

# Encompass™ 4/4800 Multiprotocol Reader System Guide

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## **Encompass 4/4800 Multiprotocol Reader System Guide**

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**WARNING TO USERS IN THE UNITED STATES**

**FEDERAL COMMUNICATIONS COMMISSION (FCC)  
LOCATION AND MONITORING SERVICE STATEMENT  
47 CFR §90.351**

**NOTE:** The user is required to obtain a Part 90 site license from the FCC to operate this radio frequency identification (RFID) device in the United States. See product label for FCC ID number. Access the FCC Web site at [www.fcc.gov/Forms/Form601/601.html](http://www.fcc.gov/Forms/Form601/601.html) for additional information concerning licensing requirements.

**NOTE:** Users in all countries should check with the appropriate local authorities for licensing requirements.

**FCC RADIO FREQUENCY INTERFERENCE STATEMENT  
47 CFR §15.105(a)**

**NOTE:** This equipment has been tested and found to comply with the limits for a Class A digital device pursuant to Part 15 of the FCC rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate RF energy and may cause harmful interference to radio communications if not installed and used in accordance with the instruction manual. Operating this equipment in a residential area is likely to cause harmful interference, in which case, depending on the laws in effect, the user may be required to correct the interference at their own expense.

**NO UNAUTHORIZED MODIFICATIONS  
47 CFR §15.21**

**CAUTION:** This equipment may not be modified, altered, or changed in any way without permission from TransCore, LP. Unauthorized modification may void the equipment authorization from the FCC and will void the TransCore warranty.

**USE OF SHIELDED CABLES IS REQUIRED  
47 CFR §15.27(a)**

**NOTE:** Shielded cables must be used with this equipment to comply with FCC regulations.

**TransCore, LP  
USA**

## Health Limits (865 to 875 MHz)

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Within the United States, environmental guidelines regulating safe exposure levels are issued by the Occupational Safety and Health Administration (OSHA).

Section 1910.97 of OSHA Safety and Health Standards 2206 legislates a maximum safe exposure limit of 10 milliwatts per square centimeter ( $\text{mW}/\text{cm}^2$ ) averaged over 6 minutes at 865 MHz.

Although not binding, other organizations such as the American National Standards Institute (ANSI) have issued similar guidelines that are more restrictive than the OSHA limits (ANSI C95.1). ANSI guidelines recommend a maximum safe power density in  $\text{mW}/\text{cm}^2$  of:

**Frequency (in MHz)**  
**1500**

Thus, the maximum permissible exposure for general population/uncontrolled exposure at 865 MHz is  $0.58 \text{ mW}/\text{cm}^2$ . The power limit is a six-minute average.

The RF power density generated by the Encompass™ 4/4800 Multiprotocol Reader was calculated using a maximum antenna gain of 9.5 dBi, equivalent to the antenna gain of the internal antenna.



### **Warning**

*At 2 W transmitted power and a distance of 19.7 inches (50 cm) from the reader, the maximum power density calculated was less than  $0.58 \text{ mW}/\text{cm}^2$ . Install the reader at least 19.7 inches (50 cm) from the general public. Maintenance personnel must remain at least 9.1 inches (23 cm) from reader when system is operating.*

The data confirms that the TransCore Encompass 4/4800 Multiprotocol Reader effectively meets OSHA requirements and thus does not represent an operating hazard to either the general public or maintenance personnel.

## Health Limits (902 to 928 MHz)

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Within the United States, environmental guidelines regulating safe exposure levels are issued by the Occupational Safety and Health Administration (OSHA).

Section 1910.97 of OSHA Safety and Health Standards 2206 legislates a maximum safe exposure limit of 10 milliwatts per square centimeter ( $\text{mW}/\text{cm}^2$ ) averaged over 6 minutes at 902 MHz.

Although not binding, other organizations such as the American National Standards Institute (ANSI) have issued similar guidelines that are more restrictive than the OSHA limits (ANSI C95.1). ANSI guidelines recommend a maximum safe power density in  $\text{mW}/\text{cm}^2$  of:

**Frequency (in MHz)**  
**1500**

Thus, the maximum permissible exposure for general population/uncontrolled exposure at 902 MHz is  $0.60 \text{ mW}/\text{cm}^2$ . The power limit is a six-minute average.

The RF power density generated by the Encompass 4/4800 Multiprotocol Reader was calculated using a maximum antenna gain of 9.5 dBi, equivalent to the antenna gain of the internal antenna.



**Warning**

*At 2 W transmitted power and a distance of 19.3 inches (49 cm) from the reader, the maximum power density calculated was less than  $0.60 \text{ mW}/\text{cm}^2$ . Install the reader at least 19.3 inches (49 cm) from the general public. Maintenance personnel must remain at least 8.66 inches (22 cm) from reader when system is operating.*

The data confirms that the TransCore Encompass 4/4800 Multiprotocol Reader effectively meets OSHA requirements and thus does not represent an operating hazard to either the general public or maintenance personnel.

PRELIMINARY

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PRELIMINARY





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PRELIMINARY

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Introduction

PRELIMINARY





## Introduction

***This chapter is the introduction to this manual and provides information pertaining to the audience, organization, document conventions, system description, and license information for the Encompass™ 4/4800 Multiprotocol Reader System.***

### **Purpose**

---

This guide provides site planning and testing, installing, and operating instructions for TransCore's Encompass 4/4800 Multiprotocol Reader System, a dual-protocol reader that reads Intellitag®-based eGo protocol and American Trucking Associations (ATA)/International Organization for Standardization (ISO) tag protocols. Before you begin installing the Encompass 4/4800 Multiprotocol Reader System, TransCore recommends that you read this entire manual.

### **Audience**

---

This document is intended to be used by authorized TransCore Encompass 4/4800 Multiprotocol Reader System dealers, installers, and service personnel. Because the Encompass 4/4800 Multiprotocol Reader System has no operator- or end-user serviceable components or features, no end-user manual or operator guide exists. Once the system is set up and tested by the *authorized* installer, Encompass 4/4800 Multiprotocol Reader System operation requires no end-user intervention.

### **System Guide Organization**

---

**Note:** *TransCore offers the Encompass 4/4800 Multiprotocol Reader in two models: one with an internal antenna and one that requires connection to an external antenna. In this system guide, information and instructions for both Encompass 4/4800 Multiprotocol Reader models are presented. Where separate sections dictate, a section detailing one Encompass 4/4800 Multiprotocol Reader model is followed immediately with a section detailing the other reader model. In this system guide, the reader with an internal antenna is listed first. In cases where the information does not warrant a separate section, the addition of "...or antenna" distinguishes between the Encompass 4/4800 Multiprotocol Reader models.*

The chapters of this guide and a description of the contents are listed below.

- Chapter 1, "[Introduction](#)," explains the purpose and describes the audience for the guide, outlines the manual's organization, provides a brief description of the Encompass 4/4800 Multiprotocol Reader system, and discusses Federal Communications Commission (FCC) licensing requirements.



- *Chapter 2, “Developing the Site Plan,” discusses factors to be considered when developing the site plan and before ordering equipment and installing the Encompass 4/4800 Multiprotocol Reader System. These considerations include reader or antenna and tag alignment, site layout and traffic flow, and electrical and communications requirements.*
- Chapter 3, “Choosing, Installing, and Removing Tags,” contains information on compatible tag models and provides procedures for installing tags onto, and removing tags from, vehicles that use the facility where the Encompass 4/4800 Multiprotocol Reader System is installed.
- *Chapter 4, “Installing the Encompass 4/4800 Multiprotocol Reader System,” lists the materials needed and provides procedures to install the Encompass 4/4800 Multiprotocol Reader System. Steps include:*
  - *Pre-testing*
  - *Installing the Encompass 4/4800 Multiprotocol Reader System on a round pole or flat surface*
  - *Connecting power and communications*
  - *Marking the read zone.*
- Chapter 5, “General Software Information,” and Chapter 6, “Communications Protocols,” provide reference information on various software-related topics and communications protocols.
- Chapter 7, “Commands,” discusses the host-transmitted commands that are used to control Encompass 4/4800 Multiprotocol Reader System configuration and operation.
- Chapter 8, “Configuring the Encompass 4/4800 Multiprotocol Reader System,” provides procedures for configuring and fine-tuning the Encompass 4/4800 Multiprotocol Reader System after installing it at the site.
- *Chapter 9, “Troubleshooting and Maintenance,” answers the most commonly asked questions about installing and maintaining the Encompass 4/4800 Multiprotocol Reader System.*
- Appendix A, “Glossary,” contains frequently used terms.
- *Appendix B, “Technical Specifications,” provides the Encompass 4/4800 Multiprotocol Reader System specifications.*
- *Appendix C, “Wiring Tables,” shows the wiring connections for the communications interfaces, electrical cable connections, and the external interface signal wiring.*
- Appendix D, “Command Quick Reference,” lists the Encompass 4/4800 Multiprotocol Reader System factory default configuration settings and provides host software commands in numerical and alphabetical order.
- Appendix E, “Compatible Tag Information,” provides helpful information about tags that are compatible with the Encompass 4/4800 Multiprotocol Reader System.

## Typographical Conventions

---

The following conventions are used in this manual:

**Table 1-1 Typographical Conventions**

Convention	Indication
	Concerns about a procedure.
Code	Code, including keywords and variables within text and as separate paragraphs, and user-defined program elements within text appear in courier typeface.
<b>Dialog Box Title</b>	Title of a dialog box as it appears on screen.
<b>Menu Item</b>	Appears on a menu. Capitalization follows the interface.
<i>Note</i>	Auxiliary information that further clarifies the current discussion. These important points require the user's attention. The paragraph is in italics and the word Note is bold.
NUL	Zero-value ASCII character or a zero-value byte.
NULL	Zero-value pointers. Null-terminated string refers to strings of printable ASCII characters with a zero-value byte placed in memory directly after the last printable character of the string.
	This procedure might cause harm to the equipment and/or the user.

## System Description

---

The Encompass 4/4800 Multiprotocol Reader System is a dual-protocol reader supporting the low-cost, high-performance Intellitag® radio frequency identification (RFID) technology. Intellitag technology provides the capability to read miniature RFID tags in a myriad of options including rugged, durable, or thin flexible forms such as the eGo Windshield Sticker Tag. The Encompass 4/4800 Multiprotocol Reader System also supports legacy transportation applications such as gated toll, parking, or security gate access and is designed to be compatible with existing TransCore SmartPass® parking access control applications certified for licensed use. The Encompass 4/4800 Multiprotocol Reader System supports the TransCore eGo and TransCore ATA/ISO tag types.

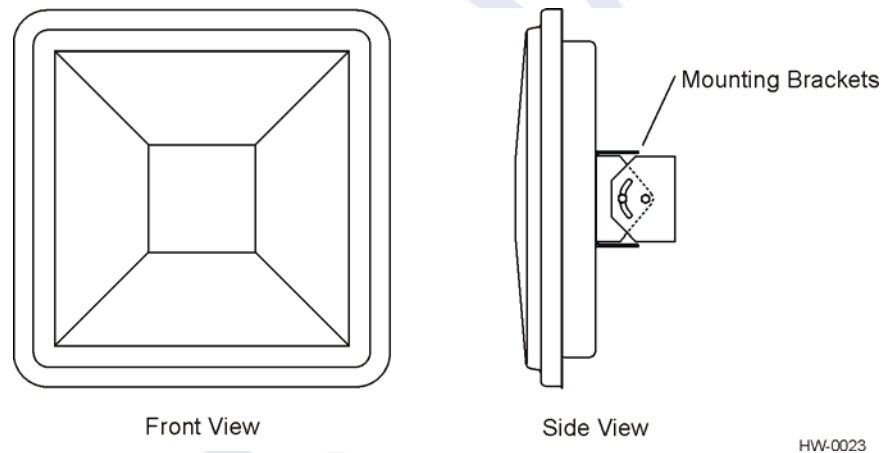
The Encompass 4/4800 Multiprotocol Reader System is a full-frame high-power unit that can read both half-frame and full-frame tags. The reader output power can be adjusted using reader commands.

---

## **Reader**

The Encompass 4/4800 Multiprotocol Reader System consists of an input/output (I/O) module, a power supply, a reader logic board (also called a tag decoder), a radio frequency (RF) transmitter/receiver (called the RF module), and a patch antenna.

A second version of the Encompass 4/4800 Multiprotocol Reader is designed to be used with a high-performance external antenna. These Encompass 4/4800 Multiprotocol Reader System components are contained in a highly reliable, compact, and easy-to-install environmentally-sealed package. Figure 1-1 shows the front and side views of an Encompass 4/4800 Multiprotocol Reader System.



**Figure 1-1 Encompass 4/4800 Multiprotocol Reader System Front and Side Views**

---

## **Tags**

The Encompass 4/4800 Multiprotocol Reader System has the capability to read the Intellitag-based eGo Windshield Sticker Tag as well as TransCore ATA protocol and TransCore ISO-compliant read-only full- and half-frame tags.

---

## **How It Works**

The Encompass 4/4800 Multiprotocol Reader System directs the RF module to generate an RF signal, which is broadcast through the internal or external antenna. Entering the Encompass 4/4800 Multiprotocol Reader System's reading range, a TransCore RFID tag installed on a vehicle or other object to be tracked adds its programmed identification information to the signal and reflects the signal back to the Encompass 4/4800 Multiprotocol Reader System. The Encompass 4/4800 Multiprotocol Reader System receives this modified, or modulated signal, and decodes the tag data carried by the reflected signal and transmits this data to a local host computer for processing.

## Licensing Requirements

---

An FCC license provides the user with the legal authorization to operate the Encompass 4 on the licensed frequencies at the site specified in the license. Only an authorized installer or service technician can set the RF frequency of the Encompass 4/4800 Multiprotocol Reader System to the frequency specified in the FCC site license. No end-user-operated controls exist on the Encompass 4/4800 Multiprotocol Reader System.

The FCC license also provides the user with protection and authorization to maintain the system should any other RFID product be used in the licensed area after the Encompass 4/4800 equipment is installed.

Users of the Encompass 4/4800 Multiprotocol Reader System in the United States must obtain a license from the FCC. The authorized frequency band for this product in the United States is 912.5 to 919 MHz.

The user is responsible for filing the FCC license according to FCC regulations, but the TransCore dealer will provide assistance and support as necessary to complete these forms. Forms are available online at the FCC internet site <http://www.fcc.gov/formpage.html>. For further information on obtaining the license contact TransCore.

## Technical Support

---

Authorized dealers and distributors are responsible for the direct support of all customers. Authorized dealers and distributors needing technical support can contact:

Technical Support

Phone: (800) 755-0378

Web: [transcore.com/rfidsupport](http://transcore.com/rfidsupport)

or

TransCore

3410 Midcourt Road, Suite 102

Carrollton, Texas 75006 USA

Phone: (214) 461-4031

Fax: (214) 461-6478

Please be prepared to answer a series of questions that are designed to direct you to the best support resource available.

PRELIMINARY

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Developing the Site Plan

PRELIMINARY





# Developing the Site Plan

*This chapter discusses site plan development for installing the Encompass™ 4/4800 Multiprotocol Reader System.*

## Overview

---

Developing a site plan provides the foundation for the site's system design and establishes the following system configuration parameters:

- Number and general location of primary components
- Number of different radio frequencies required

Gathering relevant site information is crucial before applying for Federal Communications Commission (FCC) approval and ordering and installing Encompass 4/4800 Multiprotocol Reader(s) and tags.

Also, consider the following factors when developing a site plan:

- Type of tags used in the facility
- Reader and/or antenna and tag alignment
- Site layout and traffic flow
- Encompass 4/4800 Multiprotocol Reader and/or antenna mounting requirements
- Encompass 4/4800 Multiprotocol Reader electrical requirements
- Encompass 4/4800 Multiprotocol Reader communications requirements

These factors provide relevant information regarding each site's physical and electromagnetic environment and the conditions under which the system must perform.

## Reading of Mixed Population Tags

---

The Encompass 4/4800 Multiprotocol Reader reads the American Trucking Association (ATA) and International Organization for Standardization (ISO) read-only tags, whether powered by battery or beam, or application-specific integrated circuit (ASIC)-based tags with Intellitag technology. The reader can read the ATA or ISO read-only tags in the presence of Intellitag-based tags; however, attempting to read an Intellitag-based tag in the presence of an ATA or ISO read-only tag is not recommended.



**Caution**

*Attempting to read an Intellitag-based tag in the presence of an ATA or ISO read-only tag may provide unreliable results.*

The factors that influence the readability include, but are not limited to physical orientation and configuration, type of read-only tag, ratio of backscatter cross-section of the tags, and whether the tag is battery- or beam-powered.

## **Reader and Tag Alignment**

---

The position of the Encompass 4/4800 Multiprotocol Reader and placement of the tag on the vehicle must be compatible. Also, consider any existing tagged vehicles now using the facility to determine the optimal Encompass 4/4800 Multiprotocol Reader location and orientation at the site.

***Note:** If any of the vehicles using your facility already have tags, such as those used in toll applications, contact TransCore at 1-800-755-0378 for information about mixed-tag installations before you plan tag type, location, and programming.*

Three primary criteria must be satisfied to achieve the highest read reliability:

- Polarization of the tag and the Encompass 4/4800 Multiprotocol Reader must be aligned in the same direction — both horizontal.
- The installed tag must be in a direct, unobstructed line of sight to the Encompass 4/4800 Multiprotocol Reader .
- Tags designed to be mounted in a vehicle windshield must be mounted in the vehicle's windshield, and tags designed to be mounted on the exterior surface of the vehicle must be mounted on the exterior surface of the vehicle.



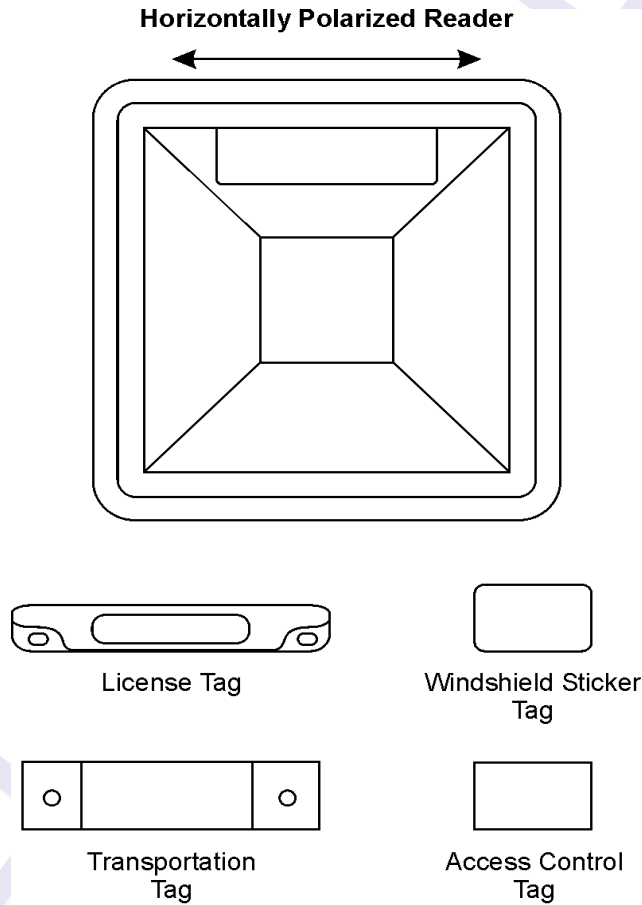
**Caution**

*A tag may not be reliably read unless the preceding criteria are met.*

## Polarization

The polarization of the tag must be aligned in the same direction as the Encompass 4/4800 Multiprotocol Reader, as shown in Figure 2-1.

*Note:* Matching the tag and antenna polarization is critical to obtain optimal system performance.

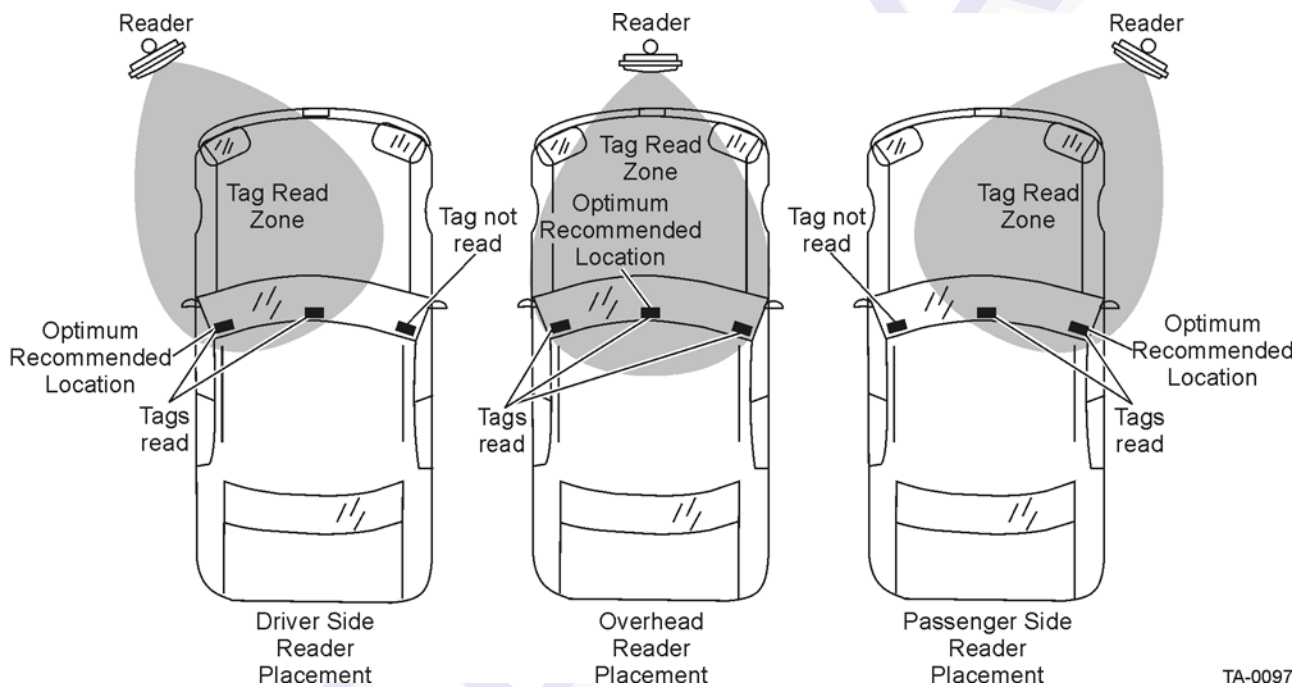


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**Figure 2-1 Tag and Reader Orientation**

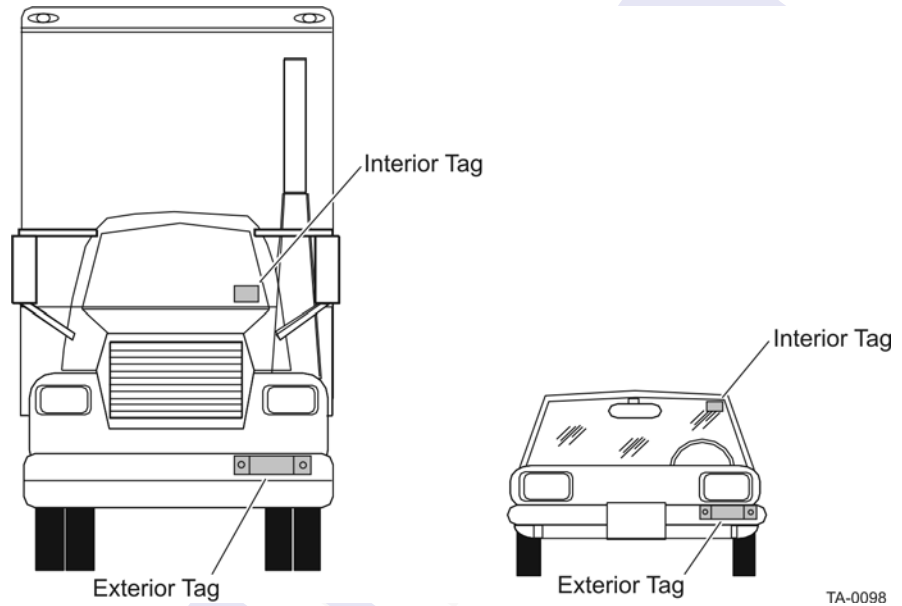
## Unobstructed Line of Sight

For optimum readability, install the Encompass 4/4800 Multiprotocol Reader and the vehicle's tag so that when the vehicle approaches the Encompass 4/4800 Multiprotocol Reader, the tag is directly facing the reader and the line of sight is clear between the Encompass 4/4800 Multiprotocol Reader and the tag. If a fence or barrier is between the tag and the reader, the Encompass 4/4800 Multiprotocol Reader cannot reliably read the tags. Figure 2-2 illustrates possible installation locations of an Encompass 4/4800 Multiprotocol Reader in relation to a tag's mounting location on a vehicle. If the tags are not in the recommended location, reliable optimum operation requires lower vehicle speeds.



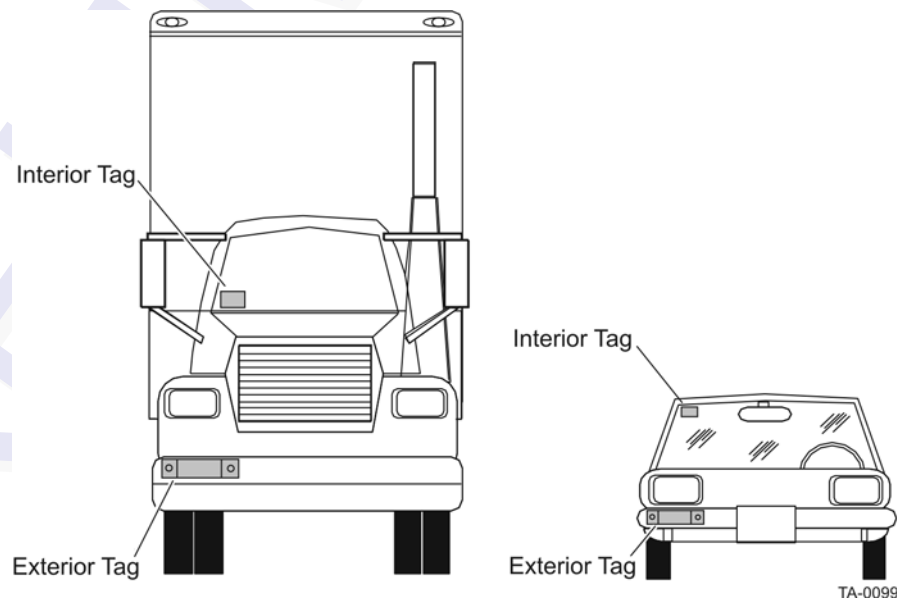
**Figure 2-2 Encompass 4/4800 Multiprotocol Reader Location Relative to Tag Position**

If the Encompass 4/4800 Multiprotocol Reader is installed on a pole or wall to the left of the vehicle, optimal tag position is on the left side of the vehicle as illustrated in Figure 2-3.



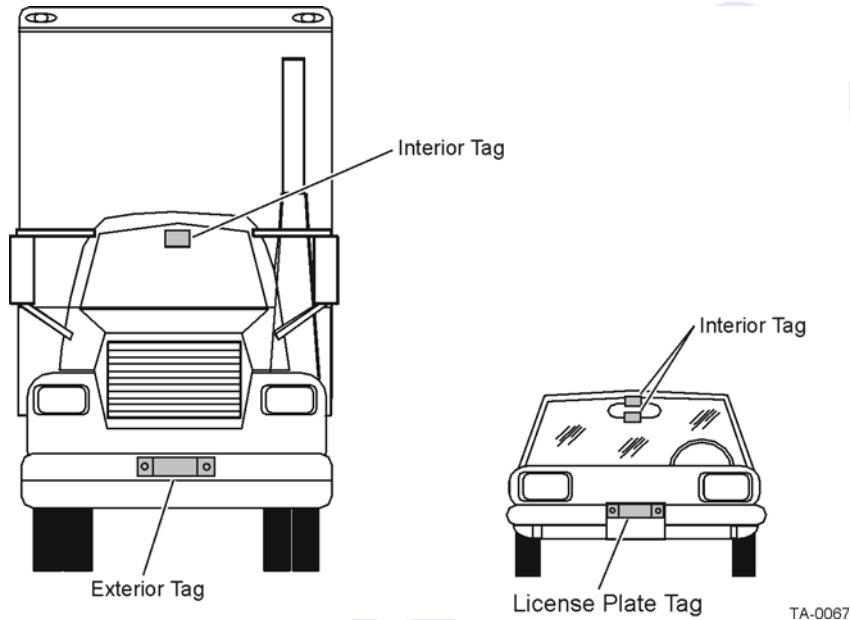
**Figure 2-3 Typical Tag Positions for U.S. Driver's Side Reader**

If an Encompass 4/4800 Multiprotocol Reader is installed on a pole or wall to the right of the vehicle, optimal tag position is on the right side of the vehicle as illustrated in Figure 2-4.



**Figure 2-4 Typical Tag Positions for U.S. Passenger's Side Reader**

If the Encompass 4/4800 Multiprotocol Reader is installed in an overhead location, optimal tag position is in the top center of the windshield in the area behind the rear view mirror or on the vehicle's front license plate or center bumper as illustrated in Figure 2-5.



**Figure 2-5 Typical Tag Positions Used with Overhead Reader**

*Note: Metallized coatings on some vehicle windshields and windows shield the RF energy emitted by the Encompass 4/4800 Multiprotocol Reader and may cause tags to be misread. Many metallized windshields have areas that are not metallized in which the tag can be placed and reasonable results achieved. If there are no openings in the metallized coating in which to install an interior tag, install exterior-type tags on the exterior of the vehicle.*

Refer to Chapter 3 “[Choosing, Installing, and Removing Tags](#)” for more detailed information on tag positioning.

## Antenna Selection

---

This section contains guidelines that assist in antenna selection for an Encompass 4/4800 Multiprotocol Reader installation that uses an external antenna. The following antennas are compatible with the Encompass 4/4800 Multiprotocol Reader installation.

### **AA3100 Yagi (without radome)**

Appropriate for installations with the following requirements and conditions:

- 902 to 928 MHz operation
- Non-icing environments

- Relatively symmetrical reading range
  - Antenna profile not a major consideration
- 

### ***AA3101 Yagi (with radome)***

Appropriate for installations with the following requirements and conditions:

- 902 to 928 MHz operation
  - Exposure to harsh environments
  - Relatively symmetrical reading range
  - Antenna profile not a major consideration
- 

### ***AA3110 Parapanel***

Appropriate for installations with the following requirements and conditions:

- 902 to 928 MHz operation
  - Exposure to harsh environments
  - Broad radiation pattern in one dimension, narrow in the other
  - Low antenna profile
  - Horizontal polarization
- 

### ***AA3140 PCB Log Periodic***

Appropriate for installations with the following requirements and conditions:

- 845 to 950 MHz operation
  - Exposure to harsh environments
  - Maximum coverage at close range (<20 ft [6.1 M])
  - Vertical or horizontal polarization
- 

### ***AA3152 Universal Toll Antenna***

Appropriate for installations with the following requirements and conditions:

- 902 to 928 MHz operation
- Exposure to harsh environments
- Broadcast pattern of similar size and shape in both horizontal and vertical planes
- Low antenna profile

---

## AA3153 Toll Antenna

Appropriate for installations with the following requirements and conditions:

- 902 to 928 MHz operation
- Exposure to harsh environments
- Broadcast pattern with virtually no side or back lobes, which helps confine coverage to a single lane width
- Low antenna profile

---

## Antenna and Tag Alignment

---

The position of the antenna connected to the Encompass 4/4800 Multiprotocol Reader and placement of the tag on the vehicle must be compatible. Also, consider any existing tagged vehicles now using the facility to determine the optimal Encompass 4/4800 Multiprotocol Reader antenna location and orientation at the site.

*Note: If any of the vehicles using your facility already have tags, such as those used in toll applications, contact TransCore at 1-800-755-0378 for information about mixed-tag installations before you plan tag type, location, and programming.*

Three primary criteria must be satisfied to achieve the highest read reliability:

- Polarization of the tag and the Encompass 4/4800 Multiprotocol Reader antenna must be aligned in the same direction — both horizontal or both vertical.
- The installed tag must be in a direct, unobstructed line of sight to the Encompass 4/4800 Multiprotocol Reader antenna.
- Tags designed to be mounted in a vehicle windshield must be mounted in the vehicle's windshield, and tags designed to be mounted on the exterior surface of the vehicle must be mounted on the exterior surface of the vehicle.



### Caution

*A tag may not be reliably read unless the preceding criteria are met.*

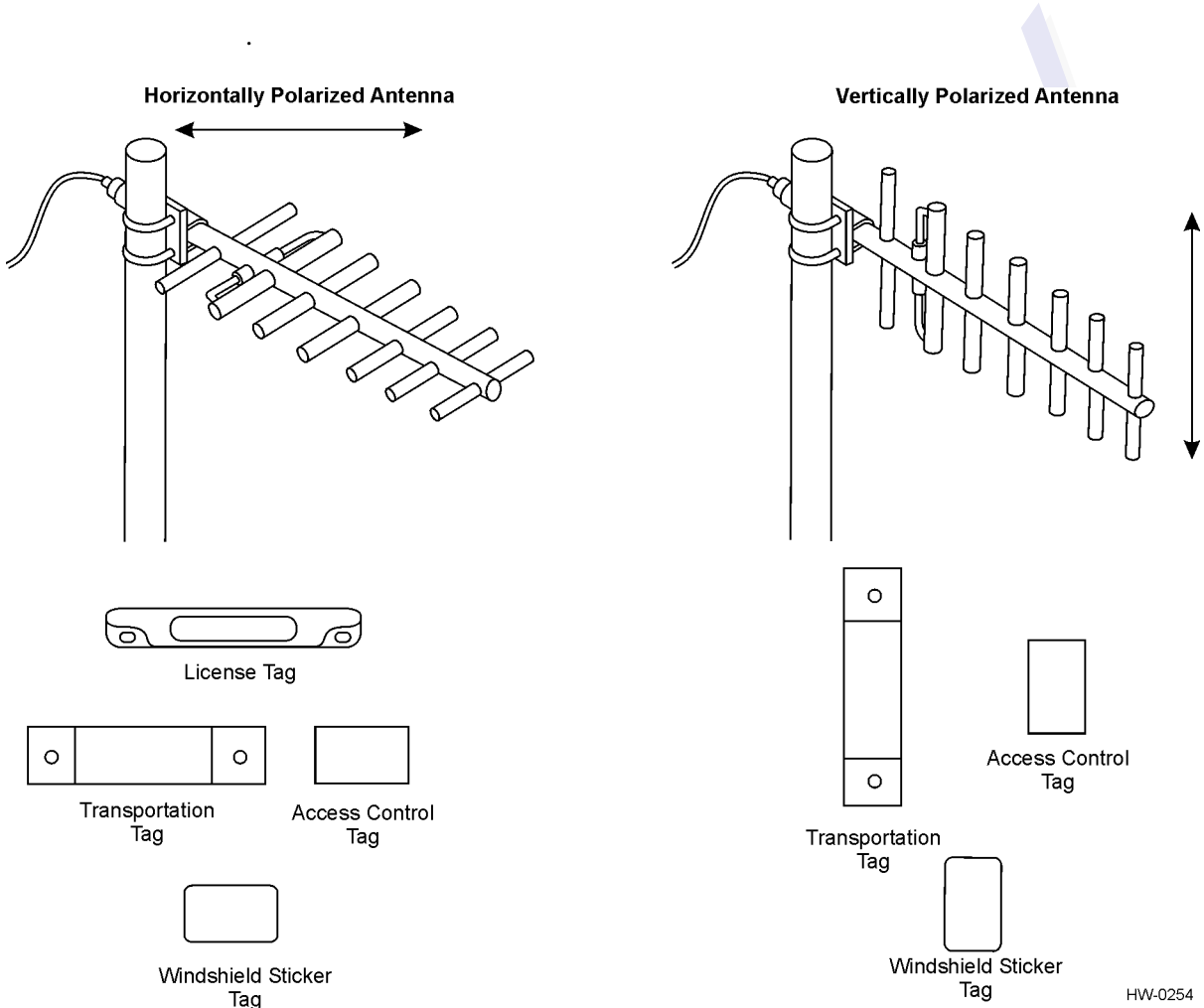
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## Polarization

The polarization of the tag must be aligned in the same direction as the antenna connected to the Encompass 4/4800 Multiprotocol Reader, as shown in Figure 2-1.

*Note: Matching the tag and antenna polarization is critical to obtain optimal system performance.*





**Figure 2-1 Horizontal and Vertical Tag Orientation**

A horizontally oriented antenna cannot read a vertically oriented tag and vice versa.

### **Unobstructed Line of Sight**

For optimum readability, install the Encompass 4/4800 Multiprotocol Reader antenna and the vehicle's tag so that when the vehicle approaches the antenna, the tag is directly facing the antenna and the line of sight is clear between the antenna and the tag. If a fence or barrier is between the tag and the antenna, the antenna cannot reliably read the tags. Figure 2-2 illustrates possible installation locations of an Encompass 4/4800 Multiprotocol Reader antenna in relation to a tag's mounting location on a vehicle. If the tags are not in the recommended location, reliable optimum operation requires lower vehicle speeds.

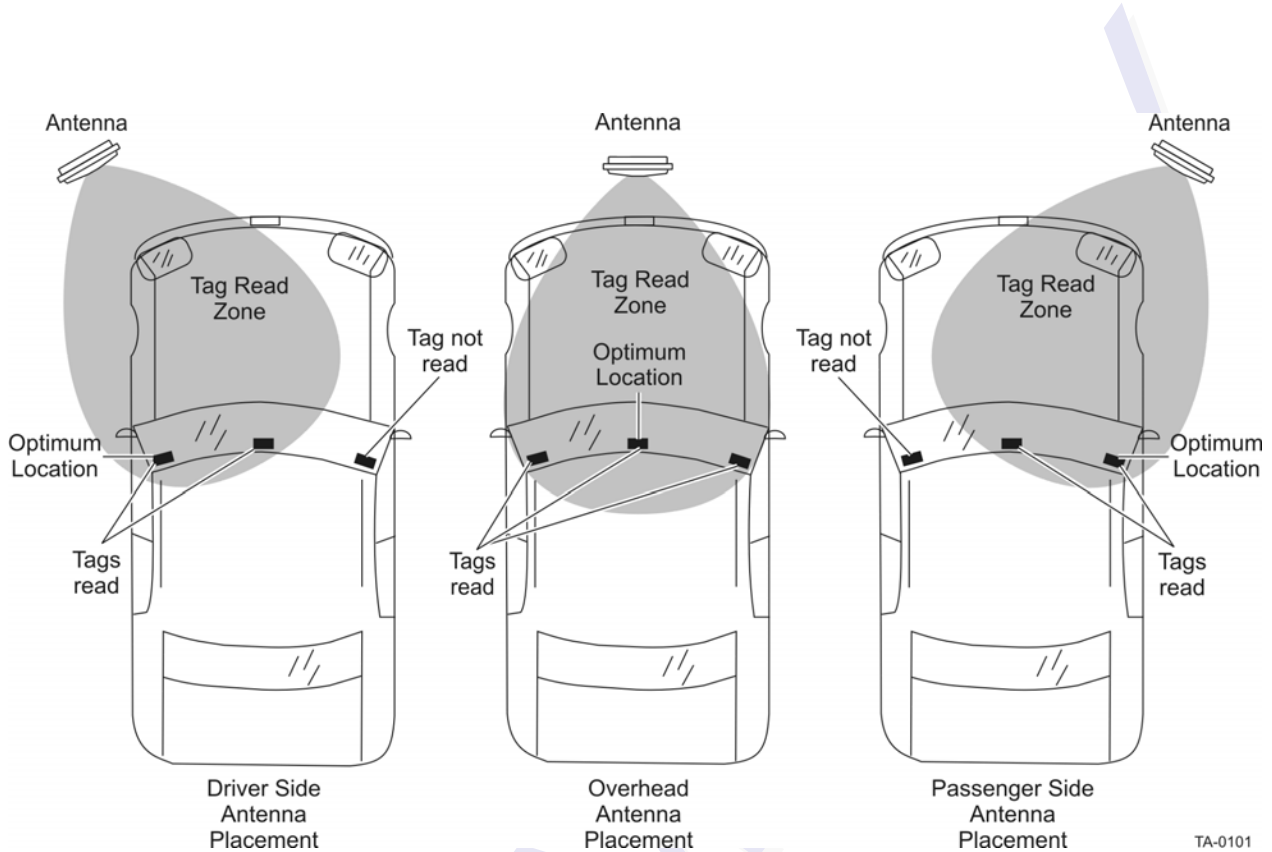


Figure 2-2 Antenna Location Relative to Tag Position

## Site Layout and Traffic Flow

The following site layout and traffic flow considerations are critical when determining Encompass 4/4800 Multiprotocol Reader installation locations:

- The Encompass 4/4800 Multiprotocol Reader read zone
- Other Encompass 4/4800 Multiprotocol Reader units and antennas in the area
- Lane configurations
- Reflection, refraction, and diffraction of RF signals
- Existing signal interference at the site

---

## ***The Encompass 4/4800 Multiprotocol Reader Read Zone***

The Encompass 4/4800 Multiprotocol Reader must be able to read the tag data properly within a specified area, called the read zone, without reading other nearby tags or interfering with other Encompass 4/4800 Multiprotocol Readers at the site. The following are some of the factors that affect the size and shape of the read zone:

- Mounting method used (pole or wall mount)
- Mounting location (overhead or side mount)
- Height from the ground and mounting angle
- Mounting method used (pole or wall mount) of the antenna
- Mounting location (overhead or side mount) of the antenna
- Height from the ground and mounting angle of the antenna
- Indoor or outdoor location
- RF output attenuation
- Range discrimination setting
- Other sources of interference and reflection

The Encompass 4/4800 Multiprotocol Reader must be positioned to allow the RF signal to travel to and return from the tags within the designated range and be placed in an area where it is not likely to be bumped out of alignment. If the antenna becomes misaligned or some nearby structure is added or removed, system operation can be seriously affected.

The external antenna must be positioned to allow the RF signal to travel to and return from the tags within the designated range and be placed in an area where it is not likely to be bumped out of alignment. If the antenna becomes misaligned or some nearby structure is added or removed, system operation can be seriously affected.

For instructions on setting the read zone, see [“Fine-Tuning and Verifying the Read Zone”](#) on page 8-20.

---

## ***Other Encompass 4/4800 Multiprotocol Readers in the Area***

Sites with more than one Encompass 4/4800 Multiprotocol Reader in proximity should have them configured with a frequency separation of at least 2 MHz from adjacent readers. If more than one Encompass 4/4800 Multiprotocol Reader is in a side-by-side or multiple lane application, the frequencies should be staggered. Also, Encompass 4/4800 Multiprotocol Readers may not operate accurately if they directly face each other or are positioned back-to-back.

If more than one Encompass 4/4800 Multiprotocol Reader and antenna is in a side-by-side or multiple lane application, the frequencies should be staggered. Also, Encompass 4/4800 Multiprotocol Readers may not operate accurately if the antennas directly face each other or are positioned back-to-back.

Table 2-1 shows examples of staggered reader frequencies in a site with up to 14 readers.

**Table 2-1 Examples of Staggered Reader Frequencies**

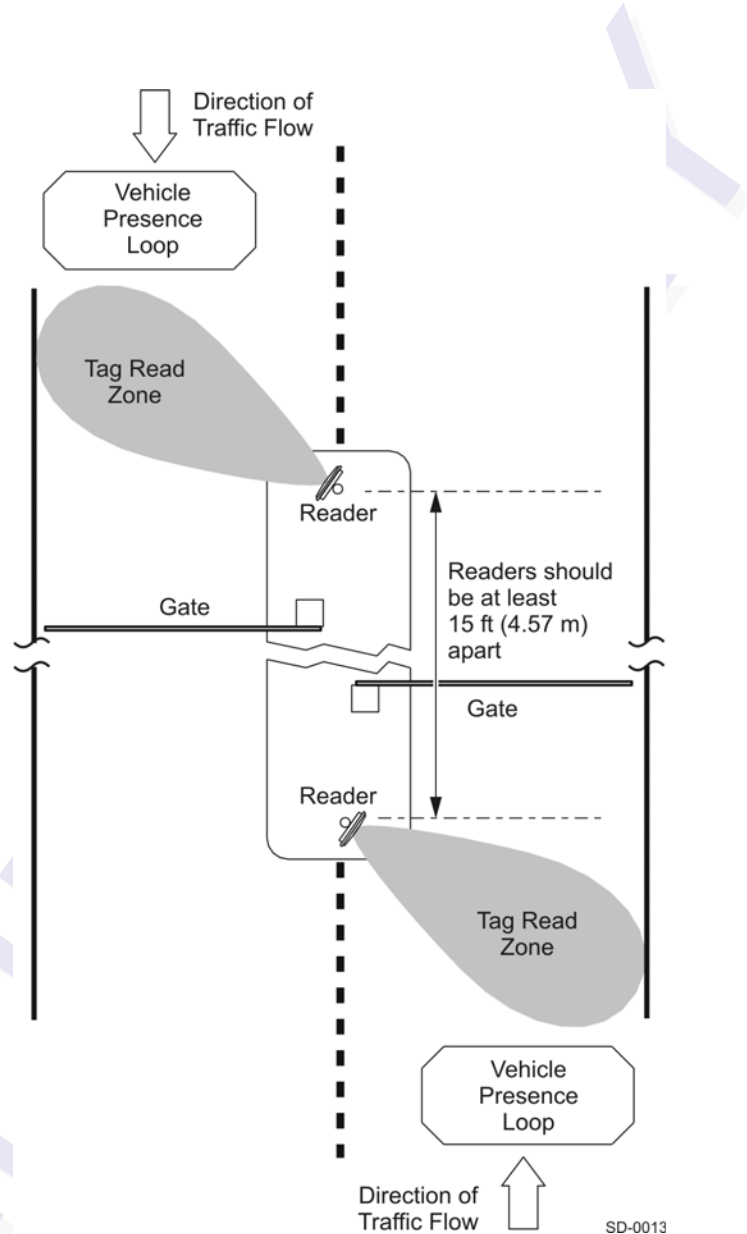
Lane Number	Reader Frequency	Lane Number	Reader Frequency
1	912.5	2	915
3	917.5	4	913.5
5	916	6	918.5
7	914.5	8	917
9	913	10	915.5
11	918	12	914
13	916.5	14	919

## **Lane Configurations**

TransCore recommends that traffic be guided through a controlled lane to consistently obtain accurate tag readings and to prevent physical damage to the Encompass 4/4800 Multiprotocol Reader. The following subsections describe some common lane configurations and offer suggestions for positioning the Encompass 4/4800 Multiprotocol Reader within the controlled traffic flow.

### **Gate with Center Island Configuration**

Figure 2-3 illustrates a typical gate application with the Encompass 4/4800 Multiprotocol Reader units positioned on a center island to read tags mounted on the inside windshield on the driver's side (United States). The readers are placed to allow time for the gate to open so the vehicle can roll through without stopping while not allowing room for an untagged vehicle to be between the vehicle being read and the gate.



**Figure 2-3 Gate Application with Center Island**

**Parking Garage with Ticket Island Configuration**

Figure 2-4 illustrates a parking garage application with each Encompass 4/4800 Multiprotocol Reader mounted on the ticket island to read tags mounted on the inside center windshield or on the center front vehicle bumper. The Encompass 4/4800 Multiprotocol Reader placement may require the vehicle to stop before the gate opens.

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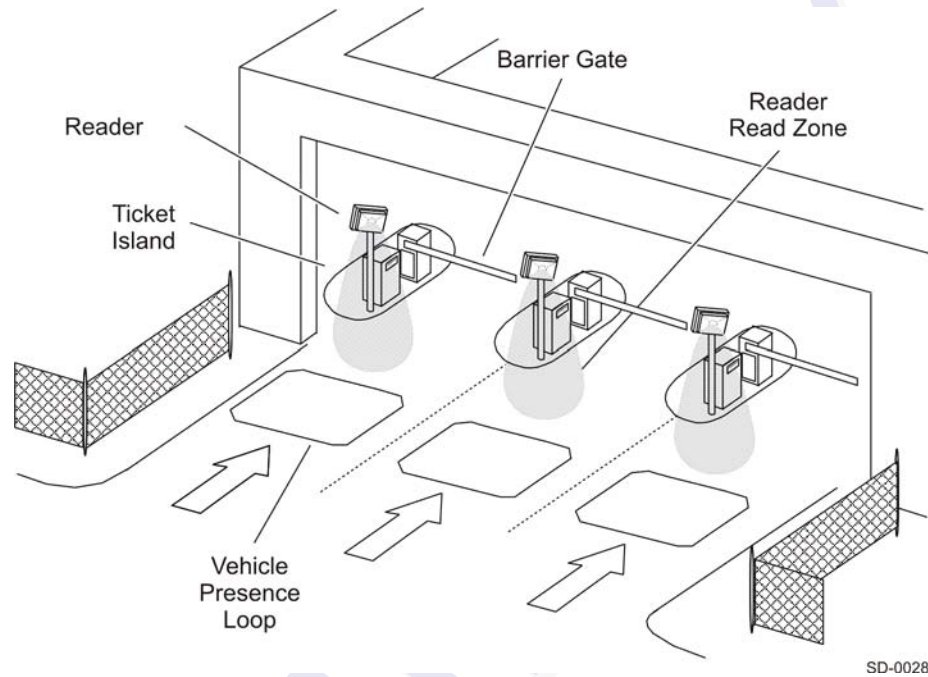


Figure 2-4 Parking Garage Application

**Overhead Reader Installation Configuration**

Another option for Encompass 4/4800 Multiprotocol Reader placement is to mount it overhead in each lane as illustrated in Figure 2-5. This illustration assumes that tags are mounted on the inside center windshield or center bumper of the vehicle.

