EV-SOMCRR-EZKIT ® Manual

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Regulatory Compliance

The *EV-SOMCRR-EZKIT* evaluation board is designed to be used solely in a laboratory environment. The board is not intended for use as a consumer-end product or as a portion of a consumer-end product. The board is an open system design, which does not include a shielded enclosure and, therefore, may cause interference to other electrical devices in close proximity. This board should not be used in or near any medical equipment or RF devices.

The *EV-SOMCRR-EZKIT* evaluation board contains ESD (electrostatic discharge) sensitive devices. Electrostatic charges readily accumulate on the human body and equipment and can discharge without detection. Permanent damage may occur on devices subjected to high-energy discharges. Proper ESD precautions are recommended to avoid performance degradation or loss of functionality. Store unused boards in the protective shipping package.



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1 Preface

Thank you for purchasing the Analog Devices, Inc. EV-SOMCRR-EZKIT carrier evaluation board.

The *EV-SOMCRR-EZKIT* carrier board is a backplane plug-in card designed for use with System on Module (SoM) evaluation boards. Together, these boards create a full evaluation system to demonstrate Analog Devices embedded processor feature sets. The SoM module features the processor, required power, and external memory circuitry; and the carrier board provides all the peripheral functionality necessary to evaluate an embedded application.

The *EV-SOMCRR-EZKIT* carrier board is compatible with numerous SoM boards and works with the Analog Devices development tools to test the capabilities of Analog Devices processors.

The evaluation board is designed to be used in conjunction with the CrossCore Embedded Studio[®] development environment for advanced application code development and debug, with features that enable the ability to:

- Create, compile, assemble, and link application programs written in C++, C, and assembly
- · Load, run, step, halt, and set breakpoints in application programs
- Read and write data and program memory
- Read and write core and peripheral registers

In addition to the system peripherals, there is an on-board debugger on the *EV-SOMCRR-EZKIT* carrier board. The on-board debugger eliminates the need to purchase the In-Circuit Emulator (ICE) that is necessary when using a SoM module in standalone mode.

Purpose of This Manual

This manual provides instructions for installing the product hardware (board). This manual describes operation and configuration of the board components and provides guidelines for running code on the board.

Manual Contents

The manual consists of:

• Using the board

Provides basic board information.

• Hardware Reference

Provides information about the hardware aspects of the board.

• Bill of Materials

A companion file in PDF format that lists all of the components used on the board is available on the website at http://www.analog.com/EV-SOMCRR-EZKIT.

• Schematic

A companion file in PDF format documenting all of the circuits used on the board is available on the website at http://www.analog.com/EV-SOMCRR-EZKIT.

Technical Support

You can reach Analog Devices technical support in one of the following ways:

• Post your questions in the processors and DSP support community at EngineerZone[®]:

http://ez.analog.com/community/dsp

• Submit your questions to technical support directly at:

http://www.analog.com/support

 E-mail your questions about processors, DSPs, and tools development software from *CrossCore Embedded Stu*dio or *VisualDSP*++[®]:

If using CrossCore Embedded Studio or VisualDSP++ choose *Help > Email Support*. This creates an e-mail to processor.tools.support@analog.com and automatically attaches your CrossCore Embedded Studio or VisualDSP++ version information and license.dat file.

• E-mail your questions about processors and processor applications to:

processor.support@analog.com

processor.china@analog.com

• Contact your Analog Devices sales office or authorized distributor. Locate one at:

http://www.analog.com/adi-sales

Supported Tools

Information about code development tools for the *EV-SOMCRR-EZKIT* evaluation board and SHARC product family is available at:

http://www.analog.com/EV-SOMCRR-EZKIT

Product Information

Product information can be obtained from the Analog Devices website and the online help system.

Analog Devices Website

The Analog Devices website, http://www.analog.com, provides information about a broad range of products - analog integrated circuits, amplifiers, converters, transceivers, and digital signal processors.

To access a complete technical library for each processor family, go to http://www.analog.com/processors/technical_library. The manuals selection opens a list of current manuals related to the product as well as a link to the previous revisions of the manuals. When locating your manual title, note a possible errata check mark next to the title that leads to the current correction report against the manual.

Also note, MyAnalog.com is a free feature of the Analog Devices website that allows customization of a web page to display only the latest information about products you are interested in. You can choose to receive weekly e-mail notifications containing updates to the web pages that meet your interests, including documentation errata against all manuals. MyAnalog.com provides access to books, application notes, data sheets, code examples, and more.

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Use EngineerZone to connect with other DSP developers who face similar design challenges. You can also use this open forum to share knowledge and collaborate with the ADI support team and your peers. Visit http://ez.analog.com to sign up.

2 Using the Board

This chapter provides information on the major components and peripherals on the board, along with instructions for installing and setting up the emulation software.

Product Overview

Below is an image of the EV-SOMCRR-EZKIT carrier board connected to a SoM board.

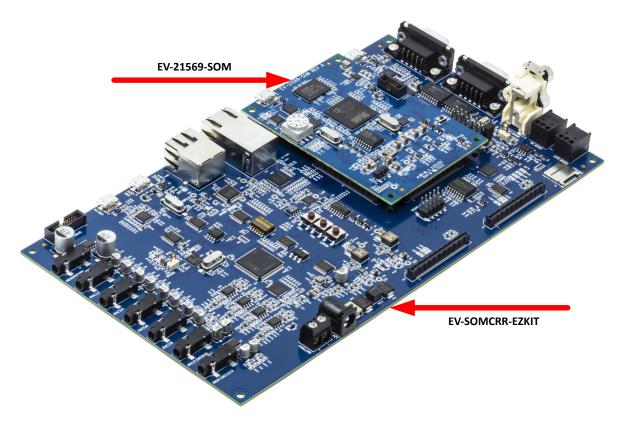


Figure 2-1: Board View

The board features:

• System-on-Module (SoM) connector

- Compatible with Analog Devices DSP SoMs
- Octal SPI flash (SPI2) memory
 - 1Gbit
 - Macronix MX66LM1G45G 1G-bit Serial Flash Memory with Single and Octal SPI
 - Single/Octal SPI
- SPI EEPROM
 - Microchip 25LC010AT 1K SPI Serial EEPROM
- Audio
 - Analog Devices ADAU1962A 12 Channel, High Performance, 192kHz, 24-Bit DAC
 - Analog Devices ADAU1979 Quad Analog-to-Digital Converter
 - 7 3.5mm Stereo connectors: 12 outputs or 8 outputs/4 inputs and stereo headphone output
- A²B
 - Two A²B interface connectors for the A²B mini modules
- Gigabit ethernet
 - TI DP83867 10/100/1000 Gigabit Ethernet
- Debug Interface (JTAG)
 - On-Board debug agent
- LEDs
 - 12 LEDs: one power (green), one board reset (red), three general-purpose (amber), six A²B LEDs, and one RGB LED for on-board debug agent
- Pushbuttons
 - Three pushbuttons: one reset and two IRQ/Flag
- External power supply
 - CE compliant
 - 12V @1.6 Amps

Package Contents

Your EV-SOMCRR-EZKIT package contains the following items.

