

12. TIMER (TRACK TIMERS)

PROGRAM

Starting the Interval Timer:

- 1) In the default configuration, Push-Button Switch Sw2 controls the Interval Timer. Press and HOLD the Push-Button Switch for 3 seconds. An audible double-tone will sound and INT will flash on the Top Screen indicating the Interval Timer is in Stand-by.


To start the Interval Timer, press the Push-Button Switch a second time or pull the Throttle Trigger. An audible double-tone will sound and the Interval Timer will start counting up. Each time the programmed Interval Time elapses, an audible double-tone will sound and the Interval Timer will restart from zero and the Cumulative Time will be displayed on the Top Screen.

You can manually restart the Interval Timer from zero by pressing the Push-Button Switch while the Interval Timer is running.

 If desired, the Timer Function can be assigned to Push-Button Switch Sw1. For more information, see the Key Assignments section on pages 53 through 58.

Stopping the Interval Timer:

- 1) To stop the Interval Timer, press and HOLD Push-Button Switch Sw2 for 3 seconds. An audible double-tone will sound indicating the Interval Timer is stopped and the Cumulative Time will be displayed on the Top Screen and in the TIMER menu.

 The Cumulative Time cannot be manually cleared. It will be automatically cleared when the Interval Timer is put in Stand-by again.

DOWN (Countdown Timer)

The Countdown Timer function can be used to notify you of your model's running time. For example, you can set the Countdown Timer to alert you when it's time to refuel. When the Countdown Timer expires, a long audible tone will sound and the Count Up Timer function begins automatically. This allows you to check the time elapsed since the Countdown Timer ran out.

Setting the Alarm:

- 1) From within the TIMER menu, scroll DOWN to highlight [ALRM] 05.
- 2) Press the ENTER key, then scroll UP or DOWN to set the desired Alarm Minutes value.
- 3) To set the Alarm Seconds value, press the ENTER key, then scroll DOWN to highlight 00. Press the ENTER key a second time, then scroll UP and DOWN to set the desired Alarm Seconds value.



TIMER ALRM setting range is 00:00 to 99:59. The default setting is 5:00 minutes. An audible tone will sound in 1 second intervals 5 seconds before reaching the Countdown Alarm Time. When the Countdown Alarm Time is reached, a long audible tone will sound.

Starting the Countdown Timer:

- 1) In the default configuration, Push-Button Switch Sw2 controls the Countdown Timer. Press and HOLD the Push-Button Switch for 3 seconds. An audible double-tone will sound and DWN will flash on the Top Screen indicating the Countdown Timer is in Stand-by.


To start the Countdown Timer, press the Push-Button Switch a second time or pull the Throttle Trigger. An audible double-tone will sound and the Countdown Timer will start counting down. An audible tone will sound in 1 second intervals 5 seconds before reaching zero. When zero is reached, a long audible tone will sound and the Countdown Timer will begin counting up.

You can manually stop the Countdown Timer at any time by pressing the Push-Button Switch. Press the Push-Button Switch again will start the Countdown Timer from where it was stopped.

 If desired, the Timer Function can be assigned to Push-Button Switch Sw1. For more information, see the Key Assignments section on pages 53 through 58.

Stopping the Countdown Timer:

- 1) To stop the Countdown Timer, press and HOLD the Push-Button Switch for 3 seconds. An audible double-tone will sound indicating the Countdown Timer is stopped and either the remaining Countdown Time or elapsed Count Up Time will be displayed on the Top Screen and in the TIMER menu.

 The remaining Countdown Time or Count Up Time cannot be manually cleared. It will be automatically cleared when the Countdown Timer is put in Stand-by again.

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13. LAP (LAP TIMES)

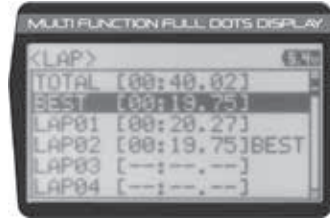
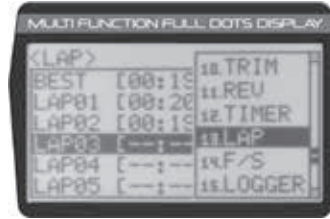
PROGRAM

The Lap Times menu displays a total of up to 99 laps that are recorded using the Lap Timer function. Each Lap Time is displayed along with the Best Lap Time and the Total (Cumulative) Lap Time.

Viewing Lap Times:

- 1) From the Top Screen, press the ENTER key to open the Programming Menu list.
- 2) Scroll UP or DOWN to highlight the LAP menu, then press the ENTER key. The LAP menu will be displayed and the last Lap selected will be highlighted.
- 3) Scroll UP and DOWN to view the stored Lap Times. Lap Times are stored from the time you start the Lap Timer to the time you Stop the Lap Timer. The Total (Cumulative) Lap Time and your Best Lap Time are always displayed at the top of the list.

 Lap Times are stored until you restart the Lap Timer function. When the Lap Timer function is restarted, old Lap Times are cleared and new Lap Times are stored.



14. F/S (FAIL SAFE)

PROGRAM

The Fail Safe function automatically moves the servos to a predetermined position in the event that the signal between the transmitter and the receiver is interrupted, whether due to signal degradation or to low transmitter battery. Several different setting options are available. The Fail Safe function can be set to Hold the servos in the last position they were in when the signal was lost, or each of the servos can be set to move to a custom position when the signal is lost. For example, the throttle servo moves to the Brake Side to engage the brakes and stop your model. If you're driving a gas- or glow-powered boat, the Fail Safe function could be set to lower the throttle to idle and turn the rudder slightly left or right so that the boat will continue in slow circles.

In addition, a Receiver Battery Voltage Fail Safe function is available which allows you to set a custom voltage that the Receiver Battery Fail Safe function will Activate at. This is useful if you're using servos with a higher than normal current draw that might run out of power before the receiver does.

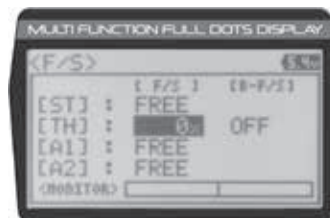
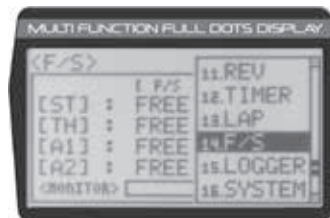
IMPORTANT: The Fail Safe function will NOT OPERATE if the receiver loses power. It will operate only if the transmitter and receiver signal is interrupted or if the transmitter loses power.

Setting the Fail Safe:

Fail Safe settings can be programmed for each of the four channels individually. In addition, Fail Safe settings are model-specific, meaning you can have different Fail Safe settings for each Model in memory. Three Fail Safe options are available for each channel as described below:

- FREE** - Fail Safe is disabled for this channel. Servos can move freely when the signal is lost.
- HOLD** - When Fail Safe Activates, the servo will be held in the last position it was in when the signal was lost.
- % (PERCENTAGE)** - When Fail Safe Activates, the servo will travel to the programmed position when the signal is lost.

- 1) From the Top Screen, press the ENTER key to open the Programming Menu list.
- 2) Scroll UP or DOWN to highlight the F/S menu, then press the ENTER key. The F/S menu will be displayed and [ST]:FREE will be highlighted.
- 3) Scroll UP or DOWN to highlight the desired channel you would like to change the Fail Safe option for.
- 4) Press the ENTER key, then scroll UP or DOWN to choose the desired Fail Safe option for that channel. If you choose to program a % value, see step 5 below.



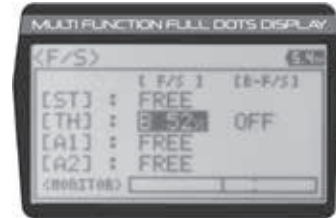
F/S setting range is FREE, HOLD, or %. The default setting is FREE.

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14.F/S (FAIL SAFE)

PROGRAM

- To program a Fail Safe percentage value, move the control the amount you want the servo to move to when the Fail Safe function Activates and HOLD it in that position, then press and HOLD the ENTER key until an audible tone sounds. The percentage and direction the servo will travel will be displayed. For example, to set the Throttle Brake to engage when the Fail Safe function Activates, push the throttle trigger toward the Brake side the desired amount, HOLD the throttle trigger in that position, then press and HOLD the ENTER key. The percentage value programmed will be indicated by two hash marks on the Servo Monitor.



- Check to ensure your Fail Safe settings are working properly. Make sure that both the transmitter and receiver are turned ON, then, while someone is holding your model, turn the transmitter OFF. The servos should react correctly based on the Fail Safe values chosen.

The Fail Safe settings will be retained even if the transmitter loses power or if the transmitter and receiver must be paired again.

When using an FH2 receiver with your transmitter, these Fail Safe features are not supported. In this case, the Fail Safe function must be programmed directly through the receiver. For more information, follow the Fail Safe Programming instructions provided with your FH2 receiver.

Setting the Receiver Battery Voltage Fail Safe Function:

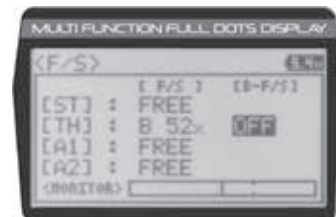
The Receiver Battery Voltage Fail Safe function is designed to alert you when your receiver battery requires recharging. This ensures that the receiver battery's voltage doesn't drop so low that your servos aren't provided adequate voltage to operate optimally. When Activated, the throttle servo will move to the predetermined position you programmed in step 5 in the Setting the Fail Safe section above. If this occurs, recharge or replace your receiver batteries.

WARNING: This function is designed for use with glow- or gas-powered Models that use a separate receiver battery pack. Do NOT use this function with an electric Model that uses the motor battery to power the servos and receiver.

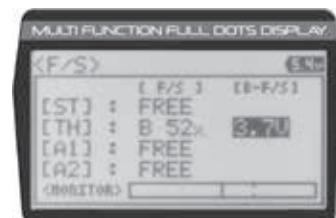
If FREE or HOLD is chosen for the Throttle channel, you cannot Activate the Receiver Battery Voltage Fail Safe function. A % value must be chosen for the Throttle channel to be able to program and use the Receiver Battery Fail Safe function.

The Receiver Battery Voltage Fail Safe function works only with FH3 and FH4T receivers.

- Follow steps 1 through 5 in the Setting the Fail Safe section to program a Throttle Fail Safe percentage value.
- From within the F/S menu, press the ENTER key, then scroll DOWN to highlight [B-F/S] OFF.



- Press the ENTER key, then scroll UP or DOWN to choose the desired Receiver Battery Fail Safe Voltage value. Many factors, such as the current draw of your servos and how many servos you're using, etc., will determine the value to use. A good starting point would be 3.7V. If it appears your servos are slow or not producing adequate torque what that Voltage value is reached, Increase the Voltage value.



F/S B-F/S setting range for FH4T receivers is OFF and 3.5V to 7.4V. F/S B-F/S setting range for FH3 receivers is OFF and 3.5V to 5.0V. The default setting is OFF regardless of the Modulation Type chosen.

15.LOGGER (TELEMETRY LOG)

PROGRAM

The Telemetry Log function allows you to view a log of the Telemetry Data that is sent from the receiver to the transmitter. You are able to view Telemetry Data for both Temperature outputs, the RPM output and the receiver's Voltage. This information can be used to track specific information about your model, such as cylinder head temperature if you're running a nitro-powered model or battery temperature if you're running an electric model and much more. The interval that Telemetry Data is read and stored can be adjusted so that Telemetry Data can be stored for up to 90 minutes of use. The Telemetry Log can store 120 different data entries at intervals ranging from 00.1 seconds to 45.9 seconds.

90478 2.4GHZ FH4T RADIO SYSTEM USER'S GUIDE

15. LOGGER (TELEMETRY LOG)

PROGRAM

IMPORTANT: Full telemetry support requires the use of an Airtronics 2.4GHz FH4T telemetry-capable surface receiver, such as the RX-461 or RX-462, along with Airtronics Temperature and RPM Sensors (available separately). The included RX-472 receiver can send Telemetry Data for the voltage of the receiver battery pack only, unless used with the Airtronics Super Vortex ZERO ESC (available separately) plugged into the BATT/SSL port of the included RX-472 receiver.

! For information about using an optional Telemetry receiver with your 90478 transmitter and installing Telemetry Sensors into your model, see the Telemetry Connections and Mounting section on pages 69 and 70. In addition, to be able to read and log Telemetry Data, the Telemetry system must be turned ON. For more information about turning the Telemetry system ON, see the Telemetry Setting section on pages 67 and 68.

Starting and Stopping the Telemetry Log:

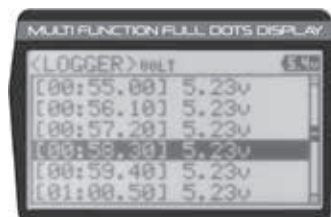
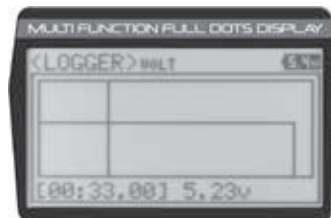
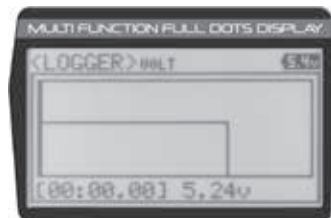
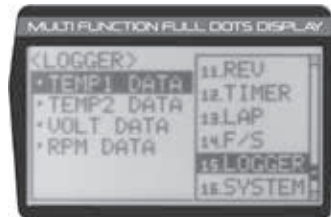
The Telemetry Log function must be Started in order for the transmitter to read and store Telemetry Data from the receiver.

- 1) In the default configuration, Push-Button Switch Sw1 controls the Telemetry Log. To start the Telemetry Log, press the Push-Button switch. LED1 (Blue) will flash, indicating the Telemetry Log is storing data. Telemetry Data is stored for all four Telemetry functions, whether the Telemetry Sensors are hooked up or not.
- 2) To stop the Telemetry Log, press the Push-Button Switch a second time. If desired, the Telemetry Log Function can be assigned to Push-Button Switch Sw2. For more information, see the Key Assignments section on pages 53 through 58.

! Each time the Telemetry Log is started, any old Telemetry Data is automatically erased. In addition, the Telemetry Log will stop automatically once the Telemetry Log is filled. The Telemetry Log can store 120 separate entries. If the Log Interval is set to 00.1 seconds, the Telemetry Log can record for 12 seconds. If the Log Interval is set to 45.1 seconds, the Telemetry Log can record for 90 minutes. To change the Log Interval value, see the Changing the Telemetry Log Step Value section on page 68.

Viewing Telemetry Data:

- 1) From the Top Screen, press the ENTER key to open the Programming Menu list.
- 2) Scroll UP or DOWN to highlight the LOGGER menu, then press the ENTER key. The LOGGER menu will be displayed and TEMP1 DATA will be highlighted.
- 3) From within the LOGGER menu, scroll UP or DOWN to highlight the desired Telemetry Data you would like to view. Choose from TEMP1 DATA, TEMP2 DATA, VOLT DATA or RPM DATA.
- 4) Press the ENTER key to open the Telemetry Log.
- 5) To view the Telemetry Data at a specific point along the graph, scroll UP or DOWN to move the vertical line right or left. The Telemetry Data for each point the vertical line is at is displayed at the bottom of the screen.
- 6) To view all of the Telemetry Data points, press the ENTER key to open the Telemetry Data List, then scroll DOWN to view all of the recorded Telemetry Data entries.



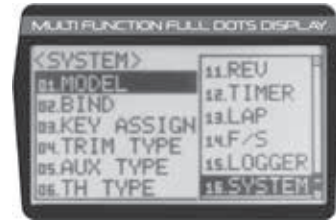
! The Telemetry Log can be started and stopped while viewing Telemetry Data. To start the Telemetry Log, press and HOLD the ENTER key and to stop the Telemetry Log, press and HOLD the ENTER key a second time.

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SYSTEM MENUS OVERVIEW

SYSTEM

The different System Menus allow you to program options related directly to the use and setup of the 90478 transmitter. From changing the Modulation Type, to adjusting LCD properties and changing Key Assignments to suit your specific setup, it's all here.



