

# BECKHOFF New Automation Technology

## Product Overview | 2021



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**Main Catalog 2021  
Volume 1 | IPC, Motion,  
Automation**



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**News Catalog**

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IPC



10 The IPC Company

I/O



30 The I/O Company

Motion

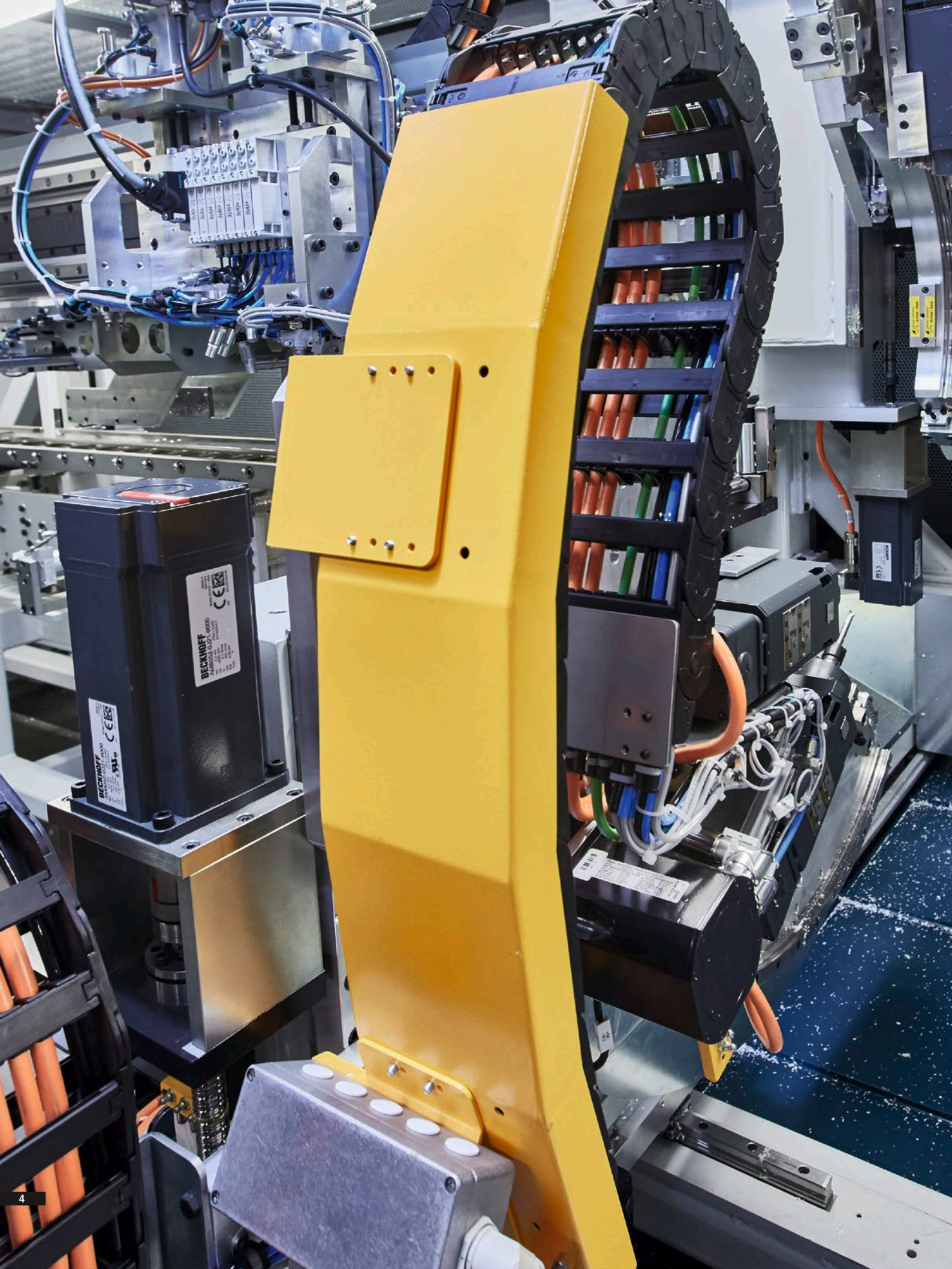


74 The Motion Company

Automation



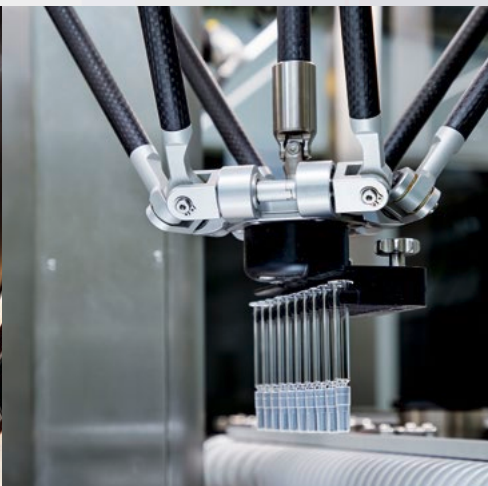
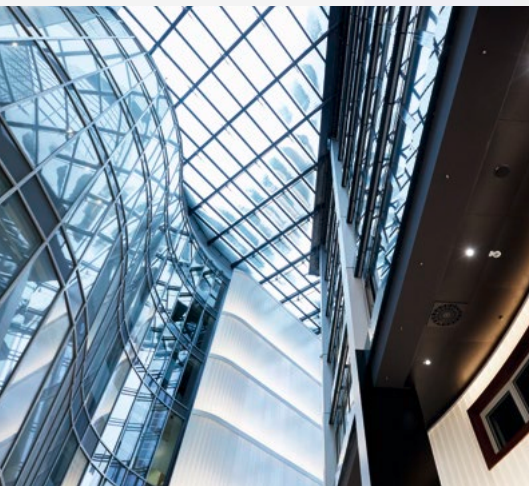
90 The Automation Company



# New Automation Technology

Beckhoff implements open automation systems based on PC Control technology. The product range covers Industrial PCs, I/O and Fieldbus Components, Drive Technology and automation software. Products that can be used as separate components or integrated into a complete and seamless control system are available for all industries. The Beckhoff New Automation Technology philosophy represents universal and open control and automation solutions that are used worldwide in a wide variety of different applications, ranging from CNC-controlled machine tools to intelligent building automation.

The central divisions of Beckhoff, such as development, production, administration, distribution, marketing, support and service are located at the Beckhoff Automation GmbH & Co. KG headquarters in Verl, Germany. Rapidly growing presence in the international market is taking place through subsidiaries and branch offices. Through worldwide co-operation with partners, Beckhoff is represented in more than 75 countries.



## Beckhoff Automation

- Headquarters: Verl, Germany
- Sales 2019: 903 million € (-1 %)
- Staff worldwide: 4,350
- Sales offices Germany: 23
- Subsidiaries/branch offices worldwide: 39
- Distributors worldwide: 75

(as of 04/2020)

# PC-based control technology

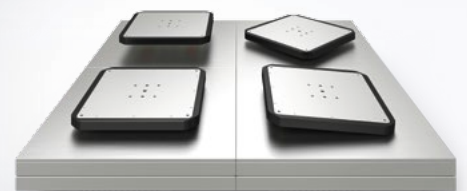
Since the foundation of the company in 1980, continuous development of innovative products and solutions using PC-based control technology has been the basis for the continued success of Beckhoff. Many automation technology standards that are taken for granted today were conceptualized by Beckhoff at an early stage and successfully introduced to the market.

The Beckhoff PC Control philosophy and the invention of the Lightbus system, the Bus Terminals and TwinCAT automation software represent milestones in automation technology and have become accepted as high-performance alternatives to traditional control technology. EtherCAT, the real-time Ethernet solution, makes forward-looking, high-performance technology available for a new generation of leading edge control concepts.

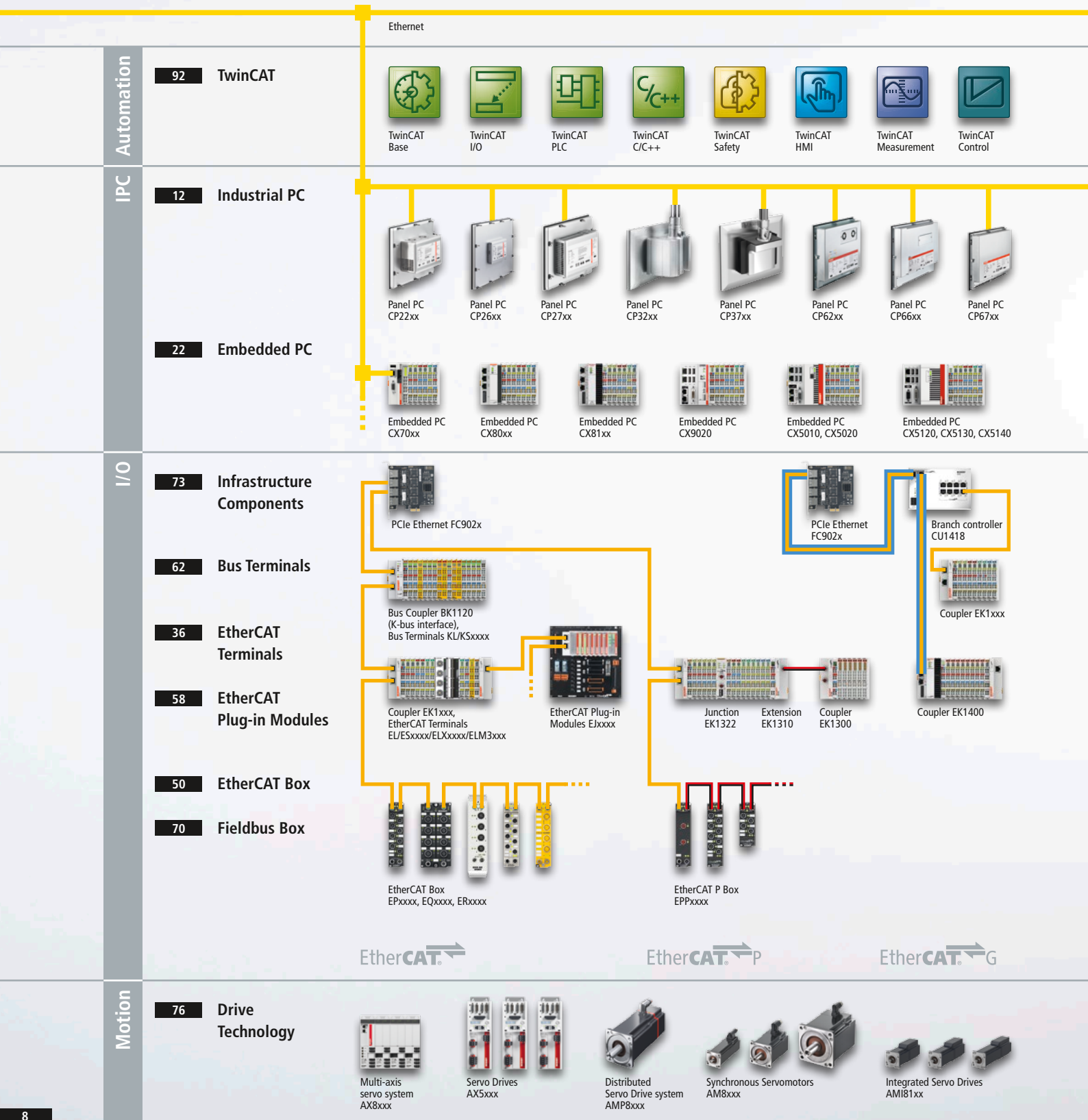


# Milestones

- 1982** P1000 – single-board motion controller
- 1986** PC Control – first PC-based machine controller
- 1988** S1000 – software PLC/NC on PC (DOS)
- 1989** Lightbus – high-speed fieldbus utilizing optical fibre
- 1990** All-in-one PC motherboard
- 1995** Bus Terminal – fieldbus technology in terminal block format
- 1996** TwinCAT – real-time software package under Windows with PLC and motion control functions
- 1998** Control Panel – remote IPC Control Panels
- 1999** Fieldbus Box – the I/O system in IP 67
- 2002** CX1000 – modular Embedded PCs for DIN rail mounting
- 2003** EtherCAT – real-time Ethernet fieldbus system
- 2005** TwinSAFE – the compact safety solution
- 2005** AX5000 – EtherCAT Servo Drives
- 2007** Industrial Motherboards – made in Germany
- 2008** XFC – eXtreme Fast Control Technology
- 2009** HD Bus Terminals – 16-channel terminals in 12 mm
- 2010** TwinCAT 3 – eXtended Automation Technology
- 2011** AM8000 – Synchronous Servomotors with One Cable Technology
- 2012** 2<sup>nd</sup> generation of Control Panels – Panel PCs and Control Panels with multi-touch technology
- 2012** XTS – eXtended Transport System
- 2014** Many-core control – industrial server maximizes industrial computing power
- 2014** AX8000 – multi-axis servo system
- 2014** EtherCAT Plug-in Modules – Bus Terminals for circuit boards
- 2015** EtherCAT P – One Cable Automation
- 2015** TwinCAT HMI – for platform-independent user interfaces
- 2015** TwinCAT IoT – for simple cloud communication
- 2015** TwinCAT Analytics – recording and analysis of process data
- 2016** EtherCAT measurement modules – system-integrated high-end measurement technology
- 2017** Process technology – system-integrated solutions for explosion protection requirement
- 2017** C60xx – the generation of ultra-compact IPCs
- 2017** AMP8000 – Distributed Servo Drive system
- 2017** TwinCAT Vision – machine vision integrated into automation technology
- 2018** Embedded PCs with ARM Cortex™-M7 processor
- 2018** EtherCAT G – Ultimate I/O Performance
- 2018** XPlanar – Flying Motion
- 2019** C70xx – multi-core Industrial PCs in IP 65/67
- 2019** TwinCAT Machine Learning – scalable, open and in real time
- 2019** TwinCAT Cloud Engineering – smart engineering directly in the cloud
- 2020** AL8000 – highly dynamic, modular linear servomotors
- 2020** PSxxxx power supplies – compact, strong, reliable



# System overview







TwinCAT Speech



TwinCAT Vision



TwinCAT Motion



TwinCAT PTP



TwinCAT NC I



TwinCAT CNC



TwinCAT Robotics



TwinCAT Connectivity



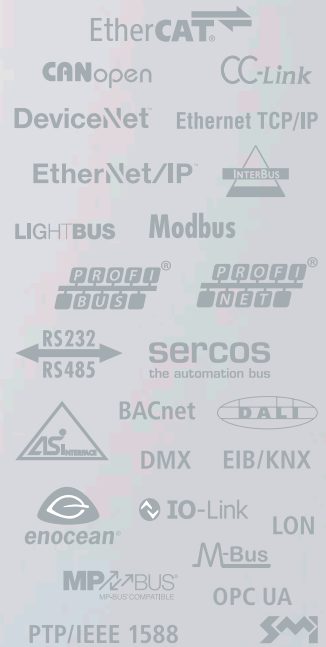
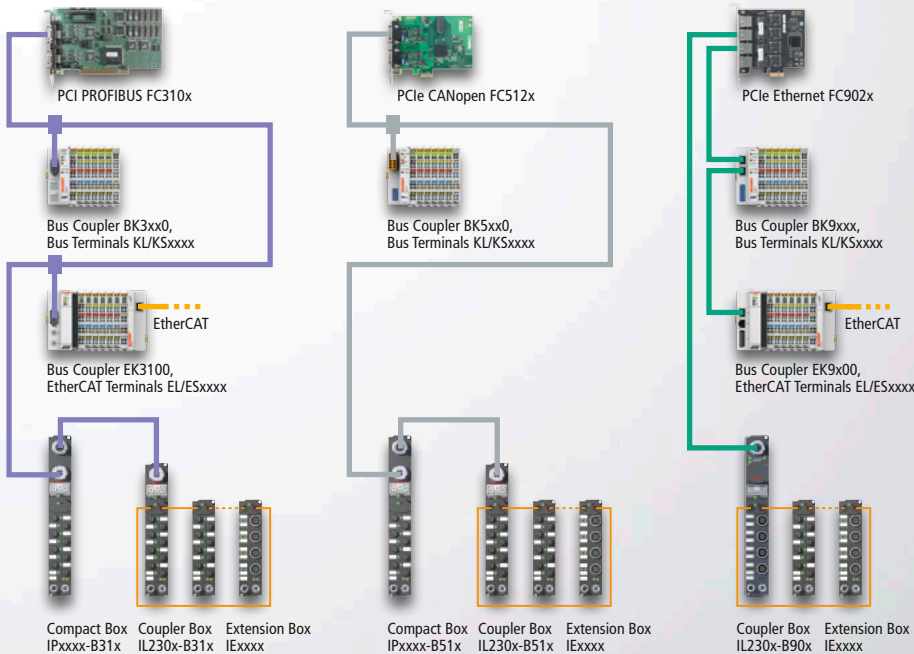
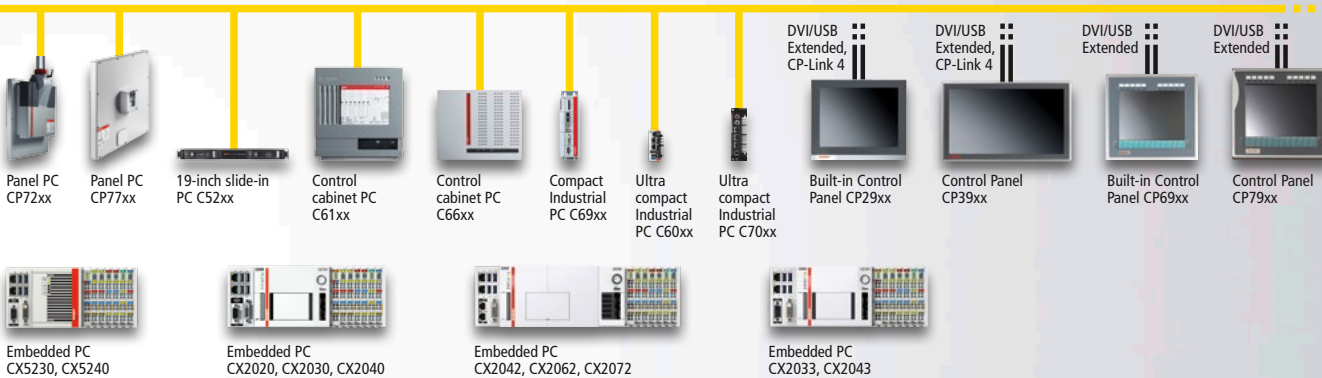
TwinCAT Industrie 4.0



TwinCAT Industry specific



TwinCAT BACnet



Servomotors with anodized housing AM87xx



Stainless steel servomotors AM88xx



Linear Servomotors ALxxxx, AAxxxx



Compact Drive Technology



XTS | Linear product transport



XPlanar | Planar motor system

# The IPC Company

The Industrial PC (IPC) is the hardware centerpiece of PC-based control technology. Beckhoff supplies Industrial PCs suitable for any application, which are based on open standards, enabling individual configuration to meet a wide range of control requirements.

Whether in the form of an Embedded PC with a compact form-factor for DIN rail mounting, a control cabinet PC, or as a Panel PC, in-house motherboard development enables Beckhoff to respond quickly to IT trends and customer-specific requirements.

► [www.beckhoff.com/ipc](http://www.beckhoff.com/ipc)

## Multi-touch Panel PCs 14

- large model variety
- high computing power
- display sizes from 7-inch to 24-inch
- easy installation in control cabinets or on mounting arms
- special versions for explosion protection
- customer-specific implementations

► [www.beckhoff.com/multi-touch](http://www.beckhoff.com/multi-touch)

## Multi-touch Control Panels 15

- large model variety
- display sizes from 7-inch to 24-inch
- landscape and portrait orientation
- easy installation in control cabinets or on mounting arms
- special versions for explosion protection
- customer-specific implementations

► [www.beckhoff.com/multi-touch](http://www.beckhoff.com/multi-touch)

## Single-touch Panels 16

- Control Panels or Panel PCs
- display sizes from 5.7-inch to 19-inch
- easy installation in control cabinets or on mounting arms
- customer-specific implementations

► [www.beckhoff.com/single-touch](http://www.beckhoff.com/single-touch)





**Ultra-compact Industrial PCs**

**PCs** 18

- high computing power
- industrial-strength housing designs
- easy installation
- high flexibility in terms of display connections

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**Embedded PCs** 22

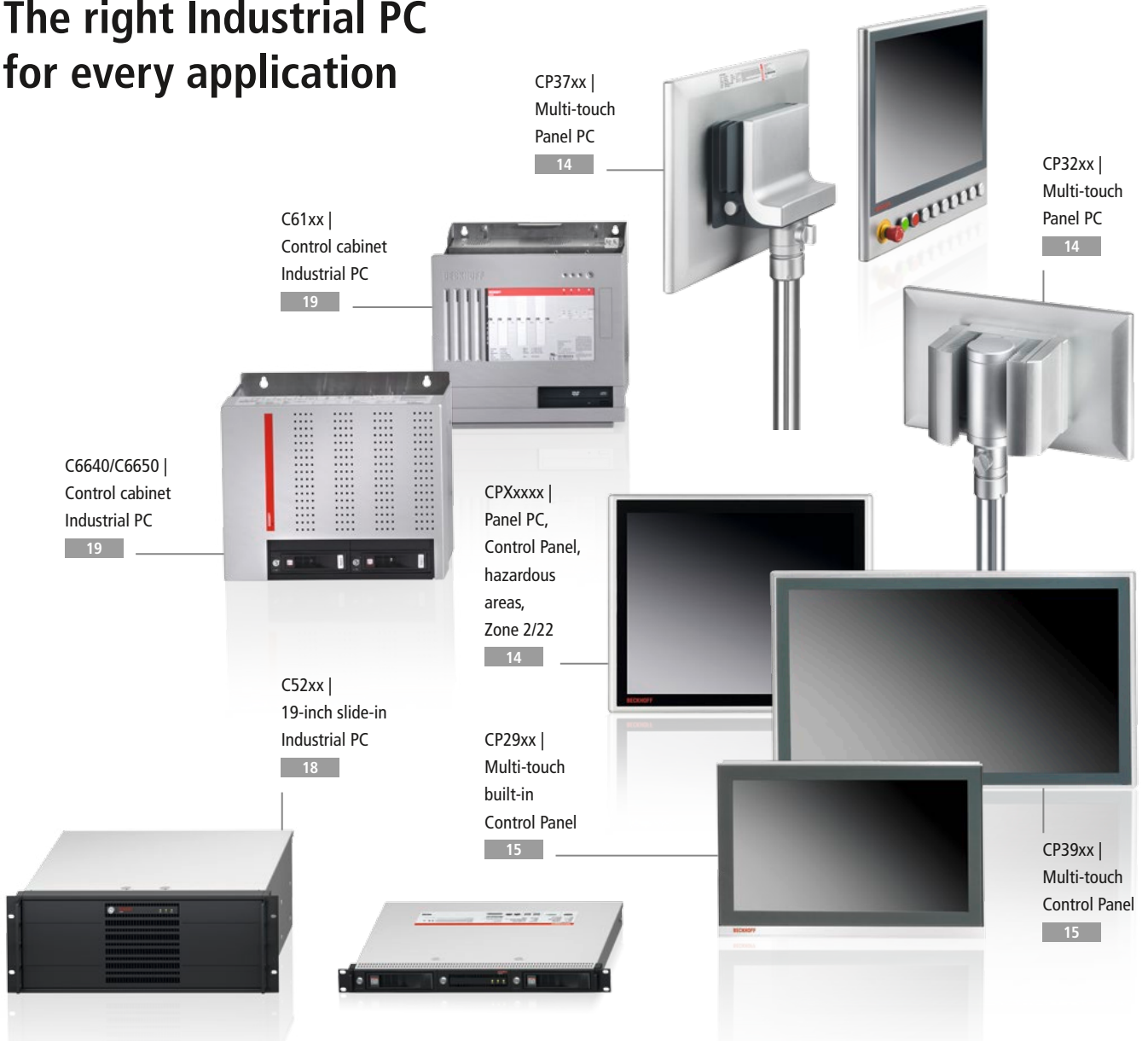
- scalable performance range
- up to 12 cores
- compact design
- direct I/O interface
- modular extension options
- DIN rail mounting

► [www.beckhoff.com/embedded-pc](http://www.beckhoff.com/embedded-pc)



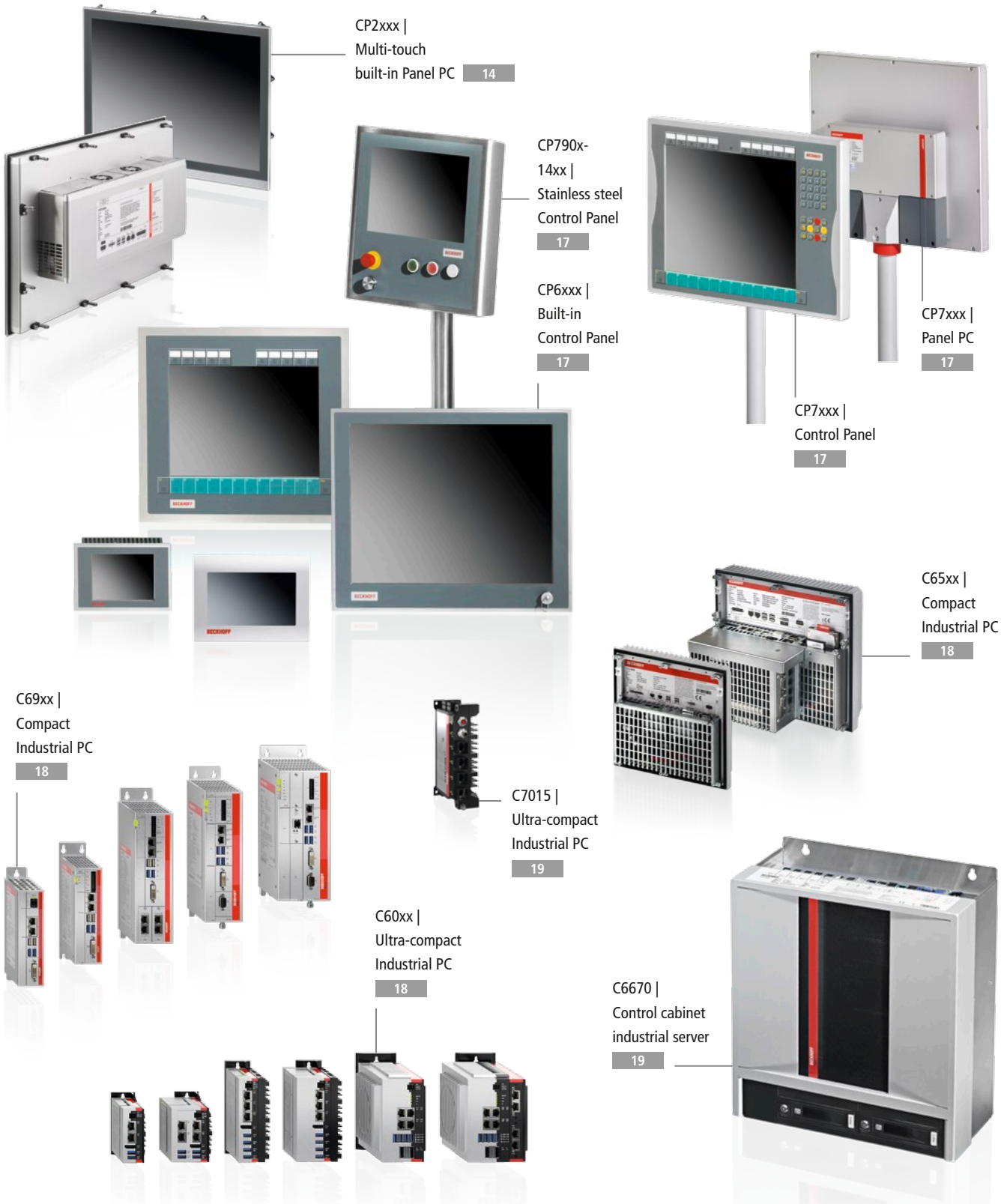
- large model variety of Industrial PCs and Embedded PCs
- high-performance PCs, featuring a wide range of processors, from Intel® Celeron® to top of the line Core™ i7 processors
- long-term availability of all Industrial PCs and Embedded PCs
- As the inventor of PC-based control technology, Beckhoff closely cooperates with global technology partners Intel and Microsoft.

# The right Industrial PC for every application



## Industrial PCs

	Compact motherboard Intel® Core™	Compact motherboard Intel Atom®	ATX motherboard Intel® Core™	3½-inch motherboard Intel® Core™	3½-inch motherboard Intel Atom®/ Intel® Celeron® ULV	3½-inch motherboard ARM Cortex™-A8	Control Panel
Multi-touch Panel PCs/Control Panels				CP22xx CP32xx	CP27xx/CPX27xx CP37xx/CPX37xx	CP26xx	CP29xx/CPX29xx CP39xx/CPX39xx
Single-touch Panel PCs/Control Panels		CP77xx		CP62xx CP72xx	CP67xx	CP66xx	CP69xx CP79xx
19-inch slide-in Industrial PCs			C5240	C5210			
Control cabinet Industrial PCs	C6025 C6027 C6030 C6032	C6015 C6017	C6140/C6150 C6240/C6250 C6640/C6650	C6515/C6525 C6920/C6930	C6905/C6915 C6925		
IP 65 Industrial PCs		C7015					



CP2xxx |  
Multi-touch  
built-in Panel PC 14

CP790x-  
14xx |  
Stainless steel  
Control Panel 17

CP6xxx |  
Built-in  
Control Panel 17

CP7xxx |  
Panel PC 17

CP7xxx |  
Control Panel 17

C65xx |  
Compact  
Industrial PC 18

C69xx |  
Compact  
Industrial PC 18

C7015 |  
Ultra-compact  
Industrial PC 19

C60xx |  
Ultra-compact  
Industrial PC 18

C6670 |  
Control cabinet  
industrial server 19

**Control cabinet industrial server**

SSI EEB motherboard  
2 x Intel® Xeon®  
C6670

# Multi-touch Panel PCs

► [www.beckhoff.com/multi-touch](http://www.beckhoff.com/multi-touch)



Multi-touch built-in Panel PCs, front side IP 65										
	Display	7-inch	12-inch	12.1-inch	15-inch	15.6-inch	18.5-inch	19-inch	21.5-inch	24-inch
	Resolution	800 x 480	800 x 600	1280 x 800	1024 x 768	1366 x 768	1366 x 768	1280 x 1024	1920 x 1080	1920 x 1080
	Format	5:3	4:3	16:10	4:3	16:9	16:9	5:4	16:9	16:9
<b>CP22xx</b> – up to Intel® Core™ i3/i5/i7	multi-finger touch screen		CP2212	CP2213	CP2215	CP2216	CP2218	CP2219	CP2221	CP2224
<b>CP26xx</b> – ARM Cortex™-A8	dual-finger touch screen	CP2607	CP2612	CP2613	CP2615	CP2616	CP2618	CP2619	CP2621	CP2624
<b>CP27xx</b> – Intel® Celeron® ULV or Atom®	multi-finger touch screen, only horizontal		CP2712	CP2713	CP2715 CPX2715	CP2716	CP2718	CP2719 CPX2719	CP2721 CPX2721	CP2724

Multi-touch Panel PCs, all sides IP 65										
	Display	7-inch	12-inch	12.1-inch	15-inch	15.6-inch	18.5-inch	19-inch	21.5-inch	24-inch
	Resolution	800 x 480	800 x 600	1280 x 800	1024 x 768	1366 x 768	1366 x 768	1280 x 1024	1920 x 1080	1920 x 1080
	Format	5:3	4:3	16:10	4:3	16:9	16:9	5:4	16:9	16:9
<b>CP32xx</b> – up to Intel® Core™ i3/i5/i7	multi-finger touch screen, only horizontal		CP3212		CP3215	CP3216	CP3218	CP3219	CP3221	CP3224
<b>CP37xx</b> – Intel Atom®	multi-finger touch screen, only horizontal		CP3712	CP3713	CP3715 CPX3715	CP3716	CP3718	CP3719 CPX3719	CP3721 CPX3721	CP3724
<b>CP37xx-1600-0020</b> – Intel Atom®	multi-finger touch screen, only horizontal, fanless without cooling fins				CP3715-1600-0020	CP3716-1600-0020	CP3718-1600-0020	CP3719-1600-0020	CP3721-1600-0020	CP3724-1600-0020

# Multi-touch Control Panels

► [www.beckhoff.com/multi-touch](http://www.beckhoff.com/multi-touch)



CP29xx



CP39xx



CP39xx-14xx-0010

## Multi-touch built-in Control Panels, front side IP 65

	Display	7-inch	12-inch	12.1-inch	15-inch	15.6-inch	18.5-inch	19-inch	21.5-inch	24-inch
	Resolution	800 x 480	800 x 600	1280 x 800	1024 x 768	1366 x 768	1366 x 768	1280 x 1024	1920 x 1080	1920 x 1080
	Format	5:3	4:3	16:10	4:3	16:9	16:9	5:4	16:9	16:9
<b>CP29xx-0000</b> – DVI/USB Extended interface*	multi-finger touch screen	CP2907- 0000	CP2912- 0000	CP2913- 0000	CP2915- 0000 CPX2915- 0000	CP2916- 0000	CP2918- 0000	CP2919- 0000 CPX2919- 0000	CP2921- 0000 CPX2921- 0000	CP2924- 0000
<b>CP29xx-0010</b> – CP-Link 4*	multi-finger touch screen	CP2907- 0010	CP2912- 0010	CP2913- 0010	CP2915- 0010	CP2916- 0010	CP2918- 0010	CP2919- 0010	CP2921- 0010	CP2924- 0010

## Multi-touch Control Panels, all sides IP 65

	Display	7-inch	12-inch	12.1-inch	15-inch	15.6-inch	18.5-inch	19-inch	21.5-inch	24-inch
	Resolution	800 x 480	800 x 600	1280 x 800	1024 x 768	1366 x 768	1366 x 768	1280 x 1024	1920 x 1080	1920 x 1080
	Format	5:3	4:3	16:10	4:3	16:9	16:9	5:4	16:9	16:9
<b>CP39xx-0000</b> – DVI/USB Extended interface*	multi-finger touch screen	CP3907- 0000	CP3912- 0000	CP3913- 0000	CP3915- 0000	CP3916- 0000	CP3918- 0000	CP3919- 0000	CP3921- 0000	CP3924- 0000
<b>CP39xx-0010</b> – CP-Link 4*	multi-finger touch screen	CP3907- 0010	CP3912- 0010	CP3913- 0010	CP3915- 0010 CPX3915- 0010	CP3916- 0010	CP3918- 0010	CP3919- 0010 CPX3919- 0010	CP3921- 0010 CPX3921- 0010	CP3924- 0010
<b>CP39xx- 14xx-0010</b> – CP-Link 4*	multi-finger touch screen, stainless steel housing			CP3913- 14xx-0010		CP3916- 14xx-0010	CP3918- 14xx-0010			

\*For further information on DVI/USB Extended and CP-Link 4 see page 21

# Single-touch Panels

► [www.beckhoff.com/single-touch](http://www.beckhoff.com/single-touch)



Single-touch built-in Panel PCs, front side IP 54/65								
	Display	5.7-inch	6.5-inch	7-inch	10.1-inch	12-inch	15-inch	19-inch
	Resolution	640 x 480	640 x 480	800 x 480	1024 x 600	800 x 600	1024 x 768	1280 x 1024
	Format	4:3	4:3	5:3	17:10	4:3	4:3	5:4
	Protect. class front	IP 65	IP 65	IP 54	IP 54	IP 65	IP 65	IP 65
<b>CP62xx</b> – 3½-inch motherboard – up to Intel® Core™ i3/i5/i7	without keys					CP6201	CP6202	CP6203
	function keys					CP6211	CP6212	CP6213
	numerical					CP6221	CP6222	CP6223
	alphanumeric					CP6231	CP6232 CP6242	CP6233
<b>CP66xx</b> – 3½-inch motherboard – ARM Cortex™-A8	without keys	CP6607	CP6609			CP6601	CP6602	CP6603
	function keys		CP6619			CP6611	CP6612	CP6613
	numerical		CP6629			CP6621	CP6622	CP6623
	alphanumeric					CP6631	CP6632	CP6633
<b>CP6606, CP6600</b> – 3½-inch motherboard – ARM Cortex™-A8	without keys			CP6606	CP6600			
<b>CP67xx</b> – 3½-inch motherboard – Intel® Celeron® ULV or Atom®	without keys	CP6707				CP6701	CP6702	CP6703
	function keys					CP6711	CP6712	CP6713
	numerical					CP6721	CP6722	CP6723
	alphanumeric					CP6731	CP6732 CP6742	CP6733
<b>CP6706, CP6700</b> – 3½-inch motherboard – Intel® Celeron® ULV or Atom®	without keys			CP6706	CP6700			





