## flexLock

Safety locking device

## SICK

Sensor Intelligence.

## Described product

flexLock

## Manufacturer

SICK AG
Erwin-Sick-Str. 1
79183 Waldkirch
Germany

## Legal information

This work is protected by copyright. Any rights derived from the copyright shall be reserved for SICK AG. Reproduction of this document or parts of this document is only permissible within the limits of the legal determination of Copyright Law. Any modification, abridgment or translation of this document is prohibited without the express written permission of SICK AG.

The trademarks stated in this document are the property of their respective owner.
© SICK AG. All rights reserved.

## Original document

This document is an original document of SICK AG.
C
$E C$

HI

## Contents

1 About this document. ..... 5
1.1 Scope ..... 5
1.2 Target groups of these operating instructions ..... 5
1.3 Additional information. ..... 5
1.4 Symbols and document conventions ..... 5
2 Safety information. ..... 7
2.1 General safety notes ..... 7
2.2 Intended use. ..... 7
2.3 Improper use ..... 7
2.4 Requirements for the qualification of personnel ..... 7
3 Product description ..... 9
3.1 Design and function ..... 9
3.2 Product characteristics ..... 9
3.3 Manual unlocking ..... 11
4 Project planning ..... 13
4.1 Manufacturer of the machine. ..... 13
4.2 Operator of the machine ..... 13
4.3 Design ..... 13
4.4 Integration in the electrical control system ..... 15
5 Mounting ..... 18
5.1 Safety ..... 18
5.2 Orientation of the safety switch ..... 18
5.3 Mounting several safety switches ..... 18
5.4 Mounting the safety switch ..... 19
5.5 Mounting the actuator ..... 19
6 Electrical installation ..... 20
6.1 Safety ..... 20
6.2 Notes on cULus ..... 21
6.3 Device connection ..... 21
6.4 Connection of a safe series connection ..... 22
7 Commissioning ..... 24
7.1 Teach-in ..... 24
7.2 Testing. ..... 26
7.3 Regular thorough check ..... 26
8 Operation ..... 28
8.1 Actuating the mechanical unlocking mechanism ..... 28
8.2 Preventing unintentional closing of the protective device. ..... 28
9 Maintenance ..... 29
9.1 Cleaning. ..... 29
10 Troubleshooting. ..... 30
10.1 Safety ..... 30
10.2 LED indicators. ..... 30
11 Decommissioning ..... 34
11.1 Disposal. ..... 34
12 Technical data. ..... 35
12.1 Data sheet. ..... 35
12.2 Connecting cables ..... 37
12.3 Safety switch dimensional drawings ..... 38
12.4 Actuator dimensional drawings. ..... 38
12.5 Dimensional drawings of the mounting bracket. ..... 38
13 Ordering information ..... 39
13.1 Scope of delivery. ..... 39
13.2 Ordering information ..... 39
14 Accessories ..... 40
14.1 Actuator. ..... 40
14.2 Connectivity ..... 40
15 Annex ..... 42
15.1 Compliance with EU directives ..... 42
15.2 FCC and IC radio approval ..... 43

## 1 About this document

### 1.1 Scope

These operating instructions are valid for the flexLock safety locking device.
This document is included with the following SICK part numbers (this document in all available language versions):

8025630

### 1.2 Target groups of these operating instructions

Some chapters of these operating instructions are intended for certain target groups. However, the entire operating instructions are relevant for intended use of the product.

Table 1: Target groups and selected chapters of these operating instructions

| Target group | Chapters of these operating instructions |
| :--- | :--- |
| Project developers (planners, developers, <br> designers) | "Project planning", page 13 <br> "Technical data", page 35 |
| Installers | "Mounting", page 18 |
| Electricians | "Electrical installation", page 20 |
| Safety experts (such as CE authorized repre- <br> sentatives, compliance officers, people who <br> test and approve the application) | "Project planning", page 13 <br> "Commissioning", page 24 <br> "Technical data", page 35 |
| Operators | "Troubleshooting", page 30 |
| Maintenance personnel | "Troubleshooting", page 30 |

### 1.3 Additional information

www.sick.com
The following information is available on the Internet:

- This document in other languages
- Data sheets and application examples
- CAD data and dimensional drawings
- Certificates (e.g. EU declaration of conformity)
- Guide for Safe Machinery Six steps to a safe machine


### 1.4 Symbols and document conventions

The following symbols and conventions are used in this document:

## Safety notes and other notes

## DANGER

Indicates a situation presenting imminent danger, which will lead to death or serious injuries if not prevented.

## WARNING

Indicates a situation presenting possible danger, which may lead to death or serious injuries if not prevented.

## CAUTION

Indicates a situation presenting possible danger, which may lead to moderate or minor injuries if not prevented.

## NOTICE

Indicates a situation presenting possible danger, which may lead to property damage if not prevented.

## NOTE

Indicates useful tips and recommendations.

## Instructions to action

- The arrow denotes instructions to action.

1. The sequence of instructions for action is numbered.
2. Follow the order in which the numbered instructions are given.
$\checkmark$ The check mark denotes the result of an instruction.

## LED symbols

These symbols indicate the status of an LED:
O The LED is off.

- The LED is flashing.
- The LED is illuminated continuously.


## 2 <br> Safety information

### 2.1 General safety notes

## DANGER

If the safety component is integrated incorrectly, the dangerous state may be ended to late.

- Plan the integration of the safety component in accordance with the machine requirements, see "Project planning", page 13.


### 2.2 Intended use

The safety locking device is a locking unit with a safety locking function and is suitable for the following applications:

- Temporarily preventing access to a hazardous area
- Monitoring of movable physical guards
- Locking for process protection

In conjunction with a movable physical guard and the machine controller, the safety locking device prevents the protective device from being opened. The locking device remains locked for as long as the hazardous machine function is performed or until the production step has finished.
The product is only suitable for use in industrial environments.
Incorrect use, improper modification of or tampering with the safety locking device will invalidate any warranty from SICK AG; in addition, any responsibility and liability of SICK AG for damage and secondary damage caused by this is excluded.

### 2.3 Improper use

The safety locking device is not suitable, among other things, for the following ambient conditions:

- Outdoor areas
- Residential areas
- Vacuum
- High pressure
- Strong UV exposure
- Near low-frequency transponders (e.g., RFID)
- Near magnetic fields
- Increased radiaoactivity (> natural radioactivity)
- High sulfur concentration
- High salt concentration


### 2.4 Requirements for the qualification of personnel

The safety locking device must be planned in, installed, connected, commissioned, and serviced only by qualified safety personnel.

## Project planning

For project planning, a person is considered competent when he/she has expertise and experience in the selection and use of protective devices on machines and is familiar with the relevant technical rules and national work safety regulations.

## Mechanical mounting, electrical installation, and commissioning

For the task, a person is considered qualified when he/she has the expertise and experience in the relevant field and is sufficiently familiar with the application of the protective device on the machine to be able to assess whether it is in an operationally safe state.

## Operation and maintenance

For operation and maintenance, a person is considered competent when he/she has the expertise and experience in the relevant field and is sufficiently familiar with the application of the protective device on the machine and has been instructed by the machine operator in its operation.

## 3 Product description

### 3.1 Design and function

## Design

The safety locking device is a locking unit with a safety locking function. The safety locking device comprises a safety switch with transpondermonitoring and a coded actuator.

## Function

The safety locking device is used on a movable physical guard. The safety switch is located on the frame of the movable guard, the actuator on the moving part. When the protective device is closed, the actuator is inserted into the safety switch. The safety switch reads the code of the actuator. If the code is valid, the safety locking function can be locked via a signal. The movable guard is held closed.

