

# **Wireless communication**

ISA100 Wireless <sup>TM</sup>

## **Technical Manual**

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# 1 Introduction

This document supplements the instructions for use for gas warning devices:

- Dräger Polytron® 6100 EC WL
- GasSecure GS01 / GasSecure GS01-EA
- Polytron Repeater ISA100
- Polytron 6700 IR WL

This document contains additional information on the ISA100 Wireless™ interface.

## 1.1 Target group



This document is intended for technicians with training in PLC programming, trained electricians or persons who have received instruction from a trained electrician. These persons must also be familiar with the applicable standards.

## 1.2 General safety statements


Before using this product, carefully read the associated instructions for use. This document does not replace the instructions for use.

## 1.3 Meaning of the warning notes

The following warning notes are used in this document to notify users of possible dangers. The meanings of the warning notes are defined as follows:

Alert icon	Signal word	Consequences in case of nonob-servance
	WARNING	Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.
	CAUTION	Indicates a potentially hazardous situation which, if not avoided, could result in injury. It may also be used to alert against unsafe practices.
	NOTICE	Indicates a potentially hazardous situation which, if not avoided, could result in damage to the product or environment.

## 1.4 Typographical conventions

<b>Text</b>	Text marked in bold denotes labeling on the device and on-screen messages.
►	This triangle labels possible methods of avoiding the hazards mentioned in warning notices.
>	The greater-than sign denotes the navigational path in a menu.
	This symbol denotes information that make using the product easier.

## 1.5 Brand names

- HART® is a registered trademark of the HART Communication Foundation.
- PROFIBUS® is a registered trademark of the PROFIBUS Nutzerorganisation e. V.
- FOUNDATION™ is a registered trademark of the Fieldbus Foundation.
- ISA100 Wireless™ is a registered trademark of the International Society of Automation (ISA).
- Bluetooth® is a registered trademark of Bluetooth SIG, Inc.
- WirelessHART® (WHART) is a registered trademark of the HART Communication Foundation.
- PROFIsafe® is a registered trademark of Siemens Aktiengesellschaft.

## 2 Wireless data transmission in industrial settings

There are a number of different protocols and types of network for wireless data transmission, which will be described in this manual in conjunction with Dräger products. The following diagram shows the application areas for various protocols. Other protocols (WPAN, for example) are not considered in this context.

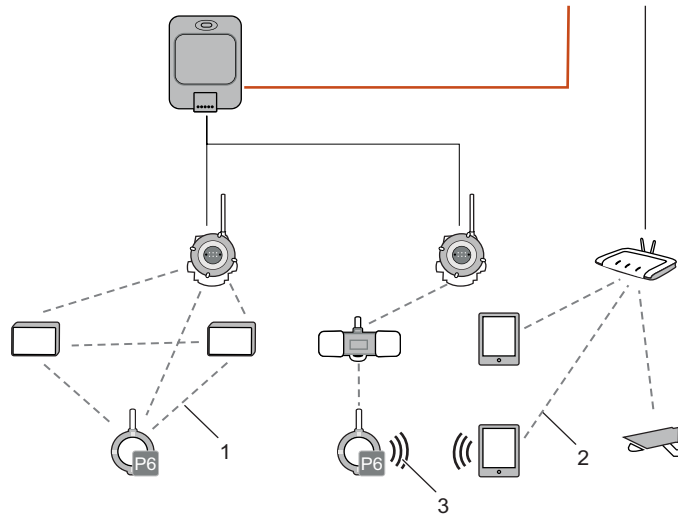


Fig. 1 Wireless data transmission protocols

1	WFAN
2	WLAN
3	Bluetooth® or infrared

### WLAN and WFAN

In a WFAN (Wireless Field (or Factory) Area Network), industrial field devices communicate with one another or with a control center. The control center controls and monitors the field devices. When communicating via WFAN, protocols such as ISA100 Wireless™ and WirelessHART® (WHART) are used.

WLAN (Wireless Local Area Network) is a local, usually private wireless network. The WLAN infrastructure of an industrial plant is used for mobile end devices and video transmission (stationary cameras).

### **Main application areas**

There are 3 main areas of application for wireless networks:

- Plant safety  
Transmitters monitor safety-critical areas and send wireless measured values. ISA100 Wireless™ allows for SIL 2-compliant failsafe communication through the transport of PROFIsafe® messages.
- Monitoring field devices  
The status of field devices is monitored (e.g. temperature, sensor status of a gas warning device).
- Process monitoring and process control  
Wireless data transmission allows for detailed process monitoring and process control without expensive cable routing costs.  
These areas of application must be able to tolerate latencies of 100 ms.

### **Advantages of a wireless network**

Wireless networks offer many advantages compared to wired networks.

- Wireless networks can be made operational more quickly and installing the infrastructure creates less costs.
- Wireless networks can be expanded with greater ease and at less cost. Adding new field devices and putting them into operation, as well as removing them, is easier.
- The parameters of field devices as well as diagnostics and maintenance can be configured centrally.
- Errors do not occur when wiring field devices (e.g. cable break, wiring problems in the field device).
- Wireless networks can be employed in places a wired network would be impossible, expensive, or difficult to implement (e.g. on rotating platforms).
- Temporary installations that are dismantled after a certain time also profit from wireless networking. Temporary installations no longer need arduous and expensive cabling.

Furthermore, a wired network's infrastructure can be expanded wirelessly (creating redundancy).



### 3 ISA100 Wireless™ basics

ISA100.11a is a wireless networking protocol internationally recognized as IEC Standard 62734 and developed by the International Society of Automation (ISA). It is based on the ISO/OSI reference model and allows for reliable, secure data transmission for control- and regulation-related applications, process monitoring and alerts.

ISA100 Wireless™ is comparable to a fieldbus system in that it allows for reliable data transmission even over long distances with low power consumption.

As with most fieldbus systems, a ISA100 Wireless™ network can be expanded with any field devices required due to standardization. All field devices in the network can interact with one another independent of manufacturer.

ISA100 Wireless™ defines basic functions and requirements for field devices, system management, gateway requirements and security specifications.

#### **Failsafe communication**

ISA100 Wireless™ allows for failsafe communication (e.g. SIL 2-compliant) between controller and field device. This secure data transfer method is performed via tunneling. Tunneling facilitates the use of different communication protocols via the ISA100 Wireless™ infrastructure. Failsafe communication is done via the PROFIsafe® communication protocol. This communication protocol is transmitted outside the ISA100 Wireless™ infrastructure via PROFINET.

#### **Advantages of ISA100 Wireless™**

There are different wireless network protocols. Among others, the ISA100 Wireless™ protocol has the following advantages over other protocols:

- Transfer of other communication standards (e.g. PROFIsafe®, HART®)
- Bandwidth for safety-relevant data can be reserved. This reserved bandwidth ensures the rapid transmission of safety-relevant data at any time to the control center. The transmission of safety-relevant data is not affected by other data traffic.
- Response times of a ISA100 Wireless™ network are variable and shorter than those of other protocols.

### 3.1 Network components and participants

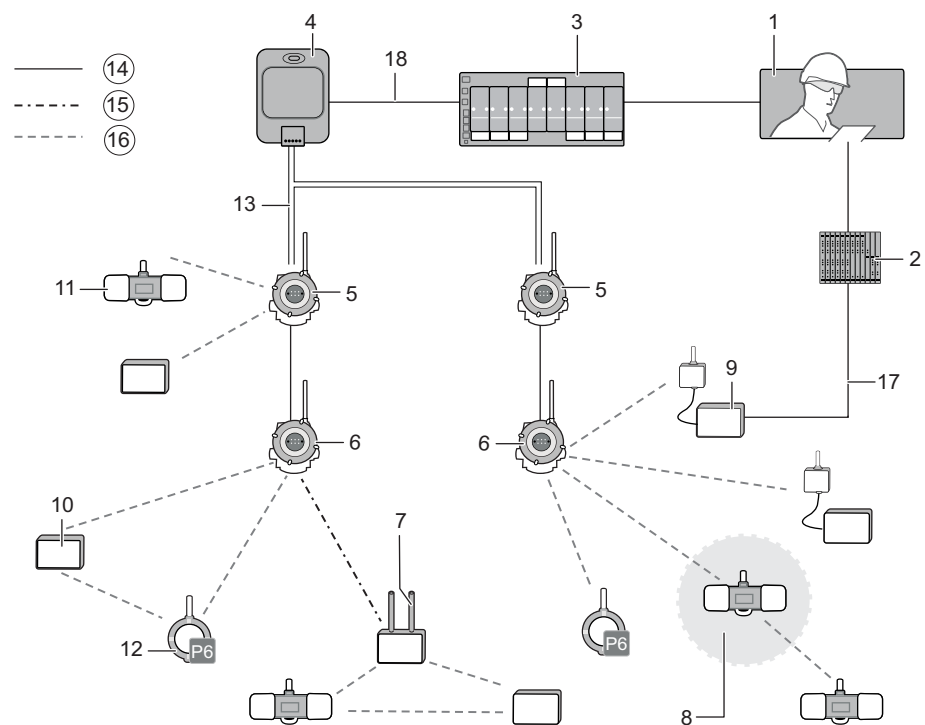


Fig. 2 Example topology of a wireless network

1	Control center
2	Control unit for wired field devices
3	Control unit
4	System manager
5	Access point in the function as a backbone router
6	Access point
7	Access point in the function as a field device access point
8	Hop point
9	Retrofitted field device
10	I/O field device
11	GasSecure GS01
12	Dräger Polytron® 6100 EC WL
13	Backbone
14	Ethernet or fiber-optics
15	Wireless data transmission from an access point to the backbone
16	Wireless data transmission between field devices and to the backbone
17	Wired analog or digital communication
18	Wired Modbus communication or PROFIsafe® communication via PROFIBUS/PROFINET

### 3.1.1 System manager

The system manager monitors and manages the following system functions, among others:

- Security management
- System performance, system latencies, redundancy
- System time
- Field device management (e.g. address allocation and routing tables)

Wireless gateway and system manager are the same thing for the purposes of this manual. In detailed descriptions, system managers and gateways must be considered separately from one another.

Controllers are connected to the system manager (e.g. Dräger REGARD® 7000 with Modbus Master module). Control units process the system manager's data and trigger alerts or countermeasures.

If PROFIsafe® is used for communication purposes (e.g. for SIL 2 applications), an F-host (failsafe host) must be used as a controller, which communicates with F-slaves (FailSafe field devices). In this case, the system manager only forwards the messages and does not interfere with PROFIsafe® communication.

### 3.1.2 Backbone

The backbone is the wired part of the network, which connects the backbone router (BBR) to the system manager. The connection is established via fiber-optic cable (FOC) or Ethernet.

### 3.1.3 Access points (AP)

An access point is the transition from the wireless to the wired parts of the network. Access points transmit the information from their end devices via cable to the system manager. APs can be compared to the base station of a mobile landline phone. In both cases, a wireless network is established for a multitude of mobile end devices.

An AP performs different roles depending on the position in which it is located in the network.

#### 3.1.3.1 Backbone router (BBR)

If an access point is wired directly to the backbone, the access point is referred to as the backbone router. Several backbone routers can be connected to the backbone.

Field devices and field device access points communicate wirelessly with the backbone router via the sub-network, which is established by the backbone router.

Additional access points can be wired to the backbone router.

