



# Application Note

## AN\_395

# User Guide for LibFT260

**Version 1.2**

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The FT260 is a USB device which supports I<sup>2</sup>C and UART communication through the standard USB HID interface. This application note is a guide for LibFT260, which provides high-level and convenient APIs for FT260 application development.

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# 1 Introduction

## 1.1 Overview

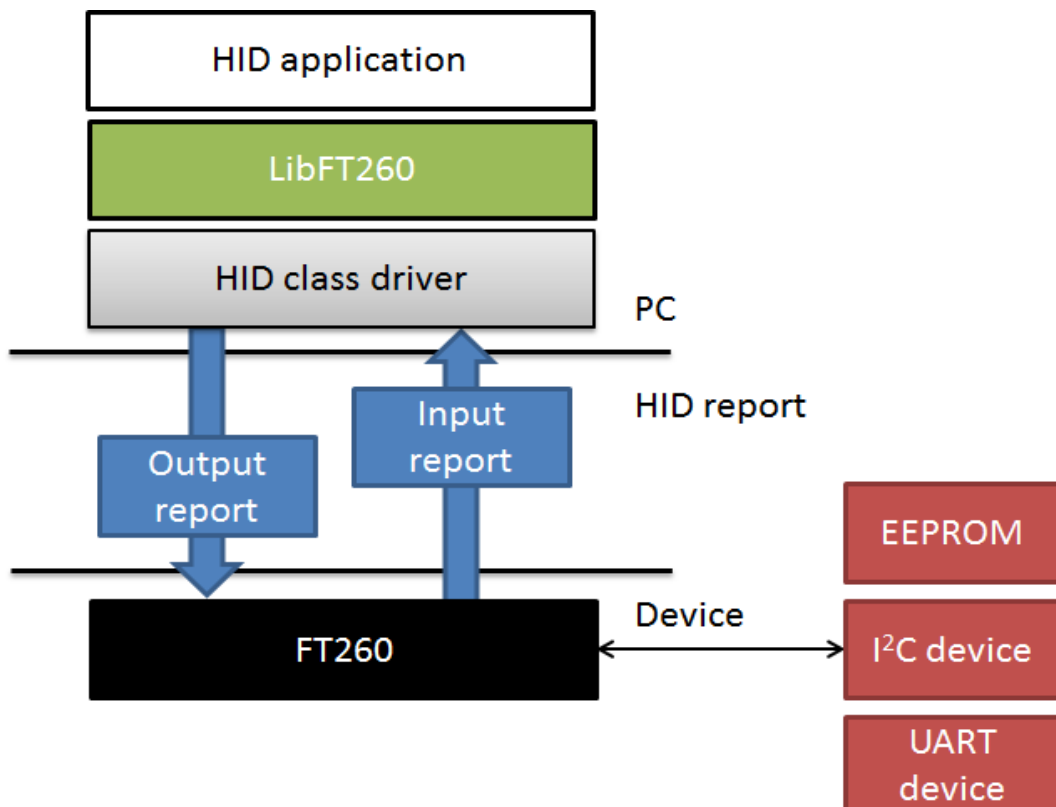
The FT260 is a full speed USB device which supports I<sup>2</sup>C and UART communication through standard USB HID interfaces. The USB HID class is natively supported by most operating systems. A custom driver is not required to be installed for the FT260. By default, the FT260 has two HID interfaces:

- The first HID interface sends and receives data via the **I<sup>2</sup>C** connection.
- The second HID interface sends and receives data via the **UART** connection.
- The HID interface can be configured by the DCF0 and DCF1 pins.

The USB HID class exchanges data between a host and a device by reports. There are three types of reports in USB HID:

1. **Feature report:** Configuration data are exchanged between the host and the HID device through a control pipe. The feature report is usually used to turn on/off a device function.
2. **Input report:** Data content that is sent from the HID device to the host.
3. **Output report:** Data content that is sent from the host to the HID device.

The FT260 device receives output reports from the HID application, decodes the requests, and passes the data to the connected I<sup>2</sup>C or UART device. Data received from the I<sup>2</sup>C or UART device is sent to the host by input reports.



**Figure 1.1 The FT260 System Block Diagram**

## 1.2 FT260 HID Interfaces and Endpoints

### 1.2.1 Interfaces

The FT260 interfaces can be configured as:

- **I<sup>2</sup>C** and **UART**
- **I<sup>2</sup>C** only
- **UART** only

The interfaces can be configured by mode pins: DCNF0 and DCNF1.

DCNF1	DCNF0	HID Interfaces
0	0	The default mode. The FT260 will create two HID interfaces: <b>I<sup>2</sup>C</b> and <b>UART</b> . This mode is the same as mode (1,1).
0	1	The FT260 will create a HID interface which sends and receives data via the <b>I<sup>2</sup>C</b> connection.
1	0	The FT260 will create a HID interface which sends and receives data via the <b>UART</b> connection.
1	1	The FT260 will create two HID interfaces: <ul style="list-style-type: none"> <li>• The first HID interface sends and receives data via the <b>I<sup>2</sup>C</b> connection.</li> <li>• The second HID interface sends and receives data via the <b>UART</b> connection.</li> </ul>

**Table 1.1 FT260 interface configuration**

### 1.2.2 Endpoints

An interface of the FT260 is composed of the following endpoints:

Endpoint	Usage
Control In	Input reports, Feature reports sent to the host with a GET_REPORT request
Control Out	Output reports, Feature reports received from the host with a SET_REPORT request
Interrupt In	Input reports
Interrupt Out	Output reports

**Table 1.2 FT260 endpoints**

### **1.3 Scope**

The guide is intended for developers who are creating applications, extending FTDI provided applications or implementing FTDI's applications for the FT260.

