Unified measurement software

UMS

Reference manual

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List of devices supported by UMS:

The unified measurement software currently supports the devices listed below. Please keep in mind that the functionality was adapted to our needs so there might be functionalities which are not yet implemented in a specific device.

Keithley measurement devices:

- Keithley 740
- Keithley 2000
- Keithley 2001
- Keithley 2182A
- Keithley 2601B
- Keithley 2602B
- Keithley 2612B
- Keithley 2700
- Keithley 2701
- Keithley 6517B
- Keithley 7001
- Keithley 6220
- Keithley 4200 SCS

Tektronix devices:

- Tektronix AFG2021
- Tektronix AFG3021C

Power supplies:

TTI QL564TP

Impedance bridges:

- Gamry Reference 600
- Zahner IM6
- Solartron 1260

Oven controllers:

- Eurotherm 2404
- Eurotherm 2416
- **Eurotherm 3216**
- Eurotherm 3500
- Eurotherm nanodac

GPIB Adapters:

- Prologix GPIB-USB Adapter
- Prologix GPIB-Ethernet Adapter

Function reference:

General remarks:

- If not stated otherwise, all function arguments are in SI units.
- Arguments, which already have a default value, do not need to be specified if you want to keep them at the default value.
- Before passing the *device* to a function, make sure you initailized it.
- Code examples are set in this particular font

Preforming of memristors

```
preforming ramp(device, start voltage, ramp speed 1, top voltage, hold time, ramp spe
ed 2, end voltage, compliance current=0, new row=False, GUI=True)
```
Return value are the following arrays: [data V I,data V t,data I t]

This function is used to preform memristors before they are cycled.

preforming ramp with current limit(device, start voltage, ramp speed 1, top voltage , hold time, ramp speed 2, end voltage, stop current, new row=False, GUI=True)

Return value are the following arrays: [data V I,data V t,data I t]

This function does basically the same as the above one, but was especially designed for the High resistance meter Keithley 6517B which does not support compliance currents. Therefore we replaced it by a certain "stop_current".

preforming_ramp_with_current_hold_time(device,start_voltage,ramp_speed_1,top_vol tage,hold_time,ramp_speed_2,end_voltage,compliance_current=0,trigger_current=0,t rigger hold time=0,new row=False, GUI=True)

Return value are the following arrays: [data V I,data V t,data I t]

This function does a usual preforming as the *preformin_ramp* function with the additional possibility to add a certain trigger_current after which the function only runs for the amount of time specified in trigger_hold_time and then stops immediately even if the hold_time is set for some longer time.

Cyclic voltammetry

cycling(device,start_voltage,ramp_speed_1,top_voltage,top_hold_time,ramp_speed_2 ,bottom_voltage,bottom_hold_time,end_voltage,n,compliance_current_pos=0,complian ce_current_neg=0,new_row=False, GUI=True)

Return value are the following arrays: $[data_V_I,data_V_t,data_I_t]$

cycling_two_channels(device,start_voltage_1,start_voltage_2,ramp_speed_1_1,ramp_ speed 1 2, top voltage 1, top voltage 2, top hold time 1, top hold time 2, ramp speed _2_1,ramp_speed_2_2,bottom_voltage_1,bottom_voltage_2,bottom_hold_time_1,bottom_ hold time⁻²,end voltage 1,end voltage 2,n 1,n 2,compliance current pos⁻¹⁼⁰,compl iance current pos $2=0$, compliance current neg $1=0$, compliance current neg $2=0$, new row=False,GUI=True)

Return value are the following arrays:

[data V I 1,data V t 1,data I t 1,data V I 2,data V t 2,data I t 2]

Blue is for **Channel A** and Green for **Channel B**

cycling_unipolar(device,start_voltage,ramp_speed_1,set_voltage,set_hold_time,com pliance current,ramp_speed 2, wait before reset time, reset voltage, reset ramp_rat e, reset hold time, n, new row=False, GUI=True)

Return value are the following arrays: [data_V_I,data_V_t,data_I_t]

