

# **Micropulse Transducers BTL/BIW** Linear position sensing – high precision with extreme reliability



## Micropulse Transducers

Linear position sensing for greater efficiency





With over 50 years of sensor experience, Balluff is a leading global sensor specialist that has developed well-engineered distance measurement technology and its own line of connectivity products for every area of factory automation. Balluff is based in Germany and has a tight international network of 54 representatives and subsidiaries.

Balluff stands for comprehensive systems from a single source, continuous innovation, the most modern technology, highest quality and greatest reliability and prides itself on distinctive customer orientation, custom-tailored solutions, fast worldwide service and outstanding application assistance.

High-quality, innovative products tested in our own accredited laboratory and a quality management system certified according to DIN ISO 9001 (EN 2008) form a secure foundation for optimized added value for our customers and reliable partnership with deliveries and logistics organized according to requirements.

Whether electronic and mechanical sensors, rotary and linear transducers, identification systems or optimized connection technology for high-performance automation, Balluff masters not only the entire technological variety with all of the different operating principles, but Balluff technology fulfills regional quality standards and is suitable for use worldwide. Wherever you are in the world, Balluff technology is never far away. You won't have to look far for you nearest Balluff expert.

Balluff products increase performance, quality and productivity around the world every day. They satisfy prerequisites for meeting demands for greater performance and cost reductions on the global market. Even in the most demanding areas. No matter how stringent your requirements may be, Balluff provides state-of-the-art solutions. Fully exploit the potential of high quality with sophisticated distance measurement technology for greater efficiency

II Id







## F **Basic Information and Definitions** 17 **Profile Series** 29 **Rod Series** 73 101 **Compact Rod and AR Rod Series** EX Rod and T Rod Series 127 SF Rod Series 141 147 Accessories 1562

**Micropulse Transducers** 

Alphanumeric Directory Worldwide Sales

# MCROPULSE®

164

168

### **Micropulse Transducers**

Overview Linear position sensing

# MCROPULSE®

Magnetic linear encoder system BML - High precision and extended lengths



BML 48000 mm

Micropulse transducers BTL/Inductive linear position sensor BIW - Extremely robust and reliable



BTL/BIW 7500 mm

Photoelectric distance sensors BOD - Independent of material and color



BOD 6000 mm

Magneto-inductive position sensors BIL - Compact and absolute



SIL 160 mm

Inductive distance sensors BAW - For short strokes

BAW 20 mm

**Micropulse Transducers** Overview Linear position sensing



## - Full-range assortment for greater flexibility Greater efficiency with optimized solutions

- Superior distance measurement technology for increased productivity



una kunana kunan kunan kunan ku











#### Balluff distance measurement the right solution for you

Balluff distance measurement offers efficient individual solutions that are adapted to your specific requirements.

Different working principles are available for distances from

1 to 48000 mm and resolutions from 1 to 100  $\mu m.$ 

From position detection to distance measurement.

Fully exploit the benefits available. Choose the option that's right for you and increase your added value with superior Balluff distance measurement technology. Robust industrial Balluff distance measurement technology is accurate, reliable, non-contact, wear-free and brings out the best from your machines.



F







## **Micropulse Transducers**

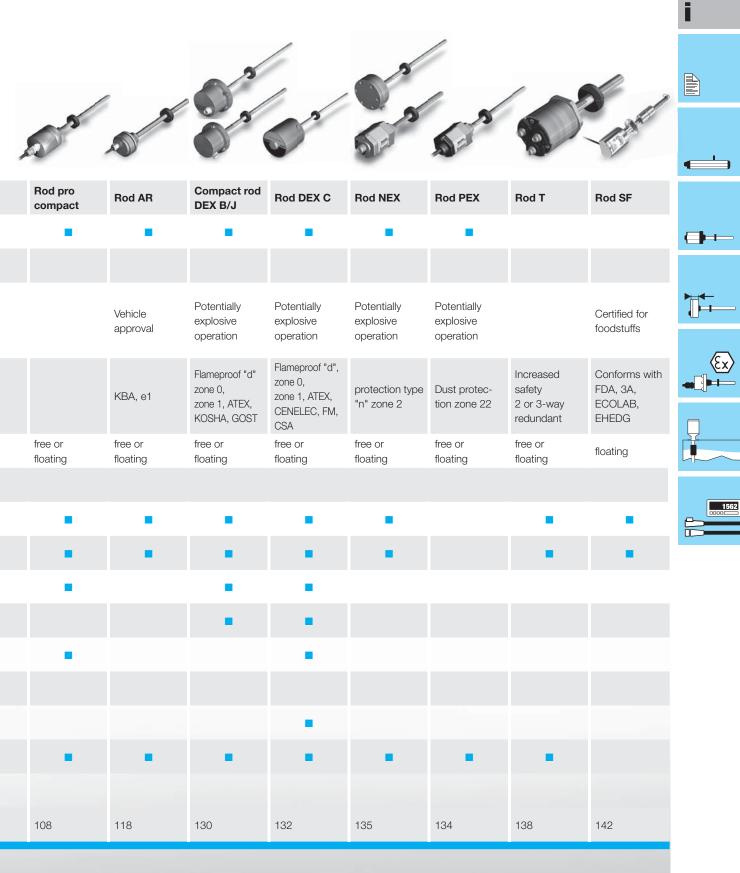
Overview Distance measurement

						02	
	01			A SURT	The state	5	
Series	Profile P	Profile PF	Profile A1	Profile BIW	Rod B, A, Z, Y	Rod compact	
Internal fitting version e.g. in hydraulic cylinders							
External fitting version e.g. on machine frames							
Filling level sensor e.g. device filling systems							
Special approvals							
Magnet	free/captive	free/captive	free	captive push rod	free or floating	free or floating	
Interfaces							
Analog voltage 010 V, 100 V, –10 V+10 V				•	•	-	
Analog current 420 mA, 020 mA					1.0		
SSI					•	•	
SSI-SYNC	•				•		
CANopen	•				•		
DeviceNet	•						
PROFIBUS-DP	•						
Start/Stop pulse interface					1.0		
VARAN							
From page	30	48	56	68	74	102	



## Micropulse transducers BTL Inductive linear position sensor BIW ... extremely robust and reliable

Micropulse Transducers Overview Distance measurement



MCROPULSE®

## **Distance Measurement**

Summary Magneto-inductive distance sensors

		Comme Comme	SMARTSENS	SMARTSENS
Magneto-indu distance sens		Micro-BIL	BIL 60	BIL 160
Working range		010 mm	060 mm	0160 mm
Resolution			±0.15 mm	±0.4 mm
Linearity		±0.3 mm	±1 mm	±2.4 mm
Repeat accura	су	±30 µm	±60 μm	±0.5 mm
Housing size		28×6.2×4.4 mm	95×15.2×15.2 mm	230×15.2×15.2 mm
Output	010 V	100 B		100 B
- stbat	420 mA			
Special feature	S	Mounted in T-slot		

Magneto-inductive distance sensors BIL ... compact and absolute



Refer to our Linear Position Sensing catalog for more information on BIL magneto-inductive position sensors or visit our website at www.balluff.com



**Distance Measurement** Overview Magnetic linear encoder system

f

€x> ➡

1562



Magnetic linear encoder system BML	BML-S1AQ digital	BML-S1AA analog sin/cos, 1 V <sub>ss</sub>	BML-S1FQ digital	BML-S1FA analog sin/cos, 1 V <sub>ss</sub>	BML-S1B0-Q digital	BML-S1E0-Q digital	BML-S1C0-Q digital	
Resolution	110 µm		110 µm		550 µm	550 µm	1002000 µm	
System accuracy	±10 μm/ ±20 μm	±10 μm/ ±20 μm	±10 μm	±10 μm	±50 μm/ ±60 μm	±100 µm	±100 μm	
Distance to tape	0.1 0.35 mm	0.1 0.35 mm	0.1 0.35 mm	0.1 0.35 mm	0.12 mm	0.12 mm	0.12 mm	
Digital output signal RS422 (TTL)	. •		•		•	•		
Digital output signal HTL (as operating voltage 1030 V)					•	•		
Analog output signal os (1 $V_{ss}$ )		•		•				
Linear tape up to 48 m	•	•	•	•	•	•	. •	
Rotary magnetic tape (mag- netic ring) Ø 30300 mm						•	$\sim 10^{-1}$	

Magnetic linear encoder system BML ... high precision and extended lengths

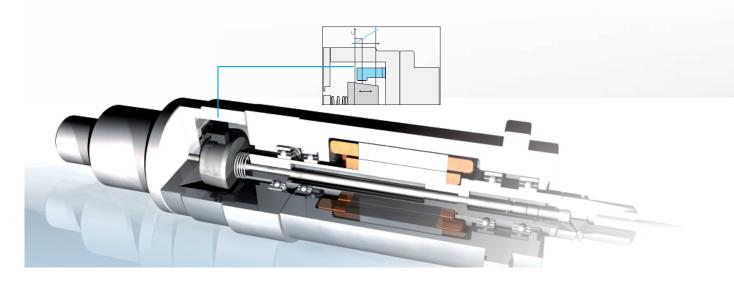


### **Distance Measurement**

Overview Inductive distance sensors

		1					
Inductive dista BAW	ince sensors	BAW Ø 6.5 mm	BAW M12	BAW M18	BAW R03	BAW PG 36	BAW 80×80 mm
1.1	Flush	0.52 mm	0.52 mm	15 mm	14 mm	020 mm	
Linear range	Not flush		14 mm	216 mm			050 mm
Housing size		Ø 6.5 mm	M12×1	M12×1	10×30×6 mm	PG 36	80×80 mm
Output	010 V 020 mA 420 mA				•	•	
Connection	Connectors						
Connection	Cable						
Special features				Teachable switching output			





**Distance Measurement** Overview Photoelectric distance sensors

f

1562

		į.	5 M	P	BALLAR	BAUUFF	
Photoelectric distance sens		BOD 6K	BOD 18K	BOD 26K	BOD 63M	BOD 66M	
Distance senso measuring rang		2080 mm	50100 mm	4585 mm 30100 mm 80300 mm	2002000 mm 2006000 mm	100600 mm 2002000 mm	•
Diffuse sensor with backgrour	measuring range nd suppression	2080 mm		30100 mm 80300 mm	2002000 mm 2006000 mm	100600 mm 2002000 mm	
Housing size		20 × 32 mm	M18×1	50 × 50 mm	90 × 70 mm	73 × 90 mm	
Outeut	010 V						
Output	420 mA						- <b>C</b>
Occurrention	Connectors						
Connection	Cable						Ţ
Special feature	S	Teachable switching output		Teachable switching output, adjustable measuring range	Teachable switching output	Teachable switching output	

# Photoelectric distance sensors BOD

... independent of material and color



## **Micropulse Transducers**

Applications

Micropulse transducers are perfect for applications that require a high degree of reliability and precision.

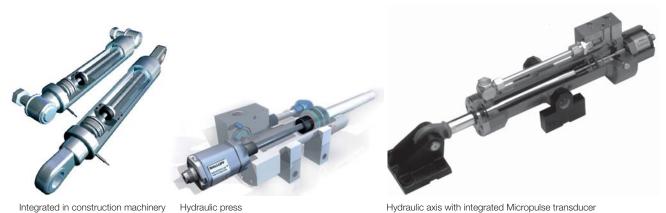
Suitable for measurement lengths between 25 and 7500 mm, integrable and compact Micropulse displacement systems are extremely versatile.

The non-contact working principle of the systems ensures a complete absence of wear and a virtually endless service life. The highprecision output signal serves as an absolute signal for the controller in a wide range of different interfaces.

Integrated in the pressure section of hydraulic cylinders, Micropulse transducers are used as displacement systems for position sensing in a wide variety of sectors.

#### **Application areas:**

- Pitch movement on wind generators
- Monitoring reflection channels on thermosolar power stations
- Large hydraulically powered valves
- Casting and rolling millsLift controls
- Flight simulators
- Foundries
- Logging machines
- Automation engineering
- Hydroelectric power stations
- Locks and floodgates
- Construction machinery
- Combine harvesters



Integrated in construction machinery

Hydraulic axis with integrated Micropulse transducer





Micropulse Transducers Applications



Wind power generator

Sawmill machinery

i

€x) ■■■

1562

Hydraulic riveting system

www.balluff.com

## **Micropulse Transducers**

Applications

In the automation of a wide range of different machine types, the most important requirements include maximum precision, no wear, easy installation, a high degree of protection and a low price. Micropulse transducers in a profile housing fulfill requirements in the automation industry 100 %.

#### Application areas:

- Injection molding
- Presses
- Handling systems
- Portal robots
- Woodworking machinery
- Packaging machines
- Conveying
- Leveling machines
- Operating tables
- Concrete blockmaking machines



#### Equipped for the future !

- Extremely flexible
- Product changes using keyboard
- Longer cycle times
- Increased availability
- Short set-up times
- Downtimes prevented
- Greater degree of automation

are just some of the requirements designers and developers must fulfill for future machine generations.

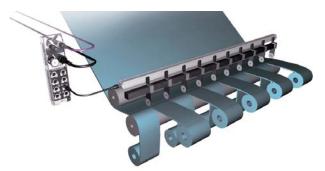
## The perfect solution for your application !

From the Balluff full-range assortment of distance measurement technology, we can work out the most economical and technically appropriate solution for you.

#### Competent

application consultation:

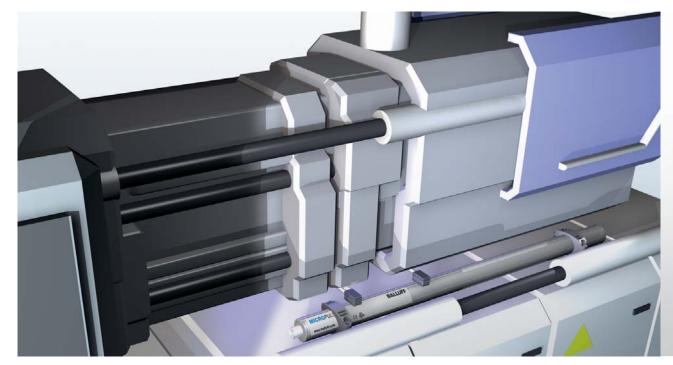
Phone: +49 7158 173-370 or +49 7158 173-777 tsm@balluff.de bzw. service@balluff.de



Film slitting machine



Injection molding machine



**Micropulse Transducers** Applications

1562

f



Multiple-stage press



Automation engineering



Concrete construction machinery



Laundry press

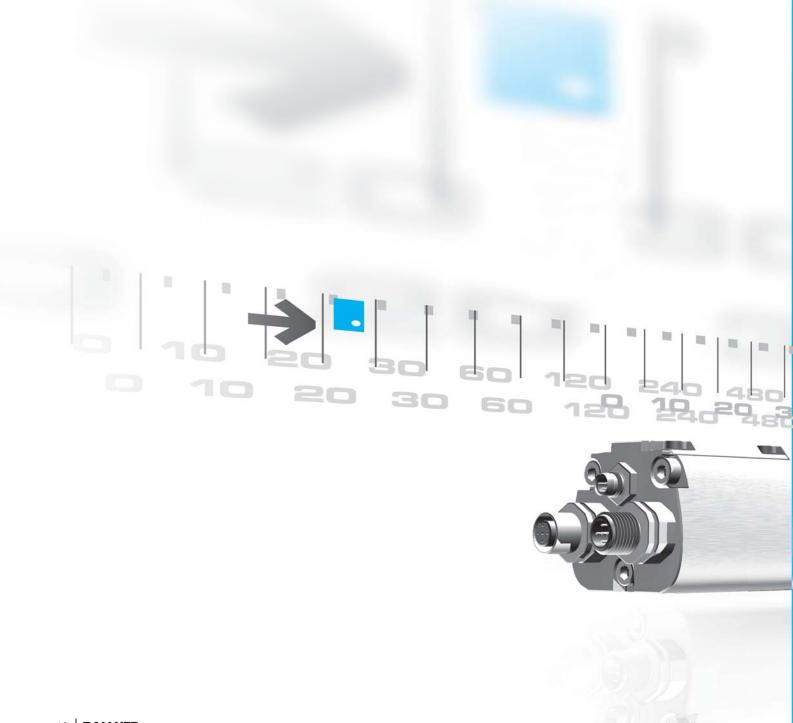


Level monitoring

The non-contact magnetostrictive working principle is also ideal for special applications.

#### Application areas:

- Process technology
- Filling of foodstuffs
- Level monitoring in milk tanks
- Dosimetry
- Perfume manufacture
- Pharmaceuticals
- Alcohol production





Definitions	18	
	10	
Principles of operation	21	
Housings	22	
Interfaces	24	
Quality and service	26	

BALLUFF

1**220<sup>2</sup>3846<sup>3</sup>9**6260 14268 3848

328004

960 960

BALLUFF

**MICRO**PULSE®

MICROPULSE

BALLU



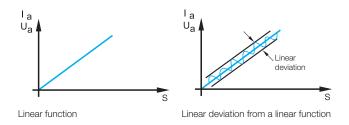
Output signal, characteristic curve, resolution, sensitivity

The characteristic curve describes the relationship between the output signal and the input signal. The slope of the curve represents the sensitivity of the device.

The sensitivity (resolution) is the quotient of the input signal change and the change in the output signal. On Micropulse transducers, the input signal change is the change in the position of the magnet and the output signal change is the change in the electrical output signal.

#### Linearity

A measuring device has a linear characteristic curve and a constant sensitivity when the relationship between the input and output variable is represented by a straight line (linear function). Linear scales are assumed for the X and Y-axes. A characteristic curve is not linear if it is not a straight line.

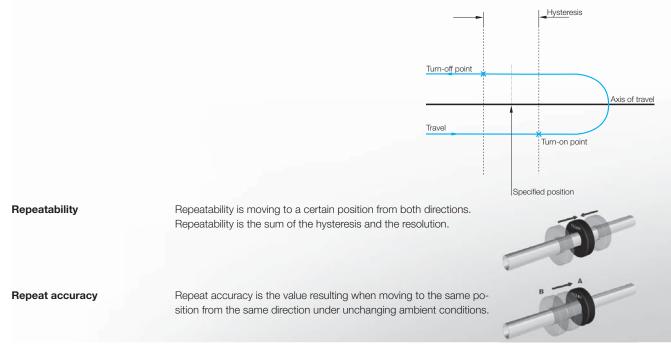


#### Non-linearity

Non-linearity is the maximum deviation from a straight line which connects the null point of the measuring range with the end point (full scale). There is a linear relationship between the position or stroke to be measured and the output signal for a voltage, current or digitized information. The linearity curve of magnetostrictive transducers does not change during the life of the system. The curve however can be corrected.

Hysteresis

Hysteresis is the signal difference resulting when arriving at a certain position, traveling beyond it and then returning to this position from the other direction.





SYNC mode	The absolute positioning information of the displacement system is established and transmitted synchronously to the read cycle of the processing electronics, e.g. an axis controller or a regulating control- ler.	
Incremental	After the system is switched off, the measured value currently avail- able is not retained. A reference run to a defined point is necessary in order to obtain a position value. The position value is calculated by adding or subtracting single identical increments from the reference point.	
Absolute	The measured value for the current position is available immediately after the system is switched on. An absolute coded digital signal or an analog value is assigned to each position, e.g. along a wave- guide. A reference run is not required.	
Temperature coefficient, formula	The temperature coefficient is the relative change of a physical quantity with changing temperature. The temperature dependence of a physical quantity y can be approximated at least for a limited temperature range by using the temperature coefficient $\alpha$ with a linear relationship y = y <sub>0</sub> (1 + $\alpha$ * $\Delta$ T).	
Temperature coefficient	The temperature coefficient indicates the relative change in length as temperature changes. This means that temperature factors change the output value by the indicated amount.	
Null point	The null point is the position with the lowest output value along the measuring range. For some transducer models the null point can be set by the user. The null point must lie within the measuring range.	
Sampling rate	The sampling rate is the frequency at which the output information is updated. It can be the same as the number of measurements per second. A high sampling rate for rapidly changing positions is important when the process is time-critical.	
Nominal stroke	The nominal stroke is the usable area along the transducer, and is represented by the length indication in the part number (see also Characteristic curve). The nominal stroke is always shorter than the overall length of the transducer.	
Damping zone	The damping zone is the area in which the second (undesired) magnetostrictive wave is damped. This area is always outside of the measuring range. Depending on the transducer model, either an erroneous output signal or an error signal will be output if the magnet is allowed to travel into this zone, which must not be considered valid information.	

Intrinsically safe "i" Coding "Ex i"	A circuit is intrinsically safe if it does not permit a spark or thermal effect which could ignite an explosive atmosphere as defined by Group IIA, IIB or IIC, whereby the test conditions prescribed in the standard must be applied. The test conditions take into account normal operation and certain fault conditions. The implementation of intrinsically-safe circuits results in certain re- strictions pertaining to the selection of components for the electrical and electronic circuits. In addition the permissible load on the components as compared with normal industrial applications must be reduced: – with respect to the voltage in terms of dielectric strength, and – with respect to the current in terms of thermal effects.	<b>Ex</b>
Flameproof enclosure "d" Designation "Ex d"	<ul> <li>Parts which could ignite a potentially explosive atmosphere must be housed in an enclosure:</li> <li>which in case of an explosion of an explosive mixture inside the housing can contain the pressure, and</li> <li>which prevents the internal explosion from igniting the atmosphere surrounding the enclosure.</li> </ul>	
Protection type "n" designation "Ex n"	Devices in these categories are intended for use in areas where an explosive atmosphere is not expected. Even if the atmosphere were to become explosive, in all probability it would be infrequent and only for a short space of time. A manufacturer's certificate is provided, confirming that the product satisfies requirements for the use of electrical equipment in poten- tially explosive areas according to EN 60079-15. Several methods of flameproofing are combined under the designa- tion.	
e1 type approval	The e1 type approval is granted by the German Federal Motor Transport Authority KBA and confirms that special motor vehicle standards have been maintained. The devices may be mounted on vehicles which travel on public roads. The standards describe EMC conditions under which the devices must operate without failure. e1 approved Micropulse transducers are indicated by "-SA265-" in the Part number.	e1
FDA	The FDA (Food and Drug Administration) oversees the US food and pharmaceutical industry and certifies devices, materials, systems and machines from these sectors. A product designation of this kind makes your system eligible for FDA approval.	FDA



Principles of operation

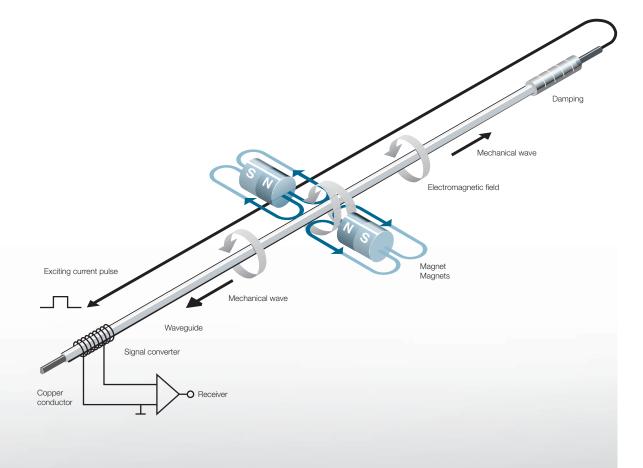
#### **Principles of operation**

The measuring element ("waveguide") consists of a special nickeliron alloy with 0.7 mm outer and 0.5 mm inner diameter. A copper conductor is introduced through the length of this tube. A short current pulse initiates the measurement process. This current generates a circular magnetic field which rotates around the waveguide. A permanent magnet at the point of measurement is used as the marker element, whose lines of field run at right angles to the electromagnetic field.

In the area on the waveguide where the two fields intersect, a magnetostrictive effect causes an elastic deformation of the waveguide (in the microrange), which propagates along the waveguide in both directions in the form of a mechanical wave.

The propagation velocity of this wave in the waveguide is 2830 m/s, and is almost completely insensitive to environmental effects such as temperature, shock and contamination.

The component of the wave which reaches the far end of the waveguide is damped, whereas the component which arrives at the signal converter is changed into an electrical signal by reversing the magnetostrictive effect. The time the wave takes to travel from its point of origin to the signal converter is directly proportional to the distance between the permanent magnet and the signal converter. A time measurement then allows this distance to be calculated with extreme accuracy.



# MCROPULSE®

Form factors

#### **Rod housings**

Rod housings are mainly used in hydraulic drive applications. When installed in the pressure section of the hydraulic cylinder, the distance sensor requires the same pressure rating as the actual hydraulic cylinder. In practice, the sensor must be able to withstand pressures up to 1000 bar. The electronics are integrated in an aluminum or stainless steel housing and the waveguide in a pressure-resistant tube made from nonmagnetic stainless steel that is sealed off at the face end with a welded plug. An O-ring seal in the flange at the opposite end seals off the high-pressure section. An magnet ring with magnets slides over the tube or rod with internal waveguide to mark the position prior to detection.



#### **Profile housings**

The electronics and waveguide are enclosed in an aluminum profiled housing. The aluminum housing is hermetically sealed according to degree of protection IP67. The magnets on the magnet act on the waveguide through the wall of the aluminum profile. There are two different versions of magnet, namely captive and free magnets. Free magnets are secured directly on the moving machine part and move with the part above and along the profile at a certain distance. The advantage is that guide precision is not an issue with this type of sensor. The sensors tolerate a lateral and upward offset of several millimeters. If these generous tolerances are exceeded, you can always revert to using captive magnets. With captive magnets, the profile housing of the distance sensor acts as a sliding rail along which the magnet travels. In this case, a control arm with spherical heads compensates for unparallel movements.



#### Explosion-proof versions

Many applications require the use of distance sensors in potentially explosive areas. Flameproof magnetostrictive Micropulse transducers are available in a wide range of designs for use in zone 0 and 1.

#### Redundancy increases safety

Magnetostrictive distance sensors are ideal for applications requiring a high degree of safety or availability. The sensors often have a 2-way or even 3-way redundant design in order to ensure mutual monitoring or provide a reserve channel when required. A distance sensor with a redundant 3-way design incorporates 3 adjacent waveguides offset by 120°C and housed in a collective outer tube along which an magnet moves in much the same way as on standard housings. The magnets on the magnet act on all three waveguides simultaneously. The three positions are evaluated by three interdependent, completely separate electronics modules that can be integrated in the same housing. Application examples include ship propulsion drives, power stations and tilting technology in trains.



Form factors

#### **Filling level sensor**

The magnetostrictive working principle is also ideal for the continuous high-precision measurement of fluid filling levels. Waveguides and processing electronics are enclosed inside a housing made from stainless steel. Stainless steel floats with permanent integrated magnets mark the current filling level in the tank or vessel. The design of the sensors meets international hygiene standards.













ALPHA



Analog

current output

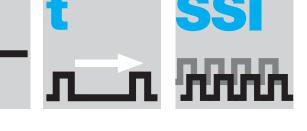
Interfaces



#### Analog voltage output

The output voltage is directly proportional to the position of the magnet along the waveguide. The most important parameter for analog outputs is the refresh rate and the ripple of the output signal. Many transducers on the market attain the specified values for output ripple only by means of low-pass filtering. This always carries with it an undesirable time delay of the output signal. Micropulse transducers attain the specified signal quality without low-pass filters, instead using an improved circuit design. This means fast update times with low levels of ripple and noise on the output signal. Micropulse transducers with voltage output have 2 outputs, one rising and one falling. Available versions include: page 32 0...10 V (10...0 V) and -10...10 V (10...-10 V).

See technical data on page 32



#### Pulse interface

The output current is The time between an directly proportional to the interrogation and the position of the magnet along the waveguide. Analog current interfaces of 0...20 mA and 4...20 mA are standard in numerous applications and in many industries. Current interfaces are significantly less sensitive to induced noise voltage than analog voltage inter-500 m. faces. A 500  $\Omega$  resistor can be used to convert the 0...20 mA signal into a voltage of 0...10 V. The 4...20 mA signal provides a simple form of cable break monitoring, since a current of 4 mA must flow even at the null point of the stroke. Appropriate control cards Micropulse transducers are available. with current output are available with rising or

See technical data on

falling signals.

reply signal is directly proportional to the position of the magnet along the waveguide. These pulses are transmitted using RS485/422 differential line drivers, guaranteeing noise-free signal transmission over distances of up to The great advantage of these interfaces is the noise-immune signal transmission with a simple and economical interface. Interfaces with tristate outputs allow multiplexing of several Micropulse transducers.

See technical data on page 34

#### Synchronous serial SSI interface

The position of the magnet along the waveguide is sent to the controller serially in a data word. Micropulse transducers with SSI interface can be connected directly to controllers or to axis control cards with SSI interface. The transmission of data from the sensor to the controller is synchronized by a clock pulse from the controller. Transducers with 16, 24 or 25-bit data words are available depending on the required resolution. The maximum non-linearity of the SSI Micropulse transducer of ±30 µm over the entire stroke, the update frequency of 5 kHz and a resolution of 1 µm make SSI Micropulse transducers an ideal feedback sensor even in the most demanding positioning and control applications.

See technical data on page 36



24 BALLUFF

Interfaces

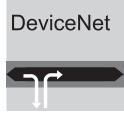


#### CANopen

The position of the magnet along the waveguide is sent over the CAN bus to the controller in so-called Process Data Objects or PDOs. Micropulse transducers work with standard CANopen protocols as per CiA DS 301 and with the standard device profile as per DS406. CANopen offers greater flexibility because of the large number of configuration options for the transducer. For example, the resolution is programmable for 5, 10, 20 or 100 µm - depending on your application. Alternatively you can select whether both position and velocity information are sent to your controller. Cyclically or on-demand. And there's more: Up to 4 so-called software cams can be defined in the active measuring range. Each time the status of one of these cams changes, high-priority emergency messages are sent to the controller.

See technical data on page 38





#### DeviceNet

DeviceNet is a fieldbus network which permits communication between basic sensors/actuators as well as programmable logic controllers. Micropulse transducers transmit the absolute position and the velocity to the controller in the form of a 4 byte value with a maximum cycle time of 1 ms. The communication parameters and the objects available to the Micropulse transducer can be parameterized using the electronic device data

See technical data on page 40

sheet (EDS file).



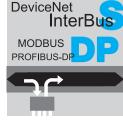
PROFIBUS-DP

#### PROFIBUS-DP

The Process Data Unit sends position and velocity information for the transducer to the controller via the PROFIBUS-DP. Micropulse transducers operate according to EN 50170 and support the PROFIBUS-DP encoder profile as well as multi-magnet operation. Micropulse transducers can be parameterized using the GSD file. The position resolution can be configured in 5 µm increments and the velocity resolution in increments of 0.1 mm/s. Working ranges and the null point can be configured individually for each magnet.

See technical data on page 42





transducers to various

bus systems is to use

the interface modules

provide the option of

available from WAGO and

Phoenix Contact. These

transmitting the position-

ing information from sev-

eral transducers through

a single bus interface to

the supervisory controller

within a single bus cycle.

null point of the transduc-

face can be programmed

bus interface. For further

modules, contact WAGO

The resolution and the

ers with the pulse inter-

through the respective

ordering bus interface

and Phoenix Contact.

See technical data on

page 162

technical data and



VARAN

#### VARAN bus

VARAN is an open realtime Ethernet bus system. Micropulse AT VARAN linear displacement systems detect the movements of highly dynamic axes in complex applications. The realtime Ethernet system is extremely economical, easy to implement and simple to program. Widely available on the market, VARAN networks are used in combination with Sigmatek controllers, for example. VARAN is fully integrated

in hardware and designed according to IEEE 802.3 for standard Ethernet physics.

The simple design guarantees extremely rapid cycle times while achieving maximum data security and reducing implementation costs.

See technical data on page 64

JS-DP Bus interface modules WAGO/Phoenix Contact ess Data Unit One flexible way of sition and veloc- connecting Micropulse

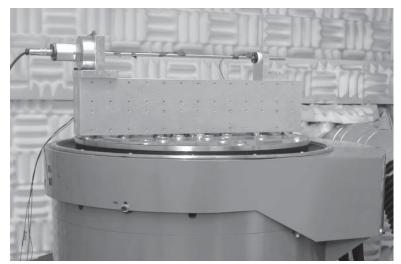
Quality and service

# Reliability doesn't happen by chance

#### Reliability doesn't happen by chance!

Maximum quality and reliability always take top priority at Balluff. All EMC, shock and vibration tests relevant to products are conducted in our internal company testing laboratory, which has been certified for 15 years.

The sophisticated test equipment in the testing laboratory can be used to implement special, more stringent tests that extend beyond standard specifications. Each product series must pass the specified tests prior to obtaining approval for the customer.



#### Tests for reliability and quality:

	Tests
1. Electromagnetic compatibility (EMC)	Immunity from discharge of static electricity (EN 61000-4-2)
	Immunity from electro-magnetic fields (EN 61000-4-3)
	Immunity from rapid transient interference (bursts) (EN 61000-4-4)
	Immunity from surge voltages (EN 61000-4-5)
	Immunity from line-borne high-frequency interference (EN 61000-4-6)
	Immunity from magnetic fields with power transmission frequencies (EN 61000-4-8)
	Immunity from voltage dips, short breaks in power supply and voltage fluctuations (EN 61000-4-11)
	Radiated emissions (EN 55011)
	Mains-borne emissions (EN 55011)
	Emissions, HF magnetic field (DIN EN 300 330-1)
2. Product-specific tests	Making capacity / breaking capacity (EN 60947-5-2) Testing cable anchoring of devices with integral connection cables (EN 60947-5-2)
	Short circuit testing (EN 60947-5-2)
3. Shock, sinusoidal and noise testing	Shock, sinusoidal and noise testing (EN 60068-2-6) (EN 60068-2-27;
	EN 60068-2-29) (EN 60068-2-64)
4. Other	X-ray analysis

## www.balluff.com

#### Global online availability

The latest product information from our databases.

- We offer the latest
- Data sheets
- CAD drawings in
- 2D or 3D
- Catalogs
- Brochures
- Manuals
- Software descriptions
- Operating manuals
- FAQs
- Worldwide addresses and much more.
- e addresses nore.



## HALT – High Accelerated Lifetime Test ... highest function security over years

#### HALT tests were designed to detect weaknesses early during the product development phase and eliminate them

The result is linear displacement systems and sensors of the highest guality and reliability which will continue to perform with the same safety and precision for years to come. The tests reduce equipment downtimes, prevent service and repair costs and achieve significantly greater efficiency. Rapid temperature cycles from -100 °C to +200 °C and vibration loads between 10 °C and 50 °C can simulate aging of a sensor. This procedure is used to test the specifications of products to determine the degree of reliability, load capacity and life expectancy of the sensor. The sample is intentionally destroyed so that we can immediately improve the first component to fail. Both sensors and transducers can be tested in the HALT system.



Nitrogen tank for the cooling system



Stress on the sample



Multifunctional climate chamber

HALT system	
Manufacturer	Thermotron Industries USA
Frequency range	210000 Hz
Acceleration	up to 50 g
Excitation	9 pneumatic cylinders, noise spectrum, 3-axis, 3 linear and 3 rotary degrees of freedom
Temperature range	-100 °C+200 °C
Temperature gradient	70 K/min
Electrical power	96 kW
Procedure	Electric heater, liquid nitrogen for cooling

# **Service Center**

## ... competent customer service

#### We offer ...

- Qualified technical consultation on the complete Balluff product range
- Technical solutions for all your applications
- Flexible assistance in dealing with your specific questions and problems
- Support whenever you need it
- Know-how for integrating controllers
- Product repair service

#### We will gladly answer any questions relating to ...

- Technical product features
- Suitability of products for your application
- Operating instructions and data sheets
- Conversion of models from other manufacturers
- Balluff successor products

#### We are happy to help!

Phone: +49 7158 173-370 E-mail: service@balluff.de Fax: +49 7158 173-691

Weekdavs 7am to 8pm Saturdays 8am to 12pm

#### Do you have a claim?

You are welcome to return your Balluff product to us for inspection and repair. Request a return consignment number from the "Technical Service" area on our website.

www.balluff.com





## **MICRO**PULSE<sup>®</sup>

	P	
	General data	30
P	Analog interface	32
	Digital pulse interface	34
	SSI interface	36
	CANopen interface	38
	DeviceNet interface	40
	PROFIBUS-DP interface	42
	Free magnets	44
	Captive magnets, control arm	46
	PF PF	
	General data	48
PF S	Analog interface	50
	Free magnets	52
	Captive magnets, control arm	54
CPUP	AT	
	General data	56
AT	Analog interface	58
	Modes	60
	Analog interface	61
	Digital pulse interface	62
	VARAN bus interface	64
	Accessories	66
	BIW	
	General data	68
BIW	Analog interface	70
Co -		

The electronics and waveguide are enclosed in an aluminum profiled housing. The aluminum housing is hermetically sealed according to degree of protection IP67. The magnets on the magnet act on the waveguide through the wall of the aluminum profile.

There are two different versions of magnet, namely captive and free magnets. Free magnets are secured directly on the moving machine part and move with the part above and along the profile at a certain distance. The advantage is that guide precision is not an issue with this type of sensor. The sensors tolerate a lateral and upward offset of several millimeters. If these generous tolerances are exceeded, you can always revert to using captive magnets. With captive magnets, the profile housing of the distance sensor acts as a sliding rail along which the magnet travels. In this case, a control arm with spherical heads compensates for unparallel movements.



## Floating or captive magnets!

The structural design, high degree of protection and simple installation of Balluff Micropulse transducers in a profiled housing makes them an excellent alternative to linear transducers, e.g. potentiometers, glass rulers and LVDTs. The linear sensing element is protected inside an extruded aluminum profile. A passive magnet with no power supply marks the measuring point along the waveguide without making contact. Measuring ranges between 50 and 5000 mm are available.

- Non-contact detection of the actual position
- Insensitive to dirt, IP 67
- Wear-free
- Insensitive to shock and vibration
- Absolute output signal
- Resolution up to 0.001 mm (depending on processing electronics used)
- Direct signal processing or in conjunction with processors for all control and regulating systems

Series	BTL5 profile P
Shock load	100 g/6 ms per IEC 60068-2-27
Vibration	12 g, 102000 Hz as per IEC 60068-2-6
Polarity reversal protected	yes
Overvoltage protection	Transzorb protection diodes
Dielectric strength	500 V (GND to housing)
Degree of protection as per IEC 60529	IP 67 (with BKS-S IP 67 connector attached)
Housing material	Anodized aluminum
Housing attachment	Compression clamps
Connection type	Connectors/cables
EMC testing:	
RF emission	EN 55016 Group 1, Class A
Static electricity (ESD)	IEC 61000-4-2 Severity Level 3
Electromagnetic fields (RFI)	IEC 61000-4-3 Severity Level 3
Fast transients (BURST)	IEC 61000-4-4 Severity Level 4
Conducted interference induced	IEC 61000-4-6 Severity Level 3
by high-frequency fields	
Standard nominal strokes [mm]	0050, 0100, 0130, 0150, 0175, 0200, 0225, 0250, 0300, 0350,
	0360, 0400, 0450, 0500, 0550, 0600, 0650, 0700, 0750, 0800,

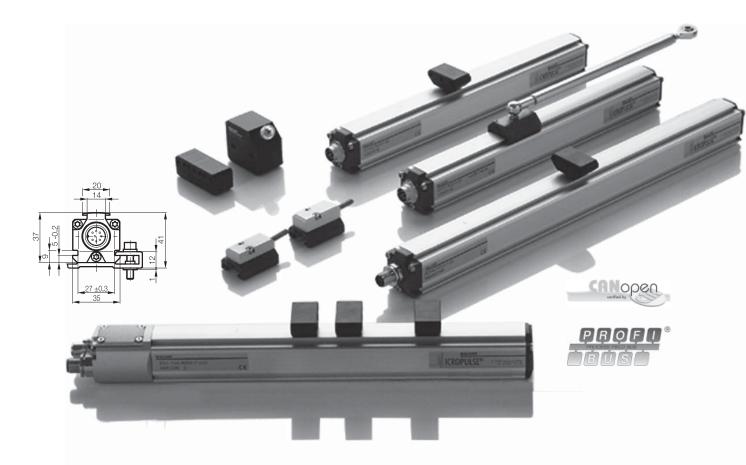
0360, 0400, 0450, 0500, 0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900, 0950, 1000, 1100, 1200, 1250, 1300, 1400, 1500, 1600, 1700, 1750, 1800, 1900, 2000, 2250, 2500, 2750, 3000, 3250, 3550, 3550, 3750, 4000, (4250, 4500, 4750, 5000, 5250, 5500) or in 5 mm increments (depending on interface) on request



## Included:Transducer (select your interface from page 32)

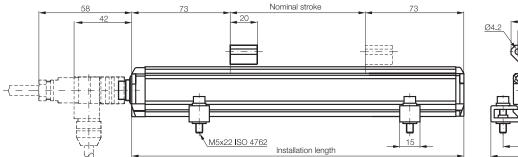
- Short user's guide
- Mounting clamps with isolation washers and screws

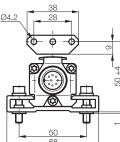
Please order separately: Magnets from page 44 Connectors, page 148



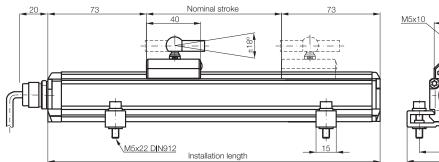


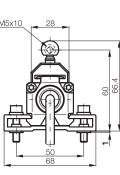
Transducer with floating magnet, S 32 connection with BKS-S 32M/BKS-S 32M-C/BKS-S 33M connector for transducers with analog interface, digital pulse interface and SSI interface, from page 32



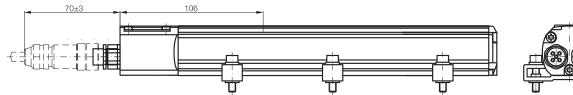


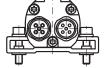
Transducers with captive magnets and cable outlet for transducers with analog interface, digital pulse interface and SSI interface, from page 32



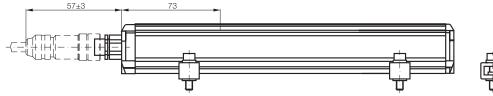


CANopen connection S 94 with connectors BKS-S 94-00 and BKS-S 92-00 for transducers with CANopen interface, page 38



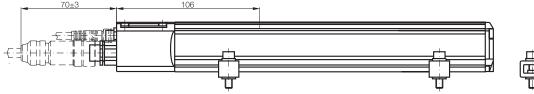


CANopen connection S 92 with connector BKS-S 92-00 for transducers with CANopen interface, page 38





DeviceNet connection S 93 with connectors BKS-S 92-00, BKS-S 93-00 and BKS-S 48-15-CP-\_\_, page 40 PROFIBUS-DP plug connector S103 with connectors BKS-S 103-00, BKS-S 105-00 and BKS-S 48-15-CP-\_ page 42





General data Analog interface Digital pulse interface SSI interface CANopen interface DeviceNet interface PROFIBUS-DP

interface Magnets floating Magnets captive, control arm PF General

data

Analog

interface Magnets floating Magnets captive. control arm AT General data

Analog interface Modes Digital pulse . interface VARAN bus interface Accessories

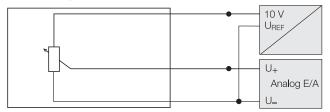
BIW General data Analog interface



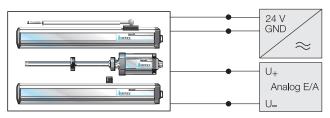
The analog outputs of the profile series are potential-free with respect to the input voltage. The isolation is galvanic using DC/DC converters.

Analog type BTL transducers are available in various output configurations: 0...10V, 4...20mA, 0...20mA and -10...10V, with rising and falling output slope.

## Micropulse transducers – a non-contact alternative to contacting feedback devices



Potentiometer connections, block diagram



Micropulse transducer connections, block diagram

Series			
Output signal			
Transducer interface			
Input interface			
Part number			
Output			
Output voltage			
Output current			
Load current			
max. ripple			
Load resistance			
System resolution			
Hysteresis			
Repeat accuracy			
Sampling rate			
Max. non-linearity			
Temperature coefficient	Voltage o		
	Current o	utput	
Operating voltage			
Current consumption			
Polarity reversal protected			
Overvoltage protection			
Dielectric strength			
Operating temperature			
Storage temperature range			
Pin assignments	Pin	Color	
Output signals	1	YE	
	2	GY	
	3	PK	
-	5	GN	
Operating voltage	6	BU	
	7	BN	
	8	WH	

Connect shield to housing

Please enter the code for the output signal and nominal stroke length in the ordering code.