• EV-SOMCRR-EZKIT board

- Universal 12V DC power supply
- Two USB 2.0 type A to micro-B cable

Contact the vendor where you purchased your *EV-SOMCRR-EZKIT* evaluation board or contact Analog Devices, Inc. if any item is missing.

Default Configuration

The *Default Hardware Setup* figure shows the default settings for jumpers and switches and the location of the jumpers, switches, connectors, and LEDs. Confirm that your board is in the default configuration before using the board.

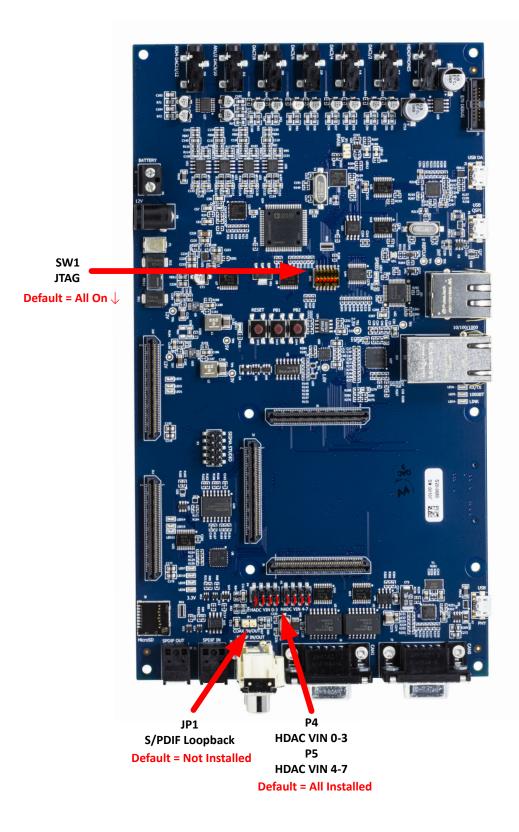


Figure 2-2: Default Hardware Setup

CrossCore Embedded Studio (CCES) Setup

Information on using the CCES tools is available at: https://analog.com/cces-quickstart

Debug Agent

The *EV-SOMCRR-EZKIT* provides a JTAG connection via an onboard Debug Agent. The Debug Agent uses a microUSB connection to the PC and allows debugging of processor SoM modules without the need of an external ICE.

To use this Debug Agent, all postions on SW1 must be in the ON position. If an emulator, such as the ICE-2000, all postions on SW1 must be in the OFF position.

Power-On-Self Test

The Power-On-Self-Test Program (POST) tests all the EZ-KIT carrier board peripherals and validates functionality as well as connectivity to the processor. Once assembled, each EZ-KIT carrier board is fully tested for an extended period of time with POST for all the compatible SoM modules. All EZ-KIT carrier boards are shipped with POST preloaded into flash memory. The POST is executed by resetting the board and connecting the USB To UART to your PC with an open terminal window. The POST also can be used as a reference for a custom software design or hardware troubleshooting.

Note that the source code for the POST program is included in the Board Support Package (BSP) along with the readme file that describes how the board is configured to run POST.

Reference Design Information

A reference design info package is available for download on the Analog Devices Web site. The package provides information on the schematic design, layout, fabrication, and assembly of the board.

The information can be found at:

http://www.analog.com/EV-SOMCRR-EZKIT

Automotive Audio Bus A²B Interface

The Automotive Audio Bus (A²B[®]) provides a multichannel, I²S/TDM link over distances of up to 15 m between nodes. It embeds bidirectional synchronous pulse-code modulation (PCM) data (for example, digital audio), clock, and synchronization signals onto a single differential wire pair. A²B supports a direct point to point connection and allows multiple, daisy-chained nodes at different locations to contribute and/or consume time division multiplexed channel content.

The A²B Interface connects processor evaluation boards, such as the EV-SOMCRR-EZKIT to A²B daugher cards, such as the ADZS-AD2428MINI board. This allows for an expandable and configurable evaluation system for ADI DSPs and A²B technologies.

25LC010AT - 1K SPI Serial EEPROM

The Microchip Technology Inc. 25LC010AT is a 1 Kbit Serial Electrically Erasable Programmable Read-Only Memory (EEPROM). The memory is accessed via a simple Serial Peripheral Interface (SPI) compatible serial bus. The bus signals required are a clock input (SCK) plus separate data in (SI) and data out (SO) lines. Access to the device is controlled through a Chip Select (CS) input.

ADAU1962A - 12 Channel, High Performance, 192kHz, 24-Bit DAC

The ADAU1962A is a high performance, single-chip digital-to-analog converter (DAC) that provides 12 DACs with differential or single-ended output using the patented Analog Devices, Inc., sigma-delta (Σ - Δ) architecture. A SPI/I²C port is included, allowing a micro-controller to adjust volume and many other parameters. The ADAU1962A operates from 2.5 V digital and 3.3 V analog supplies. A linear regulator is included to generate the digital supply voltage from the analog supply voltage.

The ADAU1962A is designed for low EMI. This consideration is apparent in both the system and circuit design architectures. By using the on-board PLL to derive the internal master clock from an external LRCLK, the ADAU1962A can eliminate the need for a separate high frequency master clock and can be used with or without a bit clock. The DACs are designed using the latest Analog Devices continuous time architectures to further minimize EMI.

ADAU1979 - Quad Analog-to-Digital Converter

The ADAU1979 incorporates four high performance, analog-to-digital converters (ADCs) with 4.5 V rms capable ac-coupled inputs. The ADCs use a multibit sigma-delta (Σ - Δ) architecture with continuous time front end for low EMI. An I²C/SPI control port is included that allows a microcontroller to adjust volume and many other parameters. The ADAU1979 uses only a single 3.3 V supply. The device internally generates the required digital DVDD supply. The low power architecture reduces the power consumption. The on-chip PLL can derive the master clock from an external clock input or frame clock (sample rate clock). When fed with the frame clock, it eliminates the need for a separate high frequency master clock in the system.

