CENTRALINA UNIVERSALE PER IL CONTROLLO DI UNO O DUE MOTORI
UNIVERSAL CONTROL UNIT FOR OPERATING ONE OR TWO MOTORS
UNITE DE COMMANDE UNIVERSELLE POUR LE CONTROLE D＇UN OU DEUX MOTEURS
UNIVERSALSTEUERUNG FÜR EINEN ODER ZWEI MOTOREN
CENTRAL UNIVERSAL PARA EL CONTROL DE UNO O DOS MOTORES
CENTRAL UNIVERSAL PARA O CONTROLO DE UM OU DOIS MOTORES

डे INSTALLAZZIONE VELOCE-QUICK INSTALLATION-INSTALILATION RAPIDE SCHNELLINSTALLATION-INSTALACION RÁPIDA - SNELLE INSTALLATIE
Connettore programmatore palmare, Palmtop programmer connector, Connecteur programmateur de poche, Steckverbinder Palmtop-Programmierer, Conector del programador de bolsillo, Connector programmeerbare palmtop.
Display + tasti programmazione
Display + programming keys Afficheur + touches programmation Display + Programmierungstasten Pantalla + botones programación Display + programmeringstoetsen
Connettore scheda opzionale Optional board connector Connecteur carte facultative Steckverbinder Zusatzkarte Conector de la tarjeta opcional Connector optionele kaart
Connettore ricevitore radio
Radio receiver connector
Connecteur Récepteur Radio
Stecker Funkempfänger
Conector del receptor de radio Connector Radio-ontvanger




| PRESET |  | DEFAULT | Rr | 5 r | Rc | 5 c | ind |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| PARAMETER |  |  |  |  |  |  |  |
| Automatic closing time (TCA) |  | 40 | 20 | 40 | 30 | 40 | 40 |
| Operation time motor 1 |  | 60 | 20 | 20 | 20 | 20 | 20 |
| Operation time motor 2 |  | 60 | 20 | 20 | 20 | 20 | 20 |
| Pedestrian operation time |  | 6 | 6 | 6 | 6 | 6 | 6 |
| Opening delay time for leaf 1 |  | 3 | 2 | 2 | 2 | 2 | 2 |
| Closing delay time for leaf 2 |  | 3 | 2 | 2 | 2 | 2 | 2 |
| Slow-down time | hydraulic | 0 | 0 | 0 | 0 | 0 | 0 |
|  | electromechanical |  | 3 | 3 | 3 | 3 | 3 |
| Traffic-light area clearance time |  | 15 | 15 | 15 | 15 | 15 | 15 |
| Preheating |  | 30 | 30 | 30 | 30 | 30 | 30 |
| Slowdown motor torque | hydraulic | 40 | 99 | 99 | 99 | 99 | 99 |
|  | electromechanical |  | 50 | 50 | 50 | 50 | 50 |
| Motor torque | hydraulic | 40 | 99 | 99 | 99 | 99 | 99 |
|  | electromechanical |  | 50 | 50 | 50 | 50 | 50 |
| Braking |  | 0 | 0 | 0 | 0 | 0 | 0 |
| Emergency braking |  | 60 | 60 | 60 | 60 | 60 | 60 |
| Zona |  | 0 | 0 | 0 | 0 | 0 | 0 |
| LOGIC |  |  |  |  |  |  |  |
| Automatic Closing |  | OFF | ON | OFF | ON | OFF | OFF |
| Opening Impulse lock |  | OFF | OFF | OFF | ON | ON | OFF |
| Impulse lock TCA |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Impulse lock on closing |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Ram blow on opening |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Ram blow in closing |  | OFF | OFF | OFF | OFF | OFF | OFF |
| 2-step logic |  | OFF | OFF | OFF | OFF | OFF | OFF |
| 3-step logic |  | OFF | ON | OFF | ON | OFF | OFF |
| Pre alarm |  | OFF | OFF | OFF | ON | ON | OFF |
| Lock hold | hydraulic | OFF | ON | ON | ON | ON | ON |
|  | electromechanical |  | OFF | OFF | OFF | OFF | OFF |
| Hold-to-run |  | OFF | OFF | OFF | OFF | OFF | ON |
| Photocells on opening |  | OFF | ON | ON | ON | ON | OFF |
| Rapid closing |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Photocell test |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Electric edge test |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Photocell test on opening |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Photocell test on closing |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Master/Slave |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Fixed code |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Radio transmitter programming |  | ON | ON | ON | ON | ON | OFF |
| Time count | hydraulic | OFF | OFF | OFF | OFF | OFF | OFF |
|  | electromechanical |  | ON | ON | ON | ON | ON |
| Courtesy light |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Clock / Pedestrian |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Light/Alarm |  | OFF | OFF | OFF | OFF | OFF | OFF |
| 1 Active motor |  | OFF | ----- | ----- | -- | ----- | ----- |
| Gate-open or 2nd radio channel warning light |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Safety edge |  | ON | ON | ON | ON | ON | ON |
| Blinking output |  | OFF | OFF | OFF | OFF | OFF | OFF |
| Type of lock |  | OFF | OFF | OFF | OFF | OFF | OFF |

