

TEA685X User Manual

Device version /V102

Rev. 1.2 — 15 April 2014

User Manual

Document information

Info	Content
Keywords	Tiger-2, TEA6850, TEA6851, TEA6852, TEA6853, /V102, firmware 2.00, API, I ² C bus, control, car radio
Abstract	Overview of TEA685X series device control



Revision history

Rev	Date	Description
		'Tiger-2' TEA6850, TEA6851, TEA6852 and TEA6853, device version V102, user manual Description of the TEA685X/V102 control interface (API) and related information
1.2	20140415	Change bars indicate changes from V102 user manual Rev. 1.1 6.2.1 , 6.2.2 , 6.2.3 updated with V102 required initialization p2.15
1.1	20140324	6.2.1 , 6.2.2 , 6.2.3 updated with V102 required initialization p2.14
1.0	20140306	6.2.1 , 6.2.2 , 6.2.3 updated with V102 required initialization p2.13
0.8	20140129	3.21 added note on ana_out = 2 3.32 corrected type numbers 4.2.3 increased allowed times using RDS data buffer 6.2.1 , 6.2.2 , 6.2.3 updated with V102 required initialization p2.12
0.6	20131210	6.2.1 , 6.2.2 , 6.2.3 updated with V102 required initialization p2.10
0.5	20131106	6.2.1 , 6.2.2 , 6.2.3 updated with V102 required initialization p2.09
0.4	20131018	Initial version

Contact information

For more information, please visit: <http://www.nxp.com>

For sales office addresses, please send an email to: salesaddresses@nxp.com

1. Introduction

TEA685X ('Tiger-2') is a series of low cost single-chip car radio devices. The devices are consumer qualified and primarily intended for aftersales ('non-OEM') market use.

The Tiger-2 series consists of four variants with increasing functionality; TEA6850, TEA6851, TEA6852 and TEA6853.

All Tiger-2 variants offer worldwide standard FM band reception as well as AM LW and MW band reception. In addition to the TEA6850 feature set the TEA6851, TEA6852 and TEA6853 offer FM-OIRT band reception and FM enhanced multipath suppression ('EMS') for improved field performance. On top of that the TEA6852 and TEA6853 include RDS/RBDS data reception and the TEA6853 additionally offers connectivity and support for digital radio operation as well as AM SW band reception up to 27 MHz.

This user manual describes the TEA685X series control interface or API (Application Programming Interface). The document describes the available write and read commands with parameter and data definitions.

This document version contains limited background information regarding the feature functionality and the offered control options so some general knowledge of car radio functions is required.

This user manual describes the functionality and control of the TEA685X device version V102 specifically (TEA685X/V102).

2. Control interface

2.1 Overview

The TEA685X devices are equipped with an I²C bus interface for control of the device. Full control of the device functions and features is available using this single interface.

The I²C bus supports bit rates of up to 400 kbit/s in accordance with the 'fast mode' I²C bus specification.

The control interface is described in this document on an abstract 'application' level as well as on I²C protocol level.

The TEA685X interface definition is compatible with the TEF668X (Lithio), the TEF665X (Atomic-2) and the TEF701X (Sabre) series of devices, although differing in available commands reflecting the available functionality.

Future NXP car radio devices will employ the same interface allowing compatible control between device types, versions and variants.

Via the I²C bus commands and parameters can be written to the device and information can be read from the device.

TEA685X control is organized in modules. Modules are independent functional blocks that can be regarded sub-devices within the device.

The TEA685X consists of four modules:

- module 32 : FM = FM radio reception
- module 33 : AM = LW, MW and SW radio reception
- module 48 : AUDIO = Audio processing
- module 64 : APPL = System and application control

Different modules can be controlled independently even when the addressed module itself is inactive at the time of control. This means modules can be prepared and initialized before use.

Compatible command definitions have been used for the modules of FM and AM radio where applicable. Defaults and range definitions may differ in some cases to fit the different band properties.

Module commands have one or more parameters for control of the module behavior and option selections.

The control is organized in such a way that future devices may support writing of a single parameter up to writing of all parameters available for a given command.

Device version V102 however does not offer this flexibility and requires all command parameters described in this document to be transmitted.

[Fig 1](#) represents the TEA685X control interface as seen from the host controller.

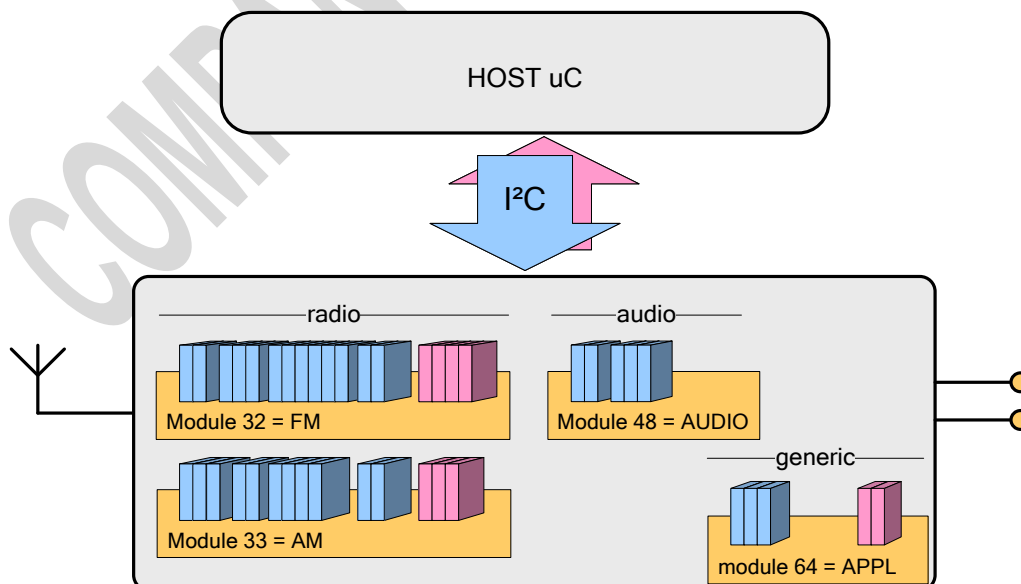


Fig 1. I2C control –TEA685X

TEA685X device variants are fully control compatible, although differing in available features. Future derivatives of these devices will remain compatible also but possibly with a different variation and extension in supported functions and features.

The API template of TEA685X and compatible devices will be used in future NXP car-radio developments also, offering compatible control with additional variation in supported functions and features.

The parameter ranges as depicted in this document are the guaranteed ranges for operation. Control outside of these ranges is not allowed for application.

The command parameters in general allow for a higher range and granularity than what is available from TEA685X. Parameters can be set to any value within the documented range even where the actual number of available settings is less than offered by the parameter. In these cases the TEA685X will realize the nearest available setting.

Information regarding the actual available granularity is limited in this document but will be extended in future user manual updates.

2.2 History

The control interface of the TEA685X has been improved over previous product generations in order to ensure and offer:

- **Extendibility:** Extension of modules, commands and parameters allowing addition and extension of control options, features and functionality for future car radio devices from low-end to high-end.
- **Granularity and range:** The parameter definition allows for extremely detailed parameter setting and range extension where needed in the future.
- **Reduced control effort:** Although not supported for device version V102 the interface definition allows for single parameter manipulation simplifying user control software.

Although no direct compatibility is present it should be noted that the TEA685X command interface shares most of its API functionality with previous products. A translation from previous generation style control to the TEA685X control can therefore be made with little effort. Description semantics and description units have been maintained between generations to support easy transfer of settings.

3. Write commands

Write commands allow control or setting of specific features. Writing consists of a module, a command and an index value generally followed by one or more parameter values.

The module value defines the processing part that is addressed. Modules are integral functional parts of the device that can be regarded sub-devices. Available modules in the TEA685X are 32 'FM' for FM radio, 33 'AM' for AM radio, 48 'AUDIO' for audio processing and 64 'APPL' for application and system settings.

The command value defines a control function, a feature setting or a set of feature settings.

The index value is present for future use to allow writing of certain specific parameter parts out of the available command parameters.

Device version V102 requires index = 1 to be used and requires all command parameters described in this user manual to be transmitted.

The first parameter starts from index = 1.

Write commands are only available in the device 'active state' operation modes with the exception of certain APPL commands available during 'idle state'.

Independent from the selected 'active state' operation mode ('radio standby', 'FM' or 'AM') the write commands of every module are available for writing so full device initialization is possible in any of the 'active state' operation modes.

Note: FM radio and AM radio are never available together. Enabling of one radio module (by a tuning action command on that module) will disable the other radio module but control to the disabled radio module remains available for initialization purposes.

For detailed information on the I²C protocol for write commands see [5.2 Write control](#).

3.1 FM / AM cmd 1 Tune_To

Tuning within the active radio band or tuning to a different radio band with selection of FM / AM operation.

module	32 / 33	FM / AM
cmd	1	Tune_To
index	1	mode
		[15:0]
		mode, frequency
		tuning actions
		0 = no action (reserved)
		1 = Preset
		Tune to new program with short mute time
		Enable radio and FM/AM change where applicable
		2 = Search
		Tune to new program and stay muted
		Enable radio and FM/AM change where applicable
	FM	3 = AF-Update
		Tune to alternative frequency, store quality
		and tune back with inaudible mute
		4 = Jump
		Tune to alternative frequency with short
		inaudible mute
		5 = Check
		Tune to alternative frequency and stay
		muted
	AM	3 ... 5 = reserved
		6 = reserved
		7 = End
		Release the mute of a Search or Check action
		(frequency is not required and ignored)
	2	frequency
		[15:0]
		tuning frequency
		FM
		6500 ... 7400
		65.00 ... 74.00 MHz (not for TEA6850)
		7600 ... 10800
		76.00 ... 180.00 MHz / 10 kHz step size
		AM LW
		144 ... 288
		144 ... 288 kHz / 1 kHz step size
		MW
		522 ... 1710
		522 ... 1710 kHz / 1 kHz step size
		SW
		2300 ... 27000
		2.3 ... 27 MHz / 1 kHz step (TEA6853 only)

Application example FM_Tune_To (1, 1, 8930)
 AM_Tune_To (1, 2, 990)
 AM_Tune_To (1, 7)

Preset tuning to FM 89.3 MHz
 Search tuning (from FM) to AM 990 kHz
 End (release mute of AM Search action)

I²C example (hex) [w 20 01 01 0001 22E2]
 [w 21 01 01 0002 03DE]
 [w 21 01 01 0007]

Preset tuning to FM 89.3 MHz
 Search tuning (from FM) to AM 990 kHz
 End (release mute of Search action)

3.1.1 radio tuning actions with setting of band and frequency

The mode control parameter allows for execution of different radio tuning actions.

The tuning actions take care of every detail of radio tuning; next to the obvious tuner functions of band switching and frequency adjustment additional control is active for inaudible audio mute, reset of quality detectors, reset or hold of weak signal processing control and suppression of pop noise. All this functionality is an integrated part of

TEA685X tuning. The set of tuning actions offered by TEA685X is an NXP standard and found in car radio devices for many generations.

The set of tuning actions frees the controlling μ C from all non-essential timing and control complexity, however control flexibility is not limited in any way because the full 'decision intelligence' remains at the μ C side. The tuning actions can be regarded building blocks for creating the desired radio tuning control. Tuning actions can be chained together to build complete tuning routines or realize a single basic routine by themselves.

A total of six mode tuning actions are defined for different types of tuning.

mode = 1 ; Preset

mode = 1 performs a complete 'Preset-change' tuning for tuning to a new program or possibly to a new band. For a Preset-change it is desired to start the new program immediately with the best quality possible, therefore time constants of the weak signal handling and AM demodulator AGC are controlled for fast settling to the new signal conditions within a small preset mute time of approx. 32 ms for FM and 60 ms for AM bands.

mode = 2 ; Search:

mode = 2 performs a tuning action to create a search to a new program (previous / next search) or searching for several programs (auto-store).

Search is equal in function to a Preset action however the mute is not released automatically. This allows signal conditions to be checked while muted and when insufficient reception quality is found a new Search action can be activated again and again for a new frequency until a valid search stop condition is found.

Mute can then be released by an End action (mode = 7).

Also a Preset may be used as the last 'search' tuning action to release mute.

Preset and Search employ a 10 ms mute and de-mute slope timing for gentle program switching, so actual tuning is delayed by 10 ms. In case mute is already active (like from a previous Search action) no mute delay is present and tuning is started instantly.

A Preset and Search tuning action also allows for band switching between FM and AM. An AM Preset or AM Search will disable 'radio standby' or 'FM' operation and enable AM module operation. Equally an FM Preset or FM Search will enable FM module operation.

Note the 10 ms mute delay time should also be taken into account when switching between FM and AM module operation.

mode = 3 ; AF_Update:

mode = 3 performs a complete 'alternative frequency update' tuning cycle for inaudible testing of the quality of alternative frequencies in the background. AF_Update tunes to an alternative frequency, gathers signal quality information and returns to the original frequency within a very short time.

Inaudible mute is employed and the measured AF quality information is stored for easy read-out by I²C. Time constants of the weak signal handling and DC decoupling are controlled so they are not disturbed by the AF signal conditions.

A default AF_Update cycle finishes within 6 ms for the complete action including mute enabling and disabling.

For AF_Update options like the bandwidth used during AF_Update tuning see [3.2 FM cmd 2 Set Tune Options](#).

mode = 4 ; Jump:

mode = 4 performs a complete tuning action for switching to a 'known' alternative frequency. Jump performs a tuning with a minimum mute time, only intended to suppress PLL tuning disturbances. Starting from the control setting of the previous frequency the weak signal handling will change gradually to the new signal conditions using the standard weak signal timings, as desired for an inaudible switching to an alternative frequency with the same program.

Since Jump releases mute automatically it must be assumed that the new frequency indeed contains the same program. Should it later be found this is not the case (e.g. by reading the RDS PI code) a new Jump is the designated tuning action for a fast return to the original frequency.

mode = 5 ; Check:

mode = 5 performs a tuning action for switching to an 'unknown' alternative frequency. Check is equal in function to a Jump action however the mute is not released automatically. During the Check mute an RDS PI code can be searched for and verified and if a valid program is found mute can be released by an End action (mode = 7). During mute the weak signal handling is not disturbed by the new signal conditions and after mute release the weak signal handling will gradually change to the new conditions using the standard weak signal timings. In case an invalid program is found a Jump is the designated tuning action for a fast return to the original frequency.

It is possible to string several Check transmissions together to create an AF_Update like routine for checking several AF signal conditions in a row. Such a string of Check transmissions may be finished by mode = End or Jump or, alternatively, by mode = AF_Update in which case a 'standard' AF_Update is executed with quality data hold while returning to the original frequency as present before the string of Check tunings.

Note: AF_Update, Jump and Check employ a 1 ms mute and de-mute slope timing for fast inaudible switching, so actual tuning is delayed by 1 ms. In case mute is already active (presumably by a previous Check action) no mute delay is present and tuning is started instantly.

mode = 7 ; End:

mode = 7 ends a currently active tuning action. End releases the sustained mute of a Search (mode = 2) or Check (mode = 5) tuning action.

An End action does not require any additional data, so only the mode parameter needs to be transmitted. In case the frequency is included it is ignored. End is only effective for the currently active radio band (module setting).

3.2 FM cmd 2 Set_Tune_Options

Settings used during a tuning action (FM AF_Update).

module
cmd
index

32	FM	
2	Set_Tune_Options	afu_bw_mode, afu_bandwidth, afu_mute_time, afu_sample_time
1	afu_bw_mode [15:0]	IF bandwidth control mode during AF_Update 0 = fixed (default) 1 = automatic bandwidth
2	afu_bandwidth [15:0]	fixed IF bandwidth during AF_Update 970 ... 3110 [*0.1 kHz] = IF bandwidth 97 ... 311 kHz; narrow ... wide 2360 = 236 kHz (default)
3	afu_mute_time [15:0]	AF_update inaudible mute slope time 250 ... 1000 [* 1 us] = 0.25 ... 1 ms 1000 = 1 ms (default)
4	afu_sample_time [15:0]	AF_update sampling time 1000 ... 20000 [* 1 us] = 1 ... 20 ms 2000 = 2 ms (default)

Application example FM_Set_Tune_Options (1, 0, 1680, 1000, 2000) 168 kHz bandwidth during AFU

I²C example (hex) [w 20 02 01 0000 0690 03E8 07D0] 168 kHz bandwidth during AFU

Note: afu_sample_time is accurate to 1 ms intervals and a minimum of 2 ms is advised for sufficient settling of all quality detectors.

3.3 FM / AM cmd 10 Set_Bandwidth

Fixed bandwidth selection of the radio selectivity filter.

For FM automatic bandwidth control can be selected with control sensitivity options.

module	32 / 33	FM / AM
cmd	10	Set_Bandwidth
		FM : mode, bandwidth, control_sensitivity, low_level_sensitivity AM : mode, bandwidth
index	1	mode [15:0]
		IF bandwidth control mode
		FM 0 = fixed 1 = automatic (default)
		AM 0 = fixed (default)
	2	bandwidth [15:0]
		fixed IF bandwidth
		FM 970 ... 3110 [*0.1 kHz] = IF bandwidth 97 ... 311 kHz; narrow ... wide 2360 = 236 kHz (default)
		AM 30 ... 80 [*0.1 kHz] = IF bandwidth 3 ... 8 kHz; narrow ... wide 40 = 4.0 kHz (default)
	3	control_sensitivity [15:0]
		FM automatic IF bandwidth control sensitivity
		500 ... 1500 [*0.1 %] = 50 ... 150 % relative adjacent channel sensitivity 1000 = 100 % (default)
	4	low_level_sensitivity [15:0]
		FM automatic IF bandwidth control sensitivity for low level conditions
		500 ... 1500 [*0.1 %] = 50 ... 150 % relative adjacent channel sensitivity 1000 = 100 % (default)

Application example	FM_Set_Bandwidth (1, 1, 2360, 1000, 1000)	All parameters with FM default value
	AM_Set_Bandwidth (1, 0, 40)	All parameters with AM default value
	FM_Set_Bandwidth (1, 0, 2360, 1000, 1000)	bandwidth = fixed 236 kHz
	FM_Set_Bandwidth (1, 1, 2360, 800, 1000)	control_sensitivity = 80 %
	FM_Set_Bandwidth (1, 1, 2360, 1000, 800)	control+low_level sensitivity = 80 %

I ² C example (hex)	[w 20 0A 01 0001 0938 03E8 03E8]	All parameters with FM default value
	[w 21 0A 01 0000 0028]	All parameters with AM default value
	[w 20 0A 01 0000 0938 03E8 03E8]	FM bandwidth = fixed 236 kHz
	[w 20 0A 01 0001 0938 0320 03E8]	control_sensitivity = 80 %
	[w 20 0A 01 0001 0938 03E8 0320]	control+low_level sensitivity = 80 %

Note: For FM the following twelve bandwidth settings are supported: 97 / 114 / 133 / 151 / 168 / 184 / 200 / 217 / 236 / 254 / 287 / 311 kHz.

For AM the following four bandwidth settings are supported: 3 / 4 / 6 / 8 kHz.

Other bandwidth parameter values are rounded to the nearest supported bandwidth.

3.4 FM / AM cmd 11 Set_RFAGC

Start level of the tuner front-end AGC.

