Digital universal particle concentration sensor

PMS5003 series data manual

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Main characteristics

◆ Zero false alarm rate

◆ Real-time response

◆ Correct data

◆ Minimum distinguishable particle diameter :0.3 micrometer

◆ High anti-interference performance because of the patent structure of six sides shielding

◆ Optional direction of air inlet and outlet in order to adapt the different design

Overview

PMS5003 is a kind of digital and universal particle concentration sensor, which can be used to obtain the number of suspended particles in the air, i.e. the concentration of particles, and output them in the form of digital interface. This sensor can be inserted into variable instruments related to the concentration of suspended particles in the air or other environmental improvement equipments to provide correct concentration data in time.

Working principle

Laser scattering principle is used for such sensor, i.e. produce scattering by using laser to radiate suspending particles in the air, then collect scattering light in a certain degree, and finally obtain the curve of scattering light change with time. In the end, equivalent particle diameter and the number of particles with different diameter per unit volume can be calculated by microprocessor based on MIE theory. Please find the functional diagram of each part of sensor from Figure 1 as follows.
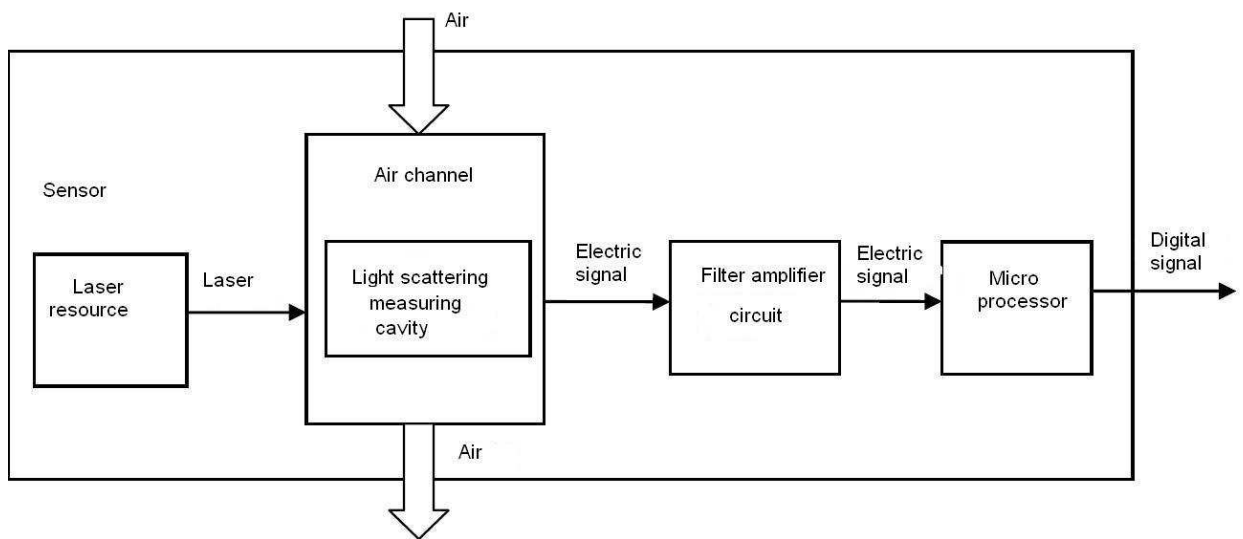
Figure 1 Functional block diagram of sensor

Technical Index

Parameter	Index	unit
Range of measurement	0.3~1.0；1.0~2.5；2.5~10	Micrometer（μm）
Counting Efficiency	50%@0.3μm 98%@>=0.5μm	
Effective Range（PM2.5 standard）	0~500	$\mu g/m^3$
Maximum Range（PM2.5 standard）*	≥1000	$\mu g/m^3$
Resolution	1	$\mu g/m^3$
Maximum Consistency Error (PM2.5 standard data)*	±10%@100~500$\mu g/m^3$ ±10$\mu g/m^3$ @0~100$\mu g/m^3$	
Standard Volume	0.1	Litre（L）
Single Response Time	＜1	Second（s）
Total Response Time	≤10	Second（s）
DC Power Supply	Typ:5.0 Min:4.5 Max: 5.5	Volt（V）
Active Current	≤100	Milliampere（mA）
Standby Current	≤200	Microampere（μA）
Interface Level	L <0.8 @3.3 H >2.7@3.3	Volt（V）
Working Temperature Range	-10~+60	℃
Working Humidity Range	0~99%	
Storage Temperature Range	-40~+80	℃
MTTF	≥3	Year（Y）
Physical Size	50×38×21	Millimeter（mm）

Note 1: Maximum range means that the highest output value of the PM2.5 standard data is not less than 1000.

