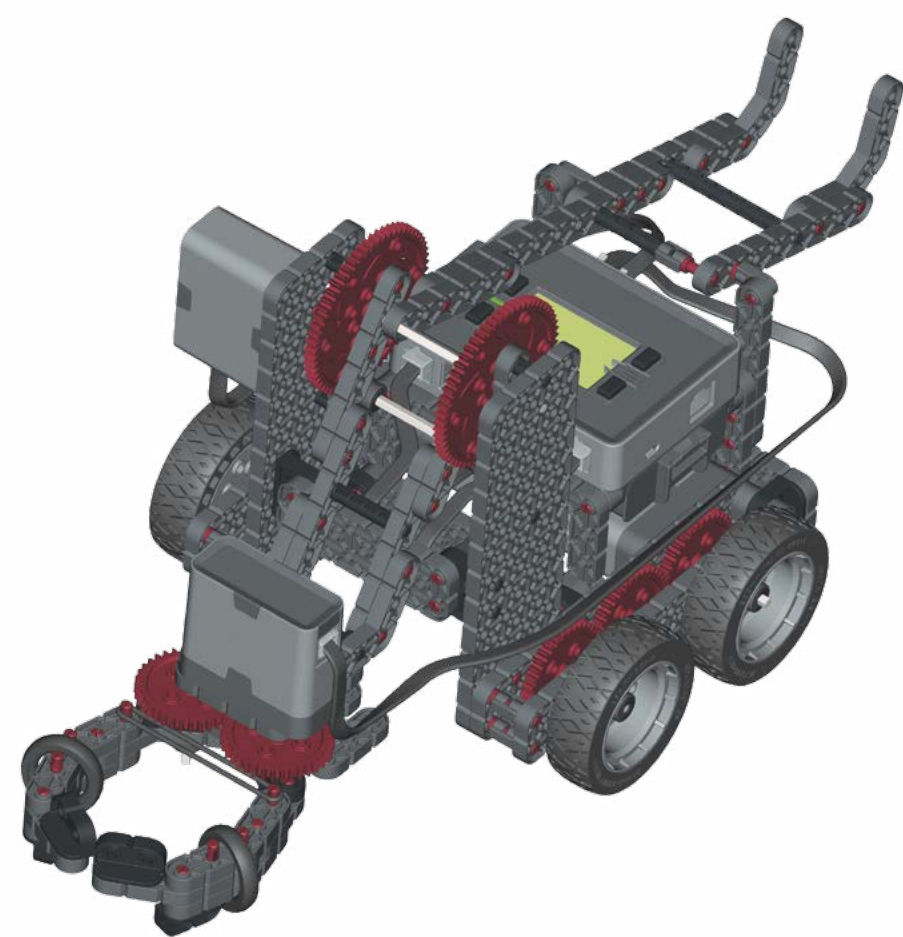
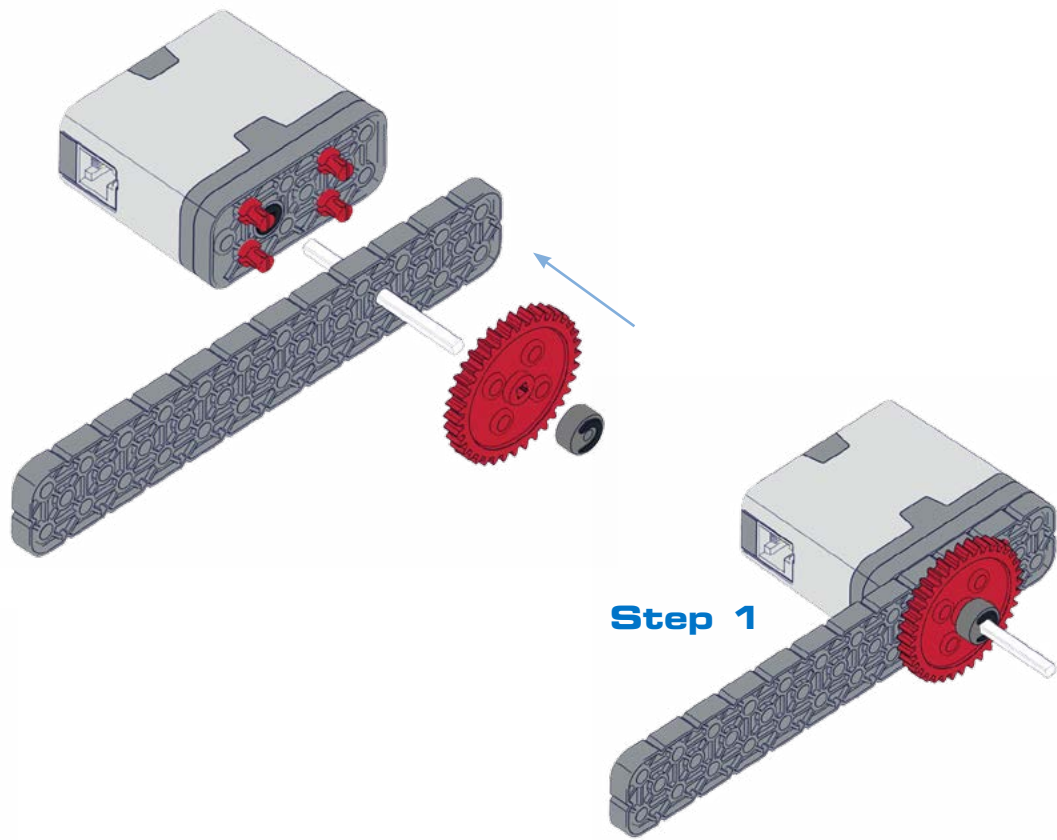
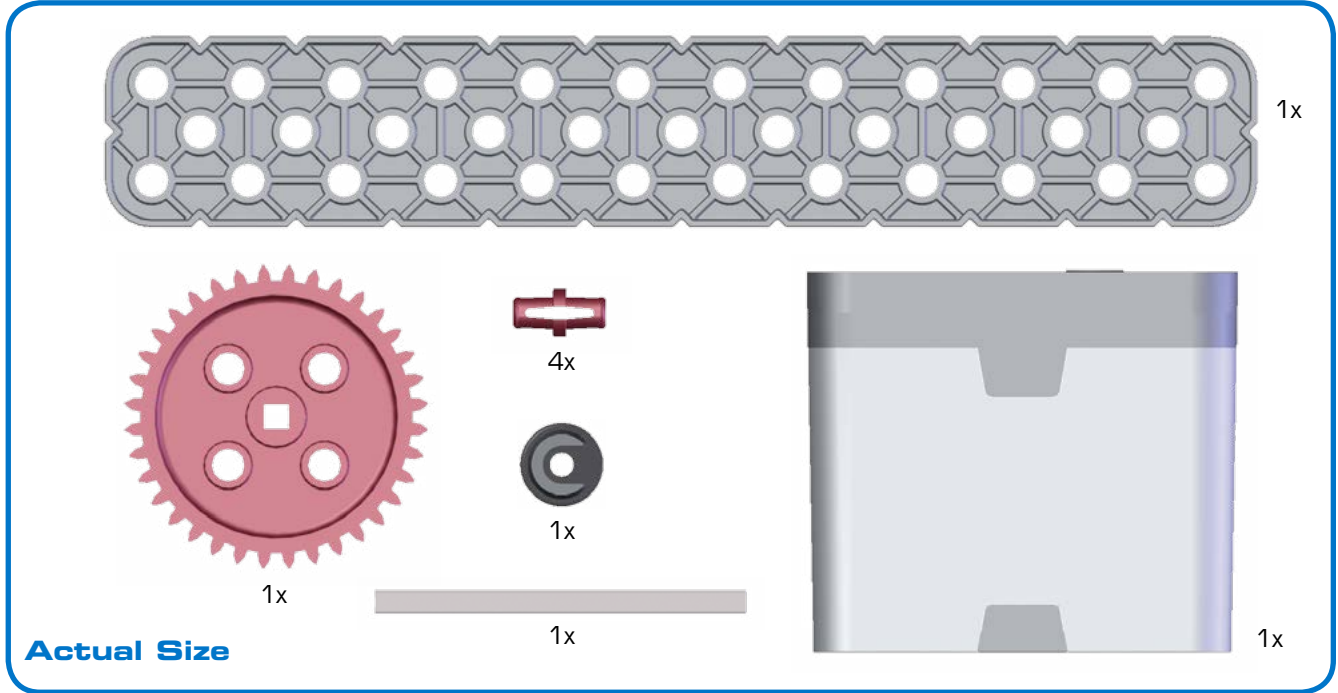


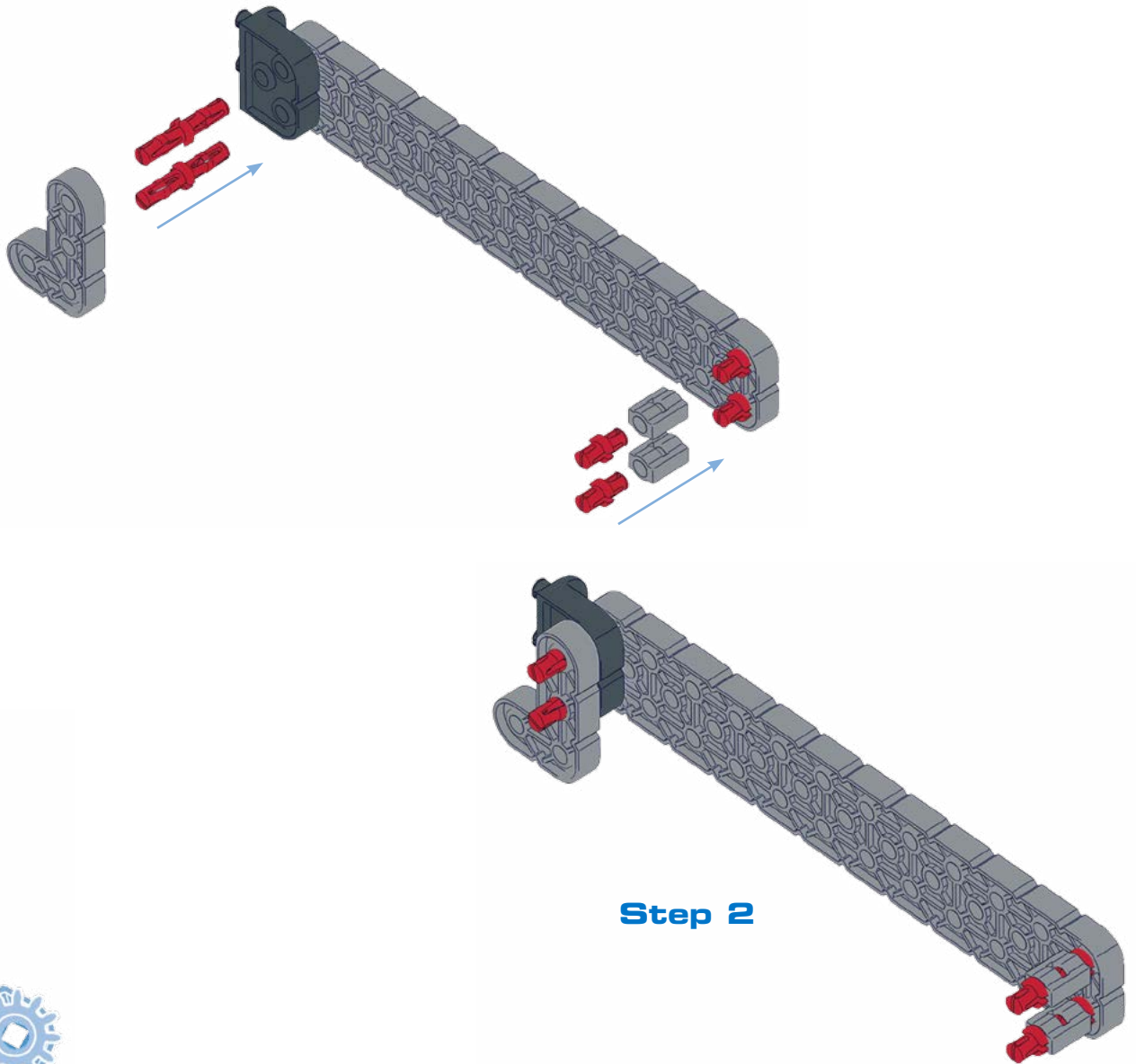
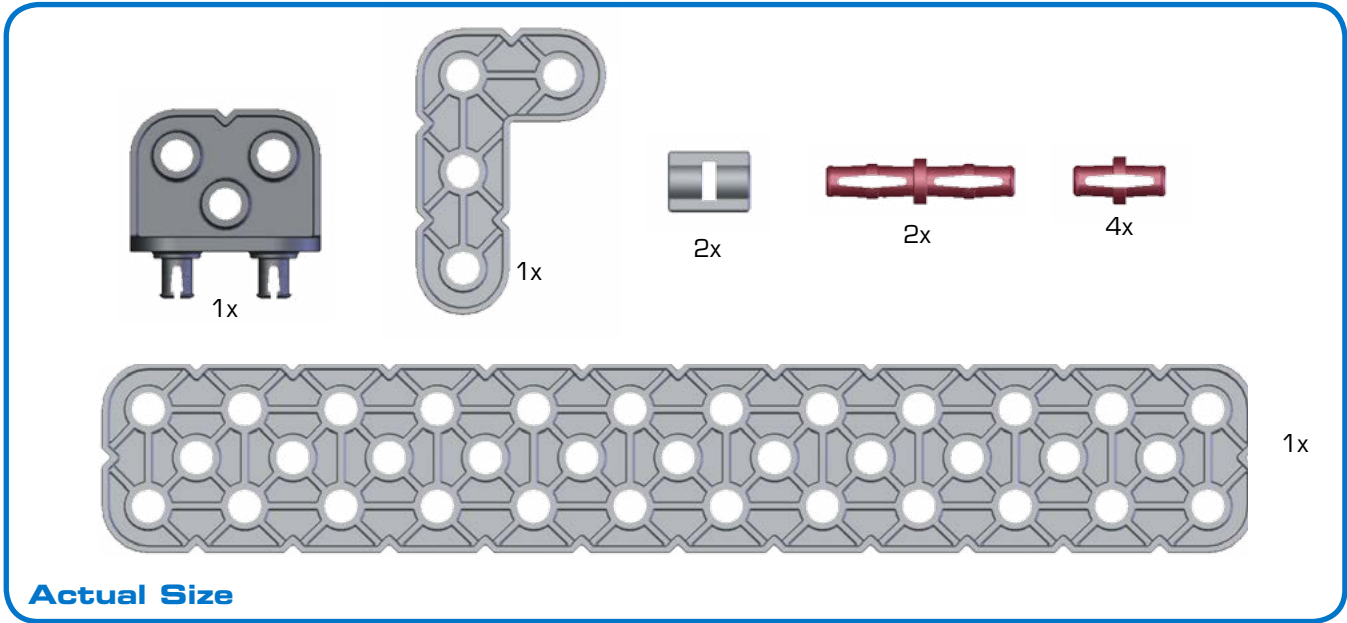


Clawbot Assembly Instructions

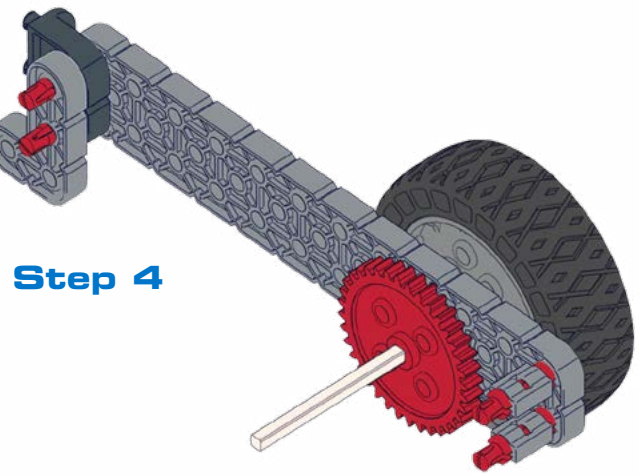
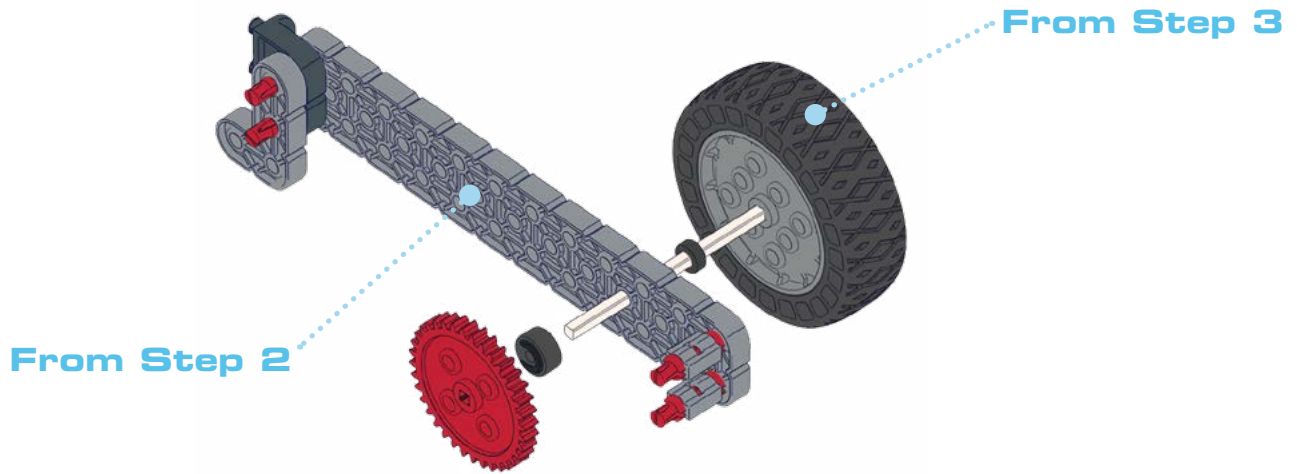
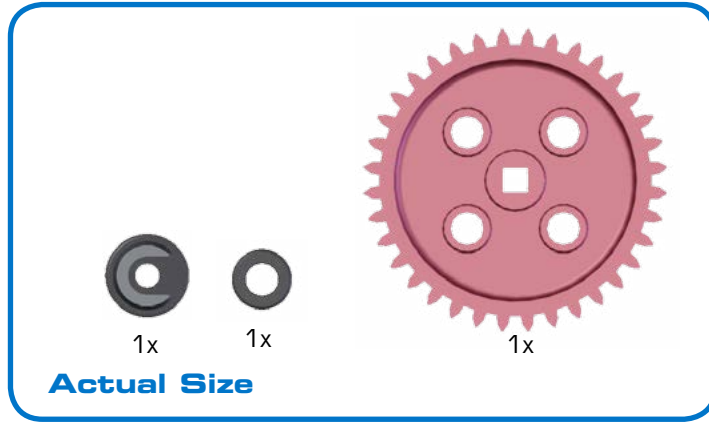


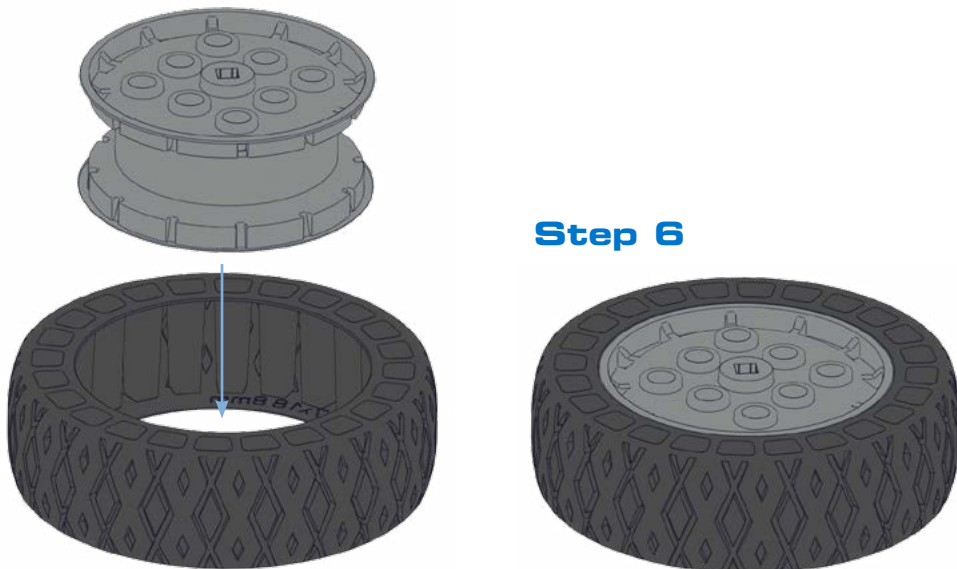
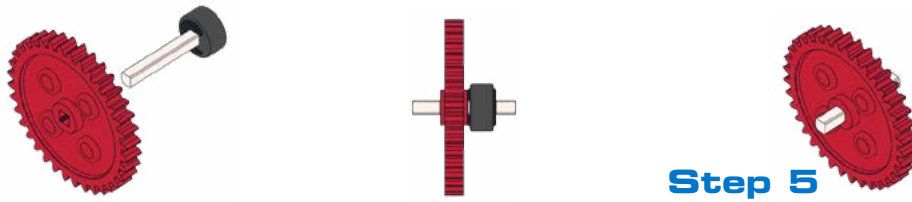
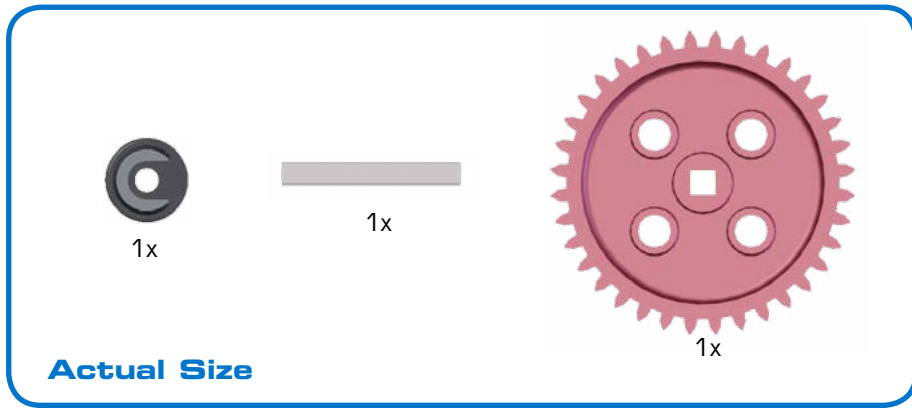
Part 1 Base

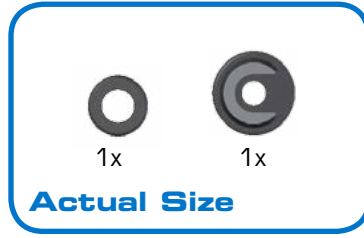










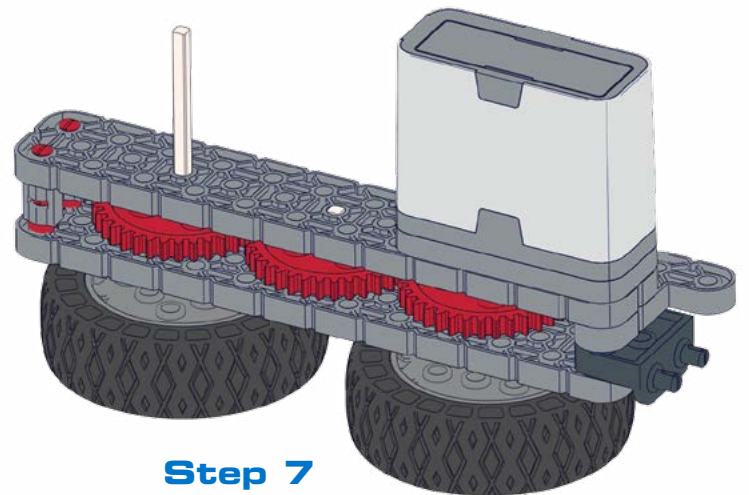
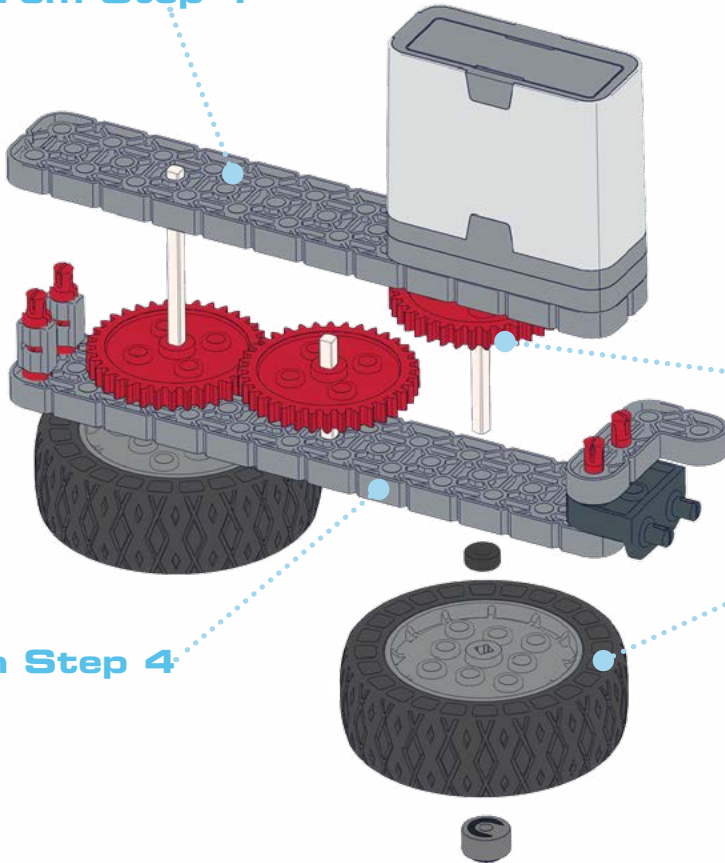


From Step 1

From Step 5

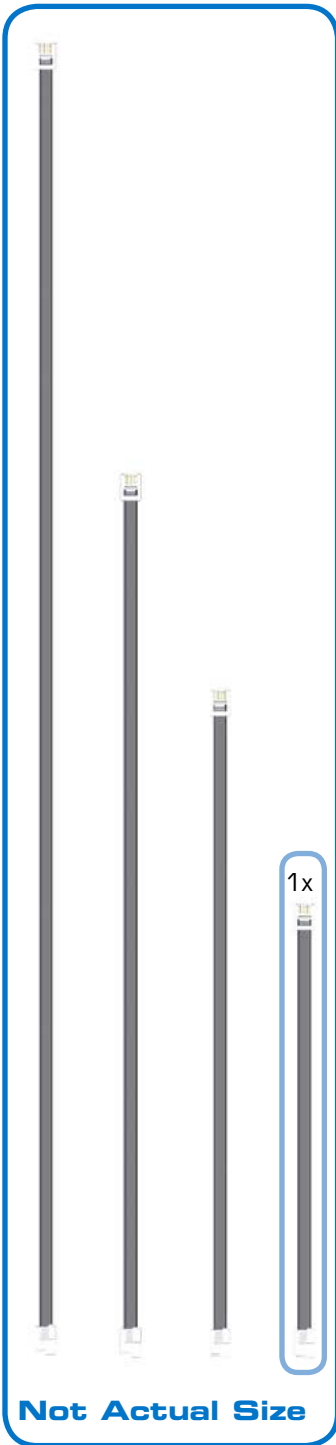
From Step 6

From Step 4

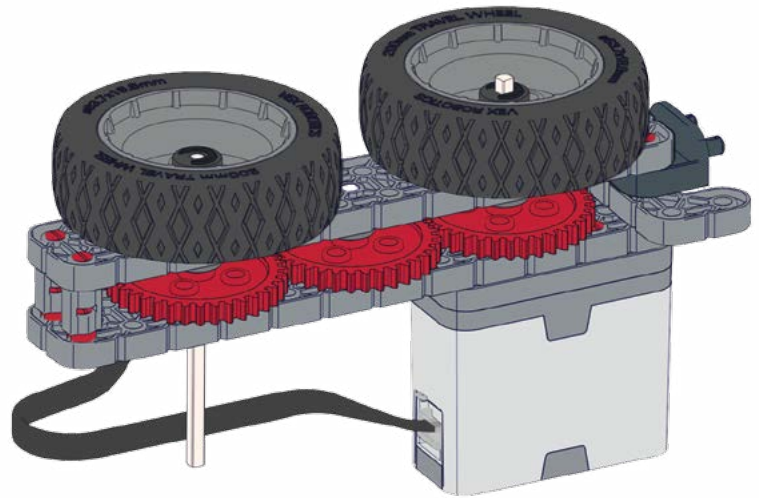
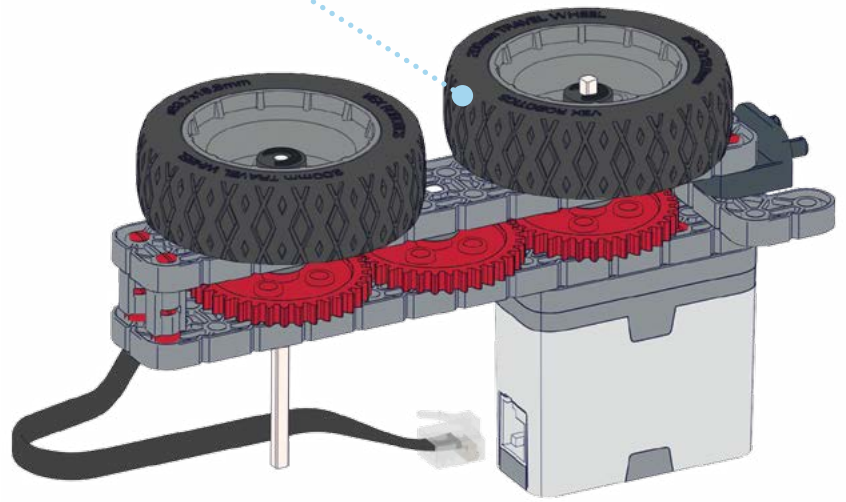


