LUCY-H200 3.5G tri-band HSDPA wireless module System Integration Manual

Abstract

This document describes the features and integration of the LUCY-H200 3.5G tri-band HSDPA data and voice module. The LUCY-H200 is a 3.5G solution offering high-speed tri-band HSDPA and quad-band GSM/GPRS data and voice transmission technology in a compact form factor.



45.10 x 37.50 x 4.32 mm

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Objective Specification	This document contains target values. Revised and supplementary data will be published later.			
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This document applies to the following products:

Name	Type number	Firmware version	PCN reference
LUCY-H200	LUCY-H200-00S-00	n.a.	n.a.

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Preface

u-blox Technical Documentation

As part of our commitment to customer support, u-blox maintains an extensive volume of technical documentation for our products. In addition to our product-specific technical data sheets, the following manuals are available to assist u-blox customers in product design and development.

AT Commands Manual: This document provides the description of the supported AT commands by the LUCY-H200 module to verify all implemented functionalities.

System Integration Manual: This Manual provides hardware design instructions and information on how to set up production and final product tests.

Application Note: document provides general design instructions and information that applies to all u-blox Wireless modules. See Section Related documents for a list of Application Notes related to your Wireless Module.

How to use this Manual

The LUCY-H200 System Integration Manual provides the necessary information to successfully design in and configure these u-blox wireless modules.

This manual has a modular structure. It is not necessary to read it from the beginning to the end.

The following symbols are used to highlight important information within the manual:



An index finger points out key information pertaining to module integration and performance.



A warning symbol indicates actions that could negatively impact or damage the module.

Questions

If you have any questions about u-blox Wireless Integration, please:

- Read this manual carefully.
- Contact our information service on the homepage http://www.u-blox.com
- Read the questions and answers on our FAQ database on the homepage http://www.u-blox.com

Technical Support

Worldwide Web

Our website (www.u-blox.com) is a rich pool of information. Product information, technical documents and helpful FAQ can be accessed 24h a day.

By E-mail

Contact the nearest of the Technical Support offices by email. Use our service pool email addresses rather than any personal email address of our staff. This makes sure that your request is processed as soon as possible. You will find the contact details at the end of the document.

Helpful Information when Contacting Technical Support

When contacting Technical Support please have the following information ready:

- Module type (e.g. LUCY-H200) and firmware version
- Module configuration
- Clear description of your question or the problem
- A short description of the application
- Your complete contact details



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1 System description

1.1 Overview

The LUCY-H200 module from u-blox integrates a full-feature Release 5 UMTS/HSDPA GSM/GPRS/EDGE protocol stack.

UMTS/HSDPA characteristics:

- UMTS Terrestrial Radio Access (UTRA) Frequency Division Duplex (FDD) operating mode
- Tri-bands: UMTS Band I (2100 MHz), Band II (1900 MHz), Band V (850 MHz)
- Power class 3 (24 dBm) for WCDMA/HSDPA mode
- HSDPA category 8, up to 7.2 Mb/s download, 384 kb/s upload
- WCDMA PS data up to 384 kb/s UL/DL
- WCDMA CS data up to 64 kb/s UL/DL

GSM/GPRS/EDGE characteristics:

- Quad-band support: GSM 850 MHz, EGSM 900 MHz, DCS 1800 MHz and PCS 1900 MHz
- Power class 4 (33 dBm) for GSM/EGSM bands
- Power class 1 (30 dBm) for DCS/PCS bands
- EDGE Power Class ES2 (27 dBm) for GSM/EGSM bands
- EDGE Power Class ES2 (26 dBm) for DCS/PCS bands
- EDGE multislot class 12, coding scheme MCS1-MCS9, up to 236.8 kb/s
- GPRS multislot class 12, coding scheme CS1-CS4, up to 85.6 kb/s
- CSD Non-transparent / Transparent mode, up to 9.6 kb/s
- DTM class 11
- Mobile Station class A for UMTS mode and Class B for E-GPRS/GPRS mode
- Network Operation Mode I.II.III
- Modem type V.32, V.110
- Fax Group 3, Class 2.0
- TCP/IP stack
- IPv4 support

The 3G modem is a Class A User Equipment: the device can work simultaneously on the GSM and GPRS/UMTS networks. Basically this means that voice calls are possible while the data connection is active without any interruption in service.

The GPRS modem is a Class B Mobile Station; this means the data module can be attached to both GPRS and GSM services, using one service at a time. For instance, if during data transmission an incoming call occurs, the data connection is suspended to permit the voice communication. Once the voice call has terminated, the data service is resumed. Network operation modes I to III are supported, with user-definable preferred service selectable from GSM to GPRS. Optionally paging messages for GSM calls can be monitored during GPRS data transfer in not-coordinating network operation mode NOM II-III.

PBCCH/PCCCH logical channels are supported, as well as CBCH reception. CBCH reception when on PBCCH is supported.

The LUCY-H200 module implements a GPRS/EGPRS class 12 for data transfer. GPRS class determines the number of timeslots available for upload and download and thus the speed at which data can be transmitted and



received, with higher classes typically allowing faster data transfer rates. GPRS multislot 12 implies a maximum of 4 slots in download (reception) and 4 slots in upload (transmission) with 5 slots in total.

The network automatically configures the number of timeslots used for reception or transmission (voice calls take precedence over GPRS traffic). The network also automatically configures channel encoding (CS1 to MCS9). The maximum (E)GPRS bit rate of the mobile station depends on the coding scheme and number of time slots.

1.2 Architecture

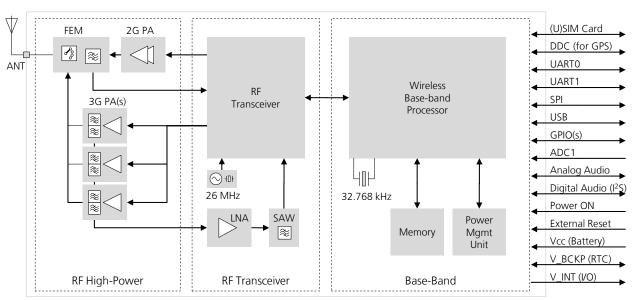


Figure 1: LUCY-H200 block diagram

1.2.1 Functional blocks

The user interfaces on the LUCY-H200 module are the RF antenna and the board-to-board connector.

The antenna is the interface for RF signals toward the wide-area network air interface. The user has freedom in choosing the antenna. The following dedicated section provides more details.

The board-to-board connector is the main interface for the user application, where all the supplies and input/output signals are connected. Detailed description of the board-to-board connector characteristics is one of the main purposes of this document, please see following sections

Between the RF air-interface and the board-to-board connector the LUCY-H200 functions by means of efficient and specialized hardware which can be grouped into the following functional blocks: RF high power front-end, RF transceiver, Baseband section and Power Management unit.

RF high-power front-end

A separated shielding chamber includes the RF high-power signal circuitry, namely:

- Quad-band 2G EDGE/GSM Power Amplifier (PA) module
- Three HSDPA/UMTS Power Amplifier module with integrated duplexers
- Front-End Module (FEM) with antenna switch multiplexer and integrated SAW filters for 2G receiver

The RF antenna is directly connected to the FEM, which dispatches the RF signals according to the active mode. For time-duplex 2G operation, the incoming signal at the active RX slot is applied to integrated SAW filters for out-of-band rejection and then sent to the appropriate receiver port of the RF transceiver. During the allocated TX slots, the low level signal coming from the RF transceiver is enhanced by the 2G power amplifier module and



then directed to the antenna through the FEM. The 3G transmitter and receiver are instead active at the same time due to frequency-domain duplex operation. The switch integrated in the FEM connects the antenna port to the passive duplexer which separates the TX and RX signals path. The duplexer itself provides front-end RF filtering for RX band selection while combining the amplified TX signal coming from the fixed gain linear power amplifier.

RF Transceiver

A second shielding box includes all the low-level analog RF components, namely:

- Tri-band HSDPA/WCDMA and quad-band EDGE/GSM transceiver
- Voltage Controlled Temperature Compensated 26 MHz Crystal Oscillator (VC-TCXO)
- Low Noise Amplifier (LNA) and SAW RF filters for 3G receivers

While operating in 3G mode, the RF transceiver performs direct up-conversion and down-conversion of the baseband I/Q signals, with the RF voltage controlled gain amplifier being used to set the uplink TX power. In the downlink path, the external LNA enhances the RX sensitivity while discrete inter-stage SAW filters additionally improve the rejection of out-of-band blockers. An internal programmable gain amplifier is used to cope with automatic gain control algorithm before to deliver the analog I/Q signal to baseband for further digital processing.

For 2G operations, a constant gain direct conversion receiver with integrated LNAs and highly linear RF quadrature demodulator are used to provide the same I/Q signals to baseband as well. In transmit mode, the upconversion is implemented by means of a digital sigma-delta transmitter or polar modulator depending on the modulation to be transmitted.

In all the modes, a fractional-N sigma-delta RF synthesizer and an on-chip 3.8–4 GHz voltage controlled oscillator are used to generate the local oscillator signal.

The frequency reference to RF oscillators is provided by the 26 MHz VC-TCXO. The same signal is buffered to the baseband as a master reference for clock generation circuits while operating in active mode.

Baseband section and power management unit

The largest shielding box includes all the digital circuitry and the power supplies, basically the following functional blocks:

- Wireless baseband processor, a mixed signal ASIC which integrates:
 - ARM Microprocessor for controller functions, 2G & 3G upper layer software
 - DSP core for 2G Layer 1 and audio processing
 - 3G coprocessor and HW accelerator for 3G Layer 1 control software and routines
 - Dedicated HW for peripherals control, as UART, USB, SPI etc
- Memory system in a Multi-Chip Package (MCP) integrating two devices:
 - NOR flash non-volatile memory
 - DDR SRAM volatile memory
- Power Management Unit (PMU), used to derive from Main Battery supply VCC all the supply voltages for the system
- 32.768 kHz crystal, connected to the oscillator of the Real Time Clock (RTC) to perform the clock reference in idle or power-off mode



1.3 Pin-out

Table 1 describes the pin-out of the board-to board connector for the LUCY-H200 module, with pins grouped by function.

Function	Pin	No	I/O	Description	Remarks
Power	VCC	57, 58, 59, 60	I	Module Supply	Clean and stable supply is required: low ripple and low voltage drop must be guaranteed. Voltage provided must always be above the minimum limit of the operating range. Consider that there are large current spikes in connected mode, when a GSM call is enabled. See section 1.5.2 VCC pins are internally connected.
	GND	1, 2, 3, 4, 19, 22, 25, 42	N/A	Ground	GND pins are internally connected but a good (low impedance) external ground can improve RF performances.
	V_BCKP	55	I/O	Real Time Clock supply	V_BCKP = 2.0 V (typical) generated by the module to supply Real Time Clock when VCC supply voltage is within valid operating range. See section 1.5.4
	V_INT	56	0	Interface supply	V_INT = 1.8V (typical) generated by the module and used as supply rail for all I/O. See section 1.5.5
	VSIM	5	0	SIM supply	SIM supply automatically generated by the module. See section 1.9
SIM	SIM_IO	6	I/O	SIM data	SIM interface: see section 1.9. Internal 4.7 k Ω pullup to VSIM. Must meet SIM specifications
	SIM_CLK	7	0	SIM clock	SIM interface: see section 1.9. Must meet SIM specifications
	SIM_RST	8	0	SIM reset	SIM interface: see section 1.9. Must meet SIM specifications
SPI	SPI_MISO	9	I/O	SPI Master Input, Slave Output	The pin by default is set to output. SPI default is Slave mode. Internal active pull-up to 1.8 V is enabled when the pin is used as input.
	SPI_MOSI	10	I/O	SPI Master Output, Slave Input	The pin by default is set to input. SPI default is Slave mode. Internal active pull-up to 1.8 V is enabled when the pin is used as input.
	SPI_SCLK0	11	I/O	SPI Serial Clock, output from Master	Input if Slave and Output if Master. SPI default is Slave mode
	SPI_SRDY	32	0	SPI Slave Ready	
	SPI_MRDY	38	I	SPI Master Ready	Internal active pull-up to 1.8 V is enabled.
DDC	SCL	12	0	I ² C bus clock line	Fixed open drain. External pull-up required. See section 1.10
	SDA	13	I/O	I ² C bus data line	Fixed open drain. External pull-up required. See section 1.10
UART0	DSR_0	45	0	UARTO data set ready	See section 1.10. Control convention of the pins
	RI_0	46	0	UARTO ring indicator	See section 1.10. Control convention of the pins
	RxD_0	47	0	UARTO received data	See section 1.10. Control convention of the pins
	TxD_0	48	I	UARTO transmitted data	Internal active pull-up to 1.8 V enabled. See section 1.10. Control convention of the pins
	CTS_0	49	0	UARTO clear to send	See section 1.10. Control convention of the pins
	RTS_0	50	I	UARTO ready to send	Internal active pull-up to 1.8 V enabled.
	DTR_0	51	I	UARTO data terminal ready	See section 1.10. Control convention of the pins Internal active pull-up to 1.8 V enabled. See section 1.10. Control convention of the pins
	DCD 0	52	0	UARTO data carrier	
	DCD_0	عد	0	OANTO UAIA CAITIEI	See section 1.10. Control convention of the pins



Function	Pin	No	I/O	Description	Remarks
				detect	
UART1	RxD_1	43	0	UART1 received data	See section 1.10. Control convention of the pins
	TxD_1	44	I	UART1 transmitted data	Internal active pull-up to 1.8 V enabled. See section 1.10. Control convention of the pins
	CTS_1	40	0	UART1 clear to send	See section 1.10. Control convention of the pins
	RTS_1	33	I	UART1 ready to send	Internal active pull-up to 1.8 V enabled. See section 1.10. Control convention of the pins
ADC	ADC1	27	I	ADC input	Resolution: 12 bits. See section 1.10; consider that the impedance of this input changes depending on the operative mode
GPIO	GPIO1	54	I/O	GPIO	See section 1.16.
	GPIO2	53	I/O	GPIO	See section 1.16.
	GPIO3	41	I/O	GPIO	See section 1.16.
	GPIO4	39	I/O	GPIO	See section 1.16.
	GPIO5	31	I/O	GPIO	See section 1.16.
USB	VUSB_DET	28	I	USB detect input	
	USB_D+	29	I/O	USB Data Line D+	Internal pull up available so external pull-up not needed.
	USB_D-	30	I/O	USB Data Line D-	
System	PWR_ON	26	I	Power-on input	Pin has internal pull-up. See section 1.6.1
	RESET_N	18	I	External reset input	Pin has internal pull-up. See section 1.6.3
Audio	I2S_CLK	14	0	l²S clock	I ² S Interface: see section 1.17.2. Check device specifications to ensure compatibilit of supported modes to LUCY-H200 module.
	I2S_RXD	15	I	l ² S receive data	I ² S Interface: see section 1.17.2. Internal active pull-up to 1.8V enabled. Check device specifications to ensure compatibilit
				2-	of supported modes to LUCY-H200 module.
	I2S_TXD	16	0	I ² S transmit data	I ² S Interface: see section 1.17.2. Check device specifications to ensure compatibilit of supported modes to LUCY-H200 module.
	I2S_WA	17	0	I ² S word alignment	I ² S Interface: see section 1.17.2. Check device specifications to ensure compatibilit of supported modes to LUCY-H200 module.
	MIC_GND	20	I	Microphone analog reference	Local ground of microphone. Audio pin: see section 1.17.1
	MIC_BIAS	21	I	Microphone analog signal input and bias output	This audio input is used for audio uplink path. Audio pin: see section 1.17.1
	SPK_P	23	0	Speaker output with high power differential analog audio	This audio output is used when audio downlink path is "Loudspeaker". Audio pin: see section 1.17.1
	SPK_N	24	0	Speaker output with power differential analog audio output	This audio output is used when audio downlink path is "Loudspeaker". Audio pin: see section 1.17.1
Reserved	Reserved	34			Do not connect
	Reserved	35			Do not connect
	Reserved	36			Do not connect
	Reserved	37			Do not connect

Table 1: LUCY-H200 pin-out



1.4 Operating modes

The LUCY-H200 module includes several operating modes, each have different active features and interfaces. Table 2 summarizes the various operating modes and provides general guidelines for operation.

General Status	Operating Mode	Description	Features / Remarks
Power-down	Not-Powered Mode	VCC supply not present or below normal operating range. Microprocessor not operating. RTC only operates if supplied through V_BCKP pin.	Module is switched off. Module cannot be switched on by a falling edge provided on the PWR_ON input, neither by a preset RTC alarm, or a rising edge to a valid range of USB voltage provided on the VUSB_DET input. Application interfaces not accessible. Internal RTC timer operates only if a valid voltage is applied to V_BCKP pin.
	Power-Off Mode	VCC supply within normal operating range. Microprocessor not operating. Only RTC runs.	Module is switched off: normal shutdown after sending the AT+CPWROFF command (refer to u-blox 3.5G HSDPA AT Commands Manual [2]). Module can be switched on by a falling edge provided on the PWR_ON input, by a preset RTC alarm, or a rising edge to a valid voltage for USB VBUS detection provided on the VUSB_DET inputs. Application interfaces are not accessible. Only the internal RTC timer in operation.
Normal operation	Idle-Mode	Microprocessor runs with 32 kHz as reference oscillator. Module does not accept data signals from an external device.	Module is switched on and is in idle mode (i.e. power saving / sleep mode). Application interfaces disabled. Module by default does not enter automatically in idle mode; this happens only if this mode is enabled by appropriate AT command (refer to u-blox 3.5G HSDPA AT Commands Manual [2]). If module is registered with the network, and idle mode is enabled, it automatically enters idle mode and periodically wakes up to active mode to monitor the paging channel for the paging block reception according to network indication. If module is not registered with the network, and idle mode is enabled, it automatically goes in idle mode and periodically wakes up to monitor external activity. Module wakes up from idle mode to active mode if an RTC alarm occurs. Module wakes up from idle mode to active mode when data received on UART interface with HW flow control enabled. Module wakes up from idle mode to active mode if a voice or data call incoming. Module wakes up from idle mode to active mode when the RTS input line is set to the ON state by the DTE if the AT+UPSV=2 command is sent to the module (feature not enabled by default). The hardware flow control output (CTS line) indicates when the module is in idle (power saving mode): the line is driven in the OFF state when the module is not prepared to accept data signals. Module wakes up from idle mode to active mode if a valid VBUS voltage is detected on VUSB_DET pin: the UARTO interface is then disabled and USB becomes active. When USB is active, the external interface connected to UARTO RTS_0 and CTS_0 should be tri-stated , see section 1.13
	Active-Mode	Microprocessor runs with 26 MHz as reference oscillator. The module is prepared to accept data signals from an external device.	Module is switched on and is fully active: power saving is not enabled. The application interfaces are enabled.



General Status	Operating Mode	Description	Features / Remarks
	Connected-Mode	Voice or data call enabled. Microprocessor runs with 26 MHz as reference oscillator. Module is prepared to accept data signals from an external device.	The module is switched on and a voice call or a data call (GSM/GPRS/UMTS) is in progress. Module is fully active. Application interfaces are enabled. When call terminates, module returns to the last operating state (Idle or Active).

Table 2: Module operating modes summary

Transition between the different modes is described in Figure 2.