---

**i** Risk of confusion

Backbone routers are connected to the backbone via cables. Repeaters or field devices with routing functionalities are often also referred to as routers. However, these "routers" are not connected to the backbone via cables and only forward the signals.

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**Backbone routers as part of the system manager**

Backbone routers can also be part of the system manager.

**3.1.3.2 Field device access points (FDAP)**

Field device access points are access points that communicate wirelessly with the backbone. Communication to the backbone is done either via access points or directly over the backbone router.

Dräger-approved devices are listed in the appendix.

**3.1.4 Field devices**

Field devices may also be called terminal devices or clients. They log on to the AP and exchange information. Field devices are also called I/O devices because they receive (input) and send (output) data.

There are field devices that communicate with the control center via cable in addition to communicating wirelessly. These field devices are retrofitted with an ISA100 Wireless™ antenna. They additionally communicate via wire with another interface (a 4–20 mA interface, for example).

Field devices can be mobile field devices (tablets, smartphones, laptops), stationary field devices or slow-moving stationary field devices. Mobile field devices often communicate with an additional system manager or gateway via a different protocol (non-ISA100 Wireless™).

Due to their being integral elements of the network infrastructure, access points or field device access points are not called field devices.

**3.1.4.1 Routing functionalities**

Some field devices can also act as a router in addition to their normal functionality. Field devices with this function activated create hop points in the network.

These devices are often connected to a power line due to the extra energy requirements involved in router operation.

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**i** Field devices with routing functionalities are also available without measuring functions. They are then only integrated into the network as routers. The Polytron® Repeater ISA100 is a router without measuring function.

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### 3.1.4.2 Power supply

Power is supplied to field devices via batteries or the power grid. ISA100 Wireless™ allows for every type of power supply.

If battery operation is not possible, field devices are connected to an external power supply. An external power supply may be necessary if the routing functionality is active and there is a lot of wireless communication.


When operating in explosion-hazard areas, an upstream safety barrier must be installed for external power supplies.

### 3.1.5 Hop points

Routers or field devices with a router function form a hop point in the sub-network.

Hop points expand a network and ensure redundant transmission routes. Signals are forwarded without processing and no separate sub-network is established.

Data transmissions via hop points to the system manager are slower than direct data transmissions to access points. Latencies (wait times) at the hop points can delay communication.

 The communication paths via hop points are prevented ex-factory for some system managers. But, the function can be activated.

#### Restrictions for installations with short response times

Series-connected hop points can delay the response time. If response times are a critical factor, there must be a limited number of hops (wireless interfaces) from the field device to the access point. Fig. 3 shows a sub-network with only one (1) or two (2) hops allowed.

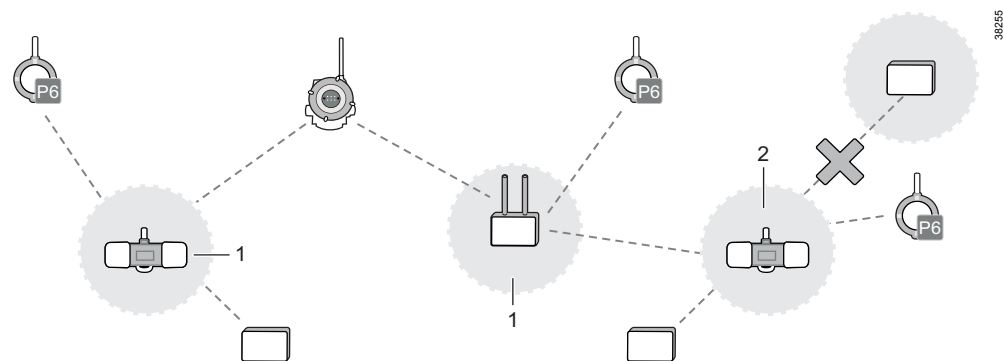



Fig. 3 Hop points in a sub-network

- 1 First hop point after the sub-network access point

One further hop point is possible.

- 2 Second hop point after the sub-network access point

Another hop point could cause too much of a delay in the response time.

 System managers from Yokogawa support a maximum of 4 hops (wireless interfaces) between a field device and the backbone router (as at September 2020).

### 3.1.5.1 Routers

Routers are also called repeaters. Routers increase the size of the network and cancel out weak spots. They form a hop point in the sub-network. Incoming data is forwarded without processing.

Routers do not establish their own sub-networks.

## 3.2 Network topologies

There are 3 network topologies for ISA100 networks.

- Star topology
- Mesh topology
- Partial mesh topology

### 3.2.1 Star topology

In a star topology, field devices communicate with one or more access points. The field devices can only exchange information via access points, not directly with one another. Multiple access points are often employed to make the network more fail-safe.

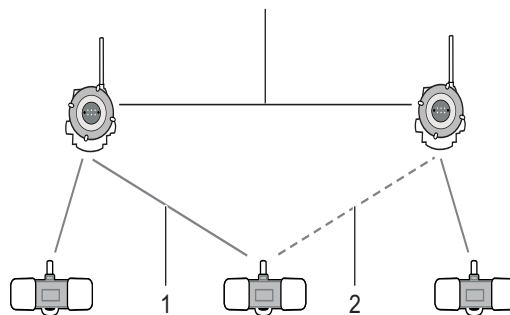


Fig. 4 Star topology and communication channels

1	Primary communication channel
2	Secondary communication channel

3.2.2 Mesh topology

In a mesh topology, all network participants that are within range communicate with one another. Field devices, routers and access points can be network participants.

In a mesh network, the data transmission is redundant. If communication over a field device or a repeater is interrupted, the data is transmitted via other network participants.

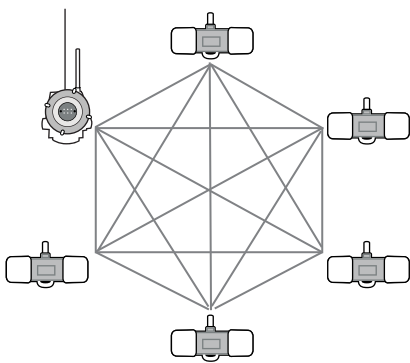


Fig. 5 Mesh topology

3.2.2.1 Partial mesh topology

The mesh topology and star topology can be mixed. This combination is called a partial mesh topology or star-mesh topology. In this topology, a core network, in which all network participants are interconnected, is expanded with network participants that are no longer connected with all network participants.

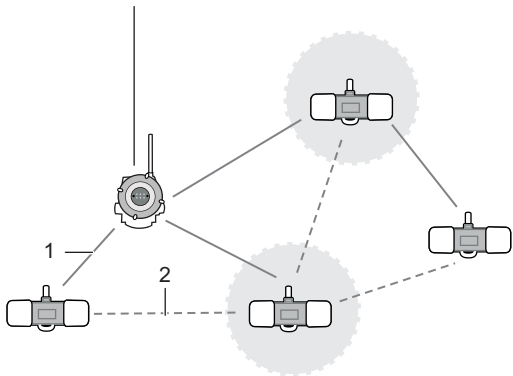


Fig. 6 Partial mesh topology

1	Preferred communication channel
2	Redundant communication channel

### 3.2.3 Comparison of star topology and mesh topology

Network cards are best compared by using the most important criteria for networks: Reliability and latency.

#### **Reliability**

In a mesh network, network participants exchange information with each other (IoT approach). If one network participant fails, communication is still possible. If a network participant fails in a star topology, communication can fail.

#### **Latencies**

The latency of star topologies is usually less than that of meshed ones due to the field devices being directly connected to an access point.

## 3.3 Network performance and network configuration

The wireless connection between field devices and the access point depends greatly on the surroundings. The connection is best when there is an unobstructed line of sight between the two. Oftentimes, however, there is no line of sight (due to intervening pipes or walls, for example). If the line of sight is obstructed, routers or the reflective properties of the obstacles themselves are used.

### 3.3.1 Signal quality

The signal quality of wireless transmissions depends on the signal strength (RSSI) and the signal integrity (PER or TxFail rate). The RSQI range is another indicator of signal quality.

#### **PER or TxFail rate**

This value represents the error rate during data transmission from the field device to the backbone. This value is displayed as a percentage. The lower the value, the better the integrity of data transmission. High values show poor data transmission integrity. Poor data integrity can be caused by unfavorable communication paths or interferences (other wireless technologies or obstacles, for example).

The expression and the limit values of this error rate depend on the manufacturer of the system manager. The error rate can be expressed either as PER (packet error rate) or as a TxFail rate.

#### **RSSI**

RSSI (received signal strength indication) shows the received signal strength between the field device and the access point. RSSI is expressed in dBm (decibel-milliwatts). The received signal strength is always shown as a negative number. The closer the value is to zero, the better the wireless connection.

#### **RSQI**

RSQI (received signal quality indication) shows the received signal strength between the field device and the access point. RSQI is a calculated value. Higher values indicate better data transmission than lower values. Four quality classes are defined in the standard ISA-100.11a (see table below).



### Signal quality values and their meaning

The interpretation of the value ranges can be adjusted in some system managers. The following table provides an example of the ranges for the purpose of orientation.

Indicator	Value range	Meaning
PER / TxFail rate	0 to 15 %	Good
	15 to 100 %	High
RSSI	-75 to -25 dBm	Good
	-85 to -75 dBm	Acceptable
	-100 to -85 dBm	Poor
RSQI	196 to 255	Excellent
	128 to 195	Good
	64 to 127	Acceptable
	0 to 63	Poor

### Fresnel zone

Signal quality can be disrupted by obstacles even if transmitter and receiver have line of sight. Disruption due to obstacles occurs when obstacles are located in the Fresnel zone. The Fresnel zone is an elliptical area formed around the line of sight, whose diameter increases with the transmission range. It is therefore recommended to install antennas as high up as possible to ensure longer distances are covered.

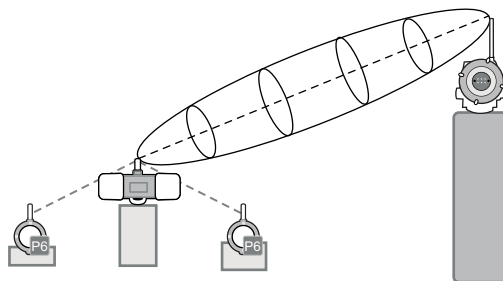


Fig. 7 Line of sight between field device and access point with an elliptical Fresnel zone

### Reflections

Metallic objects and structures can reflect radio waves. If line of sight is obstructed, this effect can be utilized.

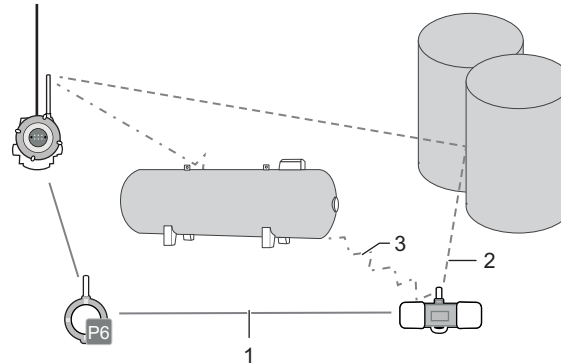


Fig. 8 Alternate communication paths via reflective objects

- |   |                                                       |
|---|-------------------------------------------------------|
| 1 | Preferred communication path (Primary-Path)           |
| 2 | Alternate communication path via reflection ensured.  |
| 3 | Obstructed, direct communication path (Line-Of-Sight) |

### 3.3.2

#### Network coverage

It can occur that network coverage is weaker in some areas. Weak spots such as these are usually due to structural conditions. The routers (repeaters) and field devices with hop point functionality are used to balance weak spots in network coverage.

