EMERSON™
Industrial Automation

Unimotor hd

Product Data

High dynamic AC brushless servo motor
for Control Techniques drives
055 to 190 Frames
0.72 Nm to 85.0 Nm
(255.0 Nm peak)

CONTROL TECHNIQUES

EMERSON
Industrial Automation

Compact servo motor for demanding applications

Unimotor is Control Techniques' high dynamic brushless AC servo motor range, designed for operation with Digitax ST, Unidrive SP, Unidrive M and Epsilon EP drives. Unimotor provides an exceptionally compact, low inertia solution for applications where very high torque is required during rapid acceleration and deceleration profiles. The Unimotor torque profile is matched to Digitax ST servo drives, providing up to 300% peak overload for maximum dynamic performance.

Engineering excellence, innovation and reliability

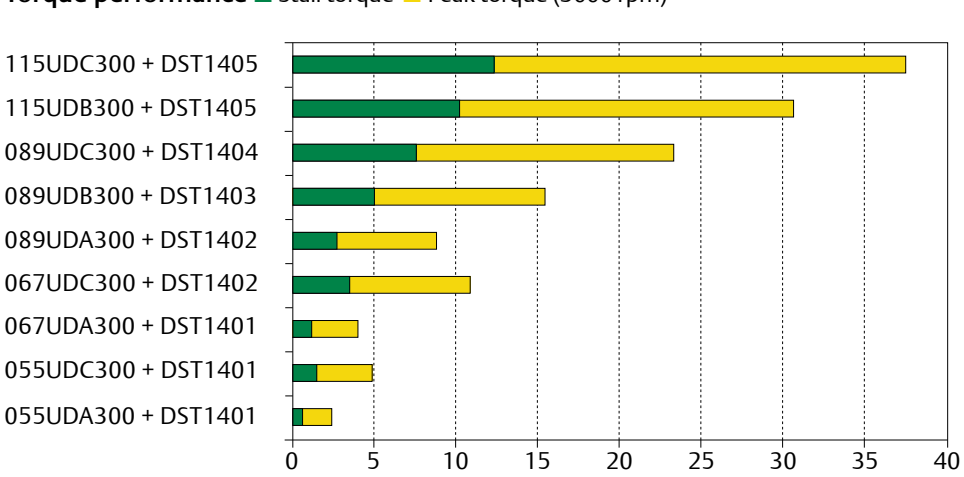
Unimotor has been developed by a dedicated team using our design process that prioritises product innovation, performance and reliability. This enables new ideas to be quickly evaluated, prototyped and tested using a suite of in-house development and modelling software tools. As a result Unimotor incorporates a number of unique performance enhancing design features with several patents pending. Unimotor "raises the bar" in terms of both performance and quality.

Key features

Unimotor is suitable for a wide range of industrial applications, due to its extensive features.

- Torque range: 0.72Nm to 85.0Nm
- High torque to inertia ratio for high dynamic performance
- Compact but powerful
- High energy dissipation brakes
- IP65 conformance: sealed against water spray and dust when mounted and connected
- Segmented stator design
- World class performance
- Supported by rigorous testing for performance and reliability
- Winding to suit 400V and 220V
- Rated speeds include 2000rpm, 3000rpm, 4000rpm and 6000rpm
- Larger shafts to increase torsional rigidity

Torque performance



Conformance and standards

FM 30610

RoHS Compliant

The ultimate motor and drive combinations

Control Techniques drive and motor combinations provide an optimised system in terms of ratings, performance, cost and ease of use. Unimotor motors fitted with high resolution SinCos or Absolute encoders are pre-loaded with the motor "electronic nameplate" data during the manufacturing process. This data can be read by Control Techniques' servo drives and used to automatically optimise the drive settings. This feature simplifies commissioning and maintenance, ensures consistent performance and saves time.

For further information on Control Techniques servo drives, please refer to the Digitax ST, Unidrive SP and Unidrive M brochures.

Accuracy and resolution to suit your application requirements

Choosing the right feedback device for your application is critical in getting optimum performance. Unimotor has a range of feedback options that offer different levels of accuracy and resolution to suit most applications:

- Resolver: robust for extreme applications and conditions - low accuracy, medium resolution
- Incremental encoder: high accuracy, medium resolution
- Inductive Absolute: medium accuracy, medium resolution, single turn and multi-turn
- Optical SinCos/Absolute: high accuracy, high resolution, single turn and multi-turn
- Hiperface (SICK) and EnDAT (Heidenhain) protocols supported

Quick reference table

Frame size	PCD (mm)	Unimotor											Page No.
055	63	0.72 1.65 0.14 0.36											5
067	75		1.45 3.70 0.30 0.75										6
089	100			3.20 8.00 0.87 2.34									7
115	130				5.80 18.80 2.42 8.38								8
142	165									25.0 38.0 17.0 27.2			9
190	230											52.0 85.0 54.6 103.5	10
Stall	0	0.5	1.0	3.0	5.0	8.0	10.0	15.0	20.0	30	60	85.0	(Nm)
Inertia	0	0.1	0.2	0.7	1.5	2.5	6.5	8.0	9.0	20.0	60.0	103.5	(kgcm²)

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Unimotor ordering code Information

Use the information below in the illustration to create an order code for a Unimotor .
The details in the band are an example of an order reference.

089	UD	B	30	5	B	A	CA		A
Frame size	Motor voltage	Stator length	Rated speed*	Brake	Connection type	Output shaft	Feedback device		Inertia
		055 - 089 Frame	055 Frame	055 Frame			055 - 067 Frame		
055	ED = 220V	A	30 = 3000 rpm	0 = Not fitted	B = Power and Signal 90° rotatable	A = Round with key	AR = Resolver		A = Standard
067	UD = 480V	B	60 = 6000 rpm	1 = Parking brake			CR = Incremental Encoder (Renco)	4096 ppr (R35i)	E = Standard + Lifting Brackets
089		C	089 Frame			B = Round Plain shaft	EM = Inductive Absolute Multi turn	EQI 1130	
115		115 Frame	30 = 3000 rpm	X = Special	J = Power size 1.5 and Signal 90° rotatable on 142		FM = Inductive Absolute Single turn	ECI 1118	
142		D	40 = 4000 rpm	067 - 190 Frame			LM = Inductive Absolute Multi turn (Serial comms only)	EQI 1130	
190		142 Frame	60 = 6000 rpm	0 = Not fitted			NM = Inductive Absolute Single turn (Serial comms only)	ECI 1118	
		C	115 Frame	5 = High energy dissipation Parking brake		F = Full key and half key supplied separately	TL = Optical Sincos Multi turn	SKM 36	
		D	20 = 2000 rpm				UL = Optical Sincos Single turn	SKS 36	
		E	30 = 3000 rpm				XX = Special		
		190 Frame	142 Frame	X = Special		X = Special	089 Frame		
		C	10 = 1000 rpm				AE = Resolver		
		D	15 = 1500 rpm				CA = Incremental Encoder (SICK)	4096 ppr (CFS50)	
		F	20 = 2000 rpm				EB = Optical Absolute Multi turn	EQN 1325	
			30 = 3000 rpm				FB = Optical Absolute Single turn	ECN 1313	
			190 Frame				EC = Inductive Absolute Multi turn	EQI 1331	
			10 = 1000 rpm				FC = Inductive Absolute Single turn	ECI 1319	
			15 = 1500 rpm				LC = Inductive Absolute Multi turn (Serial comms only)	EQI 1331	
			20 = 2000 rpm				NC = Inductive Absolute Single turn (Serial comms only)	ECI 1319	
							RA = Optical Sincos Multi turn	SRM 50 (GEN 2)	
							SA = Optical Sincos Single turn	SRS 50 (GEN 2)	
							XX = Special		
							115 - 190 Frame		
							AE = Resolver		
							CA = Incremental Encoder (SICK)	4096 ppr (CFS50)	
							EB = Optical Absolute Multi turn	EQN 1325	
							FB = Optical Absolute Single turn	ECN 1313	
							EC = Inductive Absolute Multi turn	EQI 1331	
							FC = Inductive Absolute Single turn	ECI 1319	
							LC = Inductive Absolute Multi turn (Serial comms only)	EQI 1331	
							NC = Inductive Absolute Single turn (Serial comms only)	ECI 1319	
							RA = Optical Sincos Multi turn	SRM 50 (GEN 2)	
							SA = Optical Sincos Single turn	SRM 50 (GEN 2)	
							XX = Special		