- 1) To access the various System Menus, turn the transmitter ON, then press the ENTER key (Push-Button Rotary Dial) to open the Programming Menu list. Scroll DOWN to SYSTEM, then press the ENTER key a second time to open the System Menu. A list of System Menus will be displayed and the first System Menu will be highlighted.
- 2) Use the Push-Button Rotary Dial to scroll UP or DOWN to highlight the desired System Menu, then press the ENTER key to open the highlighted System Menu.

MENU	MENU NAME	MENU DESCRIPTION	PAGE
01.MODEL	Model	Model Select, Model Naming, Model Copy and Model Clear	PG. 49
02.BIND	Binding	Bind, Select Modulation Type and Servo Operating Mode	PG. 52
03.KEY ASSIGN	Key Assignments	Assign Functions to the Switches, Rotary Dial and Auxiliary Lever	PG. 53
04.TRIM TYPE	Servo Trim Type	Change the Servo Trim Type	PG. 59
05.AUX TYPE	Auxiliary Type	Choose Auxiliary 1 and Auxiliary 2 Programming Functions	PG. 59
06.TH TYPE	Throttle Type	Change the Throttle Servo Travel Proportion	PG. 60
07.BUZZER	Audible Key Tone	Adjust Audible Key Tone Volume and Tone	PG. 61
08.BATTERY	Voltage Alarm	Specify Transmitter Battery Low Voltage and Limit Alarms	PG. 61
09.LCD	Contrast	Adjust LCD Contrast and Backlight Options	PG. 62
10.TELEMETRY	Telemetry	Program Telemetry Display Options	PG. 63
11.VR ADJUST	Variable Rate Adjust	Calibrate Steering, Throttle and Auxiliary Lever Controls	PG. 68

SYSTEM MENUS


01.MODEL (MODEL SELECT, NAMING, COPY AND CLEAR)

SYSTEM

The Model menu allows you to select different models using the Model Select function, name your saved models using the Model Naming function, and copy Programming Data from one model to another, or clear Programming Data from one or more models using the Model Copy and Model Clear functions. Programming Data for up to 18 different models can be stored in the transmitter's memory. This allows you to use the transmitter with different models and quickly and easily select the Programming Data for each of them. In addition, a Model Select Shortcut function is also featured for quick access to the Model Select (Direct Model) function.

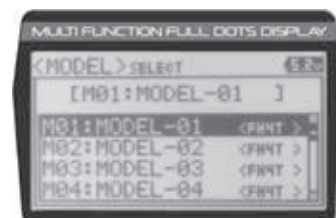
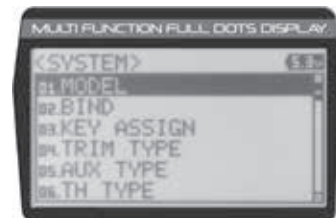
MODEL SELECT (Model Select)

The Model Select function allows you to load the Programming Data for the particular model you wish to drive. The Model Select menu displays the currently selected model, along with a list of available models that can be selected. The Modulation Type for each model is also displayed. The transmitter can store Programming Data for up to 18 different models.

 When a model is selected and loaded, the Programming Data for that model will be loaded immediately. Modulation Type, Servo Operating Mode, Key Assignments, Trim Type, Auxiliary Type and Throttle Type options, in addition to all Programming Menu function options are model-specific.

Selecting a Model:

- 1) From within the SYSTEM menu, scroll UP or DOWN to highlight the MODEL menu.
- 2) Press the ENTER key to open the MODEL menu. MODEL SELECT will be highlighted.
- 3) Press the ENTER key. The MODEL SELECT menu will be displayed and the currently selected model in the Model Select List will be highlighted.



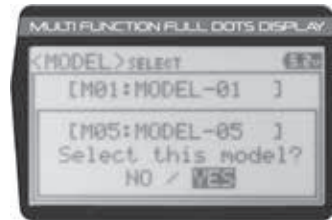
SYSTEM

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01. MODEL (MODEL SELECT, NAMING, COPY AND CLEAR)

SYSTEM

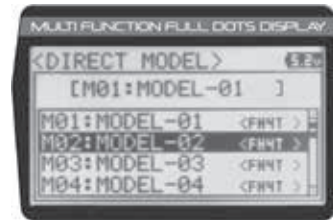
- 4) Scroll UP or DOWN to highlight the model you would like to select, then press the ENTER key. Select this model? NO/YES will be displayed.
- 5) Scroll DOWN to highlight YES, then press the ENTER key. The model that you just selected will be displayed above the Model Select List and that model's Programming Data will be loaded.



Model Select Shortcut (Direct Model):


The Model Select Shortcut function allows you to jump directly to the DIRECT MODEL menu when you turn the transmitter ON. This menu works the same as the MODEL SELECT menu and makes it much quicker select your desired model.

- 1) Turn the transmitter OFF.
- 2) Press and HOLD the BACK/CANCEL key, then turn the transmitter ON. The DIRECT MODEL menu will be displayed. To select a model, follow steps 4 and 5 in the Selecting a Model section above.



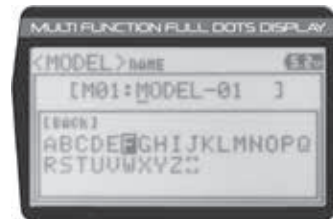
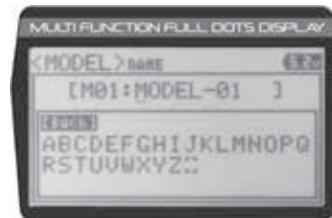
MODEL NAME (Model Naming)



The Model Naming function allows you to name each of the 18 individual models. This makes it easy to keep track of multiple models. The Model Name can consist of up to 10 letters, numbers, or symbols. Choose from capital letters, lower case letters, numbers, and various symbols.

 A model must be selected before a Model Name can be entered or modified. In the default configuration, M01:MODEL-1 is selected. To enter a Model Name for another model, that model must first be selected using the Model Select function or the Model Select Shortcut function. For more information, see the Model Select section on pages 49 and 50.



Changing the Model Name:

- 1) From within the MODEL menu, scroll DOWN to highlight MODEL NAME.
- 2) Press the ENTER key. The MODEL NAME menu will be displayed, [BACK] will be highlighted and the underscore will be flashing under the first editable character in the Model Name.
- 3) Scroll UP or DOWN to move the underscore to the character you would like change.
- 4) Press the ENTER key, then scroll UP or DOWN to highlight a character in the Character List. Press the ENTER key a second time to select the highlighted character. That character will be displayed and the underscore will move to the next space in the Model Name.
- 5) Repeat steps 3 and 4 to enter the rest of the characters. Up to ten characters can be entered. Press the BACK/CANCEL key to re-gain control of the underscore (the underscore will flash indicating you can scroll UP or DOWN to move it Forward or Backward).



 To select lower case letters, numbers or symbols, continue to scroll UP or DOWN through the various Character Lists. To add a space in your Model Name, use the  icon.

Deleting a Single Character or an Entire Model Name:

- 1) Scroll UP or DOWN to move the underscore under the character in the Model Name you want to delete. Press the ENTER key, then scroll UP or DOWN to highlight [BACK] or the  icon in the Character List and press the ENTER key. If you want to delete the entire name, move the underscore to the last character in the name, scroll UP or DOWN to highlight [BACK] or the  icon in the Character List, then repeatedly press the ENTER key.

 If you can't move the underscore, press the BACK/CANCEL key to re-gain control of the underscore (the underscore will flash indicating you can scroll UP or DOWN to move it Forward or Back).


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01. MODEL (MODEL SELECT, NAMING, COPY AND CLEAR)

SYSTEM


MODEL COPY (Model Programming Data Copy)

The Model Copy function allows you to copy the Programming Data from one model to another model. For example, if you have two models that are similar, you can copy the Programming Data from the first model to the second model to use as a base to start fine-tuning the programming for the second model.

 The Model Copy function allows you to copy Programming Data FROM the currently selected model TO any other model in the Model Copy List. Make sure that prior to using the Model Copy function, you first select and load the desired Model Programming Data you want to copy FROM, using the Model Select function.

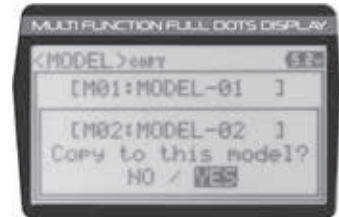
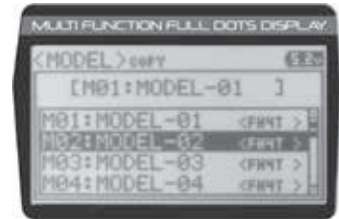
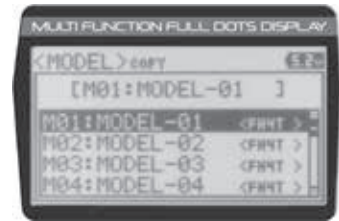
Copying Model Programming Data:

- 1) From within the MODEL menu, scroll DOWN to highlight MODEL COPY.
- 2) Press the ENTER key. The MODEL COPY menu will be displayed and the first model in the Model Copy List will be highlighted.

 The currently selected model is displayed above the Model Copy List.

- 3) Scroll UP or DOWN to highlight the model you would like to copy the Programming Data TO.

- 4) Press the ENTER key. Copy to this model? NO/YES will be displayed.
- 5) Scroll DOWN to highlight YES, then press the ENTER key. After ~3 seconds, Executed will flash, indicating the Programming Data has been copied to the highlighted model.



 All model-specific Programming Data, including the Model Name will be copied to the highlighted model. If you want to go back and change models or you don't want to copy the Programming Data for any reason, press the BACK/CANCEL key.

MODEL CLEAR (Model Programming Data Reset)

The Model Clear function allows you to Reset model-specific Programming Data for any model back to the factory default settings.


WARNING: When the Model Clear function is Executed, all custom Programming Data for that model will be lost!

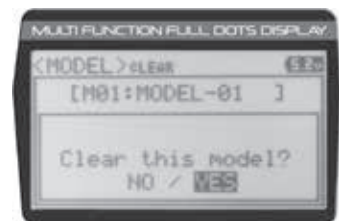
Clearing Model Programming Data:

- 1) Using the Model Select function, select the model you would like to Reset the Programming Data for.
- 2) From within the MODEL menu, scroll DOWN to highlight MODEL CLEAR.
- 3) Press the ENTER key. Clear this model? NO/YES will be displayed.

 The currently selected model is displayed at the top of the MODEL CLEAR menu.

- 4) Scroll DOWN to highlight YES, then press the ENTER key. After ~3 seconds, Executed will flash, indicating the Programming Data has been Reset to the default values.

 If you want to go back and change models or you don't want to Reset the Programming Data for any reason, press the BACK/CANCEL key. When Executed, all model-specific Programming Data, including the Model Name, Modulation Type, Servo Operating Mode, Key Assignments, Trim Type, Auxiliary Type and Throttle Type options will be Reset to the default values.



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02.BIND (BINDING, MODULATION TYPE AND SERVO OPERATING MODE)

SYSTEM

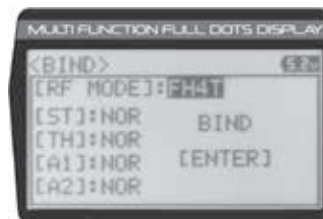
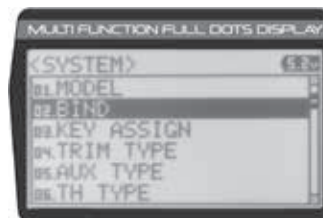
The Binding function allows you to Bind the transmitter and receiver pair. When new, it is necessary to pair the transmitter and receiver to prevent interference from transmitters operated by other users. This operation is referred to as Binding. Once the Binding process is complete, the setting is remembered even when the transmitter and receiver are turned OFF. Therefore, this procedure usually only needs to be done once. In addition, the Modulation Type and Servo Operating Mode can also be changed to suit your specific setup.

Changing the Modulation Type:

The Modulation Type function allows you to choose the transmitter Modulation Type. The Modulation Type can be changed to match the receiver you're using. For example, if you wish to use an Airtronics 2.4GHz FH2 receiver with your transmitter, you would need to change the Modulation Type to FH2 prior to Binding your transmitter and receiver. Modulation Type is model-specific, meaning that you can have one model use FH4T Modulation and another model use FH2 Modulation, etc.

 The Modulation Type must be chosen prior to Binding the transmitter and receiver. Make sure the Modulation Type you choose matches the Modulation Type of the receiver you're using.

- 1) From within the SYSTEM menu, scroll UP or DOWN to highlight the BIND menu.
- 2) Press the ENTER key. The BIND menu will be displayed and [RF MODE]:FH4T will be highlighted.
- 3) Press the ENTER key, then scroll UP or DOWN to select the desired Modulation Type, then press the ENTER key a second time. Set to (Modulation Type) NO/YES will be displayed.
- 4) Scroll DOWN to highlight YES, then press the ENTER key.



The following Modulation Type options are available:

FH2 - Select this Modulation Type when using an Airtronics 2.4GHz FH2 surface receiver.

FH3 - Select this Modulation Type when using an Airtronics 2.4GHz FH3 receiver.

FH4T - Select this Modulation Type when using an Airtronics 2.4GHz FH4T Telemetry receiver.

FH3F/FH4FT - These Modulation Types are NOT used in North America. They are typically used in France.

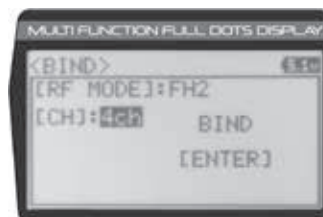
IMPORTANT: Not all BIND menu functions are supported by all Modulation Types. Only supported functions will be displayed once a Modulation Type is chosen. For example, the FH2 Modulation Type does not support the ability to change the Servo Operating Mode.

Changing the Channel Mode - FH2 Modulation Type Only:

When the FH2 Modulation Type is selected, you can choose to operate the transmitter in either 2-Channel Mode or 4-Channel Mode. This option is available ONLY when [RF MODE] FH2 is selected.

- 1) From within the BIND menu, scroll DOWN to highlight [CH]:4ch.
- 2) Press the ENTER key, then scroll UP or DOWN to choose the desired Channel Mode. Selecting 2CH will enable 2-channel operation (Steering and Throttle). Selecting 4CH will enable 4-channel operation (Steering, Throttle, Auxiliary 1 and Auxiliary 2).

BIND CH setting range is 2CH and 4CH. The default setting is 4CH.



Changing the Servo Operating Mode:

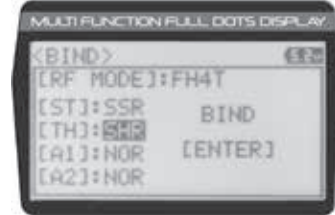
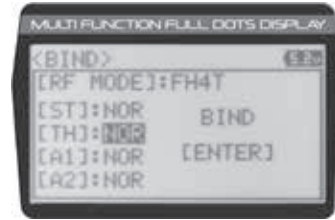
The Servo Operating Mode function is used to optimize the radio control system to suit the type of servos you're using in your model. For example, using the SHR setting with Digital servos will Increase the servo's response time, even above the manufacturer's stated specification. If you're using Airtronics SRG Digital servos, you can use the SSR setting for the fastest response time. The combination of using Digital servos and using the correct Servo Operating Mode results in the ultimate feel and response, making you feel more in control of your model than ever.

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02.BIND (BINDING, MODULATION TYPE AND SERVO OPERATING MODE)

SYSTEM

- 1) From within the BIND menu, scroll UP or DOWN to highlight the desired channel you would like to change the Servo Operating Mode for. Choose from either [ST]:NOR (Steering), [TH]:NOR (Throttle), [A1]:NOR (Auxiliary 1) or [A2]:NOR (Auxiliary 2).
- 2) Press the ENTER key, then scroll UP or DOWN to choose the desired Servo Operating Mode option for that channel.