### Single-touch Panel PCs, all sides IP 65

	Display	5.7-inch	6.5-inch	7-inch	10.1-inch	12-inch	15-inch	19-inch
	Resolution	640 x 480	640 x 480	800 x 480	1024 x 600	800 x 600	1024 x 768	1280 x 1024
	Format	4:3	4:3	5:3	17:10	4:3	4:3	5:4
<b>CP72xx</b> – 3½-inch motherboard – up to Intel® Core™ i3/i5/i7	without keys					CP7201	CP7202	CP7203
	function keys					CP7211	CP7212	CP7213
	numerical					CP7221	CP7222	CP7223
	alphanumerical					CP7231	CP7232 CP7242	CP7233
<b>CP77xx</b> – CP motherboard – Intel® Celeron® ULV or Atom®	without keys					CP7701	CP7702	CP7703
	function keys					CP7711	CP7712	CP7713
	numerical					CP7721	CP7722	CP7723
	alphanumerical					CP7731	CP7732	CP7733

### Single-touch built-in Control Panels, front side IP 54/65

	Display	5.7-inch	6.5-inch	7-inch	10.1-inch	12-inch	15-inch	19-inch
	Resolution	640 x 480	640 x 480	800 x 480	1024 x 600	800 x 600	1024 x 768	1280 x 1024
	Format	4:3	4:3	5:3	17:10	4:3	4:3	5:4
	Protect. class front	IP 65	IP 65	IP 54	IP 54	IP 65	IP 65	IP 65
<b>CP69xx</b> – DVI/USB Extended interface*	without keys	CP6907	CP6909	CP6906	CP6900	CP6901	CP6902	CP6903
	function keys		CP6919			CP6911	CP6912	CP6913
	numerical		CP6929			CP6921	CP6922	CP6923
	alphanumerical					CP6931	CP6932/42	CP6933

### Single-touch Control Panels, all sides IP 65

	Display	5.7-inch	6.5-inch	7-inch	10.1-inch	12-inch	15-inch	19-inch
	Resolution	640 x 480	640 x 480	800 x 480	1024 x 600	800 x 600	1024 x 768	1280 x 1024
	Format	4:3	4:3	5:3	17:10	4:3	4:3	5:4
<b>CP79xx</b> – DVI/USB Extended interface*	without keys		CP7909			CP7901	CP7902	CP7903
	function keys		CP7919			CP7911	CP7912	CP7913
	numerical		CP7929			CP7921	CP7922	CP7923
	alphanumerical					CP7931	CP7932/42	CP7933
<b>CP790x-14xx</b> – DVI/USB Extended interface* stainless steel housing	without keys,					CP7901-14xx	CP7902-14xx	CP7903-14xx

\*For further information on DVI/USB Extended see page 21

# PCs

► [www.beckhoff.com/pc](http://www.beckhoff.com/pc)



C5210



C65x5  
basic configuration



C65x5 with  
PCIe module slots



C6525 with  
plug-in card slots



C69xx



C69x0 with  
plug-in card slots



C60xx

## Control cabinet Industrial PCs with 3½-inch motherboard

	Processor	Intel Atom®	Intel® Celeron® ULV	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7 6 <sup>th</sup> /7 <sup>th</sup> generation	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7 8 <sup>th</sup> /9 <sup>th</sup> generation
<b>C5210, 19-inch slide-in Industrial PCs</b>	1 rack unit			C5210-0030	C5210-0040
<b>C65xx</b>	fanless fanless, RAID			C6515-0060 C6525-0060	C6515-0070 C6525-0070
<b>C69xx, compact Industrial PCs, connectors on front</b>	fanless fanless, 1 CFast card slot fanless, 2 PCIe module slots optional plug-in card slots 2 PCIe module slots, optional plug-in card slots	C6905-0010 C6905-0020 C6915-0010 C6915-0020 C6925-0030 C6925-0040	C6925-0020	C6920-0060 C6930-0060	C6920-0070 C6930-0070

## Control cabinet Industrial PCs with compact industrial motherboard

	Processor	Intel Atom®	Intel® Celeron®, Intel® Core™ i3/i5/i7 8 <sup>th</sup> generation, series U	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7 6 <sup>th</sup> /7 <sup>th</sup> generation	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7 8 <sup>th</sup> /9 <sup>th</sup> generation
<b>C60xx</b>	fanless, without slots optional interfaces and/or an optional 1-second UPS up to 2 M.2 SSDs and/or 2 PCIe com- pact module slots	C6015-0010 C6015-0020 C6017-0010 C6017-0020	C6025-0000 C6027-0000	C6030-0060 C6032-0060	C6030-0070 C6032-0070



C7015



C5240



C6140



C6150



C6240



C6250



C6640



C6650



C6670

### IP 65 Industrial PCs with compact industrial motherboard

	Processor	Intel Atom®
C70xx, IP 65	fanless	C7015-0020

### Control cabinet Industrial PCs with ATX motherboard

	Processor	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7 6 <sup>th</sup> /7 <sup>th</sup> generation	Intel® Celeron®, Intel® Pentium®, Intel® Core™ i3/i5/i7 8 <sup>th</sup> /9 <sup>th</sup> generation
C5240, 19-inch slide-in Industrial PCs	7 slots, 4 rack units	C5240-0010	C5240-0020
C61xx, connectors on top	7 slots	C6140-0070 C6150-0070	C6140-0080
C62xx, connectors on front	7 slots	C6240-0070 C6250-0080	C6240-0080
C6640/C6650, connectors on top	7 slots	C6640-0050	C6640-0060
	7 slots, 2 removable frames	C6650-0050	C6650-0060

### Control cabinet industrial server with SSI EEB motherboard

	Processor	2 x Intel® Xeon® Scalable
C6670	6 slots, 2 removable frames	C6670-0010

# Customization options for Panel PCs and Control Panels

- stainless steel housings
- special membrane keyboards
- integration of electro-mechanical keyboards
- flush-mounted touch screens
- adaptation of membrane colors
- integration of customer logos



Built-in panel with individual front laminate



Stainless steel panel



Stainless steel panel with emergency stop



Customer-specific multi-touch Control Panel



Multi-touch Control Panel for machine tools



Multi-touch Control Panel with push-button extension

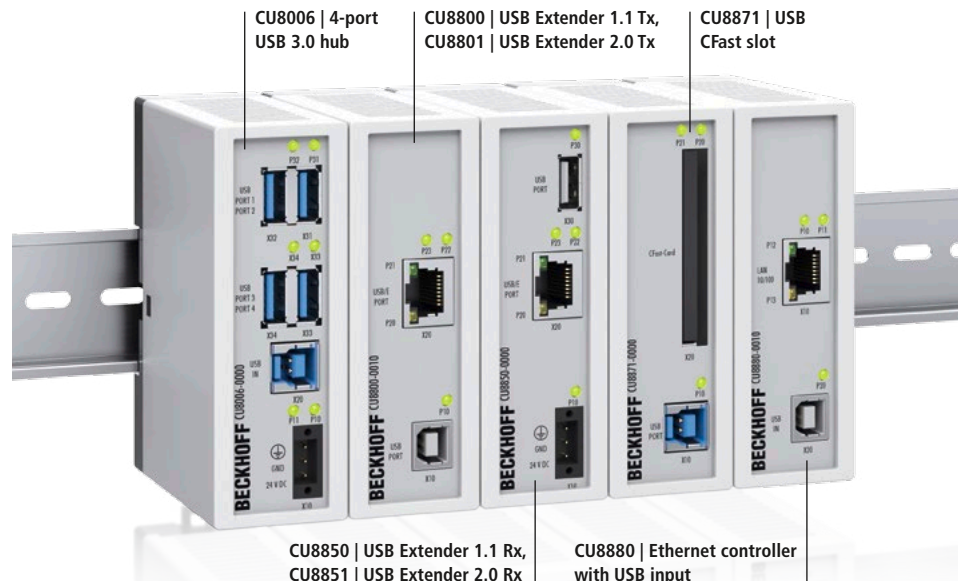


Control Panel with CNC push-button extension

## Industrial PC accessories

### CU8xxx modules

Different modules enable the use of various technologies in the industrial environment. All modules are intended for DIN rail mounting.

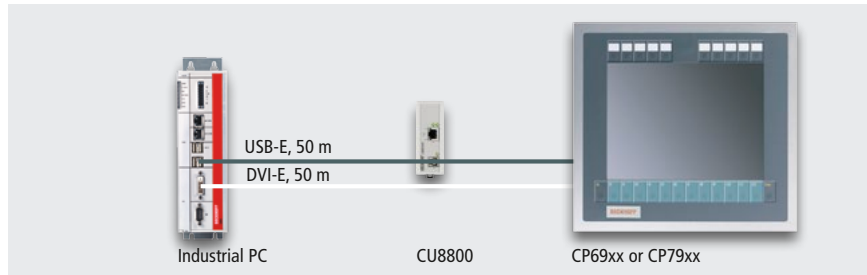


## DVI/USB Extended

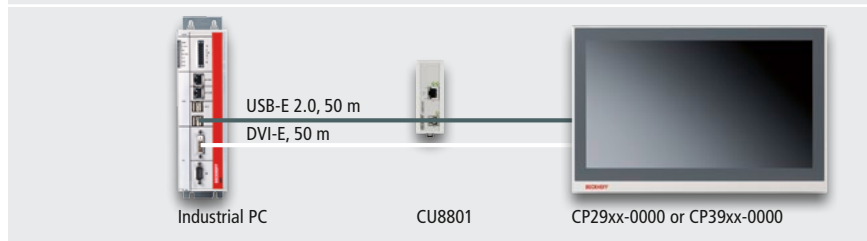
The DVI/USB Extended technology enables remote panel operation at a distance of up to 50 m from the PC. The DVI graphics signal is directly transmitted from the PC via DVI E cable. A signal processor in the Control Panels restores the DVI signal after it a distance of 50 m. For connection of the CP69xx and CP79xx Control Panels, a CU8800 USB Extender box is connected to an USB port of the PC. The signal is transmitted by the CU8800 USB Extender (USB-E) via Cat.5 cable over 50 m max. and is reconverted by the Control Panel into USB 1.1 with 12 Mbit/s.

For the CP29xx-0000 and CP39xx-0000 Control Panels, the USB signal from the PC is converted into USB Extended 2.0 by the USB Extender box CU8801, transmitted to the Control Panel via Cat.5 cable over 50 m max. to be reconverted into USB 2.0 with 480 Mbit/s. An USB hub in the Control Panel enables the connection of two external USB devices such as a keyboard or USB stick, in addition to touch screen and push-button extension.

**DVI/USB Extended**  
for CP69xx or CP79xx via  
the CU8800 transmitter box



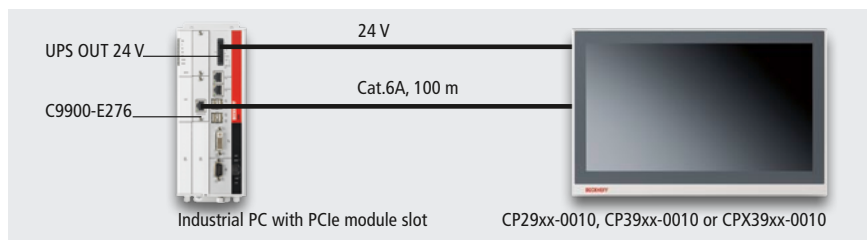
**DVI/USB Extended 2.0**  
for CP29xx-0000 or CP39xx-0000  
via the CU8801 transmitter box



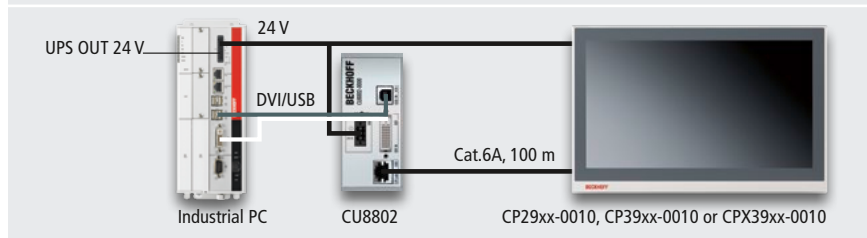
## CP-Link 4: The One Cable Display Link

With CP-Link 4 operating panels can be located up to 100 m away from the Industrial PC. The one cable solution can be used to transfer video signals, USB 2.0 and the power supply in a Cat.6A cable, thus reducing cable and installation costs. The CP-Link 4 technology is supported by the Beckhoff multi-touch Control Panel series CP29xx-0010 for installation inside the wall of a control cabinet, CP39xx-0010 for mounting arm installation and CPX39xx-0010 for use in hazardous areas, Zone 2/22.

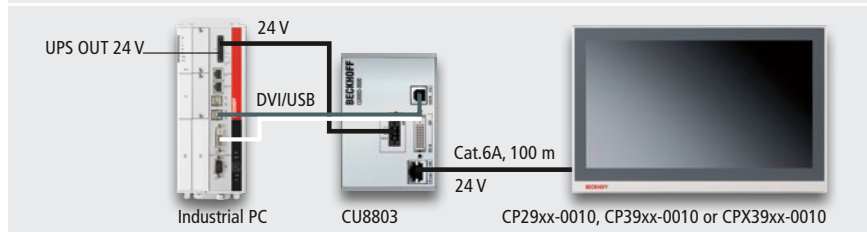
**CP-Link 4 – The Two Cable Display Link:**  
via C9900-E276 PCIe module integrated  
in the PC



**CP-Link 4 – The Two Cable Display Link:**  
via CU8802 transmitter box



**CP-Link 4 – The One Cable Display Link:**  
DVI, USB and 24 V via CU8803  
transmitter box



► [www.beckhoff.com/cp-link4](http://www.beckhoff.com/cp-link4)

# Embedded PC

► [www.beckhoff.com/embedded-pc](http://www.beckhoff.com/embedded-pc)



Embedded PC			
Basic CPU	CX70xx	<i>i</i> CX80xx	CX81xx
Processor	ARM Cortex™-M7, 480 MHz	ARM9, 400 MHz	ARM Cortex™-A9, 800 MHz
Flash memory	512 MB microSD (optionally 1 GB, 2 GB, 4 GB or 8 GB)	slot for microSD card, 512 MB included (expandable)	slot for microSD card, 512 MB included (expandable)
Main memory	32 MB SDR (internal, not expandable)	64 MB DDR2 RAM (not expandable)	512 MB DDR3 RAM (not expandable)
Interfaces	programming interface: 1 x Ethernet 10/100 Mbit/s (RJ45)	1 x RJ45 10/100 Mbit/s, 1 x USB device (behind the front flap), fieldbus interface	1 x RJ45 10/100 Mbit/s, bus interface
I/O connection	E-bus or K-bus, automatic recognition	E-bus or K-bus, automatic recognition	E-bus or K-bus, automatic recognition
System interfaces	integrated	integrated	integrated
DVI/USB	–	–	–
RS232	CX7080	CX8080	CX8180
RS422/RS485	CX7080	CX8080	CX8180
Audio	–	–	–
Ethernet	in the basic CPU	in the basic CPU	in the basic CPU
4-port USB hub	–	–	–
Memory medium	in the basic CPU	in the basic CPU	in the basic CPU
Fieldbus interfaces	expandable via EtherCAT Terminals	integrated or expandable via EtherCAT Terminals	integrated or expandable via EtherCAT Terminals
EtherCAT	EL6695 slave	CX8010 slave	CX8110 slave
PROFIBUS	EL6731 master	CX8030 master	EL6731 master
	EL6731-0010 slave	CX8031 slave	EL6731-0010 slave
CANopen	EL6751 master	CX8050 master	EL6751 master
	EL6751-0010 slave	CX8051 slave	EL6751-0010 slave
DeviceNet	EL6752 master	EL6752 master	EL6752 master
	EL6752-0010 slave	EL6752-0010 slave	EL6752-0010 slave
PROFINET RT	EL6631 controller	CX8093 device	EL6631 controller
	EL6631-0010 device		EL6631-0010 device
EtherNet/IP	EL6652 scanner	CX8095 adapter	EL6652 scanner
	EL6652-0010 adapter		EL6652-0010 adapter
UPS options	–	1-second UPS	1-second UPS



CX9020	CX5010	CX5020
ARM Cortex™-A8, 1 GHz	Intel Atom® Z510, 1.1 GHz clock frequency	Intel Atom® Z530, 1.6 GHz clock frequency
2 x slot for microSD card, 512 MB included (expandable)	slot for Compact Flash card, 128 MB included (expandable)	slot for Compact Flash card, 128 MB included (expandable)
1 GB DDR3 RAM (not expandable)	512 MB RAM (not expandable)	512 MB RAM (expandable ex factory to 1 GB)
2 x RJ45 10/100 Mbit/s (internal switch), 1 x DVI-D, 4 x USB 2.0, 1 x optional interface	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-D, 4 x USB 2.0, 1 x optional interface	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-D, 4 x USB 2.0, 1 x optional interface
E-bus or K-bus, automatic recognition	E-bus or K-bus, automatic recognition	E-bus or K-bus, automatic recognition
<b>integrated</b>	<b>integrated</b>	<b>integrated</b>
in the basic CPU	in the basic CPU	in the basic CPU
CX9020-N030	CX5010-N030	CX5020-N030
CX9020-N031	CX5010-N031	CX5020-N031
CX9020-N020	CX5010-N020	CX5020-N020
in the basic CPU	in the basic CPU	in the basic CPU
in the basic CPU	in the basic CPU	in the basic CPU
2 <sup>nd</sup> microSD slot in the basic CPU	in the basic CPU	in the basic CPU
<b>integrated or expandable via EtherCAT Terminals</b>	<b>integrated or expandable via EtherCAT Terminals</b>	<b>integrated or expandable via EtherCAT Terminals</b>
CX9020-B110 slave	CX5010-B110 slave	CX5020-B110 slave
CX9020-M310 master	CX5010-M310 master	CX5020-M310 master
CX9020-B310 slave	CX5010-B310 slave	CX5020-B310 slave
CX9020-M510 master	CX5010-M510 master	CX5020-M510 master
CX9020-B510 slave	CX5010-B510 slave	CX5020-B510 slave
EL6752 master	EL6752 master	EL6752 master
EL6752-0010 slave	EL6752-0010 slave	EL6752-0010 slave
CX9020-M930 controller	CX5010-M930 controller	CX5020-M930 controller
CX9020-B930 device	CX5010-B930 device	CX5020-B930 device
CX9020-B950 adapter	CX5010-B950 adapter	CX5020-B950 adapter
<b>1-second UPS (optional)</b>	<b>1-second UPS</b>	<b>1-second UPS</b>



## Embedded PC

Basic CPU	CX5120	CX5130	CX5140
<b>Processor</b>	Intel Atom® E3815, 1.46 GHz	Intel Atom® E3827, 1.75 GHz	Intel Atom® E3845, 1.91 GHz
<b>Flash memory</b>	slot for CFast card and microSD card, cards not included	slot for CFast card and microSD card, cards not included	slot for CFast card and microSD card, cards not included
<b>Main memory</b>	2 GB DDR3 RAM (not expandable)	4 GB DDR3 RAM (not expandable)	4 GB DDR3 RAM (not expandable)
<b>Interfaces</b>	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-I, 4 x USB 2.0, 1 x optional interface	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-I, 4 x USB 2.0, 1 x optional interface	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-I, 4 x USB 2.0, 1 x optional interface
<b>I/O connection</b>	E-bus or K-bus, automatic recognition	E-bus or K-bus, automatic recognition	E-bus or K-bus, automatic recognition
<b>System interfaces</b>	<b>integrated</b>	<b>integrated</b>	<b>integrated</b>
<b>DVI/USB</b>	in the basic CPU	in the basic CPU	in the basic CPU
<b>DisplayPort</b>	–	CX5130-N011	CX5140-N011
<b>RS232</b>	CX5120-N030	CX5130-N030	CX5140-N030
<b>RS422/RS485</b>	CX5120-N031	CX5130-N031	CX5140-N031
<b>Audio</b>	CX5120-N020	CX5130-N020	CX5140-N020
<b>Ethernet</b>	in the basic CPU	in the basic CPU	in the basic CPU
<b>Power over Ethernet</b>	–	–	–
<b>4-port USB hub</b>	in the basic CPU	in the basic CPU	in the basic CPU
<b>Memory medium</b>	in the basic CPU	in the basic CPU	in the basic CPU
<b>Fieldbus interfaces</b>	<b>integrated or expandable via EtherCAT Terminals</b>	<b>integrated or expandable via EtherCAT Terminals</b>	<b>integrated or expandable via EtherCAT Terminals</b>
<b>EtherCAT</b>	CX5120-M112 2 x master CX5120-B110 slave	CX5130-M112 2 x master CX5130-B110 slave	CX5140-M112 2 x master CX5140-B110 slave
<b>PROFIBUS</b>	CX5120-M310 master CX5120-B310 slave	CX5130-M310 master CX5130-B310 slave	CX5140-M310 master CX5140-B310 slave
<b>CANopen</b>	CX5120-M510 master CX5120-B510 slave	CX5130-M510 master CX5130-B510 slave	CX5140-M510 master CX5140-B510 slave
<b>DeviceNet</b>	EL6752 master EL6752-0010 slave	EL6752 master EL6752-0010 slave	EL6752 master EL6752-0010 slave
<b>PROFINET RT</b>	CX5120-M930 controller CX5120-B930 device	CX5130-M930 controller CX5130-B930 device	CX5140-M930 controller CX5140-B930 device
<b>EtherNet/IP</b>	CX5120-B950 adapter	CX5130-B950 adapter	CX5140-B950 adapter
<b>UPS options</b>	<b>1-second UPS</b>	<b>1-second UPS</b>	<b>1-second UPS</b>





CX5230	CX5240
Intel Atom® x5-E3930, 1.3 GHz, 2 cores	Intel Atom® x5-E3940, 1.6 GHz, 4 cores
slot for CFast card and microSD card, cards not included	slot for CFast card and microSD card, cards not included
4 GB DDR4 RAM (internal, not expandable)	8 GB DDR4 RAM (internal, not expandable)
2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-D, 4 x USB 3.0, 1 x optional interface	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-D, 4 x USB 3.0, 1 x optional interface
E-bus or K-bus, automatic recognition	E-bus or K-bus, automatic recognition
<b>modularly expandable</b>	<b>modularly expandable</b>
in the basic CPU, 2 <sup>nd</sup> DVI port as option CX5230-N010	in the basic CPU, 2 <sup>nd</sup> DVI port as option CX5240-N010
CX5230-N011	CX5240-N011
CX5230-N030 or CX2500-0030	CX5240-N030 or CX2500-0030
CX5230-N031 or CX2500-0031	CX5240-N031 or CX2500-0031
CX2500-0020	CX2500-0020
in the basic CPU or CX2500-0060	in the basic CPU or CX2500-0060
CX2500-0061	CX2500-0061
in the basic CPU or CX2500-0070	in the basic CPU or CX2500-0070
in the basic CPU	in the basic CPU
<b>integrated or expandable via EtherCAT Terminals</b>	<b>integrated or expandable via EtherCAT Terminals</b>
CX5230-M112 2 x master	CX5240-M112 2 x master
CX5230-B110 slave	CX5240-B110 slave
CX5230-M310 or CX2500-M310 master	CX5240-M310 or CX2500-M310 master
CX5230-B310 or CX2500-B310 slave	CX5240-B310 or CX2500-B310 slave
CX5230-M510 or CX2500-M510 master	CX5240-M510 or CX2500-M510 master
CX5230-B510 or CX2500-B510 slave	CX5240-B510 or CX2500-B510 slave
EL6752 master	EL6752 master
EL6752-0010 slave	EL6752-0010 slave
CX5230-M930 controller	CX5240-M930 controller
CX5230-B930 device	CX5240-B930 device
CX5230-B950 adapter	CX5240-B950 adapter
<b>1-second UPS</b>	<b>1-second UPS</b>



## Embedded PC

Basic CPU	CX2020	CX2030	CX2040
<b>Processor</b>	Intel® Celeron® 827E 1.4 GHz	Intel® Core™ i7 2610UE 1.5 GHz	Intel® Core™ i7 2715QE 2.1 GHz
<b>Flash memory</b>	20 GB or 40 GB CFast flash card (depending on the operating system), optionally extendable	20 GB or 40 GB CFast flash card (depending on the operating system), optionally extendable	20 GB or 40 GB CFast flash card (depending on the operating system), optionally extendable
<b>Main memory</b>	2 GB DDR3 RAM (expandable ex factory to 4 GB)	2 GB DDR3 RAM (expandable ex factory to 4 GB)	4 GB DDR3 RAM (not expandable)
<b>Interfaces</b>	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-I, 4 x USB 2.0, 1 x optional interface	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-I, 4 x USB 2.0, 1 x optional interface	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-I, 4 x USB 2.0, 1 x optional interface
<b>I/O connection</b>	via power supply module (E-bus or K-bus, automatic recognition)	via power supply module (E-bus or K-bus, automatic recognition)	via power supply module (E-bus or K-bus, automatic recognition)
<b>System interfaces</b>	<b>modularly expandable</b>	<b>modularly expandable</b>	<b>modularly expandable</b>
<b>DVI/USB</b>	in the basic CPU, 2 <sup>nd</sup> DVI port as option CX2020-N010	in the basic CPU, 2 <sup>nd</sup> DVI port as option CX2030-N010	in the basic CPU, 2 <sup>nd</sup> DVI port as option CX2040-N010
<b>DisplayPort</b>	CX2020-N011	CX2030-N011	CX2040-N011
<b>RS232</b>	CX2020-N030 or CX2500-0030	CX2030-N030 or CX2500-0030	CX2040-N030 or CX2500-0030
<b>RS422/RS485</b>	CX2020-N031 or CX2500-0031	CX2030-N031 or CX2500-0031	CX2040-N031 or CX2500-0031
<b>Audio</b>	CX2500-0020	CX2500-0020	CX2500-0020
<b>Ethernet</b>	in the basic CPU or CX2500-0060	in the basic CPU or CX2500-0060	in the basic CPU or CX2500-0060
<b>10G Ethernet</b>	–	–	–
<b>Power over Ethernet</b>	CX2500-0061	CX2500-0061	CX2500-0061
<b>4-port USB hub</b>	in the basic CPU or CX2500-0070	in the basic CPU or CX2500-0070	in the basic CPU or CX2500-0070
<b>Memory medium</b>	in the basic CPU or CX2550-0010/ CX2550-0020	in the basic CPU or CX2550-0010/ CX2550-0020	in the basic CPU or CX2550-0010/ CX2550-0020
<b>USB extension</b>	CX2550-0179 (USB 1.1) or CX2550-0279 (USB 2.0)	CX2550-0179 (USB 1.1) or CX2550-0279 (USB 2.0)	CX2550-0179 (USB 1.1) or CX2550-0279 (USB 2.0)
<b>Fieldbus interfaces</b>	<b>integrated or expandable via EtherCAT Terminals</b>	<b>integrated or expandable via EtherCAT Terminals</b>	<b>integrated or expandable via EtherCAT Terminals</b>
<b>EtherCAT</b>	CX2020-M112 2 x master CX2020-B110 slave	CX2030-M112 2 x master CX2030-B110 slave	CX2040-M112 2 x master CX2040-B110 slave
<b>Lightbus</b>	EL6720 master	EL6720 master	EL6720 master
<b>PROFIBUS</b>	CX2020-M310 or CX2500-M310 master CX2020-B310 or CX2500-B310 slave	CX2030-M310 or CX2500-M310 master CX2030-B310 or CX2500-B310 slave	CX2040-M310 or CX2500-M310 master CX2040-B310 or CX2500-B310 slave
<b>CANopen</b>	CX2020-M510 or CX2500-M510 master CX2020-B510 or CX2500-B510 slave	CX2030-M510 or CX2500-M510 master CX2030-B510 or CX2500-B510 slave	CX2040-M510 or CX2500-M510 master CX2040-B510 or CX2500-B510 slave
<b>DeviceNet</b>	EL6752 master EL6752-0010 slave	EL6752 master EL6752-0010 slave	EL6752 master EL6752-0010 slave
<b>PROFINET RT</b>	CX2020-M930 controller CX2020-B930 device	CX2030-M930 controller CX2030-B930 device	CX2040-M930 controller CX2040-B930 device
<b>EtherNet/IP</b>	CX2020-B950 adapter	CX2030-B950 adapter	CX2040-B950 adapter
<b>UPS options</b>	CX2100-0904, CX2100-0914	CX2100-0904, CX2100-0914	CX2100-0914



CX2042	CX2062	CX2072
Intel® Xeon® D-1527 2.2 GHz, 4 cores	Intel® Xeon® D-1548 2.0 GHz, 8 cores	Intel® Xeon® D-1567 2.1 GHz, 12 cores
slot for CFast card, card not included	slot for CFast card, card not included	slot for CFast card, card not included
8 GB DDR4 RAM (expandable ex factory to 64 GB)	8 GB DDR4 RAM (expandable ex factory to 64 GB)	8 GB DDR4 RAM (expandable ex factory to 64 GB)
2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-I, 4 x USB 3.0, 1 x optional interface	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-I, 4 x USB 3.0, 1 x optional interface	2 x RJ45 10/100/1000 Mbit/s, 1 x DVI-I, 4 x USB 3.0, 1 x optional interface
via power supply module (E-bus or K-bus, automatic recognition)	via power supply module (E-bus or K-bus, automatic recognition)	via power supply module (E-bus or K-bus, automatic recognition)
<b>modularly expandable</b>	<b>modularly expandable</b>	<b>modularly expandable</b>
in the basic CPU, 2 <sup>nd</sup> DVI port as option CX2042-N010	in the basic CPU, 2 <sup>nd</sup> DVI port as option CX2062-N010	in the basic CPU, 2 <sup>nd</sup> DVI port as option CX2072-N010
CX2042-N011	CX2062-N011	CX2072-N011
CX2042-N030 or CX2500-0030	CX2062-N030 or CX2500-0030	CX2072-N030 or CX2500-0030
CX2042-N031 or CX2500-0031	CX2062-N031 or CX2500-0031	CX2072-N031 or CX2500-0031
–	–	–
in the basic CPU or CX2500-0060	in the basic CPU or CX2500-0060	in the basic CPU or CX2500-0060
CX2042-N067 or CX2042-N167	CX2062-N067 or CX2062-N167	CX2072-N067 or CX2072-N167
CX2500-0061	CX2500-0061	CX2500-0061
in the basic CPU or CX2500-0070	in the basic CPU or CX2500-0070	in the basic CPU or CX2500-0070
in the basic CPU or CX2550-0010/ CX2550-0020	in the basic CPU or CX2550-0010/ CX2550-0020	in the basic CPU or CX2550-0010/ CX2550-0020
CX2550-0179 (USB 1.1) or CX2550-0279 (USB 2.0)	CX2550-0179 (USB 1.1) or CX2550-0279 (USB 2.0)	CX2550-0179 (USB 1.1) or CX2550-0279 (USB 2.0)
<b>integrated or expandable via EtherCAT Terminals</b>	<b>integrated or expandable via EtherCAT Terminals</b>	<b>integrated or expandable via EtherCAT Terminals</b>
CX2042-M112 2 x master	CX2062-M112 2 x master	CX2072-M112 2 x master
CX2042-B110 slave	CX2062-B110 slave	CX2072-B110 slave
EL6720 master	EL6720 master	EL6720 master
CX2042-M310 or CX2500-M310 master	CX2062-M310 or CX2500-M310 master	CX2072-M310 or CX2500-M310 master
CX2042-B310 or CX2500-B310 slave	CX2062-B310 or CX2500-B310 slave	CX2072-B310 or CX2500-B310 slave
CX2042-M510 or CX2500-M510 master	CX2062-M510 or CX2500-M510 master	CX2072-M510 or CX2500-M510 master
CX2042-B510 or CX2500-B510 slave	CX2062-B510 or CX2500-B510 slave	CX2072-B510 or CX2500-B510 slave
EL6752 master	EL6752 master	EL6752 master
EL6752-0010 slave	EL6752-0010 slave	EL6752-0010 slave
CX2042-M930 controller	CX2062-M930 controller	CX2072-M930 controller
CX2042-B930 device	CX2062-B930 device	CX2072-B930 device
CX2042-B950 adapter	CX2062-B950 adapter	CX2072-B950 adapter
–	–	–



## Embedded PC

Basic CPU	CX2033	CX2043
Processor	AMD Ryzen™ V1202B 2.3 GHz	AMD Ryzen™ V1807B 3.35 GHz
Flash memory	slot for CFast card	slot for CFast card
Main memory	8 GB DDR4 RAM (expandable ex factory to 16 GB)	8 GB DDR4 RAM (expandable ex factory to 16 GB)
Interfaces	2 x RJ45, 10/100/1000 Mbit/s, DVI-D, 4 x USB 3.1 Gen. 2, 1 x optional interface	2 x RJ45, 10/100/1000 Mbit/s, DVI-D, 4 x USB 3.1 Gen. 2, 1 x optional interface
I/O connection	via power supply module (E-bus or K-bus, automatic recognition)	via power supply module (E-bus or K-bus, automatic recognition)
System interfaces	<b>modularly expandable</b>	<b>modularly expandable</b>
DVI/USB	in the basic CPU, 2 <sup>nd</sup> DVI port as option CX2033-N010	in the basic CPU, 2 <sup>nd</sup> DVI port as option CX2043-N010
DisplayPort	CX2033-N011	CX2043-N011
RS232	CX2033-N030 or CX2500-0030	CX2043-N030 or CX2500-0030
RS422/RS485	CX2033-N031 or CX2500-0031	CX2043-N031 or CX2500-0031
Audio	CX2500-0020	CX2500-0020
Ethernet	in the basic CPU or CX2500-0060	in the basic CPU or CX2500-0060
Power over Ethernet	CX2500-0061	CX2500-0061
4-port USB hub	in the basic CPU or CX2500-0070	in the basic CPU or CX2500-0070
Memory medium	in the basic CPU or CX2550-0010/ CX2550-0020	in the basic CPU or CX2550-0010/ CX2550-0020
USB extension	CX2550-0179 (USB 1.1) or CX2550-0279 (USB 2.0)	CX2550-0179 (USB 1.1) or CX2550-0279 (USB 2.0)
Fieldbus interfaces	<b>integrated or expandable via EtherCAT Terminals</b>	<b>integrated or expandable via EtherCAT Terminals</b>
EtherCAT	CX2033-M112 2 x master CX2033-B110 slave	CX2043-M112 2 x master CX2043-B110 slave
Lightbus	EL6720 master	EL6720 master
PROFIBUS	CX2033-M310 or CX2500-M310 master CX2033-B310 or CX2500-B310 slave	CX2043-M310 or CX2500-M310 master CX2043-B310 or CX2500-B310 slave
CANopen	CX2033-M510 or CX2500-M510 master CX2033-B510 or CX2500-B510 slave	CX2043-M510 or CX2500-M510 master CX2043-B510 or CX2500-B510 slave
DeviceNet	EL6752 master EL6752-0010 slave	EL6752 master EL6752-0010 slave
PROFINET RT	CX2033-M930 controller CX2033-B930 device	CX2043-M930 controller CX2043-B930 device
EtherNet/IP	CX2033-B950 adapter	CX2043-B950 adapter
SERCOS	–	–
UPS options	CX2100-0914	CX2100-0914



CX1010	CX1020	CX1030
compatible with Intel® Pentium® MMX, clock frequency 500 MHz	Intel® Celeron® M ULV, 1 GHz clock frequency	Intel® Pentium® M, 1.8 GHz clock frequency
slot for Compact Flash card, 128 MB included (expandable)	slot for Compact Flash card, 128 MB included (expandable)	slot for Compact Flash card, 128 MB included (expandable)
256 MB DDR RAM (not expandable)	256 MB DDR RAM (expandable ex factory to 1 GB)	256 MB DDR RAM (expandable ex factory to 1 GB)
1 x RJ45 10/100 Mbit/s	2 x RJ45 10/100 Mbit/s (internal switch)	2 x RJ45 10/100 Mbit/s (internal switch)
via power supply module (E-bus, K-bus, K-bus/IP-Link)	via power supply module (E-bus, K-bus, K-bus/IP-Link)	via power supply module (E-bus, K-bus, K-bus/IP-Link)
<b>modularly expandable</b>	<b>modularly expandable</b>	<b>modularly expandable</b>
CX1010-N010	CX1020-N010	CX1030-N010
–	–	–
CX1010-N030 (COM 1/2)	CX1020-N030 (COM 1/2)	CX1030-N030 (COM 1/2)
CX1010-N040 (COM 3/4)	CX1020-N040 (COM 3/4)	CX1030-N040 (COM 3/4)
CX1010-N031 (COM 1/2)	CX1020-N031 (COM 1/2)	CX1030-N031 (COM 1/2)
CX1010-N041 (COM 3/4)	CX1020-N041 (COM 3/4)	CX1030-N041 (COM 3/4)
CX1010-N020	CX1020-N020	CX1030-N020
CX1010-N060	CX1020-N060	CX1030-N060
–	–	–
–	–	–
in the basic CPU	–	–
–	–	–
<b>modularly expandable</b>	<b>modularly expandable</b>	<b>modularly expandable</b>
–	–	–
EL6695 slave	EL6695 slave	EL6695 slave
CX1500-M200 master	CX1500-M200 master	CX1500-M200 master
CX1500-M310 master	CX1500-M310 master	CX1500-M310 master
CX1500-B310 slave	CX1500-B310 slave	CX1500-B310 slave
CX1500-M510 master	CX1500-M510 master	CX1500-M510 master
CX1500-B510 slave	CX1500-B510 slave	CX1500-B510 slave
CX1500-M520 master	CX1500-M520 master	CX1500-M520 master
CX1500-B520 slave	CX1500-B520 slave	CX1500-B520 slave
–	–	–
–	–	–
CX1500-M750 SERCOS II master	CX1500-M750 SERCOS II master	CX1500-M750 SERCOS II master
<b>CX1100-0910, -0900</b>	<b>CX1100-0920</b>	<b>CX1100-0930</b>

# The I/O Company

Beckhoff supplies a complete range of fieldbus components for all common I/O and bus systems. With Bus Terminals offering IP 20 protection and Fieldbus Box modules in IP 67, a comprehensive range of devices is available for a wide variety of signal types and fieldbus systems. In addition to components for conventional bus systems, Beckhoff offers an integrated product range optimized for EtherCAT. Invented by Beckhoff, this real-time Ethernet solution for industrial automation has global acceptance and is characterized by outstanding performance and simple handling. The result is high-precision machine and plant control and significantly increased production efficiency.

