

# **ActiveDSO**Developer's Guide



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## **ActiveDSO Developer's Guide**

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# **About ActiveDSO**

ActiveDSO<sup>™</sup> is an **ActiveX**<sup>®</sup> control that enables Teledyne LeCroy oscilloscopes to be controlled by and exchange data with a variety of Windows<sup>®</sup> applications or programming languages that support the ActiveX standard: MS Office programs, Internet Explorer<sup>®</sup>, Visual Basic<sup>®</sup>, Visual C++<sup>®</sup>, Visual Java, Python, and much more.

For easy integration of your scope data with your Windows Application, ActiveDSO helps you:

- Generate a report by importing scope data right into Excel<sup>®</sup>, PowerPoint<sup>®</sup>, or Word<sup>®</sup>.
- Archive measurement results on the fly in a Microsoft Access<sup>®</sup> Database.
- Automate tests using Visual Basic, Java, C++, Excel (VBA).

Examples Methods Properties

# Interfacing to the Oscilloscope

You can interface to most Teledyne LeCroy instruments using standard TCP/IP over Ethernet. GPIB, LSIB, and USBTMC may also be used if the oscilloscope is supplied with the optional interface card or connector.

NOTE: Legacy LeCroy instruments (prior to LSA-1000 series) support only GPIB and RS-232.

The ActiveDSO control hides the intricacies of programming for each of these interfaces and provides a simple and consistent interface to the controlling application. With less than 10 lines of VBA (Visual Basic for Applications) code in an Excel macro, the spreadsheet can recover pre-scaled waveform data from a remote instrument.

# **Embedded Control**

The ActiveDSO control can also be embedded visually in any OLE automation compatible client and used manually without the need for any programming. It will run on any PC running Windows 95 or later, with the exception of Windows 8.

There are two fundamental ways to use the control.

- 1. As a visible object embedded in an OLE Automation compatible Client (PowerPoint for example), showing a captured display image. See <a href="Embedded Control Example"><u>Embedded Control Example</u></a>.
- 2. As an invisible object accessed via a scripting language (Visual Basic for Applications for example) to remotely control an instrument. See <a href="Accessing from VBA">Accessing from VBA</a>.

The control's external name is: LeCroy.ActiveDSOCtrl.1

The control's CLSID is 450A9897-D9C9-11D1-9966-0000F840FC5E

# **System Requirements**

Any Teledyne LeCroy oscilloscope that supports TCP/IP, GPIB, LSIB, or USBTMC

**NOTE**: Only basic support is provided for members of the older 94xx family of instruments. A firmware upgrade is recommended for 93xx and LCxxx scopes. Please contact your Teledyne LeCroy service center. See the <u>Appendix</u>: Wiring for RS-232 Interfaces.

 Personal Computer running Windows 95, Windows 98, Windows NT (Intel, v3.51 or later), Windows 2000, Windows XP, Windows Vista, Windows 7, Windows 10

# **Examples**

# **Embedded Control Example**

The ActiveDSO control may be embedded in any OLE Automation compatible client and used manually without the need for any programming or scripting.

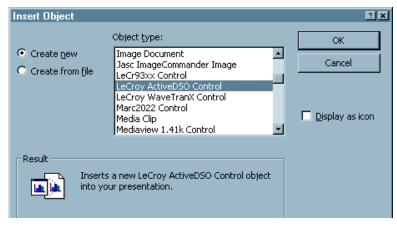
The following simple example shows the control being embedded into a Microsoft PowerPoint slide.

**NOTE:** This example uses PowerPoint 97. Other versions may not behave the same.

## **Embedded Control Example: Step 1**

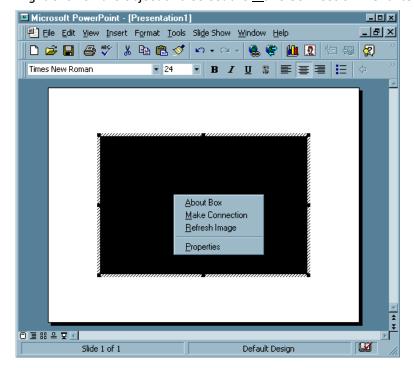
Open PowerPoint with a new blank presentation.

From the Insert Menu, select the Object menu item, then select the 'LeCroy ActiveDSO' object.



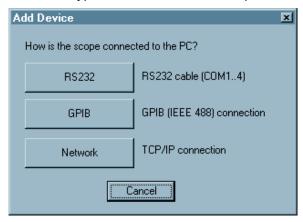
# **Embedded Control Example: Step 2**

Right-click on the object and select the Make Connection menu item.



## **Embedded Control Example: Step 3**

Select the type of connection that is required to communicate with your instrument. GPIB will be used in this example.

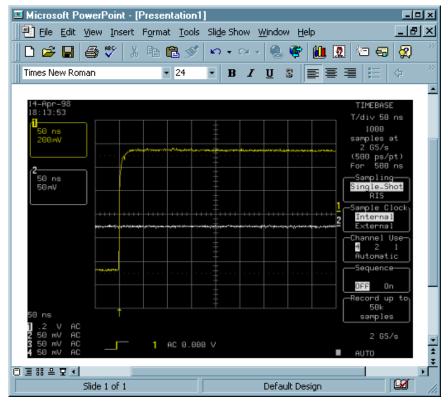


Enter the GPIB address of the device and click on OK.



# **Embedded Control Example: Step 4**

Right-click on the object again and select the <u>Refresh Image</u> menu item. If everything is functioning correctly then the scope's current display image should appear in the control.



# **Accessing from VBA**

VBA (Visual Basic for Applications) is the programming language built in to many of the more recent Windows applications. It is a subset of Visual Basic that makes it very simple to utilize the services of OLE Automation Servers and ActiveX Controls.

The following VBA subroutine demonstrates how easy it is to connect to a remote device (DSO/Signalyst) and send remote commands to it.