### 3.2 Product characteristics

### 3.2.1 Device overview



Figure 1: Device overview
(1) Guiding ball
(2) Locking bolt
(3) Safety switch
(4) LEDs
(5) Connection
(6) Auxiliary release
(7) Mounting holes of the safety switch
(8) Sealing plug for mounting holes of the safety switch
(9) Actuator tongue
(1)(0) Mounting plate of the actuator
(1) Sealing plug for mounting holes of the actuator

### 3.2.2 <br> Locking principle

## Overview

The method of locking depends on the safety locking device variant selected. There are two variants:

- Power to lock
- Power to release

Important information

## DANGER

Hazard due to lack of effectiveness of the protective device
For power to lock variants only: In the event of a voltage drop, the locking device unlocks regardless of whether the dangerous state of the machine has ended.

- Do not use the safety switch in applications in which the dangerous state cannot be ended immediately (stopping/run-down time).


## Power to lock

- Lock locking device: voltage at locking device input
- Unlock locking function: no voltage at locking device input

If voltage is interrupted, the locking device is unlocked and protective device can be opened immediately.

## Power to release

- Lock locking device: no voltage at locking device input
- Unlock locking device: voltage at locking device input

If the voltage is interrupted, the locking device retains its last state (bistable coil). If the locking device was locked before, the protective device cannot be opened. If the locking device was not locked before, the protective device can be opened.

Only the power to release variants have a mechanical unlocking mechanism.

### 3.2.3 OSSD

Output signal switching device: signal output for the protective device, which is used for stopping the dangerous movement.

An OSSD is a safety switching output. The functionality of each OSSD is tested periodically. OSSDs are always connected in pairs and must undergo dual-channel analysis for safety reasons. An OSSD pair is formed from 2 OSSDs that are connected and analyzed together.

### 3.2.4 Switching behavior of the OSSDs

## Overview

The safety locking device is available in variants for protecting people or for process protection. The variants differ with regards to the switching behavior of the OSSDs:
Variants for people protection (locking monitoring)
OSSDs go into the ON state as soon as the following requirements are all fullfilled.

- Movable physical guard is closed.
- Locking device is locked.
- $\quad$ There is a valid signal at the inputs $\ln 1$ and $\ln 2$.

Variants for process protection (actuator monitoring)
OSSDs go into the ON state as soon as the following requirements are all fullfilled.

- Movable physical guard is closed.
- $\quad$ There is a valid signal at the inputs $\ln 1$ and $\ln 2$.

Important information

## DANGER

Hazard due to lack of effectiveness of the protective device

- Do not use variants for process protection in applications in which the dangerous state cannot be ended immediately (stopping/run-down time).


### 3.2.5 Application diagnostic output

Important information

## NOTE

The application diagnostic output cannot be evaluated for a safe series connection with T-connectors.

## Switching behavior

The application diagnostic output switches parallel the detection of the actuator. This is not a safety output.

| Status of the movable physi- <br> cal guard | Switching behavior of the application diagnostic output |
| :--- | :--- |
| Open | OFF |
| Closed | ON |

### 3.2.6 Coded actuators

The safety locking device comes with coded actuators with transponders.

- Uniquely coded

Only one actuator is valid at any one time. Actuators need to be taught-in to become valid. Each time a new actuator is taught-in, the previous actuator becomes invalid.
Coding level: High (ISO 14119)

- Universally coded

The device accepts all actuators that are suitable for the device.
Coding level: Low (ISO 14119)

### 3.3 Manual unlocking

In some situations, it necessary to unlock the locking device manually (e.g. if faults are present). When unlocking, the safe output signal switching devices (OSSD) switch to the OFF status. A stop command must be generated as a result.

After manual unlocking, a function test must be performed (see "Testing", page 26).

### 3.3.1 Auxiliary release

Using the auxiliary release, the safety locking device can be unlocked manually regardless of the status.


Figure 2: auxiliary release
(1) Auxiliary release

Only the power to release variants have a auxiliary release.

## 4 Project planning

### 4.1 Manufacturer of the machine

The manufacturer of the machinery must carry out a risk assessment and apply appropriate protective measures. Further protective measures may be required in addition to the safety locking device.
The device must not be tampered with or changed, except for the procedures described in this document.

The device must not be repaired. Defect devices have to be replaced.
Observe EN ISO 14119 when using interlocking devices in conjunction with physical guards.

### 4.2 Operator of the machine

Changes to the electrical integration of the device in the machine controller and changes to the mechanical mounting of the device necessitate a new risk assessment. The results of this risk assessment may require the entity operating the machine to meet the obligations of a manufacturer.
The device must not be tampered with or changed, except for the procedures described in this document.

The device must only be repaired. Improper repair can result in the device not providing correct protection.

Restrict access to replacement actuators, so they cannot be used for bypassing.

### 4.3 Design

### 4.3.1 Features of the actuator

The actuator is available in different designs.

- Rigid
- Flexible

Table 2: Features of the actuator

|  | Flexible | R |
| :--- | :--- | :--- |
|  | Straight | Angled |
| Alignment of actuator to <br> mounting surface | 800 mm |  |
| Minimum door radius for door <br> stop above the device | 500 mm | 150 mm |
| Minimum door radius for door <br> stop on left or right of device | 180 mm | 0.5 mm |
| Max. horizontal deviation $\mathbf{1}$ | 3 mm | 0.5 mm |
| Max. vertical deviation $\mathbf{3}$ | 3 mm | $0^{\circ}$ |
| Max. offset angle about X-axis <br> $\boldsymbol{4}$ | $2.5^{\circ}$ | $0^{\circ}$ |
| Max. offset angle about Y-axis <br> $\boldsymbol{2}$ | $2.5^{\circ}$ |  |


|  | Flexible | Rigid |
| :--- | :--- | :--- |
| Max. offset angle about Z-axis <br> $\mathbf{5}$ | $2,5^{\circ}$ | $0^{\circ}$ |
| Rotable and spring loaded <br> actuator | Yes | No |



Figure 3: Offsets and offset angle

### 4.3.2 Actuating direction

The safety locking device can be actuated horizontally within a continous $180^{\circ}$ radius.


Figure 4: Possible actuating directions

The flexible actuator can only move for- The rigid actuator can move forwards or wards for actuation. sideways for actuation.


Figure 5: Sideways approach with flexible actua- Figure 6: Sideways approach with rigid actuator tor

### 4.3.3 Measures to protect against unintentional damage

You can use the following measures to avoid unintentional damage to the safety switch:

- Select the mounting location so that the safety switch is protected from impacts and mechanical pressure.
- Fit an additional stop for the door. The safety switch must not be used as a stop.


### 4.3.4 Measures against tampering

The safety switch must not be defeated (contacts jumpered), rotated away, removed, or rendered ineffective in any other way. You must put measures in place, if necessary, to reduce the possibilities for defeating the device.

### 4.4 Integration in the electrical control system

You need to take the following into consideration when integrating the safety locking device into the electrical control system.

## Requirement for use

- The safety locking device must not be bypassed by electrical means, e.g. by bridging the contacts. You may need to take measures to prevent this.
- The connected controller and all devices responsible for safety must comply with the required performance level and the required category (for example according to ISO 13849-1).
- The overall concept of the control system in which the device is integrated must be validated in accordance with ISO 13849-2.
- The inputs of a connected evaluation unit must be positive-switching (PNP) inputs because the two outputs of the safety switch supply a level of the supply voltage in the switched- ON state.


## Generating the signals for the safety locking device

- Only variants for people protection: The locking device may only be unlocked when the dangerous state has ended. Depending on the safety concept, the signal is analyzed, for example, by a safety relay or a safety controller.
- Use control without test pulses. The safety switch generates its own testpulses.