## ACCESS TO MENUS Fig. 1



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## GENERAL WARNINGS

WARNING! Important safety instructions. Carefully read and comply with the Warnings booklet and Instruction booklet that come with the product as incorrect installation can cause injury to people and animals and damage to property. They contain important information regarding safety, installation, use and maintenance. Keep hold of instructions so that you can attach them to the technical file and keep them handy for future reference.

## 1) GENERAL SAFETY

WARNING! An incorrect installation or improper use of the product can cause damage to persons, animals or things.

- The units making up the machine and its installation must meet the requirements ofthefollowing European Directives:2004/108/EEC, 2006/95/ EEC and later amendments. For all countries outside the EEC, it is advisable to comply with the above-mentioned standards, in addition to any national standards in force, to achieve a good level of safety.
- The Firm disclaims all responsibility resulting from improper use or any use other than that for which the product has been designed, as indicated herein, as well as for failure to apply Good Practice in the construction of entry systems (doors, gates, etc.) and for deformation that could occur during use.
- Make sure the stated temperature range is compatible with the site in which the automated system is due to be installed.
- Do not install the product in an explosive atmosphere.
- Disconnect the electricity supply before performing any work on the system. Also disconnect buffer batteries, if any are connected.
- Have the automated system's mains power supply fitted with a switch or omnipolar thermal-magnetic circuit breaker with a contact separation of at least 3.5 mm
- Make sure that upline from the mains power supply there is a residual current circuit breaker that trips at 0.03 A .
- Make sure the earth system has been installed correctly: earth all the metal parts belonging to the entry system (doors, gates, etc.) and all parts of the system featuring an earth terminal.
- Installation must be carried out using safety devices and controls that meet standard EN 12978.
- Apply all safety devices (photocells, safety edges, etc.) required to keep the area free of crushing, dragging and shearing hazards.
- Only use original spare parts for any maintenance or repair work. The Firm disclaims all responsibility for the correct operation and safety of the automated system if parts from other manufacturers are used.
- Do not make any modifications to the automated system's components unless explicitly authorized by the Firm.
- Dispose of packaging materials (plastic, cardboard, polystyrene, etc.) in accordance with the provisions of the laws in force. Keep nylon bags and polystyrene out of reach of children.
- Anything which is not expressly provided for in the present instructions, is not allowed.
- The device is not meant to be used by people (including children) whose physical, sensory or mental capacities are impaired or who do not have suitable experience or knowledge, unless a person responsible for their safety provides them with supervision or operating instructions.

Warning! For connection to the mains power supply, use a multicore cable with a cross-section of at least $4 \times 1.5 \mathrm{~mm}^{2}$ of the kind provided for by the regulations mentioned above (by way of example, type H05 VV-F cable can be used with a cross-section of $4 \times 1.5 \mathrm{~mm}^{2}$ ). To connect auxiliary equipment, use wires with a cross-section of at least $0,75 \mathrm{~mm}^{2}$.
Have an omnipolar circuit breaker installed with a contact separation of at least 3 mm and featuring overload protection, suitable for cutting the automated device off from the mains.
Only use pushbuttons with a capacity of 10A-250V or more.
The cables must be held in position using an extra fixing device in the proximity of the terminals, e.g. with cable clamps.
Also add more clips to the limit device wires, to the transformer primary or secondary wires, and to the wires connected to the printed circuit. During installation, the power supply cable must be stripped in order for the earthing wire to be connected to the appropriate terminal, but the active wires must be left as short as possible. The earthing wire must be the last to stretch in the case where the cable fixing device becomes loose.

WARNING: extremely low safety voltage cables must be phisically separated from low voltage cables. Access to the electrical compartment or to limit switches must be allowed to skilled personnel only.

Setting sensitivity incorrectly can result in damage to property and injury to people and animals.

Compliance with current safety rules with regard to people, animals and property must be assured at all times and, more specifically, measures must be taken to avoid risks of injury due to crushing, in the area where the pinion and rack mesh, and any other mechanical hazards. All critical points must be protected by safety devices in accordance with the provisions of the regulations in force.

## CHECKING THE AUTOMATED DEVICE

Before the automated device is finally put into operation, perform the following checks meticulously:

- Make sure all components are fastened securely.
- Check the correct functioning of all safety devices (limit microswitches, photocells, sensitive edges etc.).
- Make sure that the anti-crush system stops the door within the limits provided for by the standards in force.
- Check the emergency operation control device.
- Check the opening and closing operations with the control devices in use
- Check the standard and customised electronic functioning logic.