► [www.beckhoff.com/io](http://www.beckhoff.com/io)

► [www.beckhoff.com/ethercat](http://www.beckhoff.com/ethercat)

## EtherCAT Box 50

- IP 67 EtherCAT I/O system
  - high performance for harsh environments
  - compact and robust
  - can be mounted directly on machines, outside of control cabinets and terminal boxes
  - integrated sensor/actuator supply directly via EtherCAT P
- [www.beckhoff.com/ethercat-box](http://www.beckhoff.com/ethercat-box)

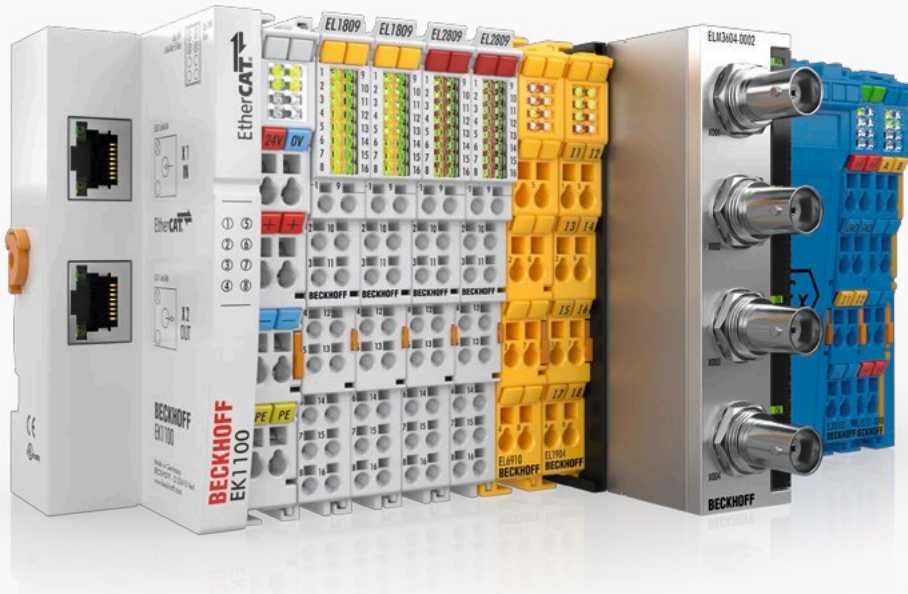
## EtherCAT Plug-in Modules 58

- very compact EtherCAT I/O system in IP 20 for plug-in into a circuit board (signal distribution board)
  - optimized for high-volume production
  - application-specific connector interface
  - Use of cable harnesses avoids wiring errors.
- [www.beckhoff.com/ethercat-plug-in-modules](http://www.beckhoff.com/ethercat-plug-in-modules)

## Bus Terminals 62

- open, fieldbus-neutral IP 20 I/O system
  - more than 400 different Bus Terminals
  - support for more than 20 fieldbus systems
  - gateways for subordinate bus systems
  - system-integrated safety I/O terminals available
- [www.beckhoff.com/busterminal](http://www.beckhoff.com/busterminal)





### EtherCAT Terminals 36

- IP 20 EtherCAT I/O system
- real-time Ethernet performance retained into each terminal
- standard digital and analog signals
- complex automation functions directly in the terminal system
- highly precise measurement technology
- condition monitoring
- drive technology
- process technology
- electronic overcurrent protection
- gateways for subordinate fieldbus systems
- TwinSAFE PLC and safety I/Os

► [www.beckhoff.com/ethercat-terminal](http://www.beckhoff.com/ethercat-terminal)

### Fieldbus Box 70

- open, fieldbus-neutral IP 67 I/O system
- 12 fieldbus systems, 24 signal types
- compact and robust
- can be mounted directly on machines, outside of control cabinets and terminal boxes while reducing machine footprint
- IO-Link box modules for inexpensive point-to-point connections

► [www.beckhoff.com/fieldbusbox](http://www.beckhoff.com/fieldbusbox)

### Infrastructure Components 73

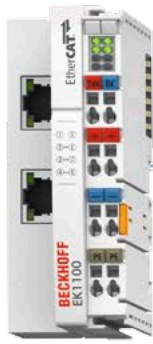
- PC cards for all common fieldbus systems
- Industrial Ethernet switches
- EtherCAT junctions and media converters in IP 20 and IP 67 ratings
- EtherCAT G/G10 components

► [www.beckhoff.com/infrastructure-components](http://www.beckhoff.com/infrastructure-components)



- comprehensive, modular I/O system for all signal types and fieldbus systems
- universal product range optimized for EtherCAT
- high investment security: mature I/O technology based on more than 25 years of success in the field
- Beckhoff is the I/O pioneer, developing the Bus Terminal concept and EtherCAT.

# System overview EtherCAT I/O



EK EtherCAT Coupler series



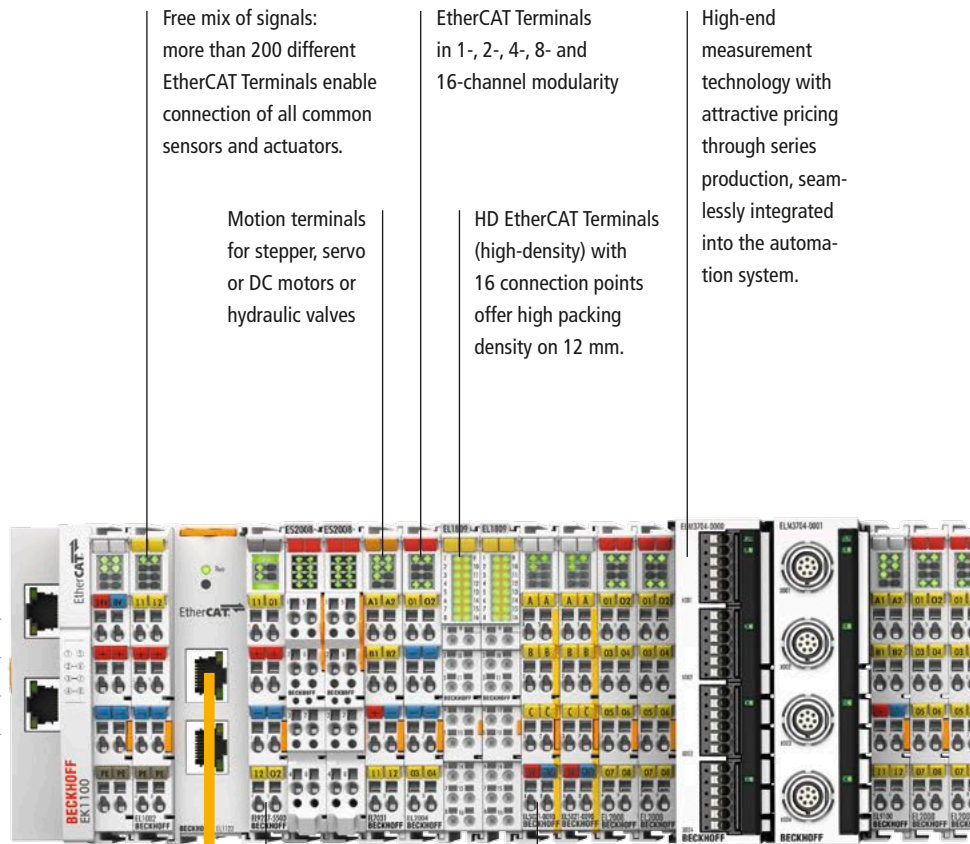
EtherCAT Coupler with integrated digital I/Os



Bus Coupler (e.g. PROFIBUS) for EtherCAT Terminals



Embedded PC series CX, further Embedded PCs see page 22



Free mix of signals: more than 200 different EtherCAT Terminals enable connection of all common sensors and actuators.

Motion terminals for stepper, servo or DC motors or hydraulic valves

EtherCAT Terminals in 1-, 2-, 4-, 8- and 16-channel modularity

HD EtherCAT Terminals (high-density) with 16 connection points offer high packing density on 12 mm.

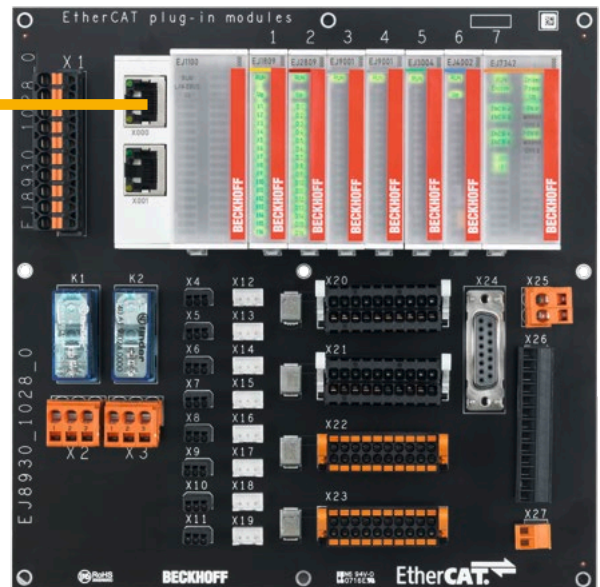
High-end measurement technology with attractive pricing through series production, seamlessly integrated into the automation system.

100 m Industrial Ethernet cable (100BASE-TX)

Integrated electronic overcurrent protection for safeguarding of potential groups incl. monitoring function

With the aid of the TwinSAFE SC technology it is possible to make use of standard signals for safety tasks in any network or fieldbus.

EtherCAT plug-in modules: very compact EtherCAT I/O system in IP 20 for plug-in into a circuit board (signal distribution board)



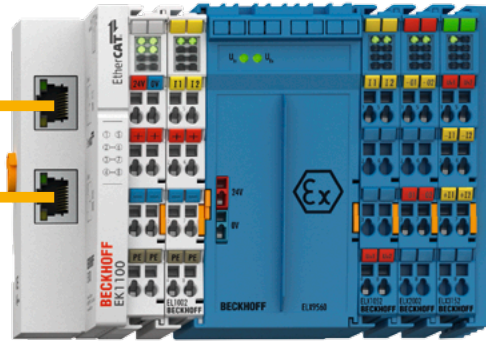


TwinSAFE: safety I/Os and compact Safety PLC for up to 212 safety-relevant bus devices

Optional fieldbus integration via decentralized fieldbus master/slave terminals

Ultra-fast I/O terminals for I/O response times < 100 µs for fast I/O, oversampling and timestamping

High-speed measurement, high-precision measurement, condition monitoring, energy monitoring

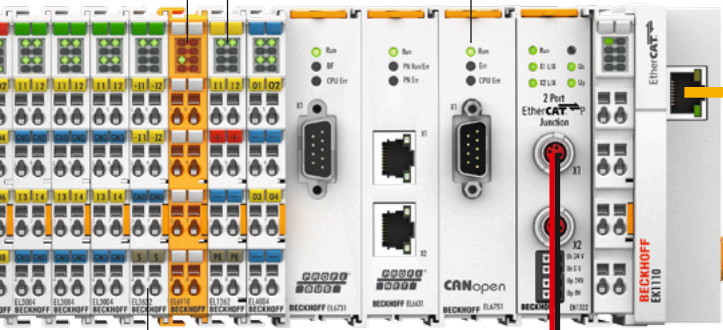


ELX terminals: direct connection of intrinsically safe sensors and actuators



2000/20,000 m fibre optic (100BASE-FX)

50 m Plastic Optical Fibre (100BASE-FX POF)



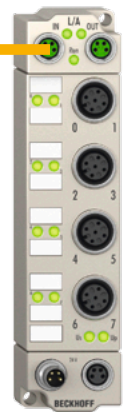
IP 67  
EtherCAT P  
Box



IP 67  
EtherCAT  
Box













IP 69K EtherCAT Box  
(stainless steel)



IP 67  
EtherCAT Box  
(die-cast zinc)

# Product overview fieldbus systems

Fieldbus	EtherCAT Terminals	EtherCAT Box	EtherCAT Plug-in Modules	Bus Terminals	Fieldbus Box	
	Couplers/Gateways	Modules		Bus Couplers/ Master terminals	PLC (IEC 61131-3)	Compact Box
EtherCAT 	EK1xxx, EKM1xxx	EPxxxx	EJxxxx	BK1120		
	EL6695 bridge	ERxxxx		BK1150		
		EQxxxx		BK1250		
EtherCAT 	EK13xx	EPPxxxx				
		EP1312				
LIGHTBUS	EL6720 master			BK20x0		IPxxxx-B200
	EK3100			BK3xx0	BC3150	IPxxxx-B31x
	EL6731 master/slave				BX3100	
	EL6740-0010 slave			BK40x0		IPxxxx-B400
CANopen	EL6751 master/slave			BK51xx	BC5150	IPxxxx-B51x
					BX5100	
DeviceNet	EL6752 master/slave			BK52x0	BX5200	IPxxxx-B52x
CC-Link	EL6711-0010 slave			BK7150		
Modbus	EK9000			BK7350		IPxxxx-B730
serCOS <small>the automation bus</small>				BK75x0		
	EL6021, EL6022	EP600x	EJ6002	BK8000	BC8050	IPxxxx-B800
		EPP600x		KL6021	BX8000	
				KL6041		
	EL6001, EL6002	EP600x	EJ6002	BK8100	BC8150	IPxxxx-B810
		EPP600x		KL6001	BX8000	
				KL6031		
Ethernet TCP/IP	EL6601, EL6614 switch port	EP6601		BK9xx0	BC9xxx	
		switch port			BX9000	
	EK9300	EP9300		BK9xx3		
	EL6631 RT controller/device					
	EL6632 IRT controller					
EtherNet/IP	EK9500			BK9xx5		
	EL6652 scanner/adapter					
AS-Interface	EL6201			KL62x1		
IO-Link	EL6224 master	EP622x,	EJ6224	KL6224 master		
		EPP6228 master	master			
EIB/KNX				KL6301		
LON				KL6401		
MP-Bus				KL6771		
M-Bus				KL6781		
DALI/DSI				KL6811		
DALI-2				KL6821		
IEEE 1588	EL6688					
DMX	EL6851					
EnOcean				KL658x		
SMI				KL6841		
BACnet	EL6861					








# EtherCAT Terminals

► [www.beckhoff.com/ethercat-terminal](http://www.beckhoff.com/ethercat-terminal)



EK1xxx, BK1xx0   EtherCAT Couplers									
	EtherCAT				EtherCAT P	EtherCAT G	Ethernet/TSN		
<b>EtherCAT Couplers E-bus</b>	<b>EK1100</b> 2 x RJ45	<b>EK1101</b> ID switch	<b>EK1101-0010</b> ID switch, Extended Distance	<b>EK1101-0080</b> ID switch, Fast Hot Connect	<b>EK1300</b> EtherCAT P	<b>EK1400</b> EtherCAT G	<b>EK1000</b> Ethernet/TSN	<b>i</b>	<b>i</b>
	<b>EK1100-0008</b> M8 connection	<b>EK1101-0008</b> ID switch, M8 connection		<b>EKM1101</b> ID switch and diagnostics					
	<b>EK1501</b> ID switch, multimode fibre optic	<b>EK1501-0010</b> ID switch, singlemode fibre optic	<b>EK1501-0100</b> ID switch, multimode fibre optic to RJ45	<b>EK1541</b> ID switch, POF					
<b>EtherCAT Couplers E-bus with integrated digital I/Os</b>	<b>EK1814</b> 4 inputs + 4 outputs	<b>EK1818</b> 8 inputs + 4 outputs	<b>EK1828</b> 4 inputs + 8 outputs	<b>EK1828-0010</b> 8 outputs					
	<b>EK1914</b> 4 standard inputs, 4 standard outputs, 2 safe inputs, 2 safe outputs	<b>EK1960</b> TwinSAFE Logic, 20 safe inputs, 24 safe outputs							
<b>EtherCAT Couplers K-bus</b>	<b>BK1120</b> Bus Coupler (Economy plus)	<b>BK1150</b> Bus Coupler (Compact)	<b>BK1250</b> E-bus to K-bus interface						
<b>Extensions</b>	<b>EK1110</b> extension end terminal	<b>EK1110-0008</b> extension end terminal, M8	<b>EK1110-0043</b> EtherCAT EJ coupler, CX and EL terminal connection	<b>EK1110-0044</b> EtherCAT EJ coupler, CX and EL terminal connection, EtherCAT junction	<b>EK1310</b> EtherCAT P extension with feed-in				
<b>Junctions</b>	<b>EK1122</b> 2-port junction	<b>EK1122-0008</b> 2-port junction, M8	<b>EK1121-0010</b> 1-port junction, Extended Distance	<b>EK1122-0080</b> 2-port junction, Fast Hot Connect	<b>EK1322</b> EtherCAT P junction with feed-in				
	<b>EK1521</b> multimode fibre optic junction	<b>EK1521-0010</b> singlemode fibre optic junction		<b>EK1561</b> POF junction					

EKxxxx   Bus Couplers	
<b>Fieldbus</b>	<b>Standard</b>
 <b>EK9160</b> IoT (MQTT, OPC UA)	
<b>EtherNet/IP</b>	<b>EK9500</b> 100 Mbit/s
<b>Modbus</b>	<b>EK9000</b> 100 Mbit/s
 <b>EK3100</b> 12 Mbaud	
 <b>EK9300</b> 100 Mbit/s	

Embedded PCs with E-bus interface see page **22** , Infrastructure Components see page **73**

**i** **Product announcement** for availability status see [www.beckhoff.com](http://www.beckhoff.com)

## EL1xxx | EtherCAT Terminals, digital input

Signal	2-channel	4-channel	8-channel	16-channel		
5 V DC	EL1252-0050 <small>T<sub>ON</sub>/T<sub>OFF</sub> 1 μs, timestamping</small>	EL1124 <small>filter 0.05 μs</small>				
	EL1262-0050 <small>T<sub>ON</sub>/T<sub>OFF</sub> 1 μs, oversampling</small>					
12 V DC		EL1144 <small>filter 10 μs</small>				
24 V DC, filter 3.0 ms	EL1002 <small>type 3</small>	EL1004 <small>type 3</small>	EL1008 <small>type 3, 1-wire</small>	EL1809 <small>type 3</small>		
		EL1104 <small>type 3, with sensor supply</small>	EL1804 <small>type 3, 8 x 24 V, 4 x 0 V</small>	EL1808 <small>type 3, 8 x 24 V DC, 2-wire</small>	EL1852 <small>type 3, 8 inputs, 8 outputs, I<sub>max</sub> = 0.5 A, flat-ribbon cable</small>	EL1859 <small>type 3, 8 inputs, 8 outputs, I<sub>max</sub> = 0.5 A</small>
		EL1084 <small>ground switching</small>	EL1024 <small>type 2</small>	EL1088 <small>ground switching</small>	EL1862 <small>type 3, flat-ribbon cable</small>	EL1862-0010 <small>flat-ribbon cable, ground switching</small>
					EL1889 <small>ground switching</small>	
24 V DC, filter 10 μs	EL1012 <small>type 3</small>	EL1014 <small>type 3</small>	EL1034 <small>type 1, potential-free inputs</small>	EL1018 <small>type 3</small>	EL1819 <small>type 3</small>	
		EL1114 <small>type 3, with sensor supply</small>	EL1814 <small>type 3, 8 x 24 V, 4 x 0 V, 3-wire</small>		EL1872 <small>type 3, flat-ribbon cable</small>	EL1872-0010 <small>flat-ribbon cable, ground switching</small>
			EL1094 <small>ground switching</small>	EL1098 <small>ground switching</small>	EL1899 <small>ground switching</small>	
24 V DC, XFC: T <sub>ON</sub> /T <sub>OFF</sub> 1 μs	EL1202 <small>type 3</small>					
	EL1252 <small>type 3, timestamping</small>	EL1254 <small>type 3, timestamping</small>		EL1258 <small>multi-timestamping</small>	EL1259 <small>8 inputs, 8 outputs, multi- timestamping, I<sub>max</sub> = 0.5 A</small>	
	EL1262 <small>type 3, oversampling</small>			EL1258-0010 <small>multi-timestamping, ground switching</small>		
24 V DC, counter	EL1502 <small>type 1, 100 kHz, 32 bit</small>					
	EL1512 <small>type 1, 1 kHz, 32 bit</small>					
24 V DC, safe input		EL1904 <small>TwinSAFE, 4 safe inputs</small>	EL2911 <small>TwinSAFE Logic, 4 safe inputs, 1 safe output</small>	EL1918 <small>TwinSAFE Logic, 8 safe inputs</small>		
48 V DC		EL1134 <small>type 1</small>				
120 V AC/DC	EL1712 <small>power contacts</small>					
120 V DC	EL1712-0020 <small>power contacts</small>					

The standard EtherCAT Terminals (ELxxxx) can be optionally ordered as ESxxxx with pluggable wiring level.

## EL1xxx | EtherCAT Terminals, digital input

Signal	2-channel	4-channel	8-channel	16-channel
120... 230 V AC	EL1702 power contacts <i>i</i>			
	EL1722 no power contacts <i>i</i>			
220 V DC	EL1702-0020 power contacts <i>i</i>			
Thermistor	EL1382			
NAMUR	EL1052	EL1054		
Ex i, NAMUR	ELX1052	ELX1054	ELX1058	

## EL2xxx | EtherCAT Terminals, digital output

Signal	1-channel	2-channel	4-channel	8-channel	16-channel
5 V DC			EL2124 $I_{max} = \pm 20 \text{ mA}$		
12 V DC			EL2024-0010 $I_{max} = 2.0 \text{ A}$		
24 V DC, $I_{max} = 0.5 \text{ A}$		EL2002 4-wire	EL2004 2-wire	EL2008 1-wire	EL2809 $I_{max} = 0.5 \text{ A}$ EM2042 D-sub connection
			EL2014 with diagnostics	EL2878-0005 flat-ribbon cable, with diagnostics	EL2872 flat-ribbon cable EL2872-0010 flat-ribbon cable, ground switching
				EL2808 8 x 0 V	EL2819 with diagnostics EL1859 type 3, 8 inputs, 8 outputs, $I_{max} = 0.5 \text{ A}$
			EL2084 ground switching	EL2088 ground switching	EL2889 ground switching EL1852 type 3, 8 inputs, 8 outputs, $I_{max} = 0.5 \text{ A}$ , flat-ribbon cable
24 V DC, $I_{max} = 2.0 \text{ A}$		EL2022 4-wire	EL2024 3-wire	EL2828	
		EL2032 with diagnostics	EL2034 with diagnostics		
			EL2044 with extended diagnostics		
24 V DC, $I_{max} = 4.0 \text{ A}/8.0 \text{ A}$		EL2042 2 x 4.0 A/1 x 8.0 A			
24 V DC, XFC: $T_{ON}/T_{OFF} 1 \mu\text{s}$		EL2202 push-pull outputs	EL2212 overexcitation, multi-timestamping	EL2258 multi-timestamping	EL1259 8 inputs, 8 outputs, multi-timestamping, $I_{max} = 0.5 \text{ A}$
		EL2252 timestamping	EL2262 oversampling		
Ex i, 24 V DC		ELX2002 45 mA		ELX2008 30 mA	
24 V DC, safe output	EL2911 TwinSAFE Logic, 4 safe inputs, 1 safe output	EL2912 TwinSAFE Logic, 2 safe outputs	EL2904 TwinSAFE, 4 safe outputs		

The standard EtherCAT Terminals (ELxxxx) can be optionally ordered as ESxxxx with pluggable wiring level.

## EL2xxx | EtherCAT Terminals, digital output

Signal	1-channel	2-channel	4-channel	8-channel	16-channel
30 V AC/ 48 V DC solid state relay, $I_{max} = 2.0 A$			EL2784	EL2788	
			EL2794 potential-free	EL2798 potential-free	
Relay (up to 250 V AC)		<b>EL2602</b> $I_{max} = 5.0 A$ , make contact, power contacts	<b>EL2622</b> $I_{max} = 5.0 A$ , make contact, no power contacts	<b>EL2624</b> $I_{max} = 2.0 A$ , make contact	
		<b>EL2602-0010</b> $I_{max} = 5.0 A$ , make contact, power contacts, contact-protecting switching	<b>EL2622-0010</b> $I_{max} = 5.0 A$ , make contact, no power contacts, contact-protecting switching	<b>EL2634</b> $I_{max} = 4.0 A$ , make contact, 250 V AC/30 V DC, no power contacts	
		<b>EL2612</b> $I_{max} = 2.0 A$ , change-over, no power contacts	<b>EL2642</b> <u>i</u> $I_{max} = 1.0 A$ , change-over, no power contacts, reed relays		
		<b>EL2652</b> $I_{max} = 1.0 A$ , change-over, no power contacts			
Triac (12...230 V AC)		<b>EL2712</b> <u>i</u> $I_{max} = 0.5 A$ , power contacts	<b>EL2722</b> <u>i</u> $I_{max} = 1.0 A$ , mutually locked outputs		
		<b>EL2732</b> <u>i</u> $I_{max} = 0.5 A$ , no power contacts			
PWM		<b>EL2502</b> push-pull outputs, separate frequency can be set for each channel	<b>EL2502-0010</b> push-pull outputs, separate frequency can be set for each channel, timestamping		
		<b>EL2535</b> 24 V DC, $I_{max} = \pm 50 mA$ , $\pm 1 A$ , $\pm 2 A$	<b>EL2535-0005</b> 24 V DC, $I_{max} = \pm 5 A$		
Frequency output	<b>EL2521</b> 1-channel AB, 0...500 kHz, RS422	<b>EL2522</b> 2-channel AB, 1-channel ABC, 0...4 MHz			
Current control, LED control	<b>EL2595</b> LED constant current terminal				
	<b>EL2596</b> 24 V DC				
	<b>EL2596-0010</b> <u>i</u> 48 V DC				
Multiplexer		<b>ELM2742-0000</b> 2 x multiplexer, 1 x 4 solid-state relays	<b>ELM2744-0000</b> 4 x multiplexer, 1 x 4 solid-state relays		
		<b>ELM2642-0000</b> 2 x multiplexer, 1 x 4 reed relays	<b>ELM2644-0000</b> 4 x multiplexer, 1 x 4 reed relays		

## EL3xxx | EtherCAT Terminals, analog input

Signal	1-channel		2-/3-channel		4-channel		5-/6-/8-channel	
<b>±10 V</b>	<b>EL3001</b> single-ended, 12 bit		<b>EL3002</b> single-ended, 12 bit		<b>EL3004</b> single-ended, 12 bit		<b>EL3008</b> single-ended, 12 bit	
	<b>EL3101</b> differential input, 16 bit		<b>EL3102</b> differential input, 16 bit		<b>EL3602</b> differential input, 24 bit		<b>EL3104</b> differential input, 16 bit	
			<b>EL3702</b> differential input, 16 bit, oversampling					
<b>0...10 V</b>	<b>EL3061</b> 12 bit	<b>EL3161</b> 16 bit	<b>EL3062</b> 12 bit	<b>EL3162</b> 16 bit	<b>EL3064</b> 12 bit	<b>EL3164</b> 16 bit	<b>EL3068</b> 12 bit	
<b>0...30 V</b>			<b>EL3062-0030</b> 12 bit					
<b>±30 V... ±20 mV</b>			<b>ELM3002-0000</b> 24 bit, 20 ksps, push-in		<b>ELM3004-0000</b> 24 bit, 10 ksps, push-in			
<b>±200 mV</b>			<b>EL3602-0002</b> differential input, 24 bit					
<b>±150 mV</b>			<b>EL3702-0015</b> differential input, 16 bit, oversampling					
<b>±75 mV</b>			<b>EL3602-0010</b> differential input, 24 bit					
<b>±10 V/ 0...20 mA</b>					<b>EL3174</b> 16 bit, NAMUR NE43		<b>EL3174-0002</b> 16 bit, electrically isolated, NAMUR NE43	
					<b>EL3174-0032</b> 16 bit, electrically isolated, NAMUR NE43, ±3 V		<b>EL3174-0090</b> 16 bit, NAMUR NE43, TwinSAFE SC	
			<b>ELM3142-0000</b> 24 bit, 1 ksps, push-in		<b>ELM3144-0000</b> 24 bit, 1 ksps, push-in		<b>ELM3146-0000</b> 24 bit, 1 ksps, push-in	
<b>0...20 mA</b>	<b>EL3041</b> single-ended, 12 bit		<b>EL3141</b> single-ended, 16 bit		<b>EL3042</b> single-ended, 12 bit		<b>EL3142</b> single-ended, 16 bit	
	<b>EL3011</b> differential input, 12 bit		<b>EL3111</b> differential input, 16 bit		<b>EL3742</b> differential input, 16 bit, oversampling		<b>EL3012</b> differential input, 12 bit	
					<b>EL3112</b> differential input, 16 bit		<b>EL3612</b> differential input, 24 bit	
<b>4...20 mA</b>	<b>EL3051</b> single-ended, 12 bit		<b>EL3151</b> single-ended, 16 bit		<b>EL3052</b> single-ended, 12 bit		<b>EL3152</b> single-ended, 16 bit	
	<b>EL3021</b> differential input, 12 bit		<b>EL3121</b> differential input, 16 bit		<b>EL3022</b> differential input, 12 bit		<b>EL3122</b> differential input, 16 bit	
			<b>EL3621-0020</b> differential input, 24 bit		<b>EL3182</b> single-ended, 16 bit, HART		<b>EL3124-0090</b> 16 bit, TwinSAFE SC	
<b>Ex i, 0/4...20 mA</b>	<b>ELX3181</b> 4...20 mA, single-ended, 16 bit, HART		<b>ELX3152</b> 0/4...20 mA, single-ended, 16 bit		<b>ELX3152-0090</b> 0/4...20 mA, single-ended, 16 bit, TwinSAFE SC		<b>ELX3184</b> 4...20 mA, single-ended, 16 bit, HART	
<b>±20 mA</b>			<b>EL3112-0011</b> differential input, 16 bit		<b>ELM3102-0000</b> 24 bit, 20 ksps, NAMUR NE43, push-in		<b>ELM3104-0000</b> 24 bit, 10 ksps, NAMUR NE43, push-in	
<b>Multi-function</b>	<b>EL3751</b> 24 bit, 10 ksps		<b>EL3751-0004</b> 24 bit, 10 ksps		<b>ELM3702-0000</b> 24 bit, 10 ksps, push-in		<b>ELM3704-0000</b> 24 bit, 10 ksps, push-in	
							<b>ELM3704-0001</b> 24 bit, 10 ksps, LEMO	

The standard EtherCAT Terminals (ELxxxx) can be optionally ordered as ESxxxx with pluggable wiring level.