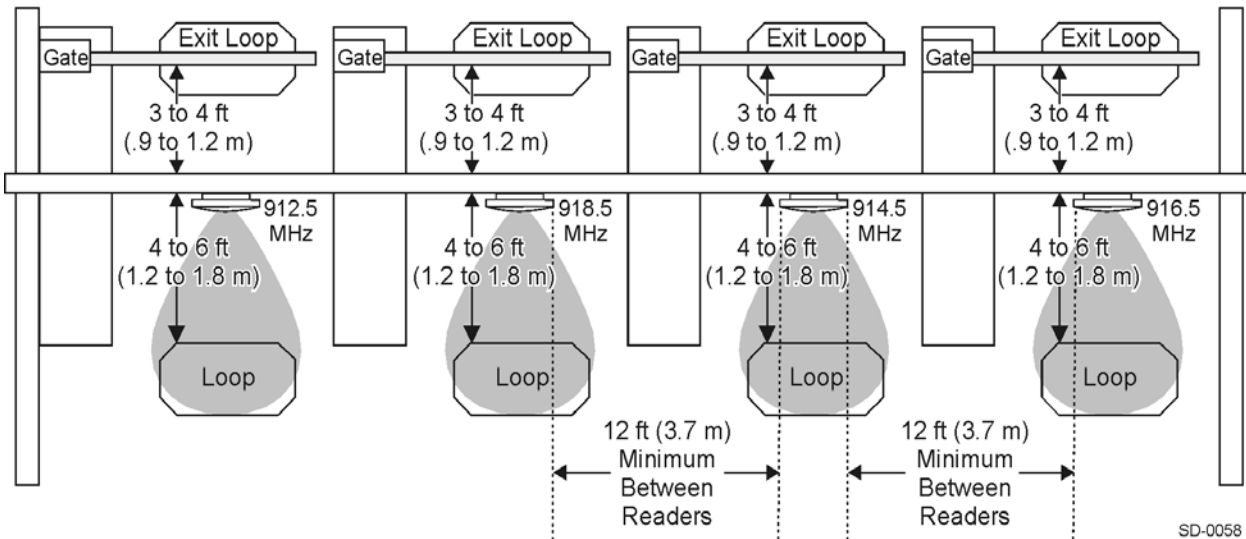


Figure 2-5 Overhead Installation

## Lane Configurations for Encompass 4/4800 Multiprotocol Readers Using an External Antenna

TransCore recommends that traffic be guided through a controlled lane to consistently obtain accurate tag readings and to prevent physical damage to the Encompass 4/4800 Multiprotocol Reader and antenna. The following subsections describe some common lane configurations and offer suggestions for positioning the external antenna within the controlled traffic flow.

### Gate with Center Island Configuration

Figure 2-3 illustrates a typical gate application with the readers and antennas positioned on a center island to read tags mounted on the inside windshield on the driver's side (United States). The antennas are placed to allow time for the gate to open so the vehicle can roll through without stopping while not allowing room for an untagged vehicle to be between the vehicle being read and the gate.

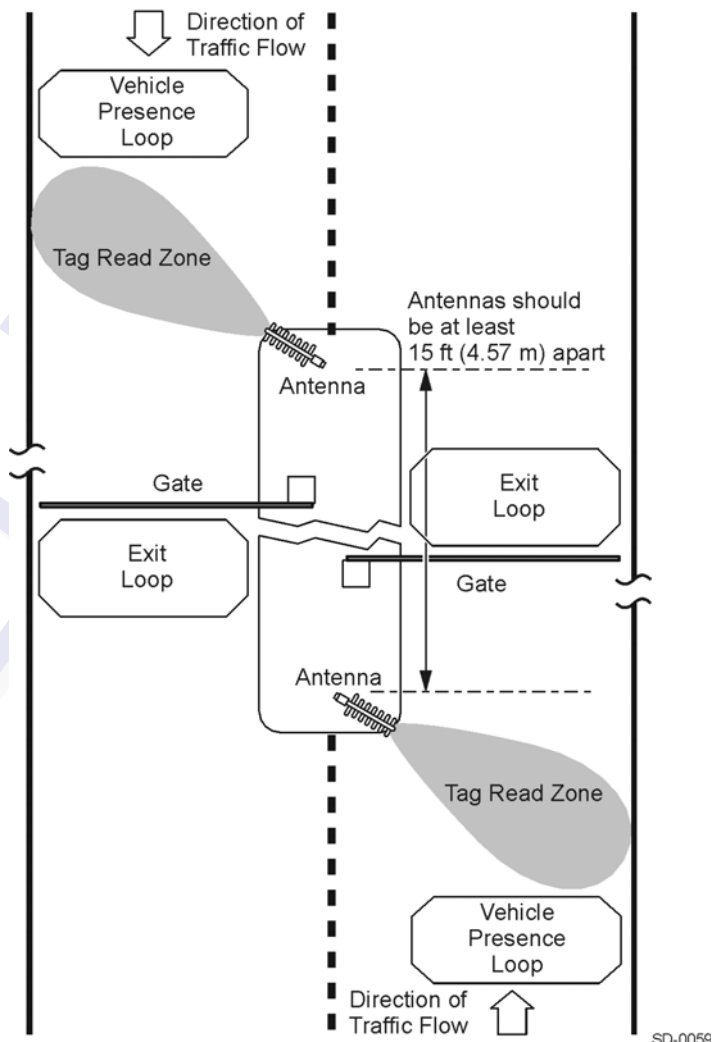
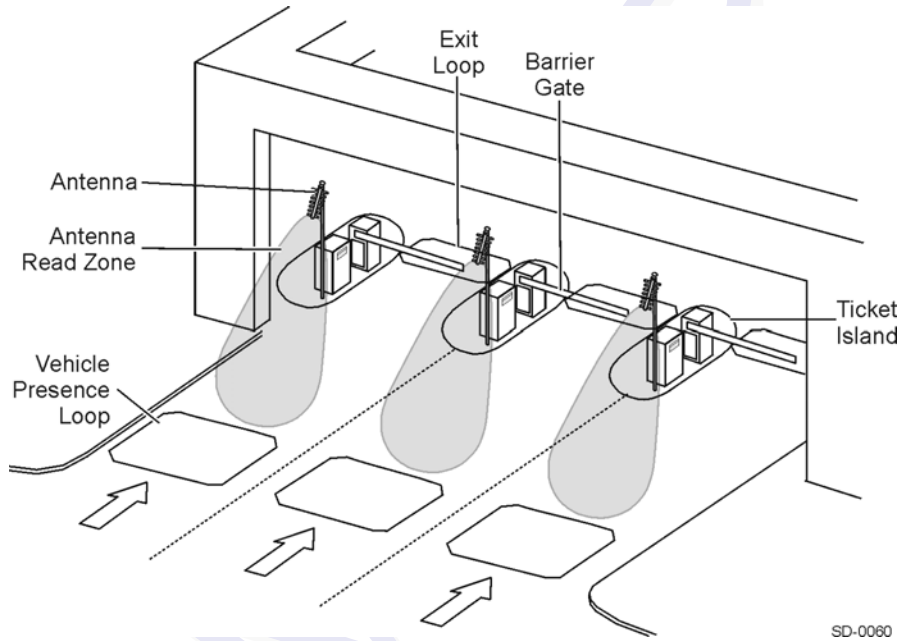


Figure 2-6 Gate Application with Center Island

### **Parking Garage with Ticket Island Configuration**

Figure 2-4 illustrates a parking garage application with each Encompass 4/4800 Multiprotocol Reader and antenna mounted on the ticket island to read tags mounted on the inside center windshield or on the center front vehicle bumper. The Encompass 4/4800 Multiprotocol Reader antenna placement may require the vehicle to stop before the gate opens.

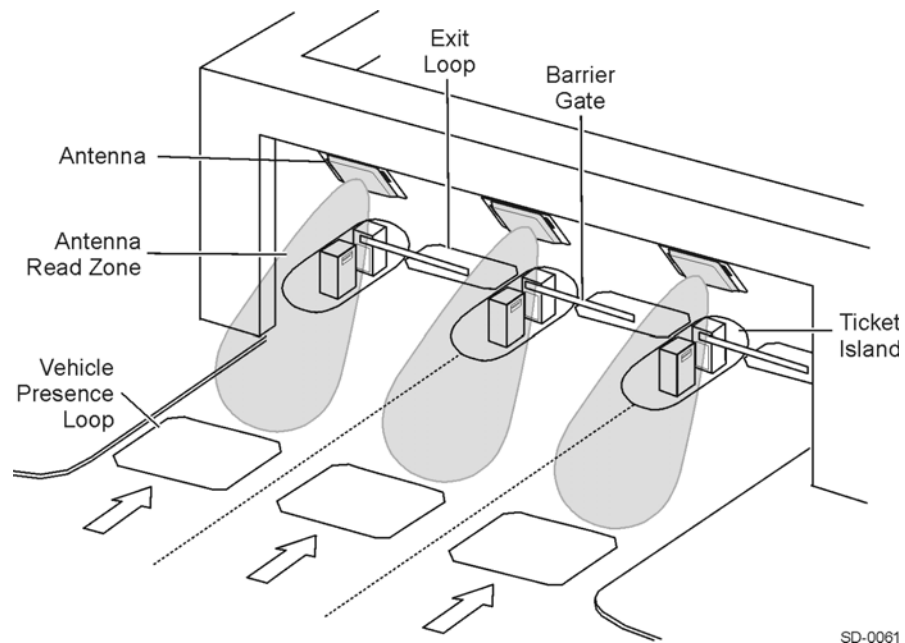


**Figure 2-7 Parking Garage Application**

### **Overhead Reader Installation Configuration**

Another option for Encompass 4/4800 Multiprotocol Reader antenna placement is to mount it overhead in each lane as illustrated in Figure 2-5. This illustration assumes that tags are mounted on the inside center windshield or center bumper of the vehicle.





**Figure 2-8 Overhead Installation**

## Reflection, Refraction, and Diffraction of RF Signals

RF signals can be reflected, refracted, or diffracted by metal objects, walls, and even wet pavement or ice. Any of these factors can alter or degrade system performance. When designing your site plan, you must consider permanent structures and transient factors in the vicinity that may affect RF signals being generated by the Encompass 4/4800 Multiprotocol Reader. Permanent structures include buildings, chain link fences, guard shacks, and gates. Transient factors include passing traffic and local weather conditions, such as rain or snow. Symptoms of reflection, refraction, and diffraction include reading tags that are out of the desired read zone or tags being read from another lane.

The most common RF reflectors are metallic surfaces. RF signals may also be partially reflected by nonconducting materials such as dirt, wood, ice, asphalt, and concrete. When nonconducting materials in the system environment become wet, they increase reflection of RF signals.

The Encompass 4/4800 Multiprotocol Reader and/or antenna mounting location, aiming, and range control adjustment, and use of presence detectors can reduce interference from RF reflections. When these actions cannot adequately control reflections, other techniques such as shielding, absorbing, range sensitivity adjustment, or barriers can also be used. See Chapter 9, “[Troubleshooting and Maintenance](#)” for more information.

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## Existing Interference

Interference from RF and electrical sources can degrade system performance and must also be considered in the site design. Fluorescent lights, neon signs, nearby radio stations, or power lines can interfere with the optimal operation of the system. The magnetic impulse noise from relays that control gate opening and closing can also disrupt the RF signal.

Interference may degrade both reader and tag performance. Existing interference at the site may be shielded, removed, or positioned further from the Encompass 4/4800 Multiprotocol Reader and/or antenna. In some cases, changing the operating frequency of the Encompass 4/4800 Multiprotocol Reader may provide a simple solution. Readers in proximity should have at least a 2 MHz frequency separation. See [“Other Encompass 4/4800 Multiprotocol Readers in the Area” on page 2-13](#). Strong RF sources of any frequency, in proximity to the tag, can preclude the tag receiving the reader interrogation. See Chapter 9, [“Troubleshooting and Maintenance.”](#)

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## Electrical and Communications Requirements

All construction work at the site must be completed before installing the Encompass 4/4800 Multiprotocol Reader. Electrical and communications cables should be installed according to all applicable local and federal building code requirements. Specific instructions for positioning and installing the Encompass 4/4800 Multiprotocol Reader are discussed in Chapter 4, [“Installing the Encompass 4/4800 Multiprotocol Reader.”](#)

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### Junction Box

Use a watertight junction box that meets applicable local and national building codes for connecting power and communications wiring. The junction box houses the terminal strip for power and communications connections. TransCore recommends a NEMA Type-4 junction box with a back mounting panel.

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### Power and Communications Cables

Cable length for power and communications depends on the physical characteristics of the Encompass 4/4800 Multiprotocol Reader installation site. Table 2-1 lists accessory kits available for cabling options based on your site’s requirements.

**Table 2-1 Connector Cabling Accessory Kits**

Part Number	Description
58-1620-001	5-ft connector cable harness
58-1620-002	20-ft connector cable harness

**Table 2-1 Connector Cabling Accessory Kits (continued)**

Part Number	Description
20-1620-003	Connector kit only
56-1620-004	13-pair cable (sold by the foot)
76-1620-005	110V AC to 18V AC Class C transformer
76-1620-006	12V AC to 18V AC step-up transformer

**Electrical Power**

A dedicated electrical power supply must be present at the site and available to the Encompass 4/4800 Multiprotocol Reader at all times. The power must be 16-20V AC or 16-28V DC. A step-down transformer is available (North America only) to convert a 120V AC duplex wall outlet with ground to 18V AC, as is a step-up transformer to convert a low-voltage 12V AC outlet to 18V AC. Consult your local and national electrical codes for installation and safety requirements.

*Note: Encompass 4/4800 Multiprotocol Readers installed outside North America require a locally supplied transformer.*

If 18V AC or 18V DC power is available, the transformer option is unnecessary.

TransCore offers a Class C transformer accessory kit (part number 76-1620-005) for sites where 110V AC is available. It is the installer’s responsibility to supply conversion equipment and wiring for other voltages. Table 2-2 contains power supply current requirements.

**Table 2-2 Power Supply Current Requirements**

Supply	(RF On) Worst Case Maximum Current at 68°F (20°C)	(RF Off) Standby Operating Current at 68°F (20°C)
16 to 20V AC	1.7 A at 18V AC	1 A at 18V AC
16 to 28V DC	1.7 A at 18V DC	1 A at 18V DC

Power circuits are protected internally against power surges.

**Power Extension**

Use [Table 2-3](#) to determine the correct cable size according to the American Wire Gauge (AWG) standard for the necessary length of extension cable. The numbers in the first row of the table indicate cable size for the approximate cable length.

*Note: If the cable is close to the maximum length, measure voltage at the Encompass 4/4800 Multiprotocol Reader with RF ON to ensure voltage does not drop below 16V. A drop in voltage below 16V causes a reduction in read range and possible damage to internal electronics as well as unreliable operation.*

**Table 2-3 Recommended Cable Length from Transformer to the Encompass 4/4800 Multiprotocol Reader**

<b>Cable Size (AWG)<sup>a</sup></b>	<b>24</b>	<b>22</b>	<b>20</b>	<b>18</b>	<b>16</b>	<b>14</b>	<b>12</b>
Maximum DCR (Ohms per foot at 68°F) <sup>b</sup>	0.0270	0.0175	0.0109	0.0069	0.0044	0.0027	0.0017
Maximum length (feet)	29.63	45.71	73.39	115.61	183.91	293.04	467.84
Maximum length (feet) <sup>c</sup>	25	39	62	98	156	249	398
When used to extend TransCore 5-ft cable (feet)	23	36	57	90	143	227	363
When used to extend TransCore 20-ft cable (feet)	14	22	35	55	88	140	224

- a. Use two conductors each for 18V and 18V return (4 conductors total on the TransCore cable harness).
- b. Direct current resistance (DCR) information is from the Belden catalog.
- c. Calculated length is reduced by -15% to adjust for other variables such as connector contact resistance. Length variable factor is 85%; maximum current drawn by the Encompass 4/4800 Multiprotocol Reader is 2.5 amps; maximum allowable voltage drop from the 18V AC transformer secondary is 2V.

## Host Communications

Your site design must include communications between the Encompass 4/4800 Multiprotocol Reader and a host computer. The Encompass 4/4800 Multiprotocol Reader communicates with the host computer through an asynchronous serial line or through a Wiegand interface. This serial line can be an

RS-232 interface or an RS-422 interface. The host computer must be able to accept one of the interfaces shown in Table 2-4.

**Table 2-4 Communications Interfaces and Conductor Requirements**

Interface	Number of Conductors
RS-232	3
RS-232 with RTS and CTS hardware and handshake signals	5
RS-422	4
Wiegand	3

### RS-232 Interface

Use an RS-232 interface if one or more of the following conditions apply to your site:

- The host computer system is 50 ft (15.2 m) or less from the Encompass 4/4800 Multiprotocol Reader .
- The host computer system is more than 50 ft (15.2 m) from the Encompass 4/4800 Multiprotocol Reader and a pair of RF modems or limited distance modem/line drivers over copper wire are used for communications between the Encompass 4/4800 Multiprotocol Reader and the host. The distance from the RF modem to the Encompass 4/4800 Multiprotocol Readers should not exceed 50 ft (15.2 m).
- Other common communications devices that can extend the RS-232 distance, such as fiber optic modems, have been selected.

The standard RS-232 connection maximum distance depends on the baud rate, cable type, and the RS-232 device at the other end.

### RS-422 Interface

Use an RS-422 interface if one or more of the following conditions apply to your site:

- The host computer is more than 50 ft (15.2 m) from the Encompass 4/4800 Multiprotocol Reader .
- The host computer has an external limited-distance modem.

The standard RS-422 connection maximum distance depends on the baud rate, cable type, and the RS-422 device at the other end.

### **Wiegand Interface**

The Encompass 4/4800 Multiprotocol Reader can interface with equipment requiring the Wiegand +5V DC data0-data1-ground interface. The reader uses the Wiegand interface included with the RS-232 or RS-422 option.

*Note: The Encompass 4/4800 Multiprotocol Reader comes from the factory with either RS-232 and Wiegand or RS-422 and Wiegand. If you wish to use Wiegand, you must first connect the Encompass 4/4800 Multiprotocol Reader using the RS-232 or RS-422 interface, set all necessary operating parameters in the reader, then set the Encompass 4/4800 Multiprotocol Reader's configuration to Wiegand, and then connect the Encompass 4/4800 Multiprotocol Reader to the Wiegand interface.*

*Note: You must order tags programmed with Wiegand-formatted data when using a Wiegand-compatible reader.*

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## **Input/Output Circuits**

To connect the Encompass 4/4800 Multiprotocol Reader to external equipment such as a treadle or traffic control light, install wires from these devices at the junction box. The Encompass 4/4800 Multiprotocol Reader input circuit is designed to connect to a dry contact closure. The Encompass 4/4800 Multiprotocol Reader output circuits are single-pole, double-throw relays providing dry contact closures. These contacts are rated at 42.2V AC peak ( $30V_{\text{rms}}$ ) or 60V DC, at 1 A maximum with noninductive load.

Output circuits are not intended for the direct control of electromechanical devices such as motorized gates and barrier arms. For such applications, the Encompass 4/4800 Multiprotocol Reader output circuits should be used to drive a secondary, appropriately rated high-power relay.

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## **Antenna Interface**

The site design must include an interface cable between the Encompass 4/4800 Multiprotocol Reader and the compatible antenna chosen for the site. The antenna interface is RF coaxial cable with male Type N sockets on each end.

Table 2-5 is a summary of coaxial cable performance. Figures indicate maximum lengths of cable in feet.

**Table 2-5 Reader to Antenna Cable Performance**

Cable Type <sup>a</sup>	Overall Diameter (in.)	915MHz	
		Low Loss <sup>b</sup>	Medium Loss <sup>c</sup>
RG-223	0.216	6	18
RG-214	0.425	12	37
FHJ1-50	0.250	16	48
FSJ1-50	0.250	15	45
LDF2-50	0.375	28	85
FSJ4-50B	0.500	27	83
LDF4-50A	0.500	42	128
LDF5-50A	0.875	76	229
LDF6-50	1.125	103	310
LDF7-50A	1.625	122	366

- a. Suffixes 50, 50A, and 50B indicate 50-ohm cables available from the Andrew Corporation.
- b. These cable lengths ensure optimal system performance (1 dB loss).
- c. These cable lengths ensure adequate, but not optimal, system performance (3 dB loss).

PRELIMINARY

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## Choosing, Installing, and Removing Tags

PRELIMINARY



# Choosing, Installing, and Removing Tags

*This chapter describes the various tag types compatible with the Encompass™ 4/4800 Multiprotocol Reader and the procedures for installing and removing compatible internal and external tags.*

## Compatible Tag Types

The Encompass 4/4800 Multiprotocol Reader provides the capability to read the various TransCore eGo tags and other American National Standards Institute (ANSI) ANS INCITS 256-2001-compliant tags with Intellitag technology. Depending on options ordered, the Encompass 4/4800 Multiprotocol Reader can read eGo tags as well as TransCore IT2000 (in optional ATA/ISO mode), ATA-protocol, ISO-compliant tags, and eGo Plus tags when they are programmed to operate in ATA mode. It can also read tags formatted to a wide range of industry-standard proprietary formats, including SIA Wiegand 26-bit standard format.

The Encompass 4/4800 Multiprotocol Reader reads only the various TransCore eGo tags.

See [Appendix E](#) for information about the numerous ATA-protocol tag models.

### Reader and Tag Model Interoperability

Table 3-1 lists the tags that are read by the Encompass 4/4800 Multiprotocol Reader. See <http://www.transcore.com/pdf/Tag-Reader-Matrix.pdf> for most current information concerning readers and supported tag protocols.

**Table 3-1 Tags Read by the Encompass 4/4800 Multiprotocol Reader**

Reader	Beam Tags	Battery Tags
Encompass 4/4800 Multiprotocol Reader	AT5100; AT5102; AT5110; AT5112; AT5125; AT5145; AT5146; AT5715  eGo Windshield Sticker Tag; eGo Tamper Resistant Tag; eGo License Plate Tag  eGo Plus Sticker* Tag; eGo Plus License Plate Tag*  other ANS INCITS 256-2001- compliant tags with Intellitag technology	AT5105; AT5114; AT5140; AT5147; AT5510; AT5540; AT5541; AT5542; AT5543; AT5544; AT5545; AT5547; AT5704; AT5707; IT2221**; IT2235**

\* in ATA and eGo modes

\*\* When used in optional ATA/ISO mode

## TransCore's eGo Tags

TransCore's various eGo tags are offered to complete your Encompass 4/4800 Multiprotocol Reader System.

Table 3-2 lists some of the features of the TransCore eGo tags.

Table 3-2 eGo Tag Features

Tag	Part Number	Used For	Special Features	Power Source	Number of 6-bit ASCII Characters	Number of 128-Bit Frames	Number of Wiegand Bits
Windshield Sticker Tag	13-0510-004	Toll, Electronic vehicle registration (EVR), mCommerce, Parking, Security access	Very thin, flexible, multi-layer lamination	Beam	20	1	NA
					10	1/2	26 to 54
License Plate Tag	13-0510-900		Water-resistant, exterior-mounted		20	1	NA
					10	1/2	26 to 54

## eGo Windshield Sticker Tag

The TransCore eGo Windshield Sticker Tag (Figure 3-1) is offered to complete your Encompass 4/4800 Multiprotocol Reader System. It is a flexible sticker much like a vehicle registration sticker.



Figure 3-1 eGo Windshield Sticker Tag

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### **eGo Plus Sticker Tag**

The Encompass 4/4800 Multiprotocol Reader can also read the eGo Plus Sticker Tag configured to support ATA or eGo modes.



**Figure 3-2 eGo Plus Windshield Sticker Tag**

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### **eGo License Plate Tag**

The eGo License Plate Tag (Figure 3-3) is a water-resistant tag used in applications requiring an exterior-mounted eGo tag.



**Figure 3-3 eGo License Plate Tag**

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## **Intellitag Data Format**

The memory of Intellitag-based tags consists of 128 bytes of non-volatile read/write memory. Portions of tag data, such as the tag serial number, manufacturing location code, and tag hardware type, are programmed at the factory and locked. The tag memory layout may be programmed by the end user and may be kept unlocked if desired.

Of the 128 bytes of memory, 12 bytes are programmed and locked at the factory and 116 bytes of user memory are available to be formatted and locked as required by the application. Six bytes of the available 116 bytes of user memory are used for defining tag memory layout.

Tags can be programmed in Wiegand formats with 26 to 54 bits. Users who choose this tag data format must complete a Wiegand format worksheet — attached to the Encompass 4/4800 Multiprotocol Reader order entry form — indicating the data to be programmed into the tags.

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## **Installing eGo Windshield Sticker Tags**

eGo Windshield Sticker Tags are designed to be attached by a semi-permanent adhesive to the interior surface of nonmetallic windshields 0.190 to 0.230 inches (4.82 to 5.84 mm) in thickness. For optimum performance, you must install the tag at least 2 inches (5 cm) from the metal in the windshield frame and 0.75 inch (1.9 cm) from the rearview mirror support post. Detailed instructions are found in the pocket guide "Quick and Easy Installation Instructions for Windshield Sticker Tag."

Some vehicles have a tinted area across the top of the windshield. If the tint is conductive, it can interfere with reading the tag. If a windshield has this conductive tint, the tag must be installed at least 2 inches (5 cm) below this tinted area.

Some vehicle windshields contain a metallic treatment that could prevent an interior windshield-mounted tag from being read. However, many of these metallized windshields have areas that are not metallized. On a vehicle without open areas in its metallized windshield, you might need to install an Encompass 4/4800 Multiprotocol Reader-compatible license plate tag on the vehicle. See the section "[Installing eGo License Plate Tags](#)" on page 3-9 and the section "[Installing ATA License Plate Tags](#)" on page 3-15. Contact TransCore for more information. See the section "[Technical Support](#)" on page 9-7.

eGo Plus Sticker Tags are positioned and installed similarly to eGo Windshield Sticker Tags. Detailed instructions are found in the pocket guide "Quick and Easy Installation Instructions for the eGo® Plus Sticker Tag."

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## **Required Materials**

You need the following supplies to install windshield sticker tags:

- Glass cleaner, mild detergent and water, or any cleaning solution appropriate for your windshield
- Clean, dry cloth

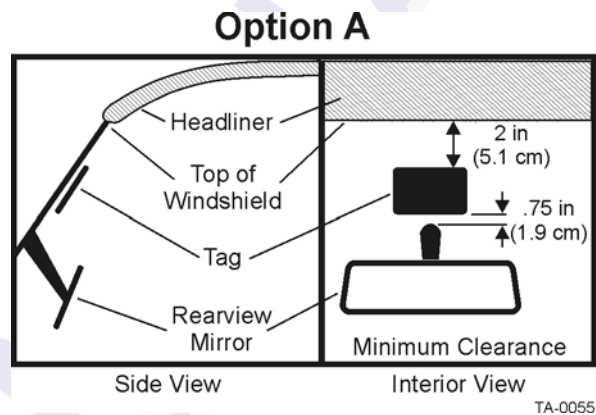
- eGo Windshield Sticker Tag

### **Positioning eGo Windshield Sticker Tags**

TransCore designed the eGo Windshield Sticker Tag to be installed on the upper center or upper corner portion of the windshield. Figures [Figure 3-4](#), [Figure 3-5](#), and [Figure 3-6](#) illustrate possible upper center tag placement locations. **If the upper portion of the windshield is tinted with an aftermarket conductive tint, use placement Option B as shown in [Figure 3-5](#).**

#### **Mirror Post Attached Low On Windshield**

Choose placement Option A shown in [Figure 3-4](#) if the mirror post is attached low on the windshield.



**Figure 3-4 eGo Windshield Sticker Tag Placement Option A**

#### **Mirror Post Attached High on Windshield**

Choose placement Option B if the mirror post is attached high on the windshield as shown in [Figure 3-5](#) or if the upper portion of the windshield is tinted with a conductive tint.

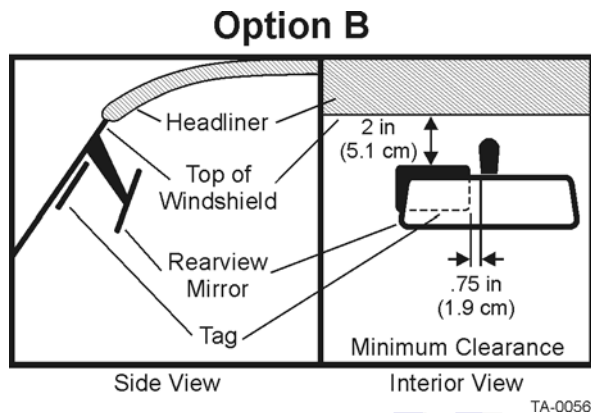


Figure 3-5 eGo Windshield Sticker Tag Placement Option B

### Mirror Post Attached to Headliner

Choose placement Option C if the mirror post is attached to the headliner as shown in Figure 3-6. If the upper portion of the windshield is tinted with an aftermarket conductive tint, place the tag two inches (5 cm) below the tinted area.

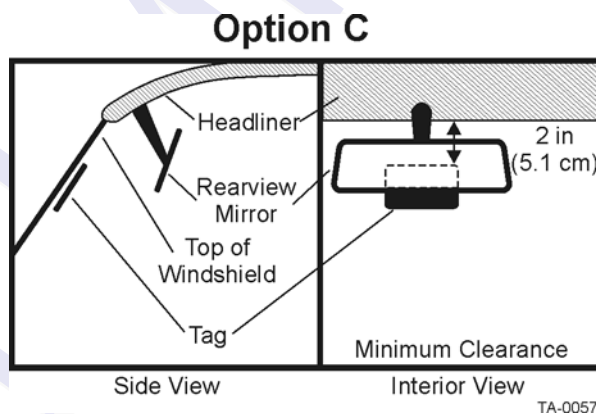


Figure 3-6 eGo Windshield Sticker Tag Placement Option C

## eGo Windshield Sticker Tag Installation Procedures



### Caution

Confirm that the outside temperature is above 50°F (10°C). The sticker tag may not adhere correctly if the temperature is below this temperature.



### To install the eGo Windshield Sticker Tag

1. Determine the tag installation location for the vehicle using the placement guidelines in the section “Positioning eGo Windshield Sticker Tags” on page 3-7.
2. Thoroughly clean the interior surface of the windshield behind and around the rearview mirror where the tag will be located.
3. Dry the tag location area thoroughly using a clean, dry cloth.
4. Remove the paper backing from the tag to expose the adhesive.



#### Caution

*Ensure that the tag is correctly located before touching it to the glass. Once the sticker tag is applied to the glass, it cannot be moved without damage to the tag.*

5. Holding the sticker tag by its edges, position the tag in the correct area of the windshield (determined in Step 1), making sure the tag is oriented horizontally and is at least two inches (5 cm) from the windshield frame and 0.75 inch (1.9 cm) from the mirror post.
6. Press the sticker tag firmly against the glass and gently rub over the entire tag surface. Ensure that no air bubbles remain between the sticker tag and the windshield.

## Removing eGo Windshield Sticker Tags

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Removing eGo Windshield Sticker Tags requires the use of a razor blade or equivalent tool. The tag is inoperable once removed.

## Installing eGo License Plate Tags

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Metallized coatings on some vehicle windshields and windows absorb the RF energy emitted by the Encompass 4/4800 Multiprotocol Reader, thus causing tags to be mis-read. You must use exterior license plate tags on vehicles with metallized coatings on their windshields and windows.

Use license plate installation techniques to install tags on the exterior of vehicles that have this type of window coating.

*Note: The read zone of an overhead Encompass 4/4800 Multiprotocol Reader should be adjusted accordingly when an exterior tag is installed on a license plate, or the read zone will be reduced.*

### Required Materials

- Screwdriver (flat-blade or Phillips depending on the vehicle’s license plate mounting screws)

- Optional TransCore Exterior Tag Accessory Kit (19077-01). This kit contains tamper-resistant mounting screws and wrench.
- eGo License Plate Tag

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### **Positioning eGo License Plate Tags**

The eGo License Plate Tag (LPT) is installed over the license plate at the upper part of the vehicle's front license plate area.

***Note:** If your state does not require a front license plate, install the LPT in the area where the license plate would normally be mounted. If your vehicle does not have a front license plate area, contact your tag agency for other tag options.*

The orientation of the tag is important. The tag must be mounted so that the holes on the tag base plate are on the top edge.

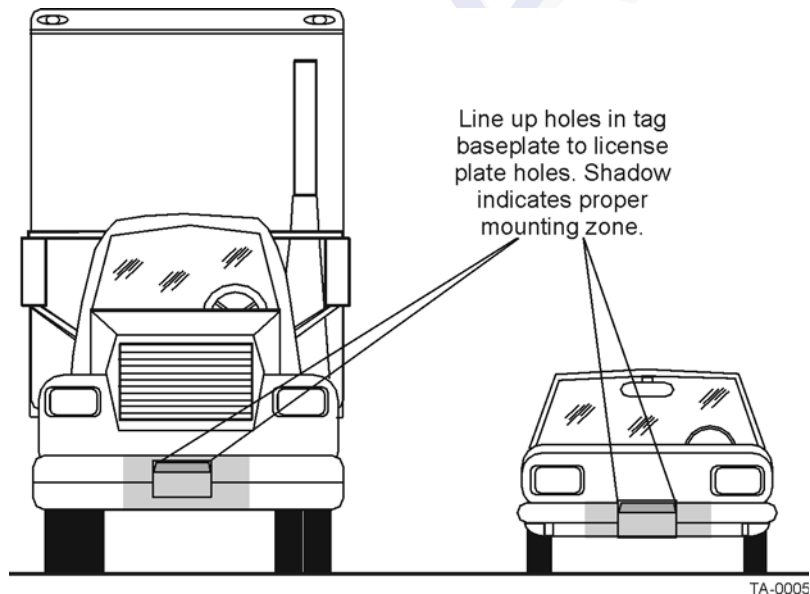
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## eGo License Plate Tag Installation Procedures

### To mount the eGo LPT

1. Remove the screws from the license plate area of your front bumper (Figure 1). If your vehicle does not have mounting screws you will need two self-tapping threaded screws. You can also contact the tag agency to inquire about the optional TransCore Exterior Tag Accessory Kit.

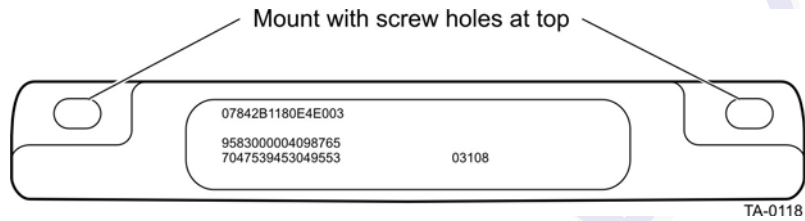
**Note:** You may need to use longer screws to fasten the LPT over the top area of your license plate.



**Figure 3-7 Correct Mounting Location for LPT**

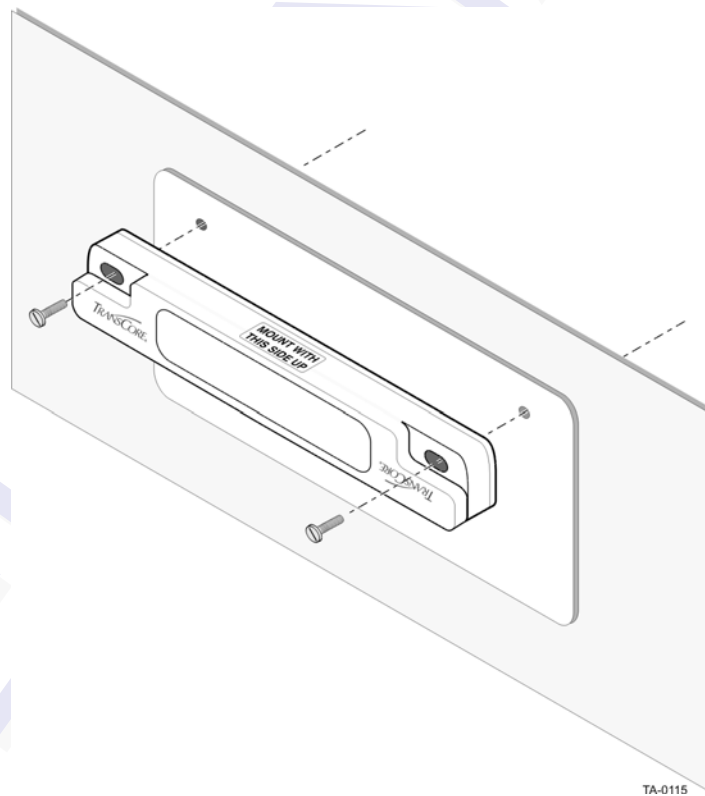
2. Position the LPT so that it is within 18 inches (46 cm) of the center of the front bumper as shown by the shaded area in [Figure 3-7](#). If your vehicle's license plate mounting area is more than 18 inches (46 cm) from the center, you may need to select an alternate location to mount the tag. Contact your tag agency if your vehicle requires an alternate mounting location for the LPT.

3. Hold the LPT so that the etched lettering is facing you with the mounting holes to the top as shown in [Figure 3-8](#).



**Figure 3-8 Correct Tag Orientation**

4. Fasten the LPT to the bumper using the license plate mounting screws ([Figure 3-9](#)). Install the LPT over the top area of the vehicle's license plate if your vehicle has a front license plate. If your state does not require a front license plate, install the LPT in the area where a license plate would normally be mounted.



**Figure 3-9 Upper Placement Over the Top Area of the License Plate**

## Installing Interior ATA Tags

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Interior ATA-protocol tags are installed using hook-and-loop material or double-sided tape attached to the tag and to the windshield. When using hook-and-loop material, the loop material should be applied to the back of the tag and the hook material should be applied to the windshield. After the tag is installed, it can be removed easily and used in any vehicle that has corresponding hook material affixed to the windshield.

*Note: Installing interior tags using double-sided tape results in a semipermanent attachment; the tag will be more difficult to remove than one installed using hook and loop material.*

Interior ATA-protocol tags may be ordered from the factory with hook-and-loop material or double-sided tape already applied to the tag. The adhesive on this material is specially formulated for temperature extremes inside vehicles.

---

### Required Materials

You will need the following materials to install interior tags:

- Rubbing alcohol or 50/50 isopropyl alcohol and water
- Sponge and dry cloth
- Interior tags with two strips of factory-installed hook-and-loop material or factory-installed double-sided tape attached

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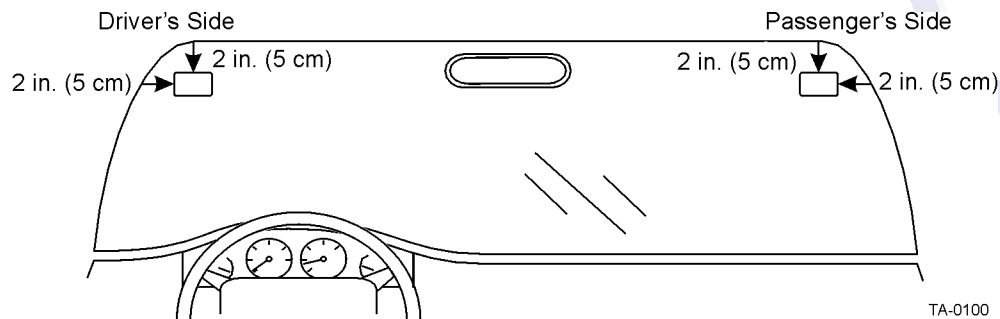
### Positioning ATA Tags

Interior ATA-protocol tags can be installed on the driver's side, passenger's side, or upper center of the vehicle's windshield, depending on the Encompass 4/4800 Multiprotocol Reader's position. See ["Reader and Tag Alignment"](#) on page 2-4.

Tags should be mounted consistently in all vehicles using a particular Encompass 4/4800 Multiprotocol Reader facility.

#### **Interior Driver's or Passenger's Side**

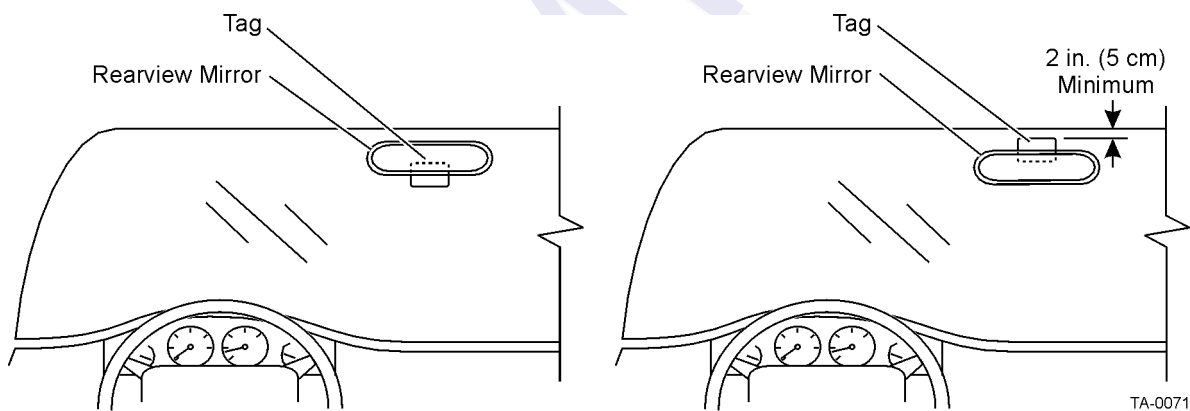
TransCore designed interior ATA-protocol tags for installation inside the vehicle, typically on the driver's side of the windshield. Install the tag in the upper corner, at least two inches (5 cm) from the metal window post, as shown in [Figure 3-10](#).



**Figure 3-10 Driver's or Passenger's Side (U.S.) Interior Windshield Tag Location**

### **Interior Center Windshield**

You may also install ATA tags on the upper center portion of the windshield. Position the tag as closely as possible to the windshield's upper center, behind the rearview mirror. The top edge of the tag should be approximately one inch (2.5 cm) below the base of the mirror, or above the base if enough room is available for the tag to be two inches (five cm) from metal around the windshield, as shown in [Figure 3-11](#).

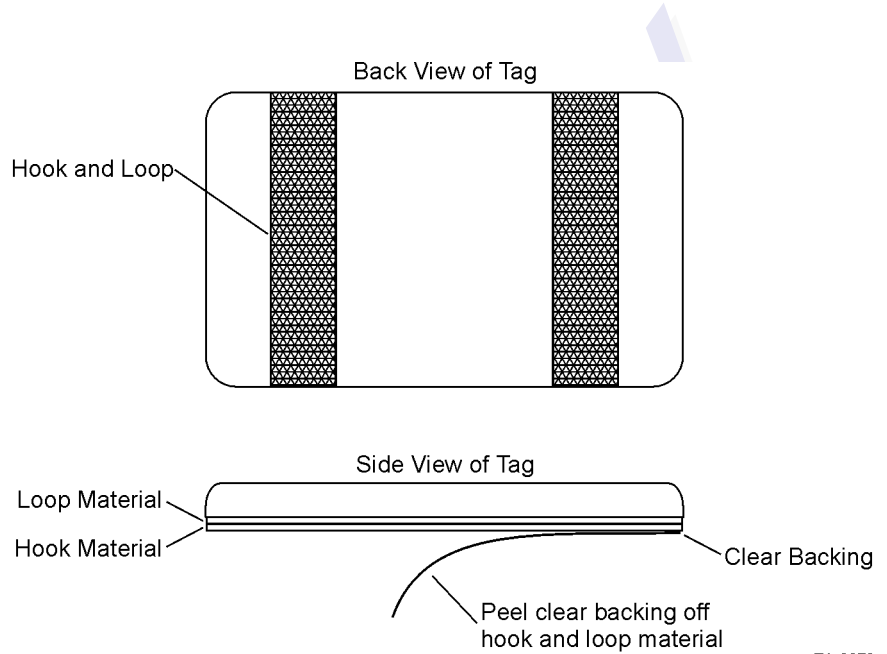


**Figure 3-11 Upper Center Interior Windshield Tag Location**

## **ATA Interior Tag Installation Procedures**

**Perform the following steps to install interior tags:**

1. Clean the tag installation area on the interior surface of the windshield with rubbing alcohol.
2. Dry the area thoroughly using a clean, dry cloth.
3. Remove the clear backing from the two strips of hook-and-loop material on the back of the tag ([Figure 3-12](#)) or from the double-sided tape.



TA-0072

**Figure 3-12 Hook-and-Loop Material on Interior Tag**

4. Position the tag over the correct area of the windshield, making sure that the tag and reader orientation are the same (horizontal or vertical).
5. Press the tag firmly against the glass.

## Removing Interior ATA Tags

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To remove an interior ATA-protocol tag installed using hook-and-loop material, simply pull the tag away from the windshield.

To remove an interior ATA-protocol tag installed using double-sided tape, slowly pry off the tag with a thin tool, such as a putty knife.

## Installing ATA License Plate Tags

---

Metallized coatings on some vehicle windshields and windows absorb the RF energy emitted by the Encompass 4/4800 Multiprotocol Reader, thus causing tags to be mis-read. Use exterior license plate tags on vehicles with metallized coatings on windshields and windows.

Use license plate installation techniques to install tags on the exterior of vehicles that have this type of window coating.

**Note:** The read zone of an overhead Encompass 4/4800 Multiprotocol Reader should be adjusted accordingly when an exterior tag is installed on a license plate, or the read zone will be reduced.

Exterior tags may be installed on metal or plastic bumpers using the existing license plate bracket and hardware.

The tag can be mounted on the front bumper where the license plate is normally located or mounted directly to the front license plate or license plate bracket. Once installed, the face of the tag should be pointing directly forward or slightly upward. If the bumper, license plate, or license plate bracket has any material that overhangs the tag, the tag will not function properly.

---

## Required Materials

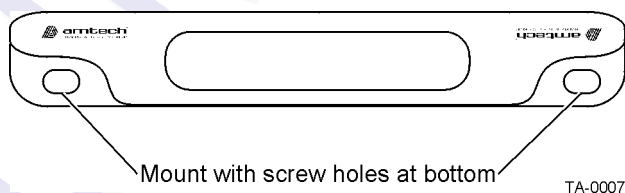
You need the following supplies to install license-plate mounted tags:

- Exterior license plate-mount tag
- Two 0.25-inch (.63 cm) bolts and nuts (user-supplied). Length of the bolts can vary depending on vehicle model.
- Screwdriver and wrench (user-supplied)
- 0.25-inch (.63 cm) spacers or washers (if needed). Thickness of spacers can vary depending on vehicle model.

---

## Positioning ATA License Plate Tags

The orientation of the tag is important. The tag must be mounted so that the holes on the tag base plate are on the bottom edge. See [Figure 3-13](#).



**Figure 3-13 Proper Tag Orientation**

When positioning the tag, observe the following guidelines:

- The tag should be horizontal and parallel to the ground.
- The tag face should be perpendicular or tilted *slightly* upward.
  - The tag may lean to the rear a maximum of 30 degrees.
  - The tag may lean to the front a maximum of 10 degrees.