SERVO OPERATING MODE setting range is NOR, SHR and SSR. The default setting is NOR. SSR Operating Mode is not supported when the FH3 or FH3F Modulation Type is selected. No Servo Operating Modes are supported when the FH2 Modulation Type is selected.

IMPORTANT INFORMATION ABOUT SERVO OPERATING MODES:

If you're using Analog servos in your model, DO NOT use SHR or SSR Servo Operating Mode for those channels. Use the NOR (Normal) Servo Operating Mode with Analog servos. Using SHR or SSR Servo Operating Mode with Analog servos can result in poor performance or even damage to the servos or the receiver! In some cases, the servo may not operate at all.

Not all ESCs are compatible with SHR or SSR Servo Operating Modes. If your ESC does not operate correctly, change the Servo Operating Mode to NOR (Normal) for that channel (or channels).

SHR and SSR Servo Operating Modes should only be used with Digital servos. While the SHR Servo Operating Mode can be used with any brand of Digital servo, the SSR Servo Operating Mode should ONLY be used with Airtronics SRG Digital servos.

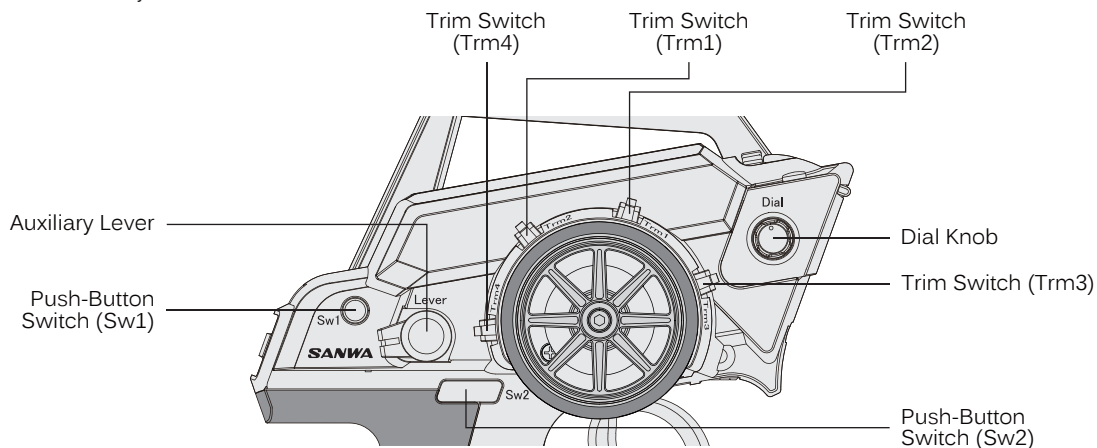
Binding the Transmitter and Receiver:

To Bind the transmitter and receiver, please see the Transmitter and Receiver Binding section on page 16. Prior to Binding the transmitter and receiver, make sure to choose the desired Modulation Type that matches the receiver you're using. Servo Operating Mode can be changed prior to Binding the transmitter and receiver, or after the Binding process.

03.KEY ASSIGN (KEY ASSIGNMENTS)

SYSTEM

The Key Assignments function allows you to assign different functions to each of the two Push-Button Switches, the four Trim Switches, the Dial Knob and the Auxiliary Lever. In addition, the ON/OFF behavior of some Push-Button Switch functions can be changed. The Key Assignments function also allows you to change the Direction of Travel and the Trim Resolution of the four Trim Switches and the Rotary Dial. This allows you to fine-tune the movement of the servos when the Trim Switches are pressed and the Rotary Dial is turned.



Trm1 - Steering Trim

Trm2 - Throttle Trim

Trm3 - Steering Dual Rate

Trm4 - Brake Dual Rate

Sw1 - Telemetry Logger ON/OFF

Sw2 - Timer ON/OFF

Dial Knob - Auxiliary 1 Channel 3

Auxiliary Lever - Auxiliary 2 Channel 4


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03.KEY ASSIGN (KEY ASSIGNMENTS)

SYSTEM

SWITCH (Push-Button Switch Key Assignments)

The Key Assignments function allows you to assign the ON/OFF control of various functions to Push-Button Switches Sw1 and Sw2. This allows you to use the Push-Button Switches to turn functions OFF and ON during use. One function can be assigned to each Push-Button switch, although both Push-Button Switches can be OFF or ON at the same time. In addition, the ON/OFF behavior of some Push-Button Switch Key functions can be changed.

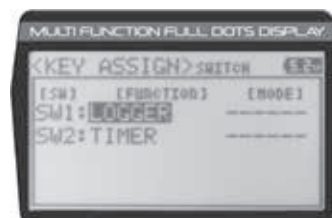
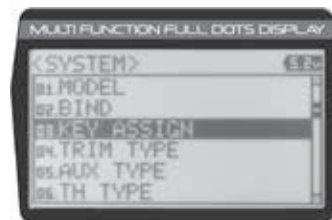
 When you program a function, that function is ON (Active) by default, unless the function's default ON/OFF value is OFF as noted in the table below. To toggle the function OFF and ON it must be assigned to a Push-Button Switch.

This table shows the different functions that can be programmed to the two Push-Button Switches:

MENU	FUNCTION	DEFAULT SWITCH	DEFAULT MODE	DEFAULT ON/OFF
OFF	Inhibited		-----	-----
D/R-ST	Dual Rate-Steering		Toggle	ON
D/R-TH	Dual Rate-Throttle		Toggle	ON
D/R-BR	Dual Rate-Brake		Toggle	ON
CUR-ST	Curve-Steering		Toggle	ON
CUR-TH	Curve-Steering		Toggle	ON
SPD-ST	Servo Speed-Steering		Toggle	ON
SPD-TH	Servo Speed-Throttle		Toggle	ON
ALB	Anti-Lock Braking		Toggle	ON
OFFSET	Throttle Offset		Toggle	ON
AUX1	Auxiliary 1 Channel 3		Toggle	ON
AUX2	Auxiliary 2 Channel 4		Toggle	ON
A1CODE1	Auxiliary 1 CODE1		Toggle	ON
A1CODE2	Auxiliary 1 CODE2		Toggle	ON
A1CODE3	Auxiliary 1 CODE3		Toggle	ON
A1CODE4	Auxiliary 1 CODE4		Toggle	ON
A1CODE5	Auxiliary 1 CODE5		Toggle	ON
A2CODE1	Auxiliary 2 CODE1		Toggle	ON
A2CODE2	Auxiliary 2 CODE2		Toggle	ON
A2CODE3	Auxiliary 2 CODE3		Toggle	ON
A2CODE4	Auxiliary 2 CODE4		Toggle	ON
A2CODE5	Auxiliary 2 CODE5		Toggle	ON
TIMER	Timers	Sw2	-----	OFF
TE-CLR	Telemetry Clear		-----	OFF
LOGGER	Telemetry Logger	Sw1	-----	OFF

Changing the Push-Button Switch Function:

- 1) From within the SYSTEM menu, scroll UP or DOWN to highlight the KEY ASSIGN menu.
- 2) Press the ENTER key to open the KEY ASSIGN menu. SWITCH will be highlighted.
- 3) Press the ENTER key. The SWITCH menu will be displayed and SW1:LOGGER will be highlighted.

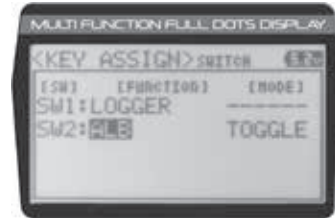


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03.KEY ASSIGN [KEY ASSIGNMENTS]

SYSTEM

- 4) Scroll UP or DOWN to highlight the function you would like to change for either SW1 or SW2.
- 5) Press the ENTER key, then scroll UP or DOWN to choose the desired function for either SW1 or SW2. A list of functions that can be assigned to the Push-Button Switches is shown in the table on the previous page.



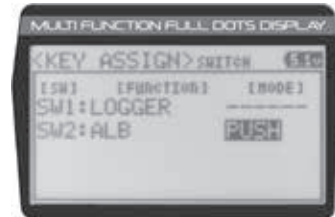
Changing the Switch Mode:

Some functions allow you to change how the Push-Button Switch operates. The following Switch Modes are available:

TOGGLE - When selected, press the Push-Button Switch to turn the function ON and press the Push-Button Switch a second time to turn the function OFF. **See note on previous page.**

PUSH - When selected, press and HOLD the Push-Button Switch to turn the function ON. When the Push-Button Switch is released, the function will be turned OFF.

- 1) From within the KEY ASSIGN SWITCH menu, scroll DOWN to highlight the MODE you would like to change for either SW1 or SW2.
- 2) Press the ENTER key, then scroll UP or DOWN to choose the desired Switch Mode setting, either TOGGLE or PUSH.



⚠ The Switch Mode cannot be changed for all functions. When [MODE] -----, the Push-Button Switch will act as if it were in Toggle Mode.

TRIM, DIAL AND LEVER (Trim Switch, Rotary Dial and Auxiliary Lever Key Assignments)

The Key Assignments function allows you to assign different functions to Trim Switches Trm1, Trm2, Trm3 and Trm4, the Rotary Dial and the Auxiliary Lever. This allows you to use the Trim Switches, Rotary Dial and Auxiliary Lever to control those functions while you're driving. In addition, the Direction of Travel (REV) and the Trim Resolution (Step value) of each Trim Switch and the Rotary Dial can be changed. The High and Low Travel Limits and the Direction of Travel of the Auxiliary Lever can be changed, too.

This table shows the different functions that can be programmed to the Trim Switches, Rotary Dial and Auxiliary Lever. Table is continued on the next page.

MENU	FUNCTION	DEFAULT SWITCH	DEFAULT STEP	DEFAULT REV
OFF	Inhibited		-----	-----
TRIM-ST	Trim-Steering	Trm1	5	NOR
TRIM-TH	Trim-Throttle	Trm2	5	NOR
TRIM-A1	Trim-Auxiliary 1			
TRIM-A2	Trim-Auxiliary 2			
D/R-ST	Dual Rate-Steering	Trm3	1	NOR
D/R-TH	Dual Rate-Throttle			
D/R-BR	Dual Rate-Brake	Trm4	1	NOR
CU-R-ST	Curve-Rate-Steering			
CU-P-ST	Curve-Point-Steering			
CU-R-TH	Curve-Rate-Throttle			
CU-P-TH	Curve-Point-Throttle			
CU-R-BR	Curve-Rate-Brake			
CU-P-BR	Curve-Point-Brake			
SP-ST-F	Speed-Steering-Forward			
SP-ST-R	Speed-Steering-Return to Neutral			
SP-TH-F	Speed-Throttle-Forward			
SP-TH-R	Speed-Throttle-Return to Neutral			
ALB-PO	Anti-Lock Braking-Point			
ALB-ST	Anti-Lock Braking-Stroke			

SYSTEM

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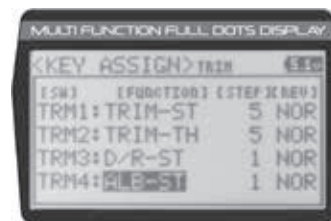
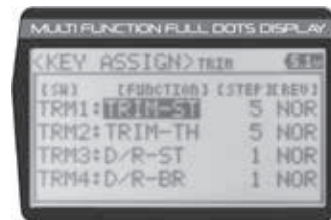
03.KEY ASSIGN (KEY ASSIGNMENTS)

SYSTEM

MENU	FUNCTION	DEFAULT SWITCH	DEFAULT STEP	DEFAULT REV
ALB-LG	Anti-Lock Braking-Lag			
ALB-HL	Anti-Lock Braking-Hold			
ALB-RE	Anti-Lock Braking-Release			
OFFSET	Throttle Offset			
AUX1	Auxiliary 1 Channel 3	Rotary Dial	5	NOR
AUX2	Auxiliary 2 Channel 4	Auxiliary Lever	N/A	N/A
A1CODE1	Auxiliary 1 CODE1			
A1CODE2	Auxiliary 1 CODE2			
A1CODE3	Auxiliary 1 CODE3			
A1CODE4	Auxiliary 1 CODE4			
A1CODE5	Auxiliary 1 CODE5			
A2CODE1	Auxiliary 2 CODE1			
A2CODE2	Auxiliary 2 CODE2			
A2CODE3	Auxiliary 2 CODE3			
A2CODE4	Auxiliary 2 CODE4			
A2CODE5	Auxiliary 2 CODE5			
INC/DEC	Increase/Decrease Values		-----	-----

Changing the Trim Switch Function:

- 1) From within the KEY ASSIGN menu, scroll UP or DOWN to highlight TRIM.
- 2) Press the ENTER key. The TRIM menu will be displayed and TRM1:TRIM-ST will be highlighted.
- 3) Scroll UP or DOWN to highlight the function you would like to change for either TRM1, TRM2, TRM3 or TRM4.
- 4) Press the ENTER key, then scroll UP or DOWN to choose the desired function for Trim Switch Trm1, Trm2, Trm3 or Trm4. A list of functions that can be assigned to the Trim Switches is shown in the table above and on the previous page.

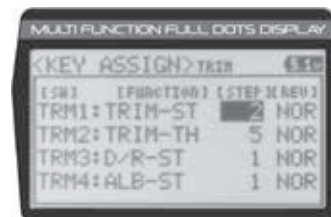


Changing the Trim Switch Step Value:

The Step function allows you to adjust how far the servos travel when the Trim Switches are pressed. You can increase the Trim Resolution by decreasing the Step value, so that the servos travel less when you press the Trim Switches. This makes it possible to fine-tune servo movement extremely accurately.

Alternately, you could decrease the Trim Resolution by increasing the Step values, so that the servos travel more when you press the Trim Switches. This setting may not be as accurate, although it allows you to command large amounts of servo travel at a time.

- 1) From within the TRIM menu, scroll UP or DOWN to highlight the Step value you would like to change for either TRM1, TRM2, TRM3 or TRM4.
- 2) Press the ENTER key, then scroll UP or DOWN to choose the desired Step value for Trim Switch Trm1, Trm2, Trm3 or Trm4.



TRIM STEP setting range is 1 to 100. The default setting for TRM1 is 5, for TRM2 is 5, for TRM3 is 1 and for TRM4 is 1. The Step value is a percentage of servo travel.

03.KEY ASSIGN (KEY ASSIGNMENTS)

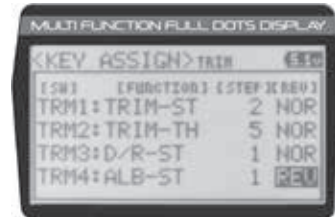
SYSTEM

Changing the Trim Switch Direction of Travel:

The direction that the Trim Switches move the servos can be changed from Normal to Reverse. In Normal mode, the Trim Switches will move the servos toward the High Side when the Trim Switches are pushed Forward. In Reverse mode, the Trim Switches will move the servos toward the Low Side (the opposite direction) when the Trim Switches are pushed Forward.

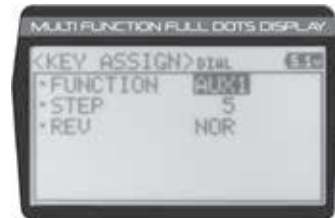
- 1) From within the TRIM menu, scroll UP or DOWN to highlight the REV value you would like to change for either TRM1, TRM2, TRM3 or TRM4.
- 2) Press the ENTER key, then scroll UP or DOWN to choose the desired REV value for Trim Switch Trm1, Trm2, Trm3 or Trm4.

TRIM REV setting range is NOR and REV. The default setting for all Trim Switches is NOR.

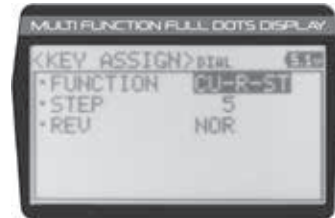


Changing the Rotary Dial Function:

- 1) From within the KEY ASSIGN menu, scroll UP or DOWN to highlight DIAL.
- 2) Press the ENTER key. The DIAL menu will be displayed and FUNCTION AUX1 will be highlighted.



- 3) Press the ENTER key, then scroll UP or DOWN to choose the desired function for the Rotary Dial. A list of functions that can be assigned to the Rotary Dial is shown in the table on pages 55 and 56.



