

# ARCHON



RISE™  
explore-rise.com

## INSTRUCTION MANUAL

### WARNING

Please read and understand this manual, the operation and all safety aspects required for the safe operation of the product. Before use, if you feel that this product is not for you, please return it to the place of purchase.

### ***Manual Specifications and Description Changes***

The instruction manual, warranties, and other associated documentation are subject to change without notice. Hobbico assumes no responsibility for inadvertent errors to this manual.



**WARNING!** This product includes a lithium polymer (LiPo) battery. Improper handling may result in FIRE! You are responsible for following all safety precautions as outlined in this instruction manual.

# INTRODUCTION

Thank you for purchasing the Archon. We want the time you spend with your new R/C quadcopter to be fun and successful so please read the entire manual before beginning setup. If for any reason you think this R/C model is not for you, return it to the dealer immediately. Your dealer cannot accept returns on any model after final assembly.

For the latest technical updates or manual corrections for the Archon please visit the RISE web site at [www.explore-rise.com](http://www.explore-rise.com). If there is any new technical information, changes or important updates to this model, a "tech notice" box will appear on the page. Click the "tech notice" box to learn more.

## SAFETY PRECAUTIONS



**Failure to follow these safety precautions may result in injury to yourself and others.**

- Keep your face and body as well as all spectators away from the rotating plane of the propellers whenever the battery is connected. Keep loose clothing, shirt sleeves, ties, scarfs, long hair or loose objects such as pencils or screwdrivers that may fall out of shirt or jacket pockets away from the propellers. The spinning propellers of a model quadcopter can cause serious injury. When choosing a flying site for your Archon, stay clear of obstacles, trees and power lines. **AVOID** flying in or near crowded areas. **DO NOT** fly close to people or pets. Maintain a safe distance from the quadcopter.
- Your Archon should not be considered a toy. Because of its performance capabilities, the Archon, if not operated correctly, could cause injury to you or spectators and damage to property.
- **DO NOT** alter or modify the model. Doing so may result in an unsafe or unflyable model.
- When and if repairs are necessary you must correctly install all components so that the model operates properly on the ground and in the air. Please check the operation of the model before every flight to ensure that all equipment is operating and that the model has remained structurally sound. Be sure to check the propellers before each flight. Replace them if they show any signs of wear or fatigue.

## LITHIUM BATTERY WARNING!



This product includes a lithium polymer (LiPo) battery. Improper handling could result in **FIRE!** A lithium battery fire has the potential to ignite surrounding areas and may cause property damage or cause personal injury.

For safe LiPo handling, follow all of these guidelines. If you are unable to follow these guidelines, return this product to the place of purchase.

- **MOST IMPORTANT! NEVER** leave the charger and LiPo battery unattended while charging.
- Keep out of reach of children!
- **NEVER** charge a LiPo battery on a flammable surface or near combustible materials.
- **NEVER** charge inside a vehicle or at a location that could be damaged in the event of a LiPo fire.
- Do not charge or use a battery that is deformed, bent, crushed or has any type of visible damage.
- Only use the included factory approved charger with this LiPo battery.
- **ALWAYS** keep a supply of sand accessible when charging. Dumping sand on the battery will assist in extinguishing a LiPo chemical fire.
- It is normal for the charger to become warm to the touch. However, disconnect the battery and unplug the charger **immediately** if either becomes hot, begins to swell, or smoke!
- Disconnect the battery and unplug the charger if the charge time **exceeds 3 hours**.
- **ALWAYS** disconnect the battery and unplug the charger after the charge is complete.
- **ALWAYS** disconnect and remove the battery from your model **immediately** following operation.
- **ALWAYS** store/transport LiPo batteries in a **fireproof container** away from combustible materials.
- **NEVER** put a LiPo battery in the pocket of any clothing.
- Keep LiPo batteries out of reach of animals. A punctured battery may cause a fire.
- Do not use the included charger for any other battery other than the one included with this model.
- In the event of a crash, place the battery into a **fireproof container** immediately. Examine the battery for damage before further use.
- Only operate and store batteries between 40-110° F (4-43° C).
- **NEVER** allow the battery temperature to exceed 140° F [60° C] during operation.
- **NEVER disassemble or modify a battery**, its wiring, or puncture cells, as this may result in fire.
- Do not allow the battery to short circuit by touching exposed wires together.
- Stop the operation of your model immediately when the battery power is low. A battery failure can occur when attempting to recharge an over-discharged battery.
- LiPo batteries **must always** be recycled or disposed of properly.

## **WARRANTY**

RISE™ guarantees this kit to be free from defects in both material and workmanship at the date of purchase. This warranty does not cover any component parts damaged by use or modification. In no case shall RISE's liability exceed the original cost of the purchased kit. Further, RISE reserves the right to change or modify this warranty without notice. In that RISE has no control over the final assembly or material used for final assembly, no liability shall be assumed nor accepted for any

damage resulting from the use by the user of the final user assembled product. By the act of using the user assembled product, the user accepts all resulting liability. If the buyer is not prepared to accept the liability associated with the use of this product, the buyer is advised to return this kit immediately in new and unused condition to the place of purchase.

To make a warranty claim, please contact our support team at <http://www.explore-rise.com/support.php>

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- RISE Archon FPV Quadcopter
- 2.4 GHz 6 – Channel Transmitter
- Extra Propellers
- Prop Guards
- 2200 mAh 2S LiPo
- LiPo Charger w/ AC Charge Adapter
- 4 AA Batteries
- Screwdriver
- Instruction Manual

(Notes: 6 channels mean different functions.

Below are the list for each channel:

1. control the drone right and left flight
2. control drone front and backward flight
3. control drone rotate to right or left
4. control flight mode of drone
5. control the throttle of drone to fly slow or fast
6. control the dual drone to react slow or fast.)

## KNOW BEFORE YOU FLY

As a new owner of an unmanned aircraft system (UAS), you are responsible for the operation of this vehicle and the safety of those around you. Please contact your local authorities to find out the latest rules and regulations.



Federal Aviation Administration  
[faa.gov/uas](http://faa.gov/uas)

# SETUP

## Unboxing

Remove the contents of the box and become familiar with the included parts. To easily remove the transmitter from the packaging, push outward at the location shown while lifting up on the transmitter from the same side.