Remote antennas are another possible way to alleviate weak spots. The antenna is positioned in a spot with good network coverage. The antenna is then connected via cable with the gas warning device. The gas warning device can then be installed in the area where it is required without negatively affecting communication.

#### Site survey (Site-Survey)

To determine the network coverage at the installation area of the gas warning device, a site survey (measurement and analysis of the site) can be conducted in advance.

The site survey generally involves the creation of a heat map. The heat map is a presentation of the site, which marks the quality of the network coverage in color.

### Network size and range

The range depends on the sources of interference (e.g. building development), infrastructure used and thus differs from location to location. The following table shows the typical ranges for three sample environments.

Environment	Example	Range [m]
Free field No sources of interference	Fuel depot	500
Environment with few sources of interference	Refinery (few buildings and plants)	200
Environment with many sources of interference	Oil platform	50

### 3.3.3 Sub-networks

Sub-networks are smaller networks which together form the main network. Sub-networks are established by access points.

ISA100 Wireless™ allows for many sub-networks. Every sub-network can theoretically contain up to  $2^{16}$  field devices. While this possibility is not utilized in practice for various reasons (e.g. flexibility for extensions and stability), addresses still need to be assigned to the field devices at the sub-network level. Every field device is assigned a 16 bit address on the sub-network level. On the main network level, the 16 bit address is increased to 128 bits.

For data transmission between sub-networks, the data packets are sent to the backbone router. The BBR forwards the data packets to the target sub-network.

Communication between sub-networks is not yet provided for gas detection applications. These applications send sub-network data packets only to the backbone. Exchanging data between sub-networks is not yet implemented.

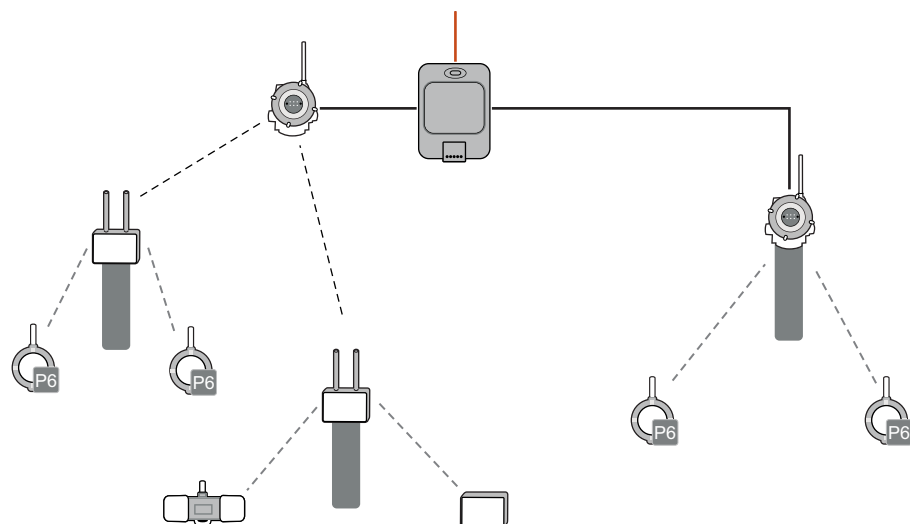


Fig. 9 Sub-networks are established by various network participants.

### 3.3.4 Sky mesh

Field device access points are installed above field devices and establish their own sub-networks. FDAPs then communicate wirelessly with the access point or the backbone router. The field devices can utilize the reflective properties of the surrounding objects for communications to the FDAP. The FDAP itself communicates via line of sight with the access point.

The line of sight's Fresnel zone should not be obstructed by structures (cranes or masts, for example).

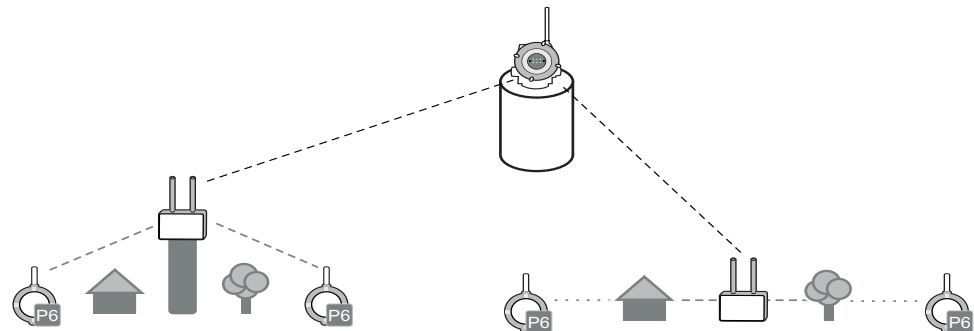


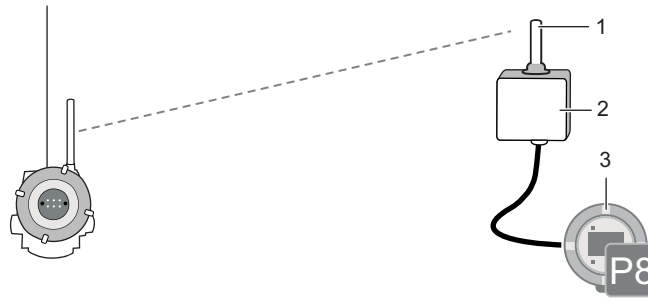
Fig. 10 Sub-networks are established by access points at a higher altitude.

### 3.3.5 Network configuration with retrofitted field devices

Field devices not actually designed for wireless communication can be retrofitted with antennas. The antenna contains a ISA100 Wireless™ module. This module is integrated into the network as a wireless field device.

The ISA100 Wireless™ module is connected to a converter that converts the field device's signals to the ISA100 Wireless™ protocol. The field device's signals can be digital signals (RS485 Modbus, HART) or analog 4–20 mA signals. The universal commands are supported bidirectionally for digital signals. Analog 4–20 mA signals have to follow the NAMUR NE43 recommendation.

Some converters come equipped with built-in batteries for supplying connected field devices with power.



42275

Fig. 11 Retrofitted gas warning device (Dräger Polytron® 8xx0)

- |   |                                                                    |
|---|--------------------------------------------------------------------|
| 1 | Antenna with ISA100 Wireless™ module                               |
| 2 | Converter for digital or analog communication                      |
| 3 | Retrofitted field device that originally only communicates by wire |

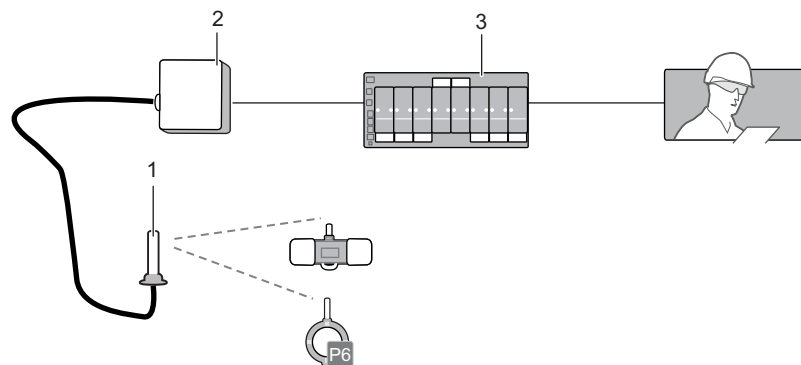
The following components from Yokogawa have been tested and approved by Dräger as suitable field devices for retrofitting purposes (as at September 2020).

- FN110 Field Wireless Communication Module  
ISA100 Wireless™ module (antenna)
- FN310 Field Wireless Multi-Protocol Module  
Converter for digital communication (HART7 and RS485 Modbus)
- FN510 Field Wireless Multi-Function Module  
Converter for analog communication (4–20 mA)

### 3.3.6

#### Network configuration for small networks

For small networks, solutions are available that combine access point and system manager in one component. This solution saves steps during network configuration, but is less effective than conventional installations.



42273

Fig. 12 Small network with system manager and backbone router in one component

- |   |                                                                                       |
|---|---------------------------------------------------------------------------------------|
| 1 | Antenna with ISA100 Wireless™ module that combines system manager and backbone router |
| 2 | Interface adapter                                                                     |
| 3 | Control unit                                                                          |

The following components from Yokogawa have been tested and approved by Dräger for small networks (as at September 2020).

- FN110 Field Wireless Communication Module  
ISA100 Wireless™ module (antenna)
- LN90 Interface Adapter  
Interface adapter between the FN110 and the control unit

#### FN110 field wireless communication module

An FN110 consists of an antenna and an ISA100 Wireless™ module. The FN110 is connected to an interface adapter (LN90) which establishes the connection to a controller via Modbus RTU.

The FN110 can only establish 1 sub-network. Field devices in this sub-network can only be configured in star topology. Depending on the network's refresh rate, 10 to 20 field devices can be integrated. SIL2 communication is not possible.

### 3.3.7

#### Network configuration with long backbone lines

The use of Ethernet cables limits the length of backbone lines to approx. 100 m. If backbone lines need to cover long distances, the Ethernet lines can be expanded with other transmission technologies.

- Fiber-optic cables (FOC)  
To use fiber-optic cables, a converter between the backbone and the system manager must be installed. The converter converts the signals of the fiber-optic cable to signals for Ethernet cables (conversion between 100BASE-TX and 100BASE-FX).
- Copper cables for DSL transmission  
To be able to use DSL, modems must be installed at the transfer point from the Ethernet to the copper cables.

#### Long backbone with fiber-optic cable

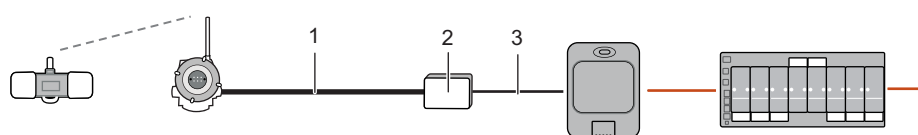


Fig. 13 Long backbone with fiber-optic cable

- |   |                                            |
|---|--------------------------------------------|
| 1 | Backbone as fiber-optic cable (100BASE-FX) |
| 2 | Converter                                  |
| 3 | Backbone as Ethernet cable (100BASE-TX)    |

The following components from Yokogawa have been tested and approved by Dräger for conversion between fiber-optic and Ethernet cables (as at September 2020).

- Field Wireless Media Converter (YFGW610)

### Long backbone with DSL transmission

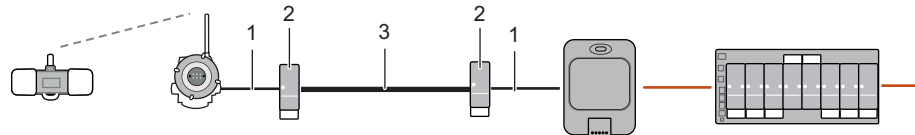


Fig. 14 Long backbone with DSL modem

- |   |                                                               |
|---|---------------------------------------------------------------|
| 1 | Backbone as Ethernet cable (100BASE-TX)                       |
| 2 | DSL modem                                                     |
| 3 | Backbone as copper cable (e.g. BFOU 2x2x1.5 mm <sup>2</sup> ) |

The following components from Phoenix Contact have been tested and approved by Dräger for conversion between Ethernet and copper cables (as at September 2018).

