Parameters (Profibus PA)

Device parameter, parameter, menu identification	Description	Factory Setting	Setting Possibilities
4.4.1.3: Level param.	= [4.2.4]		
or 4.4.1.3: Volume param.	= [4.2.5]		
4.4.1.4: Line 2 local	Display in line 2	S/N ratio	Level Volume Temperature Validity S/N ratio Amplitude Digital output Analog output
4.4.1.5: Level param.	= [4.2.4]		
or 4.4.1.5: Volume param.	= [4.2.5]		
4.4.2: Language local	= [1.1]		
4.4.3: LCD backlight	Background illumination of the LCD	off	on off
4.5: Device info			
4.5.1: Power supply	Voltage range of the built- in power supply unit	according to customer specifications	non-editable
4.5.2: Flange temperature	Temperature range of the flange in °C	according to customer specifications	non-editable
4.5.4: Electrical con- nection		according to customer specifications	non-editable
4.5.5: Antenna&flange			
4.5.5.1: Flange size	Rated width of the flange	according to customer specifications	DN 50, 2 in DN 80, 3 in DN 100, 4 in DN 150, 6 in Special design
4.5.5.2: Flange type	Type of flange	according to customer specifications	DIN ANSI JIS Special design
4.5.5.3: Pressure range	Pressure range of the process connection	according to customer specifications	non-editable

Parameters (Profibus PA)

Device parameter, parameter, menu identification	Description	Factory Setting	Setting Possibilities
4.5.5.4: Antenna type		according to customer specifications	Horn type long Horn type short Special design
4.5.5.6: Flange mate- rial		according to customer specifications	315/316L Special design
4.5.5.7: Seal material	Sealing material	according to customer specifications	Teflon Kalrez Viton Perbunan Special design
4.5.6: Tag	Device identification	according to customer specifications	up to any eight characters
4.5.7: Descriptor	Measuring point description	according to customer specifications	up to any 16 characters
4.5.8: Message	Measuring point mes- sage, e.g. the date of last check or clean	according to customer specifications	up to any 32 char- acters
4.5.9: Manufacturer identification			
4.5.9.1: Serial no.	Factory serial number	unique num- ber	non-editable
4.5.9.2: Order no.	Delivery order no. (delivery state)	according to customer specifications	non-editable
4.5.9.3: Device revision	Device version	Number	non-editable
4.5.9.4: Software revision		Number	non-editable
4.5.9.5: Hardware revision		Number	non-editable
4.5.9.6: Antenna off- set	Distance sensor/flange	approx. 0.5 m (calibration value)	non-editable
4.5.9.7: Reference distance	Internal reference distance	approx. 106 m (calibration value)	non-editable
5: Options			

Parameters (Profibus PA)

Device parameter, parameter, menu identification	Description	Factory Setting	Setting Possibilities
5.1: Enter code	Input of customer code to enable programmability		Customer code
5.2: Customer code	Determination of customer code	0	up to 4 digit code
5.3: Factory reset	Reset all parameters to factory setting	no	yes no

Troubleshooting

The SITRANS LR 400 has left the factory in a fully tested condition. Carefully selected components and compliance with prescribed quality standards guarantee the high reliability of the SITRANS LR 400. In the unlikely event of a fault, please consult the instructions in this chapter before contacting the responsible customer services.

Classification of faults

Faults occurring in the SITRANS LR 400 can be classified in the following groups:

- faults caused by ambient influences: over and undertemperature, moisture, contamination by the measuring medium and other substances, mains faults, vibration
- faults in the device: display, electronics, mechanics, connections
 Please try to determine the fault and localize it as accurately as possible..

If the fault cannot be eliminated with the measures described, follow the instructions in "Maintenance and repairs" on page 65.

Self-test

Note: The device performs a self-test every time it is switched on. It is ready for operation when the LCD displays the multi-display and the control elements can be operated.

If you get fault messages after the self-test, please proceed according to "Fault messages" on page 64.

If there is a malfunction in the device, you can also activate the self-test manually with Parameter 3.2.1.

