Team Update O3

General

- **Game Data Details:** The <u>2018 Game Data Details</u> article has been updated with additional information about initial states and to match the game updates below.
- **Drawing Updates:** <u>The Layout and Marking Diagram</u> has been updated with the following changes:
 - FE-00041-02 has been added.
 - FE-00041-03 has been added.
- **3D CAD Models Updates:** Field Graphics have been added to the <u>CAD Models</u> download.

Rules & Expectations for FIRST Robotics Competition Events

No changes.

Game and Season Manual

Section 3.3 SCALE

Figure 3-4: The SCALE (Note, cable protectors are shown, but are not part of the SCALE)



The BRICKS are graphics depicting golden squares surrounded by a black outline that extends 12 in. (~30cm) above the horizontal surface of the PLATFORM.





Section 3.3.5 PLATFORM

Located at the base of the SCALE, on each side, is a PLATFORM covered with ALLIANCE colored HDPE. The TOWER and OUTRIGGERS separate one PLATFORM from the other. Each PLATFORM top is 8 ft. 8 in. (~264 cm) wide by 3 ft. 5 ¼ in. (~105 cm) deep and 3 ½ in. (~9 cm) tall. The ramps leading to the PLATFORM includes ramps with a are 1 ft. 4 ¾ in. (~33 32 cm) run and long with a 15.35 deg. angle. The ALLIANCE colored tape that abuts the PLATFORM ramps is part of the PLATFORM.



Figure 3-11: PLATFORM top length and width dimensions

Section 3.9 Vision Targets

Vision targets are located on the SWITCH FENCE facing the ALLIANCE WALL using 2 in. (~5 cm) strips of 3M 8830 Scotchlite Reflective Material and are used to highlight the locations of the PLATES on the SWITCH.

Section 3.10 The FIELD Management System

FMS alerts participants to milestones in the MATCH using audio cues. Please note that audio cues are intended to be a courtesy to participants and not intended as official MATCH markers. If there is a discrepancy between an audio cue and the FIELD timers, the FIELD timers are the authority.

- MATCH Start: "Cavalry Charge"
- T=0 for AUTO: Buzzer
- Start of TELEOP: Three (3) Bells
- T-30 seconds in TELEOP: Train Whistle
- T=0 for TELEOP/MATCH end: Buzzer
- MATCH stopped: Foghorn
- POWER UP activated: "Linear Popping"

Section 4.1.1 Stages

Each MATCH is divided in to two stages. The first stage, called Autonomous (AUTO), is the first fifteen (0:15) seconds of a MATCH in which ROBOTS operate without any DRIVE TEAM control or input. Prior to the start of AUTO, the assignments of ALLIANCE colors for SWITCH and SCALE





PLATES are randomized among the four states in Figure 4-1 and transmitted to the OPERATOR CONSOLE by the Field Management System (FMS). During AUTO, ROBOTS attempt to deliver preloaded POWER CUBES to PLATES, retrieve additional POWER CUBES from around the FIELD, and cross their AUTO LINE any time before the end of the stage.



Figure 4-1 Possible PLATE assignments

Section 4.6 Logistics

There will not be an ARCADE FAULT called for MATCHES that accidentally begin with an incorrect number of, incorrectly positioned, or damaged POWER CUBES. Damaged POWER CUBES will not be replaced until the next FIELD reset period. DRIVE TEAMS should alert the FIELD STAFF to any missing or damaged POWER CUBES prior to the start of the MATCH.

Section 7.1 Before the MATCH

G04. Leave the POWER CUBES alone. Prior to the start of the MATCH, DRIVE TEAMS may not rearrange the POWER CUBES within a PORTAL, staged on the FIELD (that are not staged inside a ROBOT), or transfer POWER CUBES from one PORTAL to another.

Violation: MATCH will not start until the situation is corrected.

Section 8.4 Budget Constraints & Fabrication Schedule

R22. At an each Event, Teams may have access to a WITHHOLDING ALLOWANCE.





Section 8.5 BUMPER Rules

R28.