## MAINTENANCE

Dismantle the gearmotor and replace the lubricating grease every two years.

- When any operational malfunction is found, and not resolved, disconnect the mains power supply and request the assistance of a specialised technician (installer).


## SCRAPPING

Materials must be disposed of in conformity with the current regulations. In case of scrapping, the automation devices do not entail any particular risks or danger. In case of recovered materials, these should be sorted out by type (electrical components, copper, aluminium, plastic etc.).

## DISMANTLING

When the automation system is disassembled to be reassembled on another site, proceed as follows:

- Disconnect the power supply and the entire electrical installation.
- Remove the actuator from its fixing base.
- Disassemble all the installation components.

In the case where some of the components cannot be removed or are damaged, they must be replaced.

Correct controller operation is only ensured when the data contained in the present manual are observed. The Company is not to be held responsible for any damage resulting from failure to observe the installation standards and the instructions contained in the present manual.
The descriptions and illustrations contained in the present manual are not binding. The Company reserves the right to make any alterations deemed appropriate for the technical, manufacturing and commercial improvement of the product, while leaving the essential product features unchanged, at any time and without undertaking to update the present publication.

## 1) FOREWORD

The RIGEL 5 control unit is supplied by the manufacturer with standard setting. Any modifications must be entered using the universal palmtop programmer or the incorporated display. This Control unit supports the entire EELINK protocol.
These are its main features:

- Control of one or two motors up to 600W power.
- Electronic torque setting.
- Adjustable electrodynamic braking.
- End-of-run speed slow-down.
- Separate opening / closing limit-switch inputs for each motor.
- Output for zone light.
- Separate inputs for safety devices.
- 12 V output for click or suction-type electric lock.
- Output for timer piloting.
- Clock input.
- Connector for traffic-light board / motor preheating.

Incorporated radio receiver.
The board is provided with a removable terminal board for easier maintenance and replacement. This is supplied with a series of prewired jumpers to make work easy for the installer.
The jumpers relate to the following terminals: 33-34, 35-36, 36-37, 38-39, 39-40, 41-42, 42-43, 52-55. If the above terminals are used, remove the respective jumpers.

## 2) TECHNICAL SPECIFICATIONS

| CONTROL UNIT |  |
| :---: | :---: |
| Power supply | $230 \mathrm{~V} \pm 10 \% 50 \mathrm{~Hz}$ * |
| Mains/low voltage insulation | > 2MOhm 500V=-- |
| Dielectric strength | mains/bty 3750V $\sim$ for 1 minute |
| Motor output current | $\begin{aligned} & \text { 1A+1A } \max (230 \mathrm{~V} \sim)-2 \mathrm{~A}+2 \mathrm{~A} \max \\ & (110 \mathrm{~V} \sim) \end{aligned}$ |
| Motor relay commutation current | 10A |
| Zone/courtesy light | max 150W |
| Supply to accessories | 24V~ (1A max absorption) |
| Electric lock | 12V=-- (0.5A max, 2A for 3 s ) |
| Light/alarm output with free n.o. contact | max 3A 250V~ |
| Gate-open warning light | 24V~3W max |
| Blinker | 230V 40W max |
| Fuses | See Fig. A |
| Dimensions | See Fig. B |
| RECEIVER |  |
| Commands association | ```1st ch. = start 2nd ch. = relay 2nd ch. for 1 sec.``` |
| Built-in Rolling-Code radio-receiver | frequency 433.92 MHz |
| $\mathrm{N}^{\circ}$ of combinations | 4 billion |
| Max. $\mathrm{n}^{\circ}$ of remotes that can be memorized | 63 |
| Antenna impedance | 50 Ohm (RG58) |

(*) Special supply voltages to order.
Usable transmitter versions:
All ROLLING CODE transmitters compatible with

3) TUBE ARRANGEMENT Fig.A

Install the electrical system referring to the standards in force for electrical systems CEI 64-8, IEC 364, harmonization document HD 384 and other national standards.