ADM3056E - Signal and Power Isolated CAN Transceiver

The ADM3056E is a 5.7 kV rms isolated controller area network (CAN) physical layer transceiver. The ADM3056E fully meets the CAN-FD ISO 11898-2: 2016 requirements and is further capable of supporting data rates as high as 12 Mbps.

The device employs Analog Devices, Inc., iCoupler® technology to combine a highly robust 3-channel isolator and a CAN transceiver into a single SOIC, surface-mount package. The ADM3056E provides galvanic isolation between the CAN controller and physical layer bus.

Safety and regulatory approvals (pending) for 5.7 kV rms isolation withstand voltage, 849 VPEAK working insulation voltage, 8 kV surge, and 8.3 mm creepage and clearance, ensure that the ADM3056E meets isolation requirements for high voltage applications.

Low propagation delays through the isolation support longer bus cables. Slope control mode is available for standard CAN at low data rates. Standby mode can minimize power consumption when the bus is idle, or if the node goes offline. Silent mode allows the TXD input to be ignored for listen only functionality.

Dominant timeout functionality protects against bus lock-up in a fault condition, and current limiting and thermal shutdown features protect against output short circuits. The device is fully specified over the -40°C to +125°C industrial temperature range and is available in a 16-lead, increased creepage, wide-body SOIC package.

ADM6315 - Open-Drain Microprocessor Supervisory Circuit

The ADM6315 is a reliable voltage-monitoring device that is suitable for use in most voltage-monitoring applications.

The ADM6315 is designed to monitor as little as a 1.8% degradation of a power supply voltage. The ADM6315 can monitor all voltages (at 100 mV increments) from 2.5 V to 5 V.

Included in this circuit is a debounced manual reset input. RESET can be activated using an ordinary switch (pulling MR low), a low input from another digital device, or a degradation of the supply voltage.

The manual reset function is very useful, especially if the circuit in which the ADM6315 is operating enters into a state that can be detected only by the user. Allowing the user to reset a system manually can reduce the damage or danger that could otherwise be caused by an out-of-control or locked-up system.

CS2100 - Fractional-N Clock Multiplier

The CS2100-CP is an extremely versatile system clocking device that utilizes a programmable phase lock loop. The CS2100-CP is based on a hybrid analog- digital PLL architecture comprised of a unique combination of a Delta-Sigma Fractional-N Frequency Synthesizer and a Digital PLL. This architecture allows for generation of a low-jitter clock relative to an external noisy synchronization clock at frequencies as low as 50 Hz. The CS2100-CP supports both I²C and SPI for full software control.

DP83848C - 10/100 Ethernet Physical Layer

The DP83848C is a robust fully featured 10/100 single port Physical Layer device offering low power consumption, including several intelligent power down states. These low power modes increase overall product reliability due to decreased power dissipation. Supporting multiple intelligent power modes allows the application to use the absolute minimum amount of power needed for operation.

The DP83848C includes a 25MHz clock out. This means that the application can be designed with a minimum of external parts, which in turn results in the lowest possible total cost of the solution.

The DP83848C easily interfaces to twisted pair media via an external transformer. Both MII and RMII are supported ensuring ease and flexibility of design.

The DP83848C features integrated sublayers to support both 10BASE-T and 100BASE-TX Ethernet protocols, which ensures compatibility and interoperability with all other standards based Ethernet solutions.

DP83867 - 10/100/1000 Ethernet Physical Layer

The DP83867 device is a robust, low power, fully featured Physical Layer transceiver with integrated PMD sublayers to support 10BASE-Te, 100BASE-TX and 1000BASE-T Ethernet protocols. Optimized for ESD protection, the DP83867 exceeds 8-kV IEC 61000-4-2 (direct contact).

The DP83867 is designed for easy implementation of 10/100/1000 Mbps Ethernet LANs. It interfaces directly to twisted pair media via an external transformer. This device interfaces directly to the MAC layer through the IEEE 802.3 Standard Media Independent Interface (MII), the IEEE 802.3 Gigabit Media Independent Interface (GMII) or Reduced GMII (RGMII). The QFP package supports MII/GMII/RGMII whereas the QFN package supports RGMII.

The DP83867 provides precision clock synchronization, including a synchronous Ethernet clock output. It has low latency and provides IEEE 1588 Start of Frame Detection.

MX66LM1G45G - 1G-bit Serial Flash Memory with Single and Octal SPI

MX66LM1G45G is 1Gbit Serial NOR Flash memory, which is configured as 134,217,728 x 8 internally. MX66LM1G45G feature a serial peripheral interface and software protocol allowing operation on a simple 3-wire bus while it is in single I/O mode. The three bus signals are a clock input (SCLK), a serial data input (SI), and a serial data output (SO). Serial access to the device is enabled by a chip-select (CS#) input.

The MX66LM1G45G MXSMIO® (Serial Multi I/O) provides sequential read operation on the whole chip.

3 Hardware Reference

This chapter describes the hardware design of the EV-SOMCRR-EZKIT carrier board.

System Architecture

The board's configuration is shown in the Block Diagram figure.

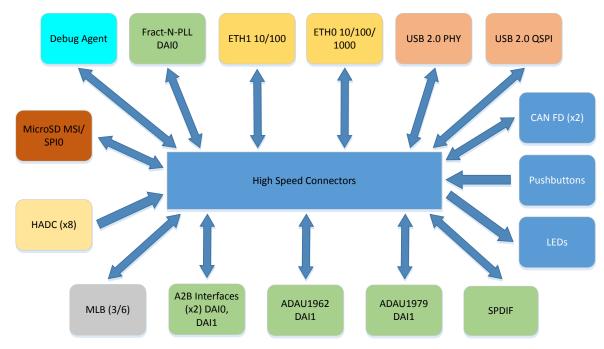


Figure 3-1: Block Diagram

This Carrier board is designed to demonstrate the connected System on Module processor's capabilities. The peripherals help evaluate the processor's features with audio DAC and ADCs, S/PDIF, 10/100/1000 ethernet, CAN, MLB and A²B expansion.

User I/O to the processor is provided in the form of two pushbuttons and three LEDs.

The software-controlled switches (SoftConfig) facilitate the switch multi-functionality by disconnecting the pushbuttons from their associated processor pins and reusing the pins elsewhere on the board.

