

Surestep Stepper Systems

Complete SureStep system in 4 components: Power Supply, Stepper Drive, Motor Extension Cable, Motor. Standard Drives (pulse and direction input; DIP-switch configuration) and Advanced Drives (communication/analog control and setup) are available.



Complete SureStep system in 2 components: Power Supply and Integrated Stepper Motor/Drive. Standard Motor/Drives (pulse and direction input; DIP-switch configuration) and Advanced Motor/Drives (communication/analog control and setup) are available.



tMNC-1 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

High-performance microstepping drives with high-torque stepping motors

SureStep stepping systems provide simple and accurate control of position and speed. Pulses (or "step" and "direction" signals) from an AutomationDirect PLC or other indexer and motion controller are "translated" by the microstepping drive into precise movement of the stepping motor shaft. The SureStep stepping motors use 2-phase technology with 200 full steps per revolution or 1.8° per full step. Older type stepping motor drives, which operate stepping motors in full step mode, can result in stalling or lost motion due to potential problems with low speed mechanical vibration (usually between 100 to 200 RPM). To minimize this vibration problem, the SureStep microstepping drives use advanced microstepping technology to smooth the motor motion and stepping response. The SureStep family has options for open loop control (no encoder), position monitoring (external encoder feedback), and inclusive position verfication (integrated motor/drives with internal encoder). Inclusive position verification provides for stall prevention and detection along with position completion after a temporary stall.

SureStep stepper drives support a wide range of selectable microstep resolutions, from 200 steps per revolution (full step) to 51,200 (full step ÷ 256) steps per revolution, depending on model.

The advanced drives can operate with traditional high-speed inputs, but can also be commanded via 0-5V analog input. They have an internal indexer that can accomplish point-topoint moves controlled via ASCII communication.

FREE configuration software!

SureMotion Pro software is available that makes setting parameters a snap for the advanced drives and advanced integrated motor/drives! SureMotion Pro replaces SureStep Pro configuration software. Download free from our website:

http://support.automationdirect.com/products/suremotion.html

Standards and Agency Approvals



How fast can my system go?

M	aximum	Potential	Speed Cha	art (rpm) *			
PLC		SureStep Drive Steps/Rev Selection					
Model	Max Output (kHz)	400 Steps/Rev	1000 Steps/Rev	2000 Steps/Rev	10,000 Steps/Rev		
DL05, DL105	7	1,050	420	210	42		
DL06	10	1,500	600	300	60		
H0/H2/H4/T1H -CTRIO	25	>2,500***	1,500	750	150		
H2-CTRIO2	250		>2,500***		1,500		
P2-HS0	1000	>2,500***					
P3-HS0	1000	>2,500***					
BRX	250	>2,500*** 1,500					

These speeds are theoretical maximums. See torque curves of specific motors for their rom limits.

Stepping Motor RPM = $(A \div B) \times (60 \text{ seconds/minute})$

A = PLC output frequency (pulses per second)
B = microstepping resolution selection (steps/revolution)

Maximum RPM =		Steps/Sec A		Steps/Rev B		Sec/Min		
Example 1:	10,000	÷	400	Х	60			
DL06 with 10 kHz Built	in Pulse Output							
Example 2: $3,750 = 25,000 \div 400 \times 60$								
Hx-CTRIO with 25 kHz	Hx-CTRIO with 25 kHz Pulse Output							

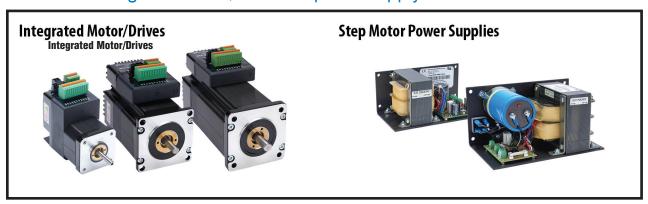
tMNC-2 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

^{*} Full step (200 steps/rev) will allow higher top speed. Full stepping, however, can create vibration at low speed.

^{**} Typical stepper systems do not run faster than 2500 rpm.

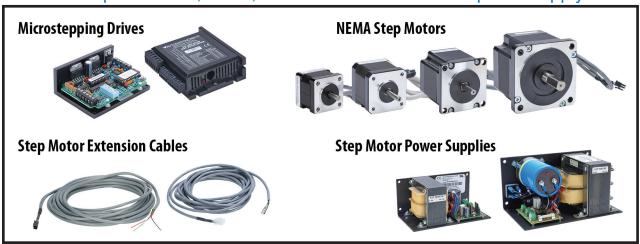
Two or Four components to make a complete system

Choose an integrated motor/drive and power supply



OR . . .

Choose a separate drive, motor, motor extension cable and power supply



Stepping System: Head to Head

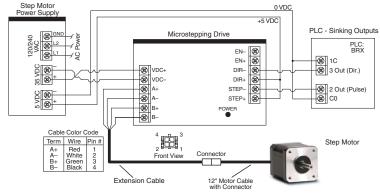


All prices are U.S. published prices. AutomationDirect prices as of August 2018

Price List. Parker prices are from http://buy. compumotor.com 8/13/2018.

\$798

for 2 drives

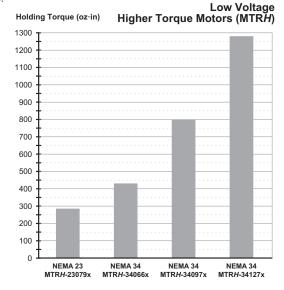


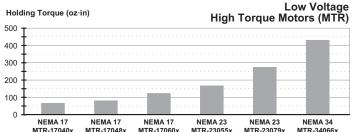
tMNC-3 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

NEMA frame stepping motors

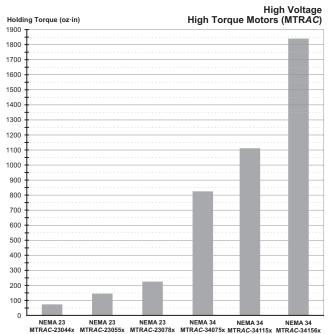
The SureStep stepping family has a wide variety of high-torque motors to handle a wide range of automation applications such as woodworking, assembly, and test machines. The motors are available in both single-shaft and dual-shaft configurations, with or without an encoder. Our square frame or "high-torque" style stepping motors are the latest in bipolar technology, resulting in very high torque to volume ratios. We have NEMA 14, 17, 23, and 34 size motors with holding torque ranging from 8 to 1841 oz·in. Wash down "W" motors (IP65) are also available. Optional 6, 10, or 20-foot extension cables with locking connectors are available to interface any of the stepping motors to the microstepping drive, except STP-MTRAC-x motors. The MTRAC motors have an integrated 10-foot pigtail cable. The extension cables can be easily cut to length, if desired. Integrated motor/drives and separate

motors with an "E" in their part number include an encoder for position feedback. The MTRAC motors are designed to work with 115 or 230 VAC powered drives and can withstand high voltages. This allows higher torque, especially at higher speeds.



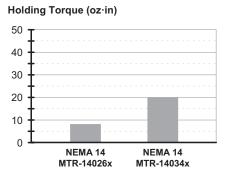


Note that the integrated/motor drive systems have a lower maximum torque due to heat constraints with the drive connected to the motor. For solutions requiring the highest torque, use the systems with our NEMA MTRH (low voltage, higher torque) or MTRAC (high voltage, high torque) motors.



Holding Torque (oz·in) Integrated Motors/Drives (MTRD) 100 100 NEMA 17 NEMA 17 NEMA 23 NEMA 23 NEMA 24 MTRD-17030x MTRD-17038x MTRD-23042x MTRD-23065x MTRD-24075x

Low Voltage Low Torque Motors (MTR)



tMNC-4 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

High-performance microstepping drives

SureStep microstepping drives

(STP-DRV-4035, -4830, -4845, -6575, & STP-MTRD-x)

- · Standard high-speed pulse input (pulse and direction)
- On-board or removable screw terminals for easy hook-up
- Optically-isolated inputs ready for +5VDC logic from AutomationDirect PLCs, or 5–24 VDC (depending on model)
- No software or add-on resistors required for drive configuration; dipswitch and/or rotary-dial setup
- Dipswitch used for built-in self-test, microstep resolution selection, current level selection, and optional idle current reduction.
- · Optional external encoder feedback for integrated models

SureStep high bus voltage microstepping drives

(STP-DRVAC-24025)

- Auto-setup measures motor parameters and configures motor current control and anti-resonance gain settings
- Uses universal AC input 90 to 240 VAC, AC input voltage must be selected by switch
- Switch selectable microstep resolution, 16 settings from 200 to 25600 steps/rev
- Switch configurable running current, anti-resonance, input signal filter, step smoothing filter, and self test
- · Motor selection via 16-bit rotary switch

SureStep advanced microstepping drives (STP-DRV-4850, STP-DRV-80100, & STP-MTRD-xR)

All the features of the standard high-performance drive, plus:

- · Software configurable
- · 200 51,200 microsteps (software selectable)
- High-speed pulse input (Quadrature, cw/ccw, pulse/direction)
- Analog velocity mode (0-5v or potentiometer)
- Internal indexer (point-to-point moves via ASCII command)
- AB quadrature/encoder following for all advanced models
- Advanced "E" integrated models contain a built-in encoder (encoder is not accessible and not available for signaling outside the drive)

Power supplies

- SureStep linear power supplies, 32V @ 4A, 48V @ 5A, 48V @ 10A, 70V @ 5A
- Input and output fuses included on power supplies
- Includes 5 VDC Logic supply for all low voltage signals
- Switching power supplies also available (12V, 24V, 48V)

tMNC-5 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

1. Choose a motor

Determine the torque and speed required by your application. Then look at the motor speed-torque curves in the Motors and Standard Integrated and Advanced Integrated sections of this catalog chapter. Choose a standalone or integrated motor that can run your application with plenty of speed and torque reserve (most stepper systems should have a 100% safety margin for torque). If encoder feedback is desired, be sure to choose an "E" model motor. If an IP65 rating is desired, choose a "W" motor. [If you chose an Integrated motor/drive, you can skip to "Choose a Power Supply". If you chose an STP-MTRAC motor, you are done. The MTRAC motors use the STP-DRVAC-24025 drive, have no motor extension cable (10' leads on the motor), and require no power supply (the drive uses AC input power).]



NEMA 14, 17, 23 and 34 mounting flanges

Variety of bipolar step motors to cover a wide range of applications

Holding torque ranges from 8 to 1841 oz.in

Single-shaft, Dual-shaft, IP65, high bus voltage, and encodermounted models available

> 1-ft cable with locking connector on the end (MTRAC motors have 10' leads)

Square frame style produces high torque and achieves best torque-to-volume ratio

20-foot extension cable with locking connector

2. Choose a motor extension cable

[If you chose an Integrated motor/drive in Step 1, skip to "Choose a Power Supply", an extension cable is not required.]

Our 6-, 10-, and 20-ft motor extension cables have a locking connector that mates up to the motor cable. The extension cables allow you to quickly connect the motor to the drive without having to splice wires or cut any cables. All STP-MTRAC-x motors have integrated 10-foot cables and don't need an extension cable.

If you chose an STP-MTR-xxxx motor, select an STP-EXT-0xx cable.

If you chose an STP-MTRL-xxxx motor, select an STP-EXTL-Oxx cable.

If you chose an STP-MTR**H**-xxxx motor, select an STP-EXT**H**-0xx cable (The "**H**" motors and cable can handle higher motor current).

If you chose an STP-MTR-xxxx \pmb{W} motor, select an STP-EXT \pmb{W} -0xx cable.

If you chose an STP-MTR**H**-xxxx**W** motor, select an STP-EXT**HW**-0xx cable.

If you chose an STP-MTRAC-xxxx motor, no cable is required.



tMNC-6 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

3. Choose a drive

[If you chose an Integrated motor/drive in Step 1, skip to "Choose a Power Supply" . . . you have already chosen your drive. If you chose STP-MTRAC, you are done - the STP-MTRAC motors use the STP-MTRAC-24025 drive and don't require an extension cable or power supply.]

The chart below is a quick selection guide. For a full list of features, check out the Technical Info later in this chapter. The requirements for what you will need from a drive are determined by your applications. Deciding whether you plan to operate the drive via high speed pulses, analog control, encoder following, or communication commands is an important factor. The voltage supplied to the drive as determined by the speed torque curves is another important factor to consider when choosing a drive. If you need to select a drive based on RMS step motor phase current, please see the next page.

- Standard and Advanced Drives and Integrated Motor/Drives can accept high speed pulse input control.
- Advanced Drives and some Integrated Motor/Drives can also accept serial communication control.
- STP-MTRAC and STP-DRVAC motors and drives are designed for use with high voltages. These components are not designed to work at low voltages (12V, 32V, 48V, 70V).





What you need	STP- DRV- 4035	STP- DRV- 4845	STP- DRV- 4850	STP- DRV- 6575	STP- DRV- 80100	STP- MTRD- 17x(E)	STP- MTRD- 23x(E)	STP- MTRD- 17xR(E)	STP- MTRD- 23xR(E)	STP- MTRD- 24xRV(E)
12V Speed-Torque Curve (from Step 1)	-	-	-	-	-	√	√	√	√	\checkmark
32V Speed-Torque Curve (from Step 1)	√	√	√	√	√	√	√	√	√	√
48V Speed-Torque Curve (from Step 1)	-	√	√	√	√	-	√	-	√	√
70V Speed-Torque Curve (from Step 1)	-	ı	-	-	√	-	√		√	√
More than 3.5A/motor phase	-	$\sqrt{}$	√	√	√	-	-	-	-	-
More than 5A/motor phase ("H" motors)	-	-	-	√	√	_	_	_	_	-
Supply voltage	12-32	24-48	24-48	24-65	24-80	12-48	12-70	12-48	12-70	12-70
Digital Input Voltage	5V (12V*, 24V*)	5-24V	5V (12V*, 24V*)	5-24V	5V (12V*, 24V*)	5-24V	5-24V	5-24V	5-24V	5-24V
Internal Indexing (Drive can move from Point A to Point B with a serial communication command)	-	-	√	-	√	-	-	V	√	V
High speed pulse input	√	√	√	√	√	√	√	V	√	V
Analog Velocity Input	-	-	√	_	√	_	_	√	√	√
Position Verification (internal encoder)	_	_	-	_	_	_	_	E models only	E models only	E models only
External encoder	-	1	-	-	-	E models only	E models only	-	-	-
RS-232 communication (ASCII)	-	-	√	-	√	_	-	-	_	_
RS-485 communication (ASCII)	-	-	-	-	-	-	-	√	√	√
Variable I/O (I/O can be either a digital input or digital output)	-	-	-	-	-	-	-	_	-	V

^{*} External dropping resistor required for 12V and 24V I/O use. See Product Data Sheet for wiring details and resistor values.

tMNC-7 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

3a. Using RMS Step Motor Phase Current to Select an Appropriate Stepper Drive Rated in Peak Phase Current

 $(Drive Amps)_{peak} = 1.2 x (Motor Amps)_{RMS}$

Generic stepper drives usually have output current specified in peak phase current while stepper motors will have their phase current specified in RMS phase current. This can cause sub-optimal drive to motor pairing unless this is understood. There is no need to understand this difference if you are selecting a system that uses the SureStep drives that are tuned for specific SureStep motors. These drives will have a rotary switch setting (STP-DRV-6575 and STP-MTRAC-24025) or a motor selection in the SureMotion Pro software (STP-DRV-4850 and STP-DRV-80100). These drives when properly paired with

a SureStep motor will output 1.2 times the motor rated phase current

When choosing a drive that only has current selections instead of motor specific selections you will want to select a peak current that is 1.2 times the motor's listed RMS current. The true peak drive current value would be 1.4 times the RMS motor value but this amount of current will cause a lot of motor heating and the torque at higher speeds will actually suffer with due to higher back electro-magnetic force caused by the inductive field of the coils changing polarity quickly.

Example of a SureStep matched stepper system

To use an STP-MTR-23055 motor with a STP-DRV-6575 drive, the drive's rotary switch should be positioned to selection 9 (STP-MTR-23055x). The STP-MTR-23055 has a phase current of 2.8 A (RMS), so the drive will actually output 1.2 x 2.8 A (RMS) = 3.36 A (peak). You do not need to calculate peak or RMS current with a pre-configured SureStep motor and drive system.



Matched stepper system

Example of an adjustable current stepper drive

To use an STP-MTR-23055 motor with a STP-DRV-4845 drive, you should calculate the correct phase current setting for the drive. The motor phase current is 2.8 A (RMS).

- If you do not understand peak vs RMS current, you would select phase current position #8, the 2.8 A selection on the drive (blue box). This setting will work (and the motor will run very cool) but will provide slightly less than the motor's rated torque.
- If a true peak current value is selected (1.4 x 2.8 A = 3.92
 A) then the rotary switch selection would be set to the C
 position (red box). This will cause excessive motor heating
 and a lack of performance at higher speeds.
- The optimal phase current selection for stepper motors is 1.2 times the motor RMS phase current (1.2 x 2.8 A (RMS) = 3.36 A (peak)). This will be the rotary switch selection A (green box)

STP-DI STEPPE			
AGE 24-48/DC RRENT 4.5A PEAK	HASE SW	CURREN VITCH	F F
PUT VOLI	SW 0 0 1 2	PHASE CURREN 1.1 1.3 1.5 1.7	
China China	5 6 7 8	2.0 2.2 2.4 2.6 2.8	
Wade in FE-90% IDLE	9 A B C	3.1 3.4 3.6 3.8	
INERTIA INERTIA	E F	4.3]

		845 Motor Sele ase)(Peak of S	
Rotary Switch Position	SW1 & SW2 @100%	SW1 & SW2 @90%	SW1 & @80
0	1.1	1.0	0.9
1	1.3	1.2	1.0
2	1.5	1.4	1.2
3	1.7	1.5	1.4
4	2.0	1.8	1.6
5	2.2	2.0	1.8
6	2.4	2.2	1.9
7	2.6	2.3	2.
8	2.8	2.5	2.2
9	3.1	2.8	2
Α	3.4	3.1	2.:
В	3.6	3.2	2.9
С	3.8	3.4	3.0
D	4.0	3.6	3.
E	4.3	3.9	3.4
F	4.5	4.1	3.0

Matching an adjustable stepper drive with any step motor

tMNC-8 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

4. Choose a power supply

Since all low voltage SureStep (non-integrated) motors can operate at 32V, 48V, and 70V, the selection of a power supply is dependent on the selected speed-torque curve of the motor and on the selection of drive. If using an integrated motor/ drive, then the power supply is dictated by the specifications of the integrated product. If using an STP-MTRAC drive, then no DC power supply is needed since the drive is powered directly from 115 to 230 VAC. Choose a power supply that

matches the desired speed-torque curve and stays within the voltage limit of the selected drive. Each SureStep linear power supply has incoming AC and outgoing DC fusing. The linear supplies have an electronic overload protected 5V supply for all your logic needs. Stepper applications without large fluctuations in load, without aggressive deceleration, and without regeneration (where the load pushes the motor) can often use a switching power supply instead.

Permissible Drive/Power Supply Combinations

		Linear Pov	wer Supply	У	Switc	hing Power S	Supply
DC Powered Drive	STP- PWR- 3204	STP- PWR- 4805	STP- PWR- 4810	STP- PWR- 7005	PSB12-xxxS	PSB24-xxxS	PSB48-xxxS
STP-DRV-4035 12-32 VDC input (42V max)	1	_	_	_	V	√	_
STP-DRV-4830 12-48 VDC input (53V max)	1	V	√	_	V	√	1
STP-DRV-4845 24-48 VDC input (60V max)	√	V	√	_	_	√	1
STP-DRV-4850 24-48 VDC input (53V max)	√	V	√	_	_	√	1
STP-DRV-6575 24-65 VDC input (85V max)	√	√	√	_	_	√	V
STP-DRV-80100 24-80 VDC input (88V max)	√	V	√	√	_	√	√
STP-MTRD-17 12-48 VDC input (55V max)	√	√	√	_	V	√	√
STP-MTRD-23, -24 12-70 VDC input (75V max)	√	√	√	√	V	√	1
Supply current calculation	ply, the power	at use multiple si supply current m d motor currents.	ust be at least th			e multiple steppers an upply current must be ned motor currents:	
	I(ps)	≥ <i>2/3 x (I_motor1</i>	+ I_motor2 + I_I	$I(ps) \ge 0.66 x$	(I_motor1 + I_motor2	+ I_motor 3 +)	

Linear Power Supply

Screw terminal AC input and 120 or 240 VAC, 50/60 Hz DC output connections power input (switch selectable)

32V. 48V and 70V linear supplies

Power ON LEDs

Unregulated linear supplies perfect for stepper systems

> Input and output fusing included



Switching Power Supply

85-264 VAC (DC input range 120-375 VDC)

Rugged plastic or aluminum housings with integral 35mm DIN rail mounting adapters

Adjustable output voltage





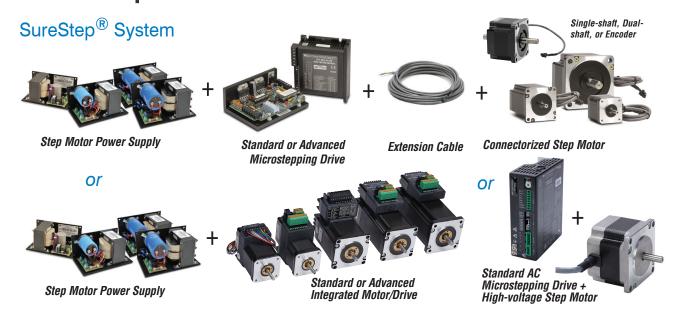


DC Output Overload and Short-Circuit

Note: For detailed information on the switching power supplies, please see: https://cdn.automationdirect.com/static/specs/rhinopsbc1d2.pdf

tMNC-9 **Motion Control**

Surestep Stepping System Components



SureStep stepping family includes:

- Linear step motor power supplies
- DIP-switch configurable microstepping drives
- Software-configurable advanced microstepping drives
- · Motor extension cables
- NEMA 14, 17, 23, and 34 frame size step motors in single shaft, dualshaft, IP65, high bus voltage, or encoder mounted configurations
- NEMA 17, 23, and 24 frame size integrated motor/drives
- Variety of step motor accessories including encoders, control cables, and connector kits
- SureStep PC adapter, USB to RS-485
- SureMotion Pro software for advanced drive and integrated motor/ drive systems

Motor features

- Low voltage, high torque, 2-phase, bipolar, 1.8° per step, 4-lead
- High voltage, high torque, 2-phase, bipolar, 1.8° per step, 8-lead
- · Available in single-shaft and dual-shaft models
- Connectorized pigtails or integrated 10' cable (STP-MTRAC only)
- Optional encoder feedback (STP-MTR-xxxxE)
- IP65 versions available (STP-MTR-xxxxW)
- High bus voltage versions available (STP-MTRAC-xxxx)
- Wide variety of NEMA 14, 17, 23, and 34 motors

Power supply features

- Linear, unregulated DC power supplies
- 120/240 VAC selectable input
- 32V, 48V, 70V DC output models available
- All linear models have additional 5VDC, 500mA regulated logic supply
- Fusing included for both incoming AC and outgoing DC
- 5V supply has electronic overload protection

NOTE: If a switching power supply is desired, we recommend the PSB12-xxxS, PSB24-xxxS, or PSB48-xxxS series.

Standard stepper drive features (STP-DRV-4035, -4830, -4845, -6575, STP-MTRD-x, STP-DRVAC-24025)

- Low cost, digital step motor driver in compact package
- Operates from Step and Direction signals, or Step CW and Step CCW (jumper selectable).
- Fault output and Enable input
- Optically isolated I/O
- Digital filters prevent position error from electrical noise on command signals; jumper selectable: 150 kHz or 2MHz
- Rotary or DIP switch easily selects from many popular motors
- Electronic damping and anti-resonance
- Automatic idle current reduction to reduce heat when motor is not moving; switch selectable: 50% or 90% of running current
- Switch-selectable step resolution: 200–25,600 steps per revolution depending on drive
- Switch-selectable microstep emulation provides smoother, more reliable motion in full- and half-step modes
- Automatic self test (switch selectable)
- Optional external encoder feedback (integrated models)
- Operates from a 24–65 VDC or 12–40 VDC power supply, depending upon model. STP-DRVAC drive operates off AC voltage.
- Running current from 0.35–7.5A

Advanced stepper drive features (STP-DRV-4850, STP-DRV-80100, STP-MTRD-xR, & STP-MTRD-xRE)

- Max 5A, 48V and max 10A, 80V models available
- Software configurable
- Programmable microsteps
- Internal indexer (via ASCII commands)
- Self test feature
- Idle current reduction
- Anti-resonance
- Torque ripple smoothing
- · Step, analog, and serial communication inputs
- Serial communications allow point-to-point positioning
- AB quadrature/encoder following (integrated models)
- Optional internal encoder feedback (integrated models)
- RS-485 communications (integrated models)
- Four 5 to 24 volt digital "Variable I/O" points (NEMA 24 integrated models)
- Controllable via streaming SCL commands

tMNC-10

Surestep Stepping System Components

SureStep Powe	SureStep Power Supply / DC Input Drive Compatibility								
Drive ⁽¹⁾⁽²⁾	Recomme	Recommended Linear Power Supply ⁽¹⁾ (2)(5)							
Model #	STP-PWR -3204								
STP-DRV-4035	V	No	No	No					
STP-DRV-4830	V	√	V	No					
STP-DRV-4845	V	√	V	No					
STP-DRV-4850	V	√	V	No					
STP-DRV-6575	√	√	V	No					
STP-DRV-80100	V	√	V	√					
STP-MTRD-17 ⁽⁴⁾	V	√	V	No					
STP-MTRD-23 ⁽⁴⁾	√	√	V	√					
STP-MTRD-24 ⁽⁴⁾	٧	V	1	√					

- Do NOT use a power supply that exceeds the drive's input voltage range.
 If using a linear power supply, ensure that the unloaded voltage does not float above the drive's maximum input range.
- For best performance, use the lowest voltage power supply that supplies the required speed and torque.
- An unloaded STP-PWR-7005 can float above the allowable input voltages of some drives if it is fed with a high AC input voltage (greater than 120VAC).
- Integrated motor/drives are included here because they include a drive as well as a motor.
- STP-DRVAC-x drives are AC powered and cannot be powered by DC power supplies.

SureStep Pow	SureStep Power Supply / DC Input Drive Compatibility									
Drive ⁽¹⁾⁽²⁾	Recommended	Recommended Switching Power Supply $^{(1)(2)(4)}$								
Model #	PSB12-xxxS	PSB24-xxxS	PSB48-xxxS							
STP-DRV-4035	√	√	No							
STP-DRV-4830	√	√	√							
STP-DRV-4845	No	√	√							
STP-DRV-4850	No	√	√							
STP-DRV-6575	No	√	√							
STP-DRV-80100	No	√	√							
STP-MTRD-17 ⁽³⁾		√	√							
STP-MTRD-23 ⁽³⁾	√	√	√							
STP-MTRD-24 ⁽³⁾	√	√	√							

- 1) Do NOT use a power supply that exceeds the drive's input voltage range.
- For best performance, use the lowest voltage power supply that supplies the required speed and torque.
- 3) Integrated motor/drives are included here because they include a drive as
- STP-DRVAC-x drives are AC powered and cannot be powered by DC power supplies.

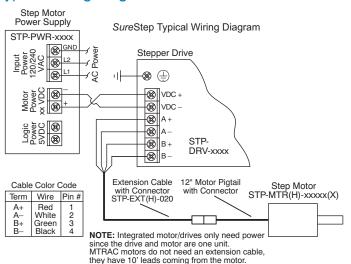
SureStep AC Motor/Drive Compatibility							
Madal #	STP-DRV	AC-24025					
Model #	Series Wired Motor	Parallel Wired Motor					
STP-MTRAC-23044(x)	√	No					
STP-MTRAC-23055(x)	√	No					
STP-MTRAC-23078(x)	√	No					
STP-MTRAC-34075(x)	√	No					
STP-MTRAC-34115(x)	√	No					
STP-MTRAC-34156(x)	√	No					

NOTE: STP-MTRAC-34156(x) motors have a 5/8" front shaft

SureStep DC	Inp	ut Dr	ive / I	Motor	Comp	atibil	ity ⁽³⁾				
Motor ⁽¹⁾⁽²⁾			Recommended Drive ⁽¹⁾								
Model # (1)(2)	Rated Amps	Extension Cable ⁽²⁾	STP-DRV-4035 ⁽¹⁾	STP-DRV-4830	STP-DRV-4845	STP-DRV-4850 ⁽¹⁾	STP-DRV-6575 ⁽¹⁾	STP-DRV-80100 ⁽¹⁾			
STP-MTRL-14026(x)	0.35	STP-	√	√	_	√					
STP-MTRL-14034(x)	0.8	EXTL- 0xx	√	1	V	√	_	-			
STP-MTR-17040(x)	1.7		√	1	4	√	4	1			
STP-MTR-17048(x)	2.0		√	1	√	√	√	1			
STP-MTR-17060(x)	2.0	STP-			STP- EXT-	√	√	√	√	√	√
STP-MTR-23055(x)	2.8	Oxx	√	√	√	√	√	√			
STP-MTR-23079(x)	2.8		√	√	√	√	√	√			
STP-MTR-34066(x)	2.8		√	√	√	√	√	√			
STP-MTRH-23079(x)	5.6						√	√			
STP-MTRH-34066(x)	6.3	STP- EXTH-					√	1			
STP-MTRH-34097(x)	6.3	Oxx					√	1			
STP-MTRH-34127(x)	6.3	Ĺ.,					√	1			

- The combinations above will perform according to the published speed/torque curves. Using a motor with a current rating higher than the drive's output rating will proportionally limit the motor torque.
- 2) MTR motors have connectors compatible with the EXT extension cables. MTRL motors have connectors compatible with the EXTL extension cables. MTRH motors have connectors compatible with the EXTH extension cables. W-series motors have connectors compatible with the EXTW and EXTHW extension cables.
- Not applicable to integrated motor/drives as drives and motors are already paired.

Typical Wiring Diagram



NOTE: STP-MTRAC motors and STP-DRVAC drives are designed to work with AC input power to the drive. They are not designed to work with DC input power.

tMNC-11 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Microstepping Drives Overview

Drive Mode	el		Star	doud Mious							
	e/		Standard Microstepping L					Advanc	ping Drives		
Price		STP- DRVAC- 24025	STP- DRV-4830	STP- DRV-4845	STP- DRV-6575	STP- MTRD-x	STP- DRV-4035	STP- DRV-4850	STP- DRV-80100	STP-MTRD-xR	
		\$199.00	\$69.00	\$79.00	\$94.00	See Integrated Motor/Drives section	\$174.00	\$243.00	\$291.00	See Integrated Motor, Drives section	
Drive Type		M	icrostepping driv	re with pulse inp	out	Integrated stepper motor/ drive	Micro- stepping drive with pulse input	with pulse or analog input, serial si		Advanced integrated stepper motor/drive with internal encoder	
			enclo	osed		enclosed	open-frame	enclo	osed	enclosed	
Output Curi	rent	0.6–2.5 A/ phase	0.35-3.0 A/ phase	0.8–4.5 A/ phase	0.5–7.5 A/ phase	_	0.4–3.5 A/ phase	0.1–5 A/phase	0.1–10 A/phase	_	
Input Volta	ge	nominal: 120/240 VAC range: 90–240 VAC	nominal: 12–48 VDC range: 10–53 VDC	nominal: 24–48 VDC range: 20–60 VDC	nominal: 24–75 VDC range: 20–85 VDC	nominal: 12-48 VDC (NEMA 17) 12-70 VDC (NEMA 23) range: 10-55 VDC (NEMA 17) 11-74 VDC (NEMA 23)	nominal: 12–32 VDC range: 12–42 VDC	nominal: 24–48 VDC range: 18– 53 VDC	nominal: 24–80 VDC range: 18–88 VDC	nominal: 12-48 VDC (NEMA 17 12-70 VDC (NEMA 23, 24) range: 10-55 VDC (NEMA 17 11-74 VDC (NEMA 23 10-75 VDC (NEMA 24	
Configurati	on Method	ı	rotary dial, dip s	witches, jumper	S	dip s	witches	SureMotion P	PRO: free download)		
Amplifier T	уре	MOSFET, dual H-bridge, 4-quadrant		idge, Dual MOSFET, dual H-bridge, quadrant bipolar chopper MOSFET, dual H-bridge, rant			MOSFET, dual H-bridge, 4-quad- rant		Dual H-bridge, 4 quadrant		
Current Co	ntrol	4-state PWM @ 20 kHz	M 4-state PWM @ 4-state PWM @ 20 kHz 4-state PWM @ 20 kHz 4-state PWM @ 20 kHz				PWM @ 20 kHz				
		0 20 11112		dipswitch	selectable	, O 10 111 12			software selecta	able	
Microstep	Kesolution	200 to 25,6	00 steps/rev	200 to 20,0	00 steps/rev	200 to 25,600 steps/rev	400 to 10,000 steps/rev	200 to 51200 steps/rev			
	Step & Dir	YES	YES	YES	YES	YES	YES	YES	YES	YES	
	CW/CCW	YES	YES	YES	YES	YES	n/a	YES	YES	YES	
Modes of	A/B Quad	n/a	n/a	n/a	n/a	n/a	n/a	YES	YES	YES	
Operation	Oscillator	n/a	n/a	n/a	n/a	n/a	n/a	YES	YES	YES	
	Serial Indexing	n/a	n/a	n/a	n/a	n/a	n/a	YES	YES	YES	
Digital Input	Step/Pulse Direction	step & direction,		n, CW/CCW step		step & direc- tion, CW/ CCW step	step & direc- tion	step & direction, CW/CCW stern/stop & direction, jog CW/C			
Signals	Enable		motor (disable		motor enable	motor disable	motor enable, ala	arm reset, speed s	elect (oscillator mode)	
Analog Inp	ut	n/a	n/a	n/a	n/a	n/a	n/a	speed (control	signal range, offset, dead band, and filtering	
Output Sigi	nal	fault	n/a	fault	fault	fault	n/a			brake, fault, motion, tach	
Communic Interface		n/a	n/a	n/a	n/a	n/a	n/a	YES (programming/communication cable incl		ation cable included)	
Non-volatil Memory St		n/a	n/a	n/a	n/a	n/a	n/a	YES			
ldle Curren	t Reduction					YE	S				
Self Test						YE	S				
Additional Features		Step pulse noise filter, accepts AC power input	Step pulse noise filter	ture to im	inti-resonance & prove motor per	formance)	n/a	(allows for fine a	esonance (Electron Auto setup Microstep emula Torque ripple smo adjustment of phas 1.5 rps) m (command sign	ation othing se in the range 0.25 to	

tMNC-12 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Standard Microstepping Drives





	_c	reStep Series Specifications – Standard Micr	octonning Drives		
Microstor	oping Drive	restep Series Specifications – Standard Micr STP-DRV-4035	STP-DRV-4830		
	· · · · · · · · · · · · · · · · · · ·				
,,		Microstepping drive with pulse input	Microstepping drive with pulse input		
		Selectable from 0.4 to 3.5 A/phase (maximum output power is 140W)	1 9 7		
	p/s required)	Nominal: 12–32 VDC Range: 12–42 VDC (including ripple voltage)	Nominal: 12–48 VDC Range: 10–53 VDC		
Configura	tion Method	DIP switches	DIP switches		
Amplifier	Туре	MOSFET, dual H-bridge, bipolar chopper	MOSFET, dual H-bridge, 4-quadrant		
Current C	ontrol	4-state PWM @ 20 kHz	4-state PWM @ 16 kHz		
Protection	n	n/a	n/a		
Recommo	ended Input Fusing	Fuse: 4A fast-acting; ADC # ACG4; Holder: ADC # DN-F6L110	Fuse: 3A fast-acting; ADC #AGC3; Holder: ADC # DN-F6L110		
	Input Circuit	Opto-coupler input with 440Ω resistance (5 to 15 mA input current); Logic Low is input 0.8 VDC or less; Logic High is input 4VDC or higher.	5–24 VDC nominal (range: 4–30 VDC); optically isolated, differential.		
Input	Step/Pulse	Motor steps on falling edge of pulse and minimum pulse width is 0.5 μs (1MHz)	Minimum pulse width = 1µs. Maximum pulse frequency = 150kHz or 500kHz (user selectable).		
Signals	Direction	Needs to change at least 2 microseconds before a step pulse is sent	FUNCTIONS: step & direction, CW/CCW step		
	Enable	Logic 1 will disable current to the motor (current is enabled with no hook-up or logic 0)	FUNCTION: disable motor when closed		
	Analog	n/a	n/a		
Output Signal		n/a	n/a		
	Current Reduction	n/a	n/a		
	Idle Current Reduction	0% or 50% reduction (Idle current setting is active if motor is at rest for 1 second or more)	90% or 50% of running current. (Holding torque is reduced by the same %.)		
	Microstep Resolution	400 (200x2), 1,000 (200x5), 2,000 (200x10), or 10,000 (200x50) steps/rev	200, 400, 800, 1000, 1600, 2000, 3200, 4000, 5000, 6000, 6400, 8000, 10000, 12800, 20000, 25600		
Features	Phase Current Setting	0.4 to 3.5 A/phase with 32 selectable levels	(peak)(0.35–3.0) (0.25–2.3) RMS		
	Self Test	Uses half-step to rotate 1/2 revolution in each direction at 100 steps/second.	Automatically rotates the motor back and forth two turns in each direction in order to confirm that the motor is operational.		
	Step Pulse Noise Filter	n/a	Select 150kHz or 500kHz		
	Load Inertia	n/a	n/a		
Connectors		Screw terminal blocks with AWG 18 maximum wire size	DEGSON 15EDGK-5.08-02P-14-00AH 2-pin power connector DEGSON 15EDGK-3.1.04P-14-00A(H) 4-pin motor connector DEGSON 15EDGK-3.5-06P-14-00A(H) 6-pin I/O connector ADC part STP-CON-5 contains replacement connectors		
Maximum Humidity		90% non-condensing	90% non-condensing		
Storage/Ambient Temperature		-20 to 80 °C [-4 to 176 °F]	0 to 40 °C [32 to 104 °F] (mount to suitable heat sink)		
Operating Temperature		0 to 55 °C [32 to 131 °F] recommended; 70 °C [158 °F] maximum	0 to 85 °C [32 to 185 °F] (interior of electronics section)		
Drive Cooling Method		Natural convection (mount drive to metal surface to dissipate heat)	Natural convection (mount drive to metal surface)		
Mounting		(4) #4 screws to mount on wide side; (2) #4 screws to mount on narrow side	(2) #6 screws to mount to metal surface		
Weight		9.3 oz. [264 g]	3.0 oz [85.9 g]		
Agency A	pprovals	CE	CE		

tMNC-13 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Standard Microstepping Drives, continued





	Sui	reStep Series Specifications – Standard Mic	rostepping Drives						
Microstep	ping Drive	STP-DRV-4845	STP-DRV-6575						
Drive Typ	е	Microstepping dr	ive with pulse input						
Output Cu	ırrent	Selectable from 0.8–4.5 A/phase (peak of sine)	Selectable from 1.0–7.5 A/phase (peak of sine)						
Input Volt (external	age p/s required)	Nominal: 24–48 VDC Range: 20–60 VDC	Nominal: 24–65 VDC Range: 20–85 VDC						
Configura	tion Method	Rotary dial, DIP switches, jumpers							
Amplifier	Туре	MOSFET, dual H-bridge, 4-quadrant							
Current C	ontrol	4-state PW	M @ 20 kHz						
Protection	1	ſ	n/a						
Recomme	ended Input Fusing	Fuse: 4A fast-acting; ADC #AGC4; Holder: ADC # DN-F6L110	Fuse: 7A fast-acting; ADC #AGC7; Holder: ADC # DN-F6L110						
	Input Circuit	5–24 VDC nomina optically isola	l (range: 4–30 VDC); ted, differential.						
Input	Step/Pulse	· · · · · · · · · · · · · · · · · · ·	e frequency = 150kHz or 2MHz (user selectable).						
Signals	Direction	FUNCTIONS: step & direction, CW/CCW step							
	Enable	FUNCTION: disable motor when closed							
	Analog	n/a							
Output Si	gnal	30 VDC / 80 mA max, optically isolated photodarlington, sinking or sourcing. Function = closes on drive fault.							
	Current Reduction	Reduce power consumption and heat generation by limiting motor running current to 100%, 90%, 80%, or 70% of maximum. Current should be increased to 100% if microstepping. (Torque is reduced/increased by the same %.)	Reduce power consumption and heat generation by limiting motor running current to 100%, 90%, or 80% of maximum. Current should be increased to 120% if microstepping. (Torque is reduced/increased by the same %.)						
	Idle Current Reduction		of running current. reduced by the same %.)						
Features	Microstep Resolution	200, 200 smooth, 400, 400 sm	smooth, 2000, 5000, 12800, 20000						
	Phase Current Setting	(peak)(1.1–4.5) x 70%–100% DIP switch selectable (0.79–3.2) RMS	(1.3–6.3) x 80%–120% DIP switch selectable						
	Self Test	Automatically rotates the motor back and forth two turns in e	ach direction in order to confirm that the motor is operational.						
	Step Pulse Noise Filter	Select 150	kHz or 2MHz						
	Load Inertia	Set motor and load inerti	rtia range to 0–4x or 5–10x.						
Connecto	rs	Removable screw terminal blocks. Motor & Power Supply: 30–12 AWG; Signals: 30–14 AWG ADC part STP-CON-1 contains replacement connectors							
Maximum	n Humidity	90% non-	condensing						
Storage/A	Imbient Temperature	0 to 50 °C [32 to 122 °F]	(mount to suitable heat sink)						
Operating	<i>Temperature</i>	0 to 85 °C [32 to 185 °F] (interior of electronics section)						
Drive Coo	oling Method	Natural convection (mount drive to metal surface)							
Mounting		(2) #6 screws to m	ount to metal surface						
Weight		10.8 o	z [306g]						
Agency A	pprovals	CE,	_c UR _{us}						

tMNC-14 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Advanced Microstepping Drives



		SureStep Series Specifications – Advanc	ed Microstepping Drives										
Mic	rostepping Drive	STP-DRV-4850	STP-DRV-80100										
Dri	ve Type	Advanced microstepping drive with pulse or analog input, seri	al communication (serial communication allows indexing capability)										
Out	put Current	0.1-5.0 A/phase (in 0.01A increments)	0.1-10.0 A/phase (in 0.01A increments)										
Inp	ut Voltage	24-48 VDC (nominal)	24-80 VDC (nominal)										
(ex	ternal p/s required)	(range: 18-53 VDC)	(range: 18-88 VDC)										
Con	figuration Method	SureMotion Pro software (included)											
Am	plifier Type	MOSFET, dual H-bridge, 4-quadrant											
Cur	rent Control	4-state PWM @ 20 kHz											
Pro	tection	Over-voltage, under-voltage, over-temperature, external output	faults (phase-to-phase & phase-to-ground), inter-amplifier shorts										
Red	commended Input Fusing	Fuse: 4A 3AG delay (ADC #MDL4) Fuse Holder: ADC #DN-F6L110	Fuse: 6.25A 3AG delay (ADC #MDL6-25) Fuse Holder: ADC #DN-F6L110										
	Input Circuit		is input 0.8 VDC or less; Logic High is input 4 VDC or higher.										
S	Step/Pulse	Optically isolated, differential, 5V, 330Ω;											
Input Signals	Direction	n pulse width = 250 ns x pulse frequency = 2MHz ustable bandwidth digital noise rejection feature NCTIONS: step & direction, CW/CCW step, A/B quadrature, run/stop & direction, jog CW/CCW, CW/CCW limits											
ldu,	Enable		ů ,										
	Enable												
0	Analog	, , , , , , , , , , , , , , , , , , , ,											
<u> </u>	put Signal	Optically isolated, 24V, 10mA max; FUNCTIONS: fault, motion	n, tacn										
	nmunication Interface	RS-232; RJ11 (6P4C) receptacle											
Noi	n-volatile Memory Storage	Configurations are saved in FLASH memory on-board the DSF											
	Idle Current Reduction	Reduction range of 0-90% of running current after delay selectable in ms											
	Microstep Resolution	Software selectable from 200 to 51200 steps/rev in increments	1.										
	Modes of Operation	Step & direction, CW/CCW, A/B quadrature, oscillator, joystick											
res	Phase Current Setting	0.1-5.0 A/phase (in 0.01A increments)	0.1-10.0 A/phase (in 0.01A increments)										
eatures-	Self Test	Checks internal & external power supply voltages, diagnoses of	open motor phases										
Fe	Additional Features	Anti-resonance (Electronic Damping) Auto setup Microstep emulation Torque ripple smoothing (allows for fine adjustment of phase in the range 0.25 to 1.5 rps) Waveform (command signal) smoothing											
Cor	nnectors	Communication: RJ11 (6P4C); programming/communication											
		Other: removable screw terminal blocks; Motor & Power Supp	ply: 26–12 AWG; Signals: 28–16 AWG										
_	ximum Humidity	90% non-condensing											
_	rage Temperature	-20 to 80 °C [-4 to 176 °F] 0 to 55 °C [32 to 131 °F]; (mount to suitable heat sink)											
_	erating Temperature	,											
_	ve Cooling Method	Natural convection (mount to suitable heat sink)											
_	unting	#6 mounting screws (mount to suitable heat sink)											
_	ight .	8 oz [227g] (approximate)											
Age	ency Approvals	CE											

tMNC-15 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® High Bus Voltage Microstepping Drives



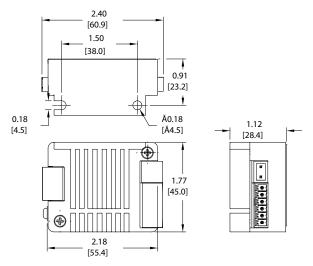
	SureS	tep Series Specifications – Standard Microstepping Drives						
Microste	ping Drive	STP-DRVAC-24025						
Price		\$199.00						
Drive Typ	е	Microstepping drive with pulse input						
Output Cu	ırrent	Selectable from 0.6–2.5 A/phase (peak of sine)						
Input Volt	age	90–240 VAC						
Configura	tion Method	Rotary dial, DIP switches, jumpers						
Amplifier	Туре	MOSFET, dual H-bridge, 4-quadrant						
Current Control		4-state PWM @ 20 kHz						
Protection	1	Over temp, over voltage, under voltage, over current, excess regen, open circuit						
Recomm	ended Input Fusing	Fuse: 4A fast-acting; ADC #AGC4; Holder: ADC # DN-F6L110						
	Input Circuit	5–24 VDC nominal (range: 4–28 VDC); optically isolated, differential.						
Input	Step/Pulse	Minimum pulse width = 1µs. Maximum pulse frequency = 150kHz or 2MHz (user selectable).						
Signals	Direction	FUNCTIONS: step & direction, CW/CCW step						
	Enable	FUNCTION: disable motor when closed						
	Analog	n/a						
Output Signal		30 VDC / 100 mA max, optically isolated photodarlington, sinking or sourcing. Function = closes on drive fault.						
	Current Reduction	n/a						
	Idle Current Reduction	90% or 50% of running current. (Holding torque is reduced by the same %.)						
F4	Microstep Resolution	200, 400, 800, 1000, 1600, 2000, 3200, 4000, 5000, 6000, 6400, 8000, 10000, 12800, 20000, 25600						
Features	Phase Current Setting	0.6–2.5 Amps RMS						
	Self Test	Automatically rotates the motor back and forth two turns in each direction in order to confirm that the motor is operational.						
	Step Pulse Noise Filter	Select 150kHz or 2MHz						
	Load Inertia	Set motor and load inertia range to 0–4x or 5–10x.						
Connectors		DEGSON 2EDGK-7.62-02P-14-00A(H) 2-pin power connector DEGSON 2EDGK-5.08-04P-14-00A(H) 4-pin motor connector DEGSON 15EDGK-3.81-08P-14-00A(H) 8-pin I/O connector ADC part STP-CON-6 contains replacement connectors						
Maximun	n Humidity	90% non-condensing						
Storage/Ambient Temperature		0 to 40 °C [32 to 104 °F]						
Operating	Temperature	0 to 85 °C [32 to 185 °F] (interior of electronics section)						
Drive Cod	ling Method	Natural convection (mount drive to metal surface)						
Mounting		(2) M4 screws to mount to metal surface						
Weight		1 lb 15 oz [0.88 kg]						
Agency A	pprovals	CE, _C UR _{US}						

tMNC-16 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

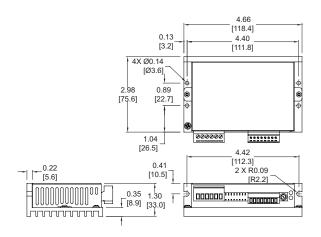
SureStep® Microstepping Drives Dimensions

Dimensions = in [mm]

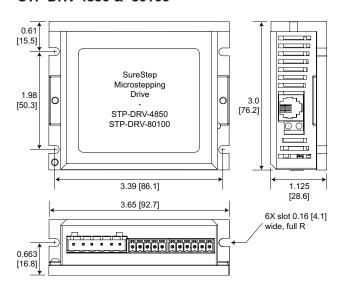
STP-DRV-4830



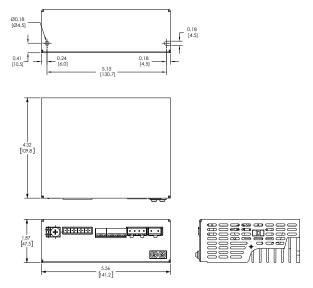
STP-DRV-4845 & -6575



STP-DRV-4850 & -80100



STP-DRVAC-24025

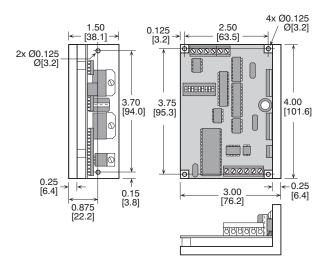


tMNC-17 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Microstepping Drives Dimensions

Dimensions = in [mm]

STP-DRV-4035



tMNC-18 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Stepping Motors

SureStep Series Part	Numbers	- Connectorized	l Bipolar Step _l	ping Motors*
Bipolar Stepping Motors	Price	Shaft Type	Torque Level	Encoder Mounting
STP-MTRL-14026	\$22.50	single		not available
STP-MTRL-14026D	\$27.00	dual		optional
STP-MTRL-14026E**	\$97.00	dual	low	pre-installed
STP-MTRL-14034	\$28.50	single	IOW	not available
STP-MTRL-14034D	\$32.50	dual		optional
STP-MTRL-14034E**	\$101.00	dual		pre-installed
STP-MTR-17040	\$19.00	single		not available
STP-MTR-17040D	\$23.00	dual		optional
STP-MTR-17040E**	\$92.00	dual		pre-installed
STP-MTR-17040W***	\$132.00	single		not available
STP-MTR-17048	\$23.00	single		not available
STP-MTR-17048D	\$27.50	dual		optional
STP-MTR-17048E**	\$97.00	dual		pre-installed
STP-MTR-17048W***	\$135.00	single		not available
STP-MTR-17060	\$37.50	single		not available
STP-MTR-17060D	\$42.00	dual		optional
STP-MTR-17060E**	\$111.00	dual		pre-installed
STP-MTR-17060W ***	\$175.00	single	high	not available
STP-MTR-23055	\$37.50	single		not available
STP-MTR-23055D	\$42.50	dual		optional
STP-MTR-23055E**	\$112.00	dual	_	pre-installed
STP-MTR-23055W ***	\$163.00	single		not available
STP-MTR-23079	\$49.00	single		not available
STP-MTR-23079D	\$54.00	dual		optional
STP-MTR-23079E**	\$123.00	dual		pre-installed
STP-MTR-23079W ***	\$177.00	single		not available
STP-MTR-34066	\$116.00	single		not available
STP-MTR-34066D	\$132.00	dual		not available
STP-MTR-34066W ***	\$211.00	single		not available
STP-MTRH-23079	\$55.00	single		not available
STP-MTRH-23079D	\$59.00	dual		optional
STP-MTRH-23079E **	\$129.00	dual		pre-installed
STP-MTRH-23079W ***	\$263.00	single		not available
STP-MTRH-34066	\$130.00	single		not available
STP-MTRH-34066D	\$145.00	dual		not available
STP-MTRH-34066W ***	\$299.00	single	higher	not available
STP-MTRH-34097	\$147.00	single		not available
STP-MTRH-34097D	\$162.00	dual		not available
STP-MTRH-34097W ***	\$335.00	single		not available
STP-MTRH-34127	\$174.00	single		not available
STP-MTRH-34127D	\$191.00	dual		not available
STP-MTRH-34127W ***	\$366.00	single		not available
Motors listing continued on next p	age			

- * For integrated motor/drives part numbers and pricing, see the integrated motor/drives section.
- ** E model motors come with a STP-MTRA-ENC9 encoder pre-installed. Requires STP-CBL-EBxx for encoder wiring. To change from the default 400ppr, use STP-USBENC-CBL-1. See the SureStep Stepping System Encoders section for more details.
- *** W models are IP65 washdown rated. All others are IP40.

