

Batch Application Toolkit



Important User Information

Read this document and the documents listed in the additional resources section about installation, configuration, and operation of this equipment before you install, configure, operate, or maintain this product. Users are required to familiarize themselves with installation and wiring instructions in addition to requirements of all applicable codes, laws, and standards.

Activities including installation, adjustments, putting into service, use, assembly, disassembly, and maintenance are required to be carried out by suitably trained personnel in accordance with applicable code of practice.

If this equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

In no event will Rockwell Automation, Inc. be responsible or liable for indirect or consequential damages resulting from the use or application of this equipment.

The examples and diagrams in this manual are included solely for illustrative purposes. Because of the many variables and requirements associated with any particular installation, Rockwell Automation, Inc. cannot assume responsibility or liability for actual use based on the examples and diagrams.

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Throughout this manual, when necessary, we use notes to make you aware of safety considerations.



WARNING: Identifies information about practices or circumstances that can cause an explosion in a hazardous environment, which may lead to personal injury or death, property damage, or economic loss.



ATTENTION: Identifies information about practices or circumstances that can lead to personal injury or death, property damage, or economic loss. Attentions help you identify a hazard, avoid a hazard, and recognize the consequence.

IMPORTANT

Identifies information that is critical for successful application and understanding of the product.

Labels may also be on or inside the equipment to provide specific precautions.



SHOCK HAZARD: Labels may be on or inside the equipment, for example, a drive or motor, to alert people that dangerous voltage may be present.

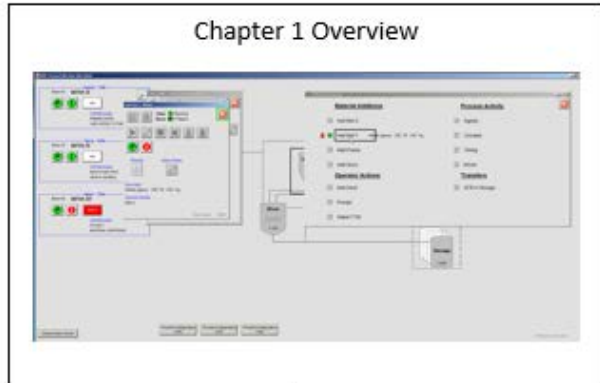


BURN HAZARD: Labels may be on or inside the equipment, for example, a drive or motor, to alert people that surfaces may reach dangerous temperatures.



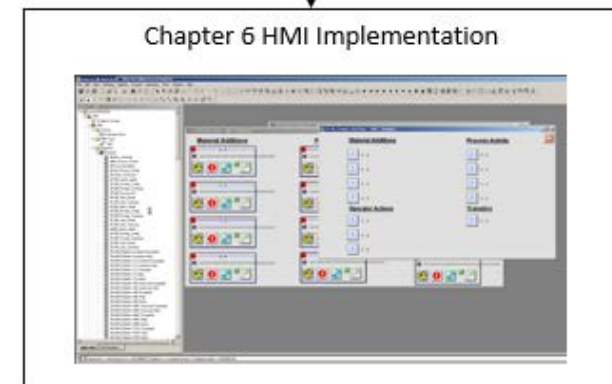
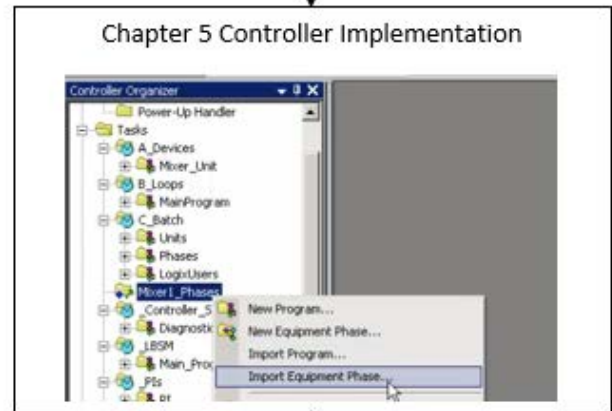
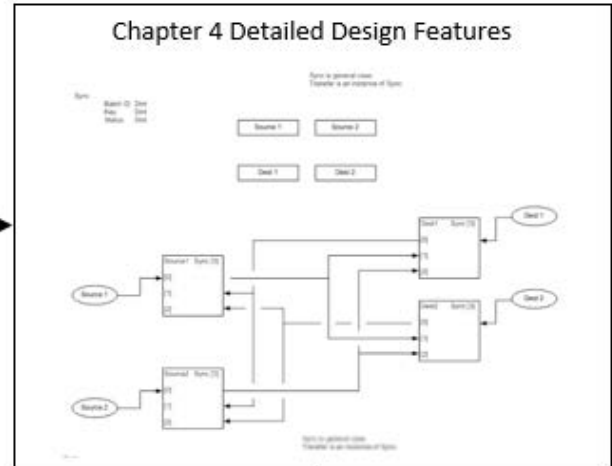
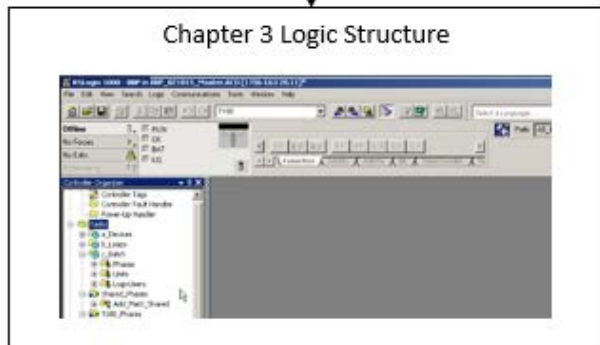
ARC FLASH HAZARD: Labels may be on or inside the equipment, for example, a motor control center, to alert people to potential Arc Flash. Arc Flash will cause severe injury or death. Wear proper Personal Protective Equipment (PPE). Follow ALL Regulatory requirements for safe work practices and for Personal Protective Equipment (PPE).

Follow this path to install and use your Batch Application Toolkit.



Chapter 2 Equipment Phase Set and Features

| Item | Phase | Comment |
|------|------------------------------------|--|
| 1 | Initiation | |
| 2 | Timing | With sync to other phases |
| 3 | Prompt | Free format, driven from recipe parameters |
| 4 | Dose or Material Add w/ Automation | |
| 5 | Hand Additions | Operator prompting |
| 6 | Transfer In / Transfer Out pairing | Coordination between units |
| 7 | Rinse | Device arbitration/allocation |
| 8 | Agitation | Non-Terminating w/ Transfer of Control |
| 9 | Circulation | Non-Terminating |
| 10 | Transfer Out | |
| 11 | Unit Message | |



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About This Publication

This quick start is designed to provide a framework for using the Batch Application Toolkit. Each section guides you through the tasks you need to complete in order to use the components of the Toolkit.

A sound understanding of the current parts of the ISA-88 batch processing control standards is necessary, including ANSI/ISA-88.01-2010 Batch Control Part 1: Models and Terminology. You should be knowledgeable of programming Rockwell Automation® Logix controllers with Studio 5000 environments and programming in FactoryTalk® View Studio. You should also be familiar with how to use the Rockwell Automation Process Library Objects, the FactoryTalk® Batch equipment and recipe editors, and the PlantPax® Logix Batch and Sequence Manager.

The beginning of each chapter contains the following information. Read these sections carefully before you begin work in each chapter:

- **Before You Begin** – This section lists the steps that must be completed and decisions that must be made before starting that chapter. The chapters in this quick start do not have to be completed in the order in which they appear, but this section defines the minimum amount of preparation that is required before completing the current chapter.
- **What You Need** – This section lists the tools that are required to complete the steps in the current chapter. These tools include, but are not limited to, hardware and software.
- **Follow These Steps** – This section illustrates the steps in the current chapter and identifies which steps are required to complete the examples by using specific networks.