A. consist of Arabic numerals at least 4 in. (~11 cm) high, at least ½ in. (~12.7 mm) in stroke width, and be either white in color or outlined in white with a minimum 1/16 in. (~1.6mm) outline

Section 8.8 Control, Command & Signals System

R65. The roboRIO Ethernet port must be connected to the Wireless Bridge port labeled "18-24 vPOE," closest to the power connector (either directly, via a network switch, or via a CAT5 Ethernet pigtail).

Section 8.9 Pneumatic System

R83. The only pneumatic system items permitted on ROBOTS include the items listed below.

E. Solenoid valves with a maximum ¹/₆ in. (nominal, ~6 mm) NPT, BSPP, or BSPT port diameter,

R89. Only the compressor, relief valve (P/N: 16-004-011 or 16-004-003), pressure switch, pressure vent plug, pressure gauge, storage tanks, tubing, pressure transducers, and connecting fittings may be in the high-pressure pneumatic circuit upstream from the regulator.

Section 10.8 MATCH Replays

Over the course of the Tournament it may be necessary for a MATCH to be replayed. Typical causes for replays are MATCHES that end in a tie during the Playoffs or if there is an ARCADE FAULT. An ARCADE FAULT is an error in ARCADE operation that includes, but is not limited to:

- A. broken FIELD elements due to
 - i. normal, expected game play or
 - ii. ROBOT abuse of FIELD elements that affects the outcome of the MATCH for their opponents.

A broken FIELD element caused by ROBOT abuse that affects the outcome of the MATCH for their ALLIANCE is not an ARCADE FAULT.

- **B.** power failure to a portion of the FIELD (tripping the circuit breaker in the PLAYER STATION is not considered a power failure)
- C. improper activation by the FMS
- **D.** errors by FIELD staff (except those listed in Section 4.6)







Team Update O2

General

- Drawing Updates: The <u>Field Drawings FIRST POWER UP specific</u> drawing package has been updated with the following changes:
 - GE-18020 has been updated to include a missing overall length dimension.
 - GE-18060 has been updated to fix a note with an incorrect item number called out.
 - GE-18126 has been updated to fix a note with an incorrect item number called out.
 - GE-18127 has been added. Please note the height of GE-18127 supplied by SolidWorks, Autodesk, and PTC is slightly taller than what is specified in <u>Section 3.6.2 EXCHANGE</u>. We will be working with them to get those models updated.

The <u>Team Drawings</u> drawing package has been updated with the following changes:

- TE-18008 has been updated to fix BOM item number and part number agreement.
- TE-18007 has been updated to fix BOM item number and part number agreement, and to include changes to the following parts:
- TE-18007-3 has been updated to correct overall length of part.
- TE-18007-4 has been updated to correct overall length of part.
- TE-18007-10 has been updated to correct overall length of part.
- TE-18007-11 Has been updated to correct overall length of part.

The revisions to the Scale in the Team Drawings correct design mistakes that resulted in differences between the team version of the Scale and the official Scale. The width of the Rung is 1 ft. 1 in. (down from 1 ft. 2 in.), the width of the Tower is 1 ft. 5 in. (down from 1 ft. 6 in.), and the distance from the Rung to the face of the Tower is 8¼ in. (up from 6¼ in.)

While we try to ensure that critical dimensions in the wooden versions of Field elements match their official counterparts, there are always discrepancies caused from using different building materials. However, the discrepancies referenced above were due to design error and may impact Robot design. We apologize, especially if these corrections affect your Robot designs.

- **360° Images:** A link to 360° images of the *FIRST* POWER UP field taken during Field Tour filming is included on the <u>Game and Season webpage</u>.
- **3D CAD Models:** A link to *FIRST* POWER UP DS SolidWorks models is now included on the <u>Game and Season webpage</u>.
- **FIRST POWER UP Field images:** A link to field images taken during Field Tour filming is now included on the <u>Game and Season webpage</u>.
- Crate Construction: Think you'll be shipping your Robot? The crate specifications are now posted <u>here</u>.

Rules & Expectations for FIRST Robotics Competition Events

No changes.

Game and Season Manual

Section 3.6.3

Caution, there are may be orientations where all three (3) POWER CUBES will not fit in a VAULT column, but if HUMAN PLAYERS place POWER CUBES logo side up they'll fit with room to spare.