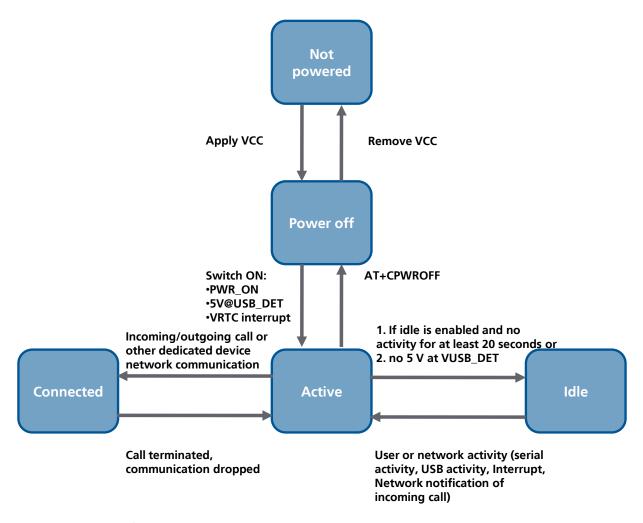


Figure 2: Operating modes transition



1.5 Power management

1.5.1 Power supply circuit overview

The LUCY-H200 module features a power management concept optimized for the most efficient use of supplied power. This is achieved by hardware design utilizing power efficient circuit topology (Figure 3), and by power management software controlling the power saving mode of the module.

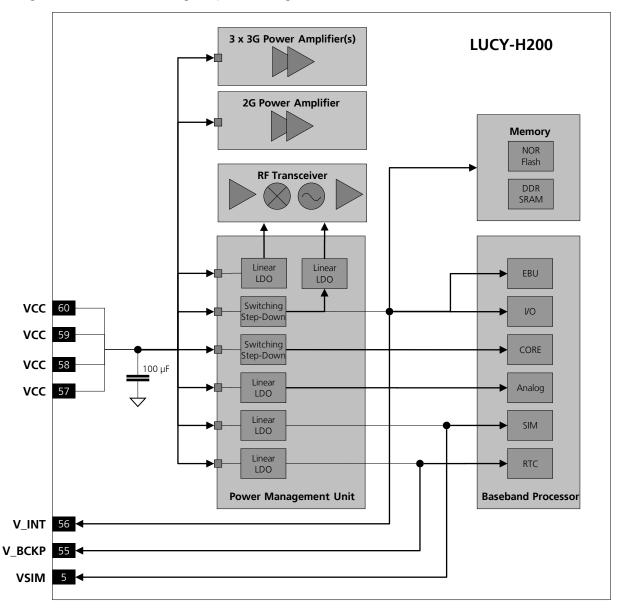


Figure 3: Power management simplified block diagram

Pins of the board-to board connector used by power supply function are reported on Table 3.



Name	Description	Remarks
VCC	Module main power supply	VCC pins are internally connected, use all the available circuits of the board-to-board connector in order to minimize the power loss due to series resistance and not exceed the current rating per pin. Clean and stable supply is required: low ripple and low voltage drop must be guaranteed. Voltage provided must be always above the minimum limit of the operating range. Consider that there are large current spike in connected mode, when a GSM call is enabled.
GND	Ground	GND pins are internally connected but a good (low impedance) external ground can improve RF performance and ensure that current rating per pin is not exceeded.
V_BCKP	Real Time Clock supply	V_BCKP = 2.0 V (typical) generated by the module to supply Real Time Clock when VCC supply voltage is within valid operating range.
V_INT	Digital Interfaces supply	V_INT = 1.8V (typical) generated by the module and internally connected to Input / Output digital pins. The user may draw limited current from this supply rail.

Table 3: Power supply pins

The LUCY-H200 module is supplied via the **VCC** pin. There is only one main power supply, available on four pins on the board-to-board connector.

The **VCC** pin is directly connected to the RF power amplifiers and to the integrated power management unit within the module: all supply voltages needed by the module are generated from the **VCC** supply by integrated voltage regulators.

When the **VCC** voltage is within the valid operating range, the module supplies the Real Time Clock. If the **VCC** voltage is under the minimum operating limit, the Real Time Clock can be externally supplied via the **V_BCKP** pin.

When a 1.8 V or a 3 V SIM card type is connected, LUCY-H200 automatically supplies the SIM card via the **VSIM** pin. Activation and deactivation of the SIM interface with automatic voltage switch from 1.8 to 3 V is implemented, in accordance to the ISO-IEC 7816-3 specifications.

The same voltage domain used internally to supply the digital interfaces is also available on pin **V_INT** on the board-to-board connector, in order to allow more economical and efficient integration of the LUCY-H200 module in the final application.

The integrated power management unit also provides the control state machine for system start up and system reset control.

1.5.2 Module supply (VCC)

The LUCY-H200 module must be supplied through the **VCC** pin by a DC power supply. Voltages must be stable: during operation, the current drawn from **VCC** can vary by some order of magnitude, especially due to surging consumption profile of the GSM system (described in the section 1.5.3). It is important that the system power supply circuit is able to support peak power (see datasheet for specification).

The DC power supply can be selected from:

- 1. A switching regulator; see the notes below about the switching regulator requirements.
- 2. A rechargeable Li-Ion battery; see the notes below about the Li-Ion battery requirements.
- 3. A primary (not rechargeable) battery; see the notes below about the primary battery requirements.

The characteristics of the switching regulator connected to the **VCC** pin should be meet the following requirements:



- power capabilities: the switching regulator with its output circuit must be capable of providing a valid voltage value to the VCC pin and must be capable of delivering 2.5 A current pulses with 1/8 duty cycle to the VCC pin
- low output ripple: the switching regulator with its output circuit must be capable of providing a clean (low noise) VCC voltage profile
- fixed switching frequency greater or equal to 1 MHz: variable or lower switching frequency will produce noise in the VCC voltage profile so that the module will not reach the GSM modulation spectrum requirements
- fixed PWM mode operation: PFM mode and PFM/PWM modes transitions must be avoided to reduce the noise on the VCC voltage profile

The characteristics of the rechargeable Li-lon battery connected to the **VCC** pin should meet the following requirements:

- maximum DC/pulse discharge current: the rechargeable Li-lon battery with its output circuit must be capable of delivering 2.5 A current pulses with 1/8 duty cycle to the **VCC** pin
- DC series resistance: the rechargeable Li-lon battery with its output circuit must be capable of avoiding a VCC voltage drop greater than 400 mV

The characteristics of the primary (not rechargeable) battery connected to the **VCC** pin are compliant with the following requirements:

- maximum DC/pulse discharge current: the not-rechargeable battery with its output circuit must be capable of delivering 2.5 A current pulses with 1/8 duty cycle to the **VCC** pin
- DC series resistance: the rechargeable Li-lon battery with its output circuit must be capable of avoiding a VCC voltage drop greater than 400 mV

The voltage provided to the **VCC** pin must be within the normal operating range limits specified in the LUCY-H200 Data Sheet [1]. Complete functionality of the module is only guaranteed within the specified minimum and maximum **VCC** voltage range.



Ensure that the input voltage at **VCC** is above the normal operating range minimum limit to enable the switch-on of the module. Note that the module cannot be switched on if the **VCC** voltage value is below the minimum specified limit. See the LUCY-H200 Data Sheet [1].

When the LUCY-H200 module is in operation, the voltage provided to the **VCC** pin can exceed the normal operating range limits but must be within the extended operating range limits specified in the LUCY-H200 Data Sheet [1]. Module reliability is only guaranteed within this specified operational extended voltage range.



Ensure that the input voltage at the **VCC** pin never drops below the extended operating range minimum limit when the module is switched on, not even during a GSM transmit burst, where the current consumption can rise up to peaks of 2.5 A in case of a mismatched antenna load. The module switches off when the **VCC** voltage value drops below the minimum limit.



Operation above the extended operating range maximum limit is not recommended and extended exposure beyond it may affect device reliability.



Stress beyond the **VCC** absolute maximum ratings may cause permanent damage to the module: if necessary, voltage spikes beyond **VCC** absolute maximum ratings must be limited to values within the specified boundaries by using appropriate protection.



When designing the power supply for the application, pay specific attention to power losses and transients:

- do not exceed 200 mV voltage drops during transmit bursts
- avoid undershoot and overshoot on voltage drops at the start and at the end of a transmission
- minimize voltage ripple on the supply

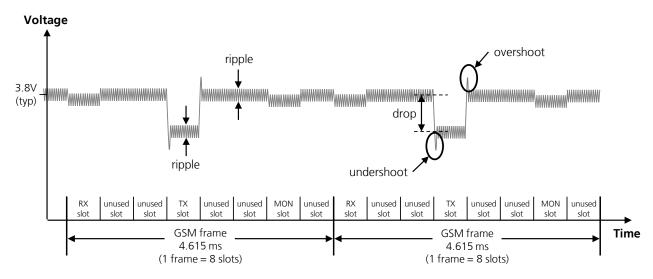


Figure 4: Description of the VCC voltage profile versus time during a GSM call

To reduce voltage drops, use a low impedance power source. The resistance of the power supply lines (connected to VCC and GND pins of the module) on the application board and battery pack should also be considered and minimized: cabling and routing must be as short as possible in order to minimize power losses.

Four pins on the board-to-board connector are allocated for **VCC** supply. Another four pins are designated for **GND** connection on the corresponding contacts of the alternate row. Even if these pins are internally connected within the module, it is recommended to connect all of them to supply the module in order to minimize the resistance losses and not exceed the current rating of the contacts.



Provide external low resistance connection between all four contacts of **VCC** and connect all four **GND** pins together on the adjacent row of the board-to-board connector.

To avoid undershoot and overshoot on voltage drops at the start and end of a transmit burst during a GSM call (when current consumption on the VCC supply can rise up to 2.5 A in the worst case), place a 330 μ F low ESR capacitor (e.g. KEMET T520D337M006ATE045) located near the **VCC** pin.

To reduce voltage ripple and noise, place near the **VCC** pin the following:

- 100 nF capacitor (e.g Murata GRM155R61A104K) and a 10 nF capacitor (e.g. Murata GRM155R71C103K) to filter digital logic noises from clocks and data sources
- 10 pF capacitor (e.g. Murata GRM1555C1E100J) to filter transmission EMI in the DCS/PCS and 3G B1 bands
- 39 pF capacitor (e.g. Murata GRM1555C1E390J) to filter transmission EMI in the GSM/EGSM bands



Any degradation in the power supply performance, due to losses, noise or transients, will directly affect the RF performance of the module since the single external DC power source indirectly supplies all the digital and analog interfaces, and also directly supplies the RF power amplifier (PA).

If the module is supplied by a battery, do not connect any other power supply at the **VCC** supply pin in parallel to the battery.



If the module is not supplied by a battery, Figure 5 and the components listed in Table 4 show an example of a power supply circuit. This example is implemented on the Evaluation Board EVK-H26H. **VCC** supply is provided by a step-down switching regulator with a 1 MHz switching frequency.

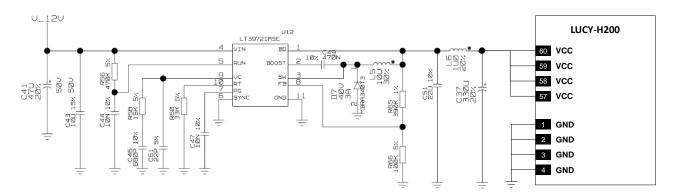


Figure 5: Suggested schematic design for the VCC voltage supply application circuit using a step-down regulator

Reference	Description	Part Number - Manufacturer
C37	330 µF Capacitor Tantalum D_SIZE 6.3 V 45 m Ω	T520D337M006ATE045 - KEMET
C41	47 μF Capacitor Aluminum 0810 50 V	MAL215371479E3 - Vishay
C43	10 μF Capacitor Ceramic X7R 5750 15% 50 V	C5750X7R1H106MB - TDK
C44	10 nF Capacitor Ceramic X7R 0402 10% 16 V	GRM155R71C103KA01 - Murata
C46	680 pF Capacitor Ceramic X7R 0402 10% 16 V	GRM155R71H681KA01 - Murata
C47	10 nF Capacitor Ceramic X7R 0402 10% 16 V	GRM155R71C103KA01 - Murata
C49	470 nF Capacitor Ceramic X7R 0603 10% 25 V	GRM188R71E474KA12 - Murata
C51	22 μF Capacitor Ceramic X5R 1210 10% 25 V	GRM32ER61E226KE15 - Murata
C61	22 pF Capacitor Ceramic COG 0402 5% 25 V	GRM1555C1H220JZ01 - Murata
D7	Schottky Diode 40V 3 A	MBRA340T3G - ON Semiconductor
L5	10 μH Inductor 744066100 30% 3.6 A	744066100 - Wurth Electronics
L6	1 μH Inductor 7445601 20% 8.6 A	7445601 - Wurth Electronics
R56	470 kΩ Resistor 0402 5% 0.1 W	2322-705-87474-L - Yageo
R58	15 kΩ Resistor 0402 5% 0.1 W	2322-705-87153-L - Yageo
R60	33 kΩ Resistor 0402 5% 0.1 W	2322-705-87333-L - Yageo
R65	390 kΩ Resistor 0402 1% 0.063 W	RC0402FR-07390KL - Yageo
R66	100 kΩ Resistor 0402 5% 0.1 W	2322-705-70104-L - Yageo
U12	Step Down Regulator MSOP10 3.5 A 2.4 MHz	LT3972IMSE#PBF - Linear Technology

Table 4: Suggested components for the VCC voltage supply application circuit using a step-down regulator

If another step-down switching regulator is used, the switching frequency must be set to 1 MHz or higher to avoid a degradation of the RF modulation spectrum performance.

An LDO linear voltage regulator can be used to supply the module. Ensure correct power dissipation on the regulator in order to avoid reaching LDO thermal limits during the high current peak generated by the module during a GSM transmit burst or UMTS continuous transmission at maximum power.

1.5.3 Current consumption profiles

During operation, the current drawn by the LUCY-H200 through the **VCC** pin can vary by some orders of magnitude. This ranges from the high peak of current consumption during the GSM transmitting bursts at maximum power level in 2G connected mode, to continuous high current drawn in UMTS connected mode, to the low current consumption during power saving in idle mode.



1.5.3.1 2G Connected-mode

When a GSM call is established, the VCC consumption is determined by the current consumption profile typical of the GSM transmitting and receiving bursts.

The current consumption peak during a transmission slot is strictly dependent on the transmitted power, which is regulated by the network. If the module is transmitting in GSM talk mode in the GSM 850 or in the EGSM 900 band and at the maximum RF power control level 5 (that is approximately 2 W or 33 dBm), the battery discharge current is modulated at up to 2500 mA (worst case value obtained with worst possible matching) with pulses of 576.9 µs (width of 1 slot/burst) that occur every 4.615 ms (width of 1 frame = 8 slots) according to GSM TDMA.

During a GSM call, current consumption is in the order of 100-200 mA in receiving or in monitor bursts and is about 30-50 mA in the inactive unused bursts (low current period). The more relevant contribution to determine the average current consumption is set by the transmitted power in the transmit slot.

An example of current consumption profile of the data module in GSM talk mode is shown in Figure 6.

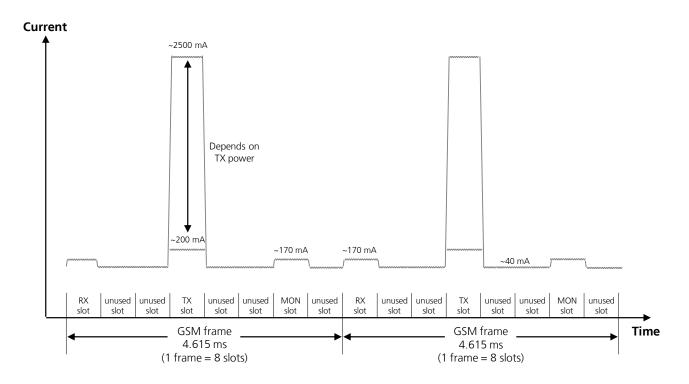


Figure 6: VCC current consumption profile versus time during a GSM call, VCC=3.8V

When a GPRS connection is established there is a different VCC current consumption profile also determined by the transmitting and receiving bursts. In contrast to a GSM call, during a GPRS connection more than one slot can be used to transmit and/or more than one slot can be used to receive. The transmitted power depends on network conditions, which set the peak current consumption, but following the GPRS specifications the maximum transmitted RF power is reduced if more than one slot is used to transmit, so the maximum peak of current consumption is not as high as can be in case of a GSM call. In fact it can reach up to 1400 mA at maximum power level and highly unmatched antenna.

An example of current consumption profile of the data module in GPRS mode is shown in Figure 7.



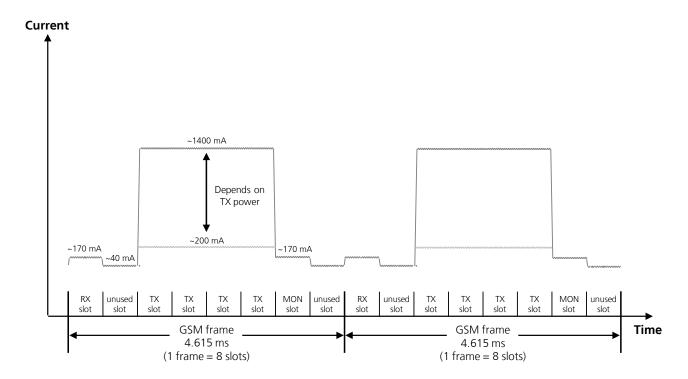


Figure 7: VCC current consumption profile versus time during a GPRS/EDGE connection, 4TX slots, 1 RX slot, VCC=3.8V

In case of EDGE connections the VCC current consumption profile is very similar to the GPRS current profile, so the image shown in Figure 7 is valid for EDGE too.

1.5.3.2 3G Connected-mode

During a 3G connection, the module may transmit and receive continuously due to the Frequency Division Duplex (FDD) mode of operation. The current consumption depends again on output RF power, which is always regulated by network commands. These power control commands are logically divided into a slot of 666 µs, thus the rate of power change can reach a maximum rate of 1.5 kHz. There are no high current peaks, but in the worst scenario corresponding to a continuous transmission and reception at maximum output power (approximately 250 mW or 24 dBm), the drawn current of the whole system is in the order of continuous 600-700 mA. Even at lowest output RF power (approximately 0.01 µW or -50 dBm), the current still remains in the order of 200 mA due to modem baseband processing and transceiver activity.

An example of current consumption profile of the data module in UMTS continuous transmission mode is shown in Figure 8.



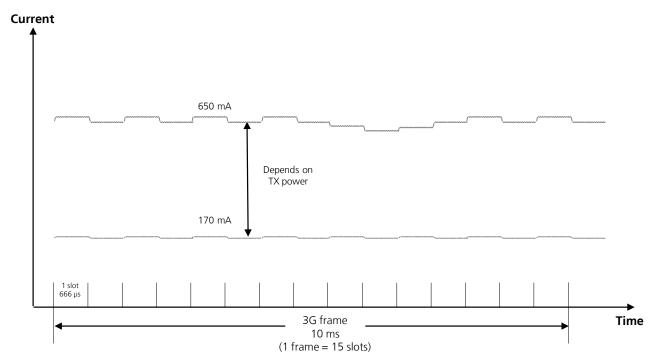


Figure 8: VCC current consumption profile versus time during a UMTS connection, VCC=3.8V

When a packet data connection is established, the actual current profile depends on the amount of transmitted packets; there might be some periods of inactivity between allocated slots where current consumption drops about 100 mA. Alternatively, at higher data rates the transmitted power is likely to increase due to the higher quality signal required by the network to cope with enhanced data speed.

1.5.3.3 Idle-mode

By default the module does not automatically enter idle-mode (power-saving mode) whenever possible; idle mode must be enabled using the appropriate AT command (refer to u-blox 3.5G HSDPA AT Commands Manual [2]).

When the data module is registered or attached to a network and a voice or data call is not enabled, the module must periodically monitor the paging channel of the current base station (paging block reception), in accordance to GSM and UMTS system requirements. When the module monitors the paging channel, it wakes up to active mode, to enable the paging block reception. In between, the module switches to idle-mode (power-saving mode). This is known as discontinuous reception (DRX).