* Not all rated speeds are available on all frame lengths

Frame size 055 For 3 Phase VPWM drives

Motor frame size (mm)		055ED			055UD		
Voltage (Vrms)		200-240			380-480		
Frame length		A	B	C	A	B	C
Continuous Stall Torque (Nm)		0.72	1.18	1.65	0.72	1.18	1.65
Peak Torque (Nm)		2.88	4.72	6.60	2.88	4.72	6.60
Inertia (kgcm²)		0.14	0.25	0.36	0.14	0.25	0.36
Winding thermal time constant (s)		34.0	38.0	42.0	34.0	38.0	42.0
Motor weight unbraked (kg)		1.20	1.50	1.80	1.20	1.50	1.80
Motor weight braked (kg)		1.60	1.90	2.20	1.6	1.90	2.20
Number of poles		8	8	8	8	8	8
Speed 3000 (rpm)	Kt (Nm/A) =	0.74	0.87	0.91	0.74	1.49	1.65
	Ke (V/krpm) =	45.00	52.50	55.00	45.00	90.00	100.00
Rated torque (Nm)		0.70	1.05	1.48	0.70	1.05	1.48
Stall current (A)		0.97	1.36	1.81	0.97	0.79	1.00
Rated power (kW)		0.22	0.33	0.46	0.22	0.33	0.46
R (ph-ph) (Ω)		28.00	14.12	9.53	28.00	45.00	31.00
L (ph-ph) (mH)		50.00	32.00	23.00	50.00	100.00	75.00
Speed 6000 (rpm)	Kt (Nm/A) =	0.45	0.43	0.48	0.74	0.79	0.83
	Ke (V/krpm) =	27.00	26.00	29.00	45.00	47.50	50.00
Rated torque (Nm)		0.68	0.90	1.20	0.68	0.90	1.20
Stall current (A)		1.61	2.74	3.44	0.97	1.49	1.99
Rated power (kW)		0.43	0.57	0.75	0.43	0.57	0.75
R (ph-ph) (Ω)		8.50	3.55	2.38	28.00	10.70	7.80
L (ph-ph) (mH)		16.00	8.20	6.30	50.00	25.00	20.00

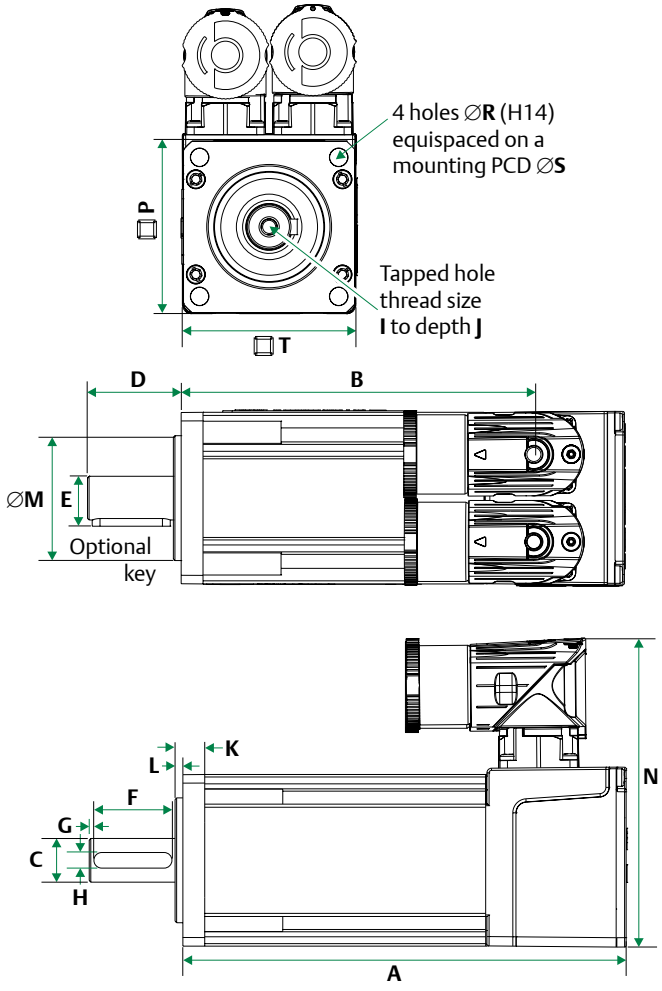
Δt= 100°C winding 40°C maximum ambient

All data subject to +/-10% tolerance

Stall torque, rated torque and power relate to maximum continuous operation tested in a 20°C ambient at 12kHz drive switching frequency

All other figures relate to a 20°C motor temperature.

Maximum intermittent winding temperature is 140°C



Motor dimension (mm)

Drawing number: GM496400

	Feedback AR, CR, EM/FM				Flange thickness	Register length	Register diameter	Overall height	Flange square	Fixing hole diameter	Fixing hole PCD	Motor housing	Mounting bolts
	Unbraked length		Braked length										
	A	B	A	B	K	L	M (j6)	N	P	R (H14)	S	T	
055A	118.0	90.0	158.0	130.0									
055B	142.0	114.0	182.0	154.0	7.0	2.5	40.0	99.0	55.0	5.8	63.0	55.0	M5
055C	166.0	138.0	206.0	178.0									

Shaft dimensions (mm)

	Shaft diameter	Shaft length	Key height	Key length	Key to shaft end	Key width	Tapped hole thread size	Tapped hole depth
	C (j6)	D	E	F	G	H (h9)	I	J
14.0 Std	14	30.0	16.0	25.0	1.5	5.0	M5	12.5

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Frame size 067 For 3 Phase VPWM drives

Motor frame size (mm)		067ED			067UD		
Voltage (Vrms)		200-240			380-480		
Frame length		A	B	C	A	B	C
Continuous Stall Torque (Nm)		1.45	2.55	3.70	1.45	2.55	3.70
Peak Torque (Nm)		4.35	7.65	11.10	4.35	7.65	11.10
Inertia (kgcm²)		0.30	0.53	0.75	0.30	0.53	0.75
Winding thermal time constant (s)		54	61	65	54	61	65
Motor weight unbraked (kg)		2.00	2.60	3.20	2.00	2.60	3.20
Motor weight braked (kg)		2.70	3.3	3.90	2.70	3.3	3.90
Number of poles		10	10	10	10	10	10
Speed 3000 (rpm)	Kt (Nm/A) =	0.93			0.80	1.60	1.60
	Ke (V/krpm) =	57.00			49.00	98.00	98.00
Rated torque (Nm)		1.40	2.45	3.50	1.40	2.45	3.50
Stall current (A)		1.56	2.74	3.98	1.81	1.59	2.31
Rated power (kW)		0.44	0.77	1.10	0.44	0.77	1.10
R (ph-ph) (Ω)		14.92	4.88	3.33	11.69	15.20	13.04
L (ph-ph) (mH)		45.43	17.40	12.70	35.18	54.20	48.65
Speed 6000 (rpm)	Kt (Nm/A) =	0.47			0.8		
	Ke (V/krpm) =	28.50			49.00		
Rated torque (Nm)		1.30	2.20		1.30	2.20	3.10
Stall current (A)		3.12	5.48		1.81	3.19	4.63
Rated power (kW)		0.82	1.38		0.82	1.38	1.95
R (ph-ph) (Ω)		3.86	1.22		11.69	3.79	2.68
L (ph-ph) (mH)		11.06	4.35		35.18	13.60	10.20

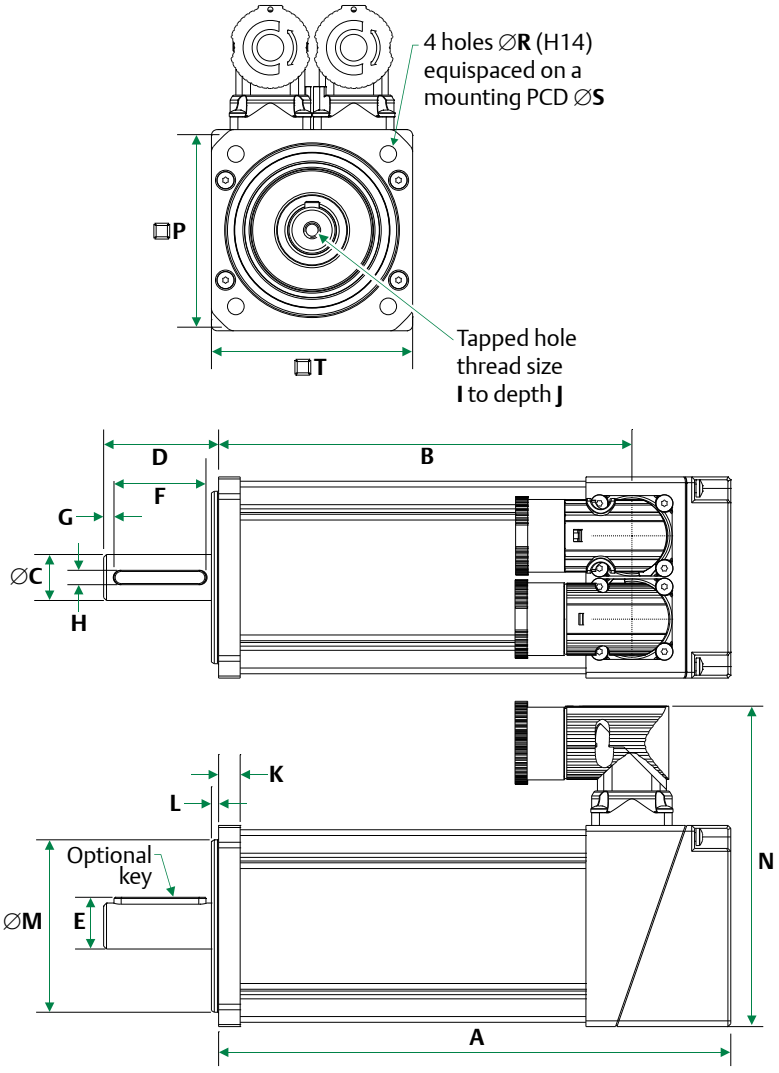
Δt= 100°C winding 40°C maximum ambient

All data subject to +/-10% tolerance

Stall torque, rated torque and power relate to maximum continuous operation tested in a 20°C ambient at 12kHz drive switching frequency

All other figures relate to a 20°C motor temperature.

