000 | 100 | 175 | 200 | 230 | 600 | 22,000 | 60.000 |
| AK-30 |  | 50,000 | 50.000 | 400 | 350 | 404 | 500 | 1600 | \$0,000 | 85.000 |
| AK. 75 |  | 85,000 | 65,000 | 2000 | 2009 | 2000 | 2000 | 3000 | 65,000 | 85,000 |
| AK-100 |  | 85,000 | 85,000 | 2000 | 2000 | 2000 | 2000 | 4090 | 85.000 | 85,000 |
| AK. 15 | 240 | 25,000 | 9,000 | 30 | 100 | 125 | 150 | 225 | 9,000 |  |
| AK-25 |  | 42.000 | 22,000 | 130 | 175 | 200 | 250 | 600 | 22,000 | 85.000 |
| AK- 30 |  | 65,000 | 50,000 | 400 | 350 | 400 | 500 | 1600 | 50,000 | 100,000 |
| AK-75 |  | 05,000 | 65,000 | 2000 | 2000 | 2000 | 2000 | 1000 | 65.000 | 130,000 |
| AK. 100 |  | 130,000 | 05,000 | 2000 | 2000 | 2000 | 2000 | 1000 | 15,000 | 130,000 |

## STANDARD CONTINUOUS CURRENT RATINGS

| 6-E. Breaker Type | Conllnuous Current Ratings <br> (Observe mintmum timin sel by applieaflon tables above and an peges (5-10) |
| :---: | :---: |
| AK. 15 | $15,20,30,40,50,70,90,100,125,150,175,200,225$ |
| AK-25 | 40, $30,70,90,100,125,150,175,200,225,250,300,350,400,300,600$ |
| AK. 30 | 200, 225, 250, 275, 300, 350, 400, 500, 600, 800, 1000, 1200, 1600 |
| AK.75 | 2000, 2500, 3000 |
| AK. 100 | 2000, 2500, 3000, 4000 |

instantaneous trips. This is called the Zone-Selective arrangement and is often desirable when the load-center feeder serves a motor control center.

## FULLY RATED SUBSTATIOṄS

Fully rated arrangements use fully rated breakers with long-time and instantaneous trip characteristics (LI) on both main and feeder circuit breakers. The main circuit breaker may, or may not, trip for a feeder fault-depending on fault magnitude.

## CASCADED SUBSTATIONS

Cascaded arrangements allow feeder breakers to be applied on circuits that are subject to fault currents in excess of the normal published interrupting rating of the breakers:

Under the cascade system a short circuit on the feeder circuit may trip the main breaker. NEMA standards state that the operation of breakers in excess of their interrupting rating (as in cascade) is limited to one operation after which inspection, maintenance or complete replacement may be required. It is further recommended that all feeders applied in cascade be power operated from a remote location.

## EXAMPLES

The tables make it easy to select the
proper G-E breakers for use with each system. For instance, using a fully rated system, a 1000 -kva, 480 -volt load-center unit substation with a primary source having a 150 mva maximum available short-circuit capacity, requires an AK-S0 main breaker with AK-25 feeder breakers.

Should either the main circuit breaker. or feeder circuit breakers be equipped with selective trips, the appropriate breakers may be found under the columns. headed Main-Selective, and Feeder-Selective or Zone-Selective. The main circuit breaker is the same size whether fully rated (LI) or selective (LS). However, the frame sizes of feeder breakers will depend upon whether they are applied as fully rated (LI), selective (LS) or zone selective (LSI).

Further, the tables indicate the main (LI) and cascaded feeder breakers (LI) for cascaded systems with a wide range of primary available short-circuit capacities and transformer sizes.

## CONTINUOUS CURRENT

The breaker types listed under the system headings satisfy the requirements for interrupting capacity. They may not be large enough to satisfy the requirements for continuous current rating, in which case, the next larger type should be used.

## A-C POWER SYSTEM APPLICATION

## TABLE VIL-Low-voltaga Powar Circuit Breakers208 Volis, Three-phase <br> -

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Applicertion Informestión
A-C POWER SYSTEM APPLICATION.


- If larger trip coils are required, see Table VI-page 16.
$\mathrm{L}=$ Long-time delay trip (overload tripping).
8 =Short-time delay trip (selective fault tripping).
I = Instantaneous trip (high fault fast tripping).
- Minimum impedance.

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TABLE IX-Low-voliage Powor Circuli Breakers480 Volls, Three-phese


## Applicestion Information A-C POWER SYSTEM APPLICATION

LE X—Low-voltage Power Circuit Breakers600 Volts, Three-phose


* If larger trip coils are required, see Table VI-page 16.

L a Long.time delay trip (overload tripping).

- Short-time delay trip (selfetive fault tripping)


## D-C MACHINE CIRCUITS

D-c rotating machines are subject to burning of the commutator and brushes and to possible flashover on currents above the commutating limit, which is usually about 200 percent of the continuous rating. For this reason, it is necessary to disconnect such machines quickly from the circuit. Hence, power circuit breakers with instantaneous overcurrent trip devices, adjustable from 80 to 250 percent of the breaker rating, are generally recommended for d-c machines and feeders. For marine service, and such other applications where some sacrifice in machine protection is justified to ensure maximum continuity of service, the dual-magnetic trip, with inverse time tripping from 80 to 160 percent of the breaker rating, and instantaneous tripping at 8 to 12 times rating, ean be used for d-c machines rated 250 volts and below.

For d-e generators and synchronous converters for general two-wire service, the recommended arrangements are shown in Fig. 26 and Fig. 29, with explanatory notes. Circuits to d-e motors should have the same arrangements as the d-c feeders.

For d-c, 3-wire machines, overcurrent protection is required in both sides of the armature, as shown in Fig. 28.

Time overcurrent protection is recommended for the neutral circuit, generally as part of an additional pole on the machine breaker. Usually the continuous rating of the machine neutral is approximately 25 percent of the full-load line current of the machine. This requires that the center pole on the 3 -pole breaker shown in Fig. 28 be of lower capacity than the other poles, with calibration adjustable from 80 to 250 percent of the pole rating.

When two 2 -wire generators are connected in series to supply power to a 3-wire system which gives a full-eapacity neutral, a 3 -pole breaker which has one pole in the positive lead, one in the nega. tive, and the third in the common neutral circuit of the two generators is recommended. Each pole is provided with overcurrent protection, as shown in Fig. 29.

For very low-voltage d-c generators (of about 25 volts or less), such as are used for electrolytic serviec, it is usually not considered necessary to employ the
high-current breakers which ordinarily would be required. For these machines, instantaneous overcurrent relays in the armature circuit (which function to reduce the generator field current) generally afford sufficient protection.

For excilors, it is not customary to furnish overcurrent protection. Sometimes, however, several exciters may be operated in parallel. In such cases, currentdirectional protection is recommended for each exciter. This should be of such a characteristic that it will trip its circuit. breaker only on values of reverse current above those which may be caused by inductive action between the a-c machine armature and its field circuit, when a system disturbance occurs. Because the required settings of the current-directional device may be above the continu-ous-current sating of the breaker, it is generally necessary to provide separate reverse-current relays rather than directacting, reverse-current devices on the breakers. A two-pole nonautomatic breaker with a shunt-trip device, or a contactor, is required for each exciter for this application.

## EQUALIZER CIRCUITS

Although knife switches can be used in the equalizer circuits of compoundwound machines, the use of power circuit breakers (as indicated in Fig. 27 to 29) usually offers advantages in switchgear, station layout, and operation. Because the equalizer circuit can in most applications be closed and opened simultaneously with the armature circuit, it is advantageous to use multipole breakers for combining both functions. The equalizer breaker poles need not be provided with overcurrent tripping, as the overcurrent protection to a machine must be provided in the armature circuit.

In two two-wire generators in serics, the series fields of both generators are connected in the neutral side of each armature. A separate, two-pole equalizer breaker should be furnished for parallel operation, as illustrated in Fig. 29. This breaker (or double-pole switch, if switch is used) must be closed before the line breaker is closed, and opened after the line breaker trips.

Normally, the amount of current in an equalizer circuit is small, but this circuit must have a low resistance to be effective.

It is recommended that the rating of the equalizer circuit and the devices be approximately one-third to one-half of the maximum or overload rating of the d-c machine.

## REVERSE-CURRENT PROTECTION

For d-c generators and synchronous converters operating in parallel, or in parallel with another source, particularly in machines above 300 kw , it is desirable to provide current-directional or reversecurrent devices on the circuit breakers to prevent abnormal interchange of current between the machines; also, to give more sensitive and faster internalfault protection than is afforded by the overcurrent tripping devices. These re-verse-current tripping devices (or separate severse-current relays), used to trip the circuit breakers, are particularly recommended for d.c generators and synchronous converters which have timeovercurrent trip on the generator circuit breakers. The setting of these reversecurrent devices should be as low as operating conditions will permit, but it mu' be high enough to prevent unnecessai. tripping on normal values of regenerated load, or on slight interchange of current between the machines at light load. The setting of standard G-E reverse-current devices is 10 percent of the breaker rating.

To give the best protection, each mschine circuit breaker requires the same number of reverse-current tripping elements (whether devices on the breaker, or separate relays) in the armature circuits as there are overcurrent trips. In d-c, 3-wire machines, however, reversecurrent protection is frequently provided in one side only, at some sacrifice in machine protection.

In some applications, protection from: loss of driving power is necessary. In these cases, and in unattended (automatic) stations, current-directional relays rather than the reverse-current devices on the breakers themselves must be used to obtain the required degree of sensitivity. Sueh sensitive protection is liable to trip the machine under conditions of regenerated load, or of momentary interchanges of current among several machines that operate in parallel, and, accordingly, these applications require special consideration.

# Application Information <br> D-C POWER SYSTEM APPLICATION 

## Direct-current Machine Circuils


(a) Ungrounded negative One 2-pole breaker with two overcurrent trips

(b) Grounded negative One 1-pole breaker with one overcurrent trip

Fig. 26. D-e, 2-wire, shunfowound ganerator or aynthranous san. verler, of compound-wound mashlm, for Isofated eperation

(a) Ungrounded negative One 3-pole breaker with two overcurrent trips

(b) Grounded negative One 2-pole breaker with one overcurrent trip

Fig. 27. D-c, 2-wlre, compound-wound gonerafar ap synehranous cenvarter, for paralfal operallon

a Fly. 28. D-c, 3-wire, thunswound ganerator of byt. chrenelt convertor, or cam-pound-wound mochlne, for bolofedopareflon, yroundad or ungrounded noutral One 3-pole breaker with aree overcurrent trips (ree Note A)

## D-C FEEDER CIRCUITS

Figs. 30 to 34, inclusive, show the required arrangements of breaker poles and overcurrent trip devices for the protection


Fig. 29. D-e, 2 -wifr genoraters in carles for 3-wifo sarvice, fos porallel operotion with ofher slallar moehines, grounded or ungroundad nautral
One 3-pole main and neutral breaker with three overcurrent trips and one 2-pole equalizer breaker with no overcurrent trips

Note A-For 3-wire, d-c machines, Fig. 28, a circuit-breaker pole with trip is shown in the neutral circuit. For 6 -phase, 3 -wire, d-e synchronous converters, some means must be provided additionally for disconnecting and segregating the transformer neutrals during the starting period (when the starting is done by means of taps in the low-voltage transformer windinge).

- The overcurtent device on the breaker pole in the neutral circuit is usually of reduced capacity ( $25 \%$ ), and should be calibrated for setting from 100 to 200 percent of the neutral poie rating.
of feeder circuits on the various types of d-e systems. Since a majority of the feeder loads will be motors the recommendations for the protection of d-c
machine circuits should be followed in selecting the overcurrent trip devices.


Fig. 30. Two-wire, ongrounded
$\dagger$ One 2-pole breaker with two overcurrent trips


Fig. 31. Two-wlre, srounded
Gre 1-pole breaker with one overcurrent trip
$\dagger$ Exception may be made for certain types of dec feeders using single-pole circuit مrayers.


Fig. 32. Two-wife, cone mectod to oufside wiran of thrae-wips grounded noulpol elicult
One 2 -pole brealer with two overcurrent trips
. 32 Twowlre, cone

National Electrical Code applies, reference should be made to paragraph 2351a. If the ewitch or eircuit brealer does not interrupt the grounded conductor, other means shall


Fig. 33. Threetwife, ungrounded
One 3-pole brealeer with three overcurrent trips

fig. 34. Three-wire, grounded
TOne 2-pole breaker with two overcurrent tripa (one in each conductor, except neutral)

[^7]
## D-C APPLICATIONS (Coni'd)

## UNDERVOLTAGE DEVICES

For d-c generators or synchronous converters which operate in parallel with another source, it is desirable to insure the disconnection of the machine from the system, both on normal and emergency shutdowns, in order that the machine cannot subsequently be.subjected to voltage from the system source. For manually operated breakers this requires a direct-acting undervoltage device with its coil connected across the machine armature circuit. For synchronous converters or for motor-driven generators, the coil of the undervoltage device should be placed in series with the normally open auxiliary switch on the running breaker or field contactor, whichever closes last in the starting sequence. Also, for d-e machines equipped with overspeed or other protective devices, or a control switch for semote tripping, and without a reliable source of tripping power in the station (such as an operating or tripping storage battery).

## FIELD DISCHARGE BREAKERS

These breakers are equipped with a field discharge clip using silver-alloy contacts. This clip is connected to the maincontact operating shaft and; therefore, operates independently of the breaker mechanism. The field-discharge clip closes BEFORE the main circuit is broken, thus assuring positive protection for field coils against high induced voltages when the breaker is opened either normally or by a protective device or relay. With the AKF breakers the field-discharge clips overlap the main contacts both opening and closing.

Double-pole field breakers are available as follows:

| Type | $\begin{gathered} \text { D-E } \\ \text { Voltoge } \\ \text { fotion } \end{gathered}$ | $\begin{aligned} & \text { Contiaucous } \\ & \text { Ampp } \\ & \text { Roting } \end{aligned}$ | Nominal Field Volloge fating -D-c Voli: |
| :---: | :---: | :---: | :---: |
|  | 350 500 | 600 2000 | $125 / 250$ $250 / 375 / 500$ |
| AKF. 20 | 300 | 4000 | 250/375/500 |

## OPERATING MECHANISMS

Power-circuit breaker operating mechanisms perform the function of closing and opening the breaker contacts in response either to a manual effort or an electrical signal. Basically, operating mechanisms fall into two categories.
a. Dirast acting in which the closing force is furnished by an operator (manual) solenoid or motor (electrical).
b. Siorod energy (both manual and electrical) in which an energy storing means is interposed between the control source and the breaker contacts.

In recent years, there has been a strong trend towards stored energy operating mechanisms because of the important advantages they offer. These include: increased safety of operation, prolonged contact and breaker life, wider breaker application, particularly selective tripping and motor starting, reduced maintenance and a reduction in control power requirements for electrical breakers.

General Electric Type AK circuit breakers utilize stored energy closing -mechanisms. Models are available for either manual or electrical operation.

## STORED ENERGY CLOSING

A spring-operated "stored energy" elosing mechanism provides fast, con-stant-speed closing for either electrical or manual AK-2-15 and AK-2-25 power circuit breakers. This mechanism, an extension of the principie long used in large-sized AK breakers, provides a closing speed completely independent of the operator (manual) or the voltage level of the control power source (electrical).

A manually operated breaker uses an insulated plastic handle. To close the breaker, the handle is first rotated counterclockwise through approximately 100 de grees. This resets the mechanism and partially stores energy in the closing spring. The handle is then rotated clockwise, completing the charging of the springs. As it approaches the normal rest position, the mechanism goes "over center," releasing energy to close the contacts. Upon receiving a tripping impulse, the breaker contacts are driven open at high speed by the same springs that are used for closing. A unique "rebound latch" which operates only during opening, prevents the contacts from rebounding in the closing direction.

Electrically operated models use an a-c or d-c solenoid to charge the closing spring and provide total closing time of less than 5 cycles from the instant the close button is energized. The solenoid is small, compact, has a low total-energy requirement, and affords greater accessibility for adjustment of overload trip devices. Electrically operated breakers are normally furnished without manual handles, but with a maintenance closing device.

The electrical stored energy closing mechanism utilizes energy stored in powerful closing springs to close the breaker contacts. A small universal motor, which can be operated from ac or de, drives a gear reducer unit. The output of this unit charges the closing springs through a charging crank and cam.
In the charged position, the springs are positively blocked by the "advance of center" location of the charging crank with respect to the charging cam. When the closing switch is operated the motor quickly drives the crank over center, releasing the springs and closing the contacts. Once the springs are released, the contacts will close regardless of continuity of control power. This is important when breakers are accidentally closed in on a short circuit and the control power source is the main bus.

Recharging is done immediately after a closing operation at a low rate of energy input. This means low closing current-.. only 4 amp at 115 volts ac. The springs. therefore, are always charged and ready to close the breaker.

Contacts require considerably more energy for closing under short circuit or overload conditions than under normal load. Each time the springs are charged, there is enough energy stored to close the contacts under full short-circuit conditions. Energy in excess of that required to close the breaker under a particular load is absorbed by the flywheel effect of the gear box, and is returned to the closing springs.

A second set of springs is used to open the contacts when the breaker receives a trip impulse.

A detachable ratchet handie, which can be slipped over the extension shaft of the gear box, is provided for maintenance operation.

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## Application Informerion

## OPERATING MECHANISMS




Thete 8014990)
Flg. 38

(Photo 8014990 )
Fig. $39^{\circ}$


Fig. 40

Electrical sfared enargy clasing mechanisms

## CONTROL-POWER REQUIREMENTS

Suceessful operation of electrical breakers is dependent on a reliable control-power source. The operating currents of the closing mechanisms and shunt trip coils together with controlcircuit fuse ratings and operating voltage ranges are listed in Table XI.

Note: The following control-power transformers are recommended where only one breaker at a time is being closed.
AK-2-15, -25
3 KVA (All control voltages)
AK-2-50, AK-2-75, $1 / 2$ KVA (All control volt- AK-2-100 ages)

TABLE XI-Operating Currents $\psi$

| $\begin{aligned} & \text { Trpe } \\ & \text { of of } \end{aligned}$ | $\begin{aligned} & \text { Anpere } \\ & \text { Eefting } \end{aligned}$ | Closing Mechoaism |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 115 .volt, 60.eycle TOperating Renge 95-125 V] |  | 230-vell, 60-cycle (Operating Range 190-250 V) |  | 125-volt, 0-6 (Operating Range 90-130 V) |  | 250-voll, 0 -c (Operating Range 180-260 V) |  |  |  |  |  |
|  |  | Operafing Current to Amperes et Roled Volts | Ampere Rating of fuse | Operating Current in amperes al Rated Valls | Ampere Rating fuso | Opercting Cutront tn Amperes of Rated Volis | Ampare daling Fose | Opereting Curront in Amperes ol Relad Voll | Ampare Roting Fuse | $\begin{gathered} 115 \mathrm{y} \\ \text { so.cycle } \\ \text { Rone } \\ \text { os-125 } \mathrm{V} \end{gathered}$ | $\begin{gathered} 230 \mathrm{~V} \\ 60-6 \mathrm{yclo} \\ \text { Ronce } \\ 190-250 \mathrm{~V} \end{gathered}$ | $\begin{gathered} 125 \mathrm{y} \\ \text { D.e. } \\ \text { monge } \\ 70-140 \mathrm{y} \end{gathered}$ | $\begin{array}{r} 250 \mathrm{~V} \\ \mathrm{D}-6 \\ \text { 2090. } \\ 140-280 \mathrm{~V} \end{array}$ |
| $\underset{A K-2-25}{\text { AK. }}$ | $\left.\begin{array}{r} 15-225 \\ 40-600 \end{array}\right]$ | 153/78* | 30 | 68/28* | 13 | 44/446 | 10 | 24/24* | 6 | 12.3/10.0¢ | 6.9/57 | 1.9/1.9 | 1.0/1.0* |
| AK.2.50 | 200-1600 | 9/40 | 6 | 4/2.6 6 | 6 | 30/46 | 6 | 15/2¢ | 6 | 123/10.8\% | 6.9/574 | 1.9/1.9* | 1.0/1.0 |
| Ax.2.75 | 2000-3000 | 9/4 ${ }^{\text {d }}$ | 6 | 4/2.6 $\dagger$ | 6 | 30/4 ${ }^{\text {1 }}$ | 6 | 15/2¢ | 6 | 12.3/10.8 | 6.9/574 | 1.9/1.9 ${ }^{\text {d }}$ | 1.0/1.0* |
| - ak-2-100 | 4000 | 9/4* | 10 | 4/3.2* | 10 | 30/5 ${ }^{\text {¢ }}$ | 10 | 13/2.5 ${ }^{\text {d }}$ | 10 | 12.1/10.8 | 6.9/37* | 1.9/1.9* | 1.0/1.0 |

* Values listed for operating currents are subject to change and
should be used for estimating purposes only.
- Inrush/sustained.


## REPETITIVE DUTY

Circuit breakers are designed primarily to perform the function of circuit interruption under short-circuit conditions. Nevertheless modern circuit-breaker mechanisms are capable of many opera-
tions under full-load operation and inrush conditions such as encountered in motor starting applications. Industry standards have been established for the minimum performance which is indicated in Table
XII. With adequate maintenance G-E breakers can be expected to exceed the standards. Refer to Switchgear Marketing when questions arise with respect to specific applications.

TABLE XII—Repetitive Dúly and Normal Maintenance

| Type of Irealer | Circutt Arealer Denfonalion interrupling Reting, Amparas | Number of Operations |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Number of Operalions Gerween Servicing. Par, $A$ | No loed Mechanical, Par. ${ }^{\text {B. }}$ $E, F, E_{0}$ $H_{\text {, }}$ cad 1 | Fint lood <br> Nonfacte, <br> Por. $C_{0}$ <br> E, F. 6 . <br> $\mathrm{H}_{4}$ and 1 | Foll tead Factl. Par. C, E, F, G. H. 4 and $K$ | tervis <br> Nonfouti, <br> Paf. D. <br> F, F, G, <br> $\mathrm{H}_{4}$ and | Lncush fault Por. D. $\mathbf{E}_{4}$ F. G. $\mathrm{H}_{2}$ 4 and $x$ |
|  | Columa | Column 2 | Column 3 | Cotuma 4 | Column 5 | Coluran 6 | Columa 7 |
| A 4.15 | 13,000 | 2500 | 50,000 | 5000 | 4000 | 3500 | 2500 |
| AX-25 | 25,000 | 1730 | 35,000 | 3500 | 2800 | 2500 | 1750 |
| AX-50 | \$0,000 | 300 | 10.000 | 1090 | 800 | 750 | 300 |
| Ax.75 | 75,000 | 230 | 3.090 | 500 | 400 | ...* | .... |
| AX-100 | 100,000 | 250 | 5,000 | 500 | 400 | .... |  |

## NOTES FOR TABLE XII

Power-operated circuit breakers, when operating under usual service conditions, ahall be capable of operating the number of times specified in the above table. The operating conditions and the permissible effect of such operations upon the breaker are given in the following lettered paracraphs. For each column, all paragraphs listed in the column heading must be given consideration.

This atandard applies to all parts of a circuit breaker that function during normal operation. It does not apply to other parts, zuch as overcurrent tripping devices, that function only during infrequent abnormal eireuit conditions.
servicing
A. Servicing shall consist of adjusting. cleaning. lubricating, tightening. etc. ot recommended by the manufacturers. The operations listed are on the basis of servicing at intervals of six months or less.

## CIRCUIY CONDITIONS

B. When closing and opening no load.
C. When closing and opening currents up to the continuous current rating of the circuit breaker at voltages up to the maximum deaign voitage and at 80 percent power factor or higher.
D. When closing carrents up to 600 percent and opering currents up to 100 percent (80 percent power factor or higher)
of the continuous current rating of the eireuit breaker at voltages up to the maximum design voltage.

## operating compitions

E. With rated control voitage applied.
F. Frequeney of operation not to exceed 20 in 10 minutes or 30 in one hour. Rectifiera or other auxiliary devices may further limit the frequency of operation.
G. Servicing at no greater intervala than shown in Column 2 of the table.
compition of the circuit breaker after THE OPERATIONS SHOWN IN THE TABLE
H. No parts shall have been replaced exeept as qualified by par. $K$.
I. Circuit breaker shall be in a condition to meet all of its current, voitage and interrupting ratings.
J. The cireuit breaker ahall be in a condition to meet all its current and voltage ratings but not necescarlly its interrupting sating.

## operation umder fault conditions

K. If a fault operation cocurs before the completion of the permissible operations, it is not to be inferred that the breaker can meet its interrupting rating or complete itu number of operations without servicing and making replacementa if necessary.

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## . . ARCURRENT TRIPPING DEVICES

Ceneral Electric low-voltage power circuit breakers are equipped with tripping devices used for two distinct functions:
a. As a means of opening the breakes during the process of normal switching operations initiated by an operator or an automatic switching equipment.
b. As a means of automatically opening the breaker under abnormal power-system conditions for circuit-- protective purposes.

Normal switching tripping is effected. by one of the following devices:

1. Manual trip button-supplied on all breakers both manually and electrically operated.
2. Shunt-trip device-supplied on all electrical breakers and optionally a available on manual breakers. Shunt trips are normally energized from a reliabie constant potential source such as a storage battery or control power transformer.
ttomatic protective tripping is ied by one of the following devices, ocpending on the type of breaker and the means employed for initiating the tripping:
3. Direct-acting series overcurrent tripping device Type EC-1 and EC-1B embodying instantaneous, short time-delay and long timedelay elements or specified combinations thereof. This trip is used primarily for selective tripping of breakers. Table XIII and Fig. 45 and 46 show the calibrations and time-current characteristics of these elements available for various ratings of breakers.
4. Direct-acting series overcurrent tripping device Type EC-2A embodies instantaneous and long timedelay elements with adjustable instantaneous pickup and long timedelay elements. This trip is used on breakers in fully-rated and cascaded systems. Table XIII and Fig. 44 show the calibrations and timecurrent characteristic of these elements which are available only on circuit breakers Types AK-2-15, -25 , and -50 .

## Applicestion Informasion



Fig. 41. Type EC-2A magnolic overcurtent Iripping dovice. Sories frip for 223, 600, and 1600 amp frame size breakers


Fig. 42. Type EC. 1 magnafle overcurrant iripping doviee, Soriaz ithp for 225,600 , and 1600 emp frame sise breakers


8024559

[^8] 3000 and 4000 emp freme sizo breckers

## TRIPPING DEVICES (Cont'd)

3. Undervoltage trip device-optionally available for all breakers both manually and electrically operated. Breaker tripping occurs when a spring mechanism is released by the reduction in voltage on a shuntholding coil which is usually energized directly from the main power circuit. The undervoltage device may have either instantancous or time-delay action depending on the application requirements.
The timing device is static, consisting of a capacitor-resistor combination. Time delay is readily adjustable over a range of 1 to 5 seconds. The device is adaptable for use with Thermo-tectors and for remote tripping.
4. Reverse-current trip device-aptionally available for mounting on pole units of d-c breakers for the detection of change in current direction in d-c circuits. They are potential polarized by coils rated 125 or 250 volts and are set to trip on reverse current equal to 10 percent of the breaker continuous current rating.
Type EC overcurrent trip devices are magnetically operated, using a series coil or single conductor and an associated magnetic structure to provide tripping force. Three basic characteristics-long time delay, short time delay, and instan-taneous-can be used singly or in combination for a wide variety of applications.
Long time delay is accomplished with a positive-displacement oil piston. Sealing of the assembly eliminates variations caused by dust and dirt. Accurate machining of the piston and cylinder, a calibrated orifice, and silicone oil keep variations in time delay due to changes in ambient temperature to a minimum.
Short time delay is accomplished with a rugged mechanical escapement.

Instantaneous tripping is obtained with a tension spring in series with the long time-delay piston.

TABLE XIH
TRIPS FÖR 225-, 600-, AND 1600-AMP FRAME SIZE BREAKERS
EC-2A Fully Adjustoble Trip for all applications where the combination of long time delay and instantaneous, or instantaneous alone is required.

| Areilable Chareflurifties | Rong of Pickup Adjustment | (at $600 \%$ of Pickup Sattingl | Factory Selling |
| :---: | :---: | :---: | :---: |
| Leng time | 80-160\% colibrated at 80, 100, 120, 140 and and $180 \%$ of coit rating |  | $\left\{\begin{array}{l} 18-1810 e \\ 100 \% \end{array}\right.$ |
| Antontonecus | $\left.\begin{array}{l} \text { 6-12X coil roting } \\ \text { 4-9X coil raling } \\ \text { e-15X coil roting } \\ \text { 80-250\% coil rotingt } \end{array}\right\}$ | $\left\{\begin{array}{l}\text { Select one ronge-s ta } \\ \text { Unlest otherwise specified }\end{array}\right.$ | $\begin{array}{r} 12 x \\ 9 x \\ 15 x \\ 100 \% \end{array}$ |

F Not available with long time delay.

## TRIP5 FOR 225-, 600-, AND 1600-AMP FRAME SIZE BREAKERS

EC-1 Selective Trips combine long time and short time elements for intentional delay up to the interrupting rating of the breaker. (See Table I, Col, 4.) For special applications, instantaneous may be added.

| Ayalleble Characteristite | longe of Fickup Adjustiment* | - Tinat Deloy | Fectory Solting |
| :---: | :---: | :---: | :---: |
| leng time | $\begin{gathered} 80-160 \% \\ \text { (Fostory set of } 100 \% \text { ) } \end{gathered}$ |  | 18-100\% |
| Shattime | 2-5 a ceil rating <br> 3-7 a ceil raling <br> 4-10 n estl faling |  |  |
| Inslantenoeus | Mon-sdiustable | High Sel | Must be spacifies |

- Pickup tolerances are $\pm 10 \%$ for EC-2A and EC-1 trip devices.


## TRIPS FOR 3000- AND 4000-AMP FRAME SIZE BREAKERS

EC-IB Fully Adjustable Trip and Selective Trips for all applications where combinations of long time delay, and instantaneous, or instantaneous alone is required-short time delay also available.

| Avoilebla Choracterintits | Range of Pithup Adinutiment | Time Dalay | Foctory Sutling |
| :---: | :---: | :---: | :---: |
| Leng time | 50-160\% calibrated at 80 . $100,120,140$ ond 160\% of ceil roting |  | 188-100\% |
| Short fime | Three ronges avoilable- $\left.\begin{array}{l} \text { galect onc } \\ 2,35,5 x \\ 3,5,7 x \\ 4,7,10 x \end{array}\right\}$ |  | $\left\{\begin{array}{l}\text { Must bo } \\ \text { epecifled }\end{array}\right.$ |
| - Ansianiencour | Three rengas availablesalect one $\left.\begin{array}{l} \text { ourct one } \\ 6-12 x \text { coil roling } \\ 9-9 x \text { coil raing } \\ 9-15 x \text { coll roling } \end{array}\right\}$ | $\left\{\begin{array}{l} \text { Select one renge- } \\ 6 \text { to isX furnizhed } \\ \text { unlesi etherwise specified } \end{array}\right.$ | $\begin{aligned} & \text { 12x } \\ & \text { ox } \\ & 15 x \end{aligned}$ |

[^9]
## Application Informasion

PE EC-2A TRIPPING DEVICE CHARACTERISTICS


Fig. 44. Timo-eurient characterisilles of the Type EC-2 and EC-2A trip dovice for AX-2.15, -25 and -50 circult breaker

## LOW-VOLTAGE AIR CIRCUIT BREAKERS

## Applicction Information



# AK LOW VOLTAGE POWER CIRCUIT BREAKERS INSTALLATION AND OPERATION 

Types

| AK-1-15 | AK-2A-15 | AKF-1A-25 |
| :---: | :---: | :---: |
| AK-1-25 | AK-2A-25 | AKF-1B |
| AK-1-50 | AK-2A-50 | AKF-1C |
| AK-1-75 | AK-2A-75 | AKF-2C |
| AK-1-100 | AK-2A-100 | AKF-1D |
| AK-2-15 | AK-2-50S | AKF-2D |
| AK-2-25 | AK-2-75S | AKU-2-25 |
| AK-2-50 | AK-2-100S | AKU-2-50 |
| AK-2-75 | AK-2A-50S | AKU-2-50S |
| AK-2-100 | AK-2A-75S |  |
| AK-1A-25 | AK-2A-100S | AKU-2A-50 |

SWITCHGEAR DEPARTMENT


Philadelphia, pa.

## RECEIVING, HANDLING AND STORAGE

Before installing, or operating these circuit breakers, make a careful reading of the sections of these instructions which are pertinent to the anticlpated work.

Upon receipt of a circuit breaker, immediately make an examination for any damage or loss sustained in shipment. If injury, loss or rough handling is evident, file a damage claim at once with the trans-
portation company and notify the nearest General Electric Sales Office.

Unpack the circuit breaker as soon as possible after it has been received. Exercise care in the unpacking to avoid damage to the breaker parts. Be sure that no loose parts are missing or left in the packaging material. Blow out any dirt or loose particles of packaging material remaining on/or in the breaker.

## INSTALLATION

## LOCATION

In choosing a location for the installation of an AK Circult Breaker, there are two factors to be considered. The first of these ts the effect of the location on the breaker itself. Much better performance and longer life may be expected If the area is clean, dry, dust-iree, and well ventilated, than if the opposites to these conditions exist. The second consideration is convenience for operation and maintenince. The breaker should be easily accessible to the operator, and there should be sufficient space allowed for malntenance work to be done if this becomes necessary.

## MOUNTLNG

AK Circuit Breakers are designed to be mounted in any one of three ways. These are dead front mounting, individual mounting with the enclosure being provided, and drawout mounting in which the breaker is designed for ingertion into a cubicle in drawout equipment such as a substation or cohtrol board.

## DEAD FRONT BREAKERS

These breakers are designed for mounting in a switchboard or enclosing case of the customer's design and construction. Mounting in this instance consists of bolting the breaker frame to a supporting structure within the switchboard or enclosure, connecting the power buses or cables, and making any necessary control connections. The front cover of the breaker enclosure may be a hinged door or a plate bolted to the panel. In elther case, it should have a section cut out, through which the front escutcheon of the breaker may protrude. Oatiline drawing numbers giving the dimenstons needed for preparing a suitable enclosure or cubicle for the various types of AK breakers are given below. These are for standard 2 or 3 pole breakers.

| Breaker | Typical Outline Drawing No. |
| :---: | :---: |
| AK-1-15 | 256 C 753 |
| AK-1-25 | 256 C 754 |
| AK-2-15 and 25 | $695 \mathrm{Cl18}$ |
| AK-1-50 Man. Oper. | 248 C 703 |
| AK-1-50 Elec. Oper. | 238 C 123 |
| AK-2-50 S. E. Man, Oper. | 845 C 281 |
| AK-1-75 | 238 C 192 |
| AK-1-100 | 238C193 |
| AK-2-75 Elec. Oper. | 269 C 225 |
| AK-2-75 S. E. Man. Oper. | 845 C 284 |
| AK-2-100 Elec. Oper. | 269 C 227 |
| AK-2-100 S. E. Man. Oper. | 845 C 290 |

The surface on which the breaker is mounted must be flat throughout in order not to impose any internal distortion on the breaker unit. The supporting structure must be rigid enough to avoid any possibility of the breaker studs supporting the weight of the breaker. Minimum cutout dimensions, as given by the appropriate outline drawing, must be maintained to provide adequate electrical clearance.

## INDIVIDUALLY ENCLOSED BREAKERS

Individually enclosed breakers are supplied with several types of enclosures, most common is the general purpose type or the weather resistant type. The former is used for favorable indoor locations and the latter for outdoor locations or indoor locations that may be subject to unfavorable conditions. All of the enclosures are provided with suitable means for mounting on walls or supporting framework. Removable cover plates are supplied with the enclosures which may be drilled or machined to accommodate the entrance of bus ducts, conduits or cables. Stepe in the procedure for installing enclosed breakers follow:

1. If the breaker is an AK-15, AK-25 or an AK-50, remove it from the enclosure. With AK-50 breakers, a handle and cam arrangement is used for that part of the breaker movement that involves the disengagement or engagement of the primary disconnect. AK-75 and AK-100 breakers

If the circuit breaker is not tobe placed in service at once, store it in a clean, dry location in an upright position. Support it to prevent bending of the studs or damage to any of the breaker parts. Do not cover the breaker with any packing or other material which absorbs molsture, that may cause corrosion of breaker parts. A covering of kraft or other non-absorbent paper will prevent dust from settling on the breaker.
are bolted solidly to the enclosure frame and need not be removed from the enclosure.
2. Remove cover plates of enclosure and prepare them to accommodate whatever power entrance means ts used.
3. Mount enclosing case to supporting structure.
4. Replace cover plates and make power connections to stationary terminals in enclosure.
5. If the breaker is a type AK-15, AK-25 or AK-50 and has been removed from the enclosure, it may now be replaced. Control power connections to the terminal board should be madeas required. (See CONNECTIONS).
6. Before energizing the power circult, operate the breaker several times to be sure that it is functioning properly. (See OPERATION).

## DRAWOUT BREAKERS AKD EQUIPMENT

Mounting drawout breakers consists of simply placing the breaker in the proper position with respect to its enclosure, sliding or rolling it to a stop position, and, by means of a racking handie and mechanism, racking it through the lastpart of its movement during which the stationary and movable halves of the disconnects engage. Large drawout breakers are fastened to a telescoping tray which extends out from the enclosure to receive the breaker. Small breakers have guides on thetr stde plates which slide in channels in the enclosures. Both large and small breakers have a test position in which the secondary disconnects are engaged, but the primary disconnects are not. In this position, the breaker may be operated electrically without energizing the load cable or bus.

These instructions do not purport to cover all details or variations in equipment nar to provide for avery poserble contingency to be met in commoction with installation, operction or maiatenance. Should furfther information be dasirod or should partiaular problems arizo which are not covered aufficionthy for the purchoser's perpocaty the matfer ahould be roferred to the General Eloctrie Compary.

Use D50H47 lubricant on the disconnect erminals to reduce the force required to tsert the breaker.

The procedure for inserting and withdrawing a drawout breaker from its enclosure is as follows:

## Inserting Breaker AK-15 and 25

## 1. Trip the breaker.

2. Raise the breaker until the guides on the sides of the breaker are level with their mating supporting channels in the enclosure, and slide the breaker part way into its enclosure. (Note - The breaker will be obstructed by a position stop at the bottom of the enclosure after the breaker bas traveled only a short distance into the cubicle. Lift the position stop handle, located at the bottom right of the enclosure, which will release the position stop and allow the breaker to travel further into the cubicle).
3. Raise the rackout handle forward and up as far as its travel will permit and push the breaker into the enclosure until the rackout pins on the handle assembly bear against the housing rackout cams on the side of the enclosing case.
4. Push downward on the rackout handle forcing the pins on the handle up into the slot in the gtationary cam plate. This action forces the breaker through a.final short portion of its movement into the enclosure and allows the operator to provide the force necessary to make the primary disconnects engage the stationary studs in the enclosure. In performing this operation, make sure that the handile is rotated downwards as far as its iree travel will permit and then pull the racking handle down to be sure the trip interlock is released. (Note - When the racking handle is in any position other than complately down, the breaker cannot be operated and is held trip-free by the trip interlock. This applies to the "tully $\mathrm{in}^{74}$ and "test" positions.)

## Withdrawing Breaker AK-15 and 25

1. Trip the breaker open. If the breaker is not open, the interlock lever of the drawout mechanism will not permit operation of the rackout handle.
2. Pull the racking handle up and forward as far as it will travel, disengaging the primary disconnects.
3. Slide the breaker out until the position stop engages in the front slot in the bottom of the breaker carriage. The breaker is now in the "test" position, where its primary disconnects are safely disconnected from the line and load terminals of the enclosure. (Note - Refer to aection describing "Test Position" in these Ingtructions.)
4. To remove the breaker from its enclosure, lift the position stop handle and slide the breaker formard until the position stop engages the rear slot in the bottom of the breaker carriage. This is the safety position stop where both the primary and
secondary contacts are disengaged. Again lift the position stop handle. Slide the breaker slightly forward to remove it from the enclosure.

## Inserting Breaker AK-50, 75 and 100

1. Lift the breaker to a position approximately six tnches above the height of the compartment tray.
2. Pull the drawout tray out under the brealser as far as the tray will travel. NOTE - When installing an individual skeleton housing for a drawout AK-50 or 75, locate a bolt head over the two iront bottom mounting holes of the housing to provide a limit stop for the drawout tray.
3. Lower the breaker about $1 / 2^{\prime \prime}$ above the dowel pins on the tray and push the breaker back into its compartment 80 that the rear bottom angle of the breaker is against the guides on the tray directly back of the dowel pins.
4. Slowly lower the breaker onto the tray and at the same time guide it 80 that the holes in the rear angle of the breaker fit over the two dowel pins on the tray. If the breaker is correctly positioned on the dowels, Its rear and side bottom irame angles will all sit itrmly on the tray:
5. Insert two $3 / 8$ inch hex. head acrews through the holes in the iront of the side angles on the breaker and thread them part way Into the tapped holes in the tray. Do not. tighten screws ifrmly. This provides better alignment of the primary stationary studs and the primary disconnects for the subsequent racking operation.
6. Push the breaker into the compartment untll the "teat" position stop engages to prevent further travel. (Note - Reier to section describing "Teat Position" In these Instructions.)
7. Release the test position stop by depressing its lever and push the breaker back into the compartment untll the racking pins on the housing butt againgt the outer surface of the racking cam. In this position, the racking pin has lifted the locking arm on the cam which allows the racking handle to be lifted enough to allow the pawl to engage the first notch on the cam.
8. When the pawl engages the first notch on the cam, push the handle down again to its normal position. This causes the cam to rotate about the racking pin. Repeat this operation five times to rack the breaker into its final operating position. Interlockis hoid the breaker trip free until it is racked into the fully contacted position. The fifth stroke of the handle is only a partial stroke and does not result in any further movement of the breaker. It does serve three useful purposes: it positions the cam 60 that it cannot rotate and allow the breaker to back out under short circuit stresses; the nartial stroke gignals that the racking operation is complete, and it releases the trip interlock which was engaged by the racking pin during the previous four pumps of the racking arm. NOTE: Once a racking operation has been started, it must be completed, as the breaker cannot be reversed until the racking operation is completed.
9. After completing the fith racking stroke, Lift the handle as high as it will go and allow it to drop to its normal position. NOTE: Any strokes begond this point will
cause the breaker to be trip free. Tighten the $3 / 8$ inch hex head screws inserted in the front holes of the drawout tray during step 5 of this operation. The breaker is now in the operating position.
Withdrawing Breaker AK-50, 75 and 100
10. Trip the breaker to releage the positive racking interlock.
11. Lift the racking handle as far as it will go.

This operation will re-engage the trip interlock to hold the breaker trip-free for the remainder of the racking operation. Note that here the cam is rotated by lifting the handle, whereas in racking the breaker in, the operation is performer as a result of pushing the handle down.
3. Reset the handle to its lowered position and lift it again. This operation must be performed 5 times to completely disengage the cams from their racking pins. After the ifth lifting stroke let the handle drop to its normal position.
4. Pull the breaker out of its compartment until the test position stop engages to hold the breaker in the "test" position.
5. Depress the test position stop handle and pull the breaker out of its compartment as far as the drawout tray will travel.
6. Remove the two $3 / 8$ hex. head screws which hold the breaker on the tray.
7. Attach a lifting device to the top frame of the breaker.
8. Lift the breaker approximately $1 / 2$ inch off the dowel pins on the tray and then pull the breaker forward until its primary contacts clear the compartment.
9. Push the tray all the way back into its compartment. The breaker is now free from its compartment.

## TEST POSITION

The "Test Position", as referred to in the previous instructions, is that breaker position where the primary power disconnect contacts are safely disengaged but the secondary control disconnects are engaged. In this position, the breaker may be tested or operated, manually or electrically with out energizing the primary power circuit, provided the racking handle has been moved to the completely down position, thus releasing the trip interlock.

For a more complete description of drawout mechanisms and enclosures see AKD DRAWOUT EQUIPMENT INSTRUCTIONS, GEH-1830 and AKD5 Drawout Equipment Instructions GER-83902.

## DRAWOUT BREAKERS AKD5 EQUIPMENTT

NOTE: AKD5 breakers are identified by letter "A" appearingafter breaker number example, "AK-2A-15".

Drawout Mechanism Operation - There are four positions of the drawout mechanism:

1. The Connected Position - the breaker in the operating position, both primary and secondary contacts made and the door may be closed.
2. The Test Position - theprimary (power) contacts not made but the secondary

- (control) contacts are made. Any breaker test not involving power may be made in this position. The door may be closed in this position.

3. Disconnect Position - neither the primary nor the secondary contacts made. The door may be closed.
4. Fully Withdrawn Position - the breaker completely out. of its compartment ready for removal from the inner housing. The door must be open in this position.

NOTE: The mechanism is designed to reverse automatically in the connect and fully disconnected position. Once an operation is started it must be completed. Completion of an operation is indicated by the red knob retracting to its original position.

## Breaker Insertion AK-2A - With the inner housing in the connected poaition proceed as follows:

1. Pull the red knob. Pull the mechanism operating handle fully out and allow it to return to its original position. Repeat this three more times. The inner house is now in the test position.
Pull the red knob again. Pull the mechantam operating handle two complete strokes drawing the inner housing to the disconnect position.


Fig. 1 (Front View)
3. Open the housing door and rotate the two track lock links, releasing the tracks. Pull the tracks out to the llmit of their travel. This ts the fully withdrawn position.
4. With a lifting device, ratse the breaker so the mounting pins are about one inch above the tracks. Lower breaker so the breaker mounting pins drop into the slots in the tracks. Remove the lifting device cable.
5. Push the breaker in against the track stops. Rotate the two lock links to lock the breaker in place. Close the door.
NOTE: When moving a breaker from one position to another be sure breaker is tripped open.
6. Pull the red knob. Pull the mechanism operating handle two times until the test position is reached.



Fig. 2 Front View AK-15 and 25 Breaker Compartment
Fig. 3 Front View AK-50, 75, 100 Breaker Compartment
7. Pull the red knob again and pull the mechanism operating handle four times. The breaker will now be completely inserted, in its connected position.

## Breaker Removal AK-2A

1. Trip the breaker.
2. Move the breaker and inner housing to the fully withdrawn position. (See Breaker Insertion, Steps 1, 2 and 3).
3. Attach lifting device and lift breaker up and away from compartment until primary disconnects clear the compartment.
4. Move the inner housing to the connected position by pushing the tracks back against the track stops and then follow Steps 6 and 7 under Breaker Insertion. The inner housing is now in the connected position and the breaker is free from its compartment.

NOTE: The installation of AK50S/75S/ $100 \mathrm{~S} / \mathrm{AKF2C} / 2 \mathrm{D}$ and breakers equipped with the quick-closing mechanism is the same as the other breakers described in this book. The only difference cccurs with drawout breakers. The compartments that house the quick-close breakers will be equipped with an interlock that prevents the manual discharging of the closing springs while the breaker is in the racked in (connected position). This interlock will be provided with both AKD and AKD5 equipment that require quick-close breakers.

## CONNECTIONS

All electrical connections should be made to assure good conductivity. Mating surfaces shouid be parallel and firmly bolted or clamped together. Contact surfaces should be clean and have a smooth finish. The bus or cable connecting to the breaker should have adequate currentcarrying capacity to prevent excessive heating. Control circuit connections should be made according to the wiring diagram
which applies to each breaker specifically. Depending on the breaker type, those connections are made either to a terminal board on the breaker or to the stationary parts of the secondary disconnects.

## INDIVLDUALLY ENCLOSED AND STATIONARY BREAKERS

The customers external connections for operation of breaker control components and accessories are shown in Fig. 1.

## DRAWOUT BREAKERS

The customers external control connections to these breakers are made to the stationary secondary disconnected $10-$ cated in the breaker compartment as shown In Figs. 2 and 3, AKD Equipment and Fige. 4 and 5 AKD5 Equipment. (Note - If the breaker is used in a General Electric Company, Drawout Switchgear Equipment, all external connections must be made to terminal blocks located in the rear vertical wiring trough of the equipment.)

In closing an AK-1-15/25/50 manual breaker on a load, make the handle movement with a fast, smapping action in order to prevent unnecessary heating of the breaker contacts.

The closing mechanism of the AK-250/75/100 manual breakers is a spring


FRONT VIEW AK-IA-15,25 \& AK-2A-15, 25 BREAKER COMPARTMENT
charged mechantsm simillar to the one used on AK-50/75/100 electrically operated breakers. AK-2-50/75/100 manual breakers are closed by rotating the closing handle counterclockwise through approximately 120 degrees, and then clockwise back through 120 degrees to the normal handie position. Four such complete movements of the handle are required to close the breaker. During the four counterclockwise movements and the first three clockwise movements of the handie, the springs are charged. Aifter approximately 70 degrees travel of the fourth clockwise handle movement, the spring charged mechanism is driven over-center and the breaker closes. A charge-indicator, numbered 1 to 4, viewed through the breaker front escutcheon, moves with each complete handle movement and indicates the number of complete handle movements that have been performed.

## ELECTRICAL CLOSING <br> (Figures 6 and 7)

## STANDARD BREAKERS

AK-15 and AK-25 electrically operated breakers are closed by a solenoid coll. The armature of the solenotd is linked to the breaker mechanism and its movement, operating through the mechanism, closes the breaker. The closing solenoid circuit may be operated by a push button closing switch on the breaker or by a remote switch or relay, depending on the individual arrangements degired. When a closing signal is given, the $X$ relay coil is energized and it in turn closes its contacts. One of these seals in the $X$ coll circult; the other three, which are arranged in series, energtze the solenold closing coll. As the breaker closes, a mechanically operated switch opens one pair of its contacts (bb) and closes another (aa). The contacts which open cut out the $X$ relay coil. The contacts which close energize the $Y$ relay coil, whose contacts now seal in the $Y$ coil and hold open the $X$ relay coll circuit. This prevents another closing operation if one of the protective devices operates to trip the breaker before contact at the closing switch ts released.

Large AK breakers (AK-50/75/100) are closed by the discharge of a closing spring. This rotates a crankshaft which, by means of an attached roller, operates a closing cam, forcing the movable breaker contacts against the stationary contacts. The closing spring is charged through the operation of a motor and gear reduction unit.

The electrical control system is comprised of an $X$ relay, two double contact mechanically operated switches ( $F$ and $G$ ), a push button closing switch and any means for remote closing which the user may incorporate into the system. When voltage is first applled to the breaker, (before any closing signal is given) the motor is energized through two of the $X$ relay contacts and the two $G$ switch contacts. The motor then compreages the closing springs to the "pre-charged" position at which point the mechanically operated $F$ and $G$ switches are operated. This opens the $G$ contacts, atopping the motor, and closes the F contacts, which readies the system for the actual closing of the breaker. When the push button or remote switch signals for a closing operation, the $X$ relay coll is

LEGEND
$X$ a $X$ RELAY COL
$y=X$ RELAY COWTAGT
$Y=Y$ RELAY COH
$Y$


> LEGEMD
> (M) - closing motor - helar coll
> - = RELAY contact
> FBG - MECMANRCALLY OPERATED SWITCHES
> \$ - NORMALLY CPEN SWITGA CONTAGTS
> F MORMALLY CLOSED SWTTEH CONTACTS
> L A AUXILIARY SWITCH CONTACT

Fig. 7 Simplified Elementary Diagrea Internal Wiring $A K-50,75$ and 100
energized, operating the $X$ contacts. This seals in the X relay and energizes the motor once again and the closing operation takes place.

## QUCK CLOSE BREAKERS (Figure 8)

Functionally, the quick close mechanism differs from the standard electrical mechanism in that the pre-charge operation Is extended to completely charge the closing springs. At the end of the charging operation, which takes approximately 5 seconds, a latch plate engages the prop roller to prevent the closing springs from discharging.

With the closing springs fully charged the breaker is ready for a closing operation upon release of the prop roller. This may be accomplished elther manually, by depressing the closing lever on the breaker, or electrically by closing the remote closing switch. Upon the release of the prop roller the closing springs discharge and close the breaker in the same manner as on the standard electrical breaker.

With control voltage applied, the motor Is energized through the G switch contacts, and charges the closing springs. When the springs reach the fully charged position, the mechanically operated switches operate, reversing their contacts. Upon operation of these awitches the motor is stopped by the opening of the G awitch. The closing of the F switch prepares the breaker for a closing operation.

A closing signal now given energizes the control relay $X$ whose contacts close and complete the circult through the closing relay coil. With the closing relay coil energized the breaker closes as described above. At the same time the closing relay contact closes to energize the anti-pump relay causing its contacts to reverse providing the anti-pump feature.

When the breaker closes, the mechanical operated $G$ awitches close to energize the motor again and the $F$ switches open
and de-energize the control relay. The auxiliary switch contact opens preventing the control relay from being energized until the breaker is tripped open. With the $\mathbf{G}$ switches closed, the motor charges the closing springs ready for the next closing operation.

## MANUAL OR MAINTENANCE CLOSING OF ELECTRICAL BREAKERS

All electrical breakers may be closed manually by means of the maintenance handle furnished with the breaker or switchgear.

To close AK-1-15/25 breakers:

1. Make sure handle is in proper position. Handle is stamped this side up.
2. Place the handles fork like fingers above the armatures stop nut that extends below the magnet behind the front escutcheon and lift up. This forces the armature down closing the breaker's contacts.



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To close AK-2-15/25 breakers:

1. Place the two small hooks of the handle into the two slots located in the lower portion of the front escutcheon.

Rotation of the long end of the handle downwards forces the shorter end of the handle upwards against the bottom of the solenoid armature, and cioses the breaker's contacts.

To close AK-50/75/100 breakers:

1. Place the ratchet type maintenance handle on the shaft that protrudes from the gear reduction unit.
2. Operate handle until the apring charge indicator reads charged.
3. Continue to operate handle until the closing springs discharge and close the contacts.

To close AK-50S/75S/100S, AKF 2C, 2D breakers and breakers equipped with the quick closing mechanism:

NOTE: All AKD, or AKD-5 drawout type breakers equipped with the quick closing mechanism cannot normally be closed manually when in the racked in (connected position), due to mechanical designed inter-
ference between the enclosure and the spring discharge lever on the breaker. If manual closing is desired with the breaker racked in, the interference feature must be removed, otherwise the breaker can be manually closed in the test position or fully racked out position only.

1. With the ratchet type maintenance handle applied to the gear box shaft, operate the handle until the springs are fully charged. The fully charged position is indicated by the spring charge indicator and by solid resistance to any further handle operation.
2. Push down on the push to close lever to release the energy stored in the closing springs which closes the breaker's contacts.

## TRIPPING

The breaker is tripped open by the displacement of a mechanism latch, which allows a toggle linkage supporting the movable contacts in the closed position to collapse. This trip latch is fastened rigidly to a trip shaft which runs horizontally from left to right through the breaker. All of the means provided for tripping the breaker operate through striker arms which displace the mechanism trip latch by moving against trip paddles fastened
on the trip shaft. Looking at the breaker from the right, counterclockwise rotation of the trip shaft causes the breaker to trip; clockwise movement resets the mechanism latch. The manual trip button, overload devices, shunt trip, undervoltage tripping device, and reverse current tripall operate In this fashion to trip the breaker. The movement of the striker arims of all of these, when activated, should move from $1 / 32$ to $1 / 16$ inch beyond the polnt at which tripping occurs. This is what is meant by the expression, "positive tripping".

Most air circult breakers are equitped with serles overcurrent trip devices either of the dual magnetic type (instantaneous and time delay tripping) or instantaneous alone. Breakers are designed to carry up to $100 \%$ of the continuous current rating of their trip devices. Any attempt to carry higher currents for a prolonged period will cause overheating and posslble damage.

For a more detailed discussion of the construction, operation, and application of overcurrent trip devices refer to the following publications:

1. Maintenance manual for spectifle breaker Involved (see "Maintenance").
2. "Selection and Application of Power Circuit Breakers" GET-1113.

## TYPE AKU AND BREAKERS WITH FUSE-BREAKER COMBINATIONS

## Open Fuse Lockout Device

This device may be furnished with any of the above type breakers. The open fuse lockout device consists of 3 separately operated devices (one per breaker pole) each wired in parallel to corresponding breaker fuses. These devices are mounted on the
left hand side of the breaker (looking from front). The purpose of this device is to trip the breaker upon the blowing of any one of the breaker fuses. Thls energizes the coll of the device causing the armature to engage the trip paddle, thereby tripping the breaker. Once operated, the armature is latched in the closed alr gap position
allowing the reset button to extend forward indicating which fuse has biown, and slmultaneously holding the breaker in the tripfree position untli the latch cloged armature is released by the operating of the manual reset button.

## MAINTENANCE INSTRUCTIONS

## INSPECTION

BEFORE INSPECTION OR ANY MAINTENANCE WORK IS DONE, BE SURE THAT THE BREAKER IS NN THE OPEN POSITION. ALL ELECTRICAL POWER, BOTH PRLMARY AND CONTROL SOURCES SHOULD ALSO BE DISCONNECTED.

Pertodic inspection of the circuit breaker is recommended at least once a year. More frequent inspections are recommanded, if severe load conditions, dust, molsture, or other unfavorable conditions exist.

Always inspect the breaker after a short clrcuit current has been interrupted.

At the time of ingpection, the following checks should be made after the breaker has been de-energized.

1. Manually operate the breaker several times, checking for obstructions or excessive friction.
2. Electrically operate the breaker several times (if breaker has electrical control) to ascertain whether the electrical attachments are functioning properly.
3. Remove the arc quenchers by removing the channel shaped retaining bar.
4. Inspect arc quenchers and contacts $r$ breakage or excessive burning.

Should arc quencher barriers or contacts be eroded to half their original thickness they should be replaced.

## LUBRICATION

In general, the circult breaker requires moderate lubrication, Bearing polints and sliding surfaces should be lubricated at the regular inspection periods with a thin film of GE Lubricant D50B15. Before lubricating remove any hardened grease and dirt from latch and bearing surfaces with kerosene. ALL EXCESS LUBRICANT SHOULD BE REMOVEDWITH A CLEAN CLOTH TO AVOD ANY ACCUMULATION OF DIRT OR DUST.

On drawout breakers, the contact surface of the disconnect studs should be cleaned and greased with GE Grease Spectification D50H47.

These Instructions have as their purpose the imparting of information of a general nature concerning the installation and operation of Type AK power circult breakers. If more complete and spectific information is required, such as might be needed for overhauling the breaker, trouble shorting, or replacing parts of the breaker, refer to the complete instruction for the particular breaker type involved. These are:

| $\begin{aligned} & \text { Maintenance } \\ & \text { Manual } \end{aligned}$ | Breaker Type |
| :---: | :---: |
| GEI-74602 | AK-1-15, AK-1/1A-25 Man. Operated. |
| GEI-74603 | AK-1-15, AK-1/1A-25 Elec. Operated. |
| GEI-74623 | AKF-1B/1A-25 Man. Oper. |
| GEI-74624 | AKF-1B/1A-25 Elec. Oper. |
| GEI-50299 | $\begin{aligned} & \mathrm{All} \mathrm{AK}-2 / 2 \mathrm{~A}-15 / 25, \mathrm{AKU}- \\ & 2 / 2 \mathrm{~A}-25 \end{aligned}$ |
| GEI-74600 | All AK-1/2/2A-50/75/100, AKU-2/2A-50, AK-2/2A508/75S/1005, AKF-1C/ 2C/1D/2D/2E |

Renewal parts bulletins for the various types of.breakers are:
Bulletin
Breaker Type
GEF-3506
AK-1-15/25 and AKF-1B
GEF-3878 AK-1-50 up to and trcluding dash 9
GEF-3879
GEF-4149
AK-1-75/100

GEF-4150

# AK LOW VOLTAGE POWER CIRCUIT BREAKERS INSTALLATION AND OPERATION 

Types

| AK-1-15 | AK-2-50 | AK-2A-75 | AK-2A-100S |
| :--- | :--- | :--- | :--- |
| AK-1-25 | AK-2-75 | AK-2A-100 | AKF-1A-25 |
| AK-1-50 | AK-2-100 | AK-2-50S | AKF-1B |
| AK-1-75 | AK-1A-25 | AK-2-75S | AKF-1C |
| AK-1-100 | AK-2A-15 | AK-2-100S | AKF-2C |
| AK-2-15 | AK-2A-25 | AK-2A-5S | AKF-1D |
| AK-2-25 | AK-2A-50 | AK-2A-75S | AKF-2D |

LOW VOLTAGE SWITCHGEAR DEPARTMENT


Philadelphia, Pa.

# RECEIVING, HANDLING AND STORAGE 

Before installing, or operating these circuit breakers, make a careful reading of the sections of these instructions which are pertinent to the anticipated work.

Upon receipt of a circuit breaker, immediately make an examination for any damage or loss sustained in shipment. If injury, loss or rough handling is evident, file a damage claim at once with the trans-

## LOCATION

In choosing a location for the installation of an AK Circuit Breaker, there are two factors to be considered. The first of these is the effect of the location on the breaker itself. Much better performance and longer life may be expected if the area is clean, dry, dust-free, and well ventilated, than if the opposites to these conditions exist. The second consideration is convenience for operation and maintenance. The breaker should be easily accessible to the operator, and there should be sufficient space allowed for maintenance work to be done if this becomes necessary.

## MOUNTING

AK Circuit Breakers are designed to be mounted in any one of three ways. These are dead front mounting, individual mounting with the enclosure being provided, and drawout mounting in which the breaker is designed for insertion into a cubicle in drawout equipment such as a substation or control board.

## DEAD FRONT BREAKERS

These breakers are designed for mounting in a switchboard or enclosing case of the customer's design and construction. Mounting in this instance consists of bolting the breaker frame to a supporting structure within the switchboard or enclosure, connecting the power buses or cables, and making any necessary control cónnections. The front cover of the breaker enclosure may be a hinged door or a plate bolted to the panel. In either case, it should have a section cut out, through which the front escutcheon of the breaker may protrude. Outline drawing numbers giving the dimensions needed for preparing a suitable enclosure or cubicle for the various types of AK breakers are given below. These are for standard 2 or 3 pole breakers.
portation company and notify the nearest General Electric Sales Office.

Unpack the circuit breaker as soon as possible after it has been received. Exercise care in the unpacking to avoid damage to the breaker parts. Be sure that no loose parts are missing or left in the packaging material. Blow out any dirt or loose particles of packaging material remaining on/or in the breaker.

## INSTALLATION

| Breaker | Typical Outline Drawing No. |
| :---: | :---: |
| AK-1-15 | 256 C 753 |
| AK-1-25 | 256 C 754 |
| AK-2-15 and 25 | 695 C 116 |
| AK-1-50 Man. Oper. | 248 C 703 |
| AK-1-50 Elec. Oper. | 238 C 123 |
| AK-2-50 S. E. Man. Oper. | 845C281 |
| AK-1-75 | 238 C 192 |
| AK-1-100 | 238 C 193 |
| AK-2-75 Elec. Oper. | 269 C 225 |
| AK-2-75 S. E. Man. Oper. | 845C284 |
| AK-2-100 Elec. Oper. | 269 C 227 |
| AK-2-100 S. E. Man. Oper. | 845C290 |

The surface on which the breaker is mounted must be flat throughout in order not to impose any internal distortion on the breaker unit. The supporting structure must be rigid enough to avoid any possibility of the breaker studs supporting the weight of the breaker. Minimum cutout dimensions, as given by the appropriate outline drawing, must be maintained to provide adequate electrical clearance.

## INDIVIDUALLY ENCLOSED BREAKERS

Individually enclosed breakers are supplied with several types of enclosures, most common is the general purpose type or the weather resistant type. The former is used for favorable indoor locations and the latter for outdoor locations or indoor locations that may be subject to unfavorable conditions. All of the enclosures are provided with suitable means for mounting on walls or supporting framework. Removable cover plates are supplied with the enclosures which may be drilled or machined to accommodate the entrance of bus ducts, conduits or cables. Steps in the procedure for installing enclosed breakers follow:

1. If the breaker is an AK-15, AK-25 or an AK-50, remove it from the enclosure. With AK-50 breakers, a handle and cam arrangement is used for that part of the breaker movement that involves the disengagement or engagement of the primary disconnect. AK-75 and AK-100 breakers

If the circuit breaker is not to be placed in service at once, store it in a clean, dry location in an upright position. Support it to prevent bending of the studs or damage to any of the breaker parts. Do not cover the breaker with any packing or other material which absorbs moisture, that may cause corrosion of breaker parts. A covering of kraft or other non-absorbent paper will prevent dust from settling on the breaker.
are bolted solidly to the enclosure frame and need not be removed from the enclosure.
2. Remove cover plates of enclosure and prepare them toaccommodate whatever power entrance means is used.
3. Mount enclosing case to supporting structure.
4. Replace cover plates and make power connections to stationary terminals in enclosure.
5. If the breaker is a type AK-15, AK- 25 or AK-50 and has been removed from the enclosure, it may now be replaced. Control power connections to the terminal board should be made as required. (See CONNECTIONS).
6. Before energizing the power circuit, operate the breaker several times to be sure that it is functioning properly. (See OPERATION).

## DRAWOUT BREAKERS AKD EQUIPMENT

Mounting drawout breakers consists of simply placing the breaker in the proper position with respect to its enclosure, sliding or rolling it to a stop position, and, by means of a racking handle and mechanism, racking it through the last part of its movement during which the stationary and movable halves of the disconnects engage. Large drawout breakers are fastened to a telescoping tray which extends out from the enclosure to receive the breaker. Small breakers have guides on their side plates which slide in channels in the enclosures. Both large and small breakers have a test position in which the secondary disconnects are engaged, but the primary disconnects are not. In this position, the breaker may be operated electrically without energizing the load cable or bus.

[^10]Use D50H47 lubricant on the disconnect terminals to reduce the force required to insert the breaker.

The procedure for inserting and withdrawing a drawout breaker from its enclosure is as follows:

## Inserting Breaker AK-15 and 25

1. Trip the breaker.
2. Raise the breaker until the guides on the sides of the breaker are level with their mating supporting channels in the enclosure, and slide the breaker part way into its enclosure. (Note - The breaker will be obstructed by a position stop at the bottom of the enclosure after the breaker has traveled only a short distance into the cubicle. Lift the position stop handle, located at the bottom right of the enclosure, which will release the position stop and allow the breaker to travel further into the cubicle).
3. Raise the rackout handle forward and up as far as its travel will permit and push the breaker into the enclosure until the rackout pins on the handle assembly bear against the housing rackout cams on the side of the enclosing case.
4. Push downward on the rackout handle forcing the pins on the handle up into the slot in the stationary cam plate. This action forces the breaker through a final short portion of its movement into the enclosure and allows the operator to provide the force necessary to make the primary disconnects engage the stationary studs in the enclosure. In performing this operation, make sure that the handle is rotated downwards as far as its free travel will permit and then pull the racking handle down to be sure the trip interlock is released. (Note - When the racking handle is in any position other than completely down, the breaker cannot be operated and is held trip-free by the trip interlock. This applies to the "fully in" and "test" positions.)

## Withdrawing Breaker AK-15 and 25

1. Trip the breaker open. If the breaker is not open, the interlock lever of the drawout mechanism will not permit operation of the rackout handle.
2. Pull the racking handle up and forward as far as it will travel, disengaging the primary disconnects.
3. Slide the breaker out until the position stop engages in the front slot in the bottom of the breaker carriage. The breaker is now in the "test" position, where its primary disconnects are safely disconnected from the line and load terminals of the enclosure. (Note - Refer to section describing "Test Position" in these instructions.)
4. To remove the breaker from its enclosure, lift the position stop handle and slide the breaker forward until the position stop engages the rear slot in the bottom of the breaker carriage. This is the safety position stop where both the primary and
secondary contacts are disengaged. Again lift the position stop handle. Slide the breaker slightly forward to remove it from the enclosure.

## Inserting Breaker AK-50, 75 and 100

1. Lift the breaker to a position approximately six inches above the height of the compartment tray,
2. Pull the drawout tray out under the breaker as far as the tray will travel. NOTE - When installing an individual skeleton housing for a drawout AK-50 or 75, locate a bolt head over the two front bottom mounting holes of the housing to provide a limit stop for the drawout tray.
3. Lower the breaker about $1 / 2^{\prime \prime}$ above the dowel pins on the tray and push the breaker back into its compartment so that the rear bottom angle of the breaker is against the guides on the tray directly back of the dowel pins.
4. Slowly lower the breaker onto the tray and at the same time guide it so that the holes in the rear angle of the breaker fit over the two dowel pins on the tray. If the breaker is correctly positioned on the dowels, its rear and side bottom frame angles will all sit firmly on the tray.
5. Insert two $3 / 8$ inch hex. head screws through the holes in the front of the side angles on the breaker and thread them part way into the tapped holes in the tray. Do not tighten screws firmly. This provides better alignment of the primary stationary studs and the primary disconnects for the subsequent racking operation.
6. Push the breaker into the compartment until the "test" position stop engages to prevent further travel. (Note - Refer to section describing "Test Position" in these instructions.)
7. Release the test position stop by depressing its lever and push the breaker back into the compartment until the racking pins on the housing butt against the outer surface of the racking cam. In this position, the racking pin has lifted the locking arm on the cam which allows the racking handle to be lifted enough to allow the pawl to engage the first notch on the cam.
8. When the pawl engages the first notch on the cam, push the handle down again to its normal position. This causes the cam to rotate about the racking pin. Repeat this operation five times to rack the breaker into its final operating position. Interlocks hold the breaker trip free until it is racked into the fully contacted position. The fifth stroke of the handle is only a partial stroke and does not result in any further movement of the breaker. It does serve three useful purposes: it positions the cam so that it cannot rotate and allow the breaker to back out under short circuit stresses; the partial stroke signals that the racking operation is complete, and it releases the trip interlock which was engaged by the racking pin during the previous four pumps of the racking arm. NOTE: Once a racking operation has been started, it must be completed, as the breaker cannot be reversed until the racking operation is completed.
9. After completing the fifth racking stroke, lift the handle as high as it will go and allow it to drop to its normal position. NOTE: Any strokes beyond this point will
cause the breaker to be trip free. Tighten the $3 / 8$ inch hex head screws inserted in the front holes of the drawout tray during step 5 of this operation. The breaker is now in the operating position.

Withdrawing Breaker AK-50, 75 and 100

1. Trip the breaker to release the positive racking interlock.
2. Lift the racking handle as far as it will go.

This operation will re-engage the trip interlock to hold the breaker trip-free for the remainder of the racking operation. Note that here the cam is rotated by lifting the handle, whereas in racking the breaker in , the operation is performer as a result of pushing the handle down.
3. Reset the handle to its lowered position and lift it again. This operation must be performed 5 times to completely disengage the cams from their racking pins. After the fifth lifting stroke let the handle drop to its normal position.
4. Pull the breaker out of its compartment until the test position stop engages to hold the breaker in the "test" position.
5. Depress the test position stop handle and pull the breaker out of its compartment as far as the drawout tray will travel.
6. Remove the two $3 / 8$ hex. head screws which hold the breaker on the tray.
7. Attach a lifting device to the top frame of the breaker.
8. Lift the breaker approximately $1 / 2$ inch off the dowel pins on the tray and then pull the breaker forward until its primary contacts clear the compartment.
9. Push the tray all the way back into its compartment. The breaker is now free from its compartment.

## TEST POSITION

The "Test Position", as referred to in the previous instructions, is that breaker position where the primary power disconnect contacts are safely disengaged but the secondary control disconnects are engaged. In this position, the breaker may be tested or operated, manually or electrically without energizing the primary power circuit, provided the racking handle has been moved to the completely down position, thus releasing the trip interlock.

For a more complete description of drawout mechanisms and enclosures see AKD DRAWOUT EQUIPMENT INSTRUCTIONS, GEH-1830 and AKD5 Drawout Equipment Instructions GEH-83902.

## DRAWOUT BREAKERS AKD5 EQUIPMENT

NOTE: AKD5 breakers are identified by letter "A" appearing after breaker number example, "AK-2A-15".

Drawout Mechanism Operation - There are four positions of the drawout mechanism:

1. The Connected Position - the breaker in the operating position, both primary and secondary contacts made and the door may be closed.
2. The Test Position - the primary (power) contacts not made but the secondary (control) contacts are made. Any breaker test not involving power maybe made in this position. The door may be closed in this position.
3. Disconnect Position-neither the primary nor the secondary contacts made. The door may be closed.
4. Fully Withdrawn Position - the breaker completely out of its compartment ready for removal from the inner housing. The door must be open in this position.

NOTE: The mechanism is designed to reverse automatically in the connect and fully disconnected position. Once an operation is started it must be completed. Completion of an operation is Indicated by the red knob retracting to its original position.

Breaker Insertion AK-2A - With the inner housing in the connected position proceed as follows:

1. Pull the red knob. Pull the mechanism operating handle fully out and allow it to return to its original position. Repeat this three more times. The inner house is now in the test position.
2. Pull the red knob again. Pull the mechanism operating handle two complete strokes drawing the inner housing to the disconnect position.


Fig. 1 (Front View)
3. Open the housing door and rotate the two track lock links, releasing the tracks. Pull the tracks out to the limit of their travel. This is the fully withdrawn position.
4. With a lifting device, ralse the breaker so the mounting pins are about one inch above the tracks. Lower breaker 80 the breaker mounting pins drop into the slots in the tracks. Remove the lifting device cable.
5. Push the breaker in against the track stops. Rotate the two lock links to lock the breaker in place. Close the door.
NOTE: When moving a breaker from one position to another be sure breaker is tripped open.
6. Pull the red knob. Pull the mechanism operating handle two times untll the test position is reached.


Fig. 2 Front View AK-15 and 25 Breaker Compartment
Fig. 3 Front View AK-50, 75, 100 Breaker Compartment
7. Pull the red knob again and pull the mechanism operating handle four times. The breaker will now be completely inserted, in its connected position.

## Breaker Removal AK-2A

1. Trip the breaker.
2. Move the breaker and inner housing to the fully withdrawn position. (See Breaker Insertion, Steps 1, 2 and 3).
3. Attach lifting device and lift breaker up and away from compartment until primary disconnects clear the compartment.
4. Move the inner housing to the connected position by pushing the tracks back against the track stops and then follow Steps 6 and 7 under Breaker Insertion. The inner housing is now in the connected position and the breaker is free from its compartment.

NOTE: The installation of AK50S/75S/ 100S/AKF2C/2D and breakers equipped with the quick-closing mechanism is the same as the other breakers described in this book. The only difference occurs with drawout breakers. The compartments that house the quick-close breakers will be equipped with an interlock that prevents the manual discharging of the closing springs while the breaker is in the racked in (connected position). This interlock will be provided with both AKD and AKD5 equipment that require quick-close breakers

## CONNECTIONS

All electrical connections should be made to assure good conductivity. Mating surfaces should be parallel and firmly bolted or clamped together. Contact surfaces should be clean and have a smooth finish. The bus or cable connecting to the breaker should have adequate currentcarrying capacity to prevent excessive heating. Control circuit connections should be made according to the wiring diagram
which applies to each breaker specifically. Depending on the breaker type, those connections are made either to a terminal board on the breaker or to the stationary parts of the secondary disconnects.

## INDIVIDUALLY ENCLOSED AND STATIONARY BREAKERS

The customers external connections for operation of breaker control components and accessories are shown in Fig. 1.

## DRAWOUT BREAKERS

The customers external control connections to these breakers are made to the stationary secondary disconnected located in the breaker compartment as shown in Figs. 2 and 3, AKD Equipment and Figs. 4 and 5 AKD5 Equipment. (Note - If the breaker is used in a General Electric Company, Drawout Switchgear Equipment, all external connections must be made to terminal blocks located in the rear vertical wiring trough of the equipment.)

## OPERATION

AK-2-15/25 and AK-1-50 manually operated breakers are closed by turning the handle 90 degrees counterclockwise and then clockwise 90 degrees back to the original position. The initial counterclockwise movement resets the closing mechanism. The clockwise movement closes the breaker.

In closing an AK-1-15/25/50 manual breaker on a load, make the handle movement with a fast, snapping action in order to prevent unnecessary heating of the breaker contacts.

The closing mechanism of the AK-2$50 / 75 / 100$ manual breakers is a spring

charged mechanism similar to the one used on AK-50/75/100 electrically operated breakers. AK-2-50/75/100 manual breakers are closed by rotating the closing handle counterclockwise through approximately 120 degrees, and then clockwise back through 120 degrees to the normal handle position. Four such complete movements of the handle are required to close the breaker. During the four counterclockwise movements and the first three clockwise movements of the handle, the springs are charged. After approximately 70 degrees travel of the fourth clockwise handle movement, the spring charged mechanism is driven over-center and the breaker closes. A charge-indicator, numbered 1 to 4, viewed through the breaker front escutcheon, moves with each complete handle movement and indicates the number of complete handle movements that have been performed.

## ELECTRICAL CLOSING

(Figures 6 and 7)

## STANDARD BREAKERS

AK-15 and AK-25 electrically operated breakers are closed by a solenold coll. The armature of the solenoid is linked to the breaker mechanism and its movement, operating through the mechanism, closes the breaker. The closing solenold circult may be operated by a push button closing switch on the breaker or by a remote switch or relay, depending on the individual arrangements desired. When a closing signal is given, the X relay coil is energlzed and it in turn closes its contacts. One of these seals in the $X$ coll circuit; the other three, which are arranged in series, energize the solenoid closing coll. As the breaker closes, a mechanically operated switch opens one pair of its contacts (bb) and closes another (aa). The contacts which open cut out the $X$ relay coil. The contacts which close energize the $Y$ relay coll, whose contacts now seal in the $Y$ coll and hold open the $X$ relay coil circuit. This prevents another closing operation if one of the protective devices operates to trip the breaker before contact at the closing switch is released.

Large AK breakers (AK-50/75/100) are closed by the dlscharge of a closing spring. This rotates a crankshaft which, by means of an attached roller, operates a closing cam, forcing the movable breaker contacts against the stationary contacts. The closing spring is charged through the operation of a motor and gear reduction unit.

The electrical control system ts comprised of an X relay, two double contact mechanically operated switches ( $F$ and G), a push button closing switch and any means for remote closing which the user may incorporate into the system. When voltage is first applied to the breaker, (before any closing signal is given) the motor is energized through two of the $X$ relay contacts and the two $\mathbf{G}$ switch contacts. The motor then compresses the closing springs to the "pre-charged" position at which point the mechanically operated $F$ and $G$ switches are operated. Thls opens the G contacts, stopping the motor, and closes the $F$ contacts, which readies the system for the actual closing of the breaker. When the push button or remote switch signals for a closing operation, the $X$ relay coll is


Fig. 7 Simplified Elementary Diagram Internal Hiring AK-50, 75 and 100
energized, operating the $\mathbf{X}$ contacts. This seals in the X relay and energizes the motor once again and the closing operation takes place.

## QUICK CLOSE BREAKERS (Figure 8)

Functionally, the quick close mechanism differs from the standard electrical mechanism in that the pre-charge operation is extended to completely charge the closing springs. At the end of the charging operation, which takes approximately 5 seconds, a latch plate engages the prop roller to prevent the closing springs from discharging.

With the closing springs fully charged the breaker is ready for a closing operation upon release of the prop roller. This may be accomplished either manually, by depressing the closing lever on the breaker, or electrically by closing the remote closing switch. Upon the release of the prop roller the closing springs discharge and close the breaker in the same manner as on the standard electrical breaker.

With control voltage applied, the motor is energized through the G switch contacts, and charges the closing springs. When the springs reach the fully charged position, the mechanically operated switches operate, reversing their contacts. Upon operation of these switches the motor is stopped by the opening of the $G$ switch. The closing of the $F$ switch prepares the breaker for a closing operation.

A closing signal now given energizes the control relay $X$ whose contacts close and complete the circuit through the closing relay coil. With the closing relay coil energized the breaker closes as described above. At the same time the closing relay contact closes to energize the anti-pump relay causing its contacts to reverse providing the anti-pump feature.

When the breaker closes, the mechanical operated $G$ switches close to energize the motor again and the $F$ switches open
and de-energize the control relay. The auxilitary switch contact opens preventing the control relay from being energized until the breaker is tripped open. With the G switches closed, the motor charges the closing springs ready for the next closing operation.

## MANUAL OR MAINTENANCE CLOSDNG

 OF ELECTRICAL BREAKERSAll electrical breakers may be closed manually by means of the malntenance handle furnished with the breaker or switchgear.

## To close AK-1-15/25 breakers:

1. Make sure handle is in proper position. Handle is stamped this side up.
2. Place the handles fork like fingers above the armatures stop nut that extends below the magnet behind the front escutcheon and lift up. This forces the armature down closing the breaker's contacts.


To close AK-2-15/25 breakers:

1. Place the two small hooks of the handle into the two slots located in the lower portion of the front escutcheon.
2. Rotation of the long end of the handle downwards forces the shorter end of the handle upwards against the bottom of the solenoid armature, and closes the breaker's contacts.

## To close AK-50/75/100 breakers:

1. Place the ratchet type maintenance handle on the shaft that protrudes from the gear reduction unit.
2. Operate handle until the spring charge indicator reads charged.
3. Continue to operate handle until the closing springs discharge and close the contacts.

To close AK-50S/75S /100S, AKF 2C, 2D breakers and breakers equipped with the quick closing mechanism:
NOTE: All AKD, or AKD-5 drawout type breakers equipped with the quick closing mechanism cannot normally be closed manually when in the racked in (connected position), due to mechanical designed inter-

## INSPECTION

BEFORE INSPECTION OR ANY MAINTENANCE WORK IS DONE, BE SURE THAT THE BREAKER IS IN THE OPEN POSITION. ALL ELECTRICAL POWER, BOTH PRIMARY AND CONTROL SOURCES SHOULD ALSO BE DISCONNECTED.

Periodic inspection of the circuit breaker is recommended at least once a year. More frequent inspections are recommended, if severe load conditions, dust, moisture, or other unfavorable conditions exist.

Always inspect the breaker after a short circuit current has been interrupted.

At the time of inspection, the following checks should be made after the breaker has been de-energized.

