# RENESAS

# R1Q2A7236ABB R1Q2A7218ABB R1Q2A7209ABB

## 72-Mbit QDR™II SRAM

2-word Burst

R10DS0164EJ0203 Rev. 2.03 Feb 01, 2019

## Description

The R1Q2A7236 is a 2,097,152-word by 36-bit, the R1Q2A7218 is a 4,194,304-word by 18-bit, and the R1Q2A7209 is a 8,388,608-word by 9-bit synchronous quad data rate static RAM fabricated with advanced CMOS technology using full CMOS six-transistor memory cell. It integrates unique synchronous peripheral circuitry and a burst counter. All input registers are controlled by an input clock pair (K and /K) and are latched on the positive edge of K and /K. These products are suitable for applications which require synchronous operation, high speed, low voltage, high density and wide bit configuration. These products are packaged in 165-pin plastic FBGA package.

## Features

#### **Power Supply**

• 1.8 V for core (V<sub>DD</sub>), 1.4 V to V<sub>DD</sub> for I/O (V<sub>DDQ</sub>)

#### Clock

- Fast clock cycle time for high bandwidth
- Two input clocks (K and /K) for precise DDR timing at clock rising edges only
- Two input clocks for output data (C and /C) to minimize clock skew and flight time mismatches
- Two output echo clocks (CQ and /CQ) simplify data capture in high-speed systems
- Clock-stop capability with  $\mu s$  restart

#### I/O

- · Separate independent read and write data ports with concurrent transactions
- 100% bus utilization DDR read and write operation
- · HSTL I/O
- User programmable output impedance
- · DLL/PLL circuitry for wide output data valid window and future frequency scaling

#### Function

- · Two-tick burst for low DDR transaction size
- · Internally self-timed write control
- Simple control logic for easy depth expansion
- JTAG 1149.1 compatible test access port

#### Package

- 165 FBGA package (13 x 15 x 1.4 mm)
- RoHS Compliance Level = 6/6



## Part Number Definition

Column No.	0	1	2	3	4	5	6	7	8	9	10	11	-	12	13	14	15	16
Example	R	1	Q	2	A	7	2	1	8	Α	В	В	-	4	0	I	В	1
Example	The above part number is just example for 72M QDRII B2 x18 250MHz, 13x15mm PKG, Pb-free part.																	

No.	-	Comments	No.	-	Comments
0-1	R1	Renesas Memory Prefix	9	А	2nd Generation
	Q2	QDR II B2 <sup>[*1]</sup> (L15) <sup>[*2]</sup>	10-11	BB	PKG = BGA 13x15 mm
	Q3	QDR II B4 (L15)		40	Frequency = 250MHz
	Q4	DDR II B2 (L15)		33	Frequency = 300MHz
	QA	QDR II+ B4 L25	12-13	25	Frequency = 400MHz
2-3	QB	DDR II+ B2 L25		20	Frequency = 500MHz
	QD	QDR II+ B4 L25 w/ ODT <sup>[*3]</sup>		19	Frequency = 533MHz
	QE	DDR II+ B2 L25 w/ ODT	14	I	Industrial temp.
	QG	QDR II+ B2 L20	14	I	$T_a$ range = -40°C to 85°C
	QH	DDR II+ B2 L20	15	В	Pb-free and Tray
4	А	V <sub>DD</sub> = 1.8 V		0 to 9,	
5-6	72	Density = 72Mb	16	A to Z	Renesas internal use
	09	Data width = 9bit		or None	
7-8	18	Data width = 18bit			
	36	Data width = 36bit			

**Notes[\*] 1.** B=Burst length (B2: Burst length=2, B4: Burst length=4)

- 2. L=Read Latency (L15: Read Latency = 1.5 cycle, L20: 2.0 cycle, L25: 2.5 cycle)
- **3.** ODT=On Die Termination

## 72M QDR/DDR SRAM (R1Q\*A72 Series) Lineup

Renesas supports or plans to support the parts listed below.

	Product	Burst	Latency	ODT	Organi-	Frequency (max) (MHz)	533	500	400	300	250			
No	Туре	Length	(Cycle)	ODT	zation	Cycle Time (min) (ns)	1.875	2.00	2.50	3.30	4.00			
1					x 9	R1Q2A7209ABB-yy								
2		B2			x18	R1Q2A7218ABB-yy					-40			
3	QDRII				x36	R1Q2A7236ABB-yy								
4		B4	1.5	No	x18	R1Q3A7218ABB-yy				-3	33			
5		D4			x36	R1Q3A7236ABB-yy				 	.5			
6	DDRII	B2						x18	R1Q4A7218ABB-yy				-3	33
7	DDIAI	52			x36	R1Q4A7236ABB-yy					.0			
8	QDRII+	B4			x18	R1QAA7218ABB-yy	-19	-20						
9	QDI	5.		No	x36	R1QAA7236ABB-yy	10			•				
10	DDRII+	B2		110	x18	R1QBA7218ABB-yy	-19		-2	0				
11			2.5		x36	R1QBA7236ABB-yy			_	•				
12	QDRII+	B4	2.0		x18	R1QDA7218ABB-yy	-19		-2	0				
13				Yes	x36	R1QDA7236ABB-yy				-				
14	DDRII+	B2			x18	R1QEA7218ABB-yy	-19		-2	0				
15					x36	R1QEA7236ABB-yy			-	•				
16	QDRII+	B4			x18	R1QGA7218ABB-yy				-25				
17	Q2.00	51	2.0	No	x36	R1QGA7236ABB-yy				20				
18	DDRII+	B2	2.0		x18	R1QHA7218ABB-yy				-25				
19	55.00	52			x36	R1QHA7236ABB-yy			20					

**Notes 1.** "yy" represents the speed bin. "R1QDA7236ABB-20" can operate at 500 MHz(max) of frequency, for example.

2. The part which is not listed above is not supported, as of the day when this datasheet was issued, in spite of the existence of the part number or datasheet.

## Pin Arrangement

	1	2	3	4	5	6	7	8	9	10	11
Α	/CQ	NC	SA	/W	/BW2	/K	/BW1	/R	SA	NC	CQ
в	Q27	Q18	D18	SA	/BW3	К	/BW0	SA	D17	Q17	Q8
С	D27	Q28	D19	Vss	SA	SA	SA	Vss	D16	Q7	D8
D	D28	D20	Q19	Vss	V <sub>SS</sub>	Vss	Vss	V <sub>SS</sub>	Q16	D15	D7
Е	Q29	D29	Q20	Vddq	Vss	Vss	Vss	Vddq	Q15	D6	Q6
F	Q30	Q21	D21	Vddq	V <sub>DD</sub>	Vss	Vdd	Vddq	D14	Q14	Q5
G	D30	D22	Q22	Vddq	Vdd	Vss	Vdd	Vddq	Q13	D13	D5
н	/DOFF	$V_{REF}$	Vddq	Vddq	V <sub>DD</sub>	Vss	Vdd	Vddq	Vddq	Vref	ZQ
J	D31	Q31	D23	Vddq	V <sub>DD</sub>	Vss	Vdd	Vddq	D12	Q4	D4
κ	Q32	D32	Q23	Vddq	Vdd	Vss	Vdd	Vddq	Q12	D3	Q3
L	Q33	Q24	D24	Vddq	Vss	Vss	Vss	Vddq	D11	Q11	Q2
М	D33	Q34	D25	Vss	Vss	Vss	Vss	Vss	D10	Q1	D2
Ν	D34	D26	Q25	Vss	SA	SA	SA	Vss	Q10	D9	D1
Ρ	Q35	D35	Q26	SA	SA	С	SA	SA	Q9	D0	Q0
R	TDO	ТСК	SA	SA	SA	/C	SA	SA	SA	TMS	TDI

## R1Q2A7236 series (Top View)

**Notes 1.** Address expansion order for future higher density SRAMs:  $10A \rightarrow 2A \rightarrow 7A \rightarrow 5B$ .

2. NC pins can be left floating or connected to 0V  $\sim$  V\_{DDQ.}

	1	2	3	4	5	6	7	8	9	10	11
Α	/CQ	NC	SA	/W	/BW1	/K	NC	/R	SA	SA	CQ
в	NC	Q9	D9	SA	NC	К	/BW0	SA	NC	NC	Q8
С	NC	NC	D10	Vss	SA	SA	SA	Vss	NC	Q7	D8
D	NC	D11	Q10	$V_{SS}$	$V_{SS}$	Vss	V <sub>SS</sub>	$V_{SS}$	NC	NC	D7
Е	NC	NC	Q11	Vddq	Vss	Vss	Vss	Vddq	NC	D6	Q6
F	NC	Q12	D12	Vddq	V <sub>DD</sub>	Vss	Vdd	Vddq	NC	NC	Q5
G	NC	D13	Q13	$V_{\text{DDQ}}$	$V_{\text{DD}}$	V <sub>SS</sub>	$V_{\text{DD}}$	$V_{\text{DDQ}}$	NC	NC	D5
н	/DOFF	$V_{REF}$	Vddq	Vddq	Vdd	Vss	Vdd	Vddq	Vddq	VREF	ZQ
J	NC	NC	D14	Vddq	$V_{\text{DD}}$	Vss	$V_{\text{DD}}$	Vddq	NC	Q4	D4
к	NC	NC	Q14	Vddq	V <sub>DD</sub>	Vss	Vdd	Vddq	NC	D3	Q3
L	NC	Q15	D15	Vddq	Vss	Vss	Vss	Vddq	NC	NC	Q2
М	NC	NC	D16	Vss	Vss	Vss	Vss	Vss	NC	Q1	D2
Ν	NC	D17	Q16	Vss	SA	SA	SA	Vss	NC	NC	D1
Ρ	NC	NC	Q17	SA	SA	С	SA	SA	NC	D0	Q0
R	TDO	TCK	SA	SA	SA	/C	SA	SA	SA	TMS	TDI

## R1Q2A7218 series (Top View)

**Notes 1.** Address expansion order for future higher density SRAMs:  $10A \rightarrow 2A \rightarrow 7A \rightarrow 5B$ .

