National Semiconductor Corporation

LM13600/LM13600A Dual Operational Transconductance Amplifiers with Linearizing Diodes and Buffers

General Description

The LM13600 series consists of two current controlled transconductance amplifiers each with differential inputs and a push-pull output. The two amplifiers share common supplies but otherwise operate independently. Linearizing diodes are provided at the inputs to reduce distortion and allow higher input levels. The result is a 10 dB signal-to-noise improvement referenced to 0.5 percent THD. Controlled impedance buffers are provided which are especially designed to complement the dynamic range of the amplifiers.

Features

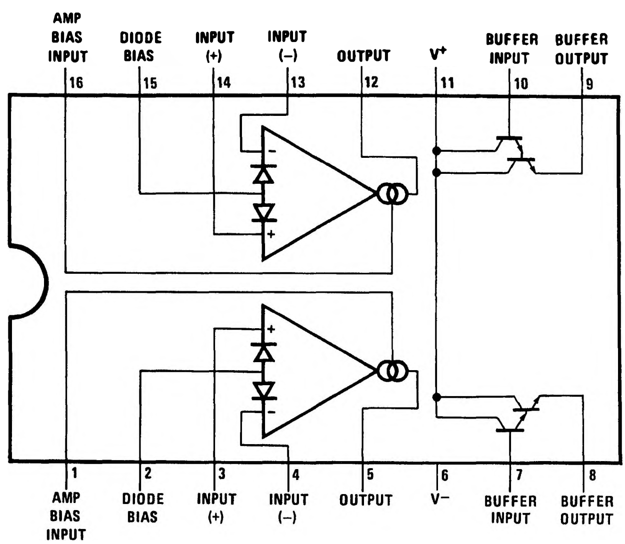
- g_m adjustable over 6 decades
- Excellent g_m linearity
- Excellent matching between amplifiers
- Linearizing diodes
- Controlled impedance buffers
- High output signal-to-noise ratio
- Wide supply range ±2V to ±22V

Applications

- Current-controlled amplifiers
- Current-controlled impedances
- Current-controlled filters
- Current-controlled oscillators
- Multiplexers
- Timers
- Sample and hold circuits

Connection Diagram

Dual-In-Line and Small Outline Packages



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Top View

Order Number LM13600M, LM13600N or LM13600AN
See NS Package Number M16A or N16A

Absolute Maximum Ratings

If Military/Aerospace specified devices are required, contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Supply Voltage (Note 1)	
LM13600	36 V_{DC} or ±18V
LM13600A	44 V_{DC} or ±22V
Power Dissipation (Note 2) $T_A = 25°C$	570 mW
Differential Input Voltage	±5V
Diode Bias Current (I_D)	2 mA
Amplifier Bias Current (I_{ABC})	2 mA
Output Short Circuit Duration	Indefinite
Buffer Output Current (Note 3)	20 mA
Operating Temperature Range	0°C to +70°C
DC Input Voltage	$+V_S$ to $-V_S$
Storage Temperature Range	−65°C to +150°C
Soldering Information	
Dual-In-Line Package	
Soldering (10 seconds)	260°C
Small Outline Package	
Vapor Phase (60 seconds)	215°C
Infrared (15 seconds)	220°C

See AN-450 "Surface Mounting Methods and Their Effect on Product Reliability" for other methods of soldering surface mount devices.

Electrical Characteristics (Note 4)

Parameter	Conditions	LM13600			LM13600A			Units
		Min	Typ	Max	Min	Typ	Max	
Input Offset Voltage (V_{OS})			0.4	4		0.4	1	mV
	Over Specified Temperature Range						2	mV
	$I_{ABC} = 5\ \mu A$		0.3	4		0.3	1	mV
V_{OS} Including Diodes	Diode Bias Current (I_D) = 500 μA		0.5	5		0.5	2	mV
Input Offset Change	$5\ \mu A \leq I_{ABC} \leq 500\ \mu A$		0.1	3		0.1	1	mV
Input Offset Current			0.1	0.6		0.1	0.6	μA
Input Bias Current			0.4	5		0.4	5	μA
	Over Specified Temperature Range		1	8		1	7	μA
Forward Transconductance (g_m)		6700	9600	13000	7700	9600	12000	μmho
	Over Specified Temperature Range	5400			4000			μmho
g_m Tracking			0.3			0.3		dB
Peak Output Current	$R_L = 0, I_{ABC} = 5\ \mu A$		5		3	5	7	μA
	$R_L = 0, I_{ABC} = 500\ \mu A$	350	500	650	350	500	650	μA
	$R_L = 0$, Over Specified Temp Range	300			300			μA
Peak Output Voltage								
Positive	$R_L = \infty, 5\ \mu A \leq I_{ABC} \leq 500\ \mu A$	+12	+14.2		+12	+14.2		V
Negative	$R_L = \infty, 5\ \mu A \leq I_{ABC} \leq 500\ \mu A$	−12	−14.4		−12	−14.4		V
Supply Current	$I_{ABC} = 500\ \mu A$, Both Channels		2.6			2.6		mA
V_{OS} Sensitivity								
Positive	$\Delta V_{OS}/\Delta V+$		20	150		20	150	μV/V
Negative	$\Delta V_{OS}/\Delta V-$		20	150		20	150	μV/V
CMRR		80	110		80	110		dB
Common Mode Range		±12	±13.5		±12	±13.5		V
Crosstalk	Referred to Input (Note 5) 20 Hz < f < 20 kHz		100			100		dB
Differential Input Current	$I_{ABC} = 0$, Input = ±4V		0.02	100		0.02	10	nA
Leakage Current	$I_{ABC} = 0$ (Refer to Test Circuit)		0.2	100		0.2	5	nA

Electrical Characteristics (Note 4) (Continued)

Parameter	Conditions	LM13600			LM13600A			Units
		Min	Typ	Max	Min	Typ	Max	
Input Resistance		10	26		10	26		kΩ
Open Loop Bandwidth			2			2		MHz
Slew Rate	Unity Gain Compensated		50			50		V/μs
Buffer Input Current	(Note 5), Except I_{ABC} = 0 μA		0.2	0.4		0.2	0.4	μA
Peak Buffer Output Voltage	(Note 5)	10			10			V

Note 1: For selections to a supply voltage above ±22V, contact factory.

Note 2: For operating at high temperatures, the device must be derated based on a 150°C maximum junction temperature and a thermal resistance of 175°C/W which applies for the device soldered in a printed circuit board, operating in still air.

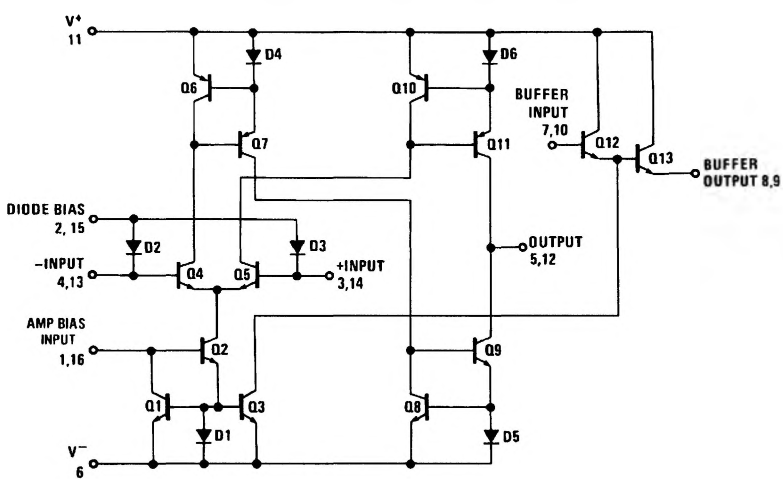
Note 3: Buffer output current should be limited so as to not exceed package dissipation.

Note 4: These specifications apply for V_S = ±15V, T_A = 25°C, amplifier bias current (I_{ABC}) = 500 μA, pins 2 and 15 open unless otherwise specified. The inputs to the buffers are grounded and outputs are open.

Note 5: These specifications apply for V_S = ±15V, I_{ABC} = 500 μA, R_{OUT} = 5 kΩ connected from the buffer output to $-V_S$ and the input of the buffer is connected to the transconductance amplifier output.