Changing the Rotary Dial Step Value:

The Step function allows you to adjust how far the servo travels when the Rotary Dial is turned. You can increase the Dial Resolution by decreasing the Step value, so that the servo travels less when you turn the Rotary Dial. This makes it possible to fine-tune servo movement extremely accurately.

Alternately, you could decrease the Dial Resolution by increasing the Step value, so that the servo travels more when you turn the Rotary Dial. This setting may not be as accurate, although it allows you to command large amounts of servo travel at a time.

- 1) From within the DIAL menu, scroll UP or DOWN to highlight STEP 5.
- 2) Press the ENTER key, then scroll UP or DOWN to choose the desired Step value for the Rotary Dial.

DIAL STEP setting range is 1 to 100. The default setting is 5. The Step value is a percentage of servo travel.



Changing the Rotary Dial Direction of Travel:

The direction that the Rotary Dial moves the servo can be changed from Normal to Reverse. In Normal mode, the Rotary Dial will move the servo toward the High Side when the Rotary Dial is turned clockwise. In Reverse mode, the Rotary Dial will move the servo toward the Low Side (the opposite direction) when the Rotary Dial is turned clockwise.

- 1) From within the DIAL menu, scroll UP or DOWN to highlight REV NOR.
- 2) Press the ENTER key, then scroll UP or DOWN to choose the desired REV value for the Rotary Dial.

DIAL REV setting range is NOR and REV. The default setting is NOR.



SYSTEM

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03.KEY ASSIGN (KEY ASSIGNMENTS)


SYSTEM

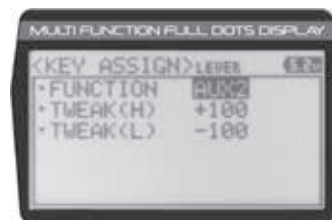
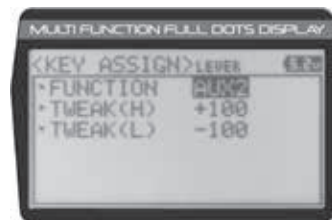
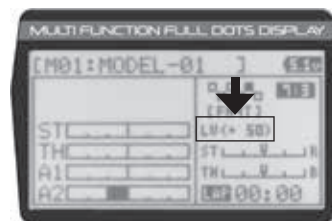
Changing the Auxiliary Lever Function:

In general, the Auxiliary Lever is used to control Auxiliary 1 Channel 3 or Auxiliary 2 Channel 4. Adjusting the High and Low Tweak values determines how far and in which direction the Auxiliary servo travels when the Auxiliary Lever is moved Up and Down. For example, if you assign AUX2 to the Auxiliary Lever and adjust the Tweak values to +50 and -50, the Auxiliary 2 servo will be centered when the Auxiliary Lever is centered and will travel 50% in one direction when the Auxiliary Lever is moved Up and travel 50% in the other direction when the Auxiliary Lever is moved Down. This allows you to use the Auxiliary Lever like a 2- or 3-position switch.

In addition, the Auxiliary Lever can be used to control the same parameter functions as the Trim Switches and the Rotary Dial. For example, if you assign TRIM-ST and adjust the Tweak values to +100 and -100, the Auxiliary Lever will control Steering channel Trim. The direction and amount the Trim moves when you move the Auxiliary Lever Up or Down is dependent on the Positive and Negative Tweak values.

 To control either the Auxiliary 1 or the Auxiliary 2 servos using the Auxiliary Lever, the Auxiliary Type in the AUX TYPE menu must be either STEP AUX or POINT AUX. For more information, see the Auxiliary Type section on pages 59 and 60.

 When you use the Auxiliary Lever to control a function, such as Steering Dual Rate or Exponential, the change in values will not be displayed in a pop-up window like they are when you use the Trim Switches or the Rotary Dial to make the same changes. Instead, the current position of the Auxiliary Lever is displayed on the Top Screen.



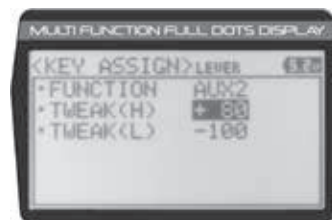
- 1) From within the KEY ASSIGN menu, scroll UP or DOWN to highlight LEVER.
- 2) Press the ENTER key. The LEVER menu will be displayed and FUNCTION AUX2 will be highlighted.
- 3) Press the ENTER key, then scroll UP or DOWN to choose the desired function for the Auxiliary Lever. A list of functions that can be assigned to the Auxiliary Lever is shown in the table on pages 55 and 56.

Changing the High and Low Tweak Values:

The High and Low Tweak values determine the direction and amount of Auxiliary 1 or Auxiliary 2 servo travel. In addition, the High and Low Tweak values determine the direction and amount of parameter function changes, such as Steering Trim or the Anti-Lock Braking Point percentage value.

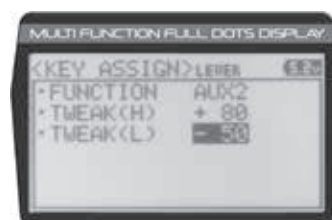
- 1) From within the LEVER menu, scroll DOWN to highlight TWEAK(H) +100.
- 2) Press the ENTER key, then scroll UP or DOWN to choose the desired High Side Tweak value. Increasing the Tweak value will increase servo travel in the High Side direction and decreasing the Tweak value will decrease servo travel in the High Side direction. Using a negative value will change the direction of servo travel.

LEVER TWEAK(H) setting range is -100 to +100. The default setting is +100.



- 3) Scroll DOWN to highlight TWEAK(L) -100.
- 4) Press the ENTER key, then scroll UP or DOWN to choose the desired Low Side Tweak value. Decreasing the Tweak value will increase servo travel in the Low Side direction and increasing the Tweak value will decrease servo travel in the Low Side direction. Using a positive value will change the direction of servo travel.

LEVER TWEAK(L) setting range is -100 to +100. The default setting is -100.




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04. TRIM TYPE [TRIM TYPE]

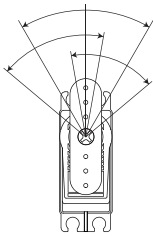
SYSTEM

The Trim Type function allows you choose the way servo Trim and servo End Point Adjustments interact with each other. When you apply Trim to a servo, the Neutral Point of the servo shifts toward the High Side or the Low Side. When you do this, the servo travels less in one direction and more in the other direction because the servo End Points are stationary. In order to balance the servo travel, you would need to manually readjust the servo End Points. Using the Trim Type function allows you to make the servo End Points shift toward the High Side or the Low Side when you apply Trim. This maintains balanced servo travel without the need to manually readjust the servo End Points.

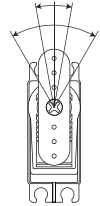
 The Trim Type function does not effect servo Sub-Trim. It only effects servo Trim that's input using the Trim Switches, Rotary Dial or Auxiliary Lever. Servo Sub-Trim, which is different, always uses Parallel Trim.

Two Trim Types are available:

CENTER - When Selected, servo End Points are stationary. In order to balance servo travel, you would need to manually readjust the servo End Points, if desired.



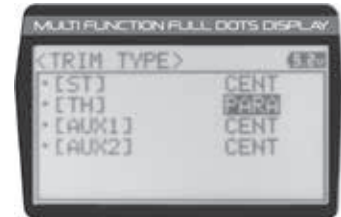
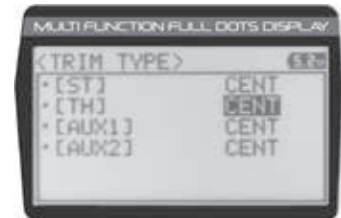
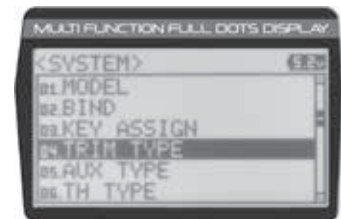
PARALLEL - When Selected, servo End Points shift toward the High Side or the Low Side automatically when you apply Trim. This maintains balanced servo travel without the need to manually readjust the servo End Points.



Changing the Trim Type:

- 1) From within the SYSTEM menu, scroll UP or DOWN to highlight the TRIM TYPE menu.
- 2) Press the ENTER key. The TRIM TYPE menu will be displayed and [ST] CENT will be highlighted.
- 3) Scroll UP or DOWN to highlight the desired channel you would like to change the Trim Type option for. Choose from either [ST] CENT (Steering), [TH] CENT (Throttle), [AUX1] CENT (Auxiliary 1) or [AUX2] CENT (Auxiliary 2).
- 4) Press the ENTER key, then scroll UP or DOWN to choose the desired Trim Type option for that channel.

TRIM TYPE setting range is CENT and PARA. The default setting for all channels is CENT.




SYSTEM

05. AUX TYPE [AUXILIARY TYPE]

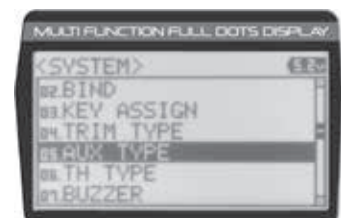
SYSTEM

The Auxiliary Type function allows you choose which Auxiliary function is assigned to Auxiliary 1 Channel 3 or Auxiliary 2 Channel 4. One Auxiliary function can be assigned to each Auxiliary Channel and both Auxiliary Channels can be Active and controlled at the same time using different controls. For example, you can control Auxiliary 1 Channel 3 using the Rotary Dial and Auxiliary 2 Channel 4 using the Auxiliary Lever.

 For details about programming and using each of the Auxiliary functions, in addition to selecting AUX Type Modes, see the Auxiliary 1 Programming section on pages 27 through 33 or the Auxiliary 2 Programming section on pages 34 through 40.

Changing the Auxiliary Function:

- 1) From within the SYSTEM menu, scroll UP or DOWN to highlight the AUX TYPE menu.



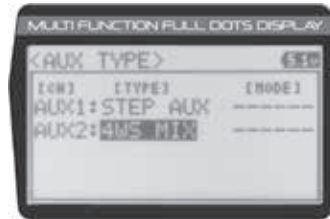
90478 2.4GHZ FH4T RADIO SYSTEM USER'S GUIDE

05.AUX TYPE (AUXILIARY TYPE)

SYSTEM

- 2) Press the ENTER key. The AUX TYPE menu will be displayed and AUX1:STEP AUX will be highlighted.
- 3) Scroll UP or DOWN to highlight the desired channel you would like to change the Auxiliary function for, either AUX1 [TYPE] (Auxiliary 1) or AUX 2 [TYPE] (Auxiliary 2).
- 4) Press the ENTER key, then scroll UP or DOWN to choose the desired Auxiliary function to be controlled by that channel.

AUX TYPE setting range is STEP AUX, POINT AUX, 4WS MIX, MOA MIX and AUX MIX. The default setting for both channels is STEP AUX.



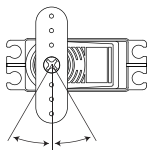
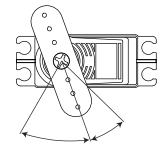
06.TH TYPE (THROTTLE TYPE)

SYSTEM

The Throttle Type function allows you to change the proportion between Throttle High Side servo travel and Throttle Brake Side servo travel. In the default configuration, the Throttle Type is set to F70:B30. This Throttle Type shifts the throttle Neutral Point toward the Brake Side, resulting in more servo travel toward the High Side and less servo travel toward the Brake Side. Some users may prefer the proportion between Throttle High Side servo travel and Throttle Brake Side servo travel to be balanced (F50:B50). The F70:B30 Throttle Type is most common for general use and racing, while the F50:B50 Throttle Type is most common for Rock Crawling.

Two Throttle Types are available:

F70:B30 - When Selected, the Throttle Neutral Point is shifted toward the Brake Side which provides more High Side servo travel and less Brake Side servo travel. This is most common for general use and racing.



F50:B50 - When Selected, the Throttle Neutral Point is centered, which provides the same amount of High Side and Brake Side servo travel. This is most common for Rock Crawling.

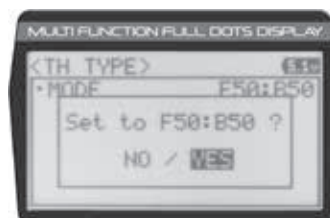
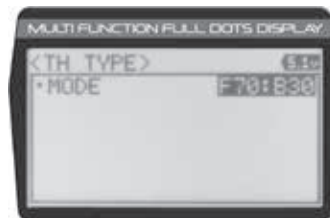
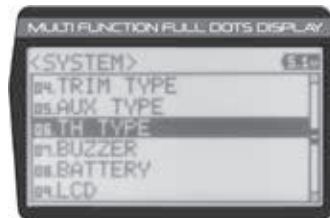
Changing the Throttle Type:

- 1) From within the SYSTEM menu, scroll UP or DOWN to highlight the TH TYPE menu.
- 2) Press the ENTER key. The TH TYPE menu will be displayed and MODE F70:B30 will be highlighted.
- 3) Press the ENTER key, then scroll UP or DOWN to choose the desired Throttle Type option.

TH TYPE setting range is F70:B30 and F50:B50. The default setting is F70:B30.

- 4) Press the ENTER key. Either Set to F70:B30? NO/YES will be displayed or Set to F50:B50? NO/YES will be displayed.
- 5) Scroll DOWN to highlight YES, then press the ENTER key to Activate the chosen Throttle Type.

 The current Throttle Type will be displayed on the Top Screen. 7:3 will be displayed to indicate the current Throttle Type is F70:B30 or 5:5 will be displayed to indicate the current Throttle Type is F50:B50.




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07. BUZZER (AUDIBLE KEY TONE)

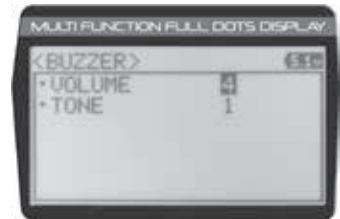
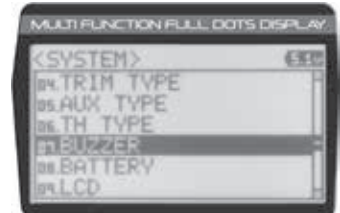
SYSTEM

The Audible Key Tone function allows you to change the Volume and Tone of the audible sounds that are made when you use the Trim Switches, Rotary Dial, Auxiliary Lever, Push-Button Rotary Dial and the Timer function. The Volume can be Increased or Decreased (or Muted) and the Tone can be changed to suit your preference.

 Changes made using the Audible Key Tone function also affect the audible sounds that are part of the Timer function. For example, if you Mute the Audible Key Tones, the sounds that are part of the Timer function will also be Muted. Transmitter warning alarms, such as the Low Voltage Alert alarm, are unaffected.

Changing the Audible Key Tone Volume:

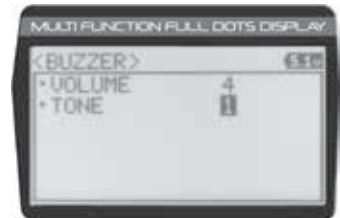
- 1) From within the SYSTEM menu, scroll UP or DOWN to highlight the BUZZER menu.
- 2) Press the ENTER key. The BUZZER menu will be displayed and VOLUME 4 will be highlighted.
- 3) Press the ENTER key, then scroll UP or DOWN to choose the desired Volume value. Increasing the Volume value will increase the Volume of the Audible Key Tones and decreasing the Volume value will decrease the Volume of the Audible Key Tones.



BUZZER VOLUME setting range is OFF to 5. The default setting is 4. When OFF is selected, Audible Key Tones will be Muted.

Changing the Tone:

- 1) From within the BUZZER menu, scroll DOWN to highlight TONE 1.
- 2) Press the ENTER key, then scroll UP or DOWN to choose the desired Tone value. Increasing the Tone value will increase the pitch of the Audible Key Tones and decreasing the Tone value will decrease the pitch of the Audible Key Tones.



BUZZER TONE setting range is 1 to 7. The default setting is 1.