Step 7



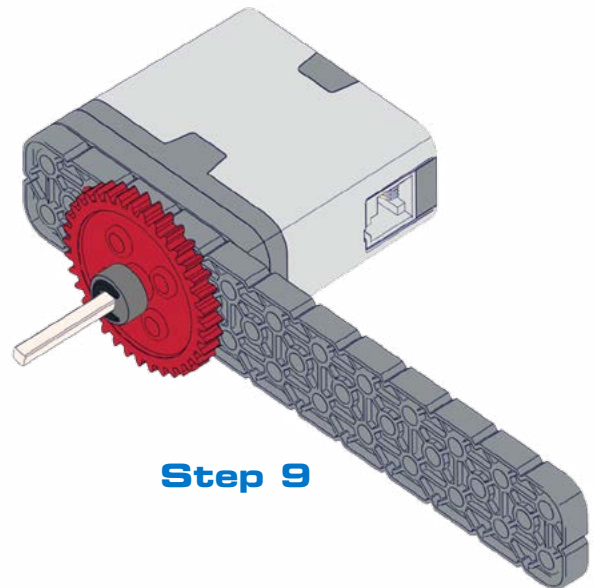
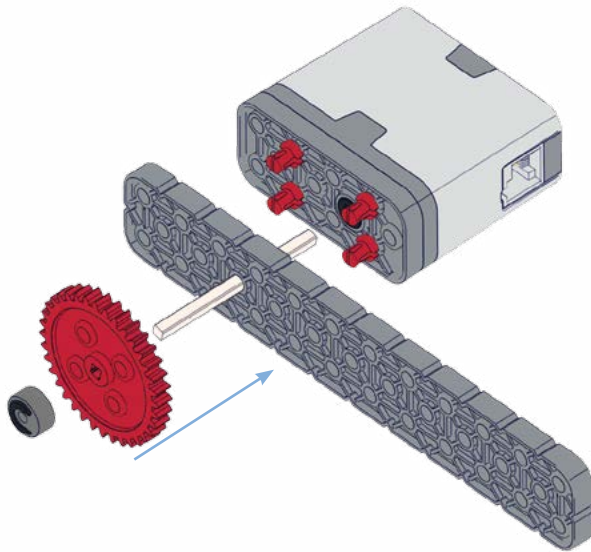
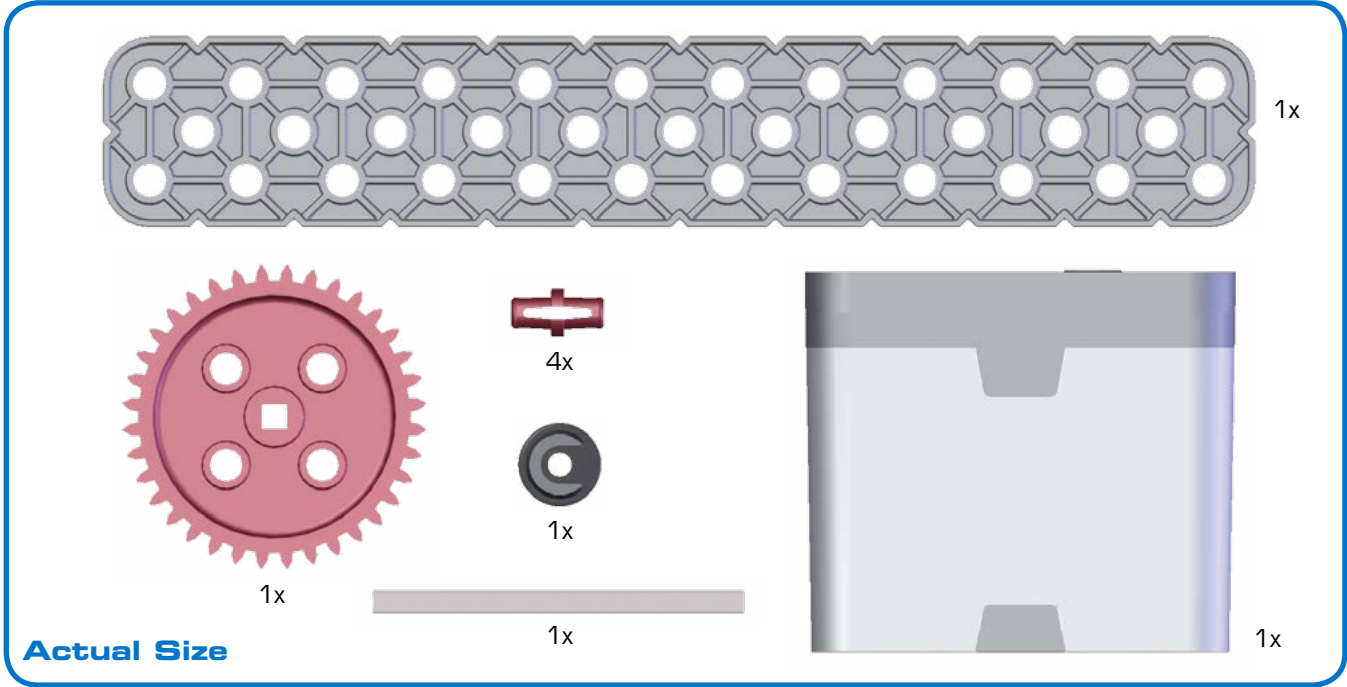


From Step 7

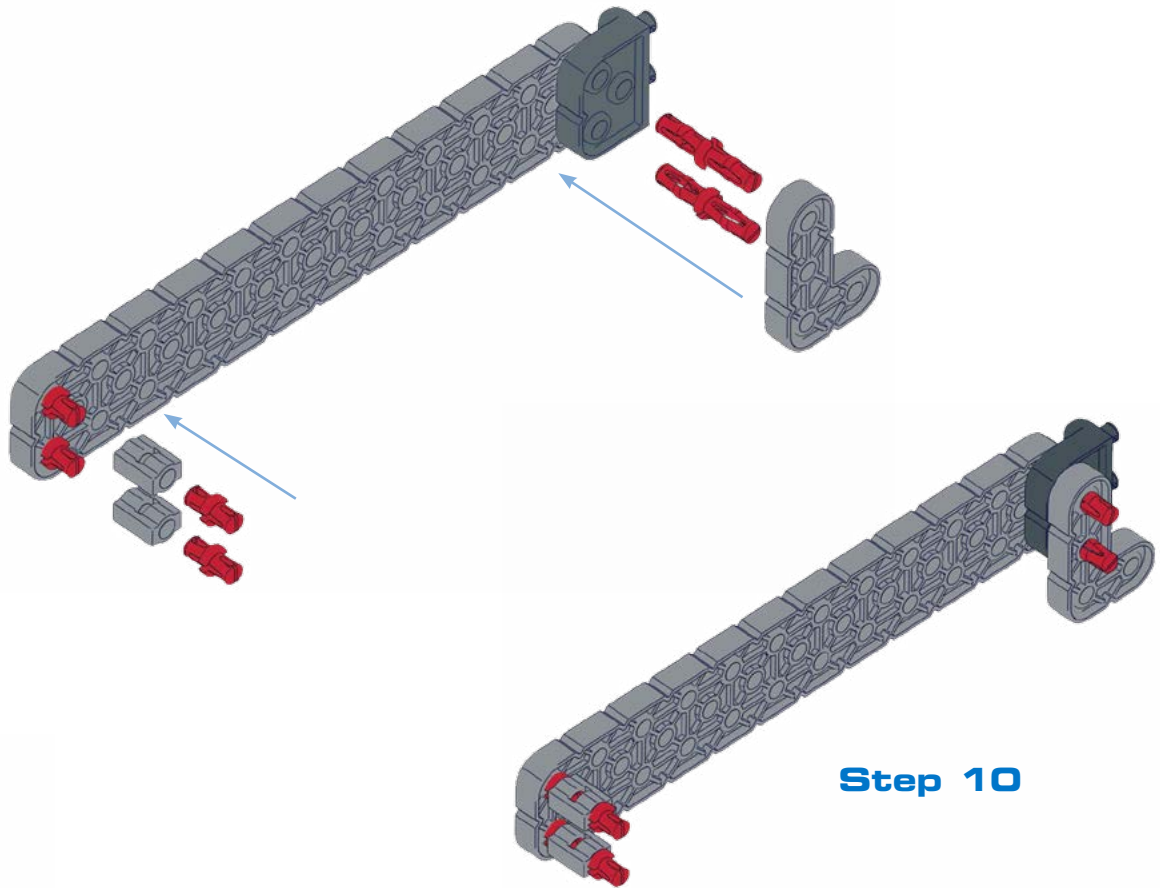
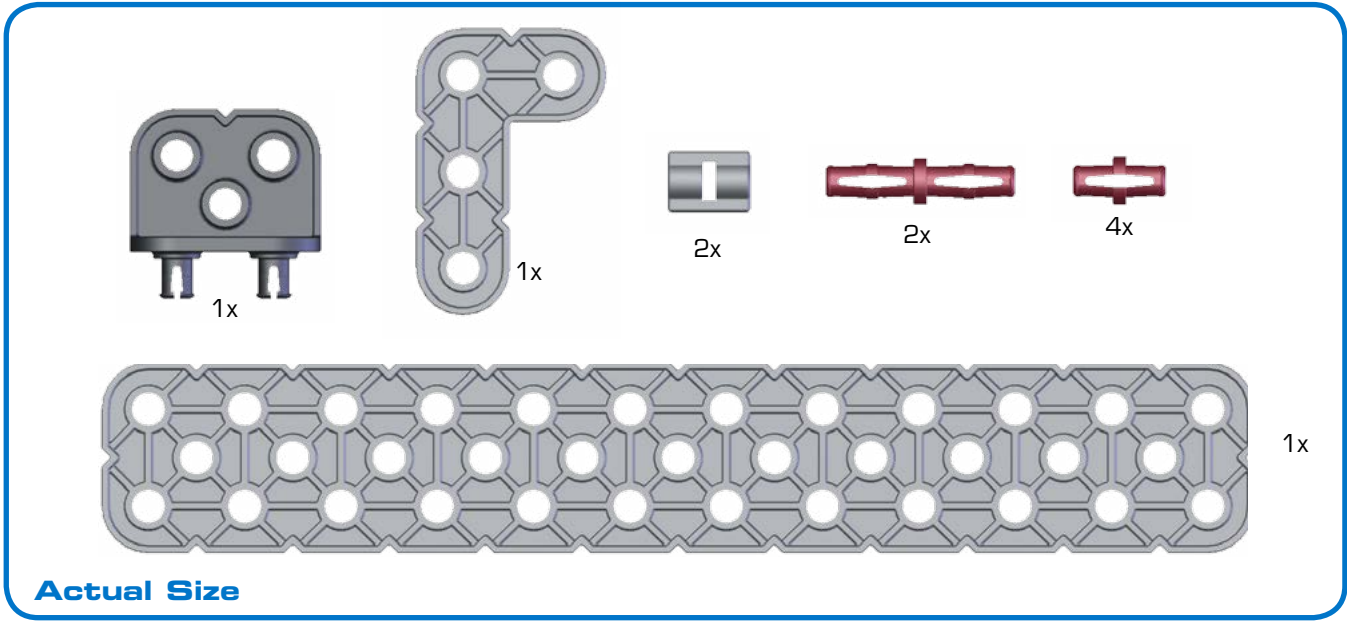


Step 8

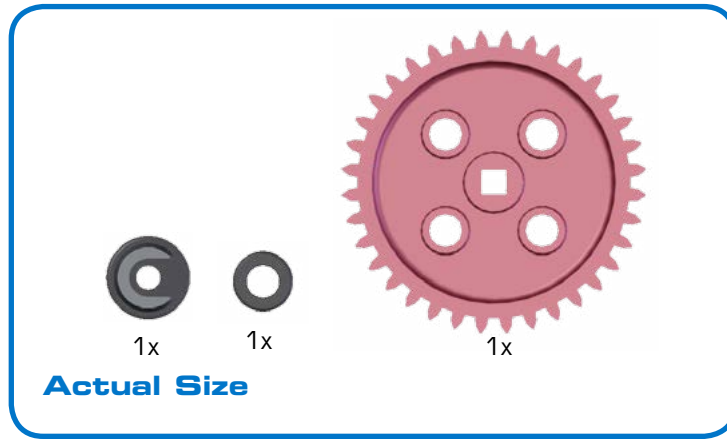




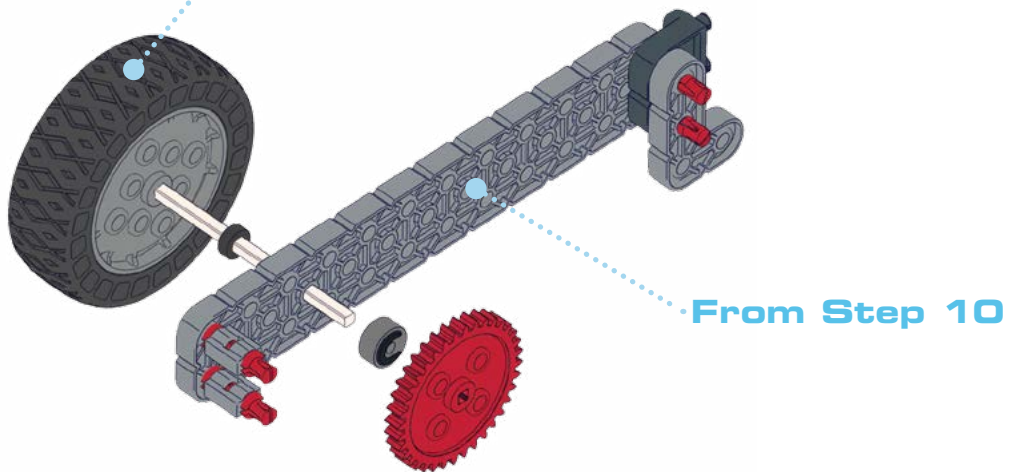
Step 9



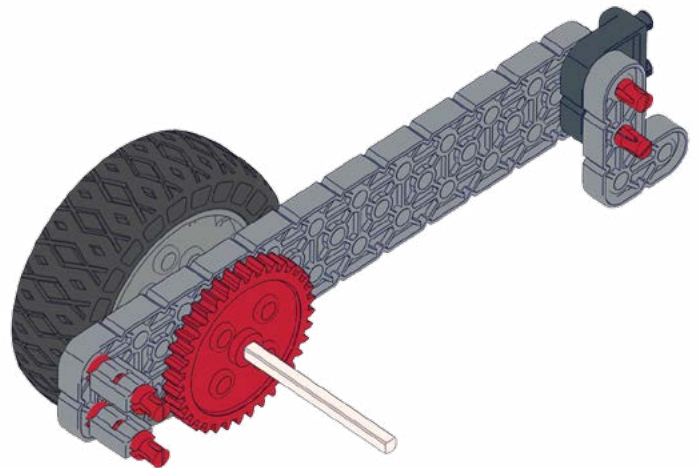


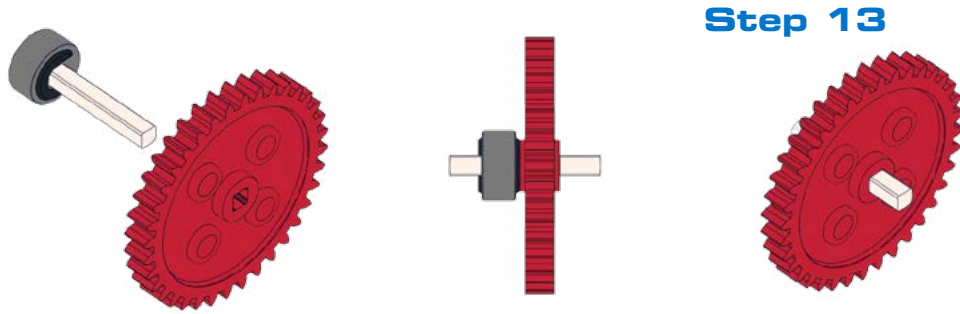
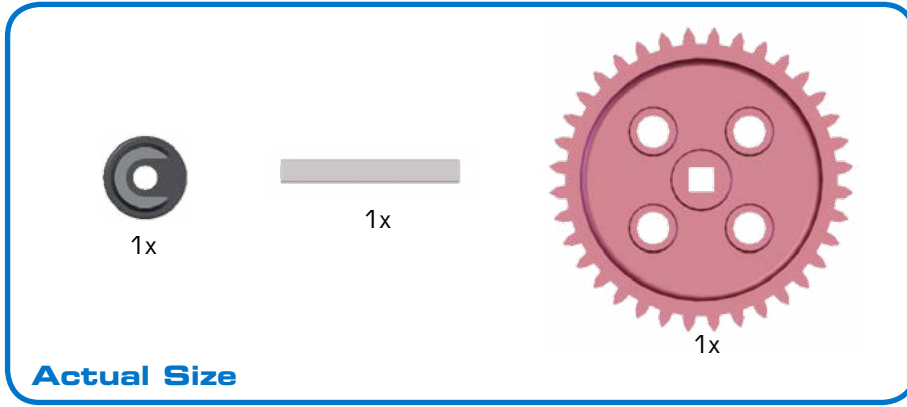


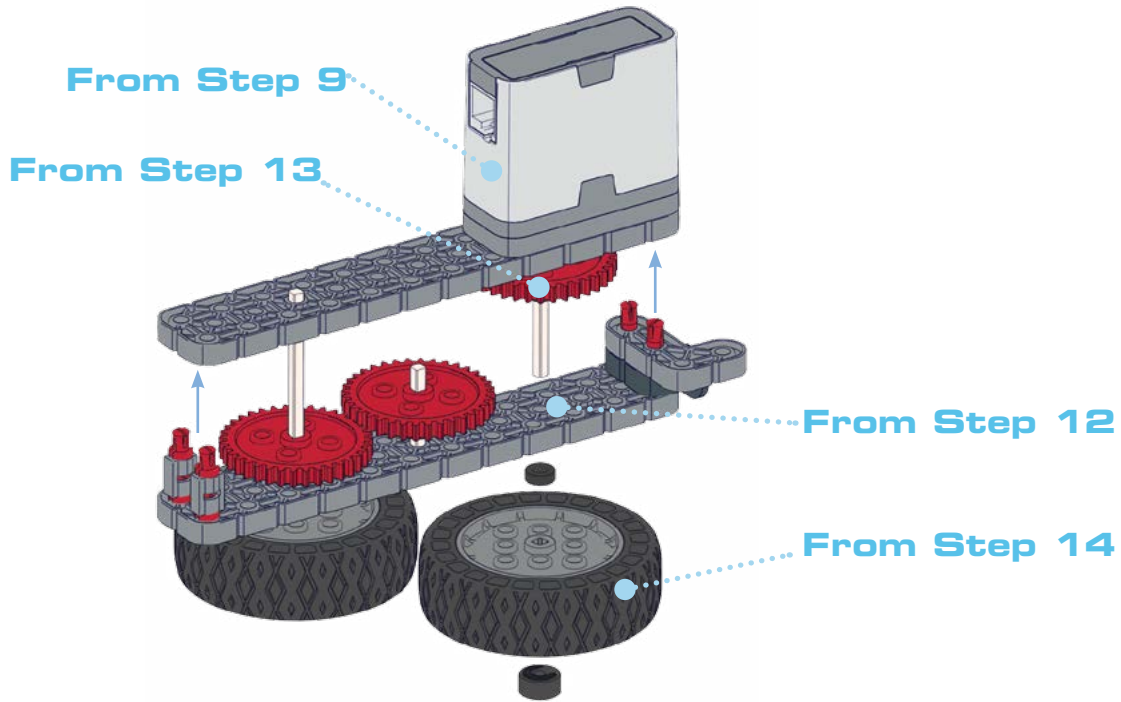
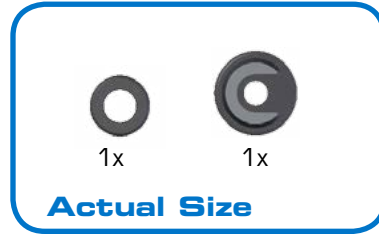
From Step 11



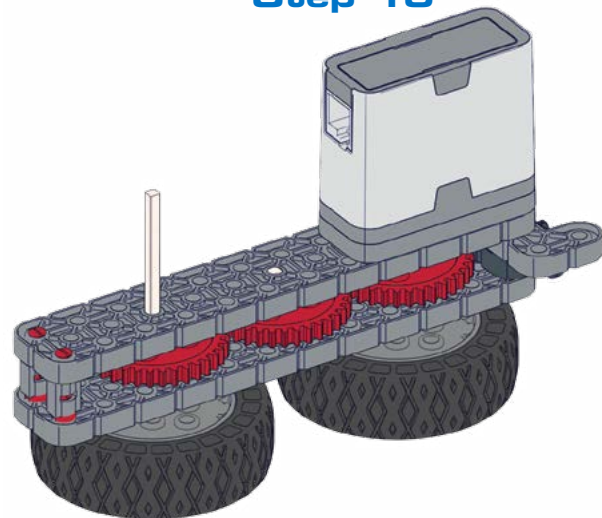
Step 12

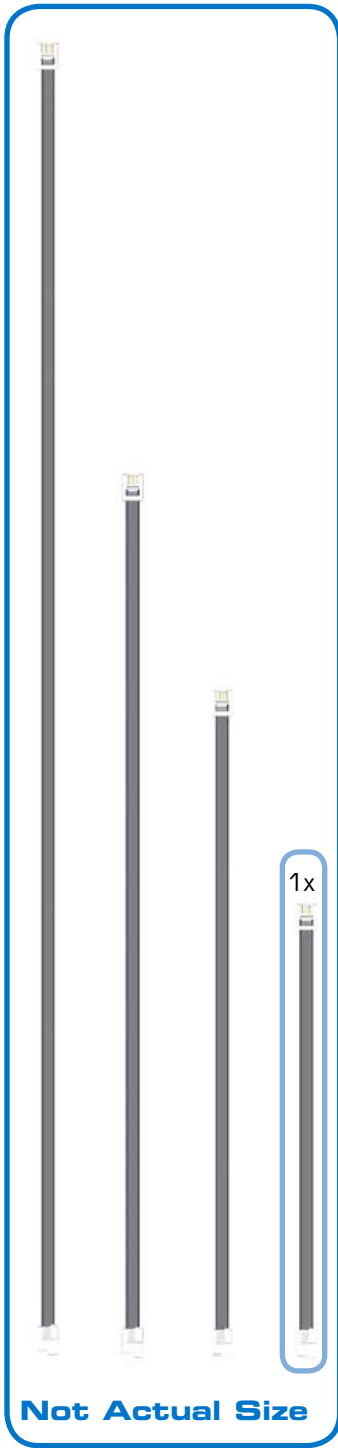




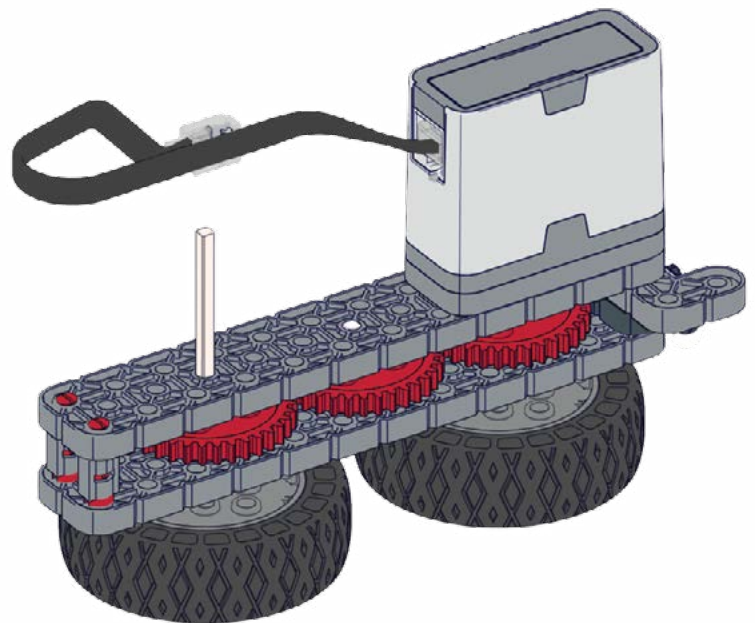
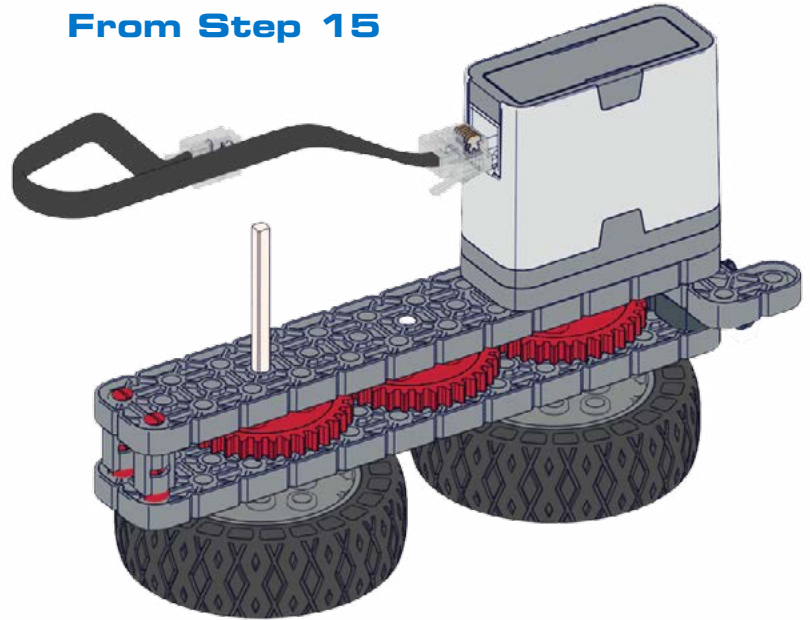


Step 15

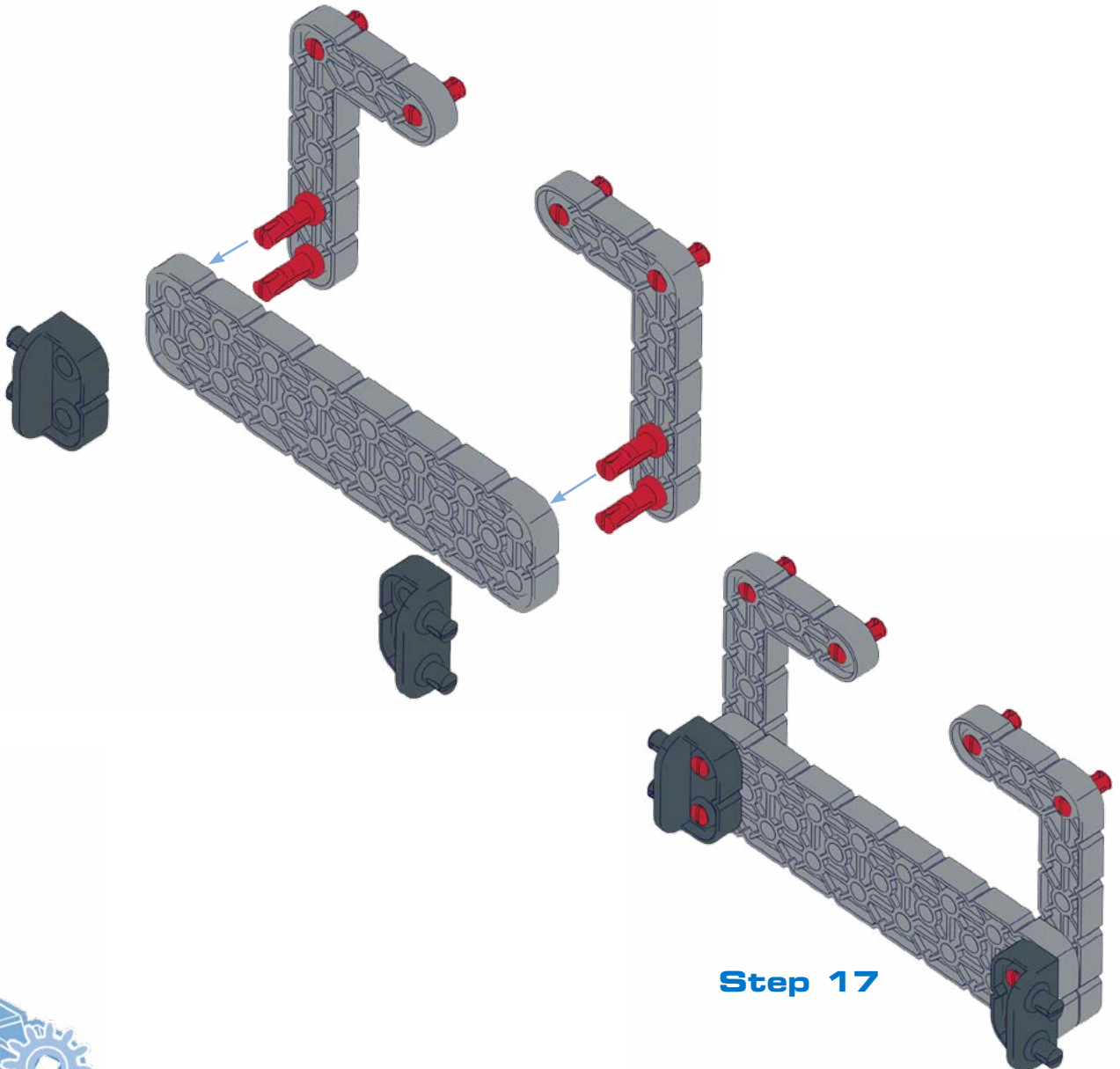
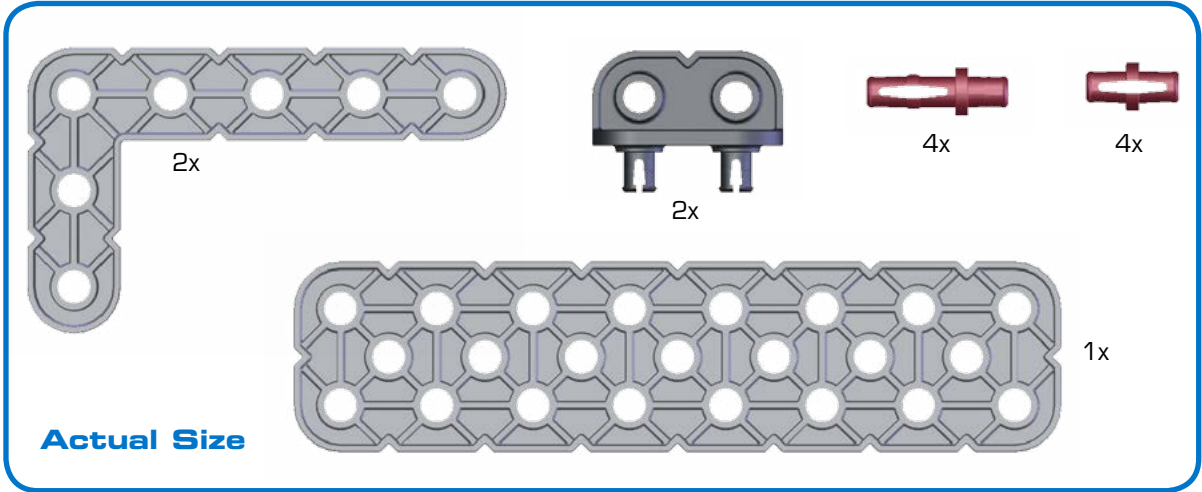