Additional Resources

These documents contain additional information concerning related products from Rockwell Automation.

| Resource | Description |
|--|--|
| PhaseManager™ User Manual, publication LOGIX-UM001 | Explains how to set up and program a Logix5000™ controller to use equipment phases. Designed for users who program or maintain industrial automation systems. |
| PhaseManager Step Indexes and Restart Control Application Note, publication PROCES-AT016 | Discusses the purposes and uses of the step index in conjunction with the Logix PhaseManager instruction. Suggests numbering conventions and practices that facilitate the development of consistent and maintainable code. |
| Batch Process Skid Solutions White Paper, publication PROCES-WP001 | Provides an overview of how mixing and blending templates can be applied to batch control to help original equipment manufacturers save engineering time while complying with S88 standards. |
| FactoryTalk Batch User's Guide, publication BATCH-UM011 | Provides instructions on how to configure and administer a FactoryTalk batch system. Includes an Administrator's Guide, an Equipment Editor User's Guide, a Recipe Editor User's Guide, a View User's Guide, an Event Archiver User's Guide, and an ActiveX Controls User's Guide. |
| FactoryTalk Batch Software Suite Product Profile, publication FTALK-PP002 | Describes the features and capabilities of the FactoryTalk Batch Software Suite. |
| PlantPax Logix Batch and Sequence Manager Product Profile, publication PROCES-PP004 | Describes the features and benefits of the PlantPax Logix Batch and Sequence Manager. |
| Tips on Using PhaseManager with FactoryTalk Batch White Paper, publication FTALK-WP001 | Provides tips and instructions on how to use PhaseManager with FactoryTalk Batch software. |
| Clean in Place Made Simple White Paper, publication PROCES-WP003 | Discusses an approach that makes Clean in Place (CIP) automation a straight forward task. Provides ample modularity and flexibility through the use and application of ANSI/ISA-88 (S-88) concepts. |
| FactoryTalk Batch Technical Reference Guide, publication BATCH-RM111 | Provides information about the interface between the FactoryTalk Batch Server and the FactoryTalk Batch View. Includes a Server API Communication Language Reference, a PCD Programmer's Technical Reference, a System Files Reference Guide |

Preface

| Resource | Description |
|---|---|
| FactoryTalk Batch Material Manager User's Guide, publication BWMTR-UM011 | Provides instructions on how to configure, administer, and develop custom interfaces for a FactoryTalk Batch system. Includes a FactoryTalk Batch Material Editor User's Guide, a FactoryTalk Batch Material Manager Administrator's Guide, and a FactoryTalk Batch Material Servier API Technical Reference. |
| Batch Management and Control Brochure, publication BATCH-BR001 | Discusses the advantages of using the PlantPAx distributed control system in the batch management and control process. |
| Rockwell Automation Library of Process Objects Reference Manual, publication PROCES-RM002 | Describes how to use the Rockwell Automation Library of Process Objects and associated productivity tools. The instructions provide common process objects for controlling and interacting with motors, valves, pumps, and numerous other devices. |
| Rockwell Automation Library of Process Objects: Interlocks with First Out and Bypass (P_Intlk) Reference Manual, publication SYSLIB-RM004 | Defines the P_Intlk (Interlocks with First Out and Bypass) Add-On Instruction and its primary operations. Describes when it is used, and also provides programming examples. |
| Rockwell Automation Library of Process Objects: Permissives with Bypass (P_Perm) Reference Manual, publication SYSLIB-RM007 | Defines the P_Perm (Permissives with Bypass) Add-On Instruction and its primary operations. Describes when it is used, and also provides programming examples. |
| Rockwell Automation Library of Process Objects: Operator Prompt (P_Prompt) Reference Manual, publication SYSLIB-RM046 | Defines the P_Prompt (Operator Prompt) Add-On Instruction and its primary operations. Describes when it is used, and also provides programming examples. |
| Logix5000 Controllers Design Considerations Reference Manual, publication 1756-RM094 | Provides detailed design information about the Logix5000 controllers. |
| FactoryTalk View Site Edition User's Guide, publication VIEWSE-UM006 | Provides information on how to use the FactoryTalk View Site Edition software to develop and run human-machine interface (HMI) applications that can involve multiple users and servers, distributed over a network. |
| PlantPAx Process Automation System Reference Manual, publication PROCES-RM001 | Elaborates on the application rules required to set up a PlantPAx distributed control system. |
| PlantPAx Process Automation System Selection Guide, publication PROCES-SG001 | Provides basic definitions of system elements and sizing guidelines for procuring a PlantPAx distributed control system. |
| PlantPAx System Application Templates Quick Start, publication PROCES-QS001 | Describes how to configure controller and HMI templates to start development of your PlantPAx distributed control system. |
| Industrial Automation Wiring and Grounding Guidelines, publication 1770-4.1 | Provides general guidelines for installing a Rockwell Automation industrial system. |
| Product Certifications website, http://www.ab.com | Provides declarations of conformity, certificates, and other certification details. |

You can view or download publications at <http://www.rockwellautomation.com/literature/>. To order paper copies of technical documentation, contact your local Allen-Bradley distributor or Rockwell Automation sales representative.

Overview

In this chapter, you learn about the content and purpose of the Batch Application Toolkit.

The Batch Application Toolkit is a collection of documentation, equipment phases, support routines, and associated HMI components that can assist you in the development of a Batch Solution using Integrated Architecture or the PlantPAx® distributed control system. It serves as a starting point to a batch project, and it demonstrates one chosen and specific batch-control philosophy that can be modified to meet your own specific needs or philosophy.

The Batch Application Toolkit was designed by using a three-unit process. These units illustrate the use of shared resources, coordinated transfers between units, and a wide selection of common equipment modules and phases found in most batch control applications.

The toolkit integrates batch process control with the Rockwell Automation® Library of Process Objects, providing a consistent look and feel at the phase and unit levels. However, the design methodology is not limited to the Rockwell Automation® Library of Process Object users.

Before You Begin

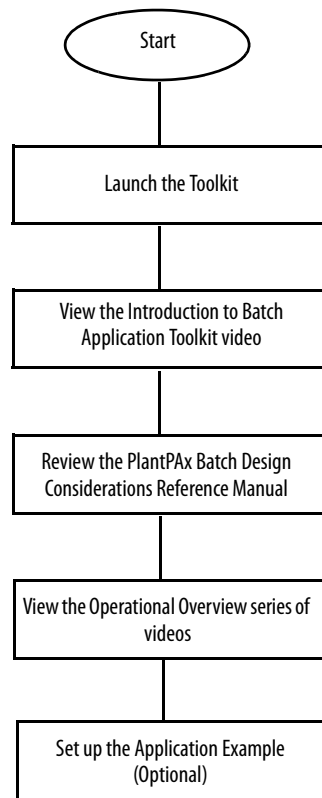
- Download and install the Batch Application Toolkit.

What You Need

- Batch Application Toolkit - [Introduction to Batch Application Toolkit](#) video
- Batch Application Toolkit - Operational Overview series of videos
- PlantPAx Batch Design Considerations Reference Manual, publication [PROCES-RM008](#)

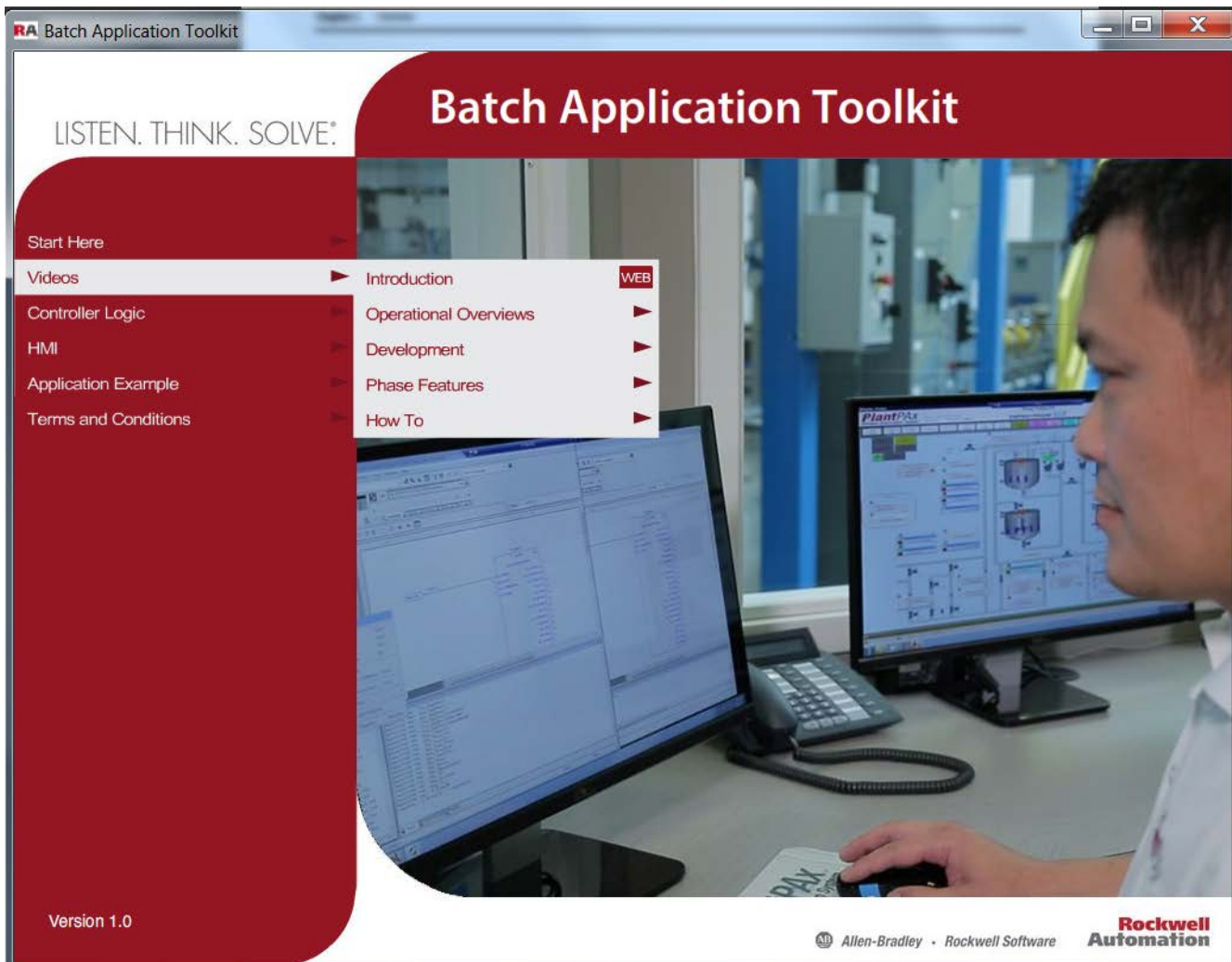
Follow These Steps

Complete these steps to familiarize yourself with the Batch Application Toolkit.