## EL3xxx | EtherCAT Terminals, analog input

Signal	1-channel		2-/3-channel		4-channel		5-/6-/8-channel	
Thermo-couple/mV	EL3311 16 bit		EL3312 16 bit		EL3314 16 bit	EL3314-0090 16 bit, TwinSAFE SC	EL3318 16 bit	
					EL3314-0002 24 bit, electrically isolated	ELM3344-0000 <i>i</i> 24 bit, 1 ksps, push-in	ELM3348-0000 <i>i</i> 24 bit, 1 ksps, push-in	
					EL3314-0010 24 bit	ELM3344-0003 <i>i</i> 24 bit, 1 ksps, push-in, Mini-TC universal	ELM3348-0003 <i>i</i> 24 bit, 1 ksps, push-in, Mini-TC universal	
Ex i, thermo-couple/mV			ELX3312 2-wire connection, 16 bit	ELX3312-0090 2-wire connection, 16 bit, TwinSAFE SC	ELX3314 2-wire connection, 16 bit	ELX3314-0090 2-wire connection, 16 bit, TwinSAFE SC		
Resistance thermometer (RTD)	EL3201 16 bit		EL3202 16 bit		EL3204 2-wire, 16 bit		EL3208 16 bit	
					EL3204-0162 2-wire, 16 bit, 2 x RTD, 2 x ±10 V	EL3204-0200 16 bit, universal input for RTD	EL3208-0010 Pt1000, Ni1000, NTC 1.8...100 k, potentiom. 1, 5, 10 kΩ	
					EL3214 3-wire, 16 bit	EL3214-0090 16 bit, TwinSAFE SC	EL3218 3-wire, 16 bit	
Ex i, resistance thermometer (RTD)			ELX3202 RTD for 2-, 3- and 4-wire connection, 16 bit	ELX3202-0090 RTD for 2-, 3- and 4-wire connection, 16 bit, TwinSAFE SC	ELX3204 RTD, 2-wire connection, 16 bit	ELX3204-0090 RTD, 2-wire connection, 16 bit, TwinSAFE SC		
Measurement bridge (SG)	EL3351 16 bit	EL3356 self-calibration	ELM3502-0000 24 bit, 20 ksps, push-in		ELM3504-0000 24 bit, 10 ksps, push-in			
	EL3356-0010 24 bit, 10 ksps	EL3356-0090 TwinSAFE SC	ELM3542-0000 <i>i</i> 24 bit, 1 ksps, push-in		ELM3544-0000 <i>i</i> 24 bit, 1 ksps, push-in			
Ex i, measurement bridge (SG)	ELX3351 24 bit	ELX3351-0090 24 bit, TwinSAFE SC						
Measurement technology	EL3681 digital multimeter terminal, 18 bit		EL3692 resistance measurement, 100 mΩ...10 MΩ				EL3255 potentiometer measure- ment, 5-channel	
Ex i, measurement technology			ELX3252 potentiometer measure- ment, 16 bit					
Condition monitoring/ IEPE			EL3632 16 bit, 50 ksps	ELM3602-0000 24 bit, 50 ksps, push-in	ELM3604-0000 24 bit, 20 ksps, push-in			
				ELM3602-0002 24 bit, 50 ksps, BNC	ELM3604-0002 24 bit, 20 ksps, BNC			
Pressure measuring	EM3701 differential pressure, ±100 hPa		EM3702 relative pressure, 7500 hPa	EM3712 relative pressure, ±1000 hPa				
Power measurement, ≤ 500 V			EL3403 500 V AC, 1 A	EL3423 480 V AC/DC, 1 A, Economy				
			EL3433 500 V AC, 10 A	EL3443 480 V AC/DC, 1 A, extended functionalities			EL3446 distributed power measurement	
			EL3443-0010 480 V AC/DC, 5 A, extended functionalities	EL3443-0011 480 V AC/DC, 100 mA, extended functionalities				
			EL3443-0013 480 V AC/DC, 333 mV, extended functionalities					

## EL3xxx | EtherCAT Terminals, analog input

Signal	1-channel	2-/3-channel	4-channel	5-/6-/8-channel
Power measurement, > 500 V		<b>EL3413</b> 690 V AC, 5 A		
		<b>EL3453</b> 690 V AC, 5 A, extended functionalities	<b>EL3453-0100</b>  690 V AC, 5 A, extended functionalities	
Mains monitor, ±480 V		<b>EL3483</b> 480 V AC/DC	<b>EL3483-0060</b> 480 V AC/DC, with voltage measurement	
Power monitoring, ≤ 500 V		<b>EL3773</b> 500 V AC/DC, 10 ksps		
Power monitoring, > 500 V		<b>EL3783</b> 690 V AC, 20 ksps	<b>EL3783-0100</b>  130 V AC, 20 ksps	

## EL4xxx | EtherCAT Terminals, analog output

Signal	1-channel	2-channel	4-channel	8-channel		
0...10 V	<b>EL4001</b> 12 bit	<b>EL4002</b> 12 bit	<b>EL4102</b> 16 bit	<b>EL4004</b> 12 bit	<b>EL4104</b> 16 bit	<b>EL4008</b> 12 bit
±10 V	<b>EL4031</b> 12 bit	<b>EL4032</b> 12 bit	<b>EL4132</b> 16 bit	<b>EL4034</b> 12 bit	<b>EL4134</b> 16 bit	<b>EL4038</b> 12 bit
		<b>EL4732</b> 16 bit, oversampling				
0...20 mA	<b>EL4011</b> 12 bit	<b>EL4012</b> 12 bit	<b>EL4112</b> 16 bit	<b>EL4014</b> 12 bit	<b>EL4114</b> 16 bit	<b>EL4018</b> 12 bit
		<b>EL4712</b> 16 bit, oversampling				
4...20 mA	<b>EL4021</b> 12 bit	<b>EL4022</b> 12 bit		<b>EL4024</b> 12 bit		<b>EL4028</b> 12 bit
		<b>EL4122</b> 16 bit		<b>EL4124</b> 16 bit		
Ex i, 0/4...20 mA	<b>ELX4181</b> single-ended, 16 bit, HART			<b>ELX4154</b> single-ended, 16 bit		
±10 mA		<b>EL4112-0010</b> 16 bit				

The standard EtherCAT Terminals (ELxxxx) can be optionally ordered as ESxxxx with pluggable wiring level.

## EL5xxx | EtherCAT Terminals, position measurement

Signal	1-channel			2-channel	
<b>Absolute position measurement</b>	<b>EL5001</b> SSI encoder interface	<b>EL5001-0011</b> SSI monitor interface	<b>EL5001-0090</b> SSI encoder interface, TwinSAFE SC	<b>EL5002</b> SSI encoder interface	<b>EL5032</b> EnDat 2.2 interface
				<b>EL5032-0090</b> EnDat 2.2 interface, TwinSAFE SC	<b>EL5042</b> BISS C interface
				<b>EL5072</b> inductive displacement sensor interface, LVDT	
<b>Incremental position measurement</b>	<b>EL5021</b> SinCos encoder interface, 1 V <sub>PP</sub>	<b>EL5021-0090</b> SinCos encoder interface, 1 V <sub>PP</sub> , TwinSAFE SC			
	<b>EL5101</b> incremental encoder interface, RS422, TTL, 1 MHz	<b>EL5101-0010</b> incremental encoder interface, RS422, 5 MHz	<b>EL5101-0011</b> incremental encoder interface, RS422, 5 MHz, oversampling	<b>EL5102</b> incremental encoder interface, RS422, TTL, Open Collector, 5 MHz	<b>EL5112</b> incremental encoder interface, RS422, TTL, Open Collector, 5 MHz, 2 x AB/1 x ABC
	<b>EL5101-0090</b> incremental encoder interface, RS422, TTL, 1 MHz, TwinSAFE SC	<b>EL5131</b> incremental encoder interface, RS422, TTL, 2 x 24 V DC push-pull outputs	<b>i</b>	<b>EL5122</b> incremental encoder interface, TTL, Open Collector, 1 MHz, 2 x AB	
	<b>EL5151</b> incremental encoder interface, 24 V HTL, 100 kHz	<b>EL5151-0021</b> incremental encoder interface, 24 V HTL, 100 kHz, 1 x 24 V DC output	<b>EL5151-0090</b> incremental encoder interface, 24 V HTL, 100 kHz, TwinSAFE SC	<b>EL5152</b> incremental encoder interface, 24 V HTL, 100 kHz	
<b>Ex i, incremental position measurement</b>	<b>ELX5151</b> incremental encoder interface, NAMUR	<b>ELX5151-0090</b> incremental encoder interface, NAMUR, TwinSAFE SC			

## EL6xxx | EtherCAT Terminals, communication

Signal	1-channel			2-channel		4-channel
<b>System</b>	<b>EL6070</b> license key terminal	<b>EL6080</b> memory terminal 128 kbyte	<b>EL6090</b> display terminal			
<b>Serial</b>	<b>EL6001</b> RS232, 115.2 kbaud	<b>EL6021</b> RS422/RS485, 115.2 kbaud		<b>EL6002</b> RS232, 115.2 kbaud, D-sub	<b>EL6022</b> RS422/RS485, 115.2 kbaud, D-sub	
<b>EtherCAT/Ethernet</b>	<b>EL6601</b> switch port	<b>EL6688</b> IEEE 1588 master/slave		<b>EL6692</b> EtherCAT bridge	<b>EL6695</b> EtherCAT bridge, high performance	<b>EL6614</b> switch port
<b>Master/slave, slave function -0010</b>	<b>EL6201</b> AS-Interface, master	<b>EL6631</b> PROFINET RT, controller/device terminal		<b>EL6632</b> PROFINET IRT, controller	<b>i</b> <b>EL6652</b> EtherNet/IP, scanner/ adapter terminal	<b>EL6224</b> IO-Link, master
	<b>EL6711-0010</b> CC-Link, slave	<b>i</b> <b>EL6720</b> Lightbus, master	<b>EL6731</b> PROFIBUS DP, master/slave			<b>EL6224-0090</b> IO-Link, TwinSAFE SC, master
	<b>EL6740-0010</b> Interbus, slave	<b>EL6751</b> CANopen, master/slave	<b>EL6752</b> DeviceNet, master/slave			
	<b>EL6851</b> DMX, master/slave	<b>EL6861</b> BACnet, MS/TP, RS485, master				
<b>Safety</b>	<b>EL6900</b> TwinSAFE Logic	<b>EL6910</b> TwinSAFE Logic, PROFIsafe master and slave support	<b>EL6930</b> TwinSAFE Logic, PROFIsafe slave support			

## EL7xxx | EtherCAT Terminals, motion

Motor type	< 3 A	3...5 A	> 5 A	16 A	
<b>Servomotor</b>			<b>ELM7211-9016</b> <i>I<sub>rms</sub></i> = 4.5 A, 48 V DC	<b>i</b>	
			<b>ELM7211-9018</b> <i>I<sub>rms</sub></i> = 4.5 A, 48 V DC, Safe Motion	<b>i</b>	
			<b>ELM7212-9016</b> <i>I<sub>rms</sub></i> = 2 x 4.5 A, 48 V DC	<b>i</b>	<b>ELM7222-9016</b> <i>I<sub>rms</sub></i> = 2 x 8.0 A, 48 V DC
			<b>ELM7212-9018</b> <i>I<sub>rms</sub></i> = 2 x 4.5 A, 48 V DC, Safe Motion	<b>i</b>	<b>ELM7222-9018</b> <i>I<sub>rms</sub></i> = 2 x 8.0 A, 48 V DC, Safe Motion
	<b>EL7201-0010</b> <i>I<sub>rms</sub></i> = 2.8 A, 48 V DC, OCT	<b>EL7211-0010</b> <i>I<sub>rms</sub></i> = 4.5 A, 48 V DC, OCT	<b>ELM7221-9016</b> <i>I<sub>rms</sub></i> = 8 A, 48 V DC	<b>i</b>	<b>ELM7231-9016</b> <i>I<sub>rms</sub></i> = 16 A, 48 V DC
	<b>EL7201</b> <i>I<sub>rms</sub></i> = 2.8 A, 48 V DC, resolver	<b>EL7211</b> <i>I<sub>rms</sub></i> = 4.5 A, 48 V DC, resolver	<b>ELM7221-9018</b> <i>I<sub>rms</sub></i> = 8 A, 48 V DC, Safe Motion	<b>i</b>	<b>ELM7231-9018</b> <i>I<sub>rms</sub></i> = 16 A, 48 V DC, Safe Motion
<b>EL7201-9014</b> <i>I<sub>rms</sub></i> = 2.8 A, 48 V DC, OCT, STO	<b>EL7211-9014</b> <i>I<sub>rms</sub></i> = 4.5 A, 48 V DC, OCT, STO	<b>EL7221-9014</b> <i>I<sub>rms</sub></i> = 7...8 A with ZB8610, 48 V DC, OCT, STO			
<b>Stepper motor</b>	<b>EL7031</b> <i>I<sub>max</sub></i> = 1.5 A, 24 V DC	<b>EL7041</b> <i>I<sub>max</sub></i> = 5.0 A, 48 V DC, incremental encoder			
	<b>EL7031-0030</b> <i>I<sub>max</sub></i> = 2.8 A, 24 V DC	<b>EL7041-0052</b> <i>I<sub>max</sub></i> = 5.0 A, 48 V DC			
	<b>EL7037</b> <i>I<sub>max</sub></i> = 1.5 A, 24 V DC, incremental encoder, vector control	<b>EL7047</b> <i>I<sub>max</sub></i> = 5.0 A, 48 V DC, incremental encoder, vector control			
		<b>EL7047-9014</b> <i>I<sub>max</sub></i> = 5.0 A, 48 V DC, incremental encoder, vector control, STO	<b>i</b>		
<b>DC motor output stage</b>	<b>EL7332</b> <i>I<sub>max</sub></i> = 1.0 A, 24 V DC	<b>EL7342</b> <i>I<sub>max</sub></i> = 3.5 A, 48 V DC, incremental encoder			
<b>BLDC</b>		<b>EL7411</b> <i>I<sub>rms</sub></i> = 4.5 A, 48 V DC			
		<b>EL7411-9014</b> <i>I<sub>rms</sub></i> = 4.5 A, 48 V DC, STO	<b>i</b>		
<b>4-axis interface</b>	<b>EM7004</b> 4 incremental encoders, 32 digital I/Os 24 V DC, 4 analog outputs ±10 V				

The standard EtherCAT Terminals (ELxxxx) can be optionally ordered as ESxxxx with pluggable wiring level.

## EL9xxx | EtherCAT Terminals, system

Signal	System				
<b>Components for system bus</b>	<b>EL9011</b> bus end cover	<b>EL9012</b> bus end cover for power and E-bus contacts	<b>ELM9012</b> bus end cover for ELMxxx, black	<b>ELX9012</b> bus end cover for ELX, blue	<b>EL9930</b> PROFIsafe, segment end terminal
	<b>EL9195</b> shield terminal	<b>EL9070</b> shield terminal	<b>EL9080</b> isolation terminal		
<b>Potential distribution</b>	<b>EL9180</b> 2 clamping units per power contact	<b>EL9181</b> 2 x 8 terminal points	<b>EL9182</b> 8 x 2 terminal points	<b>EL9183</b> 1 x 16 terminal points	<b>EL9184</b> 8 x 24 V DC, 8 x 0 V DC
	<b>EL9185</b> 4 clamping units at 2 power contacts	<b>EL9185-0010</b> 4 clamping units at 2 power contacts, potential supply function	<b>EL9186</b> 8 x 24 V DC	<b>EL9187</b> 8 x 0 V DC	<b>EL9188</b> 16 x 24 V DC
	<b>EL9189</b> 16 x 0 V DC				
<b>Potential supply, 24 V DC</b>	<b>EL9100</b>	<b>EL9110</b> diagnostics	<b>EL9200</b> with fuse	<b>EL9210</b> diagnostics, with fuse	<b>EL9520</b> AS-Interface potential supply with filter
<b>Potential supply, 120... 230 V AC</b>	<b>EL9150</b> with LED	<b>EL9160</b> diagnostics	<b>EL9190</b> any voltage up to 230 V	<b>EL9250</b> with fuse, with LED	<b>EL9260</b> diagnostics, with fuse
	<b>EL9290</b> with fuse				
<b>Overcurrent protection, 24 V DC</b>	<b>EL9221-xxxx</b> 1-channel	<b>EL9222-xxxx</b> 2-channel	<b>EL9227-xxxx</b> 2-channel, extended functionalities		
<b>Power supply</b>	<b>EL9410</b> input 24 V DC, output 5 V DC/2 A	<b>ELM9410</b> input 24 V DC, output 5 V DC/2 A	<b>ELX9410</b> power supply terminal for E-bus refresh, 1 A	<b>EL9505</b> input 24 V DC, output 5 V DC/0.5 A	<b>EL9508</b> input 24 V DC, output 8 V DC/0.5 A
	<b>EL9510</b> input 24 V DC, output 10 V DC/0.5 A	<b>EL9512</b> input 24 V DC, output 12 V DC/0.5 A	<b>EL9515</b> input 24 V DC, output 15 V DC/0.5 A	<b>EL9560</b> input 24 V DC, output 24 V DC/0.1 A with electrical isolation	<b>ELX9560</b> power supply, 24 V DC, electrically isolated
<b>Filtering and smoothing</b>	<b>EL9540</b> surge filter terminal for field supply	<b>EL9540-0010</b> surge filter terminal for field supply, onshore and offshore areas	<b>EL9550</b> surge filter terminal for system/field supply	<b>EL9550-0010</b> surge filter terminal for system/field supply, onshore and offshore areas	<b>EL9550-0012</b> surge filter terminal for system/field supply with up to 10 A
	<b>EL9570</b> buffer capacitor terminal, 500 µF, 48 V DC	<b>EL9576</b> brake chopper terminal, up to 72 V DC, 155 µF			

# Product overview current transformers

► [www.beckhoff.com/sct](http://www.beckhoff.com/sct)



SCT1111



SCT21xx

## SCT1xxx | Mini ring-type current transformers

Primary current	Max. diameter round conductor 7.6 mm
0...32 to 0...64 A AC	SCT1111 accuracy class 1

## SCT2xxx | Ring-type current transformers

Primary current	Max. diameter round conductor				
	25.7 mm	31.8 mm	43.7 mm	54.7 mm	70 mm
0...60 to 0...500 A AC	SCT2111 accuracy class 1				
0...125 to 0...600 A AC	SCT2121 accuracy class 0.5				
0...600/ 0...750 A AC		SCT2211 accuracy class 1			
		SCT2221 accuracy class 0.5			
0...800/ 0...1000 A AC			SCT2311 accuracy class 1		
			SCT2321 accuracy class 0.5		
0...1250/ 0...1500 A AC			SCT2411 accuracy class 1		
			SCT2421 accuracy class 0.5		
0...2000 A AC				SCT2515 accuracy class 1	
				SCT2525 accuracy class 0.5	
0...2500 A AC					SCT2615 accuracy class 1
					SCT2625 accuracy class 0.5



### SCT3xxx | 3-phase ring-type current transformers

Primary current	Max. diameter round conductor		
	13.5 mm	18 mm	22 mm
0...50 to 0...150 A AC	SCT3111 accuracy class 1		
0...125/ 0...150 A AC	SCT3121 accuracy class 0.5		
0...100 to 0...250 A AC		SCT3215 accuracy class 1	
0...250 to 0...600 A AC			SCT3315 accuracy class 1

### SCT6xxx | Split-core current transformers

Primary current	Max. diameter round conductor			
	18.5 mm	27.9 mm	42.4 mm	2 x 42.4 mm
0...60 to 0...150 A AC	SCT6101 accuracy class 3			
0...200/ 0...250 A AC	SCT6311 accuracy class 1			
	SCT6321 accuracy class 0.5			
0...300 to 0...500 A AC		SCT6411 accuracy class 1		
0...400/ 0...500 A AC		SCT6421 accuracy class 0.5		
0...600/ 0...750 A AC			SCT6615 accuracy class 1	
			SCT6625 accuracy class 0.5	
0...800/ 0...1000 A AC				SCT6715 accuracy class 1
				SCT6725 accuracy class 0.5



SCT72xx



SCT01xx

### SCT7xxx | Busbar split-core current transformers

Primary current	Max. diameter round conductor		
	20 mm	50 mm	80 mm
0...100/ 0...200 A AC	SCT7105 accuracy class 3		
0...250/ 0...400 A AC	SCT7115 accuracy class 1		
0...400 A AC	SCT7125 accuracy class 2		
0...500/ 0...600 A AC		SCT7215 accuracy class 1	
		SCT7225 accuracy class 2	
0...750 to 0...1500 A AC			SCT7315 accuracy class 1
			SCT7325 accuracy class 2
0...1500/ 0...5000 A AC			SCT7415 accuracy class 1
			SCT7425 accuracy class 2

### SCT0xxx | Coil current transformers

Primary current	Primary conductor for connection	
0...1 to 0...30 A AC	SCT0111 accuracy class 1	SCT0121 accuracy class 0.5



# Product overview power supplies

► [www.beckhoff.com/ps](http://www.beckhoff.com/ps)



## PS1000 | Power supplies

Output current	Output voltage			
	24 V DC (1-phase)	48 V DC (1-phase)	24 V DC (3-phase)	48 V DC (3-phase)
<b>2.5 A</b>	PS1111-2402-0002 24 V DC, 2.5 A DC, 1-phase			
<b>3.8 A</b>	PS1111-2403-0000 24 V DC, 3.8 A DC, 1-phase, NEC			
	PS1111-2403-0002 24 V DC, 3.8 A DC, 1-phase			
<b>5 A</b>	PS1021-2405-0000 24 V DC, 5 A DC, 1-phase			
<b>10 A</b>	PS1011-2410-0000 24 V DC, 10 A DC, 1-phase			
<b>20 A</b>	PS1011-2420-0000 24 V DC, 20 A DC, 1-phase			

## PS2000 | Power supplies

Output current	Output voltage			
	24 V DC (1-phase)	48 V DC (1-phase)	24 V DC (3-phase)	48 V DC (3-phase)
<b>5 A</b>	PS2001-2405-0000 24 V DC, 5 A DC, 1-phase			
<b>10 A</b>	PS2001-2410-0000 24 V DC, 10 A DC, 1-phase	PS2001-4810-0000 48 V DC, 10 A DC, 1-phase	PS2031-2410-0000 24 V DC, 10 A DC, 3-phase	
	PS2001-2420-0000 24 V DC, 20 A DC, 1-phase			

## PS3000 | Power supplies

Output current	Output voltage			
	24 V DC (1-phase)	48 V DC (1-phase)	24 V DC (3-phase)	48 V DC (3-phase)
<b>10 A</b>				PS3031-4810-0001 48 V DC, 10 A DC, 3-phase
<b>20 A</b>	PS3001-2420-0001 24 V DC, 20 A DC, 1-phase	PS3011-4820-0000 48 V DC, 20 A DC, 1-phase	PS3031-2420-0001 24 V DC, 20 A DC, 3-phase	PS3031-4820-0000 48 V DC, 20 A DC, 3-phase
	PS3011-2440-0000 24 V DC, 40 A DC, 1-phase		PS3031-2440-0000 24 V DC, 40 A DC, 3-phase	

# EtherCAT Box



EPxxxx



ERxxxx



EQxxxx

## EP1xxx | EtherCAT Box, digital input

Signal	8-channel		16-channel	
24 V DC, filter 3.0 ms	EP1008-0001 <sup>(1)</sup> 8 x M8	EP1008-0002 <sup>(1, 2)</sup> 4 x M12	EP1809-0021 <sup>(1)</sup> 16 x M8	EP1809-0022 <sup>(1, 2)</sup> 8 x M12
		EP1008-0022 <sup>(1)</sup> 8 x M12		EP1809-0042 8 x M12, EtherCAT M12
24 V DC, filter 10 µs	EP1018-0001 <sup>(1)</sup> 8 x M8	EP1018-0002 <sup>(1)</sup> 4 x M12	EP1819-0021 <sup>(1)</sup> 16 x M8	EP1819-0022 <sup>(1)</sup> 8 x M12
			EP1816-0003 connector with spring-loaded system	
			EP1816-0008 D-sub, 25-pin	EP1816-3008 D-sub, 25-pin, acceleration sensor
24 V DC, ground switching	EP1098-0001 <sup>(1)</sup> 8 x M8			
24 V DC, timestamping	EP1258-0001 <sup>(1)</sup> 8 x M8, 2-channel timestamping	EP1258-0002 <sup>(1)</sup> 4 x M12, 2-channel timestamping		
24 V DC, counter		EP1518-0002 <sup>(1)</sup> 4 x M12, multi-function input		
24 V DC, safe input	EP1908-0002 TwinSAFE, 8 safe inputs	EP1918-0002 TwinSAFE Logic, 8 safe inputs		

## EP2xxx | EtherCAT Box, digital output

Signal	4-channel	8-channel	16-channel	24-channel	
24 V DC, $I_{max} = 0.5 A$		EP2008-0001 <sup>(1)</sup> 8 x M8	EP2008-0002 <sup>(1, 2)</sup> 4 x M12		
			EP2008-0022 <sup>(1)</sup> 8 x M12	EP2809-0021 <sup>(1)</sup> 16 x M8	EP2809-0022 <sup>(1, 2)</sup> 8 x M12
				EP2816-0003 connector with spring-loaded system	EP2816-0004 M16, 19-pin
24 V DC, $I_{max} = 2.0 A$		EP2028-0001 <sup>(1)</sup> 8 x M8	EP2028-0002 <sup>(1)</sup> 4 x M12		
		EP2038-0001 <sup>(1)</sup> 8 x M8, with diagnostics	EP2038-0002 <sup>(1)</sup> 4 x M12, with diagnostics		
				EP2816-0008 D-sub, 25-pin	EP2816-0010 2 x D-sub, 9-pin
24 V DC, $I_{max} = 0.5 A$ , $\Sigma 16 A$				EP2817-0008 D-sub, 25-pin	
24 V DC, $I_{max} = 2.8 A$ , $\Sigma 16 A$			EP2028-0032 8 x M12		
			ER2028-1032 8 x M12		
24 V DC, safe output		EP2918-0032 TwinSAFE Logic, 8 safe outputs			
25 V AC/ 30 V DC	EP2624-0002 <sup>(1)</sup> relay output, 4 x M12				

EPxxxx: industrial housing in IP 67, <sup>(1)</sup>also as ERxxxx: zinc die-cast housing in IP 67, <sup>(2)</sup>also as EQxxxx: stainless steel housing in IP 69K

### EP23xx | EtherCAT Box, digital combi

Signal	8-channel	12-channel	16-channel		
24 V DC, inputs + outputs	EP2308-0001 <sup>(1)</sup> 8 x M8, 4 inputs + 4 outputs, I <sub>max</sub> = 0.5 A, 3.0 ms	EP2308-0002 <sup>(1)</sup> 4 x M12, 4 inputs + 4 outputs, I <sub>max</sub> = 0.5 A, 3.0 ms	EP1859-0042 8 x M12, 8 inputs + 8 outputs, I <sub>max</sub> = 0.5 A, EtherCAT M12, 3.0 ms		
	EP2318-0001 <sup>(1)</sup> 8 x M8, 4 inputs + 4 outputs, I <sub>max</sub> = 0.5 A, 10 µs	EP2318-0002 <sup>(1)</sup> 4 x M12, 4 inputs + 4 outputs, I <sub>max</sub> = 0.5 A, 10 µs	EP2316-0003 8 inputs + 8 outputs, I <sub>max</sub> = 0.5 A, connector with spring-loaded system, 10 µs	EP2316-0008 8 inputs + 8 outputs, D-sub, 25-pin, 10 µs	
	EP2328-0001 <sup>(1)</sup> 8 x M8, 4 inputs + 4 outputs, I <sub>max</sub> = 2 A, 3.0 ms	EP2328-0002 <sup>(1)</sup> 4 x M12, 4 inputs + 4 outputs, I <sub>max</sub> = 2 A, 3.0 ms			
24 V DC, in-/outputs	EP2338-0001 <sup>(1)</sup> 8 x M8, 8 in-/outputs, I <sub>max</sub> = 0.5 A, 10 µs	EP2338-0002 <sup>(1)</sup> 4 x M12, 8 in-/outputs, I <sub>max</sub> = 0.5 A, 10 µs	EP2339-0021 <sup>(1)</sup> 16 x M8, 16 in-/outputs, I <sub>max</sub> = 0.5 A, 3.0 ms	EP2339-0022 <sup>(1, 2)</sup> 8 x M12, 16 in-/outputs, I <sub>max</sub> = 0.5 A, 3.0 ms	
	EP2338-1001 <sup>(1)</sup> 8 x M8, 8 in-/outputs, I <sub>max</sub> = 0.5 A, 3.0 ms	EP2338-1002 <sup>(1)</sup> 4 x M12, 8 in-/outputs, I <sub>max</sub> = 0.5 A, 3.0 ms	EP2339-0121 16 x M8, 16 in-/outputs, I <sub>max</sub> = 0.5 A, 3.0 ms, ground switching	EP2339-0003 16 in-/outputs, I <sub>max</sub> = 0.5 A, connector with spring-loaded system, 3.0 ms	EP2339-0042 8 x M12, 16 in-/outputs, I <sub>max</sub> = 0.5 A, ∑ 16 A, EtherCAT M12, 3.0 ms
			EP2349-0021 <sup>(1)</sup> 16 x M8, 16 in-/outputs, I <sub>max</sub> = 0.5 A, 10 µs	EP2349-0022 <sup>(1)</sup> 8 x M12, 16 in-/outputs, I <sub>max</sub> = 0.5 A, 10 µs	
Safety, safe in-/outputs		EP1957-0022 TwinSAFE Logic, 8 safe inputs, 4 safe outputs			

### EP3xxx | EtherCAT Box, analog input

Signal	1-channel	2-channel	4-channel	
± 10 V, ± 20 mA		EP3162-0002 parameterizable, electrically isolated, single-ended, 16 bit		
± 10 V, 0/4...20 mA			EP3174-0002 <sup>(1, 2)</sup> parameterizable, differential inputs, 16 bit	EP3174-0092 parameterizable, differential inputs, 16 bit, TwinSAFE SC
		EP3182-1002 2 analog inputs, parameterizable, single- ended, 16 bit, 2 digital control outputs (sink/source type), 24 V DC, short-circuit proof	EP3184-0002 <sup>(1)</sup> parameterizable, single-ended, 16 bit	EP3184-1002 <sup>(1)</sup> parameterizable, single-ended, 16 bit, 2 channels per socket
Resistance thermometer (RTD)			EP3204-0002 <sup>(1, 2)</sup> Pt100, Pt200, Pt500, Pt1000, Ni100, Ni120, Ni1000, 16 bit	
Thermocouple/mV			EP3314-0002 <sup>(1, 2)</sup> type J, K, L, B, E, N, R, S, T, U, 16 bit	
Measurement bridge (SG)	EP3356-0022 24 bit, self-calibration			
Condition monitoring/IEPE		EP3632-0001 16 bit		
Accelerometers		EP3752-0000 2 x 3 axes		
Pressure measuring			EP3744-0041 4 pressure inputs -1...1 bar (differential pressure to fifth connection)	EP3744-1041 4 pressure inputs 0...7 bar (differential pressure to fifth connection)

## EP4xxx | EtherCAT Box, analog output

Signal	4-channel
±10 V, 0/4...20 mA	EP4174-0002 <sup>(1)</sup> parameterizable, 16 bit



## EP43xx | EtherCAT Box, analog combi

Signal	4-channel	8-channel
±10 mA, ±20 mA	EP4314-1002 2 inputs + 2 outputs, parameterizable per channel, 2 digital inputs, 24 V DC/3.0 ms	
±10 V, 0/4...20 mA	EP4374-0002 <sup>(1)</sup> 2 inputs + 2 outputs, parameterizable, 16 bit	EP4378-1022 4 inputs + 4 outputs, U/I parameterizable per channel, 8 digital I/Os, 24 V DC/3.0 ms

## EP5xxx | EtherCAT Box, position measurement

Function	M12	D-sub
SSI encoder interface	EP5001-0002 1 MHz, 32 bit	
Incremental encoder interface RS422	EP5101-0002 <sup>(1)</sup> 32/16 bit, 5 V DC sensor supply, 4 million increments/s	EP5101-0011 32/16 bit, 5 V DC sensor supply, 4 million increments/s
	EP5101-1002 <sup>(1)</sup> 32/16 bit, 24 V DC sensor supply	EP5101-2011 32/16 bit, 5 V DC sensor supply, 20 million increments/s
Incremental encoder interface 24 V DC	EP5151-0002 <sup>(1)</sup> 32/16 bit	

## EP6xxx | EtherCAT Box, communication

Function	1-channel	2-channel	4-channel	8-channel	Other
System	EP6070-0060 license key module				
Serial interface	EP6001-0002 <sup>(1)</sup> RS232, RS422/RS485, 5 V DC/1 A	EP6002-0002 <sup>(1)</sup> RS232, RS422/RS485			
EtherCAT/ Ethernet	EP6601-0002 switch port				
IO-Link master			EP6224-2022 Class A	EP6228-0022 Class A	
			EP6224-0042 Class A, EtherCAT M12	EP6228-0042 Class A, EtherCAT M12	
			EP6224-3022 Class B	EP6228-3032 Class B	
				EP6228-3132 4 x Class A, 4 x Class B	
				EP6228-3142 4 x Class A, 4 x Class B, EtherCAT M12	
2 x 16 character display					EP6090-0000 display box

EPxxx: industrial housing in IP 67, <sup>(1)</sup>also as ERxxx: zinc die-cast housing in IP 67, <sup>(2)</sup>also as EQxxx: stainless steel housing in IP 69K

## EP7xxx | EtherCAT Box, motion

Motor type	< 3 A	> 3 A	
<b>Servomotor</b>		<b>EP7211-0034</b> I <sub>rms</sub> = 4.5 A, 48 V DC, OCT, STO suitable	
<b>Stepper motor</b>		<b>EP7047-0032</b> I <sub>max</sub> = 5.0 A, 48 V DC, STO suitable	<b>EP7047-1032</b> I <sub>max</sub> = 5.0 A, 48 V DC
	<b>EP7041-1002<sup>(1)</sup></b> I <sub>max</sub> = 1.5 A, 48 V DC, incremental encoder, 2 digital inputs, 1 digital output	<b>EP7041-0002<sup>(1)</sup></b> I <sub>max</sub> = 5 A, 48 V DC, incremental encoder, 2 digital inputs, 1 digital output	<b>EP7041-2002<sup>(1)</sup></b> I <sub>max</sub> = 5 A, 48 V DC, incremental encoder, 2 digital inputs, 1 digital output, motor connection via plug
		<b>EP7041-3002<sup>(1)</sup></b> I <sub>max</sub> = 5 A, 48 V DC, incremental encoder, for high-speed applications, encoder system (24 V DC encoder)	<b>EP7041-3102</b> I <sub>max</sub> = 5 A, 48 V DC, incremental encoder, for high-speed applications, encoder system (5 V DC encoder)
		<b>EP7041-4032</b> I <sub>max</sub> = 5.0 A, 48 V DC, BiSS C encoder	
<b>DC motor output stage</b>		<b>EP7342-0002<sup>(1)</sup></b> I <sub>max</sub> = 3.5 A, 48 V DC	
<b>Motor controller</b>		<b>EP7402-0057</b> for roller conveyor systems	

## EP8xxx | EtherCAT Box, special functions

Function	8-channel
<b>Multi-function box</b>	<b>EP8309-1022<sup>(1)</sup></b> 8 digital inputs/outputs, 2 x tachometer input, 2 x 0/4...20 mA input, 1 x 0/4...20 mA output, 1 x 1.2 A PWMi output

## EPxxxx | EtherCAT Box, system

Function				
<b>Identification</b>	<b>EP1111-0000</b> 3 decimal ID switches			
<b>Junctions</b>	<table border="0"> <tr> <td> <b>EP1122-0001</b>                              EtherCAT, 2-channel                         </td> <td> <b>EP1312-0001</b>                              EtherCAT P, 2-channel                         </td> <td> <b>EP9128-0021</b>                              EtherCAT, 8 x M8                         </td> </tr> </table>	<b>EP1122-0001</b> EtherCAT, 2-channel	<b>EP1312-0001</b> EtherCAT P, 2-channel	<b>EP9128-0021</b> EtherCAT, 8 x M8
<b>EP1122-0001</b> EtherCAT, 2-channel	<b>EP1312-0001</b> EtherCAT P, 2-channel	<b>EP9128-0021</b> EtherCAT, 8 x M8		
<b>Power distribution</b>	<b>EP9214-0023</b> 4/4-channel, 7/8"	<b>EP9224-0023</b> 4/4-channel, 7/8", with current measurement and data logging		
	<b>EP9221-0057</b> 1-channel, ENP B17, ENP to EtherCAT P	<b>EP9224-0037</b> 4-channel, ENP B17, ENP to EtherCAT P	<b>EP9224-2037</b> 4-channel junction, with power supply, ENP B17	
<b>PROFINET RT EtherCAT Box</b>	<b>EP9300-0022</b> EtherCAT Box interface with PROFINET RT			
<b>EtherCAT media converters fibre optic</b>	<b>EP9521-0020</b> 1-channel, multimode			
<b>Brake chopper box</b>	<b>EP9576-1032</b> up to 72 V DC			

# EtherCAT P Box

► [www.beckhoff.com/ethercat-p-box](http://www.beckhoff.com/ethercat-p-box)



EPP1xxx   EtherCAT P Box, digital input					
Signal	4-channel	8-channel		16-channel	
24 V DC, filter 3.0 ms	EPP1004-0061 4 x M8	EPP1008-0001 8 x M8	EPP1008-0002 4 x M12	EPP1809-0021 16 x M8	EPP1809-0022 8 x M12
			EPP1008-0022 8 x M12		
24 V DC, filter 10 µs		EPP1018-0001 8 x M8	EPP1018-0002 4 x M12	EPP1819-0021 16 x M8	EPP1819-0022 8 x M12
				EPP1816-0008 D-sub, 25-pin	EPP1816-3008 D-sub, 25-pin, acceleration sensor
				EPP1816-0003 connector with spring-loaded system	
24 V DC, timestamping		EPP1258-0001 8 x M8, 2-channel timestamping	EPP1258-0002 4 x M12, 2-channel timestamping		
24 V DC, counter			EPP1518-0002 4 x M12, multi-function input		