The module processor core is activated during the paging block reception, and automatically switches its reference clock frequency from the 32 kHz to the 26 MHz used in active-mode.

The time period between two paging block receptions is defined by the network. For example, the time interval between two paging block receptions for 2G operation can be from 470.76 ms (width of 2 GSM multiframes = $2 \times 51 \text{ GSM}$ frames = $2 \times 51 \times 4.615 \text{ ms}$) up to 2118.42 ms (width of 9 GSM multiframes = $9 \times 51 \times 4.615 \text{ ms}$): this is the paging period parameter, fixed by the base station through broadcast channel sent to all users on the same serving cell.

An example of a data module current consumption profile is shown in Figure 9: the module is registered with a 2G network, automatically goes into idle mode and periodically wakes up to active mode to monitor the paging channel for paging block reception



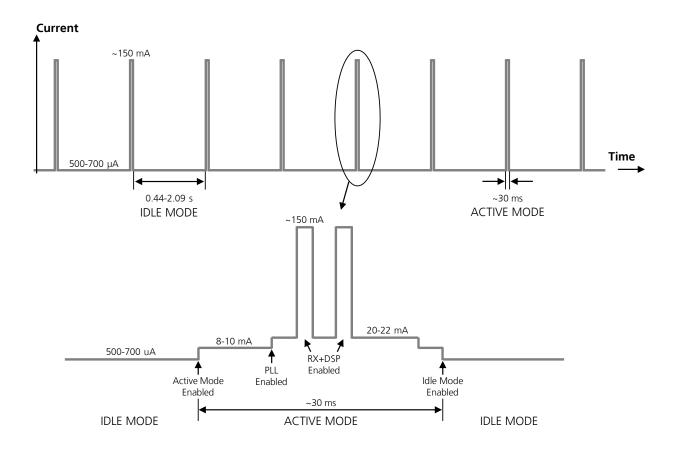


Figure 9: Description of the VCC current consumption profile versus time when the module is registered on the GSM network: the module is in idle mode and periodically wakes up to active mode to monitor the paging channel for paging block reception

1.5.4 RTC Supply (V_BCKP)

The **V_BCKP** pin connects the supply for Real Time Clock (RTC) and Power On / Reset internal logic. This supply domain is internally generated by a linear regulator integrated in the power management unit. The output of this linear regulator is always enabled when the main voltage supply provided to the module through **VCC** is within the valid operating range, being the module switched-off or powered-on.

The RTC provides the time reference (date and time) of the module, also in power-off mode, when the **V_BCKP** voltage is within its valid range (specified in u-blox LUCY-H200 Data Sheet [1]). The RTC timing is normally used to set the wake-up interval during idle-mode periods between network paging, but is able to provide programmable alarm functions by means of the internal 32.768 kHz clock.

The RTC can be supplied from an external back-up battery through the **V_BCKP**, when the main voltage supply is not provided to the module through **VCC**. This lets the time reference (date and time) run even when the main supply is not provided to the module. Please consider that the module cannot switch on if a valid voltage is not present on **VCC** even when RTC is supplied through **V_BCKP** (meaning that **VCC** is mandatory to switch-on the module).

The RTC has very low power consumption, but is highly temperature dependent. For example at 25°C and a **V_BCKP** voltage of 2.0 V the power consumption is approximately 2 μ A, whereas at 70°C and an equal voltage the power consumption increases to 5-10 μ A.



The internal regulator for **V_BCKP** is optimized for low leakage current and very light loads. It is recommended to not use **V_BCKP** to supply external loads.



If V_BCKP is left unconnected and the module main voltage supply is removed from VCC, the RTC is supplied from the 1 μ F buffer capacitor mounted inside the module. However, this capacitor is not able to provide a long buffering time: within 0.5 seconds the voltage on V_BCKP will go below the valid range (1 V min). At this time the internal RTC will stop counting and the date and time setting will be lost. This has no impact on wireless connectivity, as all the functionalities of the module do not rely on the date and time setting.



V_BCKP shall be left unconnected if the RTC is not required when the **VCC** supply is removed. The date and time will not be updated when **VCC** is disconnected. If **VCC** is always supplied, then the internal regulator will take input from the main supply and there is no need for an external component on **V_BCKP**.

If RTC is required to run for a time interval of T [seconds] at 25°C when **VCC** supply is removed, place a capacitor with a nominal capacitance of C [μ F] at the **V_BCKP** pin. Choose the capacitor using the following formula:

 $C [\mu F] = (Current_Consumption [\mu A] \times T [seconds]) / Voltage_Drop [V] = 2 \times T [seconds]$

The current consumption of the RTC is approximately 2 μ A at 25°C, and the voltage drop is equal to 1 V (from the **V_BCKP** typical value of 2.0 V to the valid range minimum limit of 1.0 V).

For example, a 100 μ F capacitor (such as the Murata GRM43SR60J107M) can be placed at **V_BCKP** to provide a long buffering time. This capacitor will hold **V_BCKP** voltage within its valid range for around 50 seconds at 25°C, after the **VCC** supply is removed. If a very long buffering time is required, a 70 mF super-capacitor (e.g. Seiko Instruments XH414H-IV01E) can be placed at **V_BCKP**, with a 4.7 k Ω series resistor to hold the **V_BCKP** voltage within its valid range for around 10 hours at 25°C, after the **VCC** supply is removed. These capacitors will allow the time reference to run during battery disconnection.

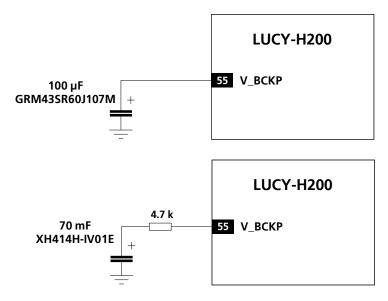


Figure 10: Real time clock supply (V_BCKP) application circuits using a 100 μF capacitor to let the RTC run for ~50 seconds at 25°C or using a 70 mF capacitor to let the RTC run for ~10 hours at 25°C when the VCC supply is removed

1.5.5 Interface supply (V_INT)

The same voltage domain used internally to supply the digital interfaces is also available at the board-to-board connector on pin **V_INT**. The internal regulator is a switching step down converter: it is directly supplied from **VCC** and output voltage is set to 1.8 V (typical). It operates in Pulse Width Modulation (PWM) for high output current mode but automatically switches to Pulse Frequency Modulation (PFM) at low output loads for greater efficiency, e.g. when the module is in idle mode between paging periods.



Being the supply of internal digital circuits (see Figure 3), **V_INT** is not suited to directly supply any sensitive analog circuit: the voltage ripple may range from 20 mV during active mode (PWM), to 70 mV in idle mode (PFM), in addition to few tens of mV of short overshoot / undershot due to dynamic response of transient loads.

- **V_INT** can be used to supply external digital circuits operating at the same voltage level as the digital interface pins, i.e. 1.8 V (typical). It is not recommended to supply analog circuitry without adequate filtering for digital noise.
- Don't apply loads which might exceed the limit for maximum available current from **V_INT** supply, as this can cause malfunctions to internal circuitry supplies to the same domain.
- **V_INT** can only be used as an output; don't connect any external regulator on **V_INT**. If not used this pin should be left unconnected.

Typical usage of V_{INT} is to connect a pull-up resistor for the DDC (I^2C) interface. See section 1.11 for more details.



1.6 System functions

1.6.1 Module power on

When supply is connected to the **VCC** pin, the voltage supervision circuit controls the subsequent activation of the power up state machines.

The module power-on sequence is initiated in one of 3 ways:

- Falling edge on the **PWR_ON** signal
- RTC alarm
- Detection on pin VUSB_DET of a valid VUSB voltage (typical 5V) for USB detection

Name	Description	Remarks
PWR_ON	Power-on input	PWR_ON pin has an internal pull-up resistor to V_BCKP. Nevertheless provide space for mounting an external pull up resistor on the application board in case of noisy environment, where an external pull-up is required

Table 5: Power-on pin

1.6.1.1 Falling edge on the PWR_ON

The module power-on sequence starts when a low level is forced on the **PWR_ON** signal.

The electrical characteristics of the **PWR_ON** input pin are different from the other digital I/O interfaces: the high and the low logic levels have different operating ranges and the pin is tolerant of voltages only up to the **V_BCKP** voltage. The nominal **V_BCKP** pin voltage is 2 V; the detailed electrical characteristics are described in the LUCY-H200 Data Sheet [1].



The **PWR_ON** pin is pulled up to **V_BCKP** through an internal 470 k Ω resistor. To avoid floating in a noisy environment: a pull up resistor to **V_BCKP** supply can be added on the application board at least as a not mounting option.



The boot time is around 1 second when the falling edge on the **PWR_ON** pin is used to power on the module.

Note that the module can be switched-on by a falling edge on the **PWR_ON** pin. Once the module has turned on moving the **PWR_ON** pin has no effect. On the other hand it makes no sense to keep this pin low when the module is turned on as it would source some unnecessary μA .

Following are some typical examples of turning the module on. The simplest way to turn on the module is to use a push button connected to ground.



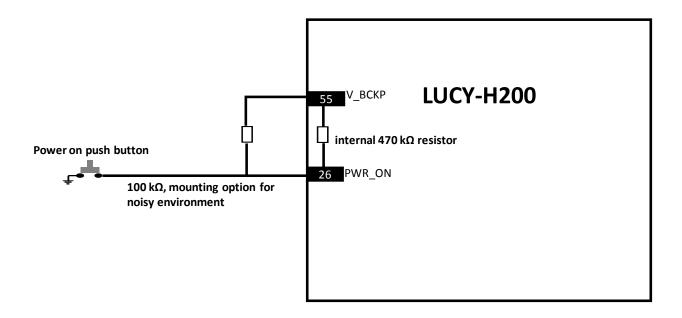


Figure 11: Power on LUCY module with push button

When power on is controlled by the GPIO of an application processor (AP) there could be different scenarios depending on voltage and pin configurations of the AP. The simplest case is when the GPIO output stage can be set to open drain. In that case a direct connection is possible.

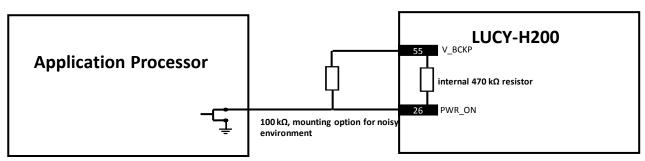


Figure 12: Power-on LUCY module by open drain GPIO



Even if open drain GPIO is available attention must be paid to the voltage ratings of the pins of the Application Processor. In fact when AP GPIOs are powered at very low voltages (e.g. 1-1.3 V) they could be damaged by the **PWR_ON** pin voltage. Please refer to the datasheet of the Application Processor for the voltage rating of its GPIOs.

If no open drain but only push pull output GPIO is available, direct connection is still possible if the GPIO is in the 1.5-2 V range.

If the push-pull output GPIO is outside the 1.5-2 V range an appropriate level translator circuit must be provided. There are several ways to provide proper level translation depending on the AP voltage:

- One is using an open drain, non inverting buffer powered at the AP voltage level; NC7WZ07 can be used for that purpose
- Another means of voltage adaption is using dual voltage chips that can provide level translation; the output side of the level translator chip (towards LUCY **PWR_ON**) must be powered in the 1.5-2 V range



Remember to fix the unused inputs of buffers or voltage translator chips with more ports than required to GND or to power in order to prevent increase in power consumption due to high impedance floating inputs.

1.6.1.2 Real Time Clock (RTC) alarm Power on

If a valid voltage is maintained at the **VCC** pin, the module can be switched-on by the RTC alarm when the RTC system reaches a pre-programmed scheduled time. The RTC system will then initiate the boot sequence by indicating to the power management unit to turn on power. Also included in this setup is an interrupt signal from the RTC block to indicate to the baseband processor, that an RTC event has occurred.



The boot time is around 1 second when the power on of the module is caused by RTC alarm.

1.6.1.3 Detection on pin VUSB_DET of a valid VUSB voltage

If a valid VUSB voltage is detected on the **VUSB_DET** pin, the module turns on. Please refer to the LUCY-H200 Data Sheet [1] for the VUSB range that must be applied to **VUSB_DET** pin. When the power on cause is a valid VUSB voltage, USB block is turned on and **UART0** is disabled. Once the module is powered, if voltage at **VUSB_DET** goes outside of the VUSB range, **UART0** is re-enabled. The line that triggers power on at **VUSB_DET** pin must have less than 100 Ω impedance.



When voltage at **VUSB_DET** pin is in the VUSB range the module does not enter idle state even if has been enabled by the appropriate AT command (for more details please refer to u-blox 3.5G HSDPA AT commands manual [2]).



The boot time is around 3 seconds when the power on is caused by a USB range voltage (4.3 V-5.3 V, typically 5 V) at **VUSB_DET** pin.

1.6.2 Module power off

The LUCY-H200 module can be switched off by one of the following switch-off events:

- Via AT command AT+CPWROFF (more details in u-blox 3.5G HSDPA AT Commands Manual [2])
- An under-voltage shutdown will be done if VCC falls below the valid operating limit

After a switch-off event has been triggered, the digital pins are locked in tri-state by the module. All internal voltage regulators, except the RTC supply, are turned off in a defined power-off sequence.

1.6.3 Module reset

Reset the module using **RESET_N**: this performs an external or hardware reset. When the **RESET_N** pin is driven low, an asynchronous reset of the entire module - except for the RTC - is triggered, and the device is initialized into a defined reset state.

Name	Description	Remarks
RESET_N	External reset input	Internal pull-up

Table 6: Reset pin

The electrical characteristics of **RESET_N** are different from the other digital I/O interfaces. The detailed electrical characteristics are described in the LUCY-H200 Data Sheet [1].

RESET_N is pulled high by an integrated pull-up resistor. Therefore an external pull-up should be not required on the application board. An internal circuit pulls the level to 2.0 V.

Forcing **RESET_N** low for at least 50 ms will cause an external reset of the module. When **RESET_N** is released from the low level, the module automatically starts its power-on reset sequence.



If **RESET_N** is connected to an external device (e.g. an application processor on an application board) an open drain output can be directly connected without any external pull-up. Otherwise, use a push-pull output. Make sure to fix the proper level on **RESET_N** in all possible scenarios, to avoid unwanted reset of the module.

The reset state of all input-output pins is reported in the pin description table in the LUCY-H200 Data Sheet [1].

1.7 RF connection

The interface for RF signal (**ANT**) is available via the Hirose U.FL-SMT-R or equivalent sub-miniature coaxial connector. The **ANT** interface has a nominal impedance of 50 Ω , and must be connected to the antenna through a 50 Ω transmission line to allow transmission and reception of radio frequency (RF) signals in the GSM and UMTS operating bands.

Name	Description	Remarks
ANT	RF antenna	Zo = 50Ω nominal characteristic impedance.
		Hirose U.FL-SMT-R receptacle connector.

Table 7: Antenna pin

The RF receptacle implemented on the LUCY-H200 for **ANT** requires a suitable mated RF plug from the same connector series. Due to its wide usage in the industry, several manufacturers offer compatible equivalents. The board-to-board connector stacked mated height also limits the selection of the RF plug. Nevertheless the

nominal 3 mm height of the board-to-board connector effectively allows the usage of all U.FL compatible plugs available on the market.

Table 8 lists some RF connector plugs that fit LUCY-H200, based on the declaration of the respective manufacturers. Only the Hirose has been qualified for the LUCY-H200 module, contact other producers to verify compatibility.

Manufacturer	Series	Remarks
Hirose	U.FL® Ultra Small Surface Mount Coaxial Connector	Recommended
I-PEX	MHF® Micro Coaxial Connector	
Тусо	UMCC® Ultra-Miniature Coax Connector	
Amphenol RF	AMC® Amphenol Micro Coaxial	
LTI (Lighthorse Technologies, Inc)	IPX ultra micro-miniature RF connector	

Table 8: U.FL compatible plug connector

Typically the RF plug is available as a cable assembly: several kinds are available and the user should select the cable assembly best suited to the application. The key characteristics are:

- RF plug type: select U.FL or equivalent
- Cable thickness: typically from 0.8 mm to 1.37 mm
- Cable length: standard length is typically 100 mm or 200 mm, custom lengths may be available on request
- RF connector on other cable side: for example another U.FL (for board-to-board connection) or SMA (for panel mounting)



The LUCY-H200 module is calibrated at the on-board U.FL receptacle: select thicker and shorter cables to minimize insertion loss.

For applications requiring an internal integrated SMT antenna, it is suggested to use a U-FL-to-U.FL cable to provide RF path from the LUCY-H200 to PCB stripline or microstrip connected to antenna pads (see Figure 13). Take care that the PCB-to-RF-cable transition, stripline and antenna pads must be optimized for 50 Ω characteristic impedance.



If an external antenna is required, consider that the connector is typically rated for a limited number of insertion cycles. In addition, the RF coaxial cable may be relatively fragile compared to other types of cables. To increase application ruggedness, connect U.FL to a more robust connector (e.g. SMA or MMCX) fixed on panel or on flange (see Figure 13).

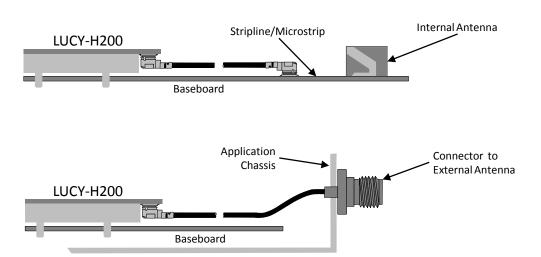


Figure 13: Example of RF connections, U.FL-to-U.FL cable for internal antenna and U.FL-to-SMA for external antenna

Choose an antenna with optimal radiating characteristics for the best electrical performance and overall module functionality. An internal antenna, integrated on the application board, or an external antenna, connected to the application board through a proper 50 Ω connector, can be used.



The recommendations of the antenna producer for correct installation and deployment (PCB layout and matching circuitry) must be followed.

For antenna supervision functionality, the antenna should have a built-in DC resistor to ground. The module injects a known DC current (few tenths of a μ A) on **ANT** and measures the resulting DC voltage, thus effectively achieving a resistance measurement for antenna detection (see section 2.4.3).



1.8 Antenna supervisor

Antenna detection is internally performed by the module via **ANT**. The RF port is DC coupled to the ADC unit in the baseband chip. The module measures the DC voltage at **ANT**, in the range of 0 to 2 V. Additionally, the module can inject a known DC current ($\sim 100 \, \mu$ A) on **ANT** and measures the resulting DC voltage.

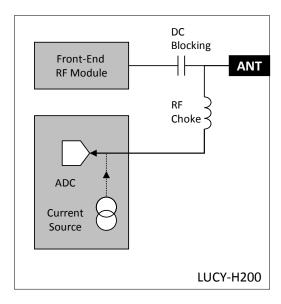


Figure 14: Antenna Supervisor internal circuit

If the DC voltage is present on **ANT**, or a DC connection to a known resistor at the radiating element is implemented, the module will be able to check the connection to the Antenna element.

Refer to the u-blox 3.5G HSDPA AT Commands Manual [2] for more details on how to access this feature.

1.9 SIM interface

An SIM card interface is provided on the board-to-board pins of the module: the high-speed SIM/ME interface is implemented as well as automatic detection of the required SIM supporting voltage.

Both 1.8 V and 3 V SIM types are supported: activation and deactivation with automatic voltage switch from 1.8V to 3 V is implemented, according to ISO-IEC 7816-3 specifications. The SIM driver supports the PPS (Protocol and Parameter Selection) procedure for baud-rate selection, according to the values determined by the SIM Card.