08. BATTERY (VOLTAGE ALARM)

SYSTEM

The Voltage Alarm function allows to specify the voltage at which the transmitter Low Voltage Alert and Low Voltage Limit alarms will sound. This allows you to choose custom voltage settings to match the type of transmitter battery you're using. For example, if you're using a 6 cell NiMH battery pack or a 2S LiPo battery pack, you can set the Low Voltage Alert alarm and the Low Voltage Limit alarm voltage values to suit.

This table shows the different Alert and Limit Voltage values we recommend programming.

BATTERY TYPE	ALERT VOLTAGE	LIMIT VOLTAGE
4 Cell Alkaline	4.6 Volts	4.4 Volts
6 Cell Ni-CD/NiMH	7.0 Volts	6.6 Volts
2S LiPo	7.2 Volts	6.8 Volts
2S LiFe	6.3 Volts	5.8 Volts

 To ensure the safety of your model and your transmitter battery, we suggest using the Alert and Limit Voltage values shown in the table above. We don't suggest using values lower than recommended.

Changing the Low Voltage Alert Alarm Value:

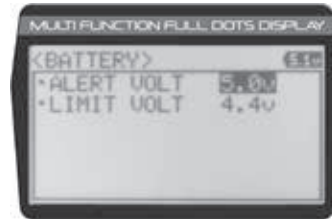
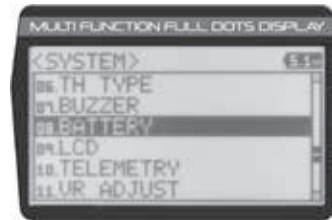
The Low Voltage Alert alarm will sound to indicate the transmitter batteries are getting low and should be replaced or recharged. We suggest stopping use as soon as safely possible and replacing or recharging the transmitter batteries. The Low Voltage Alert alarm will sound each time the transmitter battery voltage decreases by 0.1 volt. To clear this alarm, press the BACK/CANCEL key or the Push-Button Rotary Dial.

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08. BATTERY (VOLTAGE ALARM)

SYSTEM

- 1) From within the SYSTEM menu, scroll UP or DOWN to highlight the BATTERY menu.
- 2) Press the ENTER key. The BATTERY menu will be displayed and ALERT VOLT 4.6v will be highlighted.
- 3) Press the ENTER key, then scroll UP or DOWN to choose the desired Low Voltage Alert alarm value. Increasing the Low Voltage Alert alarm value will cause the Low Voltage Alert alarm to sound at a higher voltage and decreasing the Low Voltage Alert alarm value will cause the Low Voltage Alert alarm to sound at a lower voltage.



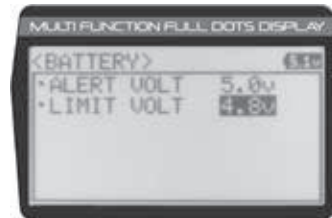
BATTERY ALERT VOLT setting range is 4.1v to 9.0v. The default setting is 4.6v.

! The Low Voltage Alert alarm voltage value cannot be set lower than the Low Voltage Limit alarm voltage value.

Changing the Low Voltage Limit Alarm Value:

The Low Voltage Limit alarm will sound to indicate the transmitter batteries are dangerously low and should be replaced or recharged right away. The Low Voltage Limit alarm cannot be cancelled. When the Low Voltage Limit alarm sounds, you should stop use as soon as it's safe, then replace or recharge the transmitter batteries.

- 1) From within the BATTERY menu, scroll DOWN to highlight LIMIT VOLT 4.4v.
- 2) Press the ENTER key, then scroll UP or DOWN to choose the desired Low Voltage Limit alarm value. Increasing the Low Voltage Limit alarm value will cause the Low Voltage Limit alarm to sound at a higher voltage and decreasing the Low Voltage Limit alarm value will cause the Low Voltage Limit alarm to sound at a lower voltage.



BATTERY LIMIT VOLT setting range is 4.0v to 4.9v. The default setting is 4.4v.

! The Low Voltage Limit alarm voltage value cannot be set higher than the Low Voltage Alert alarm voltage value.

WARNING: Continuing to use the transmitter after the Low Voltage Limit alarm sounds can result in loss of control of your model. When the Low Voltage Alert alarm sounds, stop use as soon as is safe, then replace or recharge the transmitter batteries.

09. LCD (LCD CONTRAST AND BACKLIGHT OPTIONS)

SYSTEM

The LCD menu allows you change the contrast of the LCD, the Backlight Mode and the Backlight On-Time. Changing the Contrast settings can make it easier to view the LCD in different lighting conditions and changing the Backlight Mode and Backlight On-Time affects how the Backlight is turned ON and how long the Backlight stays ON.

IMPORTANT: Leaving the LCD Backlight ON at all times will Increase battery consumption. In addition, Decreasing the Contrast value near the Lower limit can result in the LCD text becoming impossible to read. Be careful not to set the Contrast value too low.

Changing the LCD Contrast Value:

- 1) From within the SYSTEM menu, scroll UP or DOWN to highlight the LCD menu.

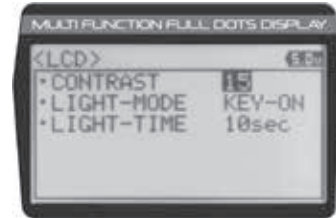


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09. LCD (LCD CONTRAST AND BACKLIGHT OPTIONS)

SYSTEM

- 2) Press the ENTER key. The LCD menu will be displayed and CONTRAST 15 will be highlighted.
- 3) Press the ENTER key, then scroll UP or DOWN to choose the desired LCD Contrast value. Increasing the LCD Contrast value will increase the Contrast of the LCD screen and decreasing the LCD Contrast value will decrease the Contrast of the LCD screen.



LCD CONTRAST setting range is 0 to 30. The default setting is 15. Decreasing the LCD Contrast value too much will make it impossible to read. We do not suggest using an LCD Contrast value lower than 7.

Changing the LCD Backlight Mode:

The LCD Backlight Mode option determines how the LCD Backlight operates. When set to OFF, the LCD Backlight will be turned OFF. When set to KEY-ON, the LCD Backlight will turn ON when a key-press is made. When set to ALWAYS, the LCD Backlight will stay ON at all times.

- 1) From within the LCD menu, scroll UP or DOWN to highlight LIGHT-MODE KEY-ON.
- 2) Press the ENTER key, then scroll UP or DOWN to choose the desired LCD Mode value. Choose from OFF, KEY-ON or ALWAYS.



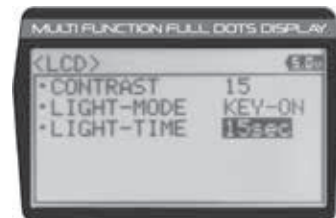
LIGHT-MODE setting range is OFF, KEY-ON and ALWAYS. The default setting is KEY-ON.

Changing the LCD Backlight On-Time:

The LCD Backlight On-Time option determines how long the LCD Backlight will stay ON before turning OFF automatically.

- 1) From within the LCD menu, scroll UP or DOWN to highlight LIGHT-TIME 10sec.
- 2) Press the ENTER key, then scroll UP or DOWN to choose the desired LCD Time value. The Time value (in seconds)

 If the Backlight Mode is set to ALWAYS or OFF, the LCD Backlight On-Time value cannot be adjusted.




LIGHT-TIME setting range is 1 to 30 seconds. The default setting is 10 seconds.

10. TELEMETRY (TELEMETRY DISPLAY OPTIONS)

SYSTEM

The Telemetry menu allows you to change different options to configure how the various Telemetry functions are displayed on the Telemetry Screen and how the Telemetry Logger operates. For example, you are able to change the Telemetry Temperature reading from Fahrenheit to Celsius, change the values at which Telemetry Sensor alarms sound, change how Speed and RPM are displayed and much more. In addition, you are also able to change the Telemetry Log Interval to customize how much Telemetry Data can be stored for review later.

IMPORTANT: Full telemetry support requires the use of an Airtronics 2.4GHz FH4T telemetry-capable surface receiver, such as the RX-461 or RX-462, along with Airtronics Temperature and RPM Sensors (available separately). The included RX-472 receiver can send Telemetry Data for the voltage of the receiver battery pack only, unless used with the Airtronics Super Vortex ZERO ESC (available separately) plugged into the BATT/SSL port of the included RX-472 receiver.

 For information about using an optional Telemetry receiver with your 90478 transmitter and installing Telemetry Sensors into your model, see the Telemetry Connections and Mounting section on pages 69 and 70.


TEMP1 AND TEMP2 SETTING (Temperature Telemetry Display Options)

The Temperature 1 and Temperature 2 Settings allow you change how Temperature information is displayed on the Telemetry Screen and when the Temperature Alert alarm sounds.

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10. TELEMETRY (TELEMETRY DISPLAY OPTIONS)

SYSTEM

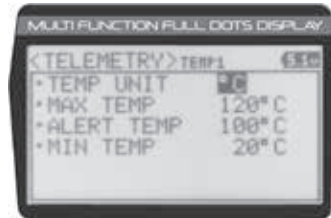
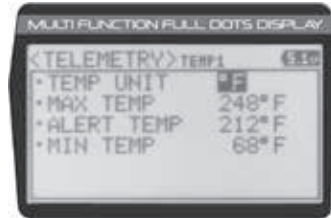
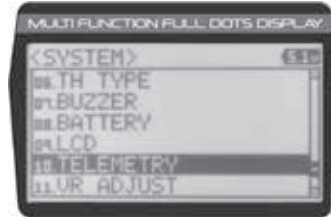
 This section covers both the TEMP1 and TEMP2 menus, since programming each of them is exactly the same. Choose either the TEMP1 or the TEMP2 menu depending on which of the two Temperature Sensor Ports you want to make changes to.

Changing the Temperature Unit Value:

If desired, the Temperature Unit value can be changed from Fahrenheit to Celsius.

- 1) From within the SYSTEM menu, scroll UP or DOWN to highlight the TELEMETRY menu.
- 2) Press the ENTER key. The TELEMETRY menu will be displayed and TEMP1 SETTING will be highlighted.
- 3) Scroll UP or DOWN to highlight TEMP1 SETTING or TEMP2 SETTING.
- 4) Press the ENTER key. The TEMP1 or TEMP2 menu will be displayed and TEMP UNIT °F will be highlighted.
- 5) Press the ENTER key, then scroll UP or DOWN to change the Temperature Unit to the desired value.

TELEMETRY TEMP UNIT setting range is °F and °C. The default setting is °F.



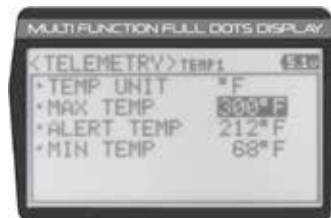
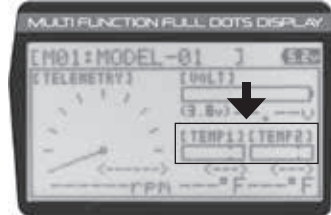
Changing the Maximum Temperature Value:


The Maximum Temperature value determines the maximum temperature shown on the [TEMP1] or [TEMP2] Telemetry Screen Temperature Display Monitors. This allows you to calibrate each Temperature Display Monitor to match what the Temperature Sensor is attached to. This setting does not effect the TEMP1 or TEMP2 Digital Displays.

 The tick marks in the Temperature Display Monitors indicate the current temperature relative to the programmed Maximum and Minimum Temperature values.

- 1) From within the TEMP1 or TEMP2 menu, scroll UP or DOWN to highlight MAX TEMP 248°F (or 120°C).
- 2) Press the ENTER key, then scroll UP or DOWN to change the Maximum Temperature value. The Temperature Display Monitor on the Telemetry Screen will not display temperature values above the Maximum Temperature value programmed.

TELEMETRY MAX TEMP setting range is 68°F to 302°F (0°C to 150°C). The default setting is 248°F (120°C).



 The Maximum Temperature value cannot be set lower than the Alert Temperature value or the Minimum Temperature value. In some cases, you may need to lower the Alert Temperature value prior to lowering the Maximum Temperature value.

Changing the Alert Temperature Value:

The Alert Temperature value determines the temperature at which the Temperature Alert alarm will sound. For example, you can set an Alert Temperature value for your Nitro engine that will alert you when your engine's cylinder head temperature is getting too hot.

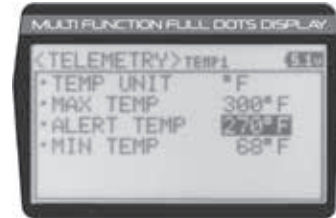
When the Alert Temperature value is reached, the Temperature Alert alarm will sound and LED2 (Red) will flash. The Temperature Alert alarm will sound for approximately 5 seconds, however, LED2 will continue to flash until the temperature drops below the Alert Temperature value. The audible portion of the Temperature Alert alarm can be cleared by pressing the BACK/CANCEL key or the Push-Button Rotary Dial.

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10. TELEMETRY (TELEMETRY DISPLAY OPTIONS)

SYSTEM

- 1) From within the TEMP1 or TEMP2 menu, scroll UP or DOWN to highlight ALERT TEMP 212°F (or 100°C).
- 2) Press the ENTER key, then scroll UP or DOWN to change the Alert Temperature value. The Alert Temperature value is the temperature that the Temperature Alert alarm will sound at.

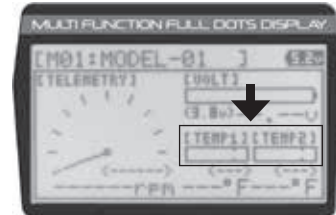


TELEMETRY ALERT TEMP setting range is 68°F to 302°F (0°C to 150°C). The default setting is 212°F (100°C).

! The Alert Temperature value cannot be set higher than the Maximum Temperature value. In addition, the Alert Temperature value cannot be set lower than the Minimum Temperature value. In some cases, you may need to lower the Minimum Temperature value prior to lowering the Alert Temperature value.

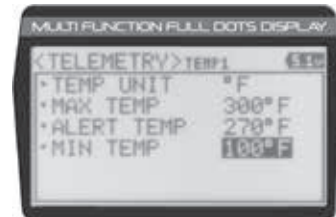
Changing the Minimum Temperature Value:

The Minimum Temperature value determines the Minimum temperature shown on the [TEMP1] or [TEMP2] Telemetry Screen Temperature Display Monitors. This allows you to calibrate each Temperature Display Monitor to match what the Temperatures Sensor is attached to. This does not effect the TEMP1 or TEMP2 Digital Displays.



! The tick marks in the Temperature Display Monitors indicate the current temperature relative to the programmed Maximum and Minimum Temperature values.

- 1) From within the TEMP1 or TEMP2 menu, scroll UP or DOWN to highlight MIN TEMP 68°F (or 20°C).
- 2) Press the ENTER key, then scroll UP or DOWN to change the Minimum Temperature value. The Temperature Display Monitor on the Telemetry Screen will not display temperature values below the Minimum Temperature value programmed.



TELEMETRY MIN TEMP setting range is 32°F to 302°F (0°C to 150°C). The default setting is 68°F (20°C).

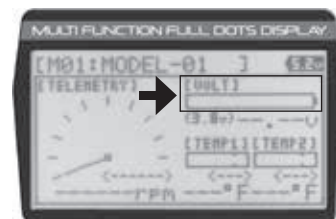
! The Minimum Temperature value cannot be set higher than the Alert Temperature value or the Maximum Temperature value. In some cases, you may need to increase these values prior to increasing the Minimum Temperature value.

VOLT SETTING (Receiver Battery Voltage Telemetry Display Options)

The Voltage Setting allows you to change the way receiver battery Voltage information is displayed on the Telemetry Screen and when the Voltage Alert alarm sounds. For example, you can adjust the Voltage value that the receiver battery Low Voltage Alert alarm will sound at to match the type of receiver battery you're using.

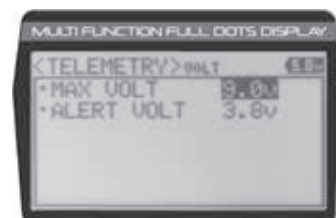
Changing the Maximum Voltage Value:

The Maximum Voltage value determines the maximum receiver battery Voltage that will be shown on the [VOLT] Telemetry Screen Display Monitor. This allows you to calibrate the Voltage Display Monitor to match your model's receiver battery. This setting does not effect the VOLT Digital Display.