Performance balancing of desensitization (high start level) against inter-modulation (low start level).

module	32 / 33	FM / AM
cmd	11	Set_RFAGC FM: start, extension AM: start
index	1	start [15:0] RF AGC start FM 860 ... 900 [*0.1 dBµV] = 86 ... 90 dBµV 920 = 92 dBµV (default) AM 960 ... 1000 (*0.1 dBµV) = 96 ... 100 dBµV 1000 = 100 dBµV (default)
	2	extension [15:0] reserved FM 0 = (default) AM reserved
Application example	FM_Set_RFAGC (1, 890, 0) FM RF AGC start at 89 dBµV AM_Set_RFAGC (1, 970) AM RF AGC start at 97 dBµV	
I²C example (hex)	[w 20 0B 01 037A 0000] FM RF AGC start at 89 dBµV [w 21 0B 01 03CA] AM RF AGC start at 97 dBµV	

Note: Transmission of FM parameter 2 is not required.

3.5 AM cmd 12 Set_Antenna

AM antenna attenuation control (RF AGC attenuation limit).
In case of an AM active antenna application part of the required level correction can be located in the front-end.

module	33	AM
cmd	12	Set_Antenna
		attenuation
	1	attenuation
		[15:0]
		LNA gain reduction
		0 / 60 / 120 / 180 / 240 / 300 / 360 (*0.1 dB) = 0 ... 36 dB antenna
		attenuation (6 dB step size)
		0 = no attenuation (default)

Application example AM_Set_Antenna (1, 180) AM 18 dB antenna attenuation

I²C example (hex) [w 21 0c 01 00b4] AM 18 dB antenna attenuation

3.6 FM cmd 20 Set_MphSuppression

Available for TEA6851, TEA6852 and TEA6853 only.

Optional use of the 'EMS' FM multipath suppression system.

module	32	FM	
cmd	20	Set_MphSuppression	mode
index	1	mode	FM multipath suppression
		[15:0]	0 = off (default)
			1 = on
Application example	FM_Set_MphSuppression (1, 1)		Enable the multipath suppression
	FM_Set_MphSuppression (1, 0)		Disable the multipath suppression
I ² C example (hex)	[w 20 14 01 0001]		Enable the multipath suppression
	[w 20 14 01 0000]		Disable the multipath suppression

Note: The advised setting is 'on' for improved field performance.

3.7 FM / AM cmd 23 Set_NoiseBlanker

Noise blanker options and sensitivity setting.

module	32 / 33	FM / AM	
cmd	23	Set_NoiseBlanker	mode, sensitivity
index	1	mode [15:0]	noise blanker
			0 = off
			1 = on (default)
	2	sensitivity [15:0]	trigger sensitivity 500 ... 1500 [*0.1 %] = 50 ... 150 % relative trigger sensitivity 1000 = 100 % (default)
Application example	FM_Set_NoiseBlanker (1, 1, 1000) AM_Set_NoiseBlanker (1, 1, 1000) AM_Set_NoiseBlanker (1, 1, 1200)		FM default values AM default values sensitivity 120% for more suppression
I ² C example (hex)	<pre>[w 20 17 01 0001 03E8] [w 21 17 01 0001 03E8] [w 21 17 01 0001 04B0]</pre>		FM default values AM default values sensitivity 120% for more suppression

3.8 AM cmd 24 Set_NoiseBlanker_Audio

AM Audio noise blanker options and sensitivity setting.

module	33	AM	
cmd	24	Set_NoiseBlanker_Audio	mode, sensitivity
index	1	mode [15:0]	AM audio noise blanker (audio frequency detection)
			0 = off
			1 = on (default)
	2	sensitivity [15:0]	AM audio noise blanker trigger sensitivity 500 ... 1500 [*0.1 %] = 50 ... 150 % relative trigger sensitivity 1000 = 100 % (default)
Application example	AM_Set_NoiseBlanker_Audio (1, 1, 1000) AM_Set_NoiseBlanker_Audio (1, 1, 1200)		AM default values sensitivity 120% for more suppression
I ² C example (hex)	<pre>[w 21 18 01 0001 03E8] [w 21 18 01 0001 04B0]</pre>		AM default values sensitivity 120% for more suppression

3.9 FM / AM cmd 30 Set_DigitalRadio

Available for TEA6853 only.

Enabling of signal lines for external digital radio processor; DR I²S output.

Note: See [3.20 FM / AM cmd 84 Set_DR_Options](#) for additional digital radio options.

module	32 / 33	FM / AM	
cmd	30	Set_DigitalRadio	mode
index	1	mode [15:0]	digital radio 0 = off (default) 1 = on
Application example	FM_Set_DigitalRadio (1, 1) Enable digital radio for FM use AM_Set_DigitalRadio (1, 1) Enable digital radio for AM use		
I ² C example (hex)	[w 20 1E 01 0001] Enable digital radio for FM use [w 21 1E 01 0001] Enable digital radio for AM use		

3.10 FM cmd 31 Set_Deemphasis

Selection of FM deemphasis time constant

module	32	FM	
cmd	31	Set_Deemphasis	timeconstant
index	1	timeconstant [15:0]	deemphasis time constant 0 = off; for evaluation purposes only 500 = 50 μ s deemphasis (default) 750 = 75 μ s deemphasis
Application example	FM_Set_Deemphasis (1, 750) 75 μ s deemphasis		
I ² C example (hex)	[w 20 1F 01 02EE] 75 μ s deemphasis		

3.11 FM / AM cmd 38 Set_LevelStep

Selection of level correction as a function of the tuner front-end AGC.

The level step offset is included in the weak signal handling and the level read value of Get_Quality ([4.1 FM / AM cmd 128 / 129 Get_Quality](#)).

A setting of 0 dB will show no level change by full compensation of the actual -6 dB AGC attenuation step. Instead a setting of -6 dB will show the actual AGC attenuation step.

module

32 / 33 FM / AM

cmd

38 Set_LevelStep

step1, step2, step3, step4, step5, step6, step7

index

1	step1 [15:0]	level offset for an AGC step from 0 to 1 -60 ... 0 (*0.1 dB) = -6 ... 0 dB -20 = -2 dB (FM default) / -10 = -1 dB (AM default)
2	step2 [15:0]	level offset for an AGC step from 1 to 2 -60 ... 0 (*0.1 dB) = -6 ... 0 dB -30 = -3 dB (FM default) / -20 = -2 dB (AM default)
3	step3 [15:0]	level offset for an AGC step from 2 to 3 -60 ... 0 (*0.1 dB) = -6 ... 0 dB -40 = -4 dB (FM default) / -30 = -3 dB (AM default)
4	step4 [15:0]	level offset for an AGC step from 3 to 4 -60 ... 0 (*0.1 dB) = -6 ... 0 dB -50 = -5 dB (FM default) / -40 = -4 dB (AM default)
5	step5 [15:0]	level offset for an AGC step from 4 to 5 -60 ... 0 (*0.1 dB) = -6 ... 0 dB -60 = -6 dB (FM default) / -50 = -5 dB (AM default)
6	step6 [15:0]	level offset for an AGC step from 5 to 6 -60 ... 0 (*0.1 dB) = -6 ... 0 dB -60 = -6 dB (default)
7	step7 [15:0]	level offset for an AGC step from 6 to 7 (or higher) -60 ... 0 (*0.1 dB) = -6 ... 0 dB -60 = -6 dB (default)

Application example

AM_Set_LevelStep(1, 0, -10, -20, -30, -40, -50, -60) AM increased level extension
 AM_Set_LevelStep(1, -20, -30, -40, -50, -60, -60, -60) AM decreased level extension

I²C example (hex)

[w 21 26 01 0000 FFF6 FFEC FFE2 FFD8 FFCE FFC4] AM increased level extension
 [w 21 26 01 FFEC FFE2 FFD8 FFCE FFC4 FFC4 FFC4] AM decreased level extension

Note: Adaptation of the LevelStep default values is not advised in general but allows for a specific fine-tuning of the weak signal handling in high signal conditions.

Note: The indicated steps are the added values of feedback and input AGC steps.

Note: AGC steps higher than step 7 will employ the step 7 setting.

3.12 FM / AM cmd 39 Set_LevelOffset

Selection of level correction.

The level offset can be used as an overall correction for antenna noise level and is included in the weak signal handling and the level read value of Get_Quality (4.1 FM / AM cmd 128 / 129 Get_Quality). A standard use case is the compensation for AM active antenna circuits (typical offset setting = -30 dB).

module	32 / 33	FM / AM
cmd	39	Set_LevelOffset
index	1	offset
		[15:0] signed
		level offset
		-480 ... +150 (*0.1 dB) = -48 ... +15 dB
		0 = 0 dB (default)
Application example	AM_Set_LevelOffset (1, -300)	-30 dB level correction
I ² C example (hex)	[w 21 27 01 FED4]	-30 dB level correction

3.13 FM / AM cmd 40 ... 45 Set_Softmute

Timing and quality sensitivity settings for the Softmute weak signal handling.

'Set_Softmute_Time' defines the weak signal handling response times active for the level detector and FM noise and multipath detectors. Fast and slow response times are available for dual timer functionality, with enable options at the level, noise and mph commands.'

'Set_Softmute_Level' sets the level sensitivity and enables slow and fast timing.

'Set_Softmute_Noise' and 'Set_Softmute_Mph' set the noise and multipath sensitivity and enables slow and fast timing (FM only)

'Set_Softmute_Max' enables and defines the maximum amount of softmute attenuation (as realized for poor signal conditions).

module	32 / 33	FM / AM
cmd	40	Set_Softmute_Time slow_attack, slow_decay, fast_attack, fast_decay
index	1	slow_attack [15:0] slow attack time of weak signal handling 60 ... 2000 (ms) = 60 ms ... 2 s slow attack time 120 = 120 ms (default)
	2	slow_decay [15:0] slow decay time of weak signal handling 120 ... 12500 (ms) = 120 ms ... 12.5 s slow attack time 500 = 500 ms (default)
	3	fast_attack [15:0] fast attack time of weak signal handling 10 ... 1200 (*0.1 ms) = 1 ms ... 120 ms fast attack time 20 = 2 ms (FM default) / 120 = 12 ms (AM default)
	4	fast_decay [15:0] fast decay time of weak signal handling 20 ... 5000 (*0.1 ms) = 2 ms ... 500 ms fast attack time 20 = 2 ms (FM default) / 500 = 50 ms (AM default)

Application example	FM_Set_Softmute_Time (1, 120, 500, 10, 20)	Slow 120 / 500 ms, fast 1 / 2 ms
	AM_Set_Softmute_Time (1, 500, 4000, 100, 500)	Slow 500 / 4000 ms, fast 10 / 50 ms

I ² C example (hex)	[w 20 28 01 0078 01F4 000A 0014]	Slow 120 / 500 ms, fast 1 / 2 ms
	[w 21 28 01 01F4 0FA0 0064 01F4]	Slow 500 / 4000 ms, fast 10 / 50 ms

Note: Suggested FM setting is 1 ms fast_attack for improved field performance.

module	32 / 33	FM / AM
cmd	42	Set_Softmute_Level mode, start, slope
index	1	mode [15:0] timer selection 0 = off (only for evaluation) 1 = fast timer control

		2 = slow timer control (default)
		3 = dual timer control; combined fast and slow timer control
2	start [15:0]	weak signal handling level start 0 ... 500 [*0.1 dB μ V] = control when level falls below 0 dB μ V ... 50 dB μ V 150 = 15 dB μ V (FM default) / 280 = 28 dB μ V (AM default)
3	slope [15:0]	weak signal handling level range 60 ... 300 [*0.1 dB] = control over level range of 6 dB ... 30 dB 220 = 22 dB (FM default) / 250 = 25 dB (AM default)

Note: Suggested AM setting for LW band is 34 dB μ V start and 30 dB slope for improved field performance.

module

cmd

index

32	FM	
43	Set_Softmute_Noise	mode, start, slope
1	mode [15:0]	timer selection 0 = off (default) 1 = fast timer control 2 = slow timer control 3 = dual timer control; combined fast and slow timer control
2	start [15:0]	FM weak signal handling noise start 0 ... 800 [*0.1 %] = control when noise above 0... 80% of USN detector 500 = 50% (default)
3	slope [15:0]	FM weak signal handling noise range 100 ... 1000 [*0.1 %] = control over range of 10... 100% of USN detector 1000 = 100% (default)

module

cmd

index

32	FM	
44	Set_Softmute_Mph	mode, start, slope
1	mode [15:0]	timer selection 0 = off (default) 1 = fast timer control 2 = slow timer control 3 = dual timer control; combined fast and slow timer control
2	start [15:0]	FM weak signal handling multipath start 0 ... 800 [*0.1 %] = control when mph above 0... 80% of WAM detector 500 = 50% (default)
3	slope [15:0]	FM weak signal handling multipath range 100 ... 1000 [*0.1 %] = control over range of 10... 100% of WAM detector 1000 = 100% (default)

module	32 / 33	FM / AM
cmd	45	Set_Softmute_Max mode, limit
index	1	mode
		[15:0]
		weak signal handling (dynamic control)
	2	limit
		[15:0]
		softmute dynamic attenuation limit
		0 ... 400 [*0.1 dB] = 0 ... 40 dB softmute maximum attenuation 200 = 20 dB (FM default) / 250 = 25 dB (AM default)

Application example	FM_Set_Softmute_Max (1, 1, 240)	FM 24 dB max. softmute attenuation
	AM_Set_Softmute_Max (1, 1, 300)	AM 30 dB max. softmute attenuation

I ² C example (hex)	[w 20 2D 01 0001 00F0]	FM 24 dB max. softmute attenuation
	[w 21 2D 01 0001 012C]	AM 30 dB max. softmute attenuation

Suggested AM setting for LW band is 33 dB limit.

3.14 FM / AM cmd 50 ... 59 Set_Highcut

Timing and quality sensitivity settings for the Highcut weak signal handling.

'Set_Highcut_Time' defines the weak signal handling response times active for the level detector and FM noise and multipath detectors. Fast and slow response times are available for dual timer functionality, with enable options at the level, noise and mph commands.'

'Set_Highcut_Level' sets the level sensitivity and enables slow and fast timing.

'Set_Highcut_Noise' and 'Set_Highcut_Mph' set the noise and multipath sensitivity and enables slow and fast timing (FM only)

'Set_Highcut_Max' enables and defines the maximum amount of Highcut attenuation (as realized for poor signal conditions).

'Set_Highcut_Min' optionally defines a minimum amount of Highcut attenuation (as realized for good signal conditions).

'Set_Lowcut_Min' optionally defines a minimum attenuation for low signal frequencies.

'Set_Highcut_Options' allows selection between three different Highcut control characteristics (FM only).

module	32 / 33	FM / AM
cmd	50	Set_Highcut_Time slow_attack, slow_decay, fast_attack, fast_decay
index	1	slow_attack [15:0] slow attack time of weak signal handling 60 ... 2000 (ms) = 60 ms ... 2 s slow attack time 500 = 500 ms (default)
	2	slow_decay [15:0] slow decay time of weak signal handling 120 ... 12500 (ms) = 120 ms ... 12.5 s slow attack time 2000 = 2 s (default)
	3	fast_attack [15:0] fast attack time of weak signal handling 10 ... 1200 (*0.1 ms) = 1 ms ... 120 ms fast attack time 20 = 2 ms (FM default) / 120 = 12 ms (AM default)
	4	fast_decay [15:0] fast decay time of weak signal handling 20 ... 5000 (*0.1 ms) = 2 ms ... 500 ms fast attack time 20 = 2 ms (FM default) / 500 = 50 ms (AM default)
Application example	FM_Set_Highcut_Time (1, 200, 500, 10, 80) Slow 200 / 500 ms, fast 1 / 8 ms AM_Set_Highcut_Time (1, 500, 4000, 100, 500) Slow 500 / 4000 ms, fast 10 / 50 ms	
I ² C example (hex)	[w 20 32 01 00C8 01F4 000A 0050] Slow 200 / 500 ms, fast 1 / 8 ms [w 21 32 01 01F4 0FA0 0064 01F4] Slow 500 / 4000 ms, fast 10 / 50 ms	

Note: Suggested FM settings are 200 ms slow_attack, 1 ms fast_attack and 8 ms fast_decay for improved field performance.

module

32 / 33 FM / AM

cmd

52 Set_Highcut_Level mode, start, slope

index

- | | | |
|---|-------------------|--|
| 1 | mode
[15:0] | timer selection

0 = off (only for evaluation)
1 = fast timer control
2 = slow timer control (AM default)
3 = dual timer control; combined fast and slow timer control (FM default) |
| 2 | start
[15:0] | weak signal handling level start
200 ... 600 [*0.1 dB μ V] = control when level is below 20 dB μ V ... 60 dB μ V
360 = 36 dB μ V (FM default) / 400 = 40 dB μ V (AM default) |
| 3 | slope
[15:0] | weak signal handling level range
60 ... 300 [*0.1 dB] = control over level range of 6 dB ... 30 dB
300 = 30 dB (FM default) / 200 = 20 dB (AM default) |

Note: Suggested AM setting for MW and SW band is 47 dB μ V start for improved field performance. Suggested for AM LW band is 52 dB μ V start.

module

32 FM

cmd

53 Set_Highcut_Noise mode, start, slope

index

- | | | |
|---|-------------------|--|
| 1 | mode
[15:0] | timer selection

0 = off
1 = fast timer control
2 = slow timer control (default)
3 = dual timer control; combined fast and slow timer control |
| 2 | start
[15:0] | FM weak signal handling noise start
0 ... 800 [*0.1 %] = control when noise above 0... 80% of USN detector
360 = 36% (default) |
| 3 | slope
[15:0] | FM weak signal handling noise range
100 ... 1000 [*0.1 %] = control over range of 10... 100% of USN detector
300 = 30% (default) |

Note: Suggested is 'dual timer' mode, 15% start and 20% slope for improved field performance.

module

32 FM

cmd

54 Set_Highcut_Mph mode, start, slope

index

- | | | |
|---|------------------|--|
| 1 | mode
[15:0] | timer selection

0 = off (only for evaluation)
1 = fast timer control
2 = slow timer control (default) |
|---|------------------|--|

		3 = dual timer control; combined fast and slow timer control
2	start [15:0]	FM weak signal handling multipath start 0 ... 800 [*0.1 %] = control when mph above 0... 80% of WAM detector 360 = 36% (default)
3	slope [15:0]	FM weak signal handling multipath range 100 ... 1000 [*0.1 %] = control over range of 10... 100% of WAM detector 300 = 30% (default)

Note: Suggested is 'dual timer' mode, 18% start and 20% slope for improved field performance.

module	32 / 33	FM / AM
cmd	55	Set_Highcut_Max mode, limit
index	1	mode [15:0] weak signal handling (dynamic control) 0 = off; for evaluation only 1 = on; maximum dynamic control set by limit parameter (default)
	2	limit [15:0] Highcut attenuation limit FM Highcut corner frequency for maximum -3 dB attenuation 4000 = 4 kHz (default) 1500 ... 7000 [*1 Hz] = 1.5 ... 7 kHz 'IIR' filter (Options '1' (default)) 700 ... 3000 [*1 Hz] = 0.7 ... 3 kHz 'deemphasis' mode (Options '2') 2700 ... 7000 [*1 Hz] = 2.7 ... 7 kHz 'FIR' highcut filter (Options '3') AM 1350 ... 7000 [*1 Hz] = 1.35 ... 7 kHz Highcut maximum -3 dB att. 1800 = 1.8 kHz (default)

Application example FM_Set_Highcut_Max (1, 1, 2400) FM 2.4 kHz max. Highcut attenuation
AM_Set_Highcut_Max (1, 1, 1500) AM 1.5 kHz max. Highcut attenuation

I²C example (hex) [w 20 37 01 0001 0960] FM 2.4 kHz max. Highcut attenuation
[w 21 37 01 0001 05DC] AM 1.5 kHz max. Highcut attenuation

Note: For FM different limit ranges apply for the different Highcut control characteristics as available from FM Set_Highcut_Options (cmd = 59).