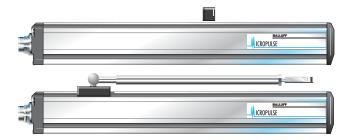
#### Preferred models interface A11 and E10

 $\begin{array}{l} BTL5-A11-M\_\_\_-P-S32\\ BTL5-E10-M\_\_\_-P-S32\\ are available from stock in the nominal lengths highlighted in blue. \end{array}$ 

Included:

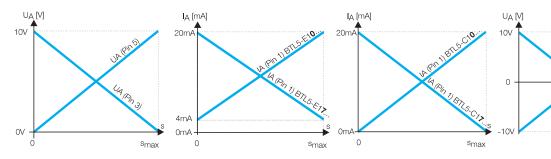
- Transducer
- Mounting clamps with isolation washers and screws
- Short user's guide

Please order separately: Magnets from page 44 Connectors, page 148/149





BTL5 profile P	BTL5 profile	P	BTL5 profile	P	BTL5 profile P
analog	analog		analog		analog
Α	E		С		G
analog	analog		analog		analog
BTL5- <b>A</b> 11-MP	BTL5-E1M_	P	BTL5-C1M_	P	BTL5-G11-MP
potential-free	potential-free		potential-free		potential-free
010 V and 100 V					-1010 V and 1010 V
	420 mA or 2	204 mA	020 mA or 2	200 mA	
max. 5 mA					max. 5 mA
$\leq 5 \text{ mV}$					≤ 5 mV
	≤ 500 ohms		≤ 500 ohms		
≤ 0.1 mV	≤ 0.2 µA		≤ 0.2 µA		≤ 0.1 mV
≤4 µm	≤ 4 µm		≤ 4 µm		≤ 4 µm
System resolution/min. 2 µm	System resolut		System resolut	•	System resolution/min. 2 µm
f <sub>standard</sub> = 1 kHz	$f_{STANDARD} = 1 \text{ kH}$		f <sub>standard</sub> = 1 k⊢	łz	$f_{\text{STANDARD}} = 1 \text{ kHz}$
$\pm 100~\mu m$ up to 500 mm nominal stroke	±100 µm up to 50	00 mm nominal stroke	±100 µm up to 50	00 mm nominal stroke	$\pm 100 \ \mu\text{m}$ up to 500 mm nominal stroke
±0.02 % 500 max. nominal stroke	±0.02 % 500 max. nominal stroke		±0.02 % 500 m	iax. nominal stroke	±0.02 % 500 max. nominal stroke
$[150 \ \mu\text{V/°C} + (5 \ \text{ppm/°C} \times \text{P} \times \text{U/L})] \times \Delta\text{T}$					$[150 \ \mu\text{V/°C} + (5 \ \text{ppm/°C} \times \text{P} \times \text{U/L})] \times \Delta\text{T}$
	$[0.6 \ \mu\text{A/°C} + (10 \ \text{ppm/°C} \times \text{P} \times \text{I/L})] \times \Delta\text{T}$		[0.6 µA/°C + (10 p	$pm/^{\circ}C \times P \times I/L)] \times \Delta T$	
2028 V DC	2028 V DC		2028 V DC		2028 V DC
≤ 150 mA	≤ 150 mA		≤ 150 mA		≤ 150 mA
yes	yes		yes		yes
Transzorb protection diodes	Transzorb prot	ection diodes	Transzorb prot	ection diodes	Transzorb protection diodes
500 V DC (ground to housing)	500 V DC (gro	und to housing)	500 V DC (gro	und to housing)	500 V DC (ground to housing)
-40+85 °C	-40+85 °C		-40+85 °C		−40+85 °C
-40+100 °C	-40+100 °C		-40+100 °C		−40+100 °C
BTL5- <b>A</b> 11	BTL5- <b>E</b> 10	BTL5- <b>E</b> 17	BTL5- <b>C</b> 10	BTL5- <b>C</b> 17	BTL5- <b>G</b> 11
	420 mA	204 mA	020 mA	200 mA	
0 V Output	0 V Output	0 V Output	0 V Output	0 V Output	0 V Output
100 V	100 V	100 V	100 V	100 V	1010 V
010 V	010 V	010 V	010 V	010 V	-1010 V
GND	GND	GND	GND	GND	GND
+24 V DC	+24 V DC	+24 V DC	+24 V DC	+24 V DC	+24 V DC
(GND)	(GND)	(GND)	(GND)	(GND)	(GND)



#### Ordering example:

www.balluff.com

BTL5-E1	MP		
	Dutput ignal	Standard nominal stroke [mm]	Co
1	Rising and falling (with A and G)	0050, 0100, 0130, 0150, 0175, 0200, 0225, 0250, 0300, 0350, 0360, 0400, 0450, 0500, 0550, 0600, 0650, 0700,	S32 KA0 KA0
0	Rising	0750, 0800, 0850, 0900, 0950, 1000,	KA1
7	Falling (with C and E)	1100, 1200, <b>1250</b> , 1300, 1400, <b>1500</b> , 1600, 1700, 1750, 1800, 1900, 2000, 2250, 2500, 2750, 3000, 3250, 3500, 3550, 3750, 4000, 4250, 4500 or in 5 mm increments (depending on	KA1
	uff oom	in a minimorements (depending on	

interface) on request



2	Connector
02	PUR cable 2 m
05	PUR cable 5 m
10	PUR cable 10 m
15	PUR cable 15 m

General data Analog interface Digital pulse interface SSI interface CANopen interface DeviceNet interface PROFIBUS-DP interface Magnets floating Magnets captive, control arm

General data Analog interface Magnets floating Magnets captive, control arm

AT General data Analog interface Modes Digital pulse interface VARAN bus interface Accessories

19

UA (Pin 3)

s<sub>max</sub> s

BIW General data Analog interface

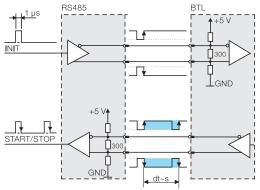


#### P Interface

Compatible with BTA/BTM processors as well as controllers and modules from various manufacturers, including Siemens, B & R, Phoenix Contact, Mitsubishi, Sigmatek, Esitron and WAGO. Reliable signal transmission, even over cable lengths up to 500 m between BTA and BTL, is assured by the noise-immune RS485 differential line drivers and receivers. Noise signals are effectively suppressed.

#### **M** Interface

The I and M interfaces are control-specific interface variations.



Block diagram of P interface

#### Highly precise digitizing of the P pulse signal

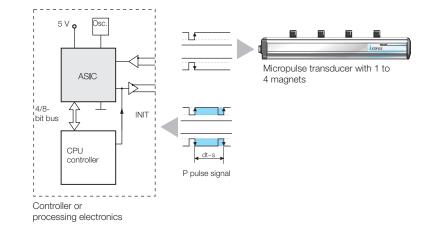
Companies developing their own control and processing electronics can create a highly accurate P interface cost effectively and with minimum effort using the Balluff digitizing chip. The digitizing chip was developed as a high-resolution, configurable ASIC for Micropulse transducers with P interface.

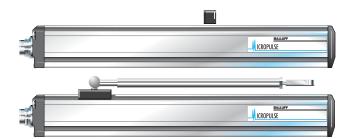
#### Advantages:

- Position resolution 1 µm!
  - The 1  $\mu$ m resolution of the Micropulse distance measurement system is achieved by the high resolution of the digitizing chip (133 pS). (Clock frequency 2 or 20 MHz)
- Position data from 4 magnets can be processed simultaneously
- 4/8-bit processor interface



Digitizing chip 44QFP





ASIC INFO: +49 7158 173-370

#### noise-immune up to 500 m

## **Profile P Series** Digital pulse interface

Series		BTL5 profile P	BTL5 profile P		
Transducer interface		Pulse P	Pulse M		
Input interface				Pulse P	Pulse M
Part number				BTL5- <b>P</b> 1-MP	BTL5-M1-MP
System resolution				processing-dependent	processing-dependent
Repeat accuracy				$2\ \mu m$ or $\pm 1$ digit depending on processing electronics	$2\ \mu m$ or $\pm 1$ digit depending on processing electronics
Resolution				≤ 2 µm	≤2 µm
Hysteresis				≤ 4 µm	≤4 µm
Sampling rate				3 kHz500 Hz depending on nominal stroke	3 kHz500 Hz depending on nominal stroke
Max. non-linearity				$\pm 100 \ \mu m$ up to 500 mm nominal stroke	±100 µm up to 500 mm nominal stroke
				±0.02 % 5005000 mm nominal stroke	±0.02 % 5005000 mm nominal stroke
Temperature coefficier	nt of overa	all syst	tem	(6 μm + 5 ppm × L)/°C	(6 μm + 5 ppm × L)/°C
Operating voltage				2028 V DC	2028 V DC
Current consumption				≤ 90 mA	≤ 90 mA
Operating temperature	Э			–40+85 °C	−40+85 °C
Storage temperature r	ange			-40+100 °C	-40+100 °C
Pin assignments		Pin	Color	BTL5- <b>P</b> 1-M	BTL5- <b>M</b> 1-M
Input/Output	Input	1	ΥE	INIT	INIT
signals	Output	2	GY	START/STOP	START/STOP
	Input	3	PK	INIT	INIT
	Output	5	GN	START/STOP	START/STOP
Operating voltage	erating voltage 6 BU		BU	GND	GND
		7	BN	+24 V DC	+24 V DC
		8	WH	(GND)	(GND)

INIT

INIT

START/STOP

dt~s

START/STOP

Please enter the code for the nominal stroke in the ordering code!

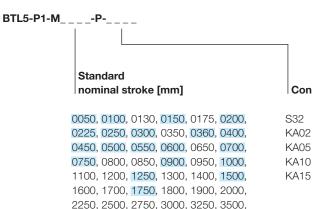
#### Preferred models interface P

BTL5-P1-M\_ \_ \_ \_-P-S32 are available from stock in the nominal lengths highlighted in blue.

- Included:
- Transducer
- Mounting clamps with isolation washers and screws
- Short user's guide

Please order separately: Magnets from page 44 Connectors from page 148/149

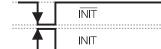
#### Ordering example:

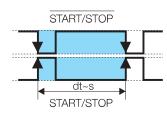


3550, 3750, 4000, 4250, 4500, 5000, 5250, 5500 or in 5 mm increments (depending on interface) on request

#### Connection type

S32	Connector
KA02	PUR cable 2 m
KA05	PUR cable 5 m
KA10	PUR cable 10 m
KA15	PUR cable 15 m





interface Digital pulse interface SSI interface CANopen interface DeviceNet interface PROFIBUS-DP interface Magnets floating Magnets captive, control arm

P General data Analog

PF General data Analog interface Magnets floating Magnets captive.

> AT General data Analog interface Modes Digital pulse interface VARAN bus interface

control arm

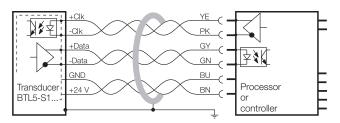
BIW General data Analog interface

Accessories



#### Standard SSI interface

Synchronous serial data transmission for controllers from various manufacturers, including Siemens, Bosch-Rexroth, WAGO, B & R, Esitron and PEP as well as for Balluff BDD-AM 10-1-SSD and BDD-CC 08-1-SSD displays/controllers. Reliable signal transmission, even with cable lengths of up to 400 m between controller and BTL transducer is assured by noise-immune RS485/422 differential line drivers and receivers. Any noise signals are effectively suppressed.



BTL5-S1... with processor/controller, wiring example

#### Synchronized SSI interface BTL5-S1\_B-M\_\_\_-P-\_\_\_ Micropulse transducers with synchronized SSI interface are suit-

able for dynamic control applications. The data acquisition in the transducer is synchronized with the external clock of the controller, permitting an optimum calculation of the velocity in the controller. The prerequisite for this synchronous mode of transducer operation is consistent clock signal timing.

The **maximum sampling frequency**  $\mathbf{f}_{\mathbf{A}'}$  at which a new current value is generated for each sample, can be derived from the following table:

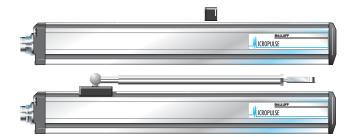
SYNC	

mm	mm	Hz
< Nominal stroke	$\leq$ 100 :	1500
120 < Nominal stroke	$\leq 1000$ :	1000
475 < Nominal stroke	$\leq 1400$ :	666
750 < Nominal stroke	$\leq\!2600$ :	500
1250 < Nominal stroke	≤4000 :	333

#### Clock frequency depends on the cable length

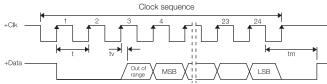
Cable length	Clock frequency
< 25 m	< 1000 kHz
< 50 m	< 500 kHz
< 100 m	< 400 kHz
< 200 m	< 200 kHz
< 400 m	< 100 kHz

### Super-fast 2.5 kHz sampling rate



# super linear and **synchronized**

Series			BTL5 profile P		
Output signal			synchronous serial		
Transducer interface			S		
Input interface			synchronous serial (SSI)		
Part number			BTL5- <b>S</b> 1MP		
Part number synchro	nization		BTL5- <b>S</b> 1B-MP		
System resolution dep	pending on	version (LSB)	1, 2, 5, 10, 20, 40 or 100 μm		
Repeat accuracy	-		±5μm		
Hysteresis			≤ 4 µm or ≤ 1 digit		
Sampling rate			$f_{\text{STANDARD}} = 2 \text{ kHz}$		
Max. non-linearity			$\pm 30 \ \mu m$ at $\leq 10 \ \mu m$ resolution or $\leq \pm 2 \ LSB$ at $> 10 \ \mu m$ resolution		
Temperature coefficie	ent of over	all system	(6 µm + 5 ppm × L)/°C		
Operating voltage			2028 V DC		
Current consumption	ı		≤ 80 mA		
Operating temperatu	re		–40+85 °C		
Storage temperature	range		-40+100 °C		
Pin assignments	Pin	Color			
Control and	1	YE	+Clk		
data signals	2	GY	+Data		
	3	PK	-Clk		
	5	GN	-Data		
Operating	6	BU	GND		
voltage (external)	7	BN	+24 V DC		
	8	WH	must remain unconnected		



**Profile P Series** 

SSI interface

Please enter the code for the coding, system resolution and nominal stroke in the ordering code!

#### Preferred models interface S

BTL5-S112-M\_ \_ \_ -P-S32 are available from stock in the nominal lengths highlighted in blue.

#### Orc

Ordering example: BTL5-S1 -M -P-		Magnets from page 44 Connectors, page 148/14	9		Analog interface Modes Digital
Coding	System resolution	Standard nominal stroke [mm]	Conne	ection type	pulse interface VARAN interface Accesso
<ul> <li>Binary code rising (24 bit)</li> <li>Gray code rising (24 bit)</li> </ul>	1 1 μm 2 5 μm 3 10 μm 4 20 μm 5 40 μm 6 100 μm	<b>0100</b> , 0130, <b>0150</b> , 0175, 0200, 0225, 0250, 0300, <b>0350</b> , 0360, <b>0400</b> , 0450, 0500, 0550, 0600, 0650, <b>0700</b> , 0750, 0800, 0850, 0900, <b>0950</b> , 1000, <b>1100</b> , 1200, 1250, 1300, 1400, 1500, <b>1600</b> , 1700, 1750, 1800, 1900, 2000, 2250,	S32 KA02 KA05 KA10 KA15	Connector PUR cable 2 m PUR cable 5 m PUR cable 10 m PUR cable 15 m	General data Analog interfaca
<ul> <li>Binary code</li> <li>rising</li> <li>(25 bit)</li> <li>Gray code</li> <li>rising</li> </ul>	7 2 µm	2500, 2750, 3000, 3250, 3500, 3550, 3750, 4000 or in 5 mm increments (depending on interface) on request Ordering code for SSI interface with sync	bropization		

Analog interface Digital pulse interface SSI interface CANopen interface DeviceNet interface PROFIBUS-DP interface Magnets floating

P General data

Included:

- Transducer
- Mounting clamps with isolation washers and screws
- Short user's guide

Please order separately:

applications) insert the letter B! BTL5-S1\_\_B-M\_\_\_\_-P-\_\_\_\_

captive, control arm PF General data Analog interface Magnets floating Magnets captive, control arm

Magnets

AT General data g ace s ace N bus ace ssories

ral ace

(25 bit)



#### **CANopen interface**

Based on CAN (ISO/IEC 7498 and DIN ISO 11898), CANopen provides a Layer-7 implementation for industrial CAN networks. The serial data protocol of the CAN specification is defined according to the producer-consumer principle as opposed to most other fieldbus protocols. This eliminates target addressing of the process data. Each bus station decides for itself how the received data is processed.

The CANopen interface of the Micropulse transducer is compatible with CANopen conforming with CiA Standard DS301 Rev. 3.0, and with CAL and Layer 2 CAN networks.

#### CAN-BUS features

- Line topology, star structure also possible via repeaters
- Low-cost wiring with two-wire cable
- Fast response times, high data integrity using CRC, hamming distance of 6
- 1 MBit/s with cable lengths < 25 m</li>
- Protocol limits number of stations to 127
- Using multiple magnets: A minimum spacing of > 65 mm must be maintained.

CANopen offers a high level of flexibility with respect to functionality and data exchange. Using a standard data sheet in the form of an EDS file it is easy to link the Micropulse transducers to any CANopen system.

#### Process Data Object (PDO)

Micropulse transducers send their position information optionally in one, two or four PDOs with 8 bytes of data each. The contents of the PDOs are freely configurable. The following information can be sent:

- Current magnet position with resolution in 5 µm increments
- Current velocity of the magnet with resolution selectable in 0.1mm/s increments
- Current status of the four freely programmable cams per magnet.

#### Synchronization Object (SYNC)

Serves as a net-wide trigger for synchronizing all network participants. When the SYNC object is received, all Micropulse transducers connected to the bus store their current position and velocity information and then send it sequentially to the controller. This assures time-synchronous acquisition of the measured values.

#### LED

Display of the CANopen status to DS303-3

#### FMM

The sensor can be operated as a 4-magnet type, whereby the sensor itself recognizes how many magnets are currently active. So if only two magnets are positioned in the measuring range, a valid value is output for the first two positions and a defined error value for positions 3 and 4.

#### **Emergency Object**

This object is sent with the highest priority and is used for example for error messages when the cam states change.

#### Service Data Object (SDO)

Service Data Objects transmit the configuration parameters to the transducer. The transducer may be configured on the bus by the controller or offline using a PC with a configuration tool which runs under Windows. The configuration is stored in the non-volatile memory of the transducer.

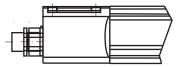


CiA 199911-301v30/11-009

#### Use of multiple magnets

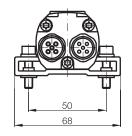
A minimum spacing of > 65 mm must be maintained.





Position of the DIP switch S1, only on BTL-H1\_\_\_-P-S94

BTL5-H1\_\_-M\_\_\_-P-S94



Node ID can be set by DIP switch.

BTL5-H1\_\_-M\_\_\_-P-S92



# **Position +** Velocity

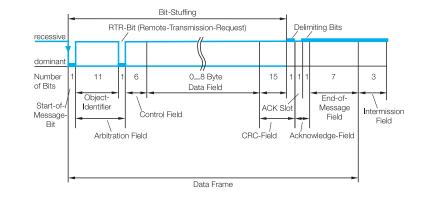
**Profile P Series** CANopen<sup>®</sup> interface

Series			BTL5 pr	BTL5 profile P								
Output signal			CANope	CANopen								
Transducer interface	Э		Н									
Input interface			CANope	CANopen								
Part number			BTL5-H	1M	P-S9	)2						
			BTL5-H	1M	P-S9	)4						
CANopen Version			DS301,	DS406								
Repeat accuracy			±1 digit									
System resolution	Positio	on	5 µm inc	rements	configurat	ole						
Configurable	Veloci	ty	0.1 mm/	s increme	ents config	gurable						•
Hysteresis			≤ 1 digit									Р
Sampling rate			f <sub>STANDARD</sub>	= 1 kHz								General
Max. non-linearity			±30 μm	$\pm$ 30 µm at 5 µm resolution					data			
Temperature coeffici	ient of ove	erall system	(6 µm +	$(6 \mu m + 5 ppm \times L)/^{\circ}C$					Analog interface			
Magnet traverse velo	ocity		any	any								
Operating voltage			2028 \	2028 V DC						Digital pulse		
Current consumptio	n		≤ 100 m	A								interface
Operating temperate	ure		-40+8	5 °C								SSI
Storage temperature	e range		-40+1	00 °C								interface
Cable length [m] per	r CiA DS3	01	< 25	< 50	< 100	< 250	< 500	< 1000	< 1250	< 2500		CANopen interface
Baud rate [kBaud] p	er CiA DS	6301	1000	800	500	250	125	100	50	20/10		DeviceNet
Pin assignments	Pin	Color										interface
Control and	1	WH	CAN_GN	١D								PROFIBUS-
data signals	4	GY	CAN_HI	GH								interface
	5	GN	CAN_LC	W								Magnets
Operating	2	BN	+24 V									floating
voltage (external)	3	BU	0 V (GNI	D)								Magnets captive,

Please enter the code for the software configuration, baud rate and nominal stroke length in the ordering code.

- Included:
- Transducer
- Mounting clamps with isolation washers and screws
- Short user's guide

Please order separately: Magnets from page 44 Connectors, page 150/151



Using the CANopen interface and cable lengths up to 2500 m, the signal is sent at a length-dependent baud rate to the controller. The high noise immunity of the connection is achieved using differential drivers and by the data monitoring scheme.

#### Ordering example:

l1MP-S92 l1MP-S94 			
Software configuration	в	aud rate	Standard nominal stroke [mm]
1 1 × position and	0	1 MBaud	0050, 0100, 0130, 0150, 0175, 0200,
1 × velocity	1	800 kBaud	0225, 0250, 0300, 0350, 0360, 0400,
2 2 × position and	2	500 kBaud	0450, 0500, 0550, 0600, 0650, 0700,
$2 \times \text{velocity}$	3	250 kBaud	0750, 0800, 0850, 0900, 0950, 1000,
	4	125 kBaud	1100, 1200, 1250, 1300, 1400, 1500,
	5	100 kBaud	1600, 1700, 1750, 1800, 1900, 2000,
	6	50 kBaud	2250, 2500, 2750, 3000, 3250, 3500,
	7	20 kBaud	3550, 3750, 4000 or in 5 mm
	8	10 kBaud	increments (depending on interface) or

request

#### nterface SSI nterface CANopen interface DeviceNet nterface nterface

PROFIBUS-DP Magnets floating Vagnets captive, control arm

PF General data Analog interface Magnets floating Magnets captive. control arm

AT General data Analog interface Modes Digital pulse . interface VARAN bus interface Accessories

BIW General data Analog interface



#### DeviceNet

DeviceNet is a manufacturer-independent open fieldbus standard used in automation technology for connecting programmable logic controllers (PLCs) to intelligent devices such as sensors, pushbuttons, I/O modules, basic user interfaces and drives via a single cable. DeviceNet is an application protocol (OSI layer 7) based on the Controller Area Network (CAN) principle. It offers high reliability for demanding applications with a high number of I/O modules.

The transmission speed is between 125 kBit/s and 500 kBit/s depending on type and length of the cable.

#### Master

DeviceNet is multi-master capable, i.e. several DeviceNet devices can simultaneously request the current position. The data transfer is controlled by the priority of the message. Messages on the DeviceNet carry an identifier.

The message that was sent can be received by all devices simultaneously (broadcast). Message filtering is performed by the device only for messages intended for it. The criterion for this decision is

the identifier, with which each message is transmitted.

#### EDS

DeviceNet offers parameterization of functionality and data exchange. Using a standard data sheet in the form of an EDS file it is easy to link the Micropulse transducers to any DeviceNet system.

#### **DeviceNet features:**

- Linear topology
- Low-cost wiring with two-wire cable
- Fast response times
- High data security due to CRC checking
- Hamming distance of 6
- Potential-free data transmission (RS485)
- 125 Kb/s at cable length < 500 m</li>
   250 Kb/s at cable length < 250 m</li>
   500 Kb/s at cable length < 100 m</li>
- Protocol limits number of stations to 64

#### **Position Sensor Object**

The DeviceNet interface of the Micropulse transducer is compatible with the CIP Common Specification Object Library "Position Sensor Object" of the ODVA.

The Micropulse transducers transmit their measurement values in an entity of the Position Sensor Objects as a 32-bit value.

The following information can be sent:

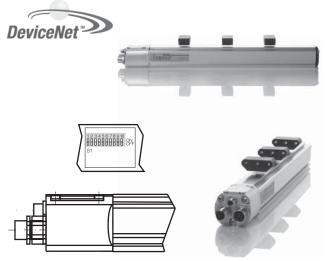
- Current magnet position with resolution in 5 µm increments
- Current magnet velocity in increments of 0.1 nm/s
- Current status of the four freely programmable cams.

#### Synchronization

Measurement can be triggered by the master I/O bit Strobe Command Message. On receiving this bit, the respective Micropulse transducer saves its current position and velocity information and sends it back to the controller.

#### FMM

The sensor can be operated as a 1...4-magnet type, whereby the sensor itself recognizes how many magnets are currently active. So if only two magnets are positioned in the measuring range, a valid value is output for the first two positions and a defined error value for positions 3 and 4.



Position of the DIP switch S1,

Device address can be set by DIP switch

**Use of multiple magnets** A minimum spacing of > 65 mm must be maintained.

**Profile P Series** DeviceNet interface

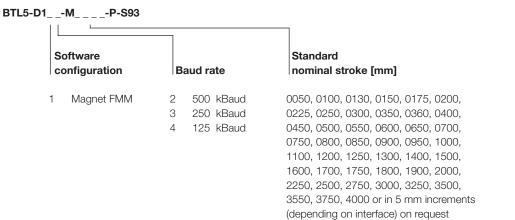
Series	BTL5 profile P					
Output signal	DeviceNet	DeviceNet				
Transducer interface	D					
Input interface	DeviceNet					
Part number plug version S103	BTL5- <b>D</b> 1M	-P-S93				
Profibus version	Encoder profile					
Profibus interface	potential-free					
Repeat accuracy	±1 digit					
System resolution Position	5 µm increments con	figurable		بالمسير المالية		
Configurable Velocity	0.1 mm/s increments	0.1 mm/s increments configurable				
Hysteresis	≤ 1 digit			Р		
Sampling rate	f <sub>standard</sub> = 1 kHz			General		
Max. non-linearity	±30 µm at 5 µm resol	ution		data		
Temperature coefficient of overall system	$(6 \mu\text{m} + 5 \text{ppm} \times \text{L})/^{\circ}$	C		Analog interface		
Magnet traverse velocity	any	any				
Operating voltage	2028 V DC					
Current consumption	≤ 100 mA					
Operating temperature	-40+85 °C	SSI				
Storage temperature range	-40+100 °C	interface				
Address assignment	mechanical switches	CANopen interface				
Cable length [m]	100 250 500			DeviceNet		
Baud rate [Kbps]	500 250 125			interface		
Pin assignments		S93 5-pin	S93 3-pin	PROFIBUS-DF		
Control and data signals	CAN GND	1		interface		
	V+	2		Magnets		
	V– (GND)	3		floating		
	CAN HIGH	4		Magnets		
	CAN LOW	5		captive, control arm		
Operating voltage and shielding	+24 V		1			
	GND		3	PF		
	Shield supply		4	General		

Please enter the code for the software configuration, baud rate and nominal stroke length in the ordering code.

- Included:
- Transducer
- Mounting clamps with isolation washers and screws
- Short user's guide

Please order separately: Magnets from page 44 Connectors, page 150/151

#### Ordering example:



of Bits

Bit-Stuffing RTR-Bit (Remote-Transmission-Request) Delimiting Bits recessive dominant Number 11 6 0...8 Byte 15 7 3 Data Field Object End-of-Start-of-Identifier ACK Slot Message Field Intermission Control Field Message Bit Field 1 Arbitration Field CRC-Field Acknowledge-Field Data Frame

ntrol arm neral ta Analog interface Magnets floating Magnets captive. control arm AT General data Analog

interface Modes Digital pulse . interface VARAN bus interface Accessories

BIW General data Analog interface

# Profile P Series PROFIBUS-DP interface

## User-friendly hardware and software set-up

As the market leading standard for serial data transmission for process automation, PROFIBUS-DP is the ideal choice for implementing automation tasks with cycle times of > 5 ms.

#### Data transmission

A PROFIBUS telegram can contain up to 244 bytes of user data per telegram and station. The BTL5-T uses max. 32 bytes (max. 4 position values and max. 4 velocity values) for process data transmission. Up to 126 active stations (Address 0...125) can be connected on PROFIBUS-DP. User data cannot be sent with station address 126. This address is used as the default address for bus stations that have to be parameterized by a Class 2 master (for setting the device address if there are no mechanical switches available). Each PROFIBUS station has the same priority. Prioritizing of individual stations is not intended, but can be done by the master since the bus transmission only makes up a fraction of the process cycle anyway. At a transfer rate of 12 Mbps, the transmission time for an average data telegram is in the 100 µs range.

#### Master

There are two types of possible masters for PROFIBUS-DP. Master Class 1 carries out the user data interchange with the connected slaves. Master Class 2 is intended for startup and diagnostic purposes and may be used to briefly assume control of a slave.

#### **GSD (Device Master Data)**

The length of the data exchangeable with a slave is defined in the Device Master Data file (GSD) and is checked by the slave with the configuration telegram and confirmed for correctness.

In modular systems, various configurations are defined in the GSD file. Depending on the desired functionality, one of these configurations can be selected by the user when the system is configured. The BTL5-T is a modular device with the possibility of selecting the number of magnets (position values).

#### Slave

Once a PROFIBUS master has received the parameter set defined for the slave, it is able to exchange data. The parameter set consists of slave parameters and configuration data.

The parameter data contain the description of the slave settings (e.g. resolution of a position value). The configuration data describe the length and structure of the data telegram.

#### Process data

Under PROFIBUS-DP the default is for process data to be sent from the master to slaves acyclically and for the slave data to then be queried. To ensure synchronization of multiple devices, the master may use the SYNC and FREEZE services.

#### DP/V1 and DP/V2 isochronous mode

Isochronous mode enables quick and deterministic data exchange through the synchronicity of cycles on the bus system. A cyclic equidistant clock signal is sent by the master to all bus devices. This signal allows master and slaves to be synchronized irrespective of application – with an accuracy < 1 µs.

#### Cross traffic between slaves

Cross traffic permits two DP slaves to exchange data directly with each other: the master ensures that the slave publishes its data on the bus with a request for "Data-eXchange-Broadcast" (DXB-Request) and thus makes it available to other slaves. Since the process data is available in the process periphery without being diverted through the master application, cross-traffic permits very fast control system responses.

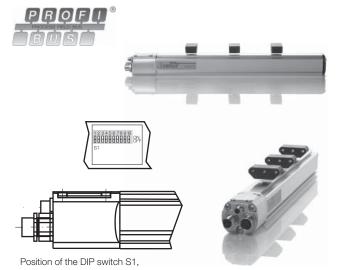
#### Acyclic services

The DP functions for prioritized communication

allow the transfer of acyclic read and write functions between master and slaves, independently of the cyclic user data traffic. The transfer of acyclic data is performed at a lower priority in parallel to the high speed cyclic data exchange – as if in the background. The background / foreground split means the ratio of cyclic to acyclic data can be adjusted if required.

#### FMM

The sensor can be operated as a 4-magnet type, whereby the sensor itself recognizes how many magnets are currently active. So if only two magnets are positioned in the measuring range, a valid value is output for the first two positions and a defined error value for positions 3 and 4.



### Device address can be set by DIP switch

**Use of multiple magnets** A minimum spacing of > 65 mm must be maintained.

# 4 × position + velocity

# Profile P Series PROFIBUS-DP interface

Series	BTL5 profile P				
Output signal	PROFIBUS-DP				
Transducer interface	Т				
Input interface	PROFIBUS-DP				
Part number plug version S103	BTL5- <b>T</b> 1_0-MP-S103				
Profibus version	DPV1/DPV2 EN 50170, encoder profile				
Profibus interface	potential-free				
Repeat accuracy	±1 digit				
System resolution Position	5 µm increments configurable				
configurable Velocity	0.1 mm/s increments configurable				
Hysteresis	≤ 1 digit	Р			
Sampling rate	f <sub>standard</sub> = 1 kHz	General			
Max. non-linearity	±30 μm at 5 μm resolution	data			
Temperature coefficient of overall system	(6 μm + 5 ppm × L)/°C	Analog			
Magnet traverse velocity	any	interface			
Operating voltage	2028 V DC	Digital			
Current consumption	≤ 120 mA				
Operating temperature	−40+85 °C				
Storage temperature range	–40+100 °C				
GSD file	BTL504B2.GSD	CANopen			
Address assignment	mechanical switches and Master Class 2	interface			
Cable length [m]	< 100 < 200 < 400 < 1000 < 1200	DeviceNe			
Baud rate [Kbps]	12000 1500 900 187,5 93,7/19,2/9,6	PROFIBU			
Pin assignments	S103 5-pin S103 3-pin	interfac			
Control and data signals	Data GND 3	Magnets			
	RxD/TxD-N (A) 2	floating			
	RxD/TxD-P (B) 4	Magnets captive,			
	VP +5 V 1	captive,			
	+24 V 1				
Operating voltage and shielding	0 V (GND) 3	PF			
	Ground PROFIBUS-DP 5	General			
	Shield supply 4	data			
		Analog			

Please enter the code for the software configuration and nominal stroke length in the ordering code!

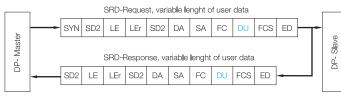
- Included:
- Transducer
- Mounting clamps with isolation washers
- and screws
- Short user's guide

Please order separately: Magnets from page 44 Connectors from page 153

#### Ordering example:

BTL5-T1\_0-M\_\_\_\_P-S103

Software configuration		Standard nominal stroke [mm]		
1	1 Magnet	0050, 0100, 0130, 0150, 0175, 0200,		
	1 Position	0225, 0250, 0300, 0350, 0360, 0400,		
	1 Velocity	0450, 0500, 0550, 0600, 0650, 0700,		
2	2 Position	0750, 0800, 0850, 0900, 0950, 1000,		
	2 Velocity	1100, 1200, 1250, 1300, 1400, 1500,		
		1600, 1700, 1750, 1800, 1900, 2000,		
		2250, 2500, 2750, 3000, 3250, 3500,		
		3550, 3750, 4000 or in 5 mm		
		increments (depending on interface) on		
1 11	<b>(f , , , , , , )</b>	request		



alog erface ital se rface rface Nopen rface viceNet rface OFIBUS-DP erface anets ting gnets tive, trol arm neral alog interface Magnets floating Magnets captive, control arm AT General data Analog

BIW General data Analog interface

interface

Modes Digital

pulse

. interface

VARAN bus interface Accessories

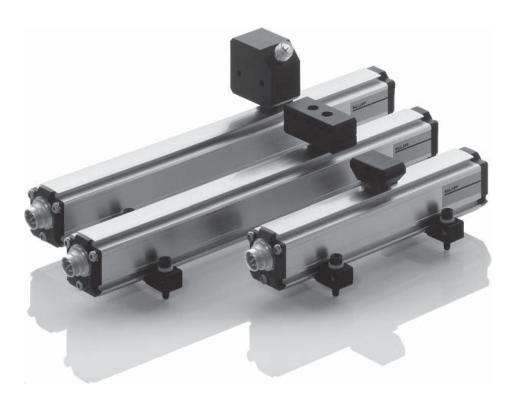


Balluff magnets are available in captive or floating design. Maximum resolution and repeatability are achieved using transducers with captive magnets.

The BTL5-P-4500-1 is an electromagnet and requires an operating voltage of 24V, which can be turned on and off for selective activation. This allows multiplex operation with multiple magnets on a single transducer, since only one magnet is active at a time.

Description	
for series	
Version	
Part number	
Housing material	
Weight	
Magnet traverse velocity	
Operating voltage	
Current consumption	
Operating temperature/Storage temperature range	
Included	
Accessories	

(please order separately)



Length			Number of mounting clamp pairs
	to	250 mm	1
251	to	750 mm	2
751	to	1250 mm	3
1251	to	1750 mm	4
1751	to	2250 mm	5
2251	to	2750 mm	6
2751	to	3250 mm	7
	more than	3251 mm	8

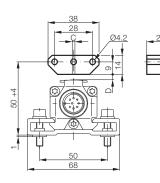
Mounting clamps with isolation washers and screws included with transducer.

1 pair of replacement clamps and screws, item no.: 110404

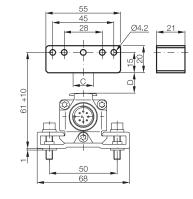


Profile P Series Magnets floating

Magnet	Magnet	Magnet	
BTL5 profile P	BTL5 profile P	BTL5 profile P	
free	free	free	
BTL5-P-3800-2	BTL5-P-5500-2	BTL5-P-4500-1	
Plastic	Plastic	Plastic	
approx. 12 g	approx. 40 g	approx. 90 g	
any	any	any	
		24 V DC	
		100 mA	
−40+85 °C	−40+85 °C	-40+60 °C	
Magnet	Magnet	Magnet	Р
2 fastening screws DIN 84 M4×35-A2 with			Gen
washers and nuts			data
		Straight connector BKS-B 19-1	Ana inte
		Right-angle connector BKS-B 20-1	Diei



Lateral offset: C =  $\pm 2 \text{ mm}$ Vertical distance of magnet: D = 0.1...4 mm



Ø14.<u>5</u>

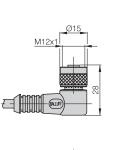
M12x1

42

Lateral offset:  $C = \pm 15 \text{ mm}$ Vertical distance of magnet: D = 5...15 mm

Lateral offset:  $C = \pm 2 \text{ mm}$ Vertical distance of magnet: D = 0.1...2 mm

Please indicate the cable length in the ordering code!
 03, 05, 10, 15
 PVC, 3 m, 5 m, 10 m or 15 m
 PU-03, PU-05, PU-10, PU-15
 PUR, 3 m, 5 m, 10 m or 15 m





General lata Analog interface Digital pulse interface SSI interface CANopen interface DeviceNet interface PROFIBUS-DP interface Magnets floating

M5x8

Magnets captive, control arm

PF General data Analog interface Magnets floating Magnets captive, control arm

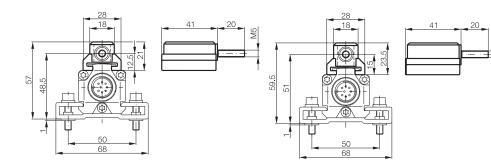
AT General data Analog interface Modes Digital pulse interface VARAN bus interface Accessories

BIW General data Analog interface





Description		Magnet	Magnet
for series		BTL5 profile P	BTL5 profile P
Version		captive	captive
Part number		BTL5-M-2814-1S	BTL5-N-2814-1S
Material	Housing	Anodized aluminum	Anodized aluminum
	Sliding surface	Plastic	Plastic
Weight		approx. 32 g	approx. 35 g
Magnet traverse velocity		any	any
Operating temperature/Storage t	emperature range	–40+85 °C	−40+85 °C





Length			Number of mounting clamp pairs
	to	250 mm	1
251	to	750 mm	2
751	to	1250 mm	3
1251	to	1750 mm	4
1751	to	2250 mm	5
2251	to	2750 mm	6
2751	to	3250 mm	7
	more than	3251 mm	8

Mounting clamps with isolation washers and screws included with transducer.

1 pair of replacement mounting clamps and screws, item no.: 110404



M5

**Profile P Series** Magnets captive, control arm

Magnet         BTL5 profile P         captive         BTL5-F-2814-1S         Anodized aluminum         Plastic         approx. 28 g         any         -40+85 °C	Description Control arm for series BTL5 profile P Version captive Part number BTL2-GS10A Material Al Weight approx. 150 g/m	
	M5 DIN 934 05H7 DIN 648 6 4 djustment range -5 mm	General data Analog interface Digital pulse interface SSI interface CANopen interface DeviceNet interface
	<ul> <li>Please the enter code for the nominal stroke in the ordering code!</li> <li>Ordering example:</li> <li>BTL2-GS10A</li> </ul>	PROFIBUS-DP interface Magnets floating Magnets captive, control arm
	Standard	PF
	0075, 0100, 0125, 0150, 0200, 0250, 0350, 0400, 0450, 0500, 0600, 0800, 1000, 1500, 2000	General data Analog interface Magnets floating Magnets captive, control arm
	Swivel eye Material number	AT General data 714619 Analog interface Modes Digital pulse interface VARAN bus interface Accessories
	When using captured magnets with ball joint and control arm, transverse forces do not impinge on the transducer system.	<b>BIW</b> General data Analog interface

www.balluff.com



The structural design, high degree of protection and simple installation of Balluff Micropulse transducers in a profiled housing makes them an excellent alternative to linear transducers, e.g. potentiometers, glass rulers and LVDTs. The linear sensing element is protected inside an extruded aluminum profile.

A passive magnet with no power supply marks the measuring point along the waveguide without making contact. Measuring ranges between 50 and 4572 mm are possible.

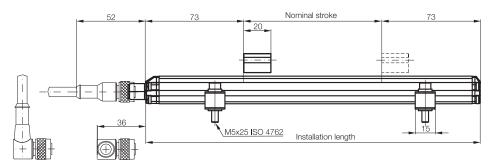
- Non-contact detection of the actual position
- IP 67, insensitive to contamination
- Wear-free
- Insensitive to shock and vibration
- Absolute output signal
- Max. resolution of 0.005 mm (depending on the processing electronics)
- Direct signal processing or in conjunction with processors for all control and regulating systems



**Profile Series PF** General data

Series	BTL6 profile PF	
Shock load	50 g/6 ms per IEC 60068-2-27	
Vibration	12 g, 102000 Hz per IEC 60068-2-6	
Polarity reversal protected	Yes (up to 36 V)	
Overvoltage protection	to 36 V	
Dielectric strength	500 VDC (GND to housing)	
Degree of protection as per IEC 60529	IP 67 (with BKS-S IP 67 connector attached)	
Housing material	Anodized aluminum	
Housing attachment	Compression clamps	
Connection type	Connectors	
EMC testing:		Р
RF emission	EN 55016-2-3 Group 1, Class A and B	General
Static electricity (ESD)	IEC 61000-4-2 Severity Level 3	data
Electromagnetic fields (RFI)	IEC 61000-4-3 Severity Level 3	Analog
Fast transients (BURST)	IEC 61000-4-4 Severity Level 3	interface
Surge voltage	IEC 61000-4-5 Severity Level 2	Digital pulse
Conducted interference induced	IEC 61000-4-6 Severity Level 3	interface
by high-frequency fields		SSI
Magnetic fields	IEC 61000-4-8 Severity Level 4	interface
Standard nominal strokes [mm]	0050, 0100, 0130, 0150, 0175, 0200, 0225, 0250, 0300, 0350, 0360, 0400, 0450, 0500, 0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900, 0950, 1000, 1100, 1200, 1250, 1300,	CANoper interface
	1400, 1500, 1600, 1700, 1750, 1800, 1900, 2000, 2250, 2500, 2750, 3000, 3250, 3500,	DeviceNe interface
	3550, 3750, 4000, 4250, 4500, 4572	PROFIBU

Transducers with floating magnet and S115 connection with BKS-S115/BKS-S116 connector for transducers with analog interface, page 50



General data Analog interface Digital pulse SI interface CANopen interface CANopen interface PROFIBUS-DP interface Magnets floating Magnets control arm

General data Analog interface Magnets floating Magnets captive, control arm

PF

AT General data Analog interface Modes Digital pulse interface VARAN bus interface Accessories

BIW General data Analog interface



Included:

- Transducer (select your interface from page 50)

- Short user's guide

- Mounting clamps with isolation washers and screws

Please order separately: Magnets from page 52 Connectors, page 156

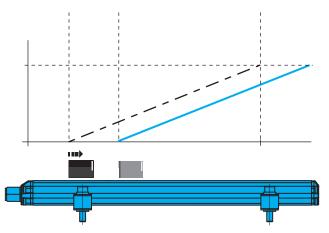


#### Output and measuring range setting

The measuring range and the output signal can be adapted to the relevant application requirements via programming inputs. In teach-in mode with inversion or reset function.

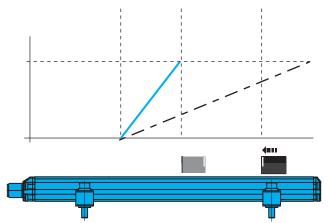
# Measuring range adjustment via programming inputs $L_a$ and $L_b$

1. Place magnet in new start position.



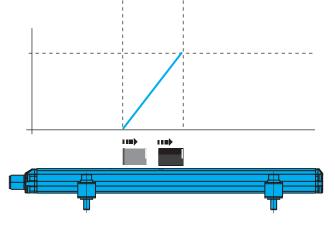
Adopting a new start position

2. Place magnet at new end position.



Adopting a new end position

3. The new measuring range



Series			
Output signal			
Transducer interface			
Input interface			
Part number			
Output voltage*			
Output current*			
Load current			
max. ripple			
Load resistance (recommended)			
System resolution			
Sampling rate			
max. non-linearity			
Temperature coefficient			
Operating voltage			
Current consumption			
Operating temperature			
Storage temperature range			
Pin assignments	Pin	Color	
Output signals	1	YE	
	2	GY	
	3	PK	
	4	RD	
	5	GN	
	8	WH	
Operating voltage	6	BU	
	7	BN	

Please enter the code for the output signal and the nominal stroke in the ordering code!

#### Preferred models interface A500 and E500

BTL6-A500-M\_\_\_\_PF-S115

BTL6-E500-M\_ \_ \_\_-PF-S115 are available from stock in the nominal lengths highlighted in blue.

- Included:
- Transducer
- Mounting clamps with isolation washers and screws
- Short user's guide

Please order separately: Magnets from page 52 Connectors, page 156

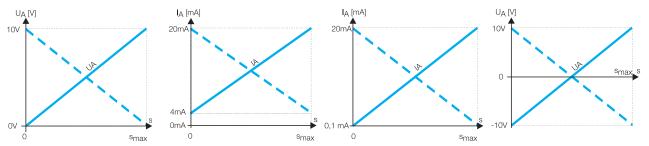


LED for diagnostics and 'programming assistance

Programmable input L<sub>b</sub>

# Profile Series PF Analog interface

BTL6 profile PF	BTL6 profile PF	BTL6 profile PF	BTL6 profile PF
analog	analog	analog	analog
A	E	C	G
analog	analog	analog	analog
BTL6-A500-MPF-S115	BTL6- <b>E</b> 500-MPF-S115	BTL6- <b>C</b> 500-MPF-S115	BTL6- <b>G</b> 500-MPF-S115
010 V			-1010 V
	420 mA	0.120 mA	
max. 5 mA			max. 5 mA
≤ 5 mV			≤ 5 mV
	≤ 500 ohms (500 ohms)	≤ 500 ohms (500 ohms)	
≤ 0.35 mV	≤ 0.7 µA	≤ 0.7 µA	≤ 0.35 mV
$f_{max} = 2 \text{ kHz}$	f <sub>max</sub> = 2 kHz	f <sub>max</sub> = 2 kHz	$f_{max} = 2 \text{ kHz}$
±200 µm up to 500 mm nominal stroke	±200 µm up to 500 mm nominal stroke	±200 µm up to 500 mm nominal stroke	±200 µm up to 500 mm nominal stroke
±0.04 % 500 max. nominal stroke			
30 ppm at 500 mm			
1030 V DC	1030 V DC	1030 V DC	1030 V DC
≤ 150 mA	≤ 150 mA	≤ 150 mA	≤ 150 mA
–25+70 °C	–25+70 °C	–25+70 °C	–25+70 °C
–40+100 °C	-40+100 °C	-40+100 °C	-40+100 °C
BTL6- <b>A</b> 500	BTL6- <b>E</b> 500	BTL6- <b>C</b> 500	BTL6- <b>G</b> 500
0 V	0 V	0 V	0 V
0 V Output	0 V Output	0 V Output	0 V Output
La (programming input)	La (programming input)	L <sub>a</sub> (programming input)	L <sub>a</sub> (programming input)
010 V	420 mA	0.120 mA	-1010 V
L <sub>b</sub> (programming input)	$L_{b}$ (programming input)	L <sub>b</sub> (programming input)	L <sub>b</sub> (programming input)
GND	GND	GND	GND
1030 V	1030 V	1030 V	1030 V



- Output signal can be inverted via programming inputs.