STP-MTR-xxxxx (single-shaft)



STP-MTR-xxxxxE (encoder mount)



STP-MTR-xxxxxD (dual-shaft)



STP-MTR-xxxxxW (IP65)



tMNC-19 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Stepping Motors

SureStep Series Part I	lumbers -	- Non-connectori	zed Bipolar St	epping Motors							
Bipolar Stepping Motors	Price	Shaft Type	Torque Level	Encoder Mounting							
Motors listing continued from previous page											
STP-MTRAC-23044	\$57.00	single		not available							
STP-MTRAC-23044D	\$58.00	dual		optional							
STP-MTRAC-23055	\$63.00	single		not available							
STP-MTRAC-23055D	\$64.00	dual		optional							
STP-MTRAC-23078	\$88.00	single		not available							
STP-MTRAC-23078D	\$89.00	dual	High voltage	optional							
STP-MTRAC-34075	\$235.00	single	High torque	not available							
STP-MTRAC-34075D	\$236.00	dual		optional							
STP-MTRAC-34115	\$245.00	single		not available							
STP-MTRAC-34115D	\$246.00	dual		optional							
STP-MTRAC-34156	\$265.00	single		not available							
STP-MTRAC-34156D	\$265.00	dual		optional							

NOTE: STP-MTRAC-34156(x) motors have a 5/8" front shaft

STP-MTRAC-xxxxx (single-shaft)



SureStep® Stepping Motors Mounting Accessory

	Mounting Accessory – for NEMA 17 SureStep Series Bipolar Stepping Motors										
Part Number	Price	Description									
STP-MTRA-RB-85	\$8.50	Reducer bushing, 8mm OD to 5mm ID, 16mm length, aluminum alloy. Connects NEMA size 17 stepper motors to Koyo TRD-NH and TRD-SH hollow shaft encoders.									

tMNC-20 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Stepping Motors

	SureSt	ep Serie	s Speci	fication	s – Con	nectori	zed Bip	olar Ste	epping N	lotors			
			oltage orque				oltage orque				Low V Higher	oltage	
Bipolar Stepping Motors	STP-MTRL-14026(x)	STP-MTRL-14034(x)	STP-MTR-17040(x)	STP-MTR-17048(x)	STP-MTR-17060(x)	STP-MTR-23055(x)	STP-MTR-23079(x)	STP-MTR-34066(x)	STP-MTRH-23079(x)	STP-MTRH-34066(x)	STP-MTRH-34097(x)	STP-MTRH-34127(x)	
NEMA Frame Size	14	14	17	17	17	23	23	34	23	34	34	34	
	(lb·in)	0.5	1.25	3.81	5.19	7.19	10.37	17.25	27.12	17.87	27.12	50.00	80.50
Maximum Holding Torque*	(oz∙in)	8	20	61	83	115	166	276	434	286	434	800	1288
Torque	(N·m)	0.06	0.14	0.43	0.59	0.81	1.17	1.95	3.06	2.02	3.06	5.65	9.10
Rotor Inertia	(oz∙in²)	0.06	0.08	0.28	0.37	0.56	1.46	2.60	7.66	2.60	7.66	14.80	21.90
	(kg·cm ²)	0.0003	0.00035	0.05	0.07	0.10	0.27	0.48	1.40	0.48	1.40	2.71	4.01
Rated Current (A/phase)	0.35	0.8	1.7	2.0	2.0	2.8	2.8	2.8	5.6	6.3	6.3	6.3	
Resistance (Ω/phase)	8.5	7.66	1.6	1.4	2.0	0.75	1.1	1.11	0.4	0.25	0.3	0.49	
Inductance (mH/phase)		5.77	6.92	3.0	2.7	3.3	2.4	3.8	6.6	1.2	1.5	2.1	4.1
Insulation Class						130°0	C [266°F] C	lass B; 300	OV rms				
Basic Step Angle							1.	8°					
Shaft Runout (in)		0.002 in [0.051 mm]											
Max Shaft Radial Play @	9 1lb load												
Perpendicularity		0.003 in [0.076 mm]											
Concentricity		0.003 in [0.076 mm]											
Maximum Radial Load ((lb [kg])*	6.0 [2.7] 15.0 [[6.8]	39.0 [17.7]	15.0 [6.8]		39.0 [17.7]		
Maximum Thrust Load ((lb [kg])*	6.0 [2.7] 13.0 [5.9] 25.0 [11.3] 13.0 [5.9] 25.0 [11.3]					
Storage Temperature Ra	ange	-20°C to 100°C [-4°F to 212°F]											
Operating Temperature	Range	-20°C to 50°C [-4°F to 122°F] (motor case temperature should be kept below 80°C [176°F])											
Operating Humidity Ran	ge					559	% to 85% n	on-conden	sing				
Product Material						steel mo	tor case; st	ainless stee	el shaft(s)				
Environmental Rating						IP	40 (IP65 fo	r "W" moto	rs)				
Weight (lb [kg]) (E models)			0.35 [0.15] (0.4 [0.2])		0.7 [0.3] (0.8 [0.4])	0.9 [0.4] (0.9 [0.4])	1.5 [0.7] (1.5 [0.7])		3.9 [1.7]	2.4 [1.1] (2.4 [1.1])	3.9 [1.7]	5.9 [2.7]	8.4 [3.8]
Agency Approvals			1				C	E	1				1
Design Tips		Allow sufficient time to accelerate the load and size the step motor with a 100% torque safety factor. DO NOT disassemble step motors because motor performance will be reduced and the warranty will be voided. DO NOT connect or disconnect the step motor during operation. Mount the motor to a surface with good thermal conductivity, such as steel or aluminum, to allow heat dissipation. Use a flexible coupling with "clamp-on" connections to both the motor shaft and the load shaft to prevent radial and thrust loading on bearlings from minor misalignment.											
Accessory Extension Cal * For dual-shaft motors (STP-			⟨T L -0xx		STP-	STP-E: EXT W -0xx (XT-0xx (for "W" mo	otors)		STP-E	STP-EX EXT HW -0xx		otors)

tMNC-21 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Stepping Motors

Sure	Step Series	Specificati	ons – High V	oltage Bipo	lar Stepping	Motors				
				High V High 1						
Bipolar Stepping Moto	rs	STP-MTRAC- 23044(x)	STP-MTRAC- 23055(x)	STP-MTRAC- 23078(x)	STP-MTRAC- 34075(x)	STP-MTRAC- 34115(x)	STP-MTRAC- 34156(x)**			
NEMA Frame Size		23	23	23	34	34	34**			
(lb·in)		4.69	9.31	14.19	51.31	69.48	115.06			
Maximum Holding Torque*	(oz·in)	75	149	227	821	1110	1841			
Torquo	(N·m)	0.53	1.05	1.6	5.8	7.84	13			
5	(oz·in²)	0.66	1.64	2.62	7.38	14.74	24.06			
Rotor Inertia	(kg·cm²)	120	300	480	1350	2700	4400			
Rated Current	Series	0.71	0.71	0.71	2.15	2.05	2.55			
(A/phase)	Parallel	1.41	1.41	1.41	4.3	4.1	5.1			
Resistance (Ω/phase)	Series	12.4	14.4	18	4	4.8	4.8			
	Parallel	3.1	3.6	4.5	1.0	1.2	1.375			
Inductance	Series	30.4	51.2	60.8	32	43.2	44.8			
(mH/phase)	Parallel	7.6	12.8	15.2	8.0	10.8	11.2			
Insulation Class		В								
Steps per Revolution		200								
Basic Step Angle		1.8°								
Shaft Runout (in)	0411.1		0.00: [0.54		0.05 mm] 0.02 in [0.5]					
Max Shaft Radial Play	@ 11b load		0.02 in [0.51 mm]		0.025 in [0.635 mm]	mm] 0.08 in [2.03			
Max End Play @ 2.2-II	h Axial load		0.08 in [2.03 mm]		0.075 in	[1.91 mm]	0.08 III [2.03 mm]			
Connectors			8 leads, 24AWG			8 leads, 22AWG				
Temperature Rise	D			80°C [17						
Storage Temperature I Operating Temperature				-40°C to 70°C			,			
Operating Humidity Ra		-20°C to 50°C [-4°F to 122°F] 5% to 95% non-condensing								
Product Material	90	Steel motor case; stainless steel shaft(s)								
Environmental Rating		IP40								
Weight (lb [kg])		1.03 [0.47]	1.54 [0.7]	2.2 [1.0]	4.2 [1.9]	8.4 [3.8]	11.46 [5.2]			
Agency Approvals * For dual-shaft motors (ST			None			_c UR _{us}				

^{*} For dual-shaft motors (STP-MTRAC-xxxxxD):

tMNC-22 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

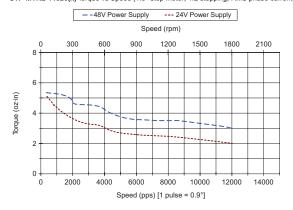
The sum of the front and rear Torque Loads, Radial Loads, and Thrust Loads must not exceed the applicable Torque, Radial, and Thrust load ratings of the motor.

^{**} STP-MTRAC-24156(x) motors have a 5/8" front shaft

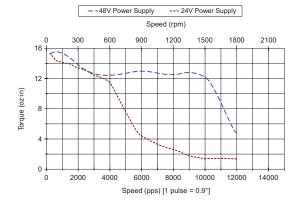
SureStep® Motor Running Torque vs. Speed Charts

STP-MTRL-14xxx(x) NEMA 14 Step Motors

STP-MTRL-14026(x) Torque vs Speed (1.8° step motor; 1/2 stepping, RMS phase current)



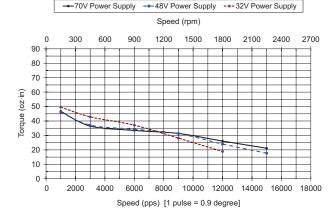
STP-MTRL-14034(x) Torque vs Speed (1.8° step motor; 1/2 stepping, RMS phase current)



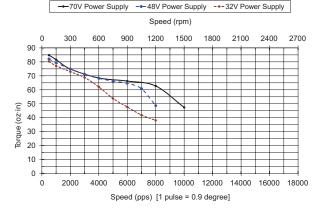
STP-MTR-17xxx(x) NEMA 17 Step Motors

Note: "W" series motors have 5% less running torque than other models

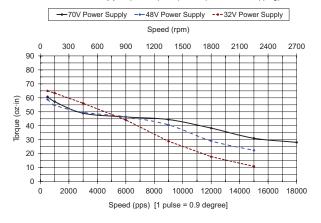
STP-MTR-17040(x) Torque vs Speed (1.8° step motor; 1/2 stepping)



STP-MTR-17060(x) Torque vs Speed (1.8° step motor; 1/2 stepping)



STP-MTR-17048(x) Torque vs Speed (1.8° step motor; 1/2 stepping)



Note: Motor torque vs speed charts for STP-MTRD series integrated motor/drives can be found in the integrated motor/drives section of the full catalog

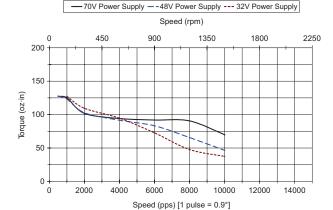
tMNC-23 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Motor Torque vs. Speed Charts (continued)

STP-MTR(H)-23xxx(x) NEMA 23 Step Motors

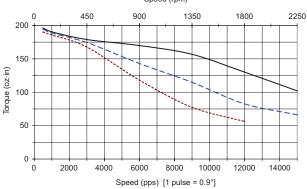
Note: "W" series motors have 5% less running torque than other models

STP-MTR-23055(x) Torque vs Speed (1.8° step motor; 1/2 stepping)

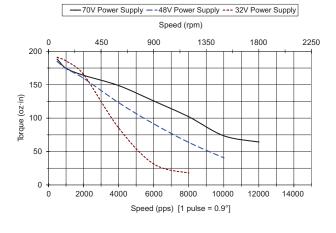


STP-MTRH-23079(x) Torque vs Speed (1.8° step motor; 1/2 stepping) -70V Power Supply --- 48V Power Supply --- 32V Power Supply

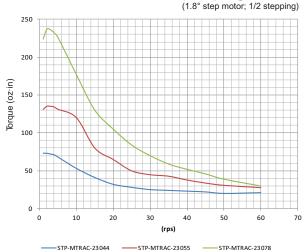




STP-MTR-23079(x) Torque vs Speed (1.8° step motor; 1/2 stepping)



STP-MTRAC-23xxxx Torque vs Speed @ 340VDC bus



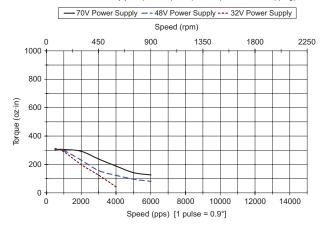
tMNC-24 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Motor Torque vs. Speed Charts (continued)

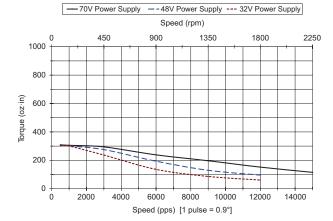
STP-MTR(H)-34xxx(x) NEMA 34 Step Motors

Note: "W" series motors have 5% less running torque than other models

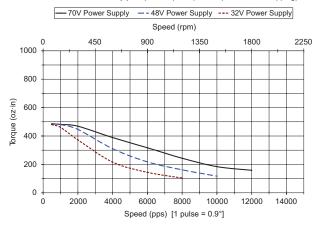




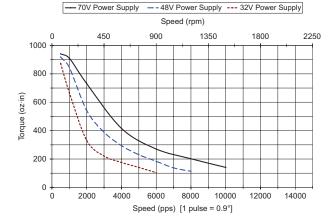
STP-MTRH-34066(x) Torque vs Speed (1.8° motor; 1/2 stepping)



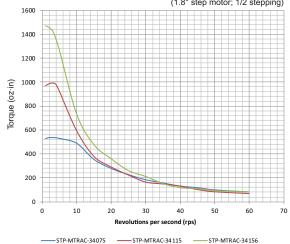
STP-MTRH-34097(x) Torque vs Speed (1.8° step motor; 1/2 stepping)



STP-MTRH-34127(x) Torque vs Speed (1.8° step motor; 1/2 stepping)



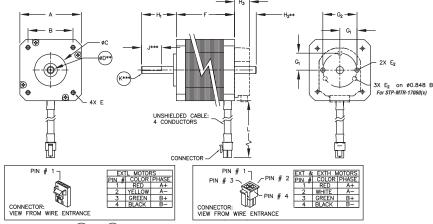
STP-MTRAC-34xxxx Torque vs Speed @ 340VDC bus (1.8° step motor; 1/2 stepping)



tMNC-25 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

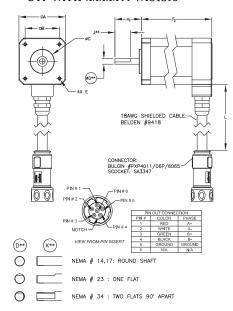
SureStep® Motor Dimensions and Cabling

STP-MTR(x)-xxxx(x) Motors



Note: Drawings and dimensions for STP-MTRD series integrated motor/drives can be found in the integrated motor/drives section of the manual

STP-MTR-xxxxxW Motors



MTRL ATTAL ATTA			SureSte	p Series	Dimensio	ns & Cabl	ing – Con	nectorize	d Bipolar	Stepping	Motors		
MTRL	Dimen	Low Torq	ue Motors			High Torq	ue Motors				Higher Tord	que Motors	i .
B 1.02 [25.9] 1.02 [25.9] 1.02 [25.9] 1.22 [31.0] 1.86 [47.2] 2.74 [69.6] 1.86 [47.2] 2.74 [69.6] C		MTRL	MTRL							MTRH	MTRH	MTRH	STP- MTRH -34127(x)
C Ø 0.87 [22.1] Ø 1.50 [38.1] Ø 2.88 [73.0] Ø 1.50 [38.1] Ø 2.88 [73.0] Ø 1.50 [38.1] Ø 2.88 [73.0] D** Ø 0.20 [5.0] Ø 0.25 [6.4] Ø 0.50 [12.7] Ø 0.25 [6.4] Ø 0.50 [12.7] Ø 0.25 [6.4] Ø 0.50 [12.7] E 0.15 DP 0.15 DP M3 x 0.5 thread on 1.5 [3.8] min depth Ø 0.20 [5.1] through Ø 0.20 [5.1] through<	Α	1.39 [35.3]	1.39 [35.3]		1.67 [42.3]		2.25	2.25 [57.2] 3.39 [86.1]					
D** Ø 0.20 [5.0] Ø 0.25 [6.4] Ø 0.50 [12.77] Ø 0.26 [6.6] Ø 0.20 [5.1] Ø 0.20 [6.1] Ø 0.20 [6.6] Ø 0.20 [6.6]<	В	1.02 [25.9]	[25.9] 1.02 [25.9] 1.22 [31.0]					[47.2]	2.74 [69.6]	1.86 [47.2]		2.74 [69.6]	
E 0.15 DP 0.15 DP M3 x 0.5 thread 0.15 [3.8] min depth Ø 0.20 [5.1] through Ø 0.20 [6.6] through	С	Ø 0.87 [22.1]						[38.1]	Ø 2.88 [73.0]	Ø 1.50 [38.1]		Ø 2.88 [73.0]	
E2 M2.5 x 0.45 thread M2.5 x 0.45 thread <th>D**</th> <th></th> <th></th> <th>Ø 0.20 [5.0]</th> <th></th> <th></th> <th>Ø 0.2</th> <th>5 [6.4]</th> <th>Ø 0.50 [12.7]</th> <th>Ø 0.25 [6.4]</th> <th></th> <th>Ø 0.50 [12.7]</th> <th></th>	D**			Ø 0.20 [5.0]			Ø 0.2	5 [6.4]	Ø 0.50 [12.7]	Ø 0.25 [6.4]		Ø 0.50 [12.7]	
E2 thread M2.5 x 0.45 thread thread 4-40 n/a 4-40 n/a F₁** 1.02 [25.9] 1.34 [34.0] 1.58 [40.1] 1.89 [48.0] 2.34 [59.5] 2.22 [56.4] 3.10 [78.7] 2.64 [67.1] 3.10 [78.7] 2.64 [67.1] 3.82 [97.0] 5.00 [7.0] F₂*** n/a 1.90 [48.3] 2.24 [56.9] 2.67 [67.8] 2.33 [59.1] 3.19 [81.0] 2.64 [67.1] 3.82 [97.0] 5.00 [7.0] G₁ 0.375 0.375 0.375 0.375 0.411 0.906 </th <th>E</th> <th colspan="4"></th> <th></th> <th></th> <th></th> <th></th> <th></th> <th></th> <th></th>	E												
F2** n/a 1.90 [48.3] 2.24 [56.9] 2.67 [67.8] 2.33 [59.1] 3.19 [81.0] 2.64 [67.1] 3.19 [81.0] 2.64 [67.1] 3.82 [97.0] 5.00 [G1 0.375 0.375 0.375 0.375 0.411 0.906	E ₂			M2.5 x 0.	45 thread		4-	40	n/a	4-40		<u> </u>	
G1 0.375 0.375 0.375 0.375 0.411 0.906 0.	F ₁ **	1.02 [25.9]	1.34 [34.0]	1.58 [40.1]	1.89 [48.0]	2.34 [59.5]	2.22 [56.4]	3.10 [78.7]	3.10 [78.7] 2.64 [67.1] 3.10 [78.7] 2.64 [67.		2.64 [67.1]	3.82 [97.0]	5.00 [127.0]
G2 0.75 0.75 0.75 n/a 1.812 </th <th>F₂**</th> <th>n,</th> <th>/a</th> <th colspan="2">1.90 [48.3] 2.24</th> <th>2.67 [67.8]</th> <th>2.33 [59.1]</th> <th>3.19 [81.0]</th> <th>2.64 [67.1]</th> <th>3.19 [81.0]</th> <th>2.64 [67.1]</th> <th>3.82 [97.0]</th> <th>5.00 [127.0]</th>	F ₂ **	n,	/a	1.90 [48.3] 2.24		2.67 [67.8]	2.33 [59.1]	3.19 [81.0]	2.64 [67.1]	3.19 [81.0]	2.64 [67.1]	3.82 [97.0]	5.00 [127.0]
H1 0.60 [15.2] 0.60 [15.2] 0.94 [24.0] 0.81 [20.6] 1.46 [37.1] 0.81 [20.6] 1.46 [37.1] H2*** 0.51 [13.0] 0.51 [13] 0.51 [13] 1.13 [28.7] 0.51 [13] 1.13 [28.7] H3**** 0.40 n/a 0.40 n/a J** n/a 0.59 [15.0] 0.98 [25.0] 0.59 [15.0] 0.98 [25.0] K** n/a 0.23 [5.8] 0.45 [11.4] 0.23 [5.8] 0.45 [11.4] L 12 [305] Conductor (4) #26 AWG (4) #20 AWG (5) #18 AWG (for W motors) (5) #18 AWG (for W motors) Connector TE # 103653-3 PXP4010/06S/6005 (for W motors) PXP4010/06S/6065 (for W motors) PXP4010/06S/6065 (for W motors)	G ₁	0.375	0.375	0.375	0.375	0.411	0.906	0.906	0.906	0.906	0.906	0.906	0.906
H2** 0.51 [13.0] 0.51 [13] 0.51 [13] 1.13 [28.7] 0.51 [13] 1.13 [28.7] H3**** 0.40 n/a 0.40 n/a 0.40 n/a J** n/a 0.59 [15.0] 0.98 [25.0] 0.59 [15.0] 0.98 [25.0] K** n/a 0.23 [5.8] 0.45 [11.4] 0.23 [5.8] 0.45 [11.4] L 12 [305] Conductor (4) #26 AWG (4) #20 AWG (4) #18 AWG (5) #18 AWG (for W motors) (5) #18 AWG (for W motors) Molex # 39-01-3042 PXP4010/06S/6065 (for W motors) PXP4010/06S/6065 (for W motors) Molex # 39-00-0039 Molex # 39-00-0039	G ₂	0.75	0.75	0.75	0.75	n/a	1.812	1.812	1.812	1.812	1.812	1.812	1.812
H ₃ *** 0.40 n/a 0.40 n/a J** n/a 0.59 [15.0] 0.98 [25.0] 0.59 [15.0] 0.98 [25.0] K** n/a 0.23 [5.8] 0.45 [11.4] 0.23 [5.8] 0.45 [11.4] L	Н ₁	0.60 [15.2]	0.60 [15.2]		0.94 [24.0]		0.81	0.81 [20.6] 1.46 [37.1]		0.81 [20.6]	1.46 [37.1]		
J** n/a 0.59 [15.0] 0.98 [25.0] 0.59 [15.0] 0.98 [25.0] K** n/a 0.23 [5.8] 0.45 [11.4] 0.23 [5.8] 0.45 [11.4] L 12 [305] Conductor (4) #26 AWG (4) #20 AWG (4) #18 AWG (for W motors) Connector TE # 103653-3 Molex # 3025-0400 Molex # 39-01-3042 PXP4010/06S/6065 (for W motors) PXP4010/06S/6065 (for W motors) Molex # 33/30-0007 Molex # 39-00-0039		0.51 [13.0]	0.51 [13.0]		0.51 [13]		0.51	[13]	1.13 [28.7]	0.51 [13]		1.13 [28.7]	
K** n/a 0.23 [5.8] 0.45 [11.4] 0.23 [5.8] 0.45 [11.4] L 12 [305] Conductor (4) #26 AWG (4) #20 AWG (4) #18 AWG (for W motors) Connector TE # 103653-3 Molex # 43025-0400 Molex # 39-01-3042 PXP4010/06S/6065 (for W motors) PXP4010/06S/6065 (for W motors) Malex # 43030-0007 Malex # 39-00-0039	H ₃ ***				0.40				n/a	0.40		n/a	
L 12 [305] Conductor (4) #26 AWG (4) #20 AWG (4) #18 AWG (for W motors) Connector TE # 103653-3 Molex # 39-01-3042 Molex # 39-01-3042 PXP4010/06S/6065 (for W motors) PXP4010/06S/6065 (for W motors) Malex # 43030-0007 Malex # 39-00-0039	J**			n/a			0.59	[15.0]	0.98 [25.0]	0.59 [15.0]		0.98 [25.0]	
Conductor (4) #26 AWG (4) #20 AWG (4) #18 AWG (5) #18 AWG (for W motors) (5) #18 AWG (for W motors) Molex # 43025-0400 Molex # 39-01-3042 PXP4010/06S/6065 (for W motors) PXP4010/06S/6066 (for W motors) Moley # 43030-0007 Moley # 39-00-0039				n/a					0.45 [11.4]	0.23 [5.8]		0.45 [11.4]	
Conductor (4) #26 AWG (5) #18 AWG (for W motors) (5) #18 AWG (for W motors) Connector TE # 103653-3 Molex # 43025-0400 Molex # 39-01-3042 PXP4010/06S/6065 (for W motors) PXP4010/06S/6066 (for W motors) Moley # 43030-0007 Moley # 39-00-0039	L			I		(4) #0		[305]			(4) #4	2 4140	
Connector TE # 103653-3 Molex # 43025-0400 Molex # 39-01-3042 PXP4010/06S/6065 (for W motors) PXP4010/06S/6065 (for W motors) Moley # 43030-0007 Moley # 39-00-0039	Conductor	(4) #2	6 AWG			()					()		
Moley # 43030_0007 Moley # 39_00_0039	Connector	TE # 10	03653-3		PX	Molex # 4	3025-0400	nrs)		Molex # 39-01-3042			
Pin TE # 1-104505-3 (LOOSE) Socket: SA3347 (for W motors) Socket: SA3347 (for W motors)	Pin	TE # 1-10450	05-3 (LOOSE)			Molex # 4	3030-0007			Molex # 39-00-0039			

^{*} mm dimensions are for reference purposes only.

tMNC-26 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

^{**} Dimension H₂ applies only to dual-shaft (D) and encoder (E) motors.

Dimension D (shaft diameter) is the same for both front and rear shafts of dual-shaft (D) and encoder (E) motors.

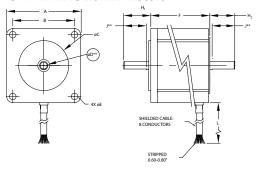
Dimensions J & K do NOT apply to rear shafts of dual-shaft (D) and encoder (E) motors (all rear shafts are round style).

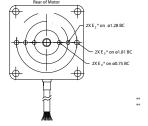
Dimension F₂ applies to IP65 (W) motors only.

^{***} Dimension H3 applies only to "E" models with the encoder pre-mounted.

SureStep® Motor Dimensions and Cabling

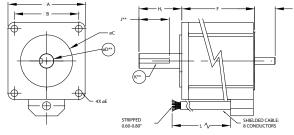
STP-MTRAC-23xxx Motors

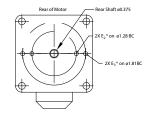


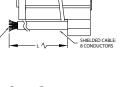




STP-MTRAC-34xxx Motors



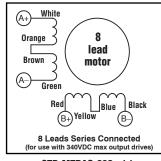




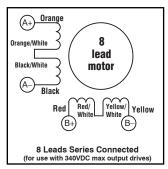


SureSt	ep Series Dir	nensions & C	abling – Higl	h Voltage Bip	olar Steppin	g Motors	
Dimen -sions*			High V High T	oltage orque			
(in [mm]*)	STP-MTRAC -23044(x)	STP-MTRAC -23055(x)	STP-MTRAC -23078(x)	STP-MTRAC -34075(x)	STP-MTRAC -34115(x)	STP-MTRAC -34156(x)	
Α	2.25 [57.15]	2.25 [57.15]	2.25 [57.15]	3.39 [86.1]	3.39 [86.1]	3.39 [86.1]	
В	1.86 [47.24]	1.86 [47.24]	1.86 [47.24]	2.74 [69.6]	2.74 [69.6]	2.87 [72.9]	
С	1.50 [38.1]	1.50 [38.1]	1.50 [38.1]	2.87 [72.9]	2.87 [72.9]	2.87 [72.9]	
D**	0.25 [6.35]	0.25 [6.35]	0.25 [6.35]	0.5 [12.7]	0.5 [12.7]	0.625 [15.9]	
E	0.2 [5.08]	0.2 [5.08]	0.2 [5.08]	0.25 [6.35]	0.25 [6.35]	0.25 [6.35]	
E ₂ ***	2-56 thru	2-56 thru	2-56 thru	2-56 UNC Tap 0.2 Deep	2-56 UNC Tap 0.2 Deep	2-56 UNC Tap 0.2 Deep	
E ₃ ***	4-40 UNC x 0.2 Deep	4-40 UNC x 0.2 Deep	4-40 UNC x 0.2 Deep	4-40 UNC Tap 0.2 Deep	4-40 UNC Tap 0.2 Deep	4-40 UNC Tap 0.2 Deep	
E ₄ ***	2-56 UNC Tap 0.2 Deep	2-56 UNC Tap 0.2 Deep	2-56 UNC Tap 0.2 Deep	-	-	_	
F	1.71 [43.43]	2.16 [54.86]	3.05 [77.47]	2.95 [74.93]	4.52 [114.81]	6.14 [155.96]	
Н ₁	0.81 [20.57]	0.81 [20.57]	0.81 [20.57]	1.25 [31.75]	1.25 [31.75]	1.25 [31.75]	
H ₂ ***	0.63 [16.0]	0.63 [16.0]	0.63 [16.0]	1.12 [28.45]	1.12 [28.45]	1.12 [28.45]	
J	0.60 [15.24]	0.60 [15.24]	0.60 [15.24]	0.87 [22.1]	0.87 [22.1]	0.87 [22.1]	
L	120 [3048]	120 [3048]	120 [3048]	120 [3048]	120 [3048]	120 [3048]	

mm dimensions are for reference purposes only.



STP-MTRAC-230xx(x), 34156(x) Motor Wiring



STP-MTRAC-34075(x), 34115(x) Motor Wiring

1 - 8 0 0 - 6 3 3 - 0 4 0 5

tMNC-27 **Motion Control**

Dimension D (shaft diameter) is the same for both front and rear shafts of NEMA 23 dual-shaft motors. See diagrams for NEMA 34.

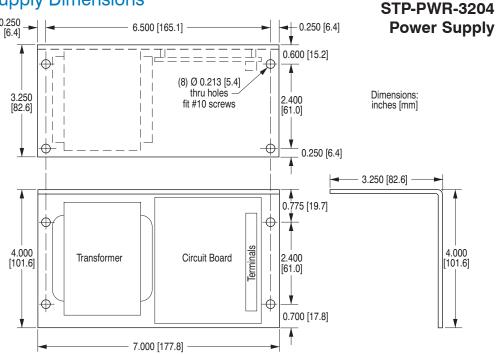
^{*} Dimension applies only to dual-shaft (D) motors.

Surestep Stepping System Power Supplies

SureStep® Power Supplies

Sı	reStep Series Specificat	tions – Stepping System	Power Supplies	
Power Supply	STP-PWR-3204	STP-PWR-4805	STP-PWR-4810	STP-PWR-7005
Price	\$132.00	\$155.00	\$200.00	\$200.00
Input Power (fuse protected *)	1-phase, 120/240 VAC, 50/60 Hz, 150 VA Fuse*: 3A	1-phase, 120/240 VAC, 50/60 Hz, 350 VA Fuse*: 5A	1-phase, 120/240 VAC, 50/60 Hz, 650 VA Fuse*: 8A	1-phase, 120/240 VAC, 50/60 Hz, 500 VA Fuse*: 7A
Input Voltage Range (switch selectable)	120	/240 VAC ±10% (Voltage range switch	ch is set to 240 VAC from factory)	
Inrush Current	120 VAC < 12 A / 240 VAC < 14 A	120 VAC < 20A / 240 VAC < 24A	120 VAC < 40A	/ 240 VAC < 50A
Motor Supply Output (linear unregulated, fuse protected *, and power on LED indicator)	32 VDC @ 4A (fully loaded) 35 VDC @ 1A load 41 VDC @ no load Fuse*: 6A (Electrically isolated from Logic Supply Output)	46.5 VDC @ 5A (fully loaded) 52 VDC @ 1A load 57.5 VDC @ no load Fuse*: 8A	46.5 VDC @ 10A (fully loaded) 50 VDC @ 1A load 57.5 VDC @ no load Fuse*: 15A	70 VDC @ 5A (fully loaded) 79 VDC @ 1A load 86.5 VDC @ no load Fuse*: 8A
Logic Supply Output		5 VDC ±5% @		
(regulated and power on LED indicator)		(Electronically Overlo (Electrically isolated from M	,	
Watt Loss	13W	25W	51W	42W
Storage Temperature Range		-55 to 85 °C [-67	to 185 °F]	
Operating Temperature Range	0 to 50 °C [32 to 12	2 °F] full rated; derate current 1.1% p	er degree above 50°C; 70 °C [15	i8 °F] maximum
Humidity		95% (non-condensing) relative	e humidity maximum	
Cooling Method	1	Natural convection (mount power supp	ly to metal surface if possible)	
Mounting	Mount (on either wide or narrow side with mad	chine screws per dimension diagra	ims
Weight (lb [kg])	6.5 [2.9]	11 [4.9]	18 [8.3]	16 [7.2]
Connections		Screw Termi	nals	
Agency Approvals		UL (file # E181899), CSA, CE	
* Fuses to be replaced by qualified ser	vice personnel only. Use (1-1/4 x	1/4 in) ceramic fast-acting fuses	(Edison type ABC from Auton	nationDirect, or equivalent).

Power Supply Dimensions

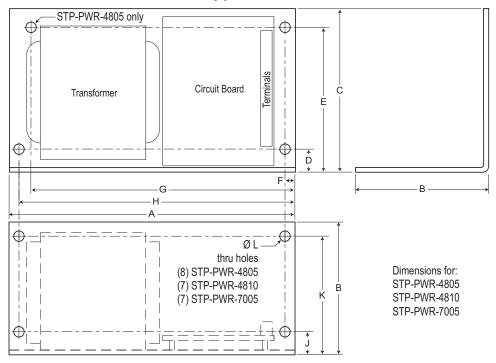


tMNC-28 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Surestep Stepping System Power Supplies

SureStep® Power Supply Dimensions (continued)

STP-PWR-4805, -4810, -7005 Power Supplies



	SureStep Series Dimensions – 48V & 70V Power Supplies												
Power Supply					Dimen	sions* (in	[mm]*)					Mtg	
Part Number	Α	В	С	D	Е	F	G	Н	J	К	L	Screw	
STP-PWR-4805	8.10 [205.7]	3.88 [98.6]	5.00 [127.0]	0.87 [22.1]	4.67 [118.6]	0.25 [6.4]	7.15 [181.6]	7.75 [196.9]	0.50 [12.7]	3.53 [89.7]	0.200 [5.1]	#10	
STP-PWR-4810 STP-PWR-7005	9.00 [228.6]	4.62 [117.3]	5.62 [142.7]	1.56 [39.6]	4.06 [103.1]	0.35 [8.9]	n/a	8.59 [218.2]	0.50 [12.7]	4.27 [108.5]	9/32 [7.1]	1/4	
* mm dimensions ar	e for referen	ice purposes	only.										

tMNC-29 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Integrated Motors System

General integrated motor/drive features

- DC power supply required (12-48 VDC or 12-70 VDC)
- Pulse/Direction or CW Pulse/CCW Pulse
- Digital input filtering
- "E" models include an encoder
- Three optically isolated digital inputs, 5 to 24 volts
- Step input signal smoothing (microstep emulation), performs high resolution stepping by synthesizing coarse steps into fine microsteps
- Dynamic smoothing, software-configurable filtering for use in removing spectral components from command sequence, reduces jerk, limiting excitation of system resonance
- Anti-resonance (electronic damping): raises the system-damping ratio to eliminate midrange instability and allow stable operation throughout the speed range of the motor
- Idle current reduction range of 0-90% of running current after a delay selectable in milliseconds (Standard models = 50/90%, DIP switch selectable)
- Configurable hardware digital noise filter, software noise filter
- Non-volatile storage, configurations are saved in FLASH memory on-board the DSP
- Dynamic current control, software configurable for running current, accel current, idle current, to make motion smoother and the motor run cooler

Standard integrated motor/drive features (STP-MTRD-x)

- "E" models have an externally wireable encoder which can provide feedback to an external controller
- Configurable via DIP switches
- Available torque from 68 to 210 oz-in

Advanced integrated motor/drive features (STP-MTRD-xR)

- Step and Direction, CW/CCW, and AB Quadrature/Encoder following
- · Velocity (Oscillator) and position mode
- Control via streaming SCL commands
- RS-485 ASCII (2- or 4-wire) communications
- On "E" models, the internal encoder provides improved position and speed control
- Four "Variable I/O" points, 5 to 24 volts (NEMA 24 models)
- · Analog input for speed and position, 0 to 5 VDC
- Configurable via SureMotion Pro software
- Available torque from 54 to 340 oz-in

SureStep Series Part Numbers Standard Integrated Motor/Drives					
Integrated Motor/Drive		Price			
STP-MTRD-17038	17	\$102.00			
STP-MTRD-17038E	17	\$177.00			
STP-MTRD-23042	23	\$156.00			
STP-MTRD-23042E	23	\$232.00			
STP-MTRD-23065	23	\$164.00			
STP-MTRD-23065E	23	\$238.00			

Note: Standard Integrated motor/drives with an "E" have an external encoder that can be wired to an external controller.



Standard NEMA 17 and 23 motor/drives



Advanced NEMA 17, 23, and 24 motor/drives

SureStep Series Part Numbers Advanced Integrated Motor/Drives					
Integrated Motor/Drive	NEMA Size	Price			
STP-MTRD-17030R	17	\$239.00			
STP-MTRD-17030RE	17	\$308.00			
STP-MTRD-17038R	17	\$252.00			
STP-MTRD-17038RE	17	\$336.00			
STP-MTRD-23042R	23	\$259.00			
STP-MTRD-23042RE	23	\$358.00			
STP-MTRD-23065R	23	\$269.00			
STP-MTRD-23065RE	23	\$365.00			
STP-MTRD-24075RV	24	\$365.00			
STP-MTRD-24075RVE	24	\$432.00			

Note: Advanced Integrated motor/drives with an "E" have an internal encoder used for stall prevention (cannot be wired to an external PLC or controller).

tMNC-30 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Standard Integrated Motor/Drives Specifications



			SureStep Integrated Series	Specifications – Standard			
Microstepping Drive/Motor			STP-MTRD-17038 STP-MTRD-17038E	STP-MTRD-23042 STP-MTRD-23042E	STP-MTRD-23065 STP-MTRD-23065E		
Input Volt (external		uired)	12-48 VDC	12-70 VDC	12-70 VDC		
Logic Sup			+4.8 - 5 volts at 50mA maximum				
Configura	tion Me	thod	DIP switches				
Current C	ontrolle	r	Digital MOSFET, PWM @ 16kHz				
Encoder F	eedbac	k		ly. External encoder must be wired to external fe			
Encoder S	Specs ("	'E" models only)	1000 ppr, Line Driver, Supply Voltage (Typ: 5V, Max: 5.5 V, Min: 4.5 V). Detailed specs, other encoder options, and PLC compatibility are listed in Appendix A of the SureStep user manual.				
Motor/Dri	ve Prote	ection	Sh	nort circuit, over-voltage, under-voltage, over-ter	mp		
	Step/Pl	ulse	5-24 VDC nominal (range 4-30VDC); (5mA @ 4V; 15 mA @ 30V); Optically isolated. Minimum pulse width = 3µs (at 2 MHz), 0.25µs (at 150kHZ), Maximum pulse frequency = 150kHz or 2MHz (switch selectable), Function = Step Input, Limit CW				
Input Signals	Direction	on	5-24 VDC nominal (range 4-30VDC); (5mA @ 4V; 15 mA @ 30V); Optically isolated. Minimum pulse width = 3µs (at 2 MHz), 0.25µs (at 150kHZ), Maximum pulse frequency = 150kHz or 2MHz (switch selectable), Function = Direction Input, Limit CCW				
	Enable		5-24 VDC nominal (range 4-30VDC); (5mA @ 4V; 15 mA @ 30V); Optically isolated. Minimum pulse width = 3µs (at 2 MHz), 0.25µs (at 150kHZ), Maximum pulse frequency = 150kHz or 2MHz (switch selectable), Function = Enable Input				
Output Si	gnal		30 VDC / 100mA max, photodarlington, voltage drop = 1.2V max at 100mA Function = Alarm Output				
Jumper Selectabl		Step Pulse Type	Step and Direction: Step signal = step/pulse; Direction signal = direction. Step CW & CCW: Step signal = CW step; Direction signal = CCW step.				
Functions	0. 5.		Selectable 150 kHz or 2MHz				
	Current	t Reduction	This is the percentage of full current that the motor will use when the shaft is rotating. 100%, 90%, 70%, and 50% current selections.				
	Idle Current Reduction		Reduce power consumption and heat generation by limiting motor idle current to 90% or 50% of running current. (Holding torque is reduced by the same %.)				
Features	Microstep Resolution		200-25000 (dip switch selectable)				
	Self Test		Automatically rotate the motor back and forth 2 1/2 turns in each direction in order to confirm that the motor is operational.				
	Load Inertia		Anti-resonance and damping feature improves motor performance. Set motor and load inertia range to 0–4x or 5–10x.				
Connecto	rs	Control	Housing: Tyco 4-643498-1 Cover: Tyco 1-643075-1 Connector part number: Weidmuller 1610200000, included in STP-CON-3				
Encoder Encoder		Encoder	Two 5 pin inserts (Molex# 14-60-0058), one housing Molex# 15-04-5104				
Drive Cooling Method		ethod	Natural convection (mount to suitable heat sink)				
Status LEDs			One red/green				
Mounting			Four M3 screws	Four #6	screws		

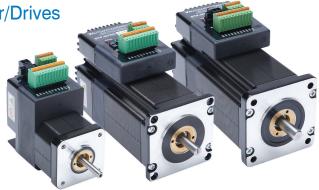
tMNC-31 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Standard Integrated Motor/Drives Specifications

SureStep Integrated Series Specifications – Standard						
Integrated Stepping Motor/Drives		STP-MTRD-17038 STP-MTRD-23042 STP-MTRD-17038E STP-MTRD-23042E		STP-MTRD-23065 STP-MTRD-23065E		
NEMA Frame Size		NEMA 17	NEMA 23	NEMA 23		
	(lb·in)	4.25	7.8125	13.125		
Maximum Holding Torque	(oz∙in)	68	125	210		
Torquo	(N·m)	0.480189	0.8827	1.482936		
Rotor Inertia	(oz∙in ²)	0.448	1.420	2.515		
	(kg·cm ²)	0.082	0.260	0.460		
Insulation Class		Class B (130°C)				
Basic Step Angle		1.8 degrees				
Shaft Runout (in)		0.03	0.05			
Max Shaft Radial Play @	1lb load	0.02				
Perpendicularity (mm)		0.08				
Concentricity (mm)		0.05				
* Maximum Radial Load	l (lb [kg])	6.7	13.9			
* Maximum Thrust Load	(lb [kg])	34	34 63			
Storage Temperature Ra	nge	0-40°C (32-104°F)				
Operating Temperature	Range	0-85°C				
Operating Humidity Ran	ge	90% max, non-condensing				
Product Material		Aluminum, steel, plastic, FR4, etc				
Environmental Rating		IP40				
Weight (oz [g])		14.7 [417]	30 [850] 42 [1200]			
Agency Approvals		CE				
Design Tips		Allow sufficient time to accelerate the load and size the step motor with a 100% torque safety factor. DO NOT disassemble step motors because motor performance will be reduced and the warranty will be voided. DO NOT connect or disconnect the step motor during operation. Mount the motor to a surface with good thermal conductivity, such as steel or aluminum, to allow heat dissipation. Use a flexible coupling with "clamp-on" connections to both the motor shaft and the load shaft to prevent radial and thrust loading on bearings from minor misalignment and to prevent loosening due to vibration.				

tMNC-32 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Advanced Integrated Motor/Drives



	SureStep Integrated Series Specifications – Advanced							
Inte	grated M	otor/Drive	STP-MTRD-17030R STP-MTRD-17030RE	STP-MTRD-17038R STP-MTRD-17038RE	STP-MTRD-23042R STP-MTRD-23042RE	STP-MTRD-23065R STP-MTRD-23065RE		
Input Voltage (external p/s required)			12-48 VDC 12-70 VDC					
	figuration		SureMotion Pro software (SM-PRO: free download)					
Sup	ply Outpu	ıt		+4.8 - 5 volts @	50mA maximum			
Cur	rent Conti	oller	Dual H-Bridge, 4 Quadrar	nt, 4 state PWM @ 16kHz	Dual H-Bridge, 4 Quadra	nt, 4 state PWM @ 20kHz		
Enc	oder Feed	lback	"E" models only. Er	ncoder is internal and provides posi	tion verification and stall prevention	n control by default.		
Mo	tor/Drive I	Protection		Short circuit, over-voltage,	under-voltage, over-temp			
	Step/Puls	se		isolated. Minimum pulse width = 25 draw = Function = Step Input, Jog CW, Lim	12mA nit CW, Start/Stop, General Purpose	}		
Input Signals	Direction	,	5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, m draw = 12mA Function = Direction Input, Jog CCW, Limit CCW, General Purpose					
Input	Enable		5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA Function = Enable Input, Reset Input, Change Speed, General Purpose					
	Analog		0-5 VDC nominal (AIN referenced to GND). Input impedance: 30K ohms minimum, resolution = 12 bits					
	rinarog		Function = analog control modes and general purpose analog usage; programmable for signal range, offset, dead band, and filtering 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz.					
Out	Output Signal Functions = Brake Output, Alarm Output, Motion Output, Tach Output, General Purpose				,			
Con	nmunicati	ion Interface	RS-485 ASCII					
Nor	n-volatile	Memory Storage	Configurations are saved in FLASH memory on-board the DSP					
	Current F	Reduction		Selectable in SureN	Notion Pro software			
es.	Idle Curre	ent Reduction	Reduction range of 0–90% of running current after delay selectable in ms					
Features	Microste	p Resolution	Software selectable from 200 to 51200 steps/rev in increments of 2 steps/rev					
Fe	Modes of	f Operation	Pulse (step) & direction, CW/CCW, A/B quadrature, velocity (oscillator), SCL streaming commands					
	Self Test		Checks internal and external power supply voltages. Diagnoses open motor phases and motor resistance changes > 40%					
		DC Power	2-position screw terminal: Weidmuller 1615780000					
Con	nectors	1/0	11-position spring cage: Phoenix 1881419					
		Comm	5-position spring cage: Phoenix 1881354					
Drive Cooling Method Natural convection (mount to suitable heat sink)								
Sta	Status LEDs 1 red, 1 green							
Мо	lounting Four M3 screws Four #6 screws					S screws		

tMNC-33 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Advanced Integrated Motor/Drives

			SureStep Integrated Series Specifications – Advanced Variable I/O			
Inte	egrated Mo	otor/Drive	STP-MTRD-24075RV / STP-MTRD-24075RVE			
	ut Voltage ternal p/s		12-70 VDC			
	ofiguration		SureMotion Pro software (SM-PRO: free download)			
Supply Output		t	+4.8 - 5 volts @ 50mA maximum			
Current Controller		oller	Dual H-Bridge, 4 Quadrant, 4 state PWM @ 20kHz			
Enc	oder Feed	lback	"E" models only. Encoder is internal and provides position verification and stall prevention control by default.			
Мо	tor/Drive F	Protection	Short circuit, over-voltage, under-voltage, over-temp			
	1/0 1 (04a	nn/Bulga)	INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA, Function = Step Input, Jog CW, Enable Input, Start/Stop, General Purpose			
	I/O 1 (Ste	:p/Puise)	OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Brake Output, Fault Output, Motion Output, Tach Output, General Purpose			
	I/O 2 (Dir	raction)	INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA, Function = Direction Input, Jog CCW, Alarm Reset Input, General Purpose			
e 1/0	ווט 2 (טוו	ection)	OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Brake Output, Fault Output, Motion Output, Tach Output, General Purpose			
Variable I/O			INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3MHz). Maximum pulse frequency = 3MHz, max current draw =			
🛎	1/0 3		12mA, Function = Limit CW Input, Enable Input, Change Speed Input, General Purpose OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Brake Output, Fault Output,			
			Motion Output, Tach Output, General Purpose			
	I/O 4		INPUT: 5-24 VDC nominal. Optically isolated. Minimum pulse width = 250ns (at 3 MHz). Maximum pulse frequency = 3MHz, max current draw = 12mA, Function = Limit CCW Input, Alarm Reset Input, General Purpose			
			OUTPUT: 30VDC, 40mA maximum. Optically isolated, open collector. Maximum pulse frequency 10kHz. Functions = Brake Output, Fault Output, Tach Output, General Purpose			
Ana	alog		0-5 VDC nominal (AIN referenced to GND). Input impedance: 30K ohms minimum, resolution = 12 bits, Function = analog control modes and general purpose analog usage; programmable for signal range, offset, dead band, and filtering			
Coi	nmunicati	on Interface	RS-485 ASCII (2- or 4-wire)			
	n-volatile l rage	Memory	Configurations are saved in FLASH memory on-board the DSP			
- 10	Current R	Reduction	Selectable in SureMotion Pro software			
SĐ,	Idle Curre	ent Reduction	Reduction range of 0–90% of running current after delay selectable in ms			
Features	Microste	Resolution .	Software selectable from 200 to 51200 steps/rev in increments of 2 steps/rev			
Fe	Modes of	Operation	Pulse (step) & direction, CW/CCW, A/B quadrature, velocity (oscillator), SCL streaming commands			
	Self Test		Checks internal and external power supply voltages. Diagnoses open motor phases and motor resistance changes > 40%			
		DC Power	2-position screw terminal: Weidmuller 1615780000			
Coi	nnectors	1/0	11-position spring cage: Phoenix 1881419			
		Comm	5-position spring cage: Phoenix 1881354			
Dri	ve Cooling	Method	Natural convection (mount to suitable heat sink)			
	Status LEDs		1 red, 1 green			
Мо	unting		Four #6 screws			

tMNC-34 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Advanced Integrated Motor/Drives

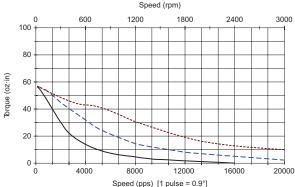
SureStep Integrated Series Specifications – Advanced						
Integrated Motor/Drive		STP-MTRD-17030R STP-MTRD-17030RE	STP-MTRD-17038R STP-MTRD-17038RE	STP-MTRD-23042R STP-MTRD-23042RE	STP-MTRD-23065R STP-MTRD-23065RE	STP-MTRD-24075RV STP-MTRD-24075RVE
NEMA Frame Size		NEMA 17	NEMA 17	NEMA 23	NEMA 23	NEMA 24
	(lb·in)	3.375	4.25	7.8125	13.125	21.25
* Maximum Holding Torque	(oz∙in)	54	68	125	210	340
Torquo	(N·m)	0.381326	0.480189	0.8827	1.482936	2.400944
Rotor Inertia	(oz·in²)	0.310	0.448	1.420	2.515	4.900
	(kg·cm ²)	0.057	0.082	0.260	0.460	0.897
Insulation Class				Class B (130°C)		
Basic Step Angle				1.8 degrees		
Shaft Runout (in)		0.0	03		0.05	
Max Shaft Radial Play (load	@ 1lb	0.02				
Perpendicularity (mm)		0.08				
Concentricity (mm)		0.05				
* Maximum Radial Loa (lb [kg])		6.7				
* Maximum Thrust Load (lb [kg])	d	34 63				
Storage Temperature Ra	ange	0-40°C (32-104°F)				
Operating Temperature	Range	0-85°C 0-70°C				0-70°C
Operating Humidity Ran	nge 💮	90% max, non-condensing				
Product Material		Aluminum, steel, plastic, FR4, etc.				
Environmental Rating		IP40				
Weight (oz [g])		12.7 [360]	15.6 [441]	30 [850]	42 [1191]	56 [1580]
Agency Approvals		CE*				
Design Tips		llow sufficient time to accelerate the load and size the step motor with a 100% torque safety factor. O NOT disassemble step motors because motor performance will be reduced and the warranty will be voided. O NOT connect or disconnect the step motor during operation. lount the motor to a surface with good thermal conductivity, such as steel or aluminum, to allow heat dissipation. se a flexible coupling with "clamp-on" connections to both the motor shaft and the load shaft to prevent radial and thrust loading on bearings om minor misalignment and to prevent loosening due to vibration.				
For NEMA 24 motors, an EMI filter (RES10F03) is needed on the power supply for CE compliance.						

tMNC-35 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Integrated Motor/Drives Motor Torque vs. Speed

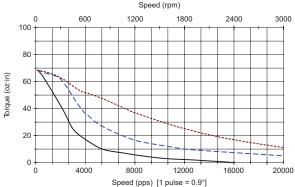




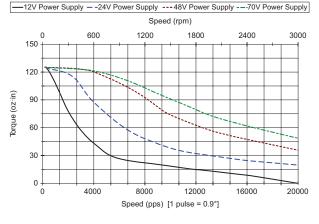


STP-MTRD-17038 Torque vs Speed (1.8° step motor; 1/2 stepping)