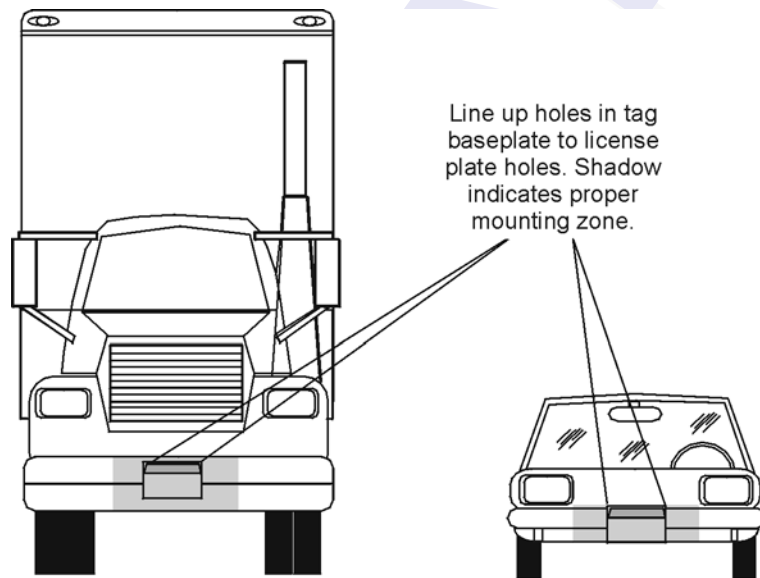
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## ATA License Plate Tag Installation Procedures

### To mount the license plate tag

1. Position the tag so that the holes in the tag are on the bottom edge and the tag is within 18 inches (.45 m) of the center of the front bumper as illustrated by the shaded area in [Figure 3-14](#).

*Note:* When mounting an exterior tag on heavy trucks or tractors, the tag must be mounted within 1.5 inches (3.81 cm) of the top of the bumper.



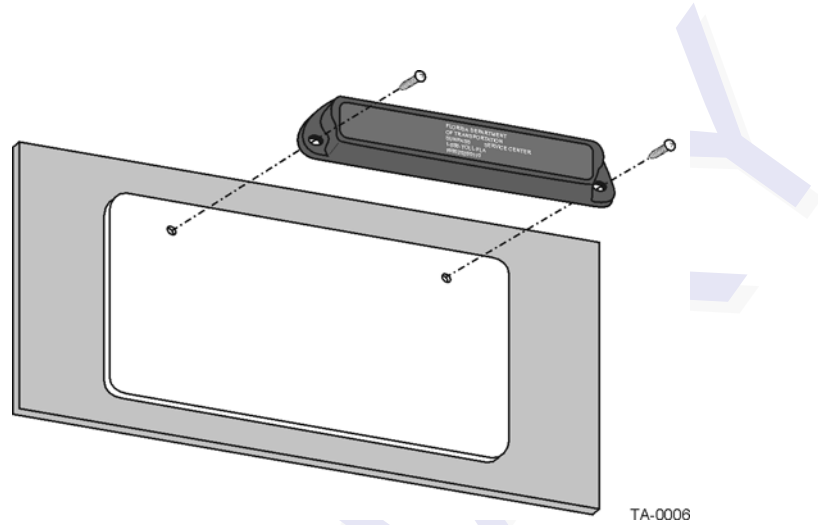
TA-0005

**Figure 3-14 Correct Exterior Tag Placement**

2. Line up the holes in the tag as follows:
  - If mounting the tag to a license plate or license plate bracket, line up the holes in the tag to the *upper* holes of the license plate or license plate bracket.

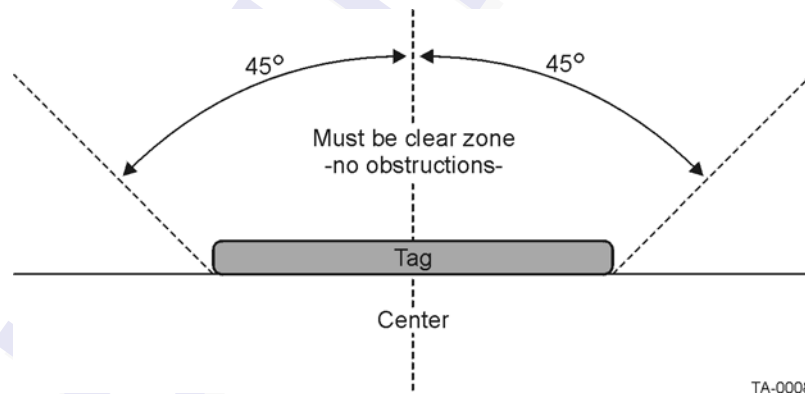
*Note: Do not mount the tag to the bottom holes of the license plate or license plate bracket. The reflective material on the license plate may interfere with the proper functioning of the tag.*

  - If mounting the tag to the bumper, line up the holes in the tag with the holes in the front bumper where the license plate would normally be located. See [Figure 3-14](#).
3. Insert bolts through the tag base plate holes and the holes in the bumper or the holes in the *upper* portion of the license plate area. See [Figure 3-15](#).



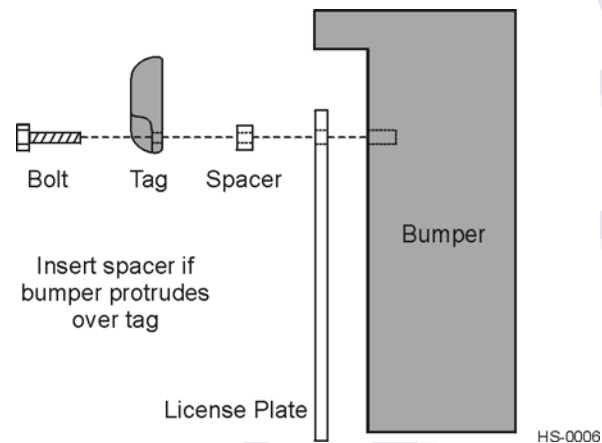
**Figure 3-15 Upper Placement In License Plate Area**

4. Make sure the area within 45 degrees of the center of the tag is free of obstructions. See [Figure 3-16](#).



**Figure 3-16 Obstruction-Free Area**

5. Make sure that no material overhangs the tag. If overhang is more than ½ inch (1.27 cm), insert spacers or washers directly behind the tag so that the tag is clear of any overhanging obstruction. Secure the bolts with a nut. See [Figure 3-17](#).



**Figure 3-17 Spacer Positioned Behind Tag**

6. Tighten the bolts and nuts with a screwdriver and wrench to secure the tag to the vehicle.

---

## **Types of Bumpers**

When mounting tags directly to a bumper, consider the following factors:

- Tags can be mounted on any metal or non-metallic surface; composition of bumper does not matter.
- Tags can be mounted to plastic bumpers using self-threading screws.
- Metal bumpers should be pre-drilled; self-threading screws may be used.

---

## **Alternate Mounting Locations**

If the exterior type tag cannot be mounted on the license plate bracket or directly on the bumper, it may be mounted on a relatively vertical front surface of the vehicle. The exterior tag should be mounted as close to the bumper as possible, following all guidelines regarding orientation, obstruction, and overhang given for bumper mounting. For applications where the integrity of the mounting surface cannot be compromised, the exterior tag can be mounted on a smooth flat surface using double-sided tape.

---

## **Required Materials**

Exterior tags need to be installed on a relatively flat surface. You need the following materials to install exterior tags:

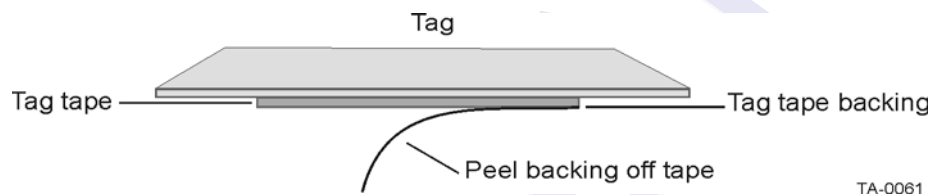
- Rubbing alcohol, 50/50 isopropyl alcohol and water, or solvent/cleaner for metal
- Sponge and dry cloth
- Exterior tag with the double-sided adhesive tape attached

---

## Installation Procedures Using Tape

### To install the tag on a metal or plastic bumper

1. Clean and degrease the tag installation area of the vehicle bumper with solvent/cleaner.
2. Dry the area thoroughly using a clean, dry cloth.
3. Remove the backing from the double-sided tape on the back of the tag, as shown in [Figure 3-18](#).



**Figure 3-18 Exterior Tag with Double-Sided Tape**

4. Position the tag over the installation area, making sure that the tag and Encompass 4/4800 Multiprotocol Reader orientation are the same (horizontal or vertical).
5. Press the tag firmly against the bumper.

---

## Installation Procedures Using Blind Rivets

### To install an exterior tag using blind rivets through the tag's installation tabs

1. Position the tag on the bumper in the installation area and mark the hole positions of the tag's installation tabs on the bumper.
2. Follow the rivet manufacturer's instructions to drill holes in the bumper for rivets.
3. If the rivet head is smaller than the tag installation holes and can be pulled through the holes, use a small washer to secure the rivet through the tag.

---

## Removing Exterior Tags

To remove an exterior tag installed with rivets, follow the rivet manufacturer's instructions to remove the rivets.

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# Installing the Encompass 4/4800 Multiprotocol Reader

PRELIMINARY



# Installing the Encompass 4/4800 Multiprotocol Reader

*This chapter lists the materials needed and presents the procedures to pre-test and install the Encompass™ 4/4800 Multiprotocol Reader.*

## **Installation Process**

---

After you have developed the site plan and identified the location to install the Encompass 4/4800 Multiprotocol Reader and antenna<sup>1</sup>, if required, you are ready to install the equipment. Installation involves the following tasks:

- Pre-installation testing of Encompass 4/4800 Multiprotocol Reader power and tag read capability
- Mounting the Encompass 4/4800 Multiprotocol Reader and antenna, if required, on a pole, ceiling, or wall
- Connecting the antenna
- Connecting the Encompass 4/4800 Multiprotocol Reader power
- Marking the read zone
- Connecting the Encompass 4/4800 Multiprotocol host and sense input/sense output and communications

---

## **Materials Supplied by TransCore**

You need the following materials to pre-test and install the Encompass 4/4800 Multiprotocol Reader. TransCore supplies some of the materials; other materials must be obtained from other sources.

## **Contents of Shipping Carton**

Ensure that you have received all parts before beginning your pre-installation Encompass 4/4800 Multiprotocol Reader tests. Your Encompass 4/4800 Multiprotocol Reader is packaged with the following materials:

- One Encompass 4/4800 Multiprotocol Reader

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1. The Encompass 4/4800 Multiprotocol Reader is designed with an internal patch antenna or with a RF cable connector for use with an external antenna. Unless noted in the text, "antenna" refers to an "external antenna."

- One mounting bracket and the mounting hardware
- Any accessories ordered as options as shown in [Table 4-1](#)

Required accessories are a power/communications cable harness and a 110V AC wall transformer or a 12V AC to 18V AC step-up transformer. If you are using an antenna with the Encompass 4, you also require an Encompass 4/4800 Multiprotocol Reader-compatible antenna and an antenna RF interface. These may be ordered as accessories from TransCore or obtained from other sources.

### **Installation Accessory Options**

[Table 4-1](#) lists optional TransCore Encompass 4/4800 Multiprotocol Reader installation accessory items.

**Table 4-1 Installation Accessories**

<b>Part No.</b>	<b>Description</b>
54-1620-001	Wall or ceiling mount kit
58-1620-001	5-ft connector cable harness
58-1620-002	20-ft connector cable harness
20-1620-003	Connector kit only
56-1620-004	13-pair cable (sold by the foot)
76-1620-005	110V AC to 18V AC Class C transformer
76-1620-006	12V AC to 18V AC step-up transformer
16-xxxx-001	<i>Encompass 4/4800 Multiprotocol Reader System Guide</i> (this manual)

*Note:* The Encompass 4/4800 Multiprotocol Reader may be ordered with a multewire cable harness (part number 58-1620-001 or 58-1620-002 in [Table 4-1](#)) as a separate accessory. One end has a waterproof connector for the Encompass 4/4800 Multiprotocol Reader, and the other end has 13 pairs of color-coded wires.

---

### **Additional Materials Needed for Testing**

You need these additional materials to perform the pre-tests on the Encompass 4/4800 Multiprotocol Reader:

- Two test tags, supplied by the TransCore dealer or distributor
- Suitable 18V AC or 18V DC power wiring for the Encompass 4/4800 Multiprotocol Reader
- Audible circuit tester and 9V DC battery for circuit tester power



- Wire stripper
- One Encompass 4/4800 Multiprotocol Reader-compatible antenna (if required)
- Suitable RF interface coaxial cable (if using antenna)

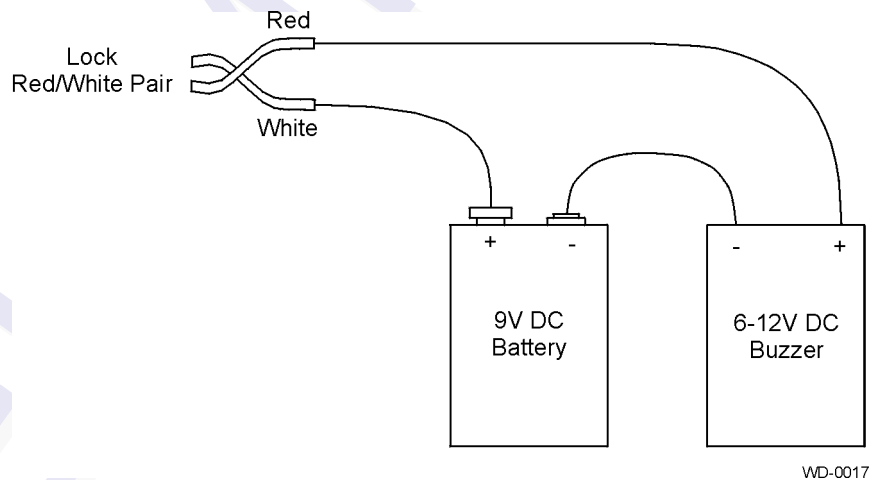
## ***Pre-installation Testing of the Encompass 4/4800 Multiprotocol Reader***

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Before installing the Encompass 4/4800 Multiprotocol Reader permanently at the site, you should use an audible circuit tester to confirm that the Encompass 4/4800 Multiprotocol Reader has power and can read a tag presented in the tag read zone.

### ***Testing the Encompass 4/4800 Multiprotocol Reader Using an Audible Circuit Tester***

An audible circuit tester is also called a buzz box. These boxes are available at some electronic parts supply stores, or you can make a buzz box, as shown in [Figure 4-1](#). The buzz box is powered by a 9V DC battery and is equipped with two alligator-clip leads. When you touch the leads together, the box makes an audible sound.



***Figure 4-1 Wiring for Audible Circuit Tester***

To test the Encompass 4/4800 Multiprotocol Reader that uses an internal antenna, connect the power supply as described in the appropriate section below, and then test as described in the section [“Bench Testing the Encompass 4/4800 Multiprotocol Reader Before Installation”](#) on page 4-12.

To test the Encompass 4/4800 Multiprotocol Reader that uses an external antenna, connect the antenna and connect the power supply as described in the appropriate section below, and then test as described in the section [“Bench Testing the Encompass 4/4800 Multiprotocol Reader Before Installation”](#) on page 4-12.

---

## Connecting the Antenna

Use these instructions to connect the Encompass 4/4800 Multiprotocol Reader and antenna.



### Caution

*To avoid damage to the Encompass 4/4800 Multiprotocol Reader, you must connect the antenna before applying power to the reader.*

Power/communications cable



Antenna connector with RF cable attached

**Figure 4-2 Back of Encompass 4/4800 Multiprotocol Reader Showing Antenna Connector**

### To connect the reader and antenna

1. Ensure the reader is turned off and unplugged.
2. Connect one end of the RF interface cable to the antenna.
3. Connect the other end of the RF interface cable to the antenna connector on the back of the Encompass 4/4800 Multiprotocol Reader. See Figure 4-1.

---

## Connecting the AC Power Supply



### Caution

*If you are using an external antenna, to avoid damage to the Encompass 4/4800 Multiprotocol Reader, you must connect the antenna before applying power to the reader.*

### To connect the Encompass 4/4800 Multiprotocol Reader to a low-voltage AC power supply

1. Connect the Encompass 4/4800 Multiprotocol power wires from the cable to the transformer using the color coding as described in [Table 4-2](#).

**Table 4-2 AC Transformer Connections for Colored-Wire Pair Cable**

Signal from Encompass 4	Colored-Wire Pair Cable		Connect to Transformer Terminal Strip
	Wire Pair from Encompass 4/4800 Multiprotocol Reader Cable	Color Used	
Main power input	Brown/Red and Orange/Red	Orange and Brown	L1 (16 to 20V AC)
Main power return		Red and Red	L2 (16 to 20V AC)

2. Complete the power connections at the power supply.

## Connecting the DC Power Supply

To connect the Encompass 4/4800 Multiprotocol Reader to a low-voltage DC power supply



### Caution

*If you are using an external antenna, to avoid damage to the Encompass 4/4800 Multiprotocol Reader, you must connect the antenna before applying power to the reader.*

1. Connect the Encompass 4/4800 Multiprotocol Reader power wires from the cable to the low-voltage terminals using the connection designations shown in [Table 4-3](#).

**Table 4-3 Low Voltage DC Cable Connections for the Colored-Wire Pair Cable**

Signal from Encompass 4	Colored-Wire Pair Cable		Connection Use
	Wire Pair from Encompass 4/4800 Multiprotocol Reader Cable	Color Used	
Main power input	Brown/Red and Orange/Red	Orange and brown	16 to 28V DC+ terminal
Main power return		Red and red	16 to 28V DC- terminal

---

## **Connecting Communications for Bench Testing**

TransCore offers reader models that communicate through RS–232, RS–422, and Wiegand interface protocols. This section describes the procedures and materials required for connecting the communications to perform pre-installation bench testing of the Encompass 4/4800 Multiprotocol Reader.

### **Required Materials**

You need the following materials to connect the communications cable to the PC:

- PC or laptop
- Any terminal emulation program such as Procomm Plus™ or Hyper Terminal™ running on a PC
- Communications cable to connect to the COM1 port on your PC

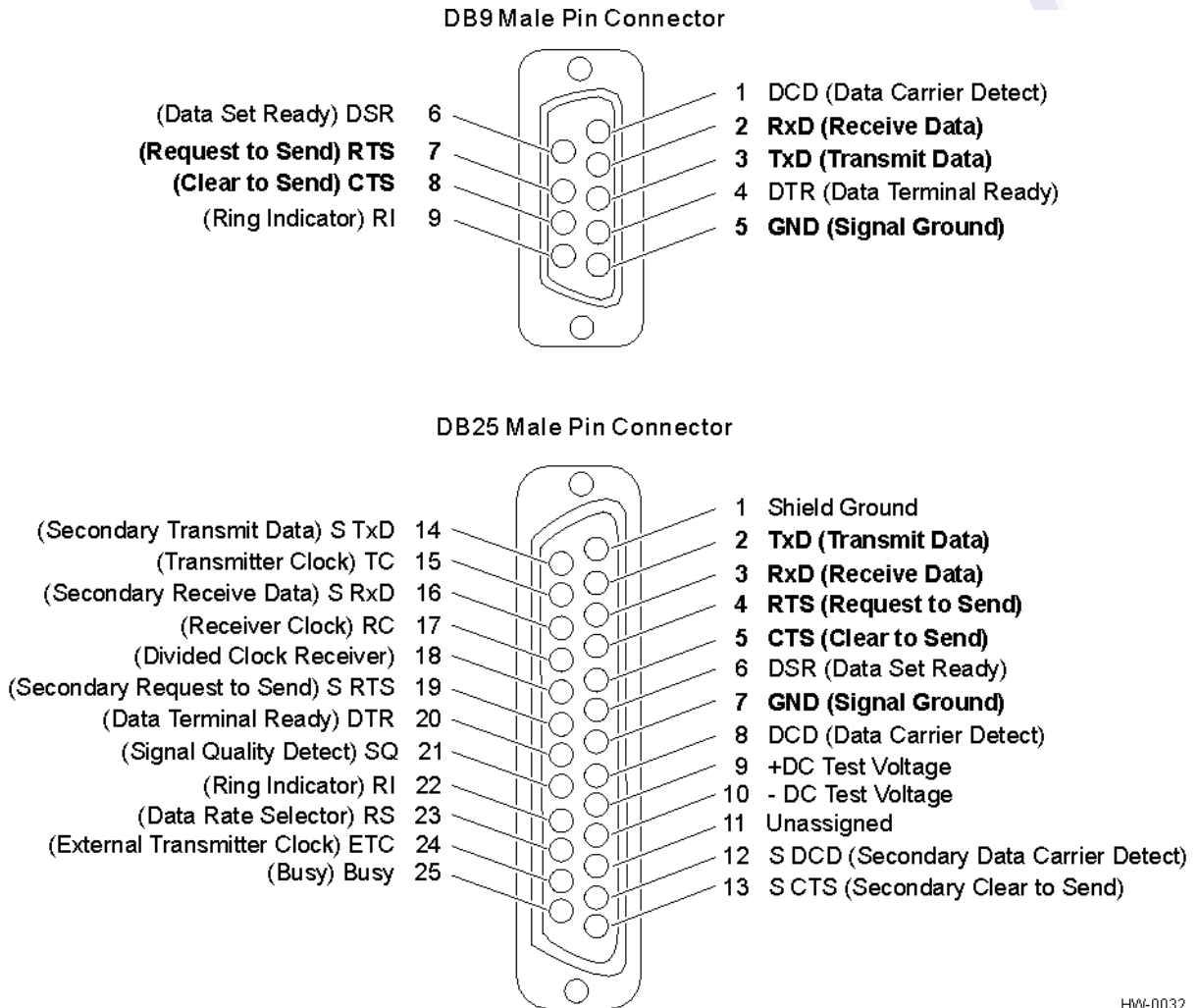
Encompass 4/4800 Multiprotocol Reader communications and customer interface signals are supplied from the Encompass 4/4800 Multiprotocol Reader to the host through a multiwire cable, which is a 13-pair pigtail. The connector for this cable is located on the back of the Encompass 4/4800 Multiprotocol Reader. Refer to the following sections to connect the appropriate communications wires from the cable to the PC.

These sections contain instructions for connecting RS–232 and RS–422 communications between the Encompass 4/4800 Multiprotocol Reader and the PC for bench testing purposes. Each section contains wiring instructions and pin assignments followed by step-by-step connection procedures.

The Encompass 4/4800 Multiprotocol Reader can remain powered up while connecting reader-to-host PC communications.

### **Connecting for Bench Testing with RS–232 Interface**

RS–232 interface signals are supplied by three or five wires from the Encompass 4/4800 Multiprotocol communications cable. The pin assignments for the signal to the host male DB9 and DB25 connectors are shown in boldface in [Figure 4-15](#).



HW-0032

**Figure 4-3 Pin Assignments for Signal to Host Connectors**

*Note: In Figure 4-3 supported pin assignments are in boldface.*

PREVIEW

**Connecting the Encompass 4/4800 Multiprotocol Reader Colored-Wire Pair Cable**

Table 4-7 shows the RS-232 colored wire assignments.

**Table 4-4 RS-232 Interface Signal Wiring for Colored-Wire Pair Cable**

Signal from Encompass 4/4800 Multiprotocol Reader	Colored-Wire Pair Cable		Connect Wire to Host DB9 Pin	Connect Wire to Host DB25 Pin
	Wire Pair from Encompass 4/4800 Multiprotocol Reader	Color Used		
TxD — Encompass 4/4800 Multiprotocol Reader sense output, host sense input	Red/Black	Black	Pin 2	Pin 3
RxD — Encompass 4/4800 Multiprotocol Reader sense input, host sense output		Red	Pin 3	Pin 2
Signal ground	Yellow/Black	Yellow or Black	Pin 5	Pin 7
<b>Optional for hardware handshaking</b>				
RTS — Encompass 4/4800 Multiprotocol Reader sense output, host sense input	Yellow/Red	Yellow	Pin 8	Pin 5
CTS — Encompass 4/4800 Multiprotocol Reader sense input, host sense output		Red	Pin 7	Pin 4

**To connect the colored-wire cable using RS-232 interface**

1. Connect the black wire (transmit data) from the red and black wire pair to pin 2 of the DB9 connector or pin 3 of the DB25 connector.
2. Connect the red wire (receive data) from the red and black wire pair to pin 3 of the DB9 connector or pin 2 of the DB25 connector.

3. Connect either the yellow or black wire (signal ground) from the yellow and black wire pair to pin 5 of the DB9 connector or pin 7 of the DB25 connector.
4. Plug the DB9 connector or DB25 connector into the PC.

If the host is set up for hardware handshaking, use the following procedures:

1. Connect the yellow wire (RTS) from the yellow and red wire pair to pin 8 of the DB9 connector or pin 5 of the DB25 connector.
2. Connect the red wire (CTS) from the yellow and red wire pair to pin 7 of the DB9 connector or pin 4 of the DB25 connector.

### Connecting for Bench Testing with RS-422 Interface

RS-422 interface signals are supplied by four wires from the Encompass 4/4800 Multiprotocol Reader communications cable. Your host must have an RS-422 interface with either an internal or external converter.

*Note:* For temporary bench testing purposes only, you may connect the RS-422 interface signal wires according to Table 4-5. For permanent installations, follow the RS-422 connection instructions on page 4-27.

### Connecting the Encompass 4/4800 Multiprotocol Reader Colored-Wire Pair Cable for Bench Testing with RS-422 Interface.

Table 4-8 shows the RS-422 signals and their interface wire connectivity for bench testing purposes only.

**Table 4-5 RS-422 Interface Signal Wiring for Bench Testing**

Signal from Encompass 4/4800 Multiprotocol Reader	Colored-Wire Pair Cable		Connect Wire to Host DB9 Pin	Connect Wire to Host DB25 Pin
	Wire Pair from Encompass 4/4800 Multiprotocol Reader	Color Used		
Signal ground	Yellow/Red	Yellow	Pin 5	Pin 7
TxD - Encompass 4/4800 Multiprotocol Reader sense output, host sense input		Red	Pin 2	Pin 3
Signal ground	Red/Black	Black	Pin 5	Pin 7
RxD - Encompass 4/4800 Multiprotocol Reader sense input, host sense output		Red	Pin 3	Pin 2

**To connect the colored-wire cable for bench testing a reader with RS-422 interface**

1. Connect the yellow wire (signal ground) from the yellow and red wire pair to the host DB9 Pin 5 or Host DB25 Pin 7.
2. Connect the red wire (transmit) from the yellow and red wire pair to the host DB9 Pin 2 or Host DB25 Pin 3.
3. Connect the black wire (signal ground) from the red and black wire pair to the host DB9 Pin 5 or Host DB25 Pin 7.
4. Connect the red wire (receive) from the red and black wire pair to the host DB9 Pin 3 or Host DB25 Pin 2.

---

**Bench Testing the Encompass 4/4800 Multiprotocol Reader Before Installation**

The Encompass 4/4800 Multiprotocol Reader factory default tag read protocol is IATA tag read mode. Initially the Encompass 4/4800 Multiprotocol Reader reads only Intellitag-based eGo tags and ignores ATA tags. For more information, see “[47N Select Tag Mode\\*\\*](#)” on page 7-15.

*Note: Test tags should be eGo Windshield Sticker Tags affixed to a piece of nonmetallic windshield-type glass 0.190 to 0.230 inches (4.82 to 5.84 mm) in thickness. The eGo Windshield Sticker Tag has a reduced read range when not attached to glass.*

**To test that the Encompass 4/4800 Multiprotocol Reader has power and can read a tag presented in the read zone**

1. Confirm that the Encompass 4/4800 Multiprotocol Reader colored-wire pair cable is correctly connected to a suitable AC or DC low-voltage power supply as discussed on page 4-6 and page 4-7 and that the transformer is connected to a power outlet.

If you are using an external antenna, confirm that the antenna is connected to the Encompass 4/4800 Multiprotocol Reader.



**Caution**

*To avoid damage to the Encompass 4/4800 Multiprotocol Reader, you must connect the antenna before applying power to the reader.*

2. Confirm that the Encompass 4/4800 Multiprotocol Reader colored-wire pair cable communications are connected correctly as described in the section “Connecting Communications for Bench Testing” on page 4-8.
3. Connect the two leads from the audible circuit tester to the white and red wire pair (pair #8, lock/lock return) from the Encompass 4/4800 Multiprotocol Reader power/communications cable.



4. Start the terminal emulation application Microsoft HyperTerminal by selecting **Programs>Accessories>Communications>HyperTerminal** and press **ENTER**.
5. In the HyperTerminal dialog boxes choose the com port to which the communications interface is attached and set the properties as:
  - Bits per second: 9600 baud
  - Data bits: 8
  - Parity: none
  - Stop bits: 1
  - Flow control: none
6. Cycle the power on the Encompass 4/4800 Multiprotocol Reader and ensure that the sign-on message displays.
7. Input the following commands in the order provided in Table 4-6. Commands include those to switch to command mode, set operational mode, turn on RF, and return the reader to data mode.

**Table 4-6 Commands for Bench Testing**

<b>Entry</b>	<b>Reader Response</b>	<b>Notes</b>
#01 <CR>	#Done <CR/LF>	Switches Encompass 4/4800 Multiprotocol Reader to command mode.
#470	#Done <CR/LF>	Sets operational mode to Dual (1) - Read eATA data from Intellitag-based tags and read ATA tags
#6401	#Done <CR/LF>	Turns on RF channel.
#00 <CR>	#Done <CR/LF>	Returns Encompass 4/4800 Multiprotocol Reader to data mode.

8. Pass an eGo Windshield Sticker Tag in front of the Encompass 4/4800 Multiprotocol Reader or antenna. The audible circuit tester should sound a tone when the tag is read. If no tone sounds, ensure that steps 1,through 5 were performed correctly and that you are using a compatible tag. Repeat steps 6 and 7. If no tone sounds, contact TransCore (see [“Technical Support” on page 9-7](#)).
9. Disconnect the circuit tester from the Encompass 4/4800 Multiprotocol Reader power/communications cable.
10. Disconnect the power and communications connections made for pre-installation testing.

**Note:** You will need the audible circuit tester again to determine the read zone when installing the Encompass 4/4800 Multiprotocol Reader at the site.

## **Mounting the Encompass 4/4800 Multiprotocol Reader on Round Pole or Flat Surface**

---

This section lists procedures and materials required for mounting the Encompass 4/4800 Multiprotocol Reader on a round pole or on a ceiling, wall, or other flat surface based on the site's requirements.

In permanent installations using an antenna, the Encompass 4/4800 Multiprotocol Reader should be positioned as close as possible to the antenna. Long cable runs increase system sensitivity to noise. See Table 2-6 on page 2-20 for maximum RF cable lengths.

---

### **Mounting the Encompass 4/4800 Multiprotocol Reader on a Round Pole**

The Encompass 4/4800 Multiprotocol Reader can be simply and inexpensively mounted on a round pole. The pole must be a minimum of 2 inches (5 cm) in diameter and should extend approximately 8 feet (2.4 m) above the pavement level. The pole must be installed according to local building codes.

#### **Required Materials**

You need the following supplies to mount the Encompass 4/4800 Multiprotocol Reader on a round pole:

- A 5/32-inch Allen wrench to assemble and adjust the mounting brackets
- Two 0.5 inch (1.3 cm) wide, stainless steel hose clamp straps that are 12 inches (30.5 cm) long for a typical 2-inch (5-cm) diameter pole or 24 inches (61 cm) long for a 10-inch (25-cm) diameter pole
- Flat-tip screwdriver or adjustable wrench to tighten hose clamp straps

#### **Procedures**

##### **To mount the Encompass 4/4800 Multiprotocol Reader to a pole**

1. Unpack the Encompass 4/4800 Multiprotocol Reader. A factory-mounted bracket (Figures 4-2 and 4-3) is attached to the back of the Encompass 4/4800 Multiprotocol Reader. A pole mount bracket assembly (Figure 4-6) is bubble-wrapped separately and contains a plastic bag of four Allen screws and washers.
2. Using the two 0.5 inch (1.3 cm) stainless steel hose clamps, attach the pole mount bracket assembly to the pole approximately 8 feet (2.4m) above the pavement surface. Tighten slightly so you can adjust the Encompass 4/4800 Multiprotocol Reader left or right, but not so slightly the straps slide down the pole.

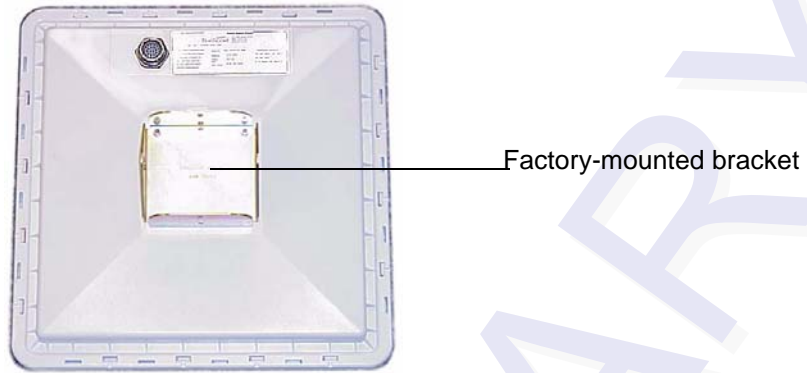
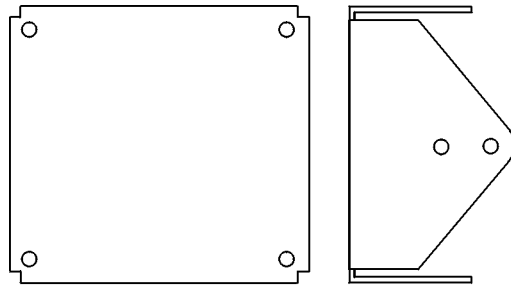
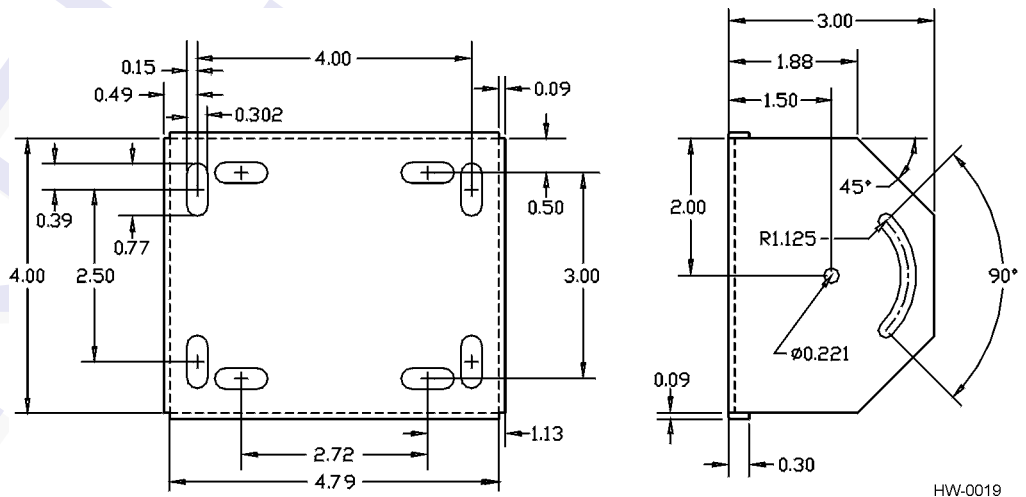


Figure 4-4 Back of the Encompass 4/4800 Multiprotocol Reader



HW-0018

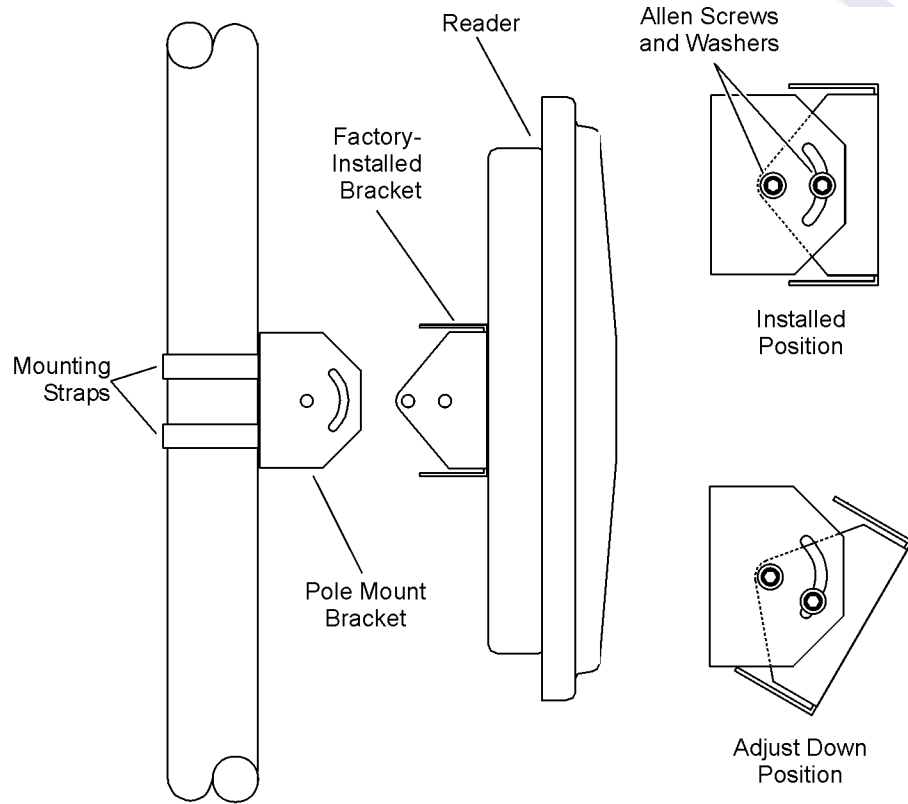
Figure 4-5 Factory-Mounted Bracket



HW-0019

Figure 4-6 Pole-Mount Bracket Assembly

- Using the four Allen screws and washers, attach the Encompass 4/4800 Multiprotocol Reader to the pole mount bracket as shown in Figure 4-7. Tighten the screws slightly so that the Encompass 4/4800 Multiprotocol Reader can be adjusted up or down, but not so slightly the mounting assembly slips.



HS-0050

**Figure 4-7 The Encompass 4/4800 Multiprotocol Reader Attached to the Pole Mount Bracket**

- Adjust the assembly by pointing the Encompass 4/4800 Multiprotocol Reader to the middle of the area where tags will be read, and tighten all screws and straps slightly.

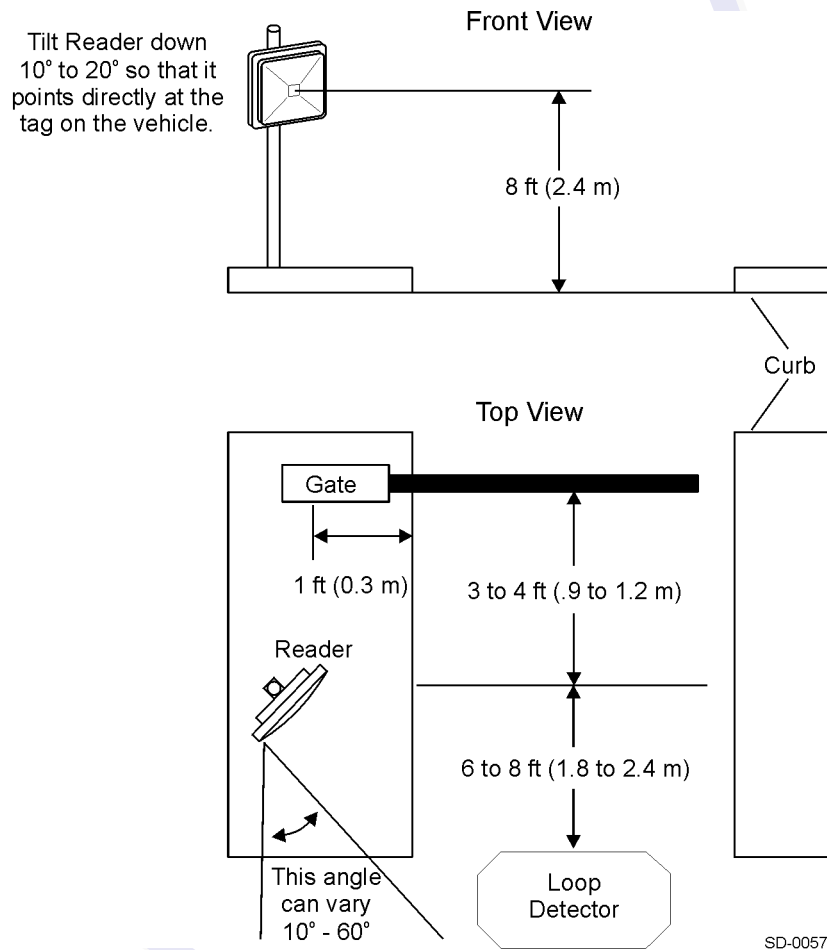
*Note: Adjust the Encompass 4/4800 Multiprotocol Reader to provide the most direct line of sight to the tags.*



Figure 4-8 illustrates front and top views of a pole-mounted Encompass 4/4800 Multiprotocol Reader with the approximate measurements for sites where tags would be mounted on the interior driver-side windshield. eGo Windshield Sticker Tags may be mounted on the interior upper center or upper corner of the windshield.

*Note: Determine the read zone before you tighten all screws and straps permanently. Refer to the section “Marking the Read Zone” on page 4-32.*

## Installing the Encompass 4/4800 Multiprotocol Reader



**Figure 4-8 Front and Top Views of the Encompass 4/4800 Multiprotocol Reader Position**

**Note:** The dimensions in Figure 4-8 are for demonstration purposes only and are approximations for sites using the older ATA-type tags. Actual dimensions vary as lane geometry and tag style varies from site to site. Adjust the Encompass 4/4800 Multiprotocol Reader matching site and tag mounting positions to provide the most direct line of sight to the tags.

### Caution

Connect the reader bracket to earth ground using a ground cable and stake. TransCore recommends that you follow the National Electric Code for lightning protection for the locale where you are installing the Encompass 4/4800 Multiprotocol Reader.

## Mounting the Encompass 4/4800 Multiprotocol Reader to a Wall or Flat Surface

The basic Encompass 4/4800 Multiprotocol Reader is supplied with a pole-mount bracket assembly (Figure 4-6) that allows you to adjust the Encompass 4/4800 Multiprotocol Reader up and down. TransCore recommends using the wall-mount bracket accessory kit (Figure 4-9) in addition to the pole-mount bracket to provide additional horizontal aiming flexibility when attaching the Encompass 4/4800 Multiprotocol Reader to a pole with flat sides or to a wall or ceiling where other structures can interfere with accurately aiming the Encompass 4/4800 Multiprotocol Reader toward the tags.

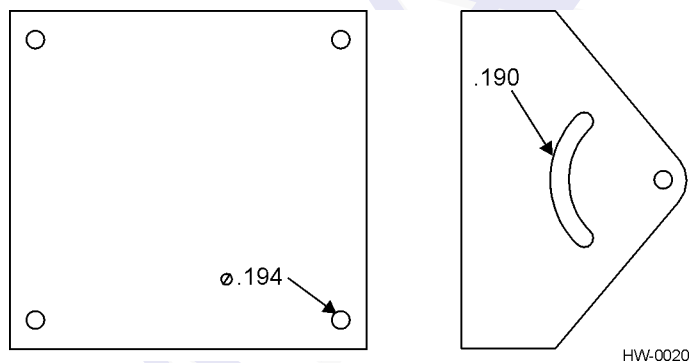


Figure 4-9 Wall Mount Bracket Accessory (part number 54-1620-001)

### Required Materials

You need the following materials to install the Encompass 4/4800 Multiprotocol Reader on a wall or flat surface. Ensure the use of high-quality, corrosion-resistant anchor hardware.

- Anchor hardware suitable for the surface on which you mount the Encompass 4/4800 Multiprotocol Reader  
Because the Encompass 4/4800 Multiprotocol Reader weighs only 9 1/2 lbs (4.3 kg), 0.25 in (0.6 cm) bolt hardware is adequate to secure the unit to a wall or ceiling.
- Four hex nuts 3/8-16 threaded and four lockwashers
- 5/32-inch Allen wrench
- One Encompass 4/4800 Multiprotocol wall mount bracket accessory kit (required)

### Procedures

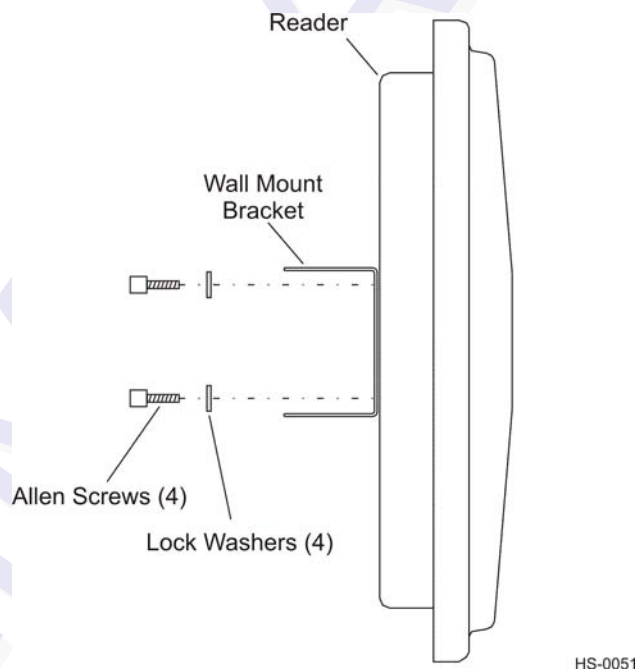
#### To mount the Encompass 4/4800 Multiprotocol Reader to a wall or ceiling

1. Unpack the Encompass 4/4800 Multiprotocol Reader. Set aside the pole mount bracket.

## Installing the Encompass 4/4800 Multiprotocol Reader

Use the bracket in the remaining steps to provide greater adjustment for the Encompass 4/4800 Multiprotocol Reader. The pole-mount bracket is wrapped separately from the Encompass 4/4800 Multiprotocol Reader and contains a plastic bag of four Allen screws and washers.

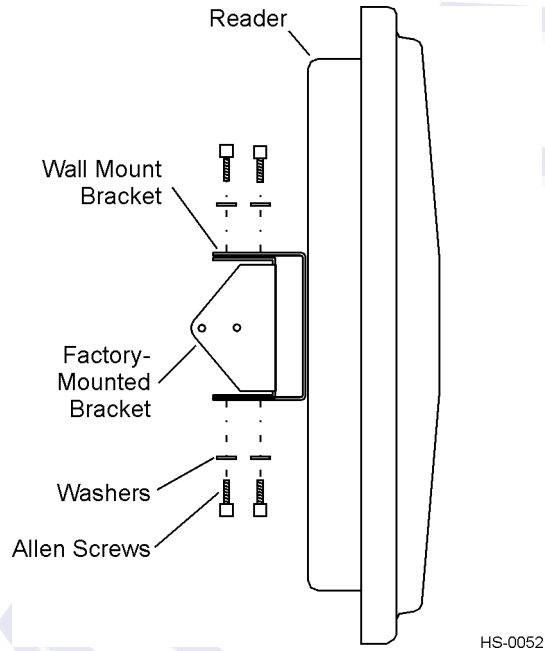
- Using the 5/32-inch Allen wrench, remove the factory-mounted bracket attached to the back of the Encompass 4/4800 Multiprotocol Reader. Remove all four Allen screws and lock washers from the bracket and set aside.
- Unpack the wall-mount bracket accessory kit.
- Using the Allen screws and lock washers set aside in Step 2, attach the wall-mount bracket to the back of the Encompass 4/4800 Multiprotocol Reader, as shown in [Figure 4-10](#).



**Figure 4-10 Wall Mount Bracket Attached to the Encompass 4/4800 Multiprotocol Reader**

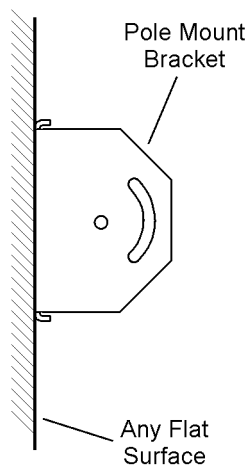
- Tighten the screws to secure the bracket.

- Using the four screws and washers supplied with the wall-mount bracket, attach the factory-mounted bracket to the wall mount bracket, lining up the four outside screw holes as shown in [Figure 4-11](#).