Table 9 describes the board to board pins related to the SIM interface:

Name	Description	Remarks
VSIM	SIM supply	1.80 V typical or 2.90 V typical automatically generated by the module
SIM_CLK	SIM clock	3.25 MHz clock frequency
SIM_IO	SIM data	Open drain, internal 4.7 k Ω pull-up resistor to VSIM
SIM_RST	SIM reset	

Table 9: SIM Interface pins

Figure 15 shows the minimal circuit connecting the LUCY module and the SIM card.



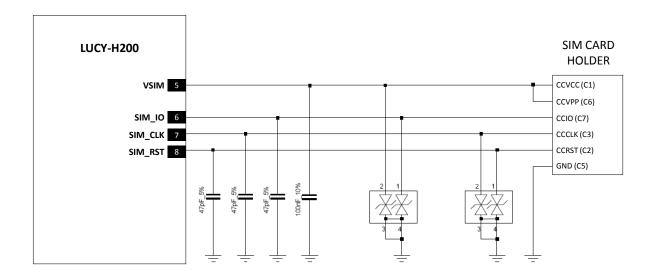


Figure 15: SIM interface application circuit

When connecting the module to SIM connector perform the following steps on the application board:

- Bypass digital noise via a 100 nF capacitor (e.g. Murata GRM155R71C104K) on the SIM supply (VSIM)
- To prevent RF coupling in case the module RF antenna is placed closer than 10 30 cm from the SIM card holder, connect a bypass capacitor of about 22 pF to 47 pF (e.g. Murata GRM1555C1H470J) at each SIM signal (SIM_CLK, SIM_IO, SIM_RST) to ground near the SIM connector
- Mount very low capacitance ESD protection (e.g. Infineon ESD8V0L2B-03L or AVX USB0002RP) near the SIM card connector
- Limit capacitance on each SIM signal to match the SIM specifications: always route the connections as short as possible

1.9.1 (U)SIM functionality

The following SIM services are supported:

- Abbreviated Dialing Numbers (ADN)
- Fixed Dialing Numbers (FDN)
- Last Dialed Numbers (LDN)
- Service Dialing Numbers (SDN)
- USIM Application Toolkit (USAT) R99 is supported.

1.10 Asynchronous serial interface (UART)

The UART interface is an 8-wire unbalanced asynchronous serial interface that provides an AT commands interface, GPRS data and CSD data, software upgrades. The LUCY module implements two UART interfaces: UART0 (8-wire interface) and UART1 (4-wire interface).

The UARTO interface provides RS-232 functionality conforming to the ITU-T V.24 Recommendation (more details available in ITU Recommendation [3]), with CMOS compatible signal levels: 0 V for low data bit or ON state, and 1.8 V for high data bit or OFF state. Two different external voltage translators (Maxim MAX3237E and On Semiconductor NLSX3018MUTAG) could be used to provide full RS-232 (8 lines) compatible signal levels. The On Semiconductor chip provides the translation from 1.8 V to 3.3 V, while the Maxim chip provides the necessary RS-232 compatible signal towards the external connector. If an UART interface with only 4 lines is needed, the Maxim 13234E voltage level translator can be used. This chip translates the voltage levels from 1.8 V (modem side) to the RS-232 standard. For detailed electrical characteristics refer to the LUCY-H200 Data Sheet [1].



The LUCY-H200 modules is designed to operate as a UMTS/HSDPA modem, which represents the data circuit-terminating equipment (DCE) as described by the ITU-T V.24 Recommendation [3]. A customer application processor connected to the module through the UART interface represents the data terminal equipment (DTE).

Take care to provide the needed accessibility (by means of test points, connector etc.) to **UARTO_TX**, **UARTO_RX** and **PWR_ON** pins in order to re-flash/update the LUCY module even if it is not planned to use UARTO.

The signal names of the LUCY-H200 UART interface are conform to ITU-T V.24 Recommendation [3]. The UART interface includes the following lines:

Name	Description	Remarks
DSR	Data set ready	Module output, functionality of ITU-T V.24 Circuit 107 (Data set ready)
RI	Ring Indicator	Module output, functionality of ITU-T V.24 Circuit 125 (Calling indicator)
DCD	Data carrier detect	Module output, functionality of ITU-T V.24 Circuit 109 (Data channel received line signal detector)
DTR	Data terminal ready	Module input, functionality of ITU-T V.24 Circuit 108/2 (Data terminal ready) Internal active pull-up to 1.8 V enabled.
RTS	Ready to send	Module hardware flow control input, functionality of ITU-T V.24 Circuit 105 (Request to send) Internal active pull-up to 1.8 V enabled.
CTS	Clear to send	Module hardware flow control output, functionality of ITU-T V.24 Circuit 106 (Ready for sending)
TxD	Transmitted data	Module data input, functionality of ITU-T V.24 Circuit 103 (Transmitted data) Internal active pull-up to 1.8 V enabled.
RxD	Received data	Module data output, functionality of ITU-T V.24 Circuit 104 (Received data)

1.10.1 UART features

UART interface(s) are controlled and operated with:

- AT commands according to 3GPP TS 27.007 [4]
- AT commands according to 3GPP TS 27.005 [5]
- AT commands according to 3GPP TS 27.010 [6]
- u-blox AT commands

All flow control handshakes are supported by the UART interface and can be set by appropriate AT commands (see u-blox 3.5G HSDPA AT Commands Manual [2]): hardware flow control (RTS/CTS), software flow control (XON/XOFF), or none flow control.



Hardware flow control is default.



For the complete list of supported AT commands and their syntax refer to the u-blox 3.5G HSDPA AT Commands Manual [2].

The following baud rates can be configured using AT commands:

- 2400 b/s
- 4800 b/s
- 9600 b/s



- 19200 b/s
- 38400 b/s
- 57600 b/s
- 115200 b/s
- 230400 b/s
- 460800 b/s

The frame format can be:

- 8N1 (8 data bits, No parity, 1 stop bit)
- 8E1 (8 data bits, even parity, 1 stop bit)
- 801 (8 data bits, odd parity, 1 stop bit)
- 8N2 (8 data bits, No parity, 2 stop bits)

The default frame configuration with fixed baud rate is 8N1, described in the Figure 16.

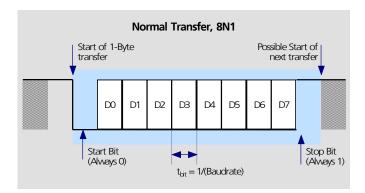


Figure 16: UART default frame format (8N1) description

1.10.2 UARTO signal behavior

See Table 2 for a description of operating modes and states referred to in this section.

By default the **RxD** and the **TxD** lines are set to OFF state at UART initialization, following the boot sequence when the module is switched on. The module holds **RxD** and **TxD** in OFF state until data is either transmitted or received by the module: an active pull-up is enabled inside the module on the **TxD** input.

The hardware flow control output (**CTS** line) indicates when the module is in active mode and the UART interface is enabled: the module drives the **CTS** line to the ON state or to the OFF state when it is either prepared or not prepared to accept data from the external device (DTE).

After the boot sequence the **CTS** line is set to ON state at UART initialization, when the module is in active-mode and ready to operate. By default the module automatically enters idle-mode (power saving) unless this mode has been disabled using an AT command (see u-blox 3.5G HSDPA AT Commands Manual [2]). Data sent by the DTE can be lost if hardware flow-control is not enabled. The module periodically wakes up from idle-mode to active-mode to be synchronized with network activity. Idle-mode time is fixed by network parameters and can be up to ~2.1 s. When the module wakes up to active-mode, the UART interface is enabled: the **CTS** line is switched to ON state and is held in this state for a minimum of ~11 ms.

The behavior of hardware flow-control output (**CTS** line) during normal module operations (idle mode and active mode) is illustrated in Figure 17.



The time delay for the module to go from active-mode to idle-mode depends (in addition to dependency on network parameters) on the timeout from the last data received at the serial port. This timeout is configurable by the AT+UPSV command, between 40 GSM frames (~184 ms) and 65000 GSM frames (~300 s). Default value is 2000 GSM frames (~9.2 s).

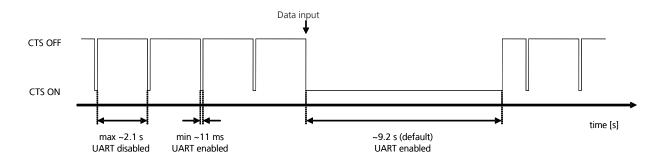


Figure 17: CTS behavior during normal module operation: the CTS line indicates when the module is able (CTS = ON) or not able (CTS = OFF) to accept data from the DTE and communicate through the UART interface

The hardware flow control input (**RTS** line) is set by default to OFF state at UART initialization at the end of the boot sequence, after the module switches on. The **RTS** line is then held by the module in OFF state if hardware flow- control is not enabled by the DTE. An active pull-up is enabled inside the module on the **RTS** input.

The module drives the **DSR** line to indicate whether it is ready to operate or not. After the module switches on, **DSR** line switches from ON state to OFF state as shown in Figure 18. During the Boot process of the module, **DSR** is forced to OFF, until the module is not ready to operate. It is switched to ON state when the module is ready to operate. The time T_{switch} depends on the duration of the boot process, and is in the range of ~1 s.

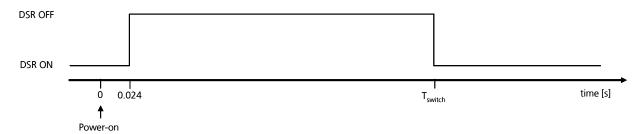


Figure 18: DSR behavior at power-on

The **DTR** line is set by default to OFF state at UART initialization, at the end of the boot sequence, after the module switch on. The DTR line is then held by the module in the OFF state if the line is not activated by the DTE. An active pull-up is enabled inside the module on the **DTR** input.

The **RI** and **DCD** lines are set by default to OFF state at UART initialization, at the end of the boot sequence. The **RI** line is then held by the module in OFF state until an incoming call or SMS is received. The **DCD** line is held in OFF state until a data call is accepted.

During an incoming call the **RI** line is switched from OFF state to ON state with a 4:1 duty cycle and a 5 s period (ON for 1 s, OFF for 4 s, see Figure 19), until the DTE attached to the module sends the ATA string and the module accepts the incoming data call. The RING string sent by the module (DCE) to the serial port at constant time intervals is not correlated with the switch of the **RI** line to the ON state. When the data call is accepted, the module is set to ON state and the serial line **DCD** sends the CONNECT<communication baudrate> to the DTE. DTE sends data through the DCE and the GSM network to the remote DCE-DTE system and data communication can be performed as for outgoing data calls.



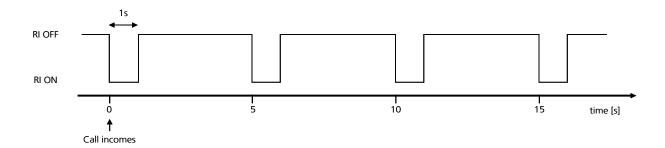


Figure 19: RI behavior during incoming call

The **RI** line is used to notify an SMS arrival. When the SMS arrives, the **RI** line switches from OFF to ON for 1 s (see Figure 20).

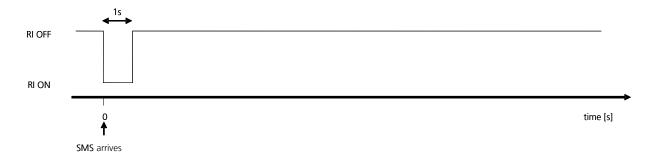


Figure 20: RI behavior at SMS arrival

1.10.3 Connecting UARTO on application boards - Full RS-232 Functionality

For complete RS-232 functionality conforming to ITU Recommendation [3] in DTE/DCE serial communication, the complete UARTO interface of the module (DCE) must be connected to the DTE as described in Figure 21.

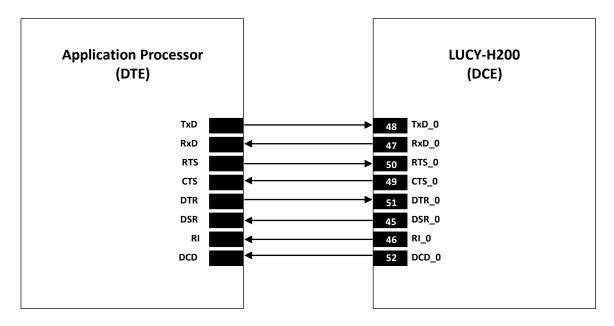


Figure 21: Interface application circuit with complete V.24 link in DTE/DCE serial communication

3G.G1-HW-10002-P1 Advance Information System description



1.10.3.1 Connecting UARTO on application boards - TxD, RxD, RTS and CTS lines only (not using the complete V.24 link)

If only the **TxD**, **RxD**, **RxS** and **CTS** lines are desired, it is possible to use the UART1 serial interface, otherwise follow the application circuit described in Figure 22. HW flow-control is used. The module wakes up from default idle-mode to active-mode when data is received at the UART interface, since the HW flow control is enabled by default in the module.

- Connect on the application board the **DSR** output line to the module **DTR** input line, since the module requires **DTR** active (low electrical level) and **DSR** is active (low electrical level) once the module is switched on and the UARTO interface is enabled
- Leave **DCD** and **RI** lines of the module unconnected and floating

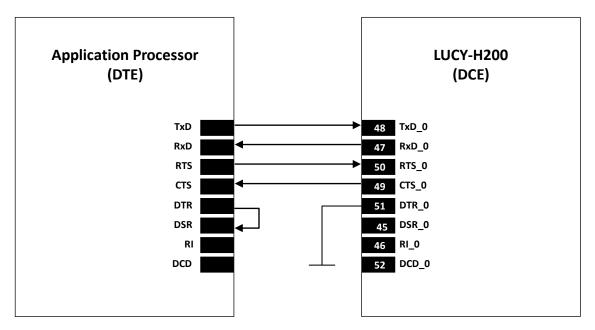


Figure 22: UART0 interface application circuit with partial V.24 link (4-wire) in the DTE/DCE serial communication

1.10.3.2 Connecting TxD and RxD lines only (not complete V24 link)

Follow the application circuit described in Figure 23. HW flow control is not used. The module doesn't wake up from idle-mode to active-mode when data is received at the UART interface. Since HW flow control is by default enabled in the module, data delivered by the DTE can be lost.

The module cannot be woken-up in this case, and for this reason this configuration is not recommended.

- Connect on the application circuit the module the **CTS** output line to the module **RTS** input line, since the module requires **RTS** active (low electrical level) and **CTS** is active (low electrical level) when the module is in active mode and the UART interface is enabled
- Connect on the application circuit the module the DSR output line to the module DTR input line, since the
 module requires DTR active (low electrical level) and DSR is active (low electrical level) once the module is
 switched on and the UART interface is enabled
- **DCD** and **RI** lines of the module can be left unconnected and floating

Also in this configuration the UART interface can be used as AT commands interface, for GPRS data and CSD data communication and for software upgrades, but without the HW flow control, data delivered by the DTE can be lost.



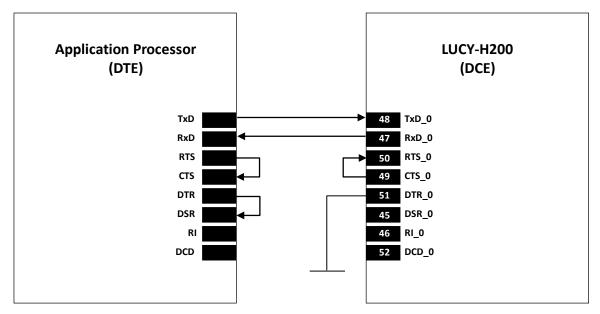


Figure 23: UART interface application circuit with partial V.24 link (2-wire) in the DTE/DCE serial communication



On an application board, it is highly recommended to provide direct access to **RxD_0** and **TxD_0** lines of the module (in addition to access to these lines from an application processor). This enables a direct connection of PC (or similar) to the module for execution of Firmware upgrade over the UART. Provide as well access to **PWR_ON** line in order to flash the module.

1.10.4 UART1 serial port

UART1 also provides RTS and CTS lines for HW handshaking. For their use please refer to UART0 RTS and CTS connection.



It is not possible to Flash the module through UART1, so provide appropriate access to UART0 RXD, UART0 TXD, and PWR_ON lines on the application board.



1.10.5 MUX Protocol (3GPP 27.010)

The module has a software layer with MUX functionality complaint with 3GPP 27.010 [8].

This is a data link protocol (layer 2 of OSI model) using HDLC-like framing and operates between the module (DCE) and the application processor (DTE). The protocol allows simultaneous sessions over the UART. Each session consists of a stream of bytes transferring various kinds of data like SMS, CBS, GPRS, AT commands in general. This permits, for example, SMS to be transferred to the DTE when a data connection is in progress.

The following virtual channels are defined:

- Channel 0: control channel
- Channel 1 5: AT commands /data connection
- Channel 6: GPS tunnelling

1.11 DDC (I²C) interface

1.11.1 Overview

An I²C compatible Display Data Channel (DDC) interface for serial communication is implemented. This interface is intended exclusively to access u-blox GPS receivers.

Name	Description	Remarks
SCL	I ² C bus clock line	Open drain. External pull-up required.
SDA	I ² C bus data line	Open drain. External pull-up required.

Table 10: DDC pins

To be compliant to the I^2C bus specifications, the module bus interface pads are open drain output and pull up resistors must be used. Since the pull-up resistors are not mounted on the module, they must be mounted externally. Resistor values must conform to the I^2C bus specifications [7]. If the LUCY-H200 module is connected through the DDC bus to a single u-blox GPS receiver only (only one device is connected on the DDC bus), use a pull-up resistor of 4.7 k Ω . Pull-ups must be connected to a supply voltage of 1.8 V (typical), since this is the voltage domain of the DDC pins. VINT voltage domain can be used to provide 1.8 V for the pull-ups (for detailed electrical characteristics see the LUCY-H200 Data Sheet [1]).

DDC Slave-mode operation is not supported, the module can act as master only.

Two lines, serial data (**SDA**) and serial clock (**SCL**), carry information on the bus. **SCL** is used to synchronize data transfers, and **SDA** is the data line. Since both lines are open drain outputs, the DDC devices can only drive them low or leave them open. The pull-up resistor pulls the line up to the supply rail if no DDC device is pulling it down to GND. If the pull-ups are missing, **SCL** and **SDA** lines are undefined and the DDC bus will not work.

The signal shape is defined by the values of the pull-up resistors and the bus capacitance. Long wires on the bus will increase the capacitance. If the bus capacitance is increased, use pull-up resistors with nominal resistance value lower than 4.7 k Ω , to match the I²C bus specifications regarding rise and fall times of the signals [7].



Capacitance must be limited on the bus to match the I²C specifications: route connections as short as possible.



If the pins are not used as DDC bus interface, they can be left unconnected.



1.11.2 DDC application circuit

The **SDA** and **SCL** lines can be used only to connect the LUCY module to a u-blox GPS module: LUCY DDC (I²C) interface is enabled by the +UGPS AT command only. **GPIO2** is automatically driven as output by the +UGPS AT command to switch-on or switch-off the u-blox GPS module, connecting **GPIO2** to the active-high enable pin (or the active-low shutdown pin) of the voltage regulator that supplies the u-blox GPS module on the application board. The application circuit for **SDA**, **SCL** and **GPIO2** is illustrated in Figure 24.