To enter the VBA editor in members of the Microsoft Office suite use the <u>Tools -> Macro -> Visual Basic Editor</u> menu item.

When the Visual Basic application appears select the **Insert -> Module** menu item and type (or copy) the above example into the editor window that appears.

To execute the example position the text cursor within the subroutine either select the **Run -> Run Sub/UserForm** or press function key **F5**.

For more examples of control use from VBA refer to the description of each of the Methods and Properties.

# Accessing from Visual C++ 5.0

Accessing the ActiveDSO control from within a Visual C++ application is a little more involved than under VBA. The following example shows how to create a 'wrapper' class for the control and then use the control to communicate with the instrument.

The example assumes a Visual C++ application based on the MFC libraries.

Accessing an ActiveX control from within a C++ application requires the creation of a 'wrapper class'. This is an automatically created file that contains a C++ interface to the ActiveDSO class.

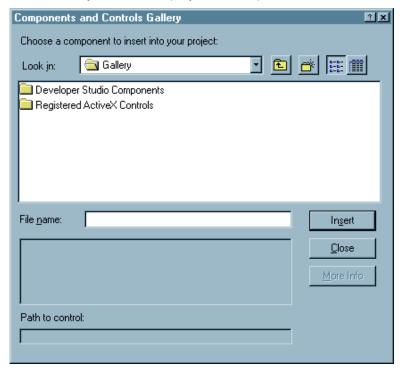
Once the wrapper class has been created the object must be instantiated and 'created' before it may be accessed.

Once communication with the device has been established and an acquisition has been taken the next major step is to read waveform data.

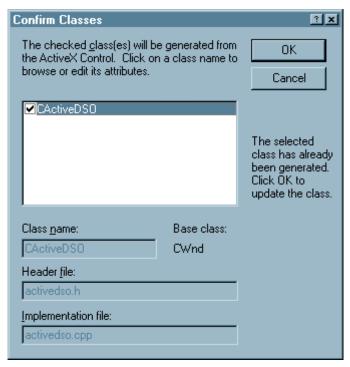
#### Accessing from Visual C++ 5.0: Creating the wrapper class

To create the wrapper class the following procedure may be used:

1. Enter the Project -> Add to project -> Components and controls... menu.



- 2. Select the Registered ActiveX Controls item.
- 3. Select the **LeCroy ActiveDSO Control** from the (long) list that appears. The following dialog should appear:



This dialog allows the class & file names of the 'wrapper' class to be changed, although the default is usually acceptable.

4. When the names are acceptable, click the OK button. Visual C++ will now create the two wrapper files.

# Accessing from Visual C++ 5.0: Using the ActiveDSO control

- 1. Include the 'wrapper' header file created in Accessing from Visual C++ 5.0: Creating the wrapper class.
- 2. Create an instance of the control using the following code snippet (the call to **dso.Create** creates the control in a hidden window since it will be used purely as an automation server):

```
CActiveDSO dso;

RECT dummyRect;

dso.Create("LeCroy.ActiveDSOCtrl.1", "HiddenWindowForDSOControl", 0, dummyRect, this, 0);
```

3. Make a connection to the instrument using the MakeConnection method:

```
Call dso.MakeConnection("GPIB: 5");
```

4. As a quick test of the control call the WriteString method to cause the instrument to beep:

```
Call dso.WriteString("BUZZ BEEP", True);
```

# Accessing from Visual C++ 5.0: Reading Waveform Data

Reading waveform data under Visual C++ is more complex than under Visual Basic since C++ does not natively support the VARIANT data type.

The following code snippet shows one way to access waveform data using the SafeArray support included in MFC (SafeArrayGetElement, SafeArrayGetLBound, and SafeArrayGetUBound).

The SafeArrayGetElement call is not terribly efficient. If performance is critical then the SafeArrayAccessData function should be used instead. See the Microsoft Visual C++ documentation for more information on these functions.

```
void CTestDialog::OnReadWaveform()
      // create the control
      CActiveDSO dso;
             RECT dummyRect;
      dso.Create("LeCroy.ActiveDSOCtrl.1", "Hello", 0, dummyRect, this, 0);
      Call dso.MakeConnection("GPIB: 5");
      Call dso.WriteString("BUZZ BEEP", True);
      // read up to 500 scaled data values from channel 1
      COleVariant waveform;
      waveform.Attach(dso.GetScaledWaveform("C1", // trace name
                            500,
                                  // numPoints
                                   0);
                                        // transfer first array
      // report any error that occurred above, if none occurred
// then loop through each data value
      if(dso.GetErrorFlag())
                 AfxMessageBox(dso.GetErrorString());
      else
          long index = 0;
          long lowerBounds = 0;
          long upperBounds = 0;
          float data;
          // get the upper and lower bounds of the waveform
          SafeArrayGetLBound(waveform.parray, 1, &lowerBounds);
          SafeArrayGetUBound(waveform.parray, 1, &upperBounds);
          // loop through each element in the array
          for(index = lowerBounds; index <= upperBounds; ++index)</pre>
              SafeArrayGetElement(waveform.parray, &index, &data);
          }
```

# **Methods**

The majority of the ActiveDSO methods return TRUE (non-zero) to indicate success, and FALSE (zero) to indicate failure. Upon a failure the ErrorFlag and ErrorString properties may be interrogated to learn more information about the failure. However, some of the methods return a VARIANT. To check for failure in this case, use the ErrorFlag and ErrorString properties.

