OV5640
Embedded Firmware User Guide
- VCM AF Module

Version 1.0

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Contents

**OV5640 Embedded Firmware User Guide** .......................................................... 1-1
Version 1.0 ........................................................................................................ 1-1
Contents ............................................................................................................ 1-3
1  Embedded Resources .................................................................................... 1-4
2  Auto Focus Solution ..................................................................................... 2-4
   2.1 Embedded Auto Focus Solution ............................................................... 2-4
   2.2 External Auto Focus Solution ................................................................. 2-5
3  User Interface ............................................................................................... 3-6
   3.1 Command and Status Registers .............................................................. 3-6
   3.2 Main Command Table ............................................................................ 3-6
   3.3 Running Status of firmware .................................................................. 3-7
4  Firmware User Guide ................................................................................... 4-8
   4.1 Stage - Sensor Init ................................................................................ 4-8
   4.2 Stage - Preview ...................................................................................... 4-8
   4.3 Stage: Zone Configuration .................................................................... 4-8
   4.4 Stage: Auto Focus ............................................................................... 4-8
   4.5 Stage: Release Auto Focus ................................................................... 4-9
5  Auto Focus Zone Configuration ................................................................... 5-10
   5.1 Zone(X₀, Y₀, X₁, Y₁) ........................................................................... 5-10
   5.2 Zone Mode ........................................................................................... 5-10
      5.2.1 Zone Mode 1 – Default zone mode ............................................... 5-10
      5.2.2 Zone Mode 2 – Touch zone mode ............................................... 5-11
      5.2.3 Zone Mode 3 – Custom mode ..................................................... 5-11
6  Update History ............................................................................................ 6-13
1 Embedded Resources

- Embedded Micro-controller
- 4KB of embedded program memory
- Embedded VCM Controller.
- Built-in Auto Focus Control (AFC) functions. AFC module collects edge information for programmable zone.

2 Auto Focus Solution

There are two basic Auto Focus solutions: embedded auto focus solution and external auto focus solution.

2.1 Embedded Auto Focus Solution

For Embedded auto focus solution, the auto focus function is controlled by the built-in micro-controller of OV5640.

The advantages of embedded auto focus solution include:

- The auto focus function is built inside camera module. Baseband or Application Processor could use the module in the same way as fixed focus module.
- The auto focus information is accessed by built-in micro controller in real time. The auto focus calculation is also done by built-in micro-controller. The speed of auto focus is very fast compared to external auto focus solution.

OmniVision had built-in the embedded auto focus control in the firmware of OV5640. This document is only for the firmware of this solution.
2.2 External Auto Focus Solution

For External AF solution, the auto focus control is implemented in Baseband or Application Processor. Baseband or application processors get auto focus information of OV5640 by SCCB interface. Then it does auto focus calculation and send the actuator control command by I2C. The I2c of actuator could be shared with the SCCB control of OV5640.

![Diagram showing OV5640, Driver IC, GPIO, Host, and AF Core connections]

The advantage of external auto focus control is that customer could implement its own auto focus algorithms. The disadvantage is the auto focus speed is not as fast as embedded auto focus.

Since embedded auto focus solution has many advantages over external auto focus solution, only embedded auto focus solution is discussed in details in this document.
3 User Interface

3.1 Command and Status Registers

Eight registers are used for OV5640 firmware interface. The MCU will auto clear CMD_MAIN to zero after the command is receipt, and auto clear CMD_ACK to zero when the command is completed.

<table>
<thead>
<tr>
<th>Name</th>
<th>Register</th>
<th>Description</th>
<th>Read/Write</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>CMD_MAIN</td>
<td>0x3022</td>
<td>main command</td>
<td>W</td>
<td>(1)</td>
</tr>
<tr>
<td>CMD_ACK</td>
<td>0x3023</td>
<td>ACK of command</td>
<td>R/W</td>
<td></td>
</tr>
<tr>
<td>CMD_PARA0</td>
<td>0x3024</td>
<td>Parameter : Byte 0</td>
<td>R/W</td>
<td></td>
</tr>
<tr>
<td>CMD_PARA1</td>
<td>0x3025</td>
<td>Parameter : Byte 1</td>
<td>R/W</td>
<td></td>
</tr>
<tr>
<td>CMD_PARA2</td>
<td>0x3026</td>
<td>Parameter : Byte 2</td>
<td>R/W</td>
<td></td>
</tr>
<tr>
<td>CMD_PARA3</td>
<td>0x3027</td>
<td>Parameter : Byte 3</td>
<td>R/W</td>
<td></td>
</tr>
<tr>
<td>CMD_PARA4</td>
<td>0x3028</td>
<td>Parameter : Byte 4</td>
<td>R/W</td>
<td></td>
</tr>
<tr>
<td>FW_STATUS</td>
<td>0x3029</td>
<td>Running Status of firmware</td>
<td>R</td>
<td></td>
</tr>
</tbody>
</table>