- TC EXTENDER 2001 ETH-2S
- TC EXTENDER 6004 ETH-2S

### 3.3.8 Network configuration with a 4–20 mA control unit

The signal output of the system manager is digital (Modbus, for example). To be able to use analog 4–20 mA link cards of control units, a digital-to-analog converter must be inserted in between.

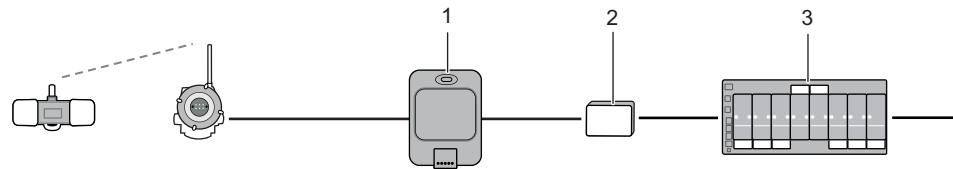


Fig. 15 Network configuration with a 4–20 mA control unit

- |   |                                           |
|---|-------------------------------------------|
| 1 | System manager with digital signal output |
| 2 | Digital-to-analog converter               |
| 3 | Control unit with 4–20 mA link card       |

The following Phoenix Contact component has been tested and approved by Dräger for converting the system manager's digital signals to an analog 4–20 mA signal to the controller (as at September 2018).

- ILC 131 ELH / IB IL AO 2UI-PAC



## 4 ISA100 Wireless™ data transmission basics

The requirements for data transmission via wireless network in industrial settings differ greatly from those for WLAN networks. In WLAN networks, the loss or delay of data packets usually "only" leads to user frustration. In an industrial network, however, this can lead to processes being halted or to injuries or material damage.

To ensure secure data transmission, the frequency spectrum and communication paths are continuously monitored.

Communication paths are the paths the data packets follow through the network.

Monitoring is done via the field devices' performance data.

Various mechanisms are executed based on this performance data.

- Time-Division-Multiple-Access (TDMA) (deterministic transmission and time diversity)
- Clear-Channel-Assessment (CCA) (collision avoidance)
- Path-Diversity, Graph-Routing (different communication paths)
- Automatic-Repeat-reQuest (ARQ) (data packet acknowledgment)
- Blacklisting, Adaptive-Hopping (frequency spectrum management)

Every mechanism contributes to the error-free transmission of data within a defined time period.

For this, every mechanism fulfills at least one of the 3 data integrity requirements.

- Latency  
Data must reach the recipient without undue delay.
- Convergence  
Data must remain complete and unaltered on its way to the recipient.
- Deterministics  
Data must reach the recipient within the predetermined time.

### 4.1 Frequency band and bandwidth

#### Radio channel and frequency

A radio channel is a frequency range for data transmission. The wider the frequency range, the more data can be transmitted.

The distance between radio channels and the width of the frequency range (bandwidth) are defined. These channel characteristics are also known as the channel spacing.

#### ISA100 Wireless™ channel spacing

The bandwidth of a radio channel is 2 MHz. The distance between 2 radio channels (distance from center of one radio channel to center of the next radio channel) is 5 MHz.

ISA100 Wireless™ uses the 2.4 GHz ISM frequency band according to IEEE standard 802.15.4 (channels 11-26). This frequency band can be used world-wide with no license needed.

ISA100 Wireless™ shares this frequency band with channels defined for WLAN transmission. Channels 1, 6 and 11 partially overlap with the wireless channels of the ISA100 Wireless™ channel spacing. Channels 15, 20, 25 and 26 of the ISA100 Wireless™ channel spacing are not overlapped.

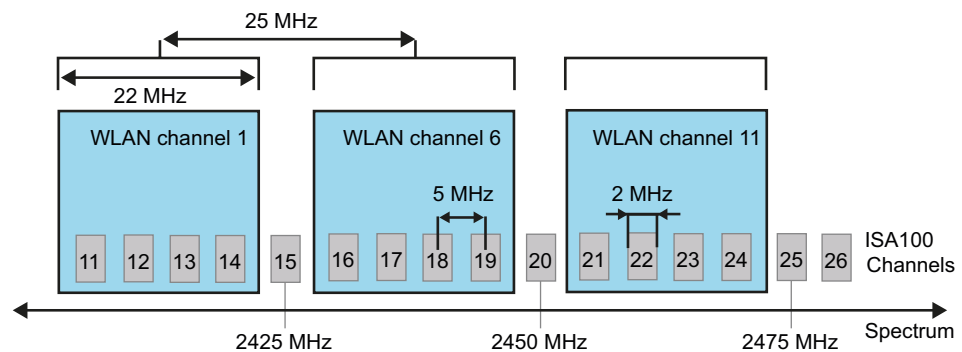


Fig. 16 ISA100 Wireless™ channel spacing and frequency band with overlapping

## 4.2 Data integrity

### 4.2.1 Frequency hopping

When frequency hopping, the field devices change the frequency. Poor performance data may make a change of frequency necessary. If the is the case, an ARQ is executed.

Frequency changes follow the predefined hopping scheme (Patterns). This sequence is assigned during provisioning of the field device.

### 4.2.2 Hopping patterns

Hopping patterns determine on which channels transmission and reception take place in a time slot. Duration and sequence are predetermined.

ISA100 Wireless™ defines 3 hopping patterns.

#### Slotted hopping

Data is transmitted once on every channel in a time slot. This way, a relatively large amount of time passes before transmission and reception occurs again on a channel.

Slotted hopping is suitable for regular data that is transmitted synchronously. It is therefore not suitable for event-based transmissions (alarms, for example). Field devices wait to transmit and receive data until their channel's turn. The time window for this is relatively small.

#### Slow hopping

Transmission and reception can occur on every channel for the duration of exactly one time slot. Slow hopping is therefore better suited for event-based transmissions that must be sent immediately. However, the energy consumption of a field device is increased due to the device having to wait for incoming messages for a longer time.

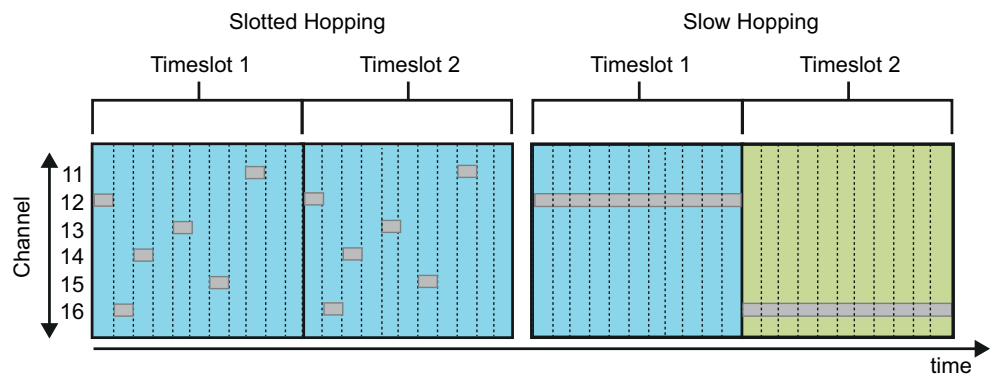


Fig. 17 Comparison of slotted hopping and slow hopping

**Hybrid hopping**

Hybrid hopping combines the advantages of slotted and slow hopping. The combination of slow and slotted hopping is configurable. This way, planned transmissions can be performed in small time slots and unplanned transmissions can be performed on another channel that has a longer time slot available.

For further information see: "Time-Division-Multiple-Access (TDMA)", page 28.

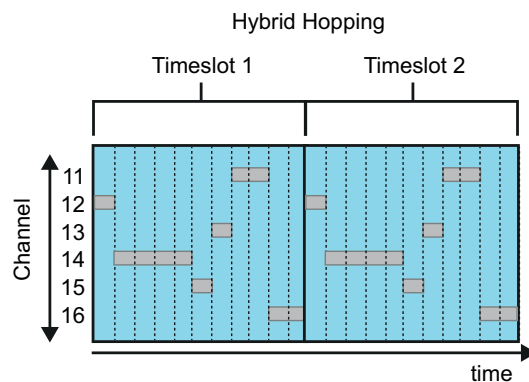


Fig. 18 Hybrid hopping

**4.2.3****Standard hopping pattern**

ISA100 Wireless™ defines 5 standard hopping patterns. A standard hopping pattern defines the channel sequence. Every field device must support the pattern.

- A 19, 12, 20, 24, 16, 23, 18, 25, 14, 21, 11, 15, 22, 17, 23, 26 (optional)
- B Reverse order of A
- C 3, 15, 20, 25
- D Reverse order of C
- E 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26 (optional)

#### 4.2.4 Duo-Cast

Duo-Cast (dual transmission) is the option of sending data packets to access points via 2 communication paths simultaneously. The access points must be synchronized for this. When Duo-Cast is active, communication is only possible with the synchronized access points. This creates a star topology. Other topologies (mesh, partial mesh) are excluded.

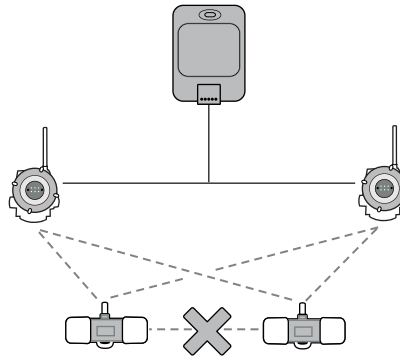


Fig. 19 Communication between field devices is not possible with duo-cast.

**i** Duo-Cast is configured in the system manager during Provisioning. Some system manager user interfaces allow for setting Duo-Cast and mesh topologies. However, these settings cannot be downloaded to the system manager.

#### 4.2.5 Time-Division-Multiple-Access (TDMA)

Time-Division-Multiple-Access defines the time slot in which messages can be sent and received on certain channels. The time slot duration can be set variably. It can be between 10 and 12 ms.

The variable duration enables the close timing of many short transmissions.

To send a number of status messages from different field devices as a bundle (from a router/access point to the backbone), a time slot with a longer duration is suitable.

#### 4.2.6 Clear channel assessment (CCA)

Clear channel assessment is performed by a field device before sending data packets. The field device checks whether the channel is free. If the channel is not free, the field device waits a set amount of time (generally several milliseconds) before attempting to send the data packet again.

#### 4.2.7 Automatic-Repeat-reQuest (ARQ)

Automatic repeat request enables sending unacknowledged data packets on another radio channel and via a different communication path.

Each received data packet must be acknowledged by the receiving participant within a set amount of time.

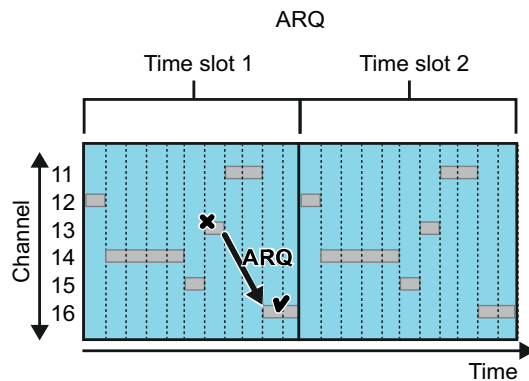


Fig. 20 Repeat transmission via another channel

#### 4.2.8 Blacklisting

Blacklisting is the exclusion of channels by the system manager. The system manager excludes channels based on performance data sent by the field devices. Other radio technologies can be the source of poor performance data. Field devices avoid these excluded channels during frequency hopping.