Symptoms, causes and their remedy

Symptom	Possible causes	Remedy
No display on the LCD	Defective or missing power supply	Check that the power supply is connected correctly. Replace the device fuse if necessary (see "Changing the device fuse" on page 65).
	LCD is defective	Connect a HART Communicator or a PC/Laptop with SIMATIC PDM software. If the device can be parameterized from there, the LCD is defective.
	Electronics are defective	Measure the analog current output. If the output current is not between 3.6 mA < x < 22 mA, the electronics are defective. Replace the electronics unit as described in "Maintenance and repairs" on page 65.
A fault message is displayed	Internal fault	Call the fault display in Function 3.1. Proceed as described in "Maintenance and repairs" on page 65.
An incorrect measured value appears after Auto-Setup.	The device is not parameterized correctly according to the application	Set the device parameters and functions manually.
No measured value appears after the Auto- Setup (measured value "0" and the fault display flashes)	Internal fault	Call the fault display in Function 3.1. Proceed as described in "Maintenance and repairs" on page 65.

Fault messages

The device indicates faults with a flashing letter on the right of the first line of the display. It has the following meaning:

- W: Warning device is still ready for operation but faults may occur
- F: Fault sporadic fault, device conditionally ready for operation
- D: continuous fault device is not ready for operation

Under Parameter 3.1.x, you will find a fault log which indicates the type of the fault(s) which occur. It indicates the device function status in which the fault occurred and outputs an fault message in plain text.

The possible fault messages are as follows:

Function	Message	Possible causes	Remedy
	MW cable defective	Microwave cable not connected or line break	Contact your Siemens Milltronics representative
Sensor	Sensor defective	Overtemperature in device	Contact your Siemens Milltronics representative
	Check antenna	Antenna contaminated, damaged or not mounted	Check the antenna
	Sensor too hot	Sensor temperature exceeds 85 °C	Check the max. permissible ambient and flange temperature
Electronics	all messages	Internal fault	Contact your Siemens Milltronics representative
Software	all messages	Internal fault	Contact your Siemens Milltronics representative
	No valid meas. value	fault in fixed target detection, fault in multiple echo detection, poorly reflecting measuring medium	1
Application	Tank empty detected	vessel is empty (only when sensor parameter "vessel empty detection" active)	Deactivate vessel empty detection if necessary
	false param.	incompatible parameters entered, e. g.: URV = LRV	Correct the parameters listed in the next function
Parameters	<parameter be="" corrected="" to=""></parameter>	False parameterization	Perform the correction as indicated
Service	(various)		For service personnel only

- 1. Make the following modifications, starting with
 - a. Check whether the fault still occurs after every step:
 - b. Check the set measuring range and the dead band (Function 4.2.2.3).
 - c. Check whether the filling speed has been correctly set (Function 4.2.2.5).
 - d. Reduce the reflectivity (Function 4.2.2.6).
 - e. Switch off the automatic fixed target detection (Function 4.2.3.6) if necessary.
 - f. Switch off the multiple echo detection (Function 4.2.3.2) if necessary.

Maintenance and repairs

Changing the device fuse

Warning: The device fuse must only be changed by qualified personnel who are familiar with the installation, commissioning, and operation of the SITRANS LR 400.

The device fuse is located on the power supply unit board.

Position of device fuse and electronics cover locking:



Change a defective fuse as follows:

- Disconnect the device from the power supply.
- If your device is in a pressure-tight housing, release the cover locking of the electronics cover with an Allen key (see above).
- 3. Remove the electronics cover from the housing.
- 4. If your device has an optional operating and monitoring module, pull it out of the front of the housing. Disconnect the plug of its cable from the socket and place the operating and monitoring module on one side.

Caution! Take care not to bend or damage any of the cables.

Touching the electronic circuit boards can damage sensitive parts.

- Lift the device fuse carefully from its clip with a suitable tool (tweezers, flat-tipped pliers or similar) (see above), and remove it from the housing.
- Insert a new fuse. Only use original spare fuses! Press it into the clip until it snaps in audibly.
- 7. Reassemble the device in reverse order.

Caution! The device contains a second fuse that is not accessible via the front side. This fuse is only to be replaced by the manufacturer (following a complete safety check of the device).

Disconnecting the electronics part from the mechanical part

For maintenance it is possible to separate the electronic enclosure of the device from the mechanical part (flange) without endangering the pressure tightness of the vessel. Release the threaded ring of the electronics part from the mechanical part with a hook key 68/75 and remove the electronics part. Place the enclosed plastic cap on the mechanical part to prevent from soiling.

Cleaning the antenna

Depending on the type of measuring material, it may be necessary to clean the antenna at certain intervals to remove soiling which could affect the measuring result. You can clean it without removing the flange from the vessel. Proceed as follows:

1. Disconnect and remove the electronics part as described above.

Caution! As soon as you remove the pressure window from the mechanical part the vessel is no longer pressure-tight and explosion protected!