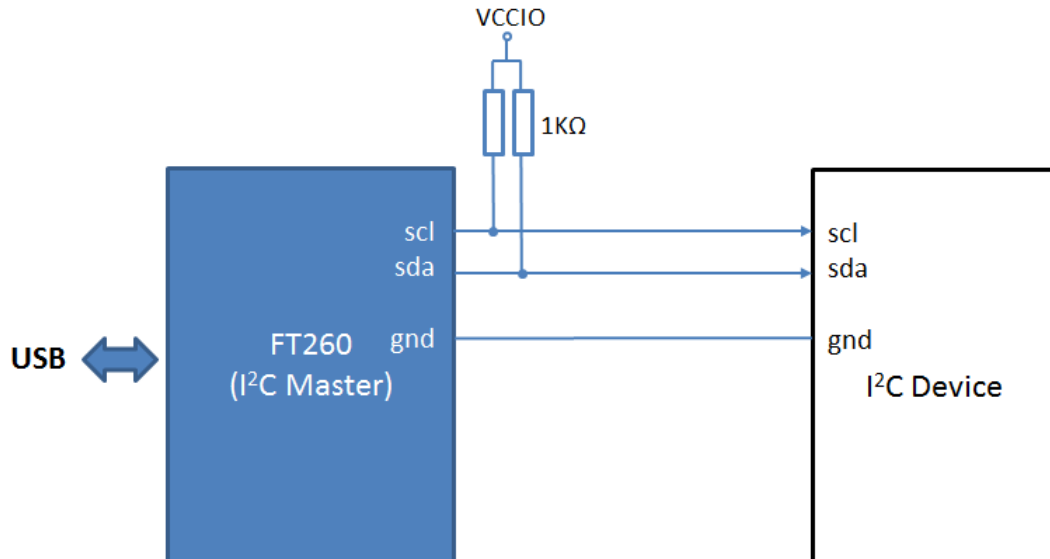
The support library, LibFT260, hides the detail of communicating by HID protocol and provides simple APIs for developers to create their own applications.

The sample source code provided in this application note is an example and is neither guaranteed nor supported by FTDI.

## 2 Wiring

### 2.1 I<sup>2</sup>C

The FT260 I<sup>2</sup>C is open-drain architecture. It requires a suitable pull-high resistor on the I<sup>2</sup>C bus.



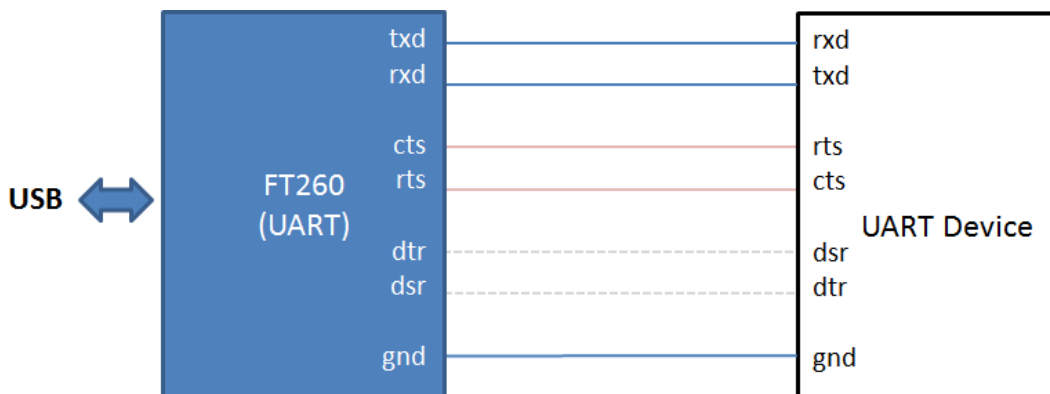
**Figure 2.1 The FT260 connects with I<sup>2</sup>C bus**

### 2.2 UART

The FT260 UART supports 3 flow control modes:

- Software flow control (default)
- Hardware flow control by CTS and RTS
- Hardware flow control by DTR and DSR

Software flow control mode is the default flow control mode of the FT260 and it has the simplest wiring. It only requires connecting TXD, RXD and GND. CTS, RTS, and DTR, DSR are optional for hardware flow control.



**Figure 2.2 The FT260 connects to an UART device**



### 3 Getting Started

This example shows how to open the device with the LibFT260 support library. After opening the device, developers need to initialize the FT260 device as either an I<sup>2</sup>C master or a UART. Different device types require different configurations. For more details refer to chapter 4.

#### Example

```
#include <windows.h>
#include <stdio.h>
#include <stdlib.h>
#include "LibFT260.h"
#define MASK_1 0x0f

void ListAllDevicePaths()
{
    DWORD devNum = 0;
    WCHAR pathBuf[128];

    FT260_CreateDeviceList(&devNum);

    for(int i = 0; i < devNum; i++)
    {
        FT260_GetDevicePath(pathBuf, 128, i);
        wprintf(L"Index:%d\nPath:%s\n\n", i, pathBuf);
    }
}

int main(int argc, char const* argv[])
{
    FT260_STATUS ftStatus = FT260_OTHER_ERROR;
    FT260_HANDLE ft260Handle = INVALID_HANDLE_VALUE;
    DWORD devNum = 0;

    ListAllDevicePaths();

    // Open device by index
    ftStatus = FT260_Open(0, & ft260Handle);
    if (FT260_OK != ftStatus) {
        printf("Open device Failed, status: %d\n", ftStatus);
        return 0;
    }
    else {
        printf("Open device OK\n");
    }

    // Show version information

    DWORD dwChipVersion = 0;

    ftStatus = FT260_GetChipVersion(ft260Handle, &dwChipVersion);
    if (FT260_OK != ftStatus)
    {
        printf("Get chip version Failed, status: %d\n", ftStatus);
    }
    else
    {
        printf("Get chip version OK\n");
        printf("Chip version : %d.%d.%d.%d\n",
            ((dwChipVersion >> 24) & MASK_1),
            ((dwChipVersion >> 16) & MASK_1),
            ((dwChipVersion >> 8) & MASK_1),
            (dwChipVersion & MASK_1) );
    }
}
```

```
}  
// Initialize as an I2C master, and read/write data to an I2C slave  
// FT260_I2CMaster_Init  
// FT260_I2CMaster_Read  
// FT260_I2CMaster_Write  
  
// Close device  
FT260_Close(ft260Handle);  
return 0;  
}
```

## 4 Application Programming Interface (API)

LibFT260 supports I<sup>2</sup>C, UART and GPIO communication by using high-level APIs. In addition, it provides chip configuration APIs, such as FT260\_SetClock. After opening the FT260 device, the FT260 could be initialized by one of the following initial functions:

- FT260\_I2CMaster\_Init
- FT260\_UART\_Init

The initialization functions set up the FT260 for the subsequent operations.