Software-Controlled Switches (SoftConfig)

On the board, most of the functionality traditionally controlled by mechanical switches and jumpers is controlled by I²C software-controlled switches. The mechanical switches the remain are provided for the boot mode and push buttons. Reference any SoftConfig*.c file found in the installation directory for an example of how to set up the SoftConfig feature of the board through software. The SoftConfig section of this manual serves as a reference to any user that intends to modify an existing software example. If software provided by ADI is used, there should be little need to reference this section.

NOTE: Be careful when changing SoftConfig settings. When connecting extender cards, configure the settings to avoid conflict among interfaces so multiple signals are not driven on the same pins.

Overview of SoftConfig

In order to further clarify the use of electronic single FET switches and multi-channel bus switches, an example of each is illustrated and compared to a traditional mechanical switching solution. This is a generic example that uses similar FET and bus switch components that are on the board.

After this generic discussion, there is a detailed explanation of the SoftConfig interface specific to the *EV-SOMCRR-EZKIT* carrier board.

The *Example of Individual FET Switches* figure shows two individual FET switches (Pericom PI3A125CEX) with reference designators UA and UB. Net names ENABLE_A and ENABLE_B control UA and UB. The default FET switch enable settings in this example are controlled by resistors RA and RB, which pull the enable pin 1 of UA and UB to ground (low), respectively. In a real example, these enable signals are controlled by the Microchip I/O expander. The default pull-down resistors connects the signals EXAMPLE_SIGNAL_A and EXAMPLE_SIGNAL_B and also connects signals EXAMPLE_SIGNAL_C and EXAMPLE_SIGNAL_D. To disconnect EXAMPLE_SIGNAL_A from EXAMPLE_SIGNAL_B, the Microchip I/O expander is used to change ENABLE_A to a logic 1 through software that interfaces with the Microchip I/O expander. The same procedure for ENABLE_B disconnects EXAMPLE_SIGNAL_C.

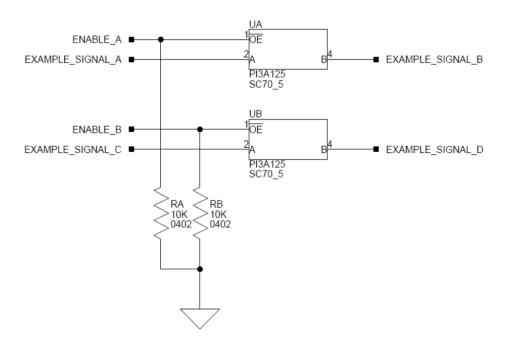


Figure 3-2: Example of Individual FET Switches

The following figure shows the equivalent circuit to the *Example of Individual FET Switches* figure but utilizes mechanical switches that are in the same package. Notice the default is shown by black boxes located closer to the *ON* label of the switches. In order to disconnect these switches, physically move the switch to the OFF position.

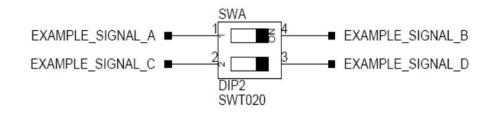


Figure 3-3: Example of a Mechanical Switch (Equivalent to Example of Individual FET Switches Figure)

The *Example of Bus Switch* figure shows a bus switch example, reference designator UC (Pericom PI3LVD512ZHE), selecting between lettered functionality and numbered functionality. The signals on the left side are multiplexed signals with naming convention letter_number. The right side of the circuit shows the signals separated into letter and number, with the number on the lower group (0B1) and the letter on the upper group (0B2). The default setting is controlled by the signal CONTROL_LETTER_NUMBER which is pulled low. This selects the number signals on the right to be connected to the multiplexed signals on the left by default. In this example, the Microchip IO expander is not shown but controls the signal CONTROL_LETTER_NUMBER and allows the user to change the selection through software.

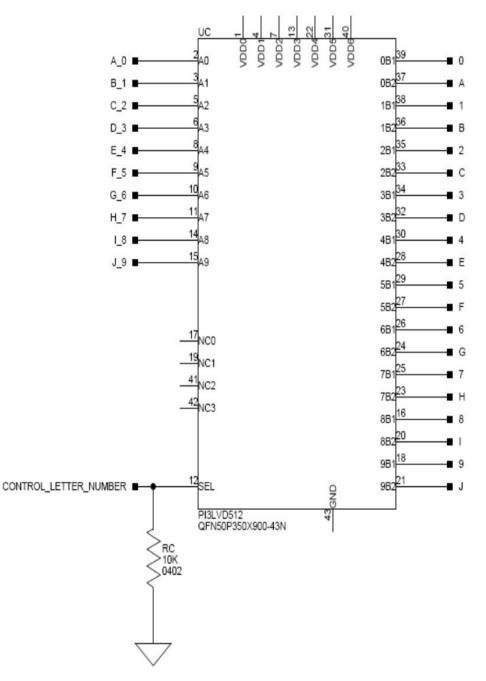


Figure 3-4: Example of a Bus Switch

The following figure shows the equivalent circuit to the *Example of Bus Switch* figure but utilizes mechanical switches. Notice the default for reference designators SWC and SWD is illustrated by black boxes located closer to the *ON* label of the switches to enable the number signals by default. Also notice the default setting for reference designators SWE and SWF is OFF. In order to connect the letters instead of the numbers, the user physically changes all switches on SWC and SWD to the OFF position and all switches on SWE and SEF to the ON position.

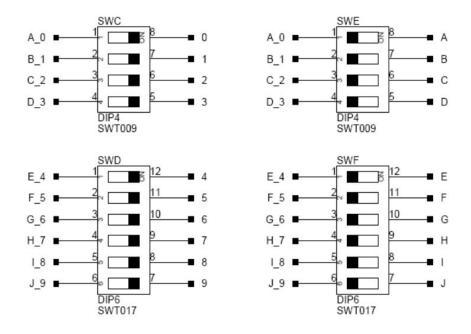


Figure 3-5: Example of a Mechanical Switch (Equivalent to Example of Bus Switch)

SoftConfig on the Board

Two Microchip MCP23017 GPIO expanders provide control for individual electronic switches. The TWI2 interface of the processor communicates with the Microchip devices. There are individual switches with default settings that enable basic board functionality.

The *Default Processor Interface Availability* table lists the processor and board interfaces that are available by default. Note that only interfaces affected by software switches are listed in the table.

Table 3-1: Default Processor Interface Availability

Interface	Availability by Default	
Audio Connectors	4 inputs/8 outputs	
S/PDIF Digital	S/PDIF RCA input and output connectors enabled	
Pushbuttons	Enabled	
LEDs	Enabled	

Programming SoftConfig Switches

On the board, two Microchip MCP23017 devices exist. Each of these devices has the following programming characteristics:

• Each GPIO register controls eight signals (software switches).