2. NC pins can be left floating or connected to 0V  $\sim$  V\_{DDQ.}

	1	2	3	4	5	6	7	8	9	10	11
Α	/CQ	SA	SA	/W	NC	/K	NC	/R	SA	SA	CQ
в	NC	NC	NC	SA	NC	К	/BW	SA	NC	NC	Q4
С	NC	NC	NC	Vss	SA	SA	SA	Vss	NC	NC	D4
D	NC	D5	NC	$V_{SS}$	$V_{SS}$	V <sub>SS</sub>	$V_{SS}$	V <sub>SS</sub>	NC	NC	NC
Е	NC	NC	Q5	Vddq	Vss	Vss	Vss	Vddq	NC	D3	Q3
F	NC	NC	NC	Vddq	V <sub>DD</sub>	Vss	Vdd	Vddq	NC	NC	NC
G	NC	D6	Q6	$V_{\text{DDQ}}$	$V_{\text{DD}}$	V <sub>SS</sub>	$V_{\text{DD}}$	$V_{\text{DDQ}}$	NC	NC	NC
н	/DOFF	$V_{REF}$	Vddq	Vddq	$V_{\text{DD}}$	Vss	Vdd	Vddq	Vddq	Vref	ZQ
J	NC	NC	NC	Vddq	$V_{\text{DD}}$	Vss	Vdd	Vddq	NC	Q2	D2
κ	NC	NC	NC	Vddq	Vdd	Vss	Vdd	Vddq	NC	NC	NC
L	NC	Q7	D7	Vddq	Vss	Vss	Vss	Vddq	NC	NC	Q1
М	NC	NC	NC	Vss	Vss	Vss	Vss	Vss	NC	NC	D1
Ν	NC	D8	NC	Vss	SA	SA	SA	Vss	NC	NC	NC
Ρ	NC	NC	Q8	SA	SA	С	SA	SA	NC	D0	Q0
R	TDO	ТСК	SA	SA	SA	/C	SA	SA	SA	TMS	TDI

## R1Q2A7209 series (Top View)

**Notes 1.** Address expansion order for future higher density SRAMs:  $10A \rightarrow 2A \rightarrow 7A \rightarrow 5B$ .

2. NC pins can be left floating or connected to 0V  $\sim$  V\_{DDQ.}

## **Pin Description**

Name	I/O type	Descriptions	Notes
SA	Input	Synchronous address inputs: These inputs are registered and must meet the setup and hold times around the rising edge of K. All transactions operate on a burst-of-four words (two clock periods of bus activity). These inputs are ignored when device is deselected.	
/R	Input	Synchronous read: When low, this input causes the address inputs to be registered and a READ cycle to be initiated. This input must meet setup and hold times around the rising edge of K, and is ignored on the subsequent rising edge of K.	
W	Input	Synchronous write: When low, this input causes the address inputs to be registered and a WRITE cycle to be initiated. This input must meet setup and hold times around the rising edge of K, and is ignored on the subsequent rising edge of K.	
/BWx	Input	Synchronous byte writes: When low, these inputs cause their respective byte to be registered and written during WRITE cycles. These signals are sampled on the same edge as the corresponding data and must meet setup and hold times around the rising edges of K and /K for each of the two rising edges comprising the WRITE cycle. See Byte Write Truth Table for signal to data relationship.	
K, /K	Input	Input clock: This input clock pair registers address and control inputs on the rising edge of K, and registers data on the rising edge of K and the rising edge of /K. /K is ideally 180 degrees out of phase with K. All synchronous inputs must meet setup and hold times around the clock rising edges. These balls cannot remain $V_{REF}$ level.	
C, /C	Input	Output clock: This clock pair provides a user-controlled means of tuning device output data. The rising edge of /C is used as the output timing reference for the first and third output data. The rising edge of C is used as the output timing reference for second and fourth output data. Ideally, /C is 180 degrees out of phase with C. C and /C may be tied high to force the use of K and /K as the output reference clocks instead of having to provide C and /C clocks. If tied high, C and /C must remain high and not to be toggled during device operation. These balls cannot remain $V_{REF}$ level.	1
/DOFF	Input	DLL/PLL disable: When low, this input causes the DLL/PLL to be bypassed for stable, low frequency operation.	
TMS TDI	Input	IEEE1149.1 test inputs: 1.8 V I/O levels. These balls may be left not connected if the JTAG function is not used in the circuit.	
ТСК	Input	IEEE1149.1 clock input: 1.8 V I/O levels. This ball must be tied to $V_{SS}$ if the JTAG function is not used in the circuit.	
ZQ	Input	Output impedance matching input: This input is used to tune the device outputs to the system data bus impedance. Q and CQ output impedance are set to $0.2 \times RQ$ , where RQ is a resistor from this ball to ground. This ball can be connected directly to V <sub>DDQ</sub> , which enables the minimum impedance mode. This ball cannot be connected directly to V <sub>SS</sub> or left unconnected.	

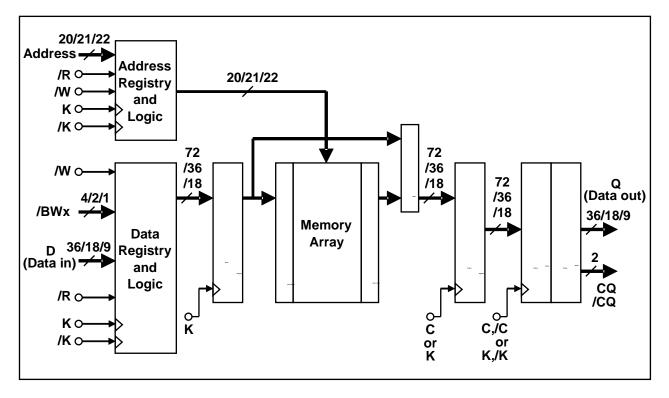
Name	I/O type	Descriptions	Notes
			NOLES
D0 to Dn	Input	Synchronous data inputs: Input data must meet setup and hold times	
		around the rising edges of K and /K during WRITE operations. See Pin Arrangement figures for ball site location of individual signals.	
		The x9 device uses D0~D8. D9~D35 should be treated as NC pin.	
		The x18 device uses D0~D07. D18~D35 should be treated as NC pin.	
		The x36 device uses D0~D35.	
CQ, /CQ	Output	Synchronous echo clock outputs: The edges of these outputs are tightly	
		matched to the synchronous data outputs and can be used as a data	
		valid indication. These signals run freely and do not stop when Q tri- states.	
TDO	Output	IEEE 1149.1 test output: 1.8 V I/O level.	
Q0 to Qn	Output	Synchronous data outputs: Output data is synchronized to the respective	
		C and /C, or to the respective K and /K if C and /C are tied high. This bus	
		operates in response to /R commands. See Pin Arrangement figures for	
		ball site location of individual signals.	
		The x9 device uses Q0~Q8. Q9~Q35 should be treated as NC pin.	
		The x18 device uses Q0~Q17. Q18~Q35 should be treated as NC pin.	
		The x36 device uses Q0~Q35.	
Vdd	Supply	Power supply: 1.8 V nominal. See DC Characteristics and Operating	2
		Conditions for range.	
Vddq	Supply	Power supply: Isolated output buffer supply. Nominally 1.5 V. See DC	2
		Characteristics and Operating Conditions for range.	
Vss	Supply	Power supply: Ground.	2
Vref	-	HSTL input reference voltage: Nominally $V_{DDQ}/2$ , but may be adjusted to	
		improve system noise margin. Provides a reference voltage for the HSTL input buffers.	
NC	-	No connect: These pins can be left floating or connected to 0V $\sim$ V <sub>DDQ</sub> .	