Refer to "[Appendix C – FT260 STATUS](#)" for the definitions of the error code of following functions.

### 4.1 FT260 General Functions

The functions listed in this section are configuration functions for the FT260.

#### 4.1.1 FT260\_CreateDeviceList

FT260\_STATUS **FT260\_CreateDeviceList** (LPDWORD lpdwNumDevs)

**Summary:**

Create device list and get the number of HID devices.

**Note:** The call creates a list for all HID devices, not only FT260 devices.

**Parameters:**

lpdwNumDevs	Pointer to a variable for retrieving the number of HID devices.
-------------	---

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.1.2 FT260\_GetDevicePath

FT260\_STATUS **FT260\_GetDevicePath**(WCHAR\* pDevicePath, DWORD bufferLength, DWORD deviceIndex)

**Summary:**

Get device path by index.

**The device path data would be of a format such as shown below:**

[\\?\hid#vid\\_0403&pid\\_6030&mi\\_00#8&1d5b3f5a&0&0000#{4d1e55b2-f16f-11cf-88cb-001111000030}](#)

**Parameters:**

pDevicePath	Pointer to the buffer for getting data.
bufferLength	The maximum number of characters to store. Note that the device path is WCHAR.
deviceIndex	The index of the device, which is 0 based.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

### 4.1.3 FT260\_Open

FT260\_STATUS **FT260\_Open**(int iDevice, FT260\_HANDLE\* pFt260Handle)

**Summary:**

Open device by index.

**Parameters:**

iDevice	The index of the device, which is 0 based.
pFt260Handle	Pointer to a variable of type FT260_HANDLE where the handle will be stored. This handle must be used to access the device.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

### 4.1.4 FT260\_OpenByVidPid

FT260\_STATUS **FT260\_OpenByVidPid**(WORD vid, WORD pid, DWORD deviceIndex, FT260\_HANDLE\* pFt260Handle)

**Summary:**

Open device by the given VID, PID and index.

For example, call this function with VID, PID and index:0, 1 and 2 when there are three devices with the same VID and PID.

**Parameters:**

vid	USB vendor ID.
pid	USB product ID
deviceIndex	The index of the device, which is 0 based. There might be several devices with the same VID/PID. Use the index to select the device.
pHandle	Pointer to a variable of type FT260_HANDLE where the handle will be stored. This handle must be used to access the device.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.1.5 FT260\_OpenByDevicePath

FT260\_STATUS **FT260\_OpenByDevicePath**(WCHAR\* pDevicePath, FT260\_HANDLE\* pFt260Handle)

**Summary:**

Open device by path.

**Parameters:**

pDevicePath	the device path to be opened
pFt260Handle	Pointer to a variable of type FT260_HANDLE where the handle will be stored. This handle must be used to access the device.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.1.6 FT260\_Close

FT260\_STATUS **FT260\_Close**(FT260\_HANDLE ft260Handle)

**Summary:**

Close the device.

**Parameters:**

ft260Handle	Handle of the device.
-------------	-----------------------

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.1.7 FT260\_GetChipVersion

FT260\_STATUS **FT260\_GetChipVersion**(FT260\_HANDLE ft260Handle, LPDWORD lpdwChipVersion )

**Summary:**

Get the chip version of the FT260 device.

**Version 1.0.0.0 is shows as 16777216 in decimal.**

**Parameters:**

ft260Handle	Handle of the device.
lpdwChipVersion	Pointer to a variable for retrieving the chip version.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.1.8 FT260\_GetLibVersion

FT260\_STATUS **FT260\_GetLibVersion**(LPDWORD lpdwLibVersion)

**Summary:**

Get the library version of the FT260 support library.

**Parameters:**

lpdwLibVersion	Pointer to a variable for retrieving the library version.
----------------	---

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.1.9 FT260\_SetClock

FT260\_STATUS **FT260\_SetClock** FT260\_SetClock(FT260\_HANDLEft260Handle, FT260\_Clock\_Rate clk)

**Summary:**

Set system clock rate. The default clock rate of the FT260 is 48 MHz.

A lower system clock rate will have lower power consumption, and it may also affect maximum transfer rates.

**Parameters:**

ft260Handle	Handle of the device.
Clk	System clock rate: <ul style="list-style-type: none"> <li>• FT260_SYS_CLK_12M</li> <li>• FT260_SYS_CLK_24M</li> <li>• FT260_SYS_CLK_48M</li> </ul>

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.1.10 FT260\_SetWakeupInterrupt

FT260\_STATUS **FT260\_SetWakeupInterrupt**(FT260\_HANDLEft260Handle, BOOL enable)

**Summary:**

Enable/Disable wakeup interrupt.

**Parameters:**

ft260Handle	Handle of the device.
enable	TRUE to enable and switch the pin mode to wakeup/interrupt FALSE to disable and switch the pin mode to GPIO3

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

**4.1.11 FT260\_SetInterruptTriggerType**

FT260\_STATUS **FT260\_SetInterruptTriggerType**(FT260\_HANDLE ft260Handle, FT260\_Interrupt\_Trigger\_Type type, FT260\_Interrupt\_Level\_Time\_Delay delay)

**Summary:**

Specify edge, level and duration of signals to generate interrupt.