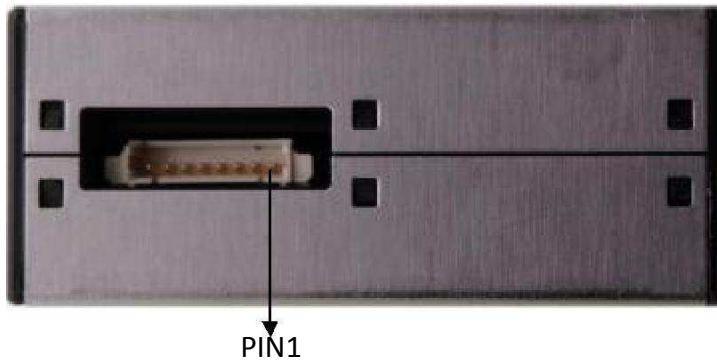Note 2:"PM2.5 standard data" is the "data2" in the appendix.

Pin Definition

PIN1

Figure 2   Connector Definition

PIN1	VCC	Positive power 5V
PIN2	GND	Negative power
PIN3	SET	Set pin /TTL level@3.3V，high level or suspending is normal working status, while low level is sleeping mode.
PIN4	RX	Serial port receiving pin/TTL level@3.3V
PIN5	TX	Serial port sending pin/TTL level@3.3V
PIN6	RESET	Module reset signal /TTL level@3.3V，low reset.
PIN7/8	NC	

Usually only pins 1, 2, 4 and 5 need to be connected.

Output result

Mainly output as the quality and number of each particles with different size per unit volume, the unit volume of particle number is 0.1L and the unit of mass concentration is μg/m^3 .

There are two options for digital output: passive and active. Default mode is active after power up. In this mode sensor would send serial data to the host automatically .The active mode is divided into two sub-modes: stable mode and fast mode. If the concentration change is small the sensor would run at stable mode with the real interval of 2.3s.And if the change is big the sensor would be changed to fast mode automatically with the interval of 200~800ms, the higher of the concentration, the shorter of the interval.
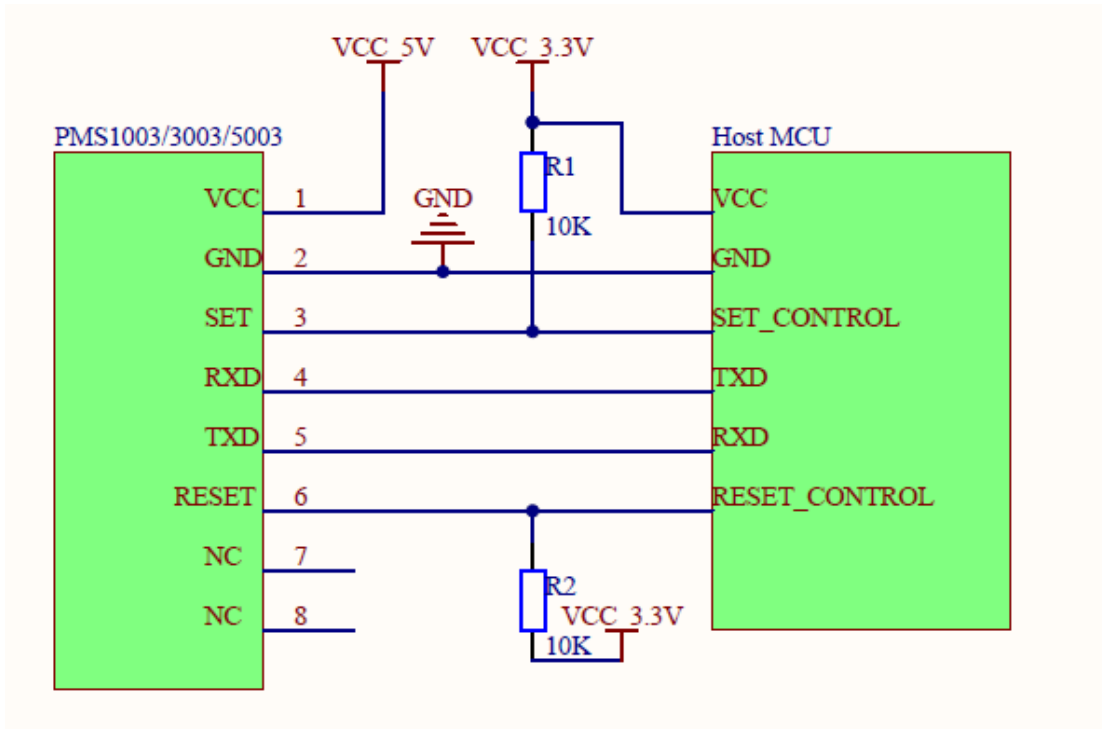
Typical Circuit