**Figure 4-11 Factory-Mounted Bracket Attached to Wall Mount Bracket**

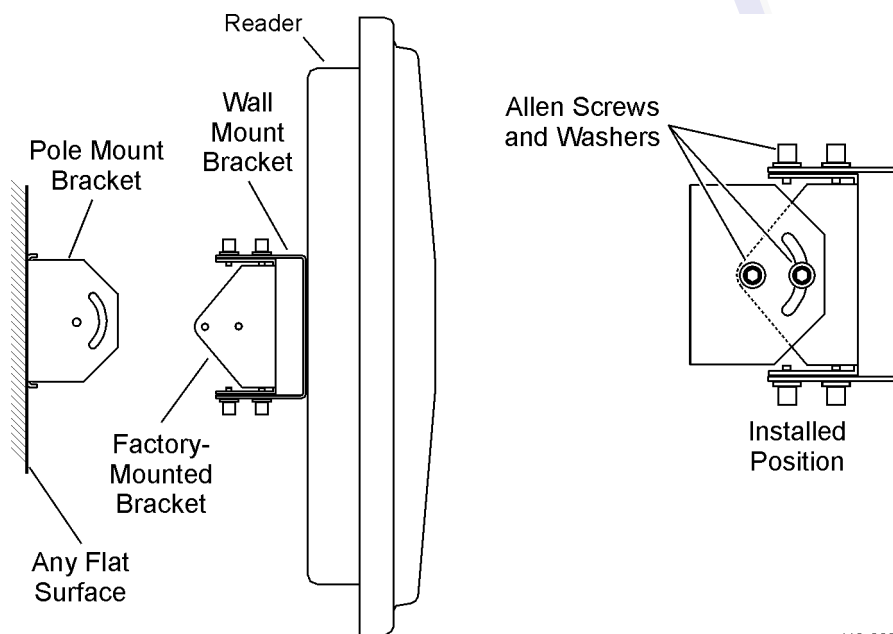
- Tighten lightly, since you will want to adjust the bracket later. This subassembly allows you to aim the Encompass 4/4800 Multiprotocol Reader left or right when all three brackets are assembled.
- Mount the pole-mount bracket to the wall, ceiling, or fixture using appropriate anchors as shown in [Figure 4-12](#).



**Figure 4-12 Pole Mount Bracket Attached to Wall**



9. Mount the Encompass 4/4800 Multiprotocol Reader to the pole-mount bracket using Allen screws, as shown in Figure 4-13.



HS-0053

**Figure 4-13 Connecting the Encompass 4/4800 Multiprotocol Assembly to Pole Mount Bracket**

10. Adjust the assembly by pointing the Encompass 4/4800 Multiprotocol Reader to the middle of the area where tags will be read and tighten all screws and straps slightly.

*Note:* Adjust the Encompass 4/4800 Multiprotocol Reader to provide the most direct line of sight to the tags.



**CAUTION**

**Caution**

*Connect the reader bracket to earth ground using a ground cable and stake. TransCore recommends that you follow the National Electric Code for lightning protection for the locale where you are installing the Encompass 4/4800 Multiprotocol Reader.*

After mounting the Encompass 4/4800 Multiprotocol Reader, you must connect it to a dedicated 16 to 20V AC or 16 to 28V DC power supply.



**CAUTION**

**Caution**

*To avoid damage to the Encompass 4/4800 Multiprotocol Reader, you must connect the antenna before applying power to the reader.*

## Mounting the Antenna

---

If you are using the Encompass4/4800 Multiprotocol Reader that requires an external antenna in permanent installations, the antenna should be positioned as close as possible to the Encompass 4/4800 Multiprotocol Reader. Long cable runs increase system sensitivity to noise. See [Table 2-6 on page 2-20](#) for maximum RF cable lengths.

This section provides guidelines for mounting antennas.

---

### Mounting the Antenna Curb-Side

Some site designs, for example those with curb-side antennas, require that the antenna be mounted on a round pole. The pole must be a minimum of 2 inches (5 cm) in diameter and should extend approximately 8 feet (2.4 m) above the pavement level. The pole must be installed according to local building codes.

#### Procedures

Use the following guidelines to mount an antenna on a curb-side round pole.

##### To mount the antenna to a curb-side pole

1. Follow the manufacturer's directions to attach the antenna assembly to the pole approximately 8 feet (2.4m) above the pavement surface.
2. Tighten slightly so that you can adjust the antenna left or right but not so slightly that the antenna slides down the pole.
3. Adjust the assembly by pointing the antenna to the middle of the area where tags will be read, and while in this position, tighten all screws and fastenings slightly.

*Note:* Adjust the antenna to provide the most direct line of sight to the tags.

Figure 4-14 illustrates front and top views of a pole-mounted antenna with the approximate measurements for sites where tags would be mounted on the interior driver-side windshield. eGo Windshield Sticker Tags may be mounted on the interior upper center or upper driver-side corner of the windshield.

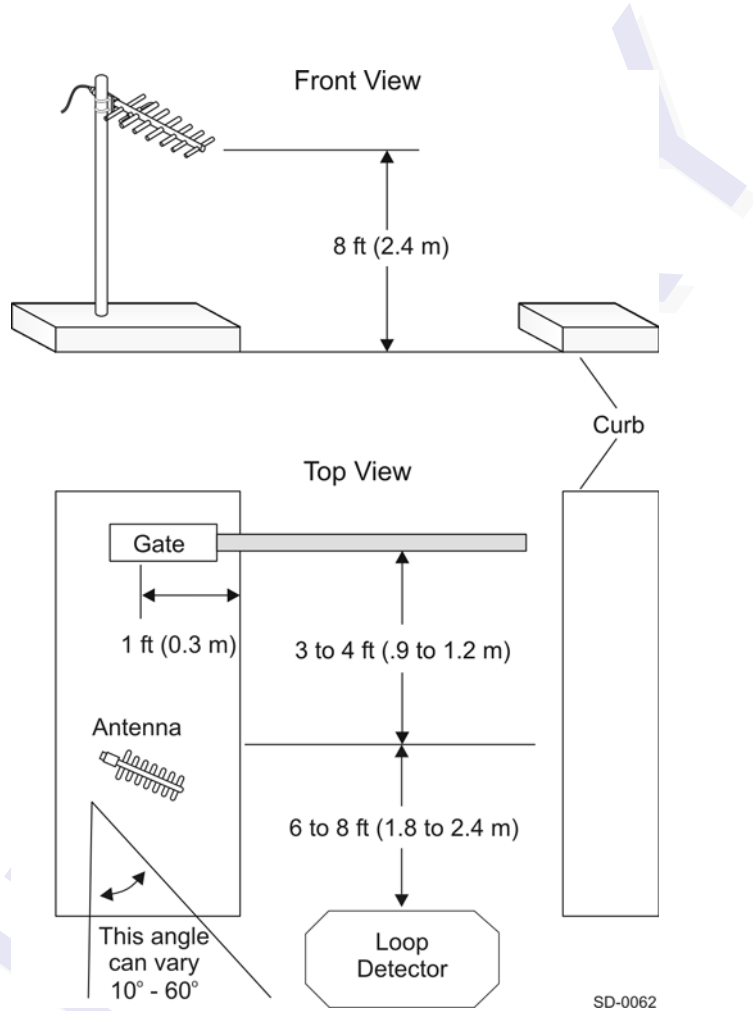
*Note:* Determine the read zone before you tighten all screws and straps permanently. Refer to the section [“Marking the Read Zone” on page 4-32](#).

After mounting the antenna, you must connect it to the Encompass 4/4800 Multiprotocol Reader. Follow the procedures described previously in the section [“Connecting the Antenna” on page 4-6](#).



#### Caution

*To avoid damage to the Encompass 4/4800 Multiprotocol Reader, you must connect the antenna before applying power to the reader.*



**Figure 4-14 Front and Top Views of the Curb-Side Antenna Position**

*Note: The dimensions in Figure 4-14 are for demonstration purposes only and are approximations for sites using the older ATA-type tags. Actual dimensions vary as lane geometry and tag style varies from site to site. Adjust the antenna to match site and tag mounting positions to provide the most direct line of sight to the tags.*

## Mounting the Antenna Overhead

Some site designs require that the antenna be mounted in an overhead location.

### Procedures

#### To mount the antenna in an overhead location

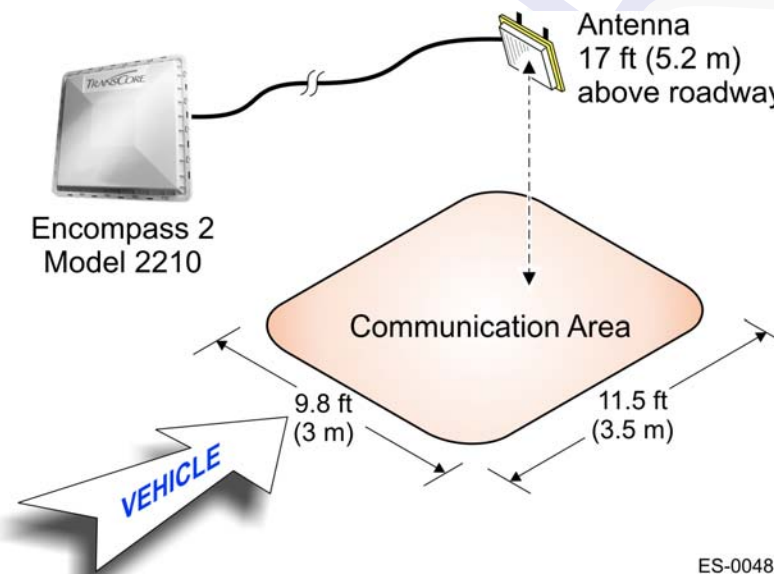
1. Follow the manufacturer's directions to attach the antenna assembly to the overhead location at approximately 18 feet above the pavement surface.
2. Tighten slightly so that you can adjust the antenna up and down but not so slightly that there is a risk of the antenna falling.

- Adjust the assembly by pointing the antenna to the middle of the area where tags will be read, and while in this position, tighten all screws and fastenings slightly.

*Note:* Adjust the antenna to provide the most direct line of sight to the tags.

For example, in toll lanes the Universal Toll Antenna (UTA) would be installed approximately 15 degrees from the verticle.

Figure 4-15 illustrates an overhead-mounted antenna with approximate measurements for the read zone.



**Figure 4-15 Encompass 4/4800 Multiprotocol Reader Installation with Overhead Antenna**

*Note:* Determine the read zone before you tighten all screws and straps permanently. Refer to the section “Marking the Read Zone” on page 4-32.

After mounting the antenna, you must connect it to the Encompass 4/4800 Multiprotocol Reader. Follow the procedures described previously in the section “Connecting the Antenna” on page 4-6.

## Connecting the Power Supply

To connect the Encompass 4/4800 Multiprotocol Reader to a low-voltage AC power supply follow the procedures described previously in the section “Connecting the AC Power Supply” on page 4-6.

To connect the Encompass 4/4800 Multiprotocol Reader to a low-voltage DC power supply follow the procedures described previously in the section “Connecting the DC Power Supply” on page 4-7.

After mounting the Encompass 4/4800 Multiprotocol Reader and antenna, if required, you must connect the reader to a dedicated 16 to 20V AC or 16 to 28V DC power supply.



**Caution**

*To avoid damage to the Encompass 4/4800 Multiprotocol Reader, you must connect the antenna before applying power to the reader.*

## Connecting Communications

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TransCore offers reader models that communicate through RS–232, RS–422, and Wiegand interface protocols. This section describes the procedures and materials required for connecting the communications to the junction box and to the sense input and sense output circuits.

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### Required Materials

You need the following materials to connect the communications cable to the PC:

- PC or laptop
- Any terminal emulation program such as Procomm Plus™ or Hyper Terminal™ running on a PC
- Communications cable to connect to the COM1 port on your PC

---

### Connecting the Encompass 4/4800 Multiprotocol Reader to the PC

Encompass 4/4800 Multiprotocol Reader communications and customer interface signals are supplied from the Encompass 4/4800 Multiprotocol Reader to the host through a multiwire cable, which is a 13-pair pigtail. The connector for this cable is located on the back of the Encompass 4/4800 Multiprotocol Reader. Refer to the following sections to connect the appropriate communications wires from the cable to the terminal strip that is located inside the junction box.

These sections contain instructions for connecting RS–232, RS–422, and Wiegand communications between the Encompass 4/4800 Multiprotocol Reader and the PC. Each section contains wiring instructions and pin assignments followed by step-by-step connection procedures.

The Encompass 4/4800 Multiprotocol Reader can remain powered up while connecting reader-to-host PC communications.

#### **RS–232 Interface**

RS–232 interface signals are supplied by three or five wires from the Encompass 4/4800 Multiprotocol Reader communications cable. The pin assignments for the signal to the host male DB9 and DB25 connectors are shown in boldface in [Figure 4-3](#).

**Connecting the Encompass 4/4800 Multiprotocol Reader Colored-Wire Pair Cable**

Table 4-7 shows the RS-232 colored wire assignments.

**Table 4-7 RS-232 Interface Signal Wiring for Colored-Wire Pair Cable**

Signal from Encompass 4/4800 Multiprotocol Reader	Colored-Wire Pair Cable		Connect Wire to Host DB9 Pin	Connect Wire to Host DB25 Pin
	Wire Pair from Encompass 4/4800 Multiprotocol Reader	Color Used		
TxD — Encompass 4/4800 Multiprotocol Reader sense output, host sense input	Red/Black	Black	Pin 2	Pin 3
RxD — Encompass 4/4800 Multiprotocol Reader sense input, host sense output		Red	Pin 3	Pin 2
Signal ground	Yellow/Black	Yellow or Black	Pin 5	Pin 7
<b>Optional for hardware handshaking</b>				
RTS — Encompass 4/4800 Multiprotocol Reader sense output, host sense input	Yellow/Red	Yellow	Pin 8	Pin 5
CTS — Encompass 4/4800 Multiprotocol Reader sense input, host sense output		Red	Pin 7	Pin 4

**To connect the colored-wire cable using RS-232 interface**

1. Connect the black wire (transmit data) from the red and black wire pair to pin 2 of the DB9 connector or pin 3 of the DB25 connector.
2. Connect the red wire (receive data) from the red and black wire pair to pin 3 of the DB9 connector or pin 2 of the DB25 connector.

3. Connect either the yellow or black wire (signal ground) from the yellow and black wire pair to pin 5 of the DB9 connector or pin 7 of the DB25 connector.
4. Plug the DB9 connector or DB25 connector into the PC.

If the host is set up for hardware handshaking, use the following procedures:

1. Connect the yellow wire (RTS) from the yellow and red wire pair to pin 8 of the DB9 connector or pin 5 of the DB25 connector.
2. Connect the red wire (CTS) from the yellow and red wire pair to pin 7 of the DB9 connector or pin 4 of the DB25 connector.

### **RS-422 Interface**

RS-422 interface signals are supplied by four wires from the Encompass 4/4800 Multiprotocol Reader communications cable. Your host must have an RS-422 interface with either an internal or external converter.

Table 4-8 shows the RS-422 signals and their interface wires.

**Table 4-8 RS-422 Interface Signal Wiring for Colored-Wire Pair Cable**

Signal from Encompass 4/4800 Multiprotocol Reader	Colored-Wire Pair Cable		Connect to Signal from Host
	Wire Pair from Encompass 4/4800 Multiprotocol Reader	Color Used	
RS-422 Transmit positive	Yellow/Red	Yellow	Receive (+)
RS-422 Transmit negative		Red	Receive (-)
RS-422 Receive positive	Red/Black	Black	Transmit (+)
RS-422 Receive negative		Red	Transmit (-)
Signal Ground	Yellow/Black	Yellow or Black	Signal Ground

#### **To connect the colored-wire cable using RS-422 interface**

1. Connect the yellow wire (transmit +) from the yellow and red wire pair to the host receive (+) signal.
2. Connect the red wire (transmit -) from the yellow and red wire pair to the host receive (-) signal.
3. Connect the black wire (receive +) from the red and black wire pair to the host transmit (+) signal.
4. Connect the red wire (receive -) from the red and black wire pair to the host transmit (-) signal.

### Wiegand Interface

Wiegand interface signals are supplied by three wires from the Encompass 4/4800 Multiprotocol Reader communications cable. The Encompass 4/4800 Multiprotocol Reader with RS-232 or RS-422 comes with the Wiegand option built in. The Wiegand interface can only be used by the reader to output valid Wiegand tag reads. All reader commands and responses are issued through the serial interface.

Table 4-9 shows the Wiegand signals and the interface wires.

**Table 4-9 Wiegand Interface Signal Wiring for Colored-Wire Pair Cable**

Signal from Encompass 4/4800 Multiprotocol Reader	Colored-Wire Pair Cable		Connect to Signal from Host
	Wire Pair from Encompass 4/4800 Multiprotocol Reader	Color Used	
Wiegand Zero Output	Blue/Red	Blue	Data0
Wiegand One Output		Red	Data1
Signal Ground	Yellow/Black	Yellow or black	Ground

#### To connect Wiegand interface

1. Connect the blue wire (data0) from the blue and red wire pair to the data0 wire of the Wiegand device.
2. Connect the red wire (data1) from the blue and red wire pair to the data1 wire of the Wiegand device.
3. Connect either the yellow or black wire from the yellow and black pair to the Wiegand device's signal ground.

*Note: The RS-232 or RS-422 interface is still included on the Encompass 4/4800 Multiprotocol Reader even when you use the Wiegand configuration. If serial communication is not needed, TransCore recommends leaving the DB9 or DB25 connected to the cable for future use.*



#### Warning

*Do not cut the RS-232 red/black wires. If you cut the wires, you may not be able to use them in the future for testing, setting frequency, or adding additional functions.*

## Connecting Sense Input and Sense Output Circuits

The Encompass 4/4800 Multiprotocol Reader has two sense input circuits and three sense output circuits available. The sense input circuits can be used to notify the Encompass 4/4800 Multiprotocol Reader of external events and are designed to be



connected to a free-of-voltage dry contact. Sense output circuits are single-pole, double-throw relays that provide normally closed and normally open dry contacts. The relay contacts are rated at 42.2V AC peak (30 Vrms) or 60V DC at 1 A maximum. If controlling an external gate or device requiring high current, an isolation transformer is required.

The following sections provide information to connect the sense input and sense output circuits.

### Sense Input Circuits

The Encompass 4/4800 Multiprotocol Reader supports two sense inputs – sense input0 and sense input1 – which requires two sense input lines for each loop sense or a total of four sense input connections. Sense input0 is the presence detection device line and is used to control RF power. As shown in Figure 4-16, sense input0 is through the red/green wire pair on the I/O pigtail. The Encompass 4/4800 Multiprotocol Reader expects the sense input0 circuit to close when a vehicle is present (i.e., a normally open condition). The minimum presence true period is fixed at 0 ms, which indicates that no delay occurs in closing the circuit when a vehicle is present.

Sense input1 allows the Encompass 4/4800 Multiprotocol Reader to monitor the status of a peripheral device. The host computer can then check the status by polling the Encompass 4/4800 Multiprotocol Reader.

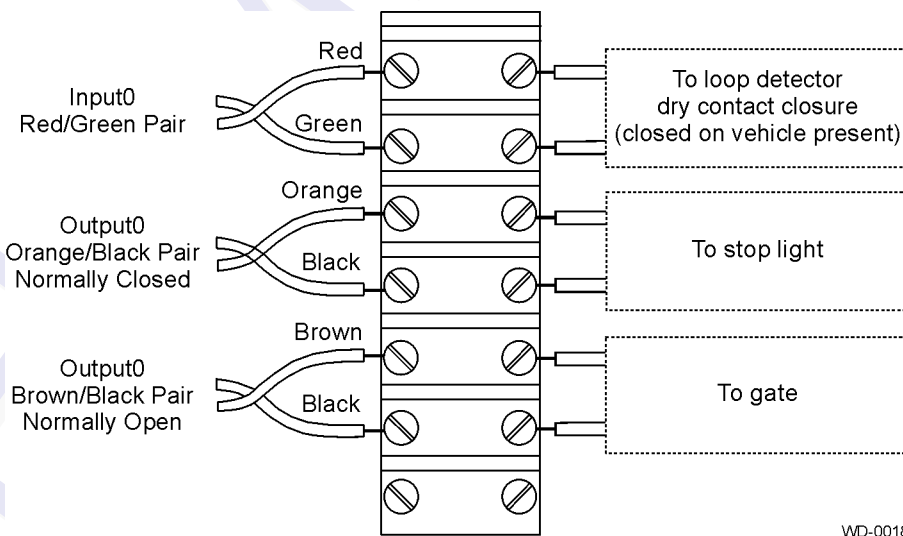


Figure 4-16 Sample Circuit Connections

### Sense Output Circuits

The Encompass 4/4800 Multiprotocol Reader supports three sets of sense output signals. Two sets – sense output0 and sense output1 – provide normally open or normally closed sense outputs. The third sense output set is dedicated for testing and set up of

the reader. It is defined as the TAG\_LOCK signal, which indicates a valid tag is in the read field.

These sense outputs are dry contacts that provide normally open and normally closed sense outputs. The relay contacts are rated at 42.2V AC peak (30 V<sub>rms</sub>) or 60V DC at 1 A maximum. If controlling an external gate or device requiring high current, an isolation transformer is required.

As illustrated in Figure 4-16, sense output0, normally closed, is located on the orange/black pair. Sense output0, normally open, is located on the brown/black pair.

In Wiegand mode operation, the sense outputs are not controlled by a predefined output mode.

Table 4-10 lists the cable descriptions and functions for the interface signals. These wire pairs can be used or terminated based on the specific project applications and site requirements.

Using Table 4-10 as a guide to the functions of each of the wire signals, connect the remaining wires to the appropriate terminal blocks on the terminal strip in the junction box.

**Table 4-10 Sense Input/Output Cabling Assignments**

Pair	Pin	Color	Signal	Description	Typical Function
Blue/Red	E	Blue	WGND0	Wiegand data0	Parking/access control applications
	F	Red	WGND1	Wiegand data1	Parking/access control applications
White/Red	L	White	Lock	Tag lock output, active-closed	Testing maintenance
	M	Red	Lock_RTN	Tag lock return	Testing maintenance
Green/Red	N	Green	Sense Input0	Sense Input0 (loop)	Loop and presence detection
	P	Red	Sense Input0_RTN	Sense Input0 return; not isolated from signal ground	Loop and presence detection
Blue/Black	R	Blue	Sense Input1	Sense Input1	General-purpose sense input, not used for detecting presence

Table 4-10 Sense Input/Output Cabling Assignments (continued)

Pair	Pin	Color	Signal	Description	Typical Function
	S	Black	Sense Input1_RTN	Sense Input1 return; not isolated from signal ground	General-purpose sense input, not used for detecting presence
Brown/Black	T	Black	Sense Output0_COM	Sense Output0 (tag detect), common terminal	Switched output to control gate
	U	Brown	Sense Output0_NO	Sense Output0 normally open terminal	Switched output to control gate
Orange/Black	V	Black	Sense Output0_COM	Sense Output0 (tag detect output), common terminal	Switched sense output for any external control (light, gate, buzzer, etc.)
	W	Orange	Sense Output0_NC	Sense Output0 normally closed terminal	Switched sense output for any external control (light, gate, buzzer, etc.)
Green/Black	X	Black	Sense Output1_COM	Sense Output1, common terminal	Switched sense output
	Y	Green	Sense Output1_NO	Sense Output1 normally open terminal	Switched sense output
White/Black	Z	Black	Sense Output1_COM	Sense Output1, common terminal	Switched sense output
	a	White	Sense Output1_NC	Sense Output1 normally closed terminal	Switched sense output
Yellow/Black	b	Yellow	GND	Logic ground	Signal ground used with RS-232 and Wiegand
	c	Black	GND	Logic ground	Signal ground used with RS-232 and Wiegand



**Caution**

*After connecting the wires in the communications cable, ground all drain wires from the communications cable to the chassis ground in the NEMA enclosure.*

## Marking the Read Zone

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The area where the Encompass 4/4800 Multiprotocol reads tags at the current RF range is called the read zone. The antenna pattern, or read zone, of the Encompass 4/4800 Multiprotocol Reader would look roughly like a pear-shaped balloon if you were able to see it. When installing the Encompass 4/4800 Multiprotocol Reader, you should first mark the unit's read zone using the RF range set at the factory-default maximum. You can later adjust the read zone using the techniques discussed in [“Fine-Tuning and Verifying the Read Zone”](#) on page 8-20.

If two Encompass 4/4800 Multiprotocol Readers are installed near each other, TransCore recommends that you fine-tune each reader for the ideal read zone before connecting it permanently to sense input/sense output and communications cables. A minimum of 2 MHz frequency separation between the two adjacent readers is required for correct operation.

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### Required Materials

You need the following materials to mark the read zone:

- Test tags, supplied by the TransCore dealer or distributor
- Piece of windshield-type glass 0.190 to 0.230 inches (4.82 to 5.84 mm) in thickness and approximately 12 inches (30.48 cm) square on which to attach the eGo Windshield Sticker Tag



#### Caution

*The eGo Windshield Sticker Tag has a reduced read range when not attached to glass.*

- Audible circuit tester and 9V DC battery for circuit tester power as described in the section [“Bench Testing the Encompass 4/4800 Multiprotocol Reader Before Installation”](#) on page 4-12.
- Piece of chalk or roll of tape
- Plastic or wooden yardstick for ATA tags
- Vinyl electrical tape or hook-and-loop material

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### Procedures

*Note: Using test tags that are not mounted to vehicles give a general idea of the read pattern but the pattern will vary somewhat when actual vehicles with tags are tested. Final adjustments must be made with tags properly mounted on a variety of vehicles.*

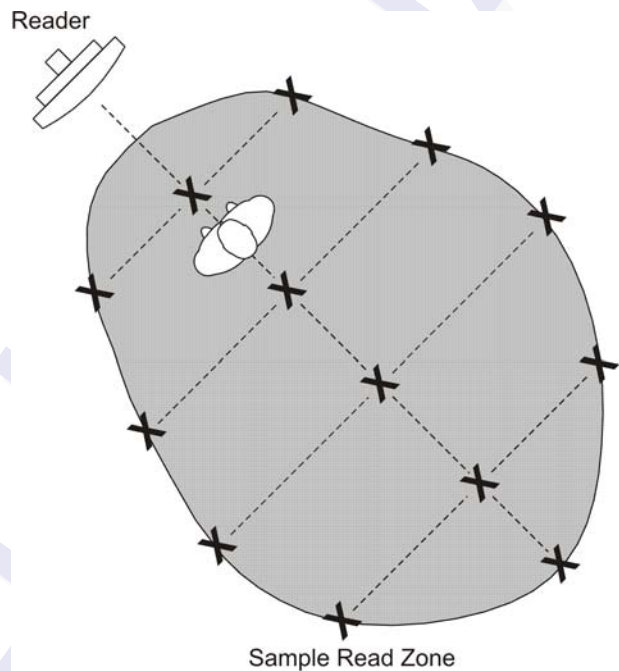
**To mark the read zone**

1. Confirm the following:
  - You have correctly connected the power supply as described “[Connecting the AC Power Supply](#)” on page 4-6 and “[Connecting the DC Power Supply](#)” on page 4-7.
  - You have correctly connected communications as described in “[Connecting Communications](#)” on page 4-25.
  - You have correctly connected sense input and sense output circuits as described in “[Connecting Sense Input and Sense Output Circuits](#)” on page 4-28.
2. Connect the red and white leads from the audible tester to the red and white pair of wires from the Encompass 4/4800 Multiprotocol Reader power/communications cable.
3. Start the terminal emulation application Microsoft HyperTerminal by selecting **Programs>Accessories>Communications>HyperTerminal** and press **ENTER**.
4. In the HyperTerminal dialog boxes choose the com port to which the communications interface is attached and set the properties as:
  - Bits per second: 9600 baud
  - Data bits: 8
  - Parity: none
  - Stop bits: 1
  - Flow control: none
5. Cycle the power on the Encompass 4/4800 Multiprotocol Reader and ensure that the sign-on message displays.
6. Input the following commands in the order provided in [Table 4-6](#) on page 4-13. Commands include those to switch to command mode, set operational mode, turn on RF, and return the reader to data mode.
7. Secure the ATA test tag to the end of the yardstick using electrical tape or hook-and-loop material or affix the test eGo Windshield Sticker Tag to the glass. Be sure the tag polarization (horizontal or vertical alignment) matches that of the Encompass 4/4800 Multiprotocol Reader or antenna used. If using an eGo test tag, the glass should be in front of the tag (between the tag and the reader or antenna).
8. Stand directly in front of and about 5 feet (1.5 m) away (see Figure 4-17) from the Encompass 4/4800 Multiprotocol Reader or antenna. Hold the stick or the piece of glass so that the tag is positioned at a height and angle consistent with a tag installed on a vehicle. The test tag should cause the audible tester to sound.

***Note:** If you hold the test tag in your hand, your hand absorbs the RF signal and the test results are not accurate.*
9. Mark the spot with chalk or tape.

10. Move to the left until the sound stops and mark the ground with chalk or tape at the location of the tag when the sound stopped.
11. Return to the center and then move to the right until the sound stops and mark the ground with chalk or tape at the location of the tag when the sound stopped.
12. Return to the center and step backward 2 feet (0.6m) and repeat steps 5 through 7.
13. Continue moving the tag in this manner, placing marks on the ground to identify the boundary of the read zone each time the sound stops. Continue moving the tag to various locations until the read zone is fully marked.
14. You can now connect the outer marks to draw the outer boundary of the read zone.

Figure 4-17 is a view of a sample read zone within a controlled lane. The outer X marks show the outside edges of the read zone.



**Figure 4-17 Sample Read Zone Marking Pattern**

15. Standing at the farthest point of the pattern, walk toward the Encompass 4/4800 Multiprotocol Reader or antenna and listen for a continuous sound from the audible tester. If the sound is not continuous, it could indicate a weak or “patchy” RF pattern. See [“Fine-Tuning and Verifying the Read Zone”](#) on page 8-20 to adjust the read zone.

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General Software Information

PRELIMINARY





## General Software Information

***This chapter provides software-related information for the Encompass™ 4/4800 Multiprotocol Reader System.***

This chapter presents various software-related topics arranged in alphabetical order by subject. In addition to this chapter, see Chapter 6, “[Communications Protocols](#),” and Chapter 7, “[Commands](#),” for more information.

### Command Entry Conventions

All Encompass 4/4800 Multiprotocol Reader commands are preceded by the start-of-message character (#). The end-of-message sequence expected from the host is a carriage return (CR). The Encompass 4/4800 Multiprotocol Reader terminates messages with a return and a line-feed (CR/LF). For example, the command #01 Switch To Command Mode is typed as follows:

```
#01<ENTER>
```

where <ENTER> is the Enter or Return key.

Some command characters may be represented by the letter N. This letter indicates you are to supply a value. Maximum valid entries are the numbers 0 through 9 and the uppercase letters A through F. These letters allow for as many as 16 available user responses and are based on the hexadecimal numbering system.

Commands have at least two characters following the # character. [Table 5-1](#) shows the basic structure of a four-character command.

**Table 5-1 Four-Character Command Structure**

#1005 Set Baud Rate To 9600 Baud	
#	All commands are preceded by the # character.
1	Indicates the command group. This command is in Group 1-Communications Port Control.
0	Indicates the command subgroup. In this example, all commands with a second digit of 0 apply to the main port.
0	The command digit. In this example, the 0 indicates that this command affects the baud rate.
5	Indicates the setting. Normally this is a variable and is usually a hexadecimal value from 0 through F. In this example, 5 sets the baud rate to 9600, the factory setting. In some commands, this digit may be a four-place hexadecimal string or a character string.

## Command Response Conventions

Like the Encompass 4/4800 Multiprotocol Reader commands, responses are preceded by the # character. Many Encompass 4/4800 Multiprotocol Reader commands respond with #Done or #Error indicating the command was or was not recognized and completed. Other commands respond with a four-character identifier followed by one or more values.

Table 5-2 shows an example of a command/reply sequence. This example assumes that an Encompass 4/4800 Multiprotocol Reader with serial number SN97001P running version X.XX software is connected to a PC running a terminal emulation software package such as Windows Hyper Terminal or Procomm Plus. The command sequence verifies that communications are working correctly.

**Table 5-2 Sample Command Sequence**

Entry	Encompass 4/4800 Multiprotocol Reader Response	Notes
#01 <CR>	#Done <CR/LF>	Switches Encompass 4/4800 Multiprotocol Reader to command mode.
#505 <CR>	#Model eGo2000 Series Ver X.0X SN97001P <CR/LF>	Reports the software version and serial number.
#00 <CR>	#Done <CR/LF>	Returns Encompass 4/4800 Multiprotocol Reader to data mode.

In command discussions, Encompass 4/4800 Multiprotocol Reader response characters may be shown in brackets < >. The use of brackets indicates that the response is a value in the range of characters. The brackets are not part of the response. For example, the response to command #520 Display Power Fail Bit is either a 0 or a 1. In the command discussion, the response is shown as:

#PWRB <0-1>

with actual Encompass 4/4800 Multiprotocol Reader response being one of the following:

#PWRB 0

#PWRB 1

In this example, PWRB is the four-character identifier for *power fail bit*, and the 0 or 1 is the value. All spaces shown in the response are actual spaces sent from the Encompass 4/4800 Multiprotocol Reader. In this example, one space is between the letter B and the number.

## Operating Parameters

---

The Encompass 4/4800 Multiprotocol Readers maintain their operating parameters in non-volatile memory (NVRAM) so that the parameters are preserved after a power-down sequence.

## Power Fail

---

The system maintains a power fail flag. The host transmits command #520 Display Power Fail Bit to determine if a power down has occurred. This flag is cleared by both command #63 Reset Reader and command #65 Reset Power Fail Bit.

## Program Download

---

Program download stores the Encompass 4/4800 Multiprotocol applications software into the Encompass 4/4800 Multiprotocol Reader's flash memory. Program download is used to install program upgrades, add features, and to recover from corrupted program data. The download mode supports a limited set of commands: #90 Load Program Block, #91 Verify Flash Checksum, #96 Erase Flash Memory, #97 Perform Destructive Memory Test, and #99 Exit Download Mode.

---

### Download Considerations

You should consider the following factors when performing program download:

- The Encompass 4/4800 Multiprotocol Reader does not process tags while in download mode.
- The Encompass 4/4800 Multiprotocol Reader accepts only download commands while in download mode. It responds to all other commands with an error message.
- The Encompass 4/4800 Multiprotocol Reader does not accept any program data unless a successful erase of flash memory has been performed before transmitting the data. Erasing the flash memory typically takes seven seconds.
- Exiting from download mode re-executes startup. If the new software has been loaded without errors, the Encompass 4/4800 Multiprotocol Reader comes up in data mode. If a flash checksum error is detected, the Encompass 4/4800 Multiprotocol Reader reenters download mode and transmits a sign-on message with a boot version of 0.00x and without a serial number.

*Note: The Encompass 4/4800 Multiprotocol Reader uses default communications parameters when operating in download mode – 9600 baud, 8 data bits, 1 stop bit, no parity, basic protocol – and does not echo commands.*

---

## Download Procedures

If TransCore releases a new version of the Encompass 4/4800 Multiprotocol Reader software or if the Encompass 4/4800 Multiprotocol Reader seems not to be working properly, you may need to download the software to the Encompass 4/4800 Multiprotocol Reader. Contact technical support or your TransCore Encompass 4/4800 Multiprotocol Reader sales representative.

---

## Startup

Upon startup, Encompass 4/4800 Multiprotocol Reader's transmit a sign-on message or a boot ROM failure message.

---

### Sign-On Message

If startup is successful, the sign-on message appears as follows:

```
Model [software version] SNYYYYYY  
[Copyright notice]
```

where YYYYYY is the serial number assigned to the Encompass 4/4800 Multiprotocol Reader unit being used.

Serial number 000000 is the default setting and is not a valid number. If this number appears in the sign-on message, the serial number has never been stored into reader memory. The serial number must be assigned by factory-authorized personnel using command #695 Set Serial Number. Because only six digits are allowed in the software, when setting the serial number skip the fourth (middle) digit of the seven-digit number shown on the reader label.

If the flash memory checksum does not indicate verification, the sign-on message appears as follows:

```
Model [PARC] Ver 0.00x  
[Copyright notice]
```

---

### Boot Failure Message

The software performs a checksum function on itself. The function returns a specific value for the particular version of software. If the value returned is not correct, the boot ROM checksum assumes that locations have been corrupted and a failure condition exists. If the boot ROM checksum is not correct, a boot failure message is transmitted. If the failure message does not transmit, a communications error has occurred or the boot failed to the extent that it cannot transmit the failure message.

If the failure message version number equals 0.00 and no serial number exists, the flash memory checksum has failed, and the Encompass 4/4800 Multiprotocol Reader is operating out of boot ROM. In this case, the Encompass 4/4800 Multiprotocol Reader automatically enters download mode and waits for a new program to be loaded into the flash memory. Follow the instructions in [“Program Download”](#) on page 5-5 to download a new program.

## ***Tag/Message Buffer***

---

In basic communication protocol, the Encompass 4/4800 Multiprotocol Reader does not provide tag memory storage beyond the quantity required for uniqueness checking. This feature allows adequate buffering of tag data under normal operating conditions. The Encompass 4/4800 Multiprotocol Reader cannot operate as a stand-alone component. When the buffer fills, subsequent tag IDs will be lost.

In error correcting protocol (ECP), a buffer of up to three additional tag reads will be held in case a host system is unable to acknowledge tag reads in real time.

PRELIMINARY

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Communications Protocols

PRELIMINARY





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# Communications Protocols

*This chapter describes the communications protocols for the Encompass™ 4/4800 Multiprotocol Reader.*

## Introduction

---

The Encompass 4/4800 Multiprotocol Reader supports the following communications protocols:

- Basic
- Error correcting protocol (ECP)

The following protocol information provides reference information relevant to developing host software.

Communications are performed using the 7-bit ASCII code with optional parity, thus providing easy setup, testing, and diagnostics with standard ASCII terminals and serial printers. Parity must be enabled to achieve the specified undetected error rate.

Each message is framed within the start-of-message (som) and end-of-message (eom) characters so that the host computer can detect the beginning and end of each message. This convention is most important under marginal communications conditions during which the host may receive extraneous noise-induced characters between reader transmissions. In such instances, the host is capable of ignoring any messages that do not conform to the som...eom frame sequence.

Both data mode and command mode require a two-way message interchange is when using ECP. This interchange is completed by the message recipient returning a message acknowledgement to the message sender.

With ECP, all transmissions require a message. If a message is not received, the sender will time out with the same effect as if it had received a negative acknowledgment (from the host) or an Error message from the Encompass 4/4800 Multiprotocol Reader.

Software (XON/XOFF) flow control is optionally supported. Be careful in the use of XON/XOFF since noise-induced characters may be interpreted by the Encompass 4/4800 Multiprotocol Reader as the XOFF character, which would suspend reader output without information reaching the host computer. For more information see [“Software Flow Control” on page 8-19](#).

**Note:** TransCore recommends that XON/XOFF flow control be disabled while using ECP.

## Basic Protocol

---

With basic protocol, messages sent to and from the Encompass 4/4800 Multiprotocol Reader and the host are transmitted without error checking. For each host transmission, the Encompass 4/4800 Multiprotocol Reader returns a Done or Error message to the host.

When the host computer is physically close to the Encompass 4/4800 Multiprotocol Reader and no sources of interference exist, the basic protocol provides reliable communications.

The host must be ready to receive reader-transmitted messages because in basic protocol the Encompass 4/4800 Multiprotocol Reader does not wait for the host to acknowledge a message before transmitting the next message. If necessary, the host may halt reader transmissions by using software or hardware flow control. Refer to Chapter 8 for flow control information.

## Error Correcting Protocol

---

When the quality of data communications is imperative or may be suspect, you can invoke ECP to ensure the integrity of data transmitted between the Encompass 4/4800 Multiprotocol Reader and the host.

*Note: TransCore recommends that basic protocol (not ECP) be used when commands are entered manually at the keyboard.*

Wiegand output is automatically disabled when the reader is put into ECP mode.

Error correction is accomplished with the use of a cyclic redundancy check (CRC) value that is based on the message data. The originator (reader or host) calculates the CRC value of a message and includes it in the transmitted message.

The recipient (reader or host) also calculates a CRC value for the received message. If the transmitted message data is correct, the CRC value calculated by the recipient will agree with the CRC value calculated by the originator. If the CRC values do not agree, the recipient rejects the message.

Message sequence numbers are also included when using ECP. These sequence numbers are checked to determine if the message received has the correct sequence number; if not, the recipient rejects the message.

Since the seven-bit ASCII code is used and there are eight data bits per character, the eighth bit can optionally be used to support parity. Where parity is selected, the CRC value calculation includes the parity of each character in the calculation of the CRC value.

Parity is required to achieve the most reliable communications. If parity is enabled, both the Encompass 4/4800 Multiprotocol Reader and the host must issue a message if any received character has a parity error. However, the message must not be trans-

mitted before receipt of the eom character. In this case, the Encompass 4/4800 Multiprotocol Reader will issue an Error message, and the host computer will issue a negative acknowledgment message.

## Basic Protocol and ECP Format

---

*Note: In the following text, the symbols < and > are used to represent required variable message data, and the symbols [and] are used to represent optional data. These symbols are not part of the message syntax.*

---

### Reader Transmissions

The basic protocol format and the data inquiry protocol format are as follows:

```
<som><data><eom>
```

The ECP format is as follows:

```
<som><seq><data><crc><eom>
```

where

<som> Start-of-message (ASCII # character)

<seq> Sequence number (ASCII hex) that represents an even number in the range 0–9, A–F (0, 2, 4, 6, 8, A, C, E). The Encompass 4/4800 Multiprotocol Reader maintains the number. The host must acknowledge reader transmissions by sending an ACK message with the same sequence number received from the Encompass 4/4800 Multiprotocol Reader. The Encompass 4/4800 Multiprotocol Reader updates its sequence number upon receipt of a valid host ACK. If an ACK is not received, the Encompass 4/4800 Multiprotocol Reader retransmits the message. A reader transmission sequence is not considered complete until the Encompass 4/4800 Multiprotocol Reader receives an ACK and updates its sequence number.

<data> An ASCII string up to 72 characters long. This string may contain tag data, a presence without tag report; an input status change report; an Error06, Error07, Error08, or Error11 message; or a sign-on message. Auxiliary data may also be included.

<crc> Field containing four ASCII digits that represent the 16-bit CRC value calculated on the message. The CRC value is calculated on bytes between the som character and the first <crc> byte.

When the host receives a properly framed message, it can calculate a 16-bit CRC value. The calculation is applied to the

character string that immediately follows the <som> and that ends with the character immediately preceding the first <crc> character.

The transmitted CRC value can then be compared with the binary equivalent of the received <crc> characters. If the transmitted and received CRC values do not match, the recipient assumes the message was received in error, and transmits a NAK message response.

<eom> End-of-message characters (ASCII CR and LF). The system includes both a carriage return (CR) and line feed (LF) to facilitate the use of terminals and printers.

If the host receives a <som> character in the middle of a data message, the message in progress is aborted. The assumption is that an <eom> was lost and the Encompass 4/4800 Multiprotocol Reader is in the process of retransmitting the previous message.

---

### **ECP Host ACK/NAK Response**

With ECP, the host computer responds to all data message transmissions from the Encompass 4/4800 Multiprotocol Reader using the following acknowledgment or negative acknowledgment response format.

<som><seq><ack/nak><crc><eom>

where

<som> Start-of-message (ASCII # character)

<seq> An echo of the sequence number received from the Encompass 4/4800 Multiprotocol Reader. The sequence number should correspond to the data message that is being positively or negatively acknowledged by the host. If the Encompass 4/4800 Multiprotocol Reader receives an ACK message with the incorrect sequence number, the data message is retransmitted.

The host computer resets the anticipated data message sequence number to that of the Encompass 4/4800 Multiprotocol Reader before communications can resume without error.

<ack/nak> ASCII @ character for ACK response; ASCII ? character for NAK response

<crc> CRC value for the message

<eom> End-of-message character (ASCII CR)

The Encompass 4/4800 Multiprotocol Reader sets a user-programmable timeout delay at the time each message is transmitted based on command #612NN *Select Error Correcting Protocol Timeout*, where NN = timeout delay. To disable the timeout delay for diagnostic purposes, issue the command #612FF *Disable Error Correcting Protocol Timeout*.

If the timeout delay expires before the Encompass 4/4800 Multiprotocol Reader receives an ACK or NAK message from the host, a logical NAK condition will be declared. If the Encompass 4/4800 Multiprotocol Reader receives a NAK or timeout, the reader retransmits the data message.

When the Encompass 4/4800 Multiprotocol Reader receives an ACK message, the system software treats the message as having been properly received by the host. The software increments the sequence number, and advances pointers to the next message in the Encompass 4/4800 Multiprotocol Reader's message queue to prepare for sending the next message.

## ***Switch to Command Mode Request***

The host computer may issue command #01 *Switch to Command Mode* while in data mode.

The basic protocol format is as follows:

<som><cmd><eom>

The ECP format is as follows:

<som><seq><cmd><crc><eom>

where

<som>	Start-of-message (ASCII # character)
<seq>	Sequence number generated by the host computer separately from that appearing in data messages transmitted by the Encompass 4/4800 Multiprotocol Reader
<cmd>	Switch to command mode (ASCII characters 01)
<crc>	CRC value for the message
<eom>	End-of-message character (ASCII CR)

## ***Host Transmission***

The host computer initiates synchronous communications between the Encompass 4/4800 Multiprotocol Reader and the host. The host begins a sequence by issuing a command; the Encompass 4/4800 Multiprotocol Reader responds accordingly.

The basic protocol format is as follows:

<som><cmd>[ <data> ]<eom>

The ECP format is as follows:

<som><seq><cmd>[ <data> ]<crc><eom>

where

<som> Start-of-message (ASCII # character)

<seq> Sequence number (ASCII hex digit) that represents an odd number in the range 0–9, A–F (1, 3, 5, 7, 9, B, D, F). The host should use odd sequence numbers in its command since the Encompass 4/4800 Multiprotocol Reader uses even sequence numbers in its transmissions. This method eliminates the possibility of a synchronous host command and an asynchronous reader transmission having the same sequence number.

Upon receiving a host command, the Encompass 4/4800 Multiprotocol Reader echoes the command's sequence number in its response. Therefore, the host computer updates its sequence number upon receipt of a valid reader message. If the sequence number is not updated before transmission of the next command, the Encompass 4/4800 Multiprotocol Reader will not service the new command; it will retransmit its previous message. A command/message sequence is not complete until the host updates its sequence number.

<cmd> Command code, a string that contains from two to four ASCII hex characters

[ <data> ] Optional data field, an ASCII string of as many as 20 characters in length. For example, the store hardware configuration string command is #696S...S or command #696 Store Hardware Configuration String followed by the data string S...S.

<crc> CRC value for the message

<eom> End-of-message character (ASCII CR)

---

## **Reader Command Response**

The basic protocol format is

<som><resp><eom>

The ECP format is

<som><seq><resp><crc><eom>

where	
<som>	Start-of-message (ASCII # character)
<seq>	Echo of sequence number received in host command message
<resp>	Response string. The Encompass 4/4800 Multiprotocol Reader returns Done, Error, or another ASCII string depending on the host transmission. This string can be up to 72 characters long.
<crc>	CRC value for the message
<eom>	End-of-message character (ASCII CR and LF)

### Sample Messages

This section contains examples of typical messages transmitted between the Encompass 4/4800 Multiprotocol Reader and the host computer.

#### Reader Transmissions

Basic protocol reader transmission

```
#KING 1302<eom>
```

Host response

No host response for non-ECP

ECP reader transmission

```
#4KING 1302 <crc><eom>
```

where

# Start-of-message character

4 Message sequence number

KING 1302 Message data: Tag ID is shown.  
Other sample message data could be as follows:  
IOST C0 O2 IO D24 (display I/O status)  
Error06 (frequency not set)

<crc> CRC value for the message

<eom> End-of-message character

Host response

```
#4@<crc><eom>
```

where

#	Start-of-message character
4	Message sequence number
@	ACK (acknowledgment character) (? returned for a negative acknowledgment)
<crc>	CRC value for the message
<eom>	End-of-message character

### **Host Command Transmissions**

Basic protocol host transmission

#64202<eom>

Reader response

#Done<eom> or #Error<eom>

#Error<eom> is returned if the host transmission is not a legal command with legal data.

ECP host transmission

#764202<crc><eom>

where

#	Start-of-message character
7	Message sequence number
64202	Select RF Operating Frequency command where 642NN is the command and NN is a hexadecimal value from 00 to 34. In this example, 02 sets the RF frequency to 903 MHz.
<crc>	CRC value for the message
<eom>	End-of-message character
Done	Command has been invoked by the Encompass 4/4800 Multiprotocol Reader

Reader response

#7Done<crc><eom> or #7Error<eom>

For some commands, the Encompass 4/4800 Multiprotocol Reader responds with data that relates to the command, such as TOF 0, to indicate Wiegand mode enabled for a 532 Display Wiegand Mode Status command.



#7Error<eom> will be returned if host transmission is not a legal command with legal data.

---

## Timing and Synchronization

The ECP is largely independent of baud rate. The timeout delays previously described are a function of baud rate.

The Encompass 4/4800 Multiprotocol Reader supports an ECP timeout, which applies equally to both transmit and receive.