Evaluating the signals from the safety locking device

- In the closed or locked state, the OSSDs signal the ON state with the signal level HIGH (non-isolated). When opened or unlocked or there is a device fault, the OSSDs signal the OFF state with the signal level LOW.
- Downstream control elements must evaluate the output signals of the protective device in such a way that the dangerous state of the machine is safely ended. The machine switches to the safe state if, at any time, at least one OSSD in the OSSD pair switches to the OFF state.
- Switch-on commands that put the machine in a dangerous state may only be activated when the OSSDs of the safety locking device are in the ON state.
- Closing or locking the protective device must not trigger the automated starting of a hazardous machine function. This must occur by means of a separate start command.
- The safety switch tests the OSSDs at regular intervals. To do this, the safety switch switches each OSSD briefly (for max. $300 \mu \mathrm{~s}$ ) to the OFF state and checks whether this channel is voltage-free during this time. Make sure that the machine's control does not react to these test pulses and the machine does not switch off.


### 4.4.1 Safe series connection

## Overview

Several safety switches can be connected in series in a safe series connection. The connected devices act like a single device. The type of safe series connection depends on the safety switch variant selected.
The following options are available:

- Safe series connection with Flexi Loop (with diagnostics) In a series connection with Flexi Loop, the safety switches are connected to Flexi Loop nodes. Each Flexi Loop node evaluates a safety switch and sends the information to the Flexi Soft safety controller.
- Safe series connection with T-connector (without diagnostics) In a series connection with T-connectors, several safety switches are connected via T-connectors and connected to the safe evaluation unit.
- Safe series connection in control cabinet (with diagnostics)

In a series connection in the control cabinet, the safety switches are led to the control cabinet individually. The OSSDs of the safety switches are connected in series there and evaluated by the evaluation unit. The Aux outputs can be individually connected to the programmable logic controller (PLC).

Safe series connection with T-connectors or in the control cabinet


Figure 7: Switching with 5 safety switches connected in series
(1) Safety switch
(2) Safe evaluation unit

The voltage drop in the series connection must be checked so that the defined minimum voltage is still applied to the last safety switch.

For connection cables with a length of 2 m and a cable cross-section of $0.25 \mathrm{~mm}^{2}$, the maximum number of safety switches connected in series depends on the voltage as follows:

Table 3: Maximum number of safety switches in a series connection depends on the voltage

| Voltage | Connection cables, uni- <br> form for the entire series <br> connection | Input voltage at 30th <br> safety switch | Maximum number of <br> safety switches in ser- <br> ies connection |
| :--- | :--- | :--- | :--- |
| 24 V | Length: 2 m | 19.2 V | 4 |
| 26 V | Cable cross-section: <br> - General: $0,34 \mathrm{~mm}^{2}$ <br> - Connection between <br> safety switch and junc- <br> tion: $0,25 \mathrm{~mm}^{2}$ | 19.5 V | 5 |

## Additional voltage supply

The voltage drop in the safe series connection must be checked so that the defined minimum voltage is still applied to each safety switch. If the defined minimum voltage is no longer applied to a safety switch, a node for voltage supply must be integrated. The node for voltage supply must be integrated in the safe series connection in the direction of the safe evaluation unit, as close as possible to the relevant switch.

## Complementary information

Number of safety locking devices in a safe series connection
The maximum number of safety locking devices in a safe series connection depends on the following factors:

- Technical realisation of the safe series connection (T-Connector, Flexi Loop or series connection in the cabinet)
- Applied supply voltage
- Length of cables used
- Cable cross-section of cables used
- Load current
- Required performance level

The number of safety locking devices in a safe series connection affects the response times of the system (see "Data sheet", page 35).

## 5 Mounting

### 5.1 Safety

## DANGER

Hazard due to unexpected starting of the machine
Death or severe injury

- Make sure that the dangerous state of the machine is and remains switched off.


## NOTICE

If incorrectly installed or if the ambient conditions are not suitable, the safety locking device can be damaged.

- Arrange the safety switch and actuator so that damage due to unintentional outside influences is prevented.
- Do not use a safety switch and actuator as a stop.
- Secure the safety switch and actuator using screws of strength class 8.8 or higher (For stainless steel screws: A2-70 or higher).
- Secure the fastening materials against loosening, e.g., using a medium-strength, material-bonding screw adhesive.
- The set-up and mounting of the safety switch and actuator must be stable enough to maintain proper operation.
- Use only reliable mounting elements that can only be removed with tools.
- Protect the switch head against damage and ingress of foreign bodies, e.g., chips, sand, abrasives, etc.
- If an opening is created in the physical guard due to alignment errors, it must not impair the protective function.
- Checking for environmental influences before using the safety locking device, e.g., UV radiation or corrosion. If necessary, mount device protected.
- When using a custom bracket: Ensure that the bracket can absorb at least the same level of mechanical forces that the safety locking device can absorb when the locking device is locked.


### 5.2 Orientation of the safety switch

The safety switch can be mounted in any orientation.

### 5.3 Mounting several safety switches

If several safety switches are mounted on the machine, they must be mounted at a minimum distance to one another.


Figure 8: Minimum distance of safety switches

### 5.4 Mounting the safety switch

## Approach

1. Select a position for the safety switch on the fixed part of the protective device. The safety switch must be positioned in such a way that the actuator is inserted into the safety switch when the movable physical guard is closed.
2. Attach the safety switch to the protective device.

Minimum requirements for mounting screws

- Number: 4
- Size: M5 $\times 25$ (or longer)
- Strength class: Class 8.8 or higher (For stainless steel screws: A2-70 or higher).
- Tightening torque: 5 Nm

3. Apply at least a middle strength adhesive screw locker.

### 5.5 Mounting the actuator

## Approach

1. Select a position for the actuator on the movable physical guard. Select the position in such a way, that when the movable guard is closed, the actuator is inserted into the safety switch.
For flexible actuators, the actuator tongue can be rotated in $90^{\circ}$ increments if necessary. To do so, press and rotate the actuator tongue in the actuator.
2. Attach the actuator to the movable physical guard.

Minimum requirements on the mounting screws

- Type : Use one ways screws when doing so to make unauthorized removal of the actuator difficult (manipulation protection).
- Number: 2
- Size: M5
- Tightening torque: 5 Nm

3. Apply at least a middle strength adhesive screw locker.

## 6 Electrical installation

### 6.1 Safety

## Overview

You can directly integrate the safety switch into the machine controller via the safety outputs (OSSDs). The OSSDs indicate the ON state with the HIGH signal level (non-isolated). The OFF state is indicated with the LOW signal level.

Downstream control elements must evaluate the output signals of the protective device in such a way that the dangerous state of the machine is safely ended. Depending on the safety concept, the signal is analyzed by, e.g., safety relays or a safety controller.

## Important information

## DANGER

Hazard due to electrical voltage
Hazard due to unexpected starting of the machine

- Make sure that the machine is and remains disconnected from the power supply during the electrical installation.
- Make sure that the dangerous state of the machine is and remains switched off during electrical installation.
- Make sure that the outputs of the safety switch have no effect on the machine during electrical installation.

DANGER
Hazard due to lack of effectiveness of the protective device
The dangerous state may not be stopped in the event of non-compliance.

- Always connect the two OSSDs separately. The two OSSDs must not be connected to each other.
- Connect the OSSDs such that the machine controller processes both signals separately.

Isolated connection of OSSD1 and OSSD2


Figure 9: Dual-channel and isolated connection of OSSD1 and OSSD2

## Avoiding any potential difference between load and protective device

If you connect loads to the output signal switching devices (switching outputs) that then also switch if controlled with negative voltage (e.g., electro-mechanical contactor without reverse polarity protection diode), you must connect the 0 V connections of these loads and those of the corresponding protective device separately and also directly to the same 0 V terminal strip. In the event of a fault, this is the only way to ensure that there can be no potential difference between the 0 V connections of the loads and those of the corresponding protective device.