#### AT General data Analog interface Modes Digital pulse interface VARAN bus

interface Accessories

BIW General data Analog interface

PF

General

Analog interface Magnets

floating Magnets

data

#### Ordering example:

BTL6500-	•M•PF-S115	
Out	put signal	Standard nominal stroke [mm]
E 4 C (	010 V 420 mA 0.120 mA -1010 V	0050, 0100, 0130, 0150, 0175, 0200, 0225, 0250, 0300, 0350, 0360, 0400, 0450, 0500, 0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900, 0950, 1000, 1100, 1200, 1250, 1300, 1400, 1500, 1600, 1700, 1750, 1800, 1900, 2000, 2250, 2500, 2750, 3000, 3250, 3500, 3550, 3750, 4000, 4250, 4572

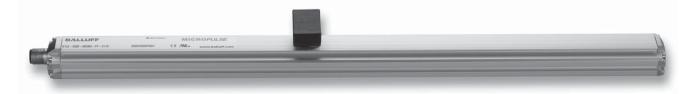


Balluff magnets are available in captive or floating designs. Maximum resolution and repeatability are achieved using transducers with captive magnets.

The BTL5-P-4500-1 is an electromagnet and requires an operating voltage of 24V, which can be turned on and off for selective activation. This allows multiplex operation with multiple magnets on a single transducer, since only one magnet is active at a time.

Description	
for series	
Version	
Part number	
Housing material	
Weight	
Magnet traverse velocity	
Operating voltage	
Current consumption	
Operating temperature/Storage temperature range	
Included	
Accessories	
(please order separately)	





L	.ength			Number of
				mounting clamp pairs
		to	250 mm	1
	251	to	750 mm	2
	751	to	1250 mm	3
	1251	to	1750 mm	4
	1751	to	2250 mm	5
	2251	to	2750 mm	6
	2751	to	3250 mm	7
	3251	to	3750 mm	8
	3751	to	4250 mm	9
		more than	4251 mm	10

Mounting clamps with isolation washers and screws included with transducer.

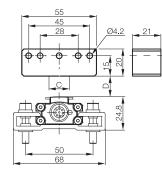
BTL6-A-MF07-A-PF/M5 1 pair of replacement mounting clamps and screws, item no.: 180961



Profile Series PF Magnets floating

Magnet	Magnet	Magnet
BTL6 profile PF	BTL6 profile PF	BTL6 profile PF
floating	floating	floating
BTL5-P-3800-2	BTL5-P-5500-2	BTL5-P-4500-1
Plastic	Plastic	Plastic
approx. 12 g	approx. 40 g	approx. 90 g
any	any	any
		24 V DC
		100 mA
–40+85 °C	−40+85 °C	-40+60 °C
Magnet	Magnet	Magnet
2 fastening screws DIN 84 M4×35-A2 with		
washers and nuts		
		Straight connector BKS-B 19-1

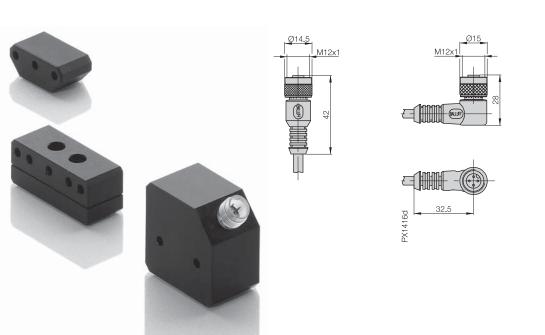
Lateral offset:  $C = \pm 2 \text{ mm}$ Vertical distance of magnet: D = 0.1...4 mm



Lateral offset:  $C = \pm 15 \text{ mm}$ Vertical distance of magnet: D = 5...15 mm Right-angle connector BKS-B 20-1-\_

Lateral offset:  $C = \pm 2 \text{ mm}$ Vertical distance of magnet: D = 0.1...2 mm

Please indicate the cable length in the ordering code!
 03, 05, 10, 15
 PVC, 3 m, 5 m, 10 m or 15 m
 PU-03, PU-05, PU-10, PU-15
 PUR, 3 m, 5 m, 10 m or 15 m



P General data Analog interface Digital pulse interface SSI interface CANopen interface DeviceNet interface PROFIBUS-DP interface Magnets floating Magnets captive, control arm

M5x8

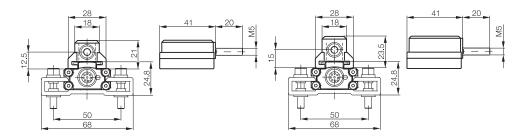
PF General data Analog interface Magnets floating Magnets captive, control arm

AT General data Analog interface Modes Digital pulse interface VARAN bus interface Accessories

BIW General data Analog interface



Description		Magnet	Magnet	
for series		BTL6 profile PF	BTL6 profile PF	
Version		captive	captive	
Part number		BTL5-M-2814-1S	BTL5-N-2814-1S	
Material	Housing	Anodized aluminum	Anodized aluminum	
	Sliding surface	Plastic	Plastic	
Weight		approx. 32 g	approx. 35 g	
Magnet traverse velocity		any	any	
Operating temperature/Storage	e temperature range	–40+85 °C	−40+85 °C	







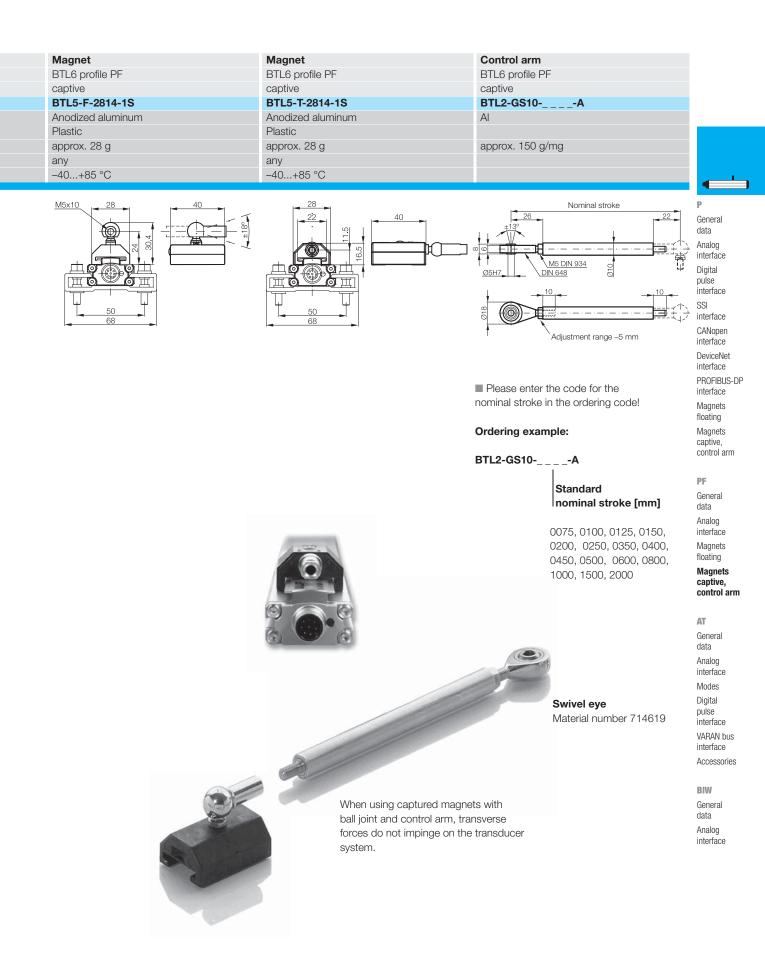
Length			Number of
			mounting clamp pairs
	to	250 mm	1
251	to	750 mm	2
751	to	1250 mm	3
1251	to	1750 mm	4
1751	to	2250 mm	5
2251	to	2750 mm	6
2751	to	3250 mm	7
3251	to	3750 mm	8
3751	to	4250 mm	9
	more than	4251 mm	10

Mounting clamps with isolation washers and screws included with transducer.

BTL6-A-MF07-A-PF/M5 1 pair of replacement mounting clamps and screws, item no.: 180961



**Profile Series PF** Magnets captive, control arm



www.balluff.com

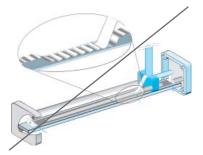


# Micropulse transducers – a non-contact alternative to contacting feedback devices

The structural design, high degree of protection and simple installation of non-contact Balluff Micropulse AT transducers in a profiled housing makes them an excellent alternative to contacting potentiometers. The linear sensing element is protected inside an extruded aluminum profile.

A passive magnet with no power supply marks the measuring point along the waveguide without making contact. Measuring ranges between 50 and 1500 mm are possible.

- Non-contact detection of the actual position
- IP 67, insensitive to contamination
- Wear-free
- Insensitive to shock and vibration
- Absolute output signal
- Direct signal processing or in conjunction with processors for all control and regulating systems



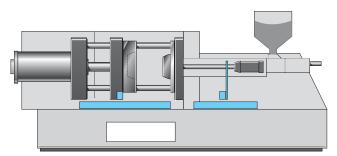


#### From optional to standard

Micropulse transducers have long been standard in the plastics machinery industry on high-precision machines and offered on standard machines as a non-contact option to potentiometric systems. The only thing that has stood in the way of more widespread use has been the comparatively high price.

The Micropulse AT has been designed in cooperation with development engineers from the plastics machinery industry and represents a system that is competitively priced and meets all the technical demands of the industry.

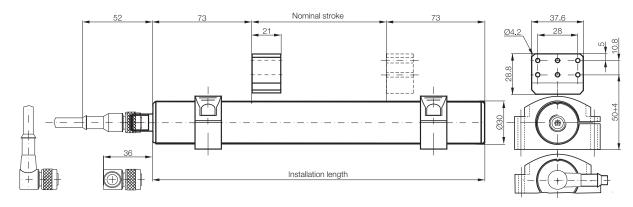
With the Micropulse AT position feedback system, now even standard machines can feature the benefit of minimum downtime provided by non-contact transducer systems.



**Profile Series AT** General data

Series **BTL6 Profile A1** BTL6-\_\_ \_\_-A1-S115 Part number \_-M\_\_\_ \_-A1-S115 BTL6-A301-M\_ 50 g/6 ms per IEC 60068-2-27 Shock load 12 g, 10...2000 Hz per IEC 60068-2-6 Vibration Polarity reversal protected yes Overvoltage protection yes Degree of protection as per IEC 60529 IP 67 (with BKS-S... IP 67 connector attached) Housing material Anodized aluminum Housing attachment Mounting clamps Connection type Connector M12, 8-pin standard EMC testing: **RF** emission EN 55016-2-3 Group 1, Class A+B Static electricity (ESD) IEC 61000-4-2 Severity Level 3 IEC 61000-4-3 Severity Level 3 Electromagnetic fields (RFI) Fast transients (BURST) IEC 61000-4-4 Severity Level 3 Line-induced disturbances, IEC 61000-4-6 Severity Level 3 induced by high-frequency fields IEC 61000-4-8 Severity Level 4

#### Transducers with floating magnet and S115 connection with BKS-S115/BKS-S116 connector for transducers with analog interface, digital pulse interface and VARAN bus interface from page 58



D General data Analog interface Digital pulse interface SSI interface CANopen interface DeviceNet interface PROFIBUS-DP interface Magnets floating Magnets captive,

PF General

control arm

data Analog interface Magnets floating Magnets captive. control arm

AT General

data Analog interface

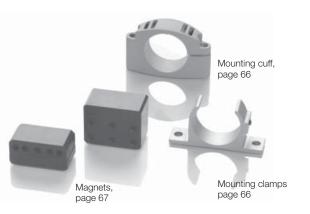
Modes Digital pulse . interface VARAN bus interface Accessories

BIW General data Analog interface

Included:

- Transducer (select your interface from page 58)
- Short user's guide

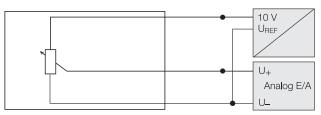
Please order separately: Magnets, page 67 Mounting clamps/cuff, page 66 Connectors, page 156



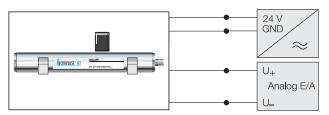


The analog outputs of the standard series BTL6-A110 are potential non-isolated.

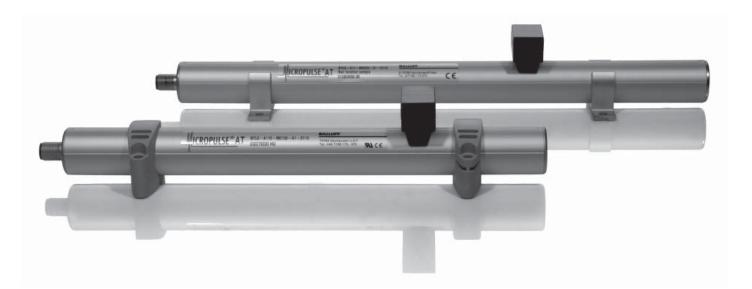
BTL6 transducers exist in the variants 0...10 V and -10...10 V with rising and falling characteristics. The version -10...10 V generally has potential isolated output signals.



Potentiometer connections, block diagram



Micropulse transducer connections, block diagram



# Profile Series AT Analog interface

Series		BTL6 Profile A1	BTL6 Profile A1		
Output signal		analog	analog		
Transducer interface		Α	G		
Input interface		analog	analog		
Part number		BTL6-A110-MA1-S115	BTL5-G310-MA1-S115		
Output voltage		010 V and 100 V	-1010 V and 1010 V		
Load current		max. 5 mA	max. 5 mA		
max. ripple		≤ 5 mV	≤5 mV		
System resolution		≤ 10 µm	≤ 10 µm		
Repeat accuracy		≤ 10 µm	≤ 10 µm		
Repeatability		≤ 20 µm	≤ 20 μm	Р	
Sampling rate		$f_{\text{STANDARD}} = 1 \text{ kHz}$	f <sub>standard</sub> = 1 kHz	General	
Non-linearity		$\leq \pm 200 \mu$ m up to 500 mm nominal stroke	$\leq \pm 200 \ \mu m$ up to 500 mm nominal stroke	data	
		typ. ±0.02 %, max. ±0.04 %	typ. ±0.02 %, max. ±0.04 %	Analog	
		5001500 mm nominal stroke	5001500 mm nominal stroke	interface	
Operating voltage		2028 V DC	2028 V DC	Digital pulse	
Current consumption		≤ 70 mA	≤ 70 mA	interface	
Polarity reversal protected		yes	yes	SSI	
Operating temperature		0+70 °C	0+70 °C	interface	
Storage temperature range		–40+100 °C	-40+100 °C	CANopen	
Pin assignments	Pin	BTL6-A110/A310	BTL6- <b>G</b> 310	interface	
Output signals	1	0 V Output	0 V Output	DeviceNet interface	
	2	0 V Output	0 V Output	PROFIBUS-DP	
	3	100 V	-1010 V	interface	
	5	010 V	1010 V	Magnets	
Operating voltage	6	GND	GND	floating	
	7	+24 V DC	+24 V DC	Magnets captive,	

AL,

UA (Pin 3)

Connect shield to housing,

pins 4 and 8 must remain unconnected.

Please enter the code for the output signal and the nominal stroke length in the ordering code.

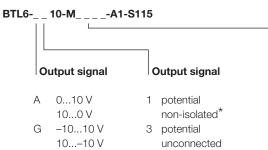
#### Preferred models

BTL6-A110-M\_ \_ \_\_-A1-S115 are available from stock in the nominal lengths highlighted in blue.

- Included:
- Transducer
- Short user's guide

Please order separately: Magnets, page 67 Mounting clamps/cuff, page 66 Connectors, page 156

#### Ordering example:



0100, 0130, 0150, 0160, 0175, 0200, 0225, 0250, 0275, 0300, 0325, 0350,

nominal stroke [mm]

Standard

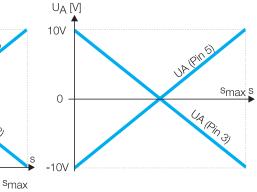
 $U_{A}[V]$ 

10V

0V

C

0225, 0250, 0275, 0300, 0325, 0350, 0360, 0375, 0400, 0425, 0450, 0475, 0500, 0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900, 0950, 1000, 1100, 1200, 1250, 1300, 1400, 1500, in 25 mm increments on request



control arm **PF** General data Analog interface Magnets floating Magnets captive, control arm

AT General data

Analog interface

Modes Digital pulse interface VARAN bus interface

Accessories

**BIW** General data Analog interface

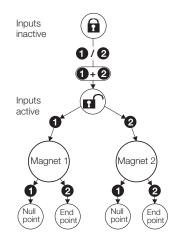
\*only for BTL6-A110-M\_\_\_\_-A1-S115



#### BTL6-A301-... 2 in 1

Two moving members on a machine often travel in the same direction. Each axis normally requires a separate feedback sensor. With the Micropulse AT you can now sense both movements at the same time using just one transducer with 2 analog outputs. The position of the respective null and end points can be set individually using 2 programming inputs.

The two measuring ranges may be adjacent, may overlap, and can be programmed for a rising or falling output signal. The transducer can be operated using one or two magnets. If one magnet leaves the measuring range or if only one is present, the position is indicated on Output 1. Output 2 then indicates an error value.



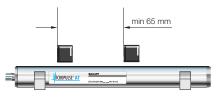
#### Teach-in

Used for changing the factory set null and end point to a new null and end point. First the magnet must be brought to the new null point and then to the new end position, and the respective values stored by pressing the button.

Example: Programming steps for setting the measuring range

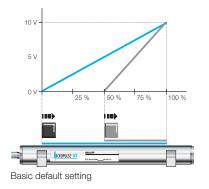
#### Mode selection

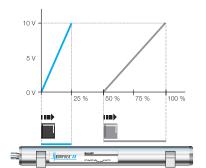
The standard function is the separate measurement of two positions. The programming inputs are used to switch the mode.



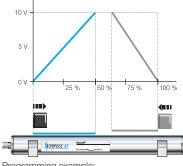
The separation between two magnets should not generally be less than 65 mm.

#### Mode 1: Single measurement of 2 positions (single measurement default setting 100 %/50 %)



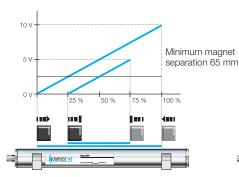


Programming example: Output 1: 25 % nominal stroke, signal rising Output 2: 50 % nominal stroke, signal rising



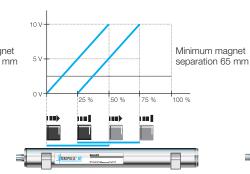
Programming example: Output 1: 50 % nominal stroke, signal rising Output 2: 37.5 % nominal stroke, signal falling

#### Mode 2: Differential measurement between 2 magnets



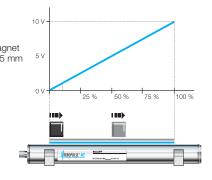
Default setting: Differential measurement Output 1: Standard travel signal (not shown) Output 2: differential signal 100 % nominal stroke = 10 V Programming example:

Programming example: Differential travel 50 % nominal stroke = 5 V differential signal



Programming example: Differential travel 50 % nominal stroke = 10 V differential signal

Mode 3: Single measurement (both magnets 0...100 %)



# "2 in 1" -100% stroke adjustment

# **Profile Series AT**

Analog interface

#### Features of Micropulse BTL6-A

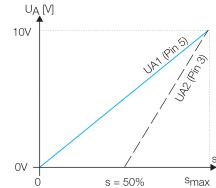
- 100 % adjustment of analog signal
- Error signal, no magnet within measuring range, transducer in calibration mode
- LED indicator for programming assistance
- Separate teach-in for all zero and span points
- Freely selectable single position or differential measurement

#### Measure two motions with one system

- One transducer senses two motions at the same time
- Significant cost reduction, half the installation costs
- Two 0...10 V analog outputs

Series			BTL6 Profile A1	
Output signal			analog	
Transducer interface			Α	
Input interface			analog	
Part number			BTL6-A301-MA1-S115	
Output			potential-free	
Output voltage			010 V programmable	
Load current			max. 5 mA	
max. ripple			≤5 mV	
System resolution			≤ 10 µm	
Repeat accuracy			≤ 10 µm	Р
Repeatability			≤ 20 µm	General
Sampling rate			f <sub>standard</sub> = 1 kHz (< 850 mm)	data
Non-linearity	Non-linearity		$\leq$ ±200 µm up to 500 mm nominal stroke	Analog interface
			typ. ±0.02 %, max. ±0.04 %	Digital
			5001500 mm nominal stroke	pulse
Operating voltage			1830 V DC	interface
Current consumption			≤ 100 mA	SSI
Polarity reversal prote			yes	interface
Operating temperatu			0+70 °C	CANopen interface
Storage temperature	0		–40+100 °C	DeviceNet
Pin assignments	Pin	Color*	BTL6- <b>A</b> 301	interface
Output signals	1	YE	Programming input La	PROFIBUS-
	2	GY	0 V Output	interface
	3	PK	010 V, output 2, programmable	Magnets
	4	RD	Programming input L <sub>b</sub>	floating
	5	GN	010 V, output 1, programmable	Magnets captive,
Operating voltage	6	BU	GND	control arm
	7	BN	+24 V DC	

Connect shield to housing, pin 8 (WH) must remain unconnected. \*Connector with cable BKS-S115/BKS-S116



-DP m PF General

data Analog interface Magnets floating Magnets captive. control arm

AT

#### General data

Analog interface

#### Modes Digital

pulse . interface VARAN bus interface Accessories

BIW

General data

Analog

interface

Please the enter code for the nominal stroke in the ordering code!

#### Preferred models interface A301

BTL6-A301-M\_\_\_\_A1-S115 are available from stock in the nominal lengths highlighted in blue.

- Included:
- Transducer
- Short user's guide

Please order separately: Magnets, page 67 Mounting clamps/cuff, page 66

#### Ordering example:

BTL6-A301-M\_\_\_\_A1-S115

Output signal	Standard nominal st
potential isolated	0160, 0175,
2 analog outputs	0325, 0350,
Single or differential	0475, 0500,
measurement, rising,	0800, 0850,
falling, zero and end	1250, 1300,
point programmable	25 mm incre

# troke [mm]

, 0200, 0225, 0250, 0275, 0300, ,0360,0375,0400,0425,0450, , 0550, 0600, 0650, 0700, 0750, ,0900,0950,1000,1100,1200, ), 1400, 1500, in 25 mm increments on request.

Standard nominal stroke (mm) 0050, 0100, 0130, 0150 for single magnet only



#### P110 interface

Compatible with BTA processors as well as controllers and modules from various manufacturers including Siemens, B & R, Phoenix Contact, Mitsubishi, Sigmatek, Esitron and WAGO.

Reliable signal transmission, even over cable lengths up to 500 m between BTA and transducer is assured by the noise-immune RS485 differential line drivers and receivers. Noise signals are effectively suppressed.

#### P110 replaces P1 and M1

Based on differing philosophies, two controller-specific interfaces have been established for the digital pulse versions. The difference lies in how the edges are processed. The falling edges are processed in the "P interface" and the rising edges in the "M interface". To reduce the number of different models to a minimum, the "P110 interface" was created as a universal pulse interface which combines both functions. The reference point for the propagation time measurement is the "start pulse".

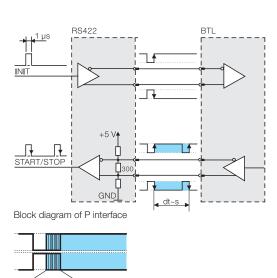
#### P111 interface – Cost savings using DPI/IP for start-up and installation

DPI/IP is a protocol for direct data interchange between a controller and transducer. The signal lines are used to send additional information such as manufacturer, stroke length and waveguide gradient. This allows start-up or replacement of a transducer without having to make manual changes to the controller parameters. The first to integrate these functions were the controllers from Sigmatek.

#### Features:

- Bi-directional communication
- Transducer controlled using Init and Start/Stop signals
- Integrated diagnostic functions
- Plug and Play
- Automatic parameterization reduces downtimes
- Sending of sensor model, stroke length, specific parameters
- Measurement length up to 3250 mm





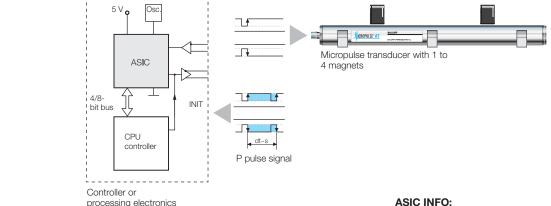
111000010111

#### Extremely precise digitizing chip for P110 pulse interface

Companies developing their own control and processing electronics can create a highly accurate P interface cost effectively and with minimum effort using the Balluff digitizing chip. The digitizing chip was developed as a high-resolution, configurable ASIC for Micropulse transducers with P interface.

#### Advantages:

- High resolution: the actual 1 µm of the BTL is fully supported by the 133 ps resolution of the chip (at low clock frequency 2 or 20 MHz)
- Position data from 4 magnets can be processed simultaneously
- 4/8-bit processor interface



ASIC INFO: +49 7158 173-370

# Digitizing chip 44QFP



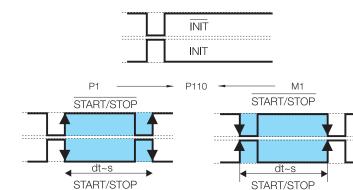
# **Plug and Play –** self-configuring

**Profile Series AT** Digital pulse interface

Series			BTL6 Profile A1		
Transducer interface			Pulse P11_		
Input interface			Pulse P11_		
Part number			BTL6- <b>P11_</b> -MA1-S115		
System resolution			processing-dependent		
Repeat accuracy			≤ 10 µm		
Repeatability			≤ 20 μm		
Resolution			≤ 10 µm		
Non-linearity			$\leq$ ±200 µm up to 500 mm nominal stroke		
			typ. ±0.02 %, max. ±0.04 % 5001500 mm nominal stroke		
Operating voltage			2028 V DC		
Current consumption $\leq 60$			$\leq$ 60 mA (at 1kHz)		
Operating temperature			0+70 °C		
Storage temperature range			-40+100 °C		
Pin assignments		Pin	BTL6- <b>P11_</b> -M		
Input/Output	Input	1	INIT		
signals	Output	2	START/STOP		
	Input	3	INIT		
	Output	5	START/STOP		
Operating voltage		6	GND		
		7	+24 V DC		

Connect shield to housing,

pins 4 and 8 must remain unconnected.



Please enter code for the data protocol and nominal stroke length in the ordering code.

#### Preferred models interface P11\_

BTL6-P11\_-M\_ \_ \_ -A1-S115 are available from stock in the nominal lengths highlighted in blue.

Included:

- Transducer

- Short user's guide

Please order separately: Magnets, page 67 Mounting clamps/cuff, page 66 Connectors, page 156

Ordering example:

0

1



DPI/IP\*

#### Standard Data protocol nominal stroke [mm] without

0050, 0075, 0100, 0130, 0150, 0160, 0175, 0200, 0225, 0250, 0300, 0350, (standard) 0360, 0400, 0450, 0500, 0550, 0600, with DPI/IP 0650, 0700, 0750, 0800, 0850, 0900, 0950, 1000, 1100, 1200, 1250, 1300, 1400, 1500, 1700, 2000, 2100, 2500, 2800, 3000, 3250, in 25 mm increments on request

\*the version without DPI/IP is only available up to a nominal stroke of 1500

General data Analog interface Digital pulse interface SSI interface CANopen interface DeviceNet interface PROFIBUS-DP interface Magnets floating Magnets captive, control arm

D

PF General data Analog interface Magnets floating Magnets captive. control arm AT General

data Analog interface Modes

Digital

. interface

VARAN bus

Accessories

interface

BIW

General data

Analog

interface

pulse



VARAN Ethernet technology and non-contact Micropulse distance measurement technology from Balluff form an outstanding team. Micropulse AT VARAN linear displacement systems detect the movements of highly dynamic axes in complex applications. The realtime Ethernet system is extremely economical, easy to

implement and simple to program. Widely available on the market, VARAN networks are used in combination with Sigmatek controllers, for example.

VARAN is fully integrated in hardware and designed according to IEEE 802.3 for standard Ethernet physics.

The simple design guarantees extremely rapid cycle times while achieving maximum data security and reducing implementation costs.

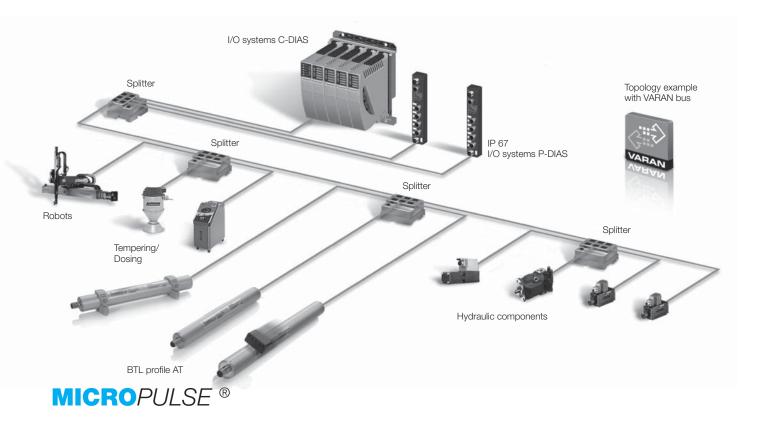
#### Micropulse AT V11V features:

- Robust non-contact IP 67 sensor reliable and wear-free
- Simple hardware structure low system costs
- M12, 8-pin plug connection simple economical cabling

#### **VARAN** features:

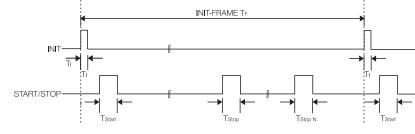
- Hard realtime data transfer cycle times < 100µs
- High reliability repeat in bus cycle
- Cost-conscious hardware design low overall system costs
- Open standard no restrictive dependences
- Easy implementation cost-effective







Series			BTL6 -V11V		
Output signal			VARAN (Ethernet)		
Transducer interface			V11V		
Input interface			VARAN		
Part number			BTL6- <b>V</b> 11V-MA1-S115		
System resolution			≤ 15 µm		
Repeat accuracy			≤ 30 µm		
Repeatability			≤ 30 µm		
Sampling rate			f <sub>standaed</sub> = 1 kHz (< 850 mm)		
Non-linearity			$\leq \pm 200 \mu\text{m}$ up to 500 mm nominal stroke		
			±0.04 %		
			5001500 mm nominal stroke		
Operating voltage	Operating voltage		1830 V DC		
Current consumption	Current consumption		≤ 75 mA		
Polarity reversal prot	ected		yes		
Operating temperatu	ire		0+70 °C		
Storage temperature range			-40+100 °C		
Pin assignments	Pin	Color	BTL6- <b>V</b> 11V		
Output signals	1				
	2	OG/WH	Tx+		
	3	OG	Tx-		
	4				
	5	GN/WH	Rx+		
	6	BU	GND		
	7	BN	+24 V DC		
	8	GN	Rx-		



Please enter code for the nominal stroke in the ordering code!

#### Included:

- Transducer

- Short user's guide

Please order separately: Magnets, page 67 Mounting clamps/cuff, page 66

#### Ordering example:

#### BTL6-V11V-M\_ \_ \_ \_-A1-S115

#### Standard nominal stroke [mm]

0160, 0175, 0200, 0225, 0250, 0275, 0300, 0325, 0350, 0360, 0375, 0400, 0425, 0450, 0475, 0500, 0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900, 0950, 1000, 1100, 1200, 1250, 1300, 1400, 1500, in 25 mm increments on request.

Standard nominal stroke (mm) 0050, 0100, 0130, 0150 for single magnet only

#### P General data Analog interface Digital pulse interface SSI interface CANopen interface DeviceNet interface PROFIBUS-DP interface Magnets floating Magnets captive, control arm

**PF** 

General data Analog interface Magnets floating Magnets captive, control arm

AT General data Analog interface Modes Digital pulse interface VARAN bus interface

# Accessories

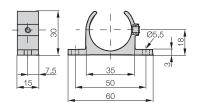
BIW General data Analog interface



The BTL6-A-3800-2 magnet can be operated at a distance of 4...8 mm from the top surface of the profile housing. In conjunction with mounting clamp BTL6-A-MF01-A-50 and mounting cuff BTL6-A-MF03-K-50, the mechanical installation is compatible with series BTL5-...-P-S32 with magnet BTL5-P-3800-2 or BTL5-P-5500-2.

As a result, large measurement lengths or transducers with a bus connection, for example, can be implemented optionally without requiring mechanical modifications.

#### Mounting clamps/cuff



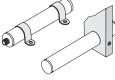
Mounting clamp Ordering code: BTL6-A-MF01-A-50 Includes: 1 clamp

Mounting clamp Ordering code: BTL6-A-MF01-A-43 Includes: 1 clamp

Mounting cuff Ordering code: BTL6-A-MF03-K-50 Includes: 1 cuff

When extreme shock and vibration loads are present, we recommend spacing mounting clamps every 250 mm.

Length			Number of mounting clamp pairs
	to	250 mm	1
251	to	750 mm	2
751	to	1250 mm	3
1251	to	1750 mm	4
1751	to	2250 mm	5
2251	to	2750 mm	6
2751	to	3250 mm	7
	more than	3251 mm	8

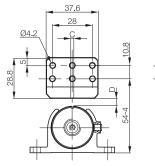


Custom mounting options

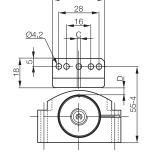
Connector accessories, page 156



Description	Magnet	Magnet
for series	BTL6 Profile A1	BTL6 Profile A1
Part number	BTL6-A-3800-2	BTL6-A-3801-2
Housing material	Plastic	Plastic
Weight	ca. 30 g	ca. 25 g
Magnet traverse velocity	any	any
Operating temperature/Storage temperature range	–40+85 °C	−40+85 °C
Included	Magnet	Magnet

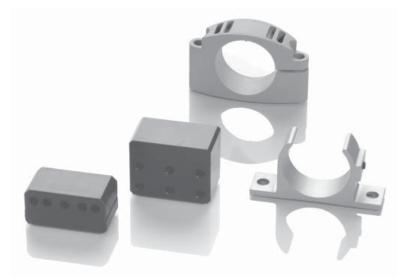


Lateral offset:  $C = \pm 5 \text{ mm}$ Vertical distance of magnet: D = 4...8 mm



37.6

Lateral offset:  $C = \pm 5 \text{ mm}$ Vertical distance of magnet: D = 4...8 mm



#### р General data Analog interface Digital pulse . interface SSI interface CANopen interface DeviceNet interface PROFIBUS-DP interface Magnets floating Magnets captive, control arm PF

21

General data Analog interface Magnets floating Magnets captive, control arm

AT General data Analog

interface

Modes Digital pulse interface VARAN bus interface

#### Accessories

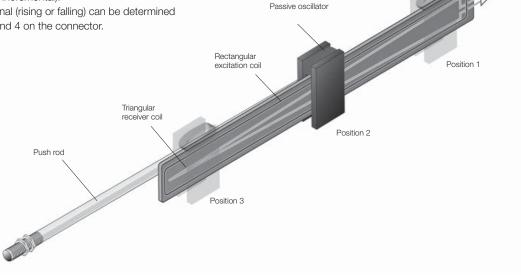
BIW General data Analog interface



#### The inductive BIW transducer is based on a new, patented operating principle that detects the actual position without making contact.

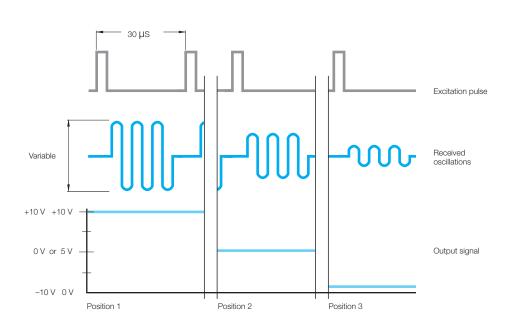
The BIW transducer contains an excitation/receiving sensor element and an oscillator, protected inside an extruded aluminum housing. The oscillator is attached to a rod which is secured on the moving member of the machine whose position needs to be determined. A momentary excitation pulse is applied to the rectangular excitation coil at a sampling rate of 32 KHz. The excitation pulse causes passive oscillations in the resonator. These are inductively coupled to a triangular receiving coil. The position is immediately available on the output and is absolute (not incremental).

The slope of the output signal (rising or falling) can be determined through the use of pins 1 and 4 on the connector.



#### Function of inductive Micropulse BIW technology:

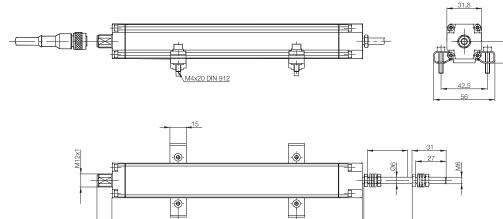
- Short exciter pulses excite the rectangular excitation coil
- The exciter pulses activate the passive oscillator on the magnet via the excitation coil
- The oscillator on the magnet transmits the frequency inductively to the triangular receiver coil without making contact
- The amplitude level varies according to the position of the magnet oscillator. Comparable to the amplitude level, the electronics integrated in the Micropulse BIW issue a standard analog, voltage or current signal



**Profile Series BIW1** General data

Series	BIW1
Shock load	100 g/2 ms
Vibration	12 g, 102000 Hz
Dielectric strength	500 V (GND to housing)
Degree of protection as per IEC 60529	IP 54
Housing material	Anodized aluminum
Mounting	Mounting clamps
Connection type	Connector M12, 8-pin standard
Standard nominal strokes [mm]	0075, 0100, 0130, 0150, 0175, 0225, 0260, 0300, 0360, 0375, 0400, 0450, 0500, 0600, 0650, 0750

#### Transducers with floating magnet and S115 connection with BKS-S115/BKS-S116 connector for transducers with analog interface, from page 70



C±1.5

A±2

\_\_\_\_B0

Housing length	A = nominal stroke + 100 mm	Calculation example:
Mechanical null point	B0 = 0 + 2 mm	
Electrical null point	B0 + 5 mm	BIW1M0100-P1-S115
Electrical stroke = mechanical stroke	B = nominal stroke + 10 mm	Nominal stroke 100
Recommend clamp distance		A = 200
Nominal stroke ≤ 300 mm	C = nominal stroke – 20 mm	B = 110
Nominal stroke 300 mm to $\leq$ 600 mm	C = nominal stroke – 15 mm	C = 80
Nominal stroke 600 mm	C = nominal stroke – 10 mm	

General data Analog interface Digital pulse interface SSI interface CANopen interface DeviceNet interface PROFIBUS-DP interface Magnets floating Magnets captive, control arm

PF General data

Analog interface Magnets floating Magnets captive, control arm

AT General data Analog interface Modes Digital pulse . interface VARAN bus interface

Accessories

BIW General data Analog interface

Included:

- Transducer
- Short user's guide - 2 mounting clamps BIW-A-MF01-M-43

Please order separately: Connectors, page 156



14

www.balluff.com

**Profile Series BIW1** Analog interface

#### Features:

- BIW transducers are characterized by:
- High resolution and repeatability
- Resistance to shock, vibration and noise fields
- An absolute rising or falling analog output signal
  A captive sensor element
  32 kHz sampling rate

- Potential-free
- Non-contact measuring principle

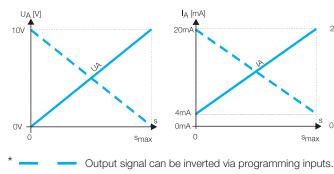
Series		
Output signal		
Transducer interface		
Input interface		
Part number		
Output voltage*U <sub>A</sub>		
Output current* I <sub>A</sub>		
Max. current load per output		
System resolution		
Repeat accuracy		
Sampling rate		
Max. non-linearity		
Operating voltage		
No-load current consumption		
Operating temperature		
Storage temperature range		
Pin assignments	Pin	
	1	
	2	
	3	
	4	
	5	
	6	
	7	
	8	
Shock load		
Vibration		
Dielectric strength		
Degree of protection as per IEC 60529		
Housing material		
Mounting		
Connection type		
Housing length A		
Mechanical stroke B		

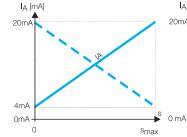


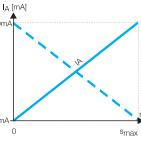
# **Profile Series BIW1**

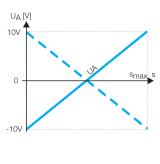
Analog interface

BIW1	BIW1	BIW1	BIW1	
analog	analog	analog	analog	
A	E	С	G	
analog	analog	analog	analog	
BIW1- <b>A</b> 310	BIW1- <b>E</b> 310	BIW1- <b>C</b> 310	BIW1- <b>G</b> 310	
010 V			–1010 V	
	420 mA	020 mA		
6 mA			6 mA	
5 µm	5 µm	5 µm	5 µm	
10 µm	10 μm	10 µm	10 µm	
typ. 32 kHz	typ. 32 kHz	typ. 32 kHz	typ. 32 kHz	Р
≤0.02 %	≤0.02 %	≤0.02 %	≤0.02 %	General
1830 V DC	1830 V DC	1830 V DC	1830 V DC	data
≤ 80 mA	≤ 80 mA	≤ 80 mA	≤ 80 mA	Analog
–20+85 °C	–20+85 °C	–20+85 °C	−20+85 °C	interface
-40+100 °C	-40+100 °C	-40+100 °C	–40+100 °C	Digital pulse
				interface
Slope selector	Slope selector	Slope selector	Slope selector	SSI
0 V Output	0 V Output	0 V Output	0 V Output	interface
reserved	reserved	reserved	reserved	CANopen
Slope selector	Slope selector	Slope selector	Slope selector	interface
010 V	420 mA	020 mA	-1010 V	DeviceNet interface
GND	GND	GND	GND	PROFIBUS
+24 V DC	+24 V DC	+24 V DC	+24 V DC	interface
reserved	reserved	reserved	reserved	Magnets
100g/2 ms	100g/2 ms	100g/2 ms	100g/2 ms	floating
12 g, 102000 Hz	Magnets			
500 V (GND to housing)	captive, control ari			
IP 54	IP 54	IP 54	IP 54	oona or ar
Anodized aluminum	Anodized aluminum	Anodized aluminum	Anodized aluminum	PF
Mounting clamps	Mounting clamps	Mounting clamps	Mounting clamps	General
Connector M12, 8-pin standard	data			
Nominal stroke + 100 mm	Analog			
Nominal stroke + 10 mm	interface			
				Magnets









ce ce en се Net ce BUS-DP се ets ets arm al ce ets floating Magnets captive, control arm

AT General data Analog interface Modes Digital pulse . interface VARAN bus interface Accessories

BIW General data

Analog

interface

Please enter the code for the output signal and nominal stroke length in the ordering code.

- Included:
- Transducer
- Short user's guide
- 2 mounting clamps BIW-A-MF01-M-43

Please order separately: Connectors, page 156



#### Ordering example:

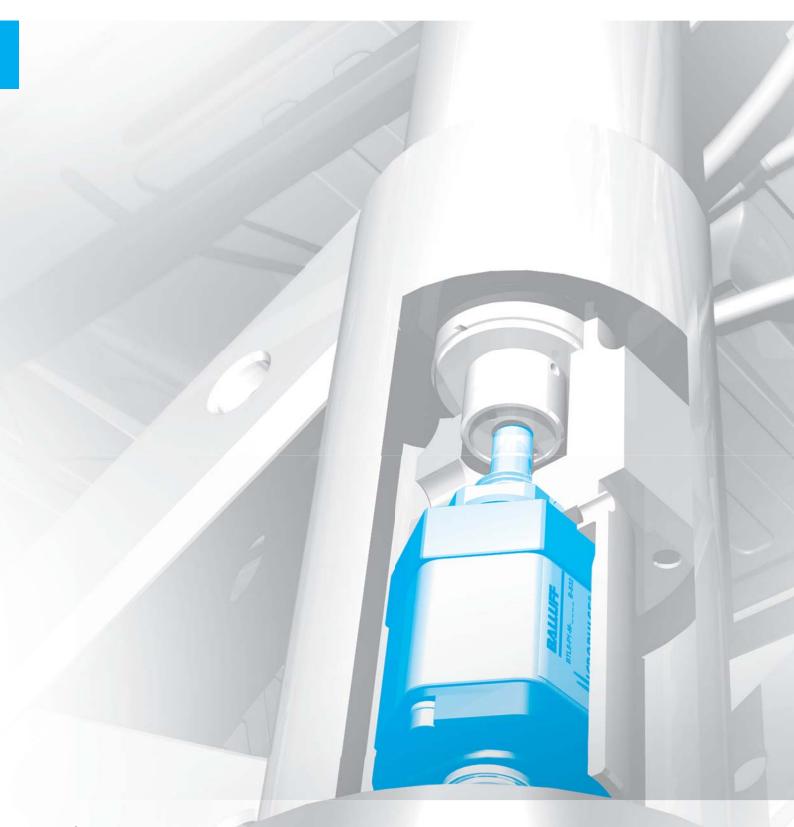
BIW1-\_310-M\_ \_-P1-S115

> Output signal

0...+10 V А G -10...+10 V Е 4...20 mA С 0...20 mA

Standard nominal stroke [mm]

0075, 0100, 0130, 0150, 0175, 0225, 0260, 0300, 0360, 0375, 0400, 0450, 0500, 0600, 0650, 0750







# MICROPULSE®

BTL7 MICROPULSE +	
General data 74	4
Analog interface 70	6
Programming 80	
BTL5	
General data 82	2
Digital pulse interface 84	4
SSI interface 80	6
CANopen interface 88	8
PROFIBUS-DP interface 92	2
4 programmable switching points 94	4
Floats 90	6
Magnets 9	7
Installation notes 98	8



Rod housings are mainly used in hydraulic drive applications. When installed in the pressure section of the hydraulic cylinder, the distance sensor requires the same pressure rating as the actual hydraulic cylinder. In practice, the sensor must be able

to withstand pressures up to 1000 bar. The electronics are integrated in an aluminum or stainless steel housing and the waveguide in a pressure-resistant tube made from nonmagnetic stainless steel that is sealed off at the face end with a welded plug. An O-ring seal in the flange at the opposite end seals off the high-pressure section. An magnet ring with magnets slides over the tube or rod with internal waveguide to mark the position prior to detection.



# **Shock and vibration resistant**

#### Pressure rated to 600 bar, High repeatability, Non-contacting, rugged

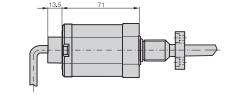
The BTL Micropulse transducer is a robust position feedback system for measuring ranges between 25 and 7620 mm as well as use under extreme ambient conditions.

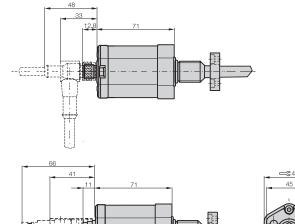
The actual waveguide is protected inside a high-pressure resistant stainless steel tube. The system is ideal for use in hydraulic cylinders for position feedback or as a level monitor with aggressive media in the food and chemical industries.

