## Product Registration

Thank you for purchasing YOKOGAWA products.

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http://www.yokogawa.com/ns/reg/

## Introduction

Thank you for purchasing the UT32A digital indicating controller (Entry model) (hereinafter referred to as UT32A).
This manual describes how to use UT32A functions other than UT32A's communication function. Please read through this user's manual carefully before using the product. Note that the manuals for the UT32A comprise the following seven documents:

- Printed manual

| Manual Name | Manual Number | Description |
| :--- | :--- | :--- |
| UT32A Operation Guide «Entry <br> Model» | IM 05P01F31-11EN | This manual describes the basic <br> operation method. |
| Precautions on the Use of the <br> UTAdvanced Series | IM 05P01A01-11EN | This manual is always delivered even if <br> 'without manuals' was selected. |

- Electronic manuals

| Manual Name | Manual Number | Description |
| :--- | :--- | :--- |
| UT32A Operation Guide «Entry <br> Model» | IM 05P01F31-11EN | This manual describes the basic <br> operation method. |
| Precautions on the Use of the <br> UTAdvanced Series | IM 05P01A01-11EN | This manual is always delivered even if <br> 'without manuals' was selected. |
| UT32A User's Manual «Entry <br> Model» | IM 05P01F31-01EN | This manual. It describes the usage of <br> all functions except the communication <br> functions. |
| UTAdvanced Series <br> Communication Interface <br> (RS-485, Ethernet) <br> User's Manual | IM 05P07A01-01EN | This manual describes how to <br> use UT32A in Ethernet and serial <br> communications. For communication <br> wiring, see the Operation Guide or <br> User's Manual. |
| LL50A Parameter Setting <br> Software Installation Manual | IM 05P05A01-01EN | This manual describes how to install and <br> uninstall the LL50A. |
| LL50A Parameter Setting <br> Software User's Manual | IM 05P05A01-02EN | This manual describes how to use the <br> LL50A, ladder sequence function, peer- <br> to-peer communication, and network <br> profile creating function. |

* User's Manual can be downloaded from a website.

For details of the each function, refer to the electronic manual. User's manuals can be downloaded or viewed at the following URL.

## http://www.yokogawa.com/ns/ut/im/

- General specifications

| Title | General specifications No. |
| :--- | :--- |
| UT32A Digital Indicating Controller «Entry Model» | GS 05P01F31-01EN |
| LL50A Parameter Setting Software | GS 05P05A01-01EN |

* The last two characters of the manual number and general specification number indicate the language in which the manual is written.
- Authorised Representative in the EEA

Authorised Representative in the EEA
Yokogawa Europe BV. (Address: Euroweg 2, 3825 HD Amersfoort, The Netherlands) is the Authorised Representative of Yokogawa Electric Corporation for this Product in the EEA.

## Target Readers

This guide is intended for the following personnel;

- Engineers responsible for installation, wiring, and maintenance of the equipment.
- Personnel responsible for normal daily operation of the equipment.


## Notice

## Trademarks

- The contents of this manual are subject to change without notice as a result of continuing improvements to the instrument's performance and functions.
- Every effort has been made to ensure accuracy in the preparation of this manual. Should any errors or omissions come to your attention, however, please inform Yokogawa Electric's sales office or sales representative.
- Under no circumstances may the contents of this manual, in part or in whole, be transcribed or copied without our permission.
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- We do not use the TM or ® mark to indicate these trademarks or registered trademarks in this user's manual.
- All other product names mentioned in this user's manual are trademarks or registered trademarks of their respective companies.


## Safety Precautions

This instrument is a product of Installation Category II of IEC/EN/CSA/UL61010-1, IEC/ EN61010-2-201, IEC/EN61010-2-030 Safety Standards and Class A of EN61326-1, EN55011 (EMC Standards).


## CAUTION

This instrument is an EMC class A product. In a domestic environment, this product may cause radio interference in which case the user needs to take adequate measures.

The instrument is a product rated Measurement Category O (other).

* Measurement Category O (other)

This category applies to electric equipment that measures a circuit connected to a low-voltage facility and receives power from stationary equipment such as electric switchboards.
To use the instrument properly and safely, observe the safety precautions described in this user's manual when operating it. Use of the instrument in a manner not prescribed herein may compromise protection features inherent in the device. We assume no liability for or warranty on a fault caused by users' failure to observe these instructions. This instrument is designed to be used within the scope of Measurement Category O (other) and is dedicated for indoor use.

## Notes on the User's Manual

- This user's manual should be readily accessible to the end users so it can be referred to easily. It should be kept in a safe place.
- Read the information contained in this manual thoroughly before operating the product.
- The purpose of this user's manual is not to warrant that the product is well suited to any particular purpose, but rather to describe the functional details of the product.


## Safety, Protection, and Modification of the Product

The following symbols are used in the product and user's manuals to indicate safety precautions:


[^0]

- In order to protect the system controlled by this product and the product itself, and to ensure safe operation, observe the safety precautions described in this user's manual. Use of the instrument in a manner not prescribed herein may compromise the product's functions and the protection features inherent in the device. We assume no liability for safety, or responsibility for the product's quality, performance or functionality should users fail to observe these instructions when operating the product.
- Installation of protection and/or safety circuits with respect to a lightning protector; protective equipment for the system controlled by the product and the product itself; foolproof or failsafe design of a process or line using the system controlled by the product or the product itself; and/or the design and installation of other protective and safety circuits are to be appropriately implemented as the customer deems necessary.
- Be sure to use the spare parts approved by YOKOGAWA when replacing parts or consumables.
- This product is not designed or manufactured to be used in critical applications that directly affect or threaten human lives. Such applications include nuclear power equipment, devices using radioactivity, railway facilities, aviation equipment, air navigation facilities, aviation facilities, and medical equipment. If so used, it is the user's responsibility to include in the system additional equipment and devices that ensure personnel safety.
- Modification of the product is strictly prohibited.
- This product is intended to be handled by skilled/trained personnel for electric devices.
- This product is UL Recognized Component. In order to comply with UL standards, end-products are necessary to be designed by those who have knowledge of the requirements.


## WARNING

- Power Supply

Ensure that the instrument's supply voltage matches the voltage of the power supply before turning ON the power.

- Do Not Use in an Explosive Atmosphere

Do not operate the instrument in locations with combustible or explosive gases or steam. Operation in such environments constitutes an extreme safety hazard. Use of the instrument in environments with high concentrations of corrosive gas ( $\mathrm{H}_{2} \mathrm{~S}, \mathrm{SO}_{x}$, etc.) for extended periods of time may cause a failure.

- Do Not Remove Internal Unit

The internal unit should not be removed by anyone other than YOKOGAWA's service personnel. There are dangerous high voltage parts inside. Additionally, do not replace the fuse by yourself.

- Damage to the Protective Construction

Operation of the instrument in a manner not specified in this user's manual may damage its protective construction.

## Warning and Disclaimer

- YOKOGAWA makes no warranties regarding the product except those stated in the WARRANTY that is provided separately.
- The product is provided on an "as is" basis. YOKOGAWA assumes no liability to any person or entity for any loss or damage, direct or indirect, arising from the use of the product or from any unpredictable defect of the product.


## Notes on Software

- YOKOGAWA makes no warranties, either expressed or implied, with respect to the software's merchantability or suitability for any particular purpose, except as specified in the terms of the separately provided warranty.
- This software may be used on one specific machine only.
- To use the software on another machine, the software must be purchased again separately.
- It is strictly prohibited to reproduce the product except for backup purposes.
- Store the software CD-ROM (the original medium) in a safe place.
- All reverse-engineering operations, such as reverse compilation or the reverse assembly of the product are strictly prohibited.
- No part of the product's software may be transferred, converted, or sublet for use by any third party, without prior written consent from YOKOGAWA.


## Handling Precautions for the Main Unit

- The instrument comprises many plastic components. To clean it, wipe it with a soft, dry cloth. Do not use organic solvents such as benzene or thinner for cleaning, as discoloration or deformation may result.
- Keep electrically charged objects away from the signal terminals. Not doing so may cause the instrument to fail.
- Do not apply volatile chemicals to the display area, operation keys, etc. Do not leave the instrument in contact with rubber or PVC products for extended periods. Doing so may result in failure.
- If the equipment emits smoke or abnormal smells or makes unusual noises, turn OFF the instrument's power immediately and unplug the device. In such an event, contact your sales representative.


## Checking the Contents of the Package

Unpack the box and check the contents before using the product. If the product is different from that which you have ordered, if any parts or accessories are missing, or if the product appears to be damaged, contact your sales representative.

## UT32A Main Unit

The UT32A main units have nameplates affixed to the side of the case.
Check the model and suffix codes inscribed on the nameplate to confirm that the product received is that which was ordered.

## No. (Instrument number)

When contacting your sales representative, inform them of this number, too.

## Model and Suffix Codes of UT32A (for Entry Model)


*1: When the /LP option is specified, the RS-485 communication of the Type 2 code "1" is 2-wire system.
*2: English, German, French, and Spanish are available for the guide display.
*3: When the /CT option is specified, the UT32A does not conform to the safety standards (UL and CSA) and CE marking (Products with /CT option are not intended for EEA-market).

## Coating Treatment

(1)HumiSeal coating treatment

Apply HumiSeal coating to the printed circuit board assembly.
Do not apply HumiSeal coating to the following parts: connector, gold-plated contact area, relay part, RJC device, and in the vicinity of the push switch/LED lamp.
(2)Apply terminal coating to the gold-plated contact area on the printed circuit board.

## Notes

- There are two treatments as described above, but we do not guarantee their effectiveness.
We do not supply any test data on these treatments.
- Do not apply any treatment to the screw terminal area on the back side of the instrument.


## Accessories

The product is provided with the following accessories according to the model and suffix codes. Check that none of them are missing or damaged.


| No. | Product Name | Quantity | Remark |
| :---: | :--- | :---: | :--- |
| 1 | Brackets | 2 | Part number: L4502TP (For fixing the upper <br> and lower parts) |
| 2 | Unit label | 1 | Part number: L4502VZ |
| 3 | Tag label | 1 | Part number: L4502VE (Only when ordered.) |
| 4 | Operation Guide | 1 | A3 size, $\times 6$ (Standard model only) |

How to use the unit label

- Affixing the unit label

Affix the unit label to the front panel. If necessary, combine with unit prefixes. Affix it so that the LCD area is not blocked.

- Affixing the unit label to the UT32A

Affix the unit label over the letters "PV" on the front panel.

- Maintenance port seals

Maintenance port seals (two spares) are available. Use them if the seal affixed to the UTAdvanced controller loses its adhesiveness.

- TAG No. labels

TAG No. labels (two pieces) are available. Use them if necessary.

## Accessory (sold separately)

The following lists an accessory sold separately.

- LL50A Parameter Setting Software

| Model | Suffix code | Description |
| :---: | :--- | :--- |
| LL50A | -00 | Parameter Setting Software |

- Terminal cover

Model: UTAP002

- Resistance Module

| Model | Suffix code | Description |
| :--- | :--- | :--- |
| X010 | See the General Specifications (*) | Resistance Module |



For UT32A

- Brackets

Part number L4502TP (2 pieces for fixing the upper and lower parts)

- User's Manual (A4 size)
* User's Manual can be downloaded from a website


## Symbols Used in This Manual

## A

This symbol is used on the instrument. It indicates the possibility of injury to the user or damage to the instrument, and signifies that the user must refer to the user's manual for special instructions. The same symbol is used in the user's manual on pages that the user needs to refer to, together with the term "WARNING" or "CAUTION."

## WARNING

Calls attention to actions or conditions that could cause serious or fatal injury to the user, and indicates precautions that should be taken to prevent such occurrences.

## CAUTION

Calls attention to actions or conditions that could cause injury to the user or damage to the instrument or property and indicates precautions that should be taken to prevent such occurrences.

## Note

Identifies important information required to operate the instrument.

Indicates related operations or explanations for the user's reference.
[ ]
Indicates a character string displayed on the display.

## Setting Display

Indicates a setting display and describes the keystrokes required to display the relevant setting display.

## Setting Details

Provides the descriptions of settings.

Description
Describes restrictions etc. regarding a relevant operation.

How to Use This Manual
For the ladder sequence and communication functions, see the respective manuals. This user's manual is organized into Chapters 1 to 18 as shown below.

| Chapter | Title and Description |
| :---: | :---: |
| 1 | Introduction to Functions <br> Describes the main functions of the UT32A. |
| 2 | UT32A Operating Procedures <br> Describes the flow from unpacking to regular operations. |
| 3 | Part Names <br> Describes part names and functions on the front panel. |
| 4 | Basic Operation <br> Describes basic operation of the UT32A. |
| 5 | Quick Setting Function <br> Describes the minimum necessary settings for operation. |
| 6 | Monitoring and Control of Regular Operations <br> Describes monitoring displays of regular operations and operation. |
| 7 | Input (PV) Functions Describes PV input. |
| 8 | Control Functions <br> Describes basic control and advanced control. |
| 9 | Auxiliary Control Functions Describes auxiliary control functions |
| 10 | Control Output Functions Describes output functions. |
| 11 | Alarm Functions <br> Describes alarm output and status output. |
| 12 | Contact Output Functions Describes contact output functions. |
| 13 | Display, Key, and Security Functions <br> Describes display, user function key and security functions. |
| 14 | Parameter Initialization <br> Describes the initialization to factory default values and to user default values. |
| 15 | Power Failure Recovery Processing/Power Frequency Setting/Other Settings Describes operations performed after momentary power interruption and power failures. |
| 16 | Troubleshooting, Maintenance, and Inspections <br> Describes troubleshooting, maintenance, periodic inspections, and disposal. |
| 17 | Installation and Wiring Describes installation and wiring. |
| 18 | Parameters <br> Provides parameter maps. |
| GS | Specifications <br> Provides the UT32A specifications. |

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Revision Information

The Quick setting function is a function to easily set the basic function of the controller.


Installation and Wiring


Setup



Operation

Q: What should I do to perform control immediately? First, I want to set the input and output.

A: Use the Quick setting function to perform the setup easily.
Quick setting function: Chapter 5

Q: How do I determine the PID?
A: Use Auto-tuning to perform the tuning easily.
Auto-tuning: Section 6.3

### 1.2 Input/Output Function

## PV Input (equipped as standard)

PV input is a universal input to arbitrarily set the type and range for the thermocouple (TC), resistance-temperature detector (RTD), and DC voltage/current.

- Chapter 7 Input (PV) Functions


Control Output (Depends on the model and suffix codes)
Output type depends on the model and suffix codes.

- Chapter 10 Control Output Functions



## Contact Output

2 contact outputs can be incorporated. Contact output can output events such as alarms.

## 24 V DC Loop Power Supply

24 V DC loop power supply can be supplied to 2-wire transmitter.

- 17.4.10 24 V DC Loop Power Supply Wiring



## PID Control

PID control is a general control using the PID control-related parameters.

- 8.2.1 PID Control



### 1.4 Display and Key Functions

Employing a 14 -segment, active color LCD greatly increases the monitoring and operating capabilities.

## Active Color PV Display (display color change)

The active color PV display function changes the PV display color (red or white) when abnormality occurs in PV etc.

- 13.1.1 Setting Active Color PV Display Function



## Guide Display

The guide is displayed on PV display when setting parameters. This guide can be turned on/off with the Fn key.

The scrolling guide is displayed when setting parameters.


## Multilingual Guide Display

English, German, French, or Spanish can be displayed in Guide display.

- 13.1.11 Switching Guide Display Language


## Parameter Display Level

To intended use of the operator, the display level of the parameter can be set.

- Chapter 18 Parameters


## User Function Keys

The UT32A has a user function key (Fn).
Assign a function to a user function key to use it as an exclusive key.

- 13.2 Assigning Function to User Function Key and A/M Key


### 1.5 Communication Functions

The UT32A can use RS-485 communication by specifying the suffix code and optional suffix code for each communication.

- UTAdvanced Series Communication Interface (RS-485, Ethernet) User's Manual


## RS-485 Communication (Modbus communication, PC link communication, and Ladder communication)

The UT32A can communicate with PCs, PLCs, touch panels, and other devices.


## Coordinated Operation

A system of coordinated operation is configured with a master controller and a number of slave controllers. The slave controllers are set to operate in the same way as the master controller. Therefore you do not have to create a communication program.


## Light-Ioader Communication

Use the LL50A to set parameters and create ladder programs. Attach the adapter to the front of the controller to communicate.

- Light-loader function: LL50A Parameter Setting Software User's Manual



## Maintenance Port Communication (Power supply is not required for the UT32A)

Maintenance port is used to connect with the dedicated cable when using LL50A Parameter Setting Software (sold separately). The parameters can be set without supplying power to the UT32A.


## CAUTION

When using the maintenance port, do not supply power to the controller. Otherwise, the controller does not work normally.
If power is supplied to the controller while the cable is connected, or the cable is connected to the controller already turned on, unplug the cable and turn on the controller again. The controller returns to the normal condition.

### 1.6 Definition of Main Symbols and Terms

## Main Symbol

PV: Measured input value
SP: Target setpoint
OUT: Control output value

A/M: AUTO/MAN
AUTO: Automatic
MAN: Manual
REMOTE, REM: Remote
LOCAL, LCL: Local

E1: Terminal areas

- 17.4 Wiring


## Engineering Units

Input range (scale): the PV range low limit is set to 0\%, and the high limit is set to $100 \%$ for conversion.
Input range (scale) span: the PV range span is set to $100 \%$ for conversion.
In this manual, the parameter setting range is described as the "input range" and "input range span." This means that engineering units are required to be set. Set a temperature for temperature input.

The following describes a conversion example.
When the PV input range is 100 to $600^{\circ} \mathrm{C}, 0 \%$ of the PV range is equivalent to $100^{\circ} \mathrm{C}$, $50 \%$ of the PV range is equivalent to $350^{\circ} \mathrm{C}$, and $100 \%$ of the PV range is equivalent to $600^{\circ} \mathrm{C}$.
$100 \%$ of the PV range span is equivalent to $500^{\circ} \mathrm{C}$.
$20 \%$ of the PV range span is equivalent to $100^{\circ} \mathrm{C}$.


The above applies to the scale for voltage and current input.

### 2.1 UT32A Operating Procedures



### 3.1 Names and Functions of Display Parts


$(2)+(3)+(4):$ Setpoint display

| No. in figure | Name | Description |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| (1) | PV display (white or red) | Displays PV. <br> Displays an error code if an error occurs. <br> Displays the scrolling guide in the Menu Display and Parameter Setting Display when the guide display ON/ OFF is set to ON. |  |  |  |
| (2) | Group display (green) | Displays a group number (1 to 4, or R) and terminal area (E1). <br> 1 to 4 represent SP numbers in the Operation Display. R and E1 to E4 are displayed in the Parameter Setting Display. |  |  |  |
| (3) | Symbol display (orange) | Displays a parameter symbol. |  |  |  |
| (4) | Data display (orange) | Displays a parameter setpoint and menu symbol. |  |  |  |
| (5) | Bar-graph display (orange) | Displays control output value (OUT) and measured input value (PV). <br> The data to be displayed can be set by the parameter. Initial value: deviation |  |  |  |
| (6) | Event indicator (orange) | Lit when the alarms 1 to 4 occur. Event displays other than alarms can be set by the parameter. |  |  |  |
| (7) | Key navigation indicator (green) | Lit or blinks when the Up/Down or Left/Right arrow key operation is possible. |  |  |  |
| (8) | Parameter display level indicator (green) | Displays the setting conditions of the parameter display level function. |  |  |  |
|  |  | Parameter display level |  | EASY | PRO |
|  |  | Easy setting mode |  | Lit | Unlit |
|  |  | Standard setting mode |  | Unlit | Unlit |
|  |  | Professional setting mode |  | Unlit | Lit |
| (9) | Status indicator (green and red) | Displays the operating conditions and control status. |  |  |  |
|  |  | Display | Description |  |  |
|  |  | REM | Lit when in remote mode (REM). |  |  |
|  |  | STOP | Lit when in stop mode (STOP). |  |  |
|  |  | MAN | Lit when in manual mode (MAN). Blinks during auto-tuning. |  |  |
| (10) | Security indicator (red) | Lit if a password is set. The setup parameter settings are locked. |  |  |  |

### 3.2 Names and Functions of Keys



| No. in figure | Name | Description |
| :---: | :---: | :---: |
| (1) | DISP key | Used to switch the Operation Displays. <br> Press the key in the Operation Display to switch the provided Operation Displays. <br> Press the key in the Menu Display or Parameter Setting Display to return to the Operation Display. |
| (2) | PARA key | Hold down the key for 3 seconds to move to the Operation Parameter Setting Display. <br> Hold down the key and the Left arrow key simultaneously for 3 seconds to move to the Setup Parameter Setting Display. <br> Press the key in the Parameter Setting Display to return to the Menu Display. Press the key once to cancel the parameter setting (setpoint is blinking). |
| (3) | SET/ENTER key Up/Down/ Left/Right arrow keys | SET/ENTER key <br> Press the key in the Menu Display to move to the Parameter Setting Display of the Menu. Press the key in the Parameter Setting Display to transfer to the parameter setting mode (setpoint is blinking), and the parameter can be changed. Press the key during parameter setting mode to register the setpoint. <br> Up/Down/Left/Right arrow keys <br> Press the Left/Right arrow keys in the Menu Display to switch the Displays. <br> Press the Up/Down/Left/Right arrow keys in the Parameter Setting Display to switch the Displays. <br> Press the Up/Down arrow keys during parameter setting mode (setpoint is blinking) to change a setpoint. <br> Press the Left/Right arrow keys during parameter setting mode (setpoint is blinking) to move between digits according to the parameter. |
| (4) | Light-loader interface | It is the communication interface to the adapter cable when setting and storing parameters via PC. The LL50A Parameter Setting Software (sold separately) is required. |
| (5) | A/M key | Used to switch between AUTO and MAN modes. The setting is switched between AUTO and MAN each time the key is pressed. The user can assign a function key. |
| (6) | User function keys | The UT32A has Fn key. The user can assign a function to the key. The function is set by the parameter. |

## Maintenance Port (Power supply is not required for the UT32A).

The maintenance port is used to connect with the dedicated cable when using LL50A Parameter Setting Software (sold separately). The parameters can be set without supplying power to the UT32A.


Maintenance port

UT32A

## CAUTION

When using the maintenance port, do not supply power to the controller. Otherwise, the controller does not work normally.
If power is supplied to the controller while the cable is connected, or the cable is connected to the controller already turned on, unplug the cable and turn on the controller again. The controller returns to the normal condition.

### 3.3 List of Display Symbols

The following shows the parameter symbols, menu symbols, alphanumeric of guide, and symbols which are displayed on the UT32A.

Figure (common to all display area)
$\begin{array}{llllllllll}0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ \square & 1 & \square & - & 4 & \square & \square & 7 & \square & \square\end{array}$
PV display (14 segments): Alphabet
$\begin{array}{llllll}A & B & C & D & E & F \\ \square & \pi & I & \pi & E & E\end{array}$

| $G$ | $H$ | $I$ | $J$ | $K$ | $L$ |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | $H$ | 1 | $L$ | $H$ | $L$ |


$\begin{array}{cccccc}S & T & U & V & W & X \\ \square & T & \| & \| & \| \prime & 11\end{array}$
$\begin{array}{ll}Y & Z \\ i & Z\end{array}$

Symbol display and Data display (11 segments): Alphabet
$\begin{array}{llllll}A & B & C & D & E & F \\ A & L & E & \square & E & F\end{array}$
C (lower-case)
E
$\begin{array}{cccccc}G & H & 1 & J & K & L \\ \Gamma & H & i & L & \Pi & L\end{array}$
$\begin{array}{cccccc}M & N & O & P & Q & R \\ M & M & \Pi & \square & \square & \square \\ M & \square & \square & \Pi\end{array}$


| $Y$ | $Z$ |
| :--- | :--- |
| 4 | 7 |
|  | 1 |

Group display (7 segments): Alphabet


$\begin{array}{cccccc}M & N & O & P & Q & R \\ M & \cap & \square & \text { O } & \square & \text { O }\end{array}$
$\begin{array}{cccccc}S & T & U & V & W & X \\ 5 & L & \text { il } & \text { if } & \text { II } & \text { None }\end{array}$
$\begin{array}{ll}Y & Z \\ & =\end{array}$
PV display (14 segments): Symbol
Space
-

### 3.4 Brief Description of Setting Details (Parameters)

This manual describes the Setting Details as follows in addition to the functional Description.

## Setting Details

(Display Example)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :--- | :--- | :--- |
| A1 to A4 | Alarm-1 to -4 <br> setpoint | EASY | Set a display value of setpoint of <br> PV alarm, SP alarm, deviation <br> alarm, output alarm, or velocity <br> alarm. <br> -19999 to 30000 (Set a value <br> within the input range.) <br> Decimal point position depends on <br> the input type | SP |

(1) Parameter symbol: Symbol displayed on Symbol display on the front panel.
(2) Name: Parameter name
(3) Display level: Indicates the parameter display level.
(4) Setting range: Parameter setting range
(5) Menu symbol: Indicates the menu to which the parameter belongs.

Ope: Operation parameter
Set : Setup parameter

## Parameter Display Level

|  | Display level | Description |
| :---: | :--- | :--- |
| EASY | Easy setting mode: The minimum <br> necessary parameters are displayed. | Corresponding parameters are displayed in <br> all modes. |
| STD | Standard setting mode: The wider <br> range of parameters than those <br> shown in Easy setting mode are <br> displayed. | in Standard setting mode and Professional <br> setting mode. <br> Parameter display level indicators "EASY" <br> and "PRO" are unlit in Standard setting <br> mode. <br> *: "STD" is the symbol used in this manual <br> only. |
| PRO | Professional setting mode: All <br> parameters are displayed. | Corresponding parameters are displayed only <br> in Professional setting mode. |

## Note

For more intelligible display operation of parameters and the references, see Chapter 18, "Parameter Map."

### 4.1 Overview of Display Switch and Operation Keys

The following shows the transition of Operation Display, Operation Parameter Setting Display, and Setup Parameter Setting Display.
The "Operation Parameter Setting Display" has the parameters for setting the functions necessary for the operation.
The "Setup Parameter Setting Display" has the parameters for setting the basic functions of the controller.
Power ON



The display pattern of the UT32A is as follows; the Menu Display and Parameter Setting Display.
For the Operation Display, see Chapter 6, "Monitoring and Control of Regular Operations."

| Display | Description |
| :---: | :---: |
| Menu Display | The Menu Display is segmented by the function and optional terminal position. The scrolling guide for the menu is displayed on PV display. The guide display can be turned on/off with the Fn key. <br> Menu Display of Operation Parameter <br> Menu Display of Setup Parameter |
| Parameter Setting Display | The following is the Display for displaying and setting a parameter. The parameters have three types of display levels; Easy setting mode, Standard setting mode, and Professional setting mode. The parameters to be displayed can be limited according to the setting of the parameter display level. The scrolling guide for the parameter is displayed on PV display. The guide display can be turned on/off with the Fn key. <br> Parameter Setting Display (Example of Operation Parameter Setting Display) <br> Group number or Terminal area is displayed. |

Display Shown at the End (the Lowest Level) of the Parameter Setting Display As shown in the figure below, the END Display is shown to indicate the end of the Menu Display and Parameter Setting Display. There are no setting items.

- The scrolling guide of END is displayed.



## Basic Key Operation Sequence

- To move to the Setup Parameter Setting Display

Hold down the PARA key and the Left arrow key simultaneously for 3 seconds.


- To move to the Operation Parameter Setting Display

Hold down the PARA key for 3 seconds.


Hold down the key
for 3 seconds.

- To move to the Operation Display

Press the DISP key once.


### 4.2 How to Set Parameters

The following operating procedure describes an example of setting alarm setpoint (A1).

## Operation

1. Hold down the PARA key for 3 seconds in the Operation Display to call up the [MODE] Menu Display.

2. 

Press the Right arrow key to display the [SP] Menu Display.

3. Press the SET/ENTER key to display the [SP] Parameter Setting Display.

4. Press the Down arrow key to display the [A1] Parameter Setting Display.

5. Press the SET/ENTER key to blink the setpoint.

6. Press the Up or Down arrow key to change the setpoint.
(Change the setpoint using the Up/Down arrow keys to increase and decrease the value and the Left/Right arrow keys to move between digits.)

7.

Press the SET/ENTER key to register the setpoint (the setpoint stops blinking)

8. Press the PARA key once to return to the Menu Display. Press the DISP key once to return to the Operation Display.

This completes the setting procedure.

## How to Cancel Parameter Setting

To cancel parameter setting when a parameter is being set (setpoint is blinking), press the PARA key once.

## How to Set Parameter Setpoint

## Numeric Value Setting



1. Display the Parameter Setting Display.

2. Press the SET/ENTER key to move to the setting mode (the setpoint blinks).
3. Press the Left arrow key to move one digit to the left. (Press the Right arrow key to move one digit to the right.)
4. Press the Up or Down arrow key to change the setpoint. Press the Up arrow key when 9 is displayed to move one digit to the left.
Press the Down arrow key when 0 is displayed to move one digit to the right.