**Parameters:**

ft260Handle	Handle of the device.
type	Trigger type: <ul style="list-style-type: none"> <li>• FT260_INTR_RISING_EDGE</li> <li>• FT260_INTR_LEVEL_HIGH</li> <li>• FT260_INTR_FALLING_EDGE</li> <li>• FT260_INTR_LEVEL_LOW</li> </ul>
delay	Specifies the minimum pulse width for level-based interrupts. When the voltage at the interrupt pin exceeds the level for the specified duration, the interrupt signal will be generated. This setting only affects trigger types that are level high or level low. <ul style="list-style-type: none"> <li>• FT260_INTR_DELAY_1MS</li> <li>• FT260_INTR_DELAY_5MS</li> <li>• FT260_INTR_DELAY_30MS</li> </ul>

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

**4.1.12 FT260\_SelectGpio2Function**

FT260\_STATUS **FT260\_SelectGpio2Function**(FT260\_HANDLE ft260Handle, FT260\_GPIO2\_Pin gpio2Function)

**Summary:**

Select the function of GPIO 2.

**Parameters:**

ft260Handle	Handle of the device.
gpio2Function	Set the active function of the pin GPIO2: <ul style="list-style-type: none"> <li>• FT260_GPIO2_GPIO GPIO 2, General Purpose I/O.</li> <li>• FT260_GPIO2_SUSPOUT SUSPOUT_N is the default functions to indicate entering the USB suspend state. Active Low. It can be configured as active high.</li> </ul>

	<ul style="list-style-type: none"> <li>• FT260_GPIO2_PWREN PWREN_N is as the power enable indicator when the FT260 is USB enumerated. Active Low.</li> <li>• FT260_GPIO2_TX_LED TX_LED is the LED driving source when data is transmitted on the UART TX port.</li> </ul>
--	---

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

### 4.1.13 FT260\_SelectGpioAFunction

FT260\_STATUS **FT260\_SelectGpioAFunction**(FT260\_HANDLE ft260Handle, FT260\_GPIOA\_Pin gpioAFunction)

**Summary:**

Select the function of GPIO A.

**Parameters:**

ft260Handle	Handle of the device.
gpioAFunction	Set the active function of the pin GPIOA: <ul style="list-style-type: none"> <li>• FT260_GPIOA_GPIO GPIO A, General Purpose I/O.</li> <li>• FT260_GPIOA_TX_ACTIVE TX_ACTIVE is the default function to indicate the UART transmitting is active.</li> <li>• FT260_GPIOA_TX_LED TX_LED is the LED driving source when data is transmitted on the UART TX port.</li> </ul>

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

### 4.1.14 FT260\_SelectGpioGFunction

FT260\_STATUS **FT260\_SelectGpioGFunction**(FT260\_HANDLE ft260Handle, FT260\_GPIOG\_Pin gpioGFunction)

**Summary:**

Select the function of GPIO G.

**Parameters:**

ft260Handle	Handle of the device.
gpioGFunction	Set the active function of the pin GPIOG:



	<ul style="list-style-type: none"> <li>• FT260_GPIOG_GPIO GPIO G, General Purpose I/O.</li>   <li>• FT260_GPIOG_PWREN PWREN_N is the power enable indicator when the FT260 is USB enumerated. Active low.</li>   <li>• FT260_GPIOG_RX_LED RX_LED is the LED driving source when data is received on the UART RX port.</li>   <li>• FT260_GPIOG_BCD_DET BCD_DET is the default function. A battery charger detection indicator output when the device is connected to a dedicated battery charger port. Polarity can be defined.</li> </ul>
--	--

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

**4.1.15 FT260\_SetSuspendOutPolarity**

FT260\_STATUS **FT260\_SetSuspendOutPolarity**(FT260\_HANDLE ft260Handle, FT260\_Suspend\_Out\_Polarity polarity)

**Summary:**

Set suspend out polarity.

**Parameters:**

ft260Handle	Handle of the device.
polarity	Suspend out level: <ul style="list-style-type: none"> <li>• FT260_SUSPEND_OUT_LEVEL_HIGH</li> <li>• FT260_SUSPEND_OUT_LEVEL_LOW</li> </ul>

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

**4.1.16 FT260\_SetUartToGPIOPin**

FT260\_STATUS **FT260\_SetUartToGPIOPin**(FT260\_HANDLE ft260Handle)

**Summary:**

Disable UART mode and switch pins to GPIO B, GPIO C, GPIO D, GPIO E, GPIO F and GPIO H.

**Parameters:**

ft260Handle	Handle of the device.
-------------	-----------------------

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

**4.1.17 FT260\_EnableDcdRiPin**

FT260\_STATUS **FT260\_EnableDcdRiPin**(FT260\_HANDLE ft260Handle, BOOL enable)

**Summary:**

Set UART DCD, RI function and switch pin function.

**Parameters:**

ft260Handle	Handle of the device.
enable	FALSE to disable UART DCD, UART RI, and switch the pins modes to GPIO4, GPIO5 TRUE to enable and switch the pins modes to UART DCD, UART RI

**Return Value:**

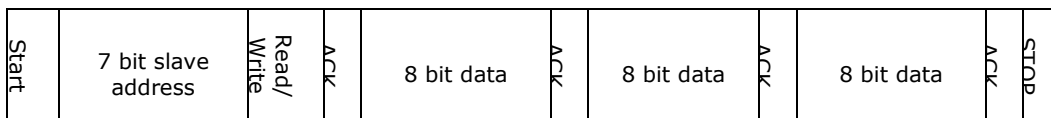
FT260\_OK if successful, otherwise the return value is an error code.