The receiver's minimum timeout delay equals the time to transmit/receive the longest anticipated message at the current baud rate setting. Additional margin should be included for idle periods between characters; for example, processing overhead, if any. The timeout delay period can be expressed as follows:

$$T_{\text{rec}} (\text{ms}) = L \times [T_{\text{char}} + T_{\text{idle}}]$$

where

$$T_{\text{char}} (\text{ms}) = 1000 \times [B_c / R_b]$$

$B_c$  Bits per character, typically 10

$R_b$  Baud rate, 2400–38.4 K

$L$  Length of message in characters

$T_{\text{idle}}$  Maximum idle period between characters (ms)

**Note:** The Encompass 4/4800 Multiprotocol Reader supports baud rates between 2400 and 38.4 K.

Likewise, the sender must set a timeout delay equal to the delay of nine characters at the current baud rate setting. For example, the time required to shift out the <eom> character plus the time to shift in the ACK or NAK message to be received plus a processing allowance for the receiver to process the message and check for error conditions.

Thus, the sending timeout delay can be expressed as follows:

$$T_{\text{send}} (\text{ms}) = 9 * T_{\text{char}} + T_{\text{errchk}}$$

where

$T_{\text{errchk}} (\text{ms})$  Processing period to perform error checking by receiver

The host computer can remotely set the Encompass 4/4800 Multiprotocol Reader's communications parameters while in the command mode, but TransCore does not recommend this action if communications conditions are marginal.

After the Encompass 4/4800 Multiprotocol Reader receives new communications parameters, the Encompass 4/4800 Multiprotocol Reader issues the Done message and switches to the new configuration immediately. The host computer switches its communications parameters immediately after the transaction is complete.

As noted, the message initiator, such as the Encompass 4/4800 Multiprotocol Reader in data mode and the host computer in command mode, starts a timeout counter at the time a message is transmitted. If the timeout expires before receiving an acknowledgement message, a logical NAK condition is declared, and the initiator assumes the message was received in error. In this instance, the message is retransmitted until an acknowledgement message is received.

The message recipient, such as the host computer in data mode and the Encompass 4/4800 Multiprotocol Reader in command mode, starts a timeout counter when a <som> character is received. If the timeout expires without the receipt of an <eom>, the message acquisition is aborted (reset), and the receiver waits for the next <som> character.

If the message recipient receives a second <som> character before an <eom> character, the message acquisition is aborted (reset), and retransmission of the previous message is assumed to be underway.

These strategies allow for recovery during periods when communications are marginal or completely lost.

*Note: It is important that the host computer limit the period during which the Encompass 4/4800 Multiprotocol Reader remains in command mode to avoid losing tag IDs. RF is off in command mode and no tags can be read.*

---

## **Reader-Addressed Failure Conditions**

The Encompass 4/4800 Multiprotocol Reader addresses the following failure conditions.

### ***Illegal Sequence Number (not in the range 0–9, A–F)***

If the Encompass 4/4800 Multiprotocol Reader detects an illegal sequence number in a host command message, it discards the received message and sends no response. If it receives an illegal sequence number in an ACK message, it responds as if a NAK had been received and retransmits the data.

### ***Wrong Sequence Number***

If the Encompass 4/4800 Multiprotocol Reader receives the wrong sequence number in an ACK message, it responds as if a NAK had been received, and it retransmits the data.

### ***Incorrect CRC***

If the Encompass 4/4800 Multiprotocol Reader detects an incorrect CRC value in a host command message, it discards the received message. No response is sent. If it receives an incorrect CRC value in an ACK message, it responds as if a NAK had been received, and it retransmits the data.

**Illegal Command**

If the Encompass 4/4800 Multiprotocol Reader receives an illegal command, it returns its standard `Error` message.

**Transmission Timeout**

If the Encompass 4/4800 Multiprotocol Reader transmits an asynchronous message and the host does not send an `ACK` before the ECP timeout occurs, the Encompass 4/4800 Multiprotocol Reader retransmits the message.

**Receive Timeout**

If the Encompass 4/4800 Multiprotocol Reader receives a `<som>` but does not receive a matching `<eom>` before the ECP timeout occurs, it discards the incomplete message and resets its receiver.

**Asynchronous Message/Command Message Collision**

If the Encompass 4/4800 Multiprotocol Reader transmits asynchronous data at the same time that the host sends a command, the Encompass 4/4800 Multiprotocol Reader gives priority to receiving the command. It processes the command and sends a message before it retransmits the asynchronous data.

---

**Host-Addressed Failure Conditions**

The host computer addresses the following failure conditions.

**Illegal or Wrong Sequence Number**

If the host detects an illegal or wrong sequence number in a reader response, it retransmits the command with the same sequence number. If the host detects an illegal sequence number in an asynchronous reader transmission, it sends a `NAK` message.

**Incorrect CRC**

If the host detects an incorrect CRC value in a reader message, it retransmits the command with the same sequence number. If the host detects an incorrect CRC value in an asynchronous reader transmission, it transmits a `NAK` message.

**Transmission Timeout**

If the Encompass 4/4800 Multiprotocol Reader does not respond to a host command within a specified interval, the host software retransmits the command with the same sequence number.

**Receive Timeout**

If the host receives a `<som>` but does not receive a matching `<eom>` within a specified timeout interval, it discards the incomplete message and resets its receiver.

### **Asynchronous Message/Command Message Collision**

If the host receives an asynchronous reader transmission at the same time it transmits a command, it ignores the asynchronous message and waits for the Encompass 4/4800 Multiprotocol Reader's response. The Encompass 4/4800 Multiprotocol Reader retransmits asynchronous data after it transmits the command message.

## **ECP Reliability**

---

An undetected error is defined as a message having incorrect data or status but no parity or CRC errors. An error transaction is defined as a message having either a parity or CRC error. Laboratory testing indicates an undetected error rate of less than one undetected error per 1,000,000 error transactions with parity enabled.

To ensure this error rate is not exceeded, the host must enable parity and adhere closely to the timing specifications discussed previously in this chapter in the "Timing and Synchronization" section.

## **CRC Calculation**

---

The CRC used by the ECP is based on a 16-bit algorithm. The algorithm, as implemented, operates on eight-bit characters, for example, seven-bit ASCII character plus one optional parity bit. The 16-bit result is converted to four ASCII hex characters and is appended to messages transmitted by the Encompass 4/4800 Multiprotocol Reader.

The Encompass 4/4800 Multiprotocol Reader accepts four ASCII <`> characters (60 hex) as a wild card CRC value in lieu of a valid four-character CRC value to facilitate testing and diagnostic checkout.

The Encompass 4/4800 Multiprotocol Reader implements the algorithm with a 512-byte lookup table to reduce the processing overhead requirements.

To simplify the implementation of the CRC algorithm by host software developers, several examples of the calculation are provided in C source code on the following pages. The calculation may be performed with or without a lookup table, depending on the trade-off between code memory and processing overhead.

Example 1 presents an example of a function (CALCCRC) that calculates the CRC value through a call to a separate function (UPDCRC).

```
unsigned short calccrc(char *message)
{
    unsigned short crc = 0;
    for ( ; *message != (char)0; message++)
        crc = updcrc(*message & 0xff, crc);
    return (crc)
}
```

Example 2 shows an example of UPDCRC that does not require a lookup table.

```
#define BITS_PER_CHAR    8
unsigned short updcrc (unsigned short ch, unsigned short
crc)
{
    register short counter = BITS_PER_CHAR;
    register short temp   = crc;
    while (--counter >= 0)
        if (temp & 0x8000) {
            temp <<= 1;
            temp += (((ch <<= 1) & 0x0100) != 0);
            temp ^= 0x1021;
        }
        else {
            temp <<= 1;
            temp += (((ch <<= 1) & 0x0100) != 0);
        }
    return(temp);
}
```

Example 3 contains an example of UPDCRC that does require a lookup table.

```
#define updcrc(cp, crc)( crctab[((crc >> 8) & 255)]^ (crc << 8) ^ cp
static unsigned short crctab [256] = {
0x0000, 0x1021, 0x2042, 0x3063, 0x4048, 0x50a5, 0x60c6, 0x70e7,
0x8108, 0x9129, 0xa14a, 0xb16b, 0xc18c, 0xd1ad, 0xe1ce, 0xf1ef,
0x1231, 0x0210, 0x3273, 0x2252, 0x52b5, 0x4294, 0x72f7, 0x62d6,
0x9339, 0x8318, 0xb37b, 0xa35a, 0xd3bd, 0xc39c, 0xf3ff, 0xe3de,
0x2462, 0x3443, 0x0420, 0x1401, 0x64e6, 0x74c7, 0x44a4, 0x5485,
0xa56a, 0xb54b, 0x8528, 0x9509, 0xe5ee, 0xf5cf, 0xc5ac, 0xd58d,
0x3653, 0x2672, 0x1611, 0x0630, 0x76d7, 0x66f6, 0x5695, 0x46b4,
0xb75b, 0xa77a, 0x9719, 0x8738, 0xf7df, 0xe7fe, 0xd79d, 0xc7bc,
0x48c4, 0x58e5, 0x6886, 0x78a7, 0x0840, 0x1861, 0x2802, 0x3823,
0xc9cc, 0xd9ed, 0xe98e, 0xf9af, 0x8948, 0x9969, 0xa90a, 0xb92b,
0x5af5, 0x4ad4, 0x7ab7, 0x6a96, 0x1a71, 0x0a50, 0x3a33, 0x2a12,
0xdbfd, 0xcbdc, 0xfbbf, 0xeb9e, 0x9b79, 0x8b58, 0xbb3b, 0xab1a,
0x6ca6, 0x7c87, 0x4ce4, 0x5cc5, 0x2c22, 0x3c03, 0x0c60, 0x1c41,
0xedae, 0xfd8f, 0xcdec, 0xddcd, 0xad2a, 0xbd0b, 0x8d68, 0x9d49,
0x7e97, 0x6eb6, 0x5ed5, 0x4ef4, 0x3e13, 0x2e32, 0x1e51, 0x0e70,
0xff9f, 0xefbe, 0xdfdd, 0xcffc, 0xbf1b, 0xaf3a, 0x9f59, 0x8f78,
```

```
0x9188, 0x81a9, 0xb1ca, 0xaleb, 0xd10c, 0xc12d, 0xf14e, 0xe16f,  
0x1080, 0x00a1, 0x30c2, 0x20e3, 0x5004, 0x4025, 0x7046, 0x6067,  
0x83b9, 0x9398, 0xa3fb, 0xb3da, 0xc33d, 0xd31c, 0xe37f, 0xf35e,  
0x02b1, 0x1290, 0x22f3, 0x32d2, 0x4235, 0x5214, 0x6277, 0x7256,  
0xb5ea, 0xa5cb, 0x95a8, 0x8589, 0xf56e, 0xe54f, 0xd52c, 0xc50d,  
0x34e2, 0x24c3, 0x14a0, 0x0481, 0x7466, 0x6447, 0x5424, 0x4405,  
0xa7db, 0xb7fa, 0x8799, 0x97b8, 0xe75f, 0xf77e, 0xc71d, 0xd73c,  
0x26d3, 0x36f2, 0x0691, 0x16b0, 0x6657, 0x7676, 0x4615, 0x5634,  
0xd94c, 0xc96d, 0xf90e, 0xe92f, 0x99c8, 0x89e9, 0xb98a, 0xa9ab,  
0x5844, 0x4865, 0x7806, 0x6827, 0x18c0, 0x08e1, 0x3882, 0x28a3,  
0xcb7d, 0xdb5c, 0xeb3f, 0xfb1e, 0x8bf9, 0x9bd8, 0xabbb, 0xbb9a,  
0x4a75, 0x5a54, 0x6a37, 0x7a16, 0x0af1, 0x1ad0, 0x2ab3, 0x3a92,  
0xfd2e, 0xed0f, 0xdd6c, 0xcd4d, 0xbdaa, 0xad8b, 0x9de8, 0x8dc9,  
0x7c26, 0x6c07, 0x5c64, 0x4c45, 0x3ca2, 0x2c83, 0x1ce0, 0x0cc1,  
0xef1f, 0xff3e, 0xcf5d, 0xdf7c, 0xaf9b, 0xbfba, 0x8fd9, 0x9ff8,  
0x6e17, 0x7e36, 0x4e55, 0x5e74, 0x2e93, 0x3eb2, 0x0ed1, 0x1ef0,  
};
```

Example 4 shows an example of a function that creates the lookup table.

```
#include <stdio.h>  
  
#define MAX_CHAR      256  
#define BITS_CHAR    8  
#define SIGN_BIT     0x8000  
#define POLY         0x1021  
unsigned short crctab [MAX_CHAR];  
main ()  
{  
    unsigned short ch;  
    unsigned short workval;  
    unsigned short bit;  
    unsigned short carry;  
    for (ch = 0; ch != MAX_CHAR; ch++) {  
        workval = ch << BITS_CHAR;  
        for (bit = BITS_CHAR; bit != 0; bit--) {  
            carry = (workval & SIGN_BIT);  
            workval <<= 1;  
            if (carry)  
                workval ^= POLY;  
        }  
        crctab[ch] = workval;  
    }  
}
```

```

}
for (ch = 0; ch != MAX_CHAR; ch++)
printf("0x%04x\n", crctab[ch]);
}

```

## Manually Disabling ECP for Maintenance

---

Under certain conditions, communications between the host and Encompass 4/4800 Multiprotocol Reader may be lost temporarily and maintenance may be required. The reader or host is sending out a message and waiting for an acknowledgment. When the acknowledgment is not received, the message is sent again. Additional messages are also buffered. Often the first indication that the Encompass 4/4800 Multiprotocol Reader software is in an ECP “loop” is when the user/technician sees a recurring display of the same message repeated over and over again on the monitor. The procedure described in the following paragraphs enables the maintenance technician to change configuration or test tag reading manually.

Assuming that the ECP timeout is at the factory default of 12.7 seconds (or other value that allows enough time for the commands to be manually entered) the following command sequence may be used to break out of an ECP loop. This command sequence uses four ASCII <`> characters (60 hex) as wild card CRC values.

*Note: The ASCII <`> character (60 hex) is commonly located on the ~ key.*

You must acknowledge existing messages by issuing commands with the generic format:

```
#x@` `` ` <eom>
```

where

#	Start-of-message character
x	Message sequence number. This must be the same as the sequence number of the message being acknowledged
@	ACK (acknowledgment character)
<` `` ` >	Wild card CRC value for the message
<eom>	End-of-message character

The following is a typical sequence after power-on limiting buffered messages.

*Note: Ensure that no tags are in the field when you are performing this troubleshooting procedure.*



### Caution

*To avoid damage to the Encompass 4/4800 Multiprotocol Reader that uses an external antenna, ensure that you have connected the antenna or a dummy load to the reader before applying power to the reader.*

Reader transmission on power-up:

#0 Model ... SN <crc><eom>

Manually enter: #0@` `` `` <eom>

Reader transmission #2 Copyright 2003 TransCore <crc><eom>

Manually enter: #2@` `` `` <eom>

Manually enter: #101` `` `` <eom> this puts reader into command mode

Reader response: #1Done<crc><eom>

Manually enter: #3610` `` `` <eom> this puts reader into basic protocol, disabling ECP

reader response: Done

Enter any other desired diagnostic or directive commands in basic protocol. After maintenance is complete enter the command:

#00 to return the reader to data mode

or

#611 to return to error correcting protocol, and then either cycle power or issue #100` `` `` <eom> command to return reader to data mode



PRELIMINARY



# Chapter 7

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## Commands

***This chapter discusses the host-transmitted commands that are used to control the Encompass™ 4/4800 Multiprotocol Reader configuration and operation.***

### **Introduction**

---

The Encompass 4/4800 Multiprotocol Reader is delivered from the factory with specified default settings that determine how the reader operates. Commands transmitted by the host computer can change the default settings and control additional features. The commands can be transmitted by manually entering the commands at the host keyboard if the host is in terminal emulation mode. The Encompass 4/4800 Multiprotocol Reader can also communicate with ASCII terminals.

*Note: If you are using Wiegand mode, you must connect the PC or laptop to the Encompass 4/4800 Multiprotocol Reader using the RS-232 or RS-422 interface and a terminal emulation program to send commands to the reader. You can leave the Wiegand interface connected during this procedure.*

### **Operating Modes**

---

The Encompass 4/4800 Multiprotocol Reader has three modes of operation: data mode, command mode, and download mode. The software for the Encompass 4/4800 Multiprotocol Reader contains two separate programs — boot and application. The boot program has control of the Encompass 4/4800 Multiprotocol Reader on startup and when operating in download mode. The application program has control of the Encompass 4/4800 Multiprotocol Reader during data mode and command mode operation and holds the application code. Together, they control the Encompass 4/4800 Multiprotocol Reader in the three modes of operation.

---

#### **Data Mode**

The Encompass 4/4800 Multiprotocol Reader is in the data mode upon power-up. While in the data mode, the Encompass 4/4800 Multiprotocol Reader sends all communications as data messages, such as tag IDs and reports, to the host computer. Reports provide information on input status changes (input0 and input1), a presence without tag report, and buffer overflow information. The host computer can send only two commands to the Encompass 4/4800 Multiprotocol Reader while in data mode:

- Command #01 Switch To Command Mode changes the Encompass 4/4800 Multiprotocol Reader from the data mode to the command mode. See “01 Switch to Command Mode” on page 7-6.
- Command #05 Switch To Download Mode allows the host computer to download new software into the Encompass 4/4800 Multiprotocol Reader. See “05 Switch to Download Mode” on page 7-6.

*Note:* The Encompass 4/4800 Multiprotocol Reader transmits ID codes to the host computer when the Encompass 4/4800 Multiprotocol Reader is in data mode. If the Encompass 4/4800 Multiprotocol Reader remains in the command mode with tags passing through the read zone, all tag IDs are lost.

---

## **Command Mode**

While the Encompass 4/4800 Multiprotocol Reader is in the command mode, the host computer sends commands to the Encompass 4/4800 Multiprotocol Reader that can be used to control the operation and configuration of the reader. After the Encompass 4/4800 Multiprotocol Reader receives a command, it transmits a command response message. Typically, the command message contains Error, Done, or data relating specifically to the command request. These messages may be of variable length since some commands require information as part of the message; for example, Display Wiegand Mode Status.

Communications can be lost if the host computer attempts to send certain commands under marginal communications conditions. For example, if the host computer transmits the command request to change the baud rate and the Encompass 4/4800 Multiprotocol Reader properly receives the request and transmits the Done message, one of the two following conditions may occur:

- If the host computer receives the Done message, then both the host and the Encompass 4/4800 Multiprotocol Reader switch to the new baud rate, and communications are maintained.

*Note:* In many applications, the host must be set to the new baud rate as it will not change automatically.

*Note:* The Encompass 4/4800 Multiprotocol Reader changes the baud rate immediately after issuing the Done message.

- However, if the host does not receive the Done message transmitted by the Encompass 4/4800 Multiprotocol Reader, the host assumes that the command was not properly sent and does not switch to the new baud rate, causing a loss of communications.



### **Caution**

*The host computer should not attempt to change communications parameters or protocols during marginal communications conditions; otherwise, a loss of communications can result.*

---

## Download Mode

In download mode, the Encompass 4/4800 Multiprotocol Reader allows the host to download new software and supports a limited set of commands.

While in download mode, the reader communications port parameters are fixed at the following factory-default settings: 9600 baud, 8 data bits, 1 stop bit, no parity, software flow control (XON/XOFF), basic protocol.

While in download mode, the Encompass 4/4800 Multiprotocol Reader turns RF off, does not process tags, and does not echo host commands. See “90 Load Program Block” on page 7-46 through “99 Exit Download Mode” on page 7-47.

---

## Command List

Reader commands are divided into groups based on primary function. The following sections provide information about each command in command number order. Refer to Appendix D for listings of commands in numerical and alphabetical order.

*Some commands supported by TransCore’s AI1620 SmartPass readers are not available or have been changed for the Encompass 4/4800 Multiprotocol Reader.*

Other commands, such as command #644NN Set RF Attenuation and #6402 Enable Diagnostic RF Continuous Wave, have been added for the Encompass 4/4800 Multiprotocol Reader. Further, commands have been added that are supported only in later versions of the Encompass 4/4800 Multiprotocol Reader Software. These commands are indicated as follows:

- A single asterisk (\*) indicates that the command has been altered so that it is different from the AI1620 SmartPass command.
- A double asterisk (\*\*) indicates a new command or added value that is not present in the AI1620 SmartPass command list.
- A triple asterisk (\*\*\*) indicates an Encompass 4/4800 Multiprotocol Reader command that is supported only in later versions of the Encompass 4/4800 Multiprotocol Reader Software. Commands so indicated have explanatory notes.

The Encompass 4/4800 Multiprotocol Reader System does not include a real-time clock. The dual-protocol Encompass 4/4800 Multiprotocol Reader internal timing varies depending on the operative tag read mode and the type of tag in the read field. Unless stated otherwise, values listed for timing-related command variables assume an ID operational mode (64-bit ID data from eGo tags, ignoring ATA tags) and an eGo-compatible tag in the read field and these values may vary.

In the following text, the symbols < and > represent variable message data. These symbols are not part of the message syntax.

Hex digits (0–9, A–F) in either uppercase or lowercase characters may be used in data strings and for hex digits A–F.

---

## **Reader Mode Control — Command Group 0**

Group 0 commands control reader mode. The mode determines whether the reader is transmitting data to or receiving data from a host computer or terminal.

### **00 Switch to Data Mode (Factory Default)**

Command #00 switches the reader to data mode, which allows the reader to transmit tag data (ID codes) to the host. The reader enters data mode on power up.

While operating in data mode, the reader accepts the following commands:

- Command #01 Switch to Command Mode
- Command #05 Switch to Download Mode

Reader response:

Done

### **01 Switch to Command Mode**

Command #01 switches the reader to command mode, which allows the reader to accept commands from a host or terminal. While in command mode, the reader turns RF off and does not acquire tags.

Reader response:

Done

### **05 Switch to Download Mode**

Command #05 switches the reader to download mode, which allows an external host computer to download new software into the reader flash memory.

While operating in download mode, the reader accepts a limited set of commands: #90 Load Program Block, #91 Verify Flash Checksum, #96 Erase Flash Memory, #97 Perform Destructive Memory Test, and #99 Exit Download Mode.

To exit the download mode, the host must transmit command #99 Exit Download Mode. The reader re-executes startup to ensure proper initialization of operating parameters and to verify the boot ROM and flash memory checksum values. The reader does not accept the command #05 Switch To Download Mode if it is operating in data mode; it must first be switched to command mode (command #01).

Reader response:

Done or Error

## Communications Port Control — Command Group 1

Group 1 commands configure the parameters used by the Encompass 4/4800 Multiprotocol Reader to communicate with a host computer or terminal. These commands set baud rate, stop bits, parity, and end-of-line delay.

### 100N Select Baud Rate\*

Command #100N selects the reader baud rate. The factory-default setting is 9600 baud. The N variable specifies the baud rate shown in [Table 7-1](#).

**Table 7-1 Select Baud Rate Commands**

Command	Baud Rate Selected
1002*** (supported only in Encompass 4/4800 Multiprotocol Software Version TBD)	1200***
1003	2400
1004	4800
<b>1005</b>	9600 (factory default)
1006	19.2 K
1007**	38.4 K**



### Caution

*If ECP is enabled, ensure that the ECP timeout is sufficient for the new baud rate. See “Timing and Synchronization” on page 6-11.*

Reader response:

Done or Error

### 101N Select Stop Bits

Command #101N selects the number of stop bits for reader character transmission. The factory default setting is 1 stop bit. The N variable specifies the number of stop bits as indicated in [Table 7-2](#).

**Table 7-2 Select Stop Bits Commands**

Command	Stop Bits Selected
<b>1010</b>	1 (factory default)
1011	2

Reader response:

Done

### 102N Select Parity

Command #102N selects the reader parity setting. The factory-default setting is parity disabled. The N variable specifies parity as shown in [Table 7-3](#).

**Table 7-3 Select Parity Commands**

Command	Data Bits	Parity Selected
1020	8	Disable parity (factory default)
1021	7	Select even parity
1022	7	Select odd parity

Reader response:

Done

---

## Command Group 2

Group 2 commands control the real-time clock which maintains the SmartPass internal time and date. This time and date can be appended to IDs, error messages, and sensor input reports. An internal battery supports the clock, so time and date are preserved if main power is lost.

### 20 Set Time

Command 20 sets the time. Enter the time in the proper format: two-digit decimal entries with no spaces between characters and using colons as delimiters. The entry format is as follows:

*20HH:MM:SS or 20HH:MM:SS:hh*

where:

*HH* represents hours (00 to 23).

*MM* represents minutes (00 to 59).

*SS* represents seconds (00 to 59).

*hh* represents hundredths of a second (00 to 99).

*:* is the time delimiter.

If hundredths of a second are not specified, the reader sets the hundredths register to 00.

Reader message:

*Done or Error*



## 21 Set Date

Command 21 sets the date. Enter the date in the proper format: two-digit decimal entries with no spaces between characters and using forward slashes “/” as delimiters. The entry format is as follows:

*21MM/DD/YY*

where:

*MM* represents the month (01 to 12).

*DD* represents the day (01 to 31).

*YY* represents the last two digits of the year (00 to 99).

*/* is the date delimiter.

Reader message:

*Done or Error*

## 22 Display Time and Date

Command 22 displays the reader’s current time and date. One space separates the time and the date output.

Reader message:

*HH:MM:SS.hh MM/DD/YY*

where:

*HH* represents hours.

*MM* represents minutes.

*SS* represents seconds.

*hh* represents hundredths of seconds.

*:* is the time delimiter.

*MM* represents the month.

*DD* represents the day.

*YY* represents the last two digits of the year.

*/* is the date delimiter.

---

## Append Information — Command Group 3

Group 3 commands append useful information to reader transmissions, such as IDs, error messages, and sensor input reports. Auxiliary information such as reader number, antenna number (or manual entry code), number of times the previous tag was read, and sensor input status can be appended to the ID using the Group 3 commands.

### 30N Append Time and Date Selection

This command selects the option of appending the time and date to transmitted IDs, error messages, presence without tag reports, and input status change reports. The factory default setting is time and date appended (command 302).

The reader returns an *Error* message if its tag buffer contains data. The reset reader command 63 may be transmitted to clear the buffer; however, tag ID data will be lost. If this is unacceptable, allow the buffer to empty before re-issuing append time and date command 30N. Append Time and Date commands are shown in [Table 7-4](#)

**Table 7-4 Append Time and Date Commands**

Command	Append Option
300	No time and date appended
<b>302</b>	Time and date appended (factory default)

The reader transmits messages with time and date appended as follows. One space separates the time from the date.

`<string>&<HH:MM:SS.hh MM/DD/YY>`

where:

*string* is a tag ID, error message, or report.

& separates *<string>* from the time and date.

*HH:MM:SS* is the time delimiter.

*MM/DD/YY* is the date delimiter.

Reader response:

Done or Error

### 31N Append Auxiliary Information Selection

The command #31N selects the option of appending auxiliary information to transmitted IDs, presence-without-tag reports, and input status change reports. Auxiliary information is not appended to error messages. The factory-default setting is no auxiliary information appended. The N variable specifies whether or not auxiliary information is to be appended. Append Auxiliary Information commands are shown in [Table 7-5](#).

**Table 7-5 Append Auxiliary Information Commands**

Command	Append Option
<b>310</b>	No auxiliary information appended (factory default)
311	Auxiliary information appended

The reader transmits messages with auxiliary information appended as:

```
<message data>%<xx-y-zz-q>
```

where

%	Separates the auxiliary information and signals the host computer that auxiliary information is appended.
xx	Reader ID. Value can be set with command #60NN.
-	Auxiliary information delimiter
y	Antenna number. Value fixed at 0.
zz	Number of reads (00 to FF hexadecimal) of the previous tag
q	Current status of input0 and input1 (0 to 3). Refer to <a href="#">“526 Display I/O Status” on page 7-20</a> . These values are inverted if input inversion is enabled with command 6941.

Reader response:

```
Done or Error
```

## **ID Filtering — Command Group 4**

Group 4 commands set criteria for filtering (buffering or discarding) ID codes. These commands are useful for eliminating duplicate ID codes and selecting the type of tags read by the Encompass 4/4800 Multiprotocol Reader.

### **40 Transmit All ID Codes**

Command #40 instructs the reader to transmit all IDs without regard for uniqueness. This command can be useful when tuning the lane and mapping the footprint or performing diagnostics.

After diagnostics are complete, you may want to reinstate the uniqueness check using command #410N Select Unique ID Code Criteria.

Reader response:

```
Done or Error
```

### **410N Select Unique ID Code Criteria (Anti-passback Feature)**

Command #410N instructs the reader to buffer and transmit ID codes according to the following test: an ID is read if previously decoded IDs have changed value at least N+1 times since the new ID was last received. IDs that do not pass the test are not read. The factory-default setting is command #4100, which selects a separation of one ID. Variable N specifies ID separation as shown in [Table 7-6](#).

**Table 7-6 Unique ID Code Criteria**

Command	Uniqueness Criteria
<b>4100</b>	Separation of 1 ID (factory default)
4101	Separation of 2 IDs

Each time the reader receives a tag ID, it compares the ID with the contents of a comparison register. This register contains the following two items:

- Item 1           Most recently acquired ID
- Item 2           Second-most recently acquired ID (if different from item 1)

When the uniqueness filter is set to a separation of one ID, the newly acquired ID is transmitted only if it is different from item 1. When the uniqueness filter is set to a separation of two IDs, the reader transmits the newly acquired ID only if it is different from both items 1 and 2.

*Note: A new ID can fail the filter test and not be transmitted; however, it remains stored in the comparison register.*

The uniqueness test has a two-minute time limit. If an ID is buffered, it will not be accepted again unless it arrives at the reader more than two minutes from the previous arrival or until the receipt of one or more other IDs reset the uniqueness.

*Note: The Encompass 4/4800 Multiprotocol Reader System does not include a real-time clock. The dual-protocol Encompass 4/4800 Multiprotocol Reader internal timing varies depending on the operative tag read mode and the type of tag in the read field.*

Reader response:

Done

### **43 Buffer All ID Codes**

Command 43 buffers all acquired ID codes. It effectively cancels any uniqueness criteria previously set by select unique ID code criteria command 410N.

*Note: Command 43 is for diagnostic purposes only.*

After diagnostics are complete, reset the select unique ID code criteria using command 410N.

Reader response:

Done

**450 Disable Wiegand Mode (Factory Default)**

Command #450 is a default set in the factory to disable Wiegand mode.

Reader response:

Done

**451 Enable Wiegand Mode**

Command #451 enables Wiegand mode, which allows the reader to transmit data in a format that emulates the output of a magnetic card reader.

In Wiegand mode, the reader transmits Wiegand-formatted tag data through the Wiegand interface and ASCII data (the reader accepts reader commands and responds) through the serial port interface. The reader outputs data from Wiegand-programmed tags via the Wiegand interface (the red/blue pair for data1/data0; yellow/black pair for logic ground). Tags that are not Wiegand-formatted are not transmitted through the Wiegand interface or the serial port when in Wiegand mode, although the tag lock relay is activated on any tag acquired.

Reader response:

Done or Error

**452 Disable Tag Translation Mode (Factory Default)**

Command 452 disables tag translation mode. Incoming full-frame tags will be directly converted to ASCII. They will not be translated from Association of American Railroads (AAR) and American Trucking Associations (ATA) format to ASCII.

Reader response:

Done

**453 Enable Tag Translation Mode**

Command 453 enables the translation of tags in AAR and ATA formats. Specific data fields, such as owner ID and car number, will be extracted from these tags, translated according to AAR or ATA standards, and converted to ASCII. Tags that are not programmed in AAR or ATA format will be directly converted to ASCII. The reader will not attempt to translate data from half-frame or dual-frame tags.

Reader response:

Done

**454 Disable Multi-tag Sort (Factory Default)**

Command #454 is a default set in the factory to disable the multi-tag sort function.

Reader response:

Done

### **455 Enable Multi-tag Sort**

Command #455 enables the multi-tag sort function that allows the reader to identify unique tags within a group of Intellitag-based tags. Multi-tag sort allows full operation of the tags and reader to be carried out with any number of tags in the presence of the reader.

Reader response:

Done or Error

*Note: Enabling the multi-tag sort function adversely affects the vehicle speed at which tags may be read. If there is only one Intellitag-based tag in the vehicles of the target population, multi-tag sort should be disabled.*

### **456 Enable eGo Tag Initialization During Multi-tag Sort (Factory Default)**

Command #456 enables the reader to send the eGo tag initialize command as part of the multi-tag sort function. When the reader sends the eGo tag initialize command, all tags in the RF field reenter the sort process.

Reader response:

Done or Error

### **457 Disable eGo Tag Initialization During Multi-tag Sort**

Command #457 disables the reader from sending the eGo tag initialize command as part of the multi-tag sort function. Any eGo tags already identified by the reader during the sort process will not be re-identified as long as they remain powered in the RF field. The reader will only identify new tags that come into the RF field or tags that do not remain powered in the RF field.

Reader response:

Done

### **458 Disable Second Alternate Group Select (Factory Default)**

Command #458 is a default set in the factory to disable the second alternate group select function.

Reader response:

Done

### **459 Enable Second Alternate Group Select**

Command #459 enables the second alternate group select function that allows the reader to distinguish tags meeting specific criteria pre-programmed into the tags.



#### **Caution**

*When second alternate group select is enabled, tags not programmed to meet the specified criteria will not be read.*

Reader response:

Done or Error

### 46NN Set Wiegand Retransmit Interval

Command #46NN sets the time delay to control the reader retransmission of Wiegand data of a tag remaining in the read zone where NN is a hexadecimal code from 01 to FF.

*Note: The actual value of the Wiegand retransmit interval may vary depending on the operative tag read mode and the type of tag in the read field.*

For example, 10 = 16 seconds and FF = 255 seconds. The factory default is 4601 (1 second). The timing in ATA tag read mode is approximately twice these values.

Uppercase or lowercase characters are allowed for NN; for example, hex digits A through F or a through f.

Reader response:

Done or Error

### 47N Select Tag Mode\*\*

Command #47N selects the eGo ATA (eATA) or ATA tag read mode for the Encompass 4/4800 Multiprotocol Reader. The N variable specifies eATA/ATA tag read mode as indicated in [Table 7-7](#).

**Table 7-7 Tag Read Mode Commands**

Command	Operational Mode	Tags Read
470	Dual (1)	Read eATA data from Intellitag-based tags and read ATA tags.
471	ATA	Read ATA data from ATA tags.
472	ID	Read 64-bit ID data from Intellitag-based tags and ignore ATA tags.
473	IATA	Read eATA data from Intellitag-based tags and ignore ATA tags.
474	Dual (2)	Read 64-bit ID data from Intellitag-based tags and read ATA data from ATA tags.
477	ID - No EAC check	Reads the 64-bit ID data from all Intellitag-based tags regardless of the factory programming of the embedded application code (EAC) in tag memory bytes 10 through 17.



**Caution**

*Dual tag read operation should only be used in applications where vehicles come to a complete stop or are controlled to a very low speed.*

Reader response:

Done or Error

#### **490 Disable Third Alternate Group Select (Factory Default)**

Command #490 is a default set in the factory to disable the third alternate group select function.

Reader response:

Done

#### **491 Enable Third Alternate Group Select**

Command #491 enables the third alternate group select function that allows the reader to distinguish tags meeting specific criteria pre-programmed into the tags.



#### **Caution**

*When third alternate group select is enabled, tags not programmed to meet the specified criteria will not be read.*

Reader response:

Done or Error

#### **492 Disable Fourth Alternate Group Select (Factory Default)**

Command #492 is a default set in the factory to disable the fourth alternate group select function.

Reader response:

Done

#### **493 Enable Fourth Alternate Group Select**

Command #493 enables the fourth alternate group select function that allows the reader to distinguish tags meeting specific criteria pre-programmed into the tags.



#### **Caution**

*When fourth alternate group select is enabled, tags not programmed to meet the specified criteria will not be read.*

Reader response:

Done or Error

#### **494 Disable Fifth Alternate Group Select (Factory Default)**

Command #494 is a default set in the factory to disable the fifth alternate group select function.

Reader response:

Done



### **495 Enable Fifth Alternate Group Select**

Command #495 enables the fifth alternate group select function that allows the reader to distinguish tags meeting specific criteria pre-programmed into the tags.



#### **Caution**

*When fifth alternate group select is enabled, tags not programmed to meet the specified criteria will not be read.*

Reader response:

Done or Error

### **495 Disable Alternate Group Select (Factory Default)**

Command #496 disables the alternate group select function that allows the reader to distinguish tags meeting specific criteria pre-programmed into the tags.

Reader response:

Done or Error

### **497 Enable Alternate Group Select**

Command #497 enables the alternate group select function that allows the reader to distinguish tags meeting specific criteria pre-programmed into the tags.

Reader response:

Done or Error

## **Reader Status — Command Group 5**

Group 5 commands provide status reports on the parameters and operation of the reader.

### **505 Display Software Version**

Command #505 displays the reader model number, software version information, and assigned serial number.

Reader response:

Model E4 TBD Series Ver X.XX SNYYYYYY

where

X.XX                      Version number

YYYYYY                      Serial number of the unit, skipping the fourth character printed on the reader product label

### **506 Display Hardware Configuration Information**

Command #506 displays hardware configuration information stored in the reader memory by the user. Hardware configuration information is empty by default until you set the information to any 20 character ASCII string desired using command #696S...S.

Reader response:

*An ASCII string from 1 to 20 characters in length*

### **520 Display Power Fail Bit**

Command #520 displays the value of the reader power fail bit. The power fail bit changes from 0 to 1 when power to the reader is interrupted. To reset the bit, use command #63 Reset Reader or command #65 Reset Power Fail Bit. On initial power-up, the host should transmit one of these two commands to clear the power fail bit.

Reader response:

PWRB P<0 to 1>R0

where

P0	No power failure detected
P1	Power failure detected
R0	Not applicable to Encompass 4/4800 Multiprotocol Reader

### **521 Display Reader ID Number**

Command #521 displays the reader ID that is sent in the auxiliary data field.

Reader response:

RDID xx

where xx = 01 to FF (hexadecimal)

### **522 Display Communications Port Parameters**

Command #522 displays the selected communications port parameters, including the baud rate (#100N), the number of stop bits (#101N), the parity scheme (#102N), and the end-of-line delay.

Reader response:

MAIN B<3 to 7> S<0 to 1> P<0 to 2> D0

where

B3	2400 baud
B4	4800 baud
B5	9600 baud (factory default)
B6	19.2 kbps

B7**	38.4 kbps
S0	one stop bit (factory default)
S1	two stop bits
P0	no parity (factory default)
P1	even parity
P2	odd parity
D0	00 ms end-of-line delay (fixed)

One space is required between each value. For example, if factory default settings are assigned, the reader message is

```
MAIN B5 S0 P0 D0
```

indicating 9600 baud, one stop bit, no parity, and 0 ms end-of-line delay.

*Note: The information transmitted in response to command #522 applies to data and command mode operation only. While operating in download mode, default communications parameters are always used.*

#### **524 Display Appended Information Status\***

Command #524 displays the information being appended to the reader transmissions. Command #31N appends information. Append time and date are not available to the Encompass 4/4800 Multiprotocol Reader.

Reader response:

```
IDAP T<0> D<0> X<0 to 1>
```

where

T0	Time not appended
T1*	Time appended (not valid for the Encompass 4/4800 Multiprotocol Reader )
D0	Date not appended
D1*	Date appended (not valid for the Encompass 4/4800 Multiprotocol Reader )
X0	Auxiliary information not appended (factory default)
X1	Auxiliary information appended

One space is required between each value. For example, if factory-default settings are assigned, the reader response is

```
IDAP T0 D0 X0
```

indicating time\*, date\*, and auxiliary information not appended.

*Note:* Auxiliary information may only be appended to ID codes, presence without tag reports, and input change reports.

### **525 Display Communications Protocol Status\***

Command #525 displays the status of command #61N Selected Communications Protocol, command #614N Selected Mode of Flow Control, and command #612NN ECP Timeout.

Reader response:

```
ECPS P<0 to 1> T<01 to FF> X<0 to 2> S0
```

where

P0	Basic protocol enabled (factory default)
P1	ECP enabled
Txx	ECP timeout where xx = 01 to FE (hexadecimal) Timeout (ms) = 50 * xx If xx = FF timeout disabled
X0	Flow control disabled
X1	Software flow control enabled (factory default)
X2	Hardware flow control enabled
S0	start of message character is #

For example, if factory default settings are assigned, the reader message is:

```
ECPS P0 TFE X1 S0
```

which means basic protocol enabled, an ECP timeout of 254 (12,700 ms, 12.7 sec), software flow control enabled, and start of message character is #.

### **526 Display I/O Status**

Command #526 displays the current input/output status. The reader message indicates whether outputs are being controlled externally by the host through command #620N Output Control or internally through command #621 Predefined Output Mode. It also displays the current status of two outputs, two inputs, and the selected output pulse duration that is set by command #67N.

*Note:* The value of the output pulse duration varies depending on the operative tag read mode and the type of tag in the read field. All times are approximate.

Reader response:

IOST C<0 to 1> O<0 to 3> I<0 to 3> D<0 to F>

where

C0	Host controls outputs
C1	Predefined output mode
O0	Both outputs off
O1	Output0 on
O2	Output1 on
O3	Both outputs on
I0	Both inputs false
I1	Input0 true
I2	Input1 true
I3	Both inputs true
D0 to D8	48 ms (ID, IATA, Dual 1, and Dual 2 modes) output pulse duration; 130 ms (ATA single mode) output pulse duration
D9	60 ms (ID, eATA, Dual 1, and Dual 2 modes) output pulse duration; 140 ms (ATA single mode) output pulse duration
DA	76 ms (ID, eATA, Dual 1, and Dual 2 modes) output pulse duration; 190 ms (ATA single mode) output pulse duration
DB	152 ms (ID, eATA, Dual 1, and Dual 2 modes) output pulse duration; 300 ms (ATA single mode) output pulse duration
DC	228 ms (ID, eATA, Dual 1, and Dual 2 modes) output pulse duration (factory default); 450 ms (ATA single mode) output pulse duration
DD	300 ms (ID, eATA, Dual 1, and Dual 2 modes) output pulse duration; 550 ms (ATA single mode) output pulse duration

DE	376 ms (ID, eATA, Dual 1, and Dual 2 modes) output pulse duration; 700 ms (ATA single mode) output pulse duration
DF	752 ms (ID, eATA, Dual 1, and Dual 2 modes) output pulse duration; 1300ms (ATA single mode) output pulse duration

**Note:** The first character of the output pulse duration value is alpha; the second character is numeric.

Table 7-8 shows the output0 and output1 open/closed conditions for the output status displays.

**Table 7-8 Open/Closed Conditions for Output Status**

Output Status	Output0 Wire Pair		Output1 Wire Pair	
	Orange/Black	Brown/Black	White/Black	Green/Black
O0	Closed	Open	Closed	Open
O1	Open	Closed	Closed	Open
O2	Closed	Open	Open	Closed
O3	Open	Closed	Open	Closed

Table 7-9 shows the input0 and input1 open/closed conditions for the input status displays.

**Table 7-9 Open/Closed Conditions for Input Status**

Input Status	Input0 Wire Pair	Input1 Wire Pair
	Green/Red	Blue/Black
I0	Open	Open
I1	Closed	Open
I2	Open	Closed
I3	Closed	Closed

### 527 Display RF Status\*\*

Command #527 displays the current status of the RF module. The reader response indicates whether RF is controlled externally by the host, set by command #640N RF Control, or internally by input set by command #641. Command #527 also displays the current RF status and the uniqueness timeout, which is fixed at two minutes.

*Note: The fixed uniqueness timeout period of two minutes may vary slightly depending on the operative tag read mode and the tag in the read field.*

Reader response:

```
RFST C<0 to 1> O<0 to 1> T1 Fx Rxx Gxx Axx
```

where

C0	RF controlled by host
C1	RF controlled by presence sensor on input0, the red/green pair (factory default)
O0	RF off
O1	RF on
T1	Uniqueness timeout of two minutes (fixed)
Fxx	RF output frequency, xx = 00 to 34 hexadecimal offset in 500 kHz from 902 MHz. If an invalid frequency value is stored (corrupted NVRAM), then xx = "XX" to indicate an error in the frequency setting.
Rxx	Tag decoder range (distance) for ATA tags, xx = 00 to 1F hexadecimal range value
Gxx**	Tag decoder range (distance) for Intellitag tags, xx = 00 to 1F hexadecimal range value
Axx**	RF power attenuation, where 00 is maximum output power and 0A is minimum output power (10dB less than maximum power).

For example, if factory default settings are assigned, the reader message is:

```
RFST C1 O0 T1 F1A R1F G1F A00
```

which means that RF is enabled by presence sensor on input0, RF signal off, and uniqueness timeout of two minutes, RF output frequency of 915 MHz, maximum RF output range for ATA tags, maximum RF output range for Intellitag tags, and full RF power.

### **529 Display Presence Input Status**

Command #529 displays the parameters associated with presence detection and RF control. The reader's message indicates if presence without tag reports are enabled/disabled (#690N Select Presence without Tag Report Option), if input inversion is enabled/disabled (#694N Select Input Inversion Option), and the minimum presence true period (always true). The reader's message also reports the selected RF timeout (#693N Select RF Timeout Period) and the selected means of RF-off control (#692N

Select RF Control Algorithm). If presence without tag reports is enabled (#6901 Enable Presence without Tag Reports), the reader transmits a report if a presence is detected without the subsequent acquisition of a valid tag.

*Note: RF timeout values vary depending on the operative tag read mode and the type of tag in the read field. All times are approximate.*

Reader response:

PRST P<0 to 1> D0 A<0 to 2> T<0 to F> I<0 to 1>

where

P0	Presence without tag reports disabled (factory default)
P1	Presence without tag reports enabled
D0	Minimum presence true period of 0 ms (fixed)
A0	RF off on timeout only
A1	RF off on timeout or tag
A2	RF off on timeout or presence condition false (factory default)
T0	RF timeout of 0 ms (always expired)
T1 to T7	RF timeout of 48 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 150 ms (ATA single mode)
T8	RF timeout of 60 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 175 ms (ATA single mode)
T9	RF timeout of 92 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 200 ms (ATA single mode)
TA	RF timeout of 152 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 370 ms (ATA single mode)
TB	RF timeout of 300 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 680 ms (ATA single mode)
TC	RF timeout of 452 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 1000 ms (ATA single mode)
TD	RF timeout of 600 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 1250 ms (ATA single mode)
TE	RF timeout of 752 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 1500 ms (ATA single mode)



TF	RF timeout infinite, never expires (factory default)
I0	input inversion disabled (factory default)
I1	input inversion enabled

For example, if factory default settings are assigned, the reader message is

```
PRST P0 D0 A2 TF I0
```

which means that presence without tag reports is disabled, minimum presence true period is 0, RF off control on timeout or presence false, infinite RF timeout, and input inversion disabled.

### **530 Display RF0 Filter Status\***

Command #530 displays the parameter set for the RF channel input, including the selected unique ID code criteria (#410N Select Unique ID Code Criteria) and the valid ID code criteria, which are fixed at one acquisition.

Reader response:

```
RF0S U<0 to 2> V0
```

where

U0	One ID separation (factory default)
U1	Two ID separations
U2	Transmit all IDs
V0	Valid ID code criteria of one acquisition (fixed)

For example, if factory default settings are assigned, the reader message is

```
RF0S U0 V0
```

which means separation of one ID for uniqueness filtering and a valid ID code criteria of one acquisition.

### **532 Display Wiegand Mode Status**

Command #532 displays the Wiegand mode status as either enabled or disabled.

Reader response:

```
TOF <0 to 1>
```

where

0	Wiegand mode disabled
1	Wiegand mode enabled

### 533 Display Wiegand Retransmit Interval

Command #533 displays the Wiegand retransmit interval. This interval specifies the delay in seconds before the reader retransmits Wiegand data for a tag still in the read zone. The factory default is 1 second.

Reader response:

WTI <01 to FF>

where 01 to FF = seconds (1–255) in hexadecimal.

*Note:* The actual value of the Wiegand retransmit interval may vary depending on the operative tag read mode and the type of tag in the read field.

For example, 10 = 16 seconds and FF = 255 seconds. The retransmit interval in ATA tag read mode is about twice these values.

### 534 Display Tag Translation Mode Status

Command 534 displays tag translation mode status, enabled or disabled. If tag translation mode is enabled, incoming full-frame tags in AAR or ATA format are translated according to ISO standards. Refer to [“452 Disable Tag Translation Mode \(Factory Default\)” on page 7-13](#) and [“453 Enable Tag Translation Mode” on page 7-13](#) for more information.