Maximum intermittent winding temperature is 140°C



Motor dimension (mm)

Drawingnumber:IM/0694/GA

	Feedback AR, CR, EM/FM, LM/NM				Flange thickness	Register length	Register diameter	Overall height	Flange square	Fixing hole diameter	Fixing hole PCD	Motor housing	Mounting bolts
	Unbraked length		Braked length										
	A (± 0.9)	B (± 1.0)	A (± 0.9)	B (± 1.0)	K (± 0.5)	L (± 0.1)	M (j6)	N (± 0.3)	P (± 0.3)	R (H14)	S (± 0.4)	T (± 0.4)	
067A	142.9	109.0	177.9	144.0									
067B	172.9	139.0	207.9	174.0	7.5	2.50	60.0	111.5	70.0	5.8	75.0	67.00	M5
067C	202.9	169.0	237.9	204.0									

	Feedback TL/UL			
	Unbraked length	Braked length	Unbraked length	Braked length
	A (± 0.9)	A (± 1.0)	A (± 0.9)	A (± 1.0)
067A	157.7	123.5	192.7	158.5
067B	187.7	153.5	222.7	188.5
067C	217.7	183.5	252.7	218.5

Shaft dimensions (mm)

	Shaft diameter	Shaft length	Key height	Key length	Key to shaft end	Key width	Tapped hole thread size	Tapped hole depth
	C (j6)	D (± 0.45)	E (IEC 72-1)	F (± 0.25)	G (± 1.1)	H (h9)	I	J (± 0.1)
14.0 Std	14.0	30.0	16.0	22.0	3.6	5.0	M5 x 0.8	13.5

Frame size 089 For 3 Phase VPWM drives

Motor frame size (mm)		089ED			089UD		
Voltage (Vrms)		200-240			380-480		
Frame length		A	B	C	A	B	C
Continuous Stall Torque (Nm)		3.20	5.50	8.00	3.20	5.50	8.00
Peak Torque (Nm)		9.60	16.50	24.00	9.60	16.50	24.00
Inertia (kgcm²)		0.87	1.61	2.34	0.87	1.61	2.34
Winding thermal time constant (s)		85	93	98	85	93	98
Motor weight unbraked (kg)		3.30	4.40	5.50	3.30	4.40	5.50
Motor weight braked (kg)		4.30	5.40	6.50	4.30	5.40	6.50
Number of poles		10	10	10	10	10	10
Speed 3000 (rpm)	Kt (Nm/A) =		0.93			1.60	
	Ke (V/krpm) =		57.00			98.00	
Rated torque (Nm)		3.00	4.85	6.90	3.00	4.85	6.90
Stall current (A)		3.44	5.91	8.60	2.00	3.44	5.00
Rated power (kW)		0.94	1.52	2.17	0.94	1.52	2.17
R (ph-ph) (Ω)		3.28	1.57	0.89	12.85	5.05	2.68
L (ph-ph) (mH)		21.55	11.84	7.09	80.66	38.36	21.72
Speed 4000 (rpm)	Kt (Nm/A) =		0.70			1.2	
	Ke (V/krpm) =		42.75			73.50	
Rated torque (Nm)		2.90	4.55	6.35	2.90	4.55	6.35
Stall current (A)		4.57	7.86	11.43	2.67	4.58	6.67
Rated power (kW)		1.21	1.91	2.66	1.21	1.91	2.66
R (ph-ph) (Ω)		2.04	0.79	0.54	6.16	2.47	1.75
L (ph-ph) (mH)		13.20	5.97	4.38	39.78	18.80	14.03
Speed 6000 (rpm)	Kt (Nm/A) =		0.47			0.8	
	Ke (V/krpm) =		28.50			49.00	
Rated torque (Nm)		2.65	3.80	5.00	2.65	3.80	5.00
Stall current (A)		6.88	11.83	17.20	4.00	6.88	10.00
Rated power (kW)		1.67	2.39	3.14	1.67	2.39	3.14
R (ph-ph) (Ω)		0.98	0.39	0.23	3.21	1.27	0.83
L (ph-ph) (mH)		6.24	2.96	1.89	20.16	9.59	6.66

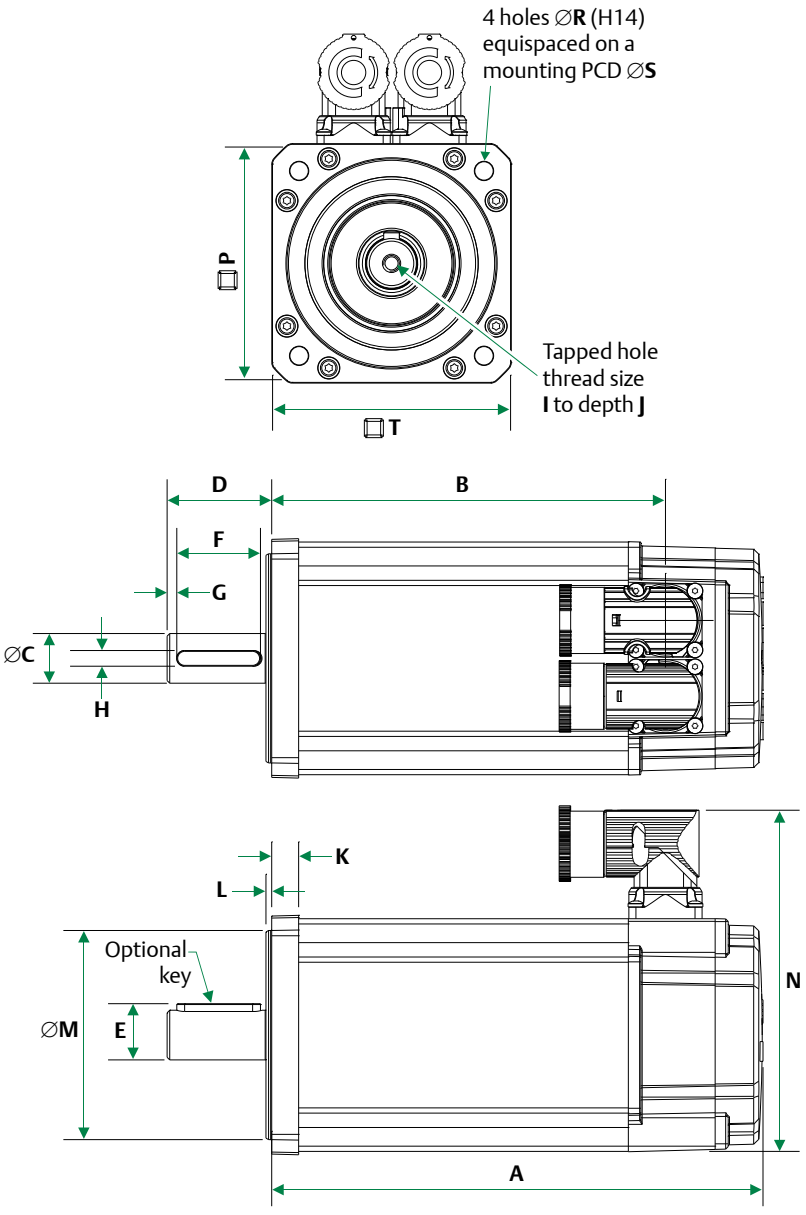
Δt= 100°C winding 40°C maximum ambient

All data subject to +/-10% tolerance

Stall torque, rated torque and power relate to maximum continuous operation tested in a 20°C ambient at 12kHz drive switching frequency

All other figures relate to a 20°C motor temperature.