Series	BTL7 rod	
Shock load	150 g/6 ms as per IEC 60068-2-27	
Vibration	20 g, 102000 Hz as per IEC 60068-2-6	
Polarity reversal protected	ves	
Overvoltage protection	Transzorb protection diodes	
Dielectric strength	500 V AC (GND to housing)	
Degree of protection as per IEC 60529	IP 68 with cable outlet, IP 67 with BKS-S connector attached	
Housing material	Anodized aluminum/1.4571 stainless steel outer tube, 1.3952 stainless steel cast flange	
Mounting	Housing B thread M18×1.5, housing Z 3/4"-16UNF	
Pressure rating with 10.2 mm outer tube	600 bar installed in hydraulic cylinder	
Pressure rating with 8 mm outer tube	250 bar installed in hydraulic cylinder	
Connection type	Connector or integral cable	
EMC testing:		
RF emission	EN 55016-2-3 Group 1, Class A and B	
Static electricity (ESD)	IEC 61000-4-2 Severity Level 3	
Electromagnetic fields (RFI)	IEC 61000-4-3 Severity Level 3	
Fast transients (BURST)	IEC 61000-4-4 Severity Level 3	
Surge voltage	IEC 61000-4-5 Severity Level 2	
Conducted interference induced	IEC 61000-4-6 Severity Level 3	
by high-frequency fields		
Magnetic fields	IEC 61000-4-8 Severity Level 4	
Standard nominal strokes [mm]	0025, 0050, 0075, 0100, 0125, 0150, 0175, 0200, 0225, 0250,	
with 8 mm outer tube is the	0275, 0300, 0325, 0350, 0375, 0400, 0425, 0450, 0475, 0500,	
max. nominal stroke 1016 mm	0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900, 0950, 1000,	
	1100, 1200, 1300, 1400, 1500, 1600, 1700, 1800, 1900, 2000,	
	2250, 2500, 2750, 3000, 3250, 3500, 3750, 3850, 4000, 4250,	
	4500, 4750, 5000, 5250, 5500, 5750, 6000, 6250, 6500, 6750,	
	7000, 7250, 7500, 7600, 7620 or in 5 mm increments (depending	

on interface) on request

Please order separately: USB communication box, page 81 Magnets/floats, from page 96 Mounting nuts, page 97 Connectors, page 148/156

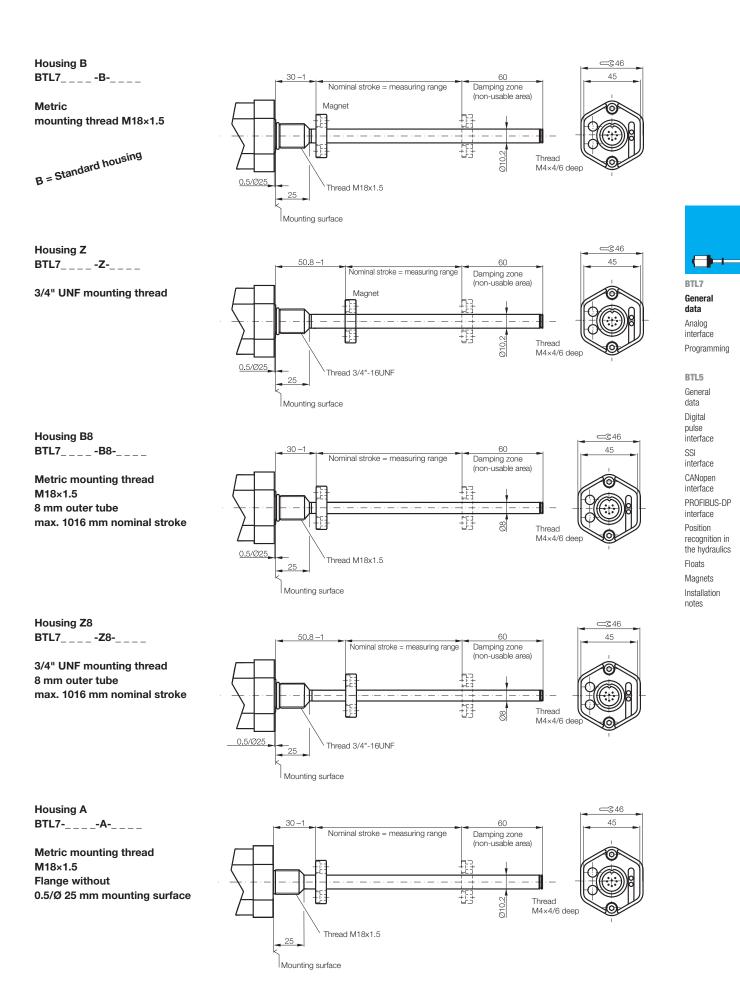






Caution! Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com

BTL7 Rod Series General data



www.balluff.com



#### Features of Micropulse BTL7-A/C/E/G...B

- Status LEDs for indicating operating status and diagnostics
- Extended application range with high degree
- of protection IP 68 (cable version)
- Electronics head can be replaced if needed
- Short housing, saves space
- Error signal, no magnet within measuring range

#### Flexible measuring range

The start and end point of the measuring range can be adapted to the application. The points are set directly on the unit using the calibration device included or remotely, see page 80.

Series Output signal Transducer interface Input interface Part number Output voltage Output current Load current max. ripple Load resistance System resolution Hysteresis Repeat accuracy Sampling rate, length-dependent Max. non-linearity

Temperature coefficient Operating voltage Current consumption at 24 V DC Polarity reversal protected Overvoltage protection Dielectric strength Operating temperature



Caution! Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com

Please enter the code for the output signal, nominal stroke, housing and connection type in the ordering code.

#### Preferred models

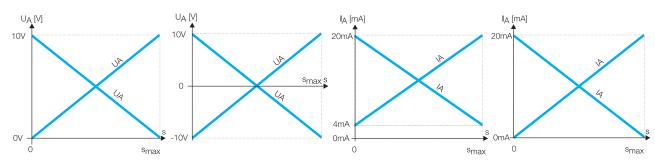
A110 and E100 interfaces BTL7-A110-M\_\_\_\_B-S32, BTL7-E100-M\_\_\_\_B-S32 are available from stock in the nominal lengths highlighted in blue.

- Included:
- Transducer
- Calibration device
- Short user's guide

Please order separately: USB communication box, page 81 Magnets/floats, from page 96 Mounting nuts, page 97 Connectors, page 148/156

**BTL7 Rod Series** Analog interface

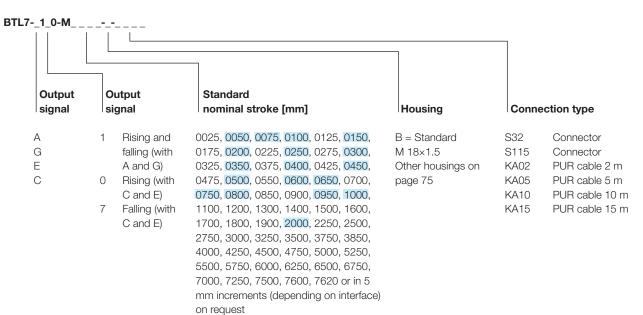
BTL7 rod	BTL7 rod	BTL7 rod	BTL7 rod	
analog	analog	analog	analog	
Α	G	E	С	
analog	analog	analog	analog	
BTL7- <b>A</b> 110-M	BTL7-G110-M	BTL5- <b>E</b> 1_0-M	BTL7- <b>C</b> 1_0-M	
010 V and 100 V	-1010 V and 1010 V			
		420 mA or 204 mA	020 mA or 200 mA	
max. 5 mA	max. 5 mA			
≤ 5 mV <sub>ss</sub>	≤ 5 mV <sub>ss</sub>			
		≤ 500 ohms	≤ 500 ohms	
≤ 0.33 mV	≤ 0.33 mV	≤ 0.66 µA	≤ 0.66 µA	
≤ 5 µm	≤ 5 µm	≤5 µm	≤ 5 µm	
System resolution/min. 2 µm				
max. 4 kHz	max. 4 kHz	max. 4 kHz	max. 4 kHz	_
$\pm 50 \ \mu m$ to $\leq 500 \ mm$ nominal stroke	$\pm 50 \ \mu m$ to $\leq 500 \ mm$ nominal stroke	$\pm 50 \ \mu m$ to $\leq 500 \ mm$ nominal stroke	$\pm 50 \ \mu m$ to $\leq 500 \ mm$ nominal stroke	
±0.01 % FS > 5500 mm nominal stroke	±0.01 % FS > 5500 mm nominal stroke	±0.01 % FS > 5500 mm nominal stroke	±0.01 % FS > 5500 mm nominal stroke	BTL7
±0.02 % FS > 5500 mm nominal stroke	±0.02 % FS > 5500 mm nominal stroke	±0.02 % FS > 5500 mm nominal stroke	±0.02 % FS > 5500 mm nominal stroke	General
≤ 30 ppm/K	≤ 30 ppm/K	≤ 30 ppm/K	≤ 30 ppm/K	data
2028 V DC	2028 V DC	2028 V DC	2028 V DC	Analog
≤ 150 mA	≤ 150 mA	≤ 150 mA	≤ 150 mA	interface
yes	yes	yes	yes	Programmir
yes	yes	yes	yes	
500 V AC (ground to housing)	BTL5			
–40+85 °C	–40+85 °C	–40+85 °C	−40+85 °C	General



neral ata Digital pulse interface SSI interface CANopen interface PROFIBUS-DP interface Position recognition in the hydraulics Floats Magnets Installation

notes

#### Ordering example:



**BTL7 Rod Series** Analog interface

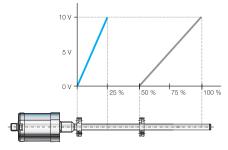
### USB-configurable Position + Velocity

#### Position and velocity

Two outputs can be assigned any position value and velocity signal using the USB interface.

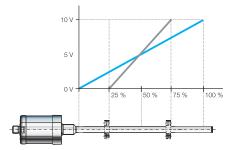
#### Mode examples:

#### Double magnet



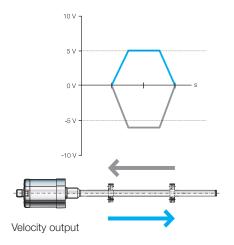
2 magnets, 2 movements, 2 output signals

#### Differential



Differential signal between 2 magnets, position and difference possible.

#### Velocity



Series Output signal Transducer interface Position signal input interface Part number Output signal factory setting Output signal adjusted via USB Configurable Load current max. ripple Load resistance System resolution Current consumption at 24 V DC Hysteresis Repeat accuracy Sampling rate, length-dependent Non-linearity, max. Temperature coefficient Operating voltage Polarity reversal protected Overvoltage protection Dielectric strength

#### Features of Micropulse\* USB-Configurable BTL7-A/E501

- Simple configuration and setting of the start and end point via the USB interface, fast startup
- "Easy Setup" for manual adjustment

Operating temperature

- Configurable dual output functions, position and velocity
- Increased operating reliability with status LEDs for indicating the operating status and diagnostic information
- Extended application range with high degree of protection IP 68 (cable version)
- Electronics head can be replaced if needed
- Short housing
- Error signals, no magnet within measuring range

Please enter the code for the output signal, nominal stroke, housing and connection type in the ordering code!

#### Preferred models

A501 and E501 interfaces BTL7-A501-M\_ \_ \_ -B-S32, BTL7-E501-M\_ \_ \_ -B-S32 are available from stock in the nominal lengths highlighted in blue.

Included:

- Transducer
- Calibration device
- Short user's guide

Please order separately: USB communication box, page 81 Magnets/floats, from page 96 Mounting nuts, page 97 Connectors, page 156

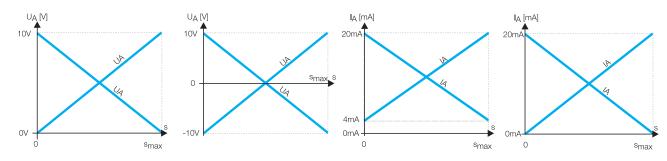
#### Caution!

Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com

# MICROPULSE +



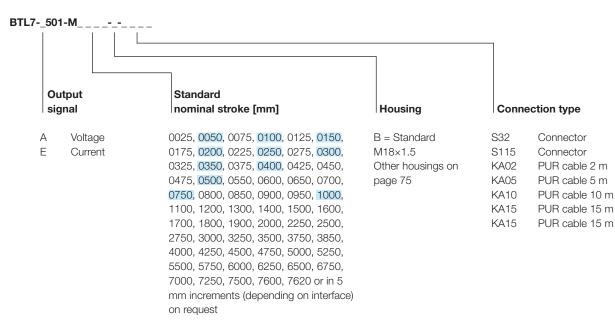
BTL7 rod	BTL7 rod
analog	analog
Α	E
analog	analog
BTL7- <b>A501</b> -M	BTL7- <b>E501</b> -M
010 V and 100 V	420 mA and 204 mA
-1010 V and 1010 V	020 mA and 200 mA
max. 5 mA	
$\leq 5 \text{ mV}_{ss}$	
	≤ 500 ohms
≤ 0.33 mV	≤ 0.66 µA
≤ 150 mA	≤ 180 mA
≤ 5 µm	≤5 μm
System resolution/min. 2 µm	System resolution/min. 2 µm
max. 4 kHz	max. 4 kHz
$\pm 50 \ \mu m$ to $\leq 500 \ mm$ nominal stroke	$\pm 50 \ \mu m$ to $\leq 500 \ mm$ nominal stroke
$\pm 0.01$ % FS > 500 $\leq$ 5500 mm nominal stroke	±0.01 % FS > 500≤ 5500 mm nominal stroke
$\pm 0.02$ % FS > 5500 mm nominal stroke	±0.02 % FS > 5500 mm nominal stroke
≤ 30 ppm/K	≤ 30 ppm/K
1030 V DC	1030 V DC
yes	yes
yes	yes
500 V AC (ground to housing)	500 V AC (ground to housing)
−40+85 °C	–40+85 °C



Programming BTL5 General data Digital pulse interface SSI interface CANopen interface PROFIBUS-DP interface Position recognition in the hydraulics Floats Magnets Installation notes

BTL7 General data Analog interface

#### Ordering example:





#### Setting options for the start and end point

		BTL7 Standard	BTL7-A/E501 Micropulse <sup>+</sup> USB-Configurable	
1. Ca	alibration device			
	– Teach-in			
	– Adjustment			
	– Online setting			
	– Easy Setup			
2. Re	emote setup			
3. U	SB-Configurate			

#### 1. Calibration device

#### 100 % start and end point calibration

Start and end point of the analog signal can be set to the desired position at the touch of a button. Depending on the application, "teach-in" or "adjust" mode is used, selectable by pressing a button combination. Two-color LED indicators assist the procedure.

#### "Easy Setup"

Buttons

inactive

Buttons

a

Teach-ir

End

active

Start point

For BTL7-A/E501, Micropulse<sup>+</sup> only. Simple programming mode for adjusting the start and end point of the transducer to the current application in just a few steps. The magnet is brought to the new position. Confirm by pressing a button. The "Adjust" function allows the new value to be fine-tuned for a stationary magnet. No error value is output during the setup procedure.

#### Teach-in

Used for changing the factory default start and end point to a new start and end point.

First the magnet must be brought to the new start point and then to the new end position, and the respective values stored by pressing the button.

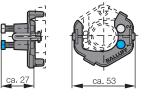
#### Adjust

Here you can adjust to a new start and end value. This may be required when you cannot physically move the magnet to the standard start and/or end point. Move the magnet to the new start and end position, and adjust the displayed value by pressing the button until the desired output values are reached.

#### **Online setting**

This programming function allows you to set the start and end point while in run mode, such as in a closed loop configuration. No error value is output during the setup procedure. The calibration range is limited to  $\pm 25$  %.

# Setting start and end point using the calibration device BTL7-A/E501



Adjust

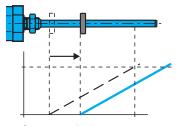
noin

## Selecting the calibration procedure BTL7 Standard

#### Procedure for teach-in, rising signal

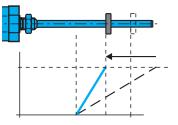
before	—	—	—	—	—	
after						

1. Place magnet in new null position.



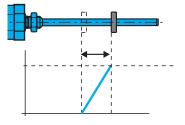
Store new null value

2. Place magnet at new end position.



Store new end value

3. Newly set measurement distance





#### 2. Remote setup aid

#### Remote setting of the start and end point using programming inputs

If the transducer is located in an inaccessible place or a hazardous area, the start and end point can be adjusted remotely. Teach-in, adjustment and online setting are identical to programming with the calibration device. Button 1 blue corresponds to programming input La and button 2 gray to input Lb.

#### 3. USB-Configurate

#### Start, end value setting and configuration via USB

The Micropulse Configuration Tool allows the quick and easy configuration of Balluff transducers type BTL7-A/E501... on a PC. The most significant features include:

- Online display of the current position of the magnet
- Graphical assistance for setting the functions and characteristic curves
- Display of information about the connected transducer
- Selectable number formats and units for display
- Factory reset possible
- Calibration device can be disabled
- Demo mode without having a transducer connected

#### Connecting the USB communication box

For model BTL7-A/E501-M...-S32/S115 transducers, the communication box can be installed between the transducer and the controller. The communication box is connected to the PC using a USB cable.

#### **USB** communication box

#### BTL7-A-CB01-USB-S32,

for BTL7-A/E501... with S32 connector

#### BTL7-A-CB01-USB-S115,

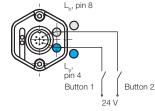
for BTL7-A/E501... with S115 connector

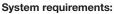
#### BTL7-A-CB01-USB-KA,

for BTL7-A/E501... with cable connection

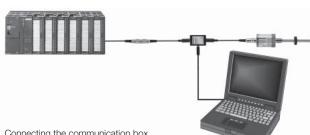
#### Included:

- USB communication box
- Cable set
- Short user's guide

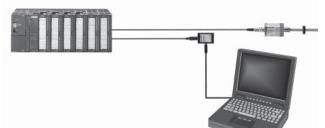




- Standard PC
- Windows 2000/XP/Vista
- Screen resolution at least 1024 × 768 pixels
- 10 MB available hard disk space
- Java Runtime Environment (JRE) version 1.4.2 or higher http://java.sun.com/getjava
- USB port



Connecting the communication box with S32 or S115 connector



Connecting the communication box via cable in the switching cabinet



The PC software and associated manual can be downloaded from the Internet at www.balluff.com/ downloads-btl7

#### Caution!

Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com



BTL7 General data Analog interface

Programming

BTL5 General data Digital pulse interface SSI interface CANopen interface PROFIBUS-DP interface Position recognition in the hydraulics Floats Magnets Installation notes

#### Pressure rated to 600 bar, High repeatability, Non-contact, rugged

General data

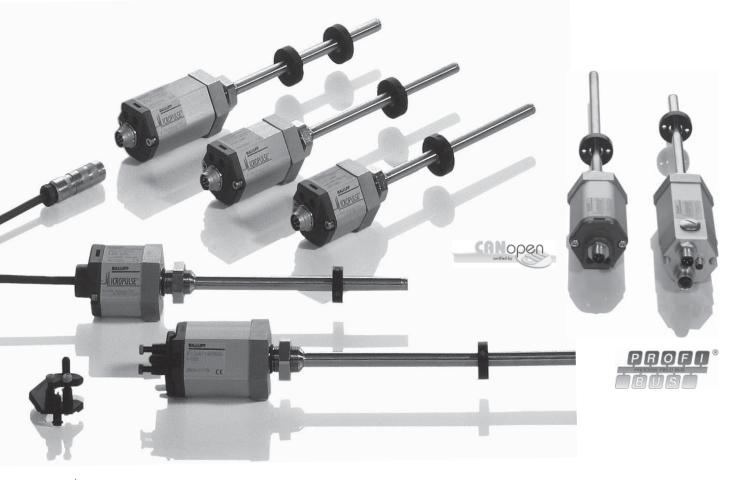
**BTL5 Rod Series** 

The BTL Micropulse transducer is a rugged position feedback system for use under extreme ambient conditions for measuring ranges between 25 and 5500 mm. The actual waveguide is protected inside a high-pressure resistant stainless steel tube. The system is ideal for use in hydraulic cylinders for position feedback or as a level monitor with aggressive media in the food and chemical industries.

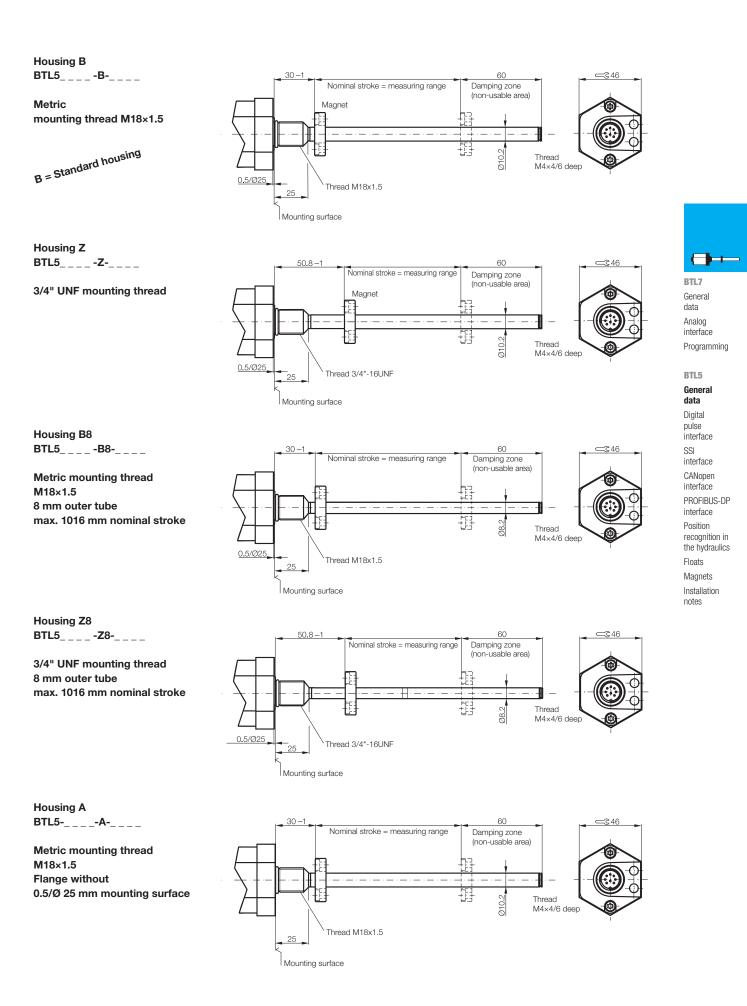
Series	BTL5 Rod
Shock load	100 g/6 ms per IEC 60068-2-27
Vibration	12 g, 102000 Hz per IEC 60068-2-6
Polarity reversal protected	yes
Overvoltage protection	Transzorb protection diodes
Dielectric strength	500 V DC (GND to housing)
Degree of protection as per IEC 60529	IP 67 (with BKS-S IP 67 connector attached)
Housing material	Anodized aluminum/1.4571 stainless steel outer tube, 1.3952 stainless steel cast flange
Housing attachment	Housing B thread M18×1.5, housing Z 3/4"-16UNF
Pressure rating with 10.2 mm outer tube	600 bar installed in hydraulic cylinder
Pressure rating with 8 mm outer tube	250 bar installed in hydraulic cylinder
Connection type	Connectors/cables
EMC testing:	
RF emission	EN 55016-2-3 Group 1, Class A
Static electricity (ESD)	IEC 61000-4-2 Severity Level 3
Electromagnetic fields (RFI)	IEC 61000-4-3 Severity Level 3
Fast transients (BURST)	IEC 61000-4-4 Severity Level 3
Conducted interference induced	IEC 61000-4-6 Severity Level 3
by high-frequency fields	
Standard nominal strokes [mm]	0025, 0050, 0075, 0100, 0125, 0150, 0175, 0200, 0225, 0250,
with 8 mm outer tube is the	0275, 0300, 0325, 0350, 0375, 0400, 0425, 0450, 0475, 0500,
max. nominal stroke 1016 mm	0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900, 0950, 1000,
	1100, 1200, 1300, 1400, 1500, 1600, 1700, 1800, 1900, 2000,
	2250, 2500, 2750, 3000, 3250, 3500, 3750, 3850, 4000 or in
	5 mm increments up to 5500 mm (depending on interface) on request
Included:	Please order separately:

- Transducer (select your
- interface from page 84) - Short user's guide

Please order separately: Magnets/floats, from page 96 Mounting nuts, page 97 Connectors, page 148



BTL5 Rod Series General data



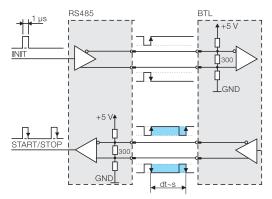


#### P Interface

Compatible with BTA/BTM processors as well as controllers and modules from various manufacturers including Siemens, B & R, Phoenix Contact, Mitsubishi, Sigmatek, Parker, Esitron and WAGO. Reliable signal transmission, even over cable lengths up to 500 m between BTA and BTL, is assured by the noise-immune RS485 differential line drivers and receivers. Noise signals are effectively suppressed.

#### **M** Interface

The M interface is a controller-specific interface variation.



Block diagram of P interface

#### Highly precise digitizing of the P pulse signal

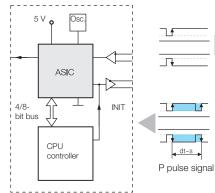
Companies developing their own control and processing electronics can create a highly accurate P interface cost effectively and with minimum effort using the Balluff digitizing chip. The digitizing chip was developed as a high-resolution, configurable ASIC for Micropulse transducers with P interface.

#### Advantages:

- Position resolution 1 µm!
- The 1 µm resolution of the Micropulse distance measurement system is achieved by the high resolution of the digitizing chip (133 pS). (Clock frequency 2 or 20 MHz)
- Position data from 4 magnets can be processed simultaneously
- 4/8-bit processor interface

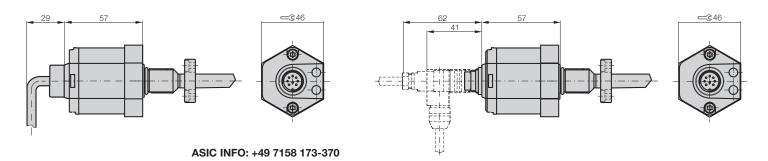


Digitizing chip 44QFP





Controller or processing electronics



# **BTL5 Rod Series** Digital pulse interface

Series		BTL5 Rod	BTL5 Rod			
Transducer interface		Pulse P	Pulse M			
Input interface				Pulse P	Pulse M	
Part number				BTL5- <b>P</b> 1-M	BTL5- <b>M</b> 1-M	
System resolution				processing-dependent	processing-dependent	
Repeat accuracy				2 $\mu m$ or ±1 digit depending on processing electronics	$2 \ \mu m \ or \pm 1$ digit depending on processing electronics	
Resolution				≤ 2 µm	≤ 2 µm	
Hysteresis				≤ 4 µm	≤4 µm	
Sampling rate				$f_{\text{STANDARD}} = 1 \text{ kHz} = \le 1400 \text{ mm}$	$f_{\text{STANDARD}} = 1 \text{ kHz} = \le 1400 \text{ mm}$	
Max. non-linearity				±100 µm up to 500 mm nominal stroke	±100 µm up to 500 mm nominal stroke	
				±0.02 % 5005500 mm nominal stroke	±0.02 % 5005500 mm nominal stroke	
Temperature coefficie	ent of over	all sys	tem	(6 µm + 5 ppm × L)/°C	(6 μm + 5 ppm × L)/°C	
Operating voltage		2028 V DC	2028 V DC			
Current consumption		≤ 90 mA	≤ 90 mA			
Operating temperatu	temperature -40+85 °C -40+85 °C		−40+85 °C			
Storage temperature	range			-40+100 °C	-40+100 °C	
Pin assignments		Pin	Color	BTL5- <b>P</b> 1-M	BTL5- <b>M</b> 1-M	
Input/Output	Input	1	YE	INIT	INIT	
signals	Output	2	GY	START/STOP	START/STOP	
	Input	3	PK	INIT	INIT	
	Output	5	GN	START/STOP	START/STOP	
Operating voltage		6	BU	GND	GND	
		7	BN	+24 V DC	+24 V DC	
		8	WH	(GND)	(GND)	

INIT

INIT

START/STOP

dt~s

START/STOP

4

Connect shield to housing

Please enter the code for the nominal stroke, housing and connection type in the ordering code.

#### Preferred models interface P

BTL5-P1-M\_\_\_\_B-S 32 are available from stock in the nominal lengths highlighted in blue.

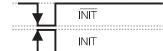
- Included:
- Transducer
- Short user's guide

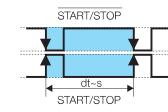
Please order separately: Magnets/floats, from page 96 Mounting nuts, page 97 Connectors from page 148

#### Ordering example:

# BTL5-P1-M\_\_\_\_-

Standard	Heusian
nominal stroke [mm]	Housing
0025, 0050, 0075, 0100, 0125, 0150,	B = Standard
0175, 0200, 0225, 0250, 0275, 0300,	M18×1.5, other
0325, 0350, 0375, 0400, 0425, 0450,	housings on page 83
0475, 0500, 0550, 0600, 0650, 0700,	
0750, 0800, <mark>0850</mark> , 0900, 0950, <mark>1000</mark> ,	
1100, 1200, 1300, 1400, 1500, 1600,	
1700, 1800, 1900, 2000, 2250, 2500,	
2750, 3000, 3250, 3500, 3750, 3850,	
4000, 4250, <mark>4500</mark> , 5000, 5250, 5500	
or in 5 mm increments on request.	





### 

BTL7 General data Analog interface Programming

BTL5 General data Digital pulse

#### pulse interface SSI interface

Interface CANopen interface PROFIBUS-DP interface Position recognition in the hydraulics Floats Magnets Installation notes

#### Connection type

S32	Connector
KA02	PUR cable 2 m
KA05	PUR cable 5 m
KA10	PUR cable 10 m
KA15	PUR cable 15 m



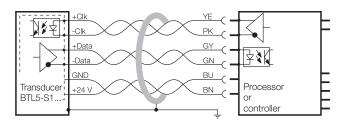
#### Standard SSI interface

Synchronous serial data transmission for controllers from various manufacturers, including Siemens, Bosch-Rexroth, WAGO, B & R, Parker, Esitron, PEP etc. as well as for Balluff BDD-AM 10-1-SSD and BDD-CC 08-1-SSD displays/controllers. Reliable signal transmission, even over cable lengths of up to 400 m between controller and BTL transducer is assured by especially noise-immune RS485/422 differential line drivers and receivers. Any noise signals are effectively suppressed.

Synchronized SSI interface BTL5-S1\_B-M\_\_\_\_P-\_\_\_ Micropulse transducers with synchronized SSI interface are suit-

able for dynamic control applications. The data acquisition in the transducer is synchronized with the external clock of the controller, permitting an optimum calculation of the velocity in the controller. The pre-requirement for this synchronous mode of transducer opera-

The **maximum sampling frequency**  $f_A$ , at which a new current value is generated for each sample, can be derived from the follow-





# SYNC -

mm	mm	Hz
Nie offentiet et al.	< 100	0500
< Nominal stroke	≤ 120 :	2500
120 < Nominal stroke	$\leq$ 475 :	2000
475 < Nominal stroke	≤ 750 :	1500
750 < Nominal stroke	≤ 1250 :	1000
1250 < Nominal stroke	≤2600 :	500
2600 < Nominal stroke	≤4000 ;	333

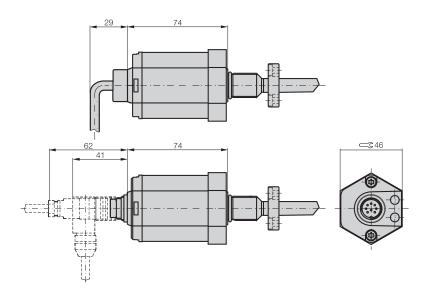
Clock frequency depends on the cable length

tion is consistent clock signal timing.

ing table:

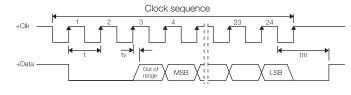
Cable length	Clock frequency
< 25 m	< 1000 kHz
< 50 m	< 500 kHz
< 100 m	< 400 kHz
< 200 m	< 200 kHz
< 400 m	< 100 kHz

## Super-fast 2.5 kHz sampling rate



# super linear and synchronized

Series			BTL5 Rod				
			synchronous serial				
Output signal							
Transducer interface	;		S				
Input interface			synchronous serial				
Part number			BTL5-S1M				
Part number synchro			BTL5-S1B-M				
System resolution de	pending or	n version (LSB)	1, 2, 5, 10, 20, 40 or 100 μm				
Repeat accuracy			±1 digit				
Hysteresis			≤ 1 digit				
Sampling rate			f <sub>standard</sub> = 2 kHz				
Max. non-linearity			$\pm$ 30 µm at 5 and 10 µm resolution or $\leq$ $\pm$ 2 LSB				
Temperature coeffici	ent of over	rall system	(6 μm + 5 ppm × L) /°C				
Operating voltage			2028 V DC				
Current consumptio	n		≤80 mA				
Operating temperatu	ure		-40+85 °C				
Storage temperature	e range		-40+100 °C	BTL7			
Pin assignments	Pin	Color		General			
Control and	1	YE	+Clk	data			
data signals	2	GY	+Data	Analog			
	3	PK	-Clk	interface			
	5	GN	-Data	Programmi			
Operating	6	BU	GND				
voltage (external)	7	BN	+24 V DC	BTL5			
	8	WH	must remain unconnected	General			



**BTL5 Rod Series** 

SSI interface

Please enter the code for the coding, system resolution, nominal stroke, design and connection type in the ordering code! Included:Transducer

- Short user's guide

Please order separately: Magnets/floats, from page 96 Mounting nuts, page 97 Connectors, page 148

#### Ordering example:

	Coding		/stem solution	Standard nominal stroke [mm]	Housing	Connection type	
0	Binary code	1	1 µm	0025, 0050, 0075, 0100, 0125, 0150,	B = Standard	S32	Connector
	rising	2	5 µm	0175, 0200, 0225, 0250, 0275, 0300,	M18×1.5,	KA02	PUR cable 2 m
	(24 bit)	3	10 µm	0325, 0350, 0375, 0400, 0425, 0450,	other housings	KA05	PUR cable 5 m
1	Gray code	4	20 µm	0475, 0500, 0550, 0600, 0650, 0700,	on page 83	KA10	PUR cable 10
	rising	5	40 µm	0750, 0800, 0850, 0900, 0950, 1000,		KA15	PUR cable 15
	(24 bit)	6	100 µm	1100, 1200, 1300, 1400, 1500, 1600,			
6	Binary code	7	2 µm	1700, 1800, 1900, 2000, 2250, 2500,			
	rising			2750, 3000, 3250, 3500, 3750, 3850,			
	(25 bit)			4000 or in 5 mm increments on request			
7	Gray code						
	rising						
	(25 bit)						

Programming BTL5 General data Digital pulse interface SSI interface CANopen

CANopen interface PROFIBUS-DP interface Position recognition in the hydraulics Floats Magnets Installation notes



#### **CANopen interface**

Based on CAN (ISO/IEC 7498 and DIN ISO 11898), CANopen provides a Layer-7 implementation for industrial CAN networks. The serial data protocol of the CAN specification is defined according to the producer-consumer principle as opposed to most other fieldbus protocols. This eliminates target addressing of the process data. Each bus station decides for itself how the received data are processed.

The CANopen interface of the Micropulse transducer is compatible with CANopen conforming with CiA Standard DS301 Rev. 3.0, and with CAL and Layer 2 CAN networks.

#### CAN-BUS features

- Line topology, star structure also possible via repeaters
- Low-cost wiring with two-wire cable
- Fast response times, high data integrity using CRC, hamming distance of 6
- 1 MBit/s with cable lengths < 25 m
- Protocol limits number of stations to 127
- Using multiple magnets: A minimum spacing of > 65 mm must be maintained.

CANopen offers a high level of flexibility with respect to functionality and data exchange. Using a standard data sheet in the form of an EDS file it is easy to link the Micropulse transducers to any CANopen system.

#### Process Data Object (PDO)

12 Micropulse transducers send their position information optionally in one, two or four PDOs with 8 bytes of data each. The contents of the PDOs are freely configurable. The following information can be sent:

- Current magnet position with resolution in 5 µm increments
- Current velocity of the magnet with resolution selectable in 0.1mm/s increments
- Current status of the four freely programmable cams per magnet.

#### Synchronization Object (SYNC)

Serves as a net-wide trigger for synchronizing all network participants. When the SYNC object is received, all Micropulse transducers connected to the bus store their current position and velocity information and then send it sequentially to the controller. This assures time-synchronous acquisition of the measured values.

#### LED

Display of the CANopen status to DS303-3

#### FMM

The sensor can be operated as a 4-magnet type, whereby the sensor itself recognizes how many magnets are currently active. So if only two magnets are positioned in the measuring range, a valid value is output for the first two positions and a defined error value for positions 3 and 4.

#### **Emergency Object**

This object is sent with the highest priority and is used for example for error messages when the cam states change.

#### Service Data Object (SDO)

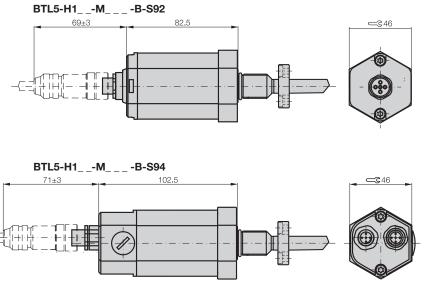
Service Data Objects transmit the parameters for the transducer configuration. The transducer may be configured on the bus by the controller or offline using a PC with a configuration tool which runs under Windows. The configuration is stored in the non-volatile memory of the transducer.

Nopen

CiA 199911-301v30/11-009

#### Use of multiple magnets

A minimum spacing of > 65 mm must be maintained.



## Position + Velocity

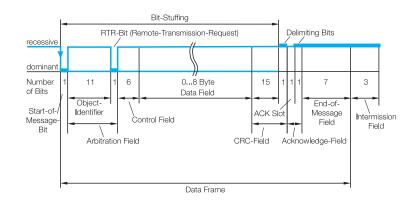
BTL5 Rod Series CANopen<sup>®</sup> interface

Series			BTL5 R	od							
Output signal C			CANopen								
Transducer interface			н								
Input interface			CANope	n							
Part number			BTL5-H	1M		2					
			BTL5-H	BTL5- <b>H</b> 1MS94							
Repeat accuracy			±1 digit								
System resolution	Positior	า	5 µm inc	rements							
configurable	Velocity	/	0.1 mm/	's increme	ents						
Hysteresis			≤ 1 digit								
Sampling rate			f <sub>STANDARD</sub>	= 1 kHz							
Max. non-linearity			±30 μm at 5 μm resolution								
Temperature coefficie	ent of over	all system	$(6 \mu m + 5 ppm \times L)/^{\circ}C$								
Operating voltage			2028 V DC								
Current consumption	I		≤ 100 m	≤ 100 mA							
Operating temperatu	re		-40+8	5 °C							
Storage temperature	range		-40+1	00 °C							
Cable length [m] per	CiA DS30	1	< 25	< 50	< 100	< 250	< 500	< 1000	< 1250	< 2500	
Baud rate [kBaud] pe	er CiA DS3	301	1000	800	500	250	125	100	50	20/10	
Pin assignments	Pin	Color									
Control and	1	WH	CAN_GN	١D							
data signals	2	BN	+24 V								
	3	BU	0 V (GNI	D)							
	4	GY	CAN_HI	GH							
	5	GN	CAN_LC	W							

Please enter the code for the software configuration, baud rate and nominal stroke in the ordering code. Cable upon request.

- Included:
- Transducer
- Short user's guide

Please order separately: Magnets/floats, from page 96 Mounting nuts, page 97 Connectors, page 150/151



Using the CANopen interface and cable lengths up to 2500 m, the signal is sent at a length-dependent baud rate to the controller. The high noise immunity of the connection is achieved using differential drivers and by the data monitoring scheme.

#### Ordering example:

BTL5-H1 BTL5-H1	-M				
-	oftware onfiguration	B	aud rate	Standard nominal stroke [mm]	Housing
1	1 × position and	0	1 MBaud	0025, 0050, 0075, 0100, 0125, 0150,	B = Standard
	1 × velocity	1	800 kBaud	0175, 0200, 0225, 0250, 0275, 0300,	M18×1.5, more
2	2 × position and	2	500 kBaud	0325, 0350, 0375, 0400, 0425, 0450,	housings on page 83
	2 × velocity	3	250 kBaud	0475, 0500, 0550, 0600, 0650, 0700,	
3	4 × position	4	125 kBaud	0750, 0800, 0850, 0900, 0950, 1000,	
		5	100 kBaud	1100, 1200, 1300, 1400, 1500, 1600,	
		6	50 kBaud	1700, 1800, 1900, 2000, 2250, 2500,	
		7	20 kBaud	2750, 3000, 3250, 3500, 3750, 3850,	
		8	10 kBaud	4000 or in 5 mm increments on request.	

# BTL7

General data Analog interface Programming

BTL5 General data Digital pulse interface

SSI interface

#### CANopen interface

PROFIBUS-DP interface Position recognition in the hydraulics Floats Magnets Installation notes



#### **Connecting analog sensors**

BTL5-H1A/C/E  $\_$  -M  $\_$   $\_$  -A/B/Y/Z(8)-C001 allows the use of analog pressure or temperature sensors in parallel with the transducer. Measured values from the analog sensor can be transmitted to the CAN protocol with ease as a result.

Analog inputs are detected in series, not simultaneously. The second channel is converted while the first channel is being read and vice versa.

The analog process signal from the BTL is converted into digital form because the analogue values from the BTL are only processed in digital form. The overall conversion time consists of the time the converter takes to perform the conversion plus additional processing time in the microcontroller ( $\mu$ C).

The analogue values are displayed in the form of a fixed-point number in the 2's complement. The prefix of the analog value is always in bit 15.

- "0" for +

- "1" for -

#### Use of 1-4 magnets

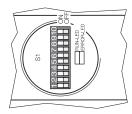
The number of magnets can be preset to 1-4 via CANopen. The transducer is preset to operate with an magnet on delivery. A minimum spacing of > 65 mm must be maintained.

#### Setting the node ID

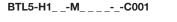
For the node ID, values between 0...63 are preset using the DIP switch S1.1...S1.6.

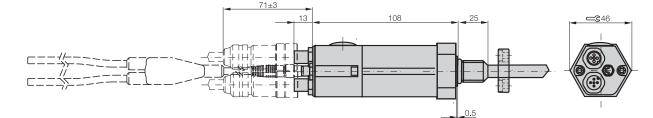


CiA 199911-301v30/11-009



#### Top view of DIP switch S1





Node ID can be set by DIP switch.



Series			BTL5 R	od							
Output signal			CANope	CANopen							
Transducer interface			н								
Input interface			CANope	n							
Part number			BTL5-H	1M							
CANopen Version			potential	-free							
Repeat accuracy			±1 digit								
System resolution	Position		5 µm inc	rements							
configurable	Velocity		0.1 mm/	's increme	ents						
Hysteresis			$\leq$ 1 digit								
Sampling rate			f <sub>STANDARD</sub> :	= 1 kHz							
Max. non-linearity			±30 µm	at 5 µm r	esolution						
Temperature coefficient	nt of overa	ll system	(6 μm + 5 ppm × L)/°C								
Operating voltage			2028 V DC								
Current consumption			≤ 100 mA								
Operating temperatur	е		-40+85 °C								
Storage temperature	range		-40+100 °C								
Cable length [m] per (			< 25	< 50	< 100	< 250	< 500	< 1000	< 1250	< 2500	
Baud rate [kBaud] per	r CiA DS30	)1	1000	800	500	250	125	100	50	20/10	
Pin assignments	Pin	Color									
Control and	1	WH	CAN_GN	١D							
data signals	2	BN	+24 V								
	3	BU	0 V (GNI								
	4	GY	CAN_HI	GH							
	5	GN	CAN_LC	W							
Analog connection	1		+24 V								
Sensor	2		0 V								
	3		Input ser								
	4		Input ser	nsor 2							

Please enter the code for the input configuration, baud rate and nominal stroke in the ordering code. Cable upon request.

- -C001

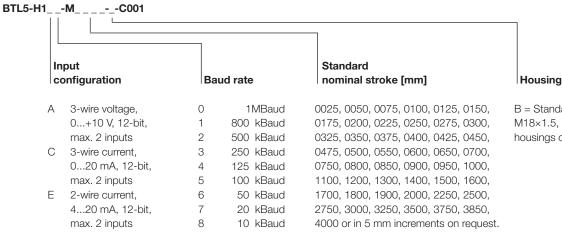
- Included:
- Transducer
- Short user's guide

Ordering example:

Please order separately: Magnets/floats, from page 96 Mounting nuts, page 97 Connectors from page 150

#### Bit-Stuffing RTR-Bit (Remote-Transmission-Request) Delimiting Bits recessive dominan Number of Bits 11 6 0...8 Byte 15 7 З Data Field Object End-of-Start-of-Identifier ACK SIÓ Message Intermission Control Field Message Field Field Bit CRC-Field Arbitration Field Acknowledge-Field Data Frame

Using the CANopen interface and cable lengths up to 2500 m, the signal is sent at a length-dependent baud rate to the controller. The high noise immunity of the connection is achieved using differential drivers and by the data monitoring scheme.



B = Standard M18×1.5, more housings on page 83

#### www.balluff.com

BTL7 General data Analog interface Programming

BTL5 General data Digital pulse interface SSI interface CANopen interface

PROFIBUS-DP interface

recognition in

the hydraulics Floats

Position

Magnets

notes

Installation

## **BTL5 Rod Series PROFIBUS-DP** interface

### User-friendly hardware and software set-up

As the market leading standard for serial data transmission for process automation, PROFIBUS-DP is the ideal choice for implementing automation tasks with cycle times of > 5 ms.

#### Data transmission

A PROFIBUS telegram can contain up to 244 bytes of user data per telegram and station. The BTL5-T uses max. 32 bytes (max. 4 position values and max. 4 velocity values) for process data transmission. Up to 126 active stations (Address 0...125) can be connected on PROFIBUS-DP. User data cannot be sent with station address 126. This address is used as the default address for bus stations that have to be parameterized by a Class 2 master (for setting the device address if there are no mechanical switches available). Each PROFIBUS station has the same priority. Prioritizing of individual stations is not intended, but can be done by the master since the bus transmission only makes up a fraction of the process cycle anyway. At a transfer rate of 12 Mbps, the transmission time for an average data telegram is in the 100 µs range.

#### Master

There are two types of possible masters for PROFIBUS-DP. Master Class 1 carries out the user data interchange with the connected slaves. Master Class 2 is intended for startup and diagnostic purposes and may be used to briefly assume control of a slave.