Figure 3   Typical Circuit

According to "Circuit Attentions" on page 10, SET and RESET should *not* be connected when not used! Additionally, they are supposed to have internal pull-up resistors. So why the extra pull-up resistors?

Typical Output Characteristic

Definition of axis Y: PM2.5 concentration , unit: μ g/m³
Definition of axis X: number of samples, unit: time

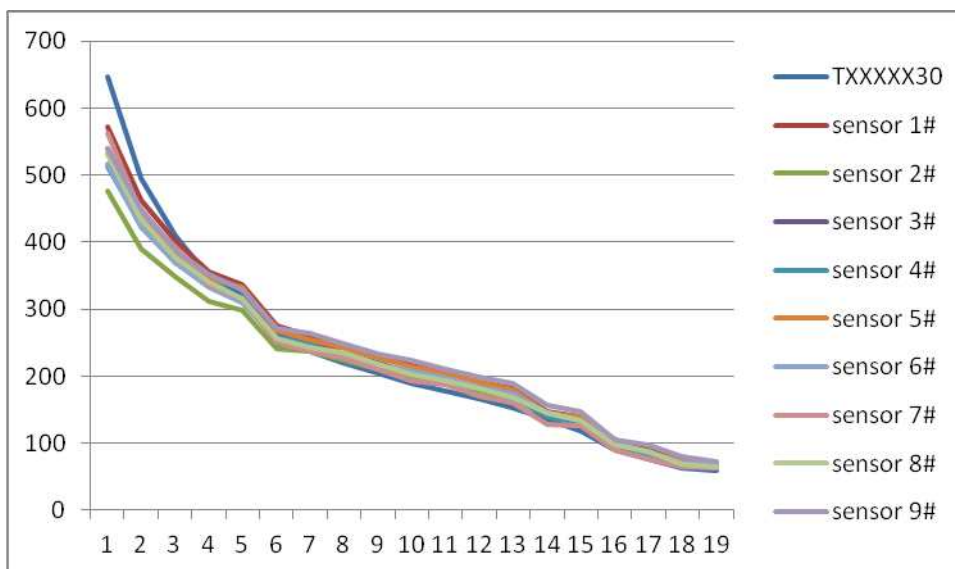Figure 4-1   Consistency at 20℃
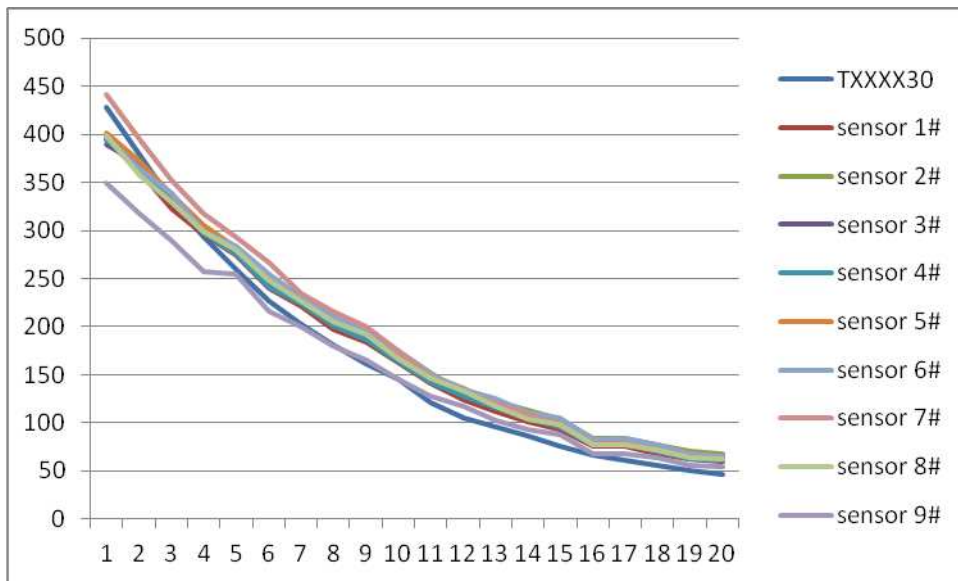
2016 product data manual of PLANTOWER
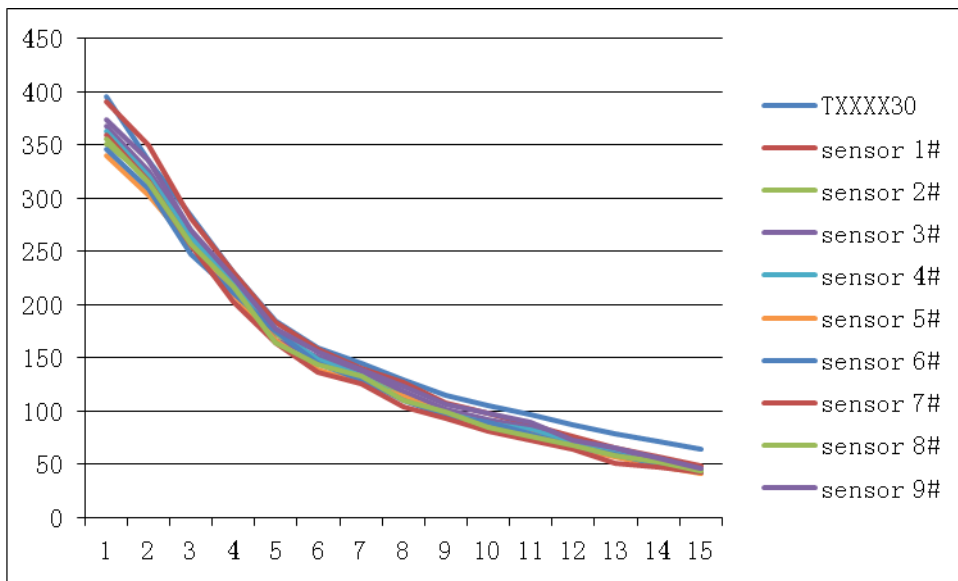