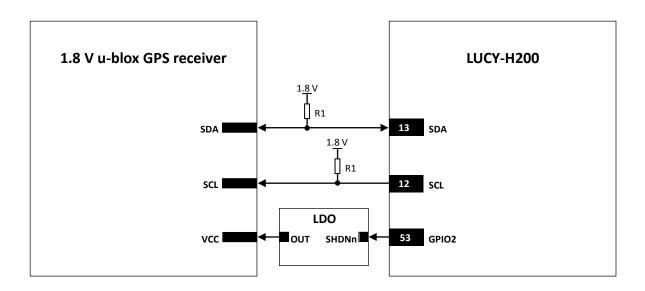


Figure 24: DDC Application circuit for 1.8V u-blox GPS receivers.

Name	Suggested Value
R1	4.7 kΩ

Table 11 - Component for DDC application circuit

The application circuit depicted in Figure 24 is valid only for the 1.8 V u-blox GPS receivers' family. LUCY VINT can be used for 1.8 V.

If a 3 V u-blox GPS receiver is used, SDA and SCL lines can be simply pulled up to 3 V as shown in Figure 25 since LUCY pins are 3 V tolerant. If a 3 V GPS receiver is used, for future compatibility with the next generation of u-blox UMTS modules, a level translating solution can be placed as a non-mounting option bypassed by zero Ω resistors. For example, Texas Instruments PCA9306 bidirectional I²C voltage level translator can be used as a not mounting option.



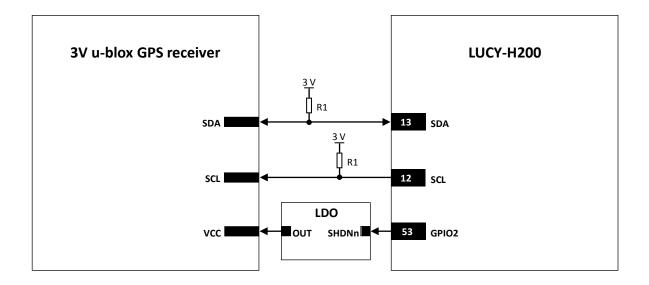


Figure 25: Application circuit for 3V u-blox GPS receivers.

1.12 SPI interface

SPI is a master-slave protocol: the LUCY module natively runs as an SPI slave, e.g. it accepts AT commands on its SPI interface. Any LUCY module can be commanded via AT commands to become an SPI master device. Then, always via AT commands, an embedded program can run on an LUCY module so that the data flow from the AT port is redirected on the SPI interface and vice versa.

The SPI-compatible synchronous serial interface cannot be used for SW download.

The SPI interface includes two signals to transmit and receive data (one is the MOSI master output / slave input data, the other is the MISO master input / slave output data) and a clock signal (SCLKO) generated by the master. The directions of these lines are inverted if the LUCY module runs as an SPI slave or as an SPI master device:

- MOSI signal is an output for the LUCY module if it runs as SPI master or is an input if it runs as SPI slave
- MISO signal is an input for the LUCY module if it runs as SPI master or is an output if it runs as SPI slave
- SCLKO signal is an output for the LUCY module if it runs as SPI master or is an input if it runs as SPI slave

On the LUCY module, the standard 3-wire SPI interface implements, together with the two handshake signals SPI MRDY and SPI SRDY, the 5-wire Inter Processor Communication (IPC) interface.

The purpose of the IPC interface is to achieve high speed communication (up to 12 Mb/s) between two processors following the same IPC specifications: the LUCY baseband processor and an external processor.

This interface is suggested for high speed UMTS/HSDPA communications and could be necessary to communicate with an Application Processor which is not equipped with a USB interface.

In the LUCY IPC interface, the SPI interface on the modem side is running in slave mode and the SPI interface on the application processor is running in master mode, so this is the direction of the SPI signals in the IPC interface:

- MOSI signal is an input for the LUCY module in the IPC interface
- MISO signal is an output for the LUCY module in the IPC interface
- SCLKO signal is an input for the LUCY module in the IPC interface



The function of the **SPI_MRDY** and **SPI_SRDY** signals is twofold. For transmitting data the signal indicates to the data receiver that data is available to be transmitted. For reception of data the signal indicates to the transmitter that the receiver is ready to receive data. Due to this setup it is possible to use the control signals as interrupt lines waking up the receiving part when data is available for transfer. When the handshaking has taken place, the transfer occurs just as if it were a standard SPI interface without chip select functionality (i.e. one master - one slave setup).

SPI_MRDY is used by the application processor (i.e. the master) to indicate to the LUCY baseband processor (i.e. the slave) that it is ready to transmit or receive (IPC master ready signal), and can also be used by the application processor to wake up the LUCY baseband processor if it is in the idle mode. **SPI_MRDY** is an input for the LUCY module able to detect an external interrupt which comes from the application processor.

SPI_MRDY can also be configured by means of software settings for different uses as an alternative to the default software setting which is the IPC flow control line input functionality support.

SPI_MRDY can be configured to support the external interrupt detection input functionality: in this case some LUCY module activity can be triggered by a rising edge or by a falling edge or both rising/falling edges presence on this line. The user can set these options by software.

SPI_SRDY line is used by the LUCY baseband processor (i.e. the slave) to indicate to the application processor (i.e. the master) that it is ready to transmit or receive (IPC slave ready signal), and can also be used by the LUCY baseband processor to wake up the application processor if it is in hibernation. **SPI_SRDY** is an output for the LUCY module, and the application processor should be able to detect an external interrupt which comes from the LUCY module on its connected pin.

SPI_SRDY can also be configured as GPIO by means of software settings as alternative of the default software setting which is the IPC flow control line output functionality support.

The description of pins of the Board-to-Board connector related to IPC interface is reported in Table 12:

B2B PIN #	LUCY Signal Name	LUCY I/O	Description	Remarks
9	SPI_MISO	0	SPI and IPC sync data (Master Input, Slave Output)	Digital I/O interfaces voltage domain
10	SPI_MOSI	I	SPI and IPC sync data (Master Output, Slave Input)	Digital I/O interfaces voltage domain
38	SPI_MRDY	I	IPC flow control line input (Master Ready)	Digital I/O interfaces voltage domain Default SW setting: IPC flow control line input Alternative SW setting: External interrupt input
32	SPI_SRDY	0	IPC flow control line output (Slave Ready)	Digital I/O interfaces voltage domain Default SW setting: IPC flow control line output Alternative SW setting: GPIO

Table 12: SPI signals on B2B

1.13 USB interface

LUCY data modules provide a USB interface which complies with the full-speed USB 2.0 standard at 12 Mb/s. It acts as a USB device and can be connected to any USB host such as a PC or other Application Processor.



Since the module acts as a USB device, the USB supply (5.0 V typ.) must be provided to **VUSB_DET** by the connected USB host. As pointed out in chapter 1.6.1 if **VUSB_DET** is at VUSB range and USB is active, **UARTO** is automatically disabled, so the two peripherals cannot be used simultaneously.



Take care to provide the needed accessibility (by means of test points, connector etc.) to **UARTO_TX**, **UARTO_RX**, and **PWR_ON** pins in order to re-flash/update LUCY module.



The module does not enter idle mode when USB voltage (typically 5 V) is detected at **VUSB_DET** pin.



When the module is connected to another device via USB (e.g. a PC) the module does not go in idle mode. The power consumption will be the same of the active state. This current is not taken from the PC but to the module power supply.

1.14 Serial interfaces configuration

Not all the serial communication are allowed in the same time. Via a dedicated AT command it's possible to set up the preferred configuration, to be chosen into the following list (for more details please refer to u-blox 3.5G HSDPA AT Commands Manual [2]):

Variant	UART0	UART1	USB	SPI (slave)
0	AT interface (if USB is not connected; otherwise disabled)	RX and TX signals for debug purposes	AT interface (if connected)	
1	RX and TX signals for debug purposes	AT interface	AT interface	
2	AT interface (if USB is not connected; otherwise disabled)	RX and TX signals for debug purposes	AT interface (if connected)	AT interface

Table 13 - Serial interfaces configuration



For UARTO and UART1 is intended the full signals configuration if not indicated differently.

1.15 ADC input

One Analog to Digital Converter input is available (**ADC1**) and is configurable using a custom AT command (see u-blox 3.5G HSDPA AT Commands Manual [2]). The resolution of this converter is 12-bit with a single ended input range.

Name	Description	Remarks
ADC1	ADC input	Resolution: 12 bits.

Table 14: ADC pin

The electrical behavior of the measurement circuit in voltage mode can be modeled by a circuit equivalent to that shown in Figure 26. This includes a resistor (R_{eq}), voltage source (U_{eq}), analog preamplifier (with typical gain G=0.5), and a digital amplifier (with typical gain $g_{ADC}=2048$ LSB/V).



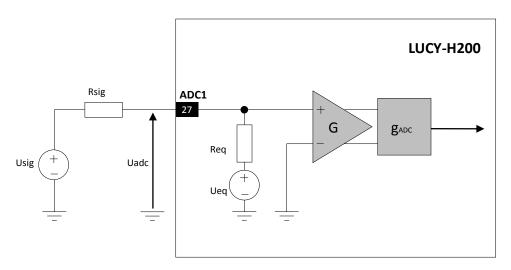


Figure 26: Equivalent network for ADC single-ended measurement

The ADC software driver takes care of the parameters shown in Figure 26 (R_{eq} , $U_{eq'}$, G, g_{ADC}). The voltage measured by the ADC is U_{adc} . If the voltage source (U_{sig}) has a significant internal resistance (R_{sig}) compared to the input resistance in measurement mode (R_{sig}) of the ADC, this should be taken into account and corrected.



If an external voltage divider is implemented to increase the voltage range, check the input resistance in measurement mode (R_{eq}) of the ADC input and all the electrical characteristics.

The detailed electrical specifications of the Analog to Digital Converter input are reported in the LUCY-H200 Data Sheet [1].

1.16 General Purpose Input/Output (GPIO)

The LUCY-H200 module provides five General Purpose Input/Output pins (**GPIO1**...**GPIO5**) which can be configured via u-blox AT commands (more details available in u-blox 3.5G HSDPA AT Commands Manual [2]). Some GPIOs are used for special indications as reported below:

- **GPIO2** is dedicated for connection to a u-blox GPS receiver: AT commands are used to drive the GPIO as output to wake up the u-blox GPS module. If LUCY-H200 module is not connected to a u-blox GPS module, GPIO2 can be used for general purposes
- **GPIO3** by default indicates whether the module is registered on a 2G or on a 3G network. If this indication is not needed, the GPIO can be used by means of the appropriate AT command
- **GPIO4** by default indicates antenna jamming activity. If this indication is not needed, the GPIO can be used by means of the appropriate AT command

When an LED is to be driven by means of a GPIO use a transistor and an appropriate voltage source as shown in the Figure 27 for **GPIO1** and **GPIO3**.



Use transistors with at least an integrated resistor in the base pin or otherwise put a 10 k Ω resistor on the board in series to the GPIO.



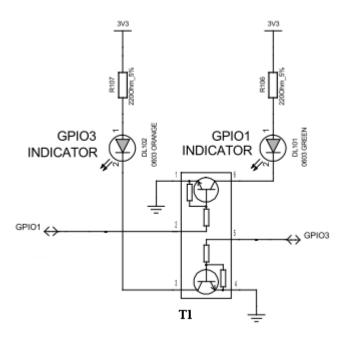


Figure 27: LED driving with GPIO

Name	Description	Remarks
T1	BCR135S BJT by Infineon	Use transistors with at least an integrated resistor in the base pin or otherwise put a $10k\Omega$ resistor on the board in series to the GPIO.

Table 15 - Component for LED driving with GPIO

1.17 Audio Interface

The LUCY-H200 module provides one digital and two analog audio interfaces:

- One microphone input
- One Speaker output
- I²S digital audio interface: input and output

Audio signal routing can be controlled by the dedicated AT command +USPM (refer to u-blox 3.5G HSDPA AT Commands Manual [2]). This command allows setting the audio path mode, composed by the uplink audio path and the downlink audio path; e.g. in headset mode the uplink audio path is "Headset microphone", the downlink audio path is "Mono headset". In turns, each uplink path is composed by the audio input and by a set of parameters to process the audio signal (uplink gains, uplink digital filters, echo canceller parameters). For example "Headset microphone" uplink path uses the analog microphone input with a default analog gain of 27 dB.

Each downlink path is composed by the audio output and by a set of parameters to process the audio signal (downlink gains, downlink digital filters, sidetone). These parameters can be changed with dedicated AT commands for each uplink or downlink path and then stored in 2 profiles in the non volatile memory (refer to ublox 3.5G HSDPA AT Commands Manual [2] for Audio parameters tuning commands).



1.17.1 Analog Audio interface

1.17.1.1 Microphone input

The microphone input can be used for direct connection of the electret condenser microphone to a headset, handset or hands-free device. The main required electrical specifications for the electret condenser microphone are $2.2 \text{ k}\Omega$ as maximum output impedance at 1 kHz and 2 V as maximum standard operating voltage.

Board-to-board pins related to the microphone input are:

- MIC_BIAS: single ended supply to the microphone and represents the microphone signal input
- MIC_GND: local ground for the microphone

Detailed electrical characteristics of the microphone input can be found in LUCY-H200 Data Sheet [1].

1.17.1.2 Speaker output

A differential high power audio output, can be used to directly connect a headset earpiece, handset earpiece or a loudspeaker used for ring-tones or for speech in a hands-free device.

Board-to-board pins related to the speaker output are:

• **SPK_N / SPK_P**: high power differential audio output. These two pins are internally connected to the output of a high power differential audio amplifier

Detailed electrical characteristics of the high power differential audio output can be found in LUCY-H200 Data Sheet [1].



Warning: excessive sound pressure from headphones can cause hearing loss.



All audio lines on an Application Board must be routed in pairs, be embedded in GND (have the ground lines as close as possible to the audio lines), and maintain distance from noisy lines such as **VCC** and from components as switching regulators.

1.17.1.3 Headset mode

Headset mode is the default audio operating mode of the LUCY-H200 module:

• In headset mode the uplink audio path is "Headset microphone", the downlink audio path is "Mono headset" (refer to AT commands manual: AT+USPM command: <main_uplink>,<main_downlink> parameters)

The audio path used in headset mode:

- Headset microphone must be connected to MIC_BIAS/MIC_GND
- Headset receiver must be connected to SPK_P/SPK_N

Figure 28 shows an example of an application circuit connecting a headset (with a 2.2 k Ω electret microphone and a 32 Ω receiver) to the LUCY-H200 module (jack connector omitted). The following should be done on the application circuit:



Mount an 82 nH series inductor (e.g. Murata LQG15HS82NJ02) on each microphone line, and a 27 pF bypass capacitor (e.g. Murata GRM1555C1H270J) on all audio lines to minimize RF coupling and TDMA noise.



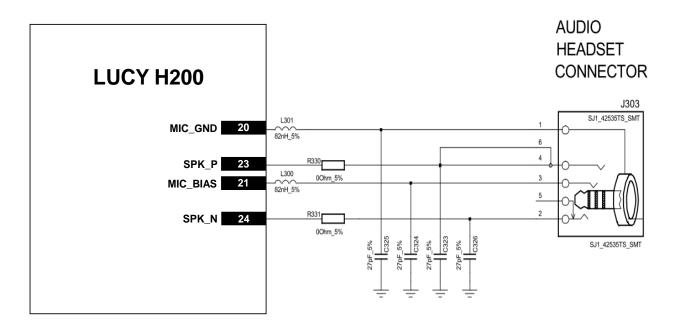


Figure 28: Headset mode application circuit

1.17.1.4 Handset mode

In handset mode, the uplink audio path is "Handset microphone", the downlink audio path is "Normal earpiece" (refer to AT commands manual: AT+USPM command: <main uplink>,<main downlink> parameters).

- Handset microphone must be connected to inputs MIC_BIAS / MIC_GND
- Handset receiver must be connected to outputs SPK P / SPK N

Figure 29 shows an example of an application circuit connecting a handset (with a 2.2 k Ω electret microphone and a 32 Ω receiver) to the LUCY-H200 module (headset connector omitted). The following should be done on the application circuit:



Mount an 82 nH series inductor (e.g. Murata LQG15HS82NJ02) on each microphone line and a 27 pF bypass capacitor (e.g. Murata GRM1555C1H270J) on all audio lines to minimize RF coupling and TDMA noise.



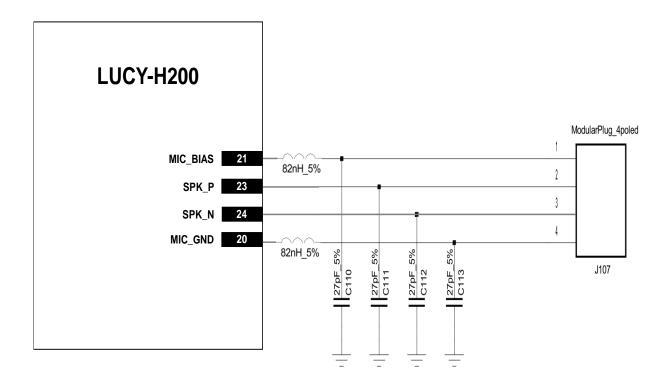


Figure 29: Handset mode application circuit

1.17.1.5 Hands-free mode

It is possible to implement a hands-free device using a loudspeaker and a microphone.

In hands-free mode, the uplink audio path is "HF carkit microphone", the downlink audio path is "Loudspeaker" (refer to AT commands manual: AT+USPM command: <main_uplink>, <main_downlink> parameters) .Hands-free functionality is implemented using appropriate DSP algorithms for voice band handling (echo canceller and automatic gain control), managed via software. (Refer to u-blox 3.5G HSDPA AT Commands Manual [2] - AT+UHFP command)

- Microphone must be connected to the input pins MIC_BIAS / MIC_GND
- High power loudspeaker must be connected to the output pins SPK_P / SPK_N



The physical width of the high-power audio outputs lines on the application board must be wide enough to minimize series resistance.

Figure 30 shows an application circuit for hands free mode. In this example the LUCY-H200 module is connected to an 8 Ω speaker and a 2.2 k Ω electret microphone. Insert an 82 nH series inductor (e.g. Murata LQG15HS82NJ02) on each microphone line and a 27 pF bypass capacitor (e.g. Murata GRM1555C1H270J) on all audio lines to minimize RF coupling and TDMA noise.



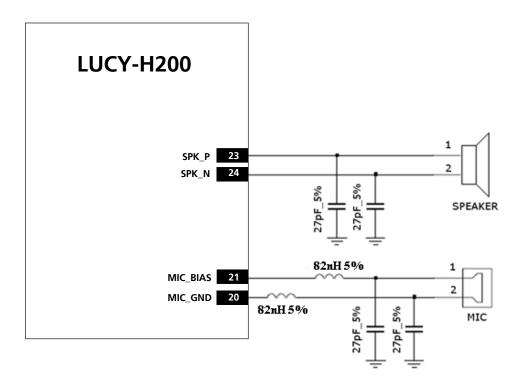


Figure 30: Hands-free mode application circuit

1.17.1.6 Connection to an external analog audio device

When the LUCY-H200 module analog audio output is connected to an external audio device, **SPK_P / SPK_N** analog audio outputs can be used. A 10 μ F series capacitor (e.g. Murata GRM188R60J106M) must be inserted between the **SPK_P** output and the single ended analog input of the external audio device (to decouple the bias).

Audio devices with a differential analog input can be connected directly to SPK_P / SPK_N balanced output.

The signal levels can be adapted by setting gain using AT commands, but additional circuitry must be inserted if the **SPK P / SPK N** output level of the module is too high for the input of the audio device.

If the LUCY-H200 module analog audio input is connected to an external audio device, **MIC_BIAS / MIC_GND** can be used (default analog audio input of the module). Insert a 10 µF series capacitor (e.g. Murata GRM188R60J106M) between the single ended analog output of the external audio device and **MIC_BIAS**. Connect the reference of the single ended analog output of the external audio device to **MIC_GND**. If the external audio device is provided with a differential analog output, insert an additional differential to single ended circuit. The signal levels can be adapted by setting gain using AT commands, but additional circuitry must be inserted if the output level of the audio device is too high for **MIC_BIAS**.