## 4) TERMINAL BOARD WIRING Fig. A

Once suitable electric cables have been run through the raceways and the automated device's various components have been fastened at the predetermined points, the next step is to connect them as directed and illustrated in the diagrams contained in the relevant instruction manuals. Connect the live, neutral and earth wire (compulsory). The mains cable must be clamped in the relevant cablegland, and the accessories'wires in the cable gland, while the earth wire with the yellow/green-coloured sheath must be connected in the relevant terminal.

| TERMINAL | DESCRIPTION |
| :---: | :---: |
| 1 | GND terminal |
| 2-3 | $230 \mathrm{~V} \sim \pm 10 \%, 50-60 \mathrm{~Hz}$ power supply (2 neutral, 3 phase). |
| 4-5-6 | Motor connection 1 (delayed opening), terminals 5-6 for motor drive, terminal 4 common. |
| 5-14 | Motor capacitor connection 1 |
| 7-8-9 | Motor connection 2 (delayed closing), terminals 8-9 for motor drive, terminal 7 common. <br> N.B.If only one motor is used, use motor output 2 and configure logic"1 active motor". |
| 8-15 | Motor capacitor connection 2. |
| 10-11 | $230 \mathrm{~V} \sim$ output for blinker light (40W max) and EBP 230 V modelelectric lock. WARNING! If the SSR5 auxiliary board is used for motor preheating, move the connection to terminals 12-13 (Fig. A) and refer to LOGIC TABLE "B" (Blinker output). |
|  | 230V~ output for zone lighting (courtesy light dipswitch ON, flashing light output dipswitch OFF) |
| 12-13 | 230V~ output for courtesy light (courtesy light dipswitch OFF, flashing light output dipswitch OFF) |
|  | 230V~ output for flashing light output (flashing light dipswitch ON) |
|  | Stair-light output (N.O.) (dip Light/alarm = OFF) Only connect these terminals to safety extralow voltage (SELV) circuits suitably insulated from live parts. |
|  | Light/alarm output (N.O.) (dip Light/alarm = ON). Only connect these terminals to safety extralow voltage (SELV) circuits suitably insulated from live parts. |
|  | N.O. output for 2nd radio channel (SCA dipswitch - 2ch = OFF) |
| 18-19 | N.O. output for gate open warning light. This warning light is off when the gate is closed, flashes as it is closing and remains on when the gate is open or opening. (dipswitch SCA - 2ch = ON) |
| 20-21 | $24 \mathrm{~V} \sim$ output (1A max.) to power accessories. |
| 20-44 | $24 \mathrm{~V} \sim$ output to power VSAFE |
| 22-23 | $12 \mathrm{~V}-\mathrm{-}$ - solenoid latch output (lock type dipswitch = OFF) |
|  | $12 \mathrm{~V}-\mathrm{--}$ solenoid sucker output (lock type dipswitch = ON) |
| 24-25 | Antenna input for radio receiver board ( 24 signal, 25 braid). |
| 26-27 | INTERNAL START Pushbutton (N.O.). Internal Start command for traffic light. |
| 27-28 | START Pushbutton (N.O.). Parallel to radio receiver relay (CH1) External Start command for traffic light. |
| 27-29 | PEDESTRIAN pushbutton (N.O.). Activation takes place on motor 2; moreover, if the opening cycle has started (not from pedestrian pushbutton), the pedestrian control has the same effect as a Start command. |
| 30-31 | OPEN Pushbutton (N.O.). |
| 30-32 | CLOSE Pushbutton (N.O.). |
| 33-34 | LOCK pushbutton (N.C.). If not used, leave the jumper connected. |
| 35-36 | Photocell contact input PHOT (n.c.). If not used, leave jumpers inserted. |
|  | Photocell contact inputPHOTOPENING (N.C.). If not used, leave jumpers inserted. (dipswitch BAR = OFF) |
| 36-37 | BAR safety edge input (n.c.) If intervenes during opening, it stops and we have partial closure. If not used, leave jumpers inserted. (dipswitch BAR = ON) |
| 38-39 | Opening limit switch for motor 1 SWO1 (N.C.). If not used, leave the jumper connected. |
| 39-40 | Closing limit switch for motor 1 SWC1 (n.c.). If not used, leave the jumper connected. |
| 41-42 | Opening limit switch for motor 2 SWO2 (n.c.). If not used, leave the jumper connected. |
| 42-43 | Closing limit switch for motor 2 SWC2 (n.c.). If not used, leave the jumper connected. |
| 20-44 | 24 V output for transmitters. |
| 45-46-47 | Connection with tested safety devices (see Fig. D) |
| 48-49-50 | Connection with tested safety devices (see Fig. D) |

## INSTALLATION MANUAL

|  | Clock input (N.O.). If the connected contact is open (N.O.), the <br> leaves close and get ready for normal operation. If the contact <br> is closed (N.C.), the leaves open and stay open until the contact <br> reopens. If the opening movement controlled by the TIMER is <br> prevented by the safety devices, gate opening can be resumed <br> by activating the START/OPEN control. |
| :---: | :--- |
| $\mathbf{5 1 - 5 2}$ |  |\(\left|\begin{array}{l}Input for photocelledge contact on closing SAFE CL (N.C.). In <br>

case of activation during closing, the gate is stopped and partly <br>

reopened. If not used, leave the jumper connected.\end{array}\right|\)| $\mathbf{5 3}$ | Photocell test input (PHOT-FAULT). |
| :---: | :--- |
| $\mathbf{5 6}$ | Safety edge/opening photocell test input (BAR-FAULT). |
| JP7 | Closing photocell test input (PHOT CL-FAULT). |
| JP8 | Optio receiver board connector. |
| JP9 | Traffic-light / Preheating SSR5 board connector. |

## 5) CONNECTIONWITH EXPANSIONBOARDS ANDUNIVERSALHANDHELD

 PROGRAMMER (Fig. A)Refer to specific manual.