Figure 10: No potential difference between load and protective device

### 6.2 Notes on cULus

The following conditions must also be fulfilled in order to use and apply the equipment in accordance with UL 60947-5-2 requirements:

- The voltage supply must conform to Class 2 according to UL 508.
- The required fuse protection for each device is 2 A . In a safe series connection, a suitable device fuse protection must be calculated.


### 6.3 Device connection



Figure 11: Device connection (male connector, M12, 8-pin, A-coded)

Table 4: Device connection pin assignment (male connector, M12, 8-pin, A-coded)

| PIN | Wire color ${ }^{1)}$ | Designation | Description |
| :--- | :--- | :--- | :--- |
| 1 | White | Out AUX | Application diagnostic output <br> (not safe) |
| 2 | Brown | +24 V DC | Voltage supply 24 V DC |
| 3 | Green | LOCK | Locking device input |
| 4 | Yellow | In 2 | Enable input for OSSD 2 ${ }^{2)}$ |
| 5 | Gray | OSSD 1 | OSSD 1 output |
| 6 | Pink | OSSD 2 | OSSD 2 output |
| 7 | Blue | O V | Voltage supply 0 V DC |


| PIN | Wire color ${ }^{1)}$ | Designation | Description |
| :--- | :--- | :--- | :--- |
| 8 | Red | In 1 | Enable input for OSSD1 ${ }^{2)}$ |

Applies to the extension cables recommended as accessories.
2) When used as an individual safety locking device or as the first safety locking device in a safe series connection, apply 24 V DC.

### 6.4 Connection of a safe series connection

## Overview

The safe series connection can be implemented using special T-connectors and an end connector. The safe evaluation unit switches off the machine in the following events:

- A protective device is unlocked (only variants with lock monitoring)
- A protective device is opened (only variants with actuator monitoring)
- An errror occurs on a safety locking device


## Important information

## NOTE

- In the case of safety locking devices cascaded with T-connectors, the application diagnostic output (Out AUX) cannot be evaluated.
- Mount the connecting cable so that individual T-connectors (and thus a safety locking device) cannot be easily jumpered.


## Connection of the safe series connection (M12, 5-pin)



Figure 12: Internal circuitry: T-connector for safe series connection


Figure 13: Internal circuitry: end connector for safe series connection

The 5-pin male connector of the last T-connector upstream of the safe evaluation unit is the interface between the safe series connection and the safe evaluation unit.


Figure 14: Internal circuitry: nodes for voltage supply


Figure 15: Connection of the safe series connection (M12, 5-pin, A-coded, male connector)

Table 5: Pin assignment connection of the safe series connector (male connector, M12, 5-pin, A-coded)

| PIN | Wire color ${ }^{1)}$ | Designation | Description |
| :--- | :--- | :--- | :--- |
| 1 | Brown | +24 V DC | Voltage supply 24 V DC |
| 2 | White | OSSD 1 | OSSD 1 output |
| 3 | Blue | O V | Voltage supply 0 V DC |
| 4 | Black | OSSD 2 | OSSD 2 output |
| 5 | Gray | Lock | Locking device input |

1) Applies to the extension cables recommended as accessories.

## Further topics

- "Accessories", page 40


## 7 Commissioning

### 7.1 Teach-in

### 7.1.1 Teaching in the first actuator

 Important information
## NOTE

Safety locking devices in the delivery condition have a teach-in-window of 30 minutes after being switched on. After this, the Safety locking device switches into safe state. For a new teach-in-window the device needs to be restarted (disconnect and restore the voltage supply).

## NOTE

The teach-in process is invalid if canceled, e.g. by interruption of the voltage supply or premature removal of the actuator.
The safety locking device then goes into the safe state, and the LEDs indicate the cause of the invalid teach-in process (see "Fault indications during operation", page 32). You can start a new teach-in process after a restrart of the device.

## Prerequisites

- Device variant is not universally coded. Universally coded devices do not require a teach-in.


## Approach

1. Open physical guard.
2. Connect safety switch to voltage supply (see "Electrical installation", page 20).
$\checkmark$ The start sequence is executed. All LEDs flash with alternating colors. OSSDs are switched off in the meantime.
$\checkmark$ The following indicators signal that the safety switch is ready for the teach-in sequence.
Table 6: Display before teach-in

| STATE LED (red/ <br> green) | LOCK LED <br> (green/yellow) | DIAG LED (yel- <br> low/red) | Step |
| :--- | :--- | :--- | :--- |
| Red | O | - Yellow/red <br> $(4 \mathrm{~Hz})$ | Safety switch ready for teach-in <br> sequence |

3. Close physical guard.
$\checkmark$ When the protective device is closed and the actuator has reached the required position, the safety switch automatically starts the teach-in sequence after 3 seconds. The individual steps are indicated via the LEDs.
Table 7: Displays of the teach-in sequences

| STATE LED (red/ <br> green) | LOCK LED <br> (green/yellow) | DIAG LEDs (yel- <br> low/red) | Step |
| :--- | :--- | :--- | :--- |
| $=$ Green $(4 \mathrm{~Hz})$ | O | - Yellow/red <br> $(4 \mathrm{~Hz})$ | Actuator is being taught-in |
| - Green $(4 \mathrm{~Hz})$ | O | - Yellow $(4 \mathrm{~Hz})$ | Actuator was successfully taught-in |

4. No later than 5 minutes after successfully teaching in the actuator, disconnect and restore the voltage supply to the safety switch. Otherwise the device will go into safe state.
$\checkmark \quad$ The safety locking device is ready for use.

### 7.1.2 Teaching in the replacement actuator

## Overview

The safety locking device can only be operated using the actuator that was last taught in.

## Important information

## NOTE

Safety locking devices with an actuator that has already been taught-in have a teach-in readiness of approx. 5 minutes after being switched on. in this time window, the following is true:

- If the actual valid actuator is detected, the teach-in process is canceled. The safety switch returns to normal mode.
- If a deactivated actuator is detected, the teach-in process is canceled. The code of the previous actuator remains active. The safety switch goes into the safe state.
- The device saves the last three deactivated codes only. Actuators that were taughtin at an earlier time can be taught-in again.
- The teach-in process is invalid if canceled, e.g., by interruption of the voltage supply or premature removal of the actuator. The safety locking device then goes into the safe state.


## Approach

1. Open physical guard.
2. Disconnect safety switch from voltage supply for at least 3 seconds.
3. Connect safety switch to voltage supply (see "Electrical installation", page 20).
$\checkmark \quad$ The start sequence is executed. All LEDs flash with alternating colors. OSSDs are switched off in the meantime.
4. Close physical guard.
$\checkmark \quad$ When the protective device is closed and the actuator has reached the required position, the safety switch automatically starts the teach-in sequence. The individual steps are indicated via the LEDs.
Table 8: Displays of the teach-in sequences

| STATE LED (red/ <br> green) | LOCK LED <br> (green/yellow) | DIAG LEDs (yel- <br> low/red) | Step |
| :--- | :--- | :--- | :--- |
| - Green $(4 \mathrm{~Hz})$ | O | - Red/Yellow <br> $(4 \mathrm{~Hz})$ | Actuator is being taught-in |
| - Green $(4 \mathrm{~Hz})$ | O | - Yellow $(4 \mathrm{~Hz})$ | Actuator was successfully taught-in |

5. No later than 5 minutes after successfully teaching in the actuator, disconnect and restore the voltage supply to the safety switch. Otherwise the device goes into safe state. The last actuator remains valid.
$\checkmark$ When the taught-in actuator is in the response range, both OSSDs switch to the ON state and the STATE LED lights up green.