To enable the audio path corresponding to these input/output, please refer to u-blox 3.5G HSDPA AT Commands Manual [2]: AT+USPM command.



To tune audio levels for the external device please refer to u-blox 3.5G HSDPA AT Commands Manual [2] (AT+USGC, AT+UMGC commands).



1.17.2 Digital mode / digital audio interface

The LUCY-H200 module supports a bidirectional 4-wire I²S digital audio interface. The module acts as master only. The applicable pins are described in Table 16:

Name	Description	Remarks
I2S_WA	I ² S word alignment	Module output (master)
I2S_TXD	l²S transmit data	Module output
I2S_CLK	I ² S clock	Module output (master)
I2S_RXD	I ² S receive data	Module input

Table 16: I2S interface pins

The I²S interface can be can be used in two modes:

- PCM mode
- Normal I²S mode

The I²S interface is activated and configured using AT commands, see u-blox 3.5G HSDPA AT Commands Manual: +USPM.

Parameters of digital path can be configured and saved as the normal analog paths, using appropriate path index as described in the u-blox 3.5G HSDPA AT Commands Manual [2]. Analog gain parameters of microphone and speakers are unused when digital path is selected.

I2S_TX and **I2S_RX** are respectively parallel to the analog front end, so resources available for analog path can be shared:

- Digital filters and digital gains are available in both uplink and downlink direction. Configure using AT commands
- Ringer tone and service tone are mixed on the TX path when active (downlink)
- The HF algorithm acts on I²S path



Any external signal connected to the digital audio interface must be set low or tri-stated when the module is in power down mode to avoid an increase of module power consumption. If the external signals connected to the digital audio interface cannot be set low or tri-stated, insert a multi channel digital switch (e.g. Texas Instruments SN74CB3Q16244, TS5A3159, or TS5A63157) between the two-circuit connections and set to high impedance when the module is in power down mode.



For debug purposes, include a test point at each I²S pin also if the digital audio interface is not used.



Refer to the u-blox 3.5G HSDPA AT Commands Manual [2]: AT+UI2S command for possible combinations of connection and settings.

1.17.2.1 I2S interface - PCM mode

Main features of the I²S interface in PCM mode:

- I²S runs in PCM short alignment mode (configurable by AT commands)
- Module functions as I²S master (I2S_CLK and I2S_WA signals generated by the module)
- I2S_WA signal always runs at 8 kHz
- **I2S_WA** toggles high for 1 or 2 CLK cycles of synchronism (configurable), then toggles low for 16 CLK cycles of sample width. Frame length can be 1 + 16 = 17 bits or 2 + 16 = 18 bits
- I2S_CLK frequency depends on frame length. Can be 17 x 8 kHz = 136 kHz or 18 x 8 kHz = 144 kHz



- I2S_TX, I2S_RX data are 16 bit words with 8 kHz sampling rate, mono. Data is in 2's complement notation. MSB is transmitted first
- When **I2S_WA** toggles high, the first synchronization bit is always low. Second synchronization bit (present only in case of 2 bit long **I2S_WA** configuration) is MSB of the transmitted word (MSB is transmitted twice in this case)
- I2S_TX changes on I2S_CLK rising edge, I2S_RX changes on I2S_CLK falling edge

1.17.2.2 I2S interface - Normal I2S mode

Normal I²S supports:

- 16 bits word
- mono interface
- 8 kHz frequency

Main features of I²S interface in normal I²S mode:

- I25_WA signal always runs at 8 kHz and synchronizes 2 channels (timeslots on WA high, WA low)
- I2S_TX data are composed of 16 bit words, dual mono (the words are written on both channels). Data are in 2's complement notation. MSB is transmitted first. The bits are written on I2S_CLK rising or falling edge (configurable)
- I2S_RX data are read as 16 bit words, mono (words are read only on the timeslot with WA high). Data is read in 2's complement notation. MSB is read first. The bits are read on the I2S_CLK edge opposite to I2S_TX writing edge (configurable)
- **I2S CLK** frequency is 16 bits x 2 channels x 8 kHz = 256 kHz

The modes are configurable through a specific AT command (refer to the related chapter in u-blox 3.5G HSDPA AT Commands Manual [2]) and the following parameters can be set:

- MSB can be 1 bit delayed or non-delayed on I2S WA edge
- I2S_TX data can change on rising or falling edge of I2S_CLK signal (rising edge in this example)
- I2S_RX data are read on the opposite front of I2S_CLK signal

1.17.3 Voiceband processing system

The voiceband processing on the LUCY-H200 is implemented in the DSP core inside the baseband chipset. The analog audio front-end of the chipset is connected to the digital system through 16 bit ADC converters in the uplink path, and through 16 bit DAC converters in the downlink path. External digital audio devices can be interfaced directly to the DSP digital processing part via the I²S digital interface. The analog amplifiers are skipped in this case.

Possible processing of audio signal are:

- Speech encoding (uplink) and decoding (downlink). The following speech codecs are supported in firmware on the DSP:
 - Fullrate, enhanced fullrate, and halfrate speech encoding and decoding
 - Adaptive multi rate (fullrate and halfrate) speech encoding and decoding
- Mandatory sub-functions:
 - Discontinuous transmission, DTX (GSM 46.031, 46.041, 46.081 and 46.093 standards)
 - Voice activity detection, VAD (GSM 46.032, 46.042, 46.082 and 46.094 standards)
 - Background noise calculation (GSM 46.012, 46.022, 46.062 and 46.092 standards)
- Signal routing: refer to the u-blox 3.5G HSDPA AT Commands Manual [2] (AT+USPM command)



- Analog amplification, Digital amplification: please refer to the u-blox 3.5G HSDPA AT Commands Manual [2] (AT+USGC,+CLVL, +CRSL, +CMUT command)
- Digital filtering: please refer to the u-blox 3.5G HSDPA AT Commands Manual [2] (AT+UUBF, +UDBF commands)
- Hands-free algorithms (echo cancellation, Noise suppression, Automatic Gain control: refer to the u-blox
 3.5G HSDPA AT Commands Manual [2] (AT+UHFP command)
- Sidetone generation (feedback of uplink speech signal to downlink path): please refer to the u-blox 3.5G HSDPA AT Commands Manual [2] (AT+USTN command)
- Playing/mixing of alert tones:
 - Service tones: Tone generator with 3 sinus tones used (please refer to the u-blox 3.5G HSDPA AT Commands Manual [2]: AT+UPAR command)
 - User generated tones: Tone generator with 3 sinus tones used (please refer to the u-blox 3.5G HSDPA AT Commands Manual [2]: AT+UTGN command)
 - Midi melodies (for ringer): Synthesizer with up to 64 voices and a 48kHz sampling rate. (please refer to the u-blox 3.5G HSDPA AT Commands Manual [2]: AT+UPAR command)
 - AMR files (for prompting): The storage format of AMR encoded audio content is defined in RFC3267 chapter 5 (please refer to the u-blox 3.5G HSDPA AT Commands Manual [2]: AT+UPLAYFILE command)

With exception of the speech encoder/decoder, these audio processing can be controlled by AT commands. The block diagram in Figure 31 summarizes the voiceband audio processing in the DSP.

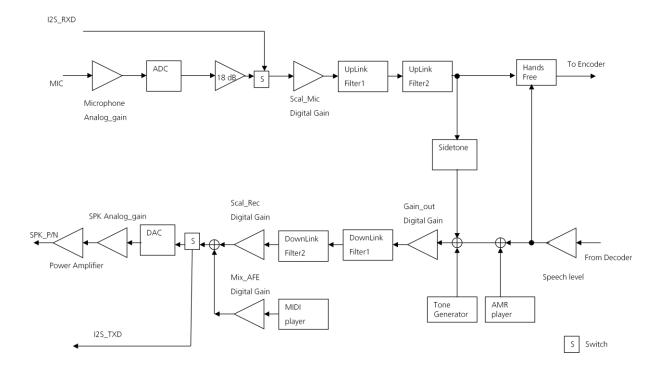


Figure 31: Voiceband processing system block diagram



1.18 Approvals

1.18.1 Federal communications commission notice

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna
- Increase the separation between the equipment and receiver
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected
- Consult the dealer or an experienced radio or television technician for help

1.18.1.1 Modifications

The FCC requires the user to be notified that any changes or modifications made to this device that are not expressly approved by u-blox could void the user's authority to operate the equipment.

1.18.1.2 Cables

The use of shielded cables for connection of the monitor to the graphics card is required to assure compliance with FCC regulations.

(Part 15.105 only applies for digital devices in the meaning of the FCC rules)

1.18.1.3 Declaration of Conformity for products marked with the FCC logo - United States only

This device complies with Part 15 of the FCC rules. Operation is subject to the following two conditions:

- (1) this device may not cause harmful interference, and
- (2) this device must accept any interference received, including interference that may cause undesired operation.

1.18.2 European Union declaration of conformity

Products bearing the CE marking comply with the R&TTE Directive (99/5/EC), EMC Directive (89/336/EEC) and the Low Voltage Directive (73/23/EEC) issued by the Commission of the European Community.

Compliance with these directives implies conformity to the following European Norms (in parentheses are the equivalent international standards and regulations):

- Radio Frequency spectrum efficiency:
 - EN 301 511, v9.0.2
 - EN 301 908-1, v3.2.1
 - EN 301 908-2, v3.2.1
- Electromagnetic Compatibility:
 - EN 301 489-1, v1.8.1
 - EN 301 489-7, v 1.3.1



- EN 301 489-24, v1.3.1
- Safety
 - EN 60950-1: 2001

1.18.2.1 Safety Warnings

- Equipment for building-in. The requirements for fire enclosure must be evaluated in the end product
- The clearance and creepage current distances required by the end product must be withheld when the module is installed
- The cooling of the end product shall not negatively be influenced by the installation of the module

1.18.3 Compliance with FCC and IC Rules and Regulations

TBD



2 Design-In

This section provides a design-in checklist.

2.1 Schematic design-in checklist

TBD

2.2 Design Guidelines for Layout

The following design guidelines must be met for optimal integration of the LUCY-H200 module on the final application board.



2.2.1 Layout guidelines per pin function

This section groups the LUCY-H200 pins by signal function and provides a ranking of importance in layout design.

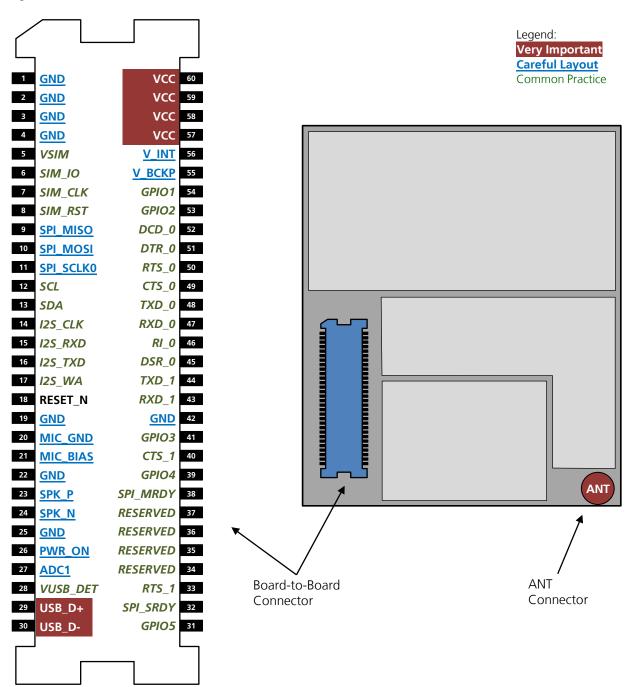


Figure 32: Module pin-out with ranked importance for layout design



Rank	Function	Pin(s)	Layout	Remarks
1 st	RF Antenna In/out	ANT	Very Important	Design for 50 Ω characteristic impedance. See section 2.2.1.1
2 nd	Main DC Supply	VCC	Very Important	VCC line should be wide and short. Route away from sensitive analog signals. See section 2.2.1.2
3 rd	USB Signals	USB_D+ USB_D-	Very Important	Route USB_D+ and USB_D- as differential lines: design for 90 Ω differential impedance. See section 2.2.1.3
4 th	Analog Audio		Careful Layout	Avoid coupling with noisy signals
	Audio Inputs	MIC_BIAS, MIC_GND		See section 2.2.1.4
	Audio Outputs	SPK_P, SPK_N		
5 th	Ground	GND	Careful Layout	Provide proper grounding. See section 2.2.1.5
6 th	Sensitive Pin :		Careful Layout	Avoid coupling with noisy signals.
	Backup Voltage	V_BCKP		See section 2.2.1.6
	A to D Converter	ADC1		
	Power On	PWR_ON		
7 th	High-speed digital pins:		Careful Layout	Avoid coupling with sensitive signals.
	SPI Signals	SPI_CLK, SPI_MISO, SPI_MOSI, SPI_SRDY, SPI_MRDY		See section 2.2.1.7
8 th	Digital pins and supplies:		Common Practice	Follow common practice rules for digital pin routing
	SIM Card Interface	VSIM, SIM_CLK, SIM_IO, SIM_RST		See section 2.2.1.8
	Digital Audio (If implemented)	I2S_CLK, I2S_RXD, I2S_TXD, I2S_WA		
	DDC	SCL, SDA		
	UARTO/UART1	TXD_0, RXD_0, CTS_0, RTS_0, DSR, RI, DCD, DTR, TXD_1, RXD_1, CTS_1, RTS_1		
	External Reset	RESET_N		
	General Purpose I/O	GPIO1, GPIO2, GPIO3, GPIO4, GPIO5		
	USB detection	VUSB_DET		
	Supply for Interfaces	V_INT		

Table 17: Pin list in order of decreasing importance for layout design

2.2.1.1 RF antenna connection

The RF antenna connection should pass through an U.FL terminated cable, connected to **ANT** connector (see Section 1.7). The other side of RF coaxial cable may be terminated with (see Figure 13):

- Connector to external antenna, mounted on application chassis
- Another U.FL plug connector, for applications requiring an internal integrated SMT antenna

In the later case, a PCB stripline or microstrip with 50 Ω characteristic impedance will connect the U.FL receptacle on baseboard to antenna pads. For this part of the layout on the baseboard, consider the following recommendations.

- Follow PCB footprint recommendations from U.FL receptacle Manufacturer. Implement cut-out prohibition area for ground and other signals below the receptacle on top layer. Copy cut-out also on first inner copper layer if dielectric thickness is below 200 µm. Connect the GND pads to solid Ground layer with multiple vias.
- The transmission line up to antenna connector or pad may be a microstrip or a stripline. In any case it must be designed to achieve 50 Ω characteristic impedance



- Microstrip lines are usually easier to implement and the reduced number of layer transitions to the antenna connector simplifies the design and diminishes reflection losses. However, the electromagnetic field extends to the free air interface above the stripline and may interact with other circuitry
- Buried striplines exhibit better shielding to external and internally generated interference. They are thererefore are preferred for sensitive applications. In case a stripline is implemented, carefully check that the via pad-stack does not couple with other signals on the crossed and adjacent layers
- Minimize the transmission line length; the insertion loss should be minimized as much as possible, in the order of a few tenths of a dB
- The transmission line should not have abrupt change to thickness and spacing to GND, but must be uniform and routed as smoothly as possible
- The transmission line must be routed in a section of the PCB where minimal interference from noise sources can be expected
- Route RF transmission line far from other sensitive circuits as it is a source of electromagnetic interference
- Avoid coupling with VCC routing and analog Audio lines
- Ensure solid metal connection of the adjacent metal layer on the PCB stack-up to main ground layer
- Add GND vias around transmission line
- Ensure no other signals are routed parallel to transmission line, or that other signals cross on adjacent metal layer
- If the distance between the transmission line and the adjacent GND area (on the same layer) does not exceed 5 times the track width of the micro strip, use the "Coplanar Waveguide" model for 50 Ω characteristic impedance calculation
- Don't route microstrip line below discrete component or other mechanics placed on top layer
- When terminating transmission line on antenna connector (or antenna pad) it is very important to strictly follow the connector manufacturer's recommended layout
- GND layer under RF connectors and close to buried vias should be cut out in order to remove stray capacitance and thus keep the RF line 50 Ω . In most cases the large active pad of the integrated antenna or antenna connector needs to have a GND keep-out at least on first inner layer to reduce parasitic capacitance to ground. Add GND keep-out on buried metal layers below antenna pad if top-layer to buried layer dielectric thickness is below 200 μ m. Note that the layout recommendation is not always available from connector manufacturers: e.g. the classical SMA Pin-Through-Hole needs to have GND cleared on all the layers around the central pin up to annular pads of the four GND posts. Check 50 Ω impedance of **ANT** line
- Ensure no coupling occurs with other noisy or sensitive signals
- Any RF transmission line on PCB should be designed for 50 Ω characteristic impedance.
- Ensure no coupling occurs with other noisy or sensitive signals.

2.2.1.2 Main DC supply connection

The DC supply of the LUCY-H200 module is very important for the overall performance and functionality of the integrated product. For detailed description, check the design guidelines in section 2.2. Some main characteristics are:

- **VCC** pins are internally connected, it is recommended to use all the available circuits of the board-to-board connector in order to minimize the power loss due to series resistance and not exceed the current rating per pin.
- **VCC** connection may carry a maximum burst current in the order of 2.5 A. Therefore, it is typically implemented as a wide PCB line with short routing from DC supply (DC-DC regulator, battery pack, etc)



- The module automatically initiates an emergency shutdown if supply voltage drops below hardware threshold. In addition, reduced supply voltage can set a worst case operation point for RF circuitry that may behave incorrectly. It follows that each voltage drop in the DC supply track will restrict the operating margin at the main DC source output. Therefore, the PCB connection must exhibit a minimum or zero voltage drop. Avoid any series component with Equivalent Series Resistance (ESR) greater than a few $m\Omega$ s
- Given the large burst current, VCC line is a source of disturbance for other signals. Therefore route VCC
 through a PCB area separated from sensitive analog signals. Typically it is good practice to interpose at least
 one layer of PCB ground between VCC track and other signal routing
- The **VCC** supply current supply flows back to main DC source through GND as ground current: provide adequate return path with suitable uninterrupted ground plane to main DC source
- A tank capacitor with low ESR is often used to smooth current spikes. This is most effective when placed as close as possible to VCC. From main DC source, first connect the capacitor and then VCC. If the main DC source is a switching DC-DC converter, place the large capacitor close to the DC-DC output and minimize the VCC track length. Otherwise consider using separate capacitors for DC-DC converter and LUCY-H200 tank capacitor. Note that the capacitor voltage rating may be adequate to withstand the charger overvoltage if battery-pack is used
- **VCC** is directly connected to the RF power amplifiers. Add capacitor in the pF range from **VCC** to GND along the supply path
- Since **VCC** is directly connected to RF Power Amplifiers, voltage ripple at high frequency may result in unwanted spurious modulation of transmitter RF signal. This is more likely to happen with switching DC-DC converters, in which case it is better to select the highest operating frequency for the switcher and add a large L-C filter before connecting to the LUCY-H200 module in the worst case
- The large current generates magnetic field that is not well isolated by PCB ground layers and which may
 interact with other analog modules (e.g. VCO) even if placed on opposite side of PCB. In this case route VCC
 away from other sensitive functional units
- The typical GSM burst has a periodic nature of approx. 217 Hz, which lies in the audible audio range. Avoid coupling between **VCC** and audio lines (especially microphone inputs)
- If **VCC** is protected by transient voltage suppressor / reverse polarity protection diode to ensure that the voltage maximum ratings are not exceeded, place the protecting device along the path from the DC source toward the LUCY-H200, preferably closer to the DC source (otherwise functionality may be compromised)
- **VCC** line should be wide and short.
- Route away from sensitive analog signals.