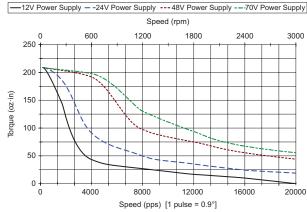
-- 12V Power Supply --- 24V Power Supply --- 48V Power Supply



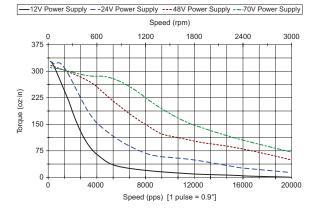
STP-MTRD-23042 Torque vs Speed (1.8° step motor; 1/2 stepping)



STP-MTRD-23065 Torque vs Speed (1.8° step motor; 1/2 stepping)



$\textbf{STP-MTRD-24075} \ \text{Torque vs Speed (1.8}^{\circ} \ \text{step motor; 1/2 stepping)}$

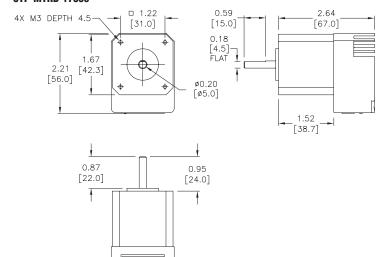


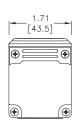
tMNC-36 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Standard Integrated Motor/Drives Dimensions

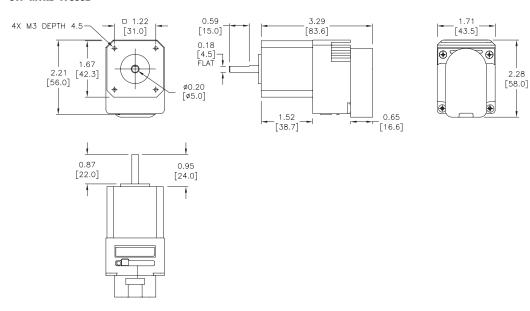
Dimensions = in [mm]

STP-MTRD-17038





STP-MTRD-17038E

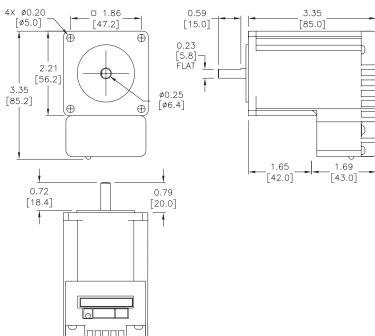


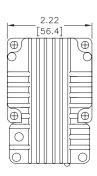
tMNC-37 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Standard Integrated Motor/Drives Dimensions, continued

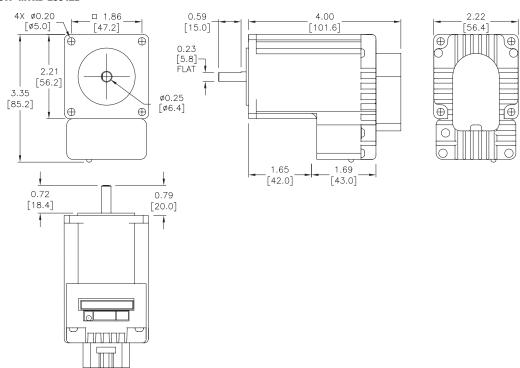
Dimensions = in [mm]

STP-MTRD-23042





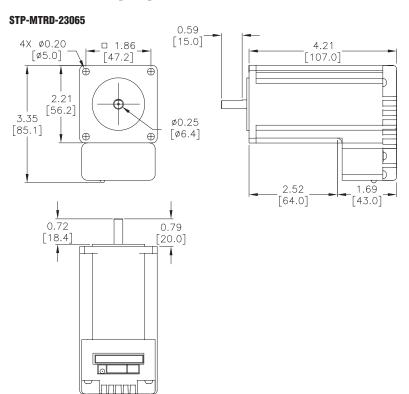
STP-MTRD-23042E

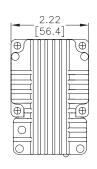


tMNC-38 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

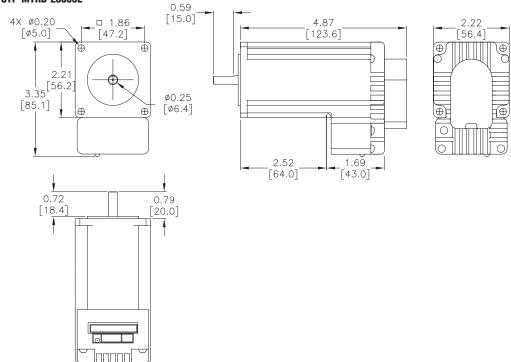
SureStep® Standard Integrated Motor/Drives Dimensions, continued

Dimensions = in [mm]







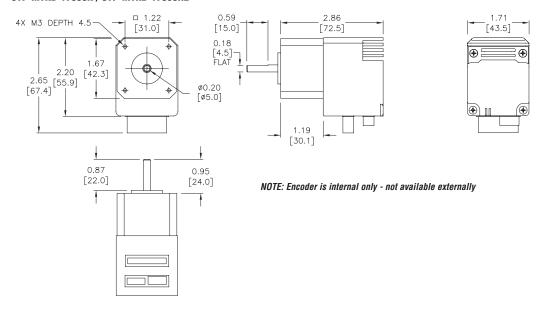


tMNC-39 Motion Control

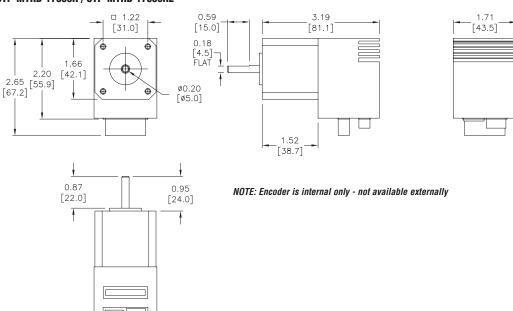
SureStep® Advanced Integrated Motor/Drives Dimensions

Dimensions = in [mm]

STP-MTRD-17030R / STP-MTRD-17030RE



STP-MTRD-17038R / STP-MTRD-17038RE

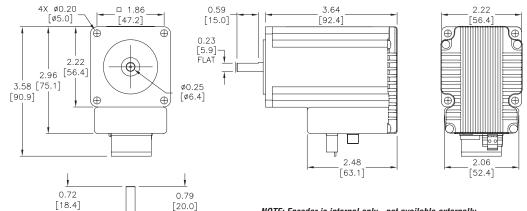


tMNC-40 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Advanced Integrated Motor/Drives Dimensions, continued

Dimensions = in [mm]

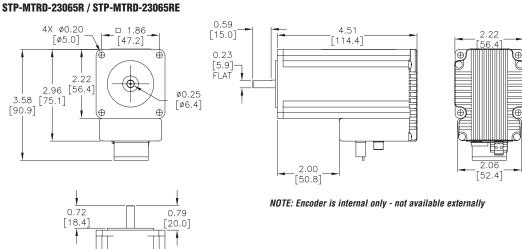
STP-MTRD-23042R / STP-MTRD-23042RE



NOTE: Encoder is internal only - not available externally

uninininu**t**

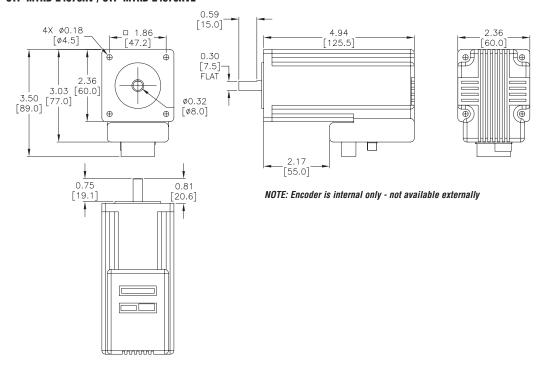
كاستشتنسك



tMNC-41 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep[®] Advanced Integrated Motor/Drives Dimensions, continued *Dimensions = in [mm]*

STP-MTRD-24075RV / STP-MTRD-24075RVE



tMNC-42 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Microstepping Drives Accessories

Braking Accessories

As a load rapidly decelerates from a high speed, much of the kinetic energy of that load is transferred back to the motor. This energy is then pushed back to the drive and power supply, resulting in increased system voltage. If there is enough overhauling load on the motor, the DC voltage will go above the drive and/or power supply limits. In general, the more torque the motor is capable of producing then the more energy it can push back into the drive.

When using a regulated/switching power supply, this can trip the overvoltage protection of the power supply or drive, and cause it to shut down.

To solve this problem, AutomationDirect offers a regeneration clamp and a braking resistor as optional accessories. The regen clamp has a built-in 50W braking resistor. For additional braking power (larger overhauling loads), an optional 100W braking resistor is also available with the STP-DRVA-RC-050. The STP-DRVA-RC-050A does not have the ability to use an external resistor.



Regeneration Clamp STP-DRVA-RC-050



Braking Resistor

Regeneration Clamp Features

Common Features

- Built-in 50W power resistor for more continuous current handling
- · Mounted on a heat sink
- Voltage range: 24-80 VDC; no user adjustments required
- Power: 50W continuous; 800W peak
- Indicators (LED):

Green = power supply voltage is present Red = clamp is operating (usually when stepper is decelerating)

 Protection: The external power supply is internally connected to an "Input Diode" in the regen clamp that protects the power supply from high regeneration voltages. This diode protects the system from connecting the power supply in reverse. If the clamp circuit fails, the diode will continue to protect the power supply from over-voltage.

STP-DRVA-RC-050 Features

- External 100W resistor available
- Multiple drives in parallel up to 20A total output current
- Non-removable terminal blocks
- Uses 12-18 AWG wires for connections

STP-DRVA-RC-050A Features

- Three drive connections, 7A max per channel, 15A total output current
- Removable terminal blocks (replacement kit STP-CON-4)
- Uses 18-20 AWG wire for connections

SureStep Damper

A step motor inertia damper can smooth out steps in a typical step motor resulting in a quieter and smoother motion when rotating between steps. Reducing the resonance and possible micro oscillations when moving from step to step is the main purpose of a "hockey puck" style damper, but it can also be used as a hand wheel to directly rotate the position of the rotor when power is removed from the motor. The damper is a properly sized machined piece of aluminum encased in plastic. It is sized and weighted for general damping of the respective frame size motor.



Regeneration Clamp STP-DRVA-RC-050A

Sure Step Series Specifications – Microstepping Drives Optional Accessories					
Part Number	Price	Description			
STP-DRVA-RC-050*	\$94.00	Regen Clamp: 50W, for DC input stepper and servo drives, non-enclosed, optional 100W external resistor			
STP-DRVA-RC-050A*	\$55.00	Regen Clamp: 50W, for DC input stepper and servo drives, enclosed			
STP-DRVA-BR-100	\$68.00	Braking Resistor: use with STP-DRVA-RC-050 regen clamp; 100W, 10Ω			
STP-MTRA-17DMP	\$13.50	SureStep damper, metal body. For use with NEMA 17 stepper motors with 5mm shafts. Mounting set screw included.			
STP-MTRA-23DMP	\$31.00	SureStep damper, metal body. For use with NEMA 23 stepper motors with 1/4 inch shafts. Mounting set screw included.			
* Do not use the regeneration clamp in an atmosphere containing corrosive gases.					



Damper

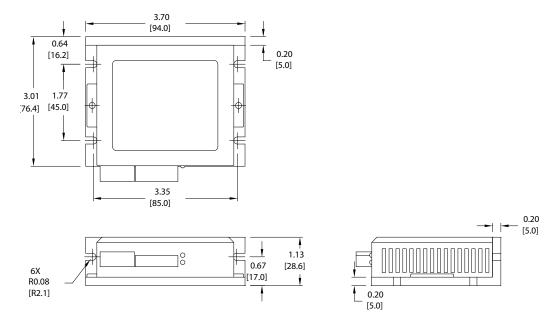
tMNC-43 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Microstepping Drives Accessories

Dimensions = in [mm]

STP-DRVA-BR-100 5.87 [149.1] 2X R0.16 5.46 [R4.0] STP-DRVA-RC-050 [138.7] 2.50 4X Ø0.12 1.50 [63.5] [Ø3.0] [38.1] 0.75 [19.1] 000000 22.00 [558.8] 0.13 4.00 3.75 [3.3] [101.6] [95.3] 0.75 [19.0] 3.00 3.69 0.16 [76.2] [93.7] ~4-40 UNC [4.0] 0.24 3X Ø0.12 [6.1] [Ø3.0] 2.21 [56.2] 1.50 1.17 1.25 [38.1] [29.7] [31,.8] 1.20 [30.6] [22.1]

STP-DRVA-RC-050A



tMNC-44 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Microstepping Drives Accessories

USB to RS-485 Adapter

The STP-USB485-4W is a USB to RS-232/RS-485 converter that can be used in 2-wire or 4-wire serial networks. Serial communication can be wired up via the 9-pin D-sub connector or through the 6-screw terminals.

The STP-USB485-4W can be set for several different configurations. These modes are set up by the 4 DIP switches on the outside of the case (RS-232/RS-485, full/half duplex) and by the 7 jumpers located inside the case (termination/bias resistors).

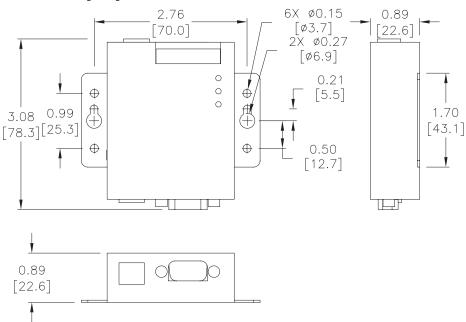
SureStep Advanced Drives communicate via RS-232 (for control and for configuration via SureMotion Pro).

The Advanced Integrated motor/drives use RS-485. While the Advanced Integrated motor/drives can be wired for either 2- or 4-wire networks, 4-wire is require for use with SureMotion Pro due to the Firmware Download utility and the Status Monitor Screen.

Depending on the host controller's RS-485 implementation, either 2- or 4-wire RS-485 can be used for control. All RS-485 PLCs that have 2-wire capability (Productivity, BRX, Click, DirectLogic, etc.) can control the Advanced Integrated steppers.

0 11	
SureStep PC	Adapter - STP-USB485-4W
Price	\$104.00
Communications	2-wire RS-232 2- or 4-wire RS-485
Configure With	Internal jumpers and external DIP switches
Compatible Cables	STP-232RJ11-CBL STP-485DB9-CBL-2

Dimensions = in [mm]



tMNC-45 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Stepping System Encoders

Replacement Encoders

The STP-MTRA-ENC1 is a replacement for the encoder that comes standard with the STP-MTRD-17038E, STP-MTRD-23042E, and STP-MTRD-23065E integrated motor/drives. Note that the encoder included with (E) model advanced integrated motor/drives is internal and cannot be replaced.

The STP-MTRA-ENC9 is a replacement for the encoder that comes standard with the STP-MTR(x)-xxxxE stand alone step motors.

Installation tool and mounting hardware is included with all replacement encoders. For more information and details on how to wire the replacement encoders, please see the SureStep User Manual.

Optional Encoders

Optional encoders can be purchased separately for standard integrated motor/drives and standalone dual-shaft motors in all NEMA 14, 17, and 23 sizes, and also for STP-MTRAC-34xxxD motors (currently not available for STP-MTRx-34xxxD motors). All (D) model (dual-shaft) step motors come with pre-drilled holes in the rear end cap for easy encoder mounting. Pre-installed encoders on standalone dual-shaft motors and standard integrated motor/drives can be retrofitted with an appropriate optional encoder if desired. Please see the chart on the following page for encoder compatibility.

Features:

- Fixed resolutions include 400ppr or 1000ppr
- Configurable models have up to 4096ppr (default = 400ppr)
- · Choose line driver or push-pull (totem) output signals



STP-MTRA-ENC2



STP-MTRA-ENC9



STP-MTRA-ENC11

		Sure Step Series Specifications – Encoders
Part Number	Price	Description
STP-MTRA-ENC1	\$68.00	SureStep incremental (quadrature) modular encoder, 5VDC, line driver (differential) output, 1000 ppr. For use with SureStep stepper motors with 5mm rear shaft. Installation tool and mounting hardware included.
STP-MTRA-ENC2	\$58.00	SureStep incremental (quadrature) modular encoder, 5VDC, Push-pull (totem) output, 1000 ppr. For use with SureStep stepper motors with 5mm rear shaft. Installation tool and mounting hardware included.
STP-MTRA-ENC3	\$59.00	SureStep incremental (quadrature) modular encoder, 5VDC, line driver (differential) output, 400 ppr. For use with SureStep stepper motors with 5mm rear shaft. Installation tool and mounting hardware included.
STP-MTRA-ENC4	\$49.50	SureStep incremental (quadrature) modular encoder, 5VDC, Push-pull (totem) output, 400 ppr. For use with SureStep stepper motors with 5mm rear shaft. Installation tool and mounting hardware included.
STP-MTRA-ENC5	\$68.00	SureStep incremental (quadrature) modular encoder, 5VDC, line driver (differential) output, 1000 ppr. For use with SureStep stepper motors with 1/4 inch rear shaft. Installation tool and mounting hardware included.
STP-MTRA-ENC6	\$58.00	SureStep incremental (quadrature) modular encoder, 5VDC, Push-pull (totem) output, 1000 ppr. For use with SureStep stepper motors with 1/4 inch rear shaft. Installation tool and mounting hardware included.
STP-MTRA-ENC7	\$59.00	SureStep incremental (quadrature) modular encoder, 5VDC, line driver (differential) output, 400 ppr. For use with SureStep stepper motors with 1/4 inch rear shaft. Installation tool and mounting hardware included.
STP-MTRA-ENC8	\$49.50	SureStep incremental (quadrature) modular encoder, 5VDC, Push-pull (totem) output, 400 ppr. For use with SureStep stepper motors with 1/4 inch rear shaft. Installation tool and mounting hardware included.
STP-MTRA-ENC9*	\$57.00	SureStep incremental (quadrature) modular encoder, 5VDC, line driver (differential) output, configurable up to 4096 ppr. For use with NEMA 14, 17, and 23 SureStep dual-shaft motors. Installation tool and mounting hardware included.
STP-MTRA-ENC10*	\$43.50	SureStep incremental (quadrature) modular encoder, 5VDC, Push-pull (totem) output, configurable up to 4096 ppr. For use with NEMA 14, 17, and 23 SureStep dual-shaft motors. Installation tool and mounting hardware included.
STP-MTRA-ENC11	\$66.00	SureStep incremental (quadrature) modular encoder, 5 VDC, line driver (differential) output, 1000 ppr. For use with SureStep stepper motors with 3/8in rear shaft. Installation hardware included. Requires STP-CBL-EAxx cable.
STP-MTRA-ENC12	\$56.00	SureStep incremental (quadrature) modular encoder, 5 VDC, push-pull (totem) output, 1000 ppr. For use with SureStep step- per motors with 3/8in rear shaft. Installation hardware included. Requires STP-CBL-EDxx cable.
STP-MTRA-ENC13	\$57.00	SureStep incremental (quadrature) modular encoder, 5 VDC, line driver (differential) output, 400 ppr. For use with SureStep stepper motors with 3/8in rear shaft. Installation hardware included. Requires STP-CBL-EAxx cable.
STP-MTRA-ENC14	\$48.00	SureStep incremental (quadrature) modular encoder, 5 VDC, push-pull (totem) output, 400 ppr. For use with SureStep stepper motors with 3/8in rear shaft. Installation hardware included. Requires STP-CBL-EDxx cable.

^{*} ENC9 and ENC10 encoders come with multiple adapter sleeves to accomodate different motor shaft diameters. See the dimensional drawing for details.

tMNC-46 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Stepping System Encoders

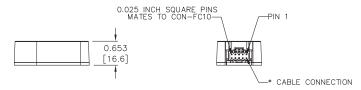
Part Number	PPR	Bore Diameter	Output Type	Encoder Cable	PLC Compatibility	Motor Compatibility	
STP-MTRA-ENC1	4000		Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0-1xDxE-D*		
STP-MTRA-ENC2	- 1000	- 5mm	Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0-1xDxE-D*	STP-MTRx-14xxxD STP-MTRx-14xxxE STP-MTRx-17xxxD STP-MTRx-17xxxE Standard STP-MTRD-xxxxxE	
STP-MTRA-ENC3	400	minc	Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0-1xDxE-D*		
STP-MTRA-ENC4	400		Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0-1xDxE-D*		
STP-MTRA-ENC5	1000		Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0-1xDxE-D*		
STP-MTRA-ENC6	1000	- 0.25 inch -	Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0-1xDxE-D*	STP-MTRx-23xxxD STP-MTRx-23xxxE	
STP-MTRA-ENC7	400	0.25 IIIGII	Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0-1xDxE-D*	STP-MTRAC-23xxxD	
STP-MTRA-ENC8	400		Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0-1xDxE-D*		
STP-MTRA-ENC9	48 to 4096 configurable**	2mm - 8mm	Line Driver	STP-CBL-EBxx (signal)	P2-HSI, P3-HSI, BRX*, CLICK C0-1xDxE-D*	STP-MTRx-14xxxD STP-MTRx-14xxxE STP-MTRx-17xxxD STP-MTRx-17xxxE	
STP-MTRA-ENC10	(default = 400)		Push-pull (totem)	STP-USBENC-CBL-1 (configuration)	BRX*, CLICK C0-1xDxE-D*	STP-MTRx-23xxxD STP-MTRx-23xxxE STP-MTRAC-23xxxD Standard STP-MTRD-xxxxxE	
STP-MTRA-ENC11			Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0-1xDxE-D*		
STP-MTRA-ENC12	1000		Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0-1xDxE-D*		
STP-MTRA-ENC13	400	- 0.375 inch -	Line Driver	STP-CBL-EAxx	P2-HSI, P3-HSI, BRX*, CLICK C0-1xDxE-D*	STP-MTRAC-34xxxD	
STP-MTRA-ENC14	400		Push-pull (totem)	STP-CBL-EDxx	BRX*, CLICK C0-1xDxE-D*		

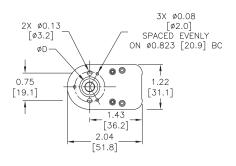
tMNC-47 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Stepping System Encoders

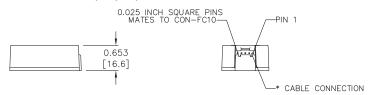
Dimensions = in [mm]

STP-MTRA-ENC1, 3, 5, 7

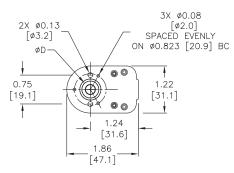




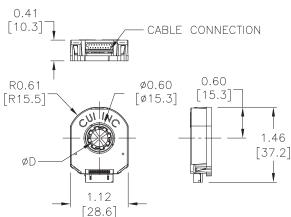
STP-MTRA-ENC2, 4, 6, 8



Bolt Hole Circles for Mounting			
Encoder	Holes		
ENC1, ENC2, ENC3, ENC4, ENC5, ENC6, ENC7, ENC8	2 holes @ 19.05mm (.75") 3 holes @ 20.9mm (.823")		
2 holes @ 16mm, 19.05mm, 32.44mm, 46.02 ENC9, ENC10 3 holes @ 20.9mm, 21.55mm, 22mm 4 holes @ 25.4mm			



STP-MTRA-ENC9, 10



STP-MTRA-ENC9, 10 Additional Dimensions			
Location	Dimensions		
D*	2mm, 3mm, 1/8 inch, 4mm, 3/16 inch, 5mm, 6mm, 1/4 inch, 8mm		

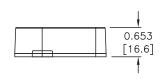
^{*} The dimension of D varies based on which sleeve is used. Values listed represent the different sleeves available for this encoder.

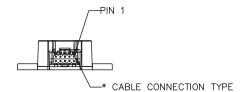
tMNC-48 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

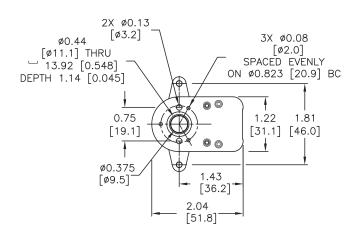
SureStep® Stepping System Encoders

Dimensions = in [mm]

STP-MTRA-ENC11, 13

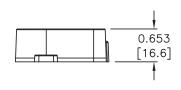


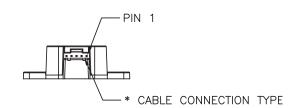


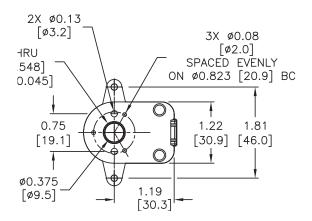


Bolt Hole Circles for Mounting				
Encoder Holes				
ENOTA ENOTO ENOTO	2 holes @ 19.05mm (.75")			
ENC11, ENC12, ENC13, ENC14	3 holes @ 20.9mm (.823")			
LINO14	2 holes @ 46.02mm (1.812")			

STP-MTRA-ENC12, 14







tMNC-49 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

AMT Series Stepping System Encoders

CUI Devices' AMT series encoders are award-winning technologically advanced capacitive encoders with a variety of uses. Small, configurable, robust, and inexpensive, AMT encoders have won Product of the Year from Electronic's Weekly and from Electronic Products magazines.

AMT series encoders are typically mounted to the back of a stepper motor, but they can be used in many other applications. Instead of manufacturing many different encoders with different resolutions, CUI Devices offers the AMT series encoders with configurable pulses per revolution (PPR). The PPR can be set for most models using the free AMT Viewpoint software (available at https://support.automationdirect.com/products/surestep.html). The AMT10 family of encoders are configured using DIP switches.

CUI Devices AMT Series Encoders

Encoder Model Overview

AMT series encoders include six distinct model lines (families) designed to meet specific needs.

- AMT10 DIP switch configurable incremental quadrature encoders. Good for NEMA 14, NEMA 17, and NEMA 23/24 size motors.
- AMT11 SW configurable resolution incremental quadrature encoders. Good for NEMA 14, NEMA 17, and NEMA 23/24 size motors (motor shaft sizes 2mm, 3mm, 1/8", 4mm, 3/16", 5mm, 6mm, 1/4", 8mm).
- AMT13 Similar to AMT11, but these are larger sized and good for NEMA 34 and NEMA 42 motors (motor shaft sizes 9mm, 3/8", 10mm, 11mm, 12mm, 1/2", 13mm, 14mm, 5/8").
- AMT31 A modified version of AMT11 with additional Hall-effect sensor outputs for commutation. This is needed for motors that don't have Hall-effect sensors mounted inside the motor. Typically "commutation encoders" are used with brushless DC (BLDC) motors and drives. Good for NEMA 14, NEMA 17, and NEMA 23/24 size motors.
- AMT33 Same encoder + commutation features as the AMT31 family, but larger size for use with NEMA 34 and NEMA 42 motors.

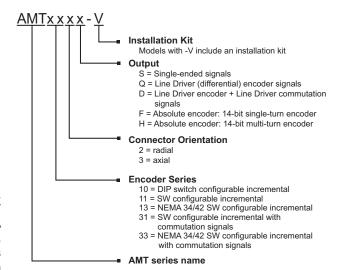
Capacitive Encoders

A capacitive encoder is comprised of three main components: a rotor, a stationary transmitter, and a stationary receiver. The rotor contains a sinusoidal pattern and, as it rotates, the high frequency reference signal of the transmitter is modulated in a predictable way. The encoder detects the changes in capacitance-reactance on the receiver board and translates them, using a demodulation algorithm, into increments of rotary motion.

Advantages of Capacitive Encoders

Derived from the same principles used in digital calipers, capacitive encoders have an excellent track record. The AMT series has proven to be both highly reliable and accurate. A capacitive encoder is more rugged than an optical encoder, tolerating a range of environmental contaminants such as dust, dirt, and oil. Capacitive encoders also hold-up much better to vibration and temperature extremes. Further, with no LED, it has a longer lifetime, a smaller footprint, and lower current consumption (6 to 18 mA) than an optical encoder. Immune to magnetic interference and electrical noise, it is as rugged as a magnetic encoder, but delivers greater accuracy and higher resolution.

Given their digital nature, capacitive encoders also offer increased flexibility, allowing users to change the encoder's resolution while a typical optical or magnetic encoder must be



swapped out each time a different resolution is needed. The programmable resolutions available in capacitive encoders are not only useful for system optimization, particularly when designing the PID control loop, but can reduce inventory holding, as one model can be used across multiple applications. Capacitive technology also allows the ability to digitally set the index pulse and alignment of the encoder for BLDC commutation, while its built-in diagnostic capabilities provide designers access to valuable system data for quick troubleshooting in the field.

tMNC-50 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

AMT Series Stepping System Encoders

Replacement Encoders

The AMT112Q-V is a replacement for the encoder that comes pre-mounted on the STP-MTR(x)-xxxxE step motors. Step motor part numbers that end in "E" have encoders pre-mounted on the rear shaft. Models that end in "D" are the same motors, without the pre-mounted encoders. If you would like a different encoder then should purchase the "D" model motor and the encoder separately.

Installation tools and mounting hardware are included with all CUI Devices brand AMT series replacement encoders. For more information and details on how to wire the replacement encoders, please see the SureStep User Manual.

PPR

CUI Devices defines PPR, pulses per revolution, as the number of high pulses per channel per revolution. CPR, the number of counts that a controller could determine from a quadrature encoder (both channels have a rising and a falling edge), is 4 x PPR

For more information regarding PPR, CPR, or LPR (Lines Per Revolution) view https://www.cuidevices.com/blog/what-is-encoder-ppr-cpr-and-lpr.

Optional Encoders

Optional encoders can be purchased separately for standard integrated motor/drives and standalone dual-shaft motors in all NEMA 14, 17, 23, 34, and 42 motors. All "D" model (dual-shaft) step motors come with pre-drilled holes in the rear end cap for easy modular encoder mounting. Pre-installed encoders on standalone dual-shaft motors and standard integrated motor/drives can be retrofitted with an appropriate optional encoder if desired. Please see the chart on the following page for encoder compatibility.





AMT102-V

AMT103-V

AMT Series Encoders				
Part Number	listprice	Description		
AMT102-V	\$24.25	CUI Devices incremental (quadrature) modular encoder, 5 VDC, radial, push-pull (totem) output, DIP switch configurable up to 2048 ppr. For use with NEMA 14, 17, and 23 dual shaft motors.		
AMT103-V	\$24.25	CUI Devices incremental (quadrature) modular encoder, 5 VDC, axial, push-pull (totem) output, DIP switch configurable up to 2048 ppr. For use with NEMA 14, 17, and 23 dual shaft motors.		
AMT112S-V	\$33.00	CUI Devices incremental (quadrature) modular encoder, 5 VDC, radial, push-pull (totem) output, configurable up to 4096 ppr. For use with NEMA 14, 17, and 23 dual shaft motors.		
AMT112Q-V	\$36.75	CUI Devices incremental (quadrature) modular encoder, 5 VDC, radial, line driver (differential) output, configurable up to 4096 ppr. For use with NEMA 14, 17, and 23 dual shaft motors.		
AMT312D-V	\$43.00	CUI Devices incremental (quadrature)/commutation modular encoder, 5 VDC, radial, line driver (differential) encoder output, configurable up to 4096 ppr, line driver (differential) commutation output. For use with NEMA 14, 17, and 23 dual shaft motors.		
AMT312S-V	\$36.75	CUI Devices incremental (quadrature)/commutation modular encoder, 5 VDC, radial, push-pull (totem) encoder output, configurable up to 4096 ppr, push-pull (totem) commutation output. For use with NEMA 14, 17, and 23 dual shaft motors.		

See Accessories section for configuration and signal cables.

CUI Devices Datasheets provide detailed encoder specifications. These datasheets can be found on each encoder's web page at www.automationdirect.com.



AMT112S-V



AMT312D-V

tMNC-51 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

AMT Series Stepping System Encoders

	AMT Series Encoders, continued				
Part Number	Price	Description			
AMT132S-V	\$33.50	CUI Devices incremental (quadrature) modular encoder, 5 VDC, radial, push-pull (totem) output, configurable up to 4096 ppr. For use with NEMA 34 and 42 dual shaft motors.			
AMT132Q-V	\$37.50	CUI Devices incremental (quadrature) modular encoder, 5 VDC, radial, line driver (differential) output, configurable up to 4096 ppr. For use with NEMA 34 and 42 dual shaft motors.			
AMT332S-V	\$37.25	CUI Devices incremental (quadrature)/commutation modular encoder, 5 VDC, radial, push-pull (totem) encoder output, configurable up to 4096 ppr, push-pull (totem) commutation output. For use with NEMA 34 and 42 dual shaft motors.			
AMT332D-V	\$43.75	CUI Devices incremental (quadrature)/commutation modular encoder, 5 VDC, radial, line driver (differential) encoder output, configurable up to 4096 ppr, line driver (differential) commutation output. For use with NEMA 34 and 42 dual shaft motors.			

See Accessories section for configuration and signal cables.

CUI Devices Datasheets provide detailed encoder specifications. These datasheets can be found on each encoder's web page at www.automationdirect.com.



AMT132S-V



AMT332S-V

	AMT Series Encoder Accessories					
Part Number	listprice	Description				
CUI-KIT-1	\$6.00	CUI Devices encoder accessory kit, replacement. For use with CUI Devices AMT102 encoders. Includes (1) AMT102 base, (1) AMT102 wide base, and (1) AMT10 sleeve kit (9 sleeves sized from 2-8mm).				
CUI-KIT-2	\$6.00	CUI Devices encoder accessory kit, replacement. For use with CUI Devices AMT103 encoders. Includes (1) AMT standard base, (1) AMT standard wide base, and (1) AMT10 sleeve kit (9 sleeves sized from 2-8mm).				
CUI-KIT-3	\$6.00	CUI Devices encoder accessory kit, replacement. For use with CUI Devices AMT11, AMT21, and AMT31 encoders. Includes (1) AMT standard base, (1) AMT standard wide base, and (1) AMT standard sleeve kit (9 sleeves sized from 2-8mm).				
CUI-KIT-4	\$6.00	CUI Devices encoder sleeve kit, replacement. For use with CUI Devices AMT13 and AMT33 encoders. Includes (8) sleeves sized from 9-14mm.				
STP-MTRA-SCRWKT-1	\$5.00	SureStep encoder mounting screw kit, for use with all stepper encoders.				



CUI-KIT-1



CUI-KIT-2







CUI-KIT-3 CUI-KIT-4 STP-MTRA-SCRWKT-1

tMNC-52 Motion Control

AMT Series Stepping System Encoders

AMT Series Encoder Compatibility							
Part Number	Max PPR	Bore Diameter	Output Type	PLC Compatibility	Encoder Cable	Configuration Cable	Motor Compatibility
AMT102-V	2048		push-pull (totem) (radial connector)	BRX ¹ , CLICK C0-1xDxE-D2	CUI-3131-x CUI-3132-1FT	- n/a	
AMT103-V	2048		push-pull (totem) (axial connector)		CUI-435-x CUI-3934-6FT		
AMT112S-V	4096	2mm, 3mm,	push-pull (totem)		AMT-17C-1-x		
AMT112Q-V	4096	1/8", 4mm, 3/16", 5mm, 6mm, 1/4",	line driver (differential)	P2-HSI, P3-HSI, BRX ¹ , CLICK C0-1xDxE-D2	AMT-17C-1-x	AMT-PGRM- 17C	NEMA 14, 17, 23 dual-shaft
AMT312D-V	4096	8mm	line driver (differential) encoder+commutation	P2-HSI, P3-HSI, BRX ¹ , CLICK C0-1xDxE-D2	AMT-17C-1-x	AMT-PGRM-	
AMT312S-V	4096		push-pull (totem) encoder+commutation	BRX ¹ , CLICK	AMT-17C-1-x	- 17C	
AMT132S-V	4096		push-pull (totem)	C0-1xDxE-D2	AMT-18C-3-x		
AMT132Q-V	4096	9mm, 3/8", 10mm, 11mm, 12mm, 1/2", 13mm,	line driver (differential)	P2-HSI, P3-HSI, BRX ¹ , CLICK C0-1xDxE-D2	AMT-18C-3-x	AMT-PGRM-	NEMA 34 and 42 dual-shaft
AMT332S-V	4096		push-pull (totem) encoder+commutation	BRX ¹ , CLICK C0-1xDxE-D2	AMT-18C-3-x	18C	(Does not fit
AMT332D-V	4096	14mm, 5/8"	line driver (differential) encoder+commutation	P2-HSI, P3-HSI, BRX ¹ , CLICK C0-1xDxE-D2	AMT-18C-3-x		STP-MTR AC -34 motors)

Note: For specific Automation Direct PLC and step motor model compatibility, please see Appendix A in the Sure Step User Manual.1 - Requires FC-ISO-C (see wiring diagrams for DIP switch settings).

	AMT Series Encoder Signal Cables			
Part Number	Price	Description		
CUI-3132-1FT	\$4.50	CUI Devices encoder cable, 5-pin connector to pigtail, 1ft cable length. For use with CUI Devices AMT102 encoders.		
CUI-3131-6FT	\$9.50	CUI Devices encoder cable, 5-pin connector to pigtail, shielded, twisted pair, 6ft cable length. For use with CUI Devices AMT102 encoders.		
CUI-3131-10FT	\$28.00	CUI Devices encoder cable, 5-pin connector to pigtail, shielded, twisted pair, 10ft cable length. For use with CUI Devices AMT102 encoders.		
CUI-3131-20FT	\$45.00	CUI Devices encoder cable, 5-pin connector to pigtail, shielded, twisted pair, 20ft cable length. For use with CUI Devices AMT102 encoders.		
CUI-435-1FT	\$5.00	CUI Devices encoder cable, 5-pin connector to pigtail, 1ft cable length. For use with CUI Devices AMT103 encoders.		
CUI-3934-6FT	\$24.50	CUI Devices encoder cable, 5-pin connector to pigtail, shielded, twisted pair, 6ft cable length. For use with CUI Devices AMT103 encoders.		
CUI-435-10FT	\$20.00	CUI Devices encoder cable, 5-pin connector to pigtail, 10ft cable length. For use with CUI Devices AMT103 encoders.		
CUI-435-20FT	\$28.00	CUI Devices encoder cable, 5-pin connector to pigtail, 20ft cable length. For use with CUI Devices AMT103 encoders.		



CUI-435-1FT CUI-435-10FT CUI-435-20FT



CUI-3131-6FT CUI-3131-10FT CUI-3131-20FT



CUI-3934-6FT

tMNC-53

CUI-3132-1FT

AMT Series Stepping System Encoders

	AMT Series Encoder Signal Cables					
Part Number	Price	Description				
AMT-17C-1-036	\$37.00	CUI Devices encoder cable, 17-pin connector to pigtail, shielded, twisted pair, 3ft cable length. For use with CUI Devices AMT112 and AMT312 encoders.				
AMT-17C-1-072	\$75.00	CUI Devices encoder cable, 17-pin connector to pigtail, shielded, twisted pair, 6ft cable length. For use with CUI Devices AMT112 and AMT312 encoders.				
AMT-17C-1-120	\$112.00	CUI Devices encoder cable, 17-pin connector to pigtail, shielded, twisted pair, 10ft cable length. For use with CUI Devices AMT112 and AMT312 encoders.				
AMT-18C-3-036	\$25.50	CUI Devices encoder cable, 18-pin connector to pigtail, shielded, twisted pair, 3ft cable length. For use with AMT13 and AMT33 encoders.				
AMT-18C-3-072	\$62.00	CUI Devices encoder cable, 18-pin connector to pigtail, shielded, twisted pair, 6ft cable length. For use with AMT13 and AMT33 encoders.				
AMT-18C-3-120	\$88.00	CUI Devices encoder cable, 18-pin connector to pigtail, shielded, twisted pair, 10ft cable length. For use with AMT13 and AMT33 encoders.				



AMT-17C-1-036 AMT-17C-1-072 AMT-17C-1-120



AMT-18C-3-036 AMT-18C-3-072 AMT-18C-3-120

AMT Series Encoders Programming Cables				
Part Number	Price	Description		
AMT-PGRM-17C	\$25.00	CUI Devices programming cable, miniB-USB to 17-pin connector, 1ft cable length. For use with CUI Devices AMT112 and AMT312 encoders.		
AMT-PGRM-18C	\$22.75	CUI Devices programming cable, miniB-USB to 18-pin connector, 1ft cable length. For use with CUI Devices AMT13 and AMT33 encoders.		



AMT-PGRM-17C AMT



AMT-PGRM-18C

tMNC-54 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

AMT Series Stepping System Encoders

Line Driver Encoder Wiring Colors							
Encoder	,	AIVI 131211-V		AMT132Q-V AMT332D-V			
Pin Function	Pin #	STP-CLB-EBx AMT-17C-1-xxx Wire Color	Pin #	AMT-18C-3-xxx Wire Color			
+5V	6	RED/BLK	6	RED/GRN			
GND	4	BLK/RED	4	GRN/RED			
Α	10	WHT/BLK	8	BRN/WHT			
Ā	11	BLK/WHT	9	WHT/BRN			
В	8	GRN/BLK	10	GRN/WHT			
Ē	9	BLK/GRN	11	WHT/GRN			
Z	12	BLU/BLK	12	BLU/WHT			
Ž	13	BLK/BLU	13	WHT/BLU			

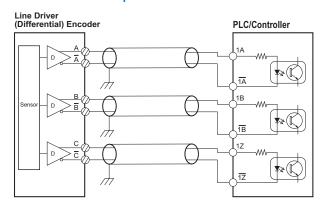
	Single Ended (Push-pull/Totem) Encoder Wiring Colors									
Encoder	AMT112S-V oder AMT312S-V STP-MTRA-ENC10		AMT132S-V AMT332S-V		AMT102-V			AMT103-V		
Pin Function	Pin #	STP-CLB-EBx AMT-17C-1-xxx Wire Color	Pin #	AMT-18C-3-xxx Wire Color	Pin #	CUI-3131-xxx Wire Color	CUI-3132-1FT Wire Color	Pin #	CUI-435-xxx Wire Color	CUI-3934-6FT Wire Color
+5V	6	RED/BLK	6	RED/GRN	5V	RED	ORG	5V	ORG	RED
GND	4	BLK/RED	4	GRN/RED	G	BLACK	BRN	G	BRN	BLACK
A+	10	WHT/BLK	8	BRN/WHT	А	WHT	BLU	Α	BLU	WHT
B+	8	GRN/BLK	10	GRN/WHT	В	BRN	YEL	В	YEL	BRN
Z +	12	BLU/BLK	12	BLU/WHT	Χ	GRN	PUR	Х	PUR	GRN

Single Ended (Push-pull/Totem) Commutation Wiring Colors						
Encoder	,	4MT312S-V	AMT332S-V			
Pin Function	Pin # AMT-17C-1-xxx Wire Color		Pin #	AMT-18C-3-xxx Wire Color		
+5V	6	RED/BLK	6	RED/GRN		
GND	4	BLK/RED	4	GRN/RED		
U+	3	BRN/BLK	3	BRN/RED		
W+	5	ORG/BLK	5	ORG/RED		
V+	7	RED/WHT	7	BLU/RED		

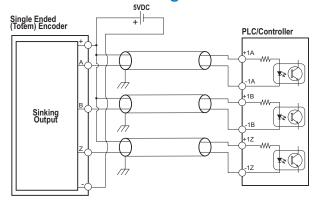
tMNC-55 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

AMT Series Encoders - PLC Connectivity

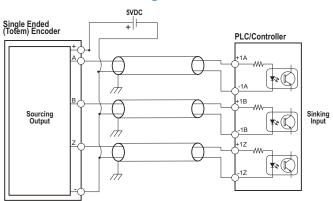
Line Driver Encoder to Line Driver PLC Input



Single Ended (Push-pull/Totem) Encoder to Sourcing PLC



Single Ended (Push-pull/Totem) Encoder to Sinking PLC



tMNC-56 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureStep® Microstepping Drives Accessories

SureMotion Pro Drive Configuration Software - for Advanced Stepper Drives and Advanced Integrated Motor/Drives

Free Download

SureMotion Pro configuration software is available as a free download from our website for SureStep advanced components (STP-DRV-4850, -80100, & STP-MTRD-xxxxxR).

- Completely replaces SureStep Pro. Required for integrated motor/ drives.
- Used for easy configuration and setup of the drive, including drive, motion control mode, I/O, motor.
- Open, Save, Upload, Download configuration files to Advanced Drives and Drive/Motors.
- Status Monitor screen aids in troubleshooting alarms and faults.
- Self Test Mode verifies motor wiring and functionality.
- SCL Terminal window allows testing/ verification of SCL (serial ASCII) commands before PLC programming begins.
- Help files include technical data, application information, advanced setup, serial command instructions.
- Runs on 32-bit/64-bit Windows operating systems.



SureStep Drive Configuration Software - for Advanced Stepper Drives						
Part Number	Price	Description				
SM-PRO	\$9.25	SureMotion Pro Windows configuration software, USB drive or free download. For use with SureStep stepper drives with serial port. Requires PC serial port, USB-RS232 or STP-USB485-4W serial adapters.				
* Available for pu	* Available for purchase on USB or can be <u>downloaded for free</u> from the AutomationDirect Web site (www.AutomationDirect.com).					

tMNC-57 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



SureStep® Cables

		SureStep Series -	- Stepping	y System Cables		
Cable	Price	Purpose	Length	Use With	Cable End Connectors	
STP-EXT-006	\$10.50		6 ft			
STP-EXT-010	\$12.00		10 ft	STP-MTR-xxxxx(x)	pigtail / Molex 43020-0401 connecto	
STP-EXT-020	\$16.00		20 ft			
STP-EXTH-006	\$22.50		6 ft			
STP-EXTH-010	\$27.00		10 ft	STP-MTR H -xxxxx(x)	pigtail / Molex 39-01-2041 connect	
STP-EXTH-020	\$31.50		20 ft			
STP-EXTHW-006	\$45.50		6 ft			
STP-EXTHW-010	\$50.00	motor to drive extension	10 ft	STP-MTR HW -xxxxx(x)	Bulgin # PXP4011/06P/6065	
STP-EXTHW-020	\$63.00		20 ft			
STP-EXTL-006	\$10.00		6 ft			
STP-EXTL-010	\$12.00		10 ft	STP-MTR L -xxxxx(x)	pigtail / Molex 105308-22004 con nector	
STP-EXTL-020	\$15.50		20 ft			
STP-EXTW-006	\$45.50		6 ft			
STP-EXTW-010	\$50.00		10 ft	STP-MTR W -xxxxx(x)	Bulgin # PXP4011/06P/6065	
STP-EXTW-020	\$63.00		20 ft			
STP-232RJ11-CBL*	\$9.50	programming/communication	10 ft	STP-DRV-4850, STP-DRV-80100	DB9 female / RJ11(6P4C)	
STP-232HD15-CBL-2**	\$11.50	communication	6.6 ft	STP-DRV-4850, STP-DRV-80100 DL06, D2-250-1, D2-260	HD 15-pin male / RJ12 6-pin plug	
STP-232RJ12-CBL-2**	\$7.00	communication	6.6 ft	STP-DRV-4850, STP-DRV-80100 DL05, CLICK	RJ12 6-pin plug / RJ12 6-pin plug	
STP-CBL-CA6	\$17.00	control cable	6 ft	CTD MTDD 17000	11-pin / pigtail	
STP-CBL-CA10	\$20.00	control cable	10 ft	STP-MTRD-17038 STP-MTRD-17038E	11-pin / pigtail	
STP-CBL-CA20	\$29.50	control cable	20 ft		11-pin / pigtail	
STP-CBL-EA6	\$17.00	encoder cable	6 ft	STP-MTRD-xxxxxE STP-MTRA-ENC1, STP-MTRA-ENC3	10-pin / pigtail	
STP-CBL-EA10	\$20.00	encoder cable	10 ft	STP-MTRA-ENC5, STP-MTRA-ENC7 STP-MTRA-ENC11, STP-MTRA-ENC13	10-pin / pigtail	
STP-CBL-EA20	\$29.50	encoder cable	20 ft	(for line driver encoders)	10-pin / pigtail	
STP-CBL-EB3	\$24.50	encoder cable	3 ft	OTD MTDA FMOO	17-pin / pigtail	
STP-CBL-EB6	\$40.50	encoder cable	6 ft	STP-MTRA-ENC9 STP-MTRA-ENC10	17-pin / pigtail	
STP-CBL-EB10	\$61.00	encoder cable	10 ft	(for both line driver and push-pull (totem)	17-pin / pigtail	
STP-CBL-EB20	\$112.00	encoder cable	20 ft	encoders)	17-pin / pigtail	
STP-CBL-ED6	\$16.50	encoder cable	6 ft	STP-MTRA-ENC2, STP-MTRA-ENC4	5-pin / pigtail	
STP-CBL-ED10	\$19.50	encoder cable	10 ft	STP-MTRA-ENC6, STP-MTRA-ENC8 STP-MTRA-ENC12, STP-MTRA-ENC14	5-pin / pigtail	
STP-CBL-ED20	\$29.00	encoder cable	20 ft	(for push-pull (totem) encoders)	5-pin / pigtail	
STP-CON-1	\$16.00	replacement connector kit	n/a	STP-DRV-4845 & -6575	-	
STP-CON-2	\$16.00	replacement connector kit	n/a	STP-DRV-4850 & 80100	-	
STP-CON-3	\$31.50	replacement connector kit	n/a	STP-MTRD-xxxxxR	-	
STP-CON-4	\$15.00	replacement connector kit	n/a	STP-DRVA-RC-050 A	-	
STP-CON-5	\$15.00	replacement connector kit	n/a	STP-DRV-4830	-	
STP-CON-6	\$21.00	replacement connector kit	n/a	STP-DRVAC-24025	-	
STP-485DB9-CBL-2	\$37.00	4-wire programming cable	6.5 ft	STP-MTRD-xxxxxR	DB9 / Phoenix 5-conductor plug	
STP-USBENC-CBL-1	\$39.50	USB programming cable	3 ft	STP-MTRA-ENC9,ENC10	17-pin / USB	

^{*} Programming/communication cable STP-232RJ11-CBLis available for spare or replacement purposes. (One cable is included with each software programmable drive.)

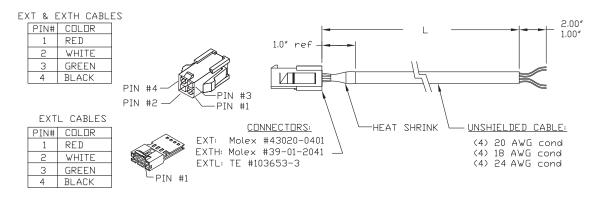
tMNC-58 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

^{**} Refer to the ZIPLinks Wiring Solutions section for complete information regarding cables STP-232HD15-CBL-2 and STP-232RJ12-CBL-2.

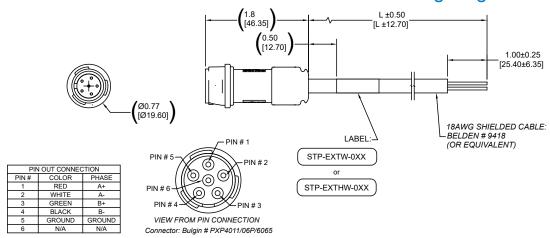


SureStep® Cables

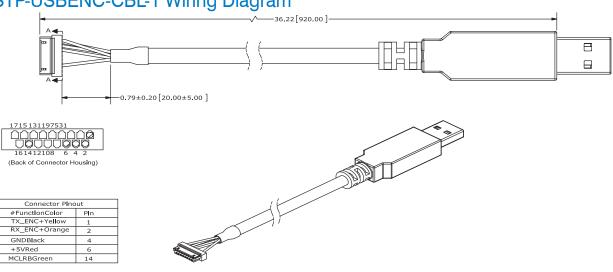
STP-EXT(x)-0xx Extension Cable Wiring Diagram



STP-EXTW-0xx and STP-EXTHW-0xx Extension Cable Wiring Diagram



STP-USBENC-CBL-1 Wiring Diagram

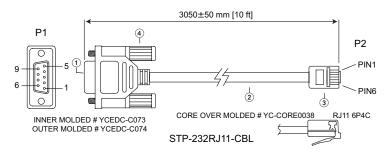


tMNC-59 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5



SureStep® Cables, continued

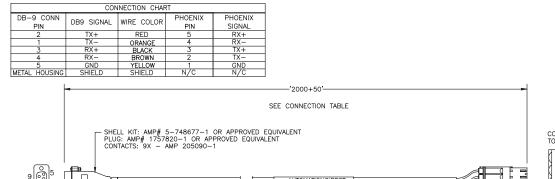
STP-232RJ11-CBL Programming Cable Wiring Diagram

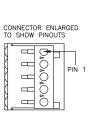


	WIRE CONNE	CTION	
(DB9) P1			P2 (RJ11 6P4C)
` ′	RX	TX	. 3
2	TX	RX	5
3	nc	nc	4
4	GND	GND	4
5			7 2

- DB 9P FEMALE CONNECTOR SHELL: FRONT NICKEL BACK TIN INSULATOR COLOR: BLACK
- CABLE: CAT-5 UTP 24AWG (7/0.203BA*2PR) 100MHz
- COLOR: BLACK OD: 4.5mm (3) RJ11 6P4C PLATED GOLD 3U"
- (4) SCREW: #4-40UNC PD40*175TNP COLOR: BLACK

STP-485DB9-CBL-2 4-wire Programming Cable Wiring Diagram



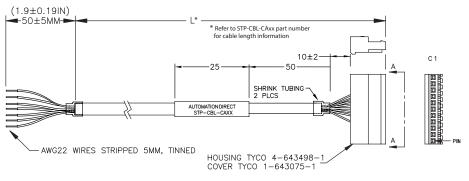


STP-CBL-CAxx Control Cable Wiring Diagram



DB-9 PIN NUMBERS

VIEWED FROM END



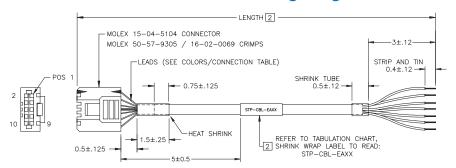
CONNECTOR: PHOENIX CONTACT 1881354

tMNC-60 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5



SureStep® Cables, continued

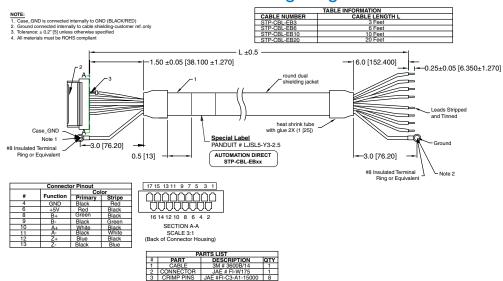
STP-CBL-EAxx Encoder Cable Wiring Diagram



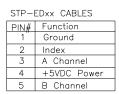
	CONNECTION TABLE			
L	SIGNAL	LOR	LEAD CO	PIN
D TWI	GROUNE	/HITE	GREEN/\	2
+ 14/1	POWER+	N	GREE	7
	I-	WHITE	ORANGE/	3
IWI	I+	SE.	ORAN	4
TWI	A-	HITE	BLUE/W	5
1441	A+		BLUI	6
Twi	B-	VHITE	BROWN/	9
14/1	B+	N	BROW	10
= NO	N/A		N/C	1
NO	N/A		N/C	8

WIRE: 24AWG, CABLE: UL2464.