1. Manually operate the breaker several times, checking for obstructions or excessive friction.
2. Electrically operate the breaker several times (if breaker has electrical control) to ascertain whether the electrical attachments are functioning properly.
3. Remove the arc quenchers by removing the channel shaped retaining bar.
4. Inspect arc quenchers and contacts for breakage or excessive burning.


# AK AIR CIRCUIT BREAKERS INSTALLATION AND OPERATION 

## Types

| AK-1-15 | AKF-1C |
| :--- | :--- |
| AK-1-25 | AKF-1D |
| AK-1-50 | AK-2-15 |
| AK-1-75 | AK-2-25 |
| AK-1-100 | AK-2-75 |
| AKF-1B | AK-2-100 |

LOW VOLTAGE Switchgear departmeat

# INSTALLATION AND OPERATION OF TYPE AK AIR CIRCUIT BREAKER 

## INSTALLATION

## LOCATION

In choosing a location for the installation of an Air Circuit Breaker, there are two factors to be considered. -The first of these is the effect of the location on the breaker itself. Much better performance and longer life may be expected if the area is clean, dry, dust-free, and well ventilated, than if the opposites to these conditions exist. The second consideration ts conventence for operation and maintenance. The breaker should be easily accessible to the operator, and there should be sulficient space allowed for maintenance work to be done if this becomes necessary.

## MOUNTING

AK AIr Circuit Breakers are designed to be mounted in any one of three ways. These are dead front mounting, individual mounting with the enclosure being provided, and drawout mounting in which the breaker is designed for insertion into a cubicle in drawout equipment such as a substation or control board.

## Dead Front Breakers

These breakers are designed for mounting in a switchboard or enclosing case of the customer's design and construction. Mounting in this instance consists of bolting the breaker frame to a supporting structure within the switchboard or enclosure, connecting the power buses or cables, and making whatever control connections are necessary. The front cover of the breaker enclosure may be a hinged door or a plate bolted to the panel. In either case, it should have a section cut out, through which the front escutcheon of the breaker may protrude. Outline drawings giving the dimensions needed for preparing a suitable enclosure or cubicle for the various types of AK breakers are given below. Theseare for standard 2 or 3 pole breakers.

Breaker Outline Drawing No.

## AK-1-15

$256 \mathrm{C753}$
AK-1-25
256 C 754
AK-1-50 man. oper.
248C703
AK-1-50 elec. oper.
238 C 123
AK-1-25
AK-1-100
238 C 192
238C193

Breaker
AK-2-15 and 25
AK-2-75
AK-2-100
The suriace on which the breaker is mounted must be flat throughout in order not to impose any internal distortion on the breaker unit. The supporting structure should be rigid enough to avoid any possibility of the breaker studs supporting the weight of the breaker. Minimum cutout dimensions, as given by the appropriate outline drawing, must be maintained to provide adequate electrical clearance.

## Individually Enclosed Breakers

Individually enclosed breakers are supplied with several types of enclosures, most commonly with the general purpose type or the weather resistant type. The former is used for favorable indoor locallons and the latter for outdoor locations or indcor locations that may be subject to unfavorable conditions. All of the enclosures are provided with suitable means for mounting on floors, walls or supporting framework. Removable cover plates are supplied with the enclosures which may be drilled or machined to accommodate the entrance of bus ducts, condults or cables. Steps in the procedure for installing enclosed breakers follow:

1. If the breaker is an AK-15, AK-25 or an AK-50, remove it from the enclosure. With AK-50 breakers, a handle and cam arrangement is used for that part of the breaker movement that involves the disengagement or engagement of the primary disconnects. AK-75 and AK-100 breakers are bolted solidly to the enclosure frame and need not be removed from the enclosure.
2. Remove cover plates of enclosure and prepare them to accommodate whatever power entrance means is used.
3. Mount enclosing case to supporting structure.
4. Replace cover plates and make power connections to stationary terminals In enclosure.
5. If enclosure is of a type that makes use of secondary disconnects, make control
connections to stationary parts of the disconлесts.
6. If the breaker is a type AK-15, AK-25 or AK-50 and has been removed from the enclosure, it may now be replaced. Control power connections to the terminal board should be made if and as required. (See CONNECTIONS).
7. Before energizing the power circult, operate the breaker several times to be sure that it is functioning properly. (See OPERATION).

## Drawout Breakers

Mounting drawout breakers consists of simply placing the breaker in the proper position with respect to its enclosure, sliding or rolling it to a stop position, and, by means of a racking handle and mechanism, racking it through the last part of its movement during which the stationary and movable halves of the disconnects engage. Large drawout breakers are fastened to a telescoping tray which extends out from the enclosure to receive the breaker. Small breakers have guides on their side plates which slide in channels in the enclosures. Both large and small breakers have a test position in which the secondary disconnects are engaged, but the primary disconnects are not. In this position, the breaker may be operated electrically without energizing the load cable or bus.

For a more complete description of drawout mechanisms and enclosures see DRAWOUT EQUIPMENT INSTRUCTIONS, GEH-1830.

## CONNECTIONS: Figure 1

All electrical connections should be made with a view toward good conductivity. Mating surfaces should be parallel and firmly bolted or clamped together. Contact surfaces should be clean and have a smooth finish. The bus or cable connecting to the breaker should have adequate current-carrying capacity to prevent excessive heating. Control circuit connections should be made according to the wiring diagram which applies to each breaker specifically. Depending on the breaker type, these connections are made elther to a terminal board on the breaker or to the stationary parts of secondary disconnects.

These instructions do not purport to cover all detaids or variations in equipment nor to provide for every possible contingency to be met in connection with installation, operation or maintenance. Should further information be dasired or should particulor problems ariso which ore not covered sufficiently for the purchoser's purposes, the matter should be referred to the General Eloclric Compony.


EXTERNAL CONNECTIONS FOR OPERATION OF BREAKER CONTROL COMPONENTS AND ACCESSORIES

Figure 1

## OPERATION

## MANUAL CLOSNAG

AK-1-15 and AK-1-25 Breakers are ed by rotating the breaker handle in a ..uckwise direction approximately 90 degrees from its normal vertical position. Ater tripping, the closing mechanism rets automatically by means of springs.
-2-15/25 and AK-50 manually operated .eakers are closed by turning the handle counterclockwise and then clockwise back to the original posittion, again through about 80 degrees. The Inittal counterclockwise movement resets the closing mechanism.

In closing an AK-1-15/25/50 manual breaker on a load, it is desirable to make the handle movement with a reasonably tast, snapping action in order to prevent annecessary heating of the breaker contacts.

## ELECTRICAL CLOSING: Figures 2A and2b

AK-15 and AK-25 electrically operated breakers are closed when a closing solenold coll is energized. The magnetic force generated by the solenoid moves an armahure into the solenoid coil. The armature ls linked to the breaker mechanism and its movement, operating through the mechaalsm, closes the movable contacts against the stationary contacts of the breaker. The closing solenoid circuit may be closed by a push button closing switch on the breaker or by a remote swiltch or relay, depending on the Individual arrangements desired. When a closing signal is given, the $\mathbf{X}$ relay coll is energized and it in turn closes its lour sets of contacts. One of these seals In the $X$ coll circult; the other three, which are arranged in series, energize the colenold closing coil. As the breaker closes,
zechanically operated switch opens one .r of its contacts (bb) and closes another (aa). The contacts which open cut out the $x$ relay coll. The contacts which close prgize the $Y$ relay coll, whose contacts


LEGENO
$X \cdot x$ helay coll
P - X RELAY CONTACT
y y relar corl
$y$ - Y RELAY CONTACT
41-कも MECHANICALLY OPERATED SWITCHES
t = MORMALLY OPEN SWITCH CONTAETS

- MORDALLY CLOSED SWITCH CONTACTS

SIMPLIFIEO ELEMENTARY DIAGRAM
INTERNAL WIRING AK-I-I5 AND 23

## Figure 24

now seal in the $Y$ coil and hold open the $X$ relay coil circuit. This prevents another closing operation if one of the protective devices operates to trip the breaker before contact at the closing switch is released.

Large AK breakers (AK-50/75/100) are closed by the discharge of a closing spring. This rotates a crankshaft which, by means of an attached roller, operates a closing cam, forcing the movable breaker contacts against the stationary contacts. The closing spring is charged through the operation of a motor and gear reduction unit.

On breakers other than drawout breakers, external control connections are made to a vertical 10 point terminal board on stationary dead Iront and Individually enclosed breakers. Numbering the points from 1 to 10 , from the top to the bottom, connections are made as follows: Closing voltage is applied between 3 and 4; tripping voltage between 6 and 7. An external closing switch may be connected between 1 and 5. If the breaker has an undervoltage tripping device, the voltage for this is applied between 8 and 9. If the breaker is a DC breaker and has a reverge current device, DC voltage is applied between terminal 10 and the " $a$ " contact of the second stage from the right of the auxiliary switch. The negative lead is connected to terminal post 10. If the breaker is a small AK type (AK-15/25), the terminal board is on the right side of the breaker and connections are made to the right side of the board, Eractly the reverse of this is true if the breaker is a large AK type (AK-50/75/100).


> LEEGEND = CLOSNG MOTOR $X$ - RELAY COIL - RELAY CONTACT

FEG * mechanically operated switches
† - NORMALLY OPEN SWITCH CONTACTS
f - normally closed switch contagts

SIMPLIFIED ELEMENTARY DIAGRAM
INTERNAL WIAING AK-i-50,75, AND 100

Figure 28

The electrical control system ts com-
prised of an $X$ relay, two double contact mechanically operated switches ( $F$ and $G$ ), a push button closing switch and any means for remote closing which the user may incorporate into the system. When voltage is IIrst applied to the breaker, (before any closing signal is given) the motor is energized througis two of the $X$ relay contacts and the two $G$ switch contacts. The motor then compresges the closing springs to the . "pre-charged" position at which point the mechanically operated $F$ and $G$ switches. are operated.

This opens the $\mathbf{G}$ contacts, stopping the motor, and closes the $F$ contacts, which readites-texe syotem for the actual closing I the breaker. When the push button or ?mote switch signals for a closing operaNon, the $X$ relay coil is energized, operating the $X$ contacts. This seals in the $X$ relay and energizes the motor once again and the plosing operation takes place. Closing gatn operates the $F$ and $G$ switches so cheir contacts again assume their original position and the motor continues to run until the "pre-charged" position is reached.

## TRIPPING

The breaker is tripped open by the displacement of a mechanism latch, which allows a toggle innkage supporting the movable contacts in the closed position to collapse. This trip latch is fastened rigidly to a trip shaft which runs horizontally from left to right through the breaker. All of the means provided for tripping the breaker operate through striker arms which displace the mechanism trip latch by moving against
trip paddles fastened on the trip shaft. Looking at the breaker from the right, counterclockwise rotation of the trip shaft causes the breaker to trip; clockwise movement resets the mechanism latch. The manual trip button, overload devices, shunt trip, undervoltage tripping device, and reverse current trip all operate in this fashion to trip the breaker. The movement of the striker arms of all of these, when activated, should have at least a perceptible amount of movement beyond the point at which tripping occurs. This is what is meant by the expression, "positive tripping".

Moat air circuit breakers are equipped with serles overcurrent trip devices either of the dual magnetic type (Instantaneous and time delay tripping) or instantaneous alone. Breakers are designed to carry up to $100 \%$ of the continuous current rating of their trip devices. Any attempt to carry higher currents for a prolonged period will cause overheating and possible damage.

Breakers are usually shlpped with the plckups of the trip devices set at $100 \%$ of
coll rating. To get best protection and to avoid nulsance tripping from a fluctuating load, it is generally recommended that the plekup be set at $125 \%$ of the actual steady state load current. For example, a breaker rated at 1200 amperes continuous current with a 1000 ampere load should have its trip device set to pick up at 1250 amperes. (Slightly above the $100 \%$ calibration mark on the trip scale plate of the device).

For a more detalled discussion of the construction, operation, and application of overcurrent trip devices refer to the following publications:

1. Instruction Blook for specific breaker involved (see "Maintenance").
2. "Selection and Application of Air Circuit Breakers" GET-1113.
3. "Overcurrent Trip Device - Type EC-2" GEI-50216. This applies only to trip devices on AK-15/25/50 breakers.

## MAINTENANCE INSTRUCTIONS

These instructions have as their purpose the imparting of information of a general nature concerning the installation and operation of type AK air circuit breakers. If more complete and speciftc information is required, such as might be needed for overhauling the breaker, trouble shooting, or replacing parts of the breaker,

refer to the complete instruction for the particular breaker type involved. These are:

| Instruction |
| :---: |
| Book |
| GEH-1824 |
| GEH-1807 |
| GEH-1799 |
| GEH-1798 |
| GEH-1823 |
| GEH-1831 |
| GEH-1832 |
| GEH-50210 |
| GEH-50212 |
| GEI-50299 |
| GEI-57077 |

## Breaker Type

AK-1-15 or 25 man. oper.
AK-1-15 or 25 elec. oper.
AK-1-50 man. oper.
AK-1-50 elec. oper.
AK-1-75 or 100
AKF-1B man. oper.
AKF-1B elec. oper.
AKF-1C
AKF-1D
AK-2-15/25
AK-2-75/100

Renewal parts bulletins for the various types of breakers are:

| Buletin | Breaker Type |
| :--- | :--- |
| GEF-3506 | AK-1-15/25 and AKF-1B |
| GEF-3878 |  |
| GEF-3879 | AK-1-50 |
|  |  |



## POWER CIRCUIT BREAKERS

Types AK-1-15-3 to 10 and AK-1-25-3 to 10 Manually Operated



LOW VOLTAGE SWITCHGEAR DEPARTMENT

philadelffita, pa.

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# POWER CIRCUIT BREAKER TYPES AK-1-15-3 TO 10 AND AK-1-25-3 TO 10 MANUALLY OPERATED INTRODUCTION 

The instructions contained herein provide information for performing maintenance procedures and for replacing AK-1-15/25 breaker components and accessories. For information regarding the receiving, handling, storage and installation of these breakers, refer to GEH-2021A, furnished with all AK breakers.

The AK-1-15 and AK-1-25 breakers differ, in that, the AK-1-25 has an extra contact per pole with corresponding differences in the upper stud and interrupter.

As various design improvements and new features were added, the suffix digit of the breaker type number was progressively increased. All of these models are essentially the same breaker, as changes were mainly of a minor nature. These are tabulated below:

AK-1-15/25-3 Basic model
AK-1-15/25-6 Stationary primary disconnects and cable clamp redesigned. (Only enclosed breakers affected).

AK-1-15/25-7 New type of front escutcheon and closing handle. Trip button relocated on escutcheon and reset lever for bell alarm and lockout device changed.

AK-1-15/25-8 EC-2 overcurrent device used instead of the EC-1 device except on units requiring short-time delay tripping.

AK-1-15/25-9 New drawout frame introduced.
NOTE: Suffix digit number changes which do not appear above do not apply to manual breakers.


1. Arc Quencher
2. Operating Handle
3. Clamp
4. Main Shaft
5. Trip Button
6. Trip Paddle
7. Position Indicator
8. Front Escutcheon
9. Grounding Strap
10. Series Overcurrent Device

Fig. I Oblique Left View of AK-1-25 Breaker

## OPERATION

## MANUAL - FIG. 1

The breaker may be closed manually by rotating the operating handle (6) 90 in the clockwise direction. After the breaker closes the operating handle is returned to its normal position by a spring force. This breaker may be tripped manually by the trip
button (7), or automatically by any of the tripping devices with which the breaker may be equipped. The mechanism is automatically reset when the breaker trips, however, the breaker is "trip-free" from the closing mechanism which assures that it cannot be closed as long as any tripping device is functioning.

MAINTENANCE

## INSPECTION

BEFORE INSPECTION OR ANY MAINTENANCE WORK IS DONE, BE SURE THAT THE BREAKER IS

IN THE OPEN POSITION. ALL ELECTRICAL. POWER, BOTH PRIMARY AND CONTROL SOURCES, SHOULD ALSO BE DISCONNECTED.

[^11]Periodic inspection of the circuit breaker is recommended at least once a year. More frequent inspections are recommended, if severe load conditions, dust, moisture, or other unfavorable conditions exist.

If the breaker remains open or closed for a long period of time, it is recommended that arrangements be made to open and close it several times in succession, preferably under load.

At all times it is important not to permit pencil lines, paint, oil or other foreign materials to remain on the insulating surfaces of the breaker as they may cause low resistance between points of different potential and result in eventual electrical breakdown.

Always inspect the breaker after a short circuit current has been interrupted.

At the time of periodic inspection, the following checks should be made after the breaker has been de-energized.

1. Manually operate the breaker several times, check for obstructions or excessive friction.
2. Arc quencher (see Section on "Arc Quencher").
3. Contact condition, wipe, and pressure (See Section on "Pole Unit Assembly").
4. Latch engagement (See Adjustments under "Operating Mechanism").
5. Overcurrent device tripping (See Adjustments under "Series Overcurrent Tripping Device").

## TOOLS

The tools listed below will adequately equip an operator for any maintenance operation on all Type $\mathrm{AK}-1-15$ and 25 Breakers:

\#1 Phillips Screw Driver<br>\#2 Phillips Screw Driver with 8" shaft<br>\#3 Phillips Screw Driver<br>K101-1/2 Crescent (Short) Screw Driver<br>K505-1/2 Crescent (Long Thin) Screw Driver<br>K306 Crescent (Standard) Screw Driver

H-28 $8^{\prime \prime}$ Gas Pliers
654 Pointed Nose Side Cutting 6" Pliers
\#2 Waldes Truarc Pliers Straight
*2 Waldes Truarc Pliers $90^{\circ}$ Angle

Ratchet Socket Wrench 1/2" Drive
7/16" - 1/2" Drive Socket
$9 / 16^{\prime \prime} \quad$ - $1 / 2^{\prime \prime}$ Drive Socket
5/8" - 1/2" Drive Socket
3/4" - 1/2" Drive Socket
13/16" - 1/2" Drive Socket
15/16" - 1/2" Drive Socket

10" Extension Bar 1/2" Drive
6" Extension Bar 1/2" Drive
8" Adjustable End Wrench
1/4" - 5/16" (Blue Point) Open End Wrench
$1 / 2^{\prime \prime}$ - 9/16" Open End Wrench
$5 / 8^{\prime \prime}-3 / 4^{\prime \prime}$ Open End Wrench
$3 / 8^{\prime \prime}-7 / 16^{\prime \prime}$ Open End Wrench
11/32" - 5/16" Open End Wrench
1/16" Allen Head Wrench for \#6 Screw
5/64" Allen Head Wrench for \#8 Screw
3/32" Allen Head Wrench for \#10 Screw
$1 / 8^{\prime \prime} \quad$ Allen Head Wrench for $1 / 4^{\prime \prime}$ Screw
5/16" Straight Shank Allen Head Wrench for 3/8" screw, with adapter for $1 / 2^{\prime \prime}$ drive ratchet

8 oz . Ball peen hammer
5/8" 6 point open box wrench
3/8" Spintite
NOTE: Obtain from local hardware, do not order on General Electric Company.

## LUBRICATION

In general, the circuit breaker requires moderate lubrication. Bearing points and latch surfaces should be lubricated at the regular inspection periods with a thin film of extreme temperature, high-pressure, light grease similar to G. E. Spec. No. D50H15. Hardened grease and dirt should be removed from latch and bearing surfaces by using kerosene. ALL EXCESS LUBRICANT SHOULD BE REMOVED WITH A CLEAN CLOTH IN ORDER TO AVOID ANY ACCUMULATION OF DIRT OR DUST.

At each maintenance period, all silver to silver friction points, such as primary disconnects, should be cleaned and given a fresh coat of G. E. Spec. No. D50H47 lubricant.

| TROUBLE | CAUSE | REMEDY |
| :---: | :---: | :---: |
| Overheating | Contacts not allgned. <br> Contacts dirty, greasy or coated with dark fllm. <br> Contacts badly burned or pitted. <br> Current carrying surfaces dirty. <br> Bolts and nuts at terminal connection not tight. <br> Current in excess of breaker rating. <br> Excessive amblent temperature. | Adjust contacts. <br> Clean contacts. <br> Replace contacts. <br> Clean surfaces of current carrying parts. <br> Tighten, but do not exceed elastic limitt of bolts or fittings. <br> Decrease load, rearrange ctrcuit or install larger breaker. <br> Provide adequate ventilation. |
| Fallure to Trip. | Travel of tripping device does not provide positive release of tripping latch. Worn or damaged trip umit parts. Binds in overcurrent device. | Re-adjust or replace trip unit. <br> Replace trip unit. <br> Replace overcurrent device. |
| False Tripping | Overcurrent pick-up too low. Overcurrent time-setting too short. Bind in overcurrent device. | Change adjustment or replace with higher rated device. Change adjustment or replace with higher rated device. Replace device. |
| Fallure to Close and Latch | Binding in attachments preventing resetting of latch. <br> Chipped or worn latch. <br> Latch out of adjustment. <br> Latch return spring too weak or broken. Hardened or gummy lubricant on bearing and latch surfaces. | Re-align and adjust attachments. <br> Replace latch. <br> Adjust latch. <br> Replace spring. <br> Clean bearing and latch surfaces. |



Fig. 2 Right Side View of Breaker

## BASIC BREAKER COMPONENTS

## ARC QUENCHER-FIG. 2

Each arc quencher has several compound inside barriers (3) containing a large number of perforations and two outside barriers (4) without periforations, as well as a front cap (5) and a rear support (24) held in place by a fiber strap (23). A clamp (6) is attached to the breaker base by two bolts. Clamp (6) holds all the arc quencher assemblies to their respective pole units. A muffler (2) is located on top of the compound barriers. The compoind barriers and the muffler, together with the slots between the barriers, serve to extinguish the arc.

The arc quenchers should be inspected at the regular inspection period. If the barriers are cracked or eroded to one-half their original thickness, they should be replaced.

## REPLACEMENT, FIG. 2

1. Remove clamp (6) by removing two bolts.
2. Unclasp fiber strap (23).
3. Remove front cap (5), muffler (2), outside barriers (4), inside barriers (3) and rear support (24).
4. Install new or disassembled parts in reverse order.
NOTE: In re-assembling the rear support (24) to the breaker, be sure and push the rear support toward the top of the pole unit so that that the clearance in the rear support will accommodate the screwhead of the back plate.

## POLE UNIT ASSEMBLY-FIG. 3

The contact assembly of each pole unit consists of a stationary and a movable contact sub-assembly.

The stationary contact assembly consists of parallel contact fingers (3) with silver alloy tips, the upper stud (20) and pins (4) with compression springs (19) which provide continuous contact pressure between the contact fingers and the upper stud (20). A shunt (21) is used to prevent pitting at the pivot point of the stationary fingers when carrying high momentary currents. The stationary contact fingers are held in place by the upper stud cap ( 6 ).

The movable contact assembly consists of parallel contact arms (5) with silver alloy tips, a contact carrier (18) with a spring (17) which provides continuous contact between the contact arms and pin (15). A clamp (14) secures pin (15) to the contact support (16). A flexible connection (12) is provided to prevent pitting at the pivot point of the movable contact arms when carrying high momentary currents.

The movable contact assembly is connected to the main shaft (16), Fig, 2, by an insulating link (7) for operating the contacts when the breaker closes. A deflinte amount of contactpressure (see Measuring Contact Presiure ${ }^{\prime \prime}$ ) must be exerted by the movable contacts agatrist the stationary contacts. A definite
amount of contact wipe, or the distance that the stationary contacts are pushed to the rear by the movable contacts (see "Measuring Contact Wipe"), must result during the closing operation. Both contact pressure and contact wipe should bechecked at the regular inspection period.

## MEASURLNG CONTACT PRESSURE - FIG. 3

1. Remove arc quencher (see "Replacements" under Arc Quencher).
2. With the breaker closed, place a push-type scale against the upper front of the stationary contact tlp (3).
3. Exert pressure against the push-type scale until the contacts just part. When the contacts first part the scale should read between 4 to 6 pounds. If the proper pressure is not indicated, see "Adjusting Contact Wipe and Pressure".
4. Re-assemble parts in reverse order.

MEASURING CONTACT WIPE - FIG. 3

1. Remove arc quencher (see "Replacements" under Arc Quencher).
2. Measure the dimension between the inside surface of the pole base and the top edge of the stationary contact tip (3), (a) with the breaker open, (b) with the breaker closed.
3. The difference between these two measurements should be approximately $7 / 32^{\prime \prime}$.
4. Re-assemble parts in reverse order.

## ADJUSTING CONTACT: WIPE AND CONTACT PRESSURE - FIG. 3

1. Remove arc quenchers (see "Replacements" under Arc Quencher).
2. Remove tru-arc retaining ring from main shaft (16), Fig. 2, nearest the insulating link and contact assembly to be adjusted.
3. Loosen clamp (9) which secures eccentric bushing (8).
4. Turn the eccentric bushing in the insulating link (7) thereby moving the insulating link closer or farther away from the stationary contacts, as required to obtain proper wipe.
5. Re-assemble parts in the reverse order after making proper adjustments.
NOTE: To adjust the insulating link in the center pole unit, first, push the main shaft through the right hand insulating link and into the center link as described in ttems 2 and 3 above. Opening spring and cap will drop out. Adjust center insulating link as described in item 4 above. Reassemble parts in reverse order being careful to replace opening spring and cap in their proper position.

If any of the contacts are badly corroded or pitted, thereby, making it impossible to adjust for proper contact pressure or wipe, such stationary contacts and/or movable contact assemblies should be replaced. A commonly used "rule of thumb" is that contact replacement is indicated if less than one-half the original thickness (approx. $1 / 8$ tnch) of the contact tip material remains.: See "Replacements" below.

If the proper contact pressure does not exist when the wipe is within its limits, the stationary contact springs must be replaced.

## REPLACEMENTS

Movable Contact Assembly, Fig. 3

1. Remove front escutcheon (see "Raplacements" under Operating Mechanism).
2. Disconnect external wiring to the terminal board and auxiliary switch.
3. Remove arc quenchers (see "Replacements" under Arc Quenchers).
4. Remove tru-arc washer from one end of the main shaft and push main shaft through insulating link (7).
5. Remove four mounting bolts (26), Fig. 5 and lift entire operating mechanism from breaker.
6. Remove four screws which attach braid (12) to the movable contact arms.
7. Remove two screws and clamp (14).
8. Remove the movable contact assembly.
9. Remove the insulating link from the old movable contact assembly and re-assemble this same link to the new movable contact assembly.
10. Remove braid (12) from new movable contact assembly.
11. Install new movable contact assembly and replace clamp (14).
12. Remove screw from left hand coil terminal.
13. Remove old braid.
14. Install new braid by re-assembling coil terminal screw and four screws in the movable contact assembly.
15. Replace parts in reverse order.
16. Adjust contact wipe and contact pressure (see above).

Stationary Contact - Fig. 3

1. Remove arc quencher (see "Replacements" under Arc Quencher).
2. Remove upper stud cap (6) by removing two holding screws.
3. Pry the stationary contact (3) from upper stud (20).
4. Replace the new stationary contact in reverse order. (It may be necessary to tap the new stationary contact into place by using a rawhide mallet).
5. Adjust contact wipe and contact pressure (see above).

## OPERATING WECHANISM

The breaker closing mechanism consists of a front escutcheon and operating handle assembly and an operating mechanism. The combination of these two assemblies serve to close the breaker by means of an operating handle.

## FRONT ESCUTCHEON ASSEMBLY - FIG. 4

The front escutcheon is mounted on front of the operating mechanism frame by four screws (9) Fig. 2. The front escutcheon and operating handle assembly consists of:


1. Position Indicator
2. Operating Handle
3. Retaining Ring
4. Roller
5. Trip Button
6. Trip Paddle
7. Spring
8. Shaft
9. Trip Rod
10. Strap
11. Nameplate

Fig. 4 Front Escutcheon and Operating Handle Assembly
a. A pistol grip operating handle (7) attached to one end of the shaft (10) which extends through the front escutcheon. The other end of the shaft has a roller (8) attached to it.
b. A trip rod (5) which extends to the front escutcheon and which has a trip button (3) mounted to it.

The breaker may be locked in the tripped position by depressing the trip button (3) and inserting a padlock through the slot in the side of the front escutcheon.

## BREAKER OPERATING MECHANISM - FIG. 5

The operating mechanism is supported between two molded side frames in front of the center pole unit. It consists of a toggle linkage (17), cam (11), crank (10), latch (13), trip shaft (14), and roller (12).

The breaker is closed by rotating the operating handle $90^{\circ}$ clockwise causing roller (5) to engage cam (11), thereby straightening the toggle linkage, which closes the breaker. The breaker is held in the closed position by prop (19) resting against pin (16) and by latch (13) against roller (12).

The breaker mechanism is tripped by rotating trip shaft (14), and releasing trip latch (13) which causes the toggle linkage to collapse, thereby allowing the opening springs (21) to push the main shaft and movable contacts forward to the open position. Trip latch (13) is automatically reset during the opening operation providing none of the trip devices are actuated. Latch adjustling screw (28) limits the rotation of the trip shaft (14) and thus determines the amount of latch engagement.

ADJUSTMENTS, FIG. 5

There should be 5/64" engagement between the latch (13) and roller (12). To obtain the adjustment proceed as follows:

1. Loosen the locking nut on adjusting
2. Screw
3. Cam Return Spring
4. Handle
5. Hold In Post
6. Cam Roller
7. Adjusting Screw
8. Cam Support
9. Cam Support Pin
10. Crank Pivot Pin
11. Crank
12. Cam
13. Roller
14. Trip Latch
15. Trip Shaft
16. Tapered Insert
17. Toggle Link Pin
18. Toggle Links
19. Spring
20. Prop
21. Cap
22. Opening Spring
23. Main Shaft
24. Mechanism Frame
25. Prop Pin
26. Prop Return Spring
27. Mounting Bolts
28. Buffer Paddle
29. Latch Adjusting Screw

29: Trip Shaft Retum Spring

Fig. 5 Operating Mechanism (Breaker Closed)
2. Manually hold the breaker contacts in a position in which the movable contacts are just touching the stationary contacts.
3. Turn down adjusting screw (28) until the breaker trips open. Normally the force required to rotate the trip shaft is small enough so that the spring on the buffer paddie (27) is not noticeably deflected. If any deflection is observed while turning down the screw, back off screw until spring returns, then turn down screw again. If deflectton persists, check trip shaft for binds.
4. Mark position of adjusting screw head when breaker trips.
5. Repeat steps 2 and 3 and check position of adjusting screw in relation to marked posithon.
6. If adjusting screw is in the same position as it was in the first tripping, back off the adjusting screw (28) three complete turns and tighten locknut. If it is not, repeat steps 2 and 3 until a constant position of the adjusting screw is determined before backing off three turns and locking. This check is necessary to avoid a false setting due to accidental tripping.
7. Latch adjustment should now be correct. Operate breaker several times to assure that the mechanism is functioning properly.
The clearance between the latch (13) and roller
(12) should be between $1 / 32^{\prime \prime}$ to $1 / 16^{\prime \prime}$ when the breaker is open, in order to allow the mechanism to reset automatically when the breaker opens, and at the same time, provide the necessary overtravel for prop (19) to move on toggle link pin (16). If not enough clearance is provided the mechanism will not reset. If too much clearance is provided, prop (19). will not move on pin (16). This adjustment is obtained by turning the Allen Head adjusting screw (6).

## REPLACEMENTS - FIG. 5

## Operating Mechanism

1. See "Replacements" under Movable Contact Assembly, items 1 to 5.
2. Replace operating mechanism in reverse order.

## Two Opening Springs (21)

1. Remove arc quencher (see "Replacements" under Arc Quencher).
2. Remove tru-arc washer from end of main shaft (16), Fig. 2, nearest the spring to be removed.
3. Push main shaft to opposite side of operating mechanism. Cap (20) and spring (21) will back up into slot occupied by main shaft.
4. Remove cap (20) and spring (21) from slot by using small screwdriver.
5. Install new springs in reverse order after
tassembling cap (20) to new spring and pushing cap and gpring in place.

6. Stationary Indicator
7. Link
(Open)
8. Movable Indicator
9. Crank (Closed)

Fig. 6 Position Indicator With Auxilfary Swltch

## Reset Spring (18)

1. Remove operating mechanism (see "Replacements" under movable Contact Assembly, items 1 to 5).
2. Remove paddles from the trip shaft on the right side of the breaker.
3. Remove tru-arc from right side of trip shaft.
4. Remove return spring (29).
5. Remove screw (1).
6. Remove nut from right end of hold-in post (4).
7. Remove right hand mechanism frame.
8. Remove reset spring (18). Replace parts in reverse order.

NOTE: To replace torsion springs (2) and (26) follow procedure for removing reset spring (18) as above and, in addition, remove the necessary tru-arc washers and pins.
Front Escutcheon Assembly-Fig. 5.

1. Remove four mounting screws (9), Fig. 2.
2. Now pull forward on the operating handle turning and tipping the front escutcheon slightly until dislodged from the breaker.
3. To remount the front escutcheon assembly, first, hold the trip shaft in a trip free position. Then puil the cam support (7) slightly forward.
4. Insert the shaft (10), Fig. 4 and roller (8), Fig. 4 into the hole of the cam support so that the roller drops behind cam (11).
5. Replace the four mounting screws to secure the front escutcheon assembly to the mechanism frame.
The operating handle may be removed by simply removing the set screw tapped in the hole in the handle. Some handles are beld to the shaft by two: set screws, which requires bbth set screws be removed in order to remove the handle.

If two set screws are used to hold the operating. handle to the shaft, the long set screw should be replaced first and the short set screw on topi

NOTE: On older model breakers where the trip button is mounted in the operating handle; the trip rod and return spring must be removed by pushing:

## PROTECTIVE DEVICES

An AK-1-15 or AK-1-25 breaker may be equipped with any combination of the following protective devices:

1. Overcurrent trip
2. Reverse Current trip
3. Undervoltage trip.

## TIME DELAY UNDERVOLTAGE TRIPPING DEVICE FIG. 8

This device is mounted to a bracket on the right side of the operating mechanism (looking from the front). The purpose of this device is to trip the breaker for undervoltage. For rated poltage, the armature (3) is attracted by magnet (14). If the voltage falls below a predetermined value the magnet (14) releases the armature (3). Spring (4) then pulls armature (3) upward against the restraining force of the oil in cylinder (10); this action causes a time delay. When the spring overcomes the restraining force of the oll the armature engages screw (20) thus rotating the trip shaft and opening the breaker.

## ADJUSTMENTS, FIG. 8

1. An adjusting screw (20) in the trip paddle (22) is used to allow from $1 / 32$ to $1 / 16$ inch overtravel after tripping the breaker.
2. The armature pick-up is a function of the open air gap of the armature. The air gap is factory set by means of adjusting screw (2) so that the armature will pick-up at $80 \%$ of rated voltage. In order to make this adjustment in the field, a variable
voltage source is required. The atr gap should be increased if pick-up occurs at less than $80 \%$ of rated voltage and decreased if pick-up occurs at more than 80\%.
3. A callbration spring (4) attached to adjusting screw (18) establishes the drop-out value of voltage which results in breaker tripping. This is largely a factory adjustment, the drop-out value beting 30 to $60 \%$ of rated voltage.
4. The time-delay of the device may be varied somewhat by changing the relative positions of the connecting rod (1i) and clevis (7). This is accomplished by loosening the lockting nut (8), raising or lowering the plunger (12) by turning the connecting rod (11) which is threaded into the clevis (7). When any time-delay of 3 to 10 seconds existsfrom loss of voitage, the device is considered satisfactorily adjusted.
5. From $1 / 4$ to $3 / 8$ inch of ofl should be maintained in the cylinder at all times. In order to make an inspection of the oil, the cylinder (10) may be unscrewed from the cap (8). Use a silicone oll, such as, G.F. 9981LT40NV or similar, in the cylinder.

## REPLACEMENTS, FIG. 8

## Time Delay Undervoltage Device

1. Disconnect coil leads.
2. Remove two screws from bracket (1). (Bracket is omitted when instantaneous undervoltage device is used).
3. Remove four mounting screws (21) and remove device.
4. Ingtall new device in reverse order.

5. Bracket
6. Shading Ring
7. Adjusting Serew
8. Pin A Mut
9. Armature
10. Spring
11. Clevis
12. Locking Mut
13. Cap
14. Cylinder
15. Connection
Rod
16. Plunger
17. Clamp
18. Magnet
19. Coil
20. Sereme
21. Pin
22. Adjusting Screw
23. Locking Wire
24. Adjusting Scrai
25. Mounting Screw
26. Trip Päddle
© Climp
fig. 8 Time Delay Undervoltage Tripping Device

## Coil (15)

1. Disconnect leads to coil.
2. Remove two screws (16).
3. Remove magnet and coil assembly.
4. Straighten laminations around shading ring (5).
5. Remove shading ring and straighten lower end of coil clamp (13).
6. Remove coil. Install new coil in reverse order.

## INSTANTANEOUS UNDERVOLTAGE TRIPPING DEVICE

This undervoltage tripping device is constructed similarly to the time delay undervoltage tripping device with the exception that the cylinder (10), plunger (12), connecting rod (11), clevis (7), bracket (1), and locking nut (8), as shown in Fig. 8 are omitted.

The adjustments and replacements for this device are also the same as those for the time delay undervoltage tripping device.

## OVERCURRENT TRIPPING DEVICES

The typical overcurrent trip device consists of a magnetic structure, a series current coil, and a pivoted armature. Depending on the type of individual device, the movement of the armature may be delayed by a timing device, of either the oil dashpot or escapement gear and pallet type.

An AK-1-15/25 breaker may be equipped with either the EC-2 or EC-1 overcurrent trip device. The majority of applications will require the use of the EC-2 device. The EC-1 device is normally used when the short-time delay feature is required, or when the trip device is used to operate a special overcurrent alarm switch.

Most circuit breakers are equipped with series overcurrent trip devices either of the dual magnetic type (instantaneous and time delay tripping) or instantaneous alone. Breakers are designed to carry up to $100 \%$ of the continuous current rating of their trip devices. Any attempt to carry higher currents for a prolonged period will cause overheating and possible damage.

## EC-2 DEVICE

The EC-2 overcurrent tripping device is available in three forms:

1. Dual overcurrent trip, with long-time delay and high-set instantaneous tripping.
2. Low-set instantaneous tripping.
3. High-set instantaneous tripping.

The dual trip has adjustable long-time and instantaneous pick-up settings and adjustable time settings. Both forms of instantaneous trips have adjustable pick-up settings.


1. Series Coil
2. Trip Adjustment Screw
3. Opening for Time Adjus tment
4. Pickup Indicator \& Calib. Plate
5. Pickup Adjustment Knob

Fig. 9 EC-2 Overcurrent Trip
DUAL OVERCURRENT TRIP, WITH LONG-TIME DELAY AND HIGH-SET INSTANTANEOUS TRIPPING. - FIG. 9

By means of the adjustment knob (5), which can be manipulated by hand, the current pick-up point can be varied from 80 to 160 percent of the series coil rating. The indicator and the calibration plate (4), on the front of the case, provide a means of indicating the pick-up point setting in terms of percentage of coil rating. The calibration plate is indexed at percentage settings of $80,100,120,140$ and 160.

The long-time delay tripping feature can be supplied with any one of three time-current characteristics which correspond to the NEMA standards maximum, intermediate and minimum long-time delay operating bands. These are identified as 1 A , 1B and 1C characteristics, respectively. Approximate tripping time for each of these, in the same order are 30,15 and 5 seconds at $600 \%$ of the pick-up value of current. (See time-current characteristic curves $286 \mathrm{~B} 201 \mathrm{~A}, \mathrm{~B}$ and C).


1. Instantaneous Calibration Spring
2. Time-Delay Adjustment Screw
3. Movable Nut (Index Pointer)
4. Oil Dashpot
5. Time-Delay Calibration Spring
6. Instantaneous Pickup Adjustment Screw
7. Dashpot Arm
8. Connecting Link
9. Instantaneous Pickap Calibration Marks

Fig. 10 EC-2 Overcurrent Trip With Cover Removed


Fig. Il Time-Adjustment Indexing

## TRE ADJUSTMENT - FIG. 10

The tripping time may be varied within the limits shown on the characteristic curves by turning the time adjustment screw (5). Turning in a clockwise direction increases the tripping time; counterclockwise decreases it. The dashpot arm (7) is indexed at four points, max. - 2/3-1/3 - min. from left to right, as viewed in Figs. (10) and (11). When the index mark on the connecting link (8) lines up with the indicated mark on the dashpot arm, the approximate time as shown by the characteristic curve is indicated. Figure 13 shows typical timecurrent curves for the EC-2 and EC-1 tripping devices. The 1A and 1B characteristic devices are usually shipped with the time setting at the $2 / 3$ mark and the $1 C$ characteristic at the $1 / \$$ mark. The standard characteristic curves are plotted at the same settings.

Time values are inversely proportional to the effective length of the dashpot arm. Therefore, the Iinicage setting that gives the shortest time value is the one at which dimension "A", Fig. 10, is greatest. The time adjustment screw (5), may be turned by inserting a Phillips head screwdriver through the hole in the front of the case, but if it is desired to relate the linkage setting to the index marks on the lintrage it will be necessary to remove the case. This may be done by removing the two mounting gcrews, one on each side of the case, which may be takien off without disturbing the trip unit itself.

NOTE: Forcing the adjusting screw to either extreme position may cause binding of the device and should be avoided.

## MYSTANTANEOUS LOW-SET TRIPPING - FIG. 9

The low-set instantaneous pick-up point may be varied by the adjustment knob (5). The calibration in this case usually ranges from $80 \%$ to $250 \%$ of the series coll rating, the callbration plate being indexed at values of $80 \%, 100 \%, 150 \%, 200 \%$ and $250 \%$ of the coil rating.

## INETANTANEOUS HIGE-SET TRIPPING - FIG. 10

The high set instantaneous pick-up value may have one of the following three ranges: 4 to 9 times coll rating; 6 to 12 times coll rating or 9 to 15 times coil rating. The pick-up setting may be varied by turning the instantaneous trip adjusting screw (4).

[^12]At the factory, the pick-up point has been set at the nameplate value of the instantaneous trip current. (Usually expressed in times the ampere rating of the trip coil.) The variation in picis-up setting is accomplished by varying the tansile force on the instantaneous spring (1). Turning the adjustment screw (4) changes the position of the movable nut. (2), on the screw. The spring is anchored to this movable nut so that when the position of the nut is changed, there is a corresponding change in the spring load. As the spring is tightened, the pick-up point is increased. The top edge of the movable nut (2), serves as an index pointer and should be lined up with the center of the desired calibration mark, punched slots on operating arm, to obtain the proper instantanieous trip settigg

## ADJUSTMENTS, EC-2 - FTG. 9

In addition to the pick-up settings and timedelay adjustments already described, overcurrent trip devices must be adjusted for positive trippitig. This adjustment is made at the factory on new breakers, but must be made in the field when the breaker mechanism or the overcurrent trip dievices have been replaced.

Positive tripping is achieved when adjustment screw (2), is in such a position that it will always carry the trip paddle on the trip shaft beyond the point of tripping the breaker, when the armature closes against the magnet.

In order to make the adjustment, first unscrew adjusting screw (2), until it will not trip the breaker even though the armature is pushed against the magnet. Then, holding the armature in the closed position, advance the screw until it just trips the breaker. After this point has been reached, advance the screw two additional full turns. This will give an overtravel of $1 / 16$ of an inch and will make sure that activation of the device will always trip the breaker.

Adjustment screw (2), can best be manipulated by an extended $1 / 4$ inch hex socket wrench.

In order to gain access to the adjustment screw of the center pole overcurrent device, it will be necessary to remove the operation mechanism and attached components as a complete unit. Toremove the mechanism, follow the first five steps of "Replacement - Movable Contact Assembly" under: "Pole Unit Assembly".

## REPLACEMENT, EC-2

Replacement of the EC-2 overcurrent trip device is accomplished by the following procedure:

1. Remove the mechanism as a complete unit as described in the firstfive steps of "Replacement Movable Contact Assembly" under "Pole Unit Assembly".
2. Remove the steel clamps which fasten the cover of the device to the bacls of the breaker. NOTE: Pickup settings on the cover of each device. are calibrated for the specific device. When rep placing covers, replace on associated deylce.

3. Remove the $3 / 8$ inch bolts which fasten the coll of the overcurrent device to the breaker copper.
4. Remove the round head screw which fastens the frame of the overcurrent device to the brealcer base.
5. After reassembling breaker with new overcurrent device, adjust for "positive trip"; as described under "Adjustments" of this section.

NOTE: When replacing an EC-1 device with an $3 C-2$, or vice versa, it will be necessary to replace the trip paddles on the trip ghaft. These will be provided with the replacement trip units.

## EC-1 DEVICE

The $E C-1$ device can be provided with the lollowing tripping combinations:

1. Long time delay, short time delay and instantaneous tripping.

2. Long time and short time delay tripping only.
3. Long time delay and instantaneous tripping.
4. Short time delay and instantaneous tripping:
5. Short time delay tripping only.
6. Instantaneous tripping oniy.
(a) Adjustable (Low set)

Nonadjustable (Figh set)

## SHORT TTME DELAY TRIPPLNG, FIG. 12

The armature (7) is retained by calibrating spring (B). After the magnetic force, produced by an overcurrent condition, overcomesthis restraining force, the armature movement lis further retarded by an escapement mechanism which produces an inverse time delay characteristic. The mechanism: is shown in the left side view of Fig. 12.


Fig. 13: Typical Tiadecurrent Characteristic of Serles overcurrent Trip Davice in $25^{\circ} \mathrm{C}$ Arbienz'

The pickup for this device can be field set between limits having a ratio of $2-1 / 2$ to 1 in the range of 200 to $1000 \%$ of the coll rating.

LONG TMME DELAY TRIPPING, FIG. 12
The armature (10), is retained by the calibration spring (11). After the magnetic force, produced by an overcurrent condition, overcomes this restraining force, the armature movement is further retarded by the flow of silicone oil in a dashpot, which produces an inverse time delay characteristic. The mechanism is shown in the right side view of Fig. 12.

## INSTANTANEOUS TRIPPING, FIG. 12

(a) Adjustable instantaneous tripping takes place after the magnetic force produced by an overcurrent condition, overcomes the restraining force of the adjustable calibration spring (11).
(b) Nonadjustable instantaneous tripping takes place after the magnetic force produced by an overcurrent condition overcomes the restraining force of a nonadjustable spring (12).

## SELECTIVE TRIPPING

Selective overcurrent tripping is the application of circuit breakers in series so that only the circuit breaker nearest the fault opens. Any one or combination of two or more of thepreceding over-current devices may be used in a gelective system. The breaker having the shorter time setting and lower pickup will trip before the breaker having the Innger setting and higher pickup, provided the fault ors on the part of the line protected by the breaker having the lower settings.

For the exact characteristics and setting of each breaker in a selective system, reference should be made to a coordination chart for the particular system.

## ADJUSTMENTS, EC-1 - FIG. 12

The EC-1 device may be adjusted for positive tripping by following the same procedure described above for the EC-2 device and using adjusting screw (9).

## REPLACEMENT - EC-1

The EC-1 device may be replaced by following the same procedure described under "Replacement -EC-2".

## REVERSE CURRENT TRIPPING DEVICE - FIG. 14

The device is enclosed in a molded case and is mounted on the right pole base similarly to the series overcurrent tripping device.

The reverse current tripping device consists of a serles coil (1) with an iron core mounted
 (4) connected across a congtantitifurce of voltage and mounted around a rotary-type armature (6), Calibration spring (3) determines the armature pick-up when a reversal of current occurs.

As long as the flow of current through the breaker is in the normal direction, the magnetic flux of the series coll and the magnetic flux of the potential coil produce a torque which tends to roiate the armature counter-clockwise. The.call bration spring also tends to rotate the armature , the same direction. This torque causes the armit ture to rest against the stop screw (9) attached ta a bearing plate on the right side of the device.

If the current through the series coll (1) is reversed, the armature (6) tends to move in the clockwise direction against; the restraint of the callbration spring (3). When the current reversal exceeds the calibration setting, the armature revolves clockwise causing the trip rod (2) to move upward engaging the trip paddle (14), thereby tstppint the breaker.

ADJUSTMENTS - FIG. 14

The only field adjustment that should be required on the reverse current device is that of "positiv" tripping ${ }^{\prime \prime}$, which is the amount of overtravel of the trip rod (2) beyond the point of tripping the breaker: Proper overtravel is provided, if the trip rde $(2)$ advances the trip paddle (14) $1 / 32^{\prime \prime}$ to $3 / 64^{\circ}$ beyand the point of tripping the breaker. To adjust tor "positive tripping", proceed as follows:

NOTE: Be extremely cautious not to have hands near moving breaker parts when making thisadjust ment.

1. Manually lift the trip rod (2) as high as possible and turn the adjusting screw (15) into the trip paddle (14) until it will not touch the trip cod and trip the breaker.
2. Back-out the adjusting screw (15) to a pogition where the breaker is just tripped when the tifip rod is lifted as far as it will go.
3. Back-out the adjusting screw (15) an addra tional 1-1/2 turns from the position estabiflied in step 2 and the proper overtravel should be obtained.
4. Be sure to tighten the locking nut on the adjusting screw.

## REPLACEMENT

After removing the wiring for the potential coil the reverse current devtce can be removed and replaced by following the procedure putlined for replacing the series overcurrent device. wiring, see Fig. 14;


1. Series Coil
2. Trip Rod
3. Spring (Calib.)
4. Potential Coil
5. Calibration Nut
6. Armature
7. Pole Pieces

7A. Screws
8. Counterweight
9. Stop Screw
10. Mounting Screw.
11. Screw
12. Trip Crank
13. Screw.
14. Trip Paddle
15. Adj. Screw

Figs 14 Reverse Current Tripping Device:

## BREAKER ACCESSORIES

## SHUNT TRIPPING DEVICE FIG. 15

The shunt tripping device is mounted on a bracket attached to the right side of the operating mechanism (looking from the front).

A remote switch or relay contact is used to close the circuit of the device causing the armature (9) to engage the trip paddle (11) thereby tripping the brealcer: The spring (2) is used to return the armature to the neutral position after the breaker trips.

To prevent overheating, the coil (7) is cut off by contacts of the auxiliary switch which are open when the breaker ts open.

## ADJUSTMENTS

From $1 / 32^{\prime \prime}$ to $1 / 16^{\prime \prime}$ overtravel of the armature is required when the breater is tripped. If any adjustment is nececessary to provide this amount of overtravel, the trip lever is formed in or out accordingly.

## REPLACEMENT

Coil (7)

1. Disconnect leads to coil.
2. Remove magnet (6) and coil from frame (3).
3. Bend lower end of clamp (8) straight and remove.
4. Remove coil and install new coll in reverse order.
If, for some reason, the entire device is to be replaced, this is accomplished by removing the fasteners between the shunt trip device frame (3) and supporting bracket (13).

After replacing either the coil or the entire shunt trip device, the overtravel adjustment should be checked.

## BELL ALARM AND. LOCKOUT DEVICES

## BELL ALARM DEVICE - FIG. 16

A bell alarm device is available which operates when an overcurrent trips the breaker. It consiats primarily of a lever (7) and hanger (11) rivéted to auxiliary shaft (6), latch (12), catch (16); switch (1), reset lever (3), and mounting bracket (4)

When the breaker is tripped by an overcurrent the overcurrent device trip arm (8) causes lever (7), hanger (11), and latch (12) to rotate counterclockwise as a single member about pin (9): This disengages the latch from the catch (16). When the breaker opens, link (17) also releases the catch, allowing its spring to rotate it counterclockwise about pin (15). This in turn permits plunger of switch (1) to move downward, closing the lower contact of the switch and thereby completing the alarm circuit.

If the breaker is opened by means other than the overcurrent device, the latch (12) remains in position and does not allow the catch to rotate even though it is released by link (17).

Operation of the reset lever (3) returns the catch and switch contacts to their original position. At the same time, spring (5) resets latch (12),

## LOCKOUT DEVICE - FIG. 16

The lockout device consists of the same mecha; nism as the bell alarm device except that a gcrew (18) secures the hanger (11) to latch (18). This causes these two parts to function as a unit. 'Whenever the breaker is opened due to an overcurrent, the trip paddle (10) will be held in the tripped position by the lever (7), thereby locking the breaker in the open position until the lockout mechanismit reset manually by means of the reset lever (8),

1. MTO Screw (3)
2. Spring
3. Screws
4. Frame
5. Magnet
6. Pin
7. Coil
8. $\mathrm{Cl}_{\text {amp }}$


## ADJUSTMENTS - FIG. 16

In order for the bell alarm and lockout device to function properly the following conditions must exist:

1. The auxdliary trip shaft (6) must swing freely from its points of suspension and hang perfectly level with respect to the breaker parts.
2. The auxdliary shaft must be positioned so that each of its clearance cut-outs has such a position relative to its respective overcurrent device trip arm that the trip arm can operate without encountering interference from the shaft and contacts the shaft only at lever (7).
3. When the breaker is closed, lever (7) must hang in a position such that it touches neither the trip arm (8) or the adjusting screw in the trip paddle (10). The optimum condition is an equidistant position.
4. The latch (12) and the catch (16) must be so positioned relative to one another that when the breaker is closed and reset, the latch will clear the catch when the latch ts rotated counterclockwise. The catch is mounted on the same supporting bracket as switch (1).

This bracket may be shifted vertically by dismounting the switch and loosening the hardware which fastens the bracket to the mechanism side frame.

## DRAWOUT BREAKER - FIG. 17

The drawout circuit breaker consists of a circult breaker mounted in a drawout carriage whigh comprises the drawout mechanism. The drawout mechanism consists of guides (2), racking pins (1), racking handle (5), interiock lever (7) and an interlock arrangement which prevents the tinsertion or withdrawal of the breaker. when in the closed position: The drawout carrlage is also equipped with a test position stop, where the secondary disconnects are engaged but the primary disconnects are safely parted. In this position the breaker may be operated for test purposes without energizing the primary circuit.

Older model breakers, were equipped with rollers in place of guides on the breaker side frames, otherwise the drawout mechanism are similar.

It is recommended that a fresh coat of C.E. Lubricant D50H47 be applted to the primary dis. connects at each inspection period.

For a complete description of the inserting and withdrawing operations, refer to GEH-2021~ furnished with all AK breakers.


TYPICAL CONNECTION
DIAGRAM


SPACER \& SCREW (IB) ADDED
FOR LOCKOUT DEVICE

1. Switch
2. Plunger
3. Reset Lever
4. Mounting Bracket
5. Spring
6. Auxiliary Shaft
7. Lever
8. Trip Arm
9. Pin
10. Trip Paddle
11. Hanger
12. Latch
13. Trip Shaft
14. Main Shaft
15. Pin
16. Catch
17. Link
18. Screw (Lockout)

Fig. 16 Bell Alarm and Lockout Device


Fig. 17 AK-1-25 Drawout Breaker

## DISCONNECTS

PRIMARY DISCONNECTS
The primary disconnects are attached to the ends of the breaker studs on the rear side of the breaker base. Each disconnect assembly consists of two pair of opposed contact fingers. These are secured to the breaker stud by a bolt which passes through the assembly and the stud. When engaged with the stationary stud of the enclosure, the disconnect fingers exert a set amount of force against the stationary stud through the action of the compression springs. Retainers and spacers hold the contact fingers in correct alignment for engagement with the stud. The amount of force which the fingers exert against the stud is determined by degree to which the springs are compressed by the bolt and nut which hold the assembly together. If, for any reason, the disconnects must be taken apart, the position of the nut on the bolt should be carefully noted, so that in reassemblying, the original amount of compression can be restored by replacing the nut at its former position on the bolt.

## SECONDARY DISCONNECT, FIG. 18

The secondary disconnects serve as connections between breaker control circuit elements and external control circuits. They are used only on drawout type breakers. A terminal board serves the same purpose on stationary mounted and general purpose enclosure mounted breakers. The secondary disconnects allow removal of the breaker without the necessity of having to detach external connections.

The movable part of the secondary disconnect consists of an insulating body which holds a conducting spring loaded plunger to which a flexible lead is attached. As the breaker moves into its enclosure, the plunger is depressed by sliding onto the stationary disconnects of the enclosure.


Fig. 18 Movable Secondary Disconnects.

## REPLACEMENT OF MOVABLE SECONARY DISCONNECTS

1. Unfasten disconnect body from breaker back frame.
2. Open tabs which hold wires on inner side.
3. Pull contact tip loose from hollow tube.
4. Remove contact tip by cutting wire at its base.
5. Push wire through hollow tube of new disconnect assembly.
6. Strip insulation off end of wire to about $1 / 4$ of an inch from end.
7. Place new contact tip on end of wire and crimp.
8. Pull wire through hollow tube until contact tip fits snugly against end of hollow tube.
9. Crimp tab on other side of assembly to hold wire in place.
10. Any hollow tubes which are not used should be pushed into the disconnect body and held in that position by placing fibre spacers over inner ends of tubes and spreading tabs.
11. When all wires have been connected, refasten the body of the assembly to the breaker back frame.

## WELDING BREAKERS

The Type AK-1-15Y1 and AK-1-25Y1 breakers are intended for the protection of resistance welding machines. They trip instantaneously at higher current settings than breakers provided with the regular instantaneous adjustable overcurrent tripping device. This type breaker differs from the regular breaker only in the provision that higher current settings may be obtained.

## Gtit-74.002 Power Circuit Breakers Type AK-1-15-3 To 10 And AK-1-25-3 To 10

Standard calibration ranges for Type AK-1-15Y1, Fig. 19, are as follows:
a. 300 to 800 amperes
b. $\mathbf{6 0 0}$ to $\mathbf{1 5 0 0}$ amperes

Standard calibration ranges for Type AK-1-25Y1, Pis, 19, are as follows:
a. 600 to 1500 amperes
b. 1100 to 4000 amperes
c. 2000 to 5000 amperes

Other ranges can be provided within reasonable limits where the highest calibration settings will not exceed approximately $2-1 / 2$ times the lowest calibration setting.

These breakers are not given $a$ continucus current rating since the duty imposed is intermiltent and quite variable depending upon various types of welding to be done. The breakers are designed to safely carry "during-weld amperest of: "during-weld KVA" at welding perlods not escoed't Ing the corresponding:" duty cycle" as tabulated below. ("Duty cycle" is the per cent of time thit current flows in any one minute.



Fig. 19 Current and Duty Cycle Limits of Types AK-I-15Y| and AK-1-25Yi Breakers

## RENEWAL PARTS

When ordering renewal parts, address the nearest Sales Office of the General Electric Company, specifying the quantity required and describing the parts by catalogue numbers as shown in Renewal Parts Bulletin, GEF-3506.

In the absence of a Renewal Parts Bulletin, the Afinctibed parts ahould be identliled by giving the
complete nameplate data of the circuit breaker or accessory:

Renewal parts which are furnished may not be identical with the original parts, ince Improvements are made from thme to time. Parts whici: are furnished will beinterchangeable.



## POWER CIRCUIT BREAKERS

Types
AK-1-15 and AK-1-25 Electrically Operated


LOW Voltage switchaear department GENERAL ( 3 gig (1) Philadelphia, pa.

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# AIR CIRCUIT BREAKERS ELECTRICALLY OPERATED TYPES AK-1-15-3 THROUGH AK-1-15-10 AND AK-1-25-3 THROUGH AK-1-25-10 <br> INTRODUCTION 

The instructions contained heretn provide information for performing maintenance procedures and for replacing AK-1-15/25 breaker components and accessories. For information regarding the receiving, handling, storage and installation of these breakers, refer to GEH-2021A, furnished with all AK breakers.

The AK-1-15 and AK-1-25 breakers differ, in that, the AK-1-25 has an extra contact per pole with corresponding differences in the upper stud and interrupter.

As various design improvements and new features were added, the suffix digit of the breaker type number was progressively increased. All of these models are essentially the same breaker, as changes were largely of a minor nature. These are tabulated as follows:

AK-1-15/25-3 Basic model.

AK-1-15/25-4 Improved "Y" relay in solenoid control system.

AK-1-15/25-6 Stationary primary disconnect and cable clamp redesigned. (Only enclosed breakers affected.)

AK-1-15/25-7 New type of front escutcheon and closing handle. Trip button relocated on escutcheon and reset lever of bell alarm and lockout breakers changed.

AK-1-15/25-8 EC-2 overload trip device uséd instead of the EC-1 device except on units requiring the short time delay feature.
AK-1-15/25-9 New drawout frame introduced.
AK-1-15/25-10 Improved "Y" relay in solenoid control system.

## OPERATION

## MANUAL

An electrical breaker may be equipped with a manual operating handle, thus providing both manual and electrical closing features. Breakers which are equipped with manual handles may be closed by rotating the handle $90^{\circ}$ in the clockwise direction. Electrical breakers which do not have a manual operating handle may be closed by means of the manual maintenance handle furnished with the breaker. The closing mechanism automatically resets when the breaker trips, regardless of the type of breaker closing.

If the front escutcheon (9) Fig. 2 has been removed from the breaker, the maintenance handle can no longer be used. However, the breaker may still be closed manually by inserting a screw driver in the cam support as shown in Fig. 9 , and then rotating its handle upwards and toward the top rear of the breaker.

The breaker may be tripped manually by means of the manual trip button in the front escutcheon
(older model breakers in the manual operating handle), or automatically by any of the tripping devices with which it is equipped.

## ELECTRICAL

The breaker is closed electrically by means of a push button, located on the front of the breaker, or by a remote switch. When the closing contact is made the $x$ contactor becomes energized, thereby closing the $x$ contacts and energizing the breaker closing solenoid, which causes the breaker to close. When the breaker closes, the prop switch causes the breaker closing solenoid to be de-energized.

The breaker may be tripped manually by pushing the manual trip button, which is located on the front escutcheon or automatically by any of the trip devices with which the breaker is equipped. The breaker mechanism will automaticaliy reset when the breaker is tripped. The breaker is "trip iree" from the closing mechanism, which assures that it cannot be closed as long as any trip device ts functioning.

[^13]
## ELECTRICAL CONTROL CIRCUIT - Fig. 1

Figure 1 shows a typical elementary and connection diagram for the AK-1-15 and 25 breakers, with the breaker in the open position.

When normal voltage is supplied to the control curcuit, either by closing a remote switch or relay, or by the push button PB , the closing contactor coil $X$ ( $9-10$ ) will become energized through contacts BB (1-2) and Y (4-3). The X contacts will then close, sealing in the $X$ coil through contact $X(1-2)$ and energizing the breaker closing coil CC (1-2) through contacts $X$ (3-4), $X(6-5)$, and $X(7-8)$. This causes the armature to move downward and the breaker to close, thereby opening the BB (1-2) contact and closing the BB (3-4) contact of the prop switch.

Prop switch contact BB (1-2) opens the circuit to the $X$ contactor coll ( $9-10$ ) thus de-energizing the breaker closing coil CC (1-2) by opening contacts $X$ (3-4), $X$ (6-5), and $X(7-8)$. Prop switch contact AA (3-4) will also energize the permissive relay $Y$ ( $6-5$ ), providing contact is maintained at the closing switch. The $Y$ relay will in turn open its contact $Y$ (4-3), thus holding open the $X$ contactor coll circuit and providing the circuits antipump feature, as long as contact is maintained at the closing switch.

The breaker may be tripped electrically by a remote switch or relay which will energize the shunt trip coil TC (1-2) and trip the breaker. The trip impulse is interrupted by an " $A$ " auxiliary switch contact (1-1C) which is connected in the shunt trip circuit.

## MAINTENANCE

## INSPECTION

BEFORE INSPECTION OR ANY MAINTENANCE WORK IS DONE! BE SURE THAT THE BREAKER IS IN THE OPEN POSITION. ALL ELECTRICAL POWER, BOTH PRIMARY AND CONTROL SOURCES, SHOULD ALSO BE DISCONNECTED.

Periodic inspection of the circuit breaker is recommended at least once a year. More frequent inspections are recommended, if severe load conditions, dust, moisture, or other unfavorable conditions exist.

If the breaker remains open or closed for a long period of time, it is recommended that arrangements be made to open and close it several times in succession, preferably under load.

At all times it is important not to permit pencil lines, paint, oil or other forelgn materials to remain on the insulating surfaces of the breaker as they may cause low resistance between points of different potential and result in eventual electrical breakdown.

Always inspect the breaker after a short circuit current has been interrupted.

At the time of periodic inspection, the following checks should be made after the breaker has been de-energized.

1. Manually operate the breaker several times, check for obstructions or excessive friction.
2. Electrically operate the breaker several times to ascertain whether the electrical attachments are functioning properly.
3. Arc quencher (See Section on "Arc Quencher").
4. Contact condition, wipe, and pressure (See Section on "Pole Unit Assembly").
5. Latch engagement (See Adjustments under "Operating Mechanism").
6. Overcurrent device tripping (See Adjustments under "Series Overcurrent Tripping Device").

## TOOLS

The tools listed below will adequately equip an operator for any maintenance operation on AK-1-15 and AK-1-25 breakers.

## \#1 Phillips Screw Driver

\#2 Phillips Screw Driver with 8" shaft
\#3 Phillips Screw Driver
K101-1/2 Crescent (Short) Screw Driver
K505-1/2 Crescent (Long Thin) Screw Driver
K306 Crescent (Standard) Screw Driver
H-28 8" Gas Pliers
654 Pointed Nose Side Cutting $6^{\prime \prime}$ Pliers
\#2 Waldes Truarc Pliers Stratght
\#2 Waldes Truarc Pliers $90^{\circ}$ Angle
Ratchet Socket Wrench 1/2" Drive
$7 / 16^{\prime \prime}-1 / 2^{\prime \prime}$ Drive Socket
9/16" $-1 / 2^{\prime \prime}$ Drive Socket
$5 / 8^{\prime \prime}-1 / 2^{\prime \prime}$ Drive Socket
3/4" - 1/2" Drive Socket
13/16" -1/2" Drive Socket
15/16" - 1/2" Drive Socket
10" Extension Bar $1 / 2^{\prime \prime \prime}$ Drive
6" Extension Bar 1/2" Drive
8" Adjustable End Wrench
$1 / 4^{\prime \prime}-5 / 16^{\prime \prime}$ (Blue Point) Open End Wrench
1/2" - $9 / 16^{\prime \prime}$ Open End Wrench
5/8' $\quad-3 / 4^{\prime \prime}$ Open End Wrench
3/8" - 7/16" Open End Wrench
11/32" - 5/16" Open End Wrench
$1 / 16^{\prime \prime}$ Allen Head Wrench for ${ }^{*} 6$ Screw
5/64" Allen Head Wrench for \#8 Screw
3/32" Allen Head Wrench for *10 Screw
$1 / 8^{\prime \prime}$ Allen Head Wrench for $1 / 4^{\prime \prime}$ Screw
$5 / 16^{\prime \prime}$ Straight Shank Allen Head Wrench for $3 / 8^{\prime \prime}$ screw, with adapter for $1 / 2^{\prime \prime}$ drive ratchet
8 oz . Ball peen hammer
5/8" 6 point open box wrench
3/8" Spintite
NOTE: Obtain from local hardware, do not order on General Electric Company.


## LIST OF ABBREVIATIONS



A-TERMINAL BOARD LOGATED TOP RIGHT, FRONT VIEW:
b-TERMINAL BOARD-LOCATED UNDER-A. F-ANTFPUMP PERMISSIVE RELAY. G-(oo-bb)-MECHANISM SWITCH. $K$ - $(x)$ - CLOSING CONTACTOR-3 SETS OF CONTACTS IN SERIES (MAIN) a I SET FOR SEAL-IN.
 ATAI OR S'G A 50' (SPECIAL) M-TTG-SHNNT TRIP DEVICE. N-ract-SOLENOID CLOSING COIL. P-fno.-closing switch on breaker. T-TRANSFORMER.

## ELEMENTARY DIAGRAM

## LUBRICATION

In general, the circuit breaker requires moderate lubrication. Bearing points and latch surfaces should be lubricated at the regular inspection periods with a thin film of extreme temperature, highpressure, light grease similar to G.E. Spec. No. b50H15. Hardened grease and dirt should be removed from latch and bearing surfaces by using kerosene. ALL EXCESS LUBRICANT SHOULD BE REMOVED WITH A CLEAN CLOTH IN ORDER TO AVOID ANY ACCUMULATION OF DIRT OR DUST.

At each inspection period, all silver to silver friction points, such as primary disconnects should be cleaned and given a fresh coat of G.E. Spec. No. D50H47 lubricant.

## TROUBLE SHOOTING

The following table lists several typical symptoms of breaker malfunctions together with their causes and remedies. If, at any time, these symptoms are observed, their cause should be determined and the necessary corrective action should be taken.

TROUBLE SHOOTING

| TROUBLE | CAUSE | REMEDY |
| :---: | :---: | :---: |
| Overheating | Contacts not aligned. <br> Contacts dirty, greasy or coated with dark film. Contacts badly burned or pitted. <br> Current carrying surfaces dirty. <br> Bolts and nuts at terminal connections not tight. <br> Current in excess of breaker rating. <br> Exceaslve amblent tomperature, | Adjust contacts. <br> Clean contacts. <br> Replace contacts. <br> Clean surfaces of current carrying parts. <br> Tighten, but do not exceed elastic limit of bolts or fittings. <br> Decrease load, rearrange circuit or install larger breaker. Provide adequate ventllation. |
| Failure to Trip | Travel of tripping device does not provide positive release of tripping latch. <br> Worn or damaged trip unit parts Binds in overcurrent device. | Re-adjust or replace trip unlt. <br> Replace trip unit. <br> Replace overcurrent device. |
| False Tripping | Overcurrent pick-up too low. <br> Overcurrent time-setting too short. <br> Bind in overcurrent device. | Change adjustment or replace with higher rated device. <br> Change adjustment or replace with higher rated device. Replace device. |
| Fallure to Close and Latch | Binding in attachments preventing resetting of latch. <br> Chipped or worn latch. <br> Latch out of adjustment. | Re-align and adjust attachments. <br> Replace latch. <br> Adjust latch. |
| - | Latch return spring too weak or broken. Hardened or gummy lubrication on bearing and latch surfaces. <br> Closing solenold burned out. <br> Solenold control device not functioning properly. | Replace spring. <br> Clean bearing and latch surfaces. <br> Replace solenoid coil. <br> Re-adjust or replace device. |

## BASIC BREAKER COMPONENTS

## ARC QUENCHER - FIG. 2

Each arc quencher has several compound inside barriers (2) containing a large number of perforations and two outside barriers (3) without perforations, as well as a front cap (4) and a rear support (24) held in place by a fiber strap (23). A clamp (5) is attached to the breaker base by two bolts. Clamp (5) holds all the arc quencher assemblies to theitr respective pole unit. A muffier
(1) is located on top of the compound barrlers. The compound barriers and the muffler, together with the slots between the barriers and the mufller, together with the slots between the barriers, serve to extingulish the arc.

The arc quenchers should be inspected at the regular inspection period. If the barriers are cracked or eroded to one-half their original thickness, they should be replaced.


1. Muffler
2. Inside Barrier
3. Outside Barrier
4. Front Cap
5. Clamp
6. Strap
7. Operating

Mechanism
8. Mounting Screw

8 Kut
9. Front Escutcheon
10. Bilb
11. Trip Shaft
12. Stop Nut
13. Overcurrent Trip Device
14. Lower Stud
15. Series Coil
16. Main Shaft
17. Cap
18. Opening Spring
19. Insulating Link
20. Stationary Contact
21. Upper Stud
22. Movable Contact
23. Fiber Strap
24. Rear Support
25. Steel Base
26. Pole Unit Base

Fig. 2 Right side View of Breaker

## REPLACEMENT, FIG. 2

1. Remove clamp (5) by removing two bolts.
2. Unclasp fiber strap (23).
3. Remove front cap (4), muffler (1), outside barriers (3), inside barriers (2) and rear support (24).
4. Install new or disassembled parts in reverse order.

NOTE: In re-assembling the rear support (24) to the breaker, be sure and push the rear support toward the top of the pole unit so that the clearance in the rear support will accommodate the screwhead of the back plate.

## POLE UNIT ASSEMBLY - FIG. 6

The contact assembly of each pole unit consists of a stationary and a movable contact subassembly.

The stationary contact assembly consists of parallel contact fingers (3) with silver alloy tips, the upper stud (20) and pins (4) with compression springs (19) which provide continuous contact pressure between the contact fingers and the upper stud (20). A shunt (21) is used to prevent pitting at the pivot point of the stationary fingers when carrying high momentary currents. The stationary contact fingers are held in place by the upper stud cap (6).

The movable contact assembly consists of parLel contact arms (5) with silver alloy tips, a contact -arrier (18) with a spring (17) which provides continuous contact between the contact arms and pin (15). A clamp (14) secures pin (15) to the contact support (16). A flexible connection (12) is provided to prevent pitting at the pivot point of the movable contact arms when carrying high momentary currents.

The movable contact assembly is connected to the main shaft (16), Fig. 2, by an insulating link (7) which causes the contacts to move when the breaker is operated. Each movable contact assembly must exert a definite amount of contact pressure (see "Measuring Contact Pressure") against the stationary contacts when the breaker closes. During a closing operation, a definite amount of contact wipe must result, the distance which the stationary contacts are forced to the rear by the movable contact. (See "Measuring Contact Wipe"). At regular inspection periods both contact pressure and contact wipe should be checked.

MEASURING CONTACT PRESSURE - Fig. 6

1. Remove arc quencher (see "Replacement" under arc quencher).
2. With the breaker closed, place a push-type scale against the upper front end of the stationary contact tip (3).
3. Exert pressure againgt the push-type scale til the contacts just part. When the contacts first
part the scale should read between 4 to 6 pounds. If the proper pressure is not indicated, (see "AdJusting Contact Wipe and Pressure").
4. Re-assemble parts in reverse order.

MEASURING CONTACT WIPE, FIG. 6

1. Remove arc quencher (see "Replacement" under Arc Quencher).
2. Measure the dimension between the inside surface of the pole base and top edge of the stationary contact tip (3), (a) with the breaker open, (b) with the breaker closed.
3. The difference between these two measurements should be within the limits of $3 / 32^{\prime \prime}$ and $1 / 4^{\prime \prime}$. If not within this range, the contact wipe must be adjusted.
4. With the breaker closed, the stationary contacts should have a minimum of $1 / 16^{\prime \prime}$ overtravel, measured at the contact tips, before reaching the limit of their movement in the direction of closing.
5. Replace arc quencher.

## ADJUSTING CONTACT WIPE AND CONTACT PRESSURE" FIG. 6

1. Remove arc quenchers (see "Replacements" under Arc Quencher).
2. Remove tru-arc retaining ring from main shaft (16), Fig. 2, nearest the insulating link and contact assembly to be adjusted.
3. Loosen clamp (9) which secures eccentric bushing (8).
4. Turn the eccentric bushing in the insulating link (7) thereby moving the insulating link closer or farther away from the stationary contacts, as required to obtain proper wipe.
5. Reassemble parts in the reverse order after making adjustments.

NOTE: To adjust the insulating link in the center pole unit, first, push the main shaft through the right hand insulating link (7) and into the center insulating link as described in item 2 and 3 above. Opening spring (18), Fig. 2 and cap (17) Fig. 2, will drop out. Adjust center insulating link as described in step 4 above. Re-assemble parts in reverse order being careful to replace the opening spring and cap to their proper position.

If any of the contacts are badly corroded or pitted, thereby making it impossible to adjust for proper contact pressure or wipe, such stationary contacts or movable contact assemblies should be replaced. A commonly used "rule of thumb" is that contact replacement is indicated if less than one-half the original thickness (approx. $1 / 8$ of an inch) of the contact tip material remains. See "Replacements" below.

If the proper contact pressure does not exist when the wipe is within its limits, the stationary contact springs (19) must be replaced.

## REPLACEMENTS

Movable Contact Assembly, Fig. 6

1. Remove arc quenchers (see "Replacement" under "Arc Quencher").
2. Remove main shaft from breaker by removing tru-arc retainer from one end and pushing shaft through insulating links (7). (See Figs. 3 and 4.) As shaft clears the mechanism side frames, the opening springs and caps, (18) and (17) Fig. 2, will probably drop out of their recesses in the side frames. If the breaker is of the drawout type, handle socket, interlock lever, bushing and nut must be removed on the side from which the main shaft is to be removed.
3. Remove the upper mechanism mounting screws (Refer to Fig. 3).
4. Loosen lower mechanism mounting screws by using screw driver in slot provided on threaded end of screw which projects through back frame of breaker. (See Fig. 5.)
5. Mechanlsm and attached components may now be lifted clear of the breaker. If breaker is of the drawout type, movement of the mechanism will be somewhat restricted by control wires. There will be enough freedom, however, toallow the mechanism to be lifted to the top of the drawout frame or on later model breakers, to the top of the pole base, where it should be secured by tying.
6. Remove insulating link (7) by removing tru-arc and drifting out pin (11).
7. Remove clamps (14) by removing fastening hardware.
8. Remove series coil terminals bolts. Movable contact unit is now free and may be removed.
9. Breaker may now be reassembled with new contact assembly by reversing the above described procedure. In remounting mechanism, be sure that dowels in mechanism side frames are well seated in dowel holes in the pole unit base. (See Fig. 7.) It will also be necessary to compress the opening spring and cap in the recess in the mechanism side frame in order to obtain clearance for replacement of the main shaft.
10. Check contact wipe and pressure and adjust If necessary.

## Stationary Contact (3) Fig. 6

1. Remove arc quencher (see Replacements" under Arc Quencher).
2. Remove upper stud cap (6) by removing two holding screws threaded through the top of the cap.
3. Pry the stationary contacts (3) from upper stud (20) with a screw driver as shown in Fig. 7. Stationary contacts of the outer poles are readily accessible. On the center pole, it is recommended that the mech-


Fig. 3 Arc Quenchers and Handle Socket Removed from Orawout Breaker


Fig. 4 Removal of Main Shaft from Drawout Breaker


Fig. 5 Loosening Lower Mechanisa Mounting Bolts


1. Pole Unit Base
2. Fiber Strap
3. Stationary Contact
4. Contact Pin
5. Movable Contact Arm
6. Upper Stud Cap
7. Insulating Link
8. Eccentric Bushing
9. $\mathrm{Cl}_{\text {amp }}$
10. Screw
11. Pin
12. Flexible Connection and Terminal
13. Lower Stud
14. Clamp
15. Pin

16 Contact Support
17. Spring
18. Contact Carrier
19. Spring
20. Upper Stud
21. Shunt
22. Steel Plate

Fig. 6 Pole Unit Assembly
anism be removed to facilitate removal of the stationary contacts. Refer to steps 1 to 5 of the procedure for "Replacing Movable Contacts."
4. Replace the new stationary contact in reverse order. (It may be necessary to tap the new stationary contact into place by using a rawhide mallet).
5. Adjust contact wipe and contact pressure (see above).

## OPERATING MECHANISM

## WITHOUT CLOSING HANDLE - Fig. 9

The operating mechanism is supported between two molded side frames in front of the center pole unit. It consists of a toggle linkage (19), crank (5), latch (15), trip shaft (12), roller (6), closing links (1), and armature (14).

When the coil (8) is energized it pulls armature (14) downward, which through closing links (1), causes the toggle linkage (19) to straighten. This motion causes the main shaft (18) and movable contacts to move to the closed position. As soon as the toggle linkage is straightened the prop (23) moves on top of prop pin (20) and roller (6) moves on latch (15) thereby holding the mechanism in the closed position. The motion of the prop (23) causes switch (25) to operate, thus de-energizing the closing coil.

The breaker mechanism is $t$-ipped by rotating the trip shaft (12), and releasing latch (15) which causes the toggle linkage to collapse, thereby allowing the opening springs (17) to push the main shaft and movable contacts forward to the open position. Trip latch (15) is automatically reset during the opening operating providing none of the trip devices are actuated. Latch adjusting screw (9) limits the rotation of the trip shaft (12) and thus determines the amount of latch engagement.

To operate the breaker manually see section titled "Manual" under "Operation".
Adjustments, Fig. 9
Latch (15) is adjusted to provide approximately $5 / 64^{\prime \prime}$ engagement between latch and roller (6). To adjust for proper latch engagement, follow the procedure described below:

1. Loosen locknut on adjusting screw (9).
2. Hold breaker contacts in a position in which the movable contacts are just touching the stationary contacts. This may be done by any of the provided means of manual closing.
3. Turn down adjusting screw (9) until breaker trips open. Normally the force required to rotate the trip shaft is small enough so that the spring on the buffer paddle (10) is not noticeably deflected. If any deflection is observed while turning down the screw, back off screw until spring returns, then turn down screw again. If deflection persists, check trip shaft for binds.
4. Mark position of adjusting screw head.
5. Repeat steps 2 and 3 and check position of adjusting screw in relation to marked position.


Fig. 7 Removal of Stationary Contacts


Fig. 8 Dismounting Upper Section of Magnet
6. If adjusting screw is in the same position as it was in the first tripping, back off the screw 3 full turns and tighten locknut. If it is not, repeat steps 2 and 3 until a constant tripping position is determined before backing off the three turns and locking. This check is necessary to avoid a false setting due to accidental tripping.
7. Operate the breaker electrically several times to make sure that the mechanism functions correctly.
With the breaker open, the stop nut (13) should be adjusted so that there is approximately $1 / 16^{\prime \prime}$ clearance between the bottom of the magnet and the upper stop nut. This will restrict linkage movement in tripping but allow enough movement for the mechanism to reset.

## Replacements, Fig. 9



OTE: If a reasonable amount of care is exercised when replacing the mechanism, wiring lead connections will not be overstressed and need not be disconnected during the disassembly procedure. The electrical accessories may be tied up out of the way of the operator. If leads are disconnected, they should be marked to avoid incor rect connection.