- Notes 1. R1Q2, R1Q3, R1Q4 series have C and /C pins. R1QA, R1QB, R1QD, R1QE, R1QG, R1QH series do not have C, /C pins. In the series, K and /K are used as the output reference clocks instead of C and /C. Therefore, hereafter, C and /C represent K and /K in this document.
  - 2. All power supply and ground balls must be connected for proper operation of the device



## **Block Diagram**

R1Q2A7236 / R1Q2A7218 / R1Q2A7209 series





## **General Description**

#### **Power-up and Initialization Sequence**

- V<sub>DD</sub> must be stable before K, /K clocks are applied.
- Recommended voltage application sequence :  $V_{SS} \rightarrow V_{DD} \rightarrow V_{DDQ} \& V_{REF} \rightarrow V_{IN}$ . (0 V to V<sub>DD</sub>, V<sub>DDQ</sub> < 200 ms)
- Apply  $V_{REF}$  after  $V_{DDQ}$  or at the same time as  $V_{DDQ}$ .
- Then execute either one of the following three sequences.
- 1. Single Clock Mode (C and /C tied high)
- Drive /DOFF high (/DOFF can be tied high from the start).
- Then provide stable clocks (K, /K) for at least 1024 cycles (II series) or 20 us (II+ series).

These meet the QDR common specification of 20 us.

When the operating frequency is less than 180 MHz, 2048 cycles are required (II series).

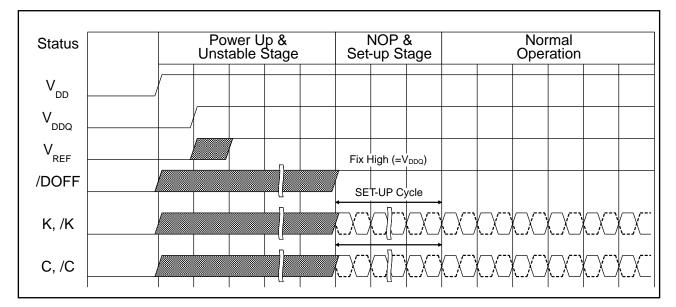
Status	Power Up & Unstable Stage		NOP & Set-up Stage	Normal Operation			
V <sub>DD</sub>							
V <sub>ddq</sub>							
V <sub>REF</sub>			Fix High (=V <sub>DDQ</sub> )				
/DOFF			SET-UP Cycle				
K, /K					<u>X</u> .		



- 2. Double Clock Mode (C and /C control outputs) (II series only)
  - Drive /DOFF high (/DOFF can be tied high from the start)
- Then provide stable clocks (K, /K, C, /C) for at least 1024 cycles.

This meets the QDR common specification of 20 us.

When the operating frequency is less than 180 MHz, 2048 cycles are required.



- 3. DLL/PLL Off Mode (/DOFF tied low)
- In the "NOP and setup stage", provide stable clocks (K, /K) for at least 1024 cycles (II series) or 20 us (II+ series). These meet the QDR common specification of 20 us.

#### **DLL/PLL Constraints**

- 1. DLL/PLL uses K clock as its synchronizing input. The input should have low phase jitter which is specified as  $t_{KC}$  var.
- 2. The lower end of the frequency at which the DLL/PLL can operate is 120 MHz.

(Please refer to AC Characteristics table for detail.)

3. When the operating frequency is changed or /DOFF level is changed, setup cycles are required again.

#### Programmable Output Impedance

1. Output buffer impedance can be programmed by terminating the ZQ ball to V<sub>SS</sub> through a precision resistor (RQ). The value of RQ is five times the output impedance desired. The allowable range of RQ to guarantee impedance matching with a tolerance of 15% is 250  $\Omega$  typical. The total external capacitance of ZQ ball must be less than 7.5 pF.



## **K Truth Table**

Operation	K	/LD	R-/W	D or Q					
Write Cycle : Load		×	L	Data in					
address, input write data on consecutive K and /K	1			Input data		D(A+0)	D(A+1)		
rising edges				Inp	out clock	K(t) ↑	/K(t) ↑		
				Data o	ut				
Read Cycle : Load				Output data		Q(A+0)	Q(A+1)		
address, output read data on consecutive C and /C	Ť	L	×	Input	RL <sup>*7</sup> = 1.5	/C(t+1) ↑	C(t+2) ↑		
rising edges				clock	RL = 2.0	C(t+2) ↑	/C(t+2) ↑		
				for Q	RL = 2.5	/C(t+2) ↑	C(t+3) ↑		
NOP (No operation)	↑	Н	Н	$D = \times$ or $Q = High-Z$					
Standby (Clock stopped)	Stopped	×	×	Previous state					

**Notes 1.** H: high level, L: low level, ×: don't care, ↑: rising edge.

- **2.** Data inputs are registered at K and /K rising edges. Data outputs are delivered at C and /C rising edges, except if C and /C are high, then data outputs are delivered at K and /K rising edges.
- **3.** /R and /W must meet setup/hold times around the rising edges (low to high) of K and are registered at the rising edge of K.
- 4. This device contains circuitry that will ensure the outputs will be in High-Z during power-up.
- 5. Refer to state diagram and timing diagrams for clarification.
- 6. When clocks are stopped, the following cases are recommended; the case of K = low, /K = high, C = low and /C = high, or the case of K = high, /K = low, C = high and /C = low. This condition is not essential, but permits most rapid restart by overcoming transmission line charging symmetrically.
- **7.** RL = Read Latency (unit = cycle).



Operation	К	/К	/BW0	/BW1	/BW2	/BW3
Write D0 to D35	↑	-	L	L	L	L
	-	<b>↑</b>	L	L	L	L
Write D0 to D8	<u>↑</u>	-	L	Н	Н	Н
	-	<b>↑</b>	L	Н	Н	Н
Write D9 to D17	<u>↑</u>	-	Н	L	Н	Н
	-	↑	Н	L	Н	Н
Write D18 to D26	↑	-	Н	Н	L	Н
	-	↑	Н	Н	L	Н
Write D27 to D35	<u>↑</u>	-	Н	Н	Н	L
	-	↑	Н	Н	Н	L
Write nothing	<u>↑</u>	-	Н	Н	Н	Н
Ŭ	-	<b>↑</b>	Н	Н	Н	Н

## **Byte Write Truth Table (x36)**

**Notes 1.** H: high level, L: low level, ↑: rising edge.

2. Assumes a WRITE cycle was initiated. /BWx can be altered for any portion of the BURST WRITE operation provided that the setup and hold requirements are satisfied.

## Byte Write Truth Table (x18)

Operation	К	/K	/BW0	/BW1
Write D0 to D17	↑ (	-	L	L
	-	↑ (	L	L
Write D0 to D8	↑ (	-	L	Н
	-	↑ (	L	Н
Write D9 to D17	↑ (	-	Н	L
	-	↑	Н	L
Write nothing	1	-	Н	Н
	-	↑	Н	Н

**Notes 1.** H: high level, L: low level, ↑: rising edge.

2. Assumes a WRITE cycle was initiated. /BWx can be altered for any portion of the BURST WRITE operation provided that the setup and hold requirements are satisfied.

## Byte Write Truth Table (x9)

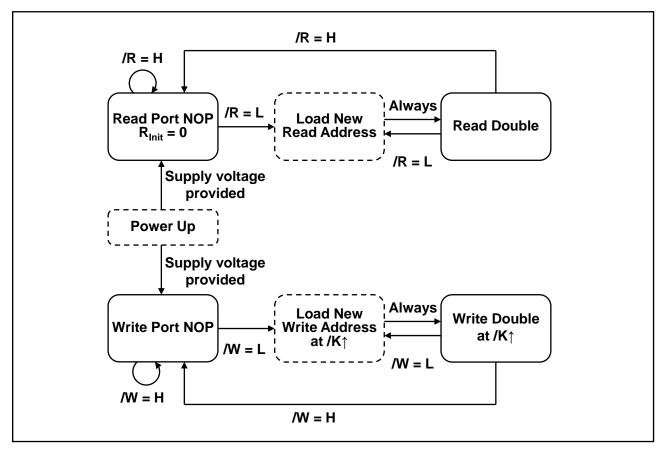
Operation	К	/K	/BW
Write D0 to D8	1	-	L
	-	1	L
Write nothing	1	-	Н
, vince not mig	-	1	Н

**Notes 1.** H: high level, L: low level,  $\uparrow$ : rising edge.

**2.** Assumes a WRITE cycle was initiated. /BWx can be altered for any portion of the BURST WRITE operation provided that the setup and hold requirements are satisfied.



## Bus Cycle State Diagram



- **Notes 1.** The address is concatenated with one additional internal LSB to facilitate burst operation. The address order is always fixed as: xxx...xxx+0, xxx...xxx+1. Bus cycle is terminated at the end of this sequence (burst count = 2).
  - 2. Read and write state machines can be active simultaneously.
  - 3. State machine control timing sequence is controlled by K.