## Selection Data Setting



## 5Pt

 DFF DH

1. Display the Parameter Setting Display.
2. Press the SET/ENTER key to move to the setting mode (the setpoint blinks).
3. Press the Up arrow key to change the setpoint (press 3. the Down arrow key to change the setpoint).
4. Press the SET/ENTER key to register the setpoint.

Time (minute.second) Setting


Example of 17 minutes 59 seconds


1. Display the Parameter Setting Display.
2. Press the SET/ENTER key to move to the setting mode (the setpoint blinks).
3. Press the Left arrow key to move one digit to the left. (press the Right arrow key to move one digit to the right.)
4. Press the Up or Down arrow key to change the setpoint. Press the Up arrow key when 5 is displayed to move one digit to the left.
Press the Down arrow key when 0 is displayed to move one digit to the right.

## dyN 1 1879

5. Press the SET/ENTER key to register the setpoint.

### 5.1 Setting Using Quick Setting Function

## Description

The Quick setting function is a function to easily set the basic function of the controller. The Quick setting function starts when the power is turned on after wiring.

The following lists the items to set using the Quick setting function.
(1) Control type (PID control, ON/OFF control.)
(2) Input function (PV input, range, scale (at voltage/current input), etc.)
(3) Output function (cycle time)

## Flowchart of Quick Setting Function



## Setting Example

Set the following parameters to set to PID control, thermocouple Type K (range: 0.0 to $500.0^{\circ} \mathrm{C}$ ), and current control output. No need to change the parameters other than the following parameters.

Set QSM = YES to enter the quick setting mode.
(1) Set CNT = PID.
(2) Set IN = K1.
(3) Set UNIT = C (initial value).
(4) Set RH = 500.0.
(5) Set RL $=0.0$.

Set EXIT = YES to quit the quick setting mode.
The Operation Display is shown.

Control Type

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :--- | :--- |
| CNT | Control type | EASY | PID: PID control <br> ONOF: ON/OFF control (1 point of <br> hysteresis) <br> ONOF2: ON/OFF control (2 points <br> of hysteresis) | CTL Set |

- Control type: 8.2 Setting Control Type (CNT)

Input Function

| Parameter symbol | Name | Display level | Setting range | Menu symbol |
| :---: | :---: | :---: | :---: | :---: |
| IN | PV input type | EASY | OFF: Disable <br> K1: -270.0 to $1370.0^{\circ} \mathrm{C} /-450.0$ to $2500.0^{\circ} \mathrm{F}$ K2: -270.0 to $1000.0^{\circ} \mathrm{C} /-450.0$ to $2300.0^{\circ} \mathrm{F}$ K3: -200.0 to $500.0^{\circ} \mathrm{C} /-200.0$ to $1000.0^{\circ} \mathrm{F}$ J: -200.0 to $1200.0^{\circ} \mathrm{C} /-300.0$ to $2300.0^{\circ} \mathrm{F}$ T1: -270.0 to $400.0^{\circ} \mathrm{C} /-450.0$ to $750.0^{\circ} \mathrm{F}$ T2: 0.0 to $400.0^{\circ} \mathrm{C} /-200.0$ to $750.0^{\circ} \mathrm{F}$ B: 0.0 to $1800.0^{\circ} \mathrm{C} / 32$ to $3300^{\circ} \mathrm{F}$ S: 0.0 to $1700.0^{\circ} \mathrm{C} / 32$ to $3100^{\circ} \mathrm{F}$ R: 0.0 to $1700.0^{\circ} \mathrm{C} / 32$ to $3100^{\circ} \mathrm{F}$ N: -200.0 to $1300.0^{\circ} \mathrm{C} /-300.0$ to $2400.0^{\circ} \mathrm{F}$ E: -270.0 to $1000.0^{\circ} \mathrm{C} /-450.0$ to $1800.0^{\circ} \mathrm{F}$ L: -200.0 to $900.0^{\circ} \mathrm{C} /-300.0$ to $1600.0^{\circ} \mathrm{F}$ U1: -200.0 to $400.0^{\circ} \mathrm{C} /-300.0$ to $750.0^{\circ} \mathrm{F}$ U2: 0.0 to $400.0^{\circ} \mathrm{C} /-200.0$ to $1000.0^{\circ} \mathrm{F}$ W: 0.0 to $2300.0^{\circ} \mathrm{C} / 32$ to $4200^{\circ} \mathrm{F}$ PL2: 0.0 to $1390.0^{\circ} \mathrm{C} / 32.0$ to $2500.0^{\circ} \mathrm{F}$ P2040: 0.0 to $1900.0^{\circ} \mathrm{C} / 32$ to $3400^{\circ} \mathrm{F}$ WRE: 0.0 to $2000.0^{\circ} \mathrm{C} / 32$ to $3600^{\circ} \mathrm{F}$ JPT1: -200.0 to $500.0^{\circ} \mathrm{C} /-300.0$ to $1000.0^{\circ} \mathrm{F}$ JPT2: - 150.0 to $150.0^{\circ} \mathrm{C} /-200.0$ to $300.0^{\circ} \mathrm{F}$ PT1: -200.0 to $850.0^{\circ} \mathrm{C} /-300.0$ to $1560.0^{\circ} \mathrm{F}$ PT2: -200.0 to $500.0^{\circ} \mathrm{C} /-300.0$ to $1000.0^{\circ} \mathrm{F}$ PT3: -150.00 to $150.00^{\circ} \mathrm{C} /-200.0$ to $300.0^{\circ} \mathrm{F}$ $0.4-2 \mathrm{~V}: 0.400$ to 2.000 V $1-5 \mathrm{~V}: 1.000$ to 5.000 V 4-20: 4.00 to 20.00 mA $0-2 \mathrm{~V}: 0.000$ to 2.000 V $0-10 \mathrm{~V}: 0.00$ to 10.00 V 0-20: 0.00 to 20.00 mA -1020: -10.00 to 20.00 mV 0-100: 0.0 to 100.0 mV | Set |
| UNIT | PV input unit | EASY | -: No unit <br> C: Degree Celsius <br> -: No unit <br> - -: No unit <br> - - -: No unit <br> F: Degree Fahrenheit |  |
| RH | Maximum value of PV input range | EASY | Depends on the input type. <br> - For temperature input - |  |
| RL | Minimum value of PV input range | EASY | Set the temperature range that is actually controlled. ( $\mathrm{RL}<\mathrm{RH}$ ) - For voltage / current input Set the range of a voltage / current signal that is applied. The scale across which the voltage / current signal is actually controlled should be set using the maximum value of input scale (SH) and minimum value of input scale (SL). (Input is always $0 \%$ when RL=RH.) |  |

Note1: W:W-5\% Re/W-26\% Re(Hoskins Mfg. Co.). ASTM E988
WRE: W97Re3-W75Re25

Input Function (Continued)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :--- | :--- | :--- |
| SDP | PV input scale <br> decimal point <br> position | EASY | 0: No decimal place <br> 1: One decimal place <br> 2: Two decimal places <br> 3: Three decimal places <br> 4: Four decimal places | PV Set |
| SH | Maximum value of <br> PV input scale | EASY | -19999 to $30000,(S L<S H)$, <br> $\|S H-S L ~\| \leq 30000$ |  |
| SL | Minimum value of <br> PV input scale | EASY |  |  |

Input setting: 7.1 Setting Functions of PV Input

## Output Function

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| CT | Control output cycle <br> time | EASY | 0.5 to 1000.0 s | OUT Set |

- Output type: 10.1 Setting Control Output Type


### 5.2 Restarting Quick Setting Function

Once functions have been built using the Quick setting function, the Quick setting function does not start even when the power is turned on. The following methods can be used to restart the Quick setting function.

- Set the parameter QSM (Quick setting mode) to ON and turn on the power again.
- Set the parameter IN (PV input type) to OFF and turn on the power again.


## CAUTION

The parameters related to the range or scale are initialized if the PV input type is changed.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| IN | PV input type | EASY | OFF: Disable | PV Set |
| QSM | Quick setting mode | EASY | OFF: Disable <br> ON: Enable | SYS Set |

### 6.1 Monitoring and Control of Operation Displays

### 6.1.1 Operation Display Transitions.

- Display/Non-display of Operation Display: 13.3.5 Setting Display/Non-display of Operation Display
- Registration of SELECT Display: 13.1.3 Registering SELECT Display (Up to 5 displays)



## Details of the Operation Display

The following is the Operation Display types and each display and operation description.


| Operation Display | Display and operation description |
| :--- | :--- |
|  | PV display: Displays measured input value (PV). <br> Setpoint display: Displays and changes target setpoint (SP). |
| SP Display |  |
| The Display is switched to the SP Display if the operation mode is |  |
| s.SP Change Operation] |  |
| (1) Press the SET/ENTER key to move to the setting mode (the setpoint |  |
| blinks). |  |
| (2) Use the Left or Right arrow key to move between digits (the setpoint |  |
| blinks). |  |
| (3) Use the UP or Down arrow key to change the value (the setpoint |  |
| blinks). |  |
| (4) Press the SET/ENTER key to register the setpoint. (the setpoint stops |  |
| binking). |  |
| * Only Up or Down arrow key operation is also possible. |  |
| When the operation mode is remote (REM lamp is lit): |  |

(Continued)

| Operation Display | Display and operation description |
| :---: | :---: |
| OUT Display | PV display: Displays measured input value (PV). <br> Setpoint display: Displays control output value and changes control output value in MAN mode. <br> The Display is switched to the OUT Display if the operation mode is switched to MAN when other Operation Display is shown. <br> The Display is switched to the OUT Display while auto-tuning is performed. <br> [OUT Change Operation] <br> The control output value can be changed with the Up or Down arrow key in MAN mode (MAN lamp is lit). <br> The control output value is changed by direct operation (without pressing the SET/ENTER key), and cannot be changed by moving between digits using the Left and Right arrow keys. |
| PID Number Display | PV display: Displays measured input value (PV). <br> Setpoint display: Displays PID number currently being used. |

## (Continued)

| Operation Display | Display and operation description |
| :--- | :--- |
| Analog Input |  |
| Setpoint display: Displays PV analog input value. |  |
| Display |  |
|  | SV analog input value |
| SELECT Display is for registering frequently-used parameters from |  |
| Parameter Setting Display, and for displaying them on Operation |  |
| Display so that the parameter settings can be easily changed in normal |  |
| operation. |  |
| PV display: Displays measured input value (PV). |  |
| Setpoint display: Displays and changes the registered parameter. |  |
| The following is the display example when the parameter A1 (alarm-1 |  |
| setpoint) is registered. |  |

### 6.2 Setting Target Setpoint

## Operation in the Operation Display

## Operation


3. Press the Left arrow key to move one digit to the left. (Press the Right arrow key to move one digit to the right.)
4. Press the Up or Down arrow key to change a setpoint. Press the Up arrow key when 9 is displayed to move one digit to the left.
Press the Down arrow key when 0 is displayed to move one digit to the right.

5
Press the SET/ENTER key to register the setpoint. Control with the new setpoint.

## Operation in Parameter Setting Display

## Setting Display

Parameter Setting Display Operation Display > PARA key for 3 seconds (to [MODE] Menu Display) > Right arrow key (to [SP] Menu Display ) >
 SET/ENTER key (The setting parameter is displayed.)

Press the Right arrow key until the [SP] Menu Display appears.

In the Setting Display for the target setpoint parameter, pressing the Left or Right arrow keys changes the group. (The group number is displayed on Group display.)

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| SP | Target setpoint | EASY | 0.0 to 100.0\% of PV input range <br> (EU) (Setting range: SPL to SPH) | SP 0 Pe |
| SPGR. | Number of SP <br> groups | STD | 1 to 4 | CTL Set |

Note1: If the SP limiter is set, the setting can be made within the range of the SP limiter.

The controller has four target setpoints (SP).

- SP limiter: 9.1 Setting SP Limiter
- SELECT parameter: 13.1.5 Registering SELECT Parameter Display (Up to 10 Displays)


### 6.3 Performing and Canceling Auto-tuning

## Setting Display

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :--- | :--- | :--- |
|  | AUTO-tuning <br> switch | EASY | OFF: Disable <br> 1: Perform auto-tuning. Tuning <br> result is stored in the PID of <br> group 1. |  |
| 2: Perform auto-tuning. Tuning |  |  |  |  |
| result is stored in the PID of |  |  |  |  |
| group 2. |  |  |  |  |
| 3: Perform auto-tuning. Tuning |  |  |  |  |
| result is stored in the PID of |  |  |  |  |
| group 3. |  |  |  |  |$\quad$ MODE Ope | 4: Perform auto-tuning. Tuning |
| :--- |
| result is stored in the PID of |
| group 4. |
| R: Tuning result is stored in the PID |
| for reference deviation. |$\quad$| AT.BS |
| :--- |
| SP bias in auto- <br> tuning |

## CAUTION

Set the operation mode to AUTO and RUN to perform auto-tuning.

## Lamp Status

| Status | STOP lamp | MAN lamp |
| :--- | :---: | :---: |
| During auto-tuning | Unlit | Blinking |

## Description

Auto-tuning is a function with which the controller automatically measures the process characteristics and sets PID constants, which are control-related parameters, to optimum values for the setpoint. Auto-tuning temporarily executes ON/OFF control, calculates appropriate PID constants from response data obtained, and sets these constants.

## CAUTION

Do not perform auto-tuning for the following processes.
Tune PID manually.

- Processes with fast response such as flow rate control and pressure control.
- Processes which do not allow the output to be turned on and off even temporarily.
- Processes which prohibit output changes at control valves (or other actuators).
- Processes in which product quality can be adversely affected if PV values fluctuate beyond their allowable ranges.


When SP bias in auto-tuning is set


## Tuning Point and Storage Location of Tuning Results

The tuning point when performing auto-tuning is the target setpoint that is currently used for control computation.
PID constants after the tuning are stored in the PID group that is specified when performing auto-tuning.

| Operation <br> mode | AT setpoint | Tuning point | Storage location |
| :--- | :--- | :--- | :--- |
| Local | 1 to 4, R | Setpoint that is currently <br> used | P, I, and D of the PID group specified in <br> AT. |
| Remote | 1 to 4, R | Remote setpoint | P, I, and D of the PID group specified in <br> AT. |

When the setpoint of AT is "R," the AT result is stored in the PID group for reference deviation.
When performing auto-tuning in AT setpoint "R", set the parameter ZON to other than 0 and 3 , and set the parameter RDV to other than 0 .

Auto-tuning cannot be performed when the control type (CNT) is as follows.

- ON/OFF control (1 point of hysteresis)
- ON/OFF control (2 points of hysteresis)

In addition, auto-tuning cannot be performed in the following cases (no error indication).

- Input error occurs. (Input burnout, ADC error, etc.)
- The operation mode is STOP.
- The operation mode is MAN.
- Output limiter setpoint at auto-tuning: AT.OL $\geq A T . O H$


## Start and Stop of Auto-tuning

Start and stop of auto-tuning can be set by parameter setting, or.
Auto-tuning is stopped in the following cases.

- Switch to MAN
- Switch to STOP
- The parameter AT is set to OFF.
- Power failure
- Auto-tuning is not finished even after the time-out detection time is elapsed.

The time-out detection time is about 24 hours.
When the auto-tuning error occurs, the error code is shown in the Operation Display.
Press any key to erase it.

- Auto-tuning time output limiter: 8.8 Adjusting Auto-tuning Operation


### 6.4 Adjusting PID Manually

## Setting Display

Parameter Setting Display Operation Display >PARA key for 3 seconds (to [MODE] Menu Display) > Right arrow key (to [PID] Menu Display ) >


SET/ENTER key (The setting parameter is displayed.) > Down arrow key (The setting parameter is displayed.)

In the Setting Display for the PID parameters, Displays can be arbitrarily switched using the Up, Down, Left or Right arrow key. Pressing the Left or Right arrow key changes the group. (The group number is displayed on Group display.)

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :--- | :--- | :--- |
| P | Proportional band | EASY | 0.0 to $999.9 \%$ <br> When $0.0 \%$ is set, it operates as <br> $0.1 \%$. |  |
| I | Integral time | EASY | OFF: Disable <br> 1 to 6000 s | PID |
| D | Derivative time | EASY | OFF: Disable <br> 1 to 6000 s |  |
| PIDN | PID number <br> selection | EASY | 1 to 4 | SP |
| PIDG. | Number of PID <br> groups | STD | 1 to 4 | CTL Set |

## Note

When changing the setpoint of the parameter PIDG., if the setpoint of the parameter PIDN which belongs to the SP menu is larger than that of the parameter PIDG., the PIDN setpoint is changed to the PIDG. setpoint.

There are four groups of PID parameters.
The PID parameters can be selected by using the following two methods:
(1) SP group number selection

The PID group which is set in the PID number selection (PIDN) of each SP group is used.

| SP number (SPNO) | Target setpoint (SP) | Setting range of PID number <br> selection (PIDN) |
| :---: | :---: | :---: |
| 1 | SP | 1 to 4 |
| 2 | SP | 1 to 4 |
| 3 | SP | 1 to 4 |
| 4 | SP | 1 to 4 |

When the SP parameter is displayed, the SP number is shown on Group display. When the PID parameters are displayed, the PID number is shown on Group display.

- Selection by keystroke: 6.6 Selecting Target Setpoint Number (SPNO)


## (2) Zone PID selection

- Selection by each Zone: 8.4 Switching PID


## Description

## Description and Tuning of Proportional Band

The proportional band is defined as the amount of change in input (or deviation), as a percent of span, required to cause the control output to change from $0 \%$ to $100 \%$. Because a narrower proportional band gives greater output change for any given deviation, it therefore also makes the control performance more susceptible to oscillation. At the same time, a narrower proportional band reduces the offset.
Reducing the proportional band to its smallest limit (proportional band $=0 \%$ ) results in ON/OFF control.


To fine-tune a proportional band obtained using auto-tuning, or to manually tune the proportional band:

- Work from larger to smaller numbers (wider to narrower).
- If cycling appears, that means that the proportional band is too narrow.
- Proportional band tuning cannot cancel an offset.

- Offset: 10.8 Canceling Offset of PV and SP (Manual Reset)


## Description and Tuning of Integral Time

The integral action (I action) is a function that will automatically diminish the offset (steady-state deviation) that is inherently unavoidable with proportional action alone. The integral action continuously increases or decreases the output in proportion to the time integral of the deviation (the product of the deviation and the time that the deviation continues.)
The integral action is normally used together with proportional action as proportional-plus-integral action (Pl action).
The integral time (I) is defined as the time required to develop, when a stepwise change in deviation is imposed, an output change due to integral action that is exactly equal to the change due to proportional action. The longer the integral time set, the slower the change in output; the smaller the time, the faster the output changes.


To manually tune the integral time

- The main goal is to reduce the offset.
- Adjust from longer time to shorter time.
- If you see an oscillation at a longer period than that seen when the proportional band is too narrow, then you have made the integral time too short.


Use the manual reset (MR) to cancel an offset when the integral action is disabled.

- Manual reset: 10.8 Canceling Offset of PV and SP (Manual Reset)


## Description and Tuning of Derivative Time

If the control object has a large time constant or dead time, the corrective action will be too slow with proportional action or proportional-plus-integral action alone, causing overshoot. However, even just sensing whether the deviation is on an increasing or a decreasing trend and adding some early corrective action can improve the controllability. Thus the derivative action ( D action) is action that changes the output in proportion to the deviation derivative value (rate-of-change).
The derivative time is defined as the time required with PD action to develop, when a constant-slope change in deviation is imposed, an output change due to derivative action that is exactly equal to the change due to proportional action.


To manually tune the derivative time

- Adjust from shorter time to longer time.
- If you see a short-period oscillation, the time is too long.

The longer the derivative time set, the stronger the corrective action, and the more likely the output will become oscillatory. Oscillations due to derivative action are characterized by a short period.
D = OFF should always be used when controlling fast-responding inputs such as pressure and flow rate, or inputs characterized by rapid fluctuation, such as optical sensors.


## Manual PID Tuning Procedure

(1) In principle, auto-tuning must be used.
(2) Tune PID parameters in the order of P, I, and D. Adjust a numeric slowly by observing the result, and keep notes of what the progress is.
(3) Gradually reduce $P$ from a larger value. When the PV value begins to oscillate, stop tuning and increase the value somewhat.
(4) Also gradually reduce I from a larger value. When the PV value begins to oscillate (with long period), stop tuning and increase the value somewhat.
(5) Gradually increase D from a smaller value. When the PV value begins to oscillate (with short period), stop tuning and lower the value slightly.

Reference Values for Manual Tuning of Temperature, Pressure, and Flow Rate

|  |  | Setting range <br> (reference) | Initial value for tuning (reference) |
| :--- | :---: | :---: | :---: |
| Pressure | P | 100 to $300 \%$ | $200 \%$ |
|  | I | 5 to 30 s | 15 s |
|  | D | OFF | OFF |
|  | P | 100 to $240 \%$ | $150 \%$ |
|  | I | 8 to 30 s | 20 s |
|  | D | OFF | OFF |
| Temperature <br> (electric <br> furnace) | P | 1 to $20 \%$ | $5 \%$ |
|  | I | 180 to 600 s | 240 s |
|  | D | $1 / 4$ to $1 / 6$ of l | 60 s |

### 6.5 Setting Alarm Setpoint

## Setting Display

Parameter Setting Display Operation Display > PARA key for 3 seconds (to [MODE] Menu Display) > Right arrow key (to [SP] Menu Display) >


SET/ENTER key (The setting parameter is displayed.) > Down arrow key (The setting parameter is displayed.)

In the setting Display for the alarm parameters, Displays can be arbitrarily switched using the Up, Down, Left or Right arrow key. Pressing the Left or Right arrow key changes the group. (The group number is displayed on Group display.)

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :--- | :--- | :--- |
| A1 to A4 | Alarm-1 to -4 <br> setpoint | EASY | Set a display value of setpoint of <br> PV alarm, SP alarm, deviation <br> alarm, output alarm, or velocity <br> alarm. <br> -19999 <br> within to 30000 (Set a value <br> Decimal point position depends on <br> the input type | SP Ope |
| ALNO. | Number of alarms | PRO | 0 to 4 | CTL Set |

Note:1 When the alarm setpoint parameter is displayed, the group number is shown on Group display.
Note2: The initial value of the parameter ALNO. is "4." Four alarm setpoint parameters are displayed for each SP group.

Each alarm type has four alarm setpoints.
Specifying the SP number (SPNO) determines the alarm setpoint to be used.

| Alarm-related parameter | Number of settings |
| :--- | :--- |
| Alarm type | 4 (number of settings) |
| PV velocity alarm time setpoint | 4 (number of settings) |
| Alarm hysteresis | 4 (number of settings) |
| Alarm delay timer | 4 (number of settings) |
| Alarm setpoint | 4 (number of settings) x 4 (number of groups) |

- Alarm type: Chapter 11 Alarm Functions


### 6.6 Selecting Target Setpoint Number (SPNO)

## Setting Display

Parameter Setting Display Operation Display > PARA key for 3 seconds (to [MODE] Menu Display) > SET/ENTER key (The setting parameter
 is displayed.) > Down arrow key (The setting parameter is displayed.)

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| SPNO. | SP number <br> selection | EASY | 1 to 4 (Depends on the setup <br> parameter SPGR. setting.) | MODE 0pe |
| SPGR. | Number of SP <br> groups | STD | 1 to 4 | CTL Set |

Description
The SP number (SPNO) selection can be used when the parameter ZON (zone PID selection) is set to "SP group number selection."

## SP Group Number Selection

The PID group which is set in the PID number selection (PIDN) of each SP group is used.

| SP number (SPNO) | Target setpoint (SP) | Setting range of PID number <br> selection (PIDN) |
| :---: | :---: | :---: |
| 1 | SP | 1 to 4 |
| 2 | SP | 1 to 4 |
| 3 | SP | 1 to 4 |
| 4 | SP | 1 to 4 |

When the SP parameter is displayed, the SP number is shown on Group display.

### 6.7 Switching Operation Modes

### 6.7.1 Switching between AUTO and MAN

Direct Operation by A/M Key

## Operation



## Description

AUTO/MAN switching can be performed by any of the following:
(1) A/M key
(2) Communication
(3) User function key


- Switch by user function key: 13.2 Assigning Function to User Function Key and A/M key

| Switch | Output action |
| :---: | :--- |
| AUTO $\rightarrow$ MAN | Holds the control output value from AUTO mode. <br> The control output value can be bump to the manual preset output value by the <br> setting of parameter MPO. <br> The output value can be changed in manual mode. |
| MAN $\rightarrow$ AUTO | The control output value does not bump (bumpless). Does not work when <br> Integral time (I) = OFF. |

- Switch from AUTO to MAN, and MPON: 10.12.2 Setting Output Value When Switched to MAN Mode (Manual Preset Output)


## Operation Display in AUTO and MAN Modes

"OUT" is displayed on Symbol display and "Output value" is displayed on Data display in MAN mode. (The OUT Display is shown.)

## IHE <br> 4717

SP Display is shown in AUTO mode.

```
% 5P
    127%I
```

Lamp Status

| Status | MAN lamp |
| :--- | :---: |
| Automatic operation (AUTO) | Unlit |
| Manual operation (MAN) | Lit |

### 6.7.2 Switching between STOP and RUN

## Setting Display

\(\begin{array}{ll}Operation Mode Setting Display \& Operation Display > PARA key for <br>
\& 3 seconds (to [MODE] Menu Display)>SET/ENTER key <br>

\)|  PV rococomn  |  |  |
| :--- | :--- | :--- |
| $5 i / \int$ |  |  (The operation mode is displayed.) $>\text { Down arrow key (The }$ |
| $15 R$ |  operation mode is displayed.)  |  |\end{array}



Setting Details

- Switch by user function key: 13.2 Assigning Function to User Function Key and A/M key

| Switch | Output action |
| :--- | :--- |
| RUN $\rightarrow$ STOP | The control output bumps. |
| STOP $\rightarrow$ RUN | The control output does not bump (bumpless). |



- Preset output value: 10.12.1 Setting Output Value in STOP Mode (Preset Output)


## Operation Display in STOP and RUN Modes

"STOP" is displayed on Symbol display and "Output value" is displayed on Data display in STOP mode. Preset output value is displayed.

## : SLETM $57 \square$

The display at operation start differs depending on AUTO or MAN mode. SP Display is shown in AUTO mode and OUT Display is shown in MAN mode.

SP Display


OUT Display


Lamp Status

| Status | STOP lamp |
| :--- | :---: |
| Operation start (RUN) | Unlit |
| Operation Stop (STOP) | Lit |

### 6.7.3 Switching between REM (Remote) and LCL (Local)

## Setting Display

Operation Mode Setting Display Operation Display >PARA key for 3 seconds (to [MODE] Menu Display) > SET/ENTER key (The operation mode
 is displayed.) > Down arrow key (The operation mode is displayed.)

The parameter R.L is displayed when the the communication is specified.


Switch by user function key: 13.2 Assigning Function to User Function Key and A/M key

The PID group before switching from LOCAL to REMOTE is applied to the PID in remote operation.
SP Action in REM/LCL Switch

| Switch | SP action |
| :--- | :--- |
| LCL $\rightarrow$ REM | The local target setpoint bumps to the remote target setpoint. |
| REM $\rightarrow$ LCL | The remote target setpoint bumps to the local target setpoint. Or forces the local <br> target setpoint to track the remote target setpoint. |

- Tracking: 9.4 Forcing SP to Track Remote Input (SP Tracking)

Lamp Status

| Status | REM lamp |
| :--- | :---: |
| Local (LCL) | Unlit |
| Remote (REM) | Lit |

### 6.8 Manipulating Control Output during Manual Operation

## Operation



In MAN mode, the control output is manipulated by direct key operation. (The value changed using the Up or Down arrow key is output as is.)
Manipulation of the control output is not possible in STOP mode (the STOP lamp is lit). Output manipulation differs depending on the ON or OFF setting of the control output limiter ( $\mathrm{OH}, \mathrm{OL}$ ).

- 10.4 Disabling Output Limiter in MAN mode

OUT Display
' IUL 4717

When the control output low limit is set to "SD" while the control output type is 4 to 20 mA , the control output value can be lowered down to 0 mA .

- 10.6 Reducing 4-20 mA Current Output to 0 mA (Tight Shut Function)


## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :--- | :--- | :--- |
| MAN.T | Manual output <br> operation type | Selects how to manipulate the <br> control output during manual <br> operation. (Note) <br> DT.ET: Direct key method <br> (The value specified by the Up <br> and Down arrow keys is <br> output as is.) <br> ST.ET: SET/ENT key method <br> (The value specified on the <br> setting display and confirmed <br> with the SET/ENT key is <br> output.) | OUT Ope |  |

### 6.9 Releasing On-State (Latch) of Alarm Output

## Description

Alarm latch can be released by any of the following.
(1) User function key
(2) Communication

For the switching operation by using the above, the last switching operation is performed.
Releasing the alarm latch function releases all of the latched alarm outputs.
By factory default, the function is not assigned to the user function key. Assign and use the function in accordance with the reference sections below.