## Battery Charging

Plug the AC wall adapter into a 120V outlet and connect the balance charger to the wall adapter. The power LED will illuminate solid **RED**. Plug the white balance plug on the battery to the 2S port on the charger. When charging, the charge status LED will illuminate solid **RED**. When charge is complete the LED will change to solid **GREEN**. Typical charge time of a depleted battery is approximately 2 hours.



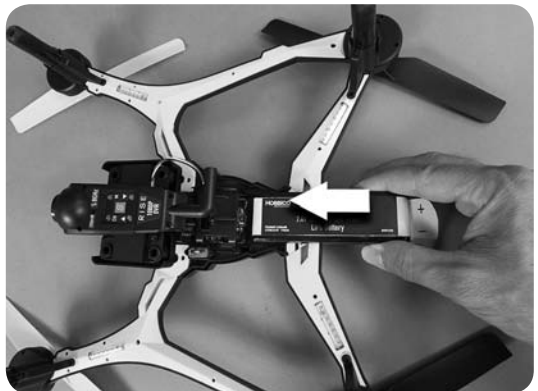
**NOTE:** A blinking red charge status LED indicates a charging error.

- **NEVER** leave the battery unattended while charging.
- **ALWAYS** unplug the charger from the outlet and the battery when charging is complete.
- **NEVER** charge a puffed or damaged battery.

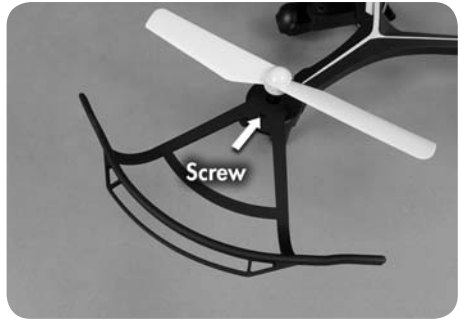
**NOTE:** It is normal for the charger to get warm during the charging process.  
🔥 See the battery precautions at the front of this manual.

## Battery Installation

Insert the flight battery into the battery tray on the underside of the Archon. Be sure that the battery is slid as far back into the tray as allowed. A battery not properly installed may fall out during flight and may affect the center of gravity of the Archon.



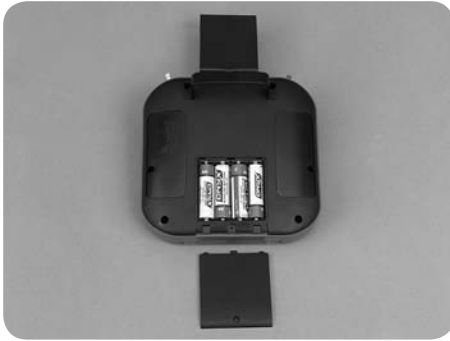
## Prop Guard Installation



**NOTE:** Prop guards are included to help protect the propellers from accidental contact with obstacles. We recommend they be installed prior to your first flight.

Fit the bottom prop guard retainer over the alignment pin on the motor cover. Press the prop guard in place as shown with the pins in the alignment holes. It should fit snugly over the screw bosses on the retainer. Secure the prop guard and retainer using three screws included in the package. Repeat this procedure for the other three prop guards.

## RADIO SYSTEM



Remove the battery door screw and slide the door down to access the battery compartment. Install the included AA batteries and replace the door.

## Flight Mode Switch

**Altitude Hold** sets the Archon to just maintain its altitude when the left stick is centered. In this mode, the drone can drift with the wind. The right stick and the rotate control may be needed to keep the Archon in position.

**GPS Hold** enables the GPS system to keep the Archon in position when the sticks are centered. The drone must be in an open area where it is receiving GPS signals for this function to work correctly.



**Home** enables the Return-To-Home function (RTH). When the switch is moved to Home, the Archon will climb to 8 meters if at or below that altitude, fly back to the launch point, and then initiate auto-land. When it has completed the landing, the Archon will stop the propellers.

## D/R Switch

This switch controls the sensitivity of the controls. When the switch is pushed toward the back of the transmitter, the controls are in the high setting. This setting is recommended for flying in moderate winds (5+ mph) or higher.



Pull the switch forward to enter the low rate setting. This setting is best for calm conditions or when beginning pilots are learning to fly the Archon.

## Picture Button

Push this button to capture a still picture on a memory card (\*not included) that has been installed in the camera.



## Video Button

Push this button to record a video on a memory card (\*not included) that has been installed in the camera.



## Transmitter LED Indicators

There are LED indicators on the transmitter and the Archon. The behavior and color of the LEDs will communicate to you the current status of the Archon. Read and understand the different LED behaviors before attempting to fly the Archon. A quick reference chart is also provided for future use.

**GPS** - This LED will flash slowly when at least six satellites have been detected for GPS mode. The LED will remain off if there are not enough satellites to fly in GPS (Global Positioning System) mode.



\*Memory card not included. Maximum storage 32GB. Class 10 or higher recommended.

**TX** - This LED is illuminated solid when the transmitter is turned on and the transmitter batteries have enough voltage to safely fly. This LED will flash and the transmitter will beep when the transmitter battery voltage reaches 4.5V. If this occurs during flight, land the Archon and replace the transmitter batteries.

**LVC** - When the Archon is powered on and the transmitter is on and properly linked to the Archon, this LED will be solid as long as the Archon battery voltage is above 7.5V. The LED will flash and the transmitter will continuously emit a series of beeps when the Archon battery voltage falls below 7.5V. If flying in altitude mode, the Archon will begin the auto-land feature in 3 seconds after LVC (Low Voltage Cutoff) occurs. If flying in GPS mode the Archon will initiate the RTH (Return-to-Home) function which will cause it to fly back to the home point at 8 meters in altitude and in a direct line of flight at which point the Archon will auto-land. **NOTE:** To cancel the RTH function when initiated by a low voltage cutoff condition, move the flight control switch to **ALTITUDE HOLD**. The Archon will stop its flight back to the point and immediately descend straight down from its current position for landing.