Section 3.8 POWER CUBES

Each POWER CUBE weighs 3 1/2 lbs (~1.6 kg) approximately 3 1/2 lbs (~1.5 kg). POWER CUBES may be purchased from AndyMark (am-3818 and am-3741), Innovation First (217-6188 and 217-6193), and Rev Robotics (REV-21-1217 and REV-21-1218).

Section 4.2 Scoring

Points are earned for establishing OWNERSHIP, with additional points earned for each additional second of OWNERSHIP. For example, a team that establishes OWNERSHIP of their SWITCH three (3) seconds after the start of AUTO and maintains OWNERSHIP for five (5) seconds earns two (2) points + ten (10) points, for a total of twelve (12) points.

The MATCH points listed in Table 4-1 for OWNERSHIP during the TELEOP stage are increased if the BOOST POWER UP is played. See Section 4.3 for details on BOOST.

AUTO-RUN and CLIMBING are both evaluated and scored by human REFEREES. Teams are encouraged to make these actions obvious and unambiguous.

Section 4.3 POWER UPS

An ALLIANCE plays a POWER UP by pressing the corresponding button on the VAULT. Only one (1) instance of the FORCE or BOOST POWER UP can be active at a time. If an ALLIANCE pushes the button for FORCE/BOOST while their other FORCE/BOOST is active, the button press is ignored. The LEVITATE POWER UP can be played at any time during the TELEOP stage.

Section 7.6 Human Action Bules

H07.

- A. the OPERATOR CONSOLE,
- B. non-powered signaling devices,
- C. reasonable decorative items,
- **D.** special clothing and/or equipment required due to a disability,
- E. devices used solely for planning or tracking strategy,
- F. devices used solely to record gameplay,
- G. non-powered Personal Protective Equipment (examples include, but aren't limited to, gloves, eye protection, and hearing protection)

Items brought to the ARCADE under allowances B-G must meet all of the following conditions:

- i. . do not connect or attach to the OPERATOR CONSOLE
- ii. do not connect or attach to the FIELD or ARCADE
- do not connect or attach to another ALLIANCE member (other than items in iii. category G)
- do not communicate with anything or anyone outside of the ARCADE. iv.
- do not communicate with the TECHNICIAN V.
- vi. do not include any form of enabled wireless electronic communication (e.g. radios, walkie-talkies, cell phones, Bluetooth communications, Wi-Fi, etc.)



- vii. do not in any way affect the outcome of a MATCH, other than by allowing the DRIVE TEAM to
 - a. plan or track strategy for the purposes of communication of that strategy to other ALLIANCE members or
 - b. use items allowed per part B to communicate with the ROBOT (provided A02 is not violated).

Section 8.3 ROBOT Safety & Damage Prevention

R07.

If the ROBOT includes protrusions that form the "leading edge" of the ROBOT as it drives and the protrusions have a surface area of less than 1 in.² (~6 cm²), it will invite detailed Inspection. For example, forklifts, lifting arms, or grapplers may be carefully inspected for these hazards.

Section 8.5 BUMPER Rules

A note about the edit to R24: The original BUMPER ZONE did not leave any tolerance for noodle alignment, wood alignment, fabric folds, etc., if using the BUMPER brackets that shipped with the Drive Base Kit.

R24. BUMPERS must be located entirely within the BUMPER ZONE, which is the volume contained between the floor and a virtual horizontal plane $\frac{7 \text{ in.}}{17 \text{ cm}}$ $\frac{71}{2} \text{ in.}$ (~19 cm) above the floor in reference to the ROBOT standing normally on a flat floor. BUMPERS do not have to be parallel to the floor.

Section 8.9 Pneumatic System

R81.

Any pressure specification such as "working," "operating," "proof," "maximum," "burst," etc. may be used to satisfy the requirements of R81.

It is recommended that all pneumatic items be rated by their manufacturers for a working pressure of at least 60 psi (~414 kPa).