## 6) SAFETY DEVICES

NOTE: ONLY USE RECEIVING SAFETY DEVICES WITH FREE CHANGEOVER CONTACT.

## 6.1) TESTED DEVICES (FIG. D)

## 6.2) NON-TESTED DEVICES (FIG. C - D)

7) CALLING UP MENUS: FIG. 1
7.1) PARAMETERS MENU (PR R $_{\text {R }}$ ) (PARAMETERS TABLE "A")
7.2) LOGIC MENU (Loí ic) (LOGIC TABLE "B")

## 7.3) RADIO MENU (rRd io) (RADIO TABLE "C")

- IMPORTANT NOTE: THE FIRST TRANSMITTER MEMORIZED MUST BE IDENTIFIED BY ATTACHING THE KEY LABEL (MASTER).
In the event of manual programming, the first transmitter assigns the RECEIVER'S KEY CODE: this code is required to subsequently clone the radio transmitters
The Clonix built-in on-board receiver also has a number of important advanced features:
- Cloning of master transmitter (rolling code or fixed code).
- Cloning to replace transmitters already entered in receiver.
- Transmitter database management.
- Receiver community management.

Touse these advanced features, refer to the universal handheld programmer's instructions and to the general receiver programming guide.
7.4) LANGUAGE MENU (LRnLiLREE)

Used to set the programmer's language on the display.
7.5) DEFAULT MENU (dEFRHiLt)

Restores the controller's DEFAULT factory settings.

## 8) SCS OPTIONAL MODULES

## 8.1) SERIAL CONNECTION USING SCS1 BOARD (Fig. A - E)

The RIGEL 5 control panel allows several automation units (SCS1) to be connected in a centralised way by means of appropriate serial inputs and outputs. This makes it possible to use one single command to open and close all the automation units connected.
Following the diagram in Fig. E, proceed to connecting all the RIGEL 5 control panels, exclusively using a telephone-type line.
Should a telephone cable with more than one pair be needed, it is indispensable to use wires from the same pair.
The length of the telephone cable between one appliance and the next must not exceed 250 m .
At this point, each of the RIGEL 5 control panels must be appropriately configured, by setting a MASTER unit first of all, which will have control over all the others, to be necessarily set as SLAVE (see logic menu).
Also set the Zone number (see parameter menu) between 0 and 127
The zone number allows you to create groups of automation units, each one answering to the Zone Master unit. Each zone can only be assigned one Master unit, the Master unit in zone $\mathbf{0}$ also controls the Slave units in the other zones.
8.2) Interface with WIEGAND systems via SCS-WIE module.

Refer to the SCS-WIE module's instructions.
9) SSR5 TRAFFIC-LIGHT / MOTOR PREHEATING BOARD

When inserted in the appropriate connector, it provides:

- Control of two traffic lights with 2 lights each.
- Preheating of motors for cold climate.

Refer to specific manual.

## 9.1) Traffic light layout

Traffic light 1 must be positioned on the outside of the gate and traffic light 2 on the inside.
WARNINGS - Place signs for speed limitation to "Walking pace".

## 9.2) Motor preheating layout

The "S" probe must be positioned and fixed on the outside to detect external temperature. It is to be connected to respective terminals 7-8 on the preheating board.
WARNINGS - Move the EBP solenoid lock and flashing light to 12-13. (Fig A Ref. 2)
WARNINGS - Set flashing light dipswitch = ON
10.1) TABLE A: PARAMETERS MENU (PRrRf)