## PREPARING FOR FLIGHT

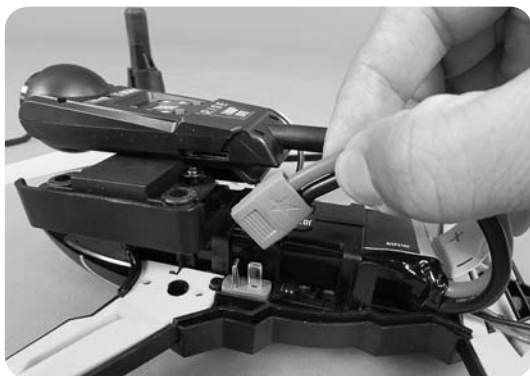
**NOTE:** Do not try to fly at this time. You must calibrate the Archon before your first flight.

### Powering the Archon

1. Turn on the transmitter by pressing the power button. The TX and LVC LEDs will illuminate and the transmitter will emit a continuous series of beeps until the Archon is powered.



2. Connect a charged battery to the Archon. The transmitter will stop beeping when it detects the radio connection to the Archon. If the transmitter continues to beep then the Archon may not be linked to the transmitter. See **LINKING THE TRANSMITTER**.

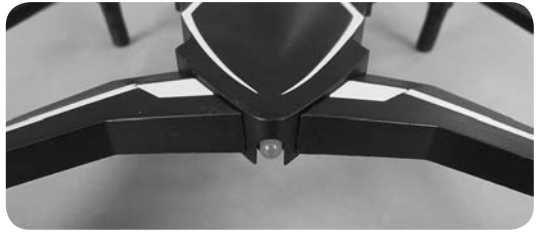


3. Place the Archon in an open area free of any people or obstacles.



## Rear Archon LED

The rear Archon LED will relay the following information to the pilot:



## Pre-flight LED status



**Fast Flash RED** - Searching for GPS satellites.



**Slow Flash RED** - GPS acquired, home position not yet set.



**Solid RED** - GPS acquired and home position set.



**Fast Flash GREEN** - Begin compass calibration. See **Compass Calibration** for complete description.

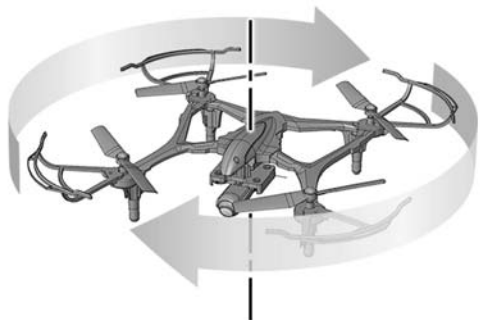


**Slow Flash GREEN** - Awaiting vertical rotation for compass calibration procedure.

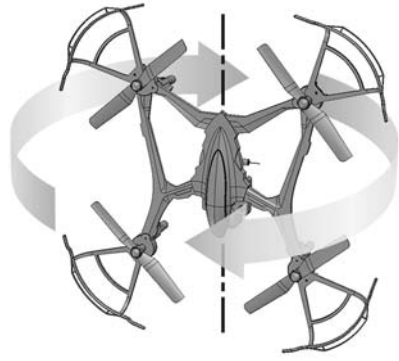
## Compass Calibration

When the Archon is powered on, it will automatically take magnetic readings of the surroundings and compare them to its current compass settings. If the Archon determines that the compass needs to be calibrated, it will initiate the compass calibration procedure indicated by the Archon rear LED flashing fast green. Compass calibration should be done in an open area, free of any large metal objects such as automobiles, fences, buildings, etc.

**Fast Flash GREEN** - The Archon should be placed on a flat, level surface. Rotate the Archon as shown while keeping it level until the LED changes to slow flash green.



**Slow Flash GREEN** - Pick the Archon up and hold it vertically with the nose pointing down. Rotate the Archon as shown until the LED no longer flashes green.



If at any time the Archon appears to be flying erratically or is unable to maintain position during hover in GPS mode, compass calibration can be manually initiated when the Archon and transmitter are powered on and propellers are un-armed (not rotating). Move both transmitter sticks simultaneously to the bottom left corners and hold until the Archon rear LED flashes fast green. Release the sticks. Then, continue with the procedure described in this section.



## Accelerometer Calibration

Accelerometer calibration can be performed whenever the Archon is placed on a flat, level surface and the propellers are un-armed (not rotating). This calibration should be performed regularly to help ensure that the sensors are operating correctly during flight.

To perform accelerometer calibration, the Archon and transmitter must be powered on and the propellers must be un-armed (not rotating). Place the Archon on a flat, level surface and move both transmitter sticks to the bottom right corners and hold until the Archon rear LED alternates quickly between red and green.



## Motor Arming and Disarming

When you are ready for flight and the Archon is in a safe, open area, arm the motors by moving both transmitter sticks to the bottom inside corners and hold until the propellers begin to rotate. **WARNING:** The props will rotate at a moderately slow, idle speed when armed. Moving the throttle stick above the middle stick position after the motors are armed will cause the propellers to accelerate for flight.



To stop the propellers from rotating after they have been armed, or at any time after landing if the propellers fail to automatically stop, you can disarm them by moving both transmitter sticks to the bottom outside corners and hold until the propellers stop.



### Emergency Stop -

The emergency stop function can be used any time during flight to stop the motors from rotating. We recommend that the emergency stop function only be used when



necessary to preserve the safety of surrounding things and people or to prevent the imminent loss of your Archon due to pilot error or malfunction.

To activate the Emergency Stop, press and hold the **PICTURE** and **VIDEO** buttons simultaneously for at least 2 seconds.

**NOTE:** The Archon motors will stop spinning when the emergency stop is activated. This will cause the Archon to fall freely to the ground. Care should be taken to ensure that causing the Archon to fall to the ground uncontrolled, likely damaging both it (the Archon) and possibly what it lands on, is preferable to a controlled descent and landing. Use the emergency stop only when necessary. The transmitter LEDs will indicate that the emergency stop was activated by flashing repeatedly in a consecutive order. This indication can be cancelled by arming the motors again or cycling the power of the transmitter.

## FLYING THE ARCHON

### Flight Modes

The Archon can be flown with or without GPS assist. The altitude hold function is always operational regardless if GPS is assisting your flight.