Note: Suggested FM setting is 2.4 kHz limit for improved 'IIR' filter field performance.

module	32 / 33	FM / AM
cmd	56	Set_Highcut_Min mode, limit
index	1	mode [15:0] strong signal handling 0 = off; high audio frequency bandwidth is not limited (FM default) 1 = on; minimum control limit set by limit parameter (AM default)

2 limit [15:0]	Highcut fixed attenuation limit
FM	Highcut corner frequency for minimum -3 dB attenuation 10000 = 10 kHz (default)
	2700 ... 15000 [*1 Hz] = 2.7 ... 15 kHz 'IIR' filter (Options '1' (default))
	1500 ... 3183 [*1 Hz] = 1.5 ... 3.18 kHz 'deemphasis' (Options '2')
	2122 = 75 μ s deemphasis / 3183 = 50 μ s deemphasis
	2700 ... 15000 [*1 Hz] = 2.7 ... 15 kHz 'FIR' highcut filter (Options '3')
AM	2700 ... 15000 [*1 Hz] = 2.7 ... 15 kHz -3 dB att. for min. Highcut 6000 = 6 kHz (default)

Application example FM_Set_Highcut_Min (1, 1, 10000) FM 10 kHz min. Highcut attenuation
AM_Set_Highcut_Min (1, 1, 3000) AM 3 kHz min. Highcut attenuation

I²C example (hex) [w 20 38 01 0001 2710] FM 10 kHz min. Highcut attenuation
[w 21 38 01 0001 0BB8] AM 3 kHz min. Highcut attenuation

Note: In case of characteristic 'deemphasis' from FM cmd 59 Set_Highcut_Options mode = 2, the [FM cmd 31 Set_Deemphasis](#) setting is ignored and 50 μ s or 75 μ s deemphasis is defined by FM_Set_Highcut_Min parameters mode = 1, and limit instead.

module	32 / 33	FM / AM
cmd	58	Set_Lowcut_Min mode, limit
index	1	mode strong signal handling
	[15:0]	0 = off; low audio frequency bandwidth is not limited (FM default) 1 = on; minimum control limit set by limit parameter (AM default)
	2	limit Lowcut fixed attenuation limit
	[15:0]	10 ... 200 [Hz] = 10 ... 200 Hz Lowcut minimum -3 dB attenuation 20 = 20 Hz (default)

Application example FM_Set_Lowcut_Min (1, 1, 10) FM 10 Hz min. Lowcut attenuation
AM_Set_Lowcut_Min (1, 1, 30) AM 30 Hz min. Lowcut attenuation

I²C example (hex) [w 20 3A 01 0001 000A] FM 10 Hz min. Lowcut attenuation
[w 21 3A 01 0001 001E] AM 30 Hz min. Lowcut attenuation

module	32	FM	
cmd	59	Set_Highcut_Options	mode
index	1	mode	FM Highcut control characteristics
		[15:0]	1 = IIR; 'analog' first order lowpass filter with controlled frequency (default)
			2 = deemphasis; controlled frequency of the 50 / 75 µs deemphasis filter
			3 = FIR; 'digital' high order lowpass filter with controlled frequency
Application example	FM_Set_Highcut_Options (1, 2)		FM 'deemphasis' type Highcut control
I ² C example (hex)	[w 20 3B 01 0002]		FM 'deemphasis' type Highcut control

Note: Different FM Highcut control characteristics are available for selection of sound taste.

Note: In addition to the _Options selection of the Highcut filter type appropriate values should be written to FM_Set_Highcut_Min and FM_Set_Highcut_Max.

Note: In case of 'deemphasis' characteristics the FM_Set_Deemphasis setting is ignored and selection of 50 µs or 75 µs deemphasis is defined by FM_Set_Highcut_Min instead.

3.15 FM cmd 60 ... 66 Set_Stereo

Timing and quality sensitivity settings for the FM Stereo weak signal handling.

'Set_Stereo_Time' defines the weak signal handling response times active for the level detector and noise and multipath detectors. Fast and slow response times are available for dual timer functionality, with enable options at the level, noise and mph commands.'

'Set_Stereo_Level' sets the level sensitivity and enables slow and fast timing.

'Set_Stereo_Noise' and 'Set_Stereo_Mph' set the noise and multipath sensitivity and enables slow and fast timing.

'Set_Stereo_Max' allows disabling the dynamic stereo control for evaluation purposes.

'Set_Stereo_Min' optionally defines a minimum amount of Stereo attenuation (as realized for good signal conditions).

module	32	FM	
cmd	60	Set_Stereo_Time	slow_attack, slow_decay, fast_attack, fast_decay
index	1	slow_attack [15:0]	slow attack time of weak signal handling 60 ... 2000 (ms) = 60 ms ... 2 s slow attack time 1000 = 1 s (default)
	2	slow_decay [15:0]	slow decay time of weak signal handling 120 ... 12500 (ms) = 120 ms ... 12.5 s slow attack time 4000 = 4 s (default)
	3	fast_attack [15:0]	fast attack time of weak signal handling 10 ... 1200 (*0.1 ms) = 1 ms ... 120 ms fast attack time 80 = 8 ms
	4	fast_decay [15:0]	fast decay time of weak signal handling 20 ... 5000 (*0.1 ms) = 2 ms ... 500 ms fast attack time 80 = 8 ms

Application example FM_Set_Stereo_Time (1, 200, 4000, 20, 80) Slow 200 / 4000 ms, fast 2 / 8 ms

I²C example (hex) [w 20 3c 01 00c8 0fa0 0014 0050] Slow 200 / 4000 ms, fast 2 / 8 ms

Note: Suggested is 200 ms slow_attack and 2 ms fast_attack for improved field performance.

module	32	FM	
cmd	62	Set_Stereo_Level	mode, start, slope
index	1	mode [15:0]	timer selection 0 = off (only for evaluation) 1 = fast timer control 2 = slow timer control

module
cmd
index

		3 = dual timer control; combined fast and slow timer control (default)
2	start [15:0]	weak signal handling level start 300 ... 600 [$\times 0.1$ dB μ V] = control when level below 30 dB μ V ... 60 dB μ V 460 = 46 dB μ V (default)
3	slope [15:0]	weak signal handling level range 60 ... 300 [$\times 0.1$ dB] = control over level range of 6 dB ... 30 dB 240 = 24 dB (default)

32 FM

63 Set_Stereo_Noise mode, start, slope

1	mode [15:0]	timer selection 0 = off 1 = fast timer control 2 = slow timer control 3 = dual timer control; combined fast and slow timer control (default)
2	start [15:0]	FM weak signal handling noise start 0 ... 800 [$\times 0.1$ %] = control when noise above 0... 80% of USN detector 240 = 24% (default)
3	slope [15:0]	FM weak signal handling noise range 100 ... 1000 [$\times 0.1$ %] = control over range of 10... 100% of USN detector 200 = 20% (default)

Note: Suggested is 12% start and 15% slope for improved field performance.

module
cmd
index

32 FM

64 Set_Stereo_Mph mode, start, slope

1	mode [15:0]	timer selection 0 = off 1 = fast timer control 2 = slow timer control 3 = dual timer control; combined fast and slow timer control (default)
2	start [15:0]	FM weak signal handling multipath start 0 ... 800 [$\times 0.1$ %] = control when mph above 0... 80% of WAM detector 240 = 24% (default)
3	slope [15:0]	FM weak signal handling multipath range 100 ... 1000 [$\times 0.1$ %] = control over range of 10... 100% of WAM detector 200 = 20% (default)

Note: Suggested is 18% start and 15% slope for improved field performance.

module	32	FM
cmd	65	Set_Stereo_Max
index	1	mode
		[15:0]
		weak signal handling (dynamic control)
		0 = off (for evaluation only)
		1 = on; maximum dynamic control is 0 dB channel sep, i.e. mono (default)

module	32	FM
cmd	66	Set_Stereo_Min
index	1	mode
		[15:0]
		strong signal handling
		0 = off; channel separation is not limited (default)
		1 = on; minimum control limit set by limit parameter
		2 = forced mono
	2	limit
		[15:0]
		Stereo fixed attenuation limit
		60 ... 400 [0.1* dB] = 6 ... 40 dB Stereo minimum channel separation
		400 = 40 dB (default)

Application example	FM_Set_Stereo_Min (1, 1, 200)	FM 20 dB min. Stereo channel sep.
	FM_Set_Stereo_Min (1, 2, 200)	FM forced mono
I ² C example (hex)	[w 20 42 01 0001 00C8]	FM 20 dB min. Stereo channel sep.
	[w 20 42 01 0002 00C8]	FM forced mono

3.16 FM / AM cmd 80 Set_Scaler

Fine tuning of sound amplitude between FM and AM analog radio sound.

module	32 / 33	FM / AM
cmd	80	Set_Scaler
index	1	gain
		[15:0] (signed)
		-120 ... +60 [*0.1 dB] = -12 ... +6 dB analog radio signal gain
		0 = 0 dB (default)

Application example FM_Set_Scaler (1, -30) FM analog radio -3 dB gain scaling

I²C example (hex) [w 20 50 01 FFE2] FM analog radio -3 dB gain scaling

Note: For fine tuning of FM and AM digital radio sound amplitude see [3.19 FM / AM cmd 83 Set_DR_Blend](#).

3.17 FM cmd 81 Set_RDS

Available for TEA6852 and TEA6853 only.

Control of the FM Radio Data System demodulator and decoder system.

module	32	FM	
cmd	81	Set_RDS	mode, restart, interface
index	1	mode [15:0]	RDS operation control
			0 = off (RDS function disabled)
			1 = decoder mode (default); output of RDS group data (block A, B, C, D) from Get_RDS_Status/Get_RDS_Data; FM cmd = 130/131
	2	restart [15:0]	2 = demodulator mode; output of raw demodulator data from Get_RDS_Status/Get_RDS_Data; FM cmd = 130/131
			RDS decoder restart
			0 = no control
	3	interface [15:0]	1 = manual restart; start looking for new RDS signal immediately
			2 = automatic restart after tuning (default); start looking for new RDS signal after Preset, Search, Jump or Check tuning action (see FM cmd = 1)
			RDS pin signal functionality
			0 = no pin interface (default)
			2 = data-available status output; active low (GPIO feature 'DAVN')
			4 = legacy 2-wire demodulator data and clock output ('RDDA' and 'RDCL')

Application example FM_Set_RDS (1, 1, 2, 2) Enable data-available status signal pin

I²C example (hex) [w 20 51 01 0001 0002 0002] Enable data-available status signal pin

See [4.2 FM cmd 130 / 131 Get_RDS](#) for information on RDS data read.

Note: RDS 'DAVN' signal (interface = 2) can be output at any of the available GPIO pins. To receive raw demodulator data use of 'demodulator mode' is advised (mode = 2), the 2-wire output option (interface = 4) is available for legacy use only and not suggested for new designs.

For pin signals a GPIO pin assignment is required; see [3.31 APPL cmd 3 Set_GPIO](#).

3.18 FM / AM cmd 82 Set_QualityStatus

Enable and define interrupt use or status pin output for quality detector status flag.

module	32 / 33	FM / AM	
cmd	82	Set_QualityStatus mode, interface	
index	1	mode	quality status flag after tuning ready
		[15:0]	0 = no flag set after tuning (default)
			[8:0] : 10 ... 320 (* 0.1 ms) = set flag at 1 ... 32 ms after tuning ready
			[15] : 1 = set flag when FM AF_Update quality result is available
	2	interface	quality status pin signal functionality
		[15:0]	0 = no pin interface (default)
			2 = quality status output; active low ('QSI')

Application example FM_Set_QualityStatus (1, 32968, 2) Set status pin at 20 ms or AFU result

I²C example (hex) [w 20 52 01 80C8 0002] Set status pin at 20 ms or AFU result

For pin signals a GPIO pin assignment is required; see [3.31 APPL cmd 3 Set_GPIO](#).

Note: the mode parameter timer setting is rounded to 1 ms step size.

3.19 FM / AM cmd 83 Set_DR_Blend

Available for TEA6853 only.

Control of digital radio blend functionality and digital radio scaler.

module	32 / 33	FM / AM
cmd	83	Set_DR_Blend
index	1	mode [15:0]
		mode, in_time, out_time, gain
		blend pin use (DR_BL input)
		0 = Standard pin use : DR Blend pin High = digital radio (default)
		1 = Inverted pin use : DR Blend pin Low = digital radio
		2 = No pin use; Force blend to digital radio
		3 = No pin use; Force blend to analog radio
	2	in_time [15:0]
		blend time from analog radio to digital radio
		10 ... 5000 [*0.1 ms] = 1 ... 500 ms
		50 = 5 ms (default)
	3	out_time [15:0]
		blend time from digital radio to analog radio
		10 ... 5000 [*0.1 ms] = 1 ... 500 ms
		50 = 5 ms (default)
	4	gain [15:0] (signed)
		digital radio channel gain
		-180 ... +60 [*0.1 dB] = -18 ... +6 dB digital radio signal gain
		0 = 0 dB (default)

Application example FM_Set_DR_Blend (1, 2, 50, 50, -60) force 5 ms blend to digital (-6 dB)

I²C example (hex) [w 20 53 01 0002 0032 0032 FFC4] force 5 ms blend to digital (-6 dB)

Note: blend is functional only when digital radio is enabled (see [3.9 FM / AM cmd 30 Set_DigitalRadio](#)) and radio is selected as an audio input source.

3.20 FM / AM cmd 84 Set_DR_Options

For TEA6853 only.

Control of digital radio I/O functionality. Note: DR output is functional only when digital radio is enabled (see [3.9 FM / AM cmd 30 Set_DigitalRadio](#)).

module	32 / 33	FM / AM
cmd	84	Set_DR_Options samplerate, mode, format
index	1	samplerate [15:0]
		baseband digital radio sample rate (DR_I2S output)
		0 = automatic frequency selection based on tuning frequency (default)
		6500 = 650 kHz (not for normal application use)
		6750 = 675 kHz (not for normal application use)
	2	mode [15:0]
		baseband digital radio pin mode
		[15:8] = BCK and WS pin mode
		34 = standard operation, voltage output (default)
		[7:0] = Data pin(s) mode
		2 = voltage output
		4 = open drain ('pull down') (default)
	3	format [15:0]
		baseband digital radio format select
		16 = I ² S 16 bit, '3 wire' interface with single I/Q signal line (DR_I_DATA)
		(f _{DR_BCK} = 32 * sample rate)
		4112 = I ² S 16 bit, '4 wire' interface with independent I and Q signal lines
		(f _{DR_BCK} = 16 * sample rate) (default)

Application example	FM_Set_DR_Options (1, 0)	automatic DR sample rate selection
	FM_Set_DR_Options (1, 0, 8706, 16)	3-wire bus with voltage output data
I ² C example (hex)	[w 20 54 01 0000]	automatic DR sample rate selection
	[w 20 54 01 0000 2202 0010]	3-wire bus with voltage output data

Note: writing of parameters mode and format is optional

Note: Digital radio audio I/O is defined by [AUDIO cmd 22 Set_Dig_IO](#) (see [3.27](#)); signal = 32; IIS_SD_0.

Note: samplerate parameter setting changes are executed at the next tuning action.

3.21 FM / AM cmd 85 Set_Specials

For TEA6852 and TEA6853 only.

Special radio options for evaluation and extended application use.

module	32	FM	
cmd	85	Set_Specials	ana_out
index	1	ana_out [15:0]	audio output use
			0 = normal operation (default)
			1 = DAC_L : FM MPX wideband (DARC) signal / DAC_R : FM mono audio
			2 = L : digital radio left channel / R : analog radio left channel
Application example	FM_Set_Specials (1, 1) FM_Set_Specials (1, 2)		DARC/VICS output mode digital radio time alignment test
I2C example (hex)	[w 20 55 01 0001]		DARC/VICS output mode
	[w 20 55 01 0002]		digital radio time alignment test

Note: setting ana_out = 1 acts on the DAC output and is available for FM on TEA6852 and TEA6853 only. FM stereo signal remains available from the TEA6853 digital audio I2S output (IIS_SD_1).

Note: setting ana_out = 2 acts on both the DAC and the digital audio I²S output. DAC source selection or I²S output source selection override this digital radio test option.

Device version V102 note:
Setting ana_out = 2 requires an audio input selection of 'radio' and digital radio must be disabled (or the blend signal in inactive state). Digital radio gain scaling is not included.

3.22 AUDIO cmd 10 Set_Volume

Setting of audio volume.

module	48	AUDIO
cmd	10	Set_Volume
index	1	volume
		[15:0] (signed)
		audio volume
		-599 ... +240 = -60 ... +24 dB volume
		0 = 0 dB (default)

Application example	AUDIO_Set_Volume (1, -100)	Set -10 dB volume gain
I ² C example (hex)	[w 30 0A 01 FF9C]	Set -10 dB volume gain

Note: Depending on the source signal a volume setting over 0 dB may introduce signal clipping.

Note: TEA685X volume settings down to volume = -40 dB are accurate within 1 dB, lower volume shows increasing inaccuracy and step size. Setting -60 dB and lower sets mute.

3.23 AUDIO cmd 11 Set_Mute

Enable and disable of the audio mute.

module	48	AUDIO
cmd	11	Set_Mute
index	1	mode
		audio mute
		[15:0]
		0 = mute disabled
		1 = mute active (default)

Application example	AUDIO_Set_Mute (1, 0)	Disable mute, allow audio output
I ² C example (hex)	[w 30 0B 01 0000]	Disable mute, allow audio output

3.24
AUDIO cmd 12
Set_Input

Input select; selection of audio input source signal.

module	48	AUDIO	
cmd	12	Set_Input	source
index	1	source [15:0]	audio source select
			0 = radio (default)
			(analog radio or digital radio when enabled and available)
			32 = I ² S digital audio input IIS_SD_0 (TEA6853 only)
			240 = sine wave generator

Application example
AUDIO_Set_Input (1, 240)
Select sine wave generator

I²C example (hex)
[w 30 0c 01 00f0]
Select sine wave generator

3.25
AUDIO cmd 13
Set_Output_Source

Output select; selection of source signal for audio output.

module	48	AUDIO	
cmd	13	Set_Output_Source	signal, source
index	1	signal [15:0]	audio output
			33 = I ² S digital audio output IIS_SD_1 (TEA6853 only)
			128 = DAC L/R output
	2	source [15:0]	source
			4 = analog radio
			32 = I ² S digital audio input IIS_SD_0 (TEA6853 only)
			224 = audio processor (default)
			240 = sine wave generator

Application example
AUDIO_Set_Output_Source (1, 33, 04)
Select analog radio on I²S output

I²C example (hex)
[w 30 0d 01 0080 00f0]
Select analog radio on I²S output

By default both the DAC output and the IIS_SD_1 output signal are taken from the audio processor, i.e. with signal defined by AUDIO_Set_Input, _Set_Volume and _Set_Mute. Set_Output_Source allows for an alternative output signal selection, directly connecting to one of the available source signals without processing.