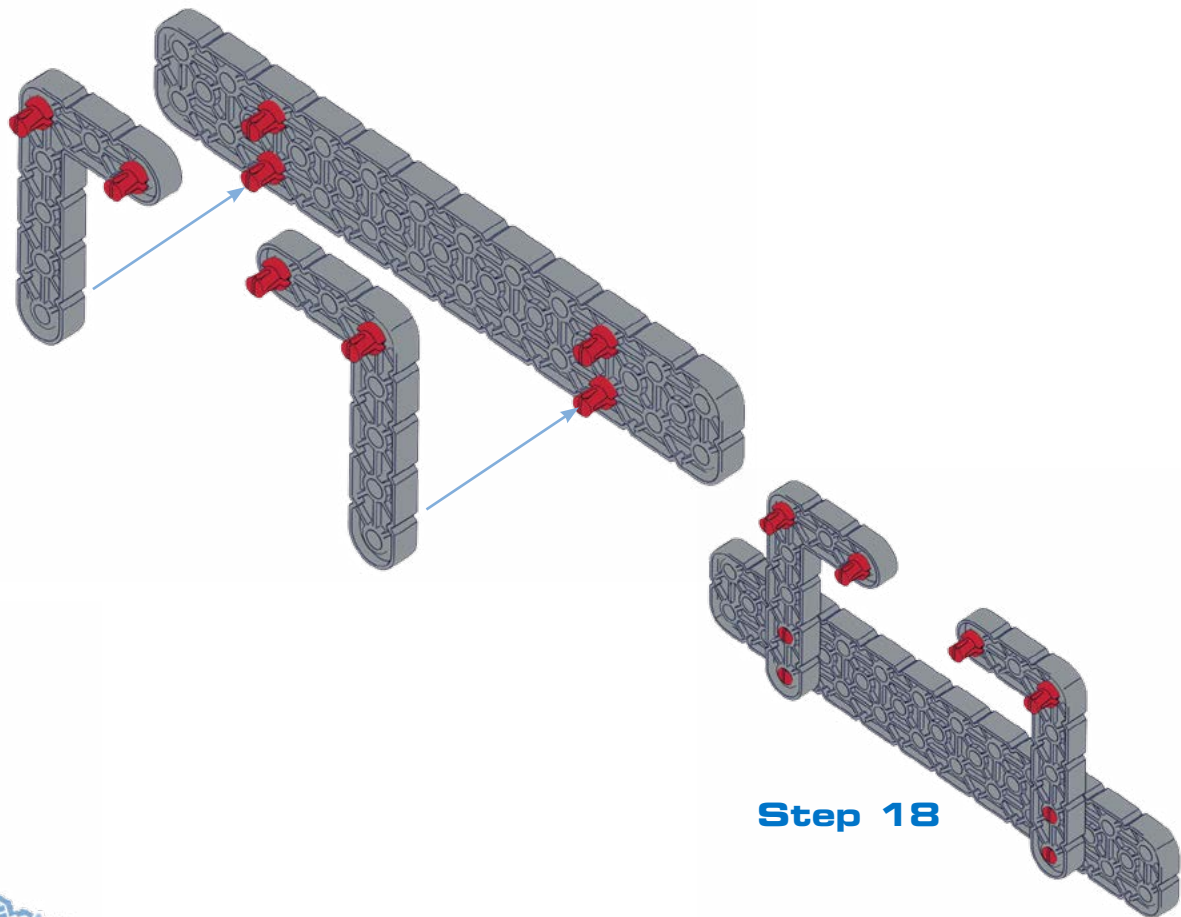
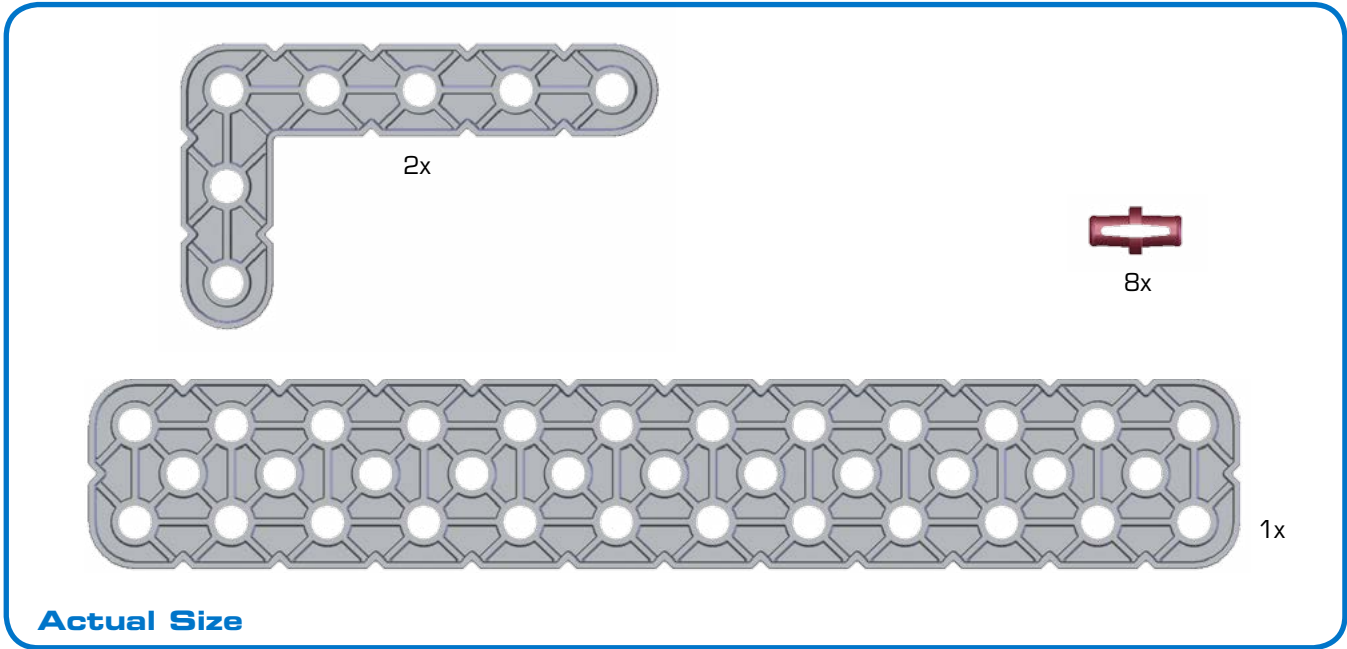


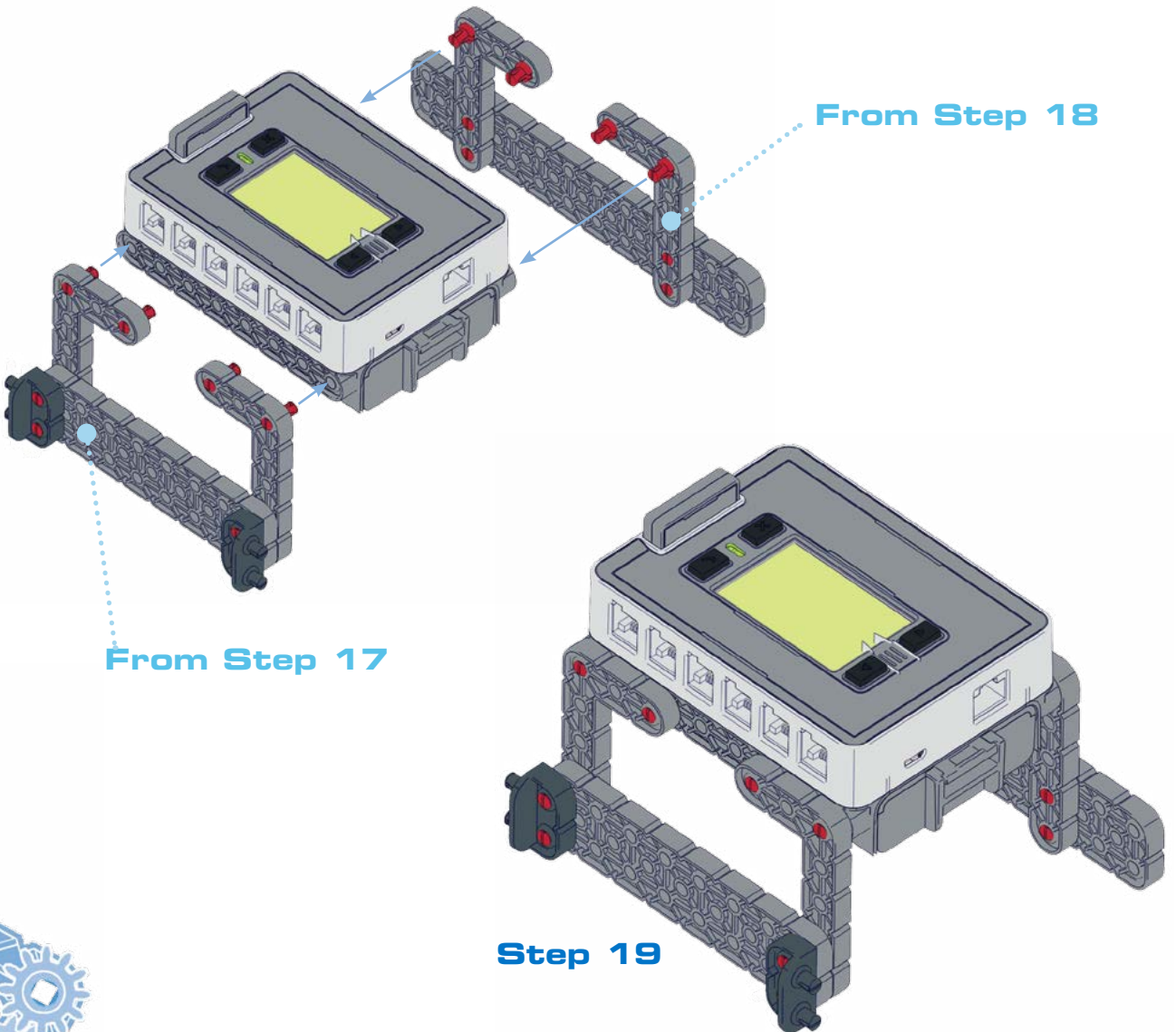
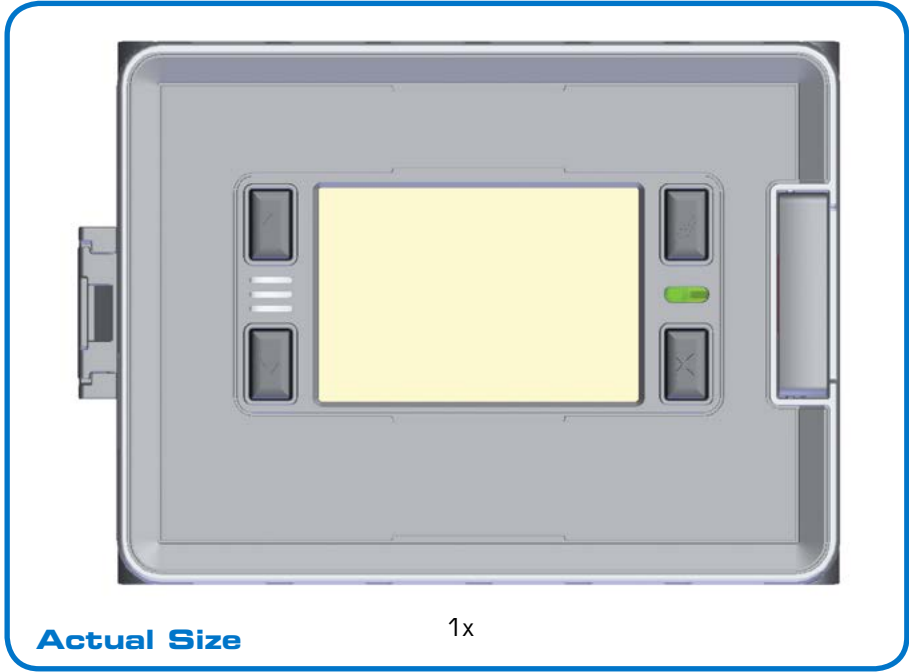
From Step 15

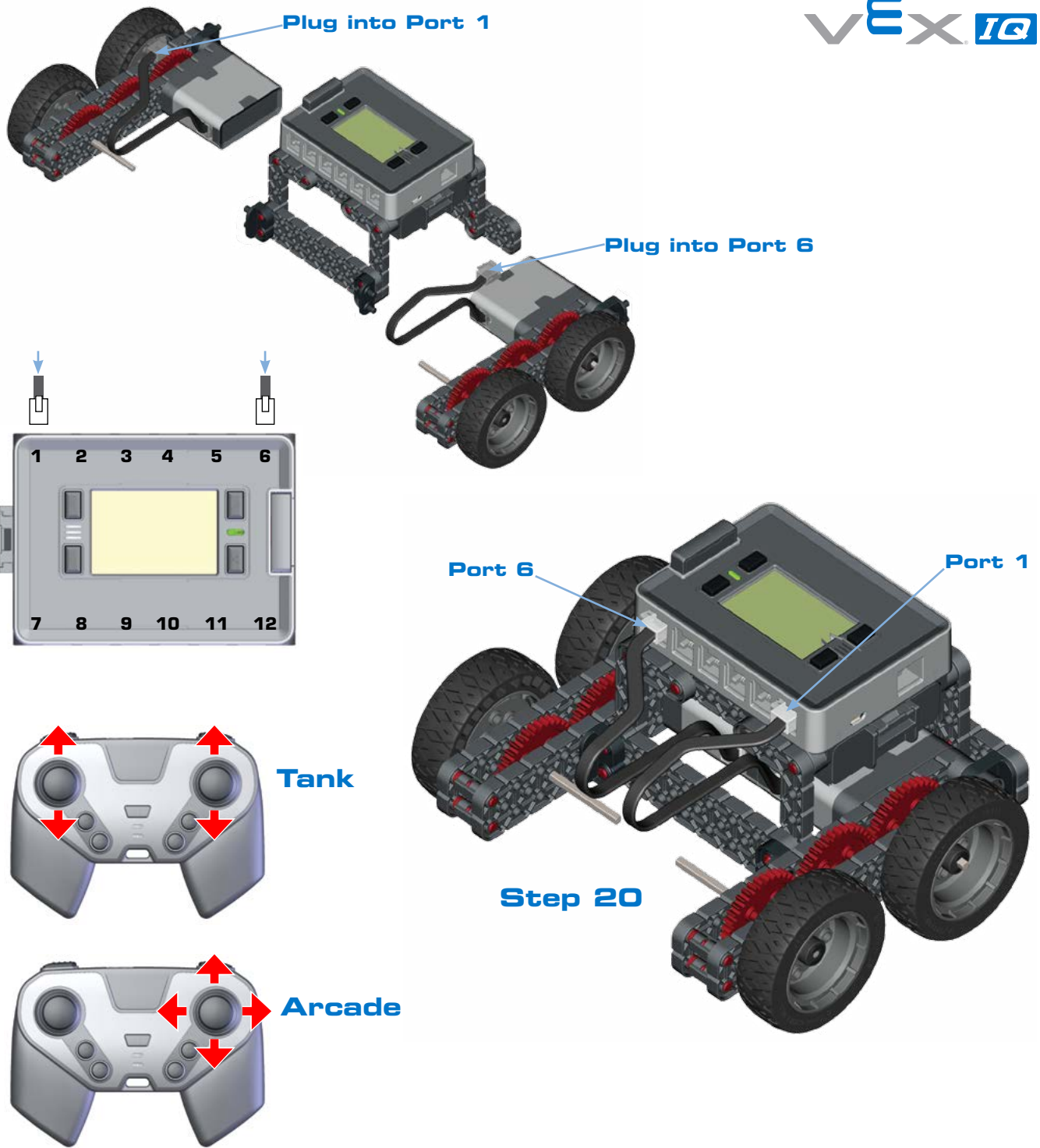


Step 16









**Robot Base is now Ready to Run!
Test it before continuing the Build.**

Part 2 Claw

1x [Grey L-shaped Technic part]

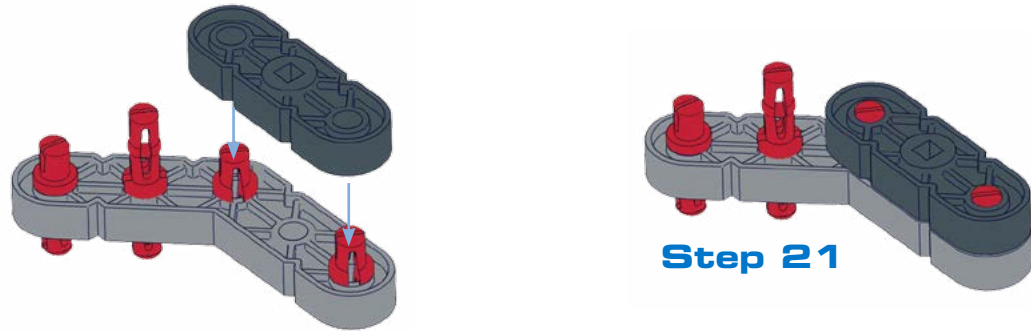
1x [Grey U-shaped Technic part]

2x [Red Technic Pin]

1x [Red Technic Pin]

1x [Red Technic Pin]

Actual Size



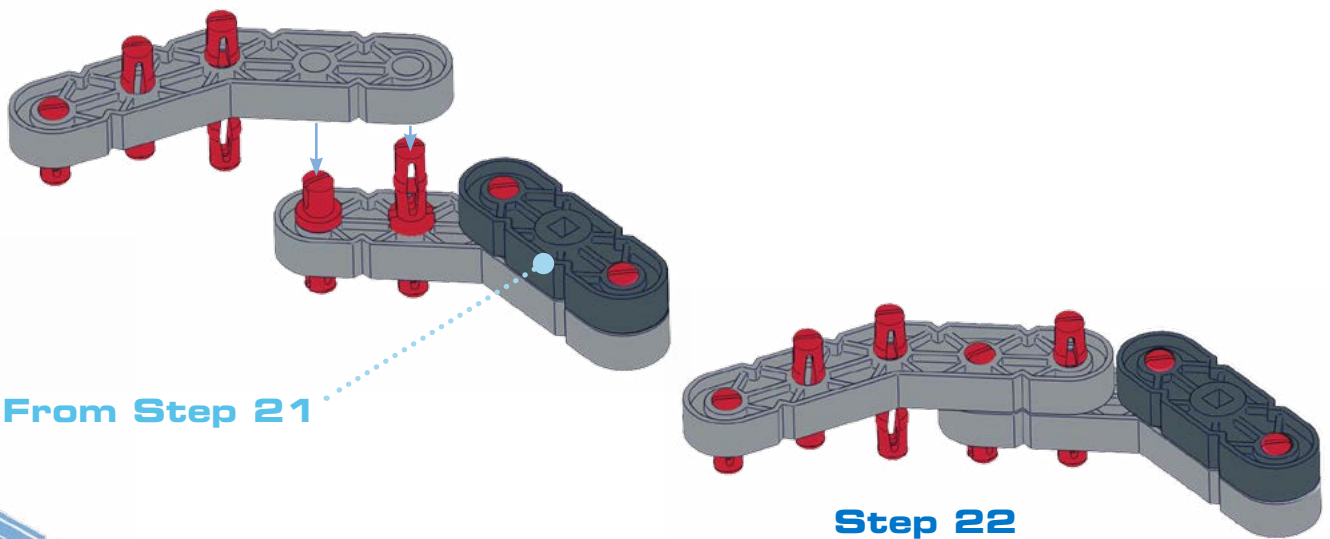
1x [Grey L-shaped Technic part]

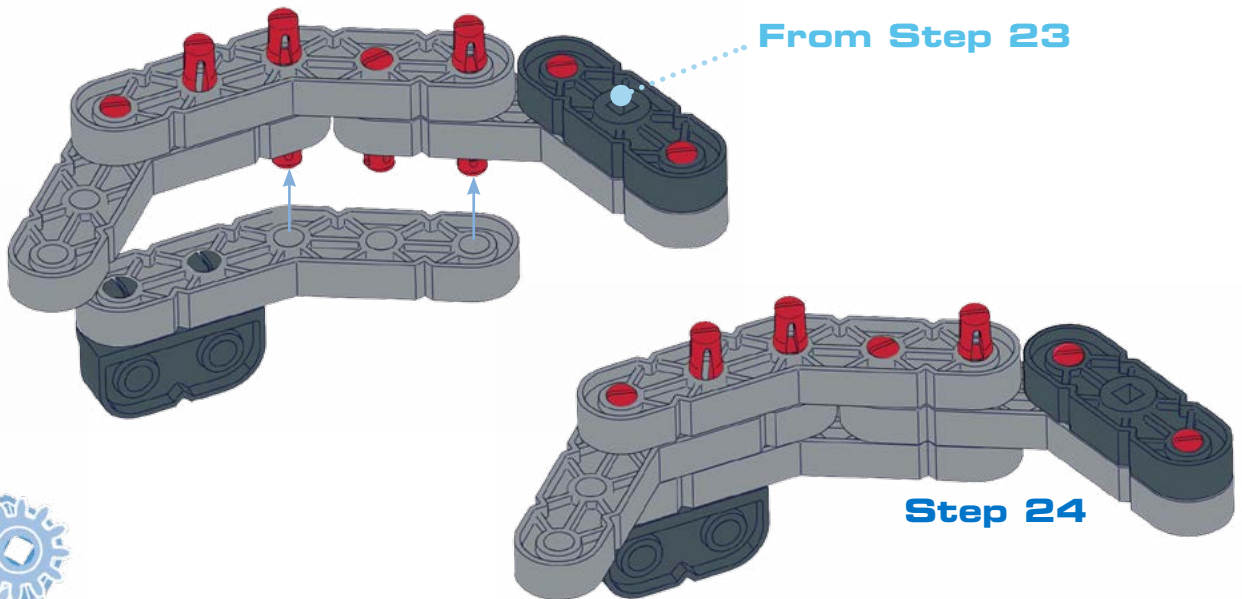
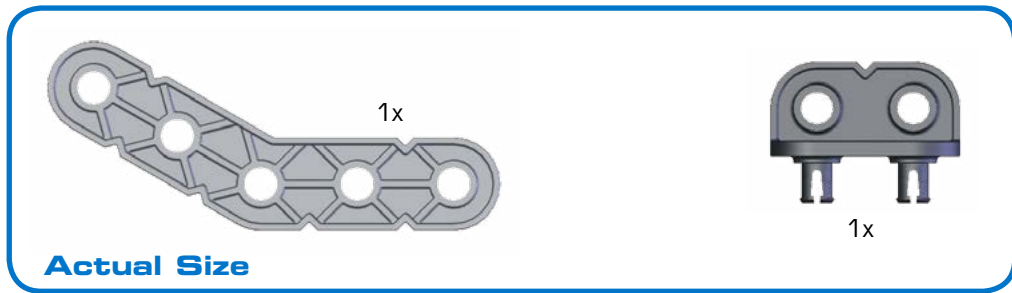
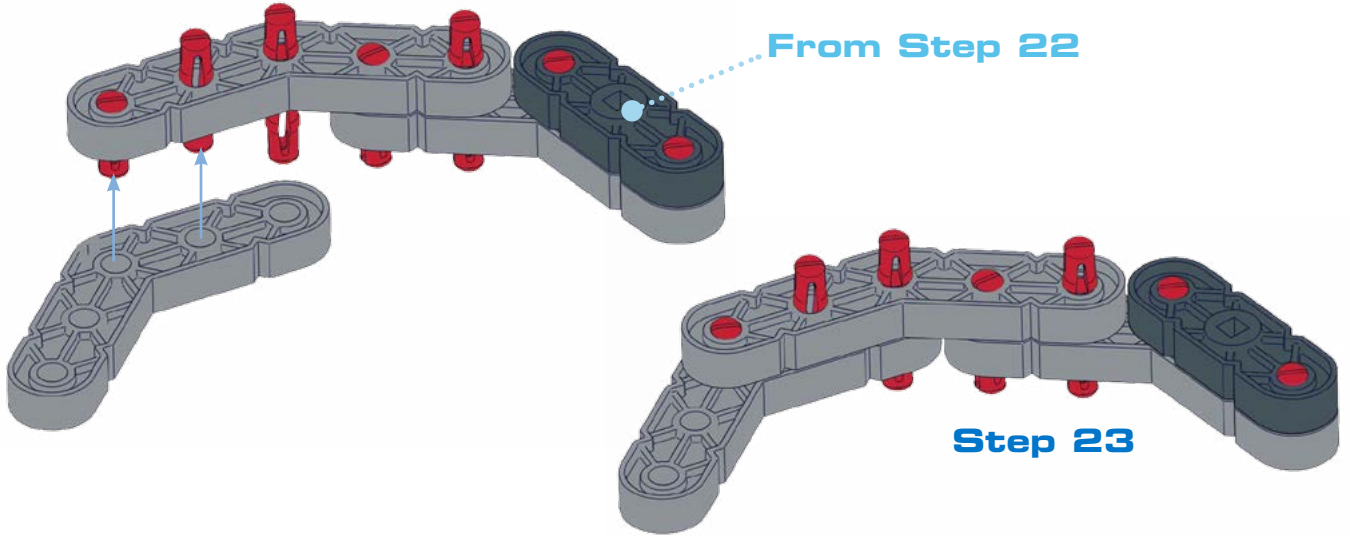
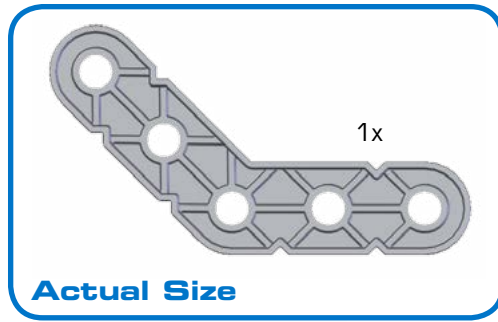
1x [Red Technic Pin]

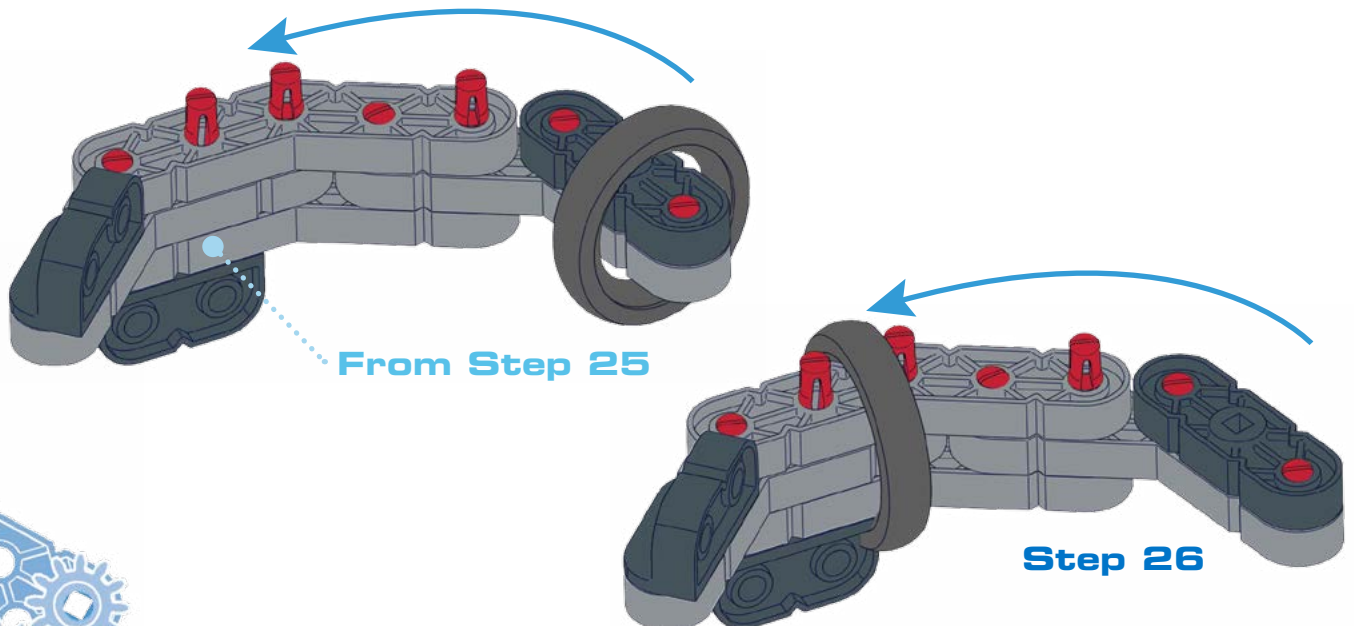
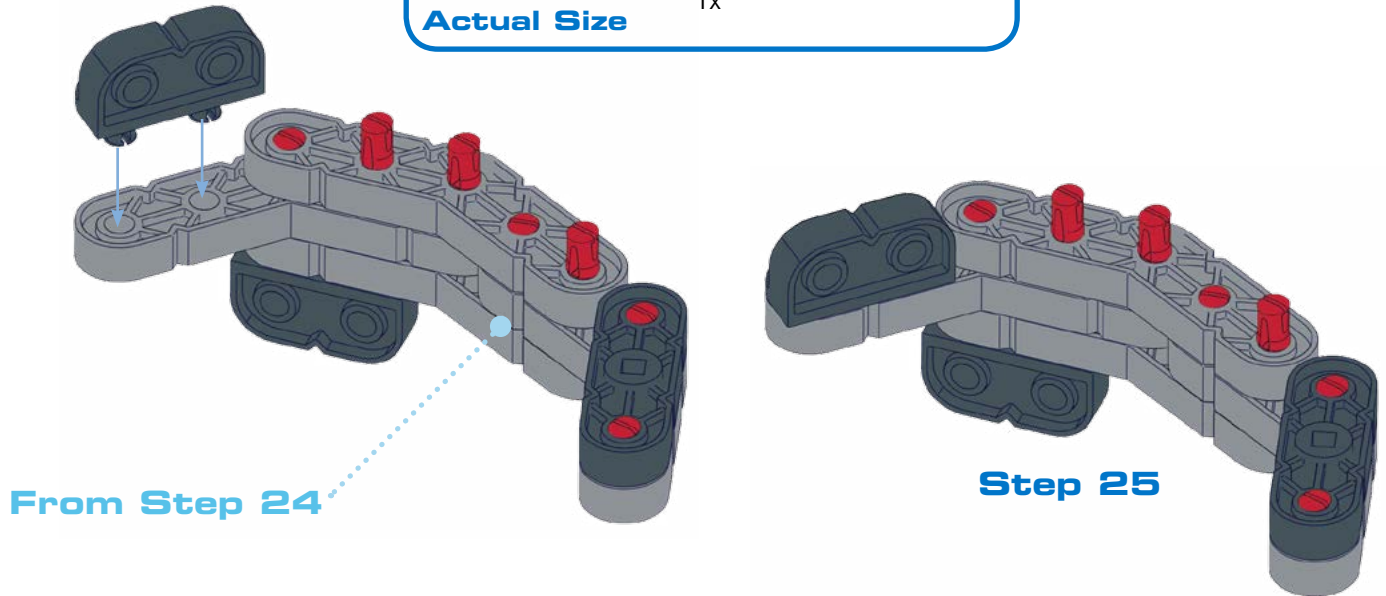
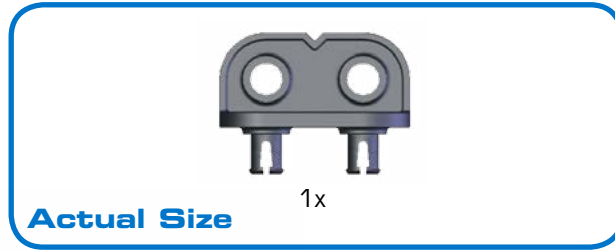
1x [Red Technic Pin]