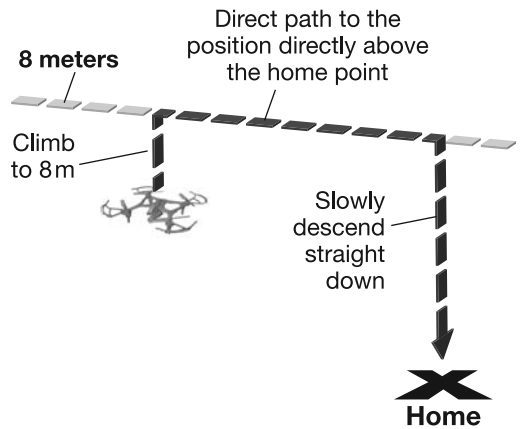
**Altitude Hold** - Moving the flight mode switch to ALTITUDE HOLD disables GPS assist. In this mode the Archon can be flown anywhere even if there is no GPS signal present. The barometric sensor will still provide information to the Archon about its altitude which will allow it to automatically maintain the current altitude when the throttle stick (left stick) is released. Because GPS is not assisting with the flight, the Archon is free to



drift with the wind or other external factors. In this mode, the pilot will need to continue to make corrections using the transmitter sticks in all directions in order to hold position (hover).

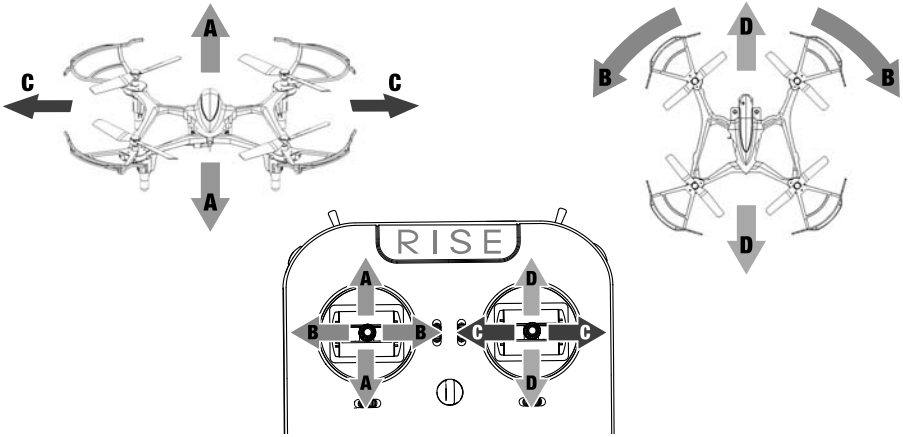
**GPS Hold** - With GPS assist turned on, the Archon benefits from having its current position detected by satellites and therefore can automatically make the necessary control corrections to hold that position. When the sticks are released, wind will not cause the Archon to move from its current position in this mode. (Some adjustment is to be expected in windy conditions as the Archon makes the necessary pitch corrections to maintain position.) This mode is very useful when using the Archon to take pictures or record video. In order for the Archon to fly with GPS assist, the Archon must be in an area free of any obstruction that would interfere with satellite communication as well as any large metal objects that might affect the Archon's geomagnetic readings.

**HOME** - The home function is used when you would like the Archon to fly automatically to the position where the Archon set the home point. When the flight mode switch is moved to Home, the Archon will climb to 8 meters in altitude (if below 8 meters) and then fly a direct path to the position directly above the home point. The Archon will then slowly descend straight down until touch down is detected at which point the Archon will automatically stop the propellers. To cancel RTH (Return-To-Home), move the flight mode switch out of Home.



**NOTE:** If the GPS signal is lost or the motors were armed before the home point was set, then the Archon cannot return to the set home point automatically.

# Stick Controls



The **VERTICAL** movement of the **LEFT** stick controls the ascent/descent of the Archon. When released, the left stick will return to the center neutral position and the Archon will hold its current altitude. The stick deflection from the center position is proportional to the rate at which the Archon ascends or descends.

The **HORIZONTAL** movement of the **LEFT** stick controls the direction the Archon is pointing. Moving the left stick in the horizontal directions will cause the Archon to rotate around its center axis (yaw). The stick deflection from the center position is proportional to the rate at which the Archon rotates.

The **RIGHT** stick controls the pitch angle of the Archon. The right stick is used to fly the Archon in the direction that the right stick is moved. Moving the right stick up will cause the Archon to move in the direction that the nose (camera) is pointing. This direction is considered **FORWARD** flight. Moving the right stick in any other direction will cause the Archon to fly in that stick direction relative to the nose direction. Remember, if you rotate the Archon using the left stick, moving the right stick up for forward flight will cause the Archon to fly in the new direction the nose is pointing. This is common sense. However, it can be difficult to adapt to this during flight for beginner pilots. The stick deflection from the center position is proportional to the rate at which the Archon flies.

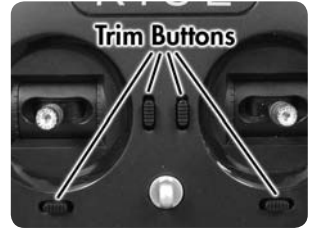
## Dual Rates (D/R)

The dual rate (D/R) switch on the transmitter adjusts the sensitivity of the stick controls. The low rate setting is with the switch toward the front of the transmitter. Low rates are recommended for calm winds and are desirable rates for smooth video recording. Low rates are also recommended for beginner pilots. The high rate setting is with the switch toward the back of the transmitter. High rates are recommended for winds greater than 5mph.



## Trim Buttons

The trim buttons make small adjustments to the neutral position for each of the four corresponding stick directions. Because the Archon has accelerometers and a compass, it will automatically correct for any unintended pitch or rotation when the transmitter sticks are in the neutral position. So, it is unlikely that adjustments to the trim buttons from their default, centered location will improve flight performance. We recommend leaving the trim buttons in the centered location.



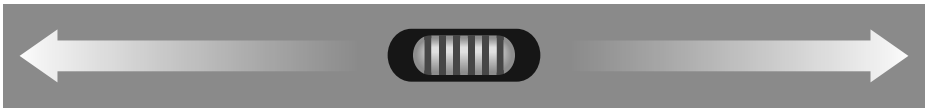
If your trim buttons have been moved from the centered location, use the image below to return them to the default position.