Figure 4-2   Consistency at 43℃
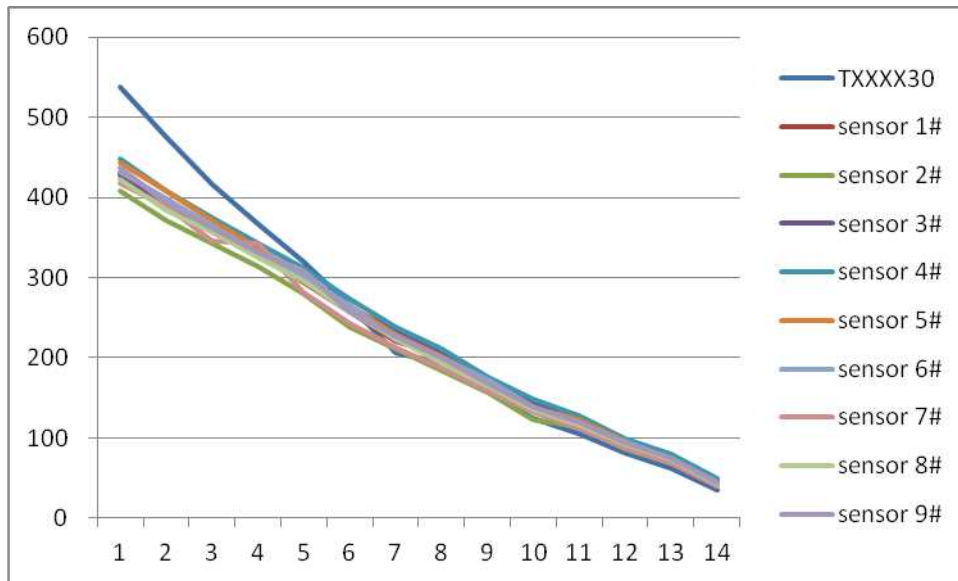

Figure 4-3   Consistency at -5℃

Figure 4-4   Consistency after 30 days' running

Relationship of Temperature and Consistency

Definition of axis Y: Maximum Error Modulus(%)
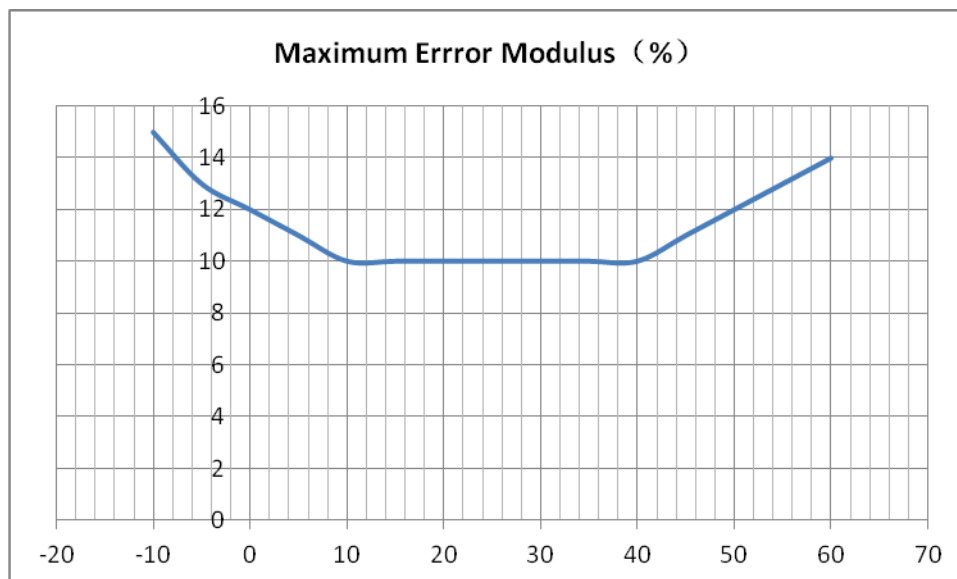Definition of axis X: Temperature(℃)

Figure 5   Consistency Vs Temperature

Endurance Characteristics

No	Item	Test Method	Characteristics	n C
1	Long Running	1. 10 ㎡ closed Lab,，20~25℃，humidity 30%~70%，particle generator and air cleaner 2. DC 5V power supply 3. Check consistency after 720 hours' running	10 samples during 0~500μ g/m³ 0~100μ g/m³ Maximum Error≤ ±15μ g/m³	n=30 C=0
2	High Temperature Operation	1. 10 ㎡ constant temperature Lab 2. 43℃，humidity 70%， 3. particle generator and air cleaner 4. DC 5V power supply 5. Check consistency	100~500μ g/m³ Maximum Error≤ ±15%	n=10 C=0
3	Cold Operation	1. 10 ㎡ constant temperature Lab 2. -5℃，humidity 30%， 3. particle generator and air cleaner 4. DC 5V power supply 5. Check consistency	FAN does not screeched	n=10 C=0
4	Vibration	1. 10 ㎡ closed Lab,，20℃，humidity 50%，particle generator and air cleaner 2. DC 5V power supply and check consistency 3. Frequency：50Hz。 4. acceleration：9.8/ S² 。 5. Direction：X、Y、Z 6. Vibration Amplitude：±2mm。 7. Time：X、Y、Z –way, Per 1 hour		n=5 C=0
5	High Temperature and Humidity Storage	1. Constant temperature cabinet 2. 70℃，humidity 90%~95， 3. Check consistency after 500 hours' storage	10 samples during 0~500μ g/m³ 0~100μ g/m³ Maximum Error≤ ±10μ g/m³	n=10 C=0
6	Cold Storage	1. Constant temperature cabinet 2. -30℃，humidity 90%~95， 3. Check consistency after 500 hours' storage	100~500μ g/m³ Maximum Error≤ ±10%	n=10 C=0
7	Variation of	4. 10 ㎡ closed Lab,，20℃，humidity		n=5