| Parameter | min. | max. | default | personal | Definition | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| tch | 3 sec . | 120 sec . | 40 |  | Automatic Closing Time | Set the numerical value of the TCA automatic closing time from 3 to 120 seconds. |
| wort. t. \# ot. 1 | 3 sec. | 180 sec . | 60 |  | Operation time motor 1 | Enter the numerical value corresponding to the working time from 3 to 180 seconds for motor 1. |
| $\begin{aligned} & \text { worh. t. n } \\ & \text { ot.2 } \end{aligned}$ | 3 sec . | 180 sec . | 60 |  | Operation time motor 2 | Enter the numerical value corresponding to the working time from 3 to 180 seconds for motor 2. |
| PEd. $t$. | 3 sec . | 9 sec . | 6 |  | Pedestrian operation time | Set the pedestrian opening time of motor 2 from 3 to 90 seconds. |
| opEn dELRY $t \operatorname{INE}$ | 0 sec . | 10 sec . | 3 |  | Opening delay time for leaf 1 | Set the opening delay time for motor 1 with respect to motor 2 , which can be adjusted from 0 to 10 seconds. |
| $\begin{array}{ll} \hline \operatorname{LL5} & d E L R Y \\ L I \cap E & \\ \hline \end{array}$ | 0 sec. | 60 sec . | 3 |  | Closing delay time for leaf 2 | Set the closing delay time for motor 2, which can be adjusted from 0 to 60 seconds. |
| 5Lou doun $k$. | 0 sec. | 20 sec . | 0 |  | Slow-down time | Set the slow-down to approach time from 0 to 20 seconds. The slow-down time is subtracted from the work time. <br> NOTE: it is advised to activate timing. <br> NOTE: only use this function when limit switches are fitted. <br> NOTE: Do not use with hydraulic motors. |
| clerr. t | 0 sec. | 30 sec . | 15 |  | Traffic-light area clearance time | Set the required clearance time for the area involved in the traffic governed by traffic light, from 0 to 30 seconds. Set to 0 if not used. |
| PrEhERt. | 0\% | 99\% | 30\% |  | Preheating | Set the percentage value of the current from 0 (deactivated pre-heating) to $99 \%$ which can be made to pass through the motor windings to keep them at the right temperature. <br> NOTE: Only with SSR5. |
| 5Loud tor PuE | 1\% | 99\% | 50\% |  | Slowdown Motor Torque | Set numerically from $1 \%$ to $99 \%$ the value of motor torque during slowdown time. |
| fot. tor lite | 1\% | 99\% | 50\% |  | Motor torque | Set the numerical torque value from 1 to $99 \%$. NOTE: When using with oil-hydraulic motors, it is necessary to set the torque value to $99 \%$ and adjust the force directly on the motor. |
| brRHE | 0\% | 99\% | 0\% |  | Braking | Set the braking value from $0 \%$ (min.) to $99 \%$ (max.) according to the gate weight and the mechanical demands involved. |
| EnEr. brahe | 0\% | 99\% | 60\% |  | Emergency braking | Set the value of the emergency braking from 0\% (min.) to 99\% (max.). This is carried out by enabling the safety commands on the inputs 34 (block), 37 (SAFE OP) and 55 (SAFE CL). |
| ZonE | 0 | 127 | 0 |  | Zona | Enter the zone number between 0 (minimum value) and 127 (maximum value). See paragraph "SCS OPTIONAL MODULES". |

10.2) TABLE B: LOGIC MENU (Loú ic)

| Logic | Default | Definition | Cross out setting used | Description |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| tch | OFF | Automatic Closing Time | ON | Switches automatic closing on. |  |  |  |  |
|  |  |  | OFF | Switches automatic closing off. |  |  |  |  |
| IbL open | OFF | Opening Impulse lock | ON | The Start impulse has no effect during the opening phase. |  |  |  |  |
|  |  |  | OFF | The Start impulse becomes effective during the opening phase. |  |  |  |  |
| ibl kch | OFF | Impulse lock TCA | ON | The Start impulse has no effect during the TCA dwell period. |  |  |  |  |
|  |  |  | OFF | The Start impulse becomes effective during the TCA dwell period. |  |  |  |  |
| bl close | OFF | Impulse lock on closing | ON | The start impulse has no effect during the closing stage. |  |  |  |  |
|  |  |  | OFF | The start impulse is effective during the closing stage. |  |  |  |  |
| $\left\lvert\, \begin{aligned} & \text { r月n } \\ & \text { c.op } \end{aligned}\right.$ | OFF | Ram blow on opening | ON | It pushes for approx. 2 seconds in closing direction before opening. This allows the electric lock to be released more easily (not affected by limit switches). IMPORTANT - When no adequate mechanical backstops are installed, do not use this function. It is also to be absolutely avoided in the automation of sliding gates. |  |  |  |  |
|  |  |  | OFF | Excludes the ram blow in closing. |  |  |  |  |
| $\left\lvert\, \begin{array}{cc} \text { ran } & \text { bLou } \\ \text { c. } \end{array}\right.$ | OFF | Ram blow in closing | ON | Before carrying out the closing manoeuvre, the gate pushes for about 2 seconds on opening. This allows the electric lock to be released more easily.(not affected by limit switches) <br> IMPORTANT - When no adequate mechanical backstops are installed, do not use this function. It is also to be absolutely avoided in the automation of sliding gates. |  |  |  |  |
|  |  |  | OFF | Excludes the ram blow in closing. |  |  |  |  |
| 2 StEP | OFF | $\begin{array}{\|l} \text { 2-step, 4-step } \\ \text { logic } \end{array}$ | ON | Enables 2-step logic (prevails over "3-step logic"). | A start impulse has the following effects: |  |  |  |
|  |  |  | OFF | Enables 4-step logic when the 3-step logic is set to OFF. |  | 2 step | 3 step | 4 step |
| 3 StEP | OFF | 3-step logic | ON | Enables 3-step logic (with 2 steps=OFF). | closed | opens | opens | opens |
|  |  |  | OFF | Disables 3-step logic. | on closing |  |  | stop |
| Pre-mlarin | OFF | Pre alarm | ON | The blinker comes on about 3 seconds before the motor starts. | open | closes | closes | closes |
|  |  |  |  |  | on opening |  | stop + TCA | stop + TCA |
|  |  |  | OFF | starts. | after stopping | closes | opens | opens |
| bloc PEr 5 15t | OFF | Lock hold | ON | If the motors remain still in a totally open or closed position for over one hour, they are activated for about 3 seconds in the respective direction. This operation takes place once every hour. <br> N.B.: This function has the purpose of compensating any oil volume decrease in the hydraulic motors, due to a temperature drop during prolonged pauses, for instance at night, or to internal leaks. <br> IMPORTANT - When no adequate mechanical backstops are installed, do not use this function. It is also to be absolutely avoided in the automation of sliding gates. |  |  |  |  |
|  |  |  | OFF | Exclude block maintenance. |  |  |  |  |
| $\begin{aligned} & \text { hoidd-to- } \\ & \text { ruin } \end{aligned}$ | OFF | Hold-to-run | ON | Hold-to-run operation: the manoeuvre continues as long as the command key is kept pressed. IMPORTANT - It is not possible to use the radio transmitter. |  |  |  |  |
|  |  |  | OFF | Impulse operation. |  |  |  |  |