EPP2xxx   EtherCAT P Box, digital output					
Signal	4-channel	8-channel		16-channel	24-channel
24 V DC, $I_{max} = 0.5 A$		EPP2008-0001 8 x M8	EPP2008-0002 4 x M12		
			EPP2008-0022 8 x M12	EPP2809-0021 16 x M8	
				EPP2809-0022 8 x M12	
				EPP2816-0008 D-sub, 25-pin	EPP2817-0008 D-sub, 25-pin
				EPP2816-0010 2 x D-sub, 9-pin	
				EPP2816-0004 M16, 19-pin	
24 V DC, $I_{max} = 2.0 A$		EPP2028-0001 8 x M8	EPP2028-0002 4 x M12		
		EPP2038-0001 8 x M8, with diagnostics	EPP2038-0002 4 x M12, with diagnostics		
25 V AC/ 30 V DC	EPP2624-0002 relay output, 4 x M12				

## EPP23xx | EtherCAT P Box, digital combi

Signal	4-channel	8-channel		16-channel		
24 V DC, inputs + outputs		<b>EPP2308-0001</b> 8 x M8, 4 inputs + 4 outputs, $I_{max} = 0.5 \text{ A}$ , 3.0 ms	<b>EPP2308-0002</b> 4 x M12, 4 inputs + 4 outputs, $I_{max} = 0.5 \text{ A}$ , 3.0 ms	<b>EPP2316-0003</b> 8 inputs + 8 outputs, $I_{max} = 0.5 \text{ A}$ , connector with spring-loaded system, 10 $\mu\text{s}$	<b>EPP2316-0008</b> 8 inputs + 8 outputs, $I_{max} = 0.5 \text{ A}$ , D-sub, 25-pin, 10 $\mu\text{s}$	
		<b>EPP2318-0001</b> 8 x M8, 4 inputs + 4 outputs, $I_{max} = 0.5 \text{ A}$ , 10 $\mu\text{s}$	<b>EPP2318-0002</b> 4 x M12, 4 inputs + 4 outputs, $I_{max} = 0.5 \text{ A}$ , 10 $\mu\text{s}$			
		<b>EPP2328-0001</b> 8 x M8, 4 inputs + 4 outputs, $I_{max} = 2 \text{ A}$ , 3.0 ms	<b>EPP2328-0002</b> 4 x M12, 4 inputs + 4 outputs, $I_{max} = 2 \text{ A}$ , 3.0 ms			
	24 V DC, in-/outputs		<b>EPP2338-0001</b> 8 x M8, 8 in-/outputs, $I_{max} = 0.5 \text{ A}$ , 10 $\mu\text{s}$	<b>EPP2338-0002</b> 4 x M12, 8 in-/outputs, $I_{max} = 0.5 \text{ A}$ , 10 $\mu\text{s}$	<b>EPP2339-0021</b> 16 x M8, 16 in-/outputs, $I_{max} = 0.5 \text{ A}$ , 3.0 ms	<b>EPP2339-0022</b> 8 x M12, 16 inputs/outputs, $I_{max} = 0.5 \text{ A}$ , 3.0 ms
		<b>EPP2334-0061</b> 4 x M8, 4 inputs/outputs, $I_{max} = 0.5 \text{ A}$ , 10 $\mu\text{s}$	<b>EPP2338-1001</b> 8 x M8, 8 in-/outputs, $I_{max} = 0.5 \text{ A}$ , 3.0 ms	<b>EPP2338-1002</b> 4 x M12, 8 in-/outputs, $I_{max} = 0.5 \text{ A}$ , 3.0 ms	<b>EPP2349-0021</b> 16 x M8, 16 in-/outputs, $I_{max} = 0.5 \text{ A}$ , 10 $\mu\text{s}$	<b>EPP2349-0022</b> 8 x M12, 16 inputs/outputs, $I_{max} = 0.5 \text{ A}$ , 10 $\mu\text{s}$
					<b>EPP2339-0003</b> 16 inputs/outputs, $I_{max} = 0.5 \text{ A}$ , connector with spring-loaded system, 3.0 ms	

## EPP3xxx | EtherCAT P Box, analog input

Signal	2-channel	4-channel
±10 V, 0/4...20 mA		<b>EPP3174-0002</b> parameterizable, differential input, 16 bit
		<b>EPP3184-0002</b> parameterizable, single-ended, 16 bit
Resistance thermometer (RTD)		<b>EPP3204-0002</b> Pt100, Pt200, Pt500, Pt1000, Ni100, Ni120, Ni1000, 16 bit
Thermo- couple/mV		<b>EPP3314-0002</b> type J, K, L, B, E, N, R, S, T, U, 16 bit
Condition monitoring/ IEPE	<b>EPP3632-0001</b> 16 bit	
Acceler- ometers	<b>EPP3752-0000</b> 2 x 3 axes	
Pressure measuring		<b>EPP3744-0041</b> 4 pressure inputs -1...1 bar (differential pressure to fifth connection)
		<b>EPP3744-1041</b> 4 pressure inputs 0...7 bar (differential pressure to fifth connection)

## EPP4xxx | EtherCAT P Box, analog output

Signal	4-channel
±10 V, 0/4...20 mA	<b>EPP4174-0002</b> parameterizable, 16 bit

## EPP43xx | EtherCAT P Box, analog combi


Signal	4-channel
±10 mA, ±20 mA	<b>EPP4314-1002</b> 2 inputs + 2 outputs, parameterizable per channel, 2 digital inputs, 24 V DC/3.0 ms
±10 V, 0/4...20 mA	<b>EPP4374-0002</b> 2 inputs + 2 outputs, parameterizable, 16 bit



## EPP5xxx | EtherCAT P Box, position measurement

Function	M12	D-sub
SSI encoder interface	EPP5001-0002 1 MHz, 32 bit	
Incremental encoder interface RS422	EPP5101-0002 32/16 bit, 5 V DC sensor supply, 4 million increments/s	EPP5101-1002 32/16 bit, 24 V DC sensor supply
Incremental encoder interface 24 V DC	EPP5151-0002 32/16 bit	EPP5101-0011 32/16 bit, 5 V DC sensor supply, 4 million increments/s

## EPP6xxx | EtherCAT P Box, communication

Function	1-channel	2-channel	8-channel	Other
Serial interface	EPP6001-0002 RS232, RS422/RS485, 5 V DC/1 A	EPP6002-0002 RS232, RS422/RS485		
IO-Link master			EPP6228-0022 Class A, 8 ports	
2 x 16 character display				EPP6090-0000 display box 

## EPP7xxx | EtherCAT P Box, motion

Motor type	< 3 A	> 3 A
Stepper motor	EPP7041-1002 <i>I</i> $I_{max} = 1.5 \text{ A}$ , 48 V DC, incremental encoder	EPP7041-3002 <i>i</i> $I_{max} = 5.0 \text{ A}$ , 48 V DC, incremental encoder
DC motor output stage		EPP7342-0002 <i>i</i> $I_{max} = 3.5 \text{ A}$ , 48 V DC

## EPPxxxx | EtherCAT P Box, system

Function			
Identification	EPP1111-0000 with ID switch		
EtherCAT P diagnostics	EPP9022-0060 4 x diagnostics (U <sub>s</sub> , U <sub>r</sub> , I <sub>s</sub> , I <sub>r</sub> )		
Converter EtherCAT P to EtherCAT	EPP9001-0060 EtherCAT P/EtherCAT connector with power transmission		
Junctions	EPP1322-0001 3 ports, with feed-in	EPP1332-0001 3 ports, with refresh	EPP1342-0001 3 ports
Supply module EtherCAT to EtherCAT P	EPP1321-0060		
Power distribution ENP to EtherCAT P	EP9221-0057 1-channel, ENP B17	EP9224-0037 4-channel, ENP B17	
TwinSAFE SC	EPP9022-9060 4 x diagnostics (U <sub>s</sub> , U <sub>r</sub> , I <sub>s</sub> , I <sub>r</sub> ), TwinSAFE SC		

# EtherCAT Plug-in Modules



## EJ11xx | EtherCAT Couplers

<b>EtherCAT Couplers E-bus</b>	<b>EJ1100</b> EtherCAT Coupler, 2 x RJ45	<b>EJ1101-0022</b> EtherCAT Coupler, external: connectors, power supply module and optional ID switches
<b>Extension system and junctions</b>	<b>EK1110-0043</b> EtherCAT EJ coupler, CX and EL terminal connection	<b>EK1110-0044</b> EtherCAT EJ coupler, CX and EL terminal connection, EtherCAT junction
	<b>EJ1122</b> 2-port junction, external: connectors	

## EJ1xxx | EtherCAT Plug-in Modules, digital input

Signal	4-channel	8-channel	16-channel
3.3 V DC/ 5 V DC		<b>EJ1128</b> filter 0.05 $\mu$ s	
24 V DC, filter 3.0 ms		<b>EJ1008</b> type 3	<b>EJ1809</b> type 3 <b>EJ1859</b> type 3, 8 inputs, 8 outputs, $I_{max} = 0.5$ A <b>EJ1889</b> ground switching
24 V DC, filter 10 $\mu$ s			<b>EJ1819</b> type 3
24 V DC, safe input	<b>EJ1914</b> TwinSAFE Logic, 4 safe inputs	<b>EJ1918</b> TwinSAFE Logic, 8 safe inputs <b>EJ1957</b> TwinSAFE Logic, 8 safe inputs, 4 safe outputs	

## EJ2xxx | EtherCAT Plug-in Modules, digital output

Signal	1-channel	2-channel	4-channel	8-channel	16-channel
3.3 V DC/ 5 V DC				<b>EJ2128</b> $I_{max} = \pm 20$ mA	
24 V DC, $I_{max} = 0.5$ A				<b>EJ2008</b>	<b>EJ2809</b> <b>EJ2889</b> ground switching <b>EJ1859</b> type 3, 8 inputs, 8 outputs, $I_{max} = 0.5$ A
24 V DC, safe output			<b>EJ2914</b> TwinSAFE Logic, 4 safe outputs <b>EJ1957</b> TwinSAFE Logic, 8 safe inputs, 4 safe outputs	<b>EJ2918</b> TwinSAFE Logic, 8 safe outputs	
PWM		<b>EJ2502</b> 24 V DC, 0.5 A			
Frequency output	<b>EJ2521-0224</b> 24 V DC, 1 A				

## EJ3xxx | EtherCAT Plug-in Modules, analog input

Signal	2-channel	4-channel	5-channel	8-channel
$\pm 10$ V		<b>EJ3004</b> single-ended, 12 bit <b>EJ3104</b> differential input, 16 bit		<b>EJ3108</b> 6 x differential inputs, 2 x single-ended, 16 bit
0...10 V				<b>EJ3068</b> single-ended, 12 bit
0...20 mA				<b>EJ3048</b> single-ended, 12 bit
4...20 mA				<b>EJ3058</b> single-ended, 12 bit

### EJ3xxx | EtherCAT Plug-in Modules, analog input

Signal	2-channel	4-channel	5-channel	8-channel
Thermo-couple/mV				EJ3318 type J, K, L...U, 16 bit
Potentiometer			EJ3255 16 bit	i
Resistance thermometer (RTD)	EJ3202 16 bit	EJ3214 16 bit		

### EJ4xxx | EtherCAT Plug-in Modules, analog output

Signal	2-channel	4-channel	8-channel
0...10 V	EJ4002 12 bit	EJ4004 12 bit	EJ4008 12 bit
±10 V	EJ4132 16 bit	EJ4134 16 bit	
0...20 mA			EJ4018 12 bit
4...20 mA		EJ4024 12 bit	

### EJ5xxx | EtherCAT Plug-in Modules, position measurement

Signal	1-channel	2-channel
Absolute position measurement		EJ5002 SSI encoder interface
Incremental position measurement	EJ5101 incremental encoder interface, RS422, TTL, 1 MHz	EJ5151 incremental encoder interface, 24 V HTL, 100 kHz

### EJ6xxx | EtherCAT Plug-in Modules, communication

Signal	1-channel	2-channel	4-channel
Master		EJ6002 serial interface RS232, RS485 or RS422	EJ6224 IO-Link
			EJ6224-0090 IO-Link, TwinSAFE SC
Safety	EJ6910 TwinSAFE Logic		

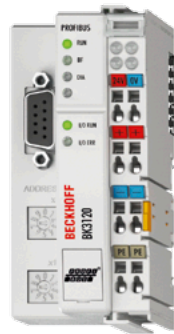
### EJ7xxx | EtherCAT Plug-in Modules, motion

Motor type	< 3 A	3...5 A
Servomotor		EJ7211-0010 $I_{ms} = 4.5 \text{ A}$ , 48 V DC, OCT
		EJ7211-9414 $I_{ms} = 4.5 \text{ A}$ , 48 V DC, OCT, STO, TwinSAFE SC
Stepper motor	EJ7031 $I_{max} = 1.5 \text{ A}$ , 24 V DC	EJ7037 $I_{max} = 1.5 \text{ A}$ , 24 V DC, incremental encoder, vector control
		EJ7041-0052 $I_{max} = 5.0 \text{ A}$ , 48 V DC
		EJ7047 $I_{max} = 5.0 \text{ A}$ , 48 V DC, incremental encoder, vector control
DC motor output stage		EJ7342 $I_{max} = 3.5 \text{ A}$ , 48 V DC, incremental encoder
BLDC		EJ7411 $I_{ms} = 4.5 \text{ A}$ , 48 V DC

### EJ9xxx | EtherCAT Plug-in Modules, system

Signal	Power supply and accessories	System
Power supply	EJ9400 input 24 V DC, E-bus power supply, 2.5 A	EJ9404 input 24 V DC, E-bus power supply, 12 A
	EJ9505 input 24 V DC, output 5 V DC, 0.5 A	
Filtering and smoothing	EJ9576 brake chopper module, up to 72 V DC, 155 µF	
System		EJ9001 placeholder module

# System overview fieldbus I/O



Bus Coupler series BK, the link between Bus Terminals and fieldbus



Bus Terminal Controller series BC with integrated IEC 61131-3 PLC



Bus Terminal Controller series BX with integrated IEC 61131-3 PLC and extended interfaces



Embedded PC series CX, further Embedded PCs see page 22

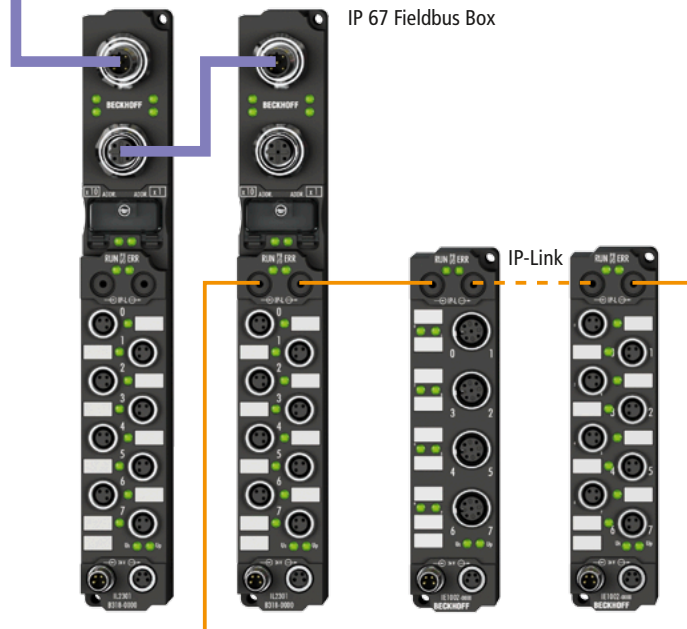
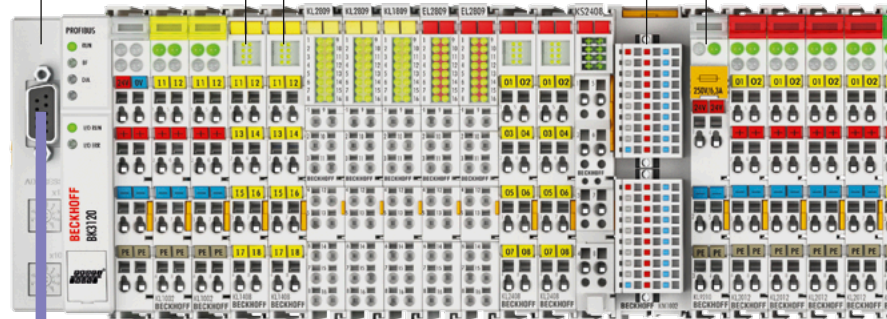
The head station of the Bus Terminals: from Bus Coupler with fieldbus interface to Embedded PC

Free mix of signals: about 400 different Bus Terminals for connection to all common sensors and actuators

Potential feed terminals enable configuration of different potential groups.

Bus Terminals in 1-, 2-, 4-, 8- and 16-channel modularity

The terminal modules with plug-in wiring combine 16, 32 or 64 digital I/Os within a very small space and with high packing density.



IP 67 Fieldbus Box

IP-Link

Compact Box

Coupler Box/  
PLC Box

Extension Box modules

3-phase power measurement capability enables all relevant electrical data of the supply network to be measured.

Communication terminals enable the integration of subsystems such as AS-Interface, RS232 and RS485.

Integrated safety: the TwinSAFE Bus Terminals enable the connection of all common safety sensors and actuators.

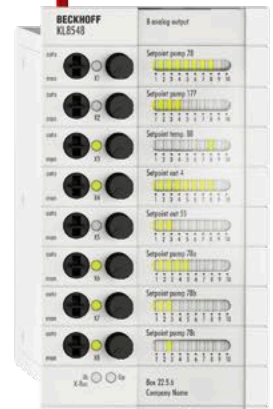
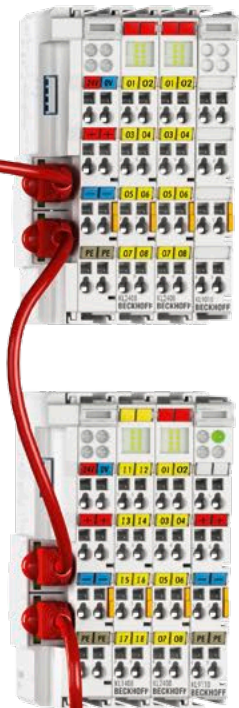
Bus Terminals with a maximum measurement error of  $\pm 0.01\%$



Bus end terminal



The terminal bus extension enables the connection of up to 255 Bus Terminals (instead of 64) to a single station.



Manual operating modules enable switching, controlling and monitoring of digital and analog signals as well as setting and reading of data and values in the event of a controller failure. Process data connection via K-bus interface with K-bus extension (up to 31 modules). Signal connection via KL9309.

IO-Link box modules



# Bus Terminals

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BKxxxx   Bus Couplers			
Fieldbus	Standard	Economy plus	Compact
<b>EtherCAT</b>		BK1120	BK1150 BK1250 E-bus to K-bus interface
<b>Ethernet TCP/IP</b>	BK9000 BK9100 2-channel switch		BK9050
<b>EtherNet/IP</b>	BK9105 2-channel switch		BK9055
<b>CANopen</b>		BK5120	BK5150 BK5151
<b>CC-Link</b>			BK7150
<b>DeviceNet</b>	BK5200	BK5220	BK5250
	BK4000	BK4020	
<b>LIGHTBUS</b>	BK2000	BK2020	
<b>Modbus</b>			BK7350
	BK3100 12 Mbaud	BK3120 12 Mbaud	BK3150 12 Mbaud
		BK3520 12 Mbaud, fibre optic	
	BK9103 2-channel switch		BK9053
	BK8000		
	BK8100		
<b>sercos</b> the automation bus	BK7500	BK7520	

BCxxxx, BXxxxx   Bus Terminal Controllers					
Fieldbus	Programm storage				
	32/96 kbyte	48 kbyte	64/96 kbyte	128 kbyte	256 kbyte
<b>Ethernet TCP/IP</b>		BC9050	BC9000 BC9100 2-channel switch	BC9020 BC9120 2-channel switch	BX9000
		BC9191 Room Controller		BC9191-0100 Room Controller, RS485 interface	
<b>CANopen</b>		BC5150			BX5100
<b>DeviceNet</b>		BC5250			BX5200
<b>Modbus</b>	BC7300				
	BC3100 12 MBaud	BC3150 12 MBaud			BX3100 12 MBaud
		BC8150			
		BC8050			BX8000

## KL1xxx | Bus Terminals, digital input

Signal	2-channel		4-channel		8-channel	16-channel	KM1xxx
5 V DC			KL1124 filter 0.2 ms				
24 V DC, filter 3.0 ms	KL1002 type 3		KL1104 type 3	KL1804 type 3, 8 x 24 V, 4 x 0 V	KL1808 type 3, 8 x 24 V DC	KL1809 type 3	KM1002 16-channel, type 1
	KL1402 type 3	KL1302 type 2	KL1404 type 3, 4 x 2-wire connection	KL1304 type 2	KL1408 type 3		KM1004 32-channel, type 1
	KL1052 positive/ground switching		KL1154 positive/ground switching	KL1184 ground switching	KL1488 ground switching	KL1889 ground switching	KM1008 64-channel, type 1
	KL1212 type 1, short-circuit protected sensor supply	KL1362 break-in alarm				KL1859 type 3, 8 inputs, 8 outputs, $I_{max} = 0.5$ A	
						KL1862 type 3, flat-ribbon cable	
						KL1862-0010 type 3, flat-ribbon cable, ground switching	
24 V DC, filter 0.2 ms	KL1012 type 3	KL1412 type 3	KL1114 type 3	KL1814 type 3, 8 x 24 V, 4 x 0 V	KL1418 type 3	KL1819 type 3	KM1012 16-channel, type 1
		KL1312 type 2		KL1314 type 2			KM1014 32-channel, type 1
			KL1414 type 3, 4 x 2-wire connection	KL1434 type 2, 4 x 2-wire connection			KM1018 64-channel, type 1
			KL1164 positive/ground switching	KL1194 ground switching	KL1498 ground switching		
						KL1872 type 3, flat-ribbon cable	
24 V DC	KL1232 pulse expansion	KL1382 thermistor	KL1904 TwinSAFE, 4 safe inputs				KM1644 4-channel, manual operation
24 V DC, counter	KL1501 type 1, 100 kHz, 32 bit	KL1512 type 1, 1 kHz, 16 bit					
≥ 48 V DC	KL1032 48 V DC, filter 3.0 ms	KL1712-0060 60 V DC					
120 V AC/DC	KL1712						
230 V AC	KL1702	KL1722 no power contacts	KL1704				
NAMUR	KL1352						

The standard Bus Terminals (KLxxxx) can be optionally ordered as KSxxxx with pluggable wiring level.

## KL2xxx | Bus Terminals, digital output

Signal	1-channel	2-channel	4-channel	8-channel	16-channel	KM2xxx
5 V DC			KL2124 <i>I</i> <sub>max</sub> = ±20 mA			
24 V DC, <i>I</i> <sub>max</sub> = 0.5 A		KL2012 short-circuit proof	KL2114 short-circuit proof	KL2808 8 x 0 V	KL2809 reverse voltage protection	KM2002 16-channel
		KL2032 reverse voltage protection	KL2134 reverse voltage protection			KM2004 32-channel
			KL2404 4 x 2-wire	KL2408 reverse voltage protection		KM2008 64-channel
		KL2212 diagnostics, protected sensor supply			KL2819 with diagnostics	KM2042 16-channel, D-sub connection
			KL2184 ground switching	KL2488 ground switching	KL2889 ground switching	
					KL1859 type 3, 8 inputs, 8 outputs, <i>I</i> <sub>max</sub> = 0.5 A	
					KL2872 flat-ribbon cable	
					KL2872-0010 flat-ribbon cable, ground switching	
24 V DC, <i>I</i> <sub>max</sub> = 2.0 A		KL2022	KL2424 4 x 2-wire	KL2828 8 x 2-wire		
24 V DC, <i>I</i> <sub>max</sub> = 4.0 A/8.0 A		KL2442 2 x 4 A/1 x 8 A				
24 V DC, safe output			KL2904 TwinSAFE, 4 safe outputs			
30 V AC/ 48 V DC solid state relay, <i>I</i> <sub>max</sub> = 2.0 A			KL2784			
			KL2794 potential-free	KL2798 potential-free		
230 V AC solid state relay	KL2701 <i>I</i> <sub>max</sub> = 3 A	KL2702 <i>I</i> <sub>max</sub> = 0.3 A				
Relay (up to 400 V AC)	KL2641 make contact, manual operation, <i>I</i> <sub>max</sub> = 16 A	KL2602 make contact, <i>I</i> <sub>max</sub> = 5 A	KL2622 make contact, no power contacts, <i>I</i> <sub>max</sub> = 5 A	KL2634 make contact, 250 V AC/30 V DC		KM2604 <i>I</i> <sub>max</sub> = 16 A, 4-channel
		KL2602-0010 make contact, <i>I</i> <sub>max</sub> = 5 A, contact- protecting switching	KL2622-0010 make contact, no power contacts, <i>I</i> <sub>max</sub> = 5 A, contact- protecting switching			KM2614 <i>I</i> <sub>max</sub> = 16 A, 4-channel, manual operation
		KL2652 change-over, <i>I</i> <sub>max</sub> = 5 A				KM2642 <i>I</i> <sub>max</sub> = 6 A, manual/ automatic operation, relay state readable
	KL2631 400 V AC, make contact	KL2612 125 V AC, change-over	KL2692 cycle monitoring (watchdog)			KM2652 <i>I</i> <sub>max</sub> = 6 A, manual/ automatic operation, switch and relay state readable

The standard Bus Terminals (KLxxxx) can be optionally ordered as KSxxxx with pluggable wiring level.




## KL2xxx | Bus Terminals, digital output

Signal	1-channel	2-channel	4-channel	8-channel	16-channel	KM2xxx
<b>Triac</b> (12...230 V AC)		<b>KL2712</b> mutually locked outputs	<b>KL2722</b> mutually locked outputs			<b>KM2774</b> $I_{max} = 1.5 A$
		<b>KL2732</b> mutually locked outputs, no power contacts				
<b>PWM</b>		<b>KL2502</b> 24 V DC, $I_{max} = 0.1 A$	<b>KL2512</b> 24 V DC, $I_{max} = 1.5 A$ , ground switching			
		<b>KL2535</b> $I_{max} = \pm 1 A$ , 24 V DC, current-controlled	<b>KL2545</b> $I_{max} = \pm 3.5 A$ , 50 V DC, current-controlled			
<b>Frequency output</b>	<b>KL2521</b> 1-channel AB, 0...500 kHz, RS422					
<b>Current control, dimmer control</b>	<b>KL2751</b> universal dimmer, 300 W					
	<b>KL2761</b> universal dimmer, 600 W					

## KL2xxx | Bus Terminals, motion

	< 3 A	3...5 A
<b>Stepper motor</b>	<b>KL2531</b> $I_{max} = 1.5 A$ , 24 V DC	<b>KL2541</b> $I_{max} = 5.0 A$ , 48 V DC, incremental encoder
<b>DC motor output stage</b>	<b>KL2532</b> $I_{max} = 1.0 A$ , 24 V DC	<b>KL2284</b> reverse switching, $I_{max} = 2.0 A$ , 0...24 V DC
<b>AC motor speed controller</b>	<b>KL2791</b> 230 V AC, 200 VA, 1-phase AC motor	<b>KL2552</b> $I_{max} = 5.0 A$ , 48 V DC, incremental encoder

## KL3xxx | Bus Terminals, analog input

Signal	1-channel	2-/3-channel	4-channel	8-channel
0...2 V, 0...500 mV		<b>KL3172</b> 0...2 V, 16 bit, 0.05 %	<b>KL3172-0500</b> 0...500 mV, 16 bit, 0.05 %	
±2 V			<b>KL3182</b> 16 bit, 0.05 %	
0...10 V	<b>KL3061</b> single-ended, 12 bit	<b>KL3062</b> single-ended, 12 bit	<b>KL3162</b> 16 bit, 0.05 %	<b>KL3064</b> single-ended, 12 bit  <b>KL3464</b> with sensor supply, single-ended, 12 bit
±10 V	<b>KL3001</b> differential input, 12 bit	<b>KL3002</b> differential input, 12 bit	<b>KL3102</b> differential input, 16 bit  <b>KL3132</b> 16 bit, 0.05 %	<b>KL3404</b> single-ended, 12 bit  <b>KL3408</b> single-ended, 12 bit
0...20 mA	<b>KL3011</b> differential input, 12 bit  <b>KL3041</b> with sensor supply, 12 bit	<b>KL3012</b> differential input, 12 bit  <b>KL3042</b> with sensor supply, 12 bit	<b>KL3112</b> differential input, 16 bit  <b>KL3142</b> 16 bit, 0.05 %	<b>KL3044</b> single-ended, 12 bit  <b>KL3444</b> with sensor supply, single-ended, 12 bit
4...20 mA	<b>KL3021</b> differential input, 12 bit  <b>KL3051</b> with sensor supply, 12 bit	<b>KL3022</b> differential input, 12 bit  <b>KL3052</b> with sensor supply, 12 bit	<b>KL3122</b> differential input, 16 bit  <b>KL3152</b> 16 bit, 0.05 %	<b>KL3054</b> single-ended, 12 bit  <b>KL3454</b> with sensor supply, single-ended, 12 bit
Resistance thermometer (RTD)	<b>KL3201</b> Pt100...1000, Ni100, 16 bit	<b>KL3202</b> Pt100...1000, Ni100, 16 bit	<b>KL3222</b> Pt100, 4-wire connection, high-precision	<b>KL3204</b> Pt100...1000, Ni100...1000, 2-wire connection  <b>KL3204-0030</b> NTC (10 kΩ)  <b>KL3214</b> Pt100...1000, Ni100...1000, KTY, 3-wire connection
				<b>KL3208-0010</b> Pt1000, Ni1000, NTC 1.8...100 k, potentiom. 1, 5, 10 kΩ  <b>KL3228</b> Pt1000, Ni1000
Thermo- couple/mV	<b>KL3311</b> type J, K, L...U, 16 bit	<b>KL3312</b> type J, K, L...U, 16 bit	<b>KL3314</b> type J, K, L...U, 16 bit	
Measurement bridge (SG)	<b>KL3351</b> 16 bit  <b>KL3356</b> 16 bit, self-calibration			
Oscilloscope	<b>KL3361</b> ±16 mV	<b>KL3362</b> ±10 V		
Measurement technology	<b>KL3681</b> digital multimeter, 18 bit	<b>KL3403</b> power measurement, 3-phase, 1 A	<b>KL3403-0010</b> power measurement, 3-phase, 5 A	
Pressure measuring	<b>KM3701</b> differential pressure, -100...+100 hPa  <b>KM3701-0340</b> differential pressure, up to 340 hPa	<b>KM3702</b> relative pressure, 7500 hPa	<b>KM3712</b> relative pressure, -1000...+1000 hPa	
Power measurement, > 500 V		<b>KL3453</b> 690 V AC, 5 A, extended functionalities		

The standard Bus Terminals (KLxxxx) can be optionally ordered as KSxxxx with pluggable wiring level.

## KL4xxx | Bus Terminals, analog output

Signal	1-channel	2-channel	4-channel	8-channel	KM4xxx
<b>0...10 V</b>	<b>KL4001</b> 12 bit, potential-free output	<b>KL4002</b> 12 bit	<b>KL4004</b> 12 bit, no power contacts		<b>KM4602</b> 12-bit manual/automatic operation
			<b>KL4404</b> 12 bit	<b>KL4408</b> 12 bit	
<b>±10 V</b>	<b>KL4031</b> 12 bit, potential-free output	<b>KL4032</b> 12 bit	<b>KL4034</b> 12 bit, no power contacts		
		<b>KL4132</b> 16 bit	<b>KL4434</b> 12 bit	<b>KL4438</b> 12 bit	
			<b>KL4494</b> 12 bit, 2 x input, 2 x output		
<b>0...20 mA</b>	<b>KL4011</b> 12 bit	<b>KL4012</b> 12 bit	<b>KL4414</b> 12 bit	<b>KL4418</b> 12 bit	
		<b>KL4112</b> 16 bit			
<b>4...20 mA</b>	<b>KL4021</b> 12 bit	<b>KL4022</b> 12 bit	<b>KL4424</b> 12 bit	<b>KL4428</b> 12 bit	

## KL5xxx | Bus Terminals, position measurement

Signal	1-channel	2-channel
<b>Absolute position measurement</b>	<b>KL5001</b> SSI encoder interface	
	<b>KL5051</b> SSI encoder interface, bidirectional	
<b>Incremental position measurement</b>	<b>KL5101</b> incremental encoder interface, RS422, TTL, 1 MHz	
	<b>KL5111</b> incremental encoder interface, 24 V HTL, 250 kHz, 16 bit counter	
	<b>KL5151</b> incremental encoder interface, 24 V HTL, 100 kHz, 32 bit counter	<b>KL5152</b> incremental encoder interface, 24 V HTL, 100 kHz, 32 bit counter
	<b>KL5121</b> incremental encoder interface, 24 V HTL, path control, 250 kHz	

## KL6xxx | Bus Terminals, communication

Signal			
Serial interfaces	<b>KL6001</b> RS232, 19.2 kbaud	<b>KL6031</b> RS232, 115.2 kbaud	<b>KL6011</b> TTY, 20 mA current loop
	<b>KL6051</b> data exchange terminal, 32 bit	<b>KL6021</b> RS422/RS485, 19.2 kbaud	<b>KL6041</b> RS422/RS485, 115.2 kbaud
Subsystems	<b>KL6201</b> AS-Interface master terminal	<b>KL6211</b> AS-Interface master terminal with power contacts	<b>KL6224</b> IO-Link master
	<b>KL6301</b> EIB/KNX Bus Terminal	<b>KL6401</b> LON Bus Terminal	
	<b>KL6581</b> EnOcean master	<b>KL6583</b> EnOcean transmitter/receiver	
	<b>KL6771</b> MP-Bus master terminal	<b>KL6781</b> M-Bus master terminal	
	<b>KL6811</b> DALI/DSI master and power supply terminal	<b>KL6821</b> DALI-2 multi-master and power supply terminal	
	<b>KL6831</b> SMI terminal, LoVo	<b>KL6841</b> SMI terminal, 230 V AC	
Safety	<b>KL6904</b> TwinSAFE Logic, 4 safe outputs		

## KL85xx | Bus Terminals, manual operation modules

Technology	4-channel	8-channel	16-channel	Other
Manual operation modules	<b>KL8524</b> 4 x 2-channel digital output, 24 V DC, 0.5 A	<b>KL8528</b> digital output, 24 V DC, 0.5 A	<b>KL8519</b> digital input signal module	<b>KL8500</b> placeholder module
		<b>KL8548</b> analog output, 0...10 V		
System				<b>KL9309</b> adapter terminal for manual operating modules

## KL8xxx | Bus Terminals, power

For Siemens contactors (Sirius 3R series)	<b>KL8001</b> switching capacity 5.5 kW, nominal current 0.9...9.9 A, connection mechanism for Siemens contactors (Sirius 3R series)
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## KL9xxx | Bus Terminals, system

Signal	System	Potential supply	Power supply and accessories
System	<b>KL9010</b> bus end terminal	<b>KL9070</b> shield terminal	
	<b>KL9020</b> terminal bus extension end terminal	<b>KL9050</b> terminal bus extension coupler terminal	
	<b>KL9060</b> adapter terminal for power terminal KL8xxx	<b>KL9309</b> adapter terminal for manual operating modules	
	<b>KL9080</b> isolation terminal	<b>KL9195</b> shield terminal	

The standard Bus Terminals (KLxxxx) can be optionally ordered as KSxxxx with pluggable wiring level.