#### **GSD (Device Master Data)**

The length of the data exchangeable with a slave is defined in the Device Master Data file (GSD) and is checked by the slave with the configuration telegram and confirmed for correctness. In modular systems, various configurations are defined in the GSD file. Depending on the desired functionality, one of these configurations can be selected by the user when the system is configured. The BTL5-T is a modular device with the possibility of selecting the number of magnets (position values).

#### Slave

Once a PROFIBUS master has received the parameter set defined for the slave, it is able to exchange data.

The parameter set consists of slave parameters and configuration data. The parameter data contain the description of the slave settings (e.g. resolution of a position value). The configuration data describe the length and structure of the data telegram.

#### Process data

Under PROFIBUS-DP the default is for process data to be sent from the master to slaves acyclically and for the slave data to then be queried. To ensure synchronization of multiple devices, the master may use the SYNC and FREEZE services.

#### DP/V1 and DP/V2 isochronous mode

Isochronous mode enables guick and deterministic data exchange by means of clock synchronicity on the bus system. A cyclic equidistant clock signal is sent by the master to all bus devices. This signal allows master and slaves to be synchronized irrespective of application – with an accuracy  $< 1 \ \mu s$ .

#### Cross traffic between slaves

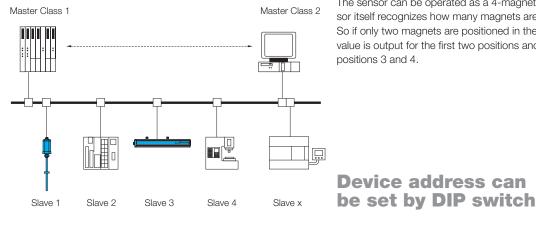
Cross traffic permits two DP slaves to exchange data directly with each other: the master ensures that the slave publishes its data on the bus with a request for "Data-eXchange-Broadcast" (DXB-Request) and thus makes it available to other slaves. Since the process data is available in the process periphery without being diverted through the master application, cross-traffic permits very fast control system responses.

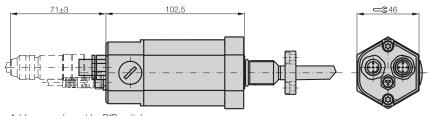
#### Acyclic services

The DP functions for prioritized communication allow the transfer of acyclic read and write functions between master and slaves, independently of the cyclic user data traffic. The transfer of acyclic data is performed at a lower priority in parallel to the high speed cyclic data exchange - as if in the background. The background / foreground split means the ratio of cyclic to acyclic data can be adjusted if required.

#### FMM

The sensor can be operated as a 4-magnet type, whereby the sensor itself recognizes how many magnets are currently active. So if only two magnets are positioned in the measuring range, a valid value is output for the first two positions and a defined error value for positions 3 and 4.





Address can be set by DIP switch.

## **Position +** Velocity

**BTL5 Rod Series PROFIBUS-DP** interface

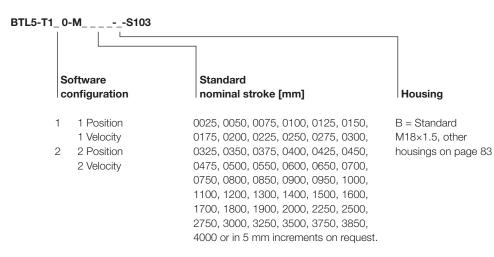
Series	BTL5 Rod	
Output signal	PROFIBUS-DP	
Transducer interface	Т	
Input interface	PROFIBUS-DP	
Part number plug version S103	BTL5- <b>T</b> 1_0-MS103	
Profibus-Version	EN 50170, Encoder profile	
Profibus interface	potential-free	
Repeat accuracy	±1 digit	
System resolution Position	5 µm increments configurable	
configurable Velocity	0.1 mm/s increments configurable	
Hysteresis	≤ 1 digit	
Sampling rate	$f_{\text{STANDARD}} = 1 \text{ kHz}$	
Max. non-linearity	±30 μm at 5 μm resolution	
Temperature coefficient of overall system	$(6 \ \mu m + 5 \ ppm \times L)/^{\circ}C$	
Magnet traverse velocity	any	
Operating voltage	2028 V DC	BTL7
Current consumption	≤ 120 mA	General
Operating temperature	–40+85 °C	data
Storage temperature range	-40+100 °C	Analog
GSD file	BTL504B2.GSD	interface
Address assignment	mechanical switches and Master Class 2	Programming
Cable length [m]	< 100 < 200 < 400 < 1000 < 1200	
Baud rate [Kbps]	12000 1500 900 187,5 93,7/19,2/9,6	BTL5
Pin assignments	S103 5-pin S103 3-pin	General data
Control and data signals	Data GND 3	Digital
	R×D/T×D-N (A) 2	pulse
	R×D/T×D-P (B) 4	interface
	VP +5 V 1	SSI
Operating voltage and shielding	+24 V 1	interface
	0 V (GND) 3	CANopen interface
	Ground PROFIBUS-DP 5	PROFIBUS-DP
	Shield supply 4	interface

Please enter the code for the software configuration, nominal stroke and housing in the ordering code.

- Included:
- Transducer
- Short user's guide

Please order separately: Magnets/floats, from page 96 Mounting nuts, page 97 Connectors from page 153

#### Ordering example:

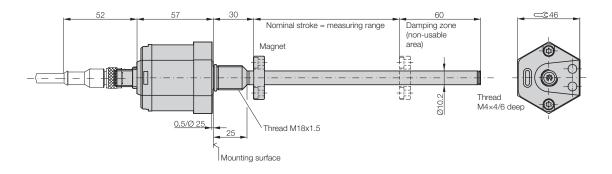




ANopen nterface ROFIBUS-DP nterface Position recognition in the hydraulics Floats Magnets Installation notes





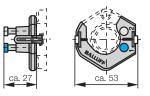


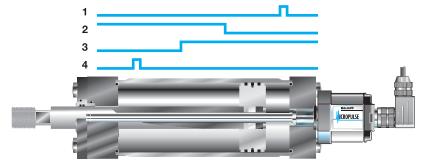
# Single position measurement between the piston limits of travel on standard cylinder series

#### Advantages:

- no special design of piston or piston rod necessary
- no permanent magnet required between the piston seals
- easy to program
- no time-consuming adjustment
- high resolution and repeatability
- switching points freely programmable using calibration device or programming inputs

#### Calibration device BTL5-A-EH01 for programming the outputs







## Position + Velocity

**BTL5 Rod Series** 4 programmable switching points

Series		BTL5 Rod					
Transducer interface		F					
Input interface		digital					
Part number		BTL5- <b>F</b> 1_0-MS115					
Output signals		4 switching outputs					
Max. current load per output		100 mA					
Max. current load for 4 outputs		200 mA					
Repeat accuracy		±0.1 mm					
Sampling rate		f <sub>standard</sub> = 1 kHz = ≤ 1400 mm					
Operating voltage		24 V DC ±20 %					
No-load current consumption		≤ 100 mA					
Operating temperature		-40+85 °C					
Storage temperature range		-40+100 °C					
Pin assignments	Pin 1	Output 1					
	Pin 2	Output 2					
	Pin 3	Output 3	BTL7				
	Pin 4	Output 4	General				
	Pin 5	La; Programming input (low-active)	data				
	Pin 6	GND	Analog				
	Pin 7	+24 V DC	interface				
	Pin 8	L <sub>b</sub> ; Programming input (low-active)	Programming				
Shock load		100 g/6 ms per IEC 60068-2-27					
Vibration		12 g, 102000 Hz per IEC 60068-2-6	BTL5				
Dielectric strength		500 V DC (GND to housing)	General data				
Degree of protection as per IEC	60529	IP 67 (with BKS-S IP 67 connector attached)	Digital				
Housing material		Anodized aluminum/1.4571 stainless steel outer tube, 1.3952 stainless steel cast flange	pulse				
Mounting		Thread M18×1.5, 3/4"-16UNF on request	interface				
Pressure rating		600 bar installed in hydraulic cylinder	SSI				
Connection type		Connectors	interface				
			CANopen interface				

Please enter the code for the output, nominal stroke and housing in the ordering code.

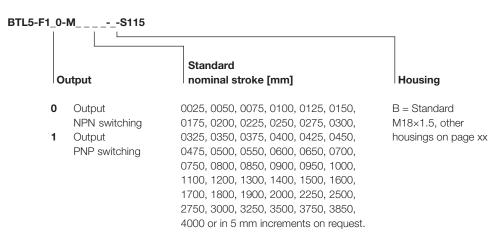
- Included:
- Transducer
- Short user's guide
- Calibration device

Please order separately: Magnets/floats, from page 96 Mounting nuts, page 97 Connectors, page 156

# Ausgang 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1</

Analog interface Programming BTL5 General data Digital pulse interface SSI interface CANopen interface PROFIBUS-DP interface PROFIBUS-DP interface PROFIBUS-DP interface PROFIBUS-DP interface Position recognition in the hydraulics Floats Magnets Installation notes

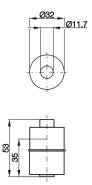
#### Ordering example:

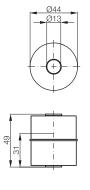


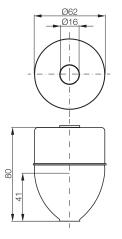
www.balluff.com

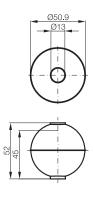
# **BTL5 Rod Series** Float

Description	Float	Float	Float	Float
for series	BTL rod	BTL rod	BTL rod	BTL rod
Part number	BTL2-S-3212-4Z	BTL2-S-4414-4Z	BTL2-S-6216-8P	BTL2-S-5113-4K
Material	Stainless steel 1.4404	Stainless steel 1.4404	Stainless steel 1.4404	Stainless steel 1.4404
Weight	approx. 20 g	approx. 34 g	approx. 69 g	approx. 35 g
Magnet traverse velocity				
Operating temperature/ Storage temperature range	–20+120 °C	–20+120 °C	–20+120 °C	–20+120 °C
Displacement in water	approx. 35 mm	approx. 31 mm	approx. 41 mm	approx. 26 mm
Pressure rating (static)	24 bar	20 bar	15 bar	40 bar
Part number PA 60				
glass fiber reinforced				
Material				
Weight				
Magnet traverse velocity				
Operating temperature/				
Storage temperature range				





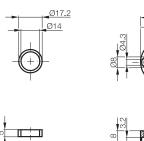


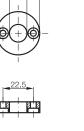


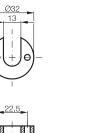




Magnet	Magnet	Magnet	Magnet	Magnet
BTL rod	BTL rod	BTL rod	BTL rod	BTL rod
BTL-P-0814-GR-PAF	BTL-P-1013-4R	BTL-P-1013-4S	BTL-P-1012-4R	BTL-P-1014-2R
Ferrite integrated in PA	Al	Al	AI	Al
approx. 1.5 g	approx. 12 g	approx. 12 g	approx. 12 g	approx. 10 g
any	any	any	any	any
-40+100 °C	-40+100 °C	-40+100 °C	–40+100 °C	–40+100 °C
	BTL-P-1013-4R-PA		BTL-P-1012-4R-PA	
	PA 60 glass fiber reinforced		PA 60 glass fiber reinforced	
	approx. 10 g		approx. 10 g	
	any		any	
	-40+100 °C		-40+100 °C	











data Digital pulse interface SSI interface CANopen interface PROFIBUS-DP interface Position

recognition in the hydraulics Floats Magnets Installation notes

....



M18×1.5 mounting nut Order designation: BTL-A-FK01-E-M18×1.5

3/4"-16 UNF mounting nut Order designation: BTL-A-FK01-E-3/4"-16 UNF



Caution! Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com

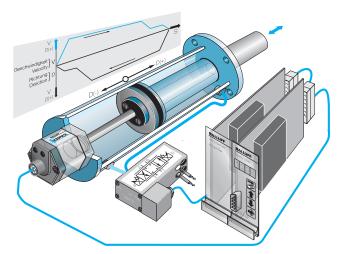


#### SSI-SYNC -

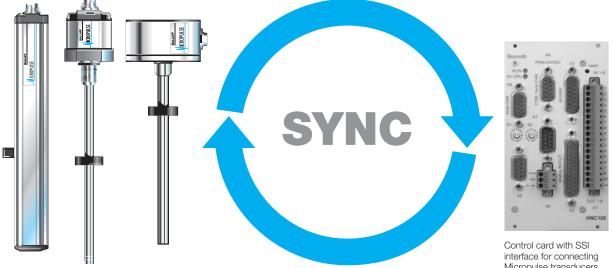
#### better control characteristics and higher dynamics

The absolute positioning information from the Micropulse transducer is transmitted synchronously to the axis control card. This synchronous data acquisition enables exact calculation of the velocity and acceleration.

The feedback of these variables (velocity and acceleration) allows the damping and resonant frequency of a hydraulic system to be increased. These measures permit greater loop gain and with it better control behavior and higher dynamics.

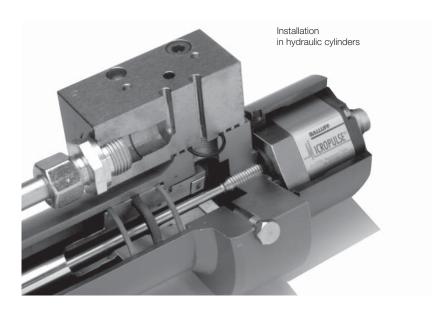


Application with hydraulic cylinder in a control circuit



Micropulse transducer BTL5-S1\_ \_- -S1-...

interface for connecting Micropulse transducers

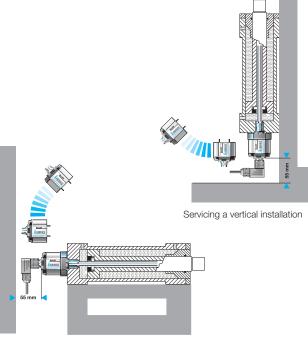




#### Hassle-free service

Cylinder-mounted transducers are often located in difficult to access spots. If a transducer is damaged or fails, replacing the complete transducer with head and waveguide is often a difficult and expensive proposition.

Should a problem occur in the electronics of the Micropulse transducer, the electronics head can be easily and quickly exchanged for a new one. The fluid circuit also remains intact, with no draining necessary.



Servicing a horizontal installation

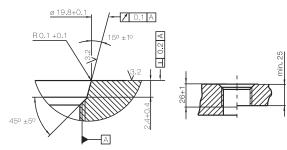
**BTL7** General data

#### Installation

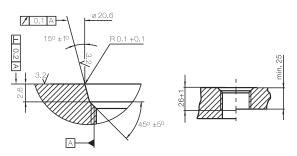
The Micropulse transducer BTL has a mounting thread M18×1.5. We recommend that the mounting is made of non-magnetizable material. If magnetizable materials are used, the installation must be carried out as shown in the drawing below. Sealing is at the flange mounting surface using the supplied O-ring 15.4×2.1 with M18×1.5 thread.

#### Insertion hole

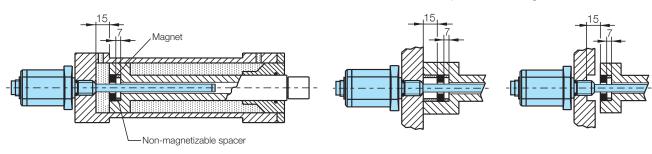
The transducer is fitted with a M18 $\times$ 1.5 (as per ISO) or 3/4"-16UNF (as per SAE) mounting thread. Depending on the version, the insertion hole may have to be manufactured prior to assembly.

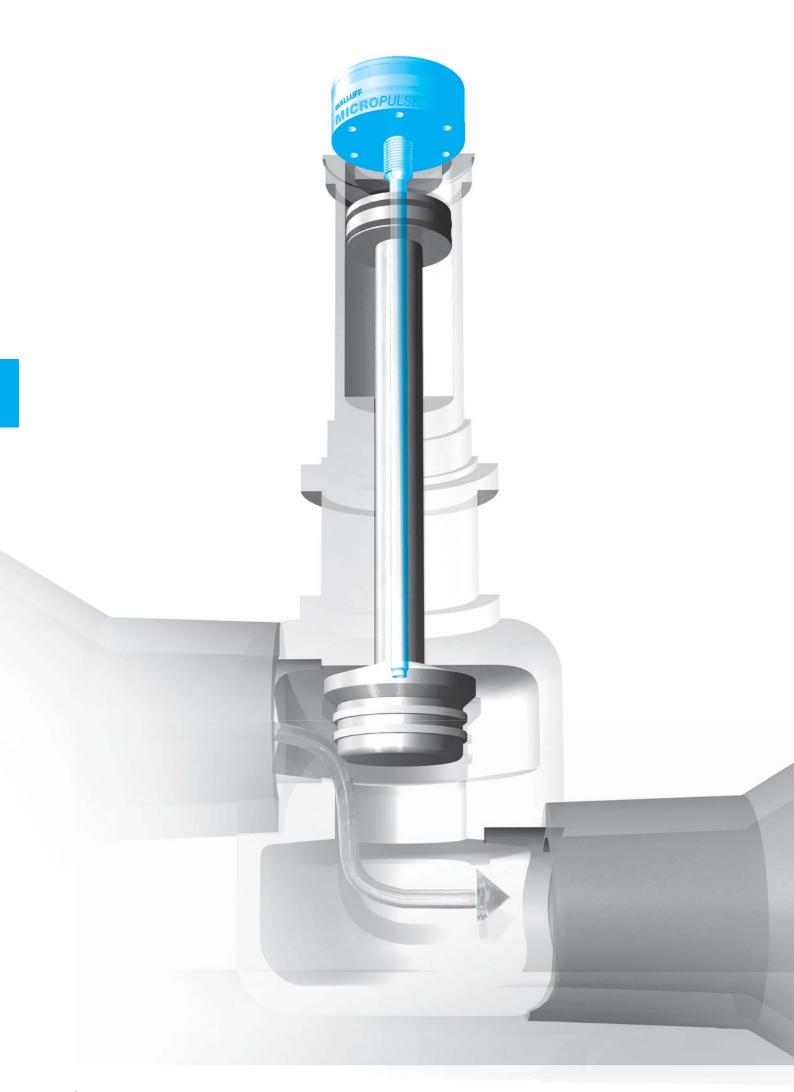


Insertion hole M18×1.5, as per ISO 6149, O-ring 15.4×2.1

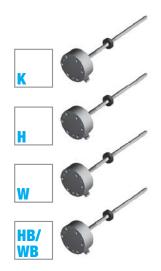


Insertion hole 3/4"-16UNF as per SAE J475, O-ring 15.3×2.4









0

AR

# MICROPULSE®

<b>K</b> Installation notes General data	102 103	
H Installation notes General data	104 105	
W Installation notes General data	106 107	
Pro Compact HB/WB Installation notes General data	108 109	
Analog interface	110	
Digital pulse interface	112	
SSI interface	114	
CANopen interface	116	
<b>AR</b> General data Analog interface Digital pulse interface P510	118 120 122	
Installation notes	124	

Rod housings are mainly used in hydraulic drive applications. When installed in the pressure section of the hydraulic cylinder, the distance sensor requires the same pressure rating as the actual hydraulic cylinder. In practice, the sensor must be able

to withstand pressures up to 1000 bar. The electronics are integrated in an aluminum or stainless steel housing and the waveguide in a pressure-resistant tube made from nonmagnetic stainless steel that is sealed off at the face end with a welded plug. An O-ring seal in the flange at the opposite end seals off the high-pressure section. An magnet ring with magnets slides over the tube or rod with internal waveguide to mark the position prior to detection.

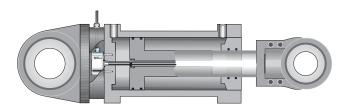


#### Pressure rated to 600 bar, high repeatability, non-contact, rugged

The BTL Micropulse transducer is a rugged position feedback system for measuring ranges between 25 and 5500 mm as well as use under extreme ambient conditions.

The actual waveguide is protected inside a high-pressure resistant stainless steel tube. The system is ideal for use in hydraulic cylinders for position feedback or as a level monitor with aggressive media in the food and chemical industries.

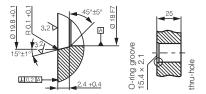
- Stainless
- extremely short 34 mm
- IP 68 with cable

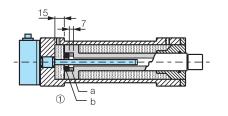


Compact rod Micropulse transducer installed in clevis mount cylinder

#### Installation BTL5 Compact rod K

The Micropulse transducer has 6 mounting holes for cylinder head screws (ISO 4762 M6×18 A2-70). We recommend that the mounting is made of non-magnetizable material. If magnetizable materials are used, the installation must be carried out as shown above. Sealing is at the flange mounting surface using the supplied O-ring 15.4×2.1 mm.





- 1.2 with magnetizable material
- ④ with non-magnetizable material
- a Spacer made from
- non-magnetizable material
- b Magnet

#### Included:

- Transducer (select your interface from page 110)
- Short user's guide
- Onon user s guide

Please order separately: Magnets/floats, page 96 Mounting nuts, page 97 Connectors, page 148/149

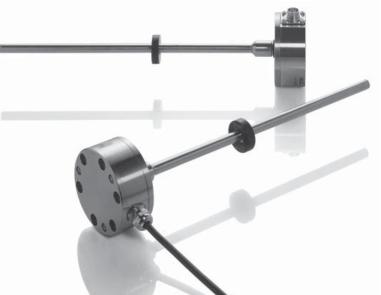
# .

**(4)** 

2

non-magnetizable material

Caution! Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com

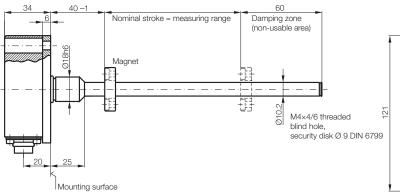


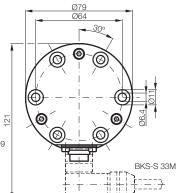


Series	BTL5 Compact Rod K
Part number	BTL5MK
Shock load	100 g/6 ms per IEC 60068-2-27 and 100 g/2 ms per IEC 60068-2-29
Vibration	12 g, 102000 Hz per IEC 60068-2-6
Polarity reversal protected	yes
Overvoltage protection	Transzorb protection diodes
Dielectric strength	500 V DC (GND to housing)
Degree of protection as per IEC 60529	IP 67 (when BKS-S32/33 is installed); IP 68 connector, 5 bar for cable version
Housing material	Stainless steel 1.4305
Flange and tube material	Tube stainless 1.4571, flange 1.4571 or 1.4429 or 1.4404
Housing attachment	flange with 6 mounting holes
Connection type	connector or integral cable
Recommended connector, see page 148/149	BKS-S 32M/BKS-S 32M-C/BKS-S 33M
EMC testing:	
RF emission	EN 55016-2-3 Group 1, Class A
Static electricity (ESD)	IEC 61000-4-2 Severity Level 3
Electromagnetic fields (RFI)	IEC 61000-4-3 Severity Level 3
Fast transients (BURST)	IEC 61000-4-4 Severity Level 3
Conducted interference induced	IEC 61000-4-6 Severity Level 3
by high-frequency fields	
Standard nominal strokes [mm]	0025, 0050, 0075, 0100, 0125, 0150, 0175, 0200, 0225, 0250, 0275, 0300, 0325, 0350,
	0375, 0400, 0425, 0450, 0475, 0500, 0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900,
	0950, 1000, 1100, 1200, 1300, 1400, 1500, 1600, 1700, 1800, 1900, 2000, 2250, 2500,
	2750, 3000, 3250, 3500, 3750, 3850, 4000, 4250, 4500, 4750, 5000, 5250, 5500 or in
	5 mm increments (depending on interface) on request

#### Housing K

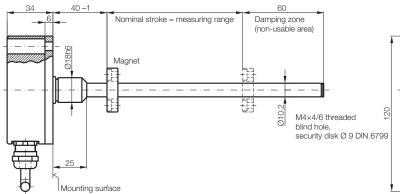
BTL5-...-M\_ \_ \_ \_-K-SR32 Flange  $\varnothing$  18 mm, PCD  $\varnothing$  64 mm **Radial connection** 





notes General data Analog Digital pulse SSI

Housing K BTL5-...-M\_ \_ \_ \_-K-K\_ \_ Flange  $\varnothing$  18 mm, PCD  $\varnothing$  64 mm **Radial cable** 



Ø79 0



General data Н Installation notes General data W Installation notes General data HB/WB Installation

interface interface interface CANopen interface

AR General data Analog interface Digital pulse interface Installation notes



#### Pressure rated to 600 bar, high repeatability, non-contact, rugged

The BTL Micropulse transducer is a robust position feedback system for measuring ranges between 25 and 5500 mm as well as use under extreme ambient conditions.

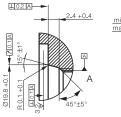
The actual waveguide is protected inside a high-pressure resistant stainless steel tube. The system is ideal for use in hydraulic cylinders for position feedback or as a level monitor with aggressive media in the food and chemical industries.

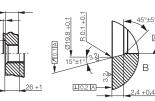
# Stainless IP 68 with cable

#### Installation BTL5 Compact rod H

The Micropulse transducer BTL has a mounting thread M18×1.5. We recommend that the mounting is made of non-magnetizable material.

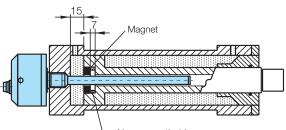
If magnetizable materials are used, the installation must be carried out as shown in the drawing below. Sealing is at the flange mounting surface using the supplied O-ring 15.4×2.1 with M18×1.5 thread.







O-ring groove, view B

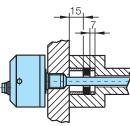


Insertion hole

M18×1.5 to

ISO 6149, O-ring 15.4×2.1

- Non-magnetizable spacer



Included:

- Transducer (select your interface from page 110)
- Short user's guide

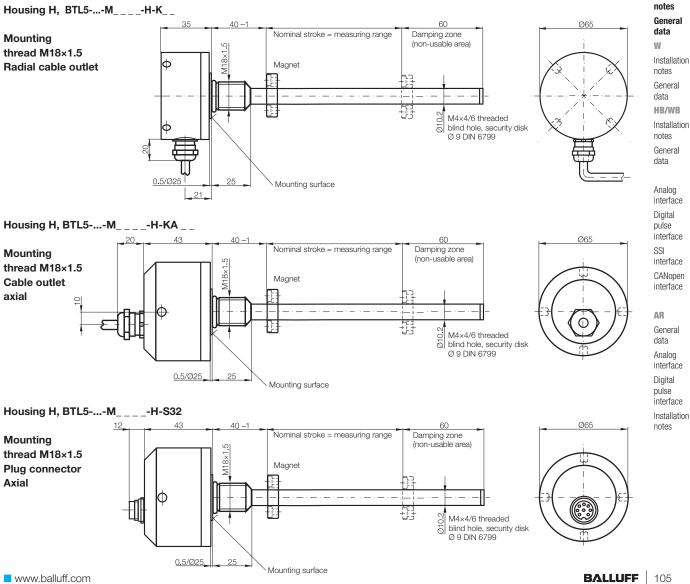
Please order separately: Magnets/floats, page 96 Mounting nuts, page 97 Connectors, page 148/149

Caution! Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com



**Compact Rod Series H** General data

Series	BTL5 Compact Rod H
Part number	BTL5MH
Shock load	100 g/6 ms per IEC 60068-2-27 and 100 g/2 ms per IEC 60068-2-29
Vibration	12 g, 102000 Hz per IEC 60068-2-6
Polarity reversal protected	yes
Overvoltage protection	Transzorb protection diodes
Dielectric strength	500 V DC (GND to housing)
Degree of protection as per IEC 60529	IP 67 (when BKS-S32/33 is installed); IP 68 connector, 5 bar for cable version
Housing material	Stainless steel 1.4305
Flange and tube material	Tube stainless 1.4571, flange 1.4571 or 1.4429 or 1.4404
Housing attachment	Flange with thread M18×1.5
Connection type	connector or integral cable
Recommended connector, see page 148/149	BKS-S 32M/BKS-S 32M-C/BKS-S 33M
EMC testing:	
RF emission	EN 55016-2-3 Group 1, Class A
Static electricity (ESD)	IEC 61000-4-2 Severity Level 3
Electromagnetic fields (RFI)	IEC 61000-4-3 Severity Level 3
Fast transients (BURST)	IEC 61000-4-4 Severity Level 3
Conducted interference induced	IEC 61000-4-6 Severity Level 3
by high-frequency fields	
Standard nominal strokes [mm]	0025, 0050, 0075, 0100, 0125, 0150, 0175, 0200, 0225, 0250, 0275, 0300, 0325, 0350,
	0375, 0400, 0425, 0450, 0475, 0500, 0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900,
	0950, 1000, 1100, 1200, 1300, 1400, 1500, 1600, 1700, 1800, 1900, 2000, 2250, 2500,
	2750, 3000, 3250, 3500, 3750, 3850, 4000, 4250, 4500, 4750, 5000, 5250, 5500 or
	in 5 mm increments on request.



Κ

Installation notes General data

Н Installation Installation

BALLUFF 105



#### Pressure rated to 600 bar, high repeatability, non-contact, rugged

The BTL Micropulse transducer is a robust position feedback system for measuring ranges between 25 and 5500 mm as well as use under extreme ambient conditions.

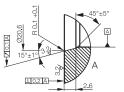
The actual waveguide is protected inside a high-pressure resistant stainless steel tube. The system is ideal for use in hydraulic cylinders for position feedback or as a level monitor with aggressive media in the food and chemical industries.

# Stainless IP 68 with cable

#### Installation BTL5 Compact rod W

The Micropulse transducer BTL has a mounting thread M18 $\times$ 1.5. We recommend that the mounting is made of non-magnetizable material.

If magnetizable materials are used, the installation must be carried out as shown in the drawing below. Sealing is at the flange mounting surface using the supplied O-ring  $15.4 \times 2.1$  with M18×1.5 thread.

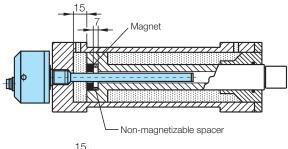


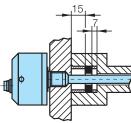
O-ring groove, view A



min. 25

Insertion hole thread 3/4"-16 UNF O-ring groove, view B





Included:

- Transducer (select your interface from page 110)
- Short user's guide

Please order separately: Magnets/floats, page 96 Mounting nuts, page 97 Connectors, page 148/149

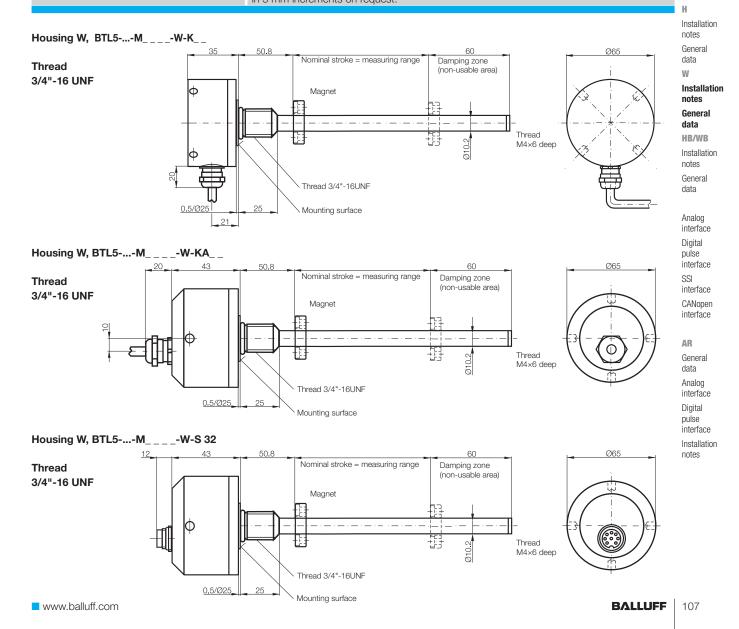
Caution! Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com



Compact W Rod Series General data

> K Installation notes General data

Series	BTL5 Compact W rod
Part number	BTL5MW
Shock load	100 g/6 ms per IEC 60068-2-27 and 100 g/2 ms per IEC 60068-2-29
Vibration	12 g, 102000 Hz per IEC 60068-2-6
Polarity reversal protected	yes
Overvoltage protection	Transzorb protection diodes
Dielectric strength	500 V DC (GND to housing)
Degree of protection as per IEC 60529	IP 67 (when BKS-S32/33 is installed); IP 68 connector, 5 bar for cable version
Housing material	Stainless steel 1.4305
Flange and tube material	Tube stainless 1.4571, flange 1.4571 or 1.4429 or 1.4404
Housing attachment	Flange with thread 3/4"-UNF
Connection type	connector or integral cable
Recommended connector, see page 148/149	BKS-S 32M/BKS-S 32M-C/BKS-S 33M
EMC testing:	
RF emission	EN 55016-2-3 Group 1, Class A
Static electricity (ESD)	IEC 61000-4-2 Severity Level 3
Electromagnetic fields (RFI)	IEC 61000-4-3 Severity Level 3
Fast transients (BURST)	IEC 61000-4-4 Severity Level 3
Conducted interference induced	IEC 61000-4-6 Severity Level 3
by high-frequency fields	
Standard nominal strokes [mm]	0025, 0050, 0075, 0100, 0125, 0150, 0175, 0200, 0225, 0250, 0275, 0300, 0325, 0350,
	0375, 0400, 0425, 0450, 0475, 0500, 0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900,
	0950, 1000, 1100, 1200, 1300, 1400, 1500, 1600, 1700, 1800, 1900, 2000, 2250, 2500,
	2750, 3000, 3250, 3500, 3750, 3850, 4000, 4250, 4500, 4750, 5000, 5250, 5500 or
	in 5 mm increments on request.



# Pro Compact HB/WB Rod Series

Installation notes

#### Pressure rated to 600 bar, high repeatability, non-contact, rugged

The BTL Micropulse transducer is a robust position feedback system for measuring ranges between 25 and 5500 mm as well as use under extreme ambient conditions.

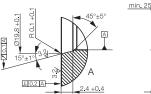
The actual waveguide is protected inside a high-pressure resistant stainless steel tube. The system is ideal for use in hydraulic cylinders for position feedback or as a level monitor with aggressive media in the food and chemical industries.

- Stainless
- IP 68 with cable
- IP 69/K
  - with cable protection system

#### Installation BTL5 Pro Compact HB/WB rod

The Micropulse transducer BTL has a mounting thread M18×1.5. We recommend that the mounting is made of non-magnetizable material.

If magnetizable materials are used, the installation must be carried out as shown in the drawing below. Sealing is at the flange mounting surface using the supplied O-ring 15.4×2.1 with M18×1.5 thread. The flange and housing are completely sealed and cannot be opened as a result. The measuring range preset in the factory cannot be modified as a result.

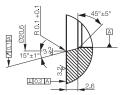




Insertion hole M18×1.5 as per ISO 6149, O-ring 15.4×2.1 O-ring groove, view A

O-ring groove, view B

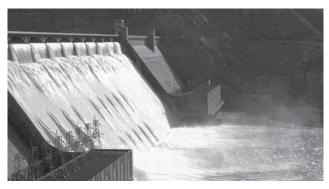


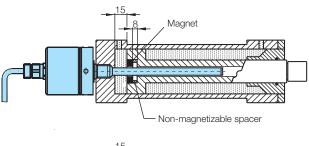


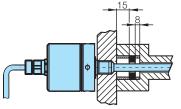


Insertion hole 3/4", O-ring 15.3×2.4 O-ring groove, view A

O-ring groove, view B







Included:

- Transducer (select your interface from page 110)
- Short user's guide

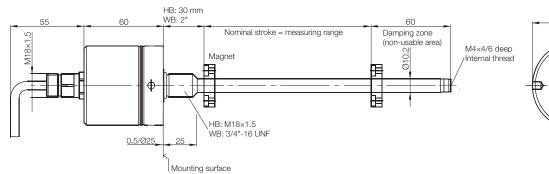
Please order separately: Magnets/floats, page 96 Mounting nuts, page 97 Caution! Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com

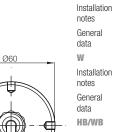
Pro Compact HB/WB Rod Series

General data

Series	BTL5 Compact HB/WB rod
Part number	BTL5MHB/WBC
Shock load	100 g/6 ms per IEC 60068-2-27 and 100 g/2 ms per IEC 60068-2-29
Vibration	12 g, 102000 Hz per IEC 60068-2-6
Polarity reversal protected	yes
Overvoltage protection	Transzorb protection diodes
Dielectric strength	500 V DC (GND to housing)
Degree of protection as per IEC 60529	IP 68 (5 bar with cable); IP 69K (with cable protection system)
Housing material	Stainless steel 1.4404
Flange and tube material	Stainless steel tube 1.4571, flange 1.4404
Housing attachment	Flange with thread
Connection type	Cable connection
EMC testing:	
RF emission	EN 55016-2-3 Group 1, Class A+B
Static electricity (ESD)	IEC 61000-4-2 Severity Level 3
Electromagnetic fields (RFI)	IEC 61000-4-3 Severity Level 3
Fast transients (BURST)	IEC 61000-4-4 Severity Level 3
Conducted interference induced	IEC 61000-4-6 Severity Level 3
by high-frequency fields	
Standard nominal strokes [mm]	0025, 0050, 0075, 0100, 0125, 0150, 0175, 0200, 0225, 0250, 0275, 0300, 0325, 0350,
	0375, 0400, 0425, 0450, 0475, 0500, 0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900,
	0950, 1000, 1100, 1200, 1300, 1400, 1500, 1600, 1700, 1800, 1900, 2000, 2250, 2500,
	2750, 3000, 3250, 3500, 3750, 3850, 4000, 4250, 4500, 4750, 5000, 5250, 5500 or
	in 5 mm increments on request.







Installation notes General data

Analog

╔┢╧╸

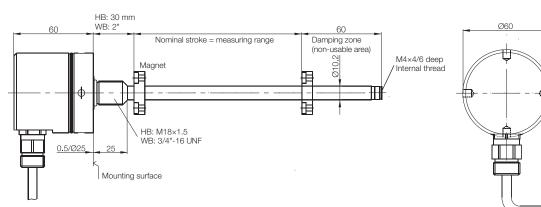
K Installation notes General data H

interface Digital pulse interface SSI interface CANopen interface

AR General data Analog interface Digital pulse interface Installation notes



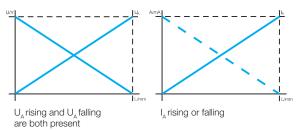
radial



Compact Rod Series Analog interface

An integrator circuit provides resolution of better than 0.1 mV. BTL transducers with analog outputs are available for 0...10 V, 4...20 mA, 0...20 mA and -10...10 V as rising or falling signals.

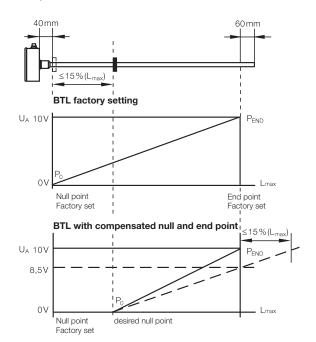
#### Outputs



#### Compensating the output signal

BTL transducers with analog output have two potentiometers for adapting the null and end point of the output signal to the particular application. The null point can be shifted by max. 15 % of the nominal stroke in the direction of the rod end.

The output signal cannot be adjusted on the Compact H, W and Pro Compact HB/WB versions.



Series				
Output signal				
Transducer interface				
Input interface				
Part number				
Output voltage				
Output current				
Load current				
max. ripple				
Load resistance				
System resolution				
Hysteresis				
Repeat accuracy				
Sampling rate				
Max. non-linearity				
Temperature coefficient	Voltage output			
	Current output			
Operating voltage				
Current consumption				
Polarity reversal protected				
Overvoltage protection				
Dielectric strength				
Operating temperature				
Storage temperature range				
Pin assignments	Pin	Color		
Output signals	1	YE		
	2	GY		
	3	PK		
	5	GN		
Operating voltage	6	BU		
	7	BN		
	8	WH		



Location of trim pots with cover removed

Please enter the code for the output signal, nominal stroke, housing and connection type in the ordering code!

- Included:
- Transducer
- Short user's guide

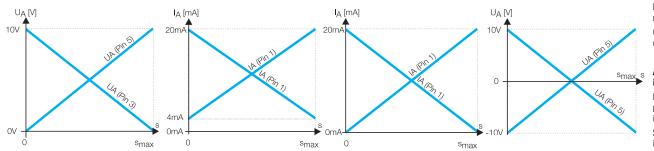
Please order separately: Magnets/floats, page 96 Mounting nuts, page 97 Connectors, page 148/149

#### Ordering example:

BTL5-E1\_-M\_ -C Output Standard nominal stroke [mm] signal Housing Connection type 0025, 0050, 0075, 0100, 0125, HB Radial output Rising and 1 falling (with 0150, 0175, 0200, 0225, 0250, WB F05 Teflon cable 5 m A and G) 0275, 0300, 0325, 0350, 0375, Rising 0400, 0425, 0450, 0475, 0500, 0 Axial output Falling (with 0550, 0600, 0650, 0700, 0750, FA05 Teflon cable 5 m 7 C and E) 0800, 0850, 0900, 0950, 1000, 1100, 1200, 1300, 1400, 1500, 1600, 1700, 1800, 1900, 2000, 2250, 2500, 2750, 3000, 3250, 3500, 3750, 3850, 4000, 4250, 4500, 5000, 5250, 5500 or in 5 mm increments on request.



BTL5 Compact Rod	BTL5 Compact Rod		BTL5 Compac	t Rod	BTL5 Compact Rod	
analog	analog		analog		analog	
A	E		С		G	
analog	analog		analog		analog	
BTL5- <b>A11</b> -M	BTL5-E1M		BTL5-C1M		BTL5-G11-M	
010 V and 100 V					-1010 V and 1010 V	
	420 mA or 20	4 mA	020 mA or 20	0 mA		
max. 5 mA					max. 5 mA	
≤ 5 mV					≤ 5 mV	
	≤ 500 ohms		≤ 500 ohms			
≤ 0.1 mV	≤ 0.2 µA		≤ 0.2 µA		≤ 0.1 mV	
≤ 4 µm	≤ 4 µm		≤ 4 µm		≤ 4 µm	
System resolution/min. 2 µm	System resolution	on/min. 2 µm	System resolution	on/min. 2 µm	System resolution/min. 2 µm	
$f_{STANDABD} = 1 \text{ kHz}$	f <sub>standard</sub> = 1 kHz	-	$f_{\text{STANDARD}} = 1 \text{ kHz}$		f <sub>standard</sub> = 1 kHz	
±100 µm up to 500 mm nominal stroke		) mm nominal stroke	±100 µm up to 500 mm nominal stroke		±100 µm up to 500 mm nominal stroke	
±0.02 % 500 max. nominal stroke	±0.02 % 500 max. nominal stroke		±0.02 % 500 max. nominal stroke		±0.02 % 500 max. nominal stroke	
$[150 \ \mu\text{V/}^{\circ}\text{C} + (5 \ \text{ppm/}^{\circ}\text{C} \times \text{P} \times \text{U/L})] \times \Delta\text{T}$					$[150 \mu\text{V/}^{\circ}\text{C} + (5 \text{ppm/}^{\circ}\text{C} \times \text{P} \times \text{U/L})] \times \Delta\text{T}$	
	[0.6 µA/°C + (10 ppr	m/°C × P × I/L)] × $\Delta$ T	[0.6 µA/°C + (10 ppi	m/°C × P × I/L)] × $\Delta$ T		
2028 V DC	2028 V DC		2028 V DC		2028 V DC	
≤ 150 mA	≤ 150 mA		≤ 150 mA		≤ 150 mA	
yes	yes		yes		yes	
Transzorb protection diodes	Transzorb prote	ction diodes	Transzorb protection diodes		Transzorb protection diodes	
500 V DC (ground to housing)	500 V DC (grou	nd to housing)	500 V DC (ground to housing)		500 V DC (ground to housing)	
−40+85 °C	-40+85 °C		−40+85 °C		−40+85 °C	
-40+100 °C	–40+100 °C		-40+100 °C		-40+100 °C	
BTL5- <b>A</b> 11	BTL5- <b>E</b> 10	BTL5- <b>E</b> 17	BTL5- <b>C</b> 10	BTL5- <b>C</b> 17	BTL5- <b>G</b> 11	
	420 mA	204 mA	020 mA	200 mA		
0 V Output	0 V Output	0 V Output	0 V Output	0 V Output	0 V Output	
100 V	100 V	100 V	100 V	100 V	10–10 V	
010 V	010 V	010 V	010 V	010 V	-1010 V	
GND	GND	GND	GND	GND	GND	
+24 V DC	+24 V DC	+24 V DC	+24 V DC	+24 V DC	+24 V DC	
(GND)	(GND)	(GND)	(GND)	(GND)	(GND)	



#### Ordering example:

# BTL5-E1\_-M\_\_\_\_-\_-\_-

Ou	Itput	Standard						General data
signal		nominal stroke [mm] Housing		Connection type				Analog interface
1 Rising and 0025, 0050, 0075, 0100, 0125,		К	Radial c	output			Digital	
	falling (with	0150, 0175, 0200, 0225, 0250,		K02	PUR cable 2 m			pulse interface
	A and G)	0275, 0300, 0325, 0350, 0375,		K05	PUR cable 5 m			Installation
)	Rising	0400, 0425, 0450, 0475, 0500,		K10	PUR cable 10 m			notes
7	Falling (with	0550, 0600, 0650, 0700, 0750,		K15	PUR cable 15 m			
	C and E)	0800, 0850, 0900, 0950, 1000,		SR32	Connector			
		1100, 1200, 1300, 1400, 1500,						
		1600, 1700, 1800, 1900, 2000,	Н	Radial c	output	Axial ou	tput	
		2250, 2500, 2750, 3000, 3250,	W	K02	PUR cable 2 m	KA02	PUR cable 2	m
		3500, 3750, 3850, 4000, 4250,		K05	PUR cable 5 m	KA05	PUR cable 5	m
		4500 or in 5 mm increments on		K10	PUR cable 10 m	KA10	PUR cable 1	0 m
		request.		K15	PUR cable 15 m	KA15	PUR cable 1	5 m
						S32	Connector	

AR

K Installation

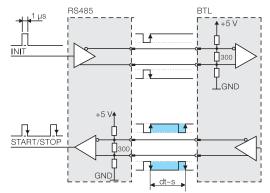


#### P Interface

Compatible with BTA processors as well as controllers and modules from various manufacturers including Siemens, B & R, Phoenix Contact, Mitsubishi, Sigmatek, Parker, Esitron and WAGO. Reliable signal transmission, even over cable lengths up to 500 m between BTA and BTL, is assured by the noise-immune RS485 differential line drivers and receivers. Noise signals are effectively suppressed.