Note: Command Set_Output_Source requires a signal definition, i.e. include index = 1

3.26 AUDIO cmd 21 Set_Ana_Out

Definition of analog output signals.

module	48	AUDIO	
cmd	21	Set_Ana_Out	signal, mode
index	1	signal [15:0]	analog audio output 128 = DAC L/R output
	2	mode [15:0]	output mode 0 = off (power down) 1 = output enabled (default)

Application example AUDIO_Set_Ana_Out (1, 128, 0) Disable DAC output

I²C example (hex) [w 30 15 01 0080 0000] Disable DAC output

3.27 AUDIO cmd 22 Set_Dig_IO

Available for TEA6853 only.

Definition of digital input and output audio signals.

module	48	AUDIO	
cmd	22	Set_Dig_IO	signal, mode, format, operation, samplerate
index	1	signal [15:0]	digital audio input / output 32 = I ² S digital audio IIS_SD_0 (input) 33 = I ² S digital audio IIS_SD_1 (output)
	2	mode [15:0]	I/O mode 0 = off (default) 1 = input (only available for signal = 32) 2 = output (only available for signal = 33)
3	format [15:0]		digital audio format select 16 = I ² S 16 bits ($f_{IIS_BCK} = 32 * \text{samplerate}$) 32 = I ² S 32 bits ($f_{IIS_BCK} = 64 * \text{samplerate}$) (default) 272 = lsb aligned 16 bit ($f_{IIS_BCK} = 64 * \text{samplerate}$) 274 = lsb aligned 18 bit ($f_{IIS_BCK} = 64 * \text{samplerate}$) 276 = lsb aligned 20 bit ($f_{IIS_BCK} = 64 * \text{samplerate}$) 280 = lsb aligned 24 bit ($f_{IIS_BCK} = 64 * \text{samplerate}$)
4	operation [15:0]		operation mode 0 = slave mode; IIS_BCK and IIS_WS input defined by source (default) 256 = master mode; IIS_BCK and IIS_WS output defined by device
5	samplerate		audio sample rate select

[15:0]	3200 = 32.0 kHz
	4410 = 44.1 kHz (default)
	4800 = 48.0 kHz

Application example AUDIO_Set_Dig_IO (1, 33, 2, 32, 256, 4800) Dig. output 32 bit I²S, master, 48 kHz.

I²C example (hex) [w 30 16 01 0021 0002 0020 0100 12C0] Dig. output 32 bit I²S, master, 48 kHz.

Note: Command Set_Dig_IO requires a signal definition, i.e. include index = 1.

Note: A TEA685X digital audio signal always employs 16 active (msb) bits.

Note: In some cases settings of 'operation' or 'samplerate' are not independently selectable, e.g. because of shared BCK and WS pins. The control setting is based on the signal with lowest enumeration value in such a case.

Note: f_{IIS_BCK} indicates the output frequency in master mode operation and the required input frequency for slave mode operation of lsb aligned formatted output signals. Slave mode operation of input signals and I²S formatted output signals also allows for other bit clock rates of $(16 \dots 32) * 2 * \text{samplerate}$.

3.28 AUDIO cmd 23 Set_Input_Scaler

Available for TEA6853 only.

Fine tuning of sound amplitude of external sources. For each of the available external sources a separate sound amplitude correction can be programmed for use when the audio input is selected (see [3.24 AUDIO cmd 12 Set_Input](#)).

module	48	AUDIO	
cmd	23	Set_Input_Scaler	source, gain
index	1	source	audio source
	[15:0]		32 = I ² S digital audio input : IIS_SD_0
	2	gain	external source channel gain
	[15:0] (signed)		-120 ... +60 [*0.1 dB] = -12 ... +6 dB external source signal gain
			0 = 0 dB (default)

Application example AUDIO_Set_Input_Scaler (1, 32, -60) Scale I²S input 0 by -6 dB

I²C example (hex) [w 30 17 01 0020 FFC4] Scale I²S input 0 by -6 dB

Note: Command Set_Input_Scaler requires a source definition, i.e. include index = 1.

Note: Scaling of digital radio signal from IIS_SD_0 is defined by radio control [FM / AM cmd 83 Set_DR_Blend](#) (see [3.19](#)).

3.29 AUDIO cmd 24 Set_WaveGen

Definition of the internal sine wave and offset generator signal.

The wave generator can be selected as an audio source (see [3.24 AUDIO cmd 12 Set_Input](#)) and is intended for test purposes only.

module	48	AUDIO	
cmd	24	Set_WaveGen	mode, offset, amplitude1, frequency1, amplitude2, frequency2
index	1	mode [15:0]	mode 0 = wave signal off (default) 1 = wave 1 signal on Left channel 2 = wave 2 signal on Right channel 3 = wave 1 signal on Left channel and wave 2 signal on Right channel 5 = wave 1 signal on Left and Right channel 6 = wave 2 signal on Left and Right channel 7 = wave 1 + wave 2 signal on Left and Right channel
	2	offset [15:0]	DC offset -32768 ... + 32767 (* 1 LSB of 16 bit) = max negative ... max positive. 0 = no offset (default)
	3	amplitude1 [15:0] signed	wave 1 amplitude 300 ... 0 (*0.1 dB) = -30 ... 0 dB 200 = -20 dB (default)
	4	frequency1 [15:0]	wave 1 frequency 10 ... 20000 (*1 Hz) = 10 Hz ... 20 kHz 400 = 400 Hz (default)
	5	amplitude2 [15:0] signed	wave 2 amplitude -300 ... 0 (*0.1 dB) = -30 ... 0 dB 200 = -20 dB (default)
	6	frequency2 [15:0]	wave 2 frequency 10 ... 20000 (*1 Hz) = 10 Hz ... 20 kHz 1000 = 1 kHz (default)

Application example AUDIO_Set_WaveGen (1, 0, 128, -200, 1000, -200, 1000)) Set offset to +128 LSB
 AUDIO_Set_WaveGen (1, 5, 0, -100, 400, -200, 1000) Set -10 dB, 400 Hz sine

I²C example (hex) [w 30 18 01 0000 0080 FF38 03E8 FF38 03E8] Set offset to +128 LSB
 [w 30 18 01 0005 0000 FF9C 0190 FF38 03E8] Set -10 dB, 400 Hz sine

Note: The reference for amplitude is digital full scale peak to peak (FS_{PP}); i.e. 0 dB represents a maximum undistorted sine wave signal when no offset is applied.

The DC offset is available on both Left and Right channel for all mode settings.

For mode = 7 the signals of wave 1 and wave 2 are added together, for undistorted signal the combined amplitudes of wave 1 and wave 2 should not exceed 0 dB.

3.30 APPL cmd 1 Set_OperationMode

Device power control.

module	64	APPL
cmd	1	Set_OperationMode mode
index	1	mode
		device operation mode
		[15:0]
		0 = normal operation
		1 = radio standby mode (low-power mode without radio functionality) (default)

Application example APPL_Set_OperationMode (1, 1) Put device in radio standby mode

I²C example (hex) [w 40 01 01 0001] Put device in radio standby mode

Note: FM and AM commands are available during both operation modes allowing for radio initialization of both FM and AM operation during radio standby mode.

Mode = 'normal operation' will return to the radio operation as defined before standby (unless other selections were made during radio standby mode).

Alternatively a radio tuning action of Preset or Search (see [3.1 FM / AM cmd 1 Tune To](#)) will enable normal operation.

3.31 APPL cmd 3 Set_GPIO

Define general purpose and application pin use.

module	64	APPL	
cmd	3	Set_GPIO	pin, module, feature
index	1	pin	GPIO number
		[15:0]	0 ... 2 = GPIO number
	2	module	module
		[15:0]	32 = FM
			33 = AM
	3	feature	feature
		[15:0]	0 = no use (default) (FM / AM)
			1 = general purpose input (FM / AM)
			2 = general purpose output '0' (FM / AM)
			3 = general purpose output '1' (FM / AM)
			257 = output RDS (FM : see cmd 81 'DAVN')
			258 = output QSI (FM / AM : see cmd 82 'timer and AF_Update flag')
			259 = output QSI + RDS (active 'low' if 'DAVN' is active or 'QSI' is active)
			260 = output RDDA (FM : see cmd 81 'RDDA, RDCL legacy option')
			261 = output RDCL (FM : see cmd 81 'RDDA, RDCL legacy option')
			262 = output AGC (FM : see cmd 11 'AGC step extension')

Application example APPL_Set_GPIO (1, 0, 32, 257) Output 'DAVN' at GPIO 0 for FM
 APPL_Set_GPIO (1, 0, 33, 3) Output 'high' at GPIO 0 for AM

I²C example (hex) [w 40 03 01 0000 0020 0101] Output 'DAVN' at GPIO 0 for FM
 [w 40 03 01 0000 0021 0003] Output 'high' at GPIO 0 for AM

Feature settings 257 and 259 ... 261 are available for TEA6852 and TEA6853 only.

Note: Command Set_GPIO requires a GPIO number definition, i.e. include index = 1.

Note: General purpose input use is limited to GPIO 0.

Note: A module setting of FM or AM is active for the appropriate radio mode only, allowing independent feature definitions for FM and AM.

Note: Feature signals RDS, QSI and AGC are all 'active low'.

Note: Definition and enabling of assigned features is available from [FM cmd 81 Set_RDS](#) for 'RDS', 'RDDA' and 'RDCL' (see [3.17](#)), from [FM / AM cmd 82 Set_QualityStatus](#) for 'QSI' (see [3.18](#)) and from [FM / AM cmd 11 Set_RFAG](#) for 'AGC' (see [3.4](#)).

3.32 Idle state - APPL cmd 4 Set_ReferenceClock

This command is only available during 'idle state'.

Several different frequencies can be used for the crystal oscillator. For proper functioning the reference frequency must be entered before activation of the device, the command is therefore available during 'idle' state only.

module	64	APPL	
cmd	4	Set_ReferenceClock	frequency_msb, frequency_lsb, type
index	1	frequency_msb	MSB part of the reference clock frequency
		[15:0]	[31:16]
	2	frequency_lsb	LSB part of the reference clock frequency
		[15:0]	[15:0]
			frequency [*1 Hz] (default = 9216000 for TEA6853, default = 4000000 for TEA6850/51/52)
	3	type	clock type
		[15:0]	0 = crystal oscillator operation (default)
Application example	APPL_Set_ReferenceClock (1, 61, 2304)		Set crystal reference 4 MHz
	APPL_Set_ReferenceClock (1, 140, 40960)		Set crystal reference 9.216 MHz
	APPL_Set_ReferenceClock (1, 183, 6912)		Set crystal reference 12 MHz
I ² C example (hex)	[w 40 04 01 003D 0900 0000]		Set crystal reference 4 MHz
	[w 40 04 01 008C A000 0000]		Set crystal reference 9.216 MHz
	[w 40 04 01 00B7 1B00 0000]		Set crystal reference 12 MHz

TEA685X supported frequencies: 4.000 MHz, 9.216 MHz, 12.000 MHz.

Note: Supported frequencies for digital radio use (TEA6853) are 9.216 and 12.000 MHz.

3.33 Idle state - APPL cmd 5 Activate

This command is only available during 'idle state'.

After the reference clock frequency has been defined the device must be put in active state to allow for further initialization and control. After activation the device will be in operational mode 'radio standby'.

module	64	APPL	
cmd	5	Activate	mode
index	1	mode	1 = goto 'active' state with operation mode of 'radio standby'
		[15:0]	

Application example APPL_Activate (1, 1) Go from 'idle state' to 'active state'.

I²C example (hex) [W 40 05 01 0001] Go from 'idle state' to 'active state'.

Note: Setting mode = 1 is the only available setting.

4. Read commands

Read commands make certain information available for read. Reading consists of writing a module, a command and an index value (i.e. similar to a write command) followed by a read of the requested data.

The module defines the processing part that is addressed. Modules are integral functional parts of the device that can be regarded sub-devices. Modules in the TEA685X offering read data are 32 'FM' for FM radio, 33 'AM' for AM radio and 64 'APPL' for application and system information.

The command value defines the set of read data of interest.

The index value is present for future use to allow reading of certain specific data parts out of the available command read data.

Device version V102 requires index = 1 to be used.

For evaluation purposes also index = 0 is supported.

The first actual read data starts from index = 1.

For evaluation purposes reading may also start from index = 0 in which case the first data word contains a confirmation of the data following (see [5.7.1](#)).

Read commands are only available in the device 'active state' operation modes (with the exception of certain APPL read commands) and only available for enabled modules.

- idle state: valid read data from 'APPL' read of operation status, device identification and I²C write checking.
- active state = radio standby: valid read data from 'AUDIO' and 'APPL' module.
- active state = FM: valid read data from 'AM', 'AUDIO' and 'APPL'.
- active state = AM: valid read data from 'FM', 'AUDIO' and 'APPL'.

For detailed information on the I²C protocol for read commands see [5.3 Read control](#).

4.1 FM / AM cmd 128 / 129 Get_Quality

Read status of the tuner reception quality information

Get_Quality_Status will read status and possibly data with the status and any frozen data (like e.g. available after AF_Update tuning) remaining unchanged.

Get_Quality_Status is intended for status read only (i.e. status polling) but data may be sampled when desired.

Get_Quality_Data will read status and data with the status and any frozen data (like e.g. available after AF_Update tuning) released after read, allowing for new data updates.

Get_Quality_Data is intended for data reading with status informing about data content and validity.

module	32 / 33	FM / AM
cmd	128	Get_Quality_Status FM : status, level, usn, wam, offset, bandwidth, modulation
	129	Get_Quality_Data AM : status, level, -, -, offset, bandwidth, modulation
index	1	status [15:0]
		quality detector status
		[15] = AF_update flag
		0 = continuous quality data with time stamp
		1 = AF_Update sampled data
		[14:10] = reserved
		[9:0] = quality time stamp
		0 = tuning is in progress, no quality data available
		1 ... 320 (* 0.1 ms) = 0.1 ... 32 ms after tuning,
		quality data available, reliability depending on time stamp
		1000 = > 32 ms after tuning
		quality data continuously updated
	2	level [15:0] (signed)
		level detector result
		-200 ... 1200 (0.1 * dBμV) = -20 ... 120 dBμV RF input level
		actual range and accuracy is limited by noise and agc
	3	usn [15:0]
		noise detector
		FM ultrasonic noise detector
		0 ... 1000 (*0.1 %) = 0 ... 100% relative usn detector result
	4	wam [15:0]
		FM multipath detector
		FM 'wideband-AM' multipath detector
		0 ... 1000 (*0.1 %) = 0 ... 100% relative wam detector result
	5	offset [15:0] (signed)
		radio frequency offset
		-1200 ... 1200 (*0.1 kHz) = -120 kHz ... 120 kHz radio frequency error
		actual range and accuracy is limited by noise and bandwidth
	6	bandwidth [15:0]
		IF bandwidth
		FM 970 ... 3110 [*0.1 kHz] = IF bandwidth 97 ... 311 kHz; narrow ... wide
		AM 30 ... 80 [*0.1 kHz] = IF bandwidth 3 ... 8 kHz; narrow ... wide
	7	modulation [15:0]
		modulation detector
		FM 0 ... 1000 [*0.1 %] = 0 ... 100% modulation = 0 ... 75 kHz FM dev.

	1000 ... 2000 [*0.1 %] = 100% ... 200% over-modulation range (modulation results are an approximate indication of actual FM dev.)
AM	0 ... 1000 [*0.1 %] = 0 ... 100% AM modulation index 1000 ... 2000 [*0.1 %] = 100% ... 200% peak modulation range (peak modulation results vary depending on the modulation setup)

Application example	FM_Get_Quality_Status (1, (status))	Poll status
	FM_Get_Quality_Data (1, (status .. modulation))	Read status and all available data

I ² C example (hex)	[w 20 80 01 [r 0014]	Poll status (2 ms after tuning)
	[w 20 81 01 [r ???? ???? ... ????]	Read status and all available data

Note: A tuning action will reset the status information and release the frozen AF_Update sampled quality data should the AF data not have been read before.

The status quality time stamp starts updating as soon as tuning is established and new sampled data becomes available for an AF_Update tuning action (see [3.1 FM / AM cmd 1 Tune To](#) : mode = 3) and new continuous data becomes available for Preset, Search, Jump or Check tuning actions (mode = 1, 2, 4 or 5.)

4.2 FM cmd 130 / 131 Get_RDS

Available for TEA6852 and TEA6853 only.

Poll status (and data) or read status and data of the FM RDS demodulator and decoder.

Get_RDS_Status returns status (and data). The status and stored data (when complete data is available) will remain unchanged. Get_RDS_Status use is suggested for status read only (i.e. status polling) but data can be sampled when desired.

Get_RDS_Data returns status and data. The status and stored data (when complete data is available) will be released allowing data updating. Get_RDS_Data is intended for data reading including status information.

4.2.1 RDS read modes

The radio data system feature of FM RDS and RBDS data reception can operate in two distinctive modes as defined by the [FM cmd 81 Set_RDS](#) mode parameter. The mode setting defines the type of data available from the Get_RDS_Status and Get_RDS_Data commands and the timing associated with 'data-available' signaling.

Decoder mode is the default mode (mode = 1) where the received RDS data is additionally decoded and output in RDS group format as defined by the RDS standard. Error correction is executed and error detection allows for discriminating between data results judged reliable, less reliable and not reliable by the RDS error detection scheme.

The optional **demodulator mode** (mode = 2) allows for output of 'raw' RDS bit data taken directly after demodulation. The data is output in 32 bit chunks for easy read-out. Additional data processing is required in the connected µC for RDS synchronization, decoding and error handling.

In both modes RDS data is output through an internal data buffer capable of storing multiple sets of output data for relaxed requirements on read timing.

4.2.2 Read data definition for RDS decoder mode

[FM cmd 81 Set_RDS](#); mode = 1.

module	32	FM	
cmd	130	Get_RDS_Status	status, A_block, B_block, C_block, D_block, dec_error
	131	Get_RDS_Data	
index	1	status	FM RDS reception status
		[15:0]	
			[15] = data available flag
			0 = no data available (incomplete group or no first PI)
			1 = RDS group data or first PI data available
			[14] = data loss flag
			0 = no data loss
			1 = previous data was not read, replaced by newer data
			[13] = data available type
			0 = group data; continuous operation
			1 = first PI data; data with PI code following decoder sync.

	[12] = group type
	0 = type A; A-B-C-D group (with PI code in block A)
	1 = type B; A-B-C'-D group (with PI code in block A and C')
	[11:10] = reserved
	[9] = synchronization status
	0 = RDS decoder not synchronized; no RDS data found
	1 = RDS decoder synchronized; RDS data reception active
	[8:0] = reserved
2 A_block [15:0]	A block data
3 B_block [15:0]	B block data
4 C_block [15:0]	C block data
5 D_block [15:0]	D block data
6 dec_error [15:0]	error code (determined by decoder)
	[15:14] = A block error code
	[13:12] = B block error code
	[11:10] = C block error code
	[9:8] = D block error code
	0 : no error; block data was received with matching data and syndrome
	1 : small error; possible 1 bit reception error detected; data is corrected
	2 : large error; theoretical correctable error detected; data is corrected
	3 : uncorrectable error; no data correction possible
	[7:0] = reserved

Application example FM_Get_RDS_Status (1, (status)) Poll status
 FM_Get_RDS_Data (1, (status ... dec_error)) Read status and all available data

I²C example [w 20 82 01 [r 8200] Poll status (*RDS available, sync'd*)
 [w 20 83 01 [r ???? ???? ... ????] Read status and all available data

4.2.3 RDS read operation for decoder mode

The availability of RDS decoder data is signaled by the status bit 15.