Maximum intermittent winding temperature is 140°C



Motor dimension (mm)

Drawingnumber:IM/0688/GA

	Feedback EC/FC, LC/NC				Flange thickness	Register length	Register diameter	Overall height	Flange square	Fixing hole diameter	Fixing hole PCD	Motor housing	Mounting bolts
	Unbraked length		Braked length										
	A (± 0.9)	B (± 1.0)	A (± 0.9)	B (± 1.0)	K (± 0.5)	L (± 0.1)	M (j6)	N (± 1.0)	P (± 0.28)	R (H14)	S (± 0.4)	T (± 0.7)	
089A	147.8	110.5	187.9	150.6									
089B	177.8	140.5	217.9	180.6	10.3	2.20	80.0	130.5	91.0	7.00	100.0	89.0	M6
089C	207.8	170.5	247.9	210.6									

	Feedback FB, EB/CA/SA, RA		Feedback AE	
	Unbraked length	Braked length	Unbraked length	Braked length
	A (± 0.9)	A (± 0.9)	A (± 0.9)	A (± 0.9)
089A	160.8	200.9	137.8	177.9
089B	190.8	230.9	167.8	207.9
089C	220.8	260.9	197.8	237.9

Shaft dimensions (mm)

	Shaft diameter	Shaft length	Key height	Key length	Key to shaft end	Key width	Tapped hole thread size	Tapped hole depth
	C (j6)	D (± 0.45)	E (IEC 72-1)	F (± 0.25)	G (± 1.1)	H (h9)	I	J (± 0.1)
19.0 Std	19.0	40.0	21.5	32.0	3.7	6.0	M6 x 1.0	17.0

Frame size 115 For 3 Phase VPWM drives

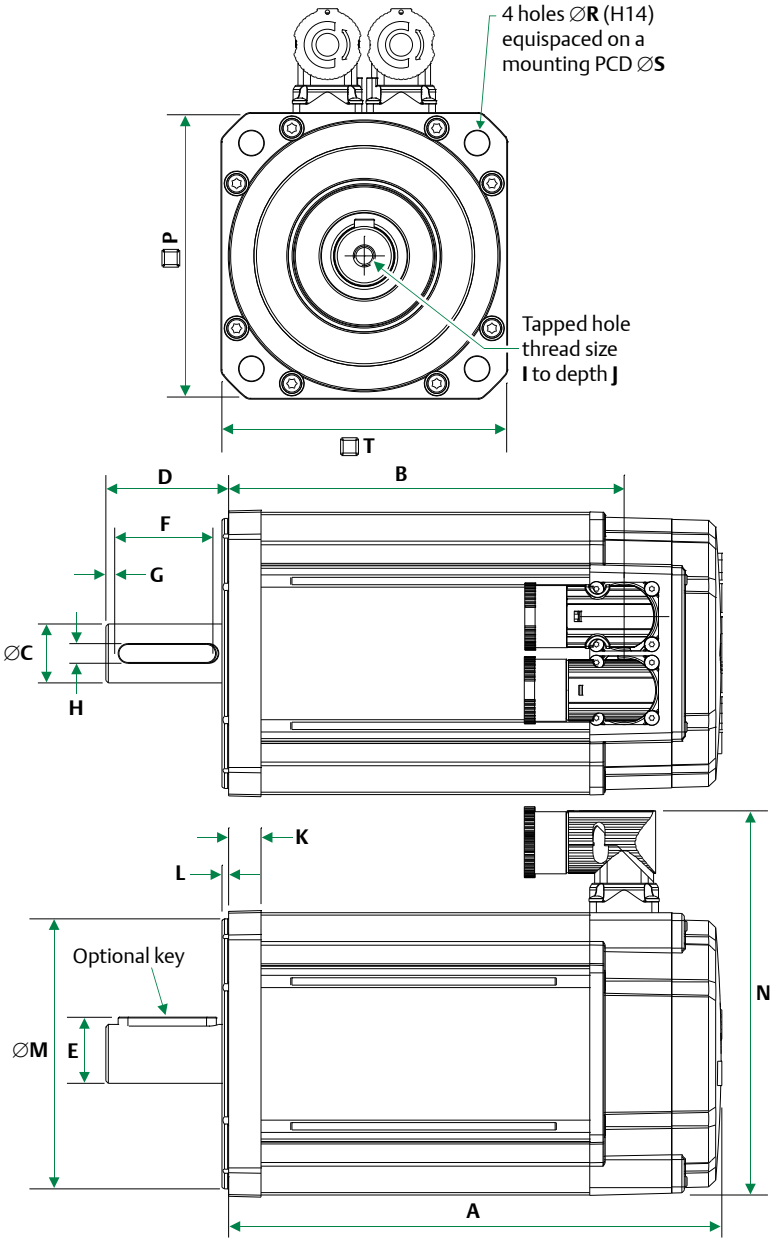
Motor frame size (mm)		115ED			115UD		
Voltage (Vrms)		200-240			380-480		
Frame length		B	C	D	B	C	D
Continuous Stall Torque (Nm)		10.20	14.60	18.80	10.20	14.60	18.80
Peak Torque (Nm)		30.60	43.80	56.40	30.60	43.80	56.40
Inertia (kgcm²)		4.41	6.39	8.38	4.41	6.39	8.38
Winding thermal time constant (s)		164	168	175	164	168	175
Motor weight unbraked (kg)		7.20	8.90	10.70	7.20	8.90	10.70
Motor weight braked (kg)		8.70	10.40	12.20	8.70	10.40	12.20
Number of poles		10	10	10	10	10	10
Speed 2000 (rpm)	Kt (Nm/A) =		1.40			2.4	
	Ke (V/krpm) =		85.50			147.00	
Rated torque (Nm)		8.60	11.90	15.60	8.60	11.90	15.60
Stall current (A)		7.29	10.43	13.43	4.25	6.08	7.83
Rated power (kW)		1.80	2.49	3.27	1.80	2.49	3.27
R (ph-ph) (Ω)		1.40	0.77	0.61	4.41	2.41	1.80
L (ph-ph) (mH)		12.84	7.87	6.62	40.59	24.69	19.45
Speed 3000 (rpm)	Kt (Nm/A) =		0.93			1.60	
	Ke (V/krpm) =		57.00			98.00	
Rated torque (Nm)		7.70	10.50		7.70	10.50	13.60
Stall current (A)		10.97	15.70		6.38	9.13	11.75
Rated power (kW)		2.42	3.30		2.42	3.30	4.27
R (ph-ph) (Ω)		0.58	0.39		1.83	1.21	0.78
L (ph-ph) (mH)		5.40	4.01		16.93	12.72	8.65

Δt= 100°C winding 40°C maximum ambient
All data subject to +/-10% tolerance

Stall torque, rated torque and power relate to maximum continuous operation tested in a 20°C ambient at 12kHz drive switching frequency

All other figures relate to a 20°C motor temperature.

Maximum intermittent winding temperature is 140°C



Motor dimension (mm)

Drawingnumber:IM/0689/GA

	Feedback EC/FC, LC/NC				Flange thickness	Register length	Register diameter	Overall height	Flange square	Fixing hole diameter	Fixing hole PCD	Motor housing	Mounting bolts
	Unbraked length		Braked length										
	A (± 0.9)	B (± 1.0)	A (± 0.9)	B (± 1.0)	K (± 0.5)	L (± 0.1)	M (j6)	N (± 1.0)	P (± 0.31)	R (H14)	S (± 0.4)	T (± 0.7)	
115B	193.8	154.0	230.9	191.1									
115C	223.8	184.0	260.9	221.1	13.2	2.70	110.0	156.5	116.0	10.00	130.0	115.0	M8
115D	253.8	214.0	290.9	251.1									

	Feedback FB, EB/CA/SA, RA		Feedback AE	
	Unbraked length	Braked length	Unbraked length	Braked length
	A (± 0.9)	A (± 0.9)	A (± 0.9)	A (± 0.9)
115B	206.8	243.9	183.8	220.9
115C	236.8	273.9	213.8	250.9
115D	266.8	303.9	243.8	280.9

Shaft dimensions (mm)

	Shaft diameter	Shaft length	Key height	Key length	Key to shaft end	Key width	Tapped hole thread size	Tapped hole depth
	C (j6)	D (± 0.45)	E (IEC 72-1)	F (± 0.25)	G (± 1.1)	H (h9)	I	J (± 0.1)
24.0 Std	24.0	50.0	27.0	40.0	5.3	8.0	M8 x 1.25	20.0

Frame size 142 For 3 Phase VPWM drives

Motor frame size (mm)		142ED			142UD		
Voltage (Vrms)		200-240			380-480		
Frame length		C	D	E	C	D	E
Continuous Stall Torque (Nm)		25.0	31.5	38.0	25.0	31.5	38.0
Peak Torque (Nm)		74.9	94.5	114.0	74.9	94.5	114.0
Inertia (kgcm²)		17.0	22.1	27.2	17.0	22.1	27.2
Winding thermal time constant (s)		245.0	251.0	256.0	245.0	251.0	256.0
Motor weight unbraked (kg)		11.5	15.0	18.5	11.5	15.0	18.5
Motor weight braked (kg)		14.3	17.8	21.3	14.3	17.8	21.3
Number of poles		10	10	10	10	10	10
Speed 1000 (rpm)	Kt (Nm/A) =	2.8					
	Ke (V/krpm) =	171.0					
Rated torque (Nm)		23.3	29.0	34.5			
Stall current (A)		8.9	11.2	13.6			
Rated power (kW)		2.44	3.04	3.61			
R (ph-ph) (Ω)		1.36	0.94	0.72			
L (ph-ph) (mH)		21.34	15.17	12.30			
Connection type		B	B	B			
Speed 1500 (rpm)	Kt (Nm/A) =				3.2		
	Ke (V/krpm) =				196.0		
Rated torque (Nm)					22.3	27.0	31.7
Stall current (A)					7.8	9.8	11.9
Rated power (kW)					3.5	4.2	5.0
R (ph-ph) (Ω)					1.36	0.94	0.72
L (ph-ph) (mH)					21.34	15.17	12.30
Connection type					B	B	B
Speed 2000 (rpm)	Kt (Nm/A) =	1.4			2.4		
	Ke (V/krpm) =	85.5			147.0		
Rated torque (Nm)		21.4	25.7	29.6	21.4	25.7	29.6
Stall current (A)		17.8	22.5	27.1	10.4	13.1	15.8
Rated power (kW)		4.48	5.38	6.20	4.48	5.38	6.20
R (ph-ph) (Ω)		0.34	0.24	0.18	0.79	0.62	0.49
L (ph-ph) (mH)		5.33	3.79	3.07	12.15	9.66	8.34
Connection type		J	J	J	B	B	B
Speed 3000 (rpm)	Kt (Nm/A) =	0.93			1.6		
	Ke (V/krpm) =	57.0			98.0		
Rated torque (Nm)		18.4	20.9	C/D	18.4	20.9	23.0
Stall current (A)		26.9	33.9		15.6	19.7	23.8
Rated power (kW)		5.78	6.57		5.78	6.57	7.23
R (ph-ph) (Ω)		0.12	0.10		0.34	0.24	0.18
L (ph-ph) (mH)		1.90	1.57		5.33	3.79	3.07
Connection type		J	J	J	B	J	J