- Release by user function key: 13.2 Assigning Function to User Function Key and A/M key
- Release via communication: UTAdvanced Series Communication Interface User's Manual


### 7.1 Setting Functions of PV Input

### 7.1.1 Setting Input Type, Unit, Range, Scale, and Decimal Point Position

## Description

The figure below describes the case of PV input.

## Example of Temperature Input

The figure below is an example of setting Type K thermocouple and a measurement range of 0.0 to $800.0^{\circ} \mathrm{C}$.


## Example of Voltage and Current Inputs

The figure below is an example of setting 2-4 V DC and a scale of 0.0 to $50.0 \mathrm{~m}^{3} / \mathrm{h}$.


Minimum value of PV input scale Maximum value of PV input scale
When using 1-5 V DC signal as is, set $\mathrm{RH}=5.000 \mathrm{~V}$, $\mathrm{RL}=1.000 \mathrm{~V}$, $\mathrm{SDP}=1$, and $\mathrm{SH}=$ 50.0, and SL=0.0.

## Setting Details

| Parameter symbol | Name | Display level | Setting range | Menu symbol |
| :---: | :---: | :---: | :---: | :---: |
| IN | PV input type | EASY | OFF: Disable K1:-270.0 to $1370.0^{\circ} \mathrm{C} /-450.0$ to $2500.0{ }^{\circ} \mathrm{F}$ K2:-270.0 to $1000.0^{\circ} \mathrm{C} /-450.0$ to $2300.0{ }^{\circ} \mathrm{F}$ K3: -200.0 to $500.0^{\circ} \mathrm{C} /-200.0$ to $1000.0{ }^{\circ} \mathrm{F}$ J: -200.0 to $1200.0^{\circ} \mathrm{C} /-300.0$ to $2300.0{ }^{\circ} \mathrm{F}$ T1: -270.0 to $400.0^{\circ} \mathrm{C} /-450.0$ to $750.0^{\circ} \mathrm{F}$ T2: 0.0 to $400.0^{\circ} \mathrm{C} /-200.0$ to $750.0^{\circ} \mathrm{F}$ B: 0.0 to $1800.0^{\circ} \mathrm{C} / 32$ to $3300^{\circ} \mathrm{F}$ S: 0.0 to $1700.0^{\circ} \mathrm{C} / 32$ to $3100^{\circ} \mathrm{F}$ R: 0.0 to $1700.0^{\circ} \mathrm{C} / 32$ to $3100^{\circ} \mathrm{F}$ N: - 200.0 to $1300.0^{\circ} \mathrm{C} /-300.0$ to $2400.0^{\circ} \mathrm{F}$ E: - -270.0 to $1000.0^{\circ} \mathrm{C} /-450.0$ to $1800.0^{\circ} \mathrm{F}$ L: : -200.0 to $900.0^{\circ} \mathrm{C} /-300.0$ to $1600.00^{\circ} \mathrm{F}$ U1:-200.0 to $400.0^{\circ} \mathrm{C} /-300.0$ to $750.0{ }^{\circ} \mathrm{F}$ U2: 0.0 to $400.0^{\circ} \mathrm{C} /-200.0$ to $1000.0^{\circ} \mathrm{F}$ W: 0.0 to $2300.0^{\circ} \mathrm{C} / 32$ to $4200^{\circ} \mathrm{F}$ (Note1) <br> PL2: 0.0 to $1390.0^{\circ} \mathrm{C} / 32.0$ to $2500.0^{\circ} \mathrm{F}$ P2040: 0.0 to $1900.0^{\circ} \mathrm{C} / 32$ to $3400{ }^{\circ} \mathrm{F}$ WRE: 0.0 to $2000.0^{\circ} \mathrm{C} / 32$ to $3600^{\circ} \mathrm{F}$ JPT1:-20.0 to $500.0^{\circ} \mathrm{C} /-300.0$ to $1000.0^{\circ} \mathrm{F}$ JPT2: - 150.0 to $150.0^{\circ} \mathrm{C} /-200.0$ to $300.0^{\circ} \mathrm{F}$ PT1:-200.0 to $850.0^{\circ} \mathrm{C} /-300.0$ to $1560.0{ }^{\circ} \mathrm{F}$ PT2: -200.0 to $500.0^{\circ} \mathrm{C} /-300.0$ to $1000.0^{\circ} \mathrm{F}$ PT3: - 150.00 to $150.00^{\circ} \mathrm{C} /-200.0$ to $300.0{ }^{\circ} \mathrm{F}$ $0.4-2 \mathrm{~V}: 0.400$ to 2.000 V $1-5 \mathrm{~V}$ : 1.000 to 5.000 V 4-20: 4.00 to 20.00 mA $0-2 \mathrm{~V}: 0.000$ to 2.000 V $0-10 \mathrm{~V}: 0.00$ to 10.00 V 0-20: 0.00 to 20.00 mA -1020: -10.00 to 20.00 mV 0-100: 0.0 to 100.0 mV | PV Set |
| UNIT | PV input unit | EASY | -: No unit <br> C: Degree Celsius <br> -: No unit <br> - -: No unit <br> - - -: No unit <br> F: Degree Fahrenheit | PV Set |
| RH (Physical quantity) | Maximum value of PV input range | EASY | Depends on the input type. - For temperature input Set the temperature range that is actually controlled. (RL<RH) <br> - For voltage / current input Set the range of a voltage / current signal that is applied. <br> The scale across which the voltage / current signal is actually controlled should be set using the maximum value of input scale (SH) and minimum value of input scale (SL). (Input is always $0 \%$ when $\mathrm{RL}=$ RH.) | PV Set |
| RL (Physical quantity) | Minimum value of PV input range | EASY | Same as RH | PV Set |

Note1: W: W-5\% Re/W-26\% Re(Hoskins Mfg. Co.). ASTM E988 WRE: W97Re3-W75Re25
(Continued)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| SDP <br> (Scaling) | PV input scale decimal <br> point position | EASY | 0: No decimal place <br> 1: One decimal place <br> 2: Two decimal places <br> 3: Three decimal places <br> 4: Four decimal places | PV Set |

IN, UNIT, RH, and RL described above are the parameters to be used for processing before the input ladder calculation program.
The following parameters are used for processing after the input ladder calculation program.

| Parameter symbol | Name | Display level | Setting range | Menu symbol |
| :---: | :---: | :---: | :---: | :---: |
| P.UNI | Control PV input unit | STD | -: No unit <br> C: Degree Celsius <br> -: No unit <br> - -: No unit <br> -- -: No unit <br> F: Degree Fahrenheit | MPV Set |
| P.DP | Control PV input decimal point position |  | 0 : No decimal place <br> 1: One decimal place <br> 2: Two decimal places <br> 3: Three decimal places <br> 4: Four decimal places |  |
| P.RH | Maximum value of control PV input range |  | ```-19999 to 30000, (P.RL<P.RH), \| P.RH - P.RL | \leq }3000``` |  |
| P.RL | Minimum value of control PV input range |  |  |  |

### 7.1.2 Setting Burnout Detection for Input

## Description

The input value when input burnout occurs can be determined.
The input value is $105.0 \%$ of the input range when the upscale is set, and $-5.0 \%$ of the input range when the downscale is set.
Burnout detection is activated for TC, RTD, and standard signal ( $0.4-2 \mathrm{~V}$ or $1-5 \mathrm{~V}$ ). For standard signal, burnout is determined to have occurred if it is 0.1 V or less for the range of $0.4-2 \mathrm{~V}$ and $1-5 \mathrm{~V}$, or if it is 0.4 mA or less for the range of $4-20 \mathrm{~mA}$.

When input burnout occurs, the error preset output (EPO) is output as control output.

- Input error preset output: 10.12.3 Setting Output Value When Error Occurs (Input Error Preset Output)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :--- | :--- |
| BSL | PV input burnout action | STD | OFF: Disable <br> UP: Upscale <br> DOWN: Downscale | PV Set |

### 7.1.3 Setting Reference Junction Compensation (RJC) or External Reference Junction Compensation (ERJC)

## Description

## Reference Junction Compensation (RJC)

When TC input is selected, presence/absence of input reference junction compensation can be set.
Usually input values are compensated with the RJC function provided for the controller. However, if it is necessary to rigorously compensate the values with a device other than the function of the controller, for example with a zero-compensator, the RJC function of the controller can be turned off.

## External Reference Junction Compensation (ERJC)

For TC input, a temperature compensation value for external device can be set.
The external RJC can be used only when RJC = OFF.


| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| RJC | PV input reference <br> junction compensation | PRO | OFF: RJC OFF <br> ON: RJC ON | PV Set |
| ERJC | PV input external RJC <br> setpoint | PRO | -10.0 to $60.0^{\circ} \mathrm{C}$ | PV Set |

### 7.1.4 Correcting Input Value

## (1) Setting Bias and Filter

## Description

## PV Input Bias

The PV input bias allows bias to be summed with input to develop a measured value for display and control use inside the controller.
This function can also be used for fine adjustment to compensate for small interinstrument differences in measurement reading that can occur even if all are within the specified instrument accuracies.
PV input bias is used for normal operation.

## PV Input Filter

If input noise or variations cause the low-order display digits to fluctuate so that the displayed value is difficult to read, a digital filter can be inserted to smooth operation.


This filter provides a first-order lag calculation, which can remove more noise the larger the time constant becomes. However, an excessively large time constant will distort the waveform.
PV input filter is used for normal operation.


## Analog Input Bias

Analog input bias is used to correct sensor-input characteristics, compensating lead wire errors, and so on.

## Analog Input Filter

The analog input filter is used to remove noise from an input signal. This filter provides a first-order lag calculation, which can remove more noise the larger the time constant becomes. However, an excessively large time constant will distort the waveform.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| BS | PV input bias | EASY | -100.0 to $100.0 \%$ of PV <br> input range span (EUS) | PVS |
| FL | PV input filter | EASY | OFF, 1 to 120 s |  |


| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| A.BS | PV analog input bias | STD | -100.0 to $100.0 \%$ of each <br> input range span (EUS) | PV Set |
| A.FL | PV analog input filter | STD | OFF, 1 to 120 s | PV Set |

### 8.1 Control Function Block Diagrams

### 8.1.1 Single-loop Control

## Description

These control functions provide the basic control function having one control computation unit.

Single-loop control can be used for Standard type controller.

- PID control: 8.2 Setting Control Type (CNT)

The Function block diagram describes only the basic functions.
Parameter symbols in the Function block diagram describe representative parameters.
For the functions and parameters which are not described in Function block diagram, see the following.

- Contact output assignment to retransmission output terminal: 10.1 Setting Control Output Type
- Analog output range change: 10.14 Changing Current Output Range


### 8.1 Control Function Block Diagrams

■ Single-loop Control Function Block Diagram


### 8.2 Setting Control Type (CNT)

The following table shows combination of Standard type.

| Control type | Suffix code: Type 1 |
| :--- | :---: |
|  | Standard type |
| PID control | $\checkmark$ |
| ON/OFF control <br> (1 point of hysteresis) | $V$ |
| ON/OFF control <br> (2 points of hysteresis) | $V$ |

$\checkmark$ : Available, N/A: Not available
The following table shows combination of control type (CNT) and output type.

| Control type | Output type |  |  |
| :--- | :---: | :---: | :---: |
|  | Current output | Time proportional <br> output | ON/OFF output |
| PID control | $\sqrt{ }$ | $\sqrt{2}$ | N/A |
| ON/OFF control <br> (1 point of hysteresis) | $\sqrt{ }$ | $\mathrm{N} / \mathrm{A}$ | $\sqrt{ }$ |
| ON/OFF control <br> (2 points of hysteresis) | $\sqrt{2}$ | $\mathrm{~N} / \mathrm{A}$ | $\sqrt{ }$ |

$\sqrt{ }$ : Available, N/A: Not available

- Output type: 10.1 Setting Control Output Type


### 8.2 Setting Control Type (CNT)

### 8.2.1 PID Control

## Description

PID control is a general control using control-related parameters PID.
When PID control is selected, PID should be obtained by auto-tuning after setting SP or PID should be set manually.

## Setting Details

| Parameter symbol | Name | Display level | Setting range | Menu symbol |
| :---: | :---: | :---: | :---: | :---: |
| CNT | Control type | EASY | PID: PID control <br> ONOF: ON/OFF control (1 point of hysteresis) <br> ONOF2: ON/OFF control (2 points of hysteresis) | CTL Set |
| P | Proportional band | EASY | 0.0 to $999.9 \%$ <br> When $0.0 \%$ is set, it operates as $0.1 \%$. | PID Ope |
| 1 | Integral time | EASY | OFF: Disable 1 to 6000 s |  |
| D | Derivative time | EASY | OFF: Disable 1 to 6000 s |  |
| MR | Manual reset | EASY | -5.0 to 105.0\% |  |
| PIDN | PID number selection | EASY | 1 to 4 | SP Ope |
| PIDG. | Number of PID groups | STD | 1 to 4 | CTL Set |

Note 1: The PID number ( 1 to 4 , or R ) is displayed on Group display while the parameter P, I, D, or MR is displayed.

## Note

When changing the setpoint of the parameter PIDG., if the setpoint of the parameter PIDN which belongs to the SP menu is larger than that of the parameter PIDG., the PIDN setpoint is changed to the PIDG. setpoint.

### 8.2.2 ON/OFF Control (1 point of hysteresis / 2 points of hysteresis)

## Description

ON/OFF control compares the SP and PV and outputs an on or off signal according to the positive or negative deviation ( $\mathrm{PV}-\mathrm{SP}$ ). Hysteresis can be set in the vicinity of the on/off output operating point.
If the SP and PV become close and the polarity of the deviation reverses frequently, the on/off output will cycle repeatedly. The life of the output relay will therefore be dramatically shortened.
In such a case, set a wider hysteresis so that the relay's frequent on/off output (chattering) will not occur.

When the control type (CNT) is set to "ONOF," one point of hysteresis can be set to the operating point.
When the control type (CNT) is set to "ONOF2," two points of hysteresis (deviation positive hysteresis and deviation negative hysteresis) can be set to the operating point.

## 1 point of hysteresis




2 points of hysteresis


## Setting Details

| Parameter symbol | Name | Display level | Setting range | Menu symbol |
| :---: | :---: | :---: | :---: | :---: |
| CNT | Control type | EASY | PID: PID control <br> ONOF: ON/OFF control (1 point of hysteresis) <br> ONOF2: ON/OFF control (2 points of hysteresis) | CTL Set |
| HYS | Hysteresis | EASY | In ON/OFF control: 0.0 to 100.0\% of PV input range span (EUS) | PID 0pe |
| HY.UP | Upper-side hysteresis (in ON/ OFF control) | EASY | 0.0 to $100.0 \%$ of PV input range span (EUS) |  |
| HY.LO | Lower-side hysteresis (in ON/ OFF control) | EASY |  |  |
| PIDN | PID number selection | EASY | 1 to 4 | SP Ope |
| PIDG. | Number of PID groups | STD | Set a number of PID groups to use. <br> 1 to 4 | CTL Set |

Note1: The PID number ( 1 to 4, or R) is displayed on Group display while the parameter HYS, HY.UP or HY.LO is displayed.

## Note

When changing the setpoint of the parameter PIDG., if the setpoint of the parameter PIDN which belongs to the SP menu is larger than that of the parameter PIDG., the PIDN setpoint is changed to the PIDG. setpoint.

### 8.2.3 PD Control (Stable Control in Which a Setpoint is not Exceeded)

## Description

This control type performs control in which integral action (I action) is excluded from PID action.
Set the integral time (I or Ic) to OFF.
It is useful when stable control in which a setpoint is not exceeded is desired for integral processes in which constant flows are delivered.
The following shows the PID control computation formula.
$O U T=\frac{100}{P}\left(e+T d \frac{d}{d t} \cdot \Delta P V\right)+M R$
where OUT: control output, e: deviation (PV-SP), P: proportional band, Td: derivative time, $\Delta \mathrm{PV}$ : PVn-PVn-1 (n-1: value before one control period), and MR: manual reset

The following table shows combination of PD control and output method.

|  | Output method |  |  |
| :--- | :---: | :---: | :---: |
|  | Current output | Time proportional <br> output | ON/OFF output |
|  | $\checkmark$ | $V$ | N/A |

$\checkmark$ : Available, N/A: Not available

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| P | Proportional band | EASY | 0.0 to $999.9 \%$ <br> When $0.0 \%$ is set, it operates as $0.1 \%$. |  |
| D | Derivative time | EASY | OFF: Disable <br> 1 to 6000 s |  |
| MR | Manual reset | EASY | -5.0 to $105.0 \%$ |  |

Note1: The PID number ( 1 to 4 , or R ) is displayed on Group display while the parameter P, D, or MR is displayed.

## Note

When changing the setpoint of the parameter PIDG., if the setpoint of the parameter PIDN which belongs to the SP menu is larger than that of the parameter PIDG., the PIDN setpoint is changed to the PIDG. setpoint

### 8.3 Setting PID Control Mode (ALG)

There are two PID control modes: standard PID control mode and fixed-point control mode.
Select a PID control computation formula shown in the following table according to the control mode or operation mode.

|  | Operation mode |  |
| :---: | :---: | :---: |
|  | AUTO+Local | AUTO+Remote |
| Standard PID control <br> mode | PV derivative type <br> (output bump at SP change) | Deviation derivative type |
| Fixed-point control <br> mode | PV derivative type <br> (output bumpless at SP change) | PV derivative type <br> (output bump at SP change) |

## PV Derivative Type PID

This is a PID control method in which the derivative action works only on the PV. It can also eliminate output bump due to SP changing operation in Local mode. The following shows the PV derivative type PID control computation formula.

OUT $=\frac{100}{P}\left(e+\frac{1}{\mathrm{Ti}} \int \mathrm{e} \cdot d \mathrm{dt}+\mathrm{Td} \frac{\mathrm{d}}{\mathrm{dt}} \cdot \Delta \mathrm{PV}\right)$
where OUT: control output, e: deviation (PV-SP), P: proportional band, Ti: integral time, Td: derivative time, and $\Delta \mathrm{PV}$ : $\mathrm{PVn}-\mathrm{PVn}-1$ ( $\mathrm{n}-1$ : value before one control period)

PV Derivative Type PID (output bump at SP change)


PV Derivative Type PID (output bumpless at SP change)


## Deviation Derivative Type PID

The PID control method in which derivative action works for the deviation value $=$ PV SP.
The following shows the deviation derivative type PID control computation formula.
OUT $=\frac{100}{P}\left(e+\frac{1}{T i} \int e \cdot d t+T d \frac{d}{d t} \cdot e\right)$
where OUT: control output, e: deviation (PV-SP), P: proportional band, Ti: integral time, and Td: derivative time


| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :---: | :---: |
| ALG | PID control mode | PRO | 0: Standard PID control mode <br> 1: Fixed-point control mode. | CTL Set |

### 8.4 Switching PID

### 8.4.1 Switching PID According to Target Setpoint Number (SPNO)

## Description

The SP group number selection selects a group of target setpoint (SP) and PID parameters by switching the SP number (SPNO).
The PID number selection (PIDN) can be set for each SP group.

| SP number (SPNO) | SP | PID parameter group |
| :---: | :---: | :---: |
| 1 | SP of group 1 | Specify using the parameter PIDN of group 1 |
| 2 | SP of group 2 | Specify using the parameter PIDN of group 2 |
| 3 | SP of group 3 | Specify using the parameter PIDN of group 3 |
| 4 | SP of group 4 | Specify using the parameter PIDN of group 4 |

When ZON=0 (SP group number selection 1): In coordinated operation, slaves operate with the same PID number as that of the master.
The setpoint in the PID number selection (PIDN) within the SP group is ignored.
When ZON=3 (SP group number selection 2): In coordinated operation, slaves operate with the setpoint in the PID number selection (PIDN) within the SP group.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :--- | :--- | :--- |
| ZON | Zone PID <br> selection | STD | 0: SP group number selection 1 <br> 1: Zone PID selection (selection <br> by PV) <br> 2: Zone PID selection (selection <br> by target SP) <br> 3: SP group number selection 2 <br> 4: Zone PID selection (selection <br> by SP) | CTL Set |
| PIDN | PID number <br> selection | EASY | 1 to 4 (Depends on the setup <br> parameter PIDG. setting.) | SP Ope |
| PID | PID number <br> (display only) | EASY | 1 to 4 | MODE Ope |
| PIDG. | Number of PID <br> groups | STD | 1 to 4 | CTL Set |

Note1: The initial values for PIDN of the four groups are same as SP number selection (SPNO.). Set a PID number to use as necessary.
Note3: A currently-used PID number is displayed for the parameter PID.

## Note

When changing the setpoint of the parameter PIDG., if the setpoint of the parameter PIDN which belongs to the SP menu is larger than that of the parameter PIDG., the PIDN setpoint is changed to the PIDG. setpoint.

### 8.4.2 Switching PID According to PV

The PID switching according to PV is a function that switches between the groups of PID parameters according to the PV.
The maximum number of PID groups to be switched is 8 . (Set RP1 to RP3.) This function is useful for reactors in which the chemical reaction gain changes depending on the temperature.

The figure below shows an example of dividing the PV input range from the maximum value to the minimum value into four zones by reference points 1 to 3 . (Set RP1 to RP3.)


The PV input range can be divided into the number of zones that is set in the reference point.
Hysteresis at the time of zone switch can be set.

- Setpoint PD: 8.4.6 Setting Hysteresis at Time of Zone Switch

Reference deviation can be set at the same time.

- Reference deviation: 8.4.5 Switching PID according to Deviation (Reference Deviation)


## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| ZON | Zone PID <br> selection | STD | 0: SP group number selection 1 <br> 1: Zone PID selection (selection <br> by PV) <br> 2:Zone PID selection (selection <br> by target SP) <br> 3: SP group number selection 2 <br> 4: Zone PID selection (selection <br> by SP) | CTL Set |
| RP1 to RP3 | Reference point <br> 1 to 3 | STD | 0.0 to 100.0\% of PV input range <br> (EU) <br> (RP1 | RON RP RP3) |

Note1: A currently-used PID number is displayed for the parameter PID.

## Note

When changing the setpoint of the parameter PIDG., if the setpoint of the parameter PIDN which belongs to the SP menu is larger than that of the parameter PIDG., the PIDN setpoint is changed to the PIDG. setpoint.

### 8.4.3 Switching PID According to SP

## Description

The zone PID selection by SP switches between the groups of PID parameters according to the SP.
The maximum number of PID groups to be switched is 4. (Set RP1 to RP3)
The figure below shows the example of switching the group of PID parameters according to the SP. It shows an example of dividing the PV input range from the maximum value to the minimum value into four zones by reference points 1 to 3. (Set RP1 to RP3.)


The PV input range can be divided into the number of zones that is set in the reference point.

Reference deviation can be set at the same time.

- Reference deviation: 8.4.5 Switching PID according to Deviation (Reference Deviation)


## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :--- | :--- | :--- |
| ZON | Zone PID <br> selection | STD | 0: SP group number selection 1 <br> 1: Zone PID selection (selection <br> by PV) <br> 2: Zone PID selection (selection <br> by target SP) <br> 3: SP group number selection 2 <br> 4: Zone PID selection (selection <br> by SP) | CTL Set |
| RP1 to RP3 | Reference point 1 <br> to 3 | STD | 0.0 to 100.0\% of PV input range <br> (EU) <br> (RP1 $\leq$ RP2 $\leq$ RP3) | ZONE Ope |
| PIDG. | Number of PID <br> groups | STD | 1 to 4 | CTL Set |
| PID | PID number <br> (display only) | EASY | 1 to 4, R: PID group for reference <br> deviation | MODE Ope |

Note1: A currently-used PID number is displayed for the parameter PID.

## Note

When changing the setpoint of the parameter PIDG., if the setpoint of the parameter PIDN which belongs to the SP menu is larger than that of the parameter PIDG., the PIDN setpoint is changed to the PIDG. setpoint.

### 8.4.4 Switching PID According to Target SP

## Description

The zone PID selection by target SP switches between the groups of PID parameters according to the target SP.

The figure below shows the example of switching the group of PID parameters according to the target SP. It shows an example of dividing the PV input range from the maximum value to the minimum value into four zones by reference points 1 to 3 . (Set RP1 to RP3.)


The PV input range can be divided into the number of zones that is set in the reference point.

Reference deviation can be set at the same time.

- Reference deviation: 8.4.5 Switching PID according to Deviation (Reference Deviation)


## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| ZON | Zone PID <br> selection | STD | 0: SP group number selection 1 <br> 1: Zone PID selection (selection <br> by PV) | 2: Zone PID selection (selection <br> by target SP) <br> 3: SP group number selection 2 <br> 4: Zone PID selection (selection <br> by SP) |
| RP1 to RP3 | Reference point 1 <br> to 3 | STD | 0.0 to 100.0\% of PV input range <br> (EU) <br> (RP1 $\leq$ RP2 $\leq$ RP3) | ZONE Ope |
| PIDG. | Number of PID <br> groups | STD | 1 to 4 | CTL Set |
| PID | PID number <br> (display number) | EASY | 1 to 4, R: PID group for reference <br> deviation | MODE Ope |

Note1: A currently-used PID number is displayed for the parameter PID.
Note
When changing the setpoint of the parameter PIDG., if the setpoint of the parameter PIDN which belongs to the SP menu is larger than that of the parameter PIDG., the PIDN setpoint is changed to the PIDG. setpoint.

### 8.4.5 Switching PID According to Deviation (Reference Deviation)

## Description

The zone PID selection by deviation switches between the groups of PID parameters according to the amount of deviation.
This function is called "reference deviation."
In the fixed point control, if the actual amount of deviation exceeds the setpoint of the reference deviation, the controller automatically changes to the PID parameter group (PID of group R) set for the zone. If the actual amount of deviation becomes smaller than the setpoint of reference deviation, the controller changes to the PID parameter group appropriate for the zone.
For example, if the deviation is large, PV can be reached more rapidly to SP by increasing the proportional gain (i.e., narrowing the proportional band). Switching PID according to deviation is effective when ZON is set to $1,2,4$. The zone PID selection by reference deviation has priority over other zone PID selections.


## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| ZON | Zone PID <br> selection | STD | 0: SP group number selection 1 <br> 1: Zone PID selection (selection <br> by PV) <br> 2: Zone PID selection (selection <br> by target SP) <br> 3: SP group number selection 2 <br> 4: Zone PID selection (selection <br> by SP) | CTL Set |
| RDV | Reference <br> deviation | STD | OFF: Disable <br> 0.0 + 1 digit to 100.0\% of PV input <br> range span (EUS) | ZONE Ope |
| PID | PID number <br> (display only) | EASY | 1 to 4, R: PID group for reference <br> deviation | MODE Ope |

Note1: A currently-used PID number is displayed for the parameter PID.

### 8.4.6 Setting Hysteresis at Time of PID Switch

Description
When the zone PID selection is selected, hysteresis at time of each zone switch can be set.
The following shows the operation example of hysteresis at time of zone switch.


Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| RHY | Zone PID switching <br> hysteresis | STD | 0.0 to 10.0\% of PV input <br> range span (EUS) | ZONE Ope |

### 8.5 Suppressing Overshoot (Super Function)

## Description

The Super function monitors the deviation for evidence that there is a danger of overshoot, and on sensing such danger automatically changes the setpoint temporarily to a somewhat lower value (sub-SP).
Once the danger of overshoot appears diminished, the function returns the effective SP gradually to the true SP. "Fuzzy ratiocination" techniques are employed in the algorithms used to change the SP to the lower temporary value, and to return it gradually to the true SP.


## Control System Block Diagram



## Example of Overshoot Suppression Control for Setpoint Changes



Example of Overshoot Suppression Control for Ramp-to-soak Transition


Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :--- | :--- |
| SC | Super function | EASY | OFF: Disable <br> 1: Overshoot suppressing function <br> (normal mode) | 2: Hunting suppressing function <br> (stable mode) <br> 3: Hunting suppressing function <br> (response mode) <br> 4: Overshoot suppressing function <br> (strong suppressing mode) |

The setting SC=4 is effective compared with $\mathrm{SC=}=1$. However, the hunting may occur until the PV reaches SP. Use it as usage.
Do not use the Super function for the Sample PI control.

### 8.6 Suppressing Hunting (Super2 Function)

## Description

The Super2 function suppresses the hunting effect of the controller without re-tuning the PID parameters.
Hunting means the PV becomes unstable and oscillates around SP.


- In hunting condition, the Super2 function selects the output from process model as PV signal.
- The process model removes a factor of dead time from the actual process.
- The real process is under the open-loop condition.
- After hunting is suppressed, the Super2 function selects real PV signal, and carry out the standard feedback control.


Effects of Super2
Load change


## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :--- | :--- | :--- |
| SC | Super function | EASY | OFF: Disable <br> 1: Overshoot suppressing function <br> (normal mode) | 2: Hunting suppressing function <br> (stable mode) <br> 3: Hunting suppressing function <br> (response mode) <br> 4: Overshoot suppressing function <br> (strong suppressing mode). |

Set $\mathrm{SC}=2$ when there are a lot of disturbances, and much hunting occurs.
Set $S C=3$ when $S P$ is changed frequently. Hunting suppressing effect is smaller than that of $\mathrm{SC}=2$, however, responsiveness is good.

The Super function does not work in direct action.