## Further topics

- "Indications when teaching in an actuator", page 31
- "Fault indications during operation", page 32


### 7.2 Testing

## DANGER

Hazard due to unexpected starting of the machine
Death or severe injury

- Before carrying out the functional test, make sure that there are no people in the hazardous area.


## Approach

Check that the device is functioning properly after installation and after every fault. To do this, proceed as follows:

## Mechanical functional test

- Open the protective device and close it again. The components of the safety locking device must not collide with other parts. When the protective device is closed, the actuator must be in a position which enables the lock to be actuated.


## Electrical functional test

1. Switch on the supply voltage.
2. Close all protective devices and activate the locks. The machine must not start up on its own.
3. Check the lock. It must not be possible to open the protective device.
4. Start the machine function.
5. Only variants with lock monitoring (people protection): Make sure that the lock cannot be deactivated as long as the dangerous machine function is active.
6. Stop the machine function and deactivate the lock.
7. Check whether the protective device is kept locked until there is no more risk of injury (e.g., due to run-on movements).
8. Check the restart interlock. The machine function must not start while the lock is deactivated.
9. Repeat steps 3 to 8 individually for each protective device.

## Complementary information

## NOTE

You can simulate an active lock command, by applying the referred voltage to the "Lock input" contact.

- Variant with locking principle power to lock: 24 V DC
- Variant with locking principle power to release 0 V DC


### 7.3 Regular thorough check

## Important information

## DANGER

Insufficient checks or incorrect repair
Hazard due to lack of effectiveness of the protective device

- In the event of wear or damage, replace the entire safety locking device with actuator. Never replace individual parts or assemblies.
- Check the safety locking device following the inspection intervals specified in the national rules and regulations.


## Monitoring

The following checks must be done to ensure permanent and proper function:

- Proper switching function
- Manual unlock function (e.g., auxiliary release)
- Safe mounting of all components
- No damage, contamination, deposits or wear
- No loose plug connectors
- No signs of manipulation of the safety locking device


## 8 Operation

### 8.1 Actuating the mechanical unlocking mechanism

## Prerequisites

- TX10 Torx screwdriver


## Approach

1. Ensure that the actuator is not under strong tensile stress ( $\leq 20 \mathrm{~N}$ ).
2. Loosen the retaining screw with the screwdriver.
3. Use the screwdriver to rotate the mechanical unlocking mechanism in the direction of the arrow to the following symbol:
6
$\checkmark$ The locking device is unlocked.

## Complementary information

If a valid actuator is detected and the locking signal is active, the Safety locking device will repeatedly try to activate locking. If locking can't be activated during the next 10 minutes, the safety locking device will change to safe state.

### 8.1.1 Moving the mechanical unlocking mechanism back after use

## Approach

- Use the screwdriver to move the mechanical unlocking mechanism back to the following symbol:


## 0

- Screw in the retaining screw and seal it (e.g. with locking varnish)
- Open the protective device and close it again.
$\checkmark$ The safety locking device operates in normal mode again.
- Carry out a functional test.


### 8.2 Preventing unintentional closing of the protective device

## Overview

For some maintenance work, it is necessary to prevent the movable physical guard from being closing.

## Approach

- Insert and lock the padlock in the latch plate of the actuator.
$\checkmark$ The physical guard can no longer be closed.


## 9 Maintenance

### 9.1 Cleaning

NOTICE

- Do not use aggressive cleaning agents (such as isopropanol or spirit).
- Do not use any substances that hinder the wetting properties of lacquers.
- We recommend anti-static cleaning agents.


## 10 Troubleshooting

### 10.1 Safety

## DANGER

Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.

- Immediately shut the machine down if the behavior of the machine cannot be clearly identified.
- Immediately put the machine out of operation if you cannot clearly identify or allocate the fault and if you cannot safely remedy the fault.
- Secure the machine so that it cannot switch on unintentionally.


## DANGER

Hazard due to unexpected starting of the machine

- When any work is taking place, use the protective device to secure the machine or to ensure that the machine is not switched on unintentionally.


## DANGER

Hazard due to lack of effectiveness of the protective device
Persons and parts of the body to be protected may not be recognized in case of non-observance.

- Do not do repair work on device components.
- Do not make changes to or manipulate device components.
- Apart from the procedures described in this document, the device components must not be opened.


## NOTE

Additional information on troubleshooting can be found at the responsible SICK subsidiary.

### 10.2 LED indicators

Overview


In combination, these LEDs indicate detailed status and error states. In general, the STATUS and LOCK LEDs indicate the following states.

Table 9: (1) STATUS LED

| Display | Status |
| :--- | :--- |
| Green | Valid actuator detected. OSSD LOW. |
| Red | Valid actuator detected. OSSD HIGH. |
| Red | No valid actuator detected. OSSD LOW. |

Table 10: 2 LOCK LED

| Display | Status |
| :--- | :--- |
| O | No active locking signal |
| Green | Locking signal active, locking device not locked. |
| Yellow | Locking signal active, locking device locked. |
| Yellow |  |

Table 11: 3 DIAG LED

| Display | Status |
| :--- | :--- |
| Yelow | No valid signal at IN 1 and IN 2 |
| :- Red | Meaning depends on the status of other LEDs |
| Yellow |  |
| Red Yellow |  |

## Further topics

- "Indications when teaching in an actuator", page 31
- "Status indications during operation", page 32
- "Fault indications during operation", page 32
10.2.1 Indications when teaching in an actuator

Table 12: Status indications during teach-in

| LED indicators |  | OSSDs | Inputs |  | Status |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | LOCK | IN 1/IN 2 |  |  |

Table 13: Error indications during teach-in

| LED indicators |  | OSSDs | Inputs |  | Cause | Troubleshooting |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | LOCK | IN 1/IN 2 |  |  |  |

### 10.2.2 Status indications during operation

Table 14: Status indications during operation

| LED indicators |  |  | OSSDs | Inputs |  | Status |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| STATUS | LOCK | DIAG |  | LOCK | IN 1/IN 2 |  |
| - Red | $\begin{aligned} & \text { Green } \\ & (1 \mathrm{~Hz}) \end{aligned}$ | Not relevant | OFF | Locking requested. | Not relevant | No actuator detected. |
| - Red | $\bigcirc$ | Not relevant | OFF | Release requested. | Not relevant | No actuator detected. |
| $\begin{aligned} & \text { G Green } \\ & (1 \mathrm{~Hz}) \end{aligned}$ | 0 | - Yellow | OFF | Release requested. | OFF | Actuator detected. <br> Locking device is unlocked. <br> No valid release signal on IN1 and IN2 |
| $\begin{aligned} & \text { Gaen } \\ & (1 \mathrm{~Hz}) \end{aligned}$ | - Green | Yellow | OFF | Locking requested. | OFF | Actuator detected. <br> Locking device is locked. <br> No valid release signal on IN1 and IN2 |
| Green $(1 \mathrm{~Hz})$ | O | O | OFF | Release requested. | ON | Actuator detected. <br> Locking device is unlocked. |
| - Green | - Green | $\bigcirc$ | ON | Locking requested. | ON | Actuator detected. <br> Locking device is locked. |
| - Green | 0 | $\bigcirc$ | ON | Release requested. | ON | Actuator detected. <br> Locking device is unlocked. |
| Not relevant | Not relevant | Yellow | OFF | Not relevant | OFF | No valid release signal on IN1 and IN2 |