Schematic Diagram

One Operational Transconductance Amplifier



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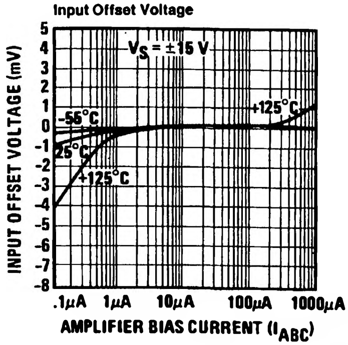
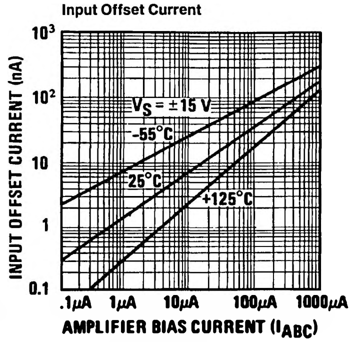
Typical Performance Characteristics

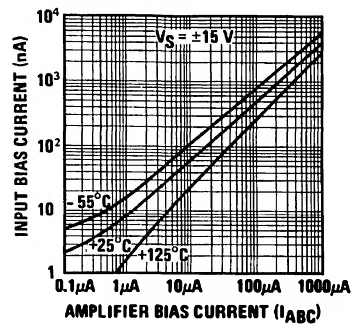
Input Offset Voltage



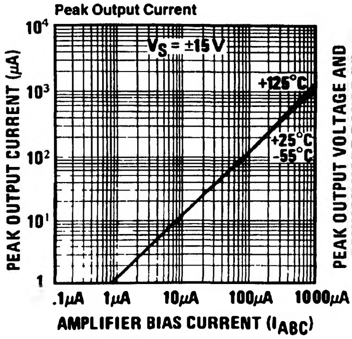
Input Offset Current



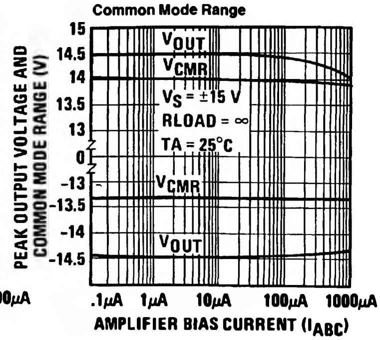
Input Bias Current



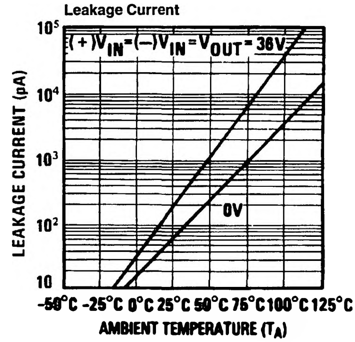
Peak Output Current



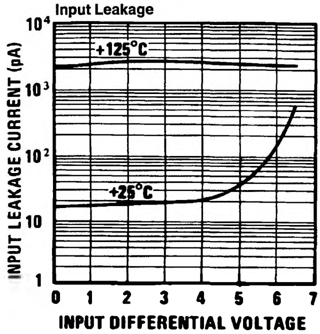
Peak Output Voltage and
Common Mode Range



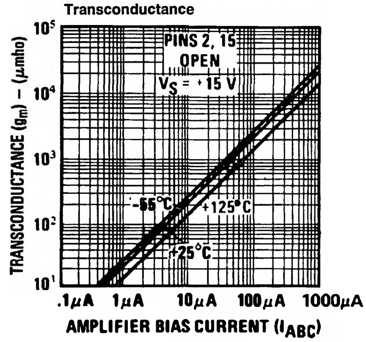
Leakage Current



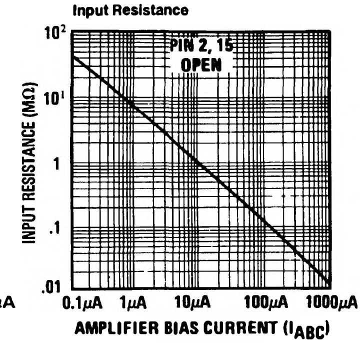
Input Leakage



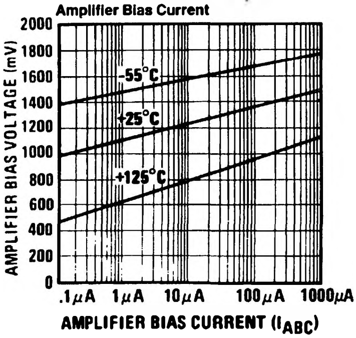
Transconductance



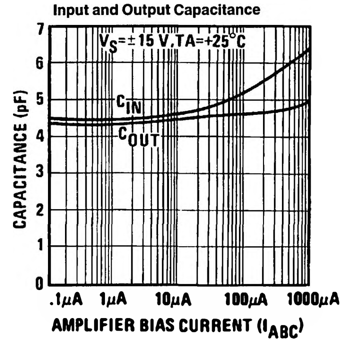
Input Resistance



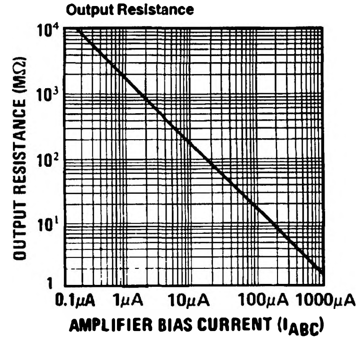
Amplifier Bias Voltage vs
Amplifier Bias Current



Input and Output Capacitance



Output Resistance



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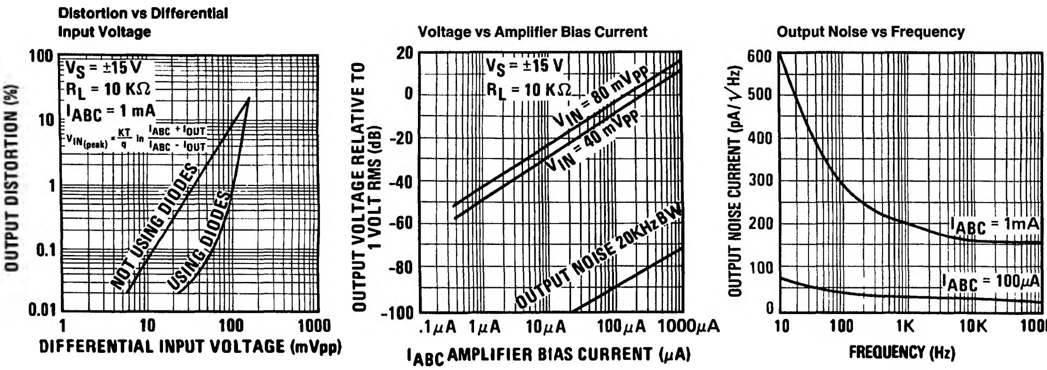
Typical Performance Characteristics (Continued)



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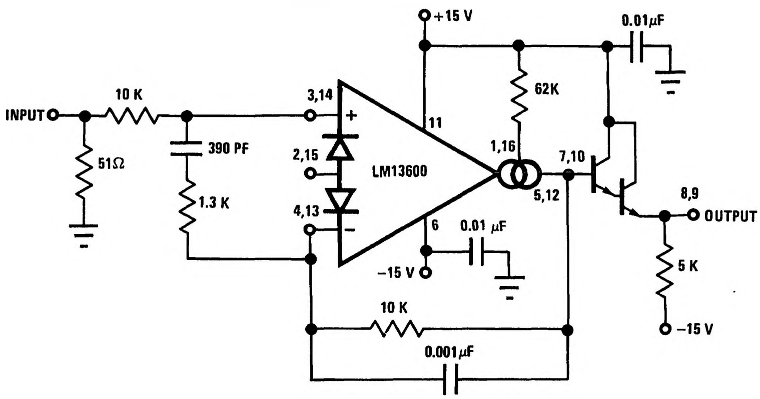
Unity Gain Follower



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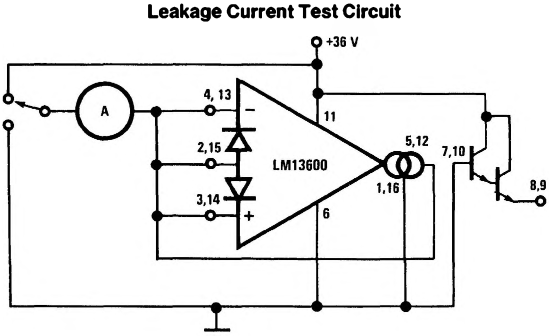
Leakage Current Test Circuit



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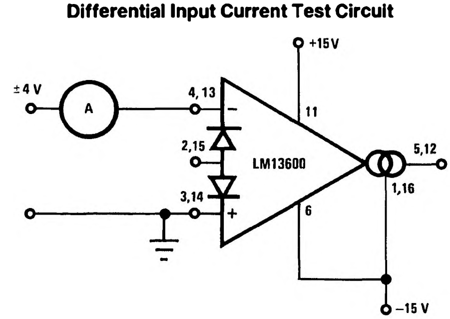
Differential Input Current Test Circuit



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Circuit Description

The differential transistor pair Q_4 and Q_5 form a transconductance stage in that the ratio of their collector currents is defined by the differential input voltage according to the transfer function:

$$V_{IN} = \frac{kT}{q} \ln \frac{I_5}{I_4} \qquad (1)$$

where V_{IN} is the differential input voltage, kT/q is approximately 26 mV at 25°C and I_5 and I_4 are the collector currents of transistors Q_5 and Q_4 respectively. With the exception of Q_3 and Q_{13}, all transistors and diodes are identical in size. Transistors Q_1 and Q_2 with Diode D_1 form a current mirror which forces the sum of currents I_4 and I_5 to equal I_{ABC};

$$I_4 + I_5 = I_{ABC} \qquad (2)$$

where I_{ABC} is the amplifier bias current applied to the gain pin.