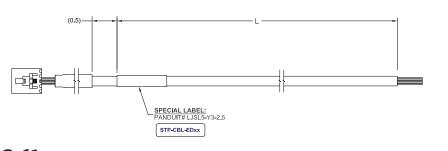
STP-CBL-EBxx Encoder Cable Wiring Diagram



STP-CBL-EDxx Encoder Cable Wiring Diagram



TAB	TABLE INFORMATION					
CABLE NUMBER	CABLE LENGTH L					
STP-CBL-ED6	6 Feet					
STP-CBL-ED10	10 Feet					
STP-CBL-ED20	20 Feet					



tMNC-61 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Surestep Stepping Systems with PLCs

Controller Compatibility

High Speed Pulse Motion Control with AutomationDirect PLCs* and SureStep® Stepping Systems								
PLC Series	Starting at \$197.00	Starting at \$247.00	Starting at \$299.00					
PLC Series	BX-DM1x-10	BX-DM1x-18	BX-DM1x-36					
Maximum Number of Axes	2	3	3					
Output Signal Type		Sink/Source						
Maximum Pulse Rate (pulses/ sec)	250,000							
Position Control	Trapezoidal Profiles (linear and S-curve ramps)							
Velocity Control		Dynamic Velocity (controlled accel/dec	el)					

High Speed Pulse Motion Control with AutomationDirect PLCs* and SureStep™ Stepping Systems							
1–16 axis control depending on base size and power supply budget **							
PLC Series	CPUs starting at	\$273.00	CPUs startin	g at \$476.00			
PLC Series	P2000		P30	000			
I/O Modules Pulse Outputs	P2-HSO P3-HSO						
Maximum Number of Axes	2 p	er module, 22 per PLC racl	k, 44 per PLC system				
Output Signal Type	Line Driver	Sink/Source	Line Driver	Sink/Source			
Maximum Pulse Rate (pulses/ sec)	1,000,000	500,000	1,000,000	500,000			
Position Control	Trapezoidal Profiles (linear and S-curve ramps)						
Velocity Control	Dynamic Velocity (controlled accel/decel)						
Maximum Number of Modules		11 per PLC rack, 22 pe	er PLC system	·			

High Speed Pulse Motion Control with AutomationDirect PLCs* and SureStep® Stepping Systems							
DLC Co. to	Starting at \$227.00	Starting at \$132.00	Starting at \$264.00				
PLC Series	DL105	DL05	DL06				
Built-In PLC Pulse Outputs	1 axis pulse output included with the PLC base unit						
Maximum Number of Axes	1 axis control**	1-2 axis control***	1-5 axis control***				
Maximum Pulse Rate (pulses/sec)	7,000 10,0						
Position Control	Trapezoidal Profiles (linear only)						
Velocity Control	Velocity Levels (no ramps available when changing velocity)						
I/O Modules Pulse Outputs	H0-CTRIO2 (1 axis per module)						
Maximum Pulse Rate (pulses/sec)		65,000					
Position Control	Not Applicable for DL105 Trapezoidal Profiles (linear & S-curve ramps)						
Velocity Control	Dynamic Velocity (controlled accel/decel)						
Maximum Number of Modules		1	4				

Any PLC capable of RS-232 ASCII communication can write serial commands to the STP-DRV-4850, -80100 Drives. Any PLC capable of RS-485 ASCII communication can write serial commands to the Advanced Integrated drives. Most AutomationDirect PLCs will communicate using either RS-232 or RS-485 communications, however we recommend using either Click, Productivity, or BRX (DoMore) as they are modern PLCs. DirectLogic will also work but is older technology.

tMNC-62 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

 $^{^{**}}$ When using DC output models only. *** When using either DC output model or H0-CTR10 option module.

Surestep Stepping Systems with PLCs

Controller Compatibility (continued)

High Speed Pulse Motion Control with AutomationDirect PLCs* and SureStep™ Stepping Systems								
1-16 axis control depending on base size and power supply budget **								
CPUs starting at \$302.00 CPUs starting at \$303.00								
PEC Series	DL205 Do-more							
I/O Modules Pulse Outputs	D2-CTRINT H2-CTRIO2 T1H-CTRIO (1 axis per module) (2 axes) (2 axes per module)				H2-CTRIO2 (2 axes)			
Maximum Pulse Rate (pulses/ sec)	5,000 65,000 25,000 250,				250,000			
Position Control	Trapezoidal Profiles (linear and S-curve ramps)							
Velocity Control	Dynamic Velocity (controlled accel/decel)							
Maximum Number of Modules	1 1-8							

^{*} Any PLC capable of RS-232 ASCII communication can write serial commands to the STP-DRV-4850, -80100 Drives. Any PLC capable of RS-485 ASCII communication can write serial commands to the Advanced Integrated drives. Most AutomationDirect PLCs will communicate using either RS-232 or RS-485 communications, however we recommend using either Click, Productivity, or BRX (DoMore) as they are modern PLCs. DirectLogic will also work but is older technology.

tMNC-63 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

^{**} using D2-CITRANT or Hx-CTRIO modules.



Leadshine 2-phase Digital Stepper Drives

Leadshine has been an industry leading motion control supplier since 1997, and is one of the largest stepper drive manufacturers in the world. Leadshine steppers offer high quality products (Leadshine factories are ISO9001 certified) at very affordable prices. Leadshine steppers are simple, easy to use, long-lasting, and reliable.

Automation Direct sells a wide range of linear and switching power supplies, stepper motors, cables, and PLCs with hi-speed outputs that are compatible with Leadshine stepper drives.

Features:

- 2-phase digital stepper drives
- Anti-resonance for optimal torque, extra smooth motion, low motor heating and noise
- Motor auto-config on power up
- All drives support step and direction control, some models support CW/CCW as well
- Micro-stepping for smooth motor movement
- DIP switch configurable

- Wide range of input voltages supported (12-110 VDC, 18-80 VAC)
- Pulse input frequency up to 200kHz
- Soft-start with no "jump" when powered on
- Automatic idle-current reduction
- Protections for over-voltage and overcurrent
- NEMA 11, 14, 17, 23, 24, 34 and 42 frame size step motors supported







		Leadshine	Series – Dri	ves Features	s Compariso	n ¹			
Drive Model	DM322E	DM542E	DM556E	DM860E	DMA860E	DM805-AI	EM542S	EM556S	
Price	\$25.50	\$36.00	\$40.00	\$49.50	\$63.00	\$105.00	\$46.50	\$57.00	
Drive Type		2-phase digital stepper drive							
Supply Voltage	12–30 VDC (24 VDC typical)		O VDC DC typical)	24–74 VDC (48–68 VDC typical)	24–110 VDC (48–90 VDC typical) or 18–80 VAC (36–70 VAC typical)	20–80 VDC (30–60 VDC typical)	20–50 VDC (24–48 VDC typical)		
Pulse Input Type	Single-ended ² Differential, Single-ended Single-ended ²						Differential, Single-ended		
Step Input Modes	Step & Direction Step & Direction, CW & CCW Step & Direction, Analog input						Step & Direction	on, CW & CCW	
Digital Input Voltage	5V (add a 1K resistor to accept +12V input, or a 2K resistor to accept +24V input) DIP switch selectab						able for 5V or 24V		
PPR Range	400–12800	400–12800 400–25600 400–51200			51200	200-12800	200–	25600	
Motor Output Current Range	0.3–2.2 A peak (0.2–1.6 RMS)	1.0-4.2 A peak (0.7-3.0 RMS)				2.6–7.0 A peak (0.3–5.0 RMS)		2 A peak 1 RMS)	
Digital Output	No +24VDC (Brake and Fault Detection								
Self-test Capable	No	No	No	No	No	Yes	Yes	Yes	
Special Features	Soft-start, motor auto-config			Accepts a DC or an AC power supply, soft-start, motor auto-config	Built-in pulse generator, com- mand source		ft-start, fault and ts, shaft lock		
1 - Refer to Specifications T	ables for detailed	specifications.			1	l	I.		
2 - See the User Manual or (Quick Start Guide	for instructions of	n wiring Single-L	Ended drives to a	Differential (Line	e Driver) controlle	er.		

tMNC-64 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Leadshine Stepping Drives





DM542E, DM556E, DM860E, DMA860E

The DM542E and DM556E drives are capable of pulse and direction operation, with auto-motor config on power up.

The DM860E and DMA860E drives possess the same capabilities but can also do CW and CCW pulse operation. The main difference between these models are output current range to the motor and supply voltage.

		Leadshine DM542E, I	DM556E, DM860E, DMA	860E Specifications					
Drive Model		DM542E	DM556E	DM860E	DMA860E				
Output Curren	t	1.0–4.2 A peak (0.7–3.0 RMS)	1.8–5.6 A peak (1.3–4.0 RMS)	2.4–7.2 A peak (1.7–5.1 RMS)	2.4–7.2 A peak (1.7–5.1 RMS)				
Input Voltage		20–50 VDC (24–48 VDC typical)		24–74 VDC (48–68 VDC typical)	24–110 VDC (48–90 VDC typical) or 18–80 VAC (36–70 VAC typical)				
Logic Signal C	Current		7–16 mA (10	OmA typical)					
Pulse Input Fr	equency		0-200	O kHz					
Minimal Pulse	. Width		2.5	μs					
Minimal Direc	tion Setup		5.0	μs					
Isolation Resi	stance	500mΩ							
	PUL+	Pulse signal: 5V signal, differential input. High input is 4-5V, Low input is 0-0.5 V. Minimum pulse width = 2.5 μs. Add a 1kΩ resistor for							
	PUL-	+12V signals, $2k\Omega$ for +24V signals.							
	DIR+	Direction signal: 5V signal, differential input. High input is 4-5V, Low input is 0-0.5 V. Minimum pulse width = 2.5μ s. Add a $1 k\Omega$ resistor for +12V signals, $2 k\Omega$ for +24V signals.							
Connector P1 Functions	DIR-	Direction Function: requires 5µs setup time. CW/CCW Function (DM860E and DMA860E only): see DIP switch SW14.							
	ENA+	Enable signal: 5V signal, differential input. High input is 4-5V, Low input is 0-0.5 V. Minimum pulse width = 2.5μ s. Add a $1 k\Omega$ resistor for +12V signals, $2 k\Omega$ for +24V signals.							
	ENA-	Enable Function: Close (pull low) to disable the drive.							
Replacement	Connectors	Power = DN-6PLUG, I/O = DN-4PLUG, Enable = DN-2PLUG							
Cooling		Natural cooling or forced cooling							
Ambient Temp	erature	0°C to 65°C (32°F to 149°F)							
Humidity		40–90% relative humidity							
Operating Ten	nperature	0°C to 50°C (32°F to 122°F)							
Vibration		10–50 Hz / 0.15 mm							
Storage Temperature -20°C to 65°C (-4°F to 149°F)									
Self Test		No							
Weight 227g (8 oz) 300g (10.6 oz) 510g (1.13 lbs) 510g (1.13 lbs)									

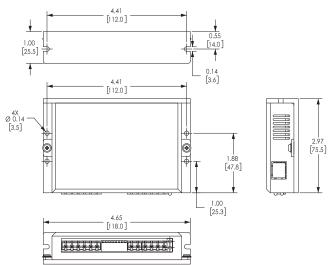
tMNC-65 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Leadshine Drive Dimensions

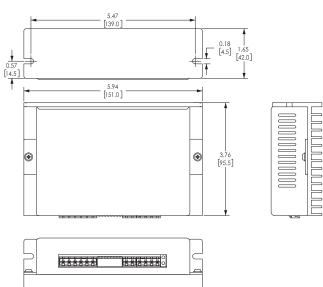
Dimensions = in [mm]

DM542E

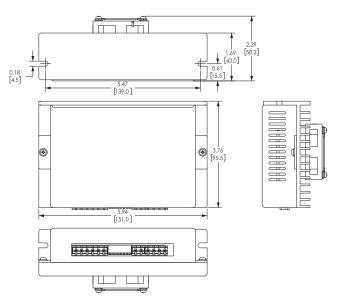


DM556E (1,12,0) (1,14) (3,6)

DM860E



DMA860E

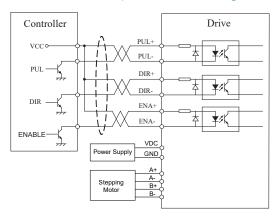


tMNC-66 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

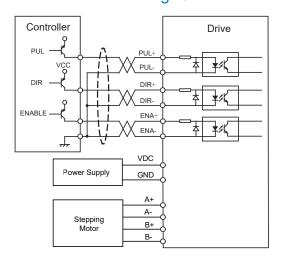


Leadshine Drive Wiring

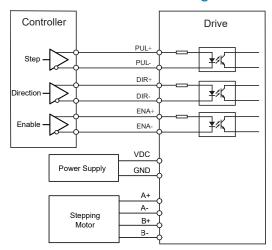
DM542E, DM556E, DM860E, DMA860E Connection to Open Collector Signal



DM542E, DM556E, DM860E, DMA860E Connection to PNP Signal



DM542E, DM556E, DM860E, DMA860E Connection to Differential Signal



tMNC-67 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



DM332E

The DM322E is a compact drive capable of pulse and direction operation, with motor auto-configuration on power up.



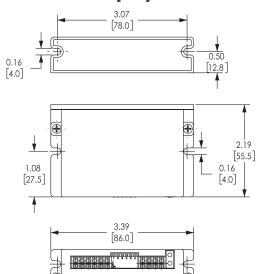
		Leadshine DM322E Specifications				
Drive Model		DM322E				
Output Current		0.3–2.2 A peak (0.2–1.6 RMS)				
Input Voltage		12–30 VDC (24 VDC typical)				
Logic Signal Cu	rrent	7–16 mA (10mA typical)				
Pulse Input Fred	quency	0–70 kHz				
Minimal Pulse	Width	7.5 µs				
Minimal Directi	on Setup	7.5 µs				
Isolation Resist	ance	100mΩ				
Connector P1 Functions	PUL	Pulse signal: 5V signal, single-ended input. High input is 4-5V, Low input is 0-0.5 V. Minimum pulse width = $2.5 \mu s$. Add a $1 k \Omega$ resistor for +12V signals, $2 k \Omega$ for +24V signals.				
	DIR	DIR signal: 5V signal, single-ended input. High input is 4-5V, Low input is 0-0.5 V. Minimum puls width = 2.5 μs. Add a $1 k_{\Omega}$ resistor for +12V signals, $2 k_{\Omega}$ for +24V signals. Direction Function: requires 5μs setup time. CW/CCW Function: see DIP switch SW14.				
	ОРТО	This input is the voltage supply for the Pulse, Direction, and Enable opto-couplers. Connect 5VDC +12V, +24V with appropriate resistors on Pulse, Direction, and Enable inputs).				
	ENA	Enable signal: 5V signal, single-ended input. High input is 4-5V, Low input is 0-0.5 V. Minimum pulse width = $2.5 \ \mu$ s. Add a $1 k\Omega$ resistor for + $12V$ signals, $2 k\Omega$ for + $24V$ signals. Enable Function: Close (pull low) to disable the drive.				
Replacement Co	onnectors	Power = 6-pin from STP-CON-4; I/O = 4-pin from STP-CON-5				
		Natural cooling or forced cooling				
Ambient Tempe	rature	0°C to 65°C (32°F to 149°F)				
Humidity		40–90% relative humidity				
Operating Temperature		0°C to 50°C (32°F to 122°F)				
Vibration		10–50 Hz / 0.15 mm				
Storage Temperature		-20°C to 65°C (-4°F to 149°F)				
Self Test		No				
Weight		90g (3.5 oz)				

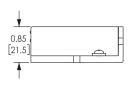
tMNC-68 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



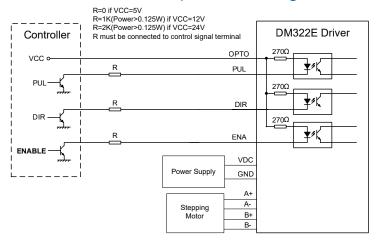
DM322E Dimensions and Wiring

Dimensions = in [mm]

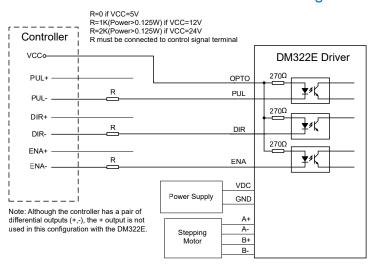




DM322E Connection to Open Collector Signal



DM322E Connection to Differential Control Signal



tMNC-69 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



DM805-AI

The DM805-Al is capable of pulse and direction as well as analog input and speed control, with motor auto-configuration on power up and motor self-test capability. Comes with built in potentiometers for adjusting accel and decel rates and can be controlled via an external potentiometer.



		Leadshine DM805-Al Specifications		
Drive Model		DM805-AI		
Output Current		2.6–7.0 A peak (0.3–5.0 RMS)		
Input Voltage		20–80 VDC (60VDC typical)		
Logic Signal Current		7–16 mA (10mA typical)		
Pulse Input Frequency		0–200 kHz		
Minimal Pulse Widt	th	2.5 μs		
Minimal Direction S	Setup	5.0 µs		
Isolation Resistance	,	500mΩ		
	Run/Stop or Pulse	Pulse signal: 5V signal, single-ended input. High input is 4-5V, Low input is 0-0.5 V. Minimum pulse width = $2.5 \mu s$. Add a 1Ω resistor for +12V signals, $2 k \Omega$ for +24V signals. Run/Stop Function: Close (pull low) to enable the motor.		
Pin Functions	Direction or +Limit	DIR signal: 5V signal, single-ended input. High input is 4-5V, Low input is 0-0.5 V. Minimum pulse width $= 2.5 \mu s$. Add a $1 k \alpha$ resistor for +12V signals, $2 k \alpha$ for +24V signals. Direction Function: requires 5μs setup time. (+)Limit Function: Close (pull low) to stop motor movement in the positive direction.		
	Speed or (-)Limit	Speed: 5V signal, single-ended input. High input is 4-5V, Low input is 0-0.5 V. Minimum pulse width = $2.5 \mu s$. Add a $1 k \alpha$ resistor for +12V signals, $2 k \alpha$ for +24V signals. Speed Function (Low Speed/High Speed Mode): Close (pull low) to select Lo Speed pot setpoint. Open (float high) to enable Hi Speed pot setpoint. (-)Limit Function: Close (pull low) to stop motor movement in the negative direction.		
	Enable/Disable	Enable signal: 5V signal, single-ended input. High input is 4-5V, Low input is 0-0.5 V. Minimum pulse width = $2.5 \mu s$. Add a $1 k\Omega$ resistor for +12V signals, $2 k\Omega$ for +24V signals. Enable Function: Close (pull low) to disable the drive.		
Replacement Conne	ectors	Power = 6-pin from STP-CON-4; I/O = 6-pin from STP-CON-4; Analog = 4-pin from STP-CON-4		
Cooling		Natural cooling or forced cooling		
Ambient Temperature		0°C to 50°C (32°F to 122°F)		
Humidity		40–90% relative humidity		
Operating Temperature		70°C (158°F) max		
Vibration		4.9 m/s2 max		
Storage Temperature		-20°C to 65°C (-4°F to 149°F)		
Self Test		Yes		
Configuration Cable		1.4.4-0609505-B3		
Weight		264g (9.3 oz)		

Leadshine Series Drive Cables						
Optional Configuration Cable Compatible With Price						
1.4.4-0609505-B3 DM805-AI \$5.00						

Note: Configuration cable only required if using optional configuration software. Software configuration not necessary unless DIP switch settings and auto-tuning aren't sufficient for your application. Requires an RS232 port on your PC, or a USB to RS232 converter, like USB-RS232.

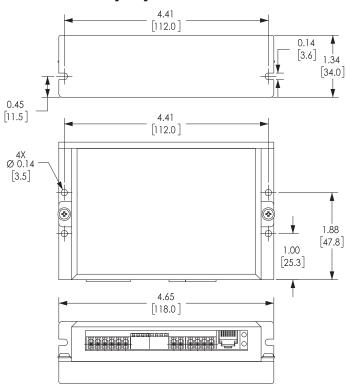


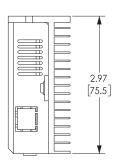
1.4.4-0609505-B3



DM805-AI Dimensions

Dimensions = in [mm]

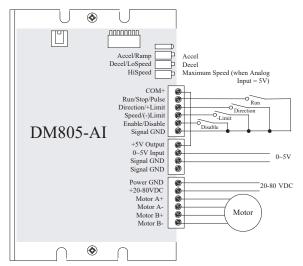




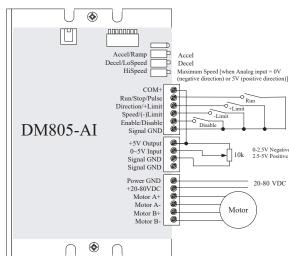
DM805-Al Wiring

The DM805-Al has four different operation modes that can be selected through DIP SW7 and SW8, and can also be wired to a differential controller.

DM805-Al Wiring for Analog Speed Mode



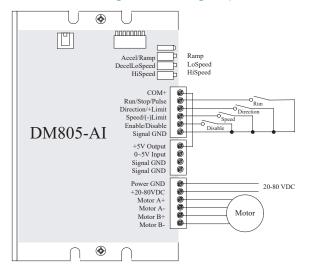
DM805-Al Wiring for External Pot Mode



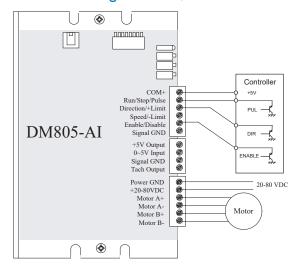
tMNC-71 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Leadshine Stepping Drives

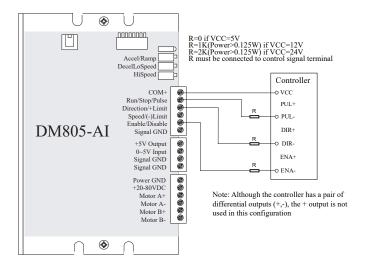
DM805-Al Wiring for Low/High Speed Mode



DM805-Al Wiring for Pulse/Direction Mode



DM805-Al Wiring for Differential Control Signal



tMNC-72 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



EM542S, EM556S

The EM542S and EM556S are digital stepper drives capable of pulse and direction as well as CW and CCW operation, with motor auto-configuration on power up and self-test capability. EM542S and EM556S have a built-in current-limiting resistor (on a switch) to allow either 5V or 24V input pulses. They also include a fault and a brake output, and a shaft lock feature. The brake output can be used with an external holding brake to hold the motor in place if power fails or the drive is disabled - you lose power, the brake engages. The shaft lock is set via DIP switch and will lock the motor into position using phase current, but only works when the drive has power.



	Lea	dshine EM542S, EM556S Specifi	cations						
Drive Model		EM5428	EM556\$						
Output Current		2.4–7.2 A peak (1.7–5.1 RMS)	2.4–7.2 A peak (1.7–5.1 RMS)						
Input Voltage		20-5	0 VDC DC typical)						
Logic Signal Currei	nt	`	IOmA typical)						
Pulse Input Freque	псу	0–20	00 kHz						
Minimal Pulse Wid			5 µs						
Minimal Direction) µs						
Isolation Resistanc	e	500	DmΩ						
	PUL+	Pulse signal: 5V or 24V signal (Switch S3 det 4-5V or 22-24V, Low input is 0-0.5 V. Minimum Switch S3 factory default = 24V position.	ermines voltage), differential input. High input is pulse width = 2.5 µs.						
	PUL-	WARNING! If switch S3 is in the 5V position ar	d 24V is applied, the drive will be damaged.						
Connector P1	DIR+	DIR signal: 5V or 24V signal (Switch S3 determines voltage), differential input. High input is 4-5V or 22-24V, Low input is 0-0.5 V. Minimum pulse width = $2.5 \mu s$.							
Functions	DIR-	Direction Function: requires 5µs setup time. CW/CCW Function: see DIP switch SW14. WARNING! If switch S3 is in the 5V position and 24V is applied, the drive will be damaged.							
	ENA+	Enable signal: 5V or 24V signal (Switch S3 determines voltage), differential input. High input is 4-5V or 22-24V, Low input is 0-0.5 V. Minimum pulse width = 2.5 μs.							
	ENA-	Enable Function: Close (pull low) to disable the drive. WARNING! If switch S3 is in the 5V position and 24V is applied, the drive will be damaged.							
Fault and Brake Output Connector	ALM BR COM-	Optional output connection. Maximum of 30V/100mA output, sinking or sourcing.							
Replacement Conn	ectors	Incoming Power = DN-2PLUG; Motor Power	r = DN-4PLUG; I/O = 6-pin from STP-CON-4						
Cooling		Natural cooling	or forced cooling						
Ambient Temperatu	ire	0°C to 65°C (32°F to 149°F)						
Humidity		40–90% rel	ative humidity						
Operating Tempera	ture	0°C to 50°C (32°F to 122°F)						
Vibration		10–50 Hz / 0.15 mm							
Storage Temperatu	re	-20°C to 65°C (-4°F to 149°F)							
Self Test		Yes							
Configuration Cable	9	1.4.4-0409505-B3							
Weight		250g (8.8 oz)	250g (8.8 oz)						

Leadshine Series Drive Cables											
Optional Configuration Cable Compatible With Price											
1.4.4-0409505-B3	1.4.4-0409505-B3 EM542S, EM556S \$5.00										

Note: Configuration cable only required if using optional configuration software. Software configuration not necessary unless DIP switch settings and auto-tuning aren't sufficient for your application. Requires an RS232 port on your PC, or a USB to RS232 converter, like USB-RS232.



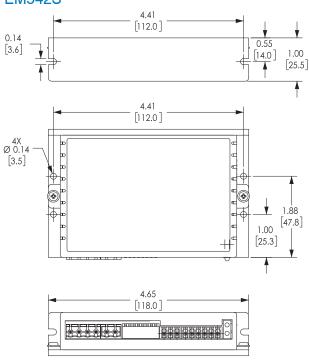
1.4.4-0409505-B3

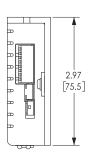


EM542S, EM556S Dimensions

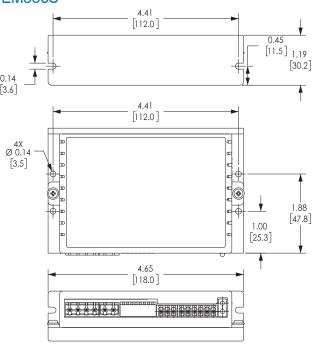
Dimensions = in [mm]

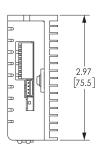
EM542S





EM556S



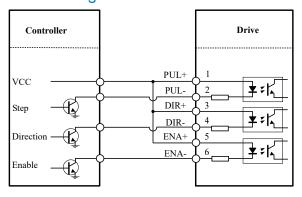




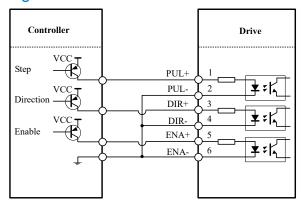
EM542S, EM556S Wiring

Note: These drives can accept Vcc of 24V or 5V. Set switch S3 before applying power.

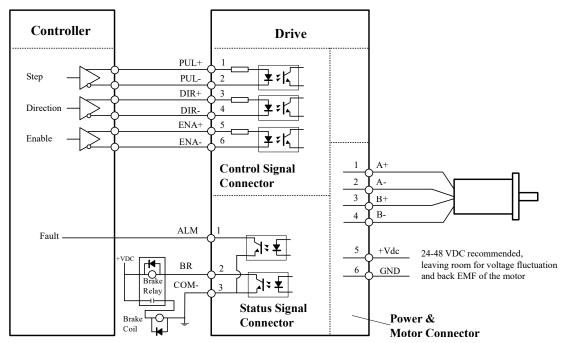
EM542S, EM556S Connection to Open-Collector Signal



EM542S, EM556S Connection to PNP Signal



EM542S, EM556S Connection to Differential Signal; Typical Connection with Brake and Fault Outputs



tMNC-75 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Linear Motion Slides and Components

The three SureMotion families of linear slide actuators easily mate to SureStep motors and other NEMA motors. Everything you need to mount your SureStep motor is included!

These units are an excellent solution for many applications such as pick and place, packaging, assembly automation and other motion control operations.



tMNC-76 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Linear Motion Products Product Overview

Actuator Overview

SureMotion linear motion offers both motor-ready actuator assemblies, and a versatile assortment of sliding components and accessories to provide a wide variety of motion control solutions.

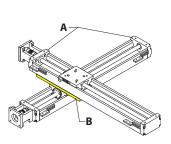
Linear Slide Actuator Comparisons

	Actuator Series Comparisons													
Actuator Series	Actuator Type	Drive Type	Max Load Capacity (lb)	Max Speed (in/s)	Travel (in)	Relative Price								
LARSD2	Twin Round Shaft	Ball Screw	920	6	12, 24	\$\$\$\$								
LACP2	Compact Slide	Lead Screw	125	20	6, 12, 24, 36	\$\$								
LAVL2	Value Slide	Lead Screw	110	15	6, 12, 18, 24	\$								

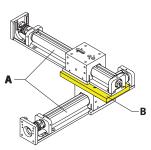


Available Multi-Axis Configurations

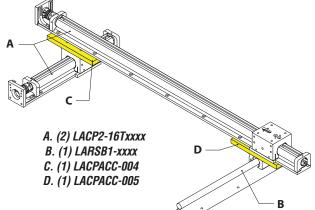
X-Y Axis Configurations



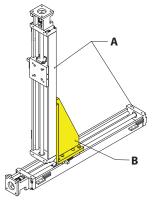
A. (2) LAVL2-60Txxxx B. (1) LAVLACC-004



A. (2) LACP2-16Txxxx B. (1) LACPACC-004

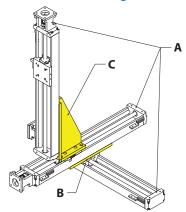


X-Z Axis Configuration

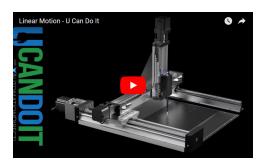


A. (2) LAVL2-60Txxxx B. (1) LAVLACC-005

X-Y-Z Axis Configuration



A. (3) LAVL2-60Txxxx B. (1) LAVLACC-004 C. (1) LAVLACC-005



Click on the above video link for a short visual example of how our products can be used.

tMNC-77 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Continuously-supported round rail slide with ball screw actuation provides a very robust precision linear motion. Units



notion Linear Ivious. Twin Round Shaft Slide Actuators **Linear Motion Products**

Description



LARSD2-08T12BP2C

Applications

· Positioning systems

are complete except for a drive motor.

Heavy loads

Features

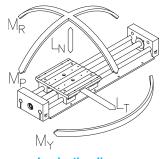
- · High-accuracy ball screw
- · Continuously-supported guide rails
- Replacement components available
- · Ready for NEMA 23 motor
- · AISI 1566 Carbon Steel, 60 RC Round Shafts
- · AISI 1045 Carbon Steel, 56 RC Ball Screw

	Twin Round Shaft Slide Actuator Specifications													
Part Number Price Drive Drive Drive Screw Payload Inertia Constant System Inertia (Ib _m -in ²) Travel Weight (Ib) Fits Motor														
LARSD2-08T12BP2C	\$2,592.00				0.2 in	02	0.001	0.11	12in	10.5	NEMA 22			
LARSD2-08T24BP2C	\$2,798.00	Ball screw	0.2 111	83	0.001	0.16	24in	14.0	NEMA 23					

System Inertia Calculation:

To calculate the inertia reflected to the motor in a particular actuator, multiply the carriage payload by the payload inertia factor and then add the constant system inertia value for that actuator. The constant system inertia value for each system includes the inertia of the shaft coupler, carriage, and lead/ball screw.

• The payload must be in units of lb_m.



Load rating diagram

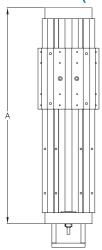
Twin Round Shaft Slide Actuator Load/Moment Ratings												
		Loa	ad (lb)		Moment (lb·in)							
Part Number	Actuator Normal – L _N		Transverse	Roll	Pitch	Yaw						
	Thrust	Down	Up	L _T	M_R	M_P	M_{Y}					
LARSD2-08TxxBP2C	200	920	644	920	1046	1210	1730					

tMNC-78 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

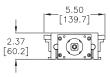


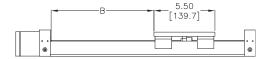
Linear Motion Products Twin Round Shaft Slide Actuators

Dimensions (in [mm])



PART	Α	В
NUMBER		(TRAVEL)
LARSD2-08T12BP2C	19.50 [495.3]	12.00 [304.9]
LARSD2-08T24BP2C	31.5 [800.1]	24.00 [609.8]





LARSD2-08TxxBP2C

See our website $\underline{\textit{www.AutomationDirect.com}}$ for complete Engineering drawings.

Accessories

Twin Round Shaft Slide Actuator Accessories										
Part Number	Price	Description	Weight (lb)							
LARSACC-010	\$26.00	SureMotion linear ball bushing, open type, 1/2 inch inside diameter, with seals, self-aligning.	0.5							
LARSACC-013*	\$691.00	SureMotion repair kit, for use with LARSD2-08T12BP2C actuators. Ballscrew, ballnut, end bearings and grease tube included.	3.0							
LARSACC-014*	\$681.00	SureMotion repair kit, for use with LARSD2-08T24BP2C actuators. Ballscrew, ballnut, end bearings and grease tube included.	5.0							
LARSACC-015*	\$259.00	SureMotion motor adapter, NEMA 23 frame. For use with LARSD2-08 series actuators. 1/4 x 1/4 inch coupler included.	1.0							
LARSACC-016*	\$312.00	SureMotion motor adapter, NEMA 34 frame. For use with LARSD2-08 series actuators. 1/2 x 1/4 inch coupler included.	1.0							
* Repair kits and NEI	MA 23/34 n	notor adapter contain replacement components that are the same as the original components in the actuator assem	ıblies.							



Some accessories not shown see <u>www.AutomationDirect.com</u> for additional product photos.

tMNC-79 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Linear Motion Products

Compact Slide Actuators - Generation 2



Features

- Compact design
- · Replacement components available
- · Ready for NEMA 17 motor (NEMA 23 motor requires new coupling)
- End-of-travel switch mounts
- · AISI 6061-T6 Aluminum Alloy base, Hard Anodized on all surfaces to a depth of 0.0005 to 0.0015"
- · AISI 303 Stainless Steel Lead Screw

Description

Self-contained linear actuator designed for light loads in harsh or wet conditions in a very small package. The base is a single piece design with integrated slide surfaces, and is hard anodized all over.

Generation 2 actuators have a reduced part count for more reliable operation, integral wireway through the body and more robust motor mount that fits both NEMA 17 and 23 motors.

Applications

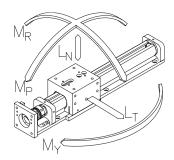
- · Space-limiting applications
- · Harsh or wet environments
- Light loads
- · Speeds up to 20 inches per second

	Compact Slide Actuator Specifications													
Part Number	Price	Drive Type	Drive Pitch	Drive Screw Efficiency (%)	Payload Inertia Factor (in ²)	Constant System Inertia (lb _m -in ²)	Travel	Weight (lb)	Fits Motor					
LACP2-16T06LP5	\$1,219.00		0.5 in			0.016	6in	1.8						
LACP2-16T12LP5	\$1,285.00			0.5 in 52	0.0063	0.017	12in	2.3						
LACP2-16T24LP5	\$1,695.00					0.020	24in	3.5						
LACP2-16T36LP5	\$2,020.00	Lood oorou				0.024	36in	4.5	NEMA 17					
LACP2-16T06L1	\$1,219.00	Lead screw				0.022	6in	1.8	INEIVIA 17					
LACP2-16T12L1	\$1,285.00		1in	44	0.025	0.023	12in	2.3						
LACP2-16T24L1	\$1,695.00		11(1	44	0.025	0.026	24in	3.5						
LACP2-16T36L1	\$2,020.00					0.030	36in	4.5						

System Inertia Calculation:

To calculate the inertia reflected to the motor in a particular actuator, multiply the carriage payload by the payload inertia factor and then add the constant system inertia value for that actuator. The constant system inertia value for each system includes the inertia of the shaft coupler, carriage, and lead/ball screw.

• The payload must be in units of lb_m.



Load rating diagram

	Compact Slide Actuator Load/Moment Ratings												
		Loa	d (lb)*	Moment (lb·in)**									
Part Number	Actuator	Norma	al – L _N	Transverse	Roll	Pitch	Yaw						
	Thrust	Down	Up	L _T	M_R	M _P	M _Y						
LACP2-16TxxLP5	51	125	60	125	12	15	33						
LACP2-16TxxL1	28	125	60	125	12	15	33						

- 30lb is the recommended maximum load capacity if the carriage is not externally supported against rolling. The higher load capacities are possible if the carriage is externally supported.
- It is recommended that offset loads be located 5 inches or less from the center of the carriage. When the loads are offset at greater distances, the carriage can vibrate during travel.

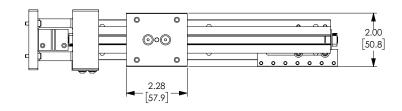
tMNC-80 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

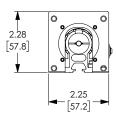


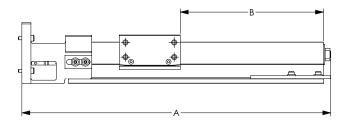
Compact Slide Actuators - Generation 2 **Linear Motion Products**

Dimensions (in [mm])

PART NUMBER	Α	B (TRAVEL)
LACP2-16T06LP5	11.57 [293.8]	6.40 [162.6]
LACP2-16T12LP5	17.57 [446.2]	12.40 [315.0]
LACP2-16T24LP5	29.57 [751.0]	24.40 [619.8]
LACP2-16T36LP5	41.57 [1055.8]	36.40 [924.6]
LACP2-16T06L1	11.57 [293.8]	6.40 [162.6]
LACP2-16T12L1	17.57 [446.2]	12.40 [315.0]
LACP2-16T24L1	29.57 [751.0]	24.40 [619.8]
LACP2-16T36L1	41.57 [1055.8]	36.40 [924.6]







LACP2-16TxxLxx

See our website www.AutomationDirect.com for complete Engineering drawings.

Accessories

	Compact Slide Actuator Accessories									
Part Number	Price	Description	Weight (lb)							
LAVLACC-003*	\$259.00	SureMotion motor adapter, NEMA 23 frame. For use with LAVL2-60 series actuators. 1/4 inch x 5 mm coupler included.	1.0							
LACPACC-0021	\$702.00	SureMotion repair kit, for use with LACP-16TxxLP5 actuators. Nut, bushings, end bearings and oil syringe included.	0.5							
LACPACC-0031	\$702.00	SureMotion repair kit, for use with LACP-16TxxL1 actuators. Nut, bushings, end bearings and oil syringe included.	0.5							
LACPACC-004	\$79.00	SureMotion mounting plate, XY type. For use with LACP2-16 series actuators.	0.5							
LACPACC-005	\$101.00	SureMotion mounting plate, XY type. For use with LACP2-16 and LARSB1 series actuators.	0.5							
LACPACC-006 ²	\$702.00	SureMotion repair kit, for use with LACP2-16TxxLP5 actuators. Nut, bushings, end bearings and oil syringe included.	1.0							
LACPACC-007 ²	\$702.00	SureMotion repair kit, for use with LACP2-16TxxL1 actuators. Nut, bushings, end bearings and oil syringe included.	1.0							

- * Use the coupling and motor mount screws from this kit to adapt any LACP2 actuator assembly to accept a NEMA 23 motor.
- ¹ These repair kits contain parts to rebuild Generation 1 (LACP series) acutator assemblies.
- ² These repair kits contain parts to rebuilt current Generation 2 (LACP2 series) actuator assemblies.



Some accessories not shown see www.AutomationDirect.com for additional product photos.

tMNC-81 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Notion Value Linear Slide Actuators - Generation 2



LAVL2-60T06LP2

Features

- · Small footprint
- · Adjustable carriage pre-load
- Replacement components available
- · Ready for NEMA 17 motor
- T-slots enable limit switches to be positioned anywhere

Low-cost linear actuator using the latest in sliding element technology. The base is a single piece design with integrated slide surfaces, and is hard anodized all over. This versatile unit can be mounted horizontally, vertically, or inverted without loss of load capacity.

Generation 2 actuators have a reduced part count for more reliable operation, integral sensor mount grooves on both sides and a more robust motor mount.

- · AISI 6061-T6 Aluminum Alloy base, hard anodized on all surfaces to a depth of 0.0005 to 0.0015'
- · AISI 304 Stainless Steel Lead Screw

Applications

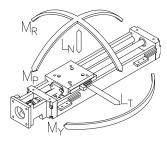
- · Harsh or wet environments
- · X-Y-Z positioning systems

	Value Linear Slide Actuator Specifications											
Part Number	Price	Drive Type	Drive Pitch	Drive Screw Efficiency (%)	Payload Inertia Factor (in ²)	Constant System Inertia (Ib _m -in ²)	Travel	Weight (lb)	Fits Motor			
LAVL2-60T06LP2	\$853.00				0.001	0.017	6in	2.0				
LAVL2-60T12LP2	\$1,069.00		0.2 in	47		0.020	12in	2.8				
LAVL2-60T18LP2	\$1,296.00		0.2 111	47		0.023	18in	3.5				
LAVL2-60T24LP2	\$1,512.00	Lead				0.027	24in	4.2	NEMA 17			
LAVL2-60T06LP5	\$853.00	screw				0.019	6in	2.0	INEIVIA 17			
LAVL2-60T12LP5	\$1,069.00		0.5 in	E-7	0.0062	0.022	12in	2.8				
LAVL2-60T18LP5	\$1,296.00		U.S III	57	0.0063	0.025	18in	3.5				
LAVL2-60T24LP5	\$1,512.00]				0.028	24in	4.2	1			

System Inertia Calculation:

To calculate the inertia reflected to the motor in a particular actuator, multiply the carriage payload by the payload inertia factor and then add the constant system inertia value for that actuator. The constant system inertia value for each system includes the inertia of the shaft coupler, carriage, and lead/ball screw.

• The payload must be in units of lb_m.



Load rating diagram

Value Linear Slide Actuator Load/Moment Ratings									
	Load (lb)				Moment (lb·in)*				
Part Number	Actuator	Normal – L _N		Transverse	Roll	Pitch	Yaw		
	Thrust	Down	Up	L _T	M_R	M_P	M_{Y}		
LAVL2-60TxxLP2	70	110	110	110	50	32	32		
LAVL2-60TxxLP5	50	110	110	110	50	32	32		

It is recommended that offset loads be located 5 inches or less from the center of the carriage. When the loads are offset at greater distances, the carriage can vibrate during travel.

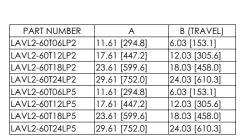
tMNC-82 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

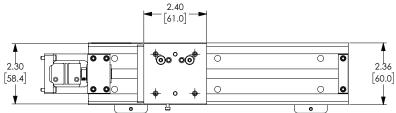


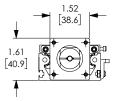
Linear Motion Products

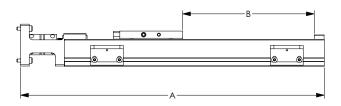
Value Linear Slide Actuators - Generation 2

Dimensions (in [mm])







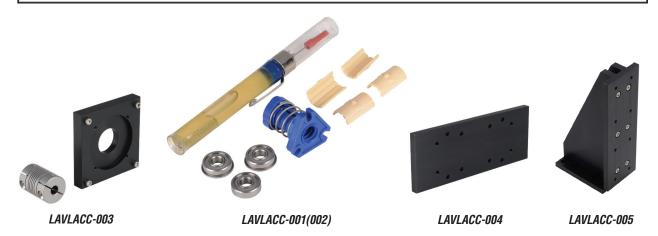


LAVL2-60TxxLPx

See our website www.AutomationDirect.com for complete Engineering drawings.

Accessories

Value Linear Slide Actuator Accessories									
Part Number	Price	Description	Weight (lb)						
LAVLACC-001*	\$312.00	SureMotion repair kit, for use with LAVL-60TxxLP2 actuators. Nut, bushings, end bearings and oil syringe included.	0.5						
LAVLACC-002*	\$312.00	SureMotion repair kit, for use with LAVL-60TxxLP5 actuators. Nut, bushings, end bearings and oil syringe included.	0.5						
LAVLACC-003	\$259.00	SureMotion motor adapter, NEMA 23 frame. For use with LAVL2-60 series actuators. 1/4 inch x 5 mm coupler included.	1.0						
LAVLACC-004	\$121.00	SureMotion mounting plate, XY type. For use with LAVL2-60 series actuators.	0.5						
LAVLACC-005	\$271.00	SureMotion mounting plate, XZ type. For use with LAVL2-60 series actuators.	1.0						
LAVLACC-006*	\$312.00	SureMotion repair kit, for use with LAVL2-60TxxLP2 actuators. Nut, bushings, end bearings and oil syringe included.	1.0						
LAVLACC-007*	\$312.00	SureMotion repair kit, for use with LAVL2-60TxxLP5 actuators. Nut, bushings, end bearings and oil syringe included.	1.0						
* Repair kits contain	replaceme	ent components that are the same as the original components in the actuator assemblies.							



Some accessories not shown see $\underline{www.AutomationDirect.com}$ for additional product photos.

tMNC-83 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Linear Motion Products Motion Round-Shaft Slide Elements Slide Rail Syste



LARSB1-12L12C

Description

Round-shaft sliding elements can be combined with other elements to build a huge variety of machine mechanisms. Available in both end- and continuously-supported shafts.

Features

- · Linear ball bearings
- High quality clear anodized aluminum blocks
- · AISI 1566 Carbon Steel, 60 RC Round Shafts

Slide Rail Sys	stems L	oad	Ratings		
Part Number	Norma Down	I (Ib) Up	Transverse (lb)		
Pillow Blocks /	Bushing	gs for	LARSA1		
LARSACC-001/007		23	30		
LARSACC-002/008		47	70		
LARSACC-003/009		85	50		
LARSA1 Line	ar Slide	Asse	mblies		
LARSA1-08LxxC		46	60		
LARSA1-12LxxC		94	40		
LARSA1-16LxxC		17	00		
Pillow Blocks /	Bushing	gs for	LARSB1		
LARSACC-004/010	230	161	230		
LARSACC-005/011	470	268	470		
LARSACC-006/012	850	485	850		
LARSB1 Line	ar Slide	Asse	mblies		
LARSB1-08LxxC	460 322 460				
LARSB1-12LxxC	940	536	940		
LARSB1-16LxxC	1700	970	1700		

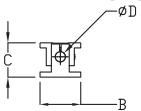
		EARIST FIGURE 1700 370	1700
		End-Supported Slide Rail Systems and Accessories	
Part Number	Price	Description	Weigh (lb)
LARSA1-08L12C	\$291.00	SureMotion, linear slide assembly, end supported, round shaft, 1/2 in diameter, 12 inch length, carbon steel. (2) single pillow blocks include	
LARSA1-08L24C	\$301.00	SureMotion, linear slide assembly, end supported, round shaft, 1/2 in diameter, 24 inch length, carbon steel. (2) single pillow blocks include	d. 2.0
LARSA1-08L36C	\$322.00	SureMotion, linear slide assembly, end supported, round shaft, 1/2 in diameter, 36 inch length, carbon steel. (2) single pillow blocks include	d. 2.7
LARSA1-12L12C	\$366.00	SureMotion, linear slide assembly, end supported, round shaft, 3/4 in diameter, 12 inch length, carbon steel. (2) single pillow blocks include	d. 3.0
LARSA1-12L24C	\$388.00	SureMotion, linear slide assembly, end supported, round shaft, 3/4 in diameter, 24 inch length, carbon steel. (2) single pillow blocks include	d. 4.5
LARSA1-12L36C	\$409.00	SureMotion, linear slide assembly, end supported, round shaft, 3/4 in diameter, 36 inch length, carbon steel. (2) single pillow blocks include	d. 6.0
LARSA1-16L12C	\$490.00	SureMotion, linear slide assembly, end supported, round shaft, 1 in diameter, 12 inch length, carbon steel. (2) single pillow blocks included.	6.0
LARSA1-16L24C	\$523.00	SureMotion, linear slide assembly, end supported, round shaft, 1 in diameter, 24 inch length, carbon steel. (2) single pillow blocks included.	8.5
LARSA1-16L36C	\$551.00	SureMotion, linear slide assembly, end supported, round shaft, 1 in diameter, 36 inch length, carbon steel. (2) single pillow blocks included.	11.0
LARSACC-001*	\$58.00	SureMotion single pillow block, closed type, linear ball bushing, 1/2 in inside diameter.	0.3
LARSACC-002*	\$72.00	SureMotion single pillow block, closed type, linear ball bushing, 3/4 in inside diameter.	0.6
LARSACC-003*	\$103.00	SureMotion single pillow block, closed type, linear ball bushing, 1 in inside diameter.	1.2
LARSACC-007*	\$22.00	SureMotion linear ball bushing, closed type, 1/2 in inside diameter, with seals, self-aligning.	0.1
LARSACC-008*	\$26.00	SureMotion linear ball bushing, closed type, 3/4 in inside diameter, with seals, self-aligning.	0.2
LARSACC-009*	\$42.00	SureMotion linear ball bushing, closed type, 1 in inside diameter, with seals, self-aligning.	0.3
		Continuously-Supported Slide Rail Systems and Accessories	
LARSB1-08L12C	\$301.00	SureMotion, linear slide assembly, continuously supported, round shaft, 1/2 in diameter, 12 in length, carbon steel. (2) single pillow blocks included	1. 2.0
LARSB1-08L24C	\$374.00	SureMotion, linear slide assembly, continuously supported, round shaft, 1/2 in diameter, 24 in length, carbon steel. (2) single pillow blocks included	1. 3.0
LARSB1-08L36C	\$466.00	SureMotion, linear slide assembly, continuously supported, round shaft, 1/2 in diameter, 36 in length, carbon steel. (2) single pillow blocks included	1. 4.5
LARSB1-12L12C	\$376.00	SureMotion, linear slide assembly, continuously supported, round shaft, 3/4 in diameter, 12 in length, carbon steel. (2) single pillow blocks included	l. 4.0
LARSB1-12L24C	\$490.00	SureMotion, linear slide assembly, continuously supported, round shaft, 3/4 in diameter, 24 in length, carbon steel. (2) single pillow blocks included	6.2
LARSB1-12L36C	\$601.00	SureMotion, linear slide assembly, continuously supported, round shaft, 3/4 in diameter, 36 in length, carbon steel. (2) single pillow blocks included	l. 9.0
LARSB1-16L12C	\$487.00	SureMotion, linear slide assembly, continuously supported, round shaft, 1 in diameter, 12 in length, carbon steel. (2) single pillow blocks included.	6.5
LARSB1-16L24C	\$630.00	SureMotion, linear slide assembly, continuously supported, round shaft, 1 in diameter, 24 in length, carbon steel. (2) single pillow blocks included.	10.5
LARSB1-16L36C	\$760.00	SureMotion, linear slide assembly, continuously supported, round shaft, 1 in diameter, 36 in length, carbon steel. (2) single pillow blocks included.	14.5
LARSACC-004*	\$62.00	SureMotion single pillow block, open type, linear ball bushing, 1/2 in inside diameter.	0.2
LARSACC-005*	\$80.00	SureMotion single pillow block, open type, linear ball bushing, 3/4 in inside diameter.	0.5
LARSACC-006*	\$112.00	SureMotion single pillow block, open type, linear ball bushing, 1 in inside diameter.	1.0
LARSACC-010*	\$26.00	SureMotion linear ball bushing, open type, 1/2 in inside diameter, with seals, self-aligning.	0.1
LARSACC-011*	\$32.00	SureMotion linear ball bushing, open type, 3/4 in inside diameter, with seals, self-aligning.	0.1
LARSACC-012*	\$54.00	SureMotion linear ball bushing, open type, 1 in inside diameter, with seals, self-aligning.	0.2
* Bushings and pillov	v blocks a	are replacement components that are the same as the original components in the slide assemblies.	