If new and complete information is available this is signaled by status[15] = 1 and RDS group status and data is stored for μ C read. RDS status and data can be read from commands Get_RDS_Status and Get_RDS_Data equally but only the command Get_RDS_Data clears the information from the internal storage buffer.

Optional an interrupt ('DAVN') can be generated at the occurrence of RDS data available, see [3.17 FM cmd 81 Set_RDS](#) to enable this option (interface = 2) and [3.31 APPL cmd 3 Set_GPIO](#) for output pin selection of the data available interrupt signal. The interrupt is set and released at the same conditions as the status[15] bit.

The RDS system includes an RDS data buffer capable of storing up to 22 RDS data sets of group data allowing for a delayed read action on the data available signaling. RDS data can be read from the device using Get_RDS_Data repeatedly with the data available signal remaining active until the RDS data storage buffer is empty.

In the unlikely case that available data was not read in time causing the RDS data buffer to become full and new group data is available then the oldest data will be overwritten by new data. This loss of buffered data is indicated by the status bit 14 = 1.

Depending on the desired setup of the μ C control software three ways of operation are suggested for the reading of RDS decoder data.

1. Non synchronized operation (data polling):

Repeated Get_RDS_Data read of RDS status and data.

When status[15] = 1 then the RDS data is used, otherwise the data is ignored.

To avoid data loss a single Get_RDS_Data read should be executed at least every 87 ms. or a burst of up to 22 Get_RDS_Data reads should be executed at least every 1.90 sec. taking advantage of the RDS data buffer.

2. Status synchronized operation (status polling):

Repeated Get_RDS_Status read of status[15].

When status[15] = 1 (i.e. data available) is found perform a Get_RDS_Data read of RDS status and data.

To avoid data loss Get_RDS_Status the polling should be executed at least every 87 ms. allowing for inclusion of a single Get_RDS_Data read or at least every 1.90 sec. allowing for inclusion of up to 22 Get_RDS_Data reads taking advantage of the RDS data buffer.

3. Interrupt synchronized operation (interrupt pin):

Setting of 'DAVN' interrupt output option and GPIO pin connected to μ C.

When interrupt active is found (pin low) perform a Get_RDS_Data read of RDS status and data.

To avoid data loss a single Get_RDS_Data read should be performed within 87 ms. after interrupt or a burst of up to 22 Get_RDS_Data reads should be executed within 1.92 sec. after interrupt taking advantage of the RDS data buffer.

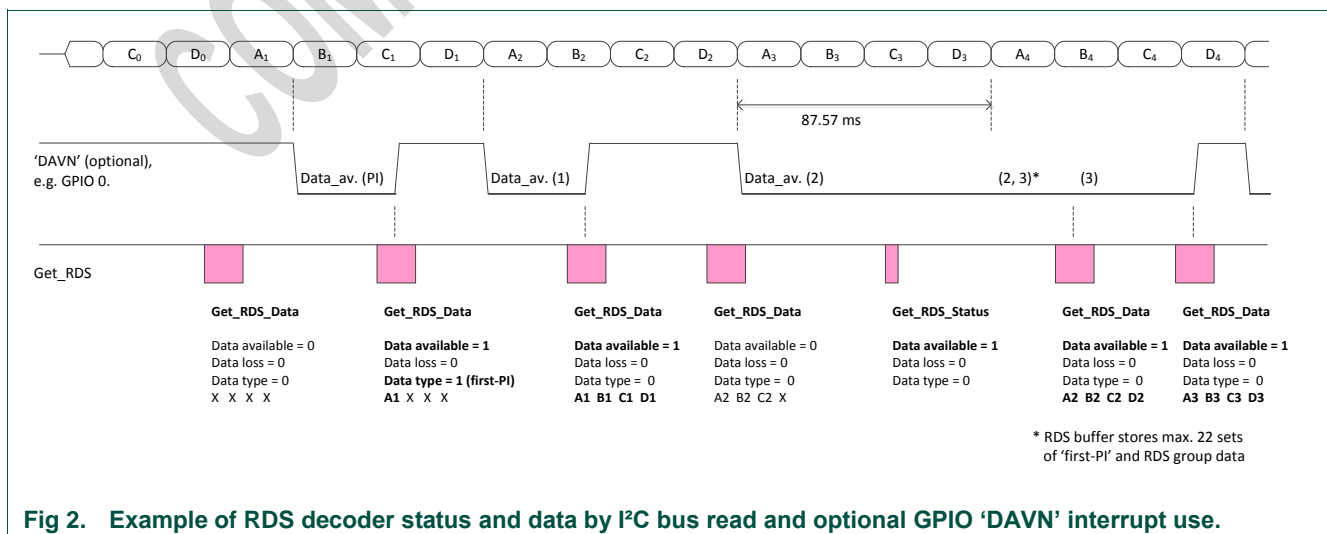


Fig 2. Example of RDS decoder status and data by I²C bus read and optional GPIO 'DAVN' interrupt use.

4.2.4 Read data definition for RDS demodulator mode

[FM cmd 81 Set_RDS](#); mode = 2.

module	32	FM	
cmd	130	Get_RDS_Status	status, raw_data_high, raw_data_low
	131	Get_RDS_Data	
index	1	status [15:0]	FM RDS reception status [15] = 0 : no data available [15] = 1 : 32 bit of raw demodulator data available [14] = 0 : no data loss [14] = 1 : previous data was not read, replaced by newer data [13 ... 0] = reserved
	2	raw_data_high [15:0]	MSB part of the 32 bit raw demodulator data ([31:16])
	3	raw_data_low [15:0]	LSB part of the 32 bit raw demodulator data ([15:0]).
Application example	FM_Get_RDS_Status (1, (status)) Poll status FM_Get_RDS_Data (1, (status, raw_data)) Read status and available data		
I ² C example	<pre>[w 20 82 01 [r 8000] Poll status (RDS raw data available) [w 20 83 01 [r ???? ???? ????] Read status and available data</pre>		

4.2.5 RDS read for demodulator mode operation

Except for the different data content and associated timings the read operation for demodulator mode equals the operation for decoder mode.

The availability of 32 bit of RDS demodulator data is signaled by the status bit.

If new and complete information is available this is signaled by status[15] = 1 and 32 bit of raw RDS data is stored for μ C read. RDS status and data can be read from commands Get_RDS_Status and Get_RDS_Data equally but only the command Get_RDS_Data clears the information from the internal storage buffer.

Optional an interrupt ('DAVN') can be generated at the occurrence of RDS data available, see [3.17 FM cmd 81 Set_RDS](#) to enable this option (interface = 2) and [3.31 APPL cmd 3 Set_GPIO](#) for output pin selection of the data available interrupt signal. The interrupt is set and released at the same conditions as the status[15] bit.

The RDS system includes an RDS data buffer capable of storing up to 50 RDS data sets of 32 bit raw data allowing for a delayed read action on the data available signaling. RDS data can be read from the device using Get_RDS_Data repeatedly with the data available signal remaining active until the RDS data storage buffer is empty.

In the unlikely case that the controlling μ C has not read the available data in time causing the RDS data buffer to become full and again 32 bits of new data are available then the

oldest data will be overwritten by the new data. This loss of buffered data is indicated by the status bit 14 = 1.

Depending on the desired setup of the μ C control software three ways of operation are suggested for the reading of RDS demodulator data.

1. Non synchronized operation (data polling):

Repeated Get_RDS_Data read of RDS status and data.

If status[15] = 1 then the RDS data is used, otherwise the data is ignored.

To avoid data loss a single Get_RDS_Data read should be executed at least every 26 ms. or a burst of up to 50 Get_RDS_Data reads should be executed at least every 1.34 sec. taking advantage of the RDS data buffer.

2. Status synchronized operation (status polling):

Repeated Get_RDS_Status read of status[15].

When status[15] = 1 (i.e. data available) is found perform a Get_RDS_Data read of RDS status and data.

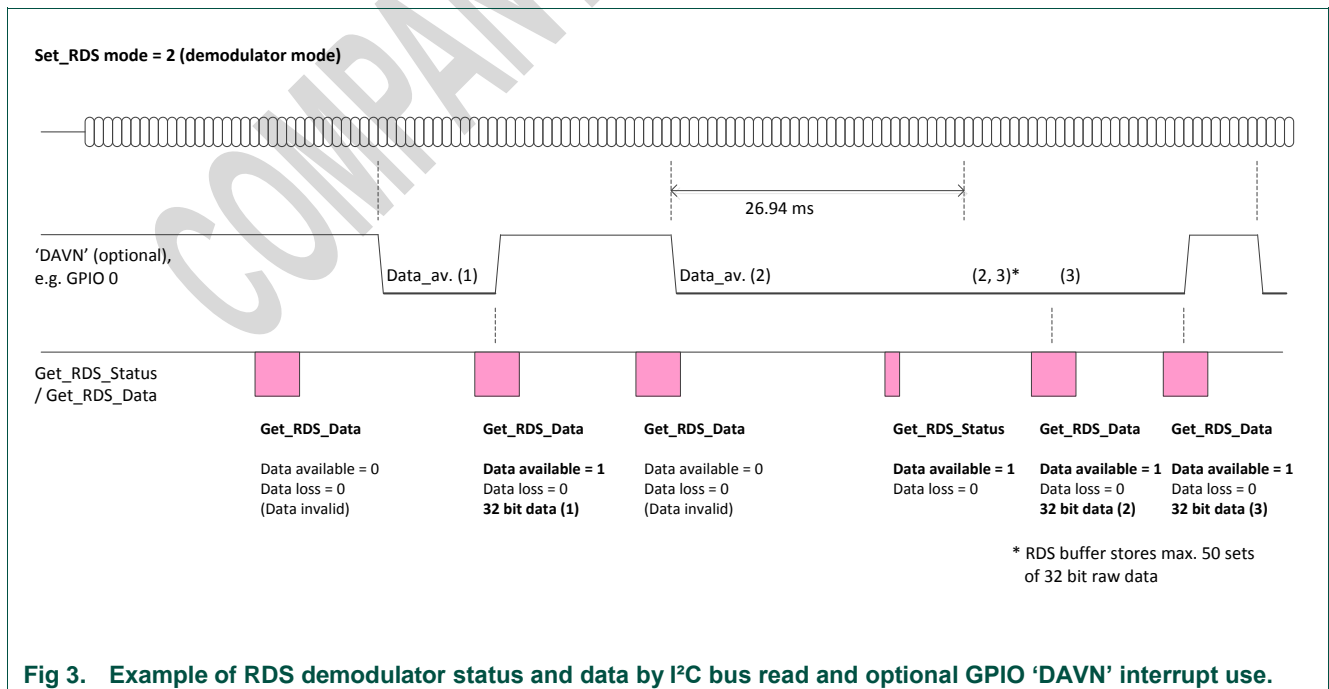
To avoid data loss Get_RDS_Status the polling should be executed at least every 26 ms. allowing for inclusion of a single Get_RDS_Data read or at least every 1.34 sec. allowing for inclusion of up to 50 Get_RDS_Data reads taking advantage of the RDS data buffer.

3. Interrupt synchronized operation (interrupt pin):

Setting of 'DAVN' interrupt output option and GPIO pin connected to μ C.

When interrupt active is found (pin low) perform a Get_RDS_Data read of RDS status and data.

To avoid data loss a single Get_RDS_Data read should be performed within 26 ms. after interrupt or a burst of up to 50 Get_RDS_Data reads should be executed within 1.34 sec. after interrupt taking advantage of the RDS data buffer.



4.3 FM / AM cmd 132 Get_AGC

Read attenuation setting of the RF AGC. The overall antenna signal attenuation is found by addition of the input_att and feedback_att value.

module	32 / 33	FM / AM
cmd	132	Get_AGC input_att, feedback_att
index	1	input_att
		[15:0]
		RF AGC input attenuation
	2	feedback_att
		[15:0]
		RF AGC feedback attenuation
		FM 0 ... 360 (0.1* dB) = 0 ... 36 dB attenuation
		AM 0 ... 420 (0.1* dB) = 0 ... 42 dB attenuation
		FM 0 ... 60 (0.1* dB) = 0 ... 6 dB attenuation
		AM 0 ... 180 (0.1* dB) = 0 ... 18 dB attenuation

Application example FM_Get_AGC (1, (input_att, feedback_att)) Read AGC attenuation settings

I²C example [w 20 84 01 [r 00B4 003C] Read AGC attenuation settings
(18 dB + 6 dB RF attenuation)

Note: The TEA685X RF AGC employs 6 dB step size, i.e. read values of 0, 60, 120...

4.4 FM / AM cmd 133 Get_Signal_Status

Read information about the received radio signal.

module	32 / 33	FM / AM
cmd	133	Get_Signal_Status status
index	1	status
		[15:0]
		Radio signal information
		[15] = 0 : mono signal
		[15] = 1 : FM stereo signal (stereo pilot detected)
		[14] = 0 : analog signal
		[14] = 1 : digital signal (blend input activated by digital processor or control) (TEA6853 only)

Application example FM_Get_Signal_Status (1, (status)) Read availability of stereo and digital

I²C example [w 20 85 01 [r 8000] Read availability of stereo and digital
(stereo signal found)

4.5 FM / AM cmd 134 Get_Processing_Status

Read information about the internal processing status (weak signal handling).
This information is intended for evaluation use only.

module	32/33	FM / AM
cmd	134	Get_Processing_Status softmute, highcut
index	1	softmute
	[15:0]	Softmute control state
		0 ... 1000 (*0.1%) = 0 % minimum ... 100 % max. softmute attenuation
	2	highcut
	[15:0]	Highcut control state
		0 ... 1000 (*0.1%) = 0 % minimum ... 100 % max. audio freq. limitation
	3	stereo
	[15:0]	FM Stereo blend control state
		0 ... 1000 (*0.1%) = 0 % minimum ... 100 % max. stereo att. (= mono)

Application example FM_Get_Processing_Status (1, (softmute, ...)) Read weak signal processing status

I²C example [w 20 86 01 [r 0000 019A 03B6] Read weak signal processing status
(softm 0%, highcut 41%, stereo 95%)

Note: 0 % equals minimum control, as defined by the weak signal ‘_Min’ setting.
100 % equals maximum control, as defined by the weak signal ‘_Max’ setting.

4.6 FM / AM cmd 135 Get_Interface_Status

Available for TEA6853 only.

Information about radio I/O functionality; DR I²S output.

module	32 / 33	FM / AM
cmd	135	Get_Interface_Status samplerate
index	1	samplerate
		Baseband digital radio sample rate (DR_I2S output)
		[15:0]
		0 = interface disabled (digital radio disabled)
		6500 = 650 kHz
		6750 = 675 kHz

Application example FM_Get_Interface_Status (1, (samplerate)) automatic DR sample rate selection

I²C example (hex) [w 20 87 01 [r 01A5] automatic DR sample rate selection (675 kHz)

4.7 APPL cmd 128 Get_Operation_Status

This read command is also available during 'boot state' and during 'idle state'.

Read information about the operation state.

module	64	APPL
cmd	128	Get_Operation_Status status
index	1	status [15:0]
		Device operation status
		0 = boot state; no command support
		1 = idle state
		2 = active state; radio standby
		3 = active state; FM
		4 = active state; AM

Application example APPL_Get_Operation_Status (1, (status)) Read operation status

I²C example [w 40 80 01 [r 0003] Read operation status
(active state FM)

Note: The value 0 indicates boot state (reset state after power-on, power dip or reference frequency disruption). Actually all get commands will return 0 values during boot state and no command support is available.

See chapter [6 Device start-up](#) on start-up device control and initialization.

4.8 APPL cmd 129 Get_GPIO_Status

Read information about the input state of designated input pins (see [3.31 APPL cmd 3 Set_GPIO](#)).

module	64	APPL
cmd	129	Get_GPIO_Status status
index	1	status [15:0]
		input state (when assigned for input use)
		[2] = input state of GPIO_2 (no input use suggested for TEA685X)
		[1] = input state of GPIO_1 (no input use suggested for TEA685X)
		[0] = input state of GPIO_0 (0 = low, 1 = high)

Application example APPL_Get_GPIO_Status (1, (status)) Read input state of GPIO input pins

I²C example [w 40 81 01 [r 0001] Read input state of GPIO input pins
(input GPIO_0 high)

Note: Because of the TEA685X designated input use of GPIO_1 and GPIO_2 during power-up only GPIO_0 is suggested for application as a general purpose input.

4.9 APPL cmd 130 Get_Identification

This read command is also available during 'idle state'.

Read information about the device type and variant.

module	64	APPL	
cmd	130	Get_Identification	device, hw_version, sw_version
index	1	device	device type and variant
		[15:0]	[15:8] type identifier
			7 = TEA685X 'Tiger-2' series
			[7:0] variant identifier
			7 = TEA6850 'Tiger-2'
			5 = TEA6851 'Tiger-2 Premium'
			4 = TEA6852 'Tiger-2 Premium RDS'
			6 = TEA6853 'Tiger-2 Digital'
	2	hw_version	hardware version
		[15:0]	[15:8] major number
			1
			[7:0] minor number
			0
	3	sw_version	firmware version
		[15:0]	[15:8] major number
			2 = '2'
			[7:0] minor number
			0 = '.00'

Application example APPL_Get_Identification (1, (device..)) Read device identification

I²C example [w 40 82 01 [r 0704 0100 0200] (TEA6853, hw 1.0, sw 2.00)

Note: The type number version designation '/V102' is derived from the major hw_version and the major sw_version number.

4.10 APPL cmd 131 Get_LastWrite

This read command is also available during 'idle state'.

Read data content of the last write transmission.

module	64	APPL
cmd	131	Get_LastWrite size/module, cmd/ index, parameter1, parameter2, parameter3, ...
index	1	size/module [15:0]
		transmission size (number of parameters) and module number [15:8] = 0 ... 6 : number of parameters of the last write transmission [7:0] = 0 ... 255 : module value of the last write transmission
	2	cmd/index [15:0]
		command byte number and index byte value [15:8] = 0 ... 255 : cmd value of the last write transmission [7:0] = 0 ... 255 : index value of the last write transmission
	3	parameter1 [15:0]
		first parameter 0 ... 65535 = value of the first parameter (when available)
	4	parameter2 [15:0]
	second parameter 0 ... 65535 = value of the second parameter (when available)	
	5	parameter3 [15:0]
		third parameter 0 ... 65535 = value of the third parameter (when available)
	6	parameter4 [15:0]
		fourth parameter 0 ... 65535 = value of the fourth parameter (when available)
	7	parameter5 [15:0]
		fifth parameter 0 ... 65535 = value of the fifth parameter (when available)

Application example `APPL_Get_LastWrite (1, (size...parameter))` Read back last write transmission

I2C example [w 40 83 01 [r 0121 1E01 0001 0000...0000] Read back last write transmission
(AM_Set_DigitalRadio = 'on')

5. I²C bus protocol

5.1 I²C protocol

TEA685X control parameters are 16 bit wide. The I²C bus native unit is the byte, multi-byte values like 16 bit parameters are transmitted MSB byte first.

With external application of a pull down resistor at GPIO_2 (10 kΩ to ground) the I²C device address for TEA685X is C8h for write and C9h for read operations. Alternatively application of a pull-up resistor (10 kΩ to Vdd) at pin GPIO_2 allows for use of device address CAh for write and CBh for read instead.

Note: GPIO_1 must be pulled low (10 kΩ to ground) during power-on to ensure proper operation.