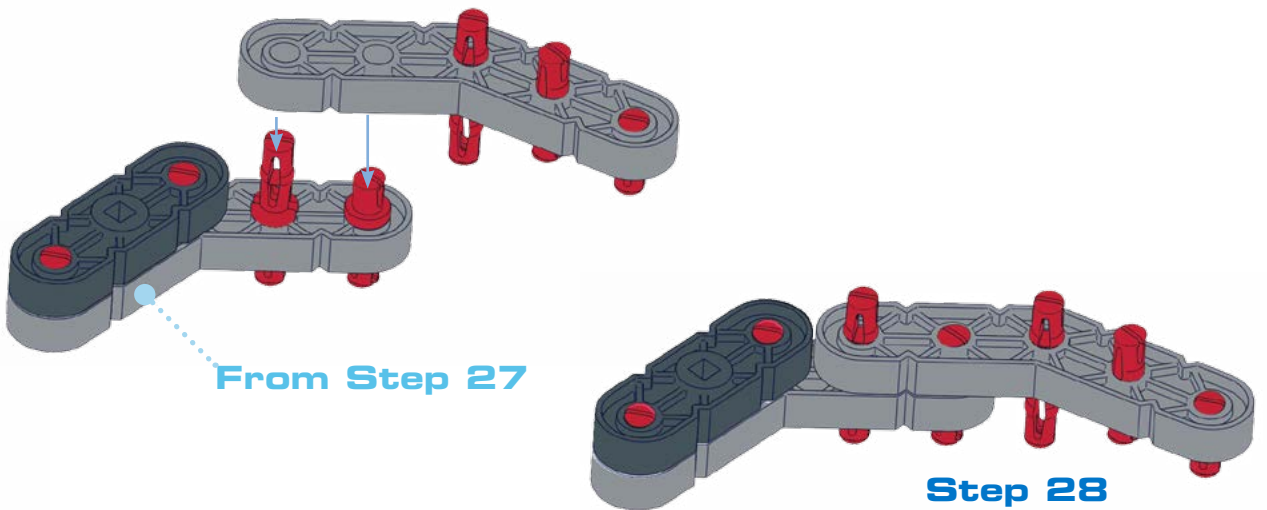
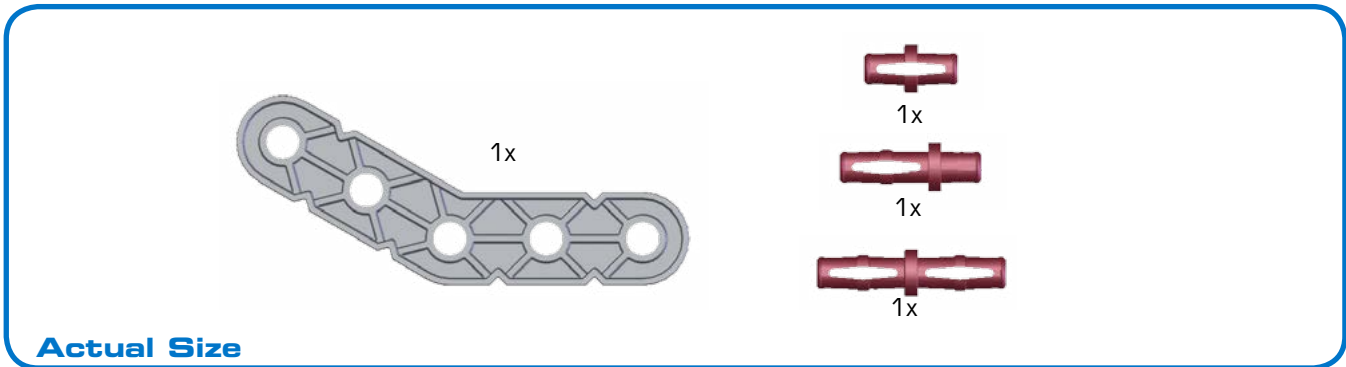
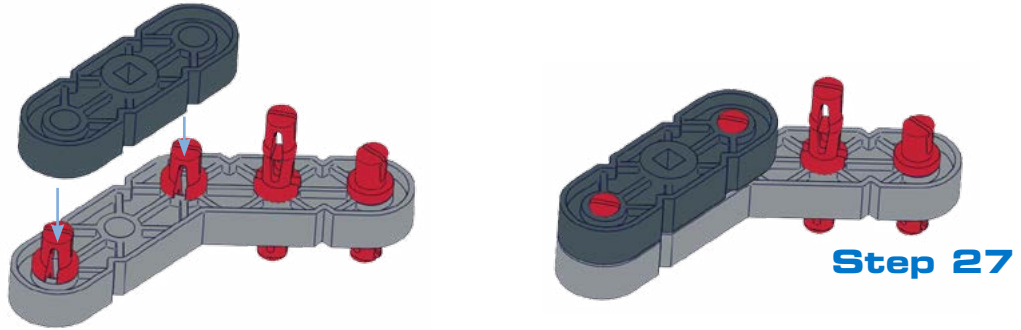
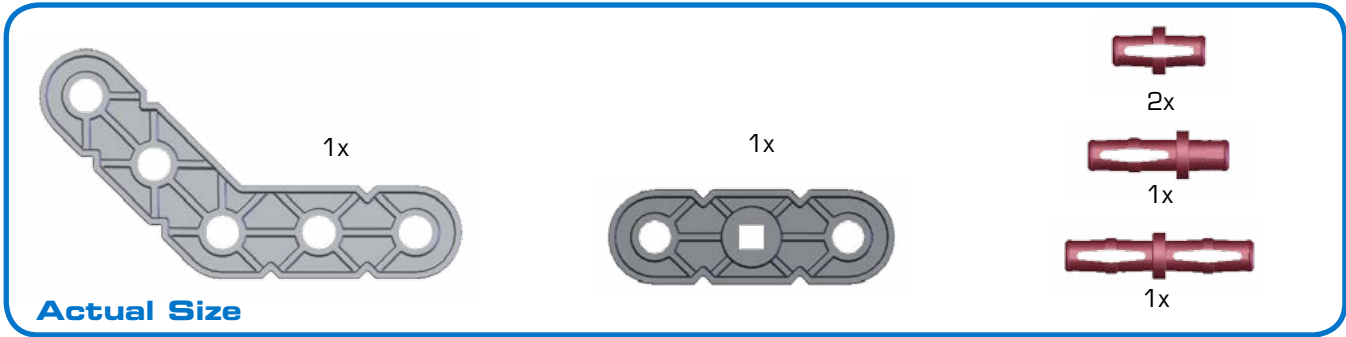
1x [Red Technic Pin]

Actual Size

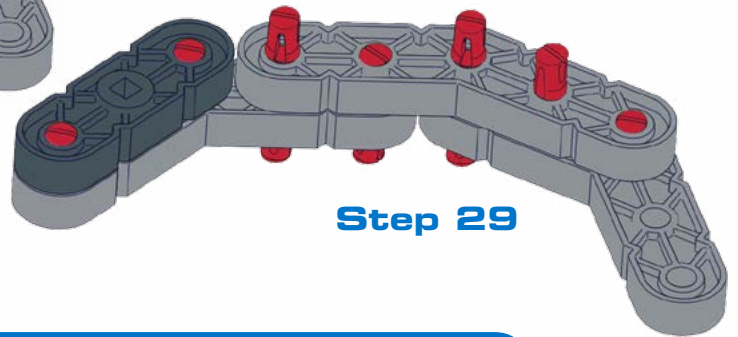
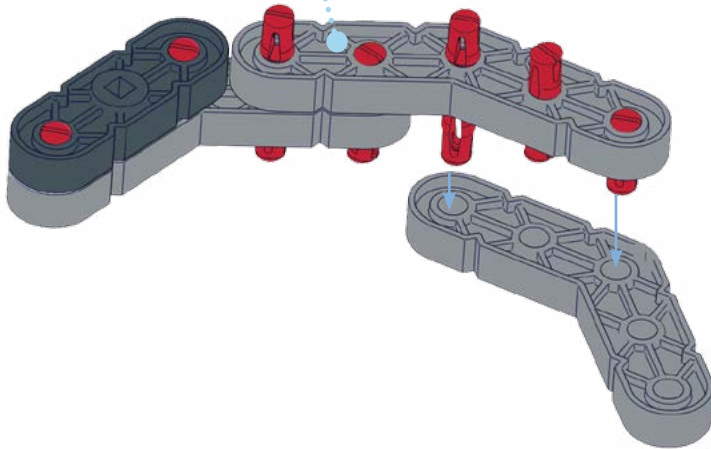
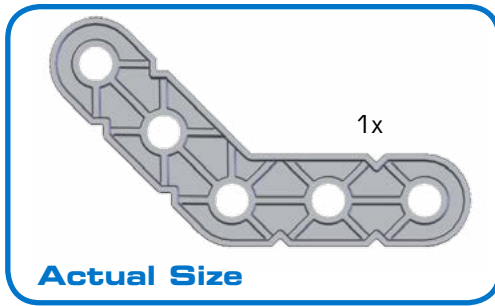




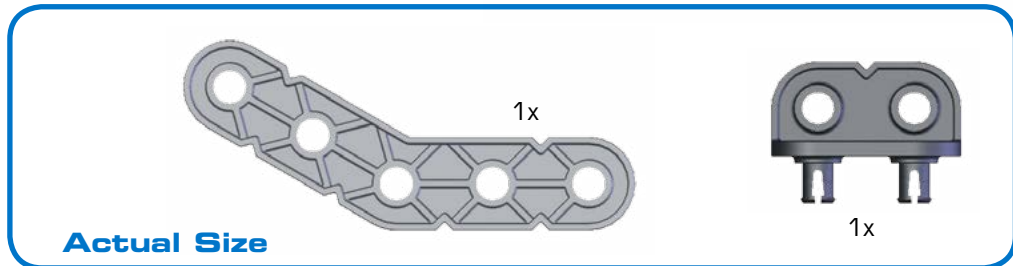




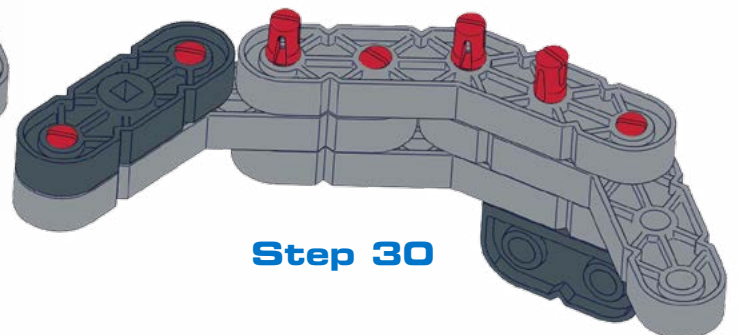
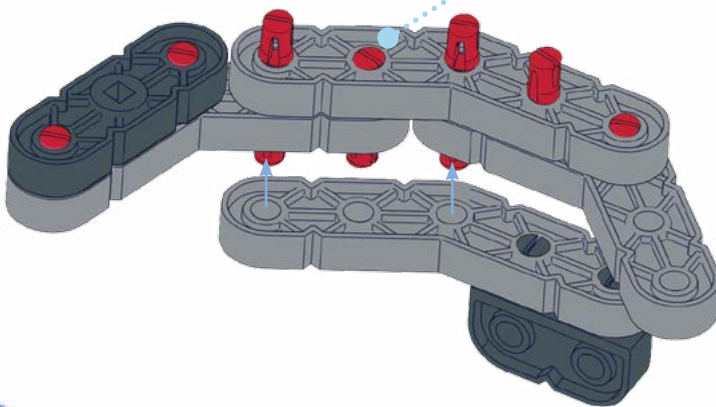
From Step 28



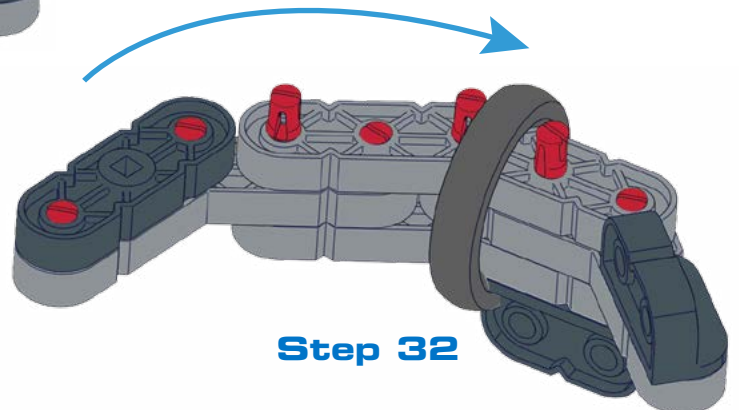
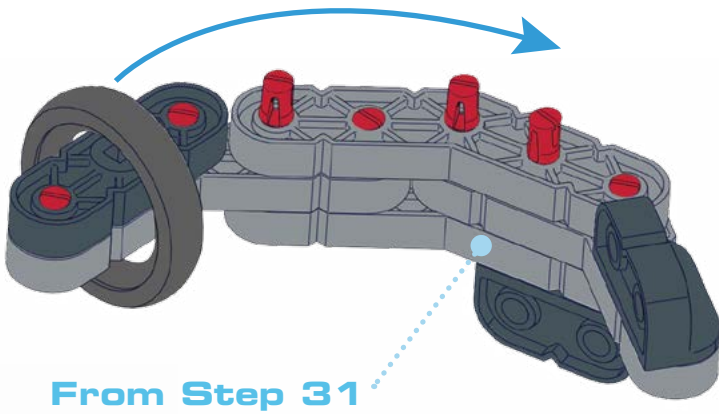
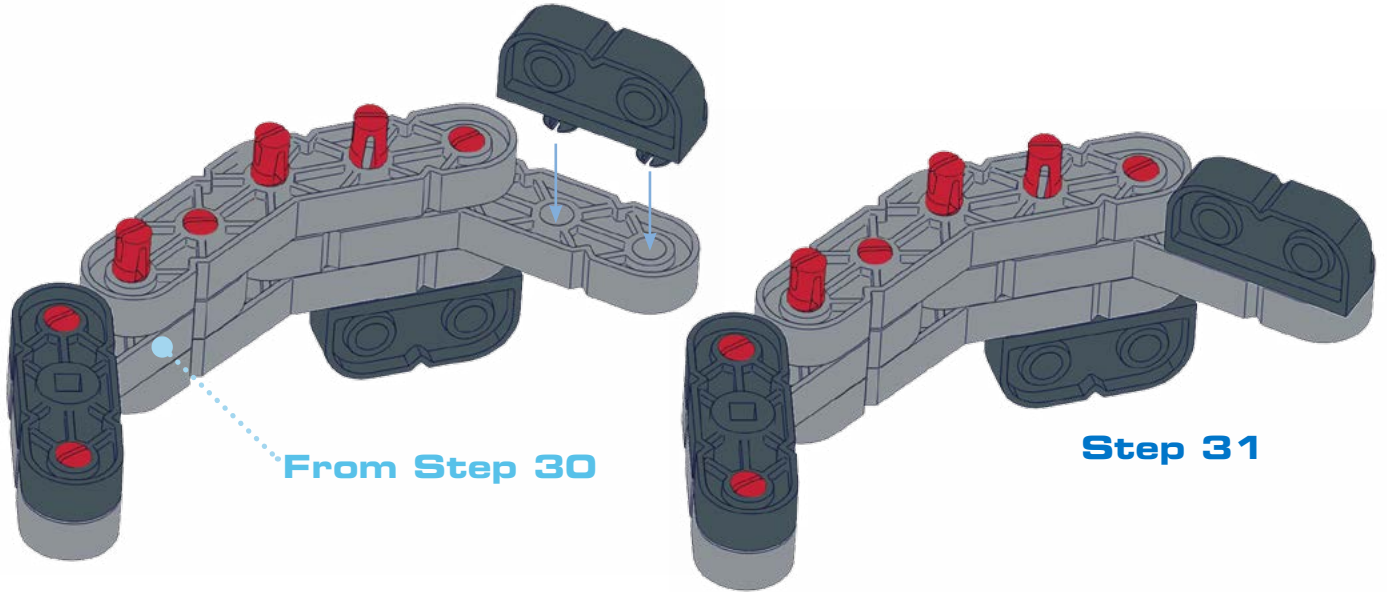
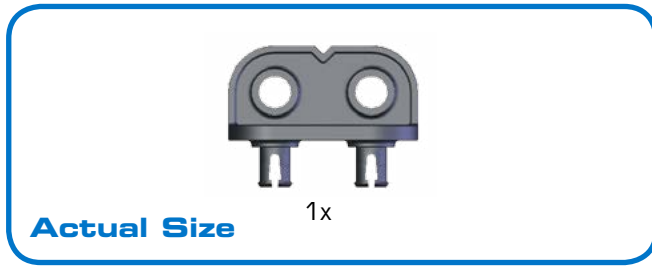
Step 29

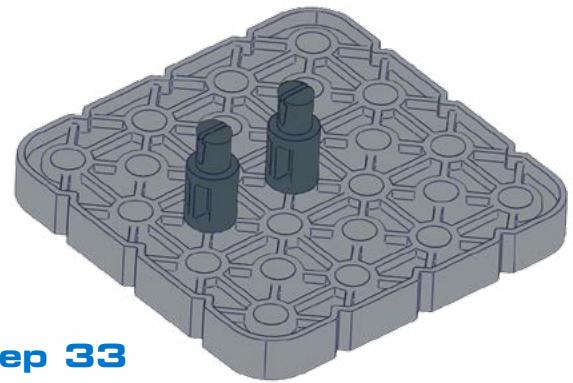
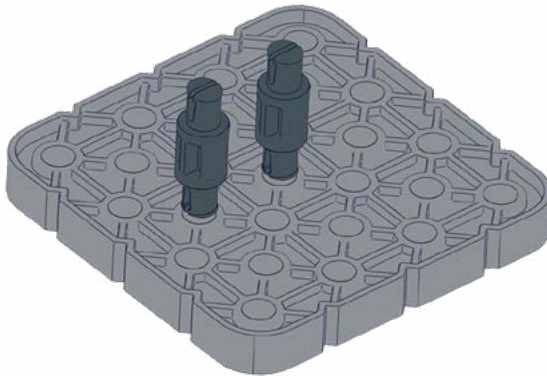
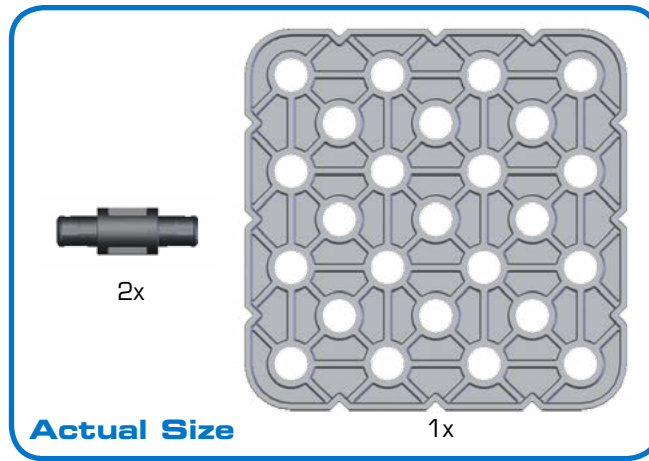


From Step 29

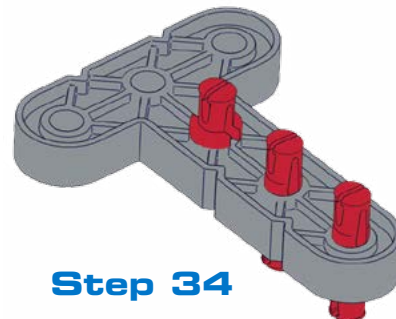
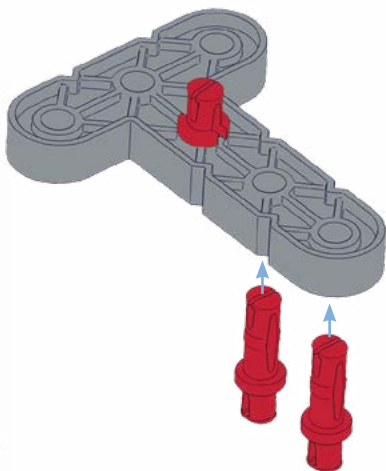
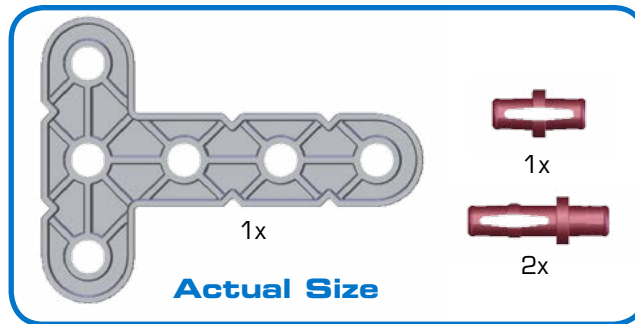


Step 30

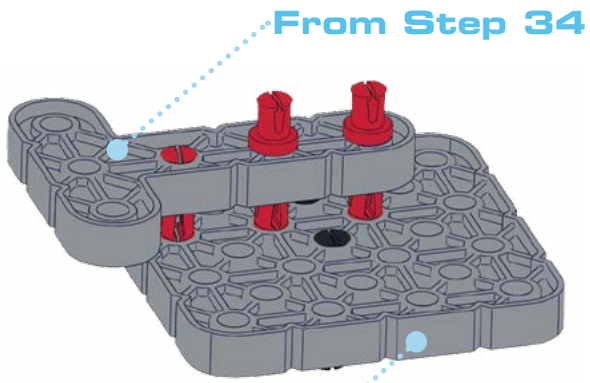




Step 33

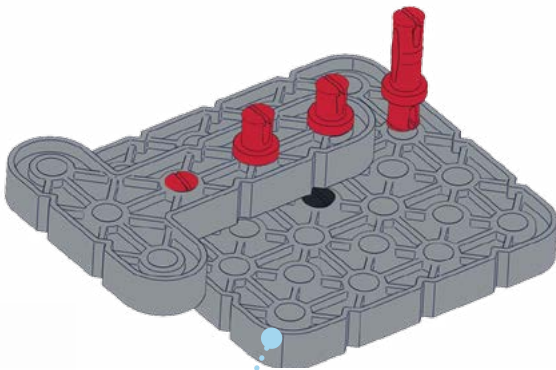
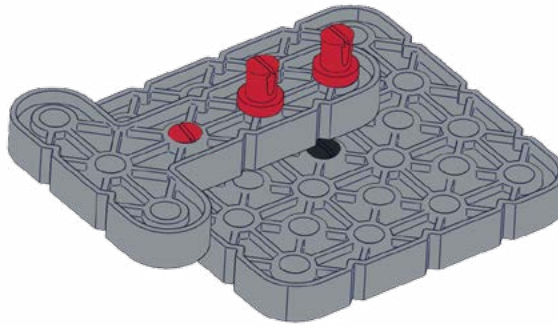
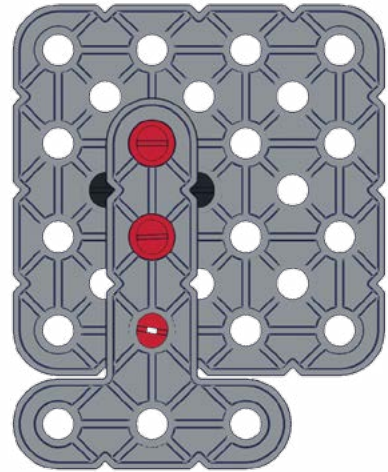


Step 34

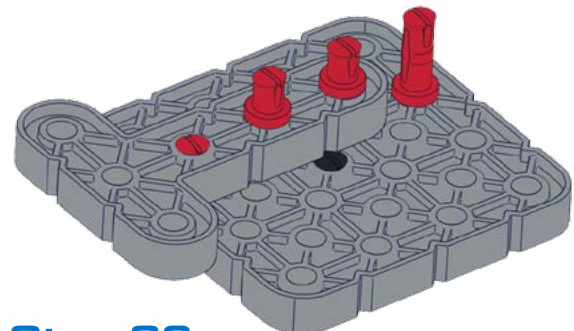


From Step 33

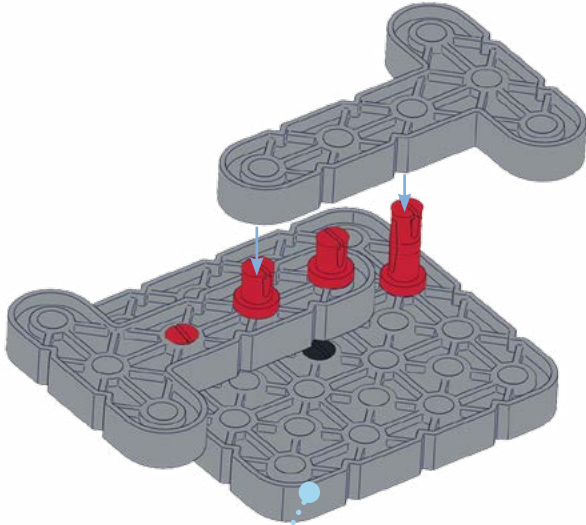
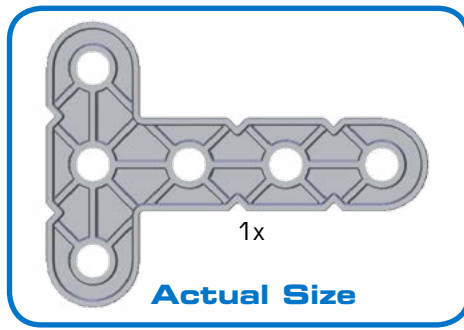
Step 35



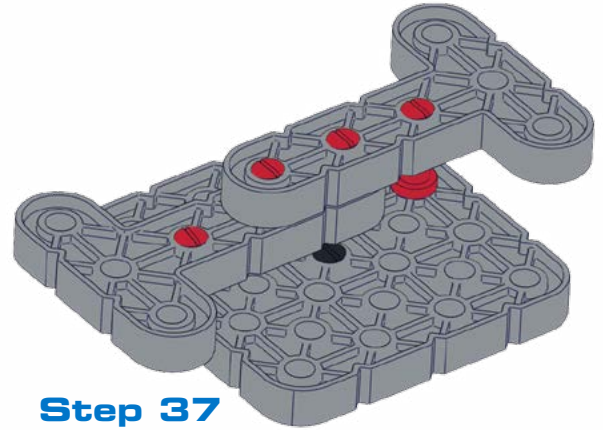
From Step 35



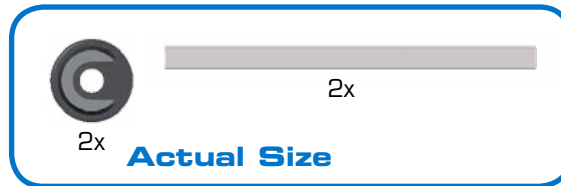
Step 36



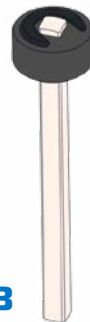
From Step 36



Step 37



Step 38



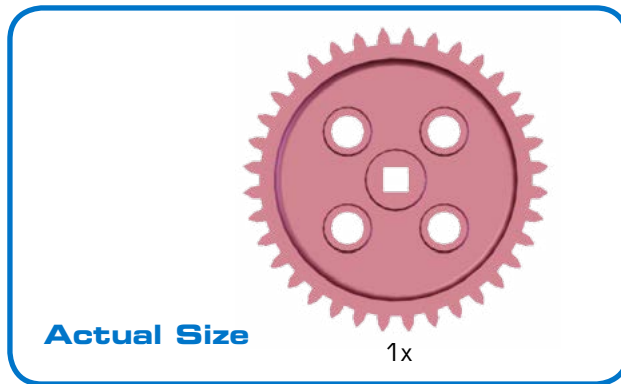
Make
(2x)