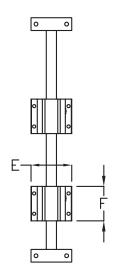
tMNC-84 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

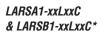


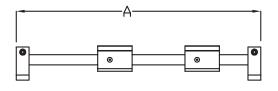
Linear IVIOLIANA Round-Shaft Slide Elements **Linear Motion Products**

Dimensions (in [mm])









PART #	А	В	С	ØD	Е	F		
LARSA1-08L12C	12.0 [304.8]							
LARSA1-08L24C	24.0 [609.6]	2.00 [50.8]	1.70 [42.9]	0.50 [12.7]	2.00 [50.8]	1.69 [42.9]		
LARSA1-08L36C	36.0 [914.4]							
LARSA1-12L12C	12.0 [304.8]							
LARSA1-12L24C	24.0 [609.6]	2.50 [63.5]	2.19 [55.6]	0.75 [19.0]	2.75 [69.9]	2.06 [52.4]		
LARSA1-12L36C	36.0 [914.4]							
LARSA1-16L12C	12.0 [304.8]							
LARSA1-16L24C	24.0 [609.6]	3.06 [77.8]	2.69 [68.3]	1.00 [25.4]	3.25 [82.6]	2.81 [71.5]		
LARSA1-16L36C	36.0 [914.4]							
LARSB1-08L12C*	12.0 [304.8]							
LARSB1-08L24C*	24.0 [609.6]	1.50 [38.1]	1.81 [46.0]	0.50 [12.7]	2.00 [50.8]	1.50 [38.1]		
LARSB1-08L36C*	36.0 [914.4]							
LARSB1-12L12C*	12.0 [304.8]							
LARSB1-12L24C*	24.0 [609.6]	1.75 [44.5]	2.44 [61.9]	0.75 [19.0]	2.75 [69.9]	1.88 [47.6]		
LARSB1-12L36C*	36.0 [914.4]							
LARSB1-16L12C*	12.0 [304.8]							
LARSB1-16L24C*	24.0 [609.6]	2.13 [54.0]	2.94 [74.6]	1.00 [25.4]	3.25 [82.6]	2.63 [66.7]		
LARSB1-16L36C*	36.0 [914.4]							
	*LARSA1-xxLxxC is shown in drawing. LARSB1-xxLxxC has different appearance, but same dimensions as shown in this table.							

See our website <u>www.AutomationDirect.com</u> for complete Engineering drawings.

tMNC-85 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5



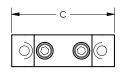


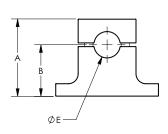
- Removable top design allows easy removal of shaft
- Maintains alignment while servicing shafts and bearings
- Lowest base to shaft height available
- Parallel and perpendicular surfaces for easy alignment
- Material: Aluminum 6061 T6 Gray, Hard Anodized
- Fasteners: Alloy Steel, Black Oxide
- Superior shaft holding strength

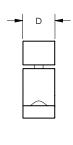


	Low Profile Aluminum Shaft Supports										
Part Number	Measurement	ØE	А	В	С	D	HSCS Screw Size	Price	Weight (lb)		
TMSSL-04		0.250	0.87	0.562	1.63	0.38	- #6	\$10.00	0.04		
TMSSL-06		0.375	1.00	0.625	1.75	0.38	#6	\$10.50	0.04		
TMSSL-08		0.500	1.19	0.750	2.00	0.50	#8	\$14.50	0.07		
TMSSL-10		0.625	1.44	0.938	2.63	0.50	#10	\$16.00	0.11		
TMSSL-12	inches	0.750	1.56	1.000	2.75	0.50	#10	\$17.00	0.12		
TMSSL-16		1.000	1.94	1.250	3.19	0.75	1/4	\$21.00	0.27		
TMSSL-20		1.250	2.31	1.500	3.75	0.75	5/16	\$26.50	0.37		
TMSSL-24		1.500	2.69	1.750	4.00	0.75		\$29.50	0.45		
TMSSL-32		2.000	3.31	2.125	5.00	1.25	3/8	\$39.50	1.11		
TMSSL-08M		8.0	21.0	12.0	44.0	10.0		\$14.00	0.04		
TMSSL-10M		10.0	25.0	14.0	46.0	12.0	M4	\$17.00	0.05		
TMSSL-12M		12.0	25.0	14.0	48.0	12.0		\$19.00	0.05		
TMSSL-16M		16.0	31.0	18.0	62.0	13.0	ME	\$21.00	0.10		
TMSSL-20M		20.0	36.0	22.0	65.0	13.0	- M5	\$24.00	0.12		
TMSSL-25M	mm	25.0	44.0	27.0	80.0	16.0	M6	\$28.50	0.20		
TMSSL-30M	1	30.0	52.0	32.0	96.0	20.0		\$35.00	0.35		
TMSSL-35M]	35.0	60.0	34.0	100.0	20.0	1	\$38.50	0.41		
TMSSL-40M	1	40.0	66.0	40.0	108.0	22.0	- M8	\$41.50	0.53		
TMSSL-50M		50.0	75.0	45.0	120.0	22.0	1	\$45.50	0.66		

Dimensions







Standard Steel Bolt/Screw Torque Specifications									
	Bolt/Scr	ew	Torq	jue*					
Size	Pitch	Туре	lb-in	lb-ft					
6	32	Low	8.7						
8	32	Carbon	17.8	_					
10	24	Steel	20.8						
1/4	20			10					
5/16	18	SAE Grade		19					
3/8	16	5 Med. Carbon	-	33					
7/16	14	Steel		54					
1/2	13			78					

^{*} It is recommended to use 50% of listed torque when using steel threads into aluminum material.

Metric Steel Bolt/Screw Torque Specifications									
l l	Bolt/Screw Torque*								
Size	Size Pitch Type								
M3	0.5		0.6						
M4	0.7	Standard	1.5						
M5	0.8	5D Med.	3.0						
M6	1.0	Carbon Steel	5.2						
M8	1.25	Sieei	12.5						
M10	1.50		24.0						

^{*} It is recommended to use 50% of listed torque when using steel threads into aluminum material.

See our website <u>www.AutomationDirect.com</u> for complete Engineering drawings.



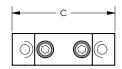


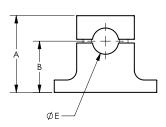
- · Removable top design allows easy removal of shaft
- Maintains alignment while servicing shafts and bearings
- Parallel and perpendicular surfaces for easy alignment
- Material: Aluminum 6061 T6 Black, Hard Anodized
- Fasteners: Alloy Steel, Black Oxide
- Superior shaft holding strength
- Interchangable with industry standard supports

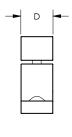


	Standard Profile Aluminum Shaft Supports									
Part Number	Measurement	ØE	A	В	С	D	HSCS Screw Size	Price	Weight (lb)	
TMSS-04		0.250	1.00	0.687	1.50	0.50	#6	\$20.00	0.05	
TMSS-06		0.375	1.13	0.750	1.63	0.56	#0	\$21.00	0.06	
TMSS-08		0.500	1.50	1.000	2.00	0.63	#8	\$22.00	0.11	
TMSS-10		0.625	1.50	1.000	2.50	0.69	#10	\$23.00	0.15	
TMSS-12	inches	0.750	1.81	1.250	2.75	0.75	#10	\$25.00	0.21	
TMSS-16		1.000	2.19	1.500	3.25	1.00	1/4	\$27.50	0.40	
TMSS-20		1.250	2.63	1.750	4.00	1.13	5/16	\$33.00	0.66	
TMSS-24		1.500	3.00	2.000	4.75	1.25	3/10	\$37.00	0.96	
TMSS-32		2.000	3.75	2.500	6.00	1.50	3/8	\$49.50	1.79	
TMSS-08M		8.0	23.0	15.0	32.0	10.0	M2.5	\$21.00	0.03	
TMSS-12M		12.0	30.0	20.0	40.0	12.0	M3	\$22.00	0.05	
TMSS-16M		16.0	38.0	25.0	50.0	16.0	M4	\$23.00	0.11	
TMSS-20M	mm	20.0	45.0	30.0	60.0	20.0	M5	\$25.00	0.19	
TMSS-25M		25.0	55.0	35.0	74.0	25.0	M6	\$27.50	0.35	
TMSS-30M		30.0	63.0	40.0	84.0	28.0	M8	\$30.50	0.50	
TMSS-40M		40.0	80.0	50.0	108.0	32.0	M10	\$42.50	0.92	

Dimensions







Standard Steel Bolt/Screw Torque Specifications									
	Bolt/Scr	ew	Torq	ue*					
Size	Pitch	Туре	lb-in	lb-ft					
6	32	Low	8.7						
8	32	Carbon	17.8	-					
10	24	Steel	20.8						
1/4	20			10					
5/16	18	SAE Grade		19					
3/8	16	5 Med. Carbon	_	33					
7/16	14	Steel		54					
1/2	13			78					

^{*} It is recommended to use 50% of listed torque when using steel threads into aluminum

Metric Steel Bolt/Screw Torque Specifications									
Bolt/Screw Torque*									
Size	Pitch	Туре	N∙m						
M3	0.5		0.6						
M4	0.7	Standard	1.5						
M5	0.8	5D Med.	3.0						
M6	1.0	Carbon Steel	5.2						
M8	1.25	Sieei	12.5						
M10	1.50		24.0						
+ 14 !			0/ -61:-44						

^{*} It is recommended to use 50% of listed torque when using steel threads into aluminum material.

See our website <u>www.AutomationDirect.com</u> for complete Engineering drawings.

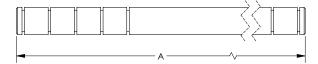


- · Retaining ring grooved
- Groove spacing to fit typical bearings
- RB-83 Hardness
- 10RMS Surface Finish
- ± 0.010" length tolerance + 0.0000" / 0.0002" diameter tolerance for 0.250 to 0.500 + 0.0000" / 0.0004" diameter tolerance for 0.625 to 1.000



	Grooved Shafts - 303 Stainless Steel									
Part Number	Groove Spacing	Number of Grooves	A	ØВ	Price	Weight (lb)				
GSS04-3			3.0		\$3.25	0.04				
GSS04-6	0.250	7	6.0	0.250	\$4.50	0.08				
GSS04-10		/	10.0	0.230	\$6.75	0.14				
GSS04-12			12.0		\$7.25	0.17				
GSS06-3			3.0		\$6.50	0.10				
GSS06-6	0.375	7	6.0	0.275	\$11.50	0.19				
GSS06-10	0.375	/	10.0	0.375	\$18.00	0.32				
GSS06-12			12.0		\$22.00	0.38				
GSS08-3			3.0		\$9.50	0.17				
GSS08-6	0.437	7	6.0	0.500	\$17.00	0.34				
GSS08-10	0.437		10.0		\$27.00	0.57				
GSS08-12			12.0		\$29.00	0.68				
GSS10-3		6	3.0	0.625	\$13.50	0.26				
GSS10-6	0.500		6.0		\$27.00	0.52				
GSS10-10	0.500	7	10.0		\$46.00	0.87				
GSS10-12			12.0		\$54.00	1.05				
GSS12-3		6	3.0		\$16.00	0.38				
GSS12-6			6.0	0.750	\$30.00	0.75				
GSS12-10		7	10.0	0.750	\$53.00	1.25				
GSS12-12	0.562		12.0		\$64.00	1.50				
GSS16-3	0.502	6	3.0		\$27.00	0.67				
GSS16-6			6.0	1.000	\$55.00	1.33				
GSS16-10		7	10.0	1.000	\$84.00	2.22				
GSS16-12			12.0		\$101.00	2.67				
Note: All measurements in	inches									

Dimensions





See our website www.AutomationDirect.com for complete Engineering drawings.



- 15-7 PH Stainless Steel E-rings
- Stainless Steel shims



	Grooved Shaft Accessories							
Part Number	Description	Price	Weight (lb)					
GSS04-RPK	6 Retainer Rings and 6 Shirns for GSS04-xx series Grooved Shafts	\$2.25	0.02					
GSS06-RPK	6 Retainer Rings and 6 Shirns for GSS06-xx series Grooved Shafts	\$2.50	0.03					
GSS08-RPK	6 Retainer Rings and 6 Shirns for GSS08-xx series Grooved Shafts	\$3.00	0.04					
GSS10-RPK	6 Retainer Rings and 6 Shims for GSS10-xx series Grooved Shafts	\$9.25	0.04					
GSS12-RPK	6 Retainer Rings and 6 Shirns for GSS12-xx series Grooved Shafts	\$9.50	0.05					
GSS16-RPK	6 Retainer Rings and 6 Shims for GSS16-xx series Grooved Shafts	\$13.00	0.05					

tMNC-89 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Precision Ground Rotary Shafts 303 Stainless Steel



Rota	ry Shafts	- 303 S	tainless S	teel
Part Number	A	ØВ	Price	Weight (lb)
RPSS02-3	3.0	0.125	\$2.50	0.02
RPSS02-6	6.0	0.125	\$3.75	0.03
RPSS02-12	12.0	0.125	\$5.50	0.08
RPSS02-24	24.0	0.125	\$11.00	1.15
RPSS02-36	36.0	0.125	\$15.00	1.41
RPSS03-3	3.0	0.1875	\$2.75	0.03
RPSS03-6	6.0	0.1875	\$4.50	0.06
RPSS03-12	12.0	0.1875	\$6.75	0.12
RPSS03-24	24.0	0.1875	\$12.00	1.23
RPSS03-36	36.0	0.1875	\$16.00	1.64
RPSS04-3	3.0	0.25	\$3.25	0.04
RPSS04-6	6.0	0.25	\$4.75	0.08
RPSS04-12	12.0	0.25	\$7.25	0.16
RPSS04-24	24.0	0.25	\$14.50	1.31
RPSS04-36	36.0	0.25	\$22.00	1.76
RPSS06-12	12.0	0.375	\$20.00	0.38
RPSS06-24	24.0	0.375	\$33.00	1.75
RPSS06-36	36.0	0.375	\$46.00	2.42
RPSS08-12	12.0	0.50	\$25.00	0.71
RPSS08-24	24.0	0.50	\$43.00	2.41
RPSS08-36	36.0	0.50	\$57.00	3.41
RPSS10-12	12.0	0.625	\$41.00	1.04
RPSS10-24	24.0	0.625	\$78.00	3.07
RPSS10-36	36.0	0.625	\$113.00	4.40
RPSS12-12	12.0	0.75	\$44.00	1.52
RPSS12-18	18.0	0.75	\$68.00	3.13
RPSS12-24	24.0	0.75	\$89.00	4.03
RPSS12-36	36.0	0.75	\$134.00	5.84
RPSS16-12	12.0	1.00	\$75.00	2.71
RPSS16-18	18.0	1.00	\$112.00	4.92
RPSS16-24	24.0	1.00	\$150.00	6.41
RPSS16-36	36.0	1.00	\$225.00	9.41
RPSS20-12	12.0	1.25	\$97.00	4.22
RPSS20-18	18.0	1.25	\$138.00	7.18
RPSS20-24	24.0	1.25	\$192.00	9.43
RPSS20-36	36.0	1.25	\$265.00	13.94

Features

- RB75-90 Hardness
- 10RMS Surface Finish
- Straightness: up to 1/4" diameter: 0.0004 in/in over 1/4" diameter: 0.0006 in/in
- 45 ° chamfer on both ends on diameters 0.1875" and over; rough cut on 0.125" diameter
- \pm 0.010" length tolerance + 0.0000" / 0.0002" diameter tolerance on 1/2" and smaller diameters + 0.0000" / 0.0004" diameter tolerance on 5/8" and larger diameters

Dimensions





See our website www.AutomationDirect.com for complete Engineering drawings.

Note: All measurements in inches



Precision Ground Linear Shafts 1060 Steel and 440C Stainless Steel



Features

- C1060 steel
- RC60-65 Hardness
- 10RMS Surface Finish

- Tolerance: Class L ± 1/32" length tolerance + 0.0000" / 0.0005" diameter tolerance



L	inear Sh	afts - 1	060 Stee	
Part Number	A	ØB	Price	Weight (lb)
LPCS08-12	12.0	0.50	\$8.25	0.71
LPCS08-24	24.0	0.50	\$18.00	2.41
LPCS08-36	36.0	0.50	\$26.50	3.41
LPCS12-12	12.0	0.75	\$12.00	1.52
LPCS12-24	24.0	0.75	\$24.00	4.03
LPCS12-36	36.0	0.75	\$35.00	5.84
LPCS16-12	12.0	1.0	\$18.00	2.71
LPCS16-24	24.0	1.0	\$35.00	6.41
LPCS16-36	36.0	1.0	\$47.50	9.41
Note: All measure	ments in in	ches		



Features

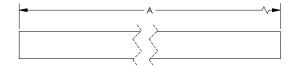
- 440C Stainless steel
- RC50-55 Hardness
- 10RMS Surface Finish

- Tolerance: Class L ± 1/32" length tolerance + 0.0000" / 0.0005" diameter tolerance



Linear	Shafts	- 440C S	Stainless	Steel
Part Number	A	ØB	Price	Weight (lb)
LPSS08-12	12.0	0.50	\$21.50	0.71
LPSS08-24	24.0	0.50	\$43.00	2.41
LPSS08-36	36.0	0.50	\$65.00	3.41
LPSS12-12	12.0	0.75	\$31.00	1.52
LPSS12-24	24.0	0.75	\$62.00	4.03
LPSS12-36	36.0	0.75	\$93.00	5.84
LPSS16-12	12.0	1.0	\$44.00	2.71
LPSS16-24	24.0	1.0	\$87.00	6.41
LPSS16-36	36.0	1.0	\$131.00	9.41
Note: All measure	ments in in	nches		

Dimensions





See our website www.AutomationDirect.com for complete Engineering drawings.

tMNC-91 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5



iglide® Plastic Plain Bearings

 $igus^{@}$ iglide $^{@}$ plastic bearings are economical, dry-running and maintenance-free. Offered in three of the most popular materials with or without flanges, these plain bearings are an excellent choice for a wide range of motion applications.

Features

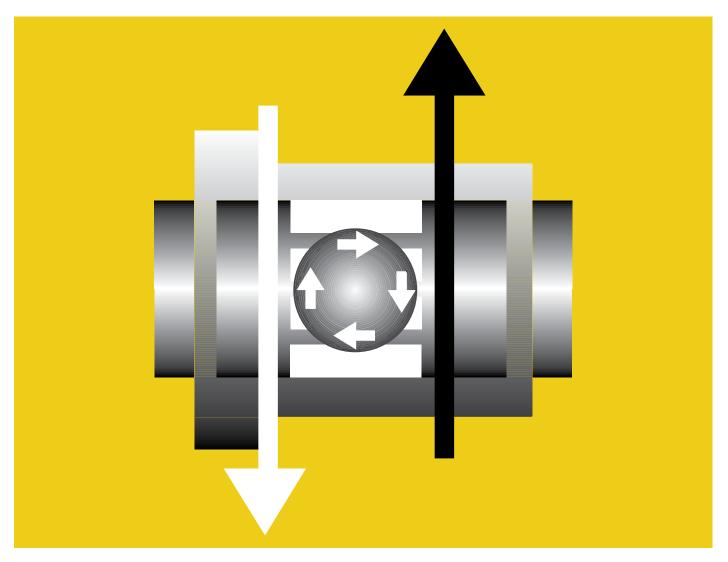
- 3 popular materials J (low friction), G300 (general purpose), T500 (high temp)
- Sleeve and flange bearings
- Fits shafts from 1/4" to 1"
- Good chemical resistance
- Link to selection guide materials





		igus	s® iglide® F	Plain Bearing	js .				
Item Photo	Part Number	Material	Size I.D. (inch)	Size O.D. (inch)	Flange	Qty. per Package	Weight (lb)	Price	Drawing Link
	A-JSI-0406-04		1/4	3/8		10	0.19	\$7.75	PDF
	A-JSI-0810-08		1/2	5/8) N. (10	0.04	\$10.00	PDF
	A-JSI-1214-12		3/4	7/8	No '	5	0.03	\$9.00	PDF
	A-JSI-1618-16		1	1-1/8		2	0.44	\$5.75	PDF
	A-JFI-0406-04	J	1/4	3/8		10	0.02	\$8.00	PDF
	A-JFI-0810-08		1/2	5/8	, , , , , , , , , , , , , , , , , , ,	10	0.49	\$12.00	PDF
	A-JFI-1214-12		3/4	7/8	Yes	5	0.49	\$9.25	PDF
	A-JFI-1618-16		1	1-1/8		2	0.04	\$5.75	PDF
	A-GSI-0405-04		1/4	5/16		10	0.02	\$7.25	PDF
	A-GSI-0809-08		1/2	9/16	- No	10	0.03	\$8.00	<u>PDF</u>
	A-GSI-1214-12		3/4	7/8		5	0.04	\$9.50	<u>PDF</u>
	A-GSI-1618-16		1	1-1/8		2	0.04	\$6.50	<u>PDF</u>
	A-GFI-0405-04	G300	1/4	5/16		10	0.02	\$7.25	PDF
	A-GFI-0809-08		1/2	9/16	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	10	0.04	\$8.75	PDF
	A-GFI-1214-12		3/4	7/8	Yes	5	0.05	\$10.50	PDF
	A-GFI-1618-16		1	1-1/8		2	0.03	\$6.50	PDF
	A-TSI-0405-04		1/4	5/16		5	0.02	\$13.50	PDF
	A-TSI-0809-08		1/2	9/16	Na	5	0.02	\$15.00	PDF
	A-TSI-1214-12		3/4	7/8	- No	2	0.03	\$17.50	PDF
	A-TSI-1618-16	T500	1	1-1/8		2	0.03	\$22.50	PDF
	A-TFI-0405-04	1500	1/4	5/16		5	0.01	\$14.50	PDF
	A-TFI-0809-08		1/2	9/16] Voc	5	0.02	\$23.00	PDF
	A-TFI-1214-12		3/4	7/8	Yes	2	0.02	\$18.50	PDF
	A-TFI-1618-16		1	1-1/8		2	0.04	\$24.00	PDF

tMNC-92 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

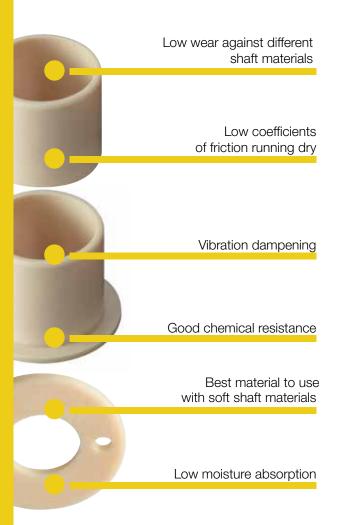


iglide® J

- Low wear against different shaft materials
- Low coefficients of friction running dry
- Vibration dampening
- Good chemical resistance
- Low moisture absorption

iglide® J - The fast and slow motion specialist

Low friction, low wear



The iglide® J plain bearings are designed for the lowest coefficients of friction while running dry and their low stick-slip tendency. With a maximum permissible surface pressure of 5,076 psi iglide® J bearings are not suitable for extreme loads.



Best Applications

- For high speeds
- For highest wear resistance at low to medium pressures
- When very low coefficients of friction are necessary
- When a cost effective bearing for low pressure loads is needed



Not For Use In Applications

When high pressure loads occur

➤ iglide® G300

When short-term temperatures occur that are greater than 248°F

➤ iglide® G300

When a low-cost bearing for occasional movements is necessary

➤ iglide® G300



Typical application areas

- Automation
- Printing industry
- Cleanroom
- Aerospace engineering
- Beverage technology
- Automation



max. +194°F

min. –58°F



Ø 1/4 to 1 inch more sizes available from igus





Ø 1.5 to 110 mm metric sizes available from igus



Material Properties Table

General Properties	Unit	iglide® J	Testing Method
Density	g/cm ³	1.49	
Color		yellow	
Max. moisture absorption at 73°F / 50% r.h.	% weight	0.3	DIN 53495
Max. moisture absorption	% weight	1.3	
Coefficient of friction, dynamic against steel	μ	0.06 - 0.18	
pv value, max. (dry)	psi x fpm	9,700	

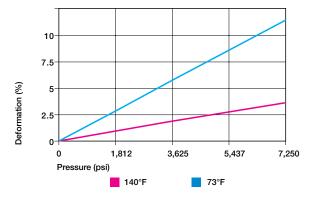
Mechanical Properties			
Modulus of elasticity	psi	348,100	DIN 53457
Tensile strength at 68°F	psi	10,590	DIN 53452
Compressive strength	psi	8,702	
Permissible static surface pressure (68°F)	psi	5,076	
Shore D-hardness		74	DIN 53505

Physical and Thermal Properties			
Max. long-term application temperature	°F	194	
Max. application temperature, short-term	°F	248	
Min. application temperature	°F	-58	
Thermal conductivity	W/m x K	0.25	ASTM C 177
Coefficient of thermal expansion	K ⁻¹ x 10 ⁻⁵	10	DIN 53752

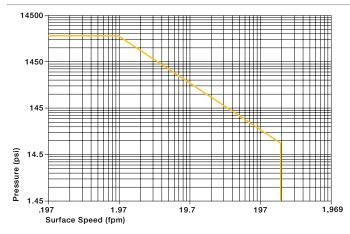
Electrical Properties			
Specific volume resistance	Ωcm	> 1013	DIN IEC 93
Surface resistance	Ω	> 1012	DIN 53482

Compressive Strength

With a maximum permissible surface pressure of 5,075 psi, iglide® J plain bearings are not suited for extreme loads. The graph shows the elastic deformation of iglide® J for radial loads. At the maximum permissible load of 5,075 psi, the deformation is less than 2.5%.



Deformation under load and temperature



Permissible pv value for iglide $^{\circ}$ J running dry against steel shaft, at 68°F

Permissible Surface Speeds

The low coefficient of friction and the extremely low stick-slip tendency of iglide® J plain bearings are especially important at very low speeds. However, iglide® J material can also be used for high speeds of over 197 fpm. In both cases, the static friction is very low and stick-slip does not occur. The maximum values given in the table can only be achieved at the lowest pressure loads. At the given speeds, friction can cause a temperature increase to maximum permissible levels. In practice, though, this temperature level is rarely reached, due to varying application conditions.

	Continuous	Short Term
	fpm	fpm
Rotating	295	590
Oscillating	216	413
Linear	1574	1968

Maximum surface speeds

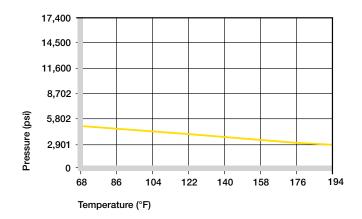
iglide® J - Technical data

Temperatures

iglide® J plain bearings can be used between -58°F and 194°F; the short-term maximum permissible temperature is 248°F. The graph shows that the compressive strength of iglide® J plain bearings decreases with increasing temperatures. Also, the wear increases significantly above 176°F

iglide® J	Application Temperature
Minimum	- 58°F
Max. long-term	+194°F
Max. short-term	+248°F
Additional axial securing	+140°F

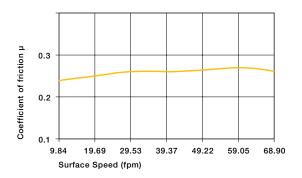
Temperature limits for iglide® J



Recommended maximum permissible static surface pressure of iglide® J as a result of the temperature

Friction and Wear

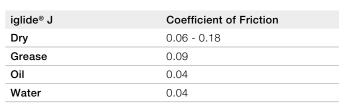
The graph to the right shows the coefficients of friction for different loads. The coefficient of friction level is very good for all loads with iglide® J. Friction and wear are also dependent, to a large extent, on the shafting partner. With increasing shaft roughness, the coefficient of friction also increases. For iglide® J a ground surface with an average roughness range of 4 - 12 rms is recommended for the shaft.



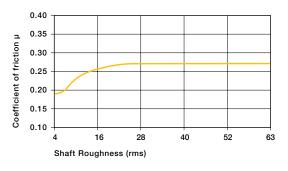
Coefficient of friction of iglide® J as a result of the surface speed; $p = 108 \ psi$

	0.30								
	0.25								
п	0.20	$\vdash \setminus$							
Coefficient of friction µ	0.15	$\vdash \setminus$							
nt of	0.10								
fficie	0.05								
Coe	0.00								
		0 72	25 14	50 21	75 29	00 36	25 43	50 507	75
		Pressur	e (psi)						

Coefficient of friction of iglide® J as a result of the load, v = 1.97 fpm



Coefficients of friction for iglide® J against steel (Shaft finish = 40 rms, 50 HRC)



Coefficient of friction of iglide® J as a result of the shaft surface (1050 hard chromed)

iglide® J - Technical data

Shaft Materials

The graphs show results of testing different shaft materials with plain bearings made

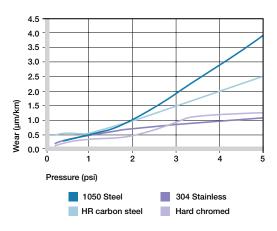
If iglide® J plain bearings are used in rotational applications with loads under 290 psi, several shaft materials are suitable. A Hard Chromed shaft provides the lowest wear in this range. When compared to most iglide® materials, iglide® J has very low wear results at low loads with all shaft materials tested.

Also, for increasing loads up to 725 psi, the wear resistance of iglide® J is excellent. Especially suitable is the combination of 303 stainless steel.

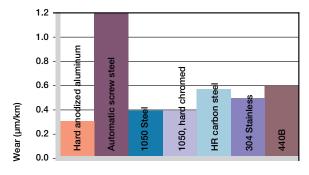
In oscillating operation with Cold Rolled Steel and HR Carbon Steel, the wear of iglide® J is slightly higher than for rotation. For oscillating movements with loads of 290 psi, iglide® J performs best with Cold Rolled Steel shaft.

As shown in the graph, the difference in wear between rotation and oscillating movements is most significant for 303 stainless steel shafts.

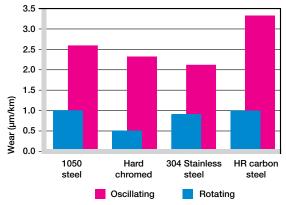
If the shaft material you plan to use is not contained in this list, please contact us.



Wear of iglide® J, rotating application with different shaft materials, depending on load



Wear of iglide® J, rotating application with different shaft materials, p = 108 psi, v = 98 fpm



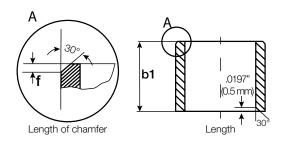
Wear for oscillating and rotating applications with different shaft materials under constant load p = 290 psi

For Inch Size Bearings

Installation Tolerances

iglide® J plain bearings After proper installation the inner diameter adju Please adhere to the ca and recommended shaf performance of iglide® p

	r or more died boarings			
s are oversized before being pressfit.	Length Tolerance (b1)			
n into a recommended housing bore, usts to meet our specified tolerances.	Length (inches)	Tolerance (h13)	Length of Chamfer (f) Based on d1	
catalog specifications for housing bore	0.1181 to 0.2362	-0.0000 /-0.0071	f = .012 → d ₁ .040"236"	
ift sizes. This will help to ensure optimal	0.2362 to 0.3937	-0.0000 /-0.0087	f = .019 → d ₁ > .236"472"	
plain bearings.	0.3937 to 0.7086	-0.0000 /-0.0106	f = .031 → d ₁ > .472" - 1.18"	
	0.7086 to 1.1811	-0.0000 /-0.0130	$f = .047 \rightarrow d_1 > 1.18$ "	
	1.1811 to 1.9685	-0.0000 /-0.0154		
	1.9685 to 3.1496	-0.0000 /-0.0181		



For Metric Size Bearings			
erance (b1)			
Tolerance (h13)	Length of Chamfer (f) Based on d1		
-0 /-140	$f = 0.3 \rightarrow d_1 \ 1 - 6 \ mm$		
-0 /-180	$f = 0.5 \rightarrow d_1 > 6 - 12 \text{ mm}$		
-0 /-220	$f = 0.8 \rightarrow d_1 > 12 - 30 \text{ mm}$		
-0 /-270	$f = 1.2 \rightarrow d_1 > 30 \text{ mm}$		
-0 /-330			
-0 /-390			
-0 /-460			
	erance (b1) Tolerance (h13) (mm) -0 /-140 -0 /-180 -0 /-220 -0 /-270 -0 /-330 -0 /-390		

iglide® J - Technical data

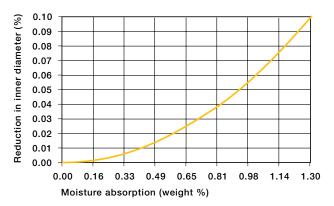
Chemical Resistance

iglide® J plain bearings are resistant to diluted lyes and very weak acids, as well as fuels and all types of lubricants. The low moisture absorption also permits use in wet or damp environments. Plain bearings made of iglide® J are resistant to common cleaning agents used in the food industry. The moisture absorption of iglide® J plain bearings is 0.3% in standard atmosphere. The saturation limit in water is 1.3%. These values are so low that possible design changes due to absorption are only necessary in extreme cases.

Medium	Resistance
Alcohol	+
Hydrocarbon	+
Greases, oils without additives	+
Fuels	+
Weak acids	0 to -
Strong acids	_
Weak alkaline	+
Strong alkaline	+ to 0

⁺ resistant, 0 conditionally resistant, - not resistant

Chemical resistance of iglide® J All data given concerns the chemical resistance at room temperature (68°F).



Effect of moisture absorption on iglide® J plain bearings

Radiation Resistance

Plain bearings made from iglide® J are resistant to radiation up to an intensity of 3 x 10² Gy.

UV-Resistance

iglide® J plain bearings become discolored under UV radiation. However, hardness, compressive strength and the wear resistance of the material do not change.

Vacuum

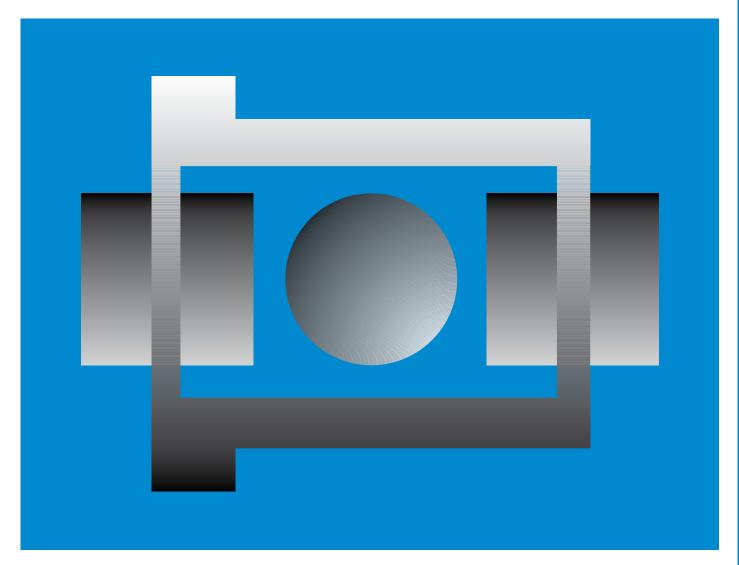
When used in a vacuum environment, the iglide® J plain bearings release moisture as a vapor. Therefore, only dehumidified bearings made of iglide® J are suitable for the vacuum environment.

Electrical Properties

iglide® J plain bearings are electrically insulating.

iglide® J	
Specific volume resistance	> 10 ¹³ Ωcm
Surface resistance	> 10 ¹² Ω

Electrical properties of iglide® G300



iglide® G300

- High wear resistance
- Resistance to dust and dirt
- Economic
- Self-lubricating and maintenance free

iglide® G300 - General Purpose

Most popular iglide® material worldwide



Maintenance-free, dry running

High wear resistance

iglide® G300 bearings cover an extremely wide range of different requirements. Typical applications include medium to high loads, medium sliding speeds and medium temperatures. Typical applications include medium to high loads, medium sliding speeds and medium temperatures.



Resistant to dirt and dust



Cost-effective



Best Applications

- When you need an economical all-around performance
- For low to average surface speeds
- When the bearing needs to run on different shaft
- For oscillating and rotating movements



Not For Use In Applications

- When mechanical reaming of the wall surface is necessary
- When the highest wear resistance is necessary
- When universal chemical resistance is required ➤ iglide® T500
- If temperatures are constantly greater than +266°F ➤ iglide® T500
- For underwater use

max.

min.



Typical application areas

- Agricultural machines
- Machine building
- Sports and leisure
- Automotive



 Construction machinery



+266°F

-40°F



Ø 1/4 to 1 inch more sizes available from igus





Ø 1.5 to 150 mm metric sizes available from igus



Material Properties Table

General Properties	Unit	iglide® G300	Testing Method
Density	g/cm³	1.46	
Color		dark gray	
Max. moisture absorption at 73°F / 50% r.h.	% weight	0.7	DIN 53495
Max. moisture absorption	% weight	4.0	
Coefficient of friction, dynamic against steel	μ	0.08 - 0.15	
pv value, max. (dry)	psi x fpm	12,000	

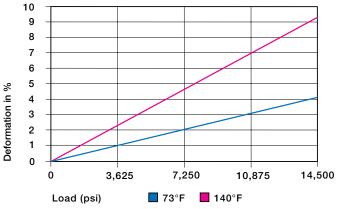
Mechanical Properties			
Modulus of elasticity	psi	1,131,000	DIN 53457
Tensile strength at 68°F	psi	30,460	DIN 53452
Compressive strength	psi	11,310	
Permissible static surface pressure (68°F)	psi	11,600	
Shore D-hardness		81	DIN 53505

Physical and Thermal Properties			
Max. long-term application temperature	°F	266	
Max. application temperature, short-term	°F	428	
Min. application temperature	°F	-40	
Thermal conductivity	W/m x K	0.24	ASTM C 177
Coefficient of thermal expansion	K ⁻¹ x 10 ⁻⁵	9	DIN 53752

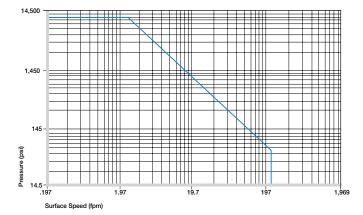
Electrical Properties			
Specific volume resistance	Ωcm	> 1013	DIN IEC 93
Surface resistance	Ω	> 1011	DIN 53482

Compressive Strength

The graph shows the elastic deformation of iglide® G300 during radial loading. At the maximum permissible load of 11,600 psi, the deformation is less than 5%. The plastic deformation is minimal up to a pressure of approximately 14,500 psi. However, it is also a result of the cycle time.



Deformation under load and temperature



Permissible pv value for iglide® G300 running dry against a steel shaft, at 68°F

Permissible Surface Speeds

iglide® G300 has been developed for low to medium surface speeds. The maximum values shown in the table can only be achieved at low pressure loads. At the given speeds, friction can cause a temperature increase to maximum permissible levels. In practice, though, this temperature level is rarely reached, due to varying application conditions.

	Continuous	Short Term
	fpm	fpm
Rotating	196	393
Oscillating	137	275
Linear	787	984

Maximum surface speeds

Temperatures

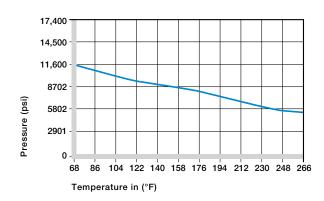
Application temperatures affect the properties of plain bearings greatly. The short-term maximum temperature is 428°F, this allows the use of iglide® G300 plain bearings in heat treating applications in which the bearings are not subjected to additional loading.

With increasing temperatures, the compressive strength of iglide® G300 plain bearings decreases. The graph shows this inverse relationship. However, at the long-term maximum temperature of 266°F, the permissible surface pressure is still above 5,800 psi.

The ambient temperatures that are prevalent in applications also has an effect on the bearing wear. With increasing temperatures, the wear increases and this effect is notable starting at the temperature of 248°F.

iglide® G300	Application Temperature
Minimum	- 40°F
Max. long-term	+266°F
Max. short-term	+428°F
Additional axial securing	+176°F

Temperature limits for iglide® G300

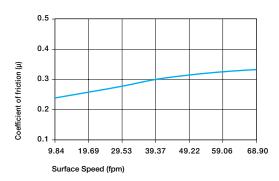


Recommended maximum permissible static surface pressure of iglide® G300 as a result of temperature

Friction and Wear

Similar to wear resistance, the coefficient of friction μ also changes with the load. The coefficient of friction decreases with increasing loads, whereas an increase in surface speed causes an increase of the coefficient of friction. This relationship explains the excellent results of iglide® G300 plain bearings for high loads and low speeds.

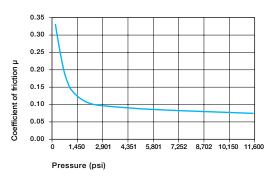
The friction and wear are also dependent, to a large degree, on the shaft partner. Shafts that are too smooth, increase both the coefficient of friction and the wear of the bearing. For iglide® G300, a ground surface with an average roughness Ra= 32 rms is recommended.



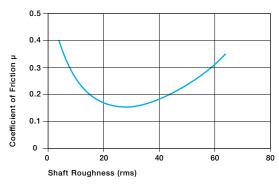
Coefficient of friction of iglide® G300 as a result of the running speed; p = 108 psi

iglide® G300	Coefficient of Friction
Dry	0.08 - 0.15
Grease	0.09
Oil	0.04
Water	0.04

Coefficient of friction for iglide® G300 against steel (Shaft finish = 40 rms, 50 HRC)



Coefficient of friction of iglide® G300 as a result of the load, v = 1.96 fpm



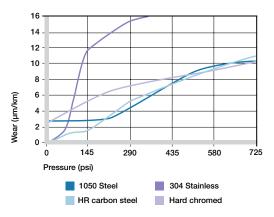
Coefficient of friction as result of the shaft surface (Shaft - 1050 hard chromed)

Shaft Materials

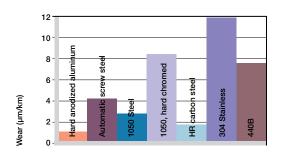
The graphs show results of testing different shaft materials with plain bearings made of iglide® G300. In the graph below it is observed that iglide® G300 can be combined with various shaft materials. The simple shaft materials of free-cutting steel and HR Carbon Steel have proven best at low loads. This helps to design cost-effective systems, since both iglide® G300 and the sliding partner are economically priced.

It is important to note that with increasing loads, the recommended hardness of the shaft increases. The "soft" shafts tend to wear more easily and thus increase the wear of the overall system. If the loads exceed 290 psi, it is important to recognize that the wear rate (the slope of the curves) clearly decreases with the hard shaft materials.

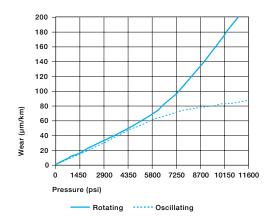
The comparison of rotational movements to oscillating movements shows that iglide® G300 can provide advantages in oscillating movements. The wear of the bearing is smaller for equivalent conditions. The higher the load, the larger the difference. This means that iglide® G300 can be used for oscillating movements that are well above the given maximum load of 11,600 psi. For these loads, the use of hardened shafts is recommended. In addition to the shaft materials presented here, many others have been tested. If the shaft material you plan on using is not contained in the test results presented here, please contact us.



Wear with different shaft materials in rotational operation, as a result of the load



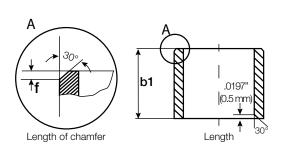
Wear of iglide® G300, rotating with different shaft materials, load p = 145 psi, v = 59 fpm



Wear for pivoting and rotating applications with shaft material 1050 hard chromed, as a result of the load

Installation Tolerances

iglide® G300 plain bearings are oversized before being pressfit. After proper installation into a recommended housing bore, the inner diameter adjusts to meet our specified tolerances. Please adhere to the catalog specifications for housing bore and recommended shaft sizes. This will help to ensure optimal performance of iglide® plain bearings.



For Inch Size Bearings		
Length Tolerance (b1)		
Length (inches)	Tolerance (h13) (inches)	Length of Chamfer (f) Based on d1
0.1181 to 0.2362	-0.0000 /-0.0071	f = .012 → d ₁ .040"236"
0.2362 to 0.3937	-0.0000 /-0.0087	f = .019 → d ₁ > .236"472"
0.3937 to 0.7086	-0.0000 /-0.0106	$f = .031 \rightarrow d_1 > .472" - 1.18"$
0.7086 to 1.1811	-0.0000 /-0.0130	$f = .047 \rightarrow d_1 > 1.18$ "
1.1811 to 1.9685	-0.0000 /-0.0154	
1.9685 to 3.1496	-0.0000 /-0.0181	

For Metric Size Bearings			
Length Tolerance (b1)			
Length (mm)	Tolerance (h13)	Length of Chamfer (f) Based on d1	
1 to 3	-0 /-140	$f = 0.3 \rightarrow d_1 \ 1 - 6 \ mm$	
> 3 to 6	-0 /-180	$f = 0.5 \rightarrow d_1 > 6 - 12 \text{ mm}$	
> 6 to 10	-0 /-220	$f = 0.8 \rightarrow d_1 > 12 - 30 \text{ mm}$	
>10 to 18	-0 /-270	$f = 1.2 \rightarrow d_1 > 30 \text{ mm}$	
>18 to 30	-0 /-330		
>30 to 50	-0 /-390		
>50 to 80	-0 /-460		

Chemical & Moisture Resistance

iglide® G300 plain bearings have strong resistance to chemicals. They are also resistant to most lubricants.

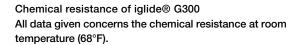
iglide® G300 plain bearings are not affected by most weak organic and inorganic acids.

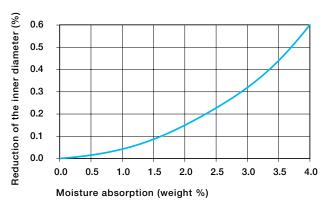
The moisture absorption of iglide® G300 plain bearings is approximately 1% in the standard atmosphere. The saturation limit submerged in water is 4%. This must be taken into account for these types of applications.

➤ Chemical table, Page 1364

+ to 0
+ 10 0
+
+
+
0 to -
-
+
0

⁺ resistant, 0 conditionally resistant, - not resistant





Effect of moisture absorption on iglide® G300 plain bearings

Radiation Resistance

Plain bearings made from iglide® G300 are resistant to radiation up to an intensity of 3 x 10² Gy.

UV-Resistance

iglide® G300 plain bearings are permanently resistant to UV-radiation.

Vacuum

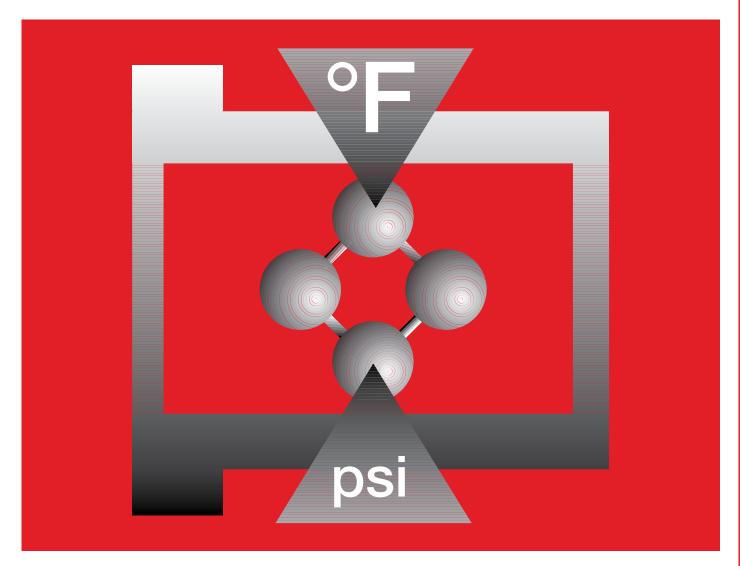
iglide® G300 plain bearings outgas in a vacuum. Use in a vacuum environment is only possible for dehumidified bearings.

Electrical Properties

iglide® G300 plain bearings are electrically insulating.

iglide® G300			
Specific volume resistance	> 10 ¹³ Ωcm		
Surface resistance	> 10 ¹¹ Ω		

Electrical properties of iglide® G300

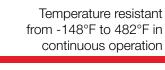


iglide® T500

- Temperature resistant from -148°F to 482°F in continuous operation
- Universal resistance to chemicals
- High compressive strength
- Very low moisture absorption
- Excellent wear resistance through the entire temperature range

iglide® T500 - High-Tech Problem Solver

High temperature and chemical resistance



iglide® T500 is defined by its combination of high temperature resistance with compressive strength, along with high resistance to chemicals. iglide® T500 is designed for higher speeds than other iglide® bearings.



Universal resistance to chemicals



High compressive strength

Very low moisture absorption



Excellent wear resistance through the entire temperature range



Best Applications

- When especially high temperature resistance is necessary
- For pressure loads up to 21,760 psi
- For linear movements with a hard stainless steel
- For linear movements especially at high temperatures
- When universal resistance to chemicals is required
- Very low moisture absorption



Not For Use In Applications

- For very low wear at high loads
- For economical underwater applications
- For edge compression



Typical application areas

- Beverage technology
- Woodworking
- Aerospace engineering
- Cleanroom
- Plastic processing industry



max. +482°F min. -148°F



Ø 1/4 to 1 inch more sizes available from igus





Ø 2 to 75 mm metric sizes available from igus



Material Properties Table

General Properties	Unit	iglide® T500	Testing Method
Density	g/cm³	1.44	
Color		black	
Max. moisture absorption at 73°F / 50% r.h.	% weight	0.1	DIN 53495
Max. moisture absorption	% weight	0.5	
Coefficient of friction, dynamic against steel	μ	0.09 - 0.27	
pv value, max. (dry)	psi x fpm	37,700	

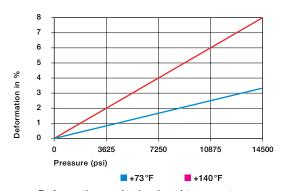
Mechanical Properties			
Modulus of elasticity	psi	1,174,800	DIN 53457
Tensile strength at 68°F	psi	24,660	DIN 53452
Compressive strength	psi	14,500	
Permissible static surface pressure (68°F)	psi	21,760	
Shore D-hardness		85	DIN 53505

Max. long-term application temperature	°F	482	
Max. application temperature, short-term	°F	599	
Min. application temperature	°F	-148	
Thermal conductivity	W/m x K	0.6	ASTM C 177
Coefficient of thermal expansion	K ⁻¹ x 10 ⁻⁵	5	DIN 53752

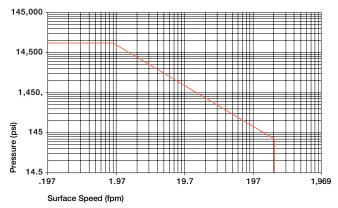
Electrical Properties			
Specific volume resistance	Ωcm	< 105	DIN IEC 93
Surface resistance	Ω	< 103	DIN 53482

Compressive Strength

The graph shows the special compression resistance of iglide® T500 also at very high temperatures. Even at the highest long-term application temperature of 482°F, iglide® T500 plain bearings still withstand a static surface pressure of approximately 4350 psi.



Deformation under load and temperature



Permissible pv values for iglide® T500 running dry against a steel shaft, at 68°F

Permissible Surface Speeds

iglide® T500 is designed for higher speeds than other iglide® bearings. This is due to its high temperature resistance and excellent heat conductivity. These benefits are readily apparent in the pv values of max. 37,700 psi x fpm. However, only the smallest radial loads may act on the bearings. At the given speeds, friction can cause a temperature increase to maximum permissible levels.

	Continuous	Short Term
	fpm	fpm
Rotating	295	689
Oscillating	216	492
Linear	984	1968

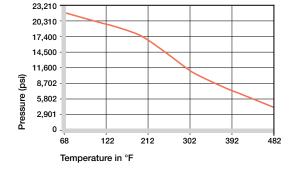
Maximum surface speeds

iglide® T500 - Technical Data

Temperatures

In terms of temperature resistance, iglide® T500 has taken on a leading position. Having a permissible long-term application temperature of 482°F, iglide® T500 will even withstand 599°F for the short-term.