#### **Absolute Maximum Ratings**

Parameter	Symbol	Rating	Unit	Notes
Input voltage on any ball	V <sub>IN</sub>	-0.5 to V <sub>DD</sub> + 0.5 (2.5 V max.)	V	1, 4
Input/output voltage	V <sub>I/O</sub>	-0.5 to V <sub>DDQ</sub> + 0.5 (2.5 V max.)	V	1, 4
Core supply voltage	V <sub>DD</sub>	-0.5 to 2.5	V	1, 4
Output supply voltage	Vddq	-0.5 to V <sub>DD</sub>	V	1, 4
Junction temperature	Tj	+125 (max)	°C	5
Storage temperature	T <sub>STG</sub>	-55 to +125	°C	

**Notes 1.** All voltage is referenced to V<sub>SS</sub>.

- 2. Permanent device damage may occur if Absolute Maximum Ratings are exceeded. Functional operation should be restricted the Operation Conditions. Exposure to higher than recommended voltages for extended periods of time could affect device reliability.
- **3.** These CMOS memory circuits have been designed to meet the DC and AC specifications shown in the tables after thermal equilibrium has been established.
- **4.** The following supply voltage application sequence is recommended: V<sub>SS</sub>, V<sub>DD</sub>, V<sub>DDQ</sub>, V<sub>REF</sub> then V<sub>IN</sub>. Remember, according to the Absolute Maximum Ratings table, V<sub>DDQ</sub> is not to exceed 2.5 V, whatever the instantaneous value of V<sub>DDQ</sub>.
- **5.** Some method of cooling or airflow should be considered in the system. (Especially for high frequency or ODT parts)

Parameter	Symbol	Min	Тур	Max	Unit	Notes
Power supply voltage – core	Vdd	1.7	1.8	1.9	V	1
Power supply voltage – I/O	Vddq	1.4	1.5	Vdd	V	1, 2
Input reference voltage – I/O	Vref	0.68	0.75	0.95	V	3
Input high voltage	VIH(DC)	V <sub>REF</sub> + 0.1	-	V <sub>DDQ</sub> + 0.3	V	1, 4, 5
Input low voltage	VIL(DC)	-0.3	-	V <sub>REF</sub> – 0.1	V	1, 4, 5

## **Recommended DC Operating Conditions**

- **Notes 1.** At power-up, V<sub>DD</sub> and V<sub>DDQ</sub> are assumed to be a linear ramp from 0V to V<sub>DD</sub>(min.) or V<sub>DDQ</sub>(min.) within 200ms. During this time V<sub>DDQ</sub> < V<sub>DD</sub> and V<sub>IH</sub> < V<sub>DDQ</sub>. During normal operation, V<sub>DDQ</sub> must not exceed V<sub>DD</sub>.
  - 2. Please pay attention to  $T_j$  not to exceed the temperature shown in the absolute maximum ratings table due to current from  $V_{DDQ}$ .
  - 3. Peak to peak AC component superimposed on VREF may not exceed 5% of VREF.
  - These are DC test criteria. The AC V<sub>IH</sub> / V<sub>IL</sub> levels are defined separately to measure timing parameters.
  - 5. Overshoot:  $V_{IH(AC)} \le V_{DDQ}$  + 0.5 V for t  $\le t_{KHKH}/2$

Undershoot:  $V_{\text{IL(AC)}} \geq$  -0.5 V for  $t \leq t_{\text{KHKH}}/2$ 

During normal operation,  $V_{IH(DC)}$  must not exceed  $V_{DDQ}$  and  $V_{IL(DC)}$  must not be lower than  $V_{SS}$ .

## **DC Characteristics**

 $T_a = -40 \sim +85^{\circ}C$ 

 $V_{DD} = 1.8V \pm 0.1V$ ,  $V_{DDQ} = 1.5V$ ,  $V_{REF} = 0.75V$ 

#### **Operating Supply Current (Write / Read)**

Symbol =  $I_{DD}$ . Unit = mA.

			Latency			Frequency (max) (MHz)	533	500	400	300	250	200
No	Product Type	Burst Length	(Cycle)	ODT	Organi- zation	Cycle Time (min) (ns)	1.875	2.00	2.50	3.30	4.00	5.00
						Speed bin	-19	-20	-25	-33	-4	10
1					x 9	R1Q2A7209ABB-yy					760	670
2		B2			x18	R1Q2A7218ABB-yy					890	780
3	QDR II				x36	R1Q2A7236ABB-yy					950	830
4		B4	1.5	No	x18	R1Q3A7218ABB-yy			820	730		
5		זי			x36	R1Q3A7236ABB-yy			850	750		
6	DDR II	B2			x18	R1Q4A7218ABB-yy			700	630		
7					x36	R1Q4A7236ABB-yy			760	680		
8	QDR II+	B4			x18	R1QAA7218ABB-yy	1220	1160	1070			
9				No	x36	R1QAA7236ABB-yy	1280	1220	1130			
10	DDR II+	B2		-	x18	R1QBA7218ABB-yy	1030	990	920			
11			2.0		x36	R1QBA7236ABB-yy	1110	1060	990			
12	QDR II+	B4			x18	R1QDA7218ABB-yy	1220	1160	1070			
13				Yes	x36	R1QDA7236ABB-yy	1280	1220	1130			
14	DDR II+	B2			x18	R1QEA7218ABB-yy	1030	990	920			
15					x36	R1QEA7236ABB-yy	1110	1060	990			
16	QDR II+	B4			x18	R1QGA7218ABB-yy			980			
17			2.5	No	x36	R1QGA7236ABB-yy			1060			
18	DDR II+	B2	2.0		x18	R1QHA7218ABB-yy			850			
19					x36	R1QHA7236ABB-yy			910			

# **Notes 1.** "yy" represents the speed bin. "R1QDA7236ABB-20" can operate at 500 MHz(max) of frequency, for example.

- 2. All inputs (except ZQ,  $V_{REF}$ ) are held at either  $V_{IH}$  or  $V_{IL}$ .
- **3.**  $I_{OUT} = 0$  mA.  $V_{DD} = V_{DD}$  max,  $t_{KHKH} = t_{KHKH}$  min.
- 4. Operating supply currents (I<sub>DD</sub>) are measured at 100% bus utilization. I<sub>DD</sub> of QDR family is current of device with 100% write and 100% read cycle. I<sub>DD</sub> of DDR family is current of device with 100% write cycle (if I<sub>DD</sub>(Write) > I<sub>DD</sub>(Read)) or 100% read cycle (if I<sub>DD</sub>(Write) < I<sub>DD</sub>(Read)).

#### Standby Supply Current (NOP)

Symbol =  $I_{SB1}$ . Unit = mA.

			Latency			Frequency (max) (MHz)	533	500	400	300	250	200
No	Product Type	Burst Length	(Cycle)	ODT	Organi- zation	Cycle Time (min) (ns)	1.875	2.00	2.50	3.30	4.00	5.00
						Speed bin	-19	-20	-25	-33	-40	
1					x 9	R1Q2A7209ABB-yy					570	510
2		B2			x18	R1Q2A7218ABB-yy					670	600
3	QDR II				x36	R1Q2A7236ABB-yy					710	630
4		B4	1.5	No	x18	R1Q3A7218ABB-yy			590	520		
5		51			x36	R1Q3A7236ABB-yy			610	540		
6	DDR II	B2			x18	R1Q4A7218ABB-yy			610	560		
7	DBIT	DL			x36	R1Q4A7236ABB-yy			670	610		
8	QDR II+	B4			x18	R1QAA7218ABB-yy	870	830	780			
9				No	x36	R1QAA7236ABB-yy	910	870	810			
10	DDR II+	B2			x18	R1QBA7218ABB-yy	870	840	780			
11			2.0		x36	R1QBA7236ABB-yy	960	920	860			
12	QDR II+	B4			x18	R1QDA7218ABB-yy	870	830	780			
13		2.		Yes	x36	R1QDA7236ABB-yy	910	870	810			
14	DDR II+	B2			x18	R1QEA7218ABB-yy	870	840	780			
15	201011	51			x36	R1QEA7236ABB-yy	960	920	860			
16	QDR II+	B4			x18	R1QGA7218ABB-yy			720			
17		7	2.5	No	x36	R1QGA7236ABB-yy			770			
18	DDR II+	B2	2.0	110	x18	R1QHA7218ABB-yy			720			
19	DBITIN	52			x36	R1QHA7236ABB-yy			790			

**Notes 1.** "yy" represents the speed bin. "R1QDA7236ABB-20" can operate at 500 MHz(max) of frequency, for example.

- **2.** IOUT = 0 mA.  $V_{DD} = V_{DD} max$ , tkhkh = tkhkh min.
- 3. All address / data inputs are static at either  $V_{\text{IN}}$  >  $V_{\text{IH}}$  or  $V_{\text{IN}}$  <  $V_{\text{IL}}.$
- **4.** Reference value. (Condition = NOP currents are valid when entering NOP after all pending READ and WRITE cycles are completed.)

Parameter	Symbol	Min	Мах	Unit	Test condition	Notes
Input leakage current	Iц	-2	2	μΑ		10
Output leakage current	I <sub>LO</sub>	-5	5	μΑ		11
Output high voltage	V <sub>он</sub> (Low)	$V_{DDQ} - 0.2$	Vddq	V	I <sub>OH</sub>   ≤ 0.1 mA	8, 9
	Vон	V <sub>DDQ</sub> /2 - 0.12	$V_{DDQ}/2 + 0.12$	V		6, 8, 9
Output low voltage	V <sub>OL</sub> (Low)	V <sub>SS</sub>	0.2	V	$I_{OL} \leq 0.1 \ mA$	8, 9
	Vol	V <sub>DDQ</sub> /2 - 0.12	$V_{DDQ}/2 + 0.12$	V		7, 8, 9

#### Leakage Currents & Output Voltage

Notes 1. All inputs (except ZQ,  $V_{REF}$ ) are held at either  $V_{IH}$  or  $V_{IL}$ .