### 10.2.3 Fault indications during operation

Table 15: Fault indications during operation

| LED indicators |  |  | OSSDs | Inputs |  | Cause | Troubleshooting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| STATUS | LOCK | DIAG |  | LOCK | IN 1/IN 2 |  |  |
| $\begin{aligned} & \text { 凋 } \\ & (1 \mathrm{~Hz}) \end{aligned}$ | Yellow | $\begin{aligned} & =\text { Red } \\ & (1 \mathrm{~Hz}) \end{aligned}$ | OFF | Not relevant | Not relevant | Device has attempted unsuccessfully to activate or deactivate the safety locking function for 10 minutes. | Make sure, auxiliary release is not active. Check alignement of the actuator. Check if the actuator reaches the final position, when the door is closed. Check if contaminants are blocking the locking pin. |


| LED indicators |  |  | OSSDs | Inputs |  | Cause | Troubleshooting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| STATUS | LOCK | DIAG |  | LOCK | IN 1/IN 2 |  |  |
| $\begin{aligned} & =\text { Red } \\ & (1 \mathrm{~Hz}) \end{aligned}$ | $\bigcirc$ |  | OFF | Not relevant | Not relevant | External error | Check OSSD-cables for short circuit to 0 V or 24 V or to each other. <br> Check cables for damage. <br> Disconnect and restore the voltage supply. |
| $\begin{aligned} & \text { 腯 } \\ & (1 \mathrm{~Hz}) \end{aligned}$ | $\bigcirc$ | $\begin{aligned} & \text { 次 Red } \\ & (1 \mathrm{~Hz}) \end{aligned}$ | OFF | Not relevant | Not relevant | Voltage supply too low or too high | Check voltage supply <br> Disconnect and restore the voltage supply. |
| - Red | $\begin{aligned} & \text { Yellow } \\ & (1 \mathrm{~Hz}) \end{aligned}$ | - Red | OFF | Locking requested. | Not relevant | Actuator was removed while the locking device was active. Actuator is propably damaged. | Replace the actuator. |
| - Red | Irrelevant | $\begin{aligned} & \text { Yellow } \\ & (1 \mathrm{~Hz}) \end{aligned}$ | OFF | Not relevant | Not relevant | Invalid actuator detected. | Use a valid actuator. |
| $\begin{aligned} & \text { O- Green } \\ & (1 \mathrm{~Hz}) \end{aligned}$ | $\begin{aligned} & \text { Yel- } \\ & \text { low/green } \\ & (1 \mathrm{~Hz}) \end{aligned}$ | Irrelevant | Not relevant | Locking requested. | Not relevant | Unable to activate the safety locking function | Check the alignment of the actuator. Check whether the movable physical guard is pulling on the actuator. |
| $\begin{aligned} & \text { Green } \\ & (1 \mathrm{~Hz}) \end{aligned}$ | $\begin{aligned} & \text { Yel- } \\ & \text { low/green } \\ & (4 \mathrm{~Hz}) \end{aligned}$ | Irrelevant | Not relevant | Release requested. | Not relevant | Unable to deactivate the safety locking function. | Check the alignment of the actuator. Check whether the movable physical guard is pulling on the actuator. |
| 0 | 0 | - Red | OFF | Not relevant | Not relevant | Internal error | Make sure, that the device is not used improperly. see "Improper use", page 7 <br> If the problem persist, replace the device. |
| Irrelevant | Irrelevant | Red/yellow $(1 \mathrm{~Hz})$ | Not relevant | Not relevant | Not relevant | Application diagnostic output error | Check AUX Output for short circuit to 0 V . <br> Check cabling for damage. |

## 11 Decommissioning

### 11.1 Disposal

## Approach

- Always dispose of unusable devices in accordance with national waste disposal regulations.



## Complementary information

SICK will be glad to help you dispose of these devices on request.

## 12 Technical data

### 12.1 Data sheet

Table 16: Features

| Principle of operation | Transponder |
| :--- | :--- |
| Frequency band | 125 Hz |
| Actuating force | 20 N |
| Retaining force | 30 N |
| Force against which unlocking is possible | $\leq 25 \mathrm{~N}$ |
| Actuating frequency | $\leq 1 \mathrm{~Hz}$ |
| Actuation speed of the actuator | $\leq 20 \mathrm{~m} / \mathrm{min}$ |
| Dwell time between interlocking and unlocking <br> (or vice versa) | 1.5 s |

Table 17: Locking forces

| Locking force $\mathrm{F}_{\mathrm{Zh}}\left(\mathrm{F}_{\mathrm{Zh}}=\mathrm{F}_{\max } /\right.$ 1.3) |  |
| :--- | :--- |
| Flexible actuator | $3,460 \mathrm{~N}$ (EN ISO 14119) |
| Rigid actuator (frontal) | $3,400 \mathrm{~N}$ (EN ISO 14119) |
| Rigid actuator (lateral) | $3,060 \mathrm{~N}$ (EN ISO 14119) |
| Locking force F for fault exclusion $\left(\mathrm{F}=\mathrm{F}_{\max } / 2\right.$ 2 $^{1)}$ |  |
| Flexible actuator | $2,250 \mathrm{~N}$ (EN ISO 14119) |
| Rigid actuator (frontal) | $2,210 \mathrm{~N}$ (EN ISO 14119) |
| Rigid actuator (lateral) | $1,990 \mathrm{~N}$ (EN ISO 14119) |

1) Use these values if your locking function requires Performance Level PL e or if the Application has a long stopping time.

Table 18: Safety-related parameters

| Safety integrity level | SIL3 (IEC 61508) |
| :--- | :--- |
| SIL claim limit | SILCL3 (EN 62061) |
| Category ${ }^{1)}$ | Category 4 (ISO 13849-1) |
| Performance level ${ }^{1)}$ | PL e (ISO 13849-1) |
| PFH <br> per hour) | mean probability of a dangerous failure | | $6.79 \times 10^{-9}$ at $40^{\circ} \mathrm{C}$ and 0 m above sea level |
| :--- |
| $7.82 \times 10^{-9}$ at $40^{\circ} \mathrm{C}$ and $2,000 \mathrm{~m}$ above sea |
| level |

1) Applies to monitoring the door position (interlocking monitoring).

Applies to monitoring the locking function (locking device monitoring).
Table 19: Electrical data

| Classification based on cULus | 2 |
| :--- | :--- |
| Protection class | III (IEC 61140) |


| Utilization category | DC 13 (IEC 60947-5-3) |
| :---: | :---: |
| Supply voltage $\mathrm{U}_{\mathrm{V}}$ | 24 V DC (19.2 V DC ... 28.8 V DC) (SELV/PELV) <br> 1) |
| Current consumption at 24 V (without load) |  |
| FXL1-SPB***** | 55 mA |
| FXL1-SPL*****, locking device unlocked | 55 mA |
| FXL1-SPL*****, locking device locked | 115 mA |
| Peak current consumption at 24 V (without load) | 800 mA for max. $200 \mathrm{~ms}^{1)}$ |
| Contamination rating | 3 (IEC 60947-1) |
| Rated insulation voltage Ui | 32 V (IEC 60947-1) |
| Rated impulse withstand voltage $\mathrm{U}_{\text {imp }}$ | 1,500 V (IEC 60947-5-1) |
| Power-up delay | 3 s |
| Bridging time in case of power outage | $\begin{aligned} & \text { FXL1-SPB*****: } \leq 4 \mathrm{~ms} \\ & \text { FXL1-SPL*****: } \leq 2 \mathrm{~ms} \end{aligned}$ |
| Response time (required time for OSSDs to switch to OFF-state) | $\leq 100 \mathrm{~ms}^{1)}$ |
| Release time (required time for OSSDs to switch to ON-state) | $\leq 350 \mathrm{~ms}^{1)}$ |
| Risk time ${ }^{2)}$ | $150 \mathrm{~ms}^{1)}$ |

1) In a safe series connection: Multiple value by the number of devices.
2) The risk time is the time needed to detect internal and external faults. External errors affect the OSSDs (short-circuit to an OSSD and cross-circuit between the two OSSDs). At least one of the two OSSDs is safely switched off during the risk time.