**4.2 I<sup>2</sup>C Master Functions**

I<sup>2</sup>C (Inter Integrated Circuit) is a multi-master serial bus invented by Philips. I<sup>2</sup>C uses two bi-directional open-drain wires called serial data (SDA) and serial clock (SCL). Common I<sup>2</sup>C bus speeds are the 100 kbit/s standard mode (SM), 400 kbit/s fast mode (FM), 1 Mbit/s Fast mode plus (FM+), and 3.4 Mbit/s High Speed mode (HS).

**I<sup>2</sup>C transaction**

All I<sup>2</sup>C transactions begin with a START condition, a slave address, a single bit representing write (0) or read (1), and are terminated by a STOP condition. All of them are always generated by the master.



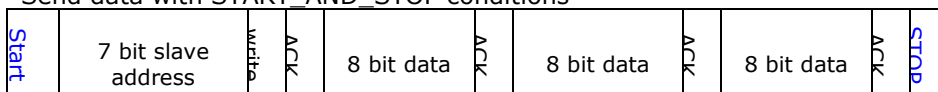
I<sup>2</sup>C defines three basic types of message:

- Single message where a master writes data to a slave;
- Single message where a master reads data from a slave;
- Combined messages, where a master issues at least two reads and/or writes to one or more slaves

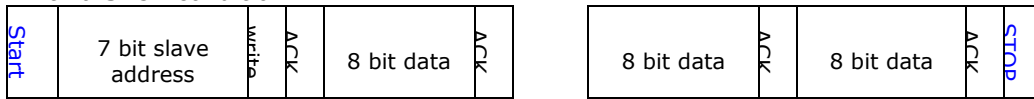
For more information on the protocol, refer to the I<sup>2</sup>C specification.

The FT260 provides flexibility to allow users to decide when to send START and STOP conditions. Here are some examples. The following scenarios are supported by the FT260.

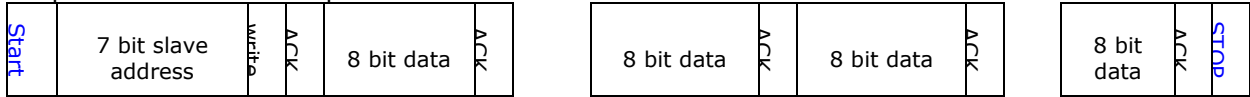
Send data with START\_AND\_STOP conditions



Send the first packet with a START condition, and then send remaining data in the other packet with a STOP condition.

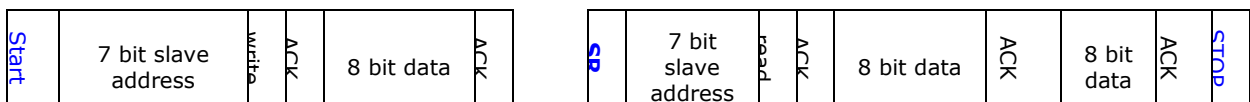


Separate data into three packets.



### I<sup>2</sup>C combined message

In a combined message, each read or write begins with a START and the slave address. After the first START, these are called repeated START bits; repeated START bits are not preceded by STOP bits, which is how slaves know the next transfer is part of the same message.



SR = repeated START condition

#### 4.2.1 FT260\_I2CMaster\_Init

FT260\_STATUS **FT260\_I2CMaster\_Init**(FT260\_HANDLE ft260Handle, uint32 kbps)

##### Summary:

Initialize the FT260 as an I<sup>2</sup>C master with the requested I<sup>2</sup>C clock speed.

##### Parameters:

ft260Handle	Handle of the device.
kbps	The speed of the I <sup>2</sup> C clock, whose range is from 100K bps to 4000K bps.

##### Return Value:

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.2.2 T260\_I2CMaster\_Reset

FT260\_STATUS **T260\_I2CMaster\_Reset**(FT260\_HANDLE ft260Handle)

##### Summary:

Reset the FT260 I<sup>2</sup>C Master controller.

##### Parameters:

ft260Handle	Handle of the device.
-------------	-----------------------

##### Return Value:

FT260\_OK if successful, otherwise the return value is an error code.

### 4.2.3 FT260\_I2CMaster\_Write

FT260\_STATUS **FT260\_I2CMaster\_Write**(FT260\_HANDLE ft260Handle, uint8 deviceAddress, FT260\_I2C\_FLAG flag, LPVOID lpBuffer, DWORD dwBytesToWrite, LPDWORD lpdwBytesWritten);

#### Summary:

Write data to the specified I2C slave device with the given I<sup>2</sup>C condition.

#### Parameters:

ft260Handle	Handle of the device.
deviceAddress	Address of the target I <sup>2</sup> C slave.
flag	I <sup>2</sup> C condition: <ul style="list-style-type: none"> <li>• FT260_I2C_NONE</li> <li>• FT260_I2C_START</li> <li>• FT260_I2C_REPEATED_START</li> <li>• FT260_I2C_STOP</li> <li>• FT260_I2C_START_AND_STOP</li> </ul>
lpBuffer	Pointer to the buffer that contains the data to be written to the device.
dwBytesToRead	Number of bytes to write to the device.
lpdwBytesReturned	Pointer to a variable of type DWORD which receives the number of bytes read and written to the device.

#### Return Value:

FT260\_OK if successful, otherwise the return value is an error code.

### 4.2.4 FT260\_I2CMaster\_Read

FT260\_STATUS **FT260\_I2CMaster\_Read**(FT260\_HANDLE ft260Handle, uint8 deviceAddress, FT260\_I2C\_FLAG flag, LPVOID lpBuffer, DWORD dwBytesToRead, LPDWORD lpdwBytesReturned, DWORD wait\_timer)

#### Summary:

Read data from the specified I2C slave device with the given I<sup>2</sup>C condition.