Launch the Toolkit

When you launch the Batch Application Toolkit, a splash screen appears. It provides links to the Quick Start manual, videos, controller, and HMI files.



View the Introduction to Batch Application Toolkit Video

Review the [Introduction to Batch Application Toolkit](#) video for an overview of the content and purpose of the Batch Application Toolkit.

Review the PlantPax Batch Design Considerations Reference Manual

Review the PlantPax Batch Design Considerations Reference Manual, publication [PROCES-RM008](#), which provides guidance on selected batch implementation topics in a Rockwell Automation PlantPax distributed control system. The information helps you make informed decisions when you implement projects by using FactoryTalk Batch, LBSM, or other batch management solutions.

The Batch Application Toolkit illustrates some of the implementation options that are outlined in this document. [Table 1](#) showcases the design consideration choices that were made when creating this first release. Future releases may provide additional application examples to help guide you in making the best design choice for your application.

Table 1 - Design Considerations

| PlantPax Batch Design Considerations (PROCES-RM008) | Batch Application Toolkit Implementation |
|---|--|
| Unit Coordination and Synchronization | Controller-based - Handshaking takes place using controller tags |
| Operator Interaction | P_Prompt |
| Material Management | Not implemented |
| Process Upsets | Active State Processing |
| Transitions | Not implemented |
| Batch Timing | Controller based phase |
| Resource Arbitration and Allocation | Controller based |
| Shared Phases | Controller based |
| Two or Three Layer Mode | Two-layer Model - PhaseManager software hosts the Equipment Phase and Equipment Module as one layer |
| Implementation Techniques | Recommended techniques were followed in the toolkit: Standard Phases, Device Ownership, Mode, Naming Conventions, Reset/Idle state |

View the Operational Overview Videos

The Operational Overview series of videos describe the process cell example that was used to build the library of phases in the toolkit, highlight some of the general design concepts that are applied in the toolkit, and provide an overview of the HMI interface philosophy.

Review the following videos:

- [Operational Overview – Process Cell Example](#)
- [Operational Overview – Object, Phase, and Unit Faceplates](#)
- [Operational Overview – Unit Detail and Summary Display](#)
- [Operational Overview – Batch Detail Display](#)
- [Operational Overview – Phase Ownership](#)
- [Operational Overview – Device Ownership and Interlocks](#)
- [Operational Overview – Phase Operation in Operator Mode](#)
- [Operational Overview – Device Acquisition and Locking](#)
- [Operational Overview – Operator Interface for Managing Batches](#)
- [Operational Overview – Material Addition Phase](#)
- [Operational Overview – Add Hand Phase](#)
- [Operational Overview – Adjust Phase](#)

Set up the Example Application (Optional)

For information on how to set up and run the example application that is provided with the toolkit, refer to the following video:

[How To – Setup the Application Example](#)

Notes:

Equipment Phase Set and Features

In this chapter, you learn about the library of phases and features that are included in the Batch Application Toolkit.

Before You Begin

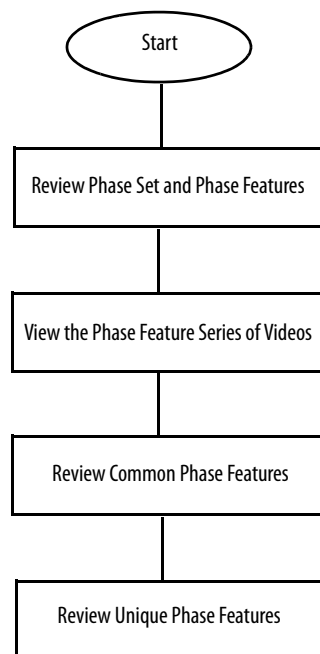
- Review the information in [Chapter 1](#).

What You Need

- Batch Application Toolkit - Phase Features series of videos

Follow These Steps

Complete these steps to learn about the phase set and features included in the Batch Application Toolkit.



Phase Set

The Batch Application Toolkit includes a library of phases that are found in most batch applications.

Table 2 - Phase Set

| Item | Phase | Comment |
|------|------------------------------------|--|
| 1 | Init(iation) | |
| 2 | Timing | With sync to other phases |
| 3 | Prompt | Free format, driven from recipe parameters |
| 4 | Dose or Material Add w/ Automation | |
| 5 | Hand Additions | Operator prompting |
| 6 | Transfer In / Transfer Out pairing | Coordination between units |
| 7 | Rinse | Device arbitration/allocation |
| 8 | Agitation | Non-Terminating w/ Transfer of Control |
| 9 | Circulation | Non-Terminating |
| 10 | Transfer Out | |
| 11 | Unit Message | |

Phase Features

Using various phases, the following functions are demonstrated. These functions can be cut and pasted as needed between various phases.

Table 3 - Phase Features

| Item | Feature – Function | See Phase | Comment |
|------|---|----------------------------------|---------------------|
| 1 | Obtaining User / Unique Batch ID | Init | PXRQ implementation |
| 2 | Shared Phase | Add_MatX_Shared | |
| 3 | Dosing w/ Flow Meter | Add_MatY_T100 | |
| 4 | Dosing w/ Load Cell | XFI_Slurry_T100 | |
| 5 | Dosing with Full / Dribble using Valves | XFI_Slurry_T100 | |
| 6 | Dosing with Full / Dribble using VSD | Add_MatX_Shared | |
| 7 | Dosing with phase driven logic | Add_MatY_T100 | |
| 8 | Dosing with coordinated function blocks | XFI_Slurry_T100 | |
| 9 | PID Flow Control | Circulate_T100 | |
| 10 | Transfer of Control | Agitate_T100 | New Parameters |
| 11 | Dedicated source / destination pair | XFO_Slurry_T400, XFI_Slurry_T100 | |
| 12 | Multiple source / destination pairs | XFO_Premix_T300, XFI_Premix_T100 | |
| 13 | Interfacing to PlantPAx objects | Add_MatY_T100 (and most others) | a_Devices routine |
| 14 | Sync and Auto-Sync | Timing_T100 | |
| 15 | Agitation w/ VSD | Agitate_T100 | |
| 16 | Agitation w/ Fixed Speed Motor | Agitate_T300 | |

Table 3 - Phase Features

| Item | Feature – Function | See Phase | Comment |
|------|---------------------------------|-------------------------|---------|
| 17 | Agitation w/ Process Interlock | Agitate_T300 | |
| 18 | Device Arbitration / allocation | Rinse_T300/T400 | |
| 19 | Phase Interlocking | Circulate_T100/XFO_T100 | |

Phase Features Videos

Review the following videos:

[Phase Features – Timing Phase Synchronization](#)

[Phase Features – Transfer Phases – Coordinated 1 to 1](#)

[Phase Features – Transfer Phases – Coordinated 1 to Many](#)

[Phase Features – Transfer Phases – Quick Add](#)

[Phase Features – Shared Resources – Shared Phases](#)

[Phase Features – Shared Resources – Device Level Allocation and Arbitration](#)

[Phase Features – Shared Resources – Interlocked Phases](#)

[Phase Features – Handling Device Level Interlocks](#)

[Phase Features – Transfer of Control](#)

[Phase Features – Initiation Phase](#)

[Phase Features – Material Addition Tolerance Checks](#)

Common Phase Features

All phases include the following features.

Table 4 - Common Phase Features

| Item | Feature | Comment |
|------|-----------------------------|---|
| 1 | Mode or ownership model | Distinguish and manage 4 users |
| 2 | Operator phase control | |
| 3 | Phase alarm processing | In-state w/ operator prompt for resolution |
| 4 | Permissive and Interlocking | Rapid detection of ownership or alarm conditions |
| 5 | Common structure | Identical Step indexes for all phases |
| 6 | Device independence | “Library” phases which can be characterized |
| 7 | Activity display | Summary and Detailed |
| 8 | HMI Global Object support | Phase Display Element, Phase and Unit Status objects, Phase and Prompt Summary objects, |
| 9 | Context prompting | |

Operator Phase Control

All phases can be controlled, by the operator, from faceplates.

All phases begin with an operator prompt, getting needed data to execute the phase. Although the phase may need many parameters, operator prompting is limited to necessary data and then supplemented with default parameters.