### 8.7 Suppressing Integral Action (Anti-reset Wind-up)

## Description

Where there is a large deviation at the start of the control operation, for example, integral outputs are accumulated and the PV exceeds the SP, thereby causing the output to overshoot. To avoid this, the controller provides an anti-reset wind-up function for suppressing an extreme integral output by stopping PID computations. Same applies to the case of undershoot.


The parameter AR sets the point (by deviation band (\%)) to restart the PID computation that is suspended by the controller's anti-reset windup function. PID computation restarts when the deviation band has decreased to the AR setpoint. When the parameter AR is set to AUTO, the controller automatically determines the point at which to restart the PID computation.
Deviation band $\left(=\right.$ Setpoint of AR) $=\frac{|P V-S P|}{\text { Proportional band }} \times 100(\%)$

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :---: | :---: |
| AR | Anti-reset windup | STD | AUTO, 50.0 to $200.0 \%$ | TUNE Ope |

### 8.8 Adjusting Auto-tuning Operation

## Description

## Auto-tuning Type

"Normal" of auto-tuning type requires a rapidly rising PID constant. This type is useful for processes that allow some overshooting.
On the other hand, "stable" of auto-tuning type requires a slowly rising PID constant.

## Auto-tuning Output Limiter

When executing auto-tuning, the control output high and low limits can be set. When the control output low limit > AT.OL, or AT.OH < control output high limit, autotuning is limited by the control output low or high limit.

Note
In time proportional output, the output is turned on and off irrespective of the upper/lower limit.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| AT.TY | Auto-tuning type | STD | $0:$ Normal <br> $1:$ Stability |  |
| AT.OH | Output high limit in <br> auto-tuning | PRO | TUNE 0 Ope |  |
| AT.OL | Output low limit in <br> auto-tuning | PRO | -5.0 to 105.0\% |  |

### 9.1 Setting SP Limiter

## Description

The SP high and low limits can be set to restrict the SP to the range between those limits whether in REM (remote) or LCL (local) mode. They works to the SP of all SP groups.


- SP group: 6.2 Setting Target Setpoint


## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| SPH | SP high limit | STD | 0.0 to $100.0 \%$ of PV input range <br> $(E U),(S P L<S P H)$ | MPV Set |
| SPL | SP low limit | STD |  |  |

### 9.2 Changing SP at a Fixed Rate (SP Ramp-Rate Setting Function)

## Description

(1) When SP is changed

(3) When power is turned on (or power has recovered) (4) When operation mode is switched from MAN to AUTO





UPR $=\frac{\text { Temperature difference }\left({ }^{\circ} \mathrm{C}\right)}{\text { Time }(\mathrm{min})}=\frac{140^{\circ} \mathrm{C}}{2 \mathrm{~min}}=70\left({ }^{\circ} \mathrm{C} / \mathrm{min}\right)$

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| UPR | SP ramp-up rate | EASY | OFF, 0.0 + 1 digit to $100.0 \%$ of PV |  |
| input range span (EUS) |  |  |  |  |

### 9.3 Forcing SP to Track PV (PV Tracking)

## Description

PV tracking function is used to prevent abrupt PV changes.
With PV tracking, SP is first aligned with PV and then changed to its original SP at the SP ramp rate.

- SP ramp-rate setting function: 9.2 Changing SP at a Fixed Rate (SP Ramp-Rate Setting Function)

PV tracking function works when:
(1) Power is turned on or has recovered from a failure,
(2) SP number (SPNO) is changed,
(3) Operation mode is switched from STOP to RUN,
(4) Operation mode is switched from MAN to AUTO

PV tracking enabled


PV tracking disabled


## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :---: | :---: |
| PVT | PV tracking selection | STD | OFF, ON | SPS 0 Pe |

### 9.4 Forcing SP to Track Remote Input (SP Tracking)

## Description

SP tracking function is the function to force the local setpoint (SP) to track the remote setpoint (RSP) when the operation mode is switched from REM (remote) to LCL (local) mode.
The function is effective to prevent abrupt PV changes.

SP tracking enabled


SP tracking disabled


REM $\rightarrow$ LCL mode switch

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :--- | :--- |
| SPT | SP tracking selection | STD | OFF, ON | SPS Ope |

[^1]
### 9.5 Setting Controller Action at Power ON (Restart Mode)

## Description

For details, see Chapter 15, "Power Failure Recovery Processing."

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :--- | :--- |
| R.MD | Restart Mode | STD | Set how the controller should <br> recover from a power failure of 5 <br> seconds or more. <br> CONT: Continue action set before <br> power failure. <br> MAN: Start from MAN. <br> AUTO: Start from AUTO. | SYS Set |

The preset output (PO) is output in MAN or AUTO mode.

### 9.6 Setting Time between Powering on Controller and Starting Control (Restart Timer)

## Description

The time between power on and the instant where controller starts control computation can be set.

Operation start time $=$ Operating time of controller initialization after power on.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :---: | :---: |
| R.TM | Restart Timer | STD | 0 to 10 s | SYS Set |

### 10.1 Control Output Functions

## Description

## Time Proportional Relay Output (suffix code: -R) / Time Proportional Voltage Pulse Output (suffix code: -V)

In time proportional output, the control computation result is output in the form of an on/off signal pulse width proportional to the time. The pulse width is calculated as follows with the cycle time (control output cycle) at 100\%.
Control output pulse width = Control output (\%) x Cycle time
The output type is selected as either the relay output or the voltage pulse output.


## Current Output (suffix code: -C)

In current output, the control computation result is output as a current signal. (Example of 4 to 20 mA )


## ON/OFF Output

ON/OFF control compares the SP and PV and outputs an on or off signal according to the positive or negative deviation (PV - SP).

### 10.2 Setting Control Output Cycle Time

## Description

Cycle time is the basic cycle period for a signal full cycle of ON/OFF operation for a relay or voltage pulse output. Reducing cycle time results in faster cycling and finer control. In contrast, reducing the ON/OFF period also reduces relay life. For relay output, set the control output cycle time to 30 to 200 seconds according to the process speed.


Comparison of operations for the same control output (50\%)


Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| CT | Control output cycle <br> time | EASY | 0.5 to 1000.0 s | OUT Set |

### 10.3 Setting Limiter to Control Output

## Description

Control output high and low limits can be set to restrict the control output to the operation range between those limits.
The output limiter is prepared for each PID group, and works according to the selected PID group.
This, however, excludes preset output in STOP mode.

- PID group: 6.4 Adjusting PID Manually


| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| OH | Control output high <br> limit | EASY | -4.9 to $105.0 \%,(\mathrm{OL<OH})$ | OID 0 Oe |
| OL | Control output low limit | EASY | -5.0 to $104.9 \%,(\mathrm{OL<OH})$, SD: <br> Tight shut |  |
| PIDN | PID number selection | EASY | 1 to 4 | SP Ope |
| PIDG. | Number of PID groups | STD | 1 to 4 | CTL Set |

Note1: The PID number ( 1 to $4, R$ ) is displayed on Group display while each parameter is displayed. Note2: When the setting is low limit $\geq$ high limit, the controller operates as low limit = high limit -1 digit.

## Note

When changing the setpoint of the parameter PIDG., if the setpoint of the parameter PIDN which belongs to the SP menu is larger than that of the parameter PIDG., the PIDN setpoint is changed to the PIDG. setpoint.

### 10.4 Disabling Output Limiter in MAN mode

## Description

Output limiter can be released when in MAN mode.
Note that the output bump is caused if the operation mode is changed from MAN to AUTO while the control output is out of the range between the control output high limit (OH) and control output low limit (OL).
Control output bumps to OH in MAN mode when it is larger than OH . Moreover, it bumps to OL when smaller than OL.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :---: | :---: |
| OLMT | Output limiter switch | PRO | OFF: Disable output limiter in <br> MAN mode <br> ON: Enable output limiter in <br> MAN mode | TUNE Ope |

### 10.5 Setting Velocity Limiter to Control Output

## Description

Output velocity limiter prevents the control output signal from changing suddenly in order to protect the control valves (or other actuators) and controlled process.
The output velocity limiter does not work in MAN or STOP mode or when input burnout or A/D error occurs.
Note that setting an output velocity limit may cancel the effects of derivative action. The following shows the operation example of output velocity limiter.


In ON/OFF control, the setting is invalid even if the output velocity limiter is set.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :--- | :--- |
| OPR | Output velocity limiter | STD | OFF: Disable <br> 0.1 to $100.0 \% / \mathrm{s}$ | TUNE Ope |

### 10.6 Reducing 4-20 mA Current Output to 0 mA (Tight Shut Function)

## Description

Tight shut function fully closes the control valve (or other actuators) (i.e., so that output is zero) beyond its positioner dead band.
When the output low limit is set to "SD," the output is as follows in MAN or AUTO mode.

## - In MAN mode

When the output is reduced with the Down arrow key and "SD" is displayed as the output value, the output level reaches tight shut level. The control output delivers a tight shut signal (about 0.0 mA ).

- In AUTO mode

The output is limited by the output low limit (OL). It does not decrease to 0.0 mA .


| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :---: | :---: |
| OL | Control output low limit | EASY | -5.0 to 104.9\%, (OL<OH), SD: <br> Tight shut (0 mA output in <br> MAN mode) | PID Ope |
| PIDN | PID number selection | EASY | 1 to 4 | SP Ope |
| PIDG. | Number of PID groups | STD | 1 to 4 | CTL Set |

Note1: The PID number ( 1 to $4, \mathrm{R}$ ) is displayed on Group display while each parameter is displayed.

## Note

When changing the setpoint of the parameter PIDG., if the setpoint of the parameter PIDN which belongs to the SP menu is larger than that of the parameter PIDG., the PIDN setpoint is changed to the PIDG. setpoint.

### 10.7 Setting ON/OFF Control Hysteresis

## Description

In ON/OFF control, since the only two possible output states are ON and OFF, the control output cycles are as shown in the figure below. ON/OFF becomes quite narrow, so that if relay output is used, chattering occurs. In this case, the hysteresis should be set wider to prevent relay chattering and for the service life of the relay.

## One Point of Hysteresis

For one point of hysteresis, set one point of hysteresis.


## Two Points of Hysteresis

For two points of hysteresis, set two points of hysteresis (upper-side hysteresis and lower-side hysteresis).


## Setting Details

| Parameter symbol | Name | Display level | Setting range | Menu symbol |
| :---: | :---: | :---: | :---: | :---: |
| HYS | Hysteresis (in ON/OFF control) | EASY | $\begin{array}{\|l\|} \hline \text { In ON/OFF control: } 0.0 \text { to } \\ 100.0 \% \text { of PV input range } \\ \text { span (EUS) } \\ \hline \end{array}$ | PID Ope |
| HY.UP | Upper-side hysteresis (in ON/OFF control) | EASY | 0.0 to $100.0 \%$ of PV input range span (EUS) |  |
| HY.LO | Lower-side hysteresis (in ON/OFF control) | EASY |  |  |
| PIDN | PID number selection | EASY | 1 to 4 | SP Ope |
| PIDG. | Number of PID groups | STD | 1 to 4 | CTL Set |

Note1: The PID number ( 1 to $4, \mathrm{R}$ ) is displayed on Group display while each parameter is displayed.

## Note

When changing the setpoint of the parameter PIDG., if the setpoint of the parameter PIDN which belongs to the SP menu is larger than that of the parameter PIDG., the PIDN setpoint is changed to the PIDG. setpoint.

### 10.8 Canceling Offset of PV and SP (Manual Reset)

## Description

Manual reset can be used when the integral action is disabled.
When the integral action is disabled, there will be an offset of PV and SP. Manual reset cancels this offset.
The manual reset value equals the output value when $\mathrm{PV}=\mathrm{SP}$ is true.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| MR | Manual reset | EASY | -5.0 to $105.0 \%$ | PID 0 pe |
| PIDN | PID number selection | EASY | 1 to 4 | SP 0 pe |
| PIDG. | Number of PID groups | STD | 1 to 4 | CTL Set |

Note1: The PID number ( 1 to 4 , or R ) is displayed on Group display while each parameter is displayed.

[^2]
### 10.9 Setting Preset Output Value

### 10.9.1 Setting Output Value in STOP Mode (Preset Output)

## Description

Preset output becomes the output when the operation mode is switched from RUN to STOP.
The preset output is not limited by the output high and low limits.
The preset output is prepared for each PID parameter group, and works according to the selected PID parameter group.


## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| PO | Preset output | EASY | In STOP mode, fixed control <br> output can be generated. <br> -5.0 to $105.0 \%$ | PID |
| PIDN | PID number selection | EASY | 1 to 4 | SP |
| PIDG. | Number of PID groups | STD | 1 to 4 | CTL Set |

Note1: The PID number ( 1 to $4, \mathrm{R}$ ) is displayed on Group display while each parameter is displayed.
Note
When changing the setpoint of the parameter PIDG., if the setpoint of the parameter PIDN which belongs to the SP menu is larger than that of the parameter PIDG., the PIDN setpoint is changed to the PIDG. setpoint.

For ON/OFF output, $0.0 \%$ is output when the setting value is $0.0 \%$ or less and $100.0 \%$ is output when $0.1 \%$ or more.

### 10.9.2 Setting Output Value When Switched to MAN Mode (Manual Preset Output)

## Description

When the operation mode is switched from AUTO to MAN, each of the following can be selected.

- The control output takes over the control output as is.
- The control output bumps to the manual preset output.

When the manual preset output is output, the manual operation is possible after the bump.
Manual preset output is limited by the output high and low limits. (when Output limiter switch $($ OLMT $)=$ ON $)$


When the operation mode is switched from MAN to AUTO, transferred without bump from the manual output to the control output.

- Output limiter: 10.3 Setting Limiter to Control Output
- Output limiter switch: 10.4 Disabling Output Limiter in MAN mode


## Setting Details

| Parameter symbol | Name | Display level | Setting range | Menu symbol |
| :---: | :---: | :---: | :---: | :---: |
| MPON | Manual preset output number selection | STD | OFF: Hold the control output in AUTO mode (bumpless) <br> 1: Use manual preset output 1 (output bump) <br> 2: Use manual preset output 2 (output bump) <br> 3: Use manual preset output 3 (output bump) <br> 4: Use manual preset output 4 (output bump) <br> 5: Use manual preset output 5 (output bump) | TUNE Ope |
| MPO1 to MPO5 | Manual preset output 1 to 5 | STD | -5.0 to 105.0\% |  |

### 10.9.3 Setting Output Value When Error Occurs (Input Error Preset Output)

## Description

The $0 \%$ control output, $100 \%$ control output, or input preset output can be selected and output as input error preset output in the following conditions.

- The input burnout occurs during operation in AUTO mode and RUN mode.
- The ADC error occurs during operation in AUTO mode and RUN mode.

However, the manual output becomes the output when the input burnout occurs in MAN mode and RUN mode.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| EPO | Input error preset <br> output | STD | 0: Preset output <br> $1: 0 \%$ output <br> $2: 100 \%$ output | SYS Set |

### 10.10 Changing Current Output Range

## Description

The analog output type can be selected from among 4 to 20,0 to 20,20 to 4 , or 20 to 0 mA .

| Parameter symbol | Name | Display level | Setting range | Menu symbol |
| :---: | :---: | :---: | :---: | :---: |
| OU.A | OUT current output range | STD | $\begin{aligned} & \text { 4-20: } 4 \text { to } 20 \mathrm{~mA} \text {, } \\ & 0-20: 0 \text { to } 20 \mathrm{~mA}, \\ & 20-4: 20 \text { to } 4 \mathrm{~mA}, \\ & 20-0: 20 \text { to } 0 \mathrm{~mA} \end{aligned}$ | OUT Set |

## Parameters and Corresponding Terminals

$\square$

### 11.1 Setting Alarm Type

Description
The alarm-related parameters consist of the alarm type (type, stand-by action, energized/ de-energized, and latch function), PV velocity alarm time setpoint, alarm hysteresis, alarm (On-/Off-) delay timer, and alarm setpoint.

| Alarm-related parameter | Number of settings |
| :--- | :--- |
| Alarm type | 4 (number of settings) |
| PV velocity alarm time setpoint | 4 (number of settings) |
| Alarm hysteresis | 4 (number of settings) |
| Alarm (on-/off-) delay timer | 4 (number of settings) |
| Alarm setpoint | 4 (number of settings) $\times 4$ (number of groups) |

- Alarm hysteresis: 11.3 Setting Hysteresis to Alarm Operation
- Alarm delay timer: 11.4 Delaying Alarm Output (Alarm Delay Timer)
- Alarm setpoint: 6.5 Setting Alarm Setpoint

Factory default: Only four groups of alarm-related parameters are displayed.

- Terminal function: 17.4.7 Contact Output Wiring

To read the conditions of alarms, outputs, or latches via communication, see Communication Interface User's Manual.


PV High Limit Alarm and PV Low Limit Alarm


SP High Limit Alarm and SP Low Limit Alarm


Contact type in the figure above: Energized when an event occurs (factory default).

## Deviation High Limit Alarm and Deviation Low Limit Alarm



Contact type in the figure above: Energized when an event occurs (factory default).
When a negative setpoint is set for the deviation high limit alarm setpoint, the deviation setpoint will be lower than the SP.
Moreover, when a positive setpoint is set for the deviation low limit alarm setpoint, the deviation setpoint will be higher than the SP.

## Deviation High and Low Limits Alarm



Contact type in the figure above: Energized when an event occurs (factory default).

## Deviation within High and Low Limits Alarm



Contact type in the figure above: Energized when an event occurs (factory default).

## Target SP High Limit Alarm and Target SP Low Limit Alarm



Contact type in the figure above: Energized when an event occurs (factory default).

Target SP Deviation High Limit Alarm and Target SP Deviation Low Limit Alarm


Contact type in the figure above: Energized when an event occurs (factory default).

* Target SP: a set target setpoint. When the ramp-rate is set, it becomes a final target setpoint.

When a negative setpoint is set for the deviation high limit alarm setpoint, the deviation setpoint will be lower than the target SP.
Moreover, when a positive setpoint is set for the deviation low limit alarm setpoint, the deviation setpoint will be higher than the target SP.

## Target SP Deviation High and Low Limits Alarm



## Target SP Deviation within High and Low Limits Alarm



Contact type in the figure above: Energized when an event occurs (factory default).

## Control Output High Limit Alarm and Control Output Low Limit Alarm



Contact type in the figure above: Energized when an event occurs (factory default).

## Analog Input PV High Limit Alarm and Analog Input PV Low Limit Alarm

These alarms monitor the input value after the analog input computation process (entrance to the input ladder calculation) is completed.


Contact type in the figure above: Energized when an event occurs (factory default).

## PV Velocity Alarm



The PV velocity alarm function does not work the alarm hysteresis, the stand-by action and the alarm delay timer functions.

## Fault diagnosis Alarm

The function outputs an alarm signal in the following cases.
The corresponding event (EV) lamp is lit and the contact output turns on (when the contact type is energized).

- Burnout of PV input
- ADC failure of PV input
- Reference junction compensation (RJC) error of PV input

The fault diagnosis alarm does not work the stand-by action functions.

## FAIL output

When the FAIL condition is caused (faulty MCU or system data error), DO (alarm output) turned off regardless of contact type.
The FAIL output does not work the alarm latch, the energized/de-energized and the stand-by action functions.

## Stand-by Action

The stand-by action is a function for ignoring the alarm condition and keeps the alarm off until the alarm condition is removed. Once the alarm condition is removed, the stand-by action is cancelled.
It is effective in the following cases where;

- The power is turned on
- SP is changed
- SP number is switched (however, except for remote setpoint) (The SP must be changed.)
- The alarm type is changed
- Forced stand-by via communication

The following shows the behavior of an alarm with the stand-by action at power ON.


## Alarm Latch Function

The alarm latch function is a function for keeping the alarm output (keeping the alarm output on) after entering the alarm condition (alarm output is turned on) until an order to release the alarm latch is received.

The alarm latch function has the following four types of action.

## Latch 1

Cancels the alarm output when an order to release the alarm latch is received. (Alarm output OFF.)
However, an order to release the alarm latch is ignored if the order is received during alarm condition.

## Latch 2

Always forces cancelling of the alarm output when an order to release the alarm latch is received. (Alarm output OFF)

## Latch 3

Cancels the alarm output when an order to release the alarm latch is received or when the alarm condition is removed. (Alarm output OFF.)

## Latch 4

Cancels the alarm output when an order to release the alarm latch is received. (Alarm output OFF.)
However, cancels the alarm output for the duration of the sampling period (control period) if an order to release the alarm latch is received during alarm condition. (Alarm output OFF)


## Release of Alarm Latch

The alarm latch function can be cancelled by the user function key, or via communication. Cancelling the alarm latch function cancels all latched alarm outputs.

- Release by user function key: 13.2 Assigning Function to User Function Key and A/M key
- Release via communication: UTAdvanced Series Communication Interface User's Manual


Contact type in the figure above: Energized when an event occurs (factory default).

## Operation of Alarm Output and Display Lamp (EV)

The contact output and display lamp (EV) are usually output and displayed according to the setpoint of the alarm type. However, the alarm conditions (operations) of the normal action, and latch action can be assigned to the contact output and display lamp (EV), regardless of the setpoint of the alarm type. (Two operations can be assigned simultaneously.)

- Display lamp action: 13.1 Setting Display Functions
- Contact output action: 12.2.1 Setting Function of Contact Output


## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :---: | :--- | :--- | :--- | :--- |
| AL1 to AL4 | Alarm-1 to -4 type | EASY | See the table below. | ALRM |
| VT1 to VT4 | PV velocity alarm time <br> setpoint 1 to 4 | EASY | 00.01 to 99.59 <br> (minute.second) |  |

Note1: The initial values of the parmeters AL1 to AL4 and VT1 to VT4 are "4". The number of alarms can be changed using the parameter ALNO.

The following shows the example of setting PV high limit (01), With stand-by action (1), De-energized (1), and Latch 1 action (1).


| Name | Latch action <br> (Note 1) | Energized (0) <br> de-energized (1) | Stand-by action <br> Without (0) $/$ with (1) | Alarm <br> type |
| :--- | :---: | :---: | :---: | :---: |
| Disable | $-($ Note 2$)$ | $-($ Note 2$)$ | $-($ Note 2$)$ | 00 |
| PV high limit | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 01 |
| PV low limit | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 02 |
| SP high limit | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 03 |
| SP low limit | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 04 |
| Deviation high limit | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 05 |
| Deviation low limit | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 06 |
| Deviation high and low limits | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 07 |
| Deviation within high and low <br> limits | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 08 |
| Target SP high limit | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 09 |
| Target SP low limit | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 10 |
| Target SP deviation high limit | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 11 |
| Target SP deviation low limit | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 12 |
| Target SP deviation high and <br> low limits | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 13 |
| Target SP deviation within <br> high and low limits | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 14 |
| Control output high limit | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 15 |
| Control output low limit | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 16 |
| Analog input PV high limit | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 19 |
| Analog input PV low limit | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $0 / 1$ | 20 |
| PV velocity | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $-($ Note 2$)$ | 29 |
| Fault diagnosis | $0 / 1 / 2 / 3 / 4$ | $0 / 1$ | $-($ Note 2$)$ | 30 |
| FAIL | $--(N o t e 2)$ | $-($ Note 2$)$ | $-($ Note 2$)$ | 31 |

Note 1: 0: No latch function, 1: Latch 1, 2: Latch 2, 3: Latch 3, 4: Latch 4
Note 2: -: Alarm function doesn't work even if any value is set.

### 11.2 Setting Number of Alarm Groups to Use

## Description

Up to four alarm groups of alarm type, alarm hysteresis, alarm (On-/Off-) delay timer, and alarm setpoint are available.
Unused alarm parameters can be hidden and their functions can be turned off. The initial value of parameter ALNO. is "4."
When ALNO. = 4, for example, only the four groups of alarm type, PV velocity alarm time setpoint, alarm hysteresis, alarm delay timer, and alarm setpoint are displayed.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| ALNO. | Number of alarm <br> groups | PRO | 0 to 4 | CTL Set |

### 11.3 Setting Hysteresis to Alarm Operation

Description
If the On/Off switch of the alarm output is too busy, you can alleviate the busyness by increasing the alarm hysteresis.

Hysteresis for PV High Limit Alarm


When Setting Hysteresis of $5^{\circ} \mathrm{C}$ and $\mathbf{1 5}^{\circ} \mathrm{C}$ for PV High Limit Alarm


| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :---: | :---: | :---: | :--- | :--- |
| HY1 to HY4 | Alarm-1 to -4 <br> hysteresis | Sets the hysteresis setpoint as a <br> display value. |  |  |
| -19999 to 30000 (set it within the <br> input range) <br> The decimal point position <br> depends on the input type. | ALRM Ope |  |  |  |

### 11.4 Delaying Alarm Output (Alarm Delay Timer)

The alarm on-delay timer is a function for turning on the alarm when the alarm condition occurs, and the timer starts and the set time elapses.
The timer is reset if the alarm condition is removed while the timer is running. No alarm is generated.
The figure below shows the example of the On-delay timer


Contact type in the figure above: Energized when an event occurs (factory default).
The alarm Off-delay timer is a function for turning off the alarm when the alarm condition is removed (normal condition), and the timer starts and the set time elapses.
The timer is reset if the alarm condition occurs again while the timer is running. The alarm is not cancelled.

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :---: | :---: |
| DYN1 to <br> DYN4 | Alarm-1 to -4 On-delay <br> timer | STD |  |  |
| DYF1 to <br> DYF4 | Alarm-1 to -4 Off-delay <br> timer | PRO | (minute.second) | ALRM 99.59 (mes |

### 11.5 Setting Alarm Action According to Operation Mode

## Description

The alarm action usually functions regardless of operation modes.
Setting the alarm mode allows the alarm action to be disabled in STOP or in STOP or MAN mode.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :---: | :---: |
| AMD | Alarm mode | STD | 0: Always active <br> 1: Not active in STOP mode <br> 2: Not active in STOP or MAN <br> mode | ALRM Ope |

### 12.1 Contact Output Functions

### 12.1.1 Setting Function of Contact Output

## Description

The contact output function works by setting a status such as an alarm to the contact output.
This explanation assumes that the contact type is energized. (The contact is turned on when an event occurs.)

## Contact Output Equipped as Standard

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :---: | :---: |
| AL1.S | AL1 function selection | STD | See the following section. | ALM Set |
| AL2.S | AL2 function selection | STD |  |  |

Note1: Nothing is displayed on Group display when each parameter is displayed.

## Alarm Status

The alarm status can be output to the contact output. (The setpoints below are I relay numbers.)

- I relay: UTAdvanced Series Communication Interface (RS-485, Ethernet) User's Manual

| Setpoint |  |  |  |
| :---: | :---: | :--- | :--- |
| Alarm status | Alarm output <br> status |  | Function |
| 4321 | 4353 | Alarm 1 |  |
| 4322 | 4354 | Alarm 2 |  |
| 4323 | 4355 | Alarm 3 |  |
| 4325 | 4357 | Alarm 4 |  |

- Alarm status: The internal alarm status is turned on when an alarm occurs and turned off in normal condition
- Alarm output status: Contact output status when an alarm occurs (ON in alarm condition and OFF in normal condition)

However, the output status depends on the settings of energized/de-energized of alarm, latch action, and contact type.

The above assumes that the contact type is energized. (Then contact is turned on when an event occurs.)
To output the normal alarm to the contact output, assign the alarm output status.

- Alarm action: 11.1 Setting Alarm Type


## Alarm Latch Status

The alarm latch status can be output to another contact output irrespective of the setting of alarm-1 to -4 type (AL1 to AL4). (The setpoints below are I relay numbers.)

- I relay: UTAdvanced Series Communication Interface (RS-485, Ethernet) User's Manual

| Setpoint |  |  |  | Function |  |
| :---: | :---: | :---: | :---: | :--- | :--- |
| Alarm output <br> latch 1 status | Alarm output <br> latch 2 status | Alarm output <br> latch 3 status | Alarm output <br> latch 4 status |  |  |
| 4385 | 4417 | 4449 | 4481 | Alarm 1 |  |
| 4386 | 4418 | 4450 | 4482 | Alarm 2 |  |
| 4387 | 4419 | 4451 | 4483 | Alarm 3 |  |
| 4389 | 4421 | 4453 | 4485 | Alarm 4 |  |

- Alarm output latch $1,2,3$, and 4 status: ON in the latch status of the contact output when an alarm occurs and OFF in the latch release status of the contact output in normal condition

However, the output status depends on the settings of contact type.