For small differential input voltages the ratio of I_4 and I_5 approaches unity and the Taylor series of the ln function can be approximated as:

$$\frac{kT}{q} \ln \frac{I_5}{I_4} \approx \frac{kT}{q} \frac{I_5 - I_4}{I_4} \qquad (3)$$

$$I_4 \approx I_5 \approx \frac{I_{ABC}}{2}$$

$$V_{IN} \left[\frac{I_{ABC}\, q}{2kT}\right] = I_5 - I_4 \qquad (5)$$

Collector currents I_4 and I_5 are not very useful by themselves and it is necessary to subtract one current from the other. The remaining transistors and diodes form three current mirrors that produce an output current equal to I_5 minus I_4 thus:

$$V_{IN} \left[\frac{I_{ABC}\, q}{2kT}\right] = I_{OUT} \qquad (5)$$

The term in brackets is then the transconductance of the amplifier and is proportional to I_{ABC}.

Linearizing Diodes

For differential voltages greater than a few millivolts, Equation 3 becomes less valid and the transconductance becomes increasingly nonlinear. *Figure 1* demonstrates how the internal diodes can linearize the transfer function of the amplifier. For convenience assume the diodes are biased with current sources and the input signal is in the form of current I_S. Since the sum of I_4 and I_5 is I_{ABC} and the difference is I_{OUT}, currents I_4 and I_5 can be written as follows:

$$I_4 = \frac{I_{ABC}}{2} - \frac{I_{OUT}}{2}, \quad I_5 = \frac{I_{ABC}}{2} + \frac{I_{OUT}}{2}$$

Since the diodes and the input transistors have identical geometries and are subject to similar voltages and temperatures, the following is true:

$$\frac{kT}{q} \ln \frac{\frac{I_D}{2} + I_S}{\frac{I_D}{2} - I_S} = \frac{kT}{q} \ln \frac{\frac{I_{ABC}}{2} + \frac{I_{out}}{2}}{\frac{I_{ABC}}{2} - \frac{I_{out}}{2}}$$

$$\therefore I_{out} = I_S \left(\frac{2I_{ABC}}{I_D}\right) \quad \text{for } |I_S| < \frac{I_D}{2} \qquad (6)$$

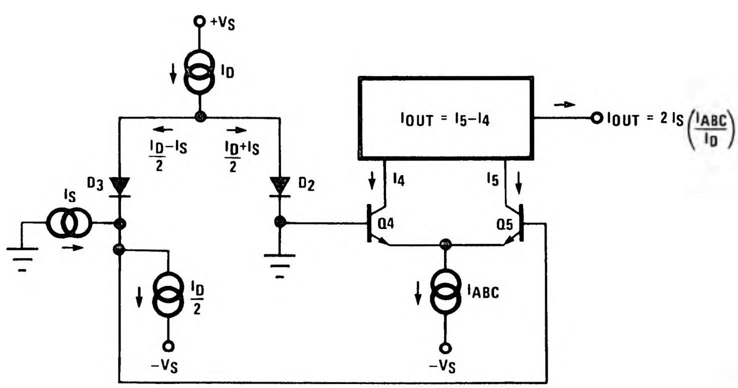

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FIGURE 1. Linearizing Diodes

Linearizing Diodes (Continued)

Notice that in deriving Equation 6 no approximations have been made and there are no temperature-dependent terms. The limitations are that the signal current not exceed $I_D/2$ and that the diodes be biased with currents. In practice, replacing the current sources with resistors will generate insignificant errors.

Controlled Impedance Buffers

The upper limit of transconductance is defined by the maximum value of I_{ABC} (2 mA). The lowest value of I_{ABC} for which the amplifier will function therefore determines the overall dynamic range. At very low values of I_{ABC}, a buffer which has very low input bias current is desirable. An FET follower satisfies the low input current requirement, but is somewhat non-linear for large voltage swing. The controlled impedance buffer is a Darlington which modifies its input bias current to suit the need. For low values of I_{ABC}, the buffer's input current is minimal. At higher levels of I_{ABC}, transistor Q_3 biases up Q_{12} with a current proportional to I_{ABC} for fast slew rate.

Applications—Voltage Controlled Amplifiers

Figure 2 shows how the linearizing diodes can be used in a voltage-controlled amplifier. To understand the input biasing, it is best to consider the 13 kΩ resistor as a current source and use a Thevenin equivalent circuit as shown in *Figure 3*. This circuit is similar to *Figure 1* and operates the same. The potentiometer in *Figure 2* is adjusted to minimize the effects of the control signal at the output.

For optimum signal-to-noise performance, I_{ABC} should be as large as possible as shown by the Output Voltage vs. Amplifier Bias Current graph. Larger amplitudes of input signal also improve the S/N ratio. The linearizing diodes help here by allowing larger input signals for the same output distortion as shown by the Distortion vs. Differential Input Voltage graph. S/N may be optimized by adjusting the magnitude of the input signal via R_{IN} *(Figure 2)* until the output distortion is below some desired level. The output voltage swing can then be set at any level by selecting R_L.

Although the noise contribution of the linearizing diodes is negligible relative to the contribution of the amplifier's internal transistors, I_D should be as large as possible. This minimizes the dynamic junction resistance of the diodes (r_e) and maximizes their linearizing action when balanced against R_{IN}. A value of 1 mA is recommended for I_D unless the specific application demands otherwise.

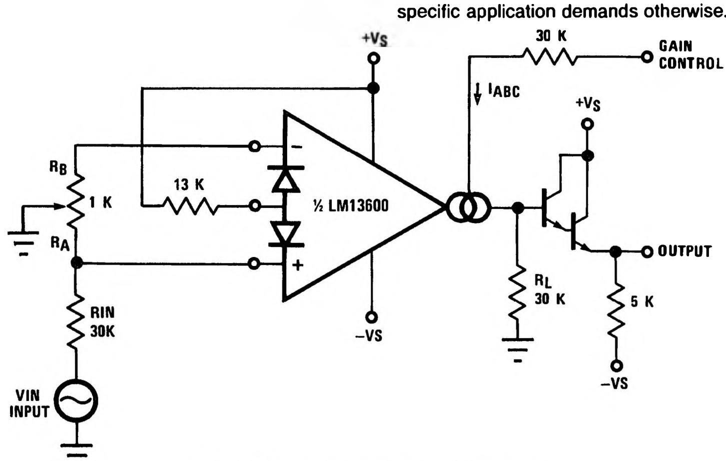

FIGURE 2. Voltage Controlled Amplifier

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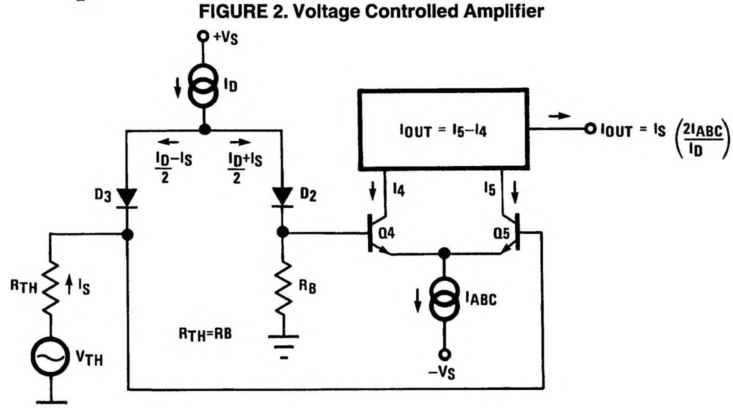