For example, an addition phase may have Setpoint, High Tolerance, and Low Tolerance Parameters. The recipe author can configure all these parameters in the recipe, but the operator only needs to enter a Setpoint. Entering High Tolerance and Low Tolerance values are a needless nuisance to an operator. Therefore, they are defaulted, typically to where tolerances are ignored on an operator-initiated material addition.

Alarming

Phase alarms can be configured for "Reset Required."

When 'Reset' is "Not Required," the phase immediately continues with its activity when all alarms are cleared. When 'Reset' is "Required," the [Phase Alarm Reset] must be entered after all alarm conditions have been acknowledged and reset. [Phase Alarm Reset] is available on the phase faceplate or phase status object.

Unique Phase Features

Unique phase features include synchronized timing, operator phase control, and interlocked equipment.

Synchronized Timing

Timing features "sync" and "auto-sync" parameters.

"Sync" indicates that timing only occurs when a "synced" or paired phase(s) is in the functioning step (SI=1500). For example, if "Timing" is "synced" with 'Circulation,' timing only occurs when circulation is in StepIndex = 1500, or when material is actually circulating. If Circulation leaves SI=1500 (eg Alarm or Hold), timing stops. Timing continues when Circulation returns to SI=1500.

The Batch Application Toolkit is provided with capability to synchronize up to two phases (Agitation and/or Circulation). The "synced" phases are defined with alias tags. Follow the code structure and modify accordingly if more than two "synced" phases are needed.

Configuration defines synchronization mode. The following options are provided:

- None
- Auto-Sync
- "A" only
- "B" only
- "A and B"

The configuration can be set by the recipe author as a recipe parameter.

"Auto-Sync" indicates the 'Timing' phase automatically synchronizes to either of the two defined paired phases, if one or both of those phases are configured in parallel in the recipe procedure. This feature reduces recipe author effort and potential errors.

Operator Phase Control

Material Additions

Material Addition phases include a "New" or "Last Entered" option. When "Last Entered" is selected, the phase uses the last Operator entered setpoint for the addition. This option is convenient when the same amount is normally entered, for example, for a repeated scale calibration sequence.

Transfers

Material transfers, coordinated with a transfer in/transfer out (XFI / XFO), include a "Non-Coordinated/Coordinated" option. Transfers need to be initiated from the XFI (destination) side of the link. "Non-Coordinated" indicates the XFI executes the transfer without handshaking, linking, or coordinating to the paired source. "Coordinated" indicates that the paired source XFO phase must be running and "ready to deliver."

The "Non-Coordinated" feature simplifies operator-initiated transfers, since the operator can verify whether the source is ready. "Non-Coordinated" eliminates the need for the operator to also start an XFO phase, which often is a redundant and unnecessary activity.

Interlocked Equipment

Occasionally, interlocked equipment has to be managed differently, depending on mode. Agitation_T300 represents such a scenario and is a method for dealing with this requirement.

In this case, the agitator is interlocked to low level and configured as such at the control module level. This prevents the operator from both starting the agitator, and continuing to run the agitator when the tank level is low. However, when a batch runs, the recipe author wants the agitation phase to begin usually in parallel to other activity. The recipe author should not be burdened with writing procedural logic to handle this low-level interlock situation.

An easy solution is to do the following:

1. Condition the CM interlock based on phase state.
2. Manage starting and stopping the agitator while considering interlock conditions in the phase.

Looking at M300 in the toolkit example, you can see where interlocks are conditioned on the phase being idle. Examining Agitate_T300, SI=900 and SI=1500, you can see where the interlock status is examined, resulting in a start and stop of the agitator.

An extra, interesting function is provided with this phase's configuration. Note at SI=2000, after the agitator is stopped, the phase returns to SI=900. Since this is a non-terminating phase, the phase continues to start and stop the agitator, based on tank level, as long as the phase is active. This simplifies recipe authoring for a tank that is filled and emptied several times during the course of the operation.

Notes:

Logic Structure

In this chapter, you learn about the logic structures used in the Batch Application Toolkit.

Before You Begin

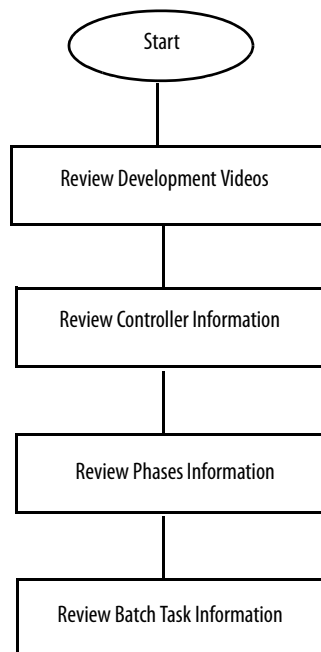
- Review the information in [Chapter 2](#).
- Ensure that you are familiar with Logix controllers.

What You Need

- Batch Application Toolkit - Development series of videos

Follow These Steps

Complete these steps to learn about the logic structure of the Batch Application Toolkit.



Development Videos

Review the following Development videos for information on how the logic structure has been configured in the toolkit:

[Development – Phase Design](#)

[Development – a_Devices Routine](#)

[Development – b_Perm_Intlk Routine](#)

[Development – c_HMI_Interface Routine](#)

[Development – Equipment Phase Organization and Scheduling](#)

[Development – Unit Routine](#)

[Development – LogixUser Routine](#)

Controller Information

The controller must be configured with the following considerations,

1. The controller must be based on Logix version 21, or earlier.
 - a. Structures can be changed to take advantage of a version 22, or later, controller organizer
2. The controller uses "Event Task" to build a batch unit hierarchy.
 - a. Event Task" is called from a single, periodic task.
 - b. Concept can only be used in non-redundant controllers.
3. The toolkit does not define an organization model for control modules.
 - a. Control modules can be developed and organized following your company standards.
 - b. The toolkit leverages Rockwell Automation Process Objects, however, using these objects is not a requirement.
 - c. Control module tags need to be controller scoped to accommodate phase access.

Phases Information

Phases are built using PhaseManager and its associated states. In addition to the state routines, phases have a minimum of three supporting routines.

1. Devices characterize the generic phase, identify and interface to explicit control modules, and support the following activities:
 - a. Acquire/Release ownership
 - b. Lock/Unlock
 - c. Open/Close - Start/Stop, as needed
2. Perm_Intlk contains the Phase P_Perm, P_Intlk, and P_Alarm objects. It also contains explicit mapping or "rungs" for each permissive or interlock condition.
3. HMI_Interface contains a number of "sections" to interface phase to system. System interfacing includes unit and HMI. The sections are:
 - a. Mode or Ownership, which contains a P_Mode object. It also contains rungs to detect phase ownership (RSLogix_5000, FTBatch), rungs for LogixUsers ownership, and rungs for Operator ownership.

- b. Operator commands
 - c. Phase activity
 - d. Unit summary
 - e. Phase summary
4. The sync routine is only required when the phase is configured as a paired phase (synchronized with another phase).

Batch Task Information

The Batch Task contains a number of programs to support the system.

1. Unit:
 - a. Contains a separate routine for each unit.
 - b. Each unit routine contains Permissive and Interlock, and Unit Summary.
2. LogixUsers:
 - a. Contains a routine for each phase.
 - b. Each routine has the PATT and PDET ownership instructions and the PCMD's for external phase control.
3. Phases:
 - a. Calls the Unit Event Tasks.

Notes:

Detailed Design Features

In this chapter, you learn about the detailed design features of the Batch Application Toolkit.

Before You Begin

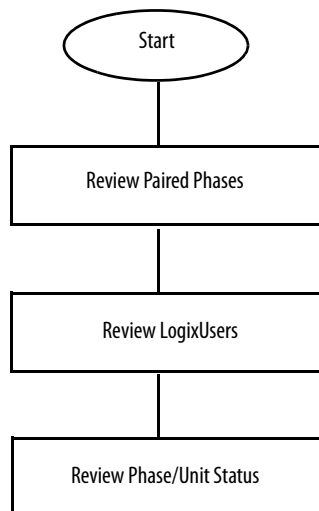
- Review the information in [Chapter 1](#) through [Chapter 3](#).