PRO TIP: We suggest using a value that matches as closely as possible the peaked voltage value of your receiver battery after it's pulled off your charger.

- 1) From within the TELEMETRY menu, scroll UP or DOWN to highlight VOLT SETTING.
- 2) Press the ENTER key. The VOLT menu will be displayed and MAX VOLT 9.0v will be highlighted.



SYSTEM

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10. TELEMETRY (TELEMETRY DISPLAY OPTIONS)

SYSTEM

- 3) Press the ENTER key, then scroll UP or DOWN to change the Maximum Voltage value. The Voltage Display Monitor on the Telemetry Screen will not display receiver battery Voltage values above the Maximum Voltage value programmed.

TELEMETRY MAX VOLT setting range is 3.0v to 9.0v. The default setting is 9.0v.

! The Maximum Voltage value cannot be set lower than the Alert Voltage value. If necessary, you may need to lower the Alert Voltage value prior to lowering the Maximum Voltage value.

Changing the Alert Voltage Value:

The Alert Voltage value determines the voltage at which the Voltage Alert alarm will sound. For example, you can set the Alert Voltage value to alert you to when your model's receiver battery is getting low and needs to be recharged. When the Alert Voltage value is reached, the Voltage Alert alarm will sound and LED2 (Red) will flash. The Voltage Alert alarm will sound for approximately 5 seconds, however, LED2 will continue to flash until you recharge the receiver battery. The audible portion of the Voltage Alert alarm can be cleared by pressing the BACK/CANCEL key or the Push-Button Rotary Dial.

! In general, the Alert Voltage value should be high enough to alert you when it's time to recharge your receiver battery, but not so low that the receiver battery loses power and can no longer control your model.

- 1) From within the VOLT menu, scroll UP or DOWN to highlight ALERT VOLT 3.8v.
- 2) Press the ENTER key, then scroll UP or DOWN to change the Alert Voltage value. The Alert Voltage value is the voltage that the Voltage Alert alarm will sound at.

TELEMETRY ALERT VOLT setting range is 3.0v to 9.0v. The default setting is 3.8v.

! The Alert Voltage value cannot be set higher than the Maximum Voltage value. In some cases, you may need to raise the Maximum Voltage value prior to raising the Alert Voltage value.

RPM SETTING (RPM and Speed Telemetry Display Options)

The RPM Setting allows you to change the way RPM and Speed information is displayed on the Telemetry Screen. For example, you can choose to display RPMs, MPH or KM/H. The RPM Gauge and the RPM Digital Displays will change from RPM to MPH or KM/H depending on the RPM Unit value chosen. In addition, if MPH or KM/H is chosen, the RPM sensor can be calibrated to ensure that the most accurate speed is displayed for your specific model.

Changing the RPM Unit Value:

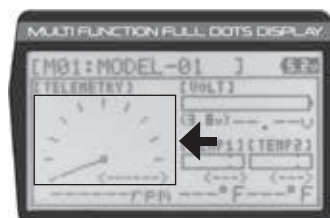
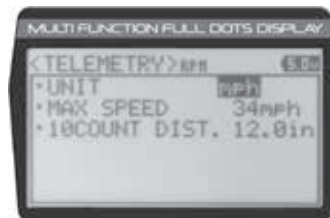
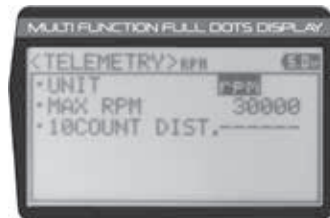
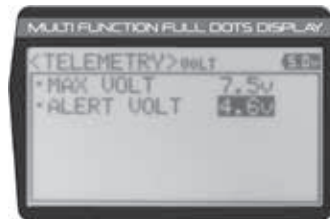
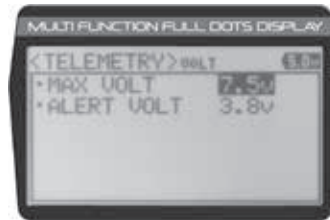
- 1) From within the TELEMETRY menu, scroll UP or DOWN to highlight RPM SETTING.
- 2) Press the ENTER key. The RPM menu will be displayed and UNIT RPM will be highlighted.
- 3) Press the ENTER key, then scroll UP or DOWN to change the RPM Unit to the desired value. When RPM is chosen, the Revolutions Per Minute of whatever the RPM Sensor is attached to will be displayed. When MPH or KM/H is chosen, the speed of your model will be displayed in either Miles Per Hour or Kilometers Per Hour, respectively.

TELEMETRY RPM UNIT setting range is RPM, MPH and KM/H. The default setting is RPM.

Changing the Maximum RPM/Speed Value:

The Maximum RPM/Speed value determines the maximum RPM or Speed value that will be shown on the Telemetry RPM Gauge. This setting does not effect the RPM or Speed Digital Display.

! The RPM Gauge and RPM/Speed Digital Display names will change from RPM to MPH or KM/H depending on the RPM Unit value chosen.

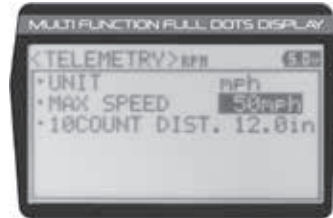


90478 2.4GHZ FH4T RADIO SYSTEM USER'S GUIDE

10. TELEMETRY (TELEMETRY DISPLAY OPTIONS)

SYSTEM

- 1) From within the RPM menu, scroll UP or DOWN to highlight MAX RPM 30000 (or MAX SPEED 34mph or MAX SPEED 54km/h).
- 2) Press the ENTER key, then scroll UP or DOWN to change the Maximum RPM or Maximum Speed value. The RPM Gauge on the Telemetry Screen will not display RPM or Speed values above the Maximum value programmed.



TELEMETRY MAX RPM setting range is 500 to 127500. The default setting is 30000. TELEMETRY MAX SPEED setting range is 1mph to 335mph (1km/h to 539km/h). The default setting is 34mph (54km/h). The Maximum Speed setting range will vary based on the 10 Count Distance value programmed when you calibrate the RPM Sensor. For more information, see the Calibrating the RPM Sensor section on page 67.

Calibrating the RPM Sensor - Changing the 10Count Distance Value:

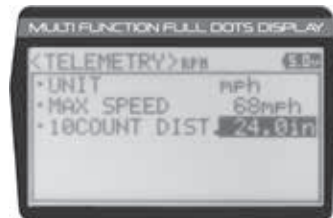
The 10Count Distance value can be changed if you've Selected UNIT MPH or UNIT KM/H. By changing the 10Count Distance value you are able to calibrate the RPM sensor to read your specific model's actual speed, in either MPH or KM/H.

! RPM Sensor calibration is only required if you choose to use the RPM Sensor to display MPH or KM/H. Calibration is not required if you're displaying RPM.

! Prior to calibrating the RPM sensor, you must connect the RPM sensor to your receiver and correctly install the RPM sensor into your model. For more information, see the Telemetry Connections and Mounting section on pages 69 and 70.

IMPORTANT: When the reflective tape attached to your model's spur gear, pinion gear, etc., crosses the RPM sensor, the Bind LED on the receiver will flash green once, indicating 1 full revolution. Use this as a guide during the calibration process.

- 1) With your transmitter and receiver turned ON, and with an Active Telemetry connection, place your model on the ground.
- 2) Measuring in inches (or centimeters if using KM/H) from where you set your model on the ground, slowly push your model and measure the distance covered to complete 10 full revolutions of the RPM sensor (the Bind LED on your receiver will flash green 10 times, indicating 10 full revolutions).
- 3) From within the RPM menu, scroll UP or DOWN to highlight 10COUNT DIST. 12.0in (or 10COUNT DIST. 30cm).
- 4) Press the ENTER key, then scroll UP or DOWN to change the 10 Count Distance value to the measurement obtained in step 2 above. For example, if your model traveled 2 feet (61cm) to complete 10 full revolutions, enter 24.0in (61cm).



TELEMETRY 10COUNT DIST setting range is 0.5in to 118.0in (1cm to 300cm). The default setting is 12.0in (30cm).

IMPORTANT: Changing the 10Count Distance value will change the Maximum Speed value. After calibration, you should reset the Maximum Speed value back to the value you chose previously.

TELEMETRY SETTING (Telemetry ON/OFF and Telemetry Log Options)

The Telemetry Setting allows you to choose whether the Telemetry System is turned ON or OFF and change the interval that Telemetry Data is read and stored.

The interval that Telemetry Data is read and stored can be adjusted so that Telemetry Data can be stored for up to 90 minutes of use. The Telemetry Log can store 120 different data entries at intervals ranging from 00.1 seconds to 45.9 seconds.

Turning the Telemetry System ON and OFF:

- 1) From within the TELEMETRY menu, scroll UP or DOWN to highlight TELEMETRY SETTING.
- 2) Press the ENTER key. The SETTING menu will be displayed and ON/OFF ON will be highlighted.



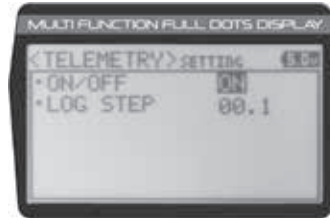
90478 2.4GHZ FH4T RADIO SYSTEM USER'S GUIDE

10. TELEMETRY (TELEMETRY DISPLAY OPTIONS)

SYSTEM

- 3) Press the ENTER key, then scroll UP or DOWN to change the Telemetry ON/OFF value. When ON is selected, the Telemetry System is turned ON. When OFF is selected, the Telemetry System is turned OFF.

TELEMETRY SETTING ON/OFF setting range is ON or OFF. The default setting is ON.



Changing the Telemetry Log Step Value:

The Telemetry Log Step value can be changed to customize how much Telemetry Data and the time interval Telemetry Data is recorded. The Telemetry Log can store up to 120 separate entries. If the Log Step value is set to 00.1 seconds, the Telemetry Log can record for 12 seconds. If the Log Step value is set to 45.1 seconds, the Telemetry Log can record for 90 minutes.

- 1) From within the SETTING menu, scroll UP or DOWN to highlight LOG STEP 00.1.
- 2) Press the ENTER key, then scroll UP or DOWN to change the Telemetry Log Step value. Programming a lower Telemetry Log Step value results in narrower, higher resolution readings, but for a shorter period of time. Programming a higher Telemetry Log Step value results in broader, lower resolution readings, but for a longer period of time.

TELEMETRY LOG STEP setting range is 00.1 to 45.9. The default setting is 00.1.



TE-CLEAR (Telemetry Clear Function)

The Telemetry Clear function allows you to Reset the High Temperature 1, High Temperature 2 and High RPM values that are displayed on the Telemetry Screen. The Telemetry Clear function can be assigned to either Push-Button Switch Sw1 or Push-Button Switch Sw2. When you press the Push-Button Switch the Telemetry Clear function is assigned to, the High Temperature 1, High Temperature 2 and High RPM values will be Reset the Current values read by the Telemetry Sensors. For more information see the Push-Button Key Assignments section on pages 53 through 58.

11. VR ADJUST (VARIABLE RATE ADJUSTMENT)

SYSTEM

The Variable Rate Adjustment function allows you to calibrate the operation of the Steering Wheel, Throttle Trigger and Auxiliary Lever End Points and Neutral positions. Over time, it's possible that the End Points and/or Neutral positions of these controls may change slightly or you may purposely limit the travel of the Steering Wheel to suit the best feel of the Steering Wheel and your driving style. Being able to calibrate these controls ensures precise operation at all times and in all conditions.

- ! We recommend using the Variable Rate Adjustment function as part of a periodic maintenance schedule or after adjusting the Steering Wheel travel as described in the Steering Wheel Travel Adjustment section on page 13.

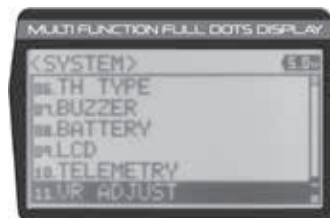
IMPORTANT: After using the Variable Rate Adjustment function, you should double-check the End Point Adjustments of each saved Model. If the End Points have moved, they will need to be readjusted using the End Point Adjustment function.

- ! The steps required to calibrate the operation of the Steering Wheel, Throttle Trigger and Auxiliary Lever are the same. The example shown in this section details calibrating the Throttle Trigger.

Calibrating Control Operation:

- 1) From within the SYSTEM menu, scroll UP or DOWN to highlight the VR ADJUST menu.
- 2) Press the ENTER key. The VR ADJUST menu will be displayed and STEERING <0> will be highlighted.
- 3) Scroll UP or DOWN to highlight the control you would like to calibrate. Choose from STEERING <0>, THROTTLE <0> or LEVER <0>.

- ! <0> indicates the current position of the specific channel relative to its specific control. For example, if the Throttle Trigger is in the Neutral position, but an H or B value is displayed, the Throttle Channel 2 Neutral position has shifted and should be recalibrated.



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11.VR ADJUST (VARIABLE RATE ADJUSTMENT)

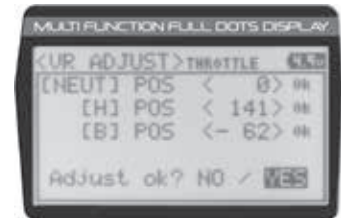
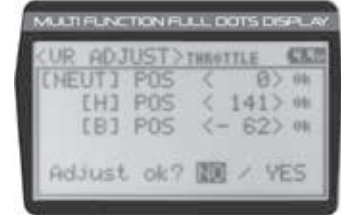
SYSTEM

- 4) With the Steering Wheel, Throttle Trigger or Auxiliary Lever in the Neutral position, press the ENTER key. [NEUT] POS <----> will be displayed.

 The Auxiliary Lever features a detent to indicate its Neutral position.

- 5) Press the ENTER key a second time. A menu with several position indicators will be displayed.
- 6) Move the Steering Wheel, Throttle Trigger or Auxiliary Lever all the way in one direction. Allow the control to return to Neutral, then move the Steering Wheel, Throttle Trigger or Auxiliary Lever all the way in the opposite direction. A series of values and Adjust ok? NO/YES will be displayed.

- 7) Scroll DOWN to highlight YES, then press the ENTER key. Executed will flash, indicating that the calibration process is complete.




 To cancel the calibration process, scroll UP or DOWN to highlight NO, then press the ENTER key. You can then return to VR ADJUST menu by pressing the BACK/CANCEL key.

- 8) If desired, repeat steps 3 through 7 to calibrate the remaining controls.

TELEMETRY CONNECTIONS AND MOUNTING


REFERENCE

When used with an Airtronics 2.4GHz FH4T Telemetry-capable surface receiver, such as the RX-461 or RX-462, and up to two Temperature Sensors and an RPM Sensor (all available separately), Telemetry Data, such as RPM or Speed, Temperature, and Receiver Voltage can be viewed on the M12 transmitter's Telemetry Screen. This section details connecting the RPM and Temperature Sensors to the RX-461 and/or RX-462 receiver and how to mount those Sensors into your model. For more information about the specifics of either receiver, refer to the User's Guide included with your receiver.

 For more information about viewing Telemetry Data on the Telemetry Screen, see the TELEMETRY Screen section on pages 14 and 15. For more information about choosing Telemetry options, see the Telemetry Display Options section on pages 63 through 68.


Overview:

The RX-461 and RX-462 receivers each feature two Temperature Sensor Inputs and one RPM Sensor Input, in addition to the Voltage Sensor built into the receiver. Temperature and RPM Sensors can be installed into your model to give you Temperature and RPM or Speed feedback in real-time displayed on the transmitter's Telemetry Screen.

 The range of the Telemetry System is approximately 260 feet (80 meters), although the range can vary based on many environmental factors. Use the Telemetry Signal Indicator to determine the quality of the Telemetry Signal.