From Step 38

From Step 26

From Step 37

Step 39

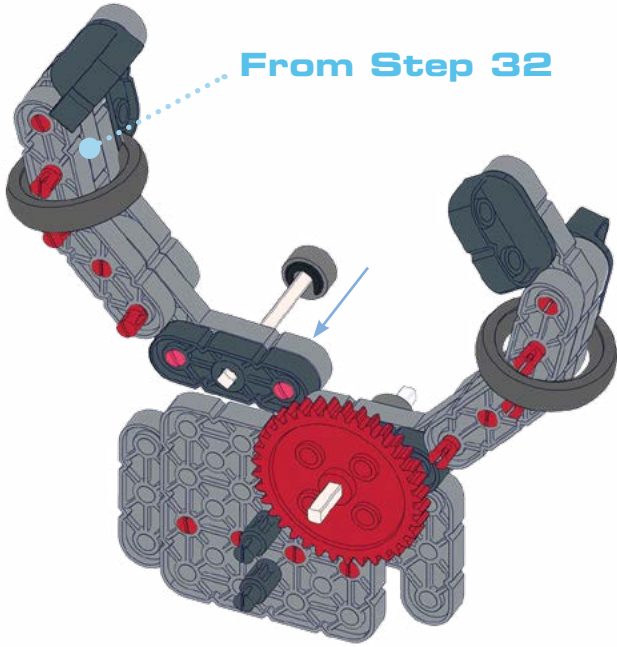


Actual Size

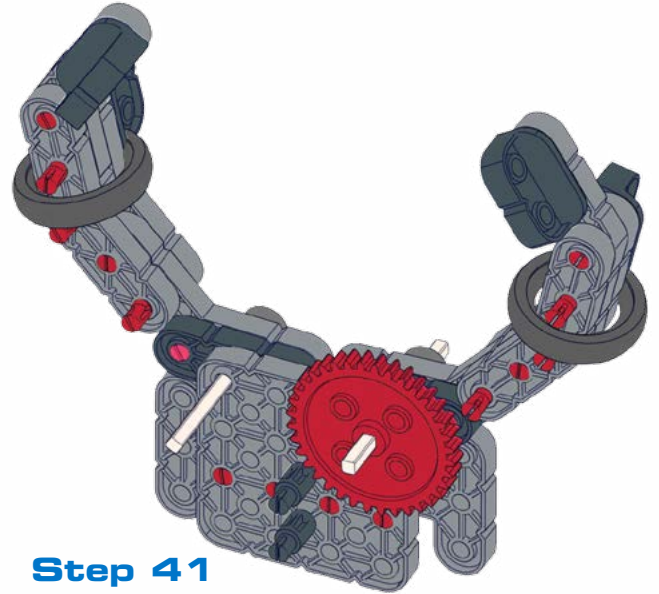
1x

From Step 39

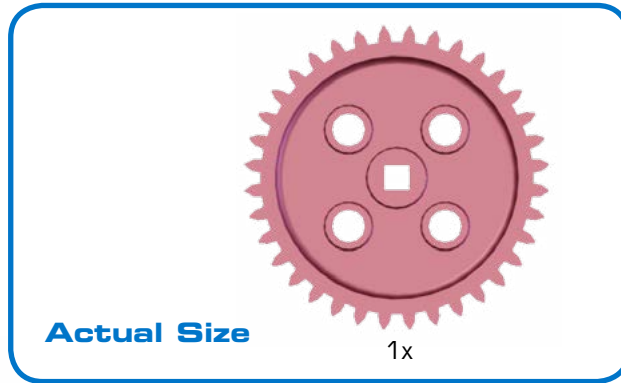
Step 40



From Step 32

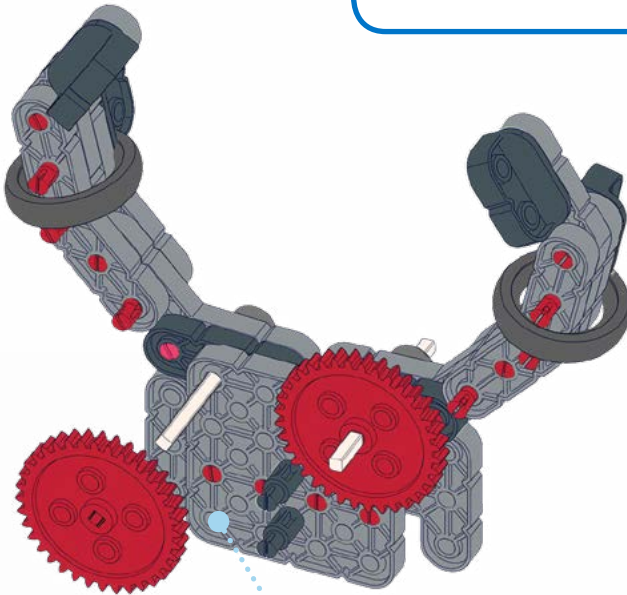


Step 41

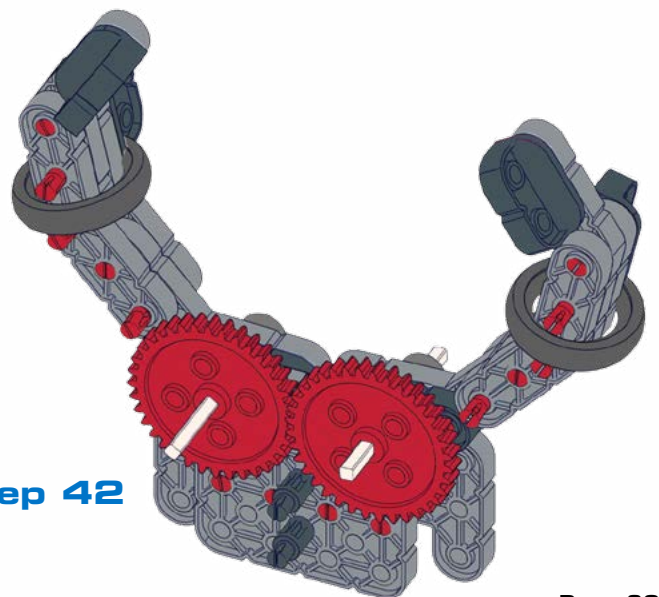


Actual Size

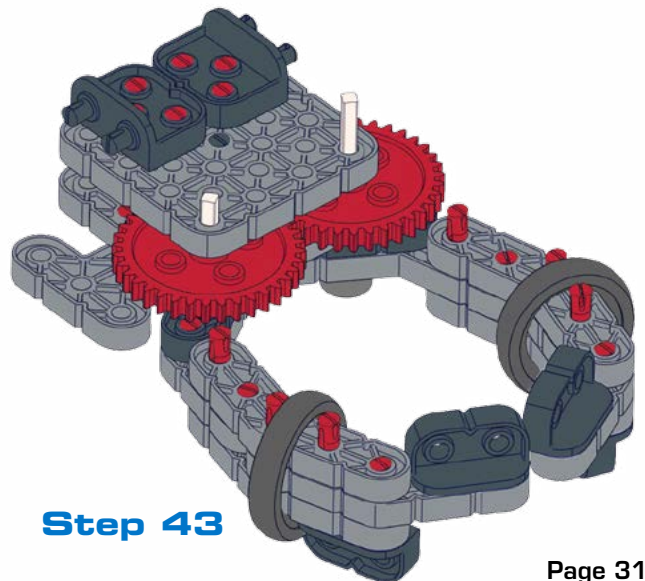
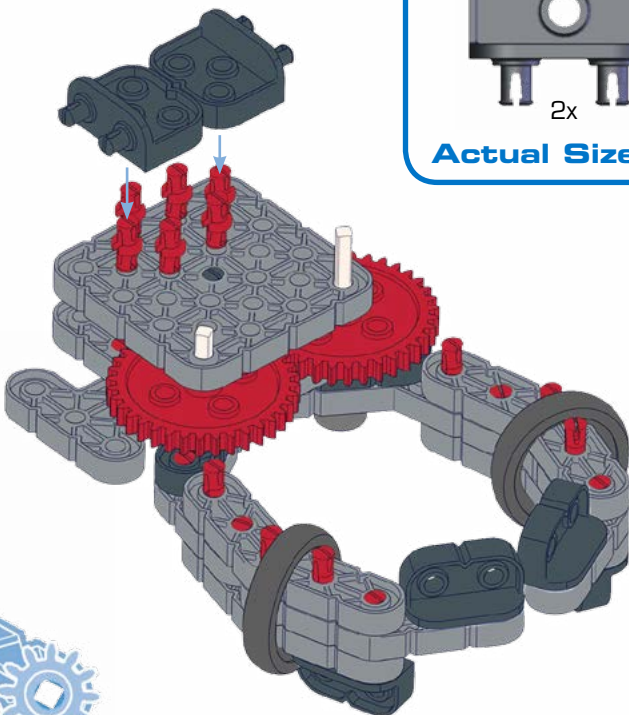
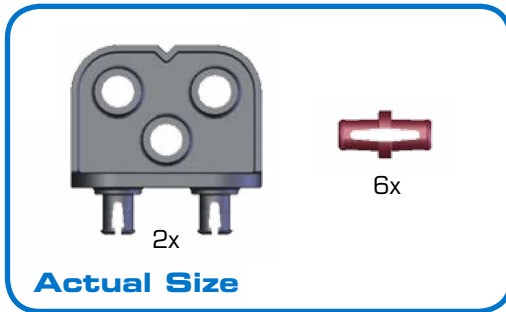
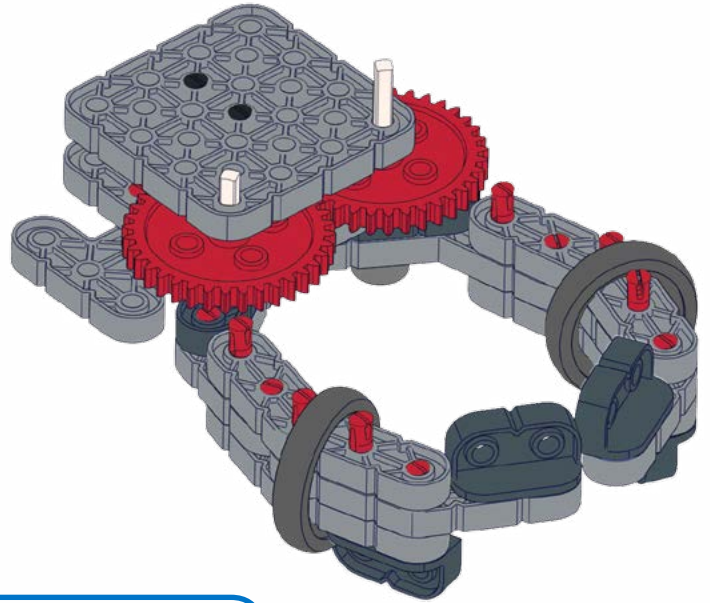
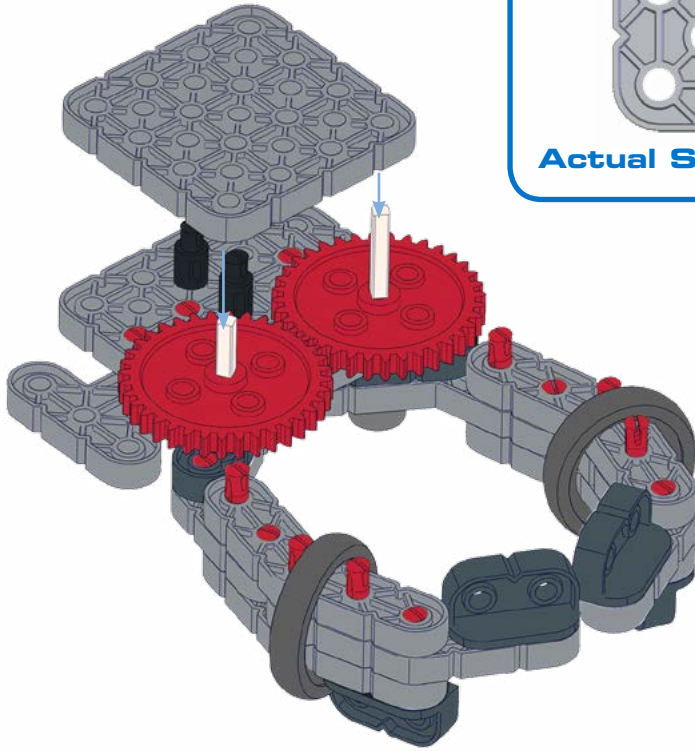
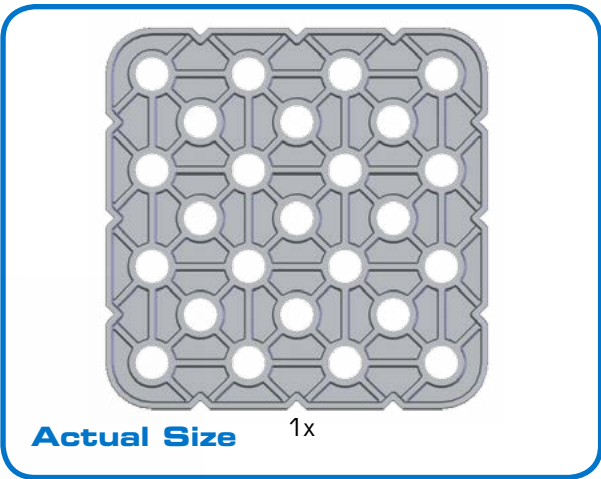
1x



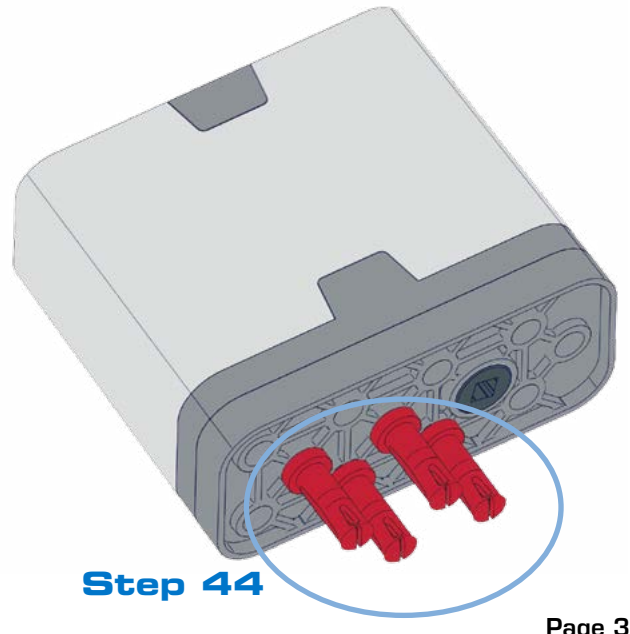
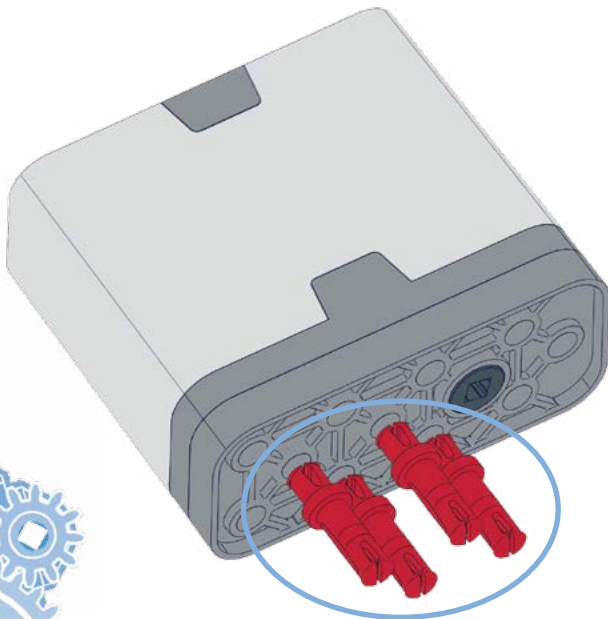
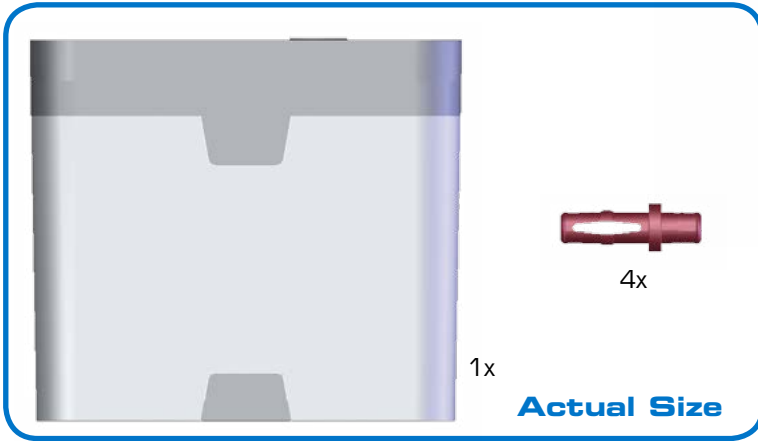
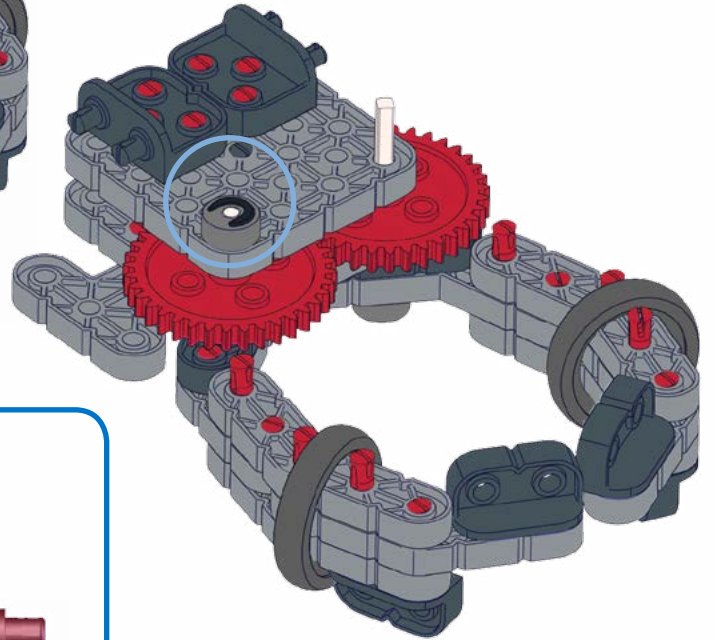
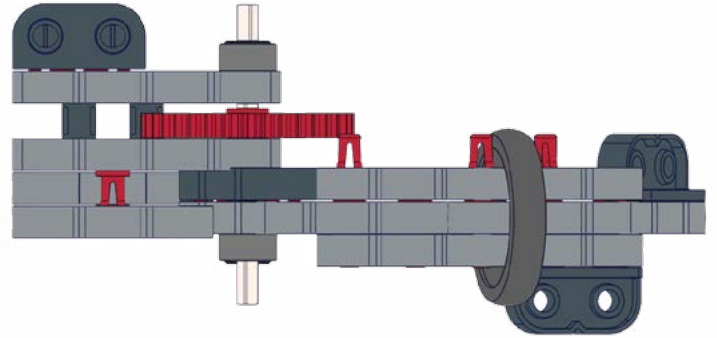
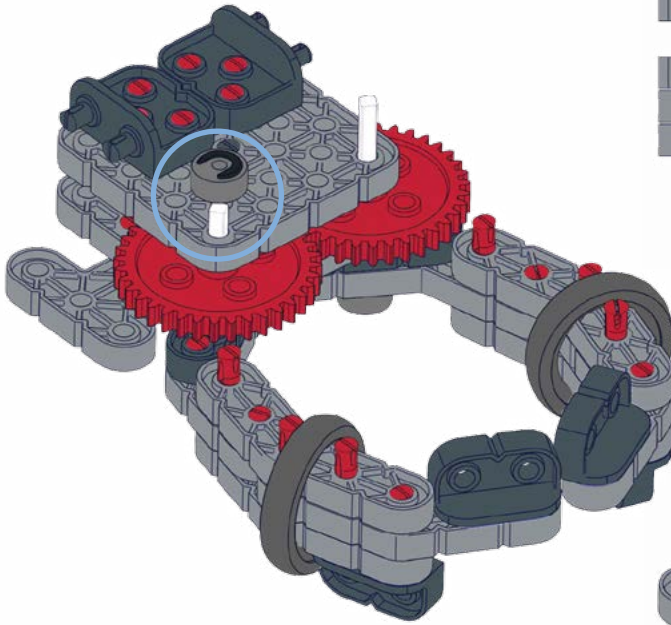
From Step 41

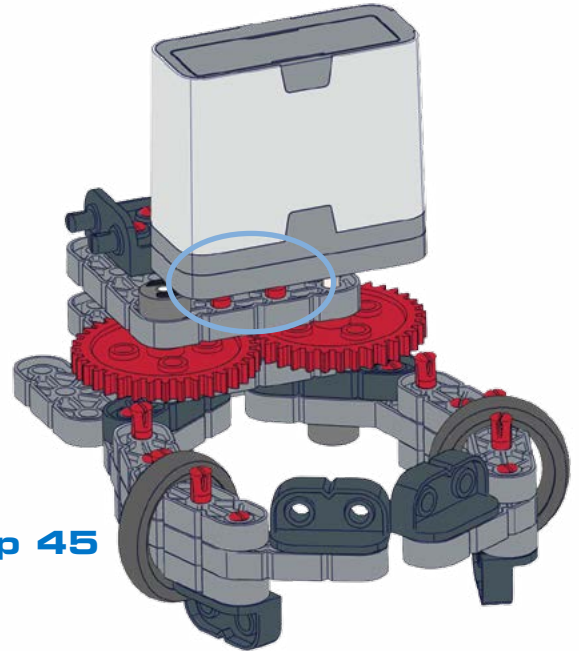
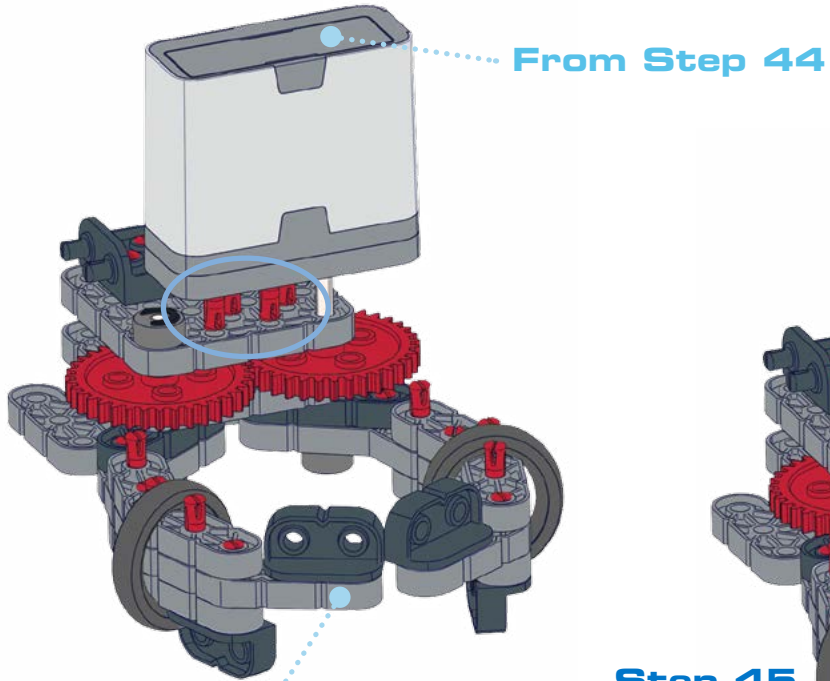


Step 42

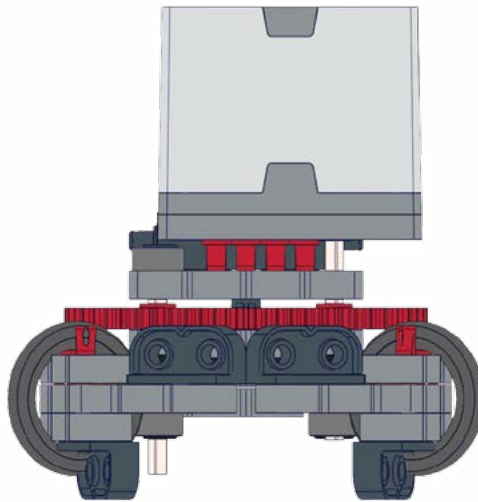


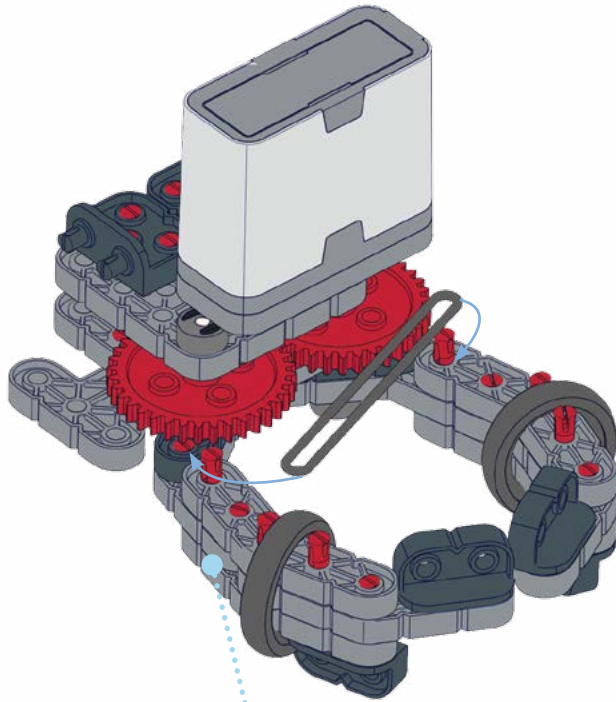
Step 43



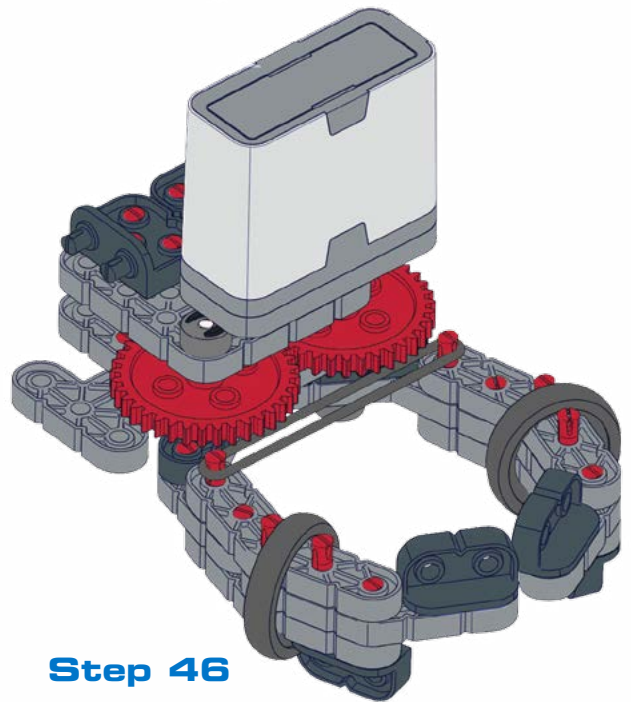


From Step 43



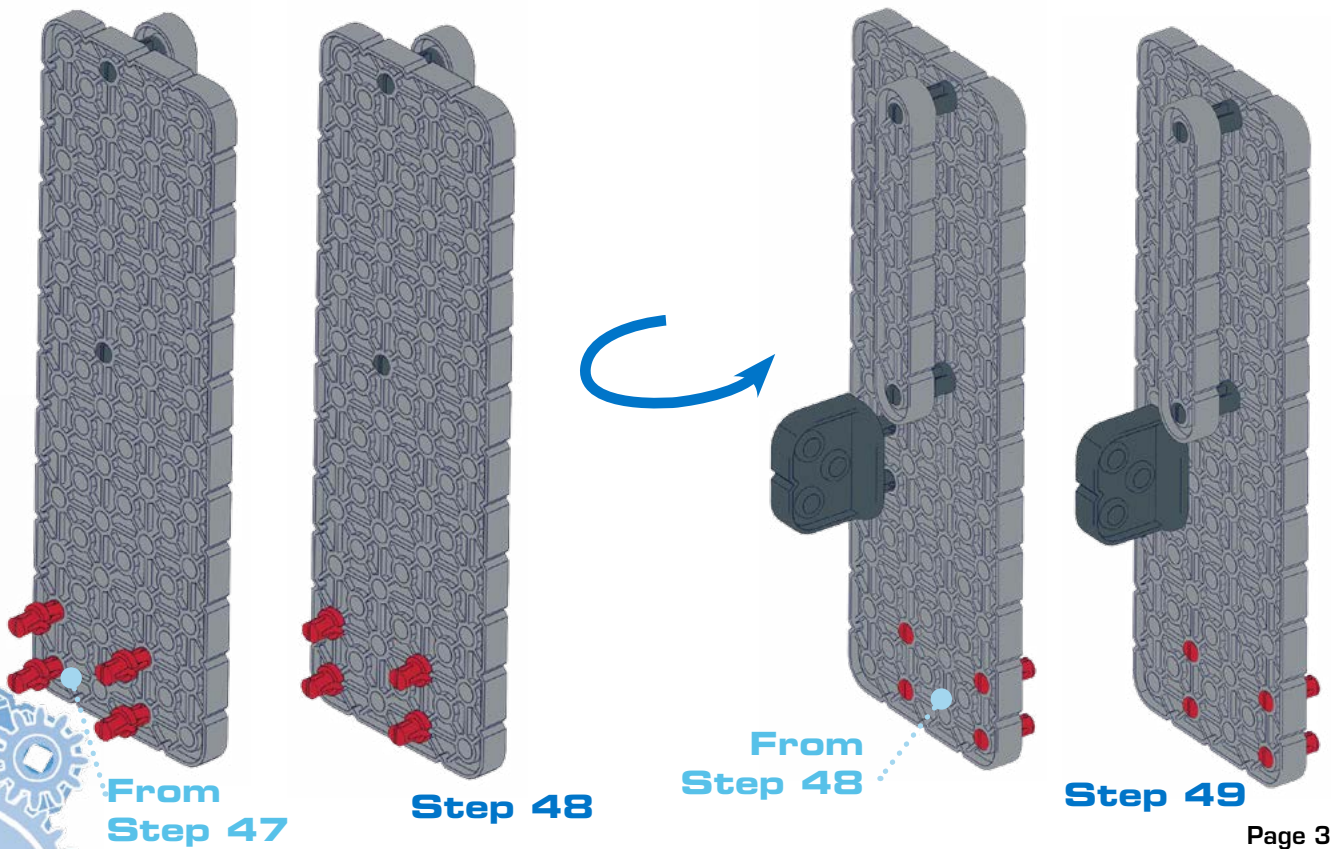
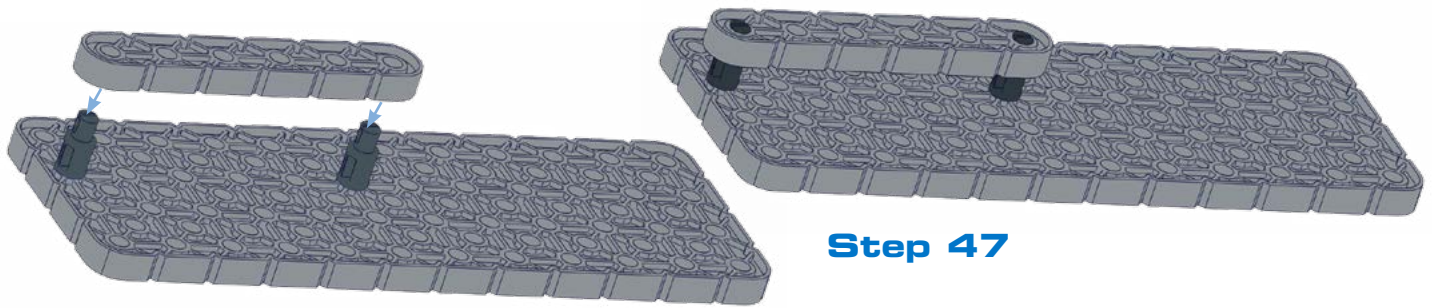
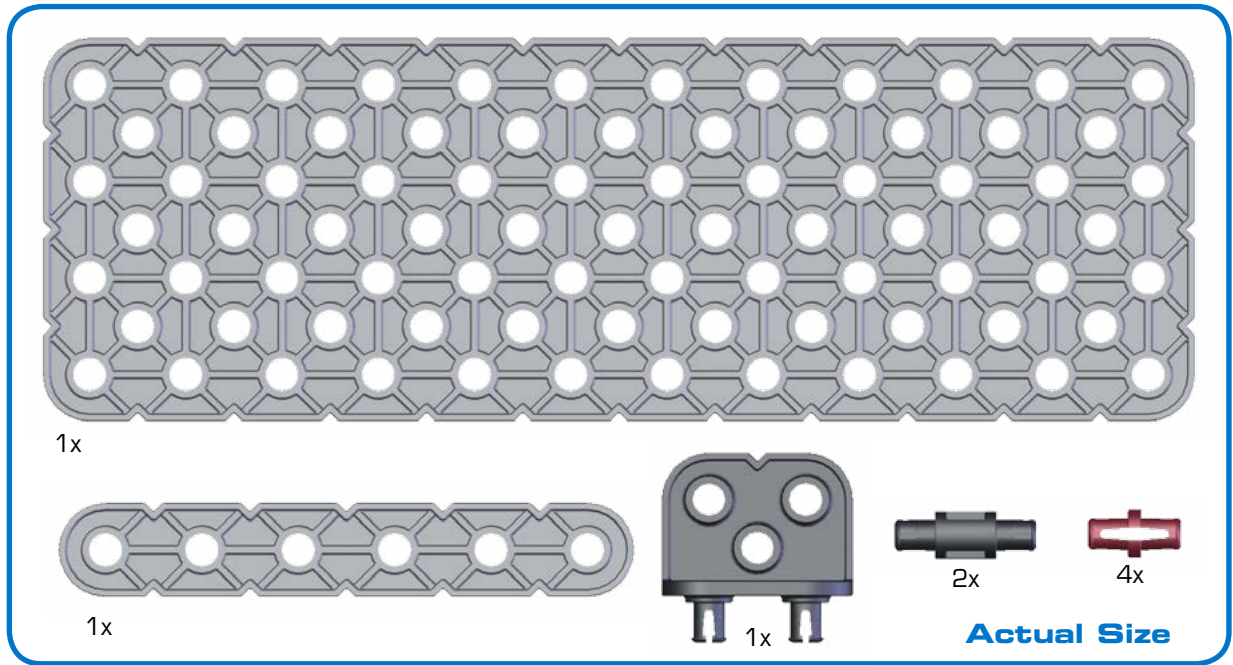