#### Parameters:

ft260Handle	Handle of the device.
deviceAddress	Address of the target I <sup>2</sup> C slave device.
Flag	I <sup>2</sup> C condition: <ul style="list-style-type: none"> <li>• FT260_I2C_NONE</li> <li>• FT260_I2C_START</li> <li>• FT260_I2C_REPEATED_START</li> <li>• FT260_I2C_STOP</li> <li>• FT260_I2C_START_AND_STOP</li> </ul>
lpBuffer	Pointer to the buffer that receives the data from the device.

dwBytesToRead	Number of bytes to read from the device.
lpdwBytesReturned	Pointer to a variable of type DWORD which receives the number of bytes read from the device.
wait_timer	A timer counter to check I2C read status from the device If times up, the I2C will return an error message FT260_I2C_READ_FAIL The default value is 5000(5 sec)

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

**4.2.5 FT260\_I2CMaster\_GetStatus**

FT260\_STATUS **FT260\_I2CMaster\_GetStatus**(FT260\_HANDLE ft260Handle, uint8\* status)

**Summary:**

Read the status of the I2C master controller.

**Parameters:**

ft260Handle	Handle of the device.
Status	Point to a variable of type uint8 which saves the status value. Status: <ul style="list-style-type: none"> <li>• bit 0 = controller busy: all other status bits invalid</li> <li>• bit 1 = error condition</li> <li>• bit 2 = slave address was not acknowledged during last operation</li> <li>• bit 3 = data not acknowledged during last operation</li> <li>• bit 4 = arbitration lost during last operation</li> <li>• bit 5 = controller idle</li> <li>• bit 6 = bus busy</li> </ul>

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

**4.3 UART Functions**

UART (Universal Asynchronous Receiver/Transmitter) is a commonly used interface to transfer serial data. Being asynchronous there is no clock signal but the structure of the transmitted data provides for a start and an end to a message. It is also important that both ends of the link decide to operate with the same pulse width defined as the baud rate. The UART of a micro-controller will normally operate at 3V3 or 5V TTL levels. The UART will only connect to one other device in the chain.

The FT260 device can be initialized as a UART. Here is a brief overview of FT260 UART features:

- The UART can support baud rates from 1.2KBaud to 12MBaud.
- UART data signals: TxD, RxD, RTS, CTS, DSR, DTR, DCD, RI, GND
- Serial Communication Parameters

- Parity: None, Odd, Even, Mark, Space
- Data bits: 7, 8
- Flow control: RTS/CTS , DSR/DTR, X-ON/X-OFF, None
- Stop bits 1,2

Please refer to [DS\\_FT260](#) for more information.

### 4.3.1 FT260\_UART\_Init

FT260\_STATUS **FT260\_UART\_Init**(FT260\_HANDLE ft260Handle);

#### Summary:

Initialize the FT260 as a UART device.

#### Parameters:

ft260Handle	Handle of the device.
-------------	-----------------------

#### Return Value:

FT260\_OK if successful, otherwise the return value is an error code.

### 4.3.2 FT260\_UART\_Reset

FT260\_STATUS **FT260\_UART\_Reset**(FT260\_HANDLE ft260Handle)

#### Summary:

Reset UART controller.

#### Parameters:

ft260Handle	Handle of the device.
-------------	-----------------------

#### Return Value:

FT260\_OK if successful, otherwise the return value is an error code.

### 4.3.3 FT260\_UART\_SetBaudRate

FT260\_STATUS **FT260\_UART\_SetBaudRate**(FT260\_HANDLE ft260Handle, ULONG baudRate)

#### Summary:

Set the baud rate for the device.

#### Parameters:

ft260Handle	Handle of the device.
baudRate	The speed of UART transmission. It ranges from 1,200 to 12,000,000 bps.

#### Return Value:

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.3.4 FT260\_UART\_SetFlowControl

FT260\_STATUS **FT260\_UART\_SetFlowControl**(FT260\_HANDLE ft260Handle, FT260\_UART\_Mode flowControl)

**Summary:** Set UART flow control for the device.

**Parameters:**

ft260Handle	Handle of the device.
flowControl	Flow control: <ul style="list-style-type: none"> <li>• FT260_UART_OFF: Disable UART and switch UART pins to GPIO.</li> <li>• FT260_UART_RTS_CTS_MODE</li> <li>• FT260_UART_DTR_DSR_MODE</li> <li>• FT260_UART_XON_XOFF_MODE</li> <li>• FT260_UART_NO_FLOW_CTRL_MODE</li> </ul>

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.3.5 FT260\_UART\_SetDataCharacteristics

FT260\_STATUS **FT260\_UART\_SetDataCharacteristics**(FT260\_HANDLE ft260Handle, FT260\_Data\_Bit dataBits, FT260\_Stop\_Bit stopBits, FT260\_Parity parity);

**Summary:**

Set UART data characteristics for the device.

**Parameters:**

ft260Handle	Handle of the device.
dataBits	Data bits: <ul style="list-style-type: none"> <li>• FT260_DATA_BIT_7</li> <li>• FT260_DATA_BIT_8</li> </ul>
stopBits	Stop bits: <ul style="list-style-type: none"> <li>• FT260_STOP_BITS_1</li> <li>• FT260_STOP_BITS_2</li> </ul>
parity	Parity: <ul style="list-style-type: none"> <li>• FT260_PARITY_NONE</li> <li>• FT260_PARITY_ODD</li> <li>• FT260_PARITY_EVEN</li> <li>• FT260_PARITY_MARK</li> <li>• FT260_PARITY_SPACE</li> </ul>

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.3.6 FT260\_UART\_SetBreakOn

FT260\_STATUS **FT260\_UART\_SetBreakOn**(FT260\_HANDLE ft260Handle)

**Summary:**

Set the BREAK condition ON for the device.

**Parameters:**

ft260Handle	Handle of the device.
-------------	-----------------------

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.3.7 FT260\_UART\_SetBreakOff

FT260\_STATUS **FT260\_UART\_SetBreakOff**(FT260\_HANDLE ft260Handle)

**Summary:**

Reset the BREAK condition OFF for the device.