**AboutBox** 

**DeviceClear** 

**Disconnect** 

**GetByteWaveform** 

**GetCommaDelimitedString** 

**GetIntegerWaveform** 

<u>GetNativeWaveform</u>

GetPanel

**GetParameterValue** 

<u>GetScaledWaveform</u>

<u>GetScaledWaveformWithTimes</u>

**MakeConnection** 

ReadBinary

ReadString

Refreshlmage

<u>SerialPoll</u>

**SetPanel** 

**SetNativeWaveform** 

**SetRemoteLocal** 

**SetTimeout** 

<u>SetupWaveformTransfer</u>

<u>StoreHardcopyToFile</u>

**TransferFileToDso** 

**TransferFileToPc** 

**WaitForOPC** 

WaitForSRQ

**WriteBinary** 

**WriteGPIBCommand** 

**WriteString** 

# **AboutBox Method**

The **AboutBox** method displays a dialog showing the ActiveDSO version number.

# **Syntax**

controlName.AboutBox

**Argument Description** 

controlname The name of the ActiveDSO control object.

# **DeviceClear Method**

The **DeviceClear** method clears the connection to the device.

## **Syntax**

Boolean controlName.DeviceClear

# **Argument Description**

controlname The name of the ActiveDSO control object.

reboot Boolean, normally FALSE, if TRUE the device will be rebooted

#### **Returns**

True on success, False on failure.

#### **Remarks**

This method will send a device clear signal to the instrument. Any unread response currently in the device's output buffer will be cleared.

If the reboot argument is true then this method will reboot the instrument. This operation may take up to 20 seconds to complete depending upon the type of device.

```
Sub example
     Dim o as Object
     set o = CreateObject("LeCroy.ActiveDSOCtrl.1")
     Call o.MakeConnection("GPIB: 5") ' Connect to GPIB device at address 5
     Call o.DeviceClear(True) ' Reboot the device
End sub
```

# **Disconnect Method**

The **Disconnect** method disconnects the control from the device.

# **Syntax**

Boolean controlName.Disconnect

# **Argument Description**

controlname The name of the ActiveDSO control object.

#### **Returns**

True on success, False on failure.

# **Remarks**

This method performs the necessary termination functions, which will cleanup and disconnect the interface connection.

# **GetByteWaveform Method**

The **GetByteWaveform** method reads raw 8-bit waveform data from the instrument into a Byte array.

## **Syntax**

Variant controlName. GetByteWaveform

Argument controlname	<b>Description</b> The name of the ActiveDSO control object.
traceName	String, Source trace name
maxBytes	Long, maximum number of bytes to read
whichArray	Integer, 0 = first array, 1 = second array (for dual-array waveform)

traceName := { C1 | C2 | C3 | C4 | M1 | M2 | M3 | M4 | TA | TB | TC | TD TD | F1 | Z1 | ... } Some scopes/options support many more trace names, refer to the documentation for each scope/option.

#### Remarks

This method should be used when unscaled 8-bit waveform data is required. It is especially useful for transferring huge waveforms due to its efficient use of memory (1 byte per sample as opposed to 4 for the GetScaledWaveform).

Note that waveforms read using this function cannot be sent back into the instrument.

An important point to note when using this function is that in order to store the signed data that the scope emits (-128 to 127) into Visual-Basic's unsigned 'Byte' data type it has been shifted by 128 (0 to 255). This should be remembered when scaling the data.

Use the SetupWaveformTransfer method to define the sparsing factor (to reduce large waveforms), first point to transfer, and segment number to transfer (for sequence waveforms).

Processed waveforms are usually 16 bit waveforms and should be transmitted in 16 bit form to avoid losing precision. Call the GetIntegerWaveform method to do this.

Use the GetScaledWaveformfunction to retrieve waveform data that has already been scaled.

The whichArray parameter should normally be zero, it is used only to specify that the second array of a dual-array waveform is required. Examples of dual-array waveforms are envelope waveforms which have a min and a max value at each sample, or a complex FFT which creates a real, imaginary pair.

#### See Also

SetupWaveformTransfer, GetNativeWaveform, SetNativeWaveform, GetIntegerWaveform, GetScaledWaveform, GetScale

# **GetCommaDelimitedString Method**

The GetCommaDelimitedString method extracts strings from a comma-delimited list.

# **Syntax**

String controlName. GetCommaDelimitedString

Argument	Description
controlname	The name of the ActiveDSO control object.
inputString	String, Source String
index	Long, zero-based index of string to extract

#### **Returns**

A string extracted from a comma-delimited list.

#### Remarks

The remote control language used by LeCroy Instruments can sometimes require a fair amount of string parsing in the remote control application. This method provides a language-independent parsing tool to simplify this.

For example, the parameter query PAVA? returns a string that may look like this:

AMPL,1.02 V,OK

The GetCommaDelimitedString method may be used to extract just the parameter value:

Value = activeDSO.GetCommaDelimitedString(pavaResponse, 1)

```
Sub example

Dim o as Object

set o = CreateObject("LeCroy.ActiveDSOCtrl.1")

Call o.MakeConnection("GPIB: 5") 'Connect to GPIB device at address 5

Call o.WriteString("C1:PAVA?", True) 'Request a parameter value replyString = o.ReadString(80) 'Ask for the instrument's reply

'Extract just the parameter value amplitudeValue = o.GetCommaDelimitedString (replyString, 1)

End sub
```

# GetIntegerWaveform Method

The GetIntegerWaveform method reads raw 16-bit waveform data from the instrument into an Integer array.

## **Syntax**

Variant controlName. GetIntegerWaveform

Argument	Description
controlname	The name of the ActiveDSO control object.
traceName	String, Source trace name
maxBytes	Long, maximum number of bytes to read
whichArray	Integer, 0 = first array, 1 = second array (for dual-array waveform)

traceName := { C1 | C2 | C3 | C4 | M1 | M2 | M3 | M4 | TA | TB | TC | TD TD | F1 | Z1 | ... } Some scopes/options support many more trace names, refer to the documentation for each scope/option.

#### **Remarks**

This method should be used when unscaled 16-bit waveform data is required.

NOTE: Waveforms read using this function cannot be sent back into the instrument.