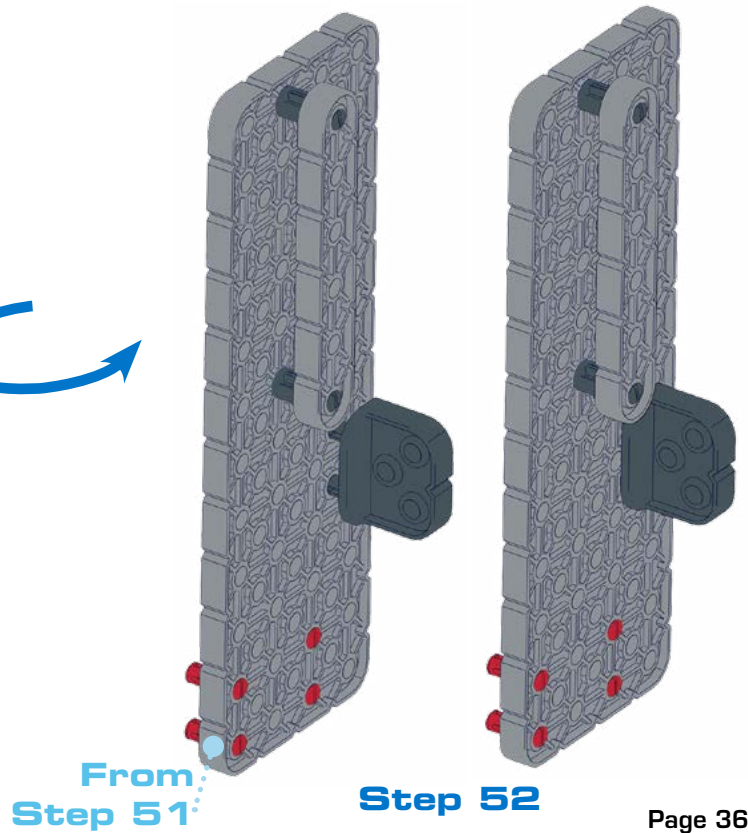
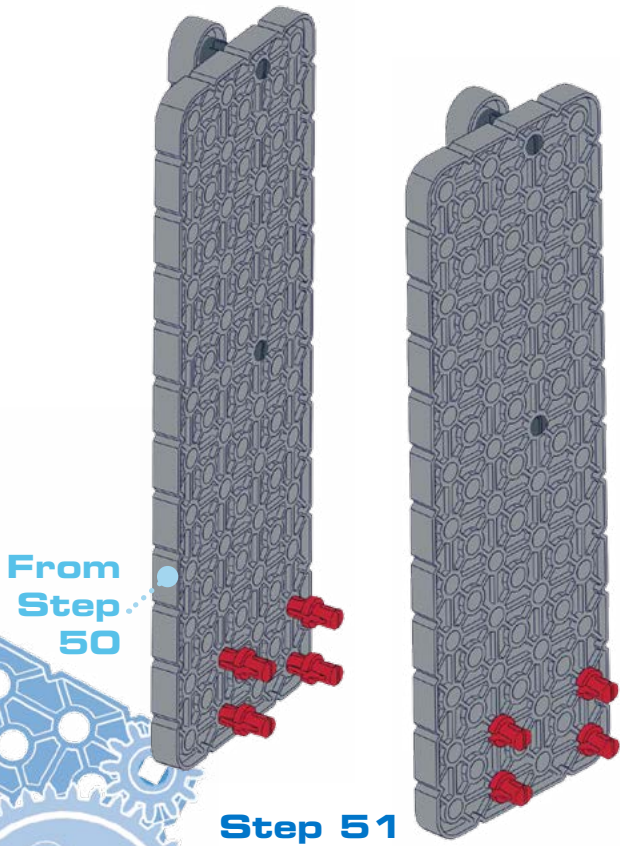
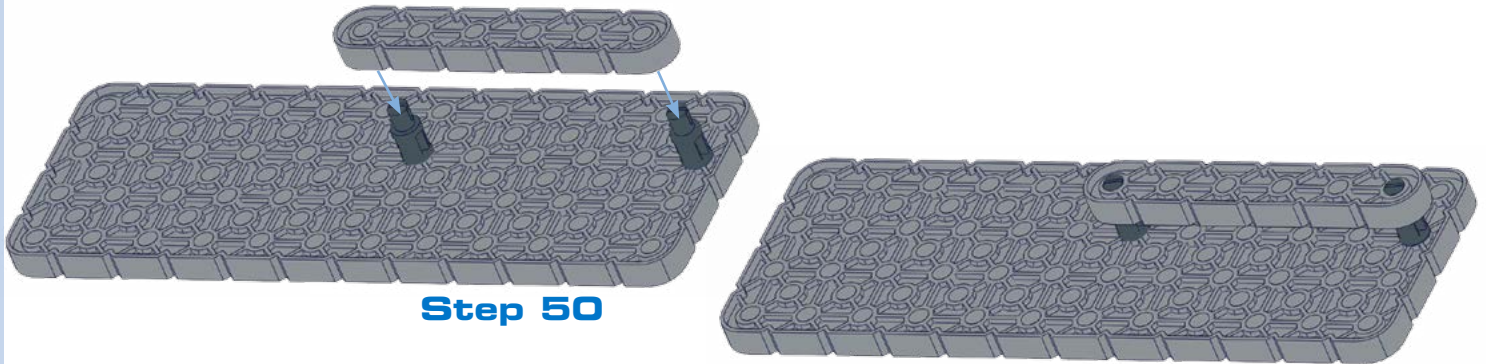
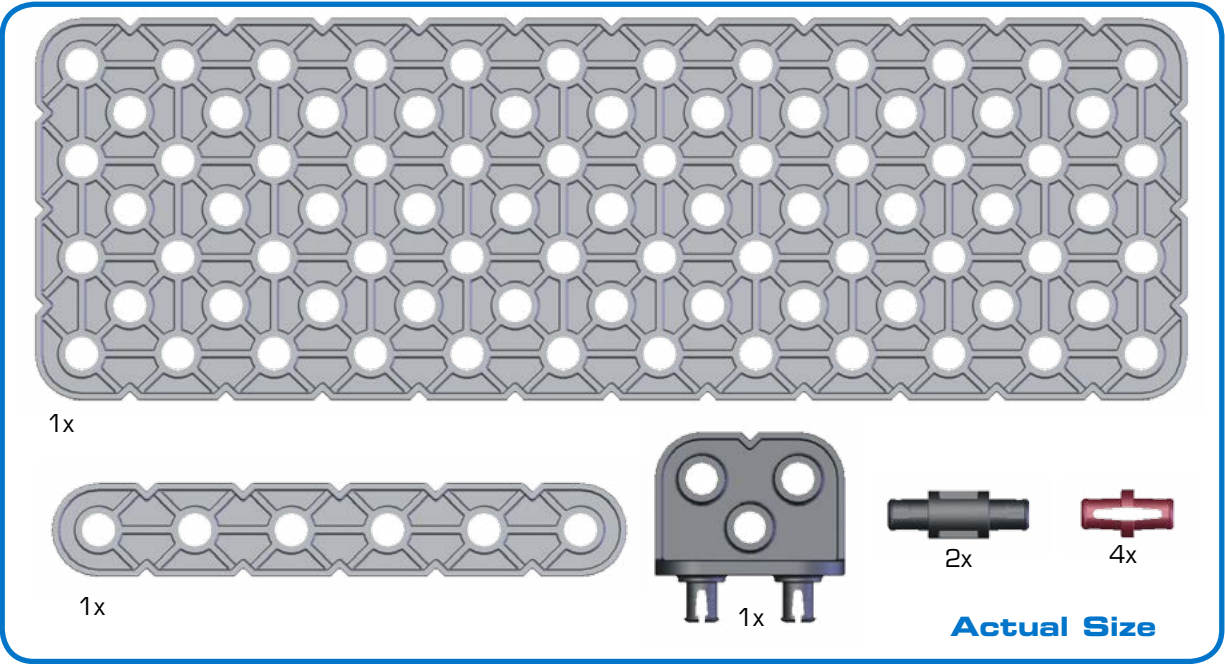
From Step 45

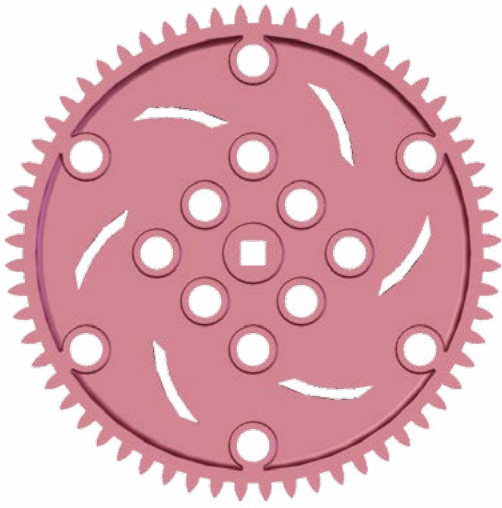


Step 46

Part 3 Tower







1x

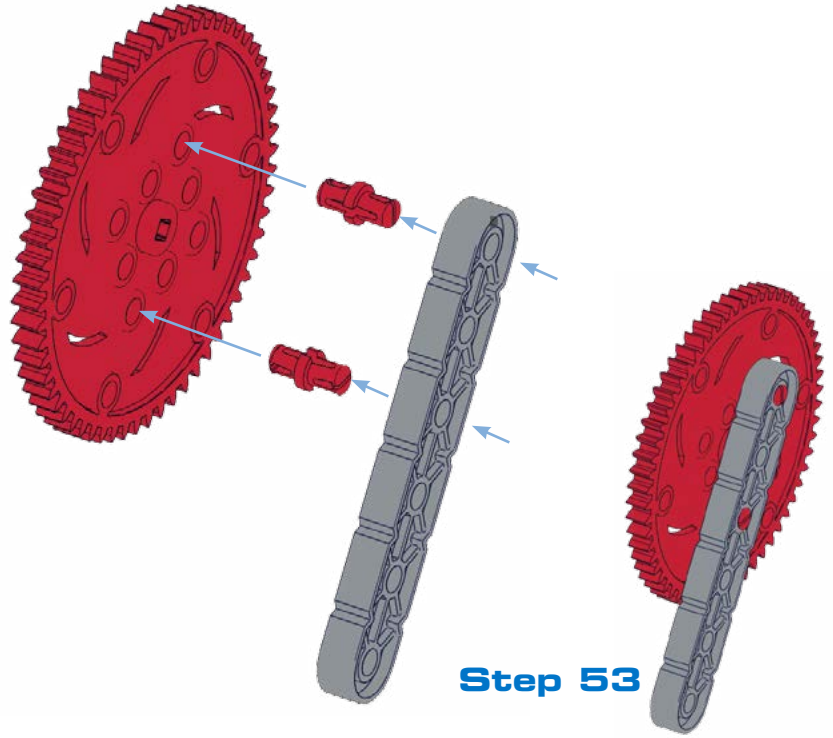


2x



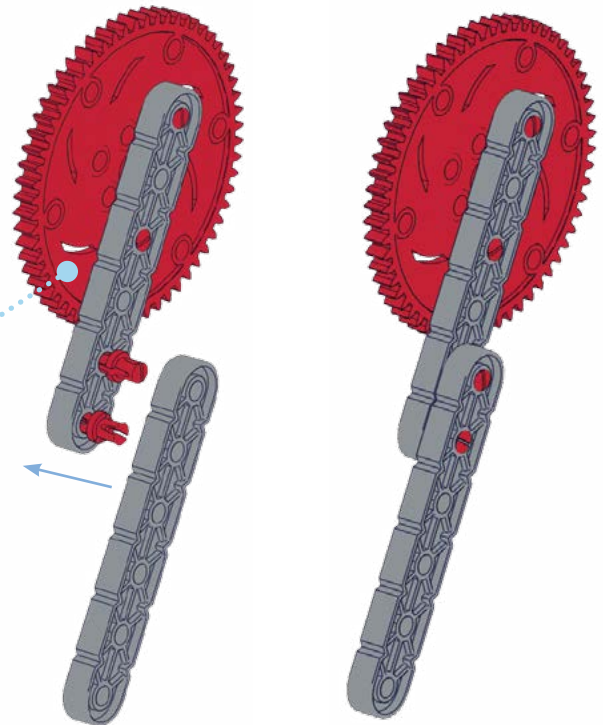
4x

Actual Size

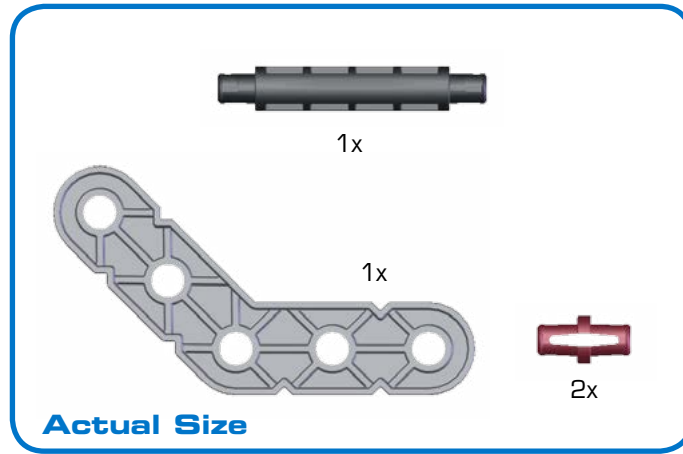


Step 53

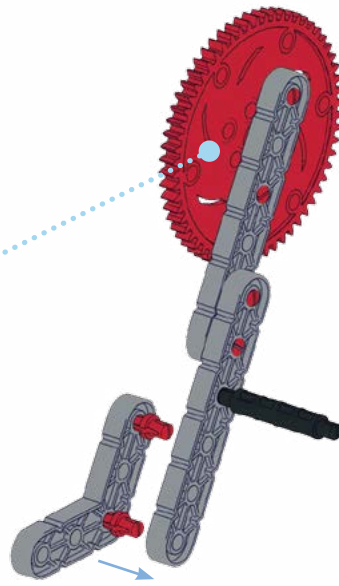
From Step 53



Step 54

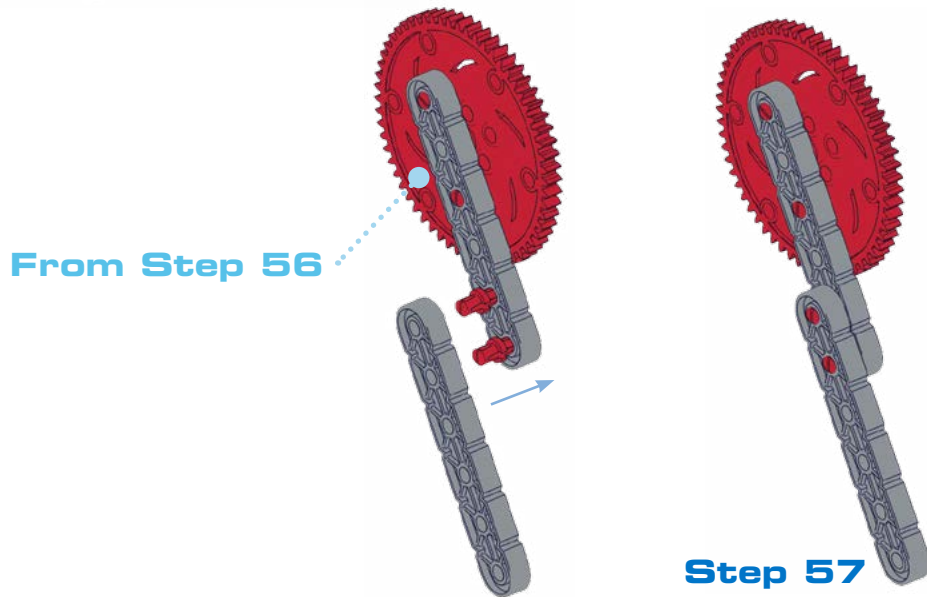
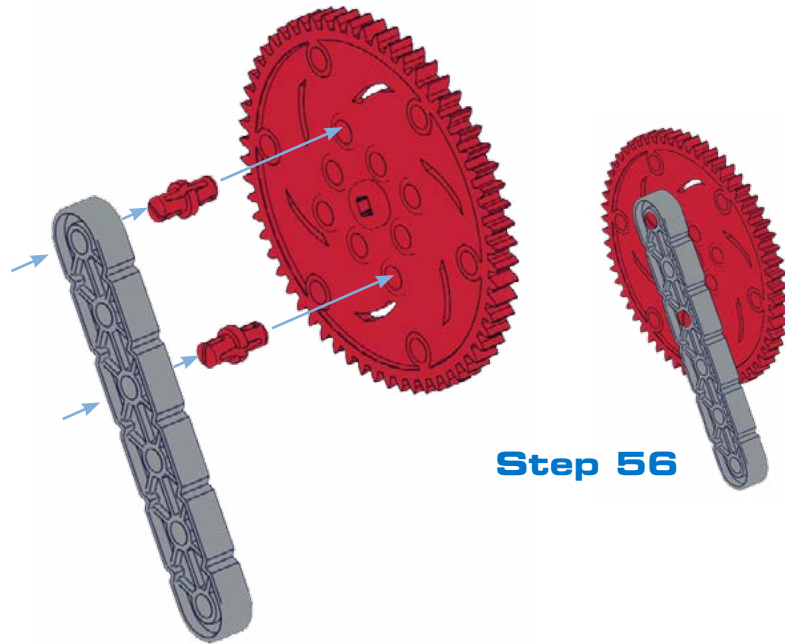
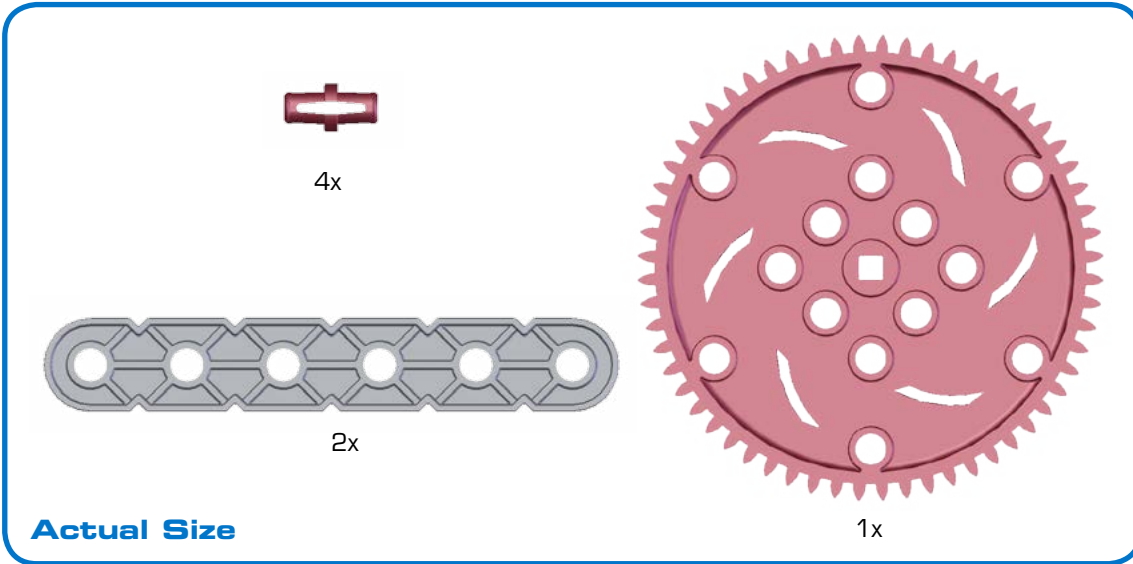


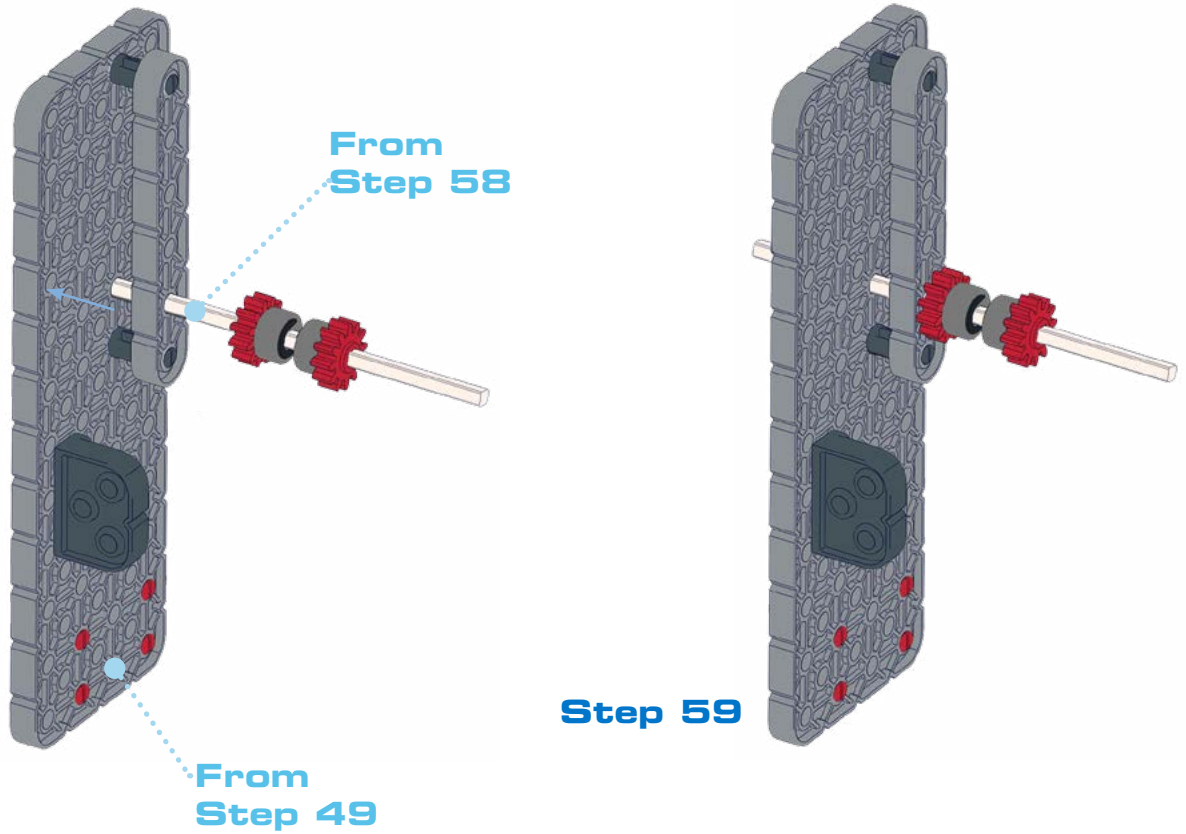
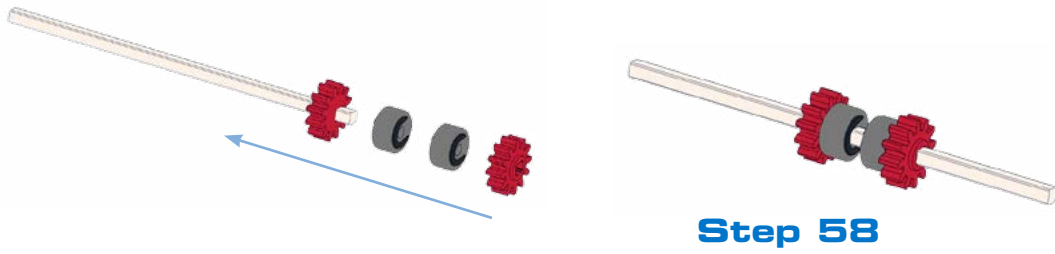
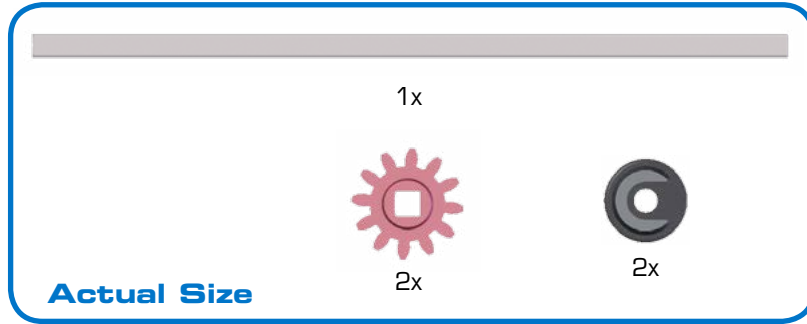
From Step 54



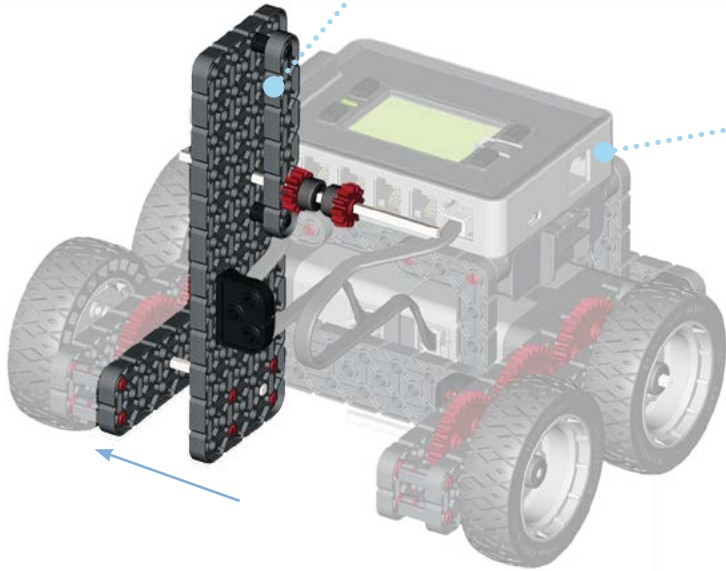
Step 55



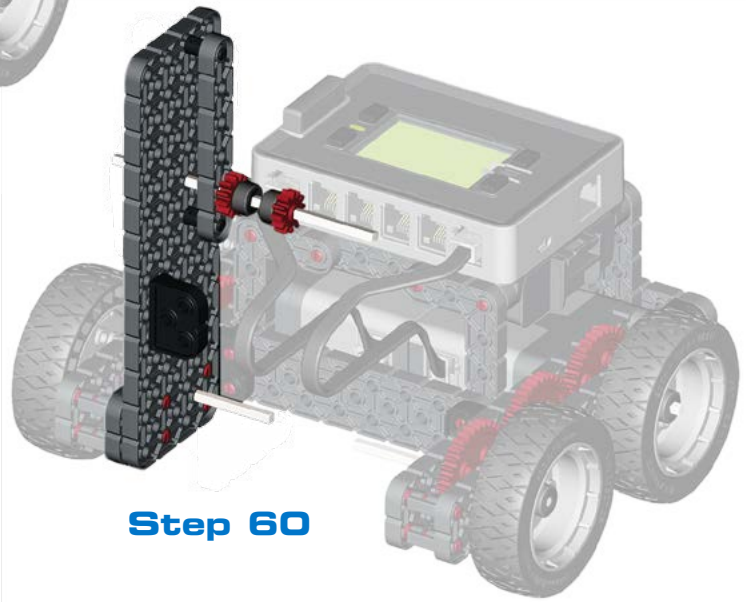




From Step 59

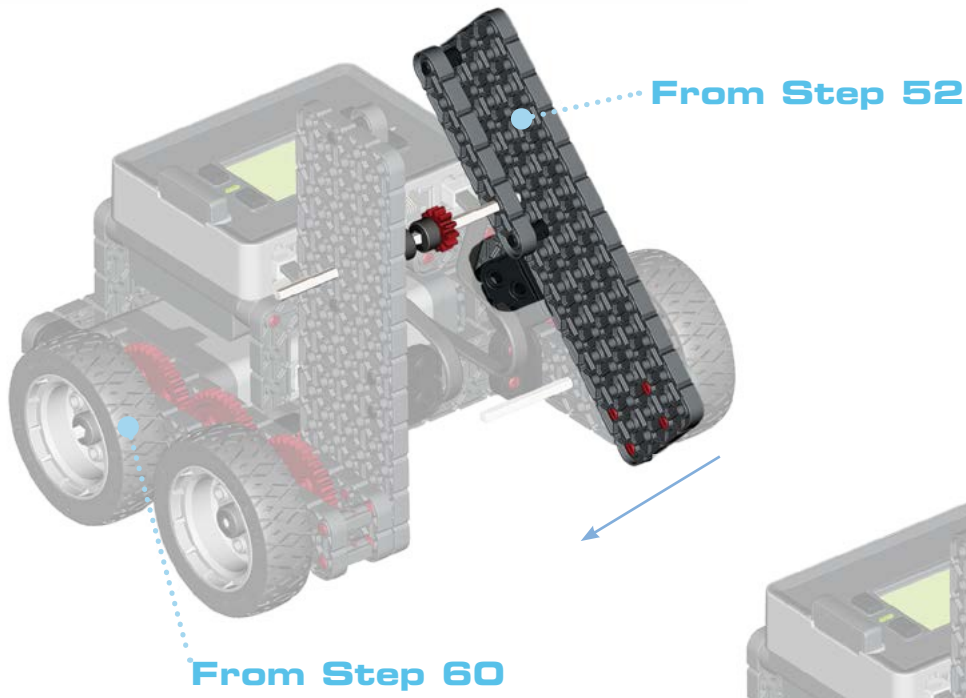


From Step 20



Step 60

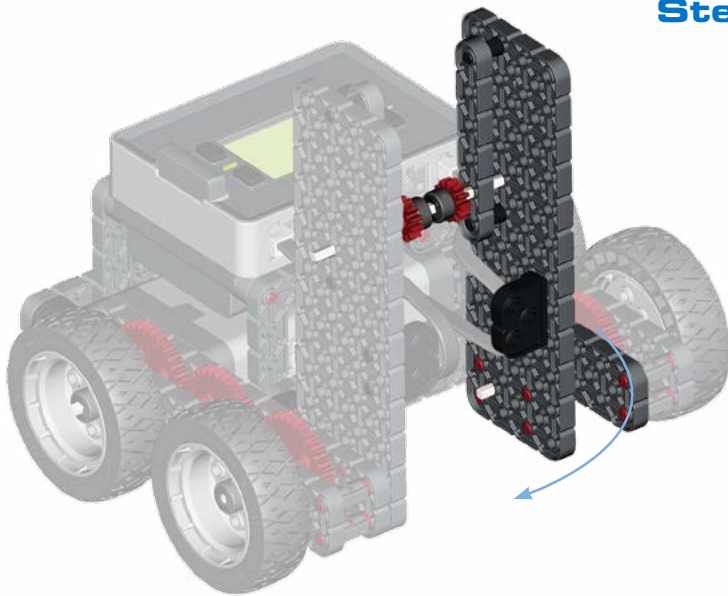




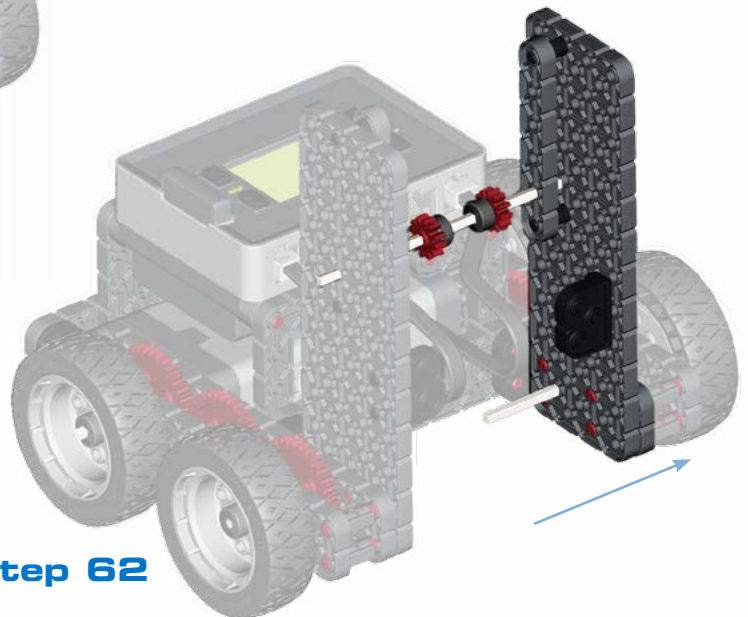
From Step 52

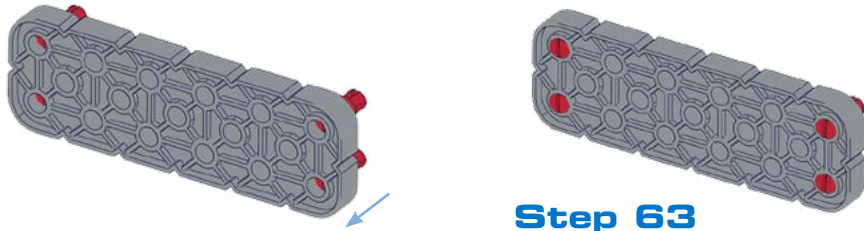
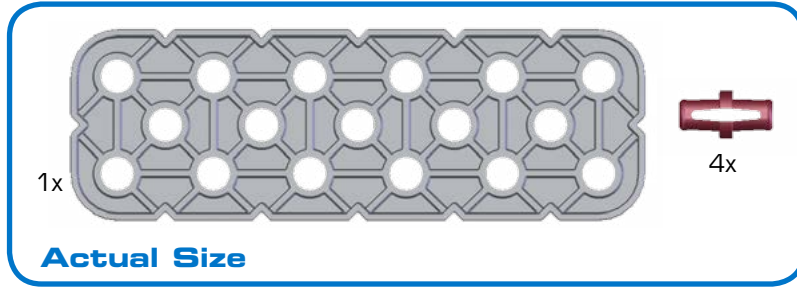
From Step 60