- Alarm latch action: 11.1 Setting Alarm Type


## Key and Display Status

The key and display status can be output to the contact output. (The setpoints below are I relay numbers.)

| Setpoint | Function | Contact status |  |
| :---: | :---: | :---: | :---: |
|  |  | ON | OFF |
| 4705 | PARA key | Key is pressed | Key is not pressed |
| 4706 | DISP key |  |  |
| 4707 | Right arrow key |  |  |
| 4708 | Down arrow key |  |  |
| 4709 | SET/ENTER key |  |  |
| 4710 | Up arrow key |  |  |
| 4711 | Left key |  |  |
| 4714 | A/M key |  |  |
| 4715 | Fn key |  |  |

Operation Mode and Status

| Setpoint | Function | Contact status |  |
| :---: | :--- | :---: | :---: |
|  |  | ON | OFF |
| 4193 | AUTO/MAN | MAN | AUTO |
| 4194 | Remote/Local | Remote | Local |
| 4195 | STOP/RUN | STOP | RUN |
| 4201 | Output tracking status | Tracking ON | Tracking OFF |
| 4207 | During auto-tuning | During AT | - |
| 4256 | FAIL output | Normal status | FAIL status |

## System Error Status

| Setpoint | Function |  | Contact status |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | ON | OFF |  |
| 4769 | Message display interruption 1 status | With interruption | Without interruption |  |
| 4770 | Message display interruption 2 status | With interruption | Without interruption |  |
| 4771 | Message display interruption 3 status | With interruption | Without interruption |  |
| 4773 | Message display interruption 4 status | With interruption | Without interruption |  |

Error Status

| Setpoint | Function |  | Contact status |  |  |  |
| :---: | :--- | :---: | :---: | :---: | :---: | :---: |
|  |  | ON |  |  |  | OFF |
| 4065 | PV input ADC error |  |  |  |  |  |
| 4073 | PV input burnout error |  |  |  |  |  |
| 4070 | PV input RJC error | Error occurs | Normal |  |  |  |
| 4097 | PV input burnout error |  |  |  |  |  |
| 4101 | PV input over-scale |  |  |  |  |  |
| 4102 | PV input under-scale |  |  |  |  |  |
| 4111 | Auto-tuning time out |  |  |  |  |  |

## System Error Status

| Setpoint | Function | Contact status |  |
| :---: | :--- | :---: | :---: |
|  |  | ON |  |
| OFF |  |  |  |
| 4001 | System data error |  |  |
| 4002 | Calibration value error |  |  |
| 4003 | User (parameter) default value error | Error occurs | Normal |
| 4005 | Setup parameter error |  |  |
| 4006 | Operation parameter error |  |  |
| 4017 | Corrupted ladder program |  |  |
| 4009 | Faulty FRAM |  |  |

### 12.1.2 Changing Contact Type of Contact Output

## Description

The contact type can set the action direction of contact output assigned to the function.

## Setting Details

Contact Output Equipped as Standard

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :---: | :---: |
| AL1.D | AL1 contact type | PRO | 0: When the event of assigned <br> function occurs, the contact <br> output is closed. | ALM Set |
| AL2.D | AL2 contact type | PRO | 1: When the event of assigned <br> function occurs, the contact <br> output is opened. |  |

Note1: Nothing is displayed on Group display when each parameter is displayed.

Terminal arrangement: 17.4 Wiring

### 13.1 Setting Display Functions

### 13.1.1 Setting Active Color PV Display Function

The active color PV display function changes the PV display color when an event occurs.

## Description

## Link to Alarm

The PV display color changes by linking to the alarm 1 or alarm 2.
The following is an example of operation linking to alarm 1.
Set the alarm-1 type to "PV high limit alarm" and alarm-1 setpoint to " $80^{\circ} \mathrm{C}$."
When the active color PV display switch is set to"2," PV display color changes from white to red if PV exceeds the alarm-1 setpoint.
The red-to-white switching action can be set.


## Change by Deviation

The PV display color changes by deviation (PV - SP).

Set the PV color change high limit to " $10^{\circ} \mathrm{C}$ " and the PV color change low limit to " $5^{\circ} \mathrm{C}$ " as deviation band for the current target setpoint " $50^{\circ} \mathrm{C}$." PV display color changes from white to red if PV is out of the deviation.
The red-to-white switching action can be set. There is no hysteresis.


## Link to PV

The PV display color changes by linking to PV.
Set the PV color change high limit to " $70^{\circ} \mathrm{C}$ " and the PV color change low limit to " $20^{\circ} \mathrm{C}$." PV display color changes from white to red if PV is out of the range.
The red-to-white switching action can be set. There is no hysteresis.


## Use in Fixed Color

PV display color can be fixed in red. It can also be fixed in white.


## Setting Details

$\left.$| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :--- | :--- | :--- |
|  |  |  | 0: Fixed in white <br> 1: Fixed in red <br> 2: Link to alarm 1 (Alarm OFF: <br> white, Alarm ON: red) <br> 3: Link to alarm 1 (Alarm OFF: <br> red, Alarm ON: white) <br> 4: Link to alarm 1 or 2 (Alarm <br> OFF: white, Alarm ON: red) |  |
| PCMD | Active color PV <br> display switch | EASY | 5: Link to alarm 1 or 2 (Alarm <br> OFF: red, Alarm ON: white) <br> 6: PV limit (Within range: white, <br> Out of range: red) <br> 7: PV limit (Within range: red, Out <br> of range: white) <br> 8: SP deviation (Within deviation: <br> white, Out of deviation: red) | DISP Set |
| 9: SP deviation (Within deviation: |  |  |  |  |
| red, Out of deviation: white) |  |  |  |  |$\quad \right\rvert\,$

### 13.1.2 Masking Arbitrary Display Value in Operation Display

## Description

Display/non-display of the PV display, Setpoint display, and Status display in the Operation Display can be set.
Items that you do not want to display can be set to non-display. For example, when the Setpoint display is set to non-display, SP of the SP Display and OUT of the OUT Display are not displayed.
When an error at power-on or hardware malfunction error occurs, Operation display cannot be set to non-display.


Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :---: | :---: |
| PV.D | PV display area ON/ <br> OFF | PRO |  |  |
| SP.D | Setpoint display area <br> ON/OFF | PRO | OFF: Nondisplay <br> ON: Display | DISP Set |
| STS.D | Status display area <br> ON/OFF | PRO |  |  |

### 13.1.3 Registering SELECT Display (Up to 5 Displays)

## Description

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :---: |
| CS1 to CS5 | SELECT Display-1 to <br> -5 registration | STD | OFF: No registration D register <br> number (2301 to 5000) | CSEL Set |

For D register numbers, see sections 8.4.2 and 8.4.5 in the UTAdvanced Series Communication Interface User's Manual.

| D Resistor <br> Number | Category | Reference in <br> Communication <br> Interface |
| :---: | :--- | :--- | :--- |
| User's Manual |  |  |$|$| Description |
| :---: |

### 13.1.4 Changing Event Display

## Description

The UT32A has four event (EV) lamps.
The alarms 1 to 4 are assigned to EV1 to EV4.

## Setting Details

| Parameter symbol | Name | Display level | Setting range | Menu symbol |
| :---: | :---: | :---: | :---: | :---: |
| EV1 to EV4 | EV1 to EV4 display condition registration | PRO | Setting range: 4001 to 6304 <br> OFF: Disable <br> 4321: Link to alarm 1 (Lit when the alarm occurs) <br> 4322: Link to alarm 2 (Lit when the alarm occurs) <br> 4323: Link to alarm 3 (Lit when the alarm occurs) <br> 4325: Link to alarm 4 (Lit when the alarm occurs) <br> 5153 to 5154: Link to AL1-AL2 (Lit when the contact is closed) <br> For other functions, see the UTAdvanced Series Communication Interface User's Manual. | $\begin{gathered} \text { DISP } \\ \text { Set } \end{gathered}$ |


| Relay <br> Number | Description <br> Communication Interface <br> User's Manual |  |
| :--- | :--- | :--- |
| 4001 to 4064 | System error |  |
| 4065 to 4128 | Input error |  |
| 4129 to 4192 | Free area |  |
| 4193 to 4256 | Operation mode |  |
| 4257 to 4320 | Free area |  |
| 4321 to 4384 | Alarm |  |
| 4385 to 4528 | Alarm latch |  |
| 4577 to 4640 | SP number and PID number |  |
| 4641 to 4704 | Free area |  |
| 4705 to 4768 | Key |  |
| 4769 to 4832 | Display |  |
| 4833 to 5024 | Free area |  |
| 5025 to 5152 | Input relay |  |
| 5153 to 5280 | Output relay |  |
| 5281 to 5408 | Control computation output |  |
| 5409 to 5472 | Special relay |  |
| 5473 to 5536 | Free area |  |
| 5537 to 5792 | Internal relay |  |
| 5793 to 6048 | Free area |  |
| 6433 to 6560 | DO terminals |  |

### 13.1.5 Registering SELECT Parameter Display (Up to 10 Displays)

## Description

Registering frequently changed operation parameters (change frequency is lower than SELECT Display) in the SELECT Parameter Display will allow you to change parameter settings easily. A maximum of ten Displays can be registered.
Set the D register number of the parameter you wish to register for the registration to the SELECT Parameter Display.
However, the parameters in the following menus cannot be set:
CTL, PV, MPV, OUT, R485, KEY, DISP, CSEL, KLOC, MLOC, ALM, I/O, SYS, INIT, VER, and LVL.
When each parameter is displayed, the terminal area (E1) is displayed on Group display according to the suffix code.


## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :---: | :---: |
| CS10 to <br> CS19 | SELECT parameter-10 <br> to -19 registration | PRO | OFF: No registration <br> D register number (2301 to <br> 5000) | CSEL Set |

For D register numbers, see sections 8.4.2 and 8.4.5 of UTAdvanced Series Communication Interface User's Manual.

| D Resistor Number | Category | Description | Reference in Communication Interface User's Manual |
| :---: | :---: | :---: | :---: |
| 2301 to 2500 | Operation Mode Parameters | Operation Mode | Section 8.4.2 |
| 2501 to 2700 | Operation Parameters | SPs and alarm setpoints setting | Section 8.4.3 |
| 2701 to 2800 |  | SP-related settings |  |
| 2801 to 2900 |  | Alarm function settings |  |
| 2901 to 3000 |  | PV-related settings |  |
| 3001 to 3500 |  | PID settings |  |
| 3501 to 3600 |  | Control action-related settings |  |

### 13.1.6 Setting Bar-graph Display Function

## Description

The bar-graph display is provided on the front of the controller.
PV or OUT can be displayed. Data which can be displayed on Bar-graph display are as follows.

## OUT, Output



For relay, OFF is equivalent to $0 \%$ and ON is equivalent to $100 \%$.
PV, SP


## Deviation

When the deviation display band (BDV) is 10\%:


Deviation negative side and deviation positive side are displayed by $10 \%$ increment of deviation. Indication is unlit when SP - (deviation display band (BDV)) $\leq P V \leq S P+($ deviation display band (BDV)).

IN = TC Type K -270.0 to $1370.0^{\circ} \mathrm{C}$
$B D V=82^{\circ} \mathrm{C}(5 \%), S P=500.0^{\circ} \mathrm{C}, \mathrm{PV}=800.0^{\circ} \mathrm{C}$

746.1 to $828.0^{\circ} \mathrm{C}$
664.1 to $746.0^{\circ} \mathrm{C}$
582.1 to $664.0^{\circ} \mathrm{C}$
-356.0 to $417.9^{\circ} \mathrm{C}$
254.0 to $355.9^{\circ} \mathrm{C}$
172.0 to $253.9^{\circ} \mathrm{C}$
90.0 to $171.9^{\circ} \mathrm{C}$
8.0 to $89.9^{\circ} \mathrm{C}$
to $7.9^{\circ} \mathrm{C}$
All indications are unlit when the deviation is $418 \leq \mathrm{PV} \leq 582^{\circ} \mathrm{C}$.

## Setting Details

| Parameter symbol | Name | Display level | Setting range | Menu symbol |
| :---: | :---: | :---: | :---: | :---: |
| BAR1 | Bar-graph display registration | STD | ```0: Disable 1:OUT 3: PV 4: SP 5: Deviation 6 to 16: Disable 18: PV terminals analog input 27: TSP 28: Deviation between the TSP``` | DISP Set |
| BDV | Bar-graph deviation display band | STD | 0.0 to 100.0\% of PV input range span (EUS) |  |

Note1: The bar-graph deviation display band (BDV) is enabled when the deviation is set to the BAR1.

### 13.1.7 Masking Least Significant Digit of PV Display

## Description

Setting Details
With and without least significant digit of the PV in the Operation Display can be set.
When without least significant digit is set, the value of the least significant digit is truncated and not displayed.
The internal value is not changed depending on whether with or without least significant digit (the value is for display only). This parameter does not function for the PV without decimal point.
$\begin{array}{lr}\text { Least significant digit } & \text { Least significant digit } \\ \text { is displayed. } & \text { is not displayed. }\end{array}$



The following shows the example of with and without least significant digit

| PV display |  |  |
| :---: | :---: | :---: |
| With least significant digit | Without least significant digit |  |
|  | Truncated | Not displayed |
| 1.4999 | 1.499 | 1500 |
| 1.5000 | 1.500 | 1500 |
| 1.9999 | 1.999 | 2000 |
| 2.0000 | 2.000 | 2000 |
| 3000.0 | 3000 | 3000 |
| 3000.9 | 3000 | 3001 |
| 3001.0 | 3001 | 3001 |

### 13.1.8 Setting Economy Mode

## Description

The LCD backlight ON/OFF can be set in the following methods.
Setting the LCD backlight to OFF saves energy.

## User Function Keys

The LCD backlight ON/OFF switch can be assigned to the user function key.

- User function key: 13.2 Assigning Function to User Function Key and A/M Key


## Backlight OFF timer

The backlight OFF timer sets the economy mode parameter to ON.
If no keys are pressed for 30 minutes, the LCD backlight goes off automatically.
The backlight OFF can be set to turn off the backlight for the whole display or a display other than the PV display.
To turn on the LCD backlight, press any key.
In the following cases, the LCD backlight does not go off.

- when an alarm occurs
- When an error at power-on or a hardware malfunction error occurs


## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :--- | :--- |
| ECO | Economy mode | STD | OFF: Disable <br> 1: Economy mode ON (All <br> indications except PV display <br> OFF) <br> 2: Economy mode ON (All <br> indications OFF) <br> 3: Brightness 10\% (all indications) | DISP Set |

### 13.1.9 Selecting the Initial Operation Display that Appears at Power ON

## Description

The initial Operation Display that appears when the power is turned on can be set.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :--- | :--- | :--- |
| HOME | Home Operation <br> Display setting | PRO | SP1: SP Display <br> OUT1: OUT Display <br> PID1: PID Number Display <br> PV: PV Analog Input Display <br> CS1 to CS5: SELECT Display 1 to 5 <br> PVO: PV Display | DISP Set |

### 13.1.10 Switching Guide Display Language

## Description

The guide display language that appears when the parameter or the menu is displayed can be switched.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| LANG | Guide display <br> language | ENG: English <br> FRA: French <br> GER: German <br> SPA: Spanish | SYS Set |  |

### 13.1.11 Changing Guide Scroll Speed

## Description

The scroll speed can be changed when the guide for the parameter or menu is displayed.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :---: | :--- |
| SPD | Scroll speed | PRO | (Slow) 1 to 8 (Quick) | DISP Set |

### 13.1.12 Turning Guide Display ON/OFF

## Description

The guide display that appears when the parameter or the menu is displayed can be switched.
The guide display can be turned on and off by the Fn key in the Menu Display and Parameter Setting Display.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :---: | :---: |
| GUID | Guide display ON/OFF | STD | OFF: Nondisplay <br> ON: Display | DISP Set |

### 13.1.13 Setting Automatic Return to Operation Display

## Description

The Display will automatically revert to the Operation Display if no keys are pressed for 5 minutes in Menu Display or Parameter Setting Display.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :---: | :---: |
| OP.JP | Automatic return to <br> Operation Display | PRO | ON: Automatically returned to <br> the Operation Display. <br> OFF: Not automatically <br> returned to the Operation <br> Display. | DISP Set |

### 13.1.14 Setting Brightness and Contrast Adjustment of LCD and Display Update Cycle

## Description

The brightness and contrast for PV, Setpoint, Bar-graph, and Status indicator can be adjusted.
Brightness ranges for each display can be set.
The LCD has a characteristic that the display action becomes late at the low temperature.
This can be solved by adjusting the display update cycle (D.CYC).

Setting Details

| Parameter symbol | Name | Display level | Setting range | Menu symbol |
| :---: | :---: | :---: | :---: | :---: |
| BRI | Brightness | EASY | (Dark) 1 to 5 (Bright) | DISP Set |
| B.PVW | White brightness adjustment of PV display | PRO | Adjusts the white brightness of PV display. <br> (Dark) -4 to 4 (Bright) |  |
| B.PVR | Red brightness adjustment of PV display | PRO | Adjusts the red brightness of PV display. <br> (Dark) -4 to 4 (Bright) |  |
| B.SP | Brightness adjustment of Setpoint display | PRO | Adjusts the brightness of SP display. <br> (Dark) -4 to 4 (Bright) |  |
| B.BAR | Brightness adjustment of Bar-graph display | PRO | Adjusts the brightness of SP display. $\text { (Dark) }-4 \text { to } 4 \text { (Bright) }$ |  |
| B.STS | Brightness adjustment of Status indicator | PRO | Adjusts the brightness of Status indicator. <br> (Dark) -4 to 4 (Bright) |  |
| D.CYC | Display update cycle | PRO | $\begin{aligned} & \text { 1: } 100 \mathrm{~ms} \\ & \text { 2: } 200 \mathrm{~ms} \\ & \text { 3: } 500 \mathrm{~ms} \\ & \text { 4: } 1 \mathrm{~s} \\ & \text { 5: } 2 \mathrm{~s} \end{aligned}$ |  |

### 13.2 Assigning Function to User Function Key and A/M Key

Description
The UT32A has one user function key on the front panel.
Various functions (operation mode switch etc.) can be assigned to the user function key. Press the user function key to perform the assigned function.
The User function key is available only on the Operation Display.
The assigned function does not work on the Parameter Setting Display. However, the Fn key can be used to turn on/off the guide display.


## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :---: | :---: |
| Fn | User function key action setting | EASY | See the table <br> below | KEY Set |
| A/M | A/M key action setting | PRO |  |  |


| Setpoint | Function | Action | Availability (Note 1) |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | F1 | F2 | Fn | A/M |
| OFF | Unassigned | - | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| A/M | AUTO/MAN switch | AUTO and MAN switches every time the user function key is pressed. | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark \sqrt{V}$ |
| R/L1 | REM/LCL switch | Remote and Local switches every time the user function key is pressed. <br> (Displayed only in cases where the communication is specified.) | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| S/R | STOP/RUN switch | STOP and START switches every time the user function key is pressed. | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\sqrt{ }$ |
| AUTO | Switch to AUTO | Pressing the user function key switches to AUTO. | $\checkmark$ | $\checkmark$ | $\sqrt{ }$ | $\sqrt{ }$ |
| MAN | Switch to MAN | Pressing the user function key switches to MAN. | $\checkmark$ | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| REM1 | Switch to REM | Pressing the user function key switches to Remote. (Displayed only in cases where the communication is specified.) | $\checkmark$ | $\checkmark$ | $\checkmark$ | - |
| LCL1 | Switch to LCL | Pressing the user function key switches to Local. (Displayed only in cases where the communication is specified.) | $\checkmark$ | $\checkmark$ | $\checkmark$ | - |
| STOP | Switch to STOP | Pressing the user function key stops the operation. | $\checkmark$ | $\checkmark$ | $\checkmark$ | - |
| RUN | Switch to RUN | Pressing the user function key starts the operation. | $\checkmark$ | $\checkmark$ | $\checkmark$ | - |
| AT | Auto-tuning | Pressing the user function key executes autotuning | $\checkmark$ | $\checkmark$ | $\checkmark$ | - |
| LTUP | LCD brightness UP | The current brightness gradually increases every time the function key is pressed. | $\checkmark$ | $\checkmark$ | $\checkmark$ | - |
| LTDN | LCD brightness DOWN | The current brightness gradually decreases every time the function key is pressed. | $\checkmark$ | $\checkmark$ | $\checkmark$ | - |
| BRI | Adjust LCD brightness | The current brightness gradually increases every time the function key is pressed. <br> Pressing the function key after reaching the maximum brightness changes to the minimum brightness. <br> Thereafter, minimum brightness $\rightarrow$ maximum brightness $\rightarrow$ maximum brightness is repeated. | $\checkmark$ | $\checkmark$ | $\checkmark$ | - |
| LCD | LCD Backlight ON/OFF switch | The LCD backlight turns on and off every time the user function key is pressed. | $\checkmark$ | $\checkmark$ | $\checkmark$ | - |
| LAT | Latch release | Latch 1 to latch 4 are released every time the user function key is pressed. | $\checkmark$ | $\checkmark$ | $\checkmark$ | - |
| PID | PID Tuning switch | Pressing the function key during operation displays the first parameter (proportional band) of the currently selected PID parameter group and enables the setting to be changed. <br> As with the operation to change the parameter setpoint, the sequence is $\mathrm{P} \rightarrow \mathrm{l} \rightarrow \mathrm{D} \rightarrow \ldots \rightarrow \mathrm{P} \rightarrow \ldots$. Pressing the function key again, or pressing the DISP key returns to the initial Operation Display. The PARA key does not switch to the Menu Display. | $\checkmark$ | $\checkmark$ | $\sqrt{ } \mathrm{V}$ | - |

Note 1: $\sqrt{ }$ indicates available, - indicates unavailable, and $\sqrt{ }$ indicates initial value.

## Status of user function key

The status of the user function key can be identified by communication.
" 1 " can be read while the user function key is held down, and " 0 " can be read when the user function key is released. (Initial value: 0)

- Reading via communication: UTAdvanced Series Communication Interface User's Manual


## Fn key operation in the Parameter Setting Display

In the Menu Display and Parameter Setting Display, the guide is displayed on PV display. At this time, use the Fn key to turn on and off the guide display on PV display. A measured input value (PV) is displayed in the ON state.

## 13．3 Setting Security Functions

## 13．3．1 Setting／canceling a Password

## Description

The password function can prevent inadvertent changes to the parameter settings． If a password is set，the checking is required when moving to the Setup Parameter Setting Display．When the password is verified，can be changed to the Setup Parameter Setting Display．The parameters in the following menus can be set only when the password is verified．
CTL，PV，MPV，OUT，R485，KEY，DISP，CSEL，KLOC，MLOC，ALM，I／O，SYS，INIT，VER， and LVL．
When each parameter is displayed，the terminal area（E1）is displayed on Group display according to the suffix code．

Always remember your password when using the password function． パスワードを解除する場合は，パラメータPASSに「0」を設定することによりパスワード が解除されます。

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :---: | :---: |
| PASS | Password setting | EASY | 0 （No password）to 65535 | SYS Set |

## 13．3．2 Setting Parameter Display Level

## Description

Parameter display level can be set according to the setting level．
－Parameter display level：Chapter 18 Parameters

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :---: | :---: |
| LEVL | Parameter display <br> level | EASY | EASY：Easy setting mode <br> STD：Standard setting mode <br> PRO：Professional setting mode | LVL Set |

### 13.3.3 Locking (Hiding) Parameter Menu Display

## Description

The parameter menu display lock function hides the following Parameter Menu Displays.

## Setting Details

| Parameter symbol | Name | Display level | Setting range | Menu symbol |
| :---: | :---: | :---: | :---: | :---: |
| CTL | [CTL] menu lock | PRO | OFF: Display ON: Nondisplay | MLOC Set |
| PV | [PV] menu lock | PRO |  |  |
| MPV | [MPV] menu lock | PRO |  |  |
| OUT | [OUT] menu lock | PRO |  |  |
| R485 | [R485] menu lock | PRO |  |  |
| KEY | [KEY] menu lock | PRO |  |  |
| DISP | [DISP] menu lock | PRO |  |  |
| CSEL | [CSEL] menu lock | PRO |  |  |
| KLOC | [KLOC] menu lock | PRO |  |  |
| ALM | [ALM] menu lock | PRO |  |  |
| DO | [DO] menu lock | PRO |  |  |
| I/O | [I/O] menu lock | PRO |  |  |
| SYS | [SYS] menu lock | PRO |  |  |
| INIT | [INIT] menu lock | PRO |  |  |
| VER | [VER] menu lock | PRO |  |  |
| LVL | [LVL] menu lock | PRO |  |  |
| MODE | [MODE] menu lock | PRO | OFF: Display ON: Nondisplay | MLOC Set |
| CS | [CS] menu lock | PRO |  |  |
| SP | [SP] menu lock | PRO |  |  |
| SPS | [SPS] menu lock | PRO |  |  |
| ALRM | [ALRM] menu lock | PRO |  |  |
| PVS | [PVS] menu lock | PRO |  |  |
| PID | [PID] menu lock | PRO |  |  |
| TUNE | [TUNE] menu lock | PRO |  |  |
| ZONE | [ZONE] menu lock | PRO |  |  |

Note1: When each parameter is displayed, the terminal area (E1) is displayed on Group display according to the suffix code and optional suffix code.

### 13.3.4 Key Lock

## Description

The key lock function locks the key on the front panel to prohibit key operation. It can prohibit the operation mode switch or parameter setting change.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| DATA | Front panel parameter data <br> key lock | STD | OFF: Unlock | KLOCK Set |
| A/M | Front panel A/M key lock | STD | ON: Lock |  |

### 13.3.5 Setting Display/Non-display of Operation Display

## Description

Display/non-display of the Operation Display can be set.

- Operation Display: Chapter 6 Monitoring and Control of Regular Operations


## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :---: | :---: |
| U.SP | SP Display lock | PRO |  |  |
| U.OUT | OUT Display lock | PRO |  |  |
| U.PID | PID Number Display lock | PRO |  | KLOC Set |
| U.PV | PV Analog Input Display lock | PRO |  |  |
| U.PVO | PV Display lock | PRO |  |  |

### 13.3.6 Prohibiting Writing via Communication

## Description

Writing data to each register via all communication methods can be permitted or prohibited. However, writing data via light-loader (front) or maintenance port (upper) is possible using LL50A Parameter Setting Software.

Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| COM.W | Communication write enable/ <br> disable | STD | OFF: Enable <br> ON: Disable | KLOC Set |

Displayed only in cases where the communication is specified.

### 13.4 Confirmation of Key and I/O Condition and Version

### 13.4.1 Confirmation of Key and I/O Condition

## Description

Can be confirm the Key and I/O condition.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| KEY | Key status | PRO | Read only. | I/O Set |
| Y000 | AL1-AL3 status (equipped as standard) | PRO |  |  |

Note: When each parameter is displayed, the terminal area (E1) is displayed on Group display according to the suffix code.

Key confirmation parameters are displayed in hexadecimal.
When the error occurs, " 1 " is set on the bit of corresponding error, and the bit data is displayed in hexadecimal.


Parameter Y000

| Displayed digit | bit | Description |
| :---: | :---: | :---: |
| 1st digit | 0 | AL1 status (0: OFF, 1: ON) |
|  | 1 | AL2 status (0: OFF, 1: ON) |
|  | 2 | - |
|  | 3 | - |
| 2nd digit | 4 | - |
|  | 5 | - |
|  | 6 | - |
|  | 7 | - |
| 3rd digit | 8 | - |
|  | 9 | - |
|  | 10 | - |
|  | 11 | - |
| 4th digit | 12 | - |
|  | 13 | - |
|  | 14 | - |
|  | 15 | - |

### 13.4.2 Confirmation of Version

## Description

Can be confirm the version of the controller.

## Setting Details

| Parameter symbol | Name | Display level | Setting range | Menu symbol |
| :---: | :---: | :---: | :---: | :---: |
| MCU | MCU version | EASY | Read only. | VER Set |
| DCU | DCU version | EASY |  |  |
| ECU1 | ECU-1 version | EASY |  |  |
| PARA | Parameter version | EASY |  |  |
| H.VER | Product version | EASY |  |  |
| SER1 | Serial number 1 | EASY |  |  |
| SER2 | Serial number 2 | EASY |  |  |

### 14.1 Initializing Parameter Settings to Factory Default Values

## Description

Parameter settings can be initialized to the factory default values.
The ladder program is also initialized to the factory default.
Use the key or LL50A Parameter Setting Software to execute it.

## Note

The user setting values (defaults) are not initialized even if the parameter setting values are initialized to the factory default values

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :---: | :---: |
| F.DEF | Initialization to factory <br> default value | PRO | -12345 : Initialization, <br> automatically returned to "0" <br> after initialization. | INIT Set |

### 14.2 Registering and Initializing User Default Values

### 14.2.1 Registering as User Setting (Default) Values

## Description

The user default values can be registered as parameter default values.
The ladder program can not be registered as user default values.
Use the LL50A Parameter Setting Software to register user setting (default) values.

## CAUTION

Before registering the user default value, make sure that the user setting value is set to the parameter.

### 14.2.2 Initializing to User Setting (Default) Values

## Description

Parameter settings can be initialized to the user setting (default) values.
The ladder program is not initialized to the factory default.
Use the LL50A Parameter Setting Software to execute it.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :--- | :---: | :--- | :--- |
| U.DEF | Initialization to user <br> default value | PRO | 12345: Initialization, <br> automatically returned to "0" <br> after initialization. | INIT Set |

### 15.1 Remedies if Power Failure Occurs during Operations

## Description

The operation status and remedies after a power failure differ with the length of power failure time:
Regardless of the length of power failure time, all functions of the controller cannot be operated for about 10 seconds after recovery. However, the case of instantaneous power failure is excepted.

- 100-240 V AC: Instantaneous power failure of 20 ms or less
- 24 V AC/DC: Instantaneous power failure of 1 ms

A power failure is not detected. Normal operation continues.