(1) If the command needs parameters, the main command must be the last register to be sent

3.2 Main Command Table

<table>
<thead>
<tr>
<th>Value</th>
<th>Main Command Description</th>
<th>tag/parameters</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x03</td>
<td><em>Trig Auto Focus</em></td>
<td>no</td>
</tr>
<tr>
<td>0x07</td>
<td><em>Get Focus Result</em></td>
<td>need</td>
</tr>
<tr>
<td>0x08</td>
<td><em>Release Focus</em></td>
<td>no</td>
</tr>
<tr>
<td>0x12</td>
<td><em>Re-launch Zone Configuration</em></td>
<td>no</td>
</tr>
<tr>
<td>0x80</td>
<td><em>Launch default zone configuration</em></td>
<td>no</td>
</tr>
<tr>
<td>0x81</td>
<td><em>Set and launch touch mode zone configuration</em></td>
<td>need</td>
</tr>
<tr>
<td>0x8f</td>
<td><em>Enable custom mode zone configuration</em></td>
<td>no</td>
</tr>
<tr>
<td>0x90</td>
<td><em>VVF coordinate: zone 0</em></td>
<td>need</td>
</tr>
<tr>
<td>0x91</td>
<td><em>VVF coordinate: zone 1</em></td>
<td>need</td>
</tr>
<tr>
<td>0x92</td>
<td><em>VVF coordinate: zone 2</em></td>
<td>need</td>
</tr>
<tr>
<td>0x93</td>
<td><em>VVF coordinate: zone 3</em></td>
<td>need</td>
</tr>
<tr>
<td>0x94</td>
<td><em>VVF coordinate: zone 4</em></td>
<td>need</td>
</tr>
<tr>
<td>0x98</td>
<td><em>Set weight of zones</em></td>
<td>need</td>
</tr>
<tr>
<td>0x9f</td>
<td><em>Launch custom zone configuration</em></td>
<td>no</td>
</tr>
<tr>
<td>0xEC</td>
<td><em>Encrypt Command</em></td>
<td>need</td>
</tr>
</tbody>
</table>
3.3 Running Status of firmware

FW_STATUS is the current focus state:

- **0x7F**  
  **S_FIRMWARE**  
  Firmware is downloaded and not run.

- **0x7E**  
  **S_STARTUP**  
  Firmware is initializing.

- **0x70**  
  **S_IDLE**  
  Idle state, focus is released; lens is located at the furthest position.

- **0x10**  
  **S_FOCUSED**  
  Auto Focus is completed.

- **0x16**  
  **S_ZONE_CONFIG**  
  Configure zone mode.

- **0x00-0x0F, 0x80-0x8F**  
  **S_FOCUSING**  
  Auto Focus is running.
4 Firmware User Guide

4.1 Stage - Sensor Init

1) Initialize sensor
2) Download firmware to sensor
3) Checking for the value of FW_STATUS.
   if value == S_IDLE
       Continue
   else
       Go to 3

4.2 Stage - Preview

1) If sensor registers about resolution are changed, **Re-launch Zone Configuration**
   (Main command: 0x12) command is needed.
   
   OV5640_Write( CMD_ACK, 0x01)
   OV5640_Write( CMD_MAIN, 0x12)
   Waiting for (OV5640_Read(CMD_ACK)==0)

4.3 Stage: Zone Configuration

Please refer to the chapter 5.