1. Remove arc quenchers (see "Replacement" under "Arc Quencher").
2. Remove escutcheon (4).
3. If breaker is supplied with a terminal block, dismount block by removing two screws in back which fasten it to the supporting bracket.
4. Remove shunt trip supporting bracket by taking out the two screws which fasten it to the mechanism side frame. The nuts for these screws are loosely held in the recess on the inner side of the frame. If breaker is supplied with an undervoltage device, this also will be dismounted since it is held by the same supporting bracket.
5. If breaker is supplied with a closing switch, dismount switch base by removing two screws (10), Fig. 13.
6. Remove solenoid control device cover.
7. Remove $X$ contactor and $Y$ relay together, first removing two screws securing $\mathbf{Y}$ relay to arm which projects from magnet, then loosening the three screws which fasten the $X$ contactor to the supporting arms. Both devices can then be removed by lifting slightly and moving towards front of breaker.

8. Closing Link
9. Cam Return Spring
10. Hold in Poot
11. Escutcheon
12. Crank
13. Roller
14. Screw
15. Coil (Solenoid)
16. Trip Shaft

Adj. Screw
10. Buffer Paddle
11. Trip Shaft Ret. Spring
12. Trip Shaft
13. Stop Mut
14. Armature
15. Latch
16. Mech. Frame
17. Opening Spring
18. Main Shaft
19. Toggle Link
20. Pin
21. Reset Spring
22. Prop Pin
23. Prop
24. Locknuts
25. Switch (Prop)
26. Screw

Fig. 9 Operating Mechanism Without Operating Handle
8. Remove stop nuts (13) from armature plunger (14).
9. Remove lower section of magnet and closing coil by taking out four screws (7).
10. Remove upper section of magnet by taking out two screws which fasten it to mechanism side frames. (See Fig. 8).
11. Remove auxiliary switch by taking out bolt (1) and screw (4), Fig. 12.
12. Remove cutoff switch (25) by removing locknuts (24).
13. Remove tru-arc and take out main shaft (18), being careful not to lose opening spring (17) and cap which may pop out when main shaft is removed.
14. Take off mechanism by removing mounting screws from mechanism frame.
15. Mechanism may now be replaced as a unit or disassembled and then reassembled with new parts as needed.
16. Reassembly of the breaker is accomplished by reversing the procedure described. In replacing the mechanism, make sure that the dowels on the mechanism side frames are properly seated in the dowel holes in the pole unit base; (see Fig. 7) also that the opening springs and caps are positioned properly when replacing the main shaft.
17. Adjust prop switch as described under "Adjustments" in "Solenoid Control System" and check operation of breaker manually and electrically.
Opening Springs (17) Fig. 9 or (16) Fig. 10
Opening springs may be replaced by following the first two steps of the procedure for replacing the "Movable Contact Assembly."

## WITH CLOSING HANDLE, FIG. 10

The electrically operated mechanism equipped with a manual operating handle is shown in Fig. 10 . This mechanism is similar to the one furnished without an operating handle with the following exceptions:
a. There is only one stop nut (11) on the lower end of the rod extending from the armature (12) since there is no need to provide for operation by the maintenance handle.
b. The mechanism which is furnished with an operating handle contains a cam support (7) and cam (6), whereas the mechanism furnished without an operating handle contains neither of these parts.
The sequence for electrical operation is the same as given for the mechanism furnished without an operating handle. (Refer to the second paragraph under, "Operating Mechanism - Without Closing Handle").

Turning the operating handle (5) in the clockwise direction $90^{\circ}$ causes a roller attached to the operating shaft to engage cam (6) thereby moving the cam support (7) toward link (4). This motion straightens the operating linkage, thereby moving the main shaft (i7) and movable contacts to the closed position. Prop (22) engaging pin (10) and
latch (13) resting on roller (8) will hold the contacts in the closed position. Rotating the tripshaft (14) in the counter-clockwise direction will release the roller (8) which causes the togele linkage to collapse thereby allowing the opening springs (16) to push the main shaft and movable contacts forward to the open position. Trip latch (13) is automatically reset during the opening operation, providing none of the trip devices are actuated.

## Adjustments - Fig. 10

In addition to the adjustments shown for mechanisms furnished without an operating handle, adjustment screw (26) must be set for proper operation. This adjustment is satisfactory if the screw is set in such a position that the following two condittons exist:

1. In closing, there must be enough overtravel of the mechanism to easily allow prop (22) to move on pin (19).
2. When the breaker is open, roller (8) must clearly be free of contact with latch (13).

## Replacements - Fig. 10

The replacement of parts in the operating mechanism furnished with a manual handle are similar to those for the mechanism furnished without a handle, with the following additions:

## Front Escutcheon Assembly

1. Remove four mounting screws (8), Fig. 2.
2. Now pull forward on the operating handle turning and tipping the front escutcheon slightly until dislodged from the breaker.
3. To remount the front escutcheon assembly, first, hold the trip shaft in a trip free position. Then pull the cam support, (7) slightly forward.
4. Insert the operating shaft and roller into the hole of the cam support so that the roller drops behind cam (6).
5. Replace the four mounting screws to secure the front escutcheon assembly to the mechanism frame.

Replacing the Operating Handle

1. Remove the short set screw from the tapped hole in the operating handle.
2. Back off a second longer set screw from the same tapped hole untll it is moved clear of the shaft.
3. Pull forward on operating handle until it is released from the front excutcheon and operating shaft.
4. Re-assemble operating handle to front escutcheon and operating shaft in reverse order.

NOTE: On older model breakers where the trip button is mounted in the operating handle, the trip rod and return spring must be removed by pushing the trip rod forward through the operating handle. In reassembly, sufficient clearance between the long set screw and the trip rod must be provided. Advance the long set screw into the tapped hole in the operating
handle until it just binds the trip rod. Then back off on set screw one turn and lock the long set screw by tnserting short set screw. Check trip rod for free movement.

## ADDITION OF CLOSING HANDLE - FIG. 10

If it is desired to add a manual closing handle to a breaker which was not furnished with one originally, the conversion may be made by following the procedure below. Required parts catalog numbers may be obtained by reference to Renewal Parts Bulletin GEF-3506.

1. Follow steps 1 to 14 of procedure for replacement of the mechanism.
2. After mechanism has been removed, remove right mechanism side frame by removing hardware at (3) and (26), Fig. 9, all trip shaft attachments to the right of the mech-
anism, and the trip shaft retaining ring.
3. The toggle linkage and armature, now free of the mechanism side frames, may be disassembled and reassembled with the parts required for manual operation. Return spring, (2) Fig. 10, replaces (2) FLg. 9, and cam support (7), is added to the linkage assembly. Fig. 10 shows how the linkage should be reassembled.
4. Reassemble mechanism and breaker parts with exception of escutcheon.
5. Mount new escutcheon assembly, which will include a manual operating handle, according to the directions in the section titled "WITH CLOSING HANDLE" under "Replacements".
6. Adjust screw (26) as described in "Adjustments" under "WITH CLOSING HANDLE."
7. Check manual and electrical operation of breaker.

8. Closing Link
9. Cam Return Spring
10. Hold in Post
11. Link
12. Handle
13. Cam
14. Cam Support
15. Roller
16. Screw
17. Coil
18. Stop Nut
19. Armature
20. Latch
21. Trip Shaft
22. Cam Roller
23. Opening Spring
24. Main Shaft
25. Toggle Link
26. Pin
27. Reset Spring
28. Prop Pin
29. Prop
30. Locknuts
31. Switch
32. Screw
33. Adjusting

Screw

Fig. 10 Operating Mechanism with Closing Handle

## AUXILIARY SWITCH - FIG. 12

The auxiliary switch is mounted on the left side of the operating mechanism. The main shaft (17), Fig. 10, of the breaker causes crank (4), Fig. 11; to rotate as the breaker opens and closes. The crank operates the auxiliary switch shaft (3) which opens and closes the "a" and " $b$ " contacts of the switch. (The "a" contacts are open when the breaker is open; the " b " contacts are closed when the breaker is open). The opening and closing of the auxiliary switch contacts is determined by an arrangement of cams (12), mounted on the auxiliary switch shaft (3). The top terminals of the switch are "a" contacts, the bottom terminals are " b " contacts.

ADJUSTMENTS, FIG. 12
The contacts of any stage may be changed from "a" to " b " or vice versa. If changes are desired in the operation of the contacts, an approved drawing of the cam (12) arrangement should be obtained or a careful sketch made. In order to change a " $a$ " contact to a "b" contact, it is necessary to remove $=\quad$ the four tie bolts (2) and change the position of the particular cam $90^{\circ}$ in relation to the shaft. Contacts should be cleaned occasionally to insure proper performance.

## REPLACEMENTS, FTG. 12

1. Disconnect all leads to the auxiliary switch.
2. Remove mounting bolt (1) and screw (4) to remove device from breaker.
3. Mounting Bolt
4. Bottom Cover
5. Tie Bolt
6. Shaft
7. Screw
8. End Plate
9. Top Cover
10. ':'Contacts
11. Contact Spring
12. Rocker Arm
13. Pin
14. Cam
15. 'b' Contacts
16. 'b' Terminals
17. ' $a$ ' Terminala
18. Barrier

Fig. 12 Auxiliary Switch
3. If no approved sketch of the cam arrangement is available, remove the end plate (6) from the device by removing the four tie bolts (2) and draw a sketch of the position of the particular cam in relation to the shaft.
4. Before installing the new device, see that the cams are in the same position as in the device that is being replaced.
5. Install the new device in reverse order.

## ELECTRICAL CLOSING DEVICES AND CONTROLS

The electrical closing devices and controls consist of the following:
a. Closing Switch
b. Solenoid Control System
c. Closing Solenoid

## CLOSING SWITCH, FIG. 13

The closing switch is located in the lower right hand corner of the front escutcheon (1).

A push button extends through the front escutcheon and is supported by bracket (3). Spring (6) returns the push button to a neutral position after the movable contact (8) has momentarily engaged the stationary contacts (12). Two retainers (2) and spacer (7) are used to hold the movable contact in place.

The stationary contacts (12) and insulation strip (13) are attached to the closing solenoid by bracket (9) and screws (10). A remote closing switch may be used to close the circuit of the solenoid control system, thereby energizing the closing solenoid.

## Adjustments

The closing switch requires no attention, other than cleaning of contact occasionally.

## SOLENOID CONTROL SYSTEM - FIG. 14

This system consists of an X contactor and Y relay which are located on the left side of the operating mechanism. It also contains a prop switch (25), Fig. 9, which is located in the top front of the operating mechanism (looking from the front). The sequence of operation is as follows:
a. When the closing switch is closed, the coil of the X contactor becomes energized.
b. The contacts of the X contactor close, sealing its coil in and also energizing the breaker closing coil.
c. The breaker then closes and latches causing the bb contact of the prop switch (25), Fig. 9, to open thereby de-energizing the $X$ contactor coil and the breaker closing coil.

NOTE: If the closing switch is closed while the breaker is in the closed position, or if it remains closed after the breaker closes, the coil of the $Y$ relay will become energized through the aa contact of the prop switch (25), Fig. 9. This will open the circuit to the X contactor coil, thereby preventing


1. Front Escutcheon
2. Movable Contact
3. Retainers
4. Bracket
5. Bracket
6. Screw
7. Closing Solenoid
8. Push Button
9. Stationary Contact
10. Insulation Strip

Fig. I3 Closing Switch


1. Mtg. Screws, Y Relay
2. Frame, Y Relay
3. Mtg. Screws, X Contactor
4. Hex. Posts
5. Term. Screws, $X$ Contactor
6. X Contactor
7. Armature Screw
8. Y Relay
9. Mtg. Screw, Y

Relay Coil

Fig. $14 \times$ Contactor and $Y$ Relay
(AK-1-15/25-9)
the $\mathbf{X}$ contactor from operating. This feature makes it impossible to operate the closing solenoid when the breaker is already closed. It also provides for cut-off of the closing solenoid and anti-pump operation.

## ADJUSTMENTS - FIG. 9

The only adjustment required for this system is on the prop switch (25). To make this adjustment proceed as follows:

1. Press the trip button in the front of the breaker.
2. Maintain pressure on the trip button and at the same time close the breaker with the maintenance operating handle.
3. The prop switch (25) should operate just before the armature (14) reaches the end of its stroke. To obtain this adjustment move the prop switch toward or away from the prop (23). Moving the switch too close to the prop can result in damage to the switch if its operating button is forced to travel beyond the limit of its movement. It is also possible, in this case, for the switch not to toggle when the breaker closes. (When the breaker closes, the prop moves away from the switch and the button is extended). This would leave the bb contacts closed with the breaker closed, and burn out the contactor and closing solenoid coils. If, on the other hand, the switch is too far away from the prop, it is possible for the bb contacts to remain open when the breaker is open. This would make it impossible to close the breaker electrically. This contition could also result in false tripping even though the switch may operate, since the thrust of the switch button is depended upon to move the prop into position and hold it in place on breaker closing operations.
REPLACEMENTS - FIG. 14
Y Relay and Coil - Fig. 14
4. Remove relay cover by removing two cover screws.
5. Disconnect wiring from front of relay (8) by loosening terminal screws.
6. Remove two screws (1) which fasten relay frame (2) to upper extension of magnet frame.
7. The relay and its frame are now free of the breaker.
8. With the relay (8) removed, the coll may now be removed by removing two small cotter keys at rear of relay frame.
9. Remove small spring at rear-center of relay frame.
10. Remove coil mounting screw (9) from center of coil. The coil may now be removed.
11. Install new coll or relay in reverse order.

## X Contactor - Fig. 14

1. Perform steps 1 and 2 of "Replacing Y Relay and Coll".
2. Remove three mounting screws (3) which fasten the $X$ contactor to magnet frame extensions.
3. The X contactor is now free from the breaker. Install new $X$ contactor in reverse order.

## $X$ Contactor Coil

1. The $X$ contactor coil may be removed without removing the $X$ contactor by first disconnecting wiring from $X$ contactor terminal screws (5).
2. Remove two hex. shaped posts (4). The coll is now free of its mounting.
3. Remove screw (7) which fastens the armature to the movable contacts. The coll is now completely removed.
4. Install new coil in reverse order.

## Prop Switch (25), Fig. 9

1. Remove wiring.
2. Remove locknuts (24) from switch.
3. Replace switch in reverse order.

## CLOSING SOLENOID, FIG. 9

The closing solenoid is located directly below the operating mechanism. It consists of a coil (8), a magnet, an armature (14), and four closing links (1).

The closing solenoid is connected in series with the main contacts on the $X$ contactor and is energized or de-energized when these contacts are closed or opened, respectively. When the closing solenoid is energized, its armature (14) is drawn downward into the coil (8) pulling the four closing links (1) in the same direction. This action straightens the toggle linkage (19), of the operating mechanism, thereby closing the breaker. As the operating mechanism moves into the closed position, the prop switch (25) operates, causing the $\mathbf{X}$ contactor coil and breaker closing coil (8) to be de-energized.

## ADJUSTMENT - FIG. 9

The stop nut (13) should be set so that there is approximately $1 / 16^{\prime \prime}$ clearance between the nut and the magnet when the breaker is in the open position. This adjustment is required in order to allow the mechanism linkage to reset.
REPLACEMENTS, FIG. 9
Closing Solenold

1. Remove the $X$ contactor and $Y$ relay (see "Replacements" under Solenoid Control System).
2. Remove stop nut (13).
3. Remove four screws (7) which attach lower part of magnet to upper part of magnet.
4. Remove two screws (see Fig. 8) which attach upper part of magnet to the two side frames of the operating mechanism.
5. Install new closing solenotd in reverse order.

Coil (8) - Fig. 9

1. Remove lower member of magnet as described in steps 1 to 3 of "Closing Solenold Replacement".
2. Remove wiring to coll (8) by disconnecting one lead at the $X$ contactor and cutting the other lead three to four inches from coll.
3. Remove brass coil guides and the coil may now be removed.
4. Install new coil in reverse order.

## PROTECTIVE DEVICES

An AK-1-15 or AK-1-25 breaker may be equipped with any combination of the following protective devices:

1. Overcurrent trip
2. Reverse Current trip
3. Undervoltage trip

## TIME DELAY UNDERVOLTAGE TRIPPING DEVICE - FIG 15

This device is mounted. to a bracket on the right side of the operating mechanism (looking from the front). The purpose of this device is to trip the breaker for undervoltage. For rated voltage, the armature (3) is attracted by magnet (14). If the voltage falle bolow a predetormined value the magnet (14) releases the armature (3). Spring (4) then pulls
armature (3) upward against the restraining force of the oil in cylinder (10); this action causes a minimum time delay of 3 seconds. When the spring overcomes the restraining force of the oil the armature engages screw (20) thus rotating the trip shaft and opening the breaker.

## ADJUSTMENTS - Fig. 15

1. An adjusting screw (20) in the trip paddle (22) is used to adjust for "positive tripping". The overtravel of the trip paddle from the point of tripping the breaker should be $1 / 32$ to $1 / 16$ inch, which may be visually observed when making this adjustment.
2. The armature pick-up is a function of the open air gap of the armature. The air gap is factory set by means of adjusting screw (9) so that the

3. Bracket
4. Adjusting Screw
and sut
5. Armature
6. Shading Ring
7. Pin
8. Clevis
9. Spring
10. Locking Nut
11. Cap
12. Cylinder
13. Connection Rod
14. Plunger
15. Clamp
16. Magnet
17. Coil
18. Screws
19. Pin
20. Adjusting Screw
21. Locking Wire
22. Adjusting Screws
23. Mounting Screws
24. Trip Paddle a Clamp
25. Supporting Bracket

Fig. 15 Time Delay Undervoltage Tripping Device
armature will pick-up at $80 \%$ of rated voltage. In order to make this adjustment in the fielda variable voltage source is required. The air gap should be increased if pick-up occurs at less than $80 \%$ of rated voltage and decreased if pick-up occurs at more than $80 \%$.
3. A calibration spring (4) attached to adjusting screw (18) extablishes the drop-out value of voltage which results in breaker tripping. This is largely a factory adjustment, the drop-out value being 30 to $60 \%$ of rated voltage.
4. The time-delay of the device may be varied somewhat by changing the relative positions of the connecting rod (11) and clevis (7). This is accomplished by loosening the locking nut (8) then raising or lowering the plunger (12) by turning the connecting rod (1i) which is threaded into the clevis ( 7 ). When any time-delay of 3 to 10 seconds exists from loss of voltage, the device is considered satisfactorily adjusted.
5. From $1 / 4$ to $3 / 8$ inch of oil should be maintained in the cylinder (10) at all times. In order to make an inspection of the oill, the cylinder may be unscrewed from the cap (9). Use a silicone oil, such as, G.E. 9981LT40NV or similar, in the cylinder.

REPLACEMENTS, FIG. 15

## Coil

The only part of the undervoltage device that is likely to require replacement during the life of the breaker is the coil (15). The replacement procedure follows:
(Note:- It is advisable to replace the magnet and coll assembly as nearly as possible in its exact original position in relation to the device frame. Doing this will result in having the same open air gap between armature and magnet and will insure the device's picking up at the same voltage value).

1. Disconect coll leads.
2. Remove two screws (16), freeing magnet (14) and coil (15) from device. (It may be more convenient to remove the entire device from its supporting bracket (23) before removing the magnet and coll. If the device is of the time-delay type, bracket (1) will also have to be removed from bracket (23).
3. Straighten laminations which were bent to hold shading ring (5) in place.
4. Removing shading ring (5).
5. Straighten end of coil clamp (13).
6. Remove coil, install new coil, and reassemble device by reversing disassembly procedure.

## Device

If the entire device is replaced, simply remove the hardware fastening the frame of the device to supporting bracket (23). If a time-delay device, bracket (1) must also be removed from bracket (23).

## INSTANTANEOUS UNDERVOLTAGE TRIPPING DEVICE

This undervoltage tripping device is constructed similarly to the time delay undervoltage tripping device with the exception that the cylinder (10), plunger (12), connecting rod (11), clevis (7), bracket (1), and locking nut (8), as shown in Fig. 15 are omitted.

The adjustments and replacements for this device are also the same as those for the time delay undervoltage tripping device.

## OVERCURRENT TRIPPING DEVICES

The typical overcurrent trip device consists of a magnetic structure, a series current coil, and a pivoted armature. Depending on the type of individual device, the movement of the armature may be delayed by a timing device, of either the oll dashpot or escapement gear and pallet type.

An AK-1-15/25 breaker may be equipped with either the EC-2 or EC-1 overcurrent trip device. The majority of applications will require the use of the EC-2 device. The EC-1 device is normally used when the short-time delay feature is required, or when the trip device is used to operate a special overcurrent alarm switch.

Most circuit breakers are equipped with series overcurrent trip devices either of the dual magnetic type (instantaneous and time delay tripping) or instantaneous alone. Breakers are designed to carry up to $100 \%$ of the continuous current rating of their trip devices. Any attempt to carry higher currents for a prolonged period will cause overheating and possible damage.

## EC-2 DEVICE

The EC-2 overcurrent tripping device ts available in three forms:

1. Dual overcurrent trip, with long-time delay and high-set instantaneous tripping.
2. Low-set instantaneous tripping.
3. High-set instantaneous tripping.

The dual trip has adjustable long-time and instantaneous pick-up setting and adjustable time settings. Both forms of instantaneous trips have adjustable pick-up settings.

## DUAL OVERCURRENT TRIP, WITH LONG-TIME DELAY AND HIGH-SET INSTANTANEOUS TRLPPING.

By means of the adjustment knob (5), Fig. 16, which can be manipulated by hand, the current plckup point may be varied from 80 to 160 percent of the series coil rating. The indicator and a callbration plate (4), Fig. 16, on the front of the case provide a means of indicating the pick-up point setting in terms of percentage of coll rating. The calibration plate is indexed at percentage settings of $80,100,120,140$ and 160.

The long-time delay tripping feature can be supplied with any one of three time-current characteristics which correspond to the NEMA standards maximum, intermediate and minimum long-time delay operating bands. These are identified as 1A, 1B and 1C characteristics, respectively. Approximate tripping time for each of these, in the same order are 30,15 and 5 seconds at $600 \%$ of the pickup value of current. (See time-current characteristic curves 286B201A, B and C).

TIME ADJUSTMENT - Fig. 17
The tripping time may be varied within the limits shown on the characteristic curves (Fig. 19) by turning the time adjustment screw (5). Turning in a clockwise direction increases the tripping time; counterclockwise decreases it. The dashpot $\operatorname{arm}$ (7) is indexed at four points, max. - 2/3-1/3min. from left to right, as viewed in Figs. 17 and 18. When the index mark on the connecting link (8) lines up with the indicated mark on the dashpot arm, the approximate time as shown by the characteristic curve is indicated. Fig. 19 shows typical time-current curves for the EC-2 and EC-1 tripping devices. The 1 A and 1 B characteristic devices are usually shipped with the time setting at the $2 / 3$ mark and the 1 C characteristic at the $1 / 3$ mark. The standard characteristic curves are plotted at the same setting.

Time values are inversely proportional to the effective length of the dashpot arm. Therefore, the linkage setting that give the shortest time value is the one at which dimension " A ", Fig. 17, is greatest. The time adjustment screw (5), may be turned by inserting a Phillips head screwdriver through the hole in the front of the case, but if it is desired to relate the linkage setting to the index marks on the linkage it will be necessary to remove the case. This may be done by removing the two mounting screws, one on each side of the case, which may be taken off without disturbing the trip unit itself.

NOTE: Forcing the adjusting screw to either extreme positon may cause binding of the device and should be avoided.

## INSTANTANEOUS-LOW-SET TRIPPING - FIG. 16

The low-set instantaneous pick-up point may be varied by the adjustment knob (5). The calibration in this case usually ranges from $80 \%$ to $250 \%$ of the series coil rating, the calibration plate being indexed at values of $80 \%, 100 \%, 150 \%, 200 \%$ and $250 \%$ of the coil rating.

INSTANTANEOUS-HIGH-SET TRIPPING - FIG. 17
The high set instantaneous pick-up value may have one of the following three ranges: 4 to 9 times coil rating; 6 to 12 times coil rating or 9 to 15 times coil rating. The pick-up setting may be varied by turning the instantaneous trip adjusting screw (4).

Three standard calibration marks will appear on the operating arm at (9), and the value of these


1. Series Coil
2. Trip Adjustment Screw
3. Opening for Time Adjus tment
4. Pickup Indicator \& Calibr Plate
5. Pickup Adjustment Knob

Fig. 16 EC-2 Overcurrent Trip
calibration marks will be indicated by stampings on the arm as follows:

| 4 X |  | 6 X |  | 9 X |
| ---: | ---: | ---: | ---: | ---: |
| 6.5 X | or | 9 X | or | 12 X |
| 9 X |  | 12 X |  | 15 X |

At the factory, the pick-up point has been set at the nameplate value of the instantaneous trip current. (Usually expressed in times the ampere rating of the trip coil.) The variations in pick-up setting is accomplished by varying the tensil force on the instantaneous spring (1). Turning the adjustment screw (4) change the position of the movable nut (2), on the screw. The spring


1. Instantaneous Calibration Spring
2. Movable Nut (Index Pointer)
3. Time-Delay Calibration Spring
4. Instantaneous Pickup Adjustment Screw
5. Time-Delay Adjustment Screw
6. Oil Dashpot
7. Dashpot Arm
8. Connecting Link
9. Instantaneous Fickup Calibration Marks

Fig. 17 EC-2 Overcurrent Trip with Cover Removed


Fig. 18 Time-Adjustment Indexing
is anchored to this movable nut so that when the position of the nut is changed, there is a corresponding change in the spring load. As the spring is tightened, the pick-up point is increased. The top edge of the movable nut (2), serves as an index pointer and should be lined up with the center of the desired callbration mark, punched $\frac{\text { slots }}{}$ on operating arm, to obtain the proper instantaneous trip setting.

## ADJUSTMENTS, EC-2 - FIG. 16

In addition to the pick-up settings and timedelay adjustments already described, overcurrent trip devices must be adjusted for positive tripping. This adjustment is made at the factory on new breakers, but must be made in the field when the breaker mechanism or the overcurrent trip devices have been replaced.

Positive tripping is achieved when adjustment screw (2), is in such a position that it will always carry the trip paddle on the trip shaft beyond the point of tripping the breaker when the device armature closes against the magnet.

In order to make the adjustment, first unscrew trip adjustment screw (2), until it will not trip the breaker even though the armature is pushed


Fig. 19 Typical Time-Current Characteristic of Series Overcurrent Trid Device in $25^{\circ} \mathrm{C}$ Ambient,
against the magnet. Then, holding the armature in the closed position, advance the screw until it just trips the breaker. After this point has been reached, advance the screw two additional full turns. This will give an overtravel of $1 / 16$ of an inch and will make sure that activation of the device will always trip the breaker.

Adjustment screw (2), can best be manipulated by an extended $1 / 4$ inch hex socket wrench.

In order to gain access to the adjustment screw of the center pole overcurrent device, it will be necessary to remove the operating mechanism and attached components as a complete unit. Toremove the mechanism, follow the first five steps of "Replacement - Movable Contact Assembly" under Pole Unit Assembly".

## REPLACEMENT, EC-2

Replacement of the EC-2 overcurrent trip device is accomplished by the following procedure:

1. Remove the mechanism as a complete unit as described in the first five steps of "Replace-
ment - Movable Contact Assembly" under "Pole Unit Assembly".
2. Remove the steel clamps which fasten the cover of the device to the back of the breaker. NOTE: Pickup settings on the cover of each device are calibrated for the specific device. When replacing covers, replace on associated device.
3. Using a $5 / 16$ inch Allen Head Wrench, remove the $3 / 8$ inch bolts which fasten the coil of the overcurrent device to the breaker copper.
4. Remove the round head screw which fastens the frame of the overcurrent device to the breaker base.
5. After reassembling breaker with new overcurrent device, adjust for "positive trip" as described under "Adjustments" of this section.

NOTE: When replacing an EC-1 device with an EC-2, or vice versa, it will be necessary to replace the trip paddles on the trip shaft. These will be provided with the replacement trip units.


| 1. Series Coil | 6. Driving Segment | 11. L.T.D. Calibration Spring |
| :--- | :--- | :--- |
| 2. Magret | 7. S.T.D. Armature | 12. Instantaneous Trip Spring |
| 3. Pallet | 8. S.T.D. Calibration Spring | 13. Spring Holder |
| 4. Pinion | 9. Trip Padde Adjusting Screw | 14. Calibration Clamp. Mut |
| 5. Escape Wheel | 10. L.T.D. Armature | 15. Plunger |

1. Series Coil
.
2. Pallet
3. Escape Wheel
4. Driving Segment
5. S.T.D. Armature
6. Trip Padle Adjusting Screw
7. L.T.D. Armature
8. L.T.D. Calibration Spring
9. Instantaneous Trip Spring
10. Spring Holder

Clamp .Mut
15. Plunger
16. Cylinder
17. Calibration Plate
18. Trip Paddle
19. Trip Arm
20. Clamping Bracket

## EC-1 DEVICE

The EC-1 device can be provided with the following tripping combinations:

1. Long time delay, short time delay and instantaneous tripping.
2. Long time and short time delay tripping only.
3. Long time delay and instantaneous tripping.
4. Short time delay and instantaneous tripping.
5. Short time delay tripping only.
6. Instantaneous tripping only.
(a) Adjustable (Low set)

Nonadjustable (High set)
SHORT TIME DELAY TRIPPING, FIG. 20
The armature (7) is retained by calibrating spring (8). After the magnetic force, produced by an overcurrent condition, overcomes this restraining force, the armature movement is further retarded by an escapement mechanism which produces an inverse time delay characteristic. The mechanism ts shown in the left side view of Fig. 20.

The pickup for this device can be field set between limits having a ratio of $2-1 / 2$ to 1 in the range of 200 to $1000 \%$ of the coil rating.
LONG TIME DELAY TRIPPING, FIG. 20
The armature (10) is retained by the calibration spring (11). After the magnetic force, produced by an overcurrent condition, overcomes this restraining force, the armature movement is further retarded by a flow of silicone oil in a dashpot, which produces an inverse time delay characteristic. The mechanism is shown in the right side view of Fig. 20.

## INSTANTANEOUS TRIPPING, FIG. 20

(a) Adjustable instantaneous tripping takes place after the magnetic force produced by an overcurrent condition, overcomes the restraining force of the adjustable calibration spring (11).
(b) Nonadjustable instantaneous tripping takes place after the magnetic force produced by an overcurrent condition overcomes the restraining force of a nonadjustable calibration spring (12).

## SELECTIVE TRIPPING

Selective overcurrent tripping is the application of circuit breakers in series so that only the circuit breaker nearest the fault opens. Any one or combination of two or more of the preceding over-current devices may be used in a selective system. The breaker having the shorter time setting and lower pickup will trip before the breaker having the longer setting and higher pickup, provided the fault is on the part of the line protected by the breaker having the lower setting.

For the exact characteristics and setting of each breaker in a selective system, reference should be made to a coordination chart for the particular system.

## ADJUSTMENTS - EC-1 - Fig. 20

The EC-1 device may be adjusted for positive tripping by following the same procedure described above for the EC-2 device and using adjusting screw (9).

## REPLACEMENT - EC-1

When replacing the EC- 1 device, refer to the section entitled "Replacement" under EC-2 device.

## REVERSE CURRENT TRIPPING DEVICE - FIG. 21

The device is enclosed in a molded case and is mounted on the right pole base similarly to the serles overcurrent tripping device.

The reverse current tripping device consists of a series coil (1) with an iron core mounted between two pole pieces (7), also a potential coil (4) connected across a constant source of voltage and mounted around a rotary-type armature ( 6 ), Calibration spring (3) determines the armature pick-up when a reversal of current occurs.

As long as the flow of current through the breaker is in the normal direction, the magnetic flux of the series coil and the magnetic flux of the potential coil produce a torque which tends to rotate the armature counter-clockwise. The calibration spring also tends to rotate the armature in the same direction. This torque causes the armature to rest against the stop screw (9) attached to a bearing plate on the right side of the device.

If the current through the series coil (1) is reversed, the armature (6) tends to move in the clockwise direction against the restraint of the calibration spring (3). When the current reversal exceeds the calibration setting, the armature revolves clockwise causing the trip rod (2) to move upward engaging the trip paddle adjusting screw (15) thereby tripping the breaker.

ADJUSTMENTS - Fig. 21
The only field adjustment that should be required on the reverse current device is that of "positive tripping", which is the amount of overtravel of the trip rod (2) beyond the point of tripping the breaker. Proper overtravel is provided, if the trip rod (2) advances the trip paddle (14) $1 / 32$ to 3/64 inch beyond the point of tripping the breaker. To adjust for "positive tripping", proceed as follows:
NOTE: Be extremely cautious not to have hands near moving breaker parts when making this adjustment.

1. Manually lift the trip rod (2) as high as possible and turn the adjusting screw (15) into the trip paddle (14) until it will not touch the trip rod and trip the breaker.
2. Back-out the adjusting screw (15) to a position where the breaker is just tripped when the trip rod is lifted as far as it will go.
3. Back-out the adjusting screw (15) an additional 1-1/2 turns from the position established in step 2 and the proper overtravel should be obtained.
4. Be sure to tighten the locicing nut on the
adjusting screw.

## REPLACEMENT

After removing the wiring for the potential coil the reverse current device can be removed and replaced by following the procedure outilined for replacing the series overcurrent device. For wiring, see Fig. 21.

12. Trip Crank
9. Stop Screw
13. Screw
14. Trip Paddle
15. Adj. Screw

Fig. 21 Reverse Current Tripping Device

## BREAKER ACCESSORIES

## SHUNT TRIPPING DEVICE - FIG. 22

The shunt tripping device is mounted on a bracket attached to the right side of the operating mechanism (looking from the front).

A remote switch or relay contact is used to close the circuit of the device causing the armature (9) to engage the trip paddle (11) thereby tripping the breaker. The spring (2) is used to return the armature to the neutral position after the breaker trips.

To prevent overheating, the coil (7) is cut off by contacts of the auxiliary switch which are open when the breaker is open.

## ADJUSTMENTS

From $1 / 32^{\prime \prime}$ to $1 / 16^{\prime \prime}$ overtravel of the armatue is required when the breaker is tripped. If any adjustment is necessary to provide this amount of overtravel, the trip lever is formed in or out accordingly.

## REPLACEMENT

Coill (7)

1. Disconnect leads to coil.
2. Remove magnet (6) and coil from frame (3).
3. Bead lower end of clamp (8) straight and remove.
4. Remove coil and install new coil in reverse order.

If, for some reason, the entire device is to be replaced, this is accomplished by removing the fasteners between the shunt trip device frame (3) and supporting bracket (13).

After replacing elther the coil or the entire shunt trip device, the overtravel adjustment should be checked.

# BELL ALARM AND LOCKOUT DEVICES 

## BELL ALARM DEVICE - FIG. 23

A bell alarm device is available which operates when an overcurrent trips the breaker. It consists primarily of a lever (7) and hanger (11) riveted to auxiliary shaft (6), latch (12), catch (16), switch (1), reset lever (3), and mounting bracket (4).

When the breaker is tripped by an overcurrent the overcurrent device trip arm (8) causes lever (7), hanger (11), and latch (12) to rotate counterclockwise as a single member about pin (9). This disengages the latch from the catch (16). When the breaker opens, link (17) also releases the catch, allowing its spring to rotate it counterclockwise about pin (15). This in turn permits plunger of switch (1) to move downward, closing the lower contact of the switch and thereby completing the alarm circuit.

If the breaker is opened by means other than the overcurrent device, the latch (12) remains in position and does not allow the catch (16) to rotate even though it is released by link (17).

Operation of the reset lever (3) returns the catch and switch contacts to their original position. At the same time, spring (5) resets latch (12).

LOCKOUT DEVICE - FIG. 23
The lockout device consists of the same mechanism as the bell alarm device except that a screw (18) secures the hanger (11) to latch (12). This causes these two parts to function as a unit. Whenever the breaker is opened due to an overcurrent, the trip paddle (10) will be held in the tripped position by the lever (7), thereby locking the breaker in the open position until the lockout mechanism is reset manually by means of the reset lever (3).


1. Mtg. Screws (3)
2. Pin
3. Coil
4. Spring
5. Screws
6. Clamp
7. Magnet
8. Armature
9. Armature Arm
10. Trip Paddle
11. Frame


Fig. 22 Shunt Tripping Device

## ADJUSTMENTS

In order for the bell alarm and lockout device to function properly the following conditions must 3xist:

1. The auxiliary trip shaft (6) must swing freely from its points of suspension and hang perfectly level with respect to the breaker parts.
2. The auxiliary shaft must be positioned so that each of its clearance cut-outs has such a position relative to its respective overcurrent device trip arm that the trip arm can operate without encountering interference from the shaft and contacts the shaft only at lever (7).
3. When the breaker is closed, lever (7) must hang in a position such that it touches neither the trip arm (8) or the adjusting screw in the trip paddle (10). The optimum condition is an equidistant position.
4. The latch (12) and the catch (16) must be 80
positioned relative to one another that when the breaker is closed and reset, the latch will clear the catch when the latch is rotated counterclockwise. The catch is mounted on the same supporting bracket as switch (1). This bracket may be shifted vertically by dismounting the switch and loosening the hardware which fastens the bracket to the mechanism side frame.

## DRAWOUT BREAKER - FIG. 24

The drawout circuit breaker consists of a circuit breaker mounted in a drawout carriage which comprises the drawout mechanism. The drawout mechanism consists of guides (5), racking pins (3), racking handle (7), interlock lever (2) and an interlock arrangement which prevents the insertion and withdrawal of the breaker in the closed position. The drawout carriage is also equipped with a "test position" stop, where the secondary disconnects are engaged but the primary disconnects are safely parted. In this position the breaker may be operated for test purposes without energizing the primary circuit.


## NOTE-BELL ALARM OR LOCKOUT DEVICE OPERATES ONLY WHEN BREAKER TRIPS ON OVERCURRENT. MANUAL RESET.

1. Switch
2. Plunger
3. Reset Lever
4. Mounting Bracket
5. Spring
6. Switch
7. Auxiliary Shaft
8. Lever
9. Trip Arm
10. Pin
11. Trip Paddle
12. Reset Lever
13. Spring
14. Hanger
15. Catch
16. Link
17. Screw

Fig. 23 Bell Alarm and Lockout Device

Older model breakers were equipped with rollers in place of guides on the breaker side frames, otherwise the drawout mechanisms are similar.

It is recommended that a fresh coat of G.E. lubricant D 50 H 47 be applied to the primary disconnects at each inspection period.

For a complete description of the inserting and withdrawing the breaker from its enclosure, refer to GEH-2021A furnished with all AK breakers.

## DISCONNECTS

## PRIMARY DISCONNECTS

The primary disconnects are attached to the ends of the breaker studs on the rear side of the breaker base. Each disconnect assembly consists of two pair of opposed contact fingers. These are secured to the breaker stud by a bolt which passes through the assembly and the stud. When engaged with the stationary stud of the enclosure, the disconnect fingers exert a set amount of force against the stationary stud through the action of the compression springs. Retainers and spacers hold the contact fingers in correct alignment for engagement with the stud. The amount of force which the fingers exert against the stud is determined by degree to which the springs are compressed by the bolt and nut which hold the assembly together. If, for any reason, the disconnects must be taken apart, the position of the nut on the bolt should be carefully noted, so that in reassemblying, the original amount of compression can be restored by replacing the nut at its former position on the bolt.

## SECONDARY DISCONNECT, FIG. 25

The secondary disconnects serve as connections between breaker control circuit elements and external control circuits. They are used only on drawout type breakers. A terminal board serves the same purpose on stationary mounted and general purpose enclosure mounted breakers. The secondary disconnects allow removal of the breaker without the necessity of having to detach external connections.

The movable part of the secondary disconnect consists of an insulating body which holds a conducting spring loaded plunger to which a flexible lead is attached. As the breaker moves into its enclosure, the plunger is depressed by sliding onto the stationary disconnects of the enclosure.

## REPLACEMENT OF MOVABLE SECONDARY DISCONNECTS

1. Unfasten disconnect body from breaker back frame.
2. Open tabs which hold wires on inner side.

## 3. Pull contact tip loose from hollow tube.

oase.


1. Secondary Disconnect
2. Handle Socket
3. Interlock Lever
4. Rack-Out Handle
5. Rack-Out Pin
6. Cam Slot
7. Locking Pin
8. Guide
9. Trip Cam

Fig. 24 AK-1-25 Drawout Breaker


Fig. 25 Movable Secondary Disconnects
5. Push wire through hollow tube of new disconnect assembly.
6. Strip insulation off end of wire to about $1 / 4$ of an inch from end.
7. Place new contact tip on end of wire and crimp.
8. Pull wire through hollow tube until contact tip fits snugly against end of hollow tube.
9. Crimp tab on other side of assembly to hold wire in place.
10. Any hollow tubes which are not used should be pushed into the disconnect body and held in that position by placing fibre spacers over inner ends of tubes and spreading tabs.
11. When all wires have been connected, refasten the body of the assembly to the breaker back frame.

## WELDING BREAKERS

The type AK-1-15Y1 and AK-1-25Y1 breakers are intended for the protection of resistance welding machines. They trip instantaneously at higher current settings than breakers provided with the regular instantaneous adjustable overcurrent tripping device. This type breaker differs from the regular breaker only in the provtsion that higher current settings may be obtained.

Standard calibration ranges for type AK-1-15Y1, Fig. 26, are as follows:
a. 300 to 800 amperes
b. 600 to 1500 amperes

Standard calibration ranges for type AK-1-25Y1, Fig. 26, are as follows:


Fig. 26

| Duty Cycle (\%) | Duringweld Amp Rms | AK-1-15Y1 Breaker During-weld KVA |  |  | Duty <br> Cycle <br> (\%) | Duringweld Amp Rms | AK-1-25Y1 Breaker During-weld KVA |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 220 Volts | 440 Volts | 550 Volts |  |  | 220 Volts | 440 Volts | 550 Volts |
| 3 | 1530 | 337 | 674 | 841 | 3 | 4040 | 890 | 1780 | 2225 |
| 4 | 1325 | 292 | 584 | 729 | 4 | 3500 | 770 | 1540 | 1925 |
| 5 | 1185 | 261 | 522 | 652 | 5 | 3130 | 689 | 1378 | 1722 |
| 6 | 1080 | 238 | 475 | 594 | 6 | 2860 | 629 | 1258 | 1574 |
| 7 | 1000 | 220 | 440 | 550 | 7 | 2740 | 580 | 1161 | 1453 |
| 8 | 936 | 206 | 412 | 516 | 8 | 2640 | 544 | 1087 | 1360 |
|  | 884 | 194 | 388 | 486 | 9 | 2330 | 513 | 1025 | 1282 |
| 10 | 839 | 185 | 370 | 461 | 10 | 2215 | 487 | 974 | 1219 |
| 20 | 594 | 131 | 262 | 327 | 20 | 1566 | 345 | 689 | 861 |
| 30 | 484 | 108 | 215 | 266 | 30 | 1278 | 281 | 562 | 703 |
| 40 | 419 | 92 | 184 | 231 | 40 | 1107 | 244 | 487 | 609 |
| 50 | 375 | 83 | 165 | 206 | 50 | 990 | 218 | 436 | 545 |
| 60 | 342 | 75 | 150 | 188 | 60 | 903 | 199 | 398 | 497 |

Current and Duty Cycle Limits of Types AK-1-15YI and AK-1-25YI Breakers

## RENEWAL PARTS

When ordering renewal parts, address the nearest Sales Office of the General Electric Company, specifying the quantity required and describing the parts by catalogue numbers as shown in Renewal Parts Bulletin, GEF-3506.

In the absence of a Renewal Parts Bulletin, se described parts should be identified by giving
a. $\mathbf{6 0 0}$ to 1500 amperes
b. 1400 to 4000 amperes
c. $\mathbf{2 0 0 0}$ to $\mathbf{5 0 0 0}$ amperes

Other ranges can be provided within reasonable limits where the highest calibration settings will not exceed approximately $2-1 / 2$ times the lowest calibration setting.

These breakers are not given a continuous current rating since the duty imposed is intermittent and quite variable depending upon various types of welding to be done. The breakers are designed to safely carry"during-weld amperes" or "during-weld KVA" at welding periods not exceeding the corresponding "duty cycle" as tabulated below. ("Duty cycle" is the per cent of time that current flows in any one minute.
the complete nameplate data of the circuit breaker or accessory.

Renewal parts which are furnished may not be identical with the original parts, since improvements are made from time to time. Parts which are furnished will be interchangeable.

# AIR Circuit Breakers 



TYPE AK-1-15, 225 AMP
TYPE AK-1-25, 600 AMP
GENERAL (3) ELECTRIC
SWITCHGEAR

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FIG. I
TYPE AK-1-25 MANUALLY-OPERATED BREAKER


FIG. 3
REAR VIEW OF BREAKER WITH DISCONNECTS


FIG. 5


FIG. 2
TYPE AK-I-15 BREAKER WITH ELECTRICAL ATTACHMENTS


FIG. 4
ENCLOSING CASE WITH BREAKER


FIG. 6
MOUNTING BREAKER IN ENCLOSING CASE

## AIR CIRCUIT BREAKERS

## TYPES AK-I-15 AND AK-1-25

These instructions do not purport to cover all details or variations in equipment nor to provide for every possible contingency to be met in connection with installation, operation or maintenance. Should further information be desired or should particular problems arise which are not covered sufficiently for the purchaser's purposes, the matter should be referred to the General Electric Company.

## I

## GENERAL INFORMATION

## 1. SIMILARITY IN CONSTRUCTION

Types AK-1-15 and AK-1-25 air circuit breakers are essentially similar in construction with the exception that the AK-1-25 is built for higher continuous and interrupting ratings. This instruction book is based on Type AK-1-15 air circuit breaker, but it applies equally to type AK-1-25 after making the following allowances for ratings and construction:

[^14]g. A compound re-enforcing plate has been added to both sides of the two outside are quenchers.
h. The main shaft has been lengthened in accordance with an increase in the width of the pole bases due to an increase in the number of contacts.
i. The flexible connection is attached with four screws instead of three screws.
j. The overcurrent and the reverse current tripping devices of the AK-1-25 breakers may have series coils up to 600 amperes (AK-1-15 breakers may have series colls up to 225 amperes).

## 2. APPLICATION

These circuit breakers are generally used for the protection and control of apparatus and branch circuits, including equipment in buildings, industries, power stations and for marine application within the ratings designated above.

The circuit breakers are furnished with two or three-pole units and are available with various automatic tripping devices and accessories for overcurrent, undervoltage and reverse current protection. The center pole of the two-pole breaker is provided for mechanical construction and may be utilized for electrical connections and a series overcurrent tripping device, when needed. No contacts or stud connections are located in the center pole of a two-pole breaker.

II

## SHIPPING - UNPACKING - STORAGE

## 1. TRANSPORTATION DAMAGE

Immediately upon receipt of the circuit breaker, an examination should be made for any damage or loss sustained in transit. If injury or rough handling is evident, a damage claim should be filed at once with the transportation company and the nearest General Electric Sales Office should bepromptly notified.

## 2. UNPACKING

The circuit breaker should be unpacked as soon as possible after being received as difficulty may be experienced in making claim for damage, not evident upon receipt, if delayed. Care should be used in unpacking to avoid damaging any of the breaker paris. Be sure that no loose parts are missing or left in the packing material. Blow out any dirt or particles of packing material that may have accumulated on the breaker parts.

## 3. STORAGE'

If the circuit breaker is not installed at once, it should be stored in a clean dry place and preferablyplaced in a vertical position. It should be supported to prevent bending of studs or damage to the
breaker parts. It is advisable not to cover the breaker with any packing of other material that absorbs moisture which may cause corrosion of breaker parts. A covering of paper will prevent dust from settling on the breaker parts.

## III <br> INSTALLATION

## 1. LOCATION

The air circuit breaker should be installed in a clean dry place where it is readily accessible for operation, inspection and proper maintenance. Special enclosures are available for the installation of circuit breakers which may be subjected to dust and moisture or other unfavorable locations.

## 2. BREAKER CONNECTIONS

- The connections to the circuit breaker studs should be firmly clamped or bolted inplace to prevent excessive heating. The connecting cables or bus bars should have a current-carrying capacity sufficient to limit their temperature rise to that specified for the breakers. If these connecting cables or bus bars are not of sufficient size, heat will be conducted from them to the breaker so that the breaker cannot carry normal rated current without exceeding the specified temperature rise. Connecting cables or bus bars should be supported so that the breaker studs will not be subjected to unnecessary strains.


## 3. DEAD FRONT BREAKERS

Dead front circuit breakers are designed for mounting in a switchboard or an enclosing case. The mounting of dead front breakers consists in placing the breakers within the enclosed structure and connecting the power buses or cables and making the necessary control connections. The standard mounting depth from the back surface of the breaker base to the back side of the front panel is 8-3/4". Provision is made, when specified, for recessing breakers to a depth of 17-1/4" (see Fig. 31). The front cover of dead front breakers consists either of a hinged door with cut-out or a plate bolted to the panel. An adapter plate is used in addition to the front cover when the breaker is recessed. This plate is bolted to two angle irons furnished by the switchboard builder.

A terminal board on the right side of the breaker, Fig. 35, is used for making various control connections with breaker devices. An auxiliary switch on the left side of the breaker Fig. 16, is used for some control connections and for connecting various auxiliary accessories.

The structural surface to which the breaker is bolted must be flat through-out and the supporting structure must be of sufficient strength to hold the breaker firmly in place. Minimum cut-out dimensions must be maintained in order to have proper electrical clearance.

When disconnects, Figs. 32,33 and 34 are used, the breaker is placed against the panel so that the
disconnects fit over the stationary studs to which the power circuits are connected. Four 1/2' mounting bolts are then inserted into the holes for bolting the breaker to the panel. When the disconnects are not used, the power circuits are bolted to the breaker studs after bolting the breaker to the panel by using the four $1 / 2^{\prime \prime}$ mounting bolts. Breakers mounted in drawouts or an enclosing case (see below) are equipped with disconnects.

## 4. ENCLOSED BREAKER

The enclosed air circuit breaker is shipped in an enclosing case. Before the enclosed breaker is installed, first, remove the cover of the enclosure and the four mounting screws in the breaker base (Fig. 6). The breaker unit is then pulled forward to disengage disconnects and to remove it from the enclosing case. Knockouts at the top and bottom of the enclosing case must be removed in order that connections can be made with power cables and control equipment. Next, mount the enclosing case in the desired location and secure the cables in the solderless connectors of the enclosing case, and connect the control circuits (Fig. 5). Finally, return the removable breaker unit to the enclosing case and replace the four mounting screws and the cover to complete the installation.

## IV

## OPERATION AND MAINTENANCE

## 1. OPERATION

The circuit breaker may be closed manually with a pistol grip operating handle. Breakers equipped with a closing solenoid may be closed manually by using the operating handle, or electrically by means of a closing switch. To close the breaker manually, the operating handle must be moved approximately $90^{\circ}$ in a clockwise direction (looking from the front). The handie will drop back automatically to the "Down" position after closing the breaker. The breaker may be tripped manually by pushing a trip button located in the front part of the operating handle, or automatically by any trip device with which the breaker is equipped. The breaker is automatically reset when tripped either manually or electrically. The breaker is "trip free" from the closing mechanism which assures that it cannot be closed as long as any trip device is functioning.

## 2. MAINTENANCE

BEFORE INSPECTION OR ANY MAINTENANCE WORK IS DONE, BE S URE THAT THE BREAKER IS IN THE OPEN POSITION. ALL ELECTRICAL POWER, BOTH PRIMARYAND CONTROL SOURCES, SHOULD ALSO BE DISCONNECTED.

Periodic inspection of the circuit breaker is recommended at least once a year. More frequent inspections are recommended, if severe load conditions, dust, moisture, or other unfavorable conditions exist. A complete inspection of the breaker, including contacts and arc quenchers, should always be made after the breaker has opened a severe short circuit.

After the breaker has been installed, as well as at the regular inspection periods, slowly operate it manually several times as described above and observe whether the contacts line up properly and make sure that all parts move freely without binding or excessive friction.

If the breaker remains open or closed for a long period of time, it is recommended that arrangements be made to open and close it several times in succession, preferably under load.

If overheating, not caused by overcurrent, is observed, a complete inspection of the breaker should be made including connections, contacts and flexible connectors.

At all times it is important not to allow pencil lines, paint, oil or other foreign materials on the insulating surfaces of the breaker as they may cause low resistance between points of different potential and result in eventual electrical breakdown.

The electrically operated breaker should be opened and closed at rated voltage, to make sure that all control circuits areproperly connected and that all electrical attachments are functioning properly. It should be remembered that the closing solenoid is rated for intermittent service only. Reasonable care, therefore, should be exercised when testing to avoid overheating of the closing solenoid by repeated operations.

The contacts should be inspected at the regular inspection periods and always after a known severe short circuit has been opened to ascertain whether the contacts are badly worn or pitted, in which case they should be dressed or replaced. It is necessary to remove the arc quenchers in order to properly inspect the contacts (see "Replacements" under Arc Quencher). For a more comprehensive discussion of contacts, see Contact Assembly.

## 3. LUBRICATION

In general, the circuit breaker requires little lubrication. Bearing points and latch surfaces should be lubricated at the regular inspection periods with a thin film of extreme temperature, highpressure, light grease similar to Royco \#20 (Royal Engineering Company, Hanover, N. J.) Hardened grease and dirt should be removed from latch and bearing surfaces by using kerosene. ALL EXCESS LUBRICANT SHOULD BE REMOVED WITH A CLEAN CLOTH IN ORDER TO AVOID ANY ACCUMULATION OF DIRT OR DUST.

## V

## SAFETY PRECAUTIONS

CARE MUST BE TAKENWHEN THE CIRCUIT BREAKER IS BEING INSTALLEDANI NHEN ANY INSPECTION OR MAINTENANCE WORK IS BEING DONE THAT THE BREAKER IS IN THE TRIPPED OR OPEN POSITION. ALL CONTROL AND POWER CIRCUITS ATTACHED TO THE BREAKERS, SHOULD ALSO BE DE-ENERGIZED.


FIG. 7
TYPE AK-I-I5 SHOWING ARC QUENCHER WITH OUTS IDE BARRIER AND SIDE OF MUFFLER REMOVED

VI

## BASIC BREAKER COMPONENTS

1. ARC QUENCHER FIGS. 7 AND 8

Each arc quencher has two compound inside barriers (3) containing a large number of perforations and two outside barriers (4) without perforations, as well as a front cap (5) and a rear support (24) held in place by a fiber strap (23). A clamp (6) is attached to the breaker base by two bolts (7). Clamp (6) holds all the arc quencher assemblies to their respective pole units. A muffler (2) is located on top of the compound barriers. The compound barriers and the muffler, together with the slots between the barriers, serve to extinguish the arc.

The arc quenchers should be inspected at the regular inspection period and parts replaced, if badly burned or corroded.

## REPLACEMENTS--Arc Quencher, Fig. 8

1. Remove clamp (6) by removing two bolts (7).
2. Unclasp fiber strap (23).
3. Remove front cap (5), muffler (2), outside barriers (4), interior barriers (3) and rear support (24).


FIG. 8


FIG. 9
TYPE AK-I-I5 SHOWING CONTACT ARRANGEMENT WITH ARC QUENCHER AND AUXILIARY SWITCH REMOVED
4. Install new or disassembled parts in reverse order.

NOTE: In re-assembling the rear support (24) to the breaker, be sure and push the rear support toward the top of the pole unit so that the clearance in the rear support will accommodate the screw-head of the back plate.

## 2. CONTACT ASSEMBLY FIGS. 9 AND 10

The contact assembly of each pole unit consists of a stationary and a movable contact sub-assembly.

The stationary contact assembly consists of three parallel contact fingers (25) with silver alloy tips, the upper stud (24) and three pins (22) with compression springs (23) which provide continuous contact pressure between the contact fingers and the upper stud (24). A shunt (26) is used to prevent pitting at the pivot point of the stationary fingers when carrying high momentary currents. The stationary contact fingers are held in place by the up-. per stud cap (6).

The movable contact assembly consists of three parallel contact arms (4) with silver alloy tips, a contact carrier (21) with a spring (20) which provides continuous contact between the contact arms and pin (17). A clamp (16) secures pin (17) to the contact support (18). A flexible connection (14) is provided to prevent pitting at the pivot point of the movable contact arms when carrying high momentary currents.

The movable contact assembly is connected to the main shaft (16), Fig. 8, by an insulating link (8) for operating the contacts when the contacts close. A definite amount of contact pressure (see 'Measuring Contact Pressure") must be exerted by the movable contacts against the stationary contacts. A definite amount of contact wipe, or the distance that the stationary contacts are pushed to the rear by the movable contacts (see "Measuring Contact Wipe ${ }^{\prime \prime}$ ), must result during the closing operation. Both contact pressure and contact wipe should be checked at the regular inspection period.

## MEASURING CONTACT PRESSURE

1. Remove arc quencher (see 'Replacements' under Arc Quencher).
2. Place a push-type scale against the upper end of the stationary contact tip (3) with the breaker closed.
3. Exert pressure against the push-type scale until the contacts just part. When the contacts part, the scale should register between 4 and 6 pounds.
4. Re-assemble parts in reverse order.

## MEASURING CONTACT WIPE

1. Remove arc quencher (see 'Replacements" under Arc Quencher).


FIGIO
CONTACT ASSEMBLY
2. Ascertain the dimension between the inside surface of the pole base and the top edge of the stationary contact tip (3), (a) with the breaker open, (b) with the breaker closed.
3. Now ascertain the difference between the two measurements which should be approxdmately 7/32".
4. Re-assemble parts in reverse order.

## ADJUSTING CONTACT WIPE AND CONTACT PRESSURE

1. Removetruarc washer from main shaft (16), Fig. 8, nearest the insulating link and contact assembly to be adjusted.
2. Loosen screw (11), Fig. 10, which secures the eccentric bushing to the insulating link to be adjusted.
3. Push the main shaft (16), Fig. 8, approximately half-way through the insulating link to be adjusted.
4. Apply an adjustable expansion tool to the bushing in the insulating link and turn the bushing, thereby moving the insulating link closer or farther away from the stationary contacts, as required.
5. Re-assemble parts in reverse order and make proper adjustments.

NOTE: To adjust the insulating link in the center pole unit, first, push the main shaft through the right hand insulating link and into the center link as described in items, 2 and 3 below. (Caution: Opening spring and cap will drop out). Adjust center insulating link as described in item 4 above. Re-assemble parts in reverse order being careful to replace opening spring and cap in their proper position.

If any of the contacts are badly corroded or pitted, thereby making it impossible to adjust for proper contact pressure or contact wipe, such stationary contacts or movable contact assemblies should be replaced. See 'Replacements' below.

REPLACEMENTS-- Movable Contact Assem-
bly, Fig. 10.

1. Remove front escutcheon (see 'Replacements" under Front Escutcheon).
2. Disconnect external wiring to terminal board and auxiliary switch.
3. Remove arc quencher (see "Replacements" under Arc Quencher).
4. Remove truarc washer from one end of the main shaft and push main shaft through insulating link.
5. Remove four mounting bolts (2), Fig. 11, and lift entire operating mechanism from breaker.

Note: To remove the two lower mounting bolts (2), Fig. 11, on electrically-operated breakers proceed as follows.
a. Move left hand trip paddle to the extreme left on the trip shaft. Also remove right hand trip paddles.
b. Remove lower mounting bolts with off-set screwdriver and lift entire operating mechanism from the breaker.
6. Remove four screws (13) attaching the braid (14) to the movable contact arms.
7. Remove two screws and clamp (16).
8. Remove the movable contactassembly from the operating mechanism.
9. Remove the insulating link from the old movable contact assembly and reassemble this same link to the new movable contact assembly.
10. Remove braid (14) from new movable contact assembly.
11. Install new movable contact assembly and replace clamp (16).
12. Remove screw from left hand coil terminal.
13. Remove old braid.
14. Install new braid by re-assembling coil terminal screw and four screws (13) in movable contact assembly.
15. Replace items 3 and 4 in reverse order.
16. Adjust contact wipe and contact pressure (see above).
17. Replace items 1 and 2 in reverse order.

## Stationary Contact (25)

1. Remove arc quencher (see 'Replacements" under Arc Quencher).
2. Remove the upper stud cap (6) by removing two screws (5).
3. Pry the stationary contact (25) from upper stud (24).
4. Replace the new stationary contact in reverse order. (It may be necessary to tap the new stationary contact intoplace by using a mallet).
5. Adjust contact wipe and contact pressure (see above).


FIG. I!

## 3. OPERATING MECHANISM FIGS. 11 AND 12

The operating mechanism, Fig. 11, is supported between two molded side frames in front of the middle pole unit. It consists primarily of a toggle linkage (25), cam (19), crank (16), latch (13), trip shaft (10) and roller (15). The mechanism is connected with insulating link (8), Fig. 10, which, in turn, is attached to the main shaft (6).

The breaker is closed manually by moving the operating handle approximately $90^{\circ}$ clockwise (looking from the front), thereby straightening the toggle linkage and pushing back main shaft (6) and movable contacts to the closed position. A similar action results when the breaker is closed electrically by means of the closing solenoid (see Fig. 18). The breaker is held in the closed position by prop (28) supported on pin (3) and by latch (13) against roller (15) attached to crank (16).

The breaker mechanism is tripped by rotating trip shaft (10) and releasing trip latch (13) which causes the toggle linkage to collapse, thereby allowing the opening springs (21) to push forward the main shaft and movable contacts to the open position. Trip latch (13) is automatically reset during the opening operation. Stop (14) limits the rotation of trip shaft (10) and thus determines the amount of latch engagement.

ADJUSTMENTS--Latch (13) is adjusted at the factory to provide approximately $1 / 16^{\prime \prime}$ engagement between latch (13) and roller (15) when the breaker is closed. To adjust for proper latch engagement, first, loosen lock nut of adjusting screw (18) on the buffer paddle, to the left of the mechanism frame, and back off several turns on this same adjusting screw. Then close breaker and place $1 / 16^{\prime \prime}$ shim between end of adjusting screw (18) and buffer paddle (11). Now advance adjusting screw (18) until the breaker just trips. Tighten lock nut.

The adjusting screw on top of cam support (20) is used to provide between $1 / 32^{\prime \prime}$ and $1 / 16^{\prime \prime}$ clearance between latch (13) and roller (15) with the breaker in the open position. With this amount of clearance, the breaker mechanism will reset automatically during the closing operation, and, at the same time, provide the necessary overtravel for prop (28) to move on pin (3). If not enough clearance is provided between latch (13) and roller (15), the breaker mechanism will not reset. If too much clearance is provided, prop (28) will not move on top of pin (3) and the breaker will not reclose because cam support (20) will move against the inner surface of the front escutcheon during the closing operating. By applying an allen wrench to screw on top of the cam support (20), and either advancing or backing off on this same screw, as required, the proper adjustment can be made.

REPLACEMENTS--Operating Mechanism, Fig. 11.

1. See 'Replacements" under Movable Contact Assembly, items 1 to 5.
2. Replace operating mechanism in reverse order.


FIG. 12

PARTIAL VIEW OF OPERATING MECHANISM

## Two Opening Springs (5)

1. Remove arc quencher (see 'Replacements" under Arc Quencher).
2. Remove truarc washer from end of main shaft (16), Fig. 8, nearest to spring to be installed.
3. Push main shaft to opposite side of operating mechanism. (Cap (4) and spring (5) will back up into slot occupied by main shaft.)
4. Remove cap (4) and spring (5) from slot by using small screwdriver.
5. Install new springs in reverse order after assembling cap (4) to new spring and push-. ing cap and spring in place.
Tension Spring (21)
6. Remove operating mechanism (see " Re placements" under Movable Contact Assembly, items 1 to 5 ).
7. Remove paddles from the trip shaft on the right side of the breaker.
8. Remove truarc washer from right side of trip shaft.
9. Remove return spring (12).

```
POSITION INDICATOR
RETAINING RING
SPRING
SLOT
TRIP EUTTON
TRIP ROD
SPLIT WASHER
NANE PLATE
OPERATING HANDLE
ROLLER
TRIP PADOLE
SHAFT
CAM
```

FIG. 13
FRONT ESCUTCHEON AND OPERATING HANDLE ASSEMBLY
5. Remove top bolt (26).
6. Remove nut from right end of bottom bolt (26).
7. Remove right hand mechanism frame.
8. Remove tension spring (21).
9. Replace new tension spring in reverse order.

NOTE: To replace torsion springs (24 and 27), follow procedures for removing tension spring (21) as above and, in addition, remove the necessary truarc washers and pins.

## 4. FRONT ESCUTCHEON AND OPERATING HANDLE ASSEMBLY FIG. 13

The front escutcheon is mounted on front of the operating mechanism frame by four screws (9), Fig. 8. The front escutcheon and operating handle assembly consists of:
a. A pistol grip operating handle (9) attached to one end of the shaft (12) which extends through the front escutcheon.
b. A roller (10) attached to the other end of the shaft.

The breaker is closed manually by turning the operating handle clockwise approximately $90^{\circ}$ causing roller (10) to engage cam(13), thereby straightening a toggle linkage (25), Fig. 11, and closing the breaker. After closing the breaker, the operating handle will return automatically to the "Down"position. The trip button (5), in the front part of the operating handle, is pushed to the rear to trip the breaker manually.

The breaker may be locked in the tripped position by pushing the trip button to the rear and inserting a padilock through slot (4) in the metal ferrule.

## REPLACEMENTS--Front Escutcheon Assembly

1. Remove four mounting screws (9), Fig. 8.
2. Now pull forward on the operating handle turning and tipping the front escutcheon slightly until dislodged from the breaker.
3. To remount the front escutcheon assembly, first, hold the trip shaft in a trip free position. Then pull the cam support (20), Fig. 11, slightly forward.
4. Insert the shaft (12) and roller (10) into the hole of the cam support so that the roller (10) drops behind cam (13).
5. Replace the four mounting screws to secure the front escutcheon assembly to the mechanism frame.


FIG. 14

## LINKAGE FOR POSITION INDICATOR AND AUXILIARY SWITCH

## REPLACING THE OPERATING HANDLE

1. Remove the short set screw from the tapped hole in the operating handle. (See Section $\mathrm{A}-\mathrm{A}$ ).
2. Back off a second longer set screw from the same tapped hole until it is moved clear of the shaft.
3. Pull forward on operating handle until trip rod (6) is released from the front escutch-
eon and shaft (12). Remove the trip rod and returning spring (3) from the operating handle by pushing the trip rod forward through the operating handle. (For removing shaft (12), see 'Recessing the Standard Breaker" under Extension for Recessed Breakers, items 3 and 4.)
4. Re-assemble operating handle to front escutcheon and shaft (12) in reverse order.

Note: In replacing set screws in operating handle, it is important that the short set screw in item (1) above, is replaced after the long set screw in item (2) has been replaced.

To provide for sufficient clearance between the long set screw and trip rod (6), the long set screw is advanced until it just binds the trip rod. Then back off on set screw one turn. After locking the long set screw with the short set screw, check trip rod (6) to see that it moves freely.

## 5. POSITION INDICATOR FIGS. 14 AND 15

The mechanism of the position indicator is mounted on the left side of the operating mechanism frame (looking from the front). It consists of a link (5) connected with the main shaft (6), crank (3) and shaft (4).

The stationary green target (9) is mounted behind a window (10) in the front escutcheon (15) and indicates when the breaker is in the open position. The red target (11) which indicates when the breaker is in the closed position, is actuated by the main shaft (6) through link (5) and crank (3), thereby moving the red target in front of the indicator window. Shaft (4) serves as a pivot for crank (3) which, in turn, also operates the rotary auxiliary switch (see 'Rotary Auxiliary Switch"Fig. 16). When the breaker opens, the main shaft moves the crank upward causing the red target to drop below the window which allows the stationary green target to become visible.

REPLACEMENTS--The position indicator is a sub-assembly of the operating mechanism and is replaced when the operating mechanism is replaced.


FIG. I5

## 6. ROTARYAUXILLARY SWITCH FIGS. 16 AND 17

The auxiliary switch is mounted on the left de of the operating mechanism frame (looking rrom the front). The main shaft of the breaker operates a crank (3) when the breaker opens or closes which, in turn, actuates a shaft (4) extending through the various stages of the device, thereby opening and closing the " $a$ " and ' $b$ " contacts of the auxiliary switch (the "1a" contacts open when the breaker opens and the " $b$ " contacts open when the breaker closes). The opening and closing operation of the contacts is determined by the arrangement of cams (16) assembled on the shaft (4) extending through the device.

ADJUSTMENTS--The contacts of any stage may be changed from " $a$ " to " $b$ " or vice versa. If changes are desired in the operating of the contacts, an approved drawing of the cam (16) arrangement should be obtained or a careful sketch made. In order to change an "a" contact to a "列" contact, it is necessary to remove the four tie bolts (2) and change the
position of the particular cam $90^{\circ}$ in relation to the shaft. Contacts should be cleaned occasionally to insure proper performance.

## REPLACEMENTS--Rotary Auxiliary Switch, Fig. 16

1. Disconnect all leads to the auxiliary switch.
2. Remove mounting bolt (1) and screw (6) removing device from breaker.
3. If no approved sketch of the cam (16) arrangement is available, remove the end plate ( 9 ) from the device by removing the four tie bolts (2) and draw a sketch of the position of the particular cam in relation to the shaft.
4. Before installing the new device, see that the cams are in the sameposition as in the device that is being replaced.
5. Install the new device in reverse order.


| 1 | MOUNTING BOLT | 11 |
| :--- | :--- | :--- |
| 2 | TIE BOLT | 12 |
| 3 CRANK | 13 |  |
| 4 SHAFT | 14 |  |
| 5 PIN | 15 |  |
| 6 SCREW | 16 |  |
| 7 LINK (SEE FIG. 15 ) | 17 |  |
| 8 BOTTOM GOVER | 18 |  |
| 9 END PLATE | 19 |  |
| 10 SLOT (SEE FIG.15) | 20 |  |



TOP COVER
"a"CONTACTS
CONTACT SPRING
ROGKER ARM
PIN
GAM
"b" CONTACTS
"b" TERMINALS
"d" TERMINALS
BARRIERS

FIG. 16

ROTARY AUXILIARY SWITCH



FIG. 17


FIG. 18
CLOSING SOLENOID

## ELECTRICAL CLOSING COMP ONENTS

A closing switch, a closing solenoid and a solenoid control device are provided for closing the breaker electrically.

## 1. CLOSING SWITCH FIG. 19

The closing switch is located in the lower right hand corner of the front escutcheon (1).

A push button extends through the front escutcheon and is supported by bracket (3). Spring (6) returns the push button to a neutral position after the movable contact (8) has momentarily engaged the stationary contacts (12). Two retainers (2) and spacer (7) are used to hold the movable contact in place.

The stationary contacts (12) and insulation strip (13) are attached to the closing solenoid by bracket (9) and screws (10). A remote closing switch is also available to close the circuit of the solenoid control device, thereby energizing the closing solenoid.

ADJUSTMENTS--The closing switch requires no attention, other than cleaning of contact occasionally.

## 2. CLOSING SOLENOD FIGS. 17 AND 18

The closing solenoid is located directly below the operating mechanism. It consists of a coil (10), magnet (9) and armature (11) with four closing links (12), a plumger (8) and cut-off lever (6).


FIG. 19
GLOSING SWITCH

The closing solenoid is connected in series with the main contacts of the solenoid control device (see Fig. 20A) and is energized or de-energized when the main contacts are closed or opened respectively. When the closing solenoid is energized, its armature (11) is drawn downward into the coil (10) pulling the four closing links (12) in the same direction and straightening the toggle linkage (16) of the operating mechanism, thereby closing the breaker. At the same time that the armature is drawn downward, the plunger (8) which is attached to the armature, engages one end of the cut-off lever. The other end of the cut-off lever moves upward and pushes the trip rod (2) of the solenoid control device (see also Fig. 20A), releasing latch (14), Fig. 20A, thereby opening the contacts of the solenoid control device, which, in turn, opens the circuit of the closing solenoid.

ADJUSTMENTS--An adjusting screw (3) in the cut-off lever (6) is used to provide the required overtravel of trip rod (2). In making this adjustment, first, close the breaker. Advance adjusting screw (3) so that the collar (7), screwed to the plunger (8), may be pulled downward as far as it will go. Then remove the cover in.front of the terminals on the solenoid control device (1) and push the armature (1), Fig. 20A, as far downward as possible by taking a thin screwdriver in the left hand and inserting it in a slot on the left hand side of the upper part of the solenoid control device. (The screwdriver is inserted about $1-1 / 2^{\prime}$ making approximately a 150 angle to the left and a 450 angle downward). Next, use the right hand to back off adjusting screw (3) to the point where the trip rod (2) releases latch (14), Fig. 20A. Then back off adjusting screw one additional turn to provide the required overtravel of trip rod (2).

A stop screw (5) in the cut-off lever (6) is used to provide approximately $1 / 16^{11}$ clearance, between the movable pin (14) and the upper edge of the slot of the closing links (12) when the breaker is in the open position. This clearance determines the proper position of the cut-off link when the breaker is open.

## REPLACEMENTS--Closing Solenoid, Fig. 18

1. Remove solenoid control device (see "Replacements" under Solenoid Control Device).
2. Remove two nuts and collar (7) from plunger (8).
3. Remove four screws attaching lower part of magnet to upper part of magnet.
4. Remove two screws attaching upper part of magnet to the two side frames of the operating mechanism.
5. Install new closing solenoid in reverse order.

## REPLACEMENTS--Coil (10)

1. Remove lower member of magnet (9), (See 'Replacements" above under Closing Solenoid, items 1 to 3).
2. Remove coil (10).
3. Remove brass coil guides.
4. Install new coil in reverse order.

```
I armature
2 COIL
3 MAgNET
4 \text { PLUNGER}
5 LOCK NUT
6 CAP NUT
7 SCREW
8 LEvER
9 PIN
```

10 SPRING
II INSULATION
12 TRIP ROD
13 SWITCH
14 TRIP LATCH
15 TOGGLE LINKS
16 SEAL-IN CONTACTS
17 MAIN CONTAGTS
18 bracket

FIG. 20A
SOLENOID CONTROL DEVICE

## 3. SOLENOID CONTROL DEVICE FIGS. 17 AND 20A

The solenoid control device is mounted in a molded case to the left and below the operating mechanism (looking from the front). It consists primarily of a magnet (3), coil (2), armature (1) and two sets of contacts.

The coil becomes energized when the closing switch closes the circuit of the device. At the same time, armature (1) is drawn downward, engaging a lever (8), pivoted on pin (9) at the bottom of the molded case. As the armature (1) pushes one end of the lever downward, the other end moves upward, straightening a toggle linkage (15) and closing the seal-in contacts (16), as well as the main contacts (17). The seal-in contacts are connected in parallel with the closing switch and provide a path for shunting the current around the closing switch. The closing solenoid, at the end of its stroke, opens the seal-in and main contacts of the solenoid control device which, in turn, de-energizes the closing solenoid.

The closing switch must be opened to permit the control device to reset, thereby preventing pumping of the breaker during the closing operations. The seal-in contacts (16) assure the closing of the breaker even though the circuit is closed only for a very brief time by the closing switch.

ADJUSTMENTS--The cut-off lever (6), Fig. 18, is adjusted by using the adjusting screw (3) so that the control device is tripped just at the end of the stroke of the closing solenoid (see "Adjustments" under Closing Solenoid).

A contact wipe of $1 / 8^{\prime \prime}$ must be provided for the proper operation of the main contacts of the solenoid control device. To check this adjustment, first, remove the cover of the device. Then push the armature (1) down into the coil (2) as far as it will go. Next, loosen lock nut attached to the plunger, and turn the cap nut either in or out until the main contacts just make. Then advance the cap nut one and one-half turns. The cap nut must now be locked in place by tightening the lock nut.

The adjusting screw (7) in the lever (8), below the molded case, is used to adjust for the opening of the switch located on the bottom exterior surface of the molded case of the control device. These contacts should open after the seal-in contacts make and before the main contacts are completely wiped in. It is recommended that a continuity meter be connected across the terminals for checking the adjustment of these contacts. A diminution in intensity will be noticed when the contacts open. The adjusting screw should be turned in or out until this condition is fulfilled.

## REPLACEMENTS--Coil (2)

1. Disconnect all leads to the device.
2. Remove two mounting screws on top of device.
3. Remove one mounting screw on bottom of device.

## 4. Remove device.

5. Remove front cover.
6. Remove insulation over terminals on back of the cover.
7. Disconnect leads to the coil.
8. Remove two screws on back of case, and remove solenoid of control device.
9. Remove two nuts from plunger.
10. Remove armature.
11. Remove brass guides after removing two screws attaching brass guides to magnet.
12. Remove coil.
13. Install new coil in magnet in reverse order. Also connect coil leads to the terminals on back of the cover.
14. Re-assemble solenoid in the molded case and replace cover.
15. Replace device on the breaker and connect leads.

## Solenoid Control Device, Fig. 20A

Note: For replacing the solenoid control device, see "Replacements" items 1 to 4 under Coil (2) above.


FIG. 20B
INTERNAL VIEW OF SOLENOID CONTROL DEVICE SHOWING WIRING


## VIII

## PROTECTIVE DEVICES

## TMME DELAY UNDERVOLTAGE TRIPPING DEVICE FIG. 21

, The device is mounted to brackets by six screws to the right of the shunt trip device (looking from the front). The purpose of this device is to trip the breaker when the voltage falls below a pre-determined value. It consists of an armature (3), coil (15), magnet (14) and cylinder (10) contalning plunger (12) which operates in oil.

When the voltage goes below a pre-determined value, spring (4) draws the armature and plunger upward causing the oil in the cylinder to flow downward through the clearance between the cylinder and the plunger. This flow of oil determines the extent of time delay before the breaker trips.

As soon as the plunger has been lifted out of the contracted part of the cylinder, the restraint of the armature will be easily overcome by the pull of spring (4), since the oil will now flow rapidly down to the bottom of the cylinder through the opening around the plunger and the wider part of the cylinder, causing the breaker to trip.

ADJUSTMENTS--A $n$ adjusting screw (20) in the trip lever is used to allow from $1 / 32^{\prime \prime}$ to $1 / 16^{\prime \prime}$ overtravel of the trip lever after tripping the breaker.

The adjusting screw (18) is used to adjust the anmature pick-up to $80 \%$ of the normal voltage and to
$W$ the armature to drop out between 30 and 60 r-cent of normal voltage.

Adjusting nut (8) on connection rod (11) is intended for a minimum amount of adjustment of the time delay setting. In order that the amount of armature air gap may be limited to $1 / 4^{\prime \prime}$ to $5 / 16^{\prime \prime}$ after the breaker is in the tripped position, adjusting screw and nut (2) make it possible to maintain this air gap and, at the same time, serve as an armature stop when the breaker trips, due to a drop in voltage. This limitation of the armature air gap is important, otherwise the armature would not be attracted to the armature after normal voltage is restored. From $1 / 4^{\prime \prime}$ to $3 / 8^{\prime}$ of oil should be maintained in the cylinder at all times. In order to make an inspection of the oil, the cylinder may be unscrewed from the cap. G.E. silicone oil 9981 LT 40NV, or similar grade, should be used in the cylinder.

## REPLACEMENTS--Time Delay Undervoltage Device, Fig. 21.

1. Disconnect coil leads (15).
2. Remove two screws from bracket (1). (Bracket (1) is omitted when the instantaneous undervoltage device is used).
3. Remove four mounting screws (21).
\$. Remove the device.
4. Install the new device in reverse order.

Coil (15)

1. Disconnect the lears to the coil.
2. Remove two screws (16).
3. Remove magnet and coil assembly.
4. Straighten laminations around shading ring
5. Remove shading ring.
6. Straighten lower end of coil clamp (13).
7. Remove coll.
8. Install new coil in reverse order.

## 2. INSTANTANEOUS UNDERVOLTAGE TRIPPING DEVICE

This undervoltage tripping device is constructed similarly to the time delay undervoltage tripping device with the exception that the cylinder (10), plunger (12), connecting rod (11), clevis (7), bracket (1) and adjusting nut (8), as shown in Fig. 21, are omitted.

ADJUSTMENTS--See "Adjustments" under Time Delay Undervoltage Tripping Device aboye.

REPLACEMENTS--See above "Replacements" under Time Delay Undervoltage.

## 3. SERIES OVERCURRENT TRIPPING DEVICE FIGS. 22A TO H, 23, 24 AND 25

Each series overcurrent tripping device is enclosed in a molded case and mounted by three screws and a bracket to the lower part of the pole unit base.

Various series overcurrent tripping devices are provided with the following tripping combina-
tions:

1. Long-time, short-time and instantaneous tripping.
2. Long-time and instantaneous tripping.
3. Short-time and instantaneous tripping.
4. Instantaneous tripping
(a) Adjustable
(b) Non-adjustable

The long-time delay mechanism consists of an armature (2i) which operates plunger (14) in a cylinder (15) containing silicone oil, and a calibration
spring (19).

[^15]The instantaneous mechanism consists of:


FIG. 22A
SHORT TIME DELAY (LEFT SIDE VIEW)


FIQ 228 Short time delay AND LONB TIME DELAY (FRONT VIEW)


FIG 22C LONG TINE DELAY (RIGHT SIDE VIEW)


SERIES OVERGURRENT TRIPPING DEVICES (A,B,C,D,E,F,G AH)
$\qquad$


FIG. 220
INSTANTANEOUS (NON-ADJUSTABLE) TRIPPING DEVICE (FRONT VIEW)


FIG. 22 E INSTANTANEOUS (ADJUSTABLE) TRIPPING DEVICE (FRONT VIEW)


FIG. 22 F INSTANTANEOUS A
SHORT TIME TRIPPING DEVICE
(FRONT VIEW)


FIG. 22 G INSTANTANEOUS a (FRONT VIEW)


FIG. 22 H INSTANTANEOUS, SHORT TIME a LONG TIME RIPPING DEVICE (FRONT VIEW)
(a) An adjustable spring (30), armature (21), calibration slide (18) and calibration clamp nut (16).
(b) A non-adjustable spring (25), armature (21) and bracket (26).