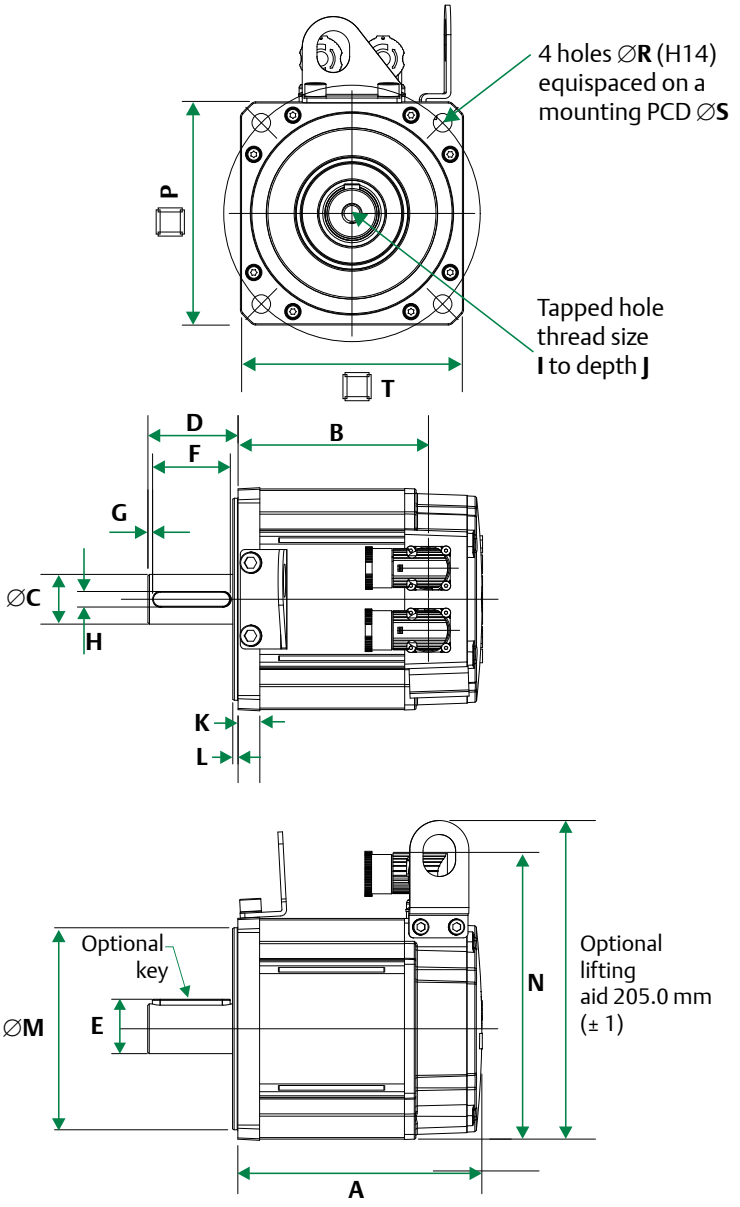
Δt= 100°C winding 40°C maximum ambient

All data subject to +/-10% tolerance

Stall torque, rated torque and power relate to maximum continuous operation tested in a 20°C ambient at 12kHz drive switching frequency

All other figures relate to a 20°C motor temperature.

Maximum intermittent winding temperature is 140°C



Motor dimension (mm)

Drawingnumber:IM/0709/GA

	Unbraked length		Braked length		Flange thickness	Register length	Register diameter	Overall height	Flange square	Fixing hole diameter	Fixing hole PCD	Motor housing	Mounting bolts
	A (± 0.9)	B (± 1.0)	A (± 0.9)	B (± 1.0)	K (± 0.2)	L (± 0.1)	M (j6)	N (± 1.0)	P (± 0.31)	R (H14)	S (± 0.4)	T (± 0.7)	
142C	217.0	182.5	282.5	248.0				183.5					
142D	247.0	212.5	312.5	278.0	14.0	3.4	130.0	183.5-204.5	142.0	12.0	165.0	142.0	M10
142E	277.0	242.5	342.5	308.0				183.5-204.5					

Shaft dimensions (mm)

	Shaft diameter	Shaft length	Key height	Key length	Key to shaft end	Key width	Tapped hole thread size	Tapped hole depth
	C (k6)	D (± 0.45)	E (IEC 72-1)	F (± 0.25)	G (± 1.5)	H (h9)	I	J (± 1.0)
32.0 Std	32.0	58.0	35.0	50.0	3.0	10.0	M12 x 1.75	29.0

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Frame size 190 For 3 Phase VPWM drives

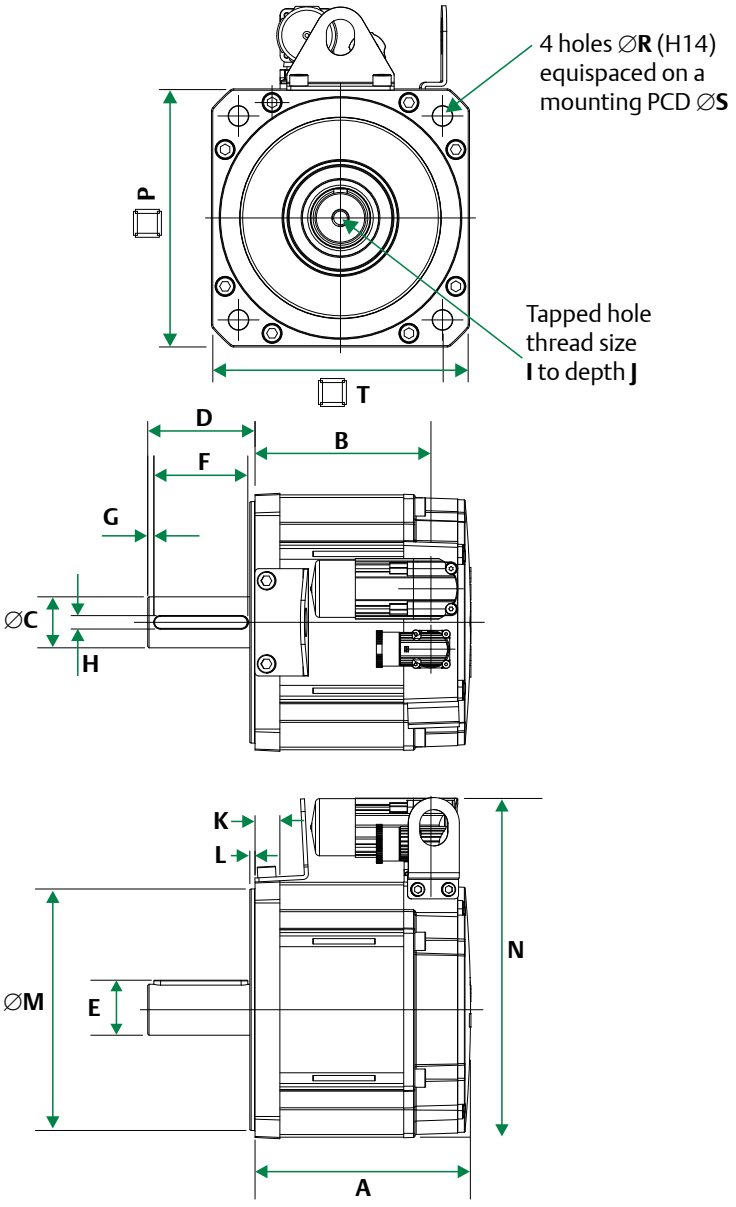
Motor frame size (mm)		190ED			190UD		
Voltage (Vrms)		200-240			380-480		
Frame length		C	D	F	C	D	F
Continuous Stall Torque (Nm)		52.0	62.0	85.0	52.0	62.0	85.0
Peak Torque (Nm)		156.0	186.0	255.0	156.0	186.0	255.0
Inertia (kgcm²)		54.6	70.9	103.5	54.6	70.9	103.5
Winding thermal time constant (s)		311.0	316.0	324.0	311.0	316.0	324.0
Motor weight unbraked (kg)		23.5	28.6	38.8	23.5	28.6	38.8
Motor weight braked (kg)		28.8	33.9	44.1	28.8	33.9	44.1
Number of poles		10	10	10	10	10	10
Speed 1000 (rpm)	Kt (Nm/A) = Ke (V/krpm) =	2.8 171.0					
Rated torque (Nm)		49.0	56.5	77.5			
Stall current (A)		18.6	22.1	30.4			
Rated power (kW)		5.13	5.92	8.12			
R (ph-ph) (Ω)		0.47	0.40	0.23			
L (ph-ph) (mH)		12.30	10.40	6.79			
Speed 1500 (rpm)	Kt (Nm/A) = Ke (V/krpm) =				3.2 196.0		
Rated torque (Nm)					46.2	52.2	68.5
Stall current (A)					16.3	19.4	26.6
Rated power (kW)					7.26	8.20	10.76
R (ph-ph) (Ω)					0.55	0.38	0.23
L (ph-ph) (mH)					14.15	10.40	6.79
Speed 2000 (rpm)	Kt (Nm/A) = Ke (V/krpm) =	1.4 85.5			2.4 147.0		
Rated torque (Nm)		42.5			42.5		
Stall current (A)		37.1			21.7		
Rated power (kW)		8.90			8.90		
R (ph-ph) (Ω)		0.12			0.32		
L (ph-ph) (mH)		3.07			8.20		