2.2.1.3 **USB** signal

The LUCY-H200 module includes a full-speed USB 2.0 compliant interface with maximum throughput of 12 Mb/s (see Section 1.13). Signals $\mathbf{USB}_{.}\mathbf{D}_{+}$ / $\mathbf{USB}_{.}\mathbf{D}_{-}$ carry the USB serial data and signaling. The lines are used in single ended mode for relatively low speed signaling handshake, as well as in differential mode for fast signaling and data transfer. Characteristic impedance of $\mathbf{USB}_{.}\mathbf{D}_{+}$ / $\mathbf{USB}_{.}\mathbf{D}_{-}$ lines is specified by USB standard. The most important parameter is the differential characteristic impedance applicable for odd-mode electromagnetic field, which should be as close as possible to 90 Ω differential: signal integrity may be degraded if PCB layout is not optimal, especially when the USB signaling lines are very long.

- Route USB_D+ / USB_D- lines as differential pair
- Ensure the differential characteristic impedance is as close as possible to 90 Ω
- Consider design rules for **USB_D+** / **USB_D-** similar to RF transmission lines, being them coupled differential micro-strip or buried stripline: avoid any stubs, abrupt change of layout, and route on clear PCB area



2.2.1.4 Analog audio

Accurate analog audio design is very important to obtain clear and high quality audio. The GSM signal burst has a repetition rate of 217 Hz that lies in the audible range. A careful layout is required to reduce the risk of noise pickup from audio lines due to both **VCC** burst noise coupling and RF detection.

Analog audio is separated in the two paths,

- 1. Audio Input (Uplink path): MIC_BIAS, MIC_GND
- 2. Audio Outputs (Downlink path): SPK_P / SPK_N

The most sensitive is the Uplink path, since the analog input signals are in the μV range.

- Avoid coupling of any noisy signals to microphone input lines
- It is strongly recommended to route MIC signals away from battery and RF antenna lines. Try to skip fast switching digital lines as well
- Keep ground separation from other noisy signals. Use an intermediate GND layer or vias wall for coplanar signals
- MIC_BIAS and MIC_GND also carry the bias for external electret active microphone. Verify that microphone
 is connected with right polarity, i.e. MIC_BIAS to the pin marked "+" and MIC_GND (zero Volt) to the
 chassis of the device
- Despite different DC level, **MIC_BIAS** and **MIC_GND** are sensed differentially within the module. Therefore they should be routed as a differential pair up to the active microphone
- Route MIC_GND with dedicated line together with MIC_BIAS up to active microphone. Note that MIC_GND is grounded internally within module and must not be connected to baseboard GND in order to avoid noise pick-up from ground current loops.
- Cross other signals lines on adjacent layers with 90° crossing
- Place bypass capacitor for RF very close to active microphone. The preferred microphone should be designed
 for GSM applications which typically have internal built-in bypass capacitor for RF very close to active device.
 If the integrated FET detects the RF burst, the resulting DC level will be in the pass-band of the audio
 circuitry and cannot be filtered by any other device
- If DC decoupling is required, consider that the input impedance of microphone lines is in the $k\Omega$ range. Therefore, series capacitors with sufficiently large value to reduce the high-pass cut-off frequency of the equivalent high-pass RC filter

Output Audio lines have two separated configurations.

- **SPK_P** / **SPK_N** are high level balanced output. They are DC coupled and must be used with a speaker connected in bridge configuration
- Route **SPK_P** / **SPK_N** as differential pair, to reduce differential noise pick-up. The balanced configuration will help reject the common mode noise
- Consider enlarging PCB lines, to reduce series resistive losses, when the audio output is directly connected to low impedance speaker transducer
- Use twisted pair cable for balanced audio usage.
- If DC decoupling is required, a large capacitor needs to be used, typically in the μF range, depending on the load impedance, in order to not increase the lower cut-off frequency of its High-Pass RC filter response

2.2.1.5 Module grounding

Good connection of the module with application board solid ground layer is required for correct RF performance. It significantly reduces EMC issues and provides a thermal heat sink for the module.

• Connect each **GND** pin with application board solid GND layer. It is strongly recommended that each **GND** pad surrounding **VCC** pins have one or more dedicated via down to application board solid ground layer



- The shielding cans metal tabs are connected to GND, and are fundamental part of electrical grounding and thermal heat-sink. Connect them to board solid ground layer, by soldering them on baseboard using PCB plated through holes connected to **GND** net
- If application board is a multilayer PCB, then it is required to tight together each GND area with complete via stack down to main board ground layer
- It is recommended to implement one layer of the application board as ground plane
- Good grounding of **GND** pads will also ensure thermal heat sink. This is critical during call connection, when the real network commands the module to transmit at maximum power: proper grounding helps prevent module overheating

2.2.1.6 Other sensitive pins

A few other pins on the LUCY-H200 requires careful layout.

- **Backup battery (V_BCKP):** avoid injecting noise on this voltage domain as it may affect the stability of sleep oscillator
- Analog-to-Digital Converter (ADC1): is a high impedance analog input; the conversion accuracy will be degraded if noise injected. Low-pass filter may be used to improve noise rejection; typically L-C tuned for RF rejection gives better results
- **Power On (PWR_ON):** is the digital input for power-on of the LUCY-H200. Ensure that the voltage level is well defined during operation and no transient noise is coupled on this line, otherwise the module might detect a spurious power-on request

2.2.1.7 High-speed digital pins

The Serial Peripheral Interface Bus (SPI) interface can be used for high speed data transfer (UMTS/HSDPA) between the LUCY-H200 module and the host processor, with a data rate up to 12 Mb/s (see Section 1.12). The high-speed data rate is carried by signals **SPI_CLK**, **SPI_MISO** and **SPI_MOSI**, while **SPI_SRDY** and **SPI_MRDY** behave as handshake signals with relatively low activity.

- High-speed signals become sources of digital noise, route away from RF and other sensitive analog signals
- Keep routing short and minimize parasitic capacitance to preserve digital signal integrity

2.2.1.8 Digital pins and supplies

- External Reset (RESET_N): input for external reset, a logic low voltage will reset the module
- SIM Card Interface (VSIM, SIM_CLK, SIM_IO, SIM_RST): the SIM layout may be critical if the SIM card is placed far away from the LUCY-H200 or in close vicinity of RF antenna. In the first case the long connection can radiate higher harmonic of digital data. In the second case the same harmonics can be picked up and create self-interference that can reduce the sensitivity of GSM Receiver channels whose carrier frequency is coincidental with harmonic frequencies. In the latter case using RF bypass capacitors on the digital line will mitigate the problem. In addition, since the SIM card typically accesses by the end use, it can be subjected to ESD discharges: add adequate ESD protection to improve the robustness of the digital pins within the module. Remember to add such ESD protection along the path between SIM holder toward the module
- **Digital Audio (I2S_CLK, I2S_RX, I2S_TX, I2S_WA)**: the I²S interface requires the same consideration regarding electro-magnetic interference as the SIM card. Keep the traces short and avoid coupling with RF line or sensitive analog inputs
- **DDC** (SCL, SDA): the DDC interface requires the same consideration regarding electro-magnetic interference as the SIM card. Keep the traces short and avoid coupling with RF line or sensitive analog inputs
- **UARTO/UART1 (TXD, RXD, CTS, RTS, DSR, RI, DCD, DTR)**: the serial interface requires the same consideration regarding electro-magnetic interference as the SIM card. Keep the traces short and avoid coupling with RF line or sensitive analog inputs



- General Purpose I/O (GPIOx): the general purpose input/output pins are generally not critical for layout
- Reserved pins: these pins are reserved for future use. Leave them unconnected on baseboard
- **Supply for USB (VUSB_DET)**: this is supply input which level will generate interrupt to baseband processor for USB detection. Avoid leaving it floating; if USB is unused then connect it to GND. If USB is implemented, then ensure the 5V (typical) supply connected to **VUSB_DET** is capable to deliver the required current
- **Supply for Interfaces (V_INT)**: this is a supply output at the same voltage rail of digital interfaces. Because of this, it can be a source of digital noise: avoid coupling with sensitive signals



2.2.2 Mechanical mating

This section highlights mechanical aspects concerning the LUCY-H200 implementation on application base-board. The key factors to be considered for proper module mating is are as follows:

- Choose correct board-to-board connector.
- Consider module physical dimensions and implement keep-out area below module
- Design base-board for shielding cans solder tabs
- Leave space for RF antenna connector and coaxial cable

2.2.2.1 Board-to-board connector

The board-to-board connector on the LUCY-H200 is Molex[™] 052991-0608 or equivalent.

The recommended mated connector for the customer's application board is Molex[™] 053748-0608 "0.50 mm Pitch 60-pin board-to-board connector (3 mm stacking mated height)".

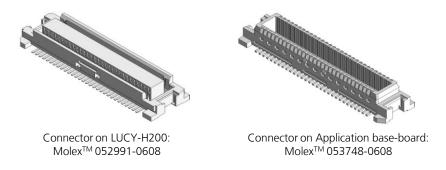


Figure 33: Board-to-board connector

Follow the connector manufacturer's recommendations for board-to-board foot-print: consider that misalignments in its placement will result in global misalignment on the whole module during installation on base-board.

The exact geometry, distances, stencil thicknesses and solder paste volumes must be adapted to the specific production processes (e.g. soldering etc.) of the customer.

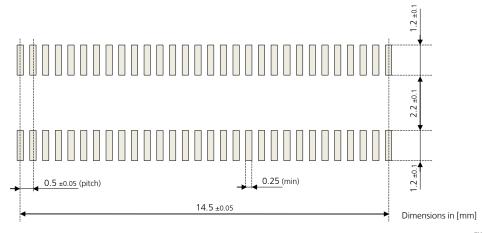


Figure 34: Board-to-board connector Footprint on Application base-board (according to Molex™ 053748-0608 datasheet)



2.2.2.2 Module keep-out

Check the module dimensions on the LUCY-H200 Data Sheet [1] and leave suitable room on base-board PCB for module installation.

- Implement component "no placement" keep-out on the area below the module, the only component allowed is the mated board-to-board connector
- consider the extra clearance required for ergonomic handling of module during mating on the application baseboard: when manual installation is concerned, define non-placement area (e.g. 15x20 mm) for components with height greater than 2mm on two opposite sides of module PCB
- Routing below the LUCY-H200 on application motherboard is generally possible but not recommended.
 When installed on base-board, the LUCY-H200 shielding cans (connected to GND) may contact the top
 surface of application PCB with consequent risk of short to GND for unprotected signal routing on baseboard top-layer

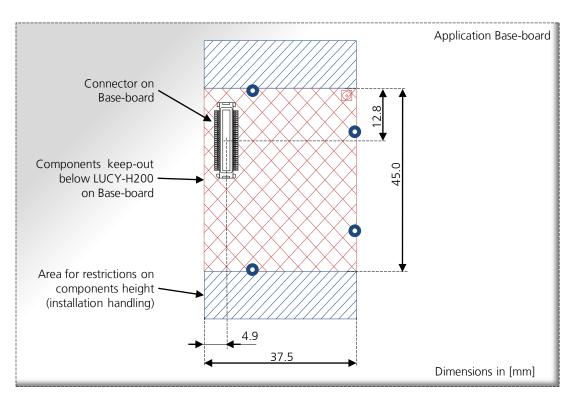


Figure 35: Keep-out dimensions

2.2.2.3 Shielding cans solder tabs

There are four solder tabs for Pin-Through-Hole (PTH) soldering of the LUCY-H200 onto the application base-board. They are designed as part of the shielding cans, and therefore are electrically connected to module main Ground (GND).



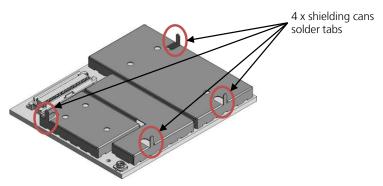


Figure 36: Tabs for Pin-through-Hole (PTH) soldering



Proper installation and soldering tabs will ensure mechanical fixing of the LUCY-H200, will improve electromagnetic connection to GND and thermal heat-sink.

The base-board needs to be designed with physical holes on coordinates corresponding to solder tabs, see Figure 37.

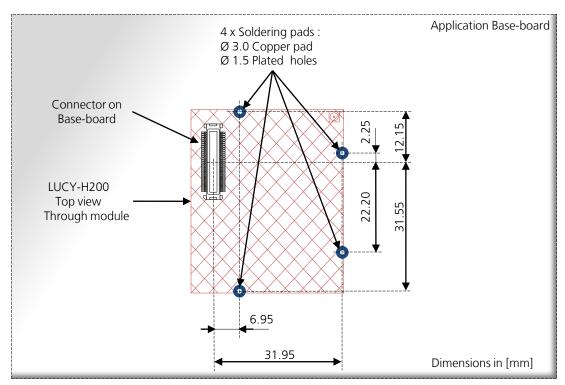


Figure 37: Coordinates of Plated Holes (PTH) on baseboard, for shields solder tabs

The recommended soldering pads on application base-board have

- round copper pad, diameter = 3.0 mm, solder mask defined
- plated through hole, drill diameter = 1.5 mm

Oblong holes are also acceptable, leading to better solder joint but more critical alignment of solder tabs to oblong holes during installation of module onto baseboard.



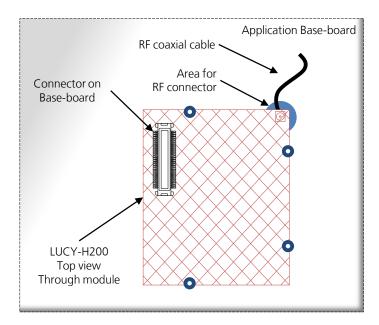


Plated holes should be electrically connected to board main GND, possibly by drilling holes through uninterrupted solid copper layer.

2.2.2.4 RF connector and coaxial cable

The RF connection is generally implemented through U.FL terminated coaxial cable:

- Design the base-board leaving suitable path for RF coaxial cable routing, minimizing the cable bending
- Consider space for U.FL plug connector at the end of RF coaxial cable, which is designed with a tail that extends a few mm beyond the module, at 0.5 mm typical distance from baseboard surface



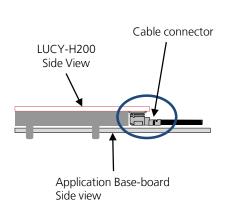


Figure 38: Keep-out for RF connector

2.2.3 Placement

Optimize placement for closer path from DC source for VCC.



The heat dissipation during continuous transmission at maximum power can significantly raise the temperature of the application base-board below the LUCY-H200: avoid placing temperature sensitive devices (e.g. GPS receiver) below the module.



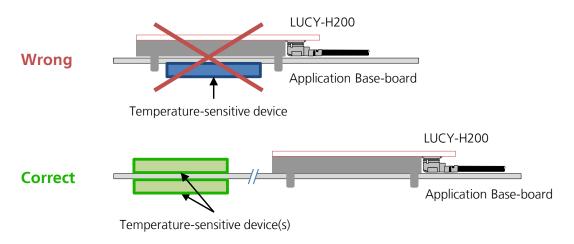


Figure 39: Avoid placement of temperature sensitive devices below module

2.3 Thermal aspects

The operating temperature range is declared on LUCY-H200 Data Sheet [1].

The most critical condition concerning thermal performances is the uplink transmission at the maximum power (data upload or voice call in connected mode), when the baseband processor runs at full speed, radio circuits are all active and the RF power amplifier is driven to higher output RF power. This scenario is not often encountered in real live network; however the application should be correctly designed to cope with it.

During transmission on the maximum RF power the LUCY-H200 module generates heat power that may exceed 2 W: this is as indicative level, being the exact generated power strictly dependent of operating condition as the number of allocated TX slot and modulation (GMSK or 8PSK) or data rate (WCDMA), transmitting frequency band, etc. The generated thermal power must be adequately dissipated through the thermal and mechanical design of application.

The Case-to-Ambient thermal resistance (R_{c-A}) of the module, with the LUCY-H200 mounted on a 130 x 110 x 1.6 mm FR4 PCB with a high coverage of copper in still air conditions is approximately 15°C/W.

With this Case-to-Ambient thermal resistance, the increasing of the module temperature is:

- around 10°C during a voice call at maximum power
- 20°C during EDGE data transfer with 4 TX slots
- up to 30°C in UMTS connection at max TX power



Case-to-Ambient thermal resistance value will be different for other mechanical deployments of the module, e.g. PCB with different size and characteristics, mechanical shells enclosure, or forced air flow.

The increasing of the thermal dissipation, i.e. reducing the thermal resistance, will reduce the operating temperature for internal circuitry of the LUCY-H200 for the same operating ambient temperature. This will improve the device long-term reliability for applications operating at high ambient temperature, e.g. greater than 55°C.

Few techniques may be used to reduce the thermal resistance in the application (Figure 40):

- Forced ventilation air-flow within mechanical enclosure
- Usage of thermal transfer material (e.g. greases and pastes) as interposer between module shielding cans and application base-board, designed with no solder-mask on top layer for better thermal transfer
- Heat sink attached on module top side, with electrically insulated / high thermal conductivity adhesive



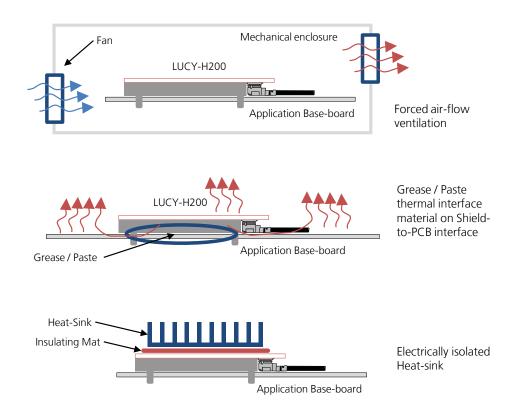


Figure 40: Techniques for thermal dissipation improvement



2.4 Antenna guidelines

Antenna characteristics are essential for good functionality of the module. Antenna radiating performance has direct impact on the reliability of connections over the Air Interface. A bad termination of **ANT** can result in poor performance of the module.

The following parameters should be checked:

Item	Recommendations
Impedance	50 Ω
Frequency Range	Depends on the Mobile Network used GSM900: 880960 MHz - GSM1800: 17101880 MHz - GSM850: 824894 MHz = UMTS B5: 824894 MHz - GSM1900: 18501990 MHz = UMTS B2: 18501990 MHz - UMTS B1: 19202170 MHz
Input Power	>2 W peak
V.S.W.R	<2:1 recommended, <3:1 acceptable
Return Loss	S ₁₁ <-10 dB recommended, S ₁₁ <-6 dB acceptable
Gain	<3 dBic

Table 18: General recommendation for GSM antenna

Please note that some 2G and 3G bands are overlapping. This depends on worldwide band allocation for telephony services, where different bands are deployed for different geographical regions. If the LUCY-H200 is planned for use on all the band combinations, then a penta-band antenna should be selected. Otherwise, for fixed applications in specific geographical region, antenna requirements can be relaxed for non-deployed frequency bands.