FIGURE 3. Equivalent VCA Input Circuit

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Stereo Volume Control

The circuit of Figure 4 uses the excellent matching of the two LM13600 amplifiers to provide a Stereo Volume Control with a typical channel-to-channel gain tracking of 0.3 dB. R_P is provided to minimize the output offset voltage and may be replaced with two 510Ω resistors in AC-coupled applications. For the component values given, amplifier gain is derived for *Figure 2* as being:

$$\frac{V_O}{V_{IN}} = 940 \times I_{ABC}$$

If V_C is derived from a second signal source then the circuit becomes an amplitude modulator or two-quadrant multiplier as shown in *Figure 5*, where:

$$I_O = \frac{-2I_S}{I_D}(I_{ABC}) = \frac{-2I_S}{I_D}\frac{V_{IN2}}{R_C} - \frac{2I_S}{I_D}\frac{(V^- + 1.4V)}{R_C}$$

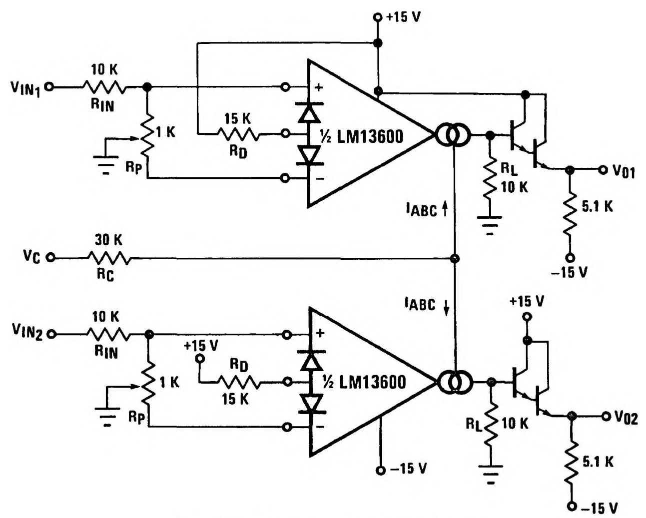

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FIGURE 4. Stereo Volume Control

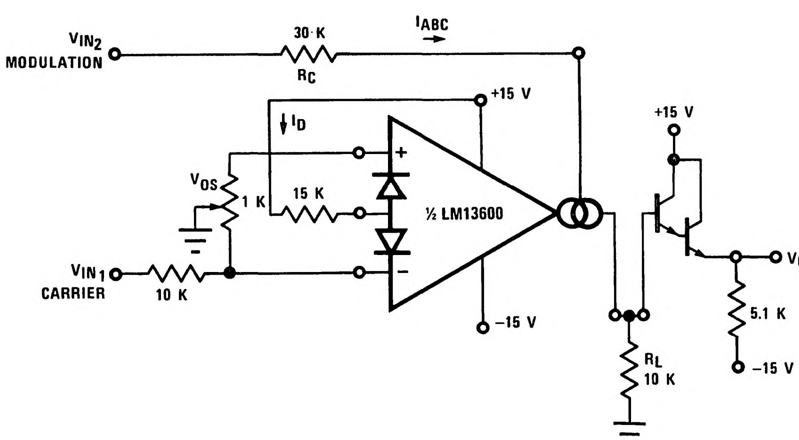

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FIGURE 5. Amplitude Modulator

Stereo Volume Control (Continued)

The constant term in the above equation may be cancelled by feeding $I_S \times I_D R_C/2\ (V^- + 1.4V)$ into I_O. The circuit of *Figure 6* adds R_M to provide this current, resulting in a four-quadrant multiplier where R_C is trimmed such that $V_O = 0V$ for $V_{IN2} = 0V$. R_M also serves as the load resistor for I_O.

Noting that the gain of the LM13600 amplifier of *Figure 3* may be controlled by varying the linearizing diode current I_D as well as by varying I_{ABC}, *Figure 7* shows as AGC Amplifier using this approach. As V_O reaches a high enough amplitude (3 V_{BE}) to turn on the Darlington transistors and the linearizing diodes, the increase in I_D reduces the amplifier gain so as to hold V_O at that level.

Voltage Controlled Resistors

An Operational Transconductance Amplifier (OTA) may be used to implement a Voltage Controlled Resistor as shown in *Figure 8*. A signal voltage applied at R_X generates a V_{IN} to the LM13600 which is then multiplied by the g_m of the amplifier to produce an output current, thus:

$$R_X = \frac{R + R_A}{g_m R_A}$$

where $g_m \approx 19.2\ I_{ABC}$ at 25°C. Note that the attenuation of V_O by R and R_A is necessary to maintain V_{IN} within the linear range of the LM13600 input.

Figure 9 shows a similar VCR where the linearizing diodes are added, essentially improving the noise performance of the resistor. A floating VCR is shown in *Figure 10*, where each "end" of the "resistor" may be at any voltage within the output voltage range of the LM13600.

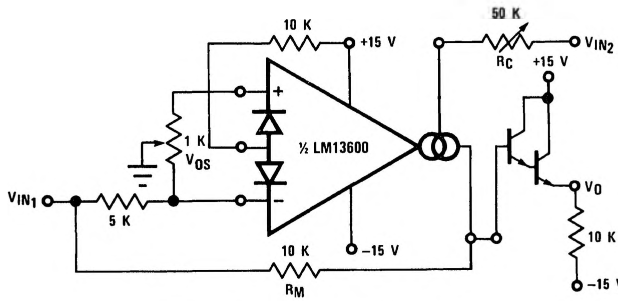

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FIGURE 6. Four-Quadrant Multiplier

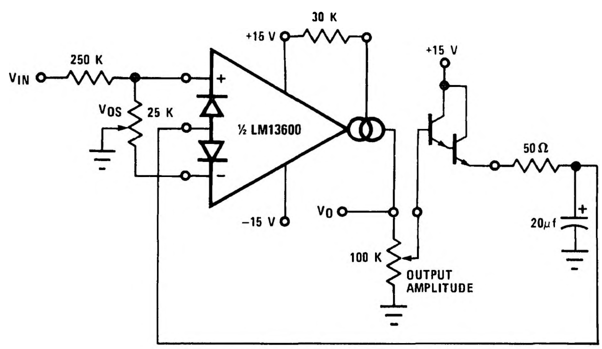

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FIGURE 7. AGC Amplifier

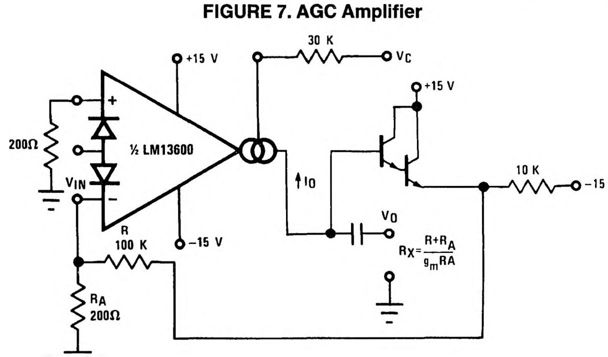

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FIGURE 8. Voltage Controlled Resistor, Single-Ended

Voltage Controlled Filters

OTA's are extremely useful for implementing voltage controlled filters, with the LM13600 having the advantage that the required buffers are included on the I.C. The VC Lo-Pass Filter of *Figure 11* performs as a unity-gain buffer amplifier at frequencies below cut-off, with the cut-off frequency being the point at which X_C/g_m equals the closed-loop gain of (R/R_A). At frequencies above cut-off the circuit provides a single RC roll-off (6 dB per octave) of the input signal amplitude with a −3 dB point defined by the given equation, where g_m is again $19.2 \times I_{ABC}$ at room temperature. *Figure 12* shows a VC High-Pass Filter which operates in much the same manner, providing a single RC roll-off below the defined cut-off frequency.

Additional amplifiers may be used to implement higher order filters as demonstrated by the two-pole Butterworth Lo-Pass Filter of *Figure 13* and the state variable filter of *Figure 14.* Due to the excellent g_m tracking of the two amplifiers and the varied bias of the buffer Darlingtons, these filters perform well over several decades of frequency.