“Beep-Beep-Beep”

“Beeeeeep”

“Beep-Beep-Beep”



## Altitude Holding

The Archon has a built-in barometer on the flight control board that detects the surrounding air pressure which enables the quad to maintain a set altitude automatically. After takeoff, the Archon maintains the current altitude whenever the throttle stick is released to the center position. Move the throttle stick up or down to change the set altitude position. When the stick is released back to center, the Archon's current height will be the new set altitude.

**NOTE:** It is normal to see slight deviations from the set altitude. Windy conditions or sensors that are out of calibration may increase the deviation from the set altitude. Recalibrate the accelerometers if the Archon is flying erratically or does not appear to be maintaining altitude well.

## Taking Off

**ATTENTION!** Before flying your Archon for the first time, be sure that you have read this manual and are familiar with the operation of your Archon or injury to yourself or others may result.

1. Ensure your flight battery is fully charged and your flying site is free of anything that may interfere with your intended flight path.
2. Turn on the transmitter and connect the flight battery to the Archon.
3. **IMPORTANT!** If flying in a new area (or automatically initiated by the Archon), perform compass calibration.
4. Perform accelerometer calibration.
5. Select your desired flight mode using the flight mode switch on the transmitter. If GPS mode is selected, the Archon cannot be armed until the GPS signal has been acquired and the home point has been set (indicated by a solid red LED at the rear of the Archon).

**NOTE:** It is recommended that you take off in GPS mode. You must wait to take off in GPS mode until GPS has been acquired and the home point is set (solid red LED at the rear of the Archon). The Archon will not be able to return to home automatically using the HOME function if you take off in Altitude Hold mode regardless of the GPS signal status.

6. Do a final check of your surroundings and confirm that it is safe to take off. The pilot (you) should be standing a safe distance from the Archon of at least 15 feet (5 meters). Ideally you should be facing away from the sun.
7. Arm the motors by moving both sticks down and inward and hold them there until the motors start to rotate.
8. Slowly move the throttle stick (left transmitter stick) up to increase the propellers' rotation. The Archon will then lift off the ground and climb in altitude as long as the throttle stick is up. Releasing the throttle stick to the center position will cause the Archon to stop climbing and hover at its current altitude. Move the throttle stick down to cause the Archon to descend.

## Landing

**Manual Landing** - Move the throttle stick to its lowest position when the Archon is hovering over your desired landing spot. The Archon will descend until it detects that landing has occurred and will then automatically stop the propellers. Continue to hold the throttle stick in the lowest position until the propellers stop rotating.

**RTH Landing** - Move the flight mode switch to HOME. The Archon will initiate the RTH function by climbing to 8 meters (if currently below that altitude), flying to the set home point, descending until landed, and then automatically stopping the propellers. If a home position was not set prior to takeoff or takeoff was done in Altitude Hold mode, the Archon will not take any action in the HOME flight mode. Landing must be done manually.

**NOTE:** If the Archon has landed but the propellers do not stop, move the transmitter sticks to the lowest, outside positions and hold until the propellers stop.



## Transmitter Signal Failure

If at anytime during the flight the signal between the transmitter and the Archon is lost (external interference, loss of transmitter battery power, etc.), the Archon will wait for 3 seconds to recover the signal. If there is still signal loss after 3 seconds the Archon will automatically return to the set home position (see RTH landing details). If no home point was set or the Archon does not have a GPS signal then the Archon will descend straight down from its current position to land. If the signal is recovered during the automatic landing procedure, then the Archon will cancel the RTH function and will stabilize itself in its current position where the transmitter signal was resumed.

*Long press* the **M** button when in review mode to enter the file management function page. To move back one menu level or to return to the review mode, *long press* the **M** button. *Short press* the **M** button to select a file management function. The functions and their descriptions are listed below:

**Delete:** Deletes contents on the camera memory card - the **Current** picture/video that was displayed on the monitor when the file management function was selected, or **All** pictures/videos saved on the camera memory card. Select **Cancel** to stop the delete function.

**Protect:** Safeguards pictures/videos stored on the camera memory card from accidental deletion. **Lock Current** will file lock the picture/video that was displayed on the monitor when the file management function was selected. **Unlock Current** will unlock the picture/video that was displayed on the monitor when the file management function was selected, if it has been previously locked. **Lock All** will file lock all the pictures/videos saved on the camera memory card. *Short press* the **M** button to select an option. **NOTE!** Locking pictures/videos using this camera function will not prevent them from being deleted when accessed through a card reader or other means. Important pictures/videos should be backed up to a secure location.

**Thumbnail:** Displays list of small thumbnail images for every picture/video saved to the camera memory card. *Short press* the up ▲ or down ▼ buttons to scroll through the thumbnails. *Short press* the **M** button to select a thumbnail to display in full size on the monitor.

**Setup:** This accesses the Setup function described in the **Menu** section.

## Taking Pictures and Videos

Pictures and videos are taken (stored on optional memory card installed in the camera) using the buttons on the upper left and right corners of the transmitter.

To take a picture, press and release the picture button on the transmitter. The LED indicator on the camera will flash purple one time when a picture is taken. To take a video, press and release the video button on the transmitter to start a video recording. The LED indicator on the camera will

continuously flash between orange and purple while the camera is recording video. To stop video recording, press and release the video button on the transmitter. The LED indicator will change to solid orange indicating that video recording has stopped.

**NOTE:** The LED indicator on the camera will continuously flash between orange and purple if there is no memory card installed in the camera. The LED will remain solid orange when there is a memory card installed and the camera is not in the process of recording video. *Be sure to unplug the battery from the Archon before removing or installing a memory card into the camera.*





# LINKING THE TRANSMITTER

The transmitter included with your Archon is linked at the factory so no action needs to be taken when you unbox your Archon. If the transmitter is ever replaced or the transmitter is no longer linked to the Archon for any reason, the transmitter can be linked to the Archon with the following procedure:

Turn off the transmitter and unplug the battery to the Archon. With the transmitter OFF, press and hold the **PICTURE** button on the transmitter. While holding the button, turn the transmitter ON. The three LEDs on the transmitter will flash continuously indicating the transmitter is now in linking mode. Connect the battery to the Archon and the transmitter will then link to the Archon.