GSM antennas are typically available as:

- Linear monopole: typical for fixed applications. The antenna extends mostly as a linear element with a dimension comparable to lambda/4 of the lowest frequency of the operating band. Magnetic base may be available. Cable or direct RF connectors are common options. The integration normally requires the fulfillment of some minimum guidelines suggested by antenna manufacturer
- Patch-like antenna: better suited for integration in compact designs (e.g. mobile phone). These are mostly custom designs where the exact definition of the PCB and product mechanical design is fundamental for tuning of antenna characteristics

For integration observe these recommendations:

- Ensure 50 Ω antenna termination, minimize the V.S.W.R. or return loss, as this will optimize the electrical performance of the module. See section 2.4.1
- Select antenna with best radiating performance. See section 2.4.2
- If a cable is used to connect the antenna radiating element to application board, select a short cable with minimum insertion loss. The higher the additional insertion loss due to low quality or long cable, the lower the connectivity
- Follow the recommendations of the antenna manufacturer for correct installation and deployment
- Do not include antenna within closed metal case
- Do not place antenna in close vicinity to end user since the emitted radiation in human tissue is limited by S.A.R. regulatory requirements
- Do not use directivity antenna since the electromagnetic field radiation intensity is limited in some countries
- Take care of interaction between co-located RF systems since the GSM transmitted power may interact or disturb the performance of companion systems
- Place antenna far from sensitive analog systems or employ countermeasures to reduce electromagnetic compatibility issues that may arise



2.4.1 Antenna termination

The LUCY-H200 module is designed to work on a 50 Ω load. However, real antennas have no perfect 50 Ω load on all the supported frequency bands. Therefore, in order to as much as possible reduce performance degradation due to antenna mismatch, the following requirements should be met:

Measure the antenna termination with a network analyzer: connect the antenna through a coaxial cable to the measurement device, the $|S_{11}|$ indicates which portion of the power is delivered to antenna and which portion is reflected by the antenna back to the modem output.

A good antenna should have an $|S_{11}|$ below -10 dB over the entire frequency band. Due to miniaturization, mechanical constraints and other design issues, this value will not be achieved. An $|S_{11}|$ value of about -6 dB - (in the worst case) - is acceptable.

Figure 41 shows an example of this measurement:



Figure 41: $|S_{11}|$ sample measurement of a penta-band antenna that covers in a small form factor the 4 GSM bands (850 MHz, 900 MHz, 1800 MHz and 1900 MHz) and the UMTS Band I

Fig 41 shows comparable measurements performed on a wideband antenna. The termination is better, but the size of the antenna is considerably larger.



Figure 42: |S,,| sample measurement of a wideband antenna



2.4.2 Antenna radiation

An indication of the antenna's radiated power can be approximated by measuring the $|S_{21}|$ from a target antenna to the measurement antenna, using a network analyzer with a wideband antenna. Measurements should be done at a fixed distance and orientation, and results compared to measurements performed on a known good antenna. Figure 43 through Figure 44 show measurement results. A wideband log periodic-like antenna was used, and the comparison was done with a half lambda dipole tuned at 900 MHz frequency. The measurements show both the $|S_{11}|$ and $|S_{21}|$ for the penta-band internal antenna and for the wideband antenna.



Figure 43: $|S_{11}|$ and $|S_{21}|$ comparison between a 900 MHz tuned half wavelength dipole and a penta-band internal antenna, if $|S_{21}|$ like in marker 3 area are similar the target antenna performances are good





Figure 44: $|S_{1}|$ and $|S_{2}|$ comparison between a 900 MHz tuned half wavelength dipole and a wideband commercial antenna: if $|S_{2}|$ values, like in marker 1/2 area, are 5 dB better in the dipole case, then the wideband antenna radiation is considerably less



For good antenna radiation performance, antenna dimensions should be comparable to a quarter of the wavelength. Different antenna types can be used for the module, many of them (e.g. patch antennas, monopole) are based on a resonating element that works in combination with a ground plane. The ground plane, ideally infinite, can be reduced down to a minimum size that must be similar to one quarter of the wavelength of the minimum frequency that has to be radiated (transmitted/received). Numerical sample: frequency = 1 GHz \rightarrow wavelength = 30 cm \rightarrow minimum ground plane (or antenna size) = 7.5 cm. Below this size, the antenna efficiency is reduced.



2.4.3 Antenna detection functionality

The internal antenna detect circuit is based on ADC measurement at **ANT**: the RF port is DC coupled to the ADC unit in the baseband chip which injects a DC current (60 μ A) on **ANT** and measures the resulting DC voltage to evaluate the resistance from **ANT** pad to GND.

The antenna detection is forced by the +UANTR AT command: refer to the u-blox 3.5G HSDPA AT Commands Manual [2] for more details on how to access this feature.

To achieve antenna detection functionality, use an RF antenna with built-in resistor from **ANT** signal to GND, or implement an equivalent solution with a circuit between the antenna cable connection and the radiating element as shown in Figure 45.

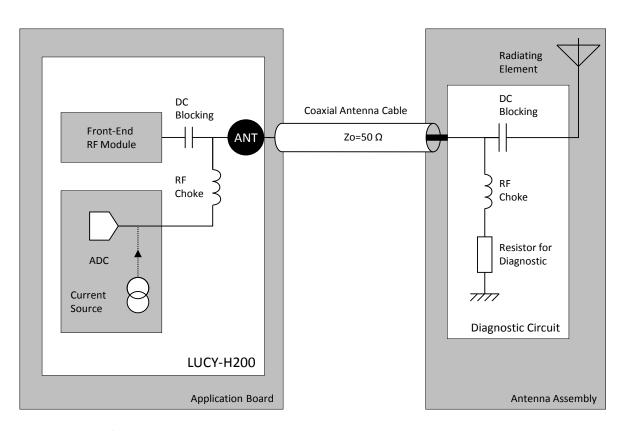


Figure 45: Antenna detection circuit

Description	Part Number - Manufacturer
DC Blocking Capacitor	Murata GRM1555C1H220JA01 or equivalent
RF Choke Inductor	Murata LQG15HS68NJ02, LQG15HH68NJ02 or equivalent (Self Resonance Frequency ~1GHz)
Resistor for Diagnostic	10kΩ 5%, various Manufacturers

Table 19: Example of components for the antenna detection diagnostic circuit

Please note that the DC impedance at RF port for some antennas may be a DC open (e.g. linear monopole) or a DC short to reference GND (e.g. PIFA antenna). For those antennas, without the diagnostic circuit of Figure 45 the measured DC resistance will always be at the limits of the measurement range (respectively open or short), and there will be no mean to distinguish between a defect on antenna path with similar characteristics (respectively: removal of linear antenna or RF cable shorted to GND for PIFA antenna).





It is recommended to use an antenna with a built-in diagnostic resistor in the range from 5 k Ω to 30 k Ω to assure good antenna detection functionality and to avoid a reduction of module RF performances. The choke inductor should exhibit a parallel Self Resonance Frequency (SRF) in the range of 1 GHz to improve the RF isolation of load resistor.

For example:

Consider a GSM antenna with built-in DC load resistor of 10 k Ω . Using the +UANTR AT command, the module reports the resistance value evaluated from **ANT** connector to GND:

- Reported values close to the used diagnostic resistor nominal value (i.e. values from 8 k Ω to 12 k Ω if a 10 k Ω diagnostic resistor is used) indicate that the antenna is properly connected
- Values close to the measurement range maximum limit (approximately 40 k Ω) or an open-circuit "over range" report (see u-blox 3.5G HSDPA AT Commands Manual [2]) means that that the antenna is not connected or the RF cable is broken open
- Reported values below the measurement range minimum limit (1 $k\Omega$) will highlight a short to GND at antenna or along the RF cable
- Measurement inside the valid measurement range and outside the expected range may indicate an improper connection, damaged antenna or wrong value of antenna load resistor for diagnostic



3 Handling and soldering

3.1 Packaging, shipping, storage and moisture preconditioning

For information pertaining to reels and tapes, Moisture Sensitivity levels (MSD), shipment and storage information, as well as drying for preconditioning see the LUCY-H200 Data Sheet [1].

3.2 Processing

3.2.1 ESD Hazard

The LUCY-H200 is an Electro-Static Discharge (ESD) sensitive device.



Ensure ESD precautions are implemented during handling of the module.

3.2.2 Hand soldering

Hand soldering is the preferred method for mounting the LUCY-H200 on the baseboard.

The procedure can be divided in following steps:

Step1: Plug the RF coaxial cable on the LUCY-H200 U.FL receptacle to provide ANT connection.

To mate the connectors, the mating axes of both connectors must be aligned and the connectors can be mated. The "click" will confirm fully mated connection. Do not attempt to insert on an extreme angle.

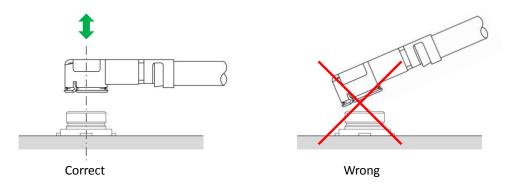


Figure 46: Precautions during RF connector mating

Step 2: Mate the board-to-board connector on baseboard soldered receptacle. Follow precautions for mating from board-to-board connector manufacturer (see Figure 47).

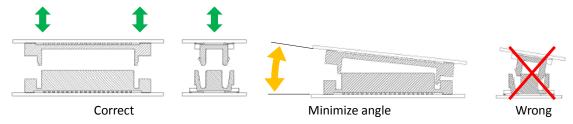


Figure 47: Precautions during board-to-board mating and extraction



Insert the connector with parallel manner. In the case of skewed mating, minimize the insertion angle and mate in the pitch direction. Do not rub housing strongly as it may damage the connector's plastic molding. After mating, verify that the module metal shielding shows uniform minimal distance from the baseboard: uneven air gap is symptom of improper mating.

Step 3: Solder the metal tabs of the LUCY-H200 shielding cans on the baseboard solder pads.

This ensures that the mated connectors hold to baseboard despite shock or vibration. Proper soldering of metal tabs will also provide a thermal heat-sink for internally generated heat during operation.

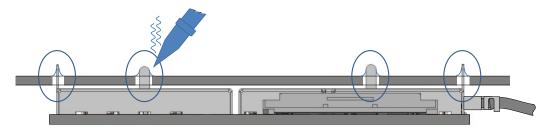


Figure 48: Shielding can soldering on baseboard by metal tabs

3.2.3 Wave soldering

The metal tabs of the LUCY-H200 shielding cans may be soldered with combined through-hole technology (THT) components by wave soldering process. Only a single wave soldering process is encouraged for boards populated with the LUCY-H200 module.

3.2.4 Reflow soldering

Reflow soldering is not recommended. The reason for this is the risk of damaging the board-to-board connector or the mated RF coaxial cable.

3.2.5 Cleaning

Cleaning the modules is not recommended. Residues underneath the modules cannot be easily removed with a washing process.

- Cleaning with water will lead to capillary effects where water is absorbed in the gap between the baseboard
 and the module. The combination of residues of soldering flux and encapsulated water leads to short circuits
 or resistor-like interconnections between neighboring pads. Water will also damage the sticker and the inkjet printed text
- Cleaning with alcohol or other organic solvents can result in soldering flux residues flooding into the two housings, areas that are not accessible for post-wash inspections. The solvent will also damage the sticker and the ink-jet printed text
- Ultrasonic cleaning will permanently damage the module, in particular the quartz oscillators

3.2.6 Rework

The LUCY-H200 module can be unsoldered from the baseboard using a soldering iron or hot air gun.



Avoid overheating the module.

Once shielding cans metal tab have been unsoldered, extract the module from the board-to-board connector and finally unplug the RF cable. It is encouraged to use a suitable extraction tool for the RF connector (e.g. Hirose U.FL-LP(V)-N).



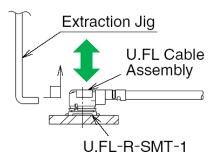


Figure 49: Precautions during RF connector extraction

After the module is removed, clean the shielding cans metal tabs before placing.



Never attempt a rework on the module itself, e.g. replacing individual components. Such actions immediately terminate the warranty.

3.2.7 Conformal coating

Certain applications employ a conformal coating of the PCB using HumiSeal® or other related coating products.

These materials affect the HF properties of the LUCY-H200 module and it is important to prevent them from flowing into the module.

The RF shields do not provide 100% protection for the module from coating liquids with low viscosity, therefore care is required in applying the coating.



Conformal Coating of the module will void the warranty.

3.2.8 Casting

If casting is required, use viscose or another type of silicon pottant. The OEM is strongly advised to qualify such processes in combination with the LUCY-H200 module before implementing this in the production.



Casting will void the warranty.

3.2.9 Grounding metal covers

Attempts to improve grounding by soldering ground cables, wick or other forms of metal strips directly onto the EMI covers is done at the customer's own risk.



u-blox makes no warranty for damages to the LUCY-H200 module caused by soldering metal cables or any other forms of metal strips directly onto the EMI covers.

3.2.10 Use of ultrasonic processes

Some components on the LUCY-H200 module are sensitive to ultrasonic waves. Use of any ultrasonic processes (cleaning, welding etc.) may cause damage to the module.



u-blox offers no warranty against damages to the LUCY-H200 module caused by any ultrasonic processes.



4 Product Testing

4.1 u-blox in-series production test

TBD

4.2 Test parameters for OEM manufacturer

TBD



Appendix

A Extra Features

A.1 Firmware (upgrade) Over AT (FOAT)

Firmware upgrade is available with LUCY modules using AT commands.

A.1.1 Overview

This feature allows upgrade the module Firmware over UART, using AT Commands.

- AT Command AT+UFWUPD triggers a reboot and followed by upgrade procedure at specified baud rate (refer to u-blox 3.5G HSDPA AT Commands Manual [2] for more details)
- The Xmodem-1k protocol is used for downloading the new Firmware image via a terminal application
- A special boot loader on the module performs Firmware installation, security verifications and module reboot
- Firmware authenticity verification is performed via a security signature during the download. Firmware is then installed, overwriting the current version. In case of power loss during this phase, the boot loader detects a fault at the next wake-up, and restarts the Firmware download from the Xmodem-1k handshake. After completing the upgrade, the module is reset again and wakes-up in normal boot

A.1.2 FOAT procedure

The application processor must proceed in the following way:

- send through the UART the AT+UFWUPD command, specifying the file type and the desired baud rate
- reconfigure the serial communication at the selected baud rate, without flow control with the Xmodem-1k protocol
- send the new FW image via Xmodem-1k

A.2 Firewall

The feature allows the LUCY-H200 user to reject incoming connections originated from IP addresses different from the specified list and inserted in a black list.

A.3 TCP/IP

Via the AT commands it's possible to access the TCP/IP functionalities over the GPRS connection. For more details about AT commands see the u-blox 3.5G HSDPA AT Commands Manual [2].

A.3.1 Multiple IP addresses and sockets

Using LUCY's embedded TCP/IP or UDP/IP stack, only 1 IP instance (address) is supported. The IP instance supports up to 16 sockets. Using an external TCP/IP stack (on the application processor), it is possible to have 2 IP instances (addresses).



A.4 FTP

The LUCY-H200 module supports via AT commands the File Transfer Protocol functionalities. File are read and stored in the local file system of the module. For more details about AT commands see the u-blox 3.5G HSDPA AT Commands Manual [2].

A.5 FTPS

TBD

A.6 HTTP

HTTP client is implemented in LUCY. HEAD, GET, POST, DELETE and PUT operations are available. The file size to be uploaded / downloaded depends on the free space available in the local file system (FFS) at the moment of the operation. Up to 4 HTTP client contexts to be used simultaneously.

For more details about AT commands see the u-blox 3.5G HSDPA AT Commands Manual [2].

A.7 HTTPS

TBD.

A.8 SMTP

The LUCY-H200 module supports SMTP client functionalities. It is possible to specify the common parameters (e.g. server data, authentication method, etc.) can be specified, to send an email to a SMTP server. E-mails can be send with or without attachment. Attachments are store in the local file system of LUCY.

For more details about AT commands see the u-blox 3.5G HSDPA AT Commands Manual [2].

A.9 GPS

The LUCY-H200 module allows a simple and fast connection with the u-blox GPS modules (u-blox 5 family and above). Via the DDC bus it's possible to communicate and exchange data, while the available GPlOs can handle the GPS device power on/off.



B Glossary

ADC Analog to Digital Converter

AP Application Processor

AT AT Command Interpreter Software Subsystem, or attention

CBCH Cell Broadcast Channel

CS Coding Scheme

CSD Circuit Switched Data

CTS Clear To Send

DAC Clear To Send

DC Direct Current

DCD Data Carrier Detect

DCE Data Communication Equipment

DCS Digital Cellular System

DDC Display Data Channel

DSP Digital Signal Processing

DSR Data Set Ready

DTE Data Terminal Equipment
DTM Dual Transfer Mode
DTR Data Terminal Ready
EBU External Bus Interface Unit

EDGE Enhanced Data rates for GSM Evolution

E-GPRS Enhanced GPRS

FDD Frequency Division Duplex

FEM Front End Module

FOAT Firmware Over AT commands

FTP File Transfer Protocol

FTPS FTP Secure
GND Ground

GPIO General Purpose Input Output
GPRS General Packet Radio Service
GPS Global Positioning System

GSM Global System for Mobile Communication

HF Hands-free

HSDPA High Speed Downlink Packet Access

HTTP HyperText Transfer Protocol

HTTPS Hypertext Transfer Protocol over Secure Socket Layer

HW Hardware

 $\mbox{I/Q}$ In phase and Quadrature $\mbox{I}^2\mbox{C}$ Inter-Integrated Circuit

I²S Inter IC Sound
IP Internet Protocol

IPC Inter Processor Communication



LNA Low Noise Amplifier

MCS Modulation Coding Scheme
NOM Network Operating Mode

PA Power Amplifier

PBCCH Packet Broadcast Control Channel

PCM Pulse Code Modulation

PCS Personal Communications Service
PFM Pulse Frequency Modulation
PMU Power Management Unit

RF Radio Frequency
RI Ring Indicator
RTC Real Time Clock
RTS Request To Send

RXD RX Data

SAW Surface Acoustic Wave

SIM Subscriber Identification Module

SMS Short Message Service

SMTP Simple Mail Transfer Protocol
SPI Serial Peripheral Interface

SRAM Static RAM

TCP Transmission Control Protocol
TDMA Time Division Multiple Access

TXD TX Data

UART Universal Asynchronous Receiver-Transmitter

UDP User Datagram Protocol

UMTS Universal Mobile Telecommunications System

USB Universal Serial Bus

UTRA UMTS Terrestrial Radio Access

VC-TCXO Voltage Controlled - Temperature Compensated Crystal Oscillator

WCDMA Wideband CODE Division Multiple Access



Related documents

- [1] u-blox LUCY-H200 Data Sheet, Document No 3G.G1-HW-10001
- [2] u-blox 3.5G HSDPA AT Commands Manual, Docu. No 3G.G1-SW-10000
- [3] ITU-T Recommendation V.24, 02-2000. List of definitions for interchange circuits between data terminal equipment (DTE) and data circuit-terminating equipment (DCE). http://www.itu.int/rec/T-REC-V.24-200002-l/en
- [4] 3GPP TS 27.007 AT command set for User Equipment (UE) (Release 1999)
- [5] 3GPP TS 27.005 Use of Data Terminal Equipment Data Circuit terminating; Equipment (DTE DCE) interface for Short Message Service (SMS) and Cell Broadcast Service (CBS) (Release 1999)
- [6] 3GPP TS 27.010 Terminal Equipment to User Equipment (TE-UE) multiplexer protocol (Release 1999)
- [7] I²C-Bus Specification Version 2.1 Philips Semiconductors (January 2000)
- [8] 3GPP TS 27.010 Terminal Equipment to User Equipment (TE-UE) multiplexer protocol (Release 1999)

Part of the documents mentioned above can be downloaded from u-blox web-site (http://www.u-blox.com).

Revision history

Revision	Date	Name	Status / Comments
-	16/04/2010	lpah	Initial Release
P1	14/05/2010	lpah	Chapter 1.18 fulfilled



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