Step 61

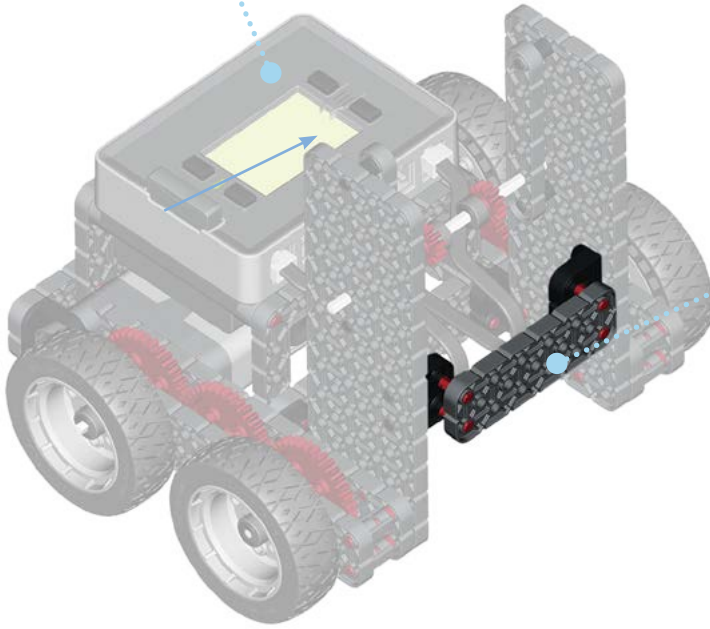


Step 62

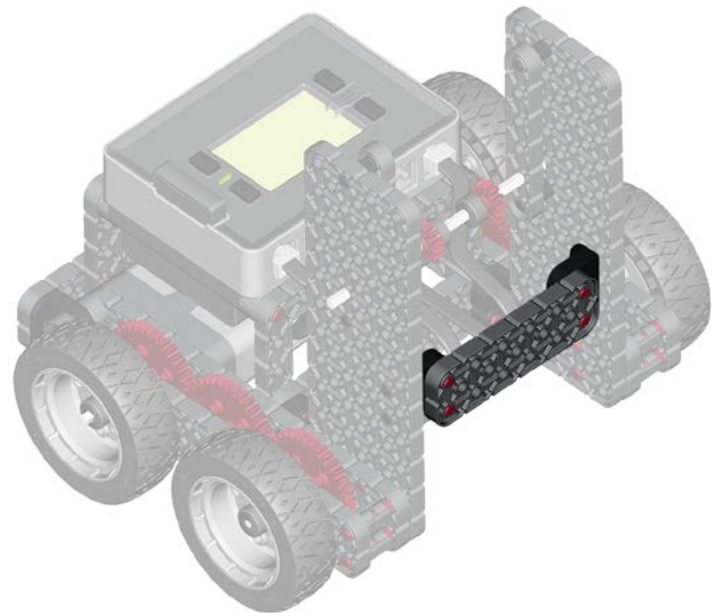




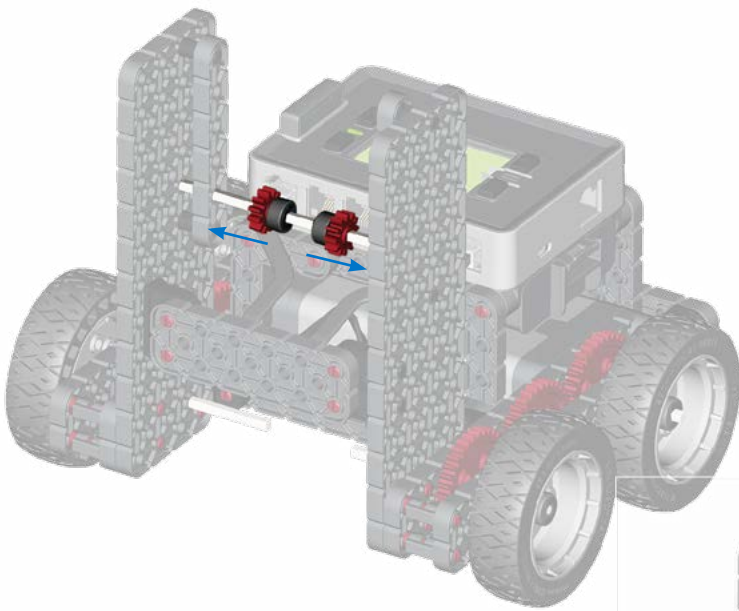
From Step 62:



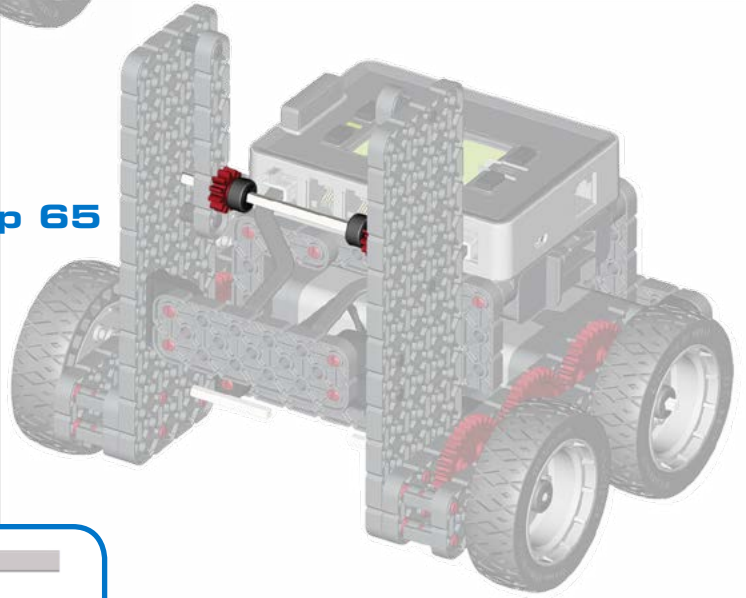
From Step 63



Step 64



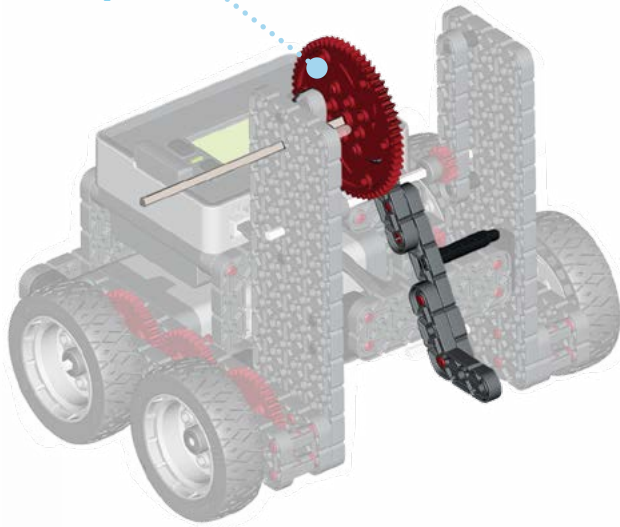
Step 65



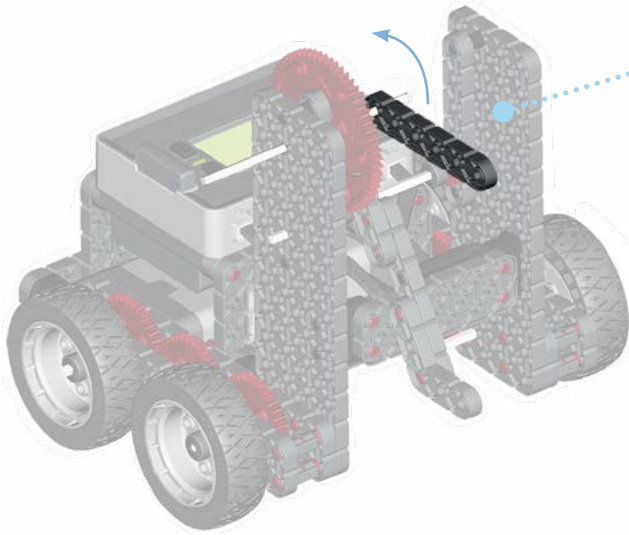
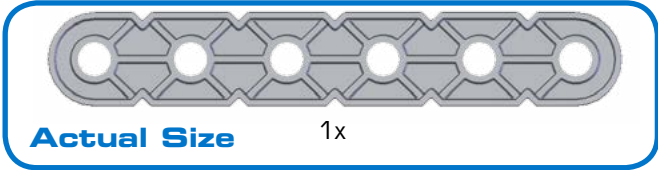
Actual Size

1x

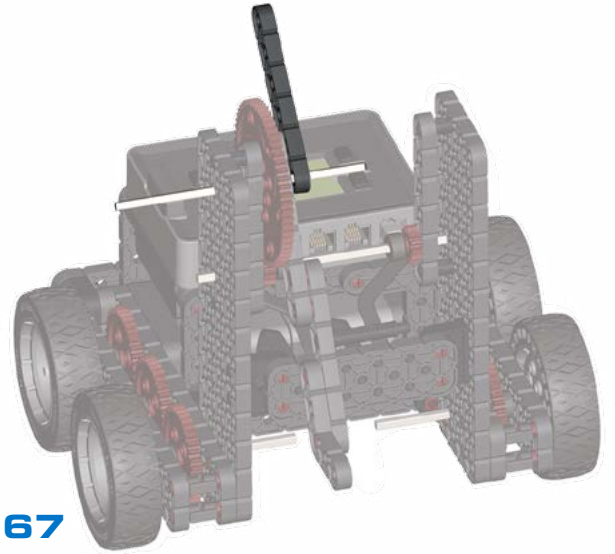
From Step 55



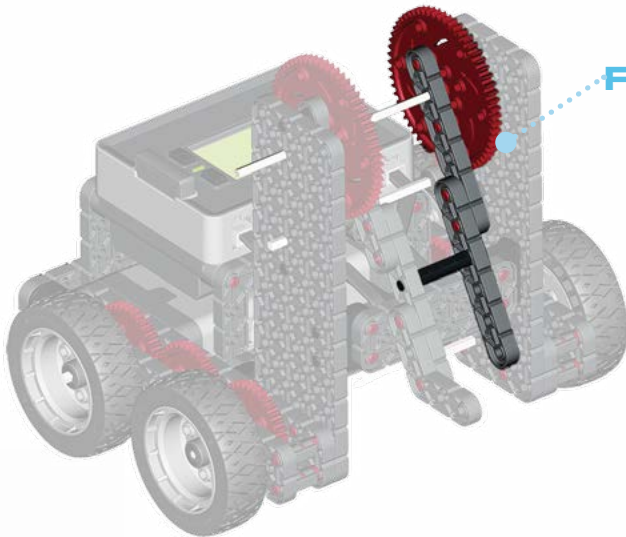
Step 66



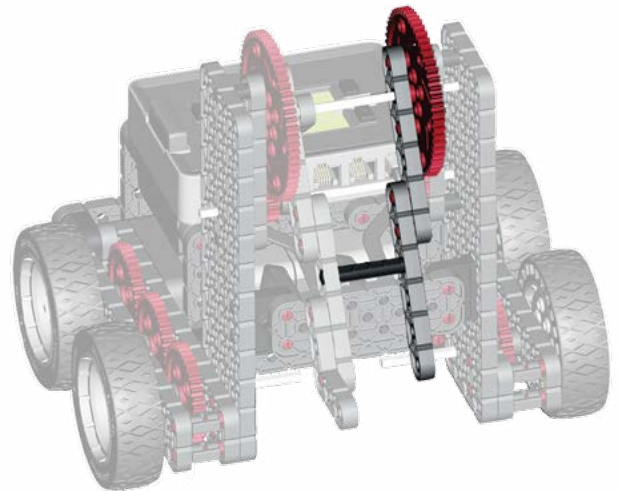
From Step 66



Step 67

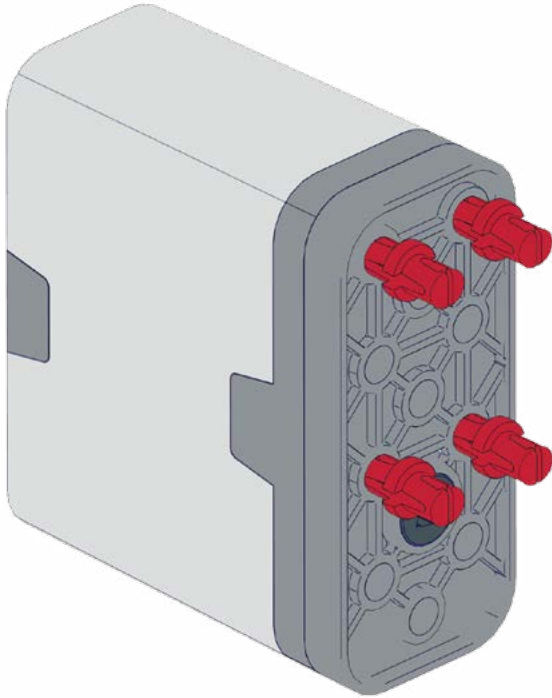
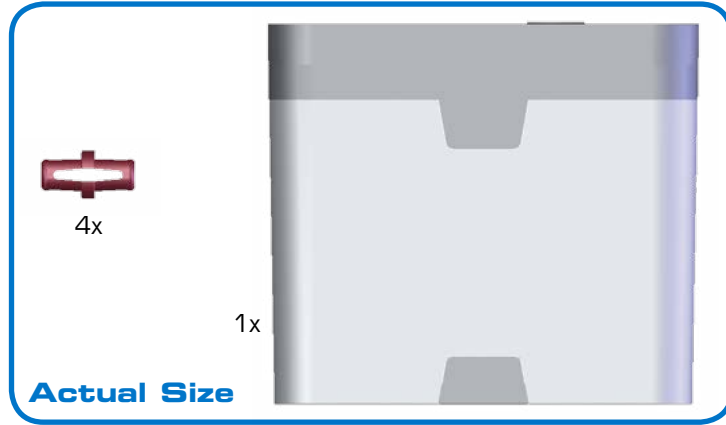


From Step 67

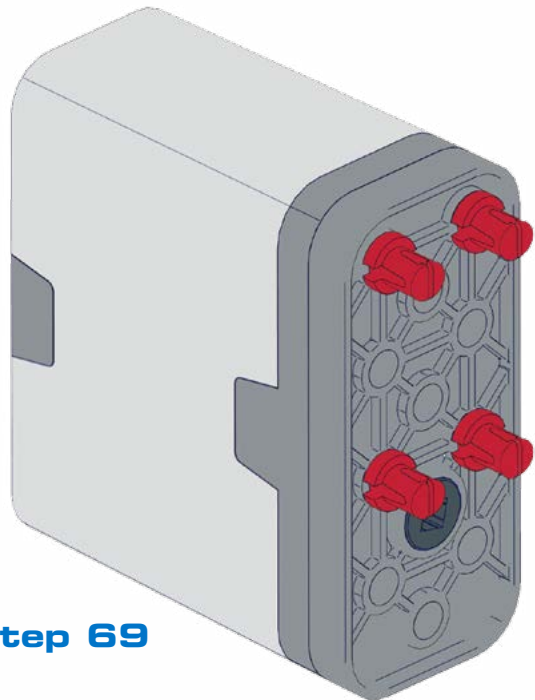


Step 68

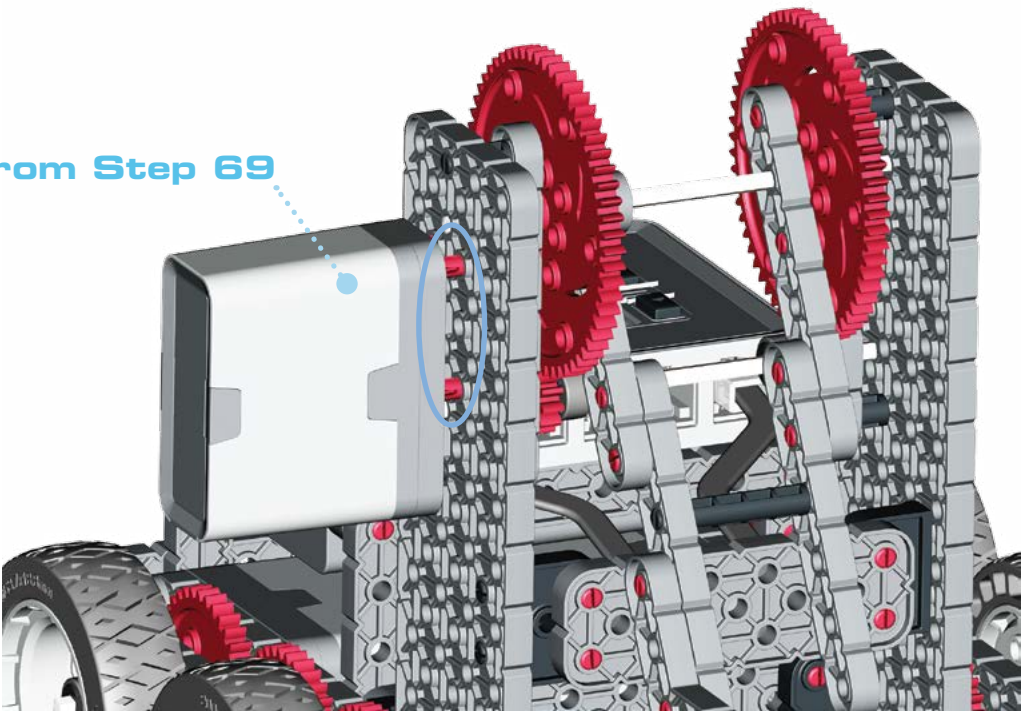




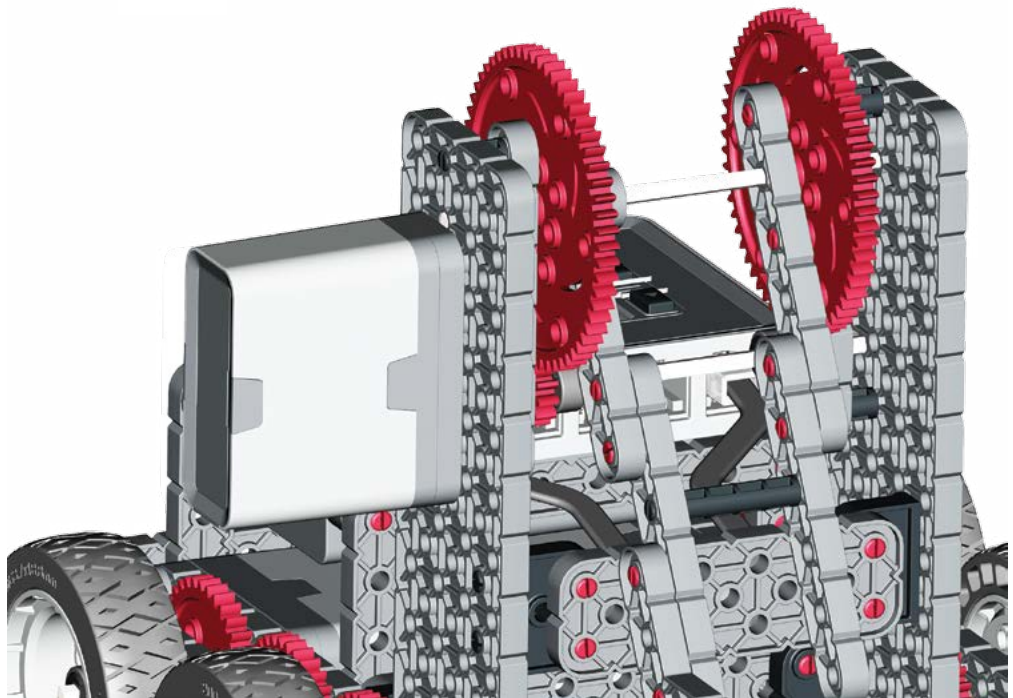
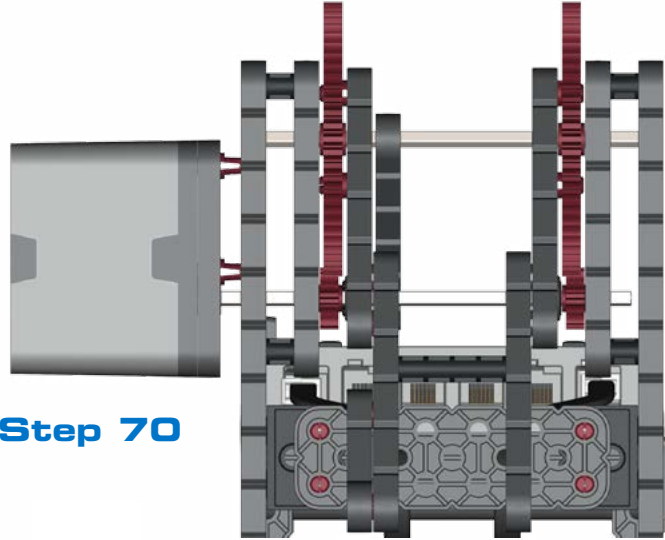
Step 69

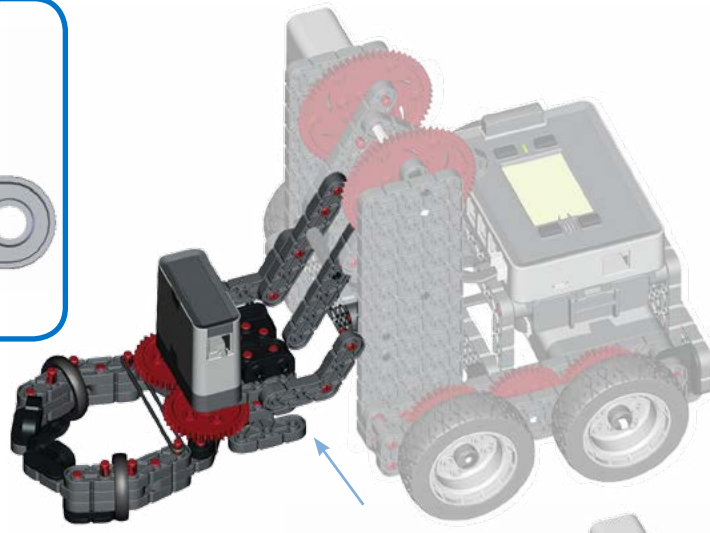
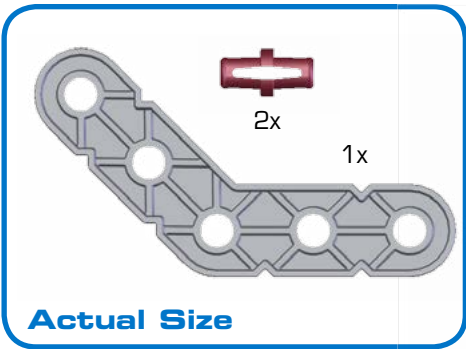


From Step 69

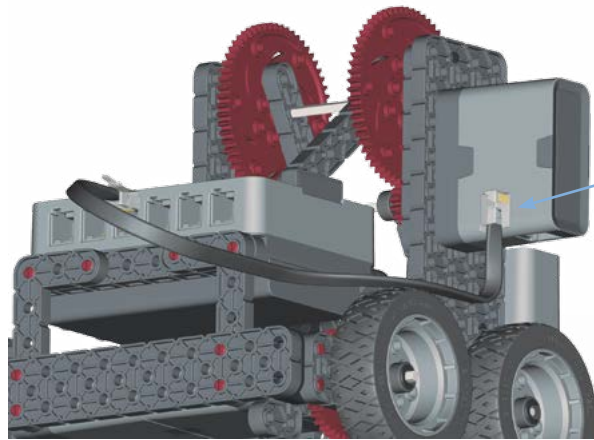
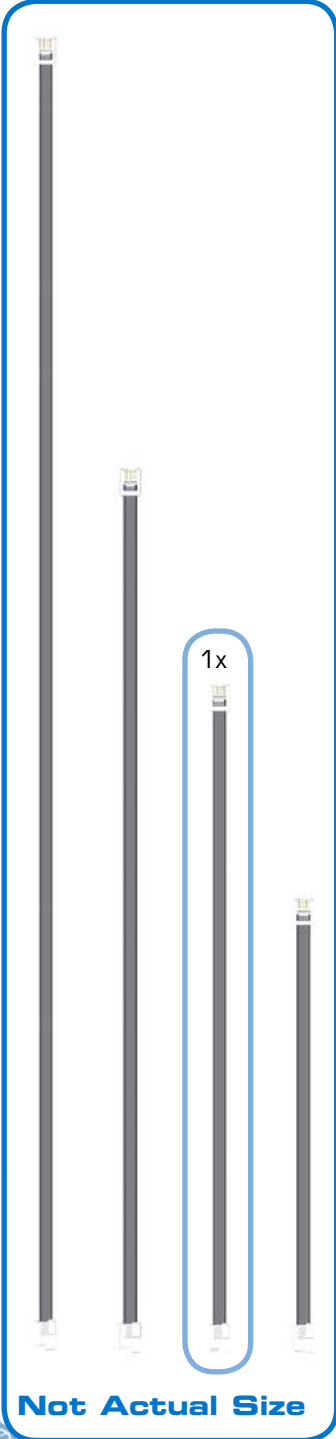


Step 70

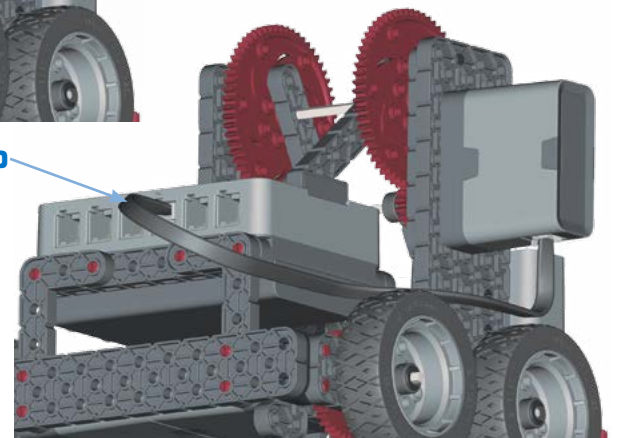
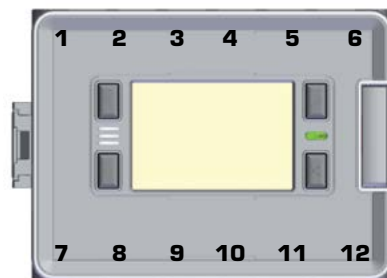




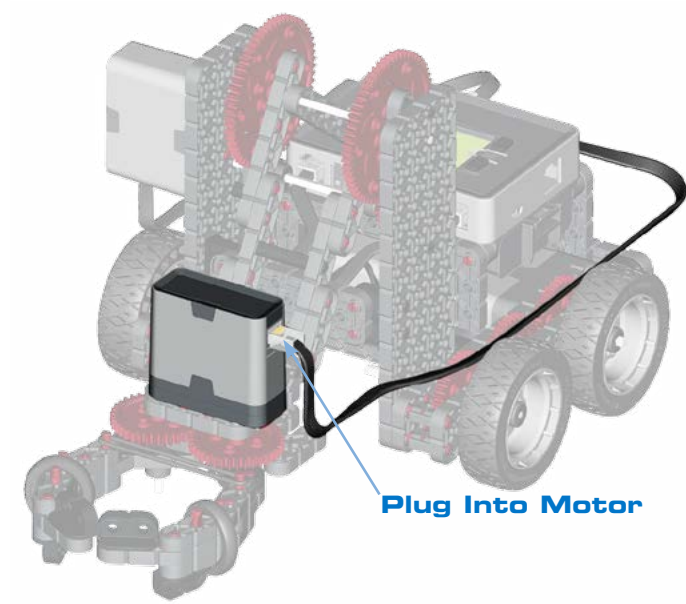
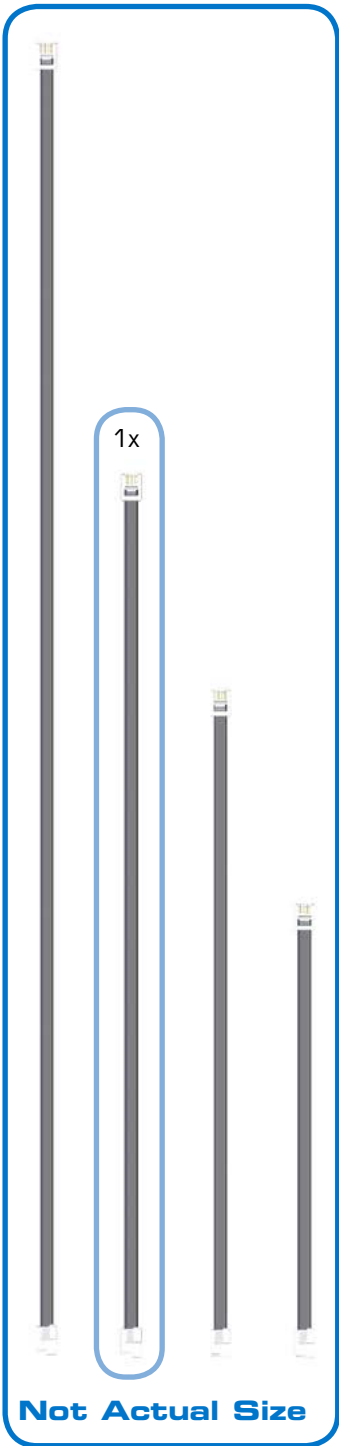
Step 71



Plug Into Port 10

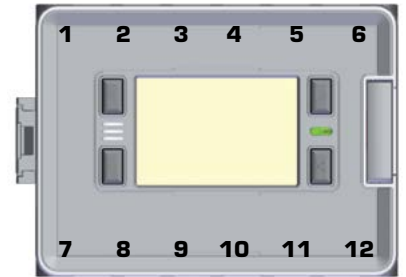
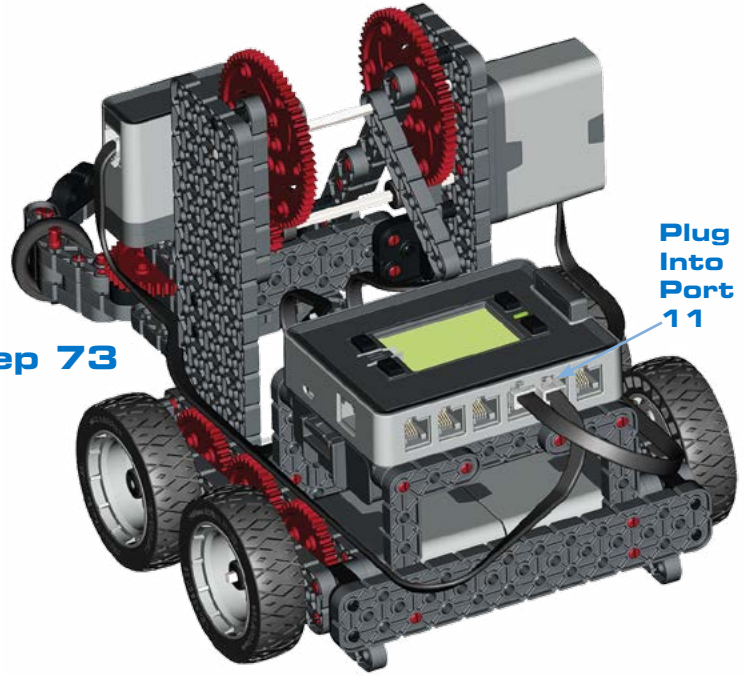
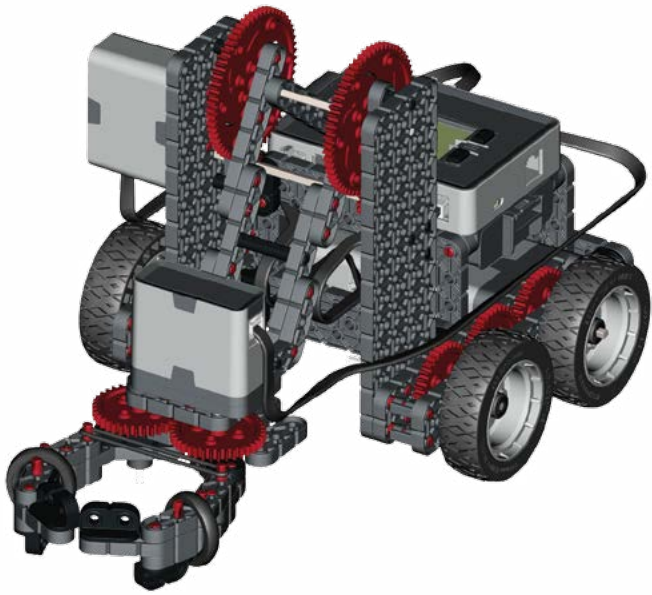