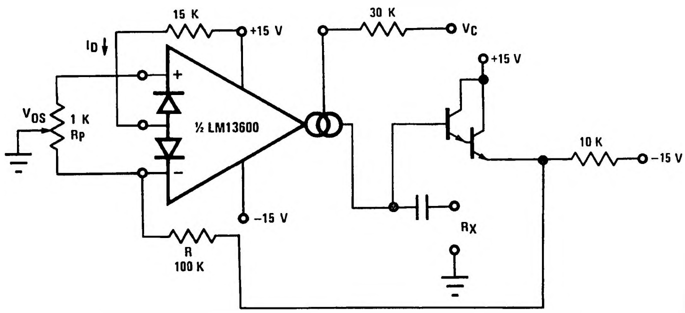

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FIGURE 9. Voltage Controlled Resistor with Linearizing Diodes

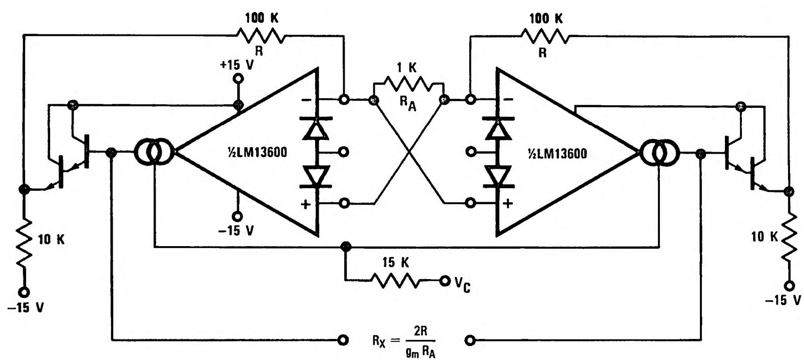

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FIGURE 10. Floating Voltage Controlled Resistor

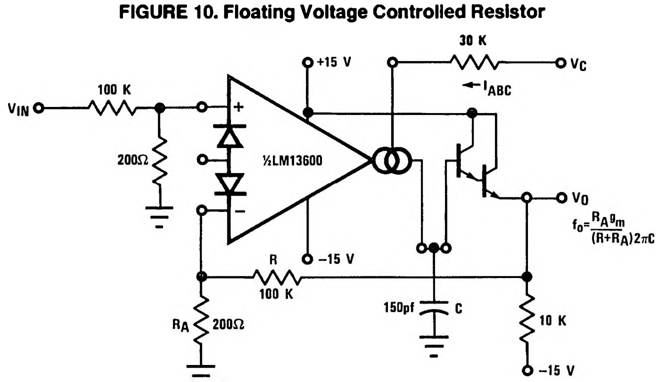

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FIGURE 11. Voltage Controlled Low-Pass Filter

Voltage Controlled Filters (Continued)

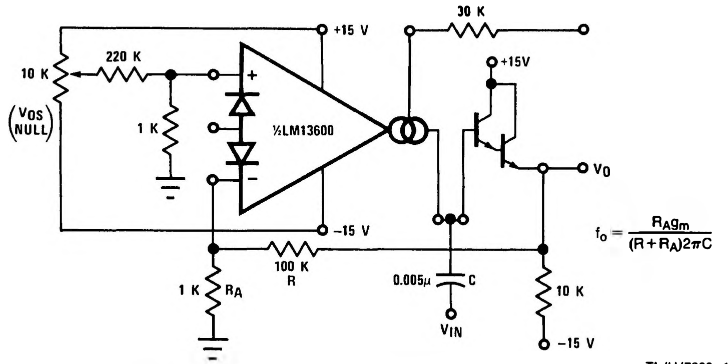

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FIGURE 12. Voltage Controlled Hi-Pass Filter

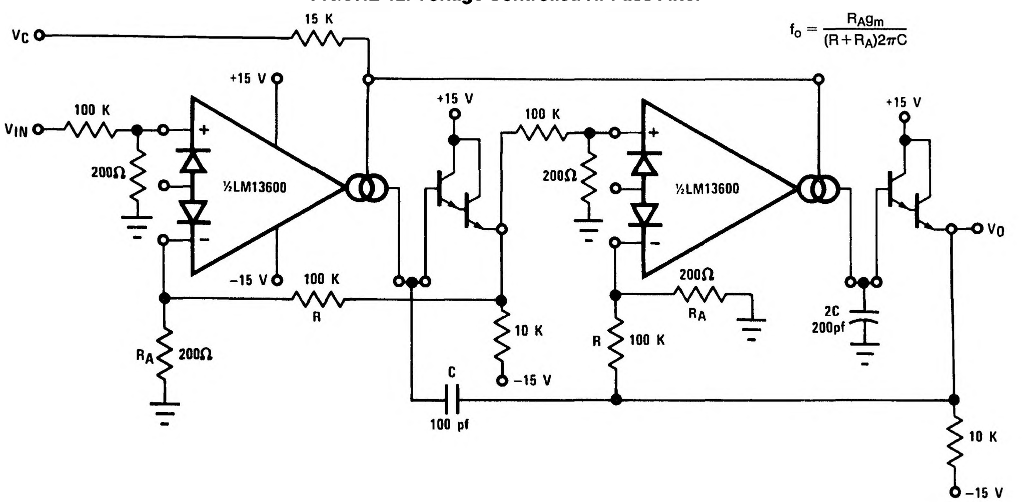

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FIGURE 13. Voltage Controlled 2-Pole Butterworth Lo-Pass Filter

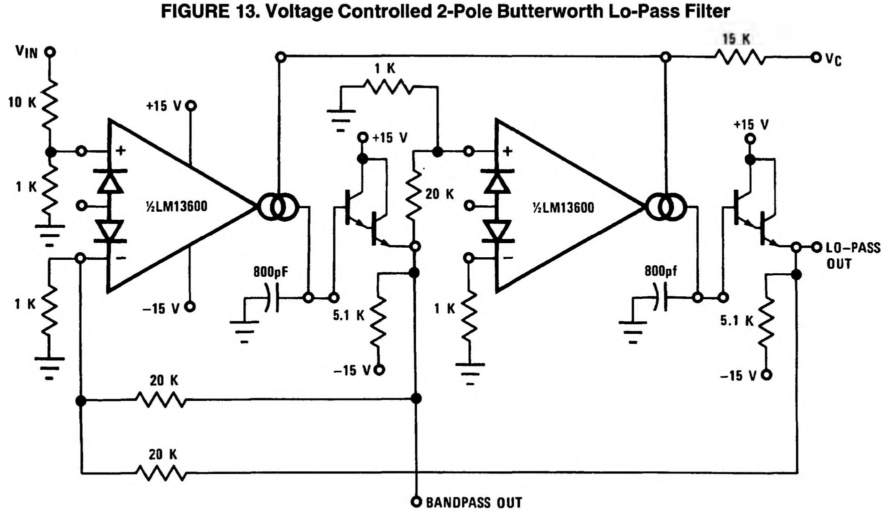

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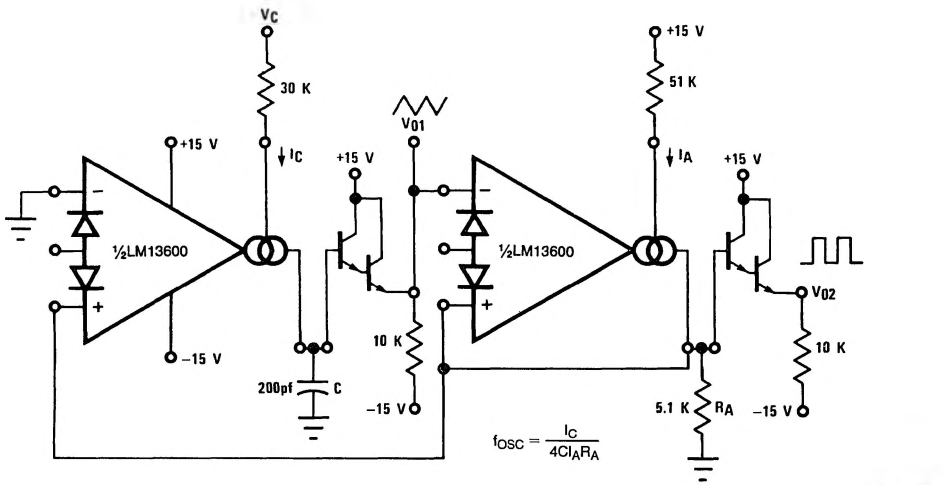
FIGURE 14. Voltage Controlled State Variable Filter

Voltage Controlled Oscillators

The classic Triangular/Square Wave VCO of *Figure 15* is one of a variety of Voltage Controlled Oscillators which may be built utilizing the LM13600. With the component values shown, this oscillator provides signals from 200 kHz to below 2 Hz as I_C is varied from 1 mA to 10 nA. The output amplitudes are set by $I_A \times R_A$. Note that the peak differential input voltage must be less than 5V to prevent zenering the inputs.