GPIO Register	Register Address
GPIOA	0x12
GPIOB	0x13

• By default, the Microchip MCP23017 GPIO signals function as input signals.

The signals must be programmed as output signals to override their default values. A zero is programmed into the register to enable the signal as an output. The following table shows the Microchip GPIO expander register addresses.

IODIR Register	IODIR Register Address
IODIRA	0x00
IODIRB	0x01

Each example in the Board Support Package (BSP) includes source files that program the soft switches, even if the default settings are being used. The README for each example identifies only the signals that are being changed from their default values. The code that programs the soft switches is located in the SoftConfig_XXX.c file in each example ,where XXX is the name of the baord.

The following table I^2C Hardware Address (0x22) outline the default values for the Microchip MCP23017 device.

 Table 3-2: I²C Hardware Address (0x22)

GPIO	MCP23017 Register Address	Default Value
GPIOA	0x12	0x00
GPIOB	0x13	0x00

The board schematic shows how the two Microchip GPIO expanders are connected to the board's ICs.

Tables *Output Signals of Microchip GPIO Expander (U6 Port A)* and *Signals of Microchip GPIO Expander (U6 Port B)* show the output signals of the Microchip GPIO expander (*U6*), with a TWI address of 0100 010X, where X represents the read or write bit. The signals that control an individual FET have an entry in the *FET* column. The *Component Connected* column shows the board IC that is connected if the FET is enabled. However, in most cases, the Microchip GPIO exapnder (U6) is controlling the enable signal of a FET switch. Also note that if a particular functionality of the processor signal is being used, it is in *bold* font in the *Processor Signal* column.

Bit	Signal Name	Description	FET	Processor Signal	Connected	Default
				(if applicable)		
0	EEPROM_EN	SPI0_SS for EEPROM chip se- lect	U26	SPI0_SS	U21	High
1	PUSHBUT- TON_EN	Enable Push buttons	U19,U20	PUSHBUTTON_1,PUSHBUT- TON_2	PB1, PB2	High

Table 3-3: Output Signals of Microchip GPIO Expander (U6 Port A)

Bit	Signal Name	Description	FET	Processor Signal (if applicable)	Connected	Default
2	MicroSD_SPI	SPI0 Signals to MicroSD socket	U35	SPI0_MISO, SPI0_MOSI, SPI0_SSb, SPI0_CLK	J9	High
3	FTDI_USB_EN	FT4222H USB Enable	U36	OSPI_CLK, OSPI_MISO, OSPI_MOSI, OSPI_D2, OSPI_D3, SPI2_SSb, TWI2_SCL, TWI2_SDA	U39	High
4	CAN_EN	CAN0/1 Enable	U15, U16	CAN0_RX, CAN0_SILENT, CAN0_STDBY, CAN1_RX, CAN1_SILENT, CAN1_STDBY	U1, U3	High
5	ADAU_RESET	Reset all audio devices on board	N/A	N/A	U34, U38	High
6	ADAU1962_EN	Enable ADAU1962	U8	ADAU_RESET, ADAU1962A_CLKIN, DAI1_PIN05, DAI1_PIN04, DAI1_PIN01, DAI1_PIN02, DAI1_PIN10	U34	High
7	ADAU1979_EN	Enable ADAU1979	U7	ADAU_RESET, DAI1_PIN20, DAI1_PIN12, DAI1_PIN06, DAI1_PIN07	U38	High

Table 3-3: Output Signals of Microchip GPIO Expander (U6 Port A) (Continued)

Table 3-4: Output Signals of Microchip GPIO Expander (U6 Port B)

Bit	Signal Name	Description	FET	Processor Signal	Connected	Default
				(if applicable)		
0	OC- TAL_SPI_CS_E N	Enable Chip Select to OSPI flash device	U17	SPI2_SS	U40	Low
1	SPDIF_DIGI- TAL_EN	Enable Digital SPDIF connector	U13	DAI0_PIN09	J14	High
2	SPDIF_OPTI- CAL_EN	Enable Optical SPDIF connector	U14	DAI0_PIN09	J2	High
3	AU- DIO_JACK_SEL	Set J4 to Input or Output	U37		J4	High
4	MLB_EN	Configure MLB for MLB3 or MLB6	J15		J15	High

Bit	Signal Name	Description	FET	Processor Signal	Connected	Default
				(if applicable)		
5	ETH1_EN	Enable signals for ETH1	U41, U42, U44	ETH1_MDIO, ETH1_MDC, ETH1_CRS, ETH1_RXD0, ETH1_RXD1, ETH1_TXD0, ETH1_TXD1, ETH1_TXEN, ETH1_CLKIN, ETH1_INTb	U52	Low
6	ETH1_RESET	Reset signal for ETH1	N/A	N/A	U52	N/A
7	GIGE_RESET	Reset signal for Gigabit Ethernet	N/A	N/A	U27	High

Table 3-4: Output Signals of Microchip GPIO Expander (U6 Port B) (Continued)

Switches

This section describes operation of the switches. The switch locations are shown in the *Switch/Jumper Locations* figure.

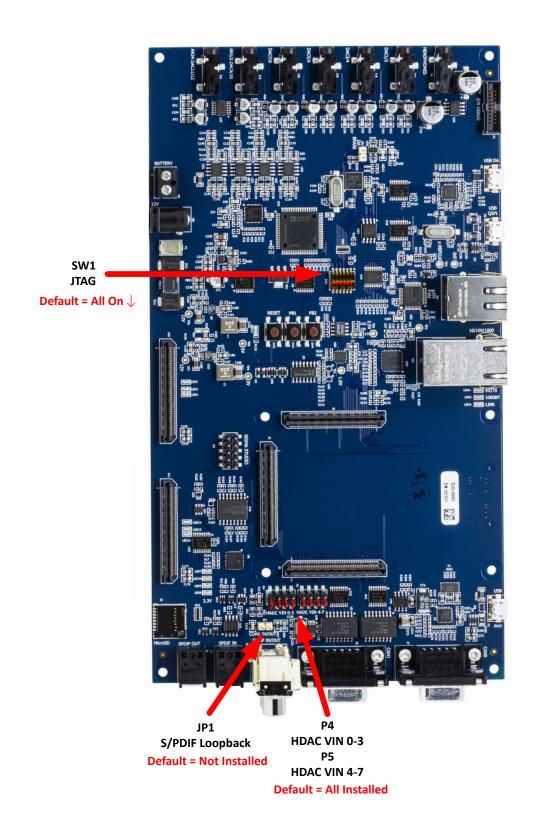


Figure 3-6: Switch/Jumper Locations

Reset Pushbutton (Sw2)

The reset pushbutton resets the ADI processor. The reset signal also is connected to the SoM interface connectors via the SYS HWRST signal. Reset (LED11) is used to indicate when the board is in reset.