**Parameters:**

ft260Handle	Handle of the device.
-------------	-----------------------

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.3.8 FT260\_UART\_GetConfig

FT260\_STATUS **FT260\_UART\_GetConfig**(FT260\_HANDLE ft260Handle, UartConfig\* pUartConfig)

**Summary:**

UART get configuration which includes baud rate, data characteristics and break condition.

**Parameters:**

ft260Handle	Handle of the device.
-------------	-----------------------



pUartConfig	<p>Pointer to a variable of type UartConfig where the value will be stored. Type UartConfig is defined as following:</p> <pre> struct UartConfig {     u8 flow_ctrl;     u32 baud_rate;     u8 data_bit;     u8 parity;     u8 stop_bit;     u8 breaking; } </pre> <p>Please refer to the previous UART setting functions for a description of the fields.</p>
-------------	--

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

### 4.3.9 FT260\_UART\_SetXonXoffChar

FT260\_STATUS **FT260\_UART\_SetXonXoffChar**(FT260\_HANDLE ft260Handle, UCHAR Xon, UCHAR Xoff)

**Summary:** Set Xon/Xoff characters for software flow control.

**Software flow control (XON\_XOFF)**

This setting uses special characters to start and stop data flow. These are termed XON and XOFF (from "transmit on" and "transmit off", respectively). The XON character tells the downstream device to start sending data. The XOFF character tells the downstream device to stop sending data. Usually it is possible to define these characters in an application. Typical default for XON is 0x11 and for XOFF is 0x13.

**Parameters:**

ft260Handle	Handle of the device.
Xon	Setting character for transmit on.
Xoff	Setting character for transmit off.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

### 4.3.10 FT260\_UART\_GetQueueStatus

FT260\_STATUS **FT260\_UART\_GetQueueStatus**(FT260\_HANDLE ft260Handle, LPDWORD lpdwAmountInRxQueue)

**Summary:**

Gets the number of bytes in the receive queue.

**Parameters:**

ft260Handle	Handle of the device.
lpdwAmountInRxQueue	Pointer to a variable of type DWORD which save the amount of data.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

### 4.3.11 FT260\_UART\_Write

FT260\_STATUS **FT260\_UART\_Write**(FT260\_HANDLE ft260Handle, LPVOID lpBuffer, DWORD dwBufferLength, DWORD dwBytesToWrite, LPDWORD lpdwBytesWritten)

**Summary:**

UART write data to the device.

**Parameters:**

ft260Handle	Handle of the device.
lpBuffer	Pointer to the buffer that contains the data to be written.
dwBufferLength	The length of the buffer.
dwBytesToWrite	Number of bytes to write.
lpdwBytesWritten	Pointer to a variable of type DWORD which receives the number of bytes written.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

### 4.3.12 FT260\_UART\_Read

FT260\_STATUS **FT260\_UART\_Read**(FT260\_HANDLE ft260Handle, LPVOID lpBuffer, DWORD dwBufferLength, DWORD dwBytesToRead, LPDWORD lpdwBytesReturned)

**Summary:**

UART read data from the device.

**Parameters:**

ft260Handle	Handle of the device.
lpBuffer	Pointer to the buffer that contains the data to be read.
dwBufferLength	The length of the buffer.
dwBytesToWrite	Number of bytes to read.
lpdwBytesWritten	Pointer to a variable of type DWORD which receives the number of bytes read.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

### 4.3.13 FT260\_UART\_GetDcdRiStatus

FT260\_STATUS **FT260\_UART\_GetDcdRiStatus**(FT260\_HANDLE ft260Handle, uint8\* value)

**Summary:**

Get DCD, RI status.

**Parameters:**

ft260Handle	Handle of the device.
Value	Pointer to a variable of type uint8 which saves the status value. <ul style="list-style-type: none"> <li>• BIT 0: DCD status</li> <li>• BIT 1: RI status</li> </ul>

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

### 4.3.14 FT260\_UART\_EnableRiWakeup

FT260\_STATUS **FT260\_UART\_EnableRiWakeup**(FT260\_HANDLE ft260Handle, BOOL enable)

**Summary:**

UART enable RI wakeup.

**Parameters:**

ft260Handle	Handle of the device.
Enable	FALSE to disable. TRUE to enable.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

### 4.3.15 FT260\_GetInterruptFlag

FT260\_STATUS **FT260\_GetInterruptFlag**(FT260\_HANDLE ft260Handle, BOOL\* pbFlag);

**Summary:**

Get interrupt flag.

**Parameters:**

ft260Handle	Handle of the device.
pbFlag	Pointer to a variable of type BOOL which saves the flag value.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

### 4.3.16 FT260\_CleanInterruptFlag

FT260\_STATUS **FT260\_CleanInterruptFlag**(FT260\_HANDLE ft260Handle, BOOL\* pbFlag);

**Summary:**

Clean the interrupt flag.

**Parameters:**

ft260Handle	Handle of the device.
pbFlag	Pointer to a variable of type BOOL which saves the flag value.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

## 4.4 GPIO Functions

The FT260 contains 14 GPIO pins. Each GPIO pin is multiplexed with other functions as listed below:

- GPIO0 / SCL
- GPIO1 / SDA
- GPIO2 / SUSPEND OUT / TX\_LED / PWREN
- GPIO3 / WAKEUP / INTR
- GPIO4 / UART DCD
- GPIO5 / UART RI
- GPIOA / TX\_ACTIVE / TX\_LED / PWREN
- GPIOB / UART\_RTS\_N
- GPIOC / UART\_RXD
- GPIOD / UART\_TXD
- GPIOE / UART\_CTS\_N
- GPIOF / UART\_DTR\_N
- GPIOG / BCD\_DET / RX\_LED
- GPIOH / UART\_DST\_N

The LibFT260 support library provides several APIs to set the function of these GPIOs and the GPIO example application shows how to use them.