Use the SetupWaveformTransfer method to define the sparsing factor (to reduce large waveforms), first point to transfer, and segment number to transfer (for sequence waveforms).

Processed waveforms are usually 16 bit waveforms and should be transmitted in 16-bit form to avoid losing precision. Channel waveforms are usually 8 bit waveforms and may be transferred using the GetByteWaveform method to reduce transfer time and storage requirements.

Use the GetScaledWaveform function to retrieve waveform data that has already been scaled.

The whichArray parameter should normally be zero, it is used only to specify that the second array of a dual-array waveform is required. Examples of dual-array waveforms are envelope waveforms which have a min and a max value at each sample, or a complex FFT which creates a real,imaginary pair.

#### See Also

SetupWaveformTransfer, GetNativeWaveform, SetNativeWaveform, GetByteWaveform, GetScaledWaveform, GetScaledWa

```
Sub example
    Dim o as Object
    set o = CreateObject("LeCroy.ActiveDSOCtrl.1")

Call o.MakeConnection("GPIB: 5") ' Connect to GPIB device at address 5
    ' Read the contents of C1 into an array
    Dim waveform
    waveform waveform = o.GetIntegerWaveform("C1", 5000, 0)

' Determine the number of samples read
    NumSamples = UBound(waveform)

' Loop through all ampl values
For i = 0 To NumSamples
amplitude = waveform(i)
Next i
End sub
```

## **GetNativeWaveform Method**

The GetNativeWaveform method reads a waveform from the instrument in its native binary form.

## **Syntax**

Variant controlName. GetNativeWaveform

Argument	Description
controlname	The name of the ActiveDSO control object.
traceName	String, Source trace name
maxBytes	Long, maximum number of bytes to read
wordData	Boolean, if TRUE transmit data as 16 bit words, FALSE for 8 bit words.
blockName	String, Waveform block name

traceName := { C1 | C2 | C3 | C4 | M1 | M2 | M3 | M4 | TA | TB | TC | TD TD | F1 | Z1 | ... } Some scopes/options support many more trace names, refer to the documentation for each scope/option.

blockName := { DESC | TEXT | TIME | DAT1 | DAT2 | ALL }

#### Remarks

Channel waveforms (C1..C4) should be transmitted in 8-bit form by setting wordData FALSE.

Processed waveforms are usually 16 bit waveforms and should be transmitted in 16-bit form to avoid loosing precision. Set wordData TRUE to do this.

Use the GetScaledWaveform function to retrieve waveform data that has already been scaled.

blockName should be used to transfer the descriptor (DESC), the user text (TEXT), the time descriptor (TIME), the data (DAT1) block and optionally a second block of data (DAT2) or all entities (ALL).

Only complete waveforms transferred with (ALL) can be sent back into the instrument using the SetNativeWaveformSetNativeWaveform Method.

Use the BytesRead property to determine how many bytes were placed in the destination buffer. This value will be required to know how many bytes to send back into the instrument with the SetNativeWaveform Method.

#### See Also

SetupWaveformTransfer, SetNativeWaveform, GetByteWaveform, GetIntegerWaveform, GetScaledWaveform, GetScaledW

```
Sub example
     Dim o as Object
     set o = CreateObject("LeCroy.ActiveDSOCtrl.1")

Call o.MakeConnection("GPIB: 5") ' Connect to GPIB device at address 5

' Read the contents of C1 into an array
     Dim waveform() as Byte
     waveform = o.GetNativeWaveform("C1", 5000, False, "ALL")
End sub
```

## **GetParameterValue Method**

The GetParameterValue method reads a parameter value from the instrument.

## **Syntax**

Double controlName. GetParameterValue

Argument controlname Description
The name of the ActiveDSO control object.

SourceTrace String, Source trace name

String, Parameter Name

retUnits String, storage for returned Units string

retState String, storage for returned State string

*traceName :=* { C1 | C2 | C3 | C4 | M1 | M2 | M3 | M4 | TA | TB | TC | TD TD | F1 | Z1 | ... } Some scopes/options support many more trace names, refer to the documentation for each scope/option.

```
paramName := { see PAVA? In remote control manual }
retState := { see PAVA? In remote control manual }
```

#### **Returns**

A double-precision floating-point value containing the parameter value.

#### Remarks

This method provides a simple way to read parameter values from the Instrument. Internally the method uses the PAVA? query to read a string containing the parameter value. This string is parsed and the value, units, and state extracted and returned.

**NOTE**: If the units are required ensure that the instrument is in 'COMM\_HEADER SHORT' or 'COMM\_HEADER LONG' mode before calling this method. If the COMM\_HEADER is 'OFF' then the parameter value will be returned correctly, but the units string will be empty.

```
Sub example
        Dim o as Object
        set o = CreateObject("LeCroy.ActiveDSOCtrl.1")

        Call o.MakeConnection("GPIB: 5") ' Connect to GPIB device at address 5
' Read the amplitude parameter measurement
Dim units As String
Dim state As String
amplitudeValue = o.GetParameterValue("C1", "AMPL", units, state)
End sub
```

# **GetPanel Method**

The **GetPanel** method reads the instrument's control state into a String, allowing a future call to **SetPanel** to reproduce the state.

# **Syntax**

String controlName. GetPanel

## **Argument Description**

controlname The name of the ActiveDSO control object.

#### **Returns**

A string containing the hex-ascii Panel.

#### **Remarks**

Use the SetPanel Method to send the panel back into the instrument.

The size of the panel will be approximately 5000 bytes, depending upon the instrument's firmware revision.

```
Sub example
Dim o as Object
set o = CreateObject("LeCroy.ActiveDSOCtrl.1")

Call o.MakeConnection("GPIB: 5") 'Connect to GPIB device at address 5

'Read the panel from the instrument and send it back in
Dim panelString as String
PanelString = o.GetPanel()
Call o.SetPanel(panelString)

End sub
```

## **GetScaledWaveform**

The GetScaledWaveform method reads a scaled waveform from the instrument.