Team Update 01

General

Drawing Packages

The <u>Field Drawings – FIRST POWER UP specific</u> drawing package has been updated with the following changes:

- GE-18130 has been added
- GE-18101 and GE18025 have been updated to include GE-18130

Kickoff Kit Checklist: Black Tote



Safety Manual

Section 3.5.5 Charging and Handling

 Do not short out the battery terminals. If metal tools/parts contact the terminals simultaneously, it will create a direct short circuit. This may cause high heat to develop in the battery terminal/part/tool area and the battery could explode. To avoid the possibility of shorting out the battery terminals and creating a hazardous situation it is required to cover all exposed battery terminals and connections with appropriate non-insulating material such as electrical tape or tubing.

It surprises us that we feel the need to say this, please don't put the POWER CUBE cover on anyone's head and zip it closed; also, don't eat it.

Rules & Expectations for FIRST Robotics Competition Events

No changes.

Game and Season Manual

Section 1.8 Question and Answer System

The Q&A is not a resource for

- rulings on hypothetical strategies or vague situations,
- challenging decisions made at past events, or
- a-design reviews of a ROBOT system for legality.

The responses in the Q&A do not supersede the text in the manual, although every effort will be made to eliminate inconsistencies between the two. While responses provided in the Q&A may be used to aid discussion at each event, per Section 10.6 REFEREE Interaction and Section 9 Inspection & Eligibility Rules, REFEREES and Inspectors are the ultimate authority on rules. If you have concerns about enforcement trends by volunteer authorities, please notify *FIRST* at firstroboticscompetition@firstinspires.org.



Weak questions are overly broad, vague, and/or include no rule references. Some examples of questions that will not be answered in the Q&A are:

- Is this part/design legal?
- How would should the a REFEREE have ruled if when this specific, hypothetical game play happened?

Good questions ask generically about features of parts or designs, gameplay scenarios, or rules, and often reference one or more relevant rules within the question. Some examples of questions that will likely be answered in the Q&A are:

- A device we are considering using on the robot comes with purple AWG 40 wire, does this comply with R?? and R??
- We're not sure how to interpret how Rule G?? applies if Blue Robot A does X and Red Robot B does Y, can you please clarify?

Section 3.1 Zones and Marking

STARTING LINE: a line of 2 in. (~5 cm), white gaffers tape that runs the width of the carpet and is 2 ft. 6 in. (~76 cm) behind the ALLIANCE WALL diamond plate, which includes the tape.

Section 3.3 SCALE

A cable protector extends from the center of each side of the PLATFORM and is 2 ½ in. (~6 cm) wide and ¾ in. (~2 cm) high (Electriduct, Inc. CSX-3, black). The cable protector is attached to the field with hook fastener, increasing the height to approximately ½ in. (~2 cm). These cable protectors extend to the GUARDRAILS and the SWITCHES.

Section 3.4.1 SWITCH PLATES

The PLATES are 9 in. (~23 cm) above the carpet when the SWITCH is level. Like the SCALE, the SWITCH tilts and rests in different positions based on the placement of POWER CUBES. During the MATCH, the SWITCH is in one of three (3) two (2) states based on the magnitude of its tilt:

- 1. OWNERSHIP by the Red its ALLIANCE, or
- 2. OWNERSHIP by the Blue ALLIANCE, or
- 3. neither ALLIANCE has OWNERSHIP

If the outside edge of an ALLIANCE'S colored PLATE is positioned between 3 in. (~8 cm) and 6 in. (~15 cm) above the FIELD carpet then the ALLIANCE has OWNERSHIP of the its SWITCH. If the outside edge of an ALLIANCE colored PLATE is positioned between $\frac{12 \text{ in}}{-30 \text{ cm}} \frac{6 \text{ in}}{6 \text{ in}} \frac{-15 \text{ cm}}{15 \text{ cm}}$ and 15 in. (~38 cm) above the FIELD carpet then the opposing ALLIANCE has OWNERSHIP. When neither ALLIANCE has OWNERSHIP of the SWITCH, the outside edges of the PLATES are between 6 in (~15 cm) and 12 in. (~30 cm) above the FIELD carpet. See Figure 3-15. The time required to move between states is dependent on the weight difference and the distribution of the weight on the SWITCH PLATES. Details on OWNERSHIP can be found in Section 4.2 Scoring.