Table 20: Interfaces

| System connection | Male connector, M12, 8-pin, A-coded (common <br> male connector for voltage supply and outputs) |
| :--- | :--- |

Table 21: Inputs

| Input voltage for ON state (HIGH) | 24 V (15 V DC ... 28.8 V DC) |
| :--- | :--- |
| Input voltage for OFF state (LOW) | $\leq 2 \mathrm{~V} \mathrm{DC}$ |
| Input current for ON state (HIGH) | $\leq 5 \mathrm{~mA}$ |
| Input current for OFF state (LOW) | $\leq 500 \mu \mathrm{~A}$ |

Table 22: Output signal switching devices (OSSDs)

| Type of output | 2 PNP semiconductors, short-circuit protected, <br> cross-circuit monitored |
| :--- | :--- |
| Output current | $\leq 100 \mathrm{~mA}$ |
| ON state | $\leq 500 \mu \mathrm{~A}$ |
| OFF state | $\mathrm{U}_{\mathrm{V}}-2 \mathrm{~V} \mathrm{DC} \ldots \mathrm{U}_{\mathrm{V}}$ |
| Output voltage | $\leq 2 \mathrm{~V}$ |
| ON state | $\leq 400 \mathrm{nF}$ |
| OFF state | $\leq 300 \mu \mathrm{~s}$ |
| Capacitive load | Typically $40 \mathrm{~ms} \pm 5 \mathrm{~ms}$ |
| Test pulse duration |  |
| Test pulse interval |  |

Table 23: Application diagnostic output

| Output current | $\leq 50 \mathrm{~mA}$ |
| :--- | :--- |


| Output voltage in OFF state | Uv - 2 V DC ... Uv (max. voltage drop $\leq 2$ V DC) |
| :--- | :--- |
| Output voltage in ON state | $\leq 2$ V DC |

Table 24: Mechanical data

| Dimensions (W x H x D) | see "Safety switch dimensional drawings", <br> page 38 <br> see "Actuator dimensional drawings", <br> page 38 <br> see "Dimensional drawings of the mounting <br> bracket", page 38 |
| :--- | :--- |
| Material | Vistal® (fiberglass-reinforced thermoplastic) <br> Stainless steel <br> Stainless steel <br> Stainless steel |
| Safety switch housing <br> Ball bracket <br> Latch plate of the actuator <br> Plug connector | 480 g |
| Weight | 535 g |
| Power to release safety switch | 90 g |
| Power to lock safety switch | 75 g |
| Flexible actuator | $1 \times 10^{6}$ switching operations |
| Rigid actuator |  |
| Mechanical service life |  |

Table 25: Ambient data

| Enclosure rating | IP 65 (IEC 60529) <br> IP 67 (IEC 60529) <br> IP $69 \mathrm{~K}($ IEC 20653) |
| :--- | :--- |
| Ambient operating temperature | $-20^{\circ} \mathrm{C} \ldots+55^{\circ} \mathrm{C}$ |
| Storage temperature | $-25^{\circ} \mathrm{C} \ldots+70^{\circ} \mathrm{C}$ |
| Relative humidity | $10-95 \%$ at $40^{\circ} \mathrm{C}($ IEC 60068) |
| Vibration resistance | $1 \mathrm{~mm} / 10 \mathrm{~Hz} \ldots 55 \mathrm{~Hz}($ IEC 60068-2-6) |
| Shock resistance | $30 \mathrm{~g}, 11 \mathrm{~ms}($ EN 60068-2-27) |
| EMC | In accordance with IEC/EN 61326-3-1, <br> IEC/EN $60947-5-2, ~ I E C / E N ~ 60947-5-3 ~ a n d ~$ <br> EN 300330 |

### 12.2 Connecting cables

## Requirements for the connecting cables

Recommended cable type $=$ LIYY $8 \times 0.25 \mathrm{~mm}^{2}$ or $5 \times 0.34 \mathrm{~mm}^{2}$

## Maximum cable lengths

Table 26: Maximum cable lengths

| Number of safety <br> locking devices | Possible output cur- <br> rent per OSSD $(\mathbf{m A})$ | Possible output cur- <br> rent AUX (mA) | Max. length of entire <br> cable from the last <br> safety locking device <br> to the controller $(\mathbf{m})$ |
| :--- | :--- | :--- | :--- |
| 4 | 100 | 50 | 10 |
| 5 | 5 | 5 | 8 |

12.3 Safety switch dimensional drawings

### 12.4 Actuator dimensional drawings

12.5 Dimensional drawings of the mounting bracket

## 13 Ordering information

### 13.1 Scope of delivery

- Safety switch
- Sealing plug for secure mounting
- Safety note
- Operating instructions for download: www.sick.com


### 13.2 Ordering information

Table 27: Ordering data for power to release safety switch

| Function of the OSSDs | Coding | Unlocking options | Type code | Part number |
| :--- | :--- | :--- | :--- | :--- |
| Locking device monitor- <br> ing | Uniquely coded | - Mechanical unlocking <br> mechanism | FXL1-SPBUSA00 | 1101320 |
| Locking device monitor- <br> ing | Universally coded | - Mechanical unlocking <br> mechanism | FXL1-SPBMSA00 | 1101321 |

Table 28: Ordering data for power to lock safety switch

| Function of the OSSDs | Coding | Type code | Part number |
| :--- | :--- | :--- | :--- |
| Locking device monitoring | Uniquely coded | FXL1-SPLUSA00 | 1101322 |
| Locking device monitoring | Universally coded | FXL1-SPLMSA00 | 1101323 |
| Actuator monitoring | Uniquely coded | FXL1-SPLUAA00 | 1101324 |
| Actuator monitoring | Universally coded | FXL1-SPLMAA00 | 1101325 |

## 14 Accessories

### 14.1 Actuator

Table 29: Actuator flexLock

| Description | Type code | Part number |
| :--- | :--- | :--- |
| Actuator, flexible | FXL1-AF1 | 1101326 |
| Actuator, rigid | FXL1-AR1 | 1101327 |

### 14.2 Connectivity

## M12 connecting cable, 8-pin ( $0.25 \mathrm{~mm}^{2}$ )

Table 30: Ordering information for M12 connecting cable, 8-pin ( $\left.0.25 \mathrm{~mm}^{2}\right)^{\text {1) }}$

| Part | Type code | Part number |
| :--- | :--- | :--- |
| Female connector, straight, 2.5 m cable, flying <br> leads | YF2A18-025UA5XLEAX | 2099229 |
| Female connector, straight, 5 m cable, flying <br> leads | YF2A18-050UA5XLEAX | 2095653 |
| Female connector, straight, 7.5 m cable, flying <br> leads | YF2A18-075UA5XLEAX | 2099230 |
| Female connector, straight, 10 m cable, flying <br> leads | YF2A18-100UA5XLEAX | 2095654 |
| Female connector, straight, 15 m cable, flying <br> leads | YF2A18-150UA5XLEAX | 2095679 |
| Female connector, straight, 20 m cable, flying <br> leads | YF2A18-200UA5XLEAX | 2095680 |
| Female connector, straight, 30 m cable, flying <br> leads | YF2A18-300UA5XLEAX | 2095681 |
| Female connector, angled, 2 m cable, flying <br> leads | YG2A18-020UA5XLEAX | 2095779 |
| Female connector, angled, 5 m cable, flying <br> leads | YG2A18-050UA5XLEAX | 2095780 |
| Female connector, angled, 10 m cable, flying <br> leads | YG2A18-100UA5XLEAX | 2095781 |