## **Syntax**

Variant controlName. GetScaledWaveform

Argument	Description
controlname	The name of the ActiveDSO control object.
traceName	String, Source trace name
maxBytes	Long, maximum number of bytes to read
whichArray	Integer, 0 = first array, 1 = second array (for dual-array waveform)

traceName := { C1 | C2 | C3 | C4 | M1 | M2 | M3 | M4 | TA | TB | TC | TD TD | F1 | Z1 | ... } Some scopes/options support many more trace names, refer to the documentation for each scope/option.

#### **Returns**

A variant containing the scaled waveform, stored as an array of single-precision floating point values.

#### Remarks

Use the GetByteWaveform or GetIntegerWaveform method to retrieve a waveform in its raw binary form. This may be preferable in a time-critical application.

If the time value corresponding to each sample amplitude is required use the GetScaledWaveformWithTimes method.

The whichArray parameter should normally be zero, it is used only to specify that the second array of a dual-array waveform is required. Examples of dual-array waveforms are envelope waveforms which have a min and a max value at each sample, or a complex FFT which creates a real, imaginary pair.

#### See Also

SetupWaveformTransfer, GetNativeWaveform, SetNativeWaveform, GetByteWaveform, GetIntegerWaveform, GetScaledWaveformWithTimes

# GetScaledWaveformWithTimes Method

The **GetScaledWaveformWithTimes** method reads a scaled waveform from the instrument and stores the time and amplitude at each sample point.

#### **Syntax**

Variant controlName. GetScaledWaveformWithTimes

Argument	Description
controlname	The name of the ActiveDSO control object.
traceName	String, Source trace name
maxBytes	Long, maximum number of bytes to read
whichArray	Integer, 0 = first array, 1 = second array (for dual-array waveform)

*traceName :=* { C1 | C2 | C3 | C4 | M1 | M2 | M3 | M4 | TA | TB | TC | TD TD | F1 | Z1 | ... } Some scopes/options support many more trace names, refer to the documentation for each scope/option.

#### **Returns**

A variant containing the scaled waveform, stored as a two-dimensional array of single-precision floating point values. Time values are stored in the first column of the array, amplitude values are stored in the second column.

#### Remarks

Use the GetByteWaveform or GetIntegerWaveform method to retrieve a waveform in its raw binary form. This may be preferable in a time-critical application.

If the time value corresponding to each sample amplitude is not required use the GetScaledWaveform method.

The whichArray parameter should normally be zero, it is used only to specify that the second array of a dual-array waveform is required. Examples of dual-array waveforms are envelope waveforms which have a min and a max value at each sample, or a complex FFT which creates a real,imaginary pair.

#### See Also

SetupWaveformTransfer, GetNativeWaveform, SetNativeWaveform, GetByteWaveform, GetIntegerWaveform, GetScaledWaveform

```
Sub example
    Dim o as Object
    set o = CreateObject("LeCroy.ActiveDSOCtrl.1")

Call o.MakeConnection("GPIB: 5") ' Connect to GPIB device at address 5

' Read the contents of C1 (up to max. of 5000 points) into an array
    Dim waveform
    Waveform = o.GetScaledWaveformWithTimes("C1", 5000, 0)

' Determine the number of samples read
    NumSamples = UBound(waveform, 2)

' Loop through all time, ampl pairs

For i = 0 To NumSamples
time = waveform(0, i)
amplitude = waveform(1, i)
Next i

End sub
```

# **MakeConnection Method**

The MakeConnection method creates the connection between the control and a device.

## **Syntax**

Boolean controlName.MakeConnection

# **Argument Description**

controlname The name of the ActiveDSO control object.

address Device address string

#### **Returns**

True on success, False on failure.

#### **Remarks**

Once the ActiveDSO object is created by the container application, this method is first one that needs to be invoked to make the initial connection to the instrument. The address argument will take an address in the form of string.

Interface	Syntax	Example
GPIB	GPIBx: nn x := 03 (optional) nn := 130	GPIB: 5
Network	IP: a.b.c.d a,b,c,d := 0 to 255	IP:128.23.24.21
RS232	COMn: baud,bits,parity,stop n := 14 baud := { 300   1200   2400   4800   9600   19200   57600   115000 } bits := 7   8 parity := N   O   E stop := 1   1.5   2	COM1: 19200,8,N,1
USBTMC	USBTMC: <visa-resource name=""></visa-resource>	USBTMC:USB0::0x05FF::0x1023::2807N59057::INSTR

## **VBA Example (GPIB)**

```
Sub example
     Dim o as Object
     set o = CreateObject("LeCroy.ActiveDSOCtrl.1")
     Call o.MakeConnection("GPIB: 5") ' Connect to GPIB device at address 5
     Call o.WriteString("VDIV 50mV", True)
End sub
```

# **ReadBinary Method**

The **ReadBinary** method reads a binary response from the instrument.

## **Syntax**

Variant controlName. ReadBinary

Argument Description

controlname The name of the ActiveDSO control object.

maxBytes Long, Maximum number of bytes to read

#### **Returns**

This method returns the received data in a Variant containing an array of bytes.

#### **Remarks**

This method reads a binary response from the instrument. The *maxBytes* argument indicates the maximum number of bytes to read. If there is more to read than the indicated *maxBytes*, then the remaining bytes will be left unread in the instrument.

# **ReadString Method**

The **ReadString** method reads a string response from the instrument.

# **Syntax**

String controlName.ReadString

Argument Description

controlname The name of the ActiveDSO control object.

maxBytes Long, Maximum number of bytes to read

#### **Returns**

The device response is returned in a String.