- Unscrew the pressure window which becomes accessible after removing the threaded ring with an M36 open-ended wrench and lift it off the mechanical part together with the white PTFE stopper.
- Clean the inside of the antenna with compressed air and/or a brush. Make especially sure that the pressure window thread is clean. Apply fresh grease to the thread as required. Check the O-rings for damage and replace them if necessary.
- If the PTFE stopper has come loose when removing from the pressure window, reinsert it long end first in the mechanical part. Push it into the guide up to its thickened stop.
- 5. Place the pressure window and screw it tight.
- 6. Reattach the electronics part to the mechanical part. You can align the rotatable housing head before tightening the threaded ring.
- 7. Check the pressure tightness of the vessel.

Certificates

Certificates

The necessary certificates are enclosed separately.

Glossary

Term	Explanation		
Antenna offset	Propagation time of the signal in the sensor, expressed as a dis-		
Antenna offset	tance		
	The maximum possible value of the output signal in fault-free		
Current limit	operation in mA. The value of the fail signal may be above the		
	current limit with 24 mA.		
Customer code	User-defined code which protects the device against accidental		
Customer code	programming.		
Dead band	Value range below the device flange declared unmeasureable.		
	Sensor parameter for a fuzzy rule which takes into account		
Echo movement	dynamic procedures in the measuring medium for example and		
	therefore rules out fixed targets.		
Fixed target	Permanently installed objects inside the vessel which may cause		
Fixed larget	reflective interference, e.g. struts, agitators, feed pipes etc.		
FMCW method	Frequency Modulated Continuous Wave method		
Frequency deviation	Changing the transmission frequency in the *FMCW method.		
Level	Distance from the *LRV to the surface of the *measuring		
Level	medium.		
I RV	Lower limit of the valid measuring range as a distance from the		
LITY	bottom inside of the vessel.		
Measuring medium	The (solid or liquid) contents of the vessel.		
Multiple echo	Sensor parameter for a fuzzy rule which detects and suppresses		
evaluation	multiple reflections of the measuring signal at the vessel walls.		
Nozzle height	Distance from the top of the inside of the vessel to the bottom of		
•	the device flange.		
PELV	Protected Extra Low Voltage		
PTFE	Polytetrafluorethylene (Teflon)		
SELV	Safety Extra Low Voltage		
Signal-to-noise ratio	Measure of the strength of reflection of the *measuring medium		
•	in the current measuring situation in dB.		
vessel height	Distance between the floor and top of the vessel.		
Triple reflector	Metal instrument formed as a cubic segment with right angles.		
URV	Upper limit of the valid measuring range as a distance from the		
	bottom inside of the vessel.		
Validity	Measure of the certainty of the current measured value in %.		