What You Need

- Batch Application Toolkit – [Development – Phase Synchronization](#) video
- Batch Application Toolkit – [Development – LogixUsers Interface](#) video
- Batch Application Toolkit – [Development – Unit Routine](#) video

Follow These Steps

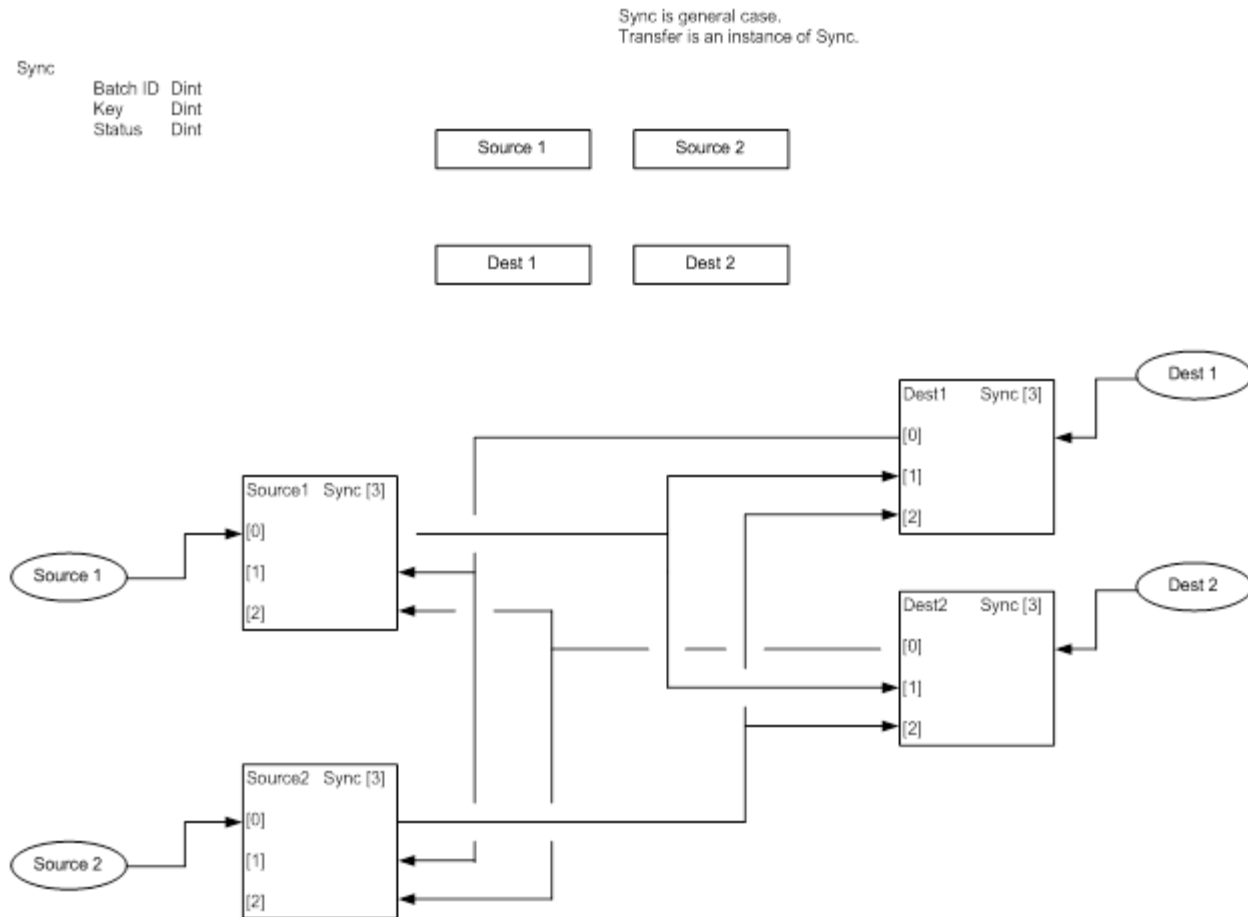
Complete these steps to gain an in-depth understanding of the detailed design features of the Batch Application Toolkit.



Paired Phases

Review the [Development – Phase Synchronization](#) video for details on how Paired Phases have been configured in the toolkit. [Figure 1](#) illustrates how synchronization data is mapped between units.

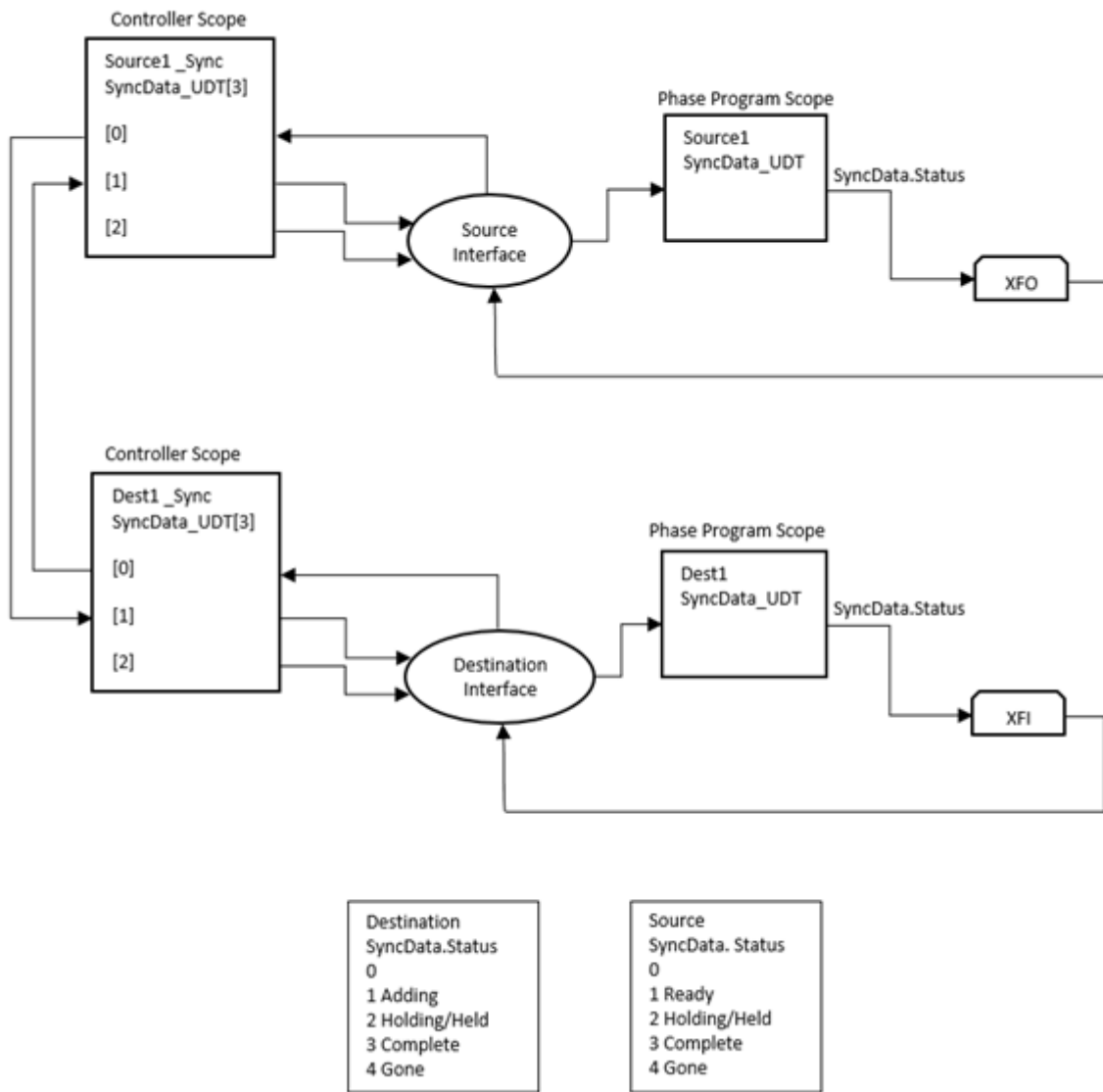
Figure 1 - Sync Data Mapping



The exchange is external to the phase, allowing phase "ing" states to be generic and independent of synchronized units and distribution.

Figure 2 shows the exchange between paired phases.