Reader message:

TT <0 to 1>

where:

0 tag translation mode disabled  
1 tag translation mode enabled

### 535 Display Buffer Control Status

Command 535 displays buffer control mode status, enabled or disabled. Refer to [“6160 Disable Buffer Control Mode \(Factory Default\)” on page 7-31](#) and [“6161 Enable Buffer Control Mode” on page 7-31](#) for more information.

Reader message:

BCM <0 to 1>

where:

0 buffer control mode disabled  
1 buffer control mode enabled

### 537 Display Echo Status

Command #537 displays echo mode status. In basic protocol (#610 Select Basic Protocol), the reader may be configured to enable (#6171 Enable Echo Mode) or disable (#6170 Disable Echo Mode) the echo of received commands. Refer to sections [“6170 Disable Echo Mode”](#) and [“6171 Enable Echo Mode \(Factory Default\)” on page 7-33](#) for more information.

Reader response:

ECHO <0 to 1>

where

0 Echo status disabled (factory default)

1 Echo status enabled

### **540 Display Flash Checksum**

Command #540 displays the flash memory checksum.

Reader response:

PCKS I0000 Exxxx

where

0000 Not applicable to the Encompass 4/4800 Multiprotocol Reader

xxxx Represents the four-byte ASCII representation of the flash memory checksum

### **543 Display Boot Checksum**

Command #543 displays the boot ROM checksum.

Reader response:

BCKS xxxx

where xxxx represents the four-byte ASCII representation of the boot ROM checksum.

### **560 Request Sensor Status Change**

Command #560 displays the sensor status change reporting. Status change reporting may be disabled by command #82N Select Input Status Change Report Option.

Reader response:

SSTC E<0 to 1>M<0 to 3>

where

E0 Input status change reports disabled (factory default)

E1 Input status change reports enabled

M0 Reporting disabled (factory default)

M1 Changes on input0 reported

M2 Changes on input1 reported

M3 Changes on either input reported

For example, if factory default settings are assigned, the reader message is

```
SSTC E0 M0
```

which means that input status change reports are disabled on both input0 and input1.

### **570 Display Tag Mode Status\*\***

Command #570 displays the currently selected tag read mode.

Reader response:

```
IT500:<I, F, D, or NI> ATA:<E or D>
```

where

I	IT500 ID (64 bits)
E	Enabled
F	Full transaction
D	Disabled
M	Multi-tag sort enabled
NI	No EAC check

[Table 7-10](#) shows reader command #47N Select Tag Mode, corresponding tag modes, and data read in each mode, when multi-tag sort is disabled.

**Table 7-10 Tag Read Mode Status**

Reader Command	Tag Read Mode Status	Tags Read
470	IT500:F ATA:E	Read eATA data from Intellitag and read ATA tags.
471	IT500:D ATA:E	Read ATA data from ATA tags.
472	IT500:I ATA:D	Read 64 bit ID data from Intellitag ignore ATA tags.
473 (default)	IT500:F ATA:D	Read eATA data from Intellitag ignore ATA tags.
474	IT500:I ATA:E	Read 64 bit ID data from Intellitag and read ATA tags.
477	IT500:NI ATA:D	Reads the 64-bit ID data from all Intellitag-based tags regardless of the factory programming of the embedded application code (EAC) in tag memory bytes 10 through 17.

## **Reader Control Functions — Command Group 6**

Group 6 commands set reader control functions such as reader ID, communication protocol, output pulse, and RF control.

### **60NN Set Reader ID Number**

Command #60NN sets the reader ID that will be sent in the auxiliary data field (command #311). Uppercase or lowercase characters are allowed for NN; for example, hex digits A through F or a through f

where NN = 00 to FF (hex for 0 to 255, factory default = 00).

Reader response:

Done

### **610 Enable Basic Communication Protocol (Factory Default)**

Command #610 enables the basic communications protocol. Refer to [“Basic Protocol” on page 6-4](#) for more information.

Reader response:

Done or Error

### **611 Enable Error Correcting Protocol**

Command 611 enables the error correcting protocol. Refer to [“Error Correcting Protocol” on page 6-4](#) for more information.

Reader response:

Done



**Caution**

*Do not switch to ECP (command #611 Select Error Correcting Protocol) unless the host is prepared to acknowledge each reader transmission.*

**612NN Select Error Correcting Protocol Timeout**

Command #612NN selects the timeout interval for ECP. This timeout applies to the transmission of tag, report, and error messages and to the receipt of host commands. The transmit timeout is initiated immediately after the end-of-message sequence CR/LF is transmitted. If the host does not acknowledge the message within the specified interval, the reader times out and retransmits the message.

The receive timeout is initiated upon receipt of the start-of-message character (#). If the end-of-message character (CR) is not received within the specified interval, the reader discards the partially received message and resets its receiver.

Uppercase or lowercase characters are allowed for NN; for example, hex digits A through F or a through f.

The value for NN specifies the timeout interval as follows:

ms                    50 \* NN for NN = 01 to FE (1–254)

**FE**                    Factory default (12,700 ms, 12.7 seconds)

**FF**                    Disables the ECP timeout

*Note: The actual value of the ECP timeout may vary depending on the operative tag read mode and the type of tag in the read field.*

Reader response:

Done or Error



**Caution**

*Ensure that the ECP timeout is sufficient for a given baud rate. See “Timing and Synchronization” on page 6-11.*

**613 Enable Data Inquiry Protocol**

Command 613 enable the data inquiry protocol. Reader message:

Done or Error

**614N Select Flow Control Option**

Command #614N selects the flow control option for reader-to-host communications. The factory default setting is software flow control (XON/XOFF) enabled. In download mode, flow control is not host-selectable; it is fixed at the default setting. However, during data mode and command mode operation, the following flow control options are available. The N variable specifies flow control as shown in [Table 7-11](#).

**Table 7-11 Flow Control Commands**

Command	Flow Control Option
6140	Disable flow control
6141	Enable software flow control (factory default)
6142	Enable hardware flow control

Reader response:

Done

If the reader is configured for software flow control (XON/XOFF), it stops transmitting if it receives an XOFF character (host software command 13H). It does not resume transmitting until it receives an XON character (host software command 11H). If the reader is configured for hardware flow control (RTS/CTS, request to send/clear to send), it stops transmission if it detects that the CTS line is no longer asserted. It resumes transmission when this line is asserted again.

*Note: TransCore recommends that XON/XOFF flow control be disabled while using the ECP.*

**6160 Disable Buffer Control Mode (Factory Default)**

Command 6160 is used to disable buffer control. Buffer control is an ECP option that prevents unsolicited (asynchronous) reader transmissions. If buffer control is not active, the reader transmits data to the host as soon as the data is acquired. The host must acknowledge the data according to the ECP acknowledgment/negative acknowledgment (ACK/NAK) protocol. Refer to command 6161 for more information.

Reader message:

Done

**6161 Enable Buffer Control Mode**

Command 6161 is used to enable buffer control. Buffer control is an ECP option that prevents asynchronous reader transmissions. When buffer control is enabled using command 6161, the reader transmits only in response to command 06, transmit buffer entry. The exception to this rule occurs on startup when the reader transmits its two-line sign-on message asynchronously.

The following commands are used for buffer control:

Number	Command Description	Message
06	Transmit buffer entry	Done, error, or <message>
535	Display buffer control status where x= 0 for disabled 1 for enabled	BCM x
6160	Disable buffer control mode (default)	Done
6161	Enable buffer control mode	Done

If BCM is enabled, the host must request tag IDs and reports from the reader using the transmit buffer entry command 06. If the reader receives this command and it has data in its buffer, it will transmit the buffered message of highest priority (tag IDs first and then reports). If the reader's buffer is empty, it will transmit the *Done* message instead. The reader will return an *Error* message if it receives command 06 when BCM is not enabled.

If buffer control is enabled, the reader will not support *ECP ACK* or *NAK* messages from the host. Since all messages are transmitted in response to a host command, acknowledgment from the host is not required. Instead, the ECP sequence numbers are used to ensure data integrity. If the host receives an erroneous reader message, it should retransmit command 06, transmit buffer entry, with the same sequence number. This will cause the reader to search and replace its previous message.

If buffer control is enabled, the reader will not use the timeout to trigger re-transmission of data because in buffer control, reader data is transmitted only when requested by the host.

Reader message:

*Done*

### **Buffer Control Error Messages**

The error messages shown in the following table are transmitted based on the content level of the tag buffer. These messages are transmitted in data mode and command mode. They will not be transmitted if uniqueness checking has been disabled to transmit all IDs (command 40) or buffer all IDs (command 43).



Error Message	Buffer Status
Error02	Tag buffer is full. Incoming IDs cannot be buffered. An overflow of the tag buffer can occur if SmartPass is left in command mode or if flow control has disabled transmission. A buffer overflow results in subsequent tag IDs being lost.
Error03	Tag buffer has been partially cleared and new IDs are once again being stored.
Error04	Tag buffer has filled to 75%.
Error05	Tag buffer has emptied to 50%.

If the buffer fills up and then transmission is re-enabled, the sequence of transmitted reports would be as follows:

*Error 04*      75% full  
*Error 02*      100% full  
*Error 03*      emptied to less than 100%  
*Error 05*      emptied to 50% or less

**6170 Disable Echo Mode**

Command #6170 disables the reader’s echo of received host commands. If operating in basic protocol or data inquiry protocol, the reader echoes by default. As the reader receives a host command, it echoes each character of the command. Once the entire command has been received and processed, the reader transmits its response. If echoing is disabled with command #6170, the reader does not echo the command, but only transmits its response. The reader never echoes while in ECP or download mode operation.

Reader response:

Done

**6171 Enable Echo Mode (Factory Default)**

Command #6171 enables the reader to echo received host commands. Command 6170 disables echo mode.

Reader response is Done or Error.

**620N Set Output Control**

Command #620N provides direct control of two output lines that may be used to operate external hardware, such as gates or traffic lights. The value for N specifies the output status requested as shown in [Table 7-12](#). Receipt of any #620N command automatically disables command #621 Predefined Output Control.

**Table 7-12 Output Control Commands**

Command	Output Control Option
<b>6200</b>	Turn off both output ports
6201	Turn off output1, Turn on output0
6202	Turn off output0, Turn on output1
6203	Turn on both output ports (default)

Reader response:

Done

### **621 Predefined Output Control (Factory Default)**

Command #621 configures the reader for predefined output mode. In this mode, both output lines – output0 and output1 – are automatically asserted upon receipt of a valid unique tag ID. The output line remains asserted for the time specified by output pulse duration (#67N Set Output Pulse Duration). Any direct control command (#620N Output Control) automatically disables the predefined output mode.

Reader response:

Done

### **63 Reset Reader**

Command #63 resets the power fail bit, clears all buffers, resets tag uniqueness, turns off both output lines, transmits the sign-on message, and returns to the data mode.

*Note: This command does not reset any other configuration parameters.*

Reader response:

Model E4 TBD Series Ver X.XX SNYYYYYY  
Copyright 2008 TransCore

where

X.XXD

Version number.

YYYYYY

Serial number of the unit, skipping the fourth character printed on the reader product label.

### **640N RF Control\***

Command #640N directly controls the RF module. The N value controls the RF power as shown in [Table 7-13](#).

**Table 7-13 RF Control Commands**

Command	RF Power
6400	Turns off RF channel
6402*	Turns on continuous wave RF until command 6400 or 641 is received by the reader.

Command #6400 disables RF-by-input control command #641 Select RF-by-Input Control.

Reader response:

Done

**641 Select RF-by-Input Control (Factory Default)**

Command #641 configures the reader for RF-by-input control. The reader automatically turns on RF when it detects a presence through sense0. The reader turns off RF according to the selected RF control algorithm (#692N Select RF Control Algorithm).

Reader response:

Done

**642NN Select RF Operating Frequency**

Command #642NN sets the reader RF frequency from 902 to 928 MHz in 500-kHz steps, where NN is a hexadecimal value from 01 to 34. After the reader’s frequency is set, the value is stored in non-volatile RAM (NVRAM). This value is not altered by power-down. It can be changed by issuing command #642NN, loading default parameters, or a flash download of new software.



**Caution**

*The authorized frequency band for the TransCore Encompass 4/4800 Multiprotocol Reader in the United States is 912.5 to 919 MHz. Contact TransCore if your application requires a frequency outside of this range.*

If the NVRAM becomes corrupted, the correct operating frequency cannot be guaranteed. In this circumstance, the RF section shuts down and the reader sends an Error06 message to the host. Until the frequency is reset using command #642NN, the unit displays the same error message every time it is powered up or if an attempt is made to enable the RF by host or by external sensor.

The commands to set the RF frequency are presented in [Table 7-14](#).

**Table 7-14 Select RF Frequency Commands**

Command	RF Frequency (MHz)	Approved for Use in the U.S.
64200	902	No
64201	902.5	No
64202	903	No
64203	903.5	No
64204	904	No
64205	904.5	No
64206	905	No
64207	905.5	No
64208	906	No
62409	906.5	No
6420A	907	No
6420B	907.5	No
6420C	908	No
6420D	908.5	No
6420E	909	No
6420F	909.5	No
64210	910	No
64211	910.5	No
64212	911	No
64213	911.5	No
64214	912	No
64215	912.5	Yes
64216	913	Yes
64217	913.5	Yes
64218	914	Yes
64219	914.5	Yes
<b>6421A</b>	915 (factory default)	Yes

**Table 7-14 Select RF Frequency Commands (continued)**

Command	RF Frequency (MHz)	Approved for Use in the U.S.
6421B	915.5	Yes
6421C	916	Yes
6421D	916.5	Yes
6421E	917	Yes
6421F	917.5	Yes
64220	918	Yes
64221	918.5	Yes
64222	919	Yes
64223	919.5	No
64224	920	No
64225	920.5	No
64226	921	No
64227	921.5	No
64228	922	No
64229	922.5	No
6422A	923	No
6422B	923.5	No
6422C	924	No
6422D	924.5	No
6422E	925	No
6422F	925.5	No
64230	926	No
64231	926.5	No
64232	927	No
64233	927.5	No
64234	928	No

Reader response:

Done

### 643NN Select ATA Operating Range (Distance)

Command #643NN selects the read range where NN is a hexadecimal value from 00 to 1F; the range increases with increasing NN value. The range can be adjusted for 32 discrete values where 00 is the shortest range and 1F is the longest range. The default range value is 1F.

Reader response:

Done

### 644NN Set RF Attenuation\*\*

Command #644NN sets the attenuation control for the output RF power where NN is a hexadecimal value from 00 to 0A. Settings for attenuation are 1.0 dB increments over a range of 10 dB of attenuation from the maximum power setting of two watts at 0-dB attenuation to a minimum power level of 200 milliwatts at 10-dB attenuation.

The Set RF Attenuation command NN variables and corresponding attenuation settings are shown in [Table 7-15](#).

**Table 7-15 RF Attenuation Command Variables**

Variable (NN)	Attenuation Setting (dB)
00	0 (factory default)
01	1
02	2
03	3
04	4
05	5
06	6
07	7
08	8
09	9
0A	10

Reader response:

Done

### **645NN Set Encompass 4/4800 Multiprotocol Reader Operating Range (Distance)\*\***

Command #645NN sets the read range where NN is a hexadecimal value from 00 to 1F; the range increases with increasing NN value. The range can be adjusted for 32 discrete values where 00 is the shortest range and 1F is the longest range. The default range value is 1F.

Reader response:

Done

### **65 Reset Power Fail Bit**

Command #65 resets the power fail bit to 0. The bit changes from 0 to 1 when power is restored to the reader. Upon reader power-up, the host transmits either command #65 or #63 Reset Reader to properly initialize this bit. The current state of the power fail bit may be displayed. Refer to [“520 Display Power Fail Bit” on page 7-18](#) for more information.

Reader response:

Done

### **66F Load Default Operating Parameters**

Command #66F loads all the factory default operating parameters except RF operating frequency. Refer to [Table 8-2, Encompass 4/4800 Multiprotocol Reader Default Configuration Settings](#) for a listing of the defaults.

Reader response:

Done All parameters loaded OK

Error A parameter load failed

### **660 Test External RAM**

Command 660 performs a read/write test of external data memory (32 K). The contents of RAM are not disturbed by this test. Command 660 updates information displayed by the display diagnostic results command 661.

Reader message:

Done passed RAM test

Error failed RAM test

### **661 Display Diagnostic Results**

Command 661 displays the results of previously performed diagnostics. The information displayed by this command is updated when the reader receives any diagnostic command. This information is preserved after power-down. Executing command 669 updates every field in this message. If diagnostics have never been performed, the information displayed by this command is not predictable.

Reader message:

*DIAG R<0 to 1> E<0 to 1> D<0 to 1> C<0 to 1>*

where:

<i>R0</i>	boot ROM OK
<i>R1</i>	boot failed
<i>E0</i>	flash memory OK
<i>E1</i>	flash memory failed
<i>D0</i>	external RAM OK
<i>D1</i>	external RAM failed
<i>C0</i>	RTC OK
<i>C1</i>	RTC failed

#### **664 Test Real-Time Clock**

Command 664 tests the real-time clock (RTC). The reader tests the RTC by retrieving both the date and time and verifying their validity. This command updates information displayed by the display diagnostic results command 661.

Reader message:

*Done* real-time clock OK  
*Error* real-time clock failed

#### **667 Verify Boot ROM Checksum**

Command 667 calculates and verifies the boot ROM checksum. This command updates information displayed by the display diagnostic results command 661.

Reader message:

*Done* boot ROM OK  
*Error* boot ROM failed

#### **668 Verify Flash Memory Checksum**

Command 668 calculates and verifies the flash memory checksum. This command updates information displayed by the display diagnostic results command 661.

Reader message:

*Done* flash memory OK  
*Error* flash memory failed

#### **669 Perform All Diagnostics**

Command 669 performs a test on each of the following items:

- External RAM
- Boot ROM



- Flash memory
- Real-time clock

This command also initiates a system check tag operation. This command updates information displayed by the display diagnostic results command 661.

Reader message:

*Done* all tests OK  
*Error* one or more failures

Use command 661 to display the diagnostic results.

### 67N Set Output Pulse Duration

Command #67N sets the output pulse duration for the command #621 Predefined Output Control. This command specifies the length of time that output line(s) will be asserted upon receipt of a valid and unique tag ID. The factory default setting is 228 ms. The variable *N* specifies an output pulse duration of 48 ms to 752 ms.

*Note: The dual-protocol Encompass 4/4800 Multiprotocol Reader internal timing varies depending on the operative tag read mode and the type of tag in the read field. Values listed in the middle column of Table 7-15 assume an ID operational tag read mode (64-bit ID data from eGo tags, ignore ATA tags) and an eGo tag in the read field. Values in the right column of Table 7-15 assume an ATA operational tag read mode (reads ATA data from ATA tags) and an ATA tag in the read field. Actual pulse length output of the reader may vary from the specified value.*

Uppercase or lowercase characters are allowed for N; for example, hex digits A through F or a through f. The command numbers and corresponding output pulse durations are shown in [Table 7-16](#).

**Table 7-16 Output Pulse Duration Commands**

Command	Approximate duration (ms) for ID, IATA, Dual 1, and Dual 2 tag read mode operation	Approximate duration (ms) for ATA tag read mode operation
670 to 678	48 ms	130 ms
679	60 ms	140 ms
67A	76	190 ms
67B	152 ms	300 ms
67C	228 ms (factory default)	450 ms
67D	300 ms	550 ms
67E	376 ms	700 ms
67F	752 ms	1300 ms

For example, command #67F specifies an output pulse duration of 752 ms if the tag read mode is ID, eATA, Dual 1, or Dual 2. See command [#47N Select Tag Mode](#) for more information.

Additional IDs may be acquired during the selected output pulse duration; however, the timing restarts upon each successive ID acquisition. This command should be used with discretion. For example, when the tag acquisition interval is short compared to the selected pulse duration, distinct pulses may not be generated.

Reader response:

Done or Error

### **690N Select Presence Without Tag Report Option**

Command #690N enables or disables the presence without tag report option. If the presence without tag reporting option is enabled using command #6901, input reports are transmitted when a tag presence is detected without the subsequent acquisition of a valid tag. The value for N specifies the reports as shown in [Table 7-17](#).

**Table 7-17 Presence Without Tag Report Commands**

Command	Report Option
<b>6900</b>	Disable presence without tag reports (factory default)
6901	Enable presence without tag reports

Reader response:

Done

Refer to [“Basic Protocol and ECP Format”](#) on page 6-5 for message format information.

### **692N Select RF Control Algorithm**

Command #692N selects the algorithm for turning off RF power when RF-by-input control is enabled using command #641 Select RF-by-Input Control.

The values for N specify the RF control algorithms as shown in [Table 7-18](#).

**Table 7-18 RF Control Algorithm Commands**

Command	RF Power Off
6920	On timeout only
6921	Timeout or tag ID acquired
<b>6922</b>	Timeout or presence false (factory default)

Command #6920 turns off RF power based on the timeout established by command #693N Select RF Timeout Period.

Command #6921 allows RF power to be turned off either after the timeout period or upon acquisition of a valid tag ID, whichever occurs first.

Command #6922 turns off RF power either after the timeout period or upon the presence false condition, whichever occurs first.

Reader response:

Done

### 693N Select RF Timeout Period

Command #693N selects the RF timeout period used by command #692N Select RF Control Algorithm. Values for N range from 0 through F.

Command #693F disables the RF timeout. The reader turns off the RF immediately following the acquisition of a valid tag, whether or not it is unique. This control algorithm may be used in Wiegand mode to ensure that the tag data is transmitted once and only once per presence on both serial and Wiegand ports.

*Note: The dual-protocol Encompass 4/4800 Multiprotocol Reader internal timing varies depending on the operative tag read mode and the type of tag in the read field. Values listed in the middle column of Table 7-19 assume an ID operational tag read mode (64-bit ID data from eGo tags, ignore ATA tags) and an eGo tag in the read field. Values in the right column of Table 7-19 assume an ATA operational tag read mode (reads ATA data from ATA tags) and an ATA tag in the read field. Actual pulse length output of the reader may vary from the specified value.*

Uppercase or lowercase characters are allowed for N; for example, hex digits A through F or a through f. The commands and corresponding timeouts are shown in [Table 7-19](#).

**Table 7-19 Timeout Period Values**

Command	Approximate timeout (ms) for ID, IATA, Dual 1, and Dual 2 tag read mode operation	Approximate timeout (ms) for ATA tag read mode operation
6930	0 (always expired)	0 (always expired)
6931 to 6937	48 ms	150 ms
6938	60 ms	175 ms
6939	92 ms	200 ms
693A	152 ms	370 ms
693B	300 ms	680 ms
693C	452 ms	1000 ms

**Table 7-19 Timeout Period Values (continued)**

Command	Approximate timeout (ms) for ID, IATA, Dual 1, and Dual 2 tag read mode operation	Approximate timeout (ms) for ATA tag read mode operation
693D	600 ms	1250 ms
693E	752 ms	1500 ms
<b>693F</b>	Infinite (never expires, factory default)	Infinite (never expires, factory default)

Reader response:

Done or Error.

The reader returns an Error message if a valid hexadecimal digit is not substituted for N in command #693N.

### **694N Select Input Inversion Option**

Command #694N enables or disables input inversion. When inversion is enabled, an open circuit input is interpreted as a closed circuit, and a closed circuit input is interpreted as an open circuit. This feature allows greater flexibility in the attachment of external equipment to the reader inputs. For example, some proximity sensors indicate presence with an open circuit. In this instance, command #6941 can enable input inversion so that an open circuit input indicates a presence. The values for N represent the two inversion options as shown in [Table 7-20](#).

**Table 7-20 Input Inversion Options**

Command	Option
<b>6940</b>	Disable input inversion (factory default)
6941	Enable input inversion

Reader response:

Done

### **695S...S Set Serial Number**

Command #695 assigns the reader serial number according to the format:

695SSSSSS

where SSSSSS is the serial number.

The serial number may contain as many as six uppercase or lowercase ASCII alphanumeric characters.

*Note:* The factory-assigned serial number of the reader contains seven characters. However, to maintain backward compatibility, the reader software allows only six

characters to be entered. When setting the serial number, skip the fourth (middle) character of the seven-character number shown on the reader product label.

*Note:* Once assigned, the serial number is preserved during power-down and the loading of default parameters.

Reader response:

Done

### **696S...S Store Hardware Configuration String**

Command #696S . . . S stores hardware configuration information into reader memory.

The hardware configuration string is assigned according to the following format:

696S . . . S

where S . . . S is the hardware configuration string that may contain as many as 20 uppercase or lowercase ASCII alphanumeric characters.

*Note:* Once assigned, configuration information is preserved during power-down and the loading of default parameters.

Reader response:

Done

## **Auxiliary Reader Control — Command Group 8**

Group 8 commands provide control of reader functions, such as the sense input lines.

### **82N Select Input Status Change Report Option**

Command #82N selects the input lines to be monitored to report any change in input status. The enabled input lines are monitored for any changes in the logic states. If a change is detected, the reader generates an input status change message and treats it as a tag ID. If the auxiliary information option is enabled, the input status field displays the current input values. The value for N specifies the report options as shown in Table 7-21.

**Table 7-21 Input Status Change Report Options**

Command	Report Option
820	Disable status change reports (factory default)
821	Report change on input0
822	Report change on input1
823	Report changes on input0 and input1

Reader response:

Done

### **830 Disable Automatic Periodic RF Status Report (Factory Default)**

Command #830 is a default set in the factory to disable the automatic periodic RF status report.

Reader response:

Done

### **831 Enable Automatic Periodic RF Status Report**

Command #831 enables the automatic periodic RF status report. This function sends out a periodic RF status report if no other message (a tag read) is sent from the reader for a period of time. This message is the same message that would be sent in response to the #527 Display RF Status command. Enabling this function is helpful in some sites where there may not be much tag activity, and the user wants an automatic way to ensure the communication channel with the reader is still intact. With this function enabled, the host system will get a message from the reader at least every three minutes.

Reader response:

Done or Error.

---

## **Flash Memory Control — Command Group 9**

Group 9 commands enables testing, erasing, and updating flash memory with new software versions.

The reader must be operating in download mode (#05 Switch to Download Mode) before it will accept any command group 9 commands. Refer to [“Program Download” on page 5-5](#) for download information.

### **90 Load Program Block**

Command #90 transfers one Intel hex data record from an external host to the reader flash memory. This command loads an entire program file into reader memory, one block at a time. The flash memory must have been previously erased using command #96 Erase Flash Memory.

Reader response:

Done	Intel hex record has been received, stored, and verified with no errors detected.
Read Error	Error occurred during the transfer of the record.
Program Error	Error occurred during the programming of the flash memory.
Verify Error	Error occurred during the verification of the programmed data.

### 91 **Verify Flash Checksum**

Command #91 calculates a checksum on the flash memory and compares it against the stored checksum.

Reader response:

Done Flash checksum verified  
 Error Flash checksum failed

### 96 **Erase Flash Memory**

Command #96 erases the flash memory. Once this command is executed, exit from download mode is not possible until a new program is loaded into flash memory.

Reader response:

Done

### 97 **Perform Destructive Flash Test**

Command #97 performs a test on the flash memory. Various patterns are programmed into the memory and verified. This test overwrites any program previously stored in the flash memory; therefore, a download of software is required afterwards. Once this command is executed, exit from download mode is not possible until a new program is loaded into flash memory.

Reader response:

Done Flash memory OK  
 Error Flash memory failed

### 99 **Exit Download Mode**

Command #99 instructs the reader to exit download mode. The reader will re-execute startup to ensure proper initialization of the reader. If the flash memory checksum is verified, the reader displays the following sign-on message and enters data mode:

```
Model E4 TBD Series Ver X.XX  SNYYYYYY
Copyright 2008 TransCore
```

where

X.XXD                      Version number.

YYYYYY                    Serial number of the unit, skipping the fourth character printed on the reader product label.

If the flash checksum is not verified, the reader restarts in download mode and transmits the boot sign-on message.

PRELIMINARY



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# Configuring the Encompass 4/4800 Multiprotocol Reader

PRELIMINARY



# Configuring the Encompass 4/4800 Multiprotocol Reader

*This chapter provides instructions for configuring the Encompass™ 4/4800 Multiprotocol Reader, including factory configuration parameter defaults and how to use terminal emulation software to check and change the Encompass 4/4800 Multiprotocol Reader factory configuration defaults.*

## Configuring the Reader

After installing the Encompass 4/4800 Multiprotocol Reader, you need to configure its operating parameters. Terminal settings should be initially set at 9600 baud, 8 data bits, no parity, 1 stop bit, and no flow control.

### General Configuration Labeling

Each Encompass 4/4800 Multiprotocol Reader and its shipping carton are labeled to indicate the unit's general configuration. [Table 8-1](#) contains explanations of the Encompass 4/4800 Multiprotocol Reader label fields.

**Table 8-1 Encompass 4/4800 Multiprotocol Reader Configuration Label Fields**

Field	Description
1st	<b>Model number</b> TBD
2nd	<b>Interface</b> 100 = RS-232 and Wiegand 101 = RS-422 and Wiegand 102 = RS-485 and Wiegand (not available at this time)

As an example, a label reading 4xxx-100 indicates that this Encompass 4/4800 Multiprotocol Reader is configured with RS-232 and Wiegand communications.

### Default Operating Parameter Settings

Table 8-2 contains the factory default configuration settings for the Encompass 4/4800 Multiprotocol Reader operating parameters. The default configuration settings may not be the correct operating configuration settings for a specific site. Changes to the configuration settings may have to be made, depending on the site plan, as described in [Chapter 2 “Developing the Site Plan.”](#)

Review the default configurations shown in [Table 8-2](#) to determine which parameters, in addition to operating frequency and operating range, need to be adjusted. Refer to [Chapter 7, “Commands,”](#) for a complete list of parameters and the corresponding commands.

*Note: The dual-protocol Encompass 4/4800 Multiprotocol Reader internal timing varies depending on the operative tag read mode and the type of tag in the read field.*

**Table 8-2 Encompass 4/4800 Multiprotocol Reader Default Configuration Settings**

Parameter	Setting	Command
Operating mode	Data	00
Baud rate	9600	1005
Stop bits	1	1010
Parity	None	1020
Auxiliary information appended	Disabled	310
Unique ID code criteria	Separation of 1 ID	4100
Wiegand mode	Disabled	450
Alternative group select	Disabled	452
Multi-tag sort	Disabled	454
eGo tag initialization during multi-tag sort <sup>a</sup>	Enabled	456
Second alternative group select <sup>a</sup>	Disabled	458
Wiegand transmit mode	1 second	4601
Select tag mode	eATA mode	473
Third alternative group select <sup>a</sup>	Disabled	490
Fourth alternative group select <sup>a</sup>	Disabled	492
Fifth alternative group select <sup>a</sup>	Disabled	494
Reader ID number	00	6000
Communications protocol	Basic	610
Error correcting protocol (ECP) timeout	12.7 sec <sup>c</sup>	612FE
Flow control	Software (XON/XOFF)	6141
Echo mode	Enabled	6171
Sense output control	Predefined	621

**Table 8-2 Encompass 4/4800 Multiprotocol Reader Default Configuration Settings (continued)**

Parameter	Setting	Command
RF-by-input control	Enabled	641
RF operating frequency <sup>b</sup>	915MHz	6421A
ATA operating range	Maximum	6431F
RF attenuation	Full power	64400
Encompass 4/4800 Multiprotocol Reader operating range	Maximum	6451F
Sense output pulse duration	228 ms <sup>c</sup>	67C
Presence without tag reports	Disabled	6900
RF-off control	Timeout or no presence	6922
RF timeout	Never true	693F
Input inversion	Disabled	6940
Serial number	NNNNNN	695
Store hardware configuration	Hardware configuration not known	696
Input status change reports	Disabled	820
Automatic periodic RF status report <sup>a</sup>	Disabled	830

a. Command supported only in the Encompass 4/4800 Multiprotocol Reader Software Version 2.08 and later.

b. Local laws apply. The authorized frequency band for the TransCore Encompass 4/4800 Multiprotocol Reader in the United States is 912.5 MHz to 919 MHz. Contact TransCore if your application requires a frequency outside of this range.

c. The Encompass 4/4800 Multiprotocol Reader system does not include a real-time clock. The dual-protocol Encompass 4/4800 Multiprotocol Reader internal timing varies depending on the operative tag read mode and the type of tag in the read field. Unless stated otherwise, values listed for timing-related command variables assume an ID operational tag read mode (64-bit ID data from eGo tags, ignore ATA tags) and an eGo-compatible tag in the read field and these values may vary.

## Configuring Parameters with Terminal Emulation Software

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To configure the Encompass 4/4800 Multiprotocol Reader using a PC and terminal emulation software to manually enter Encompass 4/4800 Multiprotocol Reader host commands, follow the instructions in the section “[Connecting the Encompass 4/4800 Multiprotocol Reader to the PC](#)” on page 4-25. Then, enter the appropriate configuration commands through the terminal emulation software on your PC.

See [Chapter 7, “Commands,”](#) for a detailed description of all available configuration commands.

---

### Starting the Terminal Emulation Software

You can use a PC and any terminal emulation software to enter the host commands to download flash software, configure reader operating parameters, perform diagnostics, and retrieve tag data. The following procedures show examples using Hyper Terminal™, an application included with Microsoft Windows. Most terminal emulation applications have a similar sequence for launching.

#### To start the terminal emulation software

1. At the command prompt, type your terminal emulation start command; or if using Windows Hyper Terminal, select:  
Programs>Accessories>Hyperterm  
and press **ENTER**.

The application displays the Connection Description dialog box as shown in [Figure 8-1](#).

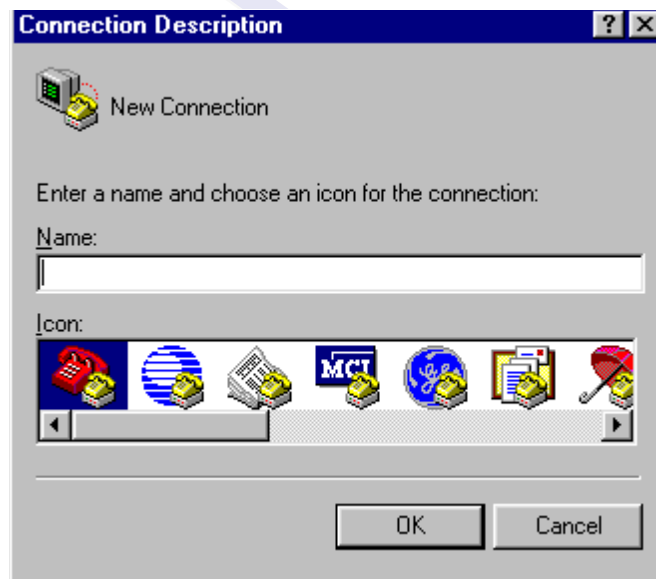


Figure 8-1 Connection Description Dialog Box

2. Enter a name for the session and click **OK**.

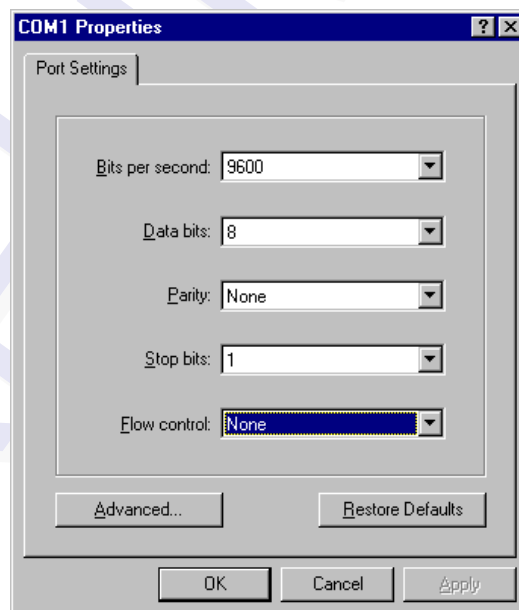
The application displays the **Phone Number** dialog box as shown in [Figure 8-2](#).



**Figure 8-2 Phone Number Dialog Box**

3. From the **Connect using** pull-down list, choose the **Com 1** option (or whichever com port on the PC to which the RS-232 cable is attached) and click **OK**.

The application displays the **COM1 Properties** dialog box as shown in [Figure 8-3](#).



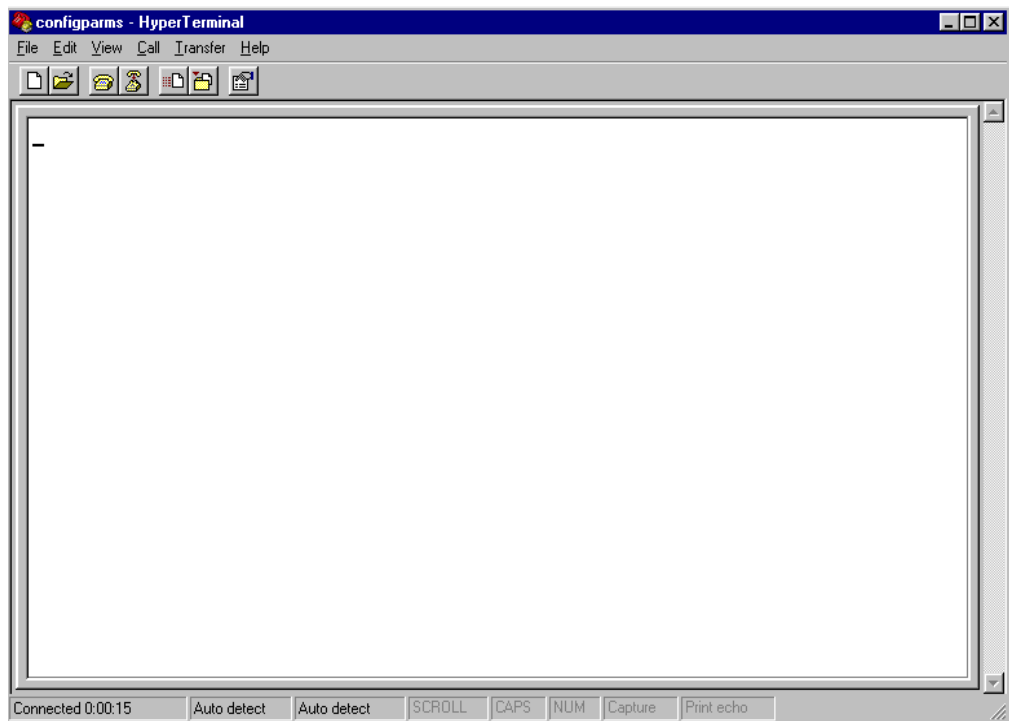
**Figure 8-3 COM 1 Properties Dialog Box**

4. In the pull-down lists on the **COM1 Properties** dialog box, choose the following values:

- Bits per second: 9600 baud
- Data bits: 8
- Parity: None
- Stop bits: 1
- Flow control: None

Click **OK**.

The application displays the **configparms - Hyper Terminal** main screen as shown in [Figure 8-4](#).



**Figure 8-4 Hyper Terminal Main Screen**

---

## **Verifying Communications**

You must verify that the Encompass 4/4800 Multiprotocol Reader and the PC or laptop are communicating.

### **To verify communications**

1. Start the terminal emulation application as described previously in [“Starting the Terminal Emulation Software”](#) on page 8-6.

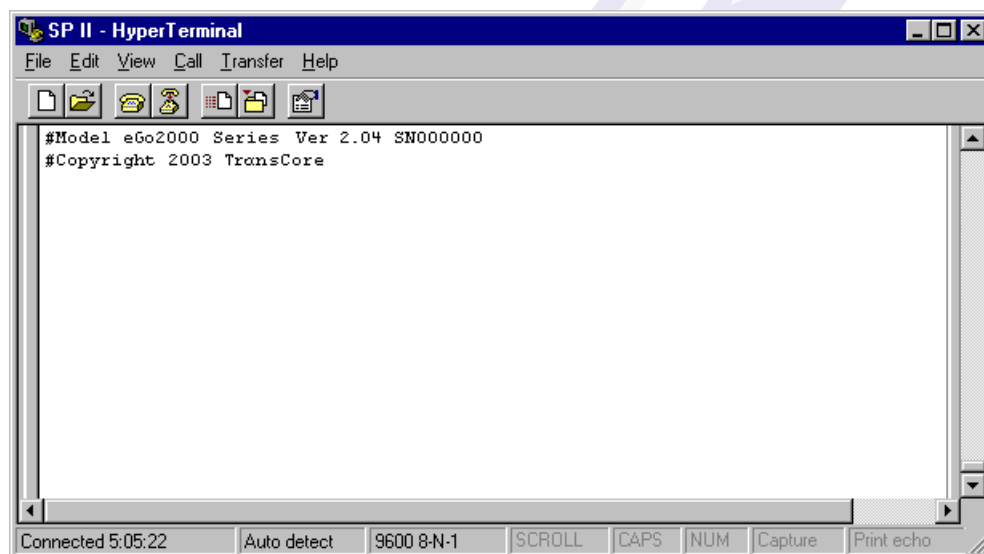
*Note:* When testing the Encompass 4/4800 Multiprotocol Reader using a laptop, TransCore recommends that you configure laptop communication parameters to



match those of the host computer to which the Encompass 4/4800 Multiprotocol Reader will be connected after testing and configuration are completed.

2. Cycle the power on the Encompass 4/4800 Multiprotocol Reader.

Upon startup, the Encompass 4/4800 Multiprotocol Reader transmits a sign-on message, displayed on the terminal emulation screen as shown in [Figure 8-5](#), or a boot ROM failure message.



**Figure 8-5 Sign-on Message**

The sign-on message appears as follows:

```
Model [software version] SNYYYYYY  
[Copyright notice]
```

where YYYYYY is the serial number assigned to the Encompass 4/4800 Multiprotocol Reader skipping the fourth character printed on the reader product label.

Serial number 000000 is the default setting and is not a valid number. If this number appears in the sign-on message, the serial number has never been stored into reader memory. Contact TransCore Technical Support.

If the flash memory checksum is not verifiable, the sign-on message appears as follows:

```
Model [Model] Ver 0.00 E  
[Copyright notice]
```

If the failure message version number equals 0.00 E and no serial number exists, the flash memory checksum has failed, and the Encompass 4/4800 Multiprotocol Reader is operating out of boot ROM. In this case, the Encompass 4/4800 Multiprotocol Reader automatically enters download mode and waits for a new program to be loaded into the flash memory. Follow the instructions in [“Program Download”](#) on page 5-5.

Communications can also be verified by using the command sequence in [Table 8-3](#).

**Table 8-3 Command Sequence to Verify Communications**

Entry	Encompass 4/4800 Multiprotocol Reader Response	Notes
#01 <CR>	#Done <CR/LF>	Switches the Encompass 4/4800 Multiprotocol Reader to command mode.
#505 <CR>	#Model eGo 2000 Ver X.0X SN97001P <CR/LF>	Reports the software version and serial number.
#00 <CR>	#Done <CR/LF>	Returns the Encompass 4/4800 Multiprotocol Reader to data mode.

3. If a successful sign-on message is not returned, check connections and communications factors and correct any errors.

**To check connections and communications factors**

1. Confirm that the Encompass 4/4800 Multiprotocol Reader has power.
2. Verify the connections between the PC and the Encompass 4/4800 Multiprotocol Reader.
3. Verify the receive (Rx) and transmit (Tx) connections.
4. If using handshaking, verify the RTS and CTS connections.
5. Verify the COM port settings for the Encompass 4/4800 Multiprotocol Reader using the instructions in [“Serial Port Communications” on page 8-18](#).

Repeat the procedures in [“Verifying Communications” on page 8-8](#).

If you still cannot verify the Encompass 4/4800 Multiprotocol Reader and PC communications, use the information in [“Technical Support” on page 9-7](#) to contact TransCore.

---

## Verifying Tag Read Capability

After verifying communications between the Encompass 4/4800 Multiprotocol Reader and the PC, verify the capability to read tags.

*Note:* Default tag read mode of the reader is eATA. If test tags are standard ATA-protocol tags, change tag read mode of the reader by issuing command #47N Select Tag Mode and using value #470 Dual 1.

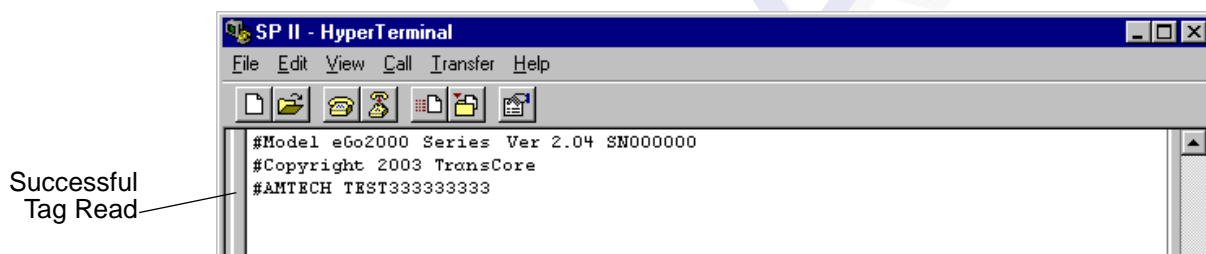


**Caution**

*To avoid damage to the Encompass 4/4800 Multiprotocol Reader using an external antenna, you must connect the antenna before applying power to the reader.*

**To verify tag read capability**

1. Once communications are verified as described in “Verifying Communications” on page 8-8, enter the following sequence of commands to turn on continuous RF:
  - #0121
  - #6401
  - #470
  - #00
2. Pass one test tag in front of the unit. If the Encompass 4/4800 Multiprotocol Reader reads the tag, the terminal emulation application displays the tag information on the screen as shown in [Figure 8-6](#).

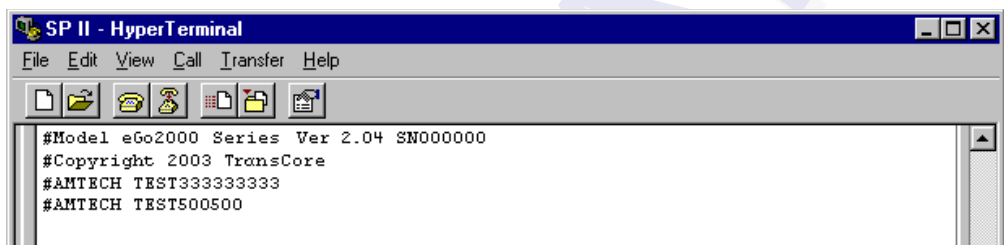


**Figure 8-6 Successful Tag Read**

If the tag ID is not displayed, perform the following actions:

- Verify that the Encompass 4/4800 Multiprotocol Reader is in data mode (command #00 Switch to Data Mode).
- Ensure that the tag you are using is compatible with the Encompass 4/4800 Multiprotocol Reader. The Encompass 4/4800 Multiprotocol Reader has the capability to read the eGo Windshield Sticker Tag as well as tags compliant with ATA and ISO standards, including TransCore’s IT2000 tags with the ATA/ISO mode enabled.
- A full-frame Encompass 4/4800 Multiprotocol Reader displays either half or full-frame ATA-protocol tags. If you are using half-frame Wiegand Windshield Sticker Tags, you might not see any tag ID information displayed.
- Using the audible circuit tester as described in “[Testing the Encompass 4/4800 Multiprotocol Reader Using an Audible Circuit Tester](#)” on page 4-5, verify that the reader is capable of reading the tag in the read zone. If it is, the problem is probably in the communications between the Encompass 4/4800 Multiprotocol Reader and the host.

3. Pass a different test tag in front of your Encompass 4/4800 Multiprotocol Reader.  
*Note:* An internal timer in the Encompass 4/4800 Multiprotocol Reader causes the reader to ignore a specific tag for two minutes or more after a good read unless a different tag is read in the interim. The dual-protocol Encompass 4/4800 Multiprotocol internal timing varies depending on the operative tag read mode and the type of tag in the read field.
4. When the Encompass 4/4800 Multiprotocol Reader reads the second tag successfully, the terminal emulation application displays that tag's information in the main screen below the information for the first tag, as shown in [Figure 8-7](#).



**Figure 8-7 Second Successful Tag Read**

If the read is unsuccessful, perform the following actions:

- Ensure the tag you are using is compatible with the Encompass 4/4800 Multiprotocol Reader.
- Using the audible circuit tester as described in [“Testing the Encompass 4/4800 Multiprotocol Reader Using an Audible Circuit Tester”](#) on page 4-5, verify that the reader is capable of reading the tag in the read zone. If it is, the problem is probably in the communications between the Encompass 4/4800 Multiprotocol Reader and the host computer.

## **Configuring Encompass 4/4800 Multiprotocol Parameters**

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Follow the procedures in this section to configure Encompass 4/4800 Multiprotocol parameters using a PC, laptop, or terminal emulator. The PC or laptop must be connected to and communicating with the Encompass 4/4800 Multiprotocol Reader, and the terminal emulation application must be configured correctly, as described in the section [“Verifying Communications”](#) on page 8-8.