#### **Remarks**

This method reads a string response from the instrument. The *maxBytes* argument indicates the maximum number of characters to read. If there is more to read than the indicated *maxBytes*, then the remaining characters will be left unread in the instrument.

```
Sub example

Dim o as Object

set o = CreateObject("LeCroy.ActiveDSOCtrl.1")

' Read the *IDN? Response

Call o.MakeConnection("GPIB: 5") ' Connect to GPIB device at address 5

Call o.WriteString("*IDN?", True) ' Request the Scope's ID string

replyString = o.ReadString(80) ' Read the DSO's reply

End sub
```

# **Refreshlmage Method**

The **RefreshImage** method updates the control's image with the current contents of the instrument's display.

# **Syntax**

Boolean controlName. RefreshImage

# **Argument Description**

controlname The name of the ActiveDSO control object.

#### **Returns**

True on success, False on failure.

# **Remarks**

This method is only useful if the control is embedded into a form or document. When the control is being used as an Automation server without it being visible it is of no use.

# SerialPoll Method

The SerialPoll method returns the device's serial poll response (GPIB Devices Only).

# **Syntax**

Boolean controlName.SerialPoll

# Argument Description

controlname The name of the ActiveDSO control object.

response Integer, storage for serial poll response

#### **Returns**

True on success, False on failure.

#### **Remarks**

Serial polling usually takes place once an SRQ (service request) has been asserted and is advantageous when there are several instruments involved.

The serial poll returns the STB register of the instrument. This contains a bit (SRQ) which indicates whether the device is currently requesting service.

```
Sub example
        Dim o as Object
        set o = CreateObject("LeCroy.ActiveDSOCtrl.1")

        Call o.MakeConnection("GPIB: 5") ' Connect to GPIB device at address 5
        ' Serially poll the device, returns STB register

Dim x As Integer
Call o.SerialPoll(x)
End sub
```

# **SetNativeWaveform Method**

The **SetNativeWaveform** method writes a waveform in its native binary form into the instrument.

# **Syntax**

Boolean controlName. SetNativeWaveform

Argument controlname	<b>Description</b> The name of the ActiveDSO control object.
destination	String, Destination trace name
buffer	Byte Array, Source buffer
destination := { M1   M2   M3   M4 }	

#### **Returns**

True on success, False on failure.

#### Remarks

This method sends a waveform captured using the GetNativeWaveform method back into the instrument. Note that waveforms captured using the other GetxxxWaveform functions cannot be sent back into the instrument in this way.

```
Sub example
      Dim o as Object
      set o = CreateObject("LeCroy.ActiveDSOCtrl.1")
      Call o.MakeConnection("GPIB: 5") 'Connect to GPIB device at address 5
      ' Read the contents of C1 into an array and write it back into M1
      Dim waveform() as Byte
      waveform = o.GetNativeWaveform("C1", 5000, False, "ALL")
      Call o.SetNativeWaveform("M1", waveform)
End sub
```

# **SetPanel Method**

The SetPanel method sets the instrument's control state using a panel string captured using the method GetPanel.

## **Syntax**

Boolean controlName. SetPanel

# **Argument Description**

controlname The name of the ActiveDSO control object.

buffer String, panel string captured with **GetPanel**.

#### **Returns**

True on success, False on failure.

#### **Remarks**

Use the GetPanel method to read the panel string.

```
Sub example
    Dim o as Object
    set o = CreateObject("LeCroy.ActiveDSOCtrl.1")

Call o.MakeConnection("GPIB: 5") ' Connect to GPIB device at address 5

' Read the panel from the instrument and send it back in
    Dim panelString as String
    PanelString = o.GetPanel()
    Call o.SetPanel(panelString)
End sub
```

# SetRemoteLocal Method

The SetRemoteLocal method controls the Remote/Local state of the device.

# **Syntax**

Boolean controlName.SetRemoteLocal

**Argument Description** 

controlname The name of the ActiveDSO control object.

mode Long, 1 = Remote mode, 0 = Local mode

#### **Returns**

True on success, False on failure.

#### **Remarks**

This method sets the instrument to Remote or Local mode, if the *mode* argument is set to 1 then the oscilloscope is set to Remote Mode, otherwise oscilloscope is set to Local Mode.

**NOTE:** All 94xx and 93xx/LCxxx oscilloscopes with firmware revisions prior to legacy firmware 7.2.0 require the oscilloscope to be in Remote mode before remote commands (not queries) would be accepted. All 93xx/LCxxx/LSAxxxx instruments running legacy 7.2.0 or later accept commands both in Local and Remote modes.

# **SetTimeout Method**

The **SetTimeout** method sets the control's time-out time.

## **Syntax**

Boolean controlName.SetTimeout

**Argument Description** 

controlname The name of the ActiveDSO control object.

timeoutTime Single, Time-out time in seconds

#### **Returns**

True on success, False on failure.

#### Remarks

This method sets the time that the control will wait for a response from the instrument. The methods to which this applies are:

ReadString, ReadBinary, WaitForOPC, GetByteWaveform, GetIntegerWaveform GetNativeWaveform, GetScaledWaveform, GetScaledWaveformWithTimes

# SetupWaveformTransfer Method

The **SetupWaveformTransfer** configures various parameters that control the transfer of waveforms from the instrument to the PC.

# **Syntax**

Boolean controlName. SetupWaveformTransfer

Argument	Description
firstPoint	Integer, The index of the first point to transfer $(0 = first point)$ .
sparsing	Integer, The sparsing factor (0 = all points, 2 = skip every other pt.)
segmentNo	Integer, Segment number to transfer (0 = all segments).

#### **Returns**

True on success, False on failure.

#### **Remarks**

This method affects how the various GetWaveform functions transfer a waveform.

For the majority of cases the default settings will be sufficient. These are:

Start Transfer at first point

Transfer all data points

Transfer all segments.