| INSTALLATION MANUAL |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Photc. OPEn | OFF | Photocells on opening | ON | In case of obscuring, this excludes photocell operation on opening. During the closing phase, it immediately reverses the motion. |
|  |  |  | OFF | In case of obscuring, the photocells are active both on opening and on closing. When a photocell is obscured on closing, it reverses the motion only after the photocell is disengaged. |
| FR5t cL5 | OFF | Rapid closing | ON | Closes the gate after photocell disengagement, before waiting for the end of the TCA (automatic closing time) set. |
|  |  |  | OFF | Command not entered. |
| tESt Phot | OFF | Photocell test | ON | Activates photocell check (see Fig. D) |
|  |  |  | OFF | Deactivates photocell check |
| tESt bRr | OFF | Electric edge test | ON | Activates electric edge check (see Fig. D) |
|  |  |  | OFF | Deactivates electric edge check |
| tE5t Phot 0 . | OFF | Photocell test on opening | ON | Enables the test of the active photocells on opening. |
|  |  |  | OFF | Desables the test of the active photocells on opening. |
| tE5t Phot cL. | OFF | Photocell test on closing | ON | Enables the test of the active photocells on closing. |
|  |  |  | OFF | Desables the test of the active photocells on closing. |
| ARStEr | OFF | Master/Slave | ON | The control panel is set as Master in a centralised connection (see "SCS OPTIONAL MODULES"). |
|  |  |  | OFF | The control panel is set as Slave in a centralised connection (see "SCS OPTIONAL MODULES"). |
| $\begin{aligned} & \text { F IHEd } \\ & \text { code } \\ & \hline \end{aligned}$ | OFF | Fixed code | ON | The receiver is configured for operation in fixed-code mode. |
|  |  |  | OFF | The receiver is configured for operation in rolling-code mode. |
| rRd io Proú | ON | Radio transmitter programming | ON | This enables transmitter storage via radio: <br> 1 - First press the hidden key (P1) and then the normal key (T1,T2, T3 or T4) of a transmitter already memorised in standard mode by means of the radio menu. <br> 2 - Within 10 s press the hidden key ( P 1 ) and the normal key ( $\mathrm{T} 1, \mathrm{~T} 2, \mathrm{~T} 3$ or T 4 ) of a transmitter to be memorised. The receiver exits the programming mode after 10 s , other new transmitters can be entered before the end of this time. <br> This mode does not require access to the control panel. |
|  |  |  | OFF | This disables transmitter storage via radio. <br> The transmitters can only be memorised using the appropriate Radio menu. Clones and replays are not accepted. |
| $t \operatorname{INE}$. | OFF | Time count | ON | The control unit calculates the activation time of each motor, based on the preceding manoeuvres. |
|  |  |  | OFF | The control unit activates the motors at each manoeuvre for the time set. N.B. Always set the operation time to a slightly higher value than needed to carry out the complete manoeuvre. |
| $\left\lvert\, \begin{aligned} & \text { ZonE } \\ & \text { L IENE } \end{aligned}\right.$ | OFF | Courtesy light | ON | Zone light. Remains active as long as the manoeuvre lasts. |
|  |  |  | OFF | Courtesy light. Remains active for 90 seconds after last operation. N.B. These settings cannot be used if the blinker output is set to ON. |
| cLoch PEd | OFF | Clock / Pedestrian | ON | Input for the connection of an external timer. <br> The Clock input is only active in Motor 2, for the pedestrian time set. <br> A start command given during the clock phase carries out complete gate opening and closing, resetting the open pedestrian position. |
|  |  |  | OFF | The Clock input acts on both motors. |
| $\begin{aligned} & \hline \text { L Wint- } \\ & \text { RiLRri } \end{aligned}$ | ON | Light/Alarm | ON | Gate-open alarm output (activated if the gate remains open for twice the TCA time set). |
|  |  |  | OFF | Stair-light control (the impulse stays on for 1 second). |
| i not. on | OFF | 1 active motor | ON | Only motor 2 activated (1 leaf). |
|  |  |  | OFF | Both motors are activated (2 leaves). |
| 5cR-3ch | OFF | Gate-openor2nd radio channel warning light | ON | The output between terminals 18 and 19 is configured as Gate-open warning light, in this case the 2 nd radio channel controls pedestrian opening. |
|  |  |  | OFF | The output between terminals 18 and 19 is configured as 2nd radio channel. |
| brir | ON | Safety edge | ON | Input of terminals 36-37 is active as input for the safety edge. |
|  |  |  | OFF | Input of terminals 36-37 is active as input for opening photocells. |
| bi inh | OFF | Blinking output | ON | Set the output at terminals 12-13 ("courtesy light") as blinking output (active only during leaf movement). N.B. Any setting relating to the "courtesy light" function is ignored. |
|  |  |  | OFF | Keep the output at terminals 12-13 as "courtesy light" or "zone light". <br> WARNING! It is not possible to use the SSR5 board in motor preheating mode and at the same time have the Zone light/Courtesy Light and Blinker/Electric lock on. In this case, outputs 10-11 cannot be used and outputs 12-13 can only be used for one of the two functions. |
| $\begin{aligned} & \text { SUct ion- } \\ & \text { LYPE } \\ & \hline \end{aligned}$ | OFF | Type of lock | ON | Suction-type lock. Enabled with gate closed. |
|  |  |  | OFF | Click lock. Enabled with a pulse at each opening. |