As in all thermoplastics, the compression resistance of T500 decreases with increasED temperature. However, the wear drops considerably when used within the observed temperature range of 73°F to 302°F. In certain cases, relaxation of the bearing can occur at temperatures greater than 275°F. This could lead to the bearing moving out of the housing after re-cooling. At temperatures over 275°F, the axial securing of the bearing in the housing needs to be tested. If necessary, secondary measures must be taken to mechanically secure the bearing. Please contact us if you have questions on bearing use.



Recommended maximum permissible static surface pressure of iglide® T500 as a result of temperature

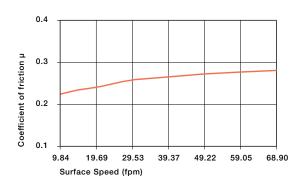
iglide® T500	Application Temperature
Minimum	- 148°F
Max. long-term	+482°F
Max. short-term	+599°F
Additional axial securing	+275°F

Temperature limits for iglide® T500

Friction and Wear

Similar to wear resistance, the coefficient of friction μ also changes with the load. The coefficient of friction increases with an increase in surface speed. On the other hand, an increased load has an inverse effect: the coefficient of friction decreases. This explains the excellent performance of iglide® T500 plain bearings for high loads.

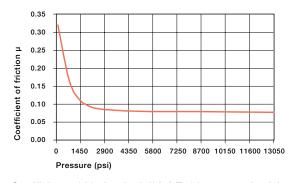
Friction and wear are also dependent to a large degree on the shafting partner. Shafts that are too smooth increase the coefficient of friction of the bearing. For iglide® T500, a ground surface with an average roughness range of 24 - 32 rms is recommended for the shaft.



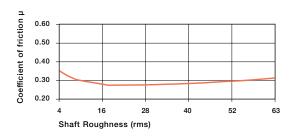
Coefficient of friction for iglide® T500 as a result of the surface speed; p = 108 psi, 1050 hard chromed

iglide® T500	Coefficient of Friction
Dry	0.09 - 0.27
Grease	0.09
Oil	0.04
Water	0.04

Coefficient of friction for iglide® T500 against steel (Shaft finish = 40 rms, 50 HRC)



Coefficient of friction for iglide® T500 as a result of the load, ν = 1.97 fpm



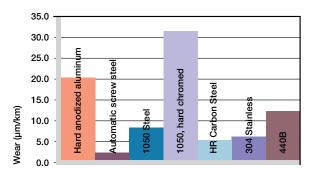
Coefficients of friction as a function of the shaft surface (1050 hard chromed)

iglide® T500 - Technical Data

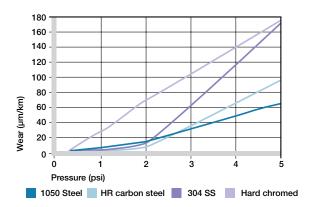
Shaft Materials

The graphs show results of testing different shaft materials with plain bearings made of iglide® T500. For low loads in rotating operation, the best wear values are found with 303 Stainless and HR Carbon Steel shafts. However, above a load of 290 psi, the bearing wear greatly increases with these two shaft materials. For the higher load range, hard-chromed shafts or Cold Rolled Steel shafts are advantageous. In oscillating operation at low loads, similar wear values for cold rolled steel and 303 stainless steel shafts occur. The wear is somewhat higher than during rotational movements.

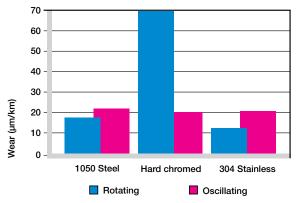
If the shaft material you plan to use is not contained in this list, please contact us.



Wear of iglide® T500 with different shaft materials, p = 108 psi, v = 98 fpm



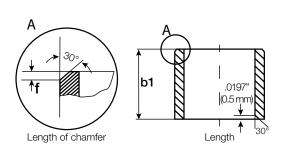
Wear of iglide® T500 with different shaft materials in rotational operation



Wear for oscillating and rotating applications with different shaft materials p = 290 psi

Installation Tolerances

iglide® T500 plain bearings are oversized before being pressfit. After proper installation into a recommended housing bore, the inner diameter adjusts to meet our specified tolerances. Please adhere to the catalog specifications for housing bore and recommended shaft sizes. This will help to ensure optimal performance of iglide® plain bearings.



For Inch Size Bearings								
Length Tol	erance (b1)							
Length (inches)	Tolerance (h13) (inches)	Length of Chamfer (f) Based on d1						
0.1181 to 0.2362	-0.0000 /-0.0071	f = .012 → d ₁ .040"236"						
0.2362 to 0.3937	-0.0000 /-0.0087	$f = .019 \rightarrow d_1 > .236"472"$						
0.3937 to 0.7086	-0.0000 /-0.0106	$f = .031 \rightarrow d_1 > .472" - 1.18"$						
0.7086 to 1.1811	-0.0000 /-0.0130	$f = .047 \rightarrow d_1 > 1.18$ "						
1.1811 to 1.9685	-0.0000 /-0.0154							
1.9685 to 3.1496	-0.0000 /-0.0181							

For Metric Size Bearings							
Length To	olerance (b1)						
Length (mm)	Tolerance (h13)	Length of Chamfer (f) Based on d1					
1 to 3	-0 /-140	$f = 0.3 \rightarrow d_1 \ 1 - 6 \ mm$					
> 3 to 6	-0 /-180	$f = 0.5 \rightarrow d_1 > 6 - 12 \text{ mm}$					
> 6 to 10	-0 /-220	$f = 0.8 \rightarrow d_1 > 12 - 30 \text{ mm}$					
>10 to 18	-0 /-270	$f = 1.2 \rightarrow d_1 > 30 \text{ mm}$					
>18 to 30	-0 /-330						
>30 to 50	-0 /-390						
>50 to 80	-0 /-460						

iglide® T500 - Technical Data

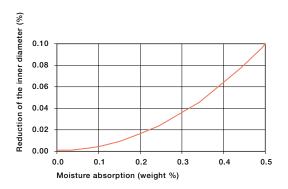
Chemical Resistance

iglide® T500 plain bearings are close to universally resistant to chemicals. They are only attacked by concentrated nitric acid and by sulfuric acid with acidity levels over 65%. The list at the end of this catalog provides more comprehensive detailed information.

Medium	Resistance
Alcohol	+
Hydrocarbon	+
Greases, oils without additives	+
Fuels	+
Weak acids	+
Strong acids	-
Weak alkaline	+
Strong alkaline	+

⁺ resistant, 0 conditionally resistant, - not resistant

Chemical resistance of iglide® T500 All data given concerns the chemical resistance at room temperature (68°F).



Effect of moisture absorption on iglide® T500 plain bearings

Radiation Resistance

Plain bearings made from iglide® T500 are resistant to radiation up to an intensity of 1x10⁵ Gy. iglide® T500 is the most radioactive-resistant material of the iglide® product line. iglide® T500 is extremely resistant to hard gamma radiation and withstands a radiation dose of 1000 Mrad without detectable change in its properties. The material also withstands an alpha or beta radiation of 10,000 Mrad with practically no damage.

UV Resistance

The excellent material properties of iglide® T500 do not change under UV radiation and other weathering effects.

Vacuum

In a vacuum environment, iglide® T500 plain bearings can be used virtually without restrictions. Outgassing takes place to a very limited extent.

Electrical Properties

iglide® T500 plain bearings are electrically conductive.

iglide® T500	
Specific volume resistance	< 105 Ωcm
Surface resistance	< 10 ³ Ω

Electrical properties of iglide® T500



igubal® Mounted Spherical Bearings

 $igus^{\circledR}$ $igubal^{\circledR}$ mounted spherical bearings are made with high quality engineered polymers. They are lubrication-free and maintenance-free. These bearings are lighter and more economical than traditional mounted spherical bearings.

Features

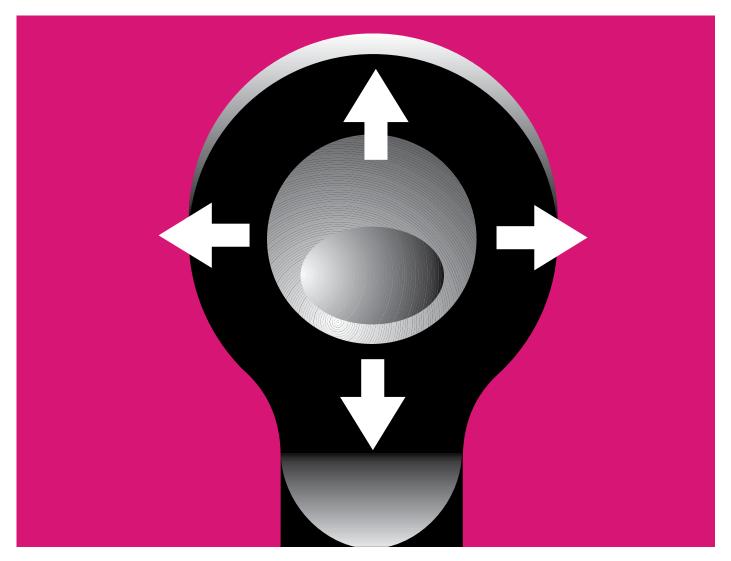
- Five popular mounting configurations
- Four popular shaft sizes
- Maintenance-free
- Excellent wear resistance
- L280 polymer type bearing material



	ig	us® igubal® M	lounted Sph	erical Bear	ings			
Item Photo	Part Number	Style	Size I.D. (inch)	Thread/ Housing Type	Qty. per Package	Weight (lb)	Price	Drawing Link
	A-KBRI-04		1/4	1/4-28 UNF female	4	0.06	\$14.50	<u>PDF</u>
	A-KBRI-08	K Series, Female	1/2	1/2-20 UNF female	2	0.12	\$21.50	<u>PDF</u>
	A-KBRI-12	Thread, Rod End	3/4	3/4-16 UNF female	1	0.14	\$17.00	<u>PDF</u>
A- A- A- A- A- A- A- A-	A-KBRI-16		1	1-12 UNF female	1	0.46	\$20.00	PDF
A-I	A-KARI-04		1/4	1/4-28 UNF male	4	0.04	\$14.00	<u>PDF</u>
	A-KARI-08	K Series,	1/2	1/2-20 UNF male	2	0.10	\$14.00	<u>PDF</u>
	A-KARI-12	Male Thread, Rod End	3/4	3/4-16 UNF male	1	0.10	\$11.00	PDF
	A-KARI-16		1	1-12 UNF male	1	0.34	\$18.00	<u>PDF</u>
	A-KSTI-04		1/4	Pillow block -	4	0.02	\$10.50	PDF
	A-KSTI-08	K Series,	1/2		2	0.07	\$14.50	<u>PDF</u>
191.00 tollar	A-KSTI-12	Pillow Block	3/4		1	0.09	\$9.00	<u>PDF</u>
	A-KSTI-16		1		1	0.20	\$15.00	<u>PDF</u>
	A-EF0I-04		1/4		4	0.03	\$14.00	<u>PDF</u>
	A-EFOI-08	E Series,	1/2	- 2-bolt flange	2	0.05	\$14.50	<u>PDF</u>
	A-EFOI-12	2-Bolt Flange	3/4	Z-DUIL HAHYE	1	0.09	\$13.00	<u>PDF</u>
	A-EFOI-16		1		1	0.14	\$16.50	<u>PDF</u>
	A-EFSI-04		1/4		4	0.04	\$20.00	<u>PDF</u>
	A-EFSI-08	E Series,	1/2	4-bolt flange	2	0.04	\$15.50	<u>PDF</u>
0	A-EFSI-12	4-Bolt Flange	3/4	4-buil hange	1	0.12	\$12.00	<u>PDF</u>
	A-EFSI-16		1		1	0.17	\$14.50	<u>PDF</u>

 ϵ

tMNC-111 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



igubal® Rod Ends

- Self-lubricating, maintenance-free
- High strength under impact loads
- High tensile strength
- Compensation of misalignment
- Compensation of edge loads
- Very low weight

igubal® Rod Ends

igubal® rod ends can also be used in rough environments. They are corrosion-resistant in humid environments and resistant to weak acids and bases. The operation temperature is from -40°F up to +176°C. Rod ends are also resistant to dirt and dust.





- If you want to save weight
- For rotating, oscillating and linear movements
- If high-frequency oscillations/vibrations occur
- If silent operation is required
- If you need an electrically insulating part
- If corrosion resistance is required
- In combination with pneumatic cylinders and gas struts
 If chemical resistance is required
- If high rigidity is required



Not For Use In Applications

- If temperatures are higher than +176°F
- If rotation speeds higher than 98.4 fpm (0.5 m/s) are required
- If really high tensile and shear loads occur
- With a hydraulic cylinder
- If dimensions above 1 inch or 30 mm are required





max. +392°F min. -40°F



Ø 1/4 to 1 inch more sizes available from igus



Ø 2 to 30 mm metric sizes available from igus





Typical application areas

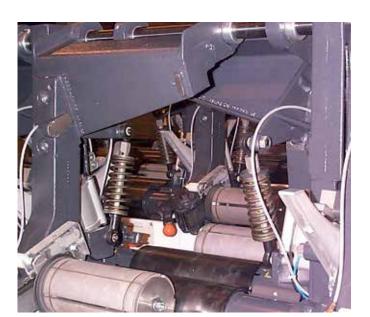
- ◆ Agricultural machines◆ Mec
- Machine building
- Sports and leisure
- Automotive
- Mechatronics
- Construction machinery



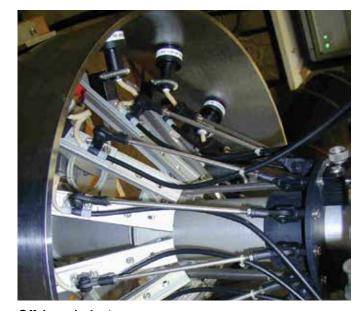
Specialty bikes



Packaging industry



Textile industry



Offshore industry

igubal® Rod Ends - Technical data

Advantages

- Maintenance-free
- High strength under impact loads
- Very high tensile strength for varying loads
- Compensation for misalignment
- Compensation for edge loads
- Resistant to dirt, dust and lint
- Resistant to corrosion and chemicals
- High vibration dampening capacity
- Suitable for rotating, oscillating and linear movements
- Lightweight
- Dimensional K series and E series, dimensions according to standard DIN ISO 12240

Product range

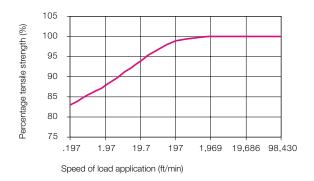
igubal[®] rod ends are available in the dimensional K series and E series for shaft diameters of 3/16 to 1 inch and 2 to 30 mm.

- Form A with male thread and
- Form B with female thread

The dimensional K series and, to a limited extent, E are available in inch dimensions, as well as a special version containing a stainless steel sleeve in the inner race. This allows a significantly higher torque than for the standard plastic race.

Loads

igubal® rod end bearings handle high loads at normal room temperatures, have excellent dampening properties and weigh only a fifth of traditional metallic rod end bearings. In applications with high continuous loads and high temperatures, the loading capacity of igubal® rod end bearings should be tested in an experiment that duplicates the application.



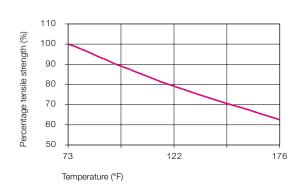
Effect of the speed of load application on the maximum tensile strength of igubal® rod end bearings

Coefficients of Friction and Speed

One important advantage of igubal® spherical bearings is that rapid, rotary movements of a mounted shaft take place directly in the spherical portion. In metallic rod ends, rotary motion takes place between the race and the spherical bearing. High speeds can be achieved with igubal® bearings.

igubal® bearings ares used in such a way that the angular movements of the spherical bearings take place at the spherical outer diameter. In contrast, rotations of the shaft are supported directly in the inner diameter of the spherical portion. The advantage, therefore, lies in the plastic vs. steel relationship. Plastic produces lower friction and permits high speeds, even when running dry.

The maintenance-free igubal® bearing system is also suited for linear and oscillating shaft movements.



Effect of the temperature on the maximum tensile strength of igubal® rod end bearings

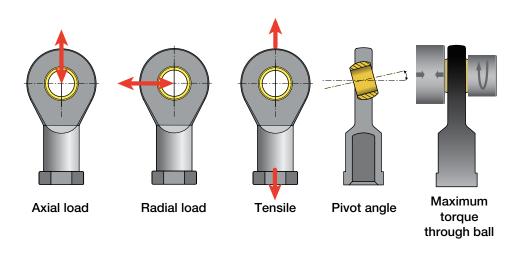
Temperatures

The igubal® rod ends can be used in temperatures from –22°F up to +176°F. igubal® rod ends made of HT-Material are suitable for temperatures from -40°F up to +392°F (E series, types A and B).

igubal® Rod Ends - Technical data

Tolerances

igubal® rod end bearings can be used at different tolerances depending on the individual application. As a standard program, they are designed with a large amount of bearing clearance, which permits secure operation even at high rotational speeds. The bore of the inner race is produced within a standard tolerance range. Shafts should also meet recommended tolerances.

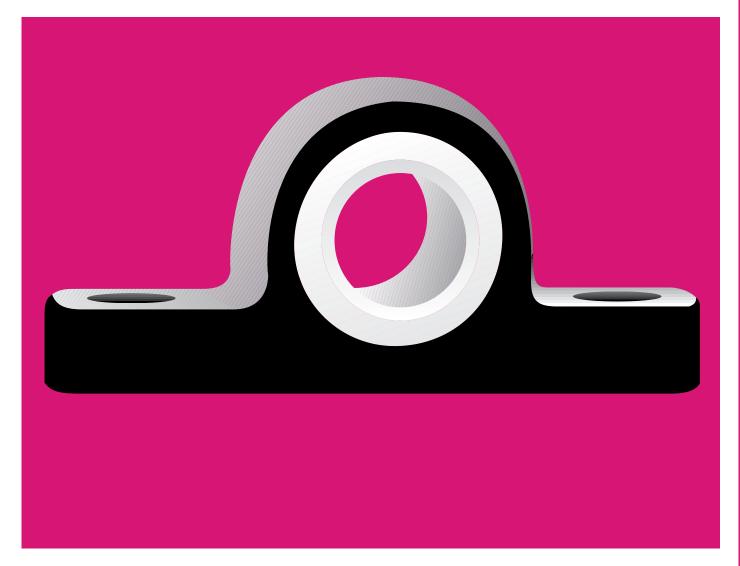


Recommended Shaft Tolerances

Inch	Shaft		Metric	Sh	aft
	Min.	Max.		Min.	Max.
3/16	0.1888	0.1900	2mm	1.975	2.000
1/4	0.2485	0.2500	3mm	2.975	3.000
5/16	0.3110	0.3125	5mm	4.970	5.000
3/8	0.3735	0.3750	6mm	5.970	6.000
7/16	0.4358	0.4375	8mm	7.964	8.000
1/2	0.4983	0.5000	10mm	9.964	10.000
5/8	0.6235	0.6250	12mm	11.957	12.000
3/4	0.7479	0.7500	16mm	15.957	16.000
1	0.9980	1.0000	20mm	19.948	20.000

Thread pitches of the igubal® rod end bearings

Thread Name	Pitch (mm)
M 2	0.40
M 3	0.50
M 4	0.70
M 5	0.80
M 6	1.00
M 8	1.25
M 10	1.50
M 10 F	1.25
M 12	1.75
M 12 F	1.25
M 14	2.00
M 16	2.00
M 16 F	1.50
M 18	1.50
M 20	2.50
M 20 M 20	1.50
M 22	1.50
M 24	2.00
M 27	2.00
M 30	2.00



igubal® Pillow Block

- Maintenance-free, dry running
- High tensile strength
- High endurance strength
- Can be used in combination with E series rod ends
- Lightweight

igubal® Pillow Block

The igubal® pillow block bearings consist of a housing with a bearing insert. igubal® pillow block bearings are especially easy to install, able to compensate for misalignment and prevent edge loads.





- If chemical resistance is required
- If a cost-effective option is requested
- If you need dirt-resistant bearings
- To account for misalignment
- If you need split components





Not For Use In Applications

- If temperatures are higher than +176°F
- If an integrated fixing collar is required
- If diameters above 1 inch or 50 mm are required
- If rotation speeds higher than 98.4 fpm (0.5 m/s) are required



max. +176°F min. -22°F



Ø 1/4 to 1 inch more sizes available from igus



Ø 5 to 50 mm metric sizes available from igus



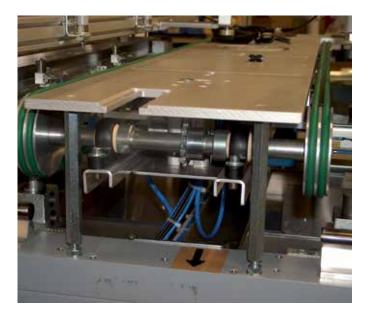


Typical application areas

- Plant design
- Machine building
- Packaging etc.



Stone processing



Paper industry



Solar technology



Packaging industry

igubal® Pillow Block - Technical data

General information

igubal® pillow blocks are made of igumid G according to DIN 71752. The pillow blocks are available in a variety of configurations. igubal® pillow blocks can be used in difficult circumstances without any problems. The pillow blocks are corrosion resistant in moist or wet environments and the sliding bearings are resistant to weak acids and alkalis. The operating temperatures range from -22°F to +176°F. igubal® pillow blocks are made out of a high-wear resistant material which requires no external lubrication.

Advantages

- Maintenance-free, self-lubricating
- High rigidity
- High strength under impact loads
- Compensation for misalignment
- Compensation for edge loads
- Corrosion-free
- Chemically resistant
- Vibration damping
- Suitable for rotating, oscillating and linear movements
- Lightweight
- High radial loads
- Can be used in liquid media
- Space-saving design
- Easy to install
- Predictable lifetime

Chemical resistance

The ability to pivot allows igubal® pillow block bearings to compensate for misalignment and possible shaft deflection. Applications where these effects cannot be prevented are suited for igubal pillow block bearings.

Tolerances

Maintenance-free igubal® pillow block bearings are designed with inside diameter tolerance of E10. The shaft should be made to tolerance class h6 to h9. These recommended tolerances allow for changes in the bearing due to temperature and moisture absorption.

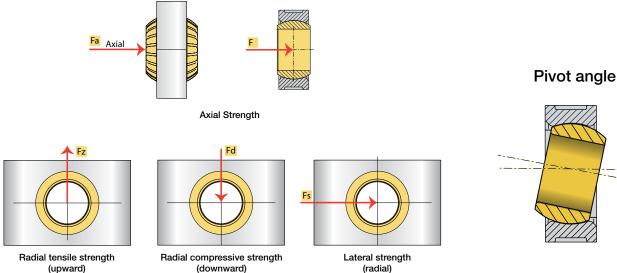
Mounting

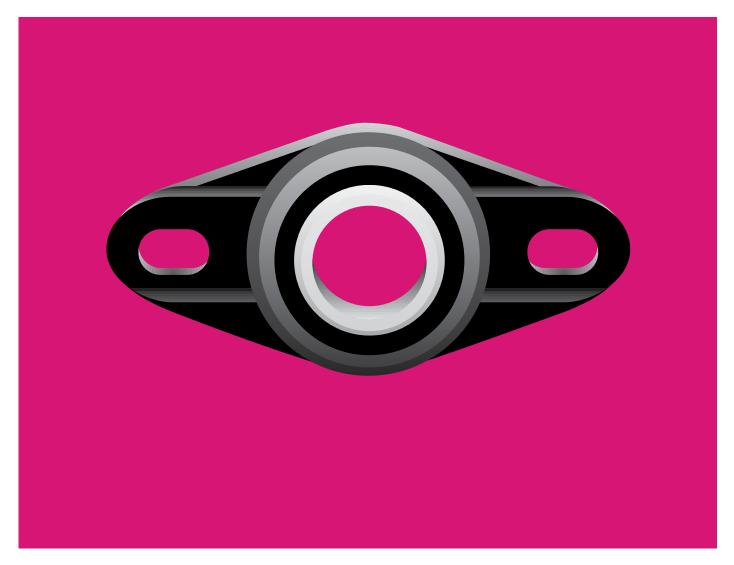
igubal® pillow block bearings are designed for mounting with 2 bolts. Precision mounting of the bearing is not necessary, since the spherical ball compensates for misalignment.

Loads

The load capacity of the maintenance-free igubal® bearing elements is very high at normal ambient temperatures. igubal® bearings absorb high forces and weigh only one fifth of traditional, metal bearing housings. The excellent dampening properties are based on the fact that the polymer material of the two part bearing can absorb vibrations differently than steel.

However, plastic specific properties, such as dependence on temperature and behavior under long-term stress, must be taken into consideration when using igubal® bearings. The load capacity of the pillow block should therefore be checked in a practical test, particularly if it will be used under continuous high loads and at elevated temperatures.





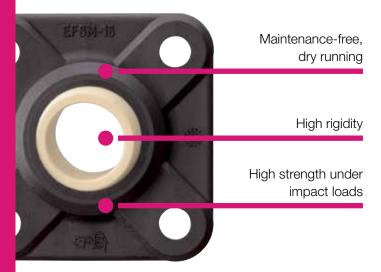
igubal® Flange Bearing

- Maintenance-free, dry running
- High tensile strength
- High endurance strength
- Compensation for alignment errors
- Compensation for edge loads
- Lightweight

tMNC-121

igubal® Flange Bearing

igubal® Flange bearings have been developed for the support of shaft ends or for shafts lead-through. Like all igubal® products, these bearings consist of an igumid G housing and an iglide® L280 spherical ball (with other options available). igubal® Flange bearings are made to the dimensional E series and are offered with two or four mounting holes.





- If chemical resistance is required
- If a cost-effective option is requested
- If you need dirt-resistant bearings
- To adjust misalignment
- If you need split components





Not For Use In Applications

- If temperatures are higher than +176°F
- If an integrated fixing collar is required
- If diameters above 1 inch or 50 mm are required
- If rotation speeds higher than 98.4 fpm (0.5 m/s) are required



max. +176°F min. -40°F



Ø 3/8 to 1 inch more sizes available from igus



Ø 4 to 50 mm metric sizes available from igus

igubal® Flange Bearing - Application examples





Typical application areas

- Plant design
- Automation
- Agricultural machines
- Machine building
- Food industry etc.





Rotary sorter



Solar industry



Food industry

igubal® Flange Bearing - Technical data

General Properties

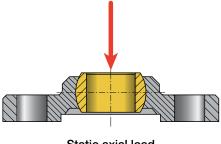
igubal® Flange bearings have been developed for the support of shaft ends or for shafts lead-through. Like all igubal® products, these bearings consist of an igumid G housing and an iglide® L280 spherical ball (with other options available). igubal® Flange bearings are made to the dimensional E series and are offered with two or four mounting holes.

Areas of Application

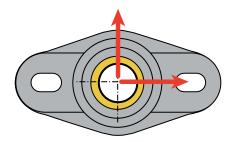
Since igubal® flange bearings are made for maintenance-free use, they are especially suited for applications in which access to the bearing is limited, in moist or wet environments or cleanroom environments. Thus, igubal® flange bearings are also found in electric toothbrushes, awnings, conveyor technology, bakery machines and agriculture to name a few.

Installation

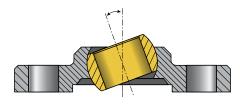
igubal® flange bearings are designed for mounting with 2 or 4 bolts, depending on the design. The 2-hole types are provided with elongated holes, which allow a problem-free adjustment. An exact positioning of the bearing housing is not necessary, since the spherical ball compensates for misalignment.



Static axial load



Static radial load



Pivot Angle

igus[®]

DryLin® R Linear Plain Bearings

 $igus^{\circledR}$ DryLin $^{\circledR}$ R linear plain bearings are dimensionally interchangeable with other popular brands, but offer a low cost alternative to recirculating ball bearings. The low friction liner makes DryLin R suitable for wet or dirty enviornments.

Features

- Dimensionally interchangeable with ball bearings
- Available in four shaft diameters in both fixed and self-aligning housings
- Type J polymer is an excellent all-purpose sliding material
- Ideally suited to work with Drylin R hard-anodized aluminum shafting



 ϵ

igus® DryLin® R Linear Plain Bearings											
Item Photo	Part Number	Housing Fit	Size I.D. (inch)	Length (inch)	Housing Type	Bearing Material	Housing Material	Qty. per Package	Weight (lb)	Price	Drawing Link
	A-RJZI-01-04		1/4	3/4			Anodized	1	0.00	\$9.25	<u>PDF</u>
	A-RJUI-01-08		1/2	1-1/4			aluminum	1	0.04	\$10.50	PDF
	A-RJUI-01-12		3/4	1-5/8	Closed			1	0.06	\$13.00	PDF
	A-RJUI-01-16	Fixed	1	2-1/4				1	0.23	\$20.00	PDF
	A-RJI-01-08	housing	1/2	1-1/4				1	0.03	\$6.50	PDF
	A-RJI-01-12		3/4	1-5/8			Type J polymer	1	0.05	\$7.00	<u>PDF</u>
	A-RJI-01-16		1	2-1/4				1	0.11	\$9.75	PDF
	A-0JUI-01-08		1/2	1-1/4		Type J		1	0.11	\$14.50	<u>PDF</u>
	A-0JUI-01-12		3/4	1-5/8	Open			1	0.06	\$16.50	<u>PDF</u>
4.	A-0JUI-01-16		1	2-1/4					1	0.23	\$22.50
	A-RJUI-03-08		1/2	1-1/4		polymer		1	0.03	\$11.00	PDF
	A-RJUI-03-12		3/4	1-5/8	Closed			1	0.06	\$13.00	<u>PDF</u>
	A-RJUI-03-16	Self-	1	2-1/4				1	0.11	\$21.00	<u>PDF</u>
	A-0JUI-03-08	aligning housing	1/2	1-1/4			Anodized aluminum	1	0.11	\$11.00	PDF
	A-0JUI-03-12]	3/4	1-5/8	Open			1	0.06	\$14.00	<u>PDF</u>
4	A-0JUI-03-16	1	1	2-1/4				1	0.23	\$21.00	<u>PDF</u>
	A-FJUI-11-08		1/2	1-11/16				1	0.18	\$41.50	<u>PDF</u>
	A-FJUI-11-12	Fixed housing	3/4	2-1/16				1	0.46	\$50.00	PDF
	A-FJUI-11-16		1	2-13/16	4-bolt flange			1	1.21	\$83.00	PDF
Straight	A-FJUI-13-08	0.10	1/2	1-11/16	pillow block			1	0.18	\$41.50	PDF
	A-FJUI-13-12	Self- aligning	3/4	2-1/16				1	0.46	\$50.00	PDF
	A-FJUI-13-16	- housing	1	2-13/16				1	1.21	\$83.00	<u>PDF</u>

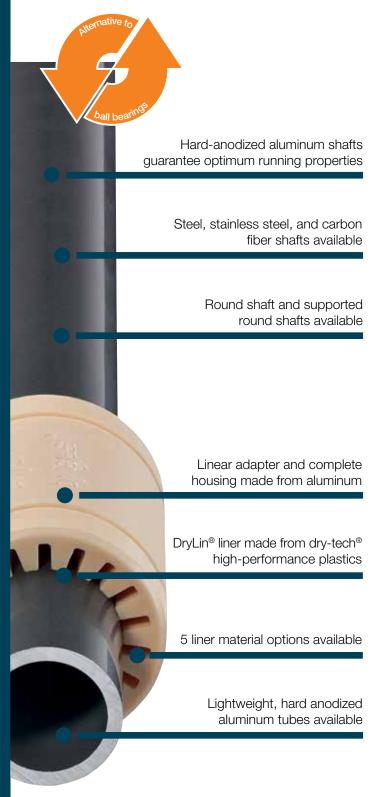
tMNC-125 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



DryLin® R Round Shaft Guide Systems

- Self-lubricating
- Maintenance-free
- Corrosion-free
- Resistant to dirt
- Low weight
- Dimensionally interchangeable with recirculating ball bearings

DryLin® R Round Shaft Guide Systems - Advantages



Self-lubricating round shaft guide systems – DryLin® R

DryLin® R is dimensionally interchangeable with linear ball bearings, but offers cleaner, more cost-effective results even in harsh environments. The standard RJUI/RJUM bearing consists of an iglide® J liner slip-fit into an aluminum housing. The unique grooved design of the J liner minimizes clearance, is suitable for use in extremely wet and dirty environments, and is easily replaceable. Dimensionally interchangeable 100% plastic parts RJI/RJM/RJIP/RJMP are also available for cost-savings, weight reduction, and other technical advantages. DryLin® R bearings may also be used with high temperature and chemically resistant iglide® T500 (X)* (TUI/TUM) liners for more demanding applications, and E7 material liners for steel and stainless shafting.

- 100% self-lubricating
- Dimensionally interchangeable with standard recirculating ball bearings
- Large variety of housing options
- Shafts, shaft-end supports and accessories available
- Replaceable bearing liner
- 300 series stainless steel housing available

Typical application areas:

- Packaging
- Lab
- Kiosk
- 3D Printing



max. +482°F (+250°C) min. -130°F (-90°C) (depending on material)



8 shaft materials 8 versions Inner-Ø up to 60 mm



Inch dimensions available



IPA Fraunhofer









ESD-compatible (electrostatic discharge)

DryLin® R Round Shaft Guide Systems - Product overview



Liners and pressfit bearings

- Low friction, optimized wear quality
- Space saving, lightweight
- High chemical resistance



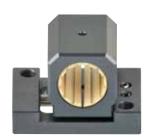




Linear plain bearing

- Aluminum or stainless steel adapter with iglide® material liner
- Solid iglide® plastic bearings available, dimensionally interchangeable with recirculating ball bearings
- Closed or open versions available
- Self-aligning
- Sliding discs available





Pillow blocks and floating pillow blocks

- Easy to assemble
- Stands up to high static load
- Replaceable bearing liners
- Split housing for quick liner replacement available





Open linear plain bearings

- For supported loads using supported shafting
- Round or mounted design
- Adjustable options
- Optional floating bearing for quick assembly and design optimization





Flange bearing

- Easy to fit
- Round or square options available
- Standard or twin flange designs





Quad block

- Closed or open design options
- Quad block housing with 4 bearing liners
- Floating bearing available

DryLin® R - Application Examples



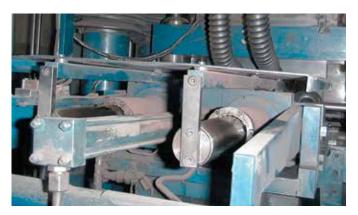
DryLin® R linear plain bearings on supported aluminum shafts are used in the guide for this cutting table. The DryLin® components stand up to the high levels of dust and dirt, and offer accurate, smooth operation.



This saw mill uses a DryLin® linear bearing with iglide® J plastic liner for the angle stops.



This heavy duty application has run reliably for more than three years thanks to DryLin® RJUM-01 linear bearings



Despite the high stresses from abrasive particles and powder particles, this compactor unit can extend maintenance-free uptime by up to two years after switching to DryLin® R linear bearings.



Maintenance-free, precise, compact, and wear resistant bearing liners were mounted directly in the passages of this machine's frame.

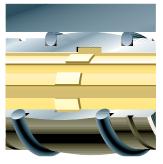


To enable fast, and precise adjustment of a production line without the need for downtime, DryLin® precision linear guides were utilized.

DryLin® R - Technical data

DryLin® R linear plain bearings

The DryLin® standard round bearings consist of a replaceable iglide® J, J200, A180 or T500 (X)* bearing liner, manufactured to fit securely into an anodized aluminum bearing housing, axially secured via a snap ring groove. DryLin® linear bearings are designed as dimensionally interchangeable with



standard ball bearings. Made of highly wear resistant iglide® J, J200, A180 or T500 (X)* materials, which offer technical advantages as well as cost savings. Plastic bearings are well suited for applications where machine components are primarily stainless steel, such as in food production and packaging equipment, as well as applications where weight savings are critical. DryLin® R linear plain bearings are designed to fit housings with our recommended tolerances, secured via circlips in the same way as ball bearings.

Dirt, dust, fibers

An important feature of all the linear plain bearings is their tolerance of dirt and other abrasive particles. For most conventional bearing systems, the use of wiper or seals is recommended to prevent the accumulation of dirt. With DryLin®, the patented design of the bearing surface, which uses connected slide pads, provides performance benefits for dirty environments. Dirt, even if it becomes wet on the shaft, is wiped away by the individual slide pads and is wiped to an open area. The running sections of the DryLin® bearings then slide on the shaft that has been cleared of all contaminants.

Split linear bearings

Applications on the edge of technical feasibility or in extreme environments often require frequent replacement of linear bearings. DryLin® linear bearings can provide significant increases in service life, and even when replacement is necessary, the replaceable bearing liners can offer substantial cost savings. Replacing only the bearing's liner can reduce maintenance time by 90%. The range of split bearing housings are easily opened, and the split shell means that the shafts are able to stay in place while a new bearing and liner can be installed around the shaft, keeping installation time to a minimum.







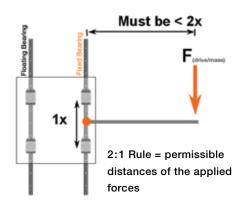
	The "all-rounder" - iglide® J	The specialist – iglide® J200	The extreme – iglide® T500 (X)	The marathon runner – iglide® E7	FDA compliant – iglide® A180
Optimal shaft material(s)	all shaft materials	Aluminum, hard anodized	Hardened stainless steel Hard chromed plated steel	Steel stainless steel shaft	all shaft materials
Application temperature	plication temperature		-148°F to +482°F (-100°C to +250°C)	-40°F to +194°F (-40°C to +90°C)	-40°F to +194°F (-40°C to +90°C)
Best coefficient of friction with	riction with Steel shaft Steel shaft Aluminum, hard anodized		Steel hard chrome-plated	Steel stainless steel shaft	Stainless steel shaft
Maximum life time	Steel shart hard anodized		Hardened stainless steel	Steel stainless steel shaft	Stainless steel shaft
Permissible stat. surface pressure	35 MPa	23 MPa	150 MPa	18 MPa	28 MPa
Moisture absorption	1.3% weight	0.7% weight	0.5% weight	< 0.1% weight	0.2% weight
Volume resistance $> 10^{13} \Omega \text{cm}$ $> 10^8 \Omega \text{c}$		> 10 ⁸ Ωcm	< 10 ⁵ Ωcm	> 10 ⁹ Ωcm	$> 10^{12} \Omega \text{cm}$
Part No.	JUM	J200UM	TUM/XUM	E7UM	A180UM

DryLin® R - Design standards

Eccentric Forces

The 2:1 Rule

When using linear plain bearings it is important to ensure that the acting forces follow the 2:1 Rule (see drawing). If either the load or the drive force (F) is greater than twice the bearing length (1X), then a binding or interrupted motion may occur. If the location of the drive force or load cannot be changed, simply increase the distance between the bearings, or create a counterbalance to move the center-of-gravity back within the 2 to 1 ratio.



Fixed and Floating Bearing Mounting Instructions

When using systems with 2 parallel rails, one side must be designated as the "fixed" rail, and the opposite side as the "floating" rail.

Why use floating bearings?

- Promotes smooth gliding performance and maximizes bearing life
- Prevents binding caused by parallelism and angle errors
- Decreases necessary drive force and wear by minimizing friction-forces
- Enhances the precision of the system over the bearings' lifetime.
- Reduce assembly time and co

Fixed Bearings

The "fixed" bearing rail should be positioned closest to the drive force. This rail will determine the precision of the system; no system should contain more than two "fixed" bearings.

Floating/Self-Aligning Bearings

The "floating" rail should be the rail located furthest from the drive force. It is to act only as a guide, and will compensate for any misalignments or angle errors in the system ensuring proper functionality.

Mounting Surfaces

The mounting surfaces for rails and bearings should have a very flat surface (e.g milled surface) in order to enhance performance. Variations in these surfaces may be compensated for by using floating bearings.

DryLin® R - Mounting Instructions

DryLin® R linear plain bearings in the 03 Design Series are self-aligning and offer great advantages in applications with parallel shafts. They are able to compensate for alignment and parallelism errors and should be used on the shaft located furthest from the drive mechanism.

The design provides a raised spherical area on the outer diameter of the aluminum adapter for self-alignment. Load capacity is the same as the fixed version.

Even in unfavorable edge-load conditions, the load is supported by the entire projected surface

In order to compensate for parallelism errors between two shafts, the outer diameter is designed to be smaller than the

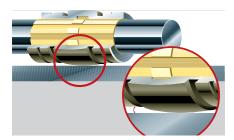
housing bore diameter by 0.2 - 0.3 mm (depending on the size). With the use of mounted O-rings, these bearings have an elastic bearing seat.

Compensation for angle errors

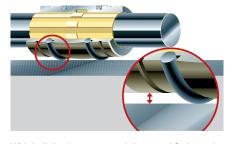
Series RJUI/RJUM/OJUI/OJUM-03 ±0.5° Series RJUM-06-LL/OJUM-06-LL ±3.5°

Compensation of parallelism errors

Series RJUI/RJUM/OJUI/OJUM-03 ±0.1 mm (.004") Series RJUM-06-LL/OJUM-06-LL ±3 mm (.12")



The spherical DryLin® adapters can compensate for alignment errors. A hard-anodization protects the aluminum adapter from wear.



With built in clearances and the use of O-rings, the self-aligning DryLin® R bearings of the 03 Design Series can compensate for parallelism errors.



The self-aligning DryLin® R bearings of the 06 LL design series can compensate parallelism errors up to ± .12" (3mm).



DryLin® R Hard-Anodized Shafts

 $igus^{\circledR}$ DryLin $^{\circledR}$ R hard-anodized shafts were specifically developed as the optimal sliding surface for DryLin R linear bearings. Available in four diameters and three lengths of both round shafting and fully supported shafting.

Features

- 6061-T6 aluminum hard-anodized to 450-550 HV surface hardness
- Round and fully supported styles
- Four diameters and three lengths up to 1000mm
- Best choice of shafting to use with DryLin R bearings



 $C \in$

		igus® D	ryLin® R H	ard-Ano	dized Sha	ıfts				
Item Photo	Part Number	Shaft Type	Diameter (inch)	Length (mm)	Material	Surface Hardness	Qty. per Package	Weight (lb)	Price	Drawing Link
	A-AWUI-08-250			250			1	0.54	\$18.00	<u>PDF</u>
	A-AWUI-08-500		1/2	500			1	1.07	\$33.00	<u>PDF</u>
	A-AWUI-08-1000			1000			1	2.13	\$65.00	<u>PDF</u>
	A-AWUI-12-250			250			1	0.92	\$24.00	<u>PDF</u>
	A-AWUI-12-500	Supported	3/4	500			1	1.85	\$46.50	<u>PDF</u>
	A-AWUI-12-1000			1000		450-550 HV	1	3.67	\$94.00	<u>PDF</u>
	A-AWUI-16-250		1	250	Hard- anodized aluminum		1	1.23	\$28.50	<u>PDF</u>
	A-AWUI-16-500			500			1	2.46	\$56.00	<u>PDF</u>
	A-AWUI-16-1000			1000			1	4.92	\$111.00	<u>PDF</u>
	A-AWI-04-250		1/4	250			1	0.05	\$9.75	<u>PDF</u>
	A-AWI-04-500			500			1	0.10	\$17.50	<u>PDF</u>
	A-AWI-04-1000			1000			1	0.20	\$35.00	<u>PDF</u>
	A-AWI-08-250		1/2	250			1	0.19	\$11.00	<u>PDF</u>
	A-AWI-08-500			500			1	0.39	\$20.50	<u>PDF</u>
	A-AWI-08-1000	Round		1000			1	0.77	\$41.50	<u>PDF</u>
	A-AWI-12-250	Tiounu		250			1	0.43	\$16.50	<u>PDF</u>
	A-AWI-12-500		3/4	500			1	0.87	\$30.50	<u>PDF</u>
	A-AWI-12-1000			1000			1	1.73	\$60.00	<u>PDF</u>
	A-AWI-16-250			250			1	0.77	\$22.00	<u>PDF</u>
	A-AWI-16-500		1	500			1	1.53	\$41.50	<u>PDF</u>
	A-AWI-16-1000			1000			1	3.05	\$84.00	PDF

tMNC-132 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



DryLin® Shafting

- Available in supported versions
- Aluminum for low weight
- Diameters 1/2 1 inch

DryLin® Shafts



Available shaft materials:

Aluminum

- Ideal in combination with liners made from iglide[®] J/J200
- Lightweight
- Lower wear
- Corrosion resistant
- Available from stock

Steel

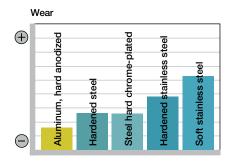
- Ideal with E7 liner
- Low-priced standard
- High load capacity
- Dry area applications
- Hard chrome-plated also available
- Lower coefficient of friction against plastic bearings

Stainless steel

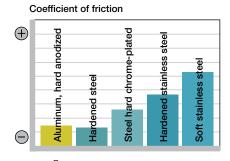
- Ideal with E7 liner
- High corrosion resistance
- High chemical resistance
- Ideal solution for wet applications
- 300 series for extremely chemical intensive applications

i

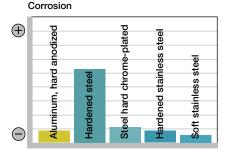
Please remember that this is a technical surface. Small color variations are possible due to variable coating depths.



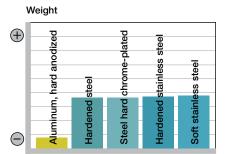
iglide [®]J against particular shaft materials

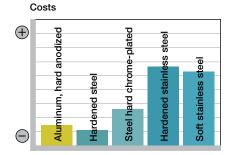


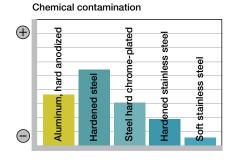
iglide [®]J against particular shaft materials



iglide [®]J against particular shaft materials







*X is the European equivalent material for iglide® T500

NEMA Planetary Gearboxes

The SureGear PGCN series easily mates to SureStep motors, and other NEMA frame motors. Everything you need to mount your SureStep motor is included!

handling, pick and place, automation, packaging, and

It is the perfect solution for applications such as material other motion control applications requiring a NEMA input/output interface.

15 models, five gear ratios available in **NEMA 17, 23** and 34 frame sizes





Tough on the outside, precision quality on the inside



tMNC-135

Planetary Gearboxes for NEMA Motors

SureGear® Planetary Gear Reducers for NEMA Motors - Óverview

The SureGear PGCN series is a great gearbox (gear reducer) value for servo, stepper, and other motion control applications requiring a NEMA size input/output interface. It offers the best quality available for the price point.

Features

- Wide range of ratios (5, 10, 25, 50, and 100:1)
- Low backlash of 30 arc-min or less
- 20,000 hour service life
- Maintenance free; requires no additional lubrication
- NEMA sizes 17, 23, and 34
- Includes hardware for mounting to SureStep stepper motors
- · Optional shaft bushings available for mounting to other motors





Applications • Material handling

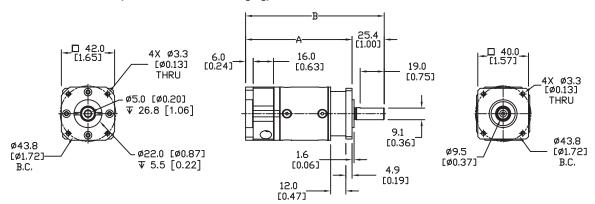
- Pick and place
- Automation
- Packaging
- Other motion control applications requiring a NEMA input/output

• Optional shall		, ,						NI 1						A mpay output
										arboxes				
Model-Specific Specifications														
Part Number	Price	Ratio	NEMA Frame Size	Nominal Output Torque (N·m [lb·in])	Maximum Acceleration Torque (N·m [lb·in])	Emergency Stop Torque (N·m [lb·in])	Standard Output Backlash (arc-min)	Allowable Radial Load (N [lb])	Allowable Axial Load (N [lb])	Torsional Stiffness (N·m/arc-min [lb·in/arc-min])	Mass Moment of Inertia (kg·cm² [lb·in²])	Efficiency (%)	Approx Weight (kg [lb])	Fits SureStep Stepper Motor
PGCN17-055M	\$295.00	5:1		6.5 [58]	13 [115]	26 [230]	<25			0.8 [7.5]	0.0096 [0.003]	94	0.45 [1.0]	
PGCN17-105M	\$295.00	10:1		5.0 [44]	10 [89]	20 [177]	<25	- - - 361 [81] 298		0.5 [4.4]	0.0078 [0.003]	94	0.45 [1.0]	5 [1.2] STP-MTR-170xx(D) 5 [1.2] 5 [1.2]
PGCN17-255M	\$371.00	25:1	17	16 [142]	20 [177]	32 [283]	<30		298 [67]	0.8 [7.5]	0.0096 [0.003]	92	0.55 [1.2]	
PGCN17-505M	\$371.00	50:1		16 [142]	20 [177]	32 [283]	<30			0.8 [7.5]	0.0078 [0.003]	92	0.55 [1.2]	
PGCN17-1005M	\$371.00	100:1		5.0 [44]	10 [89]	20 [177]	<30			0.5 [4.4]	0.0078 [0.003]	92	0.55 [1.2]	
PGCN23-0525	\$325.00	5:1		6.5 [58]	13 [115]	26 [230]	<20	301 [01]		0.9 [8.0]	0.04 [0.014] 92 92 92	94	0.45 [1.0]	STP-MTR(H)-230xx(D)
PGCN23-1025	\$325.00	10:1		5.0 [44]	10 [89]	20 [177]	<20			0.6 [5.3]		94	0.45 [1.0]	
PGCN23-2525	\$381.00	25:1	23	16 [142]	20 [177]	32 [283]	<25			0.9 [8.0]		92	0.55 [1.2]	
PGCN23-5025	\$381.00	50:1		16 [142]	20 [177]	32 [283]	<25			0.9 [8.0]		92	0.55 [1.2]	
PGCN23-10025	\$381.00	100:1		5.0 [44]	10 [89]	20 [177]	<25			0.6 [5.3]		92	0.55 [1.2]	
PGCN34-0550	\$387.00	5:1		26 [230]	44 [389]	84 [743]	<15	- [107]	425 [96]	2.4 [21.2]	0.36 [0.123]	94	1.1 [2.4]	STP-MTR(H)-34xxx(D)
PGCN34-1050	\$387.00	10:1		16 [142]	24 [212]	62 [549]	<15			1.3 [11.5]	0.34 [0.116]	94	1.1 [2.4]	
PGCN34-2550	\$524.00	25:1	34	42 [372]	52 [460]	84 [743]	<20			2.4 [21.2]	0.36 [0.123]	92	1.4 [3.1]	
PGCN34-5050	\$524.00	50:1		42 [372]	52 [460]	84 [743]	<20			2.4 [21.2]	0.34 [0.116]	92	1.4 [3.1]	
PGCN34-10050	\$524.00	100:1		16 [142]	24 [212]	62 [549]	<20		1.3 [11.5]	0.34 [0.116]	92	1.4 [3.1]		
				S	pecifica	tions Ap	plicab	le to Al	I PGCN	Gearbox	es			
Nominal Speed (<u> </u>									3500				
Maximum Input	•	pm)								6000				
Mounting Orientation			can be mounted in any orientation											
Environmental Rating			IP64											
Operating Temperature			-20 to 90 °C [-4 to 194 °F]											
Lubrication			Mineral Grease EPO											
Service Life (hrs.	Service Life (hrs) >20,000													
NOTE: SureGear PGCN gearboxes (gear reducers) are <u>not</u> designed for back driving.														

