CHAPTER 8. PRODUCT SPECIFICATIONS

8.1 General

Type: RA51, RA52, RA53, RA54 and RA55

Power supply voltage and power consumption

Power supply voltage: 24Vdc (nominal)(10.2 to 41.6 Vdc)

Power consumption: 75 W or less (RA51) 90 W or less (RA52)

100 W or less (RA53) 110 W or less (RA54)

Power supply voltage: 24Vdc (nominal)(18.0 to 41.6 Vdc)

Power consumption: 200 W or less (RA55)

Distance range: 0.125 to 36 NM, 10 ranges (RA51)

0.125 to 48 NM, 10 ranges (RA52) 0.125 to 64 NM, 11 ranges (RA53) 0.125 to 72 NM, 11 ranges (RA54) 0.125 to 120 NM, 12 ranges (RA55) (Continual variable range also possible)

Distance resolution: Within 25 m

Distance accuracy: Better than 0.9% of maximum range of the scale

in use, or 8m, whichever is the greater

Minimum detecting distance: Within 25 m

Bearing resolution: Within 4.5° (RA51)

Within 3.0° (RA52 with 3 ft antenna)

Within 2.5° (RA52/53/54/55 with 4 ft antenna) Within 1.8° (RA53/54/55 with 6 ft antenna)

Bearing accuracy: 1° or less

Warm-up time: 2 minutes

Environment conditions

Ambient temperature range (S/U): -25 to 55°C

(D/U): 0 to 55°C

Humidity: 93% RH at +40°C

Vibration: (S/U): 3 mm(300 to 500 rpm)

1.2 mm(500 to 1500 rpm) 0.3 mm(1500 to 3000 rpm) 14.7m/s2(1.5G) Resonance test

(D/U): 3 mm(300 to 500 rpm)

0.75 mm(500 to 1500 rpm) 0.2 mm(1500 to 3000 rpm)

Wind resistance: 100 knots (max.)

Waterproof standard: (D/U): IPX-5

(S/U): IPX-6

Interconnecting cable: 100 m in max. Noise: (D/U): 65 dB or less

(S/U): 65 dB or less (RA51)

(S/U): 70 dB or less (RA52/53/54/55)

8.2 Scanner Unit_

Type: RB715A (RA51)
RB716A (RA52)
RB717A (RA53)
RB718A (RA54)

RB719A (RA55)

Antenna type: Slotted-array

Antenna characteristics

Beam width (horizontal): 3.9° (RA51)

 $2.5^{\circ} \pm 0.3^{\circ}$ (RA52 with 3ft antenna)

 $1.8^{\circ} \pm 0.2^{\circ}$ (RA52/53/54/55 with 4ft antenna) $1.2^{\circ} \pm 0.2^{\circ}$ (RA53/54/55 with 6ft antenna)

Beam width (vertical): 25° (typ.) (RA51)

22° (typ.) (RA52 with 3/4ft antenna) 22° (typ.) (RA53/54/55 with 4/6ft antenna)

Pulse width and peak power output:

RA	51/52	RA53	
Pulse width (µsec)	Peak Power (kW)	Pulse width (µsec)	Peak Power (kW)
0.08	4 (-50% to +20%)	0.08	6 (-50% to +20%)
0.25	4 (-50% to +20%)	0.3	6 (-50% to +20%)
0.8	4 (-50% to +20%)	0.6	6 (-50% to +20%)
		1.0	6 (-50% to +20%)
R	A54	RA55	
Pulse width (µsec)	Peak Power (kW)	Pulse width (µsec)	Pulse Power (kW)
0.08	12 (-50% to +20%)	0.08	25 (-50% to +20%)
0.3	12 (-50% to +20%)	0.3	25 (-50% to +20%)
0.6	12 (-50% to +20%)	0.6	25 (-50% to +20%)
1.0 12 (-50% to +20%)		1.2	25 (-50% to +20%)

Radio wave type and frequency: P0N, $9410 \pm 30 \text{ MHz}$

Antenna revolution: 24 rpm or 48rpm (RA51)

24 rpm or 48rpm(24Vdc or more) (RA52)

24 rpm or 48rpm (RA53/54/55)

Transmit/receive switching: Circulator and limiter type

Intermediate frequency: 60 MHz (logarithmic amplifier)