##### Manual blacklisting

Wireless channels can also be blocked manually in the system manager. When the settings have been performed in the system manager, the system manager distributes the information in the network. The network participants are updated.

#### 4.2.9 Adaptive hopping

Adaptive-Hopping is very similar to Blacklisting. As with Blacklisting, the performance data is used to decide whether an action is performed. An action in this case is the switch to another channel. In contrast to Blacklisting, the field device itself decides this. This enables the field device to adjust itself independently to the frequency spectrum without depending on the system manager.

Adaptive hopping is activated by default.

#### 4.2.10 Path diversity

Path diversity continuously adjusts redundant communication paths. This adjustment is made based on the collected performance data.

Redundant paths are established by the network itself. Users do not have to take action.

Routing and Forwarding contribute to path diversity.


##### Forwarding

Forwarding is oftentimes also called Routing. Forwarding, however, is the decision-making process of a network participant on which communication path the data packets are forwarded over.

### **Routing**

Data packets take different communication paths. The routing is the way specified by the system manager.

---

 Routing is possible in different ways. For further information see: "Types of routing", page 30.

---

## **4.2.11**

### **Types of routing**

Routings are predefined communication paths for data packets. The predefined communication paths can be implemented in various ways.

#### **Graph routing**

In graph routing, all possible communication paths in the network are loaded onto each participant in the form of a routing table. When a data packet is sent, the sending participant writes the identification of the communication path in the packet's header. The next participant compares the identification with the routing table and forwards the packet.

#### **Source routing**

In source routing, the entire communication path is integrated into the data packet. Every network participant forwards the packet to the node specified in the data packet itself.

## **4.3**

### **Data structure**

#### **Object-oriented data model**

The ISA100 Wireless™ protocol is object-oriented. Object-oriented models describe and distinguish components and tasks of the real world in objects. Objects are an abstract representation of a specific device component or field device task.

The following task is an example of an object: methane concentration monitoring. The object must have at least one field for the current measured value data. For the measured value, Dräger uses the Process value "PV" of the ISA100 Wireless™ protocol.

ISA100 Wireless™ defines obligatory standard objects. In addition, devices can contain optional standard objects or manufacturer-specific objects.

An example of a manufacturer-specific object is the object for the PROFIsafe® communication (Custom\_("SafeData")). Observe the following information: "UAP, objects, attributes and parameters using the example of the GS01 in the Yokogawa YFGW 410 configurator (as at July 2018)", page 33.

### 4.3.1 Data fields

Regardless of their status as either standard or manufacturer-specific objects, objects always contain data fields for alarms, methods<sup>1)</sup> and attributes. Depending on the command, these are either read, written, triggered, stopped or acknowledged.

#### Methods

Methods are actions the corresponding device performs. Examples of methods are sensor adjustments or firmware updates.

#### Attributes

Attributes are device values (sensor temperature, for example) or measured values. ISA100 Wireless™ defines 5 classes of attributes (see "Attribute classes", page 34).

#### Alarms

Alarms can be set in addition to attributes. They are provided via the "alert reporting management object" (ARMO).

In order to be more flexible and to reduce complexity, Dräger gas warning devices do not support the function via ARMO. Measured values are provided as process values (PV). The user can edit the corresponding alarm values at the control unit. Editing at the controller is more flexible than via the ISA100 Wireless™ protocol at the gas warning device.

#### Parameters

The combination of object identifier and an object's attribute, method or alarm is called a parameter. The parameter for monitoring the methane concentration would therefore be: AI\_01("METHANE").PV.

AI stands for Analog Input

PV stands for Process Value

#### Failsafe parameters

For failsafe data transmission (e.g. via PROFIsafe®), manufacturer-specific objects are available in addition to the standard objects. The parameters of the manufacturer-specific objects are named as "SafeData" with the corresponding attribute (Custom\_00("SafeData").Attribut2(12), for example).

---

1) Also known as routines or operations.

### 4.3.2 User application process (UAP)

A device's objects can be found in the device software in the so-called User Application Process (UAP). A device can have multiple UAPs. To ensure compatibility with the system manager, Dräger gas warning devices only have one UAP.

Every UAP contains a main object which indicates the status of the UAP. Aside from the status, the main object also indicates the amount and types of the other objects of the UAP. This main object is called the User Application Management Object (UAPMO).

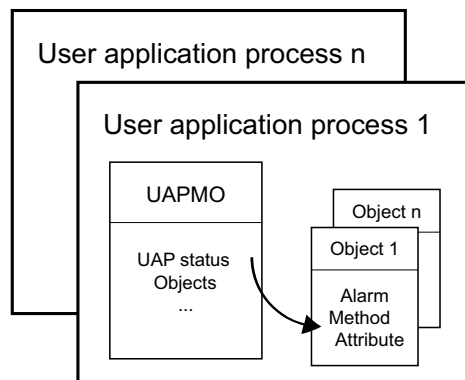


Fig. 21 UAP with UAPMO and corresponding objects

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## 4.3.2.1

**UAP and parameters in the Yokogawa YFGW 410 configurator**

The following diagram uses the GS01 as an example to show the display of the UAP, the corresponding objects, attributes and parameters in the configuration screen of a system manager (Yokogawa YFGW410).

Here, the UAP with the corresponding UAPMO object and the other objects are displayed.

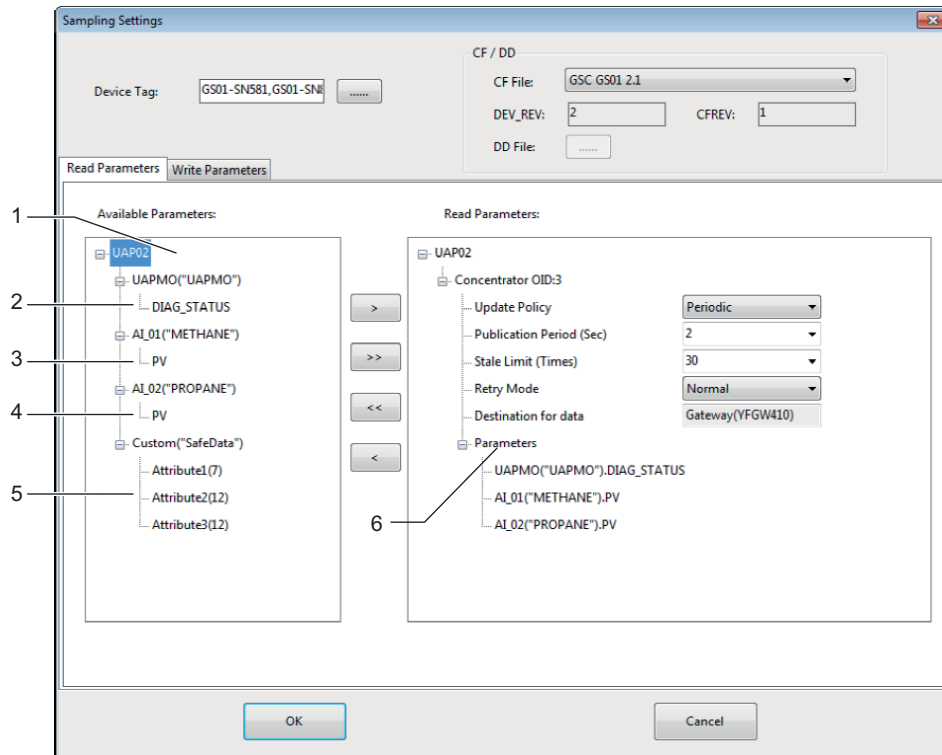


Fig. 22 UAP, objects, attributes and parameters using the example of the GS01 in the Yokogawa YFGW 410 configurator (as at July 2018)

- |   |                                                                                                        |
|---|--------------------------------------------------------------------------------------------------------|
| 1 | UAP with the UAPMO object, the gas concentration monitoring objects and a Custom object named SafeData |
| 2 | Readable DIAG_Status attribute                                                                         |
| 3 | Readable process value (PV) attribute for methane                                                      |
| 4 | Readable process value (PV) attribute for propane                                                      |
| 5 | Manufacturer-specific attributes                                                                       |
| 6 | Readable parameters of the UAP02.                                                                      |

## 4.3.3

**Object identifiers**

In addition to their names, objects also have unique identifiers. Object identifiers are 16 bits long. They can be used for finding and uniquely identifying them in the system manager.

UAPMO objects always have the identifier 1 (0x0001). Identifier 2 is reserved for UDO objects (0x0002). UDO objects are upload/download objects. They are used to transmit firmware updates.

#### **Dräger-specific object identifiers**

In addition to UAPMO and UDO objects, gas warning devices also contain objects with the following identifiers:

- 6 (0x0006) process value for methane
- 7 (0x0007) process value for propane
- 8 (0x0008) process value for EC sensor measuring gases (hydrogen sulfide, for example)

### **4.3.4**

#### **Attribute classes**

##### **Constant**

The values of these attributes must remain constant. If a device is disconnected from the power supply, reset or rebooted, the values of these attributes must remain unchanged (the serial number of a wireless node, for example).

##### **Static**

The values of these attributes rarely change. These values only change due to an external trigger. A trigger can be a configuration tool, for example. The values of these attributes should remain unchanged if a device is disconnected from the power supply or rebooted (units or operating areas, for example).

##### **Static-volatile**

The values of these attributes can change when the device is disconnected from the power supply or rebooted.

##### **Dynamic**

The values of these attributes can be changed by the field device itself. These values do not have to remain unchanged when a device is disconnected from the power supply or rebooted (process variables, timers or calculation results, for example).

##### **Non-bufferable**

The values of these attributes may not be cached. These values must be queried directly from the field device. These values may not be queried from the cache of a network node (critical safety information, for example).

### 4.3.5 Data format (without PROFIsafe® communication)

The DIAG\_STATUS byte is 4 bytes long and contains information on device performance and signal properties. The UAP parameters are 4+1 bytes long. Each parameter includes a status byte that indicates the quality of the value.

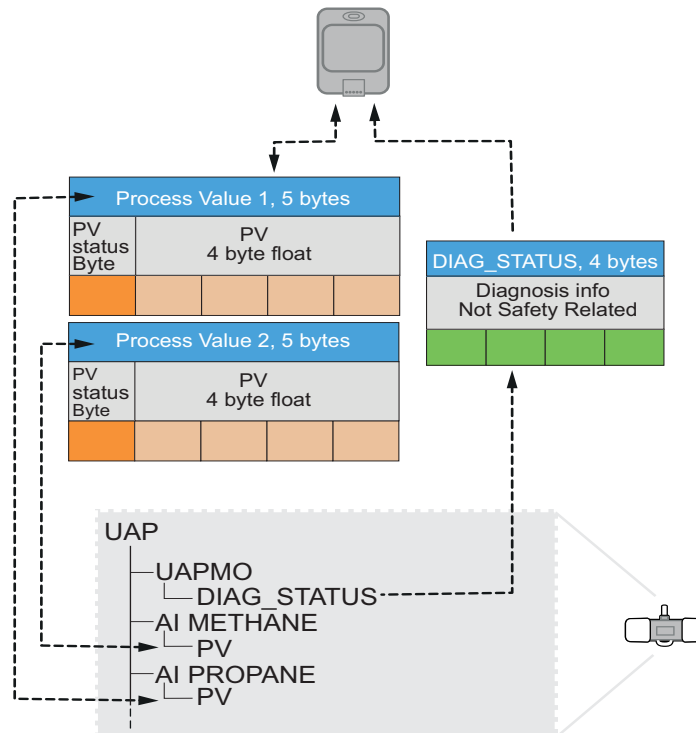


Fig. 23 Example process value data format

## 4.4 Traffic

ISA100 Wireless™ defines 3 data transmission methods

- Unidirectional, buffered data
- Unidirectional, queued data
- Bidirectional, queued data

Dräger only uses 1:1 data transmission between field devices and the system manager or F-host. This includes data transmissions via hop points. This data transmission method is known as client-server service and uses bidirectional, queued data.

