OKIN REFINED	Issue department: Bedding Division	Date:	2017-05-03
	ProductFunction instruction	Author:	Kyle
		No: CB1120	
A Phoenix Mecano Company			
	Version:	1. 1	
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# **CB1120Function instruction**

## 1. Electrical configuration diagram:

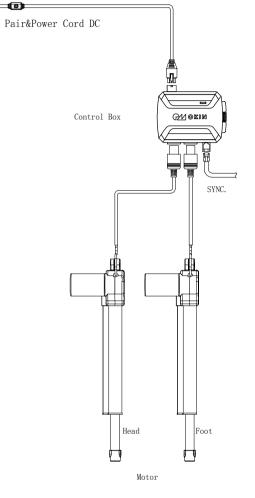
### 2. Function Picture





	Remote model (RF2005)		
1	R5. 504. 01. 250	Power Cord AC	1
2	JLDP. 10. 023. 000	Power Supply	1
3	R5. 217. 01. 013	Pair&Power Cord DC	1
4		Synchronization Cable	
5		Control Box	1
6		Motor/(Head&Foot)	2
7	RF2005	Remote model	1

Power Cord AC



Power Supply (JLDP. 10.023.000)

System-d	Irawing				
				CB1120	
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Checked					A Phoenix Mecano Company

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#### 1. Process of test

#### 1.1. HEAD MOTOR

Connect to head actuator, control by remote single:

Click head up button on the remote, head actuator moves out, stop when released;

Click headdown button, head actuator moves in, stop when released;

This function takes effect only by pressing the corresponding button on the remote.

#### 1.2. FOOTMOTOR

Connect to foot actuator, control by remote single:

Click foot up button, foot actuator moves out, stop when released;

Click foot down button, foot actuator moves in, stop when released;

This function takes effect only by pressing the corresponding button on the remote.

#### 1.3. SYNC port

Connect with the same other Control box or Other accessories;

#### 1.4. Power LED& PAIRING LED

Power supply for control box, PAIRINGLED of control box is blue, POWER LEDis green o

#### **1.5.** Power

Connect to the 29V DC;

#### 1.6. RESET button

Press and hold the RESET button, the Head, Foot actuators will moves to lower position.

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#### 1.7. Pair Function

Double click RESET button, pairing LED turns on, the control box enters into mode of code paring;

Press and hold the paring LED of Remote, the backlight of paring LED flashes, the backlight of remote flashes, the remote enters into mode of code paring;

The backlight of paring LED of remote stops flashing, and the paring led of control box turns off, it indicates that the code paring is successful;

If fails, repeat all the processes above;

#### 1.8. FLAT function

Press and release the FLAT buttonon remote, the head and foot actuators moves to lower position(when the actuator is free, can turn off the vibration motor and turn off the indicator light when press once ), stop when press any buton;

This function takes effect only by pressing the corresponding button on the remote.

#### 1.9. ZERO G position function

Press and release ZERO G button on remote, the head and foot actuator moves to preset memory position, stop when press any button;

This function takes effect only by pressing the corresponding button on the remote.

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#### FCC:

Any Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

#### **ISED RSS Warning:**

This device complies with Innovation, Science and Economic Development Canada licenceexempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Le présent appareil est conforme aux CNR d'ISED applicables aux appareils radio exempts de licence.

L'exploitation est autorisée aux deux conditions suivantes:

- (1) l'appareil ne doit pas produire de brouillage, et
- (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.