Please refer to [DS\\_FT260](#) for more information.

### 4.4.1 FT260\_GPIO\_Set

FT260\_STATUS **FT260\_GPIO\_Set**(FT260\_HANDLE ft260Handle, FT260\_GPIO\_Report report)

**Summary:**

Set directions and values for all GPIO pins with the FT260\_GPIO\_Report parameter.

**Parameters:**

ft260Handle	Handle of the device.
report	<p>The setting values which is a variable of type FT260_GPIO_Report. Type FT260_GPIO_Report is defined as follows:</p> <pre>struct FT260_GPIO_Report {     WORD value;           // bit0~5: GPIO0~5 values     WORD dir;            // bit0~5: GPIO0~5 directions     WORD gpioN_value;    // bit0~7: GPIOA~H values     WORD gpioN_dir;     // bit0~7: GPIOA~H directions }</pre>

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.4.2 FT260\_GPIO\_Get

FT260\_STATUS **FT260\_GPIO\_Get**(FT260\_HANDLE ft260Handle, FT260\_GPIO\_Report \*report)

**Summary:**

Get directions and values for all GPIO pins with the FT260\_GPIO\_Report parameter.

**Parameters:**

ft260Handle	Handle of the device.
report	<p>Pointer to a variable of type FT260_GPIO_Report where the value will be stored. Type FT260_GPIO_Report is defined as follows:</p> <pre>struct FT260_GPIO_Report {     WORD value;           // bit0~5: GPIO0~5 values     WORD dir;            // bit0~5: GPIO0~5 directions     WORD gpioN_value;    // bit0~7: GPIOA~H values     WORD gpioN_dir;     // bit0~7: GPIOA~H directions }</pre>

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.4.3 FT260\_GPIO\_SetDir

FT260\_STATUS **FT260\_GPIO\_SetDir**(FT260\_HANDLE ft260Handle, WORD pinNum, BYTE dir)

**Summary:**

Set direction for the specified GPIO pin.

**Parameters:**

ft260Handle	Handle of the device.
pinNum	Target GPIO pin number.
dir	0 for input. 1 for output.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.4.4 FT260\_GPIO\_Read

FT260\_STATUS **FT260\_GPIO\_Read**(FT260\_HANDLE ft260Handle, WORD pinNum, BYTE\* pValue)

**Summary:**

Read the value from the specified GPIO pin.

**Parameters:**

ft260Handle	Handle of the device.
pinNum	Target GPIO pin number.
pValue	Pointer to a variable of BYTE which receives the value of the GPIO pin.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.4.5 FT260\_GPIO\_Write

FT260\_STATUS **FT260\_GPIO\_Write**(FT260\_HANDLE ft260Handle, WORD pinNum, BYTE value)

**Summary:**

Write value to the specified GPIO pin.

**Parameters:**

ft260Handle	Handle of the device.
pinNum	Target GPIO pin number.
value	The output value.

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

#### 4.4.6 FT260\_GPIO\_Set\_OD

FT260\_STATUS **FT260\_GPIO\_Set\_OD**(FT260\_HANDLE ft260Handle, BYTE pinNum)

**Summary:.**

Function to enable open drain feature. The pins for operation are defined with the parameter pinNum.

It is important to note that once this feature is enabled, the **FT260\_GPIO\_Reset\_OD** must be called when the pin is to be configured for other purposes.

**Parameters:**

ft260Handle	Handle of the device.
pinNum	Target GPIO pins number : Ex : 1. Open drain enable at GPIO 0~5. GPIO_0 = 0x01; GPIO_1 = 0x01<<1; GPIO_2 = 0x01<<2; GPIO_3 = 0x01<<3; GPIO_4 = 0x01<<4; GPIO_5 = 0x01<<5; pinNum = (GPIO_0   GPIO_1   GPIO_2   GPIO_3   GPIO_4   GPIO_5)

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

**4.4.7 FT260\_GPIO\_Reset\_OD**

**FT260\_STATUS FT260\_GPIO\_Reset\_OD( FT260\_HANDLE handle)**

**Summary:.**

To RESET open drain function

ft260Handle	Handle of the device.
-------------	-----------------------

**Return Value:**

FT260\_OK if successful, otherwise the return value is an error code.

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## Appendix A – References

### Document References

[DS\\_FT260](#)

### Acronyms and Abbreviations

Terms	Description
GPIO	General-purpose input/output
HID	Human Interface Device
I2C	Inter-Integrated Circuit
UART	Universal Asynchronous Receiver/Transmitter
USB	Universal Serial Bus
USB-IF	USB Implementers Forum

## Appendix B – List of Tables & Figures

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## Appendix C – FT260\_STATUS

### FT260\_STATUS

```
FT260_OK = 0
FT260_INVALID_HANDLE = 1
FT260_DEVICE_NOT_FOUND = 2
FT260_DEVICE_NOT_OPENED = 3
FT260_DEVICE_OPEN_FAIL = 4
FT260_DEVICE_CLOSE_FAIL = 5
FT260_INCORRECT_INTERFACE = 6
FT260_INCORRECT_CHIP_MODE = 7
FT260_DEVICE_MANAGER_ERROR = 8
FT260_IO_ERROR = 9
FT260_INVALID_PARAMETER = 10
FT260_NULL_BUFFER_POINTER = 11
FT260_BUFFER_SIZE_ERROR = 12
FT260_UART_SET_FAIL = 13
FT260_RX_NO_DATA = 14
FT260_GPIO_WRONG_DIRECTION = 15
FT260_INVALID_DEVICE = 16
FT260_I2C_READ_FAIL = 17
FT260_OTHER_ERROR = 18
```

## Appendix D – Revision History

Document Title: AN\_395 User Guide for LibFT260  
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1.0	Initial Release	2016-03-08
1.1	Updated document for information related to Open drain	2017-10-06
1.2	Fix editor issue on Code example at Page 9	2018-08-31