#### 4.4.1 Data query

UAP data and field device performance are queried cyclically.

The UAP data contains the field device's parameters (process value for methane concentration, for example). Each of these parameters returns a value which provides information on the attribute quality. This value is known as a status byte.

The field device performance contains information on the field device's status and signal properties. This data is transmitted in the DIAG\_STATUS attribute.

For further information see: "Data format (without PROFIsafe® communication)", page 35.

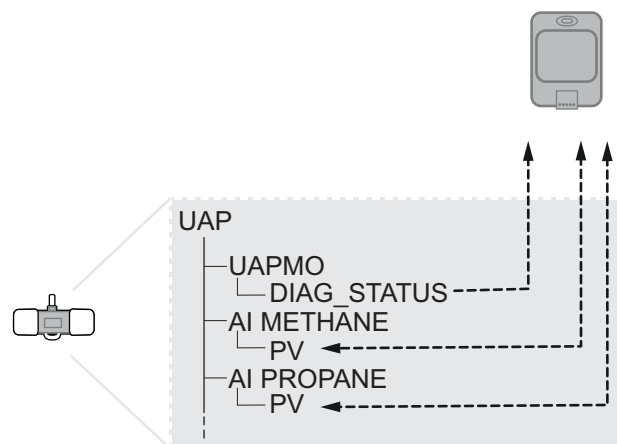


Fig. 24 Parameter with status byte and DIAG\_STATUS attribute during system manager transmission

#### 4.4.2 Sampling rate and stale limit

##### Sampling rate

The sampling rate (publication period) determines the time intervals at which uplink transmissions are sent by the gas warning device.

##### Stale limit

The stale limit, together with the sampling rate, determines the time slot within which uplink transmissions from the gas warning device must arrive at the system manager. If no uplink transmissions arrive within the time slot, the gas warning device will be marked as not available.

The following formula illustrates the relationship between sampling rate, time slot and stale limit.

$$\text{Time slot} = \text{stale limit} \times \text{sampling rate}$$

**Example: Sampling rate and stale limit**

The following example illustrates the relationship between stale limit, sampling rate and the time slot after which the gas warning device will be marked as unavailable.

In this example, the failure of the gas warning device or a poor wireless interface will be recognized after a time slot of 60 seconds.

Stale limit = 30

Sampling rate = 2 seconds

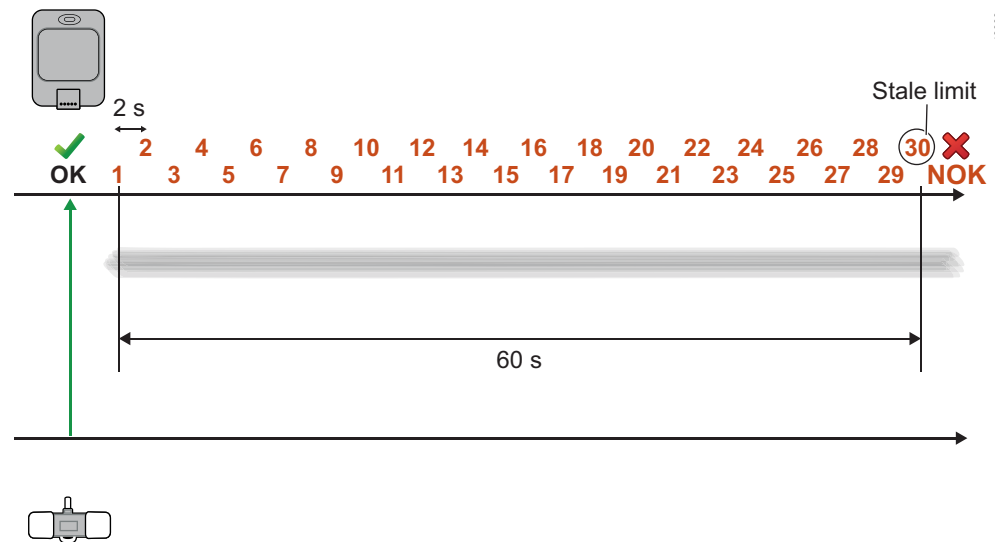


Fig. 25 Relationship between the sampling rate and stale limit

### 4.4.3 Network and energy management with ISA100 wireless communication

The wireless communication takes place between the field device and the system manager. Field devices must transmit new sampling rate and stale limit data within the time slot defined in the system manager. If new data does not arrive within the predefined time limit, the field device in the system manager and in the controller will be marked as unavailable.

The number of available time slots for the uplink transmission, i.e. from field device to system manager, is determined by the sampling rate. If there is no internal alarm condition, not all uplink time slots will be used (see illustration below). This mode of operation saves energy. If there is an internal alarm condition, all uplink time slots will be used to ensure quick communication. The relationship between available time slots and time slots used in the absence of an alarm condition is described as the publication factor. The threshold value for the internal alarm condition and the publication factor are determined in the field device.

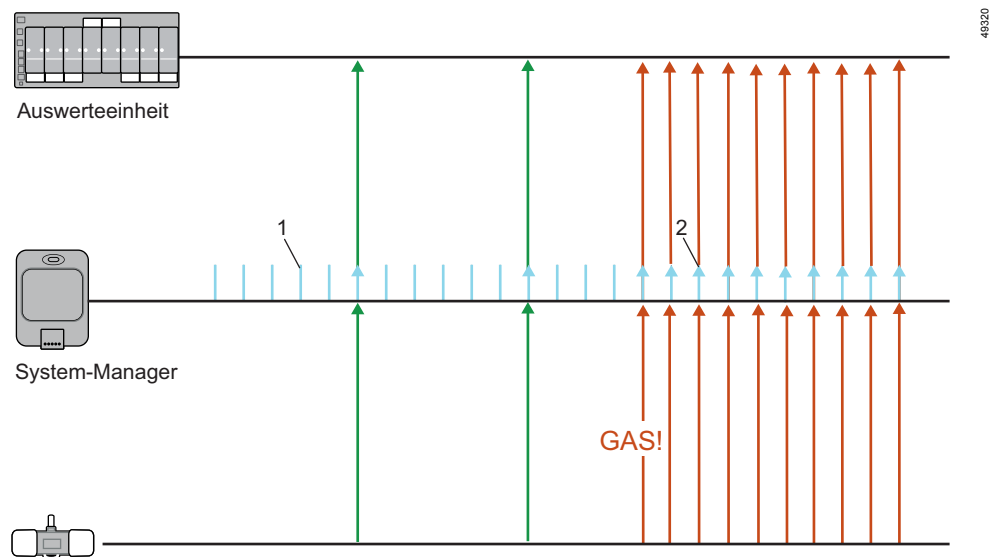


Fig. 26 Relationship between time slots and alarm conditions

Blue	Time slots for uplink transmissions
1	Time slots are not used because no alarm condition is present.
2	The presence of an alarm condition means all time slots will be used.

#### 4.4.4 Device performance information

##### **Energy life**

The battery status gives an estimate of the remaining operating time of the field device. This status is also displayed as "Days Left".

Unit: Values greater than 0 specify the remaining operating time in months. If the remaining operating times are only days, values smaller than zero are displayed.

##### **Listen rate**

Duration for which the field device can have its receiver switched on.

Unit: seconds or hours

##### **Transmit rate**

Duration for which the field device can have its transmitter switched on.

Unit: data packets or minutes

##### **Advertisement rate**

Duration for which the field device can transmit Advertisements. Field devices that support OTA send Advertisements. For further information see: "Over the air provisioning (OTA)", page 48.

Unit: Advertisements or minutes

## 5 Transmission basics for PROFIsafe® communication

With PROFIsafe® communication, failsafe field devices (F-slave) and failsafe controllers (F-host) communicate directly with each other. The infrastructure (e.g. system manager) only forwards the data.

The PROFIsafe® communication takes place in the black channel of the ISA100 Wireless™ communication. Communication via ISA100 Wireless™ continues to follow the specifications described in this document (e.g. requirements from 4).

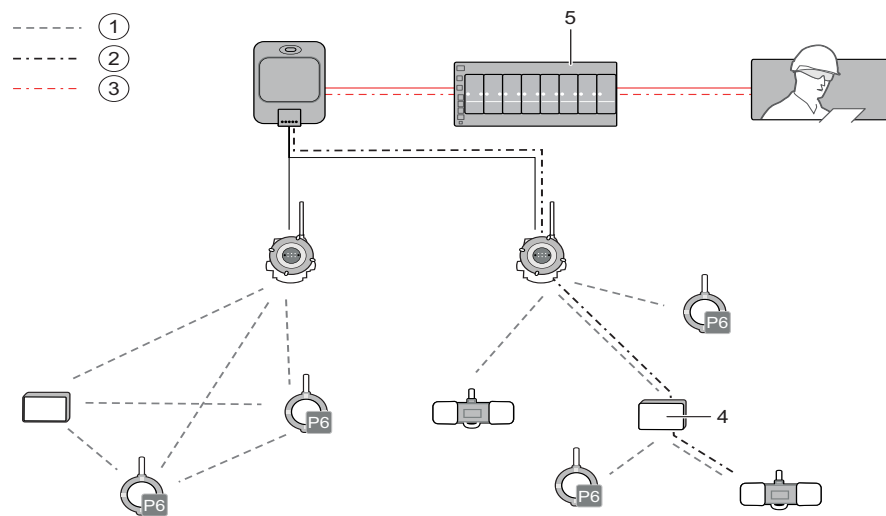


Fig. 27 PROFIsafe® communication between gas warning device (F-slave) and controller (F-host)

1	Wireless standard communication via ISA100 Wireless™ protocol
2	PROFIsafe® in black channel via ISA100 Wireless™ protocol
3	PROFIsafe® in black channel via PROFINET protocol
4	Field device (hop point) that forwards the tunneled message without processing.
5	Controller for interpreting the PROFIsafe® signals

The PROFIsafe® protocol allows for the use of a failsafe network for safety-oriented applications according to the following standards:

- SIL 3 (IEC 61508 / IEC 62061)
- Safety category 4 (EN 954-1)
- PL "e" (ISO 13849-1)

### 5.1 Black channel principle

The black channel principle enables the exchange of system- and safety-relevant data over the same network (Physical Layer). System-relevant data in this case can be the sensor vitality or adjustment interval status, etc. Safety-relevant data comprises error messages, alarm acknowledgments and pre- and main alarms.



Safety-relevant data is only evaluated by the corresponding F-slave and the F-host. All other network participants such as hop points, access points, or system managers are considered transparent.