GPIO Pushbuttons (SW4 and SW3)

The GPIO pushbuttons are connected to the processor's signals GPIO1 and GPIO2, respectively.

The GPIO pushbuttons can be disconnected from the processor by setting SoftConfig. See Software-Controlled Switches (SoftConfig) for more information.

JTAG Interface (Sw1)

The JTAG Interface switch enables/disables the on-board debug agent. When in the disabled configuration, an ICE can be attached to the JTAG header on the SoM module to provide on-chip debug capabilities.

Location	Position
SW1.1	ON
SW1.2	ON
SW1.3	ON
SW1.4	ON
SW1.5	ON
SW1.6	ON

 Table 3-5: Debug Agent Enable

Table 3-6: Debug Agent Disable

Location	Position
SW1.1	OFF
SW1.2	OFF
SW1.3	OFF
SW1.4	OFF
SW1.5	OFF
SW1.6	OFF

Jumpers

This section describes the functionality of the configuration jumpers. The *Switch/Jumper Locations* figure shows the jumper locations.

S/PDIF Loopback (JP1)

The S/PDIF loopback jumper is used to connect the S/PDIF input and output signals together and bypass the two RCA connectors.

HADC (P4 and P5)

The HADC jumper is used to connect the HADC of the processor to various voltages on the board for monitoring.

P4 Jumper	Voltage
1 and 2	VDD_INT
3 and 4	VDD_A
5 and 6	VDD_DMC
7 and 8	1.0V

P5 Jumper	Voltage
1 and 2	VDD_REF
3 and 4	VDD_INT
5 and 6	GND
7 and 8	GND

LEDs

This section describes the on-board LEDs. The *LED Locations* figure shows the LED locations.

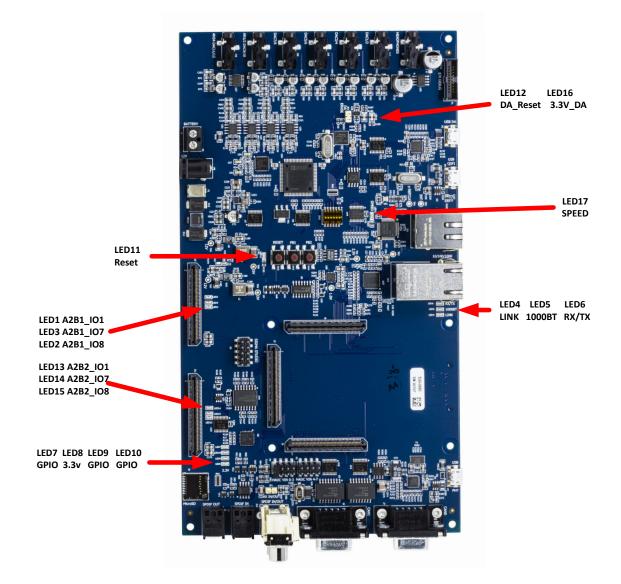


Figure 3-7: LED Locations

LEDs

A²B Interface LEDs (LED1, LED2, LED3, LED13, LED14, LED15)

The A²B Interface LEDs are driven by the connected A2B daughter card on the A2B Interface Connectors. These are connected to A2B IRQ and GPIO signals. Refere to the schematics of the connected A2B or related daughter card for more information.

Power (LED8)

When ON (green), it indicates that power is being supplied to the board properly.

GPIO (LED7, LED9, LED10)

Three LEDs are connected to the general-purpose I/O pins of the processor (see the *GPIO LEDs* table). The LEDs are active high and are turned ON (amber) by writing a 1 to the correct processor signal.

Table 3-7: GPIO LEDs

Reference Designator	Programmable Flag Pin
LED7	LED3_KIT
LED9	LED1_KIT
LED10	LED2_KIT

Reset (LED11)

When ON (red), it indicates that the board is in reset. A master reset is asserted by pressing SW2, which activates the LED. For more information, see Reset Pushbutton (SW2).

Connectors

This section describes connector functionality and provides information about mating connectors. The connector locations are shown in the *Connector Top* and *Connector Bottom* figures.