Figure 2 - Paired Phase Exchange



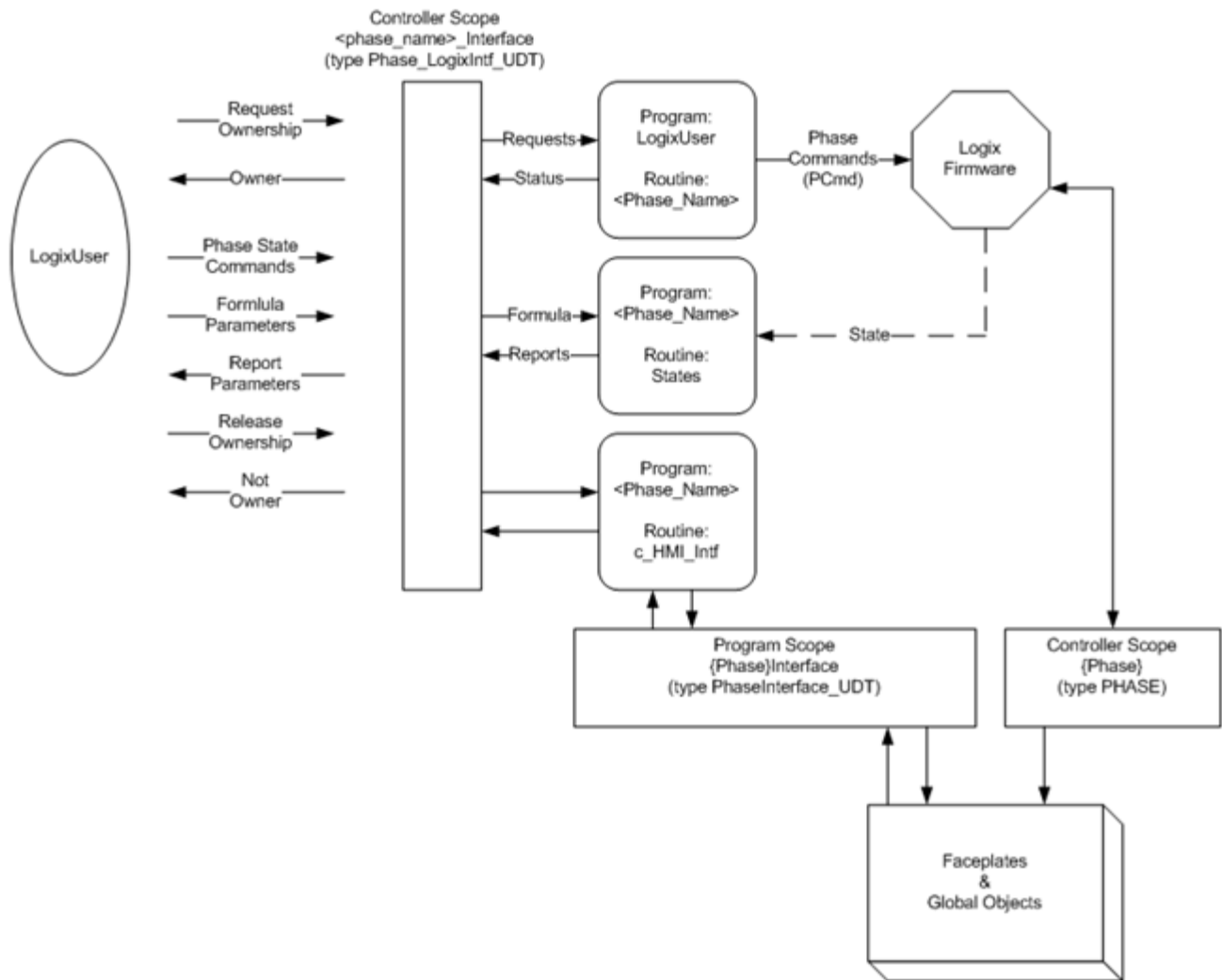
LogixUsers

LogixUsers are entities, other than FTBatch or Operator, that can own and command a phase. Examples of a LogixUser include a phase calling another phase, or a phase being called by a user-created Logix task.

Review the [Development – LogixUsers Interface](#) video for details on how this interface is configured in the toolkit.

LogixUsers interface, exclusively, through the controller scoped `<phase_name>_Intf` tag, as illustrated in [Figure 3](#). Refer to [Table 5](#) for the structure of this user-defined data type.

Figure 3 - LogixUsers Interface



The general interaction for a LogixUser is as follows.

1. LogixUser requests ownership of phase (Reqx = 1).
2. LogixUser waits until ownership is granted (Owner = x).
3. LogixUser sends state commands (Start, Hold, Stop, Reset, for example).
4. LogixUser sends formula parameters and can read report parameters.

5. LogixUser completes phase activity.
6. LogixUser must always leave phase in IDLE state when finished.
7. LogixUser releases ownership of phase (Reqx = 0).

The design supports and arbitrates between four LogixUsers. Additional users can be added, if necessary.

LogixUsers send requests and commands through <phase_name>_Intf. The layout of this interface is as follows:

- Ownership requests and ID's are paired. For example:
 - LogixUser #1 would set PCmd_Dint.16 and wait for Sts_Owner = 1.
 - LogixUser #2 would set PCmd_Dint.17 and wait for Sts_Owner = 2.
- Multiple LogixUsers are arbitrated on a first-come/first-serve basis.
 - Simultaneous requests go to the lowest number (LogixUser#1 wins over LogixUser#2).
- Formula Parameters need to be mapped in StepIndex = 100 of the Phase Running state routine.
- Report Parameters need to be mapped.
- Operator ownership and control (from HMI Global Object faceplates) is available and arbitrated in conjunction with LogixUsers.
- The report and parameter structures follow the formats of and therefore are compatible with P_Prompt and LBSM.

Table 5 - Phase_LogixIntf_UDT Structure

| UDT | Element | Data Type | Bit | Significance / Note |
|---------------------|-----------|-----------|-----|---------------------|
| Phase_LogixIntf_UDT | | | | |
| | PCmd_Dint | Dint | | |
| | | | 0 | |
| | | | 1 | |
| | | | 2 | |
| | | | 3 | Start |
| | | | 4 | Hold |
| | | | 5 | Resume |
| | | | 6 | Stop |
| | | | 7 | Abort |
| | | | 8 | Reset |
| | | | 9 | (xxxx) reserved |
| | | | 10 | |
| | | | 11 | |
| | | | 12 | |
| | | | 13 | |
| | | | 14 | |
| | | | 15 | |
| | | | 16 | OwnershipReq1 |
| | | | 17 | OwnershipReq2 |
| | | | 18 | OwnershipReq3 |
| | | | 19 | OwnershipReq4 |
| | Sts_Dint | Dint | | |

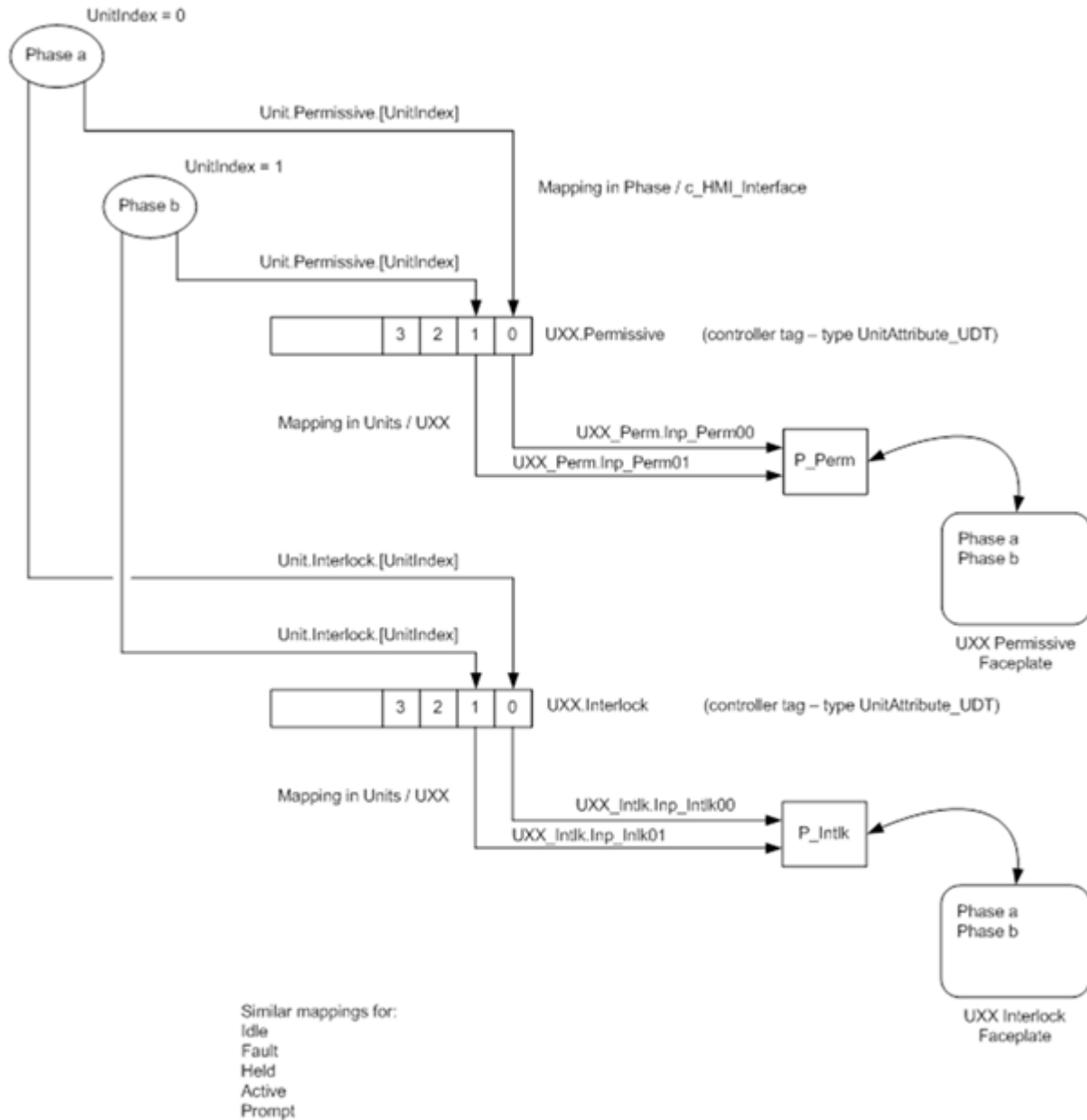
Table 5 - Phase_LogixIntf_UDT Structure

| UDT | Element | Data Type | Bit | Significance / Note |
|-----|---------------|-----------|-----|---------------------|
| | | | 0 | |
| | | | 1 | |
| | | | 2 | |
| | | | 3 | |
| | | | 4 | |
| | | | 5 | |
| | | | 6 | |
| | | | 7 | |
| | Sts_Owner | Dint | | 1 to x for owner ID |
| | Sts_Mode | Dint | | |
| | | | | |
| | PCmd_Target01 | Real | | |
| | PCmd_Target02 | Real | | |
| | PCmd_Target03 | Real | | |
| | PCmd_Target04 | Real | | |
| | PCmd_Select | Dint | | |
| | | | | |
| | Val_Report01 | Real | | |
| | Val_Report02 | Real | | |

Phase/Unit Status

Review the [Development – Unit Routine](#) video for details on how the phase status is rolled up into the Unit status. [Figure 4](#) provides additional details on how this is accomplished.