Note: GPIO_2 must be pulled low or high (10 kΩ) during power-on and activation for a defined I²C address. Pin open is not a defined state.

5.2 Write control

Standard write transmissions to the TEA685X consist of an I²C start condition and an 8 bit hardware device address for write as depicted by the I²C standard.

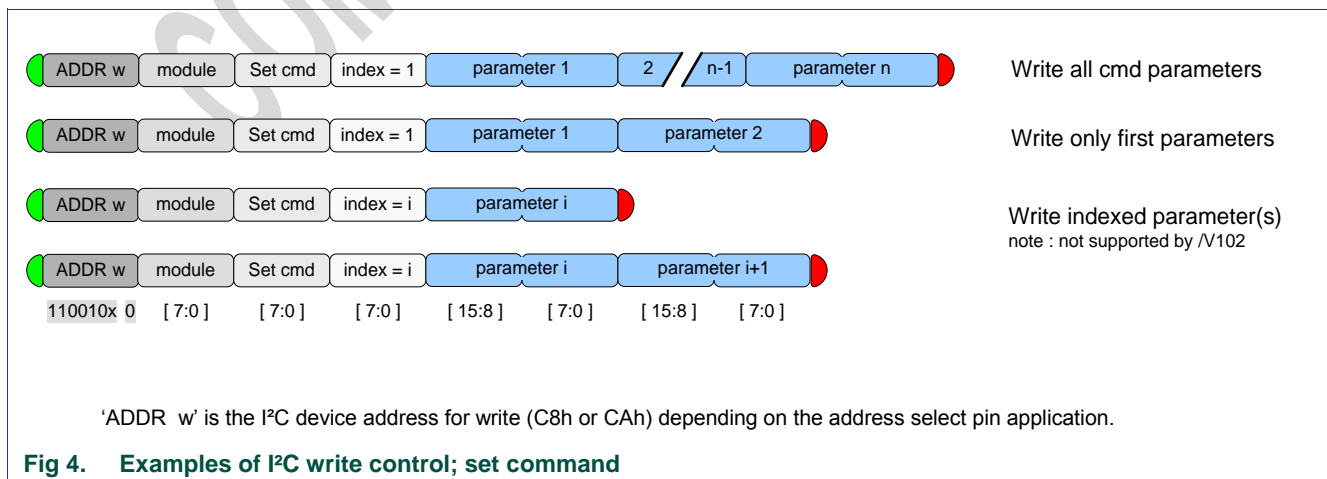
Next an 8 bit module identifier is transmitted that can be regarded as a kind of internal device address for function blocks like FM radio, AM radio, audio and system.

Control is then indicated by an 8 bit command identifier and an 8 bit parameter index allows for sub-addressing within the command parameter space, followed by one or more 16 bit parameters for actual control.

The end of transmission is indicated by an I²C standard stop condition. Because the I²C bus format includes this implicit stop condition no 'size' indication is needed as may be required by certain other bus formats.

Note: Device version V102 only supports the use of index = 1 and all parameters described in this user manual need to be transmitted.

In [Fig 4](#) examples of these transmissions are shown.



TEA685X uses only a fraction of the possible number of modules, commands and parameters. The choice for a 24 bit wide parameter address space is for future extendibility.

Writing to disabled modules is supported and will store the data for later use. Enabling of modules (where applicable) is supported by specific module commands which may imply automatic disabling of other module(s) as e.g. is the case when switching between FM and AM radio module operation.

5.3 Read control

Standard reading from the TEA685X consists of a write transmission for definition of the requested data followed by the actual read transmission for obtaining the data.

Note: this is normal practice because the I²C specification does not support read addressing within a read transmission.

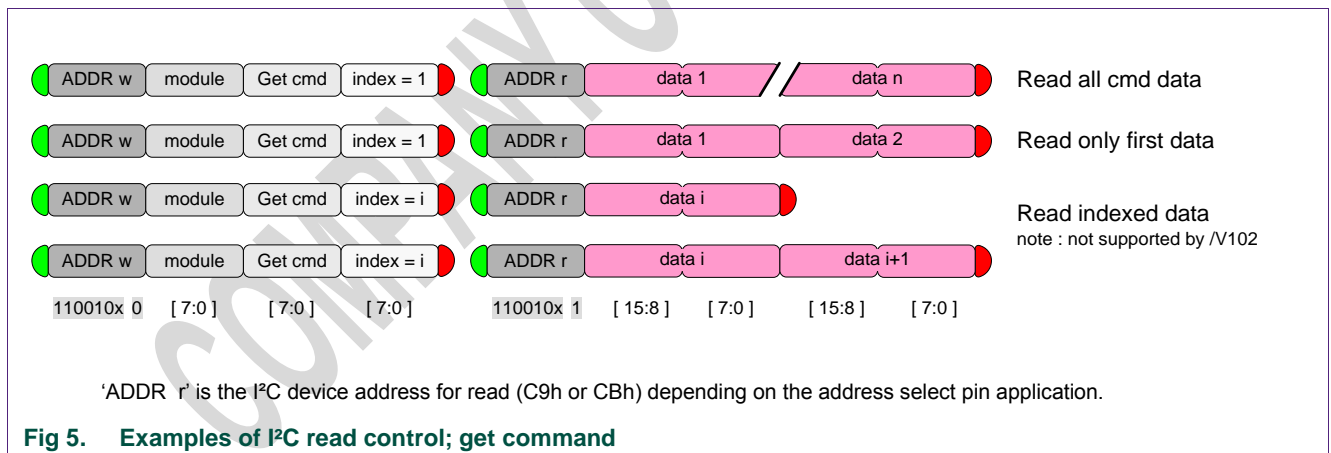
Read data is 16 bit wide (or multiples of 16 bit) transmitted with the MSB byte first.

For reading of received data or status information special 'get' commands are defined. For future extendibility and reading of data parts within larger data blocks an index setting is included similar to the write definition.

Index = 1 is the standard case with read data starting from the first data word.

Note: Device version V102 only supports the use of index = 1, it is allowed however to read less than the number of data words described in this user manual.

For evaluation purposes index = 0 is supported also (see [5.7.1](#)).



Certain timing requirements exist for TEA685X read control; see chapter [5.6](#) for details.

TEA685X 'Get' commands as published in this user manual are without parameter use. For future extensions the protocol however allows for 'Get' commands with parameters.

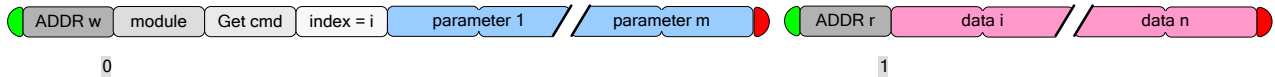


Fig 6. Example of a possible get command with parameter(s)

5.4 I²C repeated start

The I²C specification allows the joining of multiple I²C transmissions by use of I²C 'repeated start'. This way of operation ensures the set of I²C transmissions will not be interrupted by another transmission from a second microcontroller on the bus (multi-master setup).

TEA685X supports the use of I²C 'repeated start' without restriction. This means TEA685X handles I²C transmissions separated by an I²C stop and start condition in exactly the same way as I²C transmissions 'joined' by an I²C repeated start condition.

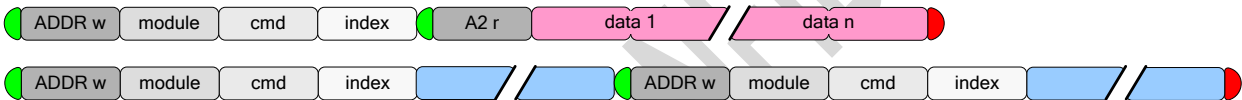


Fig 7. Examples of I²C transmissions with repeated start

5.5 Polling device presence

Checking for presence of the device on the I²C bus without any data transfer is possible by only writing of the device write address. The I²C standard acknowledge will signal device presence.



Device presence check

Fig 8. Example of testing device presence.

5.6 I²C read timing requirements

The TEA685X supports I²C clock speeds up to 400 kHz in accordance with the I²C 'fast mode' specification. TEA685X write operations require no special attention, read operations however require a minimum of 50 us time to guarantee read data setup.

The 50 us timing requirement is measured from the write transmission finish to the first read data; i.e. from the I²C 'stop' or 'repeated start' condition (= SDA edge) to the end of the device address 'acknowledge' (= falling edge of the 9th SCL clock pulse)

For 400 kHz bus operation the special control option of index = 0 offers a simple solution to meet this read timing requirement:

A setting of index = 0 will add an additional read word in front of the standard read data. This read word allows for special transmission evaluation options (see chapter [5.7 Special control](#)) but can be ignored for normal operation. For 400 kHz operation the special index 0 read word ensures a proper setup timing for the required read data of index = 1 and higher. The special index 0 word itself however must be ignored.

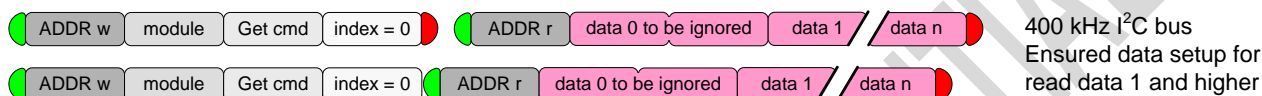


Fig 9. Example of I²C read control with guaranteed 400 kHz operation; get command index = 0

Use of index = 0 is probably the most convenient way to ensure proper read data settling for I²C fast mode bus operation.

Three alternative operation means are depicted below that may be of use, e.g. when reliable index = 0 read data is desired at high speed:

Alternative 1 : Maximum I²C bus speed limit.

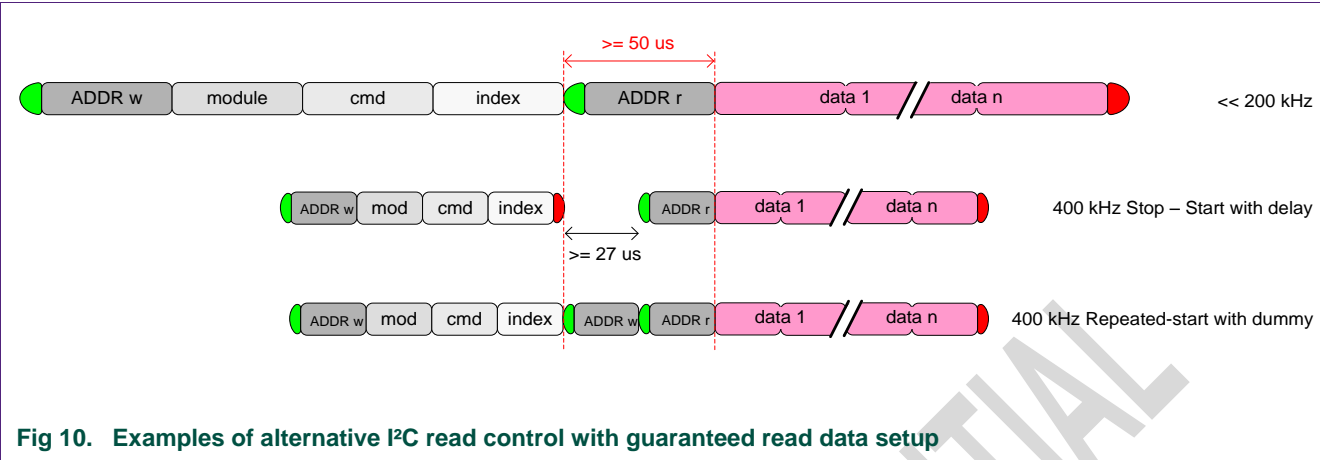
A bus speed setting of 184 kHz or lower will guarantee the required data setup time. Microcontrollers generally do not employ the 'fast mode' worst-case timing for the full device address transmission meaning a microcontroller '200 kHz' bus speed setting will ensure safe read operation in many cases.

Alternative 2 : 400 kHz I²C bus speed with microcontroller delay.

Use of separate transmissions and a timed delay of 27 us or higher between the write transmission 'stop' condition and the read transmission 'start' will guarantee the required read data setup time.

Alternative 3 : 400 kHz I²C bus speed with dual 'repeated-start'.

In case use of 'repeated-start' is desired as well as 400 kHz bus operation a 'dummy' write address transmission can be inserted between the functional write and read transmission.



5.7 Special control

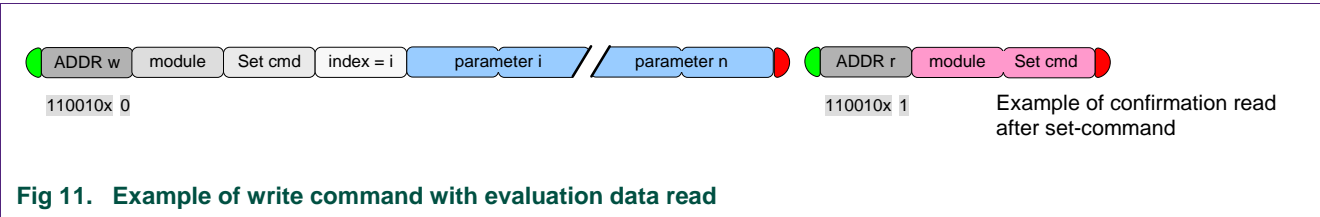
To support evaluation and debugging of the device control special control options are available.

5.7.1 Set command confirmation; special evaluation read control

For standard operation data reading is limited to status and information read data requested by a preceding 'get' command.

To this purpose TEA685X puts the requested data in its output registers after reception and evaluation of a valid 'get' command. TEA685X however also places a data word in its output registers after reception of a 'set' command, either offering confirmation of the command reception by returning the module and cmd value or delivering an error code in case of an invalid control. This data field is not intended for generic use but can be read during control software development for debugging purposes.

Condition :	Read data word :
Valid command	module / cmd
No command received	00 00h
Invalid command value	FF FFh
Invalid module value	FF FEh
Invalid index value	FF FDh (note: currently only index = 0 or 1 is permitted)
Invalid parameter value	FF FCh (note: not available in general)
Invalid state	FF FAh



5.7.2 Get command confirmation; special evaluation read control

For standard operation read command data reading is limited to application status and information data.

However similar to write commands also read commands can optionally deliver confirmation of the read command reception or an error in case of invalid control.

To this purpose use of index = 0 with a 'get' command has a special meaning where as the first data word the module and cmd value are returned or an error code in case of invalid control.

Condition :	Read data word :
Get command data available	module / cmd
No command received	00 00h
Get command data not available yet	FF F8h*
Invalid command value	FF FFh
Invalid module value	FF FEh
Invalid index value	FF FDh (currently only 0 and 1 are allowed)
Invalid state	FF FAh (command exists but not supported now)

* All TEA685X read commands show 'instant' data delivery, therefore error value FF F8h shall never be found as long as the read timing requirement of 50 us is met (see 5.6). In case of not meeting the read timing requirement also error value 00 00h may be found occasionally.

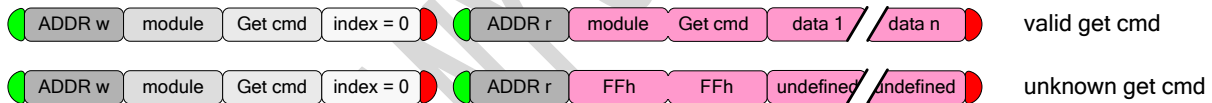


Fig 12. Examples of I²C read control with confirmation; get command index = 0

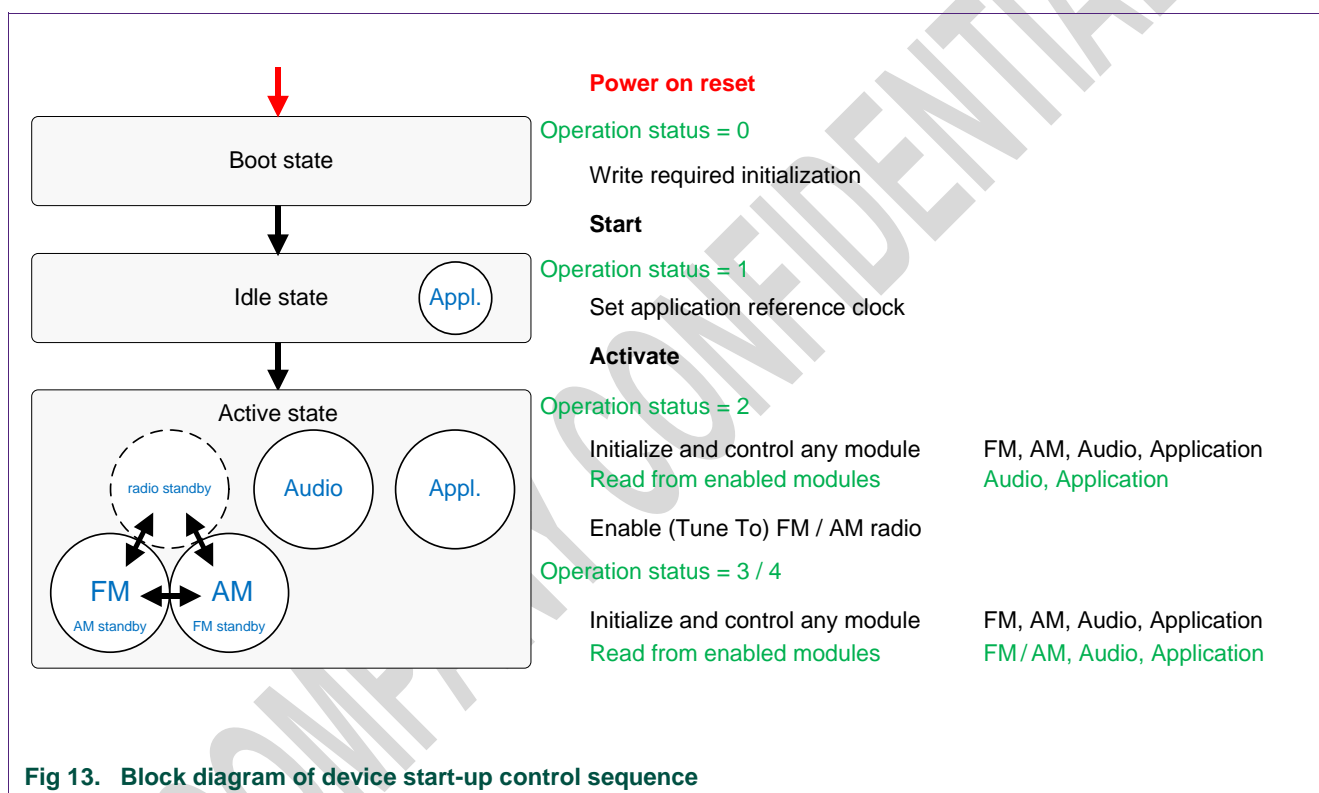
Note: The 00 00h and FF FFh ... FF F8h error codes are also returned as the first data word in case of index = 1 use but may be confused with standard expected return data.

6. Device start-up

6.1 Introduction

The TEA685X is powered by a single supply voltage. No supply power-up requirements are known to exist.

After power-on the device is found in a pre-defined reset state (boot state). A sequence of control transmissions will bring the device into idle state followed by active state to realize the desired user operation mode, function and performance.



Boot state and idle state have no function other than offering the minimum set of controls required for proper active state operation.

State transitions take a small amount of time and care should be taken to ensure a certain state is entered before any of the belonging control transmissions is started. After transmission of a 'Start' or 'Activate' state transition command it is advised to check the operation status by I²C read until the new state is found.

TEA685X state transition times will fall within the following limits:

Power-on → Boot state : power supply voltage settling + 5 ms.
(or clock active + 5 ms in case of external clock application)

Boot state → Idle state : 50 ms.