# **VBA Example**

End sub

```
Sub example

Dim o as Object

set o = CreateObject("LeCroy.ActiveDSOCtrl.1")

Call o.MakeConnection("GPIB: 5") 'Connect to GPIB device at address 5

'Setup waveform transfer to start sending at point 100, transfer every'other point, and transfer data only from segment 5 of a sequence waveform.

Call o.SetupWaveformTransfer(100, 2, 5)
```

### StoreHardcopyToFile Method

The **StoreHardcopyToFile** method transfers a hardcopy image from the instrument and stores it in a file on the controlling PC.

### **Syntax**

Boolean controlName. StoreHardcopyToFile

Argument	Description
controlname	The name of the ActiveDSO control object.
format	String, Hardcopy format. See list/explanation below
auxFormat	String, Auxiliary format, normally empty ("").
filename	Destination filename.

#### Returns

True on success, False on failure.

#### Remarks

This method uses the instrument's HARDCOPY\_SETUP and SCREEN\_DUMP remote commands to retrieve a hardcopy image and store it in a file on the controlling PC.

The *format* string may be any device shown in the remote control manual on the HARDCOPY\_SETUP command page. Depending on the family (93xx, LCxxx, and LSAxxxx) and the software version, these could include:

BMP, BMPCOMP, CANONCOL, EPSON, EPSONCOL, HPDJ, HPDJBW, HPPJ, HPTJ, HPLJ, HP7470A, HP7550A, TIFF, TIFFCOL, TIFFCOMP, HPGL

The auxFormat string may be used to send extra information to the HARDCOPY\_SETUP command. This could include the paper orientation ("FORMAT, PORTRAIT", or "FORMAT, LANDSCAPE"), page-feed ("PFEED, ON" or "PFEED, OFF"), etc. Again, see the HARDCOPY\_SETUP page of the instrument remote control manual for more details.

```
Sub example

Dim o as Object

set o = CreateObject("LeCroy.ActiveDSOCtrl.1")

Call o.MakeConnection("GPIB: 5") 'Connect to GPIB device at address 5

'Read a BMP image from the instrument and store it in file 'C:\BMPImage.bmp'

Call o.StoreHardcopyToFile("BMP", "", "C:\BMPImage.bmp")

'Read a TIFF image from the instrument and store it in file 'C:\TIFFImage.tif'

Call o.StoreHardcopyToFile("TIFF", "", "C:\TIFFImage.tif")

'Read an HPGL image from the instrument and store it in file 'C:\HPGLImage.hpl'

Call o.StoreHardcopyToFile("HPGL", "", "C:\HPGLImage.hpl")

'Read an HP LaserJet formatted image from the instrument and store it in file 'C:\HPLJImage.img'

Call o.StoreHardcopyToFile("HPLJ", "PFEED,ON,FORMAT,PORTRAIT", "C:\HPLJImage.img")

End sub
```

### TransferFileToDso Method

The **TransferFileToDso** method transfers a file from the PC to a mass storage device on the oscilloscope.

### **Syntax**

Boolean controlName.TransferFileToDso

Argument	Description
remoteDevice	String, The device name for instrument end (CARD, HDD, FLPY).
remoteFileName	String, The name (and path) of the destination file on the instrument.
localFileName	String, The name (and path) of the source file on the PC.

### **Returns**

True on success, False on failure.

### **Remarks**

CARD applies only to legacy models.

### **VBA Example**

```
Sub example

Dim o as Object

set o = CreateObject("LeCroy.ActiveDSOCtrl.1")

o.MakeConnection("GPIB: 5") 'Connect to GPIB device at address 5

'Copy localpath\localfile to remotepath\remotefile.

o.TransferFileToDso("HDD", "D:\dso\dest.txt", "C:\pc\src.txt")
```

End sub

### TransferFileToPc Method

The TransferFileToPc method transfers a file from a mass storage device on the instrument to the PC.

### **Syntax**

Boolean controlName.TransferFileToPc

Argument	Description
remoteDevice	String, The device name for instrument end (CARD, HDD, FLPY).
remoteFileName	String, The name (and path) of the source file on the instrument.
localFileName	String, The name (and path) of the destination file on the PC.

### **Returns**

True on success, False on failure.

### **Remarks**

CARD applies only to legacy models.

```
Sub example

Dim o as Object

set o = CreateObject("LeCroy.ActiveDSOCtrl.1")

o.MakeConnection("GPIB: 5") 'Connect to GPIB device at address 5

'Copy remotepath\remotefile to localpath\localfile.

o.TransferFileToPc("HDD", "D:\dso\src.txt", "C:\pc\dest.txt")

End sub
```

## WaitForOPC Method

The WaitForOPC method may be used to wait for previous commands to be interpreted before continuing.

### **Syntax**

Boolean controlName.WaitForOPC

## **Argument Description**

controlname The name of the ActiveDSO control object.

### **Returns**

True on success, False on failure.

### **Remarks**

This method sends the query '\*OPC?' to the device and waits for its reply.

## WaitForSRQ Method

The WaitForSRQ method may be used to wait for an SRQ (Service Request) from the device.

### **Syntax**

Boolean controlName.WaitForSRQ

**Argument Description** 

controlname The name of the ActiveDSO control object.timeoutTime Single, Time to wait (in seconds) for an SRQ

### **Returns**

True on success, False on failure.

### **Remarks**

If an SRQ is detected from the device within the specified time the method will return TRUE.

## **WriteBinary Method**

The WriteBinary method sends a binary data block to the device with or without a terminating EOI (End or Identify).

### **Syntax**

Boolean controlName.WriteBinary

Argument	<b>Description</b> The name of the ActiveDSO control object.		
controlname			
srcArray	Byte Array, Data Array to send to the device.		
numBytes	Long, Number of bytes to send		
EOI	Boolean, True = terminate with EOI		

#### **Returns**

True on success, False on failure.