M12 connection cable, 5-pin ( $0.34 \mathrm{~mm}^{2}$ )
Table 31: Ordering information for M12 connection cable, 5-pin ( $\left.0.34 \mathrm{~mm}^{2}\right)^{2)}$

| Part | Type code | Part number |
| :--- | :--- | :--- |
| Female connector, straight, 0.6 m cable, male <br> connector, straight | YF2A15-C60UB5M2A15 | 2096006 |
| Female connector, straight, 1 m cable, male <br> connector, straight | YF2A15-010UB5M2A15 | 2096007 |
| Female connector, straight, 2 m cable, male <br> connector, straight | YF2A15-020UB5M2A15 | 2096009 |
| Female connector, straight, 5 m cable, male <br> connector, straight | YF2A15-050UB5M2A15 | 2096010 |
| Female connector, straight, 10 m cable, male <br> connector, straight | YF2A15-100UB5M2A15 | 2096011 |
| Female connector, straight, 15 m cable, male <br> connector, straight | YF2A15-100UB5M2A15 | 2096171 |

[^0]
## M12 connection cable, 8-pin ( $0.25 \mathrm{~mm}^{2}$ )

Table 32: Ordering information for M12 connection cable, 8-pin ( $\left.0.25 \mathrm{~mm}^{2}\right)^{3)}$

| Part | Type code | Part number |
| :--- | :--- | :--- |
| Female connector, straight, 0.6 m cable, <br> straight male connector | YF2A18-C60UA5M2A18 | 2096031 |
| Female connector, straight, 1 m cable, straight <br> male connector | YF2A18-010UA5M2A18 | 2096032 |
| Female connector, straight, 20 m cable, <br> straight male connector | YF2A18-020UA5M2A18 | 2096033 |
| Female connector, straight, 1 m cable, straight <br> male connector | YF2A18-050UA5M2A18 | 2096034 |
| Female connector, straight, 10 m cable, <br> straight male connector | YF2A18-100UA5M2A18 | 2096035 |

## Distributor

Table 33: Ordering information for distributor

| Part | Type code | Part number |
| :--- | :--- | :--- |
| T-connector | STR1-XXA | 5339609 |

## Terminator plug

Table 34: Ordering information for terminator plug

| Part | Type code | Part number |
| :--- | :--- | :--- |
| End connector for series connection | MLP1-XXT | 1078201 |

## Nodes for voltage supply

Table 35: Ordering information Nodes for voltage supply

| Part | Type code | Part number |
| :--- | :--- | :--- |
| Nodes for voltage supply | MLP1-XXN | 1078202 |

[^1]
## 15 Annex

### 15.1 Compliance with EU directives

## EU declaration of conformity (extract)

The undersigned, representing the manufacturer, herewith declares that the product is in conformity with the provisions of the following EU directive(s) (including all applicable amendments), and that the standards and/or technical specifications stated in the EU declaration of conformity have been used as a basis for this.

## Complete EU declaration of conformity for download

You can call up the EU declaration of conformity and the current operating instructions for the protective device by entering the part number in the search field at www.sick.com (part number: see the type label entry in the "Ident. no." field).

### 15.2 FCC and IC radio approval

- FCC ID: 2AHDRFXL1
- IC: 21147FXL1

The device fulfills the EMC requirements for use in the USA and Canada, in accordance with the following extracts from the relevant approvals:

## FCC § 15.19

This device complies with Part 15 of the FCC rules. Operation is subject to the following two conditions:

- This device may not cause harmful interference, and
- this device must accept any interference received, including interference that may cause undesired operation.


## FCC §15.21 (warning statement)

[Any] changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

## IC

This device complies with Industry Canada's licence-exempt RSSs. Operation is subject to the following two conditions:

- This device may not cause interference; and
- This device must accept any interference, including interference that may cause undesired operation of the device.

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes :

- l'appareil ne doit pas produire de brouillage;
- I'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.


## Australia

Phone +61 (3) 94570600 1800334802 - tollfree
E-Mail sales@sick.com.au
Austria
Phone +43 (0) 2236 62288-0
E-Mail office@sick.at
Belgium/Luxembourg
Phone +32 (0) 24665566
E-Mail info@sick.be
Brazil
Phone +55 11 3215-4900
E-Mail comercial@sick.com.br

## Canada

Phone +1 905.771.1444
E-Mail cs.canada@sick.com
Czech Republic
Phone +420 234719500
E-Mail sick@sick.cz
Chile
Phone +56 (2) 22747430
E-Mail chile@sick.com

## China

Phone +86 2028823600
E-Mail info.china@sick.net.cn

## Denmark

Phone +45 45826400
E-Mail sick@sick.dk

## Finland

Phone +358-9-25 15800
E-Mail sick@sick.fi
France
Phone +33 164623500
E-Mail info@sick.fr
Germany
Phone +49 (0) 21153010
E-Mail info@sick.de

## Greece

Phone +30 2106825100
E-Mail office@sick.com.gr

## Hong Kong

Phone +852 21536300
E-Mail ghk@sick.com.hk

Hungary
Phone +36 13712680
E-Mail ertekesites@sick.hu
India
Phone +91-22-6119 8900
E-Mail info@sick-india.com
srael
Phone +972 9711011
E-Mail info@sick-sensors.com
Italy
Phone +39 02274341
E-Mail info@sick.it
Japan
Phone +81 353092112
E-Mail support@sick.jp

## Malaysia

Phone +603-8080 7425
E-Mail enquiry.my@sick.com

## Mexico

Phone +52 (472) 7489451
E-Mail mexico@sick.com

## Netherlands

Phone +31 (0) 302292544
E-Mail info@sick.nl
New Zealand
Phone +64 94150459 0800222278 - tollfree
E-Mail sales@sick.co.nz

## Norway

Phone +47 67815000
E-Mail sick@sick.no
Poland
Phone +48 225394100
E-Mail info@sick.pl

## Romania

Phone +40 356-17 1120
E-Mail office@sick.ro
Russia
Phone +7 4952830990
E-Mail info@sick.ru

## Singapore

Phone +65 67443732
E-Mail sales.gsg@sick.com

## Slovakia

Phone +421 482901201
E-Mail mail@sick-sk.sk

## Slovenia

Phone +386 59178849
E-Mail office@sick.si
South Africa
Phone +27 100600550
E-Mail info@sickautomation.co.za
South Korea
Phone +82 2786 6321/4
E-Mail infokorea@sick.com
Spain
Phone +34 934803100
E-Mail info@sick.es

## Sweden

Phone +46 101101000
E-Mail info@sick.se

## Switzerland

Phone +41416192939
E-Mail contact@sick.ch

## Taiwan

Phone +886-2-2375-6288
E-Mail sales@sick.com.tw
Thailand
Phone +66 26450009
E-Mail marcom.th@sick.com
Turkey
Phone +90 (216) 5285000
E-Mail info@sick.com.tr
United Arab Emirates
Phone +971 (0) 48865878
E-Mail contact@sick.ae
United Kingdom
Phone +44 (0)17278 31121
E-Mail info@sick.co.uk
USA
Phone +1 800.325.7425
E-Mail info@sick.com

## Vietnam

Phone +65 67443732
E-Mail sales.gsg@sick.com


[^0]:    1) Ambient operating temperature: Down to $-30^{\circ} \mathrm{C}$ with fixed installation.
[^1]:    2) Ambient operating temperature: Down to $-30^{\circ} \mathrm{C}$ with fixed installation.
    3) Ambient operating temperature: Down to $-30^{\circ} \mathrm{C}$ with fixed installation.