Figure 4 - Phase/Unit Status



Individual phase status is rolled into a consolidated unit status which summarizes all phases associated with that unit.

Notes:

Controller Implementation

In this chapter, you learn how to configure an equipment phase and supporting routines in the controller.

Before You Begin

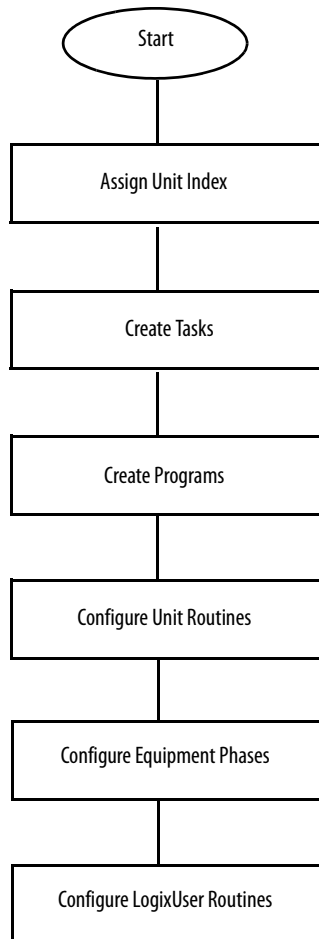
- Review [Chapter 1](#) through [Chapter 4](#).

What You Need

- Batch Application Toolkit – Development series of videos
- Batch Application Toolkit – How To series of videos (Studio 5000 Software)

Follow These Steps

Complete these steps to implement a controller by using the Batch Application Toolkit.



Unit Index

For each unit in your application, identify all of the phases associated with the unit and assign an index number to each. These index values are used in the controller as bit references to roll up the phase status to the unit level. The Indexes for the Batch Application Toolkit example are listed in [Table 6](#).

Table 6 - Unit Index

| Unit | | Mix-T100 | Premix-T300 | Slurry-T400 |
|------|-------|----------------|--------------|--------------|
| | Index | | | |
| | 0 | Init | Init | Init |
| | 1 | Prompt | Prompt | Prompt |
| | 2 | Timing | Timing | Timing |
| | 3 | Add Mat-X | Add Mat-X | Add Mat-X |
| | 4 | Add Mat-Y | Add Hand | Add Hand |
| | 5 | Add Hand | Agitate | Agitate |
| | 6 | Add Premix | XFR to Mix | XFR to Mix |
| | 7 | Add Slurry | Unit Message | Unit Message |
| | 8 | Adjust | Rinse | Rinse |
| | 9 | Agitate | | |
| | 10 | Circulate | | |
| | 11 | XFR to Storage | | |
| | 12 | Unit Message | | |

Tasks

1. For Batch Task, create a periodic task for the batch related programs/routines (refer to [Chapter 3](#)).
2. For Phase Tasks, create an event task for each unit in your process cell (refer to [Chapter 3](#)).

Programs

Add the following programs to the Batch Task:

- Units – This program holds one unit routine for each of the units in your process cell.
- Phases – This program triggers all of the event tasks for phases.
- Logixusers – The program holds a Logixuser routine for each phase in your system.

Unit

In the Batch Task, Units Program, add one routine for each of the units in your process cell.

Unit Routine

Configure a unit routine for each unit in your application. To complete this task, refer to the following videos:

[Development – Unit Routine](#)

[How To – Import a Unit Routine](#)

Equipment Phases

In the Phase task for your unit, create an instance of each phase required for the unit.

Create Phase Instance

To complete this task, refer to the following videos:

[Development – Phase Design](#)

[Development – Equipment Phase Organization and Scheduling](#)

[How To – Import an Equipment Phase](#)

Modify a_Devices (Development a_Devices Routine video)

To complete this task, refer to the following video:

[Development – a_Devices Routine](#)

Modify b_Perm_Intlk (Development b_Perm_Intlk Routine)

To complete this task, refer to the following video:

[Development – b_Perm_Intlk Routine](#)

Modify c_HMI_Interface

To complete this task, refer to the following video:

[Development – c_HMI_Interface Routine](#)

Scheduling

Schedule the phases for each unit in a consistent order. The Batch Application Toolkit follows this order.

1. Standard phases (Init, Prompt, Timing)
2. Material additions (automatic, hand)
3. Process actions (Agitate, Circulate)

4. Transfer Out
5. Miscellaneous (Adjust)
6. Unit Message

LogixUser Routine

Configure a LogixUser routine for each phase in your application. To complete this task, refer to the following videos:

[Development – LogixUser Routine](#)

[How To – Import a LogixUser Routine](#)

Notes:

HMI Implementation

In this chapter, you learn how to implement the HMI components from the toolkit in your application.

Before You Begin

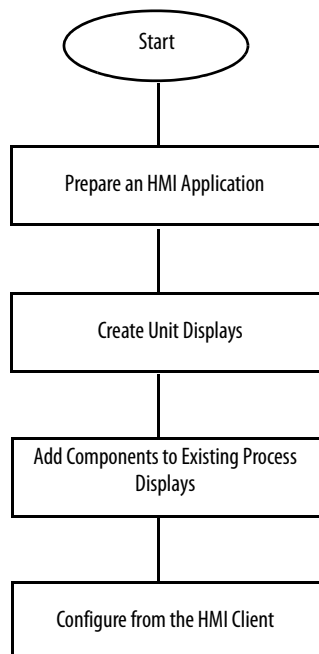
- Review [Chapter 1](#) through [Chapter 5](#).

What You Need

- Batch Application Toolkit - Development series of videos
- Batch Application Toolkit - How To series of videos (FactoryTalk View Studio Software)

Follow These Steps

Complete these steps to learn how to use the Batch Application Toolkit in an HMI implementation.



Prepare an HMI Application

To complete this task, refer to the following video:

[How To – Import HMI Components](#)

Create Unit Displays

To complete this task, refer to the following videos:

[Development – HMI Displays](#)

[Development – HMI Global Objects](#)

For each unit in your application, the following displays are required:

Table 7 - Unit Displays

| Display | Display Name Format ⁽¹⁾ | Notes |
|------------------------------|------------------------------------|--|
| Unit Detail Display | \${#103}_Unit_Detail | ex. T100_Unit_Detail |
| Unit Summary Display | \${#103}_Unit_Summary | |
| Prompt Summary Display | \${#103}_Prompt_Summary | |
| Prompt Configuration Display | \${#103}_Prompt_Config | |
| Batch Detail Display | \${#103}_Batch_Detail | Optional: Only needed when using FactoryTalk Batch |

(1) #103 is the Unit Name, where Unit Name is the controller scoped tagname for the unit.

Add Components to Existing Process Displays

To complete this task, refer to the following videos:

[Development – HMI Displays](#)

[Development – HMI Global Objects](#)

Unit Overview Object

Add Unit Overview faceplate objects to your displays where desired. We recommend adding the objects to the process cell overview display and unit detail displays.

Phase Icon

Add Phase Display "Widget" to process displays for each phase, as desired.

Configure from the HMI Client

When the controller and HMI implementation is completed and your application is running, the following items must be configured from the HMI client:

- Unit Interlock Faceplate
- Unit Permissive Faceplate
- Phase Interlock Faceplate
- Phase Permissive Faceplate
- Prompts

To configure Interlocks and Permissives, display the Interlock or Permissive faceplate from the Unit Overview or Phase Faceplate, and then complete the following steps:

1. From the Engineering Tab, Sheet 1, configure the title, label, and tag for your faceplate.
2. From the Engineering Tab, Sheet 2:
 - a. Configure the text for each interlock or permissive, as applicable.
 - b. Set "Ok Status" for each condition.
 - c. Check/Uncheck "Can Bypass," as applicable.
 - d. Check/Uncheck "Must Reset," as applicable.

To configure prompts, refer to the [Development – Prompt Configuration](#) video.