- **2.** IOUT = 0 mA.  $V_{DD} = V_{DD} \max$ , tkhkh = tkhkh min.
- 3. Operating supply currents (I<sub>DD</sub>) are measured at 100% bus utilization. I<sub>DD</sub> of QDR family is current of device with 100% write and 100% read cycle. I<sub>DD</sub> of DDR family is current of device with 100% write cycle (if I<sub>DD</sub>(Write) > I<sub>DD</sub>(Read)) or 100% read cycle (if I<sub>DD</sub>(Write) < I<sub>DD</sub>(Read)).
- 4. All address / data inputs are static at either  $V_{IN} > V_{IH}$  or  $V_{IN} < V_{IL}$ .
- 5. Reference value. (Condition = NOP currents are valid when entering NOP after all pending READ and WRITE cycles are completed.)
- 6. Outputs are impedance-controlled.  $|I_{OH}| = (V_{DDQ}/2)/(RQ/5)$  for values of 175  $\Omega \le RQ \le 350 \Omega$ .
- 7. Outputs are impedance-controlled. IoL = (V\_DDQ/2)/(RQ/5) for values of 175  $\Omega \le RQ \le 350 \Omega$ .
- 8. AC load current is higher than the shown DC values. AC I/O curves are available upon request.
- 9. HSTL outputs meet JEDEC HSTL Class I and Class II standards.
- **10.**  $0 \le V_{IN} \le V_{DDQ}$  for all input balls (except V<sub>REF</sub>, ZQ, TCK, TMS, TDI ball).
- **11.**  $0 \le V_{\text{OUT}} \le V_{\text{DDQ}}$  (except TDO ball), output disabled.

## **Thermal Resistance**

Parameter	Symbol	Airflow	Тур	Unit	Test condition	Notes
Junction to Ambient	Αιθ	1 m/s	11.0	∘C/W	EIA/JEDEC JESD51	1
Junction to Case	θја	-	4.4	0,11		

Notes 1. These parameters are calculated under the condition. These are reference values.

**2.**  $T_j = T_a + \theta_{JA} \times Pd$ 

 $T_j = T_c + \theta_{JC} \times Pd$ 

where

T<sub>j</sub> : Junction temperature when the device has achieved a steady-state after application of Pd (°C)

- T<sub>a</sub> : Ambient temperature (°C)
- $T_{\rm c}$  : Temperature of external surface of the package or case (°C)
- $\theta_{\text{JA}}$  : Thermal resistance from junction-to-ambient (°C/W)
- $\theta_{JC}$ : Thermal resistance from junction-to-case (package) (°C/W)
- Pd : Power dissipation that produced change in junction temperature (W) (cf.JESD51-2A)



### Capacitance

 $T_a = +25^{\circ}C$ , Frequency = 1.0MHz,  $V_{DD} = 1.8V$ ,  $V_{DDQ} = 1.5V$ 

Parameter	Symbol	Min	Тур	Max	Unit	Test condition	Notes
Input capacitance (SA, /R, /W, /BW, D <sub>(separate)</sub> )	CIN	-	4	5	pF	$V_{IN} = 0 V$	1, 2
Clock input capacitance (K, /K, C, /C)	C <sub>CLK</sub>	-	4	5	pF	$V_{CLK} = 0 V$	1, 2
Output capacitance (Q <sub>(separate)</sub> , DQ <sub>(common)</sub> , CQ, /CQ)	Cı/o	-	5	6	pF	$V_{I/O} = 0 V$	1, 2

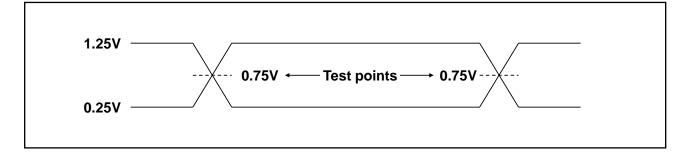
Notes 1. These parameters are sampled and not 100% tested.

2. Except JTAG (TCK, TMS, TDI, TDO) pins.

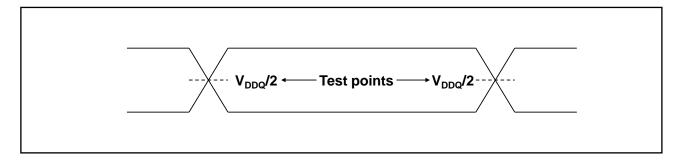
## **AC Test Conditions**

#### Input waveform

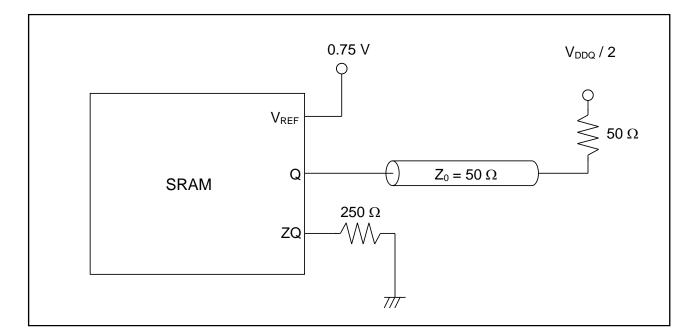
Rise/fall time  $\leq 0.3 \ \text{ns}$ 



#### Output waveform



#### **Output load conditions**



## **AC Operating Conditions**

Parameter	Symbol	Min	Тур	Мах	Unit	Notes
Input high voltage	V <sub>IH(AC)</sub>	V <sub>REF</sub> + 0.2	-	-	V	1, 2, 3, 4
Input low voltage	VIL(AC)	-	-	V <sub>REF</sub> – 0.2	V	1, 2, 3, 4

Notes 1. All voltages referenced to V<sub>SS</sub> (GND).

During normal operation,  $V_{DDQ}$  must not exceed  $V_{DD}$ .

- 2. These conditions are for AC functions only, not for AC parameter test.
- **3.** Overshoot:  $V_{IH(AC)} \le V_{DDQ} + 0.5 V$  for  $t \le t_{KHKH}/2$

Undershoot:  $V_{IL(AC)} \ge -0.5 \text{ V}$  for  $t \le t_{KHKH}/2$ 

Control input signals may not have pulse widths less than  $t_{KHKL}(min)$  or operate at cycle rates less than  $t_{KHKH}(min)$ .

- 4. To maintain a valid level, the transitioning edge of the input must:
  - a. Sustain a constant slew rate from the current AC level through the target AC level,  $V_{IL(AC)}$  or  $V_{IH(AC)}$ .
  - b. Reach at least the target AC level.
  - c. After the AC target level is reached, continue to maintain at least the target DC level, VIL(DC) or VIH(DC).

## AC Characteristics (QDR-II, DDR-II series)

Ta = -40 ~ +85°C

 $V_{\text{DD}} = 1.8V \pm 0.1V, \, V_{\text{DDQ}} = 1.5V, \, V_{\text{REF}} = 0.75V$ 

		-:	33		-4	40			
Parameter	Symbol	300	MHz	250	MHz	200	MHz	Unit	Notes
		Min	Max	Min	Max	Min	Max		
	I		Clo	ock					
Average clock cycle time (K, /K, C, /C)	tкнкн	3.30	8.40	4.00	8.40	5.00	8.40	ns	8
Clock high time (K, /K, C, /C)	tкнк∟	1.32	-	1.60	-	2.00	-	ns	
Clock low time (K, /K, C, /C)	t <sub>к∟кн</sub>	1.32	-	1.60	-	2.00	-	ns	
Clock to /clock (K to /K, C to /C)	tкн/кн	1.49	-	1.80	-	2.20	-	ns	
/Clock to clock (/K to K, /C to C)	t/кнкн	1.49	-	1.80	-	2.20	-	ns	
Clock to data clock (K to C, /K to /C)	tкнсн	0	1.49	0	1.80	0	2.20	ns	
			DLL / PL	L timing		•			
Clock phase jitter (K, /K, C, /C)	t <sub>KC</sub> var	-	0.20	-	0.20	-	0.20	ns	3
Lock time (K, C)	tκc lock	1024	-	1024	-	1024	-	Cycle	2
K static to DLL/PLL reset	t <sub>KC</sub> reset	30	-	30	-	30	-	ns	7
			Outpu	t times					
C, /C high to output valid	t <sub>CHQV</sub>	-	0.45	-	0.45	-	0.45	ns	9
C, /C high to output hold	tснох	-0.45	-	-0.45	-	-0.45	-	ns	9
C, /C high to echo clock valid	tснсqv	-	0.45	-	0.45	-	0.45	ns	9
C, /C high to echo clock hold	tснсах	-0.45	-	-0.45	-	-0.45	-	ns	9
CQ, /CQ high to output valid	tсанаv	-	0.27	-	0.30	-	0.35	ns	4, 7
CQ, /CQ high to output hold	t <sub>CQHQX</sub>	-0.27	-	-0.30	-	-0.35	-	ns	4, 7
C, /C high to output high-Z	tсноz	-	0.45	-	0.45	-	0.45	ns	5, 6, 9
C, /C high to output low-Z	<b>t</b> снqх1	-0.45	-	-0.45	-	-0.45	-	ns	5, 9