Idle state → Active state : 100 ms.

6.2 Start-up I²C control transmission sequence

- Supply power on
- Wait until device is found present on the I²C bus ('boot state') :
 - Repeat **APPL_Get_Operation_Status** read until I²C acknowledge from device; status = 0 ('boot state') is found.
`[w 40 80 01 [r 0000]`
Alternatively Wait radio supply power settling time + 5 ms.
- Send required initializations :
 - See [6.2.1 Required initialization I2C transmission – I2C example](#) and [6.2.2 Required initialization I2C transmission – C code include file](#)
- Start :
 - `[w 14 0001]`
- Wait until device is found in 'idle state' :
 - Repeat **APPL_Get_Operation_Status** read until status = 1 ('idle state') is found.
`[w 40 80 01 [r 0001]`
Alternatively Wait 50 ms.
- Set reference frequency
 - **APPL_Set_ReferenceClock** freq. = 9216000/4000000, type = 0.
`[w 40 04 01 003D 0900 0000] : 4 MHz crystal reference.`
Not required for default crystal use.
- Activate :
 - **APPL_Activate** mode = 1.
`[w 40 05 01 0001]`
- Wait until device is found in 'active state radio standby' :
 - Repeat **APPL_Get_Operation_Status** read until status = 2 ('radio standby state') is found.
`[w 40 80 01 [r 0002]`
Alternatively Wait 100 ms.
- Full API control is available from here for all modules.
 Audio and Application are on, FM and AM radio are in low-power standby.
 - Example **FM_**, **AM_**, **AUDIO_** and **APLL_** desired user settings : *module initialization.*
 - Example **AUDIO_Set_Mute** mode = 0 : *disable mute.*
`[w 30 0B 01 0000]`
 - Example **FM_Tune_To** mode = 1, frequency = 8930 : *FM radio 89.3 MHz.*
`[w 20 01 01 0001 22E2]`

6.2.1 Required initialization I²C transmission – I²C example

The following I²C transmissions (version p2.15) are a required part of the V102 boot state device initialization.

Use of these I²C transmissions is required for proper and full function and performance as described in this user manual. Version p2.15 replaces previous versions and is a critical update for AM shortwave use.

Note: The transmission example below shows a data content of 12 words for every '1B' data transmission. The data stream can be split in any desired length on (2-byte) word boundaries with every data transmission starting with hex value 1B.

```

▪ [ w 1C 0000 ]
  [ w 1C 0074 ]

▪ [ w 1B F000 382B D080 F000 3832 D080 43B2 3835 D080 F000 7000 C2F7 ]
  [ w 1B F000 3866 D080 80FC 3909 D080 F000 390E D080 F000 3911 D080 ]
  [ w 1B F000 3971 D080 F000 3928 D080 C4A2 020F 6004 9001 392A D080 ]
  [ w 1B F000 38EB D080 F000 3931 D280 F000 3935 D080 4020 3941 D080 ]
  [ w 1B 9E30 18F9 D280 F000 3943 D080 F000 3946 D080 F000 3949 D080 ]
  [ w 1B 3200 394B D080 9F9E 394D D080 A801 395E D080 F000 3973 D080 ]
  [ w 1B F000 3975 D080 F000 3977 D080 F000 398A D080 F000 398D D080 ]
  [ w 1B F000 3990 D080 F000 3993 D080 F000 7000 F000 F000 3998 D080 ]
  [ w 1B F000 396A D280 F000 39A6 D080 0043 39A9 D980 F000 39AC D080 ]
  [ w 1B F000 39C6 D080 F000 39C9 D080 F000 39DA D080 F000 39E8 D080 ]
  [ w 1B F000 0E3F 6000 5010 28D8 D280 9101 0136 6000 F000 7000 A017 ]
  [ w 1B F000 7000 A0D7 F000 7000 A0E7 F000 7000 A128 F000 7000 A14D ]
  [ w 1B F000 7000 A17E F000 2031 D080 F000 04C1 6008 F000 0101 D280 ]
  [ w 1B F000 0030 D080 007F 6002 E200 F000 0E22 600A F000 00FF 6003 ]
  [ w 1B F000 0142 D280 9003 4002 F000 9043 0170 D180 F000 0169 D080 ]
  [ w 1B 0E69 600A A1AE 2023 0001 6001 F000 7000 F000 C4CB 7000 F000 ]
  [ w 1B CA09 3023 F000 C2CB 7000 F000 F000 3023 D080 8200 0D50 6008 ]
  [ w 1B F000 0D51 6009 3000 2180 6001 F000 4032 F000 3011 45F3 F000 ]
  [ w 1B 3092 2D30 6004 3113 2D40 6005 3194 7FFF 6006 3215 0D61 600A ]
  [ w 1B 3296 0D6B 600B 3310 0D50 6001 3390 0D5C 6002 3021 0D63 6003 ]
  [ w 1B 3031 0D75 600C 30A2 8D00 6001 30B3 0173 6002 3041 0025 6003 ]
  [ w 1B 30C2 4044 F000 3143 4035 F000 31C4 6400 6006 3245 1F40 6007 ]
  [ w 1B 32C6 7000 F000 3347 1EBC 600D 33C0 0122 6001 3440 FDEE 6002 ]
  [ w 1B 3051 7B8F 6003 30D2 C429 6004 3151 1EC2 600E 3253 FF0D 6002 ]
  [ w 1B 32D4 7D2E 6003 3061 C19A 6004 30E2 7000 F000 3161 7000 F000 ]
  [ w 1B 3263 7000 F000 32E4 7000 D008 F000 0370 D280 F000 7000 A002 ]
  [ w 1B F000 7000 A059 F000 0215 D080 F000 0D51 600F F000 0517 600E ]
  [ w 1B 23F6 7000 F000 F000 2163 41F5 918F 21F8 4074 C3EF 21E0 F000 ]
  [ w 1B C3A4 33F7 F000 D85B 7000 F000 8218 7000 F000 9FAF 1800 F000 ]
  [ w 1B 9F0F 31F8 9002 F000 7000 9028 F000 7000 D008 F000 2278 F000 ]
  [ w 1B 16D3 6009 A07F 35F0 1EBC 600D F000 0D61 6008 F000 03A5 D280 ]
  [ w 1B F000 1EC2 600D F000 0D6B 6008 F000 03A5 D280 F000 2100 F000 ]
  [ w 1B 836D 22F1 F000 F000 2377 F000 9041 3670 F000 9E79 7000 9001 ]
  [ w 1B F000 32F1 D008 91C7 3375 F000 F000 3470 E600 F000 34F0 E600 ]
  [ w 1B F000 2474 F000 F000 24F3 F000 8C24 26F2 4016 8A1B 3474 4FF5 ]
  [ w 1B 82B7 34F3 F000 F000 2071 9005 8304 7000 F000 8E67 7000 F000 ]
  [ w 1B F000 7000 9002 F000 36F6 F000 F000 34F0 8006 82AF 7000 F000 ]
  [ w 1B 821B 7000 D009 8E5F 7000 F000 F000 7000 D009 F000 36F5 F000 ]
  [ w 1B F000 3470 F000 4011 2772 A151 908A 20F3 A150 8ED7 3772 F000 ]
  [ w 1B F000 37F1 E600 F000 7000 D008 F000 227A F000 16C3 6009 A058 ]
  [ w 1B F000 1820 F000 F000 3570 F000 F000 327A D008 8200 0D51 6008 ]
  [ w 1B 4003 7000 F000 3380 7000 F000 2106 7000 F000 3700 7000 F000 ]
  [ w 1B 3780 4015 F000 3683 7000 F000 3305 0D61 6009 3286 0D6B 600A ]
  [ w 1B 3210 7000 F000 3290 7000 F000 3310 7000 F000 3390 7000 F000 ]
  [ w 1B 3410 7000 F000 3490 7000 F000 3110 7000 F000 3190 7000 F000 ]
  [ w 1B 3220 7000 F000 32A0 7000 F000 3320 7000 F000 33A0 7000 F000 ]
  [ w 1B 3420 7000 F000 34A0 7000 F000 3120 7000 F000 31A0 7000 F000 ]
  [ w 1B 8200 0D30 600A 0D40 600B C010 F000 1020 F000 0D51 600C C010 ]
  [ w 1B F000 1030 F000 F000 35C0 D008 F000 0D75 600F F000 0563 600E ]
  [ w 1B 24F7 051D 600D 2576 7000 F000 91C7 20E8 4015 918F 21E9 D409 ]
  [ w 1B C3EF 2000 4012 9FBE 2011 5803 A080 3577 9001 F000 7000 D008 ]

```

```

[ w 1B F000 21F5 F000 A0CA 2254 F000 CC09 0517 600C 832C 7000 F000 ]
[ w 1B 8A61 7000 F000 AE48 2245 A119 A228 2078 F000 F000 35F0 F000 ]
[ w 1B F000 1800 F000 F000 3078 F000 16E3 6009 A027 8901 23F4 F000 ]
[ w 1B F000 20F2 F000 8261 2173 F000 A050 3670 F000 A058 2372 E140 ]
[ w 1B A801 22F3 F000 9049 2275 E040 8061 7000 F000 8A51 33F1 F000 ]
[ w 1B A058 7000 F000 AF48 7000 F000 F000 3470 D008 8200 0D75 6008 ]
[ w 1B 9009 0D00 6009 F000 3500 F000 F000 3380 C028 F000 1010 F000 ]
[ w 1B F000 3481 D008 8249 0D75 6008 F000 7000 8FFD 0400 6000 A0FF ]
[ w 1B 8EC0 4000 6005 6000 6005 E600 C81B 7000 F000 D8DB 0D51 6008 ]
[ w 1B 835B 7000 F000 9EBA 3003 F000 F000 3084 D409 F000 7000 8FAF ]
[ w 1B F000 0D75 6008 F000 0D51 6009 F000 2403 F000 F000 2794 D008 ]
[ w 1B A003 7000 F000 0011 0800 F000 0011 0800 C00E A009 0011 0800 ]
[ w 1B A009 7000 F000 A408 7000 D008 A003 7000 F000 0011 0800 F000 ]
[ w 1B 0011 0800 C026 A009 0011 0800 A009 7000 F000 A408 7000 D008 ]
[ w 1B F000 1D01 6008 F000 0A2C 6000 F000 011A 6001 3100 7000 F000 ]
[ w 1B 3181 7000 D008 A801 7FFF 6006 CC0A 7000 F000 8EA1 3106 F000 ]
[ w 1B F000 3206 D409 AEE8 04DF D080 1000 6003 A0DC 3023 0773 D280 ]
[ w 1B F000 07C6 D080 0800 6003 A002 0E6F 6009 F000 0200 6003 8000 ]
[ w 1B F000 0773 D080 40E0 001F 6001 13D5 6007 A006 13FB 6006 F000 ]
[ w 1B 9040 0D28 D280 1405 6006 F000 F000 0D28 D280 140F 6006 F000 ]
[ w 1B F000 0D28 D080 D7CA 00FF 6004 81D7 0CF7 6009 D056 7000 F000 ]
[ w 1B 8276 3017 F000 D0F6 4083 F000 C1A4 2019 F000 82F6 7000 F000 ]
[ w 1B C180 2017 A0C6 C3E7 7000 F000 C5C7 7000 F000 F000 3017 D008 ]
[ w 1B F000 7000 A079 F000 7000 8043 1EC8 6008 A0C0 F000 2000 A0BF ]
[ w 1B 9000 7000 F000 F000 7000 D409 F000 7000 8FC5 1EC8 6008 A0BB ]
[ w 1B F000 3000 D008 0028 6000 A0B9 9E38 0BF4 6009 9E38 7000 9FFF ]
[ w 1B F000 7000 D008 4040 0C8A D580 F000 0C8B D280 F000 0FB1 D280 ]
[ w 1B 9C39 7000 F000 9C31 7000 9004 F000 7000 9003 4010 7000 AFF3 ]
[ w 1B 41F1 4040 F000 F000 10B1 D080 4000 7000 AFF0 41F1 4040 F000 ]
[ w 1B F000 10B2 D080 4071 10B2 D280 F000 1081 D080 F000 0BC9 6008 ]
[ w 1B F000 1D8D D280 F000 16D5 D080 F000 0BC9 6008 F000 1D8F D280 ]
[ w 1B F000 16DA D080 3E91 1F5F D280 F000 238A D080 0D82 6008 A09F ]
[ w 1B F000 3000 D008 0F88 600B 9407 9046 0D82 600A 2EB2 1B93 D280 ]
[ w 1B F000 2025 F000 DAC9 7000 F000 8C69 7000 F000 DD49 3201 F000 ]
[ w 1B 8D89 7000 8001 8C69 7000 F000 F000 1B7F D080 F000 0B60 600E ]
[ w 1B F000 0004 6003 40A7 3FFC 6004 3263 8008 6005 32E4 199A 6006 ]
[ w 1B 3365 0D83 600F 31E6 7000 F000 3077 7000 D008 80E5 7FFF 6000 ]
[ w 1B CC0A 7000 F000 8EA9 3370 F000 AF20 3470 D409 AEE8 7000 F000 ]
[ w 1B A805 0080 6007 A8F6 3375 F000 C386 7000 F000 8F7F 33F6 F000 ]
[ w 1B A885 1DE4 D180 F000 3475 D008 0D83 6009 A080 2012 1F32 D280 ]
[ w 1B F000 3582 D008 9082 0D83 6009 40A7 4077 E640 F000 7000 F000 ]
[ w 1B F000 3017 D008 0BB4 6008 A079 F000 3182 D008 00CF 6000 A005 ]
[ w 1B 4011 0C14 D080 00CF 6000 A003 F000 2022 D080 0151 6000 A001 ]
[ w 1B F000 201E D080 F000 0E69 6008 F000 01D0 6001 F000 3080 F000 ]
[ w 1B F000 3001 D008 836D 0C35 6008 4060 3988 6001 41E2 2196 6003 ]
[ w 1B 3300 4144 F000 3381 7000 F000 3402 7000 F000 3483 0C29 6009 ]
[ w 1B 3504 3996 6000 3585 399B 6003 3090 7000 F000 3393 7000 D008 ]
[ w 1B F000 7000 AF1A F000 7000 8F5F F000 7000 AF58 F000 0C51 D280 ]
[ w 1B F000 21A0 D080 F000 052E D280 F000 7000 A00E F000 21B7 D080 ]
[ w 1B F000 1F32 D280 F000 1E84 D280 F000 21E0 D080 F000 1EA4 D280 ]
[ w 1B F000 07F7 D280 F000 2215 D080 F000 07FB D280 F000 228F D080 ]
[ w 1B 4040 22E1 D280 4080 22E2 D280 F000 229C D080 F000 07FB D280 ]
[ w 1B F000 22B6 D080 F000 20F0 D280 9002 27DF D280 9E69 7000 F000 ]
[ w 1B F000 0700 D180 F000 2320 D080 9082 0C29 6009 4017 4067 E640 ]
[ w 1B F000 7000 F000 F000 3217 D008 F000 07F7 D280 F000 27EA D280 ]
[ w 1B F000 11B5 D080 170B 600C A041 0040 4005 F000 0041 243F D080 ]
[ w 1B F000 7000 AE8F F000 0C8D 6008 F000 260A D080 83FF 0D85 6008 ]
[ w 1B F000 01F4 6000 F000 03B1 6001 1000 03B2 6002 1001 040E 6000 ]
[ w 1B 1002 040F 6001 1000 045C 6002 1001 045D 6000 1002 1380 6001 ]
[ w 1B 1000 0D90 6009 1001 02EE 6000 1007 4306 6001 1010 0469 6002 ]
[ w 1B 1011 4487 6000 1012 05E3 6001 1010 4608 6002 1011 06AE 6000 ]
[ w 1B 1012 0D8E 6008 1010 9E3C 6000 1017 0D84 6009 1000 7000 F000 ]
[ w 1B 1007 7000 F000 1017 7000 D008 0CDF 600B A024 3030 23D6 D280 ]
[ w 1B F000 26E8 D080 0D85 6008 A021 F000 0002 A020 9082 7000 F000 ]
[ w 1B 828A 7000 9003 908A 7000 9001 F000 7000 8FFB 82BF 7000 F000 ]
[ w 1B F000 0199 D280 F000 0D84 6008 F000 26C1 F000 F000 0002 A017 ]
[ w 1B 9082 7000 F000 828A 7000 9003 908A 7000 9001 F000 7000 8FFB ]
[ w 1B 8280 7000 F000 F000 7000 D008 F000 0D90 600D F000 3FFF 6002 ]
[ w 1B F000 0051 A00E C253 7000 F000 8EC4 7000 9001 F000 7000 97FC ]
[ w 1B D48F 0199 D280 4005 0D8E 600D 4017 3FFF 6002 9F7D 0051 A007 ]
[ w 1B C253 7000 F000 82C4 271C D180 F000 7000 97FC 9146 2720 D080 ]

```

```
[ w 1B F000 2915 D280 F000 39EC D280 F000 2888 D080 F000 7000 D008 ]
[ w 1B F000 16C3 6008 F000 009A 6000 F000 02E3 6000 1000 04F4 6000 ]
[ w 1B 1000 06FF 6000 1000 0907 6000 1000 0B10 6000 1000 0D1F 6000 ]
[ w 1B 1000 0F65 6000 1000 0F65 6000 1000 0D1F 6000 1000 0B10 6000 ]
[ w 1B 1000 0907 6000 1000 06FF 6000 1000 04F4 6000 1000 02E3 6000 ]
[ w 1B 1000 009A 6000 F000 1000 F000 F000 1000 F000 F000 16D3 6008 ]
[ w 1B F000 FF93 6000 F000 FE37 6000 1000 FDD9 6000 1000 FE9F 6000 ]
[ w 1B 1000 0385 6000 1000 0D6B 6000 1000 1684 6000 1000 1E49 6000 ]
[ w 1B 1000 1E49 6000 1000 1684 6000 1000 0D6B 6000 1000 0385 6000 ]
[ w 1B 1000 FE9F 6000 1000 FDD9 6000 1000 FE37 6000 1000 FF93 6000 ]
[ w 1B F000 1000 F000 F000 1000 F000 F000 16E3 6008 F000 0064 6000 ]
[ w 1B F000 FFA8 6000 1000 FFA6 6000 1000 FFDF 6000 1000 0001 6000 ]
[ w 1B 1000 0128 6000 1000 012F 6000 1000 FD23 6000 1000 FDA1 6000 ]
[ w 1B 1000 0389 6000 1000 0254 6000 1000 FE7D 6000 1000 008C 6000 ]
[ w 1B 1000 FBE1 6000 1000 F942 6000 1000 0C47 6000 1000 0EA2 6000 ]
[ w 1B 1000 EC43 6000 1000 EACE 6000 1000 1746 6000 1000 1746 6000 ]
[ w 1B 1000 EACE 6000 1000 EC43 6000 1000 0EA2 6000 1000 0C47 6000 ]
[ w 1B 1000 F942 6000 1000 FBE1 6000 1000 008C 6000 1000 FE7D 6000 ]
[ w 1B 1000 0254 6000 1000 0389 6000 1000 FDA1 6000 1000 FD23 6000 ]
[ w 1B 1000 012F 6000 1000 0128 6000 1000 0001 6000 1000 FFDF 6000 ]
[ w 1B 1000 FFA6 6000 1000 FFA8 6000 1000 0064 6000 F000 1000 F000 ]
[ w 1B F000 1000 F000 F000 170B 6008 F000 0003 6000 F000 54C0 6000 ]
[ w 1B 1000 0005 6000 1000 0005 6000 1000 000F 6000 1000 000F 6000 ]
[ w 1B 1000 09C0 6000 1000 0A20 6000 1000 1D40 6000 1000 1E60 6000 ]
[ w 1B F000 1000 F000 F000 1000 F000 F000 7000 D008 ]

[ w 1C 0000 ]
[ w 1C 0075 ]

[ w 1B 4013 402F 4168 41C1 4214 44DE 47C5 47FC 4E56 4E58 4D83 4E49 ]
[ w 1B 4E53 4F92 4FEA 5080 5660 56D4 56D9 59B4 5A3A 5B7E 5DDC 6067 ]
[ w 1B 6088 60A8 619F 61B6 61DF 6214 6259 629B 62A1 6369 643B 6609 ]
[ w 1B 66E7 670B 671A 6887 6899 68A7 68B2 ]

[ w 1C 0000 ]
```

The following data sets (p2.15) are a required part of boot state device initialization.