Appendix I

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Show table 4.2.5.8.3 44 Signal type DO 4.4.2 46 Simulate AO 3.3.1 30 Simulation 3.3 30 Software revision 4.6.9.4 51 Status 3.1 28 Stilling pipe? 4.2.1.3 33 Surface 4.2.2.2 34 Tag 4.6.6 50 Tank characteristic 4.2.5.7 41 Tank design 4.2.5.8.1 43 Tank empty detection 4.2.3.5 38 Tank geometry 4.2.1 33 Tank height 1.4 26 Tank height 4.2.1.2 33 Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume URV 4.2.5.1 40 Volume URV 4.2			
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Simulate AO 3.3.1 30 Simulation 3.3.2 31 Simulation 3.3 30 Software revision 4.6.9.4 51 Status 3.1 28 Stilling pipe? 4.2.1.3 33 Surface 4.2.2.2 34 Tag 4.6.6 50 Tank characteristic 4.2.5.7 41 Tank design 4.2.5.8.1 43 Tank empty detection 4.2.3.5 38 Tank geometry 4.2.1 33 Tank height 1.4 26 Tank height 4.2.1.2 33 Tank neight 4.2.5.8.4 44 Tank volume 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5.1 40 Volume URV <td< td=""><td>Show table</td><td>4.2.5.8.3</td><td>44</td></td<>	Show table	4.2.5.8.3	44
Simulate DO 3.3.2 31 Simulation 3.3 30 Software revision 4.6.9.4 51 Status 3.1 28 Stilling pipe? 4.2.1.3 33 Surface 4.2.2.2 34 Tag 4.6.6 50 Tank characteristic 4.2.5.7 41 Tank design 4.2.5.8.1 43 Tank empty detection 4.2.3.5 38 Tank geometry 4.2.1 33 Tank height 1.4 26 Tank height 4.2.1.2 33 Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume URV 4.2.5.1 40 Volume URV 4.2.5.	Signal type DO	4.4.2	46
Simulation 3.3 30 Software revision 4.6.9.4 51 Status 3.1 28 Stilling pipe? 4.2.1.3 33 Surface 4.2.2.2 34 Tag 4.6.6 50 Tank characteristic 4.2.5.7 41 Tank design 4.2.5.8.1 43 Tank empty detection 4.2.3.5 38 Tank geometry 4.2.1 33 Tank height 1.4 26 Tank height 4.2.1.2 33 Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume URV 4.2.5.1 40 Volume URV 4.2.5.1 40 Volume URV 4.2.5.1 40 Volume URV 4.2.5.1 <td></td> <td>3.3.1</td> <td>30</td>		3.3.1	30
Software revision 4.6.9.4 51 Status 3.1 28 Stilling pipe? 4.2.1.3 33 Surface 4.2.2.2 34 Tag 4.6.6 50 Tank characteristic 4.2.5.7 41 Tank design 4.2.5.8.1 43 Tank empty detection 4.2.3.5 38 Tank geometry 4.2.1 33 Tank height 1.4 26 Tank height 4.2.1.2 33 Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Volume URV 4.2.5.1 40 Volume URV 4.2.5.1 40 Volume URV <t< td=""><td>Simulate DO</td><td>3.3.2</td><td>31</td></t<>	Simulate DO	3.3.2	31
Status 3.1 28 Stilling pipe? 4.2.1.3 33 Surface 4.2.2.2 34 Tag 4.6.6 50 Tank characteristic 4.2.5.7 41 Tank design 4.2.5.8.1 43 Tank empty detection 4.2.3.5 38 Tank geometry 4.2.1 33 Tank height 1.4 26 Tank height 4.2.1.2 33 Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Simulation	3.3	30
Stilling pipe? 4.2.1.3 33 Surface 4.2.2.2 34 Tag 4.6.6 50 Tank characteristic 4.2.5.7 41 Tank design 4.2.5.8.1 43 Tank empty detection 4.2.3.5 38 Tank geometry 4.2.1 33 Tank height 1.4 26 Tank height 4.2.1.2 33 Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Software revision	4.6.9.4	51
Surface 4.2.2.2 34 Tag 4.6.6 50 Tank characteristic 4.2.5.7 41 Tank design 4.2.5.8.1 43 Tank empty detection 4.2.3.5 38 Tank geometry 4.2.1 33 Tank height 1.4 26 Tank height 4.2.1.2 33 Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Status	3.1	28
Tag 4.6.6 50 Tank characteristic 4.2.5.7 41 Tank design 4.2.5.8.1 43 Tank empty detection 4.2.3.5 38 Tank geometry 4.2.1 33 Tank height 1.4 26 Tank height 4.2.1.2 33 Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Stilling pipe?	4.2.1.3	33
Tank characteristic 4.2.5.7 41 Tank design 4.2.5.8.1 43 Tank empty detection 4.2.3.5 38 Tank geometry 4.2.1 33 Tank height 1.4 26 Tank height 4.2.1.2 33 Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume URV 4.2.5.1 40 Wear 3.1.1 28		4.2.2.2	34
Tank design 4.2.5.8.1 43 Tank empty detection 4.2.3.5 38 Tank geometry 4.2.1 33 Tank height 1.4 26 Tank height 4.2.1.2 33 Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Tag	4.6.6	50
Tank empty detection 4.2.3.5 38 Tank geometry 4.2.1 33 Tank height 1.4 26 Tank height 4.2.1.2 33 Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Tank characteristic	4.2.5.7	41
Tank geometry 4.2.1 33 Tank height 1.4 26 Tank height 4.2.1.2 33 Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Tank design	4.2.5.8.1	43
Tank height 1.4 26 Tank height 4.2.1.2 33 Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Tank empty detection	4.2.3.5	38
Tank height 4.2.1.2 33 Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Tank geometry	4.2.1	33
Tank height 4.2.5.8.4 44 Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Tank height	1.4	26
Tank volume 4.2.5.8.3 44 Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Tank height	4.2.1.2	33
Temperature unit 4.1.4 33 Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume unit 41.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Tank height	4.2.5.8.4	44
Units 4.1 32 Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Tank volume	4.2.5.8.3	
Validity 3.4.4 32 Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Temperature unit	4.1.4	33
Volume 2.3 27 Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume unit 41.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Units		32
Volume damping 4.2.5.3 40 Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Validity		
Volume LRV 4.2.5.2 40 Volume Parameters 4.2.5 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28	Volume	2.3	27
Volume Parameters 4.2.5 40 Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28		4.2.5.3	40
Volume unit 4.1.2 32 Volume URV 4.2.5.1 40 Wear 3.1.1 28		4.2.5.2	40
Volume URV 4.2.5.1 40 Wear 3.1.1 28			
Wear 3.1.1 28	Volume unit		32
	Volume URV		
Window tracking 4.2.3.4 38			
	Window tracking	4.2.3.4	38