#### M interface

The I and M interfaces are control-specific interface variations.



Block diagram of P interface

#### Highly precise digitizing of the P pulse signal

Companies developing their own control and processing electronics can create a highly accurate P interface cost effectively and with minimum effort using the Balluff digitizing chip. The digitizing chip was developed as a high-resolution, configurable ASIC for Micropulse transducers with P interface.

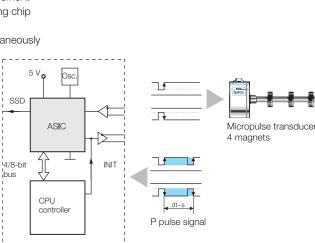
#### Benefits

- Position resolution 1 µm!
- The 1  $\mu m$  resolution of the Micropulse distance measurement system is achieved by the high resolution of the digitizing chip (133 pS) (Clock frequency 2 or 20 MHz).
- Position data from 4 magnets can be processed simultaneously

or in 5 mm increments on request.

- 4/8-bit processor interface







#### Ordering example:

BTL	.5-P1-	M		-

Standard			
nominal stroke [mm]	Housing	Conn	ection type
0025, 0050, 0075, 0100, 0125, 0150,	HB	Radial o	output
0175, 0200, 0225, 0250, 0275, 0300,	WB	F05	Teflon cable 5 r
0325, 0350, 0375, 0400, 0425, 0450,			
0475, 0500, 0550, 0600, 0650, 0700,		Axial ou	itput
0750, 0800, 0850, 0900, 0950, 1000,		FA05	Teflon cable 5 r
1100, 1200, 1300, 1400, 1500, 1600,			
1700, 1800, 1900, 2000, 2250, 2500,			
2750, 3000, 3250, 3500, 3750, 3850,			
4000, 4250, 4500, 5000, 5250, 5500			

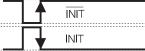
Controller or processing electronics

> ASIC INFO: +49 7158 173-370

**Compact Rod Series** Digital pulse interface

Series				BTL5 Compact rod				
Transducer interface				Pulse P				
Input interface				Pulse P				
Part number				BTL5- <b>P</b> 1-M				
System resolution				processing-dependent				
Repeat accuracy				2 µm or ±1 digit depending on processing electronics				
Resolution				≤2 µm				
Hysteresis				≤ 4 μm				
Sampling rate				$f_{\text{STANDARD}} = 1 \text{ kHz} = \le 1400 \text{ mm}$				
max. non-linearity				$\pm 100 \mu\text{m}$ up to 500 mm nominal stroke				
				±0,02 % 5005500 mm nominal stroke				
Temperature coefficie	ent of ove	rall sys	tem	(6 μm + 5 ppm × L)/°C				
Operating voltage				2028 V DC				
Current consumption	٦			≤ 100 mA				
Operating temperatu	ire			-40+85 °C				
Storage temperature	e range			-40+100 °C				
Pin assignments		Pin	Color	BTL5- <b>P</b> 1-M				
Input/Output	Input	1	ΥE	INIT				
signals	Output	2	GY	START/STOP				
	Input	3	PK	INIT				
	Output	5	GN	START/STOP				
Operating voltage		6	BU	GND				
		7	BN	+24 V DC				
		8	WH					

Connect shield to housing

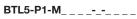


Please enter the code for the nominal stroke, housing and connection type in the ordering code.

- Included:
- Transducer
- Short user's guide

Please order separately: Magnets/floats, page 96 Mounting nuts, page 97 (for Compact rod H) Connectors, page 148/149

#### Ordering example:



Standard			
nominal stroke [mm]	Housing	Conne	ection type
0025, 0050, 0075, 0100, 0125, 0150,	K	Radial c	output
0175, 0200, 0225, 0250, 0275, 0300,		K02	PUR cable 2 m
0325, 0350, 0375, 0400, 0425, 0450,		K05	PUR cable 5 m
0475, 0500, 0550, 0600, 0650, 0700,		K10	PUR cable 10 m
0750, 0800, 0850, 0900, 0950, 1000,		K15	PUR cable 15 m
1100, 1200, 1300, 1400, 1500, 1600,		SR32	Connector
1700, 1800, 1900, 2000, 2250, 2500,			
2750, 3000, 3250, 3500, 3750, 3850,	Н	Radial c	output
4000, 4250, 4500, 5000, 5250, 5500	W	K02	PUR cable 2 m
or in 5 mm increments on request.		K05	PUR cable 5 m
		K10	PUR cable 10 m
		K15	PUR cable 15 m



dt~s START/STOP

#### Axial output

KA02PUR cable 2 mKA05PUR cable 5 mKA10PUR cable 10 mKA15PUR cable 15 mS32Connector

Κ Installation notes General data н Installation notes General data W Installation notes General data HB/WB Installation notes General data

Analog interface Digital pulse

interface

SSI interface CANopen interface

AR General data Analog interface Digital pulse interface

Installation

notes



#### Standard SSI interface

is consistent clock signal timing.

ing table:

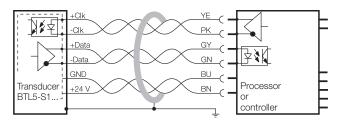
Controllers from Siemens, Bosch-Rexroth, WAGO, B & R, Parker, Esitron, PEP etc. as well as Balluff BDD-AM 10-1-SSD and BDD-CC 08-1-SSD display/controllers are used for synchronous serial data transmission.

Reliable signal transmission, even with cable lengths of up to 400 m between controller and BTL transducer is assured by noise-immune RS485/422 differential line drivers and receivers. Any noise signals are effectively suppressed.

Synchronized SSI interface BTL5-S1\_B-M\_\_\_\_P-\_\_\_ Micropulse transducers with synchronized SSI interface are suit-

able for dynamic control applications. The data acquisition in the transducer is synchronized with the external clock of the controller, permitting an optimum calculation of the velocity in the controller. The prerequisite for this synchronous mode of transducer operation

The **maximum sampling frequency**  $f_{a}$ , at which a new current value is generated for each sample, can be derived from the follow-



BTL5-S1... with processor/controller, wiring example

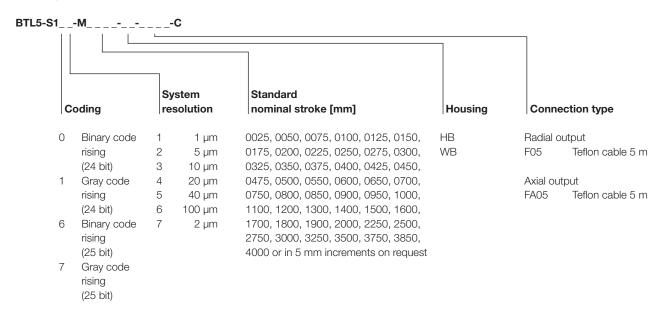


mm			mm		Hz
	< Nominal stroke	$\leq$	120	:	2500
120	< Nominal stroke	$\leq$	475	:	2000
475	< Nominal stroke	$\leq$	750	:	1500
750	< Nominal stroke	$\leq$	1250	:	1000
1250	< Nominal stroke	$\leq$	2600	:	500
2600	< Nominal stroke	$\leq$	4000	:	333

Clock frequency depends on the cable length

Cable length	Clock frequency
< 25 m	< 1000 kHz
< 50 m	< 500 kHz
< 100 m	< 400 kHz
< 200 m	< 200 kHz
< 400 m	< 100 kHz

#### Ordering example:



# short and synchronized

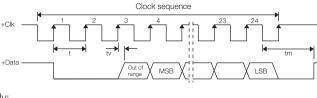
Cariaa			DTI C and			
Series			BTL5 rod			
Output signal			synchronous serial			
Transducer interface			S			
Input interface			synchronous serial			
Part number			BTL5- <b>S</b> 1M			
Part number synchro	nization		BTL5- <b>\$</b> 1B-M			
System resolution dep	pending on	version (LSB)	1, 2, 5, 10, 20, 40 or 100 μm			
Repeat accuracy			±1 digit			
Hysteresis			≤ 1 digit			
Sampling rate			$f_{\text{STANDARD}} = 2 \text{ kHz}$			
max. non-linearity			$\pm$ 30 µm at 5 and 10 µm resolution or $\leq$ $\pm$ 2 LSB			
Temperature coefficie	ent of over	all system	$(6 \mu m + +5 ppm \times L)/°C$			
Operating voltage			2028 V DC			
Current consumption	1		≤80 mA			
Operating temperatu	re		-40+85 °C			
Storage temperature	range		-40+100 °C			
Pin assignments	Pin	Color				
Control and data	1	YE	+Clk			
signals	2	GY	+Data			
	3	PK	-Clk			
	5	GN	-Data			
Operating	6	BU	GND			
voltage (external)	7	BN	+24 V DC			
	8	WH	must remain unconnected			

Please enter the code for the coding, system resolution, nominal stroke, design and connection type in the ordering code!

Included:

- Transducer
- Short user's guide

Please order separately: Magnets/floats, page 96 Mounting nuts, page 97 Connectors, page 148/149



**Compact Rod Series** 

SSI interface

Ordering example:

BTL5-S1_	<b>M</b>	 L					
	Coding	-	ystem solution	Standard nominal stroke [mm]	Housing	Conne	ection type
0	Binary code	1	1 µm	0025, 0050, 0075, 0100, 0125, 0150,	K	Output	radial
	rising	2	5 µm	0175, 0200, 0225, 0250, 0275, 0300,		K02	PUR cable 2 m
	(24 bit)	3	10 µm	0325, 0350, 0375, 0400, 0425, 0450,		K05	PUR cable 5 m
1	Gray code	4	20 µm	0475, 0500, 0550, 0600, 0650, 0700,		K10	PUR cable 10 m
	rising	5	40 µm	0750, 0800, 0850, 0900, 0950, 1000,		K15	PUR cable 15 m
	(24 bit)	6	100 µm	1100, 1200, 1300, 1400, 1500, 1600,		SR32	connector
6	Binary code	7	2 µm	1700, 1800, 1900, 2000, 2250, 2500,			
	rising			2750, 3000, 3250, 3500, 3750, 3850,	Н	Output	radial
	(25 bit)			4000 or in 5 mm increments on request	W	K02	PUR cable 2 m
7	Gray code					K05	PUR cable 5 m
	rising					K10	PUR cable 10 m
	(25 bit)					K15	PUR cable 15 m
						Output	axial
						KA02	PUR cable 2 m
						KA05	PUR cable 5 m
						KA10	PUR cable 10 m
				ation to clock (dynamic control applications)		KA15	PUR cable 15 m
insert the le	tter B! BTL5-S1_	<b>B</b> -N	1			S32	connector

K Installation notes

> General data H

Installation notes

Installation notes

General

data

W

General data HB/WB Installation notes General data Analog interface Digital pulse interface SSI interface

CANopen interface

AR General data Analog interface Digital pulse interface Installation

notes



## User-friendly hardware and software set-up

#### **CANopen interface**

Based on CAN (ISO/IEC 7498 and DIN ISO 11898), CANopen provides a Layer-7 implementation for industrial CAN networks.

The serial data protocol of the CAN specification is defined according to the producer-consumer principle as opposed to most other fieldbus protocols. This eliminates target addressing of the process data. Each bus station decides for itself how the received data are processed.

The CANopen interface of the Micropulse transducer is compatible with CANopen conforming with CiA Standard DS301 Rev. 3.0 as well as with CAL and Layer 2 CAN networks.

#### CAN-BUS features

- Line topology, star structure also possible via repeaters
- Low-cost wiring with two-wire cable
- Fast response times, high data integrity using CRC, hamming distance of 6
- 1 MBit/s with cable lengths < 25 m
- Protocol limits number of stations to 127
- Using multiple magnets: A minimum spacing of > 65 mm must be maintained.

CANopen offers a high level of flexibility with respect to functionality and data exchange. Using a standard data sheet in the form of an EDS file it is easy to link the Micropulse transducers to any CANopen system.

#### Process Data Object (PDO)

12 Micropulse transducers send their position information optionally in one, two or four PDOs with 8 bytes of data each. The contents of the PDOs are freely configurable. The following information can be sent:

- Current magnet position with resolution in 5 µm increments
- Current velocity of the magnet with resolution selectable in 0.1mm/s increments
- Current status of the four freely programmable cams per magnet.

#### Synchronization Object (SYNC)

Serves as a net-wide trigger for synchronizing all network participants. When the SYNC object is received, all Micropulse transducers connected to the bus store their current position and velocity information and then send it sequentially to the controller. This assures time-synchronous acquisition of the measured values.

#### LED

Display of the CANopen status to DS303-3

#### FMM

The sensor can be operated as a 4-magnet type, whereby the sensor itself recognizes how many magnets are currently active. So if only two magnets are positioned in the measuring range, a valid value is output for the first two positions and a defined error value for positions 3 and 4.

#### **Emergency Object**

This object is sent with the highest priority and is used for example for error messages when the cam states change.

#### Service Data Object (SDO)

Service Data Objects transmit the parameters for the transducer configuration. The transducer may be configured on the bus by the controller or offline using a PC with a configuration tool which runs under Windows. The configuration is stored in the non-volatile memory of the transducer.



CiA 199911-301v30/11-009

#### Use of multiple magnets

A minimum spacing of > 65 mm must be maintained.

#### Ordering example:

BTL5-H1	MC						
	oftware	В	aud rate	Standard nominal stroke [mm]	Housing	Conne	ection type
1	1 × position and	0	1 MBaud	0025, 0050, 0075, 0100,	HB	Radial c	output
	1 × velocity	1	800 kBaud	0125, 0150, 0175, 0200,	WB	K05	PUR cable 5 m
2	2 × position and	2	500 kBaud	0225, 0250, 0275, 0300,			
	2 × velocity	3	250 kBaud	0325, 0350, 0375, 0400,		Axial ou	tput
3	4 × position	4	125 kBaud	0425, 0450, 0475, 0500,		KA05	PUR cable 5 m
		5	100 kBaud	0550, 0600, 0650, 0700,			
		6	50 kBaud	0750, 0800, 0850, 0900,			
		7	20 kBaud	0950, 1000, 1100, 1200,			
		8	10 kBaud	1300, 1400, 1500, 1600,			
				1700, 1800, 1900, 2000,			
				2250, 2500, 2750, 3000,			
				3250, 3500, 3750, 3850,			
				4000 or in 5 mm			
				increments on request.			

# Position + Velocity

Compact Rod Series CANopen<sup>®</sup> interface

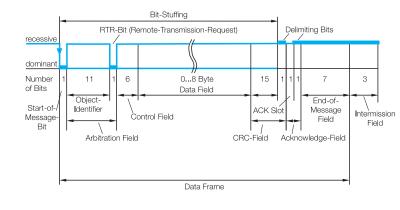
Series			BTL5 ro	hd							
Output signal				CANopen							
Transducer interface			H	•							
Input interface				CANopen							
Part number				BTL5- <b>H</b> 1M							
CANopen Version			potentia	I-free							
Repeat accuracy			±1 digit								
System resolution	Positic	on	5 µm inc	crements							
configurable	Velocit	ty	0.1 mm/	/s increm	ents						
Hysteresis			≤ 1 digit								
Sampling rate			f <sub>STANDARD</sub>	f <sub>standard</sub> = 1 kHz							
max. non-linearity			±30 µm at 5 µm resolution								
Temperature coefficie	ent of ove	erall system	$(6 \ \mu m + 5 \ ppm \times L)/^{\circ}C$								
Operating voltage			2028 V DC								
Current consumption			≤ 100 m	A							
Operating temperature	re		-40+8	-40+85 °C							
Storage temperature	range		-40+1	0° 00							
Cable length [m] per	CiA DS3	01	< 25	< 50	< 100	< 250	< 500	< 1000	< 1250	< 2500	
Baud rate [kBaud] pe	er CiA DS	301	1000	800	500	250	125	100	50	20/10	
Pin assignments	Pin	Color									
Control and	1	WH	CAN_G	ND							
data signals	2	BN	+24 V								
	3	BU	0 V (GNI	D)							
	4	GY	CAN_HI	GH							
	5	GN	CAN_LC	W							

Please enter the code for the software configuration, baud rate, nominal stroke and housing in the ordering code. Cable on request.

#### Included:

- Transducer
- Short user's guide

Please order separately: Magnets/floats, page 96 Mounting nuts, page 97 Connectors, page 148/149



Using the CANopen interface and cable lengths up to 2500 m, the signal is sent at a length-dependent baud rate to the controller. The high noise immunity of the connection is achieved using differential drivers and by the data monitoring scheme.

κ Installation notes General data Н Installation notes General data W Installation notes General data HB/WB Installation notes General data

Analog interface Digital pulse interface SSI interface CANopen interface

BTL5-H1	-M					_		CANopen interface
								AR
s	oftware			Standard				General data
c	onfiguration	В	aud rate	nominal stroke [mm]	Housing	Conne	ection type	Analog interface
1	1 × position and	0	1 MBaud	0025, 0050, 0075, 0100, 0125,	К	Radial o	output	Digital
	1 × velocity	1	800 kBaud	0150, 0175, 0200, 0225, 0250,		K02	PUR cable 2 m	pulse interface
2	2 × position and	2	500 kBaud	0275, 0300, 0325, 0350, 0375,		K05	PUR cable 5 m	Installation
	$2 \times \text{velocity}$	3	250 kBaud	0400, 0425, 0450, 0475, 0500,		SR92	Connector	notes
3	4 × position	4	125 kBaud	0550, 0600, 0650, 0700, 0750,				
		5	100 kBaud	0800, 0850, 0900, 0950, 1000,	Н	Radial o	output	
		6	50 kBaud	1100, 1200, 1300, 1400, 1500,	W	K02	PUR cable 2 m	
		7	20 kBaud	1600, 1700, 1800, 1900, 2000,		K05	PUR cable 5 m	
		8	10 kBaud	2250, 2500, 2750, 3000, 3250,				
				3500, 3750, 3850, 4000 or in		Axial ou	itput	
				5 mm increments on request.		KA02	PUR cable 2 m	
						KA05	PUR cable 5 m	

Ordering example:

Connector

S92



## Integrated in cylinders for controlled work processes

# Position detection in mobile hydraulics

Sensors are being used increasingly to extend the useful life and improve safety in mobile equipment. The new Micropulse AR transducer from Balluff senses the piston position in mobile hydraulic cylinders.

The sensor operates according to the proven magnetostrictive principle. The compact size of the transducer makes it ideal for use in pivot bearing and spherical eye end cylinders or large bore cylinders. The processing electronics integrated in the transducer have been designed to meet the strict EMC Directives for industrial lift trucks, agricultural and forestry equipment and earthmoving machinery.

# Compatibility testing according to EMC Directives

CE

e1

ISO 14982 Agricultural and Forestry Machinery ISO 13766 Earthmoving Machinery ISO 7637-1/2/3 Road Vehicles EN 12895 Industrial Trucks EN 50121-3-2 Railway Applications ISO 11452-5 Electromagnetic HF field, 200 V/m

#### e1 type approval

The e1 type approval is granted by the German Federal Motor Transport Authority KBA and confirms that special motor vehicle standards have been maintained. The devices may be mounted on vehicles which travel on public roads. The standards describe EMC conditions under which the devices must operate without failure. e1 approved Micropulse transducers are indicated by the designation "-SA265-" in the part number.

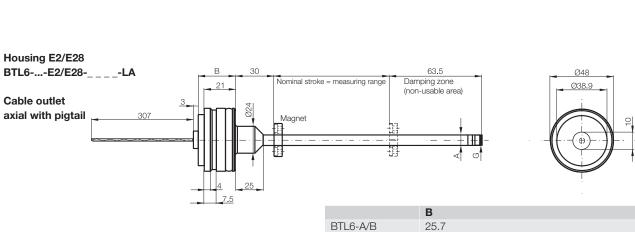
Caution! Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com

Series	BTL6 rod AR
Shock load	100 g/6 ms per IEC 60068-2-27
Continuous shock	50 g/2 ms
Vibration	12 g, 102000 Hz per IEC 60068-2-6
Polarity reversal protected	yes
Dielectric strength	500 V DC (GND to housing)
Degree of protection as per IEC 60529	IP 67
Housing material	Stainless steel outer tube 1.4571, stainless steel flange 1.4404
Pressure rating with 10.2 mm outer tube E2	350 bar installed in hydraulic cylinder
Pressure rating with 8 mm outer tube E28	250 bar installed in hydraulic cylinder
Connection type	Cable connection or pigtail
EMC tests:	
RF emission	EN 55016-2-3 Group 1, Class A/B
Static electricity (ESD)	IEC 61000-4-2 Severity Level 3
Electromagnetic fields (RFI)	IEC 61000-4-3 Severity Level 3
Fast transients (BURST)	IEC 61000-4-4 Severity Level 3
Surge voltage	IEC 61000-4-5 Severity Level 2
Line-induced disturbances	IEC 61000-4-6 Severity Level 3
Magnetic fields	IEC 61000-4-8 Severity Level 4
Standard nominal strokes [mm]	0025, 0050, 0075, 0100, 0125, 0150, 0175, 0200, 0225, 0250,
with 8 mm outer tube	0275, 0300, 0325, 0350, 0375, 0400, 0425, 0450, 0475, 0500,
(style E28) is the max. nominal	0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900, 0950, 1000,
stroke 1016 mm	1100, 1200, 1300, 1400, 1500, 1524 or 1 mm increments on
	request





Housing E2/E28 \_\_\_\_**-KA** BTL6-...-E2/E28-63.5 В Ø48 Damping zone (non-usable area) Nominal stroke = measuring range 21 Ø38.9 Cable outlet 024 axial centric Magnet ÷ 7.5 В С 25.2 13 BTL6-A/B BTL6-E 29.75 13



BTL6-E

BTL6-P

E2

E28

BTL6-P

E2

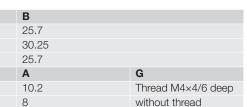
E28

25.2

10.2

Α

8



16 G

Thread M4×4/6 deep

without thread

SSI Housing E2/E28 interface BTL6-...-E2/E28-\_\_\_-KE В 63.5 Ø48 30 CANopen Damping zone Nominal stroke = measuring range Ø38.9 21 (non-usable area) interface Cable outlet axial eccentric Magnet AR General data 벖 Analog interface Digital pulse \_7.5 interface В С Installation BTL6-A/B 25.2 13 notes BTL6-E 29.75 13 BTL6-P 25.2 16 G Α E2

E28

10.2

8

Thread M4×4/6 deep

without thread

9

K Installation

notes

data

notes General

data W Installation notes

General

HB/WB

notes

data

General

Analog interface Digital pulse interface

Installation

data

н

General

Installation

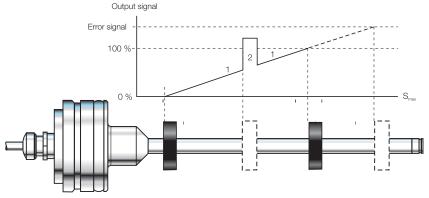


The propagation time of an ultrasonic wave induced by magnetostriction is used to determine the position of the magnet. The position is output as an analog value which rises. This is done with high precision and repeatability within the measuring range designated as the nominal stroke length. If there is no magnet within the measuring range, an error signal is output. There is a damping zone at the rod end. When an magnet is in this zone the output is spurious. The electrical connection between the transducer, the controller and the power supply is established using a cable or pigtail. Series Output signal Transducer interface Input interface Part number Output voltage Output current Load current max. ripple Load resistance System resolution Hysteresis Repeat accuracy Sampling rate max. non-linearity Temperature voltage output coefficient Current output Operating voltage Current consumption Polarity reversal protected Overvoltage protection Dielectric strength Operating temperature Storage temperature range Pin assignments Color GY Output signals GN Operating voltage ΒU ΒN

Connect shield to housing

#### Magnet position

- 1 Within the measuring range
- 2 Magnet not present



Output signal rising

Please enter the code for the output signal, nominal stroke, housing and connection type in the ordering code!

Included:

- Transducer
- Short user's guide

Please order separately: Magnets/floats, page 96



BTL6 rod AR	F	BTL6 rod AR		BTL6 rod AR	
analog		analog		analog	
A		<b>3</b>		E	
analog		analog		analog	
BTL6- <b>A</b> 500-M -		BTL6- <b>B</b> 500-M		BTL6- <b>E</b> 500-M	
010 V		)5 V			
010 V	l	) V		4 20 mA	
		0.00		420 mA	
max. 2 mA		max. 2 mA			
≤5 mV	-	≤2 mV			
				≤ 500 ohms	
± 1.5 mV	+	± 1.5 mV		±7 μΑ	
≤ 5 µm	5	≤ 4 µm			
System resolution/mir	n. 2 μm 🗧	System resolution/min. 2 µm		System resolution/min. 2 µm	
f <sub>standard</sub> = 1 kHz	f	standard = 1 kHz		f <sub>standard</sub> = 1 kHz	
±200 µm up to 500 m typ. ±0.02 % ≥ 500 nc	m nominal stroke ±	$\pm$ 200 μm up to 500 mm nomin yp. ±0.02 % ≥ 500 nominal st		$\pm$ 200 μm up to 500 mm nominal stroke typ. ±0.02 % ≥ 500 nominal stroke	
[150 µV/°C + (5 ppm/	°C × P × U/U) × AT [	150 μV/°C + (5 ppm/°C × P ×	/  )] × AT	$[150 \mu\text{V/°C} + (5 \text{ppm/°C} \times \text{P} \times \text{U/L})] \times \Delta\text{T}$	
$[0.6 \ \mu\text{A/}^{\circ}\text{C} + (10 \ \text{ppm})]$		0.6 μA/°C + (10 ppm/°C × P ×		$[150 \ \mu\text{V}^{\prime}\text{C} + (5 \ \text{ppm}^{\prime}\text{C} \times P \times 0/\text{L})] \times \Delta T$ $[0.6 \ \mu\text{A}^{\prime}\text{C} + (10 \ \text{ppm}^{\prime}\text{C} \times P \times 1/\text{L})] \times \Delta T$	
			(/L)] × Δ1		
1030 V DC		1030 V DC		1030 V DC	
typ. ≤ 60 mA		yp. ≤ 60 mA		typ. ≤ 60 mA	К
yes		/es		yes	In
yes	,	/es		yes	nc
500 V DC (ground to I	nousing) 5	500 V DC (ground to housing)		500 V DC (ground to housing)	Ge
−40+85 °C		-40+85 °C		–40+85 °C	da
-40+100 °C	-	-40+100 °C		-40+100 °C	н
BTL6- <b>A</b> 500		BTL6- <b>B</b> 500		BTL6- <b>E</b> 500	In
0 V Output	(	) V Output		0 V Output	no
010 V		)5 V		420 mA	Ge
GND		GND		GND	da
1030 V DC		1030 V DC		1030 V DC	W
ov	CH S	G		4mA	Ge da
1	C	)V	s	OmA	int Di pu
0	• U	0 V	•	s	in Di pu in SS
-	Smax		s Smax	0mA	in Di pu in SS
Ū.	• U		•	0mA	in Di pu in SS in C/
Ordering example:	• U		•	0mA	int Di pu int SS int
Ordering example:	• U		•	0mA	An int Di pu int SS int CA int
Ordering example:           BTL6500-M	• U		•	0mA	int Dig pu int SS int CA
Ordering example: BTL6500-M	Smax		•	0mA	int Die pu int SS int C <i>F</i> int <b>Al</b> Ge
Ordering example: BTL6500-M Output	Standard		s <sub>max</sub>	0mA 0 Smax	int Dig pu int SS int CA int Al Ge da
Ordering example: BTL6500-M	Smax		•	0mA 0 Smax	int Di pu int SSS int CA int CA int AI Ge da AI
Ordering example: BTL6500-M Output	Standard	m]         Housing           00,         E2         Outer tube           00,         E28         Outer tube           00,         E28         Outer tube           00,         E38         Outer tube           00,         E48         Outer tube           00,         E18         Outer tube           00,         E18         Outer tube           00,         E18         Outer tube           00,         Inominal stroke         Inominal stroke           00,         1016         mm	Smax Connection Axial output KA02 P KA05 P KA10 P KA15 P	0mA 0 Smax	in Di pu in SS in C/ in C/ A in Ge da



#### P510 interface

Compatible with Balluff BTA processors as well as controllers and modules from various manufacturers, including Siemens, B & R, Bosch, Phoenix Contact, Mitsubishi, Sigmatek, Parker, Esitron and WAGO. Reliable signal transmission, even over cable lengths up to 500 m between BTA and transducer is assured by the noise-immune RS485 differential line drivers and receivers. Noise signals are effectively suppressed.

#### Universal P510 for rising and falling edge evaluation

As a consequence of different control philosophies, digital pulse interfaces are available in two different types depending on the controller.

The difference lies in how the edges are processed. The falling edges are processed in the "P interface" and the rising edges in the "M interface".

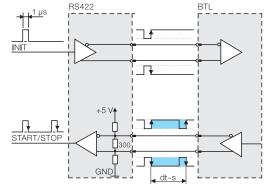
To reduce the number of different models to a minimum, the "P510 interface" was created as a universal pulse interface which combines both functions. The reference point for the propagation time measurement is the "start pulse".

#### Extremely precise digitizing chip for P510 pulse interface

Companies developing their own control and processing electronics can create a highly accurate P interface cost effectively and with minimum effort using the Balluff digitizing chip. The digitizing chip was developed as a high-resolution, configurable ASIC for Micropulse transducers with P interface.

#### **Benefits**

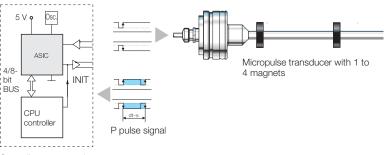
- High resolution: the actual 1 µm of the BTL is fully supported by the 133 ps resolution of the chip (at low clock frequency 2 or 20 MHz)
- Position data from 4 magnets can be processed simultaneously
- 4/8-bit processor interface



Block diagram of P interface



Digitizing chip 44QFP



Controller or processing electronics

**AR Rod Series** Digital pulse interface P510

Series			BTL6 rod AR			
Transducer interface			Pulse P510			
Input interface			Pulse P510			
Part number			BTL6- <b>P</b> 510-M			
System resolution			processing-dependent			
Repeat accuracy			≤ 10 μm			
Repeatability			≤ 20 μm			
Resolution			≤ 10 μm			
Non-linearity			±200 μm up to 500 mm nominal stroke			
			typ. ±0.02 %, max ±0.04 % 5001500 mm nominal stroke			
Operating voltage			1030 V DC			
Current consumption			$\leq$ 60 mA (at 1kHz)			
Operating temperatur	e		-40+85 ℃			
Storage temperature	range		-40+100 °C			
Pin assignments		Color	BTL6- <b>P</b> 510-M			
Input/Output	Input	YE	INIT			
signals	Output	GY	START/STOP			
	Input	PK	INIT			
	Output	GN	START/STOP			
Operating voltage		BU	GND			
		BN	1030 V DC			

Connect shield to housing

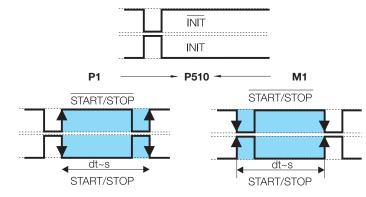
Please enter the code for the nominal stroke, housing and connection type in the ordering code.

Included:

- Transducer

- Short user's guide

Please order separately: Magnets/floats, page 96



K Installation notes General data н Installation notes General data W Installation notes General data HB/WB Installation notes General data Analog interface Digital pulse interface 00 се

#### Ordering example:

-M					SS int C/ int
Standard nominal stroke [mm]	Но	using	Conne	ection type	<b>Al</b> Ge da
0025, 0050, 0075, 0100, 0125, 0150,	E2	Outer tube	Axial ou	tput	Ar
0175, 0200, 0225, 0250, 0275, 0300,		Ø 10.2 mm	KA02	PUR cable 2 m	in
0325, 0350, 0375, 0400, 0425, 0450,	E28	Outer tube	KA05	PUR cable 5 m	D
0475, 0500, 0550, 0600, 0650, 0700,		Ø 8 mm, max.	KA10	PUR cable 10 m	p ir
0750, 0800, 0850, 0900, 0950, 1000,		nominal stroke	KA15	PUR cable 15 m	 Ir
1100, 1200, 1300, 1400, 1500, 1524 or in 1 mm increments on request		1016 mm	KA20	PUR cable 20 m	n
or in thin increments of request			Axial ec	centric output	
			KE02	PUR cable 2 m	
			KE05	PUR cable 5 m	
			KE10	PUR cable 10 m	
			KE15	PUR cable 15 m	
			KE20	PUR cable 20 m	

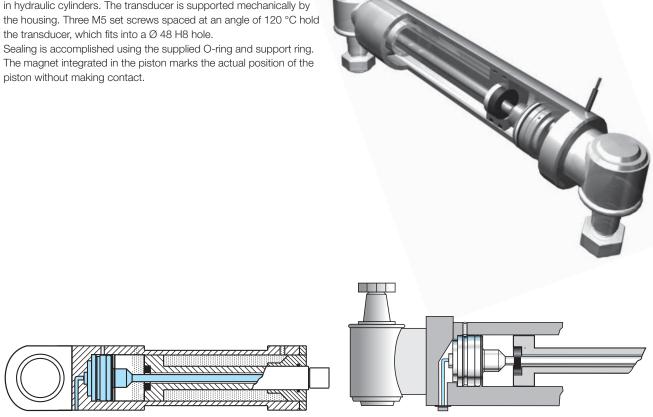
www.balluff.com

Axial output LA00.3 PUR pigtail 0.3 m



Series AR BTL Micropulse transducers are designed for integration in hydraulic cylinders. The transducer is supported mechanically by the housing. Three M5 set screws spaced at an angle of 120 °C hold the transducer, which fits into a Ø 48 H8 hole.

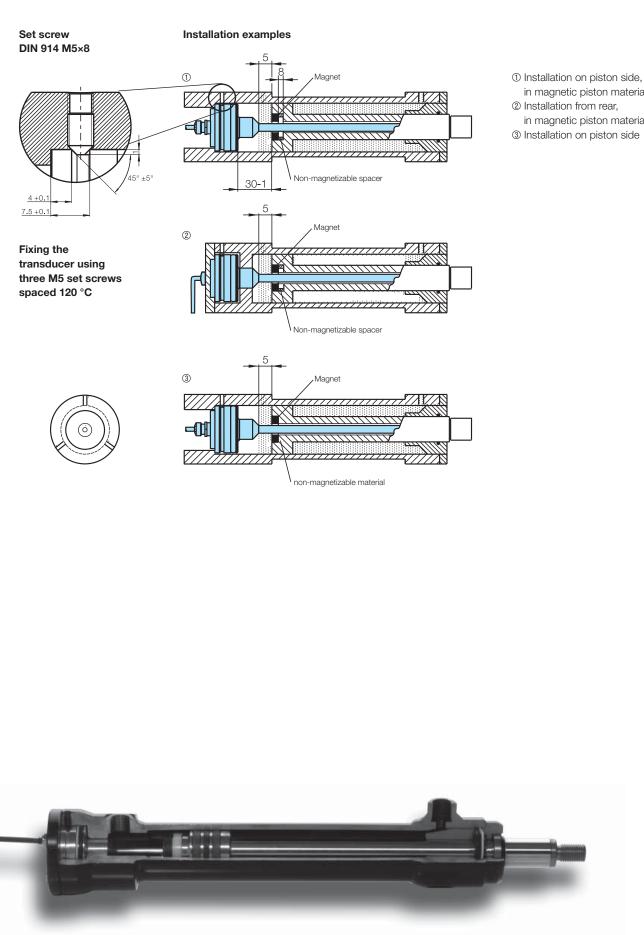
Sealing is accomplished using the supplied O-ring and support ring. The magnet integrated in the piston marks the actual position of the



The metal surrounding of the cylinder eliminates the need for a cable shield when the BTL AR...LA, cable outlet pigtail version is installed in the cylinder. The pigtail version cannot be used without additional EMC protection (shield).

> Caution! Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com





in magnetic piston material Installation from rear, in magnetic piston material ③ Installation on piston side



Κ

Installation notes General data н Installation notes General data W Installation notes General data HB/WB Installation notes General data Analog interface

Digital pulse interface SSI interface CANopen interface

AR General data Analog interface Digital pulse interface Installation notes





# MICROPULSE®

#### EX

(Ex)

EA	
Filling level sensor in zone 0/1	128
Transducer in zone 1	129
Dex rod series, general data	130
J-DEXC rod series, general data	132
PEX rod series, general data	134
NEX rod series, general data	135
Floats and magnets	136
т	

Redundant

138

Many applications require the use of distance sensors in potentially explosive areas. Flameproof magnetostrictive Micropulse transducers are available in a wide range of designs for use in zone 0 and 1.

**Rod Series EX** Filling level sensor in zone 0/1

#### BTL5-\_1-M....-B-DEXA-\_\_\_

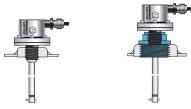
The "DEX**A**" rod version is the safe and reliable approach to level applications in Zone 0. The float is protected against loss by a cotter pin. Floats, page 136

#### Applications

- Filling stations
- Tank systems
- Refineries
- Chemical industry
- Pharmaceuticals

Zone 1 Zone 0

Installation examples



Caution! Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com

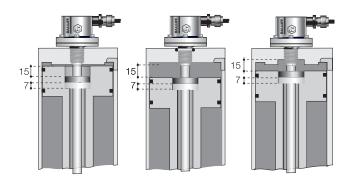


#### BTL5-\_1-M....-B-DEXB-\_ \_

The BTL can be used to sense the position of a hydraulic piston directly without making contact, even up to pressures of 600 bar. The BTL is threaded into the head of the cylinder. The rod section enters a drilled hole in the piston.

#### Applications

- Position feedback in hydraulic cylinders
- Valve positioning in power plants
- Dosimetry
- Positioning spray guns





#### Installation

The Micropulse transducer BTL has a mounting thread M18×1.5. We recommend that the mounting is made of non-magnetizable material.

If magnetizable materials are used, the installation must be carried out as shown in the drawing below. Sealing is at the flange mounting surface using the supplied O-ring 15.4×2.1 with M18×1.5 thread.

O-ring groove 15<sup>°</sup> ±1<sup>°</sup> R 0.1 +0.1 15<sup>°</sup> ±1<sup>°</sup> R 0.1 +0.1 0-ring groove 15.4 × 2.1 min. *a* 55 15.4 × 2.1 min. *a* 55 Insertion hole per ISO 6149

General linear positioning in zone 1



EX Filling level sensor in zone 0/1 Transducer in zone 1 Rod DEX Rod J-DEXC Rod J-DEXC Rod PEX Rod NEX Floats and magnets T Redundant



#### Pressure rated to 600 bar, high repeatability, non-contact, robust

The BTL Micropulse transducer is a robust position feedback system for measuring ranges between 25 and 4000 mm as well as use under extreme ambient conditions.

#### Ex protection type "d" flameproof enclosure

Transducers designated **Ex d IIB + H**<sub>2</sub> **T6** meet the requirements for electrical devices in explosive atmospheres. When using you must follow the relevant safety regulations, such as:

- Explosion protection guidelines (EX-RL)

BTL5-\_\_-M\_

- Constructing electrical equipment in potentially explosive areas (VDE 0165)
- Protection type "d", flameproof enclosure (EN 60079-1)

- - DEX

Transducers from category II 1/2 G designated Ex d IIB+H2 T6 meet the requirements for electrical devices in areas containing potentially explosive gases. Requirements for areas containing flammable dust are also fulfilled in accordance with category II 3D designated Ex tD IP67 T85°C, A zone 22.



**Analog interface** no null or end point trim possible, see page 110 for technical data Ordering example:

#### Output signal Standard nominal stroke [mm] Housing Rod end **Connection type** A11 0...10 V and 10...0 V, 0025, 0050, 0075, 0100, 0125, Axial cable outlet, В A Float stop Rising and falling 0150, 0175, 0200, 0225, 0250, J B Short stop housing B only E10 4...20 mA, rising 0275, 0300, 0325, 0350, 0375, KA02 PUR cable 2 m E17 20...4 mA, falling 0400, 0425, 0450, 0475, 0500, KA05 PUR cable 5 m C10 0...20 mA, rising 0550, 0600, 0650, 0700, 0750, KA10 PUR cable 10 m C17 20...0 mA, falling 0800, 0850, 0900, 0950, 1000, KA15 PUR cable 15 m G11 -10...10 V and 1100, 1200, 1300, 1400, 1500, 10...–10 V. 1600, 1700, 1800, 1900, 2000, Radial cable outlet Rising and falling 2250, 2500, 2750, 3000, 3250, K02 PUR cable 2 m 3500, 3750, 3850, 4000 or K05 PUR cable 5 m in 5 mm increments on request K10 PUR cable 10 m K15 PUR cable 15 m Digital pulse interface, see page 112 for technical data Ordering example: BTL5-\_1-M\_\_\_\_-B-DEX Rod end Interface Standard nominal stroke [mm] Connection type Ρ Pulse interface P A Float stop see above see above Pulse interface M analog interface DEX B Short stop analog interface DEX М Pulse interface I L SSI interface, see page 114 for technical data Ordering example: BTL5-S1\_\_-M\_\_\_\_-B-DEX\_-BTL5-S1 -M -B-DEX -Т System Standard Coding resolution nominal stroke [mm] Rod end Connection type 0 Binary code rising (24 bit) 1 1 µm see above A Float stop see above 2 1 Gray code rising (24 bit) 5 µm analog interface DEX B Short stop analog interface DEX Binary code rising (25 bit) З 10 µm 6

7

Gray code rising (25 bit)

4

5

20 µm

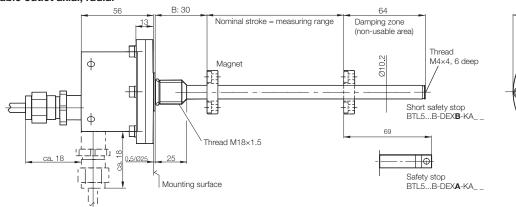
40 µm

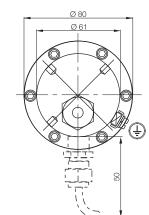


Series	BTL5 Compact rod, Ex
Part number	BTL51-MDEX
Shock load	100 g/6 ms per IEC 60068-2-27 and 100 g/2 ms per IEC 60068-2-29
Vibration	12 g, 102000 Hz per IEC 60068-2-6
Operating temperature	−40+60 °C
Polarity reversal protected	yes
Overvoltage protection	Transzorb protection diodes
Dielectric strength	500 V DC (GND to housing)
Degree of protection as per IEC 60529	IP 67
Housing material	Stainless steel 1.4305
Flange and tube material	Tube stainless steel 1.4571, flange 1.4571 or 1.4429 or 1.4404
Housing attachment	Thread M18×1.5, 3/4"-16 UNF on request
Connection type	Cable connection
EMC testing:	
RF emission	EN 55016-2-3 Group 1, Class A
Static electricity (ESD)	IEC 61000-4-2 Severity Level 3
Electromagnetic fields (RFI)	IEC 61000-4-3 Severity Level 3
Fast transients (BURST)	IEC 61000-4-4 Severity Level 4
Conducted interference induced	IEC 61000-4-6 Severity Level 3
by high-frequency fields	

#### Housing B, metric mounting thread

cable outlet axial, radial



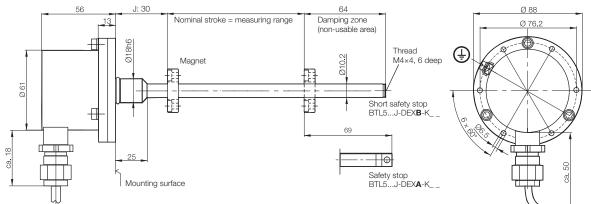




Transducer in zone 1 Rod DEX Rod J-DEXC Rod PEX Rod NEX Floats and magnets T

Redundant

# Housing J, flange $\varnothing$ 18 mm, PCD $\varnothing$ 76.2 mm, Radial cable outlet



Please enter the code for the output signal, interface, coding, nominal stroke, housing, rod end and connection type in the ordering code! Included:

- Transducer
- User guide

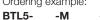
Please order separately: Magnets, page 96 Floats, page 136

#### Caution! Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com

www.balluff.com



Analog interface, see page 76/77 for technical data Ordering example:



MJ-DEXC-TA12		
Output signal	Standard nominal stroke [mm]	Connection type
A51 010 V and 100 V,	0025, 0050, 0075, 0100, 0125, 0150, 0175,	TA12 = 1/2" - 14 NPT
rising and falling	0200, 0225, 0250, 0275, 0300, 0325, 0350,	internal thread
E50 420 mA, rising	0375, 0400, 0425, 0450, 0475, 0500, 0550,	
E57 204 mA, falling	0600, 0650, 0700, 0750, 0800, 0850, 0900,	
C50 020 mA, rising	0950, 1000, 1100, 1200, 1300, 1400, 1500,	
C57 200 mA, falling	1600, 1700, 1800, 1900, 2000, 2250, 2500,	
G51 -1010 V and	2750, 3000, 3250, 3500, 3750, 3850, 4000,	
10–10 V,	4250 or in 5 mm increments on request	
rising and falling		

Programming tool for null point and end point BTL5-A-EH03

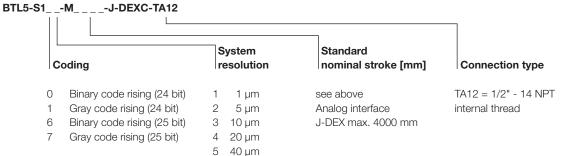
Digital pulse interface, see page 84/85 for technical data

Ordering example: BTL5-\_1-M -J-DEXC-TA12

Interface	Standard nominal stroke [mm]	Connection type
P Pulse interface P	see above	TA12 = 1/2" - 14 NPT
M Pulse interface M	Analog interface J-DEXC	internal thread
Pulse interface I		

SSI interface, see page 86/87 for technical data

#### Ordering example:



CANopen interface, see page 88/89 for technical data Ordering example:

BTL5-H1\_\_-M\_\_\_ -J-DEXC-TA12

Standard Baud nominal stroke [mm] Software configuration rate Connection type 1 × position and TA12 = 1/2" - 14 NPT 0 1 MBaud 4 125 kBaud see above 1 1 × velocity 800 kBaud 5 100 kBaud Analog interface internal thread 1 2 2 × position and 2 500 kBaud 6 50 kBaud J-DEXC max. 4000 mm 20 kBaud  $2 \times \text{velocity}$ 3 250 kBaud 7 8 10 kBaud PROFIBUS DP interface, see page 90/91 for technical data Ordering example: BTL5-T1\_0-M\_ \_-J-DEXC-TA12 Standard Software configuration nominal stroke [mm] Connection type Caution! Prior to design, TA12 = 1/2" - 14 NPT 1 × position and see above installation and startup, 1 × velocity Analog interface internal thread please read the instructions 2 × position and J-DEXC max. 4000 mm in the user guide! BALLUFF<sup>2 × velocity</sup> www.balluff.com





APPROVED Class I, Division I, Groups A, B, C and D Class II/III, Division I, Groups E, F, and G  $T6 Ta = 65^{\circ}C$ , T5 Ta = 80°C Version 4X/6P



Class I Zone 1 AEx d IIC T6 Ta = 65°C, T5 Ta = 80°C

$\langle x3 \rangle$	
EX d IIC T6 Ta = 65°C,	

 $Ta = 80^{\circ}C$ IP 68 SIRA 04 ATEX 1290

# International approval!

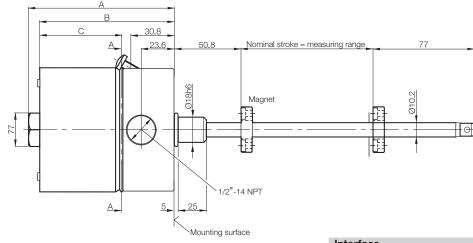
Series	BTL5MJ-DEXC-TA12
Part number	BTL5MJ-DEXC-TA12
Shock load	100 g/6 ms per IEC 60068-2-27
Vibration	12 g, 102000 Hz per IEC 60068-2-6
Operating temperature	-20+80 °C
Storage temperature range	-40+100 °C
Degree of protection	IP 68
Housing material	Stainless steel Nitronics 60
Outer tube	1.4571 stainless steel
Pressure rating	600 bar max.
Connection type	Screw terminals
Cable entry	Ex cable gland BTL-A-AD09-M-00EX
EMC testing:	
RF emission	EN 55016-2-3 Group 1, Class A
Static electricity (ESD)	IEC 61000-4-2 Severity Level 3
Electromagnetic fields (RFI)	IEC 61000-4-3 Severity Level 3
Fast transients (BURST)	IEC 61000-4-4 Severity Level 3
Conducted interference induced	IEC 61000-4-6 Severity Level 3
by high-frequency fields	

**Rod Series J-DEXC** 

General data

#### Housing J-DEXC

Flange  $\oslash$  18 mm, PCD  $\oslash$  76.2 mm



The Micropulse transducer J-DEXC has been specially developed for use in hazardous areas. The J-DEXC system fulfills demanding requirements in the oil and gas industry for high reliability and ease of servicing.