Noise figure: 6.5 dB or less

8.3 Display Unit_ RF720A /720B Type: Indication system: PPI, PPI+semi-3D, Split radar range Indicator: 15-inch TFT color LCD 640 x 480 dots Four (4) levels **Cursor Control:** Analog cursor key and rotary encoder VRM: 2 lines (One line can be offset.) Unit of distance can be selected from NM, KM, and SM. EBL: 2 lines (One line can be offset.) Display modes: HU, HS, NU, CU, and TM Off-center: Can be 100% off-centered over the full range. Guard zone: Can be set at any desired distance and angle in any desired width. IN and OUT modes are available. Stretch: 2 modes Echo track: 15, 30 sec, 1, 3, 6 min. and continuous. Other functions: Interference rejection, Zoom, Sleep mode, Hold mode, Course error display, Parallel cursors, Stern marker, and Navigation data display mode Four (4) levels Panel brightness:

Chinese, Danish, English, French, German,

Japanese,

Korean,

Spanish,

Italian,

Swedish, Turkish, and Thai

Norwegian, Portuguese, Russian,

Greek,

Language support:

8.4 External Interface_____

NMEA0183: 2 channels

(One standard channel; Optional cable is

required for 2nd-channel connections)

L/L GGA, GLL, RMA, RMC

Heading HDT, HDG, HDM, HCC, VHW, VTG

Speed VHW, VTG, RMA, RMC

Way point RMB, BEC, BWC, BWR, BER, BPI

Depth DBT, DPT Course error RMB, XTE

Seawater temperature MTW

Magnetic compass variation RMA, RMC, HDG, HVD, HVM

Others (using optional cable):

External buzzer control output, Auxiliary indicator connecting signal output and input, Bow direction signal input(SIN/COS signals), and compass interface (10/12 bits serial)

8.5 Standard set_

Display unit 1
Scanner unit 1
Display cover 1
Fuse 1 set

Interconnecting cable 1 (10m for RA51/52/53/54, 15m for RA55)

Power supply cable 1 (2m) M10 hexagonal bolt 4 sets (for RA51)

M12 hexagonal bolt 4 sets (for RA52/53/54/55)

8.6 OptionsInterconnecting cable (15, 20, and 30 m) Flush-mount installation kit Junction box for external connection (with cable 1.5m) 249J153058 Option connector kit

8.7 External dimensions and weight_____

See APPENDIX

8.8 External Connection and function_____

X1 Connector for Option

<i>,</i> \		ctor for option	
	Pin No.	Name	function
		N	N (74 10 1
	1	NMEA2-A	NMEA ch2 data input (A)
	19	NMEA2-B	NMEA ch2 data input (B)
	2	GND	
	20	EXBUZ+	Output for External Buzzer
	3	EXBUZ-	Output for External Buzzer
			Controlled ship's power output
	21	VIDEO_IN	Video input for Monitor operation
			0 to -1V negative video, Zi = 50ohm
	4	VIDEO_OUT	Video output for External Monitor
			0 to -1V negative video, Zo = 50ohm
	22	GND	
	5	TRIG_IN	Trigger signal input for Monitor operation
			0 to 5V positive pulse, rising edge
	23	TRIG_OUT	Trigger output for External Monitor
			0 to 5V positive pulse, rising edge
	6	SHF_IN	Heading signal input for Monitor operation
			0 to 5V negative pulse, falling edge
	24	SHF_OUT	Heading signal output for External Monitor
		_	0 to 5V negative pulse, falling edge
	7	AZI_IN	Bearing Pulse input for Monitor operation
		_	0 to 5V positive pulse, rising edge
	25	AZI_OUT	Bearing Pulse output for External Monitor
		_	0 to 5V positive pulse, rising edge
	8	GND	
	26	GYRCK+	Gyro Interface clock (+) input
	9	GYRCK-	Gyro Interface clock (-) input
			apply 5V pulse between (+) and (-), isolated
	27	GYRDT+	Gyro Interface data (+) input
	10	GYRDT-	Gyro Interface data (-) input
			apply 5V pulse between (+) and (-), isolated
	28	GND	
	11	MARK_I	External Marker signal input, ex) Radar Buoy
		<u> </u>	negative video, 0 to -1V Zi = 50ohm
	29	+12V	External interface power, 100mA max.
	12	SIN	Compass Interface for SIN/COS type
	30	COS	Compass Interface for SIN/COS type
	13	REF	Compass Interface for SIN/COS type
			SIN/COS signal: SIN = REF±1V, COS = REF±1V
	31	LOG	Dry contact log pulse input
	14	GND	J
	32	NMEA_OUT	NMEA data output, ex) MOB data, TARGET data
			saca varpar, on, mos accu, minosi accu