- Power failure of about less than 5 seconds

The following shows effects caused in "settings" and "operation status."

| Alarm action | Does not continue. Alarm with stand-by function will enter stand-by status. <br> Alarm latch will be initialized. |
| :--- | :--- |
| Setting parameter | Set contents of each parameter are retained. |
| Auto-tuning | Cancelled. |
| Control action | Action before power failure continues. |
| Timer, counter (ladder <br> program) | Initialized. |

- Power failure of about 5 seconds or more

The following shows effects caused in "settings" and "operation status."

| Alarm action | Does not continue. Alarm with stand-by function will enter stand-by status. <br> Alarm latch will be initialized. |  |
| :--- | :--- | :--- |
| Setting parameter | Set contents of each parameter are retained. |  |
| Auto-tuning | Cancelled. |  |
|  | Differs with setting of the parameter "R.MD" (restart mode). <br> Control action | R.MD setting Control action after recovery from power failure <br> CONT Continues action before power failure. (Factory default) <br> MAN (*) Outputs the preset output value (PO) of the PID group <br> used as control output and continues action in MAN <br> mode. <br> AUTO (*) The control computation is executed in AUTO mode <br> based on the preset output value (PO) of the PID group <br> used as control output. |

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :---: | :---: |
| R.MD | Restart mode | STD | CONT: Continue action set before <br> power failure. <br> MAN: Start from MAN. <br> AUTO: Start from AUTO. | SYS Set |

### 15.2 Power Frequency Setting

## Description

The power frequency can be set by automatic detection or manually.
However, when the /DC option is specified, only manual setting is available. Set the range to the commercial frequency of the installation location.

## Setting Details

| Parameter <br> symbol | Name | Display <br> level | Setting range | Menu symbol |
| :--- | :---: | :---: | :--- | :--- |
| FREQ | Power frequency | EASY | AUTO <br> $60: 60 \mathrm{~Hz}$ <br> $50: 50 \mathrm{~Hz}$ | SYS Set |

### 16.1 Troubleshooting

### 16.1.1 Troubleshooting Flowchart

If the Operation Display does not appear after turning on the controller's power, follow the measures in the procedure below.
If a problem appears complicated, contact our sales representative.

*: The LCD (a liquid crystal display) is used for a display portion of this product. The LCD has a characteristic that the display action becomes late at the low temperature. Additionally, the luminance and contrast degradation are caused due to aged deterioration. However, the control function is not affected.

### 16.1.2 Errors at Power On

The errors shown below may occur in the fault diagnosis when the power is turned on.

| PV display <br> (Operation <br> Display) | Setpint display (Operation Display) | Status indicator (Operation Display) | Parameter <br> that displays <br> error details | Error description | Cause and diagnosis | Remedy |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Indication off | Indication off | - | - | Faulty MCU RAM / MCU ROM | MCU RAM / MCU ROM are failed. | Faulty. <br> Contact us for repair. |
| ERR | SYS ----- |  | - | System data error | System data is corrupted. | Faulty. Contact us for repair. |
|  | PAR 0004 (for user default value error only) |  | Setup parameter (PA.ER) | User (parameter) default value error | User parameter is corrupted. Initialized to factory default value. | Check and reconfigure the initialized parameters. <br> Error indication is erased when the power is turned on again. |
|  | PAR 0010 (for setup parameter error only) |  |  | Setup parameter error | Setup parameter data is corrupted. Initialized to factory default value. |  |
|  | PAR 0020 (for operation parameter error only) |  |  | Operation parameter error | Operation parameter data is corrupted. Initialized to user default value. |  |
|  | PAR 0400 |  |  | Control parameter (operation mode, output) error | Control parameter data is corrupted. Initialized to user default value. |  |
|  | SLOT 0001 (0001: Error occurs to all hardware of E1 -terminal areas.) |  | Setup parameter (OP.ER) | Non responding hardware of extended function (E1terminal areas) | Inconsistence of system data and hardware of extended function. <br> Non responding communication between hardware of extended function (E1 -terminal areas). | Faulty. Contact us for repair. |
| Normal indication | Normal indication | Rightmost decimal point on PV display blinks. | Setup parameter (PA.ER) | Calibration value error | Initialized to calibrated default value because of corrupted factory default value. | Faulty. <br> Contact us for repair. |
|  |  | Right most decimal point on Symbol display blinks. |  | Faulty FRAM | Writing (storing) data to FRAM is impossible. |  |


| Error description | PV input | Ladder calculation | Control computation | Control output | Retransmission output | Alarm action | Analog output (control output, retransmission output) | Voltage pulse output (control output) | Relay output (control output) | Contact (alarm) output | $\begin{gathered} \text { Communi- } \\ \text { cation } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Faulty MCU RAM <br> Faulty MCU ROM | Undefined | Stopped | Stopped | Undefined | Undefined | Stopped | 0\% or less | OFF | OFF | OFF | Stopped |
| System data error | Undefined | Stopped | Stopped | Undefined | Undefined | Stopped | 0\% or less | OFF | OFF | OFF | Normal action |
| User (parameter) default value error |  |  |  |  |  |  |  |  |  |  |  |
| Setup parameter error | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action |
| Operation parameter error Control parameter error |  |  |  |  |  |  |  |  |  |  |  |
| Non responding hardware of extended function (E1 -terminal areas) | Undefined | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action |
| Calibration value error | Normal action (out of accuracy) | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action (out of accuracy) | Normal action | Normal action | Normal action | Normal action |
| Faulty FRAM | Normal action |  |  |  |  |  | Normal action |  |  |  |  |

### 16.1.3 Errors during Operation

## Errors during Operation (1)

The errors shown below may occur during operation.

| PV display (Operation Display) | Setpoint display (Operation Display) | Status indicator (Operation Display) | Parameter that displays error details | Error description | Cause and diagnosis | Remedy |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| AD.ERR | Normal indication (Note) | - | Setup parameter (AD1.E) | Analog input terminal ADC error <br> - PV input | Analog input terminal AD value error | Faulty Contact us for repair. |
| RJC.E (Displays RJC.E and PV alternately.) | Normal indication (Note) | - | Setup parameter (AD1.E) | Universal input terminal RJC error <br> - PV input | Universal input terminal RJC error | Faulty <br> Contact us for repair. <br> Set the parameter RJC to OFF to erase error indication. |
|  | Normal |  | Setup parameter (AD1.E) | Analog input terminal burnout error <br> - PV input | Analog input terminal sensor burnout | Check wiring and sensor. Error indication is erased in normal operation. |
| B.OUT | indication <br> (Note) | - | Setup parameter (PV1.E) | PV input burnout error | Burnout of analog input connected to PV | Check wiring and sensor of connected analog input terminal. <br> Error indication is erased in normal operation. |
| $\begin{aligned} & \text { OVER } \\ & \text {-OVER } \end{aligned}$ | Normal indication | - | Setup parameter (PV1.E) | PV input over-scale PV input under-scale (PV values out of -5 to $105 \%$ ) | PV input is out of -5 to $105 \%$. Also occurs when the data out of range which is the ladder computation result is input. | Check analog input value or ladder program. |

Note: When an error occurs in input shown in Analog input display (Operation display).
Setpoint display shows the same symbol as the PV display.

| Error description | PV input | Ladder calculation | Control computation | Control output | Retransmission output | Alarm action | Analog output (control output, retransmission output) | Voltage pulse output (control output) | Relay output (control output) | Contact (alarm) output | Com-munication |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Analog input terminal ADC error <br> - PV input | 105\% | Normal action | Normal action | When in AUTO and RUN modes: Error preset output When in MAN mode: MAN output | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action |
| Universal input terminal RJC error <br> - PV input | Normal action (without reference junction compensation) | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action |
| Analog input terminal burnout error <br> - PV input | Depends on the parameter BSL. Upscale: 105\% Downscale: -5\% |  |  | When in AUTO and RUN modes: |  |  |  |  |  |  |  |
| PV input burnout error | Depends on the setting of the parameter BSL. Upscale: 105\% Downscale: -5\% | Normal action | Normal action | preset <br> output <br> When <br> in MAN <br> mode: <br> MAN <br> output | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action |
| PV input over-scale <br> PV input under-scale <br> (PV values out of -5 to 105\%) | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action |

## Errors during Operation (2

The errors shown below may occur during operation.

| PV display (Operation Display) | Setpoint display (Operation Display) | Status indicator (Operation Display) | Parameter <br> that <br> displays error <br> details | Error description | Cause and diagnosis | Remedy |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| AT,E | Normal indication | - | Setup parameter (PV1.E) | Auto-tuning time-out | Auto-tuning does not end even when 24 hours have elapsed after the start of tuning. | Check the process. Hold down any key to erase the error indication |
| Normal indication | 0.00000000 (Decimal point on the left of the Symbol display blinks) | - | Setup parameter (OP.ER) | Communication error (RS-485 communication) | Framing parity error <br> Buffer overflow <br> Inter-character time-out <br> Checksum error (PC link communication with checksum) <br> CRC check error (Modbus/RTU) <br> LRC check error (Modbus/ASCII) | Check the communication parameters. Recovery at normal receipt. Hold down any key to stop blinking. |
| Normal indication | 0.00000000 (Decimal point on the left of the Symbol display blinks) | - | Setup parameter (OP.ER) | Communication error (coordinated operation) | Inconsistence of loop between coordinated master and slaves <br> Communication from coordinated master is interrupted for 2 seconds. | Check the communication parameters. <br> Recovery at normal receipt. <br> Change from remote to local mode to stop blinking. <br> When the mode is changed from remote to local, SP tracking does not work even if it is set to ON. |
| Normal indication | Normal indication | Rightmost decimal point on Symbol display blinks. | Setup parameter (PA.ER) | Faulty FRAM | Writing (storing) data to FRAM is impossible. | Faulty. Contact us for repair. |


| Error description | PV input | Ladder calculation | Control computation | Control output | Retransmission output | Alarm action | Analog output (control output, retransmission output) | Voltage pulse output (control output) | Relay output (control output) | Contact (alarm) output | $\begin{gathered} \text { Com- } \\ \text { munica- } \\ \text { tion } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Auto-tuning time-out | Normal action | Normal action | Autotuning stopped, normal action | Autotuning stopped, Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action |
| Communication error (RS485 communication) | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action |
| Communication error (coordinated operation) Inconsistence of loop between coordinated master and slaves | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action |
| Communication error (coordinated operation) Communication from coordinated master is interrupted for 2 seconds. | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action |
| Faulty FRAM | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action | Normal action |


| Errors during Operation (3) |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| The errors shown below may occur during operation. |  |  |  |  |  |  |
| PV display (Operation Display) | Data display (Operation Display) | Status indicator (Operation Display) | Parameter that displays error details | Error description | Cause and diagnosis | Remedy |
| Undefined | Undefined | - | - | Faulty MCU | MCU is corrupted. | Faulty Contact us for repair. |
| Undefined | Undefined | - | - | Faulty DCU (ROM/RAM error, corrupted) | DCU is corrupted. | Faulty Contact us for repair. |


| Error description | PV input | Ladder calculation | Control computation | Control output | Retransmission output | Alarm action | Analog output (control output, retransmission output) | Voltage pulse output (control output) | Relay output (control output) | Contact (alarm) output | Com-municatio |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Faulty MCU | Undefined | Stopped | Stopped | Undefined | Undefined | Stopped | 0\% or less | OFF | OFF | OFF | Stopped |
| Faulty DCU (ROM/RAM error, corrupted) | Undefined | Stopped | Stopped | Undefined | Undefined | Stopped | 0\% or less | OFF | OFF | OFF | Stopped |

## Hexadecimal Display on Setpoint Display (Operation Display)

Some error codes are displayed in hexadecimal.
When the error occurs, " 1 " is set on the bit of corresponding error, and the bit data is displayed in hexadecimal.

If the setup parameter error or the operation parameter errors occur, it is displayed as follows:


| Displayed digit | bit |  |
| :--- | :---: | :--- |
| 1st digit | 0 | System data error |
|  | 1 | Calibration value error |
|  | 2 | User (parameter) default value error |
|  | 3 | - |
| 2nd digit | 4 | Setup parameter error |
|  | 5 | Operation parameter error |
|  | 6 | - |
|  | 7 | - |
| 3th digit | 8 | Faulty FRAM |
|  | 9 | - |
|  | 10 | Control parameter error |
|  | 11 | - |

If the hardware in E1-terminal area does not respond, it is displayed as follows:


| Displayed digit | bit | Description |
| :---: | :---: | :---: |
| 1st digit | 0 | Non responding hardware in E1-terminal area |
|  | 1 | - |
|  | 2 | - |
|  | 3 | - |
| 2nd digit | 4 | - |
|  | 5 | - |
|  | 6 | - |
|  | 7 | - |
| 3rd digit | 8 | Communication error in E1-terminal area |
|  | 9 | - |
|  | 10 | - |
|  | 11 | - |
| 4th digit | 12 | - |
|  | 13 | - |
|  | 14 | - |
|  | 15 | - |

## Hexadecimal Display of the Parameter which Shows the Error Details

Error confirmation parameters are displayed in hexadecimal.
When the error occurs, " 1 " is set on the bit of corresponding error.


Parameter PA.ER

| Displayed digit | bit | Description |
| :---: | :---: | :---: |
| 1st digit | 0 | System data error |
|  | 1 | Calibration value error |
|  | 2 | User (parameter) default value error |
|  | 3 | - |
| 2nd digit | 4 | Setup parameter error |
|  | 5 | Operation parameter error |
|  | 6 | - |
|  | 7 | - |
| 3rd digit | 8 | Faulty FRAM |
|  | 9 | - |
|  | 10 | Control parameter error |
|  | 11 | - |
| 4th digit | 12 | - |
|  | 13 | - |
|  | 14 | - |
|  | 15 | - |

Parameter OP.ER

| Displayed digit | bit |  |
| :--- | :---: | :--- |
| 1st digit | 0 | Non responding hardware in E1-terminal area |
|  | 1 | - |
|  | 2 | - |
|  | 3 | - |
| 2nd digit | 4 | - |
|  | 5 | - |
|  | 6 | - |
|  | 7 | - |
| 3td digit | 8 | Communication error in E1-terminal area |
|  | 9 | - |
|  | 10 | - |
|  | 11 | - |
|  | 12 | - |
|  | 13 | - |
|  | 14 | - |

Parameter AD1.E

| Displayed digit | bit | Description |
| :---: | :---: | :---: |
| 1st digit | 0 | ADC error of PV input |
|  | 1 | - |
|  | 2 | - |
|  | 3 | - |
| 2nd digit | 4 | - |
|  | 5 | RJC error of PV input |
|  | 6 | - |
|  | 7 | - |
| 3rd digit | 8 | PV input burnout error |
|  | 9 | - |
|  | 10 | - |
|  | 11 | - |
| 4th digit | 12 | - |
|  | 13 | - |
|  | 14 | - |
|  | 15 | - |

Parameter PV1.E

| Displayed digit | bit | Description |
| :---: | :---: | :---: |
| 1st digit | 0 | PV input burnout error |
|  | 1 | - |
|  | 2 | - |
|  | 3 | - |
| 2nd digit | 4 | PV input over-scale |
|  | 5 | PV input under-scale |
|  | 6 | - |
|  | 7 | - |
| 3rd digit | 8 | - |
|  | 9 | - |
|  | 10 | - |
|  | 11 | - |
| 4th digit | 12 | - |
|  | 13 | - |
|  | 14 | Auto-tuning time-out |
|  | 15 | - |

### 16.2 Maintenance

### 16.2.1 Cleaning

The front panel and operation keys should be gently wiped with a cloth soaked with water and squeezed firmly.

## CAUTION

In order to prevent LCD from static electricity damage, do not wipe with dry cloth. (When LCD is electrified, it returns to normal in several minutes.)
Do not use alcohol, benzene, or any other solvents.

### 16.2.2 Packaging when Shipping the Product for Repair

Should the instrument break down and need to be shipped to our sales representative for repair, handle it as noted below:
Write down the settings of parameters for a repair request.

## WARNING

Prior to shipping the instrument, put it into an antistatic bag and repackage it using the original internal packaging materials and packaging container.
16.2.3 Replacing Parts

Do not replace any parts inside the unit.

### 16.3 Periodic Maintenance

Check the operating condition periodically to use this instrument with good condition.

### 16.4 Disposal

When disposing of this instrument, arrange for appropriate disposal as industrial waste according to the rules of a country, the area, or a local government.

### 17.1 Installation Location

The instrument should be installed in indoor locations meeting the following conditions:

- Instrumented panel

This instrument is designed to be mounted in an instrumented panel. Mount the instrument in a location where its terminals will not inadvertently be touched.

- Well ventilated locations

Mount the instrument in well ventilated locations to prevent the instrument's internal temperature from rising. However, make sure that the terminal portions are not exposed to wind. Exposure to wind may cause the temperature sensor accuracy to deteriorate. To mount multiple indicating controllers, see the external dimensions/ panel cutout dimensions which follow. If mounting other instruments adjacent to the instrument, comply with these panel cutout dimensions to provide sufficient clearance between the instruments.

- Locations with little mechanical vibration Install the instrument in a location subject to little mechanical vibration.
- Horizontal location

Mount the instrument horizontally and ensure that it is level, with no inclination to the right or left.


## Note

If the instrument is moved from a location with low temperature and low humidity to a place with high temperature and high humidity, or if the temperature changes rapidly, condensation will result. Moreover, in the case of thermocouple inputs, measurement errors will result. To avoid such a situation, leave the instrument in the new environment under ambient conditions for more than 1 hour prior to using it.

Do not mount the instrument in the following locations:

- Outdoors
- Locations subject to direct sunlight, ultrared rays, ultraviolet rays, or close to a heater Install the instrument in a location with stable temperatures that remain close to an average temperature of $23^{\circ} \mathrm{C}$. Do not mount it in locations subject to direct sunlight or close to a heater. Doing so adversely affects the instrument and LCD.
- Locations with substantial amounts of oily fumes, steam, moisture, dust, or corrosive gases
The presence of oily fumes, steam, moisture, dust, or corrosive gases adversely affects the instrument. Do not mount the instrument in locations subject to any of these substances.
- Areas near electromagnetic field generating sources Do not place magnets or tools that generate magnetism near the instrument. If the instrument is used in locations close to a strong electromagnetic field generating source, the magnetic field may cause measurement errors.
- Locations where the display is difficult to see The instrument uses an LCD for the display unit, and this can be difficult to see from extremely oblique angles. Mount the instrument in a location where it can be seen as much as possible from the front.
- Areas close to flammable articles

Absolutely do not place the instrument directly on flammable surfaces. If such a circumstance is unavoidable and the instrument must be placed close to a flammable item, provide a shield for it made of 1.43 mm thick plated steel or 1.6 mm thick unplated steel with a space of at least 150 mm between it and the instrument on the top, bottom and sides.


- Areas subject to being splashed with water


### 17.2 Mounting Method



## WARNING

Be sure to turn OFF the power supply to the controller before installing it on the panel to avoid an electric shock.

## Mounting the Instrument Main Unit

Provide an instrumented panel steel sheet of 1 to 10 mm thickness.
After opening the mounting hole on the panel, follow the procedures below to install the controller:

1. Insert the controller into the opening from the front of the panel so that the terminal board on the rear is at the far side.
2. Set the brackets in place on the top and bottom of the controller as shown in the figure below, then tighten the screws of the brackets. Take care not to overtighten them.


To uninstall the controller, perform the procedure in the reverse order.

## CAUTION

1) Tighten the screws with appropriate tightening torque within $0.25 \mathrm{~N} \cdot \mathrm{~m}$. Otherwise it may cause the case deformation or the bracket damage.
2) Make sure that foreign materials do not enter the inside of the instrument through the case's slit holes.

### 17.3 External Dimensions and Panel Cutout Dimensions



### 17.4 Wiring

### 17.4.1 Important Information on Wiring



## WARNING

1) Be sure to turn OFF the power supply to the controller before wiring to avoid an electric shock. Use a tester or similar device to ensure that no power is being supplied to a cable to be connected.
2) Wiring work must be carried out by a person with basic electrical knowledge and practical experience.
3) For the wiring cable, the temperature rating is $75^{\circ} \mathrm{C}$ or more.

JT32A Terminal Block Diagram
E1-terminal area


## CAUTION

- When connecting two or more crimp-on terminal lugs to the single terminal block, bend the crimp-on terminal lugs before tightening the screw.
- Note that the wiring of two or more crimp-on terminal lugs to the single highvoltage terminal of the power supply and relay, etc. does not comply with the safety standard.


## CAUTION

Do not use an unassigned terminal as the relay terminal.

## Recommended Crimp-on Terminal Lugs

## (ød)



Recommended tightening torque: $0.6 \mathrm{~N} \cdot \mathrm{~m}$ Applicable wire size: Power supply wiring $1.25 \mathrm{~mm}^{2}$ or more

| Applicable terminal lug | Applicable wire size $\mathbf{m m}^{2}$ (AWG\#) | (ød) | (A) | (F) |
| :--- | :--- | :--- | :--- | :--- |
| M3 | 0.25 to $1.65(22$ to 16$)$ | 3.3 | 5.5 | 4.2 |



## Cable Specifications

| Purpose | Name and Manufacturer |
| :--- | :--- |
| Power supply, relay contact <br> output | 600 V Grade heat-resistant PVC insulated wires, JIS C 3317(HIV), 0.9 <br> to $2.0 \mathrm{~mm}^{2}$ |
| Thermocouple | Shielded compensating lead wire JISC1610 <br> For thermocouple input (PV input and remote input with direct input), <br> shielded compensating lead wire of cross-sectional area less than or <br> equal to 0.75 mm 2 is recommended. If the crosssectional area is wide, <br> the reference junction compensation error may be large. |
| RTD | Shielded wire (three/four conductors) UL2482 (Hitachi Cable) |
| Other signals (other than <br> contact output) | Shielded wires |
| Other signals (contact <br> output) | Non shielded wires |
| RS485 communication | Shielded wires |

Recommended tightening torque: 0.5 to $0.6 \mathrm{~N} \cdot \mathrm{~m}$

## Note

Communication wires of cross-sectional area less than or equal to $0.34 \mathrm{~mm}^{2}$ may not be secured firmly to the terminals.
Check that the wire is firmly connected to the terminal by folding the conductor of the wire connected to the climp-on lug.
Recommended length of the stripped wire: 7 mm

### 17.4.2 PV Input Wiring

## CAUTION

1) Be careful of polarity when wiring inputs. Reversed polarity can damage the UT.
2) Keep the PV input signal line as far away as possible from the power supply circuit and ground circuit.
3) For TC input, use shielded compensating lead wires for wiring. For RTD input, use shielded wires that have low conductor resistance and cause no significant differences in resistance between the three wires.
4) If there is a risk of external lightning surges, use a lightning arrester etc.

UT32A
TC Input

## Use

PV input is used for PV input.

### 17.4.3 Control Output (Relay, Current, and Voltage Pulse) Wiring

## CAUTION

1) The use of inductance (L) loads such as auxiliary relays, motors and solenoid valves causes malfunction or relay failure; always insert a CR filter for use with alternating current or a diode for use with direct current, as a spark-removal surge suppression circuit, into the line in parallel with the load.
2) If there is a risk of external lightning surges, use a lightning arrester etc.
3) Relays cannot be used for a small load of 10 mA or less.
4) Since the insulation provided to each relay output terminal is Functional insulation, provide Reinforced insulation to the external of the device as necessary. (Refer to the drawing below.)


## DC Relay Wiring

UT32A


UT's contact terminal (socket).)
(Use one with a relay coil rating
less than the UT's contact rating.)

## AC Relay Wiring



## Transistor Output Wiring



Relay Output

| Suffix code : Type 1 = "-R" |
| :---: |
| NC OUT |
| Contact rating: $250 \mathrm{~V} \mathrm{AC}, 3 \mathrm{~A}$ |
| $30 \mathrm{~V} \mathrm{DC}, 3 \mathrm{~A}$ (resistance load) |

Note: The control output should always be used with a load of 10 mA or more.

## Current and Voltage Pulse Output



## Use

When current/voltage pulse output is not used for control output, it can be used for retransmission output.
When retransmission output terminal is not used for retransmission output, it can be used for optional control output. The current output range can be changed.
For control output setting, set the control type (CNT), then set the output terminal and output type in the output type selection (OT).

- Control output type: 10.1 Setting Control Output Type


### 17.4.4 Contact Output Wiring

## CAUTION

1) Use an auxiliary relay for load-switching if the contact rating is exceeded.
2) Connect a bleeder resistor when a small current is used, so that a current exceeding 1 mA can be supplied.
3) The output relay has a limited service life. Be sure to connect a CR filter (for AC) or diode (for DC) to the load.
4) If there is a risk of external lightning surges, use a lightning arrester etc.
5) Since the insulation provided to each relay output terminal is Functional insulation, provide Reinforced insulation to the external of the device as necessary. (Refer to the drawing below.)


- When using auxiliary relay: 17.4.3 Control Output (Relay, Current, and Voltage Pulse) Wiring


Factory default: Function is not assigned to the additional contact outputs.

- Contact output function registration: 12.2 Setting Contact Output Function

The following table shows the initial status for control type.

| AL1 terminal | AL2 terminal |
| :--- | :--- |
| Alarm 1 <br> (PV high limit) | Alarm 2 <br> (PV low limit) |

### 17.4.5 24 V DC Loop Power Supply Wiring

This can be used when the optional suffix code /LP is specified.
The controller with the optional suffix code /LP is equipped with an isolated loop power supply ( 21.6 to 28.0 V DC) for connecting a 2-wire transmitter.


### 17.4.6 RS-485 Communication Interface Wiring

Wire as follows for Modbus communication, PC link communication, or ladder communication.
Always connect a terminating resistor to the station at the end of the communication line.

- Details of communication parameter settings and communication functions: UTAdvanced Series Communication Interface (RS-485, Ethernet) User's Manual

4-wire Wiring


2-wire Wiring of 4-wire Terminal


UT32A

| Terminal <br> symbol <br> above | Suffix code: Type 2 = "1" " |
| :---: | :---: |
| RDB (+) | 304 |
| RDA (-) | 305 |
| SDB (+) | 301 |
| SDA (-) | 302 |
| SG | 303 |

## 2-wire Wiring



UT32A

| Terminal <br> symbol <br> above. | Suffix code: Type 2= "1" |
| :---: | :---: |
| RSB (+) | 301 |
| RSA (-) | 302 |
| SG | 303 |

## Note

ML2-x indicates a converter of YOKOGAWA. Other than this, RS232C/RS485 converters can also be used. If another converter is to be used, check the electrical specifications of the converter before using it.

### 17.4.7 Coordinated Operation Wiring

## 4-wire Wiring



2-wire Wiring of 4-wire Terminal (1)


2-wire Wiring of 4-wire Terminal (2)


## 17

UT32A

| Terminal <br> symbol <br> above | Suffix code: Type 2 = "1"" |
| :---: | :---: |
| RDB (+) | 304 |
| RDA (-) | 305 |
| SDB (+) | 301 |
| SDA (-) | 302 |
| SG | 303 |

## 2-wire Wiring



UT32A

| Terminal <br> symbol <br> above | Suffix code: Type 2= "1" |
| :---: | :---: |
| RSB (+) | 301 |
| RSA (-) | 302 |
| SG | 303 |

### 17.4.8 Power Supply Wiring



## WARNING

1) Wiring work must be carried out by a person with basic electrical knowledge and practical experience.
2) Be sure to turn OFF the power supply to the controller before wiring to avoid an electric shock. Use a tester or similar device to ensure that no power is being supplied to a cable to be connected.
3) As a safety measure, always install a circuit breaker (an IEC 60947-compatible product, $5 \mathrm{~A}, 100 \mathrm{~V}$ or 220 VAC ) in an easily accessible location near the instrument. Moreover, provide indication that the switch is a device for turning off the power to the instrument.
4) Install the power cable keeping a distance of more than 1 cm from other signal wires.
5) The power cable is required to meet the IEC standards concerned or the requirements of the area in which the instrument is being installed.
6) Wiring should be installed to conform to NEC (National Electrical Code: ANSI/ NFPA-70) or the wiring construction standards in countries or regions where wiring will be installed.

## CAUTION

1) Provide electricity from a single-phase power supply. If the power is noisy, install an isolation transformer on the primary side, and use a line filter on the secondary side. When measures against noise are taken, do not install the primary and secondary power cables close to each other.
2) If there is a risk of external lightning surges, use a lightning arrester etc.


### 17.5 Attaching and Detaching Terminal Cover

After completing the wiring, the terminal cover is recommended to use for the instrument.

## Attaching Method

(1) Attach the terminal cover to the rear panel
of the main unit horizontally.


## Detaching Method

(1) Slide the terminal cover to the direction of the printed arrow.


### 18.1 Parameter Map

## Brief Description of Parameter Map

## Group Display

"E1" and "1 to 4, R" appearing in the parameter map are displayed on Group display (7 segments, 2 digits) while the menu or parameter is displayed.