Additional Resources

For additional information on how to configure the interlock, permissive, and prompt objects, refer to the Rockwell Automation Library of Process Object Reference Manuals:

- Interlocks with First Out and Bypass (P_Intlk), publication [SYSLIB-RM004](#)
- Permissives with Bypass (P_Perm), publication [SYSLIB-RM007](#)
- Operator Prompt (P_Prompt), publication [SYSLIB-RM046](#)

Notes:

Index Numbering

Standard Phase Step Index Numbering

The majority of the phases in the Batch Application Toolkit follow the standard phase step index numbering as shown in [Table 8](#). However, there are minor differences with some of the special case phases, including Add_Hand, Init, Prompt, and Adjust.

Table 8 - Standard Phase Step Index Numbering

| Index | Significance | Notes |
|---------------|-----------------------------------|------------------|
| 0-2999 | Running State Step Indexes | |
| 0 | Phase Initiation | |
| Alarm | Process if phase in alarm | |
| 20 | Interlock, share resource | |
| 30 | Set up message to sources | XFI only |
| 50 | Determine action based on mode | |
| 60 | Operator mode post prompt | |
| 65 | Wait for prompt response | |
| 70 | Store prompt responses | |
| 75 | Validate source entry | XFI only |
| 100 | Establish SP based on mode | |
| 110 | Wait for source | XFI only |
| 115 | Destination starting | XFI only |
| 200 | Device ownership | |
| 210 | Device lock | |
| 220 | Tare Check | Totalizers only |
| 230 | Tare | |
| 240 | Tared | |
| 300 | Phase Specific Activity | |
| 900 | Wait for operating condition | (Agit = Level) |
| 1000 | Move setpoints | |
| 1010 | Start totalizer | |
| 1030 | Start totalizer flow | |
| 1040 | Path open | |
| 1050 | Flow start | |
| 1100 | Source Ready | XFO Only |
| 1200 | Synchronize evaluation | Up to two phases |

Table 8 - Standard Phase Step Index Numbering

| Index | Significance | Notes |
|------------------|--|-------|
| 1205 | Auto sync delay | |
| 1210 | Auto sync calculation | |
| 1215 | Wait for synchronized phase(s) | |
| 1500 | Adding/Agitating/Circulating, etc. . . | |
| 1600 | Receive new agitation speed setpoint/ Transfer of Control | |
| 1605 | Process new setpoint | |
| 2000 | Stop flow | |
| 2010 | Check Tolerance | |
| 2020 | Path close | |
| 2030 | Stop totalizer | |
| 2040 | Unlock devices | |
| 2700 | Alarm Handling – Shutdown flow | |
| 2705 | Alarm Handling – Shutdown flow | |
| 2710 | Alarm Handling – Shutdown path | |
| 2720 | Alarm Handling – Stop Totalizing | |
| 2730 | Alarm Handling – Delivery out of tolerance | |
| 2800 | Alarm Reset | |
| 2810 | Post Prompt | |
| 2815 | Wait for prompt response | |
| 2820 | Wait for Source | |
| 2830 | Post Prompt – Hi Tolerance | |
| 2835 | Prompt Response – Hi Tolerance | |
| 2840 | Post Prompt – Lo Tolerance | |
| 2845 | Prompt Response – Lo Tolerance | |
| 2850 | Lo tolerance – Continue with Bump | |
| 2999 | Phase Running State Complete | |
| 3000-3999 | Holding State Step Indexes | |
| 3000 | Clear Prompt | |
| 3010 | Stop Flow | |
| 3020 | Close Path | |
| 3030 | Stop the Totalizer Flow | |
| 3040 | Process Alarm | |
| 3050 | Unlock Devices | |
| 3700 | Take Alarm Action | |
| 3800 | Alarm Response | |
| 3999 | Holding Phase State Complete | |
| 4000-4999 | Restarting State Step Indexes | |
| 4999 | Restarting Phase State Complete | |

Table 8 - Standard Phase Step Index Numbering

| Index | Significance | Notes |
|------------------|------------------------------------|--------------|
| 5000-5999 | Stopping State Step Indexes | |
| 5000 | Clear Prompt | |
| 5010 | Stop Flow | |
| 5020 | Close Path | |
| 5030 | Stop the Totalizer Flow | |
| 5040 | Stop the Totalizer | |
| 5050 | Process Alarm | |
| 5060 | Unlock devices | |
| 5700 | Take Alarm Action | |
| 5800 | Alarm Response | |
| 5999 | Stopping Phase State Complete | |
| 6000-6999 | Aborting State Step Indexes | |
| 6000 | Clear Prompt | |
| 6010 | Stop Flow | |
| 6020 | Close Path | |
| 6030 | Stop the Totalizer Flow | |
| 6040 | Stop the Totalizer | |
| 6050 | Unlock devices | |
| 6999 | Aborting Phase State Complete | |

Notes:

Video Listing

The following videos are available on Vidyard to help you set up and use the Batch Application Toolkit.

Introduction

[Introduction to Batch Application Toolkit](#)

Operational Overview Series

[Operational Overview – Process Cell Example](#)
[Operational Overview – Object, Phase, and Unit Faceplates](#)
[Operational Overview – Unit Detail and Summary Display](#)
[Operational Overview – Batch Detail Display](#)
[Operational Overview – Phase Ownership](#)
[Operational Overview – Device Ownership and Interlocks](#)
[Operational Overview – Phase Operation in Operator Mode](#)
[Operational Overview – Device Acquisition and Locking](#)
[Operational Overview – Operator Interface for Managing Batches](#)
[Operational Overview – Material Addition Phase](#)
[Operational Overview – Add Hand Phase](#)
[Operational Overview – Adjust Phase](#)
[Operational Overview – Logix Batch and Sequence Manager](#)

Development Series

[Development – Phase Design](#)
[Development – a_Devices Routine](#)
[Development – b_Perm_Intlk Routine](#)
[Development – c_HMI_Interface Routine](#)
[Development – Equipment Phase Organization and Scheduling](#)
[Development – Unit Routine](#)
[Development – LogixUser Routine](#)
[Development – LogixUsers Interface](#)
[Development – Phase Synchronization](#)

[Development – Prompt Configuration](#)
[Development – HMI Global Objects](#)
[Development – HMI Displays](#)
[Development – HMI Security](#)
[Development – Logix Batch and Sequence Manager Interface](#)

Phase Feature Series

[Phase Features – Timing Phase Synchronization](#)
[Phase Features – Transfer Phases – Coordinated 1 to 1](#)
[Phase Features – Transfer Phases – Coordinated 1 to Many](#)
[Phase Features – Transfer Phases Quick Add](#)
[Phase Features – Shared Resources – Shared Phases](#)
[Phase Features – Shared Resources – Device Level Allocation and Arbitration](#)
[Phase Features – Shared Resources – Interlocked Phases](#)
[Phase Features – Handling Device Level Interlocks](#)
[Phase Features – Transfer of Control](#)
[Phase Features – Initiation Phase](#)
[Phase Features – Material Addition Tolerance Checks](#)

How To Series

[How To – Import a Unit Routine](#)
[How To – Import an Equipment Phase](#)
[How To – Import a LogixUser Routine](#)
[How To – Import HMI Components](#)
[How To – Import a Logix and Batch Sequence Manager Interface Routine](#)
[How To – Setup the Application Example](#)

Rockwell Automation Support

Rockwell Automation provides technical information on the Web to assist you in using its products.

At <http://www.rockwellautomation.com/support> you can find technical and application notes, sample code, and links to software service packs. You can also visit our Support Center at <https://rockwellautomation.custhelp.com/> for software updates, support chats and forums, technical information, FAQs, and to sign up for product notification updates.

In addition, we offer multiple support programs for installation, configuration, and troubleshooting. For more information, contact your local distributor or Rockwell Automation representative, or visit <http://www.rockwellautomation.com/services/online-phone>.

Installation Assistance

If you experience a problem within the first 24 hours of installation, review the information that is contained in this manual. You can contact Customer Support for initial help in getting your product up and running.

| | |
|---------------------------------|--|
| United States or Canada | 1.440.646.3434 |
| Outside United States or Canada | Use the Worldwide Locator at http://www.rockwellautomation.com/rockwellautomation/support/overview.page , or contact your local Rockwell Automation representative. |

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Rockwell Automation tests all of its products to help ensure that they are fully operational when shipped from the manufacturing facility. However, if your product is not functioning and needs to be returned, follow these procedures.

| | |
|-----------------------|---|
| United States | Contact your distributor. You must provide a Customer Support case number (call the phone number above to obtain one) to your distributor to complete the return process. |
| Outside United States | Please contact your local Rockwell Automation representative for the return procedure. |

Documentation Feedback

Your comments will help us serve your documentation needs better. If you have any suggestions on how to improve this document, complete this form, publication [RA-DU002](#), available at <http://www.rockwellautomation.com/literature/>.

Rockwell Automation maintains current product environmental information on its website at <http://www.rockwellautomation.com/rockwellautomation/about-us/sustainability-ethics/product-environmental-compliance.page>.

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