## TROUBLESHOOTING

### Flying Problems

**PROBLEM:** The Archon will not respond to the transmitter.

**SOLUTION:** (1) Charge or change the battery in the Archon.

(2) Turn off the transmitter and disconnect the battery from the Archon. Re-link the Archon and transmitter (the transmitter will beep continuously if not linked to the Archon).

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**PROBLEM:** 'TX' LED transmitter flashes with audible beeping when transmitter is powered on.

**SOLUTION:** Replace with new AA batteries.

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**PROBLEM:** The balance charger charge status LED blinks when attempting to charge the battery.

**SOLUTION:** The battery voltage is too low to charge. The battery voltage may recover on its own with time in order to be safely charged. Wait 1 hour and try charging again. If the charger LED still blinks then you may need to replace the battery.

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**PROBLEM:** The motors cannot be armed.

**SOLUTION:** (1) The flight mode is set to GPS mode but the GPS signal has not yet been acquired or the home point not set. Wait for the GPS signal to be acquired and the home point set which is indicated by a solid red rear LED on the Archon. If there is an obstruction or interference in the area preventing the GPS signal from being acquired, switch to ALTITUDE HOLD mode or move the Archon to a different area.

(2) Battery voltage is too low (indicated by a flashing LVC LED on the transmitter and a continuous beeping). Charge the flight battery.

(3) The Archon has auto-initiated compass calibration. The calibration procedure must be completed before the motors can be armed (see **Compass Calibration**).

**PROBLEM:** The Archon will not acquire GPS signal or set the home point.

**SOLUTION:** (1) Cycle the power on the Archon and allow enough time for the GPS detection and home point setting to complete. In certain locations and conditions it may take several minutes to complete. The amount of time it takes will vary.

(2) Environmental conditions are preventing the Archon from detecting GPS satellites. Move the Archon to a different area.

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**PROBLEM:** The motors will arm but the Archon cannot take off.

**SOLUTION:** (1) Propellers incorrectly installed. See **Propeller Replacement** section.

(2) A motor may be defective. Look for a motor spinning slower than the others (or not spinning at all). Replace as necessary.

**PROBLEM:** Archon flies erratically.

**SOLUTION:** (1) The compass and/or accelerometers require calibration. Land the Archon and perform compass calibration and accelerometer calibration.

(2) There is magnetic interference in the area. Take the Archon to a new location being sure to perform compass calibration before flying.

(3) GPS signal is weak or intermittent. Take the Archon to a new location, being sure to perform compass calibration before flying.

(4) Windy conditions make it difficult for the Archon to maintain position and altitude. Wait for calmer conditions to fly.

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**PROBLEM:** Archon is shaking.

**SOLUTION:** (1) Check the canopy, chassis, motors and propellers for damage.

(2) Windy conditions make it difficult for the Archon to fly smoothly. Wait for calm conditions.

**PROBLEM:** The Archon does not maintain altitude when the throttle stick is in the center position.

**SOLUTION:** (1) Perform accelerometer calibration.

(2) Windy conditions make it difficult for the Archon to maintain altitude. Wait for calmer conditions.

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**PROBLEM:** The Archon does not RTH (Return-To-Home) when the flight mode is changed to HOME.

**SOLUTION:** (1) The motors were armed with the flight mode in ALTITUDE HOLD mode. Arming the motors in this mode will cause the Archon to not set a home point. In order to RTH automatically, be sure to arm the motors with the flight mode set to GPS mode. GPS signal must be acquired and the home point set (indicated by a solid red rear LED on the Archon) before the motors can be armed in GPS mode.

(2) GPS signal was lost prior to changing the flight mode to HOME (loss indicated by the GPS LED on the transmitter turning off and a continuous beeping). Without GPS signal the Archon cannot return to the home point automatically when switching to HOME mode. The Archon must be flown and landed manually by the pilot or wait until GPS signal is re-acquired. When GPS signal is re-acquired the GPS LED on the transmitter will stop beeping and the GPS LED on the transmitter will resume flashing slowly.

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**PROBLEM:** The Archon cannot climb in altitude during flight.

**SOLUTION:** (1) A motor may be defective. Look for a motor spinning slower than the others (or not spinning at all). Replace as necessary.

(2) The Archon has already reached its maximum altitude of 400 feet (122 meters) which is an FCC regulated altitude maximum.

## Video Problems

**PROBLEM:** There are missing or corrupt files on the memory card.

**SOLUTION:** Test the camera and confirm that the camera LED behavior matches the description in the **Taking Pictures and Videos** section. If yes, try formatting the memory card or using a different memory card. If no, review the steps for taking pictures and videos. Contact product support if the problem continues.

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**PROBLEM:** The monitor screen turns on but does not display video feed from the camera.

**SOLUTION:** (1) The monitor and camera are not operating on the same channel. Review the instructions for changing the monitor and camera channels and confirm both are operating on the same frequency.

(2) Confirm that the camera wire lead is secure to both the camera and Archon.

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**PROBLEM:** The FPV feed seen on the monitor is poor quality or intermittent during flight.

**SOLUTION:** (1) There may be interference in the area. Try flying in a different location.

(2) The practical range of the camera's video transmission has been exceeded. The range is dependent on outside factors such as the presence of power lines nearby, other radio controlled/FPV devices in the area, or any other possible source of electrical interference. Maintain a closer proximity to the monitor when flying.

(3) Try a different video band/channel (see **Monitor Control** and **Camera Frequencies** sections).

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**PROBLEM:** You recorded videos/pictures but there are no files on the memory card.

**SOLUTION:** The memory card was incorrectly inserted into the camera. Refer to Memory Card for instructions on the proper installation.