E1: indicates the parameter in E1-terminal area
1 to 4 , $R$ : indicate the group numbers

- E1: Terminal assignments in 17.4 Wiring


## Parameter Display Level

The marks below appearing next to the menu symbol and parameter symbol in the parameter map indicate the display/non-display level.

| Mark | Display | Display level | Description |
| :---: | :---: | :--- | :--- |
| None | EASY | Easy setting mode: Displays <br> the minimum parameters. | Corresponding parameters are displayed <br> in all modes. |
| S | STD | Standard setting mode: <br> Displays a wider range of <br> parameters than displayed in <br> the Easy setting mode. | Corresponding parameters are displayed <br> only in Standard setting mode and <br> Professional setting mode. <br> Parameter display level indicators <br> "EASY" and "PRO" are unlit in Standard <br> setting mode. <br> *: "STD" is the symbol used in this <br> manual only. |
| P | PRO | Professional setting mode: <br> Displays all parameters. | Corresponding parameters are displayed <br> only in Professional setting mode. |



[^3]
## Function of Each Menu

| Menu symbol | Function |
| :---: | :--- |
| MODE | Operation mode (STOP/RUN switch, REMOTE/LOCAL switch, Auto-tuning <br> switch, SP number selection, etc.) |

The parameters in the menu of the following table indicate the parameters to set the functions necessary for operation. The symbol in parentheses are shown on Group display.

| Menu symbol | Function |
| :--- | :--- |
| CS | SELECT parameter |
| SP | SP and alarm setpoint |
| SPS | SP-related function |
| ALRM | Plarm function |
| PVS | PID setting |
| PID | Super, Super 2, anti-reset windup, output velocity limiter, and manual preset <br> output |
| TUNE | Zone control |
| ZONE |  |

The parameters in the menu of the following table indicate the parameters to set the basic functions of the controller. The symbol in parentheses are shown on Group display.

| Menu symbol | Functions |
| :--- | :--- |
| PASS | Password setting (Displayed only when the password has been sent.) |


| Menu symbol | Functions |
| :--- | :--- |
| CTL | Control type, number of SP groups, number of PID groups, etc |
| PV | PV input type, range, scale, etc |
| MPV | Input range, SP limiters |
| OUT | Cycle time |
| R485 (E1) | RS-485 communication (E1-terminal area) |
| KEY | Display functions |
| DISP | SELECT Display, SELECT parameter registration |
| CSEL | Parameter menu lock |
| KLOC | Alarm output function, contact output type |
| MLOC | Action setting when recovering from a power failure, guide display language, <br> password setting, etc |
| ALM | Initialization of parameter |
| I/O | Error status, version, etc |
| SYS | Parameter display level |
| INIT |  |
| VER | LVL |

## Note

Some parameters are not displayed according to the setting such as control type, or input and output.




### 18.2 List of Parameters

### 18.2.1 Operation Parameters

Operation Mode Menu (Menu: MODE)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :--- | :--- | :--- | :--- |
| S.R | STOP/RUN switch | EASY | STOP: Stop mode <br> RUN: Run mode <br> Preset output (PO) is generated in <br> STOP mode. | RUN |
| R.L | REMOTE/LOCAL |  |  |  |
| switch | EASY | LCL: Local mode <br> REM: Remote mode <br> (Displayed only in cases where the <br> communication is specified.) | LCL |  |
| AT | SP number <br> selection | OFF: Disable <br> 1 to 4: Perform auto-tuning. Tuning <br> result is stored in the specified <br> numbered PID. | OFF |  |
| R: Tuning result is stored in the |  |  |  |  |
| PID for reference deviation. |  |  |  |  |$\quad$| EASY |
| :--- |
| SPNO.1 to 4 (Depends on the setup <br> parameter SPGR. setting.) |
| PID number | | The PID group number being |
| :--- |
| selected is displayed. |
| 1 to 4, R: PID group for reference |
| deviation |$\quad 1$|  |
| :--- |

SELECT Parameter Menu (Menu: CS)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :--- | :--- | :--- | :--- |
| CS10 to <br> CS19 | SELECT parameter <br> 10 to 19 | EASY | Setting range of a registered <br> parameter. | - |

SP and Alarm Setpoint Setting Menu (Menu: SP)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :--- | :--- | :--- | :--- |
| SP | Target setpoint | EASY | 0.0 to 100.0\% of PV input range <br> (EU) (Setting range: SPL to SPH) | SPL |
| PIDN | PID number <br> selection | EASY | 1 to 4 (Depends on the PIDG. <br> setting.) | Same as SP <br> number. |
| A1 to A4 | Alarm-1 to -4 <br> setpoint | Set a display value of setpoint of <br> PV alarm, SP alarm, deviation <br> alarm, output alarm, or velocity <br> alarm. | EASY | -19999 to 30000 (Set a value <br> within the input range.) <br> Decimal point position depends on <br> the input type. |

## SP-related Setting Menu (Menu: SPS)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :--- | :---: | :--- | :--- |
| RT | Remote input ratio | STD | 0.001 to 9.999 <br> (Displayed only in cases where the <br> communication is specified.) | 1.000 |
| RBS | Remote input bias | STD | -100.0 to 100.0\% of PV input range <br> span (EUS) <br> (Displayed only in cases where the <br> communication is specified.) | 0.0 \% of PV <br> input range <br> span |
| UPR | SP ramp-up rate | EASY | OFF, 0.0 + 1 digit to 100.0\% of PV <br> input range span (EUS) | OFF |
| DNR | SP ramp-down rate | EASY | OFF |  |
| TMU | SP ramp-rate time <br> unit | EASY | HOUR: Ramp-up rate or ramp- <br> down rate per hour <br> MIN: Ramp-up rate or ramp-down <br> rate per minute | HOUR |
| SPT | SP tracking <br> selection | STD | OFF, ON | ON |
| PVT | PV tracking <br> selection | STD | OFF, ON | OFF |

Alarm Function Setting Menu (Menu: ALRM)

| Parameter symbol | Name | Display level | Setting range | Initial value |
| :---: | :---: | :---: | :---: | :---: |
| AL1 to AL4 | Alarm-1 to -4 type | EASY | Set a 5-digit value in the following order. <br> [Latch action (0/1/2/3/4)] + [Energized <br> (0) or De-energized (1)] + [Without (0) <br> or With (1) Stand-by action] + [Alarm type: 2 digits (see below)] <br> For latch action, see chapter 11. <br> Alarm type: 2 digits <br> 00: Disable <br> 01: PV high limit <br> 02: PV low limit <br> 03: SP high limit <br> 04: SP low limit <br> 05: Deviation high limit <br> 06: Deviation low limit <br> 07: Deviation high and low limits <br> 08: Deviation within high and low limits <br> 09: Target SP high limit <br> 10: Target SP low limit <br> 11: Target SP deviation high limit <br> 12: Target SP deviation low limit <br> 13: Target SP deviation high and low limits <br> 14: Target SP deviation within high and low limits <br> 15: OUT high limit <br> 16: OUT low limit <br> 19: Analog input PV high limit <br> 20: Analog input PV low limit <br> 29: PV velocity <br> 30: Fault diagnosis <br> 31: FAIL | AL1, AL3: <br> Latch action (0) <br> Energized (0) Without Standby action (0) PV high limit (01) <br> AL2, AL4: <br> Latch action <br> (0) <br> Energized (0) Without Standby action (0) PV low limit (02) |
| VT1 to VT4 | PV velocity alarm time setpoint 1 to 4 | EASY | 0.01 to 99.59 (minute.second) | 1.00 |
| HY1 to HY4 | Alarm-1 to -4 hysteresis | EASY | Set a display value of setpoint of hysteresis. <br> -19999 to 30000 (Set a value within the input range.) <br> Decimal point position depends on the input type. <br> When the decimal point position for the input type is set to " 1 ", the initial value of the hysteresis is "1.0". | 10 |
| DYN1 to DYN4 | Alarm-1 to -4 On-delay timer | STD | 0.00 to 99.59 (minute second) | 0.00 |
| DYF1 to DYF4 | Alarm-1 to -4 Off-delay timer | PRO | 0.00 to 99.59 (minute.second) | 0.00 |
| AMD | Alarm mode | STD | 0: Always active <br> 1: Not active in STOP mode <br> 2: Not active in STOP or MAN mode | 0 |

PV-related Setting Menu (Menu: PVS)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :--- | :--- | :--- | :--- |
| BS | PV input bias | EASY | -100.0 to $100.0 \%$ of PV input range <br> span (EUS) | $0.0 \%$ of PV <br> input range <br> span |
| FL | PV input filter | EASY | OFF, 1 to 120 s | OFF |

PID Setting Menu (Menu: PID)

| Parameter symbol | Name | Display level | Setting range | Initial value |
| :---: | :---: | :---: | :---: | :---: |
| P | Proportional band | EASY | 0.0 to 999.9\% <br> When $0.0 \%$ is set, it operates as $0.1 \%$. | 5.0\% |
| 1 | Integral time | EASY | OFF: Disable 1 to 6000 s | 240 s |
| D | Derivative time | EASY | OFF: Disable 1 to 6000 s | 60 s |
| OH | Control output high limit | EASY | -4.9 to 105.0\%, (OL<OH) | 100.0\% |
| OL | Control output low limit | EASY | -5.0 to 104.9\%, (OL<OH), SD: Tight shut | 0.0\% |
| MR | Manual reset | EASY | Enabled when integral time is OFF. The manual reset value equals the output value when PV = SP. -5.0 to 105.0\% | 50.0\% |
| HYS | Hysteresis (in ON/ OFF control | EASY | In ON/OFF control: 0.0 to 100.0\% of PV input range span (EUS) | In ON/OFF control: 0.5 \% of PV input range span |
| HY.UP | Upper-side hysteresis (in ON/ OFF control) | EASY | 0.0 to 100.0\% of PV input range | 0.5 \% of PV input range span |
| HY.LO | Lower-side hysteresis (in ON/ OFF control) | EASY | span (EUS) | $\begin{aligned} & 0.5 \% \text { of PV } \\ & \text { input range } \\ & \text { span } \end{aligned}$ |
| DR | Direct/reverse action switch | STD | RVS: Reverse action, DIR: Direct action | RVS |

PID Setting Menu (Menu: PID) (Continued from previous page)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :---: | :---: | :---: | :--- |
| PO | Preset output | EASY | -5.0 to $105.0 \%$ | $0.0 \%$ |

Tuning Menu (Menu: TUNE)

| Parameter symbol | Name | Display level | Setting range | Initial value |
| :---: | :---: | :---: | :---: | :---: |
| SC | Super function | EASY | OFF: Disable <br> 1: Overshoot suppressing function (normal mode) <br> 2: Hunting suppressing function (stable mode) Enables to answer the wider characteristic changes compared with response mode. <br> 3: Hunting suppressing function (response mode) Enables quick follow-up and short converging time of PV for the changed SP. <br> 4: Overshoot suppressing function (strong suppressing mode) | OFF |
| AT.TY | Auto-tuning type | STD | 0: Normal <br> 1: Stability | 0 |
| AT.OH | Output high limit in auto-tuning | PRO | 0 to 105.0 | 100.0\% |
| AT.OL | Output low limit in auto-tuning | PRO | to 105.0 | 0.0\% |
| AT.BS | SP bias in autotuning | PRO | -100.0 to $100.0 \%$ of PV input range span (EUS) | 0.0 \% of PV input range span |
| AR | Anti-reset windup (excess integration prevention) | STD | AUTO, 50.0 to 200.0\% | AUTO |
| OPR | Output velocity limiter | STD | OFF: Disable 0.1 to 100.0\%/s | OFF |
| OLMT | Output limiter switch | PRO | OFF: Disable output limiter in MAN mode <br> ON: Enable output limiter in MAN mode | ON |
| MPON | Manual preset output number selection | STD | OFF: Hold the control output in AUTO mode (bumpless) <br> 1: Use manual preset output 1 (output bump) <br> 2: Use manual preset output 2 (output bump) <br> 3: Use manual preset output 3 (output bump) <br> 4: Use manual preset output 4 (output bump) <br> 5: Use manual preset output 5 (output bump) | OFF |
| MPO1 to MPO5 | Manual preset output 1 to 5 | STD | -5.0 to 105.0\% | 0.0\% |

Zone Control Menu (Menu: ZONE)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :--- | :---: | :--- | :--- |
| RP1 to RP3 | Reference point 1 <br> to 3 | STD | 0.0 to 100.0\% of PV input range <br> $(E U)$ <br> $(R P 1 \leq R P 2 \leq R P 3)$ | $100.0 \%$ of PV <br> input range |
| RHY | Zone PID switching <br> hysteresis | STD | 0.0 to 10.0\% of PV input range <br> span (EUS) | $0.5 \%$ of PV <br> input range <br> span |
| RDV | Reference deviation | STD | OFF: Disable <br> $0.0+1$ digit to 100.0\% of PV input <br> range span (EUS) | OFF |

### 18.2.2 Setup Parameters

Control Function Setting Menu (Menu: CTL)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :--- | :---: | :--- | :--- |
| CNT | Control type | EASY | PID: PID control <br> ONOF: ON/OFF control (1 point of <br> hysteresis) <br> ONOF2: ON/OFF control (2 points <br> of hysteresis) | Standard type: <br> PID |
| ALG | PID control mode | PRO | 0: Standard PID control mode <br> 1: Fixed-point control mode | 0 |
| SPGR. | Number of SP <br> groups | STD | 1 to 4 | 4 |
| ALNO. | Number of alarms | PRO | 0 to 4 | 4 |
| ZON | Zone PID selection | STD | 1: Zone PID selection (selection by <br> PV) <br> $2: ~ Z o n e ~ P I D ~ s e l e c t i o n ~(s e l e c t i o n ~ b y ~$ <br> target SP) <br> $3: ~ S P ~ g r o u p ~ n u m b e r ~ s e l e c t i o n ~ 2 ~$ <br> $4: ~ Z o n e ~ P I D ~ s e l e c t i o n ~(s e l e c t i o n ~ b y ~$ <br> SP) | 0 |
| PIDG. | Number of PID <br> groups | STD | 1 to 4 |  |

PV Input Setting Menu (Menu: PV)

| Parameter symbol | Name | Display level | Setting range | Initial value |
| :---: | :---: | :---: | :---: | :---: |
| IN | PV input type | EASY | OFF: Disable <br> K1: -270.0 to $1370.0\left({ }^{\circ} \mathrm{C}\right) /-450.0$ to $2500.0\left({ }^{\circ} \mathrm{F}\right)$ K2: -270.0 to $1000.0\left({ }^{\circ} \mathrm{C}\right) /-450.0$ to $2300.0\left({ }^{\circ} \mathrm{F}\right)$ K3: -200.0 to $500.0\left({ }^{\circ} \mathrm{C}\right) /-200.0$ to $1000.0\left({ }^{\circ} \mathrm{F}\right)$ J: -200.0 to $1200.0\left({ }^{\circ} \mathrm{C}\right) /-300.0$ to $2300.0\left({ }^{\circ} \mathrm{F}\right)$ T1: -270.0 to $400.0\left({ }^{\circ} \mathrm{C}\right) /-450.0$ to $750.0\left({ }^{\circ} \mathrm{F}\right)$ T2: 0.0 to $400.0\left({ }^{\circ} \mathrm{C}\right) /-200.0$ to $750.0\left({ }^{\circ} \mathrm{F}\right)$ <br> B: 0.0 to $1800.0\left({ }^{\circ} \mathrm{C}\right) / 32$ to $3300\left({ }^{\circ} \mathrm{F}\right)$ <br> S: 0.0 to $1700.0\left({ }^{\circ} \mathrm{C}\right) / 32$ to $3100\left({ }^{\circ} \mathrm{F}\right)$ <br> R: 0.0 to $1700.0\left({ }^{\circ} \mathrm{C}\right) / 32$ to $3100\left({ }^{\circ} \mathrm{F}\right)$ <br> N: -200.0 to $1300.0\left({ }^{\circ} \mathrm{C}\right) /-300.0$ to $2400.0\left({ }^{\circ} \mathrm{F}\right)$ <br> E: -270.0 to $1000.0\left({ }^{\circ} \mathrm{C}\right) /-450.0$ to $1800.0\left({ }^{\circ} \mathrm{F}\right)$ <br> L: -200.0 to $900.0\left({ }^{\circ} \mathrm{C}\right) /-300.0$ to $1600.0\left({ }^{\circ} \mathrm{F}\right)$ U1: -200.0 to $400.0\left({ }^{\circ} \mathrm{C}\right) /-300.0$ to $750.0\left({ }^{\circ} \mathrm{F}\right)$ U2: 0.0 to $400.0\left({ }^{\circ} \mathrm{C}\right) /-200.0$ to $1000.0\left({ }^{\circ} \mathrm{F}\right)$ W: 0.0 to $2300.0\left({ }^{\circ} \mathrm{C}\right) / 32$ to $4200\left({ }^{\circ} \mathrm{F}\right)$ <br> PL2: 0.0 to $1390.0\left({ }^{\circ} \mathrm{C}\right) / 32.0$ to $2500.0\left({ }^{\circ} \mathrm{F}\right)$ P2040: 0.0 to $1900.0\left({ }^{\circ} \mathrm{C}\right) / 32$ to $3400\left({ }^{\circ} \mathrm{F}\right)$ WRE: 0.0 to $2000.0\left({ }^{\circ} \mathrm{C}\right) / 32$ to $3600\left({ }^{\circ} \mathrm{F}\right)$ JPT1: -200.0 to $500.0\left({ }^{\circ} \mathrm{C}\right) /-300.0$ to $1000.0\left({ }^{\circ} \mathrm{F}\right)$ JPT2: -150.00 to $150.00\left({ }^{\circ} \mathrm{C}\right) /-200.0$ to $300.0\left({ }^{\circ} \mathrm{F}\right)$ PT1: -200.0 to $850.0\left({ }^{\circ} \mathrm{C}\right) /-300.0$ to $1560.0\left({ }^{\circ} \mathrm{F}\right)$ PT2: -200.0 to $500.0\left({ }^{\circ} \mathrm{C}\right) /-300.0$ to $1000.0\left({ }^{\circ} \mathrm{F}\right)$ PT3: -150.00 to $150.00\left({ }^{\circ} \mathrm{C}\right) /-200.0$ to $300.0\left({ }^{\circ} \mathrm{F}\right)$ $0.4-2 \mathrm{~V}: 0.400$ to 2.000 V $1-5 \mathrm{~V}: 1.000$ to 5.000 V 4-20: 4.00 to 20.00 mA $0-2 \mathrm{~V}: 0.000$ to 2.000 V $0-10 \mathrm{~V}: 0.00$ to 10.00 V 0-20: 0.00 to 20.00 mA -1020: -10.00 to 20.00 mV 0-100: 0.0 to 100.0 mV <br> Note: <br> W: W-5\% Re/W-26\% Re (Hoskins Mfg. Co.), <br> ASTM E988 <br> WRE: W97Re3-W75Re25 | OFF |
| UNIT | PV input unit | EASY | -: No unit <br> C: Degree Celsius <br> -: No unit <br> --: No unit <br> ---: No unit <br> F: Degree Fahrenheit | C |
| RH | Maximum value of PV input range | EASY | Depends on the input type. <br> - For temperature input Set the temperature range that is actually | Depends on the input type |
| RL | Minimum value of PV input range | EASY | controlled. (RL<RH) <br> - For voltage / current input - <br> Set the range of a voltage / current signal that is applied. <br> The scale across which the voltage / current signal is actually controlled should be set using the maximum value of input scale (SH) and minimum value of input scale (SL). <br> (Input is always $0 \%$ when $R L=R H$.) | Depends on the input type |

PV Input Setting Menu (Menu: PV) (Continued from previous page)

| Parameter symbol | Name | Display level | Setting range | Initial value |
| :---: | :---: | :---: | :---: | :---: |
| SDP | PV input scale decimal point position | EASY | 0 : No decimal place <br> 1: One decimal place <br> 2: Two decimal places <br> 3: Three decimal places <br> 4: Four decimal places | Depends on the input type |
| SH | Maximum value of PV input scale | EASY | $\begin{aligned} & -19999 \text { to } 30000,(\mathrm{SL}<\mathrm{SH}),\|\mathrm{SH}-\mathrm{SL}\| \leq \\ & 30000 \end{aligned}$ | Depends on the input type |
| SL | Minimum value of PV input scale | EASY |  | Depends on the input type |
| BSL | PV input burnout action | STD | OFF: Disable UP: Upscale DOWN: Downscale | Depends on the input type |
| RJC | PV input reference junction compensation | PRO | OFF: RJC OFF ON: RJC ON | ON |
| ERJC | PV input external RJC setpoint | PRO | -10.0 to $60.0\left({ }^{\circ} \mathrm{C}\right)$ | 0.0 |
| A.BS | PV analog input bias | STD | -100.0 to $100.0 \%$ of PV input range span (EUS) | 0.0 \% of PV input range span |
| A.FL | PV analog input filter | STD | OFF, 1 to 120 s | OFF |

Input Range / SP Limiter Setting Menu (Menu: MPV)

| Parameter symbol | Name | Display level | Setting range | Initial value |
| :---: | :---: | :---: | :---: | :---: |
| P.UNI | Control PV input unit | STD | - : No unit <br> C: Degree Celsius <br> -: No unit <br> --: No unit <br> ---: No unit <br> F: Degree Fahrenheit | Same as PV input unit |
| P.DP | Control PV input decimal point position | STD | 0: No decimal place <br> 1: One decimal place <br> 2: Two decimal places <br> 3: Three decimal places <br> 4: Four decimal places | 1 |
| P.RH | Maximum value of control PV input range | STD | $\begin{aligned} & -19999 \text { to } 30000 \text {, (P.RL<P.RH), \| } \\ & \text { P.RH - P.RL \| } 30000 \end{aligned}$ | Depends on the input type |
| P.RL | Minimum value of control PV input range | STD |  | Depends on the input type |
| SPH | SP high limit | STD | 0.0 to $100.0 \%$ of PV input range (EU), (SPL<SPH) | 100.0 \% of PV input range |
| SPL | SP low limit | STD |  | $\begin{aligned} & 0.0 \text { \% of PV } \\ & \text { input range } \end{aligned}$ |

Output Setting Menu (Menu: OUT)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :--- | :---: | :--- | :--- |
| CT | Control output cycle <br> time | EASY | 0.5 to 1000.0 s | 30.0 s |

Output Setting Menu (Menu: OUT) (Continued from previous page)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :--- | :---: | :--- | :--- |
| OU.A | OUT current output <br> range | STD | $4-20: 4$ to 20 mA <br> $0-20: 0$ to 20 mA <br> $20-4: 20 ~ t o ~$ mA |  |
| $20-0: 20$ to 0 mA |  |  |  |  |$\quad 4-20$

RS-485 Communication Setting Menu (Menu: R485) (E1 terminal area)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :--- | :--- | :--- | :--- |
| PSL | Protocol selection | EASY | PCL: PC link communication <br> PCLSM: PC link communication <br> (with checksum) <br> LADR: Ladder communication <br> CO-M: Coordinated master station <br> CO-S: Coordinated slave station <br> MBASC: Modbus (ASCII) <br> MBRTU: Modbus (RTU) <br> CO-S1: Coordinated slave station <br> (Loop-1 mode) <br> CO-S2: Coordinated slave station <br> (Loop-2 mode) | MBRTU |
| P-P: Peer-to-peer communication |  |  |  |  |$\quad$| BPS |
| :--- |

Key Action Setting Menu (Menu: KEY)

| Parameter symbol | Name | Display level | Setting range | Initial value |
| :---: | :---: | :---: | :---: | :---: |
| Fn | User function key-n action setting | EASY | OFF: Disable <br> A/M: AUTO/MAN switch <br> R/L1: REM/LCL switch <br> S/R: STOP/RUN switch <br> AUTO: Switch to AUTO <br> MAN: Switch to MAN <br> REM1: Switch to REM <br> LCL1: Switch to LCL <br> STOP: Switch to STOP <br> RUN: Switch to RUN <br> AT: Auto-tuning <br> LTUP: LCD brightness UP <br> LTDN: LCD brightness DOWN <br> BRI: Adjust LCD brightness <br> LCD: LCD backlight ON/OFF <br> switch <br> LAT: Latch release <br> PID: PID tuning switch | PID |
| A/M | A/M key action setting | PRO | OFF: Disable A/M: AUTO/MAN switch R/L1: REM/LCL switch S/R: STOP/RUN switch AUTO: Switch to AUTO MAN: Switch to MAN | A/M |

Display Function Setting Menu (Menu: DISP)

| Parameter symbol | Name | Display level | Setting range | Initial value |
| :---: | :---: | :---: | :---: | :---: |
| PCMD | Active color PV display switch | EASY | 0 : Fixed in white <br> 1: Fixed in red <br> 2: Link to alarm 1 (Alarm OFF: white, Alarm ON: red) <br> 3: Link to alarm 1 (Alarm OFF: red, Alarm ON: white) <br> 4: Link to alarm 1 or 2 (Alarm OFF: white, Alarm ON: red) <br> 5: Link to alarm 1 or 2 (Alarm OFF: red, Alarm ON: white) <br> 6: PV limit (Within range: white, Out of range: red) <br> 7: PV limit (Within range: red, Out of range: white) <br> 8: SP deviation (Within deviation: white, Out of deviation: red) <br> 9: SP deviation (Within deviation: red, Out of deviation: white) | 0 |
| PCH | PV color change high limit | EASY | Set a display value when in PV limit or SP deviation. | 0 |
| PCL | PV color change low limit | EASY | -19999 to 30000 (Set a value within the input range.) Decimal point position depends on the input type. | 0 |
| BAR1 | Bar-graph display registration | STD | 0: Disable 1:OUT3: PV 4: SP 5: Deviation 6 to 16: Disable 18: PV terminals analog input 27: TSP 28: Deviation between the TSP | 5 |
| BDV | Bar-graph deviation display band | STD | 0.0 to $100.0 \%$ of PV input range span (EUS) | 1.0 \% of PV input range span |

Display Function Setting Menu (Menu: DISP) (Continued from previous page)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :--- | :--- | :--- | :--- |
| EV1 to |  |  |  |  |
| EV4 |  |  |  |  | | EV1 to EV4 <br> display condition <br> registration |
| :--- |

Display Function Setting Menu (Menu: DISP) (Continued from previous page)

| Parameter symbol | Name | Display level | Setting range | Initial value |
| :---: | :---: | :---: | :---: | :---: |
| B.PVW | White brightness adjustment of PV display | PRO | Adjusts the white brightness of PV display. <br> (Dark) -4 to 4 (Bright) | 0 |
| B.PVR | Red brightness adjustment of PV display | PRO | Adjusts the red brightness of PV display. <br> (Dark) -4 to 4 (Bright) | 0 |
| B.SP | Brightness adjustment of Setpoint display | PRO | Adjusts the brightness of SP display. <br> (Dark) -4 to 4 (Bright) | 0 |
| B.BAR | Brightness adjustment of Bargraph display | PRO | Adjusts the brightness of SP display. <br> (Dark) -4 to 4 (Bright) | 0 |
| B.STS | Brightness adjustment of Status indicator | PRO | Adjusts the brightness of Status indicator. <br> (Dark) -4 to 4 (Bright) | 0 |
| D.CYC | Display update cycle | PRO | $\begin{aligned} & \text { 1: } 100 \mathrm{~ms} \\ & \text { 2: } 200 \mathrm{~ms} \\ & \text { 3: } 500 \mathrm{~ms} \\ & \text { 4: } 1 \mathrm{~s} \\ & 5: 2 \mathrm{~s} \end{aligned}$ | 2 |
| OP.JP | Autoreturn to operation display | PRO | Automatically returned to the Operation Display when there has been no keystroke operation for 5 minutes. <br> OFF, ON | ON |
| MLSD | Least significant digital mask of PV display | STD | OFF: With least significant digit ON: Without least significant digit | OFF |
| MKTP | Method for least significant digital mask of PV display | STD | 0 : Rounding <br> 1: Rounding-off | 0 |

SELECT Display Setting Menu (Menu: CSEL)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :--- | :---: | :---: | :--- |
| CS1 to CS5 | SELECT Display-1 <br> to -5registration | STD | OFF |  |
| CS10 to <br> CS19 | SELECT <br> parameter-10 to -19 <br> registration | PRO | OFF, 2301 to 5000 | OFF |

Key Lock Setting Menu (Menu: KLOC)

| Parameter <br> symbol | Name | Display <br> level | Setting range |  |
| :--- | :--- | :---: | :--- | :--- | Initial value