*Note:* If you are using Wiegand mode, you must connect the PC or laptop to the Encompass 4/4800 Multiprotocol Reader using the RS-232 or RS-422 interface before attempting to send commands to the reader. You can leave the Wiegand interface connected during this procedure.

### To configure parameters

1. Switch to command mode by typing **#01** at the prompt on the terminal emulation screen, and pressing **ENTER**.

*Note:* All Encompass 4/4800 Multiprotocol Reader commands are preceded by the start-of-message character (#).

2. To meet requirements of your site, make changes to default operating parameters as described in the following sections.

The following sections contain procedures to set some of the parameters that are commonly changed to meet the requirements of a specific site. Procedures are listed in alphabetical order by parameter.

---

## Appended Tag Data

Use this procedure to set appended tag data parameters using the terminal emulation application. See [“31N Append Auxiliary Information Selection” on page 7-10](#) for more information.

### To set appended tag data parameters

1. Ensure that the host computer is in command mode.
2. Enter command **#311** to append auxiliary information or command **#310** to have no auxiliary information appended (factory default). Press **ENTER**.

---

## ID Separation

The host can select a unique ID separation of one ID or two IDs. The uniqueness timeout is fixed at two minutes. The reader default operation is for a unique ID separation of one ID and a uniqueness timeout of two minutes. You can disable the uniqueness check using command **#40** Transmit All ID Codes. In this case, every tag ID received is transmitted without regard to uniqueness. You can reinstate uniqueness checking with commands **#4100** or **#4101** Select ID Separation.

*Note:* The dual-protocol Encompass 4/4800 Multiprotocol Reader internal timing varies depending on the operative tag read mode and the type of tag in the read field.

See section [“40 Transmit All ID Codes” on page 7-11](#) and section [“410N Select Unique ID Code Criteria \(Anti-passback Feature\)” on page 7-11](#).

### To set ID separation parameters

1. Ensure that the host computer is in command mode.
2. Enter command **#4100** to select a separation of one ID; enter command **#4101** to select a separation of two IDs. Press **ENTER**.

---

## Reports

The Encompass 4/4800 Multiprotocol Reader can be configured to transmit presence without tag reports and input status change reports. A presence without tag report is transmitted in data mode only, *and only if the system has a presence detector*. This report is sent if a presence is detected without the detection of a valid tag ID. See sections “529 Display Presence Input Status” on page 7-23 and “690N Select Presence Without Tag Report Option” on page 7-42.

If configured with command #82N Select Input Status Change Report Option to transmit input status change reports, the reader will transmit a message to the host computer any time the inputs change state. Input status change reports are transmitted in data mode only. Input status change reporting is disabled by default. See sections “560 Request Sensor Status Change” on page 7-27 and “82N Select Input Status Change Report Option” on page 7-45. Also refer to Chapter 6, “Communications Protocols” for information on message formats.

### To set presence reporting

1. Ensure that the host computer is in command mode.
2. Enter command #529 to display presence input status and press **ENTER**. P0 indicates presence without tag reports disabled (factory default), and P1 indicates presence without tag reports enabled.
3. Enter command #6901 to enable presence without tag reports, or enter command #6900 to disable presence without tag reports (factory default). Press **ENTER**.

### To set input status change reporting

1. Ensure that the host computer is in command mode.
2. Enter command #560 to display input status change report options and press **ENTER**.
  - EO = input status change reports disabled (factory default)
  - E1 = input status change reports enabled
  - M0 = reporting disabled (factory default)
  - M1 = changes on input0 reported
  - M2 = changes on input1 reported
  - M3 = changes on either input reported
3. Enter command #821 to report any change on input0, command #822 to report any change on input 1, command #823 to report changes on input0 and input1, or command #820 to disable status change reports (factory default). Press **ENTER**.

---

## Reset Reader

Command #63 Reset Reader resets uniqueness, clears the power fail bit, and transmits the sign-on message. The reader returns to data mode following the completion of this command.

*Note:* This command does **not** reset any of the configuration parameters.

See “63 Reset Reader” on page 7-34.

### To reset the reader

1. Ensure that the host computer is in command mode.
2. Enter command #63. Press **ENTER**.

The terminal emulation screen displays the sign-on message as shown in [Figure 8-5 on page 8-9](#).

---

## Radio Frequency



### Caution

*The authorized frequency band for the Encompass 4/4800 Multiprotocol Reader in the United States is 912.5 to 919 MHz. The RF for each Encompass 4/4800 Multiprotocol Reader at the site must be set according to the frequency specified in the FCC site license. Only trained, authorized installation and maintenance personnel are permitted by FCC to set the RF.*

By using the Encompass 4/4800 Multiprotocol Reader an authorized person can set the frequency range from 902 to 928 MHz in 0.5 MHz steps. You can set the range by using a terminal emulation program and issuing the frequency command, as discussed in section “642NN Select RF Operating Frequency” on page 7-35.

### To set the frequency range

1. Ensure that the host computer is in command mode.
2. Enter command #642NN – where NN is a hexadecimal value from 00 to 34 – and press **ENTER**. See command “642NN Select RF Operating Frequency” on page 7-35 for a complete listing of the hexadecimal values and the corresponding frequencies.
3. To verify that the RF has been changed to the proper setting, type in command #527 to see the current frequency setting.



### Caution

*Contact TransCore if your application requires a frequency outside of the authorized frequency range.*

## RF Transmission

The RF transmission can be controlled by one of the following methods:

- Connecting a vehicle detector to the sense input0 circuit
- The host sending software commands to the Encompass 4/4800 Multiprotocol Reader

As a factory default, the Encompass 4/4800 Multiprotocol Reader is configured to control the RF power with a vehicle detector.

Figure 8-8 illustrates the methods of controlling RF sense output.

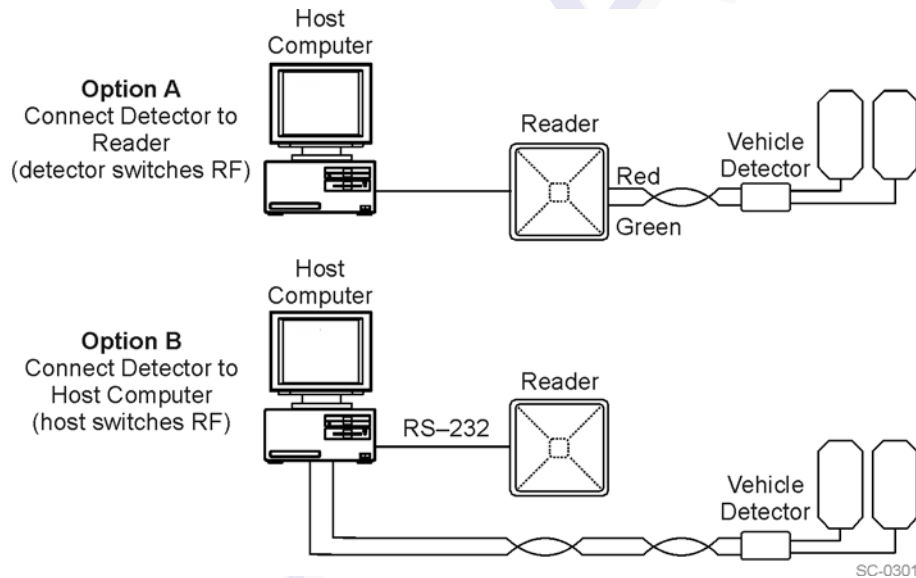


Figure 8-8 Encompass 4/4800 Multiprotocol Reader RF Control Options

### Vehicle Detector Controlling RF Transmission

The vehicle detector can be a loop detector, an infrared sensor, or an ultrasonic detector that is connected to sense input0 to turn on the Encompass 4/4800 Multiprotocol Reader RF transmitter. In Figure 8-8, Option A shows a vehicle detector controlling the RF transmitter. This operation is preferred because the RF transmits only when a vehicle is in the Encompass 4/4800 Multiprotocol Reader read zone. Command #641 Select RF-by-Input Control (factory default) must be enabled.

#### To set the option of the vehicle detector controlling the Encompass 4/4800 Multiprotocol Reader

1. Ensure that the host computer is in command mode.
2. Enter command #641. Press **ENTER**.

Leave the setting on RF-by-input control for normal operation.



## Host Controlling RF Transmission

In [Figure 8-8](#), Option B shows the host controlling the RF transmitter.

If the vehicle detector is connected to the host computer, as shown in Option B, commands #6400 RF Channel Off and #6401 RF Channel On sent from the host computer turn on and off the Encompass 4/4800 Multiprotocol Reader RF transmitter.

## Continuous RF Transmission

In [Figure 8-8](#), Option C shows the test configuration controlling the RF transmitter. To test the Encompass 4/4800 Multiprotocol Reader, as described in [“Testing the Encompass 4/4800 Multiprotocol Reader Using an Audible Circuit Tester”](#) on page 4-5, you can turn on the Encompass 4/4800 Multiprotocol Reader RF transmitter continuously by issuing command #6401.

You may also use command #6402 to turn on continuous wave RF for diagnostic purposes. Entering this command transmits a continuous RF signal at the output frequency and attenuation level as specified in the respective associated commands until command #6400 RF Channel Off, #6401 RF Channel On, or #641 Select RF-by-Input Control is received by the reader. Tags are not read in continuous wave mode. See [“640N RF Control\\*”](#) on page 7-34 for more information.

---

## Sense Inputs

Both the RS-232 and RS-422 configurations used by the Encompass 4/4800 Multiprotocol Reader have two sense inputs — sense input0 and sense input1. The default configuration uses sense input0 as the presence detection device line. RF power is automatically turned on only when the presence detection device (loop detector or other device) detects a presence. Sense input1 is not used directly by the reader; it is used by the host computer to monitor an external device. The Encompass 4/4800 Multiprotocol Reader sense inputs are designed to connect to a dry contact closure.

You can configure the Encompass 4/4800 Multiprotocol Reader to generate input status change reports, which are transmitted like tag IDs. The host can then respond based on the true/false (closed/open) status of the sense inputs. See the section [“Reports”](#) on page 8-14.

The following procedures describe how to set sense inputs using the terminal emulation software. See commands [“526 Display I/O Status”](#) on page 7-20, [“694N Select Input Inversion Option”](#) on page 7-44, and [“82N Select Input Status Change Report Option”](#) on page 7-45 for more information.

### To set sense inputs

1. Ensure that the host computer is in command mode.
2. Enter command **#526** to display the current input/output status. C0 = host controls outputs; C1= predefined output mode; O0 = both outputs off; O1 = output0 on; O2 = output1 on; O3 = both outputs on; I0 = both inputs false; I1 = input0 true; I2 = input1 true.
3. Enter command **#6940** to disable input inversion (factory default) or command **#6941** to enable input inversion, and press **ENTER**.

---

## **Sense Output Devices**

Both the RS-232 and RS-422 configurations used by the Encompass 4/4800 Multiprotocol Reader have two sense output circuits – sense output0 and sense output1.

By default, the Encompass 4/4800 Multiprotocol Reader operates in predefined output mode where sense output0 and sense output1 are asserted every time a unique valid tag is read. Both sense output devices are asserted by issuing command #621 Predefined Output Control. The devices are not asserted when tags are acquired in the transmit all or buffer all ID mode or when the Encompass 4/4800 Multiprotocol Reader is operating in Wiegand mode. The sense output pulse duration is variable (command #67N).

The host computer can disable the predefined sense output control by issuing command #6201 to turn sense output0 on or by issuing any of the following commands: #6200 Turn Off Both Output Ports, #6201 Turn Off Output0, On Output1, #6202 Turn Off Output1, On Output0, or #6203 Turn On Both Output Ports. While under host control, the sense outputs are not automatically asserted when a valid tag is read. The host must issue command #621 Predefined Output Mode to return to the predefined mode.

---

## **Serial Port Communications**

The Encompass 4/4800 Multiprotocol Reader supports one communications port, which can be ordered as either RS-232/Wiegand or RS-422/Wiegand. For the RS-232 and RS-422 communications specifications, the Encompass 4/4800 Multiprotocol Reader maintains the following three sets of parameters that affect serial port communications:

- Port configuration parameters (baud rate, data bits, stop bits, parity)
- Communications protocols (basic, error correcting)
- Flow control scheme (none, software, hardware)

The default serial port configuration for each of these three parameters is as follows:

- 9600 baud, 8 data bits, 1 stop bit, no parity
- Basic communications protocol
- Software flow control (XON/XOFF)

You can change these parameters in data mode and command mode operation by issuing commands with the host computer. Use the following procedures to set serial port communications parameters using the terminal emulation program.

---

## **Port Configuration Parameters**

Use this procedure to set port configuration parameters using the terminal emulation program. Consult sections [“100N Select Baud Rate\\*”](#) through [“102N Select Parity”](#) on page 7-8.

#### To set baud rate

1. Ensure that the host computer is in command mode.
2. Enter command **#100N** and press **ENTER**.

#### To set stop bits

1. Ensure that the host computer is in command mode.
2. Enter command **#101N** and press **ENTER**.

#### To set parity

1. Ensure that the host computer is in command mode.
2. Enter command **#102N** and press **ENTER**.

---

## Communications Protocol

Use the following procedures to set communications protocol. Consult sections “[610 Enable Basic Communication Protocol \(Factory Default\)](#)” through “[612NN Select Error Correcting Protocol Timeout](#)” on page 7-30 for more information.



#### Caution

*Do not switch to ECP (command #611) unless the host is prepared to acknowledge each reader transmission.*

#### To select a communications protocol

1. Ensure that the host computer is in command mode.
2. Enter command **#610** to select basic protocol (factory default) or command **#611** to select ECP and press **ENTER**.

---

## Software Flow Control

Two modes of flow control are supported — software (XON/XOFF) and hardware (CTS - clear to send). The host can enable or disable flow control with command **#614N** Select Flow Control Option.

The host can use software control characters (XON/XOFF) or the hardware CTS handshake line to interrupt reader transmissions. When the reader is configured for software flow control, it stops transmitting if it receives the XOFF character from the host (host software command 13H). It resumes transmitting only when it receives the XON character (host software command 11H) from the host. Likewise, when the reader is configured for hardware flow control, it stops transmitting if it detects that the CTS line is no longer asserted. It resumes transmitting when this line is asserted. If flow control is not needed, the reader should be configured for no flow control (**#6140** Disable Flow Control).

*Note: TransCore recommends that XON/XOFF flow control be disabled while using the error correcting protocol.*

Use the following procedure to set flow control parameters using the terminal emulation program. See section [“614N Select Flow Control Option” on page 7-30](#).

**To select flow control**

1. Ensure that the host computer is in command mode.
2. Enter command **#6140** to disable flow control, command **#6141** to enable software flow control (factory default), or command **#6142** to enable hardware flow control and press **ENTER**.

---

## ***Fine-Tuning and Verifying the Read Zone***

If the read zone is too wide or too deep for your application, it can be fine-tuned by physically adjusting the Encompass 4/4800 Multiprotocol Reader or external antenna mounting orientation, reprogramming the actual RF power output (#644NN Set RF Attenuation), and/or reprogramming the RF sensitivity range (#643NN Select ATA Operating Range and #645NN Select Encompass 4/4800 Multiprotocol Reader Operating Range). The combination of these adjustments allows you to confine the read zone to the area where tagged vehicles pass. This operation also minimizes reading unwanted vehicles in adjacent lanes or parking areas.

See sections [“643NN Select ATA Operating Range \(Distance\)” on page 7-38](#), [“645NN Set Encompass 4/4800 Multiprotocol Reader Operating Range \(Distance\)\\*\\*” on page 7-39](#), and [“644NN Set RF Attenuation\\*\\*” on page 7-38](#) for more information.

*Note:* As described in [“Marking the Read Zone” on page 4-32](#), marking the read pattern using test tags that are not mounted to vehicles give a general idea of the read pattern but the pattern will vary somewhat when actual vehicles with tags are tested. Final adjustments must be made with tags properly mounted on a variety of vehicles.

### ***Physically Orienting the Encompass 4/4800 Multiprotocol Reader***

You can manually adjust the location of the read zone by loosening the Encompass 4/4800 Multiprotocol Reader mounting brackets and pointing the reader in the desired direction. The unit should be aligned to point directly at the tag as it enters the desired read zone.

### ***Physically Orienting the Encompass 4/4800 Multiprotocol Reader Antenna***

You can manually adjust the location of the read zone by loosening the antenna mounting brackets and pointing the antenna in the desired direction. The unit should be aligned to point directly at the tag as it enters the desired read zone.

### ***Fine-Tuning the Read Zone by Lowering Output Power***

You can make the read zone smaller by adjusting the Encompass 4/4800 Multiprotocol Reader RF power output from a maximum of 2 watts to a minimum of 200 milliwatts using command #644NN Set RF Attenuation. Lowering the RF power has the added benefit of reducing RF interference with adjacent lanes.

### To adjust the read zone by lowering output power

1. Ensure that your PC is communicating with the Encompass 4/4800 Multiprotocol Reader using a terminal emulation program as described in section “[Verifying Communications](#)” on page 8-8.
2. Mark the current read zone as described in section “[Marking the Read Zone](#)” on page 4-32.



### Caution

*Test tags should be ATA-protocol, ISO-compliant tags, or eGo Windshield Sticker Tags affixed to a piece of nonmetallic windshield-type glass 0.190 to 0.230 in (4.82 to 5.84 mm) in thickness. The eGo Windshield Sticker Tag has a reduced read range when not attached to glass.*

3. Enter command **#01** to switch to command mode. You are prompted with **#DONE** from the reader and can now enter reader commands.
4. Enter in command **#64401** to lower the RF power by 1 dB below 2 watts (default). Press **ENTER**.

*Note: In the command #644NN, NN can be any hexadecimal value from 00 to 0A. Settings for attenuation are 1.0 dB increments over a range of 10 dB of attenuation from the maximum power setting of 2 watts at 0 dB attenuation to a minimum power level of 200 milliwatts at 10 dB attenuation. Increasing the attenuation lowers the output RF power.*

5. Switch to data mode by entering command **#00** and pressing **ENTER**.
6. Verify that the read zone has decreased by moving the tag through the desired read area. If the read zone is still too large, switch to command mode and enter the command **#64402** to lower the output RF power another 1 dB. Continue increasing the NN value until the read zone matches the desired read zone.
7. Follow the steps in “[Procedures](#)” on page 4-32 to mark the new read zone on the ground with tape or chalk.

When the desired read zone is established, test the read zone with simulated and real traffic by performing the following procedures:

### To test the read zone

1. Ensure that the Encompass 4/4800 Multiprotocol Reader is in data mode.
2. With the Encompass 4/4800 Multiprotocol Reader running, place one tag behind your back while you hold another tag in the new read zone. If a valid read, the data from the tag held in the read zone displays on the PC screen.
3. Switch tags, placing the other tag behind your back and holding the first tag in the read zone. If a valid read, the data from this tag held in the read zone displays on the PC screen. If both tags are read, you have successfully adjusted the read range.
4. If one or both tags did not read, follow the suggestions in “[Verifying Tag Read Capability](#)” on page 8-10.
5. As a last test, attach test tags to vehicles and simulate traffic going through the read zone to verify that the system performs accurately in a live environment.

### ***Fine-tuning the Read Zone by Adjusting Sensitivity Range***

The Encompass 4/4800 Multiprotocol Reader read zone can be fine-tuned by using command #643NN for ATA tag read mode or #645NN for Intellitag-based eGo tag read mode to reprogram the RF sensitivity range. Sensitivity range adjustments have less impact on the read pattern than RF power adjustment, thus RF power adjustment should be used as the main read pattern adjustment tool. Sensitivity range control may be helpful in stopping some tag reads on the very edges of the read pattern. To produce a noticeable change in the read pattern, you must decrease the range sensitivity by more than one increment.

#### **To adjust the read zone by adjusting sensitivity range**

1. Ensure that your PC is communicating with the Encompass 4/4800 Multiprotocol Reader using a terminal emulation program as described in “Verifying Communications” on page 8-8.
2. Mark the current read zone as described in [“Marking the Read Zone” on page 4-32](#).
3. Enter command **#01** to switch to command mode. You are prompted with #DONE from the reader and can now enter reader commands.
4. Enter command **#64318** or **#64518** to decrease the range sensitivity seven increments below the maximum (default). Press **ENTER**.

*Note: In the command #643NN or #645NN, NN can be any hexadecimal value from 00 to 1F. The reader’s receiver becomes less sensitive to tag signals as the value of NN is lowered from the maximum sensitivity of 1F to the minimum sensitivity of 00.*

5. Verify that the read zone has decreased by moving the tag through the desired read area. If the read zone is still too large, switch to command mode and enter the command **#64317** or **#64517** to decrease the range another increment. Continue increasing the NN value until the read zone matches the desired read zone.
6. Follow the steps in section [“Procedures” on page 4-32](#) to mark the new read zone on the ground with the tape or chalk.

When the desired read zone is established, test the read zone with simulated and real traffic by performing the following procedures.

#### **To test the read zone**

1. Ensure that the Encompass 4/4800 Multiprotocol Reader is in data mode.
2. With the Encompass 4/4800 Multiprotocol Reader running, place one tag behind your back while you hold another tag in the new read zone. If a valid read, the data from the tag held in the read zone displays on the PC screen.
3. Switch tags, placing the other tag behind your back and holding the first tag in the read zone. If a valid read, the data from this tag held in the read zone displays on the PC screen.

4. If both tags are read, you have successfully adjusted the read range. If one or both tags did not read, follow the suggestions in [“Verifying Tag Read Capability”](#) on [page 8-10](#).
5. As a last test, attach test tags to vehicles and simulate traffic going through the read zone to verify that the system performs accurately in a live environment.

PRELIMINARY

PRELIMINARY



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Troubleshooting and Maintenance

PRELIMINARY



## Troubleshooting and Maintenance

***This chapter contains information for troubleshooting an Encompass™ 4/4800 Multiprotocol Reader and performing minimal maintenance checks. It also includes information for returning products for repair, obtaining support, and contact information for providing feedback and suggestions to TransCore.***

### Error Messages

The Encompass 4/4800 Multiprotocol Reader transmits an error message if a command received from the host is not a recognized command or if information supplied with the command is not correct. The reader sends this message to diagnostic commands if the reader fails the specified test.

[Table 9-1](#) contains a list of error messages.

**Table 9-1 Error Messages**

Error Message	Description	Corrective Action
Error06	NVRAM parameters have been lost. The Encompass 4/4800 Multiprotocol Reader will not function properly because the RF section is shut off until the frequency is reset.	Reset the frequency using command #642NN.
Error07	The RF phase locked loop (PLL) has lost lock and is unable to operate at its intended frequency. RF output is disabled while the Encompass 4/4800 Multiprotocol Reader attempts to reset the PLL.	Reset the RF frequency. Refer to <a href="#">“Radio Frequency” on page 8-15</a> for instructions.
Error08	The RF PLL has successfully regained lock and has been reset to its proper operating frequency. The RF section is returned to its state prior to losing lock (enabled/disabled). <i>Error08</i> will only be issued after <i>Error07</i> has been issued.	No action necessary; the previous error has been corrected.

Table 9-1 Error Messages (continued)

Error Message	Description	Corrective Action
Error09	The Encompass 4/4800 Multiprotocol Reader software has detected an old or unsupported version of the Encompass 4/4800 Multiprotocol Reader hardware and will not function. The Encompass 4/4800 Multiprotocol Reader is immediately placed into download mode after issuing this message. This error can only occur on system power-up or reset.	The correct version of the Encompass 4/4800 Multiprotocol Reader software from TransCore must be downloaded to the Encompass 4/4800 Multiprotocol Reader. Contact Technical Support as described on page 9-7.
Error11	The operator is attempting to use an Intellitag-based tag in Wiegand mode while the Encompass 4/4800 Multiprotocol Reader is in ID-only mode, thus Wiegand compatibility issues.	Reset mode using command #473 for Intellitag-based tags only or #470 for Intellitag-based/ATA tags.

## Troubleshooting

You can use the following table for troubleshooting. Should problems continue, contact TransCore for return and replacement procedures. If you call Technical Support, use the symptom number in [Table 9-2](#) to reference the problem that you are having with the Encompass 4/4800 Multiprotocol Reader.

Table 9-2 Symptoms and Remedies

Symptom Number <sup>a</sup>	Symptom	Remedy
1	When performing a quick test of the Encompass 4/4800 Multiprotocol Reader, the buzz box does not buzz.	<p>Check all your wiring connections and antenna connections (if using external antenna), and ensure that your buzz box is functioning.</p> <p>The wires from the Encompass 4/4800 Multiprotocol Reader are grouped in pairs. You could find more than one red wire, more than one black wire, and so on. You must connect the correct red and white wire pair to the leads from the battery.</p> <p>Verify that RF is on as described in <a href="#">“Bench Testing the Encompass 4/4800 Multiprotocol Reader Before Installation” on page 4-12</a>. Using a terminal emulation program, you may switch to command mode and issue command #527 to determine RF status. See page 7-22 for more information.</p>
2	The baud rate is selected correctly but nothing happens.	The Encompass 4/4800 Multiprotocol Reader is not communicating with your PC. Check the power supply to your PC, and check the connections between the PC and the Encompass 4/4800 Multiprotocol Reader. Try reversing the receive and transmit connections.

Table 9-2 Symptoms and Remedies (continued)

Symptom Number <sup>a</sup>	Symptom	Remedy
3	When testing the Encompass 4/4800 Multiprotocol Reader, all the wires are connected correctly but the unit does not respond.	<p>The Encompass 4/4800 Multiprotocol Reader may not have the software loaded inside the unit. Contact Technical Support as described on page 9-7.</p> <p>If you are using a terminal emulation program, check that the terminal emulation setting on the Encompass 4/4800 Multiprotocol Reader is VT100.</p> <p>Check that the Encompass 4/4800 Multiprotocol communication cable is connected to the correct COM port.</p> <p>Verify that the external antenna is connected correctly.</p> <p>Verify that the reader is in the correct tag read mode (#47N).</p>
4	Strange signal responses come from the Encompass 4/4800 Multiprotocol Reader when tested with the PC.	<p>Ensure that the reader is in the correct interface mode for the test tag, i.e., Wiegand mode for a Wiegand tag.</p> <p>Check the system defaults using a terminal emulation program. Both PC and reader should be set to 9600 baud, 8 bits, 1 stop bit, and no parity.</p>
5	When a tag is moved in front of the reader or external antenna, a clicking sound comes from the Encompass 4/4800 Multiprotocol Reader.	<p>The Encompass 4/4800 Multiprotocol Reader works! The sound is the relay inside the Encompass 4/4800 Multiprotocol Reader that is controlled by a lock signal. The relay is actuated when a tag is in the read zone.</p>
6	Nothing happens when the test tag is passed in front of the Encompass 4/4800 Multiprotocol Reader or external antenna.	<p>Ensure that the Encompass 4/4800 Multiprotocol Reader is powered on and is in predefined output mode. (#621)</p> <p>Verify that the reader is in the correct tag read mode (#47N).</p> <p>Verify that the reader is set to RF ON (#6401).</p> <p>Verify that the external antenna is connected correctly.</p>
7	The Encompass 4/4800 Multiprotocol Reader came from another site and does not work the way the factory defaults indicate that it should.	<p>Different commands were probably used to support the other site's specific configuration. You can restore the factory defaults by using a terminal emulation program to switch to command mode and issuing command #66F Load Default Operating Parameters. All factory defaults except RF frequency will be restored.</p>
8	When connected to a PC that is running terminal communications software, a just-powered up Encompass 4/4800 Multiprotocol Reader displays one of the following messages: #TBD Ver X SNYYYYYY #[Copyright notice]	<p>The Encompass 4/4800 Multiprotocol Reader works! The software is now loaded. YYYYYY is the TransCore-assigned serial number for this Encompass 4/4800 Multiprotocol Reader. However, if YYYYYY = 000000, a serial number has never been assigned. If a serial number has not been assigned to your Encompass 4/4800 Multiprotocol Reader, contact TransCore Technical Support. Note that each Encompass 4/4800 Multiprotocol unit must have its own unique serial number.</p>

Table 9-2 Symptoms and Remedies (continued)

Symptom Number <sup>a</sup>	Symptom	Remedy
9	The read zone is too small, even before the RF power and range control have been adjusted.	<p>If another Encompass 4/4800 Multiprotocol Reader is in the same area, ensure that it is operating on another frequency that is at least 2 MHz different.</p> <p>Check for possible interference from another nearby RF source: fluorescent lights, neon signs, high voltage power lines, nearby cellular telephone, or radio stations. Lights will need to be removed or shielded. Point the Encompass 4/4800 Multiprotocol Reader or external antenna in a different direction to see if interference comes from only one direction. You may require a different Encompass 4/4800 Multiprotocol Reader that uses another frequency.</p> <p>Verify that the RF power is set to an appropriate value.</p> <p>Verify that the range adjustment is set to the maximum.</p> <p>Verify that the reader is getting at least 16V.</p>
10	The perimeter of the read zone has been defined, but there is a “hollow” spot in the center of the zone that does not read tags.	<p>The angle of the Encompass 4/4800 Multiprotocol Reader or external antenna may need adjustment. Slightly tilt the Encompass 4/4800 Multiprotocol Reader or external antenna to a different angle to change either the length or width of the read zone.</p> <p>Check the range control adjustment. See “Radio Frequency” on page 8-15.</p>
11	The Encompass 4/4800 Multiprotocol Reader is reading tags out of the desired read zone, or cross-lane reads are occurring.	<p>Some interference from other RF or electrical sources may be occurring. See “Reflection, Refraction, and Diffraction of RF Signals” on page 2-19.</p> <p>Verify that the read zone has been properly set up. See “Fine-Tuning and Verifying the Read Zone” on page 8-20.</p>
12	The Encompass 4/4800 Multiprotocol Reader is not providing any output to the Wiegand interface.	<p>Ensure that the Encompass 4/4800 Multiprotocol Reader is in Wiegand mode (#451). The default is either RS-232 or RS-422 mode. Refer to “Wiegand Interface” on page 4-28.</p> <p>Ensure the tags are properly programmed with Wiegand data.</p>

<sup>a</sup>Use this number to reference the problem you are having with the Encompass 4/4800 Multiprotocol Reader if you call Technical Support.

## Encompass 4/4800 Multiprotocol Reader Repair

The Encompass 4/4800 Multiprotocol Reader is designed for whole-unit replacement and is manufactured with surface-mounted components. It requires sophisticated testing and repair equipment. All testing and repairs are performed at TransCore’s factory. Please contact TransCore to obtain a Return Materials Authorization (RMA) for returning the reader.

## **Technical Support**

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Authorized dealers and distributors are responsible for the direct support of all customers. Authorized dealers and distributors needing support can call (800) 755-0378 and ask for Technical Support, which is available 24 hours a day. Send faxes to (214) 461-6478 ATTN: Technical Support. Please be prepared to answer a series of questions that are designed to direct you to the best TransCore support resource available. These questions will relate to symptoms, configuration, model, and tags used.

*Note: End users and facility operators calling Technical Support will be referred to the dealer responsible for the system sale.*

## **Marketing Support**

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Dealers requiring marketing support may call TransCore Marketing at (214) 461-4031, 9:00 a.m. to 5:00 p.m. Central Standard Time, Monday through Friday. Send faxes to (214) 461-6478 ATTN: TransCore Marketing.

## **Find a Problem with the Encompass 4/4800 Multiprotocol Reader or Have Suggestions?**

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Call (800) 755-0378, which is answered 24 hours a day, and ask for the TransCore Encompass 4/4800 Multiprotocol Reader product manager. Send faxes to (214) 461-6478 ATTN: Encompass 4/4800 Multiprotocol Reader product manager.

PRELIMINARY



A

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Glossary

PRELIMINARY



# Appendix A

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## Glossary

### A

<b>AAR</b>	Association of American Railroads
<b>AC</b>	alternating current
<b>ACK</b>	acknowledge (data valid)
<b>ANSI</b>	American National Standards Institute
<b>antenna</b>	passive device that converts RF energy into magnetic energy (RF signal)
<b>ASCII</b>	American Standard Code for Information Interchange
<b>ASIC</b>	application-specific integrated circuit
<b>ATA</b>	American Trucking Association
<b>aux</b>	auxiliary
<b>AWG</b>	AWG (American Wire Gauge) is a U.S. standard set of non-ferrous wire conductor sizes

### B

<b>backscatter</b>	portion of an RF signal that is modulated by a tag and radiated back to the reader
<b>baud</b>	measure of number of bits per second of a digital signal; for example, 9600 baud = 9600 bits per second
<b>BCKS</b>	boot checksum
<b>BCM</b>	buffer control mode
<b>bps</b>	bits per second
<b>byte</b>	a binary character; for example, one 8-bit ASCII character

### C

<b>check tag</b>	tag mounted inside a reader assembly, inside or in close proximity to an external antenna that is used to check operation of the reader
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<b>cmd</b>	command
<b>CTRL</b>	control
<b>comm</b>	communications
<b>command</b>	data set that is recognized by the receiving device as intending to elicit a specific response
<b>conduit</b>	flexible steel pipe use for electrical wiring
<b>cps</b>	characters per second
<b>CR</b>	carriage return
<b>CRC</b>	cyclic redundancy check
<b>CTS</b>	clear to send
<b>D</b>	
<b>data</b>	information that is processed by a computing device
<b>DC</b>	direct current
<b>DIAG</b>	diagnostic
<b>E</b>	
<b>ECP</b>	error correcting protocol
<b>ECPS</b>	error correcting protocol status
<b>eGo</b>	proprietary name for ANS INCITS 256-2001 compliant TransCore tag products. A registered trademark of TCP IP, Ltd.
<b>Encompass</b>	proprietary name for ANS INCITS 256-2001 compliant TransCore reader products. A trademark of TC IP, Ltd.
<b>eol</b>	end of line
<b>eom</b>	end of message
<b>EPROM</b>	erasable programmable read-only memory

**F**

**field** physical area/space in which a tag can be read by the reader; also, an element of a data record/frame. For example, division within a tag's data frame.

**frames** consecutive bits of data in memory that are read and written as a group

**frequency bands** a range of RF frequencies assigned for transmission by an RF device

**H**

**hex** hexadecimal

**hexadecimal** base 16 numbering system that uses the characters 0 through 9 and A through F to represent the digits 0 through 16

**host** device, generally a computer, that is connected to the Encompass 4/4800 Multiprotocol Reader through the communications port

**I**

**I/O or IO circuits** input/output circuits

**ID** identification; encoded information unique to a particular tag

**INCITS** American National Standards Institute International Committee for Information Technology standards

**Intellitag** Proprietary name for ANS INCITS 256-2001 compliant Intermec products. A registered trademark of Intermec Technologies Corporation, a UNOVA Company.

**interface** connection point for communication with another device

**IOST** I/O status

**ISO** International Standardization Organization

**L**

**LF** line feed

**M**

**m** meter

<b>MHz</b>	megahertz
<b>mode</b>	method of operation
<b>ms</b>	milliseconds
<b>N</b>	
<b>NAK</b>	negative acknowledgment (data not valid)
<b>P</b>	
<b>passback</b>	used to refer to a tag ID that is not passed on to the tag buffer
<b>PC</b>	personal computer
<b>PCKS</b>	EPROM flash checksum
<b>protocol</b>	specified convention for the format of data messages communicated between devices
<b>PRST</b>	presence status
<b>PWRB</b>	power fail bit
<b>R</b>	
<b>RAM</b>	random access memory
<b>RDID</b>	reader ID
<b>read</b>	process of acquiring data from a device; for example, from a tag or from computer memory
<b>reader</b>	controlled interrogating device capable of acquiring data from a device; for example, acquiring and interrupting data from a tag
<b>read zone</b>	the physical area in which a tag can be read by the reader
<b>RF</b>	radio frequency
<b>RFST</b>	RF status
<b>RFID</b>	radio frequency identification
<b>ROM</b>	read-only memory
<b>RTC</b>	real-time clock

**RTS** request-to-send

## **S**

**SCTS** status of check tag status

**SSTC** input status change reporting options

**som** start of message

**SN** serial number

## **T**

**tag** small self-contained device acting as an identifying transponder

**Tau** timeout delay

**TT** tag translation

## **V**

**v** volts

**Ver** version (software)

## **W**

**Wiegand** the trade name for a technology used in card readers and sensors, particularly for access control applications. Wiegand devices were originally developed by HID Corporation.

**write** process of recording data; for example, writing to computer memory or to a tag's memory. Writing writes over (erases) previous data stored at the specified memory locations.

**WTI** Wiegand retransmit interval

## **X**

### **XON/XOFF**

protocol for controlling the flow of data between computers and other devices on an asynchronous serial connection. X/ON and X/OFF are signals to turn a transmitter on or off. The actual signal for X/ON is the same bit configuration as the ASCII Ctrl-Q keyboard combination (11 hexadecimal). The X/OFF signal is the Ctrl-S character (13 hexadecimal).

PRELIMINARY



# B

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## Technical Specifications

PRELIMINARY



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# Technical Specifications

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## ***Reader Specifications***

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### ***Communications***

Frequency Selection    902 to 928 MHz capable  
912.5 to 919 MHz FCC-authorized in the United States<sup>a</sup>

Reading Range        Read performance varies depending on tag, reader, and external antenna (if required) configuration and environment. Optimum read range using the eGo Windshield Sticker Tag is 24.3 ft (7.4 m).  
Typical read range should be 12 to 17 ft (3.7 to 5.2 m).<sup>b</sup>

- a. Operation in the United States is regulated by the FCC. Local regulations apply. The user is required to obtain a license issued by the FCC. Contact TransCore for more information.
- b. Reading range depends on reader or external antenna configuration, tag type, tag read mode, and operating environment.

### ***Hardware Features***

Integrated System and/or integrated system with connector for external antenna    RF module, tag decoder, external antenna (if required), power supply, I/O ports, and serial communications interface all housed in a single package.

Case                    Weatherproof enclosure. The system is sealed in a tamper-proof, polycarbonate housing.

### ***Power Requirements***

Input Voltage        16 to 20V AC, 47 to 63 Hz  
or  
16 to 28V DC

### **Physical Attributes**

Size	15.5 x 15.5 x 3.25 in (39.4 x 39.4 x 8.25 cm)
Weight	9.5 lb (4.3 kg)

### **Environmental Parameters**

Operating Temperature	-40°F to +131°F (-40°C to +55°C)
Humidity	100% noncondensing
Vibration Tolerance	0.5 G <sub>rms</sub> , 10 to 500 Hz

### **Options**

Communications Interface	RS-232 and Wiegand or RS-422 and Wiegand
Cable Accessory Kits	58-1620-001: Connector with 5 ft (1.5 m) cable 58-1620-002: Connector with 20 ft (6.1 m) cable 58-1620-006: Connector with 35 ft (10.7 m) cable
Wall Mount Bracket	Allows adjustment in all planes when used to install the Encompass 4/4800 Multiprotocol Reader on a flat surface. Include the part number 54-1620-001 when ordering.
Transformer	A Class C transformer is available to allow 110V AC to 18V AC conversion. Include the part number 76-1620-005 when ordering. A Class C transformer (part number 76-1620-008) to allow 220V AC to 18V AC conversion is available by special request.

C

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Wiring Tables

PRELIMINARY



# Appendix C

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## Wiring Tables

*This appendix contains tables that show the wiring connections used to test and install the Encompass™ 4/4800 Multiprotocol Reader.*

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### Communications Interfaces

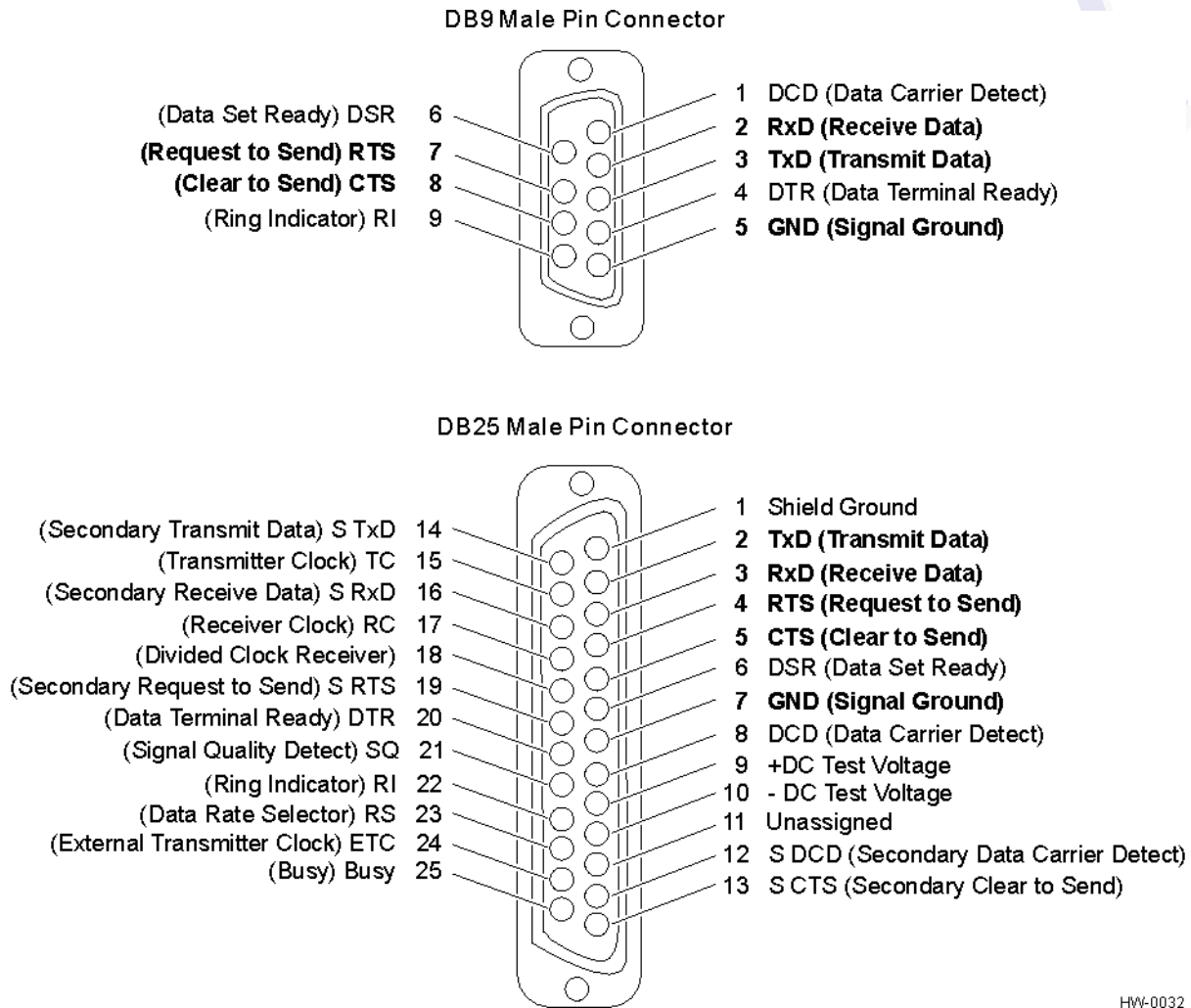
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Table C-1 lists the interfaces available with the Encompass 4/4800 Multiprotocol Reader.

**Table C-1 Communications Interfaces and Conductor Requirements**

Interface	Number of Conductors
RS-232	3
RS-232 with RTS and CTS hardware handshake signals	5
RS-422	4
Wiegand	3

Figure C-1 shows the pin assignments for the RS-232 interface signal to the host male DB9 and DB25 connectors.



HW-0032

**Figure C-1 DB9 and DB25 Connector Pin Assignments for Signal to Host**

*Note: In Figure C-1, supported pin assignments are boldface.*

## Cable Supplied with the Encompass 4/4800 Multiprotocol Reader

The Encompass 4/4800 Multiprotocol Reader is delivered with a multiwire cable (ordered as a separate accessory), which is a 13-pair pigtail. An alternate 15-pair pigtail may be substituted. The 13-pair pigtail is a colored-wire pair cable, with different colors denoting the individual pairs, one pair of which is red/black. The alternate 15-pair pigtail is a red/black-wire pair cable, with numbers on the pairs to denote the individual pairs. Two pairs of the 15-pair pigtail, numbers 14 and 15, are not used.



The following tables show the colored-wire pair (13-pair) and alternate wire pair (15-pair) assignments for the various interfaces, power, and input/output connections.

## RS-232 Interface

Table C-2 shows the RS-232 assignments for colored-wire pair (13-pair) cable.

**Table C-2 RS-232 Interface Signal Wiring for Colored-Wire Pair Cable**

Signal from Encompass 4/4800 Multiprotocol Reader	Colored-Wire Pair Cable		Connect Wire to Host DB9 Pin	Connect Wire to Host DB25 Pin
	Wire Pair from Encompass 4/4800 Multiprotocol Reader	Color Used		
TxD — Encompass 4/4800 Multiprotocol Reader output	Red/Black	Black	Pin 2	Pin 3
RxD — Encompass 4/4800 Multiprotocol Reader input		Red	Pin 3	Pin 2
Signal ground	Yellow/Black	Yellow or Black	Pin 5	Pin 7
<b>Optional for hardware handshaking</b>				
RTS — Encompass 4/4800 Multiprotocol Reader output	Yellow/Red	Yellow	Pin 8	Pin 5
CTS — Encompass 4/4800 Multiprotocol Reader input		Red	Pin 7	Pin 4

Table C-3 shows the RS-232 assignments for alternate wire (15-pair) cable.

**Table C-3 RS-232 Interface Signal Wiring for Alternate Wire Cable**

Signal from Encompass 4/4800 Multiprotocol Reader	Alternate Wire Cable		Connect Wire to Host DB9 Pin	Connect Wire to Host DB25 Pin
	Pairing	Color		
TxD — Encompass 4/4800 Multiprotocol Reader output	Pair 1	Black	Pin 2	Pin 3
RxD — Encompass 4/4800 Multiprotocol Reader input		Red	Pin 3	Pin 2
Signal ground	Pair 5	Black or Red	Pin 5	Pin 7
<b>Optional for hardware handshaking</b>				
RTS — Encompass 4/4800 Multiprotocol Reader output	Pair 11	Black	Pin 8	Pin 5
CTS — Encompass 4/4800 Multiprotocol Reader input		Red	Pin 7	Pin 4

## RS-422 Interface

Table C-4 shows the RS-422 assignments for colored-wire pair (13-pair) cable.

**Table C-4 RS-422 Interface Signal Wiring for Colored-Wire Pair Cable**

Signal from Encompass 4/4800 Multiprotocol Reader	Colored-Wire Pair Cable		Connect to Signal from Host
	Wire Pair from Encompass 4/4800 Multiprotocol Reader	Color Used	
RS-422 Transmit positive	Yellow/Red	Yellow	Receive (+)
RS-422 Transmit negative		Red	Receive (-)
RS-422 Receive positive	Red/Black	Black	Transmit (+)
RS-422 Receive negative		Red	Transmit (-)

**Table C-4 RS-422 Interface Signal Wiring for Colored-Wire Pair Cable**

Signal Ground	Yellow/Black	Yellow or Black	Signal Ground
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Table C-5 shows the RS-422 assignments for alternate wire (15-pair) cable.

**Table C-5 RS-422 Interface Signal Wiring for Alternate Wire Cable**

Signal from Encompass 4/4800 Multiprotocol Reader	Alternate Wire Cable		Connect to Signal from Host
	Pairing	Color	
RS-422 Transmit positive	Pair 11	Black	Receive (+)
RS-422 Transmit negative		Red	Receive (-)
RS-422 Receive positive	Pair 1	Black	Transmit (+)
RS-422 Receive negative		Red	Transmit (-)

## Wiegand Interface

Table C-6 shows the Wiegand assignments for colored-wire pair (13-pair) cable.

**Table C-6 Wiegand Interface Signal Wiring for Colored-Wire Pair Cable**

Signal from Encompass 4/4800 Multiprotocol Reader	Colored-Wire Pair Cable		Connect to Signal from Host
	Wire Pair from Encompass 4/4800 Multiprotocol Reader	Color Used	
Wiegand Zero Output	Blue/Red	Blue	Data0
Wiegand One Output		Red	Data1
Signal Ground	Yellow/Black	Yellow or Black	Ground

Table C-7 shows the Wiegand assignments for alternate wire (15-pair) cable.

**Table C-7 Wiegand Interface Signal Wiring for Alternate Wire Cable**

Signal from Encompass 4/4800 Multiprotocol Reader	Alternate Wire Cable		Connect to Signal from Host
	Pairing	Color	
Wiegand Zero output	Pair 10	Black	Data0
Wiegand One output		Red	Data1
Signal Ground	Pair 5	Black or Red	Ground

## Power Supply Connections

### AC Power

Table C-8 shows the colored-wire pair (13-pair) assignments for connection to a low-voltage AC power supply.