Δt= 100°C winding 40°C maximum ambient
All data subject to +/-10% tolerance

Stall torque, rated torque and power relate to maximum continuous operation tested in a 20°C ambient at 6kHz drive switching frequency

All other figures relate to a 20°C motor temperature.

Maximum intermittent winding temperature is 140°C



Motor dimension (mm)

Drawingnumber:IM/00710/GA

	Unbraked length		Braked length		Flange thickness	Register length	Register diameter	Overall height	Flange square	Fixing hole diameter	Fixing hole PCD	Motor housing	Mounting bolts
	A (± 0.9)	B (± 1.0)	A (± 0.9)	B (± 1.0)	K (± 0.2)	L (± 0.1)	M (j6)	N (± 1.0)	P (± 0.31)	R (H14)	S (± 0.4)	T (± 0.7)	
190C	220.6	191.1	319.1	289.6									
190D	250.6	221.1	349.1	319.6	18.5	3.9	180.0	252.5	190.3	14.5	215.0	190.0	M12
190F	310.6	251.1	409.1	379.6									

Shaft dimensions (mm)

	Shaft diameter	Shaft length	Key height	Key length	Key to shaft end	Key width	Tapped hole thread size	Tapped hole depth
	C (k6)	D (± 0.45)	E (IEC 72-1)	F (± 0.25)	G (± 1.5)	H (h9)	I	J (± 1.0)
38.0 Std	38.0	80.0	41.0	70.0	4.6	10.0	M12 x 1.75	29.0

Motor selection

Motor derating

Any adverse operating conditions require that the motor performance be derated. These conditions include; ambient temperature above 40°C, motor mounting position, drive switching frequency or the drive being oversized for the motor.

Ambient temperatures

The ambient temperature around the motor must be taken into account. For ambient temperatures above 40°C the torque must be derated using the following formula as a guideline. (Note: Only applies to 2000/3000rpm motors and assumes copper losses dominate)

New derated torque = Specified torque x √ [1-((Ambient temperature - 40°C) / 100)]

For example with an ambient temperature of 76°C the new derated torque will be 0.8 x specified torque.

Mounting arrangements

The motor torque must be derated if the motor mounting surface is heated from an external source, such as a gearbox. The motor is connected to a poor thermal conductor. The motor is mounted with the connectors on the side or vertical. The motor is in a confined space with restricted air flow.

Drive switching frequency

Most Digitax ST / Unidrive SP nominal current ratings are reduced for the higher switching frequencies see Digitax ST or Unidrive SP manual for details.

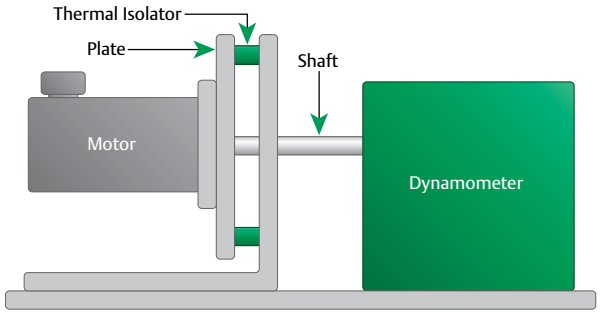
See the table below for the motor de rate factors. These figures are for guidance only.

(Note: Only applies to motors up to 3000rpm and assumes copper losses dominate)

Switching frequency	Motor type/frame					
	055	067	089	115	142	190
3kHz	0.92	0.93	0.89	0.89	0.83	0.90
4kHz	0.93	0.94	0.91	0.92	0.85	0.95
6kHz	0.95	0.95	0.95	0.96	0.88	1
8kHz	0.96	0.98	0.97	0.98	0.91	1
12/16kHz	1	1	1	1	1	1

Thermal test conditions

The performance data shown has been recorded under the following conditions. Ambient temperature 20°C, with the motor mounted on a thermally isolated aluminum plate as shown below.



Motor type/frame	Aluminium heatsink plate
055mm	110 x 110 x 27mm
067-089mm	250 x 250 x 15mm
115-142mm	350 x 350 x 20mm
190mm	500 x 500 x 20mm

Thermal protection

Thermistor protection (145°C) is built into the motor windings and gives an indication of serious overheating problems. The installer must connect the thermistor to the drive, failure to do so will invalidate the motor warranty in respect of a burnt out winding.

Environmental conditions

Any liquids or gases that may come into contact with the motor must be confirmed to ensure compliance with the correct international standards.

Brake Specification

Motor frame	Supply volts	Input power	Static torque		Release time	Moment of inertia	Backlash
			Standard parking brake (01)	High energy parking brake (05)			
Size	Vdc	Watts	Nm	Nm	ms nom	kgcm² *	Degrees**
055	24	6.3	1.8	N/A	22	0.03	0.73
067	24	10.2	N/A	4	<50	0.073	0.75
089	24	23.35	N/A	10	<50	0.115	0.75
115	24	19.5	N/A	25	120	0.327	0.75
142	24	25	N/A	42	95	2.54	0.77
190 C-D	24	25	N/A	67	120	4.57	0.77
190 F	24	54.5	N/A	100	TBD	7.72	0.75

*Note 1 kgcm² = 1x10-4kgm² **Backlash figure will increase with time

- The brakes are intended for parking duty and are not for dynamic or safety use
- The brake will engage when power is removed.
- Refer to your Drive Centre or Distributor if your application requires dynamic braking in emergency conditions.
- To provide protection to the brake control circuit it is recommended that a diode is connected across the output terminals of the solid state or relay contacts devices.
- Figures are shown at 20°C ambient. Apply a de rate factor of 0.7 to the standard brake torque figures if motor temperature is above 100°C

Feedback

Feedback device part number code	Feedback type	Encoder supply voltage[1]	Sincos cycles or incremental pulses per revolution	Resolution available to position loop[2&3]	Feedback Accuracy[1]
		055 - 067 motors			
AR	Resolver	7Vdc rms Excitation 5kHz	1	Medium 16384 (14 bit)	Low +/- 600”
CR	Incremental Encoder	5Vdc	4096	Medium 16384 (14 bit)	Medium +/- 150”
EM (Multi-turn) **FM (Single turn)**	Inductive Absolute Encoder EnDat 2.1	5Vdc	16	High 2.62x10^5 (18 bits)	Medium +/- 480”
LM (Multi-turn) **NM (Single turn)**	Inductive Absolute Encoder EnDat 2.2 (Serial comms only)	5Vdc	16	Medium 2.62x10^5 (18 bits)	Medium +/- 480”
TL (Multi-turn) **UL (Single turn)**	SinCos Optical Encoder Hiperface	8Vdc	128	Medium 1.31x10^5 (17 bit)	Medium +/- 150”
		089 - 190 motors			
AE	Resolver	6Vdc rms Excitation 6kHz	1	"Medium 16384 (14 bit)	Medium +/- 720”
CA	Incremental Encoder	5Vdc	4096	Medium 16384 (14 bit)	High +/- 60”
EC (Multi-turn) **FC (Single turn)**	Inductive Absolute Encoder EnDat 2.1	7 - 10Vdc	32	Medium Absolute position 524288 (19 bits)	Medium +/- 280”
LC (Multi-turn) **NC (Single turn)**	Inductive Absolute Encoder EnDat 2.2 (Serial comms only)	7-10Vdc	32	Medium Absolute position 524288 (19 bits)	Medium +/- 280”
RA (Multi-turn) **SA (Single turn)**	SinCos Optical Encoder Hiperface	7 - 12Vdc	1024	Very high 1.04x10^6 (20 bits)	High For SinCos Integral non-linearity +/- 45” For SinCos Differential non-linearity +/- 7” (Total accuracy+/-52”)
EB (Multi-turn) **FB (Single turn)**	Optical Absolute Encoder EnDat 2.2	3.6 - 14Vdc	2048	Very High 2.08x10^6 (21 bits)	Very High +/-20” (Differential non linearity +/- 1% signal period)

Notes:

1) The output from the resolver is an analogue output. The resolution is determined by the analogue to digital converter used. The value shown is when the resolver is used in conjunction with the SM-Resolver.