Section 3.5 PLATE Lighting

Table 3-1	PLATE	Lighting
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Color	Pre- MATCH	AUTO	TELEOP	Post- MATCH
Blue (pulsing) with solid red corners	N/A	Blue FORCE POWER UP i s active <mark>N/A</mark>	Blue FORCE POWER UP is active	N/A





Red (pulsing)	N/A	Red OWNERSHIP or FORCE POWER UP is active	Red OWNERSHIP or FORCE POWER UP is active	N/A
Red (pulsing) with solid blue corners	N/A	Red FORCE POWER UP is active N/A	Red FORCE POWER UP is active	N/A

Section 3.8 POWER CUBE

POWER CUBES may be purchased from AndyMark (am-3818 and am-3741), Innovation First (217-6188 and 217-6193), and Rev Robotics (REV-21-1217 and REV-21-1218). Please note that due to the use of recycled material in the manufacturing process, the batches of crates will vary slightly in color, but not such that it's perceptible with the cover in place.

Section 4.1.2 MATCH Setup

Prior to the start of each MATCH, POWER CUBES, elements used to affect the position of the SCALE and SWITCHES and earn POWER UPS, are staged as shown in Figure 4-1. Staging details are as follows:

- A. Seven (7) in each PORTAL (on the carpet between the PORTAL wall and the STARTING LINE), minus any preloaded POWER CUBES,
- **B.** Six (6) next to each SWITCH. They are arranged approximately equidistant from each other along the face of the FENCE closest to the SCALE, *FIRST* logo facing up
- C. Ten (10) located in each ALLIANCE POWER CUBE PILE (in a pyramid formation, with six on the bottom, three in the middle, and one on top, justified toward the SWITCH, *FIRST* logo facing up)

Section 4.2: Scoring

The primary method of earning points in *FIRST*[®] POWER UPSM is by placing POWER CUBES on the PLATES of the SWITCH or SCALE to establish OWNERSHIP. OWNERSHIP is a state of the ALLIANCE'S SWITCH or SCALE where it is tilted in favor of an ALLIANCE colored PLATE, such that the outside edge of the ALLIANCE colored PLATE is at or less than a specified height above the carpet. ALLIANCES earn points when OWNERSHIP is established and additional points for each additional second of OWNERSHIP.

• • •

An ALLIANCE has OWNERSHIP of their SWITCH when:

- A. the SWITCH is tilted in favor of their ALLIANCE colored PLATE, such that the outside edge of the ALLIANCE colored PLATE is at or less than 6 in. (~15 cm) from the floor for at least one (1) second, or
- **B.** they have played the FORCE POWER UP at level 1 or 3 (see Section 4.3 POWER UPS)

The Blue ALLIANCE'S SWITCH accumulates points for the Blue ALLIANCE when the PLATE illuminated and pulsing with blue lights is down.

The SWITCH does not accumulate points for either ALLIANCE when the blue PLATE is above 6 in (~15 cm).

An ALLIANCE has OWNERSHIP of the SCALE when:





- A. the SCALE is tilted in favor of their ALLIANCE colored PLATE, such that the outside edge of the ALLIANCE'S colored PLATE is at or lower than 4 ft. 8 in. (~142 cm) from the floor for at least one (1) second and there isn't an active opponent's Level 2 or 3 FORCE, or
- **B.** they have played the FORCE POWER UP at level 2 or 3 (see Section 4.3 POWER UPS)

Note that points for the SWITCH and SCALE are accrued over time and not a direct function of the number of POWER CUBES placed on the SWITCH or SCALE.

Points are not taken away when OWNERSHIP changes, but rather stop accumulating (if balanced) or start accumulating for the opposite ALLIANCE if they take OWNERSHIP of the SCALE.

Note from the FRC Director on the edits to Table 4-1:

You will see we added a requirement in Table 4-1 requiring a ROBOT to not be in direct contact with their PLATFORM to be considered CLIMBING. We believe this was already a requirement, given our BUMPER rules, but adding the requirement in Table 4-1 was the most straightforward way of making this clear.