	Power Supply	50%，particle generator and air cleaner 5. Power varies as the cycles of 4.5V to 5.5V ,then 5.5V to 4.5V with the pace of 0.1V/min for 2 hours. 6. Check consistency during Variation	FAN does not screeched	C=0
8	Power On-Off Cycle	1. 10㎡ closed Lab,,20℃,humidity 50%，particle generator and air cleaner 2. DC 5V power supply，keep On-Off frequency 0.5Hz for 72 hours and check consistency		n=10 C=0
9	Sleep Set On-Off Cycle	1. 10㎡ closed Lab,,20℃,humidity 50%，particle generator and air cleaner 2. DC 5V power supply，keep Sleep Set Pin High-Low frequency 0.5Hz for 72 hours and check consistency		n=10 C=0
10	Laser On-Off Cycle	1. 10㎡ closed Lab,,20℃,humidity 50%，particle generator and air cleaner 2. keep laser On-Off frequency 50Hz for 240 hours and check consistency		n=10 C=0
11	Salt Spray	5% industrial salt water, hydrolysis spray 100 hours, clean with purified water and store for 48 hours	No rust and discoloration of metal parts	n=1 C=0

Circuit Attentions

1) DC 5V power supply is needed because the FAN should be driven by 5V. But the high level of data pin is 3.3V. Level conversion unit should be used if the power of host MCU is 5V.
2) The SET and RESET pins are pulled up inside so they should not be connected if without usage.
3) PIN7 and PIN8 should not be connected.
4) Stable data should be got at least 30 seconds after the sensor wakeup from the sleep mode because of the fan's performance.
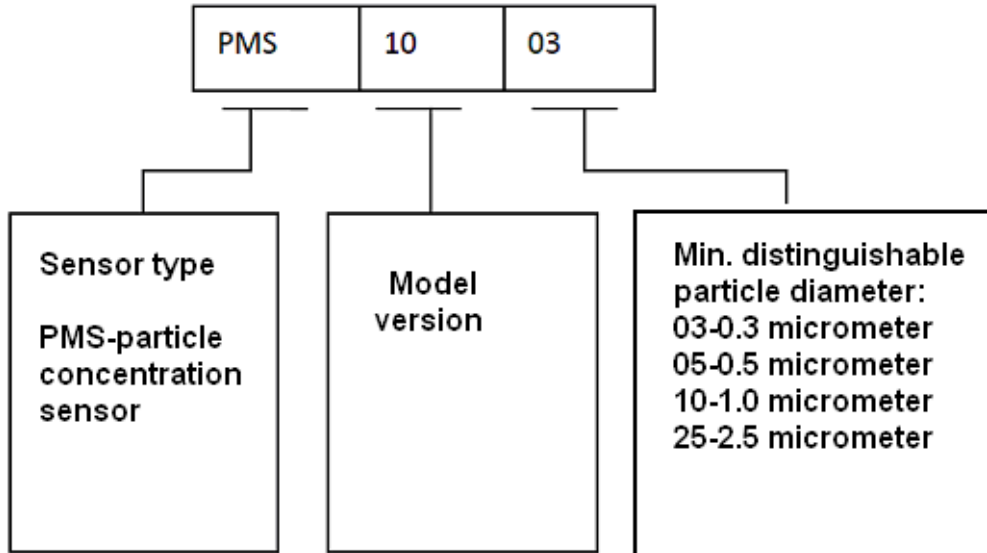
Installation Attentions

1) Metal shell is connected to the GND so be careful not to let it shorted with the other parts of circuit except GND.
2) The best way of install is making the plane of inset and outset closely to the plane of the host. Or some shield should be placed between inset and outset in order to prevent the air flow from inner loop.
3) The blowhole in the shell of the host should not be smaller than the inset.
4) The sensor should not be installed in the air flow way of the air cleaner or should be shielded by some structure.
5) The sensor should be installed at least 20cm higher than the grand in order to prevent it from blocking by the floc dust.
6) Do not break up the sensor.
7) M2 self-tapping strew should be used to fix the sensor but it should not be deeper than 5mm into the sensor.

Other Attentions

1) Only the consistency of all the PM sensors of PLANTOWER is promised and ensured. And the sensor should not be checked with any third party equipment.
2) The sensor is usually used in the common indoor environment. So some protection must be added if using in the conditions as followed:
   a) The time of concentration $\geqslant 300\mu g/m^3$ is longer than 50% of the whole year or concentration$\geqslant 500\mu g/m^3$ is longer than20% of the whole year.
   b) Kitchen
   c) Water mist condition such as bathroom or hot spring.
   d) outdoor

Part Number Definition

PMS	10	03

Sensor type PMS-particle concentration sensor	Model version	Min. distinguishable particle diameter: 03-0.3 micrometer 05-0.5 micrometer 10-1.0 micrometer 25-2.5 micrometer