J-DEXC comprises a robust flameproof Ex housing and an electronics module that is easily accessed and exchanged for servicing. Spare electronics modules can be ordered from Balluff Service Dept.

#### Applications:

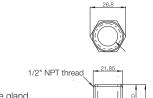
- Hydraulic or pneumatically actuated valves
- Clutch travel monitoring for compressors
- Level monitoring
- Level control
- Position sensing for hydraulic cylinders in hazardous areas

Please enter the code for the output signal, interface, coding, system solution, software configuration, baud rate, nominal stroke and connection type in the ordering code!

- Included:
- Transducer
- Short user's guide

Please order separately: Magnets, page 97 Floats, page 136

Interface	A (mm)	B (mm)	C (mm)
Analog A, E, C, digital P, M, I, SSI	104.12	96.12	59.5
PROFIBUS-DP, CANopen	135.62	127.62	91



Cable gland 1/2" - 14 NPT to M20 metric BTL-A-AD09-M-00EX

\_\_\_\_\_\_ M20 thread



Filling level sensor in zone 0/1 Transducer in zone 1 Rod DEX **Rod J-DEXC** 

Ø 87.5

Ø 76.2

CSA/AEx

E, F, G

CENELEC SIRA 00A TEX1094 EX de I & IIC I M2, II 2 GD

AEx de Class I, Zone I, Groups I & IIC

Class I, Division I & 2,

Groups A, B, C, D

Class II & III, Groups

Rod PEX Rod NEX Floats and magnets

**T** Redundant



#### **Dust protection zone 22**

Devices in these categories are intended for use in areas where swirling dust is not expected to create an explosive atmosphere. The probability is extremely small. Even if it were to occur, it would be only for a short time.

A manufacturer's certificate with the designation

#### II 3 D T 90°C X

is provided to confirm that the transducer code satisfies requirements for the use of electrical equipment in areas with inflammable dust.

			and the state of the
		EG-	Konformitätserklärung anati R. Hysto
	Dokument Nt. Document in	635278 GEP 080 D6/DH0230	
	Hersteller:	Bahufi Grebh Schurweisbersalle 9 20105 Neutrauers/Fister	
	HiceAares, I	ion amon Morgania Regari	***
	Besidning:	Transsonar Linear	weggeber
	Typ: BTLB-	1-W****-BIZ-PEX-HA**	
	Annaschus	F HEDTHICK	
	Rates von 23 für Geste um explosionsgef Die grundlege	Mars 1864 bur Angleichung der Bohulleryderne zur bestimmung Intelden Beneichen entspricht. rden Sicherheits- und Gesundhei	1993 - Usters
	duich Oberein		
		DV 60014: 1987 und EN	
	Das Zeichen , für die sichen sufgeführt sin	Childer der Sonngelchung wei Anwenching des Getätes hin, die L	it suf besonders Bedingungen Lin der Betriebsanieitung
	Uberwacht Die entoigen mit o	ablaufe sind paplant und werden Prozeškentrolen und se 150% mpulan undersköptes Proligerale and angewertet. Die Proligerale Iotext.	-Endprutung n Die Metholaten
2	Dies Qualitatie- at von der DQ	rid Unwellinknagemenikystem nach Ditt EN ISO 9001 taxe. Di	fer Beluff Gmätt N EN KilO 14001 zertilizert
2	Mechanisment of	wi 2004-11-11	
	e.K. Hang	4	in Glueily
	D. Hofoang	Abuger Homoger	Minihard Schrander Later PG3 87L/845

Digital pulse interface, see page 84/85 for technical data Ordering example:

BTL5-P1-M	<b>PEX-KA02</b>	
	Standard nominal stroke [mm]	Housing

0025, 0050, 0075, 0100, 0125, 0150, 0175, 0200, 0225, 0250, 0275, 0300, 0325, 0350, 0375, 0400, 0425, 0450, 0475, 0500, 0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900, 0950, 1000, 1100, 1200, 1300, 1400, 1500, 1600, 1700, 1800, 1900, 2000, 2250, 2500, 2750, 3000, 3250, 3500, 3750, 3850, 4000, 4250, 4500, 4750, 5000, 5250, 5500 or in 5 mm increments on request. B M18×1.5 Z 3/4"-16UNF

PUR cable 2 m

Connection type

INF



Caution! Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com

# **Protection type** "n" for zone 2



#### Protection type "n" designated "EEx n"

Devices in these categories are intended for use in areas where an explosive atmosphere is not expected. The probability is extremely small. Even if it were to occur, it would be only for a short time. A manufacturer's certificate is provided, confirming that the product satisfies requirements for the use of electrical equipment in potentially explosive areas.

Several methods of flameproofing are combined under the designation.

		BALLUFF				
	1	EG- Konformitätserklärung				
	Hersteller: Balluff CribH Schurweidstraße 9 73765 Neuhausen/Filder					
	Wir erklären, dass unsere Micropulse Wegaufreihnen					
	Bezeichnung: Transsonar- L					
	Typ: 8TL5-411-M****-842-MEX-**** 8TL5-C11-M****-82-MEX-**** 8TL5-C11-M***-82-MEX-**** 8TL5-011-M***-82-MEX-**** 8TL5-01-M****-82-MEX-****	8TL5-611-49****-K-8EE.**** 8TL5-611-49****-K-8EE.**** 8TL5-611-49****-K-8EE.**** 8TL5-61-49****-K-8EE.****				
	Kennsidmung: II 3 G EEx nA	IT4X				
	den Antonieurungen der Richtlinis D4/0/EC des Europäischen Parlaments und des Rieter vom 23. März 1904: zur Angleichung der Rechtworschritten der Mitgliedstauten für Destile und Schutztysittere zur bestimmungsgamtäßen Verwendung in explosionsgafähndeten Bereichen entspricht.					
	Die grundlegenden Sicherheits- und Ges durch Übereinstimmung mit EN 500211:					
	Das Zeichen "K" hinter der Kennzmichnung weist auf besondere Bedingungen für die sichere Anwendung des Geräles hin, die in der Betriebsanleitung sufgeführt sind.					
	Die Fertigungsabilitete sind geplant und v überwacht. Die Prozelikontrollen und die erfolgen mit. computeruntentützten Profi werden erfalt und ausgewertet. Die Prof regelmäßig kalibriert.	100%-Endprüfung perilten. Die MeGdaten				
$\frown$	Das Qualitäte- und Umweltmanagements ist von der DQS nach DIN EN ISO 9001 b					
U	Neuhausen, den 2003-07-23	.Co				
	A K TIMY Dr. Wolfgang Hauper	N Solut dui Moteel Schreider				
	Loter GualMtsmanagement	Leter PC3 BTL/BIS				
Die Boherheit	Shinaelut der milgelieheter Probabildekumentation sind zu br	uerbien.				

Housing K, see page 110/111 for analog interface and page 112/113 for digital pulse interface Ordering example:

5MK-NEX	-			-
Output signal	Standard nominal stroke [mm]		Connection type	EX Fillin sens
A11 010 V and 100 V E10 420 mA, rising E17 204 mA, falling C10 020 mA, rising C17 200 mA, falling P1 Pulse interface P series, see page 76/77 for ana ring example:	0025, 0050, 0075, 0100, 0125, 015 0200, 0225, 0250, 0275, 0300, 032 0375, 0400, 0425, 0450, 0475, 050 0600, 0650, 0700, 0750, 0800, 085 0950, 1000, 1100, 1200, 1300, 140 1600, 1700, 1800, 1900, 2000, 225 2750, 3000, 3250, 3500, 3750, 385 4250, 4500 or in 5 mm increments or request.	25, 0350, 10, 0550, 10, 0900, 10, 1500, 10, 2500, 10, 4000, 10, 4000, 10, 10, 10, 10, 10, 10, 10, 10, 10, 10,	SR32 with connector plug K05 PUR cable 5 m	in zo Trans in zo Rod Rod Rod Float and mag T Redu
Output signal	Standard nominal stroke [mm]	Housing	Connection type	
A11       010 V and 100 V         E10       420 mA, rising         E17       204 mA, falling         C10       020 mA, rising         C17       200 mA, falling         P1       Pulse interface P	0025, 0050, 0075, 0100, 0125, 0150, 0175, 0200, 0225, 0250, 0275, 0300, 0325, 0350, 0375, 0400, 0425, 0450, 0475, 0500, 0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900, 0950, 1000, 1100, 1200, 1300, 1400, 1500, 1600, 1700, 1800, 1900, 2000, 2250, 2500, 2750, 3000, 3250, 3500, 3750, 3850, 4000, 4250, 4500 or in 5 mm increments on request.	B M18×1.5 Z 3/4"-16UNF	S32 with connector plu K05 PUR cable 5 m	ıg
e output signal, nominal e, housing and connection	Please order separately: Magnets, page 97 Floats, page 136 Connectors, page 148/149	5		





# User-friendly hardware and software set-up

Floats (Zone 0)

#### BTL2-S-4414-4Z-Ex

Cylindrical float, zone 0 permitted up to density  $\rho \geq 0.7~g/cm^{\scriptscriptstyle 3}$ 

Orientation: Raised dimple on upper side of float

0+0

#### BTL2-S-4414-4Z01-Ex

Cylindrical float, zone 0, density of float  $\rho = 0.85 \mbox{ g/cm}^3$  for liquid interface sensing

Orientation: 2 raised dimples on upper side of float

#### Interface

A second float can be added to measure the position of the interface between two liquids, such as oil and condensed water. Suitable: BTL2-S-4414-4Z01-Ex.



## BTL2-A-DH01-E-32-Ex

Spacer sleeve for the float: BTL2-S-4414-4Z-Ex BTL2-S-4414-4Z01-Ex BTL2-S-5113-4K-Ex The sleeve is included.



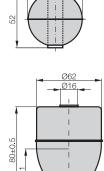
#### BTL2-S-5113-4K-Ex

Ball float, zone 0 permitted up to density  $\rho \ge 0.7 \text{ g/cm}^{\scriptscriptstyle 3}$ 

Orientation: Raised dimple on upper side of float

#### BTL2-S-6216-8P-Ex

Parabolic float, approved up to  $\rho \ge 0.6$  g/cm<sup>3</sup>



Ø50.9

Float model	Immersion depths assuming	
	$\rho = 1 \text{ g/cm}^{3} (\mathbf{H_{2}O})$	$\rho = \textbf{0.7 g/cm}^3$
BTL2-S-6216-8P-Ex	s <sub>s</sub> ~ 41 mm	s <sub>s</sub> ~ 57 mm
BTL2-S-5113-4K-Ex	s <sub>s</sub> ~ 26 mm	s <sub>s</sub> ~ 40 mm
BTL2-S-4414-4Z-Ex	s <sub>s</sub> ~ 30 mm	s <sub>s</sub> ~ 39 mm
BTL2-S-4414-4Z01-Ex	s <sub>s</sub> ~ 45 mm	submerges

See technical data on page 96

Magnets (Zone 1) for installation in hydraulic cylinders See page 97

Processors, digital displays

See page 163





EX Filling level sensor in zone 0/1 Transducer in zone 1 Rod DEX Rod J-DEXC Rod J-DEXC Rod PEX Rod NEX Floats and magnets T

Redundant



#### **Special series**

Difficult applications often make special demands on the sensors. Balluff meets these requirements with transducers that have been specified and developed in conjunction with the system integrator. Behind this is a large, highly motivated Micropulse development team as well as Balluff's own EMC Testing Laboratory and shock and vibration test centers.

#### The "3-in-1" transducer!

- 2 or 3-way redundant distance measurement system for heightened safety requirements
- One transducer consists of two or three completely separate distance measurement systems
- Start/Stop or analog interfaces
- Compact housing
- Max. nominal stroke 1000 mm

#### Available outputs:

- Analog 0...10 V, 4...20 mA, 0...20 mA, -10...10 V
- Pulse interface

Ordering example:

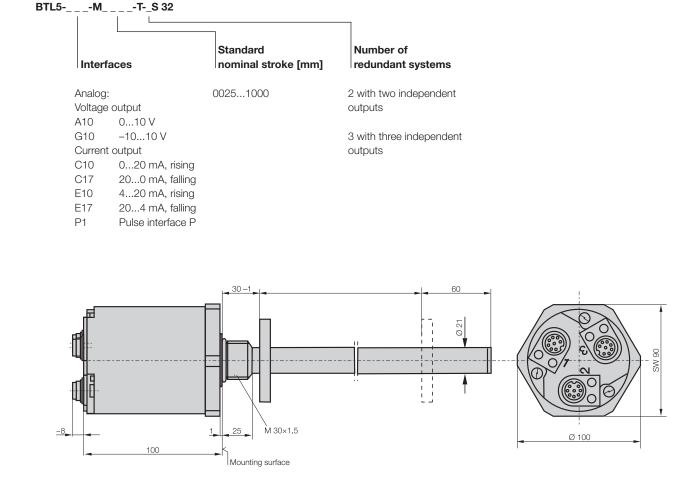
Download the operating instructions from www.balluff.com for more information



Tilting technology on rail cars



Propeller pitch control







Rudder control

010	V
420	mA
020	mA
-101	<b>0</b> V



EX Filling level sensor in zone 0/1 Transducer in zone 1 Rod DEX Rod J-DEXC Rod J-DEXC Rod NEX Floats and magnets T Redundant













142 144 146



The magnetostrictive working principle is ideal for the continuous high-precision measurement of fluid filling levels. Waveguides and processing electronics are enclosed inside a housing made from stainless steel. Stainless steel floats with permanent integrated magnets mark the current filling level in the tank or vessel. The design of the sensors meets international hygiene standards.

# **BTL-SF Filling Level Sensor**

General data

# more added value

- Continuously precise measurement in µ area delivers excellent filling results 100 % stainless steel ensures top hygiene
- standards and long service life International certificate guarantees maximum

quality

#### Maximum precision for food hygiene internationally certified

The BTL-SF filling level sensor ensures continuously precise measurement in applications that demand extreme hygiene. Made from corrosion-free stainless steel with excellent surface quality and rounded edges, the sensor meets the highest international hygiene standards and fulfills all strict requirements of the food industry. Take advantage of the best quality directly from the manufacturer.

Other benefits:

- Neutral for all liquids
- Compensates for foam, thus delivering reliable filling level values
- Adjustment-free installation
- Easy to clean in installed state (CIP Clean in Place)
- For process temperatures up to 130 °C (SIP Sterilization in Place)
- Standardized interfaces ensure flexible installation
- Internationally certified quality guarantees global marketing and sales of your system
- Rising and falling signal available



In the USA, 3-A Sanitary Standards Inc. formulates and monitors hygiene guidelines for devices used in the manufacture and packaging of milk and foodstuffs. Our products with this designation are 3-A approved.

The EHEDG (European Hygienic Engineering & Design) designation is the European standard for hygiene in the food industry. Our products with this logo conform to EHEDG standards.





The FDA (Food and Drug Administration) oversees the US food and pharmaceutical industry and certifies devices, materials, systems and machines from these sectors. A product designation of this kind makes your system eligible for FDA approval.

The ECOLAB designation stands for consistency against aggressive cleaning agents. Devices with ECOLAB markings fulfill their standards.







# 100 % stainless steel

# BTL-SF Filling Level Sensor

General data



input intenace
Part number
Polarity reversal protected
Overvoltage protection
Dielectric strength
Degree of protection as per IEC 60529
Housing material
Flange and tube material
Connection
Mounting
Pressure rating
EMC testing:
RF emission
Static electricity (ESD)
Electromagnetic fields (RFI)
Fast transients (BURST)
Line-induced disturbances,
induced by high-frequency fields
Surge voltage
Magnetic fields
Standard nominal stroke (mm)

BTL5-...-M\_\_\_\_-SF-F\_\_\_\_ yes 36 V 500 V DC (GND to housing) IP 67/IP 69K (flange and tube) Stainless steel 1.4404 1.4404 Cable connection 1.5" Tri Clamp as per SSI 3A standard 74-03 300 bar (depending on float) EN 55016-2-3 Group 1, Class A and B

EN 55016-2-3 Group 1, Class A and B EN 61000-4-2/EN 61000-4-2 Severity Level 3 EN 61000-4-3/EN 61000-4-3 Severity Level 3 EN 61000-4-4/EN 61000-4-4 Severity Level 3 EN 61000-4-6/EN 61000-4-6 Severity Level 3

IEC 61000-4-5/EN 61000-4-5 Severity Level 2 IEC 61000-4-8/EN 61000-4-8 Severity Level 4 0025, 0050, 0075, 0100, 0125, 0150, 0175, 0200, 0225, 0250, 0275, 0300, 0325, 0350, 0375, 0400, 0425, 0450, 0475, 0500, 0550, 0600, 0650, 0700, 0750, 0800, 0850, 0900, 0950, 1000, 1100, 1200, 1300, 1400, 1500, 1600, 1700, 1800, 1900, 2000, 2250, 2500 or in 5 mm increments on request SF

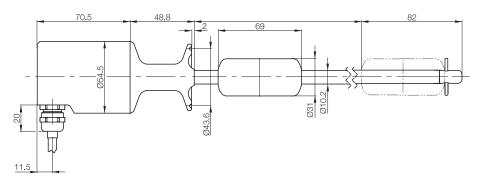
General data Analog interface Floats and accessories

Included:

- Transducer

- Short user's guide

Please order separately: Tri Clamp, page 146 Floats, page 146 O-ring, page 146 Welded hexagon nipple, page 146



Caution! Prior to design, installation and startup, please read the instructions in the user guide! www.balluff.com

# **BTL-SF Filling Level Sensor**

Analog interfaces

The industry-standard filling level sensor works with the triedand-tested Micropulse technology, an absolute and contact-free magnetostrictive measurement, which has been associated with top reliability for years. In addition, it has analog interfaces and due to this common standard signal, can be used in process automation.

#### Analog signal

A signal that can accept continuous, (almost) infinitely variable, values between a minimum and a maximum is described as an analog signal.

The output signal of the BTL-SF filling level sensor is analog and directly proportional to the position of the float on the sensor tube.

#### Features:

- Reasonably priced system solution
- Can be used from each controller
- Cable break monitoring through 4...20 mA signal
- Current signal, interference-free signal transfer
- High resolution and repeatability
- Rising and falling signal available

#### Variants:

- Current (4...20 mA or 0...20 mA)
- Voltage (0...10 V or 10...0 V)





#### Series

Output signal		
Transducer interface		
Input interface		
Part number		
Output voltage		
Output current		
Load current		
max. ripple		
Load resistance		
System resolution		
Hysteresis		
Repeat accuracy		
Sampling rate		
Non-linearity, max.		
Temperature coefficient		
Operating voltage		
Current consumption		
Polarity reversal protected		
Overvoltage protection		
Dielectric strength		
Operating temperature		
Process temperature 130° C for one h	nour	
Pin assignments	Color	
Output signals	YE	
	GY	
	PK	
	GN	
Operating voltage	BU	
	BN	
	WH	

Connect shield to housing

#### Included:

- Transducer
- Short user's guide

Please order separately: Tri Clamp, page 146 Floats, page 146 O-ring, page 146 Welded hexagon nipple, page 146

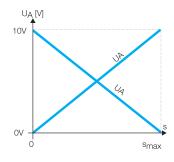
Teflon cable - LIF5Y-FC-5Y (7x0.25mm<sup>2</sup>):

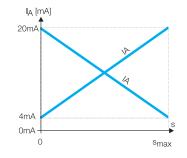
- Temperature-resistant up to 200 °C
- Good resistance against chemicals and oil

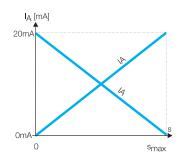
### maximum precision

## **BTL-SF Filling Level Sensor** Analog interfaces

BTL5 rod SF	BTL5 rod SF		BTL5 rod SF	
analog	analog		analog	
A	E		С	
analog	analog		analog	
BTL5- <b>A</b> 11-MSF	BTL5- <b>E</b> 1MSF		BTL5- <b>C</b> 1MSF	
010 V and 100 V				
	420 mA or 204	mA	020 mA or 200	) mA
max. 5 mA				
≤5 mV				
	≤ 500 ohms (500 oh	nms)	≤ 500 ohms (500 c	ohms)
≤0.1 mV	≤ 0.2 µA		≤ 0.2 µA	
≤ 4 μm	≤ 4 µm		≤ 4 µm	
System resolution/min. 2 µm	System resolution/m	nin. 2 µm	System resolution/min. 2 µm	
f <sub>standard</sub> = 500 Hz	$f_{STANDARD} = 500 \text{ Hz}$		f <sub>standard</sub> = 500 Hz	
±100 µm up to 500 mm nominal stroke	±100 µm up to 500	mm nominal stroke	$\pm 100~\mu m$ up to 500 mm nominal stroke	
±0.02 % 500 max. nominal stroke	±0.02 % 500 max	. nominal stroke	±0.02 % 500 max. nominal stroke	
$\leq$ 40 ppm/K for nominal stroke 500 mm,	$\leq$ 40 ppm/K for nom	ninal stroke 500 mm,	$\leq$ 40 ppm/K for nominal stroke 500 mm,	
float at center of measuring range	float at center of me	asuring range	float at center of m	neasuring range
2028 V DC	2028 V DC		2028 V DC	
≤ 150 mA	≤ 150 mA		≤ 150 mA	
yes	yes		yes	
36 V	36 V		36 V	
500 V DC (ground to housing)	500 V DC (ground to	o housing)	500 V DC (ground to housing)	
-40+85 °C	-40+85 °C		−40+85 °C	
–40+100 °C	-40+100 °C		-40+100 °C	
BTL5- <b>A</b> 11	BTL5- <b>E</b> 10	BTL5- <b>E</b> 17	BTL5- <b>C</b> 10	BTL5- <b>C</b> 17
	420 mA	204 mA	020 mA	200 mA
0 V Output	0 V Output	0 V Output	0 V Output	0 V Output
100 V				
010 V				
GND	GND	GND	GND	GND
+24 V DC	+24 V DC	+24 V DC	+24 V DC	+24 V DC







General data Analog interface Floats and accessories

SF

Ordering example:

BTL5-\_1\_-M\_\_\_\_-SF-\_\_\_\_

Inter- face		Dutput signal	Standard nominal stroke [mm]	Rad	dial connection
Ą	1	Rising	0025, 0050, 0075, 0100, 0125, 0150,	F02	Teflon cable 2 m
Ξ		and falling	0175, 0200, 0225, 0250, 0275, 0300,	F05	Teflon cable 5 m
)		with A	0325, 0350, 0375, 0400, 0425, 0450,	F10	Teflon cable 10 m
	0	Rising	0475, 0500, 0550, 0600, 0650, 0700,	F15	Teflon cable 15 m
		(with C and E)	0750, 0800, 0850, 0900, 0950, 1000,	F20	Teflon cable 20 m
	7	Falling	1100, 1200, 1300, 1400, 1500, 1600,		
		(with C and E)	1700, 1800, 1900, 2000, 2250, 2500		
			or in 5 mm increments on request		

## **BTL-SF Filling Level Sensor**

Floats and accessories









Description	Float	Tri Clamp (DIN 32676)	O-ring	Welded hexagon nipple
for series	BTL5 rod SF	BTL5 rod SF	BTL5 rod SF	BTL5 rod SF
Part number	BTL-S-3112-4Z	BAM MC-XA-006-D38.1-5	BAM SE-XA-002-D38.1-5	BAM-AD-XA-003-D38.1-5
Vlaterial	Stainless steel 1.4404	USA ASTM 316 (1.4401)	Platinum catalyzed	Part no. W. 1.4435 BN2
			silicone	(Fe $\leq$ 0.5 %) as per EB 10088
Veight	ca. 30 g			
Operating temperature/	–40+130 °C			
Storage temperature range				
Displacement in water	approx. 31 mm			
Pressure rating (static)	24 bar			
67	0 0 0 0 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1			34.8

Process temperature: maximum permissible temperature of the rod under the flange (with media contact). Certain production processes require, for example sterilization at **120 °C – 130 °C** for 0.5 – 1 hour.

"Junction float" on request.

IP69K

120 °C – 130 °C Included in scope of delivery for float:

- Float
- Instructions
- Cotter pin (spring pin 2×30)



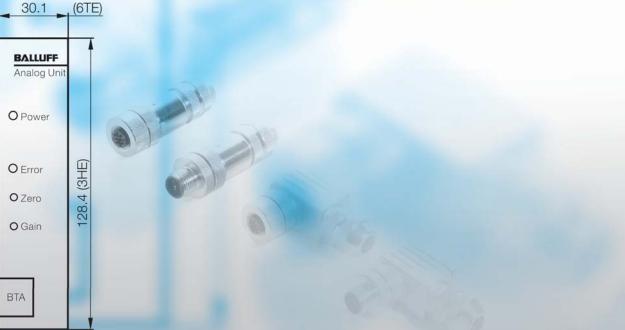
#### **Caution!** Approvals only issued through use of these components. Prior to design, installation and startup, please read the instructions in the user guide!



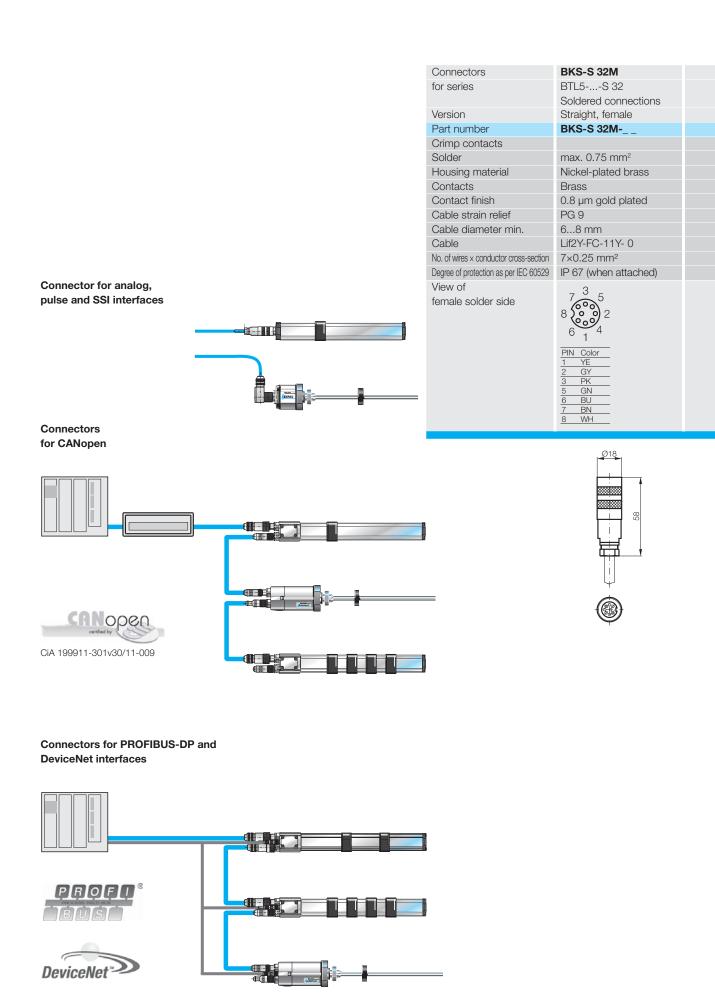


## MICROPULSE®

Connectors	148	ļ
Processors	158	
Profibus module P111	160	
BUS interface module	162	
Digital display, CAM controller	163	

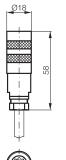


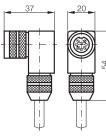




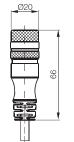
Accessories Connectors for analog, pulse and SSI interfaces

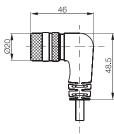
BKS-S 32M-C	BKS-S 33M	BKS-S 78M	BKS-S232	BKS-S233
BTL5S 32	BTL5S 32	BTL5S 32	BTL7S32	BTL7S32
Crimp contacts	Soldered connections	Soldered connections		
Straight, female	Right-angle, female	Straight, male		
BKS-S 32M-C	BKS-S 32M	BKS-S 78M-00	BKS-S232-PU	BKS-S233-PU
max. 0.5 mm <sup>2</sup>				
	max. 0.75 mm <sup>2</sup>	max. 0.75 mm <sup>2</sup>		
Nickel-plated brass	ZnAlCu1 nickel-plated	Nickel-plated brass	PUR	PUR
Brass	Brass	Brass	Brass	Brass
0.8 µm gold plated	0.8 µm gold plated	0.8 µm gold plated	0.8 µm gold plated	0.8 µm gold plated
PG 9	PG 9	PG 9		
68 mm	68 mm	68 mm		
Lif2Y-FC-11Y- 0	Lif2Y-FC-11Y- 0		LifgY+LifgY, FC-11Y	LifgY+LifgY, FC-11Y
7×0.25 mm <sup>2</sup>	7×0.25 mm <sup>2</sup>		8×0.25 mm <sup>2</sup>	8×0.25 mm <sup>2</sup>
IP 67 (when attached)	IP 67 (when attached)	IP 67 (when attached)	IP 67 (when attached)	IP 67 (when attached)
$7 \xrightarrow{3} 5$ $8 \xrightarrow{6} 2$ $4$ $\frac{1}{2} \xrightarrow{1} YE$ $2 \xrightarrow{6} GY$ $3 \xrightarrow{7} PK$ $5 \xrightarrow{6} GN$ $6 \xrightarrow{6} BU$ $7 \xrightarrow{8} WH$	$ \begin{array}{c} 7 & 3 & 5 \\ 8 & 6 & 1 \\ \hline PIN & Color \\ 1 & YE \\ 2 & GY \\ \hline 3 & PK \\ \hline 5 & GN \\ 6 & BU \\ \hline 7 & BN \\ 8 & WH \end{array} $	$ \begin{array}{c} 7 & 3 & 5 \\ 8 & 2 & 2 \\ 6 & 1 \\ \hline PIN & Color \\ 1 & YE \\ 2 & GY \\ 3 & PK \\ 5 & GN \\ 6 & BU \\ 7 & BN \\ 8 & WH \end{array} $	7 3 5 8 6 2 6 4 <u>PIN Color</u> 1 YE 2 GY 3 PK 5 GN 6 BU 7 BN 8 WH	$ \begin{array}{c} 7 & 3 & 5 \\ 8 & 4 & 2 \\ 6 & 1 & 2 \\ \hline PIN & Color \\ 1 & YE \\ 2 & GY \\ \hline 3 & PK \\ 5 & GN \\ 6 & BU \\ 7 & BN \\ 8 & WH \end{array} $













Connectors Processors Profibus module P111 BUS interface modules Digital display CAM controller

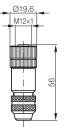


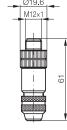
Please include the Part number in the ordering code! Code 00 for self-assembly (please use shielded cable). Code 05, 10, 15, 20, 25, 30 m for finished cable assembly.



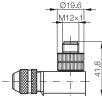
Accessories Connectors for CANopen and DeviceNet interfaces

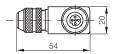
Connectors	BKS-S92-00	BKS-S94-00	BKS-S93-00	BKS-S95-00
for series	BTL5-HS92/S93/S94	BTL5-HS92/S93/S94	BTL5-HS92/S93/S94	BTL5-HS92/S93/S94
	Screw terminals	Screw terminals	Screw terminals	Screw terminals
Version	5-pin, female	5-pin, male	5-pin, female	5-pin, male
Part number	BKS-S92-00	BKS-S94-00	BKS-S93-00	BKS-S95-00
Screw terminal	max. 0.75 mm <sup>2</sup>			
Housing material	Nickel-plated brass	Nickel-plated brass	Nickel-plated brass	Nickel-plated brass
Contacts	Brass	Brass	Brass	Brass
Contact finish	0.8 µm gold plated			
Cable strain relief	PG 9	PG 9	PG 9	PG 9
Cable diameter	68 mm	68 mm	68 mm	68 mm
No. of wires × conductor cross-section				
Degree of protection as per IEC 60529	IP 67 (when attached)			
Knurled coupling ring				
Finish				
O-ring				
Resistor				
Coding	А	А	А	A
Socket on transducer	1	2	1	2
View of female coupling side				
	PIN         Signal           1         CAN_GND           2         +24 V           3         GND (0 V)           4         CAN_HIGH           5         CAN_LOW	PIN         Signal           1         CAN_GND           2         +24 V           3         GND (0 V)           4         CAN_HIGH           5         CAN_LOW	PIN         Signal           1         CAN_GND           2         +24 V           3         GND (0 V)           4         CAN_HIGH           5         CAN_LOW	PIN         Signal           1         CAN_GND           2         +24 V           3         GND (0 V)           4         CAN_HIGH           5         CAN_LOW
	Ø19.6	Ø19.6	Ø19.6	Ø19.6

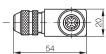












CANopen 2 1











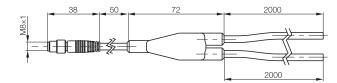
Accessories Connectors for CANopen and DeviceNet interfaces

	BKS-S92-TA1	BKS-S137-19-PC	BKS-S151-19-PC	BKS-S94-R01	BKS-S92-16/GS92
	BTL5-HS92	BTL5-HS92/S93/S94	BTL5-HS92/S93/S94	BTL5-HS92/S93/S94	BTL5-HS92/S93/S94
	T-splitter, $2 \times$ female, $1 \times$ male	5-pin, female	5-pin, male	Terminating resistor, male	Male/female extension
	BKS-S92-TA1	BKS-S137-19-PC	BKS-S151-19-PC	BKS-S94-R01	BKS-S92-16/GS92
	DA	סווס			סווס
	PA	PUR	PUR	TPU	PUR
	Brass	Brass	Brass	Brass	Brass
	INI	0.8 µm gold plated	0.8 µm gold plated	0.8 µm gold plated	0.8 µm gold plated
		5×0.25 mm <sup>2</sup>	5×0.25 mm <sup>2</sup>		5×0.34 mm <sup>2</sup>
	IP 67	IP 67	IP 67	IP 68	IP 67
	Brass	Brass	Brass	Brass	Brass
	2.5 µm Ni	2.5 µm Ni	2.5 µm Ni	2.5 µm Ni	2.5 µm Ni
	HBR	Viton	Viton	Viton	Viton
				121 ohms	
	А	А	А	А	А
	1*	1	2	2	1/2
				5	
				2 3	
				PIN Signal	
				1 -	
				2 - 3 -	
				4 5 121 ohms	
				<u>5</u>	
	*only for	Please include the type des-	Please include the type des-		Please include the type des-
	BTL5-H1M-P/B-S92	ignation in the ordering code!			ignation in the ordering code!
	51201111111175 002		02 = Length 2  m		02 = Length  2  m
			05 = Length 5 m		05 = Length 5  m
			10 = Length 10 m		10 = Length 10 m
	56.5	0145	Ø14 5	Ø14.5	0145 0145
	10.4	M12x1		M12×1	-614.5 M12x1 M12x1 M12x1
	Ø4.5 9:0				
				45.5	
			用し	H	
	00000000				
	M12×1		i i	Ι	
	M12x1Ø14.5		Ļ	I	
	M12×1 Ø14.5			I	
	014.5				
	014.5				
	014.5				
				-	
		Ļ			
		ţ		-	
04		ţ		-@	
0.4			Ļ	-	
0.0			ļ		
0.0					
04			ļ	-	
				Please order the clear	
				Please order the clear view cover separately!	

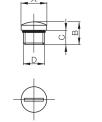
Connectors Processors Profibus module P111 BUS interface modules Digital display CAM controller

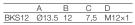


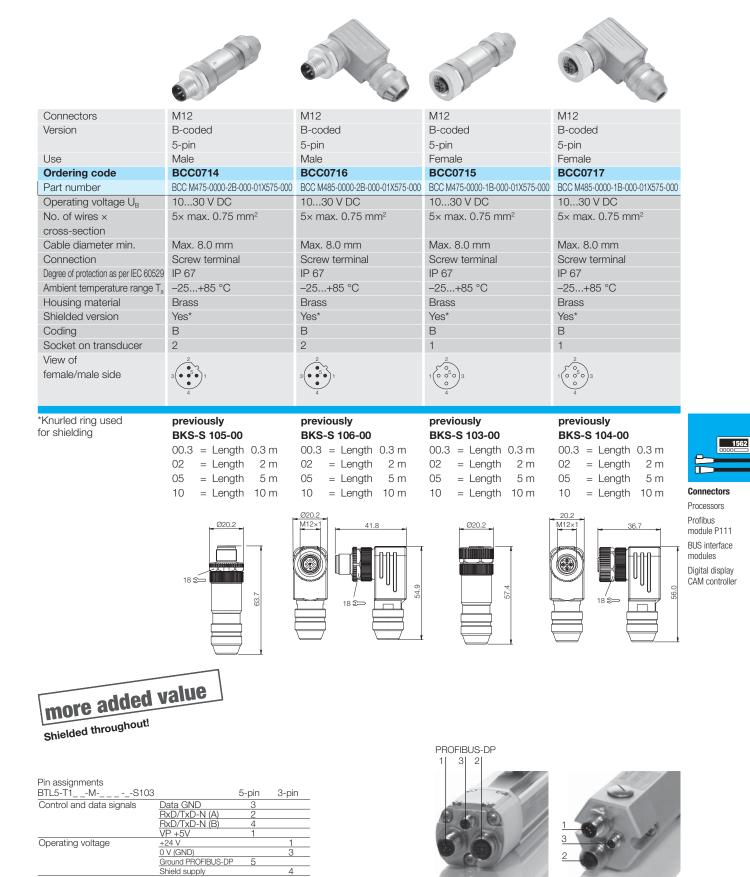
			•
Connector	1×M8 straight/2×3-wire		
Description	Y connector	M12 screw plug	M12 screw plug
Version	Male		
Use	Splitter boxes	IP 65 screw plug for	IP 65 screw plug for
		unused ports	unused ports
Ordering code		BAM0114	BAM00K7
Part number	BKS-S 75-TB4-05-PU-00.05/02/02	BKS 12-CS-01	BKS 12-CS-00
Operating voltage U <sub>B</sub>	1030 V DC		
No. of wires ×	4×0.34 mm <sup>2</sup>		
cross-section			
Cable diameter min.	max. 51 mm		
Connection	molded-in		
Degree of protection as per IEC 60529	IP 67		
Ambient temperature range T <sub>a</sub>	–25+85 °C	–20+80 °C	–20+80 °C
Housing material	PUR	Nickel-plated brass	Plastic
View of female/male side	3 4 PIN 1: brown PIN 2: white PIN 3: blue PIN 4: black		











1/2

З

Socket on

transducer

### Accessories M12 connectors, 5-pin, B-coded for PROFIBUS-DP

Connector diagrar	n and wiring		$5 \overset{3}{\underset{0}{\circ}} \overset{\circ}{\underset{0}{\circ}} \overset{4}{\underset{0}{\circ}} \overset{4}{\underset{1}{\bullet}} \overset{4}{\underset{2}{\bullet}} \overset{3}{\underset{2}{\bullet}} \overset{5}{\underset{2}{\circ}} \overset{1}{\underset{2}{\bullet}} \overset{\text{Inc}}{\underset{1}{\bullet}} \overset{\text{Inc}}{\underset$	$5 \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 2 \end{pmatrix} \begin{pmatrix} 1 & \text{NC} \\ 2 & \text{Line A green} \\ 3 & \text{NC} \\ \hline 4 & \text{Line B red} \\ \hline 5 & \text{NC} \\ \hline \end{pmatrix}$
Configuration				
Version				
Use			Female/male	Female
Operating voltage	U <sub>R</sub>		300 V	300 V
Cable	D		PUR	PUR
No. of wires × con	ductor cros	s-section	2×0.38 mm <sup>2</sup>	2×0.38 mm <sup>2</sup>
Degree of protection	on as per IE	C 60529	IP 67	IP 67
Ambient temperat	•		–25+80 °C	–25+80 °C
Housing material	and renige ra		PUR	PUR
Knurled coupling r	ina		Nickel-plated brass	Nickel-plated brass
Coding			B	B
Socket on transdu	Icer		- 1/2	1
			=	
Cable material	Color	Length	Ordering code	
			Part number	
PUR	Violet	0.6 m	BCC070M	
			BCC M415-M415-3B-329-PS72N1-006	
PUR	Violet	1 m	BCC070N	
			BCC M415-M415-3B-329-PS72N1-010	
PUR	Violet	2 m	BCC070P	BCC070Y
			BCC M415-M415-3B-329-PS72N1-020	BCC M415-0000-1B-031-PS72N1-020
PUR	Violet	5 m	BCC070R	BCC070Z
			BCC M415-M415-3B-329-PS72N1-050	BCC M415-0000-1B-031-PS72N1-050
PUR	Violet	10 m	BCC070T	BCC0710
			BCC M415-M415-3B-329-PS72N1-100	BCC M415-0000-1B-031-PS72N1-100
PUR	Violet	15 m	BCC070U	
			BCC M415-M415-3B-329-PS72N1-150	
PUR	Violet	20 m	BCC070W	
			BCC M415-M415-3B-329-PS72N1-200	
PUR	Black	2 m		
PUR	Black	5 m		
PUR	Black	10 m		







Pin assignments BTL5-T1MS103	3	5-pin	3-pin
Control and data signals	Data GND	3	
0	RxD/TxD-N (A)	2	
	RxD/TxD-N (B)	4	
	VP +5V	1	
Operating voltage	+24 V		1
	0 V (GND)		3
	Ground PROFIBUS-DP	5	
	Shield supply		4
Socket on		1/2	3
transducer		1/2	3

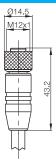
previo	usl	y BKS-S1	03/GS103-CP-	
00.3	=	Length	0.3 m	
02	=	Length	2 m	
05	=	Length	5 m	
10	=	Length	10 m	

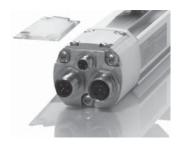


Ø14.5

M12x1

# previously BKS-S103-CP-\_\_ 00.3 = Length 0.3 m 02 = Length 2 m 05 = Length 5 m 10 = Length 10 m

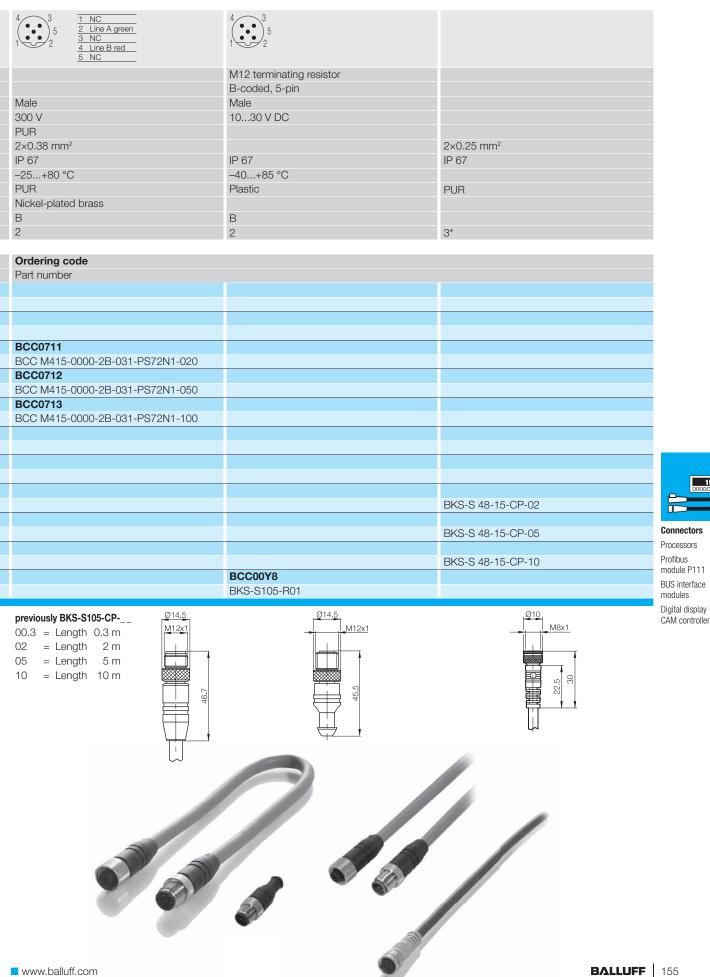




Please order the clear view cover separately! Order designation: BTL5-A-CP01-K

#### 154 **BALLUFF**

Accessories M12 connectors, 5-pin, B-coded for PROFIBUS-DP



1562

### Accessories

M12 female straight and right-angle connectors, 8-pin, customized assembly

## CE

Connectors	BKS-S115-PU	BKS-S116-PU
for series	BTL6S115	BTL6S115
Version	8-pin, straight, female	8-pin, right-angle, female
Part number	BKS-S115-PU	BKS-S116-PU
Screw terminal		
Housing material	PUR	PUR
Contacts	Brass	Brass
Contact finish	0.8 µm gold plated	0.8 µm gold plated
Degree of protection as per IEC 60529	IP 67	IP 67
Knurled coupling ring	Brass	Brass
Finish	2.5 µm Ni	2.5 μm Ni
O-ring	Viton	Viton
Cable	Molded PUR	Molded PUR
No. of wires × conductor cross-section	8×0.25 mm2	8×0.25 mm2
Version	LIYY-CF11Y	LIYY-CF11Y
Conductor configuration	14 × 0.15 mm	14 × 0.15 mm
Outer diameter	6.6 ±0.2 mm	6.6 ±0.2 mm
Min. bending radius	dynamic 4 $\times$ D, static 3 $\times$ D	dynamic 4 $\times$ D, static 3 $\times$ D
Pin assignments	. 5	5 .
View of female	4006	40006
view of leffiale	$3(\overset{\circ}{\circ}\overset{\circ}{\circ}\overset{\circ}{\circ}\overset{\circ}{\circ})_7$	$3\left(\begin{array}{c} 0 & 0 \\ 0 & 0 \end{array}\right) 7$
	8	28
	PIN Color	PIN Color 1 YE
	1 YE 2 GY 3 PK 4 RD 5 GN	
	3 PK	2 GY 3 PK
	4 RD 5 GN	4 RD 5 GN
	6 BU	6 BU
	7 <u>BN</u> 8WH	7 BN 8 WH
Please include the type		
designation in the ordering code!	<u>M12x1</u>	<u> </u>
02 = Length 2 m		
05 = Length 5 m		<b>+</b> ∰ <u>+</u>  − ∰ <u>→</u>
10 = Length 10 m		
15 = Length 15 m		
20 = Length 20 m		<u></u> <u> </u>
25 = Length 25 m		
J. J		ų Ψ
	I	
ll a		and the
	-	and the second second
	-	water in training (4
	-	Tel lines in the course of
	-	Incomplete A Discontinue of the owner of
	-	1300012E A Tanan and Common CE
	-	1300UEA Indext on the CE
	-	13000UE A Tanta the States CE
	-	100001EA Townson to CE
	-	
	-	Adapter BKS-S115 to
		Adapter BKS-S115 to
		Adapter BKS-S115 to BKS-S 32
		Adapter BKS-S115 to BKS-S 32 Ordering code:

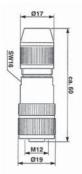
Accessories

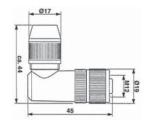
M12 female straight and right-angle connector, 8-pin, customized assembly for AT VARAN profile series



BCC04MC BCC M478-0000-1A-000-43X834-000

BCC050F BCC M488-0000-1A-000-43X834-000





Connectors

Processors Profibus module P111 BUS interface modules Digital display CAM controller



Series		BTA-A	BTA-C	BTA-E	
Output signal	Travel signal	analog	analog	analog	
	Velocity	analog	analog	analog	
Input interface (transducer)		Ρ	Ρ	Ρ	
Part number		BTA-A1	BTA-C1	BTA-E1	
Features		Resolution 0.1 mV/0.2 µA, LED function indicator, End point adjust 15 %, Span adjust 15 %, Velocity output, Error output (relay)	Resolution 0.1 mV/0.2 µA, LED function indicator, End point adjust 15 %, Span adjust 15 %, Velocity output, Error output (relay)	Resolution 0.1 mV/0.2 µA, LED function indicator, End point adjust 15 %, Span adjust 15 %, Velocity output, Error output (relay)	
Nominal stroke	of transducer	505500 mm	505500 mm	505500 mm	
Housing		Edge connector, 32-pin, DIN 41612 F, 19" plug-in card	Edge connector, 32-pin, DIN 41612 F, 19" plug-in card	Edge connector, 32-pin, DIN 41612 F, 19" plug-in card	
Operating voltage	ge	2028 V DC			
Current consumption		130 mA at 24 V DC	130 mA at 24 V DC	130 mA at 24 V DC	
Operating temperature		060 °C	060 °C	060 °C	
Update time for standard		1 kHz	1 kHz	1 kHz	
Interface		analog voltage	analog voltage, current	analog voltage, current	
Output signals	Travel signals	analog 010 V and 100 V	analog 010 V and 100 V, 020 mA	analog 010 V and 100 V, 420 mA	
	Velocity	analog ±10 V at ±2.5 m/s	analog ±10 V at ±2.5 m/s	analog ±10 V at ±2.5 m/s	
Accessories (please order se	eparately)	Card holder 48-pin Form F/627164	Card holder 48-pin Form F/627164	Card holder 48-pin Form F/627164	

#### Features:

- The processors are configured in a Eurocard format for use in 19" racks and card holders / top-hat rail fitting
- The position values are updated at a frequency of max. 2 kHz, so that the actual position can be captured even at high traverse speeds with negligible lag error
- High resolution (down to 0.01 mm) provided by microcontroller-controlled digitizing
- Parallel data format selectable binary, BCD or gray.
- Data format SSI (only BTM-H)
- Noise-immune data transmission between processor and transducer provided by RS485/422 differential line drivers, with cable lengths up to 500 m.
- ERROR output for immediate notification of cable break, defective or missing magnet.