**PROBLEM:** Horizontal scrolling lines appear in video or pictures.

**SOLUTION:** Avoid aiming the camera directly into the sun or reflected sunlight.

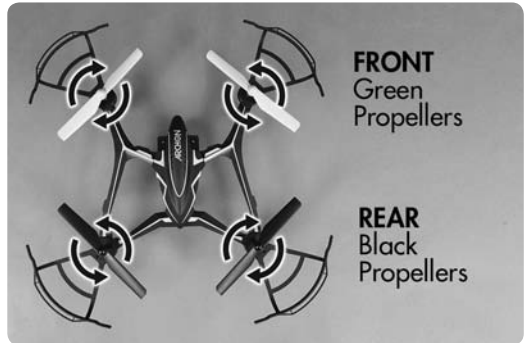
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## PROPELLER REPLACEMENT

1. Remove the screw that secures the propeller to the gear shaft.
2. Pull the propeller off the gear shaft.
3. Install the new propeller and secure it with the screw.



**NOTE:** The propellers have arrows that indicate which direction they rotate. Please refer to this diagram to verify that the correct replacement propeller is installed.



# PROP SHAFT REPLACEMENT



1. Remove the propeller from the prop shaft.
2. Remove the four screws from the black motor cover and lift it off the frame (if installed, the prop guard will also need to be removed before the motor cover can be removed). You do not need to disconnect the motor wires.
3. Slide the motor shaft out of the frame. Remove the screw securing the gear to the shaft. Slide the gear off the shaft.
4. Reinstall the parts in the same order in which they were removed.



**NOTE:** While the gear is out, check it carefully for any cracks or damage to the teeth.

# MOTOR REPLACEMENT

1. Remove the four screws from the black motor cover and lift it off the frame (if installed, the prop guard will also need to be removed before the motor cover can be removed).
2. Disconnect the motor connector. Grasp the motor by the gear with your fingertips and slide the motor out of the cover.
3. Slide the rubber banding off of the old motor and onto your replacement motor.
4. Reinstall the parts in the same order in which they were removed.



**NOTE:** There are clockwise and counter-clockwise rotating motors. Be sure that you are replacing a damaged motor with the correct part by confirming the wire colors of the replacement motor match the motor wires you are removing.

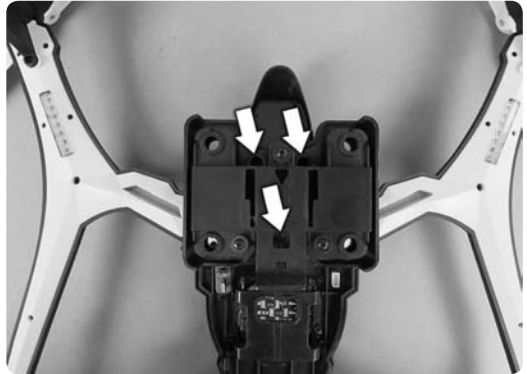
## FLIGHT CONTROL BOARD REPLACEMENT

Replacing the flight control board is not a difficult procedure, but there are many screws that need to be taken out to remove the flight control board from the quad. Have a clean work space prepared and we recommend using a container to hold all the screws.

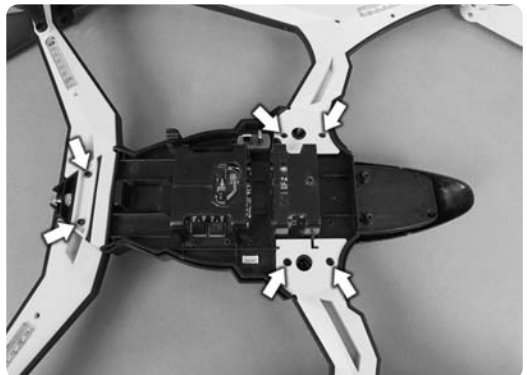
1. If equipped, remove the camera by pushing down on the camera retainer tab and sliding the camera forward. Disconnect the camera wire from the quad.



2. Remove the three camera mount screws and lift the camera mount off the frame.



3. Remove the six screws securing the canopy and lift the canopy off the frame.



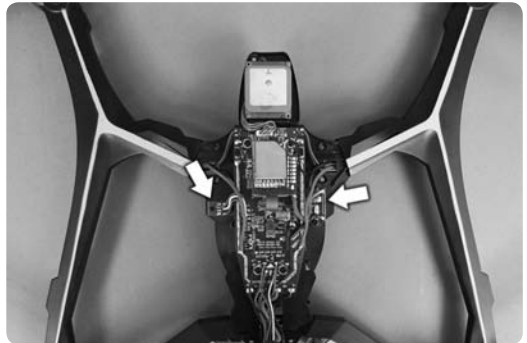
4. There are four screws holding each motor cover to the frame. Remove **all** four motor covers from the frame. The motors should come out with the covers. Disconnect the motors and set the covers aside. We recommend labelling each cover so they are installed back in the correct locations.



5. Remove the three frame bottom covers from the underside of the frame. Make note of the different screw sizes used when removing the covers. Carefully push the LED lenses out of the frame bottom covers.

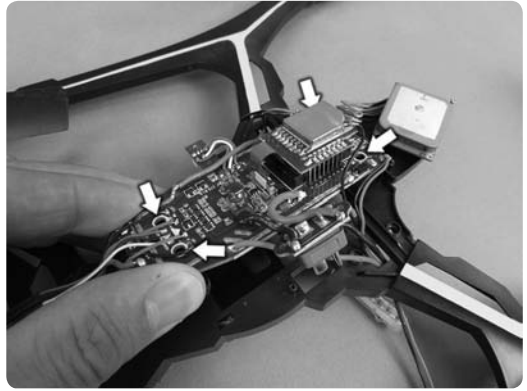


6. Unscrew the camera connector and the battery connector from the frame.



**NOTE:** Before moving on to step 7, take a close look at how the wires and LEDs are positioned in the frame. Take a picture if possible for future reference. The wires should be reinstalled with the new board as they are currently placed.

7. There are four screws that secure the flight control board to the frame. These screws are different than the other screws removed so far. Make sure you use them in the correct location during reassembly. Lift the board off the frame and start feeding the wires out through the holes in the frame. If the foam sleeves come off, slide them back on to the screw bosses.