FIG. 23
SCHEMATIC VIEW SHOWING OVERCURRENT SHORTTIME, LONG-TIME AND INSTANTANEOUS TRIPPING MECHANISM

All three tripping features are actuated by a magnet (8) and the series coil (13). The ranges of armature pick-up for the various types of overcurrent tripping are:

1. Long-time--approximately 80 to 160 percent breaker rating.
2. Short-time--approximately 500 to 1000 percent breaker rating.
3. Instantaneous
(a) Adjustable--approximately 80 to 250 percent breaker rating.
(b) Non-adjustable Without Long and Short-time 400 to 1000 percent breaker rating or interrupting capacity, whichever is lower, with frame-size only.
With Long-time
400,900 and 1500 percent breaker rating.
With Long-time and Short-time
400 to 5000 percent breaker rating or interrupting capacity, whichever is lower.

With Short-time
400 to 5000 percent breaker rating or interrupting capacity, whichever is lower.
Note: Non-adjustable instantaneous pick-up is set at the factory.

In long-time tripping, the armature is restrained by calibration spring (19). After the magnetic force, produced by an overcurrent condition, overcomes this restraining force, the armature movement is retarded by the flow of oil through an orifice in the plunger which produces an inverse timedelay characteristic.

In short-time tripping, the armature is restrained by calibration spring (9). After the magnetic force, produced by an overcurrent condition, overcomes this restraining force, the armature movement is retarded by an escapement mechanism which produces an inverse time-delay tripping characteristic.

Instantaneous Tripping:
(a) Adjustable instantaneous tripping takes place after the magnetic force produced by an overcurrent condition, overcomes the restraining force of calibration spring (30).
(b) Non-adjustable instantaneous tripping takes place after the magnetic force produced by an overcurrent condition, overcomes the restraining force of the non-adjustable spring (25).

Typicaltime-current characteristics are shown in Figs. 25A and 25B, which illustrate the time and current pick-up values of the threetripping features of the series overcurrent tripping device.


FIG. 24
ADJUSTING OVERCURRENT DEVICE FOR POSITIVE TRIPPING

CURRENT IN TIMES COIL RATING


FIG 25 A

## LONG-TIME AND INSTANTANEOUS

 TRIPPING CHARACTERISTICCURRENT $\mathbb{N}$ TIMES COIL RATING


FIG. 25 B
LONG-TIME, SHORT-TIME AND instantaneous tripping characteristic

TYPICAL TIME-CURRENT CHARACTERISTICS
OF SERIES OVERCURRENT TRIPPING
STARTING COLD IN $25^{\circ} \mathrm{C}$ AMBIENT

Selective tripping is obtained when the breakers in the electrical distribution system are arranged on the basis of a progressive series of time and current pick-up. This will allow the breaker having the shorter time setting and the lower pickup to trip out before the breaker having the longer time setting and the higher current pick-up, provided the fault is on that part of the line protected by the breaker having the lower setting. Hence, if a fault occurs in any part of the electrical system, only the breaker nearest to the fault will trip out.

In order to reduce the possibility of damaging the equipment and to provide maximum safety to the operator, the overload caused by a fault is removed in a minimum amount of time by selective tripping. Overloads producing current up to 5 or 10 times the breaker rating are removed in a matter of a few seconds, while currents in excess of this value are removed in a fraction of a second.

For the exact characteristics and setiing of each breaker in a selective system, reference should be made to the co-ordination chart furnished for the particular system.

ADJUSTMENTS--Calibration nuts in front of the device are used to determine the desired pickup for short-time, long-time and instantaneous tripping.

To adjust for approximately $1 / 32^{\prime \prime}$ overtravel of the armature:

1. Take a rod or wire and push the armature (21) against the magnet through holes in the nameplate (see Fig. 24).
2. Turn the adjusting screw in the trip paddle in or out until the breaker trips.
3. Advance the adjusting screw an additional $1 / 16^{\prime \prime}$ which provides the required amount of overtravel.

## REPLACEMENTS--Series Overcurrent Tripping Device

1. Remove two screws (23) to detach bracket (22).
2. Remove screws (27) and (29) detaching device from flexible braid, contact support and upper stud.
3. Remove device after removing mounting screw (28).
4. Replace the new device in reverse order.
5. Adjust the new device (see above).

NOTE: No component parts of the overcurrent tripping devices are replaced. It will be necessary to install a new device when parts are worn or damaged. When a new device is installed, it must be adjusted as above.
4. REVERSE CURRENT TRIPPING DEVICE FIGS. 26 AND 27

The device is enclosed in a molded case and is mounted on the right pole base similarly to the series
overcurrent tripping device (see under "Series Overcurrent Tripping Device"). In case the breaker is equipped with three overcurrent tripping devices, the reverse current tripping device is attached to a fourth pole base.

The reverse current tripping device consists of a series coil (1) with an iron core mounted between two pole pieces (7), also a potential coil (4) connected across a constant source of voltage and wound around a rotary-type armature (6). Calibration spring (3) determines the armature pick-up when a reversal of current occurs.

The device is designed for d-c current only and is used to trip the breaker when a reversal of current occurs which exceeds the calibration setting of the armature pick-up. As long as the flow of current through the breaker is in the normal direction, the magnetic flux of the series coil and the magnetic flux of the potential coil produce a torque which tends to rotate the armature counter-clockwise (looking from the right side of the breaker). The calibration spring also tends to rotate the armature in this same direction, and, at the same time, causes the armature to exert pressure against the stop screw (9) attached to a bearing plate on the right side of the device (looking from the right side of the breaker).

If the current through the series coil (1) is reversed, the armature (6) tends to move in the clockwise direction against the restraint of the calibration spring (3). When the current reversal exceeds the calibration setting, the armature revolves clockwise causing the trip rod (2) to move upward engaging the trip paddle (14) and tripping the breaker.


FIG. 26
REVERSE CURRENT TRIPPING DEVICE LOCATED ON BREAKER


FIG. 27
REVERSE CURRENT TRIPPING DEVICE

A counterweight (8) is riveted to the armature which serves to counterbalance the trip rod assembly. This counterweight also serves as a stop for stop screw (9) on the bearing plate. This stop screw is used to maintain the proper air gap between the armature and the pole pleces when the current flows normally through the breaker (see "Adjustments" below). The potential coil should be connected with "a" contacts of the auxiliary switch so that the potential circuit will be opened when the breaker opens.

ADJUSTMENTS--No adjustment should be made in the field with the exception of checking for overtravel of the trip rod. Proper overtravel of the trip rod is provided, if the trip rod advances the trip paddle between $1 / 32^{\prime \prime}$ to $3 / 64^{\prime \prime}$ beyond the point where the breaker trips. To adjust for this amount of overtravel, lift the trip rod as high as possible after backing off adjusting screw in the trip paddle (14) so that it will not touch the trip rod (2). With the trip rod still pulled upward, advance adjusting screw in the trip paddle until the breaker trips. Then advance this same adjusting screw an additional 1-1/2 turns, thereby assuring positive tripping.

If any other adjustments are necessary, the device should be returned to the factory.

## REPLACEMENTS--Reverse Current Tripping Device

1. Remove two screws to detach mounting bracket. See 'Replacements' under Series Overcurrent Tripping Device.
2. Remove two screws (11) and (13) to detach series coll (1) from the contact block and lower stud.
3. Remove device after removing mounting screw (10).
4. Install the new device in reverse order.

NOTE: No renewal of parts for the device are supplied. After the new device has been installed, the adjusting screw in the trip paddie should be used to provide for the proper overtravel of the trip rod as described above under "Adjustments".

## IX

## MISCELLANEOUS

## SHUNT TRIPPING DEVICE FIGS. 17 AND 28

The shunt tripping device is mounted on a bracket attached to the right side of the operating mechanism frame (looking from the front). It consists of a coil (7), magnet (6), armature (9) and returning spring (2). A remote switch or relay contacts are used to close the circuit of the device causing the armature to engage the trip paddle (11), thereby. tripping the breaker. The tension spring (2) is used to return the armature to a neutral position after the breaker trips.

The shunt trip device is connected with the "a" contacts of an auxiliary switch which open the cir-


FIG. 28
SHUNT TRIPPING DEVICE
cuit when the breaker opens. This prevents overheating of the coil since the coil is designed for intermittent service only.

ADJUSTMENTS--From $1 / 32^{\prime \prime}$ to $1 / 16^{\prime \prime}$ overtravel of the armature is required when the breaker is tripped. If any adjustment is necessary to provide this amount of overtravel, the trip lever is bent in or out accordingly.

REPLACEMENTS--Shunt Trip Device, Fig. 28

1. Disconnect leads to coil (7).
2. Remove the device from bracket by removing four screws (1).
3. Install new device in reverse order.

NOTE: When a second shunt trip is used, the terminal board and bracket must be removed before the second shunt tripping device can be detached. See "Replacements" under Terminal Board.

## Coil (7)

1. Disconnect leads to coil.
2. Remove two screws (5) removing magnet (6) and coil (7).
3. Remove clamp (8) after bending straight lower end of clamp.
4. Remove coil.
5. Install new coil in reverse order.

Spring (2)

1. Disconnect leads to coil (7).
2. Disconnect device from bracket by removing screws (1).
3. Remove spring (2).
4. Install new spring in reverse order.

## 2. BELL ALARM DEVICE FIG. 29A

A bell alarm device is available which operates when an overcurrent trips the breaker. It consists primarily of a lever (10) riveted to auxiliary shaft (9), hanger (14) also riveted to auxiliary shaft (9), latch (15), catch (19), switch (1), reset link (3), reset arm (6), reset button (4) and mounting bracket (7).

Lever suspended between trip arm (11) and trip paddle (13) is actuated by trip arm (11) whenever an overcurrent occurs which trips the breaker, causing hanger (14), pivoted to pin (12) to revolve 1 atch (15) counter-clockwise, thereby releasing catch (19). As the breaker opens, main shaft (17) moves link (20) forward, revolving catch (19) counterclockwise on pin (18), causing plunger (2) to drop and close the lower contacts of switch (1) which re? sults in the ringing of a bell.


1. SWITOH
2. PLUNGER
3. RESET LINK
4. RESET BUTTON
5. PIN
6. RESET ARM
7. MOUNTING BRACKET
8. SPRING
9. AUXILIARY SHAFT
10. LEVER
iI. TRIP ARM
11. PIN
12. TRIP PADDLE
13. HANGER
14. LATCH
15. TRIP SHAFT
16. MAIN SHAFT
17. PIN
18. CATCH
19. LINK


RIVET A SPACER (2I)ADDED OTHERWISE SAME AS FIG. 20 A.

FIG. 29A
FIG. 29B

In order to silence the bell, it is necessary to push down on reset button (4) in front of the breaker. The resetting of the bell alarm mechanism silences the bell.

The reset mechanism is operated by reset but--on (4) actuating link (3), which, in turn, revolves reset arm (6) on pin (5), thereby returning catch (19) to its lower position and moving plunger (2) upward, and opening the lower circuit of switch (1). At the same time, spring (8) returns latch (15) to its normal position so as to engage catch (19).
3. LOCKOUT DEVICE FIG. 29B

A lockout device is available which consists of the same mechanism employed in operating the bell alarm device with the addition of a spacer and a rivet (21) inserted in the right side hanger (14) and latch (15). This causes these two parts to operate as a unit, which results in keeping the trip paddle (13) in the tripped position whenever an overcurrent occurs which trips the breaker, thereby locking the breaker in the open position until the lockout mechanism is reset and the bell is silenced as above.

## 4. ENCLOSING CASE AND INTERLOCK DEVICE FIG. 30

The enclosing case has a cover (12) with a cutout (11), through which the front part of the escutch-
eon and the operating handle extend. The cover is attached to the enclosing case by four trunk-11ke latches (6).

The breaker rests on two supports (5) welded on opposite sides of the enclosing case. Four other supports (3) are used to secure the breaker by four mounting bolts after it has engaged the disconnects. An additional bolt in each of the four supports serves as a stop for mounting the breaker.

Three sub-bases (1) are bolted to the rear of the enclosing case to which the upper (2) and lower studs (4) are bolted. The studs have solderless connectors for securing the cables of the power circuits.

An interlock device iswelded on the lower right hand side of the metal enclosure (looking from the front). The interlock serves to trip the breaker when the front cover is removed. It consists of a trip rod ( 9 ), extending through the cam (10) and held in place by bracket (8), also a compression spring ( 7 ) on the rear of the trip rod. When the cover is clamped on the enclosing case, spring (7) is compressed between the cam and the support. Then, when the cover is removed, spring (7) is released and the rear end of the cam moves upward engaging the trip paddle, thereby tripping the breaker.

I.SUB BASE
2.UPPER CONNECTOR
3.SUPPORTS
4.LOWER GONNECTOR
5.SUPPORT
G.LATGH
7. SPRING
8.BRACKET
9.TRIP ROD
10.CAM
II.OPENING FOR FRONT ESCUTCHEON
12. COVER

FIG. 30

## 5. EXTENSION FOR RECESSED BREAKERS FIG. 31

A special shaft (9), trip rod (8) and adapter plate (2) is supplied to recess the breaker $171 / 4^{\prime \prime}$ from the rear of the front plate (2) of the switchboard to the rear of the breaker base. The special shaft and trip rod will replace the standard shaft and trip rod with which the breaker is equipped.

## RECESSING THE STANDARD BREAKER

1. Remove the front escutcheon (see 'Replacments" under Front Escutcheon and Operating Handle Assembly ).
2. Remove the operating handle (see "Replacing Operating Handlei under Front Escutcheon and Operating Handle Assembly).
3. Remove retaining rings ( 11 and 14).
4. Push standard shaft to the rear, thereby removing it from front escutcheon.
5. Insert special shaft (9 9 through rear of front escutcheon.
6. Assemble washer (15) and retaining rings (11 and 14) to special shaft (9).
7. Assemble front escutcheon to breaker (see "Replacements" under Front Escutcheon and Operating Handle Assembly).
8. Assemble hand stop (10) to special shaft (9).
9. Attach front plate (2) to angle irons (6) by using four screws. (Angle irons are supplied by the switchboard builder).
10. Secure the frontpart of shaft (9) to plate (2) by using hollow hexagon screw (4) with nut and washer.
11. Lock hexagon screw (4) by using set screw. Attach operating handle and trip rod to shaft by reverse procedure when removing operating handle. (See "Replacing Operating Handle" under Front Escutcheon and Operating Handle Assembly.)
12. Disassemble trip button from standard trip rod and assemble it to special trip rod.


FIG. 31

## EXTENSION FÖR RECESSED BREAKERS

## 6. DISCONNECTS FIGS. 32, 33 AND 34

The disconnects are attached to the circuit breaker studs on the rear side of the breaker.

Each disconnect consists of four contact fingers (3) secured to each breaker stud (7) by screw (1) and retainers (6 and 8). A pair of springs (2) exert pressure on the contact fingers when engaging the stationary studs (4). Stop (5) and retainers ( 6 and 8 ) serve to maintain the proper alignment of the fingers when engaging the breaker studs.

Note: For instructions on mounting the breakers by means of disconnects, see'Dead Front Breakers" under Installation, Section III.

ADJUSTMENTS--When the proper amount of contact pressure is exerted against the stationary stud, the dimension from the top side of the upper washer to the bottom side of the lower washer on screw (1) should be approximately $3-1 / 32^{\prime \prime}$ using $5 / 8^{\prime \prime}$ springs, or $4-1 / 32^{\prime \prime}$ using $1-1 / 8^{\prime \prime}$ springs. (The corresponding dimension on Type AK-1-25 breakers should be approximately $3-29 / 32^{\prime \prime}$ ). To adjust for proper contact pressure, the adjusting nut of any particular contact finger should be backed off or advanced, as required.

The disconnects are checked for the proper amount of spring pressure before leaving the factory.


FIG. 33
DISCONNECT FOR MOUNTING TYPE AK-I-I5 BREAKER


FIG. 32
DISCONNECTS ENGAGING STATIONARY STUD


FIG. 34
DISCONNECT FOR MOUNTING TYPE AK-1-25 BREAKER

## 7. TERMINAL BOARD FIG. 35

The terminal board is attached to the right side of the breaker (looking from the front) by a bracket and two screws. It consists of a molded contact strip on which are arranged a number of binding screws for making connections with the various breaker devices which are externally controlled. It has a front cover to prevent dust and dirt from collecting on the terminal connections.

## REPLACEMENTS--Terminal Board

1. Remove cover of terminal board by removing two screws.
2. Disconnect wiring to Terminal board.
3. Remove two screws attaching terminal board to bracket and remove terminal board.
4. Install terminal board in reverse order.

Bracket

1. Remove terminal board (see above).
2. Remove two screws from bracket and remove bracket.
3. Install bracket in reverse order.


FIG. 35
TERMINAL BOARD WITH COVER REMOVED


1. Stationary contact
2. MOVABLE CONTACT
3. SHAFT
4. LINK
5. LINK
6. PIN
7. PIN
8. CRANK
9. SPRING
10. BRACKET
II. SCREW
11. SCREW
12. GLAMP
13. PIN
14. SCREW

(II)

SK. T-6490359

FIELD DISCHARGE CONTACTS
FIG. 36

## $\mathbf{X}$

## TYPE AKF-I FIELD SWITCH

## 1. GENERAL

A fieldswitch with two parallel, stationary and movable discharge contacts is used to control the shunt field circuits of synchronous generators and non-synchronous motors. It is similar to a bi-polar air circuit breaker with field discharge contacts placed in the center pole base. It may be used with or without electrical closing attachments.

The closing of the field discharge contacts connects a discharge resistor across the field of the generator or motor. This makes it possible to open the field switch without inducing a high voltage in the field.

## 2. FIELD DISCHARGE CONTACTS FIG. 36

The field discharge contacts close before the contacts of the field switch open and likewise open after the field switch closes. The closing of the field discharge contacts is accomplished by crank (8) which also constitutes a part of the toggle linkage used in closing the field discharge contacts. Cranks (8) is pivoted to pin (7) in bracket (10) and is connected to the main shaft (3) by means of insulating link (4) and by link (5) to movable contact (2). When the main shaft moves away from the pole base, the toggle linkage straightens and the field discharge contacts are closed by springs (9) attached to the lower part of crank (8) and bracket (10). The toggle linkage is so arranged that overlapping of the field discharge contacts and the contacts of the field switch takes place, thereby preventing an open circuited field.

Sufficient clearance between the upper stud and the opper part of the stationary contact support is provided so as to establish $1 / 2$ contact wipe of both field switch and field discharge contacts.

ADJUSTMENTS--To measure the contact wipe of the field switch contacts, first, remove the arc quencher (see 'Replacements' under Arc Quencher). Then use a scale to ascertain the distance the exterior contact point travels when the stationary contact is pushed back into the pole base as far as it will go, with the breaker in the open position. To adjust contact wipe, an eccentric bushing in insulating link (8), Fig. 10, is used to make the adjustment (see "Contact Wipe" under Contact Assembly).

REPLACEMENTS--Movable Contacts (2)

1. Remove arc quencher (see 'Replacements' under Arc Quencher).
2. Remove Operating Mechanism (see "Replacements' under Operating Mechanism).
3. Remove pin (14).
4. Remove two screws (11) and remove field discharge mechanism.
5. Remove two screws (12) and two clamps (13).
6. Remove movable contacts.
7. Replace new contacts in reverse order.
8. Adjust contact wipe and contact pressure (see above).
9. Replace Operating Mechanism.
10. Replace Arc Quencher.

## Stationary Contact (1)

1. Remove arc quencher (see "Replacements" under Arc Quencher).
2. Remove the upper stud cap by removing two screws (15).
3. Pry stationary contact (1) from the upper stud.
4. Replace the new stationary sontact in reverse order.
5. Adjust contact wipe and contact pressure (see above). It may benecessary to tap the new stationary contacts in place.

## XI

## RENEWALS

When ordering renewal parts, address the nearest Sales Office of the General Electric Company, specifying the quantity required and describing the parts by catalogue numbers as shown in Renewal Parts Bulletin, GEF-3506.

In the absence of a Renewal Parts Bulletin, the described parts should be identified by giving the complete nameplate data of the circuit breaker or accessory.

Renewal parts which are furnished may not be identical with the original parts, since improvements are made from time to time. Parts which are furnished will be interchangeable.

## XII

## CONNECTION DIAGRAMS

Figs. 37 and 38 show typical elementary and typical connection diagrams respectively, for the control of electrically-operated breakers.


FIG. 37
TYPIGAL ELEMENTARY OIAGRAM
adortional aux.
CONTAGTS WHEN REQ'D.


LIST of abareviations
a. tepmimal boaro located tof richt frowt view.
b. TEmiral boasd located top richt frowt view.

H. beLL ALLAB Of LOCKOUT dEVICE - Oferates mien breaner trips on overcurpent, omly. hano reSEI. $\mathrm{a}^{\circ}$ OR " $\mathrm{B}^{\circ}$ CONTACT.
K. SOLENOID CONTROL OEVICE (52X) CONSISTS OF AN OPERATIMG COIL MITM DOUBEL EINOIMG AND Short ing silich. a main contact aid sell-in contact. min comtact and sell-in comtact CLOSE MHEM FIRST SECTIO OF OPERATIMG COIL IS ENERGIZED OY CLOSING SNITO. TE CONTACTS ARE OPEMED MECHWYICALLY MFEM THE EREAKER CLOSIME SOLENOIO ON' COMPLETISS ITS SREOKE. SHOPTIMG SNITCH THEM OPENS IMSERTIMG COETIETE OFERATIKG COHL FOR CONTIELOUS EMERGIZAT
 CLOSIMG SNITOH REMUMS CLOSED.
M. SHINT TRIP IS21
J. undervoltage trip device isij tiac or instantanedus.
n. bateaker closixg solemoio coll (52)
P. Closimg switen on breaker (52)
S. REVERSE CURRENT TRIP DEVICE FOR D.C. (52)

## AK-I FIELD SWITCH CORRECTION

These instructions have been written to cover field switches in both 225 and 600 ampere frame size. This is an error, as only the 600 ampere frame size field switch is furnished.

## TYPES AK-I-15Y1 AND AK-I-25YI BREAKERS

Types AK-1-15Y1 and AK-1-25Y1 are intended for the protection of resistance welding machines. They trip instantaneously at higher current settings than breakers provided with the regular instantaneous overcurrent tripping device as shown in Figs. 23A to 23H. Types AK-1-15Y1 and AK-125 Y 1 differ from the regular breakers only in the provision that higher current settings may be obtained.

Standard calibration ranges for type AK-115Y1, Fig. 39, are as follows:

## a. 200 to 500 amperes

b. 400 to 1000 amperes
c. 600 to 1500 amperes

Standard calibration ranges for type AK-125Y1, Fig. 39, are as follows:
a. 600 to 150 amperes
b. 1400 to 4000 amperes
c. 2000 to $\mathbf{5 0 0 0}$ amperes

Other ranges can be provided within reasonable limits where the highest calibration settings will not exceed approximately $2-1 / 2$ times the lowest callibration setting.

These breakers are not given a continuous current rating since the duty imposed is intermittent and quite variable depending upon various types of welding to be done. The breakers are destgned to safely carry"during-weld amperes"or "during-weld KVA' at welding periods not to exceed the corresponding "duty cycle" as tabulated in Fig. 39. (Duty cycle is the percent of time that current flows in any one minute').


dUTY CYCLEIn percentace


FIG. 39

# POWER CHRCHT R ReAMERS $^{2}$ 

TYPQ ARETR-3 TO 10 Rlectricully Operciod

# LOW VOLTAGE Switchgear department Bencral (3) bectuc philadelphia, pa. 

GET-74624 Power Circuit Breakers Type AKF-1B-3 to 10


TYPICAL CONNECTION DIAGRAM

1. Stationary Contact
2. Kovable Contact
3. Breaker Contacts
4. Hink
5. Main Shaft
6. Link
7. Pin
8. Pin
9. Crank
10. Eccentric Pin
11. Spring
12. Bracket
13. Holding Screw and Nut
14. Screw
15. Screw
16. Clamp
17. Pin
18. Screw


Fig. IA Field Discharge contacts (AKF-IB-3 to 5),

## POWER CIRCUIT BREAKERS

## TYPE AKF-1B-3 TO 10

## electrically operated

The instructions contained herein are a supplement to instruction book GEI-74603 and are to be used in conjunction with GEI-74603.

The AKF breaker is a special type of AK breaker designed especially for use in controlling the shunt field circuits of synchronous generators and synchronous motors. These brealers are usually furnished without series overcurrent tripping devices and have a continuous rating of 600 amperes. The AKF is a two pole air circuit breaker with field discharge contacts placed in the center pole base.

The closing of the field discharge contacts connects a discharge resistor across the field of the generator or motor. This makes it possible to open the field switch without inducing a high voltage in the field.

The AKF breakers differ as follows:

1. The AKF-1B-4 is the same as the AKF-1B-3 except for the "Y" relay of the solenoid control system.
2. The AKF-1B-5 differs from the AKF-1B-3 in that it has a plastic front escutcheon and the same "Y" relay as the AKF-1B-4 breaker.
3. The AKF-1B-6 is the same as the AKF-1B-3 except that it has a different field discharge mechanism. It also has the same "Y" relay as the AKF-1B-4 breaker.
4. The AKF-1B-6 to 10 have same field discharge mechanism. (For a complete tabulation of nomenclature changes, see Page 3 of GEI-74603.)

> AKF-1B-3, AKF-1B-4 AND AKF-1B-5 FIELD DISCHARGE MECHANISM FIGURE 1A

When an AKF-1B-3, AKF-1B-4 or AKF-1B-5 field breaker is operated, the field discharge contacts close before the main contacts of the breaker open; the field discharge contacts open after the main breaker contacts close. This overlap prevents an open circuited field.

Sufficient clearance between the upper stud and the upper part of the stationary contact support is provided.so that a contact wipe of approximately one-half inch on both the field discharge and the main contacts may be established. The main shaft (5) of the breaker passes through a large hole in compound link (4) which is pivoted on pin (7) in bracket (12). Link (4) is coupled to crank (9) which is pivoted on pin (8)

These instructions do not purport to cover all details or variations in equipment nor to provide for every possible contingency to be met in connection witi installation, operation or maintenance. Should further information be desired or should particular problems arise which are not covered sufficiently io: the purchaser's purposes, the matter should be referred to the General Electric Company.
in bractret (i2) by means of an eccentric pin (10). Compound link ( 6 ) is coupled between crant (9) and discharge contact (2). Bracket (12) is securely fastened to the pole unit b. holding sciews and nuts (13) and is dowelled in place by dovel screw (19). (Caution: No attenit siould he made to move the supporting bracket (12). When the breaker trips, the main shaft (5) moves backward, array from the pole base. This allows the spring (11) to straighten the toggle linkage ( 6 and 9 ) thus forcing the discharge contact (2) closed.

During the closing operation of the breaker, the main shait (5) moves forward toward the pale base. This causes linds (1) which pivots on pin (7) to force crank (9) to contact (2) to open.

## ADJUSTREENTS

With the discharge contacts open there should be a gap of approximately one inch between the movable and stationary contacts. This gap may be adjusted by loosening tie nuts on either side of the eccentric pin (10) and rotating the pin until the desired gap is obtained. Be sure to tighten nuts securely after adjusting.

The overlap between the discharge contacts and the outside pole contacts should be between $1 / 8^{\prime \prime}$ and $1 / 4^{\prime \prime}$, measured at the point of contact.

Contact wipe on all contacts should be approximately $1 / 2$ ". See "Pole Unit Assembly" in GEI-74603 for method of obtaining desired wipe and pressure on outer pole contacts.

## REPLACERENTS

Movable Contacts (2)

1. Remove arc quencher (see "Replacernents" under "Arc Quencher", page 6 of GEI-74603).
2. Remove operating mechanism (see "Replacements" under "Operating Mechanism", Page 11 of GEI-74603).
3. Remove pin (17).
4. Remove two screvs (13) and remove field discharge mechanism.
5. Remove two screws (15) and two clamps (16).
6. Remove movable contacts.
7. Replace new contacts in reverse order.
8. Adjust contact wipe and contact pressure (see above).
9. Replace operating mechanism.
10. Replace arc quencher.

Stationary Contacts (1)

1. Remove arc quencher (see "Replacements" under "Arc Quencher", Page 6 of 23I-74003.
2. Eemove the upper stud cap by removing two screws (18).
3. Pry staitionary contact (1) from the upper stud.
4. Replace the new stationary contact in reverse order.
E. Adjust contact wipe and contact pressure (see above) to thp the new stationary contacts in place.

## AMET-1E-6 TO 10 FIELD DISCLARGS MECEANESM FIGURE 1B

The main shaft ( 9 ) of the breaker passe; througin a large hole in arm (7), which is pivoted on pia (11) in bracket (13). When the brearer is closed, the main sinaft (9) moves iorwarci causing arm (7) to pivot about pin (12), thereby causing link (16) to move away from the brearer base. This moition causes link (14) to move downvard pivoting to bou eccentric (17). The downward motion of ink (14) is transmitted through ink (12) to coupling (10) and link (6), thus causing the linkage to collapse. The field discharge contacts (27), which pivot about pin (21), open when the coupling (10) and link (6) collapse.

When the breaker is opened, the mechanism motion described above is reversed, so that the field discharge contacts close.

The contacts of the discharge mechanism are set so that one contact makes before the other. This is done to minimize wearing of the contacts due to arcing.

## ADJUSTMENTS

With the discharge contacts open, the gap between the movable and stationary discharge contacts should.be between $1-1 / 8^{\text {n" }}$ and $1-3 / 8^{\text {I }}$, with the free movement tending to reduce the gap. This adjustment is obtained by loosening the nuts on either side of the eccentric (17) and rotating pin until the proper opening exists. Tighten the nuts securely after adjusting.

The extended stationary contact and the standard stationary contact should be staggered between $1 / 16^{\prime \prime}$ and $1 / 8^{\prime \prime}$. The extended contact finger on the center pole should close between $1 / 4^{\prime \prime}$ and $3 / 8^{\prime \prime}$ before the contacts on the outer poles break.

Both the breaker contacts and the discharge contacts should be adjusted to provide $1 / 16^{1 "}$ overtravel when they are fully wiped in. Contact wipe should be approximately $1 / 2^{4}$. However, this dimension is not critical, and wipe in excess of this amount is not significant. For method of adjusting wipe see "Pole Unit Assembly", Page 8 of GEI-74603).

## IEPLACZMENTS

## Novable Contacts (2)

1. Femove arc quencher (see "Replacement" under "Arc Quencher", Page 6 of GEI-74603).
2. Fiemove operating mechanism (see "Replacement" under "Operating Wechanism", Page 11 of GEI-74603).
3. Finncve screws which attach flexible lead (19) to the movable contact arms.
4. Fenove clanip (20) and two screws (18). The field discharge mechanism is now tree to be removed.
5. Temive pin (22) and movable contacts (2).
6. Replace contacts and re-assemble field discharge mechanism in reverse order.
7. Fieplace arc quenchers.

## Stationary Contacts (i)

之. Remove movable contacts as described above.
\%. Zamove upper win ( 25 ) by removing three screws (26).
*. Remove upper stud cap (5) by removing screws (4).
4. Remove pin (3) ansi stationary contacts (1).
5. Ficplace paris in reverse order.

NOTE: The stationary contacts on the outside pole units of the AKF-1B-6 to 10 are sining to the stationary contacts of the field discharge mechanism. When replacing the stationary contacts on the outside pole units, remove the movable contact assembly as described in GEM-74603 and then remove the stationary contacts as described above.

1. Contact Finger (Sta.)
2. Contact Arm (Hov.)
3. Pin (Contact Pivot)
4. Screw FL. PF. HD.
5. Upper Stud Cap
6. Coupling
7. Am
8. Buffer
9. Rain Shaft
10. Link
11. Pin
12. Kink
13. Bracket
14. Link
15. Pin
16. Link
17. Eccentric
18. .Screw RD. PH. ED.
19. Flexible Lead
20. Clamp
21. Pin (isov. Cont. Pivot)
22. Pin (Insul.To.Mov.Cont.)
23. Screw RD. PH. HD.
24. Spring (Stat. Cont.)
25. Upper Stud
26. Screw RD. Phi. fD.


Fig. IB Field Discharge Contacts (AXF-IB-6 to J0)


Types AKF-1B-3, AKF-1B-4, AKF-1B-5, and $A K F-18-6$, Electrically Operated



Philadelphia, pa.


Fig. IA Field Discharge Contacts

## TYPES AKF-1B-3, AKF-1B-4, AKF-1B-5 AND AKF-1B-6

## ELECTRICALLY OPERATED

The instructions contained herein are a supplement to instruction book GEH-1807 and are to be used in conjunction with GEH-1807.

The AKF breaker is a special type of AK breaker designed especially for use in controlling the shunt field circuits of synchronous generators and synchronous motors. These breakers are usually furnished without series overcurrent tripping devices and have a continuous rating of 600 amperes. The AKF is a two pole air circuit breaker with field discharge contacts placed in the center pole base.

The closing of the field discharge contacts connects a discharge resistor across the field of the generator or motor. This makes it possible to open the field switch without inducing a high voltage in the field.

- The AKF breakers differ as follows:

1. The AKF-1B-4 is the same as the AKF-1B-3 except for the "Y" relay of the solenoid control system.
2. The AKF-1B-5 differs from the AKF-1B-3 in that it has a plastic front escutcheon and the same "Y" relay as the AKF-1B-4 breaker.
3. The AKF.-1B-6 is the same as the AKF-1B-3 except that it has a different field discharge mechanism. It also has the same " Y " relay as the AKF-1B-4 breaker.

## AKF-1B-3, AKF-1B-4 AND AKF-1B-5 FIELD DISCHARGE MECHANISM FIGURE 1A

When an AKF-1B-3, AKF-1B-4 or AKF-1B-5 field breaker is operated, the field discharge contacts close before the main contacts of the breaker open; the field discharge contacts open after the main breaker contacts close. This overlap prevents an open circuited field.

Sufficient clearance between the upper stud and the upper part of the stationary contact support is provided so that a contact wipe of approximately one-half inch on both the field discharge and the main contacts may be established. The main shaft (5) of the breaker passes through a large hole in compound link (4) which is pivoted on pin (7) in bracket (12). Link (4) is coupled to crank (9) which is pivoted

These instructions do not purport to cover all details or variations in equipment nor to provide for every possible contingency to be met in connection with installation, operation or maintenance. Should further information be desired or should particular problems arise which are not covered sufficiently for the purchaser's purposes, the matter should be referred to the General Electric Com ${ }^{-}$ pany.
c. . in (8) in bracket (12) by means of an eccentric pin (10). Compound link (6) is coupled between crank (9) and discharge contact (2). Bracket (12) is securely fastened to the pole unit by holding screws and nuts (13) and is dowelled in place by dowel screw (14). (Caution: No attempt should be made to move the supporting bracket (12) ). When the breaker trips, the main shaft (5) moves backward, away from the pole base. This allows the spring (11) to straighten the toggle linkage ( 6 and 9 ) thus forcing the discharge contact (2) closed.

During the closing operation of the breaker, the main shaft (5) moves forward toward the pole base. This causes link (4) which pivots on pin (7) to force crank (9) to pivot about pin (8) causing the toggle linkage ( 6 and 9 ) to collapse allowing the discharge contact (2) to open.

## ADJUSTMENTS

With the discharge contacts open there should be a gap of approximately one inch between the movable and stationary contacts. This gap may be adjusted by loosening the nuts on either side of the eccentric pin (10) and rotating the pin until the desired gap is obtained. Be sure to tighten nuts securely after adjusting.

The overlap between the discharge contacts and the outside pole contacts should be between $1 / 8^{\prime \prime}$ and $1 / 4^{\prime \prime}$, measured at the point of contact.

Contact wipe on all contacts should be approximately $1 / 2$ ". See "Pole Unit Apembly" in GEH-1807 for method of obtaining desired wipe on outer pole contacts.
$\mathrm{R}_{\therefore} \mathrm{PL} \mathrm{LACEMENTS}$
Movable Contacts (2)

1. Remove arc quencher (see "Replacements" under "Arc Quencher", GEH-1807).
2. Remove operating mechanism (see "Replacements" under "Operating Mechanism ${ }^{11}$, GEH-1807).
3. Memove pin (17).
4. Remove two screws (13) and remove field discharge mechanism.
5. Remove two screws (15) and two clamps (16).
6. Remove movable contacts.
7. Replace new contacts in reverse order.
8. Adjust contact wipe and contact pressure (see above).
9. Replace operating mechanism.
10. Replace arc quencher.

Stationary Contacts (1)

1. Remove arc quencher (see "Replacements" under "Arc Quencher").
2. Remove the upper stud cap by removing two screws (18).
3. Pry stationary contact (1) from the upper stud.
4. Replace the new stationary contact in reverse order.
5. Adjust contact wipe and contact pressure (see above). It may be necessary to tap the new stationary contacts in place.

## AKF-1B-6 FIELD DISCHARGE MECHANSM FIGURE 1B

The main shaft (9) of the breaker passes through a large hole in arm (7), which is pivoted on pin (11) in bracket (13). When the breaker is closed, the main shaft (9) moves forward causing arm (7) to pivot about pin (11), thereby causing link (16) to move away from the breaker base. This motion causes link (14) to move downward pivoting about eccentric (17). The downward motion of link (14) is transmitted through link (12) to coupling (10) and link (6), thus causing the linkage to collapse. The field discharge contacts (27), which pivot about pin (21), open when the coupling (10) and link (6) collapse.

When the breaker is opened, the mechanism motion described above is reversed, so that the field discharge contacts close.

The contacts of the discharge mechanism are set so that one contact makes before the other. This is done to minimize wearing of the contacts due to arcing.

## ADJUSTMENTS

With the discharge contacts open, the gap between the movable and stationary discharge contacts should be between $1-1 / 8^{\prime \prime}$ and $1-3 / 8^{\prime \prime}$, with the free movement tending to reduce the gap. This adjustment is obtained by loosening the nuts on either side of the eccentric (17) and rotating the pin until the proper opening exists. Tighten the nuts securely after adjusting.

The extended stationary contact and the standard stationary contact should be staggered between $1 / 16^{\prime \prime}$ and $1 / 8^{\prime \prime}$. The extended contact finger on the center pole should close between $1 / 4^{\prime \prime}$ and $3 / 8^{\prime \prime}$ before the contacts on the outer poles break.

Both the breaker contacts and the discharge contacts should be adjusted to provide $1 / 16^{\prime \prime}$ overtravel when they are fully wiped in. Contact wipe should be approximately $1 / 2^{\prime \prime}$. However, this dimension is not critical, and wipe in excess of this amount.is not significant. For method of adjusting wipe see "Pole Unit Assembly" in GEH-1807.
REPLACEMENTS

## Movable Contacts (2)

1. Remove arc quencher (see "Replacements" under "Arc Quencher" in GEH-1807).
2. Remove operating mechanism (see "Replacements" under "Operating Mechanism" in GEH-1807).
3. Remove screws which attach flexible lead (19) to the movable contact arms.
4. Remove clamp (20) and two screws (18). The field discharge mechanism is now free to be removed.
5. Remove pin (22) and movable contacts (2).
6. Replace contacts and re-assemble field discharge mechanism in reverse order.
7. Adjust contact wipe and pressure (see above).
8. Replace arc quenchers.

## Air Circuit Breakers Type AKF

## Stationary Contacts (1)

1. Remove movable contacts as described above.
2. Remove upper stud (25) by removing three screws (26).
3. Remove upper stud cap (5) by removing screws (4).
4. Remove pin (3) and stationary contacts (1).
5. Replace parts in reverse order.

NOTE: The stationary contacts on the outside pole units of the AKF-1B-6 are similar to the stationary contacts of the field discharge mechanism. When replacing the stationary contacts on the outside pole units, remove the movable contact assembly as described in GEH-1807 and then remove the stationary contacts as described above.

1. Contact Finger (Sta.)
2. Contact Arm (Mov.)
3. Pin (Contact Pivot)
4. Screw Fl. PH. HD.
5. Upper Stud Cap
6. Coupling
7. Arm
8. Ruffer
9. Nain Shaft
10. Link
11. Pin
12. Link
13. Bracket:
14. Link
15. Pin
16. Link
17. Eccentric
18. Screw RD. PH. HD.
19. Flexible Lead
20. Clamp
21. Pin (Mov.Cont. Pivot)
22. Pin (Insul. To Mov.Cont.)
23. Screw RD: - PH. HD.
24. Spring (Stat. Cont.)
25. Upper Stud
26. Screw RD. PH. HD.


Fig. IB Field Discharge Contacts

| Abilonc，Toxas． .442 Codar St． |  |
| :---: | :---: |
| Akron 1s；Ohio．．．．．．．．．．．．．．．．．．．．．．．．Sox 5278 West Morkel S？ 8 Colvin Ave |  |
| Albuquerque，N．Mox．．．．．． 323 Third SI．，S．W． |  |
| Aloxandria，La．．．．．．．．．．．．．．ilis2 Hamilton St． |  |
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|  |  |
| Allama 2，Ca．．．． 1860 Peachree Rd．，N．W． |  |
|  | 152 St |
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| Eugone，Ora．．．．P．O．Box 352， 1170 Peorl St． |  |
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## RENEMAA PARTS

## TYPES AK-1-15 AND AK-1-25 <br> POWER CIRCUIT BREAKERS AND TYPE AKF-1B FIELD BREAKERS



Fig. 1. Type AK-1-25-8 air circuit breaker, manually operated

NOTE: All reference to "right" and "left" designate the location of the part when facing the operating mechanism end of the breaker.

## ORDERING INSTRUCTIONS

1. Always specify the complete nameplate data of the breaker.
2. Specify the quantity, catalog number (if listed), reference number (if listed), description, and this bulletin number.
3. CAUTION: When local facilities for breaker recalibration are not available, the breaker should be forwarded to the nearest G-E Service Shop, or to the General Electric Company, 6901 Elmwood Ave., Philadelphia 42, Pa.
4. Standard hardware, such as screws, bolts, nuts, washers, etc., is not listed in this bulletin. Such items should be purchased locally.
5. For prices, refer to the nearest office of the General Electric Company.


Fig. 2. Type AK-1-15 air circuit breaker, electrically operated. (shunt trip device, terminal board, and right pole overcurrent trip device and arc quencher removed)


Fig. 4. Manual operating handle and escutcheon used on breakers up to and including -6 (ref. 52)

Fig. 3. Operating mechanism linkage for Type AK-1-15 air circuit breaker (right side frame removed)


Fig. 5. Manual operating handle and escutcheon used on breakers from -7 to -9 (ref. 53)


[^16]+ Not shown.
§ For manual breaker without auxiliary switch.
* For manual breaker with auxiliary switch or for electric breaker.
$\ddagger$ Original breaker had no suffix letter or numeral.
$\emptyset$ When ordering specify complete nameplate data of device being replaced. The only part furnished for the EC-2 device is the case (Cat. No. 242C645P1).

$\ddagger$ Original breaker model has no suffix letter or numeral.


## + Not shown

* Recommended for stuck for normal maintenance.

NOTE: When replacing complete front escutcheon assembly or escutcheon plate, ordering information must include complete nameplate reading of breaker involved and must also indicate whether manually or electrically operated to enable factory to sele:t proper superseding new design assembly.

| Fig. <br> No. | Rer. No. | Number Required for 3-pole Breaker |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | For Type AK-1-15 |  |  |  |  |  |  |  |  |  |  |  | For Type AK-1-25 |  |  |  |  |  |  |  |  |  |  |  |
|  |  | F | A | -1 | -2 | -3 | -4 | -5 | -6 | -7 | -8 | -9 | -10 | $t$ | A | -1 | -2 | -3 | -4 | -5 | -6 | -7 | . 8 | 9 | 10 |
|  | +73 | 1 | - | 1 | - | - | - | - | $\rightarrow$ | - | - | - | - | 1 | - | 1 | - | - | - | - | - | - | - | - | - |
|  | +74 | 2 | - | 2 | - | - | - | - | - | - | - | - | - | 2 | - | 2 | - | - | - | - | - | - | - | - |  |
|  | -75 | 1 | - | 1 | - | - | - | - | - | - | - | - | - | 1 | - | 1 | - | - | - | - | - | - | - | - | - |
|  | +76 | 1 | - | 1 | - | - | - | - | - | - | - | - | - | 1 | - | 1 | - | - | - | - | - | - | - | - | - |
|  | +77 | 1 | - | 1 | - | - | - | - | - | - | - | - | - | 1 | - | 1 | - | - | - | - | - | - | - | - | - |
|  | +78 | 1 | - | 1 | - | - | - | - | - | - | - | - | - | 1 | - | 1 | - | - | - | - | - | - | - | - | - |
|  | +79 | 1 | - | 1 | - | - | - | - | - | - | - | - | - | 1 | - | 1 | - | - | - | - | - | - | - | - | - |
|  | +80 | 1 | - | 1 | - | - | - | - | - | - | - | - | - | 1 |  | 1 | - | - | - | - | - | - | - | - | - |
| 6 | 81 | 1 | - | 1 | - | - | - | - | - | - | - | - | - | 1 | - | 1 | - | - | - | - | - | - | - | - |  |
| 6, 7 | *82 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1. | 1 |
| 7 | 83 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 |
| 6,7 | 84 | 1 | - | 1 | - | - | - | - | - | - | - | - | - | 1 | - | 1 | - | - | - |  | - | - | - | - | - |
| 6,7 | 84 | - | 1 | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - | 1 | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 7 | 85 | - | 1 | - | 1 | 1 | - | - | - | - | - | - | - | 1 | - | 1 | 1 | - | - | - | - | , | - | - | $\bar{\square}$ |
| 7 | 85 | - | - | - | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | - | - | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 7 | *86 | - | 1 | - | 1 | 1 | - | - | - | - | - | - | - | - | 1 | - | 1 | 1 | - | - | - | - | - | - | - |
| 7 | * 86 | - | - | - | - | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | - | - | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 7 | 87 | - | 1 | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - | 1 | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 7 | *88 | - | 1 | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - | 1 | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 7 | *89 | - | 1 | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - | 1 | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 14 | 90 | - | 1 |  | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - | 1 | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 8 | 91 |  | 1 | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | - | 1 | - | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |


| Catalog Number | Description |
| :---: | :---: |
| 6403076PI | Main moving contact |
| 6404345P1 | Seal-in stationary contact |
| 6444848 | Seal-in moving contact pin |
| 6444849 P 1 | Seal-in moving contact pin |
| 6302797 | Main contact springe - C |
| 6302791 | Main contact spring, D-C |
| 6403351 | Beam return spring, A-C |
| 6302795 | Beam return spring, D-C |
| $\begin{array}{r} \mathrm{CR}-1070- \\ \mathrm{C} 122-\mathrm{A} 3 \end{array}$ | Switchette |
| (See page 7) | Closing solenoid coil |
| 6372797P1 | Armature guide |
| 6403836G1 | Armature and link assembly |
| 372A354G1 | Armature and link assembly |
| (See pare 7) | "Y"' relay complete |
| (See page 7) | "Y" relay complete |
| (See page 7) | Coll |
| (See page 7) | Coil |
| (See page 7) | "X' relay complete |
| (See paye 7) | Coil |
| 6960045G11 | Contact kit (complete set) |
| 9921661 P 4 | Prop switch |
| 377A892G1 | Maintenance operating handle |

[^17]

Fig. 6. Solenoid operating mechanism with obsolete control device


Fig. 7. Solenoid operating mechanism with modern X-Y relay control unit

Fig. 8. Maintenance operating handle (ref. 91)


4 Used on-10 only.

| Catalog Number |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Volts | Cycles | "X" Relay for: <br> AK-1-15, A-2 to -9 <br> AK-1-25, A-2 to -9 |  | § "Y" Relay for: <br> AK-1-15, -4 to -9 <br> AK-1-25, -4 to -9 |  | $\begin{gathered} " Y \text { "'Relay } \\ \text { for } \\ \text { AK }-1-15-10 \\ A K-1-25-10 \end{gathered}$ |
|  |  | Relay Complete (Ref, 87) | Coil only <br> (Ref. 88) | Relay Complete (Ref. 85) | Coil only (Rel. 86) | Relay Complete (Ref. 85) |
| $\begin{aligned} & 125 \\ & 250 \end{aligned}$ | $\} \mathrm{DC}\{$ | $\begin{aligned} & \text { CR-2810-A14AC2 } \\ & \text { CR-2810-A14AC3 } \end{aligned}$ | $\begin{aligned} & \text { 22D135G2 } \\ & \text { 22D135G3 } \end{aligned}$ | $\begin{aligned} & \text { 176L162G10 } \\ & \text { 176L162G11 } \end{aligned}$ | $\begin{aligned} & 366 \mathrm{~A} 716 \mathrm{G} 4 \\ & 366 \mathrm{~A} 716 \mathrm{G} 5 \end{aligned}$ | $\begin{aligned} & \text { 295B444P3 } \\ & \text { 295B44P4 } \end{aligned}$ |
| $\begin{aligned} & 115 \\ & 208 \\ & 230 \end{aligned}$ | $\} 25\{$ | CR-2810-A14AC17 CR-2810-A14AC18 CR-2810-A14AC18 | $\begin{aligned} & \text { 22D135G17 } \\ & \text { 22D135G18 } \\ & 22 \mathrm{D} 135 \mathrm{G} 18 \end{aligned}$ | $\begin{aligned} & \text { 176L162G20 } \\ & \text { 176L162G26 } \\ & 176 \mathrm{~L} 162 \mathrm{G} 21 \end{aligned}$ | 366A716G2 366A716G6 366A716G3 | $\begin{aligned} & \text { 295B444P7 } \\ & \text { 29513444P10 } \\ & \text { 295B444P13 } \end{aligned}$ |
| $\begin{aligned} & 115 \\ & 208 \\ & 230 \\ & 460 \end{aligned}$ | $\} 50\{$ | $\begin{aligned} & \text { CR-2810-A14AC7 } \\ & \text { CR-2810-A14AC } \\ & \text { CR -2810-A14AC8 } \\ & \text { CR -2810-A14AC9 } \end{aligned}$ | $\begin{aligned} & \text { 22D1 35G7 } \\ & \text { 22D135G8 } \\ & \text { 22D135G8 } \\ & \text { 22D135G9 } \end{aligned}$ | 176 L 162 G 16 176 L 162 G 25 176 L 162 G 17 176 L 162 G 18 | $\begin{aligned} & \text { 366A716G1 } \\ & 366 \mathrm{~A} 716 \mathrm{G} 2 \\ & 366 \mathrm{~A} 716 \mathrm{G} 2 \\ & 366 \mathrm{~A} 716 \mathrm{G} 3 \end{aligned}$ | 295B444P5 <br> 295B444P5 <br> 295B444P11 <br> 295B444P14 |
| $\begin{aligned} & 115 \\ & 208 \\ & 230 \\ & 460 \end{aligned}$ | $\} 60\{$ | $\begin{aligned} & \mathrm{CR}-2810-\mathrm{A} 14 \mathrm{AC} 2 \\ & \mathrm{CR}-2810-\mathrm{A} 14 \mathrm{AC} 3 \\ & \mathrm{CR}-2810-\mathrm{A} 14 \mathrm{AC} 3 \\ & \mathrm{CR}-2810-\mathrm{A} 14 \mathrm{AC} 4 \end{aligned}$ | $\begin{aligned} & \text { 22D1 35G2 } \\ & \text { 22D1 35G3 } \\ & \text { 22D1 35G3 } \\ & \text { 22D1 35G4 } \end{aligned}$ | $\begin{aligned} & \text { 176L162G12 } \\ & \text { 176L162G24 } \\ & \text { 176L162G13 } \\ & \text { 176L162G14 } \end{aligned}$ | $\begin{aligned} & \text { 366A716G1 } \\ & \text { 366A } 716 \mathrm{G} 2 \\ & \text { 366A } 716 \mathrm{G} 2 \\ & \text { 366A716G3 } \end{aligned}$ | 295B444P5 <br> 295B444P8 <br> 295B444P11 <br> 295B444P14 |

§ Coils for "Y'" relays on $A K-1-15-2,-3$ and $A K-1-25-2,-3$ are no longer available. If necessary to replace this coil the complete 'Y'" relay as listed for AK $-1-15-4$ to -9 or AK -1-25-4 to -9 should be ordered.


Fig. 9. Auxiliary switch 2 stages (ref. 92)

Fig. 11. Secondary disconnect. Stationary, left; moving, right (ref. 97, 98)

| Ref. No. | Catalog <br> Number | Description |
| :---: | :---: | :---: |
| 92 | 6578110G2 | Auxiliary switch (2 stages, 4 contacts) |
| - $\ddagger 92 \mathrm{~A}$ | $6578110 \mathrm{G5}$ | Auxiliary switch (5 stages, 10 contacts) |
| 93 | $\dagger 845 \mathrm{C} 276 \mathrm{G} 1$ | Primary disconnect (AK-1-15 only) |
| 94 95 | $\dagger 845 \mathrm{C} 276 \mathrm{G} 3$ | Primary disconnect (AK-1-25 only) |
| 95 | \% 412 A 222 $\$ 453 \mathrm{~A} 100 \mathrm{P} 2$ | Spring |
| 97 | -6523600G2 | Secondary |
| 98 | -386A110G2 | Secondary disconnect, stationary, for drawout breaker |
| 99 +100 | (See page 9) | Shunt trip device |
| *100 | (See page 9) | Coil |
| 101 | 365A325 | Spring |
| 102 | (See page 9) | Undervoltage device |
| *103 | (See page 9) | Coil |
| 104 | 6172594 | Spring |
| 105 | 6444315 P 1 | Gasket (time delay device) |
| 106 | 6403126 P 1 | Cvlinder (time delay device) |
| 107 | 6403128 G 1 | Plunger and link (time delay device) |

[^18]

Fig. 12. Shunt trip device (ref. 99)

| Rating |  | Catalog Number |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Volts | Cycles | Shunt Trip Device |  | Undervoltage Device |  |
|  |  | Device less Coil (Ref. 99) | Coil Only <br> (Ref. 100) | Device less Coil (Ref. 102) | Coil Only <br> (Ref. 103) |
| $\begin{array}{r} 12 \\ 24 \\ 48 \\ 125 \\ 155 \\ 250 \end{array}$ | D-C | 6319456G1 | 6275081G25 <br> 6275081G55 <br> 6275081G28 <br> 6275081G29 <br> 6275081G30 | $\left\{\begin{array}{c}6319456 \mathrm{G} 9 \text { (inst.) } \\ \text {-or - } \\ 6319456 \mathrm{G} 10 \text { (time) }\end{array}\right.$ | 6275081G15 <br> 6275081G9 <br> 6275081G18 <br> 6275081G57 <br> 6275081G19 |
| $\begin{aligned} & 115 \\ & 208 \\ & 230 \\ & 460 \\ & 575 \end{aligned}$ | 25 |  | $\begin{aligned} & 6275081 \mathrm{G} 26 \\ & 6275081 \mathrm{G} 29 \\ & 6275081 \mathrm{G} 29 \\ & 6275081 \mathrm{G} 7 \\ & 6275081 \mathrm{G} 5 \end{aligned}$ | $\cdots$ | 6275081 G 12 <br> 6275081G10 <br> 6275081G10 <br> $627508 \mathrm{iG17}$ <br> 6275081 G 21 |
| $\begin{aligned} & 115 \\ & 208 \\ & 230 \\ & 460 \\ & 575 \end{aligned}$ | 50 |  | 6275081G24 <br> 6275081G26 <br> 6275081G26 <br> 6275081G4 <br> 6275081G29 | $\left\{\begin{array}{l}6319456 \mathrm{G} 7 \text { (inst.) } \\ - \text { or - } \\ 6319456 \mathrm{G} 8 \text { (time) }\end{array}\right.$ | 6275081G4 <br> 6275081 G 12 <br> 6275081 G 12 <br> 6275081G3 <br> 6275081G8 |
| $\begin{aligned} & 115 \\ & 208 \\ & 230 \\ & 460 \\ & 575 \end{aligned}$ | 60 |  | 6275081G25 <br> 6275081G26 <br> 6275081G26 <br> 6275081 G 27 <br> 6275081G7 |  | 6275081 G2 6 6275081 G2 7 6275081 G 7 6275081G31 6275081 G20 |



Fig. 14. Material required to convert manual breaker to electric operation with X-Y control scheme


Fig. 15. Material required to convert electrically operated breaker from obsolete control device scheme to modern X-Y control scheme (two mounting brackets not shown)
*Conversion Kits for Electric Operation

| Ref. No. | Catalog <br> Number | Conversion |  |
| :---: | :---: | :---: | :---: |
|  |  | From - | To- |
| STATIONARY BREAKERS |  |  |  |
| 108A | 176L137G1 | $\dagger$ Manual operation | New style electric operation (X-Y scheme), with § closing switch |
| 108B | 176L137G5 | $\dagger$ Manual operation | New style electric operation (X-Y scheme), without closing switch |
| 109A | 176L137G2 | TOld style electric operation (using 'control device") | New style electric operation (X-Y scheme), with § closing switch |
| 109B | 1761.137G6 | TOld style electric operation (using "control device ${ }^{*}$ ) | New style electric operation (X-Y scheme), without closing switch |
| DRAWOUT BREAKERS |  |  |  |
| 108 C | 176L137G3 | $\dagger$ Manual operation | New style electric operation (X-Y scheme), with § closing switch |
| 108D | 176L137G7 | Manual operation | New style electric operation (X-Y scheme), without closing switch |
| 109C | 176L137G4 | ©Old style electric operation (using "control device") | New style electric operation (X-Y scheme), with § closing switch |
| 1091) | 176113768 | rold style electric operation (using "control device") | New style electric operation (X-Y scheme), without closing switch |

*Includes all necessary parts to convert breaker. NOTE: When ordering, be sure to include complete nameplate reading of breaker, and specify voltage and frequency to be used.
$\dagger$ All AK - 1-15 and AK - 1-25 breakers through -10.
fAK-1-15, AK-1-15-1, AK-1-25, and AK-1-25-1 only. Later breakers have new style parts.
\$Closing switch mounts on breaker front escutcheon.


Fig. 16. Field discharge (middle) pole of type AKF-1B field breaker

| Ref. No. | TYPES AKF-1B TO AKF-1B-5 |  |  |  | TYPES AKF-1B-6 TO AKF-1B-10 |  |  |  | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Center Pole |  | Each Outside Pole |  | Center Pole |  | Each Outside Pole |  |  |
|  | Catalog Number | No. <br> Req. | Catalog <br> Number | No. <br> Req. | Catalog <br> Number | No. <br> Req. | Catalog <br> Number | No. <br> Req. |  |
| 110 | 6357059 P 3 | 1 | 6357059 P 3 | 1 | 238C167P1 | 1 | 238C167P1 | 1 | Pole unit base |
| 111 | 6372777 G 2 | 2 | 6372777 G 2 | 4 | $\left\{\begin{array}{l} 372 \mathrm{~A} 363 \mathrm{G} 2\} \\ 372 \mathrm{~A} 363 \mathrm{G} 3 \end{array}\right\}$ | 1 | 372A363G2 | 4 | Stationary contact |
| 112 | 6317995G3 | 1 | 6317995G2 | 1 | 6317995G5 | 1 | 6317995G6 | 1 | Moving contact assembly |
| $\dagger 113$ | -..... | - | 6317719 P 4 | 1 | ----- | - | 6317719P4 | 2 | Insulating link |
| 114 | 6319474G1 | 1 | …-. | 1 | $695 \mathrm{C} 138 \mathrm{G1}$ | 1 | ----- | 1 | Discharge switch assembly |
| 115 | 6403109 G 4 | 1 | 6403109 G 4 | 1 | $372 \mathrm{~A} 359 \mathrm{G} 2$ | 1 | 372A 359 G 2 365 A 215 | 1 | Upper stud Stationary contact spring |
| 116 | 6403324 | 2 | 6372917 6248887 P 2 | 4 | $\begin{aligned} & 365 \mathrm{~A} 349 \\ & 372 \mathrm{~A} 367 \mathrm{P} 2 \end{aligned}$ | 2 2 | $365 A 315$ 372 A 367 P 2 | 4 | Stationary contact spring Spring pin |
| 117 118 | 6248887P2 393 A 57 P 1 | 2 | 6248887 P 2 393 A 57 P 1 | 4 1 | $372 A 367 P 2$ $393 A 557 P 1$ | 2 | 372 A 367 P 2 393 A 57 P 1 | 4 | Spring pin <br> Upper stud cap |
| 118 | $\begin{aligned} & 393 \mathrm{~A} 557 \mathrm{P} 1 \\ & 6403321 \end{aligned}$ | 1 | 393A557P1 | 1 | 393A557P1 (None used) | 1 | (None used) | 1 | Discharge switch spring |
| 120 | 6403135 G 2 | 1 | 6403135 G 2 | 1 | 6403135 G 2 | 1 | 6403135 G 2 | 1 | Lower stud |

[^19]The following tools are recommended for proper maintenance of the AK-1-15 and AK-1-25 Air Circuit Breakers. NOTE: Obtain from local hardware firm; do not order on General Electric Co.

SCREW "Drivers
Shurt heavy, slotted screw Standard, slotted screw long thin, slotted screw Phillips, No. 1 Phillips, No. 2 ( 8 in. shatt) Phillips, No. 3

## PLIERS

Gas, 8 in.
Pointed nose, side cutting., 6 ir.
Waldes Truare, No. 2, straight
Waldes Truare, No. 2, 90 degree

## END WRENCHES

Adjustable, 8 in.
1/4 in. - $5 / 16$ in., open ends 5/16 in. $-11 / 32$ in., open ends $3 / 8 \mathrm{in}$. $-7 / 16 \mathrm{in}$., open ends $1 / 2 \mathrm{in}$. $-9 / 16 \mathrm{in}$, open ends $5 / 8 \mathrm{in}$. $-3 / 4 \mathrm{in}$., open ends

SOCKET WRENCHES (1/2 IN. DRIVE)
Ratchet handle
10 in . extension bar
6 in . extension bar
7/16 in. socket
9/16 in. socket
5/8 in. socket
3/4 in. socket
13/16 in. socket
15/16 in. sucket

## ALLEN HEAD WRENCHES

1/16 in., for No. 6 screw
5/64 in., for No. 8 screw
3/32 in., for No. 10 screw
$1 / 8$ in., for $1 / 4 \mathrm{in}$. serew
$5 / 16 \mathrm{in}$., for $3 / 8 \mathrm{in}$. screw
MISCELLANEOUS
B.ll peen hammer, 8 ounce
"Spintite" wrench, $3 / 8 \mathrm{in}$.
Open box wrench, 6 point, $5 / 8 \mathrm{in}$.

#  GENERAL ELECTRIC 

philadelphia, pa.

## Power Circult Breakers

Types AK-2/2A-15 AK-2/3/2A/3A-25 AKU-2/3/2A/3A-25

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# POWER CIRCUIT BREAKERS <br> Types AK-2-15 and AK-2/3-25 

## INTRODLCTION

The instructions contained herein provide information for performing maintenance procedures and for replacing AK-2/3-15/25 breaker components and accessories. For information regarding
the receiving, handling, storage and installation of these breakers, refer to GEK-7302 furnished with all AK breakers.

## ELECTRICAL OPERATION Figure 1

The electrically operated breaker closes whenever the closing solenoid coil is energized. This causes an upward movement of the solenoid armature, which initiates the mechanical closing action. The closing signal may be given either by a remote switch or relay, or by a closing button in the front escutcheon if the breaker is so equipped. Either action (refer to the elementary of the wiring diagram) energizes the coil of the $X$ relay through the bb contacts of cutoff switch $G$ and the normally closed contacts of the Y relay. When the $X$ relay or contactor is energized, it closes its contacts. One of these (X1-2) seals in the $X$ coil. The other three sets of contacts, which are arranged in series, activate the closing solenoid.

The breaker control scheme has an antipump feature which allows only one closure of the breaker for a single operation of the closing switch no matter how long the switch may be held closed. This prevents the repeated operations that would ensue if one of the automatic trip devices was activated at the time of closing. The Y relay, together with the cut-off switch, provides the anti-pump feature. The mechanical action of closing operates the cut-off switch, reversing the position of the contacts from that shown on the diagram. This energizes the $Y$ relay, if contact is still maintained at the closing switch, with the result that the $\mathbf{X}$ relay circuit is opened by $X$ contacts $5-6$. This prevents the $X$ relay from again becoming energized. Y contact 1-2 seals in the $Y$ coil as long as contact is maintained at the closing switch.

Electrically operated breakers may also be closed by means of the maintenance handle which is furnished with the breaker. This is a separate tool and is simply a lever which permits an operator to push upwards on the closing solenoid armature. Two small hooks on one end of maintenance handle are engaged in slots (9A) Figure 5, located in the lower portion of the front escutcheon (8A) Figure 5. Rotation of the long end of the handle downwards forces the shorter end of the handle upwards against the bottom of the solenoid armature, and closes the breaker.

The breaker may be tripped open by any one of a number of electrical tripping devices which will be described in detail later in these instructions. An individual breaker may have none or any combination of these devices. They are the overcurrent tripping device, shunt tripping device, undervoltage tripping device, reverse current tripping device, and open fuse lockout device. All of them effect tripping by displacing the trip latch of the mechanism. The trip latch is rigidly attached to a trip shaft which runs through the breaker from left to right. Whenever the trip shaft is rotated in a counterclockwise direction looking from the right, the latch is displaced. The tripping devices are all equipped with strikers or trip arms which act against trip paddles rigidly fastened to the trip shaft, causing it to rotate on its bearings in a direction to trip the breaker.

The reverse current device and the shunt tripping device each have a set of auxiliary switch "a" contacts in their circuits. (An "a" contact is open when the breaker contacts are open.) This prevents their operation unless the breaker is closed.

The undervoltage device coil is normally continually energized. When the control voltage is low or non-existent, as when the breaker has bsen pulled out for inspection or maintenance, the breaker is rendered trip-free by the undervoltage device. If it is desired to close the breaker, the device armature must be tied down or blocked closed against the magnet. The open fuse lockout device is used on all AKU breakers and breaker fuse combinations. The purpose of this device is to trip the breaker upon the blowing of any one of the breaker fuses.

## MANUAL OPERATION

The manually operated breaker is closed by first rotating the handle in a counterclockwise direction through 90 degrees, then rotating it clockwise back to its normal vertical position. The counterclockwise stroke resets the mechanism, readying it for the clockwise closing stroke.

The breaker may be tripped manually by pushing the manual trip button. This action pushes

> These instructions do not purport to cover all defails or variations in equipment nor to provide for every possible contingency to be met in connection with installation, operation or maintenance. Should further information be desired or should particular problems arise which are not covered sufficiently for the purchaser's purposes, the matter should be raferred to the General Electric Compony.
a rod against a trip paddle of the trip shaft, rotating it, and causing the mechanism trip latch to = be displaced. This allows the mechanism linkage to collapse through the action of the mechanism operating springs.

CAUTION: If the breaker is tripped manually while the operating handle is in the reset position, the handle should be lowered by the right hand while operating the trip button with the left hand.

## ELECTRICAL WITH MANUAL OPERATION

This operating mechanism provides both manual and electrical closing. The operating mechanism is similar to the mechanism of the standard electrical breaker with the addition of the manual handle, cam and mechanism connecting link. The
solenoid connecting link and manual cam connecting link are both connected to the closing spring pin at the top of the mechanism, thus compressing the springs when force is provided by either means of breaker closing.

The breaker is manually closed by rotating the closing handle 90 degrees counterclockwise. No reset stroke is necessary as is the case with the standard manual breaker. Electrical closing may be performed either locally or remotely in the same manner as the standard electrical breaker.

Tripping is accomplished by the manual trip button on the escutcheon or by any of the electrical tripping devices available for use on the standard breakers.


Figure 1. (695C160-1) \& (695C159-1) Typical Wiring Diagram

## MAINTENANCE

## INSPECTION

BEFORE INSPECTION OR ANY MAINTENANCE WORK IS DONE, BE SURE THAT THE BREAKER IS IN THE OPEN POSITION. ALL ELECTRICAL POWER, BOTH PRIMARY AND CONTROL SOURCES, SHOULD ALSO BE DISCONNECTED.

Periodic inspection of the circuit breaker is recommended at least once a year. More frequent inspections are recommended, if severe load conditions, dust, moisture, or other unfavorable conditions exist.

If the breaker remains open or closed for a long period of time, it is recommended that arrangements be made to open and close it several times in succession, preferably under load.

At all times it is important not topermit pencil lines, paint, oil or other foreign materials to remain on the insulating surfaces of the breaker as they may cause low resistance between points of different potential and result in eventual electrical breakdown.

Always inspect the breaker after a short circuit current has been interrupted.

At the time of periodic inspection, the following checks should be made after the breaker has been de-energized.

1. Manually operate the breaker several times checking for obstructions or excessive friction.
2. Electrically operate the breaker several times (if breaker has electrical control) to ascertain whether the electrical attachments are functioning properly.
3. Remove and inspect the arc quencher. Breakage of parts or extensive burning will indicate need for replacement.
4. Check contact condition and wipe
5. Check latch engagement.
6. Check operation of tripping devices, including overcurrent trip devices, making sure all have positive tripping action. (Discernible movement in tripping direction beyond point of tripping.)
(For detailed information on breaker features listed, refer to appropriate sections of these instructions.)

## SEPARATION OF FRONT AND BACK FRAMES

 Figure 3Many maintenance operations will either require or be greatly facilitated by separating the
front frame and mechanism of the breaker from the back frame or base, which consists of the current carrying parts of the breaker and their supporting structure. The procedure for this operation is as follows:

1. Remove the arc quenchers (see section on "Arc Quenchers").
2. Disconnect the two insulated connecting links (6), between the mechanism and the crossbar (10), by removing the tie bolt (7), and slipping the ends of the links off the ends of the shouldered pin, (5) Figure 5 in the mechanism.
3. If the breaker is a drawout type, with secondary disconnects, Figure 2, remove the secondary disconnect supporting bracket from the breaker back frame. Also remove any wiring bundle retainers that may be attached to the back frame.
4. Remove one elastic stop nut from each of two studs (3), which tie the upper ends of the mechanism frame to the back frame of the breaker.
5. Remove the two elastic stop nuts (9/16" Hex.) which fasten the wrap around portion of the front frame to the back frame. One of these is located on each side of the breaker, about $2 / 3$ of the distance down from the top edge of the back frame.
On drawout breakers for AKD Equipment, the bottom plate must be removed by first removing two \#8-36 screws located at the front of the bottom plate and then freeing the plate from the slots located in the bottom of the back frame.
6. The two frames are now disconnected. However, care should be exercised in separating them to avoid damage to the trip shaft arms and paddles. While the back frame is held steady, lift the front frame and mechanism up and out so that the trip paddles on the trip shaft clear the trip arms of the overload trip devices.

Reassembly of the two breaker halves is accomplished by following the procedure outlined in reverse order.

## LUBRICATION

In general, the circuit breaker requires very little lubrication. Bearing points and sliding surfaces should be lubricated very lightly at the regular inspection periods with a thin film of extreme temperature, high pressure, light grease, similar to G.E. Spect. No. D50H15 or RPM No. 5. Hardened grease and dirt should be removed from latch and bearing surfaces by the use of a safe cleaning solvent such as kerosene. Latch surfaces should be left clean and dry and not be lubricated.

- ALL EXCESS LUBRICANT SHOULD BE REMOVED WITH A CLEAN CLOTH IN ORDER TO AVOID NY ACCUMULATION OF DIRT OR DUST.

At each maintenance period, all silver to silver friction points, such as primary disconnects, should be cleaned and given a fresh coat of G.E. Spec. No. D50H47 lubricant.

## TROUBLESHOOTING

The following table lists several typical symptoms of breaker malfunction, together with their causes and remedies. If, at any time, these symptoms are observed, their cause should be determined and the necessary corrective action should be taken.

| TROUBLE | CAuse | REMEDY |
| :---: | :---: | :---: |
| Overheating AK-2/3 Breakers | Contacts not aligned <br> Contacts dirty, greasy or coated with dark film <br> Contacts badly burned or pitted <br> Current carrying surfaces dirty <br> Corrosive atmosphere <br> Insufficient bus or cable capacity <br> Bolts and nuts at terminal connections not tight <br> Current in excess of breaker rating <br> Excessive ambient temperature | Adfust contacts. <br> Clean contacts <br> Replace contacts <br> Clean surfaces of current carrying parts <br> Relocate or provide adequate enclosure <br> Increase capacity of bus or cable <br> Tighten, but do not exceed eiastic limit of bolts or fittings. <br> Check breaker application or modify circuit by decreasing load <br> Prowide adequate ventilation |
| Fallure to trip AK-2 Breakers | Travel of tripping device does not provide positive release of tripping latch <br> Worn or damaged trip unit parts <br> Bind in overcurrent trip device | Re-adjust or replace tripping device and check mechanism latch adjustment <br> Heplace trip unit <br> Replace overcurrent trip device |
| False Tripping AK-2 Breakers | Overcurrent trip device pick up too low Overcurrent trip device time setting too short Bind in overcurrent trip device | Check application of overcurrent trip device Check application of overcurrent trip device Replace overcurrent trip device |
| Failure to Close and Latch AK-2/3 Breakers | Binding in attachments preventing resetting of latch <br> Latch out of adjustment <br> Latch return spring too weak or broken <br> Hardened or gummy lubricant <br> Closing solenoid burned out <br> Solenoid control device not functioning properly | Re-align and adjust attachments <br> Adjust latch <br> Replase spring <br> Clean bearing and latch surfaces <br> Replace solenoid coll <br> Re-adjust or replace device |
| False Tripping AK-3 Breakers | Captive Thump screw on Power Sensor loose fail-safe circuitry reverts characteristic to minimum setting and maximum time delay <br> Tap setting dial on Power Supply incorrectly set <br> External Ground Sensor Coil improperly connected | Tighten thumb screw on desired setting <br> Set dial to correspond with Power Sensor coil tap <br> Refer to Figure 22, page 29 for polarity and connections. Check continuity of shield and conductors connecting the external Ground Sensor coil. |
| Failure to Trip AK-3 Breakers | Loose or disconnected power sensor disconnect plugs <br> Loose or broken power sensor coil tap connections | Tighten or reconnect disconnect plugs <br> Tighten or reconnect tap connections |

## BASIC BREAKER COMPDNENTS

## DISCONNECTS

## PRIMARY DISCONNECTS

The primary disconnects are attached to the ends of the breaker studs on the rear side of the breaker base. Each disconnect assembly consists of two pair of opposed contact fingers. These are secured to the breaker stud by a bolt which passes through the assembly and the stud. When engaged with the stationary stud of the enclosure, the disconnect fingers exert a set amount of force against the stationary stud through the action of the compression springs. Retainers and spacers hold the contact fingers in correct alignment for engagement with the stud. The amount of force which the fingers exert against the stud is determined by degree to which the springs are compressed by the bolt and nut which hold the assembly together. This pressure is factory set between 60 and 70 pounds. If, for any reason, the disconnects must be taken apart, the position of the nut on the bolt should be carefully noted, so that in reassemblying, the original amount of compression can be restored by replacing the nut at its former position on the bolt.

## SECONDARY DISCONNECT, FIGURE 2.

The secondary disconnects serve as connections between breaker control circuit elements and external control circuits. They are used only on drawout type breakers. A terminal board serves the same purpose on stationary mounted and general purpose enclosure mounted breakers. The secondary disconnects allow removal of the breaker without the necessity of having to detach external connections.

The movable part of the secondary disconnect consists of an insulating body which holds a conducting spring loaded plunger to which a flexible lead is attached. As the breaker moves into its enclosure, the plunger is depressed by sliding onto the stationary disconnects of the enclosure.

## REPLACEMENT OF MOVABLE SECONDARY DISCONNECTS

1. Unfasten disconnect body from breaker back frame.
2. Open tabs which hold wires on inner side.
3. Pull contact tip loose from hollow tube.
4. Remove contact tip by cutting wire at its base.
5. Push wire through hollow tube of new disconnect assembly.
6. Strip insulation off end of wire to about $1 / 4$ of an inch from end.
7. Place new contact tip on end of wire and crimp.
8. Pull wire through hollow tube until contact tip fits snugly against end of hollow tube.
9. Crimp tab on other side of assembly to hold wire in place.
10. Any hollow tubes which are not used should be pushed into the disconnect body and held in that position by placing fibre spacers over inner ends of tubes and spreading tabs.


Figure 2. (8017973) Movable Secondary Disconnects
11. When all wires have been connected, refasten the body of the assembly to the breaker back trame.

## ARC QUENCHER

The arc quencher is an integral riveted assembly composed of two ceramic side plates, a series of steel plates, and a muffler. The assembly is covered by a wrap around of insulating material which inhibits any sidewise emission of gases. The steel plates are held in position and supported by the ceramic sides which are grooved vertically to provide recesses for the vertical edges of the steel plates. The bottom edges of the latter form an inverted "V" along the path of the arc that may be drawn between the breaker contacts during interruption. The steel plates have the effect of breaking up the arc, and cooling it and the gases that result from interruption. The entire assembly provides a "chimney" effect which directs the hot, ionized gases upwards through the steel plates and mufflers and allows their safe and controlled escape at a cooler temperature.

The muffler at the top of the assembly is a serpentine shaped strip of perforated, copper plated steel. It is important that the perforations of the muffler be kept open, since their closure could tend to prevent the escape of the gases along the desired path. At the regular maintenance inspection, it would be well to check their condition and bea any of the perforations that appear to be togged.

If any very extensive burning or corrosion is noted in the arc quencher, it should be replaced. Replacement is also indicated if any breaks or cracks are noted in the ceramic material.

## REPLACEMENT

Removal of the arc quencher is simply a matter of lifting the assembly up and out, after the steel retainer across the front of the arc quenchers has been removed. The upper edge of the steel arc runner, fastened to the back plate of the breaker, fits into a recess in the back portion of the arc quencher which locates it in its proper position upon replacement. Make sure the steel retainer is replaced and fastened firmly to its mounting studs after the arc quenchers have been replaced.

## BREAKER CONTACT STRUCTURE

The copper current carrying parts of the breaker are all mounted on a common base of insulating material made of polyester glass mat. The copper of each pole consist of an upper stud and pivot, stationary contacts, two movable contact arms, a movable contact pivot, and the lower stud.

The upper stud branches into two pivot surfaces on its inner end on the forward or front side of the breaker base. Each of these convex pivot
surfaces mates with the concave pivot surface on the rear side of the stationary contacts. Each of the stationary contacts pivot in a horizontal plane approximately at their mid-points. The end of the contact opposite to the contact tip end is formed into the shape of a small hook. A tension spring engages this hook and provides the necessary contact pressure at the pivot and also at the point of contact with the movable contact arm. When the breaker contacts open, a projection on the contact tip end of the stationary contact bears against a stop pin restricting the movement of the stationary contact. This arrangement results in a continual high force existing between the mating pivot surfaces.

The movable contact arms pivot in a vertical plane, each making contact with a pair of stationary contacts, and thus providing four low resistant parallel paths of current for each breaker pole. The movable contacts rotate about a burnished, silver plated, copper pin which, in turn, is held by a pivot support. Each side of the pivot support bears against the lower, outer surface of the contact arm and supplies a second low resistance path through the pivot. A "U" shaped spring clip made of silver plated conducting material provides an additional current path and protects the other contact surfaces of the pivot against pitting when in motion. It also contributes to the force tending to increase the contact pressure between the lower ends of the movable contacts and the pivot support.

The movable contact pivot support is mounted securely to the breaker base. If, as is normally the case, the pole is equipped with an overcurrent trip device, one of the terminals of the series coil of the trip unit is fastened to the lower end of the pivot support. The other terminal of the coil fastens to the lower stud.

## CONTACT ADJUSTMENTS

The only adjustment to be made on the breaker contacts is that of contact wipe. This may be described as the distance the movable and stationary move while they are touching one another in the process of breaker closing. The amount of contact wipe can be measured by comparing the position of the front surface of the stationary contact when the breaker is open to its position when the breaker is closed, in reference to some absolutely stationary part of the breaker. The most convenient stationary part of the breaker to use as a reference point is the steel arc runner above and behind the stationary contacts.

The amount of wipe the contacts should have is nominally $1 / 8$ of an inch. A plus or minus tolerance of $1 / 32$ of an inch is allowed.

The means of adjusting contact wipe is provided by an eccentric pin which passes through the center of the movable contact assembly. Each end of this pin has a free, projecting, hexagon
shaped section which is easily accessible to a small, open end, $1 / 4$ inch wrench. Two cantilever springs, which bear on each end against a portion of the hexagon section of the pin, lock the adjusting pin in place and provide index stops for the process of adjustment. The right hand hexagon shaped end of the pin is numbered from 1 to 6 , which provides a reference for making wipe adjustments.

When contacts are to be adjusted, the recommended procedure is as follows:

1. With the breaker in the open position andusing the numbers on the right end of each adjusting pin as a reference, set each pin in the same position. In many cases, the number 3 is a good beginning point. The proper view of the number on the adjusting pin is obtained by viewing the breaker from the front and the adjusting pin from approximately a 15 degree angle with respect to the movable contacts. Note that the numbers on the pin are not in numerical sequence as the pin is rotated.
2. By measurement, establish the position of the front surfaces of the stationary contacts with reference to the steel arc runners above and behind the contacts.
3. Close the breaker, and establish the amount of wipe by again measuring as in step two, and comparing the measurements with those taken with the breaker open.
4. If any set of contacts lead or lag the others, open the breaker and advance or retard the adjusting pin to the next higher or lower number. Moving the adjusting pin to a higher number will increase the contact wipe and moving to a lower number will decrease the contact wipe.
NOTE: No attempt should be made to move the adjusting pin when the breaker is closed. Besides being more difficult, the additional force required to move the pin will tend to round off the flats of the hexsection of the pin.
5. When all the contacts have the recommended wipe of $3 / 32$ to $5 / 32$ of an inch, the contact adjustments are complete.

## CONTACT REPLACEMENT

Figure 3
The normal situation that will exist in the matter of contact replacement will call for replacement of all the movable and stationary contacts at the same time. This will be the case
where long use of the breaker in service has resulted in extensive wear or erosion of the silver alloy contact tips. A commonly used "rule of thumb" is that contact replacement is indicated if less than one-half of the original thickness ( $1 / 8$ of an inch) of the contact tip material remains.