Appendix II

Programming Chart

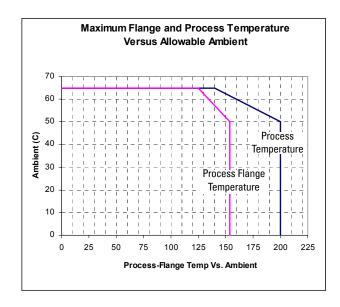
Menu Identification Number	Parameter Name	Value
1	Auto-Setup	
1.1	Language local	
1.2	Length unit	
1.3	Nozzle height	
1.4	Tank height	
1.5	Level URV	
1.6	Level LRV	
1.7	Level damping	
2	Display	
2.1	Multi-display	
2.2	Level	
2.3	Volume	
2.5	Current output	
2.6	Digital output	
3	Diagnostics	
3.1	Status	
3.1.1	Wear	
3.1.x	Sensor, electronics, software, application,	
	parameters and or service	
3.1.1.1	Operating hours	
3.1.1.2	Maximum temperature	
3.1.1.3	Minimum temperature	
3.1.1.4	Aging	
3.1.1.5	Hours > 85°C	
3.2	Device test	
3.2.1	Self-test	
3.2.2	Display test	
3.3	Simulation	
3.3.1	Simulate A0	
3.3.2	Simulate DO	
3.4	Sensor variables	
3.4.1	Raw value	
3.4.2	Echo amplitude	
3.4.3	S/N ratio	
3.4.5	Sensor temperature	
3.4.4	Validity	
4	Device data	
4.1	Units	
4.1.1	Length unit	
4.1.2	Volume unit	

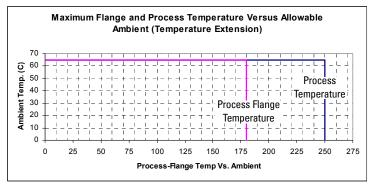
Menu		
Identification	Parameter Name	Value
Number		
4.1.4	Temperature unit	
4.1.5	Other units	
4.2	Operating Parameters	
4.2.1	Tank geometry	
4.2.1.1	Nozzle height	
4.2.1.2	Tank height	
4.2.1.3	Stilling pipe?	
4.2.1.3	Pipe diameter (if 4.2.1.3 = yes)	
4.2.2	Measuring conditions	
4.2.2.1	Application type	
4.2.2.2	Surface	
4.2.2.3	Dead band	
4.2.2.4	Correction factor	
4.2.2.5	Filling speed	
4.2.2.7	Failsafe level	
4.2.2.8	Failsafe timer	
4.2.2.9	Range Extension	
4.2.3	Sensor parameter	
4.2.3.1	Sensor damping	
4.2.3.2	Multiple echo	
4.2.3.3	Echo motion	
4.2.3.4	Window tracking	
4.2.3.5	Tank empty detection	
4.2.3.6	Auto fix distance	
4.2.3.7	Fix distance list	
4.2.3.9	Auto False Echo Suppression	
4.2.3.A	Auto False Echo Suppression Distance	
4.2.4	Level parameters	
4.2.4.1	Level URV	
4.2.4.2	Level LRV	
4.2.4.3	Level damping	
4.2.4.4	MinLim level	
4.2.4.5	MaxLim level	
4.2.4.6	HYST level	
4.2.5	Volume Parameters	
4.2.5.1	Volume URV	
4.2.5.2	Volume LRV	
4.2.5.3	Volume damping	
4.2.5.4	MinLim Volume	
4.2.5.5	MaxLim Volume	
4.2.5.6	HYST volume	
4.2.5.7	Tank characteristic	
4.2.5.8	Calibrate/table	
4.2.5.8.1	Calibrate	
4.2.5.8.2	Enter table	
4.2.5.8.3	Show table	
4.2.5.8.4	Clear table	