A few modifications to this circuit produce the ramp/pulse VCO of *Figure 16*. When V_{O2} is high, I_F is added to I_C to increase amplifier A1's bias current and thus to increase the charging rate of capacitor C. When V_{O2} is low, I_F goes to zero and the capacitor discharge current is set by I_C.

The VC Lo-Pass Filter of *Figure 11* may be used to produce a high-quality sinusoidal VCO. The circuit of *Figure 16* employs two LM13600 packages, with three of the amplifiers configured as lo-pass filters and the fourth as a limiter/inverter. The circuit oscillates at the frequency at which the loop phase-shift is 360° or 180° for the inverter and 60° per filter stage. This VCO operates from 5 Hz to 50 kHz with less than 1% THD.



$$f_{OSC} = \frac{I_C}{4CI_AR_A}$$

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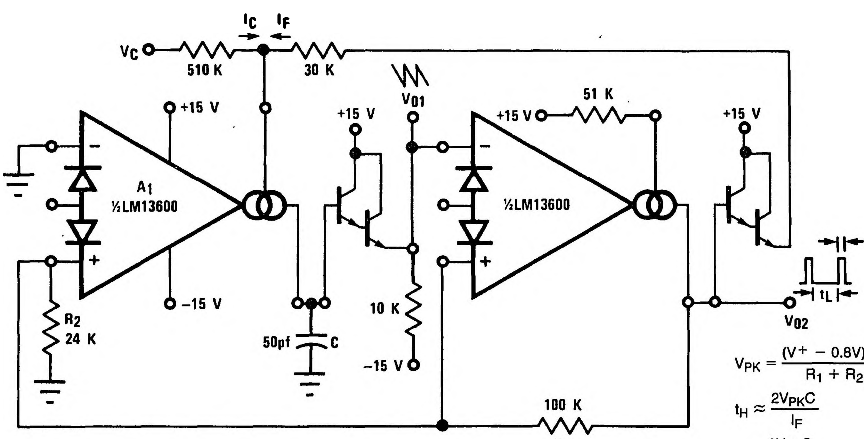
FIGURE 15. Triangular/Square-Wave VCO



$$V_{PK} = \frac{(V^+ - 0.8V)R_2}{R_1 + R_2}$$

$$t_H \approx \frac{2V_{PK}C}{I_F}$$

$$t_L = \frac{2V_{PK}C}{I_C}$$

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FIGURE 16. Ramp/Pulse VCO

$$f_O \approx \frac{I_C}{2V_{PK}C} \text{ for } I_C \ll I_F$$

Voltage Controlled Oscillators (Continued)

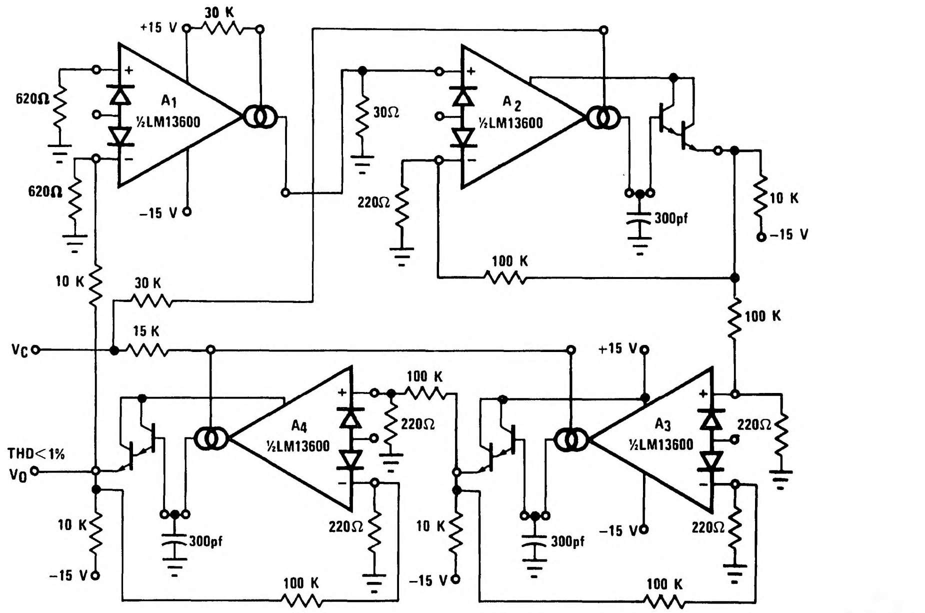

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FIGURE 17. Sinusoidal VCO

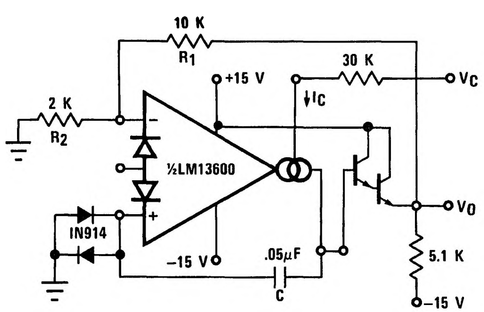

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FIGURE 18. Single Amplifier VCO

Figure 18 shows how to build a VCO using one amplifier when the other amplifier is needed for another function.

Additional Applications

Figure 19 presents an interesting one-shot which draws no power supply current until it is triggered. A positive-going trigger pulse of at least 2V amplitude turns on the amplifier through R_B and pulls the non-inverting input high. The amplifier regenerates and latches its output high until capacitor C charges to the voltage level on the non-inverting input. The output then switches low, turning off the amplifier and discharging the capacitor. The capacitor discharge rate is increased by shorting the diode bias pin to the inverting input so than an additional discharge current flows through D_I when the amplifier output switches low. A special feature of this timer is that the other amplifier, when biased from V_O, can perform another function and draw zero stand-by power as well.

The operation of the multiplexer of *Figure 20* is very straightforward. When A1 is turned on it holds V_O equal to V_{IN1} and when A2 is supplied with bias current then it controls V_O. C_C and R_C serve to stabilize the unity-gain configuration of amplifiers A1 and A2. The maximum clock rate is limited to about 200 kHz by the LM13600 slew rate into 150 pF when the (V_{IN1}-V_{IN2}) differential is at its maximum allowable value of 5V.

The Phase-Locked Loop of *Figure 21* uses the four-quadrant multiplier of *Figure 6* and the VCO of *Figure 18* to produce a PLL with a ±5% hold-in range and an input sensitivity of about 300 mV.

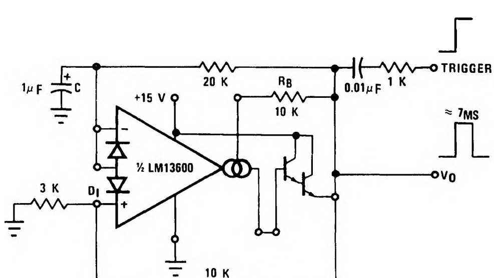

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FIGURE 19. Zero Stand-By Power Timer

Additional Applications (Continued)

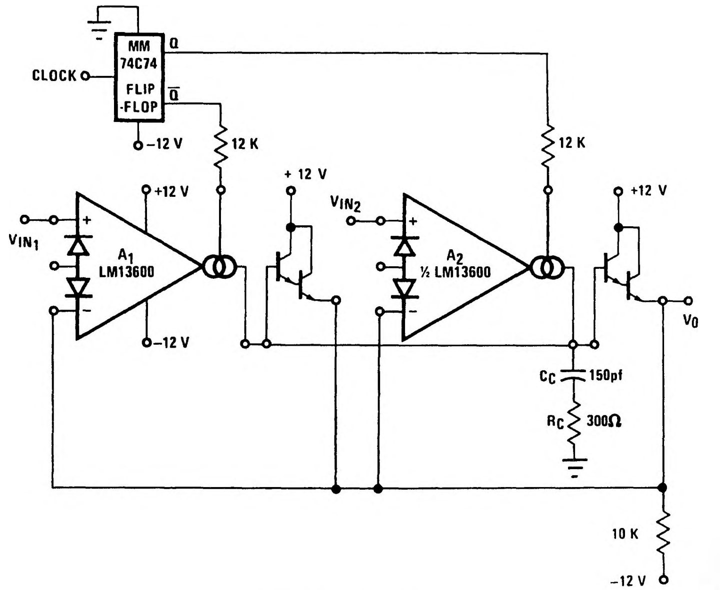

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FIGURE 20. Multiplexer

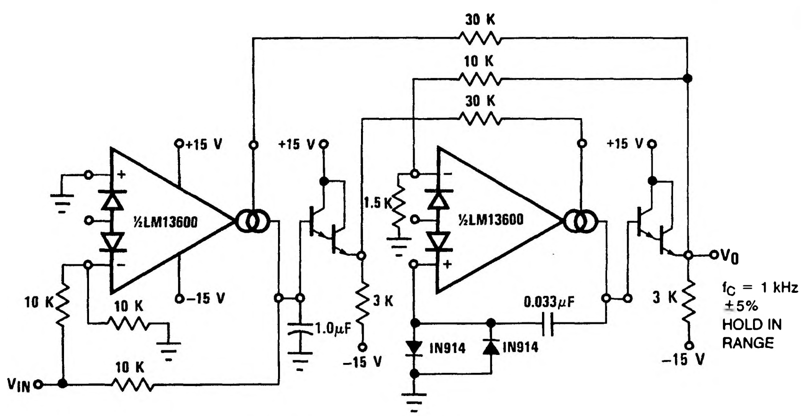

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FIGURE 21. Phase Lock Loop

The Schmitt Trigger of *Figure 22* uses the amplifier output current into R to set the hysteresis of the comparator; thus $V_H = 2 \times R \times I_B$. Varying I_B will produce a Schmitt Trigger with variable hysteresis.