## GENERAL PREPARATION

1. Remove arc quencher retainer (1), Figure 5 by loosening the two captured nuts with a 7/16" wrench.
2. Lift off the three arc quenchers.
3. Remove the $U$ shaped insulation (5) Figure 3 from each pole by lifting it and disengaging the rivet heads thru the keyholed slots in the insulation.
4. As an aid to future reassembly of the-movable contacts, note the position of all stationary insulation barriers with respect to barriers mounted on the cross bar.

## REMOVAL OF MOVABLE CONTACTS

(18) Figure 3.

1. Screw the threaded end of the steel rod lightly into pivot pin (11) on the right pole.
2. With a pair of long nosed pliers, unhook safety pin type spring clip (9) and extract pin (11) and remove spring clip (9).
3. Grasp movable contact assembly and remove it from its seat on the cross bar.
4. Repeat procedure 1, 2, and 3 above on the left pole.
5. Move the cross bar downward to disengage it from the contact wipe adjusting pin (15) on the center pole, then move the cross bar toward the front of the breaker.
6. Remove the split pin retaining the center pole pivot pin.
7. Remove the pivot pin and movable contact assembly.

## REMOVAL OF STATIONARY CONTACTS

## (21) Figure 3.

1. Slip the blade of a heavy screw driver between the two upper contacts and force the contacts toward their pivot point sufficiently far to disengage the contact stop surface from the pin.
2. The contact can then be removed by disengaging the end of the contact from its spring.
3. The two lower contacts can be similarily removed.

## REPLACEMENT OF STATIONARY CONTACTS

(21) Figure 3.

1. Coat the contact pivot area only of each of the four contacts with a thin coat of $\mathbf{D 5 0 H 4 7}$ grease. Use only D50H47 grease.
2. Note the difference between the two types of
stationary contacts and be sure to locate them - in the breaker with the upper and lower contacts having their stop projecting surfaces as shown in the section AA, Figure 3. The upper left and lower right contacts are identical as are the lower left and upper right contacts.
3. By placing the hook on the end of the contact through the loop of the contact spring, the contact can be pushed toward the pivot surface and slipped behind the stop pin. Install all stationary contacts in all poles.

REPLACEMENT OF MOVABLE CONTACTS
(18) Figure 3.

1. Coat the pivot area only of the new movable contacts with a thin coat of D50H47 grease.
2. Assemble the center pole movable contacts, align the pivot pin holes with the bullet nosed rod, and install the pivot pin and split pin.
3. Move the cross bar assembly into position and insert the eccentric contact wipe adjust-


Figure 3. (549D409-2) Contact Assembly

1. Breaker Base
2. Insulation
3. Insulated Stud
4. Upper Stud Barrier
5. Insulation
6. Links (Insulated)
7. Tie Bolt
8. Spring
9. Spring Clip (Retainer)
10. Cross Bar
11. Pivot Pin
12. Lower Stud
13. Contact Pivot Support
14. Spring
15. Contact Wipe Adjustment Pin
16. Screw
17. Upper Stud \& Arc Runner
18. Movable Contact
19. Spring
20. Nut
21. Stationary Contacts
ment pin (15) on the center pole into position. Be sure the stationary insulation barriers are correctly located.
22. Align the cross bar with the left and right pole pivot supports and install the left and right pole movable contacts. Use the bullet nosed steel pin to aid in aligning the holes in the cross bar, the contacts and the pivot supports.
23. Install the left and right pole pivot pins while threading them through the spring clips and lock the spring clips (9). Be sure the pivot pins are fully inserted.
24. Adjust the contact wipe to $1 / 8^{\prime \prime} \pm 1 / 32^{\prime \prime}$ by adjusting the eccentric contact wipe adjusting pin (15). The breaker must be open to adjust the wipe. In the event acceptable wipe cannot be obtained by moving the contact wipe adjusting pin (15), from the movable contact forward or backward as necessary to bring the wipe within the range of the contact wipe adjusting pin (15). Do not exceed the recommended settings for wipe; otherwise the breaker may not close completely. When viewed from the top with the breaker closed, the movable contact should be centrally located with respect to the stationary contacts. If the movable contacts are not centrally located as shown in section CC, form the movable contacts until they are nominally centered.

If the moving contacts are not centered with $1 / 8^{\prime \prime}$ separation when closed against the fixed contacts, they should be bent laterally (after opening the breaker contacts). To do this without squeezing the two movable contact arms together, a $1 / 8^{\prime \prime}$ spacer plate should be inserted between them; then the pair can be grasped with pliers and bent in the desired direction for centering.

New contacts should be adjustable using eccentric numbers 1,2 , or 3 . These numbers are the ones visible when viewing the breaker from the front, not from above. (The higher numbers should be reserved for tightening at future maintenance readjustments after wear.) Also, if higher numbers are used, where adequate wipe is obtainable at settings 1,2 , or 3 , it is possible that the stationary contacts will bottom, producing excessive back force on the breaker closing mechanism so that the toggle link will not pass center. As a result,the breaker will not complete its stroke, and inadequate pressure and wipe will result; burn-up of contacts from just load current will follow.

If the required wipe of new contacts cannot be obtained with eccentric number of 3 or lower, bending of the contact arms toward the closed position is required. This should be done individually, using an $8^{\prime \prime}$ Crescent or $1 / 2-5 / 8^{\prime \prime}$ tapered open end wrench to grasp the contact and a $10^{\prime \prime}$ Crescent or the $1^{\prime \prime}-1-1 / 8^{\prime \prime}$ tapered


Figure 4. (8039851) AK-2-25 Back Frame - Location of Crossbar and Pole Shields

1. Stationary Contacts
2. Movable Contacts
3. Upper Stud Asbestos Shield
4. Crossbar Plastic End Shield
5. Crossbar Assembly
6. Crossbar Asbestos Inner Shield
7. Lower Stud Asbestos Shield
open-end wrench to grasp the pivot portion of the arm. The soft copper arm will bend with little difficulty. Both arms should be bent identically.

Operate breaker several times, and recheck wipe to make sure bending of movable arms did not occur in these operations.
7. Operate the breaker manually several times to assure proper functioning occurs, then replace the $U$ shaped insulation (5) Figure 3 and arc quenchers. When replacing the arc quenchers be sure the quencher is seated downward completely and that the quencher clamp covers the knobs protruding through the arc quencher insulation.

## CONTACT SPRINGS

(19) Figure 3

A minimum force of 5 lbs and a maximum force of 9 lbs . should be required to begin movement of a single stationary contact from the open position towards the closed position. This may be checked by using a push scale applied at the point at which the movable contact touches the stationary contact. If these pressures are not obtained or if the spring is damaged, replacement is required.

In order to replace the contact spring the upper stud (17) must be removed. The hardware which fastens the stud to the breaker base consists of two screws (16), and nut (20). When These are removed, the stud may be withdrawn from the base in a forward direction. After the stud has been removed, it is a simple matter to disconnect the two ends of the spring (19) and replace it with a new one.

## MECHANISM

The breaker mechanism is a spring actuated, over-center toggle type of mechanism. As the closing force is applied, either by movement of the operating handle or the closing solenoid armature, energy is stored in the operating springs. After the springs have gone over center, movement of the output crank of the mechanism is still blocked for a time by a cam arrangement. As the springs are further extended, the blocking cam moves away from the output crank, and the springs are allowed to discharge part of their stored energy, closing the breaker contacts.

This assures a fast-snapping closing action regardless of the speed at which the closing handle is operated.

The breaker mechanism is tripped by the displacement of the trip latch (7), Figure 6 . Looking at the breaker from the right hand side as in Figure 5, the tripping movement of the latch is counter-clockwise. Operation of any of the automatic trip devices or the trip push button causes the latch to move in the tripping direction. When the latch moves off the trip latch roller (7), the remaining force in the operating spring causes the mechanism toggle to collapse, resulting in the opening of the breaker contacts.

## ADJUSTMENT

Since all the mechanism adjustments are carefully set by experienced factory personnel after assembly at the factory, it should normally not be necessary to make any adjustments in the field. At the time of installation, and also in the course of a maintenance inspection, if the breaker functions properly through several repeated operations, it is best to assume that adjustments are satisfactory.

If the breaker mechanism does not function properly, it is best to first perform the available remedial measures listed in the "Trouble Shooting" chart of these instructions. One of the remedies
listed is that of proper mechanism latch engagement, the amount of engagement between the latch (7) and latch roller (5), Figure 6. This is the only adjustment that is required on the breaker mechanism, and proper latch engagement is obtained in the following manner:
(NOTE - Before making latch adjustments, check to make sure that the buffer paddle which stops against the end of the latch adjustment screw is rigidly fastened to the trip shaft. Hold the trip shaft (8), Figure 5, steady and attempt to move the buffer paddle. If any relative movement between the two is noted, tighten the fasteners holding the buffer paddle to the trip shaft.)

## Latch Adjustment - Manual Breaker

1. Locate the latch adjustment screw on the lower, outer side of the right-hand mechanism side frame. This screw is threaded through a nylon insert locknut which, in turn, is welded to a projecting bracket on the side frame.
2. Rotate the closing handle 90 degrees counterclockwise, setting the closing mechanism in the reset position. Turn the adjusting screw .into the locknut until the closing mechanism trips open, the closing handle returning to its normal vertical position. NOTE: KEEP HANDS CLEAR OF THE CLOSING HANDLE WHEN MAKING THIS ADJUSTMENT.
3. Withdraw the adjusting screw from the locknut $1 / 4$ turn at a time, attempting to close the breaker after each $1 / 4$ turn, and observing whether the contacts move toward closing before tripping occurs. If the contacts move before tripping occurs, you have established the position of the adjusting screw where the latch and latch roller begin to engage. In some cases, it may be necessary to turn the adjusting screw less than $1 / 4$ turn in order to establish the position where the contacts begin to move before tripping occurs. When this position is established, note the position of the slot in the head of the adjusting screw.
4. Withdraw the adjusting screw three and one-half turns from the position noted in step 3. This sets the proper amount of latch engagement.

## Latch Adjustment - Electrical Breaker

1. Locate the latch adjustment screw on the lower, outer side of the right mechanism side frame. This screw is threaded through a nylon insert locknut which, in turn, is welded to a projecting bracket on the side frame.
2. With the breaker in the open position turn the adjusting screw into the locknut one complete turn at a time, closing the breaker after each complete turn of the adjusting screw, until
the breaker will not close. Use the maintenance closing handle whenever closing or attempting to close the breaker during this entire operation.
3. Withdraw the adjusting screw from the locknut $1 / 4$ turn at a time, attempting to close the breaker after each $1 / 4$ turn, and observing whether the contacts move toward closing before tripping occurs. If the contacts move toward closing before tripping occurs, you have established the position of the adjusting screw
where the latch and latch roller begin to engage. In some cases, it may be necessary to turn the adjusting screw less than $1 / 4$ turn to establish the position where the contacts move before tripping occurs. When this position is established, note the position of the slot in the head of the adjusting screw.
4. Withdraw the adjusting screw three and onehalf turns from the position noted in step 3. This sets the proper amount of latch engagement.


Figure 5. (8024457) Cut Away Model of Electrically Operated AK-2 Breaker

1. Arc Quencher Retainer
2. Cut off Switch
3. Cut off Switch Actuator
4. Spring Carrier
5. Shoulder Pin
6. Connecting Link
7. Trip Latch Roller
8. Trip Shaft

8A. Front Escutcheon
9. Closing Solenoid

9A. Location of Slots for
Maintenance Handle
10. Closing Solenoid Armature
11. Cover Retainer of Overload Device
12. Lower Stud
13. Socket Head Screws
14. Upper Stud
15. Stationary Contacts and Springs
16. Arc Runner

- Should the mechanism continue to function improperly after the proper latch engagement has been set and the corrective measures listed in the "Trouble Shooting" chart carried out, it is generally recommended that no attempt be made to repair the mechanism interior but that a replacement mechanism assembly be obtained from the factory.


## REPLACEMENT

1. If the breaker is electrically operated, remove the front escutcheon by taking four screws from flange. If the breaker is a drawout type, two small round head screws must also be removed from the bottom edge of the escutcheon. (For removal of front escutcheon from
manually operated breakers, see procedure described below.)
2. Remove arc quenchers (See "Arc Quencher").
3. Disconnect the two insulated connecting links between the mechanism and the contacts as in step 2 of the procedure for 'Separation of Front and Back Frames".
4. Remove the two elastic stop nuts, which fasten the upper extensions of mechanism frame to studs connecting with rear frame.
5. Remove four screws which fasten the bottom of the mechanism frame to the horizontal cross member of the front frame.


Figure 6. (8024516) Cut Away Model of Manually Operated AK-2 Breaker

1. Arc Quencher Muffler
2. Ceramic Side Plates
3. Steel Plates
4. Fixed Centers in Mechanism
5. Latch Roller
6. Escutcheon
7. Trip Latch
8. Handle Return Spring
9. Overload Device
10. Series Coil of Overload Device
11. Trip Arm of Overload Device
12. Trip Paddle
13. Movable Contact Pivot Support
14. Crossbar
15. Movable Contact Pivot
16. Contact Wipe Adjustment Pin
17. Movable Contact
18. Moulded Compound Bar
19. Steel Back Plate
20. If the breaker is manually operated, and has no auxiliary switch, it is now free to be lifted clear of the breaker. If it has an auxiliary switch, this may be disconnected from the mechanism as described under "Auxiliary Switch - Replacement, elsewhere in these instructions.
21. If the breaker is electrically operated, it will be necessary to disconnect the mechanism from the solenoid armature. In order to do this, raise the mechanism as far as the travel of the armature will permit and remove the screw which binds together the two extensions of the armature. After this is removed, the armature extensions must be spread apart to release them from the link connecting with the mechanism. This can be done by threading a \#10-32 screw at least 1-3/4 inches long into the top hole of the armature extension. This hole is just above the one from which the binding screw has been removed. As the end of the screw butts against the far extension, the two extensions will be spread open, releasing the mechanism link.
22. The replacement mechanism may be installed by reversing the order of procedure for disassembly. After reassembly, check the operation of the breaker and, if necessary, adjust the latch engagement.

## $\rightarrow$ <br> REMOVAL OF FRONT ESCUTCHEON <br> OF MANUAL BREAKERS

1. Remove set screw fastening the plastic handle to steel operating shaft and remove the operating
2. Open and remove annealed (soft) retainer and two flat washers from shaft.
3. Remove four screws from flange of escutcheon If the breaker is a drawout type, two small round head screws must also be removedfrom the bottom edge of the escutcheon.
4. Push steel operating shaft through escutcheon bushing.
5. Remove handle reset spring (8) Figure 6, and escutcheon is free of breaker.
6. Handle and escutcheon assembly can be assembled most easily by exactly reversing the procedure for disassembly. In replacing the escutcheon it may be necessary to use pliers to pull the operating shaft fully into the escutcheon in order to have space enough to replace the flat washers and the soft retainer. The latter may be closed on its groove in the shaft by ordinary gas pliers. After replacement, check operation of breaker.

## AUXILIARY SWITCH

The auxiliary switch is mounted on the left side of the operating mechanism frame. Its operating shaft is linked to the output crank of the breaker mechanism. Through a cam arrangement, the operating shaft of the switch controls the open and closed positions of the individual contact pairs. Each stage of the switch, which is usually two-stage or five-stage, contains one "a" and one " $b$ " set of contacts. An "a" pair of contacts is always in the same position as the main breaker contacts. That is, open when the breaker contacts are open, and closed when the breaker contacts are closed. Just the oposite is true of the " $b$ " contacts. The terminals of the switch are covered by a sheet of insulating material held in place by two screws fastened along its left edge. When this is removed, the terminals are exposed. The upper pairs of terminals are those which connect to "a" switches. The lower terminals connect to " $b$ " switches.

## REPLACEMENT

1. Remove auxiliary switch cover.
2. Disconnect leads to switch terminals.
3. Remove two screws which fasten switch to side of mechanism frame.
4. Remove switch by moving towards left.
5. Before mounting replacement switch, turn the crank end of the switch operating shaft in position to engage the hole in the link connecting with with the breaker mechanism. Be sure the bearing washer is in place between the mechanism link and the switch operating shaft.
6. Complete mounting by following disassembly steps in reverse order.

## ELECTRICAL CONTROL COMPONENTS

These consist of the following:

1. Closing solenoid
2. "X" contactor (relay)
3. "Y" permissive relay
4. Cut-off switch
5. Closing switch
6. Shunt-trip device

The last two of these components may or may not be present in the control arrangement.

## CLOSING SOLENOD

The closing solenoid consists of a magnet, armature and coil. This assembly is located directly beneath the breaker mechanism to which it is connected by a link which ties the upper end of the armature to the spring carrier of the mechanism. (See Figure 5.)

When voltage is applied to the coil, the magnetic force generated pulls the armature up into the coil and magnet assembly. This, in turn, rotates the spring carrier about its pivot, extending the mechanism spring and causing its line of action to move "over center", resulting in a closing operation.

## REPLACEMENT

The only replacement operation that might conceivably be required on this assembly is that of the solenoid coil. To replace this, proceed as follows:

1. Remove escutcheon by unfastening four flat head screws in flange.
2. Remove closing switch. (See "Closing switch".)
3. Cut off or disconnect the coll leads.
4. Remove four screws which fasten lower section of magnet to upper section.
5. Allow lower section of magnet and coil to slide downward until clear of armature.
6. Reassemble with new coil by reversing order of procedure.
"x" CONTACTOR

The " X " contactor is a heavy-duty relay which performs the function of closing the circuit of the breaker solenoid during electrical operations. Three of the four sets of contact of the device are arranged in series to minimize the duty required of any one contact. As explained under "Operation", the fourth contact is used to "seal-in" the "X" coil.

The "X" contactor is located on the right beneath the horizontal front frame member. It is mounted on three studs which fasten it to a mounting bracket which is suspended from the frame. Rubber bushings on the mounting studs provide anti-vibration and anti-shock protection for the relay. The relay contacts and their terminals are covered by a molded piece of insulation which fits over spring clips that hold the cover in place.

## REPLACEMENT

Removal of the complete device is accomplished by removing the cover, disconnecting the leads from the terminals, and removing the nuts from the three mounting studs. If the replacement unit includes the mounting bracket, the relay
need not be removed from the old bracket. This can be taken off the breaker simply by removing the two screws which fasten it to the breaker frame. If the breaker is a drawout type, the supporting bracket of the "Y" relay may be temporarily displaced to provide access to the screws.

Since the expendable parts of the " X " contactor are the contacts and the coil, ease of replacement of these parts has been designed into the relay. Methods of procedure are as follows:

## Contacts

1. Remove relay cover.
2. Remove terminal binding screw of stationary contact to be replaced.
3. Lightly pinch with pliers (pointed end) the split section of the contact which enters the hole in the compound body of the device and lift out the stationary contact.
4. With the fingers, pull forward on the spring guide of the movable contact, compressing the contact spring as far as possible.
5. With the spring thus held, grip the end of the contact strip with pointed pliers, turn it through 90 degrees on its long axis, and withdraw it.
6. Replace new contacts by reversing the procedure.

## Coil

1. Remove relay cover.
2. Turn the two retaining spring clips on the ends of the device through 90 degrees about their pivots.
3. Pull out the two halves of the body of the device which carry the stationary contacts. When these are clear of the frame, the armature and movable contact assembly will move aside, exposing the coil.
4. Remove the terminal screws of the coil and pull it free of its retaining spring clips.
5. Place new coil on pole piece inside of the spring clips and fasten terminals to leads.
6. Just start the replacement of one of the compound blocks which hold the stationary contacts into its groove in the frame.
7. Position the armature and movable contact assembly to allow the entrance of the second stationary contact block.
8. When these parts are all properly aligned, with the stationary contacts under the movable contacts, push them into their guiding grooves in the frame until they bottom.
9. Rotate the retaining spring clips to the locked position, making sure that each clip is in its proper recess, and replace the device cover.
"Y" RELAY

As described under "Operation", the 'Y" relay is a permissive relay which limits to one the number of breaker closures possible on one closing signal.

On drawout breakers, the " Y " relay mounting bracket is fastened to the right hand side member of the breaker frame by two mounting screws. On terminal board breakers, it is fastened to the rear side of the terminal board support. The relay itself is fastened to an intermediate bracket which is detachable from the main support. The junctures between the relay and the intermediate bracket and between the two brackets are rubber cushioned against vibration and shock.

## REPLACEMENT

If replacement of the " Y " relay becomes necessary, it may be detached from its supporting brackets by removal of the fastening hardware. The leads to the relay should be cut off as closely as possible to the soldered connections so that enough wire will remain for connection to the new relay. Sufficient original wire is allowed for this purpose.

After the old relay has been removed, the wire leads to the relay should be stripped of insulation to about $1 / 4$ of an inch from the ends. A good mechanical connection should be made before soldering.

After all connections are completed, the relay may should again be mounted to the breaker by means of its supporting brackets and hardware.

After replacement has been completed, the relay may be checked electrically in the following manner:

1. Apply closing voltage to terminal board or secondary disconnects.
2. Push button of closing switch and hold closed.
3. Continuing to hold push button in closed position, manually trip the breaker open.
4. If the breaker stays open, and makes no attempt to close, the " Y " relay is functioning properly.
5. While releasing the close button, observe the "Y" relay. It should open as the closing switch is released.


Figure 7. (695C162) Cut-Off Switch

1. Screw
2. Washer
3. Spring
4. Movable Contact Assembly
5. Spring
6. Actuator
7. Pivot Pin
8. Contact (BB)
9. Contact (AA)
10. Support

## CUT-OFF SWITCH

## Figure 7.

As explained under "Operation", the function of the cut-off switch is to de-energize the "X" contactor coil and energize the " Y " relay coil as the breaker mechanism moves from the opened to the closed position.

The switch is operated by the movement of a mechanism link against the switch actuator (6). This causes the actuator and movable contact assembly (4) to rotate counterclockwise about pin (7), opening the "bb" contacts (8) and closing the "aa" contacts at (9). Overtravel of the actuator (6) beyond the point of making contact at (9) is absorbed by spring (5) which couples the movable contact (4) to the actuator. Spring (3) resets the switch after the breaker contacts open and the breaker mechanism resets.

The point at which the cutoff switch operates during the breaker closing cycle is after the spring charged mechanism has been driven over-center. This assures that the cutoff switch cannot operate too early in the breaker closing cycle, thus the $X$ and $Y$ relays are de-energized and energized, respectively, at the proper time and the circuits anti-pump feature is maintained. When the closing mechanism is driven over-center, the force of the previously charged closing springs is released, closing the breaker.

## REPLACEMENT

The cut-off switch is located above the breaker mechanism. It is fitted between the upper portions of the steel side plates that make up the mechanism frame. A raised horizontal ridge on each side of the molded body of the switch fits into a corresponding groove in each of the steel side plates. A round head screw on each side fastens the switch and side plate together. Replacement of the switch is accomplished by the following procedure:

1. Remove the cover on the top of the switch by taking out the two screws which hold it in place.
2. After taking careful note of the connection arrangements, disconnect the leads from the switch terminals.
3. Remove the two screws, one on each side, which fasten the switch to the mechanism side plates. Note that the one on the right hand side also holds a wiring cleat and spacer which serves to hold the wires clear of the link connecting the mechanism and the breaker position indicator.

Remove the front escutcheonfrom the breaker.
5. Slide the cut-off switch out from between the steel side plates by pulling straight forward.
6. Mount the replacement switch by reversing the order of procedure.

## CLOSING SWITCH <br> Figure 8.

The closing switch is mounted on the upper flange of the closing solenoid coil. A hole in the escutcheon (3) permits access to the switch button (4). When the button is pressed, movable contact (5) deflects and impinges upon stationary contact (2). This energizes the "X" relay coil which seals itself in, and, in turn, energizes the closing solenoid.

## REPLACEMENT

1. Remove escutcheon (3).
2. Disconnect leads from switch terminals.
3. Deflect the left end of hinge (7) to the left so that the movable contact (5) may be disengaged from the switch assembly.
4. Removal of the two screws (10) from speednuts (9) completes the disassembly of the switch.
5. Reassembly with new parts is a matter of reversing the described procedure. In reassembling, be sure the tab on the left end of hinge (7) is bent to the right far enough to avoid any possibility that movable contact (5) might become free of the assembly.

## SHUNT TRIP DEVICE

## Figure 9.

The shunt trip device is mounted underneath the horizontal cross frame member, just to the left of the front escutcheon. It is composed of a magnet, coil and armature. The armature has an extended arm or striker (11) which bears against the trip paddle (12) on the trip shaft when the coil (8) is energized. This displaces the trip latch in the breaker mechanism, opening the breaker contacts.

The trip device is generally activated by a remote switch or relay which closes the shunt trip coil circuit.

In order to avoid unnecessary heating of the coil of the device, an auxiliary switch "a" contact is wired in series with the coil. This prevents the energization of the coil if the breaker is open.

## REPLACEMENT

The entire shunt trip device may be dismounted by disconnecting the coil leads and removing nuts (1). However, the only part of the device that might conceivably need replacement during the life of the breaker is the coil (8). This


Figure 8. (805B905) Closing Switch (Top View)

1. Insulation
2. Stationary Contact
3. Front Escutcheon
4. Push Button
5. Movable Contact
6. Spring
7. Hinge
8. Closing Solenoid
9. Speed Nut
10. Screw


Figure 9. ( 695 C 161 ) Shunt Trip Device

1. Nut
2. Frame
3. Spring
4. Rivet
5. Weight
6. Screws
7. Magnet
8. Coil
9. Clamp
10. Armature
11. Armature Arm
12. Trip Paddle
13. Mechanism Frame
14. Trip Shaft Clamp

- may be replaced without removing the device from the breaker by proceeding as follows:
.. Disconnect leads of coil (8).

2. Remove two screws (6) which fasten magnet (7) and coil to the frame (2).
3. Having removed the magnet from the device, straighten the end of clamp (9).
4. Remove the coil from the magnet.
5. Install new coil, again forming end of clamp (9) as shown.
6. Reassemble to frame.

## 7. Connect coil leads.

## ADJUSTMENT

The only adjustment required on the shunt trip device is that which ensures positively that the breaker will trip when the device is activated. In order to be sure of this, armature arm (11) must travel from $1 / 32$ to $1 / 16$ of an inch beyond the point at which the breaker trips. A good method of checking this is to hold a $1 / 32$ nd shim between the magnet and armature at (10), and with the breaker closed, push upwards at (5), closing the armature against the magnet. If the breaker trips, there is sufficient overtravel. If adjustment is necessary, trip paddle (12) may be formed towards or away from armature arm (11).

## PROTECTIVE DEVICES

An AK-2/3 breaker may be equipped with the following protective devices:

1. Overcurrent trip (Magnetic) AK-2
2. Power Sensor Trip (Static) AK-3
3. Reverse Current Trip AK-2
4. Under Voltage Trip \& Lockout Device

Bell Alarm and/or Lockout device
6. Open Fuse lockout device.
7. AKD-5 Interlock AK-2A/AK-3A

## OVERCURRENT TRIP DEVICE

(Magnetic)
The typical overcurrent trip device consists of a magnetic structure, a series current coil, and a pivoted armature.

When current flow through the series coil generates a magnetic field strong enough, the armature overcomes the restraining force of a calibration spring attached to it, and closes against the magnet. This trips the breaker by means of an extension on the armature which strikes against a trip paddle on the trip shaft.

Depending on the type of individual device, the movement of the armature may be delayed for a time by a timing device. If a relatively long time-delay (seconds or minutes) is desired, the velocity of armature movement is governed by a piston moving through an oil dashpot. If only a short-time delay (cycles or milli-seconds) is required, movement is controlled by an escapement gear and pallets arrangement.

An AK-2-15/25 breaker may be equipped with either the EC-2 or EC-1 overcurrent trip device. The majority of applications will require the use of the EC-2 device. The EC-1 device is normally
used when the short-time delay feature is required, or when the trip device is used to operate a special over-current alarm switch.

Most circuit breakers are equipped with series overcurrent trip devices either of the dual magnetic type (instantaneous and time delay tripping) or instantaneous alone. Breakers are designed to carry up to $100 \%$ of the continuous current rating of their trip devices. Any attempt to carry higher currents for a prolonged period will cause overheating and possible damage.

## EC-2 OVERCURRENT TRIP DEVICE

The Type EC-2 overcurrent tripping device is available in three forms:

1. Dual overcurrent trip, with long-time delay and high-set instantaneous tripping.
2. Low-set instantaneous tripping.
3. High-set instantaneous tripping.

The dual trip has adjustable long-time and instantaneous pick-up settings and adjustable time settings. Both forms of instantaneous trips have adjustable pick-up settings.

DUAL OVERCURRENT TRIP, WITH LONG-TIME DELAY AND HIGH-SET INSTANTANEOUS TRIPPING.

By means of the adjustment knob (5), Figure 10, which can be manipulated by hand, the current pick-up point can be varied from 80 to 160 percent of the series coil rating. The indicator and a calibration plate (4), Figure 10, on the front of the case provide a means of indicating the pick-up point setting in terms of percentage of coil rating. The calibration plate is indexed at percentage settings of $80,100,120,140$ and 160 .


Figure 10. (8024842) EC-2 Overcurrent Trip

1. Series Coil
2. Trip Adjustment Screw
3. Opening for Time Adjustment
4. Pickup Indicator \& Calib. Plate
5. Pickup Adjustment Knob

The long-time delay tripping feature can be supplied with any one of three time-current characteristics which correspond to the NEMA standards maximum, intermediate and minimum longtime delay operating bands. These are identified as $1 \mathrm{~A}, 1 \mathrm{~B}$ and 1 C characteristics, respectively. Approximate tripping time for each of these, in the same order are 30, 15 and 5 seconds at $600 \%$ of the pick-up value of current. (See time-current characteristic curves 286B201A, B, and C).

The tripping time may be varied within the limits shown on the characteristic curves by turning the time adjustment screw (5), Figure 11. Turning in a clockwise direction increases the tripping time;


Figure 11. (8024843) EC-2 Overcurrent Trip With Cover Removed.

1. Instantaneous Calibration Spring
2. Movable Nut (Index Pointer)
3. Time-Delay Calibration Spring
4. Instantaneous Pickup Adjustment Screw
5. Time-Delay Adjustment Screw
6. Oil Dashpot
7. Dashpot Arm
8. Connecting Link
9. Instantaneous Pickup Calibration Marks
counter-clockwise motion decreases it. The dashpot arm (7), Figure 11 is indexed at four points, maximum - $2 / 3-1 / 3$ - minimum from the left, as viewed in Figure 11. When the index mark on the connecting link (8), Figure 11, lines up with a mark on the dashpot arm, the approximate tripping time as shown by the characteristic curve is indicated. The 1A and 1B characteristic devices are shipped with this setting at the $2 / 3$ mark and the 1 C characteristic at the $1 / 3$ mark. The standard characteristic curves are plotted at the same settings.

Time values are inversely proportional to the effective length of the dashpot arm. Therefore, the linkage setting that gives the shortest time value is the one at which dimension "A" Figure 11, is greatest. The time adjustment screw (5), Figure 11, may be turned by inserting a Phillips head screwdriver through the hole in the front of the case, but if it is desired to relate the linkage setting to the index marks on the linkage it will be necessary to remove the case. This may be done by removing the two mounting screws, one on each side of the case, which may be taken off without disturbing the trip unit itself.


| 1. | Series Coil |
| :--- | :--- |
| 2. | Magnet |
| 3. | Pallet |
| 4. | Pinion |
| 5. | Escape Wheel |
| 6. | Driving Segment |
| 7. | S.T.D. Armature |
| 8. | S.T.D. Calibration Spring |
| 9. | Trip Arm |
| 10. | Trip Paddle |
| 11. | Trip Paddle Adjusting Screw |
| 12. | L.T.D. Armature |
| 13. | L.T.D. Calibration Spring |
| 14. | Instantaneous Trip Spring |
| (High Set) |  |
| 15. | Spring Holder |
| 16. | Calibration Clamp Nut |
| 17. | Plunger |
| 18. | Cylinder (Dashpot) |
| 19. | Calibration Plate |
| 20. | Clamping Bracket |

Figure 12. (695C189) EC-1 Type Overcurrent Trip Device

NOTE: Forcing the adjusting screw to either extreme position may cause binding of the device and should be avoided.

INSTANTANEOUS LOW-SET TRIPPING
The low-set instantaneous pick-up point may be varied by the adjustment knob (5), Figure 10. The calibration in this case usually ranges from $80 \%$ to $250 \%$ of the series coil rating, the calibration plate being indexed at values of $80 \%, 100 \%$, $200 \%$ and $250 \%$ of the rating.

## INSTANTANEOUS HIGH-SET TRIPPING

The high set instantaneous pick-up value may have one of the following three ranges: 4 to 9 times coil rating; 6 to 12 times coil rating or 9 to 15 times coil rating. The pick-up setting may be varied by turning the instantaneous trip adjusting screw (4), Figure 11.

Three standard calibration marks will appear on the operating arm at (9), Figure 11, and the value of these calibration marks will be indicated
by stampings on the arm as follows:

| 4X |  | 6X |  | X |
| :---: | :---: | :---: | :---: | :---: |
| 6X | or | 9 X | or | 12X |
| 9X |  | 12X |  | 15 X |

At the factory, the pick-up point has been set at the nameplate value of the instantaneous trip current. (Usually expressed in times the ampere rating of the trip coil.) The variation in pick-up setting is accomplished by varying the tensile force on the instantaneous spring. Turning the adjustment screw changes the position of the movable nut (2), Figure 11, on the screw. The spring is anchored to this movable nut so that when the position of the nut is changed, there is a corresponding change in the spring load. As the spring is tightened, the pick-up point is increased. The top edge of the movable nut (2), Figure 11 serves as an index pointer and should be lined up with the center of the desired calibration mark, punched slots on operating arm, to obtain the proper instantaneous trip setting.

## EC-1 OVERCURRENT TRIP DEVICE

The EC-1 device can be provided with the following tripping combination

1. Long time delay, short time delay and instantaneous -tripping.
2. Long time and short time delay tripping only.
3. Long time delay and instantaneous tripping.
4. Short time delay and instantaneous tripping.
5. Short time delay tripping only.
6. Instantaneous tripping only.
a. Adjustable (Low set)

Non-adjustable (High set)
SHORT TIME DELAY TRIPPING, Figure 12.
The armature (7) is retained by calibrating spring (8). After the magnetic force, produced by an overcurrent condition, overcomes this restraining force, the armature movement is further retarded by an escapement mechanism which produces an inverse time delay characteristic. The mechanism is shown in the left side view of Figure -12.

The pickup for this device can be field set between limits having a ratio of $2-1 / 2$ to 1 in the range of 200 to $1000 \%$ of the coil rating.

## LONG TIME DELAY TRIPPING, Figure 12

The armature (12), is retained by the calibration spring (13). After the magnetic force, produced bs an overcurrent condition, overcomes this restraining force, the armature movement is further retarded by the flow of silicone oil in a dashpot, which produces an inverse time delay characteristic. The mechanism is shown in the right side view of Figure 12.

INSTANTANEOUS TRIPPING, Figure 12.
a. Adjustable instantaneous tripping takes place after the magnetic force produced by an overcurrent condition, overcomes the restraining force of the adjustable calibration spring (13).
b. Nonadjustable instantaneous tripping takes place after the magnetic force produced by an overcurrent condition overcomes the restraining force of a nonadjustable spring (14).

ADJUSTMENTS, EC-1 AND EC-2
In addition to the pick-up settings and timedelay adjustments already described, overcurrent trip devices must be adjusted for positive tripping. This adjustment is made at the factory on new breakers, but must be made in the field when the
breaker mechanism or the overcurrent trip devices have been replaced.

Positive tripping is achieved when adjustment screw (2), Figure 10, is in such a position that it will always carry the trip paddle on the trip shaft beyond the point of tripping the mechanism, when the armature closes against the magnet.

In order to make the adjustment, first unscrew trip screw (2), Figure 10, until it will not trip the breaker even though the armature is pushed against the magnet. . Then, holding the armature in the closed position, advance the screw until it just trips the breaker. After this point has been reached, advance the screw two additional full turns. This will give an overtravel of $1 / 16$ of an inch and will make sure that activation of the device will always trip the breaker.

Adjustment screw (2), Figure 10, can best be manipulated by an extended $1 / 4$ inch hex socket wrench.

In order to gain access to the adjustment screw on the center pole overload device, it will be necessary to remove the nameplate from the front escutcheon of the breaker. This will reveal a hole, centrally located in the escutcheon, by means of which the extended socket wrench can engage the adjustment screw.

## REPLACEMENT, E $\dot{C}-1$ and EC-2

Replacement of either the EC-1 or EC-2 overcurrent trip device is accomplished by the following procedure:

1. Separate the breaker's front and back frames as described in the section under "Maintenance".
2. Remove the steel clamps which fasten the cover of the device to the back of the breaker. NOTE: Pickup settings on the cover of each device are calibrated for the specific device. When replacing covers, replace on associated device.
3. Remove the $3 / 8$ inch hexagon headed bolts which fasten the coil of the overload device to the breaker copper.
4. Remove the round head screw which fastens the frame of the overload to the breaker base.
5. After reassembling breaker with new overload device, adjust for "positive trip" as described under "Adjustments" of this section.

## REVERSE CURRENT TRIP DEVICE

Figure 13.
The reverse current trip device sometimes used with d-c breakers will trip the breaker open if the direction of current flow is reversed.

This device is similar in appearance and is mounted in the same way as the overcurrent trip.

rigure 13. (286B209) Reverse Current Tripping Device

| 1. | Series Coil | 7A. | Screws |
| ---: | :--- | ---: | :--- |
| 2. | Adjusting Nut | 8. | Counterweight |
| 2A. | Locking Nut | 9. | Stop Screw |
| 2B. | Trip Rod | 10. | Mounting Screw |
| 3. | Spring | 11. | Screw (Lower Stud) |
| 4. | Potential Coil | 12. | Trip Crank |
| 5. | Calibration Nut | 13. | Screw (Lower Stud) |
| 6. | Armature | 14. | Trip Paddle |
| 7. | Pole Pieces |  |  |

The device consists of a series coil (1), with an iron core mounted between two pole pieces (7) and a potential coil connected across a constant source of voltage and mounted around a rotary type armature (6). Calibration spring (3) determines the armature pick-up value when a reversal of current occurs.

As long as the flow of current through the breaker is in the normal direction, the magnetic fix of the series coil and the magnetic flux of the
ential coil produce a torque which tends to 2 otate the armature counterclockwise. The calibration spring (3) also tends to rotate the armature in the same direction. This torque causes the
armature to rest against stop screw (9) attached to a bearing plate on the right side of the device.

If the current through the series coil (1) is reversed, armature (6) tends to move in a clockwise direction against the restraint of calibration spring (3). When the current reversal exceeds the calibration setting, the armature will move in a clockwise direction. This causes trip rod (2B) to move upwards against trip paddle (14), tripping the breaker open.

## ADJUSTMENTS

The only adjustment to be made on the reverse current device is to make sure that the trip rod has a minimum overtravel of $1 / 32$ of an inch beyond the point of tripping the breaker. The only occasion this adjustment should have to be made is when an old device is being replaced by a new one.

The new device will be factory adjusted so that the top end of the trip rod ( 2 B ) will extend $1 / 2$ inch above the top of the device case, and no additional adjustments of the trip rod should be required. To obtain the proper $1 / 32$ of an inch overtravel, close the breaker and proceed as follows:

1. Loosen the locking nut (2A).
2. Manually lift the trip rod and vary the position of the adjusting nut (2), thus establishing the position of the adjusting nut where the breaker is just tripped. (NOTE - Be sure that all parts of the person are kept clear of moving breaker parts when tripping the breaker.
3. With this position of the adjusting nut established, advance the adjusting nut upward one and one half turns.
4. Tighten the locking nut and the minimum $1 / 32$ of an inch overtravel of the trip rod should be obtained.

## REPLACEMENT

Replacement of the ED-1 Reverse Current Device is accomplished by means of the same procedure as that followed in the case of the EC Overcurrent Trip Devices. There is, however, one additional step to the taken. This consists of disconnecting the leads of the potential coil. These are connected to a small two point terminal board mounted between two of the phases on the breaker base. After the new device has been installed, adjust for overtravel of the trip rod as described above.

## POWER SENSDR TRIP

## GENERAL DESCRIPTION

All AK-3 Type Air Circuit Breakers contain Power Sensor Overcurrent Trip Devices. The Power Sensor Trip functions with solid state components with the exception of the Magnetic Trip Device which is used to trip the breaker on signal from the Power Sensor Unit. The Power Sensor Overcurrent Trip Device consists of four major components.

1. The magnetic coils around the breaker conductors (Figure 14).
2. The Power Supply which provides both the tripping energy and the comparison basis for overcurrent detection (Figure 15).
3. The Power Sensor Unit with the various pickup settings and time delay selection taps (Figure 16).
4. The Magnetic Trip Device which physically trips the breaker (Figure 17).

In addition to the phase overcurrent protection, a ground fault sensing feature may be provided.

The Ground Sensing Device works on the principle that the instantaneous value of current flowing in the three conductors (or; in four conductors on four wire systems) must add to zero unless ground current is flowing. Therefore, if the electrical system is a four wire wye system with the neutral grounded at the transformer, the fourth sensing coil (Figure 18) must be included on the neutral conductor with its secondary combined with the secondaries of the three phase sensors which are mounted on the breaker. On Draw-out breakers, the output of the external neutral sensor must enter the breaker by a control disconnect (Figure 19) which is mounted low and on the centerline on the back of the breaker. Refer to Figure 20 for Power Sensor Cabling diagram.

## MAINTENANCE

When mal-functioning of the Power Sensor Trip is indicated the trouble should be traced to one or more of these four components involved, and that component should be replaced as a unit. The following steps should be taken to detect a malfunctioning unit.


Figure 14. (8041866) Magnetic Coils

NOTE: No adjustment to the taps controlling up or timing should be made with the breaker ca 1, ying current.

In the event the Power Sensor Device must be made non-operative to allow the breaker to continue carrying current without overcurrent protection, it is recommended that the leads to the tripping solenoid be removed to completely eliminate the possibility of the breaker tripping. Do not close breaker with power on the main contacts while the disconnect plug to the magnetic coils is disconnected

1. Check for the existence of overcurrent or ground fault conditions that may be causing


Fig. 15. (8039850) Power Supply

1. Rating Disc
2. Mounting Bracket
3. Female Disconnect Plug
4. Male Disconnect Plug
5. Terminal Block


Figure 16.(8041864) Power Sensor Unit

1. Mounting Screw
2. Captive Thumb Screw
3. Name Plate
the breaker to trip as a proper response to these abnormal circuit conditions.
4. The possibility of the breaker being trip free by mechanical interferences along the trip shaft or inadvertent shunt trip operations should be positively eliminated before investigating the Power Sensor. Successful operations in the test position should be obtained before proceeding with the Power Sensor trouble shooting.
5. A PST-1 Power Sensor Test Kit must be available. (Figure 21). Check the Power Sensor Unit for correct function for each pick-up setting and one point on each time delay characteristic. Then check for the correct operation of each phase of the Power Supply Unit. This procedure is described in the instruction manual (GEK-7301) for the PST-1 Test Kit, and GEK-7309 Power Sensor Instructions. If the test results for this test do not deviate more than $10 \%$ from the published curves, proceed to step 4. If the deviation is more than $10 \%$ contact the factory for possible replacement of the Power Sensor Unit.
6. If the breaker is equipped with ground fault protection, determine whether the false tripping is the result of falsely answering an overcurrent trip or a ground trip signal. This may be determined by temporarily eliminating the ground trip signal by shorting out the ground signal points 1 and 5 at the ground signal terminal board on the back frame bottom of the breaker. Terminals 1 and 5 can be identified by the 0.15 UF capacitor connected


Figure 17. (8041863) Magnetic Trip Device

1. Name Plate
2. Mounting Bracket
3. Spring
4. Trip Arm
5. Adjusting Screw
6. Armature
. Clamp
7. Coil
8. Magnet
between them. See drawing 138B2454 (Figure 22) with the breaker restored to service with the ground fault detector deactivated, establish whether there is false tripping due to overcurrent.

FALSE TRIPPING CAUSED BY FAULTY GROUND FAULT DETECTION

If the breaker is equipped for four wire service (fourth C.T. remotely mounted, Figure 18) it is important that the shielding be effective by having continuity from the disconnect plug at the Power Sensor Unit to the external C.T. and further, that this shield be isolated from the signal conductors. It is also important that continuity exists through the ground signal circuit. Check these conditions as follows; referring to Figure 22.

1. Remove connection plug at Power Sensor Unit and check continuity between A and C (Signal). Letters are located on end of plug.
2. Check to be sure no continuity exists between R and A , or between R and C .
3. Temporarily connect jumper from shield to either terminal at remote C.T. and check to assure the shield is continuous from Power Sensor Plug to remote C.T. by checking fo: continuity between $R$ and $A$. If continuity does not now exist, shield is not continuous and point of discontinuity must be found. Check the control disconnect as the possible point of discontinuity. Remove jumper at remote C.T. after shield continuity is established.

Note the polarity marks on the ground sensors. Be sure the external ground C.T. senses the neutral current associated with the particular breaker load current and that polarity marks are in accordance with 138B2454 (Figure 22). If the breaker bottom studs connect to the source, the external C.T. must also have its polarity mark toward the source.


Figure 19. (8918380A) Control Disconnect Plug

1. Female Disconnect Plug
2. Terminal Board
3. Mounting Bracket


Figure 20. (0133C9017) Power Sensor Cabling Diagram


Figure 21. (8039962) Power Sensor Test Kit

## TESTING MAGNETIC COILS

After the PST-1 Test Kit has been used to determine the adequacy of performance of the Power Sensor Unit, it may be advisable or required to test the magnetic coils by the use of a hi-current Low voltage type test set. In this event, only one test per phase need be made. This test should be made at some convenient multiple of pick-up setting such as $300 \%$ for comparison with published time-current curves.

In the event the breaker is equipped with ground sensor, the ground sensor will cause tripping on single phase testing unless the signal is shorted at the terminal board (Figure 22). Jumper points 1 and 5 during overcurrent test.

The above considerations should indicate which of the four major components is faulty and in need of replacement.

## REPLACEMENT OF POWER SENSOR <br> COMPONENTS

POWER SENSOR UNIT (Figure 16).

1. Loosen screw connecting the unit to the front frame.
2. Slide unit forward.
3. Remove control plug by alternately loosening the two retaining screws.
4. Replace in reverse order.

MAGNETIC TRIP DEVICE (Figure 17).

1. Remove trip solenoid wires from the terminal board on power supply.
2. Remove four screws holding power supply to breaker frame.
3. Pull power supply forward until restricted by wiring.
4. Remove two bolts holding trip device to breaker frame.
5. Lift out trip device.
6. Replace in reverse order.

POWER SUPPLY (Figure 15).

1. Remove magnetic trip wires from the terminal board on POWER SUPPLY
2. Remove four screws holding power supply to breaker frame.


Figure 22. (138B2454) Ground Fault Wiring Diagram

GET-502g9 Power Circuit Breakers Types AK-2-15 and AK-2/3-25


Figure 23. (286B209) Time-Current Characteristic - EC Devices


Figure 24. (109HL687) Time Curve
3. Remove four screws holding escutcheon to mechanism frame and remove escutcheon.
4. Disconnect control plug to power sensor coils and power sensor unit.
5. Remove cable clamps holding cabling in place.
6. Remove power supply unit with attached cabling.
7. Replace in reverse order.

SENSOR COILS (Figure 14).

1. Separate the breaker front and back frame as described in the section under "Maintenance".
2. Remove two screws holding sensor coil disconnect plug bracket to back frame.
3. Remove bolt holding resistor bracket to back frame.
4. Remove 2 screws holding capacitor bracket to back frame.


Figure 25. (109HL689) Time Curve
5. Unsolder three leads at ground disconnect and pull wire through hole in back frame. On stationary breakers with fourth wire ground disconnect, unsolder leads at external ground coil and pull wire through hole in back frame.
6. Remove primary disconnects per instructions under disconnects.
7. Remove three $3 / 8$ hexagon headed bolt connecting coils to breaker copper.
8. With the back frame in the vertical position, and supported, grasp the outside coils and lift coil assembly from back frame. When carrying or moving sensor coil assembly, always support the outside coils.

## SELECTIVE TRIPPING

Selective overcurrent tripping is the application of circuit breakers in series so that only the circuit breaker nearest the fault opens. Anyone or combination of two or more of the preceding over-current devices may be used in a selective system. The breaker having the shorter time setting and lower pickup will trip before the

breaker having the longer setting and higher pickup, provided the fault is on the part of the line protected by the breaker having the lower setting.

For the exact characteristics and setting of each breaker in a selective system, reference should be made to a coordination chart for the particular system. (Figures 23, 24, and 25)

## STATIC TIME DELAY

UNDERVOLTAGE TRIPPING DEVICE

The Static Time Delay Undervoltage Tripping Device consists of an undervoltage device mounted on the breaker, a static time delay box mounted separately from the breaker and a control power transformer which is also mounted separately from the breaker when the reference voltage is other than DC., 208V AC or 230V AC. Refer to wiring diagram 0102C3698 (Figure 26).
The voltage $208 \mathrm{~V} A C$ or $230 V A C$, to be
munitored is connected to terminals \#1 and \#2
of the time delay box. The undervoltage device
on the breaker is always connected through either its secondary disconnects or terminal board, to terminals \#4 and \#5 of the time delay box.

The undervoltage device is set to pickup at approximately $80 \%$ of bus voltage and drop out between $30 \%$ and $60 \%$.

The undervoltage device coil circuit is continuously rated and will remain picked up as long as the voltage remains above the predetermined drop out voltage. The time delay is field adjustable between 1 and 5 seconds, it is factory set at the minimum setting, and once the time delay is established, it is consistent.

No more than one undervoltage device should be connected to a static time delay box.

The Static Time Delay Undervoltage can also be furnished in conjunction with the termotector control package, as shown on wiring diagram 0102 C 3699 (Figure 27). Overheating of the motor windings causes the termotector, imbedded in the motor windings, to open and allow the " $Z$ " relay of the control box to instantaneously trip the

breaker through a normally closed " Z " contact in series with the undervoltage device mounted on the breaker.

WAFNING - Do not use bell set to check continuity of bridge circuit in static time delay box, only a volt-ohm meter or vacuum tube volt meter should be used.

In the event the device fails to pick-up, the following checks are recommended to determine whether the magnetic device on the breaker or the static time delay unit is the faulty component.
A. Check input voltages across terminals 1 \& 2 on static box. These voltages should be as follows:

1. Device $177 \mathrm{~L} 316 \mathrm{G}-12-208$ or 230 volts A.C.
2. Device 177 L 316 G-14-125 volts D.C.
3. Device $177 \mathrm{~L} 316 \mathrm{G}-15-250$ volts D.C.
B. Check output voltages on terminals 4 \& 5 with the under voltage device connected. The
approximate voltages are as follows:
4. 208 Volt A.C. 177 L 316 G-12-110 volts D.C. 230 Volt A.C. 177L316 G-12-120 volts D.C. 2. 125 Volt D.C. $177 \mathrm{~L} 316 \mathrm{G}-1450$ volts D.C. 3. 250 Volt D.C. 177 L 316 G-15-100 volts D.C.
C. The resistance of the under-voltage coils are as follows:
5. $6275080 \mathrm{G}-59-1830$ Ohms.
6. 6275081 G-61 - 440 Ohms.

## REPLACEMENT

The entire device may be dismounted by disconnecting the coil leads and removing screw (1) and nuts 16 . Normally, only the coil (12) will ever need replacement. This may be removed from the device by taking out screws (11) which will free both the magnet (10) and the coil. Straight-


1. Mounting Screw
2. Frame
3. Armature
4. Spring
5. Shading Ring
6. Adjusting Screw
7. Locking Nut
8. Bushing
9. Clamp
10. Magnet
11. Screws
12. Coil
13. Rivet
14. Adjusting Screw
15. Locking Wire
16. Mounting Nut
17. Mechanism Frame
18. Trip Paddle Clamps
19. Trip Paddle
20. Adjusting Screw

Figure 28. (0152C9206) Undervoltage Tripping Device


Figure 29. (0101C7842) Undervoltage Lockout Device

1. Cross Bar
2. Left Side Frame
3. Trip Paddle
4. Undervoltage Armature
ening of the bend in clamp (9) will separate the coil from the magnet. The coil leads, of course, must be disconnected.

## INSTANTANEOUS UNDERVOLTAGE

 TRIPPING DEVICEThe instantaneous undervoltage device is mounted in the same location and manner as the static time-delay device and its construction is similar.

The adjustments and replacement of $t$ is device are the same as those described above for the static time-delay undervoltage device.

## UNDERVOLTAGE LOCKOUT DEVICE

(Figure 29)
The undervoltage lockout device holds an open breaker trip-free when the coil of the device is deenergized. When the breaker is in the closed position, linkage operated by the breaker mechanism cam positions itself to mechanically hold the undervoltage device armature in the closed air gap position to prevent tripping the breaker in the event the undervoltage device coil is deenergized. This feature when used in conjunction with normally-closed auxiliary contacts of an
àternate breaker presents a convenient method of mechanically interlocking two or more breakers to assure that no two breakers may be closed at the same time.

## BELL ALARM SWITCH AND/OR LOCKOUT ATTACHMENTS

(Figure 30)
The bell alarm device is mounted on top of the horizontal cross frame member just to the left of the mechanism frame when the breaker is viewed from the front. This device operates a switch with two sets of contacts, one normally open, the other normally closed. The switch may be used to open or close an external circuit, giving a bell or light indication of a protective trip device operation.

If the breaker is tripped open by any means other than the manual trip button or the shunt trip device, the bell alarm mechanism is activated. The alarm is shut off and the bell alarm and lockout mechanism is reset by operation of the manual trip button or shunt trip device. If the device is a bell alarm only, the bell alarm mechanism is also reset simply by closing the breaker.

## OPERATION

Lever (2) is connected to the breaker mechanism so that when the breaker opens lever (2) rotates counterclockwise about pin (14). The motion is transmitted through links (1) and (13) to paddle (12) which operates bell alarm switch (11). If the device has the lockout feature, the movement of link (13) also causes lockout link (8) to slide in a direction that results in its striking trip paddle (5) which, by displacement of the breaker mechanism trip latch, makes it impossible to reset the breaker mechanism until the bell alarm mechanism is reset.

Link (6) serves as a latch in the bell alarm mechanism. If it is displaced, link (10) is free to rotate about its lower pin. This deprives the linkage of its normally fixed center of rotation about pin (15) and defeats both the bell alarm and the lockout operation. Operation of either the manual trip button or the shunt trip device will displace latch (6) and have this effect. Thus if the breaker is tripped by either of these means, the bell alarm and/or lockout will not operate. Also, operation of either of these devices will reset the switch and inactivate the lockout.


Figure 30. (695C158) Bell Alarm and Lockout Device

1. Link
2. Lever
3. Pin
4. Trip Shaft
5. Trip Paddle
6. Link
7. Trip Arm
8. Lockout Link
9. Frame
10. Link
11. Switch
12. Paddle
13. Link
14. Pin
15. Pin
16. Springs
17. Spring

## UPEN FUSE LOCKOUT DEVICE

 (Figure 31)The Open Fuse Lockout Device consists of two or three separately operated devices (one per phase). Each wired in parallel to corresponding breaker fuses. This device is furnished on all AKU breakers. The purpose of this device is to trip the breaker upon the blowing of any one of the breaker fuses and render the breaker trip free until the blown fuse is replaced and the associated coil assembly reset.

OPERATION, Figure 31.
When any one of the breaker fuses blow, the coil (6) in that phase is energized and the armature (5) closes. With the armature closed, leaver (2) slips under the armature and latches it in the closed position. The latched closed armature holds the breaker in the trip free position until it is released by pushing the associated reset button (1). The coil is deenergized as soon as the breaker opens.

## ADJUSTMENTS

1. Set top cylindrical collor (not shown) to engage the trip shaft paddle in the tripped position.


Figure 31. (8041865) Open Fuse Lockout Device

1. Mounting Holes
2. Lever
3. Reset Button
4. Collor
5. Armature
6. Coil
7. Check that each armature holds the breaker trip free when the armature position is limited in reset by the lower latch surface on the indicator.
8. With the breaker in the closed position, the top collor must clear the trip shaft paddle by more than $1 / 32$ inch.

## REPLACEMENT

1. Remove three mounting screws at top of device.
2. Remove coil leads from fuses and work wire harness back to the device. Remove device from breaker.
3. Replace new unit in reverse order and check procedure under ADJUSTMENTS.

## AKD-5 INTERLOCK

(Figure 32)
The rackout mechanism is interlocked so that the circuit breaker must be open before the operating handle can be inserted. When the breaker is closed, the interlock link (1) operated by the breaker cross bar blocks the interlock linkage on the rackout mechanism.


Figure 32. (8039852) AKD-5 Interlock

1. Rackout Mechanism Interlock
2. Trip Interlock

## MISCELLANEDUS

Changes in breaker requirements may occasionally bring about the necessity of adding or changing breaker components or accessories in the field. The AK-2 breaker has been designed so that such additions or conversions are simple and easy to make, requiring only a minimum of time or skill on the part of the operator.

Special instructional drawings are available which will further simplfy the addition of such accessories to breakers which were originally shipped without them.

These drawings will accompany the necessary material when it is shipped from the factory. They will also be available upon request. The drawings and the accessory additions which they cover are listed below.

When an accessory is added to a breaker, it is recommended that the section of instructions contained herein covering that particular accessory be reviewed, in addition to referring to the following instructional drawing. Any adjustments described in these instructions should be carefully made after the device has been assembled on the breaker.

Conversion of breakers from manual to electrical operation is also covered on aninstructional drawing. This operation consists simply of separation of the front and back frames of the breaker as described under "Maintenance" in these instructions and the reassembly of the existing back frame with the new front frame.

| Addition of | Covered By |
| :--- | :---: |
| Shunt Trip Device | 698 C 900 |
| Auxiliary Switch | 698 C 901 |
| Undervoltage Device | 698 C 902 |
| Bell Alarm \& Lockout Device | 698 C 904 |
| Drawout Mechanism | 698 C 922 |
| Conversion to Elec. Oper. | 698 C 904 |

## MAINTENANCE TOOLS

The following tools are recommended for proper maintenance of AK-2-15 and AK-2/3-25 breakers. (NOTE: Obtain from local hardware firm; do not order on General Electric Company.)

Screw Drivers
Long thin, slotted screw
Standard, slotted screw
Phillips, No. 2, ( $8^{\prime \prime}$ shaft)

## Pliers

Waldes Truarc, No. 2 straight
Long Nose, side cutting, ${ }^{\prime \prime}$
End Wrenches
Adjustable, $8^{\prime \prime}$
$1 / 4^{\prime \prime}$ open end

## Allen Head Wrenches

5/ $16^{\prime \prime}$ for $3 / 8^{\prime \prime}$ screw
$1 / 8^{\prime \prime}$ for $1 / 4^{\prime \prime}$ screw
Socket Wrenches ( $3 / 8^{\prime \prime}$ drive)
Ratchet Handle
$12^{\prime \prime}$ extension bar
3/8' socket
9/16' ${ }^{\prime \prime}$ socket $7 / 16^{\prime \prime}$ socket (long)

Miscellaneous Tools
$1 / 4^{\prime \prime}$ Spintite (long shank)
$7 / 16^{\prime \prime}$ Spintite
8 32 screw (at least $2^{\prime \prime}$ long)

## RENEWAL PARTS

When ordering renewal parts, address the nearest Sales Office of the General Electric Company, specifying the quantity required. Comiplete nameplate data of the breaker involved should be given as well as an accurate description of the parts required. If the parts needed are illustrated in this book, refer to the figure number and part number invoived.

Renewal Parts which are furnished may not
be identical to the original parts since from time to time design changes may be made. The parts supplied, however, will be interchangeable with the orisinal parts.

Renewal Parts Bulletin
Bulletin
GEF-4149F

Breaker Type
AK-2-15/25
AK-3-25


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## INTRODUCTION

The instructions contained herein provide information for performing maintenance procedures and for replacing AK-2/3-15/25 breaker components and accessories. For information regarding
the receiving, handling, storage and installation of these breakers, refer to GEK-7302 furnished with all AK breakers.

## ELECTRICAL OPERATION Figure 1

The electrically operated breaker closes whenever the closing solenoid coil is energized. This causes an upward movement of the solenoid armature, which initiates the mechanical closing action. The closing signal may be given either by a remote switch or relay, or by a closing button in the front escutcheon if the breaker is so equipped. Either action (refer to the elementary of the wiring diagram) energizes the coil of the X relay through the bb contacts of cutoff switch $G$ and the normally closed contacts of the $Y$ relay. When the $X$ relay or contactor is energized, it closes its contacts. One of these (K1-2) seals in the $X$ coil. The other three sets of contacts, which are arranged in series, activate the closing solenoid.

The breaker control scheme has an antipump feature which allows only one closure of the breaker for a single operation of the closing switch no matter how long the switch may be held closed. This prevents the repeated operations that would ensue if one of the automatic trip devices was activated at the time of closing. The Y relay, together with the cut-off switch, provides the anti-pump feature. The mechanical action of closing operates the cut-off switch, reversing the position of the contacts from that shown on the diagram. This energizes the $Y$ relay, if contact is still maintained at the closing switch, with the result that the $X$ relay circuit is opened by $Y$ contacts 5-6. This prevents the $X$ relay from agair becoming energized. Y contact 1-2 seais in the $Y$ coil as long as contact is maintained at the closing switch.

Electrically operated breakers may also be closed by means of the maintenance handle which is furnished with the breaker. This is a separate tool and is simply a lever which permits an operator to push upwards on the closing solenoid armature. Two small hooks on one end of maintenance handle are engaged in slots (9A) Figure 5, located in the lower portion of the front escutcheon (8A) Figure 5. Rotation of the long end of the handle downwards forces the shorter end of the handle upwards against the bottom of the solenoid armature, and closes the breaker.

The breaker may be tripped open by any one of a number of electrical tripping devices which will be described in detail later in these instructions. An individual breaker may have none or any combination of these devices. They are the overcurrent tripping device, shunt tripping device, undervoltage tripping device, reverse current tripping device, and open fuse lockout device. All of them effect tripping by displacing the trip latch of the mechanism. The trip latch is rigidly attached to a trip shaft which runs through the breaker from left to right. Whenever the trip shaft is rotated in a counterclockwise direction looking from the right, the latch is displaced. The tripping devices are all equipped with strikers or trip arms which act against trip paddles rigidly fastened to the trip shaft, causing it to $r$ on its bearings in a direction to trip the bre

The reverse current device and the shunt tripping device each have a set of auxiliary switch " $a$ " contacts in their circuits. (An " $a$ " contact is open when the breaker contacts are open.) This prevents their operation unless the breaker is closed.

The undervoltage device coil is normally continually energized. When the control voltage is low or non-existent, as when the breaker has bsen pulled out for inspection or maintenance, the breaker is rendered trip-free by the undervoltage device. If it is desired to close the breaker, the device armature must be tied down or blocked closed against the magnet. The open fuse lockout device is used on all AKU breakers and breaker fuse combinations. The purpose of this device is to trip the breaker upon the blowing of any one of the breaker fuses.

## MANUAL OPERATION

The manually operated breaker is closed by first rotating the handle in a counterclockwise direction through 90 degrees, then rotating it clockwise back to its normal vertical position. The counterclockwise stroke resets the mechanism, readying it for the clockwise closing stroke.

The breaker may be tripped manually by pushing the manual trip button. This action pushes

[^20]a rod against a trip paddle of the trip shaft, rotating it, and causing the mechanism trip latch to be displaced. This allows the mechanism linkage to collapse through the action of the mechanism operating springs.

CAUTION: If the breaker is tripped manually while the operating handle is in the reset position, the handle should be lowered by the right hand while operating the trip button with the left hand.

## ELECTRICAL WITH MANUAL OPERATION

This operating mechanism provides both manual and electrical closing. The operating mechanism is similar to the mechanism of the standard electrical breaker with the addition of the manual handle, cam and mechanism connecting link. The
solenoid connecting link and manual cam connecting link are both connected to the closing spring pin at the top of the mechanism, thus compressing the springs when force is provided by either means of breaker closing.

The breaker is manually closed by rotating the closing handle 90 degrees counterclockwise. No reset stroke is necessary as is the case with the standard manual breaker. Electrical closing may be performed either locally or remotely in the same manner as the standard electrical breaker.

Tripping is accomplished by the manual trip button on the escutcheon or by any of the electrical tripping devices available for use on the standard breakers.

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| $\times$ | a- TERMmal goaro locatcd top richt. |
| :---: | :---: |
|  | F-antr-pump permissive relay. |
| = TRP | G. (a0.bb) - cut-off Switer |
| ${ }^{10} 4$ |  TACTS N SEACS |
| $x_{0}^{\text {\% wix }}$ |  HTCO-SHNTT TAPP DEVIEE. |
|  | W-recr-solemodo closing coll. |
|  | Atrat-closing switch on breaker |
| 18. | t-transformer. |




## MAINTENANCE

## INSPECTION

BEFORE INSPECTION OR ANY MAINTENANCE WORK IS DONE, BE SURE THAT THE BREAKER IS IN THE OPEN POSITION. ALL ELECTRICAL POWER, BOTH PRIMARY AND CONTROL SOURCES, SHOULD ALSO BE DISCONNECTED.

Periodic inspection of the circuit breaker is recommended at least once a year. More frequent inspections are recommended, if severe load conditions, dust, moisture, or other unfavorable conditions exist.

If the breaker remains open or closed for a long period of time, it is recommended that arrangements be made to open and close it several times in succession, preferably under load.

At all times it is important not to permit pencil lines, paint, oil or other foreign materials to remain on the insulating surfaces of the breaker as they may cause low resistance between points of different potential and result in eventual electrical breakdown.

Always inspect the breaker after a short circuit current has been interrupted.

At the time of periodic inspection, the following checks should be made after the breaker has been de-energized.

1. Manually operate the breaker several times checking for obstructions or excessive friction.
2. Electrically operate the breaker several times (if breaker has electrical control) to ascertain whether the electrical attachments are functioning properly.
3. Remove and inspect the arc quencher. Breakage of parts or extensive burning will indicate need for replacement.
4. Check contact condition and wipe
5. Check latch engagement.
6. Check operation of tripping devices, including overcurrent trip devices, making sure all have positive tripping action. (Discernible movement in tripping direction beyond point of tripping.)
(For detailed information on breaker features listed, refer to appropriate sections of these instructions.)

## SEPARATION OF FRONT AND BACK FRAMES

 Figure 3Many maintenance operations will either require or be greatly facilitated by separating the
front frame and mechanism of the breaker from the back frame or base, which consists of the current carrying parts of the breaker and their supporting structure. The procedure for this operation is as follows:

1. Remove the arc quenchers (see section on "Arc Quenchers").
2. Disconnect the two insulated connecting links (6), between the mechanism and the crossbar (10), by removing the tie bolt (7), and slipping the ends of the links off the ends of the shouldered pin, (5) Figure 5 in the mechanism.
3. If the breaker is a drawout type, with secondary disconnects, Figure 2, remove the secondary disconnect supporting bracket from the breaker back frame. Also remove any wiring bundle retainers that may be attached to the back frame.
4. Remove one elastic stop nut from each of two studs (3), which tie the upper ends of the mechanism frame to the back frame of the breaker.
5. Remove the two elastic stop nuts ( $9 / 16^{\prime \prime}$ Hex.) which fasten the wrap around portion of the front frame to the back frame. One of these is located on each side of the breaker, about $2 / 3$ of the distance down from the top edge of the back frame.
On drawout breakers for AKD Equipment, the bottom plate must be removed by first removing two \#8-36 screws located at the front of the bottom plate and then freeing the plate from the slots located in the bottom of the back frame.
6. The two frames are now disconnected. However, care should be exercised in separating them to avoid damage to the trip shaft arms and paddles. While the back frame is held steady, lift the front frame and mechanism up and out so that the trip paddles on the trip shaft clear the trip arms of the overload trip devices.

Reassembly of the two breaker halves is accomplished by following the procedure outlined in reverse order.

## LUBRICATION

In general, the circuit breaker requires very little lubrication. Bearing points and sliding surfaces should be lubricated very lightly at the regular inspection periods with a thin film of extreme temperature, high pressure, light grease, similar to G.E. Spect. No. D50H15 or RPM No. 5. Hardened grease and dirt should be removed from latch and bearing surfaces by the use of a safe cleaning solvent such as kerosene. Latch surfaces should be left clean and dry and not be lubricated.

## ALL EXCESS LUBRICANT SHOULD BE REMOVED WITH A CLEAN CLOTH IN ORDER TO AVOID ANY ACCUMULATION OF DIRT OR DUST.

At each maintenance period, all silver to silver friction points, such as primary disconnects, should be cleaned and given a fresh coat of G.E. Spec. No. D50H47 lubricant.

## TROUBLESHOOTING

The following table lists several typical symptoms of breaker malfunction, together with their causes and remedies. If, at any time, these symptoms are observed, their cause should be determined and the necessary corrective action should be taken.

| TROUBLE | Cause | REMEDY |
| :---: | :---: | :---: |
| Overheating AK-2/3 Breakers | Contacts not aligned <br> Contacts dirty, greasy or coated with dark film <br> Contacts badly burned or pitted <br> Current carrying surfaces dirty <br> Corrosive atmosphere <br> Insufficient bus or cable capacity <br> Bolts and muts at terminal connections not tight <br> Current in excess of breaker rating <br> Excessive ambient terlperature | Adfust contacts. <br> Clean contacts <br> Replace contacts <br> Clean suriaces of current carrying parts <br> Relocate or provide adequate enclosure <br> Increase capactty of bus or cable <br> Tishten, but do not exceed elastic limit of bolts or fittings. <br> Check breaker application or modify circult by decreasing load <br> Provide adequate ventulation |
| Fallure to trip AK-2 Bragkers | Trayel of tripping derice does not provide positive release of tripping latch <br> Worn or damaged trip unit pasts <br> Bind in overcurrent trip dovice | Re-adjust or replace tripping device and check mechanism latch adjustment <br> Replace trip unit <br> Replace overcurrent trip device |
| False Tripplag AK-2 Breakers | Overcurrent trip device pick up too low Overcurrent trip device tione setting too short Bind in overcurrent trip device | Check application of overcurrent trip device Check application of overcurrent trip device Replace overcurrent trip device |
| Failure to Close and Latch AK-2/3 Breakers | Birding in attachments proventing resotting of latch <br> Latch out of adjustment <br> Latch return epring too weak or broken <br> Hardened or gummy lubricant <br> Cloaing solemold burned out <br> Solenoid control device not functioning properly | Re-allign and adfust attachments Adjust latch <br> Replare spring <br> Clean bearing and latch surfaces <br> Replace solenoid coul <br> Re-adjust or replace device |
| False Tripping AK-3 Breakers | Captive Thump acrew on Power Sensor loose fall-ade circuitry reverts characteristic to minimum setting and madimum time delay <br> Tap aetting dial on Power Supply incorrectly set <br> External Ground Sensor Coll improperly connected | Tighten thumb screw on desired setting <br> Set dial to correspond with Power Sensor coll tap <br> Refer to Figure 22, page 29 for polarity and connections. Check continuity of shield and contuctors connecting the external Ground Sensor coil. |
| Fallure to Trip AK-3 Braakers | Loose or disconnected powar sensor disconnect pluss <br> Loose or broken power sensor coll tap connections | Tighten or reconnect disconnect plugs <br> Tighten or reconnect tap connections |

## BASIC BREAKER COMPONENTS

## DISCONNECTS

## PRIMARY DISCONNECTS

The primary disconnects are attached to the ends of the breaker studs on the rear side of the breaker base. Each disconnect assembly consists of two pair of opposed contact fingers. These are secured to the breaker stud by a bolt which passes through the assembly and the stud. When engaged with the stationary stud of the enclosure, the disconnect fingers exert a set amount of force against the stationary stud through the action of the compression springs. Retainers and spacers hold the contact fingers in correct alignment for engagement with the stud. The amount of force which the fingers exert against the stud is determined by degree to which the springs are compressed by the bolt and nut which hold the assembly together. This pressure is factory set between 60 and 70 pounds. If, for any reason, the disconnects must be taken apart, the position of the nut on the bolt should be carefully noted, so that in reassemblying, the original amount of compression can be restored by replacing the mut at its former position on the bolt.

## SECONDARY DISCONNECT, FIGURE 2.

The secondary disconnects serve as connections between breaker control circuit elements and external control circuits. They are used only on drawout type breakers. A terminal board serves the same purpose on stationary mounted and general purpose enclosure mounted breakers. The secondary disconnects allow removal of the breaker without the necessity of having to detach external connections.

The movable part of the secondary disconnect consists of an insulating body which holds a conducting spring loaded plunger to which a flexible lead is attached. As the breaker moves into its enclosure, the plunger is depressed by sliding onto the stationary disconnects of the enclosure.

## REPLACEMENT OF MOVABLE SECONDARY DIS-

 CONNECTS1. Unfasten disconnect body from breaker back frame.
2. Open tabs which hold wires on inner side.
3. Pull contact tip loose from hollow tube.
4. Remove contact tip by. cutting wire at its base.
5. Push wire through hollow tube of new disconnect assembly.
6. Strip insulation off end of wire to about $1 / 4$ of an inch from end.
7. Place new contact tip on end of wire and crimp.
8. Pull wire through hollow tube until contact tip fits snugly against end of hollow tube.
9. Crimp tab on other side of assembly to hold wire in place.
10. Any hollow tubes which are not used should be pushed into the disconnect body and held in that position by placing fibre spacers over inner ends of tubes and spreading tabs.


Figure 2. (8017973) Movable Secondary Disconnects
11. When all wires have been connected, refasten the body of the assembly to the breaker back irame.

## ARC QUENCHER

The arc quencher is an integral riveted assembly composed of two ceramic side plates, a series of steel plates, and a muffler. The assembly is covered by a wrap around of insulating material which inhibits any sidewise emission of gases. The steel plates are held in position and supported by the ceramic sides which are grooved vertically to provide recesses for the vertical edges of the steel plates. The bottom edges of the latter form an inverted "V" along the path of the arc that may be drawn between the breaker contacts during interruption. The steel plates have the effect of breaking up the arc, and cooling it and the gases that result from interiuption. The entire assembly provides a "chimney" effect which directs the hot, ionized gases upwards through the steel plates and mufflers and allows their safe and controlled escape at a cooler temperature.

The muffler at the top of the assembly is a serpentine shaped strip of perforated, copper plated steel. It is important that the perforations of the muffler be kept open, since their closure could tend to prevent the escape of the gases along the desired path. At the regular maintenance inspection, it would be well to check their condition and open any of the perforations that appear to be clogged.

If any very extensive burning or corrosion is noted in the arc quencher, it should be replaced. Replacement is also indicated if any breaks or cracks are noted in the ceramic material.

## REPLACEMENT

Removal of the arc quencher is simply a matter of lifting the assembly up and out, after the steel retainer across the front of the arc quenchers has been removed. The upper edge of the steel arc runner, fastened to the back plate of the breaker, fits into a recess in the back portion of the arc quencher which locates it in its proper position upon replacement. Make sure the steel retainer is replaced and fastened firmly to its mounting studs after the arc quenchers have been replaced.

## BREAKER CONTACT STRUCTURE

The copper current carrying parts of the breaker are all mounted on a common base of insulating material made of polyester glass mat. The copper of each pole consist of an upper stud and pivot, stationary contacts, two movable contact arms, a movable contact pivot, and the lower stud.

The upper stud branches into two pivot surfaces on its inner end on the forward or front side of the breaker base. Each of these convex pivot
surfaces mates with the concave pivot surface on the rear side of the stationary contacts. Each of the stationary contacts pivot in a horizontal plane approximately at their mid-points. The end of the contact opposite to the contact tip end is formed into the shape of a small hook. A tension spring engages this hook and provides the necessary contact pressure at the pivot and also at the point of contact with the movable contact arm. When the breaker contacts open, a projection on the contact tip end of the stationary contact bears against a stop pin restricting the movement of the stationary contact. This arrangement results in a continual high force existing between the mating pivot surfaces.

The movable contact arms pivot in $a$ vertical plane, each making contact with a pair of stationary contacts, and thus providing four low resistant parallel paths of current for each breaker pole. The movable contacts rotate about a burnished, silver plated, copper pin which, in turn, is held by a pivot support. Each side of the plvot support bears against the lower, outer surface of the contact arm and supplies a second low resistance path through the pivot. A "U" shaped spring clip made of silver plated conducting material provides an additional current path and protects the other contact surfaces of the pivot against pitting when in motion. It also contributes to the force tending to increase the contact pressure between the lower ends of the movable contacts and the pivot support.

The movable contact pivot support is mounted securely to the breaker base. If, as is normally the case, the pole is equipped with an overcurrent trip device, one of the terminals of the series coil of the trip unit is fastened to the lower end of the pivot support. The other terminal of the coil fastens to the lower stud.

## CONTACT ADJUSTMENTS

The only adjustment to be made on the breaker contacts is that of contact wipe. This may be described as the distance the movable and stationary move while they are touching one another in the process of breaker closing. The amount of contact wipe can be measured by comparing the position of the front surface of the stationary contact when the breaker is open to its position when the breaker is closed, in reference to some absolutely stationary part of the breaker. The most convenient stationary part of the breaker to use as a reference point is the steel arc runner above and behind the stationary contacts.

The amount of wipe the contacts should have is nominally $1 / 8$ of an inch. A plus or minus tolerance of $1 / 32$ of an inch is allowed.

The means of adjusting contact wipe is provided by an eccentric pin which passes through the center of the movable contact assembly. Each end of this pin has a free, projecting, hexagon
chaped section which is easily accessible to a all, open end, $1 / 4$ inch wrench. Two cantilever _rrings, which bear on each end against a portion of the hexagon section of the pin, lock the adjusting pin in place and provide index stops for the process of adjustment. The right hand hexagon shaped end of the pin is numbered from 1 to 6 , which provides a reference for making wipe adjustments.

When contacts are to be adjusted, the recommended procedure is as follows:

1. With the breaker in the open position and using the numbers on the right end of each adjusting pin as a reference, set each pin in the same position. In many cases, the number 3 is a good beginning point. The proper view of the number on the adjusting pin is obtained by viewing the breaker from the front and the adjusting pin from approximately a 15 degree angle with respect to the movable contacts. Note that the numbers on the pin are not in numerical sequence as the pin is rotated.
2. By measurement, establish the position of the front surfaces of the stationary contacts with reference to the steel arc runners above and behind the contacts.
3. Close the breaker, and establish the amount of wipe by again measuring as in step two, and comparing the measurements with those taken with the breaker open.
4. If any set of contacts lead or lag the others, open the breaker and advance or retard the adjusting pin to the next higher or lower number. Moving the adjusting pin to a higher number will increase the contact wipe and moving to a lower number will decrease the contact wipe.

NOTE: No attempt should be made to move the adjusting pin when the breaker is closed. Besides being more difficult, the additional force required to move the pin will tend to round off the flats of the hex section of the pin.
5. When all the contacts have the recommended wipe of $3 / 32$ to $5 / 32$ of an inch, the contact adjustments are complete.

## CONTACT REPLACEMENT

## Figure 3

The normal situation that will exist in the matter of contact replacement will call for replacement of all the movable and stationary contacts at the same time. This will be the case
where long use of the breaker in service has resulted in extensive wear or erosion of the - Alver alloy contact tips. A commonly used Tule of thumb" is that contact replacement is indicated if less than one-half of the original thickness ( $1 / 8$ of an inch) of the contact tip material remains.

## GENERAL PREPARATION

1. Remove arc quencher retainer (1), Figure 5 by loosening the two captured nuts with a 7/16" wrench.
2. Lift off the three arc quenchers.
3. Remove the U shaped insulation (5) Figure 3 from each pole by lifting it and disengaging the rivet heads thru the keyholed slots in the insulation.
4. As an aid to future reassembly of the movable contacts, note the position of all stationary insulation barriers with respect to barriers mounted on the cross bar.

## REMOVAL OF MOVABLE CONTACTS

(18) Figure 3.

1. Screw the threaded end of the steel rod lightly into pivot pin (11) on the right pole.
2. With a pair of long nosed pliers, unhook safety pin type spring clip (9) and extract pin (11) and remove spring clip (9).
3. Grasp movable contact assembly and remove it from its seat on the cross bar.
4. Repeat procedure 1, 2, and 3 above on the left pole.
5. Move the cross bar downward to disengage it from the contact wipe adjusting pin (15) on the center pole, then move the cross bar toward the front of the breaker.
6. Remove the split pin retaining the center pole pivot pin.
7. Remove the pivot pin and movable contact assembly.

## REMOVAL OF STATIONARY CONTACTS

(21) Figure 3.

1. Slip the blade of a heavy screw driver between the two upper contacts and force the contacts toward their pivot point sufficiently far to disengage the contact stop surface from the pin.
2. The contact can then be removed by disengaging the end of the contact from its spring.
3. The two lower contacts can be similarily removed.

REPLACEMENT OF STATIONARY CONTACTS
(21) Figure 3.

1. Coat the contact pivot area only of each of the four contacts with a thin coat of D50H47 grease. Use only D50H47 grease.
2. Note the difference between the two types of
stationary contacts and be sure to locate them in the breaker with the upper and lower contacts having their stop projecting surfaces as shown in the section AA, Figure 3. The upper left and lower right contacts are identical as are the lower left and upper right contacts.
3. By placing the hook on the end of the contact through the loop of the contact spring, the contact can be pushed toward the pivot surface and slipped behind the stop pin. Install all stationary contacts in all poles.

## REPLACEMENT OF MOVABLE CONTACTS

(18) Figure 3.