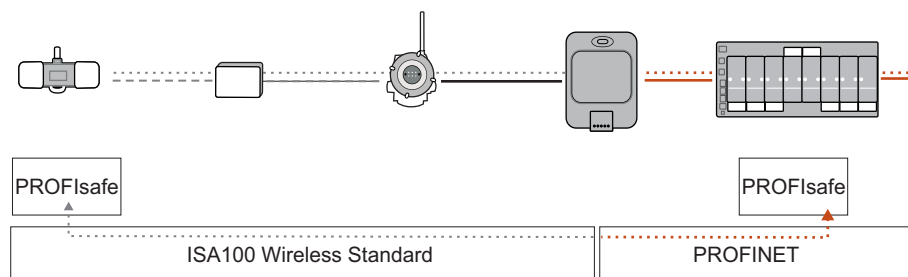


Fig. 28 PROFI-safe® communication

## 5.2 Data integrity for PROFI-safe® communication

The following measures and parameters guarantee the integrity of the data exchanged between F-host and F-slave in the black channel.

- Signal of life  
Data packages must be sent sequentially. A sequential number counter in the F-host and F-slave ensures this is the case.
- Watchdog  
Received data packets must be acknowledged.
- Safe address  
Transmitter and receiver must have a unique identifier.
- Time stamped security  
A timeout counter always starts when the transmission of a data package begins. The data package will only be accepted if it is received within a predefined “WD\_timeout” time limit. F-host and F-slave have their own counters and a time stamp for uplink and downlink transmission.
- Cyclic redundancy check - CRC (cyclic block check)  
Data completeness and consistency are checked.  
In addition to completeness and consistency of the data, whether configuration of the F-slave has changed is also verified. The CRC contains a parameter which provides information about the configuration of the F-slave. This parameter is transmitted to the F-host with the network integration of the F-slave and synchronized during data exchange. If configuration of the F-slave changes, the parameters specified during network integration and the transmitted parameters are no longer identical. If the CRC parameters are not identical, an SIL 2-compliant communication will no longer be possible.

### 5.2.1 PROFI-safe® network constraints

- The maximum number of hop points connected in series must be observed for short response times. For further information see: "Hop points in a sub-network", page 13.
- The IP addresses within a sub-network must be unique.
- If 2 sub-networks with the same IP address space are connected to one router, that router must be a multi-port router.

## 5.3 Data structure

### 5.3.1 Data fields

In addition to the data fields for communication via ISA100 Wireless™, further data fields from the manufacturer-specific objects will be required for the PROFI-safe® communication.

#### Failsafe parameters

For failsafe data transmission (e.g. via PROFI-safe®), manufacturer-specific objects are available in addition to the standard objects. The parameters of the manufacturer-specific objects are named as "SafeData" with the corresponding attribute (Custom\_00("SafeData").Attribut2(12), for example).

### 5.3.2 Data format for PROFIsafe® communication

In addition to standard data formats, manufacturer-specific custom parameters (SafeData) are also transmitted during PROFIsafe® communication

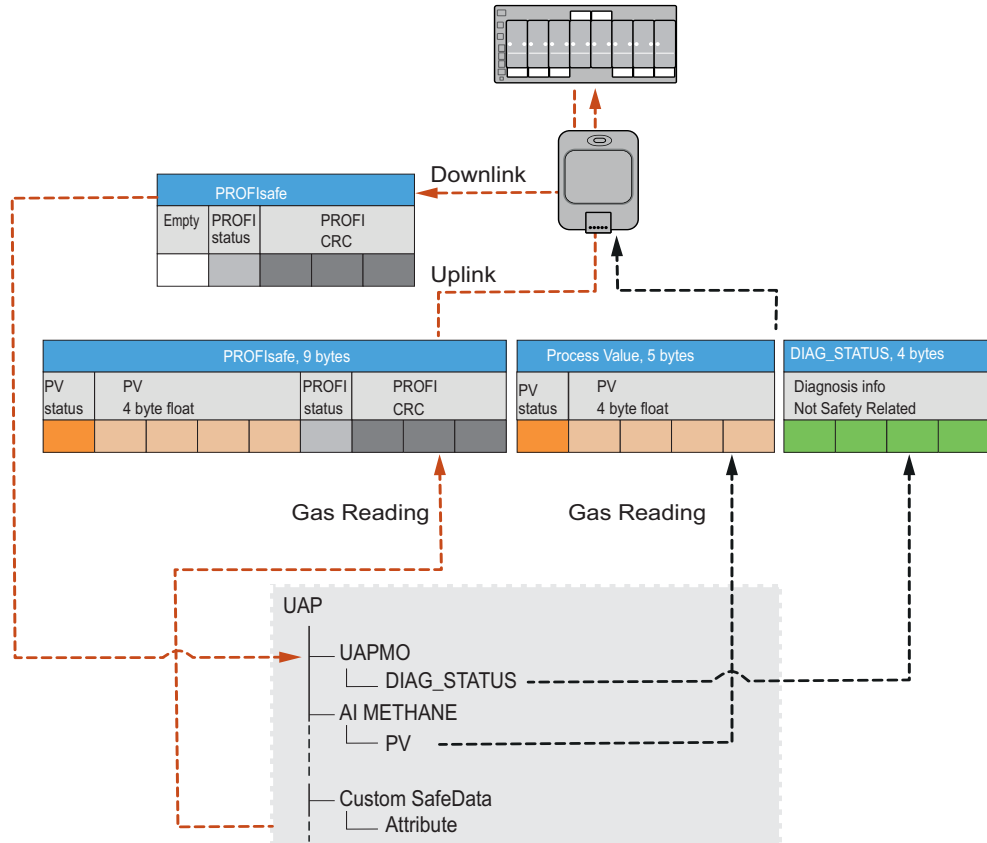


Fig. 29 Example PROFIsafe® process value data format

## 5.4 Traffic for PROFIsafe® communication

PROFIsafe® communication takes place between F-host and F-slave. F-slaves are passive. They can only respond to messages from the F-host. When the F-host has received the response, the next message is sent directly.

F-slaves must respond within a set time period. If there is no response within the predefined time period, the F-slave is marked as unavailable in the control center.

Each message must be followed by a reply (one-to-one communication). The F-slave can only send data once a new message has been sent from the F-host.

### Stale limit, sampling rate and publication factor for PROFIsafe®

The settings for ISA100 Wireless™ communication for stale limit, sampling rate (publication period) and publication factor are also valid during PROFIsafe® communication. For further information see: "ISA100 Wireless™ data transmission basics", page 25.

## Uplink and downlink transmissions

Downlink transmission is the transmission of data from the F-host to the F-slave. The F-slave responds with an uplink transmission.

## Time slots for uplink and downlink transmissions

The sampling rates set in the system manager determine the available time slots for the downlink transmission to the F-slave and the uplink transmission to the F-host. The threshold value for the internal alarm status is set in the field device. If no alarm condition is present, not all uplink time slots will be used. This mode of operation saves energy. As the response to an F-host message is delayed until just before the subsequent F-host message is expected, the field device is always prepared and ready to immediately report an alarm.

If an alarm condition is present, the F-slave (field device) always reacts immediately to the message from the F-host.

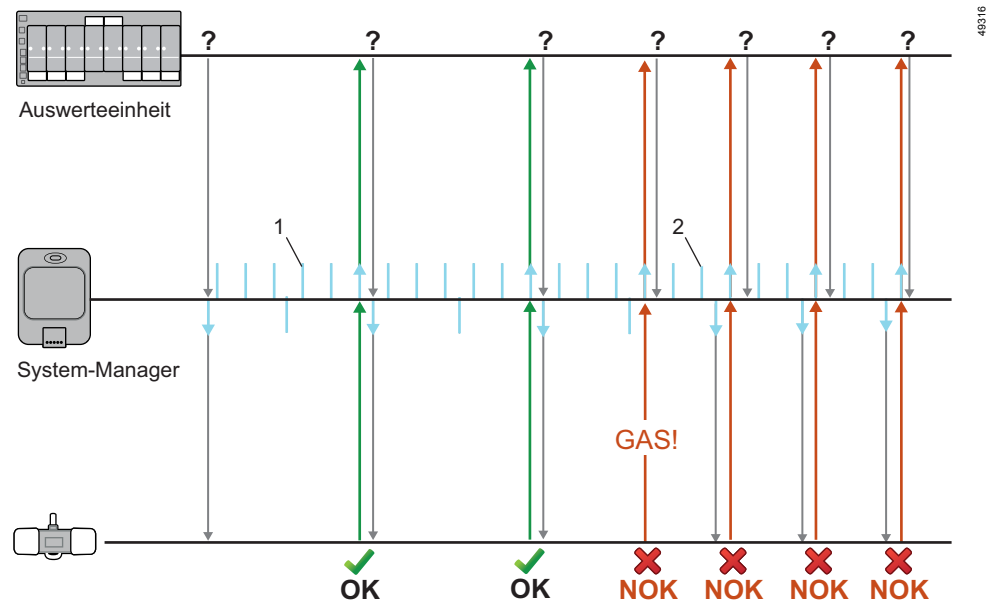


Fig. 30 Relationship between transmissions and alarm conditions

Blue	Time slots for downlink transmissions (direction F-slave) and uplink transmissions (direction F-host)
1	Uplink time slots are not used because there is no alarm condition present.
2	Because an alarm condition is present, the first available time slot is used for uplink transmissions.

## 6 Network integration (provisioning) of gas warning devices

Gas warning devices can be integrated into networks in two ways.

- Network integration with a provisioning device "Out of band" (OOB)  
In this case, a provisioning device reads out the gas warning device on-site and sets values. The read-out data is then loaded into the system manager. A provisioning device can be a handheld scanner or laptop with the corresponding software, which communicates with the gas warning device via an infrared interface, Bluetooth®, or wired adapter.
- Wireless network integration "Over the air" (OTA)  
In this case, the gas warning device joins an open (unsecured) provisioning sub-network. The gas warning device is then transferred from this sub-network to the operative sub-network.

During network integration, various settings and parameters are set for the gas warning device and the device is integrated into the network. The settings are made in the configuration software of the system manager. The configuration software is called up in the browser of a computer (Microsoft Internet Explorer and Microsoft Edge are currently suitable options).

### 6.1 Network integration parameters

#### 6.1.1 Modbus parameters

The parameters for the device status and process values are mapped to the Modbus registers (16 bits) in the configuration software of the system manager.

Process values (PV) occupy 3 registers. The status byte of the process values occupies the first 8 bits of the first register. The process value (32 bit floating point number) is divided among the other two registers.

The device status in the DIAG\_STATUS parameter is mapped to 2 registers.

Several gateways (e.g. Yokogawa) insert a status byte into the preceding register. This gateway status byte is ignored as the content has already been provided by the PV status byte.

#### 6.1.2 PROFIsafe® traffic

PROFIsafe® parameters contain data for the parameterization and operation of failsafe networks. The integrity of the data is verified by the receiver.

The following parameters are required for network integration.

- F-device address (safe address of the F-slave)  
Unique address of a field device in the network for failsafe data transmission.
- F-host address (safe address of the host)  
Unique address of the control unit in the network for failsafe data transmission.
- Watchdog timeout  
The time [ms] that may elapse after sending a data packet is entered here (time-stamped security).
- SIL  
Contains the expected SIL.

- iParameter CRC  
The configuration of the F-slave defines the value of this parameter. The F-slave parameter is stored in the F-host during network integration. For further information see: "Data integrity for PROFI-safe® communication", page 41.
- With Dräger Polytron® 6100 EC WL, this parameter is read out using the Dräger PolySoft configuration software (Version 1.9.0 or later).
- With GasSecure GS01, possible values for this parameter can be found in the GS01 and GS01-EA Safety Manual (Doc-ID 21440).

