# IwIP TCP/IP Stack and Kinetis SDK Integration User's Guide

# **1** Overview

This document describes how to compile and run the lwIP TCP/IP stack examples. This document also provides the board-specific information related to the jumper and hardware settings.

# 2 Release Scope

## 2.1 Hardware

Support for TWR-K64F120M and TWR-K65F180M Tower System modules and FRDM-K64F Freescale Freedom Development Platform

# 3 Requirements for Running IwIP Demos

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# 3.1 Hardware

- TWR-K64F120M/ Freescale Freedom FRDM-K64F platform
- TWR-SER and elevator
- TWR-K65F180M
- USB cable
- Ethernet cable

# 3.2 Software

- Freescale KSDK release package that includes the lwIP TCP/IP package
- IAR Embedded Workbench for ARM<sup>®</sup> version 7.50.0
- Keil<sup>®</sup> µVision<sup>®</sup> 5 Integrated Development Environment Version 5.17 service pack for Kinetis K60
- Kinetis Design Studio IDE Version: 3.0
- Makefiles support with GCC revision 4.9-2015-q3-update from ARM Embedded
- Atollic<sup>®</sup> TrueSTUDIO<sup>®</sup> 5.4.0

# 3.3 Board jumper settings

The Ethernet-related jumper settings are described in this document. For other jumper settings, see the board-specific user's guide. By default, the lwIP stack uses RMII mode. Follow the below hardware configuration:

- TWR-K64F120M
  - J32 1-2: Use the external clock from the CLOCKIN0 to keep the synchronization with the external PHY on TWR-SER Tower System module.
- TWR-K65F180M
  - No jumper specifications.
- TWR-SER
  - J2 3-4: Ethernet PHY Clock Select 50 MHz, RMII mode. Cut off other connections on this jumper.
  - J3 2-3: Route 50 MHz clock to CLOCKIN0. Cut off other connections on this jumper.
  - J12 9-10: Ethernet PHY Configuration, pull-up CONFIGO, RMII select. Cut off other connections on this jumper.
- Freescale Freedom FRDM-K64F platform
  - No jumper specifications.

# 4 IwIP code structure

The lwIP code is located in this folder: <KSDK install\_dir>/middleware/lwip\_1.4.1. The lwip folder includes the source code. There are two subfolders in the lwip folder as shown in the figure.

Name		
📕 port		
鷆 src		

Figure 1. IwIP folder structure

- src
- This subfolder includes the lwIP 1.4.1 source code which can be downloaded from this link: savannah.gnu.org

• port

• This subfolder includes the adapter files which can make the lwIP stack run on the KSDK and different RTOSes.

# 5 Compiling or Running the IwIP Stack and Demos

## 5.1 Step-by-step guide for IAR

This section shows how to compile and run demos in IAR.

1. Open the workspace corresponding to different demos and different boards. For example, the lwip\_ping\_demo.eww on the Freescale Freedom FRDM-K64F Platform under <install\_dir>/boards/frdmk64f/demo\_apps/lwip/lwip\_ping/bm/iar/ or the lwip\_ping\_demo\_freertos.eww on the Freescale Freedom FRDM-K64F platform under <install\_dir>/boards/ frdmk64f/demo\_apps/lwip/lwip\_ping/freertos/iar/. These steps use lwip\_ping\_demo.eww on FRDM-K64F as an example.



Figure 2. Workspace

2. Build the ksdk\_platform\_lib library.

#### Compiling or Running the IwIP Stack and Demos



Figure 3. ksdk\_platform\_lib

3. Build the lwip\_ping\_demo.



#### Figure 4. lwip\_ping\_demo

- 4. Click the "Download and Debug" button. Wait for the download to finish.
- 5. Click the "Go" button to run the demo.

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# 5.2 Step-by-step guide for Keil

This section shows how to compile and run demos in Keil.

1. Open the workspace corresponding to different demos and different boards. For example, the lwip\_ping\_demo.uvmpw on the Freescale Freedom FRDM-K64F platform under <install\_dir>/boards/frdmk64f/demo\_apps/lwip/lwip\_ping/bm/ mdk/ or the lwip\_ping\_demo\_freertos.uvmpw on the Freescale Freedom FRDM-K64F platform under <install\_dir>/ boards/frdmk64f/demo\_apps/lwip/lwip\_ping/freertos/mdk/. These steps take lwip\_ping\_demo.uvmpw on the Freescale Freedom FRDM-K64F platform for an example.



Figure 5. Workspace

- 2. Build the ksdk\_platform\_lib library.
- 3. Build the lwip\_ping\_demo.
- 4. Click Start/Stop Debug Session. Wait for the download to finish.
- 5. Click the "Run" button to run the demo.

# 5.3 Step-by-step guide for the Kinetis Design Studio IDE and Atollic TrueSTUDIO

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#### Compiling or Running the IwIP Stack and Demos

This section shows how to compile and run demos in the Kinetis Design Studio IDE. The steps are identical for Atollic TrueSTUDIO.

 The Kinetis Design Studio doesn't have a workspace. Create a workspace and import the platform/rtos libraries and the lwIP demos. For example, ksdk\_platform\_lib under <install\_dir>/lib/ksdk\_platform\_lib/kds/K64F12 and .cproject for lwip\_ping\_demo on Freescale Freedom FRDM-K64F platform under <install\_dir>/boards/frdmk64f/demo\_apps/lwip/ lwip\_ping/bm/kds/; or lwip\_ping\_demo\_freertos on Freescale Freedom FRDM-K64F platform under <install\_dir>/ boards/frdmk64f/demo\_apps/lwip/lwip\_ping/freertos/kds/.



Figure 6. Import project



Compiling or Running the IwIP Stack and Demos

Figure 7. Import project select

Compiling or Running the IwIP Stack and Demos



#### Figure 8. Demo project

- 2. Build the lwip\_ping\_demo.
- 3. Open debug configurations and choose J-Link Debugging.

#### **Revision History**

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Create, manage, and run configurations			ð.
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Filter metched 13 of 39 items		Apply	Revert
(?)		Debug	Close

#### Figure 9. Debug Configurations

- 4. Click the "Debug" button. Wait for the download to finish.
- 5. Click the "Resume" button to run the demo.

# 5.4 Step-by-step guide for ARMGCC and KDSGCC

- 1. ARMGCC and KDSGCC both use cMake to generate makefiles. Run the batch file (in the Windows<sup>®</sup> operating system) or sh file (in Linux<sup>®</sup> operating system) to build projects. These steps use ARMGCC as an example.
- 2. Change to the demo directory. For example: <install\_dir>/boards/frdmk64f/demo\_apps/lwip/lwip\_ping/bm/armgcc
- 3. Run build\_all.bat to build both debug and release projects.
- 4. Go to the debug/release directory to download and run the elf file using gdb.

# 6 Revision History

This table summarizes revisions to this document.

#### **Revision History**

Table 1.	Revision	history
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Revision number	Date	Substantive changes
2	09/2015	Updated tool versions in Section 3.2 and updated Section 5.2.
3	11/2015	Updated Section 1
4	01/2016	Updated Section 1 and Section 3.2

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