1. Coat the pivot area only of the new movable contacts with a thin coat of D50H47 grease.
2. Assemble the center pole movable contacts, align the pivot pin holes with the bullet nosed rod, and install the pivot pin and split pin.
3. Move the cross bar assembly into position and insert the eccentric contact wipe adjust-


Figure 3. (549D409-2) Contact Assembly

1. Breaker Base
2. Insulation
3. Insulated Stud
4. Upper Stud Barrier
5. Insulation
6. Links (Insulated)
7. Tie Bolt
8. Spring
9. Spring Clip (Retainer)
10. Cross Bar
11. Pivot Pin
12. Lower Stud
13. Contact Pivot Support
14. Spring
15. Contact Wipe Adjustment Pin
16. Screw
17. Upper Stud \& Arc Runner
18. Movable Contact
19. Spring
20. Nut
21. Stationary Contacts
ment pin (15) on the center pole into position. Be sure the stationary insulation barriers are correctly located.
22. Align the cross bar with the left and right pole pivot supports and install the left and right pole movable contacts. Use the bullet nosed steel pin to aid in aligning the holes in the cross bar, the contacts and the pivot supports.
23. Install the left and right pole pivot pins while threading them through the spring clips and lock the spring clips (9). Be sure the pivot pins are fully inserted.
24. Adjust the contact wipe to $1 / 8^{\prime \prime} \pm 1 / 32^{\prime \prime}$ by adjusting the eccentric contact wipe adjusting pin (15). The breaker must be open to adjust the wipe. In the event acceptable wipe cannot be obtained by moving the contact wipe adjusting pin (15), from the movable contact forward or bachward as necessary to bring the wipe within the range of the contact wipe adjusting pin (15). Do not exceed the recommended settings for wipe; otherwise the breaker may not close completely. When viewed from the top with the breaker closed, the movable contact should be centrally located with respect to the stationary contacts. If the movable contacts are not centrally located as shown in section CC, form the movable contacts until they are nominally centered.
If the moving contacts are not centered with $1 / 8^{\prime \prime}$ separation when closed against the fixed contacts, they should be bent laterally (after opening the breaker contacts). To do this without squeezing the two movable contact arms together, a $1 / 8^{\prime \prime}$ spacer plate should be inserted between them; then the pair can be grasped with pliers and bent in the desired direction for centering.
New contacts should be adjustable using eccentric numbers 1,2 , or 3 . These numbers are the ones visible when viewing the breaker from the front, not from above. (The higher numbers should be reserved for tightening at future maintenance readjustments after wear.) Also, if higher numbers are used, where adequate wipe is obtainable at settings 1,2 , or 3 , it is possible that the stationary contacts will bottom, producing excessive back force on the breaker closing mechanism so that the toggle link will not pass center. As a result.the breaker will not complete its stroke, and inadequate pressure and wipe will result; burn-up of contacts from just load current will follow.

If the required wipe of new contacts cannot be obtained with eccentric number of 3 or lower, bending of the contact arms toward the closed position is required. This should be done individually, using an $8^{\prime \prime}$ Crescent or $1 / 2-5 / 8^{\prime \prime}$ tapered open end wrench to grasp the contact and a $10^{\prime \prime}$ Crescent or the $1^{\prime \prime}-1-1 / 8^{\prime \prime}$ tapered


Figure 4. (8039851) AK-2-25 Back Frame - Location of Crossbar and Pole Shields

1. Stationary Contacts
2. Movable Contacts
3. Upper Stud Asbestos Shield
4. Crossbar Plastic End Shield
5. Crossbar Assembly
6. Crossbar Asbestos Inner Shield
7. Lower Stud Asbestos Shield
open-end wrench to grasp the pivot portion of the arm. The soft copper arm will bend with little difficulty. Both arms should be bent identically.
Operate breaker several times, and recheck wipe to make sure bending of movable arms did not occur in these operations.
8. Operate the breaker manually several times to assure proper functioning occurs, then replace the U shaped insulation (5) Figure 3 and arc quenchers. When replacing the arc quenchers be sure the quencher is seated downward completely and that the quencher clamp covers the knobs protruding through the arc quencher insulation.

## CONTACT SPRINGS

(19) Figure 3

A minimum force of 5 lbs and a maximum force of 9 lbs. should be required to begin movement of a single stationary contact from the open position towards the closed position. This may be checked by using a push scale applied at the point at which the movable contact touches the stationary contact. If these pressures are not obtained or if the spring is damaged, replacement is required.

In order to replace the contact spring the upper stud (17) must be removed. The hardware which fastens the stud to the breaker base consists of two screws (16), and nut (20). When These are removed, the stud may be withdrawn from the base in a forward direction. After the stud has been removed, it is a simple matter to disconnect the two ends of the spring (19) and replace it with a new one.

## MECHANISM

The breaker mechanism is a spring actuated, over-center toggle type of mechanism. As the closing force is applied, either by movement of the operating handle or the closing solenoid armature, energy is stored in the operating springs. After the springs have gone over center, movement of the output crank of the mechanism is still blocked for a time by a cam arrangement. As the springs are further extended, the blocking cam moves away from the output crank, and the springs are allowed to discharge part of their stored energy, closing the breaker contacts.

This assures a fast-snapping closing action regardless of the speed at which the closing handle is operated.

The breaker mechanism is tripped by the displacement of the trip latch (7), Figure 6. Looking at the breaker from the right hand side as in Figure 5, the tripping movement of the latch is counter-clockwise. Operation of any of the automatic trip devices or the trip push button causes the latch to move in the tripping direction. When the latch moves off the trip latch roller (7), the remaining force in the operating spring causes the mechanism toggle to collapse, resulting in the opening of the breaker contacts.

## ADJUSTMENT

Since all the mechanism adjustments are carefully set by experienced factory personnel after assembly at the factory, it should normally not be necessary to make any adjustments in the field. At the time of installation, and also in the course of a maintenance inspection, if the breaker functions properly through several repeated operations, it is best to assume that adjustments are satisfactory.

If the breaker mechanism does not function properly, it is best to first perform the available remedial measures listed in the "Trouble Shooting" chart of these instructions. One of the remedies
listed is that of proper mechanism latch engagement, the amount of engagement between the latch (7) and latch roller (5), Figure 6. This is the only adjustment that is required on the breaker mechanism, and proper latch engagement is obtained in the following manner:
(NOTE - Before making latch adjustments, check to make sure that the buffer paddle which stops against the end of the latch adjustment screw is rigidly fastened to the trip shaft. Hold the trip shaft (8), Figure 5, steady and attempt to move the buffer paddle. If any relative movement between the two is noted, tighten the fasteners holding the buffer paddle to the trip shaft.)

Latch Adjustment - Manual Breaker

1. Locate the latch adjustment screw on the lower, outer side of the right-hand mechanism side frame. This screw is threaded through a nylon insert locknut which, in turn, is welded to a projecting bracket on the side frame.
2. Rotate the closing handle 90 degrees counterclockwise, setting the closing mechanism in the reset position. Turn the adjusting screw into the locknut until the closing mechanism trips open, the closing handle returning to its normal vertical position. NOTE: KEEP HANDS CLEAR OF THE CLOSING HANDLE WHEN MAKING THIS ADJUSTMENT.
3. Withdraw the adjusting screw from the locknut $1 / 4$ turn at a time, attempting to close the breaker after each $1 / 4$ turn, and observing whether the contacts move toward closing before tripping occurs. If the contacts move before tripping occurs, you have established the position of the adjusting screw where the latch and latch roller begin to engage. In some cases, it may be necessary to turn the adjusting screw less than $1 / 4$ turn in order to establish the position where the contacts begin to move before tripping occurs. When this position is established, note the position of the slot in the head of the adjusting screw.
4. Withdraw the adjusting screw three and onehalf turns from the position noted in step 3. This sets the proper amount of latch engagement.

## Latch Adjustment - Electrical Breaker

1. Locate the latch adjustment screw on the lower, outer side of the right mechanism side frame. This screw is threaded through a nylon insert locknut which, in turn, is welded to a projecting bracket on the side frame.
2. With the breaker in the open position turn the adjusting screw into the locknut one complete turn at a time, closing the breaker after each complete turn of the adjusting screw, until
the breaker will not close. Use the maintenance closing handle whenever closing or attempting to close the breaker during this entire operation.
3. Withdraw the adjusting screw from the locknut $1 / 4$ turn at a time, attempting to close the breaker after each $1 / 4$ turn, and observing whether the contacts move toward closing before tripping occurs. If the contacts move toward closing before tripping occurs, you have established the position of the adjusting screw
where the latch and latch roller begin to engage. In some cases, it may be necessary to turn the adjusting screw less than $1 / 4$ turn to establish the position where the contacts move before tripping occurs. When this position is established, note the position of the slot in the head of the adjusting screw.
4. Withdraw the adjusting screw three and onehalf turns from the position noted in step 3. This sets the proper amount of latch engagement.


Figure 5. (8024457) Cut Away Model of Electrically Operated AK-2 Breaker

1. Arc Quencher Retainer
2. Cut off Switch
3. Cut off Switch Actuator
4. Spring Carrier
5. Shoulder Pin
6. Connecting Link
7. Trip Latch Roller
8. Trip Shaft

8A. Front Escutcheon
9. Closing Solenoid

9A. Location of Slots for Maintenance Handle
10. Closing Solenoid Armature
11. Cover Retainer of Overload Device
12. Lower Stud
13. Socket Head Screws
14. Upper Stud
15. Stationary Contacts and Springs
16. Arc Runner

Should the mechanism continue to function improperly after the proper latch engagement has been set and the corrective measures listed in the "Trouble Shooting" chart carried out, it is generally recommended that no attempt be made to repair the mechanism interior but that a replacement mechanism assembly be obtained from the factory.

## REPLACEMENT

1. If the breaker is electrically operated, remove the front escutcheon by taking four screws from flange. If the breaker is a drawout type, two small round head screws must also be removed from the bottom edge of the escutcheon. (For removal of front escutcheon from
manually operated breakers, see procedure described below.)
2. Remove arc quenchers (See "Arc Quencher").
3. Disconnect the two insulated connecting links between the mechanism and the contacts as in step 2 of the procedure for "Separation of Front and Back Frames".
4. Remove the two elastic stop nuts, which fasten the upper extensions of mechanism frame to studs connecting with rear frame.
5. Remove four screws which fasten the bottom of the mechanism frame to the horizontal cross member of the front frame.


Figure 6. (8024516) Cut Away Model of Manually Operated AK-2 Breaker

1. Arc Quencher Muffler
2. Ceramic Side Plates
3. Steel Plates
4. Fixed Centers in Mechanism
5. Latch Roller
6. Escutcheon
7. Trip Latch
8. Handle Return Spring
9. Overload Device
10. Series Coil of Overload Device
11. Trip Arm of Overload Device
12. Trip Paddle
13. Movable Contact Pivot Support
14. Crossbar
15. Movable Contact Pivot
16. Contact Wipe Adjustment Pin
17. Movable Contact
18. Moulded Compound Bar
19. Steel Back Plate
20. If the breaker is mamually operated, and has no auxiliary switch, it is now free to be lifted clear of the breaker. If it has an auxiliary switch, this may be disconnected from the mechanism as described under "Auxiliary Switch - Replacement, elsewhere in these instructions.
21. If the breaker is electrically operated, it will be necessary to disconnect the mechanism from the solenoid armature. In order to do this, raise the mechanism as far as the travel of the armature will permit and remove the screw which binds together the two extensions of the armature. After this is removed, the armature extensions must be spread apart to release them from the link connecting with the mechanism. This can be done by threading a \#10-32 screw at least 1-3/4 inches long into the top hole of the armature extension. This hole is just above the one from which the binding screw has been removed. As the end of the screw butts against the far extension, the two extensions will be spread open, releasing the mechanism link.
22. The replacement mechanism may be installed by reversing the order of procedure for disassembly. After reassembly, check the operation of the breaker and, if necessary, adjust the latch engagement.

## emoval of front escutcheon <br> JF MANUAL BREAKERS

1. Remove set screw fastening the plastic handle to steel operating shaft and remove the operating
2. Open and remove annealed (soft) retainer and two flat washers from shaft.
3. Remove four screws from flange of escutcheon if the breaker is a drawout type, two small round head screws must also be removedfrom the bottom edge of the escutcheon.
4. Push steel operating shaft through escutcheon bushing.
5. Remove handle reset spring (8) Figure 6, and escutcheon is free of breaker.
6. Handle and escutcheon assembly can be assembled most easily by exactly reversing the procedure for disassembly. In replacing the escutcheon it may be necessary to use pliers to pull the operating shaft fully into the escutcheon in order to have space enough to replace the flat washers and the soft retainer. The latter may be closed on its groove in the shaft by ordinary gas pliers. After replacement, check operation of breaker.

## AUXILIARY SWITCH

The auxiliary switch is mounted on the left side of the operating mechanism frame. Its operating shaft is linked to the output crank of the breaker mechanism. Through a cam arrangement, the operating shaft of the switch controls the open and closed positions of the individual contact pairs. Each stage of the switch, which is usually two-stage or five-stage, contains one " $a$ " and one " $b$ " set of contacts. An "a" pair of contacts is always in the same position as the main breaker contacts. That is, open when the breaker contacts are open, and closed when the breaker contacts are closed. Just the oposite is true of the " b " contacts. The terminals of the switch are covered by a sheet of insulating material held in place by two screws fastened along its left edge. When this is removed, the terminals are exposed. The upper pairs of terminals are those which connect to "a" switches. The lower terminals connect to " b " switches.

## REPLACEMENT

1. Remove auxiliary switch cover.
2. Disconnect leads to switch termin.
3. Remove two screws which fasten $\times \cdots$. side of mechanism frame.
4. Remove switch by moving towards lef:.
5. Before mounting replacement switch, turn the crank end of the switch operating shaft in position to engage the hole in the link connecting with with the breaker mechanism. Be sure the bearing washer is in place between the mechanism link and the switch operating shaft.
6. Complete mounting by following disassembly steps in reverse order.

## ELECTRICAL CONTROL COMPONENTS

These consist of the following:

1. Closing solenoid
2. "X" contactor (relay)
3. "Y" permissive relay
4. Cut-off switch
5. Closing switch
6. Shunt-trip device

The last two of these components may or may not be present in the control arrangement.

## CLOSING SOLENOID

The closing solenoid consists of a magnet, armature and coil. This assembly is located directly beneath the breaker mechanism to which it is connected by a link which ties the upper end of the armature to the spring carrier of the mechanism. (See Figure 5.)

When voltage is applied to the coil, the magnetic force generated pulls the armature up into the coil and magnet assembly. This, in turn, rotates the spring carrier about its pivot, extending the mechanism spring and causing its line of action to move "over center", resulting in a closing operation.

## REPLACEMENT

The only replacement operation that might conceivably be required on this assembly is that of the solenoid coil. To replace this, proceed as follows:

1. Remove escutcheon by unfastening four flat head screws in flange.
2. Remove closing switch. (See "Closing switch".)
3. Cut off or disconnect the coil leads.
4. Remove four screws which fasten lower section of magnet to upper section.
5. Allow lower section of magnet and coil to slide downward until clear of armature.
6. Reassemble with new coil by reversing order of procedure.

## "X" CONTACTOR

The " $X$ " contactor is a heavy-duty relay which performs the function of closing the circuit of the breaker solenoid during electrical operations. Three of the four sets of contact of the device are arranged in series to minimize the duty required of any one contact. As explained under "Operation", the fourth contact is used to "seal-in" the "X" coil.

The " X " contactor is located on the right beneath the horizontal front frame member. It is mounted on three studs which fasten it to a mounting bracket which is suspended from the frame. Rubber bushings on the mounting studs provide anti-vibration and anti-shock protection for the relay. The relay contacts and their terminals are covered by a molded piece of insulation which fits over spring clips that hold the cover in place.

## REPLACEMENT

Removal of the complete device is accomplished by removing the cover, disconnecting the leads from the terminals, and removing the nuts from the three mounting studs. If the replacement unit includes the mounting bracket, the relay
need not be removed from the old bracket. This can be taken off the breaker simply by removing the two screws which fasten it to the breaker frame. If the breaker is a drawout type, the supporting bracket of the "Y'" relay may be temporarily displaced to provide access to the screws.

Since the expendable parts of the "X" contactor are the contacts and the coil, ease of replacement of these parts has been designed into the relay. Methods of procedure are as follows:

## Contacts

1. Remove relay cover.
2. Remove terminal binding screw of stationary contact to be replaced.
3. Lightly pinch with pliers (pointed end) the split section of the contact which enters the hole in the compound body of the device and lift out the stationary contact.
4. With the fingers, pull forward on the spring guide of the movable contact, compressing the contact spring as far as possible.
5. With the spring thus held, grip the end of the contact strip with pointed pliers, turn it through 90 degrees on its long axis, and withdraw it.
6. Replace new contacts by reversing the procedure.
Coil
7. Remove relay cover.
8. Turn the two retaining spring clips on the ends of the device through 90 degrees about their pivots.
9. Pull out the two halves of the body of the device which carry the stationary contacts. When these are clear of the frame, the armature and movable contact assembly will move aside, exposing the coil.
10. Remove the terminal screws of the coil and pull it free of its retaining spring clips.
11. Place new coil on pole piece inside of the spring clips and fasten terminals to leads.
12. Just start the replacement of one of the compound blocks which hold the stationary contacts into its groove in the frame.
13. Position the armature and movable contact assembly to allow the entrance of the second stationary contact block.
14. When these parts are all properly aligned, with the stationary contacts under the movable contacts, push them into their guiding grooves in the frame until they bottom.
15. Rotate the retaining spring clips to the locked position, making sure that each clip is in its proper recess, and replace the device cover.

## "Y" RELAY

As described under "Operation", the "Y" relay is a permissive relay which limits to one the number of breaker closures possible on one closing signal.

On drawout breakers, the "Y" relay mounting bracket is fastened to the right hand side member of the breaker frame by two mounting screws. On terminal board breakers, it is fastened to the rear side of the terminal board support. The relay itself is fastened to an intermediate bracket which is detachable from the main support. The junctures between the relay and the intermediate bracket and between the two brackets are rubber cushioned against vibration and shock.

## REPLACEMENT

If replacement of the " Y " relay becomes necessary, it may be detached from its supporting brackets by removal of the fastening hardware. The leads to the relay should be cut off as closely as possible to the soldered connections so that enough wire will remain for connection to the new relay. Sufficient original wire is allowed for this purpose.

After the old relay has been removed, the wire leads to the relay should be stripped of insulation to about $1 / 4$ of an inch from the ends. A good mechanical connection should be made before soldering.

After all connections are completed, the relay may should again be mounted to the breaker by means of its supporting brackets and hardware.

After replacement has been completed, the relay may be checked electrically in the following manner:

1. Apply closing voltage to terminal board or secondary disconnects.
2. Push button of closing switch and hold closed.
3. Continuing to hold push button in closed position, manually trip the breaker open.
4. If the breaker stays open, and makes no attempt to close, the " Y " relay is functioning properly.
5. While releasing the close button, observe the " Y " relay. It should open as the closing switch is released.


Figure 7. (695C162) Cut-Off Switch

1. Screw
2. Washer
3. Spring
4. Movable Contact Assembly
5. Spring
6. Actuator
7. Pivot Pin
8. Contact (BB)
9. Contact (AA)
10. Support

## CUT-OFF SWITCH

## Figure 7.

As explained under "Operation", the function of the cuf-off switch is to de-energize the " X " contactor' coil and energize the "Y" relay coil as the breaker mechanism moves from the opened to the closed position.

The switch is operated by the movement of a mechanism link against the switch actuator (6). This causes the actuator and movable contact assembly (4) to rotate counterclockwise about pin (7), opening the "bb" contacts (8) and closing the "aa" contacts at (9). Overtravel of the actuator (6) beyond the point of making contact at (9) is absorbed by spring (5) which couples the movable contact (4) to the actuator. Spring (3) resets the switch after the breaker contacts open and the breaker mechanism resets.

The point at which the cutoff switch operates during the breaker closing cycle is after the spring charged mechanism has been driven over-center. This assures that the cutoff switch cannot operate too early in the breaker closing cycle, thus the $X$ and $Y$ relays are de-energized and energized, respectively, at the proper time and the circuits anti-pump feature is maintained. When the closing mechanism is driven over-center, the force of the previously charged closing springs is released, closing the breaker.

## REPLACEMENT

The cut-off switch is located above the breaker mechanism. It is fitted between the upper portions of the steel side plates that make up the mechanism frame. A raised horizontal ridge on each side of the molded body of the switch fits into a corresponding groove in each of the steel side plates. A round head screw on each side fastens the $s$ witch and side plate together. Replacement of the switch is accomplished by the following procedure:

1. Remove the cover on the top of the switch by taking out the two screws which hold it in place.
2. After taking careful note of the connection arrangements, disconnect the leads from the switch terminals.
3. Remove the two screws, one on each side, which fasten the switch to the mechanism side plates. Note that the one on the right hand side also holds a wiring cleat and spacer which serves to hold the wires clear of the link connecting the mechanism and the breaker position indicator.
4. Remove the front escutcheonfrom the breaker.
5. Slide the cut-off switch out from between the steel side plates by pulling straight forward.
6. Mount the replacement switch by reversing the order of procedure.

## CLOSING SWITCH <br> Figure 8.

The closing switch is mounted on the upper flange of the closing solenoid coil. A hole in the escutcheon (3) permits access to the switch button (4). When the button is pressed, movable contact (5) deflects and impinges upon stationary contact
(2). This energizes the "X" relay coil which seals itself in, and, in turn, energizes the closing solenoid.

## REPLACEMENT

1. Remove escutcheon (3).
2. Disconnect leads from switch terminals.
3. Deflect the left end of hinge (7) to the left so that the movable contact (5) may be disengaged from the switch assembly.
4. Removal of the two screws (10) from speednuts (9) completes the disassembly of the switch.
5. Reassembly with new parts is a matter of reversing the described procecture. In reassembling, be sure the tab on the left end of hinge (7) is bent to the right far enough to avoid any possibility that movable contact (5) might become free of the assembly.

## SHUNT TRIP DEVICE

## Figure 9.

The shunt trip device is mounted underneath the horizontal cross frame member, just to the left of the front escutcheon. It is composed of a magnet, coil and armature. The armature has an extended arm or striker (11) which bears against the trip paddle (12) on the trip shaft when the coil (8) is energized. This displaces the trip latch in the breaker mechanism, opening the breaker contacts.

The trip device is generally activated by a remote switch or relay which closes the shunt trip coil circuit.

In order to avoid unnecessary heating of the coil of the device, an auxiliary switch " $a$ " contact is wired in series with the coil. This prevents the energization of the coil if the breaker is open.

## REPLACEMENT

The entire shunt trip device may be dismounted by disconnecting the coil leads and removing nuts (1). However, the only part of the device that might conceivably need replacement during the life of the breaker is the coil (8). This


Figure 8. (805B905) Closing Switch (Top View)

1. Insulation
2. Stationary Contact
3. Front Escutcheon
4. Push Button
5. Movable Contact
6. Spring
7. Hinge
8. Closing Solenoid
9. Speed Nut
10. Screw


Figure 9. (695C161) Shunt Trip Device

1. Nut
2. Frame
3. Spring
4. Rivet
5. Weight
6. Screws
7. Magnet
8. Coil
9. Clamp
10. Armature
11. Armature Arm
12. Trip Paddle
13. Mechanism Frame
14. Trip Shaft Clamp
may be replaced without removing the device from the breaker by proceeding as follows:
15. Disconnect leads of coil (8).
16. Remove two screws (6) which fasten magnet (7) and coil to the frame (2).
17. Having removed the magnet from the device, straighten the end of clamp (9).
18. Remove the coil from the magnet.
19. Install new coil, again forming end of clamp (9) as shown.
20. Reassemble to frame.

## 7. Connect coil leads.

## ADJUSTMENT

The only adjustment required on the shunt trip device is that which ensures positively that the breaker will trip when the device is activated. In order to be sure of this, armature arm (11) must travel from $1 / 32$ to $1 / 16$ of an inch beyond the point at which the breaker trips. A good method of checking this is to hold a $1 / 32$ nd shim between the magnet and armature at (10), and with the breaker closed, push upwards at (5), closing the armature against the magnet. If the breaker trips, there is sufficient overtravel. If adjustment is necessary, trip paddle (12) may be formed towards or away from armature arm (11).

## PROTECTIVE DEVICES

An AK-2/3 breaker may be equipped with the following protective devices:

1. Overcurrent trip (Magnetic) AK-2
2. Power Sensor Trip (Static) AK-3
3. Reverse Current Trip AK-2
4. Under Voltage Trip \& Lockout Device
5. Bell Alarm and/or Lockout device
6. Open Fuse lockout device.
7. AKD-5 Interlock AK-2A/AK-3A

OVERCURRENT TRIP DEVICE
(Magnetic)
The typical overcurrent trip device consists of a magnetic structure, a series current coil, and a pivoted armature.

When current flow through the series coil generates a magnetic field strong enough, the armature overcomes the restraining force of a calibration spring attached to it, and closes against the magnet. This trips the breaker by means of an extension on the armature which strikes against a trip paddle on the trip shaft.

Depending on the type of individual device, the movement of the armature may be delayed for a time by a timing device. If a relatively long time-delay (seconds or minutes) is desired, the velocity of armature movement is governed by a piston moving through an oil dashpot. If only a short-time delay (cycles or milli-seconds) is required, movement is controlled by an escapement gear and pallets arrangement.

An AK-2-15/25 breaker may be equipped with either the EC-2 or EC-1 overcurrent trip device. The majority of applications will require the use of the EC-2 device. The EC-1 device is normally
used when the short-time delay feature is required, or when the trip device is used to operate a special over-current alarm switch.

Most circuit breakers are equipped with series overcurrent trip devices either of the dual magnetic type (instantaneous and time delay tripping) or instantaneous alone. Breakers are designed to carry up to $100 \%$ of the continuous current rating of their trip devices. Any attempt to carry higher currents for a prolonged period will cause overheating and possible damage.

## EC-2 OVERCURRENT TRIP DEVICE

The Type EC-2 overcurrent tripping device is available in three forms:

1. Dual overcurrent trip, with long-time delay and high-set instantaneous tripping.
2. Low-set instantaneous tripping.
3. High-set instantaneous tripping.

The dual trip has adjustable long-time and instantaneous pick-up settings and adjustable time settings. Both forms of instantaneous trips have adjustable pick-up settings.
DUAL OVERCURRENT TRIP, WITH LONG-TIME DELAY AND HIGH-SET INSTANTANEOUS TRIPPING.

By means of the adjustment lnob (5), Figure 10, which can be manipulated by hand, the current pick-up point can be varied from 80 to 160 percent of the series coil rating. The indicator and a calibration plate (4), Figure 10, on the front of the case provide a means of indicating the pick-up point setting in terms of percentage of coil rating. The calibration plate is indexed at percentage settings of $80,100,120,140$ and 160.


Figure 10. (8024842) EC-2 Overcurrent Trip

1. Series Coil.
2. Trip Adjustment Screw
3. Opening for Time Adjustment
4. Pickup Indicator \& Calib. Plate
5. Pickup Adjustment Knob

The long-time delay tripping feature can be supplied with any one of three time-current characteristics which correspond to the NEMA standards maximum, intermediate and minimum longtime delay operating bands. These are identified as $1 \mathrm{~A}, 1 \mathrm{~B}$ and 1 C characteristics, respectively. Approximate tripping time for each of these, in the same order are 30,15 and 5 seconds at $600 \%$ of the pick-up value of current. (See time-current characteristic curves 286B201A, B, and C).

The tripping time may be varied within the limits shown on the characteristic curves by turning the time adjustment screw (5), Figure 11. Turning in a clockwise direction increases the tripping time;


Figure 11. (8024843) EC-2 Overcurrent Trip With Cover Removed.

1. Instantaneous Calibration Spring
2. Movable Nut (Index Pointer)
3. Time-Delay Calibration Spring
4. Instantaneous Pickup Adjustment Screw
5. Time-Delay Adjustment Screw
6. Oil Dashpot
7. Dashpot Arm
8. Connecting Link
9. Instantaneous Pickup Calibration Marks
counter-clockwise motion decreases it. The dashpot arm (7), Figure 11 is indexed at four points, maximum - $2 / 3-1 / 3$ - minimum from the left, as viewed in Figure 11. When the index mark on the connecting link (8), Figure 11, lines up with a mark on the dashpot arm, the approximate tripping time as shown by the characteristic curve is indicated. The 1 A and 1 B characteristic devices are shipped with this setting at the $2 / 3$ mark and the $1 C$ characteristic at the $1 / 3$ mark. The standard characteristic curves are plotted at the same settings.

Time values are inversely proportional to the effective length of the dashpot arm. Therefore, the linkage setting that gives the shortest time value is the one at which dimension " $A$ " Figure 11, is greatest. The time adjustment screw (5), Figure 11, may be turned by inserting a Phillips head screwdriver through the hole in the front of the case, but if it is desired to relate the linkage setting to the index marks on the linkage it will be necessary to remove the case. This may be done by removing the two mounting screws, one on each side of the case, which may be taken off without disturbing the trip unit itself.


1. Series Coil
2. Magnet
3. Pallet
4. Pinion
5. Escape Wheel
6. Driving Segment
7. S.T.D. Armature
8. S.T.D. Calibration Spring
9. Trip Arm
10. Trip Paddle
11. Trip Paddle Adjusting Screw
12. L.T.D. Armature
13. L.T.D. Calibration Spring
14. Instantaneous Trip Spring (High Set)
15. Spring Holder
16. Calibration Clamp Nut
17. Plunger
18. Cylinder (Dashpot)
19. Calibration Plate
20. Clamping Bracket

Figure 12. (695C189) EC-1 Type Overcurrent Trip Device

NOTE: Forcing the adjusting screw to either extreme position may cause binding of the device and should be avoided.

## INSTANTANEOUS LOW-SET TRIPPING

The low-set instantaneous pick-up point may be varied by the adjustment knob (5), Figure 10 . The calibration in this case usually ranges from $80 \%$ to $250 \%$ of the series coil rating, the calibration plate being indexed at values of $80 \%, 100 \%$, $200 \%$ and $250 \%$ of the rating.

## INSTANTANEOUS HIGH-SET TRIPPING

The high set instantaneous pick-up value may have one of the following three ranges: 4 to. 9 times coil rating; 6 to 12 times coil rating or 9 to 15 times coil rating. The pick-up setting may be varied by turning the instantaneous trip adjusting screw (4), Figure 11.

Three standard calibration marks will appear on the operating arm at (9), Figure 11, and the value of these calibration marks will be indicated
by stampings on the arm as follows:

| 4X |  | 6x |  | 9 X |
| :---: | :---: | :---: | :---: | :---: |
| 6 X | or | 9 x | or | 12X |
| 9 X |  | 12X |  | 15X |

At the factory, the pick-up point has been set at the nameplate value of the instantaneous trip current. (Usually expressed in times the ampere rating of the trip coil.) The variation in pick-up setting is accomplished by varying the tensile force on the instantaneous spring. Turning the adjustment screw changes the position of the movable nut (2), Figure 11, on the screw. The spring is anchored to this movable nut so that when the position of the nut is changed, there is a corresponding change in the spring load. As the spring is tightened, the pick-up point is increased. The top edge of the movable nut (2), Figure 11 serves as an index pointer and should be lined up with the center of the desired calibration mark, punched slots on operating arm, to obtain the proper instantaneous trip setting.

## EC-1 OVERCURRENT TRIP DEVICE

The EC-1 device can be provided with the following tripping combination

1. Long time delay, short time delay and instantanecus -tripping.
2. Long time and short time delay tripping only.
3. Long time delay and instantaneous tripping.
4. Short time delay and instantaneous tripping.
5. Short time delay tripping only.
6. Instantaneous tripping only.
a. Adjustable (Low set)

Non-adjustable (High set)
SHORT TIME DELAY TRIPPING, Figure 12.
The armature (7) is retained by calibrating spring (8). After the magnetic force, produced by an overcurrent condition, overcomes this restraining force, the armature movement is further retarded by an escapement mechanism which produces an inverse time delay characteristic. The mechanism is shown in the left side view of Figure -12.

The pickup for this device can be field set between limits having a ratio of $2-1 / 2$ to 1 in the range of 200 to $1000 \%$ of the coil rating.

## LONG TIME DELAY TRIPPING, Figure 12

The armature (12), is retained by the calibration spring (13). After the magnetic force, produced bs an overcurrent condition, overcomes this restraining force, the armature movement is further retarded by the flow of silicone oil in a dashpot, which produces an inverse time delay characteristic. The mechanism is shown in the right side view of Figure 12.

INSTANTANEOUS TRIPPING, Figure 12.
a. Adjustable instantaneous tripping takes place after the magnetic force produced by an overcurrent condition, overcomes the restraining force of the adjustable calibration spring (13).
b. Nonadjustable instantaneous tripping takes place after the magnetic force produced by an overcurrent condition overcomes the restraining force of a nonadjustable spring (14).

ADJUSTMENTS, EC-1 AND EC-2
In addition to the pick-up settings and timedelay adjustments already described, overcurrent trip devices must be adjusted for positive tripping. This adjustment is made at the factory on new breakers, but must be made in the field when the
breaker mechanism or the overcurrent trip devices have been replaced.

Positive tripping is achieved when adjustment screw (2), Figure 10, is in such a position that it will always carry the trip paddle on the trip shaft beyond the point of tripping the mechanism, when the armature closes against the magnet.

In order to make the adjustment, first unscrew trip screw (2), Figure 10, until it will not trip the breaker even though the armature is pushed against the magnet. . Then, holding the armature in the closed position, advance the screw until it just trips the breaker. After this point has been reached, advance the screw two additional full turns. This will give an overtravel of $1 / 16$ of an inch and will make sure that activation of the device will always trip the breaker.

Adjustment screw (2), Figure 10, can best be manipulated by an extended $1 / 4$ inch hex socket wrench.

In order to gain access to the adjustment screw on the center pole overload device, it will be necessary to remove the nameplate from the front escutcheon of the breaker. This will reveal a hole, centrally located in the escutcheon, by means of which the extended socket wrench can engage the adjustment screw.

## REPLACEMENT, E $\dot{C}-1$ and EC-2

Replacement of either the EC-1 or EC-2 overcurrent trip device is accomplished by the following procedure:

1. Separate the breaker's front and back frames as described in the section under "Maintenance".
2. Remove the steel clamps which fasten the cover of the device to the back of the breaker. NOTE: Pickup settings on the cover of each deviceare calibrated for the specific device. When replacing covers, replace on associated device.
3. Remove the $3 / 8$ inch hexagon headed bolts which fasten the coil of the overload device to the breaker copper.
4. Remove the round head screw which fastens the frame of the overload to the breaker base.
5. After reassembling breaker with new overload device, adjust for "positive trip" as described under "Adjustments" of this section.

## REVERSE CURRENT TRIP DEVICE

Figure 13.
The reverse current trip device sometimes used with d-c breakers will trip the breaker open if the direction of current flow is reversed.

This device is similar in appearance and is mounted in the same way as the overcurrent trip.


Figure 13. (286B209) Reverse Current Tripping Device

| 1. | Series Coil | TA. | Screws |
| ---: | :--- | ---: | :--- |
| 2. | Adjusting Nut | 8. | Counterweight |
| 2A. | Locking Nut | 9. | Stop Screw |
| aB. | Trip Rod | 10. | Mounting Screw |
| 3. | Spring | 11. | Screw (Lower Stud) |
| 4. | Potential Coil | 12. | Trip Crank |
| 5. | Calibration Nut | 13. | Screw (Lower Stud) |
| 6. | Armature | 14. | Trip Paddle |
| 7. | Pole Pieces |  |  |

The device consists of a series coil (1), with an iron core mounted between two pole pieces (7) and a potential coil connected across a constant source of voltage and mounted around a rotary type armatare (6). Calibration spring (3) determines the armature pick-up value when a reversal of current occurs.

As long as the flow of current through the breaker is in the normal direction, the magnetic flux of the series coil and the magnetic flux of the potential coil produce a torque which tends to rotate the armature counterclockwise. The calibration spring (3) also tends to rotate the armature in the same direction. This torque causes the
armature to rest against stop screw (9) attached to a bearing plate on the right side of the device.

If the current through the series coil (1) is reversed, armature (6) tends to move in a clockwise direction against the restraint of calibration spring (3). When the current reversal exceeds the calibreion setting, the armature will move in a clockwise direction. This causes trip rod (2B) to move upwards against trip paddle (14), tripping the breaker open.

## ADJUSTMENTS

The only adjustment to be made on the reverse current device is to make sure that the trip rod has a minimum overtravel of $1 / 32$ of an inch beyond the point of tripping the breaker. The only occasion this adjustment should have to be made is when an old device is being replaced by a new one.

The new device will be factory adjusted so that the top end of the trip rod (2B) will extend $1 / 2$ inch above the top of the device case, and no additional adjustments of the trip rod should be required. To obtain the proper $1 / 32$ of an inch overtravel, close the breaker and proceed as follows:

1. Loosen the locking nut (2A).
2. Manually lift the trip rod and vary the position of the adjusting nut (2), thus establishing the position of the adjusting nut where the breaker is just tripped. (NOTE - Be sure that all parts of the person are kept clear of moving breaker parts when tripping the breaker.
3. With this position of the adjusting nut established, advance the adjusting nut upward one and one half turns.
4. Tighten the locking nut and the minimum $1 / 32$ of an inch overtravel of the trip rod should be obtained.

## REPLACEMENT

Replacement of the ED-1 Reverse Current Device is accomplished by means of the same procedure as that followed in the case of the EC Overcurrent Trip Devices. There is, however, one additional step to the taken. This consists of disconnecting the leads of the potential coil. These are connected to a small two point terminal board mounted between two of the phases on the breaker base. After the new device has been installed, adjust for overtravel of the trip rod as described above.

## POWER SENSDR TAIP

## GENERAL DESCRIPTION

All AK-3 Type Air Circuit Breakers contain Power Sensor Overcurrent Trip Devices. The Power Sensor Trip functions with solid state components with the exception of the Magnetic Trip Device which is used to trip the breaker on signal from the Power Sensor Unit. The Power Sensor Overcurrent Trip Device consists of four major components.

1. The magnetic coils around the breaker conductors (Figure 14).
2. The Power Supply which provides both the tripping energy and the comparison basis for overcurrent detection (Figure 15).
3. The Power Sensor Unit with the various pickup settings and time delay selection taps (Figure 16).
4. The Magnetic Trip Device which physically trips the breaker (Figure 17).

In addition to the phase overcurrent protection, a ground fault sensing feature may be provided.

The Ground Sensing Device works on the principle that the instantaneous value of current flowing in the three conductors (or; in four conductors on four wire systems) must add to zero unless ground current is flowing. Therefore, if the electrical system is a four wire wye system with the neutral grounded at the transformer, the fourth sensing coil (Figure 18) must be included on the neutral conductor with its secondary combined with the secondaries of the three phase sensors which are mounted on the breaker. On Draw-out breakers, the output of the external neutral sensor must enter the breaker by a control disconnect (Figure 19) which is mounted low and on the centerline on the back of the breaker. Refer to Figure 20 for Power Sensor Cabling diagram.

## MAINTENANCE

When mal-functioning of the Power Sensor Trip is indicated the trouble should be traced to one or more of these four components involved, and that component should be replaced as a unit. The following steps should be taken to detect a malfunctioning unit.

Figure 14. (8041866) Magnetic Coils

NOTE: No adjustment to the taps controlling jick-up or timing should be made with the breaker zarrying current.

In the event the Power Sensor Device must be made non-operative to allow the breaker to continue carrying current without overcurrent protection, it is recommended that the leads to the tripping solenoid be removed to completely eliminate the possibility of the breaker tripping. Do not close breaker with power on the main contacts while the disconnect plug to the magnetic coils is disconnected

1. Check for the existence of overcurrent or ground fault conditions that may be causing


Fig. 15. (8039850) Power Supply

1. Rating Disc
2. Mounting Bracket
3. Male Disconnect Plug
4. Female Disconnect Plug
5. Terminal Block
6. Mounting Bracket


Figure 16. (8041864) Power Sensor Unit

1. Mounting Screw
2. Captive Thumb Screw
3. Name Plate
the breaker to trip as a proper response to these abnormal circuit conditions.
4. The possibility of the breaker being trip free by mechanical interferences along the trip shaft or inadvertent shunt trip operations should be positively eliminated before investigating the Power Sensor. Successful operations in the test position should be obtained before proceeding with the Power Sensor trouble shooting.
5. A PST-1 Power Sensor Test Kit must be available. (Figure 21). Check the Power Sensor Unit for correct function for each pick-up setting and one point on each time delay characteristic. Then check for the correct operation of each phase of the Power Supply Unit. This procedure is described in the instruction manual (GEK-7301) for the PST-1 Test Kit, and GEK-7309 Power Sensor Instructions. If the test results for this test do not deviate more than $10 \%$ from the published curves, proceed to step 4. If the deviation is more than $10 \%$ contact the factory for possible replacement of the Power Sensor Unit.
6. If the breaker is equipped with ground fault protection, determine whether the false tripping is the result of falsely answering an overcurrent trip or a ground trip signal. This may be determined by temporarily eliminating the ground trip signal by shorting out the ground signal points 1 and 5 at the ground signal terminal board on the back frame bottom of the breaker. Terminals 1 and 5 can be identified by the $0.15 U F$ capacitor connected


Figure 17. (8041863) Magnetic Trip Device

1. Name Plate
2. Mounting Bracket
3. Spring
4. Trip Arm
5. Adjusting Screw
6. Armature
7. Clamp
8. Coil
9. Magnet
between them. See drawing 138B2454 (Figure 22) with the breaker restored to service with the ground fault detector deactivated, establish whether there is false tripping due to overcurrent.

## FALSE TRIPPLNG CAUSED BY FAULTY GROUND FAULT DETECTION

If the breaker is equipped for four wire service (fourth C.T. remotely mounted, Figure 18) it is important that the shielding be effective by having continuity from the disconnect plug at the Power Sensor Unit to the external C.T. and further, that this shield be isolated from the signal conductors. It is also important that continuity exists through the ground signal circuit. Check these conditions as follows; referring to Figure 22.

1. Remove connection plug at Power Sensor Unit and check continuity between A and C (Signal). Letters are located on end of plug.
2. Check to be sure no continuity exists between $R$ and $A$, or between $R$ and $C$.
3. Temporarily connect jumper from shield to either terminal at remote C.T. and check to assure the shield is continuous from Power Sensor Plug to remote C.T. by checking for continuity between $R$ and $A$. If continuity does not now exist, shield is not continuous and point of discontinuity must be found. Check the control disconnect as the possible point of discontinuity. Remove jumper at remote C.T. after shield continuity is established.

Note the polarity marks on the ground sensors. Be sure the external ground C.T. senses the neutral current associated with the particular breaker load current and that polarity marks are in accordance with 138B2454 (Figure 22). If the breaker bottom studs connect to the source, the external C.T. must also have its polarity mark toward the source.


Figure 19. (8918380A) Control Disconnect Plug

1. Female Disconnect Plug
2. Terminal Board
3. Mounting Bracket
4. Terminal
5. External Ground Sensor Coil
6. White Polarity Dot


Figure 20. (0133C9017) Power Sensor Cabling Diagram


Figure 21. (8039962) Power Sensor Test Kit

## TESTING MAGNETIC COILS

After the PST-1 Test Kit has been used to determine the adequacy of performance of the Power Sensor Unit, it may be advisable or required to test the magnetic coils by the use of a hi-current Low voltage type test set. In this event, only one test per phase need be made. This test should be made at some convenient multiple of pick-up setting such as $300 \%$ for comparison with published time-current curves.

In the event the breaker is equipped with ground sensor, the ground sensor will cause tripping on single phase testing unless the signal is shorted at the terminal board (Figure 22). Jumper points 1 and 5 during overcurrent test.

The above considerations should indicate which of the four major components is faulty and in need of replacement.

## REPLACEMENT OF POWER SENSOR COMPONENTS

POWER SENSOR UNIT (Figure 16).

1. Loosen screw connecting the unit to the front frame.
2. Slide unit forward.
3. Remove control plug by alternately loosening the two retaining screws.
4. Replace in reverse order.

MAGNETIC TRIP DEVICE (Figure 17).

1. Remove trip solenoid wires from the terminal board on power supply.
2. Remove four screws holding power supply to breaker frame.
3. Pull power supply forward until restricted by wiring.
4. Remove two bolts holding trip device to breaker frame.
5. Lift out trip device.
6. Replace in reverse order.

POWER SUPPLY (Figure 15).

1. Remove magnetic trip wires from the terminal board on POWER SUPPLY
2. Remove four screws holding power supply to breaker frame.


Figure 22. (138B2454) Ground Fault Wiring Diagram


Figure 23. (286B209) Time-Current Characteristic - EC Devices


Figure 24. (109HL687) Time Curve
3. Remove four screws holding escutcheon to mechanism frame and remove escutcheon.
4. Disconnect control plug to power sensor coils and power sensor unit.
5. Remove cable clamps holding cabling in place.
6. Remove power supply unit with attached cabling.
7. Replace in reverse order.

SENSOR COILS (Figure 14).

1. Separate the breaker front and back frame as described in the section under "Maintenance".
2. Remove two screws holding sensor coil disconnect plug bracket to back frame.
3. Remove bolt holding resistor bracket to back frame.
4. Remove 2 screws holding capacitor bracket to back frame.


Figure 25. (109HL689) Time Curve
5. Unsolder three leads at ground disconnect and pull wire through hole in back frame. On stationary breakers with fourth wire ground disconnect, unsolder leads at external ground coil and pull wire through hole in back frame.
6. Remove primary disconnects per instructions under disconnects.
7. Remove three $3 / 8$ hexagon headed bolt connecting coils to breaker copper.
8. With the back frame in the vertical position, and supported, grasp the outside coils and lift coil assembly from back frame. When carrying or moving sensor coil assembly, always support the outside coils.

## SELECTIVE TRIPPING

Selective overcurrent tripping is the application of circuit breakers in series so that only the circuit breaker nearest the fault opens. Anyone or combination of two or more of the preceding over-current devices may be used in a selective system. The breaker having the shorter time setting and lower pickup will trip before the


A- 2SOV DE RELAY
$C_{6} . C_{4}, C_{5}, C_{6}, C_{7} \cdot .10 u f: 10 \%$ GVOWC
$C_{2}$-550мf 350 WVDC
C3. 1000 uf 200 WVDC
D. De $D_{1} D_{6}, D_{7}$ - INS 60 -600 ma e $30^{\circ} \mathrm{C}$
$R_{1}-15 \Omega 2 W: 5 \%$
$R_{2}$ * $1500 \Omega 5 \mathrm{w}: 5 \%$
$R_{3}-75 \Omega 5 \mathrm{~W}=5 \%$
$R_{4} R_{g} R_{6}, R_{9}-10 \Omega 1 / 2 \mathrm{~W}$
$R_{B}-2750 \Omega 20 \mathrm{~W}=5 \%$
RH-0.25.000 $\Omega 25 \mathrm{~W}$
Rg - 500 $\Omega$ 3W $25 \%$
breaker having the longer setting and higher pickup, provided the fault is on the part of the line protected by the breaker having the lower setting.

For the exact characteristics and setting of each breaker in a selective system, reference should be made to a coordination chart for the particular system. (Figures 23, 24, and 25)

## STATIC TIME DELAY <br> UNDERVOLTAGE TRIPPING DEVICE

The Static Time Delay Undervoltage Tripping Device consists of an undervoltage device mounted on the breaker, a static time delay box mounted separately from the breaker and a control power transformer which is also mounted separately from the breaker when the reference voltage is other than DC., 208 V AC or 230 V AC. Refer to wiring diagram 0102C3698 (Figure 26).

The voltage 208 V AC or $230 \mathrm{~V} A C$, to be monitored is connected to terminals \#1 and \#2 of the time delay box. The undervoltage device
on the breaker is always connected through either its secondary disconnects or terminal board, to terminals \#4 and \#5 of the time delay box.

The undervoltage device is set to pickup at approximately $80 \%$ of bus voltage and drop out between $30 \%$ and $60 \%$.

The undervoltage device coil circuit is continuously rated and will remain picked up as long as the voltage remains above the predetermined drop out voltage. The time delay is field adjustable between 1 and 5 seconds, it is factory set at the minimum setting, and once the time delay is established, it is consistent.

No more than one undervoltage device should be connected to a static time delay box.

The Static Time Delay Undervoltage can also be furnished in conjunction with the termotector control package, as shown on wiring diagram 0102 C 3699 (Figure 27). Overheating of the motor windings causes the termotector, imbedded in the motor windings, to open and allow the " $Z$ " relay of the control box to instantaneously trip the
breaker through a normally closed "Z" contact in series with the undervoltage device mounted on the breaker.

WAFNING - Do not use bell set to check continuity of bridge circuit in static time delay box, only a volt-ohm meter or vacuum tube volt meter should be used.

In the event the device fails to pick-up, the following checks are recommended to determine whether the magnetic device on the breaker or the static time delay unit is the faulty component.
A. Check input voltages across terminals $1 \& 2$ on static box. These voltages should be as follows:

1. Device $177 \mathrm{~L} 316 \mathrm{G}-12-208$ or 230 volts A.C.
2. Device 177L316 G-14-125 volts D.C.
3. Device 177L316 G-15-250 volts D.C.
B. Check output voltages on terminals 4 \& 5 with the under voltage device connected. The
approximate voltages are as follows:
4. 208 Volt A.C. $177 \mathrm{~L} 316 \mathrm{G}-12-110$ volts D.C. 230 Volt A.C. 177 L 316 G-12-120 volts D.C.
5. 125 Volt D.C. $177 \mathrm{~L} 316 \mathrm{G}-1450$ volts D.C.
6. 250 Volt D.C. $177 \mathrm{~L} 316 \mathrm{G}-15-100$ volts D.C.
C. The resistance of the under-voltage coils are as follows:
7. 6275080 G-59 - 1830 Ohms.
8. 6275081 G-61 - 440 Ohms.

## REPLACEMENT

The entire device may be dismounted by disconnecting the coil leads and removing screw (1) and muts 16. Normally, only the coil (12) will ever need repiacement. This may be removed from the device by taking out screws (11)" which will free both the magnet (10) and the coil. Straight-


1. Mounting Screw
2. Frame
3. Armature
4. Spring
5. Shading Ring
6. Adjusting Screw
7. Locking Nut
8. Bushing
9. Clamp
10. Magnet
11. Screws
12. Coil
13. Rivet
14. Adjusting Screw
15. Locking Wire
16. Mounting Nut
17. Mechanism Frame
18. Trip Paddle Clamps
19. Trip Paddle
20. Adjusting Screw

Figure 28. (0152C9206) Undervoltage Tripping Device


Figure 29. (0101C7842) Undervoltage Lockout Device

1. Cross Bar
2. Left Side Frame
3. Trip Paddle
4. Undervoltage Armature
ening of the bend in clamp (9) will separate the coil from the magnet. The coil leads, of course, must be disconnected.

## INSTANTANEOUS UNDERVOLTAGE TRIPPING DEVICE

The instantaneous undervoltage device is mounted in the same location and manner as the static time-delay device and its construction is similar.

The adjustments and replacement of $t$ is device are the same as those described above for the static time-delay undervoltage device.

## UNDERVOLTAGE LOCKOUT DEVICE (Figure 29)

The undervoltage lockout device holds an open breaker trip-free when the coil of the device is deenergized. When the breaker is in the closed position, linkage operated by the breaker mechanism cam positions itself to mechanically hold the undervoltage device armature in the closed air gap position to prevent tripping the breaker in the event the undervoltage device coil is deenergized. This feature when used in conjunction with normally-closed auxiliary contacts of an
alternate breaker presents a convenient method of mechanically interlocking two or more breakers to assure that no two breakers may be closed at the same time.

## BELL ALARM SWITCH AND/OR LOCKOUT ATTACHMENTS

(Figure 30)
The bell alarm device is mounted on top of the horizontal cross frame member just to the left of the mechanism frame when the breaker is viewed from the front. This device operates a switch with two sets of contacts, one normally open, the other normally closed. The switch may be used to open or close an external circuit, giving a bell or light indication of a protective trip device operation.

If the breaker is tripped open by any means other than the manual trip button or the shunt trip device, the bell alarm mecharism is activated. The alarm is shut off and the bell alarm and lockout mechanism is reset by operation of the manual trip button or shunt trip device. If the device is a bell alarm only, the bell alarm mechanism is also reset simply by closing the breaker.

## OPERATION

Lever (2) is connected to the breaker mechanism so that when the breaker opens lever (2) rotates counterclockwise about pin (14). The motion is transmitted through links (1) and (13) to paddle (12) which operates bell alarm switch (11). If the device has the lockout feature, the movement of link (13) also causes lockout link (8) to slide in a direction that results in its striking trip paddle (5) which, by displacement of the breaker mechanism trip latch, makes it impossible to reset the breaker mechanism until the bell alarm mechanism is reset.

Link (6) serves as a latch in the bell alarm mechanism. If it is displaced, link (10) is free to rotate about its lower pin. This deprives the linkage of its normally fixed center of rotation about pin (15) and defeats both the bell alarm and the lockout operation. Operation of either the manual trip button or the shunt trip device will displace latch (6) and have this effect. Thus if the breaker is tripped by either of these means, the bell alarm and/or lockout will not operate Also; operation of either of these devices will reset the switch and inactivate the lockout.


Figure 30. (695C158) Bell Alarm and Lockout Device

1. Link
2. Lever
3. Pin
4. Trip Shaft
5. Trip Paddle
6. Link
7. Trip Arm
8. Lockout Link
9. Frame
10. Link
11. Switch
12. Paddle
13. Link
14. Pin
15. Pin
16. Springs
17. Spring

## OPEN FUSE LOCKOUT DEVICE

(Figure 31)
The Open Fuse Lockout Device consists of two or three separately operated devices (one per phase). Each wired in parallel to corresponding breaker fuses. This device is furnished on all AKU breakers. The purpose of this device is to trip the breaker upon the blowing of any one of the breaker fuses and render the breaker trip free until the blown fuse is replaced and the associated coil assembly reset.

OPERATION, Figure 31.
When any one of the breaker fuses blow, the coil (6) in that phase is energized and the armature (5) closes. With the armature closed, leaver (2) slips under the armature and latches it in the closed position. The latched closed armature holds the breaker in the trip free position until it is released by pushing the associated reset button (1). The coil is deenergized as soon as the breaker opens.

## ADJUSTMENTS

1. Set top cylindrical collor (not shown) to engage the trip shaft paddle in the tripped position.


Figure 31. (8041865) Open Fuse Lockout Device

1. Mounting Holes
2. Lever
3. Reset Button
4. Collar
5. Armature
6. Coil
7. Check that each armature holds the breaker trip free when the armature position is limited in reset by the lower latch surface on the indicator.
8. With the breaker in the closed position, the top collor must clear the trip shaft paddle by more than $1 / 32$ inch.

## REPLACEMENT

1. Remove three mounting screws at top of device.
2. Remove coil leads from fuses and work wire harness back to the device. Remove device from breaker.
3. Replace new unit in reverse order and check procedure under ADJUSTMENTS.

## AKD-5 INTERLOCK

(Figure 32)
The rackout mechanism is interlocked so that the circuit breaker must be open before the operating handle can be inserted. When the breaker is closed, the interlock link (1) operated by the breaker cross bar blocks the interlock linkage on the rackout mechanism.


Figure 32. (8039852) AKD-5 Interlock

1. Rackout Mechanism Interlock
2. Trip Interlock

## MISCELLANEDUS

Changes in breaker requirements may occasionally bring about the necessity of adding or changing breaker components or accessories in the field. The AK-2 breaker has been designed so that such additions or conversions are simple and easy to make, requiring only a minimum of time or skill on the part of the operator.

Special instructional drawings are available which will further simplfy the addition of such accessories to breakers which were originally shipped without them.

These drawings will accompany the necessary material when it is shipped from the factory. They will also be available upon request. The drawings and the accessory additions which they cover are listed below.

When an accessory is added to a breaker, it is recommended that the section of instructions contained herein covering that particular accessory be reviewed, in addition to referring to the following instructional drawing. Any adjustments described in these instructions should be carefully made after the device has been assembled on the breaker.

Conversion of breakers from manual to electrical operation is also covered on an instructional drawing. This operation consists simply of separation of the front and back frames of the breaker as described under "Maintenance" in these instructions and the reassembly of the existing back frame with the new front frame.

| Addition of | Covered By |
| :--- | :---: |
| Shunt Trip Device | 698 C 900 |
| Auxiliary Switch | 698 C 901 |
| Undervoltage Device | 698 C 902 |
| Bell Alarm \& Lockout Device | 698 C 904 |
| Drawout Mechanism | 698 C 922 |
| Conversion to Elec. Oper. | 698 C 904 |

## MAINTENANCE TOOLS

The following tools are recommended for proper maintenance of AK-2-15 and AK-2/3-25 breakers. (NOTE: Obtain from local hardware firm; do not order on General Electric Company.)

## Screw Drivers

Long thin, slotted screw
Standard, slotted screw
Phillips, No. 2, (8" shaft)
Pliers
Waldes Truarc, No. 2 straight
Long Nose, side cutting, $6^{\prime \prime}$
End Wrenches
Adjustable, $8^{\prime \prime}$
$1,4^{\prime \prime}$ open end
Allen Head Wrenches
5. $16^{\prime \prime}$ for $3 / 8^{\prime \prime}$ screw
$1 / 8^{\prime \prime}$ for $1 / 4^{\prime \prime}$ screw
Socket Wrenches (3; $8^{\prime \prime}$ drive)
Ratchet Handle
$12{ }^{*}$ extension bar
3; $8^{\prime \prime}$ socket
9/16" socket
$7.16^{\prime \prime}$ socket (long)

Miscellaneous Tools
1/4" Spintite (long shank)
7:16" Spintite
8 82 screw (at least 2 " long)

## RENEWAL PARTS

When ordering renewal parts, address the nearest Sales Office of the General Electric Company, specifying the quantity required. Complete nameplate data of the breaker involved should be given as well as an accurate description of the parts required. If the parts needed are illustrated in this book, refer to the figure number and part number involved.

Renewal Parts which are furnished may not
be identical to the original parts since from time to time design changes may be made. The parts supplied, however, will be interchangeable with the orisinal parts.

## Renewal Parts Bulletin

## Bulletin

GEF-4149F
Breaker Type
AK-2-15/25
AK-3-25

## GENERAL ELECTRIC



## Conversion Kits

For Installing the SST Solid Siate Overcurrent Trip Device on Low Voltage Power Circuit Breaker Types AK-15 and AK/AKU-25


Components of SST Conversion Kit for AK-15/25

## CONTENTS



## I. INTRODUCTION

These instructions cover installation of the SST solid state overcurrent trip device conversion kits on AK-15 and AK-25 frame breakers originally equipped with EC or Power Sensor type trip devices. Each kit contains the variety of material necessary to convert either type. The kits are designed specifically for use on the following breakers:

## Table 1 - Convertible Breaker Models

| $\begin{aligned} & \text { Frame } \\ & \text { SAze } \\ & \text { (Amp.) } \end{aligned}$ | Breaker Type |  |  | Trip Device |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Stationary | $\begin{gathered} \text { AKD } \\ \text { Drawout } \end{gathered}$ | AKD-6 Drawout | EC | Power Sensor |
| 225 | AK-2-15 | AK-2-15 | AK-2A-15 | x |  |
| 600 | AK-2-25 | AK-2-25 | AK-2A-25 | x |  |
|  | AK-3-25 | AK-3-25 | AK-3A-25 |  | $\times$ |
|  | - | AKU-2-25 | AKU-2A-25 | $x$ |  |
|  | - | AKU-3-25 | AKU-3A-25 |  | $x$ |

Kit instaliation is a straightforward operation but does require careful workmanship and attention to these instructions. Familiarity with the breaker itself is highly desirable. The general approach is to first strip the breaker of its existing trip devices (either EC or Power Sensor), then install the SST components. Following this, the converted breaker is periormance tested prior to restoring it to service.

For the majority of breaker models listed in Table 1, kit installation does not require any customized assembly work. However, some conversions may involve unusual mounting circumstances or accessory combinations which necessitate minor modification/relocation of a component(s). In most instances this supplementary work can be done on site.

Preparatory to beginning the conversion, the installer should verify that the correct kit, current sensors and programmer unit have been furnished - see Tables 2, 3 and 4. Whenever the Ground Fault trip element is furnished for breakers applied on 4 -wire systems, note that in addition to installing the kit on the breaker an associated neutral sensor (CT) must be separately mounted in the equipment. Insure also that retrofitted breakers are applied within their short circuit ratings; for example, assuming that as part of a conversion the breaker's trip elements are to be changed from LI to LS, then the short time rating would govern the application.

## TOOLS REQUIRED

| Socket Set - 3/" drive | Pliers - Assorted |
| :--- | :--- |
| Open End Wrenches - Set | Electric Drill |
| Screwdrivers - Assorted | Drill Bits |
| Allen wrenches - Assorted | $6^{\prime \prime}$ Scale |
| Tru-arc Pliers - Assorted | Crimping Tool |

Users are reminded that the installation of SST kits provides an excellent opportunity to perform normal maintenance on the breaker proper, particularly while the front and back frames are separated. Renewal parts are available as listed in Builetin GEF-4149G, a copy of which is incluced with each SST KII.

Table 2 - Basic Conversion Kits for AK-15/25, AKU-25

| Breaker <br> MountIng <br> Type | Basic Kit Cat 343L692-(Gp. No.) |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | With 4th-Wire <br> Neutral Sensor |  | W/O 4th-Wire <br> Neutral Sensor |  |
|  | Man. | Elec. | Man. | Elec. |
| Stationary | G3 | G4 | G1 | G2 |
| AKD \& AKD-5 <br> Drawout | G5 | G6 |  |  |

Table 4 - Tapped Current Sensors for Use with SST Conversion Kits

| $\begin{aligned} & \text { Breaker } \\ & \hline \text { Typer } \end{aligned}$ | Sensor Ampere Range | Cat. 343L692-(Gp. No.) |  |
| :---: | :---: | :---: | :---: |
|  |  | Phase Sensors | 4th-Wire Neutral Sensor |
| AK-15 | 70-225 | G37 | G67 |
| AK-25, AKU-25 | 70-225 |  |  |
|  | 200-600 | G38 | G68 |

Table 3 - Programmer Units for AK-15/25, AKU-25 SST Conversion Kits

| Trip <br> Eliments | Cat. 343L692-(Gp. No.) |  |  |
| :---: | :---: | :---: | :---: |
|  | None | 1.75L-4L | 3L-10L |
| LS | - | G19 | G13 |
| LI | G14 | - | - |
| LSI | - | G20 | G15 |
| LSG | - | G21 | G16 |
| LIG | G17 | - | - |
| LSIG | - | G22 | G18 |

(1) Trip Element Abbreviations
$\mathbf{L}=$ Long Time
$\mathrm{S}=$ Short Time
$1=$ Instantaneous
$G=$ Ground Fault

## II. PREPARING THE BREAKER

WARNING: Before starting any work, disconnect the breaker from all power sources (primary and secondary) and place in a clean work area.

1. Remove the steel arc quencher retainer by loosening the two $1 / 4 \times 20$ hex capnuts. On electrically operated AK-3/3A-25 breakers the " $Y$ " relay is mounted on the left end of the retainer, but there is no need to remove it.
2. Remove the three arc quenchers by lifting upward and outward.
3. Separate the breaker's front and back frames. Refer to Maintenance Manual GE1-50299 page 5; if Power Sensor, see pp. 28-31 also.

CAUTION: Be careful to avoid damage to breaker components during this operation.
4. Remove the overcurrent trip devices. Refer to Maintenance Manual GEI-50299 pp. 23. 31.
5. On drawout breakers, remove the primary disconnect fingers from the bottom (loadside) copper studs. Refer to Maintenance Manual GEI50299 page 7.
6. Remove the thres bottom (loadside) copper stud assemblies. On Power Sensor equipped breakers this will have been done during Step 4 above.
7. On electrically operated breakers equipped with EC trip devices, the " $Y$ " relay is mounted on the front frame at the right side of the operating mechanism. To provide mounting space for the SST flux shift trip device, remove the " $Y$ " relay and remount it on the left end of the arc quencher retainer as shown in Figs. 1 and 2 (using hardware and parts included). Modity the breaker's wiring harness to suit.
8. On EC equipped breakers, remove and discard the four trip device support brackets mounted along the lower front of the back frame. See Fig. 3. At this point the breaker back frame is ready for installation of the kit.
(umous ұпомедp edfi aXV)



* RE denotes reuse of existing hardware


Fig. 2 - Right side view of front frame

Fig. 3 - Front view of rear frame

## III INSTALLING THE KIT

1. Modity the left and right pole lower stud insulator shields per Fig. 8; remount on back plate using original screws and special nut (Item 93 on Fig. 7) supplied with kit.
2. Assemble and mount the three current sensor (CT) assemblies to the back frame. See Figs. 5, 6 and 7. Proceed with each pole by first inserting lower copper stud 90 through the back plate and attaching it via the mounting screw; then position CT 18 with its terminals toward the rear and loosely mount it to stud 90 with copper parts 91 and 92; align the assembly and torque the two $3 / 81$ bolts in strap 91 to 25 ft .-Ibs. each to assure proper contact integrity.
3. Install CT terminal board mounting bracket 80 below the CT's using the (2) $8-32 \times 1 / 2^{\prime \prime}$ screws provided. See Fig. 5. Mount terminal boards TB1, TB2 and TE3 to the bracket using the (6) $6-32 \times 1 / 2^{\prime \prime}$ screws and washers provided.
4. On drawout type breakers, remount the primary disconnect fingers on the new lower studs. Refer to Maintenance Manual GEl-50299 pp. 7 and 13.

CAUTION: Adequate primary contact force is mandatory. Tighten the nuts on the $1 / 4 \times 20$ mounting bolts to obtain a spring dimension of $17 / 8$ to $2 / 20$. The proper dimensions between contact fingers is $70^{\prime \prime}$. Proper contact force is 60 to 70 lbs . with the contacts spread to $1 / 2^{\prime \prime}$.
5. Mount programmer rear mounting bracket 70 together with flux shift trip devics terminal board TB4 (part of wire harness 100) to the lower right corner of the back frame utilizing existing holes - See Figs. 5 and 6.
6. Install wire harness 100 on back frame and connect per instructions on Figs. 9, 12 or 16 as applicable to the particular breaker type involved. For tie-down and forming details, see Fig. 5.
This step completes conversion of the back frame - see example illustrated in Fig. 4.
7. Proceeding next to the front frame, mount the flux shift trip paddle on the breaker's trip shaft per Figs. 17 and 18.
8. Mount the flux shift trip device per Figs. 17 and 19. NOTE: Adjustment of trip rod length will be performed later in Step 13.
9. Install programmer front mounting bracket 71 to the underside of the front frame per Fig. 21. On AK-2/2A electrically operated models, this bracket replaces the existing bracket which mounts the " $X$ " contactor. This step is not required on AK-3/3A models; they have the proper bracket already in place.
10. Reference Fig. 6, install flux shifter actuating bushing 49 in the right hand operating link; enlarge the link hole if necessary. See Fig. 4 also.
11. Rejoin the front and back frames. Refer to Maintenance Manual GE1-50299, Page 5.
12. Connect wire harness " $X$ " (attached to flux shift trip device) to terminal block TB4 per Fig. 20. Exercise care in routing to prevent leads being damaged by moving breaker components such as contact assemblies.
13. Adjust flux shitt trip rod gap per instructions on Fig. 17.
14. Mount programmer unit 17 to breaker and plug harness connector into programmer. See Fig. 21.

CAUTION: To avoid shock hazard and possible damage to wire harness and sensor coils, the harness connector must be securely mated with the programmer unit before the breaker is energized.
Conversion of the breaker is now complete. A typical example is shown in Fig. 22.

Proceed next to Section IV - EQUIPMENT MODIFICATIONS. If these are not required, proceed directly to Section V - FUNCTIONAL TESTING.


Fig. 4 - AK-25 back frame with SST conversion components instailed and ready for reassembly to front frame.


Fig. 5 - Back frame assembly


Fig. 6 - Right sida view of back frame


Fig. 7 - Phase sensor assembly, right side view


Fig. 8 - Stud insulator modification


1) $?$

FIG. 9 Harness connections for all drawout and stationary breakers used on 3 -wire systems - with and without ground fault. For elamentary diagran see Figs.
10 \& 11 .

## INSTALLATION STEPS

1. Connect the $A, B$ and $C$ Phase Sensor Leads respectively to TB1, TB2 and TB3. Identify per
Table 5.

## TABLE 5 - Harness Connections

| Component | $\xrightarrow{\text { From }}$ Board | Wire Color |  |
| :---: | :---: | :---: | :---: |
| Phase A Sensor | TB1 | White Black | $\begin{aligned} & \text { A } \\ & C \end{aligned}$ |
| Phase B Sensor | TB2 | White Black | $\stackrel{D}{\text { F }}$ |
| Phase C Sensor | TB3 | White Black | H $K$ |
| Flux Shift Trip Device | TB4 | Red Black | E |
| 4th-Wire <br> Neutral* <br> Sensor | TB5 or Secondary Disconnect | White Black | $\stackrel{L}{\text { L }}$ |



110

IJsed only with 4-wire Ground Fault.


Fig. 10 - Cabling Diagram — SST without ground fault.


Fig. 11 - Cabling Diagram - SST with ground fault on 3-wire load.


FIG. 12 Harness connections for all drawout breakers equipped with 4 -wire ground fault. For elementary diagram see Fig. 14.

## INSTALLATION STEPS

1. Connect the $A, B$, and $C$ phase sensor leads respectively to TB1, TB2 \& TB3. Identify per Table 5.
2. Mount the neutral sensor disconnect block 120 to the rear of the back frame per Fig. 13. Use existing mounting holes.
3. Insert the two prepared leads of harness 128 into the harness connector: Black to socket $N$, white to socket $L$
4. Feed the opposite end of harness 128 thru hole " $X$ " in the back frame and connect leads to block 120 as shown in Fig. 13.


FRONT VIEW OF BACK FRAME


ENLARGE THIS HOLE TO . 312 DIA.


SIDE VIEW

REAR VIEW OF BACK FRAME

Fig. 13 - Mounting detail for secondary disconnect block 120 for 4th-wire neutral sensor (drawout breakers only).


## 



FRONT VIEW OF BACK FRAME


Fig. 16 Hamess connections for stationary breakers equipped with 4 -wire ground fault. For elementary diagram see Fig. 15.

## INSTALLATION STEPS

1. Connect the $A, B$ and $C$ phase sensor leads respectively to TB1, TB2 \& TB3. Identify per Table 5.
2. Mount neutral sensor terminal board TB5 (part of harness 110) to the back frame.
3. Insert the prepared leads on the opposite end of harness 110 into the hamess connector: Black to socket N, white to socket L.

AFTER BREAKER IS REASSEMBLED, ADJUST THE FLUX SHIFT TRIP ROD AS FOLLOWS: WITH BREAKER OPEN AND THE TRIP SHAFT RESET, TURN ADJUSTER UNTIL GAP IS . 093 TO . 125 , THEN LOCK WITH JAM NUT.


Fig. 17 - Right side view of mechanism frame showing mounting of flux shift trip device 40.


Fig. 18 - Rear view of front frame showing location of trip paddle for flux shift trip device.

10)

Fig. 19 - Right side view of operating mechanism showing mounting of flux shift trip device.
sECURE WIRE HARNESS " $X$ " WITH TIES P54 AFTER ASSEMBLY OF FRONT FRAME TO BACK FRAME.

PROGRAMMER SHIELD AND BRACKET


Fig. 20 - Connection of Harness " $X$ " from flux shift trip device to terminal board TB4 on back frame.


Fig. 21 - Right side view of breaker showing mounting of programmer unit.


Fig. 22 - AK-25 breaker with SST conversion completed.

## IV. EQUIPMENT MODIFICATIONS

## गtE:

The following modifications are required ONLY in conjunction with breakers being equipped with 4-wire Ground Fault trip elements.

1. Mount the neutral sensor (CT) in the outgoing neutral lead, normally in the equipment's bus or cable compartment. See Fig. 23 for the sensor's bar drilling plan. Check to insure that the neutral and phase sensors match, i.e., have the same ampere range.
2. On drawout type breakers, mount the 4th-wire
neutral sensor stationary disconnect block 121 inside the breaker compartment at the lower rear as shown in Figs. 24 or 25, whichever applies. For the AKD-5 type equipments of Fig. 24, be careful to select the correct mounting bracket (Part 126 or 127).
3. Connect the neutral sensor to disconnect block 121 per wiring instructions of Fig. 26. For sta tionary breakers, the neutral sensor is connected to TB5.


Fig. 23 - Outline of SST Neutral Sensors: Cat. 139C4475G1 70-225 amp Cat.139C4475G2 200-600 amp (from outline dwg. 139C4476)


Fig. 24 - Mounting of 4th-wire neutral sensor disconnect block in AKD-5 switchgear compartments and AKD-5 type
OEM boxes.


Fig. 25 - Mounting of 4th-wire neutral sensor disconnect block
in AKD type OEM box.

## NOTE:

Neutral CT markings of LINE and LOAD must be respected when making bus or cable connections.

INECT TO TERMINAL BOARD TB'S ON
SIATIONARY BREAKERS, OR TO NEUTRAL SENSOR STATIONARY DISCONNECT BLOCK FOR DRAWOUT BREAKERS.

Polarity of connecting wires from Secondary of Neutral CT to Terminal Block or CT Disconnect Block must also be respected: Tap to Tap, Com. to Com.
/ NOTE: BOND ON LINE SIDE ONLY
LINE

14 MIN. WIRE, WIRES MUST BE RUN TOGETHER




FRONT VIEW LOOKING INTO BREAKER COMPARTMENT

Fig. 26 - Connecting the 4th-wire neutral sensor.

## V. FUNCTIONAL TESTING

Before the breaker is reinstalled to service:

1. Megger breaker primary circuit using a 1000 V megger.

Perform either of the following tests:
A - Using ECS/SST test set Catalog \#TAK-TS1, test per Instructions GEK-64454 to assure proper operation of the breaker and its trip device Or,

B - Using a single-phase, high current-low voltage test set, test each trip element (L, S, I, G) to assure proper protective device operation. Compare results with applicable timecurrent characteristic curves reproduced on pages $26 \& 27$.

## NOTE:

When testing units equipped with a ground fault trip element, the latter must be deactivated by using Ground Fault Defeat Cable Catalog \#TGFD as shown in Fig. 27 below. If this defeat cable is not available, the breaker can be tested by connecting two poles in series.


Fig. 27 - Cabling diagram with Ground Fault Defeat Cable inserted between breaker harness and SST Programmer Unit - for use during single-phase, high current - low voitage testing.

## TABLE 6 - TRIP CHARACTERISTICS — SST CONVERSION KITS





GENERAL EEETRIC CO．CIRCUIT FROTECTVE SEVICES DEPT．PLAINYILE．CONN，OGOS2

general elegtric co., cincuit protective devices dept., phanville. conn. osob2

## GENERAL ELECTAIC

# POWER CIRCUIT BREAKERS 

Types<br>AK-2-15<br>AK-2-25



## LOW VOLTAGE SWITCHGEAR DEPARTMENT

## GENERAL ( 궁

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# POWER CIRCUIT BREAKERS TYPES AK-2-15 AND AK-2-25 

## INTRODUCTION

The instructions contatned herein provide information for performing maintenance procedures and for replacing

AK-2-15/25 breaker components and accessories. For information regarding the receiving, handling, storage and Installation
of these breakers, refer to GBH-2021, furnished with all AK breakers.

## OPERATION

## ELECTRICAL OPERATION

## FIG. 1

The electrically operated breaker closes whenever the closing solenotd coll is energized. This causes an upward movement of the solenold armature, which inItiates the mechanical closing action. The closing signal may be given elther by a remote ewitch or relay, or by a clasing button in the front egcutcheon tif the breaker is so equipped. Ether action (refer to the olementary of the wiring diagram) energizes the coil of the X relay through the bb contacts of cutoff switch $G$ and the normally closed contacts of the $Y$ relay. When the X relay or contactor is energized, it closes Its contacts. One of these ( $\times 1-2$ ) seals in the $X$ coil. The other three sets of contacts. Which are arranged in serles, activate. the closing solenold.

The breaker control scheme has an anti-pump feature which allows only one closure of the breaker for a single operation of the closing ewitch no matter how long the switch may be held closed. This prevents the repeated operations that would ensue if one of the automatic trip devices was activated at the tlme of closing. The I relay, together with the cut off switch, provides the anti-pump feature. The mechanical action of clooing operates the cutoff gwitch, reversing the position of the contacts from that shown on the dlagram. This energizes the $Y$ relay, if contact is atill maintained at the closing switch, with the result that the $X$ relay circult 18 opened by $Y$ contacts 5-6. This prevents the $X$ relay irom again becoming energized. $Y$ contact 1-2 seals in the $Y$ collas long as contact is maintained at the closing awitch.

Electrically operated breakers may also be closed by means of the malntenance handle which ts furnlshed with the breaker. This is a separato tool and is simply a lever which permits an operator to push upwards on the closing solenold armature. handle are engenged in end of maintenance handle are engaged in slots (9A) Fig. 5 , located in the lower portion of the Iront escutcheon (8A) Fige 5. Rotation of the long end of the handle dowawards larces the shorter end of the handle upwards againat the bottom of the solenold armature, and closes the breaker.


Fig. 1 Typlcal Wirlig olagran

$$
\begin{aligned}
& \text { Them instructionaidejigh purport to cover all detuile or variations in equpmont nor to provide for ivery pomible }
\end{aligned}
$$

The breaker may be tripped open by any one of a number of electrical tripping devices which will be described in detall later in thege instructions. An individual breaker may have none or any combination of these devices. They are the overcurrent tripping device, shunt tripping device, undervoltage tripping device and reverse current tripping device. All of them effect tripping by displacing the trip latch of the mechanism. The trip latch is rigidy attached to a trip shaft which runs through the breaker from left to right. Whenever the trip shaft is rotated in a counterclockwhe direction looking from the right, the latch is diaplaced. The tripping devices are all equipped with strikers or trip arms which act against trip paddles rigidiy fastened to the trip shalt, causing it to rotate on Its bearings in a direction to trip the breaker.

The reverse current device and the ghunt tryping device each have a set of audliary 8 witch "a" contacta in their circults. : (An "a" contact is open when the breaker contacts are open). This prevents thetr operation unless the breakar is closed.

The undervoltage device coll ts normally continually energized. When the con-

## INSPECTION

BEFORE INSPECTION OR ANY MADNTENANCE WORK IS DONE, BE SURE THAT THE BREAKER IS IN THE OPEN POSTTION. ALL ELECTRICAL POWER, BOTE PRIMARY AND CONTROL SOURCES, SHOULD ALSO BE DISCONNECTED.

Periodic inspection of the circuit breaker is recommended at least once a year. More irequent inspections are recommended, if severe load condittons, dust, moisture, or other uniavorable conditions exist.

If the breaker remains open or closed for a long period of time, it is recommended that arrangements be made to open and close it beveral times in succession, preferably under load.

At all times it is important not to permit pencil lines, paint, oil or other lorelgn materials to ramain on the insulating surfaces of the breaker as they may cause low resistance between points of different potential and result in eventual electrical brealdown.

Always Inspect the breaker after a short ctrcuit current has been interrupted.

At the time of periodic inspection, the following checks should be made after the breaker has been de-energized.

1. Manually operate the breaker sev. eral times, checking for obstructions or excessive friction.
2. Electirically operate the breaker Beveral times (if breaker has electrical control) to ascertain whether the electrical: attachments are functioning properly.
3. Remove and inspect the arc quencher. Breakage of parts or extensive burning whil indicate need for replacement.
4. Check contact condition and wipe.
5. Cheok latch engagement.
trol voltage ts low or non-existant, as when the breaker has been pulled out for inspection or maintenance, the breaker is rendered trip-free by the undervoltage devtce. If it is desired to close the breaker, the device armature must be tied down or blocked closed againgt the magnet.

## MANUAL OPERATIOM

The manually operated breaker is closed by first rotating the handle in a counterclockwise direction through 90 degrees, then rotating it clockwise back to its normal vertical position. The counterclockwise stroke resets the mechanism, readying it for the clockwise closing stroke.

The breaker may be tripped manually by pushing the manual trip button. This action pushes a rod against a trip paddle of the trip shaft, rotating it, and causing the mechanism trip latch to be displaced. This allows the mechanism linkage to collapse through the action of the mechanism operating springs.
CAUTION: If the breaker is tripped manually while the operating handie is in the reset position, the handle should be lowered
by the right hand while operating the trip button with the left hand.

## ELECTRICAL AND MANUAL OPERATION

This operating mechanism provides both manual and electrical closing. The operating mechanism is similar to the mechanism of the standard electrical breaker with the addition of the manual handle, cam and mechantsm connecting lipk. The solenold connecting link and manual cam connecting link are both connected to. the closing spring pin at the top of the mechanism, thus compressing the aprings when force is provided by either means of breaker closing.

The breaker is manually closed by rotating the closing handle 90 degrees counterclockwise. No reset atroke is neces sary as is the case with the standard manual breaker. Electrical closing may be performed either locally or remotely in the same manner as the standard electrical breaker.

Tripping is accomplished by the maniual trip button on the escutcheon or by any of the electrical tripping devices: ayaliable for use on the atandard breakers.

On drawout breakers, the bottom plate must be removed by firat removing two B8-36 screws located at the front of the bottom plate and then ireeing the plate from the slots located in the bottom of the back frame.
6. The two frames are now disconnected. However, care should be exerclsed in separating them to avold damage to the trip shaft arms and paddles. While the back frame is held steady; lift the Irant frame and mechanism up and out 80 that the trip paddles on the trip shaft clear the trip arms of the overload trip devices.

Reassembly of the two breaker halves is accomplished by following the procedure outlined in reverse order.

## LUBRICATION

In general, the circuit breaker requires very little lubrication. Bearing points and sllalng surfaces should be lubricated very Hghtly at the regular ingpection periods with a thin fllm of extreme temperature, high pressure, light grease, similar to G. E. Spec. No. D50R15 or RPM No. 5 : Hardened grease and dirt should be removed from latch and bearing surfaces by the use of a sale cleaning solvent such as kerosene. Latch surfaces should be loft clean and dry and not be lubricated. ALL EXCESS LUBRICANT BHOULD BE REMOVED WITH A CLEAN CLOTH DIORDER TO AVOID ANY ACCUMULATION OF DIRT OR DUST.