## KL9xxx | Bus Terminals, system

Signal	System	Potential supply	Power supply and accessories
Potential distribution terminals	<b>KL9180</b> 2 terminal points per power contact	<b>KL9181</b> 2 x 8 terminal points	
	<b>KL9182</b> 8 x 2 terminal points	<b>KL9183</b> 1 x 16 terminal points	
	<b>KL9184</b> 8 x 24 V DC, 8 x 0 V DC	<b>KL9185</b> only 2 power contacts	
	<b>KL9186</b> 8 x 24 V DC	<b>KL9187</b> 8 x 0 V DC	
	<b>KL9188</b> 16 x 24 V DC	<b>KL9189</b> 16 x 0 V DC	
	<b>KL9380</b>		
	Filter	<b>KL9540</b> surge filter terminal for field supply	
<b>KL9540-0010</b> surge filter field supply for analog terminals		<b>KL9550</b> surge filter terminal for system/field supply	
Diode arrays	<b>KL9300</b> 4 diodes, potential-free		
	<b>KL9301</b> 7 diodes, common cathode	<b>KL9302</b> 7 diodes, common anode	
24 V DC		<b>KL9100</b>	<b>KL9400</b> K-bus power supply, 2 A
		<b>KL9110</b> diagnostics	<b>KL9505</b> output 5 V DC, 0.5 A
		<b>KL9200</b> with fuse	<b>KL9508</b> output 8 V DC, 0.5 A
		<b>KL9210</b> diagnostics, with fuse	<b>KL9510</b> output 10 V DC, 0.5 A
			<b>KL9512</b> output 12 V DC, 0.5 A
			<b>KL9515</b> output 15 V DC, 0.5 A
		<b>KL9520</b> AS-Interface potential supply	<b>KL9528</b> AS-Interface power supply terminal
			<b>KL9560</b> output 24 V DC, 0.1 A
50 V DC			<b>KL9570</b> buffer capacitor terminal, 500 µF
120... 230 V AC		<b>KL9150</b>	
		<b>KL9160</b> diagnostics	
		<b>KL9250</b> with fuse	
		<b>KL9260</b> diagnostics, with fuse	
		<b>KL9190</b> any voltage up to 230 V AC	
		<b>KL9290</b> with fuse	

# Fieldbus Box and IO-Link box

► [www.beckhoff.com/fieldbusbox](http://www.beckhoff.com/fieldbusbox)

Fieldbus Box	Compact Box		Coupler Box		PLC Box	
<b>Fieldbus</b>	Fieldbus Box without IP-Link interface		Fieldbus Box with IP-Link interface		Controller for TwinCAT 2 (IEC 61131-3) with IP-Link interface	
<b>EtherCAT</b>			IL230x-B110			
<b>LIGHTBUS</b>	IPxxxx-B200		IL230x-B200			
<b>PROFIBUS</b>	IPxxxx-B310	IPxxxx-B318 with integrated tee-connector	IL230x-B310	IL230x-B318 with integrated tee-connector	IL230x-C310	IL230x-C318 with integrated tee-connector
<b>INTERBUS</b>	IPxxxx-B400		IL230x-B400			
<b>CANopen</b>	IPxxxx-B510	IPxxxx-B518 with integrated tee-connector	IL230x-B510	IL230x-B518 with integrated tee-connector		
<b>DeviceNet</b>	IPxxxx-B520	IPxxxx-B528 with integrated tee-connector	IL230x-B520	IL230x-B528 with integrated tee-connector		
<b>Modbus</b>	IPxxxx-B730		IL230x-B730			
<b>RS485</b>	IPxxxx-B800		IL230x-B800			
<b>RS232</b>	IPxxxx-B810		IL230x-B810		IL230x-C810	
<b>Ethernet TCP/IP</b>			IL230x-B900	IL230x-B901	IL230x-C900	
<b>PROFINET</b>			IL230x-B903			
<b>EtherNet/IP</b>			IL230x-B905			

IP1xxx-Bxxx   Fieldbus Box, digital input				
Signal	2-channel	8-channel		
24 V DC, filter 3.0 ms		IP1000-Bxxx <sup>(1)</sup> 8 x 8 mm	IP1001-Bxxx <sup>(1)</sup> 8 x M8	IP1002-Bxxx <sup>(1)</sup> 4 x M12
24 V DC, filter 0.2 ms		IP1010-Bxxx <sup>(1)</sup> 8 x 8 mm	IP1011-Bxxx <sup>(1)</sup> 8 x M8	IP1012-Bxxx <sup>(1)</sup> 4 x M12
Counter	IP1502-Bxxx <sup>(1)</sup> up/down counter 24 V DC, 100 kHz			

IP2xxx-Bxxx   Fieldbus Box, digital output				
Signal	2-channel	8-channel		16-channel
24 V DC, $I_{max} = 0.5 A$		IP2000-Bxxx <sup>(1)</sup> 8 x 8 mm	IP2001-Bxxx <sup>(1)</sup> 8 x M8	IP2002-Bxxx <sup>(1)</sup> 4 x M12
24 V DC, $I_{max} = 0.5 A$ , $\Sigma 4 A$				IE2808 D-sub
24 V DC, $I_{max} = 2 A$ , $\Sigma 4 A$		IP2020-Bxxx <sup>(1)</sup> 8 x 8 mm	IP2021-Bxxx <sup>(1)</sup> 8 x M8	IP2022-Bxxx <sup>(1)</sup> 4 x M12
24 V DC, $I_{max} = 2 A$ , $\Sigma 12 A$		IP2040-Bxxx <sup>(1)</sup> 8 x 8 mm	IP2041-Bxxx <sup>(1)</sup> 8 x M8	IP2042-Bxxx <sup>(1)</sup> 4 x M12
PWM, $I_{max} = 2.5 A$	IP2512-Bxxx <sup>(1)</sup> 4 x M12			

<sup>(1)</sup>also as IExxxx: Extension Box, <sup>(2)</sup>also as ILxxxx-Bxxx: Coupler Box, <sup>(3)</sup>also as ILxxxx-Cxxx: PLC Box



## IP23/24xx-Bxxx | Fieldbus Box, digital combi

Signal	8-channel			16-channel		
24 V DC, filter 3.0 ms, $I_{max} = 0.5 A$	IP2300-Bxxx <sup>(1, 2, 3)</sup> 8 x 8 mm, 4 inputs + 4 outputs	IP2301-Bxxx <sup>(1, 2, 3)</sup> 8 x M8, 4 inputs + 4 outputs	IP2302-Bxxx <sup>(1, 2, 3)</sup> 4 x M12, 4 inputs + 4 outputs	IP2400-Bxxx <sup>(1)</sup> 8 x 8 mm, 8 inputs/outputs	IP2401-Bxxx <sup>(1)</sup> 8 x M8, 8 inputs/outputs	IE2403 IP 20 plug
24 V DC, filter 0.2 ms, $I_{max} = 0.5 A$	IP2310-Bxxx <sup>(1)</sup> 8 x 8 mm, 4 inputs + 4 outputs	IP2311-Bxxx <sup>(1)</sup> 8 x M8, 4 inputs + 4 outputs	IP2312-Bxxx <sup>(1)</sup> 4 x M12, 4 inputs + 4 outputs			
24 V DC, filter 3.0 ms, $I_{max} = 2 A, \sum 4 A$	IP2320-Bxxx <sup>(1)</sup> 8 x 8 mm, 4 inputs + 4 outputs	IP2321-Bxxx <sup>(1)</sup> 8 x M8, 4 inputs + 4 outputs	IP2322-Bxxx <sup>(1)</sup> 4 x M12, 4 inputs + 4 outputs			
24 V DC, filter 0.2 ms, $I_{max} = 2 A, \sum 4 A$	IP2330-Bxxx <sup>(1)</sup> 8 x 8 mm, 4 inputs + 4 outputs	IP2331-Bxxx <sup>(1)</sup> 8 x M8, 4 inputs + 4 outputs	IP2332-Bxxx <sup>(1)</sup> 4 x M12, 4 inputs + 4 outputs			

## IP3xxx-Bxxx | Fieldbus Box, analog input

Signal	4-channel
$\pm 10 V$	IP3102-Bxxx <sup>(1)</sup> differential inputs, 16 bit
0/4...20 mA	IP3112-Bxxx <sup>(1)</sup> differential inputs, 16 bit
Resistance thermometer	IP3202-Bxxx <sup>(1)</sup> Pt100, Pt200, Pt500, Pt1000, Ni100, 16 bit
Thermo-couple/mV	IP3312-Bxxx <sup>(1)</sup> type J, K, L, B, E, N, R, S, T, U, 16 bit

## IP4xxx-Bxxx | Fieldbus Box, analog output

Signal	4-channel
0/4...20 mA	IP4112-Bxxx <sup>(1)</sup> 16 bit
$\pm 10 V$	IP4132-Bxxx <sup>(1)</sup> 16 bit

## IP5xxx-Bxxx | Fieldbus Box, position measurement

Function	M12
SSI encoder interface	IP5009-Bxxx <sup>(1)</sup>
Incremental encoder interface RS422	IP5109-Bxxx <sup>(1)</sup> 1 MHz
SinCos encoder interface	IP5209-Bxxx 12-pin
	IP5209-Bxxx-1000 9-pin

## IP6xxx-Bxxx | Fieldbus Box, communication

Function			
Serial interfaces	IP6002-Bxxx <sup>(1)</sup> RS232	IP6012-Bxxx <sup>(1)</sup> 0...20 mA (TTY)	IP6022-Bxxx <sup>(1)</sup> RS422/RS485



EPIxxxx

ERLxxxx

### EPI1xxx | Fieldbus Box, IO-Link box, digital input

Signal	8-channel		16-channel	
24 V DC, filter 3.0 ms	EPI1008-0001 <sup>(1)</sup> 8 x M8	EPI1008-0002 <sup>(1)</sup> 4 x M12	EPI1809-0021 <sup>(1)</sup> 16 x M8	EPI1809-0022 <sup>(1)</sup> 8 x M12

### EPI2xxx | Fieldbus Box, IO-Link box, digital output

Signal	8-channel		16-channel	
24 V DC, $I_{max} = 0.5 A$	EPI2008-0001 <sup>(1)</sup> 8 x M8	EPI2008-0002 <sup>(1)</sup> 4 x M12		
24 V DC, $I_{max} = 0.5 A$ , $\Sigma 4 A$			EPI2809-0021 <sup>(1)</sup> 16 x M8	EPI2809-0022 <sup>(1)</sup> 8 x M12

### EPI23xx | Fieldbus Box, IO-Link box, digital combi

Signal	8-channel		16-channel	
24 V DC, filter 3.0 ms, $I_{max} = 0.5 A$	EPI2338-0001 <sup>(1)</sup> 8 x M8	EPI2338-0002 <sup>(1)</sup> 4 x M12		
24 V DC, filter 3.0 ms, $I_{max} = 0.5 A$ , $\Sigma 4 A$			EPI2339-0021 <sup>(1)</sup> 16 x M8	EPI2339-0022 <sup>(1)</sup> 8 x M12

### EPI3xxx | Fieldbus Box, IO-Link box, analog input

Signal	4-channel	8-channel
$\pm 10 V$ , 0/4...20 mA	EPI3174-0002 <sup>(1)</sup> parameterizable, differential input, 16 bit	EPI3188-0022 parameterizable, single-ended, 16 bit

### EPI4xxx | Fieldbus Box, IO-Link box, analog output

Signal	4-channel
$\pm 10 V$ , 0/4...20 mA	EPI4374-0002 <sup>(1)</sup> 2 inputs + 2 outputs, parameterizable, 16 bit

EPIxxxx: industrial housing in IP 67, <sup>(1)</sup>also as ERLxxxx: zinc die-cast housing in IP 67



# Infrastructure Components

► [www.beckhoff.com/infrastructure-components](http://www.beckhoff.com/infrastructure-components)



## CUxxxx, EPxxxx | EtherCAT components

	100 Mbit/s, IP 20		100 Mbit/s, IP 67	1 Gbit/s, IP 20	
<b>Junctions</b>	<b>CU1123</b> junction, 3 x RJ45	<b>CU1123-0010</b> junction, 3 x RJ45, Extended Distance	<b>EP9128-0021</b> EtherCAT, 8 x M8	<b>CU1423</b> junction, 3 x RJ45	
	<b>CU1124</b> junction, 4 x RJ45	<b>CU1128</b> junction, 8 x RJ45		<b>CU1411</b> branch controller, 1 port	<b>CU1418</b> branch controller, 8 ports
<b>Media converters</b>	<b>CU1521</b> 1-channel, multimode/singlemode	<b>CU1561</b> 1-channel, POF	<b>EP9521-0020</b> 1-channel, multimode		

## CUxxxx, EPxxxx | Ethernet switches/components

	100 Mbit/s, IP 20		100 Mbit/s, IP 67	1 Gbit/s, IP 20	
<b>Switches</b>	<b>CU2005</b> 5-port, RJ45	<b>CU2008</b> 8-port, RJ45	<b>CU2016</b> 16-port, RJ45	<b>CU2608</b> 8-port, M12 (D-coded)	<b>CU2208</b> 8-port, RJ45
<b>Media converters</b>	<b>CU1521</b> 1-channel, multimode/singlemode	<b>CU1561</b> 1-channel, POF		<b>EP9521-0020</b> 1-channel, multimode	

## CUxxxx | Ethernet port multiplier

	1 Gbit/s
<b>Multiplier</b>	<b>CU2508</b> 1 x RJ45 (+ 8 x RJ45: 100 Mbit/s)

## FCxxxx | PCI and PCIe fieldbus cards

Fieldbus	PCI		PCIe		Mini PCI	Mini PCIe
<b>EtherCAT</b>	<b>FC1100</b> 1-channel, EtherCAT slave		<b>FC1121</b> 1-channel, EtherCAT slave			
<b>Ethernet TCP/IP</b>	<b>FC9004</b> 4 x RJ45, 10/100 Mbit/s	<b>FC9002</b> 2 x RJ45, 10/100 Mbit/s	<b>FC9024</b> 4 x RJ45, 1 Gbit/s		<b>FC9051</b> 1 x RJ45, 10/100 Mbit/s	<b>FC9071</b> Gigabit Ethernet PC interface card
	<b>FC9011</b> 1 x RJ45, 1 Gbit/s	<b>FC9001-0010</b> 1 x RJ45, 10/100 Mbit/s	<b>FC9022</b> 2 x RJ45, 1 Gbit/s		<b>FC9151</b> 1 x RJ45, 1 Gbit/s	
<b>LIGHTBUS</b>	<b>FC2001</b> 1-channel	<b>FC2002</b> 2-channel				
<b>PROFIBUS</b>	<b>FC3101</b> 1-channel	<b>FC3102</b> 2-channel	<b>FC3121</b> 1-channel	<b>FC3122</b> 2-channel	<b>FC3151</b> 1-channel	<b>FC3161</b> 1-channel
<b>CANopen</b>	<b>FC5101</b> 1-channel	<b>FC5102</b> 2-channel	<b>FC5121</b> 1-channel	<b>FC5122</b> 2-channel	<b>FC5151</b> 1-channel	
<b>DeviceNet</b>	<b>FC5201</b> 1-channel	<b>FC5202</b> 2-channel			<b>FC5251</b> 1-channel	
<b>SERCOS</b> the automation bus	<b>FC7501</b> 1-channel	<b>FC7502</b> 2-channel			<b>FC7551</b> 1-channel	

# The Motion Company

In combination with the motion control solutions offered by the company's TwinCAT automation software, Beckhoff Drive Technology provides an advanced, all-inclusive drive system. PC-based control technology from Beckhoff is ideally suited for single- and multi-axis positioning tasks with high dynamic requirements.

The AX5000 and AX8000 Servo Drive series with high-performance EtherCAT communication offer the best-possible performance and dynamics. Servomotors with One Cable Technology (OCT), combining power and feedback systems into one standard motor cable, reduce material and commissioning costs.

► [www.beckhoff.com/motion](http://www.beckhoff.com/motion)

## Servo Drives 76

- available as multi-axis system or stand-alone version (1-/2-channel)
- high-speed EtherCAT communication
- nominal current types, up to 170 A
- flexible motor type selection
- optimized for multi-axis applications
- 17 drive-integrated safety functions

► [www.beckhoff.com/servo-drives](http://www.beckhoff.com/servo-drives)

## Distributed Servo Drive system 77

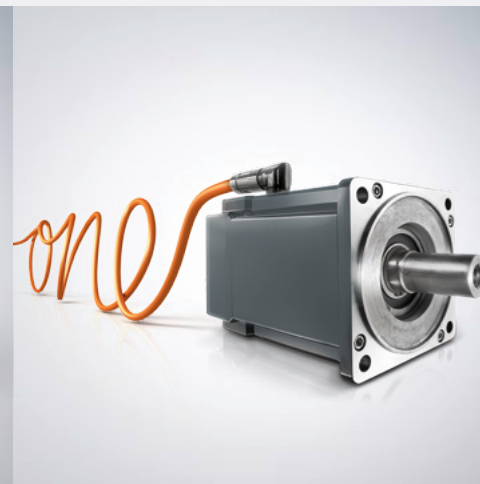
- servo drives directly integrated into the motor
- STO/SS1 safety function as standard; optionally Safe Motion
- minimal derating
- no changes in machine design required

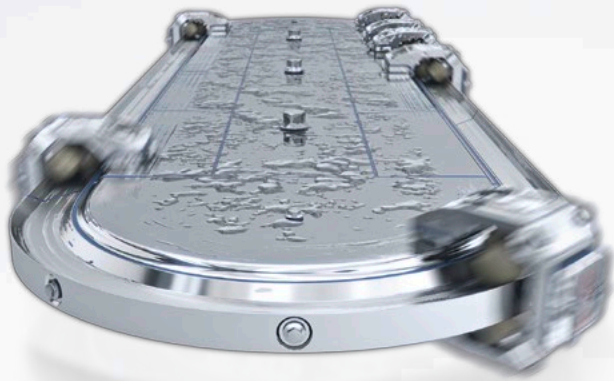
► [www.beckhoff.com/distributed-servo-drive-system](http://www.beckhoff.com/distributed-servo-drive-system)

## Rotary servomotors 78

- for demanding positioning tasks
- highly dynamic behavior
- brushless three-phase motors
- permanent magnet in the rotor
- 24 bit encoder with SIL 2 safety integration

► [www.beckhoff.com/rotary-servomotors](http://www.beckhoff.com/rotary-servomotors)





### Linear product transport 88

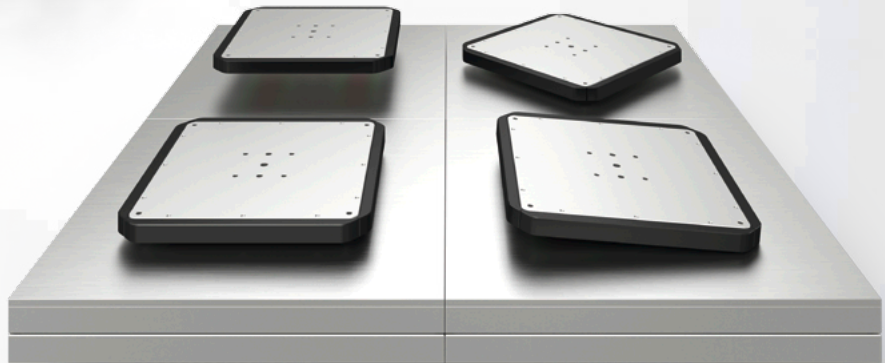
- linear motor on an endless path
- replaces traditional mechanics with advanced mechatronic solutions
- software-based functional changes
- individual product transport with continuous material flow

► [www.beckhoff.com/xts](http://www.beckhoff.com/xts)

### Planar motor system 87

- free-floating movers for non-contact movement
- 6 degrees of freedom
- integrated position feedback
- individual machine layout
- ideal for all application areas

► [www.beckhoff.com/xplanar](http://www.beckhoff.com/xplanar)



**XPlanar®**

### Translatory servomotors 82

- direct drives for highly dynamic and maximum accurate positioning applications
- maximum speed up to 12 m/s
- compact product design with peak forces up to 12500 N
- versatile and modular product concepts

► [www.beckhoff.com/translatory-servomotors](http://www.beckhoff.com/translatory-servomotors)

### Compact Drive Technology 84

- high performance in small design
- motors and output stages for the < 48 V DC low voltage range
- servo, BLDC, stepper and DC motor output stages in IP 20 or IP 67
- smart servo drive with integrated output stage for machines without control cabinets

► [www.beckhoff.com/compact-drive-technology](http://www.beckhoff.com/compact-drive-technology)



- scalable product range of servo drive technology
- integrated safety technology in compliance with safety performance level PL e, integrated into compact Drive Technology up to safety performance level PL d
- As the pioneer of One Cable Technology and the eXtended Transport System, Beckhoff specializes in manufacturing efficient, space-saving motion solutions.

# Servo Drives

► [www.beckhoff.com/servo-drives](http://www.beckhoff.com/servo-drives)



AX8000



AX5000

## AX8000 | Multi-axis Servo System

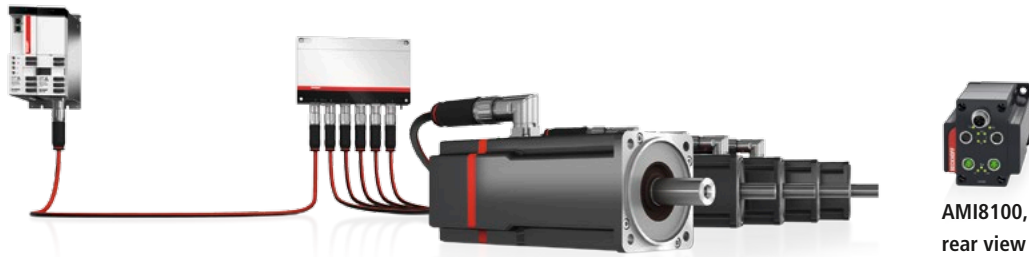
Function			
<b>Power supply module</b>	<b>AX8620</b> 20 A DC	<b>AX8640</b> 40 A DC	
<b>Axis modules</b>	<b>AX8108</b> single-axis module 8 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AX8118</b> single-axis module 18 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AX8206</b> dual-axis module 2 x 6 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion
<b>Combined power supply and axis modules</b>	<b>AX8525</b> combined power supply and axis module 25 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>i AX8540</b> combined power supply and axis module 40 A, feedback: OCT, multi-feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>i</b>
<b>Option modules</b>	<b>AX8810</b> capacitor module	<b>AX8820</b> energy recovery module	<b>i AX8831</b> coupling module, 1-channel <b>i AX8832</b> coupling module with two outputs <b>i</b>

## AX5000 | Digital Compact Servo Drives

Function	1-channel						2-channel			
<b>Servo Drives</b>	<b>AX5101</b> 100...480 V AC, 1.5 A	<b>AX5103</b> 100...480 V AC, 3 A	<b>AX5106</b> 100...480 V AC, 6 A	<b>AX5112</b> 100...480 V AC, 12 A			<b>AX5201</b> 100...480 V AC, 2 x 1.5 A	<b>AX5203</b> 100...480 V AC, 2 x 3 A	<b>AX5206</b> 100...480 V AC, 2 x 6 A	
	<b>AX5118</b> 100...480 V AC, 18 A	<b>AX5125</b> 100...480 V AC, 25 A	<b>AX5140</b> 100...480 V AC, 40 A							
	<b>AX5160</b> 3 x 400...480 V AC, 60 A	<b>AX5172</b> 3 x 400...480 V AC, 72 A	<b>AX5190</b> 3 x 400...480 V AC, 90 A	<b>AX5191</b> 3 x 400...480 V AC, 110 A	<b>AX5192</b> 3 x 400...480 V AC, 143 A	<b>AX5193</b> 3 x 400...480 V AC, 170 A				
<b>Encoder option cards</b>	<b>AX5701</b> EnDat 2.1, Hiperface, BISS B, SinCos 1 V <sub>pp</sub> , BISS C resolver						<b>AX5702</b> EnDat 2.1, Hiperface, BISS B, SinCos 1 V <sub>pp</sub> , BISS C resolver		<b>AX5722</b> 2 x EnDat 2.2, BISS C	
<b>TwinSAFE safe drive technology</b>	<b>AX5801</b> drive-integrated safety functions: STO, SS1	<b>AX5805</b> drive-integrated safety functions: Safe Motion, for AX5x01 to AX5140	<b>AX5806</b> drive-integrated safety functions: Safe Motion, for AX5160 to AX5193							

# Distributed Servo Drive system

► [www.beckhoff.com/distributed-servo-drive-system](http://www.beckhoff.com/distributed-servo-drive-system)



AMI8100,  
rear view

## AMP8000 | Distributed servo drives (400 V AC)

Flange code	Motor length 1	Motor length 2	Motor length 3	Motor length 4
<b>F4 (87 mm)</b>	<b>AMP8041</b> M <sub>0</sub> = 2.40...2.50 Nm, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AMP8042</b> M <sub>0</sub> = 4.10 Nm, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AMP8043</b> M <sub>0</sub> = 5.70 Nm, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	
<b>F5 (104 mm)</b>	<b>AMP8051</b> M <sub>0</sub> = 4.80...4.90 Nm, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AMP8052</b> M <sub>0</sub> = 7.80...8.20 Nm, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AMP8053</b> M <sub>0</sub> = 9.10...11.00 Nm, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AMP8054</b> M <sub>0</sub> = 14.0 Nm, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion

## AMP8600 | Distributed power supply modules

Function			
<b>Supply modules</b>	<b>AMP8620-2005-0000</b> 20 A DC for 400...480 V AC supply voltage, 5-channel, 24 V DC power supply	<b>AMP8620-2005-0100</b> 20 A DC for 400...480 V AC supply voltage, 5-channel, 24 V DC power supply, with regen resistor	<b>AMP8620-2005-0200</b> 20 A DC for 400...480 V AC supply voltage, 5-channel, 24 V DC power supply, with connector for external regen resistor

## AMP8800 | Decentralized distribution module

Function	
<b>Distribution module</b>	<b>AMP8805-1000-0000</b> 5-channel, 24 V DC power supply

## AX8800 | Coupling modules

Function	1-channel	2-channel
<b>Coupling modules</b>	<b>AX8831</b>	<b>AX8832</b>

## AMI8100 | Compact integrated Servo Drives (48 V DC)

Flange code	Motor length 1	Motor length 2	Motor length 3
<b>F2 (58 mm)</b>	<b>AMI8121</b> M <sub>0</sub> = 0.48 Nm	<b>AMI8122</b> M <sub>0</sub> = 0.78 Nm	<b>AMI8123</b> M <sub>0</sub> = 1.00 Nm

# Rotary servomotors

► [www.beckhoff.com/rotary-servomotors](http://www.beckhoff.com/rotary-servomotors)

## AM8000 | Servomotors

Flange code	Motor length 1	Motor length 2	Motor length 3	Motor length 4
<b>F1 (40 mm)</b>	<b>AM8011</b> M <sub>0</sub> = 0.20 Nm	<b>AM8012</b> M <sub>0</sub> = 0.38 Nm	<b>AM8013</b> M <sub>0</sub> = 0.52 Nm	
<b>F2 (58 mm)</b>	<b>AM8021</b> M <sub>0</sub> = 0.50 Nm	<b>AM8022</b> M <sub>0</sub> = 0.80 Nm	<b>AM8023</b> M <sub>0</sub> = 1.20 Nm	
<b>F3 (72 mm)</b>	<b>AM8031</b> M <sub>0</sub> = 1.37...1.40 Nm	<b>AM8032</b> M <sub>0</sub> = 2.37...2.38 Nm	<b>AM8033</b> M <sub>0</sub> = 3.20...3.22 Nm	
<b>F4 (87 mm)</b>	<b>AM8041</b> M <sub>0</sub> = 2.37...2.45 Nm	<b>AM8042</b> M <sub>0</sub> = 4.10 Nm	<b>AM8043</b> M <sub>0</sub> = 5.60...5.65 Nm	
<b>F5 (104 mm)</b>	<b>AM8051</b> M <sub>0</sub> = 4.80...6.30 Nm	<b>AM8052</b> M <sub>0</sub> = 8.20...10.7 Nm	<b>AM8053</b> M <sub>0</sub> = 11.4...15.4 Nm	<b>AM8054</b> M <sub>0</sub> = 13.8...17.2 Nm
<b>F6 (142 mm)</b>	<b>AM8061</b> M <sub>0</sub> = 12.8...17.1 Nm	<b>AM8062</b> M <sub>0</sub> = 21.1...29.9 Nm	<b>AM8063</b> M <sub>0</sub> = 29.0...41.4 Nm	<b>AM8064</b> M <sub>0</sub> = 35.0...49.0 Nm
<b>F7 (197 mm)</b>	<b>AM8071</b> M <sub>0</sub> = 31.8...42.8 Nm	<b>AM8072</b> M <sub>0</sub> = 54.6...80.7 Nm	<b>AM8073</b> M <sub>0</sub> = 70.0...104 Nm	<b>AM8074</b> M <sub>0</sub> = 92.0...129 Nm

## AM8500 | Servomotors with increased rotor moment of inertia

Flange code	Motor length 1	Motor length 2	Motor length 3
<b>F3 (72 mm)</b>	<b>AM8531</b> M <sub>0</sub> = 1.37...1.40 Nm	<b>AM8532</b> M <sub>0</sub> = 2.37...2.38 Nm	<b>AM8533</b> M <sub>0</sub> = 3.20...3.22 Nm
<b>F4 (87 mm)</b>	<b>AM8541</b> M <sub>0</sub> = 2.37...2.45 Nm	<b>AM8542</b> M <sub>0</sub> = 4.10 Nm	<b>AM8543</b> M <sub>0</sub> = 5.60...5.65 Nm
<b>F5 (104 mm)</b>	<b>AM8551</b> M <sub>0</sub> = 4.80...6.30 Nm	<b>AM8552</b> M <sub>0</sub> = 8.20...10.7 Nm	<b>AM8553</b> M <sub>0</sub> = 11.4...15.4 Nm
<b>F6 (142 mm)</b>	<b>AM8561</b> M <sub>0</sub> = 12.8...17.1 Nm	<b>AM8562</b> M <sub>0</sub> = 21.1...29.9 Nm	<b>AM8563</b> M <sub>0</sub> = 29.0...41.1 Nm

## AM8700 | Servomotors with anodized housing

Flange code	Motor length 1	Motor length 2	Motor length 3
<b>R3 (89 mm)</b>	<b>AM8731</b> M <sub>0</sub> = 1.38 Nm	<b>AM8732</b> M <sub>0</sub> = 2.37 Nm	<b>AM8733</b> M <sub>0</sub> = 3.22 Nm
<b>R4 (114 mm)</b>	<b>AM8741</b> M <sub>0</sub> = 2.45 Nm	<b>AM8742</b> M <sub>0</sub> = 4.10 Nm	<b>AM8743</b> M <sub>0</sub> = 5.65 Nm
<b>R5 (134 mm)</b>	<b>AM8751</b> M <sub>0</sub> = 4.90 Nm	<b>AM8752</b> M <sub>0</sub> = 8.20 Nm	<b>AM8753</b> M <sub>0</sub> = 11.40 Nm
<b>R6 (189 mm)</b>	<b>AM8761</b> M <sub>0</sub> = 12.80 Nm	<b>AM8762</b> M <sub>0</sub> = 21.10 Nm	<b>AM8763</b> M <sub>0</sub> = 29.00 Nm



### AM8800 | Stainless steel servomotors with hygienic design

Flange code	Motor length 1	Motor length 2	Motor length 3
<b>R3 (89 mm)</b>	<b>AM8831</b> M <sub>0</sub> = 0.85 Nm	<b>AM8832</b> M <sub>0</sub> = 1.40 Nm	<b>AM8833</b> M <sub>0</sub> = 1.85 Nm
<b>R4 (114 mm)</b>	<b>AM8841</b> M <sub>0</sub> = 1.60 Nm	<b>AM8842</b> M <sub>0</sub> = 2.60 Nm	<b>AM8843</b> M <sub>0</sub> = 3.50 Nm
<b>R5 (134 mm)</b>	<b>AM8851</b> M <sub>0</sub> = 3.10 Nm	<b>AM8852</b> M <sub>0</sub> = 4.80 Nm	<b>AM8853</b> M <sub>0</sub> = 6.40 Nm
<b>R6 (189 mm)</b>	<b>AM8861</b> M <sub>0</sub> = 7.75 Nm	<b>AM8862</b> M <sub>0</sub> = 13.1 Nm	<b>AM8863</b> M <sub>0</sub> = 16.7 Nm

### AM3000 | Servomotors

Flange code	Motor length 1	Motor length 2	Motor length 3	Motor length 4	Motor length 5
<b>F1 (40 mm)</b>	<b>AM3011</b> M <sub>0</sub> = 0.18 Nm	<b>AM3012</b> M <sub>0</sub> = 0.31 Nm	<b>AM3013</b> M <sub>0</sub> = 0.40...0.41 Nm		
<b>F2 (58 mm)</b>	<b>AM3021</b> M <sub>0</sub> = 0.48 Nm	<b>AM3022</b> M <sub>0</sub> = 0.84...0.87 Nm	<b>AM3023</b> M <sub>0</sub> = 1.13...1.16 Nm	<b>AM3024</b> M <sub>0</sub> = 1.38...1.41 Nm	
<b>F3 (72 mm)</b>	<b>AM3031</b> M <sub>0</sub> = 1.15...1.20 Nm	<b>AM3032</b> M <sub>0</sub> = 2.00...2.10 Nm	<b>AM3033</b> M <sub>0</sub> = 2.71...2.79 Nm		
<b>F4 (87 mm)</b>	<b>AM3041</b> M <sub>0</sub> = 1.95...2.06 Nm	<b>AM3042</b> M <sub>0</sub> = 3.35...3.53 Nm	<b>AM3043</b> M <sub>0</sub> = 4.70...4.82 Nm	<b>AM3044</b> M <sub>0</sub> = 5.76...6.00 Nm	
<b>F5 (104 mm)</b>	<b>AM3051</b> M <sub>0</sub> = 4.70...4.79 Nm	<b>AM3052</b> M <sub>0</sub> = 8.43...8.60 Nm	<b>AM3053</b> M <sub>0</sub> = 11.37...11.60 Nm	<b>AM3054</b> M <sub>0</sub> = 14.1...14.9 Nm	
<b>F6 (142 mm)</b>		<b>AM3062</b> M <sub>0</sub> = 11.9...12.2 Nm	<b>AM3063</b> M <sub>0</sub> = 16.6...17.0 Nm	<b>AM3064</b> M <sub>0</sub> = 20.4...21.0 Nm	<b>AM3065</b> M <sub>0</sub> = 24.3...25.0 Nm
<b>F7 (197 mm)</b>		<b>AM3072</b> M <sub>0</sub> = 29.4...30.0 Nm	<b>AM3073</b> M <sub>0</sub> = 41.6...42.0 Nm	<b>AM3074</b> M <sub>0</sub> = 51.9...53.0 Nm	
<b>AM308x</b>		<b>AM3082</b> M <sub>0</sub> = 75.0 Nm	<b>AM3083</b> M <sub>0</sub> = 130.0 Nm	<b>AM3084</b> M <sub>0</sub> = 180.0 Nm	

# Planetary gear units

► [www.beckhoff.com/planetary-gears](http://www.beckhoff.com/planetary-gears)

## AG2300 | High-end planetary gear units with output shaft

Sizes	Design straight
SP060	AG2300-+SP060S nominal output torque 21...40 Nm
SP075	AG2300-+SP075S nominal output torque 41...106 Nm
SP100	AG2300-+SP100S nominal output torque 76...277 Nm
SP140	AG2300-+SP140S nominal output torque 127...581 Nm
SP180	AG2300-+SP180S nominal output torque 289...1162 Nm
SP210	AG2300-+SP210S nominal output torque 728...2200 Nm
SP240	AG2300-+SP240S nominal output torque 1344...3784 Nm

## AG2400 | High-end planetary gear units with output flange

Sizes	Design straight
TP004	AG2400-+TP004S nominal output torque 26...48 Nm
TP010	AG2400-+TP010S nominal output torque 77...126 Nm
TP025	AG2400-+TP025S nominal output torque 169...304 Nm
TP050	AG2400-+TP050S nominal output torque 316...607 Nm
TP110	AG2400-+TP110S nominal output torque 861...1408 Nm
TP300	AG2400-+TP300S nominal output torque 1354...2353 Nm
TP500	AG2400-+TP500S nominal output torque 2800...4400 Nm