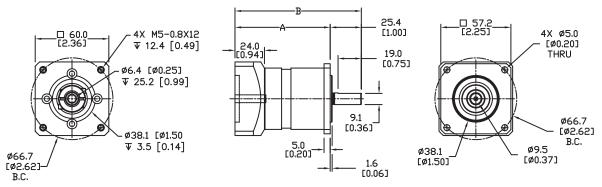
tMNC-136 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Sure gear Planetary Gearboxes for NEMA Motors

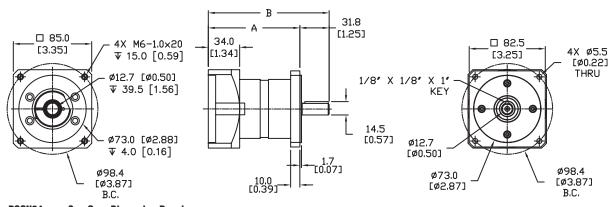
Dimensions (dimensions = mm [in])



PGCN17-xxxx SureGear Dimension Drawing



PGCN23-xxxx SureGear Dimension Drawing



PGCN34-xxxx SureGear Dimension Drawing

SureGear [®] NEMA Planetary Gearbox Dimensions (dimensions = mm [in])							
NEMA-17 Part Number	PGCN17-055M	PGCN17-105M	PGCN17-255M	PGCN17-505M	PGCN17-1005M		
Dimension A	84.0	[3.31]	99.8 [3.93]				
Dimension B	109.4	[4.31]	125.2 [4.93]				
NEMA-23 Part Number	PGCN23-0525	PGCN23-1025	PGCN23-2525	PGCN23-5025	PGCN23-10025		
Dimension A	77.6	[3.06]	95.2 [3.75]				
Dimension B	103.0	[4.06]	120.6 [4.75]				
NEMA-34 Part Number	PGCN34-0550	PGCN34-1050	PGCN34-2550	PGCN34-5050	PGCN34-10050		
Dimension A	99.3	[3.91]	121.3 [4.78]				
Dimension B	131.1	[5.16]	153.0 [6.02]				

tMNC-137 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Sure Gearboxes for NEMA Motors

Accessories







Typical PGCN Accessory Screws

SureGear [®] NEMA Planetary Gearbox Accessories						
Part Number Price		Description	Fits SureGear NEMA Planetary Gearbox			
PGCN17-SK	\$3.00	Mounting screws, replacement, for SureGear NEMA size 17 gearboxes (Package of 4)				
PGCN17-BSH5M	\$6.50	Motor shaft bushing for SureGear NEMA size 17 gearboxes, fits 5mm diameter motor shaft				
PGCN17-BSH8M	CN17-BSH8M \$6.50 Motor shaft bushing for SureGear NEMA size 17 gearboxes, fits 8mm diameter motor shaft					
PGCN17-BSH9M						
PGCN17-BSH25	\$6.50	Motor shaft bushing for SureGear NEMA size 17 gearboxes, fits 1/4 inch diameter motor shaft				
PGCN23-SK	\$3.00	Mounting screws, replacement, for SureGear NEMA size 23 gearboxes (Package of 4)				
PGCN23-BSH8M	\$6.50	Motor shaft bushing for SureGear NEMA size 23 gearboxes, fits 8mm diameter motor shaft				
PGCN23-BSH9M	\$6.50	Motor shaft bushing for SureGear NEMA size 23 gearboxes, fits 9mm diameter motor shaft	PGCN23-xxxx			
PGCN23-BSH25	GCN23-BSH25 \$6.50 Motor shaft bushing for SureGear NEMA size 23 gearboxes, fits 1/4 inch diameter motor shaft					
PGCN23-BSH37	\$6.50	Motor shaft bushing for SureGear NEMA size 23 gearboxes, fits 3/8 inch diameter motor shaft				
PGCN34-SK	\$3.00	Mounting screws, replacement, for SureGear NEMA size 34 gearboxes (Package of 4)				
PGCN34-BSH9M	\$6.50	Motor shaft bushing for SureGear NEMA size 34 gearboxes, fits 9mm diameter motor shaft				
PGCN34-BSH11M	\$6.50	Motor shaft bushing for SureGear NEMA size 34 gearboxes, fits 11mm diameter motor shaft	PGCN34-xxxx			
**GCN34-BSH37 \$6.50 Motor shaft bushing for SureGear NEMA size 34 gearboxes, fits 3/8 inch diameter motor shaft						
PGCN34-BSH50	\$6.50	Motor shaft bushing for SureGear NEMA size 34 gearboxes, fits 1/2 inch diameter motor shaft				

tMNC-138 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

SureServo® AC servo systems

The SureServo family of brushless servo systems from AutomationDirect is fully digital and offers a rich set of features at dynamite prices. Choose from eight standard servo motors that are used in combination with one of three standard servo drives.

- Eight standard systems from 100W to 3kW
- Use with any AutomationDirect PLC; or any other host controller
- Drives feature on-board indexer and adaptive tuning modes
- · Free setup software
- 30-day money-back guarantee
- Two year warranty

Why use a servo?

The SureServo servo systems provide the highest possible level of performance for precise control of position, velocity, and torque. Compared to lower cost stepping



AutomationDirect

SureServo family

The SureServo family is designed for flexibility and quick implementation. SureServo drives accept a wide range of command sources:

- Built-in motion controller w/preset position, velocity or torque
- Select presets with switch inputs and/or the multi-drop Modbus serial interface
- · Position commands with "pulse and direction" or "count up and down" format
- · Analog voltage Velocity or Torque command

ervo

vstems

• Encoder follower

For configuration, tuning and diagnostics, use the drive's integrated keypad / display or take advantage of the free SureServo Pro® PC-based software. Tune the system easily with adaptive auto-tuning selections or a manual mode.

Adapt to diverse applications with configurable I/O, including eight digital inputs, five digital outputs, two analog monitors and a scalable encoder output.

Allen-Bradley

systems, the SureServo products provide:	Digital Servo Drive	\$483.00 SVA-2040	\$1,410.00 (a)		
 More torque at higher speeds (up to 5,000 rpm) 	100W Servo Motor with connectorized Leads	\$322.00 \$VL-201	\$660.00 TLY-A130T-HK62AA		
Broader range of power (up to 3kW)	Breakout Board Kit for CN1 Control Interface	\$84.00 ZL-SVC-CBL50 + ZL-RTB50	\$316.05 2090-U38K-D4401		
Higher response with closed-loop control (high hit rate without stalling or	10' Motor Feedback Cable	\$56.00 SVC-EFL-010	\$99.10 2090-CFBM6DF-CBAA03		
lost position)	10' Motor Power Cable	\$33.50 SVC-PFL-010	\$112.00 2090-CPBM6DF-16AA03		
	Configuration Software	FREE SV-PRO*	\$85.02 2098-UWCPRG		
WYGUROORET	*SureServo Pro software is FREE when downloaded and is also available for \$9.00 or Complete 1-axis 100W System \$978.50 \$2,682.17 All prices are U.S. list prices, AutomationDirect prices as of 4/17/200. The Allen-Bradley 100W system consists of part numbers shown in table above with prices from www.wemerlectific.com, www.dockgovemponents.om 4/17/200.				
Sureyon Sure Serio	ZIPINK VAUTOMATIONDIRECTI CIERCE CERCES				



3 Standard Drives ... 8 Standard Motors ... 100W to 3kW ... over 50 gearboxes (both inline and right angle) with four ratios





Drive features

- · Main Power and Control Power Inputs
 - Main Power: 230 VAC 1-phase/3-phase (2kW and 3kW systems are 3-phase only)
 - Control Power: 230 VAC Single Phase; 50/60 Hz
- · Fully digital with up to 450 Hz velocity loop response
- · Easy setup and diagnostics with built-in keypad/display or the SureServo Pro PC-based software
- Five-in-one command options include:
 - ± 10V torque or velocity command
 - Pulse train or master encoder position command (accepts line driver or open collector) with electronic gearing
 - · Built-in indexer for position control using 8 preset positions and/or position setpoint with serial Modbus
- · Tuning aids include inertia estimation and easy tuning for up to 10 levels of response
- · Optically isolated digital inputs (8) and outputs (5), analog outputs for monitor signals (2), and line driver output for encoder (with scalable resolution)

Motor features

- Low inertia models:
 - · 100W, 200W, 400W, 750W and 1kW
 - Speeds up to 5,000 rpm.
- Medium inertia models:
 - 1kW, 2kW and 3kW
 - · Speeds up to 3,000 rpm.
- · Square flange mounting with metric dimensions:
 - · 40, 60, 80, 100, 130 and 180 mm flanges
- · Permanent magnet 3-phase synchronous motor
- Keyless drive shafts support clamp-on style coupling
- Integrated encoder with 2,500 (x4) pulses/revolution plus marker pulse (once per revolution)
- Optional 24 VDC spring-set holding brakes
- Standard hook-up cables for motor power/brake and encoder
- Standard DIN-rail mounted ZIPLink break-out kit for the drive's CN1 connector (with screw terminal connections)

SureServo tuning technology

The SureServo drive closes the loop on current, velocity, and position (depending on control mode selection). Proportional gain, integral gain, feed forward compensation, command low pass filter, and a notch filter for resonance suppression are available. There are three tuning modes:

- 1. "Manual Mode" for user-defined adjustments
- "Easy Mode" for default settings over a wide range of programmed inertia with 10 response levels
- 3. "Auto Mode" for automatic adjustment using an estimated (or measured) value of inertia

SureServo built-in motion controller

While the SureServo drives can accept traditional commands from host controls, they can also provide their own internal motion control. For example, up to eight index moves can be pre-defined and stored in the drive and then selected and executed using up to three discrete inputs. The predefined index profiles can also be changed via serial communications. The motion can be incremental or absolute (homing routines are available in the drive) and acceleration can be linear or S-curve.

Multiple drives can be daisy-chained and addressed separately using the drive's serial port. This allows very simple yet powerful control of multi-axis processes that do not need precise path control but only precise starting and stopping points. Applications include press feeds, auger fillers, rotary tables, robots for pick and place, test or assembly operations, drilling, cutting, tapping, and similar applications using simple index moves for single or multi-axis motion.

SureServo **Optional Holding Brake**

Each SureServo motor can be ordered with an optional 24VDC spring-set holding brake that holds the motor in place when power is removed.

SureGear® Precision Gearboxes for Servo motors

Inertia balancing issue in your design?



The SureGear PGA series easily mates to SureServo motors. Everything you need to mount your SureServo motor is included!

- Four gear ratios available (5, 10, 15, 25:1)
- Mounting hardware included for attaching to SureServo motors
- Industry-standard mounting dimensions
- · Thread-in mounting style
- Best-in-class backlash (5 arc-min)
- 5-year warranty

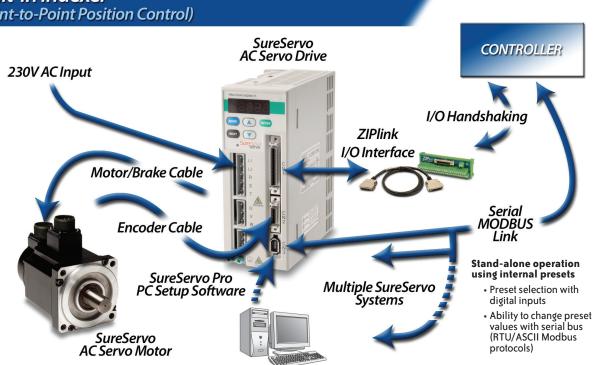
tMNC-139 **Motion Control**



Traditional Command Sources





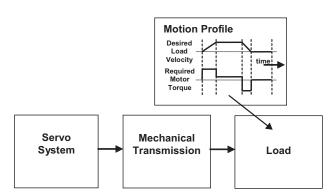


tMNC-140 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5



How to select and apply SureServo systems

The primary purpose of the AC servo system is to precisely control the motion of the load. The most fundamental considerations in selecting the servo system are "reflected" load inertia, servo system maximum speed requirement, servo system continuous torque requirement, and servo system peak torque requirement. In a retrofit application, select the largest torque SureServo system that most closely matches these parameters for



the system being replaced. In a new application, these parameters should be determined through calculation and/or measurement.

AutomationDirect has teamed with Copperhill Technologies to provide free servo-sizing software. "VisualSizer-SureServo" software will assist in determining the correct motor and drive for your application by calculating the reflected load inertia and required speed and torque based on the load configuration. "VisualSizer-SureServo" software can be downloaded from www.sureservo.com/downloads.htm.

Information for selecting SureServo systems is also included in Appendix B of the SureServo User Manual, which can be downloaded from the AutomationDirect.com website.

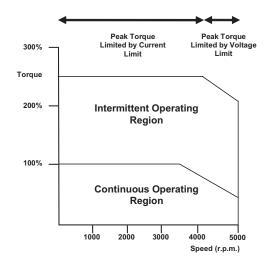
1. "Reflected" load inertia

The inertia of everything attached to the servo motor driveshaft needs to be considered and the total "reflected" inertia needs to be determined. This means that all elements of any mechanical transmission and load inertia need to be translated into an equivalent inertia as if attached directly to the motor driveshaft. The ratio of "reflected" load inertia to motor inertia needs to be carefully considered when selecting the

In general, applications that need high response or bandwidth will benefit from keeping the ratio of load inertia to motor inertia as low as possible and ideally under 10:1. Systems with ratios as high as 200:1 can be implemented, but corresponding lower bandwidth or responsiveness must be accepted. The servo response including the attached load inertia is determined by the servo tuning. SureServo systems may be tuned manually, adaptively with measurement of the load inertia, or set with default tuning based on a programmed value of load inertia

2. Torque and speed

With knowledge of the motion profile and any mechanical transmission between the motor and load, calculations can be made to determine the required servo motor continuous torque, peak torque, and maximum motor speed. The required amount of continuous torque must fall inside the continuous operating region of the system torquespeed curve (you can check the continuous torque at the average speed of the motion profile). The required amount of peak torque must also fall within the servo system's intermittent operating region of the system torque-speed curve (you need to check this value at the required maximum speed).



tMNC-141 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Application tip - coupling considerations

The SureServo motors have keyless shafts that are designed for use with clamp-on or compression style couplings. Couplings using keys and/or set screws should NOT be used with SureServo motors as they are likely to come loose or damage the motor shaft. "Servo-grade" clamp-on or compression style couplings are usually the best choice when you consider

the stiffness, torque rating, and inertia. Higher stiffness (lb-in/radian) is needed for better response but there is a trade-off between the stiffness and the added inertia of the coupling. Concerning the torque rating of the coupling, use a safety factor of 1.25 over the SureServo peak torque requirement of your application.

Coupling Suppliers: www.sureservo.com/couplingconsiderations.htm

Mechanical transmissions

Common mechanical transmissions include leadscrews, rack & pinion mechanisms, conveyors, gears, and timing belts. The use of leadscrew, rack & pinion, or conveyor are common

ways to translate the rotary motion of the servo motor into linear motion of the load. The use of a speed reducer such as a gearbox or timing belt can be very beneficial as follows:

Reduction of reflected load inertia

As a general rule, it is beneficial to keep the reflected load inertia as low as possible while using the full range of servo speed. SureServo systems can go up to 5,000 rpm for the low inertia motors and up to 3,000 rpm for the medium inertia motors.

Example: A gearbox reduces the required torque by a factor of the gear ratio, and reduces the reflected load inertia by a factor of the gear ratio squared. A 10:1 gearbox reduces output speed to 1/10, increases output torque 10 times, and decreases reflected inertia to 1/100.

However, when investigating the effect of different speed reduction ratios DO NOT forget to include the added inertia of couplings, gearbox, or timing belt pulleys. These added inertias can be significant, and can negate any inertia reduction due to the speed reduction.

2. Low speed and high torque applications

If the application requires low speed and high torque then it is common to introduce a speed reducer so that the servo system can operate over more of the available speed range. This could also have the added benefit of reducing the servo motor torque requirement which could allow you to use a smaller and lower cost servo system. Additional benefits are also possible with reduction in reflected inertia, increased number of motor encoder counts at the load, and increased ability to reject load disturbances due to mechanical advantage of the speed reducer.

3. Space limitations and motor orientation

SureServo motors can be mounted in any orientation, but the shaft seal should not be immersed in oil (open-frame gearbox, etc.). Reducers can possibly allow the use of a smaller motor or allow the motor to be repositioned. For example, some reducers would allow for in-line, right angle, or parallel mounting of the motor.

For more information, refer to the website listed below.

www.sureservo.com/mechanical_trans.htm

Ordering guide instructions

The following four pages are your ordering guide for the eight standard SureServo systems. Each of the eight standard systems has a torque-speed curve including the motor inertia for reference. This is the fundamental information that you need to select the servo drive and matching motor for your application.

Don't forget the cables and **ZIP**Link break-out board kit!

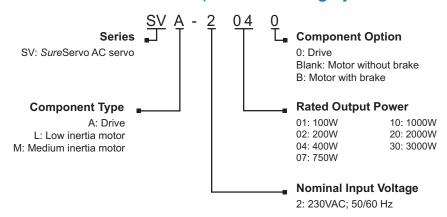
Included in the ordering guide are the available connection cables from the drive to motor in standard lengths from 10 to 60 feet. The break-out board kit includes a 0.5m (19 inch) cable for the CN1 I/O interface, and is listed for your convenience. We highly recommend all five items per system as a minimum. All cables are 100% factory tested to make your system installation as easy and quick as possible. See the Accessories section for regeneration resistors, AC line filters, fuses, contactors, and RF noise filters.

tMNC-142 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Sure AC Servo System Configuration

SureServo series drives and motors part numbering system



Here is what you will need to order a complete servo system:













NOTE: Unit can be programmed via keypad.

OPTIONAL PROGRAMMING SOFTWARE (FREE DOWNLOAD) AND OPTIONAL PROGRAMMING CABLE AVAILABLE.



NOTE: IF YOU NEED A GEAR BOX FOR YOUR CONFIGURATION, YOU CAN DO IT EASILY ONLINE: HTTP://WWW.SURESERVO.COM/GEARBOX/SELECTOR



SureServo AC servo drive, motor, and cable combinations

Inertia & Power		Drive and Motor		Power Cables (from Drive to Motor)		Encoder Feedback Cables			Miscellaneous															
Inertia	Power	Servo Drive	Servo Motor without brake (note)	Servo Motor with brake (note)	10 ft	20 ft	30 ft	60 ft	10 ft	20 ft	30 ft	60 ft	ZIPLink I/O Interface	RS-422/485 Serial Com- munication Cable										
	100W	0	SVL-201	SVL-201B	SVC-		SVC-	SVC- SVC	SVC-	SVC-	SVC-	SVC-												
.eg	200W	SVA-2040	SVL-202	SVL-202B									ZL-RTB50											
Low inertia	400W		SVL-204	SVL-204B	PFL-010		PFL-020 PFL-030	PFL-020 PFL-030 I	PFL-030	PFL-060	EFL-010	EFL-010 EFL	L-060 EFL-010	EFL-020	EFL-020	EFL-020	EFL-030	EFL-030	EFL-030	EFL-060	EFL-060	EFL-060	and	
] 3	750W	0	SVL-207	SVL-207B									ZL-SVC-CBL50	OVO MDOOM ODI										
	1000W	SVA-2100	SVL-210	SVL-210B	SVC- SV	SVC-	SVC-		SVC-				or ZL-SVC-CBL50-1	SVC-MDCOM-CBL										
ertia	1000W	S	SVM-210	SVM-210B	PHM-010	PHM-020	PHM-030			SVC-	SVC-	SVC-	or ZL-SVC-CBL50-2											
Medium inertia	2000W	2300	SVM-220	SVM-220B	SVC-	SVC-	SVC-	SVC-	EHH-010	EHH-020	EHH-030	EHH-060												
Med	3000W	SVA-2300	SVM-230		PHH-010	PHH-020	PHH-030	PHH-060																
	Note: Each servo motor requires an encoder feedback cable and a power cable. The motor power cable includes brake power wires for the optional motor brake.																							

tMNC-143 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

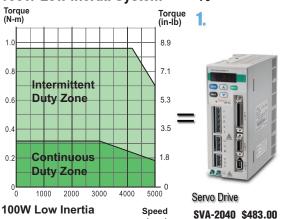
Sure AC Servo System Configuration

For all systems: Order programming software &

programming cable if needed. 100W Low Inertia System See pgs. tMNC-144 & 45.

SureServo Motor

Motor Power Cable (1)



(rpm)

 $J_m = Motor Inertia = 0.000027 Ib-in-s^2 (0.000003 kg - m^2)$





Motor Encoder Cable (1)

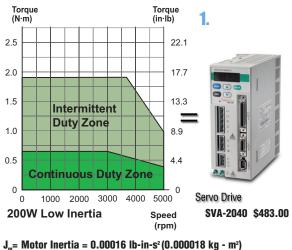


ZIPLink I/O Interface

ı		
	SVC-EFL-010 (10')	\$56.00
ı	SVC-EFL-020 (20')	\$90.00
ı	SVC-EFL-030 (30')	\$105.00
ı	SVC-EFL-060 (60')	\$134.00

ZL-SVC-CBL50-1 (1m) \$34.00 ZL-SVC-CBL50-2 (2m) \$39.50

200W Low Inertia System







3. SVC-PFL-010 (10') \$33,50 SVC-PFL-020 (20') \$62.00 SVC-PFL-030 (30') \$77.00 SVC-PFL-060 (60') \$140.00

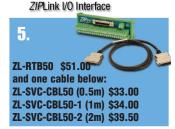
Motor Power Cable (1)

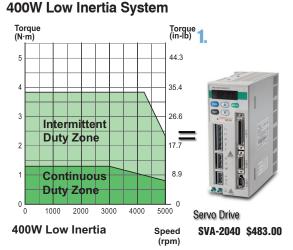
Motor Encoder Cable (1)



\$105.00

\$134.00





J_m= Motor Inertia =0.0003 lb-in-s² (0 .000034 kg - m²)

SureServo Motor

SVC-EFL-030 (30')

SVC-EFL-060 (60')







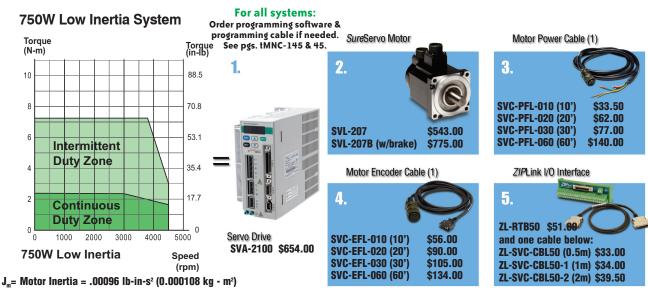


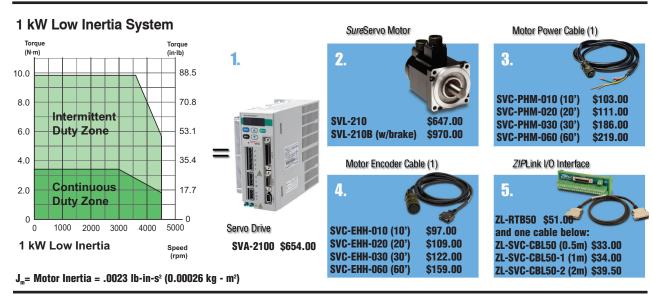
ZIPLink I/O Interface

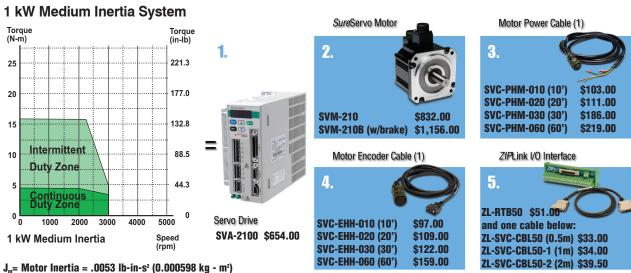


tMNC-144 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Sure AC Servo System Configuration







tMNC-145 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

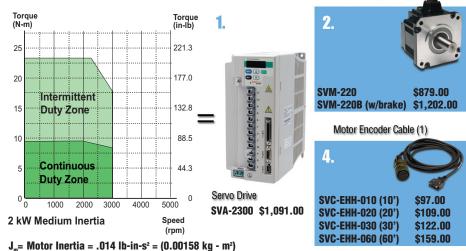


AC Servo System Configuration

SureServo Motor

For all systems: Order programming software &

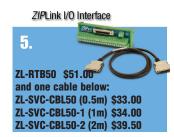




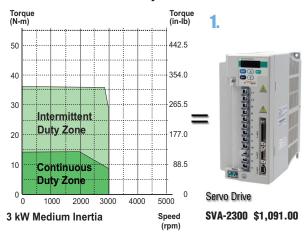


Motor Power Cable (1)





3 kW Medium Inertia System



 $J_m = Motor Inertia = 0.038 lb-in-s^2 = (0.00433 kg - m^2)$



Motor Encoder Cable (1)



SVC-EHH-020 (20') \$109.00 SVC-EHH-030 (30') \$122,00 SVC-EHH-060 (60')

Motor Power Cable (1)



ZIPLink I/O Interface



NOTE: All Motor Power Cables include brake POWER WIRES FOR THE OPTIONAL MOTOR BRAKE.

SureServo Communications Cables for Muti-drop Networks

Product	Price	Description			
SVC-MDCOM-CBL	\$27.50	RS-422/485 serial communication cable for use with multidrop networks; 3ft length; IEEE 1394 plug to unterminated wires; compatible with all <i>Sure</i> Servo systems. Facilitates connection between the <i>Sure</i> Servo drive serial port and host controllers.			
SVC-232RJ12-CBL-2 *	\$8.25	ZIPLink SureServo Drives cable with 6-pin RJ12 connector to a 6-pin IEEE 1394 connector, shielded, twisted pair, 2.0 meter (6.6 ft.) length. For RS-232 connection to all <i>Sure</i> Servo amplifiers.			
SVC-485RJ12-CBL-2 *	\$10.00	Z/PLink SureServo amplifier communication cable, RJ12 male to 6-pin IEEE 1394 connector, shielded, twisted pair, 2.0 meter (6.6 ft.) length. Cable used in conjunction with ZL-CDM-RJ12xxx distribution module can access a compatible RS-485 device network.			
SVC-485HD15-CBL-2 *	\$8.75	ZIPLink SureServo Drives cable with a HD 15-pin male to a 6-pin IEEE 1394 connector, shielded, twisted pair, 2.0 meter (6.6 ft.) length. For RS-485 connection to all SureServo amplifiers.			
* Refer to the ZIPLinks Wiring Solutions section for complete information regarding the ZIPLink cables.					



tMNC-146 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5



AC Servo System Software

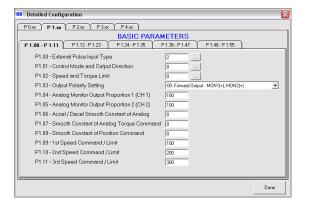


Parameter views

The SureServo Pro configuration tool logically organizes over 165 servo drive parameters into five tabbed groups. Each parameter has a factory default that usually allows the servo to run "out-of-the-box".

The parameters can be easily changed with available options or setting ranges displayed. Tuning modes and parameters can also be changed using SureServo Pro. After the parameters have been defined, the complete setup can be stored and archived. Drive configurations can be uploaded, edited, saved, and downloaded as often as necessary.

Parameter View Example Screen - Basic Parameters



SureServo Pro configuration software

SureServo Pro is an optional free downloadable configuration software package for the SureServo drives. With SureServo Pro installed, the personal computer may be directly connected to the servo drive's serial port via the PC's RS-232 serial port*. A six-foot configuration cable (SVC-PCCFG-CBL, \$19.50) is available to make the connection between the drive serial port and PC DB-9 serial port simple.

*Note: Use our USB-RS232 converter cable in conjunction with the SVC-PCCFG-CBL cable on PCs having only USB ports.

Features

- Quick Start The basic setup when you have limited time and just want to get up and running ASAP.
- Maintenance keypad allows the user to operate the servo system from the PC. This is a great aid during start-up to allow the servo to perform some basic motion and to check the I/O.
- Detailed The complete setup for all the drive parameters
- Tune and check the servo response live using the scope feature.
- Upload and download the drive setup. Save the drive setup as a file for future use.
- Edit the drive setup
- · View all drive faults
- Trend drive variables in real time



SureServo Software and Configuration Cables

Product	Price	Description			
SV-PRO	Free	SureServo Pro configuration software for use with all SureServo servo systems. FREE download from www.sureservo.com or www.automationdirect.com websites.			
SV-PRO	\$9.25	CD with SureServo Pro configuration software			
SVC-PCCFG-CBL \$24.0		ix-foot RS-232 communications cable; connects servo drive serial port to PC DB-9 serial port. For PCs having only USB ports, use our USB-RS232 converter cable in conjunction with the SVC-PCCFG-CBL cable.			
SVC-485CFG-CBL-2	\$11.50	ZIPLink SureServo amplifier configuration cable, 6-pin IEEE 1394 connector to RJ45 connector, shielded, twisted pair, 2.0 meter (6.6 ft.) length.			
3 V 0-40301 U-0DL-2	Ψ11.50	Use this cable in conjunction with our USB-485M serial adapter to connect any SureServo amplifier to a PC. Eliminates the need to reprogram networked servo drives from RS485 to RS232 when connecting to a PC.			
* Refer to the ZIPLinks Wil	ina Solut	ions section for complete information reparding ZIPLink cable SVC-485CFG-CBL-2.			

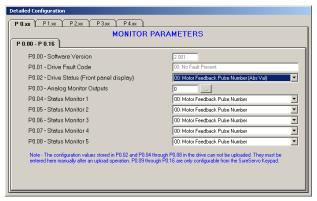
tMNC-147 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Sure AC Servo System Software

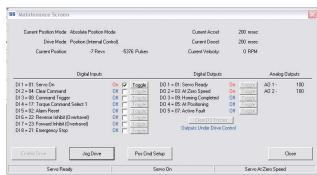
SureServo Pro configuration software -Parameter views (continued)

Parameter View Example Screen - Monitor Parameters

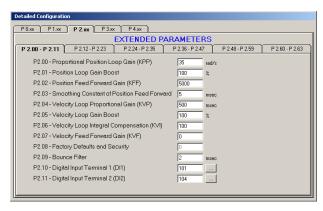


Maintenance screen

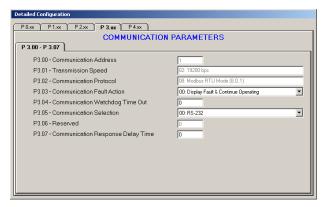
A maintenance keypad allows the user to operate the servo system from the PC. This is a great aid during start-up to allow the servo to perform some basic motion and to check the I/O.



Parameter View Example Screen - Extended Parameters



Parameter View Example Screen - Communication Parameters



Scope

SureServo Pro includes a powerful scope function that allows the user to have as many as three channels of data displayed simultaneously. Each channel has a drop-down table to select the data to be displayed. The scope also has a trigger mode and timebase selection. This function is a valuable tool for tuning SureServo drives.



tMNC-148 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Sure Servo Drive Specifications



SureServo systems run "out-of-the-box"... but may be reconfigured for many applications!

The SureServo drives are fully digital and include over 165 programmable parameters. For convenience, the parameters are grouped into five categories:

- 1) Monitor parameters
- 2) Basic parameters
- 3) Extended parameters
- 4) Communication parameters
- 5) Diagnostic parameters.

All parameters have commonly used default values which allow you to operate the SureServo system "out-of-the-box". However, the programmability and large variety of parameters make the SureServo systems suitable for a very broad range of applications, including almost all types of general purpose industrial machinery such as assembly, test, packaging, machine tool, and robotics.

tMNC-149 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Servo drive specifications

	General Drive Specifications
Permissible Frequency	50/60 Hz ±5%
Encoder Resolution / Feedback Resolution	2500 lines / 10000 ppr
Control of Main Circuit	SVPWM (Space Vector Pulse Width Modulation) Control
Tuning Modes	Easy / Auto / Manual
Dynamic Brake	Built-in control
Analog Monitor Outputs (2)	Monitor signal can be set by parameters (Output voltage range: ±8V; Resolution: 12.8 mV/count)
8 Programmable Digital Inputs	Servo enable, Alarm reset, Gain switching, Pulse counter clear, Fault stop, CW/CCW over-travel
(45 selectable functions)	Internal parameter selection, Torque limit activation, Velocity limit activation, Control mode selection
Scalable Encoder Output	Encoder signal output A, /A, B, /B, Z /Z, Line Driver
5 Programmable Outputs (9 selectable indicators)	Servo ready, Servo On, Low velocity, Velocity reached, In Position, Torque limiting, Servo fault, Electromagnetic brake control, Home search completed
Communication Interface	RS-232 / RS-485 / RS-422 / Modbus ASCII & RTU up to 115k Baud
Protective Functions	Overcurrent, Overvoltage, Undervoltage, Overload, Excessive velocity/position error, Encoder error, Regeneration error, Communication error
Installation Site	Indoor location (free from direct sunlight), no corrosive liquid and gas (far away from oil mist, flammable gas, dust)
Altitude	1000m [3281 ft] above sea level – maximum
Operating Temperature	0 to 55 °C [32 to 131 °F] (If operating temperature is above 55°C, forced cooling is required). For long-term reliability, the ambient temperature of <i>Sure</i> Servo systems should be under 45°C (113°F).
Storage Temperature	-20° to 65°C (-4° to 149°F)
Humidity	0 to 90% (non-condensing)
Vibration	9.81 m/s² (1G) less than 20Hz, 5.88 m/s² (0.6G) 20 to 50 Hz
Protection	IP 20
Agency Approvals	CE; UL Certified (U.S. and Canada)

tMNC-150 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



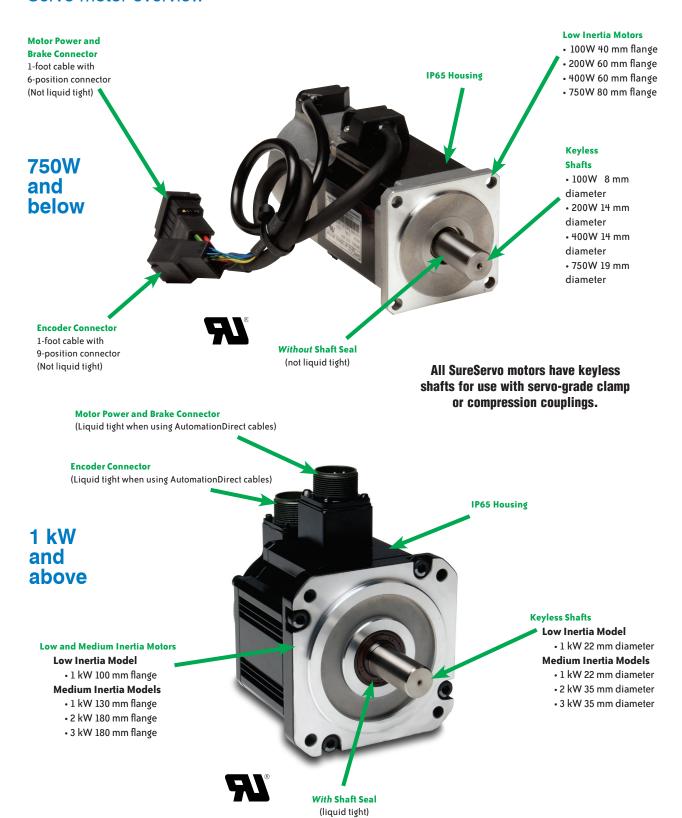
Servo drive specifications (continued)

		Mod	lel and M	ode Spec	ific Drive	Specifica	ations			
	AC Servo Model			SVA-2040			SVA-2100		SVA-	2300
	Price			\$483.00			\$667.00		\$1,1	13.00
	Voltage Phase				Single-phase of	or Three-phase			Three-phase	
	Voltage and Frequency Range Main Circuit Input Single Phase			3-phase: 170-255 VAC @ 50/60 Hz ±5%; 1-phase: 200-255 VAC @ 50/60 Hz ±5%				170~255 VAC @ 50/60 Hz ±5%		
	Main Circuit Innut	Single Phase	3.4A @ 400W 8.0A @ 1kW				-	-		
	Current	Three Phase		2.6A @ 400W	1		6.2A @ 1kW		13.6A	@ 3kW
	Main Circuit Inrush		44A 77A 87A							
	Main Circuit Power				Maximum 1 p	ower cycle per	minute			
	Control Circuit Curr				43 mA @ 20	0~255 VAC, 1	phase			
	Control Circuit Inru				32 <i>A</i>	maximum				
	Cooling System		Nati	ural Air Circula	ition			Internal Cooli	ng Fan	
	Drive Heat Loss *	Motor driven *	SVL-201(B)	SVL-202(B)	SVL-204(B)	SVL-207(B)	SVL-210(B)	SVM-210(B)	SVM-220(B)	SVM-230(B)
	Drive Heat Loss "	Heat Loss	12W	15W	20W	35W	45W	50W	75W	80W
	Weight			1.5 kg [3.3 lb]			2kg [4lb]		3kg	[7lb]
e	Max. Input Pulse F			Max. 500 kp	ps (Line drive); Max. 200 kj	ops (Open colle	ector)		
Моа	Pulse Type		Pulse + Direction, A phase + B phase Quadrature, CCW pulse + CW pulse							
rol	Command Source		External pulse train / Onboard indexer							
Con	Smoothing Strategy	Low-pass and P-curve filter								
ion	Electronic Gear		Electronic gear N/M multiple; N: 1~32767, M: 1~32767(1/50 <n m<200)<="" th=""></n>							
osit	Power Type Pulse Type Command Source Smoothing Strategy Electronic Gear Torque Limit Operation			Set by parameters or by analog input						
۵	Feed Forward Com	pensation	n Set by parameters							
	Voltage Range		Bipolar ±10 VDC							
	Analog Input	Input Resistance	10 k							
	Command	Time Constant	2.2 µs							
ode		Resolution	(Varies with input voltage) 13 bits @ 0V~1V; 13~10 bits @ 1V~2V; 10 bits @ 2V~10V						V	
Velocity Control Mode	Speed Control Rang	1:5000								
ontr	Command Source		External analog signal / Onboard indexer							
ty C	Smoothing Strategy					Low-pass	and S-curve f	Iter		
loci	Torque Limit Opera					Set by paramet	ers or via anal	og input		
Ne	Frequency Respons	se Characteristic					mum 450 Hz			
	Speed Accuracy					1% or less at 0				
	(at rated rotation s	peed)	0.01% or less at ±10% power fluctuation							
			0.01% or less at 0 to 50°C ambient temperature fluctuation							
		Voltage Range				Bipo	lar ±10 VDC			
ode	Analog Input	Input Resistance					10 kΩ			
of M	Command	Time Constant					2.2 μs			
ontra		Resolution					10 bits			
Torque Control Mode	Permissible Time f	8 sec. under 200% rated output								
orqu	Command Source			Ex	ternal analog s		rd indexer			
1	Smoothing Strategy						r-pass filter			
	Speed Limit Operation					Set by paramet	ers or via anal	og input		
* Driv	e heat loss varies deper	nding upon which motor	ıs connected	to the drive						

tMNC-151 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Sure AC Servo Motor Specifications

Servo motor overview



tMNC-152 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Sure AC Servo Motor Specifications

	VU			BH-1- O						
				Motor Sp	ecificatio	ns				
Inertia Range					Low				Medium	
Model Name: Sxx-xx	K		SVL-201	SVL-202	SVL-204	SVL-207	SVL-210	SVM-210	SVM-220	SVM-230
Price			\$322.00	\$415.00	\$508.00	\$543.00	\$647.00	\$832.00	\$879.00	\$1,341.00
Model with brake: Sx.	x-xxxB		SVL-201B	SVL-202B	SVL-204B	SVL-207B	SVL-210B	SVM-210B	SVM-220B	SVM-230B
Price			\$554.00	\$614.00	\$716.00	\$775.00	\$970.00	\$1,156.00	\$1,202.00	\$1,530.00
Rated output power		W	100	200	400	750	1000	1000	2000	3000
Rated torque		N∙m	0.32	0.64	1.27	2.39	3.3	4.8	9.4	14.3
Tratou torquo		lb·in	2.8	5.7	11.2	21.2	29.2	42.5	83.2	126.6
Maximum torque		N∙m	0.95	1.91	3.82	7.16	9.9	15.7	23.5	35.8
		lb·in	8.4	16.9	33.8	63.4	87.6	138.9	208.0	316.8
Rated speed		rpm			3000				2000	
Max. speed		rpm		5000		_	00		3000	
Rated current		Α	1.1	1.7	3.3	5.0	6.8	5.6	13.1	17.4
Max. current		Α	3.0	4.9	9.3	14.1	18.7	17.6	31.4	42.3
Drive input current		1 phase A	1.0	1.7	3.4	5.9	8.0	8.0	-	-
		3 phase A	0.8	1.3	2.6	4.7	6.2	6.2	9.1	13.6
Max. radial		N	78.4	19		343		90		84
shaft load		lb	18		4	77		10		76
Max. thrust shaft load	d	N	39.2	68			98			92
		lb	9	1	5		22		8	88
-	/oltage	VDC				i e	4		1	
<i>Brake</i> ⊢	Current		0.21		38	0.4	0.75	0.83	1.45	1.67
F		N·m	0.32	1.3		2.55	9.3	7.5	32.0	50.0
	Torque	lb·in	2.83		.24	22.57	82.3	66.38	283.2	442.5
Rotor inertia		kg·m²	0.03E-4	0.18E-4	0.34E-4	1.08E-4	2.6E-4	5.98E-4	15.8E-4	43.3E-4
w/o brake		lb∙in∙s²	0.27E-4	1.59E-4	3.0E-4	9.56E-4	23.0E-4	52.9E-4	139.8E-4	383.2E-4
Rotor inertia		kg∙m²	0.06E-4	0.28E-4	0.44E-4	1.32E-4	3.1E-4	8.8E-4	27.8E-4	56.3E-4
with brake		lb∙in∙s²	0.53E-4	2.48E-4	3.9E-4	11.7E-4	27.4E-4	77.9E-4	246.0E-4	498.3E-4
Mechanical time con	stant	ms	0.6	0.9	0.7	0.6	1.7	1.4	1.6	0.9
Static friction torque		N∙m	0.02	0.	04	0.08	0.49	0.29	0.	98
Torque constant-KT		N·m/A	0.32	0.39	0.4	0.5	0.56	0.91	0.77	0.86
Voltage constant-KE		V/rpm	33.7E-3	41.0E-3	41.6E-3	52.2E-3	58.4E-3	95.71E-3	81.1E-3	90.5E-3
Armature resistance		Ω	20.3	7.5	3.1	1.3	2.052	1.98	0.6	0.162
Armature inductance		mH	32	24	11	6.3	8.4	13.2	6.1	2.3
Electrical time consta	ant	ms	1.6	3.2	3.2	4.8	4.1	6.7	10.1	14.2
Motor Type				Brush	iless, AC, perma		, , ,	, Iron (Fe), Boro	n (B)]	
Insulation class							ss F			
Insulation resistance						>100 MΩ				
Insulation strength	*******		1500 VAC, 50 Hz, 60 seconds 0 to 40°C (32°F to 104°F)							
Ambient temperature Operating temperatur										
(measured case temperatur						70°C (158°F)			
Maximum operating t		ture				70°C + 40°C =	110°C (230°E)			
(measured case temperatur	re)									
Storage temperature							(-4 to 149°F)			
Operating humidity						20 to 90% RH (r				
Storage humidity						20 to 90% RH (r)		
Vibration / Shock			IDOF -	notor bod ID40	abatti IDOO	2.5G		IDCE (rocuites C	lumConuc soble	`
Environmental rating		ka			shaft; IP20 cor	1		IP65 (requires S		i –
Weight without brake		kg Ib	0.5 1.1	0.9 1.98	1.3 2.87	2.5 5.5	4.7	4.8	12.0	17.0 37.48
		kg	0.7	1.98	1.8	3.4	10.36 6.3	7.5	26.46 19.0	24.0
Weight with brake		lb	1.54	3.09	3.97	7.5	13.89	16.53	41.89	52.9
Agency Approvals		IN	1.04	5.05		; UL recognized			71.03	J.C.3
· · · · ·	mita ava f	or reference	only		UL	, or 1000gillzen	vo.o. and balla	uuj		

tMNC-153 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

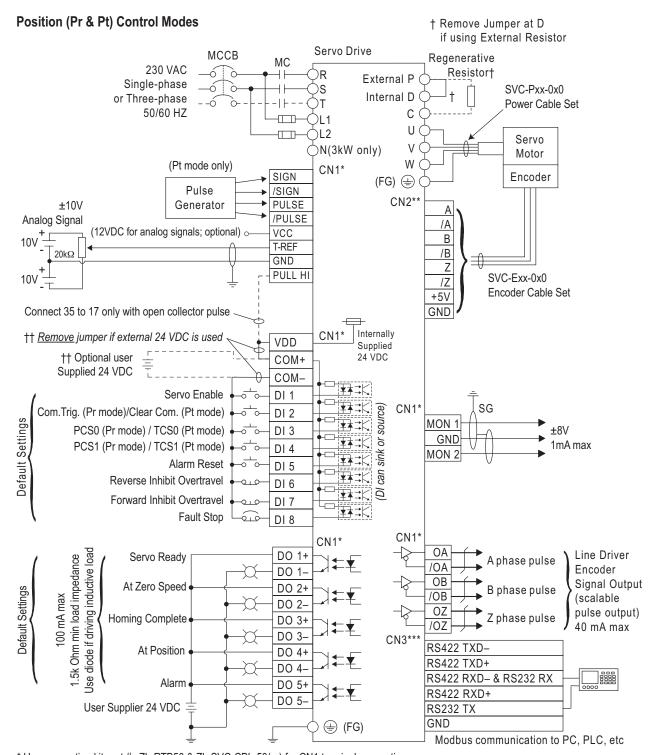
Sure AC Servo System Wiring

Standard wiring examples



This wiring diagram shows basic wiring only, and additional wiring configurations are possible for some I/O.

Refer to the "Installation and Wiring" chapter of the User Manual for more detailed wiring information.



^{*} Use connection kit part #s ZL-RTB50 & ZL-SVC-CBL-50(-x) for CN1 terminal connections.

tMNC-154 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

^{**} Use cable part # SVC-Exx-0x0 for CN2 terminal connections.

^{***} Use cable part # SVC-MDCOM-CBL for CN3 terminal Modbus network connections.

Sure/\/* servo

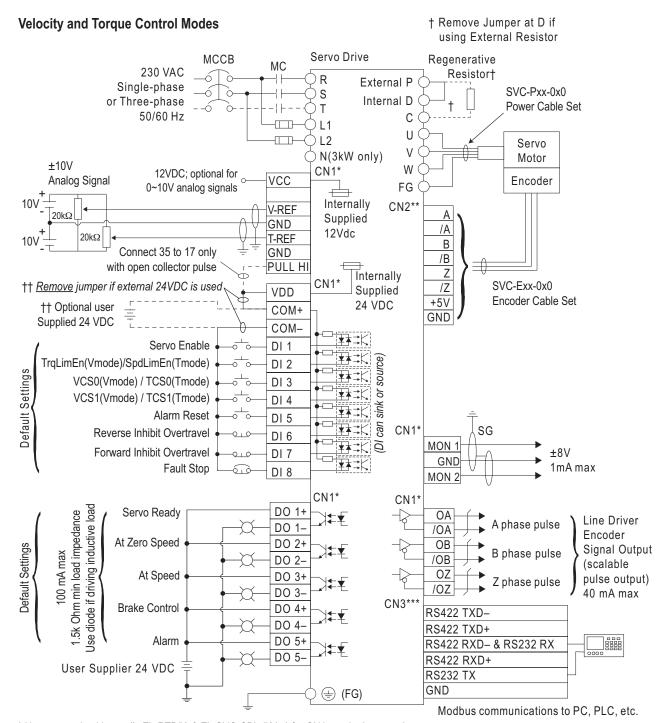
servo AC Servo System Wiring

Standard wiring examples (continued)



This wiring diagram shows basic wiring only, and additional wiring configurations are possible for some I/O.

Refer to the "Installation and Wiring" chapter of the User Manual for more detailed wiring information.



^{*} Use connection kit part #s ZL-RTB50 & ZL-SVC-CBL-50(-x) for CN1 terminal connections.

tMNC-155 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

^{**} Use cable part # SVC-Exx-0x0 for CN2 terminal connections.

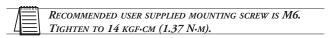
^{***} Use cable part # SVC-MDCOM-CBL for CN3 terminal Modbus network connections.

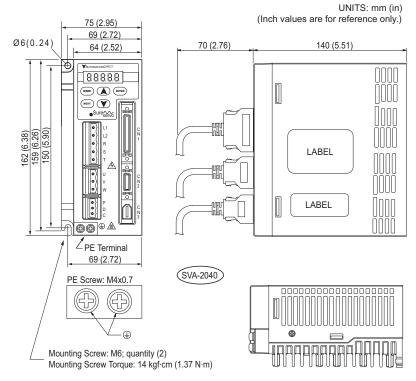
Sure/\/* servo

servo AC Servo System Dimensions

Servo drive dimensions

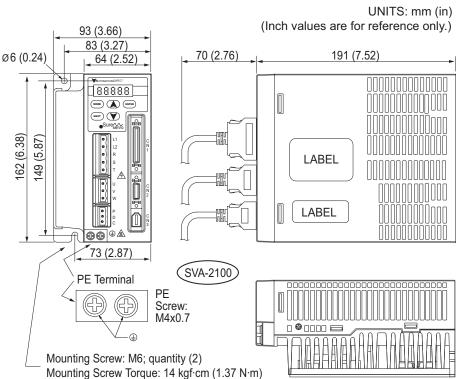
SVA-2040





SVA-2100



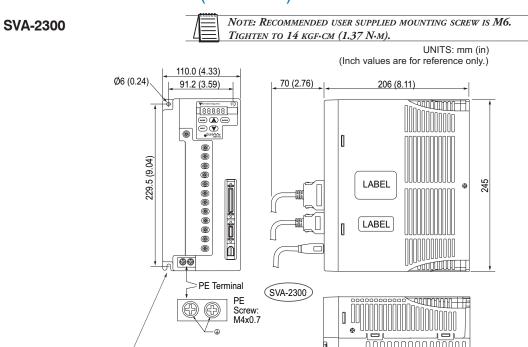


tMNC-156 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Sure AC Servo System Dimensions

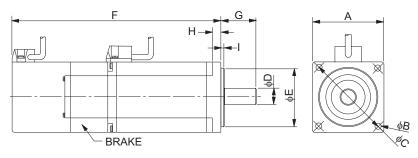
Servo drive dimensions (continued)



Servo motor dimensions

Low inertia models SVL-201(B), SVL-202(B), SVL-SVL-204(B), SVL-207(B)

Mounting Screw: M6; quantity (3) Mounting Screw Torque: 14 kgf·cm (1.37 N·m)



	SureServo® Motor	Dimensions – 10	0W-750W Low In	ertia		
Dimension	SVL-201(B)	SVL-202(B)	SVL-204(B)	SVL-207(B)		
Α	40 [1.575]	60	[2.362]	80 [3.15]		
В	4.5 [0.1772]	5.5 [0.2165]	6.6 [0.2598]		
С	46 [1.811]	70	70 [2.756]			
D	8 +0.0/-0.009 (8h6)	14 +0.0/-(14 +0.0/-0.011 (14h6)			
E	30 +0.0/-0.021 (30h7)	50 +0.0/-0	0.025 (50h7)	70 +0.0/-0.030 (70h7)		
F (w/o brake)	100.1 [3.941]	102.4 [4.032]	124.4 [4.898]	135 [5.315]		
F (with brake)	135.7 [5.343]	137 [5.394]	159 [6.26]	171.6 [6.756]		
G	25 [0.98]	30	[1.18]	35 [1.38]		
Н	5 [0.197]	6 [0.236]	8 [0.315]		
I	2.5 [0.098]		3 [0.118]			
Cable length		300mm	(12 inches)			
UNITS: mm [in]. (I	nches are for reference	only; not included on	diameter dimensions fo	or accuracy.)		

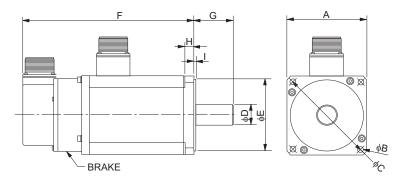
tMNC-157 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Sure AC Servo System Dimensions

Servo motor dimensions (continued)

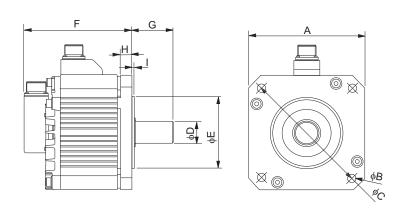
Low inertia models SVL-210(B)



SureServo® Motor I	Dimensions -1000W Low Inertia			
Dimension	SVL-210(B)			
Α	100 [3.937]			
В	9 [0.3543]			
С	115 +0.2/-0.2 [4.528]			
D	22 +0.0/-0.013 (22h6)			
E	95 +0.0/-0.035 (95h7)			
F (w/o brake)	158 [6.22]			
F (with brake)	190 [7.48]			
G	45 [1.77]			
Н	17 [0.669]			
I	7 [0.28]			
l				

UNITS: mm [in] (Inches are for reference only; not included on diameter dimensions for accuracy.)

Medium inertia models SVM-210(B), SVM-220(B), SVM-230(B)



Dimension	SVM-210(B)	SVM-220(B)	SVM-230(B)	
Α	130 [5.118]	180 [7.087]	
В	9 [0.3543]	13.5 [0.5315]		
С	145 +0.2/-0.2 [5.709]	200 +0.2/-0.2 [7.874]		
D	22 +0.0/-0.013 (22h6)	35 +0.0/-0.016 (35h6)		
E	110 +0.0/-0.035 (110h7)	114.3 +0/-0.)/-0.035 (114.3h7)	
F (w/o brake)	143 [5.63]	164 [6.457]	212 [8.35]	
F (with brake)	181 [7.126]	213 [8.386]	258 [10.16]	
G	55 [2.17]	75 [2.95]		
Н	15 [0.591]	20 [0.787]		
I		4 [0.157]		

tMNC-158 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Sure AC Servo System Accessories

Accessories

External Regeneration Resistors

Use external resistors to provide additional regenerative capacity and to dissipate heat away from the servo drive.