At each malntenance period, all silver to silver friction points, such as primary: disconnects, should be cleaned and given a fresh coat of G. E. Spec. No. D50B4' lubricant.

## TROUBLE SHOOTINE

The following table lista several typical symptoms of breaker malfunction, together with thetr causes and remedies. It, at any time, these symptoms are observed, thetr cause should be determined and the neces: sary corrective action should be taken.

## TROUBLE SHOOTING

| TROUBLE | CaUse | REMEDY |
| :---: | :---: | :---: |
| Overheating | Contacts not aligned. <br> Contacts dirty, greasy or coated with dark film. <br> Contacts badly burned or pitted. <br> Current carrying aurfaces dirty. <br> Corrosive atmosphere. <br> Insufficient bus or cable capacity. <br> Bolts and nuts at terminal connections not tight. Current in excess of breaker rating. <br> Excesbive ambient temperature. | Adjust contacts. <br> Clean contacts. <br> Replace contacts. <br> Clean surfaces of current carrying parts. <br> Relocate or provide adequate enclosure. <br> Increase capacity of bus or cable. <br> Tighten, but do not exceed elastic limit of bolts or fittingo. <br> Check breaker application or modify circuit by decreaslag: load. <br> Provide adequate ventliation. |
| Failure to 1 | Travel of tripplng device does not provide positive release of tripping latch. <br> Worn or damaged trip unit parts. <br> Bind in overcurrent trip device. | Re-adjust or replace tripping device and check mechanism. latch adjustment. <br> Replace trip unit. <br> Replace overcurrent trip device. |
| False Tripping | Overcurrent trip device pick up too low. Overcurrent trip device time setting too short. Bind in overcurrrent trip device. | Check application of overcurrent trip device. Check application of overcurrent trip device. Replace overcurrent trip device. |
| Fallure to Close and Latch | Binding in attachments preventing resetting of latch. <br> Latch out of adjustment. <br> Latch return spring too weak or braken. <br> Hardened or gummy lubricant. <br> Closing solenoid burned out. <br> Solenold control device not functioning properly. | Re-allgn and adjust attachments. <br> Adjust latch. <br> Replace spring. <br> Clean bearing and latch surfaces. <br> Replace solenold coll. <br> Re-adjust or replace device. |

## BASIC BREAKER COMPONENTS

## DISCONNECTS

## PRDAARY DISCONNECTS

The primary disconnects are attached to the ends of the braaker studs on the rear side of the breaker bape. Each digconnect assembly consists of two pair of opposed contact fingers. These are aecured to the breaker stud by a bolt which passes through the agsembly and the stud. When engaged with the stationary stud of the enclosure, the disconnect fingers oxert a set amount of force agninst the stationary stud through the action of the compression springa. Retalners and spacers hold the contact fingers in correctalignment for engagement with the stud. The amount of force which the fingers exert against the stud is determined by degree to which the springs are compressed by the bolt and nut which hold the assembly togother. If, tor any reason, the digconnects must be tiken apart, the pooition of the nut on the boit should be carefully noted,: 00 that in reassemblying, the original amouat of compression can be restored by replecing the nut at its former pooition on the bolt.

SECONDARY DISCONNECT, FIG. 2
The secondary disconnects serve as connections between breaker control circuit elements and external control circuits. They are used only on drawout type breakers. A terminal board serves the same purpose on stationary mounted and general purpose enclosure mounted breakers. The secondary disconnects allow removal of the breaker without the necessity of having to detach external connections.

The movable part of the secondary disconnect consists of an insulating body which holds a conducting apring loaded plunger to which a flexible lead to attached. As the breaker moves Into its enclosure, the plunger is depressed by sliding onto the atationary disconnects of the enclosure.

## REPLACEMENT OF MOVABLE SECOND-

 ARY DISCONNECTS1. Unfasten, dlaconnect body from breaker back frame.
2. Open tabs which hold wires on inner side.
3. Pull contact tip loose from hollow
4. Remove contact tip by cutting wire at its base.
5. Push wire through hollow tube l new disconnect assembly.
6. Strtp insulation off end of wire to about $1 / 4$ of an inch from end.
7. Place now contact tip on end of wire and crimp.
8. Pull wire through hollow tutbe vintu contact tip tits enugly againgti end of hollow. tube.
9. Crimp tabon other side of assomily to hold wire ta place.
10. Any hollow tubes which are not used ahould be puahed Into the dilscomiect bods. and held In that posittion by plactog fibre. apacers over inner onde of tubod and spreading tabs.
11. When all wires have beteconnected, refasten the body of the desombly to the breaker back frame.

## ARC QUENCHER

The arc quencher is an integral riveted assembly composed of two ceramic side plates, a series of steel plates, and a muffler. The assembly is covered by a wrap around of insulating material which inhibits any sidewise emission of gases. The steel plates are held in position and supported by the ceramic sides which are grooved vertically to provide recesses for the vertical edges of the steel plates. The ottom edges of the latter form an inverted "V" along the path of the arc that may be drawn between the breaker contacts during interruption. The steel plates have the effect of breaking up the arc, and cooling it and the gases that result from interruption. The entire assembly provides a "chimney" effect which directs the hot, fonized gases upwards through the steel plates and mufflers and allows their safe and controlled escape at a cooler temperature.

The muffler at the top of the as sembly is a serpentine shaped strip of perforated, copper plated steel. It is important that the perforations of the muffler be kept open, since their closure could tend to prevent the escape of the gases along the desired path. At the regular maintenance inspection, it would be well to check their condition and open any of the perforations that appear to be clogged.

If any very extensive burning or corrosion is noted in the arc quencher, it should be replaced. Replacement is also indicated if any breaks or cracks are noted in the ceramic material.

## REPLACEMENT

Removal of the arc quencher is simply a matter of lifting the assembly up and out, after the steel retainer across the front of the arc quenchers has been removed. The upper edge of the steel arc runner fastened to the back plate of the breaker fits into a recess in the back portion of the arc quencher and locates it in its proper position upon replacement. Make sure the steel retainer is replaced and fastened firmly to its mounting studs after the arc quencher has been replaced.

## BREAKER CONTACT STRUCTURE

The copper current carrying parts of the breaker are all mounted on a common base of insulating material made of polyester glass mat. The copper of each pole consist of an upper stud and pivot, stationary contacts, two movable contact arms, a movable contact pivot, and the lower stud.

The upper stud branches into two pivot surfaces on its inner end on the forward or front side of the breaker base. Each of these convex pivot surfaces mates with the concave pivot surface on the rear side of the stationary contacts. Each of the stationary contacts pivot in a horizontal plane approximately at their mid-points. The end of the contact opposite to the


Fig. 2 Movable Secondary Disconnects
contact tip end is formed into the shape of a small hook. A tension spring engages this hook and provides the necessary contact pressure at the pivot and also at the point of contact with the movable contact arm. When the breaker contacts open, a projection on the contact tip end of the stationary contact bears against a stop pin restricting the movement of the stationary contact. This arrangement results in a continual high force existing between the mating pivot surfaces and eliminates the necessity of fast-wearing flexible shunts around the pivot point.

The movable contact arms pivot in a vertical plane, each making contact with a pair of stationary contacts, and thus providing four low resistant parallel paths of current for each breaker pole. The movable contacts rotate about a burnished, silver plated, copper pin which, in turn, is held by a pivot support. Each side of the pivot support bears against the lower, outer surface of the contact arm and supplies a second low resistance path through the pivot. A "U" shaped spring clip made of silver plated conducting material provides an additional current path and protects the other contact surfaces of the pivot against pitting when in motion. It also contributes to the force tending to increase the contact pressure between the lower ends of the movable contacts and the pivot support.

The movable contact pivot support is mounted securely to the breaker base. If, as is normally the case, the pole is equipped with an overcurrent trip device, one of the terminals of the series coil of the trip unit is fastened to the lower end of the pivot support. The other terminal of the coil fastens to the lower stud.

## CONTACT ADJUSTMENTS

The only adjustment to be made on the breaker contacts is that of contact wipe. This may be described as the distance the movable and stationary contacts move while they are touching one another in the process of breaker closing. The amount of contact wipe can be measured by comparing the position of the front surface of the stationary contact when the breaker is open to its position when the breaker is closed, in reference to some absolutely stationary part of the breaker. The most convenient stationary part of the breaker to use as a reference point is the steel arc runner above and behind the stationary contacts.

The amount of wipe the contacts should have is nominally $1 / 8$ of an inch. A plus or minus tolerance of $1 / 32$ of an inch is allowable.

The means of adjusting contact wipe is provided by an eccentric pin which passes through the center of the movable contact assembly. Each end of this pin has a free, projecting, hexagon shaped section which is easily accessible to a small, open end, $1 / 4$ inch wrench. Two cantilever springs, which bear on each end against a portion of the hexagon section of the pin, lock the adjusting pin in place and provide index stops for the process of adjustment. The right hand hexagon shaped end of the pin is numbered from 1 to 6 , which provides a reference for making wipe adjustments.

When contacts are to be adjusted, the recommended procedure is as follows:

1. With the breaker in the open position and using the numbers on the right
end of each adjusting pin as a reference, set each pin in the same position. In many cases, the number 3 is a good beginning point. The proper view of the number on the adjusting pin is obtained by viewing the breaker from the front and the adjusting pin from approximately a 15 degree angle with respect to the movable contacts. Note that the numbers on the pin are not in numerical sequence as the pin is rotated.
2. By measurement; establish the position of the fromt surfaces of the stationary contacts with reference to the steal arc runners above and behind the contacts.
3. Close the breaker, and establish the amount of wipe by agaln measuring as in step two, and comparing the measurements with those taken with the breaker open.
4. If any set of contacts lead or lag the others, open the breaker and advance or retard the adjusting pin to the next higher or lower number, Moving the adjusting pin to a higher nitimber will increase the contact wipe and moving to a lower number will decrease the contact wipe.

NOTE: No attempt should be made to move the adjusting pin when the breaker is closed. Besides being more difficult, the additional force required to move the pin will tend to round off the Rlats of the hex aection of the pin.
5. When all the contacts have the recommended wipe of $3 / 32$ to $5 / 32$ of an inch, the contact adjustments are complete.

## CONTACT REPLACEMENT

## FIG. 3

The normal situation that will exist in the matter of contact replacement will call for replacement of all the movable and stationary contacts at the same time. This will be the case where long use of the breaker in service has reaulted in extensive wear or erosion of the allver alloy contact tips. A commonly used "rule of thumb" is that contact replacement is indicated if less than one-half of the original thickness (1/8 of an Inch) of the contact tlp material remains.

When the movable breaker contacts are to be replaced, remove the front frame from the back frame as described under "Beparation of Front and Back Frames" of these instructions. The stattonary contacts can be replaced with the breaker intact. The procedures for replacing both stationary and movable contacts ts described as follows:

## 8TATLONARY CONTACTS (21)

Without separating the breaker front and back frames, force the contacts awny irom the contact assembly center atop pln and toward thelr own pivot point with a screwdriver untli the contacts stop aurface ts iree of the center stop pln. The contact can then be remoyed with the thgers by disengagtig the contact from fts


1. Breairer Base
2. Insulation
3. Insulieted Stud
4. Upper Stud Barrier.
5. Inginlation
6. Links (Insulated)
7. Tie Bolt
8. Spring
9. Sprinc Clip (Retainer)
10. Crose Bar
11. Pivot Pin
12. Lower Stud
13. Contact Pivot Siuppore
14. Spring
15. Contact Wipo Adjustment
16. Serew
17. Upper Stud A Are Bunger
18. Movable Ontact
19. Spring
20. Nut
21. Stetloriary Conteste

Fig. 3 Contact fasably


1. Stationary Contacts
2. Movable Contacts
3. Upper Stud Asbestos Shield
4. Crossbar Plastic End Shield

Fig. 4 AK-2-25 Back Frame - Location of Crossbar and Pole Shields
spring. Remove each stationary contact in this manner.

MOVABLE CONTACTS (18)

1. Separate the front frame from the back frame of the breaker. (See section dealing with subject).
2. Remove insulation (5) by lifting and pinching sides together so that the enlarged portion of the slotted hole in each side of the insulation clears the head of the rivet which holds it in place.
3. Release the pivot pin spring clip retainer (9). On the outer poles this retainer is similar to a safety pin and is released by opening its ends as with a safety pin. The center pole is equipped with a clothes pin type retainer which can simply be pulled off the pivot pin (11).
4. The pivot pin (11) of the outer poles is tapped on its outer end. The thread size is \#8-32. A \#8-32 screw may be used to engage the threads and drift out the pin. If no screw is available, the pin may be pushed out from its inner end.
5. After the pivot pins have been removed from the outer poles, the outer movable contact assemblies may be pulled free of the crossbar assembly (10). A small amount of force will be required to do this as springs (8) and (14) will offer some resisting force.
6. The crossbar assembly (10) may now be removed from the center pole contact assembly. Again, the retaining forces of springs (8) and (14) must be overcome. The pivot pin (11) of the center pole is shorter than its counterpart in the outer poles and does not engage the bracket on the crossbar assembly.
7. If spring clip retainer (9) has not already been removed, it may now be pulled off and the center pole pivot pin (11) drifted out, freeing the contact assembly.

REASSEMBLY
Reassembly is accomplished by reversing the procedure of disassembly. Important factors to remember in performing the reassembly are as follows:

1. The stationary contacts must be arranged in the pole units as shown in sections $A-A$ and $B-B$ of Fig. 3. Note the position of the back projection of each contact. If the contacts are not arranged as shown, the back of the contacts will bear against the stud supports, causing possible damage to the contacts or failure of the breaker to latch in, when the breaker is closed.
2. In replacing the stationary contacts, first place the hook on the end of the contact in the hole of the contact spring (19), then push sidewise until the back projection on the opposite end of the contact can be slipped behind the stop pin in the center of the contact assembly.
3. The adjustment of contact wipe will be facilitated by following the procedure outlined under "Contact Adjustments" of these instructions.
4. When reassembling the crossbar assembly, the crossbar shields should be located with respect to the asbestos pole shields as shown in Fig. 4. If the crossbar shields are not located as shown, breakage may occur when the breaker is operated.

CONTACT SPRINGS (19)
A minimum force of 5 lbs and a maximum force of 9 lbs. should be required to begin movement of a single stationary contact from the open position towards the closed position. This may be checked by using a push scale applied at the point at which the movable contact touches the stationary contact. If these pressures are not obtained or if the spring is damaged, replacement is required.

In order to replace the contact spring the upper stud (17) must be removed. The hardware which fastens the stud to the breaker base consists of two screws (16), and nut (20). When these are removed, the stud may be withdrawn from the base in a forward direction. After the stud has been removed, it is a simple matter to disconnect the two ends of the spring (19) and replace it with a new one.

MECHANISM
The AK-2 breaker mechanism is a spring actuated, over-center toggle type of mechanism. As the closing force is applied, either by movement of the operating handle or the closing solenoid armature, energy is stored in the operating springs. After the springs have gone over center, movement of the output crank of the mechanism is still blocked for a time by a cam arrangement. As the springs are
further extended, the blocking cam moves away from the output crank, and the springs are allowed to discharge part of their stored energy, closing the breaker contacts.

This assures a fast-snapping closing action regardless of the speed at which the closing handle is operated.

The breaker mechanism is tripped by the displacement of the trip latch (7), Fig. 6. Looking at the breaker from the right hand side as in Fig. 5, the tripping movement of the latch is counterclockwise. Operation of any of the automatic trip devices or the trip push button causes the latch to move in the tripping direction. When the latch moves off the trip latch roller (7), the remaining force in the operating spring causes the mechanism toggle to collapse, resulting in the opening of the breaker contacts.

## ADJUSTMENT

Since all the mechanism adjustments are carefully set by experienced factory personnel after assembly at the factory, it should normally not be necessary to make any adjustments in the field. At the time of installation, and also in the course of a maintenance inspection, if the breaker functions properly through several repeated operations, it is best to assume that adjustments are satisfactory.

If the breaker mechanism does not function properly, it is best to first perform the available remedial measures listed in the "Trouble Shooting" chart of these instructions. One of the remedies listed is that of proper mechanism latch engagement, the amount of engagement between the latch (7) and latch roller (5), Fig. 6. This is the only adjustment that is required on the breaker mechanism, and proper latch engagement is obtained in the following manner:
(NOTE - Before making latch adjustments, check to make sure that the buffer paddle which stops against the end of the latch adjustment screw is rigidly fastened to the trip shaft. Hold the trip shaft (8), Fig. 5, steady and attempt to move the buffer paddle. If any relative movement between the two is noted, tighten the fasteners holding the buffer paddle to the trip shaft.)

## Latch Adjustment - Manual Breakers

1. Locate the latch adjustment screw on the lower, outer side of the right-hand mechanism side frame. This screw is threaded through a nylon insert locknut which, in turn, is welded to a projecting bracket on the side frame.
2. Rotate the closing handle 90 degrees counterclockwise, setting the closing mechanism in the reset position. Turn the adjusting screw into the locknut until the closing mechanism trips open, the closing handle returning to its normal vertical position. NOTE: KEEP HANDS CLEAR OF THE CLOSING HANDLE WHEN MAKING THIS ADJUSTMENT.
3. Withdraw the adjusting screw from the locknut $1 / 4$ turn at a time, attempting to close the breaker after each $1 / 4$

4. Are Quencher Retainer
5. Cut off Switch
6. Cut off Switch Actuator
7. Spring Carrier
8. Shoulder Pin
9. Connecting Link
10. Trip Latch Roller
11. Trip Shaft

8A. Front Escutcheon
9. Closing Solenoid

9A. Location of Slots For Maintenace Handle
10. Closing Solenoid Armature
11. Cover Retainer of Overload Device
12. Lower Stud
13. Socket Head Screws
14. Upper Stud
15. Stationary Contacts and Springs
16. Arc Runner

Fig. 5 Cut Away Model of Electrically Operated AK-2 Breaker
turn, and observing whether the contacts move toward closing before tripping occurs. If the contacts move before tripping occurs, you have established the position of the adjusting screw where the latch and latch roller begin to engage. In some cases, it may be necessary to turn the adjusting screw less than $1 / 4$ turn in order to establish the position where the contacts begin to move before tripping occurs. When this position is established, note the position of the slot in the head of the adjusting screw.
4. Withdraw the adjusting screw three and one-half turns from the position noted in step 3. This sets the proper amount of latch engagement.

## Latch Adjustment - Electrical Breakers

1. Locate the latch adjustment screw on the lower, outer side of the right mechanism side frame. This screw is threaded through a nylon insert locknut which, in turn, is welded to a projecting bracket on the side frame.
2. With the breaker in the open position turn the adjusting screw into the locknut one complete turn at a time, closing the breaker after each complete turn of the adjusting screw, until the breaker will not close. Use the maintenance closing handle whenever closing or attempting to close the breaker during this entire operation.
3. Withdraw the adjusting screw from the locknut $1 / 4$ turn at a time, attempting to close the breaker after each $1 / 4$ turn, and observing whether the contacts move toward closing before tripping occurs. If the contacts move toward closing before tripping occurs, you have established the position of the adjusting screw where the latch and latch roller begin to engage. In some cases, it may be necessary to turn the adjusting screw less than $1 / 4$ turn to establish the position where the contacts move before tripping occurs. When this position is established, note the position of the slot in the head of the adjusting screw.
4. Withdraw the adjusting screw three and one-half turns from the position noted in step 3. This sets the proper amount of latch engagement.

Should the mechanism continue to function improperly after the proper latch engagement has been set and the corrective measures listed in the "Trouble Shooting" chart carried out, it is generally recommended that no attempt be made to repair the mechanism interior but that a replacement mechanism assembly be obtained from the factory.

## REPLACEMENT

1. If the breaker is electrically operated, remove the front escutcheon by taking four screws from flange. If the breaker is a drawout type, two small round head screws must also be removed from the bottom edge of the escutcheon. (For removal of front escutcheon from manually operated breakers, see procedure described below.)

2. Arc Quencher Muffler
3. Ceramic Side Plates
4. Steel Plates
5. Fixed Centers in Mechanism
6. Latch Roller
7. Escutcheon
8. Trip Latch
9. Handle Return Spring
10. Overload Device
11. Series Coil of Overload Device
12. Trip Arm of Overload Device
13. Trip Paddle
14. Movable Contact Pivot Support
15. Crossbar
16. Movable Contact Pivot
17. Contact Wipe Adjustment Pin
18. Movable Contact
19. Moulded Compound Base
20. Steel Back Plate

Fig. 6 Cut Away Model of Manually Operated AK-2 Breaker
2. Remove arc quenchers (see "Arc Quencher").
3. Disconnect the two insulated connecting links between the mechanism and the contacts as in step 2 of the procedure for "Separation of Front and Back Frames".
4. Remove the two elastic stop nuts, which fasten the upper extensions of mechanism frame to studs connecting with rear frame.
5. Remove four screws which fasten the bottom of the mechanism frame to the horizontal cross member of the front frame.
6. If the breaker is manually operated, and has no auxiliary switch, it is now free to be lifted clear of the breaker. If it has an auxiliary switch, this may be disconnected from the mechanism as described under "Auxiliary Switch - Replacement, elsewhere in these instructions.
7. If the breaker is electrically operated, it will be necessary to disconnect the mechanism from the solenold armature In order to do this, raise the mechanism as far as the travel of the armature will permit and remove the screw which binds together the two extensions of the armature. After this is removed, the armature extensions must be spread apart to release them from the link connecting with the mechanism. This can be done by threading a $110-32$ screw at least $13 / 4$ inches long into the top hole of the armature extension. This hole is just above the one from which the binding screw has been removed. As the end of the screw butts against the far extension, the two extensions will be spread open, releasing the mechanism link.
8. The replacement mechanism may be installed by reversing the order of procedure for disassembly. After reassembly, check the operation of the breaker and, If necessary, adjust the latch engagement.

## REMOVAL OF FRONT ESCUTCHEON OF MANUAL BREAKERS

1. Remove set screw fastening the plastic handle to steel operating shaift and remove the operating handle.
2. Open and remove annealed (soft) retainer and two flat washers from shaft.
3. Remove four screws from flange of escutcheon. If. the breaker is a drawout type, two small round head screws must also be removed from the bottom edge of the escutcheon.
4. Push steel operating shaft through escutcheon bushing.
5. Remove handle reset spring (8) Flg. 6, and escutcheon is iree of breaker.
6. Handle and escutcheon assembly can be assembled most easily by exactly reversing the procedure for disaasembly. In replacing the excutcheon it may be necessary to use pliers to pull the operating shaft fully into the escutcheon in order to have space enough to replace the flat washers and the soft retainer. The latter may be closed on its groove in the shaft by ordinary gas pliers. After replacement, check operation of breaker.

## AUXILIARY SWITCH

The auxiliary switch is mounted on the left side of the operating mechanism frame. Its operating shaft is IInked to the output crank of the breaker mechanism. Through a cam arrangement, the operating shaft of the switch controls the open and closed positions of the individual contact pairs. Each stage of the switch, which is usually two-stage or five-stage, contalns one " $a$ " and one " $b$ " set of contacts. An "a" pair of contacts is always in the same position as the main breaker contacts. That is, open when the breaker contacts are open, and closed when the -breaker contacts are closed. Just the opposite is true of the " $b$ " contacts. The terminals of the switch are covered by a
sheet of insulating material held in place by two screws fastened along its left edge. When this is removed, the terminals are exposed. The upper pairs of terminals are those which connect to "a" switches. The lower terminals connect to "b" switches.

## REPLACEMENT

1. Remove auxiliary switch cover.
2. Disconnect leads to switch terminals.
3. Remove two screws which fasten switch to side of mechanism frame.
4. Remove switch by moving towards left.
5. Before mounting replacement switch, turn the crank end of the switch operating shaft in position to engage the hole in the link connecting with the breaker mechanism. Be sure the bearing washer is in place between the mechanism link and the switch operating shaft.
6. Complete mounting by following disassembly steps in reverse order.

## ELECTRICAL CONTROL COMPONENTS

These consist of the following:

1. Closing solenoid
2. "X" contactor (relay)
3. "Y" permissive relay
4. Cut-off switch
5. Closing switch
6. Shunt-trip device

The last two of these components may or may not be present in the control arrangement.

## CLOSING SOLENOID

The closing solenoid consists of a magnet, armature and coil. This assembly is located directly beneath the breaker mechantsm to which it is connected by a link which ties the upper end of the armature to the spring carrier of the mechanism. (See Fig. 5.)

When voltage is applied to the coil, the magnetic force generated pulls the armature up into the coil and magnet assembly. This, in turn, rotates the spring carrier about its plvot, extending the mechanism spring and causing its line of action to move "over center", resulting in a closing operation.

## REPLACEMENT

The only replacement operation that might conceivably be required on this assembly is that of the solenoid coil. To replace this, proceed as follows:

1. Remove escutcheon by unfastening four flat head screws in flange.
2. Remove closing switch. (See "Closlng switch",
3. Cut off or disconnect the coll leads,
4. Remove four screws which fasten lower section of magnet to upper section.
5. Allow lower section of magnet and coll to slide downward until clear of armature.
6. Reassemble with new coll by rew versing order of procedure.

## "X" CONTACTOR

The "X" contactor is a heavy-duty relay which performs the function of closing the circuit of the breaker solenoid during electrical operations. Three of the four sets of contact of the device are arranged in series to minimize the duty required of any one contact. As. explained under "Operation", the fourth contact is used to "seal-In" the "X" coil.

The "X" contactor is located on the right beneath the horizontal front frame member. It is mounted on three studs which fasten it to a mounting bracket which is suspended from the irame. Rubber bushings on the mounting studs provide anti-vibration and anti-shock protection for the relay. The relay contacts and their terminals are covered by a moulded plece of insulation. which fits over spring clips that hold the cover in place.

## REPLACEMENT

Removal of the complete device is accomplished by removing the cover, disconnecting the leads from the terminals, and removing the nuts from the three mounting studs. If the replacement unit includes the mounting bracket, the rolay need not be removed from the old bracket. This can be taken off the breaker simply by removing the two screws which fasten it to the breaker frame. If the breaker is a drawout type, the supporting bracket of the: "Y" relay may be temporarily displaced to provide access to the screws.

Since the expendable parts of the "X" contactor are the contacts and the coll, ease of replacement of these parts has been designed into the relay. Methods of procedure are as follows:

## Contacts

## 1. Remove relay cover.

2. Remove terminal binding screw of stationary contact to be replaced.
3. Lightly pinch with pliers (pointed end) the split section of the contact which enters the hole in the compound body of the device and lift out the stationary contact.
4. With the fingers, pull forward on the spring guide of the movable contact, compressing the contact spring as far as possible.
5. With the gpring thus held, grip the end of the contact $\operatorname{str} \mathrm{lp}$ with pointed pliers, turn it through 90 degrees on its long axis, and withdrawit.
6. Replace new contacts by reversing the procedure.

Coll

1. Remove relay cover.
2. Turn the two retaining spring clips on the ends of the device through 90 degrees about their pivots.
3. Pull out the two halves of the body of the device which carry the stationary contacts. When these are clear of the frame, the armature and movable contact assembly will move aside, exposing the coil.
4. Remove the terminal screws of the coll and pull it free of its retaining spring clips.
5. Place new coll on pole piece inside of the spring clips and fasten terminals to leads.
6. Just gtart the replacement of one of the compound blocks which hold the stationary contacts into its groove in the frame.
7. Position the armature and movable contact agsembly to allow the entrance of the aecond stationary contact block.
8. When these parts are all properly allgned, with the etationary contacts under the movable contacts, push them into their gulding grooves in the frame until they bottom.
9. Rotate the retaining spring clips to the locked position, making sure that each clip is in its proper recess, and replace the device cover.
"Y" RELAY
As described under "Operation", the "Y" relay is a permiselve relay which limits to one the number of breaker closurea possible on one closing signal.

On drawout breakers, the "Y" relay mounting bracket is fastened to the right hand side member of the breaker frame by two mounting acrews.' On terminal bourd breakers, it is fastened to the rear sida of the terminal board support. The relay itgelf ts fastened to an intermediate bracket which is detachable from the main sumport. The junctures between the relay and the tntermediate bracket and between the two brackets are rubber cushioned agalnst Fibration and shock.

REPLACEMENT
U replacement of the "Y" relay becomes necessary, it may be detached from its supporting brackets by removal of the fastening hardware. The leads to the relay should be cut off as closely as possible to the soldered connections so that enough Wire will remaln for connection to the new relay. sufficient original wire will be allowed for this purpose.

After the old relay has been removed, the wire leads to the relay should be etripped of insulation to about $1 / 4$ of an tach


1. Serew
2. Spring
3. Spring
4. Pivot Pin
5. Contect (EB)
6. Contact (A)
7. Waiher
8. Hovable Contact Assembly

Fig. 7 Cut-0ff Switch
from the ends. A good mechanical connection should be made before solderlag.

After all connections are completed, the relay should again be mounted to the breaker by means of its supporting brackets and hardware.

After replacement has been completed, the relay may be checked electrically in the following manner.

1. Apply closing voltage to terminal board or secondary disconnects.
2. Push button of closing switch and hold closed.
3. Continuing to hold push button in closed position, manually trip the breaker oper.
4. If the breaker stays open, and makes no attempt to close, the "Y" relay is functioning properis.
5. While releasing the close button, observe the "Y" relay. It should open as the closing switch ts released.

CUT-OFF SWITCH, FIG. 7
As explained under "Operation", the function of the cut-off switch is to deenergize the " $X$ " contactor coll and energixe the "Y" relay coll as the breaker mechanism moves from the opened to the closed posttion.

The switch is operated by the novement of a mechanism link against the switch actuator (6). This causes the actuator and movable contact assembly (4) to rotate counterclockwise about pin (7), opening the "bb" contacts (8) and closing the "aa"
contacts at (9). Overtravel of the actuator (B) beyond the point of making contact at (9) is absorbed by spring (5) which couples the movable contact (4) to the actuator. Spring (3) resets the switch after the breaker contacts open and the breaker mechanlom resets.

The polnt at which the cutoff switch operates during the breaker closing cycle is after the spring charged mechanism has been driven over-center. This assures that the cutoff switch cannot operate too early in the breaker cloaing cycle, thus the $X$ and $Y$ relays are de-energized and energized, respectively, at the proper time and the ctrcuits antl-pump feature is malntained. When the closing mechanism is driven over-center, the force of the previously charged closing aprings is released, closing the breaker.

REPLACEMENT
The cut-off switch is located above the breaker mechanism. It is fitted between the upper portions of the steel slde plates that make up the mechanism frame. A raised horisontal ridge on each side of the moulded body of the ewitch fits into a corresponding groove in each of the steel side plates. A round head screw on each aide lastens the switch and side plate together. Replacement of the switch Ls accomplished by the following procedure:

1. Remove the cover on the top of the switch by taking out the two screws which hold it in place.
2. After taking careful note of the connection arrangement, disconnect the leads from the switch terminals.
3. Remove the two screws, one on each side, which fasten the switch to the mechanism side plates. Note that the one on the right hand side also holds a wiring cleatand spacer which aerves to hold the wires clear of the link connecting the mechanism and the breaker position indicator.
4. Remove the front escutcheon from the breaker.
5. Slide the cut-off switch out from between the steel side plates by pulling straight forward.
6. Mount the replacement switch by reversing the order of procedure.

## CLOSING SWITCH, FIG. 8

The closing switch is mounted on the upper flange of the closing solenoid coil. A hole in the escutcheon (3) permits access to the switch button (4): When the button ts pressed, movable contact (5) deflects and Implnges upon gtationary contact (2). This energizes the "X" relay coth. which geals itself in, and, in turn, energizes the closing solenold.

## REPLACEMENT

1. Remove escutcheon (3).
2. Disconnect leads from switch terminals.
3. Deflect the left end of hinge (7) to the left so that the movable contact (5) may be disengaged from the switch assembly,
4. Removal of the two screws (10) Iromispeednuts (9) completes the disassembly of the switch.
5. Reassembly with new parts is a matter of reversing the described pro:cedure. In reassembling, be sure the tab on the left end of hinge (7) is bent to the right far enough to avoidany possibility that movable contact (5) might become free of the assembly.

## SHUNT TRIP DEVICE,

 FIG. 9The shunt tripping device is mounted underneath the horizontal cross frame member, just to the left of the front escutcheon. It la composed of a magnet, coil and armature. Thearmature has an extended arm or striker (11) which bears against the trip paddie (12) on the trip ghaft when the coil (8) is energized, This displaces the trip latch in the breaker mechanism, opening the breaker contacts.

The trip device is generally activated by a remote switch or relay which closes the shunt trip coll circuit.

In order to avoid unnecessary heating of the coil of the device, an auxiliary ewitch of the contact is wired in series with the coll This prevents the energization of the collif the breaker is open.

## REPLACEMENT

The entire ohunt trip devlce may ho dismounted by disconnecting the coll leads pind removing nuts (1). However, the only part of the device that might concelvably


1. Insulaticn
2. Stationary Contact
3. Front Escutcheon
4. Push Button
5. Spring
6. Hinge
7. Closing Solenoid
8. Speed Mut
9. Screw

Flg. 8. Closing, switch (Top Ylow)


1. Hut
2. Frame
3. Spring
4. Rivet
5. Waight
6. Serema
7. Armature Arm
8. Trip Paddle
9. Mechandsm Frame
10. Trip Shaft Clemp

Fig. 9 Shunt Trip Device
need replacement during the life of the breaker is the coil (8). This may be replaced without removing the device from the breaker by proceeding as follows:

1. Disconnect leads of coil (8).
2. Remove two screws (6) which fasten magnet (7) and coil to the frame (2).
3. Having removed the magnet from the device, straighten the end of clamp (9).

An AK-2-15 or AK-2-25 breaker may be equipped with any combination of the following protective devices:

1. Overcurrent trip
2. Reverse current trip
3. Undervoltage trip
4. Bell alarm and/or lockout attachment.

## OVERCURRENT TRIP DEVICE

The typical overcurrent trip device consists of a magnetic structure, a series current coil, and a pivoted armature.

When current flow through the series coil generates a magnetic field strong enough, the armature overcomes the restraining force of a calibration spring attached to it, and closes against the magnet. This trips the breaker by means of an extension on the armature which strikes against a trip paddle on the trip shaft.

Depending on the type of individual device, the movement of the armature may be delayed for a time by a timing deyice. If a relatively long time-delay (seconds or minutes) is desired, the velocity of armature movement is governed by a piston moving through an oil dashpot. If only a short-time delay (cycles or milli-seconds) is required, movement is controlled by an escapement gear and palletts arrangement.

An AK-2-15/25 breaker may be equipped with either the EC-2 or EC-1 overcurrent trip device. The majority of applications will require the use of the EC-2 device. The EC-1 device is normally used when the short-time delay feature is required, or when the trip device is used to operate a special overcurrent alarm switch.

Most circuit breakers are equipped with series overcurrent trip devices either of the dual magnetic type (instantaneous and time delay tripping) or instantaneous alone. Breakers are designed to carry up to $100 \%$ of the continuous current rating of their trip devices. Any attempt to carry higher currents for a prolonged period will cause overheating and possible damage.

## EC-2 OVERCURRENT TRIP DEVICE

The Type EC-2 overcurrent tripping device is available in three forms:

1. Dual overcurrent trip, with longtime delay and high-set instantaneous tripping.
2. Low-set instantaneous tripping.
3. High-set instantaneous tripping.
4. Remove the coil from the magnet.
5. Install new coil, again forming end of clamp (9) as shown.
6. Reassemble to frame.
7. Connect coil leads.

## ADJUSTMENT

The only adjustment required on the shunt trip device is that which ensures
positively that the breaker will trip when the device is activated. In order to be sure of this, armature arm (11) must travel from $1 / 32$ to $1 / 16$ of an inch beyond the point at which the bieaker trips. A good method of checking this is to hold a $1 / 32$ nd shim between the magnet and armature at (10), and with the breaker closed, push upwards at (5), closing the armature against the magnet. If the breaker trips, there is sufficient overtravel. If adjustment is necessary, trip paddle (12) may be formed towards or away from armature arm (11).

## PROTECTIVE DEVICES

The dual trip has adjustable long-time and instantaneous pick-up settings and adjustable time settings. Both forms of instantaneous trips have adjustable pick-up settings.

DUAL OVERCURRENT TRIP, WITH LONGTIME DELAY AND HIGH-SET INSTANTANEOUS TRIPPING.

By means of the adjustment knob (5), Fig. 10, which can be manipulated by hand, the current pick-up point can be varied from 80 to 160 percent of the series coil rating. The indicator and a calibration plate (4), Fig. 10, on the fronit of the case provide a means of indicating the pick-up point setting in terms of percentage of coil rating. The calibration plate is indexed at percentage settings of $80,100,120,140$ and 160.

The long-time delay tripping feature can be supplied with any one of three timecurrent characteristics which correspond to the NEMA standards maximum, intermediate and minimum long-time delay
operating bands. These are identified as 1A, 1B and 1C characteristics, respectively. Approximate tripping time for each of these, in the same order are 30,15 and 5 seconds at $600 \%$ of the pick-up value of current. (See time-current characteristic curves $286 \mathrm{~B} 201 \mathrm{~A}, \mathrm{~B}$ and C).

The tripping time may be varied within the limits shown on the characteristic curves by turning the time adjustment screw (5), Fig. 11. Turning in a clockwise direction increases the tripping time; counter-clockwise motion decreases it. The dashpot arm (7), Fig. 11, is indexed at four points, max. $-2 / 3-1 / 3-\min$. from the left, as viewed in Fig. 11. When the index mark on the connecting link (8), Fig. 11, lines up with a mark on the dashpot arm, the approximate tripping time as shown by the characteristic curve is indicated. The 1A and 1B characteristic devices are shipped with this setting at the $2 / 3$ mark and the 1 C characteristic at the $1 / 3$ mark. The standard characteristic curves are plotted at the same settings.


1. Series Coil
2. Trip Adjustment Screw
3. Opening for Time Adjustment
4. Pickup Indicator \& Calib. Plate
5. Pickup Adjustment Knob

Fig. 10 EC-2 Overcurrent Trip


1. Instantaneous Calibration Spring
2. Movable Nut (Index Pointer)
3. Time-Delay Calibration Spring
4. Instantaneous Pickup Adjustment Screw
5. Time-Delay Adjustment Screw
6. Oil Dashpot
7. Dashpot Arm
8. Connecting Link
9. Instantaneous Pickup Calibration Marks


Fig. 12 EC-I Type Overcurrent Trip Device
to the Time values are inversely proportional To the effective length of the dashpot arm. the shortest time value is the one at which dimension "A", Fig. 11, is greatest. The time adjustment screw (5), Fig. 11, may be turned by inserting a Phillips head screwdriver through the hole in the front of the case, but if it is desired to relate the linkage setting to the index marks on the linkage It will be necessary to remove the case. This may be done by removing the two mounting screws; one on each side of the case, which may be taken off without disturbing the trip unlt itaelf.

NOTE: Forcing the adjusting screw to either extreme position may cause binding of the device and should be avoided.

## INSTANTANEOUS LOW-SET TRIPPDG

The low-set instantaneous pick-uppoint may be varied by the adjuatment knob (5), Fig. 10. The calibrationin this case usually ranges from $80 \%$ to $250 \%$ of the series coll rating, the callibration platiebeing indexed at ralues of $80 \%, 100 \% .150 \%, 200 \%$ and $250 \%$ of the rating.

## INSTANTANEOUS HIGH-SET TRIPPING

The high set ingtantaneous pick-up value may have one of the following three ranges: 4 to 9 times coll rating 6 to 12 times cofl rating or 9 to 15 times coil rating. The pick-up setting may be varied by turning the instantaneous trip adjusting screw (4), Fig. 11.

Three standard callbration marks will appear on the operating arm at (9), Fig. 11,
and the value of these calibration marks will be indicated by stampings on the arm as follows:

| 4X |  | 6X |  |  |
| ---: | ---: | ---: | ---: | ---: |
| 6.5X | or | 9X | or | $12 X$ |
| $9 X$ |  | $12 X$ |  |  |
| $15 X$ |  |  |  |  |

At the factory, the pick-up point has been set at the nameplate value of the instantaneous trip current. (Usually expressed in times the ampere rating of the trip cotl.) The variation in pick-up setting is accomplished by varying the tensile force on the instantaneous apring. Turning the adjustment screw changes the position of the movable nut (2), Fig. 11, on the screw. The spring is anchored to this movable nut so that when the position of the nut is changed, there is a corresponding change in the spring load. As the spring is tight ened, the pick-up polnt is increased. The top edge of the movable nut (2), Fig. 11, serves as an index pointer and should be calibration wark, punched of the destred callibration mark, punched slots on operating arm, to obtain the proper ingtantaneous trip setting

## EC-1 OVERCURRENT TRIP DEVICE

The EC-1 device can be provided with the following tripping combinations:

1. Long time delay, short time delay and instantaneous tripping.
2. Long time and short time delay
3. Series Coil
4. Hagnet
5. Pallet
6. Pinion
7. Escape Wheel
8. Driving Segment
9. S.T.D. Armature
10. S.T.D. Calibration Spring
11. Trip Arm
12. Trip Paddle
13. Trip Paddle Adjusting Screw
14. L.T.D. Armature
15. L. T.D. Calibration Spring
16. Instantaneous Trip Spring (High Set),
17. Spring Holder
18. Calibration Clanp Mut
19. Plunger
20. Cylinder (Dashpot)
21. Calibration Plate
22. Clamping Bracket
23. Long time delay and ingtantaneous tripping.
24. Short time delay and instantaneous tripping.
25. Short time delay tripping only.
26. Instantaneaus tripping only.
(a)
Adjustable (Low set)
or
Nonadjustable (Figh set)

SHORT TLME DELAY TRIPPING, FIG. 18
The armature (7) is retained by calibrating spring (8). After the magnetic force, produced by an overcurrent condition, overcomes this restralning force, the armature movement is further retarded by an escapement mechaniam which produces an tnverse time delay characteristic. The mechanism is shown in the left side view of Fig. 12.

The pickup for this device can be field set between limaits having a ratio of $2-1 / 2$ to 1 in the range of 200 to $1000 \%$ of the cofl: rating.
LONG TIME DELAY TRIPPING, FIG. 12
The armature (12), is retained by the calibration spring (13). After the magnetic force, produced by an overcurrent condition, overcomes this reatraining force, the armature movement is further retarded by the flow of silicone olf in a dashpot, which produces an inverge time delay characteristlc. The mechanism is ghown in the right slde view of Fig. 12.


## INSTANTANEOUS TRIPPING, FIG. 12

(a) Adjustable instantaneous tripping takes place after the magnetic force produced by an overcurrent condition, overcomes the restraining force of the adjustable calibration spring (13).
(b) Nonadjustable instantaneous tripping takes place after the magnetic force produced by an overcurrent condition overcomes the restraining force of a nonadjustable spring (14).

## SELECTIVE TRIPPING

Selective overcurrent tripping ts the application of circult breakers in series so that only the ctrcult breaker nearest the fault opens. Any one or combination of two or more of the preceding over-current devices may be used in a selective system. The breaker having the shorter time setting and lower pickup will trip before the breaker having the longer getting and higher pickup, provided the fault is on the part of the line protected by the breaker having the lower settIng.

For the exact characteristics and setting of each breaker in a selective system, reference should be made to a coordination chart for the particular system.

## ADJUSTMENTS, EC-1 AND EC-2

In addition to the pick-up sectings and time-delay adjustments already described, overcurrent trip devices must be adjusted for positive tripping. This adjustment is made at the factory on new breakers, but must be made in the field when the breaker meichanism or the overcurrent trip devices have been replaced.

Positive tripping is achleved when adjustment screw (2), Fig. 10, is in such a position that it will always carry the trip paddle on the trip shalt beyond the point of tripping the mechanism, when the armature closes against the magnet.

In order to make the adjustment, Ilrst unscrew trip screw (2), Fig. 10, until it will not trip the breaker even though the armature is pushed against the magnet. Then holding the armature in the closed position, advance the screw until it just trips the breaker. After this point has been reached, advance the screw two additional full turns. This will give an overtravel of $1 / 16$ of an inch and will make sure that activation of the device will always trip the breaker.

Adjustment screw (2), Fig. 10, can best be manipulated by an extended 1/4 inch hex socket wrench.

In order to gain access to the adjustment screw on the center pole overload device, it whil be necessary to remove the nameplate from the front escutcheon of the breaker. This will reveal a hole, centrally located in the escutcheon, by means of which Uhe extended socket wrench can engage the adjustment screw.

## REPLACEMENT, EC-1 AND EC-2

Replacement of either the EC-1 or EC-2 overcurrent trip devicé is accomplished by the following procedure:

1. Separate the breaker's front and back frames as described in the section under "Maintenance".
2. Remove the steel clamps which fasten the cover of the device to the back of the breaker. NOTE: Pickup settings on the cover of each device are calibrated for the specific device. When replacing covers, replace on associated device.
3. Using a $5 / 16$ inch Allen ${ }^{\text {Lead }}$ Wrench, remove the $3 / 8$ inch bolts which fasten the coil of the overload device to the breaker copper.
4. Remove the round head screw which fastens the frame of the overload to the breaker base.
5. After reassembling breaker with new overload device, adjust for "positive trip" as described under "Adjustments" of this section.

## REVERSE CURRENT TRIP DEVICE

FIGURE 14
The reverse current trip device sometimes used with d-c breakers will trip the breaker open if the direction of current flow is reversed.

This device is stmilar in appearance and is mounted in the same way as the overcurrent trip. The device consists of a series coll (1), with an iron core mounted between two pole pieces (7) and a potential coll connected across a constant source of voltage and mounted around a rotary type armature (6). Calibration spring (3) determines the armature pick-up value when a reversal of current occurs.

As long as the flow of current through the breaker is in the normal direction, the magnetic flux of the series coil and the magnetic flux of the potential coll produce a torque which tends to rotate the armature counterclockwise. The callbration spring (3) also tends to rotate the armature in the same direction. This torgue causes the armature to rest against stop screw (9) attached to a bearing plate on the rightside of the device.

If the current through the series coil (1) is reversed, armature (6) tends to move in a clockwise direction against the restraint of calibration spring (3). When the current reversal exceeds the calibration setting, the armature will move in a clockWise direction. This causes trip rod (2B) to move upwards against trip paddle (14), tripping the breaker open.

## ADJUSTMENTS

The only adjustment to be made on the reverse current device is to make sure that the trip rod has a minimum overtravel of 1/32 of an inch beyond the point of tripping the breaker. The only occasion thls adjustment should have to be made is when an old device is being replaced by a new one.

The new device will be factory adjusted so that the top end of the trip rod (2B) will extend $1 / 2$ inch above the top of the device case, and no additional adjustments of the trip rod should be required. To obtain the proper $1 / 32$ of an Inch overtravel, close the breaker and proceed as follows:

## 1. Loosen the locking nut (2A).

2. Manually lift the trip rod and vary the position of the adjusting nut (2), thus establishing the position of the adjusting nut where the breaker is just tripped. (NOTE - Be sure that all parts of the person are kept clear of moving breaker parts when tripping the breaker.
3. With this position of the adjusting nut established, advance the adjusting nut upward one and one half turns.
4. Tighten the locking nut and the minimum $1 / 32$ of an inch overtravel of the trip 5 rod should be obtained.

## REPLACEMENT

Replacement of the ED-1 Reverse Current Device is accomplished by means of the same procedure as that followed in the case of the EC Overcurrent Trip Devices. There is, however, one additional step to be taken. This consists of disconnecting the leads of the potential coil. These are connected to a small two-point terminal board mounted between two of the phases on the breaker base. After the new device has been installed, adjust for overtravel of the trip rod as described above.

## UNDERVOLTAGE <br> TRIP DEVICE

## FIGURE 15

The undervoltage device is mounted on the left side of the breaker obsisved from the front. It hangs from the left end of the horizontal cross member of the front frame. This device has the function of tripping the breaker open it the ctrcult voltage drops below a predetermined value. Since the coil (16) of the device is normally energized, the flux of the magnetic circuit normally holds armature (3): down against magnet (14). If the voltage drops below a certain percentage value of nominal voltage, the magnetic llux is no longer strong enough to overcome the force of calibration spring (4) which tents to pull the armature away from the magnet. When this occurs; the striker on the armature hits against trip paddle (23), tripping the breaker open.

The undervoltage device may or may not be equipped with a time-delay feature, depending upon requirements. This is provided by an oll dashpot (12) and piston (11). If it does have this feature, when the voltage drops below tripping value, the movement of the armature is delayed by the time it takes to displace the piston a short distance through the oil. The minimum time delay thus afforded is 3 secands. The depth of the oll in the dashpot should be $1 / 4$ to $3 / 8$ of an inch. The oll level may be checked by unscrewing cylinder (12) from its cap. If additional oil is needed, G. E. silicone oll SF96-40, or its equivalent should be used.

## ADJUSTMENTS

Adjustment screw (24) is used to provide an overtravel of from $1 / 32$ to $1 / 16$ of an inch beyond the point of tripping. It the armature is manually held down with the de-energlzed breaker in the closed position, and then allowed to gradually move to


the point of tripping the breaker, the amount of further armature movement may be noted visually. If this is approximately within the range stated, the positive trip adjustment is satisfactory.

The time delay of the device may be varied somewhat by changing the relative positions oi the connecting rod (10) and clevis (7). This is accomplished by first loosening the locking nut ( 8 ), then raising or lowering the plunger (11), by turning the connecting rod which is threaded into the clevis. When any time delay of 3 to 10 seconds exists from loss of voltage, the device is considered satisfactorily adjusted.

The value of increasing voltage at whtch the open armature will pick-up and close, allowing closure of the breaker, is determined by a sliding stop which sets the open gap of the armature. This is a factory adjustment, and should not be set in the field. The pick-up point of voltage is $80 \%$ of normal voltage.

Calibration spring (4) establishes the drop out value of voltage, which resulta in breaker tripping. This setting is made at the factory. Drop-out voltage is set at between $30 \%$ and $60 \%$ of normal voltage.

## REPLACEMENT

The entire device may be dismounted by digconnecting the coll leads and removing screw (1) and nuts (20). Normally, only the coll (16) will ever need replacement. This may be removed from the device by talsing out screws (15) which will free both the magnet (14) and the coil. Straightening of the bend in clamp (13) will separate the coil from the magnet. The coll leads, of course, must be disconsected.

## BELL ALARM SWITCH AND/ OR LOCKOUT ATTACHMENT

## FIGURE 16

The bell alarm device is mounted on top of the horizontal cross frame member just to the left of the mechanism frame when the breaker is viewed from the front. This device operates a switch with two sets of contacts, one normally open, the other normally closed. The switch may be used to open or close an external circuit, giving a bell or light Indication of a protective trip device operatton.

If the breaker is tripped open by any means other than the manual trip button or the shunt trip device, the bell alarm mechnism is activated. The alarm is shut off and the bell alarm and lockout mechanism is reset by operation of the manual trip button or shunt trip device. If the device is a bell alarm only, the bell alarm mechanism is also reset simply by closing the breaker.

## OPERATION

Lever (2) is connected to the breaker mechanism so that when the breaker opens lever (2) rotates counterclockwise about pin (14). The motion is transmitted through links (1) and (13) to paddle (12) which

1. Mounting Seret
2. Device Prate
3. Armature
4. Spring
5. Suding Ring
6. Pin
7. Clevia
8. Locking Mut
9. Cap
10. Cormecting Bod
11. Plunger (Pistor)
12. Cylinder (Dashpot)
13. C1 amp
14. Nagret
15. Screws.
16. 'Coil
17. Rivet
18. Adjusting Scret
19. Locking Wire
20. Mounting Nut
21. Mechanísm Frame
22. Trip Peddle Clamps
23. Trip Paddle
24. Adjusting Serev

Fig. 15 Underwoltage Tripping Device
operates bell alarm switch (11). If the device has, the lockout feature, the movement of link (13) also causes lockout link (8) to slide in a direction that results in its striking trip paddle (5) which, by displacement of the breaker mechanism trle latch, makes it impossible to reset the breaker mechanism untll the bell alarm mechanism is reset.

Link (6) gerves as a latch in the bell alarm mechanism. If it is displaced, thnk (10) is iree to rotate about its lower pin. This deprives the linkage of its normally fixed center of rotation about pln (15) and defeats both the bell alarm and the lockout operation. Operation of elther the manual trip button or the shunt trip device will displace latch (B) and have this effect. Thus if the breaker is tripped by either of these means, the bell alarm and/or lockout will not operate. Also, operation of either of these devices will reset the switch and inactivate the lockout.

Changes in breaker requirements may occasionally bring about the necessity of adding or changing breaker components or accessories in the field. The AK-2 breaker has been designed so that such additions or conversions are simple and easy to make, requiring only a minimum of time or skill on the part of the operator.

Spectal instructional drawings are available which will further simplify the addition of such accessories to breakers which were originally shipped without them.

These drawings will accompany the necessary material when it is shipped from the factory. They will also be avallable upon request. The drawings and the accessory additions which they cover are listed below.

When an accessory is added to a breaker, it is recommended that the section of instructions contained herein covering that particular accessory be reviewed, In addition to referring to the following instructional drawing. Any adjuatments described in these tustructions should be carefully made after the device has been assembled on the breaker.

When ordering renewal parts, address the nearest sales Office of the General Electric Company, spectifing the quantity required. Complete nameplate data of the breaker involved should be glven as well as an accurate description of the


TYPICAL CONNECTION DIAGRAM

1. Link
2. Link
3. Switch
4. Springs
. Lever
5. Trip Arm
6. Paddle
7. Spring
8. Pin
9. Lockout Link
10. Link
11. Trip Sheft
12. Frame
13. Pin
14. Pin
15. Link
and Lockout Device

## MISCELLANEOUS

Conversion of breakers from manual to electrical operation is also covered on an instructional drawing. This operation consists simply of geparation of the front and back frames of the breaker as described under "Maintenance" in these instructions and the reassembly of the existing back frame with the new front frame.

ADDITION OF

Shunt Trip Device
Auxiliary Switch
Undervoltage Device
Bell Alarm \& Lockout Device
Drawout Mechanism
Conversion to Elec. Oper.

## COVERED BY

608C800
698C901
698C902
698C903
698C922
698C904

## MAINTENANCE TOOLS

The following tools are recommended for proper maintenance of AK-2-15 and 25 breakers. (NOTE - Obtain from local hardware firm; do not order on General Electric Company.)

## RENEWAL PARTS

parts required. If the parts needed are Illustrated in this book, refer to the figure number and part number involved.

Renewal Parts which are furnished may not be identical to the original parts

## SCREW DRIVERS

Long thin, slotted screw
Standard, slotted gerew
Phillips, No. 2, (8' ${ }^{\prime \prime}$ shaft)

## PLIERS

Waldes Truarc, No. 2 , straight
Long Nose, side cutting, $6^{\text {¹ }}$.
END WRENCHES
Adjustable, $8^{\prime \prime}$
$1 / 4^{\prime \prime}$ open end
ALLEN HEAD WRENCHES
$5 / 16^{\prime \prime}$ for $3 / 8^{\prime \prime}$ screw
$1 / 8^{\prime \prime}$ for $1 / 4^{\prime \prime}$ screw"
SOCKET WRENCHES (3/8" DRIVE)
Ratchet handle
$12^{\prime \prime}$ extension bar
3/8" socket
9/16" socket
7/16" socket (long)

## MISCELLANEOUS TOOLS

1/4" Spintite (long shank)
$7 / 16^{11}$ Spintite
8/32 acrew (at least $2^{\prime \prime}$ long)
since from tlme to time deaign changes may be made. The parts supplied, however, will be interchangeable with the original parts.





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SALES OFPICE CODE KEY

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## GENERAL ELECTRIC SERVICE SHOPS


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general electric company, philadelphia, pa:


INSTRUCTIONS

# AK POWER CIRCUIT BREAKERS 

 electrically and manually operated
## TYPES

AKF-2-25
AKF-2A-25

## TYPE AKF-2 POWER CIRCUIT BREAKER

The instructions contained herein supplement Instruction Book GEI-50299 and are to be used in conjunction with it.

The AKF-2-25 breaker is a special type of AK-2 breaker. The design is intended to switch shunt field circuits of synchronous generators and synchronous motors. These breakers are usually furnished without series overcurrent tripping devices and have a continuous rating of 600 amperes. The AKF is a two pole air circuit breaker with field discharge contacts located in the center pole position.

The closing of the field discharge contacts connects a field discharge resistor across the field winding of a generator or a motor. This arrangement of main and discharge contacts allows the excitation circuit to open without inducing excessively high voltage in the field winding.

## AKF-2 <br> FIELD DISCHARGE MECHANISM <br> FIGURE 2

When an AKF-2-25 field breaker is opened, the field discharge contacts close before the main contacts of the breaker open; on closing the field discharge contacts open after the main breaker contacts close. This contact overlap prevents opening the field circuit.

The outside pole contacts (1) close when the pin through eccentric bushing (12) is driven toward the pole base by the closing mechanism. The motion is transferred througheccentric bushing (12), link (10), link (14), crossbar (6) and the contact carrier pivoting about pivot pin (3).

Before the center pole contacts (7) open there is a moment of overlap when the center pole and outside poles are simultaneously closed. The motion to the center pole is transierred through eccentric


Figure 1. (415A845) Typical Connection Diagram
bushing (12) link (10), link (14), cam follower (13), link (15), link (8), pin (20) and contact (7) pivoting about pivot pin (22).

The opposite operation of opening the outside pole contacts and closing the center pole contacts is effected by the same linkage with a reversal of motion.

The mechanism of the AKF-2-25 is a spring actuated over center toggle type of mechanism. Fefer to GEI-50299 for description of the mechanism.

## ADJUSTMENTS

The contact wipe on the outside poles is measured and adjusted by following the procedures of GEI-50299 Page 6 and 7. Proper contact wipe must be maintained between $3 / 32$ to $5 / 32$ of an inch.

The center pole is measured in the same manner as the outside poles, and must be maintained between $3 / 32$ to $5 / 32$ of an inch.

The center pole contact wipe is adjusted by shims (18). This is a factory adjustment that is not likely to require fleld service. Should shims (18) be changed, it is necessary to reposition lower pivot block (17). A check of Lower Pivot Block (17) position is made by moving cam follower (13) in circular arc section of the link cam (15). The center pole contact is closed, and does not move because circular arc of (15) and center pole movable contact (7) have a common center in pin (22).

The AKF-2-25 field breaker has overlap of contacting on all poles for both opening and closing operations. The overlap condition is achieved by adjustments to eccentric bushing (12) and eccentric pins-adjustable (2).
NOTE: The pair of eccentric bushings (12) must be set to the same position before links (10) and tie bolt (11) are replaced.

Replace the links and tie bolt, and measure contact wipes on all poles. The outside poles may have contact wipe adjusted individually by eccentric bushings (12).

Open the center pole, and press toward back frame with fingers to check slight detenting action between cam follower (13) and link-cam (15). This force is acceptable if over five pounds. Adjustment of eccentric bushing-adjustable (12) will achieve the position of the detent action for open center pole contact.

## Check all contact wipes.

Test the overlap by connecting all poles in series. Check continuity of circuit for overlap during both closing and opening operations. A gas discharge lamp or an oscilloscope can be used to detect overlap action.

> These instructions do not purpert to cover ell detaits or veriations in equipment nor to provide for evary poseible contingency to be met in conmection with installation, operation or maidenonce. Strould further informotion be desired of should particulor problens arise which are not covered aufficiently for the purchoser's purposes, the matter should be raforred to the Genered Electric Company.

)
1 MOVAELE CONTACT- OUTSIDE FOLES
2 ECENTRIC PIN-ANUSTABLE
3 PIVOT PH
4 SPRINGS
5 PIN
6 CROSS BAA
7 MOVABLE CONTACT-CEMTER FOLE
6 LINK
9 PIN
D LMKK
II TIE BOLT

12 ECCENTRIC BUShing - ADIUSTABLE
13 CAM FOLIOWER
14 LINK ANO CROSS 日AD CLAMP
IS LINK AND CAM
16 PIVOT PIN
17 IONER PIVOT BLOCK
18 strims
19 stationary contact
20 gin
21 PIN
22 fivot pin

Figure 2. (121C2873) Field Switch Mechanism and Contact Assemblies.

## ONTACT OVERLAP (See Fig. 2)

Contact overlap is a factory setting that is otained by adding or removing shims under the wer pivot block (17) during assembly. When le proper overlap is obtained the lower pivot :ock (17) is pinned at the factory and should not 3 changed in the field.

## REPLACEMENTS

:OVABLE CONTACT SPRINGS (4) (See Fig. 2)

- With contact (1) in the open position, take a screwdriver and push upward on the bottom of the "U" shaped springs (4) freeing them from pin (5) and contacts (1).
- Remove the one end of pin (5) from its mounting in the contact carrier and slide new springs (4) into proper position.

OTE: If springs (4) are not going to be changed at this time. They should be reformed to original shape before installing. To check springs place closed end of springs on a level table and measure the open end of springs to the table top. This dimension should be approximately $5 / 16$ of an inch. Form springs until this dimension is obtained.
:. With spring (4) in proper position push down on pin (5) and slide pin (5) into its mounting hole in the contact carrier.

MOVABLE CONTACTS (1,7) (See Fig. 2).

1. Remove arc quencher (See "Replacement" under "Arc Quencher", page 6 of GEI-50299).
2. Remove operating mechanism (See "Replacement" under "Mechanism", page 10 of GEI50299).
3. Remove movable contact springs (4) (see above).
4. Remove movable contacts (See "Movable Contacts" under "Contact Replacement", page 8 of GEI-50299).
5. Replace new contacts in reverse order.
6. Replace operating mechanism.
7. Adjust contact wipes. (See Adjustments).
8. Replace arc quenchers.

## STATIONARY CONTACTS (19) (See Fig. 2).

1. Remove stationary contacts (See "Stationary Contacts" under "Contact Replacement", page 7 of GEI-50299).
2. Replace contacts in reverse order (See "Reassembly" under "Contact Replacement", page 8 of GEI-50299).

GENERAL ELECTRIC COMPANY CIRCUIT PROTECTIVE DEVICES DEPARTMENT PLAINVILLE, CONNECTICUT 06062

## POWER CIRCUIT BREAKERS

TYPES

| 225 | AMP FRAME SIZE | 600 |  |  |
| :--- | :--- | :--- | :--- | :--- |
| AK-2-15 |  | AMP FRAME SIZE |  |  |
|  | AK-2A-15 | AK-2-25 | AK-3-25 | AKF-2-25 |
|  |  | AK-2A-25 | AK-3A-25 | AKF-2A-25 |
|  |  | AKU-2-25 | AKU-3-25 |  |
|  | AKU-2A-25 | AKU-3A-25 |  |  |



Fig. 1. Type AK-2-25 manually operated
power circuit breaker
ORDERING INSTRUCTIONS

1. Always specify the complete nameplate data of the breaker.
2. Specify the quantity, catalog number (if listed), reference number (if listed), description, and this bulletin number.
3. CAUTION: When local facilities for breaker recalibration are not available, the breaker should be forwarded to the nearest G-E Service Shop, or to the General Electric Company, 6901 Elmwood Avenue, Philadelphia 42, Pa.
4. Standard hardware, such as screws, bolts, nuts, washers, etc., is not listed in this bulletin. Such items should be purchased locally.
5. For prices, refer to the nearest office of the General Electric Company.


Fig. 2. Type AK-2-25 power circuit breaker back frame (operating mechanism removed)


Fig. 4. Cutaway view of type AK-2-25 electrically operated power circuit breaker


Fig. 5. Type AK-2-25 electrically operated power circuit breaker (escutcheon removed and dismantled)

| Ref. <br> No. | Quantity for 3 -pole Frame 225 Amp** | Required <br> Breaker Size 600 Amp** | Catalog Number | Description |
| :---: | :---: | :---: | :---: | :---: |
| 1 A | 1 | 1 | 227D190P1 | Back plate |
| 1 | 3 | 3 | 269C260G1 | Insulation for upper stud, rear |
| †1B | 3 | 3 | 269C260G2 | Insulation for upper stud, front |
| 2 | 3 | - | 269C283G1 | Upper stud assembly |
| 2 | - | 3 | 269C283G2 | Upper stud assembly |
| 3 | 3 | 3 | 295B460P1 | Barrier |
| * 4 | 3 | 6 | 269C257G1 | Stationary contact assembly |
| * 5 | 3 | 6 | 269 C 257 G 2 | Stationary contact assembly |
| * 6 | 3 | - | 269C257G14 | Moving contact |
| * 6 | - | 3 | 269C257G15 | Moving contact |
| *7 | 2 | 2 | 412A250 | Spring (outside poles) |
| *7A |  | 1 | 269C280P5 | Spring clip (center pole) |
| 8 | 2 | 2 | $269 \mathrm{C277P9}$ | Barrier |
| 8A | 1 | 1 | 269C277P10 | Barrier, complete (includes Ref. Nos. 8 and 8A) |
| 9 | , | 1 | $269 \mathrm{C} 277 \mathrm{G1}$ | Cross bar assembly |
| 10 | 3 | 3 | 269C258G3 | Pivot |
| *11 | 3 | 3 | $269 \mathrm{C280P8}$ | Spring (back of pivot) |
| 12 | - | 3 | 269C258G1 | Lower stud assembly (not used on AK-3 or AK-3A) |
| 12 | 3 | - | $269 \mathrm{C258G} 2$ | Lower stud assembly |
| 13 | 2 | 2 | 263C526P1 | Insulation (under lower stud) |
| 14 | 2 | 2 | 269 C 280 P 7 | Support (outside) |
| 15 | 2 | 2 | 269C280P6 | Support (intermediate) |
| 16 | 3 | 3 | 269B288G1 | Arc quencher |
| 17 | - | 1 | 121C7514G2 | Arc quencher clamp AK-3 or 3A only |
| 17 | 1 | 1 | 269 C 273 G 2 | Arc quencher clamp (sand gray) AK-2 or 2A |
| 18 | 2 | 2 | $269 \mathrm{C} 280 \mathrm{P4}$ | Stud, arc quencher clamp |
| $\dagger 19$ | 2 | 2 | 177L215P219 | Insulation for Ref. No. 18 |
| $\dagger 20$ | 2 | 2 | 393A993P9 | Stop nut for Ref. No. 18 |
| *21 | 6 | 12 | 412A286 | Stationary contact spring |
| 21A | 3 | 3 | 412 A208 | Movable contact spring |
| 21B | 6 | 6 | $269 \mathrm{C277P11}$ | Spring clip |
| $\dagger 22$ | 1 | 1 | 269C280P1 | Moving contact pivot pin (center pole) |
| 23 | 2 | 2 | 269C280P2 | Moving contact pivot pin (outside poles) |
| *24 | 1 | 1 | 0412A0290 | Spring |
| 25 | 1 | 1 | $622 \mathrm{C} 21 \mathrm{G1}$ | 8Magnet and armature assembly |
| 26 | 1 | 1 | See table B | 8 Closing coil |
| 27 | 3 | 3 | See note below | Overcurrent trip device |
| 28 | 6 | 6 | 386A163P1 | Clamp for EC-2 trip device |
| 28 | 3 | 3 | 6555445P1 | Clamp for EC-1 trip device |
| 29 | - | 6 | 269C281P5 | Retaining ring |
| 29 | 3 | - | $269 \mathrm{C281P6}$ | Retaining ring |
| 30 | 3 | 3 | 845 C 276 G 2 | Primary disconnect assembly |
| 30 | - |  | $845 \mathrm{C} 276 \mathrm{G4}$ | Primary disconnect assembly |
| 30A | 6 | 6 | 412 A222 | Spring |
| 31 | 12 | 12 | 269C281P3 | Retainer |
| *32 | 24 | 24 | 453A100P2 | Contact finger |
| 33 | 6 | - | 453A129P1 | Retainer |
| 33 | - | 6 | 453A129P2 | Retainer |
| 34 | 6 | 6 6 | 457A681P4 | Spacer ${ }_{\text {Screw, }}$ hex, hd, $1 / 4 \mathrm{in}$, -20 by $31 / 2 \mathrm{in}$. |

* Recommended for stock for normal maintenance.
$\dagger$ Not shown.
** See breaker nameplate for frame size.


## $\delta$ Electrically operated breakers

Note for overcurrent trip devices:
(1) No parts furnished for field installation on EC-1 trip devices.
(2) Only part furnished for field installation on EC-2 or EC-2A trip devices is plastic cover, Cat. No. 242C645P1.
(3) When replacement trip devices are ordered, it is imperative that order includes complete nameplate reading of the breaker or breakers involved and, if a contemplated ampere rating change is involved, the order should also include information as to ampere rating, time-current characteristic, and instantaneous trip setting desired.
Note for operating mechanisms:
(1) Individual parts cannot be furnished for operating mechanisms.
(2) When replacement is necessary give complete nameplate reading when ordering.

| Ref. No. | Quantity R for 3+pole Frame 225 Amp** | Required Breaker Size 600 Amp** | Catalog Number | Description |
| :---: | :---: | :---: | :---: | :---: |
| 36 | 4 maximum | 4 maximum | 386A110G2 | Movable secondary disconnects (drawout breaker) |
| 37 | 1 | 1 | 622C505G1 | Cutoff switch (electrically operated breaker) |
| 38 | 1 | 1 | 432A671G2 | Auxiliary switch, 2 stages |
| 38 | 1 | 1 | 432A671G5 | Auxiliary switch, 5 stages |
| 39 | 1 | 1 | 269C268P1 | Manual trip button |
| 139A | 1 | 1 | 269C268P12 | Trip label |
| $\dagger 40$ | 1 | 1 | 412A133 | Spring for manual trip button |
| 41 | 1 | 1 | 622C502G1 | Shunt trip device with coil |
| 42 | 1 | 1 | 622C529G1 | Closing switch |
| 43 | 1 | 1 | 101C7891G1 | Shaft assembly (Manual Breaker only) order Ref. 43 and 43A together |
| †43A | 1 | 1 | 101C7891G2 | Link assembly |
| 44 | 1 | 1 | 259C607G1 | Escutcheon, manual breaker (black) |
| 44 | 1 | 1 | 259C607P10 | Escutcheon, electrically operated breaker (black) |
| 44 | 1 | 1 | 259C607G2 | Escutcheon, electrically operated breaker (with handle) (black) |
| $\dagger 44$ | 1 | 1 | 259C607G3 | Escutcheon, manual breaker (blue) |
| $\dagger 44$ | 1 | 1 | 259C607P11 | Escutcheon, electrically operated breaker (blue) |
| $\dagger 44$ | 1 | 1 | 259C607G4 | Escutcheon, electrically operated breaker (blue) with pistol grip handle |
| 45 | 1 | 1 | 259C608G1 | Indicator |
| 46 | 1 | 1 | 276B191P1 | Handle (black) |
| 46 | 1 | 1 | 669D807P1 | Handle (gray) |
| 47 | 1 | 1 | ---.-----* | 'X' relay (see Table A, page 6) |
| * 48 | 1 | 1 |  | "Y" relay (see Table A, page 6) |
| $\dagger 49$ | 1 | 1 | 148A2238 | Return spring, rear of escutcheon |
| $\Delta^{*} 50$ | 1 | 1 | 295B445P221 | Stationary contacts, " $X$ ' relay <br> On early AK-2-15, AK-2-25 and |
| $\Delta^{*} 51$ | 1 | 1 | 295B445P222 | Moving contacts, 'X' relay AKF-2-25 with no suffix number |
| $\dagger{ }^{\dagger}{ }^{\text {¢ }}$ | 1 | 1 | 295B445P223 | Springs, moving contacts, 'X' relay \} AKF-2-25 with no suinix number |
| $\dagger{ }^{\text {¢ }}$ * 52 A | 1 | 1 | 116B7197P221 | Stationary contacts, 'X'' relay |
| $\dagger \triangle * 52 \mathrm{~B}$ | 1 | 1 | 116B7197P223 | Molded moving arm, 'X' relay (with moving contacts) all others |
| $\dagger \triangle 52 C$ | 1 | 1 | 116B7197P222 | Armature return spring, ' $X$ '' relay \| |
| $\Delta^{*} 53$ | 1 | 1 | ---------- | Operating coil, " $\mathrm{X}^{\prime}$ ' relay (see Table A, page 6) |
| $\triangle 54$ | 1 | 1 | 622 C 501 P 1 | Cover, 'X'' relay ( On early AK-2-15, AK-2-25 and AKF-2-25 |
| $\triangle 55$ | 1 | 1 | $622 \mathrm{C} 501 \mathrm{P2}$ | Jumper, 'X' relay $\}$ with no suffix number |
| * 56 | 1 | 1 | --------- | Coil for shunt trip device (see Table B, page 7) |
|  | 1 | 1 | 269C282G2 | $\ddagger$ Instantaneous undervoltage device, a-c (with coil) |
|  | 1 | 1 | 269C282G5 | $\ddagger$ Instantaneous undervoltage device, d-c (with coil) |
| 57 | 1 | 1 | $\ddagger$ | Time-delay undervoltage device, a-c |
| 57 +58 | 1 | 1 | $\ddagger$ | Time-delay undervoltage device, d-c |
| * 58 | 1 | 1 |  | Coil for undervoltage device (see Table 8 , page 7) |
| 59 ++60 | 1 | 1 | ه | Static time delay, a-c or d-c (replaces complete time delay and volt device coil only) |
| * $\dagger 60$ | 1 | 1 | 6172594 | Spring, for undervoltage device |
| 61 | 1 | 1 | 269C299G2 | $\ddagger$ Bell alarm device |
| 62 | 1 | 1 | 6293908G275 | Terminal board, 6 terminals |
| 62 | 1 | 1 | 6293908G274 | -Terminal board, 10 terminals |
| 63 | 1 | 1 | 846C865G1 | Link and bushing for auxiliary switch |
| 64 | 1 | 1 | 6314936P1 | Cover for auxiliary switch, 1 stage |
| 64 | 1 | 1 | 6314936 P 2 | Cover for auxiliary switch, 2 stages |
| 64 | 1 | 1 | 6314936 P 3 | Cover for auxiliary switch, 5 stages |
| 65 | 3 | 3 | 295B475P2 | Base for wall mounted, general purpose breaker |
| 66 | 3 | - | 394A144P1 | Angle for wall mounted, general purpose breaker |
| 67 | 6 | - | 275B995P1 | Terminal for wall mounted, general purpose breaker |
| 67 | - | 6 | 695C131P1 | Terminal for wall mounted, general purpose breaker |
| 68 68 | 6 | $\bar{\square}$ | 394A106P1 | Cable clamp for wall mounted, general purpose breaker |
| 68 69 | 1 | 6 | 457A673G1 | Cable clamp for wall mounted, general purpose breaker |
| 69 | 1 | 1 | 269C276G2 | Maintenance handle |

* Recommended for stock for normal maintenance.
** See breaker nameplate for frame size.


## $\dagger$ Not shown.

$\ddagger$ If at any time a breaker is to have added to it either shunt trip, undervoltage device, or bell alarm device, the order for the device must include the following information:
(1) Complete nameplate reading of breaker involved.
(2) Desired voltage rating of device, whether a-c or $d-c$, and if a-c, the frequency.
(3) In the case of undervoltage devices, specify whether instantaneous or time delay.
$\Delta \mathrm{On}-1$, specify Cat. No. of ' X ' relay when ordering these parts.
$\Delta$ Order by circuit breaker Serial No.



Fig. 14. Manual (left) and electrical (right)
front frame assemblies for
Type AK-2-15 and -25
power circuit breakers
NOTES FOR FIG. 14:
(1) Should it become necessary to replace the complete front frame of the breaker, it is necessary that the order include complete nameplate reading of existing breaker.
(2) If an existing manual breaker is to be converted to electrical operation, the order must include, in addition to complete nameplate reading, a description of desired change and complete voltage and frequency rating of both closing and tripping circuits.

TABLE A

| Rating |  | Catalog Number"X" Relay |  |  |  | "Y'" Relay <br> Complete <br> (Ref. 48) <br> § |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |
| Volts | Cycles | Relay Complete, Ref. | Coil, only (Ref. 53) | Relay Complete, Ref. 47 | Coil, only (Ref. 53) |  |
|  |  | $\text { for } \begin{array}{r} \Delta \mathrm{a} \\ \mathrm{Br} \end{array}$ |  | $\begin{array}{r} \text { for Late }-1, \\ \text { Brea } \end{array}$ | $a l l-2$ |  |
| 24 | D-C | 295B445P1 | 295B445P201 | 116B7197P1 | 116B7197P201 | 295B444P1 |
| 48 |  | 295B445P2 | 295B445P202 | 116 B 7197 P 2 | 116B7197P202 | 295B444P2 |
| 125 |  | 295B445P3 | 295B445P203 | 116 B 7197 P 3 | 116B7197P203 | 295B444P3 |
| 250 |  | 295B445P4 | 295B445P204 | 116 B 7197 P 4 | 116B7197P204 | 295B444P4 |
| 115 | 25 | 295B445P7 | 295B445P207 | 116B7197P7 | 116B7197P207 | 295B444P7 |
| 208 |  | 295B445P10 | 295B445P210 | 116B7197P10 | 116B7197P210 | 295B444P10 |
| 230 |  | 295B445P13 | 295B445P213 | 116B7197P13 | 116B7197P213 | 295B444P13 |
| 460 |  |  | ------------ | 116B7197P16 | 116 B 7197 P 216 |  |
| 230 | 40 | 295B445P12 | 295B445P212 | ------------ | ------------ | 295B444P11 |
| 115 | 50 | 295B445P6 | 295B445P206 | 116B7197 P6 | 116B7197P206 | 295B444P5 |
| 208 |  | 295B445P9 | 295B445P209 | 116B7197 P9 | 116B7197P209 | 295B444P8 |
| 230 |  | 295B445P12 | 295B445P212 | 116B7197P12 | 116B7197P212 | 295B444P11 |
| 380 |  | 295B445P17 | 295B445P214 | 116B7197P17 | 116B7197P217 | 295B444P17 |
| 460 |  | 295B445P15 | 295B445P216 | 116B7197P15 | 116B7197P215 | 295B444P14 |
| 115 | 60 | 295B445P5 | 295B445P205 | 116B7197P5 | 116B7197P205 | 295B444P5 |
| 208 |  | 295B445P8 | 295B445P208 | 116B7197P8 | 116B7197P208 | 295B444P8 |
| 230 |  | 295B445P11 | 295B445P211 | 116B7197P11 | 116B7197P211 | 295B444P11 |
| 460 |  | 295B445P14 | 295B445P215 | 116B7197P14 | 116B7197P214 | 295B444P14 |

[^21]

Fig 15. Accessories for wall mounting (ref. 65, 66, 67, 68)

Fig. 16. Maintenance handle for electrically operated breakers not equipped with manual handles (ref. 69)

TABLE B

| Rating |  | Catalog Number |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Closing <br> Solenoid Coil <br> (Ref. 26) | Shunt Trip Device Coil (Ref. 56) | Undervoltage Device Coil (Ref. 58) |  |
|  |  | Instantaneous |  |  |
| Volts | Cycles |  |  | Oil Dashpot Type Time Delay | Static Time <br> Delay Type |
| 24 | D-C |  | --- | 6275081G55 | $6275081 \mathrm{G15}$ | $\begin{aligned} & 6275081 \mathrm{G} 61 \pi \\ & 6275081 \mathrm{G} 59 \pi \end{aligned}$ |
| 48 |  | 366A773G17 | 6275081G28 | 6275081G9 |  |
| 125 |  | 366A773G13 | 6275081G29 | 6275081G18 |  |
| 250 |  | 366A773G15 | 6275081G30 | 6275081G19 |  |
| 115 | 25 | 366A773G3 | 6275081G26 | 6275081G12 |  |  |
| 208 |  | 366A773G6 | 6275081G29 | $6275081 \mathrm{G10}$ |  |  |
| 230 |  | 366A773G14 | 6275081G29 | $6275081 \mathrm{G10}$ |  |  |
| 460 |  | 366A773G11 | 6275081G7 | $6275081 \mathrm{G17}$ |  |  |
| 575 |  | 366A773G12 | 6275081G5 | 6275081G21 |  |  |
| 115 | 50 | 366A773G2 | 6275081G56 | 6275081 G 4 |  |  |
| 208 |  | 366A773G3 | 6275081G26 | $6275081 \mathrm{G12}$ |  |  |
| 230 |  | 366A773G5 | 6275081G26 | $6275081 \mathrm{G12}$ |  |  |
| 380 |  | 366A773G6 | 6275081G27 | 6275081G31 |  |  |
| 460 |  | 366A773G8 | 6275081G4 | 6275081G3 |  |  |
| 575 |  | 366A773G10 | 6275081G29 | 6275081G8 |  |  |
| 115 | 60 | 366A773G1 | 6275081G25 | 6275081G26 | 6275081G59] |  |
| 208 |  | 366A773G3 | 6275081G26 | 6275081 G 27 |  |  |
| 230 |  | 366A773G4 | 6275081G26 | 6275081G7 |  |  |
| 460 |  | 366A773G7 | 6275081 G 27 | 6275081G31 |  |  |
| 575 |  | 366A773G9 | 6275081G7 | 6275081G20 |  |  |

$\pi$ Input voltage to static timing unit (Fig. 13A) indicated.