## AG2800 | Planetary gear units in hygienic design

Sizes	Design straight
HDV015	AG2800-+HDV015S nominal output torque 15...16 Nm
HDV025	AG2800-+HDV025S nominal output torque 35...40 Nm
HDV035	AG2800-+HDV035S nominal output torque 90...100 Nm





AG2300



AG2400



AG2800



AG3210



AG3300



AG3400

### AG3210 | Economy planetary gear units

Sizes	Design straight
<b>NP005</b>	<b>AG3210--+NP005S</b> nominal output torque 5.1...6.5 Nm
<b>NP015</b>	<b>AG3210--+NP015S</b> nominal output torque 17...21 Nm
<b>NP025</b>	<b>AG3210--+NP025S</b> nominal output torque 40...50 Nm
<b>NP035</b>	<b>AG3210--+NP035S</b> nominal output torque 100...130 Nm
<b>NP045</b>	<b>AG3210--+NP045S</b> nominal output torque 200...350 Nm

### AG3300 | Economy planetary gear units

Sizes	Design straight
<b>NPS015</b>	<b>AG3300--+NPS015S</b> nominal output torque 17...21 Nm
<b>NPS025</b>	<b>AG3300--+NPS025S</b> nominal output torque 40...50 Nm
<b>NPS035</b>	<b>AG3300--+NPS035S</b> nominal output torque 100...130 Nm
<b>NPS045</b>	<b>AG3300--+NPS045S</b> nominal output torque 200...350 Nm

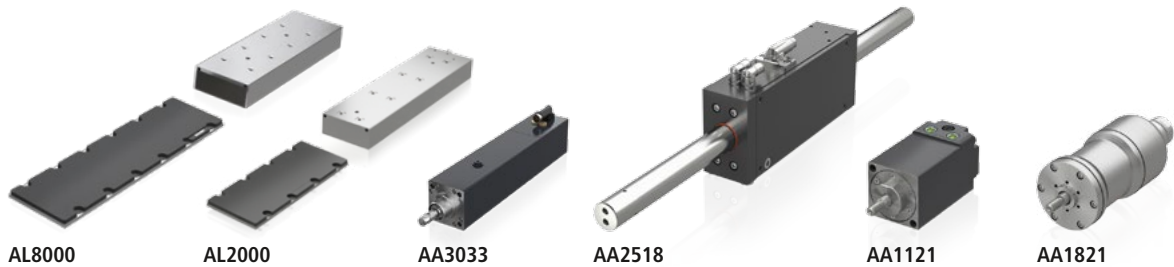
### AG3400 | Economy planetary gear units with output flange

Sizes	Design straight
<b>NPT005</b>	<b>AG3400--+NPT005S</b> nominal output torque 5.1...6.5 Nm
<b>NPT015</b>	<b>AG3400--+NPT015S</b> nominal output torque 17...21 Nm
<b>NPT025</b>	<b>AG3400--+NPT025S</b> nominal output torque 40...50 Nm
<b>NPT035</b>	<b>AG3400--+NPT035S</b> nominal output torque 100...130 Nm
<b>NPT045</b>	<b>AG3400--+NPT045S</b> nominal output torque 200...350 Nm

# Translatory servomotors

► [www.beckhoff.com/translatory-servomotors](http://www.beckhoff.com/translatory-servomotors)

AL8000   Highly dynamic linear servomotors			
Peak force	Overall width W2 (50 mm)	Overall width W4 (80 mm)	Overall width W6 (130 mm)
≤ 500 N	<b>AL8021</b> F <sub>max</sub> = 120 N, I <sub>max</sub> = 7.3 A, V <sub>max</sub> = 12 m/s	<b>AL8041</b> F <sub>max</sub> = 230 N, I <sub>max</sub> = 7.2 A, V <sub>max</sub> = 7 m/s	
	<b>AL8022</b> F <sub>max</sub> = 240 N, I <sub>max</sub> = 7.3 A, V <sub>max</sub> = 12 m/s	<b>AL8042</b> F <sub>max</sub> = 460 N, I <sub>max</sub> = 7.2 A, V <sub>max</sub> = 7 m/s	
	<b>AL8024</b> F <sub>max</sub> = 480 N, I <sub>max</sub> = 12 A, V <sub>max</sub> = 12 m/s		
> 500... 1500 N	<b>AL8026</b> F <sub>max</sub> = 720 N, I <sub>max</sub> = 12 A, V <sub>max</sub> = 10 m/s	<b>AL8043</b> F <sub>max</sub> = 690 N, I <sub>max</sub> = 7.2/12 A, V <sub>max</sub> = 3.5/7 m/s	
		<b>AL8044</b> F <sub>max</sub> = 920 N, I <sub>max</sub> = 7.2/15 A, V <sub>max</sub> = 3.5/7 m/s	
		<b>AL8045</b> F <sub>max</sub> = 1150 N, I <sub>max</sub> = 12/24 A, V <sub>max</sub> = 3.5/7 m/s	
		<b>AL8046</b> F <sub>max</sub> = 1380 N, I <sub>max</sub> = 12/24 A, V <sub>max</sub> = 3.5/7 m/s	
> 1500 N		<b>AL8048</b> F <sub>max</sub> = 1840 N, I <sub>max</sub> = 15/29 A, V <sub>max</sub> = 3.5/7 m/s	<b>AL8064</b> F <sub>max</sub> = 1800 N, I <sub>max</sub> = 12/24 A, V <sub>max</sub> = 3/6 m/s
			<b>AL8065</b> F <sub>max</sub> = 2250 N, I <sub>max</sub> = 15/24 A, V <sub>max</sub> = 3/6 m/s
			<b>AL8066</b> F <sub>max</sub> = 2700 N, I <sub>max</sub> = 18/42 A, V <sub>max</sub> = 3/6 m/s
			<b>AL806A</b> F <sub>max</sub> = 4500 N, I <sub>max</sub> = 24/72 A, V <sub>max</sub> = 3/6 m/s
			<b>AL806F</b> F <sub>max</sub> = 6750 N, I <sub>max</sub> = 42/100 A, V <sub>max</sub> = 3/6 m/s



## AL2000 | Linear servomotors

Continuous force	Winding type S	Winding type N   S					
≤ 500 N	<b>AL2003</b> F <sub>p</sub> = 225 N, I <sub>p</sub> = 5 A, F <sub>c</sub> = 75 N	<b>AL2006</b> F <sub>p</sub> = 450 N, I <sub>p</sub> = 6.5/15 A, F <sub>c</sub> = 200 N					
	<b>AL2403</b> F <sub>p</sub> = 120 N, I <sub>p</sub> = 4.1 A, F <sub>c</sub> = 45 N	<b>AL2406</b> F <sub>p</sub> = 240 N, I <sub>p</sub> = 8.2 A, F <sub>c</sub> = 90 N					
	<b>AL2412</b> F <sub>p</sub> = 480 N, I <sub>p</sub> = 16.4 A, F <sub>c</sub> = 240 N						
> 500... 1500 N		<b>AL2009</b> F <sub>p</sub> = 675 N, I <sub>p</sub> = 6.5/19 A, F <sub>c</sub> = 300 N	<b>AL2012</b> F <sub>p</sub> = 900 N, I <sub>p</sub> = 8/26 A, F <sub>c</sub> = 400 N	<b>AL2015</b> F <sub>p</sub> = 1125 N, I <sub>p</sub> = 13/33 A, F <sub>c</sub> = 500 N	<b>AL2018</b> F <sub>p</sub> = 1350 N, I <sub>p</sub> = 13/33 A, F <sub>c</sub> = 600 N	<b>AL2418</b> F <sub>p</sub> = 720 N, I <sub>p</sub> = 12.3 A (N), 25.1 A (S), F <sub>c</sub> = 360 N	
> 1500 N		<b>AL2812</b> F <sub>p</sub> = 1800 N, I <sub>p</sub> = 13/26 A, F <sub>c</sub> = 760 N	<b>AL2815</b> F <sub>p</sub> = 2250 N, I <sub>p</sub> = 13.5/33 A, F <sub>c</sub> = 950 N	<b>AL2818</b> F <sub>p</sub> = 2700 N, I <sub>p</sub> = 19.6/41 A, F <sub>c</sub> = 1140 N	<b>AL2830</b> F <sub>p</sub> = 4500 N, I <sub>p</sub> = 26/66 A, F <sub>c</sub> = 2000 N	<b>AL2845</b> I <sub>p</sub> = 41/98 A, F <sub>c</sub> = 2850 N	<b>AL2024</b> F <sub>p</sub> = 1800 N, I <sub>p</sub> = 26/52 A, F <sub>c</sub> = 800 N

## AA3033 | Electric cylinders (400 V AC)

Peak force	Flange code 75 mm
> 5000... 15000 N	<b>AA3033</b> F <sub>p</sub> = 12500 N, F <sub>c</sub> = 3240 N

## AA2500 | Tubular motors (400 V AC)

Peak force	Continuous force ≥ 300 N
> 500... 1500 N	<b>AA2518</b> F <sub>p</sub> = 1050 N, I <sub>p</sub> = 15 A, F <sub>c</sub> = 300 N

## AA1000 | Linear actuators (48 V DC)

Peak force	Continuous force ≥ 300 N	Continuous force > 150 N
> 500... 1500 N	<b>AA1121</b> F <sub>p</sub> = 800 N, F <sub>c</sub> = 300 N	<b>AA1821</b> F <sub>p</sub> = 800 N, F <sub>c</sub> = 160 N

# Compact Drive Technology

► [www.beckhoff.com/compact-drive-technology](http://www.beckhoff.com/compact-drive-technology)

## AM8100 | Servomotors for compact drive technology

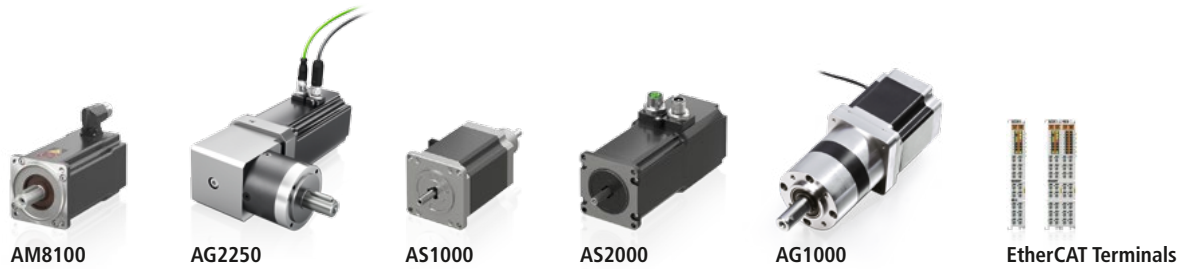
Flange code	Motor length 1	Motor length 2	Motor length 3
<b>F1 (40 mm)</b>	<b>AM8111</b> M <sub>0</sub> = 0.20 Nm	<b>AM8112</b> M <sub>0</sub> = 0.38 Nm	<b>AM8113</b> M <sub>0</sub> = 0.52 Nm
<b>F2 (58 mm)</b>	<b>AM8121</b> M <sub>0</sub> = 0.50 Nm	<b>AM8122</b> M <sub>0</sub> = 0.80 Nm	<b>AM8123</b> M <sub>0</sub> = 1.20 Nm
<b>F3 (72 mm)</b>	<b>AM8131</b> M <sub>0</sub> = 1.30...1.35 Nm	<b>AM8132</b> M <sub>0</sub> = 2.37...2.40 Nm	<b>AM8133</b> M <sub>0</sub> = 3.2 Nm
<b>F4 (87 mm)</b>	<b>AM8141</b> M <sub>0</sub> = 2.40 Nm	<b>AM8142</b> M <sub>0</sub> = 3.9 Nm	

## AG2250 | Planetary gear units for servo and stepper motors

Sizes	Design straight	Design angled
<b>PLE40</b>	<b>AG2250-+PLE40</b> nominal output torque 5...20 Nm	
<b>PLE60</b>	<b>AG2250-+PLE60</b> nominal output torque 15...44 Nm	
<b>PLE80</b>	<b>AG2250-+PLE80</b> nominal output torque 38...120 Nm	
<b>WPLE40</b>		<b>AG2250-+WPLE40</b> nominal output torque 4.5...20 Nm
<b>WPLE60</b>		<b>AG2250-+WPLE60</b> nominal output torque 14...44 Nm
<b>WPLE80</b>		<b>AG2250-+WPLE80</b> nominal output torque 38...120 Nm

## ASxxxx | Stepper motors

Flange code	Rated current (per phase)						
	1.00 A	1.50 A	2.00 A	5.00 A	5.60 A	6.50 A	5.60 A   6.40 A
<b>N1 (NEMA17/ 42 mm)</b>	<b>AS1010</b> 0.40 Nm						
	<b>AS1020</b> 0.5 Nm						
<b>N2 (NEMA23/ 56 mm)</b>		<b>AS1030</b> 0.6 Nm	<b>AS2021</b> 0.8 Nm		<b>AS2022</b> 1.50 Nm		<b>AS2023</b> 1.8 Nm   2.3 Nm
<b>N3 (NEMA34/ 86 mm)</b>				<b>AS1050</b> 1.2 Nm	<b>AS2041</b> 3.3 Nm	<b>AS2043</b> 8.0 Nm	
				<b>AS1060</b> 5.0 Nm	<b>AS2042</b> 6.4 Nm		



## AG1000 | Planetary gear units for AS1000 stepper motors

<b>Sizes</b>	<b>Design straight</b>
<b>PM52</b>	<b>AG1000-+PM52.i</b> nominal output torque 4 Nm
<b>PM81</b>	<b>AG1000-+PM81.i</b> nominal output torque 20 Nm

## EL7xxx | EtherCAT Terminals, motion

Motor type	< 3 A	3...5 A	> 5 A	16 A	
<b>Servomotor</b>			<b>ELM7211-9016</b> <i>I<sub>ms</sub></i> = 4.5 A, 48 V DC	<a href="#"><u>i</u></a>	
			<b>ELM7211-9018</b> <i>I<sub>ms</sub></i> = 4.5 A, 48 V DC, Safe Motion	<a href="#"><u>i</u></a>	
			<b>ELM7212-9016</b> <i>I<sub>ms</sub></i> = 2 x 4.5 A, 48 V DC	<a href="#"><u>i</u></a> <b>ELM7222-9016</b> <i>I<sub>ms</sub></i> = 2 x 8.0 A, 48 V DC	<a href="#"><u>i</u></a>
			<b>ELM7212-9018</b> <i>I<sub>ms</sub></i> = 2 x 4.5 A, 48 V DC, Safe Motion	<a href="#"><u>i</u></a> <b>ELM7222-9018</b> <i>I<sub>ms</sub></i> = 2 x 8.0 A, 48 V DC, Safe Motion	<a href="#"><u>i</u></a>
	<b>EL7201-0010</b> <i>I<sub>ms</sub></i> = 2.8 A, 48 V DC, OCT	<b>EL7211-0010</b> <i>I<sub>ms</sub></i> = 4.5 A, 48 V DC, OCT	<b>ELM7221-9016</b> <i>I<sub>ms</sub></i> = 8 A, 48 V DC	<a href="#"><u>i</u></a> <b>ELM7231-9016</b> <i>I<sub>ms</sub></i> = 16 A, 48 V DC	<a href="#"><u>i</u></a>
	<b>EL7201</b> <i>I<sub>ms</sub></i> = 2.8 A, 48 V DC, resolver	<b>EL7211</b> <i>I<sub>ms</sub></i> = 4.5 A, 48 V DC, resolver	<b>ELM7221-9018</b> <i>I<sub>ms</sub></i> = 8 A, 48 V DC, Safe Motion	<a href="#"><u>i</u></a> <b>ELM7231-9018</b> <i>I<sub>ms</sub></i> = 16 A, 48 V DC, Safe Motion	<a href="#"><u>i</u></a>
	<b>EL7201-9014</b> <i>I<sub>ms</sub></i> = 2.8 A, 48 V DC, OCT, STO	<b>EL7211-9014</b> <i>I<sub>ms</sub></i> = 4.5 A, 48 V DC, OCT, STO	<b>EL7221-9014</b> <i>I<sub>ms</sub></i> = 7...8 A with ZB8610, 48 V DC, OCT, STO		
<b>Stepper motor</b>	<b>EL7031</b> <i>I<sub>max</sub></i> = 1.5 A, 24 V DC	<b>EL7041</b> <i>I<sub>max</sub></i> = 5.0 A, 48 V DC, incremental encoder			
	<b>EL7031-0030</b> <i>I<sub>max</sub></i> = 2.8 A, 24 V DC	<b>EL7041-0052</b> <i>I<sub>max</sub></i> = 5.0 A, 48 V DC			
	<b>EL7037</b> <i>I<sub>max</sub></i> = 1.5 A, 24 V DC, incremental encoder, vector control	<b>EL7047</b> <i>I<sub>max</sub></i> = 5.0 A, 48 V DC, incremental encoder, vector control			
		<b>EL7047-9014</b> <i>I<sub>max</sub></i> = 5.0 A, 48 V DC, incremental encoder, vector control, STO	<a href="#"><u>i</u></a>		
<b>DC motor output stage</b>	<b>EL7332</b> <i>I<sub>max</sub></i> = 1.0 A, 24 V DC	<b>EL7342</b> <i>I<sub>max</sub></i> = 3.5 A, 48 V DC, incremental encoder			
	<b>BLDC</b>		<b>EL7411</b> <i>I<sub>ms</sub></i> = 4.5 A, 48 V DC		
			<b>EL7411-9014</b> <i>I<sub>ms</sub></i> = 4.5 A, 48 V DC, STO	<a href="#"><u>i</u></a>	
<b>4-axis interface</b>	<b>EM7004</b> 4 incremental encoders, 32 digital I/Os 24 V DC, 4 analog outputs ±10 V				

The standard EtherCAT Terminals (ELxxxx) can be optionally ordered as ESxxxx with pluggable wiring level.



EtherCAT Box modules



EtherCAT P Box modules



EtherCAT Plug-in Modules





Bus Terminals

### EP7xxx | EtherCAT Box, motion

Motor type	< 3 A	> 3 A
<b>Servomotor</b>		<b>EP7211-0034</b> <i>I<sub>rms</sub></i> = 4.5 A, 48 V DC, OCT, STO suitable
<b>Stepper motor</b>		<b>EP7047-0032</b>  <b>EP7047-1032</b> <i>I<sub>max</sub></i> = 5.0 A, 48 V DC, STO suitable <i>I<sub>max</sub></i> = 5.0 A, 48 V DC
	<b>EP7041-1002<sup>(1)</sup></b> <i>I<sub>max</sub></i> = 1.5 A, 48 V DC, incremental encoder, 2 digital inputs, 1 digital output	<b>EP7041-0002<sup>(1)</sup></b> <i>I<sub>max</sub></i> = 5 A, 48 V DC, incremental encoder, 2 digital inputs, 1 digital output
		<b>EP7041-2002<sup>(1)</sup></b> <i>I<sub>max</sub></i> = 5 A, 48 V DC, incremental encoder, 2 digital inputs, 1 digital output, motor connection via plug
		<b>EP7041-3002<sup>(1)</sup></b> <i>I<sub>max</sub></i> = 5 A, 48 V DC, incremental encoder, for high-speed applications, encoder system (24 V DC encoder)
		<b>EP7041-3102</b> <i>I<sub>max</sub></i> = 5 A, 48 V DC, incremental encoder, for high-speed applications, encoder system (5 V DC encoder)
		<b>EP7041-4032</b>  <i>I<sub>max</sub></i> = 5.0 A, 48 V DC, BiSS C encoder
<b>DC motor output stage</b>		<b>EP7342-0002<sup>(1)</sup></b> <i>I<sub>max</sub></i> = 3.5 A, 48 V DC
<b>Motor controller</b>		<b>EP7402-0057</b> for roller conveyor systems

EPxxxx: industrial housing in IP 67, <sup>(1)</sup>also as ERxxxx: zinc die-cast housing in IP 67, <sup>(2)</sup>also as EQxxxx: stainless steel housing in IP 69K

### EPP7xxx | EtherCAT P Box, motion

Motor type	< 3 A	> 3 A
<b>Stepper motor</b>	<b>EPP7041-1002</b> <i>I<sub>max</sub></i> = 1.5 A, 48 V DC, incremental encoder	 <b>EPP7041-3002</b> <i>I<sub>max</sub></i> = 5.0 A, 48 V DC, incremental encoder
<b>DC motor output stage</b>		<b>EPP7342-0002</b>  <i>I<sub>max</sub></i> = 3.5 A, 48 V DC

### EJ7xxx | EtherCAT Plug-in Modules, motion

Motor type	< 3 A	3...5 A
<b>Servomotor</b>		<b>EJ7211-0010</b> <i>I<sub>rms</sub></i> = 4.5 A, 48 V DC, OCT
		<b>EJ7211-9414</b> <i>I<sub>rms</sub></i> = 4.5 A, 48 V DC, OCT, STO, TwinSAFE SC
<b>Stepper motor</b>	<b>EJ7031</b> <i>I<sub>max</sub></i> = 1.5 A, 24 V DC	<b>EJ7037</b> <i>I<sub>max</sub></i> = 1.5 A, 24 V DC, incremental encoder, vector control
		<b>EJ7041-0052</b> <i>I<sub>max</sub></i> = 5.0 A, 48 V DC
		<b>EJ7047</b> <i>I<sub>max</sub></i> = 5.0 A, 48 V DC, incremental encoder, vector control
<b>DC motor output stage</b>		<b>EJ7342</b> <i>I<sub>max</sub></i> = 3.5 A, 48 V DC, incremental encoder
<b>BLDC</b>		<b>EJ7411</b> <i>I<sub>rms</sub></i> = 4.5 A, 48 V DC

### KL2xxx | Bus Terminals, motion

	< 3 A	3...5 A
<b>Stepper motor</b>	<b>KL2531</b> <i>I<sub>max</sub></i> = 1.5 A, 24 V DC	<b>KL2541</b> <i>I<sub>max</sub></i> = 5.0 A, 48 V DC, incremental encoder
<b>DC motor output stage</b>	<b>KL2532</b> <i>I<sub>max</sub></i> = 1.0 A, 24 V DC	<b>KL2284</b> reverse switching, <i>I<sub>max</sub></i> = 2.0 A, 0...24 V DC
<b>AC motor speed controller</b>	<b>KL2791</b> 230 V AC, 200 VA, 1-phase AC motor	<b>KL2552</b> <i>I<sub>max</sub></i> = 5.0 A, 48 V DC, incremental encoder

The standard Bus Terminals (KLxxxx) can be optionally ordered as KSxxxx with pluggable wiring level.

# XPlanar | Planar motor system

► [www.beckhoff.com/xplanar](http://www.beckhoff.com/xplanar)



XPlanar   Planar motor system				
<b>Movers</b>	<b>APM4220-0000-0000</b> 0.4 kg payload	<b>APM4330-0000-0000</b> 1.5 kg payload	<b>APM4330-0001-0000</b> 1.0 kg payload, stainless steel	<b>i APM4550-0000-0000</b> 4.2 kg payload
<b>Tile</b>	<b>APS4322-0000-0000</b> 4 active areas			
<b>Starter kits</b>	<b>APS9000</b> 6 (2 x 3) APS4322 planar motor tiles, 2 APM4330 movers, Industrial PC, software, pre-installed, ready for operation	<b>APS9001</b> 12 (4 x 3) APS4322 planar motor tiles, 4 APM4330 movers, Industrial PC, software, pre-installed, ready for operation		

# XTS | Linear product transport

► [www.beckhoff.com/xts](http://www.beckhoff.com/xts)

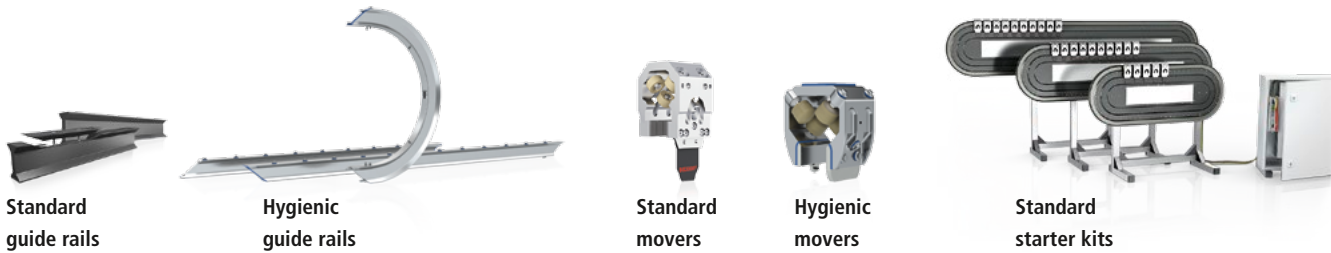


Standard motor modules

Hygienic motor modules

XTS   Motor modules		
Design form	XTS Standard	XTS Hygienic
Straight	<b>AT2000</b> straight, without infeed	<b>ATH2000</b> straight, without infeed
	<b>AT2001</b> straight, with connection cables for infeed	<b>ATH2001</b> straight, with infeed
	<b>AT2002</b> straight, with plug connector for infeed	<b>ATH2002</b> straight, with angled infeed
22.5° curved segment, in 250 mm for Ø 1273 mm	<b>AT2020</b> 22.5° curved segment, without infeed	
	<b>AT2021</b> 22.5° curved segment, with connection cables for infeed	
-22.5° curved segment, in 250 mm for Ø 1273 mm	<b>AT2025</b> -22.5° curved segment, without infeed	
	<b>AT2026</b> -22.5° curved segment, with connection cables for infeed	
45° curved segment, in 250 mm for Ø 637 mm	<b>AT2040</b> 45° curved segment, without infeed	<b>ATH2040</b> 45° curved segment, without infeed <span style="float: right;"><a href="#">i</a></span>
	<b>AT2041</b> 45° curved segment, with connection cables for infeed	<b>ATH2041</b> 45° curved segment, with straight infeed <span style="float: right;"><a href="#">i</a></span>
	<b>AT2042</b> 45° curved segment, with plug connector for infeed	<b>ATH2042</b> 45° curved segment, with angled infeed <span style="float: right;"><a href="#">i</a></span>
180° curved segment, clothoid	<b>AT2050</b> 180° curved segment, without infeed	<b>ATH2050</b> 180° curved segment, without infeed
		<b>ATH2051</b> 180° curved segment, with straight infeed





XTS   Guide rails		
Design form	XTS Standard	XTS Hygienic
Straight	<b>AT9000</b> straight, without lock	<b>ATH9000</b> straight, without lock
	<b>AT9100</b> straight, with lock	<b>ATH9100</b> straight, with lock
		<b>ATH9200</b> straight, connector
45° curved segment, for Ø 637 mm	<b>AT9040</b> 45° curved segment, without lock	
180° curved segment, clothoid	<b>AT9050</b> 180° curved segment, without lock	<b>ATH9050</b> 180° curved segment

XTS   Movers		
Material	XTS Standard	XTS Hygienic
Aluminium	<b>AT9011</b> mover, 6 rollers	<b>ATH9013</b> aluminium mover
	<b>AT9012</b> mover, 12 rollers	
	<b>AT9001</b> magnetic plate sets	
Stainless steel		<b>ATH9011</b> stainless steel mover
		<b>ATH9001</b> hygienic magnetic plate sets

XTS   Starter kits	
	Mover 70 mm length
Small	AT2000-0500-0070
Medium	AT2000-1000-0070
Large	AT2000-1500-0070

# The Automation Company

Beckhoff offers comprehensive system solutions in numerous performance classes for all areas of automation. The control technology is exceptionally scalable – from high-performance Industrial PCs to mini-PLCs – and can be adapted precisely to application-specific requirements. TwinCAT automation software integrates real-time control with PLC, NC and CNC functions in a single feature-filled package.

► [www.beckhoff.com/automation](http://www.beckhoff.com/automation)

## Efficient engineering

- integration into Microsoft Visual Studio®
- wide selection of programming languages: IEC 61131-3, C/C++, MATLAB®/Simulink®, Safety C/FBD
- modular software development
- automatic code generation interface
- link to source code control systems

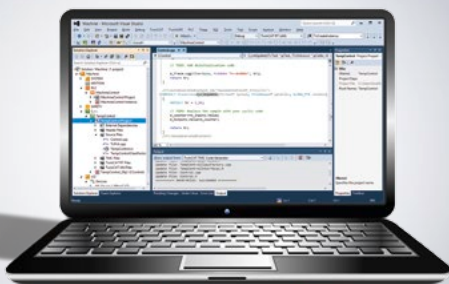
## High performance

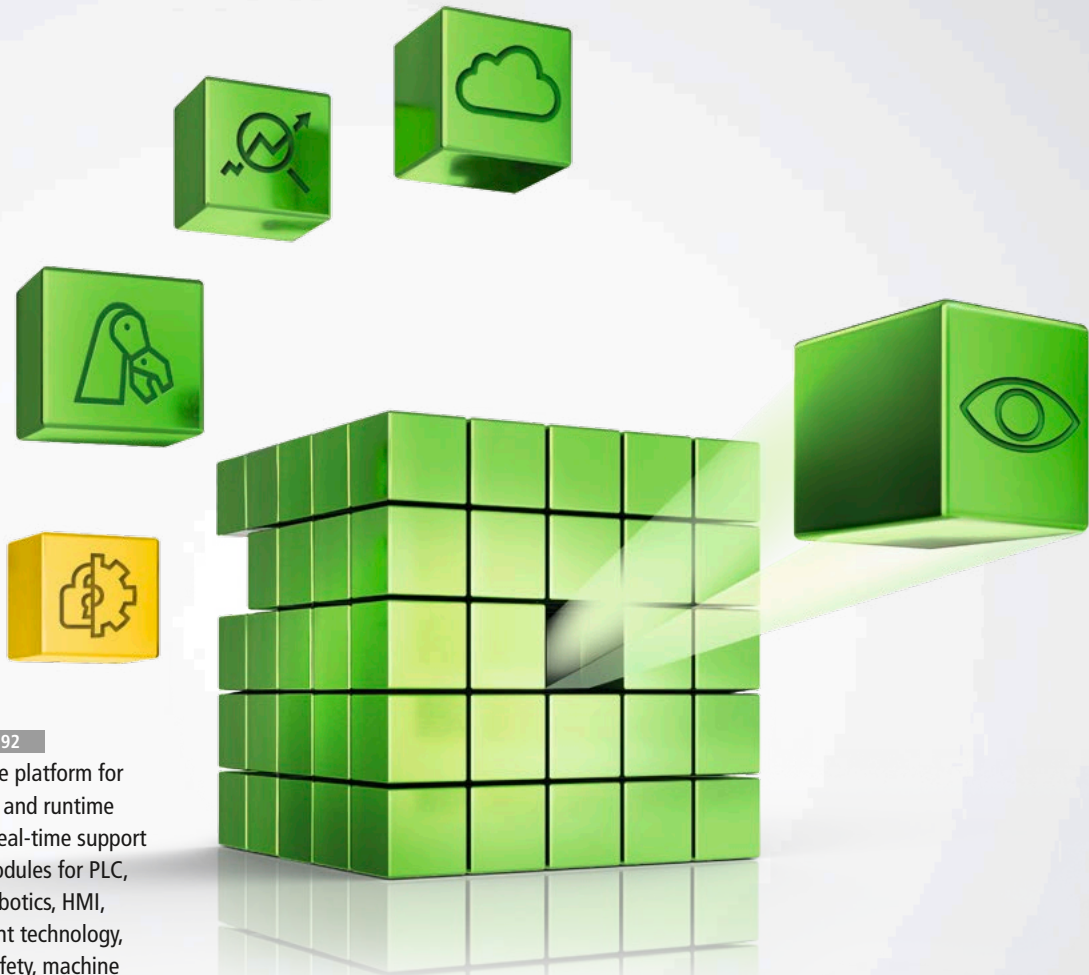
- cycle times from 50 µs
- multi-core support
- support of 32-bit and 64-bit operating systems
- pre-emptive multitasking

## Connectivity

- useable with all fieldbus systems
- open and expandable for IT trends – today and tomorrow
- adheres to industry-specific and standard protocols
- ideal for IoT and cloud computing applications

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**TwinCAT 3** 92

- one software platform for engineering and runtime
- integrated real-time support
- software modules for PLC, NC, CNC, robotics, HMI, measurement technology, analytics, safety, machine vision, machine learning

**TwinCAT 2** 98

- open, compatible PC hardware
- embedded IEC 61131-3 software PLC, software NC and software CNC
- connection to all common fieldbuses

**TwinSAFE** 102

- integrated safety system from I/Os to drives
- compact safety PLC
- certified for solutions up to IEC 61508 SIL 3 and DIN EN ISO 13849-1:2008 PL e
- safety engineering integrated into TwinCAT 3

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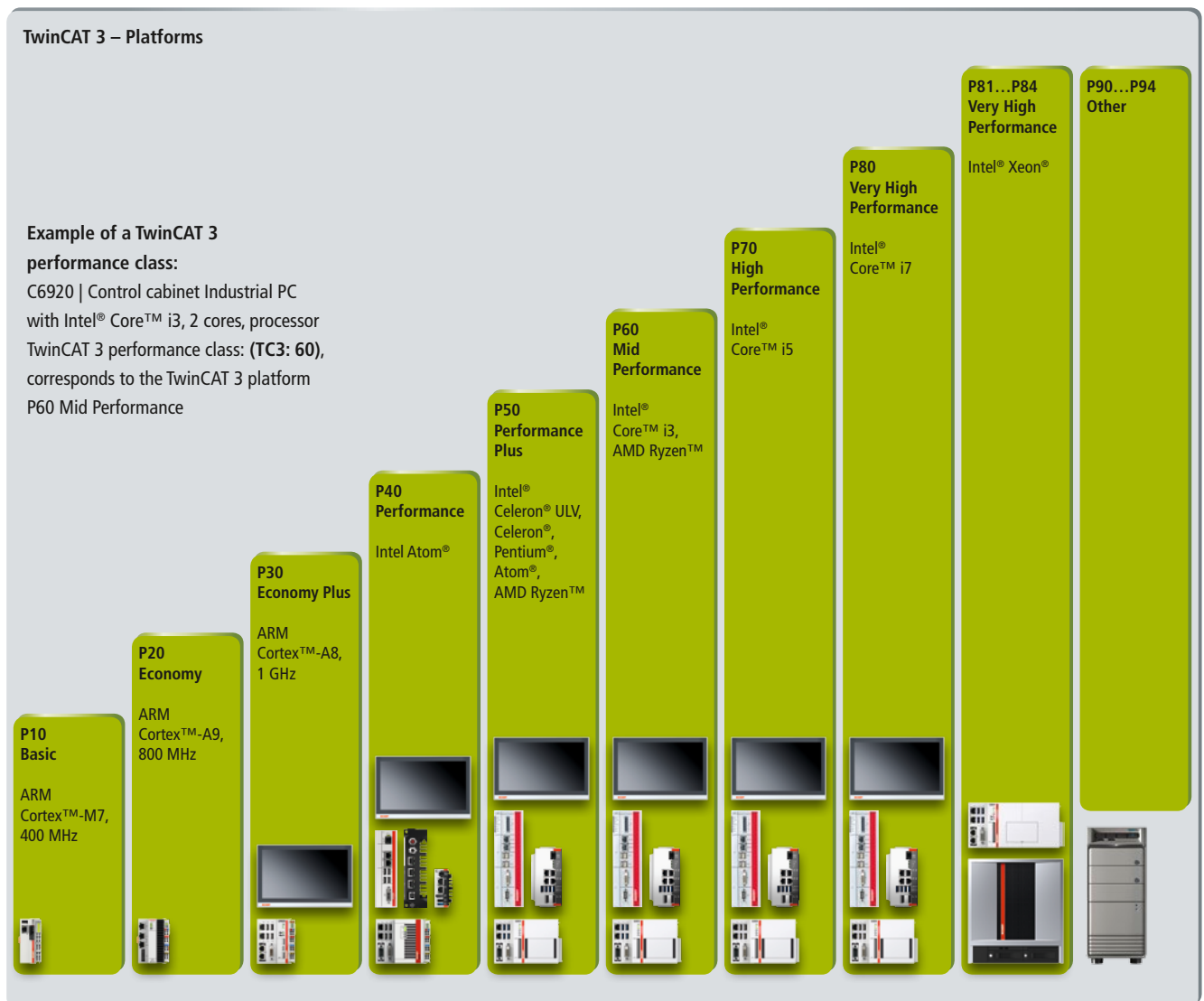
- efficient, universal engineering
- programming in different languages
- Open, hardware-independent control system gives freedom of choice in terms of automation and control components.
- scalable control platform from single- to multi-core CPUs
- all control functions on a single, centralized platform: PLC, motion control, robotics, measurement technology, a.o.

