At this point you should set the transmitter's modulation to the receiver which you will be using. If your receiver is an Rx 12 DS you don't need to make any changes. You can move straight on to point 4.3.

Button Effect	
	Enter the menu cycle
⊕ ⊕	On to "menu 4"
	On to "Select transmission mode"



	Open modulation field (flashes)
	Select PPM 7, PPM 9, PPM 12 or PCM/A with ⊕/⊡ or the Digi-adjustor
0	Open the neutral point field (flashes)
●/⊟	Select MPX (=MULTIPLEX) = 1,6 ms or OTHER = 1,5 ms
	Back to the operating screen

# 4.3 Checking the control assignments

In the "Trainer 120 deg" base type the transmitter controls are assigned as follows:

Control	operates	Note
Α	YAW	
В	PITCH-AXIS	
С	ROLL	
D	COLLECTIVE PITCH	No trim!  Collective pitch max. FORWARD
E	MIXTURE	L.H. slider
F	IDLE UP	R.H. slider
G	REGULATOR	Switch

If this arrangement suits your preferred flying mode, you can move on directly to point 4.6 "Connecting servos".

# 4.4 Changing the control assignments

Note: the controls will be interchanged!

For example, if you assign ROLL to transmitter control A, YAW will automatically be switched to control C. This prevents the danger of assigning two different transmitter controls to one function.

Button	Effect	_
	Enter the menu cycle	
•	On to "Menu 2 assign"	
0	On to the "Assign controls" menu	_



Repeat the next two steps until the control arrangement meets your requirements.

Open the CONTROL field
 Select the control with ⊕/⊟ or the Digi-adjustor
Open the OPERATES field
 Select the function with ⊕/□ or the Digi-adjustor

And when you are finished:

Back to	the	operating	screen	
	-	The second secon		 -

# 4.5 Changing the COLLECTIVE direction

Button	Effect
	"Hot key" to the "Adjust controls" menu Select the COLLECTIVE PITCH control with 1/1 or the Digi-adjustor
	Open the "Options" field  Lead through with ⊕/⊡ or the Digiadjustor until "PITCH-MAX" appears



Open select field
Select FRONT or REAR with 19/19
Back to the operating screen



#### 4.6 Connecting servos

The servos must be connected as stated in the table below. This arrangement cannot be altered!

For the "Trainer 120 deg" base type you must connect the servos in your model as follows:

Servo No.	ls	Note
1	DYN. THR.	
2	HEAD MIX	front right
3	HEAD MIX	rear
4	TAIL MIX	
5	SPEED REG	Nominal value for speed regulator
6	HEAD MIX	front left
7	GYR0	Channel for gyro sensitivity
8	RETRACT	* Reserve, no control
9	9 MIXTURE L.H. :	
10	AUX-1 *	
11	AUX-2	*
12	AUX-3	*

For helicopters all 12 possible servos are always assigned. The reason for this is that you cannot alter the servo assignment for the helicopter base types.

### 4.7 Checking (matching) mixer inputs

In the "Travel and switches" menu you can do the following:

- · set mixer input values,
- · reverse mixer inputs, and
- · assign switches to the mixer inputs.

This is the procedure:

Button	Effect
	"Hot key" to "Travel + switches" menu ("TRAV+SW")



You have to repeat the following steps for all serve

to repeat the femouring deeper for all serve
Open servo select field
Select servo with <b>1</b> ∕ □ or the Digiadjustor
Open INPUT field
Select input with ●/□ or the Digiadjustor
Open adjust field
Move associated transmitter control
Reverse mixer input with III
Adjust mixer input with ●/☐ or the Digi-adjustor
Open Switch field
Select OFF/ON or a switch

The brackets round the buttons indicate that you on have to make changes here if it is necessary.

Once everything is as you want it:

Back to the	operation	ooroon	
Dack to the	operating	SCIGALI	