This function is optimized to test memristors for unipolarity. In normal cycling a compliance current is either applied globally or not at all. It is therefore possible, that unipolar switching behavior can not be asessed

cycling current(device,start,ramp_speed_1,top,top_hold_time,ramp_speed_2,bottom, bottom hold time, end, n, maximum voltage, new row=False, GUI=True)

Return value are the following arrays: $[data_V_I,data_V_t,data_I_t]$

Pulsed experiments

pulse rnone(device smu, device function generator, V peak, const pulse width, time b etween_pulses, num_pulses,new_row=False,GUI=True)

Return value are the following arrays:

[data_V_t_2,data_I_t_2,data_cycle_R_2,data_cycle_post_R_2]

This function just measures the current responce to a series of voltage pulses - there is no reading voltage and the currents starts and ends at zero voltage.


```
pulse_rsquare(device_smu,device_function_generator,V_peak,const_pulse_width,time
_between_pulses, num_pulses,time_at_zero, 
\overline{V} read,alternate=True,new_row=False,GUI=True)
```
Return value are the following arrays:

[data_V_t_2,data_I_t_2,data_cycle_R_2,data_cycle_post_R_2]

This function allows you to measure also the resistance during (depending on the time scale) and between pulses. - that means that there is a square reading scheme between the pulses.

In case you put a negative V_peak voltage into the pulse_rsquare function then the reading voltage becomes automatically also negative. This is due to voltage spikes occurring when changing voltage polarity.

pulse_rbipolar(device_smu,device_function_generator,V_peak,const_pulse_width,tim e between pulses, num pulses, time at zero, V read, alternate=True, new row=False, GUI=True)

Return value are the following arrays:

[data V t 2,data I t 2,data cycle R 2,data cycle post R 2 plus, data cycle post R 2 minus]

This function allows you to measure also the resistance during (depending on the time scale) and between pulses. There is a bipolar pulse reading scheme between the pulses. This is an advantage over a constant reading scheme since the device will not be disturbed. No resistence will be measured during the time at zero. This is just an option to leave the current to equilibrate.

The bipolar read between the pulses ensures that no memristance change occurs during the reading process (a change during a positive reading pulse will be reversed with a negative reading pulse). Is a good choice for sensitive devices or higher reading voltages.

Simple loggers

Those functions are kept very simple for the case one just needs to monitor some measurement without further requirements.

voltage_logger(device,total_measurement_time,bias_current=0,new_row=False, GUI=True)

current logger(device,total measurement time, bias voltage=0,new row=False, GUI=True)

resistance 2w logger(device,total measurement time,new row=False, GUI=True)

Measures resistance with 2-wire setup

resistance_4w_logger(device,total_measurement_time,new_row=False, GUI=True)

Measures resistance with 4-wire setup

temperature logger(device,total measurement time, sensor="K", num of channels=1, ne w row=False, $GUI=True$)

temperature current logger(device temperature, device smu, total measurement time, bias voltage, sensor="K", new row=False, GUI=True)

Oven control programs

sintering(device temperature,device oven, temperature values, ramp rate, stabilizat ion time, sensor="K", GUI=True)

arrhenius dc(device temperature, device smu, device oven, temperature values, ramp_r ates, stabilization times, voltage values, measurement time=60, continuous voltage=T rue,GUI=True)

arrhenius_ac(device_temperature,device_oven,device_impedance,temperature_values, ramp_rates,stabilization_times,number_of_repetitions=1,start_frequency=0.1,end_f requency=1.0e6,ac_amplitude=0.1,bias=0,num_points_per_decade=10,path="/home/elec trochem/lost_data",GUI=True)

There is no return value to this function since the whole data gets already safed to a file specified.