#### R1Q2A7236ABB, R1Q2A7218ABB, R1Q2A7209ABB

		-3	3		-4	10			
Parameter	Symbol	300	300 MHz		250 MHz		200 MHz		Notes
		Min	Мах	Min	Мах	Min	Max		
			Setup	times					
Address valid to	t <sub>AVKH</sub> for R1Q2	-	-	0.35	-	0.40	-	ns	1
K rising edge	t <sub>AVKH</sub> for R1Q3/4	0.40	-	0.50	-	0.60	-		
Control inputs valid to	t <sub>IVKH</sub> for R1Q2	-	-	0.35	-	0.40	-	ns	1
K rising edge	t <sub>IVKH</sub> for R1Q3/4	0.40	-	0.50	-	0.60	-		
Data-in valid to K, /K rising edge	tovкн	0.30	-	0.35	-	0.40	-	ns	1
			Hold	times					
K rising edge	t <sub>кнах</sub> for R1Q2	-	-	0.35	-	0.40	-	ns	1
to address hold	tкнах for R1Q3/4	0.40	-	0.50	-	0.60	-	115	1
K rising edge	tкніх for R1Q2	-	-	0.35	-	0.40	-	2	4
to control inputs hold	tкніх for R1Q3/4	0.40	-	0.50	-	0.60	-	ns	1
K, /K rising edge to data-in hold	t <sub>KHDX</sub>	0.30	-	0.35	-	0.40	-	ns	1

**Notes 1.** This is a synchronous device. All addresses, data and control lines must meet the specified setup and hold times for all latching clock edges.

- V<sub>DD</sub> and V<sub>DDQ</sub> slew rate must be less than 0.1 V DC per 50 ns for DLL/PLL lock retention. DLL/PLL lock time begins once V<sub>DD</sub>, V<sub>DDQ</sub> and input clock are stable. It is recommended that the device is kept inactive during these cycles. This specification meets the QDR common spec. of 20 us.
- **3.** Clock phase jitter is the variance from clock rising edge to the next expected clock rising edge.
- **4.** Echo clock is very tightly controlled to data valid / data hold. By design, there is a ±0.1 ns variation from echo clock to data. The datasheet parameters reflect tester guardbands and test setup variations.
- **5.** Transitions are measured  $\pm 100 \text{ mV}$  from steady-state voltage.
- **6.** At any given voltage and temperature  $t_{CHQZ}$  is less than  $t_{CHQX1}$  and  $t_{CHQV}$ .
- 7. These parameters are sampled.
- 8. When x18 and x36 configuration except QDRII-B2 are operated at less than 180MHz, DLL/PLL should be disabled (/DOFF=L). Please contact Renesas if these devices are always used at less than 180MHz with DLL/PLL operation.
- 9. tchav, tchax, tchcav, tchcax, tchaz and tchax1 spec of R1Q3A and R1Q4A series are determined by the actual frequency regardless of Part Number (Marking Name). The following is the spec for the actual frequency.

tchqv, tchcqv, tchqz = 0.45 ns for  $\ge 200$  MHz and 0.50 ns for < 200 MHz

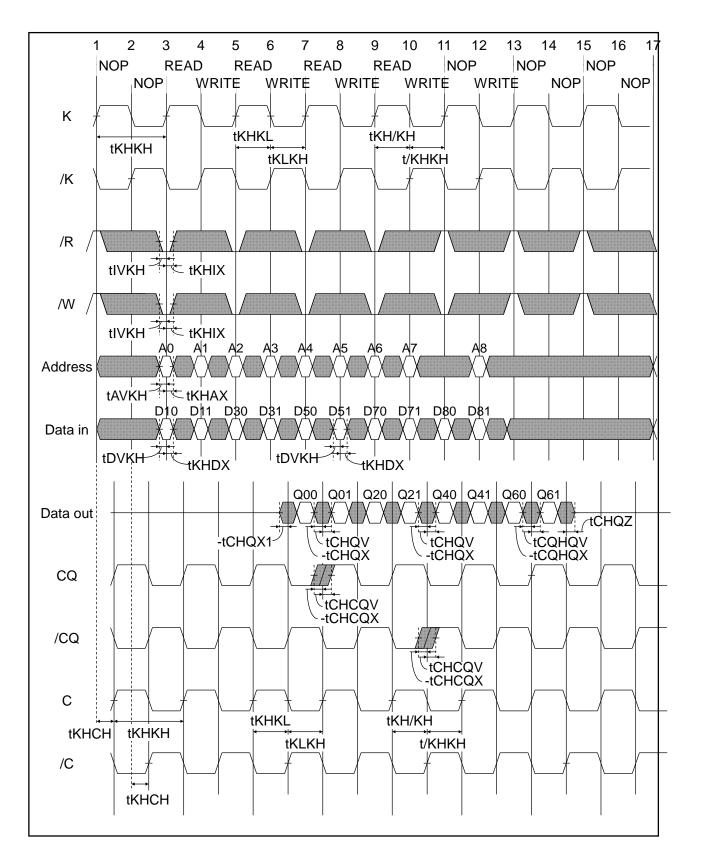
tchax, tchcax, tchax1 = -0.45 ns for  $\ge$  200 MHz and -0.50 ns for < 200 MHz



- **Remarks 1.** Test conditions as specified with the output loading as shown in AC Test Conditions unless otherwise noted.
  - 2. Control input signals may not be operated with pulse widths less than tKHKL (min).
  - 3. If C and /C are tied high, K and /K become the references for C and /C timing parameters.
  - **4.** V<sub>DDQ</sub> is +1.5 V DC. V<sub>REF</sub> is +0.75 V DC.
  - **5.** Control signals are /R, /W (QDR series), /LD, R-/W (DDR series), /BW, /BW0, /BW1, /BW2 and /BW3. Setup and hold times of /BWx signals must be the same as those of Data-in signals.

## Timing Waveforms

### Read and Write Timing (QDRII, B2, Read Latency = 1.5 cycle)



- **Notes 1.** Q00 refers to output from address A0+0. Q01 refers to output from the next internal burst address following A0, i.e., A0+1.
  - 2. Outputs are disabled (High-Z) N clock cycle after the last read cycle. Here, N = Read Latency + Burst Length  $\times$  0.5.
  - **3.** In this example, if address A0 = A1, then data Q00 = D10, Q01 = D11. Write data is forwarded immediately as read results.
  - **4.** To control read and write operations, /BW signals must operate at the same timing as Data-in signals.

## JTAG Specification

These products support a limited set of JTAG functions as in IEEE standard 1149.1.

#### **Disabling the Test Access Port**

It is possible to use this device without utilizing the TAP. To disable the TAP controller without interfering with normal operation of the device, TCK must be tied to V<sub>SS</sub> to preclude mid level inputs.

TDI and TMS are internally pulled up and may be unconnected, or may be connected to  $V_{DD}$  through a pull up resistor.

TDO should be left unconnected.

Symbol I/O	Pin assignments	Description	Notes
ТСК	2R	Test clock input. All inputs are captured on the rising edge of TCK and all outputs propagate from the falling edge of TCK.	
TMS	10R	Test mode select. This is the command input for the TAP controller state machine.	
TDI	11R	Test data input. This is the input side of the serial registers placed between TDI and TDO. The register placed between TDI and TDO is determined by the state of the TAP controller state machine and the instruction that is currently loaded in the TAP instruction.	
TDO	1R	Test data output. Output changes in response to the falling edge of TCK. This is the output side of the serial registers placed between TDI and TDO.	

#### **Test Access Port (TAP) Pins**

**Note 1.** The device does not have TRST (TAP reset). The Test-Logic Reset state is entered while TMS is held high for five rising edges of TCK. The TAP controller state is also reset on SRAM POWER-UP.

#### **TAP DC Operating Characteristics**

 $T_a = -40 \sim +85^{\circ}C$ 

 $V_{\text{DD}} = 1.8 V \pm 0.1 V$ 

Parameter	Symbol	Min	Тур	Max	Unit	Notes
Input high voltage	Vih	+1.3	-	V <sub>DD</sub> + 0.3	V	
Input low voltage	VIL	-0.3	-	+0.5	V	
Input leakage current	lu	-5.0	-	+5.0	μA	$0~V \leq V_{IN} \leq V_{DD}$
Output leakage current	ILO	-5.0	-	+5.0	μA	$\begin{array}{l} 0 \ V \leq V_{\text{IN}} \leq V_{\text{DD}}, \\ \text{output disabled} \end{array}$
Output low voltage	V <sub>OL1</sub>	-	-	0.2	V	I <sub>OLC</sub> = 100 μA
Output low voltage	V <sub>OL2</sub>	-	-	0.4	V	I <sub>OLT</sub> = 2 mA
Output high voltage	V <sub>OH1</sub>	1.6	-	-	V	Іонс  = 100 µА
Culput high voltage	V <sub>OH2</sub>	1.4	-	-	V	I <sub>ОНТ</sub>   = 2 mA

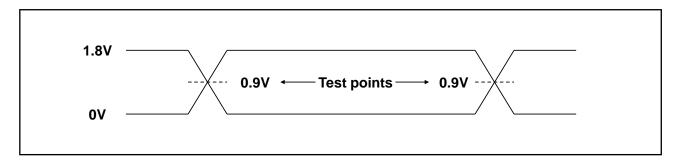
Notes 1. All voltages referenced to V<sub>SS</sub> (GND).