8. Reassembly is the reverse of steps 1-7. Take care when installing the covers to not pinch or sever the wires with screws. If a part does not feel like it is fitting back into place properly, do not force it. Check that the part is properly aligned and that the wires are not interfering with the installation.
9. Before attempting to fly your Archon, recalibrate the compass and accelerometers.

## **FCC ISEDC PRECAUTIONS**

### **Archon**

**Brand:** RISE

**Part number:** RISE0300

**FCC ID :** IYF0300

**IC:** 11104A-0300

### **RISE J2020 6-Channel Transmitter**

**Brand:** RISE

**Part number:** RISJ2020

**FCC ID :** IYFJ2020

**IC:** 11104A-RISJ2020

(Notes: 6 channels mean different functions.

Below are the list for each channel:

1. control the drone right and left flight
2. control drone front and backward flight
3. control drone rotate to right or left
4. control flight mode of drone
5. control the throttle of drone to fly slow or fast
6. control the dual drone to react slow or fast.)



### ISED Warning :

This device complies with ISED licence-exempt RSS standard(s). Operation is subject to the following two conditions:

- (1) this device may not cause interference, and
- (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Le présent appareil est conforme aux CNR d'ISED applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes : (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement

### ISED Radiation Exposure Statement:

This equipment complies with ISED RF radiation exposure limits set forth for an uncontrolled environment. This transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.

For RISE0300, this equipment should be installed and operated with minimum distance 20cm between the radiator & your body.

Cet appareil est

conforme aux limites d'exposition de rayonnement RF ISED établies pour un environnement non contrôlé.

Cet émetteur ne doit pas être co-implanté ou fonctionner en conjonction avec toute autre antenne ou transmetteur

pour RISE0300. Cet équipement doit être installé et utilisé avec une distance minimale de 20cm entre le radiateur & votre corps.

Any Changes expressly or modifications not approved by the party responsible for compliance could void the user's authority to operate the equipment.

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference,
- and (2) this device must accept any interference received, including interference that may cause undesired operation.

### FCC Radiation Exposure Statement:

This equipment complies with FCC radiation exposure limits set forth for an uncontrolled environment .

This transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.

For RISE0300, this equipment should be installed and operated with minimum distance 20cm between the radiator & your body.

**NOTE:** This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

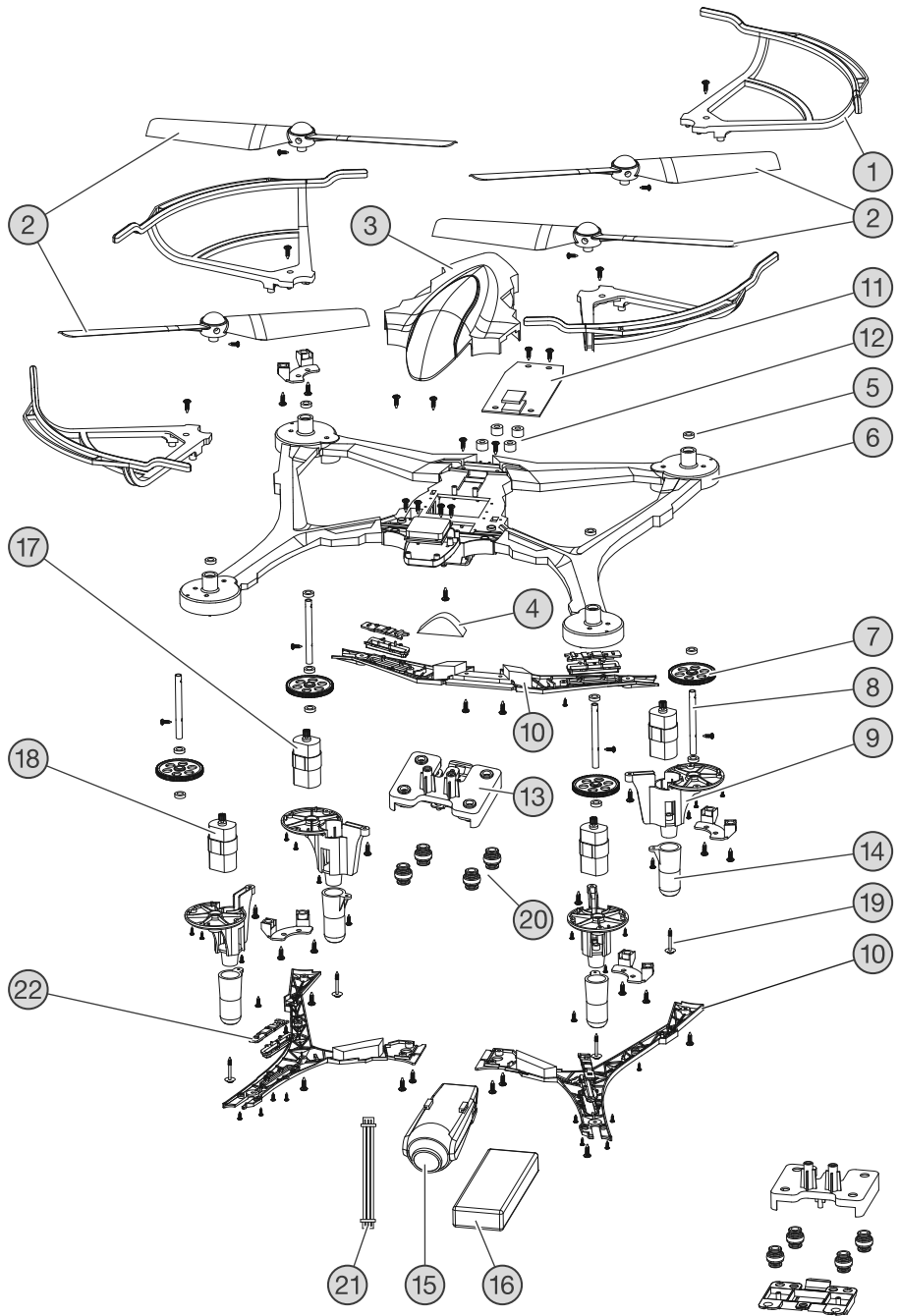
- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

The device compliance with FCC part 97 requirement.

License required for each device when use.



# EXPLODED VIEW



**RISE**<sup>TM</sup>  
**explore-rise.com**