Plugging the Telemetry Sensors into the Receiver:

- 1) Carefully pry up and remove the plastic cover from over the Telemetry Sensor Input Ports on the receiver.
- 2) Plug the Telemetry Sensor(s) into their respective Input Ports in the receiver. The Temperature Sensor can be plugged into either the TEMP 1 or the TEMP 2 Input Port and the RPM Sensor is plugged into the RPM Input Port. The Sensor Plugs are indexed so they can be plugged in only one way.

 Make sure to push the Sensor Plugs firmly in place to ensure a good connection. When routing Sensor Wires inside your model, be careful that they cannot come into contact with any moving parts. The Sensor Wires should be securely mounted and protected against damage.

In addition, install the dust covers included with your receiver to prevent dirt and debris from getting into any unused Input Ports.

90478 2.4GHZ FH4T RADIO SYSTEM USER'S GUIDE

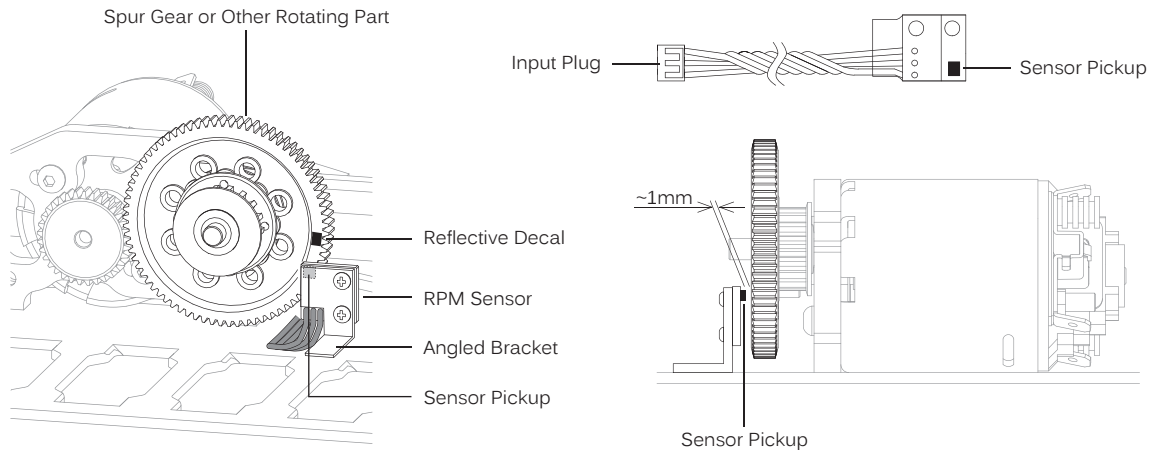
TELEMETRY CONNECTIONS AND MOUNTING

REFERENCE

IMPORTANT: If the Sensor Wires are not long enough for your specific application, you can carefully splice in extra wire of similar gauge to extend the Sensor Wires to the desired length. Make sure to solder the splices securely together and protect the splices using heat-shrink tubing.

Mounting the RPM Sensor:

The RPM Sensor uses infrared technology to record RPM data from a rotating part, such as a flywheel or a spur gear. One Black and one White reflective decal is included that is attached to the rotating part so the Sensor Pickup can 'see' it.



- 1) Mount the RPM Sensor to an aluminum or ABS angled bracket, then mount the bracket to your model, making sure that it's held securely in place.

IMPORTANT: For optimal operation, the Sensor Pickup should be positioned approximately 1mm away from the rotating part (flywheel, spur gear, pinion gear etc.)

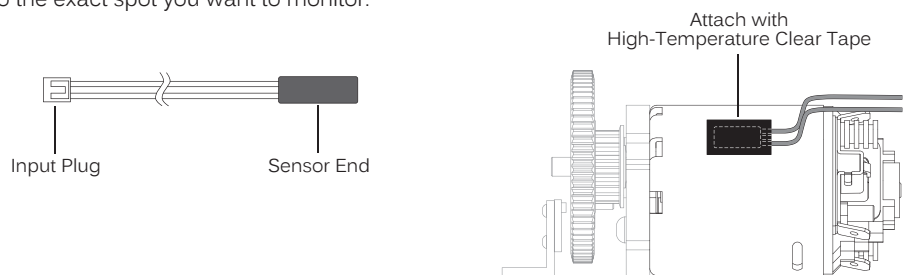
- 2) Cut one of the two reflective decals included with the RPM Sensor into an ~2mm diameter and apply it to the rotating part, so that as the part rotates, the reflective decal passes in Front of the Sensor Pickup. If the rotating part is metallic-colored (silver, aluminum, chrome, etc.), use the Black reflective decal and if the rotating part is dark-colored (black, blue or another dark color), use the White reflective decal.

IMPORTANT: When installed, it's important that the Sensor Pickup face the rotating part and that the Black or White reflective decal is positioned so that it passes in Front of the Sensor Pickup. It's also important that the reflective decal contrasts with the rotating part it's applied to and that the Sensor Pickup is mounted approximately 1mm away from the rotating part.

! After installing the RPM Sensor and connecting it to your receiver, the RPM Sensor must be calibrated. For more information, see the RPM and Speed Telemetry Display Options section on pages 63 through 68.

Mounting the Temperature Sensor:

- 1) Secure the Sensor End directly against the part of your engine, motor, battery or other object you want to monitor temperature readings from, using either a nylon cable tie or high-temperature clear tape. For example, to monitor the cylinder head temperature of your glow-powered model, the best place to secure the Sensor End is where the bottom of the cylinder head meets the top of the engine case. The Sensor End can be held in place using a nylon cable tie wrapped around your engine. To monitor the temperature of your battery pack or electric motor, high-temperature clear tape can be used to secure the Sensor End to the exact spot you want to monitor.



90478 2.4GHZ FH4T RADIO SYSTEM USER'S GUIDE

TROUBLESHOOTING GUIDE

REFERENCE

This troubleshooting guide can help you diagnose and solve some of the more common problems that you might encounter with your radio control system.

If you cannot solve the problem using this troubleshooting guide, please contact Airtronics Customer Service using the information in the Service and Support section on page 3.

PROBLEM	CAUSE	SOLUTION
Transmitter does not turn ON	Transmitter batteries installed incorrectly	Reinstall batteries, observing correct polarity
	Battery tray not plugged in	Plug in battery tray
	Transmitter batteries are dead	Replace or recharge transmitter batteries
	Damage caused by using incorrect charger or reverse polarity	Contact Airtronics Customer Service
Transmitter will not bind to receiver	Modulation Type incorrect	Change Modulation Type to match receiver
	Too much time elapsed after pressing receiver Bind Button	Quickly press ENTER key in BIND menu after releasing receiver Bind Button
	Attempting to Bind incompatible receiver	Use only Airtronics 2.4GHz FH2, FH3 or FH4T surface receivers
	Using Electronic Speed control (ESC)	Disconnect ESC and use dry cell battery for Binding procedure, then reconnect ESC after Binding
	Receiver batteries are dead	Replace or recharge receiver batteries
	Using incorrect Binding procedure	Follow Binding procedure carefully
Receiver won't power ON	Receiver batteries are dead	Replace or recharge receiver batteries
	Receiver batteries not installed correctly	Reinstall receiver batteries, observing correct polarity
	Loose switch connection	Double-check all connections including switch
Audible alarm beeps continuously	Low transmitter battery voltage	Replace or recharge transmitter batteries
	Transmitter left ON 10 minutes or more without control input	Move Steering Wheel or Throttle Trigger, or press any key to clear alarm and continue operation
	Transmitter battery voltage too high	Use transmitter battery whose voltage is 9.6 volts or less when fully charged
One or more LEDs flashing	Indicates transmitter status	For more information, see LED Condition Indicators table on page 10.
No key-press or Timer function sounds	Key Tones are Muted	Increase Key Tone volume in BUZZER menu
Servo movement is slow	Low receiver battery voltage	Replace or recharge receiver batteries
	Control linkages binding	Adjust control linkages to operate smoothly
	Using a negative Servo Speed value	Increase Servo Speed value
Servo does not move when using Trim Switch	Trim is outside of operational range	Center Trim Switches to '0', center the servo horn and control linkages
Inadequate transmitting range	Low transmitter battery voltage	Replace or recharge transmitter battery
	Low receiver battery voltage	Replace or recharge receiver batteries
	Receiver antenna not mounted correctly	Mount receiver antenna as recommended
Servo(s) move the wrong direction	Incorrect Servo Reversing setting	Change Servo Reversing setting
Servo Horn(s) not centered	Servo horn not installed correctly	Turn servo horn 180° and reinstall
	Servo Sub-Trim out of adjustment	Adjust Servo Sub-Trim to center servo horn
Control linkage(s) bind	Too much servo travel	Decrease servo travel using EPA function
Servo moves too much or not enough when Trim Switch is pressed	Trim Step resolution requires adjustment	Adjust Trim Step resolution
Throttle servo moves to programmed position without input	Receiver battery voltage has reached programmed Receiver Battery Voltage Fail Safe voltage value	Replace or recharge the receiver batteries
Can't program Receiver Battery Voltage Fail Safe	Throttle channel Fail Safe value set to FREE or HOLD	Set Throttle channel Fail Safe to a percentage value
	Using FH2 Receiver	This function is not supported with FH2 receivers
No Telemetry connection	Telemetry System turned OFF	Turn Telemetry System ON
	Outside of Telemetry range	Move transmitter closer to receiver in model

REFERENCE

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PROBLEM	CAUSE	SOLUTION
RPM Sensor not functioning	Sensor not facing reflective decal	Mount Sensor so it faces rotating part/reflective decal
	Sensor too far away from rotating part	Mount Sensor closer to rotating part
	Not using reflective decal	Apply contrasting reflective decal to rotating part
LCD is difficult to read	Contrast setting too high or too low	Readjust contrast setting
	LCD Backlight is turned OFF	Turn LCD Backlight ON
There is no LCD Backlight	LCD Backlight is turned OFF	Set LCD LIGHT-MODE to Key-On or Always
LCD Backlight keeps turning OFF	LCD LIGHT-MODE is set to Key-On	This is normal to save battery power. Increase TIME value or set LCD LIGHT-MODE to Always
Throttle servo pulsates	ABS function is Active	This is normal under Braking with the ABS Active
Model veers right or left without control input	Steering out of trim	Use Steering Trim Switch to adjust Steering Trim so model drives straight
Model accelerates without control input	Throttle out of trim	Use Throttle Trim Switch to adjust Throttle Neutral Point
	Throttle Offset function is Active	Turn Throttle Offset function OFF
Model seems extremely sensitive to control input	Dual Rate value(s) set too high	Decrease Dual Rate value(s)
	Controls out of adjustment	Use the VR Adjust function to calibrate controls
Servo(s) and/or ESC don't operate at all or operate erratically	Using incorrect Servo Mode setting	Use correct Servo Mode setting based on the type of servos you're using in your Model. Use NOR mode for Throttle channel if using ESC
Direction of travel shown on Servo Monitor is different from control input travel	This is normal	Direction of travel displayed will vary depending on Servo Reversing settings
Can't control underscore when changing Model Name or User Name	Cursor is Active in Character Select screen	Press BACK key to re-gain control of underscore
Can't clear Lap Timer	This is normal	Lap Timer will clear when you Start the Lap Timer again
Steering Wheel and/or Throttle Trigger won't center	Spring tension set too loose	Tighten spring tension
Controls don't operate as expected	Controls out of adjustment	Use the VR Adjust function to calibrate controls
CODE Auxiliary function does not work	Using incorrect receiver and/or Accessories	Must use Airtronics or Sanwa receiver and accessories that support Sanwa Synchronized Link (SSL)
Cannot control Auxiliary functions	Auxiliary Type not selected and/or AUX1 or AUX2 not assigned to a Trim Switch, Rotary Dial or Auxiliary Lever	Must first choose Auxiliary Type and ensure AUX1 and/or AUX2 are assigned to a Trim Switch, Rotary Dial or Auxiliary Lever

GLOSSARY OF TERMS

REFERENCE

Activate: To turn ON a particular function.

Antenna: Transmits the signal from the transmitter to the receiver in the model. Never touch the Antenna during use. Doing so may result in a weakened RF signal or complete loss of control of your model.

Antenna Reception Wire: The portion of the receiver antenna that receives the transmitter signal. The Antenna Reception Wire should never be bent or it could be damaged and limit the range of your model.

Anti-Lock Braking: Makes it possible to achieve stable braking even on slippery surfaces. With stable braking, your model is better able to trace an exact line under braking.

ARC: Adjustable Rate Control (ARC) allows you to vary the amount of servo travel in relation to the movement of the steering wheel, throttle trigger and auxiliary lever near the Neutral positions to change the way those functions react to control movement. The position that the Rate can be controlled from is adjustable along the length of control travel.

Audible Key Tone: An audible tone that is emitted from the transmitter each time the Push-Button Rotary Dial, Trim Switch, Push-Button Switch or Rotary Dial is used.

Auxiliary Lever: The Auxiliary Lever is programmable and will perform a different function depending on what function is assigned to it. For example, it can be used to control Auxiliary 1 Channel 3 or to control the Servo Speed function. The Auxiliary Lever features a detent and an audible tone to let you know it's in the Neutral position.

Auxiliary Lever Position Display: Displays the current position of the Auxiliary Lever on the Top Screen.

Auxiliary Mixing: Allows you to Mix either Steering Channel 1 or Throttle Channel 2 to Auxiliary 1 Channel 3 or Auxiliary 2 Channel 4, while maintaining separate Sub-Trim, End Point Adjustments, Servo Reversing and other channel-specific settings. The Auxiliary Mixing function is used when a custom Mix is necessary.

BACK/CANCEL Key: Returns to the previous menu. Press and HOLD to return to the Top Screen. In addition, cancels certain warning alarms, such as the Low Voltage Alert alarm.

90478 2.4GHZ FH4T RADIO SYSTEM USER'S GUIDE

GLOSSARY OF TERMS

REFERENCE

Battery Compartment: Houses the four 'AA' Alkaline cells that power the transmitter. Alternatively, the transmitter can be powered using four 'AA' NiCd or NiMH rechargeable batteries or a 2S LiPo or 2S LiFe battery pack.

Binding: The act of pairing the transmitter and receiver to prevent interference from transmitters operated by other users. The transmitter and receiver must be paired so that the two can 'talk' to each other. Once the Binding process is complete, the setting is remembered even when the transmitter and receiver are turned OFF.

Bind Button: Used in the process of Binding the transmitter and receiver.

Bind LED: Displays the current status of the receiver.

Brake Side: Refers to the throttle trigger stroke that engages the brakes on your model (pushing the throttle trigger).

Burn: Used with the Motor on Axle function (dual ESCs), the front motor is inhibited while keeping full control of the rear motor during rock crawling.

Center Trim Type: A Trim technology, that when selected, the servo End Points remain stationary when you apply Trim using the Trim Switches. This can result in unbalanced servo travel. In order to balance servo travel, servo End Points need to be manually readjusted.

Channel Set: Allows you to make programming changes to each of the four channels without the need to enter each Programming Menu separately.

Charging Jack: Used for onboard charging of optional NiCd or NiMH batteries. Do not attempt to charge Alkaline batteries. Only the recommended Airtronics 110v AC charger should be used through the Charging Jack. If using an after-market Peak-Detection charger or other type of fast charger, the batteries should be removed from the transmitter to avoid damage to the transmitter circuitry and/or your batteries. Do not attempt to charge a LiPo or LiFe battery pack through the Charging Jack.

Coaxial Cable: The portion of the receiver antenna that extends the Antenna Reception Wire. The Coaxial Cable can be bent into gentle curves, however, do not bend it acutely, or repeatedly bend it, or the antenna core can be damaged. The Coaxial Cable should be installed into a nylon tube (antenna tube) and positioned vertically in your model for the best reception.

Code Auxiliary: A function designed for use with future connected products, such as an ESC, whose Programming Parameters can be changed directly via the transmitter.

Countdown Timer: Used to notify you of your model's running time. For example, you can set the Countdown Timer to alert you when it's time to refuel. When the Countdown Timer expires a long audible tone will sound and the Count Up Timer function begins automatically. This allows you to check the time elapsed since the timer ran out.