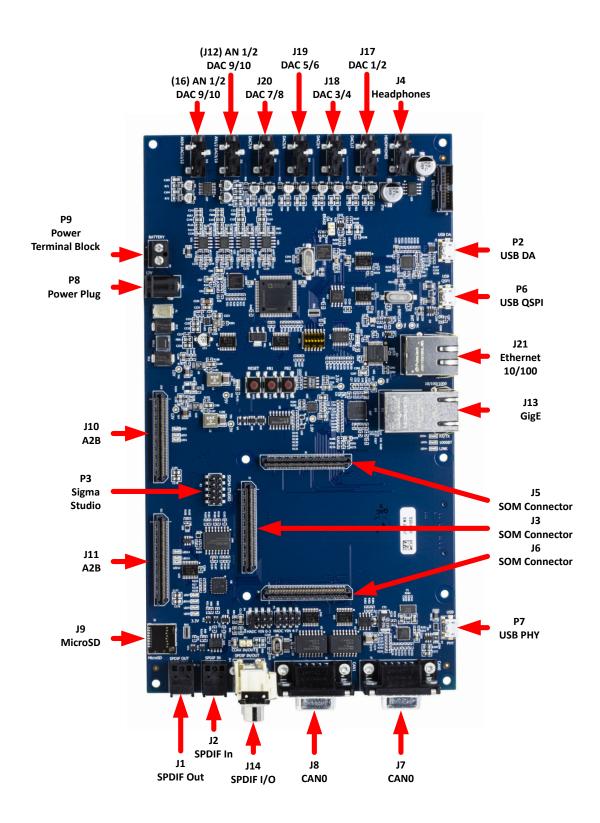


Figure 3-8: Connector Top

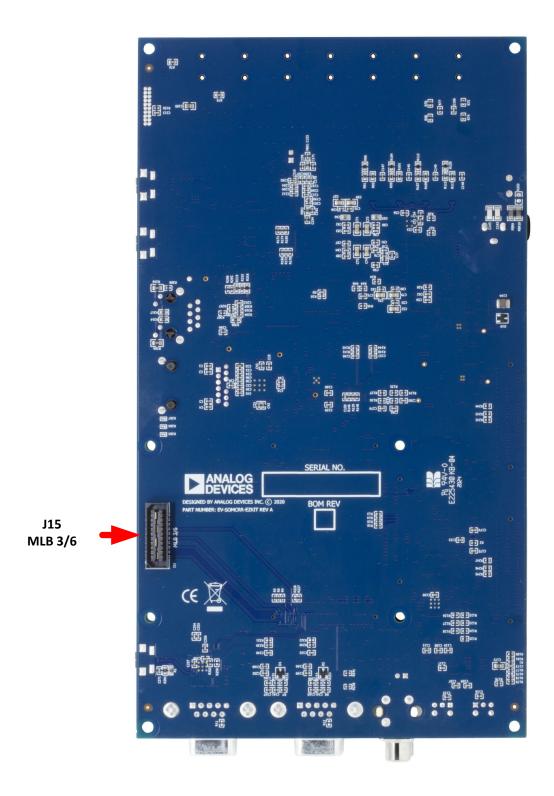


Figure 3-9: Connector Bottom

S/PDIF Optical Tx (J1)

Part Description	Manufacturer	Part Number
Fiber optic transmitter	Everlight	PLT133/T10W
Mating Cable		
Standard TOSLINK optical digital cable		

Audio Input/Output (J12)

Part Description	Manufacturer	Part Number
3.5mm Stereo female	CUI	SJ-3523-SMT
Mating Cable		
Standard 3.5mm stereo cable		

S/PDIF Optical Rx (J2)

Part Description	Manufacturer	Part Number
Fiber optic receiver	Everlight	PLR135/T10
Mating Cable		
Standard TOSLINK optical digital cable		

Audio Output (J4)

Part Description	Manufacturer	Part Number
3.5mm Stereo female	CUI	SJ-3523-SMT
Mating Cable		
Standard 3.5mm stereo cable		

S/PDIF Digital (J11)

Part Description	Manufacturer	Part Number
RCA 1x2 female	Switchcraft	PJRAS1X2S02X
Mating Cable		
Standard S/PDIF cable with RCA connectors		

MLB (J15)

Part Description	Manufacturer	Part Number
40-pin high speed socket	Samtec	QSH-020-01-L-D-DP-A
Mating Connector		
40-pin high speed header	Samtec	QTH-0202-01-L-D-DP-A

Headphone (J16)

Part Description	Manufacturer	Part Number
3.5mm headphone connector	CUI	SJ1-3525NG
Mating Cable		
Standard audio cable with 3.5mm connector		

Sigma Studio (P3)

This connector interfaces with SigmaStudio[®] through the EVAL-ADUSB2EBZ board. The connector is a 0.1" header. The pinout can be found in the schematic.

$A^2B\,($ J10 and J11)

Part Description	Manufacturer	Part Number
100-pin, 0.64mm	SAMTEC	LSS-150-01-L-DV-A-K
Mating Connector		
100-pin, 0.64mm	SAMTEC	LSS-150-01-L-DV-A-K

Ethernet 100 (J21)

Part Description	Manufacturer	Part Number							
RJ45	Pulse Engineering	J0011D21BNL							
	Mating Cable								
Standard CAT5e Ethernet cable									

Ethernet 1000 (J13)

Part Description	Manufacturer	Part Number						
RJ45	Assmann	A-2004-2-4-LPS-N-R						
Mating Cable								

Part Description	Manufacturer	Part Number						
Standard CAT5e Ethernet cable								

Power Plug (P8)

Part Description	Manufacturer	Part Number						
2.1 mm power jack	CUI	PJ-102AH						
Mating Cable								
12.0VDC@1.5A power supply	CUI	EMSA120150-P5RP-SZ						

Power Terminal Block (P9)

Part Description	Manufacturer	Part Number
5.08mm power jack	Weidmuller	1760510000
	Mating Cable	
12.0VDC discrete wires		

SoM Interface Connection (J3, J5, J6**)**

The SoM Interface consists of three SAMTEC high speed connectors that provide the DSP peripheral signals for use with a plug in SoM module. These signals are based upon the peripheral signal needs, which allows multiple processors to be used with this connection. These connectors are self-mating, and the pinout here reflects the connectors of the associated SoM board.

The SoM Interface A Connector (J5), SoM Interface B Connector (J3), and SoM Interface C Connector (J6) tables show the signal associated with each pin on the connectors.

Pin	Signal	Pin	Signal	Pin	Signal	Pin	Signal	Pin	Signal
1	GND1	21	DAI0_PIN10	41	DAI0_PIN20	61	USB0_ID	81	GPIO3
2	GND2	22	DAI1_PIN10	42	DAI1_PIN20	62	USB_D2	82	USB_RESET
3	DAI0_PIN01	23	DAI0_PIN11	43	GND3	63	USB0_VBUS	83	GPIO4
4	DAI1_PIN01	24	DAI1_PIN11	44	GND4	64	USB_D3	84	GPIO6
5	DAI0_PIN02	25	DAI0_PIN12	45	GND5	65	USB0_VBC	85	GPIO5
6	DAI1_PIN02	26	DAI1_PIN12	46	GND6	66	USB_D4	86	GPIO7
7	DAI0_PIN03	27	DAI0_PIN13	47	HADC_VIN0	67	USB1_DP	87	GND9
8	DAI1_PIN03	28	DAI0_PIN13	48	HADC_VIN4	68	USB_D5	88	GPIO8

Table 3-8: SoM Interface A Connector (J5)

Pin	Signal	Pin	Signal	Pin	Signal	Pin	Signal	Pin	Signal
9	DAI0_PIN04	29	DAI0_PIN14	49	HADC_VIN1	69	USB1_DM	89	MLB_CLKP
10	DAI1_PIN04	30	DAI1_PIN14	50	HADC_VIN5	70	USB_D6	90	GPIO9
11	DAI0_PIN05	31	DAI0_PIN15	51	HADC_VIN2	71	USB1_ID	91	MLB_CLKN
12	DAI1_PIN05	32	DAI1_PIN15	52	HADC_VIN6	72	USB_D7	92	GPIO10
13	DAI0_PIN06	33	DAI0_PIN16	53	HADC_VIN3	73	USB1_VBUS	93	MLB_SIGP
14	DAI1_PIN06	34	DAI1_PIN16	54	HADC_VIN7	74	USB_NXT	94	GND10
15	DAI0_PIN07	35	DAI0_PIN17	55	GND7	75	USB1_VBC	95	MLB_SIGN
16	DAI1_PIN07	36	DAI1_PIN17	56	GND8	76	USB_STP	96	MLB_CLK
17	DAI0_PIN08	37	DAI0_PIN18	57	USB0_DP	77	GPIO1	97	MLB_DATP
18	DAI1_PIN08	38	DAI1_PIN18	58	USB_D0	78	USB_DIR	98	MLB_SIG
19	DAI0_PIN09	39	DAI0_PIN19	59	USB0_DM	79	GPIO2	99	MLB_DATN
20	DAI1_PIN09	40	DAI1_PIN19	60	USB_D1	80	USB_CLK	100	MLB_DAT