The C code in this chapter can be included in C program code of a host μ C and be compiled on the same date as the μ 2C assembler code of chapter 8.8.1.

describes the same data as the T C script example of chapter [6.2.1](#).

found as part of the PC GUI control program installation ([/documentation/PATCH.c](#))

found as part of the FC GUI control program installation (.../documentation/FATCH.C).

```

* Creation date:      2014 04 15 14:27:38
* Version:           2.00 - p2.15
*
* Usage:
*   * Compile and link this C-file and declare in the source-file for required initialization transmissions the following:
*
* extern const size_t LutSize;
* extern const unsigned char * pLutBytes;
*
* extern const size_t PatchSize;
* extern const unsigned char * pPatchBytes;
*
*
* The source for required initialization transmissions should create the following set of ITC transmissions:
*
* [ w 1C 0000 ]      script example: S C8 1C 00 00 P
* [ w 1C 0074 ]      script example: S C8 1C 00 74 P
* [ w 1B <pPatchBytes> ] script example: S C8 1B F0 00 .... P
*
* PatchSize of pPatchBytes can be divided (on a 2 byte boundary) in separate transmissions all starting with command Identifier 0x1B.
* [ w 1C 0000 ]      script example: S C8 1C 00 00 P
* [ w 1C 0075 ]      script example: S C8 1C 00 75 P
* [ w 1B <pLutBytes> ] script example: S C8 1B 40 13 .... P
*
* LutSize of pLutBytes can be divided (on a 2 byte boundary) in separate transmissions all starting with command Identifier 0x1B.
* [ w 1C 0000 ]      script example: S C8 1C 00 00 P
*
*/

```

doc All information provided in this document is subject to legal disclaimers. © NXP B.V. 2014. All rights reserved.

6.2.3 Required initialization I²C transmission – version p2.15

Initialization version p2.15 is a required part of the V102 device startup.

Initialization version p2.15 offers the following updates over earlier releases:

Fix

- AM Shortwave use: resolved failing reception after switching from FM 94.1 MHz to AM Shortwave band

Performance

- FM multipath suppression and AFU, Jump tuning: resolved audio amplitude disturbance after Jump / AFU tuning from high to low signal condition

Initialization version p2.15 includes all the advantages offered from earlier versions:

Fix

- p2.14: Radio tuning robustness, resolving issue of wrong quality read and muted audio after > 65000 tunings with less than 32 ms between tuning actions
- p2.14: Erroneous level result in high signal conditions (in certain cases depending on RF AGC threshold, level step correction and level offset settings)
- p2.14: Resolved potential issue of boot state robustness
- p2.13: Tuning action sequence FM Check – FM Preset and FM Check – FM Search; resolved issue of frozen weak signal handling
- p2.13: Tuning action sequence FM Check – FM Jump – ... – FM Check; proper weak signal handling start at closing of FM Check (by Jump, AFU or End action)
- p2.12: Resolved critical issue of muted FM radio after temperature change
- p2.12: Resolved critical issue on variant read
- p2.12: Resolved issue concerning AM noise blanker false triggering on specific condition of 30 kHz adjacent signal with HD radio digital modulation
- p2.12: Improved digital radio large signal handling

Performance

- p2.13: Optimized digital radio large signal handling timing and adapted threshold
- p2.10: Reduction of potential whistle in the AM SW band at the crystal frequency
- p2.10: Improved digital radio high level signal response and fast settling at tuning
- p2.09: Avoidance of potential whistle at 77.40 MHz

6.3 Operation state description

6.3.1 Boot state

After power-on the device is found in 'boot state', controlled by the integrated power-on-reset detection.

Parallel to the supply power detection a clock signal detector is present which ensures boot state is entered only when a clock signal is present in order to safeguard the external clock application case.

In case of a harmful disruption of the power supply voltage (power dip) or reference clock signal the present operation state will be reset and boot state will be available after power supply voltage and reference signal are re-established.

In boot state the device functionality is reduced to the bare minimum defined by hardware only.

Required additions to the built-in firmware can be loaded up from the host μ C to the internal RAM of the device.

'Boot state' is identified by

- The I²C bus is active; I²C transmissions are acknowledged by the device.
(Note: the I²C device address has been determined during power-on).
- The device is in full power-down.
- GPIO and digital output pins are 'open'.
- No API commands are available; only hardware support.
API commands are ignored and do not harm the boot state operation.
- Reading APPL_Get_Operation_Status returns 'boot state' (0).
Note: This API read operation is defined by the fact that any API read will return '0' here.
This property can be used by the radio system μ C to detect an unforeseen power dip occurrence or unforeseen disruption of the (external) clock reference signal.
- The device can receive certain dedicated hardware commands and data;
Device version V102 requires an initialization at this point for function and performance.
- Command 'Start' will bring the device into 'idle state'.
Note: The 'Start' command is made up of I²C data byte values "14h 00h 01h".
In API definition style this equals a transmission of module = 20, cmd = 0, index = 1 and no parameters.

6.3.2 Idle state

Changing 'boot state' to 'idle state' takes a time of less than 50 ms.

Presence of 'idle state' can be verified by APPL_Get_Operation_Status returning 'idle state' (status = 1).

In 'idle state' very limited control functionality is available, only specific API commands required for system definition are available here.

'Idle state' is identified by

- The I²C bus is active; I²C transmissions are acknowledged by the device.

- The device is in power-down.
- GPIO and digital output pins are 'open'.
- Reading APPL_Get_Operation_Status will return 'idle state' (1).
- The device can receive certain API commands for application definition purposes (APPL_Set_ReferenceClock).
- The device can return certain API status information (APPL_Get_Identification, APPL_Get_Last_Write).
- Command APPL_Activate will bring the device into 'active state' = radio standby.

6.3.3 Active state

Changing 'idle state' to 'active state' takes a time of less than 100 ms.

Presence of 'active state' can be verified by APPL_Get_Operation_Status returning the radio standby 'active state' (2).

On first activation pin states do not change and the device enters the reduced power state of 'radio standby'.

The full set of API commands is available now allowing initialization of the different modules including the disabled modules of 'FM' and 'AM'. The operation mode can be completed now by enabling either FM or AM radio operation and releasing the audio mute.

'Active state' is identified by

- The I²C bus is active; I²C transmissions are acknowledged by the device.
- The device is in operation (initial operation mode is 'radio standby')
- At initial 'radio standby' operation the DR and GPIO pins are 'open'.
- In FM / AM operation the DR and GPIO pins are in their selected FM / AM state (and default state 'open' when not initialized).
- In 'radio standby' operation, after FM or AM, the DR pins remain in their previous radio state (with invalid data) and GPIO radio features are disconnected (i.e. GPIO pins are 'open').
- Reading APPL_Get_Operation_Status will return one of the 'active' states; radio standby (2), FM (3) or AM (4).
- The device can handle API commands for all modules for additional initialization and control including disabled modules like FM and/or AM.
- API get commands result in valid read data for enabled modules only.

7. Overview of available commands

Table 1. Command overview - write

	Module	Cmd	1	2	3	4
3.1	FM/AM	1	Tune_To	mode	frequency [kHz]	
3.2	FM	2	Set_Tune_Options	afu_bw_mode	afu_bandw [kHz]	mute_time [ms] sample_time [ms]
3.3	FM/AM	10	Set_Bandwidth	mode	bandwidth [kHz]	sensitivity [%] lo_sensitivity [%]
3.4	FM/AM	11	Set_RFAGC	start [dBuV]	extension	
3.5	AM	12	Set_Antenna	attenuation [dB]		
3.6	FM	20	Set_MphSuppression	mode		
3.7	FM/AM	23	Set_NoiseBlanker	mode	sensitivity [%]	
3.8	AM	24	Set_NoiseBlanker_Audio	mode	sensitivity [%]	
3.9	FM/AM	30	Set_DigitalRadio	mode		
3.10	FM	31	Set_Deemphasis	timeconstant [us]		
3.11	FM/AM	38	Set_LevelStep	step1 [dB]	step2 [dB]	step3 [dB] step4 [dB]
			step5 [dB]	step6 [dB]	step7 [dB]	
3.12	FM/AM	39	Set_LevelOffset	offset [dB]		
3.13	FM/AM	40	Set_SoftMute_Time	slow_attack [ms]	slow_decay [ms]	fast_attack [ms] fast_decay [ms]
	FM/AM	42	Set_SoftMute_Level	mode	start [dBuV]	slope [dB]
	FM	43	Set_SoftMute_Noise	mode	start [%]	slope [%]
	FM	44	Set_SoftMute_Mph	mode	start [%]	slope [%]
	FM/AM	45	Set_SoftMute_Max	mode	limit [dB]	
3.14	FM/AM	50	Set_HighCut_Time	slow_attack [ms]	slow_decay [ms]	fast_attack [ms] fast_decay [ms]
	FM/AM	52	Set_HighCut_Level	mode	start [dBuV]	slope [dB]
	FM	53	Set_HighCut_Noise	mode	start [%]	slope [%]
	FM	54	Set_HighCut_Mph	mode	start [%]	slope [%]
	FM/AM	55	Set_HighCut_Max	mode	limit [Hz]	
	FM/AM	56	Set_HighCut_Min	mode	limit [Hz]	
	FM/AM	58	Set_LowCut_Min	mode	limit [Hz]	
	FM/AM	59	Set_HighCut_Options	mode		
3.15	FM	60	Set_Stereo_Time	slow_attack [ms]	slow_decay [ms]	fast_attack [ms] fast_decay [ms]
	FM	62	Set_Stereo_Level	mode	start [dBuV]	slope [dB]
	FM	63	Set_Stereo_Noise	mode	start [%]	slope [%]
	FM	64	Set_Stereo_Mph	mode	start [%]	slope [%]

	Module	Cmd	1	2	3	4
	FM	65 Set_Stereo_Max	mode			
	FM	66 Set_Stereo_Min	mode	limit [dB]		
3.16	FM/AM	80 Set_Scaler	gain [dB]			
3.17	FM	81 Set_RDS	mode	restart	interface	
3.18	FM/AM	82 Set_QualityStatus	mode	interface		
3.19	FM/AM	83 Set_DR_Blend	mode	in_time [ms]	out_time [ms]	gain [dB]
3.20	FM/AM	84 Set_DR_Options	samplerate	mode	format	
3.21	FM/AM	85 Set_Specials	ana_out			
3.22	AUDIO	10 Set_Volume	volume [dB]			
3.23	AUDIO	11 Set_Mute	mode			
3.24	AUDIO	12 Set_Input	source			
3.25	AUDIO	13 Set_Output_Source	signal	source		
3.26	AUDIO	21 Set_Ana_Out	signal	mode		
3.27	AUDIO	22 Set_Dig_IO	signal samplerate	mode	format	operation
3.28	AUDIO	23 Set_Input_Scaler	source	gain [dB]		
3.29	AUDIO	24 Set_WaveGen	mode amplitude2	offset frequency2	amplitude1	frequency1
3.30	APPL	1 Set_OperationMode	mode			
3.31	APPL	3 Set_GPIO	pin	module	feature	
3.32	APPL	4 Set_ReferenceClock	frequency_msb	frequency_lsb	type	
3.33	APPL	5 Activate	mode			

Table 2. Command overview - read

	Module	Cmd	1	2	3	4
4.1	FM/AM	128	Get_Quality_Status	status offset	level bandwidth	usn modulation
	FM/AM	129	Get_Quality_Data	status offset	level bandwidth	usn modulation
4.2	FM	130	Get_RDS_Status	status d_block	a_block dec_error	b_block c_block
	FM	131	Get_RDS_Data	status d_block	a_block dec_error	b_block c_block
4.3	FM/AM	132	Get_AGC	input_att	feedback_att	
4.4	FM/AM	133	Get_Signal_Status	status (stereo, digital)		
4.5	FM/AM	134	Get_Processing_Status	softmute	highcut	
4.6	FM/AM	135	Get_Interface_Status	samplerate		
4.7	APPL	128	Get_Operation_Status	status		
4.8	APPL	129	Get_GPIO_Status	status (pin state)		
4.9	APPL	130	Get_Identification	device (type, variant)	hw_version (main, sub)	sw_version
4.10	APPL	131	Get_LastWrite	size / module parameter	cmd / index parameter	parameter parameter

8. Legal information

8.1 Definitions

Draft — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

8.2 Disclaimers

Limited warranty and liability — Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information.

In no event shall NXP Semiconductors be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory.

Notwithstanding any damages that customer might incur for any reason whatsoever, NXP Semiconductors' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the Terms and conditions of commercial sale of NXP Semiconductors.

Right to make changes — NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

Suitability for use — NXP Semiconductors products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an NXP Semiconductors product can reasonably be expected

to result in personal injury, death or severe property or environmental damage. NXP Semiconductors accepts no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

Applications — Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Customers are responsible for the design and operation of their applications and products using NXP Semiconductors products, and NXP Semiconductors accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the NXP Semiconductors product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products.

NXP Semiconductors does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using NXP Semiconductors products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). NXP does not accept any liability in this respect.

Export control — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

8.3 Trademarks

Notice: All referenced brands, product names, service names and trademarks are property of their respective owners.

9. List of figures

Fig 1.	I ² C control –TEA685X	4
Fig 4.	Examples of I ² C write control; set command ...	59
Fig 5.	Examples of I ² C read control; get command ...	60
Fig 6.	Example of a possible get command with parameter(s)	61
Fig 7.	Examples of I ² C transmissions with repeated start.....	61
Fig 8.	Example of testing device presence.	61
Fig 9.	Example of I ² C read control with guaranteed 400 kHz operation; get command index = 0	62
Fig 10.	Examples of alternative I ² C read control with guaranteed read data setup.....	63
Fig 11.	Example of write command with evaluation data read.....	63
Fig 12.	Examples of I ² C read control with confirmation; get command index = 0.....	64
Fig 13.	Block diagram of device start-up control sequence	65

10. List of tables

Table 1. Command overview - write.....75

Table 2. Command overview - read.....77

COMPANY CONFIDENTIAL

11. Contents

1.	Introduction	3	4.2.4	Read data definition for RDS demodulator mode	51
2.	Control interface.....	3	4.2.5	RDS read for demodulator mode operation.....	51
2.1	Overview	3	4.3	FM / AM cmd 132 Get_AGC.....	53
2.2	History	5	4.4	FM / AM cmd 133 Get_Signal_Status	53
3.	Write commands	6	4.5	FM / AM cmd 134 Get_Processing_Status.....	54
3.1	FM / AM cmd 1 Tune_To.....	7	4.6	FM / AM cmd 135 Get_Interface_Status	55
3.1.1	radio tuning actions with setting of band and frequency	7	4.7	APPL cmd 128 Get_Operation_Status	56
3.2	FM cmd 2 Set_Tune_Options	10	4.8	APPL cmd 129 Get_GPIO_Status.....	56
3.3	FM / AM cmd 10 Set_Bandwidth.....	11	4.9	APPL cmd 130 Get_Identification.....	57
3.4	FM / AM cmd 11 Set_RFAGC.....	12	4.10	APPL cmd 131 Get_LastWrite.....	58
3.5	AM cmd 12 Set_Antenna	13	5.	I²C bus protocol	59
3.6	FM cmd 20 Set_MphSuppression	14	5.1	I ² C protocol.....	59
3.7	FM / AM cmd 23 Set_NoiseBlanker	15	5.2	Write control	59
3.8	AM cmd 24 Set_NoiseBlanker_Audio	15	5.3	Read control	60
3.9	FM / AM cmd 30 Set_DigitalRadio	16	5.4	I ² C repeated start	61
3.10	FM cmd 31 Set_Deemphasis	16	5.5	Polling device presence.....	61
3.11	FM / AM cmd 38 Set_LevelStep.....	17	5.6	I ² C read timing requirements	61
3.12	FM / AM cmd 39 Set_LevelOffset	18	5.7	Special control.....	63
3.13	FM / AM cmd 40 ... 45 Set_Softmute.....	19	5.7.1	Set command confirmation; special evaluation read control	63
3.14	FM / AM cmd 50 ... 59 Set_Highcut.....	22	5.7.2	Get command confirmation; special evaluation read control	64
3.15	FM cmd 60 ... 66 Set_Stereo.....	27	6.	Device start-up.....	65
3.16	FM / AM cmd 80 Set_Scaler	30	6.1	Introduction.....	65
3.17	FM cmd 81 Set_RDS	31	6.2	Start-up I ² C control transmission sequence	66
3.18	FM / AM cmd 82 Set_QualityStatus	32	6.2.1	Required initialization I ² C transmission – I ² C example.....	67
3.19	FM / AM cmd 83 Set_DR_Blend	33	6.2.2	Required initialization I ² C transmission – C code include file	70
3.20	FM / AM cmd 84 Set_DR_Options	34	6.2.3	Required initialization I ² C transmission – version p2.15	72
3.21	FM / AM cmd 85 Set_Specials	35	6.3	Operation state description.....	73
3.22	AUDIO cmd 10 Set_Volume.....	36	6.3.1	Boot state	73
3.23	AUDIO cmd 11 Set_Mute.....	36	6.3.2	Idle state.....	73
3.24	AUDIO cmd 12 Set_Input.....	37	6.3.3	Active state.....	74
3.25	AUDIO cmd 13 Set_Output_Source.....	37	7.	Overview of available commands	75
3.26	AUDIO cmd 21 Set_Ana_Out.....	38	8.	Legal information	78
3.27	AUDIO cmd 22 Set_Dig_IO.....	38	8.1	Definitions.....	78
3.28	AUDIO cmd 23 Set_Input_Scaler.....	39	8.2	Disclaimers.....	78
3.29	AUDIO cmd 24 Set_WaveGen.....	40	8.3	Trademarks	78
3.30	APPL cmd 1 Set_OperationMode	41	9.	List of figures.....	79
3.31	APPL cmd 3 Set_GPIO.....	42	10.	List of tables	80
3.32	Idle state - APPL cmd 4 Set_ReferenceClock.....	43	11.	Contents	81
3.33	Idle state - APPL cmd 5 Activate.....	44			
4.	Read commands.....	45			
4.1	FM / AM cmd 128 / 129 Get_Quality	46			
4.2	FM cmd 130 / 131 Get_RDS.....	48			
4.2.1	RDS read modes.....	48			
4.2.2	Read data definition for RDS decoder mode....	48			
4.2.3	RDS read operation for decoder mode	49			

Please be aware that important notices concerning this document and the product(s) described herein, have been included in the section 'Legal information'.