# TwinCAT 3

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The TwinCAT 3 runtime components are available for different platforms. The platform levels correspond to the various TwinCAT 3 performance classes of the Beckhoff PCs. The TwinCAT 3 performance class of a Beckhoff PC depends on the configuration and the technical data of the PC (including the processor).

The following overview shows the various TwinCAT 3 platforms. The controllers integrated in the platform classifications represent sample configurations. The TwinCAT 3 performance class required for a TwinCAT 3 Runtime component can be found in the product description of the respective Beckhoff PC.



The controllers integrated in the platform categorization are only example configurations.

### TwinCAT 3 – eXtended Automation Engineering (XAE)

### TwinCAT 3 – eXtended Automation Runtime (XAR)

#### Base

TC1270 | TC3 PLC/NC PTP 10/NC I/CNC  
 TC1260 | TC3 PLC/NC PTP 10/NC I  
 TC1250 | TC3 PLC/NC PTP 10  
 TC1200 | TC3 PLC  
 TC1100 | TC3 I/O  
 TC1000 | TC3 ADS

TC1220 | TC3 PLC/C++/MATLAB®/Simulink®  
 TC1210 | TC3 PLC/C++  
 TC1100 | TC3 I/O  
 TC1000 | TC3 ADS

TC1320 | TC3 C++/MATLAB®/Simulink®  
 TC1300 | TC3 C++  
 TC1100 | TC3 I/O  
 TC1000 | TC3 ADS

#### Functions

TF1xxx | System

TF5xxx | Motion

TF2xxx | HMI

TF6xxx | Connectivity

TF3xxx | Measurement

TF7xxx | Vision

TF4xxx | Controller

TF8xxx | Industry specific

TwinCAT 3 is divided into components. The TwinCAT 3 engineering components enable the configuration, programming and debugging of applications. The TwinCAT 3 runtime consists of further components – basic components and functions. The basic components can be extended by functions.

## TExxxx | TwinCAT 3, Engineering

TC3 Engineering	TE1000	TwinCAT 3 engineering environment	
TC3 Realtime Monitor	TE1010	tool for precise diagnostics and optimization of the runtime behavior of tasks in the TwinCAT 3 runtime	
TC3 EtherCAT Simulation	TE1111	easy configurations of simulation environments with several EtherCAT slaves	
TC3 XCAD Interface	TE1120	interface between ECAD tools and TwinCAT 3	
TC3 CAD Simulation Interface	TE1130	link between TwinCAT and a 3D CAD system for SiL simulation	<b>i</b>
TC3 PLC Static Analysis	TE1200	analysis tool that tests PLC software on the basis of coding rules	
TC3 Scope View Professional	TE1300	software oscilloscope for the graphical display of data captured from several target systems	
TC3 Filter Designer	TE1310	graphic engineering tool for determining coefficient digital filters	
TC3 Target for Simulink®	TE1400	TwinCAT target for Simulink® for generating TwinCAT 3 modules	
TC3 Target for MATLAB®	TE1401	TwinCAT target for MATLAB® for generating TwinCAT 3 modules	<b>i</b>
TC3 Interface for MATLAB®/Simulink®	TE1410	communication interface between MATLAB®/Simulink® and the TwinCAT 3 runtime	
TC3 Target for FMI	TE1420	interface for simulation tools that support the Functional Mockup Interface (FMI)	<b>i</b>
TC3 Valve Diagram Editor	TE1500	graphical tool for designing the characteristic curve of a hydraulic valve	
TC3 Cam Design Tool	TE1510	graphic design tool for electronic cam plates	
TC3 EAP Configurator	TE1610	a tool for visualizing and configuring communication networks, in which data exchange based on the EtherCAT Automation Protocol (EAP) takes place or is to be established	
TC3 HMI Engineering	TE2000	tool for developing platform-independent user interfaces	
TC3 Analytics Workbench	TE3500	complete solution for 24/7 monitoring of machines and systems incl. visualization on analysis dashboards	
TC3 Analytics Service Tool	TE3520	process data analysis tool for commissioning and service technicians	
TC3 Motion Designer	TE5910	TC3 Motion Designer for drive dimensioning	
TC3 Drive Manager 2	TE5950	for commissioning the AX8000, AX5000, AMI8100, AMP8000 or the I/O components EL72xx, EP72xx and EJ72xx	

## TC1xxx | TwinCAT 3, Base

TC3 ADS	TC1000	TwinCAT 3 ADS	
TC3 I/O	TC1100	TwinCAT 3 I/O	
TC3 PLC	TC1200	TwinCAT 3 PLC	
TC3 PLC/C++	TC1210	TwinCAT 3 PLC and C++	
TC3 PLC/C++/MATLAB®/Simulink®	TC1220	TwinCAT 3 PLC, C++ and modules generated in MATLAB®/Simulink®	
TC3 PLC/NC PTP 10	TC1250	TwinCAT 3 PLC and NC PTP 10	
TC3 PLC/NC PTP 10/NC I	TC1260	TwinCAT 3 PLC, NC PTP 10 and NC I	
TC3 PLC/NC PTP 10/NC I/CNC	TC1270	TwinCAT 3 PLC, NC PTP 10, NC I and CNC	
TC3 PLC/NC PTP 10/NC I/CNC E	TC1275	TwinCAT 3 PLC, NC PTP 10, NC I and CNC E	
TC3 C++	TC1300	TwinCAT 3 C++	
TC3 C++/MATLAB®/Simulink®	TC1320	TwinCAT 3 C++ and modules generated in MATLAB®/Simulink®	

## TF1xxx | TwinCAT 3, Functions, System

TC3 PLC HMI	TF1800	stand-alone tool for displaying visualizations from the PLC development environment	
TC3 PLC HMI Web	TF1810	display of visualizations from the PLC development environment in a web browser	
TC3 UML	TF1910	UML (Unified Modeling Language) for modeling of PLC software	

## TF2xxx | TwinCAT 3, Functions, HMI

TC3 HMI Server	TF2000	modular web server, includes a client connection and a target connection
TC3 HMI Clients Packs	TF20x0	optional extension of the TC3 HMI Server with up to 100 additional client connections
TC3 HMI Targets Packs	TF20xx	optional extension of the TC3 HMI Server with up to 100 additional control systems
TC3 HMI OPC UA	TF2110	server extension for access to TwinCAT target systems or other controllers via OPC UA
TC3 HMI Extension SDK	TF2200	software development kit (C++/.NET) for programming application-specific solutions
TC3 HMI Scope	TF2300	software oscilloscope for graphic display of time sequences

[i](#)

## TF3xxx | TwinCAT 3, Functions, Measurement

TC3 Scope Server	TF3300	data preparation for visual display in the TwinCAT 3 Scope View
TC3 Analytics Logger	TF3500	The TwinCAT Analytics Logger enables the cyclic archiving of the process image.
TC3 Analytics Library	TF3510	PLC library used for online or offline analysis in the PLC runtime of the TwinCAT Analytics Workbench
TC3 Analytics Storage Provider	TF3520	IoT client: interface to one or more storage facilities for raw and analysis data from various sources
TC3 Analytics Runtime	TF3550	license bundle for the operation of an analytics application including HMI dashboard created with Analytics Workbench
TC3 Analytics Runtime Base	TF3551	license bundle for the operation of an analytics application created with Analytics Workbench
TC3 Analytics Controller Packs	TF356x	extension of the TC3 Analytics Workbench for the analysis of up to 128 additional controllers
TC3 Condition Monitoring	TF3600	PLC library for the implementation of condition monitoring for machines
TC3 Power Monitoring	TF3650	TwinCAT Power Monitoring PLC library
TC3 Filter	TF3680	PLC library for implementing digital filters
TC3 Interface for LabVIEW™	TF3710	enables the exchange of data between LabVIEW™ and the TwinCAT runtime
TC3 Machine Learning Inference Engine	TF3800	execution module of trained classical machine learning algorithms
TC3 Neural Network Inference Engine	TF3810	execution module of trained neural networks
TC3 Solar Position Algorithm	TF3900	precise calculation of the sun's position

## TF4xxx | TwinCAT 3, Functions, Controller

TC3 Controller Toolbox	TF4100	basic controllers (P, I, D), complex controllers (PI, PID), pulse width modulation, ramps, signal generators and filters
TC3 Temperature Controller	TF4110	temperature control for monitoring and controlling different temperature ranges
TC3 TwinCAT Speech	TF4500	enables the multilingual input and output of queries or information implemented in an industrially compatible way

## TF5xxx | TwinCAT 3, Functions, Motion

TC3 NC PTP 10 Axes	TF5000	NC PTP (point-to-point movements) for up to 10 axes
TC3 NC PTP Axes Pack 25	TF5010	extension of TwinCAT 3 NC PTP to 25 axes
TC3 NC PTP Axes Pack unlimited	TF5020	extension of TwinCAT 3 NC PTP to 255 axes
TC3 NC Camming	TF5050	providing the cam plate functionality (table coupling) of TwinCAT NC
TC3 NC Flying Saw	TF5055	providing flying saw functionality
TC3 NC FIFO Axes	TF5060	providing a FIFO interface for setpoint generation of an NC axis group
TC3 Motion Control XFC	TF5065	high-precision logging and switching of digital signals in relation to axis positions

## TF5xxx | TwinCAT 3, Functions, Motion

<b>TC3 NC I</b>	TF5100	NC I with 3 interpolating path axes and 5 auxiliary axes
<b>TC3 Kinematic Transformation L1</b>	TF5110	realization of different kinematic transformations Level 1
<b>TC3 Kinematic Transformation L2</b>	TF5111	realization of different kinematic transformations Level 2
<b>TC3 Kinematic Transformation L3</b>	TF5112	realization of different kinematic transformations Level 3
<b>TC3 Kinematic Transformation L4</b>	TF5113	realization of different kinematic transformations Level 4
<b>TC3 Robotics mxAutomation</b>	TF5120	direct communication between the PLC and a KUKA robot control
<b>TC3 Robotics uniVAL PLC</b>	TF5130	direct communication between the PLC and a Stäubli robot control
<b>TC3 CNC</b>	TF5200	CNC path control software
<b>TC3 CNC E</b>	TF5210	CNC path control software export version
<b>TC3 CNC Axes Pack</b>	TF5220	extension to up to a total of 64 axes/controlled spindles, of which a maximum of 32 can be path axes and a maximum of 12 can be controlled spindles
<b>TC3 CNC Measurement</b>	TF5225	optional package of CNC cycles that supports the measurement of tools or workpieces directly on the machine
<b>TC3 CNC Channel Pack</b>	TF5230	further CNC channel, extension to a maximum of 12 channels, channel synchronization, axis transfer between channels
<b>TC3 CNC Transformation</b>	TF5240	transformation functionality (5-axis functionality)
<b>TC3 CNC Kinematic Optimization</b>	TF5245	optional CNC package that optimizes the determination of kinematic parameters for rotary axes in 5-axis kinematics
<b>TC3 CNC HSC Pack</b>	TF5250	extending the CNC with HSC technology (high-speed cutting)
<b>TC3 CNC Spline Interpolation</b>	TF5260	path programming via splines with programmable spline type, Akima-spline, B-spline
<b>TC3 CNC Virtual NCK Basis</b>	TF5270	virtual TwinCAT CNC for simulation in a Windows environment
<b>TC3 CNC Virtual NCK Options</b>	TF5271	virtual TwinCAT CNC for simulation in a Windows environment
<b>TC3 CNC Volumetric Compensation</b>	TF5280	extension for compensating geometric machine errors based on an ISO-standardized parametric model
<b>TC3 CNC Cutting Plus</b>	TF5290	technology package for extending the CNC functionality for cutting operations
<b>TC3 Motion Collision Avoidance</b>	TF5410	collision avoidance and controlled accumulation when operating a number of linearly and/or translationally dependent axes with TC3 NC PTP
<b>TC3 Motion Pick-and-Place</b>	TF5420	for handling tasks carried out by gantry robots and other kinematics
<b>TC3 Planar Motion</b>	TF5430	enables efficient and intelligent implementation of individual XPlanar applications
<b>TC3 Hydraulic Positioning</b>	TF5810	algorithms for control and positioning of hydraulic axes
<b>TC3 XTS Extension</b>	TF5850	integration of the XTS transport system into TwinCAT 3
<b>TC3 XPlanar</b>	TF5890	calculation of the mover position, precise position control, as well as monitoring and diagnostics

## TF6xxx | TwinCAT 3, Functions, Connectivity

<b>TC3 ADS Monitor</b>	TF6010	recording and diagnostics functions for the communication of TwinCAT systems
<b>TC3 JSON Data Interface</b>	TF6020	interface for the exchange of data in JSON format between the TwinCAT system and custom applications
<b>TC3 OPC UA</b>	TF6100	access to TwinCAT in accordance with OPC UA with UA server (DA/HA/AC) and UA client (DA)
<b>TC3 EtherCAT Redundancy 250</b>	TF6220	extension of the TwinCAT EtherCAT master with cable redundancy capability for up to 250 slaves
<b>TC3 EtherCAT Redundancy 250+</b>	TF6221	extension of the TwinCAT EtherCAT master with cable redundancy capability for more than 250 slaves
<b>TC3 EtherCAT External Sync</b>	TF6225	extension of the TwinCAT EtherCAT master with an option to synchronize the Beckhoff real-time communication with external signals
<b>TC3 Modbus TCP</b>	TF6250	communication with Modbus TCP devices (server and client functionality)
<b>TC3 Modbus RTU</b>	TF6255	serial communication with Modbus end devices
<b>TC3 PROFINET RT Device</b>	TF6270	communication via PROFINET (PROFINET slave)
<b>TC3 PROFINET RT Controller</b>	TF6271	communication via PROFINET (PROFINET master)
<b>TC3 EtherNet/IP Adapter</b>	TF6280	communication via EtherNet/IP (EtherNet/IP adapter)
<b>TC3 EtherNet/IP Scanner</b>	TF6281	communication via EtherNet/IP (EtherNet/IP scanner)



## TF6xxx | TwinCAT 3, Functions, Connectivity

TC3 FTP Client	TF6300	easy access from TwinCAT PLC to FTP server
TC3 TCP/IP	TF6310	communication via generic TCP/IP server
TC3 TCP/UDP Realtime	TF6311	direct access from real-time to Ethernet communication
TC3 Serial Communication	TF6340	communication via serial Bus Terminals or PC COM ports with the 3964R and RK512 protocol
TC3 SMS/SMTP	TF6350	sending SMS and e-mails from the PLC
TC3 Virtual Serial COM	TF6360	virtual serial COM driver for Windows platforms
TC3 Database Server	TF6420	accessing databases from the PLC
TC3 XML Server	TF6421	read and write access to XML files from the PLC
TC3 IEC 60870-5-10x	TF6500	communication according to IEC 60870-101, -102, -103, -104
TC3 IEC 61850/IEC 61400-25	TF6510	communication according to IEC 61850 and IEC 61400-25 <a href="#">i</a>
TC3 RFID Reader Communication	TF6600	connection of RFID readers to the TwinCAT PLC
TC3 S7 Communication	TF6620	enables TCP/IP based communication with variables of a Siemens S7 controller <a href="#">i</a>
TC3 DBC File Import for CAN	TF6650	reading of DBC file formats <a href="#">i</a>
TC3 IoT Communication (MQTT)	TF6701	provides basic publisher/subscriber-based data connectivity via MQTT
TC3 IoT Functions	TF6710	provides connectivity for cloud-based communication services
TC3 IoT Data Agent	TF6720	gateway application for data connectivity between TwinCAT runtime and IoT services
TC3 IoT Data Agent Packs	TF672x	extension of the TC3 IoT Data Agent for up to 256 additional ADS target runtimes or OPC UA namespaces
TC3 IoT Communicator	TF6730	sends process data and push notifications from TwinCAT to smartphones and tablets through a messaging service
TC3 IoT Communicator App	TF6735	smartphone and tablet app to receive and visualize live data and push notifications sent from TwinCAT
TC3 IoT HTTPS/REST	TF6760	basic functions for HTTP/HTTPS communication in the form of a PLC library providing the ability to address REST APIs as a client

## TF7xxx | TwinCAT 3, Functions, Vision

TC3 GigE Vision Connector	TF700x	interface for the configuration and integration of GigE Vision cameras directly into TwinCAT
TC3 Vision Base	TF7100	extensive PLC library with a large number of widely varying functions and algorithms for solving image processing tasks
TC3 Vision Matching 2D	TF7200	extension to find and compare objects based on learned references, contours, feature points or other properties
TC3 Vision Code Reading	TF7250	functions for reading various 1D and 2D codes
TC3 Vision Metrology 2D	TF7300	detection of edges, holes and circular arcs as well as the determination of lengths, distances, diameters, angles and coordinates, all with sub-pixel accuracy

## TF8xxx | TwinCAT 3, Functions, Industry specific

TC3 HVAC	TF8000	library covering all technical systems in building automation
TC3 Building Automation Basic	TF8010	license for the use of a PLC library for execution of basic functions in the field of room automation
TC3 BACnet	TF8020	communication with data networks of building automation and building control systems
TC3 Building Automation	TF8040	software package covering all technical building automation services
TC3 Lighting Solution	TF8050	software package for simple commissioning of DALI lighting controllers
TC3 Wind Framework	TF8310	framework for the development of operational management software for wind turbines
TC3 AES70 (OCA)	TF8810	communication library for the operation of a system as an OCA (Open Control Architecture) controller or OCA device in an OCA network

# TwinCAT 2

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## TX1000 | TwinCAT 2, TwinCAT CP

PC hardware	standard PC/IPC hardware, no extras
Operating systems	Windows 7/10, Windows Embedded WES2009/WES7*
Real-time	Beckhoff real-time kernel

Windows driver for Beckhoff Control Panel

## TX1100 | TwinCAT 2, TwinCAT I/O

PC hardware	standard PC/IPC hardware, no extras
Operating systems	Windows 7/10, Windows CE*
Real-time	Beckhoff real-time kernel

Multi-purpose I/O interface for all common fieldbus systems, PC Fieldbus Cards and interfaces with integrated real-time driver

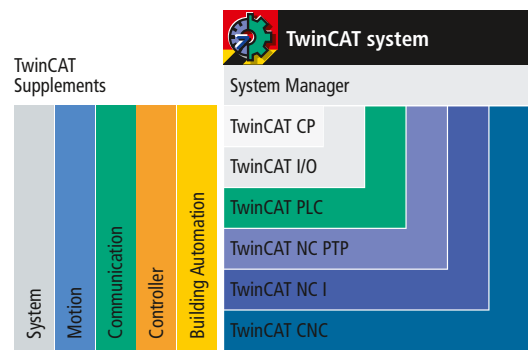
## TX1200 | TwinCAT 2, TwinCAT PLC

PC hardware	standard PC/IPC hardware, no extras
Operating systems	Windows 7/10, Windows CE*
Real-time	Beckhoff real-time kernel
I/O system	EtherCAT, Lightbus, PROFIBUS DP/MC, Interbus, CANopen, DeviceNet, SERCOS, Ethernet
Runtime system	4 multi-tasking PLCs each with 4 tasks in each PLC runtime system, development and runtime systems on one PC or separately (CE: only runtime)
Memory	process image size, flags area, program size, POU size, number of variables only limited by the size of the user memory (max. 2 GB with NT/2000/XP/Vista)
Cycle time	adjustable from 50 µs
Link time	1 µs (Intel® Core™ 2 Duo)
Programming	IEC 61131-3: IL, FBD, LD, SFC, ST, CFC, powerful library management

## TX1250 | TwinCAT 2, TwinCAT NC PTP

TwinCAT PLC	inclusive
PC hardware	standard PC/IPC hardware, no extras
Operating systems	Windows 7/10, Windows CE*
Real-time	Beckhoff real-time kernel
I/O system	EtherCAT, Lightbus, PROFIBUS DP/MC, Interbus, CANopen, DeviceNet, SERCOS, Ethernet
Programming	performed using function blocks for TwinCAT PLC according to IEC 61131-3 (standardized PLCopen Motion Control libraries), convenient axis commissioning menus in the System Manager
Runtime system	NC point-to-point including TwinCAT PLC
Number of axes	up to 255
Axis types	electrical and hydraulic servo drives, frequency converter drives, stepper motor drives, switched drives (fast/crawl axes)
Cycle time	50 µs upwards, typically 1 ms (selectable)
Axis functions	standard axis functions: start/stop/reset/reference, velocity override, special functions: master/slave cascading, cam plates, electronic gearings, online distance compensation of segments, flying saw

\*Version-dependent/older operating system versions are available on request from our service department.



## TX1260 | TwinCAT 2, TwinCAT NC I

<b>TwinCAT PLC</b>	inclusive
<b>TwinCAT NC PTP</b>	inclusive
<b>PC hardware</b>	standard PC/IPC hardware, no extras
<b>Operating systems</b>	Windows 7/10, Windows CE*
<b>Real-time</b>	Beckhoff real-time kernel
<b>I/O system</b>	EtherCAT, Lightbus, PROFIBUS DP/MC, Interbus, CANopen, DeviceNet, SERCOS, Ethernet
<b>Programming</b>	DIN 66025 programs for NC interpolation, access via function blocks from TwinCAT PLC according to IEC 61131-3
<b>Runtime system</b>	NC interpolation, including TwinCAT NC PTP and PLC
<b>Number of axes</b>	max. 3 axes and up to 5 auxiliary axes per group, 1 group per channel, max. 31 channels
<b>Axis types</b>	electrical servo axes, stepper motor drives
<b>Interpreter functions</b>	subroutines and jumps, programmable loops, zershifts, tool compensations, M and H functions
<b>Geometries</b>	straight lines and circular paths in 3D space, circular paths in all main planes, helixes with base circles in all main planes linear, circular, helical interpolation in the main lanes and freely definable planes, Bezier splines, look-ahead function
<b>Axis functions</b>	online reconfiguration of axes in groups, path override, slave coupling to path axes, auxiliary axes, axis error and sag compensation, measuring functions
<b>Operation</b>	automatic operation, manual operation (jog/inching), single block operation, referencing, handwheel operation (motion/superposition)
<b>Options</b>	<b>TS511x</b> TwinCAT Kinematic Transformation

## TX1270 | TwinCAT 2, TwinCAT CNC

<b>TwinCAT PLC</b>	inclusive						
<b>TwinCAT NC PTP</b>	inclusive						
<b>TwinCAT NC I</b>	inclusive						
<b>PC hardware</b>	standard PC/IPC hardware, no extras						
<b>Operating systems</b>	Windows 7/10*						
<b>Real-time</b>	Beckhoff real-time kernel						
<b>I/O system</b>	EtherCAT, Lightbus, PROFIBUS DP/MC, CANopen, DeviceNet, SERCOS, Ethernet						
<b>Programming</b>	DIN 66025 programming language with high-level language extensions, access via function blocks from TwinCAT PLC according to IEC 61131-3						
<b>Runtime system</b>	CNC, including TwinCAT NC I, NC PTP, PLC						
<b>Axes/spindles</b>	8 path axes/controlled spindles, max. of 64 axes/controlled spindles (optional), max. 12 channels (optional)						
<b>Axis types</b>	electrical servo-axes, analog/encoder interface via fieldbus, digital interface via fieldbus						
<b>Interpreter functions</b>	subroutines and jumps, programmable loops, zero shifts, tool compensations, M and H functions, mathematical functions, programming of parameters/variables, user macros, spindle and help functions, tool functions						
<b>Geometries</b>	linear, circular, helical interpolation in the main planes and freely definable planes, max. 32 interpolating path axes per channel, look-ahead function						
<b>Axis functions</b>	coupling and gantry axis function, override, axis error and sag compensation, measuring functions						
<b>Operation</b>	automatic operation, manual operation (jog/inching), single block operation, referencing, block search, handwheel operation (motion/superposition)						
<b>Options</b>	<table border="0"> <tr> <td><b>TS5220</b> TwinCAT CNC Axes Pack</td> <td><b>TS5250</b> TwinCAT CNC HSC Pack</td> </tr> <tr> <td><b>TS5230</b> TwinCAT CNC Channel Pack</td> <td><b>TS5260</b> TwinCAT CNC Spline Interpolation</td> </tr> <tr> <td><b>TS5240</b> TwinCAT CNC Transformation</td> <td></td> </tr> </table>	<b>TS5220</b> TwinCAT CNC Axes Pack	<b>TS5250</b> TwinCAT CNC HSC Pack	<b>TS5230</b> TwinCAT CNC Channel Pack	<b>TS5260</b> TwinCAT CNC Spline Interpolation	<b>TS5240</b> TwinCAT CNC Transformation	
<b>TS5220</b> TwinCAT CNC Axes Pack	<b>TS5250</b> TwinCAT CNC HSC Pack						
<b>TS5230</b> TwinCAT CNC Channel Pack	<b>TS5260</b> TwinCAT CNC Spline Interpolation						
<b>TS5240</b> TwinCAT CNC Transformation							

## TSxxxx | TwinCAT 2, Supplements, System

<b>TwinCAT Simulation Manager</b>	TS1110	simplified preparation and configuration of a simulation environment
<b>TwinCAT ECAD Import</b>	TS1120	importing engineering results from an ECAD program
<b>TwinCAT Management Server</b>	TS1140	central administration of Beckhoff CE control systems
<b>TwinCAT Backup</b>	TS1150	backing up and restoring files, operating system and TwinCAT settings
<b>TwinCAT Engineering Interface Server</b>	TS1600	co-ordinating programming tasks via a central source code management system
<b>TwinCAT PLC HMI</b>	TS1800	displaying visualizations created in PLC Control
<b>TwinCAT PLC HMI Web</b>	TS1810	displaying visualizations created in PLC Control in a web browser
<b>TwinCAT Scope 2</b>	TS3300	graphical analysis tool for displaying time-continuous signals
<b>TwinCAT Solar Position Algorithm</b>	TS3900	precise calculation of the sun's position
<b>TwinCAT EtherCAT Redundancy</b>	TS622x	extension of the TwinCAT EtherCAT master with cable redundancy capability
<b>TwinCAT Database Server</b>	TS6420	accessing databases from the PLC
<b>TwinCAT XML Data Server</b>	TS6421	reading and writing of XML-based data by the PLC

## TS4xxx | TwinCAT 2, Supplements, Controller

<b>TwinCAT PLC Controller Toolbox</b>	TS4100	modules for basic controllers (P, I, D), complex controllers (PI, PID), pulse width modulation, ramps, signal generators and filters
<b>TwinCAT PLC Temperature Controller</b>	TS4110	instanced temperature control function block for monitoring and controlling different temperature ranges

## TSxxxx | TwinCAT 2, Supplements, Motion

<b>TwinCAT Valve Diagram Editor</b>	TS1500	graphical tool for designing the characteristic curve of a hydraulic valve
<b>TwinCAT Cam Design Tool</b>	TS1510	graphic design tool for electronic cam plates
<b>TwinCAT NC Camming</b>	TS5050	providing the cam plate functionality (table coupling) of TwinCAT NC
<b>TwinCAT NC Flying Saw</b>	TS5055	providing flying saw functionality
<b>TwinCAT NC FIFO Axes</b>	TS5060	providing a FIFO interface for setpoint generation of an NC axis group
<b>TwinCAT PLC Motion Control XFC</b>	TS5065	high-precision logging and switching of digital signals in relation to axis positions
<b>TwinCAT Kinematic Transformation</b>	TS511x	implementation of different kinematic transformations for TwinCAT PTP or TwinCAT NC I
<b>TwinCAT Digital Cam Server</b>	TS5800	software implementation of fast cam controller
<b>TwinCAT PLC Hydraulic Positioning</b>	TS5810	control and adjustment of hydraulic axes

## TS6xxx | TwinCAT 2, Supplements, Communication

TwinCAT OPC UA Server	TS6100	access to TwinCAT in accordance with OPC UA with UA server (DA/HA/AC) and UA client (DA)
TwinCAT Modbus TCP Server	TS6250	communication with Modbus TCP devices (server and client functionality)
TwinCAT PLC Modbus RTU	TS6255	serial communication with Modbus end devices
TwinCAT PROFINET RT Device	TS6270	TwinCAT PROFINET RT device turns every PC-based controller into a PROFINET RT device.
TwinCAT PROFINET RT Controller	TS6271	TwinCAT PROFINET RT controller turns every PC-based controller into a PROFINET RT controller.
TwinCAT EtherNet/IP Adapter	TS6280	TwinCAT EtherNet/IP Adapter turns every PC-based controller into an EtherNet/IP adapter.
TwinCAT FTP Client	TS6300	basic access from TwinCAT PLC to FTP server
TwinCAT TCP/IP Server	TS6310	communication via generic TCP servers
TwinCAT PLC Serial Communication	TS6340	communication via serial Bus Terminals or PC COM ports
TwinCAT PLC Serial Communication 3964R/RK512	TS6341	communication via serial Bus Terminals or PC COM ports with the 3964R and RK512 protocol
TwinCAT SMS/SMTP Server	TS6350	sending SMS and e-mails from the PLC
TwinCAT Virtual Serial COM Driver	TS6360	virtual serial COM driver for Windows and Windows CE platforms
TwinCAT DriveCOM OPC Server	TS6370	fieldbus-independent communication connections between the engineering tool and the drive
TwinCAT DriveTop Server	TS6371	configuring Indramat SERCOS drives with DriveTop software on TwinCAT systems
TwinCAT PLC IEC 60870-5-101, -102, -103, -104 Master	TS650x	implementation of IEC 60870-101, -102, -103 and -104 masters
TwinCAT PLC IEC 60870-5-101, -104 Slave	TS650x	implementation of IEC 60870-101 and -104 slaves
TwinCAT PLC IEC 61400-25 Server	TS6509	IEC 61400-25 communication
TwinCAT PLC IEC 61850 Server	TS6511	IEC 61850 communication
TwinCAT PLC RFID Reader Communication	TS6600	connection of RFID readers to the TwinCAT PLC

## TS8xxx | TwinCAT 2, Supplements, Building Automation

TwinCAT PLC HVAC	TS8000	automation of HVAC and sanitary installations
TwinCAT PLC Building Automation Basic	TS8010	executing basic room automation functions
TwinCAT BACnet/IP	TS8020	communication with the data networks of the building automation and building control systems
TwinCAT FIAS Server	TS8035	communication between TwinCAT PLC and a system using the FIAS standard
TwinCAT Crestron Server	TS8036	communication between a TwinCAT PLC and a Crestron controller
TwinCAT Building Automation	TS8040	software package covering all technical building automation services
TwinCAT Building Automation Framework	TS8100	configuration and commissioning of building automation projects

# TwinSAFE

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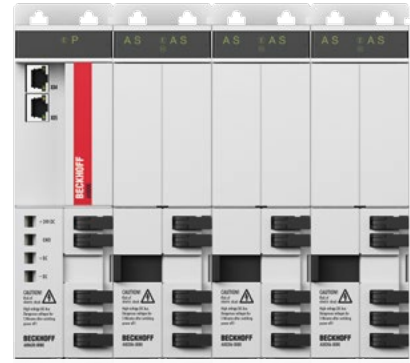


EK1960



EJ1914

TwinSAFE hardware, I/O						
	Input	Dedicated Logic	Output	Input and Logic	Logic and Output	Input, Logic and Output
<b>EtherCAT Terminals</b>	<b>EK1914</b> 4 standard inputs, 4 standard outputs, 2 safe inputs, 2 safe outputs	<b>EL6900</b> TwinSAFE Logic	<b>EK1914</b> 4 standard inputs, 4 standard outputs, 2 safe inputs, 2 safe outputs	<b>EL1918</b> TwinSAFE Logic, 8 safe inputs	<b>EL2912</b> TwinSAFE Logic, 2 safe outputs	<b>EK1960</b> TwinSAFE Logic, 20 safe inputs, 24 safe outputs
	<b>EL1904</b> TwinSAFE, 4 safe inputs	<b>EL6910</b> TwinSAFE Logic, PROFIsafe master and slave support	<b>EL2904</b> TwinSAFE, 4 safe outputs			<b>EL2911</b> TwinSAFE Logic, 4 safe inputs, 1 safe output
		<b>EL6930</b> TwinSAFE Logic, PROFIsafe slave support				
<b>EtherCAT Box</b>	<b>EP1908-0002</b> TwinSAFE, 8 safe inputs			<b>EP1918-0002</b> TwinSAFE Logic, 8 safe inputs	<b>EP2918-0032</b> TwinSAFE Logic, 8 safe outputs	<b>EP1957-0022</b> TwinSAFE Logic, 8 safe inputs, 4 safe outputs
<b>EtherCAT Plug-in Modules</b>		<b>EJ6910</b> TwinSAFE Logic		<b>EJ1914</b> TwinSAFE Logic, 4 safe inputs	<b>EJ2914</b> TwinSAFE Logic, 4 safe outputs	<b>EJ1957</b> TwinSAFE Logic, 8 safe inputs, 4 safe outputs
				<b>EJ1918</b> TwinSAFE Logic, 8 safe inputs	<b>EJ2918</b> TwinSAFE Logic, 8 safe outputs	
<b>Bus Terminals</b>	<b>KL1904</b> TwinSAFE, 4 safe inputs		<b>KL2904</b> TwinSAFE, 4 safe outputs		<b>KL6904</b> TwinSAFE Logic, 4 safe outputs	



AX8000

## TwinSAFE hardware, Drive Technology

	Output	Input, Logic and Output				
<b>AX5000, TwinSAFE drive option card for AX5000 servo drive</b>	<b>AX5801</b> drive-integrated safety functions: STO, SS1					
	<b>AX5805</b> drive-integrated safety functions: Safe Motion, for AX5x01 to AX5140	<b>AX5806</b> drive-integrated safety functions: Safe Motion, for AX5160 to AX5193				
<b>AX8000, multi-axis servo drives</b>		<b>AX8108</b> single-axis module 8 A, feedback: OCT, multi- feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AX8118</b> single-axis module 18 A, feedback: OCT, multi- feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AX8206</b> dual-axis module 2 x 6 A, feedback: OCT, multi- feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion		
		<b>AX8525</b> ⓘ combined power supply and axis module 25 A, feedback: OCT, multi- feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AX8540</b> ⓘ combined power supply and axis module 40 A, feedback: OCT, multi- feedback interface, TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion			
<b>AMP8000, distributed servo drive</b>		<b>AMP8041</b> ⓘ $M_0 = 2.40 \dots 2.50 \text{ Nm}$ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AMP8042</b> ⓘ $M_0 = 4.10 \text{ Nm}$ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AMP8043</b> ⓘ $M_0 = 5.70 \text{ Nm}$ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion		
		<b>AMP8051</b> ⓘ $M_0 = 4.00 \dots 4.90 \text{ Nm}$ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AMP8052</b> ⓘ $M_0 = 7.80 \dots 8.20 \text{ Nm}$ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AMP8053</b> ⓘ $M_0 = 9.10 \dots 11.00 \text{ Nm}$ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	<b>AMP8054</b> ⓘ $M_0 = 14.0 \text{ Nm}$ , TwinSAFE Logic, TwinSAFE: STO/SS1, Safe Motion	

## TwinSAFE software

<b>TC3 Safety Editor</b>	<b>TE9000</b>	implementing of safety applications in graphical environment
<b>TwinSAFE Loader/User</b>	<b>TE9200</b>	TwinSAFE command line tools: Loader for downloading/customizing safety projects at runtime; User for handling user management of TwinSAFE logic components
<b>TwinSAFE Logic Simulator</b>	<b>TE9100</b>	virtual commissioning of a safety application based on the TwinCAT 3 Safety Editor



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