Physical Size (mm)
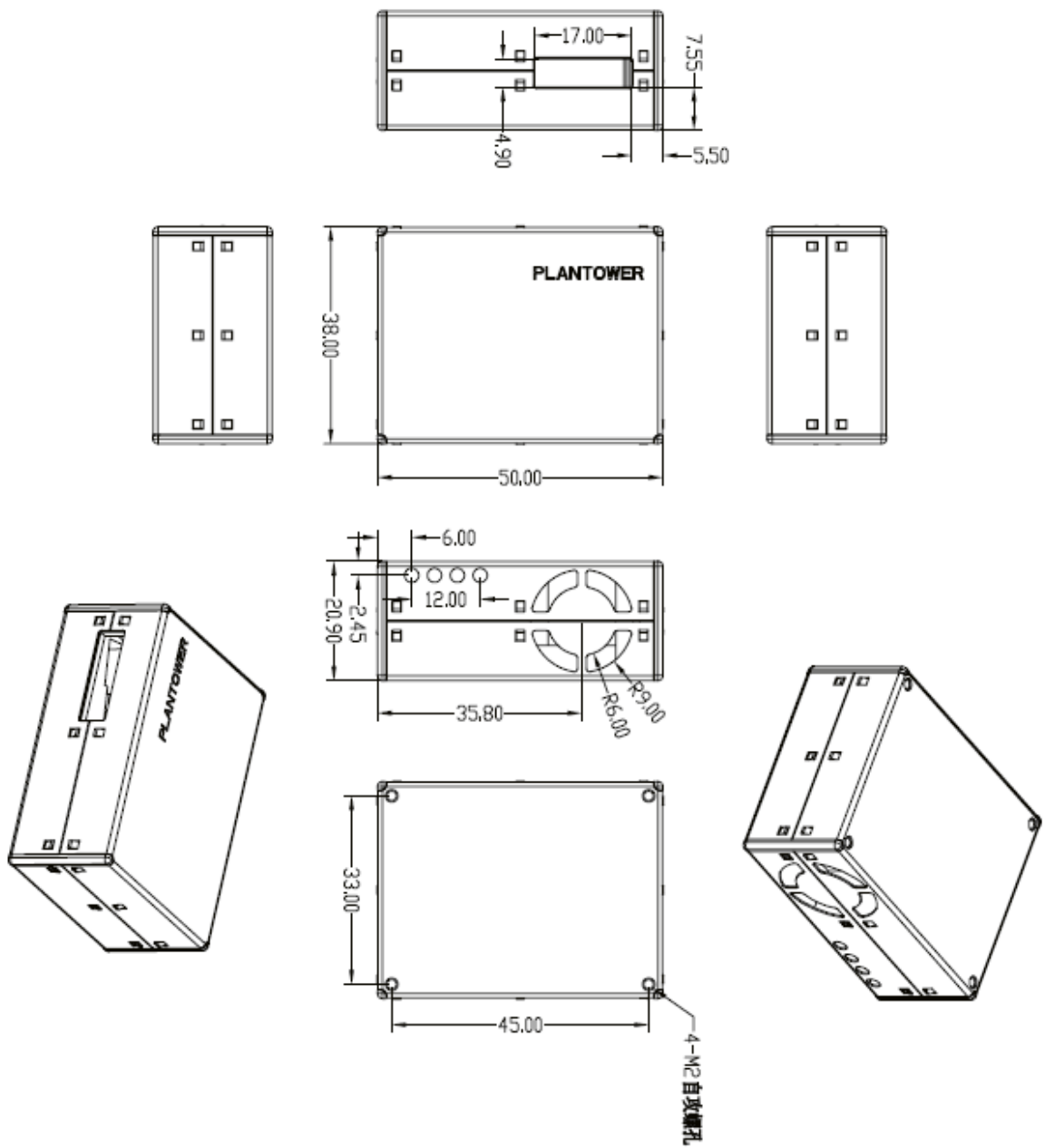
Appendix I：PMS5003 transport protocol-Active Mode

Default baud rate：9600bps　Check bit：None　Stop bit：1 bit

32 Bytes

unsigned short:

Start character 1	0x42	(Fixed)	0
Start character2	0x4d	(Fixed)	
Frame length high 8 bits	……	Frame length=2x13+2(data+check bytes)	1
Frame length low 8 bits	……		
Data 1 high 8 bits	……	Data1 refers to PM1.0 concentration unit μ g/m3（CF=1，standard particle）*	2
Data 1 low 8 bits	……		
Data2 high 8 bits	……	Data2 refers to PM2.5 concentration unit μ g/m3（CF=1，standard particle）	3
Data2 low 8 bits	……		
Data3 high 8 bits	……	Data3 refers to PM10 concentration unit μ g/m3（CF=1，standard particle）	4
Data3 low 8 bits	……		
Data4 high 8 bits	……	Data4 refers to PM1.0 concentration unit　* μ g/m3（under atmospheric environment） PM1.0 is everything ≤1 μm	5
Data4 low 8 bits	……		
Data5 high 8 bits	……	Data 5 refers to PM2.5 concentration unit μ g/m3（under atmospheric environment） PM2.5 is everything ≤2.5 μm	6
Data5 low 8 bits	……		
Data6 high 8 bits	…….	Data 6 refers to concentration unit (under atmospheric environment) μ g/m3 This probably is PM10. PM10 is everything ≤10 μm	7
Data6 low 8 bits	……		
Data7 high 8 bits	……	Data7 indicates the number of particles with diameter beyond 0.3 um in 0.1 L of air.	8
Data7 low 8 bits	……		
Data8 high 8 bits	……	Data 8 indicates the number of particles with diameter beyond 0.5 um in 0.1 L of air.	9
Data8 low 8 bits	……		
Data9 high 8 bits	……	Data 9 indicates the number of particles with diameter beyond 1.0 um in 0.1 L of air.	10
Data9 low 8 bits	……		

unsigned short:

Data10 high 8 bits	……	Data10 indicates the number of particles with diameter beyond 2.5 um in 0.1 L of air.	11
Data10 low 8 bits	……		
Data11 high 8 bits	……	Data11 indicates the number of particles with diameter beyond 5.0 um in 0.1 L of air.	12
Data11 low 8 bits	……		
Data12 high 8 bits	……	Data12 indicates the number of particles with diameter beyond 10 um in 0.1 L of air.	13
Data12 low 8 bits	……		
Data13 high 8 bits	……	Data13 Reserved	14
Data13 low 8 bits	……		
Data and check high 8 bits	……	Check code=Start character 1+ Start character 2+……..+data 13 ~~Low 8 bits~~	15
Data and check low 8 bits	……		

Note: CF=1 should be used in the factory environment

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In the Python programming language (version 3), you can use the `struct` module to extract the numbers from the data packet. Assuming that you have captured a complete transport packet in a `bytes` object called `data`, you can extract the numbers simply like this:

```
numbers = struct.unpack('>HHHHHHHHHHHHHHHH', data)
```

Calculating the checksum is simply done by summation:

```
cksum = sum(data[0:30])
```

This checksum should be equal to `numbers[-1]`.

NOTE: <R.F. Smith> The unit that I bought tends to start producing nothing but checksum errors after several hours of active mode. Restarting the unit by dicsonnecting and reconnecting the power fixes that. In passive mode, I have not yet seen this.

Appendix II：PMS5003 transport protocol-Passive Mode

Default baud rate：9600bps   Check bit：None   Stop bit：1 bit

Host Protocol

Start Byte 1	Start Byte 2	Command	Data 1	Data 2	Verify Byte 1	Verify Byte 2
0x42	0x4d	CMD	DATAH	DATAL	LRCH	LRCL

1. Command Definition

CMD	DATAH	DATAL	说明
0xe2	0x00	0x00	Read in passive mode
0xe1	0x00	00H-passive 01H-active	Change mode
0xe4	0x00	00H-sleep 01H-wakeup	Sleep set

Alternatively, you can pull pin 3 down to put the sensor to sleep, see page 4.

2. Answer

0xe2: 32 bytes , same as appendix I

3. Verify Bytes :

Add of all the bytes except verify bytes.

To clarify, below are the possible commands (in the form of byte strings) to send to the PMS5003:

Command	Hexadecimal byte strings
Request data in passive mode	42 4D E2 00 00 01 71
Change to passive mode	42 4D E1 00 00 01 70
Change to active mode	42 4D E1 00 01 01 71
Go to sleep	42 4D E4 00 00 01 73
Wake up	42 4D E4 00 01 01 74

The first part of each byte string are the two start bytes. Then follows the command. The last two bytes are the checksum. An example how to calculate the checksum of the last command in Python 3:

```
hex(0x42 + 0x4d + 0xe4 + 0x00 + 0x01)
```

This results in 0x174.