4.4 Stage: Auto Focus

1) Use **Trig Auto Focus** command to start auto focus
   
   OV5640_Write( CMD_ACK, 0x01)
   OV5640_Write( CMD_MAIN, 0x03)
   Waiting for (OV5640_Read(CMD_ACK)==0)

2) Get Focus Result
   
   OV5640_Write( CMD_ACK, 0x01)
   OV5640_Write( CMD_MAIN, 0x07)
   Waiting for (OV5640_Read(CMD_ACK)==0)
   S_Zone[0]= OV5640_Read(CMD_PARA0)
   S_Zone[1]= OV5640_Read(CMD_PARA1)
   S_Zone[2]= OV5640_Read(CMD_PARA2)
   S_Zone[3]= OV5640_Read(CMD_PARA3)
   S_Zone[4]= OV5640_Read(CMD_PARA4)
   if(S_Zone[i]==0) zone i is focused
   if no zone is focused, the focus is failed.
4.5 Stage: Release Auto Focus

1) Use **Release Focus** command to release focus
   OV5640_Write( CMD_ACK, 0x01)
   OV5640_Write( CMD_MAIN, 0x08)
   Waiting for (OV5640_Read(CMD_ACK)==0)
5 Auto Focus Zone Configuration

The firmware supports 3 zone modes. If special Zone mode is required, please contact with OmniVision local FAE.

5.1 Zone($X_0$, $Y_0$, $X_1$, $Y_1$)

The zone definition is based on the virtual viewfinder (VVF). The full size of VVF is 80 x 60.

5.2 Zone Mode

There are 3 zone modes supported: default zone mode, touch mode, and custom mode. In run-time, the size and position of zones are fixed in default mode, the size is fixed and position can be specified in touch mode. If needing to update the zone size and position in run-time, please use custom mode. If only need to focus on center region, the default mode is better.

5.2.1 Zone Mode 1 – Default zone mode

After initialization, this mode is auto launched.

Zone (32, 24, 48, 36)

How to launch this mode

OV5640_Write( CMD_ACK, 0x01)
OV5640_Write( CMD_MAIN, 0x80)
Waiting for (OV5640_Read(CMD_ACK)==0)
5.2.2 Zone Mode 2 – Touch zone mode

- ZoneEx(X₀, Y₀, X₀+16, Y₀+12)
  - Xₜ <= 72
  - Yₜ <= 54
  Other values are invalid.

- How to set and launch this mode
  - OV5640_Write( CMD_PARA0,   X₀ )
  - OV5640_Write( CMD_PARA1,   Y₀ )
  - OV5640_Write( CMD_ACK,   0x01 )
  - OV5640_Write( CMD_MAIN,  0x81 )
  - Waiting for (OV5640_Read( CMD_ACK )==0)

5.2.3 Zone Mode 3 – Custom mode

In this mode, all the zones is free in run-time. The zones can be defined by User.

- Zone(X₀, Y₀, X₁, Y₁)
  - X₀, X₁ <= 80, X₁ – X₀ >= 8
  - Y₀, Y₁ <= 60, Y₁ – Y₀ >= 8

  **Note:** If need to use zone 0, the Y₁ of zone 0 must be the max in the all zones!!!

- Zone Weight[i]  zone=0,1,2,3,4
  - 0<=ZoneWeight[i]<=8
  - ZoneWeight[i] = 0 means this zone is not to be care of.

- How to set and launch this mode
  1. Enable custom mode zone configuration
     - OV5640_Write( CMD_ACK,   0x01 )
     - OV5640_Write( CMD_MAIN,  0x8f )
     - Waiting for (OV5640_Read( CMD_ACK )==0)
  2. Set VVF coordinate for Zone i
     - OV5640_Write( CMD_PARA0,   X₀ )
     - OV5640_Write( CMD_PARA1,   Y₀ )
     - OV5640_Write( CMD_PARA2,   X₁ )
     - OV5640_Write( CMD_PARA3,   Y₁ )
     - OV5640_Write( CMD_ACK,   0x01 )
     - OV5640_Write( CMD_MAIN, (0x90+i) )
     - Waiting for (OV5640_Read( CMD_ACK )==0)
3. Set Weight for All zones
   OV5640_Write( CMD_PARA0, ZoneWeight[0])
   OV5640_Write( CMD_PARA1, ZoneWeight[1])
   OV5640_Write( CMD_PARA2, ZoneWeight[2])
   OV5640_Write( CMD_PARA3, ZoneWeight[3])
   OV5640_Write( CMD_PARA4, ZoneWeight[4])
   OV5640_Write( CMD_ACK, 0x01)
   OV5640_Write( CMD_MAIN, 0x98)
   Waiting for (OV5640_Read(CMD_ACK)==0)

4. Launch custom mode zone configuration
   OV5640_Write( CMD_ACK, 0x01)
   OV5640_Write( CMD_MAIN, 0x9f)
   Waiting for (OV5640_Read(CMD_ACK)==0)
6 Update History

July 30, 2010 Version 1.0
Firmware Version V1.00
P3-7, new define of STA_STATUS