2. At power-up, V<sub>DD</sub> and V<sub>DDQ</sub> are assumed to be a linear ramp from 0V to V<sub>DD</sub>(min.) or V<sub>DDQ</sub>(min.) within 200ms. During this time V<sub>DDQ</sub> < V<sub>DD</sub> and V<sub>IH</sub> < V<sub>DDQ</sub>. During normal operation, V<sub>DDQ</sub> must not exceed V<sub>DD</sub>.

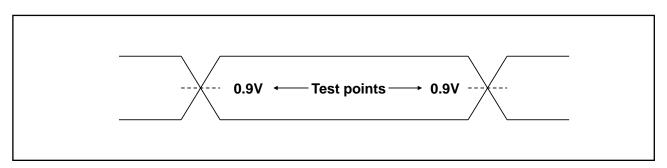
#### TAP AC Test Conditions

Parameter	Symbol	Conditions	Unit	Notes
Input timing measurement reference levels	VREF	0.9	V	
Input pulse levels	Vil, Vih	0 to 1.8	V	
Input rise/fall time	t <sub>r</sub> , t <sub>f</sub>	≤ <b>1</b> .0	ns	
Output timing measurement reference levels		0.9	V	
Test load termination supply voltage (V $_{TT}$ )		0.9	V	
Output load		See figures		

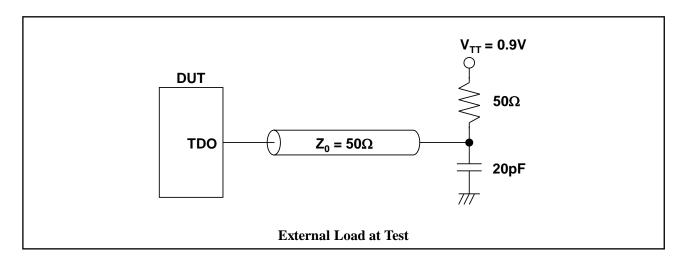
#### Input waveform



#### Output waveform



#### **Output load condition**



### **TAP AC Operating Characteristics**

 $T_a = -40 \sim +85^{\circ}C$ 

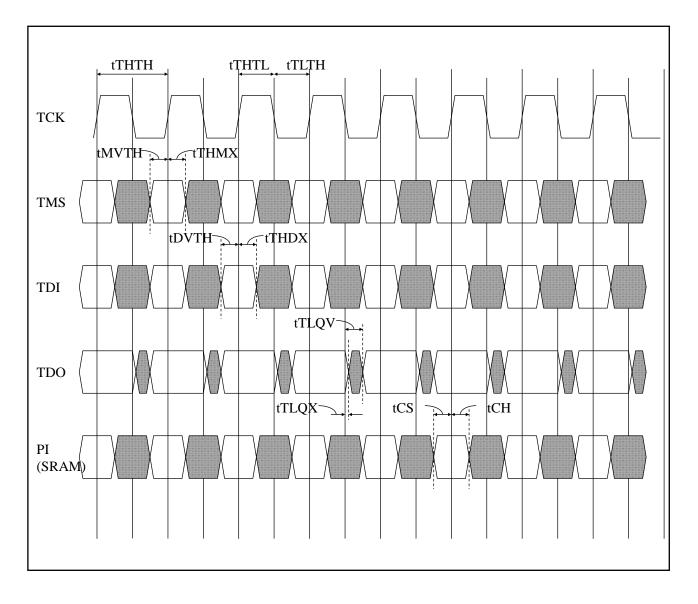
 $V_{\text{DD}} = 1.8 \text{V} \pm 0.1 \text{V}$ 

Parameter	Symbol	Min	Тур	Max	Unit	Notes
Test clock (TCK) cycle time	tтнтн	50	-	-	ns	
TCK high pulse width	tтнт∟	20	-	-	ns	
TCK low pulse width	tт∟тн	20	-	-	ns	
Test mode select (TMS) setup	tмvтн	5	-	-	ns	
TMS hold	tтнмх	5	-	-	ns	
Capture setup	t <sub>CS</sub>	5	-	-	ns	1
Capture hold	tсн	5	-	-	ns	1
TDI valid to TCK high	tdvth	5	-	-	ns	
TCK high to TDI invalid	tтнdx	5	-	-	ns	
TCK low to TDO unknown	tτlqx	0	-	-	ns	
TCK low to TDO valid	tτlqv	-	-	10	ns	

**Note 1.** t<sub>CS</sub> + t<sub>CH</sub> defines the minimum pause in RAM I/O pad transitions to assure pad data capture.



## TAP Controller Timing Diagram



## **Test Access Port Registers**

Register name	Length	Symbol	Notes
Instruction register	3 bits	IR [2:0]	
Bypass register	1 bit	BP	
ID register	32 bits	ID [31:0]	
Boundary scan register	109 bits	BS [109:1]	

#### TAP Controller Instruction Set

IR2	IR1	IR0	Instruction	Description	Notes
0	0	0	EXTEST	The EXTEST instruction allows circuitry external to the component package to be tested. Boundary scan register cells at output balls are used to apply test vectors, while those at input balls capture test results. Typically, the first test vector to be applied using the EXTEST instruction will be shifted into the boundary scan register using the PRELOAD instruction. Thus, during the Update-IR state of EXTEST, the output driver is turned on and the PRELOAD data is driven onto the output balls.	1, 2, 3, 5
0	0	1	IDCODE	The IDCODE instruction causes the ID ROM to be loaded into the ID register when the controller is in capture-DR mode and places the ID register between the TDI and TDO balls in shift-DR mode. The IDCODE instruction is the default instruction loaded in at power up and any time the controller is placed in the Test-Logic-Reset state.	
0	1	0	SAMPLE-Z	If the SAMPLE-Z instruction is loaded in the instruction register, all RAM outputs are forced to an inactive drive state (High-Z), moving the TAP controller into the capture-DR state loads the data in the RAMs input into the boundary scan register, and the boundary scan register is connected between TDI and TDO when the TAP controller is moved to the shift-DR state.	3, 4, 5
0	1	1	RESERVED	The RESERVED instructions are not implemented but are reserved for future use. Do not use these instructions.	
1	0	0	SAMPLE (/PRELOAD)	When the SAMPLE instruction is loaded in the instruction register, moving the TAP controller into the capture-DR state loads the data in the RAMs input and I/O buffers into the boundary scan register. Because the RAM clock(s) are independent from the TAP clock (TCK) it is possible for the TAP to attempt to capture the I/O ring contents while the input buffers are in transition (i.e., in a metastable state). Although allowing the TAP to SAMPLE metastable input will not harm the device, repeatable results cannot be expected. Moving the controller to shift-DR state then places the boundary scan register between the TDI and TDO balls.	3, 5
1	0	1	RESERVED	-	
1	1	0	RESERVED	-	
1	1	1	BYPASS	The BYPASS instruction is loaded in the instruction register when the bypass register is placed between TDI and TDO. This occurs when the TAP controller is moved to the shift- DR state. This allows the board level scan path to be shortened to facilitate testing of other devices in the scan path.	

**Notes 1.** Data in output register is not guaranteed if EXTEST instruction is loaded.

- **2.** After performing EXTEST, power-up conditions are required in order to return part to normal operation.
- **3.** RAM input signals must be stabilized for long enough to meet the TAPs input data capture setup plus hold time (t<sub>CS</sub> plus t<sub>CH</sub>). The RAMs clock inputs need not be paused for any other TAP operation except capturing the I/O ring contents into the boundary scan register.
- 4. Clock recovery initialization cycles are required after boundary scan.
- 5. For R1QD and R1QE series, ODT is disabled in EXTEST, SAMPLE-Z or SAMPLE mode.