10.3) TABLE C: RADIO MENU (rRd io)

| Logic | Description |
| :---: | :--- |
| Rdd 5tRrt | Ads Statt Key <br> associates the desired key with the Start command. |
| Rdd 2ch | Add 2ch Key <br> associates the desired key with the 2nd radio channel command. |
| ErR5E 54 | Erase List <br> WARNING! Erases all memorized remote controls from the receiver's memory. |
| cod rH | Read receiver code <br> Displays receiver code required for cloning remote controls. |
| wik | ON Enables remote programming of cards via a previously memorized W LINK transmitter. It remains enabled for 3 minutes from the time the <br> W LINK remote control is last pressed. <br> OFF=W LINK programming disabled. |



Combinazioni non possibili, Not possible combinations, Combinaisons non possibiles, Nicht mogliche kombinationen, Combinaciones no posibles, Combinaties niet mogelijk.

| Fotocellule, <br> Photocellles, <br> Potocells, <br> Fotocellulas, $F$ Fotocellen, | Coste / Fotocellule in Apertura, Coste / Fotocellule in Apertura, Coste $/$ <br> Fotocellule in Apertura, Coste / Fotocellue in Apertura, Coste / Fotocel- <br> lule in Apertura, Coste /Fotocellule in Apertura, | Fotocellule in Chiusura, Fotocellule in Chiusura, Fo- <br> tocelllule in Chiusura, Fotocellule in Chiusura, Foto- <br> cellule in Chiusura, Fotocellule in Chiusura, |
| :---: | :---: | :---: |
| A1 | B4 | C5 |
| A1 | B5 | C4, C5 |
| A2 | B4 | C5 |
| A2 | B5 | C4, C5 |
| A3 | B4 | C5 |
| A3 | B5 | C4, C5 |
| A4 | B1 | C5 |
| A4 | B2 | C5 |
| A4 | B3 | C5 |
| A4 | B4 | C4, C5 |
| A4 | B5 | C1, C2, C3, C4, C5 |
| A5 | B1 | C4, C5 |
| A5 | B2 | C4, C5 |
| A5 | B3 | C4, C5 |
| A5 | B4 | C1, C2, C3, C4, C5 |
| A5 | B5 | C1, C2, C3, C4, C5 |