#### Micropulse analog processor Please enter the code for the output signal and nominal stroke in the ordering code!

Micropulse digital processor

Please enter the code for the output signal and nominal stroke

in the ordering code!



30.1 (6TE) BALLUFF Analog Unit O Power O Error O Zero O Gain BTA

Nominal stroke

Transducer in [mm]

Ordering examples: **BTA-A1\_-**\_\_\_

#### Output signal

- 0 Rising, use only for current output
- 7 Falling, use only for current output
- 1 Rising/falling, use only for voltage output

#### BTM-H1-\_\_\_

#### Output driver

- 240 Source driver (PNP with SCP, 10...30 V) and 24-bit synchronous serial data transmission (SSI)
- 340 TTL outputs tri-state and24-bit synchronous serial data transmission (SSI)

#### 158 BALLUFF

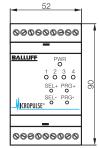
Accessories

Analog and digital processors, analog module

	nalog	and the second	
	lalog	digital	analog
a	nalog		analog
P	)	Ρ	Ρ
B	STA-G1	BTM-H1	BTM1
F	Resolution 0.1 mV/0.2 µA,	Resolution 0.01 mm, 0.025 mm, 0.1 mm,	Resolution 16 bits
L	ED function indicator,	1 mm, BCD, binary, gray code, null point	Up to 4 magnets on a single transducer can
E	nd point adjust 15 %,	adjustment, direction signal, DATA READY,	be processed individually. Analog
S	span adjust 15 %,	min./max. programming, ENABLE, DATA	velocity output. 100 % programmable
V	elocity output,	HOLD, bus-compatible, ERROR output.	measuring range,
E	rror output (relay)	Replaces processors:	ERROR output
		BTA-D, BTA-H, BTA-P	
5	05500 mm	505500 mm	254000 mm
E	dge connector, 32-pin,	Plastic housing for mounting on standard	Plastic housing for mounting on standard
D	IN 41612 F, 19" plug-in card	top-hat rail EN 50022-35	top-hat rail EN 50022-35
1	30 mA at 24 V DC	max. 500 mA	max. 300 mA
0	60 °C	060 °C	070 °C
1	kHz	2 kHz	2 kHz
a	nalog	digital 22 bit parallel BCD, binary, gray code,	analogue, voltage or current
V	oltage	24 bit synchronous serial (SSI) gray code	see ordering code
а	nalog	Digital TTL 5 V DC (BTM-H1-340)	Analog, voltage or current
-	10+10 V and +1010 V	PNP source driver, 24 V DC (BTM-H1-240)	see ordering code
а	nalog		analog ±10 V programmed to 1000 mm/s,
±	10 V at ±2.5 m/s		adjustable over the range 50 mm/s10 m/s
С	Card holder		
4	8-pin		
F	orm F/627164		

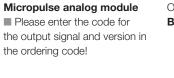


BALLUFF         30         31         31         32         20           BTM-H1-240         C €         MCR0PULSE*         The H1-240         C €           Program         Program         Program         Program         The H1-240         C €           Program         Program         Program         Program         Program         Program	06
2 4 6 8 10 12 14 16 18 20 22 24 1 3 5 7 9 11 13 15 17 19 21 23	
ŎŎŎŎŎŎŎŎŎŎŎ	





Connectors **Processors** Profibus module P111 BUS interface modules Digital display CAM controller



Ordering BTM1-	examples: 		
o	utput signal	Vers	sions
A	010 V, 100 V -1010 V, 1010 V 420 mA, 204 mA	101 102 103	1 analog output, 1 magnet 2 analog outputs, 2 magnets 3 analog outputs, 3 magnets
	020 mA, 200 mA	104	4 analog outputs, 4 magnets
	102-VM1000	ns	Velocity

A E 2 analog outputs, 1 magnet with velocity

±10 V at a velocity of 1000 mm/s



P111 Profibus modules are an elegant, cost-effective solution from Balluff.

The modules have a robust metal housing that was designed for use in harsh industrial environments and is capable of withstanding powerful mechanical loads. These modules are fitted with four interdependent ports for Micropulse transducers BTL with P111 or M1 pulse interfaces. A maximum of 16 magnets can be used per BTL port. The maximum nominal stroke is 7500 mm. Four additional ports can be configured with digital or analog sensors, depending on the version.

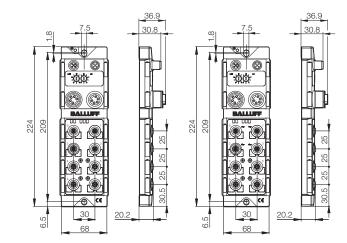
You can achieve maximum functionality and cost efficiency for fieldbus integration by combining Micropulse transducers BTL with Profibus modules P111.

PRQFT naba CE



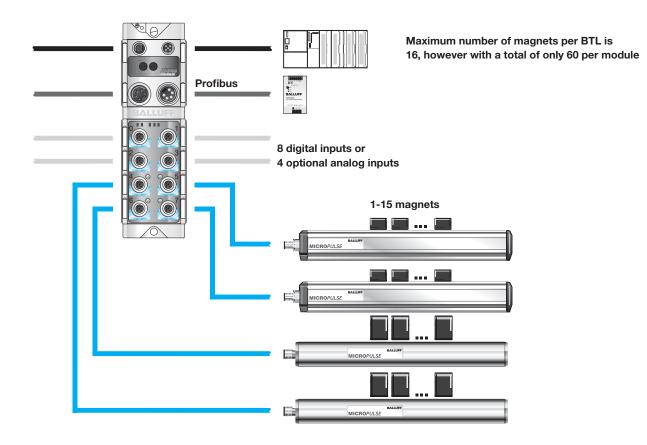


Fieldbus	Profibus	Profibus
Version	4× P111 or M1	4× P111 or M1
Ordering code	BNI001A	BNI002H
Part number	BNI-PBS-551-000-Z001	BNI-PBS-552-000-Z001
Operating voltage U <sub>B</sub>	1830 V DC	1830 V DC
Function indicator	BUS RUN	BUS RUN
Fault function indicator	Red LED	
Power indicator	$U_A$ , $U_S$ , undervoltage	$U_A$ , $U_S$ , undervoltage
Connection: Fieldbus	M12, B-coded	M12, B-coded
Connection: Operating voltage	7/8", 5-pin, female and male	7/8", 5-pin, female and male
Connection: I/O ports	M12, A-coded, 5-pin, female	M12, A-coded, 5-pin, female
Connection: P111 port	M12, A-coded, 8-pin, female	M12, A-coded, 8-pin, female
No. of I/O ports	8	8
No. of digital inputs	8	
No. of analog inputs		4
Outputs	0	0
No. of P111 inputs	4	4
max. load current sensors/channel	1 A	1 A
Port status indicator (signal status)	Yellow LED	Yellow LED
Port diagnostic indicator (overload)	Red LED	Red LED
Total current U <sub>Sensor</sub>	9 A	9 A
Degree of protection as per IEC 60529	IP 67 (when attached)	IP 67 (when attached)
Operating temperature T <sub>a</sub>	0+55 °C	0+55 °C
Weight	approx. 735 g	approx. 735 g
Mounting	2 mounting holes	2 mounting holes
Dimensions (L×W×H)	224×68×36.9	224×68×36.9
Housing material	Nickel-plated GD-Zn, matt finish	Nickel-plated GD-Zn, matt finish



All modules include 4 screw plugs and 1 label set.

Accessories Profibus modules P111 for BTL





Connectors Processors **Profibus** module P111 BUS interface modules Digital display CAM controller



#### WAGO digital pulse interface 750-635 for BTL5-P1-\_\_ or BTL6-P1\_\_-

The digital pulse interface was developed for connecting Micropulse transducers (BTL5-P1-...). Die RS422 interface assures quick and noise-immune transmission of signals with a resolution down to 1 $\mu$ m. The absolute position of the Micropulse transducer is sent to the supervisory controller as a 24-bit value.

The controller can perform a null point offset and configure the number of magnets.

The bus terminal with digital pulse interface can be operated by all bus drivers of the WAGO-I/O-SYSTEM 750, except the Economy variants.

#### Interfaces:

- InterBus
- PROFIBUS-DP
- CANopen
- DeviceNet
- Ethernet TCP/IP
- MODBUS
- CC Link

Resolution: 1 µm Number of magnets configurable (1...4)

Further technical details and orders from:

#### WAGO

Kontakttechnik GmbH Hansastraße 27 32423 Minden Phone +49 571 887-0 Fax +49 571 887-169 E-mail: info@wago.com www.wago.com

#### Phoenix Contact IMPULSE-IN terminal for BTL5-P1-\_\_ or BTL6-P1\_\_-

The IB IL IMPULSE-IN is a terminal from the Inline product family by Phoenix Contact and processes the Micropulse transducer with pulse interface.

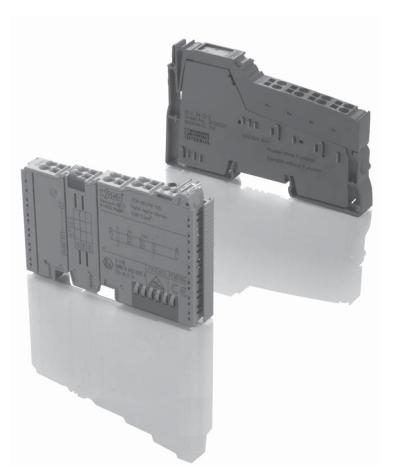
The IMPULSE-IN terminal enables particularly cost-effective solutions because it senses the positions using the low-cost pulse interface. In addition, the pulse interface has the advantage of real-time capability, making it especially suitable for applications with position or bearing control.

Interfaces:

- InterBus
- PROFIBUS-DP
- CANopen
- DeviceNet
- Ethernet

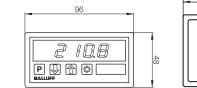
Further technical details and orders from:

Phoenix Contact GmbH & Co. KG Flachsmarktstraße 8 32823 Blomberg Phone +49 5235-300 Fax +49 5235-341200 E-mail: info@phoenixcontact.com www.phoenixcontact.com



## Accessories Digital display, CAM controller

Digital display for analog input signalsDigital display for BTL5-P with for BD-CC 08-1-P BDD-CC 08-1-P BDD-CC 08-1-P BDD-CC 08-1-P BDD-CC 08-1-P BDD-CC 08-1-P BDD-CC 08-1-P solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution solution <br< th=""></br<>
Current/voltageP InterfaceSSD interfaceP InterfaceSSD interfacePart numberBDD-UM 3023BDD-AM 10-1-PBDD-AM 10-1-SSDBDD-CC 08-1-PBDD-CCFeatures- 4-digit display with prefix - LED display 14 mm high red 7-segment- Seven 1/2-digit display with prefix- 8 programmable outputs - 8 directional switching p possibleFeatures- 4-digit display 14 mm high red 7-segment- Seven 1/2-digit display with prefix- 8 programmable outputs - 8 directional switching p possibleFeatures- 4-digit display 14 mm high red 7-segment- Seven 1/2-digit display with prefix- 8 programmable outputs - 8 directional switching p possibleFeatures- 4-digit display 14 mm high red 7-segment- Seven 1/2-digit display 14 mm high red 7-segment- 8 directional switching p on frost panelPorgrammable decimal point setting- 12-bit AC/DC converter - Measuring range selection - Voltage input 0-10V - Current input 0/4-20 mA - Scalable display range- 2 programmable relay outputs, defined as - Limit switch/comparator- 300 switching points can be distributed over on 15 programs - Adjustable null point offs
Part number       BDD-UM 3023       BDD-AM 10-1-P       BDD-AM 10-1-SSD       BDD-CC 08-1-P       BDD-CC         Features       - 4-digit display with prefix       - Seven 1/2-digit display with prefix       - Seven 1/2-digit display with prefix       - 8 programmable outputs         - LED display 14 mm high red       - Seven 1/2-digit display with prefix       - 8 directional switching propossible         - Programmable decimal point       - LED display 14 mm high red       - Scalable units       - LED display, 14 mm high red         - 12-bit AC/DC converter       - Variable decimal point       - Adjustable null point       - LEDs for switching point         - Weasuring range selection       - Adjustable null point       - Operating voltage 1032 V       - 300 switching points         - Scalable display range       - Limit switch/comparator       - 2 programmable relay outputs,       - Adjustable null point offs
Features- 4-digit display with prefix - LED display 14 mm high red 7-segment- Seven 1/2-digit display with prefix- 8 programmable outputs - 8 directional switching p possible- Programmable decimal point setting- LED display 14 mm high red 7-segment- 12-bit AC/DC converter - Measuring range selection - Voltage input 0-10V - Current input 0/4-20 mA - Scalable display range- Seven 1/2-digit display with prefix - LED display 14 mm high red 7-segment - Variable decimal point setting - Adjustable null point - 2 programmable relay outputs, defined as - Limit switch/comparator- 8 programmable outputs - 8 directional switching p possible- IED display 14 mm high red - Scalable display range- Seven 1/2-digit display with prefix - Seven 1/2-digit display with - 8 directional switching p onsible- LED display 14 mm high red - LED display, 14 mm high resegment - LED display 14 mm high red - Scalable units - 2 programmable decimal point - 2 programmable relay outputs, defined as - Limit switch/comparator- 8 directional switching p on front panel - 300 switching points can be distributed over or 15 programs
<ul> <li>LED display 14 mm high red 7-segment</li> <li>LED display, 14 mm high 7-segment, 6-digit</li> <li>12-bit AC/DC converter</li> <li>Variable decimal point setting</li> <li>LEDs for switching point on front panel</li> <li>Voltage input 0-10V</li> <li>Operating voltage 1032 V</li> <li>Scalable display range</li> <li>Limit switch/comparator</li> <li>Adjustable null point</li> </ul>
<ul> <li>2-position controller</li> <li>1 configurable input</li> <li>External null set</li> <li>Latch display value</li> <li>Isolated DIN housing for mounting in front panel (mounting hardware included)</li> <li>Isolated DIN housing for mounting in front panel (mounting hardware included)</li> </ul>





Housing depth 110 mm

⇔∔↑

789 456 123 10 ⊕±0C

Housing depth 110 mm



Connectors Processors Profibus module P111 BUS interface modules Digital display CAM controller



## Alphanumeric Directory BAM to BTL

Part number	Ordering code	Page	Part number	Ordering code Page
BAM MC-XA-006-D38.1-5		146	BTL5MH	105
BAM SE-XA-002-D38.1-S		146	BTL5MHB/WB	109
BAM-AD-XA-003-D38.1-5		146	BTL5MK	103
BCC M415-0000-1B-031-PS72N1-020	BCC070Y	154	BTL5MW	107
BCC M415-0000-1B-031-PS72N1-050	BCC070Z	154	BTL5MSF-F	143
BCC M415-0000-1B-031-PS72N1-100	BCC0710	154	BTL5MJ-DEXC-TA12	133
BCC M415-0000-2B-031-PS72N1-020	BCC0711	155	BTL51-MDEX	131
BCC M415-0000-2B-031-PS72N1-050	BCC0712	155	BTL5-A11-M	111
BCC M415-0000-2B-031-PS72N1-100	BCC0713	155	BTL5-A11-MP	33
BCC M415-M415-3B-329-PS72N1-006	BCC070M	154	BTL5-A11-MSF	145
BCC M415-M415-3B-329-PS72N1-010	BCC070N	154	BTL5-C1M	111
BCC M415-M415-3B-329-PS72N1-020	BCC070P	154	BTL5-C1MP	33
BCC M415-M415-3B-329-PS72N1-050	BCC070R	154	BTL5-C1MSF	145
BCC M415-M415-3B-329-PS72N1-100	BCC070T	154	BTL5-D1MP-S93	41
BCC M415-M415-3B-329-PS72N1-150	BCC070U	154	BTL5-E1_0-M	77
BCC M415-M415-3B-329-PS72N1-200	BCC070W	154	BTL5-E1M	111
BCC M475-0000-1B-000-01X575-000	BCC0715	153	BTL5-E1MP	33
BCC M475-0000-2B-000-01X575-000	BCC0714	153	BTL5-E1MSF	145
BCC M478-0000-1A-000-43X834-000	BCC04MC	157	BTL5-F1_0-MS115	95
BCC M485-0000-1B-000-01X575-000	BCC0717	153	BTL5-F-2814-1S	47
BCC M485-0000-2B-000-01X575-000	BCC0716	153	BTL5-F-2814-1S	55
BCC M488-0000-1A-000-43X834-000	BCC050F	157	BTL5-G11-M	111
BDD-AM 10-1-P		163	BTL5-G11-MP	33
BDD-AM 10-1-SSD		163	BTL5-G310-MA1-S115	59
BDD-CC 08-1-P		163	BTL5-H1M	89
BDD-CC 08-1-SSD		163	BTL5-H1M	91
BDD-UM 3023		163	BTL5-H1M	117
BIW1-A310		71	BTL5-H1MP-S92	39
BIW1-C310		71	BTL5-H1MP-S94	39
BIW1-E310		71	BTL5-M1-M	85
BIW1-G310		71	BTL5-M1-MP	35
BKS 12-CS-00	BAM00K7	152	BTL5-M-2814-1S	46
BKS 12-CS-01	BAM0114	152	BTL5-M-2814-1S	54
BKS-S 32M		148	BTL5-N-2814-1S	46
BKS-S 32M		149	BTL5-N-2814-1S	54
BKS-S 32M-C		149	BTL5-P1-M	85
BKS-S 75-TB4-05-PU-00,05/02/02		152	BTL5-P1-M	113
BKS-S 78M-00		149	BTL5-P1-MP	35
BKS-S 92-00		150	BTL5-P-3800-2	45
BKS-S 92-16/GS92		151	BTL5-P-3800-2	53
BKS-S 92-TA1		151	BTL5-P-4500-1	45
BKS-S 93-00		150	BTL5-P-4500-1	53
BKS-S 94-00		150	BTL5-P-5500-2	45
BKS-S 94-R01		151	BTL5-P-5500-2	53
BKS-S 95-00		150	BTL5-S1B-M	87
BKS-S105-R01	BCC00Y8	155	BTL5-S1B-M	115
BKS-S115-PU		156	BTL5-S1B-MP	37
BKS-S116-PU		156	BTL5-S1M	87
BKS-S137-19-PC		151	BTL5-S1M	115
BKS-S151-19-PC		151	BTL5-S1MP	37
BKS-S232-PU-		149	BTL5-T1_0-MS103	93
BKS-S233-PU		149	BTL5-T1_0-MP-S 103	43
BNI-PBS-551-000-Z001	BNI001A	160	BTL5-T-2814-1S	55
BNI-PBS-552-000-Z001	BNI002H	160	BTL6MA1-S115	57
BTA-A1	2	158	BTL6-A110-M -A1-S115	59
BTA-C1		158	BTL6-A301-MA1-S115	57
BTA-E1		158	BTL6-A301-MA1-S115	61
BTA-G1		159	BTL6-A-3800-2	67
BTL2-GS10A		47	BTL6-A-3801-2	67
BTL2-GS10A		55	BTL6-A500-M	121
BTL2-GS10A BTL2-S-3212-4Z		96	BTL6-A500-M	51
BTL2-S-3212-42 BTL2-S-4414-4Z		96 96	BTL6-B500-M	121
BTL2-S-5113-4K				
		96 96	BTL6-C500-MPF-S115	51
BTL2-S-6216-8P		90	BTL6-E500-M	121



BTL6-E500-MPF-S115       51         BTL6-G500-MPF-S115       51         BTL6-P11MA1-S115       63         BTL6-V11V-MA1-S115       65         BTL7-A110-MM1-S115       65         BTL7-A110-MM1-S115       65         BTL7-C1_0-MM1-S115       77         BTL7-C1_0-MS       77         BTL7-F101-MS       79         BTL7-G110-MS       77         BTL-P-1012-4R       97         BTL-P-1012-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4S       97         BTL-S-3112-4Z       146         BTM- 1 -       159	Part number		Ordering code	Page
BTL6-P11MA1-S115       63         BTL6-P510-MM1-S115       65         BTL6-V11V-MA1-S115       65         BTL7-A110-MM1-S115       67         BTL7-A501-MM1-S115       77         BTL7-C1_0-MM1-S115       79         BTL-P-1012-4R       97         BTL-P-1012-4R-PA       97         BTL-P-1013-4R       97         BTL-P-1013-4S       97         BTL-P-1014-2R       97         BTL-S-3112-4Z       146	BTL6-E500-M	PF-S115		51
BTL6-P510-M       123         BTL6-V11V-MA1-S115       65         BTL7-A110-M       77         BTL7-A501-M       79         BTL7-C1_0-M       77         BTL7-G110-M       79         BTL7-G110-M       77         BTL7-G110-M       77         BTL7-G110-M       77         BTL7-P1012-4R       97         BTL-P-1012-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4S       97         BTL-P-1014-2R       97         BTL-P-1014-2R       146	BTL6-G500-M	PF-S115		51
BTL6-V11V-MA1-S115       65         BTL7-A110-MM.       77         BTL7-A501-MM.       79         BTL7-C1_0-MM.       77         BTL7-C1_0-MM.       77         BTL7-C1_0-MM.       77         BTL7-G110-MM.       77         BTL7-G110-MM.       77         BTL-P-0814-GR-PAF       97         BTL-P-1012-4R       97         BTL-P-1012-4R-PA       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4S       97         BTL-P-1014-2R       97         BTL-S-3112-4Z       146	BTL6-P11M	A1-S115		63
BTL7-A110-M       77         BTL7-A501-M       79         BTL7-C1_0-M       77         BTL7-E501-M       79         BTL7-G110-M       77         BTL7-G110-M       77         BTL-P-0814-GR-PAF       97         BTL-P-1012-4R       97         BTL-P-1012-4R-PA       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4R-PA       97         BTL-P-1013-4R       97         BTL-P-1013-4S       97         BTL-P-1014-2R       97         BTL-S-3112-4Z       146	BTL6-P510-M	_=		123
BTL7-A501-M	BTL6-V11V-M	A1-S115		65
BTL7-C1_0-M       77         BTL7-E501-M       79         BTL7-G110-M       77         BTL7-G110-M       77         BTL-P-0814-GR-PAF       97         BTL-P-1012-4R       97         BTL-P-1012-4R-PA       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4S       97         BTL-P-1014-2R       97         BTL-S-3112-4Z       146	BTL7-A110-M	_=		77
BTL7-E501-M       79         BTL7-G110-M       77         BTL-P-0814-GR-PAF       97         BTL-P-1012-4R       97         BTL-P-1012-4R-PA       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4R-PA       97         BTL-P-1013-4R       97         BTL-P-1013-4S       97         BTL-P-1014-2R       97         BTL-S-3112-4Z       146	BTL7-A501-M	_=		79
BTL7-G110-M       77         BTL-P-0814-GR-PAF       97         BTL-P-1012-4R       97         BTL-P-1012-4R-PA       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4S       97         BTL-P-1014-2R       97         BTL-S-3112-4Z       146	BTL7-C1_0-M	_=		77
BTL-P-0814-GR-PAF       97         BTL-P-1012-4R       97         BTL-P-1012-4R-PA       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4S       97         BTL-P-1014-2R       97         BTL-S-3112-4Z       146	BTL7-E501-M			79
BTL-P-1012-4R       97         BTL-P-1012-4R-PA       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4R       97         BTL-P-1013-4S       97         BTL-P-1014-2R       97         BTL-S-3112-4Z       146	BTL7-G110-M			77
BTL-P-1012-4R-PA       97         BTL-P-1013-4R       97         BTL-P-1013-4R-PA       97         BTL-P-1013-4S       97         BTL-P-1014-2R       97         BTL-S-3112-4Z       146	BTL-P-0814-GR-PA	F		97
BTL-P-1013-4R       97         BTL-P-1013-4R-PA       97         BTL-P-1013-4S       97         BTL-P-1014-2R       97         BTL-S-3112-4Z       146	BTL-P-1012-4R			97
BTL-P-1013-4R-PA     97       BTL-P-1013-4S     97       BTL-P-1014-2R     97       BTL-S-3112-4Z     146	BTL-P-1012-4R-PA			97
BTL-P-1013-4S         97           BTL-P-1014-2R         97           BTL-S-3112-4Z         146	BTL-P-1013-4R			97
BTL-P-1014-2R         97           BTL-S-3112-4Z         146	BTL-P-1013-4R-PA			97
BTL-S-3112-4Z 146	BTL-P-1013-4S			97
	BTL-P-1014-2R			97
BTM-1 - 159	BTL-S-3112-4Z			146
	BTM1			159
BTM-H1 159	BTM-H1			159

## Sales and Logistics Services

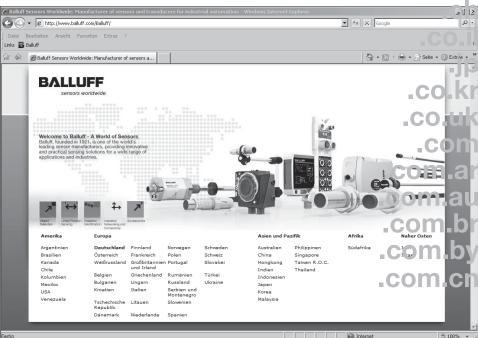
Convenient online access to the latest information

## Global online availability of the latest product information

Our Sales and Logistics Services offer you the latest

- Data sheets
- CAD drawings in 2D or 3D
- Catalogs
- Brochures
- Manuals
- Software descriptions
- Operating manuals
- FAQs

- Worldwide addresses and much more.



.at

.be

.ca

.com.hk

.pl .se

## www.balluff.com

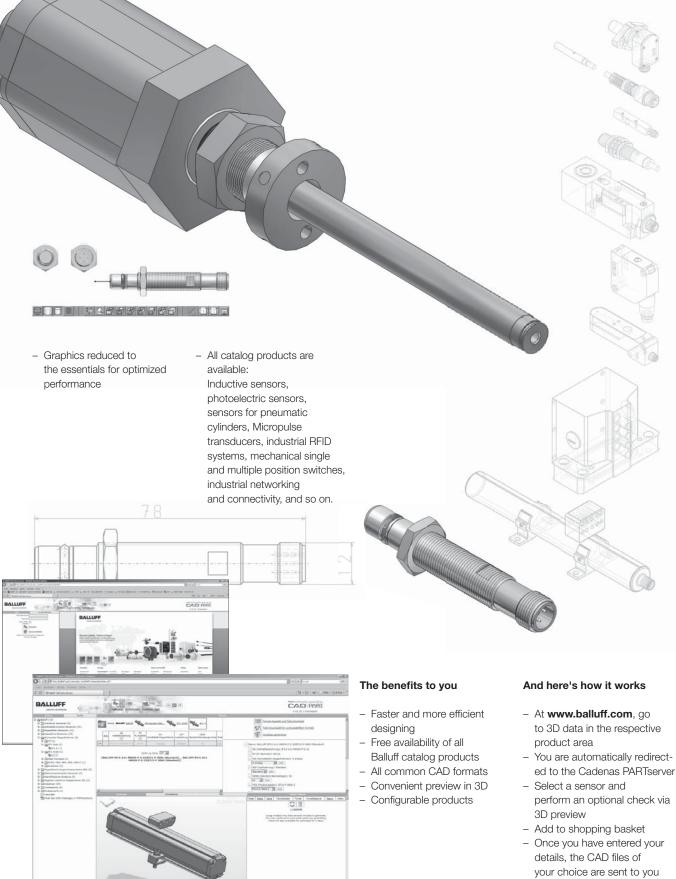


#### .ru 70 .com.sg .com.tr 45 (LED) .CZ 40.5 .de \$10.7 .dk V .es M12x1 A M12x1 .fr .gr .hu .it =317 .nl .no

BALLUFF

## Sales and Logistics Services

Retrieve product information online in 3D



MegaCAF

I-deas" CATIA

Propose designer



DS.

Mastercam

t St

DPTC

by e-mail

DXF

CADdy

HiCAD neXt

## Vorldwide Sales

#### **Headquarters**

#### Germany

Balluff GmbH Schurwaldstrasse 9 73765 Neuhausen a.d.F. Phone +49 7158 173-0 Fax +49 7158 5010 balluff@balluff.com

#### Subsidiaries and Representatives

#### Argentina

Nortécnica S.R.L 103 - Heredia 638 B1672BKD Villa Lynch – San Martin Pcia. de Buenos Aires Phone +54 11 47573129 Fax +54 11 47571088 info@nortecnica.com.ar

#### Australia

Balluff-Leuze Pty. Ltd. 12 Burton Court Bayswater VIC 3153 Phone +61 397 204100 Fax +61 397 382677 sales@balluff.com.au

Austria Balluff GmbH Industriestraße B16 2345 Brunn am Gebirge Phone +43 2236 32521-0 Fax +43 2236 32521-46 sensor@balluff.at

#### Belarus

Automaticacentre OOO. Nezavisimosti Av. 185, Block 19, Office 3 220125 Minsk Phone +375 17 2181713 Fax +375 17 2181798 balluff@nsys.by

#### Belgium

Balluff byba Researchpark Haasrode 1820 Interleuvenlaan 62, 3001 Leuven Phone +32 16 397800 Fax +32 16 397809 info.be@balluff.be

#### Brazil

Balluff Controles Elétricos Ltda. Rua Francisco Foga, 25 Distrito Industrial CEP 13280.000 Vinhedo – Sao Paulo Phone +55 19 38769999 Fax +55 19 38769990 balluff@balluff.com.br

#### Bulgaria

BPS AG 41, Nedelcho Bonchev St. 1528 Sofia Phone +359 2 9609875 Fax +359 2 9609896 bps@bps.bg

#### Canada

Balluff Canada Inc. 2840 Argentia Road, Unit 2 Mississauga, Ontario L5N 8G4 Phone +1 905 816-1494 Toll-free 1-8 00-927-9654 Fax +1 905 816-1411 balluff canada@balluff ca

Chile Balluff Controles Elétricos Ltda.,

#### Brazil China

Balluff (Shanghai) Trading Co. Ltd. Room 337, Xinxing Building 2005 Yanggao Rd. North 200131 Shanghai Tel. +86 21 51698788, 50644131 Fax +86 21 50644131, 22818067 info@balluff.com.cn

#### Columbia

Balluff Controles Elétricos Ltda., Brazil

#### Croatia

HSTEC d.d. Zagrebacka 100 23000 Zadar Phone +385 23 205-405 Fax +385 23 205-406 info@hstec.hr

#### Czech Republic

Balluff CZ, s.r.o Pelušková 1400 198 00 Praha 9 – Kyje Phone +420 281 000 666 Fax +420 281 940066 obchod@balluff.cz

#### Denmark

Balluff ApS Åbogade 15 8200 Århus N Phone +45 70 234929 Fax +45 70 234930 info.dk@balluff.dk

#### Egypt

EGEC Taksym El Kodah-smouha 24 St. El Helal El Ahmer Alexandria Phone +20 3 4299771 Fax +20 3 4261773 info@egecgroup.com

#### Finland

Murri Pääkonttori Koukkukatu 1 15700 Lahti Phone +358 3 8824000 Fax +358 3 8824040 myynti@murri.fi

#### France Balluff SAS

ZI Nord de Torcy-Bat 3 Rue des Tanneurs - BP 48 77201 Marne La Vallée Cedex 1 Phone +33 1 64111990 Fax +33 1 64111991 info.fr@balluff.fr

#### Greece

S. NAZOS S.A. 10 KLM Thessalonikis-Kilkis P.O. Box 57008 Thessaloniki Phone +30 2310 462120 Fax +30 2310 474079 parasxos@nazos.gr

#### Hong Kong

Sensortech Company No. 43, 18th Street Hong Lok Yuen, Tai Po, NT Phone +852 26510188 Fax +852 26510388 sensortech@netvigator.com

#### Hungary

Balluff Elektronika Kft. Pápai út. 55. 8200 Veszprém Phone +36 88 421808 Fax +36 88 423439 saleshu@balluff.hu

#### India Balluff India

405 Raikar Chambers Deonar Village Road, Govandi, Mumbai 400088 Phone +91 22 67551646 Fax +91 22 67973257 balluff@balluff.co.in

#### Indonesia

PT. Multiguna Cemerlang Bumi Serpong Damai Sektor XI Multipurpose Industrial Building Block H 3-31 Serpong Tangerang 15314 Banten Phone +62 21 75875555 Fax +62 21 75875678 sales\_bsd@multigunacemerlang.com

#### Israel

Ancitech Ltd. 19, Hamashbir St. Industrial Zone Holon 58853 Holon Phone +972 3 5568351 Fax +972 3 5569278 moshe@ancitech.com

#### Italy

Balluff Automation S.R.L. Via Morandi 4 10095 Grugliasco, Torino Phone +39 11 3150711 Fax +39 11 3170140 info.italy@balluff.it

#### Japan

Balluff Co., Ltd. Ishikawa Bldg. 2nd Fl. 1-5-5 Yanagibashi, Taito-Ku Tokyo 111-0052 Tel. +81 03 5833-5440 Fax +81 03 5833-5441 info.jp@balluff.jp

#### Kazakhstan

elcos electric control systems 2A, Molodezhniy Str. 3D block O., offices 318-319 050061 Almaty Phone +7 727 3340536 Fax +7 727 3340539 info@elcos.kz

#### Lithuania

UAB Interautomatika Kęstučio 47 08127 Vilnius Phone +370 5 2607810 Fax +370 5 2411464 andrius@interautomatika It

#### Malaysia

Sumber Engineering (M) Sdn. Bhd. 20T 558 Jalan Subang 6 077 Persiaran Subang, Sungai Penaga Industrial Parc 47500 Subang Jaya, Selangor Phone +60 3 56334227 Fax +60 3 56334239 louis@sumbersarana.com

Team Automation Systems (M) Sdn. Bhd. No. 26, 1st Floor, Jalan TTC 23, Taman Teknologi Cheng, 75250 Melaka Phone +60 6 3366223 Fax +60 6 3368223 sales@teamtas.com.my

#### Mexico

Balluff de México S.A. de C.V. Prol. Av. Luis M. Vega #109 Col. Ampliación Cimatario C.P. 76030 Queretaro, Qro. Phone +52 442 2124882 Fax +52 442 2140536 balluff.mexico@balluff.com

#### Netherlands

Balluff B.V. Kempenlandstraat 11H 5262 GK Vught Phone +31 73 6579702 Fax +31 73 6579786 info.nl@balluff.nl

#### New Zealand

Balluff-Leuze Pty. Ltd., Australia

#### Norway

Primatec as Lillesandsveien 44 4877 Grimstad Phone +47 37 258700 Fax +47 37 258710 post@primatec.no

#### Philippines

Technorand Sales Corporation 803 Wilshire Annapolis Plaza, No. 11 Annapolis Street, San Juan, Metro Manila 1500 Phone +63 2 7245006 Fax +63 2 7245010 techno@compass.ph

#### Poland

Balluff Sp. z o.o. UI. Muchoborska 16 54-424 Wrocław Phone +48 71 3384929 Fax +48 71 3384930 balluff@balluff.pl

**Portugal** LA2P Lda. Rua Teofilo Braga, 156 A Escrit. F – Edificio S. Domingos Cabeco Do Mouro 2785-122 S. Domingos De Rana Phone +351 21 4447070 Fax +351 21 4447075 la2p@la2p.pt

#### Romania

East Electric s.r.l. 256 Basarabia Blvd. 030352 Bucuresti Phone +40 31 4016301 Fax +40 31 4016302 office@eastelectric.ro

### Worldwide Sales

Switzerland

Riedstrasse 6

8953 Dietikon

Taiwan

Thailand Compomax Co. Ltd. 16 Soi Ekamai 4,

Sukhumvit 63 Rd.

Bangkok 10110

Prakanongnua, Vadhana,

Phone +66 2 7269595

info@compomax.co.th

Turkey Balluff Sensor Otomasyon

Sanayi Ve Ticaret Ltd. Sti.

34381 Okmeydani/Istanbul

Phone +90 212 3200411

Fax +90 212 3200416

Perpa Ticaret Is Merkezi A Blok, Kat 1-2-3 No: 0013-0014

Fax +66 2 7269800

Balluff Sensortechnik AG

Phone +41 43 3223240

sensortechnik@balluff.ch

Fax +41 43 3223241

Canaan Electric Corp.

Phone +886 22 5082331

sales@canaan-elec.com.tw

Fax +886 22 5084744

6F-5, No. 63 Sec. 2 Chang An East Road 10455 Taipei

#### Russia

Balluff OOO M. Kaluzhskaja Street 15 Building 17, Office 500 119071 Moscow Tel. +7 495 78071-94 Fax +7 495 78071-97 balluff@balluff.ru

#### Serbia

ENEL d.o.o. UI. Vasilja Pavlovica 10 14000 Valjevo Phone +381 14 291161 Fax +381 14 244641 enelva@ptt.rs

#### Singapore

Balluff Asia Pte. Ltd. BLK 1004 Toa Payoh Ind. Park Lorong 8, #03-1489 Singapore 319076 Phone +65 62524384 Fax +65 62529060 balluff@balluff.com.sg

#### Slovakia

Balluff Slovakia s.r.o. Blagoevova 9 85104 Bratislava Phone +421 2 67200062 Fax +421 2 67200060 info@balluff.sk

#### Slovenia

Senzorji SB d.o.o., Proizvodnja, trgovina in storitve d.o.o. Livadna ulica 1 2204 Miklavž na Dravskem polju Phone +386 2 6290300 Fax +386 2 6290302 senzorji.sb@siol.net

#### Spain

Balluff S.L. Edificio Forum SCV Planta 5°, Oficina 4° Carretera Sant Cugat a Rubi Km01, 40-50 08190 Sant Cugat del Vallés Barcelona Phone +34 93 5441313 Fax +34 93 5441312 info.es@balluff.es

#### South Africa

PAL Distributers CC P.O. Box 211 Randburg, 2125 Johannesburg Phone +27 11 7814381 Fax +27 11 7818166 pal@polka.co.za

#### South Korea

Mahani Electric Co. Ltd. 792-7 Yeoksam-Dong Kangnam-Gu, Seoul Post code: 135-080 Phone +82 2 21943300 Fax +82 2 21943397 yskim@balluff.co.kr

#### Sweden

Balluff AB Industrivägen 2 43361 Sävedalen Phone +46 31 3408630 Fax +46 31 3409431 info.se@balluff.se

## balluff@balluff.com.tr

Micronlogistik Ltd UI. Promyischlennaya Street 37 65031 Odessa Phone +380 48 7781278 Fax +380 48 2358760 info@balluff-ua.com

#### United Kingdom and Ireland

Balluff Ltd. 4 Oakwater Avenue Cheadle Royal Business Park Cheadle, Cheshire SK8 3SR Phone +44 161 282-4700 Fax +44 161 282-4701 sales@balluff.co.uk

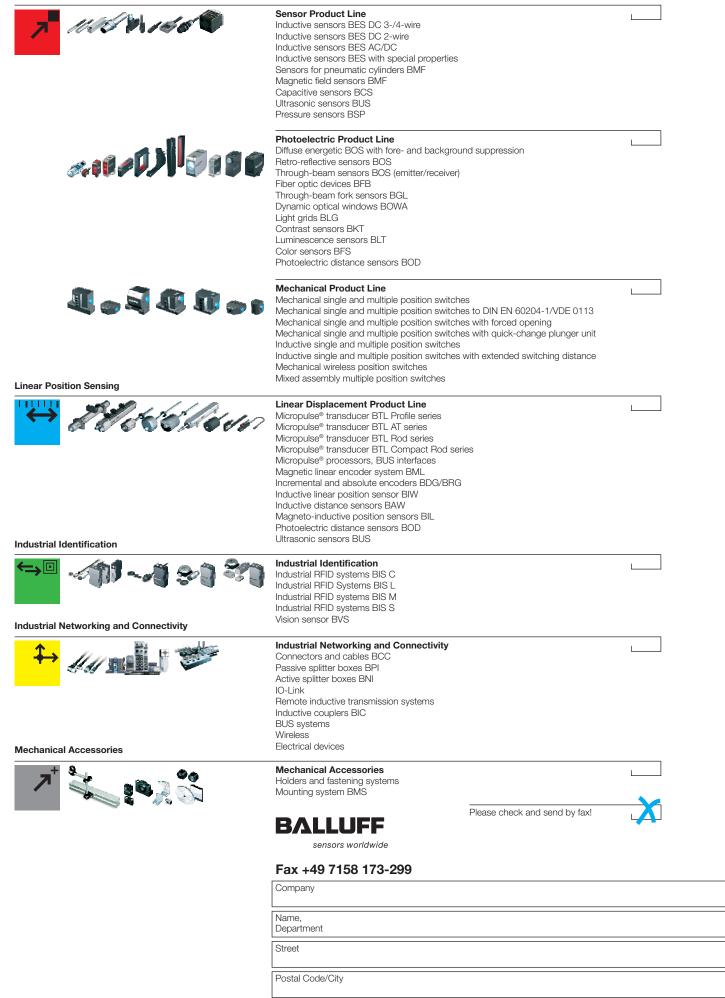
#### USA

Balluff Inc. 8125 Holton Drive Florence, KY 41042-0937 Phone +1 859 727-2200, Toll-free 1-800-543-8390 Fax +1 859 727-4823 balluff@balluff.com

#### Venezuela

Balluff Controles Elétricos Ltda., Brazil





Phone





**Object Detection** 



Linear Position Sensing



Industrial Identification



Industrial Networking and Connectivity



**Mechanical Accessories** 



Balluff GmbH Schurwaldstrasse 9 73765 Neuhausen a.d.F. Germany Phone +49 7158 173-0 Fax +49 7158 5010 balluff@balluff.de

## www.balluff.com