Menu Lock Setting Menu (Menu: MLOC)

| Parameter symbol | Name | Display level | Setting range | Initial value |
| :---: | :---: | :---: | :---: | :---: |
| CTL | [CTL] menu lock | PRO | OFF: Display ON: Nondisplay | OFF |
| PV | [PV] menu lock | PRO |  |  |
| MPV | [MPV] menu lock | PRO |  |  |
| OUT | [OUT] menu lock | PRO |  |  |
| R485 | [R485] menu lock | PRO |  |  |
| KEY | [KEY] menu lock | PRO |  |  |
| DISP | [DISP] menu lock | PRO |  |  |
| CSEL | [CSEL] menu lock | PRO |  |  |
| KLOC | [KLOC] menu lock | PRO |  |  |
| ALM | [ALM] menu lock | PRO |  |  |
| I/O | [//O] menu lock | PRO |  |  |
| SYS | [SYS] menu lock | PRO |  |  |
| INIT | [INIT] menu lock | PRO |  |  |
| VER | [VER] menu lock | PRO |  |  |
| LVL | [LVL] menu lock | PRO |  |  |
| MODE | [MODE] menu lock | PRO | OFF: Display ON: Nondisplay | OFF |
| CS | [CS] menu lock | PRO |  |  |
| SP | [SP] menu lock | PRO |  |  |
| SPS | [SPS] menu lock | PRO |  |  |
| ALRM | [ALRM] menu lock | PRO |  |  |
| PVS | [PVS] menu lock | PRO |  |  |
| PID | [PID] menu lock | PRO |  |  |
| TUNE | [TUNE] menu lock | PRO |  |  |
| ZONE | [ZONE] menu lock | PRO |  |  |

AL1-AL3 Function Registration Menu (Menu: ALM)

| Parameter symbol | Name | Display level | Setting range | Initial value |
| :---: | :---: | :---: | :---: | :---: |
| AL1.S | AL1 function selection | STD | Set an I relay number. Setting range: 4001 to 6000 | 4353 |
| AL2.S | AL2 function selection | STD | No function: OFF <br> Alarm 1: 4353 <br> Alarm 2: 4354 <br> Alarm 3: 4355 <br> Alarm 4: 4357 <br> AUTO (ON ) / MAN (OFF) status: 4193 REM (ON) / LCL (OFF) status: 4194 <br> STOP (ON) / RUN (OFF) status: 4195 <br> FAIL (Normally ON) output: 4256 | 4354 |
| AL1.D | AL1 contact type | PRO | 0: When the event of assigned | 0 |
| AL2.D | AL2 contact type | PRO | 1: When the event of assigned function occurs, the contact output is opened. | 0 |

I/O Display Menu (Menu: I/O)

| Parameter <br> symbol | Name | Display <br> level | Read only |
| :--- | :--- | :---: | :---: |
| KEY | Key status | PRO | See Chapter 13. |
| Y000 | AL1-AL2 status (equipped as standard) | PRO |  |

System Setting Menu (Menu: SYS)

| Parameter symbol | Name | Display level | Setting range | Initial value |
| :---: | :---: | :---: | :---: | :---: |
| R.MD | Restart mode | STD | CONT: Continue action set before power failure. <br> MAN: Start from MAN. <br> AUTO: Start from AUTO. | CONT |
| R.TM | Restart timer | STD | 0 to 10 s | 0 |
| EPO | Input error preset output | STD | 0: Preset output 1: $0 \%$ output 2: $100 \%$ output | 0 |
| C.GRN | Response as GREEN Series | PRO | OFF: Works as UT32A in communication of device information response or broadcasting. <br> ON: Works as GREEN Series in communication of device information response or broadcasting. | OFF |
| FREQ | Power frequency | EASY | AUTO, 60: $60 \mathrm{~Hz}, 50: 50 \mathrm{~Hz}$ | AUTO |
| QSM | Quick setting mode | EASY | OFF: Disable ON: Enable | ON |
| LANG | Guide display language | EASY | ENG: English FRA: French GER: German SPA: Spanish | Depends on the Model and Suffix Codes |
| PASS | Password setting | EASY | 0 (No password) to 65535 | 0 |
| SMEC | Sampling period error counter | PRO | 0 to 65535 (display only) | 0 when power is turned on. |

Initialization Menu (Menu: INIT)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :--- | :--- | :--- | :--- |
| U.DEF | Initialization to user <br> default value | PRO | 12345: Initialization, automatically <br> returned to "0" after initialization. | 0 |
| F.DEF | Initialization to <br> factory default value | PRO | -12345: Initialization, automatically <br> returned to "0" after initialization. | 0 |

Error and Version Confirmation Menu (Menu: VER)

| Parameter symbol | Name | Display level | Read only |
| :---: | :---: | :---: | :---: |
| PA.ER | Parameter error status | EASY | See Chapter 16. |
| OP.ER | Option error status | EASY |  |
| AD1.E | A/D converter error status 1 | EASY |  |
| PV1.E | PV input error status | EASY |  |
| MCU | MCU version | EASY | See Chapter 13. |
| DCU | DCU version | EASY |  |
| ECU1 | ECU-1 version | EASY |  |
| PARA | Parameter version | EASY |  |
| H.VER | Product version | EASY |  |
| SER1 | Serial number 1 | EASY |  |
| SER2 | Serial number 2 | EASY |  |

Parameter Display Level Menu (Menu: LVL)

| Parameter <br> symbol | Name | Display <br> level | Setting range | Initial value |
| :--- | :--- | :---: | :--- | :--- |
| LEVL | Parameter display <br> level | EASY | EASY: Easy setting mode <br> STD: Standard setting mode <br> PRO: Professional setting mode | STD |

# General Specifications 

## Overview

The UT32A entry model digital indicating controller is an easily configurable single-loop controller that can generate relay, voltage pulse, or current signals for control output. The short depth of the controller helps save instrument panel space.

## Features

- A 14-segment, active (PV display color changing function) color LCD display is employed.
Two five-digit, high-resolution displays are possible. Alphabet letters can be displayed in an easy-to-read manner. The guide display shows parameter names.
- Easy to operate Navigation keys (SET/ENTER and Up/Down/Left/ Right arrow keys) are employed to facilitate making settings.
- 65 mm depth

The small depth enables the mounting in a thin and small instrumented panel.

- Quick setting function

Setting only the minimum necessary parameters for operation is possible.

- Equipped with a multitude of functions Universal I/O is included as standard. PID control, ON/OFF control, etc. are available.
- LL50A Parameter Setting Software (sold separately) The parameters of UTAdvanced digital indicating controller can be built from a PC using this software.
It makes data management even easier.
- Dust-proof and drip-proof IP66 (for front panel) (Not applicable to side-by-side close mounting.)
NEMA4 (Hose-down test only)


## $\square$ Functional Specifications

## Control Specifications

(1) Control Mode

Single-loop control
(2) Control period

200 ms

## Control Computation Function

(1) Types of control

- PID control
- ON/OFF control
(2) Control Computation Function
(a) Target setting point and the number of PID parameter groups
Respectively, four sets of target setpoints, alarm setpoints, and PID parameters can be set.

(b) Selecting the PID parameter group

The following PID parameter groups can be selected.

- Target setpoint number (SPNO) (The PID number can be set arbitrarily.)
- Measured input zone PID
- Target setpoint zone PID
- Reached target setpoint zone PID
(c) Auto-tuning
- Tuning results can be selected from two options, Normal or Stable.
- Tuning output limit can be set.
(d) "Super" function: Overshoot-suppressing function
(e) "Super 2" function: Hunting-suppressing function
(f) STOP preset output function
(g) Input ERROR preset output function
(h) MANUAL preset output function


## (3) Operation Mode Switching

| Operation mode <br> switching | AUTO/MANUAL and RUN/STOP switching |
| :---: | :--- |

(4) Control Parameter Setting Range

| Proportional band | 0.1 to $999.9 \%$ |
| :---: | :--- |
| Integral time | 1 to 6000 sec . or OFF (using manual reset) |
| Derivative time | 1 to 6000 sec . or OFF |
| ON/OFF control <br> hysteresis (one or two <br> hysteresis points) | 0.0 to $100.0 \%$ of measured input range width |
| Preset output <br> value | -5.0 to $105.0 \%$ (however, 0 mA or less cannot <br> be output) |
| High/low output <br> limiter | -5.0 to $105.0 \%$ <br> Low limit setpoint < high limit setpoint |
| Tight shut <br> function | When manual control is carried out with 4 to <br> 20 mA output, control output can be reduced to <br> about 0 mA. |
| Rate-of-change <br> limiter of output | 0.1 to $100.0 \% /$ sec., OFF |

## Alarm Functions

- Types of Alarm

| Measured value <br> alarm <br> Deviation alarm <br> Rate-of-change <br> alarm | PV (measured value) high/low limit alarm <br> Deviation high/low limit alarm <br> Deviation high and low limits alarm <br> Deviation within high and low limits alarm <br> Analog input PV high/low limit alarm <br> PV rate-of-change alarm |
| :---: | :--- |
| Setpoint alarm | SP (setpoint) high/low limit alarm <br> Target SP high/low limit alarm <br> Target SP deviation high/low limit alarm <br> Target SP deviation high and low limits alarm <br> Target SP deviation within high and low limits alarm |
| Output alarm | Control output high/low limit alarm |
| Other alarms | Self-diagnosis alarm <br> FAIL |

- Alarm Functions

$\left.$| Alarm output |
| :---: | :--- |
| action |$\quad$| Alarm stand-by action |
| :--- |
| Alarm latch (forced reset) function |
| Alarm hysteresis |
| Alarm ON/OFF delay timer | \right\rvert\, | Number of alarm <br> settings | 4 |
| :---: | :---: |
| Number of alarm <br> output points | 2 |

## Communication Function

|  | Function | Method | Interface | Targets | Max connection | Communication Data |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Modbus (RTU/ASCII) | A standard industry protocol allowing communications between the controller and devices such as PCs, PLCs, and DCSs. | Slave | RS-485 | PLC and others, UT75A/UT55A/ UT52A/UT35A/UT32A/UP55A/ UP35A/UP32A/UM33A ${ }^{(1)}$ | 31 units | PV, ALM etc |
| PC link | The proprietary Yokogawa protocol allowing communications to PCs, PLCs and touch panels. |  |  |  |  |  |
| Ladder | A protocol to communicate to PLCs. |  |  |  |  |  |

*1: UT digital indication controllers can be connected.

## Physical Interface

## RS-485

Standard: EIA RS-485
Communication method: Two-wire harf-duplex or four-wire harf-duplex, start-stop synchronization, and non-procedural
Baud rate: 600,1200,2400,4800,9600,19200 or 38400bps
Maximum communication distance: 1200 m
Terminating resistor: $220 \Omega$ (External)

## Hardware Specifications

## Display Specifications

- PV display

5-digit, 14-segment active color LCD (white/red)
Character height: 13.0 mm

- Data display

5 -digit, 11-segment color LCD (orange)

- Bar graph display

12-segment color LCD (orange)

## Universal Input Specifications

- Number of input points: 1
- Types of input, instrument range, and measurement accuracy (see the table below)

| Types of input |  | Instrument range |  | Accuracy |
| :---: | :---: | :---: | :---: | :---: |
|  |  | ${ }^{\circ} \mathrm{C}$ | ${ }^{\circ} \mathrm{F}$ |  |
| әןdnoэowגəપ」 | K | -270.0 to $1370.0^{\circ} \mathrm{C}$ | -450.0 to $2500.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit for $0^{\circ} \mathrm{C}$ or more $\pm 0.2 \%$ of instrument range $\pm 1$ digit for less than $0^{\circ} \mathrm{C}$ <br> However, $\pm 2 \%$ of instrument range $\pm 1$ digit for less than $-200^{\circ} \mathrm{C}$ of thermocouple $\mathrm{K} \pm 1 \%$ of instrument range $\pm 1$ digit for less than $-200^{\circ} \mathrm{C}$ of thermocouple T |
|  |  | -270.0 to $1000.0^{\circ} \mathrm{C}$ | -450.0 to $2300.0^{\circ} \mathrm{F}$ |  |
|  |  | -200.0 to $500.0^{\circ} \mathrm{C}$ | -200.0 to $1000.0^{\circ} \mathrm{F}$ |  |
|  | J | -200.0 to $1200.0^{\circ} \mathrm{C}$ | -300.0 to $2300.0^{\circ} \mathrm{F}$ |  |
|  | T | -270.0 to $400.0^{\circ} \mathrm{C}$ | -450.0 to $750.0^{\circ} \mathrm{F}$ |  |
|  |  | 0.0 to $400.0^{\circ} \mathrm{C}$ | -200.0 to $750.0^{\circ} \mathrm{F}$ |  |
|  | B | 0.0 to $1800.0^{\circ} \mathrm{C}$ | 32 to $3300{ }^{\circ} \mathrm{F}$ | $\pm 0.15 \%$ of instrument range $\pm 1$ digit for $400^{\circ} \mathrm{C}$ or more $\pm 5 \%$ of instrument range $\pm 1$ digit for less than $400^{\circ} \mathrm{C}$ |
|  | S | 0.0 to $1700.0^{\circ} \mathrm{C}$ | 32 to $3100^{\circ} \mathrm{F}$ | $\pm 0.15 \%$ of instrument range $\pm 1$ digit |
|  | R | 0.0 to $1700.0^{\circ} \mathrm{C}$ | 32 to $3100^{\circ} \mathrm{F}$ |  |
|  | N | -200.0 to $1300.0^{\circ} \mathrm{C}$ | -300.0 to $2400.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit $\pm 0.25 \%$ of instrument range $\pm 1$ digit for less than $0^{\circ} \mathrm{C}$ |
|  | E | -270.0 to $1000.0^{\circ} \mathrm{C}$ | -450.0 to $1800.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit for $0^{\circ} \mathrm{C}$ or more $\pm 0.2 \%$ of instrument range $\pm 1$ digit for less than $0^{\circ} \mathrm{C}$ However, $\pm 1.5 \%$ of instrument range $\pm 1$ digit for less than $-200.0^{\circ} \mathrm{C}$ of thermocouple E |
|  | L | -200.0 to $900.0^{\circ} \mathrm{C}$ | -300.0 to $1600.0^{\circ} \mathrm{F}$ |  |
|  | U | -200.0 to $400.0^{\circ} \mathrm{C}$ | -300.0 to $750.0^{\circ} \mathrm{F}$ |  |
|  |  | 0.0 to $400.0^{\circ} \mathrm{C}$ | -200.0 to $1000.0^{\circ} \mathrm{F}$ |  |
|  | $W^{(2)}$ | 0.0 to $2300.0^{\circ} \mathrm{C}$ | 32 to $4200^{\circ} \mathrm{F}$ | $\pm 0.2 \%$ of instrument range $\pm 1$ digit |
|  | Platinel 2 | 0.0 to $1390.0^{\circ} \mathrm{C}$ | 32.0 to $2500.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit |
|  | PR20-40 | 0.0 to $1900.0^{\circ} \mathrm{C}$ | 32 to $3400^{\circ} \mathrm{F}$ | $\pm 0.5 \%$ of instrument range $\pm 1$ digit for $800^{\circ} \mathrm{C}$ or more Accuracy not guaranteed for less than $800^{\circ} \mathrm{C}$ |
|  | $\begin{array}{\|c\|} \hline \text { W97 } \\ \text { Re3-W75 } \\ \text { Re25 } \\ \hline \end{array}$ | 0.0 to $2000.0^{\circ} \mathrm{C}$ | 32 to $3600^{\circ} \mathrm{F}$ | $\pm 0.2 \%$ of instrument range $\pm 1$ digit |
|  | JPt100 | -200.0 to $500.0^{\circ} \mathrm{C}$ | -300.0 to $1000.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit ${ }^{\left({ }^{(1)}\right.}$ |
|  |  | -150.00 to $150.00^{\circ} \mathrm{C}$ | -200.0 to $300.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit |
|  |  | -200.0 to $850.0^{\circ} \mathrm{C}$ | -300.0 to $1560.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit ${ }^{(41)}$ |
|  |  | -200.0 to $500.0^{\circ} \mathrm{C}$ | -300.0 to $1000.0^{\circ} \mathrm{F}$ |  |
|  | Pt100 | -150.00 to $150.00^{\circ} \mathrm{C}$ | -200.0 to $300.0^{\circ} \mathrm{F}$ | $\pm 0.1 \%$ of instrument range $\pm 1$ digit |
| Standard signal |  | 0.400 to 2.0000 V | - | $\pm 0.1 \%$ of instrument range $\pm 1$ digit |
|  |  | 1.000 to 5.000 V | - |  |
|  |  | 4.00 to 20.00 mA | - |  |
| DC voltage |  | 0.000 to 2.000 V | - |  |
|  |  | 0.00 to 10.00 V | - |  |
|  |  | -10.00 to 20.00 mV | - |  |
| DC | current | 0.00 to 20.00 mA | - |  |

The accuracy is that in the standard operating conditions: $23 \pm 2^{\circ} \mathrm{C}, 55 \pm 10 \% \mathrm{RH}$, and power frequency at $50 / 60 \mathrm{~Hz}$.
*1: $\quad \pm 0.3^{\circ} \mathrm{C}$ and $\pm 1$ digit in the range between 0 and $100^{\circ} \mathrm{C}$ $\pm 0.5^{\circ} \mathrm{C} \pm 1$ digit in the range between -100 and $200^{\circ} \mathrm{C}$
*2: W-5\% Re/W-26\% Re (Hoskins Mfg.Co.), ASTM E988

- Applicable standards: JIS, IEC and DIN (ITS-90) for thermocouples and resistance-temperature detectors (RTD)
- Input sampling period: Synchronized to control period
- Burnout detection

Upscale and downscale of function, and OFF can be specified for the standard signal of thermocouple and resistance-temperature detector (RTD).
For integrated signal input, 0.1 V or 0.4 mA or less is judged as a burnout.

- Input bias current: $0.05 \mu \mathrm{~A}$ (for thermocouple and resistance-temperature detector (RTD))
- Resistance-temperature detector (RTD) measured current: About 0.16 mA
- Input resistance
$1 \mathrm{M} \Omega$ or more for thermocouple $/ \mathrm{mV}$ input
About $1 \mathrm{M} \Omega$ for voltage input
About $250 \Omega$ for current input (with built-in shunt resistance)
- Allowable signal source resistance
$250 \Omega$ or less for thermocouple/mV input
Effect of signal source resistance: $0.1 \mu \mathrm{~V} / \Omega$ or less
$2 \mathrm{k} \Omega$ or less for $D C$ voltage input
Effect of signal source resistance: about $0.01 \% / 100 \Omega$
- Allowable wiring resistance

Up to $150 \Omega$ per line for resistance-temperature detector (RTD) input (conductor resistance
between the three lines shall be equal)
Effect of wiring resistance: $\pm 0.1^{\circ} \mathrm{C} / 10 \Omega$

- Allowable input voltage/current
$\pm 10 \mathrm{~V}$ DC for thermocouple $/ \mathrm{mV} / \mathrm{mA}$ or resistance-
temperature detector (RTD) input
$\pm 20 \mathrm{~V}$ DC for V input
$\pm 40 \mathrm{mADC}$ for mA input
- Noise reduction ratio

40 dB or more (at $50 / 60 \mathrm{~Hz}$ ) in normal mode 120 dB or more (at $50 / 60 \mathrm{~Hz}$ ) in common mode

- Reference junction compensation error
$\pm 1.0^{\circ} \mathrm{C}\left(15\right.$ to $\left.35^{\circ} \mathrm{C}\right)$
$\pm 1.5^{\circ} \mathrm{C}\left(-10\right.$ to $5^{\circ} \mathrm{C}$ and 35 to $\left.50^{\circ} \mathrm{C}\right)$


## Analog Output Specifications (Suffix code: -C)

- Number of points Control output: 1 point
- Output functions

Current output

- Current output

4 to 20 mA DC or 0 to $20 \mathrm{~mA} \mathrm{DC/load} \mathrm{resistance}$ $600 \Omega$ or less

- Current output accuracy
$\pm 0.1 \%$ of span (however, $\pm 5 \%$ of span for 1 mA or less)
The accuracy is that in the standard operating conditions: $23 \pm 2^{\circ} \mathrm{C}, 55 \pm 10 \% \mathrm{RH}$, and power frequency at $50 / 60 \mathrm{~Hz}$


## Analog Output Specifications (Suffix code: -V)

- Number of points

Control output: 1 point

- Output functions Voltage pulse output
- Current output

4 to 20 mA DC or 0 to $20 \mathrm{~mA} \mathrm{DC/load} \mathrm{resistance}$ $600 \Omega$ or less

- Voltage pulse output

Application: time proportional output
ON voltage: 12 V or more/load resistance of 600
$\Omega$ or more
OFF voltage: 0.1 V DC or less
Time resolution: 10 ms or $0.1 \%$ of output value, whichever is larger
Contact Input Specifications (Suffix code: -R)

- Types of contact and number of points Control relay output: one, 1c-contact point
- Input type: no-voltage contact input or transistor contact input
- Contact rating

1c-contact: 3 A at 250 V AC or 3 A at 30 V DC (resistance load)
*: The control output should always be used with a load of 10 mA or more.

- Application: ON/OFF output or time proportional output
- Time resolution for control output: 10 ms or $0.1 \%$ of output value, whichever is larger


## Relay Contact Output Specifications

- Types of contact and number of points

Alarm output: 2, 1a-contact points (Common is separated)

- Contact rating

1a-contact:
For alarm output: 1 A at 240 V AC or 1 A at 30 V DC (resistance load)
*: The alarm output should always be used with a load of 1 mA or more.

- Application: alarm output, FAIL output, etc.


## 24 V DC Loop Power Supply Specifications (for /LP Option)

- Application: Power is supplied to the 2-wire transmitter.
- Supply voltage: 21.6 to 28.0 V DC
- Rated current: 4 to 20 mADC
- Maximum supply current: About 30 mA (with shortcircuit current limiting circuit)


## Safety and EMC Standards

- Safety:

Compliant with IEC/EN 61010-1 (CE), IEC/EN 61010-2-201 (CE), IEC/EN 61010-2-030 (CE), approved by CAN/CSA C22.2 No. 61010-1 (CSA), approved by UL 61010-1.

Installation category: II
Pollution degree: 2
Measurement category: I (CAT I) (UL, CSA)

$$
\mathrm{O} \text { (Other) (CE) }
$$

Rated measurement input voltage: Max. 10 V DC
Rated transient overvoltage: $1500 \mathrm{~V}\left({ }^{*}\right)$
*: This is a reference safety standard value for measurement category I of CSA/UL 61010-1, and for measurement category O of IEC/EN 61010-2-030. This value is not necessarily a guarantee of instrument performance.

- EMC standards:

Compliant with
CE marking
EN 61326-1 Class A, Table 2 (For use in industrial locations),
EN 61326-2-3
*: The instrument continues to operate at a measurement accuracy of within $\pm 20 \%$ of the range during testing.

## EN 55011 Class A, Group 1 <br> EN 61000-3-2 Class A <br> EN 61000-3-3

EMC Regulatory Arrangement in Australia and New Zealand EN 55011 Class A, Group 1

- KC marking: Electromagnetic wave interference prevention standard, electromagnetic wave protection standard compliance


## Power Supply Specifications and Isolation

- Power supply

Rated voltage: 100 to 240 V AC (+10\%/-15\%), $50 / 60 \mathrm{~Hz}$ 24 V AC/DC (+10\%/-15\%) (When the /DC option is specified)

- Power consumption: 15 VA (For the /DC option. DC: $7 \mathrm{VA}, \mathrm{AC}: 11 \mathrm{VA})$
- Storage: Nonvolatile memory
- Allowable power interruption time: 20 ms (at 100 V AC)
- Withstanding voltage

2300 V AC for 1 minute between primary and
secondary terminals (UL, CSA)
3000 V AC for 1 minute between primary and secondary terminals (CE)
1500 V AC for 1 minute between primary terminals 500 V AC for 1 minute between secondary terminals
(Primary terminals $=$ Power ( ${ }^{*}$ ) and relay output terminals, Secondary terminals = Analog I/O signal terminals, communication terminals,
and functional grounding terminals.)
*: Power terminals for $24 \mathrm{~V} \mathrm{AC/DC}$ models are the secondary terminals.

- Insulation resistance

Between power supply terminals and a grounding
terminal: $20 \mathrm{M} \Omega$ or more at 500 V DC

- Isolation specifications

| PV (universal) input terminal |  |  |
| :--- | :--- | :--- |
| Control (voltage pluse, analog) output terminal <br> Control relay (c-contact) output terminal |  |  |
| Alarm-1 relay (a-contact) output terminal | Internal <br> circuits | Power <br> supply |
| Alarm-2 relay (a-contact) output terminal |  |  |
| RS485 communication terminal |  |  |
| 24 V DC loop power supply terminal |  |  |

[^4]
## Environmental Conditions

Normal operating conditions

- Ambient temperature: -10 to $50^{\circ} \mathrm{C}\left(-10\right.$ to $40^{\circ} \mathrm{C}$ for side-by-side mounting of controllers)
- Ambient humidity: 20 to $90 \%$ RH (no condensation)
- Magnetic field: $400 \mathrm{~A} / \mathrm{m}$ or less
- Continuous vibration (at 5 to 9 Hz ) Half amplitude of 1.5 mm or less
(at 9 to 150 Hz ) $4.9 \mathrm{~m} / \mathrm{s}^{2}$ or less, $1 \mathrm{oct} / \mathrm{min}$ for 90 min utes each in the three axis directions
- Rapid vibration: $14.7 \mathrm{~m} / \mathrm{s}^{2}, 15 \mathrm{~s}$ or less
- Impact: $98 \mathrm{~m} / \mathrm{s}^{2}$ or less, 11 msec .
- Installation altitude: $2,000 \mathrm{~m}$ or less above sea level
- Warm-up time: 30 minutes or more after the power is turned on
- Start-up time within 10 s


## Transportation and Storage Conditions

- Temperature: -25 to $70^{\circ} \mathrm{C}$
- Temperature change rate: $20^{\circ} \mathrm{C}$ per hour or less
- Humidity: 5 to $95 \%$ RH (no condensation)


## Effects of Operating Conditions

- Effect of ambient temperature For voltage or TC input:
$\pm 1 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$ or $\pm 0.01 \%$ of $\mathrm{F} . \mathrm{S}$. (instrument range) $/{ }^{\circ} \mathrm{C}$, whichever is greater
For RTD input: $\pm 0.05^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{C}$ (ambient temperature) or less
For current input: $\pm 0.01 \%$ of $\mathrm{F} . \mathrm{S}$. (instrument range) $/{ }^{\circ} \mathrm{C}$
For analog output: $\pm 0.02 \%$ of $\mathrm{F} . \mathrm{S} .{ }^{\circ}{ }^{\circ} \mathrm{C}$ or less
- Effect of power supply fluctuation:

For analog input: $\pm 0.05 \%$ of F.S. (instrument range) or less
For analog output: $\pm 0.05 \%$ of F.S. or less
(Each within rated voltage range)

## Block Diagram

## Single Loop Control



## Terminal Arrangement




Factory default:
PV input type is
undefined.

## Power supply

(Suffix code: Type1=-V or -C)


## External Dimensions and Panel Cutout Dimensions



■ Construction, Mounting, and Wiring

- Dust-proof and drip-proof: IP66 (Front panel) (Except for side-by-side close mounting)/NEMA4 * *: Hose-down test only
- Material: Polycarbonate resin (Flame retardancy: UL94 V-0)
- Case color: White (Light gray) or Black (Light Charcoal gray)
- Weight: 0.5 kg or less
- External dimensions (mm): 48 (width) x 96 (height) x 65 (depth from the panel surface)
- Mounting: Direct panel mounting; mounting bracket, one each for upper and lower mounting
- Panel cutout dimensions (mm): 45+ ${ }^{0.6 / 6}$ (width) $\times 92^{+0.810}$ (height)
- Mounting position: Up to 30 degrees above the horizontal. No downward titling allowed.
- Wiring: M3 screw terminal with square washer (signal wiring and power)


## $\square$ Model and Suffix Code


*1: When the /LP option is specified, the RS-485 communication of the Type 2 code "1" is 2-wire system.
*2: English, German, French, and Spanish are available for the guide display.
*3: When the /CT option is specified, the UT32A does not conform to the safety standards (UL and CSA) and CE marking (Products with /CT option are not intended for EEA-market).
$\square$ Items to be specified when ordering
Model and suffix codes, whether User's Manual and QIC required.

## Standard accessories

Brackets (mounting hardware), Unit label, Operation Guide

## Special Order Items

| Model code | Suffix code | Description |
| :---: | :--- | :--- |
| LL50A | -00 | Parameter Setting Software |
| X010 | See the General Specifications (*) | Resistance Module |

*: Necessary to input the current signal to the voltage input terminal.

| Name | Model |
| :--- | :---: |
| Terminal cover (for UT32A) | UTAP002 |
| User's Manual (CD) | UTAP003 |

User's Manual
Product user's manuals can be downloaded or viewed at the following URL. To view the user's manual, you need to use Adobe Reader 7 or later by Adobe Systems.
URL: http://www.yokogawa.com/ns/ut/im/

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[^0]:    "Handle with Care" (This symbol is attached to the part(s) of the product to indicate that the user's manual should be referred to in order to protect the operator and the instrument from harm.)

    AC
    AC/DC
    The equipment wholly protected by double insulation or reinforced insulation.
    Functional grounding terminal (Do not use this terminal as a protective grounding terminal.)

[^1]:    Displayed only in cases where the communication is specified.

[^2]:    Note
    When changing the setpoint of the parameter PIDG., if the setpoint of the parameter PIDN which belongs to the SP menu is larger than that of the parameter PIDG., the PIDN setpoint is changed to the PIDG. setpoint.

[^3]:    Display level: 13.3.2 Setting Parameter Display Level

[^4]:    The circuits divided by lines are insulated mutually