Step 72



Step 73

Plug Into Port 11



Open Claw

Close Claw

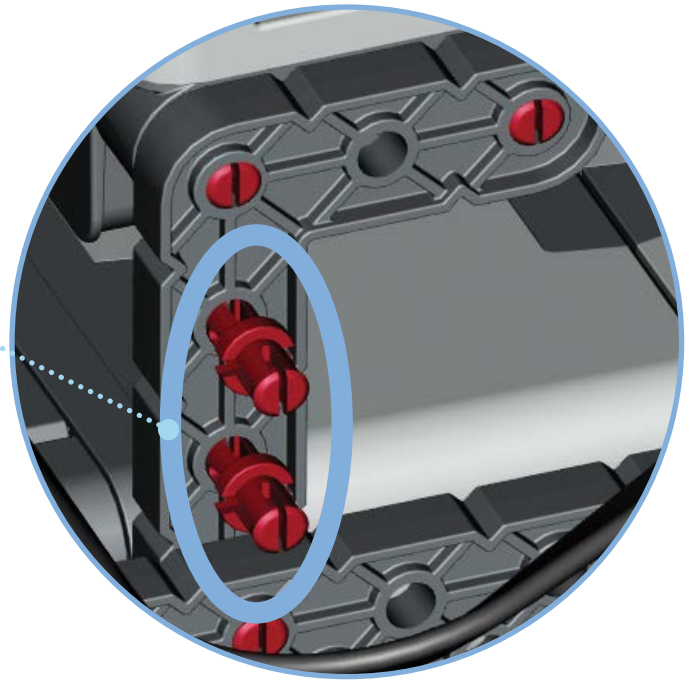
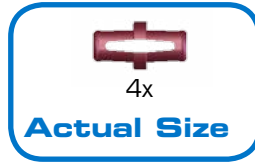


Raise Arm

Lower Arm

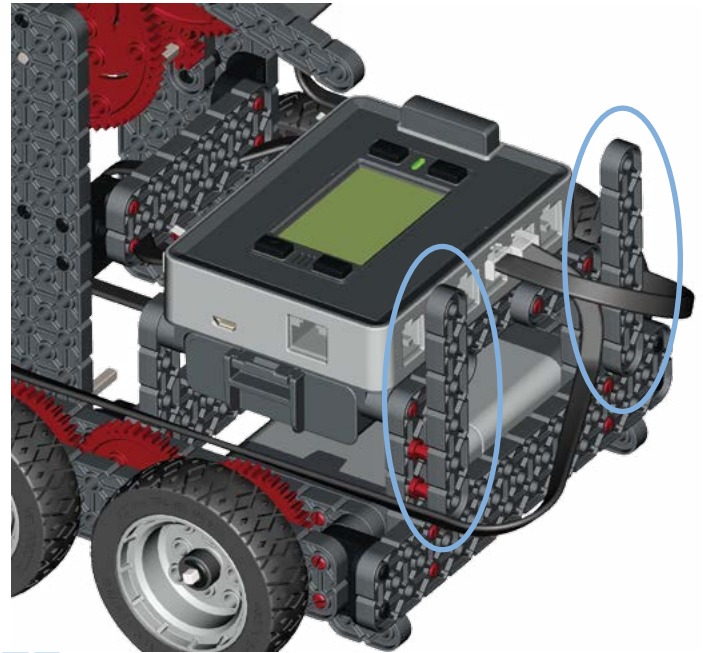
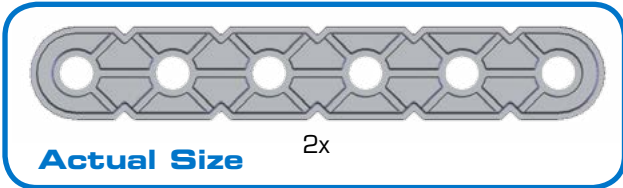
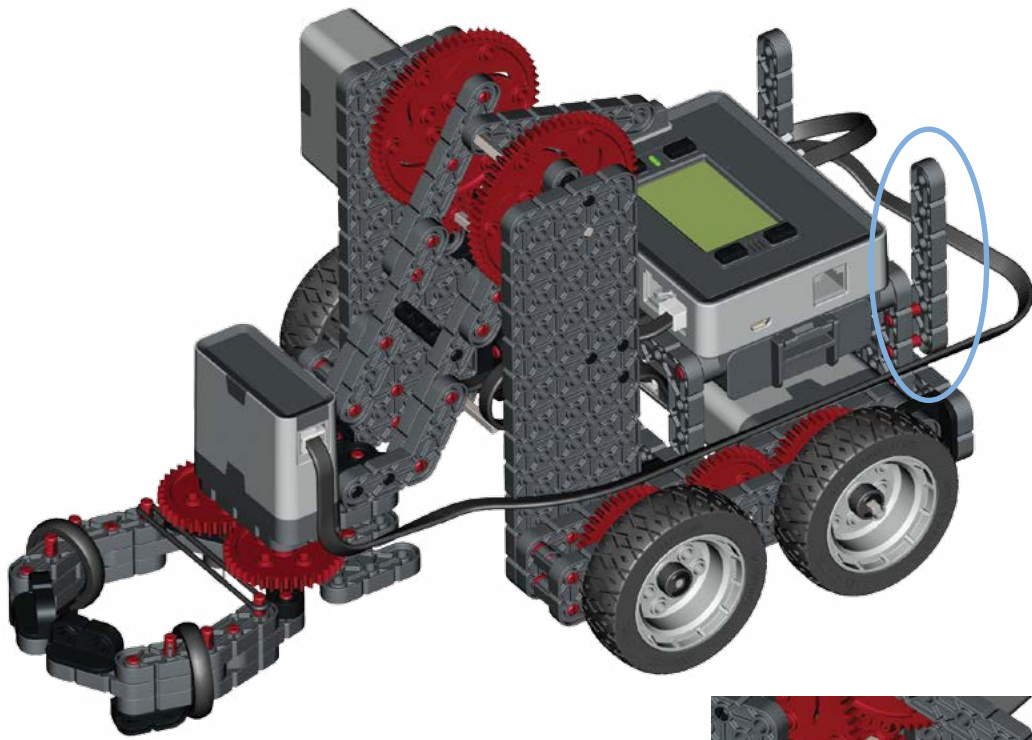
Robot Claw is now Ready to Run!

Part 4 Ball Holder



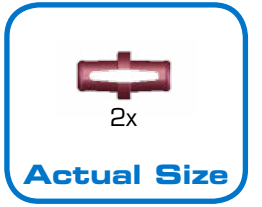
Step 74



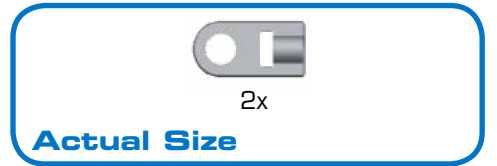
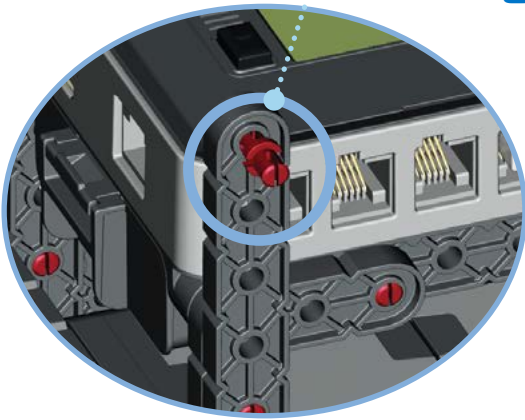


Step 75

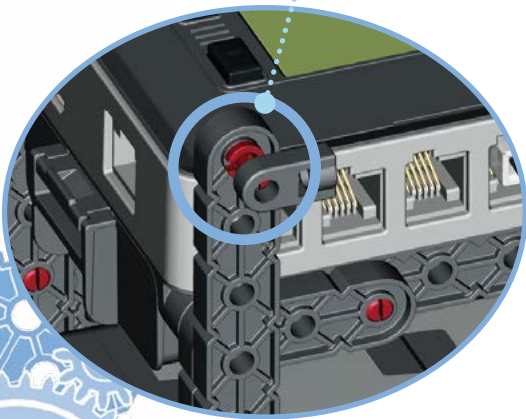


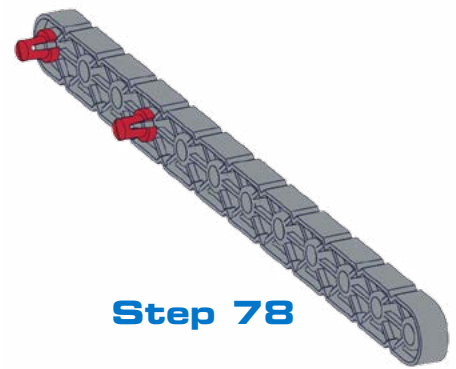
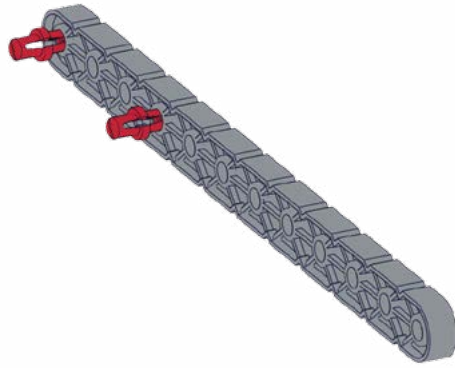
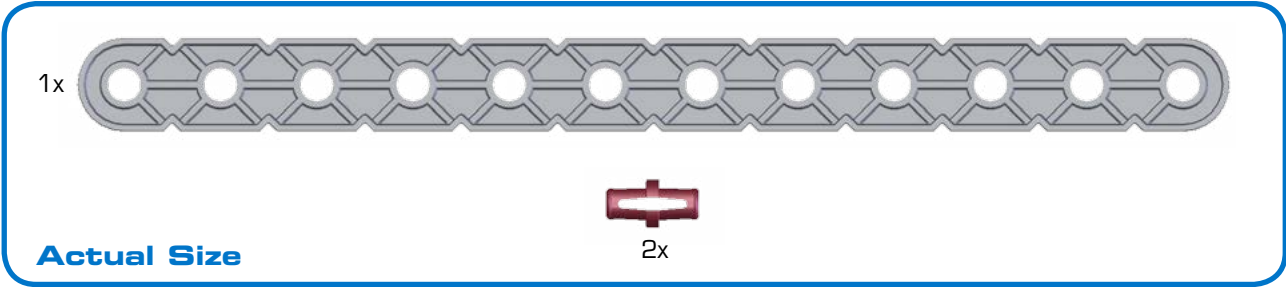


Step 76

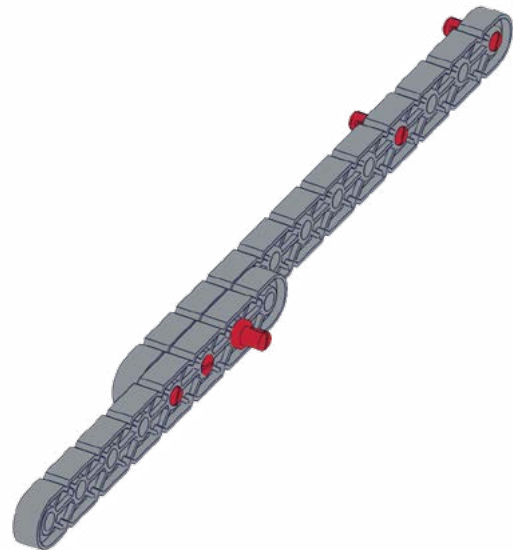
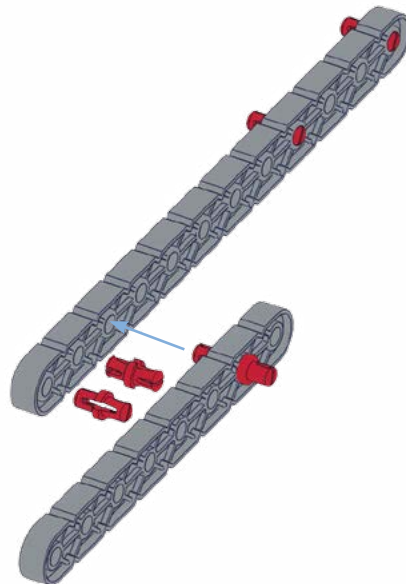
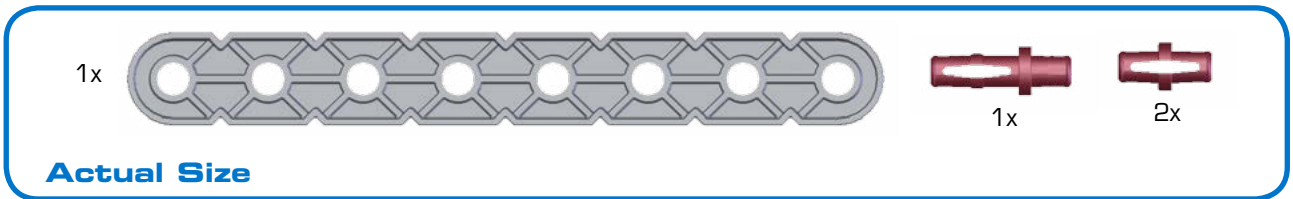


Step 77

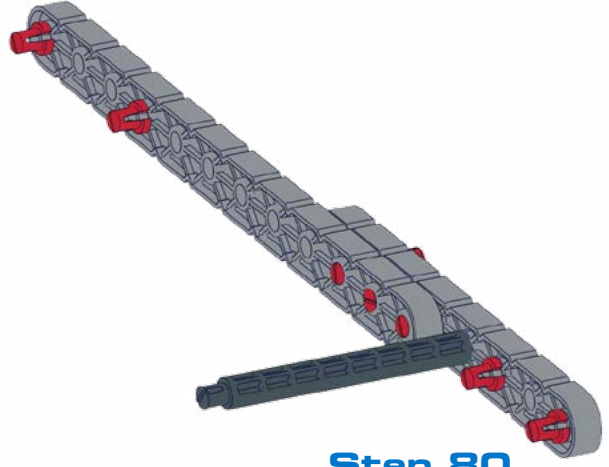
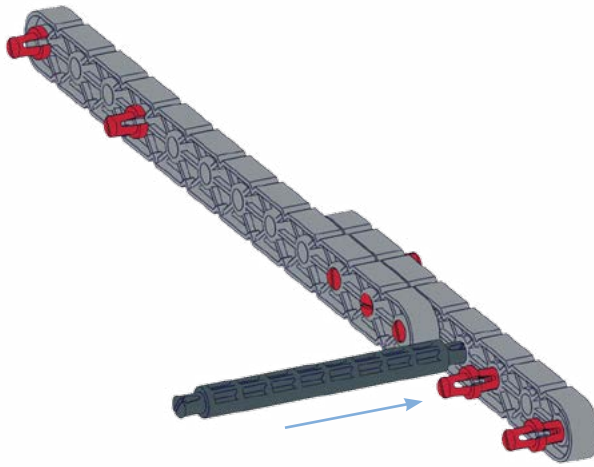
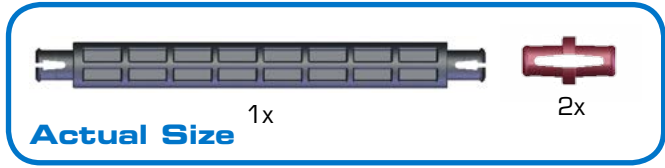




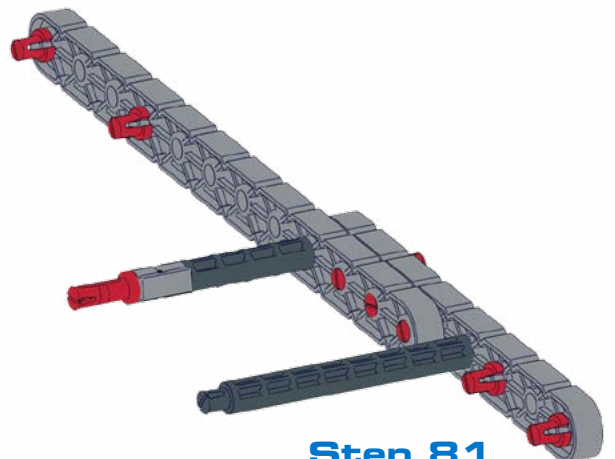
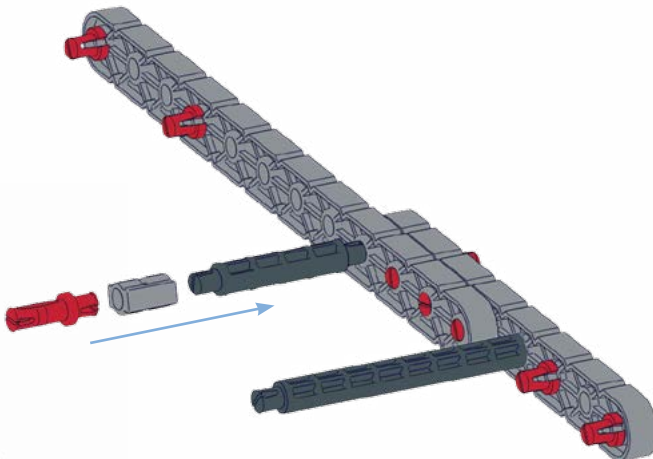
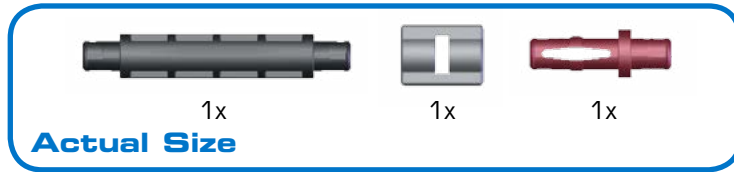
Step 78



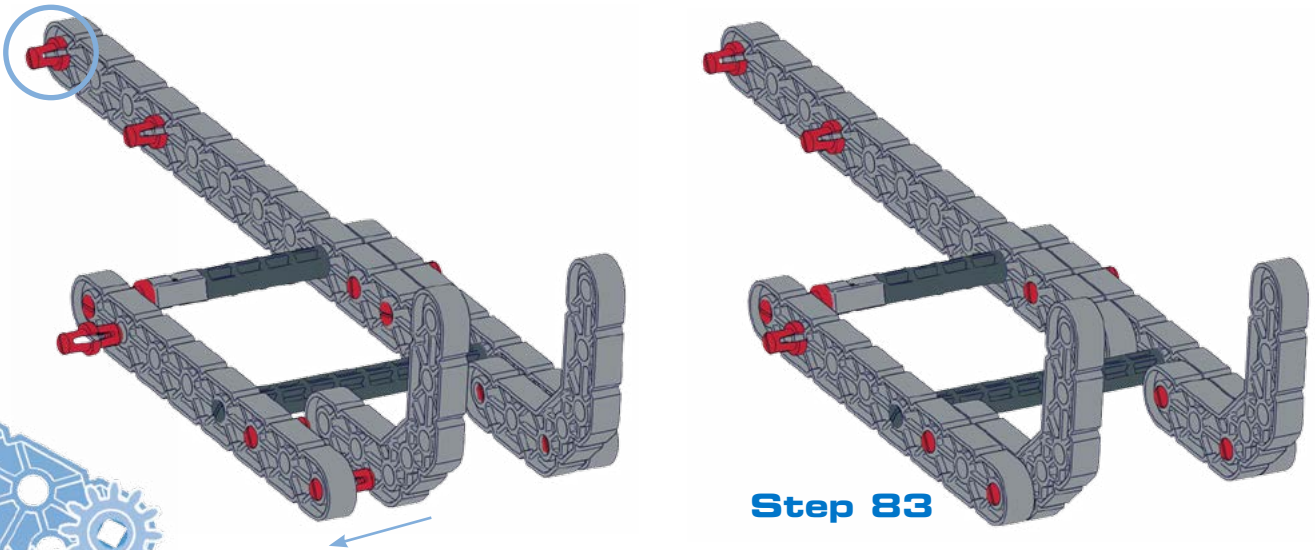
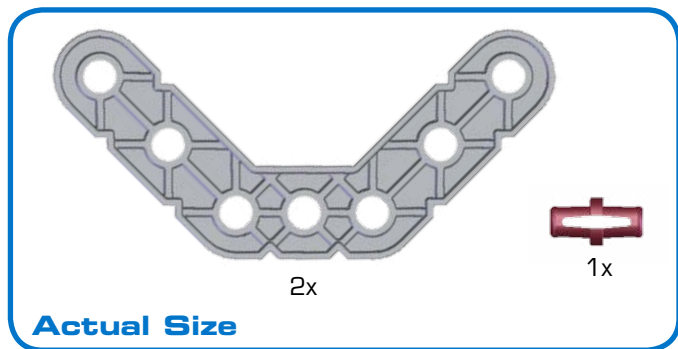
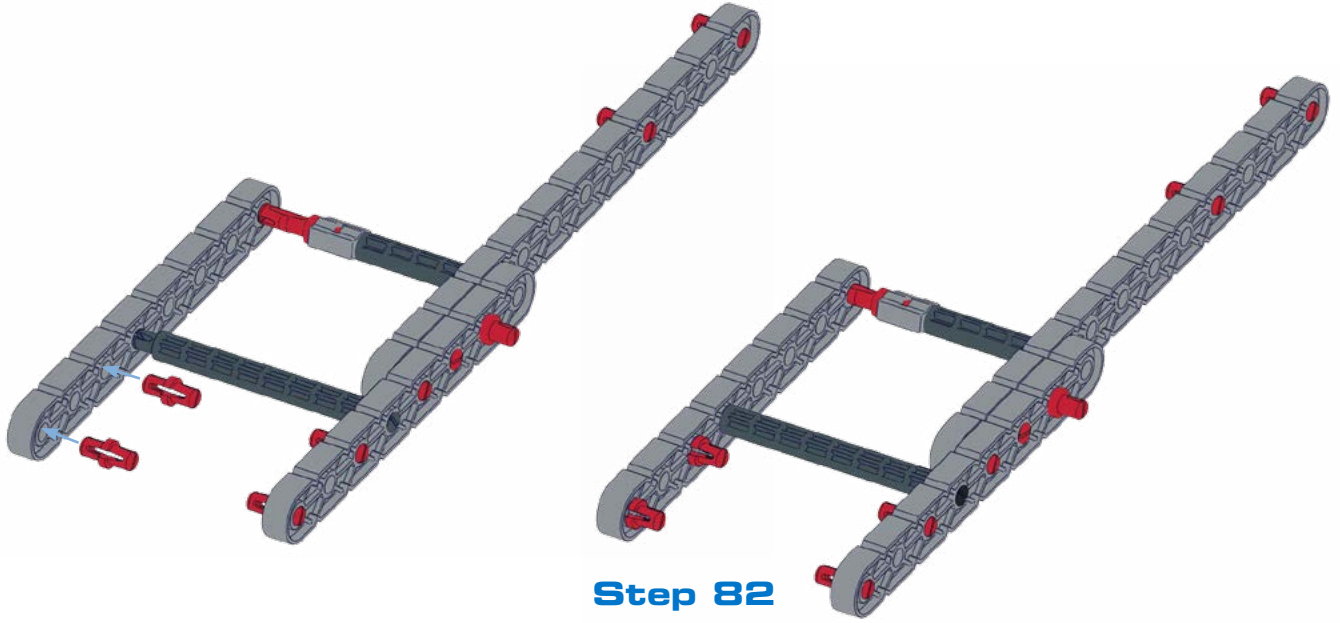
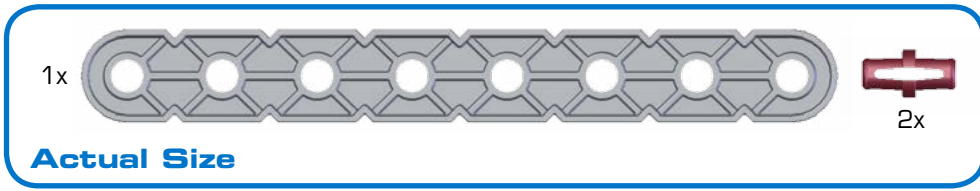
Step 79

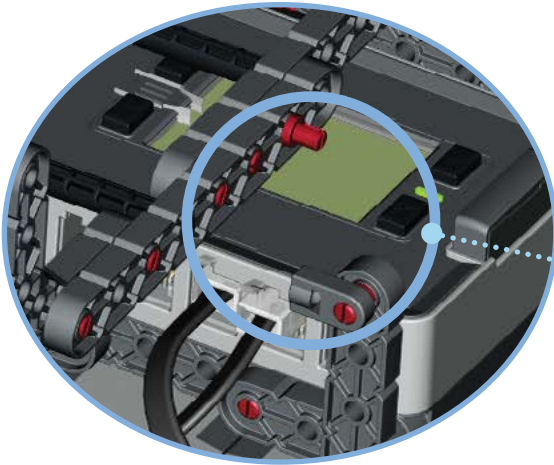
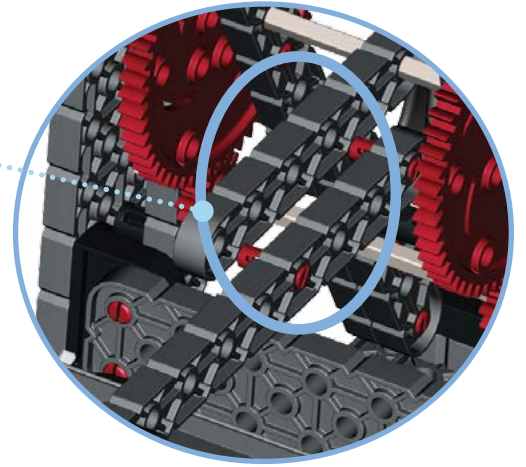
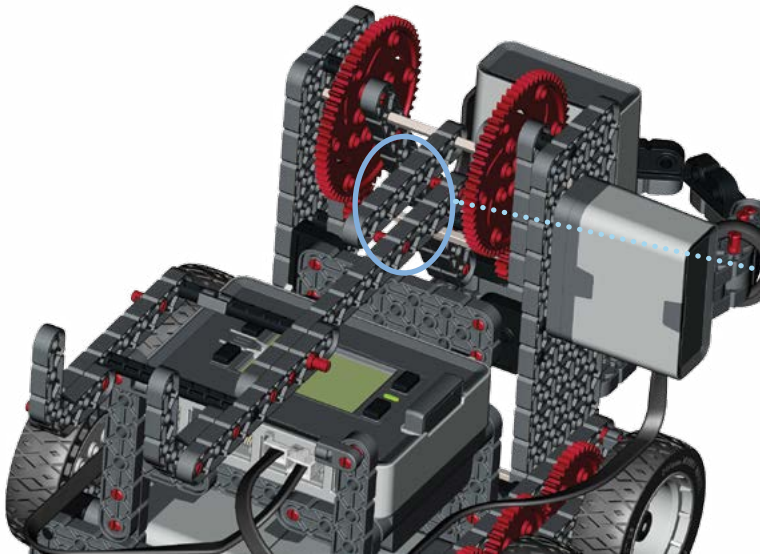


Step 80

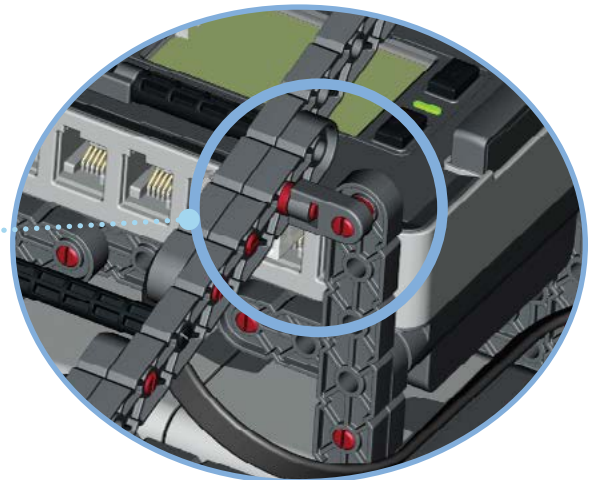


Step 81

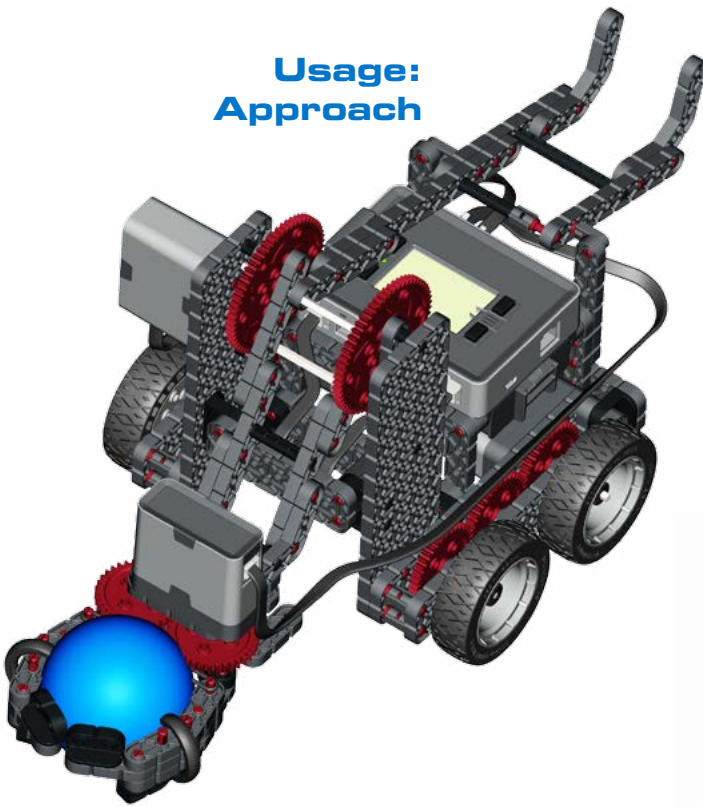




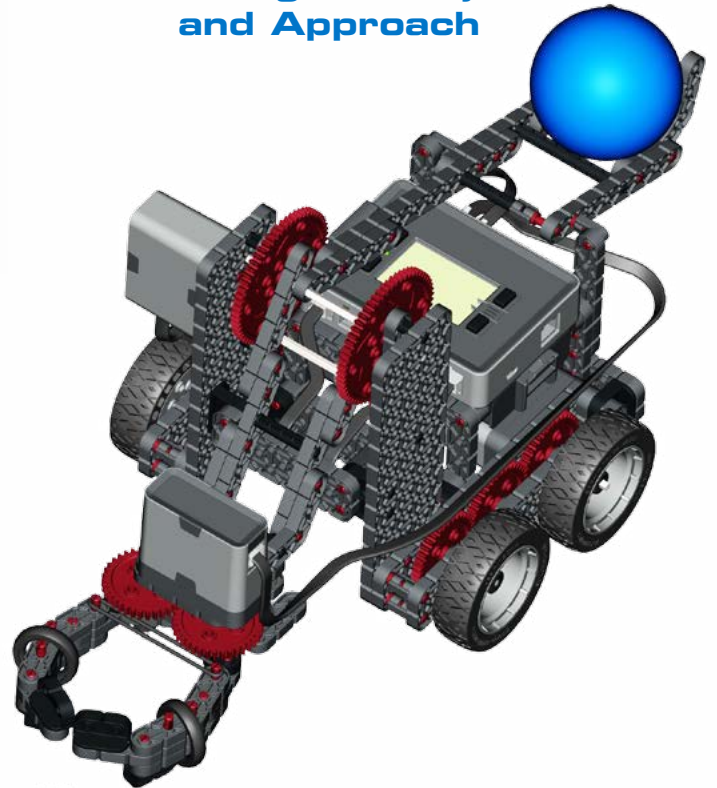
Step 84



Usage: Approach



Usage: Carry and Approach



Usage: Storage