#### Remarks

If EOI is set to TRUE then the device will start to interpret the command immediately. This is normally the desired behavior.

If EOI is set to FALSE then a command may be sent in several parts with the device starting to interpret the command only when it receives the final part which should have EOI set TRUE.

```
Sub example
      Dim o as Object
      set o = CreateObject("LeCroy.ActiveDSOCtrl.1")
      Call o.MakeConnection("GPIB: 5") ' Connect to GPIB device at address 5
'read waveform into 'wf' Variant array
      Call o.WriteString "VBS app.Memory.M2.ClearMem", True ' clear M2,
' Important ! turn header off
' Important ! ALL must be used as argument for WF?
' Request the waveform data for C1
      Call o.WriteString "CHDR OFF; MSIZ 500; C1:WF? ALL", True
      Dim wf
      wf = o.ReadBinary(2000) ' Read C1 data
      o.WaitForOPC
      Call o.WriteString "M2:WF ", False ' Prepare the DSO to receive a waveform in M2
      Call o.WriteBinary "wf, 2000, True" ' Send the waveform, terminate with EOI
      o.WaitForOPC
End sub
```

## WriteGpibCommand Method

The WriteGpibCommand method sends low-level GPIB commands to the device.

### **Syntax**

Boolean controlName.WriteGpibCommand

Argument	Description
controlname	The name of the ActiveDSO control object.
cmdArray	Byte Array, GPIB commands to send to the device.
numBytes	Long, Number of bytes to send

### **Returns**

True on success, False on failure.

### **Remarks**

This method is useful only for devices connected using the GPIB bus and is not usually required when communicating with a LeCroy instrument. It is used to support older GPIB devices.

When invoked while the instrument is connected via other means than GPIB, this method does nothing and returns immediately without error.

### **WriteString Method**

The WriteString method sends a string to the connected device with or without a terminating EOI (End or Identify).

### **Syntax**

Boolean controlName.WriteString

Argument	Description
controlname	The name of the ActiveDSO control object.
textString	String, Text string to send to the device.
EOI	Boolean, TRUE = terminate with EOI

#### **Returns**

True on success, False on failure.

### **Remarks**

This method sends a string command to the instrument.

If EOI is set to TRUE then the device will start to interpret the command immediately. This is normally the desired behavior.

If EOI is set to FALSE then a command may be sent in several parts with the device starting to interpret the command only when it receives the final part which should have EOI set TRUE.

```
Sub example
        Dim o as Object
        set o = CreateObject("LeCroy.ActiveDSOCtrl.1")
        Call o.MakeConnection("GPIB: 5") ' Connect to GPIB device at address 5
        Call o.WriteString("VDIV ", False) ' First part of command, no EOI
        Call o.WriteString("10V ", True)' Second part of command, terminate with EOI
End sub
```

# **Properties**

<u>BinTransferSupport</u>

BytesRead

ConnectionType

DeviceModel

ErrorFlag

ErrorString
NumChannels

<u>ScreenType</u>

SerialNumber

## **BinTransferSupport Property**

The **BinTransferSupport** property is a read-only **Boolean** value that is set TRUE during a call to the MakeConnection method if it is determined that the connection can support binary data transfers.

**NOTE**: Binary data transfers are supported by the GPIB and Network interfaces but not by the RS232 interface. The GetBinaryWaveform and SetBinaryWaveform methods automatically compensate for an interface that does not support binary data transfers by transferring the waveform in hex-ascii form.

# **BytesRead Property**

The **BytesRead** property is a read-only **Long** value that indicates the number of bytes read from the device by the last method used.

# **ConnectionType Property**

The **ConnectionType** property is a read-only **String** value that is set to indicate the type of connection to the device when the MakeConnection is called.

## Settings

GPIB Device

**Network Device** 

**RS232 Device** 

# **DeviceModel Property**

The **DeviceModel** property is a read-only String value that is set to the device model string extracted from the \*IDN? query when the MakeConnection method is called.

## **ErrorFlag Property**

The **ErrorFlag** property is a read-only **Boolean** value that is set TRUE if an error occurred since either the MakeConnection call or the last time that it was read.

If the ErrorFlag is set TRUE the ErrorString property may be used to extract a verbose description of the error.

It is highly advisable to check the state of the ErrorFlag frequently during a remote control session.

## **ErrorString Property**

The **ErrorString** property is a read-only **String** value that should be read if the ErrorFlag property is set TRUE to extract a verbose description of the error that occurred.

**NOTE:** The ErrorString property is cleared by a call to the MakeConnection method, or when the ErrorString property is read.

# **NumChannels Property**

The **NumChannels** property is a read-only **Long** value that is set to the number of channels supported by the device when the MakeConnection method is called.

# **ScreenType Property**

The **ScreenType** property is a read-only **String** value that is set to the type of display supported by the device when the MakeConnection method is called.

## Settings

Color Screen

Monochome Screen

# **SerialNumber Property**

The **SerialNumber** property is a read-only String value that is set to the device serial number string extracted from the \*IDN? query when the MakeConnection method is called.

# **Appendix: Wiring for RS-232 Interfaces**

DB-9 to DB-9 Null-Modem cable wiring is required.

**NOTE**: ScopeExplorer uses the oscilloscope in Hardware Handshake mode and therefore requires a full Null-Modem cable. A cable that just connects TxD/RxD and Gnd will not function correctly.

A cable constructed using the following wiring diagram may be used to control a 93xx/LCxxx DSO from a standard PC using the RS-232 port.

Description	DB-9 Male Pin #		DB-9 Male Pin #	Description
DCD+DSR	1 and 6	<->	4	DTR
RxD	2	<->	3	TxD
TxD	3	<->	2	RxD
DTR	4	<->	1 and 6	DCD+DSR
Gnd	5	<->	5	Gnd
RTS	7	<->	8	CTS
CTS	8	<->	7	RTS

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