## Boundary Scan Order

D:/ #		Signal names			D:4.#	Dell ID	Signal names		
Bit #	Ball ID	x9	x18	x36	Bit #	Ball ID	x9	x18	x36
1	6R	/C	/C	/C	36	10E	D3	D6	D6
2	6P	С	С	С	37	10D	NC	NC	D15
3	6N	SA	SA	SA	38	9E	NC	NC	Q15
4	7P	SA	SA	SA	39	10C	NC	Q7	Q7
5	7N	SA	SA	SA	40	11D	NC	D7	D7
6	7R	SA	SA	SA	41	9C	NC	NC	D16
7	8R	SA	SA	SA	42	9D	NC	NC	Q16
8	8P	SA	SA	SA	43	11B	Q4	Q8	Q8
9	9R	SA	SA	SA	44	11C	D4	D8	D8
10	11P	Q0	Q0	Q0	45	9B	NC	NC	D17
11	10P	D0	D0	D0	46	10B	NC	NC	Q17
12	10N	NC	NC	D9	47	11A	CQ	CQ	CQ
13	9P	NC	NC	Q9	48	10A	SA	SA	NC
14	10M	NC	Q1	Q1	49	9A	SA	SA	SA
15	11N	NC	D1	D1	50	8B	SA	SA	SA
16	9M	NC	NC	D10	51	7C	SA	SA	SA
17	9N	NC	NC	Q10	52	6C	SA	SA	SA
18	11L	Q1	Q2	Q2	53	8A	/R	/R	/R
19	11M	D1	D2	D2	54	7A	NC	NC	/BW1
20	9L	NC	NC	D11	55	7B	/BW	/BW0	/BW0
21	10L	NC	NC	Q11	56	6B	К	К	К
22	11K	NC	Q3	Q3	57	6A	/K	/K	/K
23	10K	NC	D3	D3	58	5B	NC	NC	/BW3
24	9J	NC	NC	D12	59	5A	NC	/BW1	/BW2
25	9K	NC	NC	Q12	60	4A	/W	/W	/W
26	10J	Q2	Q4	Q4	61	5C	SA	SA	SA
27	11J	D2	D4	D4	62	4B	SA	SA	SA
28	11H	ZQ	ZQ	ZQ	63	3A	SA	SA	SA
29	10G	NC	NC	D13	64	2A	SA	NC	NC
30	9G	NC	NC	Q13	65	1A	/CQ	/CQ	/CQ
31	11F	NC	Q5	Q5	66	2B	NC	Q9	Q18
32	11G	NC	D5	D5	67	3B	NC	D9	D18
33	9F	NC	NC	D14	68	1C	NC	NC	D27
34	10F	NC	NC	Q14	69	1B	NC	NC	Q27
35	11E	Q3	Q6	Q6	70	3D	NC	Q10	Q19



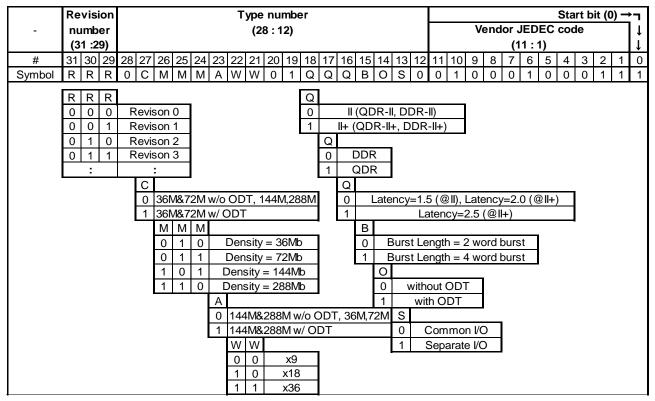
#### R1Q2A7236ABB, R1Q2A7218ABB, R1Q2A7209ABB

Bit #	Ball ID	S	ignal name	es	Bit #	Ball ID	S	ignal name	es
DIL #	Ball ID	x9	x18	x36	Bit #	Ball ID	x9	x18	x36
71	3C	NC	D10	D19	91	2L	Q7	Q15	Q24
72	1D	NC	NC	D28	92	3L	D7	D15	D24
73	2C	NC	NC	Q28	93	1M	NC	NC	D33
74	3E	Q5	Q11	Q20	94	1L	NC	NC	Q33
75	2D	D5	D11	D20	95	3N	NC	Q16	Q25
76	2E	NC	NC	D29	96	3M	NC	D16	D25
77	1E	NC	NC	Q29	97	1N	NC	NC	D34
78	2F	NC	Q12	Q21	98	2M	NC	NC	Q34
79	3F	NC	D12	D21	99	3P	Q8	Q17	Q26
80	1G	NC	NC	D30	100	2N	D8	D17	D26
81	1F	NC	NC	Q30	101	2P	NC	NC	D35
82	3G	Q6	Q13	Q22	102	1P	NC	NC	Q35
83	2G	D6	D13	D22	103	3R	SA	SA	SA
84	1H	/DOFF	/DOFF	/DOFF	104	4R	SA	SA	SA
85	1J	NC	NC	D31	105	4P	SA	SA	SA
86	2J	NC	NC	Q31	106	5P	SA	SA	SA
87	3K	NC	Q14	Q23	107	5N	SA	SA	SA
88	3J	NC	D14	D23	108	5R	SA	SA	SA
89	2K	NC	NC	D32	109	-	Internal	Internal	Internal
90	1K	NC	NC	Q32			1	1	1

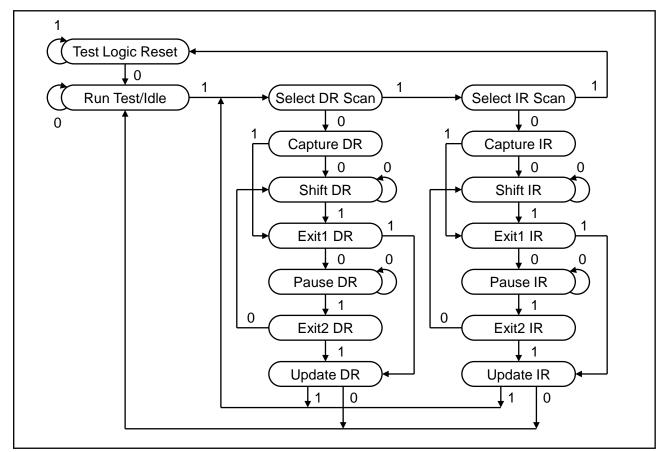
Notes In boundary scan mode,

- 1. Clock balls (K, /K, C, /C) are referenced to each other and must be at opposite logic levels for reliable operation.
- 2. CQ and /CQ data are synchronized to the respective C and /C (except EXTEST, SAMPLE-Z).
- **3.** If C and /C tied high, CQ is generated with respect to K and /CQ is generated with respect to /K (except EXTEST, SAMPLE-Z).

#### **ID Register**



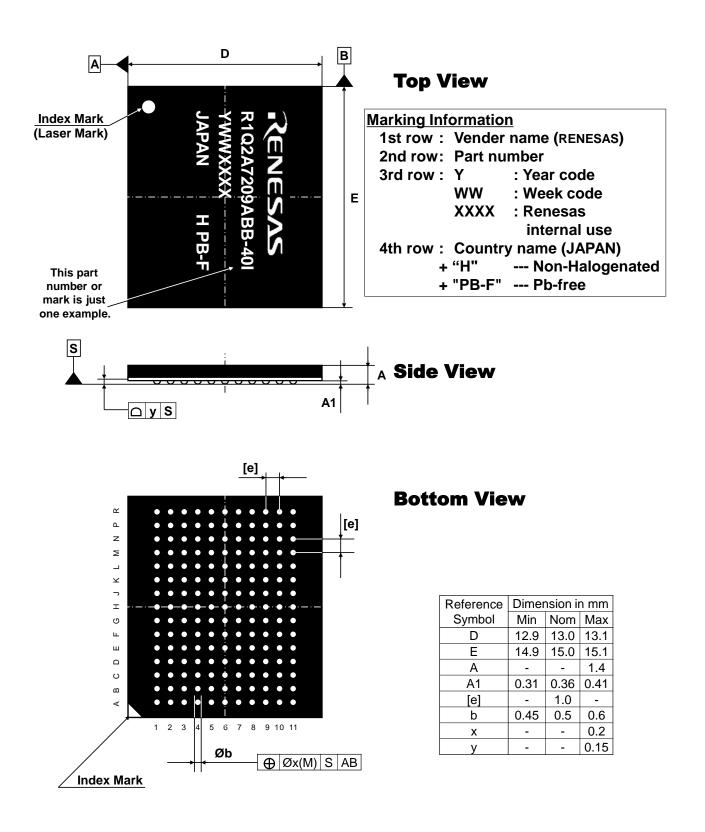
#### **TAP Controller State Diagram**



**Note 1.** The value adjacent to each state transition in this figure represents the signal present at TMS at the time of a rising edge at TCK. No matter what the original state of the controller, it will enter Test-Logic-Reset when TMS is held high for at least five rising edges of TCK.

## **Package Dimensions and Marking Information**

JEITA Package Code	Renesas Code	Previous Code	Mass (typ.)	
P-LBGA165-13x15-1.00	PLBG0165FE-A	165FHG	0.5g	





**Revision History** 

## R1Q2A7236ABB, R1Q2A7218ABB, R1Q2A7209ABB

		Description			
Rev.	Date	Page	Summary		
1.00	-	-	Applied new document format.		
2.00	'17.05.15	-	Reflected the information related change to non-halogenated package and merger some speed bin.		
2.01	'17.06.09	P.18	Added description of Pd.		
		-	Fixed some typo.		
2.02	'18.12.01	-	Fixed some typo.		
2.03	'19.02.01	-	Deleted description other than current Renesas 72M QDR Lineup.		
			Fixed some typo and orthographical variants.		

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