2) The sin and cosine outputs from the SinCos optical encoders are analogue outputs. With Unidrive SP and Digitax ST the resolutions quoted above are when the encoder type is set to either SC Endat or SC Hiper depending on the encoder.

3) The information is supplied by the feedback device manufacturer and relates to it as a standalone device. The values may change when mounted into the motor and connected to a drive.

These values have not been verified by CT Dynamics.

Resolver

A passive wound device consisting of a stator and rotor elements excited from an external source, such as an SM-Resolver, the resolver produces two output signals that correspond to the sine and cosine angle of the motor shaft. This is a robust absolute device of low accuracy, capable of withstanding high temperature and high levels of vibration. Positional information is absolute within one turn - i.e. position is not lost when the drive is powered down.

Incremental Encoder

An electronic device using an optical disc. The position is determined by counting steps or pulses. Two sequences of pulses in quadrature are used so the direction sensing may be determined and 4 x (pulses per rev) may be used for resolution in the drive. A marker pulse occurs once per revolution and is used to zero the position count. The encoder also provides commutation signals, which are required to determine the absolute position during the motor phasing test. This device is available in 4096 ppr version. Positional information is non absolute - i.e. position is lost when the drive is powered down.

SinCos/Absolute Encoders

Types available are: Optical or Inductive - which can be single or multi-turn.

1) Optical: An electronic device using an optical disc. An absolute encoder with high resolution that employs a combination of absolute information, transmitted via a serial link, and sine/cosine signals with incremental techniques.

2) Inductive: An electronic device using inductively coupled PCB’s. An absolute encoder with medium resolution that employs a combination of absolute information, transmitted via a serial link, and sine/cosine signals with incremental techniques. This encoder can be operated with the drive using either sine/consine or absolute (serial) values only. Positional information is absolute within 4096 turns - i.e. position is not lost when the drive is powered down.

Multi-turn: As previous but with extra gear wheels included so that the output is unique for each shaft position and the encoder has the additional ability to count complete turns of the motor shaft up to 4096 revolutions.

Electronic nameplating

Available on both these types of encoders, and allows quick set-up times as the motor information is stored on board the encoder (067-190 motors only).

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Cable information

PS	B	A	H	A	015
Cable type	Jacket	Phase & ground: conductor size	Connection details drive end	Connection details motor end	Cable length
PS = Power (Standard)	**B** = PUR	**H*** = 1.0mm² **10A**	**C** = Extension power connector 6 way	**A** = **055 - 142 Unimotor hd** size 1 power connector	Min = 001 (1m)
PB = Power (with brake)	**C** = OFS	**G** = 1.5mm² **16A**	**F** = **Unidrive** SP (1-2) Ferrules		Max = 100 (100m)
		A = 2.5mm² **22A**	**H** = **Digitax** ST and **Unidrive** SP0 Ferrules	**B** = **142 - 190 Unimotor hd** size 1.5 power connector	
* Only available in OFS		**B** = 4.0mm² **30A**	**K** = Epsilon EP Ferrules		
			X = Cut end	**X** = Cut end	

Cable type	PS for motor without brakes, PB for motors with brake.
Jacket	B is for the PUR sheath and is the Dynamic cable selection. C is for the OFS sheath and is the Static cable selection.
Conductor size	Select the conductor size according to the motors STALL CURRENT. Cables of 6mm² and above will be fitted with ring terminals only. Ratings are for individual cables (not lashed together) in free air temperature up to 40°C - make allowances as appropriate.
Connection detail drive end	Select the correct drive end connection for the drive in use.
Connection detail motor end	Select the correct motor end connection for the motor in use.
Length	Numbers represent the required cable length in metres.

SI	B	A	A	A	015
Cable type	Jacket	Special options		Connection details motor end	Cable length*
SI = Incremental Encoder Hyperboloid pins	**B** = PUR	**A** = Standard cable		**A** = Encoder 17 pin connector	Min = 001 (1m)
SR = Resolver	**C**** = OFS	**E** = Twisted screened SS cable		**B** = Resolver 12 pin connector	Max = 100 (100m)
SS = Sin/Cos Encoder		**L** = 8.5mm dia SI cable		**C** = Sin/Cos 12 pin connector (Hiperface)	
SE = Incremental Encoder Split pins				**E** = 17 pin extension connector	
				F = 90° Encoder 17 pin connector	
Connection details drive end				**G** = 90° Resolver 12 pin connector	
A = **Digitax ST/Unidrive** SP**/Epsilon EP** Encoder 15 pin connector				**H** = 90° Sin/Cos 12 pin connector (Hiperface)	
B = Resolver / Sin/Cos Ferrules				**N** = Sin/Cos 17 pin connector (EnDat)	
F = **Epsilon** Encoder 26 pin connector				**O** = 90° Sin/Cos 17 pin connector (EnDat)	
H = **Digitax ST/Unidrive** SP Sin/Cos 15 pin connector				**X** = Cut end	
I = Extension connector male pins					
X = Cut end					

* Max cable length - 50m with the SIBA/SICA as standard, 100m only if +5V tolerance can be maintained.

* Max cable length - 10m with the SIBL.

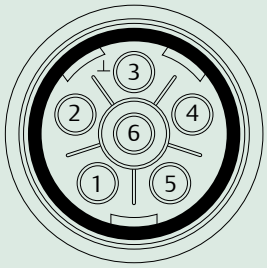
* Max cable length - Heidenhain EC/FC 20m EB/FB 30m with the SSBA cable,EC/FC 20m EB/FB 100m with the SSBE cable.

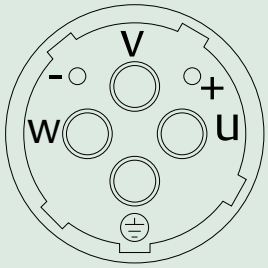
** OFS only available on SI encoder cable.

Cable type	Choose the cable type to match the feedback device.
Jacket	B is for the PUR sheath and is the Dynamic cable selection. C is for the OFS sheath and is the Static cable selection.
Special options	A is for standard cable. L is for the low cost 8.5mm incremental cable.
Connection detail drive end	Select the correct drive end connection for the drive in use.
Connection detail motor end	Select the correct motor end connection for the motor feedback device in use.
Length	Numbers represent the required cable length in metres.

Motor connector details

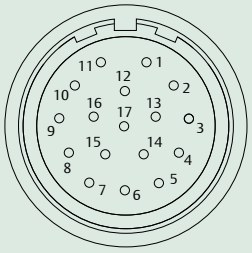
Power plug

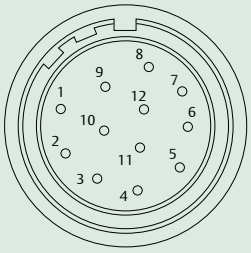




Size 1	With brake	Without brake	Size 1.5	With brake	Without brake
Pin	**Function**	**Function**	**Pin**	**Function**	**Function**
1	Phase U (R)	Phase U (R)	U	Phase U (R)	Phase U (R)
2	Phase V (S)	Phase V (S)	V	Phase V (S)	Phase V (S)
3	Ground	Ground	⏚	Ground	Ground
4	Phase W (T)	Phase W (T)	W	Phase W (T)	Phase W (T)
5	Brake	-	+	Brake	
6	Brake	-	-	Brake	
Shell	Screen	Screen	Shell	Screen	Screen

Signal plug





	Incremental encoder (CR,CA)	Heidenhain Absolute Encoders (EM, FM, EC, FC, EB, FB, LC, NC, LM, NM)	Resolver (AR, AE)	Sick|Stegmann Sin/Cos encoders (RA, SA, TL, UL)
Pin	**Function**	**Function**	**Function**	**Function**
1	Thermistor	Thermistor	Excitation high	REF Cos
2	Thermistor	Thermistor	Excitation low	+Data
3	-	Screen (Optical encoder only)	Cos high	-Data
4	S1	-	Cos low	+Cos
5	S1 Inverse	-	Sin high	+Sin
6	S2	-	Sin low	REF Sin
7	S2 Inverse	-	Thermistor	Thermistor
8	S3	+ Clock	Thermistor	Thermistor
9	S3 Inverse	- Clock	-	Screen
10	Channel A	+ Cos	-	0 Volts
11	Index	+ Data	-	-
12	Index Inverse	- Data	-	+ Volts
13	Channel A Inverse	- Cos	-	-
14	Channel B	+ Sin	-	-
15	Channel B Inverse	- Sin	-	-
16	+ Volts	+ V	-	-
17	0 Volts	0 Volts	-	-
Body	Screen	Screen	Screen	Screen

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Control Techniques Drive & Application Centres

AUSTRALIA
Melbourne Application Center
T: +613 973 81777
controltechniques.au@emerson.com

Sydney Drive Center
T: +61 2 9838 7222
controltechniques.au@emerson.com

AUSTRIA
Linz Drive Center
T: +43 7229 789480
controltechniques.at@emerson.com

BELGIUM
Brussels Drive Center
T: +32 1574 0700
controltechniques.be@emerson.com

BRAZIL
Sorocaba Drive Center
T: +55 15 3413 8169
vendasbrasil.cta@emerson.com

CANADA
Toronto Application Center
T: +1 905 948 3402
controltechniques.ca@emerson.com