**Table C-8 AC Transformer Connections for Colored-Wire Pair Cable**

Signal From Encompass 4/4800 Multiprotocol Reader	Colored-Wire Pair Cable		Connect to Transformer Terminal Strip
	Wire Pair from Encompass 4/4800 Multiprotocol Reader	Color Used	
Main power input	Brown/Red and Orange/Red	Brown/Orange	L1 16-20 V AC
Main power return		Red/Red	L2 16-20 V AC

Table C-9 shows the alternate wire (15-pair) assignments for connection to a low-voltage AC power supply.

**Table C-9 AC Transformer Connections for Alternate Wire Cable**

Signal from Encompass 4/4800 Multiprotocol Reader	Alternate Wire Cable		Connect to Transformer Terminal Strip
	Pairing	Color	
Main power input	Pair 12 and Pair 13	Black/Black	L1 16-20 V AC
Main power return		Red/Red	L2 16-20 V AC

### Low-Voltage DC Power

Table C-10 shows the colored-wire pair (13-pair) assignments for connection to a low-voltage DC power supply.

**Table C-10 Low Voltage DC Cable Connections for Colored-Wire Pair Cable**

Signal from Encompass 4/4800 Multiprotocol Reader	Colored-Wire Pair Cable		Connection Use
	Wire Pair from Encompass 4/4800 Multiprotocol Reader	Color Used	
Main power input	Brown/Red and Orange/Red	Brown and Orange	16 to 28 V DC + terminal
Main power return		Red and Red	16 to 28 V DC – terminal

Table C-11 shows the alternate wire (15-pair) assignments for connection to a low-voltage DC power supply.

**Table C-11 Low Voltage DC Cable Connections for Alternate Wire Cable**

Signal from Encompass 4/4800 Multiprotocol Reader	Alternate Wire Cable		Connection Use
	Pairing	Color	
Main power input	Pair 12 and Pair 13	Black and Black	16 to 28 V DC + terminal
Main power return		Red and Red	16 to 28 V DC – terminal

## Input/Output Cabling Assignments

Table C-12 shows the sense input/output assignments for colored-wire pair (13-pair) cable.

**Table C-12 Sense Input/Output Cabling Assignments for Colored-Wire Pair Cable**

Pair	Pin	Color	Signal	Description	Typical Function
Blue/ Red	E	Blue	WGND0	Wiegand data0	Parking/access control applications
	F	Red	WGND1	Wiegand data1	Parking/access control applications
White/ Red	L	White	Lock	Tag lock output, active-closed	Testing maintenance
	M	Red	Lock_RTN	Tag lock return	Testing maintenance
Green/ Red	N	Green	Sense Input0	Sense Input0 (loop), active-closed	Loop and presence detection
	P	Red	Sense Input0_RTN	Sense Input0 return; not isolated from signal ground	Loop and presence detection
Blue/ Black	R	Blue	Sense Input1	Sense Input1, active-closed	General-purpose sense input, not used to detect presence
	S	Black	Sense Input1_RTN	Sense Input1 return; not isolated from signal ground	General-purpose sense input, not used to detect presence
Brown/ Black	T	Black	Sense Output0_COM	Sense Output0 (tag detect), common terminal	Switched output to control gate
	U	Brown	Sense Output0_NO	Sense Output0, normally open terminal	Switched output to control gate
Orange/ Black	V	Black	Sense Output0_COM	Sense Output0 (tag detect output), common terminal	Switched sense output for any external control (light, gate, buzzer, etc.)

**Table C-12 Sense Input/Output Cabling Assignments for Colored-Wire Pair Cable**

Pair	Pin	Color	Signal	Description	Typical Function
	W	Orange	Sense Output 0_NC	Sense Output0, normally closed terminal	Switched sense output for any external control (light, gate, buzzer, etc.)
Green/Black	X	Black	Sense Output1_COM	Sense Output1, common terminal	Switched sense output
	Y	Green	Sense Output1_NO	Sense Output1, normally open terminal	Switched sense output
White/Black	Z	Black	Sense Output1_COM	Sense Output1, common	Switched sense output
	a	White	Sense Output1_NC	Sense Output1, normally closed terminal	Switched sense output
Yellow/Black	b	Yellow	GND	logic ground	Signal ground (used with RS-232 and Wiegand communications)
	c	Black	GND	logic ground	Signal ground (used with RS-232 and Wiegand communications)

Table C-13 shows the sense input/output assignments for alternate wire (15-pair) cable.-

**Table C-13 Sense Input/Output Cabling Assignments for Alternate Wire Cable**

Alternate Wire Cable			Signal	Description	Typical Function
Pairing	Pin	Color			
Pair 10	E	Black	WGND0	Wiegand data0	Parking/access control applications
	F	Red	WGND1	Wiegand data1	Parking/access control applications
Pair 8	L	Black	Lock	Tag lock sense output, active-closed	Testing maintenance
	M	Red	Lock_RTN	Tag lock return	Testing maintenance

**Table C-13 Sense Input/Output Cabling Assignments for Alternate Wire Cable**

Alternate Wire			Signal	Description	Typical Function
Pairing	Pin	Color			
Pair 9	N	Black	Sense Input0	Sense Input0 (loop), active-closed	Loop and presence detection
	P	Red	Sense Input0_RTN	Sense Input0 return; not isolated from signal ground	Loop and presence detection
Pair 4	R	Black	Sense Input1	Sense Input1, active-closed	General-purpose sense input, not used to detect presence
	S	Red	Sense Input1_RTN	Sense Input1 return; not isolated from signal ground	General-purpose sense input, not used to detect presence
Pair 6	T	Black	Sense Output0_COM	Sense Output0 (tag detect), common terminal	Switched sense output to control gate
	U	Red	Sense Output0_NO	Sense Output0, normally open terminal	Switched sense output to control gate
Pair 7	V	Black	Sense Output0_COM	Sense Output0 (tag detect output), common terminal	Switched sense output for any external control (light, gate, buzzer, etc.)
	W	Red	Sense Output0_NC	Sense Output0, normally closed terminal	Switched sense output for any external control (light, gate, buzzer, etc.)
Pair 3	X	Black	Sense Output1_COM	Sense Output1, common terminal	Switched sense output
	Y	Red	Sense Output1_NO	Sense Output1, normally open terminal	Switched sense output
Pair 2	Z	Black	Sense Output1_COM	Sense Output1, common terminal	Switched sense output
	a	Red	Sense Output1_NO	Sense Output1, normally closed terminal	Switched sense output
Pair 5	b	Black	GND	logic ground	Signal ground (used with RS-232 and Wiegand communications)



**Table C-13 Sense Input/Output Cabling Assignments for Alternate Wire Cable**

Alternate Wire			Signal	Description	Typical Function
Pairing	Pin	Color			
	c	Red	GND	logic ground	Signal ground (used with RS-232 and Wiegand communications)

## Summary Table

Table C-14 shows all assignments for both colored-wire pair (13-pair) and alternate wire (15-pair) cables.

**Table C-14 All Cabling Assignments for Colored-Wire Pair Cable or Alternate Wire Cable**

Colored-Wire Pair Cable			Alternate Wire Cable		Signal	Description	Typical Function
Pair	Pin	Color	Pair	Color			
Red/Black	A	Black	Pair 1	Black	TX232, RX422+, IF485-	RS-232 transmit, RS-422 receive positive, RS-485 negative	Encompass 4/4800 Multiprotocol Reader output, host input
	B	Red		Red	RX232, RX422-, IF485+	RS-232 receive, RS-422 receive negative, RS-485 positive	Encompass 4/4800 Multiprotocol Reader input, host output
Yellow/Red	C	Yellow	Pair 11	Black	RTS232, TX422	RS-232 request to send or RS-422 transmit positive	Encompass 4/4800 Multiprotocol Reader output, host input for hardware handshaking
	D	Red		Red	CTS232, TX422	RS-232 clear to send or RS-422 transmit negative	Encompass 4/4800 Multiprotocol Reader input, host output for hardware handshaking
Blue/Red	E	Blue	Pair 10	Black	WGND0	Wiegand data0	Parking/access control applications
	F	Red		Red	WGND1	Wiegand data1	Parking/access control applications
Orange/Red	G	Orange	Pair 13	Black	18V	Main power input	
	H	Red		Red	18V_RTN	Main power return	

Table C-14 All Cabling Assignments for Colored-Wire Pair Cable or Alternate Wire Cable (continued)

Colored-Wire Pair Cable			Alternate Wire Cable		Signal	Description	Typical Function
Pair	Pin	Color	Pair	Color			
Brown/ Red	J	Brown	Pair 12	Black	18V	Main power input	
	K	Red		Red	18V_RTN	Main power return	
White/ Red	L	White	Pair 8	Black	Lock	Tag lock sense output, active-closed	Testing maintenance
	M	Red		Red	Lock_RTN	Tag lock return	Testing maintenance
Green/ Red	N	Green	Pair 9	Black	Sense Input0	Sense input0 (loop), active-closed	Loop and presence detect
	P	Red		Red	Sense Input0_RTN	Sense input0 return; not isolated from signal ground	Loop and presence detect
Blue/ Black	R	Blue	Pair 4	Black	Sense Input1	Sense input1, active-closed	General-purpose sense input, not used to detect presence.
	S	Black		Red	Sense Input1_RTN	Sense input1 return; not isolated from signal ground	General-purpose sense input, not used to detect presence.
Brown/ Black	T	Black	Pair 6	Black	Sense Output0_COM	Sense output0 (tag detect), common terminal	Switched sense output to control gate
	U	Brown		Red	Sense Output0_NO	Sense output0, normally open terminal	Switched sense output to control gate
Orange/ Black	V	Black	Pair 7	Black	Sense Output0_COM	Sense output0 (tag detect output), common terminal	Switched sense output for any external control (light, gate, buzzer, etc.)
	W	Orange		Red	Sense Output0_NC	Sense output0, normally closed terminal	Switched sense output for any external control (light, gate, buzzer, etc.)

Table C-14 All Cabling Assignments for Colored-Wire Pair Cable or Alternate Wire Cable (continued)

Colored-Wire Pair Cable			Alternate Wire Cable		Signal	Description	Typical Function
Pair	Pin	Color	Pair	Color			
Green/Black	X	Black	Pair 3	Black	Sense Output1_COM	Sense output1, common terminal	Switched sense output.
	Y	Green		Red	Sense Output1_NO	Sense output1, normally open terminal	Switched sense output
White/Black	Z	Black	Pair 2	Black	Sense Output1_COM	Sense output1, common terminal	Switched sense output
	a	White		Red	Sense Output1_NC	Sense output1, normally closed terminal	Switched sense output
Yellow/Black	b	Yellow	Pair 5	Black	GND	logic ground	Signal ground (used with RS-232 and Wiegand communications)
	c	Black		Red	GND	logic ground	Signal ground (used with RS-232 and Wiegand communications)

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# D

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## Command Quick Reference

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## Command Quick Reference

*This appendix lists the default configuration settings for the Encompass™ 4/4800 Multiprotocol Reader and its commands. Commands are listed both numerically and alphabetically.*

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### Command Syntax

The command numbers consist of from 2 to 4 hex digits. The letters N or S may follow a command number. The letter N indicates that part of the command number is variable. The letter S indicates the requirement for an alphanumeric data string that is to be included immediately following the command number. Hex digits (0–9, A–F) in either uppercase or lowercase characters may be used in data strings and for hex digits A–F. For more information see Chapter 5, “General Software Information.”

Table D-1 lists factory default settings. Table D-2 on page D-6 lists, in numerical order, all of the commands available to users. Table D-3 on page D-16 lists the same commands by command name.

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### Factory Default Settings

**Note:** [Table D-1](#) lists the factory default settings for the Encompass 4/4800 Multiprotocol Reader.

**Table D-1 Encompass 4/4800 Multiprotocol Reader Default Configuration Settings**

Parameter	Setting	Command
Operating mode	Data	00
Baud rate	9600	1005
Stop bits	1	1010
Parity	None	1020
Auxiliary information appended	Disabled	310
Unique ID code criteria	Separation of 1 ID	4100
Wiegand mode	Disabled	450
Alternative group select	Disabled	452

**Table D-1 Encompass 4/4800 Multiprotocol Reader Default Configuration Settings (continued)**

Parameter	Setting	Command
Multi-tag sort	Disabled	454
eGo tag initialization during multi-tag sort	Enabled	456
Second alternative group select	Disabled	458
Wiegand transmit mode	1 second	4601
Select tag mode	eATA mode	473
Third alternative group select	Disabled	490
Fourth alternative group select	Disabled	492
Fifth alternative group select	Disabled	494
Reader ID number	00	6000
Communications protocol	Basic	610
Error correcting protocol (ECP) timeout	12.7 sec <sup>b</sup>	612FE
Flow control	Software (XON/XOFF)	6141
Echo mode	Enabled	6171
Sense output control	Predefined	621
RF-by-input control	Enabled	641
RF operating frequency <sup>a</sup>	915MHz	6421A
ATA operating range	Maximum	6431F
RF attenuation	Full power	64400
Encompass 4/4800 Multiprotocol Reader operating range	Maximum	6451F
Sense output pulse duration	228 ms <sup>b</sup>	67C
Presence without tag reports	Disabled	6900
RF-off control	Timeout or no presence	6922
RF timeout	Never true	693F
Input inversion	Disabled	6940
Serial number	NNNNNN	695



**Table D-1 Encompass 4/4800 Multiprotocol Reader Default Configuration Settings (continued)**

Parameter	Setting	Command
Store hardware configuration	Hardware configuration not known	696
Input status change reports	Disabled	820
Automatic periodic RF status report	Disabled	830

- a. Local laws apply. The authorized frequency band for the TransCore Encompass 4/4800 Multiprotocol Reader in the United States is 912.5 MHz to 919 MHz. Contact TransCore if your application requires a frequency outside of this range.
- b. The Encompass 4/4800 Multiprotocol Reader system does not include a real-time clock. The dual-protocol Encompass 4/4800 Multiprotocol Reader internal timing varies depending on the operative tag read mode and the type of tag in the read field. Unless stated otherwise, values listed for timing-related command variables assume an ID operational tag read mode (64-bit ID data from eGo tags, ignore ATA tags) and an eGo-compatible tag in the read field and these values may vary.

## Numerical Command List

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The following conventions are used in Table D-2:

- Items in ***bold italics*** identify factory default settings.
- Only the command-related data portion of the reader message is shown.
- A single asterisk (\*) indicates that the command has been altered so that it is different from the AI1620 SmartPass command.
- A double asterisk (\*\*) indicates a new command or added value that is not present in the AI1620 SmartPass command list.
- A triple asterisk (\*\*\*) indicates an Encompass 4/4800 Multiprotocol Reader command that is supported only in the Encompass 4/4800 Multiprotocol Reader Software Version TBD.

Refer to [Chapter 6, “Communication Protocols,”](#) for the complete syntax of commands and messages.

The Encompass 4/4800 Multiprotocol Reader system does not include a real-time clock. The dual-protocol Encompass 4/4800 Multiprotocol Reader internal timing varies depending on the operative tag read mode and the type of tag in the read field. Unless stated otherwise, values listed for timing-related command variables assume an ID operational tag read mode (64-bit ID data from eGo tags, ignore ATA tags) and an eGo tag in the read field and these values may vary. See [Chapter 7, “Commands”](#) for more information.

**Table D-2 Encompass 4/4800 Multiprotocol Reader Commands Listed Numerically**

Number	Command Name	Reader Message
<b>00</b>	<b>Switch to data mode</b>	<b>Done</b>
01	Switch to command mode	Done
05	Switch to download mode	Done
1002***	Set baud rate = 1200 baud	Done or Error
1003	Set baud rate = 2400 baud	Done or Error
1004	Set baud rate = 4800 baud	Done or Error
<b>1005</b>	<b>Set baud rate = 9600 baud</b>	<b>Done or Error</b>
1006	Set baud rate = 19.2 K baud	Done or Error
1007**	Set baud rate = 38.4 K baud	Done or Error
<b>1010</b>	<b>Use one stop bit</b>	<b>Done</b>
1011	Use two stop bits	Done
<b>1020</b>	<b>Disable parity</b>	<b>Done</b>
1021	Select even parity	Done
1022	Select odd parity	Done
<b>310</b>	<b>Disable aux info append</b>	<b>Done or Error</b>
311	Enable aux info append	Done or Error
40	Transmit all IDs	Done or Error
<b>4100</b>	<b>Select one ID separation</b>	<b>Done</b>
4101	Select two ID separation	Done
<b>450</b>	<b>Disable Wiegand mode</b>	<b>Done</b>
451	Enable Wiegand mode	Done or Error
<b>452</b>	<b>Disable alternative group select</b>	<b>Done</b>
453	Enable alternative group select	Done or Error
<b>454</b>	<b>Disable multi-tag sort</b>	<b>Done</b>
455	Enable multi-tag sort	Done or Error
<b>456***</b>	<b>Enable eGo tag initialization during multi-tag sort</b>	<b>Done or Error</b>

**Table D-2 Encompass 4/4800 Multiprotocol Reader Commands Listed Numerically (continued)**

Number	Command Name	Reader Message
457***	Disable eGo tag initialization during multi-tag sort	Done
<b>458***</b>	<b>Disable second alternative group select</b>	<b>Done</b>
459***	Enable second alternative group select	Done or Error
<b>46NN</b>	<b>Set Wiegand retransmit interval NN = 01–FF seconds</b> <b>01 =factory default</b>	<b>Done or Error</b>
47N**	Select tag mode N = 0–4 0 = Dual (1); eATA (128 bits) and ATA tags 1 = ATA tags only 2 = eATA ID only (64 bits) <b>3 = eATA (128 bits) tags only, default</b> 4 = eATA ID (64 bits) and ATA tags 7 = eATA ID (64 bits) no EAC check	Done or Error
<b>490***</b>	<b>Disable third alternative group select</b>	<b>Done</b>
491***	Enable third alternative group select	Done or Error
<b>492***</b>	<b>Disable fourth alternative group select</b>	<b>Done</b>
493***	Enable fourth alternative group select	Done or Error
<b>494***</b>	<b>Disable fifth alternative group select</b>	<b>Done</b>
495***	Enable fifth alternative group select	Done or Error
505	Display version	Model [model] Ver [version no.] SN [serial no.]
506	Display hardware configuration information	S...S S...S = ASCII string (maximum length of 20 characters)

**Table D-2 Encompass 4/4800 Multiprotocol Reader Commands Listed Numerically (continued)**

Number	Command Name	Reader Message
520	Display power fail bit	PWRB Px R0 P0 = no power fail has occurred P1 = power fail has occurred
521	Display reader ID number	RDID xx xx = 00–FF
522*	Display comm port parameters*	MAIN Bx Sx Px D0 B0 = 110* B1 = 300* B2 = 1200* B3 = 2400 B4 = 4800 B5 = 9600 B6 = 19.2 B7** = 38.4 S0 = one stop bit S1 = two stop bits P0 = no parity P1 = even P2 = odd D0 = EOL delay of 0 ms
524*	Display appended info status*	IDAP T0 D0 Xx T0 = time not appended T1* = time appended * D0 = date not appended D1* = date appended* X0 = aux info not appended X1 = aux info appended
525*	Display comm protocol*	ECPS Px Txx Xx S0 P0 = basic P1 = ECP P2 = echo Inquiry Txx = ECP timeout ms = 50 * xx FF = disabled ECP timeout X0 = no flow control X1 = software flow control X2 = hardware flow control S0 = som character is #

**Table D-2 Encompass 4/4800 Multiprotocol Reader Commands Listed Numerically (continued)**

Number	Command Name	Reader Message
526	Display I/O status	IOST Cx Ox lx Dx C0 = host controls outputs C1 = predefined output mode O0 = both outputs off O1 = output0 on O2 = output1 on O3 = both outputs on I0 = both inputs false I1 = input0 true I2 = input1 true I3 = both inputs true D0 - DF = output pulse duration D0 to D8: 48 ms (ID, IATA, Dual 1, and Dual 2 modes) 130 ms (ATA single mode) D9: 60 ms (ID, eATA, Dual 1, and Dual 2 modes) 140 ms (ATA single mode) DA: 76 ms (ID, eATA, Dual 1, and Dual 2 modes) 190 ms (ATA single mode) DB: 152 ms (ID, eATA, Dual 1, and Dual 2 modes) 300 ms (ATA single mode) <b>DC: 228 ms (ID, eATA, Dual 1, and Dual 2 modes) (factory default);                      450 ms (ATA single mode)</b> DD: 300 ms (ID, eATA, Dual 1, and Dual 2 modes) 550 ms (ATA single mode) DE: 376 ms (ID, eATA, Dual 1, and Dual 2 modes) 700 ms (ATA single mode) DF: 752 ms (ID, eATA, Dual 1, and Dual 2 modes) 1300ms (ATA single mode)

**Table D-2 Encompass 4/4800 Multiprotocol Reader Commands Listed Numerically (continued)**

Number	Command Name	Reader Message
527**	Display RF status	RFST Cx Ox T1 Fxx Rxx C0 = RF controlled by host C1 = RF-by-input control O0 = RF off O1 = RF on T1 = uniqueness timeout of 2 min Fxx = RF output frequency, 00 to 34 Rxx** = Tag decoder range (distance) for ATA tags, xx = 00 to 1F hexadecimal range value GXX** = Tag decoder range (distance) for Intellitag tags, 00 to 1F hexadecimal range value Axx** = RF power attenuation, 00 max to 0A min (10db less than max)

**Table D-2 Encompass 4/4800 Multiprotocol Reader Commands Listed Numerically (continued)**

Number	Command Name	Reader Message
529	Display presence input status	<p>PRST Px D0 Ax Tx Ix                      P0 = disable presence w/o tag reports                      P1 = enable presence w/o tag reports                      D0 = min presence true period of 0 ms                      A0 = RF off on timeout                      A1 = RF off on timeout or tag                      A2 = RF off on timeout or no presence                      T0: RF timeout of 0 ms (always expired)                      T1 to T7: RF timeout of 48 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 150 ms (ATA single mode)                      T8: RF timeout of 60 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 175 ms (ATA single mode)                      T9: RF timeout of 92 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 200 ms (ATA single mode)                      TA: RF timeout of 152 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 370 ms (ATA single mode)                      TB: RF timeout of 300 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 680 ms (ATA single mode)                      TC: RF timeout of 452 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 1000 ms (ATA single mode)                      TD: RF timeout of 600 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 1250 ms (ATA single mode)                      TE: RF timeout of 752 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 1500 ms (ATA single mode)  <b>TF: RF timeout infinite, never expires (factory default)</b>  <b>I0 = Input inversion disabled (factory default)</b>                      I1 = Input inversion enabled</p>

**Table D-2 Encompass 4/4800 Multiprotocol Reader Commands Listed Numerically (continued)**

Number	Command Name	Reader Message
530*	Display RF0 filter status	RF0S Ux V0 U0 = one ID separation U1 = two ID U2 = transmit all V0 = valid ID code criteria of one acquisition (fixed)
532	Display Wiegand mode status	TOF x 0 = disabled 1 = enabled
533	Display Wiegand retransmit interval	WTI xx xx = 01–FF seconds
537	Display echo status	ECHO x 0 = disabled 1 = enabled
540	Display flash checksum	PCKS I0000 Exxxx xxxx = 4-byte ASCII checksum
543	Display boot checksum	BCKS xxxx xxxx = 4-byte ASCII checksum
560	Display input status change	SSTC Ex Mx E0 = status change reports disabled E1 = status change reports enabled M0 = no reporting M1 = report change on input0 M2 = report change on input1 M3 = report change on either input
570	Display tag mode status	IT500:x ATA:x I = IT500 ID (64 bits) E = enabled F = full transaction D = disabled M = multi-tag sort enabled NI = No EAC check
<b>60NN</b>	<b>Set reader ID number NN = 00–FF (00 = factory default)</b>	<b>Done</b>
<b>610</b>	<b>Select basic protocol</b>	<b>Done or Error</b>
611	Select ECP protocol	Done or Error



**Table D-2 Encompass 4/4800 Multiprotocol Reader Commands Listed Numerically (continued)**

Number	Command Name	Reader Message
612NN	Set ECP timeout NN = 01–FE (1–255) timeout = 50 ms * NN (if NN = FF, timeout is disabled)	Done or Error
<b>612FE</b>	<b>Set ECP timeout = 12.7 sec</b>	<b>Done or Error</b>
6140	Disable flow control	Done
<b>6141</b>	<b>Enable software flow control</b>	<b>Done</b>
6142	Enable hardware flow control	Done
6170	Disable echo	Done
<b>6171</b>	<b>Enable echo</b>	<b>Done or Error</b>
6200	Turn both outputs off	Done
6201	Turn output0 on	Done
6202	Turn output1 on	Done
6203	Turn both outputs on	Done
<b>621</b>	<b>Select predefined output mode</b>	<b>Done</b>
63	Reset reader	Model [model] Ver [version no.] SN [serial no.] Copyright [date] TransCore
6400	Turn RF off	Done
6401	Turn RF on	Done
6402*	Turns on continuous wave RF until commands 6400, 6401, or 641 are received by the reader*	Done
<b>641</b>	<b>Select RF-by-input control</b>	<b>Done</b>
642NN	Set RF operating frequency from 902 to 928 in 500 kHz steps NN = 01- 34  <b>Caution: in the U.S., authorized frequency band for Encompass 4/4800 Multiprotocol Readers is 912.5 to 919 MHz; 64215 to 64222</b>	Done

**Table D-2 Encompass 4/4800 Multiprotocol Reader Commands Listed Numerically (continued)**

Number	Command Name	Reader Message
643NN	Set ATA operating range NN = 00 (shortest) to 1F (longest) <b>1F = default</b>	Done
644NN**	Set attenuation** NN = 00 to 0A	Done
645NN**	Set Encompass 4/4800 Multiprotocol Reader operating range** NN = 00 (shortest) to 1F (longest)	Done
65	Reset power fail bit	Done
66F	Load default operating parameters	Done or Error
67N	Set output pulse duration N = 0–F (4,8,12,16,20,24,32,40,48, 60,76,152,228,300,376, 752 ms)	Done or Error
<b>67C</b>	<b>Set output pulse duration = 228 ms</b>	<b>Done or Error</b>
<b>6900</b>	<b>Disable presence without tag reports</b>	<b>Done</b>
6901	Enable presence without tag reports	Done
6920	Turn RF off on timeout	Done
6921	Turn RF off on timeout/tag	Done
<b>6922</b>	<b>Turn RF off on timeout/no presence</b>	<b>Done</b>
693N	Set RF timeout N = 0–F (always expired, 4,8,12,20,24, 32,48,60,92,152, 300,452, 600,752, infinite)	Done or Error
<b>693F</b>	<b>Set RF timeout = infinite</b>	<b>Done</b>
<b>6940</b>	<b>Disable input inversion</b>	<b>Done</b>
6941	Enable input inversion	Done

**Table D-2 Encompass 4/4800 Multiprotocol Reader Commands Listed Numerically (continued)**

Number	Command Name	Reader Message
<b>695S...S</b>	<b>Set serial number</b> <b>S...S = ASCII string</b> <b>(maximum length of 6 characters)</b>	<b>Done</b>
<b>696S...S</b>	<b>Store hardware configuration string</b> <b>S...S = ASCII string</b> <b>(maximum length of 20 characters)</b>	<b>Done</b>
<b>820</b>	<b>Disable status change reports</b>	<b>Done</b>
821	Report change on input0	Done
822	Report change on input1	Done
823	Report changes on both	Done
<b>830***</b>	<b>Disable automatic periodic RF status report</b>	<b>Done</b>
831***	Enable automatic periodic RF status report	Done or Error
90	Load program block	Done, Checksum Error, Program Error, or Verify Error
91	Verify flash checksum	Done or Error
96	Erase flash memory	Done
97	Perform destructive flash test	Done or Error
99	Exit download mode	Model [model] Ver [ver no.] SN [serial no.] Copyright [date] TransCore

## Alphabetical Command List

The following conventions are used in [Table D-3](#):

- Items in ***bold italics*** identify factory default settings.
- Only the command-related data portion of the reader message is shown.
- A single asterisk (\*) indicates that the command has been altered so that it is different from the A11620 SmartPass command.
- A double asterisk (\*\*) indicates a new command or added value that is not present in the A11620 SmartPass command list.
- A triple asterisk (\*\*\*) indicates an Encompass 4/4800 Multiprotocol Reader command that is supported only in the Encompass 4/4800 Multiprotocol Reader Software Version TBD.

The Encompass 4/4800 Multiprotocol Reader system does not include a real-time clock. The dual-protocol Encompass 4/4800 Multiprotocol Reader internal timing varies depending on the operative tag read mode and the type of tag in the read field. Unless stated otherwise, values listed for timing-related command variables assume an ID operational tag read mode (read 64-bit ID data from eGo tags, ignore ATA tags) and an eGo tag in the read field and these values may vary. See [Chapter 7, “Commands,”](#) for more information.

Refer to [Chapter 7](#) for the complete syntax of commands and messages.

**Table D-3 Encompass 4/4800 Multiprotocol Reader Commands Listed Alphabetically**

Command Name	Code	Reader Message
All IDs transmit	40	Done
<b><i>Alternative group select disable</i></b>	<b>452</b>	<b>Done</b>
Alternative group select enable	453	Done or Error
<b><i>Alternative fifth group select disable</i></b> ***	<b>494</b> ***	<b>Done</b>
Alternative fifth group select enable***	495***	Done or Error
<b><i>Alternative fourth group select disable</i></b> ***	<b>492</b> ***	<b>Done</b>
Alternative fourth group select enable***	493***	Done or Error

**Table D-3 Encompass 4/4800 Multiprotocol Reader Commands Listed Alphabetically (continued)**

Command Name	Code	Reader Message
<b>Alternative second group select disable***</b>	<b>458***</b>	<b>Done</b>
Alternative second group select enable***	459***	Done or Error
<b>Alternative third group select disable***</b>	<b>490***</b>	<b>Done</b>
Alternative third group select enable***	491***	Done or Error
Appended info status display*	524*	IDAP T0 D0 Xx T0 = time not appended T1 = time appended* D0 = date not appended D1 = date appended* X0 = aux info not appended X1 = aux info appended
ATA operating range set NN = 00 (shortest) to 1F (longest) <b>1F = default</b>	643NN	Done
<b>Automatic periodic RF status report disable***</b>	<b>830***</b>	<b>Done</b>
Automatic periodic RF status report enable***	831***	Done
<b>Aux info append disable</b>	<b>310</b>	<b>Done or Error</b>
Aux info append enable	311	Done or Error
<b>Basic protocol select</b>	<b>610</b>	<b>Done or Error</b>
Baud rate = 1200 baud set***	1002***	Done or Error
Baud rate = 19.2 K baud set	1006	Done or Error
Baud rate = 2400 baud set	1003	Done or Error
Baud rate = 38.4 K baud set**	1007**	Done or Error
Baud rate = 4800 baud set	1004	Done or Error
<b>Baud rate = 9600 baud set</b>	<b>1005</b>	<b>Done or Error</b>
Boot checksum display	543	BCKS xxxx xxxx = 4-byte ASCII checksum

**Table D-3 Encompass 4/4800 Multiprotocol Reader Commands Listed Alphabetically (continued)**

Command Name	Code	Reader Message
Comm port parameters display*	522*	MAIN Bx Sx Px D0 B0 = 110* B1 = 300* B2 = 1200* B3 = 2400 B4 = 4800 B5 = 9600 B6 = 19.2 B7 = 38.4 S0 = one stop bit S1 = two stop bits P0 = no parity P1 = even P2 = odd D0 = EOL delay of 0 ms
Comm protocol display*	525*	ECPS Px Txx Xx S0 P0 = basic P1 = ECP P2 = data inquiry Txx = ECP timeout ms = 50 * xx TFF = disabled ECP timeout X0 = no flow control X1 = software flow control X2 = hardware flow control S0 = SOM character is #
Command mode switch	01	Done
Data mode switch	00	Done
Default operating parameters load	66F	Done or Error
Destructive flash test perform	97	Done or Error
Diagnostic results display	661	DIAG Rx Ex Dx C1 R0 = boot ROM OK R1 = boot failed E0 = flash memory OK E1 = flash failed D0 = external RAM OK D1 = RAM failed C0 = RTC OK* C1 = RTC failed
Diagnostics perform all (Use 661 to display diagnostic results.)	669	Done or Error

**Table D-3 Encompass 4/4800 Multiprotocol Reader Commands Listed Alphabetically (continued)**

Command Name	Code	Reader Message
Download mode exit	99	Model [model] Ver [ver no.] SN [serial no.] Copyright [date] AMTECH
Download mode switch	05	Done
Echo disable	6170	Done
<b>Echo enable</b>	<b>6171</b>	<b>Done or Error</b>
Echo status display	537	ECHO x 0 = disabled 1 = enabled
ECP protocol select	611	Done or Error
<b>ECP timeout set = 12.7 sec set</b>	<b>612FE</b>	<b>Done or Error</b>
ECP timeout set NN = 01–FE (1–255) timeout = 50 ms * NN (if NN = FF, timeout is disabled)	612NN	Done or Error
<b>eGo tag initialization during multi-tag sort***</b>	<b>456***</b>	<b>Done or Error</b>
eGo tag initialization during multi-tag sort***	457***	Done or Error
Even parity select	1021	Done
Flash checksum display	540	PCKS I0000 Exxxx xxxx = 4-byte ASCII checksum
Flash checksum verify	91	Done or Error
Flash memory checksum verify	668	Done or Error
Flash memory erase	96	Done
Flow control disable	6140	Done
<b>Flow control enable</b>	<b>6141</b>	<b>Done</b>
Hardware configuration information display	506	S...S S...S = ASCII string (maximum length of 20 characters)

**Table D-3 Encompass 4/4800 Multiprotocol Reader Commands Listed Alphabetically (continued)**

Command Name	Code	Reader Message
<b>Hardware configuration string store</b> <i>S...S = ASCII string (maximum length of 20 characters)</i>	<b>696S...S</b>	<b>Done</b>
Hardware flow control enable	6142	Done
I/O status display	526	<p>IOST Cx Ox lx Dx            C0 = host controls outputs            C1 = predefined output mode            O0 = both outputs off            O1 = output0 on            O2 = output1 on            O3 = both outputs on            I0 = both inputs false            I1 = input0 true            I2 = input1 true            I3 = both inputs true            D0–DF = output pulse duration</p> <p>D0 to D8: 48 ms (ID, IATA, Dual 1, and Dual 2 modes)            130 ms (ATA single mode)</p> <p>D9: 60 ms (ID, eATA, Dual 1, and Dual 2 modes)            140 ms (ATA single mode)</p> <p>DA: 76 ms (ID, eATA, Dual 1, and Dual 2 modes)            190 ms (ATA single mode)</p> <p>DB: 152 ms (ID, eATA, Dual 1, and Dual 2 modes)            300 ms (ATA single mode)</p> <p><b>DC: 228 ms (ID, eATA, Dual 1, and Dual 2 modes)(factory default);            450 ms (ATA single mode)</b></p> <p>DD: 300 ms (ID, eATA, Dual 1, and Dual 2 modes)            550 ms (ATA single mode)</p> <p>DE: 376 ms (ID, eATA, Dual 1, and Dual 2 modes)            700 ms (ATA single mode)</p> <p>DF: 752 ms (ID, eATA, Dual 1, and Dual 2 modes)            1300ms (ATA single mode)</p>
<b>Input inversion disable</b>	<b>6940</b>	<b>Done</b>
Input inversion enable	6941	Done



**Table D-3 Encompass 4/4800 Multiprotocol Reader Commands Listed Alphabetically (continued)**

Command Name	Code	Reader Message
Input status change display	560	SSTC Ex Mx E0 = status change reports disabled E1 = status change reports enabled M0 = no reporting M1 = report change on input0 M2 = report change on input1 M3 = report change on either input
Input0 change report	821	Done
Input1 change report	822	Done
<b>Multi-tag sort disable</b>	<b>454</b>	<b>Done</b>
Multi-tag sort enable	455	Done or Error
Odd parity select	1022	Done
<b>Output pulse duration = 228 ms set</b>	<b>67C</b>	<b>Done or Error</b>
Output pulse duration set N = 0–F (4,8,12,16,20,24,32,40,48,60,76, 152, 228,300,376,752 ms)	67N	Done or Error
Output0 turn on	6201	Done
Output1 turn on	6202	Done
Outputs turn off both	6200	Done
Outputs turn on both	6203	Done
<b>Parity disable</b>	<b>1020</b>	<b>Done</b>
Power fail bit display	520	PWRB Px R0 P0 = no power fail has occurred P1 = power fail has occurred
Power fail bit reset	65	Done
<b>Predefined output mode select</b>	<b>621</b>	<b>Done</b>

**Table D-3 Encompass 4/4800 Multiprotocol Reader Commands Listed Alphabetically (continued)**

Command Name	Code	Reader Message
Presence input status display	529	<p>PRST Px D0 Ax Tx Ix                      P0 = disable presence w/o tag reports                      P1 = enable presence w/o tag reports                      D0 = min presence true period of 0 ms                      A0 = RF off on timeout                      A1 = RF off on timeout or tag                      A2 = RF off on timeout or no presence                      T0: RF timeout of 0 ms (always expired)                      T1 to T7: RF timeout of 48 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 150 ms (ATA single mode)                      T8: RF timeout of 60 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 175 ms (ATA single mode)                      T9: RF timeout of 92 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 200 ms (ATA single mode)                      TA: RF timeout of 152 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 370 ms (ATA single mode)                      TB: RF timeout of 300 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 680 ms (ATA single mode)                      TC: RF timeout of 452 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 1000 ms (ATA single mode)                      TD: RF timeout of 600 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 1250 ms (ATA single mode)                      TE: RF timeout of 752 ms (ID, eATA, Dual 1, and Dual 2 modes); RF timeout of 1500 ms (ATA single mode)</p> <p><b>TF: RF timeout infinite, never expires (factory default)</b>  <b>I0 = Input inversion disabled (factory default)</b>                      I1 = Input inversion enabled</p>
<b>Presence without tag reports disable</b>	<b>6900</b>	<b>Done</b>

**Table D-3 Encompass 4/4800 Multiprotocol Reader Commands Listed Alphabetically (continued)**

Command Name	Code	Reader Message
Presence without tag reports enable	6901	Done
Program block load	90	Done, Checksum Error, Program Error, or Verify Error
Reader ID number display	521	RDID xx xx = 00–FF
<b>Reader ID number set NN = 00-FF (00 = factory default)</b>	<b>60NN</b>	<b>Done</b>
Reader reset	63	Model [model] Ver [ver no.] SN [serial no.] Copyright [date] AMTECH
Report changes both	823	Done
RF attenuation set**	644NN**	Done or Error
RF continuous wave on until commands 6400, 6401, or 641 are received by reader*	6402*	Done
RF off	6400	Done
RF off on timeout	6920	Done
<b>RF off on timeout/no presence</b>	<b>6922</b>	<b>Done</b>
RF off on timeout/tag	6921	Done
RF on	6401	Done
<b>RF on by input control</b>	<b>641</b>	<b>Done</b>
RF operating frequency set from 902 to 928 in 500 kHz steps NN = 01- 34 <b>Caution: in the U.S., authorized frequency band for Encompass 4/4800 Multiprotocol Readers is 912.5 to 919 MHz; 64215 to 64222</b>	642NN	Done
RF operating range set** NN = 00 (shortest) to 1F (longest)	645NN**	Done

**Table D-3 Encompass 4/4800 Multiprotocol Reader Commands Listed Alphabetically (continued)**

Command Name	Code	Reader Message
RF status display**	527**	RFST Cx Ox T1 Fxx Rxx C0 = RF controlled by host C1 = RF-by-input control O0 = RF off O1 = RF on T1 = uniqueness timeout of 2 min Fxx = RF output frequency, 00 to 34 Rxx** = Tag decoder range (distance) for ATA tags, xx = 00 to 1F hexadecimal range value GXX** = Tag decoder range (distance) for Intellitag tags, 00 to 1F hexadecimal range value Axx** = RF power attenuation, 00 max to 0A min (10db less than max)
<b>RF timeout = infinite set</b>	<b>693F</b>	<b>Done</b>
RF timeout set N = 0–F (always expired, 4,8,12,20,24,32,48,60,92,152,300,452,600,752 ms, infinite)	693N	Done or Error
RF0 filter status display*	530*	RF0S Ux V0 U0 = one ID separation U1 = two ID U2 = transmit all
<b>Serial number set</b> <b>S...S = ASCII string</b> <b>(maximum length of 6 characters)</b>	<b>695S...S</b>	<b>Done</b>
<b>Status change reports disable</b>	<b>820</b>	<b>Done</b>
<b>Stop bit use one</b>	<b>1010</b>	<b>Done</b>
Stop bit use two	1011	Done
<b>Tag ID separation select one</b>	<b>4100</b>	<b>Done</b>
Tag ID separation select two	4101	Done

**Table D-3 Encompass 4/4800 Multiprotocol Reader Commands Listed Alphabetically (continued)**

Command Name	Code	Reader Message
Tag mode select** N = 0–4 0 = Dual (1); eATA (128 bits) and ATA tags 1 = ATA tags only 2 = eATA ID only (64 bits) <b>3 = eATA (128 bits) tags only, default</b> 4 = eATA ID (64 bits) and ATA tags 7 = eATA ID (64 bits) no EAC check	47N**	Done or Error
Tag mode display	570	IT500:x ATA:x I = IT500 ID (64 bits) E = enabled F = full transaction D = disabled M = multi-tag sort enabled NI = no EAC check
Version display	505	Model [model] Ver [ver no.] SN [serial no.]
<b>Wiegand mode disable</b>	<b>450</b>	<b>Done</b>
Wiegand mode enable	451	Done
Wiegand mode status display	532	T0F x 0 = disabled 1 = enabled
Wiegand retransmit interval display	533	WTI xx xx = 01–FF seconds
<b>Wiegand retransmit interval set NN = 01–FF seconds</b>	<b>46NN</b>	<b>Done or Error</b>

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## Compatible Tag Information

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## Appendix E

# Compatible Tag Information

*This appendix gives helpful information about the tags that are compatible with the Encompass™ 4/4800 Multiprotocol Reader.*

## Tag Configurations

Table E-1 and Table E-2 list most tag models that are compatible with the Encompass 4/4800 Multiprotocol Reader.

**Table E-1 ATA Protocol Tags**

Tag Model Number	TagType	Power Source	Number of 6-Bit ASCII Characters	Number of 128-Bit Frames	Number of Wiegand Bits	Special Features
AT5100	Toll	Beam	20	1	N/A	915 MHz, thin case, non-metal window install
AT5102	Access control	Beam	10	1/2	26 to 54	915 MHz, thin case, non-metal window install
AT5105	Access control	5-yr battery	10	1/2	26 to 54	Multifrequency, thin case, non-metal window install
AT5106	Access control	10-yr battery	10	1/2	26 to 54	Multifrequency, sealed case, non-metal window install or non-metal external install
AT5107	Access control	10-yr battery	10	1/2	26 to 54	Multifrequency, sealed case, metal external install
AT5110	Transportation	Beam	20	1	N/A	915 MHz frequency, metal external install

Table E-1 ATA Protocol Tags (continued)

Tag Model Number	TagType	Power Source	Number of 6-Bit ASCII Characters	Number of 128-Bit Frames	Number of Wiegand Bits	Special Features
AT5112	Access control, transportation	Beam	10	1/2	26 to 54	915 MHz frequency, metal external install
AT5114	Access control, transportation	10-yr battery	10	1/2	26 to 54	Multifrequency, metal external install
AT5125	Transportation	Beam	20	1	N/A	915 MHz frequency; high-temperature chemical-resistant case, metal external install
AT5140	Toll	10-yr battery	20	1	N/A	915 MHz frequency, license plate install
AT5145	Toll	Beam	20	1	N/A	915 MHz frequency, license plate install
AT5146	Access control	Beam	10	1/2	26 to 54	915 MHz, license plate install
AT5147	Access control	10-yr battery	10	1/2	26 to 54	915 MHz, license plate install
AT5510	Transportation	10-yr battery	20	1	N/A	Multifrequency, metal external install
AT5544	Toll	10-yr battery	20	1	N/A	Multifrequency, sealed case, non-metal window or external install
AT5545	Toll	10-yr battery	20	1	N/A	Multifrequency, sealed case, metal external install

Table E-1 ATA Protocol Tags (continued)

Tag Model Number	TagType	Power Source	Number of 6-Bit ASCII Characters	Number of 128-Bit Frames	Number of Wiegand Bits	Special Features
AT5547	Toll	5-yr battery	20	1	N/A	Multifrequency, thin case, non-metal window install
AT5704	Transportation	External	4608	256	N/A	Multifrequency, dynamic tag, metal external install
AT5707	Transportation	8-yr battery	40 <sup>a</sup>	2	N/A	915 MHz frequency, dynamic tag, metal external install

a. If desired, in place of 40 6-bit ASCII characters, the AT5707 can support up to 34 7-bit ASCII characters.

Table E-2 eGo Protocol Tags

Tag	Tag Type	Power Source	Number of 6-bit ASCII Characters	Number of 128-Bit Frames	Number of Wiegand Bits	Special Features
Windshield Sticker Tag	Toll, Electronic vehicle registration (EVR), <i>mCommerce</i> , Parking, Security access	Beam	20	1	NA	Very thin, flexible, multi-layer lamination
			10	1/2	26 to 54	
License Plate Tag			20	1	NA	Water-resistant, exterior-mounted
			10	1/2	26 to 54	

## Reader/Tag Interoperability (Needs to be updated)

Table E-3 lists the various SmartPass reader models, the Encompass 4/4800 Multiprotocol Reader, and the tags that are read by them.

**Table E-3 Reader/Tag Interoperability**

Reader	Beam Tags	Battery Tags
AI1620-100	AT5100; AT5102; AT5110; AT5112; AT5125; AT5145; AT5146; AT5715	AT5105; AT5114; AT5140; AT5147; AT5510; AT5540; AT5541; AT5542; AT5543; AT5544; AT5545; AT5547; AT5704; AT5707; IT2221*; IT2235*
AI1620-101	AT5100; AT5102; AT5110; AT5112; AT5125; AT5145; AT5146; AT5715	AT5105; AT5114; AT5140; AT5147; AT5510; AT5540; AT5541; AT5542; AT5543; AT5544; AT5545; AT5547; AT5704; AT5707; IT2221*; IT2235*
AI1620-102	AT5100; AT5102; AT5112; AT5146	AT5105; AT5114; AT5147; IT2221*; IT2235*
AI1620-103	AT5100; AT5102; AT5112; AT5146	AT5105; AT5114; AT5147; IT2221*; IT2235*
AI1620-104	AT5100; AT5102; AT5110; AT5112; AT5125; AT5145; AT5146; AT5715	AT5105; AT5114; AT5140; AT5147; AT5510; AT5540; AT5541; AT5542; AT5543; AT5544; AT5545; AT5547; AT5704; AT5707; IT2221*; IT2235*
AI1620-105	AT5100; AT5102; AT5110; AT5112; AT5125; AT5145; AT5146; AT5715	AT5105; AT5114; AT5140; AT5147; AT5510; AT5540; AT5541; AT5542; AT5543; AT5544; AT5545; AT5547; AT5704; AT5707; IT2221*; IT2235*
Encompass 4/4800 Multiprotocol Reader	AT5100; AT5102; AT5110; AT5112; AT5125; AT5145; AT5146; AT5715  eGo Windshield Sticker Tag; eGo License Plate Tag  other ANS INCITS 256-2001-compliant tags with Intellitag technology	AT5105; AT5114; AT5140; AT5147; AT5510; AT5540; AT5541; AT5542; AT5543; AT5544; AT5545; AT5547; AT5704; AT5707; IT2221*; IT2235*

\* When used in optional ATA/ISO mode

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## Tag Data Formats

Tags are programmed at the TransCore factory with the tag model number, date of manufacture, and data format. Contact TransCore for special order entry procedures for the format that applies to your system. The following four tag data formats can be used:

- 10-character alphanumeric ASCII — Four alphanumeric characters are fixed and can be used to identify either the dealer or the user. The remaining six positions are numeric and should be unique for each tag issued. For example, the entry ACME000001 might be specified as the first tag on the order entry form from ACME Parking Garage.
- 20-character alphanumeric ASCII — Four alphanumeric characters are typically fixed and the remaining 16 positions are numbered sequentially.
- Wiegand — Tags can be programmed in Wiegand formats with 26 to 54 bits. If you choose this format, complete a Wiegand format worksheet — attached to the order entry form — indicating the data to be programmed into the tags.

**Note:** Only access control tag models can be Wiegand-formatted. See [Table E-1](#) for Wiegand-compatible tag models.

- AAR/ISO — For requirements for this format, refer to ISO 10374 and the most recent version of *Association of American Railroads Standard for Automatic Equipment Identification*.

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