Menu Identification Number	Parameter Name	Value
4.2.5.8	Calculate	
4.2.5.8.1	Tank design	
4.2.5.8.2	Bottom design	
4.2.5.8.3	Tank volume	
4.2.5.8.4	Tank height	
4.3	Analog output	
4.3.1	A0 select	
4.3.2	Volume parameter	
4.3.2	Level parameter	
4.3.3	Current limit	
4.3.4	Error signal	
4.4	Digital output	
4.4.1	Function DO	
4.4.2	Signal type DO	
4.4.3	Volume parameter	
4.4.3	Level parameter	
4.5	Display parameter	
4.5.1	Multi-display	
4.5.1.1	Line 1 local	
4.5.1.2	Display local	
4.5.1.3	Volume parameter	
4.5.1.3	Level parameter	
4.5.1.4	Line 2 local	
4.5.1.5	Volume parameter	
4.5.1.5	Level parameter	
4.5.2	Language local	
4.5.3	LCD lighting	
4.6	Device info	
4.6.1	Power supply	
4.6.2	Flange temperature	
4.6.3	Explosion protection	
4.6.4 4.6.5	Electrical connection	
4.6.5.1	Antenna&flange Flange size	
4.6.5.2	Flange type	
4.6.5.3	Pressure stage	
4.6.5.4	Antenna type	
4.6.5.6	Flange material	
4.6.5.7	Seal material	
4.6.6	Tag	
4.6.7	Descriptor	
4.6.8	Message	
4.6.9	Manufacturer identification	
4.6.9.1	Serial no.	
4.6.9.2	Order no.	
4.6.9.3	Device Revision	
4.6.9.4	Software revision	
	1	

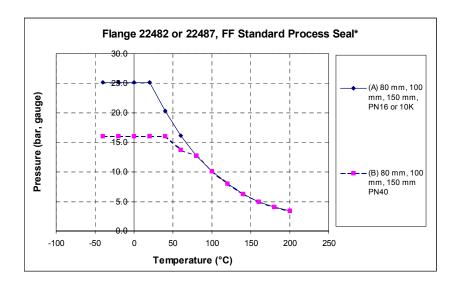
Menu Identification Number	Parameter Name	Value
4.6.9.5	Hardware revision	
4.6.9.6	Antenna offset	
4.6.9.7	Reference distance	
5	Options	
5.1	Enter code	
5.2	Customer code	
5.3	Factory reset	

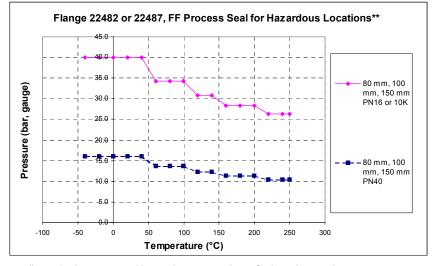
Ambient/Operating Temperature Specification





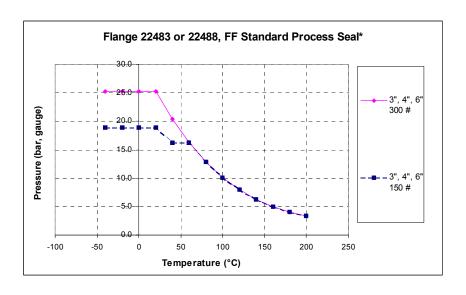
Process Pressure/Temperature de-Rating

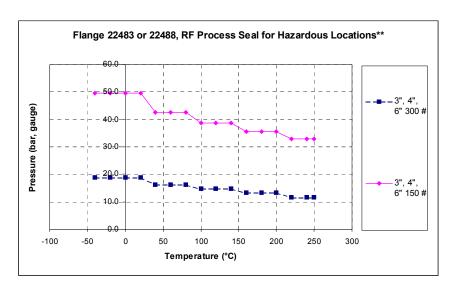




^{*} standard process seal is rated to a max. of 200°C of continuous duty.

^{*}process seal for hazardous location is rate for a max of 290°C of continuous duty.





^{*} standard process seal is rated to a max. of 200°C of continuous duty.

^{*}process seal for hazardous location is rated to a max of 290°C of continuous duty.

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