Calgary Drive Center
T: +1 403 253 8738
controltechniques.ca@emerson.com

CHILE
Santiago Application Center
T: +56 9 7708 9470
saleschile.cta@emerson.com

CHINA
Shanghai Drive Center
T: +86 21 3418 3888
controltechniques.cn@emerson.com

Shenzhen Application Center
T: +86 755 8618 7287
controltechniques.cn@emerson.com

CZECH REPUBLIC
Brno Drive Center
T: +420 511 180111
controltechniques.cz@emerson.com

DENMARK
Copenhagen Drive Center
T: +45 4369 6100
controltechniques.dk@emerson.com

FRANCE*
Angoulême Drive Center
T: +33 5 4564 5454
controltechniques.fr@emerson.com

GERMANY
Bonn Drive Center
T: +49 2242 8770
controltechniques.de@emerson.com

Chemnitz Drive Center
T: +49 3722 52030
controltechniques.de@emerson.com

Darmstadt Drive Center
T: +49 6251 17700
controltechniques.de@emerson.com

GREECE*
Athens Application Center
T: +0030 210 57 86086/088
controltechniques.gr@emerson.com

HOLLAND
Rotterdam Drive Center
T: +31 184 420555
controltechniques.nl@emerson.com

INDIA
Chennai Drive Center
T: +91 44 2496 1123/1130/1083
T: +91 44 6691 8400
controltechniques.in@emerson.com

IRELAND
Newbridge Drive Center
T: +353 45 448200
controltechniques.ie@emerson.com

ITALY
Milan Drive Center
T: +39 02575 751
controltechniques.it@emerson.com

Vicenza Drive Center

T: +39 0444 933400
controltechniques.it@emerson.com

MALAYSIA
Selangor Drive Center
T: +603 5891 6099
controltechniques.my@emerson.com

MEXICO
Mexico City Application Center
T: +52 155 3333 6666
salesmexico.cta@emerson.com

POLAND
Warsaw Application Center
T +48 22 45 89 200
controltechniques.pl@emerson.com

REPUBLIC OF SOUTH AFRICA
Johannesburg Drive Center
T: +27 11 462 1740
controltechniques.za@emerson.com

Cape Town Application Center
T: +27 21 556 0245
controltechniques.za@emerson.com

RUSSIA
Moscow Application Center
T: +7 495 981 9811
controltechniques.ru@emerson.com

SINGAPORE
Singapore Drive Center
T: +65 6556 1100
controltechniques.sg@emerson.com

SLOVAKIA EMERSON A.S
T: +421 32 7700 369
controltechniques.sk@emerson.com

SOUTH KOREA
Seoul Application Center
T: +82 2 3483 1605
controltechniques.kr@emerson.com

SPAIN
Barcelona Drive Center
T: +34 93 680 1661
controltechniques.es@emerson.com

Bilbao Drive Center
T: +34 94 620 3646
controltechniques.es@emerson.com

Valencia Drive Center
T: +34 96 154 2900
controltechniques.es@emerson.com

SWEDEN*
Stockholm Application Center
T: +468 554 241 00
controltechniques.se@emerson.com

SWITZERLAND
Zurich Drive Center
T: +41 56 201 4242
controltechniques.fr.ch@emerson.com

Lausanne Application Center
T: +41 21 637 7070
controltechniques.fr.ch@emerson.com

TAIWAN
Taipei Application Center
T: +886 2 8161 7695
controltechniques.tw@emerson.com

THAILAND
Bangkok Drive Center
T: +66 2 962 2099
controltechniques.th@emerson.com

TURKEY
Istanbul Drive Center
T: +90 216 4182420
controltechniques.tr@emerson.com

UAE*
Emerson FZE
T: +971 4 8118100
ct.dubai@emerson.com

UNITED KINGDOM
Telford Drive Center
T: +44 1952 213700
controltechniques.uk@emerson.com

USA
Charlotte Application Center
T: +1 800 893 2321

controltechniques.us@emerson.com

Cleveland Drive Center
T: +1 216 901 2400
controltechniques.us@emerson.com

Detroit Application Center
T: +1 248 882 2652
controltechniques.us@emerson.com

Minneapolis Drive Center
Americas Headquarters
T: +1 952 995 8000
controltechniques.us@emerson.com

Portland Drive Center
T: +1 503 266 2094
controltechniques.us@emerson.com

Providence Application Center
T: +1 401 392 4256
controltechniques.us@emerson.com

LATIN AMERICA
Miami Application Center
T: +1 954 846 5082
saleslatinam.cta@emerson.com

Control Techniques Distributors

ARGENTINA
Euro Techniques SA
T: +54 11 4331 7820
eurotech@eurotechsa.com.ar

BAHRAIN
Emerson FZE
T: +971 4 8118100
ct.bahrain@emerson.com

BULGARIA
BLS - Automation Ltd
T: +359 32 968 007
info@blsautomation.com

CHILE
Ingeniería Y Desarrollo Tecnológico S.A
T: +56 2 719 2200
rdunner@idt.cl

COLOMBIA
Sistronic LTDA
T: +57 2 555 60 00
luis.alvarez@sistronic.com.co

Redes Electricas S.A.
T: +57 1 364 7000
alvaro.rodriguez@redeselectricas.com

CROATIA
Zigg-Pro d.o.o
T: +385 1 3463 000
zigg-pro@zg.htnet.hr

CYPRUS
Acme Industrial Electronic Services Ltd
T: +3572 5 332181
acme@cytanet.com.cy

EGYPT
Samiram
T: +202 29703868/+202 29703869
samiramz@samiram.com

EL SALVADOR
Servielectric Industrial S.A. de C.V.
T: +503 2278 1280
aeorellana@gruposervielectric.com

FINLAND
SKS Control
T: +358 207 6461
control@sks.fi

GUATEMALA
MICE, S.A.
T: +502 5510 2093
mice@itelgua.com

HONDURAS
Temtronics Honduras
T: +504 550 1801
temtronics@amnethn.com

HUNGARY
Control-VH Kft
T: +361 431 1160
info@controlvh.hu

ICELAND
Samey ehf
T: +354 510 5200
samey@samey.is

INDONESIA
Pt Apikon Indonesia
T: +65 6556 1100
info.my@controltechniques.com

Pt Yua Esa Sempurna Sejahtera
T: +65 6556 1100
info.my@controltechniques.com

ISRAEL
Dor Drives Systems Ltd
T: +972 3900 7595
info@dor1.co.il

KENYA
Kassam & Bros Co. Ltd
T: +254 2 556 418
kassambros@africaonline.co.ke

KUWAIT
Emerson FZE
T: +971 4 8118100
ct.kuwait@emerson.com

LATVIA
EMT
T: +371 760 2026
janis@emt.lv

LEBANON
Black Box Automation & Control
T: +961 1 443773
info@blackboxcontrol.com

LITHUANIA
Elinta UAB
T: +370 37 351 987
sales@elinta.lt

MALTA
Mekanika Limited
T: +35621 442 039
mfrancica@gasan.com

MEXICO
MELCSA S.A. de CV
T: +52 55 5561 1312
jcervera@melcsa.com

MOROCCO
Cietec
T: +212 22 354948
cietec@cietec.ma

NEW ZEALAND
Advanced Motor Control. Ph.
T: +64 (0) 274 363 067
info.au@controltechniques.com

PERU
Intech S.A.
T: +51 1 224 9493
artur.mujamed@intech-sa.com

PHILIPPINES
Control Techniques Singapore Ltd
T: +65 6468 8979
info.my@controltechniques.com

POLAND
APATOR CONTROL Sp. z o.o
T: +48 56 6191 207
info@acontrol.com.pl

PORTUGAL
Harker Sumner S.A
T: +351 22 947 8090
drives.automation@harker.pt

PUERTO RICO
Motion Industries Inc.
T: +1 787 251 1550
roberto.diaz@motion-ind.com

QATAR
Emerson FZE
T: +971 4 8118100
ct.qatar@emerson.com

ROMANIA
C.I.T. Automatizari
T: +40212550543
office@citautomatizari.ro

SAUDI ARABIA
A. Abunayyan Electric Corp.
T: +9661 477 9111
aec-salesmarketing@abunayyangroup.com

SERBIA & MONTENEGRO
Master Inzenjering d.o.o
T: +381 24 525 235
office@masterinzenjering.rs

SLOVENIA
PS Logatec
T: +386 1 750 8510
ps-log@ps-log.si

TUNISIA
SIA Ben Djemaa & CIE
T: +216 1 332 923
bendjemaa@planet.tn

URUGUAY
SECOIN S.A.
T: +5982 2093815
jose.barron@secoin.com.uy

VENEZUELA
Digimex Sistemas C.A.
T: +58 243 551 1634
digimex@digimex.com.ve

VIETNAM
N.Duc Thinh
T: +84 8 9490633
infotech@nducthinh.com.vn

P.N. 0702-0016-06 03/13

* Operated by sister company