Part Number	Resistance	SureServo Drives	Price
GS-25P0-BR	40Ω	SVA-2040	\$80.00
GS-2010-BR-ENC	20Ω	SVA-2100, SVA-2300	\$242.00



Resistor GS-25PO-BR

AC Line Filters

Input EMI filters reduce electromagnetic interference or noise on the input side of the servo drive. They are required for CE compliance and recommended for installations prone to or sensitive to electromagnetic interference.

AC Input Power	EMI Filter Rating	EMI Filter Part Number	Price
Single-Phase	250V, 1-phase, 20A	20DRT1W3\$	\$81.00
Three-Phase	250V, 3-phase, 10A	10TDT1W4C	\$86.00
Single-Phase	250V, 1-phase, 20A	20DRT1W3\$	\$81.00
Three-Phase	250V, 3-phase, 10A	10TDT1W4C	\$86.00
Three-Phase	250V, 3-phase, 26A	26TDT1W4C	\$119.00
	Single-Phase Three-Phase Single-Phase Three-Phase	Single-Phase 250V, 1-phase, 20A Three-Phase 250V, 3-phase, 10A Single-Phase 250V, 1-phase, 20A Three-Phase 250V, 3-phase, 10A	Act input Power Livit Pitter Nating Number Single-Phase 250V, 1-phase, 20A 20DRT1W3S Three-Phase 250V, 3-phase, 10A 10TDT1W4C Single-Phase 250V, 1-phase, 20A 20DRT1W3S Three-Phase 250V, 3-phase, 10A 10TDT1W4C



Note: These EMI Filters are electrically compatible with the SureServo drives. However, they are intended to be mounted NEXT TO THE SERVO DRIVE. DO NOT MOUNT THE FILTER UNDER THE DRIVE. THE DRIVE MOUNTING HOLES ON THESE UNITS ARE INTENDED TO BE USED ONLY WITH AUTOMATION DIRECT'S LINE OF VFDs.



AC Line Filter 10TD1W4C

Edison Fuses & Fuji Contactors

SureServo® Drives	Input Type	Input Voltage	Edison Fuse - Class CC	Price*	Contactor**	Price
SVA-2040			HCTR4	\$103.00	SC-E02-xxx	varies
SVA-2100		230V 3-Phase	HCTR7-5	\$114.00	SC-E03-xxx	varies
SVA-2300	Main Input Power		HCTR15	\$97.00	SC-E04-xxx	varies
SVA-2040	1 01101	0001/1 = h	HCTR4	\$103.00	SC-E02-xxx	varies
SVA-2100		230V 1-phase	HCTR10	\$103.00	SC-E03-xxx	varies
SVA-2040 SVA-2100 SVA-2300	Control Input Power	230V 1-phase	HCTR2-5	\$106.00		

Fuses are sold in packages of 10.



Fuji Contactor SC-E02-xxx



Edison Fuse HCTRx

tMNC-159 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Note: For contactors, xxx = coil voltage (for example, SC-E02-220VAC).





Precision Servo Gearboxes

SureGear® Servo Gearbox Overview

PGA In-line Series

The SureGear PGA series of high-precision servo gear reducers is an excellent choice for applications that require good accuracy and reliability at an exceptional value. This in-line planetary gear reducer has a thread-in mounting style, along with a level of precision and torque capacity that is best in its class. Offered in a concentric shaft design with a maximum seven arc-min backlash rating, the SureGear PGA series is an accurate, high-performance, and cost effective solution for any OEM.

The machining quality of the SureGear PGA helical planetary gears provides a very quiet and more efficient reducer than other competitive products that are similarly priced. The SureGear PGA series easily mates to SureServo motors, and is the perfect solution for applications such as gantries, injection-molding machines, pick-and-place automation, and linear slides.

PGB Right-angle Series

The SureGear PGB series of high-precision right-angle servo gear reducers is an excellent choice for applications that require a more compact footprint.

The PGB right-angle planetary gear reducers offer similar technical specifications to the PGA series in-line gear reducers, and provides the customer with an excellent solution when space and clearance requirements are limited.

Offered with a six arc-min backlash rating for 2-stage and nine arc-min backlash for 3-stage, the SureGear PGB series performs to OEMs' demanding expectations.

PGD Hub Style In-line Series

The SureGear PGD series sets a new standard in applications requiring extremely high-torque ratings and rigidity. The compact design and hubstyle output is ideal for equipment that requires high-speed, high-precision indexing movement. The remarkable torsion stiffness and the low backlash of the planetary gearing combine to provide outstanding positioning accuracy.

With a backlash rating less than 3 arc-minutes and exceptional torque handling capabilities, the PGD series offers a high performance robust planetary solution for OEM customers. The PGD reducer is often used for larger indexing applications and dial tables commonly found in packaging and filling equipment and assembly automation systems.

Features

- Thread-in mounting style
- Best-in-class backlash
- Four gear ratios available (5:1, 10:1, 15:1, 25:1), Two additional for PGD models (35:1 and 50:1)
- Mounting hardware included for attaching to SureServo motors
- Helical-cut planetary gears for quiet operation and reduced vibration
- Right-angle reducer utilizes a spiral bevel gear; motor can be located at a 90° position from the reducer, providing a more compact footprint
- Uncaged needle roller bearings for high rigidity and torque
- Adapter bushing connection for simple and effective attachment to most servo motors
- High-viscosity, anti-separation grease does not migrate away from the gears; no leakage through the seal
- Maintenance free: No need to replace the grease for the life of the unit
- At nominal speed, service life is 20,000 hours
- Can be positioned in any orientation
- IP55 environmental rating
- 5-year warranty



SureGear PGA Gearbox



SureGear PGB Gearbox



SureGear 2-Stage Cutaway View

Applications

- Gantries
- Injection-molding machines
- Pick-and-place automation
- Linear slides
- · Packaging machines
- Conveyors

tMNC-161 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Suregear Precision Servo Gearboxes

SureGear® Servo Gearbox Selection

			SureGea	r® Servo	Gearb	ox Sele	ction				
Sure			Frame				Nominal	Nominal	Max		oad Inertia
Servo	Gear	<i>Sure</i> Gear	Size	Output	Torque	Output	Torque	Output	Output	@ 5:1 Mi	
Motor	Ratio	Gearbox	(mm)	N⋅m	lb∙in	N⋅m	lb∙in	Speed (rpm)	Speed (rpm)	kg∙cm²	lb·in·s²
		PGD047-05A1	47					(10111)	(10111)	2.68	0.002
	5:1	PGA050-05A1	50			1.52	13.44	600	1,000	2.85	0.003
	0.1	PGA070-05A1	70				10.10	000	1,000	1.83	0.002
		PGB070-05A1 PGD047-10A1	70 47			1.49	13.16			-2.50** 11.80	-0.002** 0.010
		PGA050-10A1	50	-		3.04	26.89			12.00	0.010
	10:1	PGA070-10A1	70	-		0.01	20.00	300	500	9.40	0.008
SVL-201(B)		PGB070-10A1	70	0.32	2.83	2.98	26.32			-8.00**	-0.007**
3VL-201(D)		PGA050-15A1	50	0.32	2.03	4.32	38.21			25.88	0.023
	15:1	PGA070-15A1	70					200	333	21.38	0.019
		PGB070-15A1	70 47			4.22	37.36			17.33	0.015
		PGD047-25A1 PGA050-25A1	50			7.20	63.68			72.50 72.50	0.064 0.064
	25:1	PGA070-25A1	70			1.20	05.00	120	200	60.63	0.054
		PGB070-25A1	70			7.04	62.26			49.38	0.044
	50:1	PGD064-50A1	64			14.40	127.35	60	100	252.50	0.223
		PGD064-05A2	64			3.04	27.08			20.00	0.018
	5:1	PGA070-05A2	70					600	1,000	20.58	0.018
		PGB070-05A2	70 64	-		2.98	26.51			16.25	0.014 0.074
	10:1	PGD064-10A2 PGA070-10A2	70	-		6.08	54.15	300	500	83.80 84.40	0.074
	10.1	PGB070-10A2	70	-		5.95	53.01	000	000	67.00	0.059
		PGA070-15A2	70			8.64	76.95			190.13	0.168
SVL-202(B)	15:1	PGB070-15A2	70	0.64	5.7	8.45	75.24	200	333	186.08	0.165
0 V L 202(D)		PGB090-15A2	90	0.04	0.7	0.40	10.27			126.00	0.112
		PGD064-25A2	64			14.40	128.25			528.75	0.468
	25:1	PGA070-25A2 PGB070-25A2	70 70					120	200	529.38 518.13	0.468 0.459
	23.1	PGB090-25A2	90			14.08	125.40	120	200	362.50	0.439
		PGD090-25A2	90			14.40	128.25			481.25	0.426
	50:1	PGD090-50A2	90			28.80	256.50		100	2000.00	1.770
	30.1	PGD110-50A2	110			20.00	230.30		100	1250.00	1.106
	- 1	PGD064-05A2	64			6.03	53.20	000	1 000	40.00	0.035
	5:1	PGA070-05A2 PGB070-05A2	70 70			5.91	52.08	600	1,000	40.58 36.25	0.036 0.032
		PGD064-10A2	64	-						163.80	0.032
	10:1	PGA070-10A2	70			12.07	106.40	300	500	164.40	0.145
		PGB070-10A2	70			11.81	104.16			147.00	0.130
		PGA070-15A2	70			17.15	151.20			370.13	0.328
SVL-204(B)	15:1	PGB070-15A2	70	1.27	11.2	16.76	147.84	200	333	366.08	0.324
		PGB090-15A2	90							306.00 1028.75	0.271 0.910
		PGD064-25A2 PGA070-25A2	70			28.58	252.00			1028.75	0.910
	25:1	PGB070-25A2	70			07.04	0.40.40	120	200	1018.13	0.901
		PGB090-25A2	90			27.94	246.40			862.50	0.763
		PGD090-25A2	90			28.58	252.00			981.25	0.868
	50:1	PGD090-50A2	90			57.15	504.00	60	100	4000.00	3.540
	-	PGD110-50A2	110							3250.00	2.876
	5:1	PGA070-05A3 PGB090-05A3	70 90			11.35 11.11	100.70 98.58	600	1000	133.08 90.00	0.118
	0.1	PGD090-05A3	90	1		11.35	100.70	000	1000	120.50	0.000
		PGA090-10A3	90	1		22.71	201.40			511.00	0.452
	10:1	PGB090-10A3	90			22.23	197.16	300	500	371.00	0.328
SVL-207(B)		PGD090-10A3	90	2.39	21.2	22.71	201.40			507.00	0.449
312 201(b)	15:1	PGA090-15A3	90		-1.2	32.27	286.20	200	333	1185.75	1.049
	-	PGB090-15A3	90	-		31.55	279.84			1138.50	1.008
	25:1	PGA090-25A3 PGB090-25A3	90	-		53.78 52.58	477.00 466.40	120	200	3300.00 3175.00	2.921 2.810
	23.1	PGD090-25A3	110	1		53.78	477.00	120	200	2937.50	2.600
1	50:1	PGD110-50A3	110	1		107.55	954.00	60	100	12500.00	11.063
* Available load inert		ited hased on servo mi		ucina the	formula						

^{*} Available load inertia is calculated based on servo motor inertia using the formula: Available Inertia = (5 x Motor Inertia – Gearbox Inertia) x (Gear Ratio)² A 5:1 inertia mismatch is a good target for design purposes. Systems with lower or higher mismatch may be possible, depending on operating conditions.

tMNC-162 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

^{**} This gearbox is NOT a suitable choice at a 5:1 mismatch. If inertia balancing is a selection criteria for your end use, please use a mismatch of 8:1 to 10:1.

Surege Precision Servo Gearboxes

SureGear® Servo Gearbox Selection (continued)

			SureGea	r® Serv	o Gearb	ox Sele	ction				
<i>Sure</i> Servo	Gear	<i>Sure</i> Gear	Frame Size		Nominal Torque	Combo Output	Nominal Torque	Output	Max Output		oad Inertia smatch *
Motor	Ratio	Gearbox	(mm)	N⋅m	lb∙in	N⋅m	lb∙in	Speed (rpm)	Speed (rpm)	kg∙cm²	lb·in·s²
		PGA090-05A4	90			15.68	138.70	(ipiii)	(10111)	315.00	0.279
	5:1	PGB090-05A4	90			15.35	135.78	600	1000	280.00	0.248
		PGD090-05A4	90			15.68	138.70			313.00	0.277
		PGA090-10A4	90			31.45	277.40			1271.00	1.125
	10:1	PGB090-10A4	90			30.69	271.56	300	500	1131.00	1.001
O// 040/D)		PGD090-10A4	90		00.0	31.35	277.40			1267.00	1.121
SVL-210(B)	45.4	PGA120-15A4	120	3.3	29.2	44.55	394.20	000	000	2828.25	2.503
	15:1	PGB120-15A4	120	1		43.56	385.44	200	333	2418.75	2.141
		PGD110-25A4	110			74.25	657.00			7687.50	6.803
	25:1	PGA120-25A4	120			74.23	037.00	120	200	7887.50	6.980
		PGB120-25A4	120			72.60	642.40			6762.50	5.985
	50:1	PGD110-50A4	110			148.50	1314.00	60	100	31500.00	27.878
		PGA090-05A5	90			22.80	201.88			737.50	0.653
	5:1	PGD090-05A5	90				201.00	600	1000	735.50	0.651
		PGB120-05A5	120			22.32	197.63			622.00	0.550
		PGA090-10A5	90			45.60	403.75			2961.00	2.620
	10:1	PGD110-10A5	110			10.00		300	500	2957.00	2.617
SVM-210(B)		PGB120-10A5	120	4.8	42.5	44.64	395.25			2544.00	2.251
OVIVI 210(D)	15:1	PGA120-15A5	120	1.0	12.0	64.80	573.75	200	333	6630.75	58.68
		PGB120-15A5	120			63.36	561.00	200		6221.25	5.506
		PGD110-25A5	110			108.00	956.25			18250.00	16.151
	25:1	PGA120-25A5	120					120	200	18450.00	16.328
		PGB120-25A5	120	_		105.60	935.00			17325.00	15.333
	35:1	PGD110-35A5	110			151.20	1338.75	86	143	35770.00	31.656
		PGD110-05A6	110	-		44.65	395.20			5355.00	4.739
	5:1	PGA120-05A6	120	-				600	1000	5372.50	4.755
		PGB120-05A6	120 155	-		43.71	386.88			5287.00 4989.75	4.679 4.416
		PGB155-05A6 PGD110-10A6	110	1						21540.00	19.063
		PGD110-10A6	120	-		89.30	790.40			21540.00	19.005
SVM-220(B)	10:1	PGB120-10A6	120	9.4	83.2			300	500	21204.00	18.766
		PGB120-10A0	155	-		87.42	773.76			20184.00	17.863
		PGA155-15A6	155	+		126.90	1123.20			48420.00	42.852
	15:1	PGB155-15A6	155	†		124.08	1098.24	200	333	47272.50	41.836
		PGA155-25A6	155	†		211.50	1872.00			134625.00	119.143
	25:1	PGB155-25A6	155	1		206.80	1830.40	120	200	131468.75	116.350
		PGD110-05A6	110							5355.00	4.739
	5:1	PGA120-05A6	120			67.93	601.35	600	1000	5372.50	4.755
		PGB120-05A6	120			66.50	588.69			5287.00	4.679
		PGD110-10A6	110							21540.00	19.063
	10.4	PGA120-10A6	120			135.85	1202.70	000	F00	21555.00	19.076
SVM-230(B)	10:1	PGB120-10A6	120	14.3	12.6	120.00	1177.00	300	500	21204.00	18.766
		PGB155-10A6	155			132.99	1177.38			20184.00	17.863
	15.1	PGA155-15A6	155			193.05	1709.10	200	222	48420.00	42.852
	15:1	PGB155-15A6	155			188.76	1671.12	200	333	47272.50	41.836
	25.1	PGA155-25A6	155			321.75	2848.50	120	200	134625.00	119.143
	25:1	PGB155-25A6	155			314.60	2785.20	120	200	131468.75	116.350

^{*} Available load inertia is calculated based on servo motor inertia using the formula: Available Inertia = (5 x Motor Inertia — Gearbox Inertia) x (Gear Ratio)²

A 5:1 inertia mismatch is a good target for design purposes. Systems with lower or higher mismatch may be possible, depending on operating conditions.

tMNC-163 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Suregear Precision Servo Gearboxes

Pricing & Specifications - In-Line Shaft PGA Series

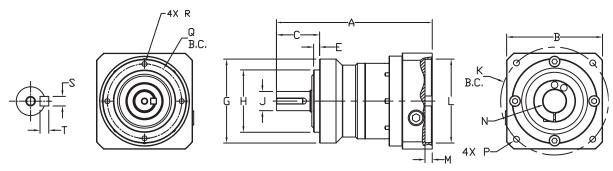
Pricing &	Оро	OII									n-Line		PGA S	erie	S			
Part Number	Price	Frame Size (mm)	Ratio	Reduction	Nominal Output Torque (N·m [lb·in])	Max. Acceleration Torque (N·m [lb·in])	Emergency Stop Torque (N·m [lb·in])	Backlash (arc-min)	Nominal Input Speed (rpm)	Max. Input Speed (rpm)	Allowable Radial Load (N[lb])	Allowable Thrust Load (N[lb])	Moment of Inertia (kg·cm²)	Efficiency (%)	Max. Housing Temperature	Approx Weight (kg [lb])	Environmental Rating	Fits SureServo Servo Motor
PGA050-05A1	\$420.00		5:1	single	9 [80]	18 [159]	35 [310]	5			290 [65]	330 [74]	0.036	95		0.7		
PGA050-10A1	\$442.00	50	10:1	single	6 [53]	12 [106]	30 [266]) 5	4000	8000	360 [81]	450 [101]	0.030	90		[1.5]		
PGA050-15A1	\$606.00	50	15:1	double	6 [53]	12 [106]	30 [266]	7	4000	8000	410 [92]	540 [121]	0.035	90		0.8		
PGA050-25A1	\$606.00		25:1	double	9 [80]	18 [159]	35 [310]	,			490 [110]	640 [144]	0.034	90		[1.8]		SVI 201/P)
PGA070-05A1	\$420.00		5:1	single	27 [239]	50 [443]	100 [885]				510 [115]	390 [88]	0.077	O.E.		1.5		SVL-201(B)
PGA070-10A1	\$442.00		10:1	single	18 [159]	35 [310]	80 [708]				640 [144]	530 [119]	0.056	95		[3.3]		
PGA070-15A1	\$606.00		15:1	double	18 [159]	35 [310]	80 [708]				740 [166]	630 [142]	0.055	90		1.7		
PGA070-25A1	\$606.00		25:1	double	27 [239]	50 [443]	100 [885]				870 [196]	790 [178]	0.053	90		[3.7]		
PGA070-05A2	\$458.00	70	5:1	single	27 [239]	50 [443]	100 [885]				510 [115]	390 [88]	0.160	95		1.5		
PGA070-10A2	\$458.00		10:1	single	18 [159]	35 [310]	80 [708]				640 [144]	530 [119]	0.140	90		[3.3]		SVL-202(B)
PGA070-15A2	\$628.00	0.00 15.1 double [159] [310] [7	80 [708]				740 [166]	630 [142]	0.140	90		1.7		SVL-204(B)				
PGA070-25A2	\$628.00		25:1	double	27 [239]	50 [443]	100 [885]				870 [196]	790 [178]	0.130	90		[3.7]		
PGA070-05A3	\$458.00		5:1	single	27 [239]	50 [443]	100 [885]				510 [115]	390 [88]	0.360	95		1.5 [3.3]		
PGA090-10A3	\$543.00		10:1	single	50 [443]	80 [708]	200 [1770]				1200 [270]	1600 [360]	0.750	90		3.5 [7.7]		SVI 207/B)
PGA090-15A3	\$717.00		15:1	double	50 [443]	80 [708]	200 [1770]		2000	6000	1400 [315]	1900 [427]	0.720	90	90 °C [194 °F]	4.0	IP55	SVL-207(B)
PGA090-25A3	\$717.00		25:1	double	75 [664]	125 [1106]	250 [2213]		3000	6000	1600 [360]	2200 [495]	0.710	90		[8.8]		
PGA090-05A4	\$542.00	90	5:1	single	75 [664]	125 [1106]	250 [2213]	5			960 [216]	1200 [270]	2.900			3.5		SVI 210/P)
PGA090-10A4	\$542.00		10:1	single	50 [443]	80 [708]	200 [1770]				1200 [270]	1600 [360]	2.800	O.E.		[7.7]		SVL-210(B)
PGA090-05A5	\$542.00		5:1	single	75 [664]	125 [1106]	250 [2213]				960 [216]	1200 [270]	2.900	95		3.5		SVA 210/D)
PGA090-10A5	\$542.00		10:1	single	50 [443]	80 [708]	200 [1770]				1200 [270]	1600 [360]	2.800			[7.7]		SVM-210(B)
PGA120-15A4	\$900.00		15:1	double	120 [1062]	225 [1991]	500 [4425]				2300 [517]	3000 [674]	2.800			8.7		SVL-210(B)
PGA120-25A4	\$900.00		25:1	double	180 [1593]	330 [2921]	625 [5532]				2700 [607]	3700 [832]	2.800	90		[19.2]		3VL-210(B)
PGA120-15A5	\$900.00	100	15:1	double	120 [1062]	225 [1991]	500 [4425]				2300 [517]	3000 [674]	2.800	90		8.7		CVA4 210/P)
PGA120-25A5	\$900.00	120	25:1	double	180 [1593]	330 [2921]	625 [5532]				2700 [607]	3700 [832]	2.800			[19.2]		SVM-210(B)
PGA120-05A6	\$718.00		5:1	single	180 [1593]	330 [2921]	625 [5532]				1600 [360]	1900 [427]	11.000	٥٢		7.8		
PGA120-10A6	\$718.00		10:1	single	120 [1062]	225 [1991]	500 [4425]				2000 [450]	2500 [562]	11.000	95		[17.2]		
PGA155-10A6	\$887.00		10:1	single	240 [2124]	470 [4160]	1000 [8851]				4700 [1057]	4100 [922]	11.000	95		16 [35.3]		SVM-220(B) SVM-230(B)
PGA155-15A6	\$1,207.00	155	15:1	double	240 [2124]	470 [4160]	1000 [8851]		2000	4000	5400 [1214]	4900 [1102]	11.000	00		18		230(8)
PGA155-25A6	\$1,207.00		25:1	double	360 [3186]	700 [6196]	1250 [11063]				6400 [1439]	6100 [1371]	11.000	90		[40.0]		

tMNC-164 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Suregear Precision Servo Gearboxes

Dimensions - In-Line Shaft PGA Series



SureGear PGA Series In-Line Shaft Gearboxes Dimension Drawing

Sure	Gear ®	Prec	ision S	ervo (Gearbox	d Dimen	sions –	In-Line	Shaft I	PGA S	eries (dimen	sions =	mm [iı	1])	
Part Number	A	В	С	Ε	G	Н	J	K	L	М	N	P	Q	R	S	T
PGA050-05A1	88.5	42.0	24.5	4.0	Ø50.0	Ø35.0	Ø12.0	Ø46.0	Ø30.0	5.0	Ø8.0	M4-	Ø44.0	M4-	4.0	4.0
PGA050-10A1	[3.48]	[1.65]	[0.96]	[0.16]	[Ø1.97]	[Ø1.38]	[Ø0.47]	[Ø1.81]	[Ø1.18]	[0.20]	[Ø0.31]	0.7x9	[Ø1.73]	0.7x8	[0.16]	[0.16]
PGA050-15A1	105.0	42.0	24.5	4.0	Ø50.0	Ø35.0	Ø12.0	Ø46.0	Ø30.0	5.0	Ø8.0	M4-	Ø44.0	M4-	4.0	4.0
PGA050-25A1	[4.13]	[1.65]	[0.96]	[0.16]	[Ø1.97]	[Ø1.38]	[Ø0.47]	[Ø1.81]	[Ø1.18]	[0.20]	[Ø0.31]	0.7x9	[Ø1.73]	0.7x8	[0.16]	[0.16]
PGA070-05A1	112.0	52.0	36.0	5.0	Ø70.0	Ø52.0	Ø16.0	Ø46.0	Ø30.0	5.0	Ø8.0	M4-	Ø62.0	M5-	5.0	5.0
PGA070-10A1	[4.41]	[2.05]	[1.42]	[0.20]	[Ø2.76]	[Ø2.05]	[Ø0.63]	[Ø1.81]	[Ø1.18]	[0.20]	[Ø0.31]	0.7x9	[Ø2.44]	0.8x10	[0.20]	[0.20]
PGA070-05A2	115.0	65.0	36.0	5.0	Ø70.0	Ø52.0	Ø16.0	Ø70.0	Ø50.0	5.0	Ø14.0	M5-	Ø62.0	M5-	5.0	5.0
PGA070-10A2	[4.53]	[2.56]	[1.42]	[0.20]	[Ø2.76]	[Ø2.05]	[Ø0.63]	[Ø2.76]	[Ø1.97]	[0.20]	[Ø0.55]	0.8x11	[Ø2.44]	0.8x10	[0.20]	[0.20]
PGA070-05A3	130.0	80.0	36.0	5.0	Ø70.0	Ø52.0	Ø16.0	Ø90.0	Ø70.0	6.0	Ø19.0	M6-	Ø62.0	M5-	5.0	5.0
	[5.12]	[3.15]	[1.42]	[0.20]	[Ø2.76]	[Ø2.05]	[Ø0.63]	[Ø3.54]	[Ø2.76]	[0.24]	[Ø0.75]	1.0x13	[Ø2.44]	0.8x10	[0.20]	[0.20]
PGA070-15A1	131.0	52.0	36.0	5.0	Ø70.0	Ø52.0	Ø16.0	Ø46.0	Ø30.0	5.0	Ø8.0	M4-	Ø62.0	M5-	5.0	5.0
PGA070-25A1	[5.16]	[2.05]	[1.42]	[0.20]	[Ø2.76]	[Ø2.05]	[Ø0.63]	[Ø1.81]	[Ø1.18]	[0.20]	[Ø0.31]	0.7x9	[Ø2.44]	0.8x10	[0.20]	[0.20]
PGA070-15A2	136.0	65.0	36.0	5.0	Ø70.0	Ø52.0	Ø16.0	Ø70.0	Ø50.0	5.0	Ø14.0	M5-	Ø62.0	M5-	5.0	5.0
PGA070-25A2	[5.35]	[2.56]	[1.42]	[0.20]	[Ø2.76]	[Ø2.05]	[Ø0.63]	[Ø2.76]	[Ø1.97]	[0.20]	[Ø0.55]	0.8x11	[Ø2.44]	0.8x10	[0.20]	[0.20]
PGA090-10A3	153.0	80.0	46.0	7.0	Ø90.0	Ø68.0	Ø22.0	Ø90.0	Ø70.0	6.0	Ø19.0	M6-	Ø80.0	M6-	6.0	6.0
	[6.02]	[3.15]	[1.81]	[0.28]	[Ø3.54]	[Ø2.68]	[Ø0.87]	[Ø3.54]	[Ø2.76]	[0.24]	[Ø0.75]	1.0x13	[Ø3.15]	1.0x12	[0.24]	[0.24]
PGA090-05A4	170.0	100.0	46.0	7.0	Ø90.0	Ø68.0	Ø22.0	Ø115.0	Ø95.0	8.0	Ø22.0 *	M8-	Ø80.0	M6-	6.0	6.0
PGA090-10A4	[6.69]	[3.94]	[1.81]	[0.28]	[Ø3.54]	[Ø2.68]	[Ø0.87]	[Ø4.53]	[Ø3.74]	[0.31]	[Ø0.87]	1.25x17	[Ø3.15]	1.0x12	[0.24]	[0.24]
PGA090-05A5	165.0	130.0	46.0	7.0	Ø90.0	Ø68.0	Ø22.0	Ø145.0	Ø110.0	8.0	Ø22.0 *	M8-	Ø80.0	M6-	6.0	6.0
PGA090-10A5	[6.50]	[5.12]	[1.81]	[0.28]	[Ø3.54]	[Ø2.68]	[Ø0.87]	[Ø5.71]	[Ø4.33]	[0.31]	[Ø0.87]	1.25x17	[Ø3.15]	1.0x12	[0.24]	[0.24]
PGA090-15A3	175.0	80.0	46.0	7.0	Ø90.0	Ø68.0	Ø22.0	Ø90.0	Ø70.0	6.0	Ø19.0	M6-	Ø80.0	M6-	6.0	6.0
PGA090-25A3	[6.89]	[3.15]	[1.81]	[0.28]	[Ø3.54]	[Ø2.68]	[Ø0.87]	[Ø3.54]	[Ø2.76]	[0.24]	[Ø0.75]	1.0x13	[Ø3.15]	1.0x12	[0.24]	[0.24]
PGA120-05A6	225.0	180.0	70.0	9.0	Ø120.0	Ø90.0	Ø32.0	Ø200.0	Ø114.0	8.0	Ø35.0 *	M12-	Ø108.0	M8-	10.0	8.0
PGA120-10A6	[8.86]	[7.09]	[2.76]	[0.35]	[Ø4.72]	[Ø3.54]	[Ø1.26]	[Ø7.87]	[Ø4.49]	[0.31]	[Ø1.38]	1.75x25	[Ø4.25]	1.25x16	[0.39]	[0.31]
PGA120-15A4	231.5	100.0	70.0	9.0	Ø120.0	Ø90.0	Ø32.0	Ø115.0	Ø95.0	8.0	Ø22.0 *	M8-	Ø108.0	M8-	10.0	8.0
PGA120-25A4	[9.11]	[3.94]	[2.76]	[0.35]	[Ø4.72]	[Ø3.54]	[Ø1.26]	[Ø4.53]	[Ø3.74]	[0.31]	[Ø0.87]	1.25x17	[Ø4.25]	1.25x16	[0.39]	[0.31]
PGA120-15A5	231.5	130.0	70.0	9.0	Ø120.0	Ø90.0	Ø32.0	Ø145.0	Ø110.0	8.0	Ø22.0 *	M8-	Ø108.0	M8-	10.0	8.0
PGA120-25A5	[9.11]	[5.12]	[2.76]	[0.35]	[Ø4.72]	[Ø3.54]	[Ø1.26]	[Ø5.71]	[Ø4.33]	[0.31]	[Ø0.87]	1.25x17	[Ø4.25]	1.25x16	[0.39]	[0.31]
PGA155-10A6	264.0	180.0	97.0	12.0	Ø155.0	Ø120.0	Ø40.0	Ø200.0	Ø114.0	8.0	Ø35.0 *	M12-	Ø140.0	M10-	12.0	8.0
	[10.39]	[7.09]	[3.82]	[0.47]	[Ø6.10]	[Ø4.72]	[Ø1.57]	[Ø7.87]	[Ø4.49]	[0.31]	[Ø1.38]	1.75x25	[Ø5.51]	1.50x28	[0.47]	[0.31]
PGA155-15A6	298.5	180.0	97.0	12.0	Ø155.0	Ø120.0	Ø40.0	Ø200.0	Ø114.0	8.0	Ø35.0 *	M12-	Ø140.0	M10-	12.0	8.0
PGA155-25A6	[11.75]	[7.09]	[3.82]	[0.47]	[Ø6.10]	[Ø4.72]	[Ø1.57]	[Ø7.87]	[Ø4.49]	[0.31]	[Ø1.38]	1.75x25	[Ø5.51]	1.50x28	[0.47]	[0.31]

Dimension with supplied bushing

NOTE: See our website: www.AutomationDirect.com for complete engineering drawings.

tMNC-165 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Sure Gearboxes Sure Gearboxes

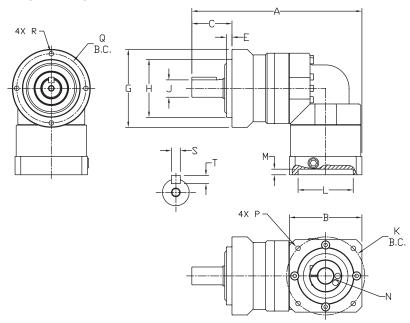
Pricing & Specifications - Right-Angle Shaft PGB Series

Fricing &				Gear®		_		_	_	_				erie	es			
Part Number	Price	Frame Size (mm)	Ratio	Reduction	Nominal Output Torque (N·m [lb·in])	Max. Acceleration Torque (N·m [lb·in])	Emergency Stop Torque (N·m [Ib·in])	Backlash (arc-min)	Nominal Input Speed (rpm)	Max. Input Speed (rpm)	Allowable Radial Load (N[lb])	Allowable Thrust Load (N[lb])	Moment of Inertia (kg·cm²)	Efficiency (%)	Max. Housing Temperature	Approx Weight (kg [lb])	Environmental Rating	Fits SureServo Servo Motor
PGB070-05A1	\$712.00		5:1	double	22 [195]	40 [354]	80 [708]				510 [115]	390 [88]	0.250	00		1.9		
PGB070-10A1	\$712.00		10:1	double	16 [142]	32 [283]	65 [575]	6			640 [144]	530 [119]	0.230	93		[4.2]		SVI 201/B)
PGB070-15A1	\$900.00		15:1	triple	16 [142]	32 [283]	65 [575]	9			740 [166]	630 [142]	0.073	88		1.7		SVL-201(B)
PGB070-25A1	\$900.00	70	25:1	triple	24 [212]	45 [398]	90 [797]	9			870 [196]	790 [178]	0.071	00		[3.7]		
PGB070-05A2	\$712.00	70	5:1	double	22 [195]	40 [354]	80 [708]	6			510 [115]	390 [88]	0.320	93		1.9		SVL-202(B)
PGB070-10A2	\$712.00		10:1	double	16 [142]	32 [283]	65 [575]	0			640 [144]	530 [119]	0.300	90		[4.2]		SVL-204(B)
PGB070-15A2	\$900.00		15:1	triple	16 [142]	32 [283]	65 [575]	9			740 [166]	630 [142]	0.118	88		1.7		SVL-202(B)
PGB070-25A2	\$900.00		25:1	triple	24 [212]	45 [398]	90 [797]	J			870 [196]	790 [178]	0.115	00		[3.7]		3VL 202(B)
PGB090-15A2	\$1,099.00		15:1	triple	45 [398]	65 [575]	170 [1505]	9			1400 [314]	1900 [427]	0.410	88		4.3		SVL-202(B)
PGB090-25A2	\$1,099.00		25:1	triple	65 [575]	110 [974]	220 [1947]	J			1600 [360]	2200 [495]	0.400	00		[9.5]		SVL-204(B)
PGB090-05A3	\$842.00		5:1	double	65 [575]	90 [797]	220 [1947]	6			960 [216]	1200 [270]	2.130	93		4.9		
PGB090-10A3	\$842.00	90	10:1	double	45 [398]	65 [575]	170 [1505]	0	3000	6000	1200 [270]	1600 [360]	2.020	50		[10.8]		SVL-207(B)
PGB090-15A3	\$1,099.00		15:1	triple	45 [398]	65 [575]	170 [1505]	9	0000	0000	1400 [314]	1900 [427]	0.600	88		4.3		372 207 (5)
PGB090-25A3	\$1,099.00		25:1	triple	65 [575]	110 [974]	220 [1947]				1600 [360]	2200 [495]	0.590	00	90 °C	[9.5]	IP55	
PGB090-05A4	\$842.00		5:1	double	65 [575]	90 [797]	220 [1947]	6			960 [216]	1200 [270]	4.260	93	[194 °F]	4.9	00	
PGB090-10A4	\$842.00		10:1	double	45 [398]	65 [575]	170 [1505]				1200 [270]	1600 [360]	4.150	00		[10.8]		SVL-210(B)
PGB120-15A4	\$1,365.00		15:1	triple	110 [974]	200 [1770]	450 [3983]	9			2300 [517]	3000 [674]	4.700	88		10		012 210(5)
PGB120-25A4	\$1,365.00		25:1	triple	150 [1328]	300 [2655]	550 [4868]	J			2700 [607]	3700 [832]	4.640	00		[22]		
PGB120-05A5	\$1,099.00		5:1	double	120 [1062]	240 [2124]	500 [4425]	6			1600 [360]	1900 [427]	6.610	93		10.2		
PGB120-10A5	\$1,099.00	120	10:1	double	110 [974]	200 [1770]	450 [3983]	Ť			2000 [450]	2500 [562]	6.050			[22.5]		SVM-210(B)
PGB120-15A5	\$1,365.00		15:1	triple	110 [974]	200 [1770]	450 [3983]	9			2300 [517]	3000 [674]	4.700	88		10		,
PGB120-25A5	\$1,365.00		25:1	triple	150 [1328]	300 [2655]	550 [4868]				2700 [607]	3700 [832]	4.640			[22]		
PGB120-05A6	\$1,099.00		5:1	double	120 [1062]	240 [2124]	500 [4425]	6			1600 [360]	1900 [427]	13.690	93		10.2		SVM-220(B)
PGB120-10A6	\$1,099.00		10:1	double	110 [974]	200 [1770]	450 [3983]				2000 [450]	2500 [562]	13.120			[22.5]		SVM-230(B)
PGB155-15A6	\$1,599.00		15:1	triple	200 [1770]	400 [3540]	750 [6638]	9			5400 [1214]	4900 [1102]	15.070	88		20.4		SVM-220(B)
PGB155-25A6	\$1,599.00	155	25:1	triple	300 [2655]	600 [5310]	1100 [9736]	-	2000	4000	6400 [1439]	6100 [1371]	14.820			[45.0]		(-)
PGB155-05A6	\$1,265.00	.50	5:1	double	200 [1770]	400 [3540]	1100 [9736]	6	2500	.500	3800 [854]	3000 [674]	21.280	93		19.8		SVM-220(B)
PGB155-10A6	\$1,265.00		10:1	double	200 [1770]	400 [3540]	750 [6638]	Ü			4700 [1057]	4100 [922]	19.030	50		[43.7]		SVM-230(B)

tMNC-166 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Sure Precision Servo Gearboxes

Dimensions - Right-Angle Shaft PGB Series



SureGear PGB Series Right-Angle Shaft Gearboxes Dimension Drawing

SureGe	ar® Pro	ecisio	n Serv	o Gea	rbox Di	mensio	ns – Ri	ight-An	gle Sha	ft PG/	A Series	s (dim	ension	s = mm	[in])	
Part Number	A	В	С	E	G	Н	J	K	L	М	N	P	Q	R	S	Т
PGB070-05A1 PGB070-10A1	151.5	52.0 [2.05]						Ø46.0 [Ø1.81]	Ø30.0 [Ø1.18]		Ø8.0 [Ø0.31]	M4- 0.7x9				
PGB070-05A2 PGB070-10A2	[5.96]	65.0 [2.56]	36.0	5.0	Ø70.0	Ø52.0	Ø16.0	Ø70.0 [Ø2.76]	Ø50.0 [Ø1.97]		Ø14.0 [Ø0.55]	M5- 0.8x11	Ø62.0	M5-	5.0	5.0
PGB070-15A1 PGB070-25A1	158.0 [6.22]	52.0 [2.05]	[1.42]	[0.20]	[Ø2.76]	[Ø2.05]	[Ø0.63]	Ø46.0 [Ø1.81]	Ø30.0 [Ø1.18]	5.0 [0.20]	Ø8.0 [Ø0.31]	M4- 0.7x9	[Ø2.44]	0.8x10	[0.20]	[0.20]
PGB070-15A2 PGB070-25A2	163.5 [6.44]	65.0						Ø70.0	Ø50.0		Ø14.0	M5-				
PGB090-15A2 PGB090-25A2	204.5 [8.05]	[2.56]						[Ø2.76]	[Ø1.97]		[Ø0.55]	0.8x11				
PGB090-05A3 PGB090-10A3	205.5 [8.09]	80.0	46.0	7.0	Ø90.0	Ø68.0	Ø22.0	Ø90.0	Ø70.0	6.0	Ø19.0	M6-	Ø80.0	M6-	6.0	6.0
PGB090-15A3 PGB090-25A3	210.5 [8.29]	[3.15]	[1.81]	[0.28]	[Ø3.54]	[Ø2.68]	[Ø0.87]	[Ø3.54]	[Ø2.76]	[0.24]	[Ø0.75]	1.0x13	[Ø3.15]	1.0x12	[0.24]	[0.24]
PGB090-05A4 PGB090-10A4	205.5 [8.09]	100.0						Ø115.0	Ø95.0							
PGB120-15A4 PGB120-25A4	272.0 [10.71]	[3.94]						[Ø4.53]	[Ø3.74]		Ø22.0 *	M8-				
PGB120-05A5 PGB120-10A5	266.0 [10.47]	130.0	70.0	9.0	Ø120.0	Ø90.0	Ø32.0	Ø145.0	Ø110.0		[Ø0.87]	1.25x17	Ø108.0	M8-	10.0	
PGB120-15A5 PGB120-25A5	272.0 [10.71]	[5.12]	[2.76]	[0.35]	[Ø4.72]	[Ø3.54]	[Ø1.26]	[Ø5.71]	[Ø4.33]	8.0 [0.31]			[Ø4.25]	1.25x16	[0.39]	8.0
PGB120-05A6 PGB120-10A6	268.5 [10.57]															[0.31]
PGB155-05A6 PGB155-10A6	341.0 [13.43]	180.0 [7.09]	[7.09] 97.0	12.0	Ø155.0	Ø120.0	Ø40.0	Ø200.0 [Ø7.87]	Ø114.0 [Ø4.50]		Ø35.0 * [Ø1.38]	M12- 1.75x25	Ø140.0	M10-	12.0	
PGB155-15A6 PGB155-25A6	364.0 [14.33]		[3.82]	[0.47]	[Ø6.10]	[Ø4.72]	[Ø1.57]						[Ø5.51]	1.5x20	[0.47]	
* Dimension with s	supplied b	ushing														

NOTE: See our website: www.AutomationDirect.com for complete engineering drawings.

tMNC-167 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5



Suregear Precision Servo Gearboxes

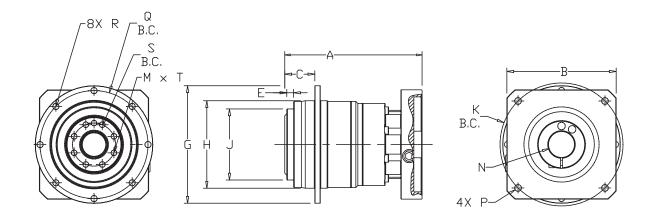
Pricing & Specifications – Hub Style In-Line PGD Series

			Sure	Gear®) Preci	sion S	ervo G	eart	oxes	– Hub	Style	In-Lin	e PGD	Ser	ies			
Part Number	Price	Frame Size (mm)	Ratio	Reduction	Nominal Output Torque (N·m [lb·in])	Max. Acceleration Torque (N·m [lb·in])	Emergency Stop Torque (N·m [lb·in])	Backlash (arc-min)	Nominal Input Speed (rpm)	Max. Input Speed (rpm)	Allowable Radial Load (N[lb])	Allowable Thrust Load (N[lb])	Moment of Inertia (kg·cm²)	Efficiency (%)	Max. Housing Temperature	Approx Weight (kg [lb])	Environmental Rating	Fits SureServo Servo Motor
PGD047-05A1	\$762.00		5:1	single	9 [80]	18 [159]	35 [310]				300 [67]	330 [74]	0.043	05		0.7		
PGD047-10A1	\$762.00	47	10:1	single	6 [53]	12 [106]	30 [266]	≤3	4000	8000	370 [83]	450 [101]	0.032	95		[1.5]		SVII 201/B)
PGD047-25A1	\$953.00		25:1	double	9 [80]	18 [159]	35 [310]	≤5			510 [115]	550 [124]	0.034	90		0.8 [1.8]		SVL-201(B)
PGD064-50A1	\$1,153.00		50:1	double	27 [239]	50 [443]	100 [885]				850 [191]	750 [169]	0.049	90		1.6 [3.5]		
PGD064-05A2	\$984.00	64	5:1	single	27 [239]	50 [443]	100 [885]				400 [90]	390 [88]	0.1	95		1.4 [3.1]		
PGD064-10A2	\$984.00	04	10:1	single	18 [159]	35 [310]	80 [708]				500 [112]	530 [119]	0.062	95		1.4 [3.1]		
PGD064-25A2	\$1,153.00		25:1	double	27 [239]	50 [443]	100 [885]				680 [153]	750 [169]	0.054	90		1.6		SVL-202(B) SVL-204(B)
PGD090-25A2	\$1,322.00		25:1	double	75 [664]	125 [1106]	250 [2213]				1300 [292]	1400 [315]	0.130	90		4 [8.8]		
PGD090-50A2	\$1,322.00		50:1	double	75 [664]	125 [1106]	250 [2213]				1700 [382]	1700 [382]	0.099	90		4 [8.8]		
PGD090-05A3	\$1,153.00		5:1	single	75 [664]	125 [1106]	250 [2213]				780 [175]	680 [153]	0.580	95		3.6 [7.9]		SVL-207(B)
PGD090-10A3	\$1,153.00	90	10:1	single	50 [443]	80 [708]	200 [1770]				980 [220]	920 [207]	0.330	95		3.6 [7.9]		3VL-207(B)
PGD090-05A4	\$1,153.00		5:1	single	75 [664]	125 [1106]	250 [2213]				780 [175]	680 [153]	0.580	95	90 °C	3.6 [7.9]	IP54	SVL-210(B)
PGD090-10A4	\$1,153.00		10:1	single	50 [443]	80 [708]	200 [1770]				980 [220]	920 [207]	0.330	95	[194 °F]	3.6 [7.9]	(IP65)	3VL-210(B)
PGD090-05A5	\$1,153.00		5:1	single	75 [664]	125 [1106]	250 [2213]	≤3	3000	6000	780 [175]	680 [153]	0.580	95		3.6 [7.9]		SVM-210(B)
PGD110-50A2	\$1,687.00		50:1	double	180 [1593]	330 [2921]	625 [5532]				10000 [2248]	6800 [1529]	0.400	90		8.6 [19]		SVL-202(B) SVL-204(B)
PGD110-25A3	\$1,687.00		25:1	double	180 [1593]	330 [2921]	625 [5532]				8200 [1843]	5500 [1236]	0.700	90		8.6 [19]		SVL-207(B)
PGD110-50A3	\$1,687.00		50:1	double	180 [1593]	330 [2921]	625 [5532]				10000 [2248]	6800 [1529]	0.400	90		8.6 [19]		012 207 (0)
PGD110-25A4	\$1,687.00		25:1	double	180 [1593]	330 [2921]	625 [5532]				8200 [1843]	5500 [1236]	0.700	90		8.6 [19]		SVL-210(B)
PGD110-50A4	\$1,687.00		50:1	double	180 [1593]	330 [2921]	625 [5532]				10000 [2248]	6800 [1529]	0.400	90		8.6 [19]		
PGD110-10A5	\$1,434.00	110	10:1	single	120 [1062]	225 [1991]	500 [4425]				6200 [1394]	4200 [944]	1.100	95		7.8 [17.2]		
PGD110-25A5	\$1,687.00		25:1	double	180 [1593]	330 [2921]	625 [5532]				8200 [1843]	5500 [1236]	0.700	90		8.6 [19]		SVM-210(B)
PGD110-35A5	\$1,687.00		35:1	double	180 [1593]	330 [2921]	625 [5532]				9000 [2023]	6100 [1371]	0.700	90		8.6 [19]		
PGD110-05A6	\$1,434.00		5:1	single	180 [1593]	330 [2921]	625 [5532]				5000 [1124]	3400 [427]	2.300	95		7.8 [17.2]		SVM-220(B)
PGD110-10A6	\$1,434.00		10:1	single	120 [1062]	225 [1991]	500 [4425]				6200 [1394]	4200 [944]	1.100	95		7.8 [17.2]		SVM-230(B)

tMNC-168 **Motion Control** 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Suregear Precision Servo Gearboxes

Dimensions - Hub Style In-Line PGD Series



SureGear PGD Series Hub Style In-Line Gearboxes Dimension Drawing

	SureGea	r® Pre	cisior	Servo	Geart	ox Dim	ensions	– Hub	Style In-L	ine F	GD Ser	ies (c	limensi	ons = n	nm [in]	
	Part Number	A*	В*	С	Ε	G	Н	J	K	M	N**	Р	Q	R	S	Т
1	PGD047-05A1 PGD047-10A1	66.5	42.0			Ø72.0	Ø47.0	Ø28.0		4	Ø8.0		Ø67.0	3.4	Ø20.0	M3-
2	PGD047-25A1	[2.62]	[1.65]			[Ø2.83]	[Ø1.85]	[Ø1.102]	Ø46.0 [Ø1.811]	4	[Ø0.31]	M4- 0.7x9	[Ø2.6378]	[0.13]	[Ø0.7874]	0.5x6.5
2	PGD064-50A1	98.0 [3.86]	52.0 [2.05]	19.5 [0.7677]	3.0 [0.1181]						Ø8.0 [Ø0.31]					M5- 0.8x10
1	PGD064-05A2 PGD064-10A2	82.0 [3.228]				Ø86.0 [Ø3.385]	Ø64.0 [Ø2.52]	Ø40.0 [Ø1.575]		8	Ø14.0 [Ø0.55]		Ø79.0 [Ø3.11]	4.5 [0.18]	Ø31.5 [Ø1.24]	M5- 0.8x4
2	PGD064-25A2	103.0 [4.055]	65.0 [2.56]						Ø70.0 [Ø2.756]		Ø14.0 [Ø0.55]	M5- 0.8x11				M5- 0.8x10
2	PGD090-25A2 PGD090-50A2	122.0 [4.803]									Ø14.0 [Ø0.55]					
1	PGD090-05A3 PGD090-10A3	110.0 [4.33]	80.0 [3.15]	30.0		Ø118.0	Ø90.0 [Ø3.54]	Ø63.0 [Ø2.48]	Ø90.0 [Ø3.543]	8	Ø19.0 [Ø0.75]	M6- 1.0x13	Ø109.0		Ø50.0	
1	PGD090-05A4 PGD090-10A4	127.0	100.0 [3.94]	[1.1811]		[Ø4.65]		[02.10]	Ø115.0 ±0.2 [Ø4.528]	U	Ø28.0	M8-	[Ø4.30]		[Ø1.9685]	
1	PGD090-05A5	[5.0]	130.0 [5.12]						Ø145.0 ±0.2 [Ø5.709]		[Ø1.102]	1.25x17				
2	PGD110-50A2	159.5 [6.28]	65.0 [2.56]		6.0				Ø70.0 [Ø2.756]		Ø14.0 [Ø0.55]	M5- 0.8x11		5.5		M6-
2	PGD110-25A3 PGD110-50A3	169.5 [6.673]	80.0 [3.15]		[0.236]				Ø90.0 [Ø3.543]		Ø19.0 [Ø0.75]	M6- 1.0x13		[0.22]		1.0x12
2	PGD110-25A4 PGD110-50A4	186.5 [7.3425]	100.0 [3.94]	29.0		Ø145.0	Ø110.0	Ø80.0 [Ø3.15]	Ø115.0 ±0.2 [Ø4.528]	45			Ø135.0		Ø63.0	
1	PGD110-10A5	159.0 [6.26]	130.0	[1.142]		[Ø5.70]	[Ø4.33]	[ພວ. ເວ]	Ø145.0 ±0.2	15	Ø28.0 [Ø1.102]	M8- 1.25x17	[Ø5.315]		[Ø2.48]	
2	PGD110-25A5 PGD110-35A5	186.5 [7.3425]	[5.12]						[Ø5.709]							
1	PGD110-05A6 PGD110-10A6	180.0 [7.087]	180.0 [7.087]						Ø200.0 ±0.2 [Ø7.874]		Ø38.0 [Ø1.45]	M12- 1.75x25				
	* Length will vary ** Bushing will be NOTE: See our we	inserted	to adap	t to moto		for compl	ete engine	eering dra	wings.							

tMNC-169 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5

Sure Precision Servo Gearboxes

SureGear® Servo Gearbox Replacement Parts



	SureGear® Precision Servo Gearboxes – Replacement Parts											
Part Number	Price	Description										
PG050-KEY	\$4.00	Output Shaft Key, replacement, 4 x 4 x 14 mm, for SureGear PGA050 series gearboxes.										
PG070-KEY	\$4.00	Output Shaft Key, replacement, 5 x 5 x 22 mm, for SureGear PGA070 and PGB070 series gearboxes.										
PG090-KEY	\$4.00	Output Shaft Key, replacement, 6 x 6 x 28 mm, for SureGear PGA090 and PGB090 series gearboxes.										
PG120-KEY	\$4.00	Output Shaft Key, replacement, 10 x 8 x 45 mm, for SureGear PGA120 and PGB120 series gearboxes.										
PG155-KEY	\$4.00	Output Shaft Key, replacement, 12 x 8 x 65 mm, for SureGear PGA155 and PGB155 series gearboxes.										
PGA4-A5-BUSH	\$20.00	Input Shaft Bushing, replacement, 28 x 22 x 30.5 mm, for all SureGear gearboxes using SVL-210(B) and SVM-210(B) SureServo motors.										
PGA6-BUSH	\$20.00	Input Shaft Bushing, replacement, 38 x 35 x 36 mm, for all SureGear gearboxes using SVM-220(B) and SVM-230(B) SureServo motors.										

tMNC-170 Motion Control 1 - 8 0 0 - 6 3 3 - 0 4 0 5