## 6.2 Out Of Band Provisioning (OOB, Yokogawa gateway only)

A provisioning device is required for OOB. OOB communication devices include the infrared adapter (e.g. Actisys ACT-IR224UN-LN96-LE), BLE (Bluetooth Low Energy), and wired front ports (e.g. serial GS01 adapter). Various data and files are required for the network integration of gas warning devices and provisioning devices:

- Information on stale limit and sampling rate
- Capability file (CF file)<sup>1)</sup> for the gas warning device

These files contain information from the gas warning device. They can be compared to drivers for devices connected to a computer.

- Provisioning file (.ypif file)

This file is created with the provisioning device that is connected to the field device and contains the following information:

- Date and time of the provisioning file creation
- Join-Key  
The join key is a 128-bit-long alphanumeric key which is synchronized during network integration in the system manager.
- Device tag of the gas warning device  
The device tag is the gas warning device's unique identifier in the network.
- EUI64 address  
The EUI64 is the gas warning device's world-wide unique identifier. It is 64 bits long and is formatted as a standard MAC address.
- Network ID  
The network ID is the unique identifier of the network into which the gas warning device is integrated.

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1) Device description files (DD) are not currently supported (as at September 2020).

**Network integration with provisioning device**

The integration of gas warning devices into a wireless network can be divided into a few main steps.

1. Create the gas warning device's provisioning file (.ypif file).

A connection between the gas warning device and a provisioning device (a laptop, for example) with the corresponding software is required for this. For Polytron®6100 EC WL and Polytron® Repeater ISA100, PolySoft (Version 1.9.0 or higher) is the configuration tool, while the GasSecure GS01 Configurator is used for GS01. Wireless products from third-party providers may require other tools (e.g. FieldMate for Yokogawa products).

- a. Set the network ID
  - b. Create a join key
  - c. Assign the device tag of the gas warning device
2. Read the provisioning file into the system manager.
  3. Determine the gas warning device's task (hop point, simple I/O field device or both).
  4. Determine the communication paths for the gas warning device.
  5. Read the gas warning device's capability file (CF) into the system manager.
  6. Set the parameters of the gas warning device.

Values for the read and write parameters must be set in the system manager (the process value for the gas concentration, for example).

7. Set the properties for reading and writing parameters (stale limit and sampling rate, for example).
8. Save the settings in the system manager.

The settings made in the system manager's configuration software must still be saved in the system manager. In the configuration software, saving is often called "downloading".

- ✓ The system manager updates the network and the gas warning device with the data entered.

## 6.3 Over the air provisioning (OTA)

### Neighbor discovery and advertisements

Some field devices support OTA provisioning. OTA provisioning integrates new field devices directly from the system manager. No provisioning device is required.

A neighbor discovery is performed by some field devices for this function. These field devices send Advertisements. A field device wishing to be integrated into the network responds to the advertisements.

### Wireless network integration (OTA)

The wireless network integration of gas warning devices can be divided into a few main steps.

1. Set the gas warning device to default via the configuration software of the gas warning device.
  2. Turn on the gas warning device.
    - ⇒ The gas warning device waits for Advertisements
  3. Add the gas warning device in the configuration software of the system manager.
    - ⇒ The system manager searches for and establishes the communication paths and access points for the gas warning device.
  4. Read the gas warning device's capability file (CF) or the device description file (DD) into the system manager.
  5. Set the parameters of the gas warning device.

The read/write parameters must be set in the system manager (send/uplink and receive/downlink).
  6. Set the properties for reading and writing parameters (stale limit and sampling rate, for example).
  7. Download the settings to the system manager.

The settings made in the system manager's configuration software must still be saved in the system manager. In the configuration software, saving is often called "downloading".
- ✓ The system manager updates the network and the gas warning device with the data entered.



## 7 Troubleshooting

### 7.1 Errors during network integration

#### Errors in large networks

Communication paths with more than 4 series-connected hop points are not supported by the Yokogawa system managers (status: September 2020).

### 7.2 Errors during operation

Errors in the field device or the connection to the field device are visible in the DIAG\_STATUS attribute and in the status byte.

- Status byte  
Every attribute provided in the UAP has a status byte. The status byte provides information on the quality of the transmitted value.
- DIAG\_STATUS attribute  
The DIAG\_STATUS attribute provides information on the gas warning device's state.

#### 7.2.1 Status byte of a transmitted value

If the status of the byte is "Good" or "Uncertain", the content of the process value corresponds to the current measured value (for process values for gas concentrations)

If the status is "Bad", NaN (Not a Number) will be transmitted as a process value and 0x7fc00000 as a status byte. This corresponds to the definition of IEEE754. The cause of the bad status is given in the DIAG\_STATUS attribute.

Quality	Decimal value	Description
Good	128	Normal operation
Uncertain	64 ... 127	The integrity of the data is uncertain.
Bad	< 64	No connection or hardware failure.

The following table shows the status byte bits determined by the standard. Not all substatus and limit conditions are implemented in the gas warning devices; please refer to the documentation provided with the respective gas warning device for implemented bits.

### Status byte bits

Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)
Quality		<reserved>	Substatus (quality-dependent)			Limit condition	
0 = Bad Value should not be used		This bit should always be set to 0.	0 = non-specific			0 = Not limited 1 = Low limit 2 = High limit 4 = Constant	
			1 = configuration error				
			2 = not connected				
			3 = device failure				
			4 = sensor failure				
			5 = no communication with LUV (last used value)				
			6 = no communication no LUV				
			7 = out of service				
			All other values are reserved.				
1 = Uncertain Quality less than normal		This bit should always be set to 0.	0 = non-specific			0 = Not limited 1 = Low limit 2 = High limit 4 = Constant	
			1 = last usable value				
			2 = substituted or manual entry				
			3 = initial value				
			4 = sensor conversion inaccurate				
			5 = range limits exceeded				
			6 = sub normal				
			All other values are reserved.				
2 = Good (Good) Measured value quality good, but alarm condition could be present		This bit should always be set to 0.	0 = no special conditions exist			0 = Not limited 1 = Low limit 2 = High limit 4 = Constant	
			All other values are reserved.				
3 = Reserved (Reserved)		This bit should always be set to 0.	All values are reserved. Should always be set to 0 in this configuration.			0 = Not limited 1 = Low limit 2 = High limit 4 = Constant	

## 7.2.2 DIAG\_STATUS attribute byte

Bit	DIAG_STATUS	NAMUR NE 107
31	F: Failure status	
30	C: Function check	
29	O: Out of specification status	
28	M: Maintenance required status	
27	Faults in electronics	F
26	Faults in sensor or actuator element	F
25	Installation, calibration problem	C
24	Out of service	C
23	Outside sensor limits	O
22	Environmental conditions, out of device spec.	O
21	Fault prediction: Maintenance required	M
20	Power is critically low: maintenance short term	F M
19	Power is low: maintenance long term	M
18	Software update incomplete	C
17	Simulation is active	C
16	Faults due to process influence	C
15	Faults due to non-compliance with operation conditions	F
14	Other faults	F
13	Reserved for baseline device profile	
12	Reserved for baseline device profile	
11	Reserved for baseline device profile	
10	Reserved for baseline device profile	
09	Reserved for baseline device profile	
08	Manufacturer-specific, only for GS01: Optical beam block fault	F M
07	Manufacturer-specific, only for GS01: Attenuated optical beam	M
06	Manufacturer-specific, only for Polytron 6100 EC WL: Warm-up 1	O
05	Manufacturer-specific, only for Polytron 6100 EC WL: Calibration interval warning	M
04	Manufacturer-specific, only for Polytron 6100 EC WL: Sensor selftest warning	M

Bit	DIAG_STATUS	NAMUR NE 107
03	Manufacturer-specific, only for Polytron 6100 EC WL: Network connectivity error	F
02	Manufacturer-specific	
01	Manufacturer-specific	
00	Detailed information available	

## 8 Recommended network components

The interoperability of network components from different manufacturers has not yet been tested (e.g. a system manager from manufacturer A together with an access point from manufacturer B). Dräger recommends only using network components from one manufacturer.

### 8.1 Network components recommended without restrictions

The following devices can be used without restrictions (status September 2018).

#### 8.1.1 System manager

- Honeywell OneWireless Device Manager WDMX<sup>1)</sup>
- Honeywell OneWireless Device Manager WDMY<sup>2)</sup>
- Yokogawa Field Wireless Management Station YFGW410

#### 8.1.2 Access points

- Honeywell OneWireless Field Device Access Point FDAP2<sup>3)</sup>
- Honeywell OneWireless Field Device Access Point FDAP1<sup>4)</sup>
- Yokogawa Field Wireless Access Point YFGW510
- Yokogawa Field Wireless Access Point YFGW520

#### 8.1.3 Other components

- Yokogawa Field Wireless Media Converter YFGW610  
Converter for the transition between fiber-optic cables (100BASE-FX) and copper cables (100BASE-TX)

### 8.2 Network components recommended with restrictions

The following devices can be used with certain restrictions (status September 2020).

#### 8.2.1 System manager

- Yokogawa Field Wireless Communication Module FN110 with Interface Adapter LN90<sup>5)</sup>

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1) Software version  $\geq$  R300 for GS01, software version  $\geq$  R320 for Polytron 6100

2) Software version  $\geq$  R300 for GS01, software version  $\geq$  R320 for Polytron 6100

3) Software version  $\geq$  R300

4) Software version  $\geq$  R300

5) This recommendation is with restrictions because some functions are not available.


## 9 Glossary

Glossary entry	Description
Network component	Network components make up the network's infrastructure. They are an integral part of the infrastructure. Network components include the system manager, e.g. system manager and the access points.
Network participants	Network participants are not integral parts of the infrastructure. They participate in the network and can extend it (hop points). Field devices are network participants.
IPv4 address	IPv4 addresses have a 32 bit numeric address. The numbers are separated by 4 periods (e.g. 1.170.10.255).
IPv6 address	IPv6 addresses have a 128 bit hexadecimal address. The characters are separated by colons (e.g. 4ffe:1801:5545:3:155:e8ff:ef22:56df).
Gateway	In this manual: synonymous with the system manager. In another context, a distinction would have to be made between the gateway and the system manager.
Backbone	The backbone is the main line of a network.
Latency	In this context: delay in transmission of a message
Uplink transmission	Data transmission from a field device (client) to the system manager or control unit (server)
Downlink transmission	Data transmission from the system manager or the control unit (server) to a field device (client)
100BASE-TX	100BASE-TX is a media type for Fast Ethernet transmission. The medium is copper in CAT 5 cables.
100BASE-FX	100BASE-FX is a media type for Ethernet transmission. The medium is fiber-optic cables.

## 9.1 Glossary on parameter and object names

Parameter names consist of the object ID and the attribute. Object ID and attribute are abbreviated.

Glossary entry	Description
GW_STATUS	Gateway status, status of the system manager
BBR_STATUS	Backbone router status
DEV_STATUS	Device status
AI_xx("BLOCK_DEXCRIPTION").PV	Analog input, analog process value
UAP	The user application process is a main component of the field device firmware. The UAP contains all readable and writable objects of the field device.
UAPMO	The user application process management object contains information on the status and the objects of the UAP.
UDO	UDO objects are upload/download objects. They are used for transmitting firmware updates.

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