Table 3-8: SoM Interface A Connector (J5) (Continued)

Table 3-9: SoM Interface B Connector (J3)

Pin	Signal	Pin	Signal	Pin	Signal	Pin	Signal	Pin	Signal
1	GND1	21	OSPI_D7	41	TWI2_SDA	61	MSI_D3	81	LINKPORT0_D7
2	GND2	22	SPI1_SEL2b	42	UART2_RXb	62	GND8	82	LINKPORT1_D7
3	SP2_OSPI_MISO	23	SPI2_SEL2b	43	UART0_TXb	63	MSI_D4	83	LINKPORT0_D6
4	SPI0_CLK	24	GND3	44	UART2_RTSb	64	CAN0_TX	84	LINKPORT1_D6
5	SP2_OSPI_MOSI	25	GND4	45	UART0_RXb	65	MSI_D5	85	LINKPORT0_D5
6	SPI0_MISO	26	NU	46	UART2_CTSb	66	CAN0_RX	86	LINKPORT1_D5
7	SPI2_OSPI_D2	27	NU	47	UART0_RTSb	67	MSI_D6	87	LINKPORT0_D4
8	SPI0_MOSI	28	NU	48	GND6	68	GND	88	LINKPORT1_D4
9	SP2_OSPI_D3	29	NU	49	UART0_CTSb	69	MSI_D7	89	LINKPORT0_D3
10	SPI0_SSb	30	NU	50	GPIO1	70	CAN1_TX	90	LINKPORT1_D3
11	SP2_OSPI_CLK	31	TWI0_SCL	51	GND5	71	GND7	91	LINKPORT0_D2
12	SPI0_SEL2b	32	UART1_TXb	52	GPIO2	72	CAN1_RX	92	LINKPORT1_D2
13	SP2_OSPI_SSb	33	TWI0_SDA	53	NU	73	NU	93	LINKPORT0_D1
14	SPI1_CLK	34	UART1_RXb	54	NU	74	NU	94	LINKPORT1_D1
15	OSPI_D4	35	TWI1_SCL	55	MSI_D0	75	NU	95	LINKPORT0_D0
16	SPI1_MISO	36	UART1_RTSb	56	MSI_CLK	76	NU	96	LINKPORT1_D0
17	OSPI_D5	37	TWI1_SDA	57	MSI_D1	77	NU	97	LINKPORT0_ACK

Pin	Signal	Pin	Signal	Pin	Signal	Pin	Signal	Pin	Signal
18	SPI1_MOSI	38	UART1_CTSb	58	MSI_CMD	78	NU	98	LINKPORT1_ACK
19	OSPI_D6	39	TWI2_SCL	59	MSI_D2	79	GND9	99	LINKPORT0_CLK
20	SPI1_SSb	40	UART2_TXb	60	MSI_CDb	80	GND10	100	LINKPORT1_CLK

Table 3-9: SoM Interface B Connector (J3) (Continued)

Table 3-10: SoM Interface C Connector (J6)

Pin	Signal	Pin	Signal	Pin	Signal	Pin	Signal	Pin	Signal
1	GND1	21	ETH0_ RXCLK_REFCLK	41	GND7	61	PPI_D05	81	PPI_D15
2	GND2	22	GND4	42	CLK1	62	PPI_D17	82	GPIO3
3	ETH0_MDIO	23	ETH0_RXCTL_C RS	43	PPI_CLK	63	PPI_D06	83	PPI_D16
4	ETH1_MDIO	24	ETH0_PTPCLKI N0	44	CLK2	64	PPI_D18	84	GPIO4
5	ETH0_MDC	25	GND3	45	PPI_FS1	65	PPI_D07	85	GND11
6	ETH1_MDC	26	ETH0_PTPAUX- IN0	46	GND8	66	PPI_D19	86	GPIO5
7	ETH0_MD_INT	27	ETH0_TXD3	47	PPI_FS2	67	PPI_D08	87	VDD_EXT
8	ETH0_RXD1	28	ETH0_PTPPPS0	48	JTG0_TMS/ SWDIO	68	PPI_D20	88	GPIO6
9	ETH0_GPIO_1	29	ETH0_TXD2	49	PPI_FS3	69	PPI_D09	89	VDD_VREF
10	ETH0_RXD0	30	ETH0_PTPPPS1	50	JTG0_TCK/ SWCLK	70	PPI_D21	90	GND12
11	ETH0_GPIO_2	31	ETH0_TXD1	51	PPI_D00	71	PPI_D10	91	VDD_A
12	ETH0_TXEN	32	ETH0_PTPPPS2	52	JTG0_TDO/SW0	72	PPI_D22	92	VDD_DMC
13	ETH0_RXD3	33	ETH0_TXD0	53	PPI_D01	73	PPI_D11	93	VDD_INT
14	ETH0_TXD0	34	ETH0_PTPPPS3	54	JTG0_TDI	74	PPI_D23	94	SYS_HWRST
15	ETH0_RXD2	35	ETH0_TCLK	55	PPI_D02	75	PPI_D12	95	PWR_SEQ_GOOD
16	ETH0_TXD1	36	GND5	56	JTG0_TRST	76	GND10	96	SoM_Reset
17	ETH0_RXD1	37	ETH0_TXEN	57	PPI_D03	77	PPI_D13	97	VDD1
18	ETH1_CRS	38	SYS_CLKOUT	58	TARGET_RESET	78	GPIO1	98	VSS1
19	ETH0_RXD0	39	GND6	59	PPI_D04	79	PPI_D14	99	VDD2
20	ETH1_INTb	40	AUDIO_CLK	60	GND9	80	GPIO2	100	VSS2

Table 3-11: Mating Connector

Part Description	Manufacturer	Part Number							
100-pin, 0.64 mm	SAMTEC	LSS-150-01-L-DV-A-K							
	Mating Connector								
100-pin, 0.64 mm	SAMTEC	LSS-150-01-L-DV-A-K							