Action	Criteria	MATCH Points		Ranking
		AUTO	TELEOP	Points
CLIMBING	For each ROBOT fully supported by the SCALE (either directly or transitively) with BUMPERS fully above the BRICKS at T=0, not in direct contact with their PLATFORM, and not at all in the opponent's PLATFORM ZONE	-	30	-

Table 4-1: FIRST® POWER UPSM rewards

Section 4.3: POWER UPS

Note from the FRC Director on the edits to Table 4-2:

These changes are an attempt to clarify how BOOST works. They do not significantly change the points being earned under BOOST.





Table 4-2: POWER UPS

Name	# of POWER CUBES	Effect	Duration (seconds)
LEVITATE	3	An additional CLIMBING ROBOT, up to a maximum of three (3) ROBOTS, is credited to the ALLIANCE at the end of the MATCH	N/A
FORCE	1	ALLIANCE earns OWNERSHIP points from their SWITCH regardless of PLATE position	10
	2	ALLIANCE earns OWNERSHIP points from the SCALE regardless of PLATE position	10
	3	ALLIANCE earns OWNERSHIP points from the SWITCH and the SCALE regardless of PLATE position	10
BOOST	1	Increases the points for OWNERSHIP of the ALLIANCE'S SWITCH from one (1) point per second to two (2) points per second Doubles the points being earned by the ALLIANCE for OWNERSHIP of their SWITCH.	10
	2	Increases the points for OWNERSHIP of the SCALE from one (1) point per second to two (2) points per second Doubles the points being earned by the ALLIANCE for OWNERSHIP of the SCALE.	10
	3	Increases the points for OWNERSHIP of both the ALLIANCE'S SWITCH and the SCALE from one (1) point per second to two (2) points per second Doubles the points earned by the ALLIANCE for OWNERSHIP of a) their SWITCH and b) the SCALE.	10

Section 8.3 ROBOT Safety & Damage Prevention

R07. Protrusions from the ROBOT and exposed surfaces on the ROBOT shall not pose hazards to the ARCADE elements (including the **POWER CUBES** GAME PIECES) or people.

If the ROBOT includes protrusions that form the "leading edge" of the ROBOT as it drives and have a surface area of less than 1 in.² (~6 cm²), it will invite detailed Inspection. For example, forklifts, lifting arms, or grapplers may be carefully inspected for these hazards.-

Section 8.6 Motors & Actuators

R33.

For servos, note that the roboRIO is limited to a max current output of 2.2A on the 6V rail (12.4W of electrical input power). Teams should make sure that their total servo power usage remains below this limit at all times.

This is the total number of each motor a Team may use on their ROBOT, not the quantity per part number. For example, each team may use up to six (6) CIM motors on their ROBOT, regardless of the quantity or combination of each individual part number used.

Given the extensive amount of motors allowed on the ROBOT, Teams are encouraged to consider the total power available from the ROBOT



battery during the design and build of the ROBOT. Drawing large amounts of current from many motors at the same time could lead to drops in ROBOT battery voltage that may result in tripping the main breaker or trigger the brownout protection of the roboRIO. For more information about the roboRIO brownout protection and measuring current draw using the PDP, see <u>roboRIO Brownout and Understanding</u> <u>Current Draw</u>.

R34.

F. The wiring harness of the Nidec Dynamo BLDC Motor may be modified as documented by *FIRST* in the "Nidec Dynamo BLDC Motor with Controller" <u>Screensteps article</u>.

Section 10.12 Advancement Between Tournaments

T17.

A *FIRST*[®] Robotics Competition Team listed in the <u>Championship</u> <u>Eligibility Criteria document</u> is pre-qualified for the *FIRST* Championship if the Team meets one of the following criteria:

- A. member of the FIRST® Hall of Fame
- **B.** an original and sustaining team since 1992
- C. a 2017 FIRST Championship winner
- D. a 2017 FIRST Championship Engineering Inspiration Award winner
- E. a 2017 FIRST Championship Chairman's Award Finalist

Section 11: GLOSSARY

Section 11: Glossary has been updated to include entries for ACTIVE DEVICE, CAW, FENCE, LRI, RSL, SCALE, SIGNAL LEVEL, SWITCH, and VENDOR.