Impedance measurement

impedance(device impedance, start frequency, end frequency, ac amplitude=0.05, bias=0, num points per decade=10, new row=False, GUI=True)

Return value are the following arrays:

[data_Zi_Zr,data_freq_mod,data_bias_ampl_time_range_err_temp]

Mass flow controller

mfc(device mfc, stabilization times, flow rates, GUI=True)

Return value are the following arrays: [data_F_t,data_FP_t]

Pass the following device to this function as an example:

voegtlin $qsc = voeqtlin qsc("/dev/ttyUSB0", [12,3])$

The first argument "/dev/ttyUSB0" is the corresponding USB port on that Linux-machine, and the array [12,3] specifies that the Modbus-Addresses 12 and 3 are used by the devices we want to communicate with.

flow rates example:

You can specify this array in 3 different ways. It can be in the following manner

[[["gastype1" or modbusnumber , set_flow],[...]] , [...]]

for example: [[["Air 5000",1000],["N2 300",50]],[["Air 5000",500],["N2 300",150]]] Assuming you have two stabilization times, this will set Air-flow to 1000 sccm and N2 to 50 sccm in the first step and Air-flow to 500 sccm and N2 to 150 sccm in the second step.

or if only one gas used: **[["gastype1" or modbusnumber , set_flow] , [...]]**

for example: [["Air 5000",1000],["Air 5000",700],["Air 5000",100]] Assuming you have 3 stabilization times, this will set Air-flow to 1000 sccm in the first step to 700 sccm in the second step and finally to 100 in the 3rd step.

or if only one gas and one flow used:

["gastype1" or modbusnumber , set_flow]

for example: ["Air 5000",1000] In this case during all step 1000sccm Air will be used

Galvanostatic cycling

galvanostatic cycling(device smu, current 1, target voltage 1, hold time 1, hold cur rent_1,current_2,target_voltage_2,hold_time_2,hold_current_2,n=1,ocv_measurement _time=0,set_I_zero_after_cycle=False,new_row=False,GUI=True)

Return value are the following arrays: [data 0, data 1, data 2, data 3]

Galvanostatic cycling examples:

You can specify arrays for the purpose of rate capability testing.

galvanostatic_cycling(device_smu,[10e-9,100e-9,10e-9], 4.1,0,0,[-10e-9,-100e-9,- 10e-9], $1.1, 0, 0, n=[10, 5, 10],$ ocv measurement time=60)

this example: will perform 10 cycles at 10 nA of current followed by 5 cycles at 100 nA and then go back to 10 cycles at 10 nA. OCV is measured for 1 minute and the cycling range is between 1.1 Volts and 4.1 Volts.

High precision galvanostatic cycling

This function is intended to be used in combination with a high precision current source such as Keithley 6220 series in order to cycle under most stable low currents. Note that the function is similar to the previous description, but a second device file (the current source) has to be provided in addition. The current source is exclusively dedicated to providing stable ultra-low currents.

galvanostatic_cycling_nano(device_voltmeter,device_current_source,current_1,targ et voltage 1, hold time 1, hold current 1, current 2, target voltage 2, hold time 2, h old current 2 , n=1, ocv measurement time=0, set I zero after cycle=False, new row=Fa $lse, GUI=True)$

Return value are the following arrays: $[data 0, data 1, data 2, data 3]$

Galvanostatic cycling examples:

```
galvanostatic cycling nano(device smu, device current source, 10e-9, 4.2,0,0,-
10e-9, 1.1,0,0,n=100, ocv measurement time=120)
```
this example: will perform 100 cycles at 10 nA of current. OCV is measured for 2 minute and the cycling range is between 1.1 Volts and 4.2 Volts.

You can specify arrays for the purpose of rate capability testing.

```
galvanostatic_cycling_nano(device_smu, device_current_source, [10e-9,100e-9,10e-
9], 4.1,0,0, \left[-10e-9,-100e-9,-10e-9\right], 1.1,0,0, n=[10,5,\overline{1}0],
ocv measurement time=60)
```
this example: will perform 10 cycles at 10 nA of current followed by 5 cycles at 100 nA and then go back to 10 cycles at 10 nA. OCV is measured for 1 minute and the cycling range is between 1.1 Volts and 4.1 Volts.