Figure 23 shows a Tachometer or Frequency-to-Voltage converter. Whenever A1 is toggled by a positive-going input, an amount of charge equal to $(V_H - V_L)\ C_t$ is sourced into C_f and R_t. This once-per-cycle charge is then balanced by the current of V_O/R_t. The maximum f_{IN} is limited by the amount of time required to charge C_t from V_L to V_H with a current of I_B, where V_L and V_H represent the maximum low and maximum high output voltage swing of the LM13600. D1 is added to provide a discharge path for C_t when A1 switches low.

The Peak Detector of *Figure 24* uses A2 to turn on A1 whenever V_{IN} becomes more positive than V_O. A1 then charges storage capacitor C to hold V_O equal to $V_{IN}PK$. One precaution to observe when using this circuit: the Darlington transistor used must be on the same side of the package as A2 since the A1 Darlington will be turned on and off with A1. Pulling the output of A2 low through D1 serves to turn off A1 so that V_O remains constant.

Additional Applications (Continued)

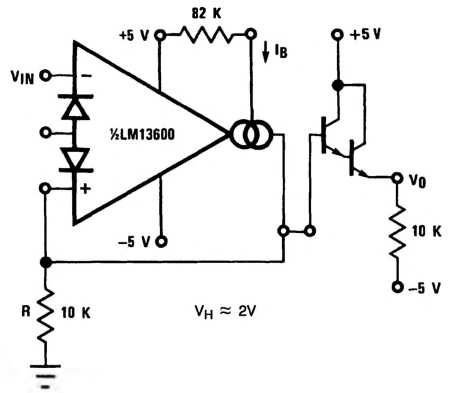

FIGURE 22. Schmitt Trigger

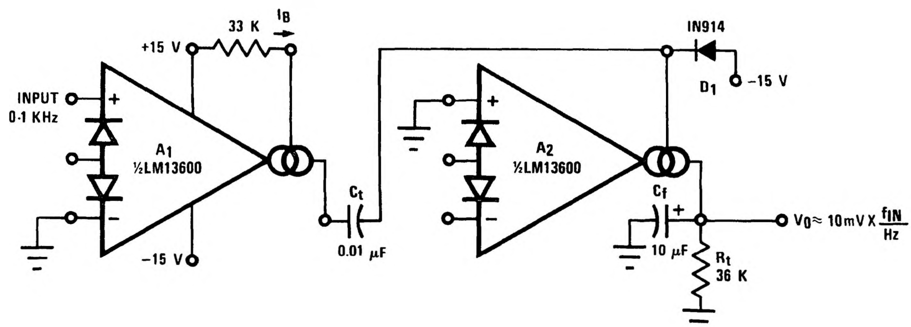

FIGURE 23. Tachometer

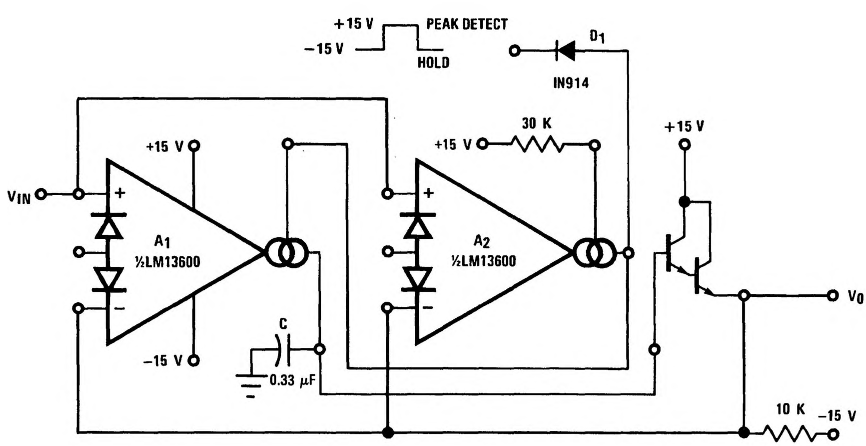

FIGURE 24. Peak Detector and Hold Circuit

Additional Applications (Continued)

The Sample-Hold circuit of *Figure 25* also requires that the Darlington buffer used be from the other (A2) half of the package and that the corresponding amplifier be biased on continuously. The Ramp-and-Hold of *Figure 26* sources I_B into capacitor C whenever the input to A1 is brought high, giving a ramp-rate of about 1 V/ms for the component values shown.

The true-RMS converter of *Figure 27* is essentially an automatic gain control amplifier which adjusts its gain such that the AC power at the output of amplifier A1 is constant. The output power of amplifier A1 is monitored by squaring amplifier A2 and the average compared to a reference voltage with amplifier A3. The output of A3 provides bias current to the diodes of A1 to attenuate the input signal. Because the output power of A1 is held constant, the RMS value is constant and the attentuation is directly proportional to the RMS value of the input voltage. The attenuation is also proportional to the diode bias current. Amplifier A4 adjusts the ratio of currents through the diodes to be equal and therefore the voltage at the output of A4 is proportional to the RMS value of the input voltage. The calibration potentiometer is set such that V_O reads directly in RMS volts.

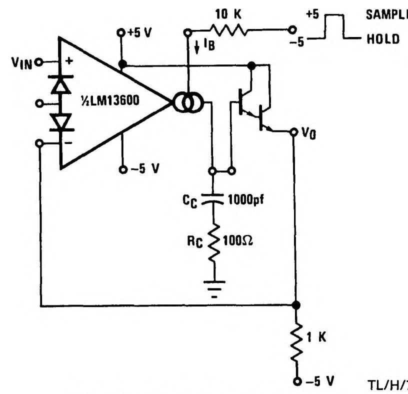

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FIGURE 25. Sample-Hold Circuit

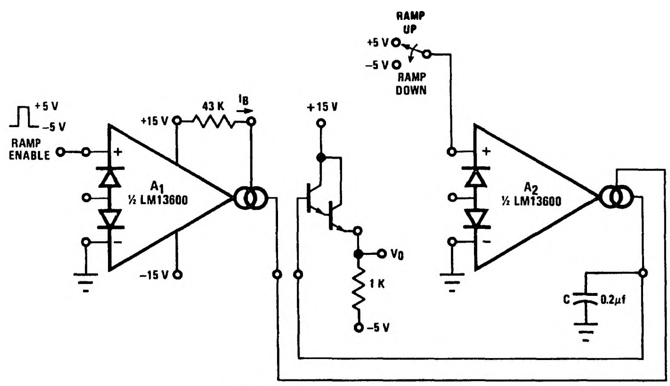

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FIGURE 26. Ramp and Hold

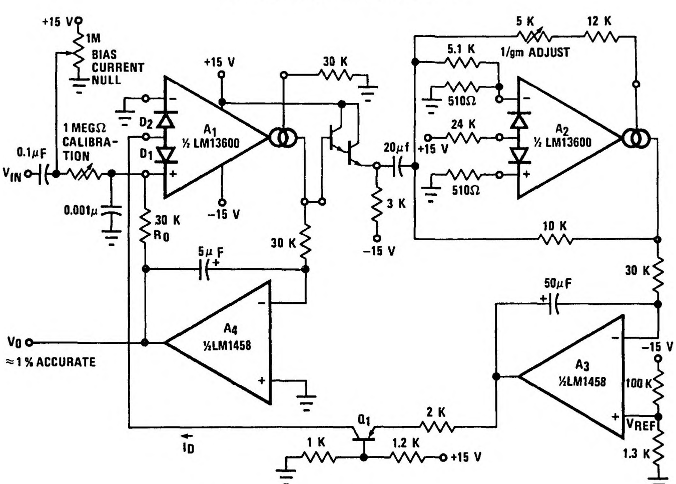

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FIGURE 27. True RMS Converter

Additional Applications (Continued)

The circuit of *Figure 28* is a voltage reference of variable temperature coefficient. The 100 kΩ potentiometer adjusts the output voltage which has a positive TC above 1.2V, zero TC at about 1.2V and negative TC below 1.2V. This is accomplished by balancing the TC of the A2 transfer function against the complementary TC of D1.