Fig. 17. Magnetic coil assembly

| Magnetic Sensor Coils - Assembly (Fig. 17) |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Woles | Rating | Cat. No. | Poles | Rating | Grd. Trip Range | Cat. No. |
| 2 | $45 / 225$ | 107D7554G2 | 2 | $45 / 225$ | $100 / 400$ | With ground trip |
| 3 | $45 / 225$ | 107D7554G3 | 3 | $45 / 225$ | $107 \mathrm{D} 7554 \mathrm{G6}$ |  |
| 2 | $200 / 600$ | 107D7554G4 | 2 | $200 / 600$ | $100 / 400$ | 107D7554G7 |
| 3 | $200 / 600$ | 107D7554G5 | 3 | $200 / 600$ | $100 / 400$ | 107D7554G8 |
|  |  |  | 2 | $200 / 600$ | 107D7554G9 |  |
|  |  |  | 3 | $200 / 600$ | 300/1200 | 107D7554G10 |
|  |  |  |  |  |  |  |



Fig. 19. Power sensor unit
Fig. 18. Power supply unit
Power Supply Units - Cat. No. 156C4508G10

Power Sensor Unit AK-25 (Fig. 19)
$\left.\begin{array}{l|c|c|c|c}\hline \hline & \begin{array}{c}\text { With Long Time Delay } \\ 80 \text { to 130\% Range } \\ \text { With Instantaneous Trip } \\ \text { 4 to 12X Range }\end{array} & \begin{array}{c}\text { Without Long Time } \\ \text { Delay } \\ \text { With Instantaneous Trip } \\ 4 \text { to 12X Range }\end{array} & \begin{array}{c}\text { With Long Time Delay } \\ \text { 80 to 130\% Range }\end{array} \\ \begin{array}{c}\text { Without Instantaneous } \\ \text { Trip }\end{array} & \begin{array}{c}\text { Without Long } \\ \text { Time Delay }\end{array} \\ \text { taneous Trip }\end{array}\right]$


Fig. 20. Magnet trip device with mounting bracket
Magnet Trip Device with Mounting Bracket - Cat. No. 0846C0882 G4


Fig. 21. Ground sensor coil with neutral mounting
Fourth Wire Grid Sensor Coils
100/400 Cat. No. 152C9218G1 300/1200 Cat. No. 152C9218G2


Fig. 22. Power sensor kit
Power Sensor Test Kit - Cat. No. 0102D2526 G10


Fig. 23. Field switch mechanism and contact assemblies
NOTE: Parts listed below apply only to Types AKF-2-25 and AKF-2A-25. All other parts are identical to those used on Type AK-2-25.

| $\begin{aligned} & \text { Ref. } \\ & \text { No. } \\ & \hline \end{aligned}$ | Qty. Per Center Pole | Catalog No. | Description | Rel. No. | Qty, Per Center Pole | Catalog No. | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 100 | 1 | 073-108C9697P9 | Insulation | 114 | 1 | 079-412A404P136 | Pin |
| * 101 | 1 | 108C9698G1 | Moving con- | 115 | 1 | 108C9694P7 | Lower pivot |
| 102 | 2 | 108C9695P2 | tact | *116 | 1 | 269C257G1 | Stationary contact |
| 103 | 4 | 394A133P8 | Retaining | *116 | 1 | 269C25762 | Stationary |
| 104 | 1 | 108C9695P9 | ring | 117 | 2 | 412A286 | contact |
| 105 | 2 | 148A2279P1 | Adjustable |  |  |  | contact spring |
|  |  |  | bushing | 118 | 1 | 269C283G4 | Upper stud |
| 106 | 2 | 377A871P12 | Bearing | 119 | 1 | 108C9697P11 | Contact spac- |
| 107 | 1 | 108C9895P10 | Cam follow- | 119 | 1 | 108C9697P12 | er right side Contact spac- |
| 108 | 1 | 108C9696G1 | Crossbar |  |  |  | er left side |
| 109 | 1 | 108C9695G3 | Cam assembly, left | 120 | 1 | 269C280P1 | Moving contact pivot pln |
| 109 | 1 | 108C9695G4 | Cam assem- | 121 | 1 | 108C9688P14 | Spacer Lower stud |
|  |  |  | bly, right | 122 | 1 | 269C258G13 2938288G1 | Lower stud |
| 110 | 1 | 108C9695P6 | Pivot | ${ }_{+123}+123$ | 1 | ${ }_{108} 108969769$ | Insulation |
|  |  |  | insulation | *125 | 1 | 108C9698G2 | Moving con- |
| 112 |  | 108C9695Ps | Connector |  |  |  | tact |
| 113 | 2 | 394A193P9 | Retaining | 126 | 2 | 108C9694P6 | Spring |

[^22]
## ORDERING INSTRUCTIONS

1. Always specify complete nameplate data of the breaker.
2. Specify the quantity, catalog number (if listed), reference number (if listed), description, and this bulletin number.
3. Standard hardware such as screws, bolts, nuts, washers, etc., is not listed in this bulletin. Such items should be purchased locally.
4. For prices, refer to the nearest office of the General Electric Company.

(PHOTO 8029416)
Manual breaker, Type AK-2-50


Fig. 1. Pole unit

| Fig. <br> No. | Ref. No. | No. Required per Pole 1 |  |  |  |  |  |  |  |  |  |  |  | Cat. No. | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | AK-2-50 |  |  |  |  |  | AK-2A-50 |  | AK-3-50 |  | $\frac{\mathrm{AK}-3 \mathrm{~A}-50}{\mathrm{Man} \text { Elec. }}$ |  |  |  |
|  |  |  | Man |  |  | lec. |  | Man. | Elec. | Man. | Elec. |  |  |  |  |
|  |  | $\pm$ | -1 | -2 | $\ddagger$ | -1 | -2 | $\dagger$ | 1 | 1 | 1 | $\dagger$ | t |  |  |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 371A208P1 | Spacer |
| 1 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 9921587 P 1 | Stop. AK -50 AC |
| 1 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 449A994P3 | Stop, AK50 DC. AKU-50, AKT-50 |
| 1 | 3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1178512 Pl | Block, AK-50 AC |
| 1 | 3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 452A542 P1 | Block, AK50 DC. AKU-50, AKT-50 |
| 1 | * 4 | - | - | - | 2 | - | - | - | - | - | - | - | - | 295B408G1 | Stationary areing contact, AK-50 AC |
| 1 | * 4 | - | - | - | 3 | - | - | - | - | - | - | - | - | 295B408GI | Stationary arcing contact. AK-50 DC. AKU-50, AKT-50 |
| 1 | $\bullet 4$ | 2 | 2 | 2 | - | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 295B408G3 | Stationary arcing contact, AK-50 AC |
| 1 | * 4 | 3 | 3 | 3 | - | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 295B408G3 | Stationary arcing contact, AK-50 DC. AKU-50. AKT-50 |
| 1 | - 5 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 6509858P1 | Spring for stationary arcing contacts, (outer) AK-50 AC |
| 1 | -5 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 6509858 Pl | Spring for stationary areing contacts. (outer) AK50 DC, AKU-50, AKT-50 |
| 1 | * 6 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 6509859P1 | Spring for stationary arcing contacts. <br> (inner) AK-50 AC |
| 1 | * 6 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 6509859P1 | Spring for stationary arcing contacts, (inner) AK-50 DC. AKU-50, AKT-50 |
| 1 | 7 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 6447046P1 | Spring guide for stationary arcing contact springs. AK-50 AC |
| 1 | 7 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 6447046 Pl | Spring guide for stationary arcing contact springs. AK-50 DC, AKU-50, AKT-50 |
| 1 | 8 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6404793 P 3 | Pivot pin for stationary arcing contacts. $A K-50 \mathrm{AC}$ |
| 1 | 8 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6404793P2 | Pivot pin for stationary arcing contacts. AK-50 DC, AKU-50, AKT-50 |
| 1 | 9 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 433A319P2 | Leaf spring for stationary arcing contacts, AK-50 AC |
| 1 | 9 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 433A319PI | Leaf spring for stationary arcing contacts, AK-50 DC, AKU-50, AKT-50 |
| 1 | 10 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 459A373P3 | Insulation for stationary arcing contacts, $\mathrm{AK}-50 \mathrm{AC}$ |
| 1 | 10 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 459A373P1 | Insulation for stationary arcing contacts, AK-50 DC, AKU-50. AKT-50 |
| 1 | $\cdot 11$ | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 9921572 G 2 | Moving arcing contact. AK-50 AC |
| 1 | -11 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | - | - | 9921572 G 2 | Moving areing contact. AK-50 DC. AKU-50, AKT-50 |
| 1 | *12 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 293B221G1 | Stationary main contact |
| 2 | ${ }^{+13}$ | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 459A385GI | Stationary intermediate contact (includes barrier) |
| 1 | * 14 ! | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 293B220G7 | Moving main contacts |
| 2 | * 15 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 293B220G4 | Moving intermediate contact |
| 1 | 16 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 452A528P1 | Pin for movable main contact |
| 1 | 17 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 6404784P4 | Link for movable main contact |
| 1 | 18 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6447153 P 3 | pin for movable arcing contact link, AK-50 AC |
| 1 | 18 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6447153 Pl | Pin for movable arcing contact link, AK-50 DC, AKU-50, AKT -50 |
| 1 | 19 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 394A133P9 | Retainer |
| 1 | 20 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | $!$ | 1 | 1 | 1 | 1 | 275B975 P1 | Link for movable arcing contact, AK-50 AC |
| 1 | 20 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 27513975 P1 | Link for novable arcing contact. AK-50 DC. AKU-50. AKT-50 |
| 1 | 21 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | $6447741 \mathrm{P1}$ | Insulating tube |
| 1 | 22 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 6203981P1 | Pin for side link |
| 1 | 23 | 10 | 10 | 10 | 10 | 10 | 10 | 10 | 10 | 10 | 10 | 10 | 10 | 394A133P10 | Retainer |
| 1 | 24 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 457A624GI | Side link, right |
| 1 | 24 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 457A624G2 | Side link, left |
| 1 | 25 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 452A569G2 | Terminal |
| 1 | 26 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 452A529P1 | Leaf spring for movable main contacts |
| 1 | 27 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6414314P2 | Pole unit base |
| 1 | 28 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 452A564G1 | Lower stud |
| 1 | 29 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6203981 P9 | Pivot pin for movable main contacts |
| 1 | 30 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 293B287P3 | Spacer for terminal |
| 1 | 31 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6203981P13 | Pivot pin for movable arcing contact |
| 1 | 32 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 453A116P1 | Stop for stationary main contacts |
| 1 | 33 | - | - | - | 1 | , | - | - | - | - | 1 | - | - | 453A116P2 | Spacer for stationary main contact stop |
| 1 | 33 | 1 | 1 | 1 | - | 1 | 1 | 1 | 1 | 1 | - | 1 | 1 | 453A116P3 | Spacer for stationary main contact stop |
| 1 | 34 | - | 4 | 4 | 4 | , | , | 4 | - | - | 4 | - | - | 6509893 P1 | Spring for stationary main contacts |
| 1 | 34 | 4 | 4 | 4 | - | 4 | 4 | 4 | 4 | 4 | - | 4 | 4 | 412A0287P1 | Spring for stationary main contacts |
| 1 | 35 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 293B240G1 | Upper stud, AK-50 AC |
| 1 | 35 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 293B240G2 | Upper stud, AK-50 DC, AKU-50, AKT-50 |
| 1 | 36 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |  | 1 | 1 | 1 | 1 | 449A995P1 | Leal spring for stationary main contacts |
| 1 | 37 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6447734 P 2 | Pivot pin for stationary main contacts |
| 3 | 38 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 238D674G1 | Arc quencher, AK-50 AC |
| 3 | 38 | 1 | 1 | 1 | 1 | 1 | , | 1 | 1 | , | 1 | 1 | 1 | 238D674G2 | Arc quencher, AK-50 DC, AKU-50, AKT-50 |

$\dagger$ To determine quantity required per breaker multiply by number of poles (2, 3 or 4).
\$ Original breaker had no suffix letter or numeral

- Recommended for stock for normal maintenance.


Fig. 2. Back frame assembly


Fig. 3. Arc quencher (Ref. No. 38)


Fig. 4. AK-2-50 manual


Fig. 5. AK-2-50 electrical

| Fig. No. | Ref. No. | No. Required per Pole $\dagger$ |  |  |  |  |  |  |  |  |  |  |  | Cat. No. | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | AK-2-50 |  |  |  |  |  | AK-2A-50 |  | AK-3-50 |  | AK-3A-50 |  |  |  |
|  |  | Man. |  |  | Elec. |  |  | Man. Elec. |  | Man, Elec. |  | $\frac{\operatorname{Man}}{\ddagger}$ | $\begin{array}{\|c} \hline \text { Elec. } \\ \hline \ddagger \end{array}$ |  |  |
|  |  | $\ddagger$ | -1 | -2 | $\ddagger$ | -1 | -2 | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\ddagger$ |  |  |  |  |
| * | 51 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 6414763P1 | Phase barrier |
| 4 | 52 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | - | - | - | - | 372A275G1 | Lifting bracket, right (pearl gray) |
| 4 | 52 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | 1 | 1 | - | - | 372A275G3 | Lifting bracket, right (sand gray) |
| 4 | 53 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | - | - | - | - | 372A275G2 | Lifting bracket, left (pearl gray) |
| 4 | 53 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | 1 | 1 | - | - | 372A275G4 | Lifting bracket, left (sand gray) |
| 4 | 54 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | - | - | - | - | 9921630P1 | Arc quencher tie bar (pearl gray) |
| 4 | 54 | 1 | 1 | 1 | 1 | 1 | 1 | - | - | 1 | 1 | - | - | 9921630P3 | Arc quencher tie bar (sand gray) |
| 4 | 54 | - | - | - | - | - | - | 1 | 1 | - | - | 1 | 1 | 9921630P2 | Arc quencher tie bar |
| 2 | 55 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 267B101P2 | Cross bar |
| 4 | 56 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 6509914P1 | Opening spring, AC (not used on AKU or AKT) |
| 4 | 56 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 6509813P1 | Opening spring, AC (AKU or AKT) |
| 4 | 56 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | - | - | - | - | 6509813P1 | Opening spring, DC |
| 4 | 57 | 1 | 1 | 1 | - | - | - | - | - | - | - | - | - | 6548046P3 | Handle (black) |
| 17 | 57 | - | - | 1 | - | - | - | 1 | - | - | - | 1 | - | 669D0807P2 | Handle (gray) |
| 4 | 58 | 1 | 1 | 1 | $\overline{-}$ | - | - | - | - | - | - | - | - | 698C997P1 | Front escutcheon (black) |
| 5 | 58 | - | - |  | 1 | 1 | 1 | - | - | - | - | - | - | 275B997P2 | Front escutcheon (w/o closing switch, black) |
| * | 58 | - | - | - | 1 | 1 | 1 | - | - | - | 1 | - | - | 805B975P1 | Front escutcheon (with closing switch black) |
| * | 58 | - | - | 1 | - | - | - | 1 | - | - | - | 1 | - | 698C997P5 | Front escutcheon (blue) |
| * | 58 | - | - | $\overline{-}$ | - |  | 1 | - | 1 | - | - | - | 1 | 805B975P2 | Front escutcheon (blue) |
| 4 | 59 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 411A904G5 | Trip button and rod assembly |
| * | 60 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 412A139 | Trip button spring |
| 7 | 61 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6203939P3 | Hand, trip paddle |
| * | 62 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 192A9567P1 | Clamp |
| 7 | 63 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 276B250P1 | Trip shaft (outside) |
| 7 | 64 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | $174 V 536 \mathrm{P} 1$ | Coupling |
| 7 | 65 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 127A6493P2 | Dowel pin |
| 8 | 66 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 276B250P2 | Trip shaft (center) |
| * | 67 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 394A133P1 | Retainer |
| * | 68 | 4 | 4 | 4 | 4 | 4 | 4 | 4 | 4 | 4 | 4 | 4 | 4 | 192A9653P4 | Trip shaft bearing (side sheets and mechanism frame) |
| * | 69 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 394A133P16 | Retainer |
| 6 | 74 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 174V531P1 | Pin |
| 6 | 75 | 6 | 6 | 6 | 6 | 6 | 6 | 6 | 6 | 6 | 6 | 6 | 6 | 394A133P10 | Retainer |

$\dagger$ To determine quantity required per breaker multiply by number of poles (2 or 3).

* Not shown.
$\dagger$ Original breaker had no suffix letter or numeral.

FIG. NO. 5, REF. NO. 152 - GEAR BOXES
177 L 316 and 177 L 362 gear boxes are no longer manufactured for AK-50, 75, 100 breakers. A modification of the AKR design electrical closing assembly is available to replace these units. The replacement unit will include a new closing motor. Select replacement for 175 L 316 G 1 or G 2 gear box from Column 1. Replacements for 177 L 362 G 2 should be selected from Columns i to 4, for G3 select from Columns 5 to 8.

| REPLACEMENT KIT CAT. NO. 343L761 (Select Group Number Below) |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Column |  |  | Conventional C |  |  | Quick Close Type |  |  |  |
|  |  | $\underline{1}$ | 1 |  | 4 | 5 | 6 | 7 | 8 |
|  |  | AK-1-50, 75, 100 | AK-2A-50 | AKT-2A-50 | AK -2A -75, 100 | AK-2-50, 75, 100 | AK-2A-50 | AKT-2A-50 | AK-2A -75, 100 |
| Volts | Hertz | AK-2-50, 75, 100 | AK-3A -50 | AKT -3A-50 | AK-3A-75, 100 | AK -3-50, 75, 100 | AK-3A-50 | AKT-3A -50 | AK-3A-75, 100 |
|  | Hertz | $\left\|\begin{array}{c} \text { AK-3-50, 75, } 100 \\ \text { Includes AKU } \end{array}\right\|$ | Includes AKU |  |  | Includes AKU | Includes AKU |  |  |
| 48 | DC | G37 | G49 | G61 | G37 | G28 | G49 | G61 | G37 |
| 125 | DC | G38 | G50 | G62 | G38 | G29 | G50 | G62 | G37 |
| 250 | DC | G39 | G51 | G63 | G39 | G30 | G51 |  |  |
| 120 | 60 | G40 | G52 | G64 | G40 | G31 | G51 | G63 | G39 |
| 208 | 60 | G44 | G56 | G68 | G44 | G34 | G56 | G68 | G40 |
| 240 | 60 | G43 | G55 | G67 | G43 | G34 | G55 | G67 | G44 |
| 120 | 50 | G41 | G53 | G65 | G41 | G32 | G53 | G67 G65 | G41 |
| 208 | 50 | G46 | G58 | G70 | G46 | G35 | G58 | G70 | G41 |
| 240 | 50 | G45 | G57 | G69 | G45 | G35 | G57 | G69 | G45 |



Fig. 6. AK-2-50 mechanism assembly


Fig. 7. AK-2-50 manual front frame assembly

| Fig <br> No. | Ref. <br> No. | No. Required per Ereaker |  |  |  |  |  |  |  |  |  |  |  | Cat. No. | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | AK-2-50 |  |  |  |  |  | AK-2A-50 |  | AK-3-50 |  | AK-3A-50 |  |  |  |
|  |  |  | Man |  |  | Elec |  | Man. | Elec. | Man. | Elec. | Man. | Elec. |  |  |
|  |  | $\ddagger$ | -1 | -2 | $\dagger$ | -1 | -2 | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\pm$ | $\pm$ |  |  |
| 6 | 76 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 412A140P1 | Spring |
| 6 | 77 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 419A366P1 | Prop |
| 6 | 78 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6414743 P 1 | Cam |
| 6 | 83 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6555414 P 2 | Coupling |
| 6 | 84 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 412 A 413 P 3 | Clevis |
| 6 | 85 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 412A405P414 | Pin |
| 6 | 87 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6447744 P 1 | Pin |
| * | 88 | - | - | - | 1 | 1 | - | - | - | - | 1 | - | - | 457A610G1 | Reset latch |
| 6 | 89 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | . 1 | 1 | 6444916 P 1 | Latch bolt |
| * | 90 | - | - | - | 1 | 1 | - | - | - | - | 1 | , | - | 6414764 P 1 | Latch |
| 6 | 91 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6403348 P 1 | Spring |
| 6 | 92 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 698C993G1 | Prop |
| 6 | 93 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 377 A 81 P 2 | Prop shaft bearing |
| 6 | 94 | 4 | 4 | 4 | 4 | 4 | 4 | 4 | 4 | 4 | 4 | 4 | 4 | 394A133P9 | Retainer |
| 6 | 95 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 457A622G1 | Link assembly |
| 6 | 96 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6447099 P 1 | Pin |
| 6 | 97 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6447091P1 | Pin |
| 6 | 98 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6447331 P 1 | Spring guide (upper) |
| 6 | 99 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 148A2213P1 | Spring reset (inner) |
| 6 | 100 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 148A2214P1 | Spring reset (outer) |
| 6 | 101 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6447353 P 1 | Spring guide (lower) |
| 6 | 102 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6203914 G 1 | Spring support assembly |
| 6 | 103 | 1 | 1 | 1 | - | - | 1 | 1 | 1 | 1 | - | 1 | 1 | 457A627G1 | Buffer assembly |
| 6 | 104 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 383A671G2 | Counter weight |
| 6 | 105 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6403366 P1 | Trip shaft return spring |
| 6 | 106 | 1 | 1 | 1 | - | - | 1 | 1 | 1 | 1 | - | 1 | 1 | 848C0487P1 | Latch |
| 6 | 107 | 1 | 1 | 1 | - | - | 1 | 1 | 1 | 1 | - | 1 | 1 | 889B0410G1 | Reset latch |
| 7 | 109 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 412A412P2 | Prop stop |
| 7 | 110 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 269C267G5 | Trip paddle |

* Not shown.
$\ddagger$ Original breaker had no suffix letter or numeral.


## TYPE AK POWER CIRCUIT BREAKERS



Fig. 9. AK-2-50 manual closing mechanism

Fig. 8. AK-2-50 electrical front frame assembly

| Fig. <br> No. | Ref. No. | No. Required per Breaker |  |  |  |  |  |  |  |  |  |  | Cat. No. | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | AK-2-50 |  |  |  |  | AK-2A-50 |  | AK-3-50 |  | AK-3A-50 |  |  |  |
|  |  | Man. |  |  | Elec. |  | Man. | Elec. | Man. | Elec. | Man. | Elec. |  |  |
|  |  | $\ddagger$ |  | -2 | $\ddagger-1$ |  | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\ddagger$ |  |  |
| * | 111 | 1 | 1 | 1 | 11 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6447767 P 1 | Trip shaft stop |
| 7 | 112 | 1 | 1 | 1 | $1{ }_{1} 1$ | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 148A1946P10 | Spacer |
| 7 | 113 | 1 | 1 | 1 | $1 \begin{array}{ll}1 & 1 \\ 1\end{array}$ | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6447010 P 1 | Upper spring guide assembly pin |
| 7 | 114 | 1 | 1 | 1 | 111 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 148A1946P1 | Spacer |
| 7 | 115 | 4 | 4 | 4 | 44 | 4 | 4 | 4 | 4 | 4 | 4 | 4 | 394A133P4 | Retaining ring |
| 7 | 116 | 1 | 1 | 1 | - - |  | 1 | - | 1 | - | 1 | - | 698C996G5 | Pawl spring support (upper) |
| 7 | 117 | 1 | 1 | 1 | - - |  | 1 | - | 1 | - | 1 | - | 698C996G4 | Pawl spring support (lower) |
| * | 118 | 2 | 2 | 2 | - - |  | 2 | - | 2 | - | 2 | - | 698C996P13 | Pawl spring rollers |
| 7 | 119 | 1 | 1 | 1 | - - |  | 1 | - | 1 | - | 1 | - | 6447032 P 2 | Lower spring guide assembly pin |
| 8 | 119 | 1 | - | - | 11 | 1 | - | 1 | - | 1 | - | 1 | 6447032 P 1 | Lower spring guide assembly pin |
| 7 | 120 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 698C993P4 | Buffer pin |
| 7 | 121 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 698C993P3 | Buffer support |
| * | 122 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 698C993P5 | Buffer washer |
| * | 123 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 393A993P24 | Buffer stop nut |
| 7 | 124 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 889B0408G1 | Spring guide assembly (closing) |
| 8 | 124 | 1 | - | - | 1 | 1 | - | 1 | - | 1 | - | 1 | 273B569G9 | Spring guide assembly (closing) |
| 7 | 125 | 2 | 2 | 2 | - - | - | 2 | - | 2 | - | 2 | - | 698C992G5 | Support (includes bearing less outer race) |
| 7 | 126 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 698C992G4 | Crank (includes outer race of bearing) |
| 8 | 127 | - | - | - | 111 | 1 | - | 1 | - | 1 | - | 1 | 393A554P1 | Support |
| 8 | 128 | - | - | - | 1 | 1 | - | 1 | - | 1 | - | 1 | 393A796P3 | Bearing |
| 9 | 129 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 698C987G2 | Ratchet assembly |
| 9 | 130 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 698C988G3 | Support assembly |
| 9 | 131 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 698C990G2 | Shaft assembly |
| 9 | 132 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | $394 \mathrm{Al37P12}$ | Roll pin |
| 9 | 133 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 127A8306P1 | Spring |
| 9 | 134 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 394A133P28 | Retainer |
| 9 | 135 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 698C985G1 | Pawl with spring (rear) |
| 9 | 136 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 698C985G2 | Pawl with spring (front) |
| 9 | 137 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 846C817G1 | Spring arm |
| 9 | 138 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 698C991G5 | Prop |
| 9 | 139 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | $394 \mathrm{A133P} 3$ | Retainer |
| 9 | 140 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 412A280 P1 | Prop spring |
| 9 | 141 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | $698 \mathrm{C991P10}$ | Pin |
| 4,10 | 142 | 1 | 1 | 1 | - - | - | 1 | - | 1 | - | 1 | - | 698C996G1 | Indicator (when ordering indicator include label ref. No. 151) |

[^23]
## TYPE AK POWER CIRCUIT BREAKERS



Fig. 10. AK-2-50 manual indicator assembly


Fig. 11. Section of gear box


Fig. 12.
Motor cut-off switch

| Fig. No. | $\begin{aligned} & \text { Ref. } \\ & \text { No. } \end{aligned}$ | No. Required per Breaker |  |  |  |  |  |  |  | Cat. No. | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | AK-2-50 |  | AK-2A-50 |  | AK -3-50 |  | AK-3A-50 |  |  |  |
|  |  | Man. | Elec. | Man. | Elec. | Man. | Elec. | Man. | Elec. |  |  |
|  |  | $\ddagger-1-2$ | $\pm-1-2$ | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\pm$ | $\ddagger$ | $\ddagger$ |  |  |
| 10 | 143 | 222 | - - | 2 | - | 2 | - | 2 | - | 394A137P11 | Roll Pin |
| 10 | 144 | $1{ }^{1} 121$ | --- | 1 | - | 1 | - | 1 | - | 698C995P2 | Bearing |
| 10 | 145 | $1{ }^{1} 111$ | - - - | 1 | - | 1 | - | 1 | - | 127A6493P3 | Rod |
| 10 | 146 | $1 \begin{array}{lll}1 & 1 \\ & 1\end{array}$ | - - - | 1 | - | 1 | - | 1 | - | 698C995P14 | Tube |
| 10 | 147 | 1 1 1 | - -- | 1 | - | 1 | - | 1 | - | 412A267 P1 | Spring |
| 10 | 148 | $1{ }^{1} 111$ | - -- - | 1 | - | 1 | - | 1 | - | 698C995G1 | Indicator lever assembly |
| 10 | 149 | $1{ }^{1} 121$ | - - - | 1 | - | 1 | - | 1 | - | 412A0292P1 | Spring |
| 10 | 150 | $1{ }^{1} 111$ | - - - | 1 | - | 1 | - | 1 | - | 698C995G2 | Indicator crank assembly |
| 10 | 151 | 1.111 | - - - | 1 | - | 1 | - | 1 | - | 259C608P3 | Open-close label |
| 11 | 153 | - - - | 1.101 | - | 1 | - | 1 | - | 1 | 6447398P1 | Plug |
| 11 | 154 | - - - | $1{ }^{1}$ | - | 1 | - | 1 | - | 1 | 393A992P2 | "O' ring for plug |
| 11 | 155 | - - - | $1 \begin{array}{lll}1 & 1\end{array}$ | - | 1 | - | 1 | - | 1 | 6509871 P1 | Spring for ratchet pin |
| 11 | 156 | - - - | $1 \begin{array}{lll}1 & 1 & 1\end{array}$ | - | 1 | - | 1 | - | 1 | 372A383P1 | Ratchet pin |
| , | 157 | - - - | $1 \begin{array}{lll}1 & 1 & 1\end{array}$ | - | 1 | - | 1 | - | 1 | 393A991P1 | Lubricant for gear box (4 oz.) |
| * | 158 | - - - | $1 \begin{array}{lll}1 & 1\end{array}$ | - | 1 | - | 1 | - | 1 | 6447101P1 | Gasket motor |
| 5 | 158A | - - - - | 1.101 | - | 1 | - | 1 | - | 1 | 6447102P1 | Gasket, gear box end plate |
| 8 | 159 | - - - |  | - | 1 | - | 1 | - | 1 | 5P66MA6A | Motor, 115 volts, $25,50,60$ cycles and 125 volt DC |
| 8 | 159 | - | 1.111 | - | 1 | - | 1 | - | 1 | 5P66MA7A | Motor, 208-230 volts, 25, 50, 60 cycles and 250 volt DC |
| 12 | 160 |  | $1 \begin{array}{lll}1 & 1\end{array}$ | - | 1 | - | 1 | - | 1 | 192A7153P8 | Cut-off switch ' C ' ${ }^{\text {c }}$ |
| 12 | 161 | - - - | $1 \begin{array}{llll}1 & 1\end{array}$ | - | 1 | - | 1 | - | 1 | 192A9792P1 | Cut-off switch insulation |
| 12 | 162 | - - - | $1 \begin{array}{lll}1 & 1\end{array}$ | - | 1 | - | 1 | - | 1 | 192A7153P7 | Cut-off switch ' F ' |
| 12 | 163 | - - - | $1 \begin{array}{lll}1 & 1\end{array}$ | - | 1 | - | 1 | - | 1 | 371A235P1 | Cut-off switch cover |
| 12 | 164 | - - - | $1 \begin{array}{lll}1 & 1\end{array}$ | - | 1 | - | 1 | - | 1 | 371A233G1 | Cut-off switch mounting bracket |
| 12 | 165 | - - - | $1{ }^{1} 11$ | - | 1 | - | 1 | - | 1 | 371A234G1 | Cut-off switch lever bracket |
| 12 | 166 | - - | 1.111 | - | 1 | - | 1 | - | 1 | 394A133P9 | Cut-off switch retainer |

[^24]

Fig. 13. Shunt trip
(Ref. No. 170)


Fig. 14. Time delay undervoltage device (Ref. No. 173)

| Fig. No. | Ref. <br> No. | No. Required per Pole $\dagger$ |  |  |  |  |  |  |  |  |  |  |  | Cat. No. | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | AK-2-50 |  |  |  |  |  | AK-2A-50 |  | AK -3-50 |  | AK -3A-50 |  |  |  |
|  |  | Man. |  |  | Elec. |  |  | Man. | Elec. | Man. | Elec. | Man. | Elec. |  |  |
|  |  | $\ddagger$ | -1 | -2 | $\ddagger$ | -1 | -2 | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\ddagger$ |  |  |
| 12 | 167 | - | - | - | 1 | 1 | 1 | - | 1 | - | 1 | - | 1 | 192A8404P41 | Cut-off switch spacer |
| 5 | 168 | - | - | - | 1 | 1 | 1 | - | 1 | - | 1 | - | 1 | See Table "'B" | Closing relay (X) - standard |
| 5 | 168A | - | - | - | 1 | 1 | 1 | - | 1 | - | 1 | - | 1 | See Table 'B' | Closing relay (X) - quick close |
| * | 168B | - | - | - | 1 | 1 | 1 | - | 1 | - | 1 | - | 1 | See Table "B" | Anti-pump relay (W) - quick close |
| * | 168C | - | - | - | 1 | 1 | 1 | - | 1 | - | 1 | - | 1 | See Table "B" | Closing solenoid - quick close |
| 13 | 169 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 449A537P1 | Shunt trip device support |
| 13 | 170 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | See Table "A" | Shunt trip device (with coil) |
| 13 | 171 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | See Table "A" | Shunt trip coil |
| * | 172 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 423A380P1 | Undervoltage device support |
| 14 | 173 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | ס | Time delay undervoltage device, AC |
| 14 | 173 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | $\delta$ | Time delay undervoltage device, DC |
| 15 | 174 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | \# | Static time delay, AC or DC (replaces complete oil displacement time delay undervoltage device) |
| 14 | 175 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | See Table "A" | Undervoltage device coil |
| * | 176 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | See Table "A" | Instantaneous undervoltage device, AC (with coil) |
| * | 176 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | See Table "A" | Instantaneous undervoltage device, DC (with coil) |
| 5 | 177 | - | - | - | 1 | 1 | 1 | - | 1 | - | 1 | - | 1 | 192A9791P3 | Auxiliary switch 3 stage |
| 5 | 177 | - | - | , | 1 | 1 | 1 | - | 1 | - | 1 | - | 1 | 192A9791P6 | Auxiliary switch 6 stage |
| * | 177 | 1 | 1 | 1 | - | - | - | 1 | - | 1 | - | 1 | - | 192A9791P2 | Auxiliary switch 2 stage |
| * | 177 | 1 | 1 | 1 | - | - | - | 1 | - | 1 | - | 1 | - | 192A9791P5 | Auxiliary switch 5 stage |
| 8 | 178 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 411A952G1 | Auxiliary switch crank bracket |
| 8 | 179 | - | - | - | 1 | 1 | 1 | - | 1 | - | 1 | - | 1 | 887B386G2 | Auxiliary switch link assembly |
| 8 | 179 | 1 | 1 | 1 | - | - | - | 1 | - | 1 | - | 1 | - | 887B386G1 | Auxiliary switch link assembly |
| 8 | 180 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 6447157 P 1 | Tube - |
| * | 181 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 457A643P8 | Groove pin |
| * | 182 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 127A6463G2 | Auxiliary switch operating rod |
| * | 183 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 127A6439P1 | Auxiliary switch coupling |
| * | 184 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 6076402P203 | Pin |
| * | 185 | 1 | 1 | 1 | - | - | , | 1 | - | 1 | - | 1 | - | 887B387G1 | Adjusting plate |
| 8 | 186 | - | - | - | 1 | 1 | 1 | - | 1 | - | 1 | - | 1 | 6203934 P 1 | Open and close indicator limk |
| 5 | 187 | - | - | - | 1 | 1 | 1 | - | 1 | - | 1 | - | 1 | 265B268G1 | Open and close indicator |
| 5 | 188 | - | - | - | 1 | 1 | 1 | - | 1 | - | 1 | - | 1 | 265B268G2 | Charged and discharged indicator |

[^25]$\ddagger$ Original breaker had no suffix letter or numeral.
$\delta$ When ordering time delay undervoltage devices, the following information must be included:
(1) Complete nameplate reading of breaker involved.
(2) Desired voltage rating of device, whether a-c or d-c, and if a-c, the frequency.
\# Order by circuit breaker Serial No.

## TYPE AK POWER CIRCUIT BREAKERS



Fig. 15. Static time delay, (Ref. No. 174)


Fig. 15 A . Oil-displacement type time-delay undervoltage tripping device.


Fig. 16. AK-2A-50 manual

TABLE A

| Volts | Hertz | Shunt Trip Device |  | Instantaneous Undervoltage Device |  | Time Delay Undervoltage Device $\dagger$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Complete with Coil (less mounting) Reference 170 (Fig. 13) | Coil Only <br> Reference 171 | Complete with Coil (less mounting) | Coil Only for Instantaneous or Old Design Dashpot Type Time Delay | Complete with Coil (less mounting) Reference 173 (Fig. 14) | Coil Only <br> Reference 175 |
| 24 | DC | 139C4378G1 | 6275081 G 55 | 568B309G1 | 6275081 G 15 |  |  |
| 48 | DC | 139C4378G3 | 6275081 G 28 | 568B309G2 | 6275081G9 | ----- |  |
| 125 | DC | 139C4378G4 | 6275081 G 29 | 568B309G3 | 6275081 G 18 | 568B309G5 | 6275081G61 |
| 250 | DC | 139C4378G5 | 6275081G30 | 568B309G4 | 6275081G19 | 568B309G6 | 6275081G59 |
| 70 | 60 | 139C4378G6 | 6275081G62 | ----- | ----- | ----- | ----- |
| 120 | 60 | 139C4378G7 | 6275081 G 25 | 568B309G7 | 6275081G26 |  |  |
| 120 | 50 | 139C4378G8 | 6275081G56 | 568B309G8 | 6275081 G 4 | ----- | ----- |
| 208 | 60 | 139 C 4378 G 10 | 6275081 G 26 | 568 B 309 G 10 | 6275081G27 | 568 B 309 G 24 | 6275081G59 |
| 208 | 50 | 139C4378G11 | 6275081 G 26 | 568B309G11 | $6275081 \mathrm{G12}$ | 568 B 309 G 24 | 6275081G59 |
| 240 | 60 | 139 C 4378 G 13 | 6275081G26 | 568 B 309 G 13 | $6275081 \mathrm{G7}$ | 568 B 309 G 24 | 6275081G59 |
| 240 | 50 | $139 \mathrm{C} 4378 \mathrm{G14}$ | 6275081 G 26 | 558B309G14 | 6275081 G 12 | 568 B 309 G 24 | 6275081G59 |
| 380 | 50 | 139C4378G17 | 6275081 G 27 | 568B309G17 | 6275081G31 | --.-- | -.-.-- |
| 480 | 60 | 139 C 4378 G 18 | 6275081 G 27 | 568B309G18 | 6275081G31 |  |  |
| 480 | 50 | 139 C 4378 G 19 | 6275081 G 4 | 568B309G19 | 6275081 G 3 |  |  |
| 575 | 60 | 139 C 4378 G 21 | $6275081 \mathrm{G7}$ | 568 B 309 G 21 | 6275081G20 |  |  |
| 575 | 50 | 139C4378G22 | 6275081 G 29 | 568B309G22 | 6275081 G 8 |  |  |

NOTE: The static time undervoltage device (Fig. 14, Ref. 173) when used in combination with the static timing device (Fig. 15. Ref. 174) and a slight modification of breaker wiring will replace the older design oil-displacement type time delay undervoltage device shown in Fig. 15A.

TABLE B
CLOSING RELAYS AND COILS FOR CONVENTIONAL CLOSE AND QUICK CLOSE BREAKERS
Quick close breakers are identified by the letter " $S$ " following the breaker type (i.e., AK-2A-50S-3).

| Rating |  | For Conventional Close Breaker Closing Relay " X " | For Quick Close Breaker |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | ' X " Relay | *'W" Relay. Complete $\delta$ | *Closing Solenoid, Complete $\delta$ |
| Volts | Hertz |  |  |  | Relay. Complete | *Coil, Only |
| 125 | D-C |  | 12HGA11H52 | 192A9770P2 | 116B7197P203 | 192A9771P2 | CR9500B202H3A |
| 250 | D-C | 12HGA11H51 | 192A9770P3 | 116B7197P204 | 192A9771P3 | CR9500B202H4A |
| 115 |  | 12HGA11H74 | 192A9770P5 | 116B7197P206 | 192A9771P4 | CR9500B102A6A |
| 208 | 50 | 12HGA11H75 | 192A9770P7 | 116B7197P209 | 192A9771P5 | CR9500B102A 7 A |
| 230 |  | 12HGA11H75 | 192A9770P9 | 116B7197P212 | 192A9771P6 | CR9500B102A 7A |
| 115 |  | 12 HGA 11 H 70 | 192A9770P4 | 116B7197P205 | 192A9771P4 | CR9500B102A 2 A |
| 208 | 60 | 12HGA11H71 | 192A9770P6 | 116B7197P208 | 192A9771P5. | CR9500B102A3A |
| 230 |  | 12HGA11H71 | 192A9770P8 | 116B7197P211 | 192A9771P6 | CR9500B102A3A |

[^26]

Fig. 17. AK-2A-50 manual


Fig. 18. Drawout racking mechanism, (Ref. No. 195)

| $\begin{aligned} & \text { Fig. } \\ & \text { No. } \end{aligned}$ | Ref. No. | No. Required per Breaker |  |  |  |  |  |  |  |  | Cat. No. | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | AK-2-50 |  |  | AK-2A-50 |  | AK-3-50 |  | AK-3A-50 |  |  |  |
|  |  | Man. |  | Elec. | Man. | Elec. | Man. | Elec. | Man. | Elec. |  |  |
|  |  | $\ddagger-1$-2 |  | -1-2 | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\ddagger$ |  |  |
| * | 189 |  | 1 | 111 | - | 1 | - | 1 | - | 1 | 174V532P1 | Pin for indicator |
| * | 190 | - - - | 3 | 3 | - | 3 | - | 3 | - | 3 | 394A133P1 | Retainer for indicator |
| * | 191 | - - - | 2 | 22 | - | 2 | - | 2 | - | 2 | 6176109 P 7 | Spacer for indicator |
| * | 192 | - - - | 1 | $1 \begin{array}{ll}1 & 1\end{array}$ | - | 1 | - | 1 | - | 1 | 365A305P1 | Spring for indicator |
| 5 | 193 | -- | 1 | $1 \begin{array}{ll}1 & 1\end{array}$ | - | - | - | 1 | - | - | 6293908 G 185 | Terminal board (4 point) |
| 5 | 193 | $11_{1} 1$ | 1 | 111 | - | - | 1 | 1 | - | - | 6293908G168 | Terminal board (6 point) |
| * | 194 | 12111 | 1 | 111 | - | - | 1 | 1 | - | - | 6423721 P 4 | Terminal board support |
| * | 194 | - - - | - | - - | - | - | - | - | - | - | 9921543 P 1 | Terminal board support |
| 18 | 195 | $11_{1} 1$ | 1 | 11 | - | - | 1 | 1 | - | - | 238D689G1 | Drawout racking mechanism assembly |
| 18 | 196 | $1{ }_{1} 1$ | 1 | 11 | - | - | 1 | 1 | - | - | 365A313/P1 | Pawl spring |
| 18 | 197 | 12111 | 1 | 11 | - | - | 1 | 1 | - | - | 412A135\|P1 | Link spring |
| 16 | 198 | - - - | - | - - | 1 | 1 | - | - | 1 | 1 | 669D0819G1 | Upper side sheet (left hand side) |
| 17 | 199 | - - - | - | - - | 1 | 1 | - | - | 1 | 1 | 669D0819G2 | Upper side sheet (right hand side) |
| 16 | 200 | - - - | - | - - | 2 | 2 | - | - | 2 | 2 | 888B0420P1 | Wheel |
| 16 | 201 | - - - | - | - - | 2 | 2 | - | - | 2 | 2 | 888B0420P2 | Shaft |
| 16 | 202 | - - - | - | - - | 1 | 1 | - | - | 1 | 1 | 846C0839G1 | Interlock link assembly |
| 16 | 203 | - - - | - | - - | 4 | 4 | - | - | 4 | 4 | 192A6976P53 | Mounting stud |
| 16 | 204 | - - - | - | - - | 4 | 4 | - | - | 4 | 4 | 148A1988P1 | Jam nut |
| 17 | 205 | - - - | - | - - | 1 | 1 | - | - | 1 | 1 | 846C0839P1 | Latch |
| 16 | 206 | - - - | - | - - | 1 | 1 | - | - | 1 | 1 | 6076401 P 12 | Pin |
| 16 | 207 | - - - | - | - - | 1 | 1 | - | - | 1 | 1 | 177L292P53 | Rivet |
| * | 208 | - - - |  | - | 1 | 1 | - | - | 1 | 1 | 846C0839P10 | Latch spring, in back of Ref. 205 |
| 17 | 209 | - - - |  | - | 1 | 1 | - | - | 1 | 1 | 148A1946P5 | Spacer (left) |
| 16 | 210 | - - - |  | - | 1 | 1 | - | - |  | 1 | 177 L 292 P 58 | Screw (left) |
| 17 | 211 | - - - |  | - - | 1 | 1 | - | - | 1 | 1 | 148A1946P6 | Spacer (right) |
| 17 | 212 | - - - |  | - - | 1 | 1 | - | - | 1 | 1 | 177L292P59 | Screw (right) |
| * | 213 | - - - | - | - - | 1 | 1 | - | - | 1 | 1 | 6203939P5 | Trip paddle |
| * | 214 | - - - | - | - - | 1 | 1 | - | - | 1 | 1 | 192A9567P1 | Clamp |
| 17 | 215 | -- | - | - - | 1 | 1 | - | - | 1 | 1 | 801B138G4 | Anti rebound hook and slider |
| * | 216 | 1211 | 1 | 111 | 1 | 1 | 1 | 1 | 1 | 1 | 265B237P1 | Secondary disconnect support |
| 17 | 217 | x x x | x | x x | x | x | x | x | x | x | 386A110G2 | Secondary disconnect device (7 pt.) |
| 17 | 218 | $1 \begin{array}{lll}1 & 1 & \end{array}$ | 1 | 111 | 1 | 1 | 1 | 1 | 1 | 1 | 362 A 494 P 1 | Insulation |
| * | 219 | $2{ }^{2} 22$ | 2 | 22 | 2 | 2 | 2 | 2 | 2 | 2 | 6176109 P 72 | Spacer |

$\ddagger$ Original breaker had no suffix letter or numeral.
$x$ Order as required. Quantity of 3 maximum for AK-50 Breakers.

* Not shown.

| Fig. <br> No. | Ref. <br> No. | No. Required per Breaker |  |  |  |  |  |  |  |  |  |  |  | Cat. No. | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | AK-2-50 |  |  |  |  |  | AK-2A-50 |  | AK-3-50 |  | AK-3A-50 |  |  |  |
|  |  | Man. |  |  | Elec. |  |  | Man. | Elec. | Man. | Elec. | Man. | Elec. |  |  |
|  |  | $\ddagger$ |  |  |  |  |  | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\ddagger$ | $\ddagger$ |  |  |
| 19A | 220 | 3 | 3 |  |  |  | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 845C276G6 | Movable primary disconnect (not used on AKT) |
| 19B | 220A | 3 | 3 | 3 |  |  | 3 | 6 | 6 | 6 | 6 | 6 | 6 | 132C2655G1 | Movable primary disconnect (for AKT only) |
| * | 221 | - |  |  |  |  | 1 | - | 1 | - | 1 | - | 1 | 568B386G1 | Maintenance handle |
| * | 222 | - | - |  |  | 1 | 1 | - | 1 | - | 1 | - | 1 | 805B949G1 | Closing switch |
| 2 | 223 | 3 | 3 | 3 |  | 3.3 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | $\delta$ | Overcurrent trip device |
| 5 | 224 | - | - | - |  | 2 | 2 | - | 2 | - | 2 | - | 2 | 174V 535P1 | Window |
| 4 | 224 | 1 | 1 | 1 | - | - | - | 1 | - 0 | 1 | - | 1 | - | 269C272P8 | Window (open and close) |
| 4 | 225 | 1 | 1 | 1 | - | - | - | 1 | - | 1 | - | 1 | - | 698C997P2 | Window (charge indicator) (when ordering window include label Ref. No. 226) |
| * | 226 | 1 | 1 | 1 | - | - | - | 1 | - | 1 | - | 1 | - | 698C997P4 | Label (charge indicator) |
| 17 | 227 | - | - | 1 | - | - | - | 1 | - | - | - | 1 | - | NP148A1048 | Bib for front esc. (manual) (blue) |
| 17 | 227 | - |  |  | - |  | $1$ | - | 1 | - | - | - | 1 | NP148A1049 | Bib for front esc. (elec. breaker w/o closing switch) (blue) |
| 17 | 227 | - | , | - | - | $-1$ | 1 | - | 1 | - | - | - | 1 | NP148A1050 | Bib for front esc. (elec. breaker with closing switch) (blue) |

* Not shown.
$\ddagger$ Original breaker had no suffix letter or numeral.
$\delta$ (1) No parts furnished for field installation on EC-1 trip devices.
(2) Only part furnished for field installation on EC-2 or EC-2A trip devices is plastic cover, Cat. No. 242 C 645 P 1.
(3) When replacement trip devices are ordered, it is imperative that order includes complete nameplate reading of the breaker or breakers involved and, if a contemplated ampere rating change is involved, the order should also include information as to ampere rating, time-current characteristic, and instantaneous trip setting desired.
NOTE:
Illustrations and catalog numbers listed on the following pages apply only to Type AK-3-50 and AK-3A-50 breakers.


Fig. 19. Front view of back frame assembly-AK-3-50


Fig. 19A. Primary disconnect assembly (for AK-50), Ref. No. 220.


Fig. 19B. Primary disconnect assembly (for AKT-50), Ref. No. 220A.


Fig. 20. Magnetic coil assembly for AK-3-50 breakers

Magnetic Sensor Coils - Assembly
TABLE C

| Without ground trip |  |  | With ground trip |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Pole | Rating | Cat. No. | Pole | Rating | Cat. No. |
|  |  |  |  | 3P | $200 / 600$ |
| 3P |  |  | 0133C1555 G9 |  |  |
| 3P | $200 / 600$ | 0133C1555 G5 | 3P For AKT-3/3A-50 | 800/1600 | 0133C1555 G11 |
| 3P For AKT-3/3A-50 | $600 / 1600$ | 0133C1555 G7 |  |  |  |
|  | $800 / 2000$ | 0133C1555 G14 |  | 0133C1555 G16 |  |
|  |  |  |  |  |  |



Fig. 21. Power supply unit
Powe" Supply Units - Cat. No. 0152C9262G10


Fig. 22. Power sensor unit
(See Table D)

## TYPE AK POWER CIRCUIT BREAKERS



Fig. 23. Magnet trip device with mounting bracket
Magnet Trip Device with Mounting
Bracket - Cat. No. 184L369G1

TABLE D POWER SENSOR LOGIC UNIT, TYPE PS-1A

| Trip Elements |  |  |  | Cat. No. |
| :---: | :---: | :---: | :---: | :---: |
| L | $\mathrm{S}_{(\mathrm{LO})}$ | I | G | 184L410G52 |
| L | $\mathrm{S}_{(\mathrm{HI})}$ | I | G | 184L410G55 |
| L | $\mathrm{S}_{(\mathrm{LO})}$ | - | G | 184L410G61 |
| L | $\mathrm{S}_{(\mathrm{HI})}$ | - | G | 184L410G64 |
| L | - | I | G | 184L410G58 |
| - | $\mathrm{S}_{(\mathrm{LO})}$ | I | G | 184L410G67 |
| - | $\mathrm{S}_{(\mathrm{HI})}$ | I | G | 184L410G70 |
| - | $\mathrm{S}_{(\mathrm{LO})}$ | - | G | 184L410G73 |
| - | $\mathrm{S}_{(\mathrm{HI})}$ | - | G | 184L410G76 |
| - | - | I | G | 184L410G79 |
| L | $\mathrm{S}_{(\mathrm{LO})}$ | I | - | 184L410G41 |
| L | $\mathrm{S}_{(\mathrm{HI})}$ | I | - | 184L410G42 |
| L | $\mathrm{S}_{(\mathrm{LO})}$ | - | - | 184L410G44 |
| L | $\mathrm{S}_{(\mathrm{HI})}$ | - | - | 184L410G45 |
| L | - | I | - | 184L410G43 |
| - | $\mathrm{S}_{(\mathrm{LO})}$ | I | - | 184L410G46 |
| - | $\mathrm{S}_{(\mathrm{HI})}$ | I | - | 184L410G47 |
| - | $\mathrm{S}_{(\mathrm{LO})}$ | - | - | 184L410G48 |
| - | $\mathrm{S}_{(\mathrm{HI})}$ | - | - | 184L410G49 |
| - | - | I | - | 184L410G50 |

L $=$ Long time-delay element
$S_{(L O)}=$ Short time-delay element (2 to 5X range)
$S_{(\mathrm{HI})}=$ Short time-delay element (4 to 10X range)
$I=$ Instantaneous trip element
$\mathrm{G}=$ Ground fault protective element


Fig. 25. Power sensor kit


Fig. T. Type AK-2-25 manually operoted
power circult breaker
ORDERING DISTRUCTIONS
T. Alwags epecify the compiete nameplate data of the breaker.
2. Spectiy the quantity, catalog number (If listed), reference number (if listed), description, and thifo bullétin number.
\$. CAUTION: When local factlities for breaker recallbration are not abailable, the brealor ahoild bo forwarded to the nearest G-E Service Shop; or to the Generad Electric Company, 6901 kinpood Avenue; Philadelphia 4\%, Pa.
4. Standard hardware, such as screws, bolts, nuts, washers, etc, is not listed in this builetine stich ttems should be purchased locally.
5. Por prices, refor to the nearest office of the General Electric Company.

GENERAL ELECTRIC


Flo, 2 Type AK-2025 power circuit bropkior bick frame (operating mechanism romo yod)


Fig. 3, Moving and stofionary dohtacts Wind ctost War assembly


Fig. 4. Culaway view of type ÁK-2-25 olectrecilly openated power circuit breaker


Fig. 5. Type AK-2-25 electrically operated power circuit breaker (escutchoon romoved and dismantied)


* Recommended for stock for normal maintenance:

Whorignal breake had no paifir numeral or letter.

## $\uparrow$ Not Ehown,

## Y $t$ Electrically operated breakers

Note tor overcurrent trip dêvces:
(1) Noparts furinished for field Instaliation on EC-1 trip devices.
(2) Only part furnished for field installation on EC-2 or EC-2A trip devices is plasitc cover, Cat, No. $342 C 645 \mathrm{P}$
(0). When replacement trip devices are ordered, it is imperative that order inchudes complete nameplate xatading $f$ of the breater or breakeris involved and, if a contemplated ampare rating change is involved, the ordar ohoofil alsolnclade informationas to ampere rating; time-current characteristic, and instantaneons trip dettins desired.

Note tor operating mechantems:

1) Trdifidual partscannot be furnished for operating mechanisms.
2) When ropincament is necessary give complete nameplate reading when ordering.

\& Recomnended for stode tor normal maintenance.
LOrginal brealcer had no euffit numeral or letter.

## $\dagger$ Not shown.

If at any time a breaker ts to have added to it either shunt trip, umdervoltage device, or belralarm tevico; tot otdor foy y the deyice must include the following information:
(1) Complete nameplate reading of breaker involved.
(2) Desired poltage rating of device, whether a-c or d-c, fand if a-o, the irequency;
(3) In the case of underfoltage devices, specify whether thstantaneous or time delay.

A On $-1 \%$ specify Cat. No. of "xyl relay when ordering these partis.
ifotrder by elrcuult begatzer Berial No.



Fig. 14. Manual (left) and electrical (right) front frame assemblies for Type AK-2-15 and -25 power circuit breakers
NOTES FOR FIG. 14:
(1) Should it become necessary to replace the complete front frame of the breaker, it is necessary that the order include complete nameplate reading of existing breaker.
(2) If an existing manual breaker is to be converted to electrical operation, the order must include, in addition to complete nameplate reading, a description of desired change and complete voltage and frequency rating of both closing and tripping circuits.

TABLE A

| Rating |  | Catalog Number |  |  |  | "Y" Relay Complete (Ref. 48) $\$$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Relay  <br> Complete, Ref. 47 Coil, only <br> (Ref. 53)  |  | Relay  <br> Complete, Ref. 47 Coil, only <br> (Ref. 53) |  |  |
| Volts | Cycles |  |  |  |  |  |
|  |  | for $\Delta$ and Early -1 Breakers |  | for Late -1, and all -2 Breakers |  |  |
| 24 | D-C | 295B445P1 | 295B445P201 | 116B7197P1 | 116B7197 P201 |  |
| 48 |  | 295B445P2 | 295B445P202 | 116B7197P2 | 116B7197P202 | $\begin{aligned} & 295 \mathrm{~B} 444 \mathrm{P} 1 \\ & 295 \mathrm{~B} 444 \mathrm{P} 2 \end{aligned}$ |
| 125 |  | 295B445P3 | 295B445P203 | 116B7197P3 | 116B7197P203 | $295 \mathrm{~B} 444 \mathrm{P} 3$ |
| $\frac{250}{115}$ |  | 295B445P4 | 295B445P204 | 116B7197P4 | 116B7197P204 | 295B444P4 |
| 115 | 25 | 295B445P7 | 295B445P207 | 116B7197P7 | 116B7197P207 | 295B444P7 |
| 230 |  | 295B445P13 | 2958445 P 210 | 116B7197P10 | 116B7197P210 | 295B444P10 |
| 4601 |  |  | 295B445P213 | 116B7197P13 | 116B7197P213 | 295B444P13 |
| 230 | 40 | 295B445P12 | 295B445P212 | 116B7197P16 | 116B7197P216 |  |
| 115 | 50 | 295B445P6 | 295B445P206 | 116B7197P6 | --.-.-.-.-.-- | 295B444P11 |
| 208 |  | 295B445P9 | 295B445P209 | 116B7197P9 | 116B7197P206 116 B 7197 P 209 | 295B444P5 |
| 230 |  | 295B445P12 | 295B445P212 | 116B7197P12 | 116B7197P209 116 B 197 P 212 | 295B444P8 |
| 380 |  | 295B445P17 | 295B445P214 | 116B7197P17 | 116B7197P212 | 295B444P11 |
| 460 |  | 295B445P15 | 295B445P216 | 116B7197P15 | 116B7197P217 | 295B444P17 |
| 115 208 | 60 | 295B445P5 | 295B445P205 | 116 B 7197 P 5 | 116B7197P215 | 295B444P14 |
| 208 |  | 295B445P8 | 295B445P208 | $116 \mathrm{B7} 197 \mathrm{P8}$ | $116 \mathrm{B7197P} 205$ | 295B444P5 |
| 230 |  | 295B445P11 | 295B445P211 | 116B7197P11 | 116B7197P208 | 295B444P8 |
| 4601 |  | 295B445P14 | 295B445P215 | 116B7197P14 | 11687197 P 211 116 B 7197 P 214 | 295B444P11 |
|  |  |  |  |  | 116B7197P214 | 295B444P14 |

$\Delta$ Original breaker had no suffix numeral or letter.
8 Only complete relay furnished.

(PHOTO 8026586)

Fig 15. Accessories for wall mounting (ref. $65,66,67,68$ )

Fig. 16. Maintenance handle for electrically operated breakers not equipped with manual handies (ref. 69)

TABLE B

| Volts | Rating | Catalog Number |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | Closing Solenoid Coil (Ref. 26) | Shunt Trip Device Coil (Ref. 56) | Undervoltage Device Coil (Ref. 58) |
|  | Cycles |  |  |  |
| $\begin{array}{r} 24 \\ 48 \\ 125 \\ 250 \end{array}$ | D-C | 366A773G17 <br> 366A773G13 <br> 366A773G15 | $\begin{aligned} & 6275081 \mathrm{G} 55 \\ & 6275081 \mathrm{G} 28 \\ & 6275081 \mathrm{G} 29 \\ & 6275081 \mathrm{G} 30 \end{aligned}$ | $\begin{aligned} & 6275081 \mathrm{G} 15 \\ & 6275081 \mathrm{G} 9 \\ & 6275081 \mathrm{G} 18 \\ & 6275081 \mathrm{G} 19 \end{aligned}$ |
| $\begin{aligned} & 115 \\ & 208 \\ & 230 \\ & 460 \\ & 575 \end{aligned}$ | 25 | $\begin{aligned} & \text { 366A773G3 } \\ & \text { 366A773G6 } \\ & \text { 366A773G14 } \\ & 366 \text { A773G11 } \\ & \text { 366A773G12 } \end{aligned}$ | $\begin{aligned} & 6275081 \mathrm{G} 26 \\ & 6275081 \mathrm{G} 29 \\ & 6275081 \mathrm{G} 29 \\ & 6275081 \mathrm{G} 7 \\ & 6275081 \mathrm{G} 5 \end{aligned}$ | $\begin{aligned} & \text { 6275081G12 } \\ & 6275081 \mathrm{G} 10 \\ & 6275081 \mathrm{G} 10 \\ & 6275081 \mathrm{G} 17 \\ & 6275081 \mathrm{G} 1 \end{aligned}$ |
| $\begin{aligned} & 115 \\ & 208 \\ & 230 \\ & 380 \\ & 460 \\ & 575 \end{aligned}$ | 50 | 366A773G2 366A773G3 366A773G5 366A773G6 366A773G8 366A773G10 | 6275081G56 6275081G26 <br> 6275081G26 <br> 6275081G27 <br> 6275081G4 <br> 6275081G29 | 6275081G4 <br> 6275081G12 <br> 6275081 G12 <br> 6275081 G31 <br> 6275081G3 <br> 6275081G8 |
| $\begin{aligned} & 115 \\ & 208 \\ & 230 \\ & 460 \\ & 575 \\ & \hline \end{aligned}$ | 60 | $\begin{aligned} & \text { 366A773G1 } \\ & \text { 366A773G3 } \\ & \text { 366A773G4 } \\ & \text { 366A773G7 } \\ & \text { 366A773G9 } \end{aligned}$ | $\begin{aligned} & 6275081 \mathrm{G} 25 \\ & 6275081 \mathrm{G} 26 \\ & 6275081 \mathrm{G} 26 \\ & 6275081 \mathrm{G} 27 \\ & 6275081 \mathrm{G7} \end{aligned}$ | $\begin{aligned} & 6275081 \mathrm{G} 26 \\ & 6275081 \mathrm{G} 27 \\ & 6275081 \mathrm{G} 7 \\ & 6275081 \mathrm{G} 31 \\ & 6275081 \mathrm{G} 20 \end{aligned}$ |



Tig. 17. Fiold switch mectionitm and contact astembilios
NOTE: Parts Listed below apply only to Types AKF-2-25 and AKF-2A-26, All othor parts are ldontical to those used on Type AK-2-25.

| $\begin{array}{ll} \text { Ref. } \\ \text { No. } \end{array}$ | Cenper. | Cutalo No. | Description | $\begin{aligned} & \text { fief. } \\ & \text { sa } \end{aligned}$ | $\begin{aligned} & \text { iqgy. Per } \\ & \text { Comer Pole } \end{aligned}$ | Cutalog Noi. | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 1 | 1023-108C960720 | Tngulation | 114 | $\because 1$ | ORS-124404P130. |  |
| 101 | \%: 1 | $1{ }^{1} 1086960861$ | Mpving eo | 115 | 1 | C $10869694{ }^{\text {P }}$, 2 |  |
| , |  | - | taet | -116 | 1 | 868905701. | Statlonipty |
| 40\% |  | C108C9098P2 | Hink |  |  |  | contagt |
| \% 108 |  | Sochtsapg | Retaining, | ${ }^{1} 116$ |  | 3680 ces70\% | 8tationa |
|  |  |  | ${ }_{\text {r }}^{\text {r }}$ | 117 |  |  | contact |
| 105 |  | 148人2379P1 | Adjuatable |  |  | 4, | contact ef |
|  |  | 1 | bashing. | 118 |  | 30pcrsscal | Dpper stud |
| 108 | . | VCS77A671212. | Bearing, | 118 |  | $108 \mathrm{C9}$ 9 | Contrict |
| 107 |  | - , 10960689810 |  | 118 |  | 108 |  |
| 108 |  | 1086889601 | Crossbar |  |  |  |  |
| 109 |  | 108c969508 | Cam assem- <br> biy, latt | 120 |  | 2696280 PI |  |
| 109 |  | 108 ctsegsos | Cfy, lets. | 121 |  | 109C9698P14 | spacer |
|  |  |  | Whis reght | 129 |  | 2696258015 | Power mider |
| 110 |  | 10890009889 | Plyot | 1283 | $1$ | tigspasgic | Are quanel |
| 111 |  | $2{ }^{2} 1056969488$ | Lower stud Insulation | $124$ |  | $\begin{aligned} & 1108 C 9 e_{9}^{76} \\ & 10869898 \end{aligned}$ | Insmiation: |
| 42 | 6, 1 | O Couscoasprs | Connvector |  |  |  |  |
| TH3 |  | 10.80418389 | Rotaining | 128 |  | 11080 | Ejed |

[^27]
## TYPES AK-2-15 AND AK-2-25 POWER CIRCUIT BREAKERS

Fig. 1. Type AK-2-25 manually operated power circuit breaker

## ORDERING INSTRUCTIONS

1. Always specify the complete nameplate data of the breaker.
2. Specify the quantity, catalog number (fifisted), reference number (if listed), description, and this bulletin number.
3. CAUTION: When local facilities for breaker recalibration are not available, the breaker should be forwarded to the nearest G-E Service Shop; or to the General Electric Company, 6801 Elwood Avenue, Philadelphia 42, Pa.
4. Standard hardware, such as screws, bolts, nuts, washers, etc., is not listed in this bulletin. Such Items should be purchased locally.
5. For prices, refer to the nearest office of the General Electric Company.


Fig. 2. Type AK-2-25 power circuil breaker beck frame (oparating mechanism removed)

Fig. 4. Culaway view of type AK-2-25 elecr:cci. iv e. ated power circuil breaker - . .



Fig. 3. Moving and stationary confacts and cross bar assembly


Fig. 5. Type AK-2-25 electrically operated power circuis breaker (escuicheon removed and dismantled)


* Recommended for stock for normal maintenance.
$\dagger$ Not shown.
$\ddagger$ Electrically operated breakers.
Note for overcurrent trip devices :
(1) No parts furnished for field instaliation on EC-1 trip devices.
(2) Only part furnished for field installation on EC-2 trip devices is plastic cover, Cat. No. 242 C 45 P 1.
(3) When replacement trip devices are ordered, it is imperative that order includes complete nameplate reading of the breaker or breakers involved and, if a contemplated ampere rating change is involved, the order should also include information as to ampere rating, time-current characteristic, and instantaneous trip setting desired.

Note for operating mechanisms:
(1) Individual parts cannot be furnlshed for operating mechanisms.
(2) When replacement is neceasary give complete nameplate reading when ordering.

| Ref. No. | Quantity wined for 3-pole Breaker |  | Catalog Number | tion |
| :---: | :---: | :---: | :---: | :---: |
|  | $\begin{aligned} & \text { Type } \\ & \text { AK-2-15 } \end{aligned}$ | $\begin{gathered} \text { Type } \\ \text { AK-2-25 } \end{gathered}$ |  |  |
| 36 | 4 | 4 | 386A110G2 | Movable secondary disconnects (drawout breaker) |
| 37 | 1 | 1 | 622C505G1 | Cutoff switoh (elecirically operated breaker) |
| 38 | 1 | 1 | 432A671G2 | Auxiliary switch, 2 stages |
| 38 | 1 | 1 | G5 | Auxiliary switch, 5 stages, |
| 39 | 1 | 1 | - 269C268G1 | Manual trip bution |
| $t 40$ | 1 | 1 | 412A133 | Spring for maunal trip button |
| 41 | 1 | 1 | See Ref. 55, 56 | Shunt trip device |
| 42 | 1 | 1 | 622C529G1 | Closing switch. |
| 43 | 1 | 1 | 269C272G1 | Shaft assembly |
| 44 | 1 | 1 | 259C607G1 | Escutcheon, mianual breaker (black) |
| 44 | 1 | 1 | P10 | Eiscutcheon, electrically operated breaker (black, |
| 44 | 1 | 1 : | G2 | Escutcheon, electrically operated breaker (with handle) (blanil). |
| $\dagger 44$ | 1 | 1 | 259C607G3 | Escutcheon, manual breaker (blue) |
| 144 | 1 | 1 | P11 | Escutcheon, clectrically operated breaker (blue) |
| \$44 | 1 | 1 | G4 | Escutcheon. electrically operated breaker (with handie) (blue) |
| 45 | 1 | 1 | 259C608G1 | Indicator |
| 46 | 1 | 1 | 276B191P1 | Handle (black) |
| 46 | 1 | 1 | $669 \mathrm{D} 807 \mathrm{P1}$ | Handle (sand gray) |
| 47 | 1 | 1 | See table A | "X" contactor |
| *48 | 1 | 1 | See table A | "Y" relay |
| $\dagger 49$ | 1 | 1 | $412 \mathrm{Al58}$ | Opening spring, rear of escutcheon |
| * 50 | 8 | 8 | 295B445P221 | Stationary contucts, "X" contactor |
| * 51 | 4 | 4 | P222 | Moving coutactis, 'X' contactor |
| $\dagger 52$ | 4 | 4 | P223 | Springs, moving contacts, "X" contactor |
| * 53 | 1 | 1 | See table A | Operating coil, 'X' contactor |
| 54 | 1 | 1 | 622C501P1 | Cover, " X " contactor |
| 55. | 2 | 2 | P2 | Jumper, 'X" contactor |
| 55 | 1 | 1 | 622C502G1 | $\ddagger$ Shunt trip device |
| *56 | 1 | 1 | See table B | Coil for sliunt trip device |
| 57 | 1 | 1 | 269 C282G2 | $\ddagger$ Instantancous undervoltage device, a-c |
| 57 | 1 | 1 | G5 | $\ddagger$ Instantansous undervoltage device, d-c |
| 57 | 1 | 1 | G6 | $\ddagger$ Time delay undervoltage device, a-c |
| 57 | 1 | 1 | G7 | $\ddagger$ Tinse delay undervoltage device, d-c |
| -58 | 1 | 1 | See table B | Coil for undervoltage device |
| 59 | 1 | 1 | 269C282G1 | Time delay uashpot for undervoltage device |
| * $\dagger 60$ | 1 | 1 | 6172594 | Spring, fur undervoltage device |
| 61 | 1 | 1 | 269 C 299 G 2 | $\ddagger$ Bell alarm device. |
| 62 | 1 | 1 | 6293908G275 | Terminal board, 6 poles |
| 62 | 1 | 1 | G274 | Terminal board, 10 poles . |
| 63 | 1 | 1 | 269C268GI | link and inusning for auxlliary switch. |
| 64 | 1 | 1 | 6314936 Pl | Cover for auxillary switch, 1 stage |
| 64 | 1 | 1 | P2 | Cover for auxiliary switch, 2 stages |
| 64 | 1 | 1 | P3 | Cover for auxiliary switch, 5 stages |
| 65 | 3 | 3 | 295B475P2 | Base for wall mounted, general purpose breaker |
| 66 | 6 | - | 394A144P1 | Angle for wall mounted, general purpose breaker |
| 67 | 6 | - | 275B995P1 | Terminail for wall mounted, general purpose breaker |
| 67 | - | 6 | 695C131P1 | Terminal for wall mounted, general purpose breaker |
| 68 | 6 | - | 394A106P1 | Cable clamp for wall mounted, general purpose breaker |
| 68 | - | 6 | 457A673G1 | Cable clamp for wall mounted, general purpose breaker |
| 69 | 1 | 1 | 269C276G2 | Maintenance handle |

- Recommended for stock for normal maintenance.
$\dagger$ Not shown.
- If at any time a breaker is to have added to it either shunt trip, undervoltage device, or bell alarm device, the order for the device must include the following information:
(1) Complete nameplate reading of breaker involved.
(2) Desired voltage rating of device, whether $a-c$ or $d-c$, and if $a-c$, the frequency.
(3) In the case of undervoltage devices, specify whet her instantaneous or time delay.
$(\%) \cdot \cdots)$
$3 ?$


Fig. 6. "X" contactor (ref. 47)


Fig. 7. "Y" relay (ref. 48)


Fig. 8. Shunt trip devise (ref. 41)


Fig. 9. Undervoltage device (ref. 57)

Fig. 10. Cutoff switch

- (ref. 37)

Fig. 11. Bell alarm device (ref. 61)


Fig. 12. Terminal beard (ref. 62)

Fig. 13. Auxiliary swith (ref. 38)



Fig. 14. Manual (left) and electrical (right) front frame assemblies for
Type AK-2-15 and -25
power circuit breakers

## NOTES FOR FIG. 14:

(1) Should it become necessary to replace the complete front frame of the breaker, it is necessary that the order include complete nameplate reading of existing breaker.
(2) If an existing manual breaker is to be converted to electrical operation, the order must include, in addition to complete nameplate reading, a description of desired change and complete voltage and frequency rating of both closing and tripping circuits.

TABLE A


Fig 15. Accessories for wall mounting (ref. 65, 66, 67, 68)

Fig. 16. Maintenance handle for electrically operated breakers not equipped with manval handles (ref. 69)

TABLE B

| Rating |  | Catalog Number |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | Closing Solenoid Coil (Ref. 26) | Shunt Trip Device Coil (Rcf. 56) | Undervoltage Device Coll (Ref. 58) |
| Volts | Cycles |  |  |  |
| $\begin{gathered} 24 \\ 48 \\ 125 \\ 250 \end{gathered}$ | D-C | $\begin{array}{r} 36 \mathrm{CA773G17} \\ 366 \mathrm{~A} 73 \mathrm{G} 13 \\ 366 \mathrm{~A} 773 \mathrm{G} 15 \\ \hline \end{array}$ | $\begin{aligned} & \text { 6275081G55 } \\ & \text { 6275081G28 } \\ & 6275081 \mathrm{G29} \\ & 6275081 \mathrm{G} 30 \end{aligned}$ | $\begin{aligned} & 6275081 \mathrm{G15} \\ & 6275081 \mathrm{G9} \\ & 6275081 \mathrm{G18} \\ & 6275081 \mathrm{G19} \end{aligned}$ |
| $\begin{aligned} & 115 \\ & 208 \\ & 230 \\ & 460 \\ & 575 \end{aligned}$ | 25 | $\begin{aligned} & 366 A 773 \mathrm{~GB} \\ & 366 \mathrm{~A} 773 \mathrm{G} 6 \\ & 366 \mathrm{~A} 773 \mathrm{G14} \\ & 366 \mathrm{~A} 73 \mathrm{G11} \\ & 366 \mathrm{~A} 773 \mathrm{G} 12 \end{aligned}$ | $\begin{aligned} & 6275081 \mathrm{G} 26 \\ & 6275081 \mathrm{G} 29 \\ & 6275081 \mathrm{G} 29 \\ & 6275081 \mathrm{G7} \\ & \mathrm{G} 275081 \mathrm{G} 5 \end{aligned}$ | $\begin{aligned} & 6275081 \mathrm{G} 12 \\ & 6275081 \mathrm{G10} \\ & 6275081 \mathrm{G10} \\ & 6275081 \mathrm{G} 17 \\ & 6275081 \mathrm{G} 21 \end{aligned}$ |
| $\begin{aligned} & 115 \\ & 208 \\ & 230 \\ & 380 \\ & 460 \\ & 575 \end{aligned}$ | 50 | 366A773G2 <br> 366A773G3 <br> 366A773G5 <br> 366A773G6 <br> 366A773G8 ${ }^{\circ}$ <br> 366A773G10 | 6275081G56 6275081G26 6275081G26 6275081G27 6275081G4 6275081G29 | 6275081G4 <br> 6275081G12 <br> 6275081G12 <br> 6275081G31 <br> 6275081G3 <br> 6275081G8 |
| $\begin{aligned} & 115 \\ & 208 \\ & 230 \\ & 460 \\ & 575 \end{aligned}$ | 60 | $\begin{aligned} & \text { 366A773G1 } \\ & \text { 366A773G3 } \\ & \text { 366A773G4 } \\ & \text { 366A773G7 } \\ & \text { 366A773G9 } \end{aligned}$ | $\begin{aligned} & 6275081 \mathrm{G} 25 \\ & 6275081 \mathrm{G} 26 \\ & 6275081 \mathrm{G} 26 \\ & 6275081 \mathrm{G} 27 \\ & 6275081 \mathrm{G7} \end{aligned}$ | $\begin{aligned} & 6275081 \mathrm{G} 26 \\ & 6275081 \mathrm{G} 27 \\ & 6275081 \mathrm{G7} \\ & 6275081 \mathrm{G} 31 \\ & 6275081 \mathrm{G} 20 \\ & \hline \end{aligned}$ |

tie following tools are recommended for proper maintenanice of of the AK-2-15 and AK-2-25 Power Circuil Breakers. NOTE:- Otain direct from mamuacturor incticated.

| Description | Calalog <br> Number | MManufacturer |
| :---: | :---: | :---: |
| SCREW DRIVERS |  |  |
| For slotted head <br> For slotted head <br> For Phlllips head, No. 2 super | $\begin{gathered} \mathrm{R}+304 \\ \mathrm{~K}-505 \mathrm{~L} / 2 \\ 1202 \end{gathered}$ | Crescent <br> Crescent <br> Apex |
| PLIERS |  |  |
| Polnted <br> Truarc (atraight) | $\begin{gathered} 1661-6 \\ 22 \end{gathered}$ | Kraeuter <br> Waldes |
| END WHENCHES |  |  |
| Adjustable <br> 1/4 inch, open end | $\begin{aligned} & 91-8 \\ & 5-00 \end{aligned}$ | Utica Armstrong |
| SOCKET WRENCHES (3/8' DRIVE) |  |  |
| Ratchet handle Extension bar, 12 inch 3/8 inch socket <br> 7/16 inch socket (long) <br> 9/16 inch socket | $\begin{gathered} \text { F-710A } \\ \text { FX-11 } \\ \text { FD-121 } \\ F-181 \end{gathered}$ | $\qquad$ |
| ALLEN HEAD WRENCHES |  |  |
| 1/8 inch 5/16 inch | ----- | -- |
| MISCELLANEOUS |  |  |
| 1/4 inch spintite wrench (long shank) <br> 7/16 inch spintite wrench <br> *Maintenance operating handie | $\begin{gathered} 3208 \\ 3414 \\ 269 \mathrm{C} 276 \mathrm{G} 2 \end{gathered}$ | Stevens-Walden Stevens-Walden G. E. Co., Phila |

* For electrically operated breakers not equipped with manual handles.

LOW VOLTAGE SHITCHGEAR DEPARTMENT GENERAL ELECTRIC
philadelphia, pa.


[^0]:    These instructions do not purport to cover afl detoils or vorictions in equipment nor to provide for every posible contingency fo be anet in conmetion with hataflation, operotion or maintenames. Should further information be desired or showtd porticulor problams arise which ere not eevered afficiently for the purthorser's purperes, the mafter should be raferred to the General Electric Compony.

[^1]:    
    

[^2]:    
    

[^3]:    

[^4]:    On incoming serviec lines, where the Underwriters' rules apply, provide some means of disconnecting the grounded neutral in accordance with the following requirements: $\mathbf{2 3 0 - 7 0}$ (i) of the National Elec. trieal Code: "If the switeh or circuit breaker

[^5]:    - Locked-rotor currents are based upon motors having NEC code letters "a" through "j" inclusive. If the locked-rotor current exceeds this value, select the circuit breaker having the next higher continuous current rating, provided there is a calibration point on the breaker which is less than 140 percent of the motor full-load current.

[^6]:    t Numbar of operotion: bofore mepoir which may inciude replocament of interrupling unif perts. These numbers opply only fo fully completed storts, ond not to inturruptod starts such as jogging. Inching eufamolie sequencing of prateclive meloy operations. See ASA-C-37.13. These endurancs pelings do mot aliminute the netd fer periodic mainlenomet os indisoted in the applieable instruction boek far the breoler.

    * Mofor rolings ope limitud by the meximum rolinge of fuset which con be used on AKU breokers.

[^7]:    be provided in the service cabinet or on the switchboard for disconnecting the grounded conductor from the interior winding.

[^8]:    Fig. 43. Type EC. 18 magnelic overcurrent iripping dovice.Trips for

[^9]:    - Pickup tolerances are $\pm 15 \%$ for EC-1B.

[^10]:    These instructions do not purport to cover all details or variations in equipment nor to provide for every possible contingency to be met in connection with installation, operation or maintenance. Should further information be desired or should particular problems arise which are not covered sufficiently for the purchaser's purposes, the matter should be referred to the General Electric Company.

[^11]:    These instructions do not purport to cover all details or variations in equipment nor to provide for avery possible contingency to be met in connection with installation, operation or maintenance. Should further information be desired or should particular problems arise which are not covered sufficiently for the purchaser's purposes, the matter should be referred to the General Electric Company.

[^12]:    Three standard calibration marks will appear on the operating arm at (9), and the value of these callbration marks will be indicated by stampings on the arm as follows: ( $4 X-6.5 X-9 X$ ) or ( $6 X-9 X-$ $12 X)$ or $(8 X-12 X-15 X)$.

[^13]:    These instruetions do not purport to cover all dotails or variations in equipment nor to provide for every possible contingency to be met in connection with instatlation, operotion or maiatenance. Should further informatron be desired or should particulor problems arise which are not covered sufficiently for the purchecer's purposes, the mafter should be referred to the General Electric Company.

[^14]:    Ratings
    a. AK-1-25 current rating- 600 amperes (AK-1-15 current rating- 225 amperes).
    b. Voltage rating is similar for both breakers; namely 600 volts a-c and 250 volts d-c.
    c. AK-1-25 interrupting capacity $-25,000$ amperes (AK-1-15 interrupting capicity 15,000 amperes).

    Construction-- Type AK-1-25 Compared with Type AK-1-15
    a. The metal base is wider and longer.
    b. The studs have been increased in width and thickness.
    c. The pole units are wider and longer to provide for an additional movable and a stationary contact arm.
    d. The insulating link for each pole unit has been increased in size to provide insulation for the additional contact arms.
    e. The shunt has been increased in length and width.
    f. An interior barrier has been added. Also, the interior and exterior barriers, as well as muffler, front cap, rear support and fiber straps for each pole unit have been increased in size to dissipate any increase in arcing.

[^15]:    The short-time delay mechanism consists of an escapement composed of a driving segment (4), pinion (3), pallet (1), escape wheel (2) and a callbration spring (9).

[^16]:    - Recommended for stock for normal maintenance

[^17]:    * Recommended for stock for normal maintenance.
    $\ddagger$ Original breaker model had no suffix letter or numeral.
    + Not shown.

[^18]:    * Recommended for stock for normal maintenance.
    $\dagger$ Includes two assemblies - for one complete breaker pole.
    $\int$ Four required per pole.
    ight required per pole.
    reaker may have up to four.
    + Not shown
    8

[^19]:    $\dagger$ Not shown

[^20]:    These instructions do not purport to cover all details or variations in equipment nor to provide for every possible contingency to be met in connection with installation, operation or maintenonce. Should further information be desired or should paticular problems arise which are not covered sufficiently for the purchaser's purposes, the matter should be referred to the General Electric Compony.

[^21]:    $\Delta$ Original breaker had no suffix numeral or letter.
    § Only complete relay furnished.

[^22]:    * Recommended for stock for normal maintenance.

[^23]:    * Not shown.
    $\ddagger$ Original breaker had no suffix letter or numeral.

[^24]:    * Not shown.
    $\ddagger$ Original breaker had no suffix letter or numeral.

[^25]:    * Not shown.

[^26]:    * Recommended for stock for normal maintenance.
    $\delta$ Only complete relay furnished.

[^27]:    
    thitit shomit
    gEMERAL EECTAIC COMPABY, SHTTCHEEAR PRODUGTS DEPARTMENT, PHLLADEIPHLA, PA: 18142