Dial Knob: The Dial Knob can rotate 360° and is programmable to perform a different function depending on what function is assigned to it. For example, it can be used to increase and decrease Programming Values, control a Trim function or control an Auxiliary Channel.

Dig: Used with the Motor on Axle function (dual ESCs), the rear motor is inhibited while keeping full control of the front motor during rock crawling.

Digital RPM Display: Displays the current RPM from the RPM Sensor in digital format on the Telemetry Screen.

Digital Temperature Display: Displays the current temperature from the TEMP1 and TEMP2 Temperature Sensors in digital format on the Telemetry Screen.

Digital Trim Memory: Allows the transmitter to store Trim values in its memory. Any amount of Trim that you set during use using the Trim Switches is automatically stored in memory for that specific channel and for that specific model. The Trim values for each model will automatically be loaded when the transmitter is turned ON.

Digital Voltage Indicator: Indicates the current Voltage of the transmitter batteries on both the Top Menu and the Telemetry Screen.

Dual Rate: The Dual Rate function allows you to change the control authority of the Steering, Throttle High Side and Throttle Brake Side by changing the amount of servo travel relative to control input. For example, by increasing the Steering Dual Rate, you can make the steering servo travel more which might prevent your model from pushing during turns. If your model oversteers during turns, you can reduce the amount of Steering Dual Rate.

End Point Adjustment: Used to adjust the desired amount of servo travel in both directions independently. This makes it possible to balance servo travel in both directions.

Enter Key: Opens the selected menu or programming option. Press and HOLD to reset the selected programming option to its default value.

Exponential: Allows you to vary the amount of servo travel in relation to the movement of the steering wheel, throttle trigger and auxiliary lever near the Neutral positions to change the way those functions react to control movement. The position that the Rate can be controlled from is fixed.

Fail Safe: Automatically moves the servos to a predetermined position in the event that the signal between the transmitter and the receiver is interrupted, whether due to signal degradation or low transmitter battery.

FH2 Modulation: Frequency Hopping 2nd generation FHSS technology. FH2 Modulation is used in legacy Airtronics 2.4GHz FHSS-2 transmitters and receivers, such as the Airtronics M11, M11 FHSS-2, and MX-3FG radio control systems.

90478 2.4GHZ FH4T RADIO SYSTEM USER'S GUIDE

GLOSSARY OF TERMS

REFERENCE

FH3 Modulation: Frequency Hopping 3rd generation FHSS technology. FH3 Modulation is used in new-generation Airtronics radio control systems, such as the M11X and MX-3X.

FH4T Modulation: Frequency Hopping 4th generation FHSS technology. FH4T Modulation is the latest Airtronics 2.4GHz frequency modulation and supports Telemetry.

FHSS: Frequency Hopping Spread Spectrum. FHSS is a modulation type which transmits data across the entire frequency spectrum by transmitting data on different channels at an extremely fast interval.

Four Wheel Steering Mixing: Used to control either the Front or Rear steering independently, or Mix the Front and Rear steering so that they can be used together. Front or Rear Independent Steering, Parallel Four Wheel Steering and Tandem Four Wheel Steering options are available.

Goal Time: Used in conjunction with the Lap Timer, the Goal Time is designed to alert you when you reach the maximum desired elapsed time during your race or during practice.

Grip: The Grip is molded from rubber in an ergonomic shape for increased comfort, control and feel. An optional larger Grip is included that some users may find feels more comfortable.

High RPM Display: Displays the last highest RPM value on the Telemetry Screen.

High Side: Refers to the throttle trigger stroke that opens the throttle and powers your model (pulling the throttle trigger).

High Temperature Display: Displays the last highest Temperature value on the Telemetry Screen.

Hold Setting: Determines how quickly the Brake moves from the Stroke setting to Neutral when the Anti-Lock Braking function is Active.

Inactivity Alarm (Power ON Alarm): The Inactivity Alarm will sound if the transmitter is left on for a period of 10 minutes without any control input from the user. This alarm alerts you to prevent unwanted draining of the transmitter battery. To clear this alarm, either turn the transmitter OFF or press the BACK/CANCEL key or the Push-Button Rotary Dial.

Inhibit: To deactivate or turn OFF a particular function.

Interval Timer: Notifies you when a set interval elapses while you are driving, giving you an idea of how close you are to your target time.

KM/H: Kilometers per Hour.

Lag: Controls the amount of delay before the Anti-Lock Brake Activates after reaching the POINT setting.

Lap Timer: Allows you to measure and record times for up to 99 laps. The number of laps completed is displayed in the Timer menu, and when a lap is completed, the lap time is displayed momentarily on the Top Screen.

Latency: The Response Time between the transmitter and receiver. The lower the Latency value, the faster the Response Time and the more connected you feel to your model.

LCD Screen: The heart of the programming and display features of the transmitter. All programming and transmitter display functions are shown on the LCD Screen. The LCD screen features an adjustable backlight and adjustable contrast, making it easy to view in almost any condition.

LED 1/2: Displays the current signal output status of the transmitter (LED 1 - Blue) and the Telemetry connection (LED 2 - Red). In addition, one or both LEDs are used to indicate various transmitter conditions. For example, when a Throttle Offset percentage value is programmed, the blue LED will flash.

Low Voltage Alert Alarm: The Low Voltage Alert alarm will sound when the transmitter batteries reach the Alert Voltage value programmed in the SYSTEM - ALARM menu. The alarm will sound each time the transmitter battery voltage decreases by 0.1 volt. To clear this alarm, press the BACK/CANCEL key or the Push-Button Rotary Dial.

Low Voltage Limit Alarm: The Low Voltage Limit alarm will sound when the transmitter batteries reach the Limit Voltage value programmed in the SYSTEM - ALARM menu. This alarm can only be cleared by turning the transmitter OFF and recharging or replacing the transmitter batteries.

Model Clear: Used to reset the selected model's Programming Data to the default values. All model-specific Programming Data, including the Model Name and Modulation Type will be Reset to the default values.

Model Naming: Used to name the different models you have saved in the transmitter. This makes it easy to keep track of multiple models. The Model Name can consist of up to 10 letters, numbers, or symbols. Choose from capital letters, lower case letters, numbers, and various symbols.

Model Number and Name: Displays the Model Number and Model Name of the currently selected model on both the Top Screen and the Telemetry Screen.

Model Select: Used to store and retrieve Programming Data for any model 1 through 18. If you have Programming Data stored for more than one model, using the Model Select function to load the Programming Data for the particular model that you wish to use. The currently selected Model Number and Model Name is displayed on both the Top Screen and the Telemetry Screen.

Modulation Type Indicator: Indicates the current Modulation Type on the Top Screen that the transmitter is set to.

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Motor on Axle Mixing: Used to control either the Front and Rear throttles together or independently, giving you Dig and Burn functions. These functions are mostly used in Rock Crawling.

MPH: Miles Per Hour.

Operating Voltage: The safe voltage that the transmitter or receiver can operate within. Exceeding the minimum operating voltage can result in loss of power to the device(s). Exceeding the maximum operating voltage can result in damage to the device(s).

Output Power: The power (in Milliwatts) that your transmitter transmits a signal. Output power is defined by government guidelines and differs by region.

Over Voltage Alarm: The Over Voltage Alarm will sound if the transmitter battery voltage is greater than 9.6 volts. To clear this alarm, turn the transmitter OFF and replace the transmitter battery with one that when fully charged does not exceed 9.6 volts.

Parallel (Crab) Steering: Used with Four Wheel Steering, both front and rear wheels pivot right and left together.

Parallel Trim: A Trim technology that when selected, the servo End Points move in equal amounts as the Trim when you use the Trim Switches. This results in balanced servo travel without the need to manually readjust the End Points.

Point Auxiliary: Used to program Auxiliary Channel 3 or Auxiliary Channel 4 to move the servo to up to 6 different points along its travel, then cycle through those Points. For example, if your model requires a separate 3-position or more switch to operate a feature, the Point Auxiliary function can be customized to control this.

Point Setting: Locates the actual point in the servo travel that you want a specific programming setting to occur. This setting can vary depending on the actual programming setting the Point setting is controlling.

Power Switch: Turns the transmitter ON and OFF.

Push-Button Rotary Dial: The Push-Button Rotary Dial (also referred to as the Up Key, Down Key, or Enter key) is used along with the BACK/CANCEL Key to facilitate transmitter programming. It allows you to quickly and easily navigate the various Programming and System Menus and switch between the Top Screen and the Telemetry Screen.

Push-Button Switch: The transmitter features two separate Push-Button Switches in different locations (Sw1 and Sw2). Each Push-Button Switch is programmable and will perform a different function depending on what function is assigned to it.

Receiver Battery Voltage Fail Safe: Used to set a custom voltage that the Receiver Battery Fail Safe function will Activate at. When your receiver battery voltage drops to the programmed voltage, the throttle servo will move to the predetermined position programmed using the Fail Safe function. If this occurs, recharge or replace your receiver batteries.

Receiver Voltage Display: Displays the current voltage of the receiver battery on the Telemetry Screen.

Release Setting: Determines how quickly the Brake moves from Neutral to the percentage value determined by the Stroke setting when the Anti-Lock Braking function is Active.

RPM: Revolutions Per Minute.

RPM Display Monitor: Displays the current RPM on the Telemetry Screen from the RPM Sensor in graphical format.

Servo Monitor Display: Displays the output levels of the four different channels in bar graph form, allowing you to monitor servo operation in a virtual manner.

Servo Reversing: Used to electronically switch the direction of servo travel. For example, if you move the steering wheel to the right, and the steering servo moves to the left, you can use the Servo Reversing function to make the steering servo move to the left.

Servo Speed: Used to slow down the transit speed of the servos. Servo transit speed can be slowed in both the Forward and the Return to Center directions.

SHR Servo Operating Mode: Using this setting with Digital servos will increase the servo's response time, even above the manufacturer's stated specification. Do not use with Analog servos!

SSR Servo Operating Mode: If you're using Airtronics SRG Digital servos, you can use the SSR setting for the fastest response time. This results in the ultimate feel and response, making you feel more in control of your model than ever. Use only with Airtronics SRG Digital servos!

Steering Program Indicator: Indicates on the LCD Screen up to four different programming options that are currently programmed to the Steering channel. The Steering Program Indicator will only be displayed if a Steering channel Programming Value is programmed.

Steering Trim Display: Displays the current position of the Steering Trim Switch on the Top Screen.

Steering Wheel: Proportionally operates the model's right and left steering control. The Steering Wheel features a foam grip for increased comfort, control and feel. In addition, the Steering Wheel spring tension and travel limits can be adjusted.

Steering Wheel Tension Adjustment Screw: Used to adjust the spring tension of the steering wheel to best suit the feel of the user.

Step Auxiliary: Allows you to program the Auxiliary 1 servo or Auxiliary 2 servo to move a defined amount when toggled ON and OFF using a Push-Button Switch.

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Step Value: A preset amount that the servo will travel when a Trim Switch is pressed once. The step value can be adjusted so that the servo either moves more or moves less when the Trim Switch is pressed.

Stroke: Determines the amount of Brake that's applied automatically when the Anti-Lock Braking function Activates.

Sub-Trim: Used to correct the Neutral Trim setting for the servos, making it possible to center the Trim switches while ensuring the servo horns remain centered.

Suppression Capacitor: Primarily used on brushed electric motors, a suppression capacitor helps eliminate electrical noise that could interfere with the operation of your radio control system.

Tandem Steering: Used with Four Wheel Steering, the front wheels pivot opposite to the rear wheels.

Telemetry: A connection between the receiver and the transmitter that transfers Sensor data from the receiver to the transmitter that can be viewed in real-time on the Telemetry Screen. Data such as Temperature, Receiver Voltage and RPM or Speed can be viewed.

Telemetry Signal Indicator: Indicates the current signal strength of the Telemetry connection between the transmitter and receiver. The Telemetry Signal Indicator will only be displayed when the receiver is turned ON and there is a Telemetry connection Active.

Temperature Alert Alarm: The Temperature Alert alarm will sound when the TEMP1 and/or TEMP2 temperature reaches the Alert Temperature value programmed in the SYSTEM - TELEMETRY menu. To clear this alarm, press the BACK/CANCEL key or the Push-Button Rotary Dial.

Temperature Display Monitor: Displays the current TEMP1 and TEMP2 temperatures in bar graph format on the Telemetry Screen.

Throttle Mode Indicator: Indicates the current Throttle Mode type on the Top Screen.

Throttle Offset: Allows you to shift the Neutral position of the throttle servo, either toward the High Side or the Brake Side. When used in conjunction with a Push-Button Switch, this function can be used several different ways. For example, if you're driving a glow- or gas-powered model, you can program the Throttle Offset function to shut down your engine with the press of a button. In addition, you can program the Throttle Offset function to increase to a steady idle while you're refueling during a race.

Throttle Offset Indicator: Indicates that the Throttle Offset function is programmed. The Throttle Offset Indicator will only be displayed if a Throttle Offset percentage value is programmed.

Throttle Program Indicator: Indicates on the LCD Screen up to four different programming options that are currently programmed to the Throttle channel. The Throttle Program Indicator will only be displayed if a Throttle channel Programming Value is programmed.

Throttle Trigger: Controls the speed of the model, both forward and backward, or the model's brake. The Throttle Trigger position, angle and spring tension can all be adjusted.

Throttle Trigger Position Adjustment Indicator: Indicates the current position of the Throttle Trigger. As the throttle trigger position is adjusted forward or backward, the Throttle Trigger Position Adjustment Indicator will move forward or backward.

Throttle Trigger Position Adjustment Screw: Used to adjust the position of the Throttle Trigger either forward or backward.

Throttle Trigger Tension Adjustment Screw: Used to adjust the spring tension of the throttle trigger to best suit the feel of the user. Turning the Throttle Trigger Tension Adjustment Screw clockwise increases throttle trigger tension and turning the Throttle Trigger Tension Adjustment Screw counter-clockwise decreases throttle trigger tension.

Throttle Trim Display: Displays the current position of the Throttle Trim Switch on the Top Screen.

Timer Display: Displays the time of the currently selected Timer on the Top Screen.

Timer Type Indicator: Indicates the current Timer Type selected, either LAP or INT (Interval) on the Top Screen.

Trim Step Resolution: Used to adjust how far the servos travel when the Trim Switches are pressed. You can increase the resolution, so that the servos travel less when you press the Trim Switches. This makes it possible to fine-tune the settings extremely accurately. In addition, you could decrease the resolution, so that the servos travel more when you press the Trim Switches. This setting may not be as accurate, although you can set large amounts of Trim faster.

Trim Switch: The transmitter features four separate Trim Switches positioned around the steering wheel (Trm1, Trm2, Trm3 and Trm4). Each Trim Switch is programmable and will perform a different function depending on what function is assigned to it. For example, Trm1 and Trm2 can be used to adjust steering and throttle Trim and Trm4 and Trm5 can be used to adjust Dual Rate and steering EPA.

Variable Rate Adjustment: The Variable Rate Adjustment function allows you to recalibrate the operation of the Steering, Throttle and Auxiliary Lever End Points and Neutral positions to ensure precise control operation.

Voltage Alert Alarm: The Voltage Alert alarm will sound when the receiver battery in your model reaches the Alert Voltage value you've programmed in the SYSTEM - TELEMETRY menu. To clear this alarm, press the BACK/CANCEL key or the Push-Button Rotary Dial.

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Voltage Alert Indicator: Indicates the currently programmed Voltage value on the Telemetry Screen that the receiver Voltage Alert alarm will sound at.

Voltage Display Monitor: Displays the current receiver battery voltage on the Telemetry Screen in bar graph format.

Wrist Strap Anchor Slot: Used to attach the wrist strap anchor to the transmitter.

Z-Connector: The type of servo and battery connector used by Airtronics. The Z-Connector is a universal connector which is electronically compatible with the airborne components of other radio control system manufacturers.

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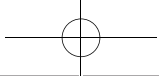
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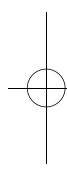
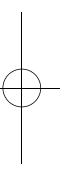
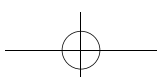
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