The log amplifier of *Figure 29* responds to the ratio of currents through buffer transistors Q3 and Q4. Zero temperature dependence for V_{OUT} is ensured because the TC of the A2 transfer function is equal and opposite to the TC of the logging transistors Q3 and Q4.

The wide dynamic range of the LM13600 allows easy control of the output pulse width in the Pulse Width Modulator of *Figure 30*.

For generating I_{ABC} over a range of 4 to 6 decades of current, the system of *Figure 31* provides a logarithmic current out for a linear voltage in.

Since the closed-loop configuration ensures that the input to A2 is held equal to 0V, the output current of A1 is equal to $I_3 = -V_C/R_C$.

The differential voltage between Q1 and Q2 is attenuated by the R1, R2 network so that A1 may be assumed to be operating within its linear range. From equation (5), the input voltage to A1 is:

$$V_{IN}1 = \frac{-2kTI_3}{qI_2} = \frac{2kTV_C}{qI_2R_C}$$

The voltage on the base of Q1 is then

$$V_B1 = \frac{(R_1+R_2)\,V_{IN}1}{R_1}$$

The ratio of the Q1 and Q2 collector currents is defined by:

$$V_B1 = \frac{kT}{q}\ln\frac{I_{C2}}{I_{C1}} \approx \frac{kT}{q}\ln\frac{I_{ABC}}{I_1}$$

Combining and solving for I_{ABC} yields:

$$I_{ABC} = I_1 \exp\left[\frac{2(R_1+R_2)\,V_C}{R_1I_2R_C}\right]$$

This logarithmic current can be used to bias the circuit of *Figure 4* provide a temperature independent stereo attenuation characteristic.

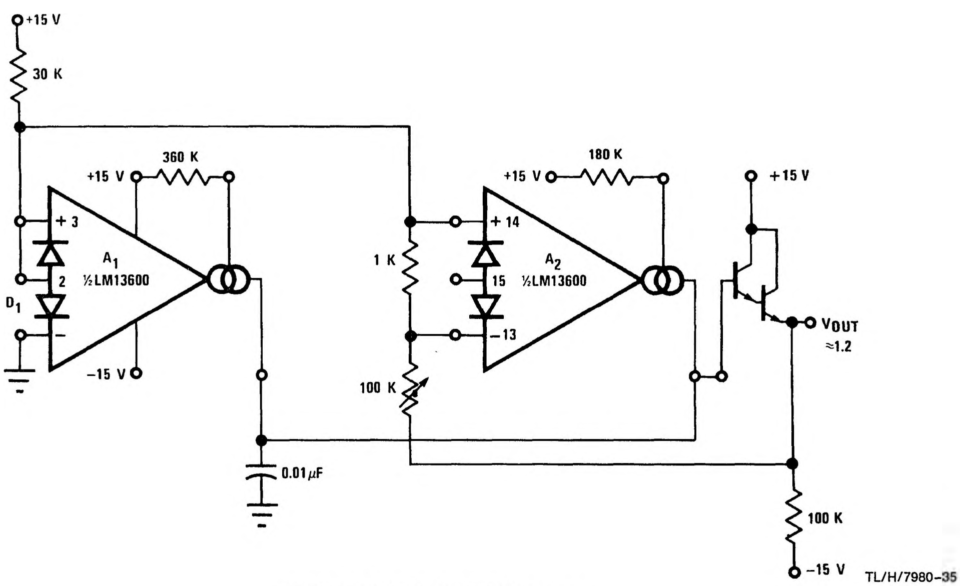

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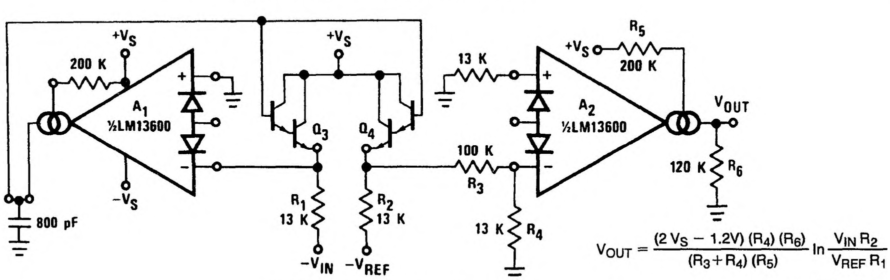
FIGURE 28. Delta VBE Reference



$$V_{OUT} = \frac{(2\,V_S - 1.2V)\,(R_4)\,(R_6)}{(R_3+R_4)\,(R_5)}\ln\frac{V_{IN}\,R_2}{V_{REF}\,R_1}$$

FIGURE 29. Log Amplifier

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Additional Applications (Continued)

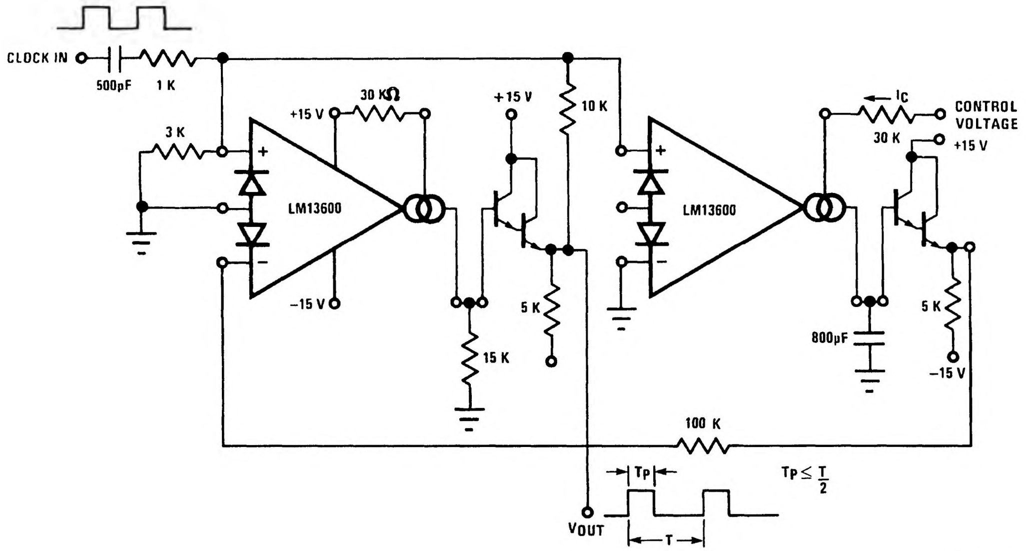

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FIGURE 30. Pulse Width Modulator

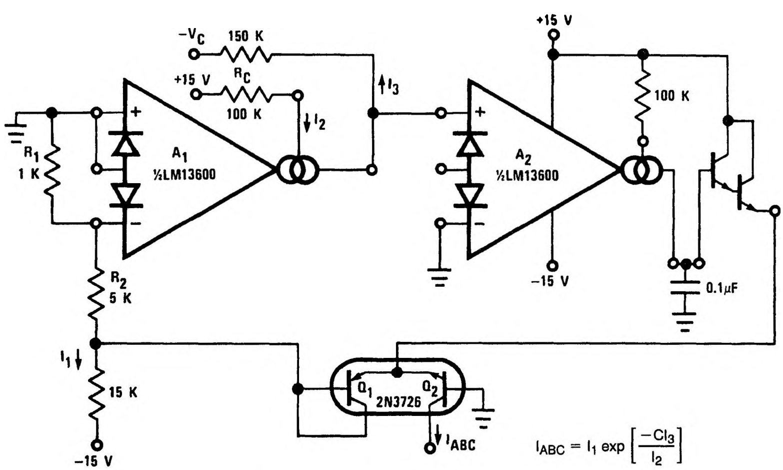

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FIGURE 31. Logarithmic Current Source